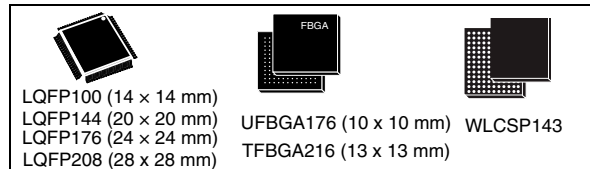


ARM<sup>®</sup>-based Cortex<sup>®</sup>-M7 32b MCU+FPU, 428DMIPS, up to 1MB Flash/320+16+ 4KB RAM, crypto, USB OTG HS/FS, ethernet, 18 TIMs, 3 ADCs, 25 com intf, cam & LCD

Data brief

## Features

- Core: ARM<sup>®</sup> 32-bit Cortex<sup>®</sup>-M7 CPU with FPU, adaptive real-time accelerator (ART Accelerator™) and L1 cache: 4KB data cache and 4KB instruction cache, allowing 0-wait state execution from embedded Flash memory and external memories, frequency up to 200 MHz, MPU, 428 DMIPS/2.14 DMIPS/MHz (Dhystone 2.1), and DSP instructions.
- Memories
  - Up to 1MB of Flash memory
  - SRAM: 320KB (including 64KB of data TCM RAM for critical real time data) + 16KB of instruction TCM RAM (for critical real time routines) + 4KB of backup SRAM (available in the lowest power modes)
  - Flexible external memory controller with up to 32-bit data bus: SRAM, PSRAM, SDRAM/LPDDR SDRAM, NOR/NAND memories
- Dual mode Quad SPI
- LCD parallel interface, 8080/6800 modes
- LCD-TFT controller up to XGA resolution with dedicated Chrom-ART Accelerator™ for enhanced graphic content creation (DMA2D)
- Clock, reset and supply management
  - 1.7 V to 3.6 V application supply and I/Os
  - POR, PDR, PVD and BOR
  - Dedicated USB power
  - 4-to-26 MHz crystal oscillator
  - Internal 16 MHz factory-trimmed RC (1% accuracy)
  - 32 kHz oscillator for RTC with calibration
  - Internal 32 kHz RC with calibration
- Low power
  - Sleep, Stop and Standby modes
  - V<sub>BAT</sub> supply for RTC, 32×32 bit backup registers + 4KB backup SRAM
- 3×12-bit, 2.4 MSPS ADC: up to 24 channels and 7.2 MSPS in triple interleaved mode
- 2×12-bit D/A converters
- General-purpose DMA: 16-stream DMA controller with FIFOs and burst support
- Up to 18 timers: up to thirteen 16-bit (1x low power 16-bit timer available in stop mode) and two 32-bit timers, each with up to 4 IC/OC/PWM or pulse counter and quadrature (incremental) encoder input. All 15 timers running up to 200 MHz. 2x watchdogs, SysTick timer



- Debug mode
  - SWD & JTAG interfaces
  - Cortex<sup>®</sup>-M7 Trace Macrocell™
- Up to 168 I/O ports with interrupt capability
  - Up to 164 fast I/Os up to 100 MHz
  - Up to 166 5 V-tolerant I/Os
- Up to 25 communication interfaces
  - Up to 4× I<sup>2</sup>C interfaces (SMBus/PMBus)
  - Up to 4 USARTs/4 UARTs (12.5 Mbit/s, ISO7816 interface, LIN, IrDA, modem control)
  - Up to 6 SPIs (up to 50 Mbits/s), 3 with muxed simplex I<sup>2</sup>S for audio class accuracy via internal audio PLL or external clock
  - 2 × SAI (serial audio interface)
  - 2 × CAN (2.0B Active) and SDMMC interface
  - SPDIF-IN interface
  - HDMI-CEC
- Advanced connectivity
  - USB 2.0 full-speed device/host/OTG controller with on-chip PHY
  - USB 2.0 high-speed/full-speed device/host/OTG controller with dedicated DMA, on-chip full-speed PHY and ULPI
  - 10/100 Ethernet MAC with dedicated DMA: supports IEEE 1588v2 hardware, MII/RMII
- 8- to 14-bit parallel camera interface up to 54 Mbytes/s
- Cryptographic acceleration: hardware acceleration for AES 128, 192, 256, Triple DES, HASH (MD5, SHA-1, SHA-2), and HMAC
- True random number generator
- CRC calculation unit
- RTC: subsecond accuracy, hardware calendar
- 96-bit unique ID

Table 1. Device summary

Reference	Part number
STM32F756xx	STM32F756VG, STM32F756ZG, STM32F756IG, STM32F756BG, STM32F756NG, STM32F756IE, STM32F756VE, STM32F756ZE, STM32F756BE, STM32F756NE

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# 1 Description

The STM32F756xx devices are based on the high-performance ARM® Cortex®-M7 32-bit RISC core operating at up to 200 MHz frequency. The Cortex®-M7 core features a single floating point unit (SFPU) precision which supports all ARM® single-precision data-processing instructions and data types. It also implements a full set of DSP instructions and a memory protection unit (MPU) which enhances application security.

The STM32F756xx devices incorporate high-speed embedded memories with Flash memory up to 1 Mbyte, 320 KB of SRAM (including 64 KB of Data TCM RAM for critical real time data), 16 KB of instruction TCM RAM (for critical real time routines), 4 KB of backup SRAM available in the lowest power modes, and an extensive range of enhanced I/Os and peripherals connected to two APB buses, two AHB buses, a 32-bit multi-AHB bus matrix and a multi layer AXI interconnect supporting internal and external memories access.

All devices offer three 12-bit ADCs, two DACs, a low-power RTC, twelve general-purpose 16-bit timers including two PWM timers for motor control, two general-purpose 32-bit timers, a true random number generator (RNG), and a cryptographic acceleration cell. They also feature standard and advanced communication interfaces.

- Up to four I<sup>2</sup>Cs
- Six SPIs, three I<sup>2</sup>Ss in duplex mode. To achieve audio class accuracy, the I<sup>2</sup>S peripherals can be clocked via a dedicated internal audio PLL or via an external clock to allow synchronization.
- Four USARTs plus four UARTs
- An USB OTG full-speed and a USB OTG high-speed with full-speed capability (with the ULPI),
- Two CANs
- Two SAI serial audio interfaces
- An SDMMC host interface
- Ethernet and camera interface
- LCD-TFT display controller
- Chrom-ART Accelerator™.
- SPDIF-Rx interface
- HDMI-CEC

Advanced peripherals include an SDMMC interface, a flexible memory control (FMC) interface, a Quad SPI flash memories interface, a camera interface for CMOS sensors and a cryptographic acceleration cell. Refer to [Table 2: STM32F756xx features and peripheral counts](#) for the list of peripherals available on each part number.

The STM32F756xx devices operate in the –40 to +105 °C temperature range from a 1.7 to 3.6 V power supply. A dedicated supply input for USB (OTG\_FS and OTG\_HS) is available on all packages except LQFP100 for greater power supply choice.

The supply voltage can drop to 1.7 V with the use of an external power supply supervisor (refer to [Section 2.17.2: Internal reset OFF](#)). A comprehensive set of power-saving mode allows the design of low-power applications.

The STM32F756xx devices offer devices in 7 packages ranging from 100 pins to 216 pins. The set of included peripherals changes with the device chosen.

These features make the STM32F756xx microcontrollers suitable for a wide range of applications:

- Motor drive and application control
- Medical equipment
- Industrial applications: PLC, inverters, circuit breakers
- Printers, and scanners
- Alarm systems, video intercom, and HVAC
- Home audio appliances
- Mobile applications, Internet of Things
- Wearable devices: smartwatches.

Figure 2 shows the general block diagram of the device family

**Table 2. STM32F756xx features and peripheral counts**

Peripherals		STM32F756Vx		STM32F756Zx		STM32F756Ix		STM32F756Bx		STM32F756Nx	
Flash memory in Kbytes		512	1024	512	1024	512	1024	512	1024	512	1024
SRAM in Kbytes	System	320(240+16+64)									
	Instruction	16									
	Backup	4									
FMC memory controller		Yes <sup>(1)</sup>									
Ethernet		Yes									
Timers	General-purpose	10									
	Advanced-control	2									
	Basic	2									
	Low-power	1									
Random number generator		Yes									
Communication interfaces	SPI / I <sup>2</sup> S	4/3 (simplex) <sup>(2)</sup>			6/3 (simplex) <sup>(2)</sup>						
	I <sup>2</sup> C	4									
	USART/UART	4/4									
	USB OTG FS	Yes									
	USB OTG HS	Yes									
	CAN	2									
	SAI	2									
	SPDIF-RX	4 inputs									
	SDMMC	Yes									
Camera interface		Yes									
LCD-TFT		Yes									
Chrom-ART Accelerator™ (DMA2D)		Yes									
Cryptography		Yes									
GPIOs		82		114		140				168	
12-bit ADC		3									
Number of channels		16		24							

Table 2. STM32F756xx features and peripheral counts (continued)

Peripherals	STM32F756Vx	STM32F756Zx	STM32F756Ix	STM32F756Bx	STM32F756Nx
12-bit DAC Number of channels	Yes 2				
Maximum CPU frequency	200 MHz				
Operating voltage	1.7 to 3.6 V <sup>(3)</sup>				
Operating temperatures	Ambient temperatures: -40 to +85 °C / -40 to +105 °C				
	Junction temperature: -40 to + 125 °C				
Package	LQFP100	WLCSP143 LQFP144	UFBGA176 LQFP176	LQFP208	TFBGA216

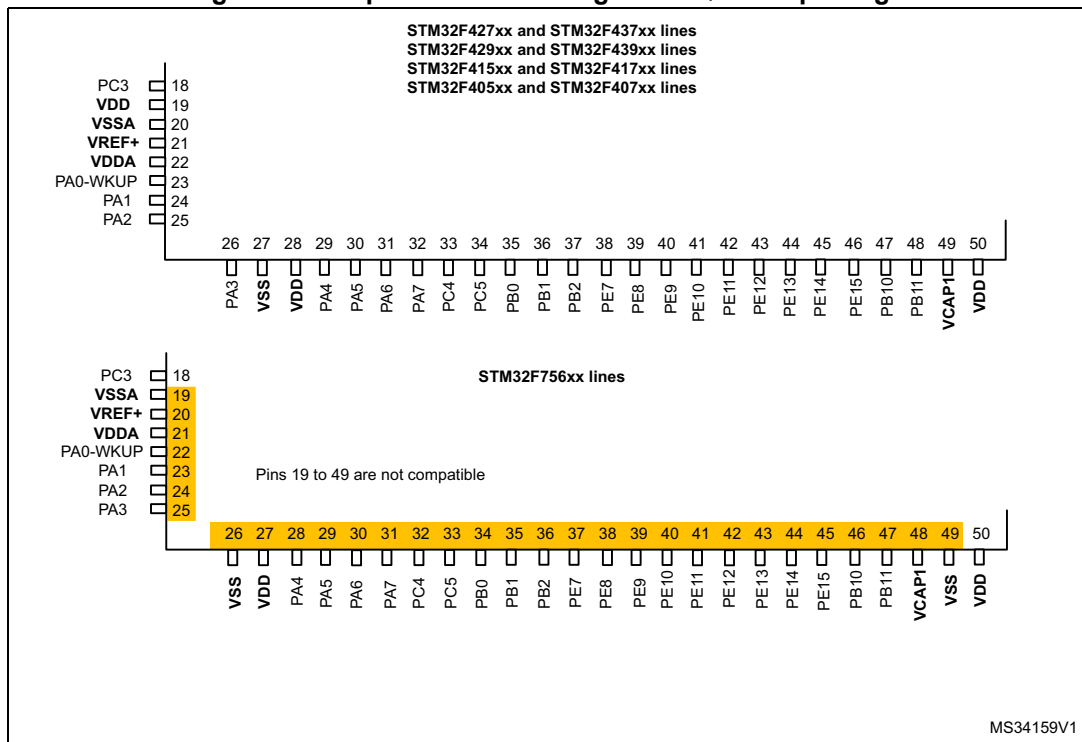
1. For the LQFP100 package, only FMC Bank1 is available. Bank1 can only support a multiplexed NOR/PSRAM memory using the NE1 Chip Select.
2. The SPI1, SPI2 and SPI3 interfaces give the flexibility to work in an exclusive way in either the SPI mode or the I2S audio mode.
3. VDD/VDDA minimum value of 1.7 V is obtained when the internal reset is OFF (refer to [Section 2.17.2: Internal reset OFF](#)).

### 1.1 Full compatibility throughout the family

The STM32F756xx devices are fully pin-to-pin, compatible with the STM32F4xx devices, allowing the user to try different peripherals, and reaching higher performances (higher frequency) for a greater degree of freedom during the development cycle.

Figure 1 give compatible board designs between the STM32F4xx families.

Figure 1. Compatible board design for LQFP100 package



The STM32F75x LQFP144, LQFP176, LQFP208, TFBGA216, UFBGA176, WLCSP143 packages are fully pin to pin compatible with STM32F4xx devices.



## 2 Functional overview

### 2.1 ARM<sup>®</sup> Cortex<sup>®</sup>-M7 with FPU

The ARM<sup>®</sup> Cortex<sup>®</sup>-M7 with FPU processor is the latest generation of ARM processors for embedded systems. It was developed to provide a low-cost platform that meets the needs of MCU implementation, with a reduced pin count and low-power consumption, while delivering outstanding computational performance and low interrupt latency.

The Cortex<sup>®</sup>-M7 processor is a highly efficient high-performance featuring:

- Six-stage dual-issue pipeline
- Dynamic branch prediction
- Harvard caches (4kB of I-cache and 4kB of D-cache)
- 64-bit AXI4 interface
- 64-bit ITCM interface
- 2x32-bit DTCM interfaces

The processor supports the following memory interfaces:

- Tightly Coupled Memory (TCM) interface.
- Harvard instruction and data caches and AXI master (AXIM) interface.
- Dedicated low-latency AHB-Lite peripheral (AHBP) interface.

The processor supports a set of DSP instructions which allow efficient signal processing and complex algorithm execution.

Its single precision FPU (floating point unit) speeds up software development by using metalanguage development tools, while avoiding saturation.

[Figure 2](#) shows the general block diagram of the STM32F756xx family.

*Note:* Cortex<sup>®</sup>-M7 with FPU core is binary compatible with the Cortex<sup>®</sup>-M4 core.

### 2.2 Memory protection unit

The memory protection unit (MPU) is used to manage the CPU accesses to memory to prevent one task to accidentally corrupt the memory or resources used by any other active task. This memory area is organized into up to 8 protected areas that can in turn be divided up into 8 subareas. The protection area sizes are between 32 bytes and the whole 4 gigabytes of addressable memory.

The MPU is especially helpful for applications where some critical or certified code has to be protected against the misbehavior of other tasks. It is usually managed by an RTOS (real-time operating system). If a program accesses a memory location that is prohibited by the MPU, the RTOS can detect it and take action. In an RTOS environment, the kernel can dynamically update the MPU area setting, based on the process to be executed.

The MPU is optional and can be bypassed for applications that do not need it.

## 2.3 Embedded Flash memory

The STM32F756xx devices embed a Flash memory of up to 1 Mbytes available for storing programs and data.

## 2.4 CRC (cyclic redundancy check) calculation unit

The CRC (cyclic redundancy check) calculation unit is used to get a CRC code using a configurable generator polynomial value and size.

Among other applications, CRC-based techniques are used to verify data transmission or storage integrity. In the scope of the EN/IEC 60335-1 standard, they offer a means of verifying the Flash memory integrity. The CRC calculation unit helps compute a signature of the software during runtime, to be compared with a reference signature generated at link-time and stored at a given memory location.

## 2.5 Embedded SRAM

All devices features:

- System SRAM up to 320Kbytes :
  - SRAM1 on AHB bus Matrix: 240Kbytes
  - SRAM2 on AHB bus Matrix: 16Kbytes
  - DTCM-RAM on TCM interface (Tightly Coupled Memory interface): 64 Kbytes for critical real time data.
- Instruction RAM (ITCM-RAM) 16Kbytes:
  - It is mapped on TCM interface and reserved only for CPU Execution/Instruction useful for critical real time routines.

The Data TCM RAM is accessible by the GP-DMA's and peripherals DMA's through specific AHB slave of the CPU. The instruction TCM RAM is reserved only for CPU. It is accessed at CPU clock speed with 0 wait states.

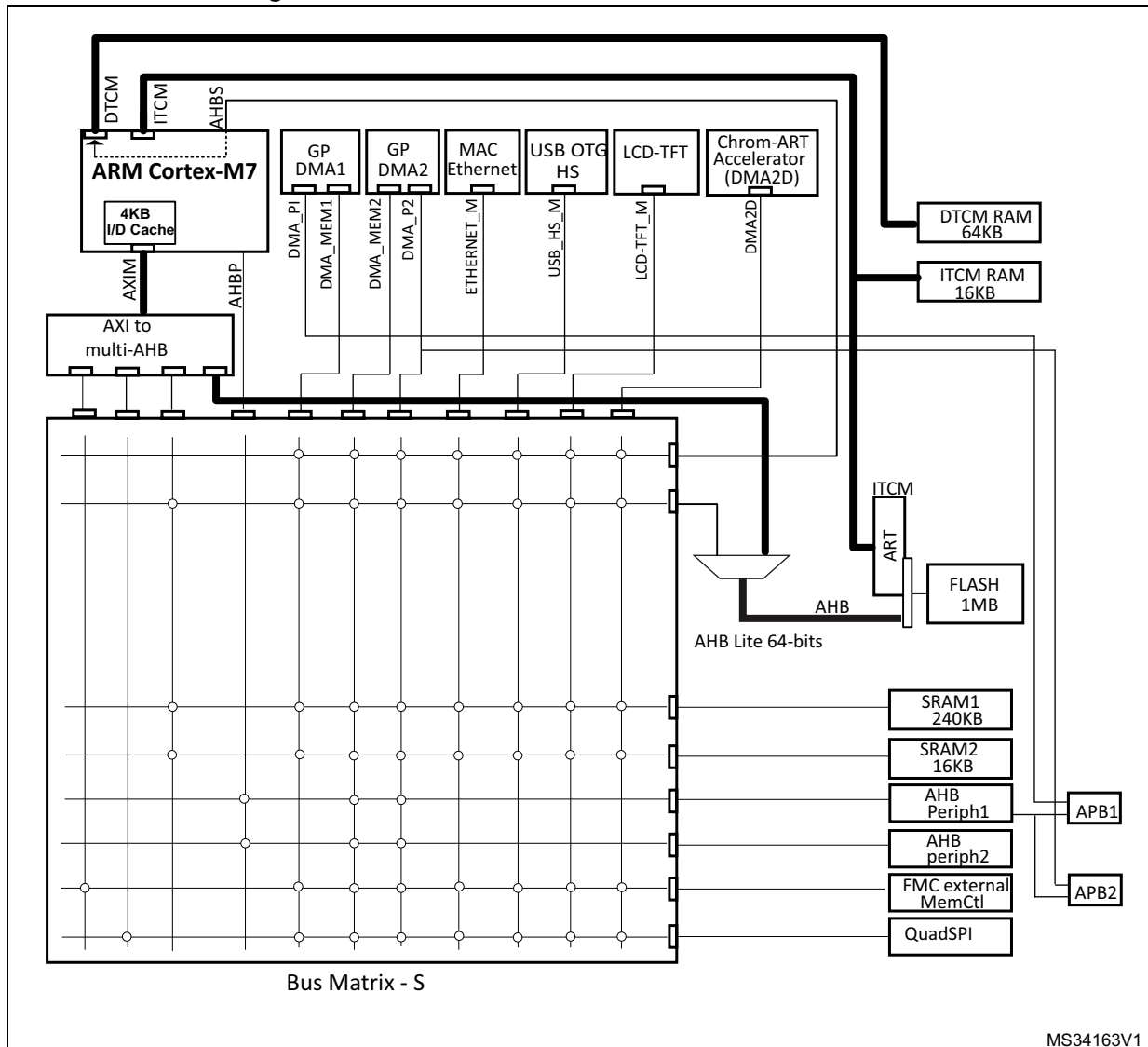
- 4 Kbytes of backup SRAM
  - This area is accessible only from the CPU. Its content is protected against possible unwanted write accesses, and is retained in Standby or VBAT mode.

## 2.6 AXI-AHB bus matrix

The STM32F756xx system architecture is based on 2 sub-systems :

- An AXI to multi AHB bridge converting AXI4 protocol to AHB-Lite protocol:
  - 3x AXI to 32-bit AHB bridges connected to AHB bus matrix
  - 1x AXI to 64-bit AHB bridge connected to the embedded flash
- A multi-AHB Bus-Matrix
  - The 32-bit multi-AHB bus matrix interconnects all the masters (CPU, DMA's, Ethernet, USB HS, LCD-TFT, and DMA2D) and the slaves (Flash memory, RAM, FMC, Quad SPI, AHB and APB peripherals) and ensures a seamless and efficient operation even when several high-speed peripherals work simultaneously.

Figure 3. STM32F756xx AXI-AHB bus matrix architecture



1. The above figure has large wires for 64-bits bus and thin wires for 32-bits bus.

## 2.7 DMA controller (DMA)

The devices feature two general-purpose dual-port DMAs (DMA1 and DMA2) with 8 streams each. They are able to manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers. They feature dedicated FIFOs for APB/AHB peripherals, support burst transfer and are designed to provide the maximum peripheral bandwidth (AHB/APB).

The two DMA controllers support circular buffer management, so that no specific code is needed when the controller reaches the end of the buffer. The two DMA controllers also have a double buffering feature, which automates the use and switching of two memory buffers without requiring any special code.

Each stream is connected to dedicated hardware DMA requests, with support for software trigger on each stream. Configuration is made by software and transfer sizes between source and destination are independent.

The DMA can be used with the main peripherals:

- SPI and I<sup>2</sup>S
- I<sup>2</sup>C
- USART
- General-purpose, basic and advanced-control timers TIMx
- DAC
- SDMMC
- Cryptographic acceleration
- Camera interface (DCMI)
- ADC
- SAI
- SPDIF-RX
- Quad SPI
- HDMI-CEC

## 2.8 Flexible memory controller (FMC)

The Flexible memory controller (FMC) includes three memory controllers:

- The NOR/PSRAM memory controller
- The NAND/memory controller
- The Synchronous DRAM (SDRAM/Mobile LPDDR SDRAM) controller

The main features of the FMC controller are the following:

- Interface with static-memory mapped devices including:
  - Static random access memory (SRAM)
  - NOR Flash memory/OneNAND Flash memory
  - PSRAM (4 memory banks)
  - NAND Flash memory with ECC hardware to check up to 8 Kbytes of data
- Interface with synchronous DRAM (SDRAM/Mobile LPDDR SDRAM) memories
- 8-, 16-, 32-bit data bus width
- Independent Chip Select control for each memory bank
- Independent configuration for each memory bank
- Write FIFO
- Read FIFO for SDRAM controller
- The Maximum FMC\_CLK/FMC\_SDCLK frequency for synchronous accesses is HCLK/2.

### LCD parallel interface

The FMC can be configured to interface seamlessly with most graphic LCD controllers. It supports the Intel 8080 and Motorola 6800 modes, and is flexible enough to adapt to specific LCD interfaces. This LCD parallel interface capability makes it easy to build cost-effective graphic applications using LCD modules with embedded controllers or high performance solutions using external controllers with dedicated acceleration.

## 2.9 Quad SPI memory interface (QUADSPI)

All STM32F75xx devices embed a Quad SPI memory interface, which is a specialized communication interface targeting Single, Dual or Quad SPI flash memories. It can work in:

- Direct mode through registers
- External flash status register polling mode
- Memory mapped mode.

Up to 256 Mbytes external flash are memory mapped, supporting 8, 16 and 32-bit access. Code execution is supported.

The opcode and the frame format are fully programmable. Communication can be either in Single Data Rate or Dual Data Rate.

## 2.10 LCD-TFT controller

The LCD-TFT display controller provides a 24-bit parallel digital RGB (Red, Green, Blue) and delivers all signals to interface directly to a broad range of LCD and TFT panels up to XGA (1024x768) resolution with the following features:

- 2 displays layers with dedicated FIFO (64x32-bit)
- Color Look-Up table (CLUT) up to 256 colors (256x24-bit) per layer
- Up to 8 Input color formats selectable per layer
- Flexible blending between two layers using alpha value (per pixel or constant)
- Flexible programmable parameters for each layer
- Color keying (transparency color)
- Up to 4 programmable interrupt events.

## 2.11 Chrom-ART Accelerator™ (DMA2D)

The Chrom-Art Accelerator™ (DMA2D) is a graphic accelerator which offers advanced bit blitting, row data copy and pixel format conversion. It supports the following functions:

- Rectangle filling with a fixed color
- Rectangle copy
- Rectangle copy with pixel format conversion
- Rectangle composition with blending and pixel format conversion.

Various image format coding are supported, from indirect 4bpp color mode up to 32bpp direct color. It embeds dedicated memory to store color lookup tables.

An interrupt can be generated when an operation is complete or at a programmed watermark.

All the operations are fully automatized and are running independently from the CPU or the DMAs.

## 2.12 Nested vectored interrupt controller (NVIC)

The devices embed a nested vectored interrupt controller able to manage 16 priority levels, and handle up to 97 maskable interrupt channels plus the 16 interrupt lines of the Cortex<sup>®</sup>-M7 with FPU core.

- Closely coupled NVIC gives low-latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Allows early processing of interrupts
- Processing of late arriving, higher-priority interrupts
- Support tail chaining
- Processor state automatically saved
- Interrupt entry restored on interrupt exit with no instruction overhead

This hardware block provides flexible interrupt management features with minimum interrupt latency.

## 2.13 External interrupt/event controller (EXTI)

The external interrupt/event controller consists of 24 edge-detector lines used to generate interrupt/event requests. Each line can be independently configured to select the trigger event (rising edge, falling edge, both) and can be masked independently. A pending register maintains the status of the interrupt requests. The EXTI can detect an external line with a pulse width shorter than the Internal APB2 clock period. Up to 168 GPIOs can be connected to the 16 external interrupt lines.

## 2.14 Clocks and startup

On reset the 16 MHz internal HSI RC oscillator is selected as the default CPU clock. The 16 MHz internal RC oscillator is factory-trimmed to offer 1% accuracy. The application can then select as system clock either the RC oscillator or an external 4-26 MHz clock source. This clock can be monitored for failure. If a failure is detected, the system automatically switches back to the internal RC oscillator and a software interrupt is generated (if enabled). This clock source is input to a PLL thus allowing to increase the frequency up to 200 MHz. Similarly, full interrupt management of the PLL clock entry is available when necessary (for example if an indirectly used external oscillator fails).

Several prescalers allow the configuration of the two AHB buses, the high-speed APB (APB2) and the low-speed APB (APB1) domains. The maximum frequency of the two AHB buses is 200 MHz while the maximum frequency of the high-speed APB domains is 100 MHz. The maximum allowed frequency of the low-speed APB domain is 50 MHz.

The devices embed two dedicated PLL (PLLI2S and PLLSAI) which allow to achieve audio class performance. In this case, the I<sup>2</sup>S and SAI master clock can generate all standard sampling frequencies from 8 kHz to 192 kHz.

## 2.15 Boot modes

At startup, the boot memory space is selected by the BOOT pin and BOOT\_ADDx option bytes, allowing to program any boot memory address from 0x0000 0000 to 0x3FFF FFFF which includes:

- All Flash address space mapped on ITCM or AXIM interface
- All RAM address space: ITCM, DTCM RAMs and SRAMs mapped on AXIM interface
- The System memory bootloader

The boot loader is located in system memory. It is used to reprogram the Flash memory through a serial interface.

## 2.16 Power supply schemes

- $V_{DD} = 1.7$  to  $3.6$  V: external power supply for I/Os and the internal regulator (when enabled), provided externally through  $V_{DD}$  pins.
- $V_{SSA}$ ,  $V_{DDA} = 1.7$  to  $3.6$  V: external analog power supplies for ADC, DAC, Reset blocks, RCs and PLL.  $V_{DDA}$  and  $V_{SSA}$  must be connected to  $V_{DD}$  and  $V_{SS}$ , respectively.
- VDDUSB can be connected either to VDD or an external independent power supply (3.0 to 3.6V) for USB transceivers. For example, when device is powered at 1.8V, an independent power supply 3.3V can be connected to VDDUSB.
- $V_{BAT} = 1.65$  to  $3.6$  V: power supply for RTC, external clock 32 kHz oscillator and backup registers (through power switch) when  $V_{DD}$  is not present.

*Note:*  $V_{DD}/V_{DDA}$  minimum value of 1.7 V is obtained when the internal reset is OFF (refer to [Section 2.17.2: Internal reset OFF](#)). Refer to [Table 3: Voltage regulator configuration mode versus device operating mode](#) to identify the packages supporting this option.

## 2.17 Power supply supervisor

### 2.17.1 Internal reset ON

On packages embedding the PDR\_ON pin, the power supply supervisor is enabled by holding PDR\_ON high. On the other packages, the power supply supervisor is always enabled.

The device has an integrated power-on reset (POR)/ power-down reset (PDR) circuitry coupled with a Brownout reset (BOR) circuitry. At power-on, POR/PDR is always active and ensures proper operation starting from 1.8 V. After the 1.8 V POR threshold level is reached, the option byte loading process starts, either to confirm or modify default BOR thresholds, or to disable BOR permanently. Three BOR thresholds are available through option bytes. The device remains in reset mode when  $V_{DD}$  is below a specified threshold,  $V_{POR/PDR}$  or  $V_{BOR}$ , without the need for an external reset circuit.

