

FR81S
32-BIT MICROCONTROLLER
MB91590 Series
HARDWARE MANUAL

Following URL introduces the information for effective development of Fujitsu Semiconductor microcontrollers. Helpful information is being released for the customers who are considering, or have adopted our microcontrollers.

<http://edevice.fujitsu.com/micom/en-support/>

Preface

Thank you for your continued use of Fujitsu semiconductor products.

Read this manual and "Data Sheet" thoroughly before using products in the MB91590 series.

■ Purpose of this manual and intended readers

This series is Fujitsu 32-bit microcontroller designed for automotive and industrial control. It contains the FR81S CPU that is compatible with the FR family. The FR81S CPU has a high level performance among the FR family by enhancing instruction pipeline and load store processing, and improving internal bus transfer.

It is best suited for application control for automotive.

This manual explains the function, operation, and the usage for the engineer who develops the product by actually using this series.

■ Trademark

FR is an abbreviation for the FUJITSU RISC controller, which is a product of Fujitsu Semiconductor Limited.

The company names and brand names herein are the trademarks or registered trademarks of their respective owners.

■ Sample programs and development environment

Fujitsu Semiconductor offers sample programs free of charge for using the peripheral functions of the FR81S family. Fujitsu Semiconductor also makes available descriptions of the development environment required for the MB91590 series. Feel free to use them to verify the operational specifications and usage of this Fujitsu semiconductor microcontroller.

- Microcontroller support information:

<http://edevic.fujitsu.com/micom/en-support/>

- * : Note that the sample programs are subject to change without notice. Since they are offered as a way to demonstrate standard operations and usage, evaluate them sufficiently before running them on your system.

Fujitsu semiconductor assumes no responsibility for any damage that may occur as a result of using a sample program.

- The contents of this document are subject to change without notice.
Customers are advised to consult with sales representatives before ordering.
- The information, such as descriptions of function and application circuit examples, in this document are presented solely for the purpose of reference to show examples of operations and uses of FUJITSU SEMICONDUCTOR device; FUJITSU SEMICONDUCTOR does not warrant proper operation of the device with respect to use based on such information. When you develop equipment incorporating the device based on such information, you must assume any responsibility arising out of such use of the information. FUJITSU SEMICONDUCTOR assumes no liability for any damages whatsoever arising out of the use of the information.
- Any information in this document, including descriptions of function and schematic diagrams, shall not be construed as license of the use or exercise of any intellectual property right, such as patent right or copyright, or any other right of FUJITSU SEMICONDUCTOR or any third party or does FUJITSU SEMICONDUCTOR warrant non-infringement of any third-party's intellectual property right or other right by using such information. FUJITSU SEMICONDUCTOR assumes no liability for any infringement of the intellectual property rights or other rights of third parties which would result from the use of information contained herein.
- The products described in this document are designed, developed and manufactured as contemplated for general use, including without limitation, ordinary industrial use, general office use, personal use, and household use, but are not designed, developed and manufactured as contemplated (1) for use accompanying fatal risks or dangers that, unless extremely high safety is secured, could have a serious effect to the public, and could lead directly to death, personal injury, severe physical damage or other loss (i.e., nuclear reaction control in nuclear facility, aircraft flight control, air traffic control, mass transport control, medical life support system, missile launch control in weapon system), or (2) for use requiring extremely high reliability (i.e., submersible repeater and artificial satellite).
Please note that FUJITSU SEMICONDUCTOR will not be liable against you and/or any third party for any claims or damages arising in connection with above-mentioned uses of the products.
- Any semiconductor devices have an inherent chance of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.
- Exportation/release of any products described in this document may require necessary procedures in accordance with the regulations of the Foreign Exchange and Foreign Trade Control Law of Japan and/or US export control laws.
- The company names and brand names herein are the trademarks or registered trademarks of their respective owners.

Copyright ©2011 FUJITSU SEMICONDUCTOR LIMITED All rights reserved.

How to Use This Manual

■ Finding a function

The following methods can be used to search for the explanation of a desired function in this manual:

- Search from the table of the contents
The table of the contents lists the manual contents in the order of description.
- Search from the register
The register list for this device has been described. You can look up the name of a desired register on the list to find the address of its location or the page that explains it.
The address where each register is located is not described in the text. To verify the address of a register, see "B. I/O Map" of "APPENDIX".
- Search from the index
You can look up the keyword such as the name of a peripheral function in the index to find the explanation of the function.

■ About the chapters

Basically, this manual explains 1 peripheral function per chapter.

■ Terminology

This manual uses the following terminology.

Term	Explanation
Word	Indicates access in units of 32 bits.
Half word	Indicates access in units of 16 bits.
Byte	Indicates access in units of 8 bits.

■ How to Read This Manual

- Primary Terms

The following explains the primary terms used in this series

Term	Explanation
XBS	A 32-bit width, high-speed internal bus. The bus master is used for access from the CPU (for instruction fetch), the CPU (for data reading or writing), or the on-chip bus. The bus slave is used to access to the on-chip bus, RAM (via the XBS built-in wild register), and flash memory. The bus has a crossbar switch configuration, and a circuit from each bus master to each bus slave can operate simultaneously.
On-chip bus	A 32-bit width, high-speed internal bus. It has a 2-layer structure for XBS and DMA, and they can operate simultaneously. The bus master of the XBS layer is accessed from the XBS. The bus master of the DMA layer is accessed from the DMA. The bus slave of both layers has an external bus interface, CAN, 16/32-bit peripheral bus bridge and others. The bus slave of only DMA layer has an access to the XBS.
32-bit peripheral	A 32-bit width, low-speed internal bus.

Term	Explanation
bus	It connects to various types of peripherals.
16-bit peripheral bus (R-bus)	A 16-bit width, low-speed internal bus. It connects to various types of peripherals. The 32-bit width access to this bus is divided into 16 bits x 2.
External bus (External bus)	8/16-bit width, low-speed external bus. It connects to memory devices, ASIC and others. This series is the bus master, and a device connected to the external bus is a bus slave.
Main clock (MCLK)	This is the reference clock for LSI operation, and it is supplied from the high-speed system oscillator. It is connected to the timer for main oscillation stabilization wait, the clock generator (PLL) and others.
Sub clock (SBCLK)	This is the reference clock for LSI operation, and it is supplied from the low-speed system oscillator. It is connected to the timer for sub oscillation stabilization wait and others. It can be used by the dual clock products only.
CR oscillation	The clock for watchdog timer 1 (hardware watchdog)
PLL clock (PLLCLK)	The main clock is multiplied by PLL.
CPU clock (CCLK)	The clock for peripherals operating under the XBS.
On-chip bus clock (HCLK)	The clock for peripherals operating under the on-chip bus.
Peripheral clock (PCLK)	The clock for peripherals operating under the 32-bit peripheral bus and 16-bit peripheral bus.
External bus clock (TCLK)	The reference clock for an external bus interface connected to the X-bus and for the external clock output. It is generated from the base clock by the clock generator.
Main clock mode	The operation mode based on the main clock. The main clock mode has the main RUN, main sleep, main stop, oscillation stabilization wait RUN, oscillation stabilization wait reset, and program reset state.
Main RUN	The main clock mode is selected, and all circuits are operable.
Oscillation stabilization wait time	When the clock is switched from the stop state to the oscillation state, the clock takes the oscillation stabilization time. During the oscillation stabilization wait time, the clock is not supplied.
OCD	The on-chip debugger for this series
OCDE	The OCD interface built in this product.
OCD tool	The OCD tool can be connected to the DEBUG I/F pin of this device.
Chip reset sequence	In the chip reset sequence, the connection of OCD tool is checked. It takes (1026+3) PCLK cycles.
Power shutdown	The power supply to the target circuit is stopped, and power consumption is decreased.
Always power supply ON block	It is not a target division for the power shutdown.
PMU Power management unit	The power shutdown is controlled. PMU exists in always ON block.

Term	Explanation
SSCG	<p>SSCG mean "Spread Spectrum Clock Generator".</p> <p>When the clock in electronic equipment generates a single frequency, the radiation because of the frequency and the higher harmonics wave grows.</p> <p>It is a technology to suppress the peak of EMI to low.</p> <p>SSCG is a technology that suppresses the peak of EMI to low by the clock frequency change slightly and oscillates it (= frequency modulation). When the clock in electronic equipment generates a single frequency, the radiation because of the frequency and the higher harmonics wave grows.</p> <p>SSCG is a technology that does working that suppresses the peak of EMI to low especially depending that makes the clock frequency change slightly and oscillates it (= frequency modulation).</p>

■ Access Unit and Address Position

Address	Address offset value/Register name				Block
	+0	+1	+2	+3	
000060 _H	SSR0[R/W] B, H, W 00001000	SIDR0[R] B, H, W SODR0[W] B, H, W XXXXXXXX	SCR0[R/W] B, H, W 00000100	SMR0[R/W] B, H, W 00000-0-	UART0
000064 _H	UTIM0[R] H (UTIMR0[W]H) 00000000 00000000		DRCL0[W] B XXXXXXXX	UTIMC0[R/W] B 0--00001	U-TIMER0

Offset
Register name
Read only
Readable/Writable

Byte access, Half-word access, Word access
Write only
Initial Value

Although three types of access (Byte, Half-word, and Word access) are enabled, some registers have access restrictions. For details, see "APPENDIX", or section "4. Detailed Register Description" of each chapter.

- B, H, W : Byte access, Half-word access, and Word access are enabled.
- B : Byte access (Use the Byte access only.)
- H : Half-word access (Use the Half-word access only.)
- W : Word access (Use the Word access only.)
- B, H : Byte access and Half-word access only (The Word access is not allowed.)
- H, W : Half-word access and Word access only (The Byte access is not allowed.)

(Reference)

The following explains the address position during access.

- During Word access, the address is a multiple of 4 (the lowest order 2 bits are forcibly set to "00").
- During Half-word access, the address is a multiple of 2 (the lowest order 1 bit is forcibly set to "0").
- During Byte access, the address remains unchanged.

Therefore, if the SSR0 register is set to the Half-word access, for example, SSR0 + SIDR0 (SODR0) register at address 060_H is accessed.

(If the address offsets are +1 and +2 (for example, SIDR0+SCR0), the Half-word access is not allowed.)

■ Access Unit and Bit Position

Register name Register abbreviation Target peripheral function Address Access unit

4.3 Serial Status Register

The register indicates the UART state.

(Example) SSR0 (UART0) : Address 0060H (Access : Byte, Half-word, Word)

Bit position

bit	7	6	5	4	3	2	1	0
	PE	ORE	FRE	RDRF	TDRE	BDS	RIE	TIE
Initial value	0	0	0	0	1	0	0	0
Attribute	R/W	R/WX	R/WX	R/WX	R/WX	R/W	R/W	R/W

If the access unit is changed, the bit position changes.

If the address offset is +0: (Example of SSR0 register)

Access size	Address	Bit position							
Word	060H+0H	7	6	5	4	3	2	1	0
Half-word	060H+0H	15	14	13	12	11	10	9	8
Word	060H+0H	31	30	29	28	27	26	25	24
Bit name		PE	ORE	FRE	RDRF	TDRE	BDS	RIE	TIE

If the address offset is +1: (Example of SIDR0 register)

Access size	Address	Bit position							
Word	060H+1H	7	6	5	4	3	2	1	0
Half-word	060H+0H	7	6	5	4	3	2	1	0
Word	060H+0H	23	22	21	20	19	18	17	16
Bit name		D7	D6	D5	D4	D3	D2	D1	D0

If the address offset is +2: (Example of SCR0 register)

Access size	Address	Bit position							
Word	060H+2H	7	6	5	4	3	2	1	0
Half-word	060H+2H	15	14	13	12	11	10	9	8
Word	060H+0H	15	14	13	12	11	10	9	8
Bit name		PEN	P	SBL	CL	A/D	REC	RXE	TXE

If the address offset is +3: (Example of SMR0 register)

Access size	Address	Bit position							
Word	060H+3H	7	6	5	4	3	2	1	0
Half-word	060H+2H	7	6	5	4	3	2	1	0
Word	060H+0H	7	6	5	4	3	2	1	0
Bit name		MD1	MD0	CS2	CS1	CS0	-	SCKE	-

■ Meaning of Bit Attribute Symbols

R	: Read enabled
W	: Write enabled
RM	: Reading operation during read-modify-write(RMW) operation
"/" (slash) R/W	: Read and write enabled. (The read value is the written value.)
"," (comma) R, W	: The read and written values differ from each other. (The read value is different from the written value.)
R0	: The read value is "0".
R1	: The read value is "1".
W0	: This bit must always be written to "0".
W1	: This bit must always be written to "1".
(RM0)	: "0" is read by read-modify-write(RMW) operation.
(RM1)	: "1" is read by read-modify-write(RMW) operation.
RX	: The read value is undefined. (A reserved bit or an undefined bit)
WX	: Writing does not affect on the operation. (Undefined bit)

• R/W writing examples

- R/W : Read and write enabled (The read value is the written value.)
- R,W : Read and write enabled (The read value is different from the written value.)
- R,RM/W : Read and write enabled (The read value is different from the written value. The written value is read by read-modify-write (RMW) instruction.) An example is a port data register.
- R(RM1),W : Read and write enabled (The read value is different from the written value. For read-modify-write (RMW) instructions, "1" will be read out.) An example is an interrupt request flag.
- R,WX : Read only (Read enabled. Writing has no effect on operation.)
- R1,W : Write only (Write enabled. The read value is "1".)
- R0,W : Write only (Write enabled. The read value is "0".)
- RX,W : Write only (Write enabled. The read value is undefined.)
- R0,W0 : Reserved bit (The written value is "0". The read value is the written value.)
- R0,W0 : Reserved bit (The written value is "0". The read value is "0".)
- R1,W0 : Reserved bit (The written value is "0". The read value is "1".)
- RX,W0 : Reserved bit (The written value is "0". The read value is undefined.)
- R/W1 : Reserved bit (The written value is "1". The read value is the written value.)
- R1,W1 : Reserved bit (The written value is "1". The read value is "1".)
- R0,W1 : Reserved bit (The written value is "1". The read value is "0".)
- RX,W1 : Reserved bit (The written value is "1". The read value is undefined.)
- RX,WX : Undefined bit (The read value is undefined. Writing has no effect on operation.)
- R0,WX : Undefined bit (The read value is "0". Writing has no effect on operation.)

CONTENTS

CHAPTER 1: OVERVIEW	1
1. Overview	2
2. Features	3
2.1. FR81S CPU Core	4
2.2. Peripheral Functions.....	5
3. Product Line-up.....	8
4. Function Overview	16
5. Block Diagram.....	19
6. CPU.....	20
6.1. General-purpose Registers	21
6.2. Dedicated Registers	22
7. Pin Assignment	23
8. Package Dimensions	25
9. Explanation of Pin Functions	27
10. Pins of Each Function.....	44
10.1. Pins of AD Converter	45
10.2. Pins of CAN (ch.0 to ch.2).....	46
10.3. Pins of External Interrupt Input (ch.0 to ch.15).....	47
10.4. Pins of LIN-UART (ch.2 to ch.7)	48
10.5. Pins of Multi-function Serial Interface (ch.0, ch.1).....	49
10.6. Pins of PPG (ch.0 to ch.23).....	50
10.7. Pin of Real Time Clock	52
10.8. Pins of Stepping Motor Controller (ch.0 to ch.5)	53
10.9. Pins of Output Compare (ch.0 to ch.3).....	54
10.10. Pins of Input Capture (ch.0 to ch.5)	55
10.11. Pins of Sound Generator (ch.0 to ch.4).....	56
10.12. Pins of Free-run Timer (ch.0, ch.1)	57
10.13. Pins of Base Timer (ch.0, ch.1)	58
10.14. Pins of Reload Timer (ch.0 to ch.3).....	59
10.15. Pins of External Bus Interface (GDC External Memory I/F).....	60
10.16. Pins of SPI Interface (GDC External Memory I/F)	61
10.17. Pins of Port Function (General-purpose I/O)	62
10.18. Pins of GDC (Capture RGB Mode)	65
10.19. Pins of GDC (Capture 656 Mode).....	66
10.20. Pins of GDC (Capture Other)	67
10.21. Pins of GDC (Display)	68
10.22. Pins of GDC (NTSC)	69
10.23. Pin of GDC (Other).....	70
10.24. Pins of Other	71
11. I/O Circuit Types.....	72
CHAPTER 2: HANDLING THE DEVICE	77
1. Handling Precautions.....	78
2. Handling Device.....	82
3. Application Notes	85
3.1. Function Switching of a Multiplexed Port	86
3.2. Low-power Consumption Mode.....	87
3.3. Notes When Writing Data in a Register Having the Status Flag.....	88

CHAPTER 3: CPU	89
1. Overview	90
2. Features	91
3. CPU Operating Description	93
4. Pipeline Operation	95
5. Floating Point Operation Processing	96
6. Data Structure	97
7. Addressing	98
8. Programming Model.....	99
8.1. General-purpose Registers, Dedicated Registers, and Floating Point Registers	100
8.2. System Register	101
9. Reset and EIT Processing	102
9.1. Reset	103
9.2. EIT Processing	104
9.3. Vector Table.....	105
10. Memory Protection Function (MPU)	107
10.1. Overview.....	108
10.2. List of Registers.....	109
10.3. Description of Registers	110
10.3.1. MPU Control Register (MPUCR)	111
10.3.2. Instruction Access Protection Violation Address Register (IPVAR)	114
10.3.3. Instruction Access Protection Violation Status Register (IPVSR)	115
10.3.4. Data Access Protection Violation Address Register (DPVAR).....	117
10.3.5. Data Access Protection Violation Status Register (DPVSR)	118
10.3.6. Data Access Error Address Register (DEAR).....	120
10.3.7. Data Access Error Status Register (DESR)	121
10.3.8. Protection Area Base Address Register 0 to 7 (PABR0 to PABR7).....	123
10.3.9. Protection Area Control Register 0 to 7 (PACR0 to PACR7)	124
10.4. Operations of Memory Protection Function (MPU)	128
10.4.1. Setting Up Memory Protection Areas.....	129
10.4.2. Instruction Access Protection Violation.....	130
10.4.3. Data Access Protection Violation	131
10.4.4. Data Access Errors	132
10.4.5. Memory Protection Operation by Delay Slot	133
10.4.6. DEAR and DESR Update	134
10.4.7. Notes.....	135
 CHAPTER 4: OPERATION MODE	 137
1. Overview	138
2. Features	139
3. Configuration.....	140
4. Register.....	141
5. Operation	142
5.1. MD0, MD1, MD2, P127 Pins Settings	143
5.2. Fetching the Operation Mode.....	144
5.3. Explanation of Each Operation Mode.....	145

CHAPTER 5: CLOCK	147
1. Overview	148
2. Features	150
3. Configuration.....	151
4. Registers	156
4.1. Division Configuration Register 0 : DIVR0 (Division clock configuration Register 0).....	158
4.2. Division Configuration Register 1 : DIVR1 (Division clock configuration Register 1).....	159
4.3. Division Configuration Register 2 : DIVR2 (Division clock configuration Register 2).....	160
4.4. Clock Source Selection Register : CSELR (Clock source Selection Register)	161
4.5. Clock Source Monitor Register : CMONR (Clock source MONitor Register).....	164
4.6. Main Timer Control Register : MTMCR (Main clock TiMER Control Register)	166
4.7. Sub Timer Control Register : STMCR (Sub clock TiMER Control Register).....	168
4.8. PLL Setting Register : PLLCR (PLL Configuration Register)	170
4.9. Clock Stabilization Selection Register : CSTBR (Clock STaBilization selection Register).....	173
4.10. PLL Clock Oscillation Timer Control Register : PTMCR (PLL clock osc TiMER Control Register).....	175
4.11. PLL/SSCG Clock Selection Register : CCPSELR (CCtl Pll/Sscg clock Selection Register)	176
4.12. PLL/SSCG Output Clock Division Setting Register : CCPSDIVR (CCtl Pll/Sscg clock DIVision Register)	177
4.13. PLL Feedback Division Setting Register : CCPLLFBR (CCtl PLL FB clock division Register)	179
4.14. SSCG Feedback Division Setting Register 0 : CCSSFBR0 (CCtl SScg FB clock division Register 0).....	180
4.15. SSCG Feedback Division Setting Register 1 : CCSSFBR1 (CCtl SScg FB clock division Register 1).....	181
4.16. SSCG Configuration Setting Register 0 : CCSSCCR0 (CCtl SScg Config. Register 0) .	182
4.17. SSCG Configuration Setting Register 1 : CCSSCCR1 (CCtl SScg Config. Register 1) .	184
4.18. Clock Gear Configuration Setting Register 0 : CCCGRCR0 (CCtl Clock Gear Config. Register 0).....	185
4.19. Clock Gear Configuration Setting Register 1 : CCCGRCR1 (CCtl Clock Gear Config. Register 1).....	187
4.20. Clock Gear Configuration Setting Register 2 : CCCGRCR2 (CCtl Clock Gear Config. Register 2).....	188
4.21. RTC/PMU Clock Selection Register : CCRTSELR (CCtl RTc pmu clock Selection Register)	189
4.22. PMU Clock Division Setting Register 0 : CCPMUCR0 (CCtl PMU Clock division Register 0)	191
4.23. PMU Clock Division Setting Register 1 : CCPMUCR1 (CCtl PMU Clock division Register 1)	192
4.24. Sync/Async Control Register : SACR (Sync/Async Control Register)	194
4.25. Peripheral Interface Clock Divider : PICD (Peripheral Interface Clock Divider).....	195
4.26. GDC PLL Control Register : GPLLCR.....	197
4.27. GDC PLL Timer Setting Register : PTIMCR:.....	198
4.28. GDC PLL External Division Setting Register : PEDIVCR	199
4.29. GDC PLL Multiplier Setting Register : PDIVCR	201
4.30. GDC PLL_SSCG Multiplier Setting Register 0 : SDIVCR0	202
4.31. GDC PLL_SSCG Multiplier Setting Register 1 : SDIVCR1	203
4.32. GDC PLL_SSCG Spread Spectrum Setting Register 0 : SSSCR0.....	204
4.33. GDC PLL_SSCG Spread Spectrum Setting Register 1 : SSSCR1.....	206
4.34. GDC PLL Clock Gear Setting Register 0 : PGRRCR0	207
4.35. GDC PLL Clock Gear Setting Register 1 : PGRRCR1	209
4.36. GDC PLL Clock Gear Setting Register 2 : PGRRCR2	211
4.37. GDC PLL_SSCG Clock Gear Setting Register 0 : SGRRCR0	212
4.38. GDC PLL_SSCG Clock Gear Setting Register 1: SGRRCR1	214
4.39. GDC PLL_SSCG Clock Gear Setting Register 2 : SGRRCR2	216

5. Operation	217
5.1. Oscillation Control	218
5.1.1. Main Clock (MCLK).....	219
5.1.2. Sub Clock (SBCLK)	220
5.1.3. PLL/SSCG Clock (PLLSSCLK).....	221
5.1.4. Limitations when PLL/SSCG Clock is used.....	224
5.2. Oscillation Stabilization Wait.....	226
5.2.1. Conditions for Generating Stabilization Wait Time.....	227
5.2.2. Selecting Stabilization Wait Time	228
5.2.3. End of the Stabilization Wait Time	229
5.3. Selecting the Source Clock (SRCCLK)	230
5.3.1. Selecting the Source Clock at the Time of Initialization.....	231
5.3.2. Procedure of switching the source clock	232
5.4. Timer.....	237
5.4.1. Main Clock Oscillation Stabilization Wait Timer (Main Timer).....	238
5.4.2. Sub Clock Oscillation Stabilization Wait Timer (Sub Timer)	239
5.4.3. PLL/SSCG Clock Oscillation Stabilization Wait timer (PLL Timer)	240
5.4.4. Setting.....	241
5.4.5. Procedure for Setting the Timer Interrupt	242
5.4.6. Timer Operations	243
5.4.7. Watch Mode and Timer Interrupt	244
5.5. Notes when Clocks Conflict.....	245
5.6. The Clock Gear Circuit	246
5.6.1. Procedure of Gear Up.....	247
5.6.2. Procedure of Gear Down	248
5.7. Operations during MDI Communications	249
5.8. About PMU clock (PMUCLK)	250
CHAPTER 6: CLOCK RESET STATE TRANSITIONS.....	253
1. Overview	254
2. Device States and Transitions	255
2.1. Diagram of State Transitions.....	256
2.2. Explanation of Each States	258
2.3. Priority of State Transition Requests.....	260
3. Device State and Regulator Mode Corresponding to those States.....	261
CHAPTER 7: RESET	263
1. Overview	264
2. Features	265
3. Configuration.....	266
4. Registers	268
4.1. Reset Source Register : RSTRR (ReSeT Result Register)	269
4.2. Reset Control Register : RSTCR (ReSeT Control Register).....	271
4.3. CPU Abnormal Operation Register : CPUAR (CPU Abnormal operation Register).....	272
4.4. PMU Status Register : PMUSTR (Power Management Unit STatus register)	274
5. Operation Description	275
5.1. Reset Level.....	276
5.1.1. Initialize Reset (INIT)	277
5.1.2. Reset (RST)	278
5.2. Reset Factor	279
5.2.1. Power-on Reset	280

5.2.2.	RSTX Pin Input	281
5.2.3.	Watchdog Reset 0	282
5.2.4.	Watchdog Reset 1	283
5.2.5.	External Low-Voltage Detection Reset	284
5.2.6.	Illegal Standby Mode Transition Detection Reset	285
5.2.7.	Internal Low-Voltage Detection Reset	286
5.2.8.	Flash Security Violation Reset	287
5.2.9.	Software Reset (RSTCR:SRST)	288
5.2.10.	Recovery from Standby (Power Interception)	289
5.3.	Reset Acceptance	290
5.3.1.	Generation of Reset Request	291
5.3.2.	Acceptance of Reset Request	292
5.3.3.	Reset Issue Delay Counter	293
5.3.4.	Irregular Reset	294
5.4.	Reset Issue	295
5.4.1.	Power-on Reset (SINIT)	296
5.4.2.	Initialize Reset (INIT)	298
5.4.3.	Reset (RST)	299
5.5.	Reset Sequence	300
5.5.1.	Reset Cycle	301
5.5.2.	Reset Release	302
5.5.3.	Operating Mode Fix	303
5.5.4.	Transition of Bus Control	304
5.5.5.	Reset Vector Fetch	305
5.5.6.	Reset and Forced Break	306
5.6.	Notes	307

CHAPTER 8: DMA CONTROLLER (DMAC)309

1.	Overview	310
2.	Features	311
3.	Configuration	312
4.	Registers	313
4.1.	DMA Control Register: DMACR (DMA Control Register)	316
4.2.	DMA Channel Control Register 0 to 15: DCCR0 to 15 (DMA Channel Control Register 0 to 15)	318
4.3.	DMA Channel Status Register 0 to 15 : DCSR0 to 15: (DMA Channel Status Register 0 to 15)	324
4.4.	DMA Transfer Count Register 0 to 15 : DTCR0 to 15: (DMA Transfer Count Register 0 to 15)	326
4.5.	DMA Transfer Source Register 0 to 15 : DSAR0 to 15: (DMA Source Address Register 0 to 15)	327
4.6.	DMA Transfer Destination Register 0 to 15 : DDAR0 to 15 (DMA Destination Address Register 0 to 15)	329
4.7.	DMA Transfer Suppression NMI Flag Register : DNMIR (DMA-halt by NMI Register)	331
4.8.	DMA Transfer Suppression Level Register : DILVR (DMA-halt by Interrupt Level Register)	332
5.	Operation	334
5.1.	DMA Operation Enable	335
5.2.	Separate Items for Each Channel	336
5.3.	Operations	340
6.	DMA Usage Examples	352

CHAPTER 9: GENERATION AND CLEARING OF DMA TRANSFER REQUESTS	355
1. Overview	356
2. Features	357
3. Configuration.....	358
4. Registers	359
4.1. DMA Request Clear Register 0 : ICSEL0 (Interrupt Clear SElect register 0)	361
4.2. DMA Request Clear Register 1 : ICSEL1 (Interrupt Clear SElect register 1)	362
4.3. DMA Request Clear Register 2 : ICSEL2 (Interrupt Clear SElect register 2)	363
4.4. DMA Request Clear Register 3 : ICSEL3 (Interrupt Clear SElect register 3)	364
4.5. DMA Request Clear Register 4 : ICSEL4 (Interrupt Clear SElect register 4)	365
4.6. DMA Request Clear Register 5 : ICSEL5 (Interrupt Clear SElect register 5)	366
4.7. DMA Request Clear Register 6 : ICSEL6 (Interrupt Clear SElect register 6)	367
4.8. DMA Request Clear Register 7 : ICSEL7 (Interrupt Clear SElect register 7)	368
4.9. DMA Request Clear Register 8 : ICSEL8 (Interrupt Clear SElect register 8)	369
4.10. DMA Request Clear Register 9 : ICSEL9 (Interrupt Clear SElect register 9)	370
4.11. DMA Request Clear Register 10 : ICSEL10 (Interrupt Clear SElect register 10)	371
4.12. DMA Request Clear Register 11 : ICSEL11 (Interrupt Clear SElect register 11)	372
4.13. DMA Request Clear Register 12 : ICSEL12 (Interrupt Clear SElect register 12)	373
4.14. DMA Request Clear Register 13 : ICSEL13 (Interrupt Clear SElect register 13)	374
4.15. DMA Request Clear Register 14 : ICSEL14 (Interrupt Clear SElect register 14)	375
4.16. DMA Request Clear Register 15 to 18 : ICSEL15 to 18 (Interrupt Clear SElect register 15 to 18)	376
4.17. DMA Request Clear Register 19 : ICSEL19 (Interrupt Clear SElect register 19)	377
4.18. DMA Request Clear Register 20 : ICSEL20 (Interrupt Clear SElect register 20)	378
4.19. DMA Request Clear Register 21 : ICSEL21 (Interrupt Clear SElect register 21)	379
4.20. DMA Request Clear Register 22 : ICSEL22 (Interrupt Clear SElect register 22)	380
4.21. IO Transfer Request Setting Register 0 to 15 : IORR0 to 15 (IO triggered DMA Request Register for ch. 0 to 15).....	381
5. Operation	384
5.1. Configuration	385
5.2. Notes	386
 CHAPTER:10 FIXEDVECTOR FUNCTION	 387
1. Overview	388
2. Operation Explanation	389
 CHAPTER:11 I/O PORTS	 391
1. Overview.....	392
2. Features.....	393
3. Configuration	394
4. Registers.....	395
4.1. Port Data Register 00 to 13, A to H : PDR00 to PDR13, PDRA to PDRH (Port Data Register 00-13,A-H).....	398
4.2. Data Direction Register 00 to 13, A to H : DDR00 to DDR13, DDRA to DDRH (Data Direction Register 00-13,A-H)	400
4.3. Port Function Register 00 to 13, A to H : PFR00 to PFR13, PFRA to PFRH (Port Function Register 00-13,A-H)	402
4.4. Input Data Direct Register 00 to 13, A to H : PDDR00 to PDDR13, PDDRA to PDDRH (Port Data Direct Register 00-13,A-H)	404
4.5. Port Pull-up/down Control Register 00 to 13, A to H : PPCR00 to PPCR13, PPCRA to PPCRH (Port Pull-up/down Control Register 00-13,A-H)	406

4.6.	Port Pull-up/down Enable Register 00 to 13, A to H : PPER00 to PPER13, PPERA to PPERH (Port Pull-up/down Enable Register 00-13,A-H).....	408
4.7.	Port Input Level selection Register 00 to 13, A to H : PILR00 to PILR13, PILRA to PILRH (Port Input Level Register 00-13, A-H).....	410
4.8.	Extended Port Input Level selection Register 06 to 13 : EPILR06 to EPILR13 (Extended Port Input Level Register 06-13).....	412
4.9.	Port Output Drive Register 06 to 13 : PODR06 to PODR13 (Port Output Drive Register 06-13).....	413
4.10.	Extended Port Output Drive Register 06 to 08 : EPODR06 to EPODR08 (Extended Port Output Drive Register 06-08).....	415
4.11.	Extended Port Output Drive Register for Graphic Digital Interface: EPODRGD.....	416
4.12.	Extended Port Output Drive Register for Graphic Flash Interface: EPODRGF.....	417
4.13.	Extended Port Function Register 00 to 55 : EPFR00 to EPFR55 (Extended Port Function Register 00-55).....	419
4.13.1.	Extended Port Function Register 00, 01 : EPFR00, EPFR01 (Extended Port Function Register 00, 01).....	420
4.13.2.	Extended Port Function Register 02 to 05 : EPFR02 to EPFR05 (Extended Port Function Register 02-05).....	421
4.13.3.	Extended Port Function Register 06 to 09, 33, 34 : EPFR06 to EPFR09, EPFR33, EPFR34 (Extended Port Function Register 06-09,33,34).....	423
4.13.4.	Extended Port Function Register 10 to 15, 45, 46 : EPFR10 to EPFR15, EPFR45, EPFR46 (Extended Port Function Register 10-15,45,46).....	426
4.13.5.	Extended Port Function Register 21 to 23 : EPFR21 to EPFR23 (Extended Port Function Register 21-23).....	429
4.13.6.	Extended Port Function Register 24 : EPFR24 (Extended Port Function Register 24).....	430
4.13.7.	Extended Port Function Register 25 : EPFR25 (Extended Port Function Register 25).....	431
4.13.8.	Extended Port Function Register 26 : EPFR26 (Extended Port Function Register 26).....	432
4.13.9.	Extended Port Function Register 27, 30 : EPFR27, EPFR30 (Extended Port Function Register 27,30).....	433
4.13.10.	Extended Port Function Register 28 : EPFR28 (Extended Port Function Register 28).....	434
4.13.11.	Extended Port Function Register 29 : EPFR29 (Extended Port Function Register 29).....	435
4.13.12.	Extended Port Function Register 35, 36 : EPFR35, EPFR36 (Extended Port Function Register 35,36).....	436
4.13.13.	Extended Port Function Register 48 to 50 : EPFR48 to EPFR50 (Extended Port Function Register 48-50).....	438
4.13.14.	Extended Port Function Register 51, 52 : EPFR51, EPFR52 (Extended Port Function Register 51,52).....	440
4.13.15.	Extended Port Function Register 55 : EPFR55 (Extended Port Function Register 55).....	441
4.13.16.	Extended Port Function Register 16 to 20, 31, 32, 37 to 44, 47, 53, 54 : EPFR16 to EPFR20, EPFR31, EPFR32, EPFR37 to EPFR44, EPFR 47, EPFR53, EPFR54(Extended Port Function Register 16-20, 31, 32, 37-44, 47, 53, 54).....	442
4.14.	Port Input Enable Register : PORTEN(PORT ENable register).....	446
5.	Operation.....	447
5.1.	Pin I/O Assignment.....	448
5.1.1.	Peripheral I/O (bidirectional) Pin Assignment.....	449
5.1.2.	Peripheral Input Assignment.....	450
5.1.3.	Peripheral Output Assignment.....	451
5.1.4.	External Bus Assignment.....	452
5.1.5.	Port Function (Input) Assignment.....	453
5.1.6.	Port Function (Output) Assignment.....	454
5.1.7.	AD Converter Input Assignment.....	455
5.2.	EPFR Setting Priority.....	456

5.3.	Notes on Input I/O Relocation Setting	457
5.4.	Input Interception by GPORTEN	458
5.5.	Notes on Pins with the AD Converter Function	459
5.6.	Setting when Using the Base Timer TIOA1 Pin	460
5.7.	Operation at Wake Up from Power Shutdown	461
5.8.	Notes on switching the port function	462
CHAPTER 12: INTERRUPT CONTROL (INTERRUPT CONTROLLER)		463
1.	Overview	464
2.	Features	465
3.	Configuration	466
4.	Registers	467
4.1.	Interrupt Control Registers 00 to 47 : ICR00 to ICR47 (Interrupt Control Register 00 to 47):	468
5.	Operation	469
CHAPTER 13: EXTERNAL INTERRUPT INPUT		471
1.	Overview	472
2.	Features	473
3.	Configuration	474
4.	Registers	475
4.1.	External Interrupt Factor Register 0/1 : EIRR0/EIRR1 (External Interrupt Request Register 0/1)	476
4.2.	External Interrupt Enable Register 0/1 : ENIR0/ENIR1 (ENable Interrupt request Register 0/1)	477
4.3.	External Interrupt Request Level Register 0/1 : ELVR0/ELVR1 (External interrupt LeVel Register 0/1)	478
5.	Operation	479
6.	Setting	481
7.	Q&A	482
8.	Notes	483
CHAPTER 14: NMI INPUT		485
1.	Overview	486
2.	Features	487
3.	Configuration	488
4.	Register	489
5.	Operation	490
6.	Usage Example	491
CHAPTER 15: DELAY INTERRUPT		493
1.	Overview	494

2.	Features	495
3.	Configuration.....	496
4.	Registers	497
5.	Operation	498
6.	Restrictions	499
CHAPTER 16: INTERRUPT REQUEST BATCH READ		501
1.	Overview	502
2.	Features	503
3.	Configuration.....	504
4.	Registers	505
4.1.	Interrupt Request Batch Read Register 0 upper-order : IRPR0H (Interrupt Request Peripheral Read register 0H)	507
4.2.	Interrupt Request Batch Read Register 0 lower-order : IRPR0L (Interrupt Request Peripheral Read register 0L)	508
4.3.	Interrupt Request Batch Read Register 1 upper-order : IRPR1H (Interrupt Request Peripheral Read register 1H)	509
4.4.	Interrupt Request Batch Read Register 1 lower-order : IRPR1L (Interrupt Request Peripheral Read register 1L)	510
4.5.	Interrupt Request Batch Read Register 2 upper-order : IRPR2H (Interrupt Request Peripheral Read register 2H)	511
4.6.	Interrupt Request Batch Read Register 2 lower-order : IRPR2L (Interrupt Request Peripheral Read register 2L)	512
4.7.	Interrupt Request Batch Read Register 3 upper-order : IRPR3H (Interrupt Request Peripheral Read register 3H)	513
4.8.	Interrupt Request Batch Read Register 3 lower-order : IRPR3L (Interrupt Request Peripheral Read register 3L)	514
4.9.	Interrupt Request Batch Read Register 4 upper-order : IRPR4H (Interrupt Request Peripheral Read register 4H)	515
4.10.	Interrupt Request Batch Read Register 4 lower-order : IRPR4L (Interrupt Request Peripheral Read register 4L)	516
4.11.	Interrupt Request Batch Read Register 5 upper-order : IRPR5H (Interrupt Request Peripheral Read register 5H)	517
4.12.	Interrupt Request Batch Read Register 5 lower-order : IRPR5L (Interrupt Request Peripheral Read register 5L)	518
4.13.	Interrupt Request Batch Read Register 6 upper-order : IRPR6H (Interrupt Request Peripheral Read register 6H)	519
4.14.	Interrupt Request Batch Read Register 6 lower-order : IRPR6L (Interrupt Request Peripheral Read register 6L)	520
4.15.	Interrupt Request Batch Read Register 7 upper-order : IRPR7H (Interrupt Request Peripheral Read register 7H)	521
4.16.	Interrupt Request Batch Read Register 7 lower-order : IRPR7L (Interrupt Request Peripheral Read register 7L)	522
4.17.	Interrupt Request Batch Read Register 8 upper-order : IRPR8H (Interrupt Request Peripheral Read register 8H)	523
4.18.	Interrupt Request Batch Read Register 8 lower-order : IRPR8L (Interrupt Request Peripheral Read register 8L)	524
4.19.	Interrupt Request Batch Read Register 9 upper-order : IRPR9H (Interrupt Request Peripheral Read register 9H)	525
4.20.	Interrupt Request Batch Read Register 9 lower-order : IRPR9L (Interrupt Request Peripheral Read register 9L)	526
4.21.	Interrupt Request Batch Read Register 12 upper-order : IRPR12H (Interrupt Request Peripheral Read register 12H)	527

4.22.	Interrupt Request Batch Read Register 12 lower-order : IRPR12L (Interrupt Request Peripheral Read register 12L)	528
4.23.	Interrupt Request Batch Read Register 13 upper-order : IRPR13H (Interrupt Request Peripheral Read register 13H)	529
4.24.	Interrupt Request Batch Read Register 13 lower-order : IRPR13L (Interrupt Request Peripheral Read register 13L)	530
4.25.	Interrupt Request Batch Read Register 14 upper-order : IRPR14H (Interrupt Request Peripheral Read register 14H)	531
4.26.	Interrupt Request Batch Read Register 14 lower-order : IRPR14L (Interrupt Request Peripheral Read register 14L)	532
4.27.	Interrupt Request Batch Read Register 15 upper-order : IRPR15H (Interrupt Request Peripheral Read register 15H)	533
5.	Operation	534
 CHAPTER 17: PPG		 535
1.	Overview	536
2.	Features	537
3.	Configuration.....	538
4.	Registers	539
4.1.	PPG Cycle Setting Register : PCSR	543
4.2.	PPG Duty Setting Register : PDUT	544
4.3.	PPG Control Status Register : PCN	545
4.4.	General Control Register 10-13 : GCN10 to GCN13	548
4.5.	General Control Register 14, 15 : GCN14, GCN15	550
4.6.	General Control Register 20-25 : GCN20 to GCN25	551
4.7.	PPG Timer Register : PTMR	552
4.8.	PPG0 Output Division Setting Register : PPGDIV	553
5.	Operation	554
5.1.	PWM Operation	555
5.2.	One-shot Operation	557
5.3.	Restart Operation	559
6.	Setting	560
7.	Q&A.....	562
7.1.	How to Set (Rewrite) Cycle and Duty Values	563
7.2.	How to Enable/Stop PPG Operation?	564
7.3.	How to Set PPG Operation Mode (PWM/One-shot)	565
7.4.	How to Restart	566
7.5.	Type and Selection of Count Clock	567
7.6.	How to Fix the PPG Pin Output Level	568
7.7.	Type and Selection of Activation Trigger	569
7.8.	How to Reverse the Output Polarity	571
7.9.	How to Change a Pin to a PPG Output Pin	572
7.10.	How to Generate Activation Trigger	573
7.11.	How to Stop PPG Operation	574
7.12.	Interrupt-related Registers	575
7.13.	Type and Selection of Interrupts	576
7.14.	How to Enable/Disable/Clear Interrupt	577
8.	Sample Programs	578
9.	Notes	582

CHAPTER 18: WATCHDOG TIMER	583
1. Overview	584
2. Features	585
3. Configuration.....	586
4. Registers	587
4.1. Watchdog Control Register 0 : WDTCR0 (WatchDog Timer Configuration Register 0)...	588
4.2. Watchdog Timer 0 Clear Register : WDTCPR0 (WatchDog Timer Clear Pattern Register 0)	590
4.3. Watchdog Timer 1 Cycle information Register : WDTCR1 (WatchDog Timer Cycle information Register 1)	591
4.4. Watchdog Timer 1 Clear Register : WDTCPR1 (WatchDog Timer Clear Pattern Register 1)	592
5. Operation	593
6. Usage Example.....	595
CHAPTER 19: BASE TIMER.....	597
1. Overview	598
2. Features	599
2.1. 16/32-bit Reload Timer	600
2.2. 16-bit PWM Timer	601
2.3. 16/32-bit PWC Timer	602
2.4. 16-bit PPG Timer	603
3. Configuration.....	604
4. Registers	605
4.1. Common Registers.....	607
4.1.1. Timer Registers 0, 1 : BTxTMR (Base Timer 0/1 TiMer Register)	608
4.1.2. Timer Control Registers 0, 1 : BTxTMCR (Base Timer 0/1 TiMer Control Register)	609
4.1.3. I/O Selection Register : BTSEL01 (Base Timer SElect register ch.0 and ch.1)	614
4.1.4. Simultaneous Software Activation Register : BTSSSR (Base Timer Software Synchronous Start Register).....	615
4.2. Registers for 16/32-bit Reload Timer.....	616
4.2.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control).....	617
4.2.2. Cycle Setting Registers 0, 1 : BTxPCSR (Base Timer 0/1 Pulse Counter Start Register)	618
4.3. Registers for 16-bit PWM Timer	619
4.3.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control).....	620
4.3.2. Cycle Setting Registers 0, 1 : BTxPCSR (Base Timer 0/1 Pulse Counter Start Register)	622
4.3.3. Duty Setting Registers 0, 1 : BTxPDUT (Base Timer 0/1 Pulse DuTy register)	623
4.4. Registers for 16-bit PPG Timer	624
4.4.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control).....	625
4.4.2. L Width Setting Registers 0, 1 : BTxPRL (Base Timer 0/1 Pulse Length of "L" register)	626
4.4.3. H Width Setting Registers 0, 1 : BTxPRLH (Base Timer 0/1 Pulse Length of "H" register)	627
4.5. 16/32-bit PWC Timer Register.....	628
4.5.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control).....	629
4.5.2. Data Buffer Registers 0, 1 : BTxDTB (Base Timer 0/1 DaTa BuFfer register)	631
5. Operation	632
5.1. Selection of Timer Function	633
5.2. I/O Allocation	634
5.3. 32-bit Mode Operation.....	637

5.3.1.	32-bit Mode Function	638
5.3.2.	32-bit Mode Setting	639
5.3.3.	32-bit Mode Operation	640
5.4.	16/32-bit Reload Timer Operation	641
5.4.1.	Overview	643
5.4.2.	Operation in Reload Mode	644
5.4.3.	Operation in One-Shot Mode	647
5.4.4.	32-bit Timer Mode Operation	649
5.4.5.	Interrupts	651
5.4.6.	Precautions for Using this Device	652
5.5.	16-bit PWM Timer Operation	653
5.5.1.	Overview	654
5.5.2.	Operation in Reload Mode	655
5.5.3.	Operation in One-Shot Mode	659
5.5.4.	Interrupt	661
5.5.5.	Precautions for Using this Device	662
5.6.	16-bit PPG Timer Operation	663
5.6.1.	Overview	664
5.6.2.	Pulse Width Calculation Method	665
5.6.3.	Operation in Reload Mode	666
5.6.4.	Operation in One-Shot Mode	670
5.6.5.	Interrupts	673
5.6.6.	Application Notes	674
5.7.	16/32-bit PWC Timer Operation	675
5.7.1.	Overview	677
5.7.2.	Operation during PWC Measurement	681
5.7.3.	32-bit Timer Mode Operation	684
5.7.4.	Interrupt	686
5.7.5.	Application Notes	687

CHAPTER 20: RELOAD TIMER

1.	Overview	690
2.	Features	691
3.	Configuration	692
4.	Registers	693
4.1.	Control Status Register : TMCSR (TiMer Control and Status Register)	694
4.2.	16-bit Timer Register : TMR (16bit TiMer Register)	698
4.3.	16-bit Timer Reload Register A, 16-bit Timer Reload Register B : TMRLRA, TMRLRB(16bit TiMer ReLoad Register A/B)	699
5.	Operation	701
5.1.	Setting	702
5.1.1.	Count Source	703
5.1.2.	Timer Underflow period	704
5.1.3.	Trigger	705
5.1.4.	Gate	706
5.1.5.	Counter Operation Selection	707
5.1.6.	TOUT Pin Level Setting	708
5.2.	Operation Procedure	710
5.2.1.	Activation	711
5.2.2.	Retrigger	713
5.2.3.	Underflow/Reload	715
5.2.4.	Generation of Interrupt Requests	716
5.2.5.	Concurrent Operation of Register Write and a Timer Activation	717
5.3.	Operations of Each Counter	718
5.3.1.	Single One-shot Operation	719

5.3.2.	Single Reload Operation.....	721
5.3.3.	Dual One-shot Operation.....	723
5.3.4.	Dual Reload Operation	725
5.3.5.	Compare One-shot Operation	727
5.3.6.	Compare Reload Operation.....	730
5.3.7.	Capture Mode	733
5.4.	Cascade Input	736
5.5.	Priority of Concurrent Operations.....	737
6.	Application Note.....	738
6.1.	Single One-shot Timer.....	740
6.2.	Reload Timer	743
6.3.	PPG	746
6.4.	PWM.....	750
6.5.	PWC	753
CHAPTER 21: FREE-RUN TIMER.....	755	
1.	Overview	756
2.	Features	757
3.	Configuration.....	758
4.	Registers	759
4.1.	Timer Control Register (Upper Bit) : TCCSH	760
4.2.	Timer Control Register (Lower Bit) : TCCSL	762
4.3.	Compare Clear Register : CPCLR	764
4.4.	Timer Data Register : TCDT	765
5.	Operation	766
5.1.	Count Operation of the Free-run Timer	767
5.2.	Counting Up.....	768
5.3.	Timer Clear	769
5.4.	Each Clear Operations of the Free-run Timer	770
5.5.	Timer Interrupt	771
6.	Setting	772
7.	Q&A.....	773
7.1.	How to Select Internal Clock Dividers	774
7.2.	How to Select the External Clock	775
7.3.	How to Enable/Disable the Count Operation of the Free-run Timer	776
7.4.	How to Clear the Free-run Timer.....	777
7.5.	About Interrupt Related Registers	778
7.6.	How to Enable Compare Clear Interrupt	779
7.7.	How to Stop the Free-run Timer Operation	780
8.	Sample Program	781
9.	Notes	782
CHAPTER 22: OUTPUT COMPARE	783	
1.	Overview	784
2.	Features	785
3.	Configuration Diagram	786
4.	Registers	787
4.1.	Free-run Timer Selection Register : OCFS	788
4.2.	Output Control Register (Upper Bit) : OCSH.....	789

4.3. Output Control Register (Lower Bit) : OCSL	791
4.4. Compare Register : OCCP	793
5. Operation	794
5.1. Output Compare Output (Independent Invert) CMOD = "0"	795
5.2. Output Compare Output (Coordinated Invert) CMOD = "1"	796
5.3. Output Compare Operation Timing	797
5.3.1. Compare Register Write.....	798
5.3.2. Compare match, Interrupt	799
5.3.3. Pin Output	800
6. Setting	801
7. Q&A.....	802
7.1. How Can I Set the Compare Value?	803
7.2. How Can I Set the Compare Mode? (Example with OCU1)	804
7.3. How Can I Enable/Disable the Compare Operation? (Example with OCU0, OCU1)	805
7.4. How Can I Set the Compare Pin Output Initial Level? (Example with OCU0, OCU1)	806
7.5. How Can I Set the Compare Pin OCU0, OCU1 for Output?	807
7.6. How Can I Clear the Free-run Timer?	808
7.7. How Can I Enable the Compare Operation?.....	809
7.8. Interrupt Related Register?	810
7.9. Interrupt Type?	811
7.10. How Can I Enable the Interrupt?	812
7.11. Calculation Method for the Compare Value?	813
7.11.1. Toggle Output Pulse	814
7.11.2. PWM Output.....	815
8. Sample Program	816
9. Notes	818
CHAPTER 23: INPUT CAPTURE	819
1. Overview	820
2. Features	821
3. Configuration.....	822
4. Registers	823
4.1. Input Capture Data Register : IPCP	825
4.2. Free-run Timer Selection Register : ICFS	826
4.3. Input Capture Control Register : ICS.....	828
4.4. LIN SYNCH FIELD Switching Register : LSYNS	830
5. Operation	832
5.1. Capture and Interrupt Timings.....	833
5.2. Edge Detection Specifications for Input Capture And Their Operations	834
6. Setting	836
7. Q&A.....	837
7.1. Effective Edge Polarity of External Input: Types and How to Select.....	838
7.2. How to Enable External Input Pins (ICU0, ICU1, ICU2, ICU3, ICU4, ICU5).....	839
7.3. About Interrupt Related Registers	840
7.4. About Interrupt Types	841
7.5. How to Enable Interrupt.....	842
7.6. How to Measure the Pulse Width of the Input Signal.....	843
8. Sample Program	844
9. Notes	845

CHAPTER 24: REAL-TIME CLOCK(RTC)	847
1. Overview	848
2. Features	849
3. Configuration.....	850
4. Registers	851
4.1. RTC Control Register : WTCR	852
4.2. Sub-second Register : WTBR	857
4.3. Day/Hour/Minute/Second Register : WTDR/ WTHR/WTMR/ WTSR	858
5. Operation	860
6. Setting	862
7. Q&A.....	863
7.1. How to Set the 0.5 Second Count Interval?	864
7.2. How to Initialize the Real-time Clock?.....	865
7.3. How to Set/Update Number of Days (Day) and Time (Hour/Minute/Second)?	866
7.4. How to Start/Stop the Count of the Real-time Clock?	867
7.5. How to Confirm That the Real-time Clock Is Running?.....	868
7.6. How to Know the Number of Days and Time?	869
7.7. How to Stop the Real-time Clock?	870
7.8. How to Calibrate the Real-time Clock?	871
7.9. What Are Interrupt Related Registers?	872
7.10. What Are the Interrupt Types and How to Select Them?	873
7.11. How to Enable Interrupts?	874
8. Sample Program	875
9. Notes	876
CHAPTER 25: RTC/WDT1 CALIBRATION	877
1. Overview	878
2. Features	879
3. Configuration.....	880
4. Registers	881
4.1. Calibration Unit Control Register 0 : CUCR0 (Calibration Unit Control Register 0)	882
4.2. Sub Clock Timer Data Register : CUTD0 (Calibration Unit Timer Data register 0)	883
4.3. Main Oscillation Timer Result Register 0 : CUTR0 (Calibration Unit Timer Result register 0)	884
4.4. Calibration Unit Control Register 1 : CUCR1 (Calibration Unit Control Register 1)	885
4.5. CR Clock Timer Data Register : CUTD1 (Calibration Unit Timer Data register 1)	886
4.6. Main Oscillation Timer Result Register 1 : CUTR1 (Calibration Unit Timer Result register 1)	887
4.7. CR Oscillation Trimming Setting Register : CRTR (CR oscillator calibration Trimming Register)	888
5. Operation	889
5.1. Real-Time Clock (RTC) Calibration	890
5.2. WDT1 Calibration (CR Clock Calibration)	891
5.3. Notes	892
CHAPTER 26: POWER CONSUMPTION CONTROL	893

1. Overview	894
2. Features	895
3. Configuration.....	896
4. Registers	898
4.1. Standby Control Register : STBCR (STandby mode Control Register)	899
4.2. PMU Control Register : PMUCTLR (Power Management Unit ConTroL register).....	901
4.3. PoWeR on TiMing Control Register : PWRTMCTL (PoWeR on TiMing ConTroL register).....	902
4.4. PMU Interrupt Flag Register 0 : PMUINTF0 (Power Management Unit INTerrupt Flag0 register)	903
4.5. PMU Interrupt Flag Register 1 : PMUINTF1 (Power Management Unit INTerrupt Flag1 register)	904
4.6. PMU Interrupt Flag Register 2 : PMUINTF2 (Power Management Unit INTerrupt Flag2 register)	905
4.7. GDC Status Register : GSTR (Gdc Status Register)	907
4.8. GDC Control Register : GCTLR (Gdc ConTroL Register).....	908
5. Operation	909
5.1. Clock Control	910
5.2. List of Clock Supply in Low-power Consumption Mode.....	911
5.3. Sleep Mode	912
5.4. Standby Mode : Watch Mode	914
5.5. Standby Mode : Watch Mode with power-shutdown	916
5.6. Standby Mode : Stop Mode	919
5.7. Standby Mode : Stop Mode with power-shutdown	921
5.8. Stop State of Microcontroller	925
5.9. Power-shutdown GDC Unit	926
5.10. Transition to Illegal Standby Mode	928
5.11. GDC Regulator	929
5.12. Restrictions on Power Shutdown and Normal Standby Control	930
6. Example of Use.....	933

CHAPTER 27: LOW VOLTAGE DETECTION (INTERNAL LOW-VOLTAGE DETECTION) 935

1. Overview	936
2. Features	937
3. Configuration.....	938
4. Registers	939
4.1. Microcontroller Unit Internal Low Voltage Detection Register : LVD (Low Voltage Detect internal power fall register)	940
4.2. GDC Unit Internal Low Voltage Detection Register : GLVD (Gdc Low Voltage Detect internal power fall register).....	942
5. Operation	944
5.1. Internal Low-voltage Detection in Microcontroller Unit.....	945
5.2. Internal Low-voltage Detection in GDC unit	946
6. Notes.....	947

CHAPTER 28: LOW VOLTAGE DETECTION (EXTERNAL LOW-VOLTAGE DETECTION) 949

1. Overview	950
2. Features	951

3. Configuration.....	952
4. Registers.....	953
4.1. Microcontroller Unit External Low Voltage Detection Rise Detection Register : LVD5R (Low Voltage Detect external 5v Rise register).....	954
4.2. Microcontroller Unit External Low Voltage Detection Fall Detection Register : LVD5F (Low Voltage Detect external 5v Fall register).....	955
4.3. GDC Unit External Low Voltage Detection Rise Detection Register : GLVD5R (Gdc Low Voltage Detect external 5v Rise Register).....	957
4.4. GDC Unit External Low Voltage Detection Fall Detection Register : GLVD5F (Gdc Low Voltage Detect external 5v Fall Register).....	959
5. Operation.....	961
5.1. Microcontroller Unit External Low Voltage Detection.....	962
5.2. GDC Unit External Low Voltage Detection.....	963
6. Notes.....	964
CHAPTER 29: WILD REGISTER.....	965
1. Overview.....	966
2. Features.....	967
3. Configuration.....	968
4. Registers.....	969
4.1. Wild Register Data Enable Register : WREN (Wild Register data ENable register).....	971
4.2. Wild Register Address Register 00 to 15 : WRAR00 to 15 (Wild Register Address Register 00 to 15).....	972
4.3. Wild Register Data Register 00 to 15 : WRDR00 to 15 (Wild Register Data Register 00 to 15).....	973
5. Operation.....	974
6. Usage Example.....	975
CHAPTER 30: CLOCK SUPERVISOR.....	977
1. Overview.....	978
2. Configuration.....	979
3. Register.....	980
4. Operation.....	983
4.1. Initial State.....	984
4.2. Stopping CR Oscillator and the Clock Supervisor Function.....	985
4.3. Re-enabling the Clock Supervisor.....	986
4.4. Sub Clock Mode.....	987
4.5. Stop Mode.....	988
4.6. Watch Mode.....	989
4.7. Checking the Reset Factor Using the Clock Supervisor.....	990
4.8. Return from CR Clock.....	991
CHAPTER 31: SOUND GENERATOR.....	993
1. Overview.....	994
2. Features.....	995
3. Configuration.....	996

4.	Registers	997
4.1.	DMA Transfer Update Enable Register : SGDER (SG DMA Enable Register)	999
4.2.	Sound Control Register : SGCR (SG Control Register)	1001
4.3.	Amplitude Data Register : SGAR (SG Amplitude Register)	1004
4.4.	Frequency Data Register : SGFR (SG Frequency Register)	1005
4.5.	Tone Outputs Number Register : SGNR (SG tone Number Register)	1006
4.6.	Cycle Register : SGTCCR (SG Tone Cycle Register)	1007
4.7.	Increment Decrement Data Register : SGIDR (SG Increment Decrement Register)	1008
4.8.	PWM Cycles Number Data Register : SGPCR (SG PWM Cycle Register)	1009
4.9.	DMA Transfer Indirect Register : SGDMAR (SG DMA Register)	1010
5.	Operation	1011
5.1.	Relation of Amplitude Data Register (SGAR) and PWM Pulse	1012
5.2.	Relation of Frequency Data Register (SGFR) and Tone Pulse Signals	1013
5.3.	Relation of PWM Cycles Number Data Register (SGPCR) and PWM cycle	1014
5.4.	Relation of DMA Transfer Update Enable Register (SGDER) and DMA Transfers Count/DMA Transfer Size/Transfer Byte Location	1015
5.4.1.	DMA Transfers Count	1016
5.4.2.	DMA Transfer Size	1017
5.4.3.	Transfer Byte Location for DMA Transfer Indirect Register	1018
5.4.4.	DMA Transfer Image	1021
5.5.	Operation of Sound Generator	1022
5.6.	Sound Generator Continuous Operation by CPU	1024
5.7.	Sound Generator Operation Coordinated with DMA	1026
5.8.	When DMA Transfer of 4 Bytes × 2 Is Performed N Times	1027
5.8.1.	When DMA Transfer of 2 Bytes × 2 Is Performed N Times	1030
5.8.2.	When DMA Transfer of 1 Byte × 1 Is Performed N Times	1033
5.8.3.	For DMA Transfer of 4 Bytes × 2 N Times and DMA Transfer of 2 Bytes × 1 M Times (Transfer Bytes Number Change During Sound Output)	1036
5.8.4.	For DMA Transfer of 4 Bytes × 2 N Times and DMA Transfer of 4 Bytes × 2 M Times (Transfer Bytes Number and Increment Decrement Setting Change During Sound Output)	1039
 CHAPTER 32: STEPPING MOTOR CONTROLLER		1043
1.	Overview	1044
2.	Features	1045
3.	Configuration	1046
4.	Registers	1047
4.1.	PWM Control Register : PWC	1049
4.2.	PWM1&2 Compare Register : PWC1/PWC2	1051
4.3.	PWM1 Selection Register : PWS1	1052
4.4.	PWM2 Selection Register : PWS2	1053
5.	Operation	1055
5.1.	PWM Operation	1056
5.2.	PWM Compare Register Loading with The BS bit	1057
5.3.	Selection of Motor Drive Signals	1059
6.	Setting	1060
7.	Q&A	1061
7.1.	How to Set Cycle and Duty	1062
7.2.	How to Enable/Stop PWM Operation	1063
7.3.	How to Reflect the Duty Change	1064
7.4.	Type and Selection of Operating Clock	1065
7.5.	How to Change the Motor Drive Signals	1066
7.6.	How to Assign a Pin as a PWM Output Pin	1067
7.7.	How to Assign a Pin as an A/D Converter Analog Input Pin	1068

8. Sample Programs	1069
9. Notes	1070
CHAPTER 33: REGULATOR CONTROL	1071
1. Overview	1072
2. Features	1073
3. Configuration	1074
4. Register	1075
4.1. Regulator Output Voltage Select Register : REGSEL (REGulator output voltage SElect register)	1076
5. Operation	1078
CHAPTER 34: BUS PERFORMANCE COUNTERS	1079
1. Overview	1080
2. Features	1081
3. Configuration	1082
4. Registers	1083
4.1. BPC-A Control Register : BPCCRA (Bus Performance Counter Control Register A)	1084
4.2. BPC-B Control Register : BPCCRB (Bus Performance Counter Control Register B)	1086
4.3. BPC-C Control Register : BPCCRC (Bus Performance Counter Control Register C)	1087
4.4. BPC-A Count Register : BPCTRA (Bus Performance CounTer Register A)	1088
4.5. BPC-B Count Register : BPCTRB (Bus Performance CounTer Register B)	1089
4.6. BPC-C Count Register : BPCTRC (Bus Performance CounTer Register C)	1090
5. Operations	1091
5.1. Setting	1092
5.2. Starting and Stopping	1094
5.3. Operation	1095
5.4. Measurement and Result Processing	1096
CHAPTER 35: CRC	1099
1. Overview	1100
2. Features	1101
3. Configuration	1102
4. Registers	1103
4.1. CRC Control Register : CRCCR	1104
4.2. CRC Initial Value Register : CRCINIT	1105
4.3. CRC Input Data Register : CRCIN	1106
4.4. CRC Register : CRCCR	1107
5. Operation	1108
5.1. CRC Definition	1109
5.2. Reset Operation	1110
5.3. Initialization	1111
5.4. Byte and Bit Orders	1112
5.5. CRC Calculation Sequence	1113
5.6. Examples	1114

5.6.1.	Example 1 CRC16, Fixed Byte Input	1115
5.6.2.	Example 2 CRC16, Mixture of Different Input Bit Widths.....	1117
5.6.3.	Example 3 CRC32, Byte Order, Big-endian.....	1118
5.6.4.	Example 4 CRC32, Byte Order, Little-endian	1119
CHAPTER 36: RAMECC	1121	
1.	Overview	1122
2.	Features	1123
3.	Configuration.....	1124
4.	Registers	1126
4.1.	ECC Error Control Register XBS RAM : EECSRX (Ecc Error Control and Status Register Xbs ram).....	1127
4.2.	Single-bit ECC Error Address Register XBS RAM : SEEARX (Single bit Ecc Error Address Register Xbs ram)	1128
4.3.	Double-bit ECC Error Address Register XBS RAM : DEEARX (Double bit Ecc Error Address Register Xbs ram)	1129
4.4.	ECC False Error Generation Address Register XBS RAM : EFEARX (Ecc False Error Address Register Xbs ram).....	1130
4.5.	ECC False Error Generation Control Register XBS RAM : EFECRX (Ecc False Error Control Register Xbs ram).....	1131
4.6.	ECC Error Control Register BACKUP-RAM : EECSRA (Ecc Error Control and Status Register bAckup-ram)	1133
4.7.	Single-bit ECC Error Address Register BACKUP-RAM : SEEARA (Single bit Ecc Error Address Register bAckup-ram).....	1134
4.8.	Double-bit ECC Error Address Register BACKUP-RAM : DEEARA (Double bit Ecc Error Address Register bAckup-ram).....	1135
4.9.	ECC False Error Generation Address Register BACKUP-RAM : EFEARA (Ecc False Error Address Register bAckup-RAM)	1136
4.10.	ECC False Error Generation Control Register BACKUP-RAM : EFECRA (Ecc False Error Control Register bAckup-RAM).....	1137
5.	Operation	1139
5.1.	ECC Generation	1140
5.2.	ECC Inspection.....	1141
5.3.	Interrupt by Error Detection	1142
5.4.	Test Function	1143
CHAPTER 37: MULTI FUNCTION SERIAL INTERFACE	1145	
1.	Overview.....	1146
2.	Features.....	1147
2.1.	UART.....	1148
2.2.	CSIO.....	1149
2.3.	LIN-UART	1150
2.4.	I ² C.....	1151
2.5.	Note.....	1152
3.	Configuration.....	1153
4.	Registers.....	1157
4.1.	Common Registers.....	1159
4.1.1.	Serial Mode Register : SMR.....	1160
4.1.2.	FIFO Control Register 1 : FCR1.....	1163
4.1.3.	FIFO Control Register 0 : FCR0.....	1165
4.1.4.	FIFO BYTE Register : FBYTE.....	1168
4.2.	Registers for UART	1170

4.2.1.	Serial Control Register : SCR	1171
4.2.2.	Serial Status Register : SSR	1173
4.2.3.	Extended Serial Control Register : ESCR.....	1176
4.2.4.	Receive Data Register/Transmit Data Register : RDR/TDR.....	1178
4.2.5.	Baud rate Generator Register : BGR	1180
4.3.	Registers for CSIO	1181
4.3.1.	Serial Control Register : SCR	1182
4.3.2.	Serial Status Register : SSR	1184
4.3.3.	Extended Serial Control Register : ESCR.....	1186
4.3.4.	Receive Data Register/Transmit Data Register : RDR/TDR.....	1187
4.3.5.	Baud rate Generator Register : BGR	1189
4.4.	Registers for LIN-UART.....	1190
4.4.1.	Serial Control Register : SCR	1191
4.4.2.	Serial Status Register : SSR	1193
4.4.3.	Extended Serial Control Register : ESCR.....	1196
4.4.4.	Receive Data Register/Transmit Data Register : RDR/TDR.....	1198
4.4.5.	Baud rate Generator Register : BGR	1200
4.5.	Registers for I ² C	1201
4.5.1.	I ² C Bus Control Register : IBCR	1202
4.5.2.	Serial Status Register : SSR	1207
4.5.3.	I ² C Bus Status Register : IBSR	1210
4.5.4.	Receive Data Register/Transmit Data Register : RDR/TDR.....	1214
4.5.5.	Baud rate Generator Register : BGR	1216
4.5.6.	I ² C 7-bit Slave Address Mask Register : ISMK	1217
4.5.7.	I ² C 7-bit Slave Bus Address Register : ISBA	1218
5.	Operation of UART.....	1219
5.1.	Interrupt of UART	1220
5.1.1.	List of Interrupt of UART	1221
5.1.2.	Reception Interrupts and Flag Setting Timing.....	1222
5.1.3.	Interrupts when Using Reception FIFO and Flag Setting Timing.....	1224
5.1.4.	Transmission Interrupts and Flag Setting Timing.....	1226
5.1.5.	Interrupts When Using Transmission FIFO and Flag Setting Timing.....	1227
5.2.	Operation of UART	1228
5.2.1.	Transmission/Reception Data Format.....	1229
5.2.2.	Transmission Operation	1231
5.2.3.	Reception Operation	1232
5.2.4.	Clock Selection.....	1233
5.2.5.	Start Bit Detection.....	1234
5.2.6.	Stop Bit.....	1235
5.2.7.	Error Detection	1236
5.2.8.	Parity Bit.....	1237
5.2.9.	Data Signaling Method.....	1238
5.2.10.	Data Transfer Method	1239
5.2.11.	UART Baud Rate Selection/Setting	1240
5.3.	Setup Procedure and Program Flow.....	1245
5.3.1.	Operation Mode 0 (One-to-One Connection).....	1246
5.3.2.	Operation Mode 1 (One-to-N Connection).....	1248
6.	Operation of CSIO.....	1251
6.1.	Interrupts of CSIO.....	1252
6.1.1.	List of Interrupts of CSIO.....	1253
6.1.2.	Reception Interrupts and Flag Setting Timing.....	1254
6.1.3.	Interrupts when Using Reception FIFO and Flag Setting Timing.....	1255
6.1.4.	Transmission Interrupts and Flag Setting Timing.....	1257
6.1.5.	Interrupts When Using Transmission FIFO and Flag Setting Timing.....	1258
6.2.	Operation of CSIO	1259
6.2.1.	Normal Transfer (I)	1260
6.2.2.	Normal Transfer (II)	1264
6.2.3.	SPI Transfer (I)	1268

6.2.4.	SPI Transfer (II).....	1272
6.2.5.	Baud Rate Generation	1276
6.3.	Setup Procedure and Program Flow	1278
6.3.1.	Connections between Chips	1279
6.3.2.	Flowchart.....	1280
7.	Operation of LIN-UART.....	1281
7.1.	Interrupts of LIN-UART	1282
7.1.1.	List of Interrupts of LIN-UART Interface.....	1283
7.1.2.	Reception Interrupts and Flag Setting Timing.....	1285
7.1.3.	Interrupts when Using Reception FIFO and Flag Setting Timing.....	1288
7.1.4.	Transmission Interrupts and Flag Setting Timing.....	1290
7.1.5.	Interrupts When Using Transmission FIFO and Flag Setting Timing.....	1291
7.2.	Operation of LIN-UART	1292
7.2.1.	Master Device Operation	1293
7.2.2.	Slave Device Operation	1298
7.2.3.	LIN-UART Baud Rate Selection/Setting.....	1302
7.3.	Setup Procedure and Program Flow	1303
7.3.1.	Inter-CPU Connection	1304
7.3.2.	Flowchart Example.....	1305
8.	Operation of I ² C.....	1309
8.1.	Interrupts of I ² C	1310
8.2.	Operation for I ² C Interface Communication	1312
8.2.1.	I ² C Bus Start Condition.....	1313
8.2.2.	I ² C Bus Stop Condition.....	1314
8.2.3.	I ² C Bus Repeated Start Condition	1315
8.2.4.	I ² C Bus Error	1316
8.2.5.	Baud Rate Generation	1317
8.3.	I ² C Master Mode.....	1319
8.3.1.	Start Condition Generation.....	1320
8.3.2.	Slave Address Output	1321
8.3.3.	Acknowledge Reception by Transmitting First Byte.....	1323
8.3.4.	Data Transmission by Master.....	1329
8.3.5.	Data Reception by Master System.....	1345
8.3.6.	Arbitration Lost	1352
8.3.7.	Wait of the Master Mode	1353
8.3.8.	Repetition Start Condition Issue when DMA Mode Enabled (SSR:DMA=1)	1354
8.4.	I ² C Slave Mode.....	1355
8.4.1.	Detection of Slave Address Matching	1356
8.4.2.	Data Direction Bit	1358
8.4.3.	Reception by Slave Device	1359
8.4.4.	Transmission by Slave Device	1365
8.5.	Bus Error	1366
8.5.1.	Bus Error Generation Condition	1367
8.5.2.	Bus Error Operation	1368
8.6.	Example of I ² C Flowchart	1369
8.6.1.	Example of I ² C Flowchart (FIFO Memory Not Used) (When DMA mode is disable (SSR:DMA=0))	1369
8.6.2.	Example of I ² C Flowchart (FIFO Memory Not Used) (When DMA mode is enable (SSR:DMA=1))	1372
CHAPTER 38: LIN-UART		1377
1.	Overview.....	1378
2.	Features.....	1379
2.1.	Functions	1380
2.2.	Operation Mode.....	1381

3.	Configuration.....	1382
3.1.	Block Diagram of the LIN-UART	1383
3.2.	Explanation of Each Block.....	1385
3.2.1.	Reload Counter	1386
3.2.2.	Reception Control Circuit	1387
3.2.3.	Reception Shift Register	1388
3.2.4.	Reception Data Register (RDR).....	1389
3.2.5.	Transmission Control Circuit	1390
3.2.6.	Transmission Shift Register	1391
3.2.7.	Transmission Data Register (TDR)	1392
3.2.8.	Error Detection Circuit.....	1393
3.2.9.	Over-sampling Circuit.....	1394
3.2.10.	Interrupt Generation Circuit.....	1395
3.2.11.	LIN Synch Break/LIN Synch Field Detection Circuit	1396
3.2.12.	LIN Synch Break Generation Circuit	1397
3.2.13.	Bus Idle Detection Circuit.....	1398
3.2.14.	Serial Mode Register (SMR)	1399
3.2.15.	Serial Control Register (SCR).....	1400
3.2.16.	Serial Status Register (SSR).....	1401
3.2.17.	Extended Status Control Register (ESCR)	1402
3.2.18.	Extended Communication Control Register (ECCR)	1403
4.	Registers.....	1404
4.1.	Serial Control Register : SCR.....	1407
4.2.	Serial Mode Register : SMR.....	1410
4.3.	Serial Status Register :SSR	1413
4.4.	Reception Data Register / Transmission Data Register : RDR / TDR.....	1416
4.4.1.	Reception Data Register : RDR	1417
4.4.2.	Transmission Data Register : TDR.....	1418
4.5.	Extended Status Control Register : ESCR	1419
4.6.	Extended Communication Control Register : ECCR.....	1422
4.7.	Baud Rate Generator Register : BGR	1424
5.	Interrupts.....	1425
5.1.	Overview.....	1426
5.1.1.	Interrupts of LIN-UART.....	1427
5.1.2.	Reception Interrupt.....	1428
5.1.3.	Transmission Interrupt.....	1429
5.1.4.	LIN Synch Break Interrupt.....	1430
5.1.5.	LIN Synch Field Edge Detection Interrupt.....	1431
5.2.	Generation of Reception Interrupt and Flag Setting Timing.....	1432
5.2.1.	Generation of Reception Interrupt and Flag Setting Timing.....	1433
5.3.	Occurrence of Transmission Interrupt and Flag Timing	1435
5.3.1.	Occurrence of Transmission Interrupt and Flag Timing	1436
5.3.2.	Transmission Interrupt Request Generation Timing	1437
6.	Baud Rates.....	1438
6.1.	Selection of Baud Rates	1439
6.1.1.	Baud Rate Obtained when a Dedicated Baud Rate Generator (Reload Counter) Divides the Frequency of the Internal Clock.....	1440
6.1.2.	Baud Rate Obtained when a Dedicated Baud Rate Generator (Reload Counter) Divides the Frequency of the External Clock	1441
6.1.3.	Baud Rate Due from External Clock (One-to-One Mode)	1442
6.2.	Baud Rate Setting	1443
6.2.1.	Baud Rate Calculations.....	1444
6.2.2.	Baud Rate Setting Example for Each Clock Frequency	1445
6.2.3.	Use of the External Clock.....	1447
6.2.4.	Reload Counter Operation	1448
6.3.	Reload Counter	1449
6.3.1.	Reload Counter Functions	1450

6.3.2.	Count Start	1451
6.3.3.	Restart.....	1452
6.3.4.	Counter Clear	1453
6.3.5.	Simple Timer Use.....	1454
7.	Operation.....	1455
7.1.	Overview.....	1456
7.1.1.	Operation Mode	1457
7.1.2.	Connection Method between CPUs.....	1458
7.1.3.	Synchronization System.....	1459
7.1.4.	Signaling System	1460
7.1.5.	Transmission/Reception Start	1461
7.1.6.	Stopping of Transmission/Reception.....	1462
7.1.7.	Stopping of Transmission/Reception in Progress	1463
7.2.	Asynchronous Mode (Operation Modes 0 and 1)	1464
7.2.1.	Transmission/Reception Data Format.....	1465
7.2.2.	Transmission Operation	1466
7.2.3.	Reception Operation	1467
7.2.4.	Clock Usage	1468
7.2.5.	Stop Bit	1469
7.2.6.	Error Detection	1470
7.2.7.	Parity	1471
7.2.8.	Data Signaling Method.....	1472
7.2.9.	Data Transfer Method	1473
7.3.	Synchronous Mode (Operation Mode 2).....	1474
7.3.1.	Transmission/Reception Data Format.....	1475
7.3.2.	Master/Slave Setting	1476
7.3.3.	Sampling Edge Selection	1477
7.3.4.	Clock Supply	1478
7.3.5.	Clock Usage	1479
7.3.6.	Delayed Serial Clock.....	1480
7.3.7.	Sequential Serial Clock	1481
7.3.8.	Parity	1482
7.3.9.	Data Signaling Method.....	1483
7.3.10.	Stop Bit.....	1484
7.3.11.	Error Detection	1485
7.3.12.	Communication Start.....	1486
7.3.13.	Communication End.....	1487
7.3.14.	Data Transfer Method	1488
7.4.	LIN Mode (Operation Mode 3).....	1489
7.4.1.	Transmission/Reception Data Format.....	1490
7.4.2.	LIN Master Operation.....	1491
7.4.3.	LIN Slave Operation	1492
7.4.4.	LIN Bus Timing.....	1493
7.4.5.	Baud Rate Calculation	1494
7.4.6.	Clock Usage	1495
7.4.7.	Data Signaling Method.....	1496
7.4.8.	Stop Bit.....	1497
7.4.9.	Error Detection	1498
7.5.	Direct Access to the Serial Pin	1499
7.6.	Bidirectional Communication Function (Normal Mode).....	1500
7.6.1.	Connection between CPUs.....	1501
7.6.2.	Communication Procedure.....	1502
7.7.	Master/ Slave Mode Communication Function (Multi-processor Mode)	1503
7.7.1.	Connection between CPUs.....	1504
7.7.2.	Function Selection.....	1505
7.7.3.	Communication Procedure.....	1506
7.8.	LIN Communication Function	1508
7.8.1.	LIN Master/Slave Communication Function.....	1509

7.8.2.	LIN Device Connection	1510
7.9.	LIN-UART Sample Flowchart in LIN Communication Mode (Operation Mode 3)	1511
7.9.1.	LIN-UART as a Master Device	1512
7.9.2.	LIN-UART as a Slave Device	1513
8.	Notes on Usage.....	1514
8.1.	Operation Enable	1515
8.2.	Communication Mode Setting	1516
8.3.	Timing of Enabling Transmission Interrupt	1517
8.4.	Operation Setting Change	1518
8.5.	Detection of a LIN Synch Break	1519
8.6.	LIN Slave Setting.....	1520
8.7.	Program Compatibility	1521
8.8.	Address/Data Format Selection Bit (SCR:AD)	1522
8.9.	LIN-UART Software Reset	1523
8.10.	Detection of LIN Synch Field in Input Capture	1524
9.	Notes on DMAC Linkage Operation.....	1525
9.1.	Transmission Operation	1526
9.2.	Reception Operation	1527
 CHAPTER 39: CAN		 1529
1.	Overview.....	1530
2.	Features.....	1531
3.	Configuration.....	1532
4.	Registers.....	1533
4.1.	Overview.....	1534
4.2.	Overall Control Registers	1541
4.2.1.	CAN Control Register (CTRLR)	1542
4.2.2.	CAN Status Register (STATR).....	1545
4.2.3.	CAN Error Counter (ERRCNT)	1548
4.2.4.	CAN Bit Timing Register (BTR).....	1549
4.2.5.	CAN Interrupt Register (INTR)	1550
4.2.6.	CAN Test Register (TESTR)	1552
4.2.7.	CAN Prescaler Extension Register (BRPER)	1554
4.3.	Message Interface Register	1555
4.3.1.	IFx Command Request Register (IFxCREQ).....	1556
4.3.2.	IFx Command Mask Register (IFxCMSK).....	1559
4.3.3.	IFx Mask Registers 1, 2 (IFxMSK1, IFxMSK2)	1563
4.3.4.	IFx Arbitration Registers 1, 2 (IFxARB1, IFxARB2)	1564
4.3.5.	IFx Message Control Register (IFxMCTR).....	1565
4.3.6.	IFx Data Registers A1, A2, B1, B2 (IFxDTA1, IFxDTA2, IFxDTB1, IFxDTB2)	1566
4.4.	Message Object.....	1567
4.4.1.	Configuration of Message Object.....	1568
4.4.2.	Functions of Message Object.....	1569
4.5.	Message Handler Registers	1574
4.5.1.	CAN Transmission Request Registers (TREQR1, TREQR2)	1575
4.5.2.	CAN Data Update Registers (NEWDT1, NEWDT2)	1577
4.5.3.	CAN Interrupt Pending Registers (INTPND1, INTPND2)	1579
4.5.4.	CAN Message Valid Registers (MSGVAL1, MSGVAL2)	1581
4.6.	CAN Prescaler Register (CANPRE).....	1583
5.	Operation.....	1585
5.1.	Message Object.....	1586
5.1.1.	Message Object	1587
5.1.2.	Data Transmission/Reception with Message RAM	1588
5.2.	Message Transmission Operation.....	1589

5.2.1.	Message Transmission	1590
5.2.2.	Transmission Priority	1591
5.2.3.	Transmission Message Object Setting	1592
5.2.4.	Update of Transmission Message Object	1593
5.3.	Message Reception Operation	1594
5.3.1.	Reception Message Acceptance Filter	1595
5.3.2.	Reception Priority	1596
5.3.3.	Data Frame Reception	1597
5.3.4.	Remote Frame	1598
5.3.5.	Reception Message Object Setting	1599
5.3.6.	Reception Message Processing	1600
5.4.	FIFO Buffer Function	1601
5.4.1.	Configuration of FIFO Buffer	1602
5.4.2.	Message Reception by FIFO Buffer	1603
5.4.3.	Reading from FIFO Buffer	1604
5.5.	Interrupt Function	1606
5.6.	Bit Timing and CAN System Clock (fsys) Generation	1607
5.7.	Test Mode	1610
5.7.1.	Test Mode Setting	1611
5.7.2.	Silent Mode	1612
5.7.3.	Loopback Mode	1613
5.7.4.	Combination of Silent and Loopback Modes	1614
5.7.5.	Basic Mode	1615
5.7.6.	Software Control of the CAN_TX Pin	1616
5.8.	Software Initialization	1617

CHAPTER 40: AD CONVERTER.....1619

1.	Overview.....	1620
2.	Features.....	1621
3.	Configuration.....	1622
4.	Registers.....	1623
4.1.	Analog Input Enable Register : ADER.....	1624
4.2.	A/D Control Status Register (Upper) : ADCS1	1625
4.3.	A/D Control Status Register (Lower) : ADCS0	1628
4.4.	Data Register : ADCR0, ADCR1	1631
4.5.	Conversion Time Setting Register : ADCT	1632
4.6.	A/D Start/Completion Channel Setting Register : ADSCH, ADECH.....	1634
5.	Operation.....	1637
5.1.	Single Conversion Operation	1638
5.2.	Scan Conversion Operation	1639
5.3.	Conversion Mode	1640
6.	Setting.....	1642
7.	Q&A.....	1644
7.1.	Conversion Mode Type and Setting Method?	1645
7.2.	How Can I Specify the Bit Length?	1646
7.3.	How Can I Select Channels?	1647
7.4.	How Can I Set the Conversion Time?	1650
7.5.	How Can I Enable the Analog Pin Input?	1651
7.6.	How Can I Select the A/D Converter Activation Method?	1653
7.7.	How Can I Activate the A/D Converter?	1654
7.8.	How Can I Check the Conversion Completion?	1655
7.9.	How Can I Read the Conversion Value?	1656
7.10.	How Can I Stop the A/D Conversion Operation Forcibly?	1657
7.11.	Interrupt-Related Register?	1658

7.12. Interrupt Type?.....	1659
7.13. How Can I Enable/Disable/Clear the Interrupt?	1660
8. Sample Program	1661
9. Notes.....	1664
10. Term Definition for A/D Converter	1665
CHAPTER 41: FLASH MEMORY	1669
1. Overview.....	1670
2. Features.....	1671
3. Configuration.....	1672
3.1. Block Diagram	1673
3.2. Sector Configuration Diagram	1674
3.3. Sector Number and Flash Macro Number Correspondence Chart.....	1676
4. Registers.....	1678
4.1. Flash Control Register : FCTLR (Flash ConTroL Register)	1679
4.2. Flash Status Register : FSTR (Flash STratus Register)	1681
4.3. Flash Interface Control Register : FLIFCTLR(Flash I/F Control Register)	1683
4.4. Flash I/F Feature Extension Register 1: FLIFFER1	1684
4.5. Flash I/F Feature Extension Register 2: FLIFFER2	1685
5. Operation.....	1686
5.1. Access Mode Setting.....	1687
5.1.1. Configuring CPU-ROM Mode	1688
5.1.2. Configuring CPU Programming Mode	1689
5.2. Programming Flash Memory by CPU.....	1690
5.3. Automatic Algorithm.....	1691
5.3.1. Command Sequence	1692
5.3.2. Automatic Algorithm Execution State	1696
5.4. Reset Command.....	1700
5.5. Write Command.....	1701
5.6. Chip Erase Command	1704
5.7. Sector Erase Command	1705
5.8. Sector Erase Suspend Command.....	1708
5.9. Security Function.....	1709
5.9.1. Flash Security On/Off Determination When Reset Released.....	1710
5.9.2. Flash Security Setting Method	1711
5.9.3. Unlocking Flash Security	1712
5.9.4. Flash Access Restrictions When Security is ON	1713
5.10. Notes on Using Flash Memory	1714
CHAPTER 42: WORKFLASH MEMORY	1715
1. Overview.....	1716
2. Features.....	1717
3. Configuration.....	1718
3.1. Block Diagram	1719
3.2. Sector Configuration Diagram	1720
4. Registers.....	1721
4.1. WorkFlash Control Register : DFCTLR (WorkFlash ConTroL Register)	1722
4.2. WorkFlash Status Register : DFSTR (WorkFlash STratus Register).....	1723
4.3. Flash Interface Control Register : FLIFCTLR (Flash I/F Control Register)	1725

5.	Operation.....	1726
5.1.	Access Mode Setting.....	1727
5.1.1.	Configuring CPU-ROM Mode below.....	1728
5.1.2.	Configuring CPU Programming Mode.....	1729
5.2.	Writing Flash Memory by CPU.....	1730
5.3.	Automatic Algorithm.....	1731
5.3.1.	Command Sequence.....	1732
5.3.2.	Automatic Algorithm Execution State.....	1735
5.4.	Reset Command.....	1739
5.5.	Write Command.....	1740
5.6.	Chip Erase Command.....	1743
5.7.	Sector Erase Command.....	1744
5.8.	Sector Erase Suspend Command.....	1747
5.9.	Security Function.....	1748
5.9.1.	Flash Security On/Off Determination When Reset Released.....	1749
5.9.2.	Flash Security Setting Method.....	1750
5.9.3.	Unlocking Flash Security.....	1751
5.9.4.	Flash Access Restrictions When Security is ON.....	1752
5.10.	Notes on Using Flash Memory.....	1753
 CHAPTER 43: ON CHIP DEBUGGER (OCD).....		1755
1.	Overview.....	1756
2.	Features.....	1757
3.	Configuration.....	1758
3.1.	DEBUG I/F Clock.....	1760
3.1.1.	DEBUG I/F Main Clock (M_MCLK).....	1761
3.1.2.	DEBUG I/F PLL Clock (M_PCLK).....	1762
4.	Registers.....	1763
4.1.	DBG Register.....	1764
4.2.	User IO Register.....	1765
5.	Operation.....	1766
5.1.	OCDU Operating Mode.....	1767
5.1.1.	Operating Mode.....	1768
5.1.2.	Operating Mode Status Transition.....	1769
5.2.	Overview of DEBUG I/F.....	1770
5.2.1.	Chip Reset Sequence.....	1771
5.2.2.	Security Function.....	1773
5.3.	Specification Restrictions at Connection to OCD Tool of This Series.....	1774
5.3.1.	Clock Setting.....	1775
5.3.2.	Standby Mode.....	1776
5.3.3.	CAN Prescaler Register.....	1777
5.3.4.	Clock Reset State Transitions.....	1778
5.3.5.	Summary of Specification Restrictions.....	1780
5.4.	OCD-DSU ID Code and Mount Type Information on This Series.....	1784
 CHAPTER:44 GDC EXTERNAL CONTROL.....		1785
1.	Overview.....	1786
2.	Features.....	1787
3.	Configuration.....	1788
4.	Registers.....	1789

4.1.	GDC Control Register : GDCCR	1790
4.2.	GDC Trigger Register : GDCTRGR.....	1792
4.3.	GDC Swap Setting Register : GDCSWPR.....	1793
5.	Note.....	1795

APPENDIX.....	1797	
A.	Memory Map.....	1798
B.	I/O Map	1805
C.	List of Interrupt Vector.....	1841
D.	Pin Status in CPU Status	1844

CHAPTER: OVERVIEW

This chapter explains the overview.

1. Overview
2. Features
3. Product Line-up
4. Function Overview
5. Block Diagram
6. CPU
7. Pin Assignment
8. Package Dimensions
9. Explanation of Pin Functions
10. Pins of Each Function
11. I/O Circuit Types

Code : 01_MB91590_HM_E_overview_009_20111128

1. Overview

This section explains features of MB91590 series and basic specification.

MB91590 series is Fujitsu 32-bit microcontroller for application control for automotives. The FR81S CPU that is compatible with the FR family is used.

2. Features

This section explains features of MB91590 series.

- 2.1. FR81S CPU Core
- 2.2. Peripheral Functions

2.1. FR81S CPU Core

This section explains FR81S CPU core.

- 32-bit RISC, load/store architecture, 5-stage pipeline
- Maximum operating frequency: 128 MHz (Source oscillation = 4.0 MHz and 32 multiplied (PLL clock multiplication system))
- General-purpose register : 32 bits, 16 sets
- 16-bit fixed length instructions (basic instruction), 1 instruction per cycle
- Instructions appropriate to embedded applications
 - Memory-to-memory transfer instruction
 - Bit processing instruction
 - Barrel shift instruction etc.
- High-level language support instructions
 - Function entry/exit instructions
 - Register content multi-load and store instructions
- Bit search instructions
 - Logical 1 detection, 0 detection, and change-point detection
- Branch instructions with delay slot
 - Reduced overhead during branch process
- Register interlock function
 - Easy assembler writing
- Built-in multiplier / instruction level support
 - Signed 32-bit multiplication : 5 cycles
 - Signed 16-bit multiplication : 3 cycles
- Interrupt (PC/PS saving)
 - 6 cycles (16 priority levels)
- The Harvard architecture allows simultaneous execution of program and data access.
- Instruction compatibility with the FR family
- Built-in memory protection function (MPU)
 - Eight protection areas can be specified commonly for instructions and the data.
 - Control access privilege in both privilege mode and user mode.
- Built-in FPU (floating point arithmetic)
 - IEEE754 compliant
 - Floating-point register 32-bit × 16 sets

2.2. Peripheral Functions

This section explains peripheral functions of MB91590 series.

- Clock generation (equipped with SSCG function)
 - Main oscillation (4MHz)
 - Sub oscillation (32kHz) or none sub oscillation
 - PLL multiplication rate : 1 to 32 times
- Built-in program flash capacity 1024 + 64KB
- Built-in Data flash memory (WorkFlash) 64KB
- Built-in RAM capacity
 - Main RAM 64KB
 - Backup RAM 8 KB
- General-purpose ports (5V Pin) : 63 (dual clock products : 61)
 - Included I²C pseudo open drain ports: 4
- General-purpose ports (3V Pin) : 93
 - Included 48 combined external bus interface (For GDC external memory I/F)
- External bus interface
 - GDC external memory for I/F use
 - 25-bit address, 16-bit data
 - Power supply voltage fixed to 3.3V
- DMA Controller
 - Up to 16 channels can be started simultaneously.
 - 2 transfer factors (Internal peripheral request and software)
- A/D converter (successive approximation type)
 - 8/10-bit resolution : 32 channels
 - Conversion time : 3 μ s
- External interrupt input: 16 channels
 - Level ("H" / "L"), or edge detection (rising or falling) enabled
- LIN-UART
 - 6 channels, ch.2 to ch.7
 - UART, synchronous mode, LIN-UART mode is selectable.
 - LIN protocol Revision 2.1 is supported
 - SPI(Serial Peripheral Interface) supported (synchronous mode)
 - Full-duplex double buffering system
 - LIN synch break detection (linked to the input capture)
 - Built-in dedicated baud rate generator
 - DMA transfer supported
- Multi-function serial I/O (with built-in transmission/reception FIFO) : 2 channels
 - < UART (Asynchronous serial interface) >
 - Full-duplex double buffering system, 16-byte transmission FIFO, 16-byte reception FIFO
 - Parity or no parity is selectable.
 - Built-in dedicated baud rate generator
 - An external clock can be used as the transfer clock
 - Parity, frame, and overrun error detect functions provided
 - DMA transfer supported
 - <CSIO (Synchronous serial interface) >
 - Full-duplex double buffering system, 16-byte transmission FIFO, 16-byte reception FIFO
 - SPI supported; master and slave systems supported; 5 to 9-bit data length can be set.
 - Built-in dedicated baud rate generator (Master operation)
 - An external clock can be entered. (Slave operation)
 - Overrun error detect function is provided
 - DMA transfer supported
 - <LIN-UART (Asynchronous Serial Interface for LIN) >

- Full-duplex double buffering system, 16-byte transmission FIFO, 16-byte reception FIFO
- LIN protocol revision 2.1 supported
- Master and slave systems supported
- Framing error and overrun error detection
- LIN synch break generation and detection; LIN synch delimiter generation
- Built-in dedicated baud rate generator
- An external clock can be adjusted by the reload counter
- DMA transfer supported
- < I²C >
 - Full-duplex double buffering system, 16-byte transmission FIFO, 16-byte reception FIFO
 - Standard mode (Max. 100kbps) / high-speed mode (Max. 400kbps) supported
 - DMA transfer supported (for transmission only)
- CAN Controller (C-CAN) : 3 channels
 - Transfer speed : Up to 1Mbps
 - 64-transmission/reception message buffering : 1 channel,
32-transmission/reception message buffering : 2 channels
- PPG : 16-bit × 24 channels
- Reload timer : 16-bit × 4 channels
- Free-run timer : 32-bit × 2 channels (Can select each channel for input capture, output compare)
32-bit × 2 channels (LSYN (LIN synch field detection) for exclusive input capture)
- Input capture : 32-bit × 6 channels (linked to the free-run timer) LSYN (LIN synch field detected)
Exclusive 32-bit × 2 channels (linked to the free-run timer)
- Output compare : 32-bit × 4 channels (linked to the free-run timer)
- Sound generator : 5 channels
 - Frequency and amplitude sequencers provided
- Stepping motor controller : 6 channels
 - 8/10-bit PWM
 - High current output supported (4 lines × 6 channels)
 - Can refer back electromotive force from the motor using pin-shared ADC
 - Real-time clock (RTC) (for day, hours, minutes, seconds)
 - Main oscillation frequency or sub oscillation frequency(dual clock product only) can be selected for the operation clock
- Calibration: A hardware watchdog of the CR oscillation drive and real-time clock (RTC) of the sub clock drive(dual clock product only)
 - The CR oscillation frequency can be trimmed
 - The main clock to sub clock(dual clock product only) ratio can be corrected by setting the real-time clock prescaler
- Clock Supervisor
 - Monitoring abnormality (damage of crystal etc.) of sub oscillation (32kHz) (dual clock products) of the outside and main oscillation (4 MHz)
 - When abnormality is detected, it switches to the CR clock.
- Base timer : 2 channels
 - 16-bit timer
 - Any of four PWM/PPG/PWC/reload timer functions can be selected and used
 - A 32-bit timer can be used in 2 channels of cascade mode
- CRC generation
- Watchdog timer
 - Hardware watchdog
 - Software watchdog
- NMI
- Interrupt controller
- Interrupt request batch read
 - Multiple interrupts from peripherals can be read by a series of registers.
- I/O relocation
 - Peripheral function pins can be reassigned.

- Low-power consumption mode
 - Sleep / Stop / Watch / Sub RUN mode
 - Stop (power shutdown) / Watch (power shutdown) mode
 - GDC part self-support power supply
- Power on reset/Internal low-voltage detection reset
- Low-voltage detection reset
- GDC
 - Internal/memory frequency : 81MHz
 - The resolution of the display which can support : 800×480 at the maximum
Screen overlay of three simultaneous layers at the maximum (window)
Size of the resolution which can be supported varies depending on color format.

- Analog video input (NTSC)
- Digital video input (RGB666/555)
- YUV input (BT.656)
- Video image expansion/reduction /invert function is supported
- RGB Digital output (6-bit \times 3)
- Built-in 2D rendering engine
 - The line drawing is supported.
 - The BitBlt function is supported.
 - Display list operation is supported
 - 8bpp indirect color
 - ARGB-1555 direct color
 - Alpha blending, anti-aliasing

- Built-in Sprite engine
 - Equipped with automatic display function when booted
 - Maximum of 512 sprites are supported
 - 32 special sprites capable of automatic animation are supported.
 - The command list execution is supported.
 - 1bpp, 2bpp, 4bpp, 8bpp indirect color
 - ARGB-1555, RGB-565, ARGB-8888 direct color
 - The color format for each sprite can be set.
 - Horizontal invert, Vertical invert
 - Alpha blending

- Built-in memory (800KB)
- Device Package : LQFP-208, HQFP-208
- CMOS 90nm Technology
- Power supplies
 - 5V/3.3V Power supply
 - The internal 1.2V is generated from 5V/3.3V with the depression circuit.
 - For I/O of an external bus and GDC, 3.3V power supply used.
 - For the other I/O, 5V power supply used.
 - There is a constraint about power on sequence (5V \rightarrow 3.3V).

3. Product Line-up

This section shows product line-up of this series.