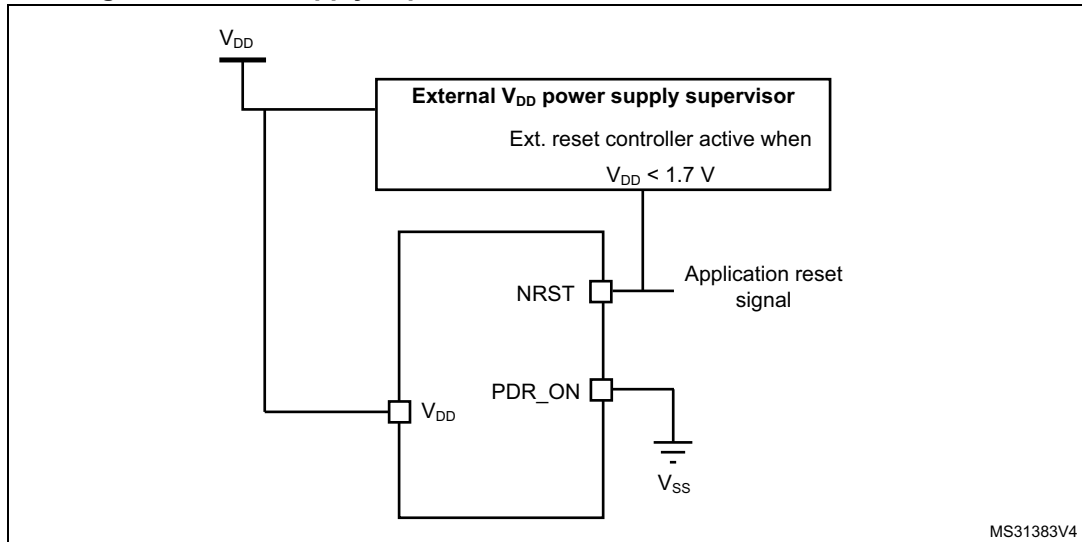
The device also features an embedded programmable voltage detector (PVD) that monitors the  $V_{DD}/V_{DDA}$  power supply and compares it to the  $V_{PVD}$  threshold. An interrupt can be generated when  $V_{DD}/V_{DDA}$  drops below the  $V_{PVD}$  threshold and/or when  $V_{DD}/V_{DDA}$  is higher than the  $V_{PVD}$  threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

## 2.17.2 Internal reset OFF

This feature is available only on packages featuring the PDR\_ON pin. The internal power-on reset (POR) / power-down reset (PDR) circuitry is disabled through the PDR\_ON pin.

An external power supply supervisor should monitor  $V_{DD}$  and NRST and should maintain the device in reset mode as long as  $V_{DD}$  is below a specified threshold. PDR\_ON should be connected to  $V_{SS}$ . Refer to [Figure 4: Power supply supervisor interconnection with internal reset OFF](#).

**Figure 4. Power supply supervisor interconnection with internal reset OFF**



The  $V_{DD}$  specified threshold, below which the device must be maintained under reset, is 1.7 V (see [Figure 5](#)).

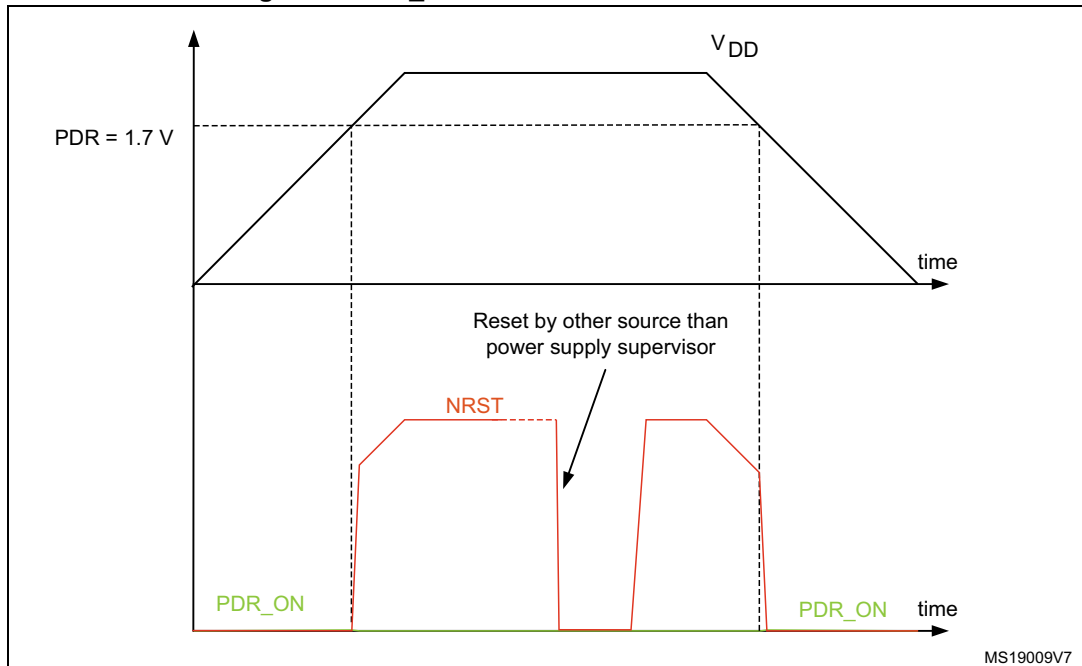
A comprehensive set of power-saving mode allows to design low-power applications.

When the internal reset is OFF, the following integrated features are no more supported:

- The integrated power-on reset (POR) / power-down reset (PDR) circuitry is disabled
- The brownout reset (BOR) circuitry must be disabled
- The embedded programmable voltage detector (PVD) is disabled
- $V_{BAT}$  functionality is no more available and  $V_{BAT}$  pin should be connected to  $V_{DD}$ .

All packages, except for the LQFP100, allow to disable the internal reset through the PDR\_ON signal when connected to  $V_{SS}$ .

Figure 5. PDR\_ON control with internal reset OFF



## 2.18 Voltage regulator

The regulator has four operating modes:

- Regulator ON
  - Main regulator mode (MR)
  - Low power regulator (LPR)
  - Power-down
- Regulator OFF

### 2.18.1 Regulator ON

On packages embedding the BYPASS\_REG pin, the regulator is enabled by holding BYPASS\_REG low. On all other packages, the regulator is always enabled.

There are three power modes configured by software when the regulator is ON:

- MR mode used in Run/sleep modes or in Stop modes
  - In Run/Sleep mode
    - The MR mode is used either in the normal mode (default mode) or the over-drive mode (enabled by software). Different voltages scaling are provided to reach the best compromise between maximum frequency and dynamic power consumption.

The over-drive mode allows operating at a higher frequency than the normal mode for a given voltage scaling.

- In Stop modes
  - The MR can be configured in two ways during stop mode:
    - MR operates in normal mode (default mode of MR in stop mode)
    - MR operates in under-drive mode (reduced leakage mode).
- LPR is used in the Stop modes:
  - The LP regulator mode is configured by software when entering Stop mode. Like the MR mode, the LPR can be configured in two ways during stop mode:
    - LPR operates in normal mode (default mode when LPR is ON)
    - LPR operates in under-drive mode (reduced leakage mode).
- Power-down is used in Standby mode.
  - The Power-down mode is activated only when entering in Standby mode. The regulator output is in high impedance and the kernel circuitry is powered down, inducing zero consumption. The contents of the registers and SRAM are lost.

Refer to [Table 3](#) for a summary of voltage regulator modes versus device operating modes.

Two external ceramic capacitors should be connected on V<sub>CAP\_1</sub> and V<sub>CAP\_2</sub> pin.

All packages have the regulator ON feature.

**Table 3. Voltage regulator configuration mode versus device operating mode<sup>(1)</sup>**

Voltage regulator configuration	Run mode	Sleep mode	Stop mode	Standby mode
Normal mode	MR	MR	MR or LPR	-
Over-drive mode <sup>(2)</sup>	MR	MR	-	-
Under-drive mode	-	-	MR or LPR	-
Power-down mode	-	-	-	Yes

1. '-' means that the corresponding configuration is not available.  
 2. The over-drive mode is not available when V<sub>DD</sub> = 1.7 to 2.1 V.

### 2.18.2 Regulator OFF

This feature is available only on packages featuring the BYPASS\_REG pin. The regulator is disabled by holding BYPASS\_REG high. The regulator OFF mode allows to supply externally a V<sub>12</sub> voltage source through V<sub>CAP\_1</sub> and V<sub>CAP\_2</sub> pins.

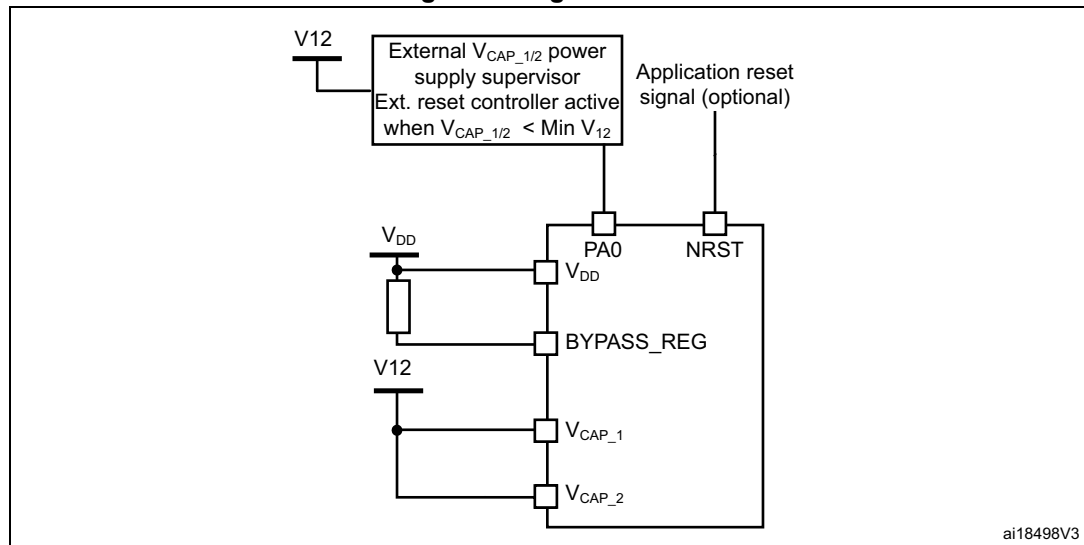
Since the internal voltage scaling is not managed internally, the external voltage value must be aligned with the targeted maximum frequency. The two 2.2 µF ceramic capacitors should be replaced by two 100 nF decoupling capacitors.

When the regulator is OFF, there is no more internal monitoring on V<sub>12</sub>. An external power supply supervisor should be used to monitor the V<sub>12</sub> of the logic power domain. PA0 pin should be used for this purpose, and act as power-on reset on V<sub>12</sub> power domain.

In regulator OFF mode, the following features are no more supported:

- PA0 cannot be used as a GPIO pin since it allows to reset a part of the  $V_{12}$  logic power domain which is not reset by the NRST pin.
- As long as PA0 is kept low, the debug mode cannot be used under power-on reset. As a consequence, PA0 and NRST pins must be managed separately if the debug connection under reset or pre-reset is required.
- The over-drive and under-drive modes are not available.
- The Standby mode is not available.

Figure 6. Regulator OFF

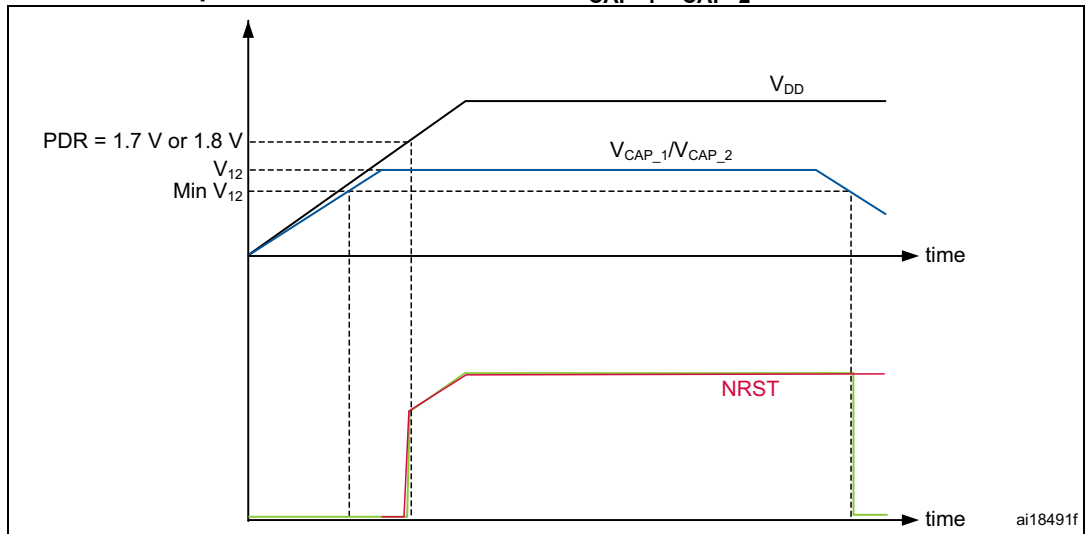


The following conditions must be respected:

- $V_{DD}$  should always be higher than  $V_{CAP\_1}$  and  $V_{CAP\_2}$  to avoid current injection between power domains.
- If the time for  $V_{CAP\_1}$  and  $V_{CAP\_2}$  to reach  $V_{12}$  minimum value is faster than the time for  $V_{DD}$  to reach 1.7 V, then PA0 should be kept low to cover both conditions: until  $V_{CAP\_1}$  and  $V_{CAP\_2}$  reach  $V_{12}$  minimum value and until  $V_{DD}$  reaches 1.7 V (see [Figure 7](#)).
- Otherwise, if the time for  $V_{CAP\_1}$  and  $V_{CAP\_2}$  to reach  $V_{12}$  minimum value is slower than the time for  $V_{DD}$  to reach 1.7 V, then PA0 could be asserted low externally (see [Figure 8](#)).
- If  $V_{CAP\_1}$  and  $V_{CAP\_2}$  go below  $V_{12}$  minimum value and  $V_{DD}$  is higher than 1.7 V, then a reset must be asserted on PA0 pin.

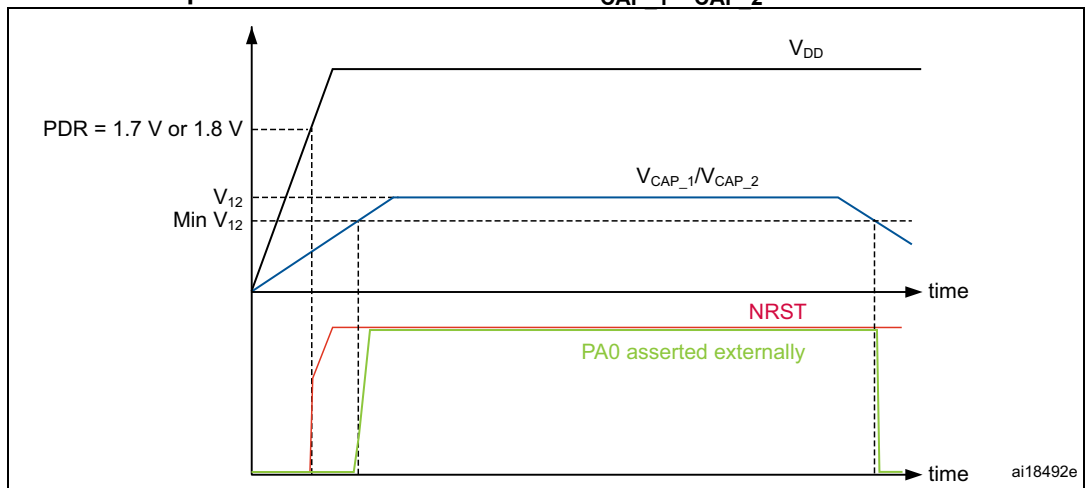
*Note:* The minimum value of  $V_{12}$  depends on the maximum frequency targeted in the application.

**Figure 7. Startup in regulator OFF: slow  $V_{DD}$  slope - power-down reset risen after  $V_{CAP\_1}/V_{CAP\_2}$  stabilization**



1. This figure is valid whatever the internal reset mode (ON or OFF).

**Figure 8. Startup in regulator OFF mode: fast  $V_{DD}$  slope - power-down reset risen before  $V_{CAP\_1}/V_{CAP\_2}$  stabilization**



1. This figure is valid whatever the internal reset mode (ON or OFF).

### 2.18.3 Regulator ON/OFF and internal reset ON/OFF availability

Table 4. Regulator ON/OFF and internal reset ON/OFF availability

Package	Regulator ON	Regulator OFF	Internal reset ON	Internal reset OFF
LQFP100	Yes	No	Yes	No
LQFP144, LQFP208			Yes PDR_ON set to V <sub>DD</sub>	Yes PDR_ON set to V <sub>SS</sub>
LQFP176, WLCSP143, UFBGA176, TFBGA216	Yes BYPASS_REG set to V <sub>SS</sub>	Yes BYPASS_REG set to V <sub>DD</sub>		

### 2.19 Real-time clock (RTC), backup SRAM and backup registers

The RTC is an independent BCD timer/counter. It supports the following features:

- Calendar with subsecond, seconds, minutes, hours (12 or 24 format), week day, date, month, year, in BCD (binary-coded decimal) format.
- Automatic correction for 28, 29 (leap year), 30, and 31 days of the month.
- Two programmable alarms.
- On-the-fly correction from 1 to 32767 RTC clock pulses. This can be used to synchronize it with a master clock.
- Reference clock detection: a more precise second source clock (50 or 60 Hz) can be used to enhance the calendar precision.
- Digital calibration circuit with 0.95 ppm resolution, to compensate for quartz crystal inaccuracy.
- Three anti-tamper detection pins with programmable filter.
- Timestamp feature which can be used to save the calendar content. This function can be triggered by an event on the timestamp pin, or by a tamper event, or by a switch to V<sub>BAT</sub> mode.
- 17-bit auto-reload wakeup timer (WUT) for periodic events with programmable resolution and period.

The RTC and the 32 backup registers are supplied through a switch that takes power either from the V<sub>DD</sub> supply when present or from the V<sub>BAT</sub> pin.

The backup registers are 32-bit registers used to store 128 bytes of user application data when V<sub>DD</sub> power is not present. They are not reset by a system or power reset, or when the device wakes up from Standby mode.

The RTC clock sources can be:

- A 32.768 kHz external crystal (LSE)
- An external resonator or oscillator(LSE)
- The internal low power RC oscillator (LSI, with typical frequency of 32 kHz)
- The high-speed external clock (HSE) divided by 32.

The RTC is functional in  $V_{BAT}$  mode and in all low-power modes when it is clocked by the LSE. When clocked by the LSI, the RTC is not functional in  $V_{BAT}$  mode, but is functional in all low-power modes.

All RTC events (Alarm, WakeUp Timer, Timestamp or Tamper) can generate an interrupt and wakeup the device from the low-power modes.

## 2.20 Low-power modes

The devices support three low-power modes to achieve the best compromise between low power consumption, short startup time and available wakeup sources:

- **Sleep mode**

In Sleep mode, only the CPU is stopped. All peripherals continue to operate and can wake up the CPU when an interrupt/event occurs.

- **Stop mode**

The Stop mode achieves the lowest power consumption while retaining the contents of SRAM and registers. All clocks in the 1.2 V domain are stopped, the PLL, the HSI RC and the HSE crystal oscillators are disabled.

The voltage regulator can be put either in main regulator mode (MR) or in low-power mode (LPR). Both modes can be configured as follows (see [Table 5: Voltage regulator modes in stop mode](#)):

- Normal mode (default mode when MR or LPR is enabled)
- Under-drive mode.

The device can be woken up from the Stop mode by any of the EXTI line (the EXTI line source can be one of the 16 external lines, the PVD output, the RTC alarm / wakeup / tamper / time stamp events, the USB OTG FS/HS wakeup or the Ethernet wakeup and LPTIM1 asynchronous interrupt).

**Table 5. Voltage regulator modes in stop mode**

Voltage regulator configuration	Main regulator (MR)	Low-power regulator (LPR)
Normal mode	MR ON	LPR ON
Under-drive mode	MR in under-drive mode	LPR in under-drive mode

- **Standby mode**

The Standby mode is used to achieve the lowest power consumption. The internal voltage regulator is switched off so that the entire 1.2 V domain is powered off. The PLL, the HSI RC and the HSE crystal oscillators are also switched off. After entering Standby mode, the SRAM and register contents are lost except for registers in the backup domain and the backup SRAM when selected.

The device exits the Standby mode when an external reset (NRST pin), an IWDG reset, a rising or falling edge on one of the 6 WKUP pins (PA0, PA2, PC1, PC13, PI8, PI11), or an RTC alarm / wakeup / tamper /time stamp event occurs.

The standby mode is not supported when the embedded voltage regulator is bypassed and the 1.2 V domain is controlled by an external power.

## 2.21 V<sub>BAT</sub> operation

The V<sub>BAT</sub> pin allows to power the device V<sub>BAT</sub> domain from an external battery, an external supercapacitor, or from V<sub>DD</sub> when no external battery and an external supercapacitor are present.

V<sub>BAT</sub> operation is activated when V<sub>DD</sub> is not present.

The V<sub>BAT</sub> pin supplies the RTC, the backup registers and the backup SRAM.

*Note:* When the microcontroller is supplied from V<sub>BAT</sub>, external interrupts and RTC alarm/events do not exit it from V<sub>BAT</sub> operation.

*When PDR\_ON pin is connected to V<sub>SS</sub> (Internal Reset OFF), the V<sub>BAT</sub> functionality is no more available and V<sub>BAT</sub> pin should be connected to V<sub>DD</sub>.*

## 2.22 Timers and watchdogs

The devices include two advanced-control timers, eight general-purpose timers, two basic timers and two watchdog timers.

All timer counters can be frozen in debug mode.

[Table 6](#) compares the features of the advanced-control, general-purpose and basic timers.

Table 6. Timer feature comparison

Timer type	Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/compare channels	Complementary output	Max interface clock (MHz)	Max timer clock (MHz) <sup>(1)</sup>
Advanced-control	TIM1, TIM8	16-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	Yes	100	200
General purpose	TIM2, TIM5	32-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	No	50	100/200
	TIM3, TIM4	16-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	No	50	100/200
	TIM9	16-bit	Up	Any integer between 1 and 65536	No	2	No	100	200
	TIM10, TIM11	16-bit	Up	Any integer between 1 and 65536	No	1	No	100	200
	TIM12	16-bit	Up	Any integer between 1 and 65536	No	2	No	50	100/200
	TIM13, TIM14	16-bit	Up	Any integer between 1 and 65536	No	1	No	50	100/200
Basic	TIM6, TIM7	16-bit	Up	Any integer between 1 and 65536	Yes	0	No	50	100/200

1. The maximum timer clock is either 100 or 200 MHz depending on TIMPRE bit configuration in the RCC\_DCKCFGR register.

**2.22.1 Advanced-control timers (TIM1, TIM8)**

The advanced-control timers (TIM1, TIM8) can be seen as three-phase PWM generators multiplexed on 6 channels. They have complementary PWM outputs with programmable

inserted dead times. They can also be considered as complete general-purpose timers. Their 4 independent channels can be used for:

- Input capture
- Output compare
- PWM generation (edge- or center-aligned modes)
- One-pulse mode output

If configured as standard 16-bit timers, they have the same features as the general-purpose TIMx timers. If configured as 16-bit PWM generators, they have full modulation capability (0-100%).

The advanced-control timer can work together with the TIMx timers via the Timer Link feature for synchronization or event chaining.

TIM1 and TIM8 support independent DMA request generation.

### 2.22.2 General-purpose timers (TIMx)

There are ten synchronizable general-purpose timers embedded in the STM32F756xx devices (see [Table 6](#) for differences).

- **TIM2, TIM3, TIM4, TIM5**

The STM32F756xx include 4 full-featured general-purpose timers: TIM2, TIM5, TIM3, and TIM4. The TIM2 and TIM5 timers are based on a 32-bit auto-reload up/downcounter and a 16-bit prescaler. The TIM3 and TIM4 timers are based on a 16-bit auto-reload up/downcounter and a 16-bit prescaler. They all feature 4 independent channels for input capture/output compare, PWM or one-pulse mode output. This gives up to 16 input capture/output compare/PWMs on the largest packages.

The TIM2, TIM3, TIM4, TIM5 general-purpose timers can work together, or with the other general-purpose timers and the advanced-control timers TIM1 and TIM8 via the Timer Link feature for synchronization or event chaining.

Any of these general-purpose timers can be used to generate PWM outputs.

TIM2, TIM3, TIM4, TIM5 all have independent DMA request generation. They are capable of handling quadrature (incremental) encoder signals and the digital outputs from 1 to 4 hall-effect sensors.

- **TIM9, TIM10, TIM11, TIM12, TIM13, and TIM14**

These timers are based on a 16-bit auto-reload upcounter and a 16-bit prescaler. TIM10, TIM11, TIM13, and TIM14 feature one independent channel, whereas TIM9 and TIM12 have two independent channels for input capture/output compare, PWM or one-pulse mode output. They can be synchronized with the TIM2, TIM3, TIM4, TIM5 full-featured general-purpose timers. They can also be used as simple time bases.

### 2.22.3 Basic timers TIM6 and TIM7

These timers are mainly used for DAC trigger and waveform generation. They can also be used as a generic 16-bit time base.

TIM6 and TIM7 support independent DMA request generation.

### 2.22.4 Low-power timer (LPTIM1)

The low-power timer has an independent clock and is running also in Stop mode if it is clocked by LSE, LSI or an external clock. It is able to wakeup the devices from Stop mode.

This low-power timer supports the following features:

- 16-bit up counter with 16-bit autoreload register
- 16-bit compare register
- Configurable output: pulse, PWM
- Continuous / one-shot mode
- Selectable software / hardware input trigger
- Selectable clock source:
  - Internal clock source: LSE, LSI, HSI or APB clock
  - External clock source over LPTIM input (working even with no internal clock source running, used by the Pulse Counter Application)
- Programmable digital glitch filter
- Encoder mode

### 2.22.5 Independent watchdog

The independent watchdog is based on a 12-bit downcounter and 8-bit prescaler. It is clocked from an independent 32 kHz internal RC and as it operates independently from the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free-running timer for application timeout management. It is hardware- or software-configurable through the option bytes.

### 2.22.6 Window watchdog

The window watchdog is based on a 7-bit downcounter that can be set as free-running. It can be used as a watchdog to reset the device when a problem occurs. It is clocked from the main clock. It has an early warning interrupt capability and the counter can be frozen in debug mode.

### 2.22.7 SysTick timer

This timer is dedicated to real-time operating systems, but could also be used as a standard downcounter. It features:

- A 24-bit downcounter
- Autoreload capability
- Maskable system interrupt generation when the counter reaches 0
- Programmable clock source.

## 2.23 Inter-integrated circuit interface (I<sup>2</sup>C)

The device embeds 4 I<sup>2</sup>C. Refer to table [Table 7: I<sup>2</sup>C implementation](#) for the features implementation.

The I<sup>2</sup>C bus interface handles communications between the microcontroller and the serial I<sup>2</sup>C bus. It controls all I<sup>2</sup>C bus-specific sequencing, protocol, arbitration and timing.

The I2C peripheral supports:

- I<sup>2</sup>C-bus specification and user manual rev. 5 compatibility:
  - Slave and master modes, multimaster capability
  - Standard-mode (Sm), with a bitrate up to 100 kbit/s
  - Fast-mode (Fm), with a bitrate up to 400 kbit/s
  - 7-bit and 10-bit addressing mode, multiple 7-bit slave addresses
  - Programmable setup and hold times
  - Optional clock stretching
- System Management Bus (SMBus) specification rev 2.0 compatibility:
  - Hardware PEC (Packet Error Checking) generation and verification with ACK control
  - Address resolution protocol (ARP) support
  - SMBus alert
- Power System Management Protocol (PMBus<sup>TM</sup>) specification rev 1.1 compatibility
- Independent clock: a choice of independent clock sources allowing the I2C communication speed to be independent from the PCLK reprogramming.
- Programmable analog and digital noise filters
- 1-byte buffer with DMA capability

**Table 7. I2C implementation**

I2C features <sup>(1)</sup>	I2C1	I2C2	I2C3	I2C4
Standard-mode (up to 100 kbit/s)	X	X	X	X
Fast-mode (up to 400 kbit/s)	X	X	X	X
Programmable analog and digital noise filters	X	X	X	X
SMBus/PMBus hardware support	X	X	X	X
Independent clock	X	X	X	X

1. X: supported

## 2.24 Universal synchronous/asynchronous receiver transmitters (USART)

The device embeds USART. Refer to [Table 8: USART implementation](#) for the features implementation.

The universal synchronous asynchronous receiver transmitter (USART) offers a flexible means of full-duplex data exchange with external equipment requiring an industry standard NRZ asynchronous serial data format.

The USART peripheral supports:

- Full-duplex asynchronous communications
- Configurable oversampling method by 16 or 8 to give flexibility between speed and clock tolerance
- Dual clock domain allowing convenient baud rate programming independent from the PCLK reprogramming
- A common programmable transmit and receive baud rate of up to 12.5 Mbit/s when the clock frequency is 100 MHz and oversampling is by 8.
- Auto baud rate detection
- Programmable data word length (7 or 8 or 9 bits) word length
- Programmable data order with MSB-first or LSB-first shifting
- Programmable parity (odd, even, no parity)
- Configurable stop bits (1 or 1.5 or 2 stop bits)
- Synchronous mode and clock output for synchronous communications
- Single-wire half-duplex communications
- Separate signal polarity control for transmission and reception
- Swappable Tx/Rx pin configuration
- Hardware flow control for modem and RS-485 transceiver
- Multiprocessor communications
- LIN master synchronous break send capability and LIN slave break detection capability
- IrDA SIR encoder decoder supporting 3/16 bit duration for normal mode
- Smartcard mode ( T=0 and T=1 asynchronous protocols for Smartcards as defined in the ISO/IEC 7816-3 standard )
- Support for Modbus communication

The table below summarizes the implementation of all U(S)ARTs instances

**Table 8. USART implementation**

features <sup>(1)</sup>	USART1/2/3/6	UART4/5/7/8
Data Length	7, 8 and 9 bits	
Hardware flow control for modem	X	X
Continuous communication using DMA	X	X
Multiprocessor communication	X	X
Synchronous mode	X	
Smartcard mode	X	
Single-wire half-duplex communication	X	X
IrDA SIR ENDEC block	X	X
LIN mode	X	X
Dual clock domain	X	X
Receiver timeout interrupt	X	X
Modbus communication	X	X

Table 8. USART implementation (continued)

features <sup>(1)</sup>	USART1/2/3/6	UART4/5/7/8
Auto baud rate detection	X	X
Driver Enable	X	X

1. X: supported

## 2.25 Serial peripheral interface (SPI)/inter- integrated sound interfaces (I2S)

The devices feature up to six SPIs in slave and master modes in full-duplex and simplex communication modes. SPI1, SPI4, SPI5, and SPI6 can communicate at up to 50 Mbits/s, SPI2 and SPI3 can communicate at up to 25 Mbit/s. The 3-bit prescaler gives 8 master mode frequencies and the frame is configurable from 4 to 16 bits. The SPI interfaces support NSS pulse mode, TI mode and Hardware CRC calculation. All SPIs can be served by the DMA controller.

Three standard I<sup>2</sup>S interfaces (multiplexed with SPI1, SPI2 and SPI3) are available. They can be operated in master or slave mode, in simplex communication modes, and can be configured to operate with a 16-/32-bit resolution as an input or output channel. Audio sampling frequencies from 8 kHz up to 192 kHz are supported. When either or both of the I<sup>2</sup>S interfaces is/are configured in master mode, the master clock can be output to the external DAC/CODEC at 256 times the sampling frequency.

All I2Sx can be served by the DMA controller.

## 2.26 Serial audio interface (SAI)

The devices embed two serial audio interfaces.

The serial audio interface is based on two independent audio subblocks which can operate as transmitter or receiver with their FIFO. Many audio protocols are supported by each block: I2S standards, LSB or MSB-justified, PCM/DSP, TDM, AC'97 and SPDIF output, supporting audio sampling frequencies from 8 kHz up to 192 kHz. Both subblocks can be configured in master or in slave mode.

In master mode, the master clock can be output to the external DAC/CODEC at 256 times of the sampling frequency.

The two sub-blocks can be configured in synchronous mode when full-duplex mode is required.

SAI1 and SAI2 can be served by the DMA controller

## 2.27 SPDIF-RX Receiver Interface (SPDIF-RX)

The SPDIF-RX peripheral, is designed to receive an S/PDIF flow compliant with IEC-60958 and IEC-61937. These standards support simple stereo streams up to high sample rate, and compressed multi-channel surround sound, such as those defined by Dolby or DTS (up to 5.1).

The main features of the SPDIF-RX are the following:

- Up to 4 inputs available
- Automatic symbol rate detection
- Maximum symbol rate: 12.288 MHz
- Stereo stream from 32 to 192 kHz supported
- Supports Audio IEC-60958 and IEC-61937, consumer applications
- Parity bit management
- Communication using DMA for audio samples
- Communication using DMA for control and user channel information
- Interrupt capabilities

The SPDIF-RX receiver provides all the necessary features to detect the symbol rate, and decode the incoming data stream. The user can select the wanted SPDIF input, and when a valid signal will be available, the SPDIF-RX will re-sample the incoming signal, decode the manchester stream, recognize frames, sub-frames and blocks elements. It delivers to the CPU decoded data, and associated status flags.

The SPDIF-RX also offers a signal named `spdif_frame_sync`, which toggles at the S/PDIF sub-frame rate that will be used to compute the exact sample rate for clock drift algorithms.

## 2.28 Audio PLL (PLLI2S)

The devices feature an additional dedicated PLL for audio I<sup>2</sup>S and SAI applications. It allows to achieve error-free I<sup>2</sup>S sampling clock accuracy without compromising on the CPU performance, while using USB peripherals.

The PLLI2S configuration can be modified to manage an I<sup>2</sup>S/SAI sample rate change without disabling the main PLL (PLL) used for CPU, USB and Ethernet interfaces.

The audio PLL can be programmed with very low error to obtain sampling rates ranging from 8 KHz to 192 KHz.

In addition to the audio PLL, a master clock input pin can be used to synchronize the I<sup>2</sup>S/SAI flow with an external PLL (or Codec output).

## 2.29 Audio and LCD PLL(PLLSAI)

An additional PLL dedicated to audio and LCD-TFT is used for SAI1 peripheral in case the PLLI2S is programmed to achieve another audio sampling frequency (49.152 MHz or 11.2896 MHz) and the audio application requires both sampling frequencies simultaneously.

The PLLSAI is also used to generate the LCD-TFT clock.

## 2.30 SD/SDIO/MMC card host interface (SDMMC)

An SDMMC host interface is available, that supports MultiMediaCard System Specification Version 4.2 in three different databus modes: 1-bit (default), 4-bit and 8-bit.

The interface allows data transfer at up to 50 MHz, and is compliant with the SD Memory Card Specification Version 2.0.

The SDMMC Card Specification Version 2.0 is also supported with two different databus modes: 1-bit (default) and 4-bit.

The current version supports only one SD/SDMMC/MMC4.2 card at any one time and a stack of MMC4.1 or previous.

The SDMMC can be served by the DMA controller

## 2.31 Ethernet MAC interface with dedicated DMA and IEEE 1588 support

The devices provide an IEEE-802.3-2002-compliant media access controller (MAC) for ethernet LAN communications through an industry-standard medium-independent interface (MII) or a reduced medium-independent interface (RMII). The microcontroller requires an external physical interface device (PHY) to connect to the physical LAN bus (twisted-pair, fiber, etc.). The PHY is connected to the device MII port using 17 signals for MII or 9 signals for RMII, and can be clocked using the 25 MHz (MII) from the microcontroller.

The devices include the following features:

- Supports 10 and 100 Mbit/s rates
- Dedicated DMA controller allowing high-speed transfers between the dedicated SRAM and the descriptors
- Tagged MAC frame support (VLAN support)
- Half-duplex (CSMA/CD) and full-duplex operation
- MAC control sublayer (control frames) support
- 32-bit CRC generation and removal
- Several address filtering modes for physical and multicast address (multicast and group addresses)
- 32-bit status code for each transmitted or received frame
- Internal FIFOs to buffer transmit and receive frames. The transmit FIFO and the receive FIFO are both 2 Kbytes.
- Supports hardware PTP (precision time protocol) in accordance with IEEE 1588 2008 (PTP V2) with the time stamp comparator connected to the TIM2 input
- Triggers interrupt when system time becomes greater than target time

## 2.32 Controller area network (bxCAN)

The two CANs are compliant with the 2.0A and B (active) specifications with a bitrate up to 1 Mbit/s. They can receive and transmit standard frames with 11-bit identifiers as well as extended frames with 29-bit identifiers. Each CAN has three transmit mailboxes, two receive FIFOs with 3 stages and 28 shared scalable filter banks (all of them can be used even if one CAN is used). 256 bytes of SRAM are allocated for each CAN.

## 2.33 Universal serial bus on-the-go full-speed (OTG\_FS)

The device embeds an USB OTG full-speed device/host/OTG peripheral with integrated transceivers. The USB OTG FS peripheral is compliant with the USB 2.0 specification and with the OTG 2.0 specification. It has software-configurable endpoint setting and supports suspend/resume. The USB OTG controller requires a dedicated 48 MHz clock that is generated by a PLL connected to the HSE oscillator.

The major features are:

- Combined Rx and Tx FIFO size of 1.28 KB with dynamic FIFO sizing
- Supports the session request protocol (SRP) and host negotiation protocol (HNP)
- 1 bidirectional control endpoint + 5 IN endpoints + 5 OUT endpoints
- 12 host channels with periodic OUT support
- Software configurable to OTG1.3 and OTG2.0 modes of operation
- USB 2.0 LPM (Link Power Management) support
- Internal FS OTG PHY support
- HNP/SNP/IP inside (no need for any external resistor)

For OTG/Host modes, a power switch is needed in case bus-powered devices are connected

## 2.34 Universal serial bus on-the-go high-speed (OTG\_HS)

The device embeds a USB OTG high-speed (up to 480 Mb/s) device/host/OTG peripheral. The USB OTG HS supports both full-speed and high-speed operations. It integrates the transceivers for full-speed operation (12 MB/s) and features a UTMI low-pin interface (ULPI) for high-speed operation (480 MB/s). When using the USB OTG HS in HS mode, an external PHY device connected to the ULPI is required.

The USB OTG HS peripheral is compliant with the USB 2.0 specification and with the OTG 2.0 specification. It has software-configurable endpoint setting and supports suspend/resume. The USB OTG controller requires a dedicated 48 MHz clock that is generated by a PLL connected to the HSE oscillator.

The major features are:

- Combined Rx and Tx FIFO size of 4 KB with dynamic FIFO sizing
- Supports the session request protocol (SRP) and host negotiation protocol (HNP)
- 8 bidirectional endpoints
- 16 host channels with periodic OUT support
- Software configurable to OTG1.3 and OTG2.0 modes of operation
- USB 2.0 LPM (Link Power Management) support
- Internal FS OTG PHY support
- External HS or HS OTG operation supporting ULPI in SDR mode. The OTG PHY is connected to the microcontroller ULPI port through 12 signals. It can be clocked using the 60 MHz output.
- Internal USB DMA
- HNP/SNP/IP inside (no need for any external resistor)
- for OTG/Host modes, a power switch is needed in case bus-powered devices are connected

## 2.35 High-definition multimedia interface (HDMI) - consumer electronics control (CEC)

The device embeds a HDMI-CEC controller that provides hardware support for the Consumer Electronics Control (CEC) protocol (Supplement 1 to the HDMI standard).

This protocol provides high-level control functions between all audiovisual products in an environment. It is specified to operate at low speeds with minimum processing and memory overhead. It has a clock domain independent from the CPU clock, allowing the HDMI-CEC controller to wakeup the MCU from Stop mode on data reception.

## 2.36 Digital camera interface (DCMI)

The devices embed a camera interface that can connect with camera modules and CMOS sensors through an 8-bit to 14-bit parallel interface, to receive video data. The camera interface can sustain a data transfer rate up to 54 Mbyte/s at 54 MHz. It features:

- Programmable polarity for the input pixel clock and synchronization signals
- Parallel data communication can be 8-, 10-, 12- or 14-bit
- Supports 8-bit progressive video monochrome or raw bayer format, YCbCr 4:2:2 progressive video, RGB 565 progressive video or compressed data (like JPEG)
- Supports continuous mode or snapshot (a single frame) mode
- Capability to automatically crop the image

## 2.37 Cryptographic acceleration

The devices embed a cryptographic accelerator. This cryptographic accelerator provides a set of hardware acceleration for the advanced cryptographic algorithms usually needed to provide confidentiality, authentication, data integrity and non repudiation when exchanging messages with a peer.

- These algorithms consists of:
  - Encryption/Decryption
    - DES/TDES (data encryption standard/triple data encryption standard): ECB (electronic codebook) and CBC (cipher block chaining) chaining algorithms, 64-, 128- or 192-bit key
    - AES (advanced encryption standard): ECB, CBC, GCM, CCM, and CTR (counter mode) chaining algorithms, 128, 192 or 256-bit key
  - Universal hash
    - SHA-1 and SHA-2 (secure hash algorithms)
    - MD5
    - HMAC

The cryptographic accelerator supports DMA request generation.

## 2.38 Random number generator (RNG)

All devices embed an RNG that delivers 32-bit random numbers generated by an integrated analog circuit.

## 2.39 General-purpose input/outputs (GPIOs)

Each of the GPIO pins can be configured by software as output (push-pull or open-drain, with or without pull-up or pull-down), as input (floating, with or without pull-up or pull-down) or as peripheral alternate function. Most of the GPIO pins are shared with digital or analog alternate functions. All GPIOs are high-current-capable and have speed selection to better manage internal noise, power consumption and electromagnetic emission.

The I/O configuration can be locked if needed by following a specific sequence in order to avoid spurious writing to the I/Os registers.

Fast I/O handling allowing maximum I/O toggling up to 100 MHz.

## 2.40 Analog-to-digital converters (ADCs)

Three 12-bit analog-to-digital converters are embedded and each ADC shares up to 16 external channels, performing conversions in the single-shot or scan mode. In scan mode, automatic conversion is performed on a selected group of analog inputs.

Additional logic functions embedded in the ADC interface allow:

- Simultaneous sample and hold
- Interleaved sample and hold

The ADC can be served by the DMA controller. An analog watchdog feature allows very precise monitoring of the converted voltage of one, some or all selected channels. An interrupt is generated when the converted voltage is outside the programmed thresholds.

To synchronize A/D conversion and timers, the ADCs could be triggered by any of TIM1, TIM2, TIM3, TIM4, TIM5, or TIM8 timer.

## 2.41 Temperature sensor

The temperature sensor has to generate a voltage that varies linearly with temperature. The conversion range is between 1.7 V and 3.6 V. The temperature sensor is internally connected to the same input channel as  $V_{BAT}$ , ADC1\_IN18, which is used to convert the sensor output voltage into a digital value. When the temperature sensor and  $V_{BAT}$  conversion are enabled at the same time, only  $V_{BAT}$  conversion is performed.

As the offset of the temperature sensor varies from chip to chip due to process variation, the internal temperature sensor is mainly suitable for applications that detect temperature changes instead of absolute temperatures. If an accurate temperature reading is needed, then an external temperature sensor part should be used.

## 2.42 Digital-to-analog converter (DAC)

The two 12-bit buffered DAC channels can be used to convert two digital signals into two analog voltage signal outputs.

This dual digital Interface supports the following features:

- two DAC converters: one for each output channel
- 8-bit or 12-bit monotonic output
- left or right data alignment in 12-bit mode
- synchronized update capability
- noise-wave generation
- triangular-wave generation
- dual DAC channel independent or simultaneous conversions
- DMA capability for each channel
- external triggers for conversion
- input voltage reference  $V_{REF+}$

Eight DAC trigger inputs are used in the device. The DAC channels are triggered through the timer update outputs that are also connected to different DMA streams.

## 2.43 Serial wire JTAG debug port (SWJ-DP)

The ARM SWJ-DP interface is embedded, and is a combined JTAG and serial wire debug port that enables either a serial wire debug or a JTAG probe to be connected to the target.

Debug is performed using 2 pins only instead of 5 required by the JTAG (JTAG pins could be re-use as GPIO with alternate function): the JTAG TMS and TCK pins are shared with SWDIO and SWCLK, respectively, and a specific sequence on the TMS pin is used to switch between JTAG-DP and SW-DP.

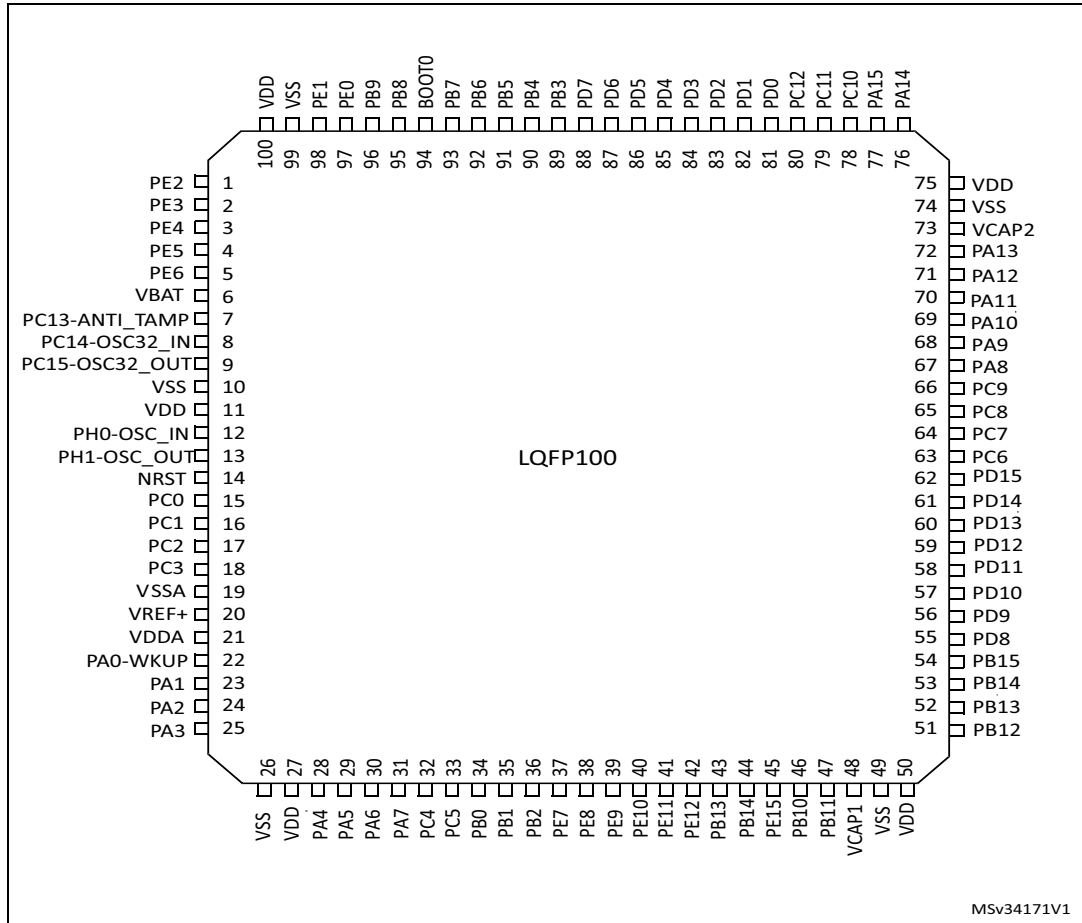
## 2.44 Embedded Trace Macrocell™

The ARM Embedded Trace Macrocell provides a greater visibility of the instruction and data flow inside the CPU core by streaming compressed data at a very high rate from the STM32F756xx through a small number of ETM pins to an external hardware trace port analyzer (TPA) device. The TPA is connected to a host computer using USB, Ethernet, or any other high-speed channel. Real-time instruction and data flow activity can be recorded and then formatted for display on the host computer that runs the debugger software. TPA hardware is commercially available from common development tool vendors.

The Embedded Trace Macrocell operates with third party debugger software tools.

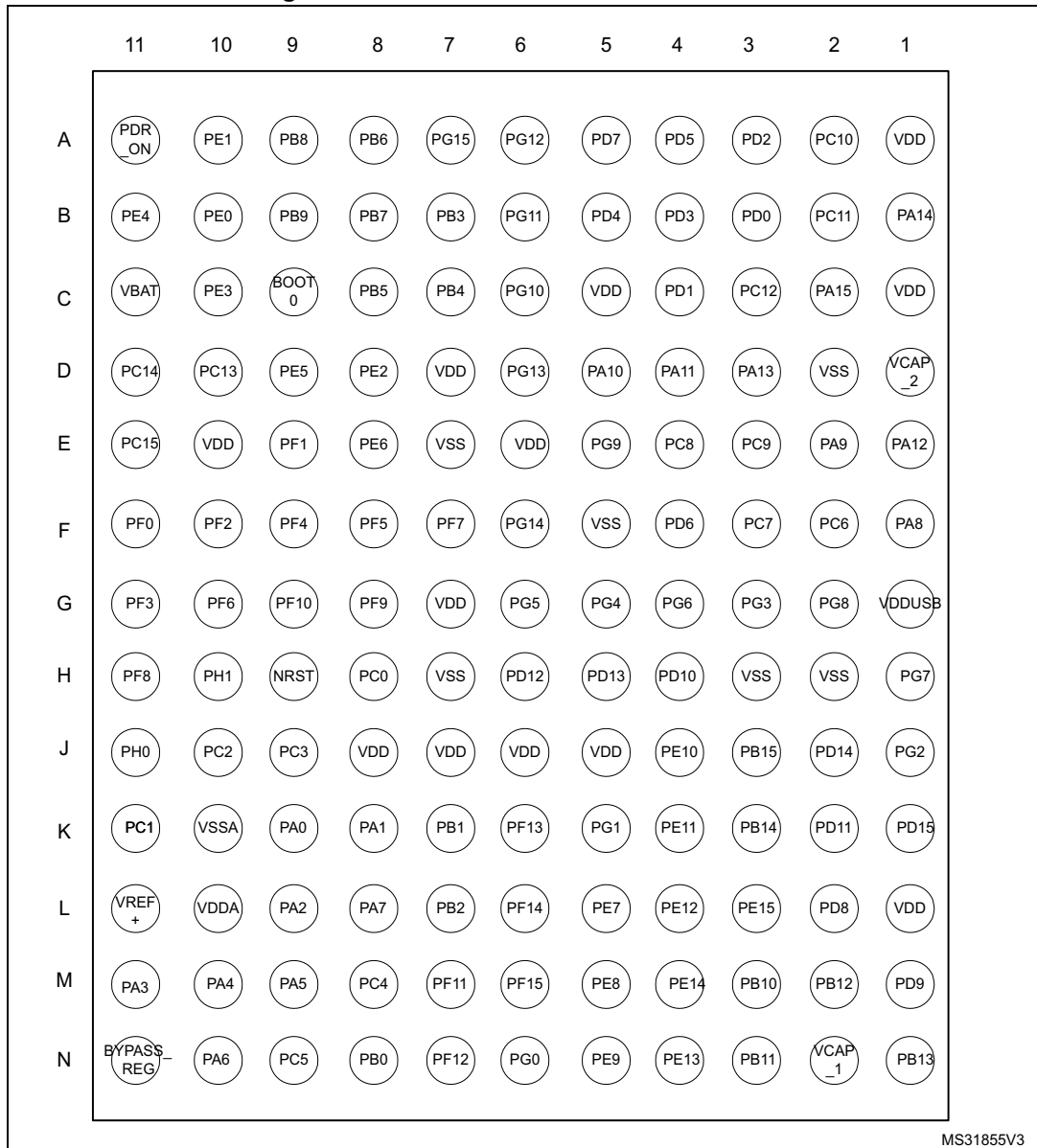
### 3 Pinouts and pin description

Figure 9. STM32F756xx LQFP100 pinout



1. The above figure shows the package top view.

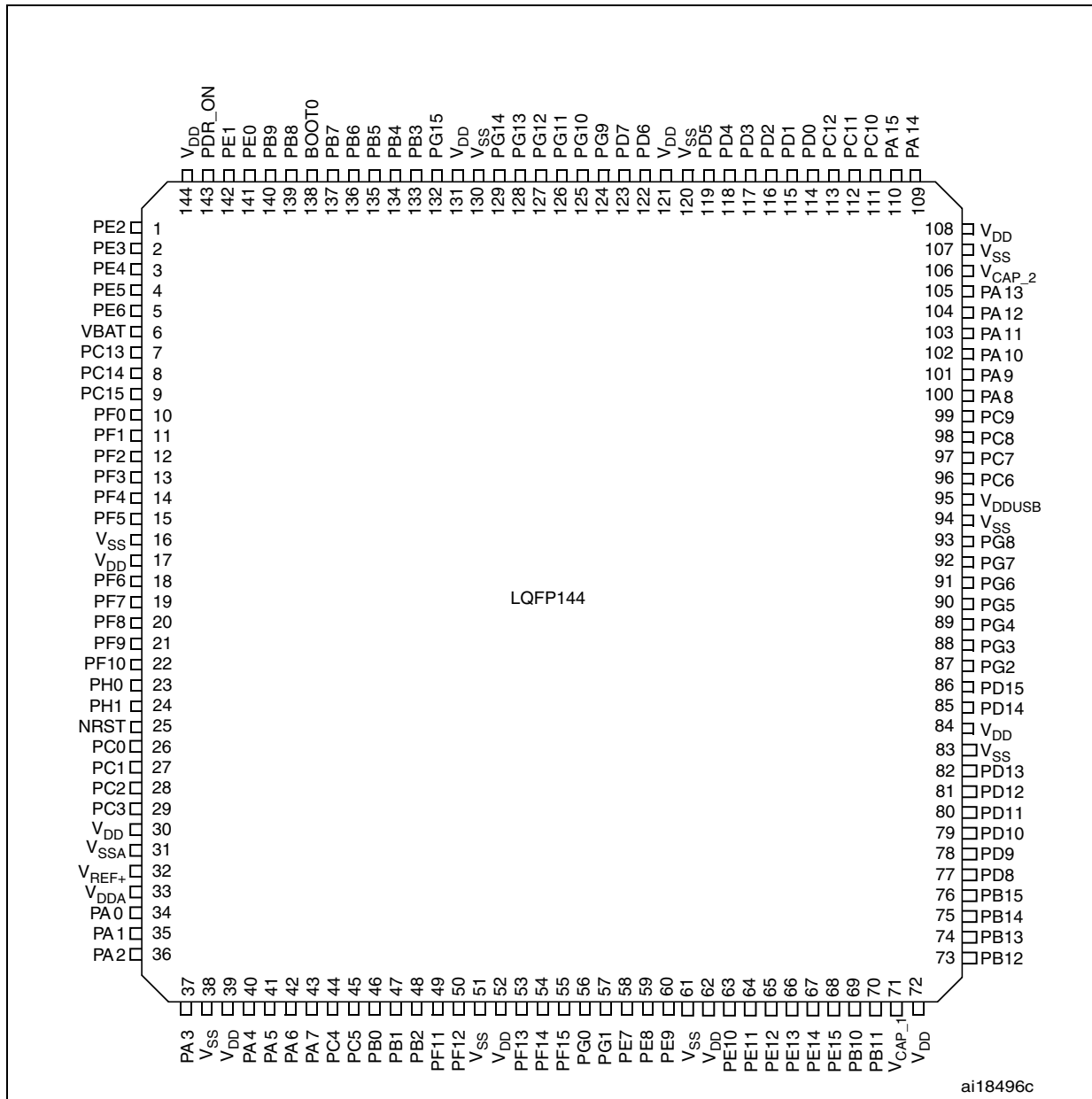
Figure 10. STM32F756xx WLCSP143 ballout



MS31855V3

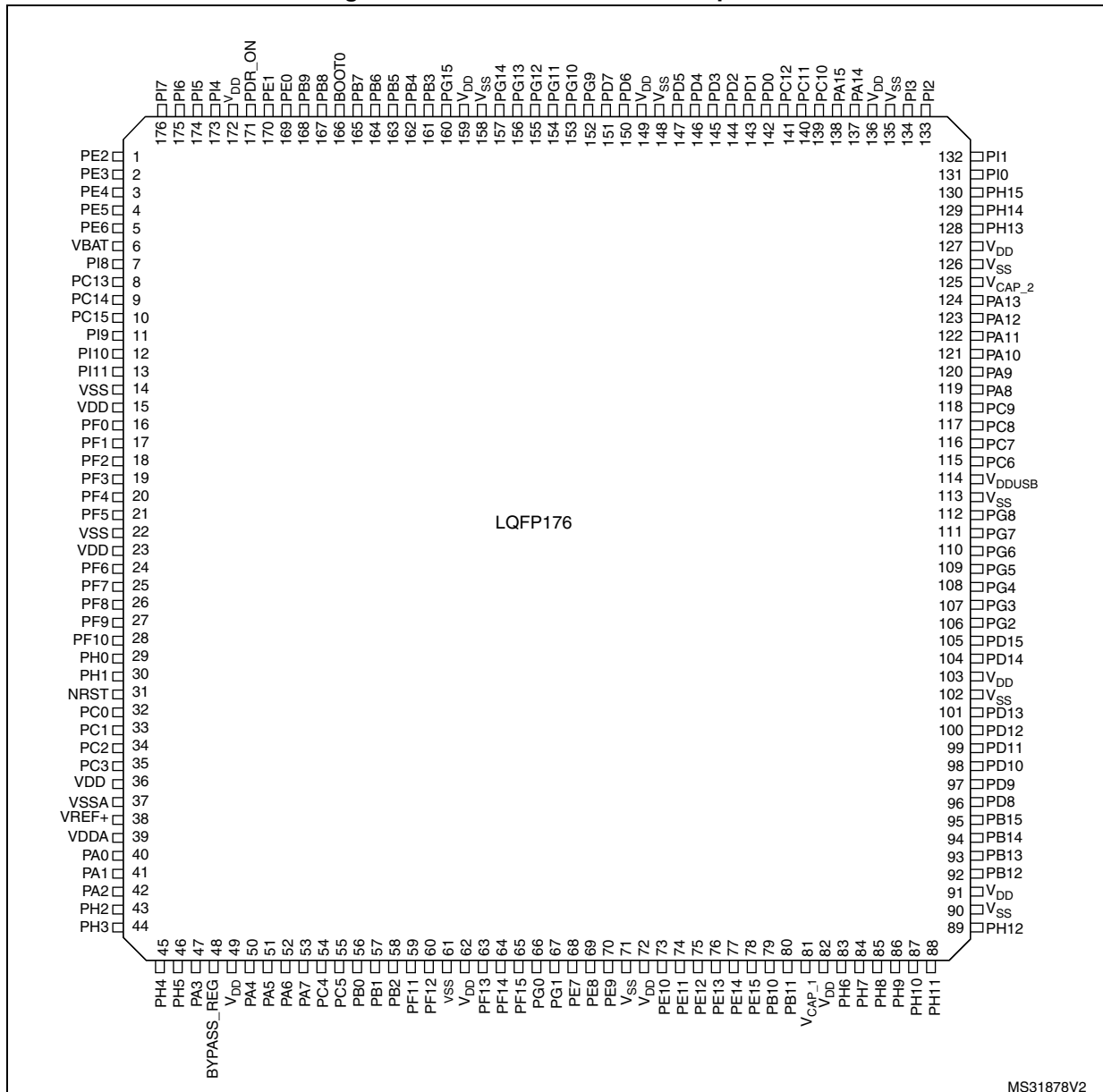
The above figure shows the package bump view.