Table 3-1 : Product Line-up

Product		MB91F591B/S	MB91F591BH/S
CPU core		FR81S	
Technology		90nm	
Package		LQFP208	
Sub clock		Yes (Non-S series) No (S series)	
Maximum CPU operating frequency		80MHz	
Maximum GDC operating frequency		81MHz	
Built-in CR oscillator		100kHz	
System clock		On chip PLL	
Flash	Main	576KB	
	Sub	64KB	
RAM	Main	40KB	
	Backup	8KB	
VRAM		260KB	
Watchdog timer		1ch Hardware 1ch Software	
Clock supervisor		Initial value "OFF"	Initial value "ON"
External low voltage detection reset		Yes	
Internal low voltage detection reset		Yes	
NMI function		Yes	
DMA Controller		16ch	
CAN		1ch (64msg) 2ch (32msg)	
USART		LINx6 MFSx2	
A/D converter (8bit/10bit)		1unit/32ch	
Reload timer(16bit)		4ch	
Base timer(16bit)		2ch	
Free-run timer(32bit)		2ch	
Input capture(32bit)		6ch	
Output compare(32bit)		4ch	
PPG timer(16bit)		24ch	
Sound generator		5ch	
Real-time clock		Yes	
External interrupt		16ch	
CR/SUB compensation function		Yes	
CRC generator		Yes	

Item \ Product	MB91F591B/S	MB91F591BH/S
Stepping motor control	6ch	
Stop mode (with power-shutdown)	Supported	
Power supply voltage	MICOM : 4.5V to 5.5V GDC : 3.0V to 3.6V	
Operating temperature	-40 to +105°C	
Allowable power [mW]	1250	
Others	Flash product	
On chip debugger	Yes	

Product		MB91F592B/S	MB91F592BH/S	MB91F594B/S	MB91F594BH/S
CPU core		FR81S			
Technology		90nm			
Package		LQFP208			
Sub clock		Yes (Non-S series) No (S series)			
Maximum CPU operating frequency		80MHz			
Maximum GDC operating frequency		81MHz			
Built-in CR oscillator		100kHz			
System clock		On chip PLL			
Flash	Main	576KB		1088KB	
	Sub	64KB			
RAM	Main	40KB		64KB	
	Backup	8KB			
VRAM		800KB			
Watchdog timer		1ch Hardware 1ch Software			
Clock supervisor		Initial value "OFF"	Initial value "ON"	Initial value "OFF"	Initial value "ON"
External low voltage detection reset		Yes			
Internal low voltage detection reset		Yes			
NMI function		Yes			
DMA Controller		16ch			
CAN		1ch (64msg) 2ch (32msg)			
USART		LINx6 MFSx2			
A/D converter (8bit/10bit)		1unit/32ch			
Reload timer(16bit)		4ch			
Base timer(16bit)		2ch			
Free-run timer(32bit)		2ch			
Input capture(32bit)		6ch			
Output compare(32bit)		4ch			
PPG timer(16bit)		24ch			
Sound generator		5ch			
Real-time clock		Yes			
External interrupt		16ch			
CR/SUB compensation function		Yes			
CRC generator		Yes			
Stepping motor control		6ch			

Item \ Product	MB91F592B/S	MB91F592BH/S	MB91F594B/S	MB91F594BH/S
Stop mode (with power-shutdown)	Supported			
Power supply voltage	MICOM:4.5V to 5.5V GDC:3.0V to 3.6V			
Operating temperature	-40 to +105°C			
Allowable power [mW]	1250			
Others	Flash product			
On chip debugger	Yes			

Product		Item			
		MB91F596B/S	MB91F596BH/S	MB91F597B/S	MB91F597BH/S
CPU core		FR81S			
Technology		90nm			
Package		HQFP208			
Sub clock		Yes (Non-S series) No (S series)			
Maximum CPU operating frequency		128MHz			
Maximum GDC operating frequency		81MHz			
Built-in CR oscillator		100kHz			
System clock		On chip PLL			
Flash	Main	576KB			
	Sub	64KB			
RAM	Main	40KB			
	Backup	8KB			
VRAM		260KB		800KB	
Watchdog timer		1ch Hardware 1ch Software			
Clock supervisor		Initial value "OFF"	Initial value "ON"	Initial value "OFF"	Initial value "ON"
External low voltage detection reset		Yes			
Internal low voltage detection reset		Yes			
NMI function		Yes			
DMA Controller		16ch			
CAN		1ch (64msg) 2ch (32msg)			
USART		LINx6 MFSx2			
A/D converter (8bit/10bit)		1unit/32ch			
Reload timer(16bit)		4ch			
Base timer(16bit)		2ch			
Free-run timer(32bit)		2ch			
Input capture(32bit)		6ch			
Output compare(32bit)		4ch			
PPG timer(16bit)		24ch			
Sound generator		5ch			
Real-time clock		Yes			
External interrupt		16ch			
CR/SUB compensation function		Yes			
CRC generator		Yes			
Stepping motor control		6ch			

Item \ Product	MB91F596B/S	MB91F596BH/S	MB91F597B/S	MB91F597BH/S
Stop mode (with power-shutdown)	Supported			
Power supply voltage	MICOM:4.5V to 5.5V GDC:3.0V to 3.6V			
Operating temperature	-40 to +105°C			
Allowable power [mW]	2500			
Others	Flash product			
On chip debugger	Yes			

Product		MB91F599B/S	MB91F599BH/S
CPU core		FR81S	
Technology		90nm	
Package		HQFP208	
Sub clock		Yes (Non-S series) No (S series)	
Maximum CPU operating frequency		128MHz	
Maximum GDC operating frequency		81MHz	
Built-in CR oscillator		100kHz	
System clock		On chip PLL	
Flash	1088KB	1088KB	
	64KB	64KB	
RAM	64KB	64KB	
	8KB	8KB	
VRAM		800KB	
Watchdog timer		1ch Hardware 1ch Software	
Clock supervisor		Initial value "OFF"	Initial value "ON"
External low voltage detection reset		Yes	
Internal low voltage detection reset		Yes	
NMI function		Yes	
DMA		16ch	
CAN		1ch (64msg) 2ch (32msg)	
USART		LINx6 MFSx2	
A/D Converter (8bit/10bit)		1unit/32ch	
Reload timer(16bit)		4ch	
Base timer(16bit)		2ch	
Free-run timer(32bit)		2ch	
Input capture(32bit)		6ch	
Output compare(32bit)		4ch	
PPG timer(16bit)		24ch	
Sound generator		5ch	
Real-time clock		Yes	
External interrupt		16ch	
CR/SUB compensation function		Yes	
CRC generator		Yes	
Stepping motor control		6ch	

Item \ Product	MB91F599B/S	MB91F599BH/S
Stop mode (with power-shutdown)	Supported	
Power supply voltage	MICOM:4.5V to 5.5V GDC:3.0V to 3.6V	
Operating temperature	-40 to +105°C	
Allowable power [mW]	2500	
Others	Flash product	
On chip debugger	Yes	

4. Function Overview

This section shows function overview of MB91590 series.

Table 4-1 : Function Overview

Function	Features
CPU	32-bit RISC microcontroller FR81S CPU core Built-in memory protection function (MPU) 8 channels Built-in floating-point operation (FPU)
Clock	Main oscillation : 4MHz (Up to a maximum of 8MHz) Sub oscillation : 32kHz or None PLL multiplication rate: Up to 32 times of multiplication Built-in CR oscillator as the count clock of hardware watchdog timer
I/O ports	Each bit can be programmed for I/O or peripheral signals Input thresholds, driving capacity, and pull-up/pull-down can be set.
External bus Interface	25-bit address, 16-bit Data output For GDC external memory I/F Power supply voltage is fixed to 3.3V
Internal bus interface	On chip bus : 32-bit, maximum operating frequency : 128MHz
Peripheral bus interface	Maximum operating frequency : 40MHz 32-bit peripheral bus, or 16-bit peripheral bus (R-bus) * Both of them operate in the same frequency.
Flash interface	Wild register function provided. However, usable only during NoWait operation. 1wait necessary to be added if operation frequency exceeds 80MHz. Small sector (64KB size) is also supported.
DMA controller	Up to 16 channels can be started simultaneously. The transfer cause (internal peripheral request or software) is selectable. Burst or block transfer mode is selectable. -When two or more interrupts are in one interrupt vector, it can select from which interrupt to generate the DMA request. -When two or more interrupts are in one interrupt vector, the interrupt cleared at the DMA transfer completion can be selected.
Base timer	16-bit timer Any of four PWM/PPG/PWC/reload timer functions can be selected and used. A 32-bit timer can be used in 2 channels of cascade mode for the reload timer/PWC function.
Free-run timer	32-bit up counter
Input capture	32-bit capture registers to detect a rising edge, a falling edge, or both edges. When an edge of pin input is detected, the counter value of 32-bit free-run timer is latched and an interrupt request is generated. LIN synch break/synch field linkage : Input capture ch.0 → LIN-UART ch.2 Input capture ch.1 → LIN-UART ch.3 Input capture ch.2 → LIN-UART ch.4 Input capture ch.3 → LIN-UART ch.5 Input capture ch.4 → LIN-UART ch.6 Input capture ch.5 → LIN-UART ch.7 LSYN exclusive input capture ch.6 → Multi-function serial ch.0 LSYN exclusive input capture ch.7 → Multi-function serial ch.1

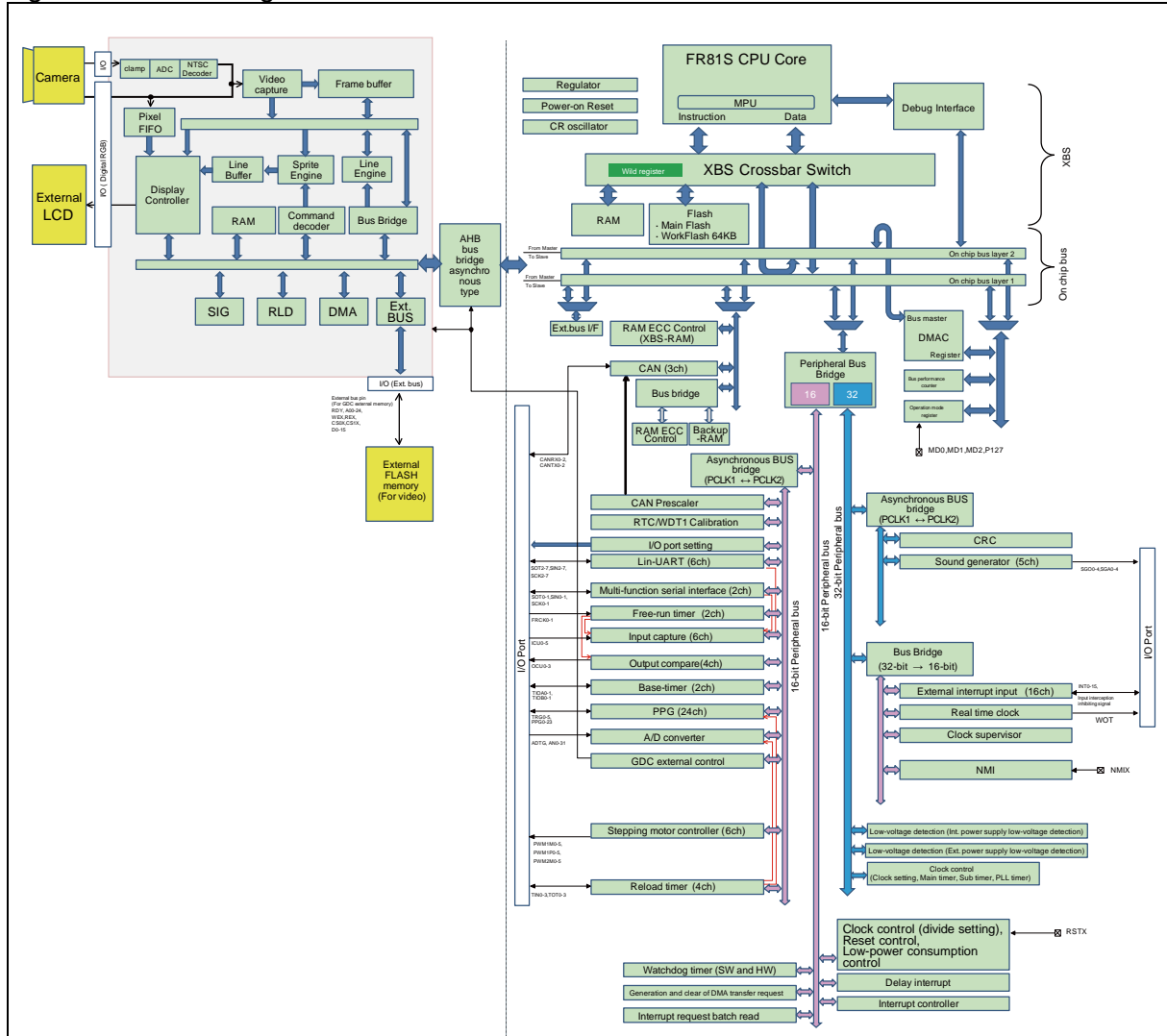
Function	Features
Output compare	An interrupt signal is output during collating with the 32-bit free-run timer.
Reload timer	16-bit reload timer operation (The toggle output or one-shot output can be selected) Event count function can be selected.
PPG	The cycle and duty used for the one-shot square wave output and PWM output can be changed by the software. Operation clock frequency : Can be selected from following 4 types : $PCLK \times 1, 1/2^2, 1/2^4, 1/2^6$
Delay interrupt	An interrupt for task switching is generated. The CPU interrupt request can be generated or canceled by the software.
External interrupt	16 channel, independent Interrupt factor : rising edge / falling edge / "L" level / "H" level can be selected. Support of edge input detection when returned to standby state.
A/D Converter	Built-in A/D converter 1ch of resolution in 10-bit or 8-bit Able to sample the analog value from 32ch input port Conversion time : 3 μ s External trigger activation Can be activated by the internal timer (16-bit reload timer)
LIN-UART	Full-duplex system Asynchronous/synchronous transfer (with start/stop bits) Built-in dedicated baud rate generator LIN protocol, slave node supported, and LIN synch break/synch field detectable SPI(Serial Peripheral Interface) supported Version 2.1 supported.
Multi-function serial	Any of UART/CSIO/LIN-UART/I ² C-UART functions can be selected and used. Transmission FIFO (16-byte) and reception FIFO (16-byte) are provided. Receive interrupt factor (3 types) - Receive error detection (parity, overrun, and frame error) - Data which amount is set for FIFO memory can be received. - Data below the FIFO memory capacity is received, and an idle period longer than 8 clocks of baud rate clock is detected. Transmission interrupt factor (2 types) - No transmission operation. - Empty transmission FIFO memory (including the time of transmission) SPI(Serial Peripheral Interface) supported LIN protocol revision 2.1 supported
Interrupt controller	Detects an interrupt request. Sets an interrupt level.
Interrupt request batch read	A generation of multiple interrupts from peripherals can be read by a series of registers.
CAN interface	CAN Specifications Version 2.0, Part A and Part B satisfied 64 message buffers \times 1channel, 32 message buffers \times 2channels Plural messages are supported. Flexible composition of acceptance filter : Entire bit compare Entire bit Mask 2 portion bit Mask Up to 1Mbps supported. CAN prescaler is mounted for the CAN operation clock
Stepping motor controller	High current output \times 4 lines The PWM cycle can be set to 15.625kHz (when the peripheral clock operates in 16MHz). Can refer back electromotive force from the motor using pin-shared ADC

Function	Features
Sound generator	In addition to the frequency data and amplitude data setting, the followings can be set : - Decrement or increment data, and execution cycle - Tone output pulse count (output interval)
Real-time clock	Day/hours/minutes/seconds register Main or sub oscillation frequency can be selected for the operation clock. Sub clock correction function - The sub clock cycle error is monitored by the main clock. - The detected error is reflected on the second counter set value. An interrupt can be generated in unit of 0.5 second, seconds, minutes, hours, or day.
Calibration	The real-time clock of the sub clock drive is corrected by comparison with the main clock. The CR oscillation frequency can be corrected by the comparison with the main clock.
Software watchdog	It counts while CPU is working. Stops counting when the CPU is stopped. Cycle can be selected from 16 kinds of PCLK \times (2^9 to 2^{24}) cycles
Hardware watchdog	CR-based CPU operation detect counter Used against program overrun Period: 260ms to 416ms (usually, 328ms, depending on the accuracy of the CR oscillation) The calibration is possible with "RTC/WDT1 correction" circuit. It is the one that width is at the cycle that originates in the difference of manufacturing. Note that it is not because the cycle can be arbitrarily set.
CRC generation	The CRC code is displayed in the result register by writing in the input register one by one.
Internal power supply low voltage detection	Reset is generated when 1.2V voltage of the faction is observed, and it falls below. An internal power supply voltage is observed, the low voltage is set, and the flag is set by detection.
Low-voltage detection	Reset generation at low voltage detection
Graphic device interface	Maximum resolution: 800×480 NTSC/RGB666/555/BT.656 input supported RBG666 output supported Sprite engine mounted Line engine mounted VRAM : 800KB
Low-power consumption mode	Sleep mode Stop mode Watch mode Stop mode (power shutdown) Watch mode (power shutdown) GDC part independence power supply Sub RUN Mode
I/O relocation	Relocation peripheral function and number of branches - PPG 24 channels (4 branches for ch.1, 3 branches for ch.0 and ch.2 to ch.10, no branches for ch.11 to ch.23). - Input capture 6 channels \times 3 branches - LIN-UART 4 channels \times 2 branches (No relocation for the remaining 2 channels) - Reload timer 4 channels \times 3 branches
NMI request	Non-maskable interrupt signal that is entered from NMIX pin.
Debug interface	Built-in OCD (On Chip Debug Unit)

5. Block Diagram

This section shows block diagram of this series.

Figure 5-1 Block Diagram



6. CPU

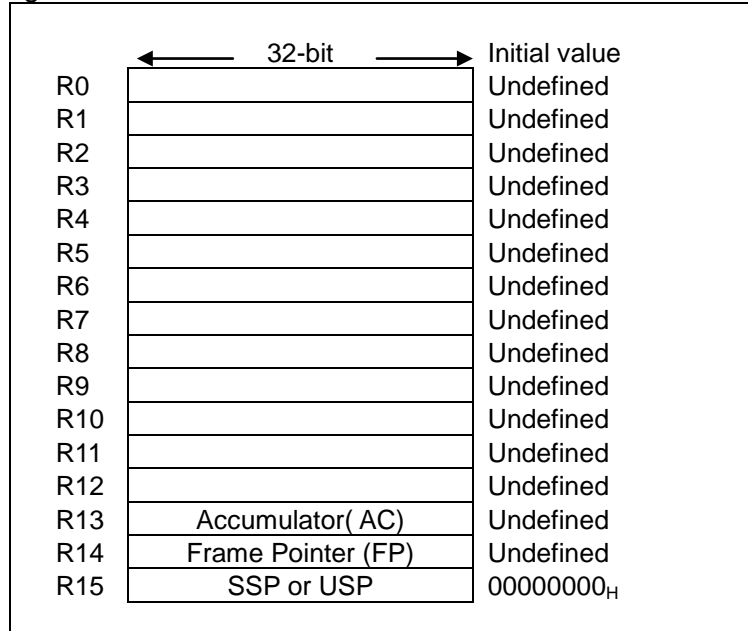
This section explains general-purpose registers and dedicated registers of CPU.

- 6.1. General-purpose Registers
- 6.2. Dedicated Registers

6.1. General-purpose Registers

Registers R0 to R15 are a general-purpose registers. They are used as the accumulators for various operations and as pointers for memory access.

Figure 6-1 General-purpose Registers



Among these 16 registers, the following registers are assumed to be used for special applications. Therefore, some instruction functions have been enhanced.

- R13: AC (Accumulator)
- R14: FP (Frame Pointer)
- R15: SP (Stack Pointer)

The initial value during reset is undefined for registers R0 to R14. Register R15 has 00000000_H (SSP value).

6.2. Dedicated Registers

There are nine dedicated registers for 32-bit length exclusive for various usages, and there is one dedicated register for 64-bit length of the multiplication and division calculation.

Figure 6-2 List of Dedicated Registers

		Initial value
PC		Reset entry address
PS		SSR=3 _H ,ILM=01111 _B ,SCR=XX0 _B ,CCR=0000XXXX _B
TBR		000FFC00 _H
RP		Undefined
SSP		00000000 _H
USP		Undefined
BP		Undefined
FCR		Undefined
ESR		00000000 _H
MD		Undefined

Dedicated register is used for a specific purpose.

In the FR family, the following dedicated registers are prepared.

- Program counter (PC)
- Program status (PS)
- Table base register (TBR)
- Return pointer (RP)
- System stack pointer (SSP)
- User stack pointer (USP)
- Base pointer (BP)
- FPU control register (FCR)
- Exception status register (ESR)
- Multiplication and division register (MD)

7. Pin Assignment

This section shows pin assignment of MB91590 series.

Figure 7-1 Pin Assignment (single clock product)

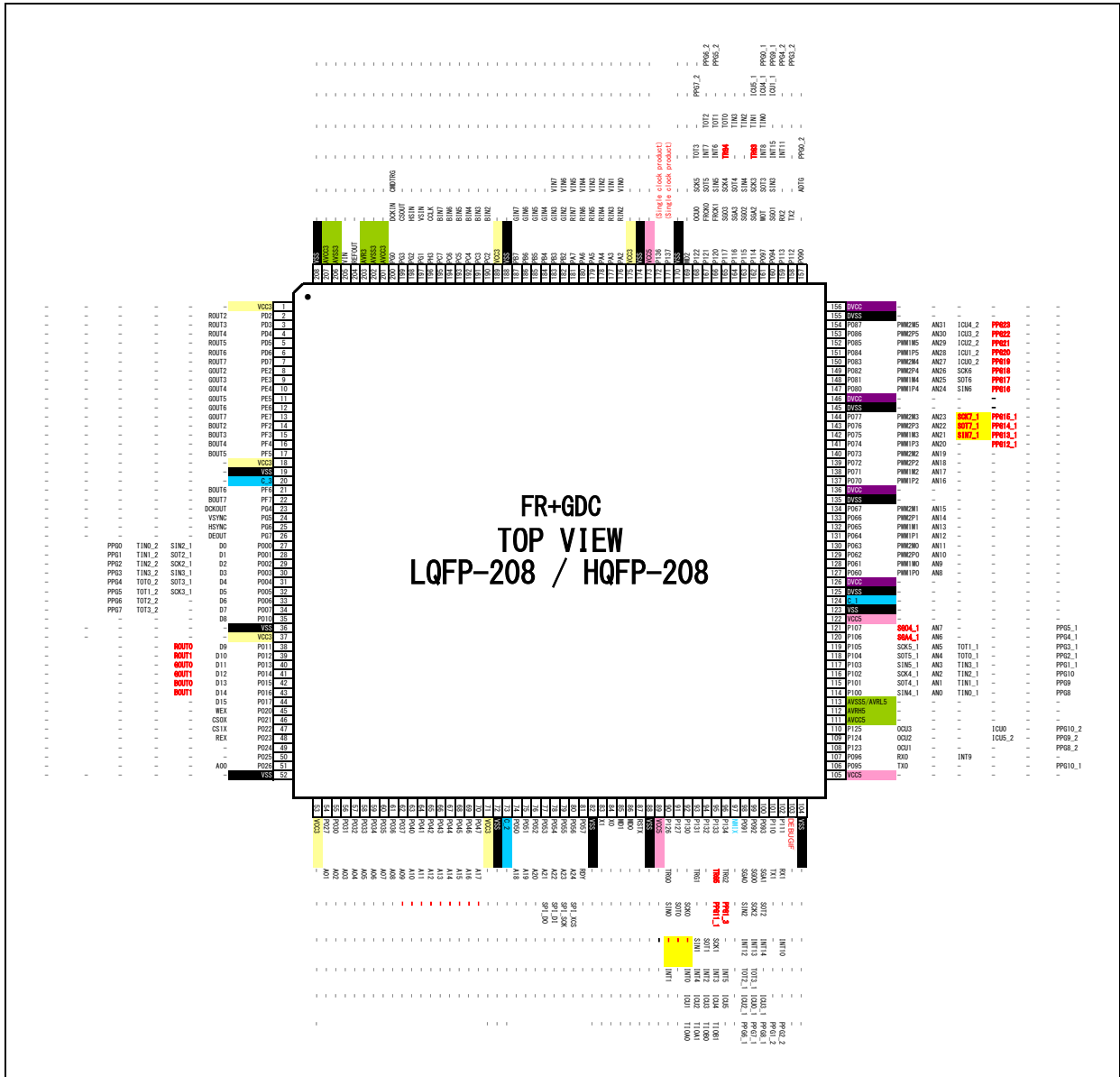
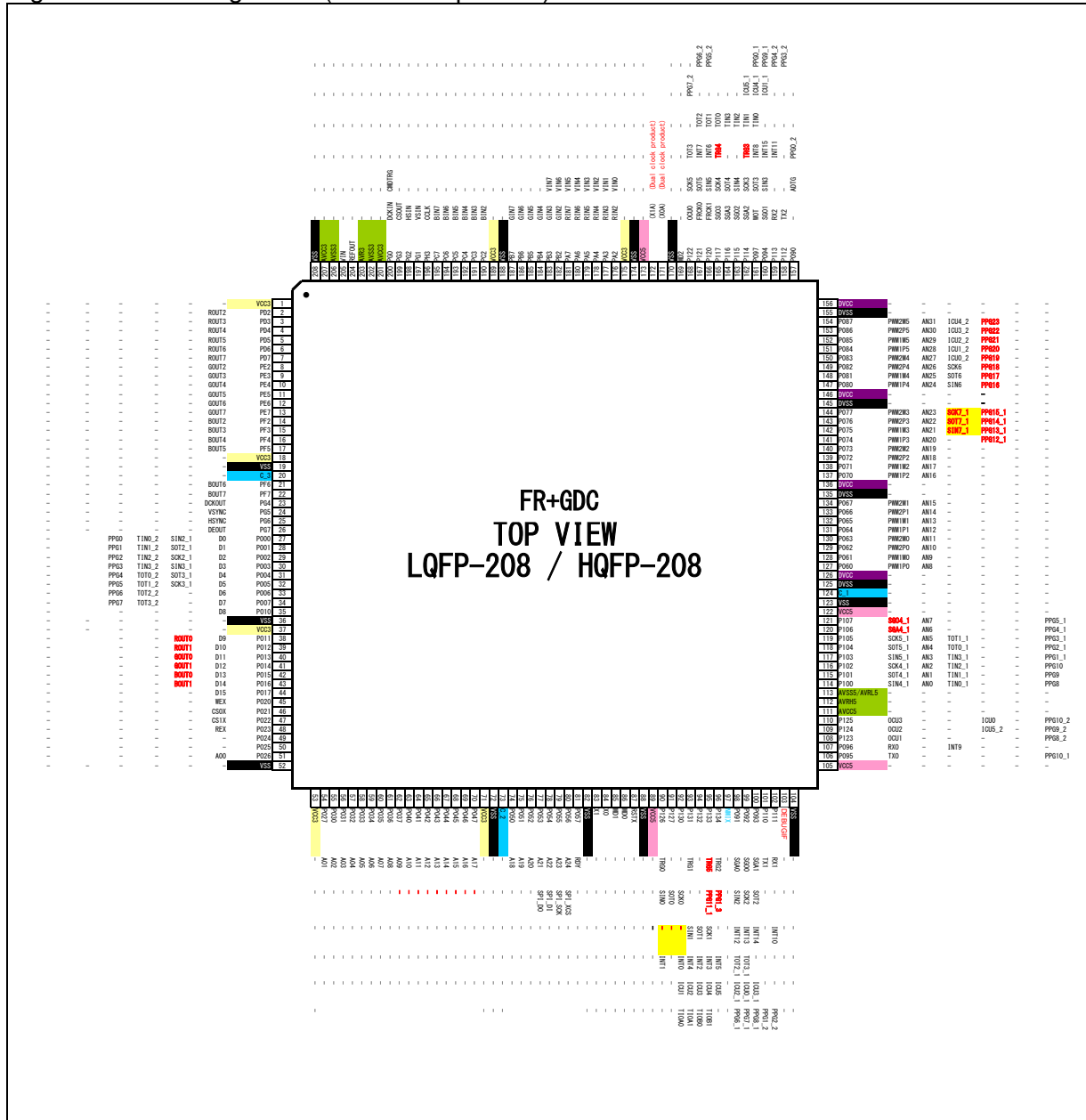


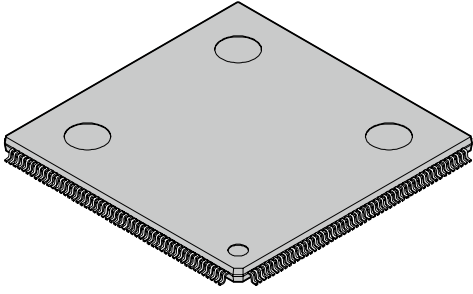
Figure 7-2 Pin Assignment (dual clock product)

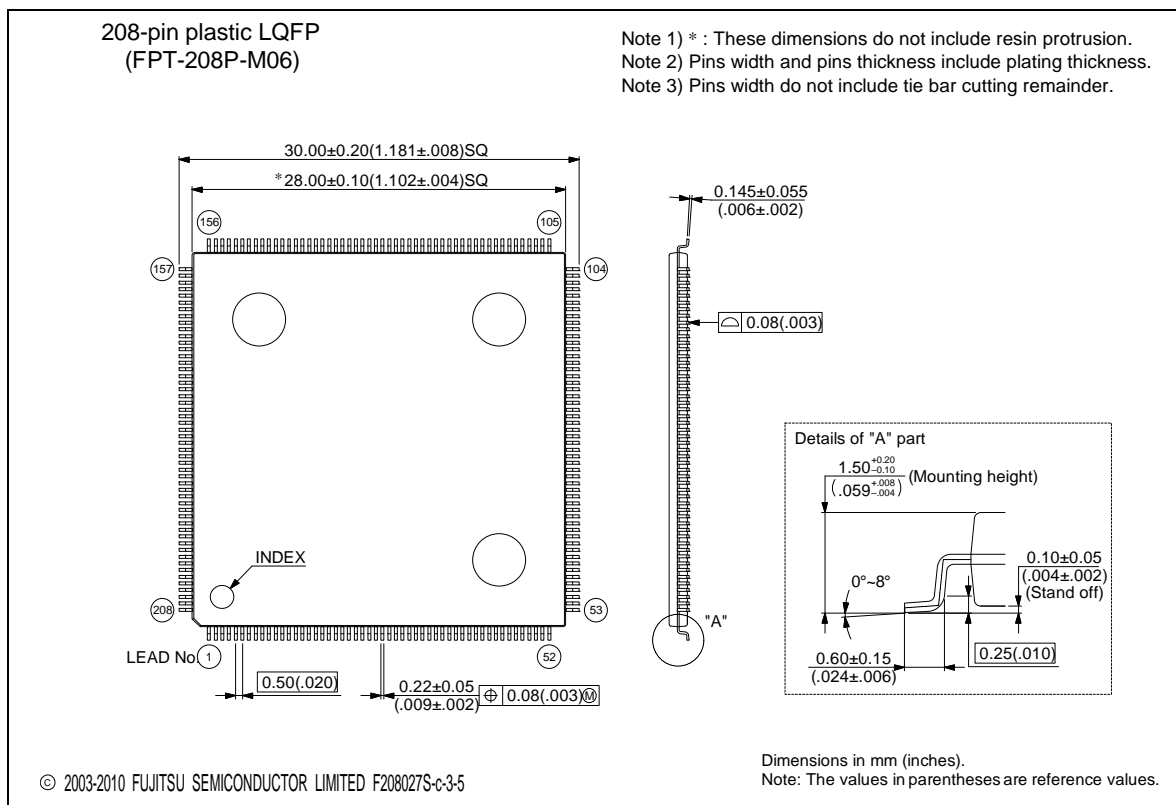


8. Package Dimensions

This section shows package dimensions of MB91590 series.

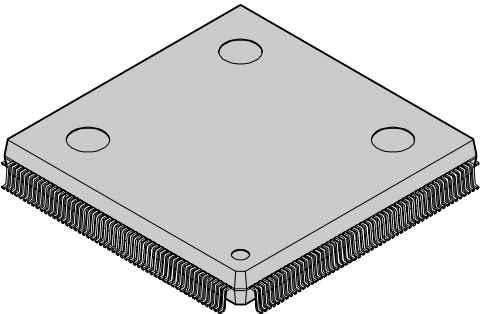
Figure 8-1 LQFP-208(FPT-208P-M06) Package Dimensions

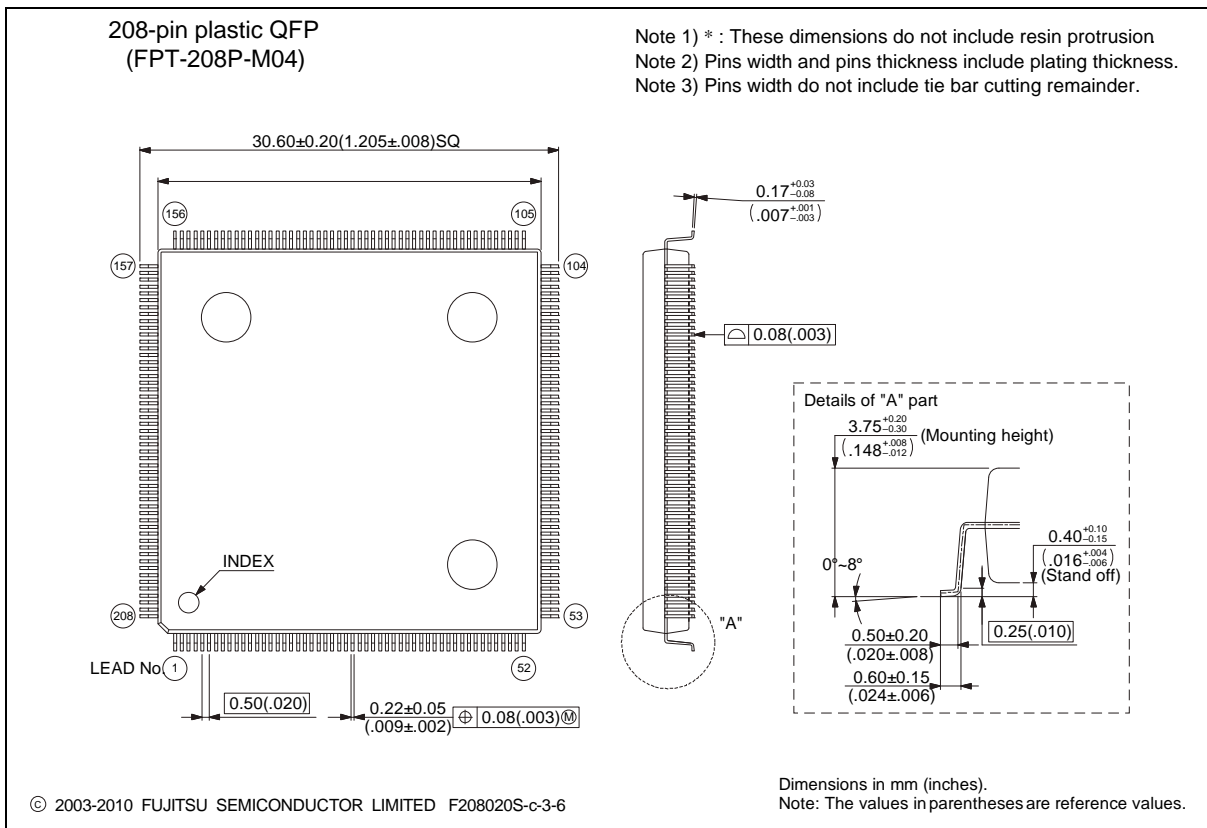
<p>208-pin plastic LQFP</p>  <p>(FPT-208P-M06)</p>	Lead pitch	0.50 mm
	Package width × package length	28.0 × 28.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Weight	2.55 g
	Code (Reference)	P-LFQFP208-28×28-0.50



Please confirm the latest Package dimension by following URL.
<http://edevice.fujitsu.com/package/en-search/>

Figure 8-2 HQFP-208(FPT-208P-M04) Package Dimensions (Under planning)

<p style="text-align: center;">208-pin plastic QFP</p>  <p style="text-align: center;">(FPT-208P-M04)</p>	Lead pitch	0.50 mm
	Package width × package length	28.0 mm × 28.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	3.95 mm MAX
	Weight	5.71g
	Remark	Low heat resistance type



Please confirm the latest Package dimension by following URL.
<http://edevice.fujitsu.com/package/en-search/>

9. Explanation of Pin Functions

The pin function list of the MB91590 series is shown.

Table 9-1 List of Pin Functions

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
84	X0	—	L	Main clock oscillation input pin
83	X1	—	L	Main clock oscillation output pin
171 (dual clock product)	X0A	—	N	Sub clock oscillation input pin
172 (dual clock product)	X1A	—	N	Sub clock oscillation output pin
171 (single clock product)	P137	—	A	General-purpose I/O port
172 (single clock product)	P136	—	A	General-purpose I/O port
97	NMIX	N	F1	Non-masking interrupt input pin
170	VSS	—	—	GND pin
87	RSTX	N	F1	External reset input pin
86	MD0	—	P	Mode pin 0
85	MD1	—	P	Mode pin 1
169	MD2	—	F2	Mode pin 2
27	P000	—	O	General-purpose I/O port (3V pin)
	D0	—		External bus / Data bit0 I/O pin
	SIN2_1	—		LIN-UART ch.2 serial data input pin (1)
	TIN0_2	—		Reload timer ch.0 event input pin (2)
	PPG0	—		PPG ch.0 output pin
28	P001	—	O	General-purpose I/O port (3V pin)
	D1	—		External bus / Data bit1 I/O pin
	SOT2_1	—		LIN-UART ch.2 serial data output pin (1)
	TIN1_2	—		Reload timer ch.1 event input pin (2)
	PPG1	—		PPG ch.1 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
29	P002	—	O	General-purpose I/O port (3V pin)
	D2	—		External bus / Data bit2 I/O pin
	SCK2_1	—		LIN-UART ch.2 clock I/O pin (1)
	TIN2_2	—		Reload timer ch.2 event input pin (2)
	PPG2	—		PPG ch.2 output pin
30	P003	—	O	General-purpose I/O port (3V pin)
	D3	—		External bus / Data bit3 I/O pin
	SIN3_1	—		LIN-UART ch.3 serial data input pin (1)
	TIN3_2	—		Reload timer ch.3 event input pin (2)
	PPG3	—		PPG ch.3 output pin
31	P004	—	O	General-purpose I/O port (3V pin)
	D4	—		External bus / Data bit4 I/O pin
	SOT3_1	—		LIN-UART ch.3 serial data output pin (1)
	TOT0_2	—		Reload timer ch.0 output pin (2)
	PPG4	—		PPG ch.4 output pin
32	P005	—	O	General-purpose I/O port (3V pin)
	D5	—		External bus / Data bit5 I/O pin
	SCK3_1	—		LIN-UART ch.3 clock I/O pin (1)
	TOT1_2	—		Reload timer ch.1 output pin (2)
	PPG5	—		PPG ch.5 output pin
33	P006	—	O	General-purpose I/O port (3V pin)
	D6	—		External bus / Data bit6 I/O pin
	TOT2_2	—		Reload timer ch.2 output pin (2)
	PPG6	—		PPG ch.6 output pin
34	P007	—	O	General-purpose I/O port (3V pin)
	D7	—		External bus / Data bit7 I/O pin
	TOT3_2	—		Reload timer ch.3 output pin (2)
	PPG7	—		PPG ch.7 output pin
35	P010	—	O	General-purpose I/O port (3V pin)
	D8	—		External bus / Data bit8 I/O pin
38	P011	—	O	General-purpose I/O port (3V pin)
	D9	—		External bus / Data bit9 I/O pin
	ROUT0	—		Display digital R0 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
39	P012	—	O	General-purpose I/O port (3V pin)
	D10	—		External bus / Data bit10 I/O pin
	ROUT1	—		Display digital R1 output pin
40	P013	—	O	General-purpose I/O port (3V pin)
	D11	—		External bus / Data bit11 I/O pin
	GOUT0	—		Display digital G0 output pin
41	P014	—	O	General-purpose I/O port (3V pin)
	D12	—		External bus / Data bit12 I/O pin
	GOUT1	—		Display digital G1 output pin
42	P015	—	O	General-purpose I/O port (3V pin)
	D13	—		External bus / Data bit13 I/O pin
	BOUT0	—		Display digital B0 output pin
43	P016	—	O	General-purpose I/O port (3V pin)
	D14	—		External bus / Data bit14 I/O pin
	BOUT1	—		Display digital B1 output pin
44	P017	—	O	General-purpose I/O port (3V pin)
	D15	—		External bus / Data bit15 I/O pin
45	P020	—	O	General-purpose I/O port (3V pin)
	WEX	—		External bus / Write enable output pin
46	P021	—	O	General-purpose I/O port (3V pin)
	CS0X	—		External bus / Chip select 0 output pin
47	P022	—	O	General-purpose I/O port (3V pin)
	CS1X	—		External bus / Chip select 1 output pin
48	P023	—	O	General-purpose I/O port (3V pin)
	REX	—		External bus / Read enable output pin
49	P024	—	O	General-purpose I/O port (3V pin)
50	P025	—	O	General-purpose I/O port (3V pin)
51	P026	—	O	General-purpose I/O port (3V pin)
	A00	—		External bus / Address bit0 output pin
54	P027	—	O	General-purpose I/O port (3V pin)
	A01	—		External bus / Address bit1 output pin
55	P030	—	O	General-purpose I/O port (3V pin)
	A02	—		External bus / Address bit2 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
56	P031	—	O	General-purpose I/O port (3V pin)
	A03	—		External bus /Address bit3 output pin
57	P032	—	O	General-purpose I/O port (3V pin)
	A04	—		External bus / Address bit4 output pin
58	P033	—	O	General-purpose I/O port (3V pin)
	A05	—		External bus / Address bit5 output pin
59	P034	—	O	General-purpose I/O port (3V pin)
	A06	—		External bus / Address bit6 output pin
60	P035	—	O	General-purpose I/O port (3V pin)
	A07	—		External bus / Address bit7 output pin
61	P036	—	O	General-purpose I/O port (3V pin)
	A08	—		External bus/Address bit8 output pin
62	P037	—	O	General-purpose I/O port (3V pin)
	A09	—		External bus/Address bit9 output pin
63	P040	—	O	General-purpose I/O port (3V pin)
	A10	—		External bus / Address bit10 output pin
64	P041	—	O	General-purpose I/O port (3V pin)
	A11	—		External bus / Address bit11 output pin
65	P042	—	O	General-purpose I/O port (3V pin)
	A12	—		External bus / Address bit12 output pin
66	P043	—	O	General-purpose I/O port (3V pin)
	A13	—		External bus / Address bit13 output pin
67	P044	—	O	General-purpose I/O port (3V pin)
	A14	—		External bus / Address bit14 output pin
68	P045	—	O	General-purpose I/O port (3V pin)
	A15	—		External bus / Address bit15 output pin
69	P046	—	O	General-purpose I/O port (3V pin)
	A16	—		External bus / Address bit16 output pin
70	P047	—	O	General-purpose I/O port (3V pin)
	A17	—		External bus / Address bit17 output pin
74	P050	—	O	General-purpose I/O port (3V pin)
	A18	—		External bus / Address bit18 output pin
75	P051	—	O	General-purpose I/O port(3V pin)
	A19	—		External bus / Address bit19 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
76	P052	—	O	General-purpose I/O port(3V pin)
	A20	—		External bus / Address bit20 output pin
77	P053	—	O	General-purpose I/O port(3V pin)
	A21	—		External bus / Address bit21 output pin
	SPI_DO	—		SPI data output pin
78	P054	—	O	General-purpose I/O port (3V pin)
	A22	—		External bus / Address bit22 output pin
	SPI_DI	—		SPI data input pin
79	P055	—	O	General-purpose I/O port (3V pin)
	A23	—		External bus / Address bit23 output pin
	SPI_SCK	—		SPI clock output pin
80	P056	—	O	General-purpose I/O port (3V pin)
	A24	—		External bus / Address bit24 output pin
	SPI_XCS	—		SPI chip select output pin
81	P057	—	O	General-purpose I/O port (3V pin)
	RDY	—		External bus / Wait input pin
127	P060	—	E	General-purpose I/O port
	PWM1P0	—		SMC ch.0 output pin
	AN8	—		ADC Analog 8 input pin
128	P061	—	E	General-purpose I/O port
	PWM1M0	—		SMC ch.0 output pin
	AN9	—		ADC Analog 9 input pin
129	P062	—	E	General-purpose I/O port
	PWM2P0	—		SMC ch.0 output pin
	AN10	—		ADC Analog 10 input pin
130	P063	—	E	General-purpose I/O port
	PWM2M0	—		SMC ch.0 output pin
	AN11	—		ADC Analog 11 input pin
131	P064	—	E	General-purpose I/O port
	PWM1P1	—		SMC ch.1 output pin
	AN12	—		ADC Analog 12 input pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
132	P065	—	E	General-purpose I/O port
	PWM1M1	—		SMC ch.1 output pin
	AN13	—		ADC Analog 13 input pin
133	P066	—	E	General-purpose I/O port
	PWM2P1	—		SMC ch.1 output pin
	AN14	—		ADC Analog 14 input pin
134	P067	—	E	General-purpose I/O port
	PWM2M1	—		SMC ch.1 output pin
	AN15	—		ADC Analog 15 input pin
137	P070	—	E	General-purpose I/O port
	PWM1P2	—		SMC ch.2 output pin
	AN16	—		ADC Analog 16 input pin
138	P071	—	E	General-purpose I/O port
	PWM1M2	—		SMC ch.2 output pin
	AN17	—		ADC Analog 17 input pin
139	P072	—	E	General-purpose I/O port
	PWM2P2	—		SMC ch.2 output pin
	AN18	—		ADC Analog 18 input pin
140	P073	—	E	General-purpose I/O port
	PWM2M2	—		SMC ch.2 output pin
	AN19	—		ADC Analog 19 input pin
141	P074	—	E	General-purpose I/O port
	PWM1P3	—		SMC ch.3 output pin
	AN20	—		ADC Analog 20 input pin
	PPG12_1	—		PPG ch.12 output pin (1)
142	P075	—	E	General-purpose I/O port
	PWM1M3	—		SMC ch.3 output pin
	AN21	—		ADC Analog 21 input pin
	SIN7_1	—		LIN-UART ch.7 serial data input pin
	PPG13_1	—		PPG ch.13 output pin (1)
143	P076	—	E	General-purpose I/O port
	PWM2P3	—		SMC ch.3 output pin
	AN22	—		ADC Analog 22 input pin
	SOT7_1	—		LIN-UART ch.7 serial data output pin
	PPG14_1	—		PPG ch.14 output pin (1)

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
144	P077	—	E	General-purpose I/O port
	PWM2M3	—		SMC ch.3 output pin
	AN23	—		ADC Analog 23 input pin
	SCK7_1	—		LIN-UART ch.7 clock I/O pin
	PPG15_1	—		PPG ch.15 output pin (1)
147	P080	—	E	General-purpose I/O port
	PWM1P4	—		SMC ch.4 output pin
	AN24	—		ADC Analog 24 input pin
	SIN6	—		LIN-UART ch.6 serial data input pin
	PPG16	—		PPG ch.16 output pin
148	P081	—	E	General-purpose I/O port
	PWM1M4	—		SMC ch.4 output pin
	AN25	—		ADC Analog 25 input pin
	SOT6	—		LIN-UART ch.6 serial data output pin
	PPG17	—		PPG ch.17 output pin
149	P082	—	E	General-purpose I/O port
	PWM2P4	—		SMC ch.4 output pin
	AN26	—		ADC Analog 26 input pin
	SCK6	—		LIN-UART ch.6 clock I/O pin
	PPG18	—		PPG ch.18 output pin
150	P083	—	E	General-purpose I/O port
	PWM2M4	—		SMC ch.4 output pin
	AN27	—		ADC Analog 27 input pin
	ICU0_2	—		Input capture ch.0 input pin (2)
	PPG19	—		PPG ch.19 output pin
151	P084	—	E	General-purpose I/O port
	PWM1P5	—		SMC ch.5 output pin
	AN28	—		ADC Analog 28 input pin
	ICU1_2	—		Input capture ch.1 input pin (2)
	PPG20	—		PPG ch.20 output pin
152	P085	—	E	General-purpose I/O port
	PWM1M5	—		SMC ch.5 output pin
	AN29	—		ADC Analog 29 input pin
	ICU2_2	—		Input capture ch.2 input pin (2)
	PPG21	—		PPG ch.21 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
153	P086	—	E	General-purpose I/O port
	PWM2P5	—		SMC ch.5 output pin
	AN30	—		ADC Analog 30 input pin
	ICU3_2	—		Input capture ch.3 input pin (2)
	PPG22	—		PPG ch.22 output pin
154	P087	—	E	General-purpose I/O port
	PWM2M5	—		SMC ch.5 output pin
	AN31	—		ADC Analog 31 input pin
	ICU4_2	—		Input capture ch.4 input pin (2)
	PPG23	—		PPG ch.23 output pin
157	P090	—	A	General-purpose I/O port
	ADTG	—		A/D converter external trigger input pin
	PPG0_2	—		PPG ch.0 output pin (2)
98	P091	—	C	General-purpose I/O port
	SGA0	—		Sound generator ch.0 SGA output pin
	SIN2	—		LIN-UART ch.2 serial data input pin
	INT12	—		INT12 External interrupt input pin
	TOT2_1	—		Reload timer ch.2 output pin (1)
	ICU2_1	—		Input capture ch.2 input pin (1)
	PPG6_1	—		PPG ch.6 output pin (1)
99	P092	—	C	General-purpose I/O port
	SGO0	—		Sound generator ch.0 SGO output pin
	SCK2	—		LIN-UART ch.2 clock I/O pin
	INT13	—		INT13 External interrupt input pin
	TOT3_1	—		Reload timer ch.3 output pin (1)
	ICU0_1	—		Input capture ch.0 input pin (1)
	PPG7_1	—		PPG ch.7 output pin (1)
100	P093	—	C	General-purpose I/O port
	SGA1	—		Sound generator ch.1 SGA output pin
	SOT2	—		LIN-UART ch.2 serial data output pin
	INT14	—		INT14 External interrupt input pin
	ICU3_1	—		Input capture ch.3 input pin (1)
	PPG8_1	—		PPG ch.8 output pin (1)

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
160	P094	—	C	General-purpose I/O port
	SGO1	—		Sound generator ch.1 SGO output pin
	SIN3	—		LIN-UART ch.3 serial data input pin
	INT15	—		INT15 External interrupt input pin
	ICU1_1	—		Input capture ch.1 input pin (1)
	PPG9_1	—		PPG ch.9 output pin (1)
106	P095	—	A	General-purpose I/O port
	TX0	—		CAN transmission data0 output pin
	PPG10_1	—		PPG ch.10 output pin (1)
107	P096	—	A	General-purpose I/O port
	RX0	—		CAN reception data0 input pin
	INT9	—		INT9 External interrupt input pin
161	P097	—	C	General-purpose I/O port
	WOT	—		RTC overflow output pin
	SOT3	—		LIN-UART ch.3 serial data output pin
	INT8	—		INT8 External interrupt input pin
	TIN0	—		Reload timer ch.0 event input pin
	ICU4_1	—		Input capture ch.4 input pin (1)
	PPG0_1	—		PPG ch.0 output pin (1)
114	P100	—	C	General-purpose I/O port
	SIN4_1	—		LIN-UART ch.4 serial data input pin (1)
	AN0	—		ADC Analog 0 input pin
	TIN0_1	—		Reload timer ch.0 event input pin (1)
	PPG8	—		PPG ch.8 output pin
115	P101	—	C	General-purpose I/O port
	SOT4_1	—		LIN-UART ch.4 serial data output pin (1)
	AN1	—		ADC Analog 1 input pin
	TIN1_1	—		Reload timer ch.1 event input pin (1)
	PPG9	—		PPG ch.9 output pin
116	P102	—	C	General-purpose I/O port
	SCK4_1	—		LIN-UART ch.4 clock I/O pin(1)
	AN2	—		ADC Analog 2 input pin
	TIN2_1	—		Reload timer ch.2 event input pin (1)
	PPG10	—		PPG ch.10 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
117	P103	—	C	General-purpose I/O port
	SIN5_1	—		LIN-UART ch.5 serial data input pin (1)
	AN3	—		ADC Analog 3 input pin
	TIN3_1	—		Reload timer ch.3 event input pin (1)
	PPG1_1	—		PPG ch.1 output pin (1)
118	P104	—	C	General-purpose I/O port
	SOT5_1	—		LIN-UART ch.5 serial data output pin (1)
	AN4	—		ADC Analog 4 input pin
	TOT0_1	—		Reload timer ch.0 output pin (1)
	PPG2_1	—		PPG ch.2 output pin (1)
119	P105	—	C	General-purpose I/O port
	SCK5_1	—		LIN-UART ch.5 clock I/O pin (1)
	AN5	—		ADC Analog 5 input pin
	TOT1_1	—		Reload timer ch.1 output pin (1)
	PPG3_1	—		PPG ch.3 output pin (1)
120	P106	—	C	General-purpose I/O port
	SGA4_1	—		Sound generator ch.4 SGA output pin
	AN6	—		ADC Analog 6 input pin
	PPG4_1	—		PPG ch.4 output pin (1)
121	P107	—	C	General-purpose I/O port
	SGO4_1	—		Sound generator ch.4 SGO output pin
	AN7	—		ADC Analog 7 input pin
	PPG5_1	—		PPG ch.5 output pin (1)
101	P110	—	C	General-purpose I/O port
	TX1	—		CAN transmission data1 output pin
	PPG1_2	—		PPG ch.1 output pin (2)
102	P111	—	C	General-purpose I/O port
	RX1	—		CAN reception data 1 input pin
	INT10	—		INT10 External interrupt input pin
	PPG2_2	—		PPG ch.2 output pin (2)
158	P112	—	C	General-purpose I/O port
	TX2	—		CAN transmission data 2 output pin
	PPG3_2	—		PPG ch.3 output pin (2)

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
159	P113	—	C	General-purpose I/O port
	RX2	—		CAN reception data 2 input pin
	INT11	—		INT11 External interrupt input pin
	PPG4_2	—		PPG ch.4 output pin (2)
162	P114	—	C	General-purpose I/O port
	SGA2	—		Sound generator ch.2 SGA output pin
	SCK3	—		LIN-UART ch.3 clock I/O pin
	TRG3	—		PPG trigger 3 input pin (ch.12 to ch.15)
	TIN1	—		Reload timer ch.1 event input pin
	ICU5_1	—		Input capture ch.5 input pin (1)
163	P115	—	C	General-purpose I/O port
	SGO2	—		Sound generator ch.2 SGO output pin
	SIN4	—		LIN-UART ch.4 serial data input pin
	TIN2	—		Reload timer ch.2 event input pin
164	P116	—	C	General-purpose I/O port
	SGA3	—		Sound generator ch.3 SGA output pin
	SOT4	—		LIN-UART ch.4 serial data output pin
	TIN3	—		Reload timer ch.3 event input pin
165	P117	—	C	General-purpose I/O port
	SGO3	—		Sound generator ch.3 SGO output pin
	SCK4	—		LIN-UART ch.4 clock I/O pin
	TRG4	—		PPG trigger 4 input pin (ch.16 to ch.19)
	TOT0	—		Reload timer ch.0 output pin
166	P120	—	C	General-purpose I/O port
	FRCK1	—		Free-run timer 1 clock input pin
	SIN5	—		LIN-UART ch.5 serial data input pin
	INT6	—		INT6 External interrupt input pin
	TOT1	—		Reload timer ch.1 output pin
	PPG5_2	—		PPG ch.5 output pin (2)

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
167	P121	—	C	General-purpose I/O port
	FRCK0	—		Free-run timer 0 clock input pin
	SOT5	—		LIN-UART ch.5 serial data output pin
	INT7	—		INT7 External interrupt input pin
	TOT2	—		Reload timer ch.2 output pin
	PPG6_2	—		PPG ch.6 output pin (2)
168	P122	—	C	General-purpose I/O port
	OCU0	—		Output compare ch.0 output pin
	SCK5	—		LIN-UART ch.5 clock I/O pin
	TOT3	—		Reload timer ch.3 output pin
	PPG7_2	—		PPG ch.7 output pin (2)
108	P123	—	A	General-purpose I/O port
	OCU1	—		Output compare ch.1 output pin
	PPG8_2	—		PPG ch.8 output pin (2)
109	P124	—	A	General-purpose I/O port
	OCU2	—		Output compare ch.2 output pin
	ICU5_2	—		Input capture ch.5 input pin (2)
	PPG9_2	—		PPG ch.9 output pin (2)
110	P125	—	A	General-purpose I/O port
	OCU3	—		Output compare ch.3 output pin
	ICU0	—		Input capture ch.0 input pin
	PPG10_2	—		PPG ch.10 output pin (2)
90	P126	—	A	General-purpose I/O port
	TRG0	—		PPG trigger 0 input pin(ch.0 to ch.3)
	SIN0	—		Multi-UART ch.0 serial data input pin
	INT1	—		INT1 External interrupt input pin
91	P127	—	K	General-purpose I/O port
	SOT0	—		Multi-UART ch.0 serial data output pin / I ² C ch.0 serial data I/O pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
92	P130	—	K	General-purpose I/O port
	SCK0	—		Multi-UART ch.0 clock I/O pin / I ² C ch.0 clock I/O pin
	INT0	—		INT0 External interrupt input pin
	ICU1	—		Input capture ch.1 input pin
	TIOA0	—		Base timer TIOA0 output pin
93	P131	—	A	General-purpose I/O port
	TRG1	—		PPG trigger 1 input pin (ch.4 to ch.7)
	SIN1	—		Multi-UART ch.1 serial data input pin
	INT4	—		INT4 External interrupt input pin
	ICU2	—		Input capture ch.2 input pin
	TIOA1	—		Base timer TIOA1 output / input pin
94	P132	—	K	General-purpose I/O port
	SOT1	—		Multi-UART ch.1 serial data output pin / I ² C ch.1 serial data I/O pin
	INT2	—		INT2 External interrupt input pin
	ICU3	—		Input capture ch.3 input pin
	TIOB0	—		Base timer TIOB0 input pin
95	P133	—	K	General-purpose I/O port
	TRG5	—		PPG trigger 5 input pin(ch.20 to ch.23)
	PPG11_1	—		PPG ch.11 output pin (1)
	SCK1	—		Multi-UART ch.1 clock I/O pin / I ² C ch.1 clock I/O pin
	INT3	—		INT3 External interrupt input pin
	ICU4	—		Input capture ch.4 input pin
	TIOB1	—		Base timer TIOB1 input pin
96	P134	—	A	General-purpose I/O port
	TRG2	—		PPG trigger 2 input pin (ch.8 to ch.11)
	PPG1_3	—		PPG ch.1 output pin (3)
	INT5	—		INT5 External interrupt input pin
	ICU5	—		Input capture ch.5 input pin
103	DEBUGIF	—	G	DEBUG IF pin
176	PA2	—	O	General-purpose I/O port (3V pin)
	RIN2	—		Capture R2 input pin (RGB mode)
	VIN0	—		Capture VIN0 input pin (656 mode)

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
177	PA3	—	O	General-purpose I/O port (3V pin)
	RIN3	—		Capture R3 input pin (RGB mode)
	VIN1	—		Capture VIN1 input pin (656 mode)
178	PA4	—	O	General-purpose I/O port (3V pin)
	RIN4	—		Capture R4 input pin (RGB mode)
	VIN2	—		Capture VIN2 input pin (656 mode)
179	PA5	—	O	General-purpose I/O port (3V pin)
	RIN5	—		Capture R5 input pin (RGB mode)
	VIN3	—		Capture VIN3 input pin (656 mode)
180	PA6	—	O	General-purpose I/O port (3V pin)
	RIN6	—		Capture R6 input pin (RGB mode)
	VIN4	—		Capture VIN4 input pin (656 mode)
181	PA7	—	O	General-purpose I/O port (3V pin)
	RIN7	—		Capture R7 input pin (RGB mode)
	VIN5	—		Capture VIN5 input pin (656 mode)
182	PB2	—	O	General-purpose I/O port (3V pin)
	GIN2	—		Capture G2 input pin (RGB mode)
	VIN6	—		Capture VIN6 input pin (656 mode)
183	PB3	—	O	General-purpose I/O port (3V pin)
	GIN3	—		Capture G3 input pin (RGB mode)
	VIN7	—		Capture VIN7 input pin (656 mode)
184	PB4	—	O	General-purpose I/O port (3V pin)
	GIN4	—		Capture G4 input pin (RGB mode)
185	PB5	—	O	General-purpose I/O port (3V pin)
	GIN5	—		Capture G5 input pin (RGB mode)
186	PB6	—	O	General-purpose I/O port (3V pin)
	GIN6	—		Capture G6 input pin (RGB mode)
187	PB7	—	O	General-purpose I/O port (3V pin)
	GIN7	—		Capture G7 input pin (RGB mode)
190	PC2	—	O	General-purpose I/O port (3V pin)
	BIN2	—		Capture B2 input pin (RGB mode)
191	PC3	—	O	General-purpose I/O port (3V pin)
	BIN3	—		Capture B3 input pin (RGB mode)
192	PC4	—	O	General-purpose I/O port (3V pin)
	BIN4	—		Capture B4 input pin (RGB mode)

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
193	PC5	—	O	General-purpose I/O port (3V pin)
	BIN5	—		Capture B5 input pin (RGB mode)
194	PC6	—	O	General-purpose I/O port (3V pin)
	BIN6	—		Capture B6 input pin (RGB mode)
195	PC7	—	O	General-purpose I/O port (3V pin)
	BIN7	—		Capture B7 input pin (RGB mode)
2	PD2	—	O	General-purpose I/O port (3V pin)
	ROUT2	—		Display digital R2 output pin
3	PD3	—	O	General-purpose I/O port (3V pin)
	ROUT3	—		Display digital R3 output pin
4	PD4	—	O	General-purpose I/O port (3V pin)
	ROUT4	—		Display digital R4 output pin
5	PD5	—	O	General-purpose I/O port (3V pin)
	ROUT5	—		Display digital R5 output pin
6	PD6	—	O	General-purpose I/O port (3V pin)
	ROUT6	—		Display digital R6 output pin
7	PD7	—	O	General-purpose I/O port (3V pin)
	ROUT7	—		Display digital R7 output pin
8	PE2	—	O	General-purpose I/O port (3V pin)
	GOUT2	—		Display digital G2 output pin
9	PE3	—	O	General-purpose I/O port (3V pin)
	GOUT3	—		Display digital G3 output pin
10	PE4	—	O	General-purpose I/O port (3V pin)
	GOUT4	—		Display digital G4 output pin
11	PE5	—	O	General-purpose I/O port (3V pin)
	GOUT5	—		Display digital G5 output pin
12	PE6	—	O	General-purpose I/O port (3V pin)
	GOUT6	—		Display digital G6 output pin
13	PE7	—	O	General-purpose I/O port (3V pin)
	GOUT7	—		Display digital G7 output pin
14	PF2	—	O	General-purpose I/O port (3V pin)
	BOUT2	—		Display digital B2 output pin
15	PF3	—	O	General-purpose I/O port (3V pin)
	BOUT3	—		Display digital B3 output pin

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
16	PF4	—	O	General-purpose I/O port (3V pin)
	BOUT4	—		Display digital B4 output pin
17	PF5	—	O	General-purpose I/O port (3V pin)
	BOUT5	—		Display digital B5 output pin
21	PF6	—	O	General-purpose I/O port (3V pin)
	BOUT6	—		Display digital B6 output pin
22	PF7	—	O	General-purpose I/O port(3V pin)
	BOUT7	—		Display digital B7 output pin
200	PG0	—	O	General-purpose I/O port (3V pin)
	DCKIN	—		Display reference clock input pin (for External sync)
	CMDTRG	—		GDC command trigger input pin
197	PG1	—	O	General-purpose I/O port (3V pin)
	VSIN	P		Capture vertical sync signal input pin
198	PG2	—	O	General-purpose I/O port (3V pin)
	HSIN	P		Capture horizontal sync signal input pin
199	PG3	—	O	General-purpose I/O port (3V pin)
	CSOUT	—		Display composite sync signal output pin, Graphics/Video switch (for External sync) output pin
23	PG4	—	O	General-purpose I/O port (3V pin)
	DCKOUT	—		Display reference clock output pin (for Internal sync)
24	PG5	—	O	General-purpose I/O port (3V pin)
	VSYNC	—		Display vertical sync signal output pin (for Internal sync), / Display vertical sync signal input pin (for External sync)
25	PG6	—	O	General-purpose I/O port (3V pin)
	HSYNC	—		Display horizontal sync signal output pin (for Internal sync) / Display horizontal sync signal input pin (for External sync)
26	PG7	—	O	General-purpose I/O port (3V pin)
	DEOUT	P		Display enable display period output pin
196	PH3	—	O	General-purpose I/O port (3V pin)
	CCLK	—		For capture, capture clock input pin
204	REFOUT	—	T	Clamp level output pin
203	AVR3	—	S	"L" level reference voltage for NTSC-AD
205	VIN	—	S	NTSC signal input pin
111	AVCC5	—	—	AD converter analog power supply pin
201, 207	AVCC3	—	—	For NTSC, AD converter analog power supply pin
112	AVRH5	—	—	AD converter upper limit reference voltage

Pin no.	Pin Name	Polarity	I/O circuit types	Function (For switching, see "CHAPTER : I/O Port")
113	AVSS5/ AVRL5	—	—	AD converter GND/ AD converter lower limit reference voltage
202, 206	AVSS3	—	—	NTSC AD converter GND pin
124	C_1	—	—	Built-in regulator capacitor connected pin 1
73	C_2	—	—	Built-in regulator capacitor connected pin 2
20	C_3	—	—	Built-in regulator capacitor connected pin 3
126, 136,146, 156	DVCC	—	—	SMC high current port power supply pin
125, 135, 145, 155	DVSS	—	—	SMC high current port GND pin
89, 105, 122, 173	VCC5	—	—	+5.0v power supply pin
1, 18, 37,53, 71,175, 189	VCC3	—	—	+3.3v power supply pin
19, 36, 52, 72, 82, 88, 104, 123, 174, 188, 208	VSS	—	—	GND pin

10. Pins of Each Function

This section shows the pins of each function.

- 10.1. Pins of AD Converter
- 10.2. Pins of CAN (ch.0 to ch.2)
- 10.3. Pins of External Interrupt Input (ch.0 to ch.15)
- 10.4. Pins of LIN-UART (ch.2 to ch.7)
- 10.5. Pins of Multi-function Serial Interface (ch.0, ch.1)
- 10.6. Pins of PPG (ch.0 to ch.23)
- 10.7. Pin of Real Time Clock
- 10.8. Pins of Stepping Motor Controller (ch.0 to ch.5)
- 10.9. Pins of Output Compare (ch.0 to ch.3)
- 10.10. Pins of Input Capture (ch.0 to ch.5)
- 10.11. Pins of Sound Generator (ch.0 to ch.4)
- 10.12. Pins of Free-run Timer (ch.0, ch.1)
- 10.13. Pins of Base Timer (ch.0, ch.1)
- 10.14. Pins of Reload Timer (ch.0 to ch.3)
- 10.15. Pins of External Bus Interface (GDC External Memory I/F)
- 10.16. Pins of SPI Interface (GDC External Memory I/F)
- 10.17. Pins of Port Function (General-purpose I/O)
- 10.18. Pins of GDC (Capture RGB Mode)
- 10.19. Pins of GDC (Capture 656 Mode)
- 10.20. Pins of GDC (Capture Other)
- 10.21. Pins of GDC (Display)
- 10.22. Pins of GDC (NTSC)
- 10.23. Pin of GDC (Other)
- 10.24. Pins of Other

10.1. Pins of AD Converter

Pins of AD converter are shown.

• A/D converter external trigger input	(pin name) ADTG	(pin no.) 157
• ADC Analog 0 input	(pin name) AN0	(pin no.) 114
• ADC Analog 1 input	(pin name) AN1	(pin no.) 115
• ADC Analog 2 input	(pin name) AN2	(pin no.) 116
• ADC Analog 3 input	(pin name) AN3	(pin no.) 117
• ADC Analog 4 input	(pin name) AN4	(pin no.) 118
• ADC Analog 5 input	(pin name) AN5	(pin no.) 119
• ADC Analog 6 input	(pin name) AN6	(pin no.) 120
• ADC Analog 7 input	(pin name) AN7	(pin no.) 121
• ADC Analog 8 input	(pin name) AN8	(pin no.) 127
• ADC Analog 9 input	(pin name) AN9	(pin no.) 128
• ADC Analog 10 input	(pin name) AN10	(pin no.) 129
• ADC Analog 11 input	(pin name) AN11	(pin no.) 130
• ADC Analog 12 input	(pin name) AN12	(pin no.) 131
• ADC Analog 13 input	(pin name) AN13	(pin no.) 132
• ADC Analog 14 input	(pin name) AN14	(pin no.) 133
• ADC Analog 15 input	(pin name) AN15	(pin no.) 134
• ADC Analog 16 input	(pin name) AN16	(pin no.) 137
• ADC Analog 17 input	(pin name) AN17	(pin no.) 138
• ADC Analog 18 input	(pin name) AN18	(pin no.) 139
• ADC Analog 19 input	(pin name) AN19	(pin no.) 140
• ADC Analog 20 input	(pin name) AN20	(pin no.) 141
• ADC Analog 21 input	(pin name) AN21	(pin no.) 142
• ADC Analog 22 input	(pin name) AN22	(pin no.) 143
• ADC Analog 23 input	(pin name) AN23	(pin no.) 144
• ADC Analog 24 input	(pin name) AN24	(pin no.) 147
• ADC Analog 25 input	(pin name) AN25	(pin no.) 148
• ADC Analog 26 input	(pin name) AN26	(pin no.) 149
• ADC Analog 27 input	(pin name) AN27	(pin no.) 150
• ADC Analog 28 input	(pin name) AN28	(pin no.) 151
• ADC Analog 29 input	(pin name) AN29	(pin no.) 152
• ADC Analog 30 input	(pin name) AN30	(pin no.) 153
• ADC Analog 31 input	(pin name) AN31	(pin no.) 154
• AD converter analog power supply	(pin name) AVCC5	(pin no.) 111
• AD converter upper limit reference voltage	(pin name) AVRH5	(pin no.) 112
• AD converter GND/ AD converter lower limit reference voltage	(pin name) AVSS5/AVRL5	(pin no.) 113

10.2. Pins of CAN (ch.0 to ch.2)

Pins of CAN are shown.

• CAN reception data 0 input	(pin name) RX0	(pin no.) 107
• CAN reception data 1 input	(pin name) RX1	(pin no.) 102
• CAN reception data 2 input	(pin name) RX2	(pin no.) 159
• CAN transmission data 0 output	(pin name) TX0	(pin no.) 106
• CAN transmission data 1 output	(pin name) TX1	(pin no.) 101
• CAN transmission data 2 output	(pin name) TX2	(pin no.) 158

10.3. Pins of External Interrupt Input (ch.0 to ch.15)

Pins of external interrupt input are shown.

• INT0 External interrupt input	(pin name) INT0	(pin no.) 92
• INT1 External interrupt input	(pin name) INT1	(pin no.) 90
• INT2 External interrupt input	(pin name) INT2	(pin no.) 94
• INT3 External interrupt input	(pin name) INT3	(pin no.) 95
• INT4 External interrupt input	(pin name) INT4	(pin no.) 93
• INT5 External interrupt input	(pin name) INT5	(pin no.) 96
• INT6 External interrupt input	(pin name) INT6	(pin no.)166
• INT7 External interrupt input	(pin name) INT7	(pin no.)167
• INT8 External interrupt input	(pin name) INT8	(pin no.)161
• INT9 External interrupt input	(pin name) INT9	(pin no.)107
• INT10 External interrupt input	(pin name) INT10	(pin no.)102
• INT11 External interrupt input	(pin name) INT11	(pin no.)159
• INT12 External interrupt input	(pin name) INT12	(pin no.) 98
• INT13 External interrupt input	(pin name) INT13	(pin no.) 99
• INT14 External interrupt input	(pin name) INT14	(pin no.)100
• INT15 External interrupt input	(pin name) INT15	(pin no.)160

10.4. Pins of LIN-UART (ch.2 to ch.7)

Pins of LIN-UART are shown.

• LIN-UART ch.2 clock I/O	(pin name) SCK2	(pin no.) 99
• LIN-UART ch.2 clock I/O (1)	(pin name) SCK2_1	(pin no.) 29
• LIN-UART ch.2 serial data output	(pin name) SOT2	(pin no.)100
• LIN-UART ch.2 serial data output (1)	(pin name) SOT2_1	(pin no.) 28
• LIN-UART ch.2 serial data input	(pin name) SIN2	(pin no.) 98
• LIN-UART ch.2 serial data input (1)	(pin name) SIN2_1	(pin no.) 27
• LIN-UART ch.3 clock I/O	(pin name) SCK3	(pin no.)162
• LIN-UART ch.3 clock I/O (1)	(pin name) SCK3_1	(pin no.) 32
• LIN-UART ch.3 serial data output	(pin name) SOT3	(pin no.)161
• LIN-UART ch.3 serial data output (1)	(pin name) SOT3_1	(pin no.) 31
• LIN-UART ch.3 serial data input	(pin name) SIN3	(pin no.)160
• LIN-UART ch.3 serial data input (1)	(pin name) SIN3_1	(pin no.) 30
• LIN-UART ch.4 clock I/O	(pin name) SCK4	(pin no.)165
• LIN-UART ch.4 clock I/O (1)	(pin name) SCK4_1	(pin no.)116
• LIN-UART ch.4 serial data output	(pin name) SOT4	(pin no.)164
• LIN-UART ch.4 serial data output (1)	(pin name) SOT4_1	(pin no.)115
• LIN-UART ch.4 serial data input	(pin name) SIN4	(pin no.)163
• LIN-UART ch.4 serial data input (1)	(pin name) SIN4_1	(pin no.)114
• LIN-UART ch.5 clock I/O	(pin name) SCK5	(pin no.)168
• LIN-UART ch.5 clock I/O (1)	(pin name) SCK5_1	(pin no.)119
• LIN-UART ch.5 serial data output	(pin name) SOT5	(pin no.)167
• LIN-UART ch.5 serial data output (1)	(pin name) SOT5_1	(pin no.)118
• LIN-UART ch.5 serial data input	(pin name) SIN5	(pin no.)166
• LIN-UART ch.5 serial data input (1)	(pin name) SIN5_1	(pin no.)117
• LIN-UART ch.6 clock I/O	(pin name) SCK6	(pin no.)149
• LIN-UART ch.6 serial data output	(pin name) SOT6	(pin no.)148
• LIN-UART ch.6 serial data input	(pin name) SIN6	(pin no.)147
• LIN-UART ch.7 clock I/O	(pin name) SCK7_1	(pin no.)144
• LIN-UART ch.7 serial data output	(pin name) SOT7_1	(pin no.)143
• LIN-UART ch.7 serial data input	(pin name) SIN7_1	(pin no.)142

10.5. Pins of Multi-function Serial Interface (ch.0, ch.1)

Pins of multi-function serial interface are shown.

- | | | |
|-----------------------------------------------------------------------|-----------------|--------------|
| • MFS ch.0 clock I/O / I ² C ch.0 clock I/O | (pin name) SCK0 | (pin no.) 92 |
| • MFS ch.0 serial data output / I ² C ch.0 serial data I/O | (pin name) SOT0 | (pin no.) 91 |
| • MFS ch.0 serial data input | (pin name) SIN0 | (pin no.) 90 |
| • MFS ch.1 clock I/O / I ² C ch.1 clock I/O | (pin name) SCK1 | (pin no.) 95 |
| • MFS ch.1 serial data output / I ² C ch.1 serial data I/O | (pin name) SOT1 | (pin no.) 94 |
| • MFS ch.1 serial data input | (pin name) SIN1 | (pin no.) 93 |

10.6. Pins of PPG (ch.0 to ch.23)

Pins of PPG are shown.

• PPG ch.0 output	(pin name) PPG0	(pin no.) 27
• PPG ch.0 output (1)	(pin name) PPG0_1	(pin no.)161
• PPG ch.0 output (2)	(pin name) PPG0_2	(pin no.)157
• PPG ch.1 output	(pin name) PPG1	(pin no.) 28
• PPG ch.1 output (1)	(pin name) PPG1_1	(pin no.)117
• PPG ch.1 output (2)	(pin name) PPG1_2	(pin no.)101
• PPG ch.1 output (3)	(pin name) PPG1_3	(pin no.) 96
• PPG ch.2 output	(pin name) PPG2	(pin no.) 29
• PPG ch.2 output (1)	(pin name) PPG2_1	(pin no.)118
• PPG ch.2 output (2)	(pin name) PPG2_2	(pin no.)102
• PPG ch.3 output	(pin name) PPG3	(pin no.) 30
• PPG ch.3 output (1)	(pin name) PPG3_1	(pin no.)119
• PPG ch.3 output (2)	(pin name) PPG3_2	(pin no.)158
• PPG ch.4 output	(pin name) PPG4	(pin no.) 31
• PPG ch.4 output (1)	(pin name) PPG4_1	(pin no.)120
• PPG ch.4 output (2)	(pin name) PPG4_2	(pin no.)159
• PPG ch.5 output	(pin name) PPG5	(pin no.) 32
• PPG ch.5 output (1)	(pin name) PPG5_1	(pin no.)121
• PPG ch.5 output (2)	(pin name) PPG5_2	(pin no.)166
• PPG ch.6 output	(pin name) PPG6	(pin no.) 33
• PPG ch.6 output (1)	(pin name) PPG6_1	(pin no.) 98
• PPG ch.6 output (2)	(pin name) PPG6_2	(pin no.)167
• PPG ch.7 output	(pin name) PPG7	(pin no.) 34
• PPG ch.7 output (1)	(pin name) PPG7_1	(pin no.) 99
• PPG ch.7 output (2)	(pin name) PPG7_2	(pin no.)168
• PPG ch.8 output	(pin name) PPG8	(pin no.)114
• PPG ch.8 output (1)	(pin name) PPG8_1	(pin no.)100
• PPG ch.8 output (2)	(pin name) PPG8_2	(pin no.)108
• PPG ch.9 output	(pin name) PPG9	(pin no.)115
• PPG ch.9 output (1)	(pin name) PPG9_1	(pin no.)160
• PPG ch.9 output (2)	(pin name) PPG9_2	(pin no.)109
• PPG ch.10 output	(pin name) PPG10	(pin no.)116
• PPG ch.10 output (1)	(pin name) PPG10_1	(pin no.)106
• PPG ch.10 output (2)	(pin name) PPG10_2	(pin no.)110
• PPG ch.11 output (1)	(pin name) PPG11_1	(pin no.) 95
• PPG ch.12 output (1)	(pin name) PPG12_1	(pin no.)141
• PPG ch.13 output (1)	(pin name) PPG13_1	(pin no.)142
• PPG ch.14 output (1)	(pin name) PPG14_1	(pin no.)143
• PPG ch.15 output (1)	(pin name) PPG15_1	(pin no.)144
• PPG ch.16 output	(pin name) PPG16	(pin no.)147
• PPG ch.17 output	(pin name) PPG17	(pin no.)148
• PPG ch.18 output	(pin name) PPG18	(pin no.)149
• PPG ch.19 output	(pin name) PPG19	(pin no.)150
• PPG ch.20 output	(pin name) PPG20	(pin no.)151
• PPG ch.21 output	(pin name) PPG21	(pin no.)152
• PPG ch.22 output	(pin name) PPG22	(pin no.)153
• PPG ch.23 output	(pin name) PPG23	(pin no.)154
• PPG trigger 0 input (ch.0 to ch.3)	(pin name) TRG0	(pin no.) 90
• PPG trigger 1 input (ch.4 to ch.7)	(pin name) TRG1	(pin no.) 93
• PPG trigger 2 input (ch.8 to ch.11)	(pin name) TRG2	(pin no.) 96
• PPG trigger 3 input (ch.12 to ch.15)	(pin name) TRG3	(pin no.)162

- PPG trigger 4 input (ch.16 to ch.19) (pin name) TRG4 (pin no.)165
- PPG trigger 5 input (ch.20 to ch.23) (pin name) TRG5 (pin no.) 95

10.7. Pin of Real Time Clock

Pin of real time clock is shown.

• RTC overflow output

(pin name) WOT

(pin no.) 161

10.8. Pins of Stepping Motor Controller (ch.0 to ch.5)

Pins of stepping motor controller are shown.

• SMC ch.0 output	(pin name) PWM1M0	(pin no.) 128
• SMC ch.0 output	(pin name) PWM1P0	(pin no.) 127
• SMC ch.0 output	(pin name) PWM2M0	(pin no.) 130
• SMC ch.0 output	(pin name) PWM2P0	(pin no.) 129
• SMC ch.1 output	(pin name) PWM1M1	(pin no.) 132
• SMC ch.1 output	(pin name) PWM1P1	(pin no.) 131
• SMC ch.1 output	(pin name) PWM2M1	(pin no.) 134
• SMC ch.1 output	(pin name) PWM2P1	(pin no.) 133
• SMC ch.2 output	(pin name) PWM1M2	(pin no.) 138
• SMC ch.2 output	(pin name) PWM1P2	(pin no.) 137
• SMC ch.2 output	(pin name) PWM2M2	(pin no.) 140
• SMC ch.2 output	(pin name) PWM2P2	(pin no.) 139
• SMC ch.3 output	(pin name) PWM1M3	(pin no.) 142
• SMC ch.3 output	(pin name) PWM1P3	(pin no.) 141
• SMC ch.3 output	(pin name) PWM2M3	(pin no.) 144
• SMC ch.3 output	(pin name) PWM2P3	(pin no.) 143
• SMC ch.4 output	(pin name) PWM1M4	(pin no.) 148
• SMC ch.4 output	(pin name) PWM1P4	(pin no.) 147
• SMC ch.4 output	(pin name) PWM2M4	(pin no.) 150
• SMC ch.4 output	(pin name) PWM2P4	(pin no.) 149
• SMC ch.5 output	(pin name) PWM1M5	(pin no.) 152
• SMC ch.5 output	(pin name) PWM1P5	(pin no.) 151
• SMC ch.5 output	(pin name) PWM2M5	(pin no.) 154
• SMC ch.5 output	(pin name) PWM2P5	(pin no.) 153
• SMC high current port GND	(pin name) DVSS	(pin no.) 125,135,145,155
• SMC high current port power supply	(pin name) DVCC	(pin no.) 126,136,146,156

10.9. Pins of Output Compare (ch.0 to ch.3)

Pins of output compare are shown.

- | | | |
|------------------------------|-----------------|---------------|
| • Output compare ch.0 output | (pin name) OCU0 | (pin no.) 168 |
| • Output compare ch.1 output | (pin name) OCU1 | (pin no.) 108 |
| • Output compare ch.2 output | (pin name) OCU2 | (pin no.) 109 |
| • Output compare ch.3 output | (pin name) OCU3 | (pin no.) 110 |

10.10. Pins of Input Capture (ch.0 to ch.5)

Pins of input capture are shown.

• Input capture ch.0 input	(pin name) ICU0	(pin no.) 110
• Input capture ch.0 input (1)	(pin name) ICU0_1	(pin no.) 99
• Input capture ch.0 input (2)	(pin name) ICU0_2	(pin no.) 150
• Input capture ch.1 input	(pin name) ICU1	(pin no.) 92
• Input capture ch.1 input (1)	(pin name) ICU1_1	(pin no.) 160
• Input capture ch.1 input (2)	(pin name) ICU1_2	(pin no.) 151
• Input capture ch.2 input	(pin name) ICU2	(pin no.) 93
• Input capture ch.2 input (1)	(pin name) ICU2_1	(pin no.) 98
• Input capture ch.2 input (2)	(pin name) ICU2_2	(pin no.) 152
• Input capture ch.3 input	(pin name) ICU3	(pin no.) 94
• Input capture ch.3 input (1)	(pin name) ICU3_1	(pin no.) 100
• Input capture ch.3 input (2)	(pin name) ICU3_2	(pin no.) 153
• Input capture ch.4 input	(pin name) ICU4	(pin no.) 95
• Input capture ch.4 input (1)	(pin name) ICU4_1	(pin no.) 161
• Input capture ch.4 input (2)	(pin name) ICU4_2	(pin no.) 154
• Input capture ch.5 input	(pin name) ICU5	(pin no.) 96
• Input capture ch.5 input (1)	(pin name) ICU5_1	(pin no.) 162
• Input capture ch.5 input (2)	(pin name) ICU5_2	(pin no.) 109

10.11. Pins of Sound Generator (ch.0 to ch.4)

Pins of sound generator are shown.

- | | | |
|-----------------------------------|-------------------|---------------|
| • Sound generator ch.0 SGA output | (pin name) SGA0 | (pin no.) 98 |
| • Sound generator ch.0 SGO output | (pin name) SGO0 | (pin no.) 99 |
| • Sound generator ch.1 SGA output | (pin name) SGA1 | (pin no.) 100 |
| • Sound generator ch.1 SGO output | (pin name) SGO1 | (pin no.) 160 |
| • Sound generator ch.2 SGA output | (pin name) SGA2 | (pin no.) 162 |
| • Sound generator ch.2 SGO output | (pin name) SGO2 | (pin no.) 163 |
| • Sound generator ch.3 SGA output | (pin name) SGA3 | (pin no.) 164 |
| • Sound generator ch.3 SGO output | (pin name) SGO3 | (pin no.) 165 |
| • Sound generator ch.4 SGA output | (pin name) SGA4_1 | (pin no.) 120 |
| • Sound generator ch.4 SGO output | (pin name) SGO4_1 | (pin no.) 121 |

10.12. Pins of Free-run Timer (ch.0, ch.1)

Pins of free-run timer are shown.

- Free-run timer 0 clock input (pin name) FRCK0 (pin no.) 167
- Free-run timer 1 clock input (pin name) FRCK1 (pin no.) 166

10.13. Pins of Base Timer (ch.0, ch.1)

Pins of base timer are shown.

- | | | |
|---------------------------------|------------------|--------------|
| • Base timer TIOA0 output | (pin name) TIOA0 | (pin no.) 92 |
| • Base timer TIOB0 input | (pin name) TIOB0 | (pin no.) 94 |
| • Base timer TIOA1 output/input | (pin name) TIOA1 | (pin no.) 93 |
| • Base timer TIOB1 input | (pin name) TIOB1 | (pin no.) 95 |

10.14. Pins of Reload Timer (ch.0 to ch.3)

Pins of reload timer are shown.

• Reload timer ch.0 event input	(pin name) TIN0	(pin no.) 161
• Reload timer ch.0 event input (1)	(pin name) TIN0_1	(pin no.) 114
• Reload timer ch.0 event input (2)	(pin name) TIN0_2	(pin no.) 27
• Reload timer ch.0 output	(pin name) TOT0	(pin no.) 165
• Reload timer ch.0 output (1)	(pin name) TOT0_1	(pin no.) 118
• Reload timer ch.0 output (2)	(pin name) TOT0_2	(pin no.) 31
• Reload timer ch.1 event input	(pin name) TIN1	(pin no.) 162
• Reload timer ch.1 event input (1)	(pin name) TIN1_1	(pin no.) 115
• Reload timer ch.1 event input (2)	(pin name) TIN1_2	(pin no.) 28
• Reload timer ch.1 output	(pin name) TOT1	(pin no.) 166
• Reload timer ch.1 output (1)	(pin name) TOT1_1	(pin no.) 119
• Reload timer ch.1 output (2)	(pin name) TOT1_2	(pin no.) 32
• Reload timer ch.2 event input	(pin name) TIN2	(pin no.) 163
• Reload timer ch.2 event input (1)	(pin name) TIN2_1	(pin no.) 116
• Reload timer ch.2 event input (2)	(pin name) TIN2_2	(pin no.) 29
• Reload timer ch.2 output	(pin name) TOT2	(pin no.) 167
• Reload timer ch.2 output (1)	(pin name) TOT2_1	(pin no.) 98
• Reload timer ch.2 output (2)	(pin name) TOT2_2	(pin no.) 33
• Reload timer ch.3 event input	(pin name) TIN3	(pin no.) 164
• Reload timer ch.3 event input (1)	(pin name) TIN3_1	(pin no.) 117
• Reload timer ch.3 event input (2)	(pin name) TIN3_2	(pin no.) 30
• Reload timer ch.3 output	(pin name) TOT3	(pin no.) 168
• Reload timer ch.3 output (1)	(pin name) TOT3_1	(pin no.) 99
• Reload timer ch.3 output (2)	(pin name) TOT3_2	(pin no.) 34

10.15. Pins of External Bus Interface (GDC External Memory I/F)

Pins of external bus interface (GDC external memory I/F) are shown.

• External bus/Wait input	(pin name) RDY	(pin no.) 81
• External bus/Address bit0 output	(pin name) A00	(pin no.) 51
• External bus/Address bit1 output	(pin name) A01	(pin no.) 54
• External bus/Address bit2 output	(pin name) A02	(pin no.) 55
• External bus/Address bit3 output	(pin name) A03	(pin no.) 56
• External bus/Address bit4 output	(pin name) A04	(pin no.) 57
• External bus/Address bit5 output	(pin name) A05	(pin no.) 58
• External bus/Address bit6 output	(pin name) A06	(pin no.) 59
• External bus/Address bit7 output	(pin name) A07	(pin no.) 60
• External bus/Address bit8 output	(pin name) A08	(pin no.) 61
• External bus/Address bit9 output	(pin name) A09	(pin no.) 62
• External bus/Address bit10 output	(pin name) A10	(pin no.) 63
• External bus/Address bit11 output	(pin name) A11	(pin no.) 64
• External bus/Address bit12 output	(pin name) A12	(pin no.) 65
• External bus/Address bit13 output	(pin name) A13	(pin no.) 66
• External bus/Address bit14 output	(pin name) A14	(pin no.) 67
• External bus/Address bit15 output	(pin name) A15	(pin no.) 68
• External bus/Address bit16 output	(pin name) A16	(pin no.) 69
• External bus/Address bit17 output	(pin name) A17	(pin no.) 70
• External bus/Address bit18 output	(pin name) A18	(pin no.) 74
• External bus/Address bit19 output	(pin name) A19	(pin no.) 75
• External bus/Address bit20 output	(pin name) A20	(pin no.) 76
• External bus/Address bit21 output	(pin name) A21	(pin no.) 77
• External bus/Address bit22 output	(pin name) A22	(pin no.) 78
• External bus/Address bit23 output	(pin name) A23	(pin no.) 79
• External bus/Address bit24 output	(pin name) A24	(pin no.) 80
• External bus/Write enable output	(pin name) WEX	(pin no.) 45
• External bus/Read enable output	(pin name) REX	(pin no.) 48
• External bus/Chip select 0 output	(pin name) CS0X	(pin no.) 46
• External bus/Chip select 1 output	(pin name) CS1X	(pin no.) 47
• External bus/Data bit 0 I/O	(pin name) D0	(pin no.) 27
• External bus/Data bit 1 I/O	(pin name) D1	(pin no.) 28
• External bus/Data bit 2 I/O	(pin name) D2	(pin no.) 29
• External bus/Data bit 3 I/O	(pin name) D3	(pin no.) 30
• External bus/Data bit 4 I/O	(pin name) D4	(pin no.) 31
• External bus/Data bit 5 I/O	(pin name) D5	(pin no.) 32
• External bus/Data bit 6 I/O	(pin name) D6	(pin no.) 33
• External bus/Data bit 7 I/O	(pin name) D7	(pin no.) 34
• External bus/Data bit 8 I/O	(pin name) D8	(pin no.) 35
• External bus/Data bit 9 I/O	(pin name) D9	(pin no.) 38
• External bus/Data bit10 I/O	(pin name) D10	(pin no.) 39
• External bus/Data bit11 I/O	(pin name) D11	(pin no.) 40
• External bus/Data bit12 I/O	(pin name) D12	(pin no.) 41
• External bus/Data bit13 I/O	(pin name) D13	(pin no.) 42
• External bus/Data bit14 I/O	(pin name) D14	(pin no.) 43
• External bus/Data bit15 I/O	(pin name) D15	(pin no.) 44

10.16. Pins of SPI Interface (GDC External Memory I/F)

Pins of SPI interface (GDC external memory I/F) are shown.

• SPI data output	(pin name) SPI_DO	(pin no.) 77
• SPI data input	(pin name) SPI_DI	(pin no.) 78
• SPI clock output	(pin name) SPI_SCK	(pin no.) 79
• SPI chip select output	(pin name) SPI_XCS	(pin no.) 80

10.17. Pins of Port Function (General-purpose I/O)

Pins of port function (general-purpose I/O) are shown.

• General-purpose I/O port (3V pin)	(pin name) P000	(pin no.) 27
• General-purpose I/O port (3V pin)	(pin name) P001	(pin no.) 28
• General-purpose I/O port (3V pin)	(pin name) P002	(pin no.) 29
• General-purpose I/O port (3V pin)	(pin name) P003	(pin no.) 30
• General-purpose I/O port (3V pin)	(pin name) P004	(pin no.) 31
• General-purpose I/O port (3V pin)	(pin name) P005	(pin no.) 32
• General-purpose I/O port (3V pin)	(pin name) P006	(pin no.) 33
• General-purpose I/O port (3V pin)	(pin name) P007	(pin no.) 34
• General-purpose I/O port (3V pin)	(pin name) P010	(pin no.) 35
• General-purpose I/O port (3V pin)	(pin name) P011	(pin no.) 38
• General-purpose I/O port (3V pin)	(pin name) P012	(pin no.) 39
• General-purpose I/O port (3V pin)	(pin name) P013	(pin no.) 40
• General-purpose I/O port (3V pin)	(pin name) P014	(pin no.) 41
• General-purpose I/O port (3V pin)	(pin name) P015	(pin no.) 42
• General-purpose I/O port (3V pin)	(pin name) P016	(pin no.) 43
• General-purpose I/O port (3V pin)	(pin name) P017	(pin no.) 44
• General-purpose I/O port (3V pin)	(pin name) P020	(pin no.) 45
• General-purpose I/O port (3V pin)	(pin name) P021	(pin no.) 46
• General-purpose I/O port (3V pin)	(pin name) P022	(pin no.) 47
• General-purpose I/O port (3V pin)	(pin name) P023	(pin no.) 48
• General-purpose I/O port (3V pin)	(pin name) P024	(pin no.) 49
• General-purpose I/O port (3V pin)	(pin name) P025	(pin no.) 50
• General-purpose I/O port (3V pin)	(pin name) P026	(pin no.) 51
• General-purpose I/O port (3V pin)	(pin name) P027	(pin no.) 54
• General-purpose I/O port (3V pin)	(pin name) P030	(pin no.) 55
• General-purpose I/O port (3V pin)	(pin name) P031	(pin no.) 56
• General-purpose I/O port (3V pin)	(pin name) P032	(pin no.) 57
• General-purpose I/O port (3V pin)	(pin name) P033	(pin no.) 58
• General-purpose I/O port (3V pin)	(pin name) P034	(pin no.) 59
• General-purpose I/O port (3V pin)	(pin name) P035	(pin no.) 60
• General-purpose I/O port (3V pin)	(pin name) P036	(pin no.) 61
• General-purpose I/O port (3V pin)	(pin name) P037	(pin no.) 62
• General-purpose I/O port (3V pin)	(pin name) P040	(pin no.) 63
• General-purpose I/O port (3V pin)	(pin name) P041	(pin no.) 64
• General-purpose I/O port (3V pin)	(pin name) P042	(pin no.) 65
• General-purpose I/O port (3V pin)	(pin name) P043	(pin no.) 66
• General-purpose I/O port (3V pin)	(pin name) P044	(pin no.) 67
• General-purpose I/O port (3V pin)	(pin name) P045	(pin no.) 68
• General-purpose I/O port (3V pin)	(pin name) P046	(pin no.) 69
• General-purpose I/O port (3V pin)	(pin name) P047	(pin no.) 70
• General-purpose I/O port (3V pin)	(pin name) P050	(pin no.) 74
• General-purpose I/O port (3V pin)	(pin name) P051	(pin no.) 75
• General-purpose I/O port (3V pin)	(pin name) P052	(pin no.) 76
• General-purpose I/O port (3V pin)	(pin name) P053	(pin no.) 77
• General-purpose I/O port (3V pin)	(pin name) P054	(pin no.) 78
• General-purpose I/O port (3V pin)	(pin name) P055	(pin no.) 79
• General-purpose I/O port (3V pin)	(pin name) P056	(pin no.) 80
• General-purpose I/O port (3V pin)	(pin name) P057	(pin no.) 81
• General-purpose I/O port	(pin name) P060	(pin no.) 127
• General-purpose I/O port	(pin name) P061	(pin no.) 128
• General-purpose I/O port	(pin name) P062	(pin no.) 129

• General-purpose I/O port	(pin name) P063	(pin no.) 130
• General-purpose I/O port	(pin name) P064	(pin no.) 131
• General-purpose I/O port	(pin name) P065	(pin no.) 132
• General-purpose I/O port	(pin name) P066	(pin no.) 133
• General-purpose I/O port	(pin name) P067	(pin no.) 134
• General-purpose I/O port	(pin name) P070	(pin no.) 137
• General-purpose I/O port	(pin name) P071	(pin no.) 138
• General-purpose I/O port	(pin name) P072	(pin no.) 139
• General-purpose I/O port	(pin name) P073	(pin no.) 140
• General-purpose I/O port	(pin name) P074	(pin no.) 141
• General-purpose I/O port	(pin name) P075	(pin no.) 142
• General-purpose I/O port	(pin name) P076	(pin no.) 143
• General-purpose I/O port	(pin name) P077	(pin no.) 144
• General-purpose I/O port	(pin name) P080	(pin no.) 147
• General-purpose I/O port	(pin name) P081	(pin no.) 148
• General-purpose I/O port	(pin name) P082	(pin no.) 149
• General-purpose I/O port	(pin name) P083	(pin no.) 150
• General-purpose I/O port	(pin name) P084	(pin no.) 151
• General-purpose I/O port	(pin name) P085	(pin no.) 152
• General-purpose I/O port	(pin name) P086	(pin no.) 153
• General-purpose I/O port	(pin name) P087	(pin no.) 154
• General-purpose I/O port	(pin name) P090	(pin no.) 157
• General-purpose I/O port	(pin name) P091	(pin no.) 98
• General-purpose I/O port	(pin name) P092	(pin no.) 99
• General-purpose I/O port	(pin name) P093	(pin no.) 100
• General-purpose I/O port	(pin name) P094	(pin no.) 160
• General-purpose I/O port	(pin name) P095	(pin no.) 106
• General-purpose I/O port	(pin name) P096	(pin no.) 107
• General-purpose I/O port	(pin name) P097	(pin no.) 161
• General-purpose I/O port	(pin name) P100	(pin no.) 114
• General-purpose I/O port	(pin name) P101	(pin no.) 115
• General-purpose I/O port	(pin name) P102	(pin no.) 116
• General-purpose I/O port	(pin name) P103	(pin no.) 117
• General-purpose I/O port	(pin name) P104	(pin no.) 118
• General-purpose I/O port	(pin name) P105	(pin no.) 119
• General-purpose I/O port	(pin name) P106	(pin no.) 120
• General-purpose I/O port	(pin name) P107	(pin no.) 121
• General-purpose I/O port	(pin name) P110	(pin no.) 101
• General-purpose I/O port	(pin name) P111	(pin no.) 102
• General-purpose I/O port	(pin name) P112	(pin no.) 158
• General-purpose I/O port	(pin name) P113	(pin no.) 159
• General-purpose I/O port	(pin name) P114	(pin no.) 162
• General-purpose I/O port	(pin name) P115	(pin no.) 163
• General-purpose I/O port	(pin name) P116	(pin no.) 164
• General-purpose I/O port	(pin name) P117	(pin no.) 165
• General-purpose I/O port	(pin name) P120	(pin no.) 166
• General-purpose I/O port	(pin name) P121	(pin no.) 167
• General-purpose I/O port	(pin name) P122	(pin no.) 168
• General-purpose I/O port	(pin name) P123	(pin no.) 108
• General-purpose I/O port	(pin name) P124	(pin no.) 109
• General-purpose I/O port	(pin name) P125	(pin no.) 110
• General-purpose I/O port	(pin name) P126	(pin no.) 90
• General-purpose I/O port	(pin name) P127	(pin no.) 91
• General-purpose I/O port	(pin name) P130	(pin no.) 92
• General-purpose I/O port	(pin name) P131	(pin no.) 93
• General-purpose I/O port	(pin name) P132	(pin no.) 94
• General-purpose I/O port	(pin name) P133	(pin no.) 95
• General-purpose I/O port	(pin name) P134	(pin no.) 96

• General-purpose I/O port(single clock product)	(pin name) P136	(pin no.) 172
• General-purpose I/O port(single clock product)	(pin name) P137	(pin no.) 171
• General-purpose I/O port (3V pin)	(pin name) PA2	(pin no.) 176
• General-purpose I/O port (3V pin)	(pin name) PA3	(pin no.) 177
• General-purpose I/O port (3V pin)	(pin name) PA4	(pin no.) 178
• General-purpose I/O port (3V pin)	(pin name) PA5	(pin no.) 179
• General-purpose I/O port (3V pin)	(pin name) PA6	(pin no.) 180
• General-purpose I/O port (3V pin)	(pin name) PA7	(pin no.) 181
• General-purpose I/O port (3V pin)	(pin name) PB2	(pin no.) 182
• General-purpose I/O port (3V pin)	(pin name) PB3	(pin no.) 183
• General-purpose I/O port (3V pin)	(pin name) PB4	(pin no.) 184
• General-purpose I/O port (3V pin)	(pin name) PB5	(pin no.) 185
• General-purpose I/O port (3V pin)	(pin name) PB6	(pin no.) 186
• General-purpose I/O port (3V pin)	(pin name) PB7	(pin no.) 187
• General-purpose I/O port (3V pin)	(pin name) PC2	(pin no.) 190
• General-purpose I/O port (3V pin)	(pin name) PC3	(pin no.) 191
• General-purpose I/O port (3V pin)	(pin name) PC4	(pin no.) 192
• General-purpose I/O port (3V pin)	(pin name) PC5	(pin no.) 193
• General-purpose I/O port (3V pin)	(pin name) PC6	(pin no.) 194
• General-purpose I/O port (3V pin)	(pin name) PC7	(pin no.) 195
• General-purpose I/O port (3V pin)	(pin name) PD2	(pin no.) 2
• General-purpose I/O port (3V pin)	(pin name) PD3	(pin no.) 3
• General-purpose I/O port (3V pin)	(pin name) PD4	(pin no.) 4
• General-purpose I/O port (3V pin)	(pin name) PD5	(pin no.) 5
• General-purpose I/O port (3V pin)	(pin name) PD6	(pin no.) 6
• General-purpose I/O port (3V pin)	(pin name) PD7	(pin no.) 7
• General-purpose I/O port (3V pin)	(pin name) PE2	(pin no.) 8
• General-purpose I/O port (3V pin)	(pin name) PE3	(pin no.) 9
• General-purpose I/O port (3V pin)	(pin name) PE4	(pin no.) 10
• General-purpose I/O port (3V pin)	(pin name) PE5	(pin no.) 11
• General-purpose I/O port (3V pin)	(pin name) PE6	(pin no.) 12
• General-purpose I/O port (3V pin)	(pin name) PE7	(pin no.) 13
• General-purpose I/O port (3V pin)	(pin name) PF2	(pin no.) 14
• General-purpose I/O port (3V pin)	(pin name) PF3	(pin no.) 15
• General-purpose I/O port (3V pin)	(pin name) PF4	(pin no.) 16
• General-purpose I/O port (3V pin)	(pin name) PF5	(pin no.) 17
• General-purpose I/O port (3V pin)	(pin name) PF6	(pin no.) 21
• General-purpose I/O port (3V pin)	(pin name) PF7	(pin no.) 22
• General-purpose I/O port (3V pin)	(pin name) PG0	(pin no.) 200
• General-purpose I/O port (3V pin)	(pin name) PG1	(pin no.) 197
• General-purpose I/O port (3V pin)	(pin name) PG2	(pin no.) 198
• General-purpose I/O port (3V pin)	(pin name) PG3	(pin no.) 199
• General-purpose I/O port (3V pin)	(pin name) PG4	(pin no.) 23
• General-purpose I/O port (3V pin)	(pin name) PG5	(pin no.) 24
• General-purpose I/O port (3V pin)	(pin name) PG6	(pin no.) 25
• General-purpose I/O port (3V pin)	(pin name) PG7	(pin no.) 26
• General-purpose I/O port (3V pin)	(pin name) PH3	(pin no.) 196

Note:

P135 is a missing number.