Figure 11. STM32F756xx LQFP144 pinout



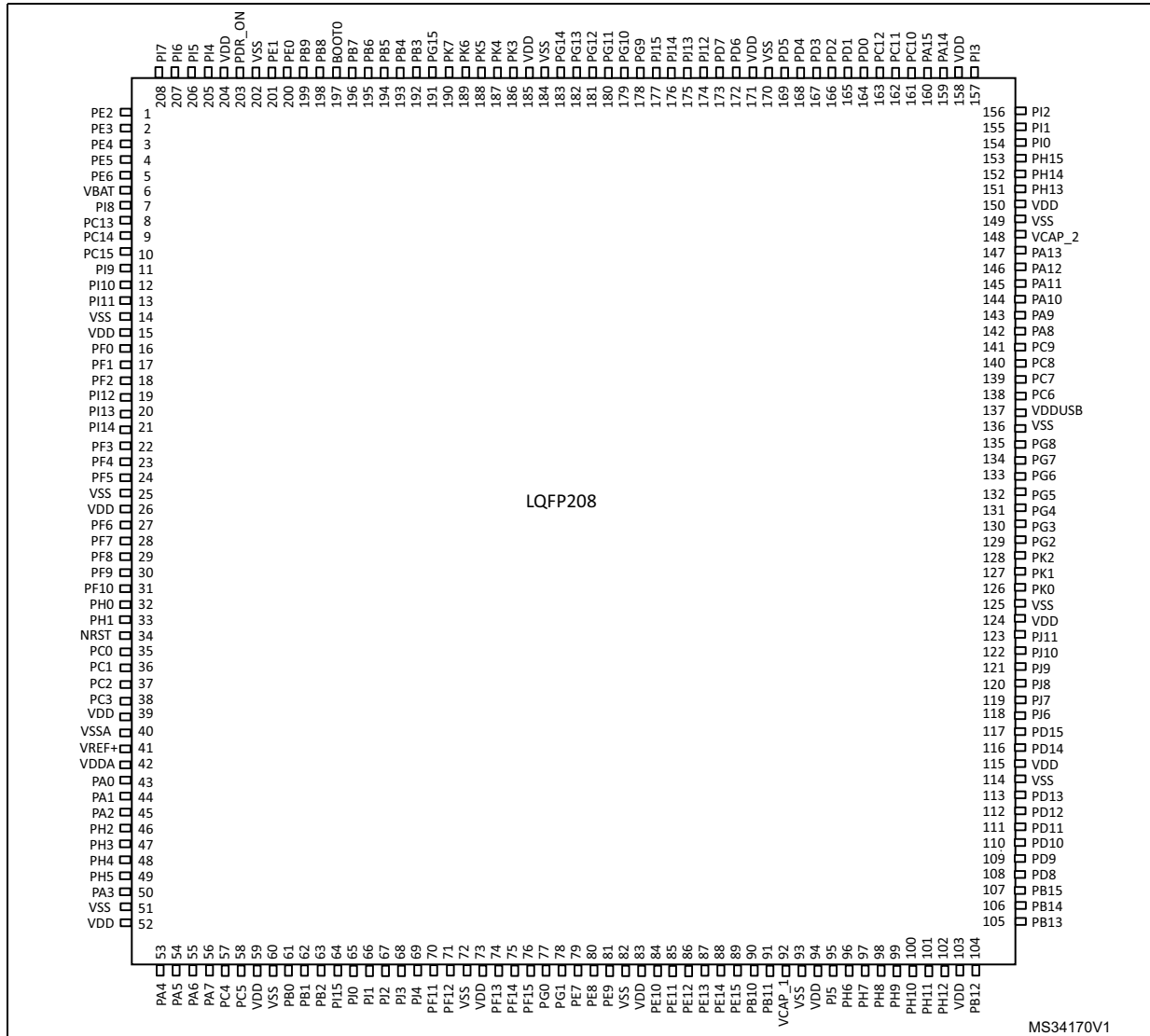
1. The above figure shows the package top view.

Figure 12. STM32F756xx LQFP176 pinout



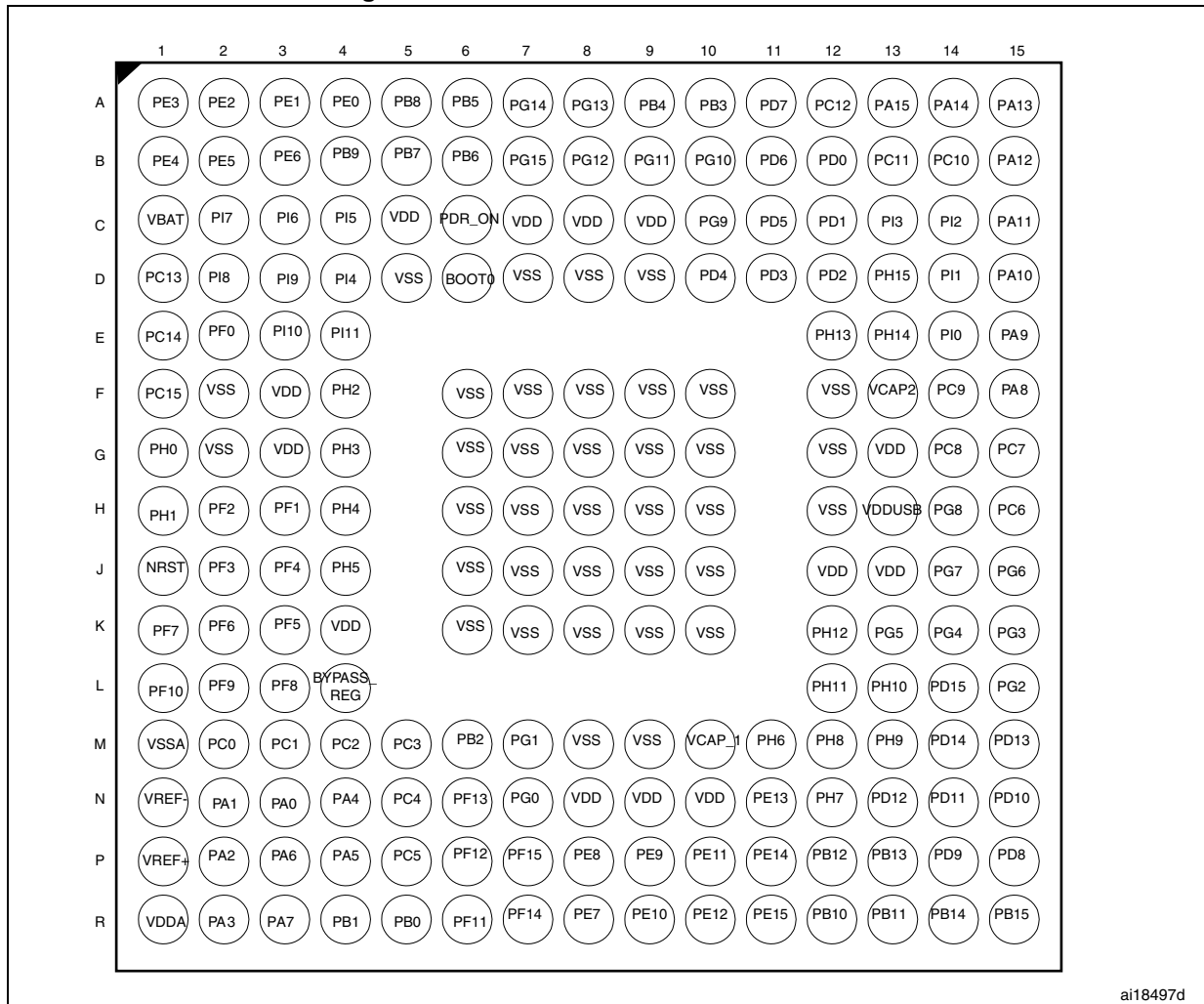
1. The above figure shows the package top view.

Figure 13. STM32F756xx LQFP208 pinout



1. The above figure shows the package top view.

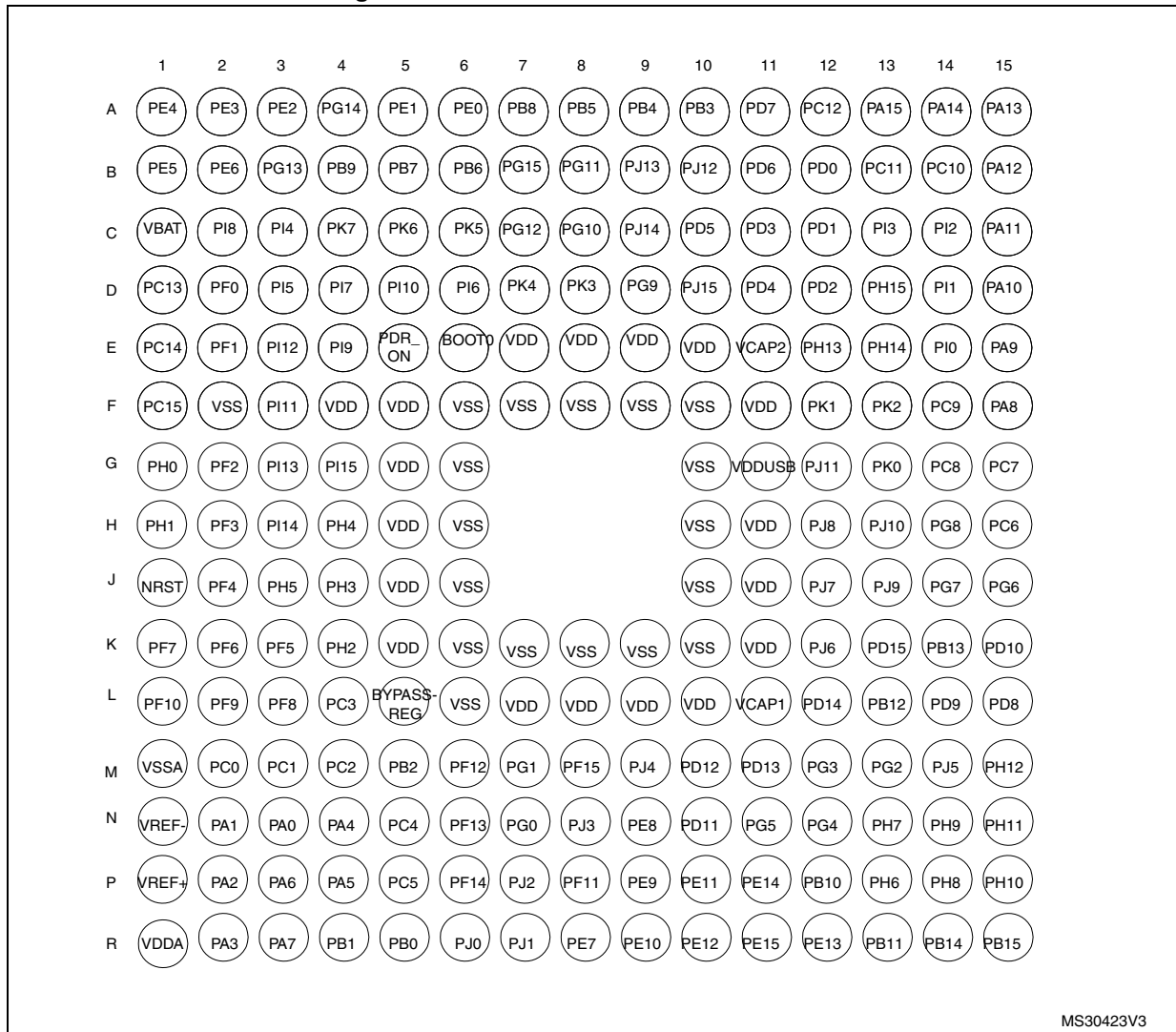
Figure 14. STM32F756xx UFBGA176 ballout



ai18497d

1. The above figure shows the package top view.

Figure 15. STM32F756xx TFBGA216 ballout



MS30423V3

1. The above figure shows the package top view.

**Table 9. Legend/abbreviations used in the pinout table**

Name	Abbreviation	Definition
Pin name	Unless otherwise specified in brackets below the pin name, the pin function during and after reset is the same as the actual pin name	
Pin type	S	Supply pin
	I	Input only pin
	I/O	Input / output pin
I/O structure	FT	5 V tolerant I/O
	TTa	3.3 V tolerant I/O directly connected to ADC
	B	Dedicated BOOT pin
	RST	Bidirectional reset pin with weak pull-up resistor
Notes	Unless otherwise specified by a note, all I/Os are set as floating inputs during and after reset	
Alternate functions	Functions selected through GPIOx_AFR registers	
Additional functions	Functions directly selected/enabled through peripheral registers	

**Table 10. STM32F756xx pin and ball definition**

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
1	D8	1	A2	1	1	A3	PE2	I/O	FT	-	TRACECLK, SPI4_SCK, SAI1_MCLK_A, QUADSPI_BK1_IO2, ETH_MII_TXD3, FMC_A23, EVENTOUT	-
2	C10	2	A1	2	2	A2	PE3	I/O	FT	-	TRACED0, SAI1_SD_B, FMC_A19, EVENTOUT	-
3	B11	3	B1	3	3	A1	PE4	I/O	FT	-	TRACED1, SPI4_NSS, SAI1_FS_A, FMC_A20, DCMI_D4, LCD_B0, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
4	D9	4	B2	4	4	B1	PE5	I/O	FT	-	TRACED2, TIM9_CH1, SPI4_MISO, SAI1_SCK_A, FMC_A21, DCMI_D6, LCD_G0, EVENTOUT	-
5	E8	5	B3	5	5	B2	PE6	I/O	FT	-	TRACED3, TIM1_BKIN2, TIM9_CH2, SPI4_MOSI, SAI1_SD_A, SAI2_MCK_B, FMC_A22, DCMI_D7, LCD_G1, EVENTOUT	-
-	-	-	-	-	-	G6	VSS	S	-	-	-	-
-	-	-	-	-	-	F5	VDD	S	-	-	-	-
6	C11	6	C1	6	6	C1	VBAT	S	-	-	-	-
-	-	-	D2	7	7	C2	PI8	I/O	FT	(2) (3)	EVENTOUT	RTC_TAMP2/ RTC_TS,WKUP3
7	D10	7	D1	8	8	D1	PC13	I/O	FT	(2) (3)	EVENTOUT	RTC_TAMP1/ RTC_TS/RTC_OUT ,WKUP2
8	D11	8	E1	9	9	E1	PC14- OSC32_I N(PC14)	I/O	FT	(2) (3)	EVENTOUT	OSC32_IN
9	E11	9	F1	10	10	F1	PC15- OSC32_ OUT(PC 15)	I/O	FT	(2) (3)	EVENTOUT	OSC32_OUT
-	-	-	-	-	-	F2	VSS	S	-	-	-	-
-	-	-	-	-	-	G5	VDD	S	-	-	-	-
-	-	-	D3	11	11	E4	PI9	I/O	FT	-	CAN1_RX, FMC_D30, LCD_VSYNC, EVENTOUT	-
-	-	-	E3	12	12	D5	PI10	I/O	FT	-	ETH_MII_RX_ER, FMC_D31, LCD_HSYNC, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	-	E4	13	13	F3	PI11	I/O	FT	-	OTG_HS_ULPI_DIR, EVENTOUT	WKUP4
-	E7	-	F2	14	14	F2	VSS	S	-	-	-	-
-	E10	-	F3	15	15	F4	VDD	S	-	-	-	-
-	F11	10	E2	16	16	D2	PF0	I/O	FT	-	I2C2_SDA, FMC_A0, EVENTOUT	-
-	E9	11	H3	17	17	E2	PF1	I/O	FT	-	I2C2_SCL, FMC_A1, EVENTOUT	-
-	F10	12	H2	18	18	G2	PF2	I/O	FT	-	I2C2_SMBA, FMC_A2, EVENTOUT	-
-	-	-	-	-	19	E3	PI12	I/O	FT	-	LCD_HSYNC, EVENTOUT	-
-	-	-	-	-	20	G3	PI13	I/O	FT	-	LCD_VSYNC, EVENTOUT	-
-	-	-	-	-	21	H3	PI14	I/O	FT	-	LCD_CLK, EVENTOUT	-
-	G11	13	J2	19	22	H2	PF3	I/O	FT	-	FMC_A3, EVENTOUT	ADC3_IN9
-	F9	14	J3	20	23	J2	PF4	I/O	FT	-	FMC_A4, EVENTOUT	ADC3_IN14
-	F8	15	K3	21	24	K3	PF5	I/O	FT	-	FMC_A5, EVENTOUT	ADC3_IN15
10	H7	16	G2	22	25	H6	VSS	S	-	-	-	-
11	-	17	G3	23	26	H5	VDD	S	-	-	-	-
-	G10	18	K2	24	27	K2	PF6	I/O	FT	-	TIM10_CH1, SPI5_NSS, SAI1_SD_B, UART7_Rx, QUADSPI_BK1_IO3, EVENTOUT	ADC3_IN4
-	F7	19	K1	25	28	K1	PF7	I/O	FT	-	TIM11_CH1, SPI5_SCK, SAI1_MCLK_B, UART7_Tx, QUADSPI_BK1_IO2, EVENTOUT	ADC3_IN5

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	H11	20	L3	26	29	L3	PF8	I/O	FT	-	SPI5_MISO, SAI1_SCK_B, UART7_RTS, TIM13_CH1, QUADSPI_BK1_IO0, EVENTOUT	ADC3_IN6
-	G8	21	L2	27	30	L2	PF9	I/O	FT	-	SPI5_MOSI, SAI1_FS_B, UART7_CTS, TIM14_CH1, QUADSPI_BK1_IO1, EVENTOUT	ADC3_IN7
-	G9	22	L1	28	31	L1	PF10	I/O	FT	-	DCMI_D11, LCD_DE, EVENTOUT	ADC3_IN8
12	J11	23	G1	29	32	G1	PH0-OSC_IN(PH0)	I/O	FT	-	EVENTOUT	OSC_IN <sup>(4)</sup>
13	H10	24	H1	30	33	H1	PH1-OSC_OUT(PH1)	I/O	FT	-	EVENTOUT	OSC_OUT <sup>(4)</sup>
14	H9	25	J1	31	34	J1	NRST	I/O	RS T	-	-	-
15	H8	26	M2	32	35	M2	PC0	I/O	FT	(4)	SAI2_FS_B, OTG_HS_ULPI_STP, FMC_SDNWE, LCD_R5, EVENTOUT	ADC123_IN10
16	K11	27	M3	33	36	M3	PC1	I/O	FT	(4)	TRACED0, SPI2_MOSI/I2S2_SD, SAI1_SD_A, ETH_MDC, EVENTOUT	ADC123_IN11, RTC_TAMP3, WKUP5
17	J10	28	M4	34	37	M4	PC2	I/O	FT	(4)	SPI2_MISO, OTG_HS_ULPI_DIR, ETH_MII_TXD2, FMC_SDNE0, EVENTOUT	ADC123_IN12

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
18	J9	29	M5	35	38	L4	PC3	I/O	FT	(4)	SPI2_MOSI/I2S2_SD, OTG_HS_ULPI_NXT, ETH_MII_TX_CLK, FMC_SDCKE0, EVENTOUT	ADC123_IN13
-	G7	30	G3	36	39	J5	VDD	S	-	-	-	-
-	-	-	-	-	-	J6	VSS	S	-	-	-	-
19	K10	31	M1	37	40	M1	VSSA	S	-	-	-	-
-	-	-	N1	-	-	N1	VREF-	S	-	-	-	-
20	L11	32	P1	38	41	P1	VREF+	S	-	-	-	-
21	L10	33	R1	39	42	R1	VDDA	S	-	-	-	-
22	K9	34	N3	40	43	N3	PA0- WKUP(P A0)	I/O	FT	(5)	TIM2_CH1/TIM2_ETR, TIM5_CH1, TIM8_ETR, USART2_CTS, UART4_TX, SAI2_SD_B, ETH_MII_CRS, EVENTOUT	ADC123_IN0, WKUP0 <sup>(4)</sup>
23	K8	35	N2	41	44	N2	PA1	I/O	FT	(4)	TIM2_CH2, TIM5_CH2, USART2_RTS, UART4_RX, QUADSPI_BK1_IO3, SAI2_MCK_B, ETH_MII_RX_CLK/ETH_ RMII_REF_CLK, LCD_R2, EVENTOUT	ADC123_IN1
24	L9	36	P2	42	45	P2	PA2	I/O	FT	(4)	TIM2_CH3, TIM5_CH3, TIM9_CH1, USART2_TX, SAI2_SCK_B, ETH_MDIO, LCD_R1, EVENTOUT	ADC123_IN2, WKUP1
-	-	-	F4	43	46	K4	PH2	I/O	FT		LPTIM1_IN2, QUADSPI_BK2_IO0, SAI2_SCK_B, ETH_MII_CRS, FMC_SDCKE0, LCD_R0, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	-	G4	44	47	J4	PH3	I/O	FT	-	QUADSPI_BK2_IO1, SAI2_MCK_B, ETH_MII_COL, FMC_SDNE0, LCD_R1, EVENTOUT	-
-	-	-	H4	45	48	H4	PH4	I/O	FT	-	I2C2_SCL, OTG_HS_ULPI_NXT, EVENTOUT	-
-	-	-	J4	46	49	J3	PH5	I/O	FT	-	I2C2_SDA, SPI5_NSS, FMC_SDNWE, EVENTOUT	-
25	M11	37	R2	47	50	R2	PA3	I/O	FT	(4)	TIM2_CH4, TIM5_CH4, TIM9_CH2, USART2_RX, OTG_HS_ULPI_D0, ETH_MII_COL, LCD_B5, EVENTOUT	ADC123_IN3
26	-	38	-	-	51	K6	VSS	S	-	-	-	-
-	N11	-	L4	48	-	L5	BYPASS_REG	I	FT	-	-	-
27	J8	39	K4	49	52	K5	VDD	S	-	-	-	-
28	M10	40	N4	50	53	N4	PA4	I/O	TTa	(4)	SPI1_NSS/I2S1_WS, SPI3_NSS/I2S3_WS, USART2_CK, OTG_HS_SOF, DCMI_HSYNC, LCD_VSYNC, EVENTOUT	ADC12_IN4, DAC_OUT1
29	M9	41	P4	51	54	P4	PA5	I/O	TTa	(4)	TIM2_CH1/TIM2_ETR, TIM8_CH1N, SPI1_SCK/I2S1_CK, OTG_HS_ULPI_CK, LCD_R4, EVENTOUT	ADC12_IN5, DAC_OUT2
30	N10	42	P3	52	55	P3	PA6	I/O	FT	(4)	TIM1_BKIN, TIM3_CH1, TIM8_BKIN, SPI1_MISO, TIM13_CH1, DCMI_PIXCLK, LCD_G2, EVENTOUT	ADC12_IN6

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
31	L8	43	R3	53	56	R3	PA7	I/O	FT	(4)	TIM1_CH1N, TIM3_CH2, TIM8_CH1N, SPI1_MOSI/I2S1_SD, TIM14_CH1, ETH_MII_RX_DV/ETH_RMII_CRS_DV, FMC_SDNWE, EVENTOUT	ADC12_IN7
32	M8	44	N5	54	57	N5	PC4	I/O	FT	(4)	I2S1_MCK, SPDIF_RX2, ETH_MII_RXD0/ETH_RMII_RXD0, FMC_SDNE0, EVENTOUT	ADC12_IN14
33	N9	45	P5	55	58	P5	PC5	I/O	FT	(4)	SPDIF_RX3, ETH_MII_RXD1/ETH_RMII_RXD1, FMC_SDCKE0, EVENTOUT	ADC12_IN15
-	J7	-	-	-	59	L7	VDD	S	-	-	-	-
-	-	-	-	-	60	L6	VSS	S	-	-	-	-
34	N8	46	R5	56	61	R5	PB0	I/O	FT	(4)	TIM1_CH2N, TIM3_CH3, TIM8_CH2N, UART4_CTS, LCD_R3, OTG_HS_ULPI_D1, ETH_MII_RXD2, EVENTOUT	ADC12_IN8
35	K7	47	R4	57	62	R4	PB1	I/O	FT	(4)	TIM1_CH3N, TIM3_CH4, TIM8_CH3N, LCD_R6, OTG_HS_ULPI_D2, ETH_MII_RXD3, EVENTOUT	ADC12_IN9
36	L7	48	M6	58	63	M5	PB2	I/O	FT	-	SAI1_SD_A, SPI3_MOSI/I2S3_SD, QUADSPI_CLK, EVENTOUT	-
-	-	-	-	-	64	G4	PI15	I/O	FT	-	LCD_R0, EVENTOUT	-
-	-	-	-	-	65	R6	PJ0	I/O	FT	-	LCD_R1, EVENTOUT	-
-	-	-	-	-	66	R7	PJ1	I/O	FT	-	LCD_R2, EVENTOUT	-
-	-	-	-	-	67	P7	PJ2	I/O	FT	-	LCD_R3, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	-	-	-	68	N8	PJ3	I/O	FT	-	LCD_R4, EVENTOUT	-
-	-	-	-	-	69	M9	PJ4	I/O	FT	-	LCD_R5, EVENTOUT	-
-	M7	49	R6	59	70	P8	PF11	I/O	FT	-	SPI5_MOSI, SAI2_SD_B, FMC_SDNRAS, DCMI_D12, EVENTOUT	-
-	N7	50	P6	60	71	M6	PF12	I/O	FT	-	FMC_A6, EVENTOUT	-
-	-	51	M8	61	72	K7	VSS	S	-	-	-	-
-	-	52	N8	62	73	L8	VDD	S	-	-	-	-
-	K6	53	N6	63	74	N6	PF13	I/O	FT	-	I2C4_SMBA, FMC_A7, EVENTOUT	-
-	L6	54	R7	64	75	P6	PF14	I/O	FT	-	I2C4_SCL, FMC_A8, EVENTOUT	-
-	M6	55	P7	65	76	M8	PF15	I/O	FT	-	I2C4_SDA, FMC_A9, EVENTOUT	-
-	N6	56	N7	66	77	N7	PG0	I/O	FT	-	FMC_A10, EVENTOUT	-
-	K5	57	M7	67	78	M7	PG1	I/O	FT	-	FMC_A11, EVENTOUT	-
37	L5	58	R8	68	79	R8	PE7	I/O	FT	-	TIM1_ETR, UART7_Rx, QUADSPI_BK2_IO0, FMC_D4, EVENTOUT	-
38	M5	59	P8	69	80	N9	PE8	I/O	FT	-	TIM1_CH1N, UART7_Tx, QUADSPI_BK2_IO1, FMC_D5, EVENTOUT	-
39	N5	60	P9	70	81	P9	PE9	I/O	FT	-	TIM1_CH1, UART7_RTS, QUADSPI_BK2_IO2, FMC_D6, EVENTOUT	-
-	H3	61	M9	71	82	K8	VSS	S	-	-	-	-
-	J5	62	N9	72	83	L9	VDD	S	-	-	-	-
40	J4	63	R9	73	84	R9	PE10	I/O	FT	-	TIM1_CH2N, UART7_CTS, QUADSPI_BK2_IO3, FMC_D7, EVENTOUT	-
41	K4	64	P10	74	85	P10	PE11	I/O	FT	-	TIM1_CH2, SPI4_NSS, SAI2_SD_B, FMC_D8, LCD_G3, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
42	L4	65	R10	75	86	R10	PE12	I/O	FT	-	TIM1_CH3N, SPI4_SCK, SAI2_SCK_B, FMC_D9, LCD_B4, EVENTOUT	-
43	N4	66	N11	76	87	R12	PE13	I/O	FT	-	TIM1_CH3, SPI4_MISO, SAI2_FS_B, FMC_D10, LCD_DE, EVENTOUT	-
44	M4	67	P11	77	88	P11	PE14	I/O	FT	-	TIM1_CH4, SPI4_MOSI, SAI2_MCK_B, FMC_D11, LCD_CLK, EVENTOUT	-
45	L3	68	R11	78	89	R11	PE15	I/O	FT	-	TIM1_BKIN, FMC_D12, LCD_R7, EVENTOUT	-
46	M3	69	R12	79	90	P12	PB10	I/O	FT	-	TIM2_CH3, I2C2_SCL, SPI2_SCK/I2S2_CK, USART3_TX, OTG_HS_ULPI_D3, ETH_MII_RX_ER, LCD_G4, EVENTOUT	-
47	N3	70	R13	80	91	R13	PB11	I/O	FT	-	TIM2_CH4, I2C2_SDA, USART3_RX, OTG_HS_ULPI_D4, ETH_MII_TX_EN/ETH_R MII_TX_EN, LCD_G5, EVENTOUT	-
48	N2	71	M10	81	92	L11	VCAP_1	S	-	-	-	-
49	H2	-	-	-	93	K9	VSS	S	-	-	-	-
50	J6	72	N10	82	94	L10	VDD	S	-	-	-	-
-	-	-	-	-	95	M14	PJ5	I/O	FT	-	LCD_R6, EVENTOUT	-
-	-	-	M11	83	96	P13	PH6	I/O	FT	-	I2C2_SMBA, SPI5_SCK, TIM12_CH1, ETH_MII_RXD2, FMC_SDNE1, DCMI_D8, EVENTOUT	-
-	-	-	N12	84	97	N13	PH7	I/O	FT	-	I2C3_SCL, SPI5_MISO, ETH_MII_RXD3, FMC_SDCKE1, DCMI_D9, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	-	M12	85	98	P14	PH8	I/O	FT	-	I2C3_SDA, FMC_D16, DCMI_HSYNC, LCD_R2, EVENTOUT	-
-	-	-	M13	86	99	N14	PH9	I/O	FT	-	I2C3_SMBA, TIM12_CH2, FMC_D17, DCMI_D0, LCD_R3, EVENTOUT	-
-	-	-	L13	87	100	P15	PH10	I/O	FT	-	TIM5_CH1, I2C4_SMBA, FMC_D18, DCMI_D1, LCD_R4, EVENTOUT	-
-	-	-	L12	88	101	N15	PH11	I/O	FT	-	TIM5_CH2, I2C4_SCL, FMC_D19, DCMI_D2, LCD_R5, EVENTOUT	-
-	-	-	K12	89	102	M15	PH12	I/O	FT	-	TIM5_CH3, I2C4_SDA, FMC_D20, DCMI_D3, LCD_R6, EVENTOUT	-
-	-	-	H12	90	-	K10	VSS	S	-	-	-	-
-	-	-	J12	91	103	K11	VDD	S	-	-	-	-
51	M2	73	P12	92	104	L13	PB12	I/O	FT	-	TIM1_BKIN, I2C2_SMBA, SPI2_NSS/I2S2_WS, USART3_CK, CAN2_RX, OTG_HS_ULPI_D5, ETH_MII_TXD0/ETH_RMII_TXD0, OTG_HS_ID, EVENTOUT	-
52	N1	74	P13	93	105	K14	PB13	I/O	FT	-	TIM1_CH1N, SPI2_SCK/I2S2_CK, USART3_CTS, CAN2_TX, OTG_HS_ULPI_D6, ETH_MII_TXD1/ETH_RMII_TXD1, EVENTOUT	OTG_HS_VBUS

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
53	K3	75	R14	94	106	R14	PB14	I/O	FT	-	TIM1_CH2N, TIM8_CH2N, SPI2_MISO, USART3_RTS, TIM12_CH1, OTG_HS_DM, EVENTOUT	-
54	J3	76	R15	95	107	R15	PB15	I/O	FT	-	RTC_REFIN, TIM1_CH3N, TIM8_CH3N, SPI2_MOSI/I2S2_SD, TIM12_CH2, OTG_HS_DP, EVENTOUT	-
55	L2	77	P15	96	108	L15	PD8	I/O	FT	-	USART3_TX, SPDIF_RX1, FMC_D13, EVENTOUT	-
56	M1	78	P14	97	109	L14	PD9	I/O	FT	-	USART3_RX, FMC_D14, EVENTOUT	-
57	H4	79	N15	98	110	K15	PD10	I/O	FT	-	USART3_CK, FMC_D15, LCD_B3, EVENTOUT	-
58	K2	80	N14	99	111	N10	PD11	I/O	FT	-	I2C4_SMBA, USART3_CTS, QUADSPI_BK1_IO0, SAI2_SD_A, FMC_A16/FMC_CLE, EVENTOUT	-
59	H6	81	N13	100	112	M10	PD12	I/O	FT	-	TIM4_CH1, LPTIM1_IN1, I2C4_SCL, USART3_RTS, QUADSPI_BK1_IO1, SAI2_FS_A, FMC_A17/FMC_ALE, EVENTOUT	-
60	H5	82	M15	101	113	M11	PD13	I/O	FT	-	TIM4_CH2, LPTIM1_OUT, I2C4_SDA, QUADSPI_BK1_IO3, SAI2_SCK_A, FMC_A18, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	83	-	102	114	J10	VSS	S	-	-	-	-
-	L1	84	J13	103	115	J11	VDD	S	-	-	-	-
61	J2	85	M14	104	116	L12	PD14	I/O	FT	-	TIM4_CH3, UART8_CTS, FMC_D0, EVENTOUT	-
62	K1	86	L14	105	117	K13	PD15	I/O	FT	-	TIM4_CH4, UART8_RTS, FMC_D1, EVENTOUT	-
-	-	-	-	-	118	K12	PJ6	I/O	FT	-	LCD_R7, EVENTOUT	-
-	-	-	-	-	119	J12	PJ7	I/O	FT	-	LCD_G0, EVENTOUT	-
-	-	-	-	-	120	H12	PJ8	I/O	FT	-	LCD_G1, EVENTOUT	-
-	-	-	-	-	121	J13	PJ9	I/O	FT	-	LCD_G2, EVENTOUT	-
-	-	-	-	-	122	H13	PJ10	I/O	FT	-	LCD_G3, EVENTOUT	-
-	-	-	-	-	123	G12	PJ11	I/O	FT	-	LCD_G4, EVENTOUT	-
-	-	-	-	-	124	H11	VDD	S	-	-	-	-
-	-	-	-	-	125	H10	VSS	S	-	-	-	-
-	-	-	-	-	126	G13	PK0	I/O	FT	-	LCD_G5, EVENTOUT	-
-	-	-	-	-	127	F12	PK1	I/O	FT	-	LCD_G6, EVENTOUT	-
-	-	-	-	-	128	F13	PK2	I/O	FT	-	LCD_G7, EVENTOUT	-
-	J1	87	L15	106	129	M13	PG2	I/O	FT	-	FMC_A12, EVENTOUT	-
-	G3	88	K15	107	130	M12	PG3	I/O	FT	-	FMC_A13, EVENTOUT	-
-	G5	89	K14	108	131	N12	PG4	I/O	FT	-	FMC_A14/FMC_BA0, EVENTOUT	-
-	G6	90	K13	109	132	N11	PG5	I/O	FT	-	FMC_A15/FMC_BA1, EVENTOUT	-
-	G4	91	J15	110	133	J15	PG6	I/O	FT	-	DCMI_D12, LCD_R7, EVENTOUT	-
-	H1	92	J14	111	134	J14	PG7	I/O	FT	-	USART6_CK, FMC_INT, DCMI_D13, LCD_CLK, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	G2	93	H14	112	135	H14	PG8	I/O	FT	-	SPI6_NSS, SPDIF_RX2, USART6_RTS, ETH_PPS_OUT, FMC_SDCLK, EVENTOUT	-
-	D2	94	G12	113	136	G10	VSS	S	-	-	-	-
-	G1	95	H13	114	137	G11	VDDUSB	S	-	-	-	-
63	F2	96	H15	115	138	H15	PC6	I/O	FT	-	TIM3_CH1, TIM8_CH1, I2S2_MCK, USART6_TX, SDMMC_D6, DCMI_D0, LCD_HSYNC, EVENTOUT	-
64	F3	97	G15	116	139	G15	PC7	I/O	FT	-	TIM3_CH2, TIM8_CH2, I2S3_MCK, USART6_RX, SDMMC_D7, DCMI_D1, LCD_G6, EVENTOUT	-
65	E4	98	G14	117	140	G14	PC8	I/O	FT	-	TRACED1, TIM3_CH3, TIM8_CH3, UART5_RTS, USART6_CK, SDMMC_D0, DCMI_D2, EVENTOUT	-
66	E3	99	F14	118	141	F14	PC9	I/O	FT	-	MCO2, TIM3_CH4, TIM8_CH4, I2C3_SDA, I2S_CKIN, UART5_CTS, QUADSPI_BK1_IO0, SDMMC_D1, DCMI_D3, EVENTOUT	-
67	F1	100	F15	119	142	F15	PA8	I/O	FT	-	MCO1, TIM1_CH1, TIM8_BKIN2, I2C3_SCL, USART1_CK, OTG_FS_SOF, LCD_R6, EVENTOUT	-
68	E2	101	E15	120	143	E15	PA9	I/O	FT	-	TIM1_CH2, I2C3_SMBA, SPI2_SCK/I2S2_CK, USART1_TX, DCMI_D0, EVENTOUT	OTG_FS_VBUS

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
69	D5	102	D15	121	144	D15	PA10	I/O	FT	-	TIM1_CH3, USART1_RX, OTG_FS_ID, DCMI_D1, EVENTOUT	-
70	D4	103	C15	122	145	C15	PA11	I/O	FT	-	TIM1_CH4, USART1_CTS, CAN1_RX, OTG_FS_DM, LCD_R4, EVENTOUT	-
71	E1	104	B15	123	146	B15	PA12	I/O	FT	-	TIM1_ETR, USART1_RTS, SAI2_FS_B, CAN1_TX, OTG_FS_DP, LCD_R5, EVENTOUT	-
72	D3	105	A15	124	147	A15	PA13(JT MS-SWDIO)	I/O	FT	-	JTMS-SWDIO, EVENTOUT	-
73	D1	106	F13	125	148	E11	VCAP_2	S	-	-	-	-
74	D2	107	F12	126	149	F10	VSS	S	-	-	-	-
75	C1	108	G13	127	150	F11	VDD	S	-	-	-	-
-	-	-	E12	128	151	E12	PH13	I/O	FT	-	TIM8_CH1N, CAN1_TX, FMC_D21, LCD_G2, EVENTOUT	-
-	-	-	E13	129	152	E13	PH14	I/O	FT	-	TIM8_CH2N, FMC_D22, DCMI_D4, LCD_G3, EVENTOUT	-
-	-	-	D13	130	153	D13	PH15	I/O	FT	-	TIM8_CH3N, FMC_D23, DCMI_D11, LCD_G4, EVENTOUT	-
-	-	-	E14	131	154	E14	PI0	I/O	FT	-	TIM5_CH4, SPI2_NSS/I2S2_WS, FMC_D24, DCMI_D13, LCD_G5, EVENTOUT	-
-	-	-	D14	132	155	D14	PI1	I/O	FT	-	TIM8_BKIN2, SPI2_SCK/I2S2_CK, FMC_D25, DCMI_D8, LCD_G6, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	-	C14	133	156	C14	PI2	I/O	FT	-	TIM8_CH4, SPI2_MISO, FMC_D26, DCMI_D9, LCD_G7, EVENTOUT	-
-	-	-	C13	134	157	C13	PI3	I/O	FT	-	TIM8_ETR, SPI2_MOSI/I2S2_SD, FMC_D27, DCMI_D10, EVENTOUT	-
-	F5	-	D9	135	-	F9	VSS	S	-	-	-	-
-	A1	-	C9	136	158	E10	VDD	S	-	-	-	-
76	B1	109	A14	137	159	A14	PA14(JT CK-SWCLK)	I/O	FT	-	JTCK-SWCLK, EVENTOUT	-
77	C2	110	A13	138	160	A13	PA15(JT DI)	I/O	FT	-	JTDI, TIM2_CH1/TIM2_ETR, HDMI-CEC, SPI1_NSS/I2S1_WS, SPI3_NSS/I2S3_WS, UART4_RTS, EVENTOUT	-
78	A2	111	B14	139	161	B14	PC10	I/O	FT	-	SPI3_SCK/I2S3_CK, USART3_TX, UART4_TX, QUADSPI_BK1_IO1, SDMMC_D2, DCMI_D8, LCD_R2, EVENTOUT	-
79	B2	112	B13	140	162	B13	PC11	I/O	FT	-	SPI3_MISO, USART3_RX, UART4_RX, QUADSPI_BK2_NCS, SDMMC_D3, DCMI_D4, EVENTOUT	-
80	C3	113	A12	141	163	A12	PC12	I/O	FT	-	TRACED3, SPI3_MOSI/I2S3_SD, USART3_CK, UART5_TX, SDMMC_CK, DCMI_D9, EVENTOUT	-
81	B3	114	B12	142	164	B12	PD0	I/O	FT	-	CAN1_RX, FMC_D2, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
82	C4	115	C12	143	165	C12	PD1	I/O	FT	-	CAN1_TX, FMC_D3, EVENTOUT	-
83	A3	116	D12	144	166	D12	PD2	I/O	FT	-	TRACED2, TIM3_ETR, UART5_RX, SDMMC_CMD, DCM1_D11, EVENTOUT	-
84	B4	117	D11	145	167	C11	PD3	I/O	FT	-	SPI2_SCK/I2S2_CK, USART2_CTS, FMC_CLK, DCM1_D5, LCD_G7, EVENTOUT	-
85	B5	118	D10	146	168	D11	PD4	I/O	FT	-	USART2_RTS, FMC_NOE, EVENTOUT	-
86	A4	119	C11	147	169	C10	PD5	I/O	FT	-	USART2_TX, FMC_NWE, EVENTOUT	-
-	-	120	D8	148	170	F8	VSS	S	-	-	-	-
-	C5	121	C8	149	171	E9	VDD	S	-	-	-	-
87	F4	122	B11	150	172	B11	PD6	I/O	FT	-	SPI3_MOSI/I2S3_SD, SAI1_SD_A, USART2_RX, FMC_NWAIT, DCM1_D10, LCD_B2, EVENTOUT	-
88	A5	123	A11	151	173	A11	PD7	I/O	FT	-	USART2_CK, SPDIF_RX0, FMC_NE1, EVENTOUT	-
-	-	-	-	-	174	B10	PJ12	I/O	FT	-	LCD_B0, EVENTOUT	-
-	-	-	-	-	175	B9	PJ13	I/O	FT	-	LCD_B1, EVENTOUT	-
-	-	-	-	-	176	C9	PJ14	I/O	FT	-	LCD_B2, EVENTOUT	-
-	-	-	-	-	177	D10	PJ15	I/O	FT	-	LCD_B3, EVENTOUT	-
-	E5	124	C10	152	178	D9	PG9	I/O	FT	-	SPDIF_RX3, USART6_RX, QUADSPI_BK2_IO2, SAI2_FS_B, FMC_NE2/FMC_NCE, DCM1_VSYNC, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	C6	125	B10	153	179	C8	PG10	I/O	FT	-	LCD_G3, SAI2_SD_B, FMC_NE3, DCMI_D2, LCD_B2, EVENTOUT	-
-	B6	126	B9	154	180	B8	PG11	I/O	FT	-	SPDIF_RX0, ETH_MII_TX_EN/ETH_R MII_TX_EN, DCMI_D3, LCD_B3, EVENTOUT	-
-	A6	127	B8	155	181	C7	PG12	I/O	FT	-	LPTIM1_IN1, SPI6_MISO, SPDIF_RX1, USART6_RTS, LCD_B4, FMC_NE4, LCD_B1, EVENTOUT	-
-	D6	128	A8	156	182	B3	PG13	I/O	FT	-	TRACED0, LPTIM1_OUT, SPI6_SCK, USART6_CTS, ETH_MII_TXD0/ETH_RM II_TXD0, FMC_A24, LCD_R0, EVENTOUT	-
-	F6	129	A7	157	183	A4	PG14	I/O	FT	-	TRACED1, LPTIM1_ETR, SPI6_MOSI, USART6_TX, QUADSPI_BK2_IO3, ETH_MII_TXD1/ETH_RM II_TXD1, FMC_A25, LCD_B0, EVENTOUT	-
-	-	130	D7	158	184	F7	VSS	S	-	-	-	-
-	E6	131	C7	159	185	E8	VDD	S	-	-	-	-
-	-	-	-	-	186	D8	PK3	I/O	FT	-	LCD_B4, EVENTOUT	-
-	-	-	-	-	187	D7	PK4	I/O	FT	-	LCD_B5, EVENTOUT	-
-	-	-	-	-	188	C6	PK5	I/O	FT	-	LCD_B6, EVENTOUT	-
-	-	-	-	-	189	C5	PK6	I/O	FT	-	LCD_B7, EVENTOUT	-
-	-	-	-	-	190	C4	PK7	I/O	FT	-	LCD_DE, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	A7	132	B7	160	191	B7	PG15	I/O	FT	-	USART6_CTS, FMC_SDNCAS, DCMI_D13, EVENTOUT	-
89	B7	133	A10	161	192	A10	PB3(JTD O/TRAC ESWO)	I/O	FT	-	JTDO/TRACESWO, TIM2_CH2, SPI1_SCK/I2S1_CK, SPI3_SCK/I2S3_CK, EVENTOUT	-
90	C7	134	A9	162	193	A9	PB4(NJT RST)	I/O	FT	-	NJTRST, TIM3_CH1, SPI1_MISO, SPI3_MISO, SPI2_NSS/I2S2_WS, EVENTOUT	-
91	C8	135	A6	163	194	A8	PB5	I/O	FT	-	TIM3_CH2, I2C1_SMBA, SPI1_MOSI/I2S1_SD, SPI3_MOSI/I2S3_SD, CAN2_RX, OTG_HS_ULPI_D7, ETH_PPS_OUT, FMC_SDCKE1, DCMI_D10, EVENTOUT	-
92	A8	136	B6	164	195	B6	PB6	I/O	FT	-	TIM4_CH1, HDMI-CEC, I2C1_SCL, USART1_TX, CAN2_TX, QUADSPI_BK1_NCS, FMC_SDNE1, DCMI_D5, EVENTOUT	-
93	B8	137	B5	165	196	B5	PB7	I/O	FT	-	TIM4_CH2, I2C1_SDA, USART1_RX, FMC_NL, DCMI_VSYNC, EVENTOUT	-
94	C9	138	D6	166	197	E6	BOOT	I	B	-	-	VPP
95	A9	139	A5	167	198	A7	PB8	I/O	FT	-	TIM4_CH3, TIM10_CH1, I2C1_SCL, CAN1_RX, ETH_MII_TXD3, SDMMC_D4, DCMI_D6, LCD_B6, EVENTOUT	-

Table 10. STM32F756xx pin and ball definition (continued)

Pin Number							Pin name (function after reset) <sup>(1)</sup>	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
96	B9	140	B4	168	199	B4	PB9	I/O	FT	-	TIM4_CH4, TIM11_CH1, I2C1_SDA, SPI2_NSS/I2S2_WS, CAN1_TX, SDMMC_D5, DCM1_D7, LCD_B7, EVENTOUT	-
97	B10	141	A4	169	200	A6	PE0	I/O	FT	-	TIM4_ETR, LPTIM1_ETR, UART8_Rx, SAI2_MCK_A, FMC_NBL0, DCM1_D2, EVENTOUT	-
98	A10	142	A3	170	201	A5	PE1	I/O	FT	-	LPTIM1_IN2, UART8_Tx, FMC_NBL1, DCM1_D3, EVENTOUT	-
99	-	-	D5	-	202	F6	VSS	S	-	-	-	-
-	A11	143	C6	171	203	E5	PDR_ON	S	-	-	-	-
100	D7	144	C5	172	204	E7	VDD	S	-	-	-	-
-	-	-	D4	173	205	C3	PI4	I/O	FT	-	TIM8_BKIN, SAI2_MCK_A, FMC_NBL2, DCM1_D5, LCD_B4, EVENTOUT	-
-	-	-	C4	174	206	D3	PI5	I/O	FT	-	TIM8_CH1, SAI2_SCK_A, FMC_NBL3, DCM1_VSYNC, LCD_B5, EVENTOUT	-
-	-	-	C3	175	207	D6	PI6	I/O	FT	-	TIM8_CH2, SAI2_SD_A, FMC_D28, DCM1_D6, LCD_B6, EVENTOUT	-
-	-	-	C2	176	208	D4	PI7	I/O	FT	-	TIM8_CH3, SAI2_FS_A, FMC_D29, DCM1_D7, LCD_B7, EVENTOUT	-

1. Function availability depends on the chosen device.

2. PC13, PC14, PC15 and PI8 are supplied through the power switch. Since the switch only sinks a limited amount of current (3 mA), the use of GPIOs PC13 to PC15 and PI8 in output mode is limited:
  - The speed should not exceed 2 MHz with a maximum load of 30 pF.
  - These I/Os must not be used as a current source (e.g. to drive an LED).
3. Main function after the first backup domain power-up. Later on, it depends on the contents of the RTC registers even after reset (because these registers are not reset by the main reset). For details on how to manage these I/Os, refer to the RTC register description sections in the STM32F7xxx reference manual.
4. FT = 5 V tolerant except when in analog mode or oscillator mode (for PC14, PC15, PH0 and PH1).
5. If the device is delivered in an WLCSP143, UFBGA176, LQFP176 or TFBGA216 package, and the BYPASS\_REG pin is set to VDD (Regulator OFF/internal reset ON mode), then PA0 is used as an internal Reset (active low).

Table 11. FMC pin definition

Pin name	NOR/PSRAM/SRAM	NOR/PSRAM Mux	NAND16	SDRAM
PF0	A0	-	-	A0
PF1	A1	-	-	A1
PF2	A2	-	-	A2
PF3	A3	-	-	A3
PF4	A4	-	-	A4
PF5	A5	-	-	A5
PF12	A6	-	-	A6
PF13	A7	-	-	A7
PF14	A8	-	-	A8
PF15	A9	-	-	A9
PG0	A10	-	-	A10
PG1	A11	-	-	A11
PG2	A12	-	-	A12
PG3	A13	-	-	-
PG4	A14	-	-	BA0
PG5	A15	-	-	BA1
PD11	A16	A16	CLE	-
PD12	A17	A17	ALE	-
PD13	A18	A18	-	-
PE3	A19	A19	-	-
PE4	A20	A20	-	-
PE5	A21	A21	-	-
PE6	A22	A22	-	-
PE2	A23	A23	-	-
PG13	A24	A24	-	-
PG14	A25	A25	-	-
PD14	D0	DA0	D0	D0
PD15	D1	DA1	D1	D1
PD0	D2	DA2	D2	D2
PD1	D3	DA3	D3	D3
PE7	D4	DA4	D4	D4
PE8	D5	DA5	D5	D5
PE9	D6	DA6	D6	D6
PE10	D7	DA7	D7	D7

Table 11. FMC pin definition (continued)

Pin name	NOR/PSRAM/SRAM	NOR/PSRAM Mux	NAND16	SDRAM
PE11	D8	DA8	D8	D8
PE12	D9	DA9	D9	D9
PE13	D10	DA10	D10	D10
PE14	D11	DA11	D11	D11
PE15	D12	DA12	D12	D12
PD8	D13	DA13	D13	D13
PD9	D14	DA14	D14	D14
PD10	D15	DA15	D15	D15
PH8	D16	-	-	D16
PH9	D17	-	-	D17
PH10	D18	-	-	D18
PH11	D19	-	-	D19
PH12	D20	-	-	D20
PH13	D21	-	-	D21
PH14	D22	-	-	D22
PH15	D23	-	-	D23
PI0	D24	-	-	D24
PI1	D25	-	-	D25
PI2	D26	-	-	D26
PI3	D27	-	-	D27
PI6	D28	-	-	D28
PI7	D29	-	-	D29
PI9	D30	-	-	D30
PI10	D31	-	-	D31
PD7	NE1	NE1	-	-
PG9	NE2	NE2	NCE	-
PG10	NE3	NE3	-	-
PG11	-	-	-	-
PG12	NE4	NE4	-	-
PD3	CLK	CLK	-	-
PD4	NOE	NOE	NOE	-
PD5	NWE	NWE	NWE	-
PD6	NWAIT	NWAIT	NWAIT	-
PB7	NADV	NADV	-	-

Table 11. FMC pin definition (continued)

Pin name	NOR/PSRAM/SRAM	NOR/PSRAM Mux	NAND16	SDRAM
PF6	-	-	-	-
PF7	-	-	-	-
PF8	-	-	-	-
PF9	-	-	-	-
PF10	-	-	-	-
PG6	-	-	-	-
PG7	-	-	INT	-
PE0	NBL0	NBL0	-	NBL0
PE1	NBL1	NBL1	-	NBL1
PI4	NBL2	-	-	NBL2
PI5	NBL3	-	-	NBL3
PG8	-	-	-	SDCLK
PC0	-	-	-	SDNWE
PF11	-	-	-	SDNRAS
PG15	-	-	-	SDNCAS
PH2	-	-	-	SDCKE0
PH3	-	-	-	SDNE0
PH6	-	-	-	SDNE1
PH7	-	-	-	SDCKE1
PH5	-	-	-	SDNWE
PC2	-	-	-	SDNE0
PC3	-	-	-	SDCKE0
PB5	-	-	-	SDCKE1
PB6	-	-	-	SDNE1



**Table 12. STM32F756xx alternate function mapping**

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15	
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/11/LPTIM1/CEC	I2C1/2/3/4/CEC	SPI1/2/3/4/5/6	SPI3/SAI1	SPI2/3/UART1/2/3/UART5/SPDIF	SAI2/USART6/UART4/5/7/8/SPDIF	CAN1/2/TIM12/13/14/QUADSPI/LCD	SAI2/QUADSPI/OTG1_FS	ETH/OTG1_FS	FMC/SDMMC/OTG2_FS	DCMI	LCD	SYS	
Port A	PA0	-	TIM2_C H1/TIM2_ETR	TIM5_C H1	TIM8_ETR	-	-	-	USART2_CTS	UART4_TX	-	SAI2_SDB	ETH_MII_CRS	-	-	-	EVEN TOUT	
	PA1	-	TIM2_C H2	TIM5_C H2	-	-	-	-	USART2_RTS	UART4_RX	QUADSPI_BK1_IO3	SAI2_MCK_B	ETH_MII_RX_CLK/ETH_RMII_REF_CLK	-	-	LCD_R2	EVEN TOUT	
	PA2	-	TIM2_C H3	TIM5_C H3	TIM9_CH1	-	-	-	USART2_TX	SAI2_SCK_B	-	-	ETH_MDI_O	-	-	LCD_R1	EVEN TOUT	
	PA3	-	TIM2_C H4	TIM5_C H4	TIM9_CH2	-	-	-	USART2_RX	-	-	OTG_HS_ULPI_D0	ETH_MII_COL	-	-	LCD_B5	EVEN TOUT	
	PA4	-	-	-	-	-	-	SPI1_NSS/I2S1_WS	SPI3_NSS/I2S3_WS	USART2_CK	-	-	-	OTG_HS_SOF	DCMI_HSYNC	LCD_VSYNC	EVEN TOUT	
	PA5	-	TIM2_C H1/TIM2_ETR	-	TIM8_CH1N	-	-	SPI1_SCK/I2S1_CK	-	-	-	-	OTG_HS_ULPI_CK	-	-	-	LCD_R4	EVEN TOUT
	PA6	-	TIM1_BKIN	TIM3_C H1	TIM8_BKIN	-	-	SPI1_MISO	-	-	-	TIM13_C H1	-	-	DCMI_PIXCLK	LCD_G2	EVEN TOUT	
	PA7	-	TIM1_C H1N	TIM3_C H2	TIM8_CH1N	-	-	SPI1_MOSI/I2S1_SD	-	-	-	TIM14_C H1	-	ETH_MII_RX_DV/ETH_RMII_CRS_DV	FMC_SDNWE	-	-	EVEN TOUT
	PA8	MCO1	TIM1_C H1	-	TIM8_BKIN2	I2C3_SCL	-	-	USART1_CK	-	-	OTG_FS_SOF	-	-	-	LCD_R6	EVEN TOUT	
	PA9	-	TIM1_C H2	-	-	I2C3_SMBA	SPI2_SCK/I2S2_CK	-	USART1_TX	-	-	-	-	-	DCMI_D0	-	EVEN TOUT	
	PA10	-	TIM1_C H3	-	-	-	-	-	USART1_RX	-	-	OTG_FS_ID	-	-	DCMI_D1	-	EVEN TOUT	
	PA11	-	TIM1_C H4	-	-	-	-	-	USART1_CTS	-	CAN1_RX	OTG_FS_DM	-	-	-	LCD_R4	EVEN TOUT	
PA12	-	TIM1_ETR	-	-	-	-	-	USART1_RTS	SAI2_FS_B	CAN1_TX	OTG_FS_DP	-	-	-	LCD_R5	EVEN TOUT		