10.18. Pins of GDC (Capture RGB Mode)

Pins of GDC (Capture RGB mode) are shown.

• Capture R2 input (RGB mode)	(pin name) RIN2	(pin no.) 176
• Capture R3 input (RGB mode)	(pin name) RIN3	(pin no.) 177
• Capture R4 input (RGB mode)	(pin name) RIN4	(pin no.) 178
• Capture R5 input (RGB mode)	(pin name) RIN5	(pin no.) 179
• Capture R6 input (RGB mode)	(pin name) RIN6	(pin no.) 180
• Capture R7 input (RGB mode)	(pin name) RIN7	(pin no.) 181
• Capture G2 input (RGB mode)	(pin name) GIN2	(pin no.) 182
• Capture G3 input (RGB mode)	(pin name) GIN3	(pin no.) 183
• Capture G4 input (RGB mode)	(pin name) GIN4	(pin no.) 184
• Capture G5 input (RGB mode)	(pin name) GIN5	(pin no.) 185
• Capture G6 input (RGB mode)	(pin name) GIN6	(pin no.) 186
• Capture G7 input (RGB mode)	(pin name) GIN7	(pin no.) 187
• Capture B2 input (RGB mode)	(pin name) BIN2	(pin no.) 190
• Capture B3 input (RGB mode)	(pin name) BIN3	(pin no.) 191
• Capture B4 input (RGB mode)	(pin name) BIN4	(pin no.) 192
• Capture B5 input (RGB mode)	(pin name) BIN5	(pin no.) 193
• Capture B6 input (RGB mode)	(pin name) BIN6	(pin no.) 194
• Capture B7 input (RGB mode)	(pin name) BIN7	(pin no.) 195

10.19. Pins of GDC (Capture 656 Mode)

Pins of GDC (Capture 656 mode) are shown.

• Capture VIN0 input (656 mode)	(pin name) VIN0	(pin no.) 176
• Capture VIN1 input (656 mode)	(pin name) VIN1	(pin no.) 177
• Capture VIN2 input (656 mode)	(pin name) VIN2	(pin no.) 178
• Capture VIN3 input (656 mode)	(pin name) VIN3	(pin no.) 179
• Capture VIN4 input (656 mode)	(pin name) VIN4	(pin no.) 180
• Capture VIN5 input (656 mode)	(pin name) VIN5	(pin no.) 181
• Capture VIN6 input (656 mode)	(pin name) VIN6	(pin no.) 182
• Capture VIN7 input (656 mode)	(pin name) VIN7	(pin no.) 183

10.20. Pins of GDC (Capture Other)

Pins of GDC (Capture other) are shown.

- | | | |
|----------------------------------------|-----------------|---------------|
| • Capture vertical sync signal input | (pin name) VSIN | (pin no.) 197 |
| • Capture horizontal sync signal input | (pin name) HSIN | (pin no.) 198 |
| • Capture capture clock input | (pin name) CCLK | (pin no.) 196 |

10.21. Pins of GDC (Display)

Pins of GDC (Display) are shown.

• Display digital R0 output	(pin name) ROUT0	(pin no.) 38
• Display digital R1 output	(pin name) ROUT1	(pin no.) 39
• Display digital R2 output	(pin name) ROUT2	(pin no.) 2
• Display digital R3 output	(pin name) ROUT3	(pin no.) 3
• Display digital R4 output	(pin name) ROUT4	(pin no.) 4
• Display digital R5 output	(pin name) ROUT5	(pin no.) 5
• Display digital R6 output	(pin name) ROUT6	(pin no.) 6
• Display digital R7 output	(pin name) ROUT7	(pin no.) 7
• Display digital G0 output	(pin name) GOUT0	(pin no.) 40
• Display digital G1 output	(pin name) GOUT1	(pin no.) 41
• Display digital G2 output	(pin name) GOUT2	(pin no.) 8
• Display digital G3 output	(pin name) GOUT3	(pin no.) 9
• Display digital G4 output	(pin name) GOUT4	(pin no.) 10
• Display digital G5 output	(pin name) GOUT5	(pin no.) 11
• Display digital G6 output	(pin name) GOUT6	(pin no.) 12
• Display digital G7 output	(pin name) GOUT7	(pin no.) 13
• Display digital B0 output	(pin name) BOUT0	(pin no.) 42
• Display digital B1 output	(pin name) BOUT1	(pin no.) 43
• Display digital B2 output	(pin name) BOUT2	(pin no.) 14
• Display digital B3 output	(pin name) BOUT3	(pin no.) 15
• Display digital B4 output	(pin name) BOUT4	(pin no.) 16
• Display digital B5 output	(pin name) BOUT5	(pin no.) 17
• Display digital B6 output	(pin name) BOUT6	(pin no.) 21
• Display digital B7 output	(pin name) BOUT7	(pin no.) 22
• Display enable display period output	(pin name) DEOUT	(pin no.) 26
• Display composite sync signal output, / Graphics/Video switch (External sync) output	(pin name) CSOUT	(pin no.)199
• Display reference clock output (Internal sync)	(pin name) DCKOUT	(pin no.) 23
• Display vertical sync signal output (Internal sync) / Display vertical sync signal input (External sync)	(pin name) VSYNC	(pin no.) 24
• Display horizontal sync signal output (Internal sync) / Display horizontal sync signal input (External sync)	(pin name) HSYNC	(pin no.) 25
• Display reference clock input (External sync)	(pin name) DCKIN	(pin no.)200

10.22. Pins of GDC (NTSC)

Pins of GDC (NTSC) are shown.

• Clamp level output	(pin name) REFOUT	(pin no.) 204
• “L” level reference voltage for NTSC-AD	(pin name) AVR3	(pin no.) 203
• NTSC signal input	(pin name) VIN	(pin no.) 205
• For NTSC, AD converter analog power supply	(pin name) AVCC3	(pin no.) 201, 207
• NTSC AD converter GND	(pin name) AVSS3	(pin no.) 202, 206

10.23. Pin of GDC (Other)

Pin of GDC (Other) is shown.

- GDC command trigger input (pin name) CMDTRG (pin no.) 200

10.24. Pins of Other

Pins of other such as power supply and GND are shown.

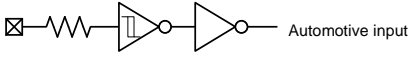
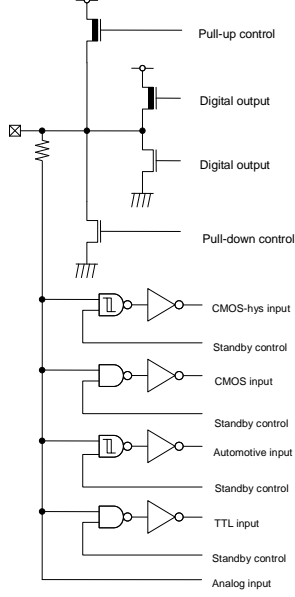
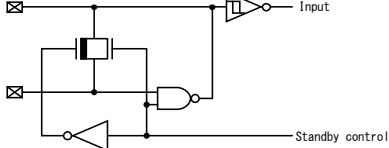
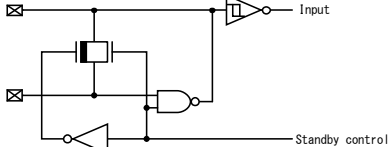
• +5.0v power supply	(pin name) VCC5	(pin no.) 89,105,122,173
• +3.3v power supply	(pin name) VCC3	(pin no.) 1,18,37,53,71, 175,189
• GND	(pin name) VSS	(pin no.) 19,36,52,72,82,88, 104,123,174,188,208,170
• Built-in regulator capacitor connected pin 1	(pin name) C_1	(pin no.) 124
• Built-in regulator capacitor connected pin 2	(pin name) C_2	(pin no.) 73
• Built-in regulator capacitor connected pin 3	(pin name) C_3	(pin no.) 20
• Main clock oscillator output	(pin name) X1	(pin no.) 83
• Main clock oscillator input	(pin name) X0	(pin no.) 84
• Sub-clock oscillator output (dual clock product)	(pin name) X1A	(pin no.) 172
• Sub-clock oscillator input (dual clock product)	(pin name) X0A	(pin no.) 171
• Mode pin 0	(pin name) MD0	(pin no.) 86
• Mode pin 1	(pin name) MD1	(pin no.) 85
• Mode pin 2	(pin name) MD2	(pin no.) 169
• NMI interrupt input	(pin name) NMIX	(pin no.) 97
• DEBUG I/F	(pin name) DEBUGIF	(pin no.) 103
• External reset input	(pin name) RSTX	(pin no.) 87

11. I/O Circuit Types

This section shows I/O circuit types of MB91590 series.

Type	Circuit	Remarks
A		<ul style="list-style-type: none"> • General-purpose I/O port • Output 1mA, 2mA • Pull-up resistor control 50kΩ • Pull-down resistor control 50kΩ • CMOS input • Schmitt input • TTL input • Automotive input
C		<ul style="list-style-type: none"> • Analog I/O, General-purpose I/O port • Output 1mA, 2mA • Pull-up resistor control 50kΩ • Pull-down resistor control 50kΩ • CMOS input • Schmitt input • TTL input • Automotive input

Type	Circuit	Remarks
E	<p>The diagram for Type E shows a central input node connected to a pull-up resistor and a pull-down resistor. Above the node is a PMOS transistor controlled by 'Pull-up control'. Below the node is an NMOS transistor controlled by 'Pull-down control'. Two 'Digital output' transistors are connected to the node. Below the node, several input configurations are shown: a CMOS-hys input with a Schmitt trigger and a pull-up resistor; a CMOS input with a Schmitt trigger and a pull-up resistor; an Automotive input with a Schmitt trigger and a pull-up resistor; a TTL input with a Schmitt trigger and a pull-up resistor; and an Analog input.</p>	<ul style="list-style-type: none"> • Analog input, General-purpose I/O port • Output 1mA, 2mA, 30mA (High current for SMC) • Pull-up resistor control 50kΩ • Pull-down resistor control 50kΩ • CMOS input • Schmitt input • TTL input • Automotive input
F1	<p>The diagram for Type F1 shows an input node with a pull-up resistor and a PMOS transistor controlled by 'Pull-up control'. The node is connected to a Schmitt trigger input labeled 'CMOS-hys input'.</p>	<ul style="list-style-type: none"> • Schmitt input • Pull-up resistor control 50kΩ (5V cont)
F2	<p>The diagram for Type F2 shows an input node with a pull-down resistor and an NMOS transistor controlled by 'Pull-down control'. The node is connected to a Schmitt trigger input labeled 'CMOS-hys input'.</p>	<ul style="list-style-type: none"> • Schmitt input • Pull-down resistor control 50kΩ (5V cont)
G	<p>The diagram for Type G shows an input node with a pull-up resistor and an NMOS transistor controlled by 'Pull-down control'. The node is connected to a TTL input.</p>	<ul style="list-style-type: none"> • Open-drain I/O • Output 25mA (NOD) • TTL input

Type	Circuit	Remarks
J		<ul style="list-style-type: none"> • Automotive input
K		<ul style="list-style-type: none"> • Analog input, General-purpose I/O port • Output 1mA, 2mA, 3mA(I²C) • Pull-up resistor control 50kΩ • Pull-down resistor control 50kΩ • CMOS input • Schmitt input • TTL input • Automotive input
L		<ul style="list-style-type: none"> • Main oscillation I/O
N		<ul style="list-style-type: none"> • Sub oscillation I/O

Type	Circuit	Remarks
O		<ul style="list-style-type: none"> • Analog input, 3.3V General-purpose I/O port • Output 2mA, 5mA, 10mA and 20mA • Pull-up resistor control 33kΩ • Pull-down resistor control 33kΩ • Schmitt input • TTL input
P		<ul style="list-style-type: none"> • Mode I/O • Schmitt input
S		<ul style="list-style-type: none"> • Analog input(3V)
T		<ul style="list-style-type: none"> • Analog output(3V)

CHAPTER: HANDLING THE DEVICE

This chapter explains the notes on using this series.

1. Handling Precautions
2. Handling Device
3. Application Notes

1. Handling Precautions

Any semiconductor devices have inherently a certain rate of failure. The possibility of failure is greatly affected by the conditions in which they are used (circuit conditions, environmental conditions, etc.).

This page describes precautions that must be observed to minimize the chance of failure and to obtain higher reliability from your FUJITSU SEMICONDUCTOR devices.

■ Precautions for Product Design

This section describes precautions when designing electronic equipment using semiconductor devices.

● Absolute Maximum Ratings

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of certain established limits, called absolute maximum rating. Do not exceed these ratings.

● Recommended Operating Conditions

Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their sales representative beforehand.

● Processing and Protection of Pins

These precautions must be followed when handling the pins which connect semiconductor devices to power supply and input/output functions.

1. Preventing Over-Voltage and Over-Current Conditions

Exposure to voltage or current levels in excess of maximum ratings at any pin is likely to cause deterioration within the device, and in extreme cases leads to permanent damage of the device. Try to prevent such overvoltage or over-current conditions at the design stage.

2. Protection of Output Pins

Shorting of output pins to supply pins or other output pins, or connection to large capacitance can cause large current flows. Such conditions if present for extended periods of time can damage the device. Therefore, avoid this type of connection.

3. Handling of Unused Input Pins

Unconnected input pins with very high impedance levels can adversely affect stability of operation. Such pins should be connected through an appropriate resistance to a power supply pin or ground pin.

● Latch-up

Semiconductor devices are constructed by the formation of P-type and N-type areas on a substrate. When subjected to abnormally high voltages, internal parasitic PNP junctions (called thyristor structures) may be formed, causing large current levels in excess of several hundred mA to flow continuously at the power supply pin. This condition is called latch-up.

CAUTION:The occurrence of latch-up not only causes loss of reliability in the semiconductor device, but can cause injury or damage from high heat, smoke or flame. To prevent this from happening, do the following:

1. Be sure that voltages applied to pins do not exceed the absolute maximum ratings.
This should include attention to abnormal noise, surge levels, etc.
2. Be sure that abnormal current flows do not occur during the power-on sequence.

- **Observance of Safety Regulations and Standards**

Most countries in the world have established standards and regulations regarding safety, protection from electromagnetic interference, etc. Customers are requested to observe applicable regulations and standards in the design of products.

- **Fail-Safe Design**

Any semiconductor devices have inherently a certain rate of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

- **Precautions Related to Usage Devices**

FUJITSU SEMICONDUCTOR devices are intended for use in standard applications (computers, office automation and other office equipment, industrial, communications, and measurement equipment, personal or household devices, etc.).

CAUTION: Customers considering the use of our products in special applications where failure or abnormal operation may directly affect human lives or cause physical injury or property damage, or where extremely high levels of reliability are demanded (such as aerospace systems, atomic energy controls, sea floor repeaters, vehicle operating controls, medical devices for life support, etc.) are requested to consult with sales representatives before such use. The company will not be responsible for damages arising from such use without prior approval.

- **Precautions for Package Mounting**

Package mounting may be either lead insertion type or surface mount type. In either case, for heat resistance during soldering, you should only mount under FUJITSU SEMICONDUCTOR's recommended conditions. For detailed information about mount conditions, contact your sales representative.

- **Lead Insertion Type**

Mounting of lead insertion type packages onto printed circuit boards may be done by two methods: direct soldering on the board, or mounting by using a socket.

Direct mounting onto boards normally involves processes for inserting leads into through-holes on the board and using the flow soldering (wave soldering) method of applying liquid solder. In this case, the soldering process usually causes leads to be subjected to thermal stress in excess of the absolute ratings for storage temperature. Mounting processes should conform to FUJITSU SEMICONDUCTOR recommended mounting conditions.

If socket mounting is used, differences in surface treatment of the socket contacts and IC lead surfaces can lead to contact deterioration after long periods. For this reason it is recommended that the surface treatment of socket contacts and IC leads be verified before mounting.

- **Surface Mount Type**

Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

You must use appropriate mounting techniques. FUJITSU SEMICONDUCTOR recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with FUJITSU SEMICONDUCTOR ranking of recommended conditions.

- **Lead-Free Packaging**

CAUTION: When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

● Storage of Semiconductor Devices

Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

- (1) Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product. Store products in locations where temperature changes are slight.
- (2) Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5 °C and 30 °C. When you open Dry Package that recommends humidity 40% to 70% RH.
- (3) When necessary, FUJITSU SEMICONDUCTOR packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
- (4) Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

● Baking

Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the FUJITSU recommended conditions for baking.

Condition: 125°C /24 h

● Static Electricity

Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

- (1) Maintain relative humidity in the working environment between 40% and 70%. Use of an apparatus for ion generation may be needed to remove electricity.
- (2) Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
- (3) Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1MΩ). Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
- (4) Ground all fixtures and instruments, or protect with anti-static measures.
- (5) Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

■ Precautions for Use Environment

Reliability of semiconductor devices depends on ambient temperature and other conditions as described above.

For reliable performance, do the following:

- (1) Humidity
Prolonged use in high humidity can lead to leakage in devices as well as printed circuit boards. If high humidity levels are anticipated, consider anti-humidity processing
- (2) Discharge of Static Electricity
When high-voltage charges exist close to semiconductor devices, discharges can cause abnormal operation.
In such cases, use anti-static measures or processing to prevent discharges.
- (3) Corrosive Gases, Dust, or Oil
Exposure to corrosive gases or contact with dust or oil may lead to chemical reactions that will adversely affect the device. If you use devices in such conditions, consider ways to prevent such exposure or to protect the devices.
- (4) Radiation, Including Cosmic Radiation
Most devices are not designed for environments involving exposure to radiation or cosmic radiation. Users should provide shielding as appropriate.
- (5) Smoke, Flame
CAUTION: Plastic molded devices are flammable, and therefore should not be used near combustible substances. If devices begin to smoke or burn, there is danger of the release of toxic gases. Customers considering the use of FUJITSU SEMICONDUCTOR products in other special environmental conditions should consult with sales representatives.

Please check the latest handling precautions at the following URL.
<http://edevic.fujitsu.com/fj/handling-e.pdf>

2. Handling Device

This section explains the handling device.

■ Notes on Handling Device

This section explains the latch-up prevention and pin processing.

● For latch-up prevention

If a voltage higher than VCC or a voltage lower than VSS is applied to an I/O pin, or if a voltage exceeding the ratings is applied between VCC and VSS pins, a latch-up may occur in CMOS IC. If the latch-up occurs, the power supply current increases excessively and device elements may be damaged by heat. Take care to prevent any voltage from exceeding the maximum ratings in device application.

Also, the analog power supply (AVCC5, AVRH5), the NTSC power supply (AVCC3, AVR3), analog input and power supply to high-current output buffer pins must not be exceed the digital power supply (VCC5 or VCC3) when the power supply to the analog system and high-current output buffer pins is turned on or off.

In the correct power-on sequence of the microcontroller unit, turn on the digital power supply (VCC5), analog power supplies (AVCC5, AVRH5), and the power supply of high-current output buffer pins (DVCC) simultaneously. Or, turn on the digital power supply (VCC5), and then turn on analog power supplies (AVCC5, AVRH5) and the power supply of high-current output buffer pins (DVCC).

In the correct power-on sequence of GDC unit, similarly turn on the digital power supply (VCC3) and the NTSC analog power supply (AVCC3) simultaneously. Or, turn on the digital power supply (VCC3), and then turn on the NTSC analog power supply (AVCC3).

● Treatment of unused pins

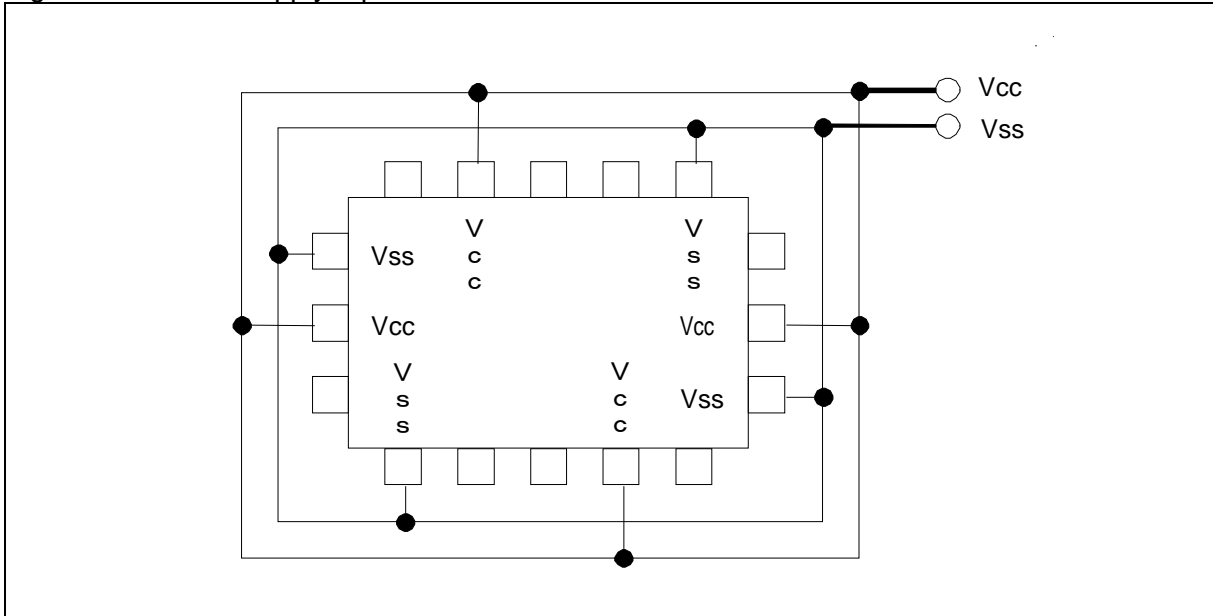
If unused input pins are left open, they may cause a permanent damage to the device due to malfunction or latch-up. Connect a 2kΩ resistor or more to each of unused pins for pull-up or pill-down processing.

Also, if I/O pins are not used, they must be set to the output state for releasing or they must be set to the input state and treated in the same way as for the input pins.

● **Power supply pins**

The device is designed to ensure that if the device contains multiple VCC or VSS pins, the pins that should be at the same potential are interconnected to prevent latch-up or other malfunctions. Further, connect these pins to an external power supply or ground to reduce unwanted radiation, prevent strobe signals from malfunctioning due to a raised ground level, and fulfill the total output current standard, etc. As shown in Figure 2-1, all Vss power supply pins must be treated in the similar way. If multiple Vcc or Vss systems are connected, the device cannot operate correctly even within the guaranteed operating range.

Figure 2-1 Power Supply Input Pins



The power supply pins should be connected to VCC and VSS of this device at the low impedance from the power supply source.

In the area close to this device, a ceramic capacitor having the capacitance larger than the capacitor of the C pin is recommended to use as a bypass capacitor between VCC and VSS pins.

● **Crystal oscillation circuit**

An external noise to the X0 or X1 pin may cause a device malfunction. The printed circuit board must be designed to lay out X0 and X1 pins, crystal oscillator (or ceramic resonator), and the bypass capacitor to be grounded to the close position to the device.

The printed circuit board artwork is recommended to surround the X0 and X1 pins by ground circuits.

● **Mode pins (MD2, MD1, MD0)**

Connect the MD2, MD1 and MD0 mode pins to the VCC or VSS pin directly. To prevent an erroneous selection of test mode caused by the noise, reduce the pattern length between each mode pin and VCC or VSS pin on the printed circuit board. Also, use the low-impedance pin connection.

● **During power-on**

To prevent a malfunction of the voltage step-down circuit built in the device, set the voltage rising time to have 50µs or longer (between 0.2V and 2.7V) during power-on.

● **Notes during PLL clock operation**

When the PLL clock is selected and if the oscillator is disconnected or if the input is stopped, this clock may continue to operate at the free running frequency of the self oscillator circuit built in the PLL clock. This operation is not guaranteed.

● **Treatment of A/D converter power supply pins**

Connect the pins to have $AVCC5=AVRH5=VCC5$ and $AVSS5/AVRL5=VSS$ even if the A/D converter is not used.

Also, similarly connect the pins of NTSC A/D converter power supply to have $AVCC3=VCC3$ and $AVSS3=VSS$. At this time, open VIN/REFOUT.

● **Notes on using external clock**

An external clock is not supported.

None of the external direct clock input can be used for both main clock and sub clock.

● **Power-on sequence of A/D converter power supplies and analog inputs**

Be sure to turn on the digital power supply ($Vcc5$) first, and then turn on the A/D converter power supplies ($AVcc5$, $AVRH5$, $AVRL5$) and analog inputs ($AN0$ to $AN31$). Also, turn off the A/D converter power supplies and analog inputs first, and then turn off the digital power supply ($Vcc5$). When the $AVRH5$ is turned on or off, it must not exceed $AVCC5$. Even if a common analog input pin is used as an input port, its input voltage must not exceed $AVcc5$. (However, the analog power supply and digital power supply can be turned on or off simultaneously.)

Be sure to similarly turn on the digital power supply ($VCC3$) first, and then turn on the A/D converter power supply ($AVCC3$) for NTSC and NTSC inputs (VIN , AVR). Also, turn off the A/D converter power supplies and analog inputs first, and then turn off the digital power supply ($VCC3$).

● **Treatment of power supplies for high current output buffer pins ($DVcc$, $DVss$)**

Be sure to turn on the digital power supply (Vcc) first, and then turn on the power supplies for high current output buffer pins ($DVcc$, $DVss$). Also, turn off the power supplies for high current output buffer pins first, and then turn off the digital power supply (Vcc).

Even if the high current output buffer pins are used as general-purpose ports, the power supplies of high current output buffer pins ($DVcc$, $DVss$) must be powered. (The power supplies of high current output buffer pins and the digital power supplies can be turned on or off simultaneously.)

● **Treatment of C pin**

This device contains a voltage step-down circuit. A capacitor must always be connected to the C pin to assure the internal stabilization of the device. For the standard values, see the "Recommended Operating Conditions" of the latest data sheet.

Note:

For the detailed specifications of operating voltages, see the latest data sheet.

3. Application Notes

This section explains application notes.

- 3.1 Function Switching of a Multiplexed Port
- 3.2 Low-power Consumption Mode
- 3.3 Notes When Writing Data in a Register Having the Status Flag

3.1. Function Switching of a Multiplexed Port

Function switching of a multiplexed port is shown.

To switch between the port function and the multiplexed pin function, use the PFR (port function register).
For details, see "CHAPTER: I/O PORTS".

3.2. Low-power Consumption Mode

This section explains low-power consumption mode.

To transit to the sleep mode, watch mode, stop mode, watch mode(power shutdown) or stop mode(power shutdown), follow the procedure explained in the "Activating the sleep mode, watch mode, or stop mode" or the "Activating the watch mode (power shutdown) or stop mode(power shutdown)" of "CHAPTER: POWER CONSUMPTION CONTROL".

And GDC part and MICOM part should be power-controlled separately.

Take the following notes when using a monitor debugger.

- Do not set a break point for the low-power consumption transition program.
- Do not execute an operation step for the low-power consumption transition program.

3.3. Notes When Writing Data in a Register Having the Status Flag

This section explains notes when writing data in a register having the status flag.

When writing data in the register that has a status flag (especially, an interrupt request flag) to control function, taking care not to clear its status flag erroneously must be followed.

The program must be written not to clear the flag to the status bit, and then to set the control bits to have the desired value.

Especially, if multiple control bits are used, the bit instruction cannot be used. (The bit instruction can access to a single bit only.) By the Byte, Half-word, or Word access, data is written to the control bits and status flag simultaneously. During this time, take care not to clear other bits (in this case, the bits of status flag) erroneously.

Note:

It is not necessary to note that the bit instruction considers this respect compared with the register to which read-modify-write (RMW) is supported. When the bit instruction is used for the register to which read-modify-write (RMW) is not supported, it is necessary to note it.

CHAPTER: CPU

This chapter explains the CPU.

1. Overview
2. Features
3. CPU Operating Description
4. Pipeline Operation
5. Floating Point Operation Processing
6. Data Structure
7. Addressing
8. Programming Model
9. Reset and EIT Processing
10. Memory Protection Function (MPU)

1. Overview

This section explains the overview of the CPU.

The FR81 architecture is a microcontroller architecture that uses the FR family instruction set with improved floating point functionality, memory protection functionality and on-chip debugging functionality.

The integer family instruction set is compatible with the FR80.

For details, see "FR Family FR81 32-bit Microcontroller Programming Manual".

2. Features

This section explains features of the CPU.

The FR family is a CPU core for 32-bit RISC-based controllers equipped with a custom FUJITSU architecture. In particular, this architecture is optimal as the CPU core in microcontrollers designed for embedded control applications that require high-speed control.

■ General

- General-purpose register architecture (32-bit × 16)
- 32-bit address space (4GB)
- 16-bit fixed instruction length (excluding immediate data transfer instructions)
- High-speed processing of basic instructions at one instruction per cycle using a 5-stage pipeline architecture
- 32-bit × 32-bit multiplication instruction that completes in 5 cycles
- 32-bit/32-bit division instruction by stepped division
- Direct addressing instructions for accessing peripherals
- High-speed interrupt processing that finishes in six cycles
- Single precision floating point arithmetic instructions
- Floating point register 32-bit × 16
- Privilege mode and user mode
 - Protection of some address-mapped registers as system registers during user mode
 - Protection of some instructions as privilege instructions during user mode
- FPU, instruction access, and data access exception functions
 - FPU exceptions
 - Instruction access protection violation exception
 - Data access protection violation exception
 - Illegal instruction exception (changed from undefined instruction exception)
 - Data access error exception
 - Non-existent FPU exception

■ Memory Protection Function (MPU)

- Eight protection areas can be specified common to instructions and data
- The protection areas are determined in a fixed order of precedence.(The areas can overlap)
- Areas are specified by a page address and a page size
 - Page size: Can be specified as 2ⁿ bytes from 16 bytes
 - Page address: Misaligned address also supported
- The following access privileges are controlled using privilege mode and user mode
 - Instruction fetch (execution) permitted / forbidden
 - Read permitted / forbidden
 - Write permitted / forbidden
- The following attributes can be specified for each area
 - Bufferable/Non-Bufferable
- Access privileges and attributes can be specified for unset areas
- On protection violation, an instruction access protection violation exception or data access protection violation exception occurs

■ **Floating Point Operations**

- IEEE754 compliant
- Support single precision
- Six exception sources are supported.
 - Underflow
 - Overflow
 - Division-by-zero
 - Invalid operation
 - Inexact
 - Inputs an unnormalized number
- The only rounding mode supported is nearest value
- Denormalized numbers are truncated to 0 or generate an exception
- Floating-point register: 32-bit × 16 sets
- Multiply and Add, Multiply and Sub instructions supported
- Division and square root operations supported

3. CPU Operating Description

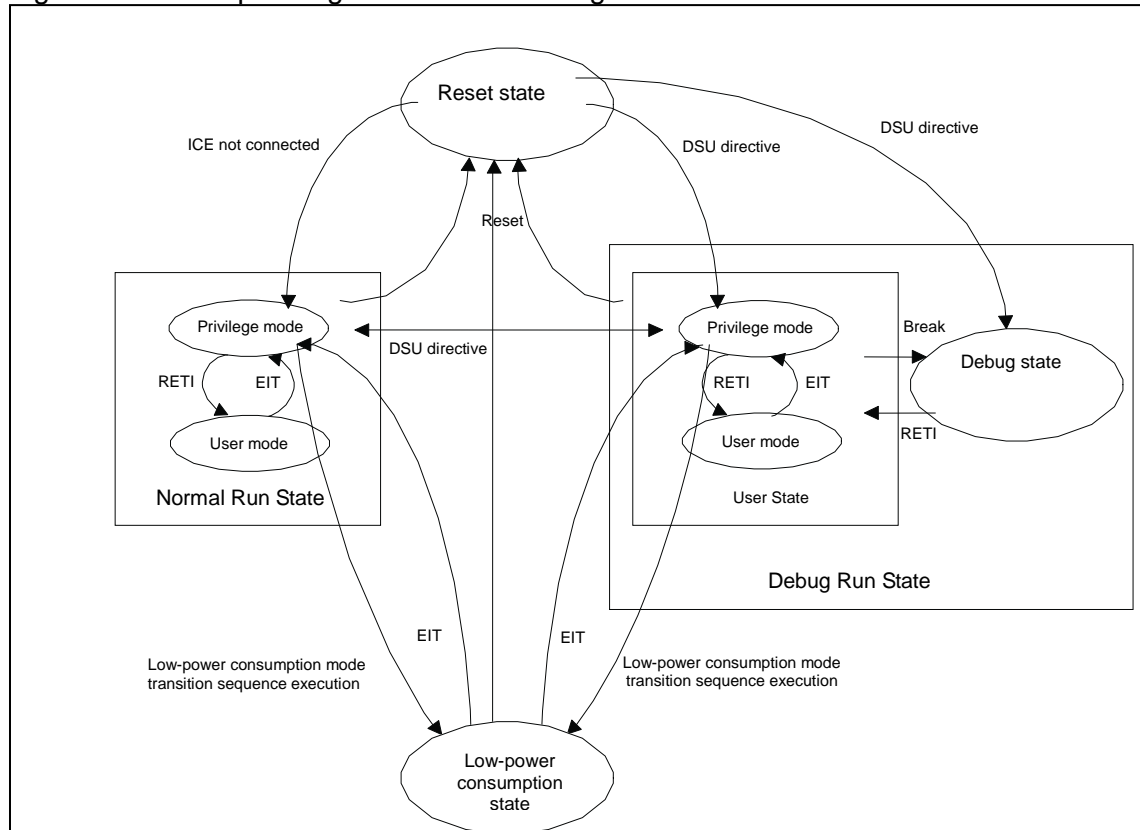
This section explains the operation of the CPU.

■ CPU Operating Status

The CPU operation state includes the following states: reset state, normal run state, low-power consumption state, and debug run state.

The operating state transitions are shown below.

Figure 3-1 CPU operating state transition diagram



● Reset State

The reset state is the state when the CPU is being reset. Resets consist of two levels: initialize level and reset level. When an initialize level reset is issued, everything in the chip is initialized. For the reset level, others exclusive of the debug control functions, clocks, and reset control functions are initialized.

● Normal Run State

The normal run state is the state when sequential instruction and EIT processing are executed. The normal run state has privilege mode and user mode.

In user mode, there are restrictions on instructions and access destination, and there are instructions and access destinations that can only be executed in privilege mode. When the CPU enters the normal run state after reset is released, the CPU enters privilege mode, and changes to user mode when RETI is executed. The transition from user mode to privilege mode in the normal run state is triggered by reset or the EIT execution, and transition from privilege mode to user mode is triggered by the RETI execution.

● **Low-power Consumption State**

The low-power consumption state is the state when the CPU is stopped to reduce the power consumption. The transition to the low-power consumption state is carried out by the standby control of the the clock control unit. The low-power consumption state has three modes: sleep, stop and watch mode. Recovery from the low-power consumption state is carried out by interrupts.

● **Debug Run State**

The debug run state is the state when the CPU is connected to ICE and debug related functions are enabled. The debug run state has two states: a user state and a debug state. The transition between the debug run state and other states is basically carried via the reset state. However, the transition from the normal run state to the debug run state forcefully is also enabled.

The user state has a privilege mode and a user mode as the normal run state. However, when a break for debugging is carried out, the state changes to the debug state. In the debug state, instructions are executed in a privilege mode and all registers and memory can be accessed under the state when the memory protection function, etc. is disabled. The transition from a debug state to a user state is carried by the RETI instruction.

4. Pipeline Operation

This section explains the pipeline operation of the CPU.

In FR81, the common pipeline processing is carried out by the decode stage, and there are two types of pipelines such as an integer pipeline and a floating point pipeline from the execution stage. Although the completion between each pipeline processing differs from the sequence of instruction issuances, the processing results based on the program sequence are guaranteed.

For details, see "FR Family FR81 32-bit Microcontroller Programming Manual".

5. Floating Point Operation Processing

The floating point operation processing for the CPU is shown.

This series incorporates FPU.

For details of the floating point operation processing, see "FR Family FR81 32-bit Microcontroller Programming Manual".

6. Data Structure

This section explains the data structure.

The data types which can be handled with FR81 family CPU are the integer type, which can be handled with FR80 family or earlier, and the single precision floating point type.

For the integer type, little endian as the bit ordering and big endian as the byte ordering are used.

For details, see "FR Family FR81 32-bit Microcontroller Programming Manual".

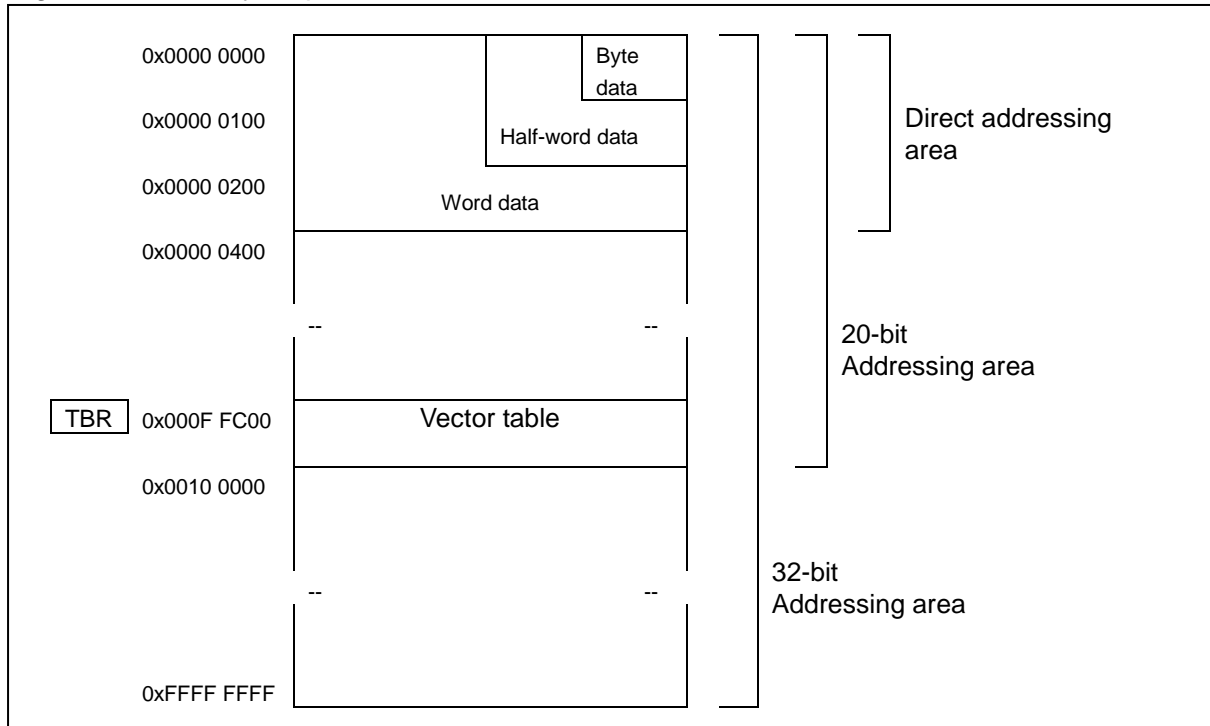
7. Addressing

This section explains addressing of the CPU.

A memory space is 32-bit linear.

The CPU manages the address space in bytes. Specify a value of 32-bit for the address on the address space to access from the CPU. Figure 7-1 shows the address space.

Figure 7-1 Memory Map



The address space is also called memory space. The address space is the CPU-based logical address space. Address conversion is not performed. The CPU-based logical address is same as the physical address where memory and I/O are actually located.

For details, see "FR Family FR81 32-bit Microcontroller Programming Manual".

8. Programming Model

This section explains the programming model of the CPU.

The CPU of FR81 has general-purpose registers, dedicated registers, and floating point registers. Besides these registers, the FR81 core has address-mapped system registers.

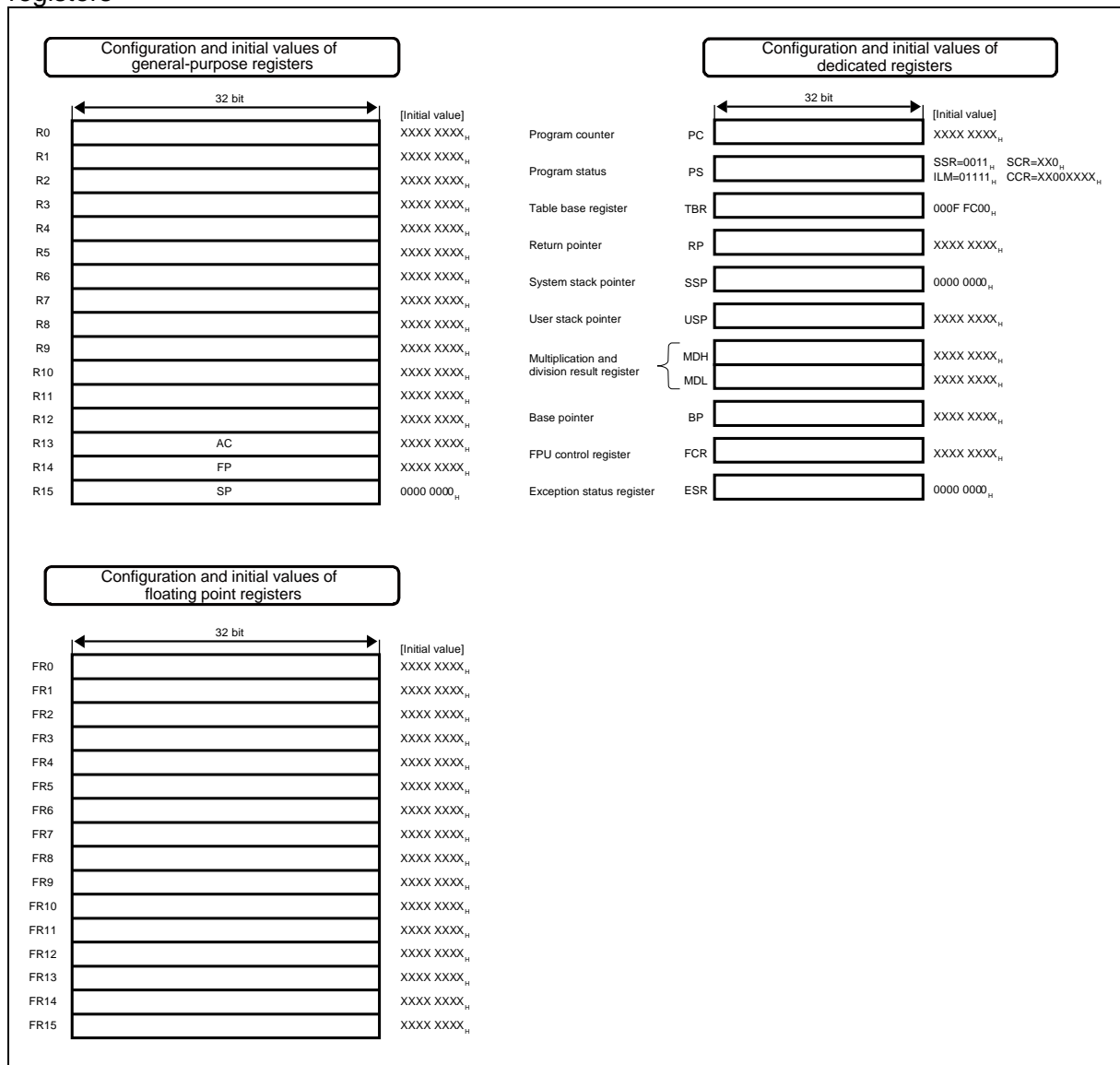
8.1. General-purpose Registers, Dedicated Registers, and Floating Point Registers

This section explains general-purpose registers, dedicated registers, and floating point registers.

Figure 8-1 shows the initial values for this series.

For details of each register, see "FR Family FR81 32-bit Microcontroller Programming Manual".

Figure 8-1 Initial values of general-purpose registers, dedicated registers, and floating point registers



8.2. System Register

This section explains System register.

System register is an address mapping register for controlling system. These registers can be accessed only in the privilege mode. There are system registers as follows.

- Clock control-related register
- Reset control-related register
- Debug control-related register
- Memory protection-related register
- DMA-related register
- Watchdog timer register
- Wild register control register
- FLASH control register

When these registers are written and/or read in the user mode, the illegal instruction exception (data access error) occurs.

The access protection to system registers is judged on a priority bases than the memory protection function. Therefore, when user access to the system register area is enabled in the memory protection function and access is disabled in the privilege mode, those settings are disabled. Read and/or write is enabled only in the privilege mode and read and/or write is disabled in the user mode.

9. Reset and EIT Processing

This section explains Reset and EIT processing.

Reset and EIT processing is the processing that is carried out by other than normal programs when Reset, Exception, Interrupt and Trap are detected.

9.1. Reset

This section explains Reset.

Reset forcibly suspends operations currently running, initializes the device and restarts the program from the reset vector entry address.

Note:

In this series, the FixedVector function returns not the value written in the address of 0xF_FFFC on flash memory but the first address of + 0x0024 on flash memory to reset vector. See "CHAPTER10 FixedVector FUNCTION" for details.

9.2. EIT Processing

This section explains the EIT processing.

The EIT processing suspends operations currently running, stores resumable information into memory and transfers control to the predetermined processing program.

9.3. Vector Table

The vector table is shown.

Table 9-1 Vector Table

Interruption Factor	Interrupt Vector Number		Interrupt Level	Offset	Address at TBR Initial Value
	Decimal	Hexa decimal			
Reset	0	00	-	0x3FC	0x000FFFFC
System reserved	1	01	-	0x3F8	0x000FFFF8
System reserved	2	02	-	0x3F4	0x000FFF4
System reserved	3	03	-	0x3F0	0x000FFF0
System reserved	4	04	-	0x3EC	0x000FFFE4
FPU exception	5	05	-	0x3E8	0x000FFFE8
Instruction access protection violation exception	6	06	-	0x3E4	0x000FFFE4
Data access protection violation exception	7	07	-	0x3E0	0x000FFFE0
Data access error interrupt	8	08	-	0x3DC	0x000FFFD4
INTE instruction	9	09	-	0x3D8	0x000FFFD8
Instruction break	10	0A	-	0x3D4	0x000FFFD4
System reserved	11	0B	-	0x3D0	0x000FFFD0
System reserved	12	0C	-	0x3CC	0x000FFFC4
System reserved	13	0D	-	0x3C8	0x000FFFC8
Illegal instruction exception	14	0E	-	0x3C4	0x000FFFC4
NMI request	15	0F	15(0xF)Fixed	0x3C0	0x000FFFC0
Peripheral interrupt #0	16	10	ICR00	0x3BC	0x000FFFB4
Peripheral interrupt #1	17	11	ICR01	0x3B8	0x000FFFB8
Peripheral interrupt #2	18	12	ICR02	0x3B4	0x000FFFB4
Peripheral interrupt #3	19	13	ICR03	0x3B0	0x000FFFB0
Peripheral interrupt #4	20	14	ICR04	0x3AC	0x000FFFA4
Peripheral interrupt #5	21	15	ICR05	0x3A8	0x000FFFA8
Peripheral interrupt #6	22	16	ICR06	0x3A4	0x000FFFA4
Peripheral interrupt #7	23	17	ICR07	0x3A0	0x000FFFA0
Peripheral interrupt #8	24	18	ICR08	0x39C	0x000FFF9C
Peripheral interrupt #9	25	19	ICR09	0x398	0x000FFF98
Peripheral interrupt #10	26	1A	ICR10	0x394	0x000FFF94
Peripheral interrupt #11	27	1B	ICR11	0x390	0x000FFF90
Peripheral interrupt #12	28	1C	ICR12	0x38C	0x000FFF8C
Peripheral interrupt #13	29	1D	ICR13	0x388	0x000FFF88
Peripheral interrupt #14	30	1E	ICR14	0x384	0x000FFF84
Peripheral interrupt #15	31	1F	ICR15	0x380	0x000FFF80
Peripheral interrupt #16	32	20	ICR16	0x37C	0x000FFF7C
Peripheral interrupt #17	33	21	ICR17	0x378	0x000FFF78
Peripheral interrupt #18	34	22	ICR18	0x374	0x000FFF74
Peripheral interrupt #19	35	23	ICR19	0x370	0x000FFF70
Peripheral interrupt #20	36	24	ICR20	0x36C	0x000FFF6C
Peripheral interrupt #21	37	25	ICR21	0x368	0x000FFF68
Peripheral interrupt #22	38	26	ICR22	0x364	0x000FFF64
Peripheral interrupt #23	39	27	ICR23	0x360	0x000FFF60
Peripheral interrupt #24	40	28	ICR24	0x35C	0x000FFF5C
Peripheral interrupt #25	41	29	ICR25	0x358	0x000FFF58
Peripheral interrupt #26	42	2A	ICR26	0x354	0x000FFF54
Peripheral interrupt #27	43	2B	ICR27	0x350	0x000FFF50

Interruption Factor	Interrupt Vector Number		Interrupt Level	Offset	Address at TBR Initial Value
	Decimal	Hexa decimal			
Peripheral interrupt #28	44	2C	ICR28	0x34C	0x000FFF4C
Peripheral interrupt #29	45	2D	ICR29	0x348	0x000FFF48
Peripheral interrupt #30	46	2E	ICR30	0x344	0x000FFF44
Peripheral interrupt #31	47	2F	ICR31	0x340	0x000FFF40
Peripheral interrupt #32	48	30	ICR32	0x33C	0x000FFF3C
Peripheral interrupt #33	49	31	ICR33	0x338	0x000FFF38
Peripheral interrupt #34	50	32	ICR34	0x334	0x000FFF34
Peripheral interrupt #35	51	33	ICR35	0x330	0x000FFF30
Peripheral interrupt #36	52	34	ICR36	0x32C	0x000FFF2C
Peripheral interrupt #37	53	35	ICR37	0x328	0x000FFF28
Peripheral interrupt #38	54	36	ICR38	0x324	0x000FFF24
Peripheral interrupt #39	55	37	ICR39	0x320	0x000FFF20
Peripheral interrupt #40	56	38	ICR40	0x31C	0x000FFF1C
Peripheral interrupt #41	57	39	ICR41	0x318	0x000FFF18
Peripheral interrupt #42	58	3A	ICR42	0x314	0x000FFF14
Peripheral interrupt #43	59	3B	ICR43	0x310	0x000FFF10
Peripheral interrupt #44	60	3C	ICR44	0x30C	0x000FFF0C
Peripheral interrupt #45	61	3D	ICR45	0x308	0x000FFF08
Peripheral interrupt #46	62	3E	ICR46	0x304	0x000FFF04
Delay interrupt	63	3F	ICR47	0x300	0x000FFF00
System reserved (For REALOS use)	64	40	-	0x2FC	0x000FFEFC
System reserved (For REALOS use)	65	41	-	0x2F8	0x000FFE8
For INT instruction use	66	42	-	0x2F4	0x000FEF4
	255	FF		0x000	0x000FFC00

10. Memory Protection Function (MPU)

This section explains the memory protection function (MPU) of the CPU.

- 10.1. Overview
- 10.2. List of Registers
- 10.3. Description of Registers
- 10.4. Operations of Memory Protection Function (MPU)

10.1. Overview

The overview of the memory protection function (MPU) is shown.

This architecture supports a memory protection function. The memory protection function is a function that monitors access to a specified area and generates an exception on prohibited access. However, protection specified on system registers is ignored.

- Eight protection areas can be specified that are shared by instructions and data
- The protection area with the highest priority is area 0, with the priority decreasing for areas 1, 2, 3, etc. (The areas can overlap)
- Areas are specified by a page address and a page size
 - Page size: Can be specified in units of 2^n bytes from 16 bytes
 - Page address: Misaligned addresses also supported
- The following access privileges are controlled using privilege mode and user mode
 - Instruction fetch: Enabled/ Disabled
 - Data Read: Enabled/ Disabled
 - Data Write: Enabled/ Disabled
- Attributes are specified for each area
 - Buffer: Enabled/ Disabled
- The access rights and attributes of undefined areas are controlled as a default area
- Protection violation exceptions occur when a protection violation occurs
- The register for the memory protection function can only be accessed in a privilege mode as system registers
- Data access error notification function
- I/O area (00000000_H to $0000FFFF_H$) is fixed buffer disabled

10.2. List of Registers

The list of registers is shown.

Table 10-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0310	Reserved		MPUCR		MPU Control Register
0x0314	Reserved				
0x0318	Reserved				
0x031C	Reserved				
0x0320	DPVAR				Data access protection violation address register
0x0324	Reserved		DPVSR		Data access protection violation status register
0x0328	DEAR				Data access error address register
0x032C	Reserved		DESR		Data access error status register
0x0330	PABR0				Protection area base address register 0
0x0334	Reserved		PACR0		Protection area control register 0
0x0338	PABR1				Protection area base address register 1
0x033C	Reserved		PACR1		Protection area control register 1
0x0340	PABR2				Protection area base address register 2
0x0344	Reserved		PACR2		Protection area control register 2
0x0348	PABR3				Protection area base address register 3
0x034C	Reserved		PACR3		Protection area control register 3
0x0350	PABR4				Protection area base address register 4
0x0354	Reserved		PACR4		Protection area control register 4
0x0358	PABR5				Protection area base address register 5
0x035C	Reserved		PACR5		Protection area control register 5
0x0360	PABR6				Protection area base address register 6
0x0364	Reserved		PACR6		Protection area control register 6
0x0368	PABR7				Protection area base address register 7
0x036C	Reserved		PACR7		Protection area control register 7

10.3. Description of Registers

Registers are shown.

- 10.3.1. MPU Control Register (MPUCR)
- 10.3.2. Instruction Access Protection Violation Address Register (IPVAR)
- 10.3.3. Instruction Access Protection Violation Status Register (IPVSR)
- 10.3.4. Data Access Protection Violation Address Register (DPVAR)
- 10.3.5. Data Access Protection Violation Status Register (DPVSR)
- 10.3.6. Data Access Error Address Register (DEAR)
- 10.3.7. Data Access Error Status Register (DESR)
- 10.3.8. Protection Area Base Address Register 0 to 7 (PABR0 to PABR7)
- 10.3.9. Protection Area Control Register 0 to 7 (PACR0 to PACR7)

10.3.1. MPU Control Register (MPUCR)

The bit configuration of the MPU control register (MPUCR) is shown.

The MPU control register controls whether the MPU is enabled or disabled, and configures the access permissions in privilege mode and user mode to default areas (areas not specified as protection areas).

■ **MPUCR : Address 0312_H (Access: Half-word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	PIE	PRE	PWE	UIE	URE	UWE	Reserved	BE
Initial value	0	0	0	0	0	0	-	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R0,W0	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				PAN1	PAN0	DEE	MPE
Initial value	-	-	-	-	0	1	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,WX	R1,WX	R/W	R/W

[bit15] PIE (Privilege Mode Instruction Fetch Enable)

This bit is for permitting instruction fetch in privilege mode from the default areas (areas that have not been specified as protection areas).

PIE	Access to default area
0	Instruction fetch not permitted in privilege mode (Initial value)
1	Instruction fetch permitted in privilege mode

[bit14] PRE (Privilege Mode Read Access Enable)

This bit is for permitting data read access in privilege mode from the default areas (areas that have not been specified as protection areas).

PRE	Access to default area
0	Read access not permitted in privilege mode (Initial value)
1	Read access permitted in privilege mode

[bit13] PWE (Privilege Mode Write Access Enable)

This bit is for permitting data write access in privilege mode to the default areas (areas that have not been specified as protection areas).

PWE	Access to default area
0	Write access not permitted in privilege mode (Initial value)
1	Write access permitted in privilege mode

[bit12] UIE (User Mode Instruction Fetch Enable)

This bit is for permitting instruction fetch in user mode from the default areas (areas that have not been specified as protection areas).

UIE	Access to default area
0	Instruction Fetch not enable at User Mode (Initial value)
1	Instruction Fetch enable at User Mode

[bit11] URE (User Mode Read Access Enable)

This bit is for permitting data read access in user mode from the default areas (areas that have not been specified as protection areas).

URE	Access to default area
0	Read access not permitted in user mode (Initial value)
1	Read access permitted in user mode

[bit10] UWE (User Mode Write Access Enable)

This bit is for permitting data write access in user mode to the default areas (areas that have not been specified as protection areas).

UWE	Access to default area
0	Write access not permitted in user mode (Initial value)
1	Write access permitted in user mode

[bit9] Reserved

Always write "0" when writing. This bit reads out "0".

[bit8] BE (Buffer Enable)

The bit permits buffering to be used when performing data access to default areas (areas that are not specified as protection areas). When the use of buffering is forbidden, the CPU stops pipeline operation and waits for the data access to finish before starting the next operation. As a result, although the data access efficiency decreases, it is possible to perform data access synchronized to the instruction. Illegal instruction exceptions occur when there is an error during data access only if buffering is forbidden. When buffering is permitted, data access errors can be notified as interrupts.

BE	Buffer enable specification for the default area
0	Buffer disabled (Initial value)
1	Buffer enabled

[bit7 to bit4] Reserved

These bits are reserved. Always write "0" when writing.

[bit3, bit2] PAN[1:0] (Protection Area Number)

Indicates the number of configurable protection areas that can be specified. This bit is read-only and indicates the number of areas implemented in hardware.

PAN[1:0]	Number of memory protection areas implemented
00	Reserved
01	8 areas
10	12 areas
11	16 areas

[bit1] DEE (Data Access Error Interrupt Enable)

This bit permits interrupts to occur when a data access error occurs in areas where buffer operation is enabled. If a data access error occurs in an area where buffer operation is permitted while this bit is enabled, a data access error interrupt occurs. At this time, the address where the error occurred is stored in the data access error address register (DEAR), and the details of the access are stored in the data access error status register (DESR). If interrupts are disabled, the above registers are updated only.

DEE	Data access error interrupt enabled
0	Data access error interrupt disabled (Initial value)
1	Data access error interrupt enable

[bit0] MPE (Memory Protection Unit Enable)

This bit is for enabling the memory protection function. If the memory protection function is disabled, buffering is configured as disabled for accesses to all areas.

MPE	Memory protection function
0	Memory protection function disabled (Initial value)
1	Memory protection function enabled

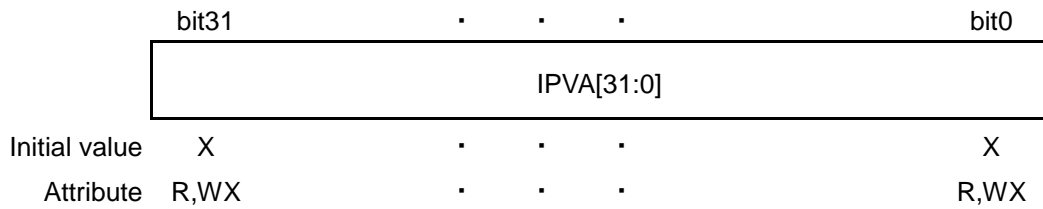
10.3.2. Instruction Access Protection Violation Address Register (IPVAR)

The bit configuration of the instruction access protection violation address register is shown.

This register stores the address where an instruction access protection violation occurred.

Also see "10.4.2. Instruction Access Protection Violation" and "10.4.7. Notes".

■ **IPVAR : Address 0318_H (Access: Word)**



[bit31 to bit0] IPVA[31:0] (Instruction fetch Protection Violation Address)

This register stores the address where an instruction access protection violation occurred when a violation has not occurred in the instruction access protection violation status register (IPVSR:IPV =0). This is not aligned.

Note:

This register is a prohibition of use.

10.3.3. Instruction Access Protection Violation Status Register (IPVSR)

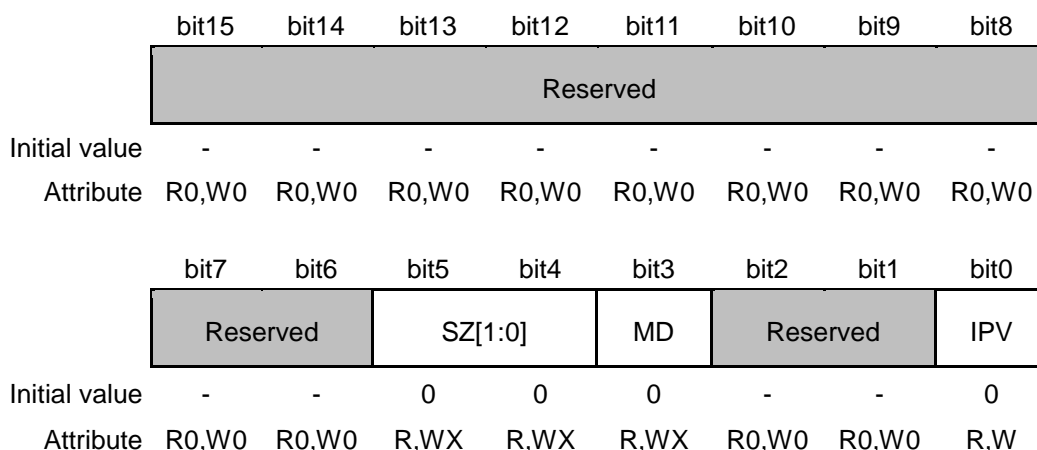
The bit configuration of the instruction access protection violation status register is shown.

This register indicates the status when an instruction access protection violation occurs.

The content of this register is updated by hardware only when IPV=0. Only writing "0" to the IPV bit has an effect. Writes to any other bits and writing "1" to IPV are ignored.

Also see "10.4.2. Instruction Access Protection Violation" and "10.4.7. Notes".

■ **IPVSR : Address 031E_H (Access : Half-word)**



[bit15 to bit6, bit2, bit1] Reserved

These bits are reserved. Always write "0" to these bits.

[bit5, bit4] SZ[1:0]

The access size when the violation occurred.

SZ[1:0]	Access size
00	Byte
01	Half-word
10	Word
11	Reserved

[bit3] MD

Indicates the mode of the access.

MD	Operation mode
0	Access in user mode
1	Access in privilege mode

[bit0] IPV (Instruction fetch Protection Violation)

This bit indicates that an instruction access protection violation occurred. In order to save the details of new protection violations, clear this bit.

IPV	Instruction access protection violation
0	Instruction access protection violation not detected (initial value)
1	Instruction access protection violation detected

Note:

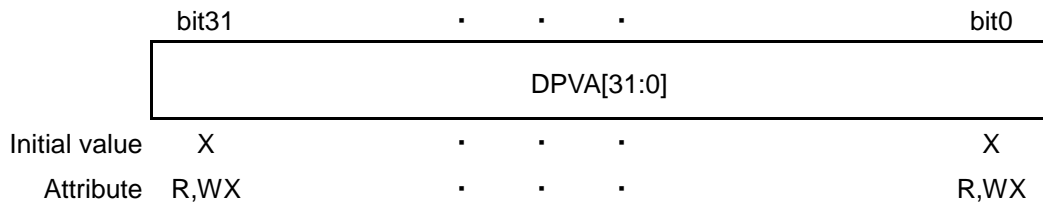
This register is a prohibition of use.

10.3.4. Data Access Protection Violation Address Register (DPVAR)

The bit configuration of the data access Protection violation address register is shown.

The address where the violation of the data access protection occurs is saved.

■ **DPVAR : Address 0320_H (Access : Word)**



[bit31 to bit0] DPVA[31:0] (Data Access Protection Violation Address)

This register stores the address where a data access protection violation occurred when a violation has not occurred in the data access protection violation status register (DPVSR:DPV =0). This register indicates the address requested by the CPU, and the address is not aligned.

10.3.5. Data Access Protection Violation Status Register (DPVSR)

The bit configuration of the data access protection violation status register is shown.

This register indicates the status when a data access protection violation occurs.

The content of this register is updated by hardware only when DPV=0. Writing "0" to DPV only is valid. Writes to any other bits and writing "1" to DPV are ignored.

■ **DPVSR : Address 0326_H (Access : Half-word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RW[1:0]		SZ[1:0]		MD	Reserved		DPV
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R0,W0	R0,W0	R,W

[bit15 to bit8, bit2, bit1] Reserved

These bits are reserved. Always write "0" to these bits.

[bit7, bit6] RW[1:0] (Read/Write)

The access type when the violation occurred. When a read-modify-write is executed, because both read and write access rights are required and the determination is made in the initial read cycle, RW=01_B read (read-modify-write) even if the violation occurs in the write part of the read-modify-write.

RW[1:0]	Access type
00	Read
01	Read (Read-modify-write)
10	Write
11	Reserved

[bit5, bit4] SZ[1:0]

The access size when the violation occurred.

SZ[1:0]	Access size
00	Byte
01	Half word
10	Word
11	Reserved

[bit3] MD

Indicates the mode of the access.

MD	Operation mode
0	Access in user mode
1	Access in privilege mode

[bit0] DPV (Data Access Protection Violation)

This bit indicates that a data access protection violation occurred. In order to save the details of new protection violations, clear this bit.

Writing "0" to this bit only is valid. Writing "1" to the bit is ignored.

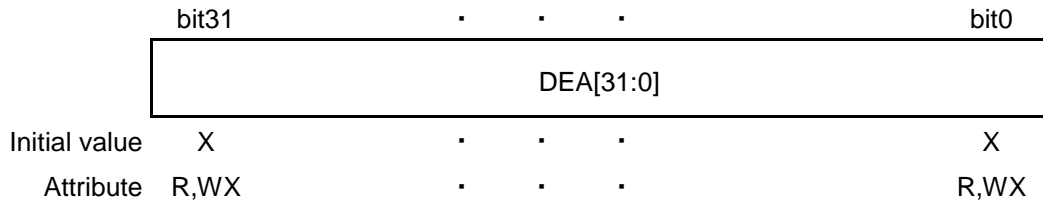
DPV	Data access protection violation
0	Data access protection violation not detected (initial value)
1	Data access protection violation detected

10.3.6. Data Access Error Address Register (DEAR)

The bit configuration of the data access error address register is shown.

This register stores the address where a data access error occurred.

■ **DEAR : Address 0328_H (Access : Word)**



[bit31 to bit0] DEA[31:0] (Data Access Error Address)

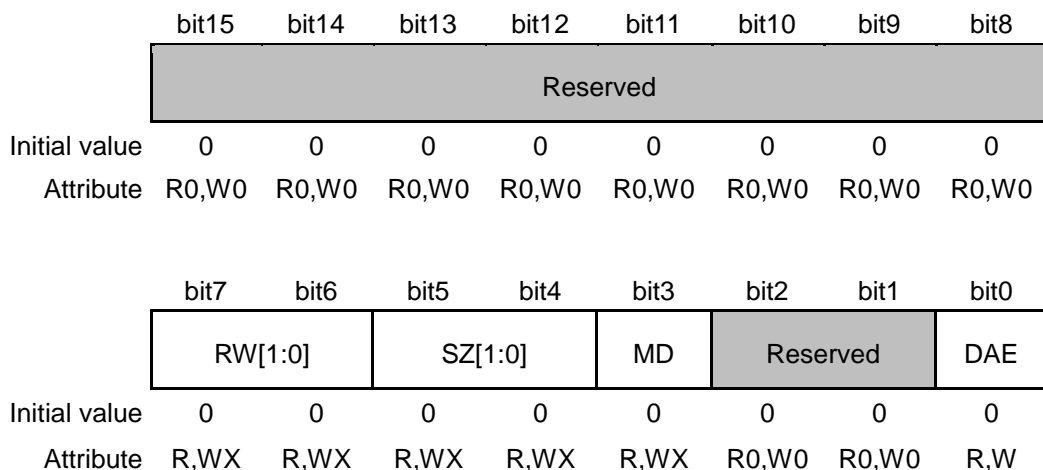
This register stores the address where a data access error occurred when a violation has not occurred in the data access error status register (DESR:DAE =0). If the protection violation occurred while accessing system registers, the access address from the CPU is stored as it is without being aligned. If the result of performing a bus access is an error, the address is aligned.

10.3.7. Data Access Error Status Register (DESR)

The bit configuration of the data access error status register is shown.

This register indicates the status when a data access error occurs. The content of this register is updated by hardware only when DAE=0. Writing "0" to DAE only is valid. Writes to any other bits and writing "1" to DAE are ignored.

■ **DESR : Address 032E_H (Access : Half-word)**



[bit15 to bit8, bit2, bit1] Reserved

These bits are reserved. Always write "0" to these bits. These bits read out "0".

[bit7, bit6] RW[1:0] (Read/Write)

The access type when the error occurred.

RW[1:0]	Access type
00	Read
01	Read (Read-modify-write)
10	Write
11	Reserved

[bit5, bit4] SZ[1:0]

The access size when the error occurred.

SZ[1:0]	Access size
00	Byte
01	Half-word
10	Word
11	Reserved

[bit3] MD

This bit indicates the mode of the access.

MD	Operation mode
0	Access in user mode
1	Access in privilege mode

[bit0] DAE (Data Access Error)

This bit indicates that a data access error occurred. In order to save the details of new data errors, clear this bit.

The interrupt request is withdrawn by clearing this bit when the data access error interrupt is effectively done. Only "0" writing is effective to this bit. "1" writing is invalid.

DAE	Data access error
0	Data Access Error not detected (Initial value)
1	Data Access Error detected

10.3.8. Protection Area Base Address Register 0 to 7 (PABR0 to PABR7)

The bit configuration of protection area base address register 0 to 7 is shown.

These registers set the base addresses of the protection areas for each MPU channel.

■ **PABR0 to PABR7 : Address 0330_H , 0338_H , 0340_H . . . (Access : Word)**

	bit31						bit8	
	PABR[31:8]							
Initial value	X	X	.	.	.	X	X	X
Attribute	R/W	R/W	.	.	.	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PABR[7:0]							
Initial value	X	X	X	X	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R0,WX	R0,WX	R0,WX	R0,WX

[bit31 to bit0] PABR[31:0] (Protection Area Base Address Register)

These registers point to the base address of the protection area. The area from the address specified here to the size specified by the protection area control registers (PACR0 to PACR7) is the protection area. The address does not need to be aligned to the protection area size.

The lower 4 bits of the PABR register are fixed at "0000_b".

10.3.9. Protection Area Control Register 0 to 7 (PACR0 to PACR7)

The bit configuration of protection area control register 0 to 7 is shown.

These registers set access permissions and restrictions for each MPU channel.

■ **PACR0 to PACR7 : Address 0336_H, 033E_H, 0346_H . . . (Access : Half-word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	PIE	PRE	PWE	UIE	URE	UWE	Reserved	BE
Initial value	0	0	0	0	0	0	-	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R0,W0	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ASZ[4:0]					Reserved		PAE
Initial value	0	0	0	0	0	-	-	0
Attribute	R/W	R/W	R/W	R/W	R/W	R0,W0	R0,W0	R/W

[bit15] PIE (Privilege Mode Instruction Fetch Enable)

This bit is for enabling instruction fetch in privilege mode for the specified protection area.

PIE	Access to the specified protection area
0	Instruction fetch not permitted in privilege mode (Initial value)
1	Instruction fetch permitted in privilege mode

[bit14] PRE (Privilege Mode Read Access Enable)

This bit is for enabling data read access in privilege mode for the specified protection area.

PRE	Access to the specified protection area
0	Read access not permitted in privilege mode (Initial value)
1	Read access permitted in privilege mode

[bit13] PWE (Privilege Mode Write Access Enable)

This bit is for enabling data write access in privilege mode for the specified protection area.

PWE	Access to the specified protection area
0	Write access not permitted in privilege mode (initial value)
1	Write access permitted in privilege mode

[bit12] UIE (User Mode Instruction Fetch Enable)

This bit is for enabling instruction fetch in user mode for the specified protection area.

UIE	Access to the specified protection area
0	Instruction fetch not permitted in user mode (initial value)
1	Instruction fetch permitted in user mode

[bit11] URE (User Mode Read Access Enable)

This bit is for enabling data read access in user mode for the specified protection area.

URE	Access to the specified protection area
0	Read access not permitted in user mode (initial value)
1	Read access permitted in user mode

[bit10] UWE (User Mode Write Access Enable)

This bit is for enabling data write access in user mode for the specified protection area.

UWE	Access to the specified protection area
0	Write access not permitted in user mode (initial value)
1	Write access permitted in user mode

[bit9] Reserved

Always write "0" to this bit. This bit reads out "0".

[bit8] BE (Buffer Enable)

This bit permits buffering to be used during data access for the specified protection area. When the use of buffering is forbidden, the CPU stops pipeline operation and waits for the data access to finish before starting the next operation. As a result, although the data access efficiency decreases, it is possible to perform data access synchronized to the instruction. Illegal instruction exceptions occur when there is an error during data access only if buffering is forbidden. When buffering is permitted, data access errors can be notified as interrupts.

BE	Buffer enable specification for the specified protection area
0	Buffer Disable (Initial value)
1	Buffer Enable

[bit7 to bit3] ASZ[4:0] (Area Size)

These bits specify the size of the specified protection area. The specified address does not need to be aligned to the sizes described below. Furthermore, if the lower limit of the area specified by the address and size exceeds FFFFFFFFH, the lower limit of the area is treated as FFFFFFFFH.

ASZ[4:0]	Size of the specified protectorate area
00000	Reserved
00001	Reserved

ASZ[4:0]	Size of the specified protectorate area
00010	Reserved
00011	16B
00100	32B
00101	64B
00110	128B
00111	256B
01000	512B
01001	1KB
01010	2KB
01011	4KB
01100	8KB
01101	16KB
01110	32KB
01111	64KB
10000	128KB
10001	256KB
10010	512KB
10011	1MB
10100	2MB
10101	4MB
10110	8MB
10111	16MB
11000	32MB
11001	64MB
11010	128MB
11011	256MB
11100	512MB
11101	1GB
11110	2GB
11111	4GB

[bit2, bit1] Reserved

These bits are reserved. Always write "0" when writing.

[bit0] PAE (Protection Area Enable)

This bit is for enabling the memory protection function.

PAE	Memory protection area
0	Specified memory protection area disabled (Initial value)
1	Specified memory protection area enabled

10.4. Operations of Memory Protection Function (MPU)

This section explains operations of the memory protection function (MPU) of the CPU.

- 10.4.1. Setting Up Memory Protection Areas
- 10.4.2. Instruction Access Protection Violation
- 10.4.3. Data Access Protection Violation
- 10.4.4. Data Access Errors
- 10.4.5. Memory Protection Operation by Delay Slot
- 10.4.6. DEAR and DESR Update
- 10.4.7. Notes

10.4.1. Setting Up Memory Protection Areas

This section explains setting up memory protection areas of the CPU.

The memory protection function is configured by settings whether instructions, data reads, and data writes are permitted or forbidden in privilege mode and user mode for a maximum of eight protection areas specified by address and size, and default areas that are not contained in these protection areas. The buffer permitted or forbidden setting can also be configured for each area at the same time.

If there are overlaps between specified protection areas, the area with the smallest number takes precedence.

When the memory protection function is disabled (MPUCR:MPE =0), access is performed with access permitted to all areas and buffering disabled.

10.4.2. Instruction Access Protection Violation

This section explains instruction access protection violation of the CPU.

The memory protection unit (MPU) monitors CPU instruction fetches and determines whether instruction fetches are permitted to the accessed areas. The instruction address when an instruction access protection violation exception occurs can be determined from the PC value saved on the system stack.

10.4.3. Data Access Protection Violation

This section explains data access protection violation of the CPU.

The memory protection unit (MPU) monitors CPU data accesses and determines whether accesses (reads and writes) to the corresponding area are permitted. If an access was not permitted, the MPU stores that address and access information in the data access protection violation address register (DPVAR) and the data access protection violation status register (DPVSR). However, if data access protection violation information already exists in the above register (DPVSR:DPV =1), this is not overwritten. The data access that caused the violation at this time is not performed.

If a data access protection violation occurs during the execution of an instruction that performs multiple data accesses, the data accesses that had executed up until the violation occurred are not cancelled. If a data access protection violation exception occurs during the LDM0, LDM1, STM0, STM1, FLDM, or FSTM instructions, the list of remaining registers is stored in the exception status register ESR:RL.

If a data access protection violation occurs during the EIT processing sequence or the RETI instruction, the CPU is halted and can only be recovered by break interrupt or reset.

10.4.4. Data Access Errors

This section explains data access errors of the CPU.

If the following conditions are satisfied during a data access, this is treated as a data access error and the access information at that time are stored in the data access error address register (DEAR) and data access error status register (DESR). However, if data access error information already exists in the above register (DESR:DAE =1), this is not overwritten.

- System register access in user mode
- Bus error during data access

The operation after a bus error occurs during data access differs between accesses with buffering enabled and accesses with buffering disabled. System register accesses in user mode are always processed as illegal instruction exceptions (data access).

If a data access error occurs during access to an unbufferable area, the CPU processes this as an illegal instruction exception (data access error).

If a data access error occurs during access to a bufferable area, and if the data access error interrupt is enabled by MPU control register MPUCR:DEE =1, the data access error interrupt is triggered and the CPU performs data access error interrupt processing. If a data access error occurs during access to a bufferable area, because the CPU is executing a subsequence instruction, the PC saved when the data access error interrupt occurs is not the PC value for the instruction that performed the data access.

If an illegal instruction exception (data access error) occurs during the execution of an instruction that performs multiple data accesses, the data accesses that had executed up until the error occurred are not cancelled. If an illegal instruction exception (data access error) occurs during the LDM0, LDM1, STM0, STM1, FLDM, or FSTM instructions, the list of remaining registers is stored in the exception status register ESR:RL, and the bit indicating a data access error ESR:INV6 is set.

If an illegal instruction exception (data access error) occurs during the EIT processing sequence or the RETI instruction, the CPU is halted and can only be recovered by break interrupt or reset.

10.4.5. Memory Protection Operation by Delay Slot

The memory protection operation by a delay slot is shown.

The instruction arranged in the delay slot is processed as 16-bit. Therefore, the exception is generated as an illegal instruction exception (instruction that cannot be arranged in the delay slot) even if there are an instruction access protection violation factor and an instruction access error factor in the lower 16-bit by arranging 32-bit instruction in the delay slot.

10.4.6. DEAR and DESR Update

The DEAR and the DESR update are shown.

The data access error address register (DEAR) and the data access error status register (DESR) are renewed in the following cases.

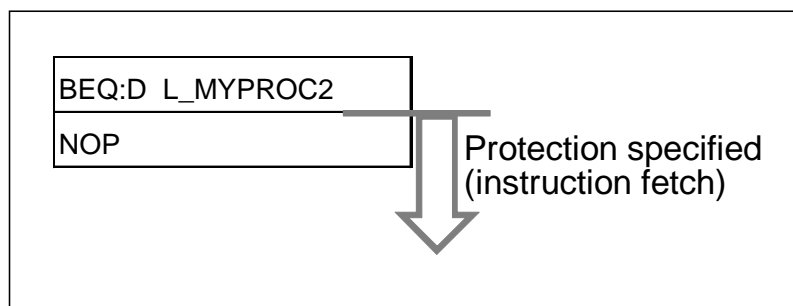
- System register access in user mode (illegal instruction exception)
- Bus error in buffer prohibition area access (illegal instruction exception)
- Bus error in buffer permission area access (data access error interrupt)

DEAR and DESR are renewed in the instruction that did the corresponding access and it is renewed to the asynchronization with the instruction operation in the case where the data access error interrupt is generated in the case where the illegal instruction exception is generated. It gives priority to the illegal instruction exception factor when the factor is generated at the same time.

10.4.7. Notes

This section explains notes of the Memory Protection Function (MPU).

- Access protection violation exception will occur when an instruction of access protection violation is executed. For details, see "FR Family FR81 32-bit Microcontroller Programming Manual". For details of the instruction access protection violation and the instruction access protection violation exception, also see "10.4.2. Instruction Access Protection Violation".
- If the boundary of delay slot is different from that of instruction access protection area, the instruction access protection violation occurs regardless of whether the branch is established or not. PC with occurrence of exception is PC of delayed branch instruction.



CHAPTER : OPERATION MODE

This chapter explains the operation mode.

1. Overview
2. Features
3. Configuration
4. Register
5. Operation

1. Overview

This section explains the overview of the operation mode.

This chapter explains the operation mode of this type of item decided after reset is released. See "CHAPTER: POWER CONSUMPTION CONTROL" for the mode of each power consumption control and the mode of each clock selection.

2. Features

This section explains features of the operation mode.

This device supports the following operation modes.

- **User mode**

The external bus of the 16-bit bus width for GDC only can be used.

The program starts from the built-in FLASH.

- **Serial writer mode**

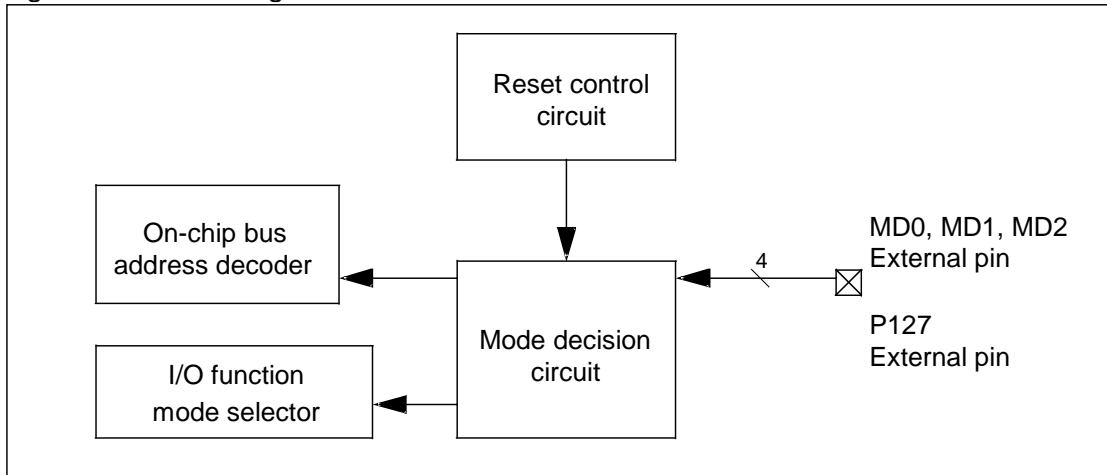
It is a mode to which the built-in FLASH is programmed by using the serial writer.

The program starts from the built-in Boot-ROM.

3. Configuration

This section explains the configuration of the operation mode.

Figure 3-1 Block Diagram



4. Register

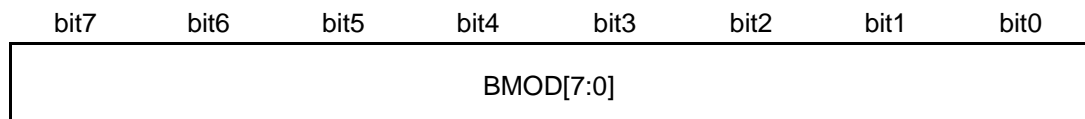
This section explains the register of the operation mode.

Address	Register				Register function
	+0	+1	+2	+3	
0x07FC	BMODR	Reserved	Reserved	Reserved	Bus mode data register

■ Bus Mode Register : BMODR (Bus MODE Register)

This register indicates the mode that has been set during startup. The register data can be read only. Data writing does not affect on this register value.

● BMODR : Address 07FC_H (Access : Byte, Half-word, Word)



Initial value	*	*	*	*	*	*	*	*
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

* It depends on operation mode.

[bit7 to bit0] BMOD[7:0] : Operation mode

These bits indicate the current operation mode. Data writing is ineffective.

BMOD[7:0]	Operation mode
0101xxxx	User mode
0111xx1x	Serial writer mode

5. Operation

This section shows operations of the operation mode.

- 5.1. MD0, MD1, MD2, P127 Pins Settings
- 5.2. Fetching the Operation Mode
- 5.3. Explanation of Each Operation Mode

5.1. MD0, MD1, MD2, P127 Pins Settings

MD0, MD1, MD2 and P127 pins settings are shown.

Table 5-1 Pin Settings

Operation mode	MD2	MD1	MD0	P127
User mode	0	0	0	-
Serial writer mode	0	0	1	1

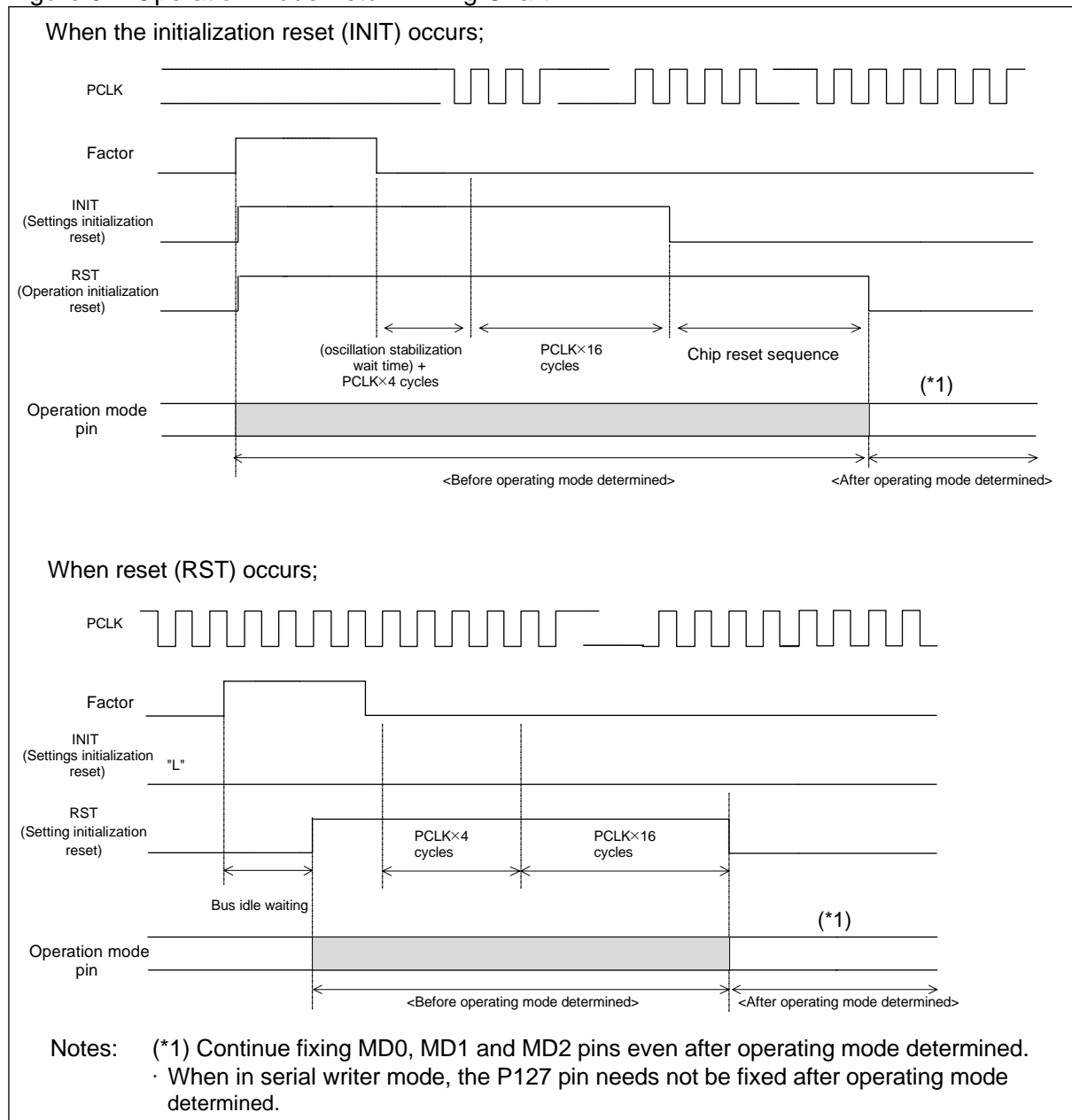
5.2. Fetching the Operation Mode

This section explains fetching the operation mode.

The operation mode is fetched by sampling the RST (Reset). During the time when an RST is issued and when it is released, the MD0, MD1, MD2 and P127 pin inputs must be determined. (The P127 pin needs not be determined in the User mode.)

The following shows an operation sequence from an occurrence of reset cause to the determination of an operation mode.

Figure 5-1 Operation Mode Fetch Timing Chart



5.3. Explanation of Each Operation Mode

This section explains each operation mode.

The following details each operation mode.

■ **User Mode**

An external bus pin is reset immediately when a reset is entered for the external reset pin. For details, see "D. Pin Status in CPU Status" in "APPENDIX".

■ **Serial Writer Mode**

Contact their representatives.

CHAPTER : CLOCK

This chapter explains the clock.

1. Overview
2. Features
3. Configuration
4. Register
5. Operation

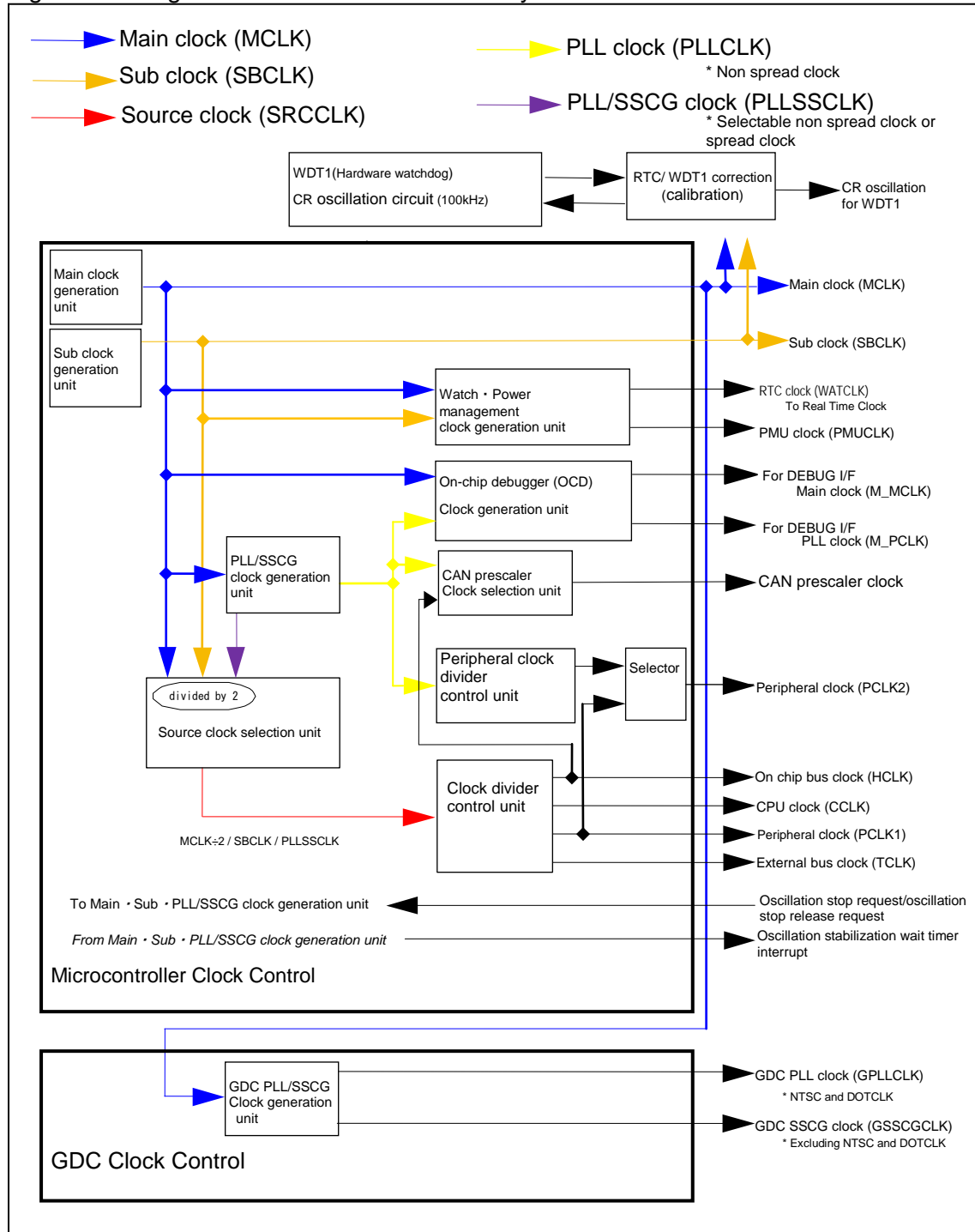
1. Overview

This section explains the overview of the clock.

The built-in oscillation circuit generates a dual clock product, which generates individual clock systems on the chip. This product also implements the CR oscillation circuit for watchdog timer 1.

- External pins for the built-in oscillation circuit :
 - Main clock : Connects to the crystal oscillator
 - Sub clock : Connects to the crystal oscillator
- Generation of source clocks : Selects from the clocks which are multiplied by PLL/SSCG of main clock (MCLK) or divided by 2 of main clock, or sub clock (SBCLK).
- Division of source clock : Divides the source clock and generates operating clocks for supplying to each unit.

Figure 1-1 Diagram of the Clock Generation System



2. Features

This section explains features of the clock.

- 2 system on-chip oscillators is implemented.
- The main clock (MCLK) is multiplied by on-chip PLL/SSCG.
- Microcontroller/GDC multiply clock is supplied by independent PLL/SSCG.
- Each clock has been forced not to supply by using the timer until it becomes stabilized (oscillation stabilization wait timer).
- Oscillation stabilization wait end interrupt can be generated.
- Main clock oscillation stabilization wait timer (main timer) and sub clock oscillation stabilization wait timer (sub timer) can be used as a general-purpose interrupt interval timer after the oscillation stabilization of each clock for main, and sub takes place.
- The clock for the real time clock can be selected from the main clock (MCLK) and the sub clock (SBCLK).
- Implements a CR oscillation circuit for 100kHz WDT1 clock. See "CHAPTER: RTC/WDT1 CALIBRATION" for configuration (calibration) of this oscillation circuit.
- Generates the clock for CAN prescaler. Use the PLL clock (PLLCLK) [non spread clock] when using a PLL, otherwise use the on-chip bus clock (HCLK).
- For the noise decrement, the SSCG clock [spread clock] can be selected as CPU and a clock of the resource.

3. Configuration

This section explains the configuration of the clock.