Table 12. STM32F756xx alternate function mapping (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15		
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS		
Port A	PA13	JTMS- SWDIO	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT	
	PA14	JTCK- SWCLK	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT	
	PA15	JTDI	TIM2_C H1/TIM2 _ETR	-	-	HDMI- CEC	SPI1_NS S/I2S1_ WS	SPI3_NS S/I2S3_ WS	-	UART4_ RTS	-	-	-	-	-	-	-	EVEN TOUT	
Port B	PB0	-	TIM1_C H2N	TIM3_C H3	TIM8_CH 2N	-	-	-	-	UART4_ CTS	LCD_R3	OTG_HS_ ULPI_D1	ETH_MII_ RXD2	-	-	-	-	EVEN TOUT	
	PB1	-	TIM1_C H3N	TIM3_C H4	TIM8_CH 3N	-	-	-	-	-	LCD_R6	OTG_HS_ ULPI_D2	ETH_MII_ RXD3	-	-	-	-	EVEN TOUT	
	PB2	-	-	-	-	-	-	SAI1_SD _A	SPI3_MO S/I2S3_ SD	-	QUADSP I_CLK	-	-	-	-	-	-	EVEN TOUT	
	PB3	JTDO/T RACES WO	TIM2_C H2	-	-	-	SPI1_SC K/I2S1_ CK	SPI3_SC K/I2S3_ CK	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PB4	NJTRST	-	TIM3_C H1	-	-	SPI1_MI SO	SPI3_MI SO	SPI2_NS S/I2S2_ WS	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PB5	-	-	TIM3_C H2	-	I2C1_SM BA	SPI1_M OSI/I2S1_ _SD	SPI3_M OSI/I2S3_ _SD	-	-	CAN2_R X	OTG_HS_ ULPI_D7	ETH_PPS_ _OUT	FMC_SD CKE1	DCMI_D 10	-	-	-	EVEN TOUT
	PB6	-	-	TIM4_C H1	HDMI- CEC	I2C1_SC L	-	-	USART1 _TX	-	CAN2_T X	QUADSPI _BK1_NC S	-	FMC_SD NE1	DCMI_D 5	-	-	-	EVEN TOUT
	PB7	-	-	TIM4_C H2	-	I2C1_SD A	-	-	USART1 _RX	-	-	-	-	FMC_NL	DCMI_V SYNC	-	-	-	EVEN TOUT
	PB8	-	-	TIM4_C H3	TIM10_C H1	I2C1_SC L	-	-	-	-	CAN1_R X	-	ETH_MII_ TXD3	SDMMC _D4	DCMI_D 6	LCD_B6	-	-	EVEN TOUT
	PB9	-	-	TIM4_C H4	TIM11_CH 1	I2C1_SD A	SPI2_NS S/I2S2_ WS	-	-	-	CAN1_T X	-	-	SDMMC _D5	DCMI_D 7	LCD_B7	-	-	EVEN TOUT



**Table 12. STM32F756xx alternate function mapping (continued)**

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS
Port B	PB10	-	TIM2_C H3	-	-	I2C2_SC L	SPI2_SC K/I2S2_ CK	-	USART3 _TX	-	-	OTG_HS_ ULPI_D3	ETH_MII_ RX_ER	-	-	LCD_G4	EVEN TOUT
	PB11	-	TIM2_C H4	-	-	I2C2_SD A	-	-	USART3 _RX	-	-	OTG_HS_ ULPI_D4	ETH_MII_ TX_EN/E TH_RMII_ TX_EN	-	-	LCD_G5	EVEN TOUT
	PB12	-	TIM1_B KIN	-	-	I2C2_SM BA	SPI2_NS S/I2S2_ WS	-	USART3 _CK	-	CAN2_R X	OTG_HS_ ULPI_D5	ETH_MII_ TXD0/E H_RMII_T XD0	OTG_HS _ID	-	-	EVEN TOUT
	PB13	-	TIM1_C H1N	-	-	-	SPI2_SC K/I2S2_ CK	-	USART3 _CTS	-	CAN2_T X	OTG_HS_ ULPI_D6	ETH_MII_ TXD1/E H_RMII_T XD1	-	-	-	EVEN TOUT
	PB14	-	TIM1_C H2N	-	TIM8_CH 2N	-	SPI2_MI SO	-	USART3 _RTS	-	TIM12_C H1	-	-	OTG_HS _DM	-	-	EVEN TOUT
	PB15	RTC_RE FIN	TIM1_C H3N	-	TIM8_CH 3N	-	SPI2_M OSI/I2S2 _SD	-	-	-	TIM12_C H2	-	-	OTG_HS _DP	-	-	EVEN TOUT
Port C	PC0	-	-	-	-	-	-	-	-	SAI2_FS _B	-	OTG_HS_ ULPI_ST P	-	FMC_SD NWE	-	LCD_R5	EVEN TOUT
	PC1	TRACED 0	-	-	-	-	SPI2_M OSI/I2S2 _SD	SAI1_SD _A	-	-	-	-	ETH_MD C	-	-	-	EVEN TOUT
	PC2	-	-	-	-	-	SPI2_MI SO	-	-	-	-	OTG_HS_ ULPI_DIR	ETH_MII_ TXD2	FMC_SD NE0	-	-	EVEN TOUT
	PC3	-	-	-	-	-	SPI2_M OSI/I2S2 _SD	-	-	-	-	OTG_HS_ ULPI_NX T	ETH_MII_ TX_CLK	FMC_SD CKE0	-	-	EVEN TOUT
	PC4	-	-	-	-	-	I2S1_M CK	-	-	SPDIF_R X2	-	-	ETH_MII_ RXD0/E H_RMII_ RXD0	FMC_SD NE0	-	-	EVEN TOUT



Table 12. STM32F756xx alternate function mapping (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15	
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS	
Port C	PC5	-	-	-	-	-	-	-	-	SPDIF_R X3	-	-	ETH_MII RXD1/ET H_RMII_ RXD1	FMC_SD CKE0	-	-	EVEN TOUT	
	PC6	-	-	TIM3_C H1	TIM8_CH 1	-	I2S2_M CK	-	-	USART6 _TX	-	-	-	SDMMC _D6	DCMI_D 0	LCD_HS YNC	EVEN TOUT	
	PC7	-	-	TIM3_C H2	TIM8_ CH2	-	-	I2S3_M CK	-	USART6 _RX	-	-	-	SDMMC _D7	DCMI_D 1	LCD_G6	EVEN TOUT	
	PC8	TRACED 1	-	TIM3_C H3	TIM8_ CH3	-	-	-	UART5_ RTS	USART6 _CK	-	-	-	SDMMC _D0	DCMI_D 2	-	EVEN TOUT	
	PC9	MCO2	-	TIM3_C H4	TIM8_ CH4	I2C3_SD A	I2S_CK1 N	-	UART5_ CTS	-	QUADSP I_BK1_IO 0	-	-	SDMMC _D1	DCMI_D 3	-	EVEN TOUT	
	PC10	-	-	-	-	-	-	SPI3_SC K/I2S3_ CK	USART3 _TX	UART4_T X	QUADSP I_BK1_IO 1	-	-	SDMMC _D2	DCMI_D 8	LCD_R2	EVEN TOUT	
	PC11	-	-	-	-	-	-	SPI3_MI S0	USART3 _RX	UART4_ RX	QUADSP I_BK2_N CS	-	-	SDMMC _D3	DCMI_D 4	-	EVEN TOUT	
	PC12	TRACED 3	-	-	-	-	-	SPI3_M OS/I2S3 _SD	USART3 _CK	UART5_T X	-	-	-	SDMMC _CK	DCMI_D 9	-	EVEN TOUT	
	PC13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PC14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
PC15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT	
Port D	PD0	-	-	-	-	-	-	-	-	-	CAN1_R X	-	-	FMC_D2	-	-	EVEN TOUT	
	PD1	-	-	-	-	-	-	-	-	-	CAN1_T X	-	-	FMC_D3	-	-	EVEN TOUT	
	PD2	TRACED 2	-	TIM3_ET R	-	-	-	-	-	UART5_ RX	-	-	-	SDMMC _CMD	DCMI_D 11	-	EVEN TOUT	



**Table 12. STM32F756xx alternate function mapping (continued)**

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS
Port D	PD3	-	-	-	-	-	SPI2_SC K/I2S2_ CK	-	USART2 _CTS	-	-	-	-	FMC_CL K	DCMI_D 5	LCD_G7	EVEN TOUT
	PD4	-	-	-	-	-	-	-	USART2 _RTS	-	-	-	-	FMC_N OE	-	-	EVEN TOUT
	PD5	-	-	-	-	-	-	-	USART2 _TX	-	-	-	-	FMC_N WE	-	-	EVEN TOUT
	PD6	-	-	-	-	-	SPI3_M OSI/I2S3 _SD	SAI1_SD _A	USART2 _RX	-	-	-	-	FMC_N WAIT	DCMI_D 10	LCD_B2	EVEN TOUT
	PD7	-	-	-	-	-	-	-	USART2 _CK	SPDIF_R X0	-	-	-	FMC_NE 1	-	-	EVEN TOUT
	PD8	-	-	-	-	-	-	-	USART3 _TX	SPDIF_R X1	-	-	-	FMC_D1 3	-	-	EVEN TOUT
	PD9	-	-	-	-	-	-	-	USART3 _RX	-	-	-	-	FMC_D1 4	-	-	EVEN TOUT
	PD10	-	-	-	-	-	-	-	USART3 _CK	-	-	-	-	FMC_D1 5	-	LCD_B3	EVEN TOUT
	PD11	-	-	-	-	I2C4_SM BA	-	-	USART3 _CTS	-	QUADSP I_BK1_IO 0	SAI2_SD_ A	-	FMC_A1 6/FMC_ CLE	-	-	EVEN TOUT
	PD12	-	-	TIM4_C H1	LPTIM1_I N1	I2C4_SC L	-	-	USART3 _RTS	-	QUADSP I_BK1_IO 1	SAI2_FS_ A	-	FMC_A1 7/FMC_ ALE	-	-	EVEN TOUT
	PD13	-	-	TIM4_C H2	LPTIM1_ OUT	I2C4_SD A	-	-	-	-	QUADSP I_BK1_IO 3	SAI2_SC K_A	-	FMC_A1 8	-	-	EVEN TOUT
	PD14	-	-	TIM4_C H3	-	-	-	-	-	UART8_ CTS	-	-	-	FMC_D0	-	-	EVEN TOUT
	PD15	-	-	TIM4_C H4	-	-	-	-	-	UART8_ RTS	-	-	-	FMC_D1	-	-	EVEN TOUT
	Port E	PE0	-	-	TIM4_ET R	LPTIM1_E TR	-	-	-	-	UART8_ Rx	-	SAI2_MC K_A	-	FMC_NB L0	DCMI_D 2	-



Table 12. STM32F756xx alternate function mapping (continued)

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15	
	SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS	
Port E	PE1	-	-	-	LPTIM1_J N2	-	-	-	-	UART8_T x	-	-	-	FMC_NB L1	DCMI_D 3	-	EVEN TOUT
	PE2	TRACEC LK	-	-	-	-	SPI4_SC K	SAI1_M CLK_A	-	-	QUADSP I_BK1_IO 2	-	ETH_MII_ TXD3	FMC_A2 3	-	-	EVEN TOUT
	PE3	TRACED 0	-	-	-	-	-	SAI1_SD _B	-	-	-	-	-	FMC_A1 9	-	-	EVEN TOUT
	PE4	TRACED 1	-	-	-	-	SPI4_NS S	SAI1_FS _A	-	-	-	-	-	FMC_A2 0	DCMI_D 4	LCD_B0	EVEN TOUT
	PE5	TRACED 2	-	-	TIM9_CH 1	-	SPI4_MI SO	SAI1_SC K_A	-	-	-	-	-	FMC_A2 1	DCMI_D 6	LCD_G0	EVEN TOUT
	PE6	TRACED 3	TIM1_B KIN2	-	TIM9_CH 2	-	SPI4_M OSI	SAI1_SD _A	-	-	-	SAI2_MC K_B	-	FMC_A2 2	DCMI_D 7	LCD_G1	EVEN TOUT
	PE7	-	TIM1_ET R	-	-	-	-	-	-	UART7_ Rx	-	QUADSPI _BK2_IO0	-	FMC_D4	-	-	EVEN TOUT
	PE8	-	TIM1_C H1N	-	-	-	-	-	-	UART7_T x	-	QUADSPI _BK2_IO1	-	FMC_D5	-	-	EVEN TOUT
	PE9	-	TIM1_C H1	-	-	-	-	-	-	UART7_ RTS	-	QUADSPI _BK2_IO2	-	FMC_D6	-	-	EVEN TOUT
	PE10	-	TIM1_C H2N	-	-	-	-	-	-	UART7_ CTS	-	QUADSPI _BK2_IO3	-	FMC_D7	-	-	EVEN TOUT
	PE11	-	TIM1_C H2	-	-	-	SPI4_NS S	-	-	-	-	SAI2_SD_ B	-	FMC_D8	-	LCD_G3	EVEN TOUT
	PE12	-	TIM1_C H3N	-	-	-	SPI4_SC K	-	-	-	-	SAI2_SC K_B	-	FMC_D9	-	LCD_B4	EVEN TOUT
	PE13	-	TIM1_C H3	-	-	-	SPI4_MI SO	-	-	-	-	SAI2_FS_ B	-	FMC_D1 0	-	LCD_DE	EVEN TOUT
	PE14	-	TIM1_C H4	-	-	-	SPI4_M OSI	-	-	-	-	SAI2_MC K_B	-	FMC_D1 1	-	LCD_CL K	EVEN TOUT
	PE15	-	TIM1_B KIN	-	-	-	-	-	-	-	-	-	-	FMC_D1 2	-	LCD_R7	EVEN TOUT



**Table 12. STM32F756xx alternate function mapping (continued)**

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15	
	SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C2_1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS	
Port F	PF0	-	-	-	-	I2C2_SD A	-	-	-	-	-	-	FMC_A0	-	-	EVEN TOUT	
	PF1	-	-	-	-	I2C2_SC L	-	-	-	-	-	-	FMC_A1	-	-	EVEN TOUT	
	PF2	-	-	-	-	I2C2_SM BA	-	-	-	-	-	-	FMC_A2	-	-	EVEN TOUT	
	PF3	-	-	-	-	-	-	-	-	-	-	-	FMC_A3	-	-	EVEN TOUT	
	PF4	-	-	-	-	-	-	-	-	-	-	-	FMC_A4	-	-	EVEN TOUT	
	PF5	-	-	-	-	-	-	-	-	-	-	-	FMC_A5	-	-	EVEN TOUT	
	PF6	-	-	-	TIM10_C H1	-	SPI5_NS S	SAI1_SD _B	-	UART7_ Rx	QUADSP I_BK1_IO 3	-	-	-	-	-	EVEN TOUT
	PF7	-	-	-	TIM11_CH 1	-	SPI5_SC K	SAI1_M CLK_B	-	UART7_T x	QUADSP I_BK1_IO 2	-	-	-	-	-	EVEN TOUT
	PF8	-	-	-	-	-	SPI5_MI SO	SAI1_SC K_B	-	UART7_ RTS	TIM13_C H1	QUADSPI _BK1_IO0	-	-	-	-	EVEN TOUT
	PF9	-	-	-	-	-	SPI5_M OSI	SAI1_FS _B	-	UART7_ CTS	TIM14_C H1	QUADSPI _BK1_IO1	-	-	-	-	EVEN TOUT
	PF10	-	-	-	-	-	-	-	-	-	-	-	-	DCMI_D 11	LCD_DE	-	EVEN TOUT
	PF11	-	-	-	-	-	SPI5_M OSI	-	-	-	-	SAI2_SD_ B	-	FMC_SD NRAS	DCMI_D 12	-	EVEN TOUT
	PF12	-	-	-	-	-	-	-	-	-	-	-	-	FMC_A6	-	-	EVEN TOUT
	PF13	-	-	-	-	I2C4_SM BA	-	-	-	-	-	-	-	FMC_A7	-	-	EVEN TOUT
	PF14	-	-	-	-	I2C4_SC L	-	-	-	-	-	-	-	FMC_A8	-	-	EVEN TOUT
PF15	-	-	-	-	I2C4_SD A	-	-	-	-	-	-	-	FMC_A9	-	-	EVEN TOUT	



Table 12. STM32F756xx alternate function mapping (continued)

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15	
	SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/J SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS	
Port G	PG0	-	-	-	-	-	-	-	-	-	-	-	FMC_A1 0	-	-	EVEN TOUT	
	PG1	-	-	-	-	-	-	-	-	-	-	-	FMC_A1 1	-	-	EVEN TOUT	
	PG2	-	-	-	-	-	-	-	-	-	-	-	FMC_A1 2	-	-	EVEN TOUT	
	PG3	-	-	-	-	-	-	-	-	-	-	-	FMC_A1 3	-	-	EVEN TOUT	
	PG4	-	-	-	-	-	-	-	-	-	-	-	FMC_A1 4/FMC_ BA0	-	-	EVEN TOUT	
	PG5	-	-	-	-	-	-	-	-	-	-	-	FMC_A1 5/FMC_ BA1	-	-	EVEN TOUT	
	PG6	-	-	-	-	-	-	-	-	-	-	-	-	DCMI_D 12	LCD_R7	EVEN TOUT	
	PG7	-	-	-	-	-	-	-	-	USART6 _CK	-	-	-	FMC_IN T	DCMI_D 13	LCD_CL K	EVEN TOUT
	PG8	-	-	-	-	-	SPI6_NS S	-	SPDIF_R X2	USART6 _RTS	-	-	ETH_PPS _OUT	FMC_SD CLK	-	-	EVEN TOUT
	PG9	-	-	-	-	-	-	-	SPDIF_R X3	USART6 _RX	QUADSP I_BK2_IO 2	SAI2_FS_ B	-	FMC_NE 2/FMC_ NCE	DCMI_V SYNC	-	EVEN TOUT
	PG10	-	-	-	-	-	-	-	-	-	LCD_G3	SAI2_SD_ B	-	FMC_NE 3	DCMI_D 2	LCD_B2	EVEN TOUT
	PG11	-	-	-	-	-	-	-	SPDIF_R X0	-	-	-	ETH_MII TX_EN/E TH_RMII_ TX_EN	-	DCMI_D 3	LCD_B3	EVEN TOUT
	PG12	-	-	-	LPTIM1_I N1	-	SPI6_MI SO	-	SPDIF_R X1	USART6 _RTS	LCD_B4	-	-	FMC_NE 4	-	LCD_B1	EVEN TOUT
PG13	TRACED 0	-	-	LPTIM1_ OUT	-	SPI6_SC K	-	-	USART6 _CTS	-	-	-	ETH_MII_ TXD0/ET H_RMII_T XD0	FMC_A2 4	-	LCD_R0	EVEN TOUT



**Table 12. STM32F756xx alternate function mapping (continued)**

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS
Port G	PG14	TRACED 1	-	-	LPTIM1_E TR	-	SPI6_M OSI	-	-	USART6 _TX	QUADSP I_BK2_IO 3	-	ETH_MII_ TXD1/ET H_RMII_T XD1	FMC_A2 5	-	LCD_B0	EVEN TOUT
	PG15	-	-	-	-	-	-	-	-	USART6 _CTS	-	-	-	FMC_SD NCAS	DCMI_D 13	-	EVEN TOUT
Port H	PH0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PH1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PH2	-	-	-	LPTIM1_I N2	-	-	-	-	-	QUADSP I_BK2_IO 0	SAI2_SC K_B	ETH_MII_ CRS	FMC_SD CKE0	-	LCD_R0	EVEN TOUT
	PH3	-	-	-	-	-	-	-	-	-	QUADSP I_BK2_IO 1	SAI2_MC K_B	ETH_MII_ COL	FMC_SD NE0	-	LCD_R1	EVEN TOUT
	PH4	-	-	-	-	I2C2_SC L	-	-	-	-	-	OTG_HS_ ULPI_NX T	-	-	-	-	EVEN TOUT
	PH5	-	-	-	-	I2C2_SD A	SPI5_NS S	-	-	-	-	-	-	FMC_SD NWE	-	-	EVEN TOUT
	PH6	-	-	-	-	I2C2_SM BA	SPI5_SC K	-	-	-	TIM12_C H1	-	ETH_MII_ RXD2	FMC_SD NE1	DCMI_D 8	-	EVEN TOUT
	PH7	-	-	-	-	I2C3_SC L	SPI5_MI SO	-	-	-	-	-	ETH_MII_ RXD3	FMC_SD CKE1	DCMI_D 9	-	EVEN TOUT
	PH8	-	-	-	-	I2C3_SD A	-	-	-	-	-	-	-	FMC_D1 6	DCMI_H SYNC	LCD_R2	EVEN TOUT
	PH9	-	-	-	-	I2C3_SM BA	-	-	-	-	TIM12_C H2	-	-	FMC_D1 7	DCMI_D 0	LCD_R3	EVEN TOUT
	PH10	-	-	TIM5_C H1	-	I2C4_SM BA	-	-	-	-	-	-	-	FMC_D1 8	DCMI_D 1	LCD_R4	EVEN TOUT
	PH11	-	-	TIM5_C H2	-	I2C4_SC L	-	-	-	-	-	-	-	FMC_D1 9	DCMI_D 2	LCD_R5	EVEN TOUT
PH12	-	-	TIM5_C H3	-	I2C4_SD A	-	-	-	-	-	-	-	FMC_D2 0	DCMI_D 3	LCD_R6	EVEN TOUT	



Table 12. STM32F756xx alternate function mapping (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15		
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS		
Port H	PH13	-	-	-	TIM8_CH 1N	-	-	-	-	-	-	CAN1_T X	-	-	FMC_D2 1	-	LCD_G2	EVEN TOUT	
	PH14	-	-	-	TIM8_CH 2N	-	-	-	-	-	-	-	-	-	FMC_D2 2	DCMI_D 4	LCD_G3	EVEN TOUT	
	PH15	-	-	-	TIM8_CH 3N	-	-	-	-	-	-	-	-	-	FMC_D2 3	DCMI_D 11	LCD_G4	EVEN TOUT	
Port I	PI0	-	-	TIM5_C H4	-	-	SPI2_NS S/12S2_ WS	-	-	-	-	-	-	-	FMC_D2 4	DCMI_D 13	LCD_G5	EVEN TOUT	
	PI1	-	-	-	TIM8_BK1 N2	-	SPI2_SC K/12S2_ CK	-	-	-	-	-	-	-	FMC_D2 5	DCMI_D 8	LCD_G6	EVEN TOUT	
	PI2	-	-	-	TIM8_CH 4	-	SPI2_MI SO	-	-	-	-	-	-	-	FMC_D2 6	DCMI_D 9	LCD_G7	EVEN TOUT	
	PI3	-	-	-	TIM8_ET R	-	SPI2_M OSI/12S2_ SD	-	-	-	-	-	-	-	FMC_D2 7	DCMI_D 10	-	EVEN TOUT	
	PI4	-	-	-	TIM8_BK1 N	-	-	-	-	-	-	-	-	-	FMC_NB L2	DCMI_D 5	LCD_B4	EVEN TOUT	
	PI5	-	-	-	TIM8_CH 1	-	-	-	-	-	-	-	-	-	FMC_NB L3	DCMI_V SYNC	LCD_B5	EVEN TOUT	
	PI6	-	-	-	TIM8_CH 2	-	-	-	-	-	-	-	-	-	FMC_D2 8	DCMI_D 6	LCD_B6	EVEN TOUT	
	PI7	-	-	-	TIM8_CH 3	-	-	-	-	-	-	-	-	-	FMC_D2 9	DCMI_D 7	LCD_B7	EVEN TOUT	
	PI8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PI9	-	-	-	-	-	-	-	-	-	-	-	CAN1_R X	-	-	FMC_D3 0	-	LCD_VS YNC	EVEN TOUT
	PI10	-	-	-	-	-	-	-	-	-	-	-	-	ETH_MII_ RX_ER	FMC_D3 1	-	LCD_HS YNC	EVEN TOUT	
	PI11	-	-	-	-	-	-	-	-	-	-	-	-	OTG_HS_ ULPI_DIR	-	-	-	-	EVEN TOUT



**Table 12. STM32F756xx alternate function mapping (continued)**

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/J SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS
Port I	PI12	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_HS YNC	EVEN TOUT
	PI13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_VS YNC	EVEN TOUT
	PI14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_CL K	EVEN TOUT
	PI15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R0	EVEN TOUT
Port J	PJ0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R1	EVEN TOUT
	PJ1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R2	EVEN TOUT
	PJ2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R3	EVEN TOUT
	PJ3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R4	EVEN TOUT
	PJ4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R5	EVEN TOUT
	PJ5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R6	EVEN TOUT
	PJ6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R7	EVEN TOUT
	PJ7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G0	EVEN TOUT
	PJ8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G1	EVEN TOUT
	PJ9	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G2	EVEN TOUT
	PJ10	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G3	EVEN TOUT
PJ11	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G4	EVEN TOUT	



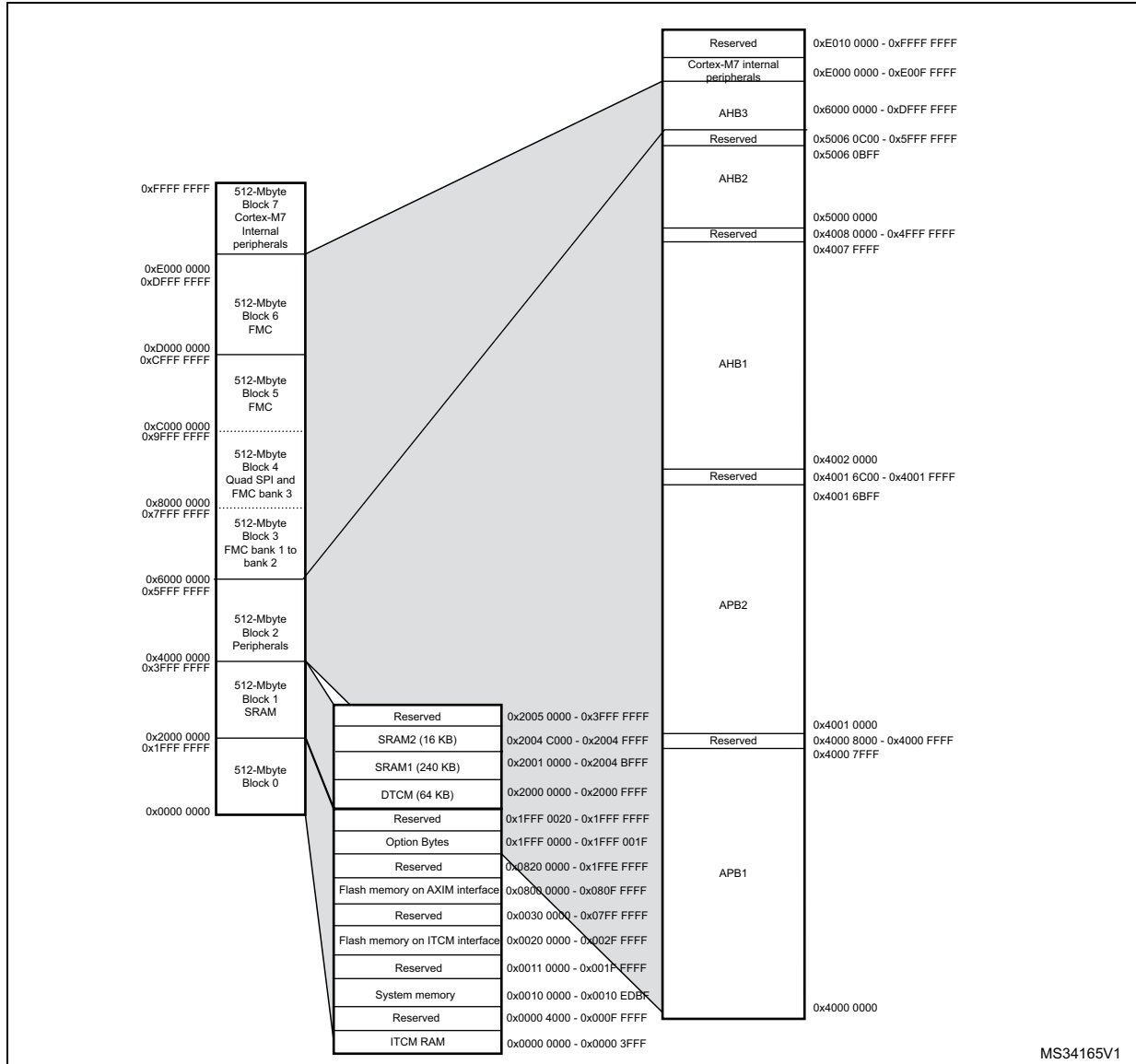
Table 12. STM32F756xx alternate function mapping (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/J SART1/2/ 3/UART5/ SPDIF	SAI2/US ART6/UA RT4/5/7/8 /SPDIF	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC/OT G2_FS	DCMI	LCD	SYS
Port J	PJ12	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B0	EVEN TOUT
	PJ13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B1	EVEN TOUT
	PJ14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B2	EVEN TOUT
	PJ15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B3	EVEN TOUT
Port K	PK0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G5	EVEN TOUT
	PK1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G6	EVEN TOUT
	PK2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_G7	EVEN TOUT
	PK3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B4	EVEN TOUT
	PK4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B5	EVEN TOUT
	PK5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B6	EVEN TOUT
	PK6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B7	EVEN TOUT
	PK7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_DE	EVEN TOUT

# 4 Memory mapping

The memory map is shown in *Figure 16*.