Figure 3-1 Connection Diagram of Clock (1)-1 Main Clock Generation Unit

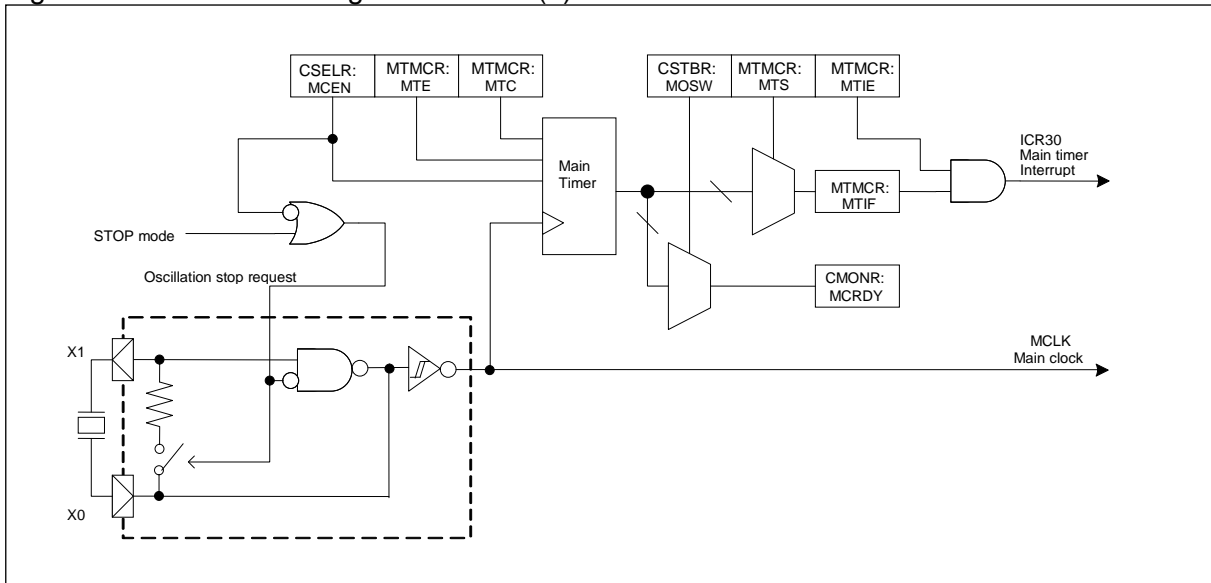


Figure 3-2 Connection Diagram of Clock (1)-2 Sub Clock Generation Unit

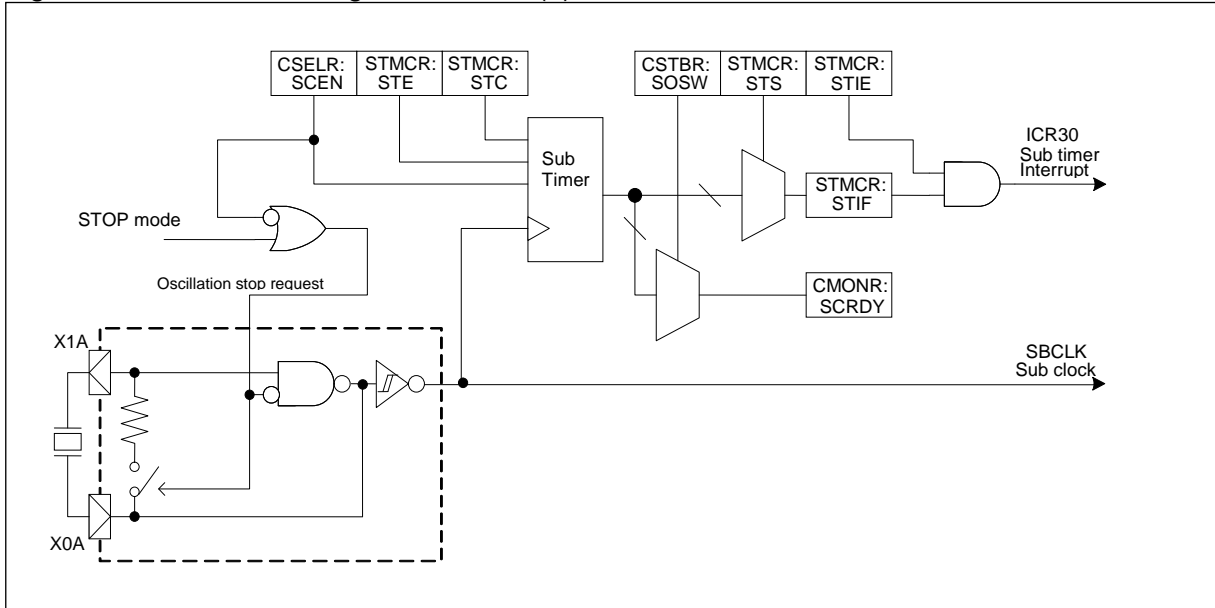


Figure 3-3 Connection Diagram of Clock (1)-3 PLL Clock Generation Unit

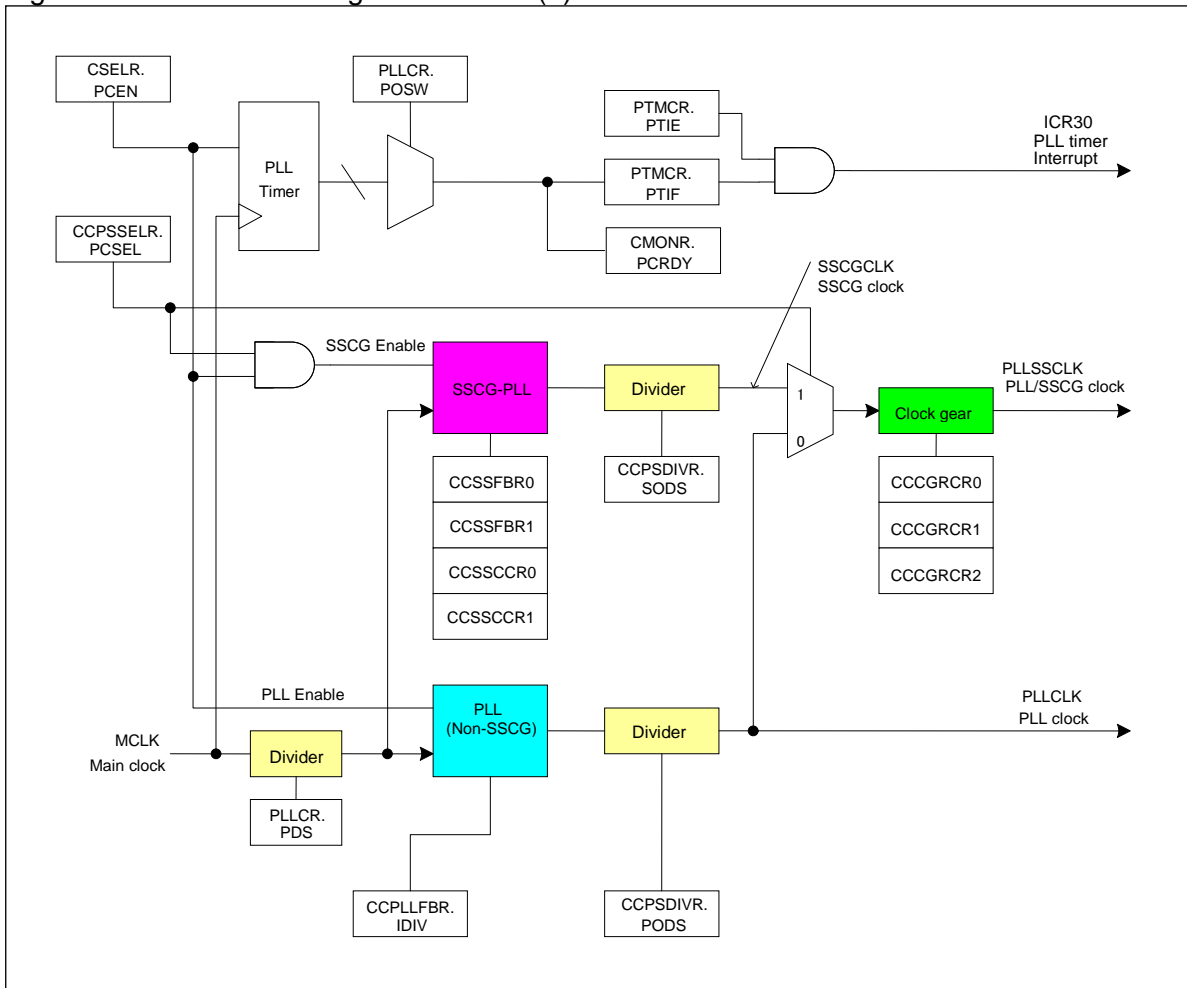


Figure 3-4 Connection Diagram of Clock (2) Source Clock Selection Unit

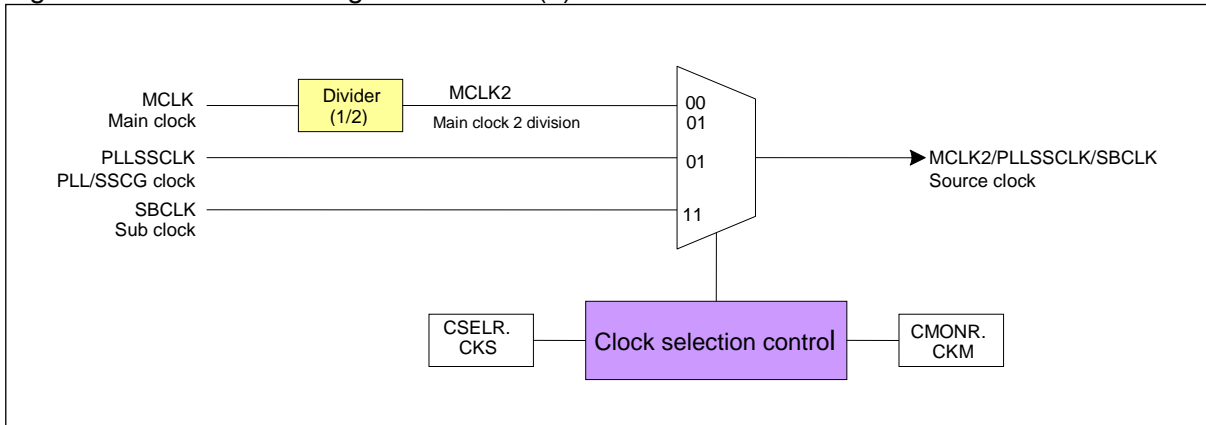


Figure 3-5 Connection Diagram of Clock (3) Divider Control

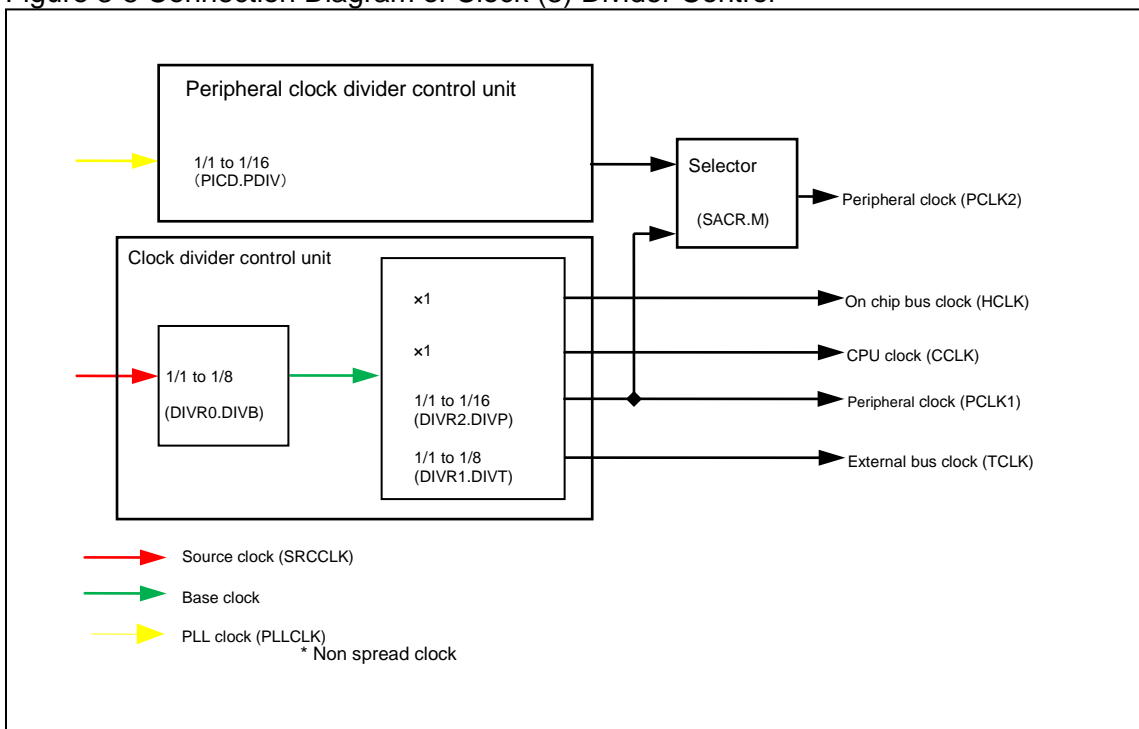


Figure 3-6 Connection Diagram of Clock (4) CAN Prescaler Clock Generation

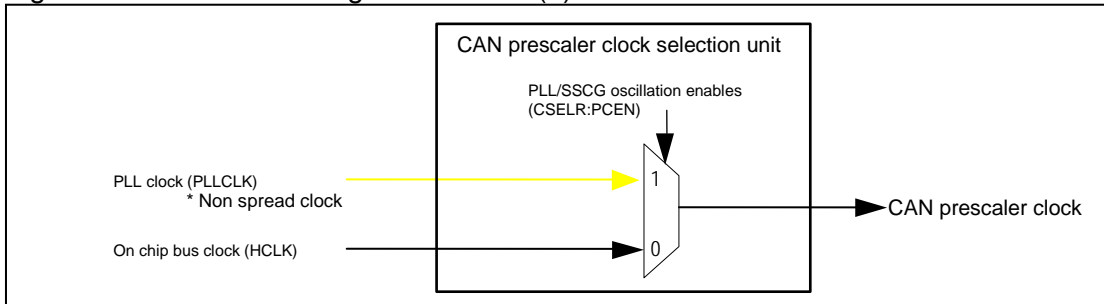


Figure 3-7 Connection Diagram of Clock (5) GDC Clock Generation

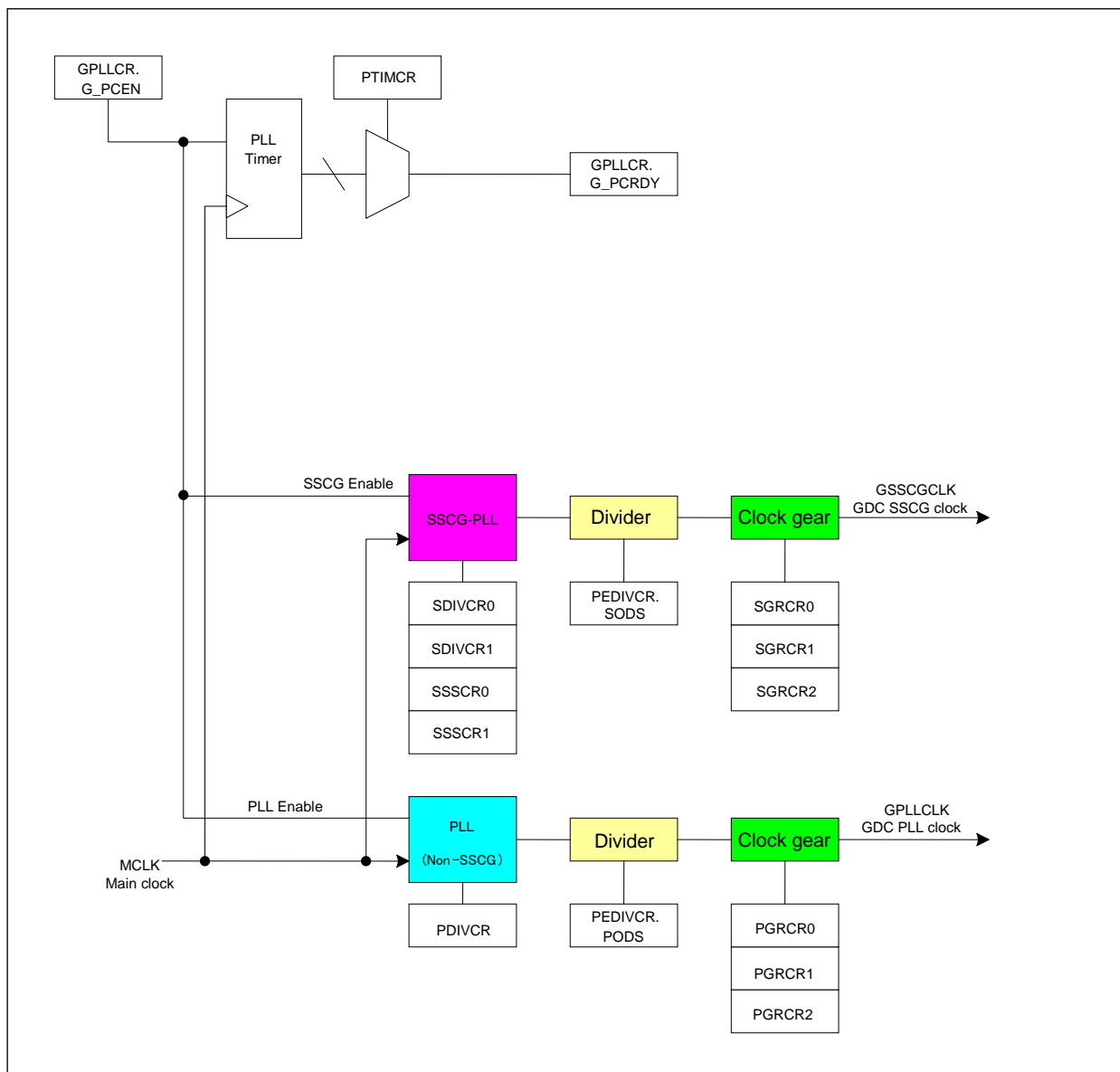


Figure 3-8 Connection Diagram of Clock (6) Watch/Power Management Clock Generation

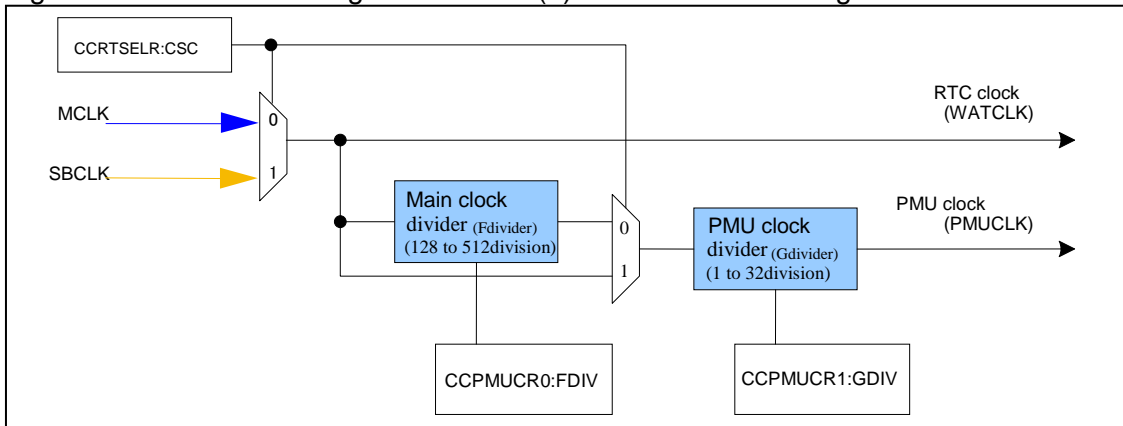
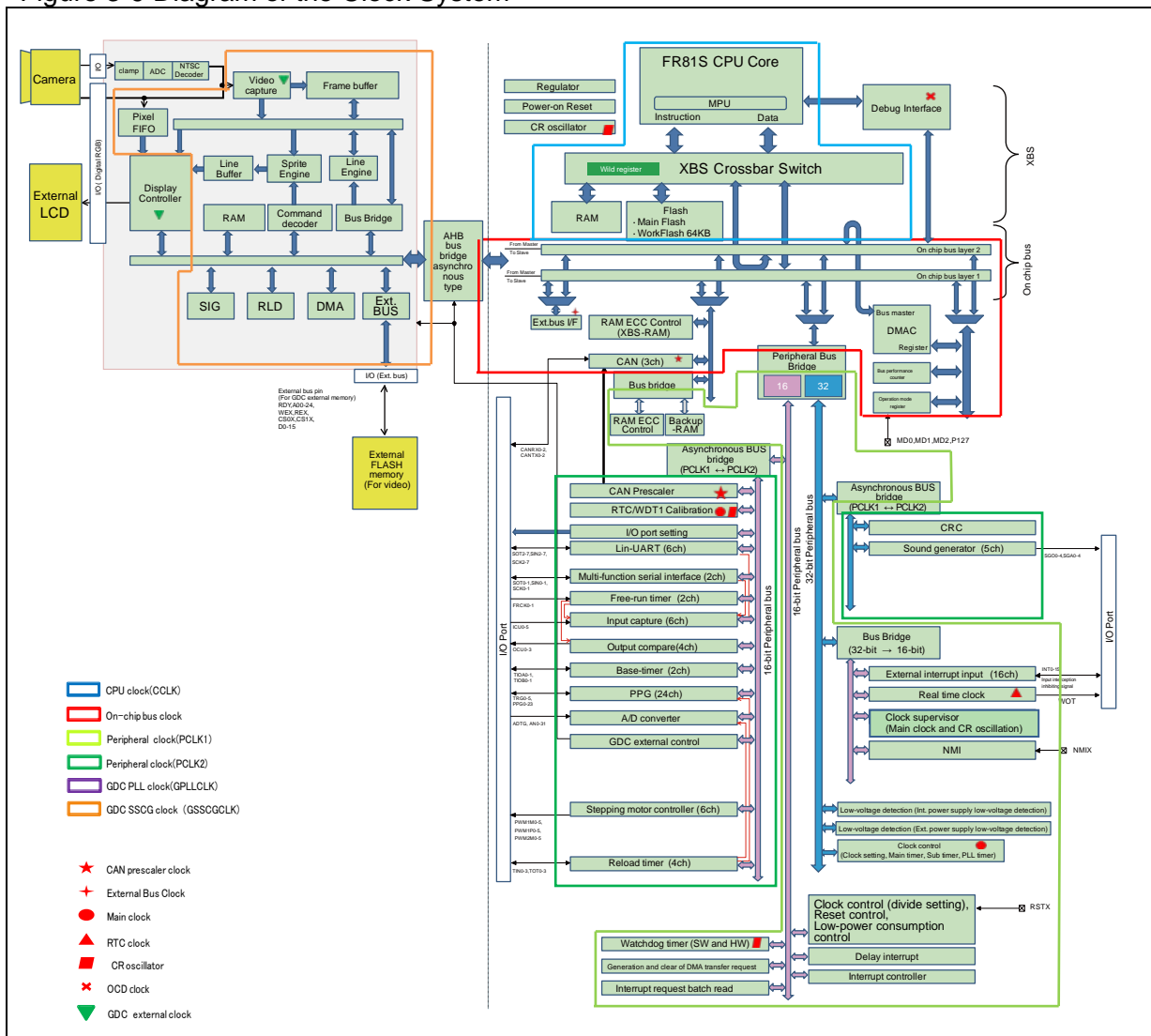


Figure 3-9 Diagram of the Clock System



4. Registers

This section explains registers of the clock.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0488	DIVR0	DIVR1	DIVR2	Reserved	Division Configuration Register 0 Division Configuration Register 1 Division Configuration Register 2
0x0510	CSELR	CMONR	MTMCR	STMCR	Clock Source Configuration Register Clock Source Monitor Register Main Timer Control Register Sub Timer Control Register
0x0514	PLLCR		CSTBR	PTMCR	PLL Setting Register Oscillation Stabilization Wait Setting Register PLL clock Oscillation Stabilization Wait Timer Control Register
0x0520	CCPSELR	Reserved	Reserved	CCPSDIVR	PLL/SSCG Clock Selection Register PLL/SSCG Output Clock Division Setting Register
0x0524	Reserved	CCPLLFBR	CCSSFBR0	CCSSFBR1	PLL Feedback Division Setting register SSCG Feedback Division Setting register 0 SSCG Feedback Division Setting register 1
0x0528	Reserved	CCSSCCR0	CCSSCCR1		SSCG configuration setting register 0 SSCG configuration setting register 1
0x052C	Reserved	CCCGRCR0	CCCGRCR1	CCCGRCR2	Clock Gear Configuration setting Register 0 Clock Gear Configuration setting Register 1 Clock Gear Configuration setting Register 2
0x0530	CCRTSELR	Reserved	CCPMUCR0	CCPMUCR1	RTC/PMU Clock Selection Register PMU Clock Division Register 0 PMU Clock Division Register 1
0x0534	Reserved	Reserved	Reserved	Reserved	Reserved
0x0538	Reserved	Reserved	Reserved	Reserved	Reserved
0x053C	Reserved	Reserved	Reserved	Reserved	Reserved
0x0F50	Reserved	GPLLCR	PTIMCR	PEDIVCR	GDC PLL Control Register GDC PLL Timer Setting Register GDC PLL External Division Setting Register
0x0F54	Reserved	PDIVCR	SDIVCR0	SDIVCR1	GDC PLL Multiply Setting Register GDC PLL_SSCG Multiply Setting Register 0 GDC PLL_SSCG Multiply Setting Register 1

Address	Registers				Register function
	+0	+1	+2	+3	
0x0F58	Reserved	SSSCR0	SSSCR1		GDC PLL_SSCG Spread Spectrum Setting Register 0 GDC PLL_SSCG Spread Spectrum Setting Register 1
0x0F5C	Reserved	PGRCR0	PGRCR1	PGRCR2	GDC PLL Clock Gear Setting Register 0 GDC PLL Clock Gear Setting Register 1 GDC PLL Clock Gear Setting Register 2
0x0F60	Reserved	SGRCR0	SGRCR1	SGRCR2	GDC PLL_SSCG Clock Gear Setting Register 0 GDC PLL_SSCG Clock Gear Setting Register 1 GDC PLL_SSCG Clock Gear Setting Register 2
0x1000	SACR	PICD	Reserved	Reserved	Sync/Async Control Register Peripheral Interface Clock Divider

4.1. Division Configuration Register 0 : DIVR0 (Division clock configuration Register 0)

The bit configuration of the division configuration register 0 is shown.

This register controls division of clocks.

■ DIVR0 : Address 0488_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DIVB[2:0]			Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit5] DIVB[2:0] (Division ratio of Baseclock) : Base clock division setting

These bits configure a division in the area where the base clock is generated from the source clock (SRCCLK) as follows.

The CPU clock (CCLK) and the on-chip bus clock (HCLK) have the same frequency as that of the base clock.

DIVB[2:0]	Division ratio
000	Do not divide (Initial value)
001	2 division
010	3 division
011	4 division
100	5 division
101	6 division
110	7 division
111	8 division

[bit4 to bit0] (Reserved)

4.2. Division Configuration Register 1 : DIVR1 (Division clock configuration Register 1)

The bit configuration of the division configuration register 1 is shown.

This register controls division of clocks.

■ DIVR1 : Address 0489_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TSTP	DIVT[2:0]			Reserved			
Initial value	0	0	0	1	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7] TSTP (TCLK SToP) : External bus clock stop enable

This bit configures whether to stop the external bus clock (TCLK) when going into sleep mode.

TSTP	TCLK in sleep mode
0	Do not stop (Initial value)
1	Stop

[bit6 to bit4] DIVT[2:0] (DIVide ratio of TCLK) : External bus clock division setting

These bits configure the division ratio when generating the external bus clock (TCLK) from the base clock.

DIVT[2:0]	Base clock → TCLK division ratio
000	Do not divide
001	2 division (Initial value)
010	3 division
011	4 division
100	5 division
101	6 division
110	7 division
111	8 division

Note:

Set this register so that the external bus clock (TCLK) definitely becomes 40MHz or less.

[bit3 to bit0] (Reserved)

4.3. Division Configuration Register 2 : DIVR2 (Division clock configuration Register 2)

The bit configuration of the division configuration register 2 is shown.

This register controls division of clocks.

■ **DIVR2 : Address 048A_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DIVP[3:0]				Reserved			
Initial value	0	0	1	1	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit4] DIVP[3:0] (Division ratio of PCLK) : Peripheral clock division setting

These bits configure the division ratio when generating the peripheral clock (PCLK1) from the base clock.

DIVP[3:0]	Base clock → PCLK1 division ratio
0000	Do not divide
0001	2 division
0010	3 division
0011	4 division (Initial value)
0100	5 division
0101	6 division
0110	7 division
0111	8 division
1000	9 division
1001	10 division
1010	11 division
1011	12 division
1100	13 division
1101	14 division
1110	15 division
1111	16 division

Note:

Set this register to peripheral clock (PCLK1) to be sure to become 40MHz or less.

[bit3 to bit0] (Reserved)

4.4. Clock Source Selection Register : CSELR (Clock source Selection Register)

The bit configuration of the clock source selection register is shown.

This register selects a control and a source clock (SRCCLK) for each clock source.

Note:

The value set for this register and the value read out from this register are not actually controlled and selected. You can make sure that the value set for this register would really take effect by reading out CMONR. After making sure that the value of this register is the same as that of CMONR, rewrite the register. While switching clocks is in progress (CKS[1:0] ≠ CKM[1:0]), a write operation to this register will be ignored.

■ **CSELR : Address 0510_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SCEN	PCEN	MCEN	Reserved			CKS[1:0]	
Initial value	*	0	1	0	0	0	0	0
Attribute	R,W	R,W	R,W	R0,WX	R0,WX	R0,WX	R,W	R,W

*: This bit is initialized to "0". But this bit is not initialized by the return from the watch mode (power shut-down).

[bit7] SCEN (Sub Clock ENable) : Sub clock oscillation enable

This bit controls an oscillation circuit for sub clock (SBCLK) as follows.

SCEN	Oscillation control for sub clock
0	Stop oscillation (Initial value)
1	Oscillate

This bit cannot be rewritten when a sub clock (SBCLK) is selected as the source clock (SRCCLK).

The oscillation circuit for sub clock always stops in stop mode regardless of the value of this bit.

The sub timer is cleared when this bit is set to "0".

For a single clock product, this bit always reads "0" and therefore a write operation would not be affected.

Note:

It takes main clock × about 3 cycles + sub clock × about 3 cycles until the switch operation of RTC and PMU clock completes after rewriting the CSC bit . When main clock and sub clock oscillation are stopped during the switching operation, the switching operation does not complete correctly. The oscillation must always be stopped in the status that the CST bit is "0" (the status of the completion of switching).

The CSC bit is not initialized by the return from the standby watch mode (power shut-down). Moreover, any reset factors other than those, caused by power on reset/internal low voltage reset/RSTX-NMIX simultaneous assertion, can not be accepted because an internal reset signal is generated while returning from the standby watch mode (power shut-down). At this time the CSC bit is not initialized. Initialize this bit in case of need, when the reset signal comes from RSTX terminal input or external low-voltage detection is flagged after the return from power shut-down.

[bit6] PCEN (PLL Clock ENable) : PLL oscillation enable

This bit controls the PLL/SSCG clock oscillation circuit as follows .

PCEN	Oscillation control for PLL/SSCG clock (PLLSSCLK)
0	Stop oscillation (Initial value)
1	Oscillate

This bit cannot be rewritten when a PLL/SSCG clock (PLLSSCLK) is selected as the source clock (SRCCLK). Also, this bit cannot be rewritten when the main clock oscillation is stopped or during the main clock oscillation stabilization wait time (CMONR. MCRDY=0).

Set this bit to "0" before switching to the stop mode.

Rewriting the MCEN bit with "0" causes this bit to set to "0".

Note:

PLL enters the status of the oscillation enable regardless of the value of this bit while communicating the MDI in high-speed.

[bit5] MCEN (Main Clock ENable) : Main clock oscillation enable

This bit controls an oscillation circuit for main clock as follows.

MCEN	Oscillation control for main clock
0	Stop oscillation
1	Oscillate (Initial value)

This bit cannot be rewritten when a main clock (MCLK) or PLL/SSCG clock (PLLSSCLK) is selected as the source clock (SRCCLK).

The oscillation circuit for main clock always stops in stop mode regardless of the value of this bit.

The main timer is cleared when this bit is set to "0".

Note:

The main clock enters the status of the oscillation enable regardless of the value of this bit while communicating the MDI in low-speed.

[bit4 to bit2] (Reserved)

[bit1, bit0] CKS[1:0] (Clock Select) : Source clock selection

These bits select the source clock (SRCCLK) as follows.

CKS[1:0]	Source selection
00	Division of the main clock (MCLK) by 2(Initial value)
01	Division of the main clock (MCLK) by 2
10	PLL/SSCG clock (PLLSSCLK)
11	Sub clock (SBCLK)

However, when $CKS[1:0] \neq CKM[1:0]$, these bits cannot be rewritten. When the clock oscillation which you are trying to switch operations by these bits stops or is waiting for a stabilization (CMONR:xCRDY=0), this bit cannot also be rewritten.

A direct switch from PLL/SSCG clock (PLLSSCLK) to the sub clock (SBCLK) or vice versa cannot be performed.

Possible combinations for changing these bits are shown below.

CKS value before change	Eligible values	Rewritten conditions	Ineligible values
00	00, 01	MCRDY=1	11
	10	PCRDY=1	
01	00, 01	MCRDY=1	10
	11	SCRDY=1	
10	00	MCRDY=1	01,11
	10	PCRDY=1	
11	01	MCRDY=1	00,10
	11	SCRDY=1	

Do not write the values which cannot be rewritten.

4.5. Clock Source Monitor Register : CMONR (Clock source MONitor Register)

The bit configuration of the clock source monitor register is shown.

This register displays a status and a source clock (SRCCLK) for each clock source.

You can confirm that the value set at CSELR is really reflected in the actual status by reading this register.

Note:

If you have changed CSELR, do not write next value on CSELR until CMONR is equal to CSELR.

■ CMONR: Address 0511_H (Access : Byte, Half-word, Word)

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCRDY	PCRDY	MCRDY	Reserved			CKM[1:0]	

Initial value * 0 1 0 0 0 0 0

Attribute R,WX R,WX R,WX R0,WX R0,WX R0,WX R,WX R,WX

*: This bit is initialized to "0". But this bit is not initialized by the return from the watch mode (power shut-down).

[bit7] SCRDY (Sub Clock ReaDY) : Sub clock ready

This bit shows the sub clock (SBCLK) status as follows.

SCRDY	Sub clock (SBCLK) status
0	Oscillation stops or in the oscillation stabilization wait status.
1	It is in the oscillation stabilization status and available for the source clock.

This bit cannot select a sub clock (SBCLK) as the source clock (SRCCLK) when this bit is set to "0".

Note:

SCRDY=1 may be read immediately after changing SCEN=1 to 0.

[bit6] PCRDY (PLL Clock ReaDY) : PLL clock ready

This bit shows the PLL/SSCG clock (PLLSSCLK) status as follows.

PCRDY	PLL/SSCG clock (PLLSSCLK) status
0	Oscillation stops or in the oscillation stabilization wait status.
1	It is in the oscillation stabilization status and available for the source clock.

This bit cannot select a PLL/SSCG clock (PLLSSCLK) as the source clock (SRCCLK) when this bit is set to "0".

Note:

PCRDY=1 may be read immediately after changing PCEN=1 to 0.
PLL enters the status of the oscillation enable regardless of the value of this bit while communicating the MDI in high-speed.

[bit5] MCRDY (Main Clock ReaDY) : Main clock ready

This bit shows the main clock (MCLK) status as follows.

MCRDY	Main clock (MCLK) status
0	Oscillation stops or in the oscillation stabilization wait status.
1	It is in the oscillation stabilization status and available for the source clock.

This bit cannot select a main clock (MCLK) or a PLL/SSCG clock (PLLSSCLK) as the source clock (SRCCLK) when this bit is set to "0".

The initial value of "1" for this bit means that it is oscillation stabilized at the first reset vector fetch after power-on reset, not that it is already oscillation stabilized immediately after power-on reset.

Note:

MCRDY=1 may be read immediately after changing MCEN=1 to 0.
The main clock enters the status of the oscillation enable regardless of the value of this bit while communicating the MDI in high-speed.

[bit4 to bit2] (Reserved)

[bit1, bit0] CKM[1:0] (Clock Monitor) : Source clock display

These bits show the source clock (SRCCLK) currently selected.

CKM[1:0]	Source selection
00	Division of main clock (MCLK) by 2
01	Division of main clock (MCLK) by 2
10	PLL/SSCG clock (PLLSSCLK)
11	Sub clock (SBCLK)

4.6. Main Timer Control Register : MTMCR (Main clock TiMer Control Register)

The bit configuration of the main timer control register is shown.

This register controls the main timer which runs with the main clock (MCLK).

■ MTMCR : Address 0512_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MTIF	MTIE	MTC	MTE	MTS[3:0]			
Initial value	0	0	0	0	1	1	1	1
Attribute	R(RM1),W	R/W	R(RM0),W	R/W	R1,WX	R/W	R/W	R/W

Because the main timer is used for generating the oscillation stabilization wait time for main clock (MCLK), it can be used only after the main clock oscillation is stabilized.

The main timer is cleared when the main clock oscillation stops (MCEN=0) or it is in the stop mode.

When the operation of the main timer is not allowed (MTE=0), the main timer stops except that it is waiting for a main clock oscillation stabilization. The write operation to this register becomes enabled only when MCRDY=1 except for MTIE. Thus a main timer clear executed by MTC=1 in main clock oscillation stabilization wait status (MCEN=1 and MCRDY=0) is not effective.

When the main timer stops (MTE=0) it will be cleared and while being cleared MTC=1 will be read out.

At that time the main timer interrupt flag (MTIF) is not set. The main timer overflow period (MTS[3:0]) should be changed at the time when the main timer stops (MTE=0).

When rewriting MTE=1 with 0, the main timer will continue to operate until the MTC bit is set to "0". In this interval, the main timer interrupt flag may turn to "1". When writing MTC=1, the main timer will continue to operate until the MTC bit is set to "0". In this interval, the main timer interrupt flag may turn to "1". If a MTE=0 to 1 rewrite and a MTC=1 write occur at the same time, the operation starts after a clear takes place, so the start will be delayed.

[bit7] MTIF (Main clock Timer Interrupt Flag) : Main timer interrupt flag

The flag to indicate that an overflow happens in the interval for which the main timer has selected.

When the MTIE bit is "1" and this bit is set, a main timer interrupt request is generated.

Clear factor	<ul style="list-style-type: none"> "0" write A DMA transfer is generated by the main timer interrupt.
Set factor	<ul style="list-style-type: none"> An overflow occurred in the interval set by MTS[3:0] The end of oscillation stabilization wait time of the main clock after setting MCEN=0 to 1. The end of oscillation stabilization wait time of the main clock (MCLK) after exiting the stop mode. (A set will not take place at the end of oscillation stabilization wait time after reset by SINIT.)

Writing "1" to this bit is ineffective.

When the MTIE bit is set to "0", this bit will not be cleared by DMA transfer.

For read-modify-write instructions, "1" will be read out.

If a set factor and a clear factor occur at the same time, the set factor will take precedence.

[bit6] MTIE (Main clock Timer Interrupt Enable) : Main timer interrupt enabled
This bit controls interrupts by main timer overflow as follows.

MTIE	Main timer interrupt
0	Interrupt disabled (Initial value)
1	Interrupt enabled (outputs the interrupt request at the time when the MTIF bit is "1")

[bit5] MTC (Main clock Timer Clear) : Main timer clear
This bit clears the main timer.

MTC	Write
0	Does nothing.
1	Clear the main timer.

MTC	Read
0	Operating normally
1	Clearing the main timer

This bit automatically returns to "0" after writing "1".
For read-modify-write instructions, "0" will be read out.
When writing MTC=1 at the time of MTC=1, the second write will be ignored.

[bit4] MTE (Main clock Timer Enable) : Main timer operation enable
This bit controls the operation of the main timer as follows.

MTE	Main timer operation
0	Operation disabled (Initial value)
1	Operation enabled

At the time of MTC=1, MTE=1 write is prohibited.

When you perform a PLL/SSCG clock oscillation stabilization wait, make sure to set this bit to "0" and stop the main timer.

[bit3 to bit0] MTS[3:0] (Main clock Timer interval selection) : Main timer interval selection
These bits select the overflow interval of the main timer as follows.

MTS[3:0]	Main timer overflow interval	At 4MHz
1000	$2^9 \times$ main clock cycle	128.0[μ s]
1001	$2^{10} \times$ main clock cycle	256.0[μ s]
1010	$2^{11} \times$ main clock cycle	512.0[μ s]
1011	$2^{12} \times$ main clock cycle	1024.0[μ s]
1100	$2^{13} \times$ main clock cycle	2048.0[μ s]
1101	$2^{14} \times$ main clock cycle	4096.0[μ s]
1110	$2^{15} \times$ main clock cycle	8192.0[μ s]
1111	$2^{16} \times$ main clock cycle (Initial value)	16384.0[μ s]

The MTS3 bit always reads "1".
Change MTS[3:0] at the time when the main timer stops (MTE=0).

4.7. Sub Timer Control Register : STMCR (Sub clock TiMer Control Register)

The bit configuration of the sub timer control register is shown.

This register controls the sub timer which runs with the sub clock.

■ STMCR: Address 0513_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	STIF	STIE	STC	STE	Reserved	STS[2:0]		
Initial value	0	0	0	0	0	1	1	1
Attribute	R(RM1),W	R/W	R(RM0),W	R/W	R0,WX	R/W	R/W	R/W

Because the sub timer is used for generating the oscillation stabilization wait time for the sub clock (SBCLK), it can be used only after the sub clock oscillation is stabilized.

The sub timer is cleared when the sub clock oscillation stops (SCEN=0) or it is in the stop mode.

When the operation of the sub timer is not allowed (STE=0), the sub timer stops except that it is waiting for a sub clock oscillation stabilization. The write operation to this register becomes enabled only when SCRDY=1 except for STIE. Thus a sub timer clear executed by STC=1 in sub clock oscillation stabilization wait status (SCEN=1 and SCRDY=0) is not effective.

When the sub timer stops (STE=0) it will be cleared and while being cleared STC=1 will be read out. At that time the sub timer interrupt flag is not set. The sub timer overflow period (STS[2:0]) should be changed at the time when the sub timer stops (STE=0).

When rewriting STE=1 with 0, the sub timer will continue to operate until STC is set to "0". In this interval, the sub timer interrupt flag may turn to "1". When writing STC=1, the sub timer will continue to operate until STC is set to "0". In this interval, the sub timer interrupt flag may turn to "1". If a STE=0 to 1 rewrite and a STC=1 write occur at the same time, the operation starts after a clear takes place, so the start will be delayed.

[bit7] STIF (Sub clock Timer Interrupt Flag) : Sub timer interrupt flag

The flag to indicate that an overflow happens in the interval for which the sub timer has selected.

When the STIE bit is "1" and this bit is set, a sub timer interrupt request is generated.

Clear factor	<ul style="list-style-type: none"> "0" write A DMA transfer is generated by the sub timer interrupt.
Set factor	<ul style="list-style-type: none"> An overflow occurred in the interval set by STS[2:0]. The end of oscillation stabilization wait time of the sub clock after setting SCEN=0 to 1. The ends of oscillation stabilization wait time of the sub clock after exiting the stop mode.

Writing "1" to this bit is ineffective.

When the STIE bit is set to "0", this bit will not be cleared by DMA transfer.

For read-modify-write instructions, "1" will be read out.

If a set factor and a clear factor occur at the same time, the set factor will take precedence.

[bit6] STIE (Sub clock Timer Interrupt Enable) : Sub timer interrupt enable

This bit controls interrupts by sub timer overflow as follows.

STIE	Sub timer interrupt
0	Interrupt disabled (Initial value)
1	Interrupt enabled (output the interrupt request at the time STIF bit is "1")

[bit5] STC (Sub clock Timer Clear) : Sub timer clear

This bit clears the sub timer.

STC	Write
0	Does nothing.
1	Clear the sub timer.

STC	Read
0	Operating normally
1	Clearing the sub timer

This bit automatically returns to "0" after writing "1".

For read-modify-write instructions, "0" will be read out.

When writing STC=1 at the time of STC=1, the second write will be ignored.

[bit4] STE (Sub clock Timer Enable) : Sub timer operation enabled

This bit controls the operation of the sub timer as follows.

STE	Sub timer operation
0	Operation disabled (Initial value)
1	Operation enabled

At the time of STC=1, STE=1 write is prohibited.

[bit3] (Reserved)

[bit2 to bit0] STS[2:0] (Sub clock Timer interval selection) : Sub timer interval selection

These bits select the overflow interval of the sub timer as follows.

STS[2:0]	Sub timer overflow interval	At 32kHz
000	$2^8 \times$ sub clock cycle	8[ms]
001	$2^9 \times$ sub clock cycle	16[ms]
010	$2^{10} \times$ sub clock cycle	32[ms]
011	$2^{11} \times$ sub clock cycle	64[ms]
100	$2^{12} \times$ sub clock cycle	128[ms]
101	$2^{13} \times$ sub clock cycle	0.256[s]
110	$2^{14} \times$ sub clock cycle	0.512[s]
111	$2^{15} \times$ sub clock cycle (Initial value)	1.024[s]

4.8. PLL Setting Register : PLLCR (PLL Configuration Register)

The bit configuration of the PLL setting register is shown.

This register configures the multiplication rate or division ratio in the PLL/SSCG clock oscillation circuit and the oscillation stabilization wait time.

■ PLLCR: Address 0514_H (Access : Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved		Reserved	Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,WX	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	POSW[3:0]				PDS[3:0]			
Initial value	1	1	1	1	0	0	0	0
Attribute	R1,WX	R,W	R,W	R,W	R,W	R,W	R,W	R,W

This register configures the parameters in the PLL/SSCG clock oscillation circuit generating the PLL/SSCG clock (PLLSSCLK) from the main clock (MCLK).

When PLL/SSCG clock oscillation is allowed (CSELR:PCEN=1), writing to this register will be disabled.

[bit15, bit14] Reserved
Always write "0".

[bit13] (Reserved)

[bit12 to bit8] Reserved
Always write "0".

[bit7 to bit4] POSW[3:0] (PLL clock clock OSc Wait) : PLL clock oscillation stabilization wait selection
These bits select the oscillation stabilization wait time for the PLL/SSCG clock (PLLSCLK) as follows.

POSW[3:0]	PLL/SSCG clock oscillation stabilization wait time	At 4MHz	At 8MHz
1000	$2^9 \times$ main clock cycle	128.0[μ s]	64.0[μ s]
1001	$2^{10} \times$ main clock cycle	256.0[μ s]	128.0[μ s]
1010	$2^{11} \times$ main clock cycle	512.0[μ s]	256.0[μ s]
1011	$2^{12} \times$ main clock cycle	1024.0[μ s]	512.0[μ s]
1100	$2^{13} \times$ main clock cycle	2048.0[μ s]	1024.0[μ s]
1101	$2^{14} \times$ main clock cycle	4096.0[μ s]	2048.0[μ s]
1110	$2^{15} \times$ main clock cycle	8192.0[μ s]	4096.0[μ s]
1111	$2^{16} \times$ main clock cycle (Initial value)	16384.0[μ s]	8192.0[μ s]

POSW3 always reads "1".

Note:

The PLL/SSCG clock oscillation stabilization wait time specification in this model is 200[μ s]. Reserve the 200[μ s] wait time or more by either of the following methods.

- Select 256[μ s] POSW[3:0] or more.
- Reserve the 200[μ s] wait time or more by software processing, regardless of POSW[3:0] settings.

[bit3 to bit0] PDS[3:0] (PLL input clock Divider selection) : PLL input clock divider selection
These bits select the main clock (MCLK) division for the PLL/SSCG input clock as follows.

PDS[3:0]	PLL/SSCG input clock divider select
0000	PLL/SSCG input clock = Main clock / 1
0001	PLL/SSCG input clock = Main clock / 2
0010	PLL/SSCG input clock = Main clock / 3
0011	PLL/SSCG input clock = Main clock / 4
0100	PLL/SSCG input clock = Main clock / 5
0101	PLL/SSCG input clock = Main clock / 6
0110	PLL/SSCG input clock = Main clock / 7
0111	PLL/SSCG input clock = Main clock / 8
1000	PLL/SSCG input clock = Main clock / 9
1001	PLL/SSCG input clock = Main clock / 10
1010	PLL/SSCG input clock = Main clock / 11
1011	PLL/SSCG input clock = Main clock / 12
1100	PLL/SSCG input clock = Main clock / 13
1101	PLL/SSCG input clock = Main clock / 14
1110	PLL/SSCG input clock = Main clock / 15
1111	PLL/SSCG input clock = Main clock / 16

- * Follow the configuration steps for your appropriate PLL/SSCG and system specifications.
- * See "5.1.3 PLL/SSCG Clock (PLLSSCLK)" for configuration samples.

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.9. Clock Stabilization Selection Register : CSTBR (Clock STaBilization selection Register)

The bit configuration of the oscillation stabilization selection register is shown.

This register configures the oscillation stabilization wait for each clock source.

The oscillation stabilization wait time set by this register will be used at the time when returning from the stop/watch mode. It will also be used for a period from the time when the oscillation of a clock which have not been selected as the source clock is allowed until the ready status (CMONR:*CRDY) of that clock switches to "1". If an oscillation stabilization wait is necessary at reset, it will always be set to the stabilization wait time selected as an initial value by this register. Write operations to MOSW[3:0] will not be effective at the main clock oscillation stabilization wait time (MCEN=1 and MCRDY=0).

Write operations to SOSW[2:0] will not be effective at the sub clock oscillation stabilization wait time (SCEN=1 and SCRDY=0).

■ CSTBR: Address 0516_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	SOSW[2:0]			MOSW[3:0]			
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R,W	R,W	R,W	R,W	R,W	R,W	R,W

[bit7] (Reserved)

[bit6 to bit4] : SOSW[2:0] (Sub clock OSc Wait) : Sub clock oscillation stabilization wait selection
These bits select the oscillation stabilization wait time for the sub clock (SBCLK) as follows.

SOSW[2:0]	Sub clock oscillation stabilization wait time	At 32kHz
000	$2^8 \times$ sub clock cycle (Initial value)	8[ms]
001	$2^9 \times$ sub clock cycle	16[ms]
010	$2^{10} \times$ sub clock cycle	32[ms]
011	$2^{11} \times$ sub clock cycle	64[ms]
100	$2^{12} \times$ sub clock cycle	128[ms]
101	$2^{13} \times$ sub clock cycle	0.256[s]
110	$2^{14} \times$ sub clock cycle	0.512[s]
111	$2^{15} \times$ sub clock cycle	1.024[s]

[bit3 to bit0] MOSW[3:0] (Main clock OSc Wait) : Main clock oscillation stabilization wait selection
The main timer interval is set by the set value for MOSW[3:0].
These bits select the oscillation stabilization wait time for the main clock (MCLK) as follows.

MOSW[3:0]	Main clock oscillation stabilization wait time	At 4MHz
0000	$2^{15} \times$ main clock cycle (Initial value)	8[ms]
0001	$2^1 \times$ main clock cycle	500[ns]
0010	$2^5 \times$ main clock cycle	8[μ s]
0011	$2^6 \times$ main clock cycle	16[μ s]
0100	$2^7 \times$ main clock cycle	32[μ s]
0101	$2^8 \times$ main clock cycle	64[μ s]
0110	$2^9 \times$ main clock cycle	128[μ s]
0111	$2^{10} \times$ main clock cycle	256[μ s]
1000	$2^{11} \times$ main clock cycle	512[μ s]
1001	$2^{12} \times$ main clock cycle	1[ms]
1010	$2^{13} \times$ main clock cycle	2[ms]
1011	$2^{14} \times$ main clock cycle	4[ms]
1100	$2^{17} \times$ main clock cycle	33[ms]
1101	$2^{19} \times$ main clock cycle	131[ms]
1110	$2^{21} \times$ main clock cycle	524[ms]
1111	$2^{23} \times$ main clock cycle	2[s]

Note:

Note that the determination detection is done while waiting for the oscillation stability when the cycle of the determination detection is shorter than a set cycle of this register when the Clock supervisor function is effective.

4.10. PLL Clock Oscillation Timer Control Register : PTMCR (PLL clock osc TiMer Control Register)

The bit configuration of the PLL clock Oscillation timer control register is shown.

The timer that works with the main clock that does PLL/SSCG clock oscillation stabilization wait is controlled.

The PLL/SSCG clock oscillation stabilization wait timer is used only at the oscillation stabilization wait time of the PLL/SSCG clock (PLLSSCLK).

The PLL/SSCG clock oscillation stabilization wait time becomes time set by PLLCR:POSW[3:0].

When PLL/SSCG clock oscillation is enabled(CSELR.PCEN=1), PLL/SSCG clock stabilization timer starts counting up. After the oscillation stabilization time elapses, PLL/SSCG clock stabilization timer stops.

Moreover, when PLL/SSCG clock oscillation stop (CSELR:PCEN =0) is done, it is cleared.

■ PTMCR: Address 0517_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	
	PTIF	PTIE	Reserved						
Initial value	0	0	0	0	0	0	0	0	
Attribute	R(RM1),W	R/W	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	

[bit7] PTIF (PLL clock osc wait Timer Interrupt Flag) : PLL clock oscillation stabilization wait timer interrupt flag

It is a flag that shows that the overflow at the time set by PLL clock oscillation stabilization wait selection (PLLCR: POSW [3:0]) was generated. If this bit is set when the PTIE bit is "1", PLL/SSCG clock oscillation stabilization wait timer interrupt request is generated.

Clear factor	<ul style="list-style-type: none"> "0" write Generation of DMA transfer with PLL/SSCG oscillation stabilization wait timer
Set factor	<ul style="list-style-type: none"> End of the oscillation stabilization wait time for PLL/SSCG clock oscillation stabilization wait clock after PCEN=0→1

The "1" writing in this bit is invalid.

When the PTIE bit is '0', the clearness of this bit by the DMA forwarding is not done.

In the read modify write instruction, "1" is read.

The set factor is given priority when a set factor and a clear factor are generated at the same time.

[bit6] PTIE (PLL clock osc wait Timer Interrupt Enable) : PLL clock oscillation stabilization wait timer interrupt enable

The interrupt by the overflow of PLL/SSCG clock oscillation stabilization wait timer is controlled as follows.

PTIE	Operation
0	Interrupt disabled (Initial value)
1	Interrupt enabled (The interrupt request is output when the PTIF bit is "1".)

[bit5 to bit0] (Reserved)

4.11. PLL/SSCG Clock Selection Register : CCPSELR (CCTl PII/Sscg clock Selection Register)

The bit configuration of the PLL/SSCG clock selection register is shown.

It is a register that selects the clock source supplied to system.

This register can be written only at PLL/SSCG clock oscillation stop (CSELR:PCEN = 0).

■ CCPSELR: Address 0520_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							PCSEL
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

[bit7 to bit1] (Reserved)

[bit0] PCSEL (PII Clock source Selection) : PLL/SSCG Clock source selection

It selects the PLL/SSCG clock source.

PCSEL	PLL or SSCG
0	Selects PLL
1	Selects SSCG

Note:

SSCG (Because it is unused) always becomes a reset status for PCSEL=0.
The PLL clock is supplied to CAN and OCDU for PCSEL=1.

4.12. PLL/SSCG Output Clock Division Setting Register : CCPSDIVR (Cctl Pll/Sscg clock DIVision Register)

The bit configuration of the PLL/SSCG output clock division setting register is shown.

It is a register that sets the ratio of dividing frequency of the PLL/SSCG clock.

This register can be written only at PLL/SSCG clock oscillation stop (CSELR:PCEN = 0).

■ CCPSDIVR: Address 0523_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	PODS[2:0]			Reserved	SODS[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R/W	R/W	R/W	R0,WX	R/W	R/W	R/W

[bit7] (Reserved)

[bit6 to bit4] PODS[2:0] (Pll Oscillator Divider selection) : Selection of PLL macro oscillation clock dividing frequency ratio

The ratio of dividing frequency of the PLL clock is set.

PODS[2:0]	Dividing frequency ratio setting
000	PLL clock = PLL macro oscillation clock /2
001	PLL clock = PLL macro oscillation clock /4
010	PLL clock = PLL macro oscillation clock /6
011	PLL clock = PLL macro oscillation clock /8
100	PLL clock = PLL macro oscillation clock /10
101	PLL clock = PLL macro oscillation clock /12
110	PLL clock = PLL macro oscillation clock /14
111	PLL clock = PLL macro oscillation clock /16

Note:

It is only dividing of the even number in the setting by this bit. The odd number dividing frequency cannot be set. Duty of the output clock becomes 50%.

Please set for the PLL clock to become 128MHz or less. (The operation guarantee that exceeds 128MHz is not done.)

[bit3] (Reserved)

[bit2 to bit0] SODS[2:0] (Sscg Oscillator Divider selection) : SSCG Selection of SSCG macro oscillation clock dividing frequency Ratio

The ratio of dividing frequency of the SSCG clock is set.

SODS[2:0]	Dividing frequency ratio setting
000	SSCG clock = SSCG macro oscillation clock /2
001	SSCG clock = SSCG macro oscillation clock /4
010	SSCG clock = SSCG macro oscillation clock /6
011	SSCG clock = SSCG macro oscillation clock /8
100	SSCG clock = SSCG macro oscillation clock /10
101	SSCG clock = SSCG macro oscillation clock /12
110	SSCG clock = SSCG macro oscillation clock /14
111	SSCG clock = SSCG macro oscillation clock /16

Note:

It is only dividing of the even number in the setting by this bit. The odd number dividing frequency cannot be set. Duty of the output clock becomes 50%.

Please set for the SSCG clock to become 128MHz or less. (The operation guarantee that exceeds 128MHz is not done.)

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.13. PLL Feedback Division Setting Register : CCPLLFBR (CCTl PLL FB clock division Register)

The bit configuration of the PLL feedback division setting register is shown.

It is a register that sets the multiple ratio of PLL.

This register can be written only at PLL/SSCG clock oscillation stop (CSELR:PCEN = 0).

■ **CCPLLFBR: Address 0525_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	IDIV[6:0]						
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7] (Reserved)

[bit6 to bit0] IDIV[6:0] (pll feedback Input DIVider ratio settings) : Setting of PLL macro FB input dividing frequency ratio

PLL multiple ratio is set.

IDIV[6:0]	Dividing frequency ratio setting
0000000 to 0001011	Setting is prohibited
0001100	13
0001101	14
0001110	15
...
1100010	99
1100011	100
1100100 to 1111111	Setting is prohibited

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.14. SSCG Feedback Division Setting Register 0 : CCSSFBR0 (Cctl SScg FB clock division Register 0)

The bit configuration of the SSCG feedback division setting register 0 is shown.

It is a register that sets multiple ratio of SSCG.

The multiple ratio of SSCG becomes $P \times N$ together with the setting of CCSSFBR1.

This register can be written only at PLL/SSCG clock oscillation stop (CSELR:PCEN = 0).

■ CCSSFBR0: Address 0526_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		NDIV[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] (Reserved)

[bit5 to bit0] NDIV[5:0] (sscg feedback input N-DIVider ratio settings) : SSCG macro FB input N dividing frequency ratio setting

It sets the SSCG multiple ratio N.

NDIV[5:0]	Dividing frequency ratio setting
000000	Setting is prohibited
000001	2
000010	3
000011	4
...
111101	62
111110	63
111111	Setting is prohibited

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.15. SSCG Feedback Division Setting Register 1 : CCSSFBR1 (Cctl SScg FB clock division Register 1)

The bit configuration of the SSCG feedback division setting register 1 is shown.

It is a register that sets the multiple ratio P of SSCG. The multiplication ratio of SSCG becomes $P \times N$ along with the setting of CCSSFBR0.

This register can be written only at PLL/SSCG clock oscillation stop (CSELR.PCEN = 0).

■ CCSSFBR1: Address 0527_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			PDIV[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W

[bit7 to bit5] (Reserved)

[bit4 to bit0] PDIV[4:0] (sscg feedback input P-DIVider ratio settings) : SSCG macro FB input P divider frequency ratio setting

It sets the SSCG multiple ratio P.

PDIV[4:0]	Dividing frequency ratio setting
00000	1
00001	2
00010	3
00011	4
...
11101	30
11110	31
11111	Setting is prohibited

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.16. SSCG Configuration Setting Register 0 : CCSSCCR0 (Cctl SSCg Config. Register 0)

The bit configuration of the SSCG configuration setting register 0 is shown.

SSCG is variously set.

This register can be written only at PLL/SSCG clock oscillation stop (CSELR:PCEN = 0)

■ CCSSCCR0: Address 0529_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				SFREQ[1:0]	SMODE	SSEN	
Initial value	0	0	0	1	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W

[bit7 to bit4] (Reserved)

[bit3, bit2] SFREQ[1:0] (Spread spectrum modulation FREQUENCY settings) : Spread spectrum modulation frequency settings

The spread spectrum modulation frequency of SSCG is set.

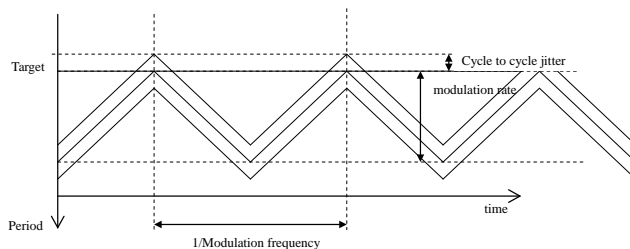
SFREQ[1:0]	Modulation frequency
00	1/1024
01	1/2048
1x	1/4096

[bit1] SMODE (Spread spectrum modulation MODE settings) : Spread spectrum modulation mode settings

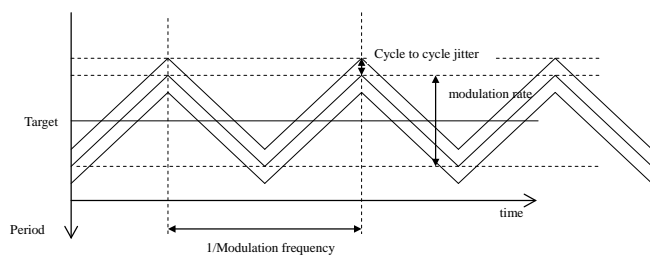
Sets spread spectrum modulation mode of SSCG.

SMODE	Modulation mode
0	Down Spread
1	Center Spread

● Down Spread



● **Center Spread**



[bit0] SSEN (Spread Spectrum ENable) : Spread spectrum enable

This bit enables spread spectrum of SSCG.

SSEN	Spread spectrum enable
0	Spread spectrum disabled
1	Spread spectrum enabled

Note:

Diffusivity of the spread spectrum becomes 0% regardless of a setting of the CCSSCCR1:RATESEL when SSEN is set disabled.

4.17. SSCG Configuration Setting Register 1 : CCSSCCR1 (Cctl SSCg Config. Register 1)

The bit configuration of the SSCG configuration setting register 1 is shown.

Sets various settings of SSCG.

This register can be written only when PLL/SSCG clock oscillation stops. (CSELR:PCEN = 0).

■ CCSSCCR1: Address 052A_H (Access : Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	RATESEL[2:0]			Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R0,WX	R0,WX	R0,WX	R/W0	R/W0
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W0	R/W0	R/W0	R/W0	R/W0	R/W0	R/W0	R/W0

[bit15 to bit13] RATESEL[2:0] (spread spectrum modulation RATE SElection) : spread spectrum modulation rate selection

Sets the spread spectrum modulation rate of SSCG.

RATESEL[2:0]	Modulation rate
00x	0.5%
010	1%
011	2%
100	3%
101	4%
110	5%
111	Setting is prohibited

[bit12 to bit10] (Reserved)

Writing has no effect.

[bit9 to bit0] (Reserved)

Always write "0" to these bits.

4.18. Clock Gear Configuration Setting Register 0 : CCCGRCR0 (Cctl Clock Gear Config. Register 0)

The bit configuration of the clock gear configuration setting register 0 is shown.

Sets various settings of clock gear.

■ CCCGRCR0: Address 052D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GRSTS[1:0]		Reserved				GRSTR	GREN
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R(RM0),W1	R/W

[bit7, bit6] GRSTS[1:0] (clock Gear STatus flags) : Clock gear status flags
Displays status of Clock gear.

GRSTS[1:0]	Status
00	Stop in the state of clock gear low-speed oscillation or No use of clock gear (CCCGRCR0:GREN=0) or In the status of PLL/SSCG reset (CSELR:PCEN=0)
01	In operation of GEAR UP
10	Stop in the status of clock gear high-speed oscillation
11	In operation of GEAR DOWN

[bit5 to bit2] (Reserved)

[bit1] GRSTR (clock Gear STaRt) : clock gear start
Writing "1" to this bit starts the operation of clock gear

The operation of clock gear depends on the value of the GRSTS bits. (Gear up or gear down)

When GRSTS=00

GRSTR	Operation
"0" write	Not affect the operation
"1" write	Start the operation of gear up

When GRSTS=01/11

GRSTR	Operation
"0" write	Not affect the operation
"1" write	Not affect the operation

When GRSTS=10

GRSTR	Operation
"0" write	Not affect the operation
"1" write	Start the operation of gear down

Note:

This bit can be written only when CSELR:CKS[1:0]=10 (PLL/SSCG clock (PLLSSCLK) selection) and CCCGRCR0:GREN=1 (clock gear enabled).

This bit is automatically cleared to "0" after the operation of clock gear up (down) complete. Also, this bit is cleared to "0" when CSELR:PCEN=0 (PLL/SSCG clock oscillation stopped).

In the instruction of read modify write "0" is always read from this bit. When writing is executed while this bit is "1", writing for the second and subsequent times is ignored.

[bit0] GREN (clock Gear ENable) : Clock gear enable

This bit enables the operation of clock gear.

GREN	Operation
0	No use of clock gear
1	Use of clock gear

Note:

This bit can be written only when PLL/SSCG clock oscillation is stopped (CSELR:PCEN = 0).

4.19. Clock Gear Configuration Setting Register 1 : CCCGRCR1 (CCTl Clock Gear Config. Register 1)

The bit configuration of the clock gear configuration setting register 1 is shown.

Sets various settings of clock gear.

This register can be written only when PLL/SSCG clock oscillation is stopped (CSELR:PCEN = 0).

■ CCCGRCR1 : Address 052E_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GRSTP[1:0]		GRSTN[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] GRSTP[1:0] (clock Gear STeP selection) : Clock gear step selection

These bits select the step number at the time of clock gear up/down (the number of increment /decrement).

GRSTP[1:0]	Step number
00	1
01	2
10	3
11	4

[bit5 to bit0] GRSTN[5:0] (clock Gear SStart step Number selection) : Clock gear start step number selection

These bits select the step at the start of clock gear operation and select the step between 0 and 63.

GRSTN[5:0]	Step number
000000	0
000001	1
000010	2
...
111101	61
111110	62
111111	63

Note:

The gear does not operate at GRSTN =111111(number 63 of steps) setting.

4.20. Clock Gear Configuration Setting Register 2 : CCCGR2 (Cctl Clock Gear Config. Register 2)

The bit configuration of the clock gear configuration setting register 2 is shown.

Sets various settings of clock gear.

This register can be written only when PLL/SSCG clock oscillation is stopped. (CSELR:PCEN = 0).

■ CCCGR2 : Address 052F_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GRLP[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] GRLP[7:0] (clock Gear Loop number selection) : clock gear loop number selection

These bits select the loop number of one step. The setting enabled number of iteration is between 1 to 256. Step is incremented/decremented when the number set to this bit is completed.

GRLP[7:0]	Loop number
0000_0000	1
0000_0001	2
0000_0010	3
...
1111_1101	254
1111_1110	255
1111_1111	256

4.21. RTC/PMU Clock Selection Register : CCRTSELR (Cctl RTc pmu clock Selection Register)

The bit configuration of the RTC/PMU clock selection register is shown.

Selects RTC/PMU clock source.

■ CCRTSELR : Address 0530_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	CST	Reserved						CSC
Initial value	*	0	0	0	0	0	0	*
Attribute	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

*: These bits are initialized to "0". But these bits are not initialized by the return from the watch mode (power shut-down).

[bit7] CST (Clock source selection SStatus monitor): Clock source selection status monitor

A time lag by clock switch occurs until the CSC bit is written and then the clock switch completes. Whether the switch completes or not is monitored by this bit.

CST	Monitor
0	The completion of clock switch
1	During clock switch

Note:

When single clock products (SUBDIS=1), this bit is always fixed with "0". Normally, switch completes by main clock × about 3 cycles + sub clock × about 3 cycles.

[bit6 to bit1] (Reserved)

[bit0] CSC (Clock SourCe selection) : Clock source selection

Selects clock source of RTC/PMU clock.

CSC	Clock source
0	Main oscillation clock
1	Sub oscillation clock

Note:

The CSC bit can be rewritten only when SCRDY=1 and MCRDY=1. When single clock products , this bit is always fixed with "0" in spite of the written value.

Note:

It takes main clock \times about 3 cycles + sub clock \times about 3 cycles until the switch operation of RTC and PMU clock completes after rewriting the CSC bit. When main clock and sub clock oscillation are stopped during the switching operation, the switching operation does not complete correctly. The oscillation must always be stopped in the status that the CST bit is "0" (the status of the completion of switching).

The CSC bit is not initialized by the return from the standby watch mode (power shut-down). Moreover, any reset factors other than those, caused by power on reset/internal low voltage reset/RSTX-NMIX simultaneous assertion, can not be accepted because an internal reset signal is generated while returning from the standby watch mode (power shut-down). At this time the CSC bit is not initialized. Initialize this bit in case of need, when the reset signal comes from RSTX terminal input or external low-voltage detection is flagged after the return from power shut-down.

4.22. PMU Clock Division Setting Register 0 : CCPMUCR0 (CCTl PMU Clock division Register 0)

The bit configuration of the PMU clock division setting register 0 is shown.

This register does the setting of dividing frequency of the PMU clock. .

■ CCPMUCR0 : Address 0532_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FST	Reserved					FDIV[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit7] FST (F-divider STatus monitor): F-divider status monitor

A time lag by clock switch occurs until FDIV[1:0] register is written and the written value is reflected. Whether the setting value is reflected can be monitored by this bit.

Normally, it takes RTC clock × about 4 cycles + PCLK1 × about 4 cycles to reflect the setting value of the register.

FST	Monitor
0	Completion of reflecting the written value
1	During reflecting the written value

[bit6 to bit2] (Reserved)

[bit1 to bit0] FDIV[1:0] (F-DIVide ratio setting): F-divide ratio setting

Sets the division rate of F-divider. The clock less than 32kHz must be provided with PMU. When CCRTSELR:CSC=0 (selection of main oscillation clock), this bit is set to be less than 32kHz by F divider.

FDIV[1:0]	Division rate	Target main oscillation frequency
00	Divided by 128 (Initial value)	4MHz
01	Divided by 256	8MHz
10	Divided by 384	12MHz
11	Divided by 512	16MHz

Note:

Writing to this bit is ignored while the CCPMUCR0:FST bit is "1".

When CCRTSELR:CSC=1 (selection of sub oscillation clock), F-division rate become undivided in spite of the value of this bit.

4.23. PMU Clock Division Setting Register 1 : CCPMUCR1 (CCTl PMU Clock division Register 1)

The bit configuration of the PMU clock division setting register 1 is shown.

This register does the setting of dividing frequency of the PMU clock.

■ CCPMUCR1 : Address 0533_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GST	Reserved		GDIV[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W

[bit7] GST (G-divider S_Tatus monitor): G-divider status monitor

A time lag by clock switch occurs until GDIV[4:0] register is written and the written value is reflected. Whether the setting value is reflected can be monitored by this bit.

Normally, it takes RTC clock × about 4 cycles + PCLK1 × about 4 cycles to reflect the setting value of the register.

GST	Monitor
0	Completion of reflecting the written value
1	During reflecting the written value

Note:

Writing to CCPMUCR1:GDIV[4:0] is ignored while this bit is "1".

[bit6, bit5] (Reserved)

[bit4 to bit0] GDIV[4:0] (G-DIVide ratio setting) : G-divide ratio setting

These bits set the division rate of G-divider. The period of the PMU clock must be more than four times the period of the bus clock (APB) which is provided with PMU. The division rate of the PMU clock is set by this divider to meet the above relation.

GDIV[4:0]	Division rate
00000	Do not divide (Initial value)
00001	2
00010	3
...
11101	30
11110	31
11111	32

Note:

Writing to this bit is ignored while CCPMUCR1:GST bit is "1".

4.24. Sync/Async Control Register : SACR (Sync/Async Control Register)

The bit configuration of the sync/async control register is shown.

Selects the peripheral clock (PCLK2).

■ SACR : Address 1000_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							M
Initial value	1	1	1	1	1	1	1	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W

[bit7 to bit1] (Reserved)

[bit0] M : Synchronous/asynchronous setting register of peripheral clock(PCLK2)

The peripheral clock(PCLK2) is switched when CPU selects the SSCG clock.

M	Synchronous/asynchronous setting
0	Synchronous (PLL/SSCG clock for CPU/peripheral)
1	Asynchronous (PLL/SSCG clock for CPU, PLL clock for peripheral)

4.25. Peripheral Interface Clock Divider : PICD (Peripheral Interface Clock Divider)

The bit configuration of peripheral interface clock divider is shown.

The setting of dividing frequency of the peripheral clock made from the PLL clock (PLLCLK) is done.

■ PICD : Address 1001_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				PDIV[3:0]			
Initial value	1	1	1	1	0	0	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W

[bit7 to bit4] (Reserved)

[bit3 to bit0] PDIV[3:0] : Sets peripheral clock division rate

The ratio of dividing frequency of the peripheral clock (PCLK2) is set from the PLL clock (PLLCLK) [non spread spectrum clock] at SACR.M=1.

PDIV[3:0]	PLL clock (PLLCLK)[non spread spectrum clock] → PCLK2 division rate
0000	Do not divide
0001	2 division
0010	3 division
0011	4 division (initial value)
0100	5 division
0101	6 division
0110	7 division
0111	8 division
1000	9 division
1001	10 division
1010	11 division
1011	12 division
1100	13 division
1101	14 division
1110	15 division
1111	16 division

Note:

Set this register so that the peripheral clock (PCLK2) definitely becomes 40MHz or less.

4.26. GDC PLL Control Register : GPLLCR

The bit configuration of the GDC PLL control register is shown.

Displays the status of PLL/SSCG oscillation in GDC and sets interrupt.

■ GPLLCR : Address 0F51_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	G_PCRDY	Reserved						G_PCEN
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	RX,WX	RX,WX	RX,WX	RX,WX	R/W0	R/W0	R/W

[bit7] G_PCRDY : PLL clock ready flag

It is a flag to confirm whether PLL/SSCG in the GDC can be used.

G_PCRDY	PLL/SSCG clock ready in the GDC
0	Oscillation is stopped or oscillation stabilization wait
1	Oscillation stabilization and enabled

[bit6 to bit3] Reserved

The reading value is undefined. Writing has no effect.

[bit2, bit1] Reserved

Always write "0" to these bits.

[bit0] G_PCEN : PLL clock enabled

This bit controls PLL/SSCG clock oscillation circuit for GDC as follows.

G_PCEN	PLL/SSCG clock enabled in GDC
0	Oscillation stopped
1	Oscillation enabled

4.27. GDC PLL Timer Setting Register : PTIMCR:

The bit configuration of the GDC PLL timer setting register is shown.

Sets the oscillation stabilization wait time of PLL SSCG in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ PTIMCR : Address 0F52_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				POSW[3:0]			
Initial value	0	0	0	0	1	1	1	1
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W	R/W

[bit7 to bit4] Reserved

[bit3 to bit0] POSW[3:0] : PLL oscillation stabilization wait time selection

These bits select the oscillation stabilization wait time of PLL/SSCG for GDC as follows:

POSW[3:0]	Oscillation stabilization wait time of PLL/SSCG for GDC	At 4MHz
1000	$2^9 \times$ main clock period	128.0[μ s]
1001	$2^{10} \times$ main clock period	256.0[μ s]
1010	$2^{11} \times$ main clock period	512.0[μ s]
1011	$2^{12} \times$ main clock period	1024.0[μ s]
1100	$2^{13} \times$ main clock period	2048.0[μ s]
1101	$2^{14} \times$ main clock period	4096.0[μ s]
1110	$2^{15} \times$ main clock period	8192.0[μ s]
1111	$2^{16} \times$ main clock period (Initial value)	16384.0[μ s]

"1" is always read from POSW3.

4.28. GDC PLL External Division Setting Register : PEDIVCR

The bit configuration of the GDC PLL external division setting register is shown.

Sets the division rate of PLL SSCG output clock in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ PEDIVCR : Address 0F53_H (Access : Byte, Half-word,Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	PODS[2:0]			Reserved	SODS[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R/W	R/W	R/W	R0,WX	R/W	R/W	R/W

[bit7] (Reserved)

[bit6 to bit4] PODS[2:0] : PLL macro oscillation clock division rate selection

Selects the division rate when the PLL macro oscillation clock in GDC is converted to the PLL clock in GDC (which is input into clock gear) from the followings:

PODS[2:0]	Division rate setting
000	GDC PLL clock = GDC PLL macro oscillation clock /2
001	GDC PLL clock = GDC PLL macro oscillation clock /4
010	GDC PLL clock = GDC PLL macro oscillation clock /6
011	GDC PLL clock = GDC PLL macro oscillation clock /8
100	GDC PLL clock = GDC PLL macro oscillation clock /10
101	GDC PLL clock = GDC PLL macro oscillation clock /12
110	GDC PLL clock = GDC PLL macro oscillation clock /14
111	GDC PLL clock = GDC PLL macro oscillation clock /16

Note:

Setting by this bit is only division by an even number. Division by an odd number can not be set.
The duty of the output clock is 50%.

[bit3] (Reserved)

[bit2 to bit0] SODS[2:0] : PLL_SSCG macro oscillation clock division rate selection

Selects the division rate when the SSCG macro oscillation clock in GDC is converted to the SSCG clock in GDC (which is input into clock gear) from the followings:

SODS[2:0]	Division rate setting
000	GDC SSCG clock = GDC SSCG macro oscillation clock /2
001	GDC SSCG clock = GDC SSCG macro oscillation clock /4
010	GDC SSCG clock = GDC SSCG macro oscillation clock /6
011	GDC SSCG clock = GDC SSCG macro oscillation clock /8
100	GDC SSCG clock = GDC SSCG macro oscillation clock /10
101	GDC SSCG clock = GDC SSCG macro oscillation clock /12
110	GDC SSCG clock = GDC SSCG macro oscillation clock /14
111	GDC SSCG clock = GDC SSCG macro oscillation clock /16

Note:

Setting by this bit is only division by an even number.

Division by an odd number can not be set. The duty of the output clock is 50%.

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.29. GDC PLL Multiplier Setting Register : PDIVCR

The bit configuration of the GDC PLL multiplier setting register is shown.

Sets the multiplication rate of PLL in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ PDIVCR : Address 0F55_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	IDIV[6:0]						
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7] (Reserved)

[bit6 to bit0] IDIV[6:0] : PLL Clock multiplication rate selection

Selects the multiplication rate of the PLL macro oscillation clock in GDC from the following:

IDIV[6:0]	Multiplication rate
0000000-0001011	Setting is prohibited
0001100	13
...
1100010	99
1100011	100
1100100-1111111	Setting is prohibited

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.30. GDC PLL_SSCG Multiplier Setting Register 0 : SDIVCR0

The bit configuration of the GDC PLL_SSCG multiplier setting register 0 is shown.

This is a register to set the multiplication rate N of SSCG in GDC. The multiplication ratio of SSCG for GDC is $P \times N$ with the setting of SDIVCR1.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ SDIVCR0 : Address 0F56_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		NDIV[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] (Reserved)

[bit5 to bit0] NDIV[5:0] : PLL_SSCG clock multiplication rate (N-Divider) selection

Selects the multiplication rate of the SSCG macro oscillation clock (the part of N-Divider) in GDC from the followings:

NDIV[5:0]	Multiplication rate
000000	Setting is prohibited
000001	2
000010	3
000011	4
...
111101	62
111110	63
111111	Setting is prohibited

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.31. GDC PLL_SSCG Multiplier Setting Register 1 : SDIVCR1

The bit configuration of the GDC PLL_SSCG multiplier setting register 1 is shown.

This is a register to set the multiplication rate P of SSCG in GDC. The multiplication ratio of SSCG for GDC is P x N with the setting of SDIVCR0.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ **SDIVCR1 : Address 0F57_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			PDIV[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W

[bit7 to bit5] (Reserved)

[bit4 to bit0] PDIV[4:0] : PLL_SSCG clock multiplication rate (P-Divider) selection

Selects the multiplication rate of the SSCG macro oscillation clock (the part of P-Divider) in GDC from the followings:

PDIV[4:0]	Multiplication rate
00000	1
00001	2
00010	3
00011	4
...
11101	30
11110	31
11111	Setting prohibited

A set value is limited. See "5.1.4 Limitations when PLL/SSCG Clock is used" when you set it.

4.32. GDC PLL_SSCG Spread Spectrum Setting Register 0 : SSSCR0

The bit configuration of the GDC PLL_SSCG spread spectrum setting register 0 is shown.

Sets various settings of SSCG in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ SSSCR0 : Address 0F59_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				SFREQ[1:0]		SMODE	SEN
Initial value	0	0	0	1	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R1,W1	R/W	R/W	R/W	R/W

[bit7 to bit4] (Reserved)

Always write "1" to bit 4.

[bit3, bit2] SFREQ[1:0] : Spread spectrum modulation frequency selection

These bits select a spread spectrum modulation frequency of SSCG in GDC from the followings:

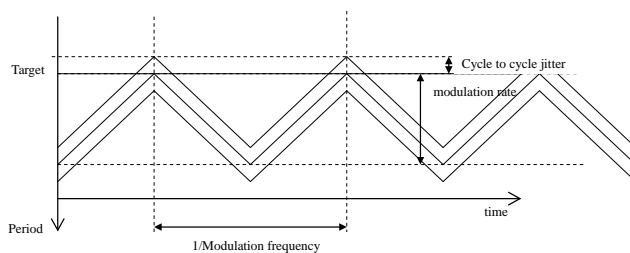
SFREQ[1:0]	Modulation frequency
00	1/1024
01	1/2048
1x	1/4096

[bit1] SMODE : Spread spectrum modulation mode selection

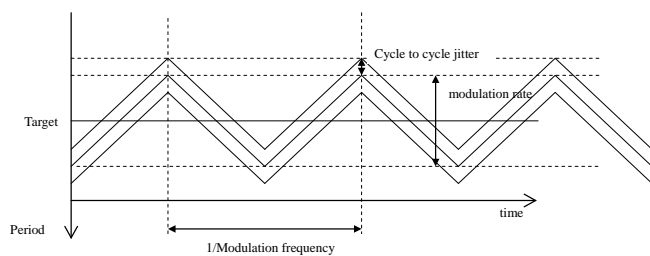
These bits select spread spectrum modulation mode of SSCG in GDC from the followings:

SMODE	Modulation mode
0	Down Spread
1	Center Spread

● Down Spread



● **Center Spread**



[bit0] SEN : Spread spectrum enabled

This bit controls spread spectrum enabled /disabled of SSCG in GDC.

SEN	Spread spectrum enabled
0	Spread spectrum disabled
1	Spread spectrum enabled

Note:

Diffusivity of the spread spectrum becomes 0% regardless of a setting of the SSSCR1:RATESEL when SEN is set disabled.

4.33. GDC PLL_SSCG Spread Spectrum Setting Register 1 : SSSCR1

The bit configuration of the GDC PLL_SSCG spread spectrum setting register 1 is shown.

Sets various settings of SSCG in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ SSSCR1 : Address 0F5A_H (Access : Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	RATESEL[2:0]			Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R0,WX	R0,WX	R0,WX	R/W0	R/W0
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W0	R/W0	R/W0	R/W0	R/W0	R/W0	R/W0	R/W0

[bit15 to bit13] RATESEL[2:0] : Spread spectrum modulation rate selection

Selects the spread spectrum modulation rate of SSCG in GDC from the followings.

RATESEL[2:0]	Modulation rate
00x	0.5%
010	1%
011	2%
100	3%
101	4%
110	5%
111	Setting is prohibited

[bit12 to bit10] (Reserved)

Writing has no effect.

[bit9 to bit0] (Reserved)

Always write "0" to these bits.

4.34. GDC PLL Clock Gear Setting Register 0 : PGRCR0

The bit configuration of the GDC PLL clock gear setting register 0 is shown.

Sets various settings of PLL clock gear in GDC.

■ **PGRCR0: Address 0F5D_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PGRSTS[1:0]		Reserved				PGRSTR	PGREN
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R,W	R/W

[bit7, bit6] PGRSTS[1:0] : PLL clock gear status flag

These bits indicate the status of a clock gear for controlling PLL clock in GDC.

PGRSTS[1:0]	Status
00	Stop in the status of low-speed oscillation or no use of clock gear
01	In the operation of GEAR UP
10	Stop in the status of high-speed oscillation
11	In the operation of GEAR DOWN

[bit5 to bit2] (Reserved)

[bit1] PGRSTR : PLL clock gear start

The clock gear starts when PGRSTR=1(this bit) and PGREN=1.

After the operation of gear completes, this bit is cleared to "0".

When PGRSTS=00

PGRSTR	Operation
"0" write	Not affect the operation
"1" write	Start the operation of gear up

When PGRSTS=01/11

PGRSTR	Operation
"0" write	Not affect the operation
"1" write	Not affect the operation

When PGRSTS=10

PGRSTR	Operation
"0" write	Not affect the operation
"1" write	Start the operation of gear down

Note:

Write "1" to this bit when GPLLCR:G_PCEN=1
The operation of this bit depends on the setting value of the PGRSTS bit.
The clock gear does not operate while PGREN=0 even if "1" is written to this bit.

[bit0] PGREN PLL clock gear enabled

Enables the operation of the clock gear.

PGREN	Operation
0	No use of clock gear
1	Use of clock gear

Note:

This bit can be set when GPLLCR:G_PCEN=0.
Only use of the clock gear up or the clock gear down is disabled.

4.35. GDC PLL Clock Gear Setting Register 1 : PGRCR1

The bit configuration of the GDC PLL clock gear setting register 1 is shown.

Sets the various settings of the PLL clock gear in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ **PGRCR1 : Address 0F5E_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PGRSTP[1:0]		PGRSTN[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] PGRSTP[1:0]: PLL clock gear step selection

These bits select the number of steps (the number of increments/decrements) at the time of the clock gear up/down.

PGRSTP[1:0]	The number of steps
00	1
01	2
10	3
11	4

[bit5 to bit0] PGRSTN[5:0] : PLL clock gear start step selection

These bits select the step at the start of the clock gear operation. The step between 0 to 63 can be selected.

PGRSTN[5:0]	The number of steps
000000	0
000001	1
000010	2
...
111101	61
111110	62
111111	63

Note:

The gear does not operate at PGRSTN =111111(number 63 of steps) setting.

4.36. GDC PLL Clock Gear Setting Register 2 : PGRCR2

The bit configuration of the GDC PLL clock gear setting register 2 is shown.

Sets the various settings of the PLL clock gear in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ PGRCR2 : Address 0F5F_H (Access : Byte, Half-word, Word)

	7	6	5	4	3	2	1	0
	PGRLP[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] PGRLP[7:0]: PLL clock gear repeat count selection

Selects the repeat count of 1 step. The repeat count between 1 to 256 can be set.

The step is incremented/decremented when the repeat count set by this bit completes.

PGRLP[7:0]	The number of loop
0000_0000	1
0000_0001	2
0000_0010	3
...
1111_1101	254
1111_1110	255
1111_1111	256

4.37. GDC PLL_SSCG Clock Gear Setting Register 0 : SGRCR0

The bit configuration of the GDC PLL_SSCG clock gear setting register 0 is shown.

Sets the various settings of the SSCG clock gear in GDC.

■ **SGRCR0 : Address 0F61_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SGRSTS[1:0]		Reserved				SGRSTR	SGREN
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R,W	R/W

[bit7, bit6] SGRSTS[1:0] : PLL_SSCG clock gear status flag

These bits indicate the status of the clock gear which controls the SSCG clock in GDC.

SGRSTS[1:0]	Status
00	Stop in the status of low-speed oscillation or no use of clock gear
01	In the operation of GEAR UP
10	Stop in the status of high-speed oscillation
11	In the operation of GEAR DOWN

[bit5 to bit2] (Reserved)

[bit1] GRSTR : PLL_SSCG clock gear start

The operation of the clock gear starts when SGRSTR=1 (this bit) and SGREN=1.

This bit is cleared to "0" when the operation of gear completes.

When SGRSTS=00

SGRSTR	Operation
"0" write	Not affect the operation
"1" write	Start the operation of gear up

When SGRSTS=01/11

SGRSTR	Operation
"0" write	Not affect the operation
"1" write	Not affect the operation

When SGRSTS=10

SGRSTR	Operation
"0" write	Not affect the operation
"1" write	Start the operation of gear down

Note:

Write "1" to this bit when GPLLCR:G_PCEN=1.

The operation of this bit depends on the setting value of the SGRSTS bit.

The clock gear does not operate while SGREN =0 even if "1" is written to this bit.

[bit0] SGREN : PLL_SSCG clock gear enabled

This bit enables the operation of the clock gear.

SGREN	Operation
0	No use of clock gear
1	Use of clock gear

Note:

This bit can be set when GPLLCR:G_PCEN=0.

Only use of the clock gear up or the clock gear down is disabled.

4.38. GDC PLL_SSCG Clock Gear Setting Register 1: SGRCR1

The bit configuration of the GDC PLL_SSCG clock gear setting register 1 is shown.

Sets the various settings of the SSCG clock gear in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ **SGRCR1 : Address 0F62_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SGRSTP[1:0]		SGRSTN[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] SGRSTP[1:0]: PLL_SSCG clock gear step selection

Selects the number of steps (the number of increments/decrements) at the time of the clock gear up/down.

SGRSTP[1:0]	The number of steps
00	1
01	2
10	3
11	4

[bit5 to bit0] SGRSTN[5:0] : PLL_SSCG clock gear start step selection

Selects the step at the start of the clock gear operation. The step between 0 to 63 can be selected.

SGRSTN[5:0]	The number of steps
000000	0
000001	1
000010	2
...
111101	61
111110	62
111111	63

Note:

The gear does not operate at SGRSTN =111111(number 63 of steps) setting.

4.39. GDC PLL _SSCG Clock Gear Setting Register 2 : SGRCR2

The bit configuration of the GDC PLL _SSCG clock gear setting register 2 is shown.

Sets the various settings of the SSCG clock gear in GDC.

Note:

This register can be written only when GPLLCR:G_PCEN=0.

■ **SGRCR2 : Address 0F63_H (Access : Byte, Half-word, Word)**

	7	6	5	4	3	2	1	0
	SGRLP[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] SGRLP[7:0] : PLL_SSCG clock gear repeat count selection

These bits select the repeat count of one step. The repeat count between 1 to 256 can be set.

The step is incremented/decremented when the repeat count set by this bit completes.

SGRLP[7:0]	The number of loops
0000_0000	1
0000_0001	2
0000_0010	3
...
1111_1101	254
1111_1110	255
1111_1111	256

5. Operation

This section explains operations of clock.

- 5.1. Oscillation Control
- 5.2. Oscillation Stabilization Wait
- 5.3. Selecting the Source Clock (SRCCLK)
- 5.4. Timer
- 5.5. Notes when Clocks Conflict
- 5.6. The Clock Gear Circuit
- 5.7. Operations during MDI Communications
- 5.8. About PMU clock (PMUCLK)

5.1. Oscillation Control

This section explains oscillation control.

- 5.1.1. Main Clock (MCLK)
- 5.1.2. Sub Clock (SBCLK)
- 5.1.3. PLL/SSCG Clock (PLLSSCLK)
- 5.1.4. Limitations when PLL/SSCG Clock is used

5.1.1. Main Clock (MCLK)

The main clock (MCLK) is shown.

The oscillation of the main clock stops on any of the following conditions.

- SINIT reset (See "CHAPTER: RESET".)
- During the stop mode
- While the sub clock (SBCLK) are selected as the source clock (SRCCLK) and "0" is set to CSELR:MCEN

After all the above conditions of the oscillation stop are cancelled and then the oscillation stabilization wait time which is set to CSTBR:MOSW[3:0] goes by, supplying the clock starts. The oscillation stabilization wait time specified by the initial value is required because CSTBR:MOSW[3:0] is initialized at the time of return from the reset input.

Note:

For the single clock products, the main clock oscillation enable is always enabled (MCEN=1).

5.1.2. Sub Clock (SBCLK)

The sub clock (SBCLK) is shown.

The oscillation of the sub clock stops on any of the following conditions.

- After the occurrence of reset (the bus idle wait time before stop is required. See "CHAPTER: RESET".)
- During the stop mode
- While a clock other than the sub clock (SBCLK) are selected as the source clock (SRCCLK) and "0" is set to CSELR:SCEN.
- When the clock is used as a port because the clock is used for sub oscillation and port (metal option).

After all the above conditions of the oscillation stop are cancelled and then the oscillation stabilization wait time which is set to CSTBR:SOSW[2:0] goes by, supplying the clock starts. The sub clock oscillation stops until "1" is set to because CSELR:SCEN is initialized to "0" at the time of return from the reset input or the INIT status.

Notes:

- For the single clock products, the sub clock oscillation enable is always disabled (SCEN=0).
 - For the single clock product, the sub timer cannot be used.
-

5.1.3. PLL/SSCG Clock (PLLSSCLK)

The PLL/SSCG clock (PLLSSCLK) is shown.

This LSI has PLL and SSCG (PLL which generates spread spectrum clock) and can select SSCG for reducing noise. The combinations of clocks which CPU and peripheral functions can select are as follows.

Table 5-1 Clock Mode

	Clock mode		
	RUN1	RUN2	RUN3
CPU	PLL	SSCG	SSCG
CAN	PLL	PLL	PLL
Peripheral	PLL	SSCG	PLL
OCDU	PLL	PLL	PLL
GDC(NTSC)	PLL	PLL	PLL
GDC(other than above)	SSCG	SSCG	SSCG

The CPU/Peripheral (timer/communication) clock is selected by CCPSELR:PCSEL. Also, when CPU is operated by the SSCG clock, peripheral (timer/communications) can be operated by the PLL clock. In this case, the peripheral clock is selected by SACR:M and divided by PICD:PDIV [3:0].

Note:

When the CPU is operated by SSCG and the peripherals are operated by PLL, because the asynchronization transfer enters between CPU/ Peripheral, the penalty of $5 \times PCLK2$ to $8 \times PCLK2$ is added to the access cycle. In this case, the frequency of PCLK2 must be same as that of PCLK1. Select synchronization with SACR:M when you want to make both CPU/Peripheral operation with the PLL clock.

The oscillation of the PLL/SSCG clock (PLLSSCLK) stops on any of the following conditions.

- After the occurrence of reset (the bus idle wait time before stop is required. See "CHAPTER: RESET".)
- While the main clock oscillation stops (PCEN=0)
- During the time of main clock oscillation stabilization wait (PCEN=0)
- During the watch mode
- While a clock other than the PLL/SSCG clock (PLLSSCLK) are selected as the source clock (SRCCLK) and "0" is set to CSELR:PCEN.

After all the above conditions of the oscillation stop are cancelled and then PLL/SSCG clock lock wait time which is set to PLLCR:POSW[3:0] goes by, supplying the clock starts. The PLL/SSCG clock oscillation stops until "1" is set to because CSELR:PCEN is initialized to "0" at the time of return from the reset input or the INIT status.

The formula for calculating the clock frequency and the multiplication rate related to PLL/SSCG is as follows:

(PLL/SSCG setting in Microcontroller unit)

- PLL/SSCG input clock frequency = (main oscillation frequency) / (PLLCR:PDS[3:0] division ratio)
- PLL/SSCG multiplication rate = (CCPLLFBR:IDIV[6:0] FB input division ratio)
SSCG multiplication rate = (CCSSFBR0:NDIV[5:0]FB input division ratio) × (CCSSFBR1:PDIV [4:0] FB input division ratio)
- PLL macro oscillation clock frequency = (PLL/SSCG input clock frequency) × PLL multiplication rate
SSCG macro oscillation clock frequency = (PLL/SSCG input clock frequency) × SSCG multiplication rate
- PLL clock frequency = (PLL macro oscillation clock frequency) / (CCPSDIVR:PODS[2:0] division ratio)
SSCG clock frequency = (SSCG macro oscillation clock frequency) / (CCPSDIVR:SODS[2:0] division ratio)

Figure 5-1 PLL Peripheral Block Diagram in Microcontroller Unit

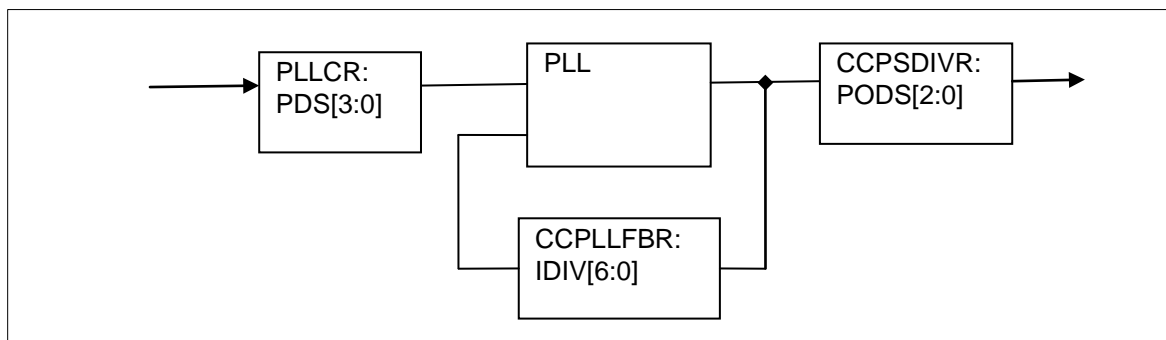
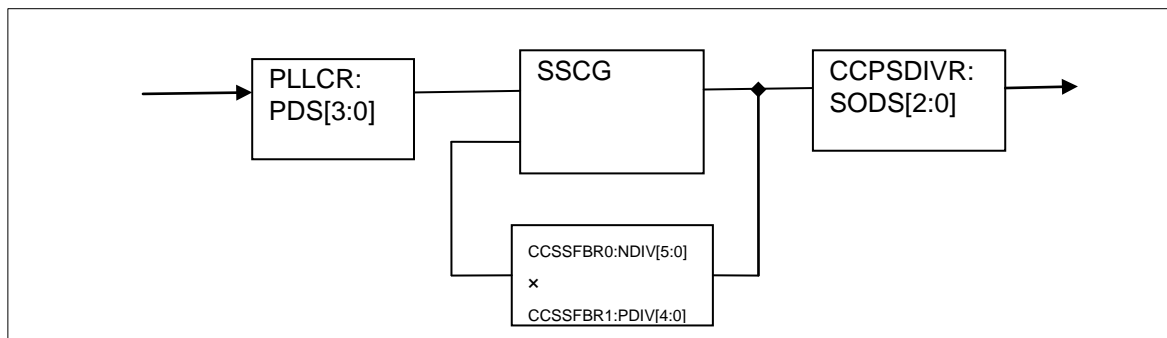


Figure 5-2 SSCG Peripheral Block Diagram in Microcontroller Unit



(PLL/SSCG setting in GDC unit)

- PLL/SSCG input clock frequency = (main oscillation frequency)
- PLL multiplication rate = (PDIVCR:IDIV[6:0] FB input division ratio)
SSCG multiplication rate = (SDIVCR0:NDIV[5:0] FB input division ratio) × (SDIVCR1:PDIV[4:0] FB input division ratio)
- PLL macro oscillation clock frequency = (PLL/SSCG input clock frequency) × PLL multiplication rate
SSCG macro oscillation clock frequency = (PLL/SSCG input clock frequency) × SSCG multiplication rate
- PLL clock frequency = (PLL macro oscillation clock frequency) / (PEDIVCR:PODS[2:0] division ratio)
SSCG clock frequency = (SSCG macro oscillation clock frequency) / (PEDIVCR:SODS[2:0] division ratio)

Figure 5-3 PLL Peripheral Block Diagram in GDC Unit

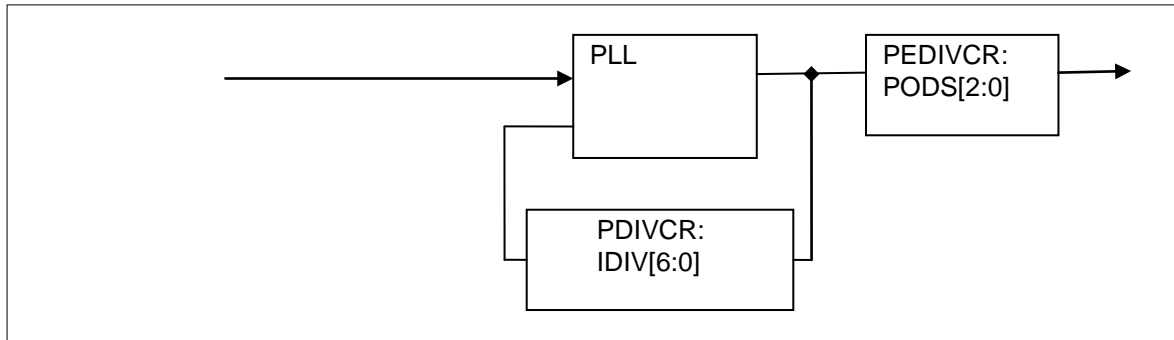
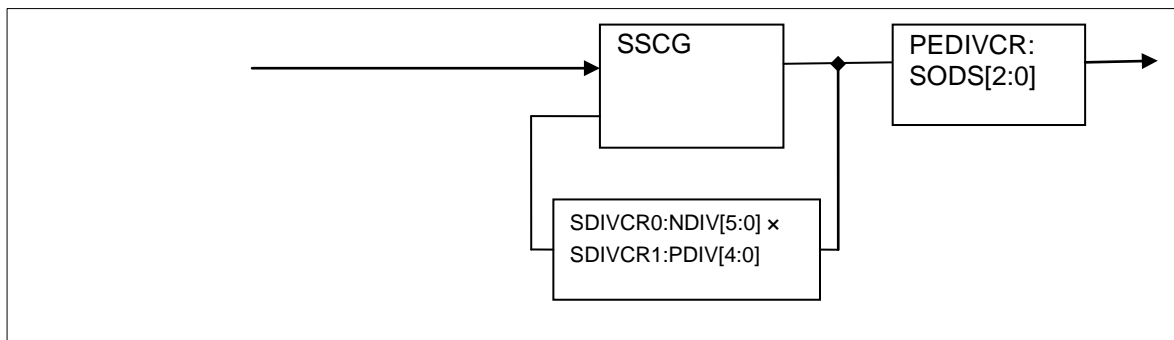


Figure 5-4 SSCG Peripheral Block Diagram in GDC Unit



PLL/SSCG input clock, PLL/SSCG multiplication rate and PLL/SSCG macro oscillation clock must be set within the operating condition ranges for built-in PLL/SSCG in this series. For the operating condition ranges of PLL/SSCG, see the data sheet.

Notes:

- In debug operation (E_DBCR:PLOCK =1), PLL can not stop because always supplying the PLL clock is required for MDI communication.
- Interrupts can not be transferred normally in switching PLL-SSCG. Therefore, when switching PLL-SSCG synchronous/asynchronous, disable the interrupt from resource.
- The PLL/SSCG macro oscillation clock frequency has the upper bound and the lower bound. Set the multiplication rate of PLL/SSCG so as not to exceed the following range.

PLL/SSCG in Microcontroller unit:

- $200\text{MHz} \leq \text{PLL macro oscillation clock frequency} \leq 333\text{MHz}$
- $200\text{MHz} \leq \text{SSCG macro oscillation clock frequency} \leq 333\text{MHz}$ (Down Spread)

PLL/SSCG in GDC unit:

- $200\text{MHz} \leq \text{PLL macro oscillation clock frequency} \leq 400\text{MHz}$
- $200\text{MHz} \leq \text{SSCG macro oscillation clock frequency} \leq 400\text{MHz}$ (Down Spread)

5.1.4. Limitations when PLL/SSCG Clock is used

The limitations of the PLL/SSCG clock are shown.

Use it according to the following limitations when you use the PLL/SSCG clock.

Microcontroller Unit Clock Control PLL Clock Frequency

Frequency (max)	FCTLR:FAW	CCPSSELR:PCSEL	Remarks
128MHz	01	0	
80MHz	00	0	

Note:

Set PLLCR or CCPSDIVR and CCPLLFBP so as not to exceed frequency (max).

Microcontroller Unit Clock Control SSCG Clock Frequency

Frequency (max)	FCTLR:FAW	CCPSSELR:PCSEL	CCSSCCR0:SSEN	CCSSCCR0:SMODE	CCSSCCR1:RATESEL	Remarks
128MHz	01	1	1	0 / 1	000 to 110	
72MHz	00	1	1	0	000 to 110	DownSpread
72MHz	00	1	1	1	000	CenterSpread (0.5%)
72MHz	00	1	1	1	010	CenterSpread (1%)
72MHz	00	1	1	1	011	CenterSpread (2%)
71MHz	00	1	1	1	100	CenterSpread (3%)
71MHz	00	1	1	1	101	CenterSpread (4%)
70MHz	00	1	1	1	110	CenterSpread (5%)
128MHz	01	1	0	0/1	000 to 110	Spread 0%
80MHz	00	1	0	0/1	000 to 110	Spread 0%

Note:

Set CCPSDIVR, CCSSFBR0 and CCSSFBR1 so as not to exceed frequency (max).

GDC Unit Clock Control PLL Clock Frequency

Frequency (max)	Remarks
108MHz	

Note:

Set PEDIVCR and PDIVCR so as not to exceed frequency (max).

GDC Unit Clock Control SSCG Clock Frequency

Frequency (max)	SSSCR0: SSEN	SSSCR0: SMODE	SSSCR1: RATESEL	Remarks
81MHz	1	0 / 1	000 to 110	
81MHz	0	0 / 1	000 to 110	Spread 0%

Note:

Set PEDIVCR, SDIVCR0 and SDIVCR1 so as not to exceed frequency (max).

Relation Modulation Rate and Division Ratio when SSCG is Used

CCSSCCR1:RATESEL[2:0] SSSCR1:RATESEL[2:0]		CCSSFBR0:NDIV[5:0] SDIVCR0:NDIV[5:0]		
Modulation rate	Set value	Range of division ratio	Set value lower limit	Set value upper limit
0.50%	00x	8 - 60	7h	3Bh
1.00%	010	8 - 60	7h	3Bh
2.00%	011	8 - 48	7h	2Fh
3.00%	100	8 - 31	7h	1Eh
4.00%	101	8 - 23	7h	16h
5.00%	110	8 - 18	7h	11h

5.2. Oscillation Stabilization Wait

Oscillation stabilization wait is shown.

This section describes oscillation stabilization wait for each clock input.

5.2.1. Conditions for Generating Stabilization Wait Time

Conditions for the generating stabilization wait time are shown.

The cancellation of the oscillation stop control for each clock enters the oscillation stabilization wait status. After the oscillation stabilization wait time specified by each clock, the oscillation stabilization wait status is cancelled and supplying clock restarts.

The main (MCLK) clock enters the oscillation stabilization wait status when the oscillation stops before cancellation of reset because the setting register is initialized by reset. The main clock does not enter the oscillation stabilization wait status when the main clock oscillates by reset of INIT and RST level because the main clock oscillation does not stop by reset of INIT and RST level.

5.2.2. Selecting Stabilization Wait Time

Selecting the stabilization wait time is shown.

The stabilization wait time for each clock can be changed by setting of CSTBR and PLLCR .

Initial values after reset for clock oscillation stabilization wait time

- Main clock : CSTBR:MOSW[3:0] bit $2^{15} \times$ main clock period
- PLL/SSCG clock : PLLCR:POSW[3:0] bit $2^{16} \times$ main clock period
- Sub clock : CSTBR:SOSW[2:0] bit $2^8 \times$ sub clock period

The main clock oscillation stabilization wait time is always specified by the initial value because CSTBR:MOSW[3:0] is initialized by reset (INIT or RST). Except that case, the main clock oscillation stabilization wait time can be changed by setting to CSTBR:MOSW[3:0].

The PLL/SSCG clock lock wait time is always specified by the initial value because PLLCR:POSW[3:0] is initialized by reset (INIT or RST). Except that case, the PLL/SSCG clock lock wait time can be changed by setting to PLLCR:POSW[3:0]. Set "1" to CSELR:PCEN after setting to PLLCR:POSW[3:0]. For details, see the explanation of POSW in "4.8 PLL Setting Register : PLLCR (PLL Configuration Register)".

The sub clock oscillation stabilization wait time is always specified by the initial value because CSTBR:SOSW[2:0] is initialized by reset (INIT or RST). Except that case, the sub oscillation stabilization wait time can be changed by setting to CSTBR:SOSW[2:0].

5.2.3. End of the Stabilization Wait Time

The end of the stabilization wait time is shown.

The operations are stopped while the clock which is selected as a source clock (SRCCLK) is the status of the oscillation stabilization wait time. The operations restart after the end of the oscillation stabilization wait time. You can verify that the clock which is not selected as the source clock has entered the oscillation stabilization wait time by checking the value of the ready bit corresponding to each clock for CMONR register when each clock is enabled.

Displays the clock oscillation stabilization wait status and the oscillation stabilization status

- Main clock : CMONR:MCRDY ="0" , CMONR:MCRDY ="1"
- PLL/SSCG clock (PLLSSCLK) : CMONR:PCRDY ="0" , CMONR:PCRDY ="1"
- Sub clock (SBCLK) : CMONR:SCRDY ="0" , CMONR:SCRDY ="1"

5.3. Selecting the Source Clock (SRCCLK)

Selecting the source clock (SRCCLK) is shown.

This section explains the selection control of the source clock (SRCCLK) which functions as the operation clock.

5.3.1. Selecting the Source Clock at the Time of Initialization

Selecting the source clock at the time of initialization is shown.

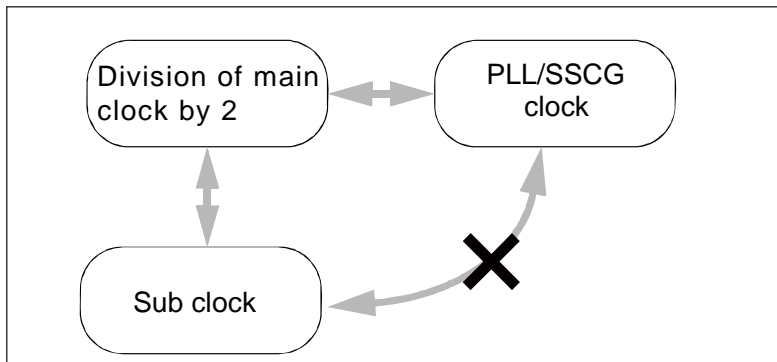
After reset (RST) the main clock (MCLK) divided by 2 is selected as the source clock (SRCCLK). After program operation the source clock can be changed by setting CSELR:CKS[1:0].

5.3.2. Procedure of switching the source clock

The procedure of switching the source clock is shown.

The source clock (SRCCLK) can not be directly switched from the PLL/SSCG clock (PLLSSCLK) to the sub clock (SBCLK) and from the sub clock to the PLL/SSCG clock. Switch the main clock divided by 2 once. Set the oscillation stop as necessary because the value of the oscillation enabled bit (CSELR:xCEN) is held, even though the source clock is switched.

Figure 5-5 Procedure of Switching the Source Clock



1. The main clock divided by 2→PLL/SSCG clock
While selecting the main clock divided by 2 as the source clock (CMONR:CKM[1:0]=00)
 - ↓
 - PLL/SSCG multiplication rate, SSCG modulation, PLL/SSCG selection, setting PLL/SSCG lock wait time (setting PLLCR/ CCPSELR/ CCPSDIVR/ CCPLLFBR/ CCSSFBR0/ CCSSFBR1/ CCSSCCR0/ CCSSCCR1) --when PLL/SSCG oscillation is not enabled--
 - ↓
 - Sets clock gear (CCCGRCR0:GREN/CCCGRCR1/CCCGRCR2)
 - ↓
 - Clears PLL/SSCG clock oscillation stabilization wait timer interrupt source (PTIF=0)
 - ↓
 - (as necessary) setting PLL/SSCG clock oscillation stabilization wait timer interrupt enabled (PTIE=1)
 - ↓
 - PLL/SSCG oscillation begins (PCEN=0→1)
 - ↓
 - PLL/SSCG lock wait loop (loop until when PCRDY=1), or interrupt wait
 - ↓
 - PLL/SSCG clock oscillation stabilization wait timer interrupt clear (PTIF=0, PTIE=0)
 - ↓
 - Switches from the source clock to PLL/SSCG clock (CSELR:CKS[1:0]=00→10)

↓

The clock gear begins (CCCGRCR0:GRSTR=1)

↓

Verifies that the clock gear high-speed oscillation is stopped (CCCGRCR0:GRSTS[1:0]=10)

↓

While selecting PLL/SSCG clock as the source clock (CMONR:CKM[1:0]=10)

2. PLL/SSCG clock→the main clock divided by 2

While selecting PLL/SSCG clock as the source clock (CMONR:CKM[1:0]=10)

↓

Clock gear begins (CCCGRCR0:GRSTR=1)

↓

Verifies that the clock gear low-speed oscillation is stopped (CCCGRCR0:GRSTS[1:0]=00)

↓

Switches the source clock to the main clock divided by 2 (CSELR:CKS[1:0]=10→00)

↓

While selecting the main clock as the source clock (CMONR:CKM[1:0]=00)

3. the main clock divide by 2→sub clock

While selecting the main clock divided by 2 as the source clock (CMONR:CKM[1:0]=01)

↓

Sets the sub clock oscillation stabilization wait time (sets CSTBR:SOSW[2:0])
–when sub oscillation is not enabled–

↓

Clears the sub timer interrupt source (STIF=0)

↓

(as necessary) sets sub timer interrupt enable (STIE=1)

↓

The sub oscillation begins (SCEN=0→1)

↓

Sub clock oscillation stabilization wait loop (loop until when SCRDY=1), or interrupt wait

↓

Clears sub timer interrupt (STIF=0)

↓

Switches the source clock to the sub clock (CSELR:CKS[1:0]=01→11)

↓

While selecting the sub clock as the source clock (CMONR:CKM[1:0]=11)

4. the sub clock→the main clock divided by 2

While selecting the sub clock as the source clock (CMONR:CKM[1:0]=11)

↓

Sets the main clock oscillation stabilization wait time (sets CSTBR:MOSW[3:0])
– when the main oscillation is not enabled–

↓

Clears the main timer interrupt source (MTIF=0)

↓

(as necessary) Sets the main timer interrupt enable (MTIE=1)

↓

The main oscillation begins (MCEN=0→1)

↓

The main clock oscillation stabilization wait loop (loop until when MCRDY=1), or interrupt wait

↓

Clears the main timer interrupt (MTIF=0)

↓

Switches the source clock to the main clock divided by 2 (CSELR:CKS[1:0]=11→01)

↓

While selecting the main clock as the source clock (CMONR:CKM[1:0]=01)

Figure 5-6 Example of PLL/SSCG Mode Setting Main → PLL/SSCG

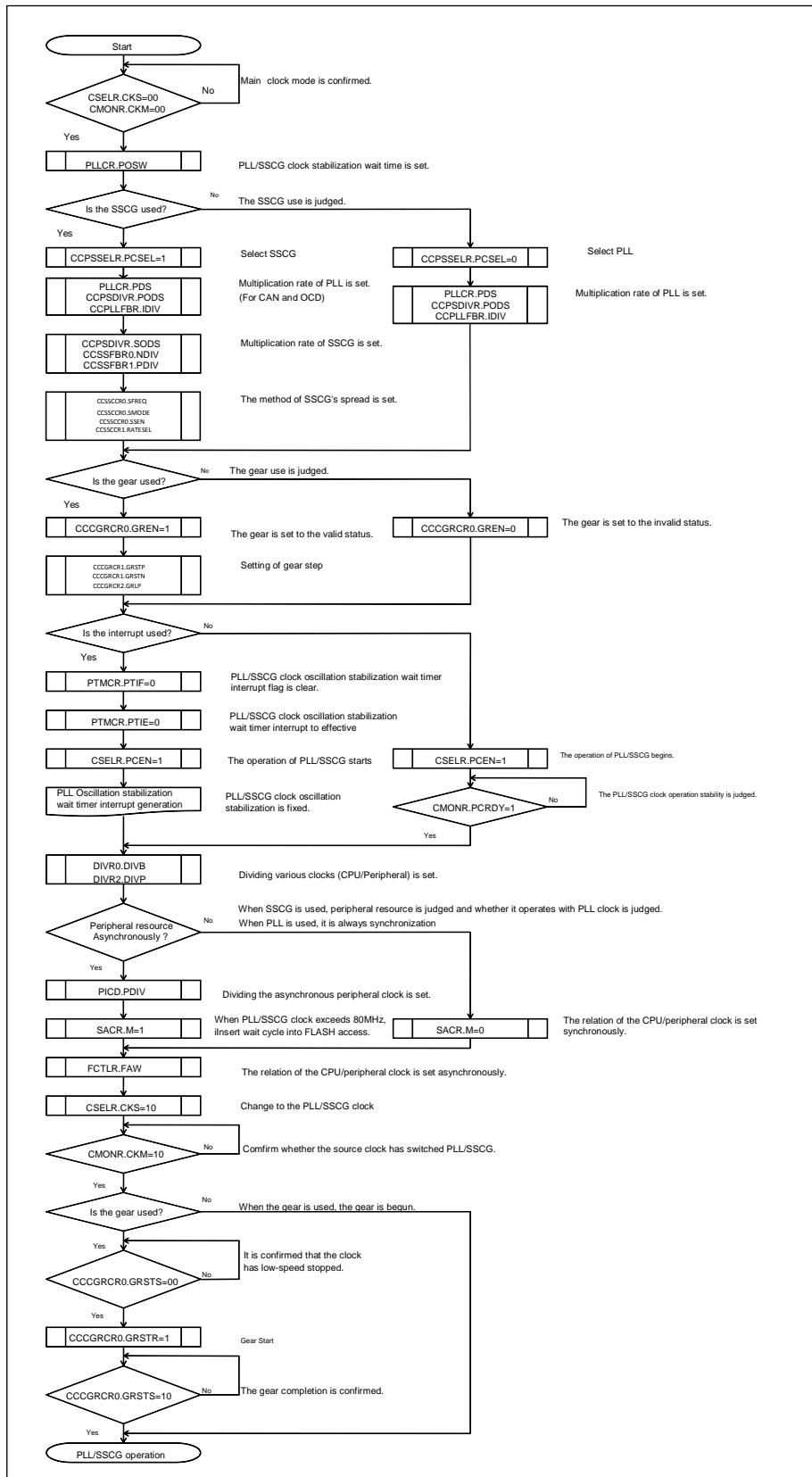
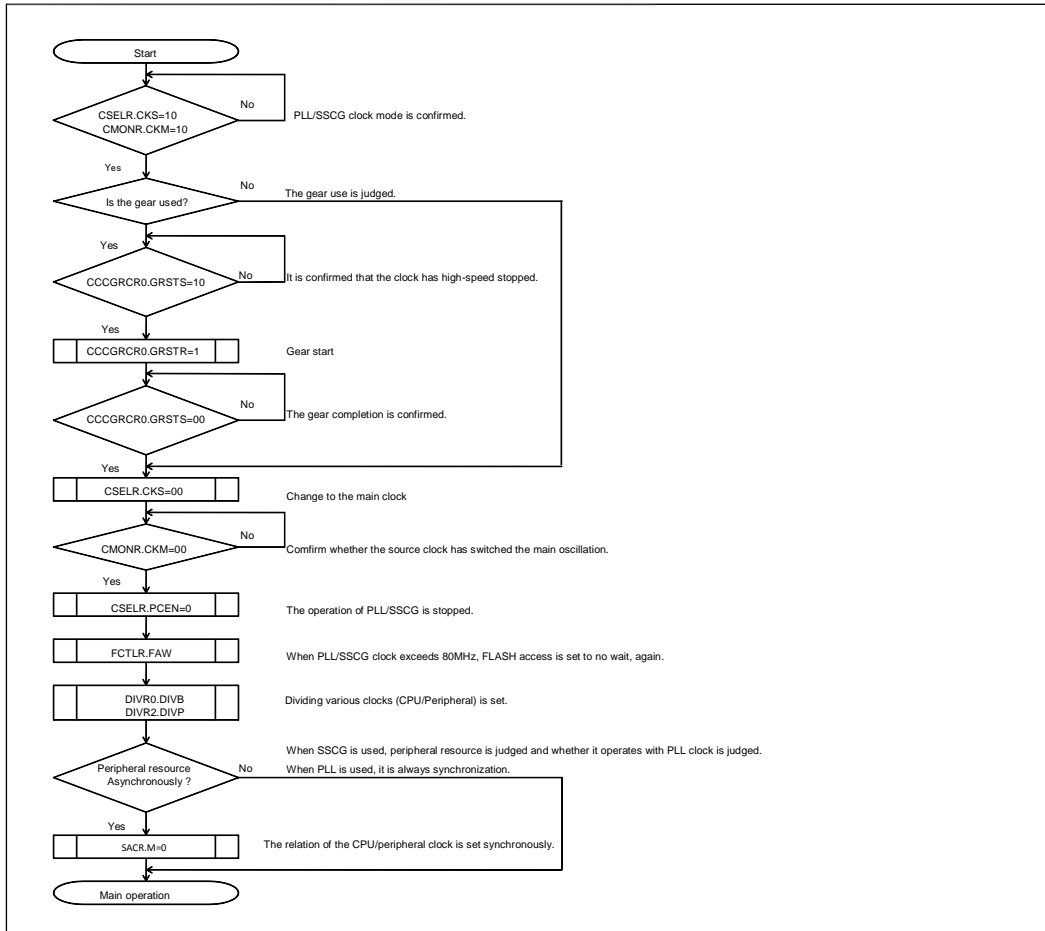


Figure 5-7 Example of PLL/SSCG Mode Setting PLL/SSCG → Main



5.4. Timer

The timer is shown.

- 5.4.1. Main Clock Oscillation Stabilization Wait Timer (Main Timer)
- 5.4.2. Sub Clock Oscillation Stabilization Wait Timer (Sub Timer)
- 5.4.3. PLL/SSCG Clock Oscillation Stabilization Wait timer (PLL Timer)
- 5.4.4. Setting
- 5.4.5. Procedure for Setting the Timer Interrupt
- 5.4.6. Timer Operations
- 5.4.7. Watch Mode and Timer Interrupt

5.4.1. Main Clock Oscillation Stabilization Wait Timer (Main Timer)

The main clock oscillation stabilization wait timer (Main Timer) is explained.

The main timer is operated by the main clock (MCLK). It is used for the main clock stabilization time counter. When main clock is stabilized, the timer can be used as the timer which generates interrupt after the specified period.

5.4.2. Sub Clock Oscillation Stabilization Wait Timer (Sub Timer)

The sub clock oscillation stabilization wait timer (Sub Timer) is explained.

The sub timer is operated by the sub clock (SBCLK). This timer is used for the generation of the sub clock oscillation stabilization wait time, and in the the sub clock stabilization status other than those can be used as the timer which generates interrupt after the specified period.

5.4.3. PLL/SSCG Clock Oscillation Stabilization Wait timer (PLL Timer)

The PLL/SSCG clock oscillation stabilization wait timer (PLL Timer) is shown.

The PLL timer is operated by the main clock and only for generation of the PLL/SSCG clock oscillation stabilization wait time. This timer can not be used for a general-purposed timer.

5.4.4. Setting

Setting is shown.

If the main timer operation is enabled (MTMCR:MTE=1), the count operation of the main timer starts. If the main timer operation is disabled (MTMCR:MTE=0), the count operation of the main timer stops and the main timer is cleared. If the main timer is cleared (MTMCR:MTC=1), the main timer is cleared.

MTMCR:MTC=1 is read until clear. The period of interrupt can be set by MTMCR:MTS[3:0]. When MTMCR:MTIE=1, if MTMCR:MTIF=1, the main timer interrupt occurs. MTMCR:MTIF is cleared by writing "0".

If the sub timer operation is enabled (STMCR:STE=1), the count operation of the sub timer starts. If the sub timer operation is disabled (STMCR:STE=0), the count operation of the sub timer stops and the sub timer is cleared.

If the sub timer is cleared (STMCR:STC=1), the sub timer is cleared. STMCR:STC=1 is read until clear. The period of interrupt can be set by STMCR:STS[2:0]. When STMCR:STIE=1, if STMCR:STIF=1, the sub timer interrupt occurs. STMCR:STIF is cleared by writing "0".

Note:

For setting the period of the timer interrupt (MTS and STS), set the period more than $PCLK1 \times 5$ clock. When the period of the timer interrupt is set to the extremely short time, the interrupt source may not be set.

5.4.5. Procedure for Setting the Timer Interrupt

The procedure for setting the timer interrupt is shown.

This section describes the procedure for setting interrupt. The examples of the procedure for setting interrupt are shown as follows.

Sets the timer interrupt disable (MTMCR:MTIE=0)/(STMCR:STIE=0)
and the interrupt flag clear(MTMCR:MTIF=0)/(STMCR:STIF=0)

↓

Sets the timer operation disable (MTMCR:MTE=0)/(STMCR:STE=0)

↓

Verifies MTC=0/STC=0

↓

Sets the period of the timer (MTMCR:MTS=1000 to 1111)/(STMCR:STS=000 to 111)

↓

Sets the timer interrupt enable (MTMCR:MTIE=1)/(STMCR:STIE=1)

↓

Sets the timer operation enable (MTMCR:MTE=1)/(STMCR:STE=1)

↓

The interrupt occurs after setting time

↓

To the interrupt routine

↓

Sets the interrupt flag clear (MTMCR:MTIF=0)/(STMCR:STIF=0)

↓

Verifies the interrupt flag (MTMCR:MTIF=0)/(MTMCR:STIF=0)

↓

Program operations

↓

RETI

* Repeat reading until "0" is read because actual setting of the interrupt flag clear is delayed.

5.4.6. Timer Operations

Timer operations are shown.

When `MTMCR:MTE=1`, the main timer counts up by the main clock (MCLK). If the timer overflows by the period which is selected by `MTMCR:MTS[3:0]`, `MTMCR:MTIF` is "1".

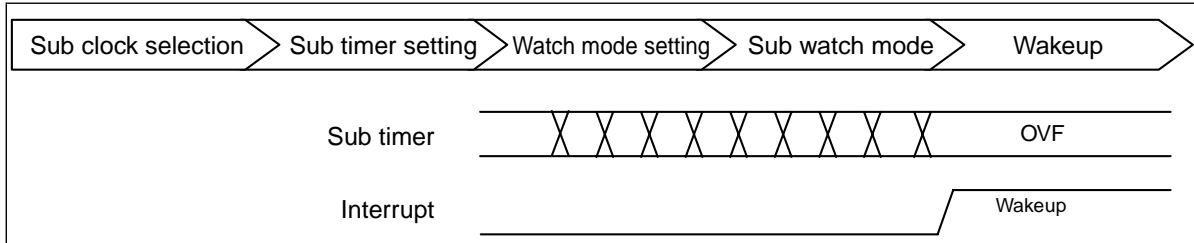
While `STMCR:STE=1`, the sub timer counts up by the sub clock (SBCLK). If the timer overflows by the period which is selected by `STMCR:STS[2:0]`, `STMCR:STIF` is "1".

5.4.7. Watch Mode and Timer Interrupt

Watch mode and timer interrupt are shown.

Watch mode stops the specific functions and all operations other than timer. (See "CHAPTER: POWER CONSUMPTION CONTROL") The wake-up from the watch mode is enabled by using main/sub timer interrupt or RTC interrupt. The example for switching of the watch mode in the setting of wake-up from the sub timer is shown as follows.

Figure 5-8 Wake-up from the Watch Mode



5.5. Notes when Clocks Conflict

Notes when clocks conflict is shown.

Notes that if peripheral interrupt activated by the very low frequency lower than the CPU clock (CCLK) in the interrupt handler is cleared and the interrupt handler is immediately stopped, the peripheral can not complete the internal process within the period of interrupt handler and the interrupt handler may be called over again.

5.6. The Clock Gear Circuit

The clock gear circuit is shown.

When the main clock is switched to the PLL/SSCG clock or the PLL/SSCG clock is switched to the main clock, the power supply current fluctuates widely because the frequency fluctuates rapidly. Using the clock gear circuit in the part of the clock switching can gradually fluctuate the operating frequency from a low frequency to a high frequency or from a high frequency to a low frequency and therefore can reduce the fluctuation of the power supply current.

5.6.1. Procedure of Gear Up

The procedure of gear up is shown.

1. The clock of the start step set to the clock gear start step selection is output after the oscillation stabilization wait timer completes.
2. When the clock gear start (CCCGRCR0:GRSTR, PGRRCR0:PGRSTR and SGRRCR0:SGRSTR) is set to "1" and the rising is detected, the clock gear status flag (CCCGRCR0:GRSTS[1:0], PGRRCR0:PGRSTS[1:0] and SGRRCR0:SGRSTS[1:0]) transits to "00"->"01" (give up start).
3. The gear up is executed according to the clock gear step selection and the repeat number selection. The step number is the smaller and the repeat number is the larger that the operation changes the more gradually
4. When the clock reaches the maximum step, the clock gear status flag (CCCGRCR0:GRSTS[1:0], PGRRCR0:PGRSTS[1:0] and SGRRCR0:SGRSTS[1:0]) transits to "01"->"10" (the end of gear up, the gear stops). After this, a clock is output at the maximum step (64 steps).
5. After the gear stops, the clock gear start (CCCGRCR0:GRSTR,PGRRCR0.PGRSTR and SGRRCR0:SGRSTR) is cleared to "0" by hardware.

5.6.2. Procedure of Gear Down

The procedure of gear down is shown.

1. When the clock gear start (CCCGRCR0:GRSTR, PGRRCR0:PGRSTR and SGRRCR0:SGRSTR) is set to "1" and the rising is detected, the clock gear status flag (CCCGRCR0:GRSTS[1:0], PGRRCR0:PGRSTS[1:0] and SGRRCR0:SGRSTS[1:0]) transits to "10"->"11" (give down start).
2. The gear down is executed according to the clock gear step selection and the repeat number selection. The step number is the smaller and the repeat number is the larger that the operation changes the more gradually.
3. When the clock reaches the minimum step, the clock gear status flag (CCCGRCR0:GRSTS[1:0], PGRRCR0:PGRSTS[1:0] and SGRRCR0:SGRSTS[1:0]) transits to "11"->"00" (the end of gear down, the gear stops). After this, the clock of the start step set for the clock gear start step selection is output.
4. After the gear stops, the clock gear start (CCCGRCR0:GRSTR, PGRRCR0:PGRSTR and SGRRCR0:SGRSTR) is cleared to "0" by hardware.

5.7. Operations during MDI Communications

Operations during MDI communications are shown.

The main oscillation is controlled so as not to be stopped during MDI communications even if the stop mode is transited to.

Moreover, (E_DBCR:PLOCK=1) is controlled so that the PLL reference clock is supplied even if CSELR:PCEN is cleared while communicating the MDI high speed. The value of the register related to PLL is maintained and not updated. However, when software sets CSELR:PCEN=0, the value of the register related to PLL can be freely updated (write).

When a value set to the register related to PLL last time and a different value are written and the PLL/SSCG clock oscillation permission is assumed to be effective (CSELR:PCEN=1), the frequency of the PLL clock is not updated. (PLL : because it maintains the locked status.)

Normally, always write the same value in the register related to PLL usually. When you change the setting value in the debug, monitor the value of E_DBCR:PLOCK and rewrite the register related to PLL in the status of E_DBCR:PLOCK =0.

* The register related to PLL is as follows.

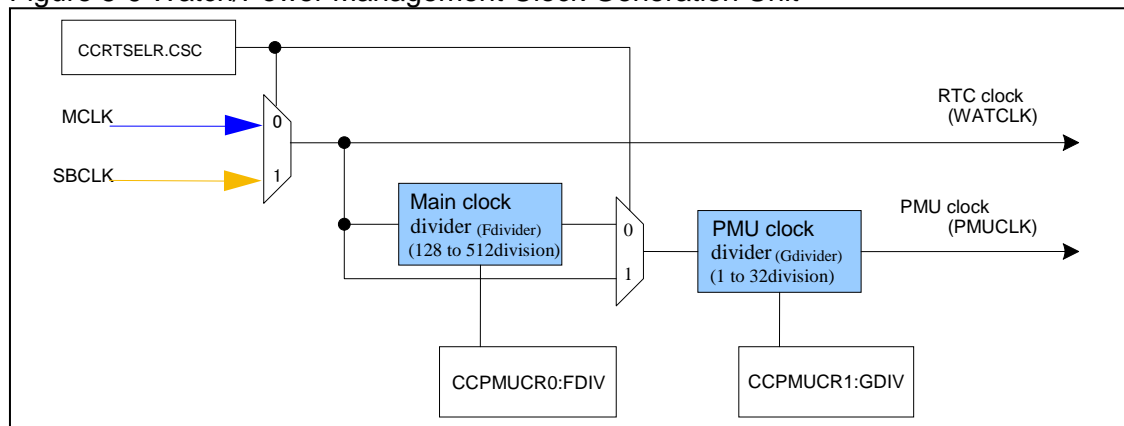
- CCPSDIVR:PODS
- CCPLLFBR: IDIV
- PLLCR:PDS

5.8. About PMU clock (PMUCLK)

The PMU clock (PMUCLK) is shown.

The PMU clock is an operation clock of power management unit (PMU). Complete the setting of this clock before controlling the standby mode.

Figure 5-9 Watch/Power Management Clock Generation Unit



The frequency of the PMU clock can be calculated by the following expressions.

- When CCRTSELR:CSC=0 (main clock is selected)

PMU clock frequency=

(Main clock frequency) / (CCPMUCR0:FDIV [1:0] division ratio) / (CCPMUCR1:GDIV[4:0] division ratio)

- When CCRTSELR:CSC=1 (sub clock is selected)

PMU clock frequency=(Sub clock frequency) / (CCPMUCR1:GDIV[4:0] division ratio)

Moreover, observe the following specification limitation to the PMU clock. (There is a possibility that the shutdown processing is not normally done when this limitation is not defended.)

- (1) Selects the clock under the oscillation about CCRTSELR:CSC.*
- (2) The PMU clock must use the machine of F divider frequency to become 32kHz or less.
- (3) Please use the machine of G dividing frequency to become 1/4 of the frequencies of peripheral clock (PCLK1).

*: Always CCRTSELR:CSC="0" is always read for single clock products.

It explains each specification limitation as follows.

- (1) Selects the clock under the oscillation about CCRTSELR:CSC.

Please confirm the CMONR: MCRDY register and the CMONR: SCRDY register to the oscillation of the main clock and a sub-clock. Moreover, when the CCRTSELR:CSC register is rewritten, the processing of the handshaking of the main clock and a sub-clock (clock transfer) is generated. If both clocks are oscillating (CMONR:MCRDY=CMONR:SCRDY=1), the change operation is not normally completed for this period. Please confirm the status of the clock transfer by the CCRTSELR:CST register.

(2) The PMU clock must use the machine of F divider frequency to become 32kHz or less. The PMU clock is used to control the power switch, and the frequency of 32kHz or less is recommended for the reasons for the stabilization at the pressure rising time when the power supply is input etc.

As for the PMU clock, the main clock is selected for CCRTSELR:CSC=0 as a source clock. Please set the CCPMUCR0:FDIV register so that the frequency of the PMU clock may become 32kHz or less. The machine of F divider frequency does not influence operation for CCRTSELR:CSC=1.

FDIV[1:0]	Division rate	Target main oscillation frequency
00	128 division(initial value)	4MHz
01	256 division	8MHz
10	384 division	12MHz
11	512 division	16MHz

(3) Please use the machine of G dividing frequency to become 1/4 of the frequencies of peripheral clock (PCLK1). Signal transfer between peripheral clock (PCLK) and PMU clock (PMUCLK) needs 4 PMU clock cycles.

When the source clock of peripheral clock(PCLK1) is sub oscillation clock (CMONR:CKM=10), the frequency of peripheral clock(PCLK1) should be set quadruple (or more higher) frequency of PMU clock. It can be set by CCPMUCR1:GDIV register.

When the source clock of peripheral clock(PCLK1) is main oscillation clock (CMONR:CKM=00 or CMONR:CKM=01). If the frequency of peripheral clock(PCLK1) is slower than 128kHz (depends on DIVR0:DIVB and DIVR2:DIVP), CCPMUCR1:GDIV register should be set as same.

GDIV[4:0]	Division ratio
00000	Do not divide (initial value)
00001	2 division
...	...
11110	31 division
11111	32 division

[Reference]

The frequency of the peripheral clock (PCLK1) can be calculated by the following expressions.

Peripheral clock (PCLK1) frequency=(Clock frequency selecting it by CMONR:CKM) / (DIVR0:DIVB[2:0] division ratio) / (DIVR2:DVP[3:0] division ratio)

CHAPTER: CLOCK RESET STATE TRANSITIONS

This chapter explains clock reset state transitions.

1. Overview
2. Device States and Transitions
3. Device State and Regulator Mode Corresponding to those States

Code : 06_MB91590_HM_E_clockreset_004_20111127

1. Overview

This section explains the overview of clock reset state transitions.

This chapter explains state transition of clock and reset. For features and settings of power consumption control state, see "CHAPTER: POWER CONSUMPTION CONTROL". For the operations of reset, see "CHAPTER: RESET". For the regulator mode, see "CHAPTER: REGULATOR CONTROL".

2. Device States and Transitions

This section explains device states and transitions of clock reset state transitions.

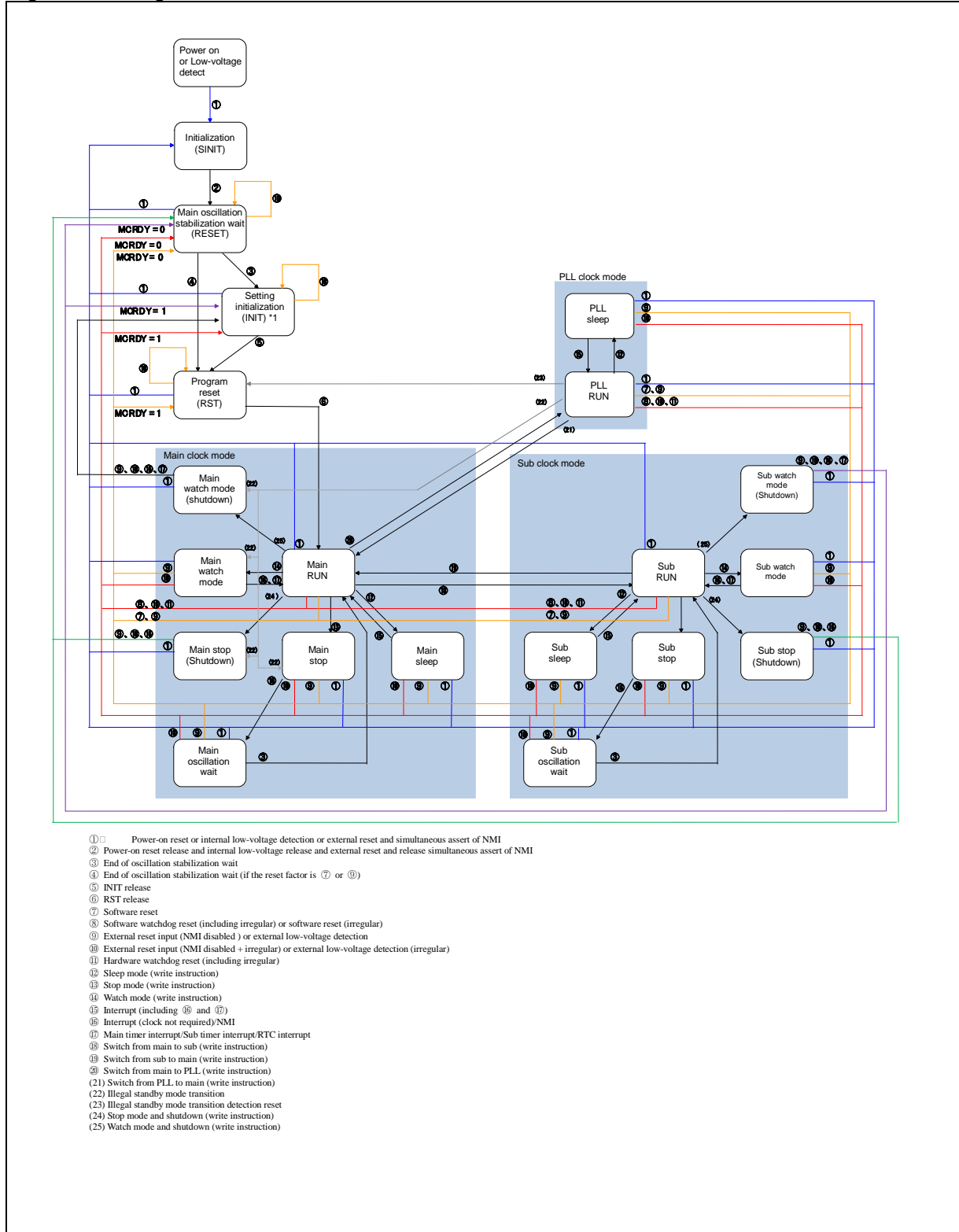
- 2.1. Diagram of State Transitions
- 2.2. Explanation of Each States
- 2.3. Priority of State Transition Requests

2.1. Diagram of State Transitions

This section shows diagram of state transitions.

The device state transitions for this series are shown below.

Figure 2-1 Diagram of Device State Transitions



*1 : There is a register not reset when returning from the watch mode (Shutdown) and returning from the stop mode (Shutdown). See "Limitations of the standby control power shutdown/usually" in "CHAPTER : POWER CONSUMPTION CONTROL" for detail.

Notes:

- The transition may be different from above diagram when connecting to OCD tool. See "CHAPTER: ON CHIP DEBUGGER (OCD)" for details.
 - The sub clock mode is not transmitted to because single clock products do not include the sub clock input.
-

2.2. Explanation of Each States

This section explains each state.

Device operation states for this series are shown below.

■ RUN State (Normal Operation)

The program is running. All internal clocks supply and all circuits are ready to operate. High-impedance controls for the external pins in the stop state and watch mode state will be released.

■ Sleep Mode

The program is not running. The state transits by program operations. There are some settings; one to stop program execution of the CPU only (CPU sleep mode) and the other to stop the CPU, on-chip bus (on-chip bus) and on-chip bus clock (HCLK) driven peripheral (bus sleep mode). For details, see "CHAPTER: POWER CONSUMPTION CONTROL".

■ Watch Mode State

The devices are not running. The state transits by program operations. Internal circuits other than oscillation circuits (main clock generation unit, sub clock generation unit) stop. Stop PLL oscillation before going into the watch mode state. It is also possible to use the external pins altogether (except for some pins) for high impedance by the settings. Transits to the RUN state by some specific (no clock required) effective interrupts, main timer interrupts, sub timer interrupts and watch counter interrupts. For details, see "CHAPTER: POWER CONSUMPTION CONTROL".

■ Watch Mode (Power Shutdown) State

The device is stopped while the power supply unnecessary for the watch mode is turned off. The state transits by program operation. The power supply for the internal circuit in Microcontroller/GDC unit is turned off and the internal circuits other than the oscillation circuits (the main clock generation unit and the sub clock generation unit) are stopped. Stop PLL oscillation before going into the watch mode (power shutdown) state. It is also possible to use the external pins altogether (except for some pins) for high impedance by the settings. Transits to the setting initialization (INIT) state by some specific (no clock required) effective interrupts, the main timer interrupt, the sub timer interrupt and the watch counter interrupt. For details, see "CHAPTER: POWER CONSUMPTION CONTROL".

■ Stop State

The devices are not running. The state transits by program operations. All internal circuits will stop. Stop PLL oscillation before going into the stop mode state. It is also possible to use the external pins altogether (except for some pins) for high-impedance by the settings. Transits to the oscillation stabilization wait RUN state by NMI interrupt. For details, see "CHAPTER: POWER CONSUMPTION CONTROL".

■ Stop (Power Shutdown) State

The device is stopped while the power supply unnecessary for the stop state is turned off. The state transits by program operation. The power supply for the internal circuit in Microcontroller/GDC unit is turned off and all the internal circuits are stopped. Stop PLL oscillation before going into the stop (power shutdown) state. It is also possible to use the external pins altogether (except for some pins) for high impedance by the settings. Transits to the main oscillation stabilization wait (reset) state by NMI interrupt. For details, see "CHAPTER: POWER CONSUMPTION CONTROL".

■ Main Oscillation Stabilization Wait, Sub Oscillation Stabilization Wait (RUN) State

The devices are not running. Transits after returning from the stop state. All the internal circuits except for the timer operations for oscillation stabilization wait will stop. All internal clocks stop but the enabled oscillation circuits will still be running. After the elapse of the oscillation stabilization wait time interval set, transits to the RUN state (normal operation).

■ **Main Oscillation Stabilization Wait (Reset) State**

The devices are not running. Transits after returning from the initialization (SINIT) state. All the internal circuits except for the timer operations for oscillation stabilization wait will stop. All internal clocks stop but the main oscillation circuit will still be running. Outputs the program reset (RST) to the internal circuits. When the accepted reset level is an initialization reset, outputs also the setting initialization reset (INIT). After the elapse of the main clock oscillation stabilization wait time ($2^{15} \times$ main clock cycle), transits to the setting initialization (INIT) state.

■ **Program Reset (RST) State**

The program is initialized. Transits after accepting the operation initialization reset (RST) request or at the end of the setting initialization (INIT) state. Outputs the program reset (RST) to the internal circuits. When transiting from the INIT state, OCD chip reset sequence (1026+3 PCLK cycles) will be performed.

Transits to the RUN state (normal operation) when removing the operation initialization reset (RST) request. For details, see "CHAPTER: RESET".

■ **Setting Initialization (INIT) State**

All settings are initialized. Transits after accepting a setting initialization (INIT) request. The main oscillation circuit continues to run but the sub oscillation circuit and PLL will stop operations. Outputs a setting initialization (INIT) and a program reset (RST) to the internal circuits. Transits to the program reset (RST) state when removing the setting initialization (INIT) request and this state being released. For details, see "CHAPTER: RESET".

2.3. Priority of State Transition Requests

Priority of state transition requests is shown.

The state transition requests are prioritized in the following order in any states. However, since some requests are generated only in the specific states, they are enabled only in those states.

[Highest priority]	Initialization (SINIT) request
↓	Setting initialization (INIT) request
↓	The end of the oscillation stabilization wait time (generates an oscillation stabilization wait reset state and an oscillation stabilization wait RUN state only.)
↓	Program reset (RST) request
↓	Effective interrupt request (generates RUN, sleep, stop, watch mode states only)
↓	Stop mode request (register write) (generates RUN state only)
↓	Watch mode request (register write) (generates RUN state only)
[Lowest priority]	Sleep mode request (register write) (generates RUN state only)

3. Device State and Regulator Mode Corresponding to those States

Device state and regulator mode corresponding to those states are shown.

The regulator mode corresponding to each device state is shown in the following table. For regulator mode, see "CHAPTER: REGULATOR CONTROL".

Table 3-1 Relationship between Device State and Regulator Mode (single clock product)

Device state	Main clock	Regulator mode
Main RUN	Oscillation	Main mode
Main sleep	Oscillation	Main mode
Main watch mode	Oscillation	Standby mode
Main watch mode (Shutdown)	Oscillation	Standby mode
Main stop	Stop	Standby mode
Main stop (Shutdown)	Stop	Standby mode
Main Oscillation wait	Oscillation	Main mode
PLL RUN	Oscillation	Main mode
PLL sleep	Oscillation	Main mode

Table 3-2 Relationship between Device State and Regulator Mode (dual clock product)

Device state	Main clock	Sub clock	Regulator mode
Main RUN	Oscillation	Oscillation or Stop	Main mode
Main sleep	Oscillation	Oscillation or Stop	Main mode
Main watch mode	Oscillation	Oscillation or Stop	Standby mode
Main watch mode(Shutdown)	Oscillation	Oscillation or Stop	Standby mode
Main stop	Stop	Stop	Standby mode
Main stop (Shutdown)	Stop	Stop	Standby mode
Main Oscillation wait	Oscillation	Oscillation or Stop	Main mode
Sub RUN 1	Oscillation	Oscillation	Main mode
Sub RUN 2	Stop	Oscillation	Sub mode
Sub sleep 1	Oscillation	Oscillation	Main mode
Sub sleep 2	Stop	Oscillation	Sub mode
Sub watch mode	Oscillation or Stop	Oscillation	Standby mode
Sub watch mode (Shutdown)	Oscillation or Stop	Oscillation	Standby mode
Sub stop	Stop	Stop	Standby mode
Sub stop (Shutdown)	Stop	Stop	Standby mode
Sub Oscillation wait 1	Oscillation	Oscillation	Main mode
Sub Oscillation wait 2	Stop	Oscillation	Sub mode
PLL RUN	Oscillation	Oscillation or Stop	Main mode
PLL sleep	Oscillation	Oscillation or Stop	Main mode

Note:

When OCD tool is connected, the regulator mode is a main mode in the above any tables.

CHAPTER: RESET

This chapter explains the reset.

1. Overview
2. Features
3. Configuration
4. Regisyers
5. Operation Description

1. Overview

This section explains the overview of the reset.

When a reset factor is generated, the device terminates all programs and most of the hardware operations and initializes the state. This state is referred to as a reset.

2. Features

This section explains features of the reset.

This product, which has the following reset factors, issues a reset by accepting each factor to initialize the components in the device.

- Power-on reset
- RSTX pin Input
- Watchdog reset 0 (Software watchdog)
- Watchdog reset 1 (Hardware watchdog)
- Software reset
- Illegal standby mode transition detection reset
- Flash security violation
- Internal low-voltage detection
- External low-voltage detection
- Clock supervisor reset
- Recovery reset from stand by (power shutdown)

Other than the case of irregular reset (see "4.1 Reset Source Register : RSTRR (ReSeT Result Register)"), the contents of memory being accessed by the reset (RAM, Flash) will not be destroyed since all resets are issued once the completion of all bus accesses have been confirmed.

To issue a forced reset in case the bus does not return the response within a certain time frame, the device waits for the reset issue delay counter. If there is no response within the specified time frame, a reset will be issued whether or not the bus has responded. (Reset timeout)

See "CHAPTER : CLOCK SUPERVISOR" for clock supervisor reset.

3. Configuration

This section explains the configuration of the reset.

Figure 3-1 Configuration Diagram of Reset

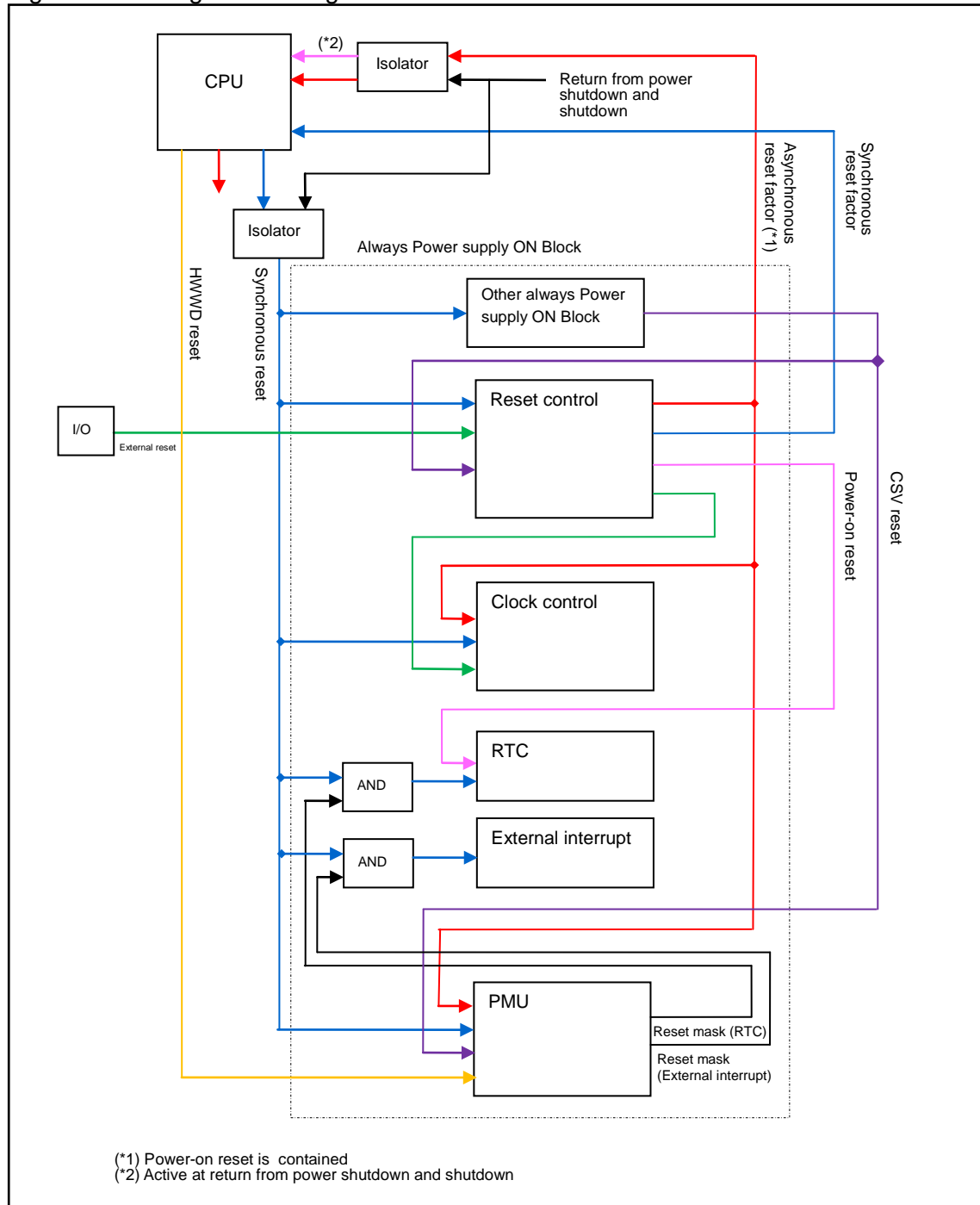


Figure 3-2 Configuration Diagram of Reset (Reset Control)

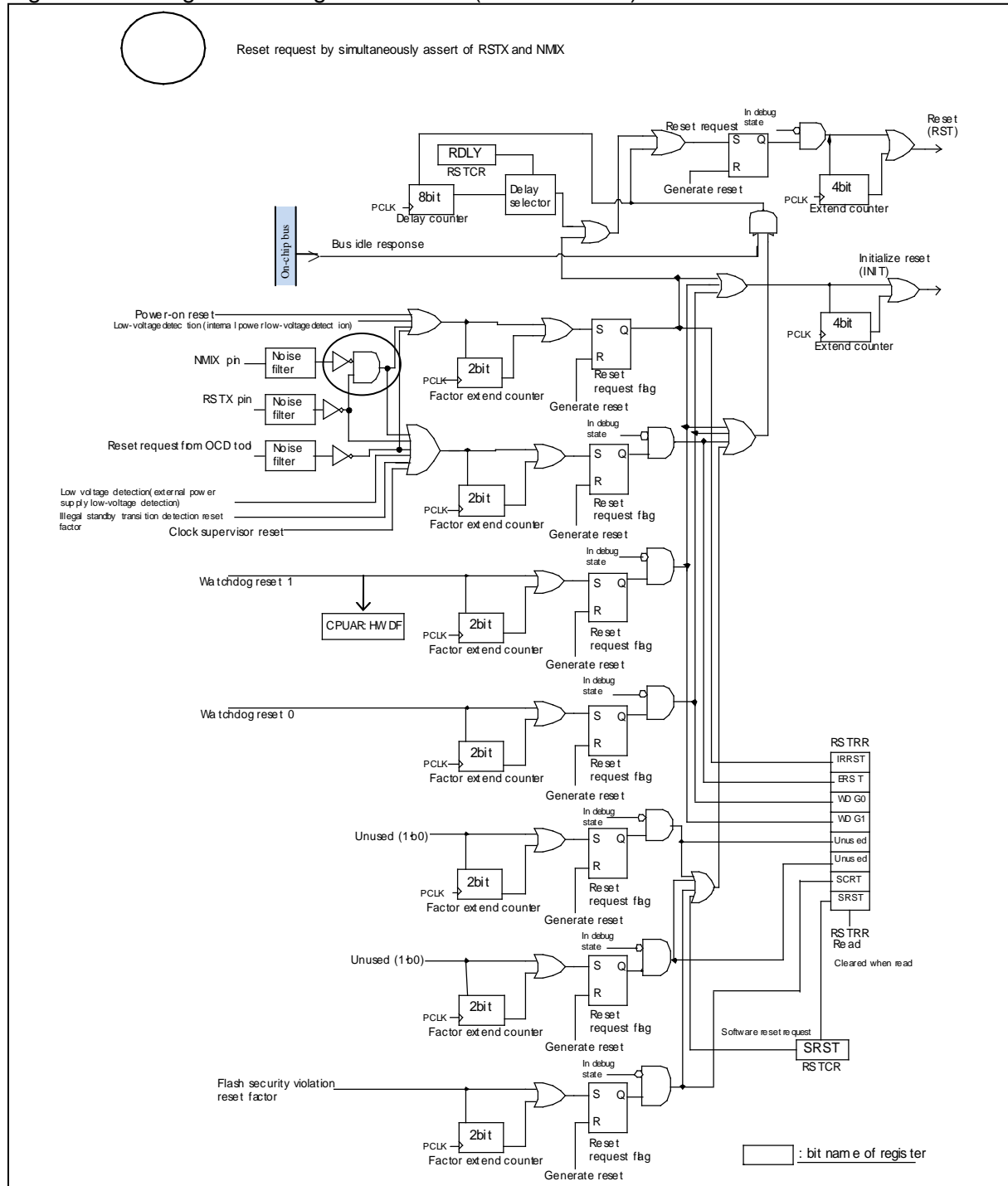
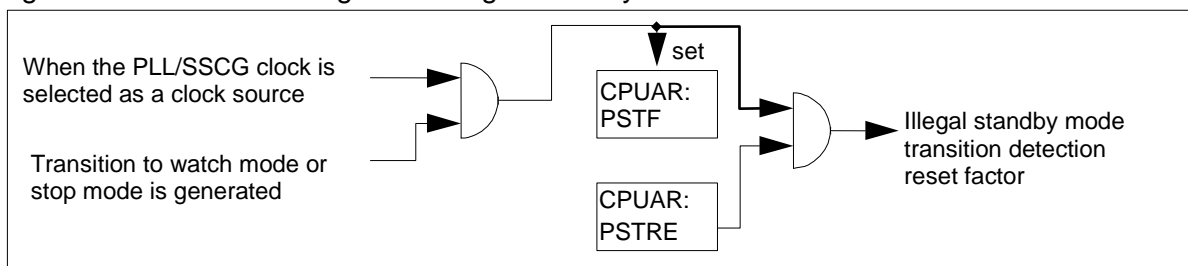


Figure 3-3 Generation Diagram of Illegal Standby Mode Transition Detection Reset Factor



4. Registers

This section explains the registers of the reset.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0480	RSTRR	RSTCR	Reserved	Reserved	Reset Source Register Reset Control Register
0x0518	Reserved	Reserved	CPUAR	Reserved	CPU Abnormal Operation Register
0x0590	PMUSTR	Reserved	Reserved	Reserved	PMU Status Register

Note:

Please note that the register of "CHAPTER : POWER CONSUMPTION CONTROL" is allocated in address 0x0482, 0x0591, and 0x0592.

4.1. Reset Source Register : RSTRR (ReSeT Result Register)

The bit configuration of the reset source register is shown.

This register displays various reset factors generated until just before.

Note:

When this register is read out, all bits will be cleared.
This register is not cleared in reading in the debugging state.
Because each reset factor is masked in the debugging state, this register does not detect the reset factor either.

■ **RSTRR : Address 0480_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	IRRST	ERST	WDG1	WDG0	Reserved		SCRT	SRST
Initial value	*	*	*	*	-	-	*	*
Attribute	R,WX	R,WX	R,WX	R,WX	RX,WX	RX,WX	R,WX	R,WX

* Due to a reset factor.

[bit7] IRRST (IRregular ReSeT) : Irregular reset

This bit indicates that any of power-on reset, internal low-voltage detection, reset timeout, or simultaneous assert of RSTX and NMIX external pins has occurred, so that the bus access state when issuing a reset cannot be guaranteed. When this bit is "0" after the reset, no bus access was executed at the previous reset, which guarantees that memory contents have not been destroyed by the reset. When this bit is "1" after the reset, it is possible that a bus access was executed at the previous reset, which does not guarantee that memory contents have not been destroyed by the reset.

IRRST	Irregular reset detected
0	Irregular reset undetected
1	Irregular reset detected

This bit will be cleared when it is read out.

[bit6] ERST (External ReSeT) : Reset pin input, illegal standby mode transition detection, external low-voltage detection, clock supervisor reset, simultaneous assert of RSTX and NMIX external pins

This bit indicates that there was a reset input from RSTX pin input, illegal standby mode transition detection reset, external low-voltage detection, clock supervisor reset or simultaneous assert of RSTX and NMIX external pins.

In case of a reset time out due to this reset factor, IRRST along with this bit will be "1".

ERST	RSTX pin reset detection, illegal standby mode transition detection, external low-voltage detection, clock supervisor reset or simultaneous assert of RSTX and NMIX external pins
0	Undetected
1	Detected

This bit will be cleared when it is read out.

[bit5] WDG1 (WatchDoG reset 1) : Watchdog Reset 1

This bit indicates a reset from the watchdog timer 1.

In case of a reset time out due to this reset factor, IRRST along with this bit will be "1".

WDG1	Watchdog timer 1 reset
0	Undetected
1	Detected

This bit will be cleared when it is read out.

The CPUAR register also has a flag that indicates a reset factor generation by the watchdog reset 1. The bit will not be cleared when the CPUAR register is read.

[bit4] WDG0 (WatchDoG reset 0) : Watchdog Reset 0

This bit indicates a reset from the watchdog timer 0.

In case of a reset time out due to this reset factor, IRRST along with this bit will be "1".

WDG0	Watchdog timer 0 reset
0	Undetected
1	Detected

This bit will be cleared when it is read out.

[bit1] SCRT (Flash SeCuRiT y violation) : Flash security violation reset

This bit indicates that a flash memory security violation reset has occurred.

In case of a reset time out due to this reset factor, IRRST along with this bit will be "1".

SCRT	Flash security violation reset
0	Undetected
1	Detected

This bit will be cleared when it is read out.

[bit0] SRST (Software ReSeT) : Software reset

This bit indicates a reset by writing "1" to the RSTCR:SRST bit.

In case of a reset time out due to this reset factor, IRRST along with this bit will be "1".

SRST	Software reset
0	Undetected
1	Detected

This bit will be cleared when it is read out.

4.2. Reset Control Register : RSTCR (ReSeT Control Register)

The bit configuration of the reset control register is shown.

This register controls various types of reset issuance.

■ RSTCR : Address 0481_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RDLY[2:0]			Reserved				SRST
Initial value	1	1	1	0	0	0	0	0
Attribute	R,W	R,W	R,W	R/W	R/W	R/W	R/W	R,W

[bit7 to bit5] RDLY[2:0] (Reset DeLaY) : Reset issue delay

These bits set the reset timeout value. A reset will be issued if all bus operations become idle or the timer has counted to the reset timeout by this bit after a reset factor has been detected. (The latter is a case of irregular reset). These bits can be written for only once after the reset.

RDLY[2:0]	Reset timeout value
000	PCLK × 2 cycles
001	PCLK × 4 cycles
010	PCLK × 8 cycles
011	PCLK × 16 cycles
100	PCLK × 32 cycles
101	PCLK × 64 cycles
110	PCLK × 128 cycles
111	PCLK × 256 cycles (Initial value)

[bit0] SRST (Software ReSeT) : Software reset

You will be able to generate a software reset request by reading RSTCR after writing "1" to this bit.

After you have written "1" to this bit, any values written to RSTCR will be ignored until a reset is generated, which means that register values cannot be changed.

In the RSTCR reading in the debugging state, reset is not generated.

SRST	Software reset
0	No output (initial value)
1	The set request is output by RSTCR reading.

4.3. CPU Abnormal Operation Register : CPUAR (CPU Abnormal operation Register)

The bit configuration of the CPU abnormal operation register is shown.

This register indicates the status and settings associated with the abnormal operation of CPU.

■ **CPUAR : Address 051A_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PSTRE	Reserved				P MDF	PSTF	HWDF
Initial value	0	0	0	0	*	*	*	*
Attribute	R/W	R0,WX	R0,WX	R0,WX	RX,WX	R(RM1),W	R(RM1),W	R(RM1), W

* : It will be initialized to "0" by RSTX pin asserts (including simultaneous assert with NMIX). It will not be initialized by the other reset factors.

[bit7] PSTRE (illegal PLL-run to SStandby Reset Enable) : Illegal standby mode transition detection reset enable

This bit configures whether or not to issue a reset when a watch mode or a stop mode transition has been detected (illegal standby mode transition) with the PLL clock selected as a clock source.

When enabled, a reset due to the illegal standby mode transition detection factor will be generated at a transition from the PLL-run state to watch mode or stop mode.

PSTRE	Description
0	Reset will not be generated (initial value)
1	Reset generation enabled

Note:

When you set this bit, make sure to clear the PSTF bit by writing "0" to the PSTF bit before setting this bit. If you set this bit before clearing the PSTF bit, a reset may be generated since the value of the PSTF bit after the power-on reset is indefinite.

Note:

When the OCD tool is connected, and the high-speed UART mode and phase modulation UART mode are selected, an illegal standby mode transition detection reset will not be generated.

[bit2] PMDF (PLL mode Main clock Down detection Flag) : PLL mode main oscillation determination detection flag

When the clock supervisor does the main oscillation determination detection when PLL output is selected as a clock source, this bit is set. Moreover, the source clock is written automatically in main mode (CKS=CKM=00), and reset (RST level) is generated at once.

If a read-modify-write instruction is executed, "1" will be read out.

PMDF	Read	Write
0	The main oscillation determination detection is not in PLL mode. (initial value)	Clear this bit
1	The main oscillation determination detection is in PLL mode.	No effect

The set factor is given to priority when a set factor and a clear factor are generated at the same time.

[bit1] PSTF (illegal PLL-run to Standby Flag) : Illegal standby mode transition detection flag

This bit will be set when a watch mode or a stop mode transition has been detected (illegal standby mode transition) with the PLL clock selected as a clock source. Moreover, the source clock is written automatically in main mode (CKS=CKM=00). When the PSTRE bit is "1", reset (RST level) is generated.

This bit is cleared by writing "0".

If a read-modify-write instruction is executed, "1" will be read out.

PSTF	Read	Write
0	No illegal standby mode transition has been detected	Clear this bit
1	Illegal standby mode transition has been detected.	No effect

[bit0] HWDF (Hardware WatchDog Flag) : Hardware watchdog detection flag

When a reset factor for the watchdog timer 1 (Hardware watchdog) has been detected, this bit will be set.

This bit is cleared by writing "0".

If a read-modify-write instruction is executed, "1" will be read out.

HWDF	Read	Write
0	No watchdog timer1 (Hardware watchdog) reset factor has been generated.	Clear this bit
1	Watchdog timer1 (Hardware watchdog) reset factor has been generated.	No effect

The set factor is given to priority when a set factor and a clear factor are generated at the same time.

Note:

There is a detection flag also in RSTRR:WDG1, and the factor disappears when read once because it is read clear. Because CPUAR:HWDF is maintained, the factor is maintained until clearing.

4.4. PMU Status Register : PMUSTR (Power Management Unit Status register)

The bit configuration of the PMU status register is shown.

This register indicates the PMU status.

■ PMUSTR : Address0590_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PMUST	Reserved					PONR_F	RSTX_F
Initial value	0	0	0	0	0	0	1	*
Attribute	R,W	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R,W	R,W

* : It will be initialized to "1" by RSTX pin asserts (including simultaneous assert with NMIX). It will not be initialized by the other reset factors.

[bit7] PMUST (Power Management Unit Status)

The state immediately before shows information on whether it was a shutdown mode.

PMUST	PMU status
0	Operation return from initial state and initialization reset
1	Operation return from Shutdown mode

This bit is cleared by writing "0". "1" writing is invalid.

[bit6 to bit2] Reserved

"0" is always read. Please be sure to write "0".

[bit1] PONR_F (Power ON Reset Flag)

This bit is a power-on reset detection flag.

PONR_F	Power-on reset
0	No detection
1	Detection

This bit is cleared by writing "0". "1" writing is invalid.

This bit is not initialized in reset factors other than power-on reset.

[bit0] RSTX_F (ReSeTX input Flag)

This bit is an external reset detection flag.

RSTX_F	RSTX input reset
0	No detection
1	Detection

This bit is cleared by writing "0". "1" writing is invalid.

This bit is not cleared by the power-on reset. Be sure to use after clear.

5. Operation Description

This section explains each operation of the reset feature of this product.

- 5.1. Reset Level
- 5.2. Reset Factor
- 5.3. Reset Acceptance
- 5.4. Reset Issue
- 5.5. Reset Sequence

5.1. Reset Level

The reset level is explained.

The following two levels of resets are available with this product.

Note:

Except the registers for debug interface (OCDU), the registers initialized by the reset of both levels are the same for this product. However, there are some registers initialized by the INIT level instead of the RST level when the OCD tool is connected, and the high speed UART mode and phase modulation UART mode are selected. See "CHAPTER : ON CHIP DEBUGGER (OCD)".

5.1.1. Initialize Reset (INIT)

Initialize reset (INIT) is explained.

It initializes all register settings and the entire hardware. It terminates the CPU programs running, and the program counter will be initialized. All peripheral circuits will be initialized. A main oscillation circuit continues to run. If it was inactive, it starts running again. In this case a sub oscillation circuit and, PLL become inactive.

This reset level is applied at a reset by the following reset factors.

- Irregular reset
- Watchdog reset 0, 1

Only the following register will be initialized by this reset level.

- Register of the debug interface (OCDU)

There are some registers initialized by the INIT level instead of the RST level when the OCD tool is connected, and the high-speed UART mode and phase modulation UART mode are selected. See "CHAPTER : ON CHIP DEBUGGER (OCD)".

5.1.2. Reset (RST)

The reset (RST) is explained.

It initializes the entire hardware and all registers except the ones initialized only by the initialize reset (INIT). It terminates the CPU programs running, and the program counter will be initialized. All peripheral circuits will be initialized.

When an initialize reset (INIT) is issued, a reset (RST) is issued at the same time.

The reset in the entire document indicates this reset level unless otherwise specified.

There are some registers initialized by the INIT level instead of the RST level when the OCD tool is connected, and the high-speed UART mode and phase modulation UART mode are selected. See "CHAPTER : ON CHIP DEBUGGER (OCD)".

5.2. Reset Factor

This section explains each reset factor of this product.

- 5.2.1. Power-on Reset
- 5.2.2. RSTX Pin Input
- 5.2.3. Watchdog Reset 0
- 5.2.4. Watchdog Reset 1
- 5.2.5. External Low-Voltage Detection Reset
- 5.2.6. Illegal Standby Mode Transition Detection Reset
- 5.2.7. Internal Low-Voltage Detection Reset
- 5.2.8. Flash Security Violation Reset
- 5.2.9. Software Reset (RSTCR:SRST)
- 5.2.10. Recovery from Standby (Power Interception)

5.2.1. Power-on Reset

Power-on reset is shown.

It is a reset factor generated when detecting the power has turned on.

All resets due to this reset factor are detected as an irregular reset and issue an initialize reset (INIT).

5.2.2. RSTX Pin Input

The RSTX pin input is shown.

It is a hardware reset input from the outside of the device.

Reset by this reset factor is detected as irregular reset only at the reset timeout or simultaneous assert of the NMIX pin.

Other than the irregular reset detection, a reset (RST) will be issued.

5.2.3. Watchdog Reset 0

The watchdog reset 0 is shown.

It is a hardware reset input from the FR81S-core built-in watchdog timer 0 (software watchdog).

Resets due to this reset factor will be detected as an irregular reset only at the time of reset timeout. Whether or not an irregular reset has been detected, an initialize reset (INIT) will be issued.

5.2.4. Watchdog Reset 1

The watchdog reset 1 is shown.

It is a hardware reset input from the FR81S-core built-in watchdog timer 1 (hardware watchdog).

Resets due to this reset factor will be detected as an irregular reset only at the time of reset timeout.
Whether or not an irregular reset has been detected, an initialize reset (INIT) will be issued.

5.2.5. External Low-Voltage Detection Reset

The external low-voltage detection reset is shown.

Low-voltage detection (external voltage) is a hardware reset input from the low-voltage detection circuit located inside of the device. Resets due to this reset factor will be detected as an irregular reset only at the time of reset timeout. Other than the irregular reset detection, a reset (RST) will be issued.

See "CHAPTER : LOW VOLTAGE DETECTION (EXTERNAL LOW-VOLTAGE DETECTION)" for details on voltage detection.

5.2.6. Illegal Standby Mode Transition Detection Reset

the illegal standby mode transition detection reset is shown.

It is a hardware reset generated when a watch mode or a stop mode transition has been detected (illegal standby mode transition) with the PLL clock selected as a clock source.

Resets due to this reset factor will be detected as an irregular reset only at the time of reset timeout. Other than the irregular reset detection, a reset (RST) will be issued

5.2.7. Internal Low-Voltage Detection Reset

The internal low-voltage detection reset is shown.

Low-voltage detection (internal voltage) is a hardware reset input from the low-voltage detection circuit located inside of the device. The reset from this reset source is detected as irregular reset. After the detection, an initialize reset (INIT) will be issued.

See "CHAPTER : LOW VOLTAGE DETECTION (INTERNAL LOW-VOLTAGE DETECTION)" for details on voltage detection.

5.2.8. Flash Security Violation Reset

The Flash security violation reset is shown.

It is a reset issued when a violation of flash memory security protection has occurred.
Resets due to this reset factor will be detected as an irregular reset only at the time of reset timeout.

Other than the irregular reset detection, a reset (RST) will be issued.

5.2.9. Software Reset (RSTCR:SRST)

The software reset (RSTCR:SRST) is shown.

It is a software reset generated inside of the device.

This reset will be issued when you read RSTCR after writing "1" to the bit0: SRST bit of the RSTCR. Resets due to this reset factor will be detected as an irregular reset only at the time of reset timeout. Other than the irregular reset detection, a reset (RST) will be issued.

[Example] Sample program of a software reset issue

```
LDI    #value_of_reset, R0      ; SRST bit=1
LDI    #_RSTCR, R12            ;
STB    R0, @R12                ; Write
LDUB   @R12, R0                ; Read (generation of a software reset request)
MOV    R0, R0                  ; Dummy processing for pipeline adjustment
NOP                                     ; Dummy processing for pipeline adjustment
```


5.2.10. Recovery from Standby (Power Interception)

Recovery from standby (power interception) is shown.

On majority of the block including microcontroller, the operation corresponding to the power-on reset is executed by the start from the standby. However, power-on reset factor is always at the power-on block, the detection is not displayed in the reset source register (RSTRR) . The factors are displayed in the PMU status register (PMUSTR), and please confirm this register, when the microcontroller reactivates.

Reset by this reset factor issues the initialization reset (INIT).

5.3. Reset Acceptance

This section explains the acceptance processing of each reset factor.

- 5.3.1. Generation of Reset Request
- 5.3.2. Acceptance of Reset Request
- 5.3.3. Reset Issue Delay Counter
- 5.3.4. Irregular Reset

5.3.1. Generation of Reset Request

The generation of a reset request is shown.

A reset request will be generated when at least one reset factor is retrieved. The reset request will be notified to the internal bus controller, and the following processing will be executed.

- Stop the CPU programs running (same processing as sleep mode)
- Acquire bus control right of the on-chip bus
- Confirm that idle request has been notified to all busses

5.3.2. Acceptance of Reset Request

Acceptance of a reset request is shown.

Once all processing for the reset request completes, the component where a reset is issued accepts the reset request and issues a reset of which level corresponds to the reset factor. If the reset issue delay counter overflows (= reset timeout occurs), the reset request is accepted without waiting for the completion of reset request processing, and an irregular reset will be issued.

5.3.3. Reset Issue Delay Counter

The reset issue delay counter is shown.

As soon as a reset request is generated, the 8-bit reset issue delay counter starts counting. If the delay cycle specified by the bit7 to bit5: RDLY[2:0] bits of the RSTCR register has elapsed without a reset being issued and the counter overflows (= reset timeout occurs), an irregular reset will be issued.

The RDLY[2:0] bit of the RSTCR will be initialized by a reset. This bit can be rewritten for once only after a reset is released. If the delay cycle is set for a short time, it is more likely to generate an irregular reset. If the delay cycle is set for a long time, it might take a long time for a reset to be issued since the generation of a reset factor.

5.3.4. Irregular Reset

The irregular reset is shown.

If a reset is issued without confirming the completion of reset request processing, it will generate an irregular reset.

Once an irregular reset is generated, the following processing will be executed.

- Regardless of the type of reset factor, initialize reset (INIT) will be issued.
- Set the bit7: IRRST bit of RSTRR register to "1".

When an irregular reset occurs, there is no guarantee that memory contents were not destroyed by the reset since a bus access may have been executed at the time of inputting the reset. The irregular reset does not necessarily mean that the memory contents were destroyed, but how the bus access was executed cannot be identified.

5.4. Reset Issue

A reset will be issued after a reset request has been accepted. This section explains each type of reset issue.

- 5.4.1. Power-on Reset (SINIT)
- 5.4.2. Initialize Reset (INIT)
- 5.4.3. Reset (RST)

5.4.1. Power-on Reset (SINIT)

The Power-on reset (SINIT) is shown.

The power-on reset (SINIT) will be issued first for power-on reset, internal low-voltage detection, or simultaneous assert of RSTX and NMIX.

This reset is exclusively used for initializing the indefinite state of division circuits and so on.

While this reset is being issued, all clocks become inactive.

When this reset is issued, an initialize reset (INIT) and a reset (RST) will be always issued at the same time.

This reset initializes the clock control register.

This reset involves the wait time of main clock oscillation to be stabilized. Along with the control register initialization, the oscillation stabilization wait time is $2^{15} \times$ main clock cycle.

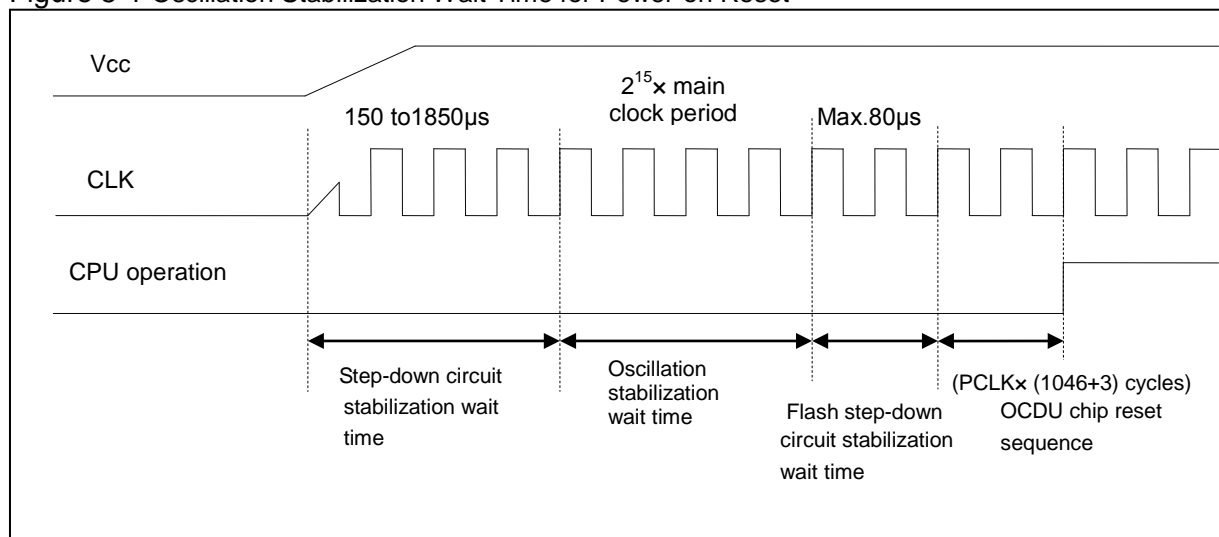
Table 5-1 Oscillation Stabilization Wait Time (SINIT)

Type	Main clock oscillation stabilization wait time
Power-on reset	$2^{15} \times$ Main clock cycle
Internal low-voltage detection	$2^{15} \times$ Main clock cycle
Simultaneous assert of RSTX and NMIX	$2^{15} \times$ Main clock cycle

Note:

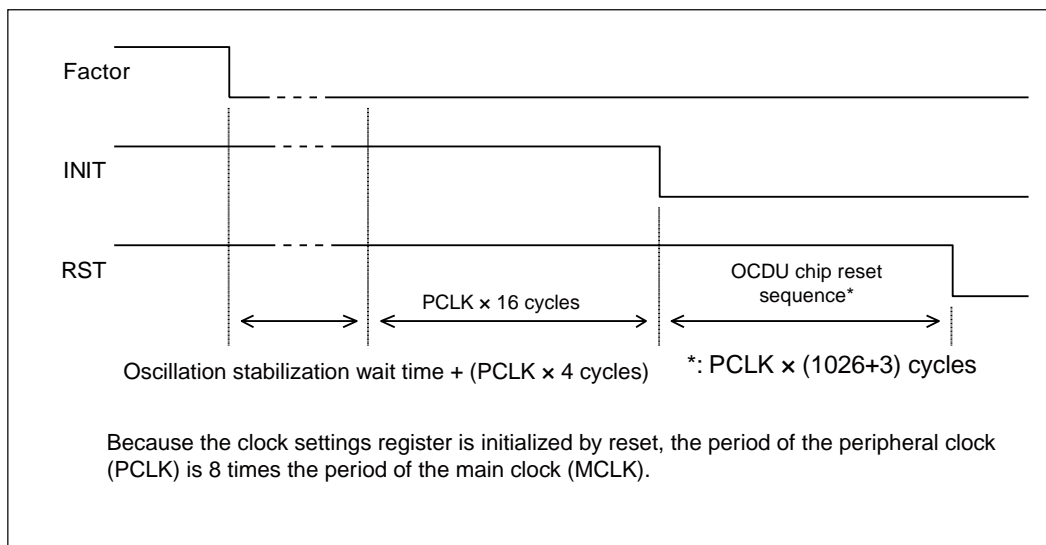
The oscillation stabilization wait time shown in the above table does not include the regulator stabilization wait time and FLASH stabilization wait time associated with the power-on and voltage restore. These stabilization wait time (150µs to 1850µs and maximum 80µs) are needed at power-on reset.

Figure 5-1 Oscillation Stabilization Wait Time for Power-on Reset



The following describes each reset issue sequence after reset factors of this reset have been released.

Figure 5-2 Power-on Reset (SINIT) Sequence



5.4.2. Initialize Reset (INIT)

Initialize reset (INIT) is shown.

If a reset factor of the initialize reset (INIT) level occurs, an initialize reset (INIT) and a reset (RST) will be issued at the same time. This reset is exclusively used for initializing the registers that cannot be initialized by a reset (RST).

While this reset is being issued, all clocks become active. When this reset is issued, a reset (RST) will be always issued at the same time. Although this reset initializes the clock control register, the oscillation of the clock does not change while the main clock (MCLK) is oscillating.

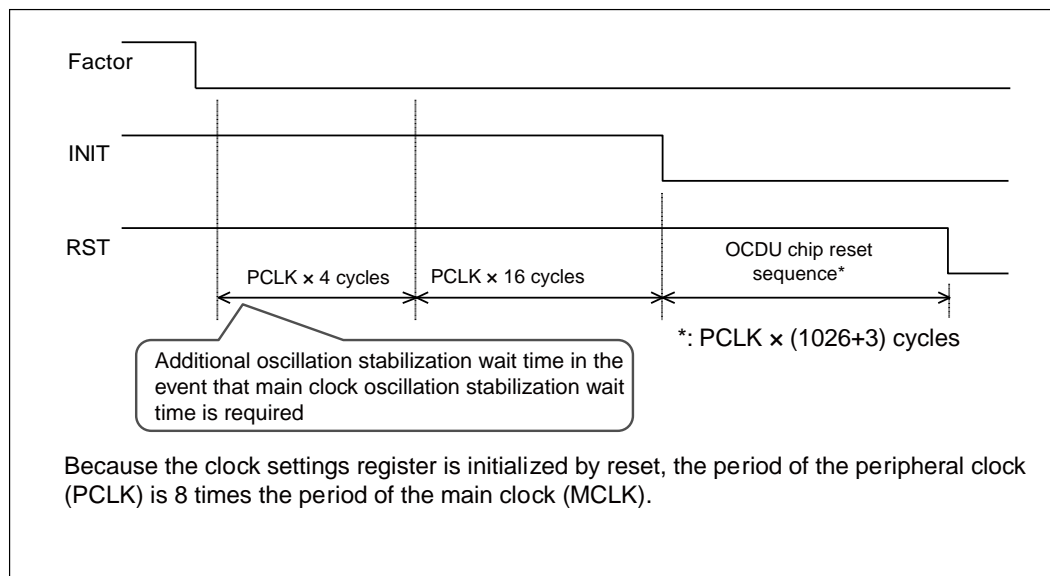
If the main clock is inactive such as in a stop mode, it takes the main clock oscillation stabilization wait time. Since the register of the clock control part will be initialized by a reset, the oscillation stabilization wait time is the default value of this product ($2^{15} \times$ main clock cycle).

Table 5-2 Oscillation Stabilization Wait Time (INIT)

Is main clock oscillation inactive before inputting a reset?	Main clock oscillation stabilization wait time
No	None
Yes	$2^{15} \times$ Main clock cycle

The following describes each reset issue sequence after reset factors of this reset have been released.

Figure 5-3 Initialize Reset (INIT) Sequence



5.4.3. Reset (RST)

The reset (RST) is shown.

If a reset factor that is not the initialize reset (INIT) level occurs, only a reset (RST) will be issued.

This reset is used for initializing the entire hardware except some registers (see "5.1.1. Initialize Reset (INIT)").

While this reset is being issued, all clocks become active.

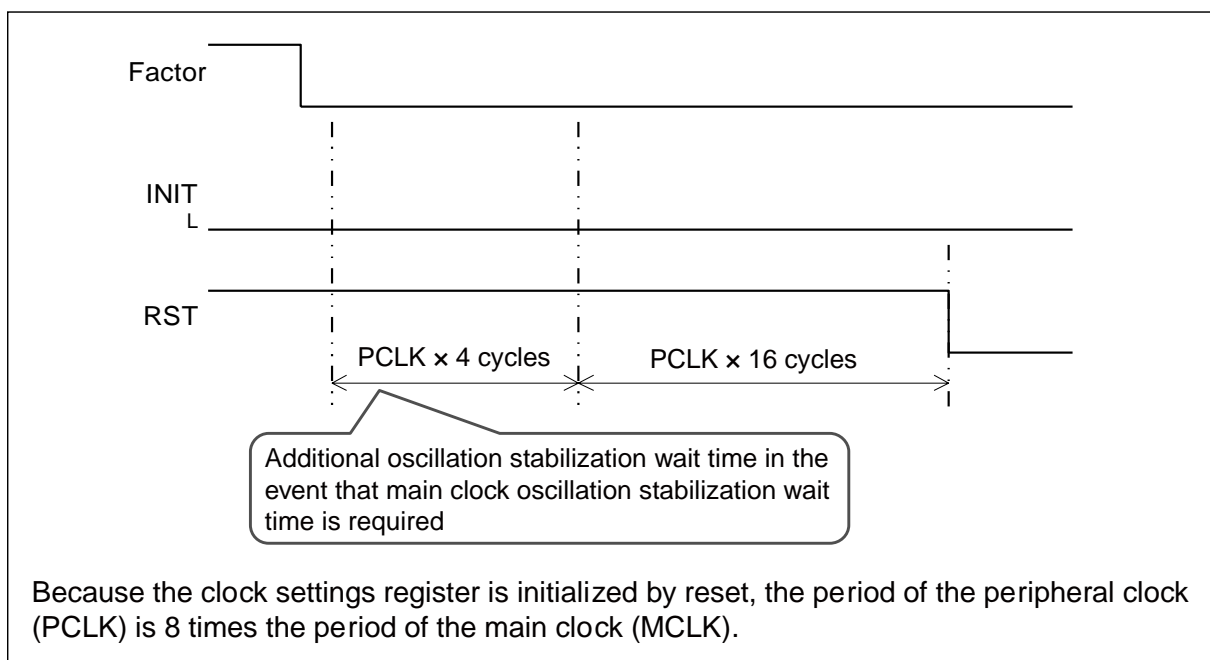
If the main clock is inactive such as in a stop mode before the reset, it takes the main clock oscillation stabilization wait time. Since the register of the clock control part will be initialized by a reset, the oscillation stabilization wait time is the default value of this product ($2^{15} \times$ main clock cycle).

Table 5-3 Oscillation Stabilization Wait Time (RST)

Is main clock oscillation inactive before inputting a reset?	Main clock oscillation stabilization wait time
No	None
Yes	$2^{15} \times$ Main clock cycle

The following describes each reset issue sequence after reset factors of this reset have been released.

Figure 5-4 Reset (RST) Sequence

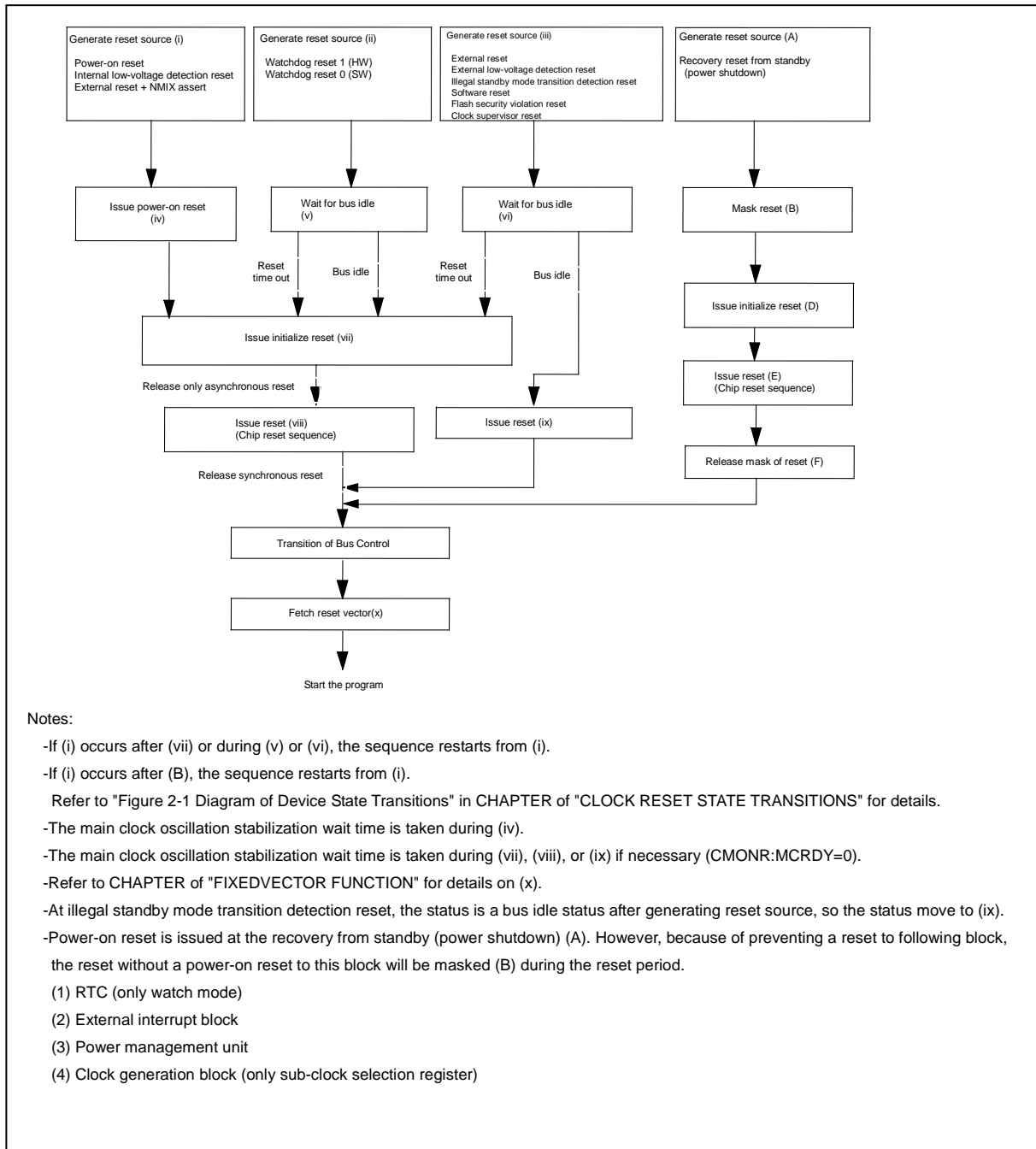


5.5. Reset Sequence

The reset sequence is shown.

This product transits from the initial state to start running the programs and hardware by disappearance of reset factors. A series of operations from this reset to the start of operation is called a reset sequence. This section explains the reset sequence.

Figure 5-5 Reset Sequence



5.5.1. Reset Cycle

The reset cycle is shown.

After the release of reset factors, the reset request is extended during the $4 \times$ peripheral clock (PCLK) cycle. After that, a reset cycle will be maintained by the period of peripheral clock (PCLK) $\times 16$ cycles for each reset level. Thus, the minimum number of issue cycles for each reset is 20 cycles. If it requires the main clock oscillation stabilization wait time, the cycle will be extended for the time required.

5.5.2. Reset Release

The reset release is shown.

Once a reset cycle has completed, each reset will be released and each hardware starts running. Right after the reset release, the mode control circuit functions as a bus master of on-chip bus.

5.5.3. Operating Mode Fix

Operating mode fix is shown.

The mode control circuit as a bus master will notify the operating mode, which was determined based on the mode setting value acquired, to each hardware component. Then, it will release the bus control of on-chip bus.

5.5.4. Transition of Bus Control

Transition of bus control is shown.

After the mode control circuit releases the bus control of on-chip bus, the CPU acquires the bus control and starts running bus operations by the CPU.

5.5.5. Reset Vector Fetch

Reset vector fetch is shown.

After the reset release, the CPU starts fetching the reset vector (at 0x000FFFFC).

After CPU acquires the bus control, the CPU accesses the reset vector through on-chip bus and retrieves the acquired reset vector to the PC to start running programs.

5.5.6. Reset and Forced Break

Reset and forced break are shown.

If a forced break has occurred during the reset release, it accepts the forced break upon completion of the reset vector fetch. Thus, the PC value by the reset vector acquired will be saved at the emulator space side (stored at the E_BPCHR,E_BPCLR register).

5.6. Notes

Notes are shown.

During return from standby watch mode (power shut-down) and standby stop mode (power shut-down), an internal reset is issued. Therefore any reset source without power-on reset, internal low-voltage detection reset, reset by simultaneous assert of RSTX and NMIX will not be accepted.

CHAPTER : DMA CONTROLLER (DMAC)

This chapter explains the DMA controller (DMAC).

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. DMA Usage Examples

1. Overview

This section explains the overview of the DMA controller (DMAC).

DMAC is the module which performs the DMA (Direct Memory Access) transfer. DMA transfer controlled by this module enables the high speed transfer of variety of data without any interventions of a CPU, thus increases the system performance.

2. Features

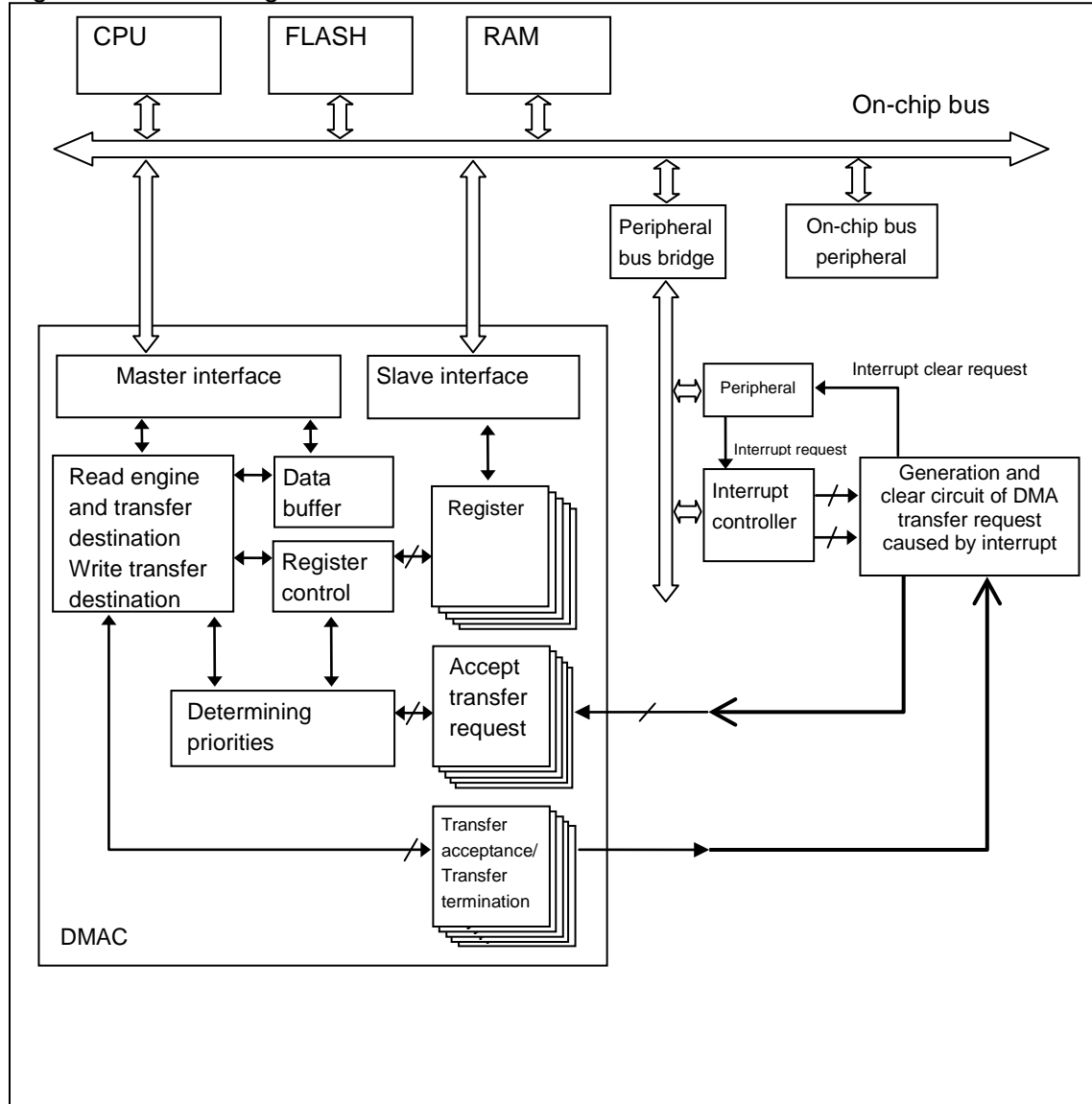
This section explains the features of the DMA controller (DMAC).

- Channels : 16 channels
- Address space : 32-bit address space (4 GB)
- Transfer mode : Block/burst transfer
- Address update : Increment/Decrement/Fixed (Address increment/decrement range : 1, 2, 4)
- Transfer size : 8-bits, 16-bits, 32-bits
- Block size : 1 to 16
- Transfer count : 1 to 65535
- Transfer request :
 - Software transfer requests
 - Transfer requests by peripheral interrupt (for the transfer request by peripheral interrupt, you should select interrupt by channels. See "CHAPTER: GENERATION AND CLEARING OF DMA TRANSFER REQUESTS".)
 - Transfer stop request : Transfer stop request by interrupts
- Reload function : All channels can be specified for reload
 - Transfer source address reload
 - Transfer destination address reload
 - Transfer count reload
- Priority :
 - Fixed (ch.0 > ch.1 > ch.2 > ch.3 > ch.4 > ch.5 > ch.6 > ch.7 > ch.8 > ch.9 > ch.10 > ch.11 > ch.12 > ch.13 > ch.14 > ch.15)
 - Round robin
- Interrupt request : Normal completion interrupt requests, abnormal completion interrupt requests, and transfer suspend interrupt requests by transfer stop requests can be generated

3. Configuration

This section explains the block configuration of the DMA controller (DMAC).

Figure 3-1 Block Diagram



4. Registers

This section explains registers of the DMA controller (DMAC).

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0C00	DCCR0				DMA channel control register 0
0x0C04	DCSR0		DTCR0		DMA channel status register 0 DMA transfer count register 0
0x0C08	DSAR0				DMA transfer source address register 0
0x0C0C	DDAR0				DMA transfer destination address register 0
0x0C10	DCCR1				DMA channel control register 1
0x0C14	DCSR1		DTCR1		DMA channel status register 1 DMA transfer count register 1
0x0C18	DSAR1				DMA transfer source address register 1
0x0C1C	DDAR1				DMA transfer destination address register 1
0x0C20	DCCR2				DMA channel control register 2
0x0C24	DCSR2		DTCR2		DMA channel status register 2 DMA transfer count register 2
0x0C28	DSAR2				DMA transfer source address register 2
0x0C2C	DDAR2				DMA transfer destination address register 2
0x0C30	DCCR3				DMA channel control register 3
0x0C34	DCSR3		DTCR3		DMA channel status register 3 DMA transfer count register 3
0x0C38	DSAR3				DMA transfer source address register 3
0x0C3C	DDAR3				DMA transfer destination address register 3
0x0C40	DCCR4				DMA channel control register 4
0x0C44	DCSR4		DTCR4		DMA channel status register 4 DMA transfer count register 4
0x0C48	DSAR4				DMA transfer source address register 4
0x0C4C	DDAR4				DMA transfer destination address register 4
0x0C50	DCCR5				DMA channel control register 5
0x0C54	DCSR5		DTCR5		DMA channel status register 5 DMA transfer count register 5
0x0C58	DSAR5				DMA transfer source address register 5

Address	Registers				Register function
	+0	+1	+2	+3	
0x0C5C	DDAR5				DMA transfer destination address register 5
0x0C60	DCCR6				DMA channel control register 6
0x0C64	DCSR6		DTCR6		DMA channel status register 6 DMA transfer count register 6
0x0C68	DSAR6				DMA transfer source address register 6
0x0C6C	DDAR6				DMA transfer destination address register 6
0x0C70	DCCR7				DMA channel control register 7
0x0C74	DCSR7		DTCR7		DMA channel status register 7 DMA transfer count register 7
0x0C78	DSAR7				DMA transfer source address register 7
0x0C7C	DDAR7				DMA transfer destination address register 7
0x0C80	DCCR8				DMA channel control register 8
0x0C84	DCSR8		DTCR8		DMA channel status register 8 DMA transfer count register 8
0x0C88	DSAR8				DMA transfer source address register 8
0x0C8C	DDAR8				DMA transfer destination address register 8
0x0C90	DCCR9				DMA channel control register 9
0x0C94	DCSR9		DTCR9		DMA channel status register 9 DMA transfer count register 9
0x0C98	DSAR9				DMA transfer source address register 9
0x0C9C	DDAR9				DMA transfer destination address register 9
0x0CA0	DCCR10				DMA channel control register 10
0x0CA4	DCSR10		DTCR10		DMA channel status register 10 DMA transfer count register 10
0x0CA8	DSAR10				DMA transfer source address register 10
0x0CAC	DDAR10				DMA transfer destination address register 10
0x0CB0	DCCR11				DMA channel control register 11
0x0CB4	DCSR11		DTCR11		DMA channel status register 11 DMA transfer count register 11
0x0CB8	DSAR11				DMA transfer source address register 11
0x0CBC	DDAR11				DMA transfer destination address register 11
0x0CC0	DCCR12				DMA channel control register 12

Address	Registers				Register function
	+0	+1	+2	+3	
0x0CC4	DCSR12		DTCR12		DMA channel status register 12 DMA transfer count register 12
0x0CC8	DSAR12				DMA transfer source address register 12
0x0CCC	DDAR12				DMA transfer destination address register 12
0x0CD0	DCCR13				DMA channel control register 13
0x0CD4	DCSR13		DTCR13		DMA channel status register 13 DMA transfer count register 13
0x0CD8	DSAR13				DMA transfer source address register 13
0x0CDC	DDAR13				DMA transfer destination address register 13
0x0CE0	DCCR14				DMA channel control register 14
0x0CE4	DCSR14		DTCR14		DMA channel status register 14 DMA transfer count register 14
0x0CE8	DSAR14				DMA transfer source address register 14
0x0CEC	DDAR14				DMA transfer destination address register 14
0x0CF0	DCCR15				DMA channel control register 15
0x0CF4	DCSR15		DTCR15		DMA channel status register 15 DMA transfer count register 15
0x0CF8	DSAR15				DMA transfer source address register 15
0x0CFC	DDAR15				DMA transfer destination address register 15
0x0DF4	Reserved	Reserved	DNMIR	DILVR	DMA transfer suppression NMI flag register DMA transfer suppression interrupt level register
0x0DF8	DMACR				DMA control register
0x0DFC	Reserved				Reserved

4.1. DMA Control Register: DMACR (DMA Control Register)

This section explains the DMA control register (DMACR).