**Figure 16. Memory map**



MS34165V1

Table 13. STM32F756xx register boundary addresses

Bus	Boundary address	Peripheral
	0xE00F FFFF - 0xFFFF FFFF	Reserved
Cortex-M7	0xE000 0000 - 0xE00F FFFF	Cortex-M7 internal peripherals
AHB3	0xD000 0000 - 0xDFFF FFFF	FMC bank 6
	0xC000 0000 - 0xCFFF FFFF	FMC bank 5
	0xA000 2000 - 0xBFFF FFFF	Reserved
	0xA000 1000 - 0xA000 1FFF	Quad SPI control register
	0xA000 0000 - 0xA000 0FFF	FMC control register
	0x9000 0000 - 0x9FFF FFFF	Quad SPI
	0x8000 0000 - 0x8FFF FFFF	FMC bank 3
	0x7000 0000 - 0x7FFF FFFF	FMC bank 2
	0x6000 0000 - 0x6FFF FFFF	FMC bank 1
	0x5006 0C00 - 0x5FFF FFFF	Reserved
AHB2	0x5006 0800 - 0x5006 0BFF	RNG
	0x5006 0400 - 0x5006 07FF	HASH
	0x5006 0000 - 0x5006 03FF	CRYP
	0x5005 0400 - 0x5006 07FF	Reserved
	0x5005 0000 - 0x5005 03FF	DCMI
	0x5004 0000 - 0x5004 FFFF	Reserved
	0x5000 0000 - 0x5003 FFFF	USB OTG FS

**Table 13. STM32F756xx register boundary addresses (continued)**

Bus	Boundary address	Peripheral
	0x4008 0000 - 0x4FFF FFFF	Reserved
AHB1	0x4004 0000 - 0x4007 FFFF	USB OTG HS
	0x4002 BC00 - 0x4003 FFFF	Reserved
	0x4002 B000 - 0x4002 BBFF	Chrom-ART (DMA2D)
	0x4002 9400 - 0x4002 AFFF	Reserved
	0x4002 9000 - 0x4002 93FF	ETHERNET MAC
	0x4002 8C00 - 0x4002 8FFF	
	0x4002 8800 - 0x4002 8BFF	
	0x4002 8400 - 0x4002 87FF	
	0x4002 8000 - 0x4002 83FF	
	0x4002 6800 - 0x4002 7FFF	Reserved
	0x4002 6400 - 0x4002 67FF	DMA2
	0x4002 6000 - 0x4002 63FF	DMA1
	0x4002 5000 - 0x4002 5FFF	Reserved
	0x4002 4000 - 0x4002 4FFF	BKPSRAM
	0x4002 3C00 - 0x4002 3FFF	Flash interface register
	0x4002 3800 - 0x4002 3BFF	RCC
	0x4002 3400 - 0x4002 37FF	Reserved
	0x4002 3000 - 0x4002 33FF	CRC
	0x4002 2C00 - 0x4002 2FFF	Reserved
	0x4002 2800 - 0x4002 2BFF	GPIOK
	0x4002 2400 - 0x4002 27FF	GPIOJ
	0x4002 2000 - 0x4002 23FF	GPIOI
	0x4002 1C00 - 0x4002 1FFF	GPIOH
	0x4002 1800 - 0x4002 1BFF	GPIOG
	0x4002 1400 - 0x4002 17FF	GPIOF
	0x4002 1000 - 0x4002 13FF	GPIOE
	0x4002 0C00 - 0x4002 0FFF	GPIOD
	0x4002 0800 - 0x4002 0BFF	GPIOC
	0x4002 0400 - 0x4002 07FF	GPIOB
	0x4002 0000 - 0x4002 03FF	GPIOA

Table 13. STM32F756xx register boundary addresses (continued)

Bus	Boundary address	Peripheral
	0x4001 6C00- 0x4001 FFFF	Reserved
APB2	0x4001 6800 - 0x4001 6BFF	LCD-TFT
	0x4001 6000 - 0x4001 67FF	Reserved
	0x4001 5C00 - 0x4001 5FFF	SAI2
	0x4001 5800 - 0x4001 5BFF	SAI1
	0x4001 5400 - 0x4001 57FF	SPI6
	0x4001 5000 - 0x4001 53FF	SPI5
	0x4001 4C00 - 0x4001 4FFF	Reserved
	0x4001 4800 - 0x4001 4BFF	TIM11
	0x4001 4400 - 0x4001 47FF	TIM10
	0x4001 4000 - 0x4001 43FF	TIM9
	0x4001 3C00 - 0x4001 3FFF	EXTI
	0x4001 3800 - 0x4001 3BFF	SYSCFG
	0x4001 3400 - 0x4001 37FF	SPI4
	0x4001 3000 - 0x4001 33FF	SPI1/I2S1
	0x4001 2C00 - 0x4001 2FFF	SDMMC
	0x4001 2400 - 0x4001 2BFF	Reserved
	0x4001 2000 - 0x4001 23FF	ADC1 - ADC2 - ADC3
	0x4001 1800 - 0x4001 1FFF	Reserved
	0x4001 1400 - 0x4001 17FF	USART6
	0x4001 1000 - 0x4001 13FF	USART1
	0x4001 0800 - 0x4001 0FFF	Reserved
	0x4001 0400 - 0x4001 07FF	TIM8
0x4001 0000 - 0x4001 03FF	TIM1	

**Table 13. STM32F756xx register boundary addresses (continued)**

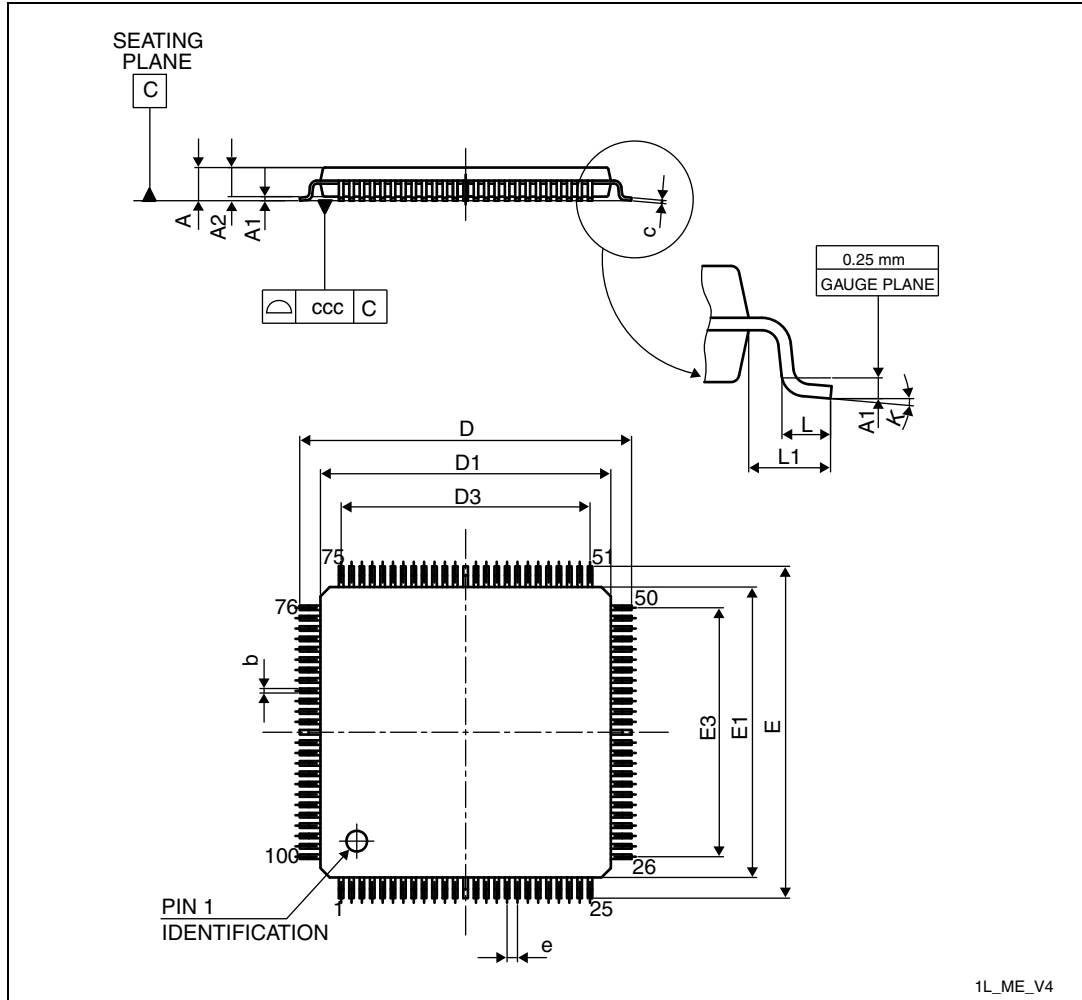
Bus	Boundary address	Peripheral
	0x4000 8000- 0x4000 FFFF	Reserved
APB1	0x4000 7C00 - 0x4000 7FFF	UART8
	0x4000 7800 - 0x4000 7BFF	UART7
	0x4000 7400 - 0x4000 77FF	DAC
	0x4000 7000 - 0x4000 73FF	PWR
	0x4000 6C00 - 0x4000 6FFF	HDMI-CEC
	0x4000 6800 - 0x4000 6BFF	CAN2
	0x4000 6400 - 0x4000 67FF	CAN1
	0x4000 6000 - 0x4000 63FF	I2C4
	0x4000 5C00 - 0x4000 5FFF	I2C3
	0x4000 5800 - 0x4000 5BFF	I2C2
	0x4000 5400 - 0x4000 57FF	I2C1
	0x4000 5000 - 0x4000 53FF	UART5
	0x4000 4C00 - 0x4000 4FFF	UART4
	0x4000 4800 - 0x4000 4BFF	USART3
	0x4000 4400 - 0x4000 47FF	USART2
	0x4000 4000 - 0x4000 43FF	SPDIF-RX
	0x4000 3C00 - 0x4000 3FFF	SPI3 / I2S3
	0x4000 3800 - 0x4000 3BFF	SPI2 / I2S2
	0x4000 3400 - 0x4000 37FF	Reserved
	0x4000 3000 - 0x4000 33FF	IWDG
	0x4000 2C00 - 0x4000 2FFF	WWDG
	0x4000 2800 - 0x4000 2BFF	RTC & BKP Registers
	0x4000 2400 - 0x4000 27FF	LPTIM1
	0x4000 2000 - 0x4000 23FF	TIM14
	0x4000 1C00 - 0x4000 1FFF	TIM13
	0x4000 1800 - 0x4000 1BFF	TIM12
	0x4000 1400 - 0x4000 17FF	TIM7
	0x4000 1000 - 0x4000 13FF	TIM6
	0x4000 0C00 - 0x4000 0FFF	TIM5
	0x4000 0800 - 0x4000 0BFF	TIM4
0x4000 0400 - 0x4000 07FF	TIM3	
0x4000 0000 - 0x4000 03FF	TIM2	

## 5 Package characteristics

### 5.1 Package mechanical data

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK® is an ST trademark.

Figure 17. LQFP100, 14 x 14 mm 100-pin low-profile quad flat package outline



1. Drawing is not to scale.

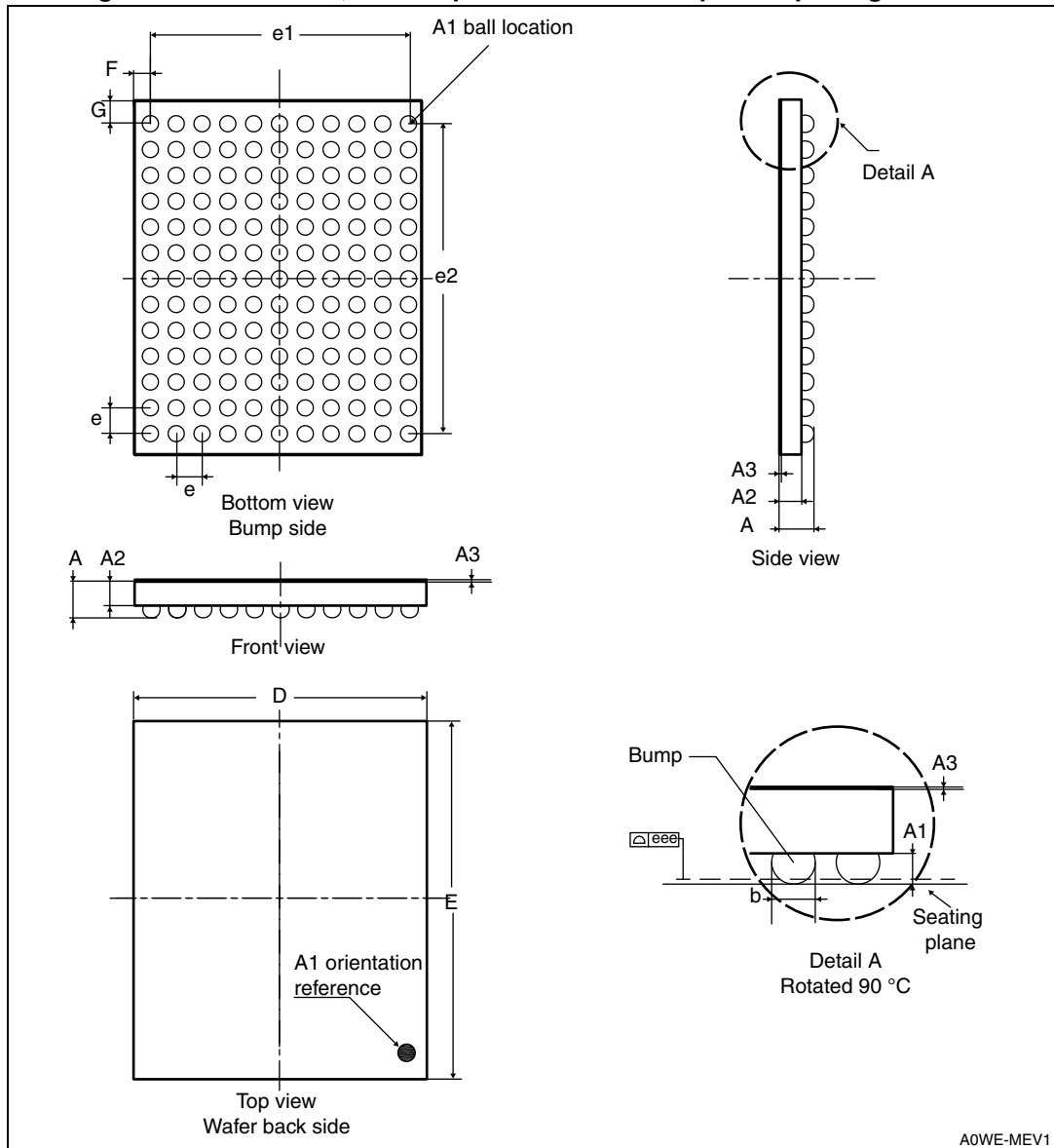
Table 14. LQPF100, 14 x 14 mm 100-pin low-profile quad flat package mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	15.800	16.000	16.200	0.6220	0.6299	0.6378
D1	13.800	14.000	14.200	0.5433	0.5512	0.5591
D3	-	12.000	-	-	0.4724	-
E	15.800	16.000	16.200	0.6220	0.6299	0.6378
E1	13.800	14.000	14.200	0.5433	0.5512	0.5591
E3	-	12.000	-	-	0.4724	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7°	0°	3.5°	7°
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.



Figure 20. WLCSP143, 0.4 mm pitch wafer level chip scale package outline



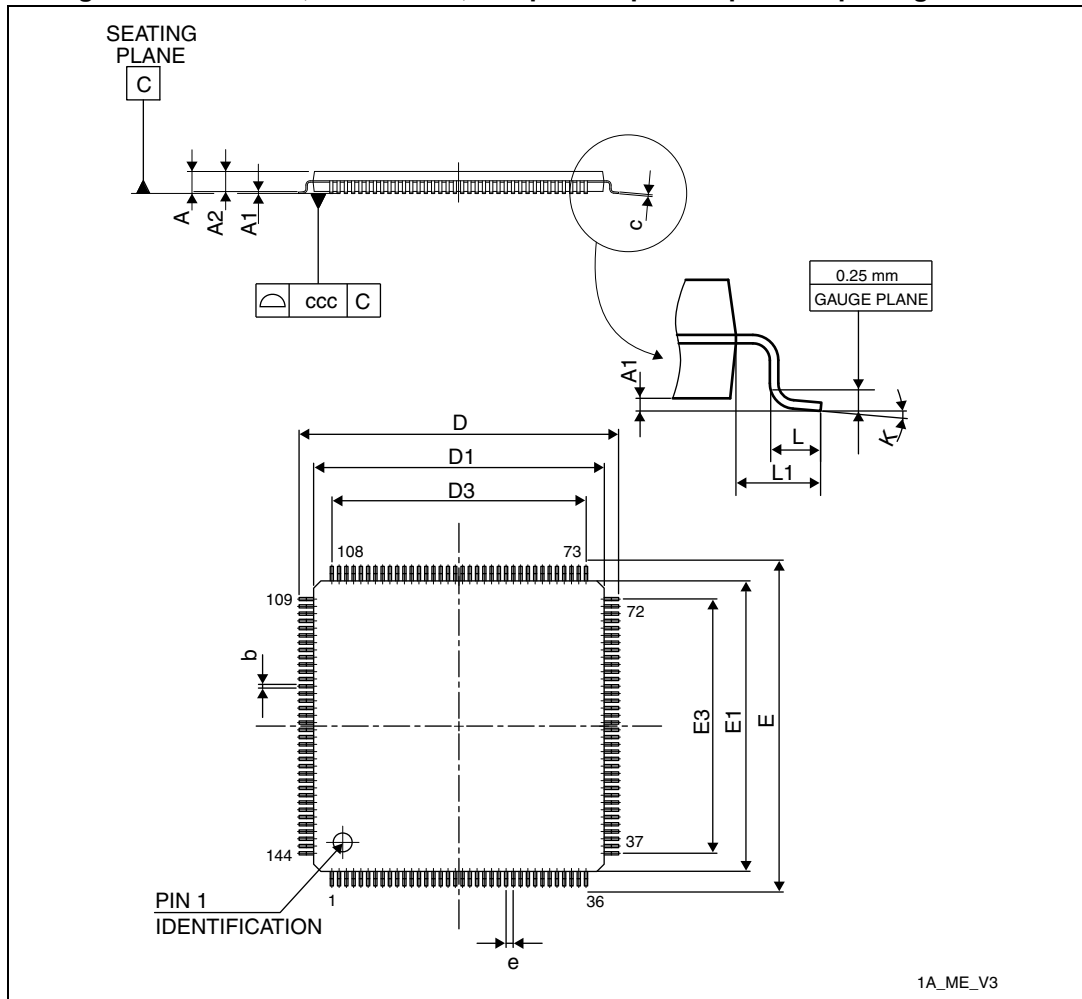
1. Drawing is not to scale.

Table 15. WLCSP143, 0.4 mm pitch wafer level chip scale package mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	0.525	0.555	0.585	0.0207	0.0219	0.0230
A1	-	0.175	-	-	0.0069	-
A2	-	0.380	-	-	0.0150	-
A3	0.220	0.025	0.280	0.0087	0.0010	0.0110
b	-	0.250°	-	-	0.250°	-
D	4.486	4.521	4.556	0.1766	0.1780	0.1794
E	5.512	5.547	5.582	0.2170	0.2184	0.2198
e	-	0.400	-	-	0.0157	-
e1	-	4.000	-	-	0.1575	-
e2	-	4.800	-	-	0.1890	-
F	-	0.261	-	-	0.0103	-
G	-	0.374	-	-	0.0147	-
eee	-	0.050	-	-	0.0020	-

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 21. LQFP144, 20 x 20 mm, 144-pin low-profile quad flat package outline



1. Drawing is not to scale.

Table 16. LQFP144, 20 x 20 mm, 144-pin low-profile quad flat package mechanical data

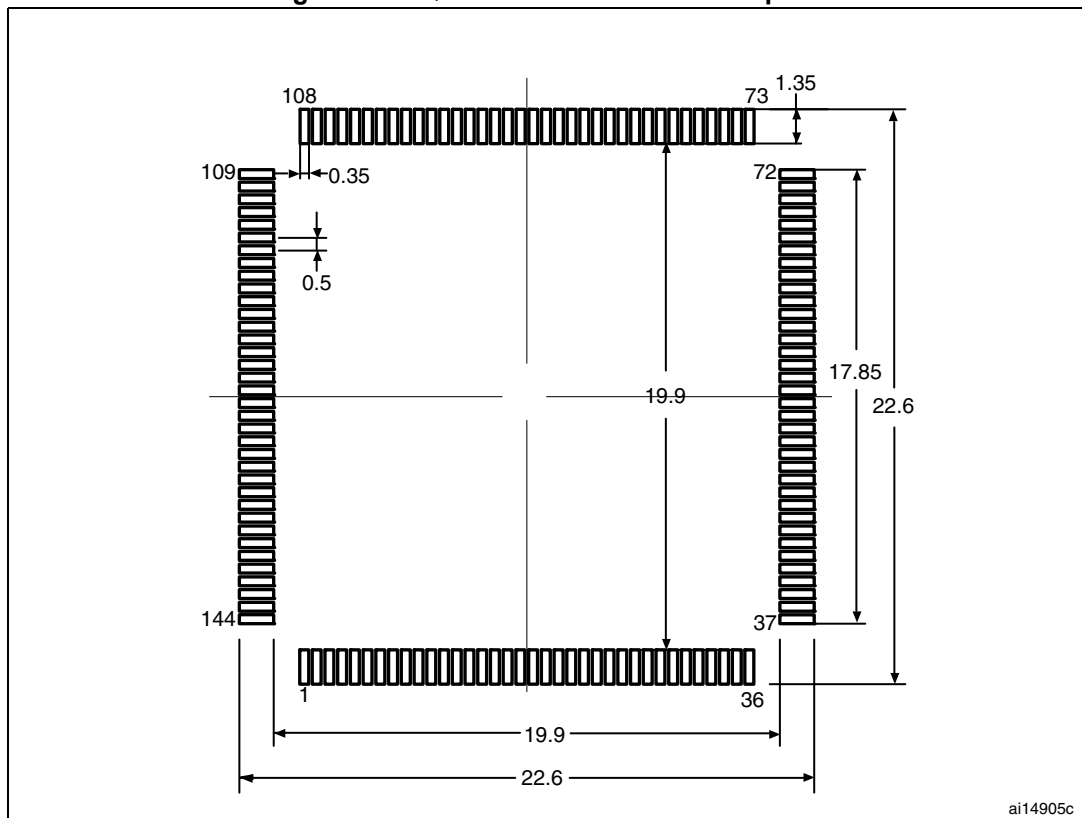
Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	21.800	22.000	22.200	0.8583	0.8661	0.874
D1	19.800	20.000	20.200	0.7795	0.7874	0.7953
D3	-	17.500	-	-	0.689	-
E	21.800	22.000	22.200	0.8583	0.8661	0.8740

Table 16. LQFP144, 20 x 20 mm, 144-pin low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
E1	19.800	20.000	20.200	0.7795	0.7874	0.7953
E3	-	17.500	-	-	0.6890	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7°	0°	3.5°	7°
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

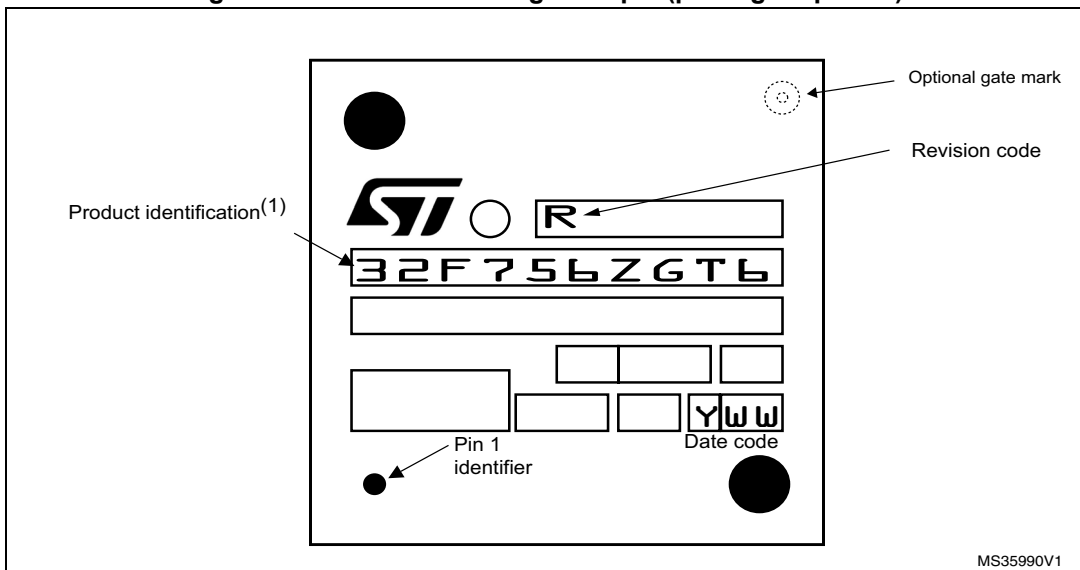
Figure 22. LQFP144 recommended footprint



1. Dimensions are expressed in millimeters.

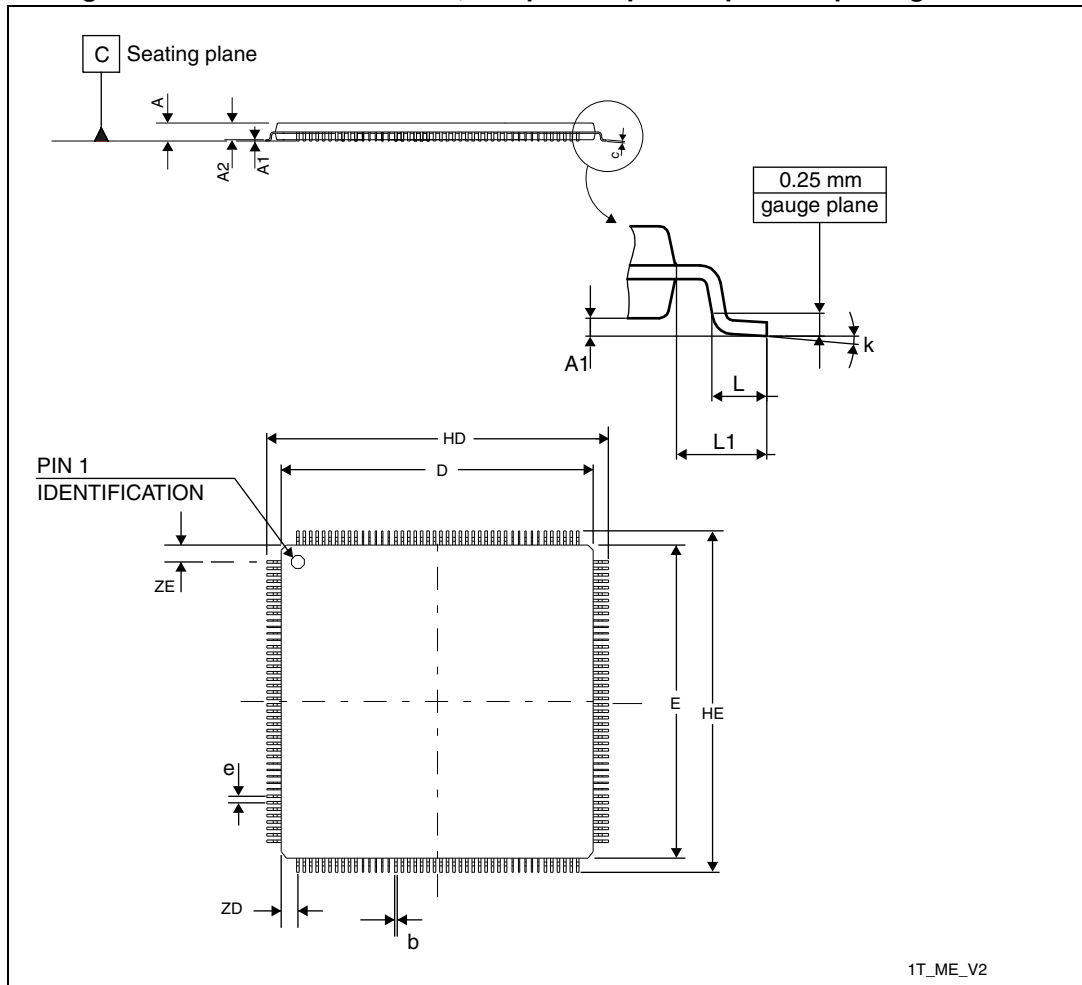
Device marking

Figure 23. LQFP144 marking example (package top view)



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

Figure 24. LQFP176 24 x 24 mm, 176-pin low-profile quad flat package outline



1. Drawing is not to scale.

Table 17. LQFP176, 24 x 24 mm, 176-pin low-profile quad flat package mechanical data