The DMA control register is a 32-bit register to control the entire DMAC (all channels). This register must be accessed as a 32-bit data.

■ DMACR : Address 0DF8_H (Access: Word)

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	DME	Reserved						
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0
	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0
	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	AT	Reserved						
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

[bit31] DME (DMA Enable) : DMA operation enabled

This bit controls the operation of the entire DMAC. When this bit is "0", a DMA transfer will not be performed even if operation of each channel is enabled. When this bit is "1", operations according to the settings for each channel are performed.

If "0" is written while a DMA transfer is in progress, the transfer is stopped in blocks specified in DCCRn:BLK.

DME	DMA operation enable
0	DMA operation disabled (Initial value)
1	DMA operation enabled

[bit30 to bit16] Reserved

Always write "0" to these bits. The read value is "0".

[bit15] AT (Arbitration Type) : Priority setting

This bit configures how to determine priority for each channel. If the priority is set to "fixed" (AT = 0), ascending order, ch.0 > ch.1 > ch.2 > ch.3, is taken. If the priority is set to "round robin" (AT = 1), DMAC makes the priority of the channel which started the transfer the lowest and raises the priority of following channels one by one. The decision on priority is made on each transfer of a block unit specified in DCCRn:BLK regardless of the priority setting.

AT	Priority setting
0	Fixed (initial value)
1	Round robin

[bit14 to bit0] Reserved

Always write "0" to these bits. The read value is "0".

4.2. DMA Channel Control Register 0 to 15: DCCR0 to 15 (DMA Channel Control Register 0 to 15)

This section explains the bit configuration for DMA channel control register 0 to 15 (DCCR0 to 15).

DMA channel control registers are 32-bit registers to control the operation of DMAC channels, which exists independently for each channel. This register must be accessed as a 32-bit data.

■ DCCR0 to 15 : Address BASE + 0000_H (Access: Word)

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	CE	Reserved				AIE	SIE	NIE
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W

	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	Reserved		RS[1:0]	Reserved		TM[1:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R/W	R/W	R0,W0	R0,W0	R/W	R/W

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	ST	SAR	SAC[1:0]		DT	DAR	DAC[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TCR	Reserved	TS[1:0]		BLK[3:0]			
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W

[bit31] CE (Channel Enable) : Channel operation enabled

This bit controls the operation of the channels. If the request source is set to "software", writing "1" to this bit starts a DMA transfer according to the configuration. In this case, the CE bit is automatically cleared when the transfer according to the transfer request completed. If the request source is other than software, writing "1" to this bit makes channel operation enabled. After enabling operation, a DMA transfer starts when the corresponding transfer request is detected. In case of a request other than software, the CE bit will not be automatically cleared if transfer count reload (DCCRn:TCR) is specified. When transfer count reload is disabled, the CE bit will be cleared when all transfers are finished. If "0" is written while the operation is going on regardless of the request source, stop transfer in blocks specified in DCCRn:BLK. When writing "1" again and detecting a new transfer request, the operation restarts.

CE	Channel operation enabled
0	Disabled (initial value)
1	Enabled

[bit30 to bit27] Reserved

Always write "0" to these bits. The read value is "0".

[bit26] AIE (Abnormal completion Interrupt Enable) : Abnormal completion interrupt enabled

This bit controls the generation of interrupts when setting the prohibited values to the DMA channel control register (DCCR). The items not allowed to set to registers are listed below.

- Transfer mode : DCCRn:TM = 10_B
- Transfer source address count : DCCRn:SAC = 10_B
- Transfer destination address count : DCCRn:DAC = 10_B
- Transfer size : DCCRn:TS = 11_B
- Demand transfer mode by software request : DCCRn:RS = 00_B and DCCRn:TM = 11_B

As for the interrupt factor, refer to the status register (DCSRn).

AIE	Abnormal completion interrupt enabled
0	Disabled (initial value)
1	Enabled

[bit25] SIE (Stop Interrupt Enable) : Transfer suspend interrupt enabled by transfer stop requests

This bit controls the generation of interrupts when a DMA transfer is suspended by a transfer stop request from the transfer request source. As for the interrupt factor, refer to the status register (DCSRn).

SIE	Transfer suspend interrupt enabled
0	Disabled (initial value)
1	Enabled

[bit24] NIE (Normal completion Interrupt Enable) : Normal completion interrupt enabled

This bit controls the generation of interrupts when completing DMA transfers successfully. After completing transfers as many times as set by transfer count (DTCRn:DTC) or when writing "1" to the corresponding channel's DCCRn:CE bit at the time the transfer count is "0", the operation will complete normally. As for the interrupt factor, see the status register (DCSRn).

NIE	Normal completion interrupt enabled
0	Disabled (initial value)
1	Enabled

[bit23 , bit22] Reserved

Always write "0" to these bits. The read value is "0".

[bit21, bit20] RS[1:0] (Request Source) : DMA transfer request source

These bits select the transfer request source for the channel.

RS[1:0]	DMA transfer request source
00	Software (initial value)
01	Interrupts
10	Reserved (setting is prohibited)
11	Reserved (setting is prohibited)

[bit19, bit18] Reserved

Always write "0" to these bits. The read value is "0".

[bit17, bit16] TM[1:0] (Transfer Mode) : Transfer mode

These bits specify the DMA transfer mode.

TM[1:0]	Transfer mode
00	Block transfer (initial value)
01	Burst transfer
10	Reserved (setting is prohibited)
11	Reserved (setting is prohibited)

[bit15] ST (Source Type) : Transfer source type

The setting values are different depending on the combinations of DMA transfer request source (DCCR:RS[1:0]), transfer source address (DSAR), and transfer destination address (DDAR). As for the setting, see "■ Setting the ST Bit (Transfer source type) and DT Bit (Transfer destination type)".

ST	Transfer source type
0	See "■ Setting the ST Bit (Transfer source type) and DT Bit (Transfer destination type)".
1	

[bit14] SAR (Source Address Reload) : Transfer source address reload

This bit specifies the transfer source address register reload. When specifying a reload, the transfer source address register value is returned to the initial value at the end of the transfer. When disabling a reload, the transfer source address register will point to the next access address to the last address at the end of the transfer.

SAR	Transfer Source address reload specified
0	Reload disabled (initial value)
1	Reload

[bit13, bit12] SAC[1:0] (Source Address Count) : Transfer source address count

These bits specify the address update once for each transfer of the transfer source address. The update values when specifying "increment/decrement" will be one of the values, 1, 2, 4 depending on the transfer size (DCCRn:TS).

SAC[1:0]	Transfer Source address count
00	Address increment (initial value)
01	Address decrement
10	Reserved (setting is prohibited)
11	Address fixed

[bit11] DT (Destination Type) : Transfer destination type

The setting values are different depending on the combinations of DMA transfer request source (DCCR.RS[1:0]), transfer source address (DSAR), and transfer destination address (DDAR). As for the setting, see "■ Setting the ST Bit (Transfer source type) and DT Bit (Transfer destination type)".

DT	Transfer destination type
0	See "■ Setting the ST Bit (Transfer source type) and DT Bit (Transfer destination type)".
1	

[bit10] DAR (Destination Address Reload) : Transfer destination address reload

This bit specifies the transfer destination address register reload. When specifying a reload, the transfer destination address register value is returned to the initial value at the end of the transfer. When disabling a reload, the transfer destination address register will point to the next access address to the last address at the end of the transfer.

DAR	Transfer destination address reload specified
0	Reload disabled (initial value)
1	Reload

[bit9, bit8] DAC[1:0] (Destination Address Count) : Transfer destination address count

These bits specify the address update once for each transfer of the transfer destination address. The update values when specifying "increment/decrement" will be one of the values, 1, 2, 4 depending on the transfer size (DCCRn:TS).

DAC[1:0]	Transfer destination address count
00	Address increment (initial value)
01	Address decrement
10	Reserved (setting is prohibited)
11	Address fixed

[bit7] TCR (Transfer Count Reload) : Transfer count reload

This bit specifies the transfer count register reload.

When specifying a reload, the transfer count register value is returned to the initial value at the end of the transfer. If the transfer request source is set other than "software", DCCRn:CE bit will not be cleared at the end of the transfer and the operation will go into the transfer request wait state. When disabling a reload, the transfer count register value at the end of the transfer will point to "0". In this case, DCCRn:CE bit will be cleared at the end of the transfer regardless of the transfer request source.

TCR	Transfer count reload
0	Reload disabled (initial value)
1	Reload

[bit6] Reserved

Always write "0" to this bit. The read value is "0".

[bit5, bit4] TS[1:0] (Transfer Size) : Transfer size

These bits specify the transfer size. DMA transfers will be performed once with the bit width specified here.

TS[1:0]	Transfer size
00	8-bit :byte (initial value)
01	16-bit :halfword
10	32-bit :word
11	Reserved (setting is prohibited)

Set values to DSARn and DDARn registers so as not to cause a misalignment for the transfer size specified in these bits.

[bit3 to bit0] BLK[3:0] (Block Size) : Block size

These bits specify the block size. 1 block transfer will be repeated for the number of blocks of the transfer size specified with DCCRn:TS bit.

BLK[3:0]	Block size
0000	Once (initial value)
0001	Twice
0010	3 times
0011	4 times
0100	5 times
0101	6 times
0110	7 times
0111	8 times
1000	9 times
1001	10 times
1010	11 times
1011	12 times
1100	13 times
1101	14 times
1110	15 times
1111	16 times

4.3. DMA Channel Status Register 0 to 15 : DCSR0 to 15: (DMA Channel Status Register 0 to 15)

This section explains the bit configuration for DMA channel status register 0 to 15 (DCSR0 to 15).

These registers are 16-bit registers to indicate the status for each DMAC channel, which exist independently for each channel. These registers must be accessed as a 16-bit data.

■ DCSR0 to 15: Address BASE + 0004_H (Access: Half-word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	CA	Reserved						
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					AC	SP	NC
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R,W	R,W	R,W

[bit15] CA (Channel Active) : Channel active

This bit indicates the operation of the channels. Writing "1" to the corresponding DCCRn:CE bit for the channel makes it in the operating state. Completing transfers for as many times as set transfer count or writing "0" to DCCRn:CE makes the operation stop.

Writing this bit is ignored.

CA	Channel operating state
0	Stop state (initial value)
1	Channel operating

[bit14 to bit3] Reserved

Always write "0" to these bits. The read value is "0".

[bit2] AC (Abnormal Completion) : Abnormal completion state

This bit indicates that a prohibited value has been set to the DMA channel control register (DCCR). The items not allowed to set to registers are listed below.

- Transfer mode : DCCRn:TM = 10_B
- Transfer source address count : DCCRn:SAC = 10_B
- Transfer destination address count : DCCRn:DAC = 10_B
- Transfer size : DCCRn:TS = 11_B
- Demand transfer mode by software request : DCCRn:RS = 00_B and DCCRn:TM = 11_B

When having allowed the abnormal completion interrupt (DCCRn:AIE), writing "0" to this bit clears the interrupt. Writing "1" to this bit is ignored.

Make sure to clear this bit before enabling DMA operation. This bit will not be cleared automatically.

AC	Abnormal completion state
0	Abnormal completion undetected (initial value)
1	Abnormal completion

[bit1] SP (Stop) : Transfer suspension state by the transfer stop request

This bit indicates that a DMA transfer has been suspended by a transfer stop request from the transfer request source. When having allowed the transfer suspension interrupt (DCCRn:SIE), writing "0" to this bit clears the interrupt. Writing "1" to this bit is ignored.

Make sure to clear this bit before enabling DMA operation. This bit will not be cleared automatically.

SP	Transfer suspend state
0	Transfer suspend undetected (initial value)
1	Transfer suspend

[bit0] NC (Normal Completion) : Normal completion state

This bit indicates that DMA transfer has been completed successfully. After completing transfers as many times as set by transfer count or when writing "1" to the corresponding channel's "DCCRn:CE" bit at the time the transfer count is "0", the operation will complete normally. When having allowed the normal completion interrupt (DCCRn:NIE), writing "0" to this bit clears the interrupt. Writing "1" to this bit is ignored.

Make sure to clear this bit before enabling DMA operation. This bit will not be cleared automatically.

NC	Normal completion state
0	Normal completion undetected (initial value)
1	Normal completion

4.4. DMA Transfer Count Register 0 to 15 : DTCR0 to 15: (DMA Transfer Count Register 0 to 15)

This section explains the bit configuration for DMA transfer count register 0 to 15 (DTCR0 to 15).

These registers are 16-bit registers to indicate the transfer count for each DMAC channel, which exist independently for each channel. These registers must be accessed as a 16-bit data.

■ DTCR0 to 15: Address BASE + 0006_H (Access: Half-word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	DTC[15:8]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DTC[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

[bit15 to bit0] DTC (DMA Transfer Count) : DMA transfer count

These registers indicate the number of transfer times. DMAC decreases a transefer count at the end of each block transfer and stops the transfer when the transfer count becomes "0". If "0" is set for transfer count, transfer will not be performed. Also, the dedicated reload register is provided. If DCCRn:TCR is "1", the value is returned to the initial value after data transfer.

4.5. DMA Transfer Source Register 0 to 15 : DSAR0 to 15: (DMA Source Address Register 0 to 15)

This section explains the bit configuration for DMA transfer source register 0 to 15 (DSAR0 to 15).

These registers are 32-bit registers to indicate the transfer source address of each DMAC channel, and each channel has these registers separately. This register must be accessed as a 32-bit data.

■ DSAR0 to 15: Address BASE + 0008_H (Access: Word)

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	DSA[31:24]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	DSA[23:16]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	DSA[15:8]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DSA[7:0]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

[bit31 to bit0] DSA[31:0] (DMA Source Address) : DMA transfer source address

These registers indicate the transfer source address. If an increment or a decrement is set by DCCRn:SAC, the address is updated according to the transfer size (DCCRn:TS). Also, the dedicated reload register is provided. If DCCRn:SAR is "1", the value is returned to the initial value after data transfer.

Set a value in these registers not to cause a misalignment against the transfer size to be set by DCCRn:TS.

If the DMA transfer request source has a peripheral interrupt (DCCR:RS[1:0]=01), at least either the transfer source address (DSAR) or the transfer destination address (DDAR) must be within the address range of peripheral under control of 16-bit peripheral bus or 32-bit peripheral bus. For details, see "■ Setting the ST

Bit (Transfer source type) and DT Bit (Transfer destination type)".

4.6. DMA Transfer Destination Register 0 to 15 : DDAR0 to 15 (DMA Destination Address Register 0 to 15)

This section explains the bit configuration for DMA transfer destination register 0 to 15 (DDAR0 to 15).

These registers are 32-bit registers to indicate the transfer destination address of each DMAC channel, and each channel has these registers separately. These registers must be accessed as a 32-bit data.

■ DDAR0 to 15: Address BASE + 000C_H (Access: Word)

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	DDA[31:24]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	DDA[23:16]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	DDA[15:8]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DDA[7:0]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

[bit 31 to bit0] DDA[31:0] (DMA Destination Address) : DMA transfer destination address

These registers indicate the transfer destination address. If an increment or a decrement is set by DCCRn:DAC, the address is updated according to the transfer size (DCCRn:TS). Also, the dedicated reload register is provided. If DCCRn:DAR is "1", the value is returned to the initial value after data transfer.

Set a value in these registers not to cause a misalignment against the transfer size to be set by DCCRn:TS.

If the DMA transfer request source has a peripheral interrupt (DCCRn:RS[1:0]=01), at least either the transfer source address (DSAR) or the transfer destination address (DDAR) must be within the address range of peripheral under control of 16-bit peripheral bus or 32-bit peripheral bus. For details, see "■ Setting the ST

Bit (Transfer source type) and DT Bit (Transfer destination type)".

4.7. DMA Transfer Suppression NMI Flag Register : DNMIIR (DMA-halt by NMI Register)

This section explains the bit configuration for DMA transfer suppression NMI flag register (DNMIIR).

This register is 8-bit register to suppress DMA transfer by the user NMI. This register must be accessed as a 8-bit data.

■ DNMIIR: Address 0DF6_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	NMIH	Reserved						NMIHD
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R/W

[bit7] NMIH (NMI Halt) : DMA suppression flag (by NMI factor)

If the NMIHD bit is "0", this flag shows an occurrence of the user NMI request. The "H" level of NMI is detected, and this bit is set to "1". To restart DMA transfer, set this bit to "0".

Writing "1" to this bit is ignored.

NMIH	DMA suppression flag
0	DMA transfer is not suppressed. (Initial value)
1	The DMA transfer has been stopped by user NMI.

[bit6 to bit1] Reserved

Always write "0" to these bits. The read value is "0".

[bit0] NMIHD (NMI Halt Disable) : DMA suppression control (by NMI factor)

The control bit that stops DMA transfer if a user NMI request is generated.

If an NMI occurs when this bit is "0", the DMAC does not restart a new DMA transfer. During DMA transfer, the controller stops the current DMA transfer when a block unit transfer has completed.

NMIHD	DMA suppression control
0	Stops the DMA transfer by the user NMI. (initial value)
1	Does not stop the DMA transfer by the user NMI.

4.8. DMA Transfer Suppression Level Register : DILVR (DMA-halt by Interrupt Level Register)

This section explains the bit configuration for DMA transfer suppression level register (DILVR).

This register is 8-bit register to control the DMA transfer suppression by peripheral interrupts. This register must be accessed as a 8-bit data.

■ DILVR: Address 0DF7_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			LVL4	LVL[3:0]			
Initial value	0	0	0	1	1	1	1	1
Attribute	R0,W0	R0,W0	R0,W0	R1,WX	R/W	R/W	R/W	R/W

[bit7 to bit5] Reserved

Always write "0" to these bits. The read value is "0".

[bit4 to bit0] LVL[4:0] (Level) : DMA suppression interrupt level

These bits set an interrupt level for suppression of DMA transfer. If a peripheral interrupt having an interrupt level higher than the one specified by this register occurs, the DMA transfer is suppressed. LVL4 is fixed to "1", but LVL[3:0] can be set to any level.

LVL[4:0]	DMA suppression control
11111	Suppresses the DMA transfer when any peripheral interrupt request is issued. (initial value)
11110	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1E _H is issued.
11101	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1D _H is issued.
11100	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1C _H is issued.
11011	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1B _H is issued.
11010	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1A _H is issued.
11001	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 19 _H is issued.
11000	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 18 _H is issued.
10111	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 17 _H is issued.
10110	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 16 _H is issued.

LVL[4:0]	DMA suppression control
10101	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 15 _H is issued.
10100	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 14 _H is issued.
10011	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 13 _H is issued.
10010	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 12 _H is issued.
10001	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 11 _H is issued.
10000	Does not suppress the DMA transfer when a peripheral interrupt request is issued.

5. Operation

This section explains the operation of the DMA controller (DMAC).

■ Configuration

The following explains the setting items common to all channels and the items to be set separately for each channel.

● Common Items for All Channels

“5.1 DMA Operation Enable” explains the register settings for the entire DMAC control.

5.1. DMA Operation Enable

This section explains the DMA operation enable of the DMA controller (DMAC).

The entire DMAC operation can be controlled using the DMACR:DME.

- DMA operation disabled (DMACR:DME = 0)
- DMA operation enabled (DMACR:DME = 1)

■ Channel Priority

A channel priority can be set by the DMACR:AT.

- Fixed priority (DMACR:AT = 0)
- Round robin (DMACR:AT = 1)

■ DMA Transfer Suppression Setting for Interrupt Occurrence

The DMA transfer suppression control during user NMI occurrence can be set by the DNMIR:NMIHD.

- Stops DMA transfer by the user NMI. (DNMIR:NMIHD = 0)
- Does not stop DMA transfer by the user NMI. (DNMIR:NMIHD = 1)

Also, an interrupt level, which precedes the DMA transfer when an interrupt occurs, can be set by DILVR:LVL. Allowed interrupt levels are 0x1F to 0x10.

5.2. Separate Items for Each Channel

This section explains the separate items for each channel of the DMA controller (DMAC).

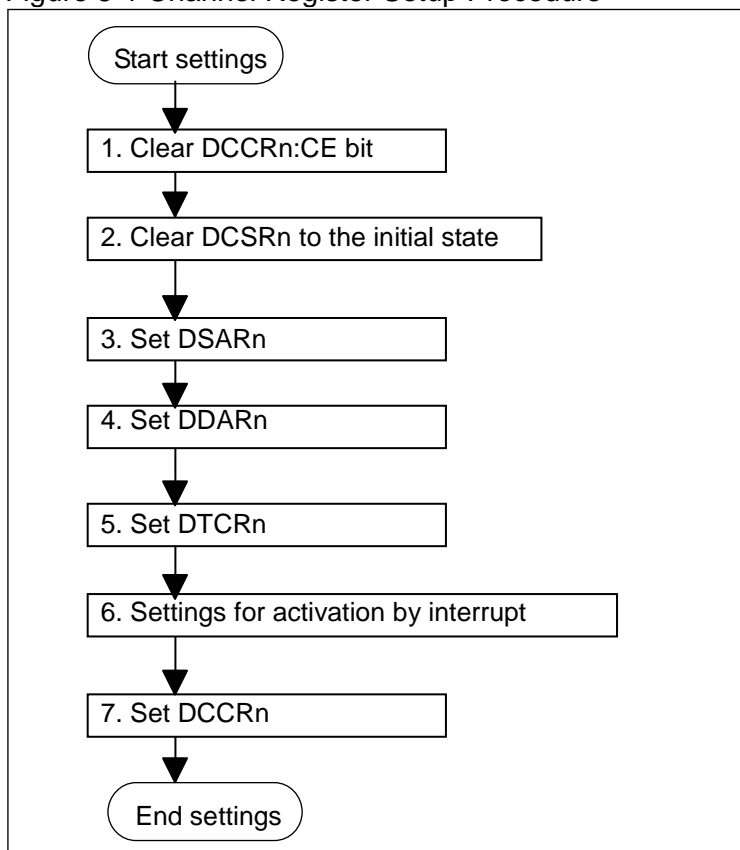
The following explains both the items to be set separately for each channel and the register setup procedure.

■ Register Setup Procedure

The channel registers must be set in the following procedure. When you set the DCCRn:CE bit to "1", be sure to set the DTCRn to 1 or a higher value.

1. Clear the DCCRn:CE bit to disable the channel operation.
2. Clear each bit of DCSRn register to initialize the channel status flag.
3. Set the transfer source address (to be used when the transfer starts) in the DSARn register.
4. Set the transfer destination address (to be used when the transfer starts) in the DDARn register.
5. Set the transfer count in the DTCRn register. This count must be 1 or a larger value.
6. If transfer is started by a peripheral interrupt, the occurrence of each peripheral interrupt must be enabled and the ICSEL and IORR registers must be set. (See the "CHAPTER: GENERATION AND CLEARING OF DMA TRANSFER REQUESTS" about the ICSEL and IORR registers.)
7. Set the DCCRn register. During this time, the channel operation is enabled when the DCCRn:CE bit is set.

Figure 5-1 Channel Register Setup Procedure



■ Transfer Source Address and the Transfer Destination Address Setting

Set the transfer source address (to be used when the transfer starts) using the DSARn:DSA.

Set the transfer destination address (to be used when the transfer starts) using the DDARn:DDA.

Align the transfer source and destination addresses based on the transfer size (DCCRn:TS), and ignore the lower 1 bit or lower 2 bits for 16-bit or 32-bit transfer size respectively.

■ Transfer Count Setting

Set the number of times of block transfer (repeated to the end of transfer) using the DTCRn:DTC. The transfer count can be 1 to 65535 times. The DMAC transfers data (1 block data), whose length in bytes is set by the transfer size and block size (see "■ Transfer Size and Block Size Setting") for the specified number of times.

■ Channel Operation Enable

Set the channel operation control using the DCCRn:CE.

- Disable the channel operation (DCCRn:CE = 0)
- Enable the channel operation (DCCRn:CE = 1)

When the software is selected at the transfer request source and when the DCCRn:CE bit is set, the channel operation is enabled and data transfer is started.

■ Interrupt Permission Setting

Enable an interrupt during abnormal completion, using the DCCRn:AIE.

- Disable an abnormal completion interrupt (DCCRn:AIE = 0)
- Enable an abnormal completion interrupt (DCCRn:AIE = 1)

Using the DCCRn:SIE, enable an interrupt to occur if data transfer is suspended by a transfer stop request.

- Disable a transfer suspend interrupt during detection of transfer stop request (DCCRn:SIE = 0)
- Enable a transfer suspend interrupt during detection of transfer stop request (DCCRn:SIE = 1)

Enable an interrupt during normal completion, using the DCCRn:NIE.

- Disable a normal completion interrupt (DCCRn:NIE = 0)
- Enable a normal completion interrupt (DCCRn:NIE = 1)

■ Transfer Request Source setting

Set the transfer request source to accept a transfer request using the DCCRn:RS.

- Request by software (DCCRn:RS = 00)
- Request by an interrupt (DCCRn:RS = 01)

■ Transfer Mode Setting

Set the DMA transfer mode using the DCCRn:TM.

- Block transfer (DCCRn:TM = 00)
- Burst transfer (DCCRn:TM = 01)

■ **Setting the ST Bit (Transfer source type) and DT Bit (Transfer destination type)**

Set them by following the table definition below. The DMA transfer is not supported in combination (5).

Table 5-1 ST Bit (Transfer Source Type) and DT Bit (Transfer Destination Type) Setting

	Combination of transfer request source, transfer source, and transfer destination			DMA transfer support	ST and DT bit setting
	Transfer request source (DCCRn:RS[1:0])	Transfer source (DSAR)	Transfer destination (DDAR)		
(1)	Request by software (DCCRn:RS[1:0] = 00)	Any combination		Supported	ST= 0, DT= 0
(2)	Peripheral interrupt (DCCRn:RS[1:0] = 01)	●	□	Supported	ST= 1, DT= 0
(3)		□	●	Supported	ST= 0, DT= 1
(4)		●	●	Supported	ST= 0, DT= 1
(5)		□	□	Not supported	-

● : Address range of the peripheral under control of 16-bit peripheral bus or 32-bit peripheral bus

□ : Other address range

If the ST and DT bits are set in a combination other than above, the interrupt may not be cleared automatically after occurrence of the DMA transfer request.

■ **Transfer Address Reload Setting**

Using the DCCRn:SAR, set the reload control of transfer source address at the end of transfer.

- The transfer source address is not reloaded after the transfer. (The next access address after the last address is shown.) (DCCRn:SAR=0)
- The transfer source address is returned to the initial value at the end of transfer. (DCCRn:SAR=1)

Using the DCCRn:DAR, set the reload control of transfer destination address at the end of transfer.

- The transfer destination address is not reloaded after the transfer. (The next access address after the last address is shown.) (DCCRn:DAR=0)
- The transfer destination address is returned to the initial value at the end of transfer. (DCCRn:DAR=1)

■ **Transfer Address Update Setting**

Using the DCCRn:SAC, set the updating of transfer source address for DMA transfer.

- Address is increased. (DCCRn:SAC = 00)
- Address is decreased. (DCCRn:SAC = 01)
- Address is fixed. (DCCRn:SAC = 11)

Using the DCCRn:DAC, set the updating of transfer destination address for DMA transfer.

- Address is increased. (DCCRn:DAC = 00)
- Address is decreased. (DCCRn:DAC = 01)
- Address is fixed. (DCCRn:DAC = 11)

■ Transfer Count Reload Setting

Using the DCCRn:TCR, set the reload control of transfer count at the end of transfer.

- The transfer count is not reloaded after the transfer. (After the normal completion of transfer, the transfer count is set to 0.) (DCCRn:TCR=0)
- The transfer count is returned to the initial value at the end of transfer. (DCCRn:TCR=1)

■ Transfer Size and Block Size Setting

To set a transfer unit for DMA transfer (the byte count to be transferred as 1 block), set the transfer size and block size.

Using the DCCRn:TS, set the size of data to be sent by a single DMA transfer (8-bit/16-bit/32-bit).

- 8-bit (DCCRn:TS = 00)
- 16-bit (DCCRn:TS = 01)
- 32-bit (DCCRn:TS = 10)

Using the DCCRn:BLK, set the DMA transfer count for 1-block data transfer. The block size can be 1 to 16 times. In the 1-block transfer, data having the bit width being set by the transfer size (DCCRn:TS), is transferred for the number of times being set by the block size.

5.3. Operations

This section explains DMAC operations.

This section explains the DMAC operations as follows.

- (1) Channel status check
- (2) Data transfer

■ (1) Channel Status Check

Each DMAC channel status can be checked using the DCSRn register.

- When the channel operation is enabled (the channel is active), the DCSRn:CA bit is "1". When the channel is stopped, its status is shown as "0".
- If data transfer terminates abnormally, the DCSRn:AC bit is set to "1".
- If data transfer is suspended by the transfer stop request, the DCSRn:SP bit is set to "1".
- When data transfer terminates normally, the DCSRn:NC bit is set to "1".

Data writing to the DCSRn:CA bit is ignored.

The DCSRn:AC, DCSRn:SP, and DCSRn:NC bits must be cleared before the DMA transfer is allowed because these bits are not cleared automatically.

■ (2) Data Transfer

The DMAC starts DMA transfer when the transfer source address and transfer destination address are set. By receiving a transfer source read instruction, this controller reads the data, having the bit width (8-bit/16-bit/32-bit) being set by DCCRn:TS, from the transfer source address, and temporarily stores it in the data buffer inside of the DMAC. By receiving a transfer destination write instruction, the controller writes the data temporarily stored in the DMAC into the transfer destination address.

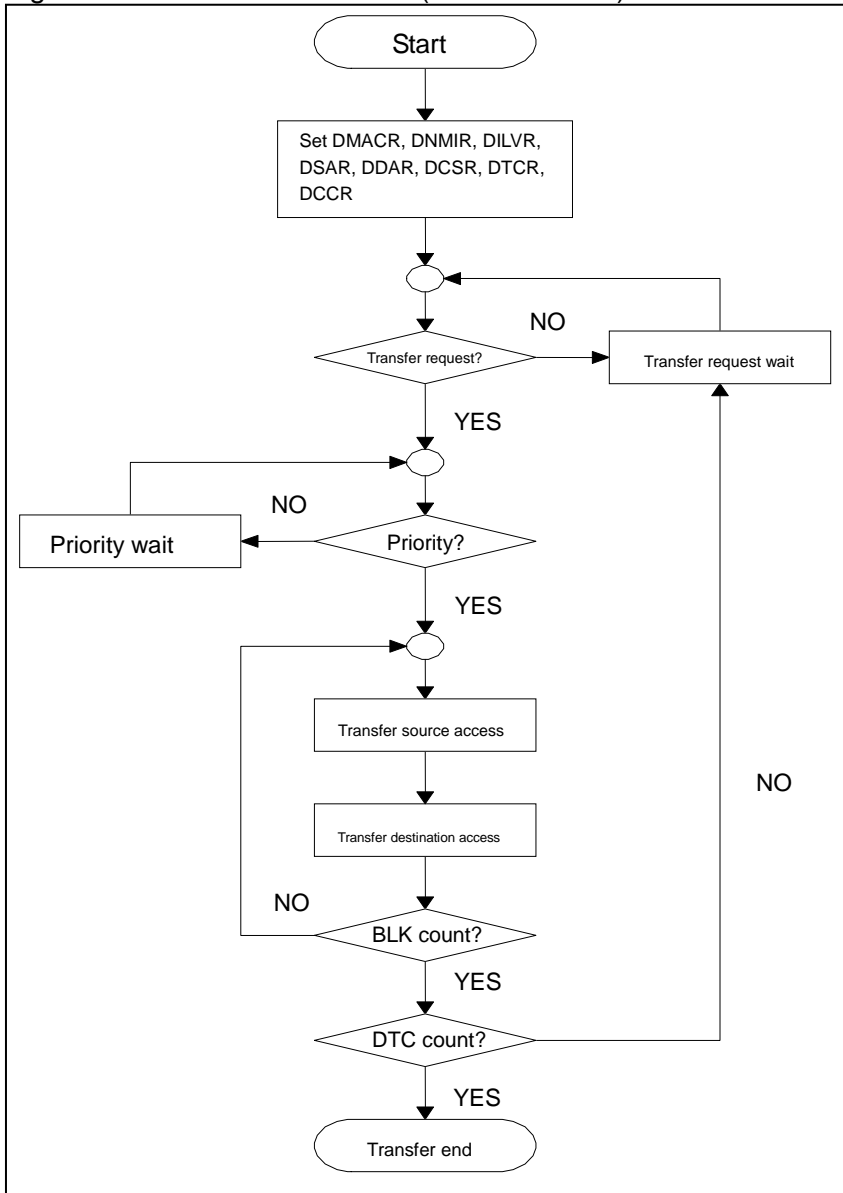
● Transfer Mode

The transfer mode has block transfer mode or burst transfer mode.

● Block Transfer Mode

1-time transfer request causes the 1 block transfer. When a transfer request is detected after the block transfer, the next 1-block transfer occurs. These operations are repeated until the end of data transfer. During 1-block data transfer, the data having the size specified by the DCCRn:TS bit is transferred for the number of times being set by the block size.

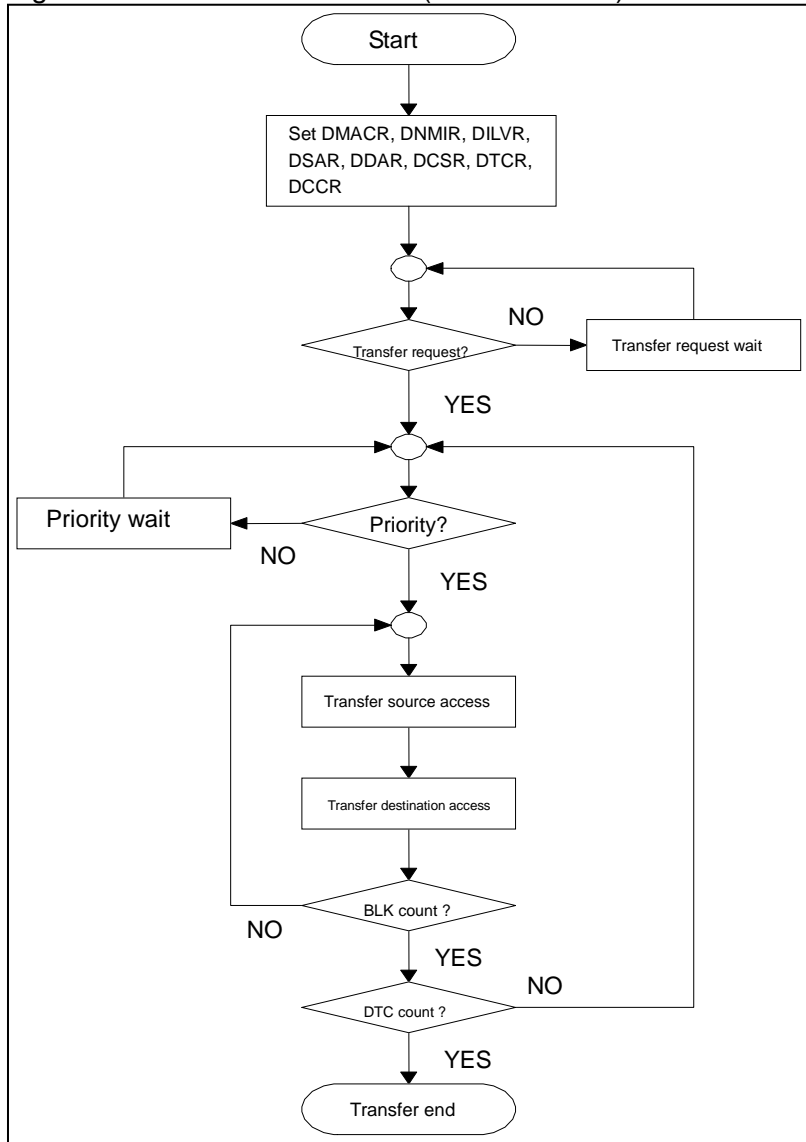
Figure 5-2 Each Transfer Mode (Block Transfer)



• **Burst transfer mode**

1-time transfer request causes the continuous data transfer until the end of transfer. (Data having the size set by the DCCRn:TS bit is transferred continuously for the block size × number of transfer times.)

Figure 5-3 Each Transfer Mode (Burst Transfer)



● **Transfer request**

The transfer request has a request by software or a request by interrupt. The following explains the relationship between the transfer request detection conditions and the transfer mode.

● **Request by software**

If the DCCRn:CE bit is set to "1", a transfer request is detected. When the DMA operation is enabled (DMACR:DME=1), the priority is determined and the data transfer is started immediately. When the data transfer by the transfer request has terminated, the DCCRn:CE bit is cleared automatically.

● **Request by interrupt**

If the channel operation is enabled (DCCRn:CE=1), a transfer request is awaited. If a peripheral interrupt, being set by the interrupt controller, has occurred, its transfer request is detected. When the DMA operation is enabled (DMACR:DME=1), the priority is determined and the data transfer is started immediately.

When a transfer stop request is asserted from the peripheral, a transfer request is not detected.

Also, an interrupt vector to be used for transfer request must be set for each channel. See the section "CHAPTER: GENERATION AND CLEARING OF DMA TRANSFER REQUESTS".

* : As the interrupt request from peripherals is detected by an edge, the transfer request cannot be detected even if the CE bit is reset from "0" to "1" while the interrupt request is enabled. The interrupt of the peripheral function should be enabled after the CE bit is set to "1".

Table 5-2 Relationship between Transfer Request Detection Conditions and Transfer Mode

	Block transfer	Burst transfer	-
Request by software	Set the DCCRn:CE bit to "1".	Set the DCCRn:CE bit to "1".	-
Request by interrupt	Edge detection	Edge detection	-

Also, the relationship between the detected transfer request and the DMACR:DME and DCCRn:CE bits is given on Table 5-3. If the DME bit or CE bit is cleared during transfer, the block transfer is stopped.

Table 5-3 Relationship between Transfer Requests and DME/CE Bits

		DME bit	CE bit
DME/CE clear		The already detected transfer request is not cleared.	The already detected transfer request is cleared.
DME/CE setting after the transfer interrupt	Block transfer	When a new transfer request is detected, the data transfer is restarted based on the priority.	When a new transfer request is detected, the data transfer is restarted based on the priority.
	Burst transfer	When the DME bit is set, the data transfer is restarted immediately based on the priority.	

● **Standby recovery request by DMA transfer request**

If the MCU receives a transfer request in the standby mode, the DMAC requests the MCU to recover from the standby mode. If data transfer is enabled and if a transfer request is asserted by the transfer request source, a standby recovery is requested.

● **Channel priority**

If multiple transfer requests are issued, the DMAC starts data transfer on the channel having the highest priority. The channel priority can be fixed or can be set by round robin. The priority is determined for each block transfer or when data transfer ends.

● **Fixed priority (DMACR:AT = 0)**

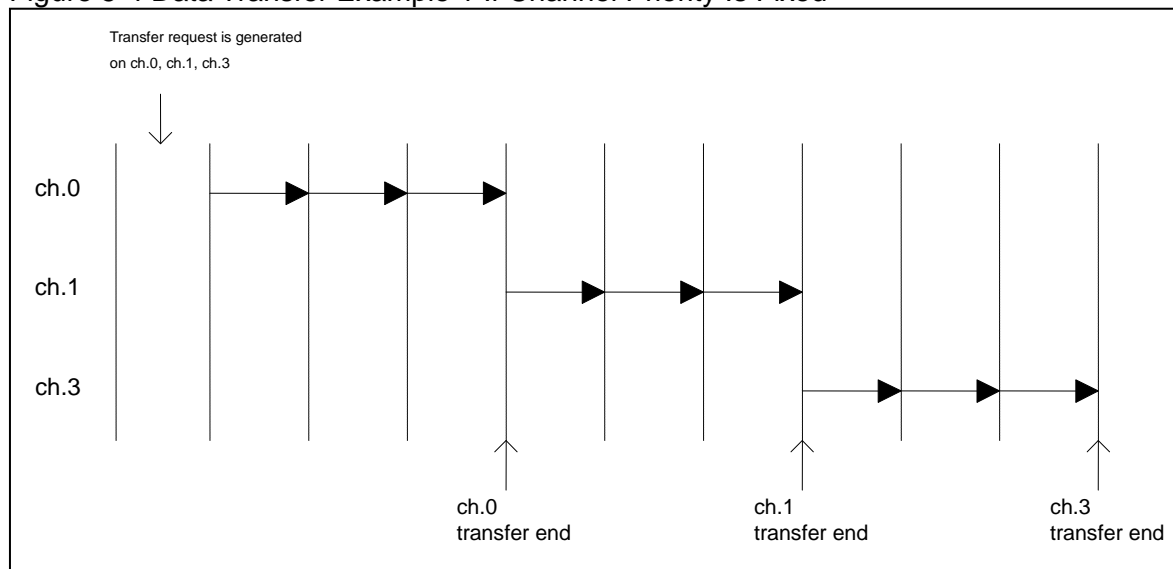
The channel priority is fixed in the sequence of "ch.0 > ch.1 > ch.2 > ch.3". The following gives an example.

Example 1 : If transfer requests are issued on ch.0, ch.1 and ch.3 simultaneously, data transfer starts from ch. 0. When data transfer ends on ch.0, the next data transfer starts on ch.1. After data transfer on ch.1, the next data transfer starts on ch.3. The following gives transfer examples. Dotted lines in the figure show the block delimiters.

Transfer request : Requests are issued for ch0, ch.1 and ch.3 simultaneously.

Setting : Ch.0, ch.1 and ch.3 are set to the burst transfer mode, and data transfer occurs 3 times.

Figure 5-4 Data Transfer Example 1 If Channel Priority Is Fixed

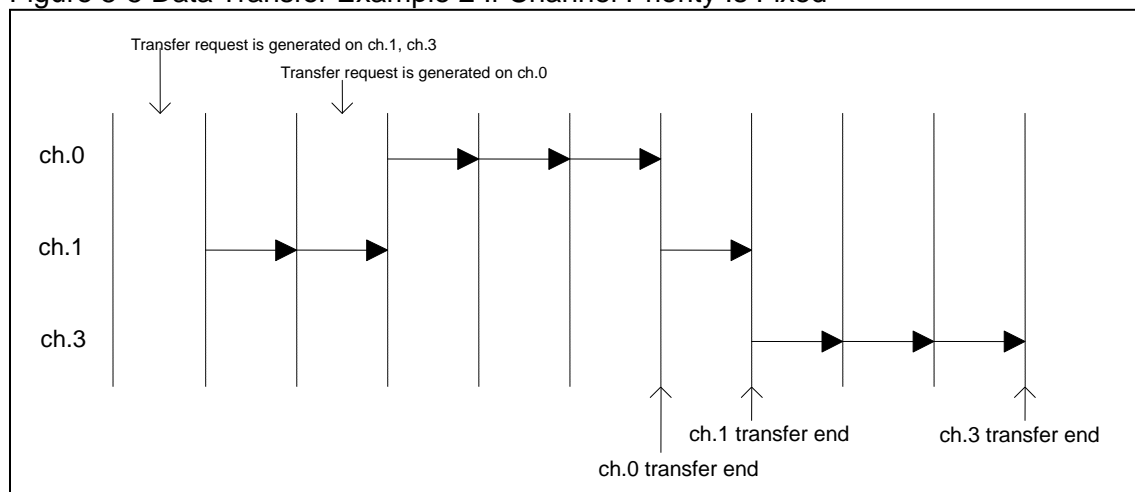


Example 2: If transfer requests are issued simultaneously for ch.1 and ch.3 and if a transfer request on ch.0 is issued during data transfer on ch.1, the data transfer on ch.1 is temporarily stopped and data transfer on ch.0 is started. During this time, the channel transition occurs in units of blocks. When the requested data transfer ends on ch.0, the data transfer is started on ch.1. Dotted lines in the figure show the block delimiters.

Transfer request : Requests are issued for ch.1 and ch.3 simultaneously. When data is transferred on ch.1, another request for transfer on ch.0 is issued.

Setting : Ch.0, ch.1 and ch.3 are set to the burst transfer mode, and data transfer occurs 3 times.

Figure 5-5 Data Transfer Example 2 If Channel Priority Is Fixed



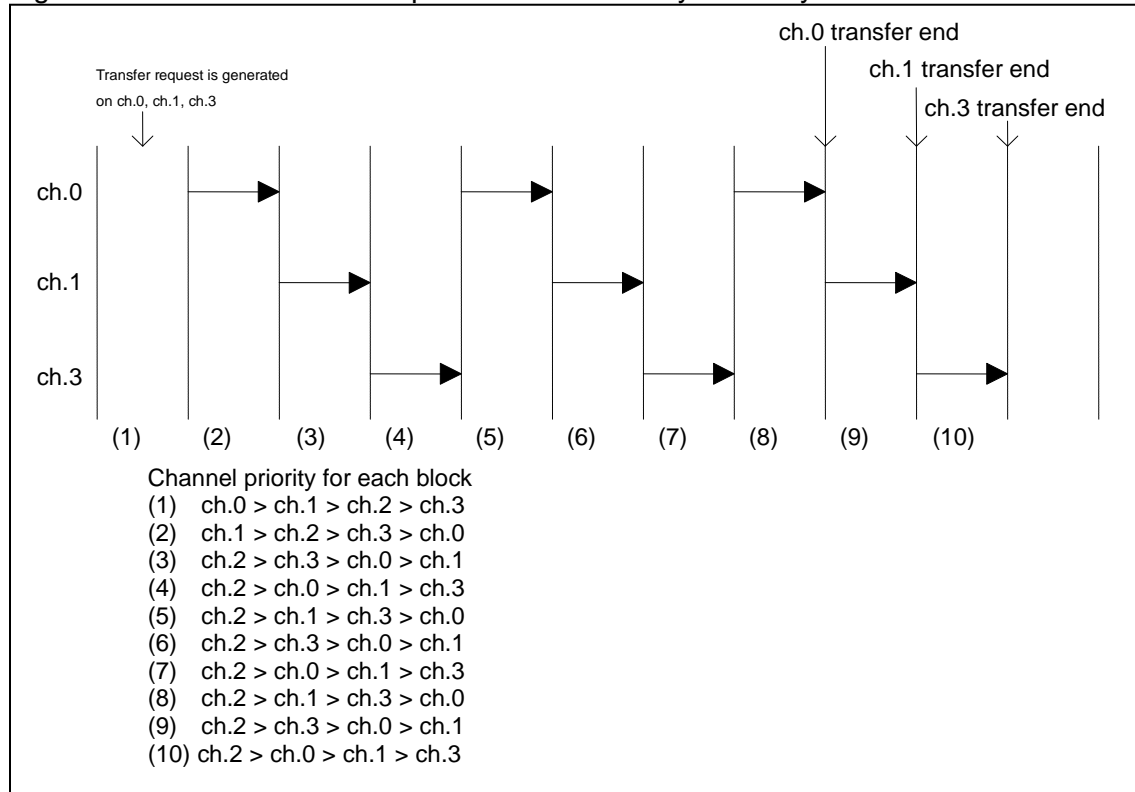
•Round robin (DMACR:AT = 1)

When data transfer is started on a channel, its priority is set to the lowest level. A channel priority below this level is raised by one level. In the round robin, data transfer starts on a channel having the highest priority when a transfer request is issued. The priority of the channel where data transfer has started is dropped to the lowest level. The priority is determined for each of block data transfer, and data transfer is started on the channel having the highest priority. The following gives a transfer example. Dotted lines in the figure show the block delimiters.

Example : Transfer request : Requests are issued for ch.0, ch.1 and ch.3 simultaneously.

Setting : Ch.0, ch.1 and ch.3 are set to the burst transfer mode; and data transfer occurs 3 times.

Figure 5-6 Data Transfer Example If Channel Priority Is Set by Round Robin



● **Updating of transfer address**

The transfer source address and transfer destination address are updated each time data which size has been set by the DCCRn:TS is transferred. The address updating can be increasing, decreasing, or fixed. When increasing or decreasing, its address amount is determined by the transfer size (DCCRn:TS). If fixed, the address value does not change. Table 5-4 shows the address increasing or decreasing width during address updating. If an overflow occurs due to address updating, the relevant bit is discarded.

Table 5-4 Updating of Transfer Source Address and Transfer Destination Address

Address setting		Transfer size (TS)	Address updating for each data transfer		
Transfer source (SAC)	Transfer destination (DAC)		Transfer source (DSA)	Transfer destination (DDA)	
Increments ("00")	Increments ("00")	8-bit ("00")	Increments by 1	Increments by 1	
		16-bit ("01")	Increments by 2	Increments by 2	
		32-bit ("10")	Increments by 4	Increments by 4	
	Decrements ("01")	8-bit ("00")	Increments by 1	Decrements by 1	
		16-bit ("01")	Increments by 2	Decrements by 2	
		32-bit ("10")	Increments by 4	Decrements by 4	
	Fixed ("11")	8-bit ("00")	Increments by 1	Not updated	
		16-bit ("01")	Increments by 2		
		32-bit ("10")	Increments by 4		
Decrements ("01")	Increments ("00")	8-bit ("00")	Decrements by 1	Increments by 1	
		16-bit ("01")	Decrements by 2	Increments by 2	
		32-bit ("10")	Decrements by 4	Increments by 4	
	Decrements ("01")	8-bit ("00")	Decrements by 1	Decrements by 1	
		16-bit ("01")	Decrements by 2	Decrements by 2	
		32-bit ("10")	Decrements by 4	Decrements by 4	
	Fixed ("11")	8-bit ("00")	Decrements by 1	Not updated	
		16-bit ("01")	Decrements by 2		
		32-bit ("10")	Decrements by 4		
Fixed ("11")	Increments ("00")	8-bit ("00")	Not updated	Increments by 1	
		16-bit ("01")		Increments by 2	
		32-bit ("10")		Increments by 4	
	Decrements ("01")	8-bit ("00")		Decrements by 1	
		16-bit ("01")		Decrements by 2	
		32-bit ("10")		Decrements by 4	
	Fixed ("11")	8-bit ("00")		Not updated	Not updated
		16-bit ("01")			
		32-bit ("10")			

● **Reloading of transfer address**

The DMAC can reload the transfer address after the specified number of data transfer has completed.

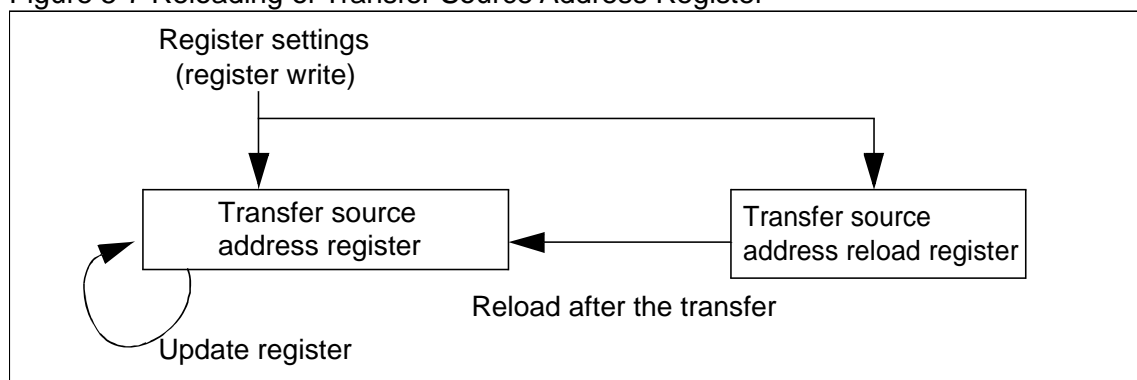
● **Reloading of transfer source address**

If the reloading of transfer source address has been set, the DSARn:DSA bit is returned to the initial value after the data transfer.

If the reloading of transfer source address is disabled, the DSARn:DSA bit indicates the next access address of the last address after the current data transfer.

If the specified number of times of transfer is suspended or abnormally terminated, the DSARn:DSA bit indicates the next access address (after the terminated address) regardless of the reload setting of the transfer source address.

Figure 5-7 Reloading of Transfer Source Address Register



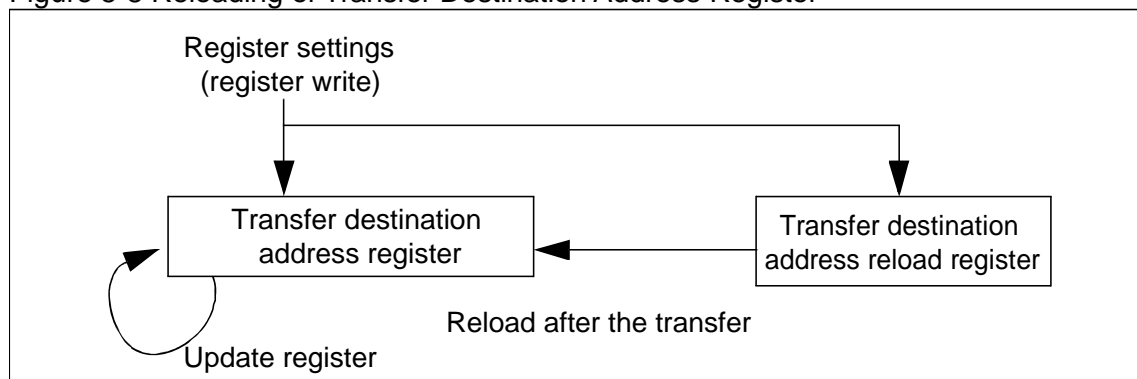
● **Reloading of transfer destination address register**

If the reloading of the transfer destination address has been set, the DDARn:DDA bit is returned to the initial value after the data transfer.

If the reloading of the transfer destination address is disabled, the DDARn:DDA bit indicates the next access address of the last address after the current data transfer.

If the specified number of times of transfer is suspended or abnormally terminated, the DDARn:DDA bit indicates the next access address (after the terminated address) regardless of the reload setting of the transfer destination address.

Figure 5-8 Reloading of Transfer Destination Address Register



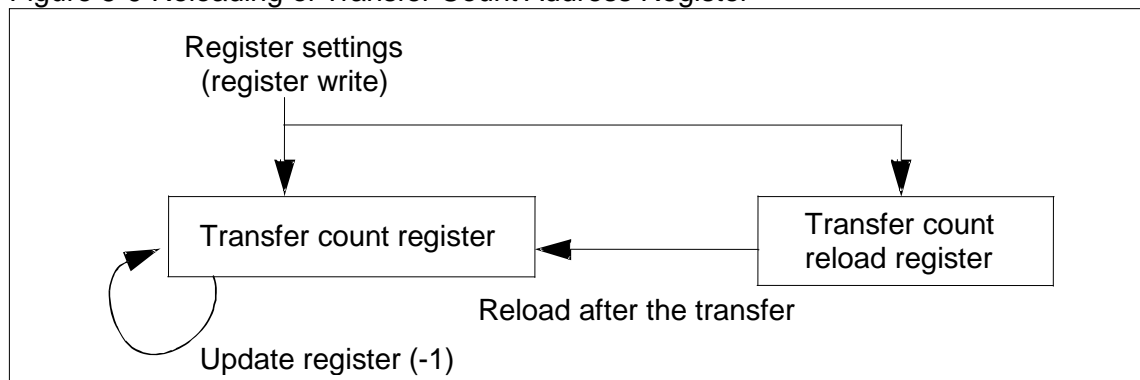
● **Reloading of transfer count**

If the reloading of the transfer count has been set, the DTCRn:DTC bit is returned to the initial value after the data transfer.

If reloading of the transfer count is disabled, the DTCRn:DTC bit is set to "0" after the data transfer.

If the specified number of times of transfer is suspended or abnormally terminated, the DTCRn:DTC bit indicates the remaining transfer count regardless of the reload setting of the transfer count.

Figure 5-9 Reloading of Transfer Count Address Register



The DCCRn:CE bit status varies after the data transfer, depending on the reload setting of the transfer count. The following explains the relation between the transfer count reload setting and the transfer request source.

Table 5-5 DCCRn:CE Bit at the End of Transfer

	Software request	Non-software request
If the reloading of transfer count is set	The DCCRn:CE bit is cleared	The DCCRn:CE bit is not cleared
If the reloading of transfer count is disabled	The DCCRn:CE bit is cleared	The DCCRn:CE bit is cleared

● **Transfer suspension**

The DMAC suspends the DMA transfer due to the following causes.

- A suspension as the DMACR:DME bit is cleared
- A suspension as the DCCRn:CE bit is cleared
- A suspension caused by the transfer stop request by the transfer request source peripheral

Data transfer is suspended in units of blocks. If data transfer is suspended, the next transfer is not started. Data transfer is stopped. The settings to restart data transfer vary depending on the suspension cause.

- A suspension as the DMACR:DME bit is cleared

If the DMACR:DME bit is cleared, all channels are stopped from operating. After a block of data has been transferred on the current channel, the data transfer is suspended. To restart data transfer, set the DMACR:DME bit.

- A suspension as the DCCRn:CE bit is cleared

If the DCCRn:CE bit is cleared, the channel is stopped from operating. After a block of data has been transferred, the data transfer is suspended. Also, as the DCCRn:CE bit is cleared, the already detected transfer request is cleared. To restart data transfer, set the DCCRn:CE bit for the stopped channel and issue a new transfer request.

- A transfer stop request from the transfer request source peripheral

The following peripherals can issue a transfer stop request under certain conditions.

(A) Multi-function serial interface

If a PE, FRE, or ORE flag is set

(B) LIN-UART

If a PE, FRE, or ORE flag is set

If a transfer stop request is issued, the transfer is suspended after one block of the current data has been transferred. If the data transfer is suspended, the following occur.

- The SP bit of DMA channel status registers (DCSRn) is set to "1".
- The CE bit of DMA channel control registers (DCCRn) is set to "0".
- The already detected transfer request is cleared.

While a transfer stop request being issued, a new transfer request is rejected. Restart the DMA transfer in the following procedure.

1. Clear the flags described in paragraphs (A) and (B) to make the transfer stop request invalid.
2. Set the SP bit of DMA channel status registers (DCSRn) of the corresponding channel to "0".
3. Set the CE bit of DMA channel control registers (DCCRn) to "1".
4. Issue a new transfer request.

Table 5-6 Settings to Restart the Suspended Data Transfer

	DME clear	CE clear	If a transfer stop request from transfer request source peripheral is detected
Setting to restart transfer	(1) Set the DME bit	(1) Set the CE bit (2) Issue a transfer request	(1) The transfer request is negated (2) The SP bit is cleared (3) The CE bit is set (4) Issue a transfer request

● **Transfer termination**

Data transfer can terminate normally or abnormally.

● **Normal termination**

The transfer terminates normally at the time when the transfers for the number of times set by the transfer count (DTCRn:DTC) end. When terminated normally, the DCSRn:NC bit of the corresponding channel is set. Also, the DCCRn:CE bit is cleared and data transfer is stopped. However, if the reloading of the transfer count has been set by non-software transfer request source, the DCCRn:CE bit of the channel is not cleared.

If the transfer count (DTCRn:DTC) is "0" and if the DCCRn:CE bit of the corresponding channel is set to "1", the DCSRn:NC bit is set in the similar way as for the normal termination. Before setting the DCCRn:CE bit to "1", be sure to set the DTCRn:DTC bit to "1" or a larger value.

● **Abnormal termination**

If an inhibited value is set in the register, data transfer terminates abnormally. When terminated abnormally, the DCSRn:AC bit of the corresponding channel is set. Also, the DCCRn:CE bit is cleared and data transfer is stopped.

The items not allowed to set to registers are listed below.

- Transfer mode : DCCRn:TM = 10
- Transfer source address count : DCCRn:SAC = 10
- Transfer destination address count : DCCRn:DAC = 10
- Transfer size : DCCRn:TS = 11
- Demand transfer mode by software request : DCCRn:RS = 00 and DCCRn:TM = 11

● **Interrupt request**

The DMAC can issue an interrupt request at normal termination of data transfer, at abnormal termination of data transfer, or at transfer suspension by a transfer stop request. When issuing an interrupt request, set the interrupt controller as well.

Use the DMA channel status register (DCSRn) to check the interrupt request cause or to clear the interrupt request.

● **Interrupt request at normal termination**

If the normal termination interrupt of a channel is enabled (DCCRn:NIE=1), the DMAC issues the interrupt request at the normal termination.

However, the DCSRn:NC bit of the corresponding channel must be set regardless of the normal termination interrupt setting (DCCRn:NIE).

Clear the interrupt request by clearing the DCSRn:NC bit of the corresponding channel.

● **Interrupt request at abnormal termination**

If the abnormal termination interrupt of a channel is enabled (DCCRn:AIE=1), the DMAC issues the interrupt request at the abnormal termination. However, the DCSRn:AC bit of the corresponding channel is set regardless of the abnormal termination interrupt (DCCRn:AIE) setting.

Clear the interrupt request by clearing the DCSRn:AC bit of the corresponding channel.

● **A transfer suspension interrupt request by a transfer stop request**

If the transfer suspension interrupt of a channel is enabled (DCCRn:AIE=1), the DMAC issues the interrupt request if data transfer is suspended by a transfer stop request. However, the DCSRn:SP bit of the corresponding channel is set regardless of the transfer suspension interrupt (DCCRn:SIE) settings.

Clear the interrupt request by clearing the DCSRn:SP bit of the corresponding channel.

● **DMA transfer suppressing**

The DMA transfer is suppressed due to the following causes.

- A DMA transfer suppress request from DSU/OCD (for debugging)
- NMI
- Peripheral interrupt

The DMA transfer is suppressed in units of blocks. If data transfer is suppressed, new data transfer does not start. Data transfer is stopped. The settings to restart data transfer vary depending on the DMA transfer suppress causes.

● **DMA transfer suppressing request from DSU/OCD (for debugging)**

When the DMA transfer suppressing request by DSU/OCD is asserted, a new transfer does not start and a current transfer stops with the block unit. The acknowledge is not returned to the DMA transfer suppressing from DSU/OCD.

● **DMA transfer suppressing by NMI**

If the NMIH bit is set to "0", DMAC sets NMIH flag when user NMI occurs and suppresses DMA transfer after the block unit transfer is done.

Write "0" in the NMIH flag when you restart transfer.

● **DMA transfer suppressing by peripheral interrupt**

If an interrupt having the level higher than the one specified in the DILVR register occurs, the DMA transfer is suppressed after the current block has been transferred.

When the interrupt request is cleared and the interrupt level drops to LVL[4:0] or lower level, the DMA transfer restarts.

Table 5-7 LVL[4:0] Settings to Suppress DMA Transfer

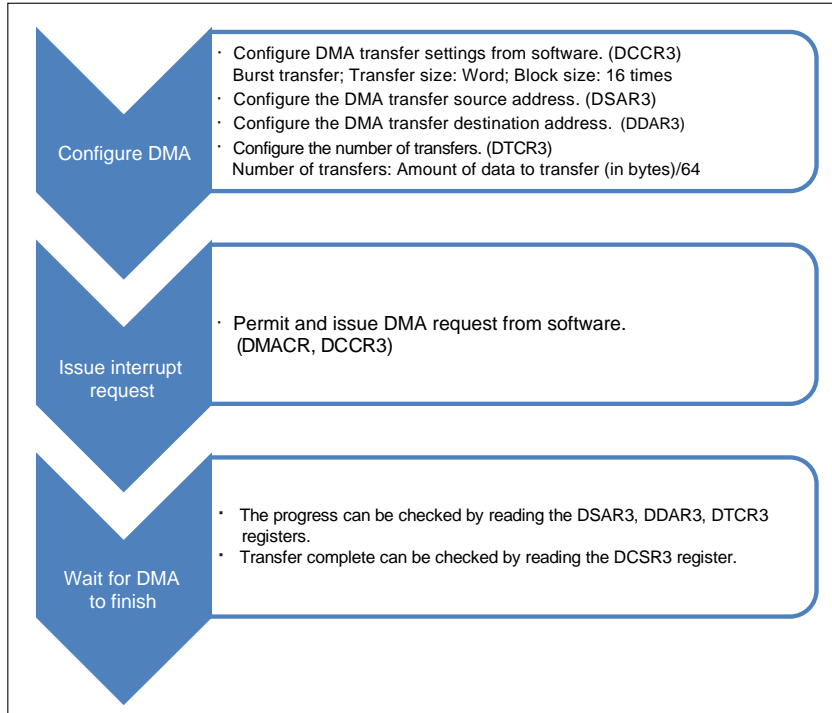
LVL[4:0]	DMA suppress control
11111	Suppresses the DMA transfer when any peripheral interrupt request is issued. (initial value)
11110	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1E _H is issued.
11101	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1D _H is issued.
11100	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1C _H is issued.
11011	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1B _H is issued.
11010	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 1A _H is issued.
11001	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 19 _H is issued.
11000	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 18 _H is issued.
10111	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 17 _H is issued.
10110	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 16 _H is issued.
10101	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 15 _H is issued.
10100	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 14 _H is issued.
10011	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 13 _H is issued.
10010	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 12 _H is issued.
10001	Suppresses the DMA transfer when a peripheral interrupt request having a level higher than 11 _H is issued.
10000	Does not suppress the DMA transfer when a peripheral interrupt request is issued.

6. DMA Usage Examples

DMA usage examples are shown.

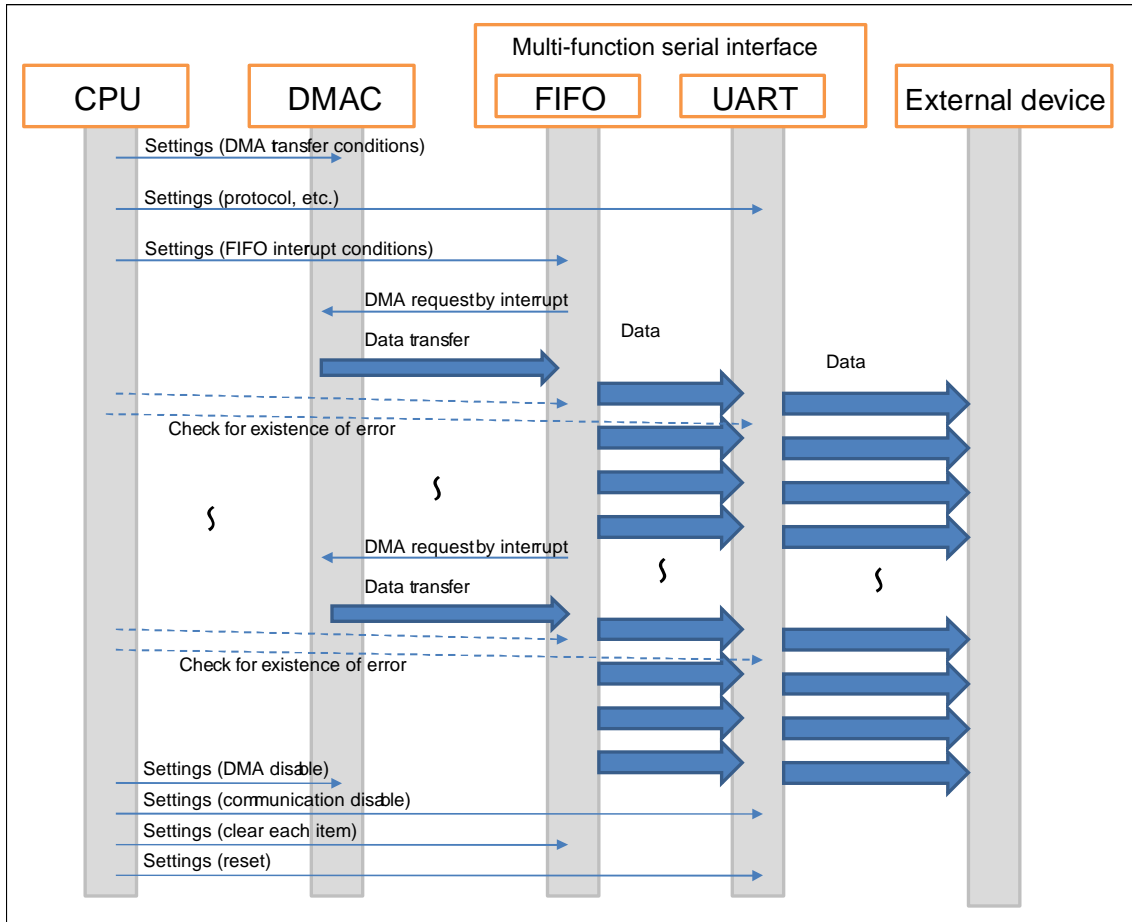
The following gives an example of memcopy instruction in every 64-byte data using the DMA. This is the simplest DMA transfer example.

Figure 6-1 memcopy Example Using the DMA (ch.3 is used)



This is a communication example via the multi-function serial interface that uses the DMA. In this example, an interrupt of the multi-function serial interface is occupied by the DMA transfer request. Therefore, the CPU polls the status registers to check for an error occurrence.

Figure 6-2 Communication Example via the Multi-function Serial Interface That Uses DMA



CHAPTER : GENERATION AND CLEARING OF DMA TRANSFER REQUESTS

This chapter explains the generation and clearing of DMA transfer requests.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains the overview of the generation and clearing of DMA transfer requests.

This series can activate DMA transfer using interrupt requests from peripheral functions. Registers used to select interrupt requests that activate DMA transfer are provided for each DMA controller (DMAC) channel. If multiple interrupt requests are assigned to one interrupt vector number, it is also necessary to specify what interrupt request flag is to be cleared by the DMA controller (DMAC).

DMA controller (DMAC) registers allow DMA transfer request generation factors (transfer request sources) to be set on interrupt requests from peripheral functions. The interrupt requests to be used can be selected by specifying the value corresponding to the interrupt vector number.

2. Features

This section explains features of the generation and clearing of DMA transfer requests.

■ Transfer Request Generation Setting

For each 16-channel DMA transfer request, you need to specify what interrupt from interrupt vector numbers 0x10 (16 in decimal notation) to 0x3F (63 in decimal notation) is used to generate the DMA transfer request.

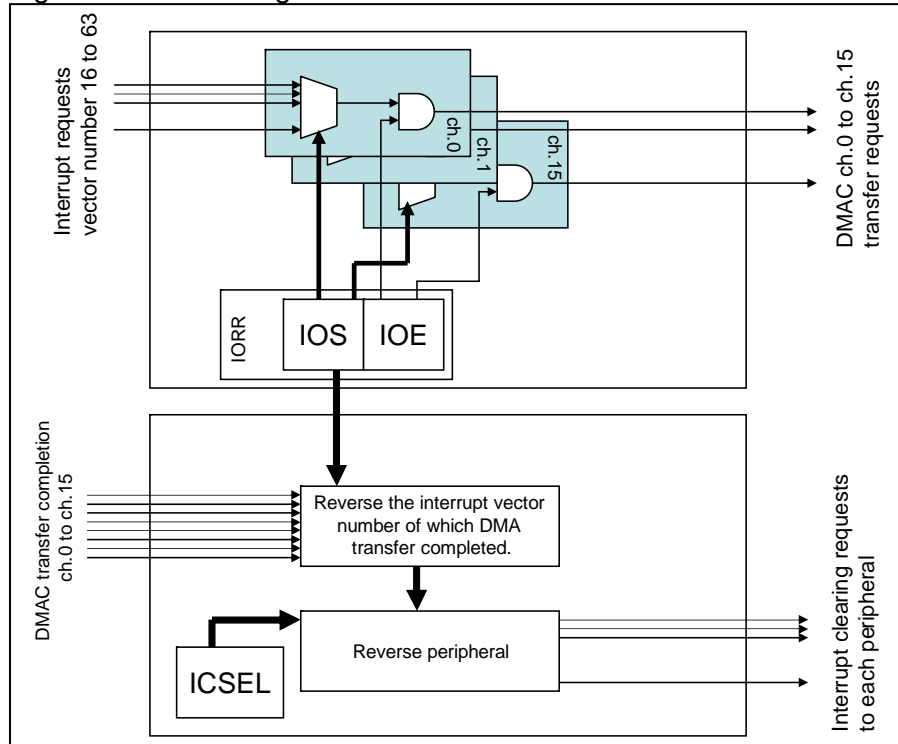
■ Interrupt Clearing Setting

After the DMA transfer ends, the interrupt source peripheral that has issued the interrupt request to be cleared is identified if the transfer request source is a vector number to which multiple interrupt source peripherals belong.

3. Configuration

This section explains the configuration of the generation and clearing of DMA transfer requests.

Figure 3-1 Block Diagram



4. Registers

This section explains registers of the generation and clearing of DMA transfer requests.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0400	ICSEL0	ICSEL1	ICSEL2	ICSEL3	DMA clear request register 0 (for vector number #16) DMA clear request register 1 (for vector number #17) DMA clear request register 2 (for vector number #18) DMA clear request register 3 (for vector number #19)
0x0404	ICSEL4	ICSEL5	ICSEL6	ICSEL7	DMA clear request register 4 (for vector number #38) DMA clear request register 5 (for vector number #39) DMA clear request register 6 (for vector number #40) DMA clear request register 7 (for vector number #41)
0x0408	ICSEL8	ICSEL9	ICSEL10	ICSEL11	DMA clear request register 8 (for vector number #42) DMA clear request register 9 (for vector number #43) DMA clear request register 10 (for vector number #44) DMA clear request register 11 (for vector number #46)
0x040C	ICSEL12	ICSEL13	ICSEL14	ICSEL15	DMA clear request register 12 (for vector number #47) DMA clear request register 13 (for vector number #52) DMA clear request register 14 (for vector number #53) DMA clear request register 15 (reserved)
0x0410	ICSEL16	ICSEL17	ICSEL18	ICSEL19	DMA clear request register 16 (reserved) DMA clear request register 17 (reserved) DMA clear request register 18 (reserved) DMA clear request register 19 (for vector number #58)
0x0414	ICSEL20	ICSEL21	ICSEL22	Reserved	DMA clear request register 20 (for vector number #59) DMA clear request register 21 (for vector number #60) DMA clear request register 22 (for vector number #61)
0x0490	IORR0	IORR1	IORR2	IORR3	IO transfer request register 0 IO transfer request register 1 IO transfer request register 2 IO transfer request register 3
0x0494	IORR4	IORR5	IORR6	IORR7	IO transfer request register 4 IO transfer request register 5 IO transfer request register 6 IO transfer request register 7

Address	Registers				Register function
	+0	+1	+2	+3	
0x0498	IORR8	IORR9	IORR10	IORR11	IO transfer request register 8 IO transfer request register 9 IO transfer request register 10 IO transfer request register 11
0x049C	IORR12	IORR13	IORR14	IORR15	IO transfer request register 12 IO transfer request register 13 IO transfer request register 14 IO transfer request register 15

4.1. DMA Request Clear Register 0 : ICSEL0 (Interrupt Clear SElect register 0)

The bit configuration of DMA request clear register 0 is shown below.

■ ICSEL0 : Address 0400_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					EISEL[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W

[bit2 to bit0] EISEL[2:0] (External Interrupt request SElection) : Interrupt clear selection bits for external interrupts 0 to 7

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #16).

EISEL[2:0]	Clear target
000	External interrupt 0
001	External interrupt 1
010	External interrupt 2
011	External interrupt 3
100	External interrupt 4
101	External interrupt 5
110	External interrupt 6
111	External interrupt 7

4.2. DMA Request Clear Register 1 : ICSEL1 (Interrupt Clear SElect register 1)

The bit configuration of DMA request clear register 1 is shown below.

■ ICSEL1: Address 0401_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					EISEL[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W

[bit2 to bit0] EISEL[2:0] (External Interrupt request SElection) : Interrupt clear selection bits for external interrupts 8 to 15

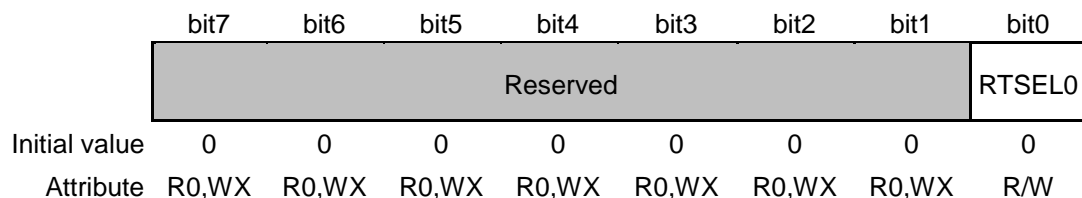
These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #17).

EISEL[2:0]	Clear target
000	External interrupt 8
001	External interrupt 9
010	External interrupt 10
011	External interrupt 11
100	External interrupt 12
101	External interrupt 13
110	External interrupt 14
111	External interrupt 15

4.3. DMA Request Clear Register 2 : ICSEL2 (Interrupt Clear SElect register 2)

The bit configuration of DMA request clear register 2 is shown below.

■ **ICSEL2: Address 0402_H (Access : Byte, Half-word, Word)**



[bit0] RTSEL0 (Reload Timer SElection) : Interrupt clear selection bit for reload timer 0/1

This bit is used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #18).

RTSEL0	Clear target
0	Reload timer 0
1	Reload timer 1

4.4. DMA Request Clear Register 3 : ICSEL3 (Interrupt Clear SElect register 3)

The bit configuration of DMA request clear register 3 is shown below.

■ ICSEL3: Address 0403_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							RTSEL1
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

[bit0] RTSEL1 (Reload Timer SElection) : Interrupt clear selection bit for reload timer 2/3

This bit is used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #19).

RTSEL1	Clear target
0	Reload timer 2
1	Reload timer 3

4.5. DMA Request Clear Register 4 : ICSEL4 (Interrupt Clear SElect register 4)

The bit configuration of DMA request clear register 4 is shown below.

■ ICSEL4: Address 0404_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							SG_RX_SEL0
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

[bit0] SG_RX_SEL0 (SG_RX SElection0) : Interrupt clear selection bit for sound generator ch.0 / LIN-UART ch.7 reception completion

This bit is used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #38).

SG_RX_SEL0	Clear target
0	Sound generator ch.0
1	LIN-UART ch.7 reception completion

4.6. DMA Request Clear Register 5 : ICSEL5 (Interrupt Clear SElect register 5)

The bit configuration of DMA request clear register 5 is shown below.

■ ICSEL5: Address 0405_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							SG_RX_SEL1
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

[bit0] SG_RX_SEL1 (SG_RX SElection1) : Interrupt clear selection bit for sound generator ch.1 / LIN-UART ch.7 transmission completion

This bit is used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #39).

SG_RX_SEL1	Clear target
0	Sound generator ch.1
1	LIN-UART ch.7 transmission completion

4.7. DMA Request Clear Register 6 : ICSEL6 (Interrupt Clear SElect register 6)

The bit configuration of DMA request clear register 6 is shown below.

■ ICSEL6: Address 0406_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					PPGSEL0[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W

[bit2 to bit0] PPGSEL0[2:0] (PPG SElection0) : Interrupt clear selection bits for PPG0, 1, 10, 11, 20, 21

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #40).

PPGSEL0[2:0]	Clear target
000	PPG0
001	PPG1
010	PPG10
011	PPG11
100	PPG20
101	PPG21
110	Reserved (Does not clear any)
111	Reserved (Does not clear any)

Note:

Setting PPGSEL0[2:0]= "3'b110", "3'b111" is prohibited. During this setting, no interrupt clear will be selected.

4.8. DMA Request Clear Register 7 : ICSEL7 (Interrupt Clear SElect register 7)

The bit configuration of DMA request clear register 7 is shown below.

■ ICSEL7: Address 0407_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					PPGSEL1[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W

[bit2 to bit0] PPGSEL1[2:0] (PPG SElection1) : Interrupt clear selection bits for PPG2, 3, 12, 13, 22, 23

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #41).

PPGSEL1[2:0]	Clear target
000	PPG2
001	PPG3
010	PPG12
011	PPG13
100	PPG22
101	PPG23
110	Reserved (Does not clear any)
111	Reserved (Does not clear any)

Note:

Setting PPGSEL1[2:0]= "3'b110", "3'b111" is prohibited. During this setting, no interrupt clear will be selected.

4.9. DMA Request Clear Register 8 : ICSEL8 (Interrupt Clear SElect register 8)

The bit configuration of DMA request clear register 8 is shown below.

■ ICSEL8: Address 0408_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						PPGSEL2[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit1, bit0] PPGSEL2[1:0] (PPG SElection2) : Interrupt clear selection bits for PPG4, 5, 14, 15
These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #42).

PPGSEL2[1:0]	Clear target
00	PPG4
01	PPG5
10	PPG14
11	PPG15

4.10. DMA Request Clear Register 9 : ICSEL9 (Interrupt Clear SElect register 9)

The bit configuration of DMA request clear register 9 is shown below.

■ ICSEL9: Address 0409_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						PPGSEL3[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit1, bit0] PPGSEL3[1:0] (PPG SElection3) : Interrupt clear selection bits for PPG6, 7, 16, 17

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #43).

PPGSEL3[1:0]	Clear target
00	PPG6
01	PPG7
10	PPG16
11	PPG17

4.11. DMA Request Clear Register 10 : ICSEL10 (Interrupt Clear SElect register 10)

The bit configuration of DMA request clear register 10 is shown below.

■ ICSEL10: Address 040A_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						PPGSEL4[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit1, bit0] PPGSEL4[1:0] (PPG SElection4) : Interrupt clear selection bits for PPG8, 9, 18, 19

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #44).

PPGSEL4[1:0]	Clear target
00	PPG8
01	PPG9
10	PPG18
11	PPG19

4.12. DMA Request Clear Register 11 : ICSEL11 (Interrupt Clear SElect register 11)

The bit configuration of DMA request clear register 11 is shown below.

■ ICSEL11: Address 040B_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						PMSTSEL[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit1, bit0] PMSTSEL[1:0] (PLL, Main, Sub Timer SElection) : Interrupt clear selection for main timer / sub timer / PLL timer

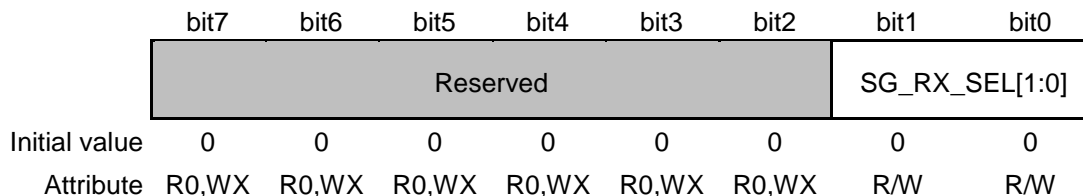
These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #46).

PMSTSEL[1:0]	Clear target
00	Main timer
01	Sub timer
10	PLL timer
11	Setting is prohibited

4.13. DMA Request Clear Register 12 : ICSEL12 (Interrupt Clear SElect register 12)

The bit configuration of DMA request clear register 12 is shown below.

■ **ICSEL12: Address 040C_H (Access : Byte, Half-word, Word)**



[bit1, bit0] SG_RX_SEL[1:0] (SG_RX Selection) : Interrupt clear selection for SG4

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #47).

SG_RX_SEL[1:0]	Clear target
00	Reserved (Does not clear any)
01	Sound generator ch.4
10	Setting is prohibited
11	Reserved (Does not clear any)

Note:

Clock calibration (SUB) is not covered as it is an interrupt which does not support the IIOC.
Setting SG_RX_SEL[1:0]= "2'b11" is prohibited. During this setting, no interrupt clear will be selected.

4.14. DMA Request Clear Register 13 : ICSEL13 (Interrupt Clear SElect register 13)

The bit configuration of DMA request clear register 13 is shown below.

■ ICSEL13: Address 040D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							ICUSEL0
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

[bit0] ICUSEL0 : Interrupt clear selection for ICU ch.0, ch.6

This bit is used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #52).

ICUSEL0	Clear target
0	ICU ch.0
1	ICU ch.6

4.15. DMA Request Clear Register 14 : ICSEL14 (Interrupt Clear SElect register 14)

The bit configuration of DMA request clear register 14 is shown below.

■ ICSEL14: Address 040E_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							ICUSEL1
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W

[bit0] ICUSEL1 : Interrupt clear selection for ICU ch.1, ch.7

This bit is used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #53).

ICUSEL1	Clear target
0	ICU ch.1
1	ICU ch.7

4.16. DMA Request Clear Register 15 to 18 : ICSEL15 to 18 (Interrupt Clear SElect register 15 to 18)

The bit configuration of DMA request clear register 15 to 18 is shown below.

■ ICSEL15: Address 040F_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,W0

■ ICSEL16: Address 0410_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,W0

■ ICSEL17: Address 0411_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,W0

■ ICSEL18: Address 0412_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,W0

[bit0] Reserved

This is a reserved bit. Always write "0" to this bit.

4.17. DMA Request Clear Register 19 : ICSEL19 (Interrupt Clear SElect register 19)

The bit configuration of DMA request clear register 19 is shown below.

■ ICSEL19: Address 0413_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					OCUSEL0[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W

[bit2 to bit0] OCUSEL0[2:0] (OCU Selection0) : Interrupt clear selection bits for OCU0, 1

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #58).

OCUSEL0[2:0]	Clear target
000	OCU0
001	OCU1
010	Setting is prohibited
011	Setting is prohibited
100	Setting is prohibited
101	Setting is prohibited
110	Reserved (Does not clear any)
111	Reserved (Does not clear any)

Note:

Setting OCUSEL0[2:0]= "3'b110", "3'b111" is prohibited. During this setting, no interrupt clear will be selected.

4.18. DMA Request Clear Register 20 : ICSEL20 (Interrupt Clear SElect register 20)

The bit configuration of DMA request clear register 20 is shown below.

■ ICSEL20: Address 0414_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					OCUSEL1[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W

[bit2 to bit0] OCUSEL1[2:0] (OCU Selection1) : Interrupt clear selection bits for OCU2, 3

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #59).

OCUSEL1[2:0]	Clear target
000	OCU2
001	OCU3
010	Setting is prohibited
011	Setting is prohibited
100	Setting is prohibited
101	Setting is prohibited
110	Reserved (Does not clear any)
111	Reserved (Does not clear any)

Note:

Setting OCUSEL1[2:0]= "3'b110", "3'b111" is prohibited. During this setting, no interrupt clear will be selected.

4.19. DMA Request Clear Register 21 : ICSEL21 (Interrupt Clear SElect register 21)

The bit configuration of DMA request clear register 21 is shown below.

■ ICSEL21: Address 0415_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						BT_SG_SEL0[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit1, bit0] BT_SG_SEL0[1:0] (BT_SG Selection0) : Interrupt clear selection bits for Base Timer0 IRQ0, IRQ1/ SG2

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #60).

BT_SG_SEL0[1:0]	Clear target
00	Base Timer0 IRQ0
01	Base Timer0 IRQ1
10	Sound generator ch.2
11	Reserved (Does not clear any)

Note:

Setting BT_SG_SEL0[1:0]="2'b11" is prohibited. During this setting, no interrupt clear will be selected.

4.20. DMA Request Clear Register 22 : ICSEL22 (Interrupt Clear SElect register 22)

The bit configuration of DMA request clear register 22 is shown below.

■ ICSEL22: Address 0416_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						BT_SG_SEL1[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R/W	R/W

[bit1, bit0] BT_SG_SEL [1:0] (BT_SG_Selection1) : Interrupt clear selection bits for Base Timer1 IRQ0, IRQ1/ SG3

These bits are used to select the peripheral that has generated the interrupt to be cleared (assigned to interrupt vector number #61).

BT_SG_SEL1[1:0]	Clear target
00	Base Timer1 IRQ0
01	Base Timer1 IRQ1
10	Sound generator ch.3
11	Reserved (Does not clear any)

Note:

Interrupts for XBS RAM single-bit error occurrence and backup RAM single-bit error occurrence shall not be covered as they do not support the IIOC.

Setting BT_SG_SEL1[1:0]="2'b11" is prohibited. During this setting, no interrupt clear will be selected.

4.21. IO Transfer Request Setting Register 0 to 15 : IORR0 to 15 (IO triggered DMA Request Register for ch. 0 to 15)

The bit configuration of IO transfer request setting register 0 to 15 is shown below.

If the DMA transfer request generation factor is specified as a peripheral interrupt request, these registers are used to identify the vector number of the interrupt request that has generated the DMA transfer request.

An instance of these registers is provided for each DMA controller (DMAC) channel.

■ IORR0 to 15: Address 0490_H to 049F_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	IOE	IOS[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7] Reserved

Always write "0" to this bit. The read value is always "0".

[bit6] IOE (IO Enabled) : Transfer request enable bit

When an interrupt request specified by the IOS5 to IOS0 bits has been generated, this bit is used to notify the DMA controller (DMAC) for the pertinent channel whether to output the DMA transfer request.

IOE	Function
0	No DMA transfer request output -- The interrupt request generated by the peripheral is not used as a DMA transfer request (Initial value).
1	DMA transfer request output

[bit5 to bit0] IOS[5:0] (IO triggered DMA transfer request Select) : Transfer request selection bits

These registers are used to identify the interrupt request of the vector number that is used as the transfer request source by the DMA controller (DMAC) for the channel corresponding to these registers.

IOS[5:0]	Interrupt vector number (Hexadecimal)
000000	0x10 (Initial value)
000001	0x11
000010	0x12
000011	0x13
000100	0x14
000101	0x15
:	:
101100	0x3C
101101	0x3D
101110	0x3E
101111	0x3F

IOS[5:0]	Interrupt vector number (Hexadecimal)
11xxxx	Reserved

Note:

You cannot configure setting that causes interrupt requests with the same interrupt vector number to be transfer requests from multiple DMA channels (example:simultaneous setting of IORR0 = 0x42 and IORR1 = 0x42).

5. Operation

This section explains the operation of the generation and clearing of DMA transfer requests.

- 5.1. Configuration
- 5.2. Notes

5.1. Configuration

This section explains the configuration of the generation and clearing of DMA transfer requests.

The operating sequence is as follows:

1. On the IORR, set the interrupt vector number of the transfer request source peripheral and the IOE bit.
2. Set ICSEL if multiple peripherals is assigned to the vector number selected in step 1.
3. Set the interrupt configuration-related registers for the peripheral.
4. Configure the DMAC.

5.2. Notes

This section explains notes of the generation and clearing of DMA transfer requests.

- Do not change the IORR and ICSEL registers when the DMAC enables DMA transfer requests issued by peripherals.
- Peripherals to which resource numbers (RN) are not assigned (see "APPENDIX") cannot use the feature for clearing interrupts after the completion of DMA transfer. It should therefore be noted that once such a peripheral has requested DMA transfer, the interrupt will not be cleared after the completion of the requested DMA transfer.
- Interrupt requests used as transfer requests are considered as interrupt requests addressed to the CPU. Therefore, configure the interrupt controller to disable interrupts. (ICR register)

CHAPTER: FIXEDVECTOR FUNCTION

This chapter explains the FixedVector function.

1. Overview
2. Operation Explanation

1. Overview

This section explains the overview of the FixedVector function.

The FixedVector function is a function for returning the start address of flash memory + 0x0024 instead of the content of flash memory at the address (0xF_FFFC) corresponding to the interrupt vector on reset.

■ Features

- Interrupt vector on reset returned by the FixedVector function
- 0x0007_0024

■ Configuration

See "Figure 3-2" in "CHAPTER: FLASH MEMORY" for the configuration diagram.

■ Registers

None.

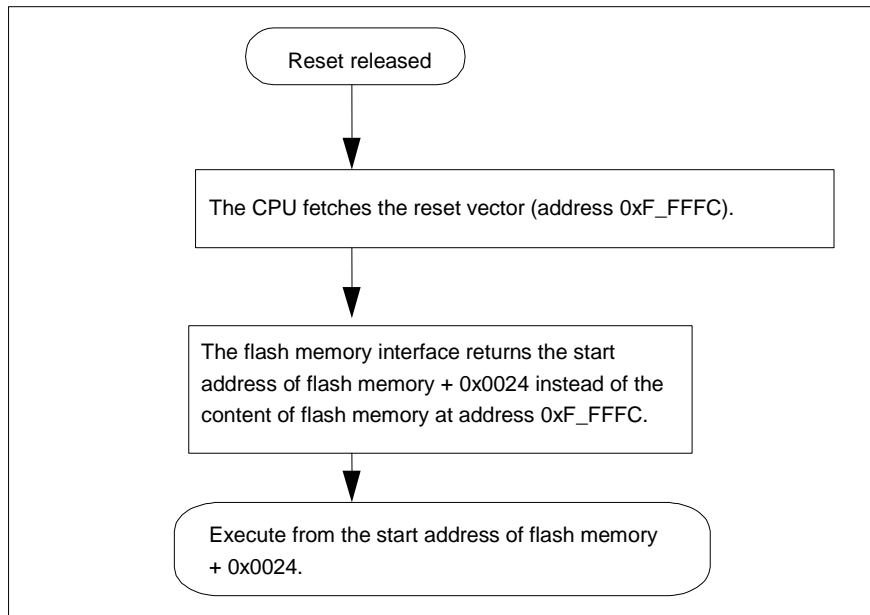
2. Operation Explanation

This section explains the operation of the FixedVector function.

■ Operation After Reset Released

In the following flow, the start address of flash memory + 0x0024 is returned instead of the content of 0xF_FFFC in flash memory when the reset is released.

Figure 2-1 Operation Flow after Reset



■ Usage

After the reset is released, this series executes from the start address of flash memory + 0x0024 instead of the value written at address 0x000F_FFFC.

■ Notes

During reads from addresses 0x000F_FFFC to 0x000F_FFFF other than reset vector fetch (Example: the call destination when INT #00H is executed while TBR is its initial value (=0x000F_FC00)), the content of flash memory at the addresses 0x000F_FFFC to 0x000F_FFFF is returned.

CHAPTER: I/O PORTS

This chapter explains the I/O ports.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains the overview of the I/O ports.

This section explains the setting for assigning to the external pins (peripherals and external bus) and using external pins as the I/O port.

2. Features

This section explains features of the I/O ports.

- **I/O multiplexing**

If the I/O of multiple peripherals is assigned to one external pin, one of these peripherals is selected to be used.

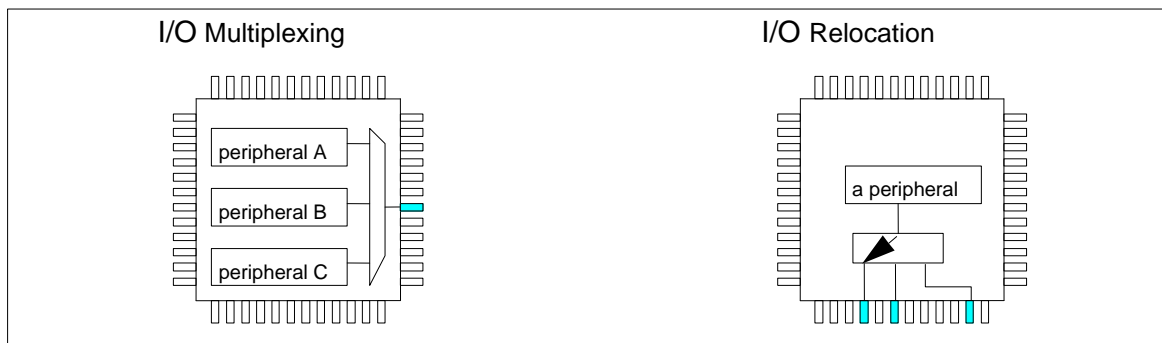
- **I/O relocation**

If one pin for one peripheral can serve multiple external pins for I/O, one of these external pins is selected to be used.

- **PORT function**

External pins can be used for general-purpose I/O: if they are used for output, their values can be set and if they are used for input, input values assigned to them can be read.

Figure 2-1 Diagram of I/O Multiplexing, I/O Relocation



3. Configuration

This section explains the configuration of the I/O ports.

No configuration diagram is provided.

4. Registers

This section explains registers of the I/O ports.

Address	Registers				Register function
	+0	+1	+2	+3	
0x0000	PDR00	PDR01	PDR02	PDR03	Port data register 00 to 13 Port data register A to H
0x0004	PDR04	PDR05	PDR06	PDR07	
0x0008	PDR08	PDR09	PDR10	PDR11	
0x000C	PDR12	PDR13	Reserved	Reserved	
0x0010	PDRA	PDRB	PDRC	PDRD	
0x0014	PDRE	PDRF	PDRG	PDRH	
0x0E00	DDR00	DDR01	DDR02	DDR03	Data direction register 00 to 13 Data direction register A to H
0x0E04	DDR04	DDR05	DDR06	DDR07	
0x0E08	DDR08	DDR09	DDR10	DDR11	
0x0E0C	DDR12	DDR13	Reserved	Reserved	
0x0E10	DDRA	DDRB	DDRC	DDRD	
0x0E14	DDRE	DDRF	DDRG	DDRH	
0x0E20	PFR00	PFR01	PFR02	PFR03	Port function register 00 to 13 Port function register A to H
0x0E24	PFR04	PFR05	PFR06	PFR07	
0x0E28	PFR08	PFR09	PFR10	PFR11	
0x0E2C	PFR12	PFR13	Reserved	Reserved	
0x0E30	PFRA	PFRB	PFRC	PFRD	
0x0E34	PFRE	PFRF	PFRG	PFRH	
0x0E40	PDDR00	PDDR01	PDDR02	PDDR03	Input data direct read register 00 to 13 Input data direct read register A to H
0x0E44	PDDR04	PDDR05	PDDR06	PDDR07	
0x0E48	PDDR08	PDDR09	PDDR10	PDDR11	
0x0E4C	PDDR12	PDDR13	Reserved	Reserved	
0x0E50	PDDRA	PDDRB	PDDRC	PDDRDR	
0x0E54	PDDRE	PDDRF	PDDRG	PDDRH	
0x0E60	EPFR00	EPFR01	EPFR02	EPFR03	Extended port function register 00 to 55
0x0E64	EPFR04	EPFR05	EPFR06	EPFR07	
0x0E68	EPFR08	EPFR09	EPFR10	EPFR11	

Address	Registers				Register function
	+0	+1	+2	+3	
0x0E6C	EPFR12	EPFR13	EPFR14	EPFR15	Extended port function register 00 to 55
0x0E70	EPFR16	EPFR17	EPFR18	EPFR19	
0x0E74	EPFR20	EPFR21	EPFR22	EPFR23	
0x0E78	EPFR24	EPFR25	EPFR26	EPFR27	
0x0E7C	EPFR28	EPFR29	EPFR30	EPFR31	
0x0E80	EPFR32	EPFR33	EPFR34	EPFR35	
0x0E84	EPFR36	EPFR37	EPFR38	EPFR39	
0x0E88	EPFR40	EPFR41	EPFR42	EPFR43	
0x0E8C	EPFR44	EPFR45	EPFR46	EPFR47	
0x0E90	EPFR48	EPFR49	EPFR50	EPFR51	
0x0E94	EPFR52	EPFR53	EPFR54	EPFR55	
0x0EA0	PPCR00	PPCR01	PPCR02	PPCR03	
0x0EA4	PPCR04	PPCR05	PPCR06	PPCR07	
0x0EA8	PPCR08	PPCR09	PPCR10	PPCR11	
0x0EAC	PPCR12	PPCR13	Reserved	Reserved	
0x0EB0	PPCRA	PPCRB	PPCRC	PPCRD	
0x0EB4	PPCRE	PPCRF	PPCRG	PPCRH	
0x0EC0	PPER00	PPER01	PPER02	PPER03	Port pull-up/down enable register 00 to 13 Port pull-up/down enable register A to H
0x0EC4	PPER04	PPER05	PPER06	PPER07	
0x0EC8	PPER08	PPER09	PPER10	PPER11	
0x0ECC	PPER12	PPER13	Reserved	Reserved	
0x0ED0	PPERA	PPERB	PPERC	PPERD	
0x0ED4	PPERE	PPERF	PPERG	PPERH	
0x0EE0	PILR00	PILR01	PILR02	PILR03	
0x0EE4	PILR04	PILR05	PILR06	PILR07	
0x0EE8	PILR08	PILR09	PILR10	PILR11	
0x0EEC	PILR12	PILR13	Reserved	Reserved	
0x0EF0	PILRA	PILRB	PILRC	PILRD	
0x0EF4	PILRE	PILRF	PILRG	PILRH	

Address	Registers				Register function
	+0	+1	+2	+3	
0x0F00	Reserved	Reserved	Reserved	Reserved	Extended port input level selection register 06 to 13
0x0F04	Reserved	Reserved	EPILR06	EPILR07	
0x0F08	EPILR08	EPILR09	EPILR10	EPILR11	
0x0F0C	EPILR12	EPILR13	Reserved	Reserved	
0x0F20	Reserved	Reserved	Reserved	Reserved	Port output drive register 06 to 13
0x0F24	Reserved	Reserved	PODR06	PODR07	
0x0F28	PODR08	PODR09	PODR10	PODR11	
0x0F2C	PODR12	PODR13	Reserved	Reserved	
0x0F38	EPODR06	EPODR07	EPODR08	Reserved	Extended port output drive register 06 to 08
0x0F3C	EPODRGD	EPODRGF	Reserved	Reserved	Extended port output drive register (GDC interface, graphics FLASH interface)
0x0F40	PORTEN	Reserved	Reserved	Reserved	Port input enable register

4.1. Port Data Register 00 to 13, A to H : PDR00 to PDR13, PDRA to PDRH (Port Data Register 00-13,A-H)

The bit configuration of port data register 00 to 13, A to H is shown below.