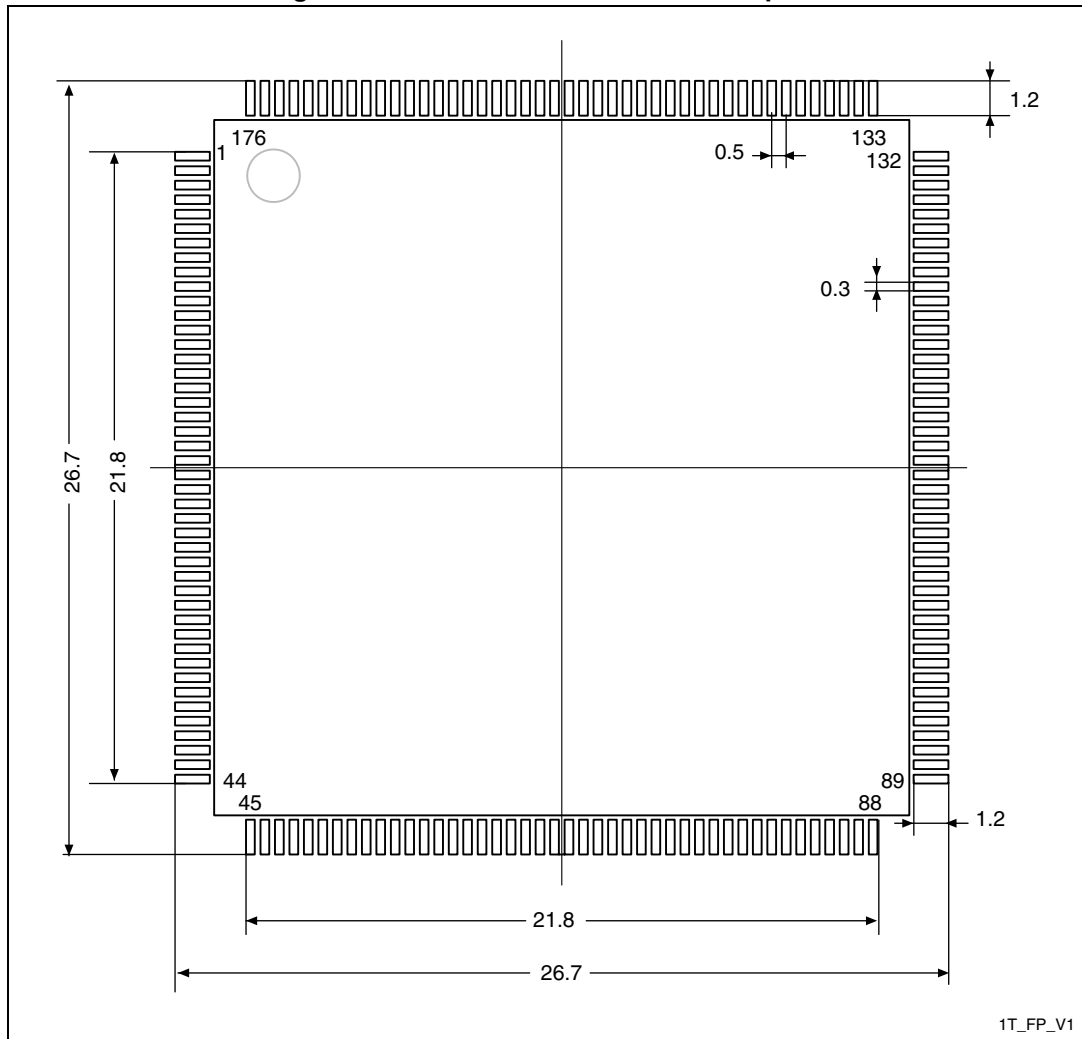
Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	-	1.450	0.0531	-	0.0060
b	0.170	-	0.270	0.0067	-	0.0106
C	0.090	-	0.200	0.0035	-	0.0079
D	23.900	-	24.100	0.9409	-	0.9488
E	23.900	-	24.100	0.9409	-	0.9488
e	-	0.500	-	-	0.0197	-
HD	25.900	-	26.100	1.0200	-	1.0276

**Table 17. LQFP176, 24 x 24 mm, 176-pin low-profile quad flat package mechanical data (continued)**

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
HE	25.900	-	26.100	1.0200	-	1.0276
L	0.450	-	0.750	0.0177	-	0.0295
L1	-	1.000	-	-	0.0394	-
ZD	-	1.250	-	-	0.0492	-
ZE	-	1.250	-	-	0.0492	-
ccc	-	-	0.080	-	-	0.0031
k	0 °	-	7 °	0 °	-	7 °

1. Values in inches are converted from mm and rounded to 4 decimal digits.

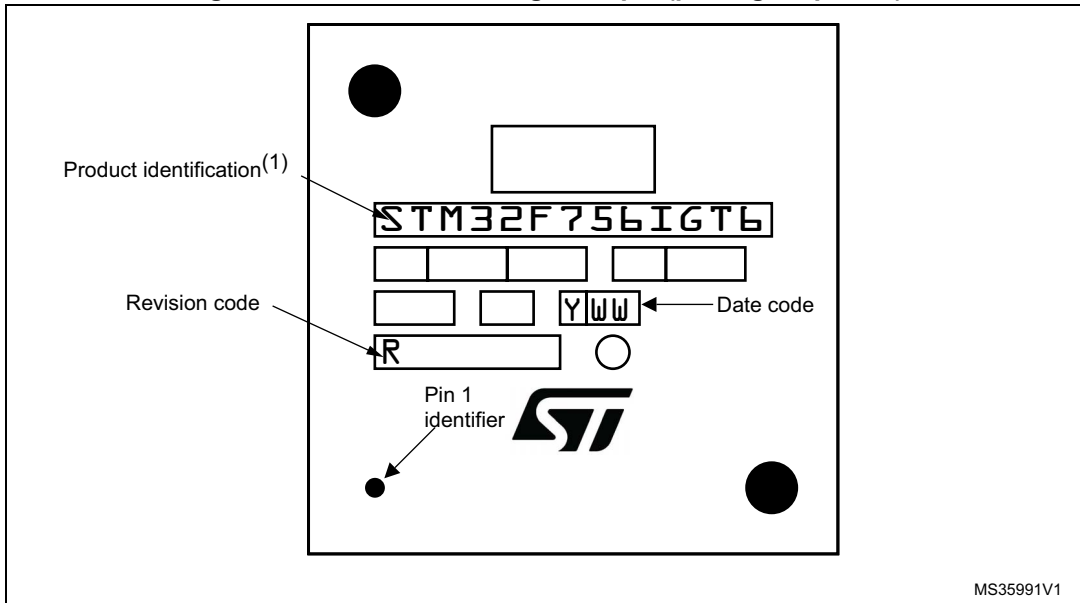
Figure 25. LQFP176 recommended footprint



1. Dimensions are expressed in millimeters.

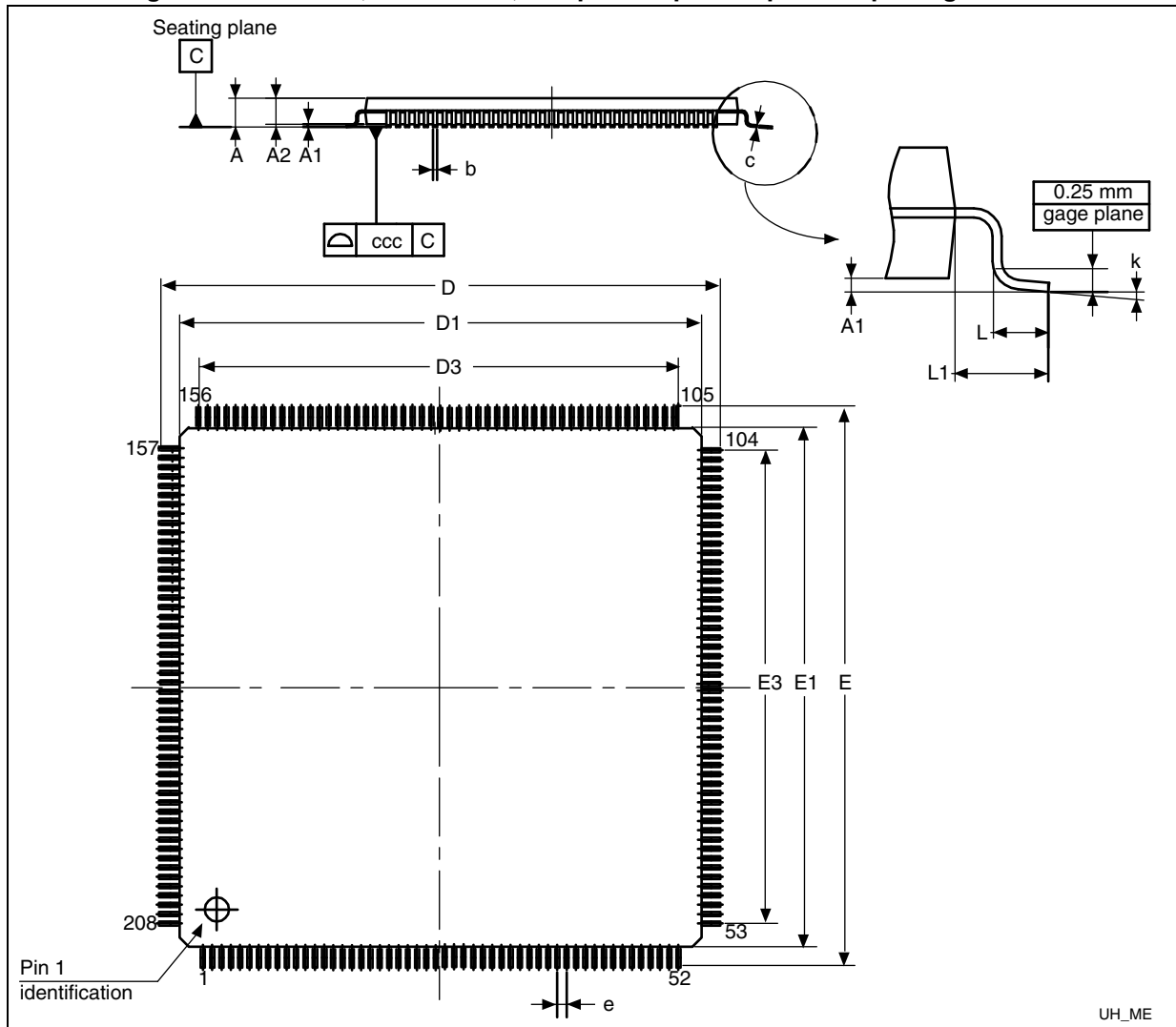
Device marking

Figure 26. LQFP176 marking example (package top view)



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

Figure 27. LQFP208, 28 x 28 mm, 208-pin low-profile quad flat package outline



1. Drawing is not to scale.

Table 18. LQFP208, 28 x 28 mm, 208-pin low-profile quad flat package mechanical data

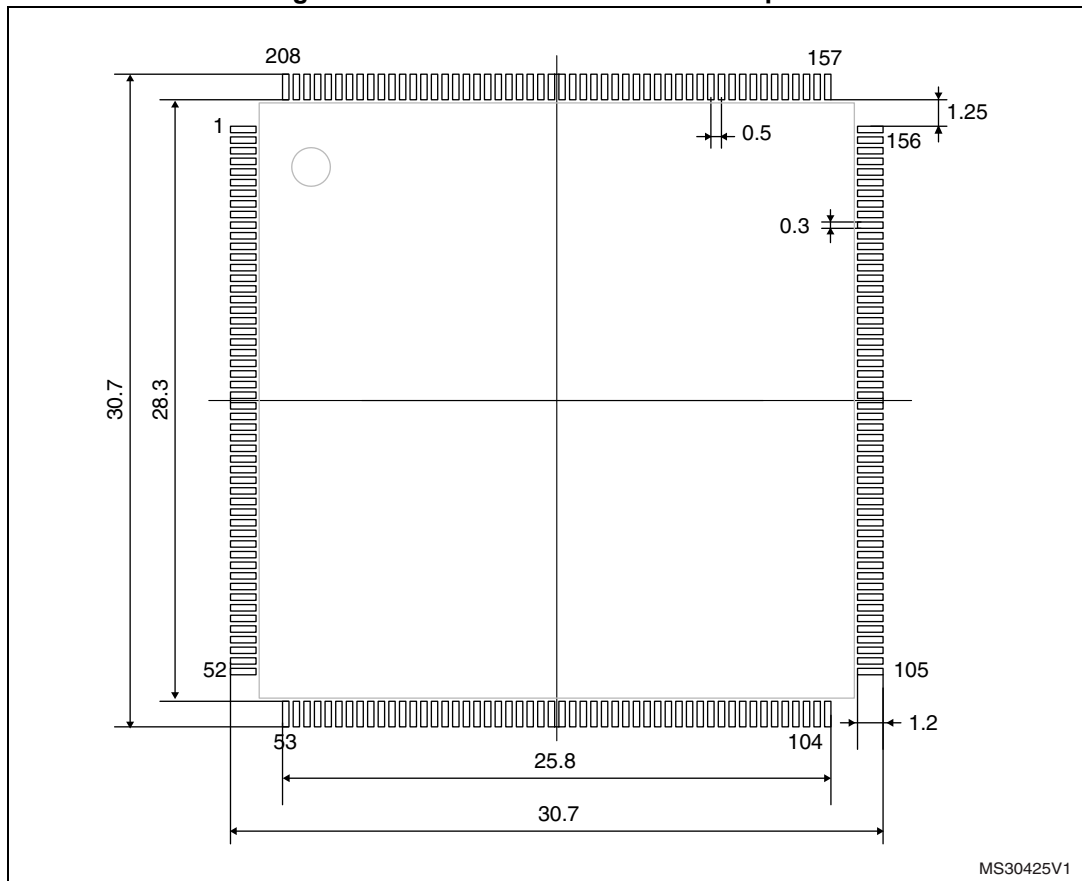
Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	--	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	29.800	30.000	30.200	1.1732	1.1811	1.1890
D1	27.800	28.000	28.200	1.0945	1.1024	1.1102

Table 18. LQFP208, 28 x 28 mm, 208-pin low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
D3	-	25.500	-	-	1.0039	-
E	29.800	30.000	30.200	1.1732	1.1811	1.1890
E1	27.800	28.000	28.200	1.0945	1.1024	1.1102
E3	-	25.500	-	-	1.0039	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7.0°	0°	3.5°	7.0°
ccc	-	-	0.080	-	-	0.0031

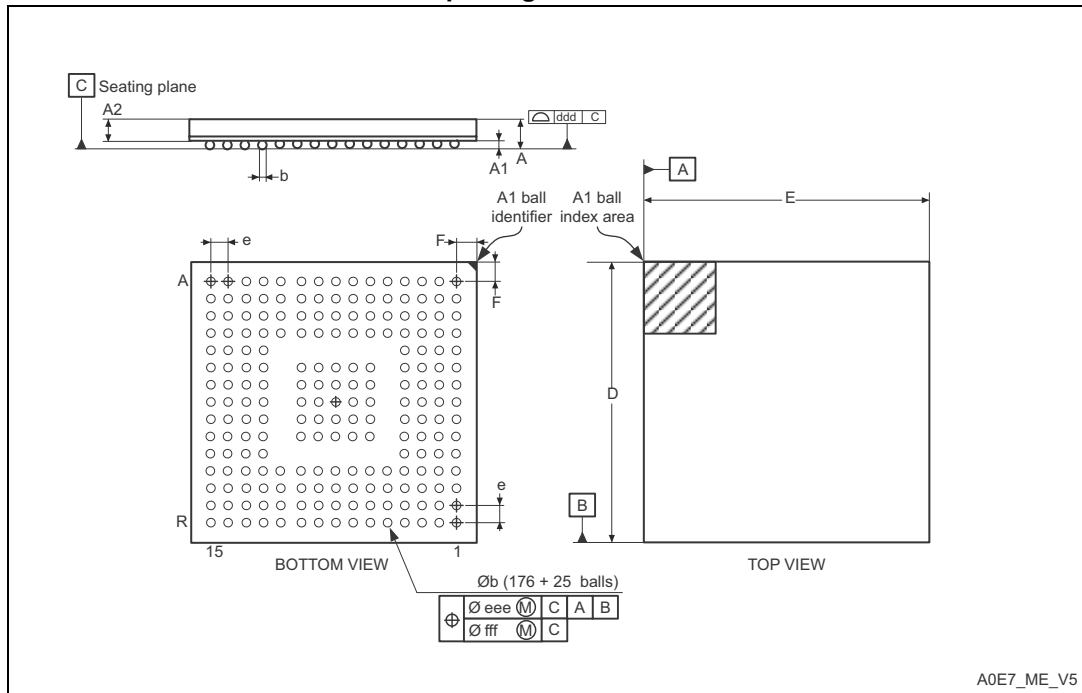
1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 28. LQFP208 recommended footprint



1. Dimensions are expressed in millimeters.

Figure 29. UFBGA176+25 - ultra thin fine pitch ball grid array 10 × 10 × 0.6 mm, package outline



1. Drawing is not to scale.

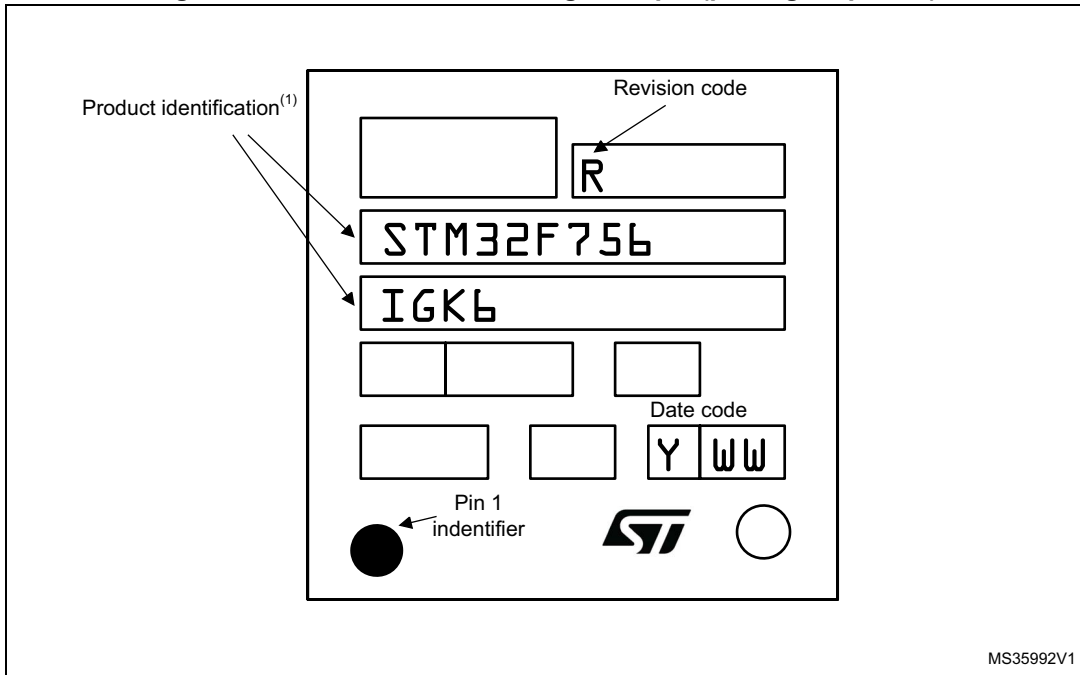
Table 19. UFBGA176+25 - ultra thin fine pitch ball grid array 10 × 10 × 0.6 mm mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	0.460	0.530	0.600	0.0181	0.0209	0.0236
A1	0.050	0.080	0.110	0.002	0.0031	0.0043
A2	0.400	0.450	0.500	0.0157	0.0177	0.0197
b	0.230	0.280	0.330	0.0091	0.0110	0.0130
D	9.950	10.000	10.050	0.3917	0.3937	0.3957
E	9.950	10.000	10.050	0.3917	0.3937	0.3957
e	-	0.650	-	-	0.0256	-
F	0.400	0.450	0.500	0.0157	0.0177	0.0197
ddd	-	-	0.080	-	-	0.0031
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

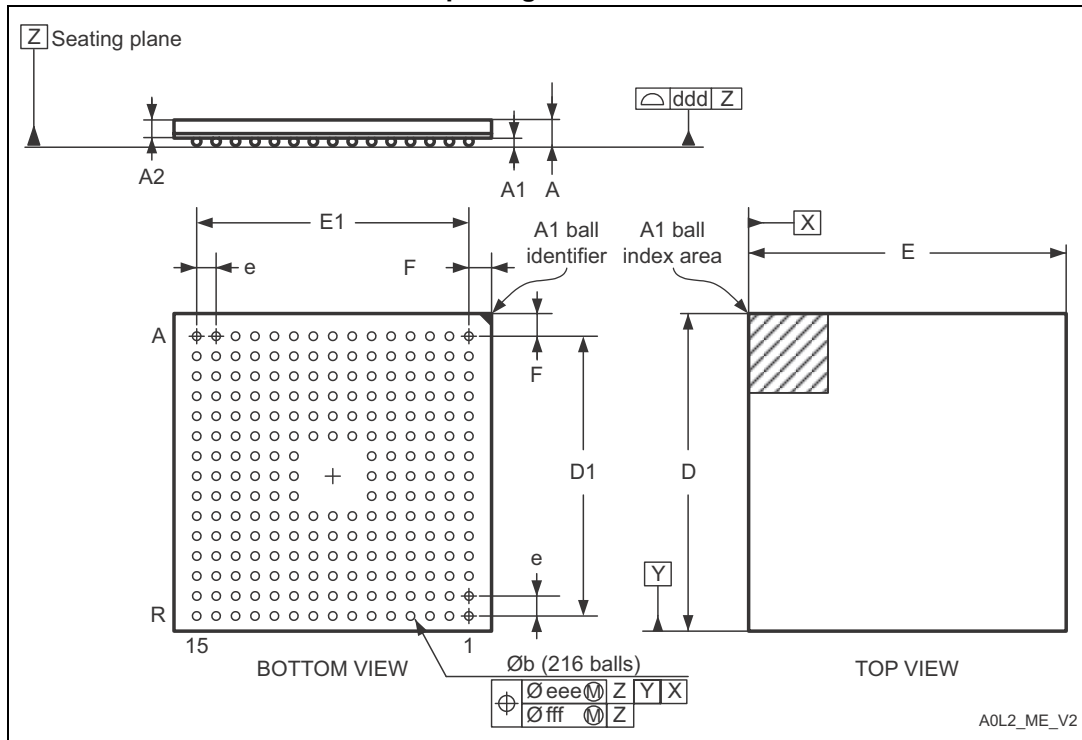
Device marking

Figure 30. UFBGA176+25 marking example (package top view)



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

Figure 31. TFBGA216 - thin fine pitch ball grid array 13 × 13 × 0.8mm, package outline



1. Drawing is not to scale.

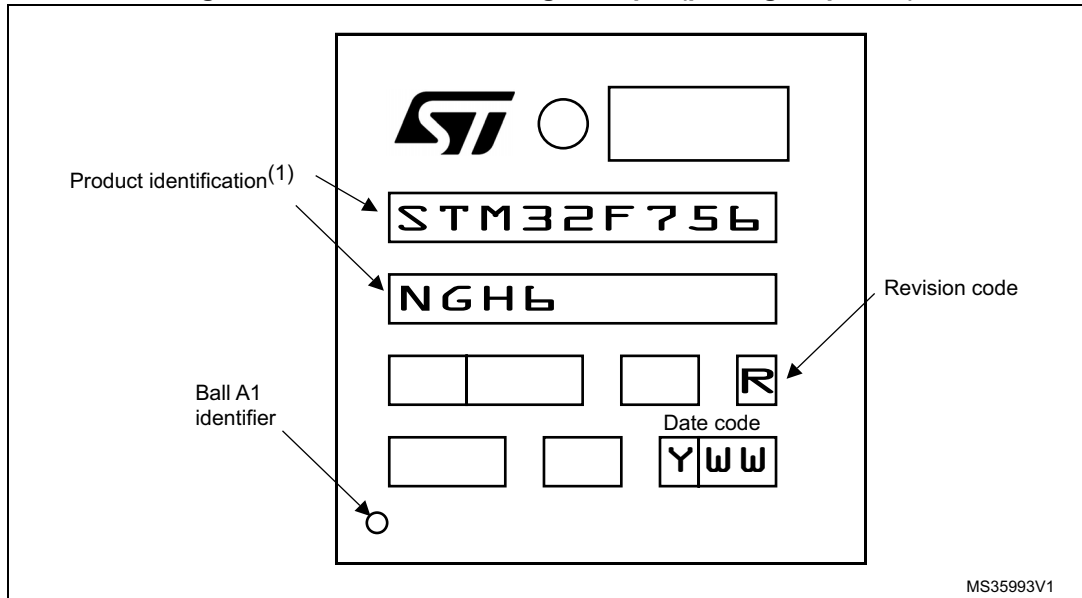
Table 20. TFBGA216 - thin fine pitch ball grid array 13 × 13 × 0.8mm package mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.100	-	-	0.0433
A1	0.150	-	-	0.0059	-	-
A2	-	0.760	-	-	0.0299	-
A4	-	0.210	-	-	0.0083	-
b	0.350	0.400	0.450	0.0138	0.0157	0.0177
D	12.850	13.000	13.150	0.5118	0.5118	0.5177
D1	-	11.200	-	-	0.4409	-
E	12.850	13.000	13.150	0.5118	0.5118	0.5177
E1	-	11.200	-	-	0.4409	-
e	-	0.800	-	-	0.0315	-
F	-	0.900	-	-	0.0354	-
ddd	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Device marking

Figure 32. TFBGA216 marking example (package top view)



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

## 5.2 Thermal characteristics

The maximum chip-junction temperature,  $T_J \text{ max}$ , in degrees Celsius, may be calculated using the following equation:

$$T_J \text{ max} = T_A \text{ max} + (P_D \text{ max} \times \Theta_{JA})$$

Where:

- $T_A \text{ max}$  is the maximum ambient temperature in °C,
- $\Theta_{JA}$  is the package junction-to-ambient thermal resistance, in °C/W,
- $P_D \text{ max}$  is the sum of  $P_{INT} \text{ max}$  and  $P_{I/O} \text{ max}$  ( $P_D \text{ max} = P_{INT} \text{ max} + P_{I/O} \text{ max}$ ),
- $P_{INT} \text{ max}$  is the product of  $I_{DD}$  and  $V_{DD}$ , expressed in Watts. This is the maximum chip internal power.

$P_{I/O} \text{ max}$  represents the maximum power dissipation on output pins where:

$$P_{I/O} \text{ max} = \Sigma (V_{OL} \times I_{OL}) + \Sigma ((V_{DD} - V_{OH}) \times I_{OH}),$$

taking into account the actual  $V_{OL} / I_{OL}$  and  $V_{OH} / I_{OH}$  of the I/Os at low and high level in the application.

**Table 21. Package thermal characteristics**

Symbol	Parameter	Value	Unit
$\Theta_{JA}$	Thermal resistance junction-ambient LQFP100 - 14 × 14 mm / 0.5 mm pitch	43	°C/W
	Thermal resistance junction-ambient WLCSP143	31.2	
	Thermal resistance junction-ambient LQFP144 - 20 × 20 mm / 0.5 mm pitch	40	
	Thermal resistance junction-ambient LQFP176 - 24 × 24 mm / 0.5 mm pitch	38	
	Thermal resistance junction-ambient LQFP208 - 28 × 28 mm / 0.5 mm pitch	19	
	Thermal resistance junction-ambient UFBGA176 - 10× 10 mm / 0.5 mm pitch	39	
	Thermal resistance junction-ambient TFBGA216 - 13 × 13 mm / 0.8 mm pitch	29	

### Reference document

JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air). Available from [www.jedec.org](http://www.jedec.org).

## 6 Part numbering

**Table 22. Ordering information scheme**

Example:	STM32	F	756	V	G	T	6	xxx
<b>Device family</b>								
STM32 = ARM-based 32-bit microcontroller								
<b>Product type</b>								
F = general-purpose								
<b>Device subfamily</b>								
756= STM32F756xx, USB OTG FS/HS, camera interface, Ethernet, LCD-TFT, cryptographic acceleration								
<b>Pin count</b>								
V = 100 pins								
Z = 143 and 144 pins								
I = 176 pins								
B = 208 pins								
N = 216 pins								
<b>Flash memory size</b>								
E = 512 Kbytes of Flash memory								
G = 1024 Kbytes of Flash memory								
<b>Package</b>								
T = LQFP								
K = UFBGA								
H = TFBGA								
Y = WLCSP								
<b>Temperature range</b>								
6 = Industrial temperature range, -40 to 85 °C.								
7 = Industrial temperature range, -40 to 105 °C.								
<b>Options</b>								
xxx = programmed parts								
TR = tape and reel								

For a list of available options (speed, package, etc.) or for further information on any aspect of this device, please contact your nearest ST sales office.

## Appendix A Recommendations when using internal reset OFF

When the internal reset is OFF, the following integrated features are no longer supported:

- The integrated power-on reset (POR) / power-down reset (PDR) circuitry is disabled.
- The brownout reset (BOR) circuitry must be disabled.
- The embedded programmable voltage detector (PVD) is disabled.
- V<sub>BAT</sub> functionality is no more available and VBAT pin should be connected to V<sub>DD</sub>.
- The over-drive mode is not supported.

### A.1 Operating conditions

Table 23. Limitations depending on the operating power supply range

Operating power supply range	ADC operation	Maximum Flash memory access frequency with no wait states (f <sub>Flashmax</sub> )	Maximum Flash memory access frequency with wait states <sup>(1)(2)</sup>	I/O operation	Possible Flash memory operations
V <sub>DD</sub> = 1.7 to 2.1 V <sup>(3)</sup>	Conversion time up to 1.2 Msps	20 MHz <sup>(4)</sup>	168 MHz with 8 wait states and over-drive OFF	– No I/O compensation	8-bit erase and program operations only

1. Applicable only when the code is executed from Flash memory. When the code is executed from RAM, no wait state is required.
2. Thanks to the ART accelerator and the 128-bit Flash memory, the number of wait states given here does not impact the execution speed from Flash memory since the ART accelerator allows to achieve a performance equivalent to 0 wait state program execution.
3. V<sub>DD</sub>/V<sub>DDA</sub> minimum value of 1.7 V, with the use of an external power supply supervisor (refer to [Section 2.17.1: Internal reset ON](#)).
4. Prefetch is not available.

## 7 Revision history

**Table 24. Document revision history**

Date	Revision	Changes
09-Sept-2014	1	Initial release.
18-Nov-2014	2	Updated <i>Figure 1: Compatible board design for LQFP100 package</i> and <i>Figure 2: STM32F756xx block diagram</i> . Updated <i>Figure 16: Memory map</i> . Updated <i>Figure 19: LQFP100 marking example (package top view)</i> , <i>Figure 23: LQFP144 marking example (package top view)</i> , <i>Figure 26: LQFP176 marking example (package top view)</i> , <i>Figure 30: UFBGA176+25 marking example (package top view)</i> and <i>Figure 32: TFBGA216 marking example (package top view)</i> .

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