These registers hold the output levels of the pins corresponding to individual ports that are in output mode.

■ PDR00 to PDR12, PDRG : Address 0000_H to 000C_H, 0016_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W

■ PDR13 : Address 000D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	X	X	X	X	X	X	X	X
Attribute	R,RM/W	R,RM/W	RX,WX	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W

■ PDRA to PDRF : Address 0010_H to 0015_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	X	X	X	X	X	X	1	1
Attribute	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R,RM/W	R1,WX	R1,WX

■ PDRH : Address 0017_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				P3	Reserved		
Initial value	1	1	1	1	X	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R,RM/W	R1,WX	R1,WX	R1,WX

[bit7 to bit0] P (Port) : Port data setting bits

These bits set the output level of external pins P000, P001, ..., when the ports are in output mode.

PDR00:P[7:0] is for external pins P007 to P000

PDR01:P[7:0] is for external pins P017 to P010

PDR02:P[7:0] is for external pins P027 to P020

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	Output of "0"
1	Output of "1"

The value read by a read-modify instruction is determined based on the combination with the data direction register (DDR).

DDR	Reading by read-modify instruction	PDR reading value
1	No	The PDR value can be read.
1	Yes	The PDR value can be read.
0	No	The pin value can be read.
0	Yes	The PDR value can be read.

PDR13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.2. Data Direction Register 00 to 13, A to H : DDR00 to DDR13, DDRA to DDRH (Data Direction Register 00-13,A-H)

The bit configuration of data direction register 00 to 13, A to H is shown below. .

These registers set the I/O directions of the pins when they function as ports. If a pin is to be used for input for a peripheral, the corresponding bit must be set for input.

■ DDR00 to DDR12, DDRG : Address 0E00_H to 0E0C_H, 0E16_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ DDR13 : Address 0E0D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R0,W0	R/W	R/W	R/W	R/W	R/W

■ DDRA to DDRF : Address 0E10_H to 0E15_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	0	0	0	0	0	0	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R1,WX	R1,WX

■ DDRH : Address 0E17_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				P3	Reserved		
Initial value	1	1	1	1	0	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R1,WX	R1,WX	R1,WX

[bit7 to bit0] P (Port) : Data direction selection bits

These bits set the I/O direction of external pins P000, P001, ..., when the ports are in output mode.

DDR00:P[7:0] is for external pins P007 to P000

DDR01:P[7:0] is for external pins P017 to P010

DDR02:P[7:0] is for external pins P027 to P020

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	Input (Initial value)
1	Output

DDR13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.3. Port Function Register 00 to 13, A to H : PFR00 to PFR13, PFRA to PFRH (Port Function Register 00-13,A-H)

The bit configuration of port function register 00 to 13, A to H is shown below. .

These registers specify whether or not the pins are used to function as ports. If a pin is to be used as a peripheral's input pin, the corresponding bit register must be set for the port function.

■ **PFR00 to PFR04, PFR06 to PFR08, PFR10, PFR11 : Address 0E20_H, to 0E24_H, 0E26_H to 0E28_H, 0E2A_H, 0E2B_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **PFR05 : Address 0E25_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	P[6:0]						
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **PFR09, PFR12 : Address 0E29_H, 0E2C_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7]	Reserved	P[5:0]					
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W

■ **PFR13 : Address 0E2D_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			P[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W	R/W	R/W

■ **PFRA to PFRC : Address 0E30_H to 0E32_H**
(Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	0	0	0	0	0	0	1	1
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R1,WX	R1,WX

■ **PFRD to PFRF : Address 0E33_H to 0E35_H**
(Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	0	0	0	0	0	0	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R1,WX	R1,WX

■ **PFRG : Address 0E36_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:3]					Reserved		
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R0,W0	R0,W0	R0,W0

■ **PFRH : Address 0E37_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	1	1	1	1	0	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0	R1,WX	R1,WX	R1,WX

[bit7 to bit0] P (Port) : Port function selection bits

These bits are used to set the port function.

PFR00:P[7:0] is for external pins P007, P006 to P000

PFR01:P[7:0] is for external pins P017, P016 to P010

PFR02:P[7:0] is for external pins P027, P026 to P020

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	Port function or peripheral input pin (Initial value)
1	Peripheral I/O (bidirectional) pin, peripheral output pin, or external bus pin(set by EPFR)

4.4. Input Data Direct Register 00 to 13, A to H : PDDR00 to PDDR13, PDDRA to PDDRH (Port Data Direct Register 00-13,A-H)

The bit configuration of input data direct register 00 to 13, A to H is shown below.

These registers can always show the voltage levels of individual external pins. These registers can always be read without condition.

■ PDDR00 to PDDR12, PDDRG : Address 0E40_H to 0E4C_H, 0E56_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ PDDR13 : Address 0E4D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	X	X	0	X	X	X	X	X
Attribute	R,WX	R,WX	R0,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ PDDRA to PDDRF : Address 0E50_H to 0E55_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	X	X	X	X	X	X	1	1
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R1,WX	R1,WX

■ PDDRH : Address 0E57_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				P3	Reserved		
Initial value	1	1	1	1	X	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R,WX	R1,WX	R1,WX	R1,WX

[bit7 to bit0] P (Port) : read bits

The value at the external pin can be read.

PDDR00:P[7:0] is for external pins P007 to P000

PDDR01:P[7:0] is for external pins P017 to P010

PDDR02:P[7:0] is for external pins P027 to P020

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	Low level
1	High level

PDDR13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.5. Port Pull-up/down Control Register 00 to 13, A to H : PPCR00 to PPCR13, PPCRA to PPCRH (Port Pull-up/down Control Register 00-13,A-H)

The bit configuration of port pull-up/down control register 00 to 13, A to H is shown below.

These registers are used to select pull-up or pull-down for each port. These registers are functioned for input condition pins only. These registers are combined with the pull-up/down enable register (PPER) for this setting.

■ PPCR00 to PPCR12, PCRG : Address 0EA0_H to 0EAC_H, 0EB6_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PPCR13 : Address 0EAD_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PPCRA to PPCRF : Address 0EB0_H to 0EB5_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R1,WX	R1,WX

■ PPCRH : Address 0EB7_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				P3	Reserved		
Initial value	1	1	1	1	1	1	1	1
Attribute	R1, WX	R1, WX	R1,WX	R1, WX	R/W	R1, WX	R1, WX	R1, WX

[bit7 to bit0] P (Port) : Pull-up/down control selection bits

PPCR00:P[7:0] is for external pins P007 to P000

PPCR01:P[7:0] is for external pins P017 to P010

PPCR02:P[7:0] is for external pins P027 to P020

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	Pull-down
1	Pull-up (Initial value)

See "9. List of Pin Functions" and "11. I/O Circuit Types" of "CHAPTER: OVERVIEW" for the presence of pull-up/pull-down.

PPCR13:bit5 is a reserved bit.

Writing and reading are not effective.

PPCR13:P[7:6] is a reserved bit in dual clock products.

Writing and reading are not effective.

4.6. Port Pull-up/down Enable Register 00 to 13, A to H : PPER00 to PPER13, PPERA to PPERH (Port Pull-up/down Enable Register 00-13,A-H)

The bit configuration of port pull-up/down enable register 00 to 13, A to H is shown below.

These registers are used to enable pull-up or pull-down each port. These registers are functioned for input condition pins only. These registers are combined with the pull-up/down control register (PPCR) for this setting.

■ PPER00 to PPER12, PPERG : Address 0EC0_H, 0EC1_H to 0ECC_H, 0ED6_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PPER13 : Address 0ECD_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PPERA to PPERF : Address 0ED0_H to 0ED5_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	0	0	0	0	0	0	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R1,WX	R1,WX

■ PPERH : Address 0ED7_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				P3	Reserved		
Initial value	1	1	1	1	0	1	1	1
Attribute	R1, WX	R1, WX	R1,WX	R1, WX	R/W	R1, WX	R1, WX	R1, WX

[bit7 to bit0] P (Port) : Pull-up/down enable selection bits

PPER00:P[7:0] is for external pins P007 to P000

PPER01:P[7:0] is for external pins P017 to P010

PPER02:P[7:0] is for external pins P027 to P020

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	Pull-up/down disabled (Initial value)
1	Pull-up/down enabled

See "9. List of Pin Functions" and "11. I/O Circuit Types" of "CHAPTER: OVERVIEW" for the presence of pull-up/pull-down of each port.

The attribute of PPER13[5] is R/W. Write does not cause any effect.

PPER13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.7. Port Input Level selection Register 00 to 13, A to H : PILR00 to PILR13, PILRA to PILRH (Port Input Level Register 00-13, A-H)

The bit configuration of port input level selection register 00 to 13, A to H is shown below.

These registers are used to set input levels for individual ports. Glitch input may occur at a pin. Therefore, if the pin is used to supply external input clock or trigger to a peripheral, the peripheral must be disabled.

These registers, when used, are paired with the extended port input level selection register (EPILR).

■ PILR00 to PILR12, PILRG : Address 0EE0_H to 0EEC_H, 0EF6_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PILR13 : Address 0EED_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R1,W1	R/W	R/W	R/W	R/W	R/W

■ PILRA to PILRF : Address 0EF0_H to 0EF5_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:2]						Reserved	
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R1,WX	R1,WX

■ PILRH : Address 0EF7_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				P3	Reserved		
Initial value	1	1	1	1	1	1	1	1
Attribute	R1, WX	R1, WX	R1,WX	R1, WX	R/W	R1, WX	R1, WX	R1, WX

[bit7 to bit0] P (Port) : Port input level selection bits

PILR00:P[7:0] is for external pins P007 to P000

PILR01:P[7:0] is for external pins P017 to P010

PILR02:P[7:0] is for external pins P027 to P020

(A similar process continues)

The assignment is as shown above.

(Port setting in 5V interface) →P06x,P07x,P08x,P09x,P10x,P11x,P12x,P13x

PILR:P[n]	EPILR:P[n]	Input level	Remarks
0	0	CMOS Schmitt $V_{IL}=0.3V_{cc}$ $V_{IH}=0.7V_{cc}$	
0	1	TTL $V_{IL}=0.8[V]$ $V_{IH}=2.0[V]$	
1	0	Automotive $V_{IL}=0.5V_{cc}$ $V_{IH}=0.8V_{cc}$	Initial value
1	1	CMOS $V_{IL}=0.3V_{cc}$ $V_{IH}=0.7V_{cc}$	

(Port setting in 3.3V interface) →P00x,P01x,P02x,P03x,P04x,P05x,PAx,PBx,PCx,PDx,
PEx,PFx,PGx,PHx

PILR:P[n]	Input level	Remarks
0	TTL $V_{IL}=0.8[V]$ $V_{IH}=2.0[V]$	
1	CMOS Schmitt $V_{IL}=0.3V_{cc}$ $V_{IH}=0.7V_{cc}$	Initial value

PILR13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.8. Extended Port Input Level selection Register 06 to 13 : EPILR06 to EPILR13 (Extended Port Input Level Register 06-13)

The bit configuration of extended port input level selection register 06 to 13 is shown below.

These registers, when used, are paired with the port input level selection register (PILR). See “4.7. Port Input Level selection Register 00 to 13, A to H: PILR00 to PILR13, PILRA to PILRH (Port Input Level Register 00-13,A-H)”.

■ EPILR06 to EPILR12 : Address 0F06_H to 0F0C_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ EPILR13 : Address 0F0D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] P (Port) : Extended port input level selection bits

EPILR06:P[7:0] is for external pins P067 to P060

EPILR07:P[7:0] is for external pins P077 to P070

EPILR08:P[7:0] is for external pins P087 to P080

(A similar process continues)

The assignment is as shown above. For settings, see the section of PILR.

The attribute of EPILR13[5] is R/W. Write does not cause any effect.

EPILR13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.9. Port Output Drive Register 06 to 13 : PODR06 to PODR13 (Port Output Drive Register 06-13)

The bit configuration of port output drive register 06 to 13 is shown below.

These registers are used to set drive levels for individual ports.

■ PODR06 to PODR12 : Address 0F26_H to 0F2C_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PODR13 : Address 0F2D_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:6]		Reserved	P[4:0]				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] P (Port) : Port output drive selection bits

PODR06:P[7:0] is for external pins P067 to P060

PODR07:P[7:0] is for external pins P077 to P070

PODR08:P[7:0] is for external pins P087 to P080

(A similar process continues)

The assignment is as shown above.

P[n]	Operation
0	1 mA
1	2 mA

[Only P127, P130, P132, and P133 pins]

When the multi-function serial interface is selected and I²C has been selected by the operational mode of the multi-function serial interface, it becomes 3 mA. In other cases, the setting in the above table needs to be followed.

The drive level of a pin that doubles as the output pin for a stepping motor controller can be set to be 1 mA/ 2 mA/30 mA by the combination with a extended port output drive register (EPODR) setting.

If a pin is specified as the output pin for a stepping motor controller, the drive level at the pin must be 30mA regardless of the PODR register setting.

PODR:P[n]	EPODR:P[n]	Operation	Remarks
0	0	1 mA	Initial value
1	0	2 mA	
0	1	30 mA	
1	1	2 mA	

The attribute of PODR13[5] is R/W. Write does not cause any effect.

PODR13[7:6] is reserved because the built-in sub clock products (dual clock products) do not have the assigned pins.

4.10. Extended Port Output Drive Register 06 to 08 : EPODR06 to EPODR08 (Extended Port Output Drive Register 06-08)

The bit configuration of extended port output drive register 06 to 08 is shown below.

These registers are used to set drive levels for SMC ports.

■ **EPODR06 to EPODR08 : Address 0F38_H to 0F3A_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	P[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

See "4.9. Port Output Drive Register 06 to 13 : PODR06 to PODR13 (Port Output Drive Register 06-13)" for the setting.

4.11. Extended Port Output Drive Register for Graphic Digital Interface: EPODRGD

The bit configuration of the extended port output drive register GDC interface is shown below.

This register is used to set drive levels (2mA/5mA/10mA/20mA) for Graphic Digital I/F in each group.

■ EPODRGD: Address 0F3C_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				GDI1[1:0]		GDI0[1:0]	
Initial value	1	1	1	1	1	0	1	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W

[bit3, bit2] GDI1[1:0] GDC interface port output drive selection bits 1
These bits select following port output drive.

PG[4]

GDI1[1:0]	Operation
00	2 mA
01	5 mA
10	10 mA (Initial value)
11	20 mA

[bit1, bit1] GDI0[1:0] GDC interface port output drive selection bits 0
These bits select following port output drive.

PA[7:2], PB[7:2], PC[7:2], PD[7:2], PE[7:2], PF[7:2], PG[7:5], PG[3:0], PH[3]

GDI0[1:0]	Operation
00	2 mA
01	5 mA
10	10 mA (Initial value)
11	20 mA

4.12. Extended Port Output Drive Register for Graphic Flash Interface: EPODRGF

The bit configuration of the extended port output drive register for the graphic flash interface is shown below.

This register is used to set drive levels (2mA/5mA/10mA/20mA) for Graphic FLASH interface in each group.

■ EPODRGF: Address 0F3D_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		GFI2[1:0]		GFI1[1:0]		GFI0[1:0]	
Initial value	1	1	1	0	1	0	1	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit5, bit4] GFI2[1:0] Graphic FLASH interface port output drive selection bits 2
These bits select following port output drive.

P05[6:3]

GFI2[1:0]	Operation
00	2 mA
01	5 mA
10	10 mA (Initial value)
11	20 mA

[bit3, bit2] GFI1[1:0] Graphic FLASH interface port output drive selection bits 1
These bits select following port output drive.

P03[7], P04[7:0]

GFI1[1:0]	Operation
00	2 mA
01	5 mA
10	10 mA (Initial value)
11	20 mA

[bit1, bit0] GFIO[1:0] Graphic FLASH interface port output drive selection bits 0
These bits select following port output drive.

P00[7:0], P01[7:0], P02[7:0], P03[6:0], P05[7], P05[2:0]

GFIO[1:0]	Operation
00	2 mA
01	5 mA
10	10 mA (Initial value)
11	20 mA

4.13. Extended Port Function Register 00 to 55 : EPFR00 to EPFR55 (Extended Port Function Register 00-55)

The bit configuration of extended port function register 00 to 55 is shown below.

These registers control switching between the peripheral and the external bus, I/O relocation and I/O multiplexing. Unlike other port registers, these registers have an enable bit for each peripheral, rather than for each pin.

When I/O relocation is executed, glitch occurs by switching and operation may happen by recognition as a signal change. Therefore, execute I/O relocation for input neglecting inputs from peripheral resource. The external interrupt flag must be cleared before the interrupt is enabled.

Pin assignment to peripheral resources is made by the registers of PFR and EPFR. However, since all registers cannot be changed at one time, I/O relocation for outputs must be executed in the port setting state (PFRn:P[n]=0).

4.13.1. Extended Port Function Register 00, 01 : EPFR00, EPFR01 (Extended Port Function Register 00, 01)

The bit configuration of extended port function register 00, 01 is shown below.

These registers are used to select input pins for input capture. (I/O relocation)

■ **EPFR00 : Address 0E60_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ICU3E[1:0]		ICU2E[1:0]		ICU1E[1:0]		ICU0E[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR01 : Address 0E61_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				ICU5E[1:0]		ICU4E[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W	R/W

[bit7 to bit4] Reserved bits
These bits must be written to "0".

- ICU0E[1:0] Input capture ch.0 input pin selection
- ICU1E[1:0] Input capture ch.1 input pin selection
- ICU2E[1:0] Input capture ch.2 input pin selection
- ICU3E[1:0] Input capture ch.3 input pin selection
- ICU4E[1:0] Input capture ch.4 input pin selection
- ICU5E[1:0] Input capture ch.5 input pin selection

ICUnE[1:0] (n=0 to 5)	Operation
00	Input from the ICUn pin
01	Input from the ICUn_1 pin
10	Input from the ICUn_2 pin
11	Reserved (Input from the ICUn_2 pin)

4.13.2. Extended Port Function Register 02 to 05 : EPFR02 to EPFR05 (Extended Port Function Register 02-05)

The bit configuration of extended port function register 02 to 05 is shown below.

These registers are used to enable reload timer output and to select output/input pins. (I/O relocation and I/O multiplexing)

■ EPFR02 : Address 0E62_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			TOT0E[2:0]			TIN0E[1:0]	
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ EPFR03 : Address 0E63_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			TOT1E[2:0]			TIN1E[1:0]	
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ EPFR04 : Address 0E64_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			TOT2E[2:0]			TIN2E[1:0]	
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ EPFR05 : Address 0E65_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			TOT3E[2:0]			TIN3E[1:0]	
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

TOT0E[2:0] Reload timer ch.0 TOT output pin selection

TIN0E[1:0] Reload timer ch.0 TIN input pin selection

TOT1E[2:0] Reload timer ch.1 TOT output pin selection

TIN1E[1:0] Reload timer ch.1 TIN input pin selection

TOT2E[2:0] Reload timer ch.2 TOT output pin selection

TIN2E[1:0] Reload timer ch.2 TIN input pin selection

TOT3E[2:0] Reload timer ch.3 TOT output pin selection

TIN3E[1:0] Reload timer ch.3 TIN input pin selection

TOTnE[2:0] (n=0 to 3)	Operation
000	No output
xx1	Output from the TOTn pin
x1x	Output from the TOTn_1 pin
1xx	Output from the TOTn_2 pin

TINnE[1:0] (n=0 to 3)	Operation
00	Input from the TINn pin
01	Input from the TINn_1 pin
10	Input from the TINn_2 pin
11	Reserved (Input from the TINn_2 pin)

4.13.3. Extended Port Function Register 06 to 09, 33, 34 : EPFR06 to EPFR09, EPFR33, EPFR34 (Extended Port Function Register 06-09,33,34)

The bit configuration of extended port function register 06 to 09, 33, 34 is shown below.

These registers are used to enable LIN-UART output and to select output/input pins. (I/O relocation and I/O multiplexing)

Note:

Please set SCK/SOT/SIN of LIN-UART to the same group (SCKn/SOTn/SINn or SCKn_1/SOTn_1/SINn_1). It is a prohibition to do relocations as disjointedly as the following examples.

Prohibition example : SCKn/SOTn_1/SINn

■ EPFR06 : Address 0E66_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT2E[1:0]		SCK2E[1:0]		SIN2E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ EPFR07 : Address 0E67_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT3E[1:0]		SCK3E[1:0]		SIN3E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ EPFR08 : Address 0E68_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT4E[1:0]		SCK4E[1:0]		SIN4E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ EPFR09 : Address 0E69_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT5E[1:0]		SCK5E[1:0]		SIN5E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ **EPFR33 : Address 0E81_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT6E[1:0]		SCK6E[1:0]		SIN6E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ **EPFR34 : Address 0E82_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT7E[1:0]		SCK7E[1:0]		SIN7E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

- SOT2E[1:0] LIN-UART ch.2 SOT output pin selection
- SCK2E[1:0] LIN-UART ch.2 SCK output/input pin selection
- SIN2E LIN-UART ch.2 SIN input pin selection
- SOT3E[1:0] LIN-UART ch.3 SOT output pin selection
- SCK3E[1:0] LIN-UART ch.3 SCK output/input pin selection
- SIN3E LIN-UART ch.3 SIN input pin selection
- SOT4E[1:0] LIN-UART ch.4 SOT output pin selection
- SCK4E[1:0] LIN-UART ch.4 SCK output/input pin selection
- SIN4E LIN-UART ch.4 SIN input pin selection
- SOT5E[1:0] LIN-UART ch.5 SOT output pin selection
- SCK5E[1:0] LIN-UART ch.5 SCK output/input pin selection
- SIN5E LIN-UART ch.5 SIN input pin selection

SOTnE[1:0] (n=2 to 5)	Operation
00	No output
01	Output from the SOTn pin
1x	Output from the SOTn_1 pin

SCKnE[1:0] (n=2 to 5)	Operation
00	Non input/output from the SCKn
01	Input from the SCKn / output from the SCKn
10	Input from the SCKn_1 / output from the SCKn_1
11	Reserved (Input from the SCKn_1 / output from the SCKn_1)

SINnE (n=2 to 5)	Operation
0	Input from the SINn pin
1	Input from the SINn_1 pin

SOT6E[1:0] LIN-UART ch.6 SOT output pin selection
 SCK6E[1:0] LIN-UART ch.6 SCK output/input pin selection
 SIN6E LIN-UART ch.6 SIN input pin selection

SOTnE[1:0] (n=6)	Operation
00	No output
01	Output from the SOTn pin
1x	Setting is prohibited

SCKnE[1:0] (n=6)	Operation
00	No input / output from the SCKn pin
01	Input from the SCKn / Output from the SCKn
10	Setting is prohibited
11	Setting is prohibited

SINnE (n=6)	Operation
0	Input from the SINn pin
1	Setting is prohibited

SOT7E[1:0] LIN-UART ch.7 SOT output pin selection
 SCK7E[1:0] LIN-UART ch.7 SCK output/input pin selection
 SIN7E LIN-UART ch.7 SIN input pin selection

SOTnE[1:0] (n=7)	Operation
00	No output
01	Setting is prohibited
1x	Output from the SOTn_1 pin

SCKnE[1:0] (n=7)	Operation
00	No input/output from the SCKn
01	Setting is prohibited
10	Input from the SCKn_1 / Output from the SCKn_1
11	Reserved (Input from the SCKn_1 / Output from the SCKn_1)

SINnE (n=7)	Operation
0	Setting is prohibited
1	Input from the SINn_1

4.13.4. Extended Port Function Register 10 to 15, 45, 46 : EPFR10 to EPFR15, EPFR45, EPFR46 (Extended Port Function Register 10-15,45,46)

The bit configuration of extended port function register 10 to 15, 45, 46 is shown below.

These registers are used to enable PPG output and to select output pins. (I/O relocation and I/O multiplexing)

■ **EPFR10 : Address 0E6A_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	PPG1E[3:0]			PPG0E[2:0]			
Initial value	1	0	0	0	0	0	0	0
Attribute	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR11 : Address 0E6B_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		PPG3E[2:0]			PPG2E[2:0]		
Initial value	1	1	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR12 : Address 0E6C_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		PPG5E[2:0]			PPG4E[2:0]		
Initial value	1	1	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR13 : Address 0E6D_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		PPG7E[2:0]			PPG6E[2:0]		
Initial value	1	1	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR14 : Address 0E6E_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		PPG9E[2:0]			PPG8E[2:0]		
Initial value	1	1	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR15 : Address 0E6F_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	PPG12E[1:0]		PPG11E[1:0]		PPG10E[2:0]		
Initial value	1	0	0	0	0	0	0	0
Attribute	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR45 : Address 0E8D_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PPG17E	PPG16E	PPG15E[1:0]		PPG14E[1:0]		PPG13E[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR46 : Address 0E8E_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		PPG23E	PPG22E	PPG21E	PPG20E	PPG19E	PPG18E
Initial value	1	1	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

- PPG0E[2:0] PPG ch.0 output pin selection
- PPG2E[2:0] PPG ch.2 output pin selection
- PPG3E[2:0] PPG ch.3 output pin selection
- PPG4E[2:0] PPG ch.4 output pin selection
- PPG5E[2:0] PPG ch.5 output pin selection
- PPG6E[2:0] PPG ch.6 output pin selection
- PPG7E[2:0] PPG ch.7 output pin selection
- PPG8E[2:0] PPG ch.8 output pin selection
- PPG9E[2:0] PPG ch.9 output pin selection
- PPG10E[2:0] PPG ch.10 output pin selection

PPGnE[2:0] (n=0,2 to 10)	Operation
000	No output
xx1	Output from the PPGn pin
x1x	Output from the PPGn_1 pin
1xx	Output from the PPGn_2 pin

PPG1E[3:0] PPG ch.1 output pin selection

PPGnE[3:0] (n=1)	Operation
0000	No output
xxx1	Output from the PPGn pin
xx1x	Output from the PPGn_1 pin
x1xx	Output from the PPGn_2 pin
1xxx	Output from the PPGn_3 pin

PPG11E[1:0] PPG ch.11 output pin selection

PPG12E[1:0] PPG ch.12 output pin selection

PPG13E[1:0] PPG ch.13 output pin selection

PPG14E[1:0] PPG ch.14 output pin selection

PPG15E[1:0] PPG ch.15 output pin selection

PPGnE[1:0] (n=11 to 15)	Operation
0x	No output
1x	Output from the PPGn_1 pin

PPG16E PPG ch.16 output pin selection

PPG17E PPG ch.17 output pin selection

PPG18E PPG ch.18 output pin selection

PPG19E PPG ch.19 output pin selection

PPG20E PPG ch.20 output pin selection

PPG21E PPG ch.21 output pin selection

PPG22E PPG ch.22 output pin selection

PPG23E PPG ch.23 output pin selection

PPGnE (n=16 to 23)	Operation
0	No output
1	Output from the PPGn pin

4.13.5. Extended Port Function Register 21 to 23 : EPFR21 to EPFR23 (Extended Port Function Register 21-23)

The bit configuration of extended port function register 21 to 23 is shown below.

These registers are used to enable stepping motor controller output. (I/O multiplexing)

■ **EPFR21 : Address 0E75_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PWM2M1E	PWM2P1E	PWM1M1E	PWM1P1E	PWM2M0E	PWM2P0E	PWM1M0E	PWM1P0E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR22 : Address 0E76_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PWM2M3E	PWM2P3E	PWM1M3E	PWM1P3E	PWM2M2E	PWM2P2E	PWM1M2E	PWM1P2E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR23 : Address 0E77_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PWM2M5E	PWM2P5E	PWM1M5E	PWM1P5E	PWM2M4E	PWM2P4E	PWM1M4E	PWM1P4E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

PWM2M_nE (n=0 to 5) SMC channel n PWM control (M2) output enable

PWM2P_nE (n=0 to 5) SMC channel n PWM control (P2) output enable

PWM1M_nE (n=0 to 5) SMC channel n PWM control (M1) output enable

PWM1P_nE (n=0 to 5) SMC channel n PWM control (P1) output enable

PWM2M _n E (n=0 to 5)	Operation
0	SMC channel n PWM M2 output disabled (Initial value)
1	SMC channel n PWM M2 output enabled

PWM2P_nE, PWM1M_nE and PWM1P_nE (n=0 to 5) are also similar to PWM2M_nE.

4.13.6. Extended Port Function Register 24 : EPFR24 (Extended Port Function Register 24)

The bit configuration of extended port function register 24 is shown below.

This register is used to enable CAN output. (I/O multiplexing)

■ **EPFR24 : Address 0E78_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					TX2E	TX1E	TX0E
Initial value	1	1	1	1	1	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W

TXnE (n=0 to 2) : CAN channel n transmission data output enabled

TXnE (n=0 to 2)	Operation
0	CAN channel n output disabled (Initial value)
1	CAN channel n output enabled

4.13.7. Extended Port Function Register 25 : EPFR25 (Extended Port Function Register 25)

The bit configuration of extended port function register 25 is shown below.

This register is a reserved register.

■ **EPFR25 : Address 0E79_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					EPFR25D[2:0]		
Initial value	1	1	1	1	1	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W0	R/W0	R/W0

EPFR25D[2:0] : Reserved bits
"0" must be written to these bits.

4.13.8. Extended Port Function Register 26 : EPFR26 (Extended Port Function Register 26)

The bit configuration of extended port function register 26 is shown below.

This register is used to enable base timer output. (I/O multiplexing)

■ **EPFR26 : Address 0E7A_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				TIB1E	TIB0E	TIA1E	TIA0E
Initial value	1	1	1	1	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W

TIBnE (n=0, 1) Reserved bits

Setting to these bits does not affect on the operation.

TIA_nE (n=0, 1) Base timer TIOAn output enable

TIA _n E (n=0, 1)	Operation
0	Base timer TIOAn output disabled (Initial value)
1	Base timer TIOAn output enabled

4.13.9. Extended Port Function Register 27, 30 : EPFR27, EPFR30 (Extended Port Function Register 27,30)

The bit configuration of extended port function register 27, 30 is shown below.

These registers are used to enable the real-time clock and sound generator output. (I/O multiplexing and I/O relocation)

■ **EPFR27 : Address 0E7B_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			WOTE	SGO1E	SGA1E	SGO0E	SGA0E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ **EPFR30 : Address 0E7E_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SGO4E[1:0]		SGA4E[1:0]		SGO3E	SGA3E	SGO2E	SGA2E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- SGAnE (n=0 to 3) Sound generator channel n SGA output enable
- SGOnE (n=0 to 3) Sound generator channel n SGO output enable
- WOTE Real time clock overflow output enable

SGAnE (n=0 to 3)	Operation
0	Sound generator channel n SGA output disabled (Initial value)
1	Sound generator channel n SGA output enabled

SGOnE (n=0 to 3) and WOTE are also similar to the above.

- SGA4E [1:0] Sound generator channel 4 SGA output enable
- SGO4E [1:0] Sound generator channel 4 SGO output enable

SGA4E[1:0]	Operation
00	Sound generator channel 4 SGA output disabled (Initial value)
01	Setting prohibited
10	Output from the SG4_1
11	Setting is prohibited

SGO4E[1:0] are also similar to the above.

4.13.10. Extended Port Function Register 28 : EPFR28 (Extended Port Function Register 28)

The bit configuration of extended port function register 28 is shown below.

This register is used to enable free-run timer clock input. (I/O multiplexing)

■ **EPFR28 : Address 0E7C_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				Reserved	Reserved	FRCK1E	FRCK0E
Initial value	1	1	1	1	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0	R/W	R/W

[bit2, bit3] Reserved

"0" must always be written to these bits.

[bit1] FRCK1E : Free-run timer ch.1 clock input selection enable

[bit0] FRCK0E : Free-run timer ch.0 clock input selection enable

FRCKnE (n=0, 1)	Operation
0	Input from the FRCKn (Initial value)
1	Setting is prohibited

4.13.11. Extended Port Function Register 29 : EPFR29 (Extended Port Function Register 29)

The bit configuration of extended port function register 29 is shown below.

This register is used to enable output compare output. (I/O multiplexing and I/O relocation)

■ **EPFR29 : Address 0E7D_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	OCU3E[1:0]		OCU2E[1:0]		OCU1E[1:0]		OCU0E[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

OCUnE[1:0] (n=0 to 3) Output compare channel n output enabled

OCUnE[1:0] (n=0 to 3)	Operation
00	Output compare channel n output disabled (Initial value)
01	Output from the OCUn
10	Setting is prohibited
11	Setting is prohibited

4.13.12. Extended Port Function Register 35, 36 : EPFR35, EPFR36 (Extended Port Function Register 35,36)

The bit configuration of extended port function register 35, 36 is shown below.

These registers are used to enable multi-function serial interface output. (I/O multiplexing and I/O relocation)

■ **EPFR35 : Address 0E83_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT0E[1:0]		SCK0E[1:0]		SIN0E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ **EPFR36 : Address 0E84_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			SOT1E[1:0]		SCK1E[1:0]		SIN1E
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

- SOT0E [1:0] : multi-function serial interface ch.0 SOT output/input pin selection
- SCK0E [1:0] : multi-function serial interface ch.0 SCK output/input pin selection
- SIN0E : multi-function serial interface ch.0 SIN input pin selection
- SOT1E [1:0] : multi-function serial interface ch.1 SOT output/input pin selection
- SCK1E [1:0] : multi-function serial interface ch.1 SCK output/input pin selection
- SIN1E : multi-function serial interface ch.1 SIN input pin selection

SOTnE[1:0] (n=0,1)	Operation
00	No output
01	Input from the SOTn pin / Output from the SOTn pin
1x	Setting is prohibited

SCKnE[1:0] (n=0,1)	Operation
00	No input/output from the SCKn
01	Input from the SCKn / Output from the SCKn
10	Setting is prohibited
11	Setting is prohibited

SINnE (n=0,1)	Operation
0	Input from the SINn pin
1	Setting is prohibited

4.13.13. Extended Port Function Register 48 to 50 : EPFR48 to EPFR50 (Extended Port Function Register48-50)

The bit configuration of extended port function register 48 to 50 is shown below.

These registers are used to set enable/disable for display RGB signal output.

■ **EPFR48 : Address 0E90_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ROUT7E	ROUT6E	ROUT5E	ROUT4E	ROUT3E	ROUT2E	ROUT1E	ROUT0E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR49 : Address 0E91_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GOUT7E	GOUT6E	GOUT5E	GOUT4E	GOUT3E	GOUT2E	GOUT1E	GOUT0E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **EPFR50 : Address 0E92_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BOUT7E	BOUT6E	BOUT5E	BOUT4E	BOUT3E	BOUT2E	BOUT1E	BOUT0E
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

ROUTnE (n=0 to 7) Display R[n] output enabled

ROUTnE (n=0 to 7)	Operation
0	Display RGB(R[n]) output disabled (Initial value)
1	Display RGB(R[n]) output enabled

GOUTnE (n=0 to 7) Display G[n] output enabled

GOUTnE (n=0 to 7)	Operation
0	Display RGB(G[n]) output disabled (Initial value)
1	Display RGB(G[n]) output enabled

BOUtnE (n=0 to 7) Display B[n] output enabled

BOUtnE (n=0 to 7)	Operation
0	Display RGB(B[n]) output disabled (Initial value)
1	Display RGB(B[n]) output enabled

4.13.14. Extended Port Function Register 51, 52 : EPFR51, EPFR52 (Extended Port Function Register 51,52)

The bit configuration of extended port function register 51, 52 is shown below.

These registers are used to set enable/disable for display control signal output and SPI Flash signal output.

■ **EPFR51 : Address 0E93_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			CSOUTE	HSOUTE	VSOUTE	DCKOUTE	DEOUTE
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W

■ **EPFR52 : Address 0E94_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					SPISCK	SPIXCS	SPIDO
Initial value	1	1	1	1	1	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W

- [bit0] DEOUTE : Display effective term output enable
- [bit1] DCKOUTE : Display output standard clock output enable
- [bit2] VSOUTE : Display vertical sync signal output enable
- [bit3] HSOUTE : Display horizontal sync signal output enable
- [bit4] CSOUTE : Display composite sync signal / graphics/ video switch output enable

DEOUTE	Operation
0	Display effective term output disabled (Initial value)
1	Display effective term output enabled

DCKOUTE, VSOUTE, HSOUTE and CSOUTE are similar to the above.

- [bit0] SPIDO : SPI Flash data output enabled
- [bit1] SPIXCS : SPI Flash chip selection output enable
- [bit2] SPISCK : SPI Flash clock output enable

SPIDO	Operation
0	SPI Flash data output disabled (Initial value)
1	SPI Flash data output enabled

SPIXCS and SPISCK are similar to the above.

4.13.15. Extended Port Function Register 55 : EPFR55 (Extended Port Function Register 55)

The bit configuration of extended port function register 55 is shown below.

This register is used to set enable/disable for the external bus function.

■ **EPFR55 : Address 0E97_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						EXTBUS1E	EXTBUS0E
Initial value	1	1	1	1	1	1	0	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

[bit0] EXTBUS0E : External bus output enable 0

[bit1] EXTBUS1E : External bus output enable 1

EXTBUS1E	EXTBUS0E	Operation
0	0	External bus output disabled regardless of PFR's setting
0	1	GDC external bus output enabled (Initial value)
1	0	Setting is prohibited
1	1	GDC external bus output enabled

4.13.16. Extended Port Function Register 16 to 20, 31, 32, 37 to 44, 47, 53, 54 : EPFR16 to EPFR20, EPFR31, EPFR32, EPFR37 to EPFR44, EPFR 47, EPFR53, EPFR54(Extended Port Function Register 16-20, 31, 32, 37-44, 47, 53, 54)

The bit configuration of extended port function register 16 to 20, 31, 32, 37 to 44,47,53,54 is shown below.

These are reserved registers. These must not be used.

■ EPFR16 : Address 0E70_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR16D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ EPFR17 : Address 0E71_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR17D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ EPFR18 : Address 0E72_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR18D[7:0]							
Initial value	1	0	0	0	0	0	0	0
Attribute	R1,W1	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ EPFR19 : Address 0E73_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR19D[7:0]							
Initial value	1	1	1	1	1	1	1	1
Attribute	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1

■ EPFR20 : Address 0E74_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	EPFR20D[6:0]						
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W1	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1	R1,W1

■ **EPFR31 : Address 0E7F_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR31D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR32 : Address 0E80_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR32D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR37 : Address 0E85_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR37D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR38 : Address 0E86_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			EPFR38D[4:0]				
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR39 : Address 0E87_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR39D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR40 : Address 0E88_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		EPFR40D[5:0]					
Initial value	1	1	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR41 : Address 0E89_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					EPFR41D[2:0]		
Initial value	1	1	1	1	1	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0	R0,W0

■ **EPFR42 : Address 0E8A_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						EPFR42D[1:0]	
Initial value	1	1	1	1	1	1	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0

■ **EPFR43 : Address 0E8B_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR43D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR44 : Address 0E8C_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EPFR44D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR47 : Address 0E8F_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							EPFR47D
Initial value	1	1	1	1	1	1	1	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0

■ **EPFR53 : Address 0E95_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			EPFR53D[4:0]				
Initial value	1	1	1	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **EPFR54 : Address 0E96_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				EPFR54D[3:0]			
Initial value	1	1	1	1	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0	R0,W0	R0,W0

4.14. Port Input Enable Register : PORTEN(PORT ENable register)

The bit configuration of the port input enable register is shown below.

This register contains control-bit to enable port input. At a power-on reset, inputs to most pins are disabled in order to avoid pass-through current fluctuations before the ports are configured by software. For information on pins whose inputs are disabled, see "APPENDIX-D: Pin status in CPU Status". After each port pin is configured for its function by software, Global PORT Enable (GPORTEN) bit must be set to "1" to enable input.

■ PORTEN : Address 0F40_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							GPORTEN
Initial value	1	1	1	1	1	1	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

[bit0] GPORTEN (Global PORT ENable) : Global input enable

GPORTEN	Operation
0	Most of pins are set input-disabled to cut off pass-through current at unstable condition. See "APPENDIX-D: Pin Status in CPU Status" for the pin that is input-disabled at initial state by reset.
1	The input is enabled by this bit.

5. Operation

This section explains operations of I/O ports.

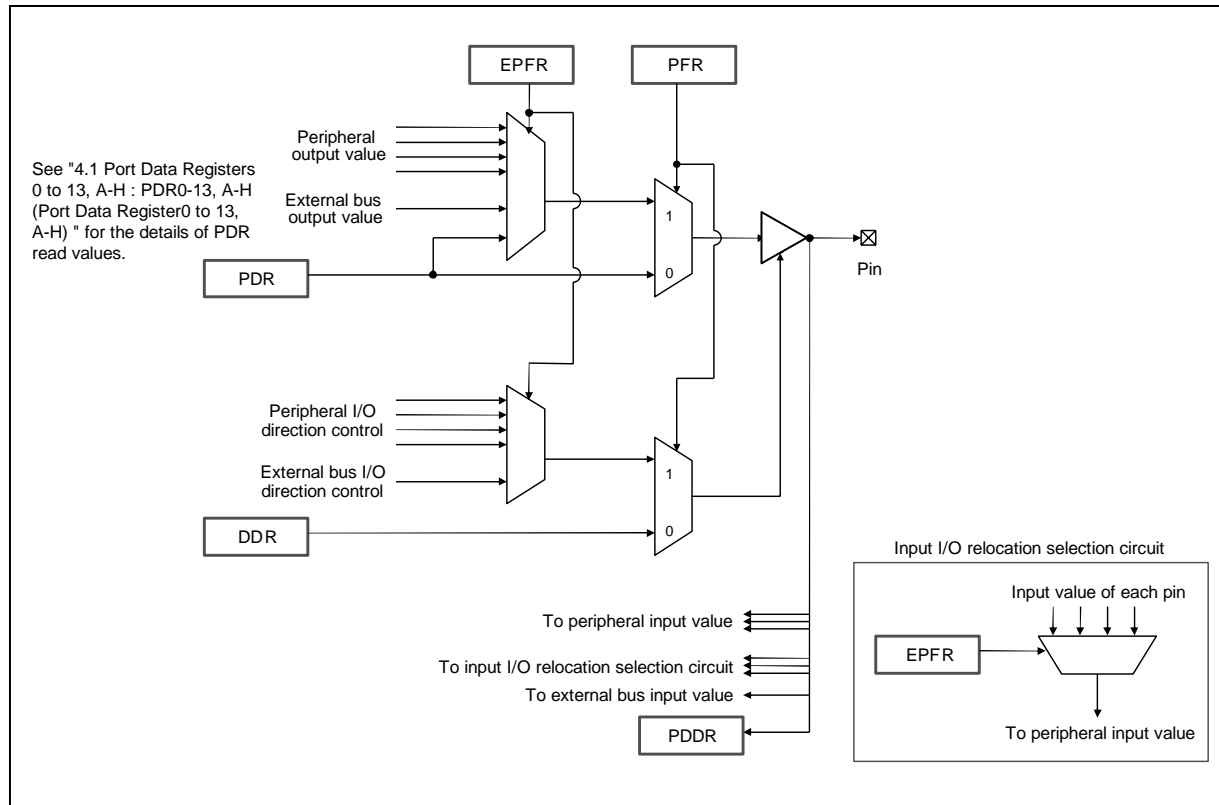
- 5.1. Pin I/O Assignment
- 5.2. EPFR Setting Priority
- 5.3. Notes on Input I/O Relocation Setting
- 5.4. Input Interception by GPORTEN
- 5.5. Notes on Pins with the AD Converter Function
- 5.6. Setting when Using the Base Timer TIOA1 Pin
- 5.7. Operation at Wake Up from Power Shutdown

5.1. Pin I/O Assignment

The pin I/O assignment is shown below.

Pin I/O assignment is explained here. The I/O direction of each pin is controlled based on the configuration shown below.

Figure 5-1 Configuration of Pin I/O Directions, Output Value Selection, and Input Value Retrieval



As explained in the pertinent section concerning pin assignment, first change the PFR setting to enable the port function. Since the pin then functions as a port, also set the DDR and PDR values in advance if necessary. When doing this, note that the I/O direction of the pin is once set as specified by the DDR. For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".

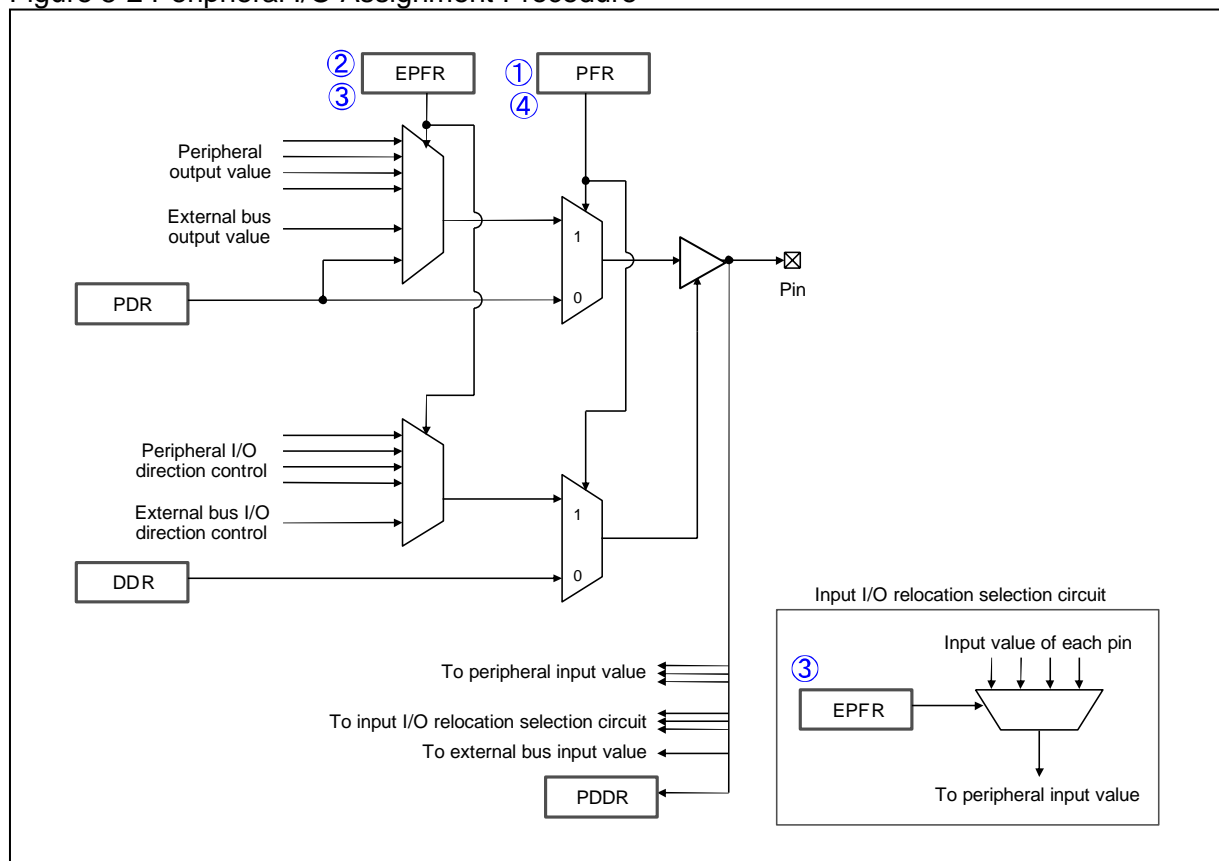
5.1.1. Peripheral I/O (bidirectional) Pin Assignment

The peripheral I/O (bidirectional) pin assignment is shown below.

■ Preparation

- Since the pin once functions as a port as the result of step (1), also set the DDR and PDR values in advance if necessary.
 - For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".
1. Set the PFR for the applicable pin to enable the port function.
 2. Disable the EPFRs for all other peripherals to be used by the relevant pin.
 3. If the relevant pin is also used for an external bus or the relevant peripheral is one of the targets of I/O multiplexing, set the EPFR of the relevant peripheral. In addition, if the relevant peripheral has the I/O relocation function, set the EPFR of the relevant peripheral.
 4. Set the PFR for the peripheral.

Figure 5-2 Peripheral I/O Assignment Procedure



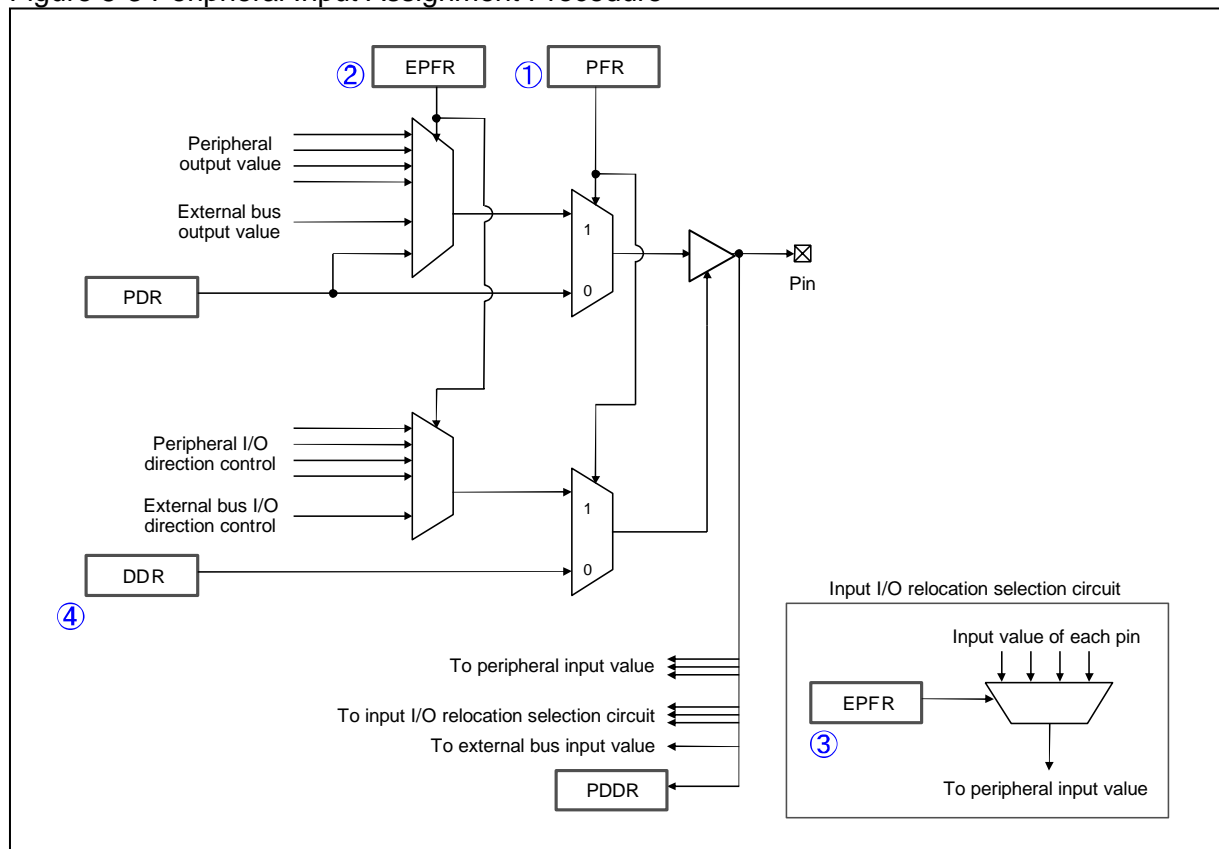
5.1.2. Peripheral Input Assignment

The peripheral input assignment is shown below

■ Preparation

- Since the pin will once function as a port as the result of step (1), set the DDR and PDR values in advance if necessary.
 - For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".
1. Set the PFR of the applicable pin to enable the port function.
 2. Disable the EPFRs for all other peripherals to be used by the relevant pin.
 3. An addition, if the relevant peripheral has the I/O relocation function, set the EPFR of the relevant peripheral.
 4. Set the DDR for input.

Figure 5-3 Peripheral Input Assignment Procedure



Note:

As shown in the figure above, if the pin is set for peripheral output etc., its output value is supplied to other peripheral inputs sharing the same pin.

Example: Since INT10 and PPG2_2 are assigned to the same pin (pin number 102-P111), external interrupt 10 can be generated at the PPG2 output by setting the pin for PPG2_2 peripheral output.

5.1.3. Peripheral Output Assignment

The peripheral output assignment is shown below.

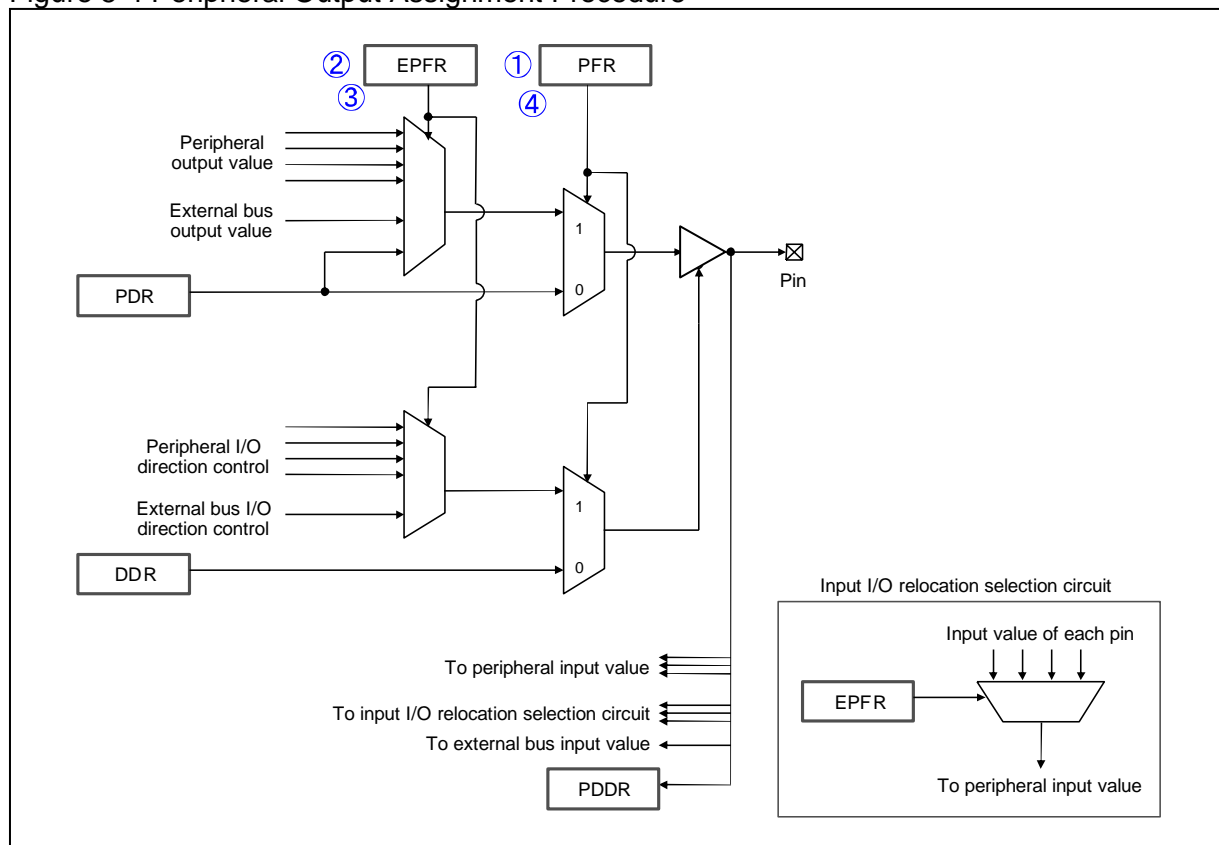
The setting method is the same as that described in "5.1.1. Peripheral I/O (bidirectional) Pin Assignment".

■ Preparation

- Since the pin will once function as a port as the result of step (1), set the DDR and PDR values in advance if necessary.
- For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".

1. Set the PFR of the applicable pin to enable the port function.
2. Disable the EPFRs for all other peripherals to be used by the relevant pin.
3. If the relevant pin is also used for an external bus or the relevant peripheral is one of the targets of I/O multiplexing, set the EPFR of the relevant peripheral. In addition, if the relevant peripheral has the I/O relocation function, set the EPFR of the relevant peripheral.
4. Set the PFR for the peripheral.

Figure 5-4 Peripheral Output Assignment Procedure



5.1.4. External Bus Assignment

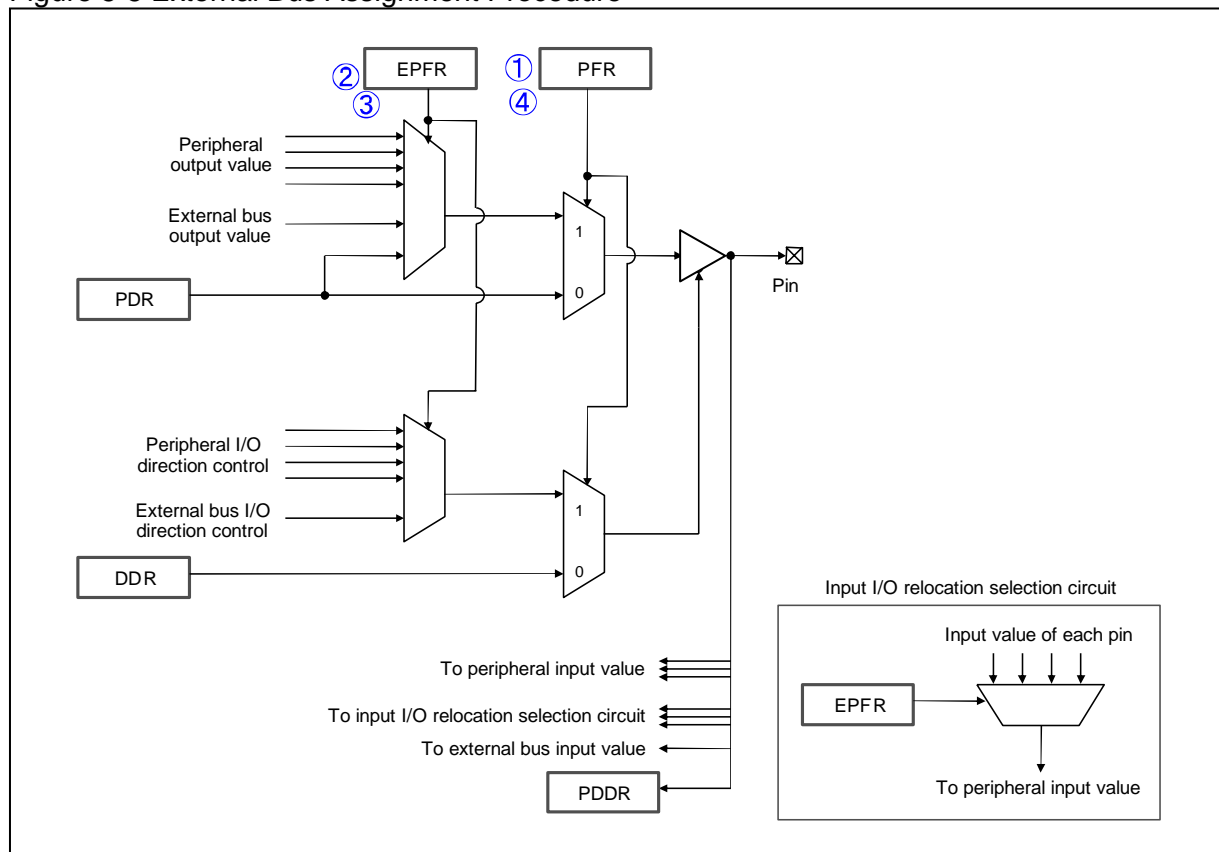
The external bus assignment is shown below.

■ Preparation

- Since the pin will once function as a port as the result of step (1), set the DDR and PDR values in advance if necessary.
- For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".

1. Set the PFR for the applicable pin to enable the port function.
2. Disable the EPFRs for all other peripherals that use the same pin as the external bus.
3. EPFR55 is set to become "GDC external bus output enabled".
4. Set the PFR for the peripheral.

Figure 5-5 External Bus Assignment Procedure



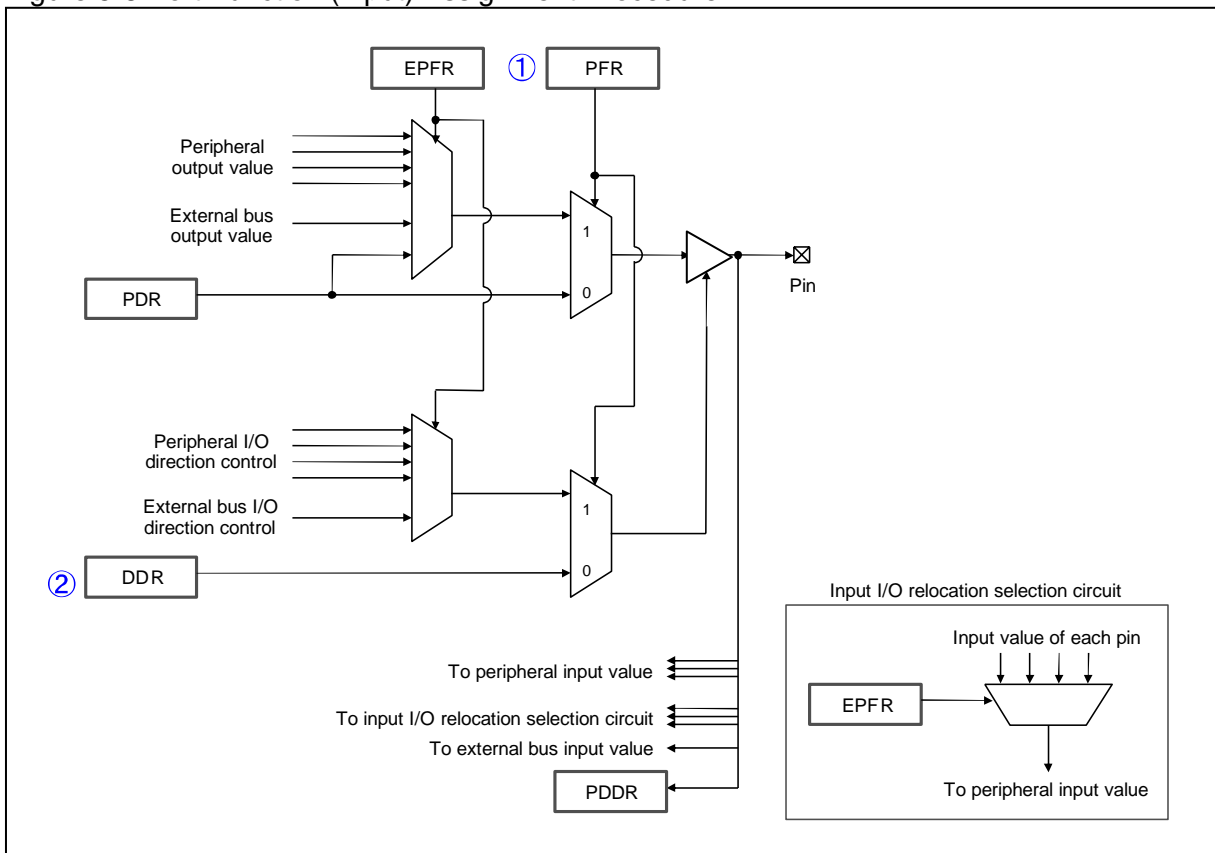
5.1.5. Port Function (Input) Assignment

The port function (input) assignment is shown below.

■ Preparation

- For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".
1. Set the PFR to enable the port function.
 2. Set the DDR for input.

Figure 5-6 Port Function (Input) Assignment Procedure



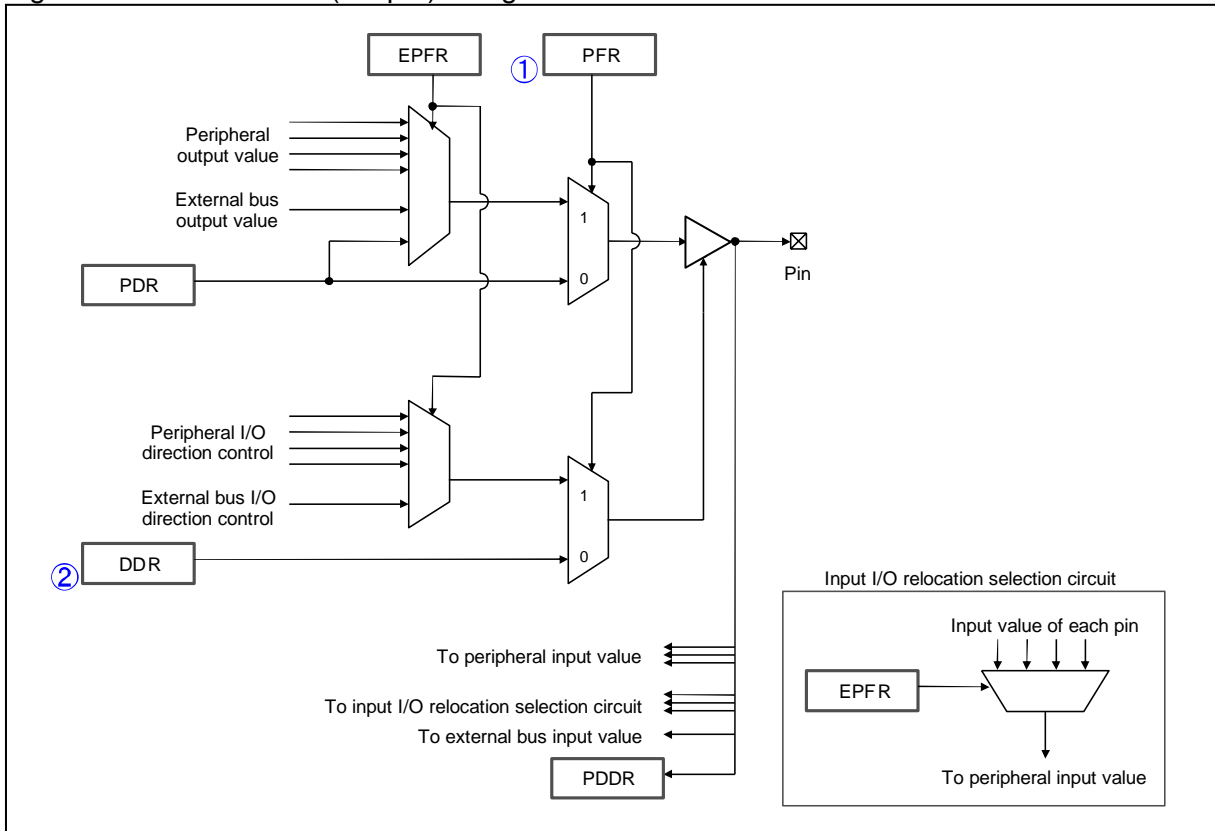
5.1.6. Port Function (Output) Assignment

The port function (Output) assignment is shown below.

■ Preparation

- For a pin with the AD converter function, set the applicable bit in the analog input enable register (ADER) of the AD converter to "Port I/O mode". For information on the setting method, see "CHAPTER: A/D CONVERTER".
1. Set the PFR to enable the port function.
 2. Set the DDR for output.

Figure 5-7 Port Function (Output) Assignment Procedure



5.1.7. AD Converter Input Assignment

The AD converter input assignment is shown below.

1. Set the analog input enable register (ADER) of the AD converter to analog input mode. See "CHAPTER: A/D CONVERTER".
Since the AD converter assignment is given the highest priority, no other configuration is required.

5.2. EPFR Setting Priority

The EPFR setting priority is shown below.

If the PFR is set for the peripheral and multiple EPFR settings are overlapping for a single pin, the valid peripheral is determined based on the following priorities:

1. CAN
2. Multi-function serial interface
3. LIN-UART
4. PPG
5. Sound generator
6. Real time clock
7. Base timer
8. Reload timer
9. Output compare

5.3. Notes on Input I/O Relocation Setting

Notes on input I/O relocation setting are shown below.

When switching an input pin to another pin, if there is a difference between pin levels before and after the switch, the I/O relocation change may become a trigger input to the peripheral that uses the relevant pin as a trigger.

5.4. Input Interception by GPORTEN

The input interception of the products equipped with GPORTEN is shown below.

The majority of pins become the input interceptions to avoid the change of the penetration current before the port is set with software at power-on reset. See "APPENDIX-D: Pin Status in CPU Status" for the pin that becomes an input interception. See "4.14. Port Input Enable Register : PORTEN(PORT ENable register)" for the method of releasing the input interception.

5.5. Notes on Pins with the AD Converter Function

Notes on pins with the AD converter function are shown below.

When using a pin with the AD converter function to perform a different function, set the relevant bit of the AD converter analog input enable register (ADER) to "Port I/O mode" in advance. For information on the setting method, see "CHAPTER: A/D CONVERTER". If analog input is enabled, inputs from ports and from peripheral functions are fixed at "0" and outputs are fixed at Hi-Z regardless of the port function register (PFR00 to PFR13, PFRA to PFRH) and extended port function register (EPFR00 to EPFR55) settings.

5.6. Setting when Using the Base Timer TIOA1 Pin

Setting when using the base timer TIOA1 pin is shown below.

If the base timer TIOA1 pin is to be used, it must be set for input for base timer I/O mode 1 and set for output for all cases other than base timer I/O mode 1. If the base timer TIOA1 pin is to be used, it must be set for peripheral input for base timer I/O mode 1 (see "5.1.2 Peripheral Input Assignment") and set for peripheral output for all cases other than base timer I/O mode 1 (see "5.1.3 Peripheral Output Assignment").

5.7. Operation at Wake Up from Power Shutdown

The operation at wake up from the power shutdown is shown below.

When PMUCTLR:IOCTMD bit is set, I/O output level is kept during wake up sequence from the power shutdown. The maintenance of I/O output level continues until PMUCTLR:IOCT is set.

When PMUCTLR:IOCTMD bit is cleared maintenance is released after wake up is completed, and the register of the I/O port becomes effective though I/O is maintained at wake up from the power shutdown.

On waking up from power shutdown, it has possibilities that the maintenance of I/O is not released.

On waking up from power shutdown, PMUCTLR.IOCT bit must be written "1" for releasing the maintenance of I/O

5.8. Notes on switching the port function

Notes on switching the port function is shown below.

When the port function is changed (general purpose port to peripheral function or peripheral function to general purpose port), it has possibilities that port outputs short spike.

Short spike is the same logic level as PDR value.

It is happened in the case of switching with direction change.

If this output is critical for the system, please set the certain value on PDR in prior to change port function.

CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)

This chapter explains the interrupt control (interrupt controller).

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains overview the of the interrupt control (interrupt controller).

The interrupt controller performs arbitration of interrupt requests.

2. Features

This section explains features of the interrupt control (interrupt controller).

This module is composed of the following parts.

- ICR register
- Interrupt priority determination circuit
- Interrupt level and interrupt vector generation circuit

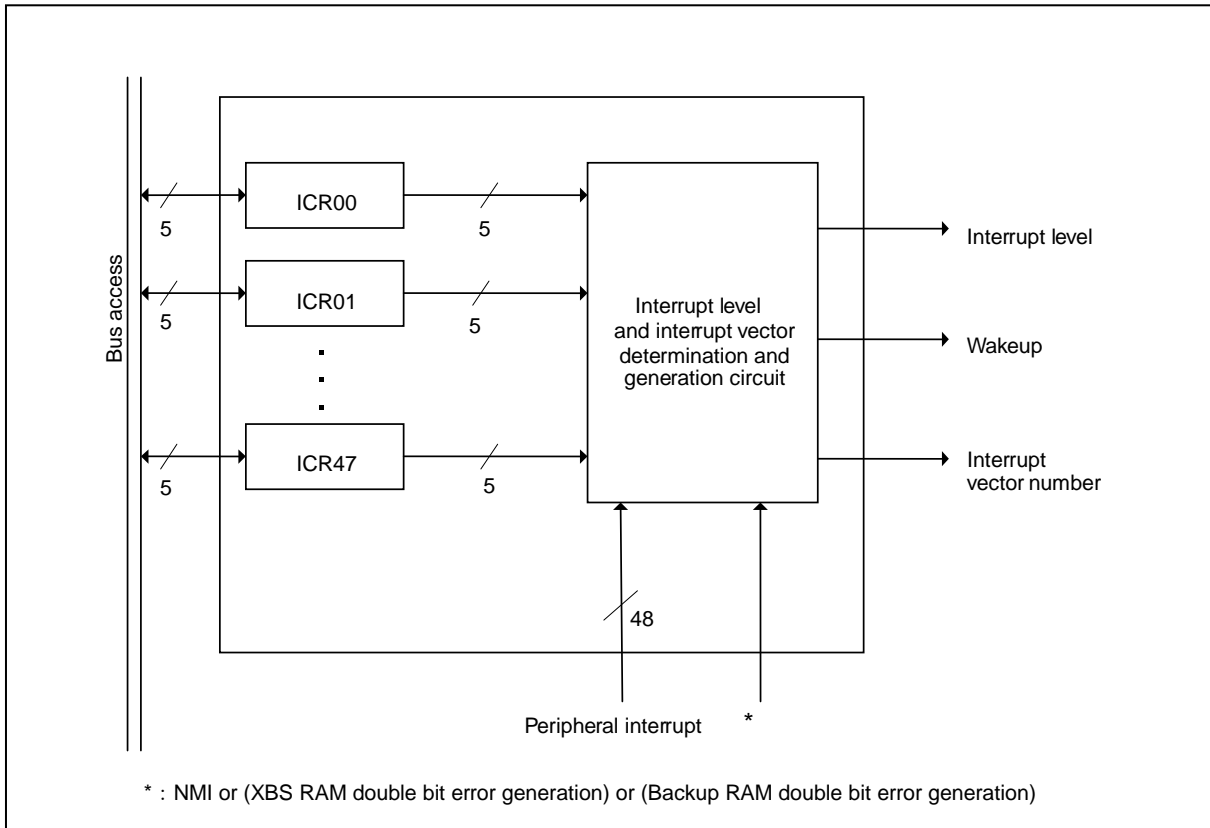
This module has the following functions.

- Detecting NMI requests and peripheral interrupt requests
- Priority determination (by level and interrupt vector)
- Transmitting the interrupt level of the source with the highest priority to the CPU
- Transmitting the interrupt vector number of the source with the highest priority to the CPU
- Generating wakeup requests by NMI / interrupts that occur with a level other than "1111"

3. Configuration

This section explains the configuration of the interrupt control (interrupt controller).

Figure 3-1 Block Diagram



4. Registers

This section explains the registers of the interrupt control (interrupt controller).

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0440	ICR00	ICR01	ICR02	ICR03	Interrupt control registers 00 to 47
0x0444	ICR04	ICR05	ICR06	ICR07	
0x0448	ICR08	ICR09	ICR10	ICR11	
0x044C	ICR12	ICR13	ICR14	ICR15	
0x0450	ICR16	ICR17	ICR18	ICR19	
0x0454	ICR20	ICR21	ICR22	ICR23	
0x0458	ICR24	ICR25	ICR26	ICR27	
0x045C	ICR28	ICR29	ICR30	ICR31	
0x0460	ICR32	ICR33	ICR34	ICR35	
0x0464	ICR36	ICR37	ICR38	ICR39	
0x0468	ICR40	ICR41	ICR42	ICR43	
0x046C	ICR44	ICR45	ICR46	ICR47	

4.1. Interrupt Control Registers 00 to 47 : ICR00 to ICR47 (Interrupt Control Register 00 to 47):

This section explains the bit configuration of the interrupt control registers 00 to 47 (ICR00 to ICR47).

One register is provided for each interrupt input to set the level for the corresponding interrupt request.

■ ICR00 to ICR47 : Address 0440_H to 046F_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			IL[4:0]				
Initial value	1	1	1	1	1	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W

[bit4 to bit0] IL[4:0] (Interrupt Level control)

The interrupt level setting bits specify the interrupt level for the corresponding interrupt request. An interrupt request is masked in the CPU if the interrupt level set in these registers is greater than or equal to the level mask value in the ILM register of the CPU. These bits are initialized to "5'b11111" on reset.

The correspondence between the configurable interrupt level settings bits and the interrupt levels is shown below.

IL[4:0]	Interrupt level
10000	16
10001	17
10010	18
10011	19
10100	20
10101	21
10110	22
10111	23
11000	24
11001	25
11010	26
11011	27
11100	28
11101	29
11110	30
11111	31

↑
Configurable highest level
(High)
↓
(Low)
Interrupts disabled

IL4 is fixed at "1". Writing has no effect.

5. Operation

This section explains the operation of the interrupt control (interrupt controller).

■ Setup

1. Configure the ICR register of the interrupt vector number corresponding to the peripheral for which you want to generate the interrupt.
2. Configure the peripheral where you want to generate the interrupt. (Configure interrupt output as enabled on the peripheral.)

■ Starting

Start the configured peripheral.

■ Determining Priorities

This module selects the highest priority interrupt among interrupt factors that occur simultaneously and outputs the interrupt level and interrupt vector number for the interrupt factors to the CPU.

The criteria for determining the priority of interrupt factors are as follows.

1. NMI
2. Factors that meet the following conditions
 - If the value of the interrupt level is not 31 (5'b11111). (31 indicates interrupts disabled)
 - The factors where the value of the interrupt level is the smallest.
 - When the interrupt level is the same (except for 31), the factors that has the smallest interrupt vector number from amongst these.

If no interrupt factors is selected by the above criteria, 31 (5'b11111) is output as the interrupt level. The interrupt vector number at this time is undefined.

■ Recovering From Stop Mode

The function for using an interrupt request to recover from stop mode is performed by this module. If an interrupt request (the interrupt level is anything other than "5'b11111") is generated from a peripheral (including NMI), a request is generated to the clock control unit to recover from stop mode.

As the interrupt priority judgment unit restarts operation once the clock supply starts after recovery from stop mode, the CPU is able to execute instructions until the interrupt priority judgment unit produces a result.

For interrupts that are not used as sources for recovering from stop mode, set the interrupt level of the corresponding interrupt control registers (ICR00 to ICR47) to "5'b11111" (interrupts disabled).

■ Recovering From Standby Mode (Power shutdown)

When the interrupt level is higher than ICR=0x1F (interrupt disable) and the standby return factor is more effective in the state that the interrupt factor has been generated, the thing that changes to the state of the power supply interception cannot be done. The instruction execution is continued as it is.

It returns immediately through the power supply interception return sequence though it changes to the state of the power supply interception because the interruption level does not become a standby return factor in the state that ICR=0x1F (interrupt disable) and the interrupt factor have been generated once because it is a state with the factor of the power supply interception return. (It is executed from the reset vector.)

CHAPTER : EXTERNAL INTERRUPT INPUT

This chapter explains the external interrupt input.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Setting
7. Q&A
8. Notes

1. Overview

This section explains the overview of the external interrupt input.

Interrupt request input from external interrupt input pins (INT0 to INT15).

2. Features

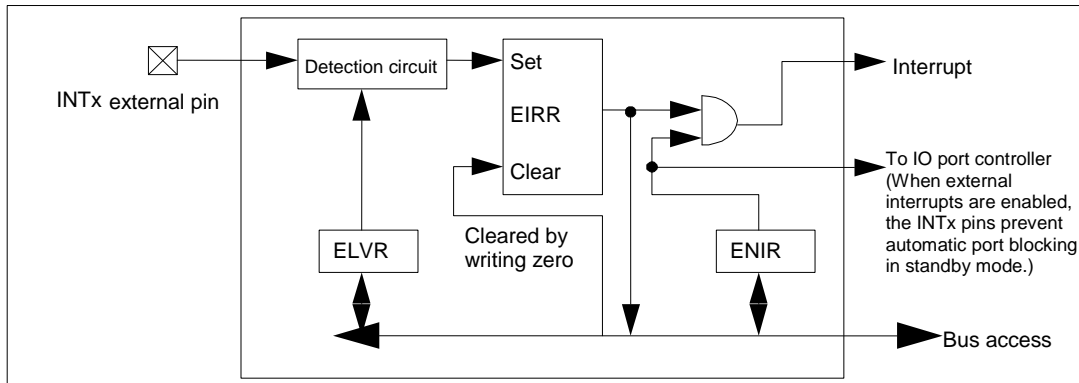
This section explains features of the external interrupt input.

- 16 systems external interrupt input pins (INT0 to INT15)
- Interrupt detection factors: 4 types: ("L" level, "H" level, rising edge, falling edge)

3. Configuration

This section explains the configuration of the external interrupt input.

Figure 3-1 Block Diagram



4. Registers

This section explains registers of the external interrupt input.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0550	EIRR0	ENIR0	ELVR0		External interrupt factor register 0 External interrupt enable register 0 External interrupt request level register 0
0x0554	EIRR1	ENIR1	ELVR1		External interrupt factor register 1 External interrupt enable register 1 External interrupt request level register 1

4.1. External Interrupt Factor Register 0/1 : EIRR0/EIRR1 (External Interrupt Request Register 0/1)

The bit configuration of external interrupt factor register 0/1 (EIRR0/EIRR1) is shown below.

This register holds information that an external interrupt factor has been generated.

■ **EIRR0 : Address 0550_H (Access: Byte, Half-word, Word)**

■ **EIRR1 : Address 0554_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ER7	ER6	ER5	ER4	ER3	ER2	ER1	ER0
Initial value	X	X	X	X	X	X	X	X

Attribute R(RM1),WR(RM1),WR(RM1),WR(RM1),WR(RM1),WR(RM1),WR(RM1),WR(RM1),W

[bit7 to bit0] ER7 to ER0 (External interrupt Request7 to 0) : External interrupt request bits
Flags to indicate that there is an interrupt request by INT external pin input. Writing "0" will clear it.

ERn	Meaning	
	Read	Write
0	No external interrupt request	Clear
1	External interrupt request exists	Does not influence operation

- EIRR0:ER0 corresponds to INT0 pin, EIRR0:ER1 to INT1 pin, ..., EIRR0:ER7 to INT7 pin, EIRR1:ER0 to INT8 pin, ..., EIRR1:ER7 to INT15 pin.
- Writing "1" to these bits doesn't influence operation.
- The values read with read-modify-write (RMW) instructions will always be "1".
- When external interrupt detection condition is at "L" level or "H" level, the corresponding bit will be set again if the external interrupt pin input is at an active level after clearing each bit in the EIRR register.
- The factor bit in the interrupt factor register may be set by changing interrupt request level register. Initialize the interrupt factor register after changing the interrupt request level register.
- The value after resetting this register depends on the pin state after the reset.
- This register will be initialized by all reset factors except recovery from standby (power shutdown) when PMUCTLR:IOCTMD=1.

4.2. External Interrupt Enable Register 0/1 : ENIR0/ENIR1 (ENable Interrupt request Register 0/1)

The bit configuration of external interrupt enable register 0/1 (ENIR0/ENIR1) is shown below.

This register enables external interrupt inputs.

■ **ENIR0 : Address 0551_H (Access: Byte, Half-word, Word)**

■ **ENIR1 : Address 0555_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EN7	EN6	EN5	EN4	EN3	EN2	EN1	EN0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] EN7 to EN0 (interrupt ENable) : External interrupt enable bits

These bits perform mask controls of interrupt requests from external pin INT inputs.

ENn	Operations at the detection of an external pin
0	Interrupt request mask. Holds interrupt requests but does not output them. (initial value)
1	Interrupt request enabled. Enables interrupt requests.

- ENIR0:EN0 corresponds to INT0 pin, ENIR0:EN1 to INT1 pin, ..., ENIR0:EN7 to INT7 pin, ENIR1:EN0 to INT8 pin, ..., ENIR1:EN7 to INT15 pin.
- This register will be initialized by all reset factors except recovery from standby (power shutdown) when PMUCTLR:IOCTMD=1.

4.3. External Interrupt Request Level Register 0/1 : ELVR0/ELVR1 (External interrupt LeVel Register 0/1)

The bit configuration of external interrupt request level register 0/1 (ELVR0/ELVR1) is shown below.

This register selects detection conditions for external interrupt requests.

■ **ELVR0 : Address 0552_H (Access: Byte, Half-word, Word)**

■ **ELVR1 : Address 0556_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	LB7	LA7	LB6	LA6	LB5	LA5	LB4	LA4

Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	LB3	LA3	LB2	LA2	LB1	LA1	LB0	LA0

Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit1] LB7 to LB0 (Level select B) : Level select B

[bit14 to bit0] LA7 to LA0 (Level select A) : Level select A

These bits select detection conditions for external interrupt requests. Combination of 2 bits, LA bit and LB bit will be used.

LBn	LAN	Detection conditions
0	0	"L" level detection(Initial value)
0	1	"H" level detection
1	0	Rising edge detection
1	1	Falling edge detection

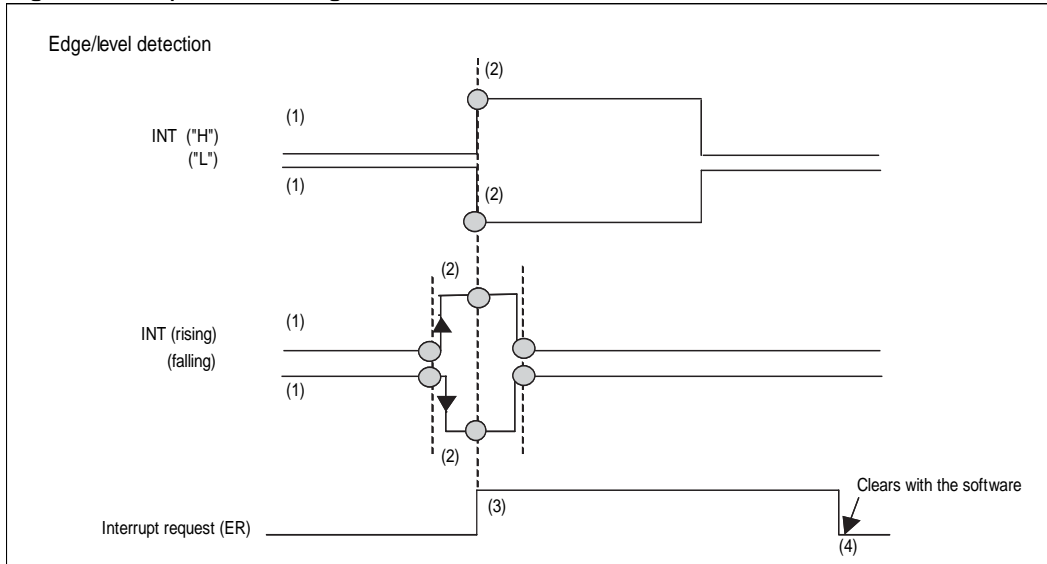
When the request input is a level (LAN, LBn =00 or 01), the corresponding bit (ERn) will turn back to "1" if INTn pin input is still in the effective levels after setting the external interrupt request bit (ERn) to "0".

- ELVR0:LA/LB0 corresponds to INT0 pin, ELVR0:LA/LB1 to INT1 pin, ..., ELVR0:LA/LB7 to INT7 pin, ELVR1:LA/LB0 to INT8 pin, ..., ELVR1:LA/LB7 to INT15 pin.
- The factor bit in the interrupt factor register may be set by changing the interrupt request level register. Initialize the interrupt factor register after changing the interrupt request level register.
- This register will be initialized by all reset factors except recovery from standby (power shutdown) when PMUCTLR:IOCTMD=1.

5. Operation

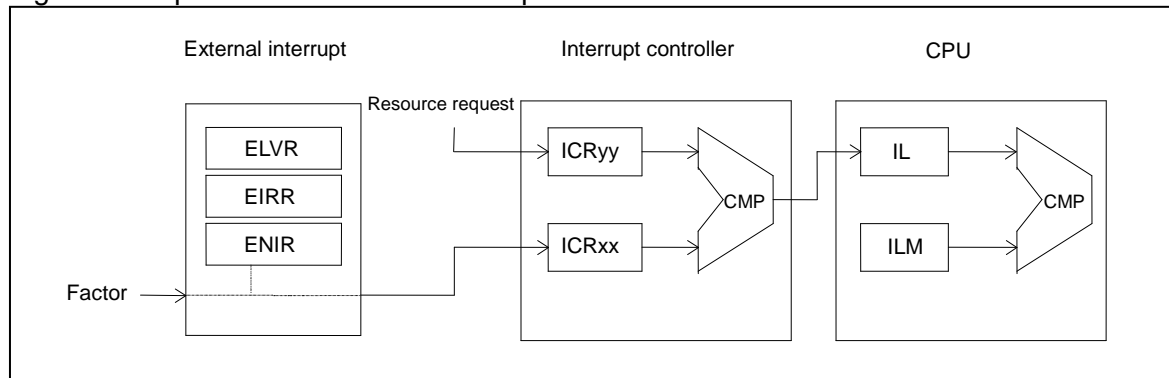
This section explains the operation of the external interrupt input.

Figure 5-1 Operation Diagram



- (1) External interrupt signal (INT) input
- (2) Detects interrupt signals (level/edge).
- (3) Generates interrupt requests.
- (4) Clears interrupt requests with the software.

Figure 5-2 Operation of External Interrupt



1. Operation of external interrupt

This module generates the interrupt request signal to the interrupt controller when a request set in the ELVR register is input in the corresponding pin after setting a request level and the enable register. The corresponding interrupt will be generated when the interrupt from this resource was found to have the highest priority in the result for examining the priority in interrupts concurrently occurred in the interrupt controller.

2. Transition to standby mode

Channels not to be used should be moved to disable state before letting them go into the standby mode. For the enabled channel, the standby mode automatic input/output disabled feature to the external pin will also be suppressed. See "CHAPTER: POWER CONSUMPTION CONTROL" for the automatic input/output disabled feature.

3. Setting procedure of external interrupts

When setting registers which reside in the external interrupt unit, follow the steps below.

- (1) Disable the corresponding bit for the enable register.
 - (2) Set the corresponding bit for the request level setting register.
 - (3) Read the request level register.
 - (4) Clear the corresponding bit for the factor register.
 - (5) Enable the corresponding bit for the enable register.
- (Note that concurrent writes of 16-bit data are allowed in step (4) and (5).)

The enable register must be disabled before you can set the registers in this module. The factor register must be cleared before you can set the enable register to enable state.

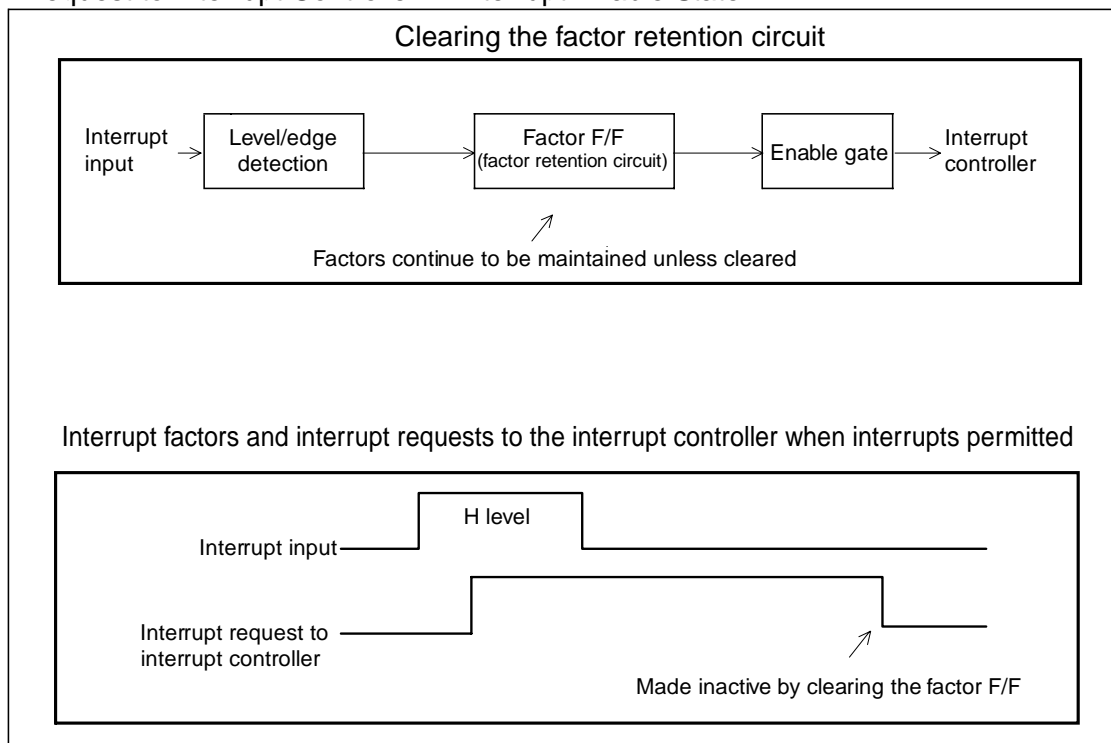
This has to be done to avoid generating erroneous interrupt factors at the time of setting register or in interrupt enable state.

4. External interrupt factor

Requests to the interrupt controller will continue to be active although a request input from outside is canceled, because there is an internal factor retention circuit.

To cancel requests going toward the interrupt controller, the factor register should be cleared.

Figure 5-3 Clearing the Factor Retention Circuit and Interrupt Factor and Interrupt Request to Interrupt Controller in Interrupt Enable State



6. Setting

This section explains setting of the external interrupt input.

Table 6-1 Necessary Settings for Using External Interrupts

Settings	Setting register	Setting method
Detection level settings	External interrupt request level setting register (ELVR0, ELVR1)	See "■ About Detection Levels and Their Setting Procedures" in "7. Q&A".
Make external pins to use for input.	See "CHAPTER: I/O PORTS".	See "CHAPTER: I/O PORTS".
External interrupt	An input from the external pin → Input signal to pins INT0 to INT15	—

7. Q&A

This section explains Q&A of the external interrupt input.

■ About Detection Levels and Their Setting Procedures

Four levels: ("L" level, "H" level, rising edge, falling edge)

Set the detection level bits as follows: (ELVRy:LBn, LAn) (n=0 to 7, y=0, 1).

Operation modes	Detection level bits (LBn, LAn) n=0 to 7
To perform "L" level detection	Set "00".
To perform "H" level detection	Set "01".
To perform rising edge detection	Set "10".
To perform falling edge detection	Set "11".

■ How to Make External Pins to Use for Input

See "CHAPTER: I/O PORTS".

■ About Interrupt Related Registers

See "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

■ About Interrupt Types

Interrupt factors are only for external interrupts. There are no select bits.

■ How to Enable/Disable/Clear Interrupts

Interrupt request enable flag, interrupt request flag

Interrupt enable setting is done by the interrupt enable bit (ENIR0/ENIR1:EN0 to EN7).

Operation	Interrupt enable bit (ENn)
To disable interrupt requests	Set "0".
To enable interrupt requests	Set "1".

Interrupt request clear is done by the interrupt request bit (EIRR0/EIRR1:ER0 to ER7).

Operation	Interrupt request bit (ERn)
To clear interrupt requests	Write "0".

8. Notes

This section explains the notes of the external interrupt input.

The external interrupt input register is not initialized when returned from the standby clock mode (power shutdown) and the standby stop mode (power shutdown) when PMUCTLR:IOCTMD=1. To maintain the status before it returns and the status under return, set the device in the status of the I/O maintenance by setting PMUCTLR:IOCTMD before setting standby. And, release the I/O maintenance by setting PMUCTLR:IOCT after the I/O port is set. See "CHAPTER: POWER CONSUMPTION CONTROL" for the details of the PMUCTLR register.

Moreover, the internal reset is issued at the return from the standby watch mode (power shutdown) and the standby stop mode (power shutdown) when PMUCTLR:IOCTMD=1. Therefore, only the reset factors (power-on reset, internal low-voltage detection, and simultaneous assert of RSTX and NMIX) are accepted. At this time, the register of the external interrupt input is not initialized. If the reset input from RSTX pin input or the external low voltage detection flag is set after the start-up, initialize the external interrupt input register before using.

CHAPTER : NMI INPUT

This chapter explains the NMI input.

1. Overview
2. Features
3. Configuration
4. Register
5. Operation
6. Usage Example

1. Overview

This section explains the overview of the NMI input.

NMI (Non Maskable Interrupt) is the non-maskable interrupt signal that is entered from the NMIX pin. The NMI can be used as a source for recovering from stop mode.

2. Features

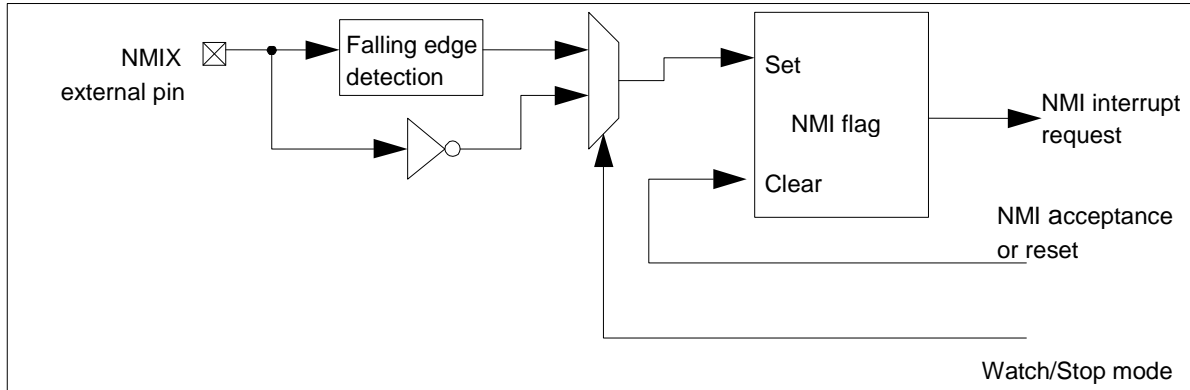
This section explains features of the NMI input

Can be used in both stop mode (Power shut-down is included) and watch mode (Power shut-down is included).

3. Configuration

This section explains the configuration of the NMI input.

Figure 3-1 Block Diagram



4. Register

This section explains the register of the NMI input.

This function has no register.

5. Operation

This section explains the operation of the NMI input.

■ NMI Interrupt Level

The NMI has the highest level among the user interrupts and cannot be masked. As an exception, the NMI is masked after reset until the ILM is set by the CPU.

■ NMI External Pin

In stop mode, this pin detects the L level, and at other times it detects the falling edge.

■ Interrupt Request Output

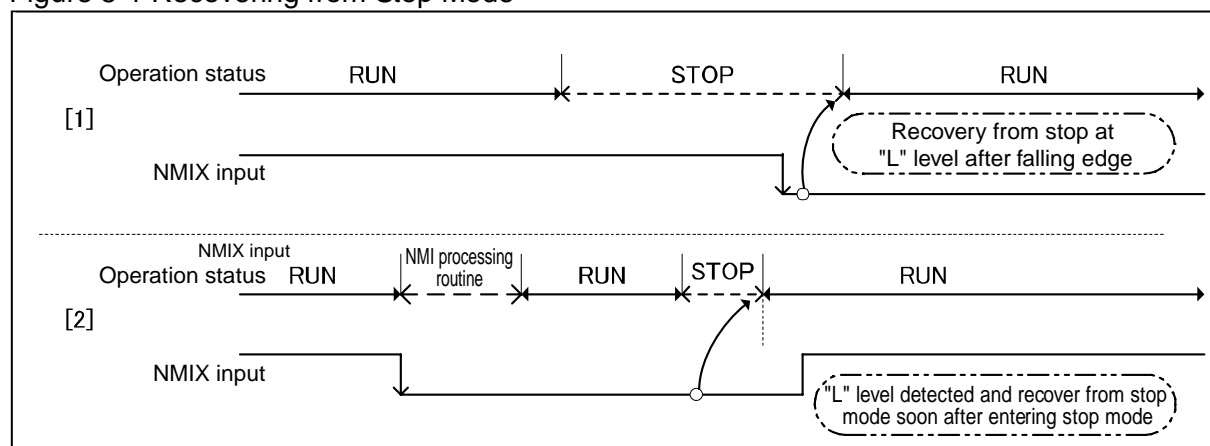
The NMI request detector has an NMI flag that is set for an NMI request and is cleared only if an interrupt for the NMI itself is accepted or reset occurs. The NMI flag cannot be read or written.

Read IRPR15H register to judge whether the NMI is caused by the NMIX external pin or the other factors. For details of this register, see "INTERRUPT REQUEST BATCH READ".

■ Recovering From Stop Mode

When switching to stop mode, if an "L" level is input to the NMIX, an NMI request is output to the interrupt controller and the CPU recovers from stop mode. If the CPU switches to stop mode without returning the input level of the NMIX pin to the "H" level after the NMI processing routine has finished in normal mode (not stop mode), the CPU recovers immediately after switching to stop mode (see [2] in Figure 5-1). Similarly, the power shut-down will not be controlled when the status changes to the stop mode (power shut-down) without setting the NMIX pin to the "H" level. Return the input level of the NMIX pin to the "H" level before entering stop mode so that the input level of the NMIX pin is set to the "L" level in stop mode.

Figure 5-1 Recovering from Stop Mode



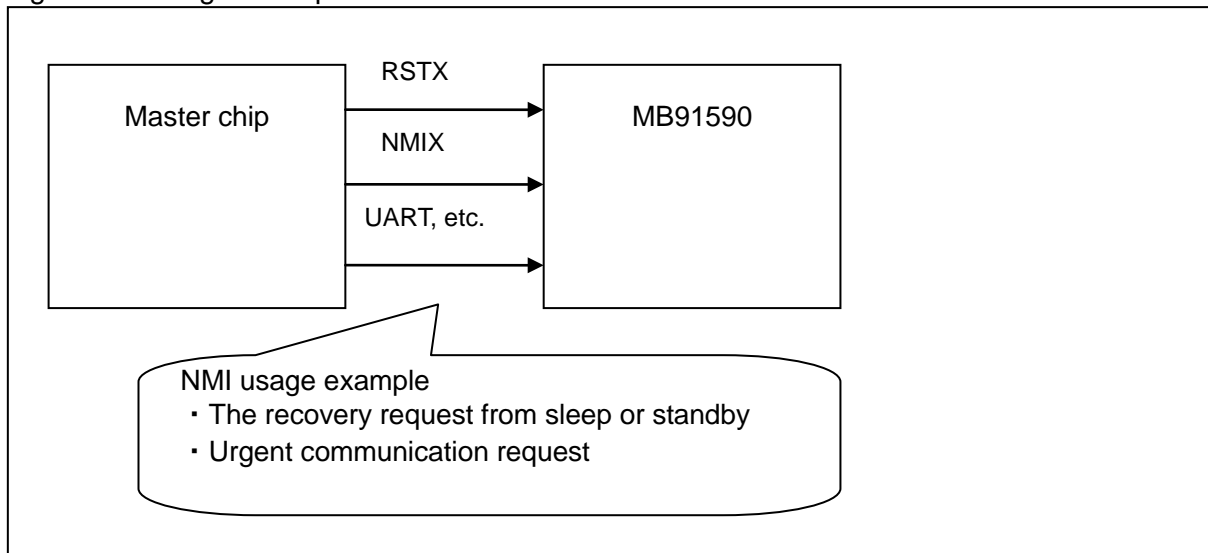
*: The watch mode and the watch mode (power shut-down) are similarly controlled.

6. Usage Example

This section explains a usage example of the NMI input.

This section gives an example of using the NMI function.

Figure 6-1 Usage Example



CHAPTER : DELAY INTERRUPT

This chapter explains the delay interrupt.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Restrictions

Code : 15_MB91590_HM_E_delayint_004_20111127

1. Overview

This section explains the overview of the delay interrupt.

The delay interrupt is a function for generating interrupts for the OS (operating system) to switch between tasks.

This function allows interrupt requests to the CPU to be generated and cancelled by software.

2. Features

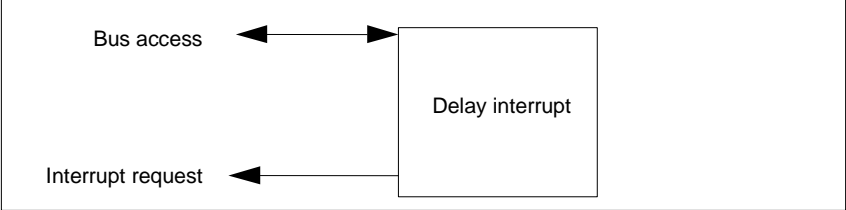
This section explains features of the delay interrupt.

The delay interrupt can be generated by writing to a register.

3. Configuration

This section explains the configuration of the delay interrupt.

Figure 3-1 Block Diagram



4. Registers

This section explains registers of the delay interrupt.

Address	Registers				Register function
	+0	+1	+2	+3	
0x0044	DICR	Reserved	Reserved	Reserved	Delay Interrupt Control Register

■ Delay Interrupt Control Register : DICR (Delay Interrupt Control Register)

This register controls the delay interrupts.

● DICR : Address 0044_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							DLYI
Initial value	1	1	1	1	1	1	1	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W

[bit0] DLYI (DeLaY Interrupt enable) : Delay Interrupt Enable Bit

This bit generates and clears the delay interrupt source.

DLYI	Description
Write 0	Clears the delay interrupt source
Write 1	Generates the delay interrupt source

5. Operation

This section explains the operation description of the delay interrupt.

The delay interrupts are used to generate interrupts for task switching. Using this function allows interrupt requests to the CPU to be generated and cancelled by software.

■ **Interrupt Vector Number**

The delay interrupts are allocated to the interrupt sources with the highest interrupt vector number.

In this core, delay interrupts are allocated to interrupt vector number 63 (0x3F).

■ **DLYI Bit of the DICR Register**

Writing "1" to this bit generates a delay interrupt source. Writing "0" to this bit cancels the delay interrupt source.

This bit functions like a standard interrupt source flag and should be cleared in the interrupt routine at the same time as when switching a task.

6. Restrictions

This section explains restrictions of the delay interrupt.

Do not use delay interrupts in DMA transfer requests.

CHAPTER : INTERRUPT REQUEST BATCH READ

This chapter explains the overview, features, and configuration of the interrupt request batch read.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

Code : 16_MB91590_HM_E_irqread_005_20111127

1. Overview

This section explains the overview of the interrupt request batch read.

This module can read multiple interrupt requests assigned to one interrupt vector number in a batch. Interrupt requests that have been generated can be identified by using the bit search instruction of the FR80-family CPU.

2. Features

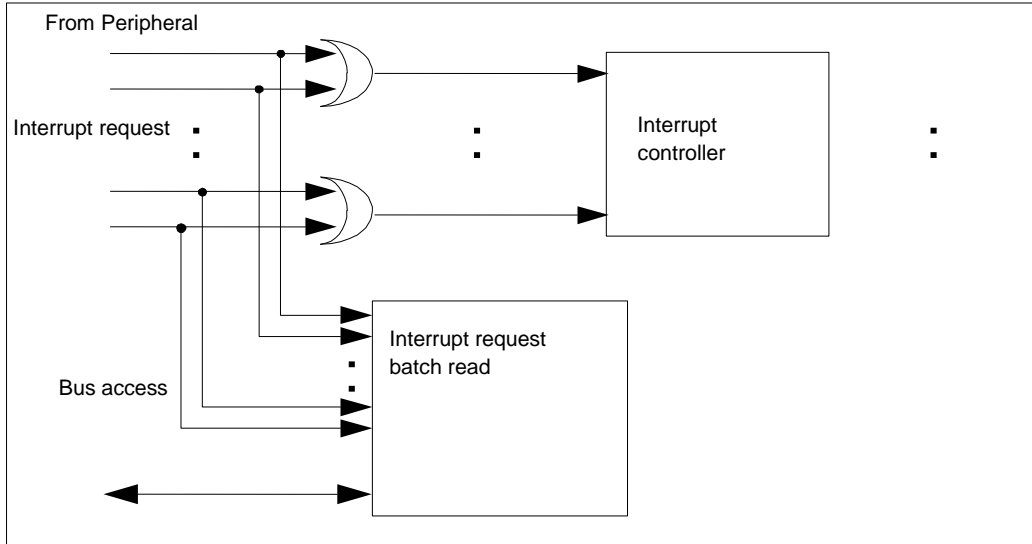
This section shows features of the interrupt request batch read.

Using this module, you can easily check whether interrupts have been generated.

3. Configuration

This section shows the configuration of the interrupt request batch read.

Figure 3-1 Block Diagram



4. Registers

This section explains the registers of the interrupt request batch read.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0418	IRPR0H	IRPR0L	IRPR1H	IRPR1L	Interrupt request batch read register 0 upper-order (#18) Interrupt request batch read register 0 lower-order (#19) Interrupt request batch read register 1 upper-order (#20) Interrupt request batch read register 1 lower-order (#22)
0x041C	IRPR2H	IRPR2L	IRPR3H	IRPR3L	Interrupt request batch read register 2 upper-order (#38) Interrupt request batch read register 2 lower-order (#39) Interrupt request batch read register 3 upper-order (#40) Interrupt request batch read register 3 lower-order (#41)
0x0420	IRPR4H	IRPR4L	IRPR5H	IRPR5L	Interrupt request batch read register 4 upper-order (#42) Interrupt request batch read register 4 lower-order (#43) Interrupt request batch read register 5 upper-order (#44) Interrupt request batch read register 5 lower-order (#36)
0x0424	IRPR6H	IRPR6L	IRPR7H	IRPR7L	Interrupt request batch read register 6 upper-order (#45) Interrupt request batch read register 6 lower-order (#46) Interrupt request batch read register 7 upper-order (#47) Interrupt request batch read register 7 lower-order (#49)
0x0428	IRPR8H	IRPR8L	IRPR9H	IRPR9L	Interrupt request batch read register 8 upper-order (#50) Interrupt request batch read register 8 lower-order (#51) Interrupt request batch read register 9 upper-order (#52) Interrupt request batch read register 9 lower-order (#53)
0x042C	Reserved	Reserved	Reserved	Reserved	

Address	Registers				Register function
	+0	+1	+2	+3	
0x0430	IRPR12H	IRPR12L	IRPR13H	IRPR13L	Interrupt request batch read register 12 upper-order (#58) Interrupt request batch read register 12 lower-order (#59) Interrupt request batch read register 13 upper-order (#60) Interrupt request batch read register 13 lower-order (#61)
0x0434	IRPR14H	IRPR14L	IRPR15H	Reserved	Interrupt request batch read register 14 upper-order (#62) Interrupt request batch read register 14 lower-order (#62) Interrupt request batch read register 15 upper-order (#15)

* IRPR10H/L, IRPR11H/L are unused.
#nn : Interrupt vector number (decimal)

4.1. Interrupt Request Batch Read Register 0 upper-order : IRPR0H (Interrupt Request Peripheral Read register 0H)

The bit configuration of the interrupt request batch read register 0 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #18)

■ IRPR0H : Address 0418_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RTIR0	RTIR1	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] RTIR0 (Reload Timer Interrupt Request 0) : Reload Timer 0 Interrupt Request

[bit6] RTIR1 (Reload Timer Interrupt Request 1) : Reload Timer 1 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.2. Interrupt Request Batch Read Register 0 lower-order : IRPR0L (Interrupt Request Peripheral Read register 0L)

The bit configuration of the interrupt request batch read register 0 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #19)

■ IRPR0L : Address 0419_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RTIR2	RTIR3	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] RTIR2 (Reload Timer Interrupt Request 2) : Reload Timer 2 Interrupt Request

[bit6] RTIR3 (Reload Timer Interrupt Request 3) : Reload Timer 3 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.3. Interrupt Request Batch Read Register 1 upper-order : IRPR1H (Interrupt Request Peripheral Read register 1H)

The bit configuration of the interrupt request batch read register 1 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #20)

■ **IRPR1H : Address 041A_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RXIR0	ISIR0	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] RXIR0 (Multi-Function-Serial-Interface RX Interrupt Request 0) : Multi-Function-Serial-Interface ch.0 reception completion Interrupt Request

[bit6] ISIR0 (Multi-Function-Serial-Interface Status Interrupt Request 0) : Multi-Function-Serial-Interface ch.0 Status Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.4. Interrupt Request Batch Read Register 1 lower-order : IRPR1L (Interrupt Request Peripheral Read register 1L)

The bit configuration of the interrupt request batch read register 1 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #22)

■ IRPR1L : Address 041B_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RXIR1	ISIR1	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] RXIR1 (Multi-Function-Serial-Interface RX Interrupt Request 1) : Multi-Function-Serial-Interface ch.1 reception completion Interrupt Request

[bit6] ISIR1 (Multi-Function-Serial-Interface Status Interrupt Request 1) : Multi-Function-Serial-Interface ch.1 Status Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.5. Interrupt Request Batch Read Register 2 upper-order : IRPR2H (Interrupt Request Peripheral Read register 2H)

The bit configuration of the interrupt request batch read register 2 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #38)

■ IRPR2H : Address 041C_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SGIR0	RXIR7	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] SGIR0 (SG Interrupt Request 0) : Sound Generator 0 Interrupt Request

[bit6] RXIR7 (RX Interrupt Request 7) : LIN-UART7 reception completion Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.6. Interrupt Request Batch Read Register 2 lower-order : IRPR2L (Interrupt Request Peripheral Read register 2L)

The bit configuration of the interrupt request batch read register 2 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #39)

■ IRPR2L : Address 041D_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SGIR1	TXIR7	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] SGIR1 (SG Interrupt Request 1) : Sound Generator 1 Interrupt Request

[bit6] TXIR7 (TX Interrupt Request 7) : LIN-UART7 transmission completion Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.7. Interrupt Request Batch Read Register 3 upper-order : IRPR3H (Interrupt Request Peripheral Read register 3H)

The bit configuration of the interrupt request batch read register 3 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #40)

■ IRPR3H : Address 041E_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PPGIR0	PPGIR1	PPGIR10	PPGIR11	PPGIR20	PPGIR21	Reserved	
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R0,WX	R0,WX

[bit7] PPGIR0 (PPG Interrupt Request 0) : PPG0 Interrupt Request

[bit6] PPGIR1 (PPG Interrupt Request 1) : PPG1 Interrupt Request

[bit5] PPGIR10 (PPG Interrupt Request 10) : PPG10 Interrupt Request

[bit4] PPGIR11 (PPG Interrupt Request 11) : PPG11 Interrupt Request

[bit3] PPGIR20 (PPG Interrupt Request 20) : PPG20 Interrupt Request

[bit2] PPGIR21 (PPG Interrupt Request 21) : PPG21 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.8. Interrupt Request Batch Read Register 3 lower-order : IRPR3L (Interrupt Request Peripheral Read register 3L)

The bit configuration of the interrupt request batch read register 3 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #41)

■ IRPR3L : Address 041F_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PPGIR2	PPGIR3	PPGIR12	PPGIR13	PPGIR22	PPGIR23	Reserved	
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R0,WX	R0,WX

[bit7] PPGIR2 (PPG Interrupt Request 2) : PPG2 Interrupt Request

[bit6] PPGIR3 (PPG Interrupt Request 3) : PPG3 Interrupt Request

[bit5] PPGIR12 (PPG Interrupt Request 12) : PPG12 Interrupt Request

[bit4] PPGIR13 (PPG Interrupt Request 13) : PPG13 Interrupt Request

[bit3] PPGIR22 (PPG Interrupt Request 22) : PPG22 Interrupt Request

[bit2] PPGIR23 (PPG Interrupt Request 23) : PPG23 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.9. Interrupt Request Batch Read Register 4 upper-order : IRPR4H (Interrupt Request Peripheral Read register 4H)

The bit configuration of the interrupt request batch read register 4 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #42)

■ IRPR4H : Address 0420_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PPGIR4	PPGIR5	PPGIR14	PPGIR15	Reserved			
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] PPGIR4 (PPG Interrupt Request 4) : PPG4 Interrupt Request

[bit6] PPGIR5 (PPG Interrupt Request 5) : PPG5 Interrupt Request

[bit5] PPGIR14 (PPG Interrupt Request 14) : PPG14 Interrupt Request

[bit4] PPGIR15 (PPG Interrupt Request 15) : PPG15 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.10. Interrupt Request Batch Read Register 4 lower-order : IRPR4L (Interrupt Request Peripheral Read register 4L)

The bit configuration of the interrupt request batch read register 4 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #43)

■ IRPR4L : Address 0421_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PPGIR6	PPGIR7	PPGIR16	PPGIR17	Reserved			
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] PPGIR6 (PPG Interrupt Request 6) : PPG6 Interrupt Request

[bit6] PPGIR7 (PPG Interrupt Request 7) : PPG7 Interrupt Request

[bit5] PPGIR16 (PPG Interrupt Request 16) : PPG16 Interrupt Request

[bit4] PPGIR17 (PPG Interrupt Request 17) : PPG17 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.11. Interrupt Request Batch Read Register 5 upper-order : IRPR5H (Interrupt Request Peripheral Read register 5H)

The bit configuration of the interrupt request batch read register 5 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #44)

■ IRPR5H : Address 0422_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PPGIR8	PPGIR9	PPGIR18	PPGIR19	Reserved			
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] PPGIR8 (PPG Interrupt Request 8) : PPG8 Interrupt Request

[bit6] PPGIR9 (PPG Interrupt Request 9) : PPG9 Interrupt Request

[bit5] PPGIR18 (PPG Interrupt Request 18) : PPG18 Interrupt Request

[bit4] PPGIR19 (PPG Interrupt Request 19) : PPG19 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.12. Interrupt Request Batch Read Register 5 lower-order : IRPR5L (Interrupt Request Peripheral Read register 5L)

The bit configuration of the interrupt request batch read register 5 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #36)

■ IRPR5L : Address 0423_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	CANIR2	Reserved						
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] CANIR2 (CAN Interrupt Request 2) : CAN ch.2 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.13. Interrupt Request Batch Read Register 6 upper-order : IRPR6H (Interrupt Request Peripheral Read register 6H)

The bit configuration of the interrupt request batch read register 6 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #45)

■ **IRPR6H : Address 0424_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GDC	GDC_ALM	Reserved		GDC_LVD	Reserved		
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R,WX	R0,WX	R0,WX	R0,WX

[bit7] GDC (GDC Interrupt Request) : GDC Interrupt Request

[bit6] GDC_ALM (PLL OVF Interrupt Request) : PLL Overflow Interrupt Request

[bit3] GDC_LVD (GDC Low Voltage Detect Interrupt Request) : GDC Low Voltage Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.14. Interrupt Request Batch Read Register 6 lower-order : IRPR6L (Interrupt Request Peripheral Read register 6L)

The bit configuration of the interrupt request batch read register 6 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #46)

■ IRPR6L : Address 0425_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MTIR	STIR	PTIR	Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] MTIR (Main Timer Interrupt Request) : Main Timer Interrupt Request

[bit6] STIR (Sub Timer Interrupt Request) : Sub Timer Interrupt Request

[bit5] PTIR (PLL Timer Interrupt Request) : PLL Timer Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.15. Interrupt Request Batch Read Register 7 upper-order : IRPR7H (Interrupt Request Peripheral Read register 7H)

The bit configuration of the interrupt request batch read register 7 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #47)

■ IRPR7H : Address 0426_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	SUBIR	SGIR4	Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit6] SUBIR (SUB Interrupt Request) : Clock Calibration (Sub) Interrupt Request

[bit5] SGIR4 (SG Interrupt Request 4) : Sound Generator 4 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.16. Interrupt Request Batch Read Register 7 lower-order : IRPR7L (Interrupt Request Peripheral Read register 7L)

The bit configuration of the interrupt request batch read register 7 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #49)

■ IRPR7L : Address 0427_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved						CRIR	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R,WX	R0,WX

[bit1] CRIR (CR clock calibration Interrupt Request) : Clock Calibration (CR) Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.17. Interrupt Request Batch Read Register 8 upper-order IRPR8H (Interrupt Request Peripheral Read register 8H)

The bit configuration of the interrupt request batch read register 8 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #50)

■ IRPR8H : Address 0428_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FRTIR0	FRTIR2	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] FRTIR0 (FRT Interrupt Request 0) : Free-run Timer ch.0 Interrupt Request

[bit6] FRTIR2 (FRT Interrupt Request 2) : Free-run Timer ch.2 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.18. Interrupt Request Batch Read Register 8 lower-order : IRPR8L (Interrupt Request Peripheral Read register 8L)

The bit configuration of the interrupt request batch read register 8 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #51)

■ IRPR8L : Address 0429_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FRTIR1	FRTIR3	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] FRTIR1 (FRT Interrupt Request 1) : Free-run Timer ch.1 Interrupt Request

[bit6] FRTIR3 (FRT Interrupt Request 3) : Free-run Timer ch.3 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.19. Interrupt Request Batch Read Register 9 upper-order : IRPR9H (Interrupt Request Peripheral Read register 9H)

The bit configuration of the interrupt request batch read register 9 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #52)

■ IRPR9H : Address 042A_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	
	ICUIR0	ICUIR6	Reserved						
Initial value	0	0	0	0	0	0	0	0	
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	

[bit7] ICUIR0 (ICU Interrupt Request 0) : Input Capture ch.0 Interrupt Request

[bit6] ICUIR6 (ICU Interrupt Request 6) : Input Capture ch.6 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.20. Interrupt Request Batch Read Register 9 lower-order : IRPR9L (Interrupt Request Peripheral Read register 9L)

The bit configuration of the interrupt request batch read register 9 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #53)

■ IRPR9L : Address 042B_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ICUIR1	ICUIR7	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] ICUIR1 (ICU Interrupt Request 1) : Input Capture ch.1 Interrupt Request

[bit6] ICUIR7 (ICU Interrupt Request 7) : Input Capture ch.7 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.21. Interrupt Request Batch Read Register 12 upper-order : IRPR12H (Interrupt Request Peripheral Read register 12H)

The bit configuration of the interrupt request batch read register 12 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #58)

■ IRPR12H : Address 0430_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	OCUIR0	OCUIR1	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] OCUIR0 (OCU Interrupt Request 0) : Output Compare ch.0 Interrupt Request

[bit6] OCUIR1 (OCU Interrupt Request 1) : Output Compare ch.1 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.22. Interrupt Request Batch Read Register 12 lower-order : IRPR12L (Interrupt Request Peripheral Read register 12L)

The bit configuration of the interrupt request batch read register 12 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #59)

■ IRPR12L : Address 0431_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	OCUIR2	OCUIR3	Reserved					
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] OCUIR2 (OCU Interrupt Request 2) : Output Compare ch.2 Interrupt Request

[bit6] OCUIR3 (OCU Interrupt Request 3) : Output Compare ch.3 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.23. Interrupt Request Batch Read Register 13 upper-order : IRPR13H (Interrupt Request Peripheral Read register 13H)

The bit configuration of the interrupt request batch read register 13 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #60)

■ **IRPR13H : Address 0432_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BT0IR0	BT0IR1	SGIR2	Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] BT0IR0 (BT0 Interrupt Request 0) : Base Timer ch.0 Interrupt Request 0

[bit6] BT0IR1 (BT0 Interrupt Request 1) : Base Timer ch.0 Interrupt Request 1

[bit5] SGIR2 (SG Interrupt Request 2) : Sound Generator 2 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.24. Interrupt Request Batch Read Register 13 lower-order : IRPR13L (Interrupt Request Peripheral Read register 13L)

The bit configuration of the interrupt request batch read register 13 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #61)

■ IRPR13L : Address 0433_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BT1IR0	BT1IR1	SGIR3	XB_ECC_SE	BR_ECC_SE	Reserved		
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX

[bit7] BT1IR0 (BT1 Interrupt Request 0) : Base Timer ch.1 Interrupt Request 0

[bit6] BT1IR1 (BT1 Interrupt Request 1) : Base Timer ch.1 Interrupt Request 1

[bit5] SGIR3 (SG Interrupt Request 3) : Sound Generator 3 Interrupt Request

[bit4] XB_ECC_SE : XBS RAM single bit error generation Interrupt Request

[bit3] BR_ECC_SE : Backup RAM single bit error generation Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.25. Interrupt Request Batch Read Register 14 upper-order : IRPR14H (Interrupt Request Peripheral Read register 14H)

The bit configuration of the interrupt request batch read register 14 upper-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #62)

■ IRPR14H : Address 0434_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DMAC0IR	DMAC1IR	DMAC2IR	DMAC3IR	DMAC4IR	DMAC5IR	DMAC6IR	DMAC7IR
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit7] DMAC0IR (DMAC 0 Interrupt Request) : DMAC ch.0 Interrupt Request

[bit6] DMAC1IR (DMAC 1 Interrupt Request) : DMAC ch.1 Interrupt Request

[bit5] DMAC2IR (DMAC 2 Interrupt Request) : DMAC ch.2 Interrupt Request

[bit4] DMAC3IR (DMAC 3 Interrupt Request) : DMAC ch.3 Interrupt Request

[bit3] DMAC4IR (DMAC 4 Interrupt Request) : DMAC ch.4 Interrupt Request

[bit2] DMAC5IR (DMAC 5 Interrupt Request) : DMAC ch.5 Interrupt Request

[bit1] DMAC6IR (DMAC 6 Interrupt Request) : DMAC ch.6 Interrupt Request

[bit0] DMAC7IR (DMAC 7 Interrupt Request) : DMAC ch.7 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.26. Interrupt Request Batch Read Register 14 lower-order : IRPR14L (Interrupt Request Peripheral Read register 14L)

The bit configuration of the interrupt request batch read register 14 lower-order is explained.

This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #62)

■ IRPR14L : Address 0435_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	DMAC8IR	DMAC9IR	DMAC10IR	DMAC11IR	DMAC12IR	DMAC13IR	DMAC14IR	DMAC15IR
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit7] DMAC8IR (DMAC 8 Interrupt Request) : DMAC ch.8 Interrupt Request

[bit6] DMAC9IR (DMAC 9 Interrupt Request) : DMAC ch.9 Interrupt Request

[bit5] DMAC10IR (DMAC 10 Interrupt Request) : DMAC ch.10 Interrupt Request

[bit4] DMAC11IR (DMAC 11 Interrupt Request) : DMAC ch.11 Interrupt Request

[bit3] DMAC12IR (DMAC 12 Interrupt Request) : DMAC ch.12 Interrupt Request

[bit2] DMAC13IR (DMAC 13 Interrupt Request) : DMAC ch.13 Interrupt Request

[bit1] DMAC14IR (DMAC 14 Interrupt Request) : DMAC ch.14 Interrupt Request

[bit0] DMAC15IR (DMAC 15 Interrupt Request) : DMAC ch.15 Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

4.27. Interrupt Request Batch Read Register 15 upper-order : IRPR15H (Interrupt Request Peripheral Read register 15H)

The bit configuration of the interrupt request batch read register 15 upper-order is explained.

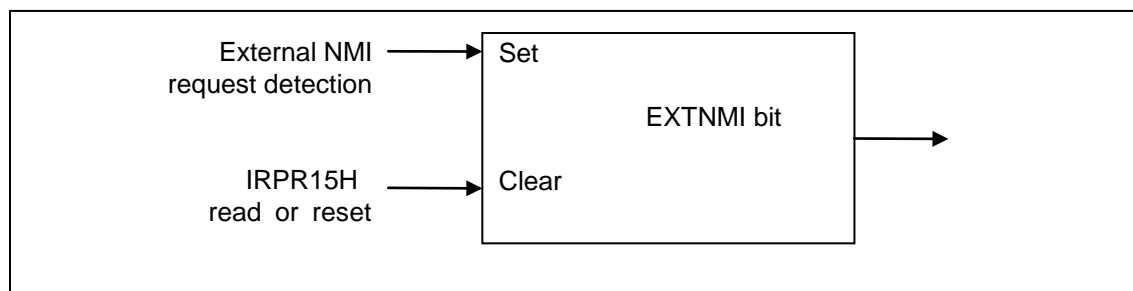
This register indicates the peripheral that has issued the interrupt request. (Interrupt vector number #15)

■ IRPR15H : Address 0436_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EXTNMI	XB_ECC_DE	BR_ECC_DE	Reserved				
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

[bit7] EXTNMI : External NMI Request

The EXTNMI bit is set by detecting external NMI request, and cleared by reading this register.



[bit6] XB_ECC_DE : XBS RAM double bit error generation Interrupt Request

[bit5] BR_ECC_DE : Backup RAM double bit error generation Interrupt Request

Read value of each bit	Meaning
0	No interrupt request has been issued.
1	An interrupt request has been issued.

5. Operation

This section explains the operation of the interrupt request batch read.

Within each interrupt handler, the pertinent register is read to determine what bits are set. As a consequence, what interrupt requests have been generated is found.

Note:

This register does not provide a function that can be used to input external interrupts. Read registers EIRR0 and EIRR1, which are used to input external interrupts.

CHAPTER : PPG

This chapter explains the PPG.

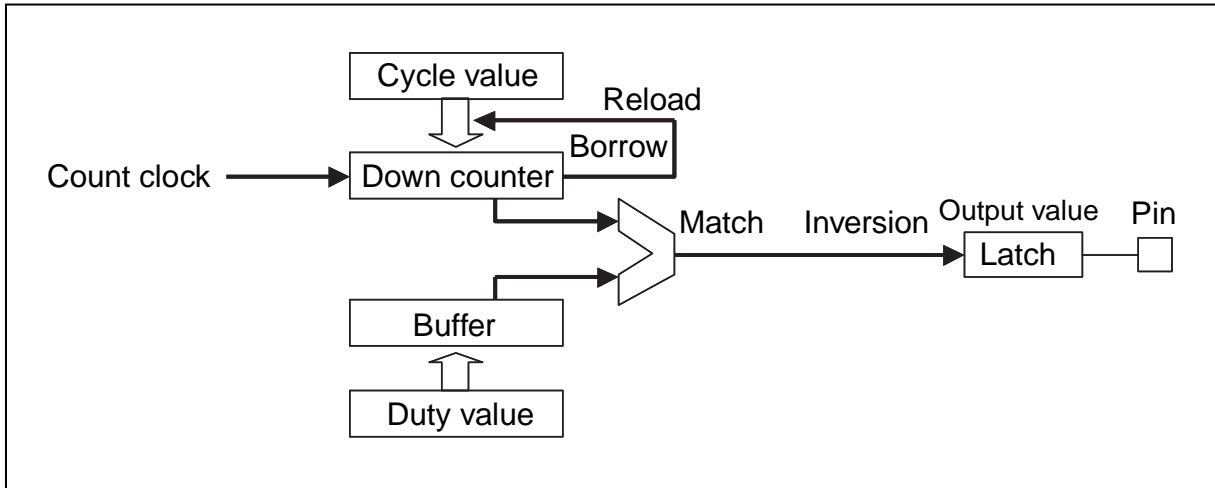
1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Setting
7. Q&A
8. Sample Programs
9. Notes

Code : 17_MB91590_HM_E_ppg_006_20111127

1. Overview

This section explains an overview of the PPG.

The programmable pulse generator (PPG) is used to generate one-shot (rectangular wave) or pulse width modulation (PWM) outputs. The PPG can be used in a wide range of applications because the cycle and duty of its output can be freely changed by software.

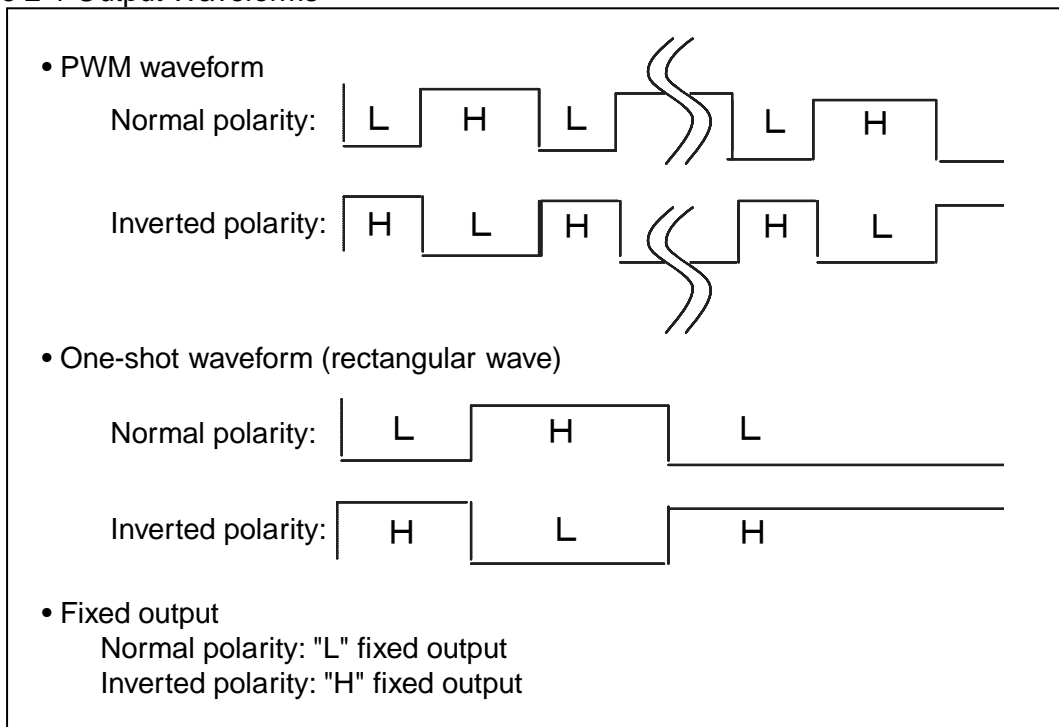


2. Features

This section explains features of the PPG.

- Number of PPG: 24 (Output: 24 channels, PPG0, PPG1, PPG2, PPG3, PPG4, PPG5, PPG6, PPG7, PPG8, PPG9, PPG10, PPG11, PPG12, PPG13, PPG14, PPG15, PPG16, PPG17, PPG18, PPG19, PPG20, PPG21, PPG22, PPG23)
- Count clock: Selects from 4 types (Peripheral clock (PCLK)/1, /4, /16, /64)
- Cycle:
 - $\text{Cycle} = \text{Count clock} \times (\text{PCSR register value} + 1)$
 - (Example) Count clock = 16 MHz (62.5 ns), PCSR value = 63999
 - $\text{Cycle} = 62.5\text{ns} \times (63999+1) = 4\text{ms}$
- Duty:
 - $\text{Duty} = \text{Count clock} \times (\text{PDUT register value} + 1)$
- Output waveform: 6 types shown in the figure below:

Figure 2-1 Output Waveforms



● **Interrupt factors: One of the following four interrupts is selected**

- Software trigger
- Borrow occurrence on the counter (match with the specified cycle)
- Duty match
- Borrow occurrence on the counter (match with the specified cycle) or duty match

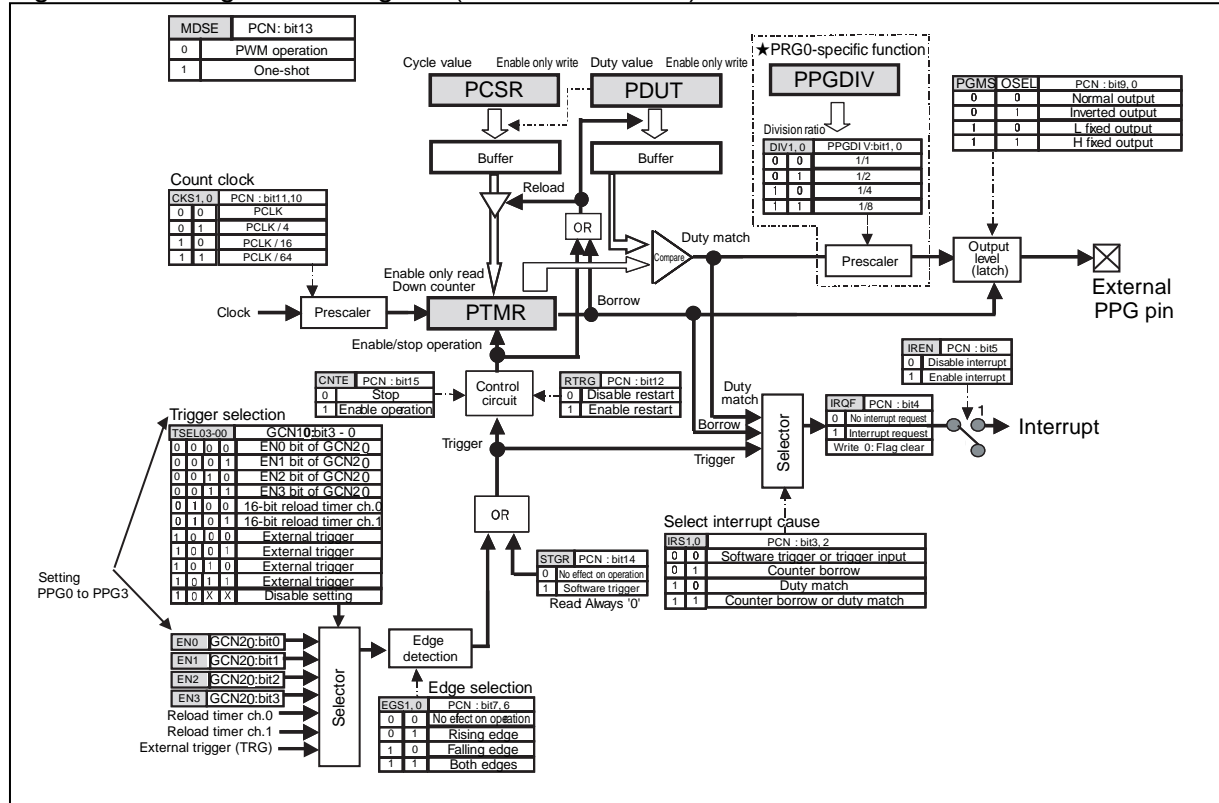
● **Activation triggers**

- Software trigger (set with software trigger bit)
- Internal trigger:
 - Trigger with register written
 - Trigger with reload timer
- External trigger

3. Configuration

This section explains a configuration of the PPG.

Figure 3-1 Configuration Diagram (for Each Channel)



4. Registers

This section explains registers of the PPG.

■ Table of Base Addresses (Base_addr) and External Pins

Table 4-1 Table of Base Addresses and External Pins

Channel	Base_addr	External pin	
		PPG output	Trigger input
0	0x026C	PPG0/PPG0_1/PPG0_2	TRG0
1	0x0274	PPG1/PPG1_1/PPG1_2/PPG1_3	
2	0x027C	PPG2/PPG2_1/PPG2_2	
3	0x0284	PPG3/PPG3_1/PPG3_2	
4	0x028C	PPG4/PPG4_1/PPG4_2	TRG1
5	0x0294	PPG5/PPG5_1/PPG5_2	
6	0x029C	PPG6/PPG6_1/PPG6_2	
7	0x02A4	PPG7/PPG7_1/PPG7_2	
8	0x02AC	PPG8/PPG8_1/PPG8_2	TRG2
9	0x02B4	PPG9/PPG9_1/PPG9_2	
10	0x02BC	PPG10/PPG10_1/PPG10_2	
11	0x0150	PPG11_1	
12	0x0158	PPG12_1	TRG3
13	0x0160	PPG13_1	
14	0x0168	PPG14_1	
15	0x0170	PPG15_1	
16	0x0178	PPG16	TRG4
17	0x0180	PPG17	
18	0x0188	PPG18	
19	0x0190	PPG19	
20	0x0198	PPG20	TRG5
21	0x01A0	PPG21	
22	0x01A8	PPG22	
23	0x01B0	PPG23	

■ **Registers map**

Table 4-2 Registers map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0144	GCN13		Reserved	GCN23	General control register 13 General control register 23
0x0148	GCN14		Reserved	GCN24	General control register 14 General control register 24
0x014C	GCN15		Reserved	GCN25	General control register 15 General control register 25
0x0150	PTMR11		PCSR11		PPG timer register 11 PPG cycle setting register 11
0x0154	PDUT11		PCN11		PPG duty setting register 11 PPG control status register 11
0x0158	PTMR12		PCSR12		PPG timer register 12 PPG cycle setting register 12
0x015C	PDUT12		PCN12		PPG duty setting register 12 PPG control status register 12
0x0160	PTMR13		PCSR13		PPG timer register 13 PPG cycle setting register 13
0x0164	PDUT13		PCN13		PPG duty setting register 13 PPG control status register 13
0x0168	PTMR14		PCSR14		PPG timer register 14 PPG cycle setting register 14
0x016C	PDUT14		PCN14		PPG duty setting register 14 PPG control status register 14
0x0170	PTMR15		PCSR15		PPG timer register 15 PPG cycle setting register 15
0x0174	PDUT15		PCN15		PPG duty setting register 15 PPG control status register 15
0x0178	PTMR16		PCSR16		PPG timer register 16 PPG cycle setting register 16
0x017C	PDUT16		PCN16		PPG duty setting register 16 PPG control status register 16
0x0180	PTMR17		PCSR17		PPG timer register 17 PPG cycle setting register 17
0x0184	PDUT17		PCN17		PPG duty setting register 17 PPG control status register 17
0x0188	PTMR18		PCSR18		PPG timer register 18 PPG cycle setting register 18

Address	Registers				Register function
	+0	+1	+2	+3	
0x018C	PDUT18		PCN18		PPG duty setting register 18 PPG control status register 18
0x0190	PTMR19		PCSR19		PPG timer register 19 PPG cycle setting register 19
0x0194	PDUT19		PCN19		PPG duty setting register 19 PPG control status register 19
0x0198	PTMR20		PCSR20		PPG timer register 20 PPG cycle setting register 20
0x019C	PDUT20		PCN20		PPG duty setting register 20 PPG control status register 20
0x01A0	PTMR21		PCSR21		PPG timer register 21 PPG cycle setting register 21
0x01A4	PDUT21		PCN21		PPG duty setting register 21 PPG control status register 21
0x01A8	PTMR22		PCSR22		PPG timer register 22 PPG cycle setting register 22
0x01AC	PDUT22		PCN22		PPG duty setting register 22 PPG control status register 22
0x01B0	PTMR23		PCSR23		PPG timer register 23 PPG cycle setting register 23
0x01B4	PDUT23		PCN23		PPG duty setting register 23 PPG control status register 23
0x025C	GCN10	Reserved	GCN20		General control register 10 General control register 20
0x0260	GCN11	Reserved	GCN21		General control register 11 General control register 21
0x0264	GCN12	Reserved	GCN22		General control register 12 General control register 22
0x0268	Reserved			PPGDIV	PPG0 output division setting register
0x026C	PTMR0		PCSR0		PPG timer register 0 PPG cycle setting register 0
0x0270	PDUT0		PCN0		PPG duty setting register 0 PPG control status register 0
0x0274	PTMR1		PCSR1		PPG timer register 1 PPG cycle setting register 1
0x0278	PDUT1		PCN1		PPG duty setting register 1 PPG control status register 1

Address	Registers				Register function
	+0	+1	+2	+3	
0x027C	PTMR2		PCSR2		PPG timer register 2 PPG cycle setting register 2
0x0280	PDUT2		PCN2		PPG duty setting register 2 PPG control status register 2
0x0284	PTMR3		PCSR3		PPG timer register 3 PPG cycle setting register 3
0x0288	PDUT3		PCN3		PPG duty setting register 3 PPG control status register 3
0x028C	PTMR4		PCSR4		PPG timer register 4 PPG cycle setting register 4
0x0290	PDUT4		PCN4		PPG duty setting register 4 PPG control status register 4
0x0294	PTMR5		PCSR5		PPG timer register 5 PPG cycle setting register 5
0x0298	PDUT5		PCN5		PPG duty setting register 5 PPG control status register 5
0x029C	PTMR6		PCSR6		PPG timer register 6 PPG cycle setting register 6
0x02A0	PDUT6		PCN6		PPG duty setting register 6 PPG control status register 6
0x02A4	PTMR7		PCSR7		PPG timer register 7 PPG cycle setting register 7
0x02A8	PDUT7		PCN7		PPG duty setting register 7 PPG control status register 7
0x02AC	PTMR8		PCSR8		PPG timer register 8 PPG cycle setting register 8
0x02B0	PDUT8		PCN8		PPG duty setting register 8 PPG control status register 8
0x02B4	PTMR9		PCSR9		PPG timer register 9 PPG cycle setting register 9
0x02B8	PDUT9		PCN9		PPG duty setting register 9 PPG control status register 9
0x02BC	PTMR10		PCSR10		PPG timer register 10 PPG cycle setting register 10
0x02C0	PDUT10		PCN10		PPG duty setting register 10 PPG control status register 10

4.1. PPG Cycle Setting Register : PCSR

The bit configuration of the PPG cycle setting register (PCSR) is shown below.

The PPG cycle setting register (PCSR) specifies a cycle of the PPG.

■ PCSR : Address Base_addr + 02_H (Access: Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	S15	S14	S13	S12	S11	S10	S9	S8
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	S7	S6	S5	S4	S3	S2	S1	S0
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W

- The PPG cycle setting register has a buffer. Data transfer from the buffer to the counter occurs automatically when a borrow occurs on the counter.
- Be sure to set the PPG duty setting register (PDUT) after the PPG cycle setting register is rewritten.
- PPG cycle setting registers must be accessed in half-word (16-bit) or word (32-bit).
(See "9. Notes".)

4.2. PPG Duty Setting Register : PDUT

The bit configuration of the PPG duty setting register (PDUT) is shown below.

The PPG duty setting register (PDUT) specifies the duty of the PPG output waveform.

■ PDUT : Address Base_addr + 04_H (Access: Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	D15	D14	D13	D12	D11	D10	D9	D8
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W

- The PPG duty setting register has a buffer. Data transfer from the buffer to the counter occurs automatically when a borrow occurs on the counter.
- For the PPG duty setting register, set a value that is smaller than the value set for the PPG cycle setting register (PCSR).
(See "9. Notes".)
- If an equal value is set on the PPG duty setting register and the PPG cycle setting register (PCSR), the result is as follows:
 - If the polarity is normal (OSEL = "0"), the output is always "H".
 - If the polarity is inverted (OSEL = "1"), the output is always "L".
(The OSEL bit is the output polarity selection bit on the PPG control status register (PCN).)
- PPG duty setting registers must be accessed in half-word (16-bit) or word (32-bit).
(See "9. Notes".)

4.3. PPG Control Status Register : PCN

The bit configuration of the PPG control status register (PCN) is shown below.

The PPG control status register (PCN) controls operation of the PPG and shows status of the PPG as well.

■ **PCN : Address Base_addr + 06_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	CNTE	STRG	MDSE	RTRG	CKS1	CKS0	PGMS	—
Initial value	0	0	0	0	0	0	0	—
Attribute	R/W	R0,W	R/W	R/W	R/W	R/W	R/W	R1,WX
Rewrite while in operation	○	○	×	×	×	×	○	×

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EGS1	EGS0	IREN	IRQF	IRS1	IRS0	Reserved	OSEL
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R(RM1),W	R/W	R/W	R/W0	R/W
Rewrite while in operation	×	×	○	○	×	×	×	×

○ : Rewrite enabled, × : Rewrite disabled (See "9. Notes".)

[bit15] CNTE : Timer operation enable

CNTE	Operation
0	Inactive
1	Active

This bit enables the operation of the PPG.

[bit14] STRG : Software trigger

STRG	Operation
0	PPG operation is not influenced by the value written to this bit (which is always "0" when read).
1	A software trigger is generated.

If this bit is set to "1", the PPG is activated by a software trigger. The software trigger activates the PPG independent of the trigger generated by the EN bit.

[bit13] MDSE : Mode selection

MDSE	Mode
0	PWM operation
1	One-shot operation

- If this bit is set to "0", the PPG is enabled to perform PWM operation, thus generating a sequence of pulses.
- If this bit is set to "1", the PPG generates only one pulse.

[bit12] RTRG : Restart enable

RTRG	Operation
0	Restart disabled
1	Restart enabled

When the restart enable bit is set to "1", the PPG is enabled to restart with a trigger (such as software, an internal factor, or an external factor).

[bit11, bit10] CKS1, CKS0 : Count clock selection

CKS1	CKS0	Down counter count clock selection
0	0	Peripheral clock (PCLK)
0	1	Division of the peripheral clock frequency by 4
1	0	Division of the peripheral clock frequency by 16
1	1	Division of the peripheral clock frequency by 64

[bit9] PGMS : PPG output mask selection

PGMS	Operation
0	No output mask
1	Output mask (Output is fixed to "L": OSEL = "0")

- When this bit is set to "1", the PPG output can be clamped to "L" or "H" regardless of the mode selection, cycle, and duty settings.
- The output level can be specified by the output polarity selection bit (PCNn:OSEL). (n = 0 to 23)

[bit8] - : Undefined bit

The read value is always "1". This does not affect the writing operation.

[bit7, bit6] EGS1, EGS0 : Trigger input edge selection

EGS1	EGS0	Selected edge
0	0	Writing does not affect on the operation
0	1	Rising edge
1	0	Falling edge
1	1	Both edges (rising or falling)

Select a source edge for activation with the trigger input edge selection bits (ESG[1:0]) to the trigger input selected by the trigger specification bits (GCN10/11/12/13/14/15:TSEL3/2/1/0) of the PPG registers.

[bit5] IREN : Interrupt request enable

IREN	Operation
0	Interrupt request disabled
1	Interrupt request enabled

[bit4] IRQF : Interrupt request flag

IRQF	Read	Write
0	No interrupt request	Clears the interrupt request flag.
1	Interrupt request present	Writing does not affect on the operation

If this bit is set to "0" when the interrupt request flag (IRQF) = "1", the interrupt request flag (IRQF = "1") that is set takes precedence.

[bit3, bit2] IRS1, IRS0 : Interrupt factor selection

IRS1	IRS0	Selection
0	0	Software trigger or trigger input
0	1	Borrow occurrence on the counter (match with the specified cycle)
1	0	Counter matched with the specified duty value
1	1	Borrow occurrence on the counter (matched with the specified cycle) or counter matched with duty value

These bits select the operation that generates an interrupt request.

[bit1] Reserved

"0" should be written to this bit.

[bit0] OSEL : PPG output polarity selection

OSEL	Operation
0	Normal polarity
1	Inverted polarity

If the PPG output mask selection bit (PCNn:PGMS) is set to "1", setting the output polarity selection bit (OSEL) to "0" or "1" causes the output to be clamped to "L" or "H", respectively. (n = 0 to 23)

4.4. General Control Register 10-13 : GCN10 to GCN13

The bit configuration of the general control register 10-13(GCN10 to GCN13) is shown below.

The general control register selects the trigger input for PPG0 to PPG15.

GCN10: PPG0 to PPG3

GCN11: PPG4 to PPG7

GCN12: PPG8 to PPG11

GCN13: PPG12 to PPG15

■ **GCN10 : Address 025C_H (Access: Half-word)**

■ **GCN11 : Address 0260_H (Access: Half-word)**

■ **GCN12 : Address 0264_H (Access: Half-word)**

■ **GCN13 : Address 0144_H (Access: Half-word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TSEL3[3:0]				TSEL2[3:0]			
Initial value	0	0	1	1	0	0	1	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TSEL1[3:0]				TSEL0[3:0]			
Initial value	0	0	0	1	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit12] TSEL3[3:0] : Trigger specification for PPG3, PPG7, PPG11 and PPG15

[bit11 to bit8] TSEL2[3:0]: Trigger specification for PPG2, PPG6, PPG10 and PPG14

[bit7 to bit4] TSEL1[3:0]: Trigger specification for PPG1, PPG5, PPG9 and PPG13

[bit3 to bit0] TSEL0[3:0]: Trigger specification for PPG0, PPG4, PPG8 and PPG12

TSEL0[3:0] (PPG0/4/8/12) TSEL1[3:0] (PPG1/5/9/13) TSEL2[3:0] (PPG2/6/10/14) TSEL3[3:0] (PPG3/7/11/15)				Activation trigger specification
0	0	0	0	EN0 bit (GCN20/21/22/23 register)
0	0	0	1	EN1 bit (GCN20/21/22/23 register)
0	0	1	0	EN2 bit (GCN20/21/22/23 register)
0	0	1	1	EN3 bit (GCN20/21/22/23 register)
0	1	0	0	16-bit reload timer 0
0	1	0	1	16-bit reload timer 1
1	0	0	0	External trigger
1	0	0	1	External trigger
1	0	1	0	External trigger
1	0	1	1	External trigger
1	1	X	X	Setting is prohibited
Other than above				Setting is prohibited (See "9. Notes ".)

When an edge that is specified with the trigger input edge selection bits (PCNn:EGS[1:0]) (n = 0 to 15) is detected for the specified activation trigger, selected PPG0 to PPG15 will be activated.

4.5. General Control Register 14, 15 : GCN14, GCN15

The bit configuration of the general control register 14,15 (GCN14, GCN15) is shown below.

The general control register selects the trigger input for PPG16 to PPG23.

GCN14: PPG16 to PPG19

GCN15: PPG20 to PPG23

■ GCN14 : Address 0148_H (Access: Half-word)

■ GCN15 : Address 014C_H (Access: Half-word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TSEL3[3:0]				TSEL2[3:0]			
Initial value	0	0	1	1	0	0	1	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TSEL1[3:0]				TSEL0[3:0]			
Initial value	0	0	0	1	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit12] TSEL3[3:0] : Trigger specification for PPG19 and PPG23

[bit11 to bit8] TSEL2[3:0] : Trigger specification for PPG18 and PPG22

[bit7 to bit4] TSEL1[3:0] : Trigger specification for PPG17 and PPG21

[bit3 to bit0] TSEL0[3:0] : Trigger specification for PPG16 and PPG20

TSEL0[3:0] (PPG16/20) TSEL1[3:0] (PPG17/21) TSEL2[3:0] (PPG18/22) TSEL3[3:0] (PPG19/23)				Activation trigger specification
0	0	0	0	EN0 bit (GCN24/25 register)
0	0	0	1	EN1 bit (GCN24/25 register)
0	0	1	0	EN2 bit (GCN24/25 register)
0	0	1	1	EN3 bit (GCN24/25 register)
0	1	0	0	16-bit reload timer 2
0	1	0	1	16-bit reload timer 3
1	0	0	0	External trigger
1	0	0	1	External trigger
1	0	1	0	External trigger
1	0	1	1	External trigger
1	1	X	X	Setting is prohibited
Other than above				Setting is prohibited (See "9. Notes ".)

When an edge that is specified with the trigger input edge selection bits (PCNn:EGS[1:0]) (n = 16 to 23) is detected for the specified activation trigger, selected PPG16 to PPG23 will be activated.

4.6. General Control Register 20-25 : GCN20 to GCN25

The bit configuration of the general control register 20-25 (GCN20 to GCN25) is shown below.

The general control register generates the internal trigger level with software for PPG0 to PPG23.

GCN20: PPG0 to PPG3

GCN21: PPG4 to PPG7

GCN22: PPG8 to PPG11

GCN23: PPG12 to PPG15

GCN24: PPG16 to PPG19

GCN25: PPG20 to PPG23

■ **GCN20 : Address 025F_H (Access: Byte)**

■ **GCN21 : Address 0263_H (Access: Byte)**

■ **GCN22 : Address 0267_H (Access: Byte)**

■ **GCN23 : Address 0147_H (Access: Byte)**

■ **GCN24 : Address 014B_H (Access: Byte)**

■ **GCN25 : Address 014F_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	Reserved	Reserved	Reserved	EN3	EN2	EN1	EN0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W0	R/W0	R/W0	R/W0	R/W	R/W	R/W	R/W

[bit7 to bit4] Reserved

These bits must always be written to "0". (See "9. Notes ".)

[bit3] EN3 : trigger input

[bit2] EN2 : trigger input

[bit1] EN1 : trigger input

[bit0] EN0 : trigger input

ENn	Internal triggers ENn
0	Sets the level to "L"
1	Sets the level to "H"

- Sets the internal trigger level.
- When one of the EN trigger inputs (EN0, EN1, EN2, EN3) is selected for the trigger specification bits (TSEL3, TSEL2, TSEL1, TSEL0) in the general control registers (GCN10 to GCN15), selected EN becomes the trigger input bit for the PPG.
- When the state selected with the trigger input edge selection bits (EGS[1:0]) of the PPG control status register is activated by the trigger input bits (selected EN0, EN1, EN2 and EN3) with software, this trigger will activate the PPG.

4.7. PPG Timer Register : PTMR

The bit configuration of the PPG timer register (PTMR) is shown below.

The PPG timer register (PTMR) allows reading the PPG timer count down values of PPG0 to PPG23.

■ **PTMR : Address Base_addr + 00_H (Access: Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	T15	T14	T13	T12	T11	T10	T9	T8
Initial value	1	1	1	1	1	1	1	1
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	T7	T6	T5	T4	T3	T2	T1	T0
Initial value	1	1	1	1	1	1	1	1
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

- The count value of the 16-bit down counter can be read from these bits.
- The PPG timer register (PTMR_n) cannot be read correctly by the byte access. (n = 0 to 23)

4.8. PPG0 Output Division Setting Register : PPGDIV

The bit configuration of the PPG0 output division setting register (PPGDIV) is shown below.

The PPG0 output division setting register (PPGDIV) sets the output division ratio for PPG0.

■ PPGDIV : Address 026B_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	-	-	-	-	-	DIV1	DIV0
Initial value	-	-	-	-	-	-	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

[bit7 to bit2] - : Undefined

The read value is always "1". Writing does not affect the operation.

[bit1, bit0] DIV1, DIV0 : division ratio setting

DIV1	DIV0	Division ratio
0	0	1/1
0	1	1/2
1	0	1/4
1	1	1/8

Sets the division ratio for PPG0 output.

Note:

Following restrictions will apply for setting 1/2, 1/4 and 1/8 divisions.

- The duty of the output waveform is fixed to 50%.
- Setting the one-shot operation (PCN:MDSE = 1) is prohibited.
- Setting the PPG reversed output function (PCN:OSEL = 1) is prohibited.
- Setting the PPG fixed output state (PCN:PGMS, OSEL = 01, 10, 11) is prohibited.
- Setting is prohibited when PCSR = PDUT.

5. Operation

This section explains the operation of the PPG.

There are 24 of PPG (Programmable Pulse Generator) to output programmable pulses independently/systematically.

Followings are explanations for each operation mode.

5.1. PWM Operation

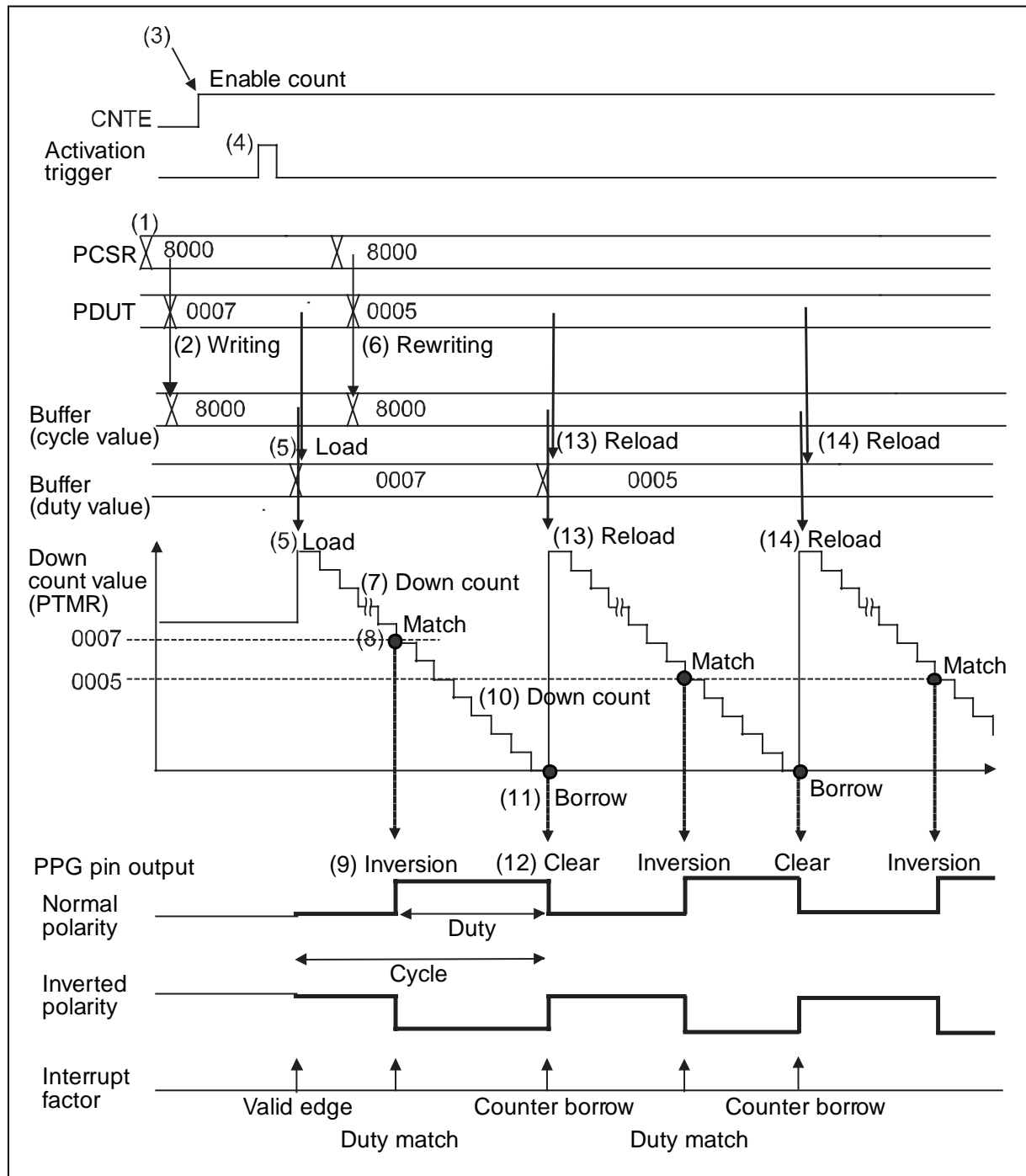
5.2. One-shot Operation

5.3. Restart Operation

5.1. PWM Operation

This section explains the PWM operation of the PPG.

During the PWM operation, programmable variable-duty pulses are output at the PPG pin.



- (1) Writing cycle values
- (2) Writing duty value and transferring cycle value to the buffer
- (3) Enabling of PPG operation
- (4) Activation trigger generation
- (5) Loading cycle value and duty value
- (6) Rewriting duty value and transferring cycle value to the buffer
- (7) Counter decrement

- (8) The down counter matches the duty value
- (9) Output level inversion at the PPG pin
- (10) Counter decrement
- (11) Counter borrow occurrence
- (12) Clearing PPG pin output level (restoration to normal state)
- (13) Reloading cycle value
- (14) Reloading duty value
- (15) Repeat step (6) to (14) (See "9.Notes ").

Calculation formulas:

$$\text{Cycle} = \{\text{Cycle value (PCSR)} + 1\} \times \text{Count clock}$$

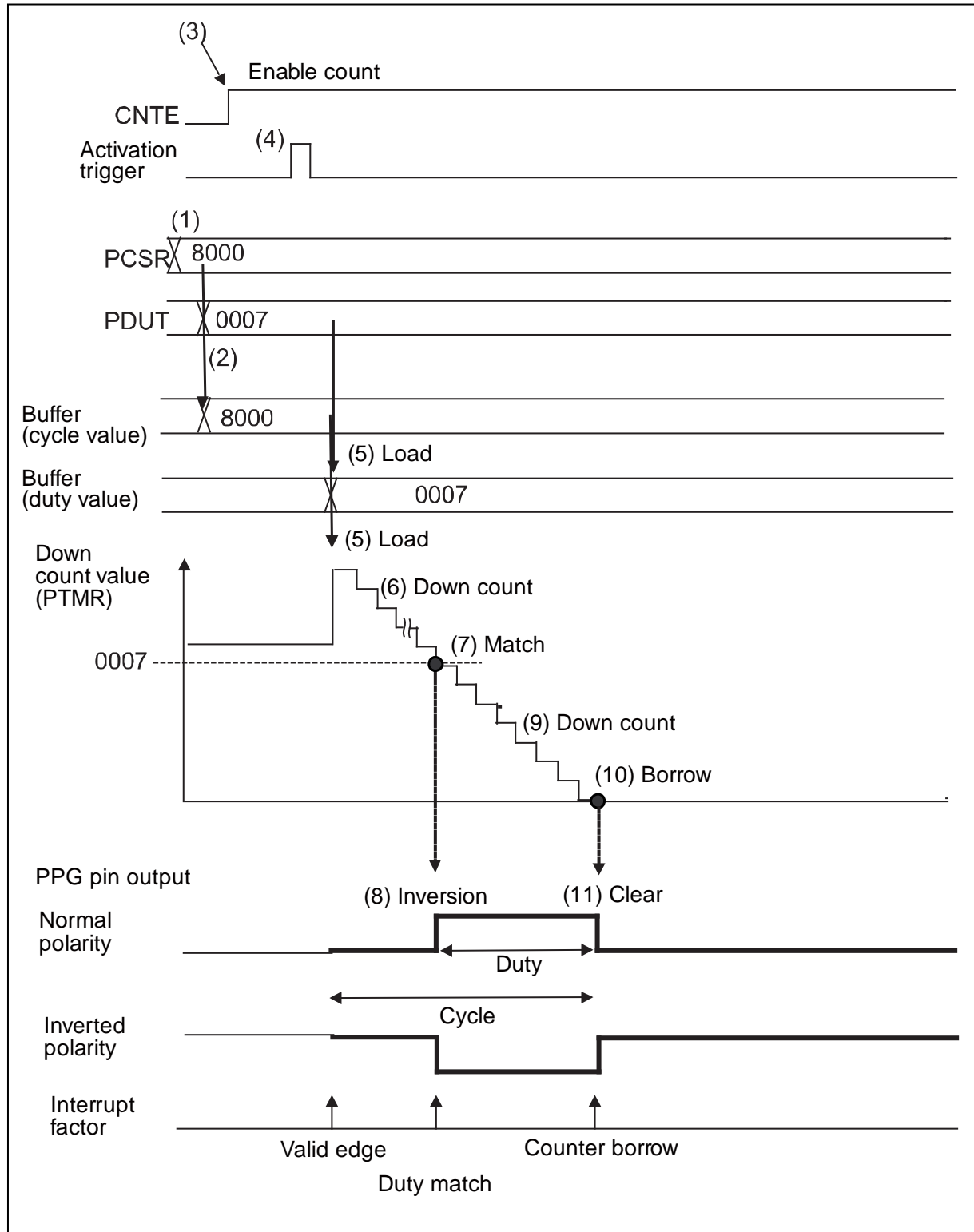
$$\text{Duty} = \{\text{Duty value (PDUT)} + 1\} \times \text{Count clock}$$

$$\text{Time to pulse output} = [\text{Cycle value (PCSR)} - \text{duty value (PDUT)}] \times \text{Count clock}$$

5.2. One-shot Operation

This section explains the one-shot operation of the PPG.

During the one-shot operation, one-shot pulses are output at the PPG pin.



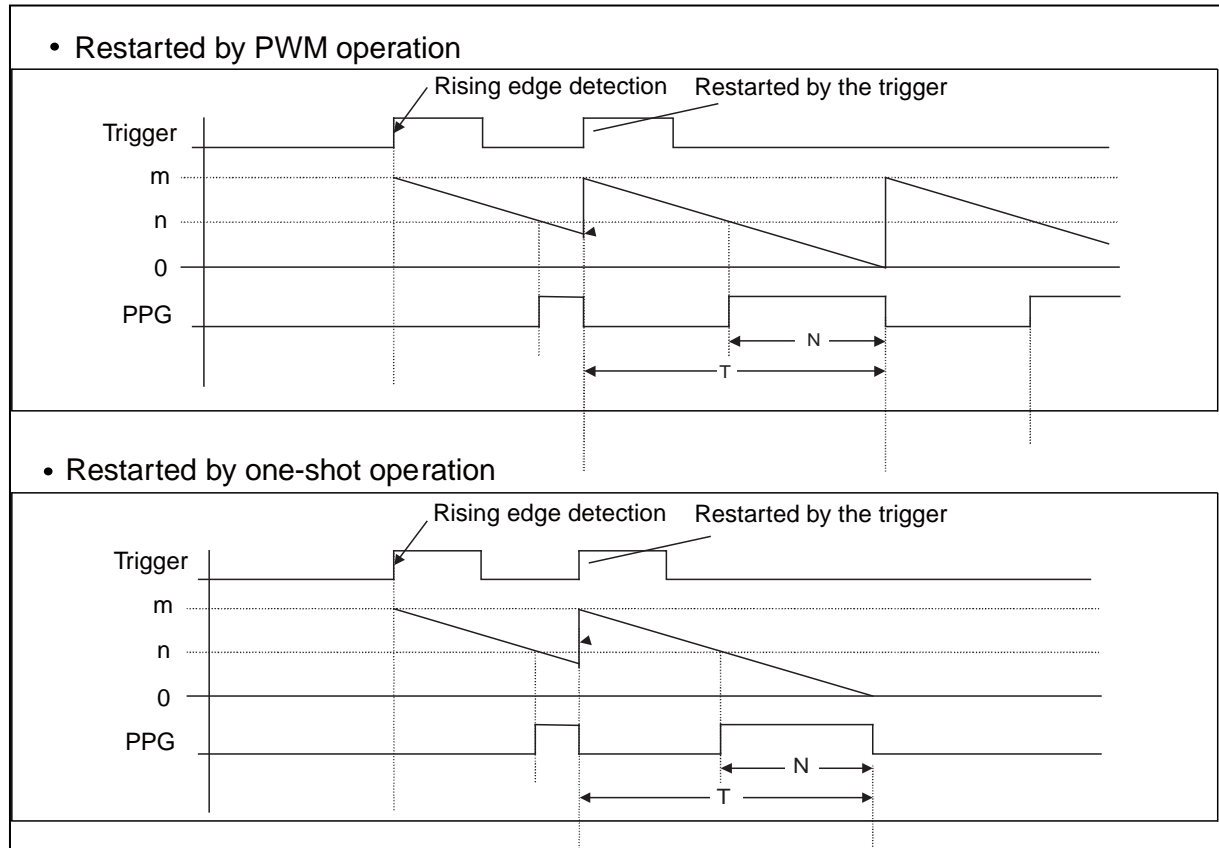
- (1) Writing cycle values
 - (2) Writing duty value and transferring cycle value to the buffer
 - (3) Enabling of PPG operation
 - (4) Activation trigger generation
 - (5) Loading cycle value and duty value
 - (6) Counter decrement
 - (7) The down counter matches the duty value
 - (8) Output level inversion at the PPG pin
 - (9) Counter decrement
 - (10) Counter borrow occurrence
 - (11) Clearing PPG pin output level (restoration to normal state)
 - (12) End of operation sequence
- (See "9. Notes ".)

5.3. Restart Operation

This section explains the restart operation of the PPG.

The restart operation is as follows:

* N = duty, T = cycle, m = cycle setting register (PCSR) value, n = duty setting register (PDUT) value



When restart operation is disabled, second and latter triggers will be invalid for both the PWM operation and the one-shot operation.

(Triggers after the down counter is stopped will still be valid even if second and latter triggers occur.)

6. Setting

This section explains setting of the PPG.

Table 6-1 Settings required for PPG operation

Setting	Setting register	Setting method
Cycle and duty value setting	PPG cycle setting (PCSR0 to PCSR23) PPG duty setting (PDUT0 to PDUT23)	See 7.1
Enabling PPG operation	PPG control status (PCN0 to PCN23)	See 7.2
Operation mode selection (PWM/one-shot)		See 7.3
Restart enable		See 7.4
Count clock selection		See 7.5
PPG output mask selection		See 7.6
Trigger selection · Software trigger · External trigger · Internal trigger (reload timer, GCN20/21/22/23/24/25:EN bit)		PPG control status (PCN0 to PCN23) Trigger input from TRG pin General control 10/11/12/13/14/15 (GCN10/11/12/13/14/15)
Output polarity selection	PPG control status (PCN0 to PCN23)	See 7.8
PPG pin output setting	Set the pins as peripheral output. For setting, see the "CHAPTER: I/O PORTS".	
Trigger generation · External trigger · Software trigger	Trigger input from TRG pin PPG control status (PCN0 to PCN23)	See 4.3
· Reload timer	See "CHAPTER: RELOAD TIMER".	
· GCN20/21/22/23/24/25:EN bit	General control 20/21/22/23/24/25 (GCN20/21/22/23/24/25)	See 4.6

Table 6-2 Settings required for stopping PPG operation

Setting	Setting register	Setting method
PPG stop bit setting	PPG control status (PCN0 to PCN23)	See 7.11

Table 6-3 Settings required for fixing output level

Setting	Setting register	Setting method
Output polarity selection	PPG control status (PCN0 to PCN23)	See 7.8
PPG output mask selection		See 7.6
Setting cycle value = duty value	PPG duty setting (PDUT0 to PDUT23)	See 7.6

Table 6-4 Settings required for PPG interrupt

Setting	Setting register	Setting method
Setting for PPG interrupt vector and PPG interrupt level	See "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".	See 7.12
PPG interrupt factor selection (Activation trigger generation, borrow generation, duty match)	PPG control status (PCN0 to PCN23)	See 7.13
PPG interrupt setting Interrupt request clear Interrupt request enable		See 7.14

7. Q&A

This section explains Q&A of the PPG.

- 7.1. How to Set (Rewrite) Cycle and Duty Values
- 7.2. How to Enable/Stop PPG Operation?
- 7.3. How to Set PPG Operation Mode (PWM/One-shot)
- 7.4. How to Restart
- 7.5. Type and Selection of Count Clock
- 7.6. How to Fix the PPG Pin Output Level
- 7.7. Type and Selection of Activation Trigger
- 7.8. How to Reverse the Output Polarity
- 7.9. How to Change a Pin to a PPG Output Pin
- 7.10. How to Generate Activation Trigger
- 7.11. How to Stop PPG Operation
- 7.12. Interrupt-related Registers
- 7.13. Type and Selection of Interrupts
- 7.14. How to Enable/Disable/Clear Interrupt

7.1. How to Set (Rewrite) Cycle and Duty Values

This section explains how to set (rewrite) the cycle and duty values.

Cycle value setting and duty value setting

- Set the cycle value in the PPG cycle setting register PCSRn. (n = 0 to 23)
- Set the duty value in the PPG duty setting register PDUTn. (n = 0 to 23)
- As the PPG cycle setting register and PPG duty setting register have their own buffers, no timing consideration for writing is required.

Calculation formulas:

PCSR register value = {Cycle/Count clock} - 1

PDUT register value = {"H" width (duty)*Count clock} - 1

*: Normal polarity (OSEL=0)

Available setting range

PCSR register value = PDUT register value to FFFF_H (65535)

PDUT register value = 0 to PCSR register value

Note:

Be sure to set the duty value after the cycle is set.(See "9. Notes".)

7.2. How to Enable/Stop PPG Operation?

This section explains how to enable/stop the PPG operation.

Enabling PPG operation

Use the PPG operation enable bit (PCNn:CNTE). (n = 0 to 23)

Control	PPG operation enable bit (CNTE)
How to stop PPG operation	Set to "0"
How to enable PPG operation	Set to "1"

Activate the PPG after the PPG operation is enabled.
(See "9. Notes".)

7.3. How to Set PPG Operation Mode (PWM/One-shot)

This section explains how to set the PPG operation mode (PWM/one-shot).

Use the mode selection bit (PCNn:MDSE) for selecting an operation mode. (n = 0 to 23)

Operating mode	Mode selection bit (MDSE)
How to set to PWM operation	Set to "0"
How to set to one-shot operation	Set to "1"

(See "9. Notes".)

7.4. How to Restart

This section explains how to restart the PPG.

Restart enable

PPG restart can be enabled while the PPG is running.

Use the restart enable bit (PCNn:RTRG) for setting.(n = 0 to 23)
(See "9. Notes".)

7.5. Type and Selection of Count Clock

This section explains the type and selection of the count clock.

Count clock selection

The count clock can be selected from the following four types in the table below:

Use the count clock selection bit (PCNn:CKS[1:0]). (n = 0 to 23)

Count clock	Count clock selection bit		Example) Peripheral clock (PCLK) = 16 MHz	
	CKS1	CKS0	Count clock	Cycle (1 to FFFF _H)
PCLK	0	0	16MHz	125.0 ns to 4.096 μs
PCLK/4	0	1	4MHz	500 ns to 16.384 μs
PCLK/16	1	0	1MHz	2.0 μs to 65.536 ms
PCLK/64	1	1	250kHz	8.0 μs to 262.144 ms

(See "9. Notes".)

7.6. How to Fix the PPG Pin Output Level

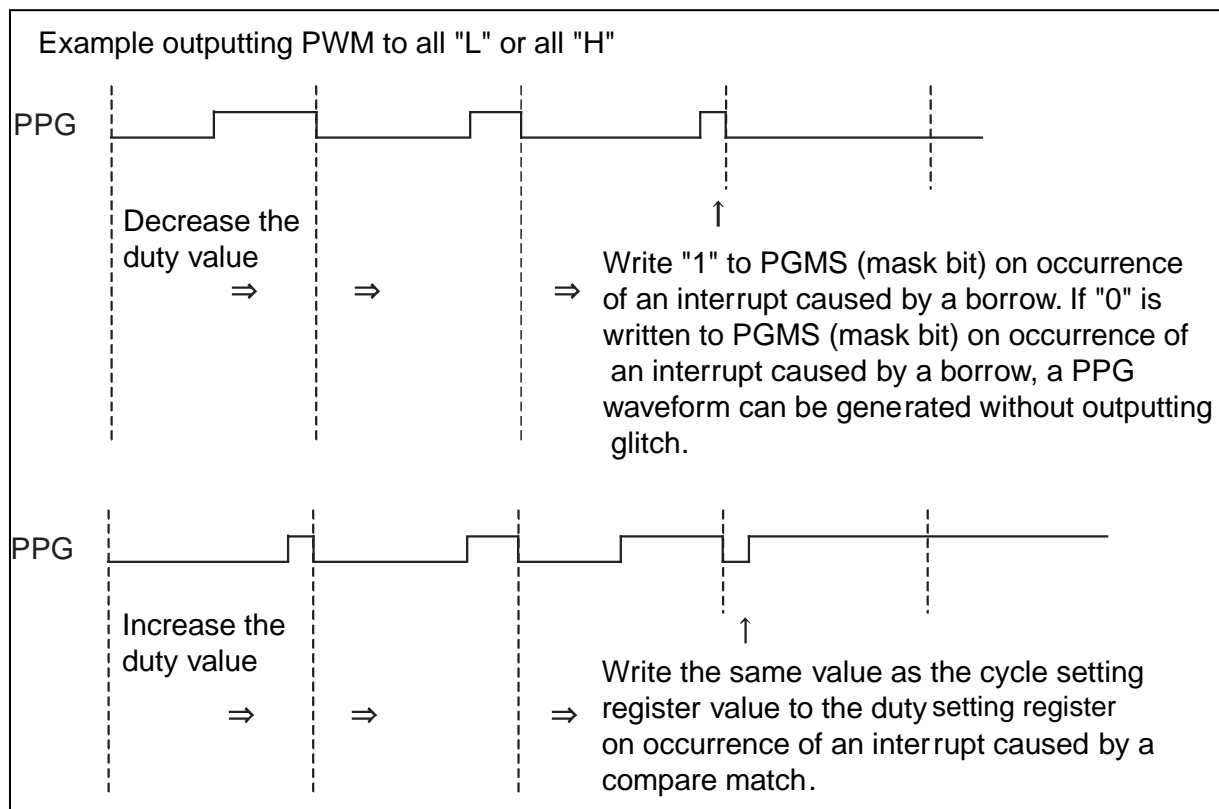
This section explains how to fix the PPG pin output level.

PPG output mask selection

The PPG pin output level can be fixed.

Use the PPG output mask selection bit (PCNn:PGMS) and duty value (PDUT) for setting.(n = 0 to 23)

PPG pin output	PPG output polarity selection bit (OSEL)	Setting method
How to fix the level to "L" in normal polarity	OSEL is "0"	Set the PPG output mask selection bit (PGMS) to "1"
How to fix the level to "H" in normal polarity	OSEL is "0"	Set cycle value (PCSR) = duty value (PDUT)
How to fix the level to "H" in reversed polarity	OSEL is "1"	Set the PPG output mask selection bit (PGMS) to "1"
How to fix the level to "L" in reversed polarity	OSEL is "1"	Set cycle value (PCSR) = duty value (PDUT)



7.7. Type and Selection of Activation Trigger

This section explains the type and selection of the activation trigger.

■ Selecting internal trigger

- The software trigger is always valid.
- The internal trigger of PPG0 to PPG3 is the GCN20 register.
The internal trigger of PPG4 to PPG7 is the GCN21 register.
The internal trigger of PPG8 to PPG11 is the GCN22 register.
The internal trigger of PPG12 to PPG15 is the GCN23 register.
The internal trigger of PPG16 to PPG19 is the GCN24 register.
The internal trigger of PPG20 to PPG23 is the GCN25 register.
- Use TSEL0/TSEL1/TSEL2/TSEL3 of the following general control registers for the settings for the internal triggers:
 - GCN10 register (PPG0 to PPG3)
 - GCN11 register (PPG4 to PPG7)
 - GCN12 register (PPG8 to PPG11)
 - GCN13 register (PPG12 to PPG15)
 - GCN14 register (PPG16 to PPG19)
 - GCN15 register (PPG20 to PPG23)

Settings for PPG0 to PPG3 are as follows:

Internal trigger	Example for PPG0 (GCN10:TS EL0[3:0] setting value)	Example for PPG1 (GCN10:TS EL1[3:0] setting value)	Example for PPG2 (GCN10:TS EL2[3:0] setting value)	Example for PPG3 (GCN10:TS EL3[3:0] setting value)
How to select EN0 bit of the GCN20 register	Set to "0000"			
How to select EN1 bit of the GCN20 register	Set to "0001"			
How to select EN2 bit of the GCN20 register	Set to "0010"			
How to select EN3 bit of the GCN20 register	Set to "0011"			
How to select reload timer 0	Set to "0100"			
How to select reload timer 1	Set to "0101"			

■ **Selecting external trigger**

Use TSEL0/TSEL1/TSEL2/TSEL3 of the following general control registers for the settings for the external triggers:

- GCN10 register (PPG0 to PPG3)
- GCN11 register (PPG4 to PPG7)
- GCN12 register (PPG8 to PPG11)
- GCN13 register (PPG12 to PPG15)
- GCN14 register (PPG16 to PPG19)
- GCN15 register (PPG20 to PPG23)

Settings for PPG0 to PPG3 are as follows:

External trigger	Example for PPG0 (GCN10:TSEL0[3:0] setting value)	Example for PPG1 (GCN10:TSEL1[3:0] setting value)	Example for PPG2 (GCN10:TSEL2[3:0] setting value)	Example for PPG3 (GCN10:TSEL3[3:0] setting value)
How to select external trigger (TRGn)	Set to any of following values. "1000", "1001", "1010", "1011"			

Specifying a same trigger to multiple PPGs will activate multiple PPGs simultaneously.
(See "9. Notes".)

■ **Selecting internal/external trigger edge**

Use trigger input edge selection bits (PCN0:EGS[1:0]) to (PCN23:EGS[1:0]) for internal/external trigger edge settings.

Selecting internal trigger edge	Trigger input edge selection bits (EGS[1:0])
No trigger is detected (software trigger only)	Set to "00"
Trigger is generated at "L" → "H" (rising)	Set to "01"
Trigger is generated at "H" → "L" (falling)	Set to "10"
Trigger is generated at both edges	Set to "11"

(See "9. Notes".)

7.8. How to Reverse the Output Polarity

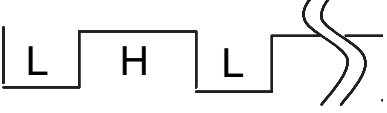
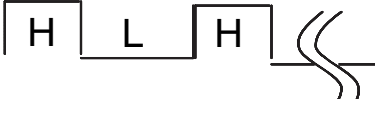
The section explains how to reverse the output polarity.

Output polarity selection

The polarity in the normal state can be specified as following table:

Use the PPG output polarity selection bit (PCNn:OSEL) for setting. (n = 0 to 23)

("Normal state" is a state which does not output pulses.)

Output level in the normal state	PPG output polarity selection bit (OSEL)
<p>To achieve "L" level output (normal polarity)</p> 	<p>Set to "0"</p>
<p>To achieve "H" level output (inverted polarity)</p> 	<p>Set to "1"</p>

7.9. How to Change a Pin to a PPG Output Pin

The section explains how to change a pin to a PPG output pin.

Set the pins as peripheral output. For setting, see "CHAPTER: I/O PORTS".

7.10. How to Generate Activation Trigger

The section explains how to generate an activation trigger.

Trigger generation

The following is how to generate activation triggers.

How to activate software trigger

Use the software trigger bit (PCNn:STRG) for setting. (n = 0 to 23)

If "1" is written to the software trigger bit (STRG), the activation trigger will be generated.

This bit is always valid independent of the state of GCN10 register to GCN15 register.

How to activate with external trigger

See "7.7 Type and Selection of Activation Trigger". Set the pins TRG0, TRG1 and TRG2 as peripheral input. For setting, see "CHAPTER: I/O PORTS". Then you will be able to generate the activation trigger by changing the input level for the pins TRG0, TRG1 and TRG2.

How to activate with reload timer 0/1

You need to set up and activate the reload timer. See "CHAPTER: RELOAD TIMER" for details.

The activation trigger will be generated when underflow of the reload timer generated the specified edge in the reload timer output signal.

How to activate with EN trigger input bits (GCN20/21/22/23/24/25:EN[0:3])

The activation trigger will be generated by rewriting the level of the EN trigger input bits (GCN20/21/22/23/24/25:EN[0:3]) with software.

Edge	Software setting (EN0, EN1, EN2, EN3)
Rising edge	First set the EN bit to "0", then set the EN bit to "1".
Falling edge	First set the EN bit to "1", then set the EN bit to "0".

How to activate multiple PPGs simultaneously

Multiple PPGs will be activated on trigger by specifying the same trigger (trigger input bit) from the PPG trigger specification bits.

Note:

The PPG will not be activated on the activation trigger before the PPG operation is enabled. Be sure to enable the PPG operation before generating the activation trigger. (See "7.2 How to Enable/Stop PPG Operation?".)

7.11. How to Stop PPG Operation

This section explains how to stop the PPG operation.

Set the PPG stop bit. (See "7.2 How to Enable/Stop PPG Operation?".)

7.12. Interrupt-related Registers

This section explains the interrupt-related registers.

Setting for PPG interrupt vector and PPG interrupt level

The PPG number, interrupt level and interrupt vector are as follows:

For information on the interrupt level and interrupt vector, see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

	Interrupt vector (default)	Interrupt level setting register (ICR[4:0])
PPG0	#40 Address: 0FFF5C _H	Interrupt level register (ICR24) Address: 00458 _H
PPG1		
PPG10		
PPG11		
PPG20		
PPG21		
PPG2	#41 Address: 0FFF58 _H	Interrupt level register (ICR25) Address: 00459 _H
PPG3		
PPG12		
PPG13		
PPG22		
PPG23		
PPG4	#42 Address: 0FFF54 _H	Interrupt level register (ICR26) Address: 0045A _H
PPG5		
PPG14		
PPG15		
PPG6	# 43 Address: 0FFF50 _H	Interrupt level register (ICR27) Address: 0045B _H
PPG7		
PPG16		
PPG17		
PPG8	# 44 Address: 0FFF4C _H	Interrupt level register (ICR28) Address: 0045C _H
PPG9		
PPG18		
PPG19		

Clear the interrupt request flags (PCNn:IRQF) by software before the recovery from the interrupt process as the flags will not be cleared automatically. (Write "0" to the IRQF bit) (n = 0 to 23)

7.13. Type and Selection of Interrupts

This section explains the type and selection of interrupts.

Selecting interrupt factor

The interrupt factor can be selected from following four factors:

Use interrupt factor setting bits (PCNn:IRS[1:0]) for setting. (n = 0 to 23)

Interrupt factor	Interrupt factor setting bits (IRS[1:0])
Software trigger or internal trigger	Set to "00"
Down counter borrow (match with the specified cycle)	Set to "01"
Duty match	Set to "10"
Down counter borrow (match with the specified cycle) or duty match	Set to "11"

7.14. How to Enable/Disable/Clear Interrupt

This section explains how to enable/disable/clear interrupt.

Interrupt request enable flag and interrupt request flag

Use the interrupt request enable bit (PCNn:IREN) for enabling interrupts. (n = 0 to 23)

Operation	Interrupt request enable bit (IREN)
How to disable interrupt request	Set to "0"
How to enable interrupt request	Set to "1"

Use the interrupt request bit (PCNn:IRQF) for clearing interrupt requests. (n = 0 to 23)

Operation	Interrupt request bit (IRQF)
How to clear interrupt request	Write "0"

(See "9. Notes".)

8. Sample Programs

This section explains sample programs of the PPG.

<p>Setting procedure example 1</p> <p>PWM output from PPG4, Software trigger (duty1/4), Normal polarity</p> <pre> graph TD A[Initial setting (PPG4)] --> B[Activation (PPG4)] </pre> <p>< Initial setting> - Port</p> <table border="1"> <thead> <tr> <th></th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>PPG output setting for ports</td> <td>See "CHAPTER: I/O Port".</td> </tr> </tbody> </table> <p>- PPG4 control</p> <table border="1"> <thead> <tr> <th></th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Control register setting</td> <td>PCN4</td> </tr> <tr> <td>Timer operation enable»</td> <td>.CNTE</td> </tr> <tr> <td>Software trigger (unprocessed)»</td> <td>.STRG</td> </tr> <tr> <td>Operation mode selection»</td> <td>.MDSE</td> </tr> <tr> <td>Restart disable»</td> <td>.RTRG</td> </tr> <tr> <td>Clock source selection»</td> <td>.CKS1-0</td> </tr> <tr> <td>Output mask selection»</td> <td>.PGMS</td> </tr> <tr> <td>Edge selection»</td> <td>.EGS1-0</td> </tr> <tr> <td>Interrupt disable»</td> <td>.IREN</td> </tr> <tr> <td>Interrupt flag clear»</td> <td>.IRQF</td> </tr> <tr> <td></td> <td>.IRS1-0</td> </tr> <tr> <td>Output polarity selection»</td> <td>.OSEL</td> </tr> </tbody> </table> <p>- Cycle setting</p> <table border="1"> <thead> <tr> <th></th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Cycle setting for PPG4</td> <td>PCSR4</td> </tr> </tbody> </table> <p>- Duty setting</p> <table border="1"> <thead> <tr> <th></th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Duty setting for PPG4</td> <td>PDUT4</td> </tr> </tbody> </table> <p><Activation> - PPG4 activation</p> <table border="1"> <thead> <tr> <th></th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>PPG4 activation</td> <td>PCN4.STRG</td> </tr> </tbody> </table> <p><Others> (Note) You need settings for clock and "_set_il"(numerical value) in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)" for details.</p>		Register name.Bit name	PPG output setting for ports	See "CHAPTER: I/O Port".		Register name.Bit name	Control register setting	PCN4	Timer operation enable»	.CNTE	Software trigger (unprocessed)»	.STRG	Operation mode selection»	.MDSE	Restart disable»	.RTRG	Clock source selection»	.CKS1-0	Output mask selection»	.PGMS	Edge selection»	.EGS1-0	Interrupt disable»	.IREN	Interrupt flag clear»	.IRQF		.IRS1-0	Output polarity selection»	.OSEL		Register name.Bit name	Cycle setting for PPG4	PCSR4		Register name.Bit name	Duty setting for PPG4	PDUT4		Register name.Bit name	PPG4 activation	PCN4.STRG	<p>Program example 1</p> <pre> void PPG_sample_1(void) { PPG4_initial(); PPG4_start(); } void PPG4_initial(void) { PORT_SETTING_PPG4_OUT(); /* Set the PPG4 pins as peripheral input. */ IO_PCN4.hword = 0x8000; /* Setting value = 1000_0000_0000_0000 */ /* bit15 = 1 CNTE timer enable */ /* bit14 = 0 STRG Software trigger */ /* bit13 = 0 MDSE PWM operation */ /* bit12 = 0 RTRG restart disable */ /* bit11 to 10 = 00 CKS1,0 */ /* bit9 = 0 PGMS PPG output mask */ /* bit8 = 0 Undefined bit */ /* bit7 to 6 = 00 EGS1,0 Edge selection: disabled */ /* bit5 = 0 IREN interrupt request enable */ /* bit4 = 0 IRQF interrupt request flag */ /* bit3 to 2 = 00 IRS1,0 Interrupt factor: software trigger */ /* bit1 = 0 Undefined bit */ /* bit0 = 0 OSEL normal polarity */ IO_PCSR4 = 0x0909; /* PPG cycle setting */ IO_PDUT4 = 0x0242; /* PPG duty ratio (1/4) setting */ } void PPG4_start(void) { IO_PCN4.bit.STRG = 1; /* bit14 = 1 STRG Software trigger */ } </pre>
	Register name.Bit name																																										
PPG output setting for ports	See "CHAPTER: I/O Port".																																										
	Register name.Bit name																																										
Control register setting	PCN4																																										
Timer operation enable»	.CNTE																																										
Software trigger (unprocessed)»	.STRG																																										
Operation mode selection»	.MDSE																																										
Restart disable»	.RTRG																																										
Clock source selection»	.CKS1-0																																										
Output mask selection»	.PGMS																																										
Edge selection»	.EGS1-0																																										
Interrupt disable»	.IREN																																										
Interrupt flag clear»	.IRQF																																										
	.IRS1-0																																										
Output polarity selection»	.OSEL																																										
	Register name.Bit name																																										
Cycle setting for PPG4	PCSR4																																										
	Register name.Bit name																																										
Duty setting for PPG4	PDUT4																																										
	Register name.Bit name																																										
PPG4 activation	PCN4.STRG																																										

Setting procedure example 2

PPG one-shot output from PPG2, Reload timer ch.0 (duty1/2), Normal polarity

Initial setting (PPG2)

Initial setting (reload timer 0)

Activation(PPG2)

<Initial setting>

- Port	Register name.Bit name
PPG output setting for ports	See "CHAPTER: I/O Port".

- PPG2 control

Control register setting	Register name.Bit name
Timer operation enable»	.CNTEN
Software trigger (unprocessed)»	.STRG
Operation mode selection»	.MDSE
Restart disable»	.RTRG
Clock source selection»	.CKS1-0
Output mask selection»	.PGMS
Edge selection»	.EGS1-0
Interrupt disable»	.IREN
Interrupt flag clear»	.IRQF
	.IRS1-0
Output polarity selection»	□OSEL

- Cycle setting

Cycle setting for PPG2	Register name.Bit name
	PCSR2

- Duty setting

Duty setting for PPG2	Register name.Bit name
	PDUT2

- Trigger selection

PPG2 trigger selection	Register name.Bit name
	GCN10.TSEL2

<Initial setting (reload timer 0)>

- Control for reload timer 0

Control register setting	Register name.Bit name
Mode selection»	.MOD
Internal clock selection»	.TRGM,CSL
Trigger selection»	.TRGM
Output level selection»	.OUTL
Reload enable»	.RELD
Interrupt disable»	.INTE
Interrupt flag clear»	.UF
Count enable»	.CNTE
Software trigger (unprocessed)»	.TRG

- Count value

Count value setting	Register name.Bit name
	TMRLRA0

<Activation>

- Trigger will be input to the PPG2 by activation of the reload timer 0

Software trigger generation	Register name.Bit name
	TMCSR0.TRG

<Others>

(Note)

You need settings for clock and "_set_il"(numerical value) in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)" for details.

Program example 2

```

void PPG_sample_2(void)
{
    PPG2_initial();
    RTIMO_initial();
    RTIMO_start ();
}

void PPG2_initial(void)
{
    PORT_SETTING_PPG2_OUT(); /* Set the PPG2 pins as peripheral input */

    IO_PCN2.hword = 0x8040; /* Setting value = 1000_0000_0100_0000 */
                          /* bit15 = 1   CNTE timer enable */
                          /* bit14 = 0   STRG Software trigger */
                          /* bit13 = 0   MDSE PWM operation */
                          /* bit12 = 0   RTRG restart disable */
                          /* bit11 to 10 = 00 CKS1,0 */
                          /* bit9 = 0    PGMS PPG output mask */
                          /* bit8 = 0    Undefined bit */
                          /* bit7 to 6 = 01   EGS1,0 edge selection: rising edge */
                          /* bit5 = 0    IREN interrupt request enable */
                          /* bit4 = 0    IRQF interrupt request flag */
                          /* bit3 to 2 = 00   IRS1,0 Interrupt factor: software trigger */
                          /* bit1 = 0    Undefined bit */
                          /* bit0 = 0    OSEL normal polarity */

    IO_PCSR2 = 0x0909; /* PPG cycle setting */

    IO_PDUT2 = 0x0484; /* PPG duty ratio (1/2) setting */

    IO_GCN10.bit.TSEL2 = 4; /* bit11 to 8 = 0100 TSEL23 to 20 Reload timer ch.0 */
}

void RTIMO_initial(void)
{
    IO_TMCSR0.hword = 0x0012; /* Setting value = 0000_0000_0001_0010 */
                          /* bit15 to 14 = 00   MOD=00 Single mode */
                          /* bit13 to 12 = 00   TRGM=00 No external trigger detection/
                          Software trigger */
                          /* bit11 to 9 = 000   CSL=000 Count source selection
                          (peripheral clock/2) */
                          /* bit8 to 6 = 000   GATE=0, EF=0 */
                          /* bit5 = 0   OUTL=0 External output level */
                          /* bit4 = 1   RELD=1 Reload enable */
                          /* bit3 = 0   INTE=0 Interrupt request disabled */
                          /* bit2 = 0   UF=0   Flag clear */
                          /* bit1 = 1   CNTE=1 Timer operation enable/activation trigger wait */
                          /* bit0 = 0   TRG=0   Trigger is still disabled */

    IO_TMRLRA0 = 0xffff; /* Initial value for counting */
}

void rtim0_start(void)
{
    IO_TMCSR0 = IO_TMCSR0 | 0x0001; /* bit0 = 1 TRG software trigger */
}
                    
```

Setting procedure example 3

PPG one-shot output from PPG1, High output, activation trigger (GCN20.EN1)

Initial setting (PPG1)

Activation (PPG1)

<Initial setting>

-Port	Register name.Bit name
PPG output setting for ports	See "CHAPTER: I/O Port".

-PPG1 control

Register name.Bit name	Register name.Bit name
Control register setting	PCN1
Timer operation enable >>	.CNTE
Software trigger (unprocessed) >>	.STRG
Operation mode selection >>	.MDSE
Restart disable >>	.RTRG
Clock source selection >>	.CKS1-0
Output mask selection >>	.PGMS
Edge selection >>	.EGS1-0
Interrupt disable >>	.IREN
Interrupt flag clear >>	.IRQF
Output polarity selection >>	.SEL

-Cycle setting

Register name.Bit name	Register name.Bit name
Cycle setting for PPG1	PCSR1

-Duty setting

Register name.Bit name	Register name.Bit name
Duty setting for PPG1	PDUT1

-Trigger selection

Register name.Bit name	Register name.Bit name
PPG1 trigger selection	GCN10.TSEL1

-Trigger signal level

Register name.Bit name	Register name.Bit name
Trigger level = "L"	GCN20.EN1

<Activation>

Register name.Bit name	Register name.Bit name
PPG1 activation	PCN4.STRG

Trigger signal level

Register name.Bit name	Register name.Bit name
Trigger level = "H"	GCN20.EN1

<Others>
(Note)
You need settings for clock and ".set_ii"(numerical value) in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)" for details.

Program example 3

```

void PPG_sample_3(void)
{
    PPG1_initial();
    PPG1_start ();
}

void PPG1_initial(void)
{
    PORT_SETTING_PPG1_OUT(); /* Set the PPG1 pins as peripheral input */

    IO_PCN1.hword = 0xA040; /* Setting value = 1010_0000_0100_0000 */
                          /* bit15 = 1   CNTE timer enable */
                          /* bit14 = 0   STRG Software trigger */
                          /* bit13 = 1   MDSE One-shot operation */
                          /* bit12 = 0   RTRG restart disable */
                          /* bit11-10 = 00 CKS1,0 */
                          /* bit9 = 0    PGMS PPG output mask */
                          /* bit8 = 0    Undefined bit */
                          /* bit7-6 = 01  EGS1,0 edge selection: rising edge */
                          /* bit5 = 0    IREN interrupt request enable */
                          /* bit4 = 0    IRQF interrupt request flag */
                          /* bit3-2 = 00  IRS1,0 interrupt factor: software trigger */
                          /* bit1 = 0    Undefined bit */
                          /* bit0 = 0    OSEL normal polarity */

    IO_PCSR1 = 0x0909; /* PPG cycle setting */

    IO_PDUT1 = 0x0484; /* PPG duty ratio (1/2) setting */

    IO_GCEN10.bit.TSEL1 = 1; /* bit3-0 = 0001 TSEL03 to 00 EN1 bit of GCN20 */
    IO_GCEN20 = 0x00; /* bit1 = 0 EN1 bit of GNC20 */
}

void PPG1_start(void)
{
    IO_PCN4.bit.STRG = 1; /* bit14 = 1 STRG Software trigger */

    IO_GCEN20 = 0x02; /* bit1 = 1 EN1 bit of GNC20 */
}
                    
```

Setting procedure example 4

Interval interrupt
PPG output from PPG4, Software trigger (duty1/4), Normal polarity

```

graph TD
    A[Initial setting (PPG4)] --> B[Activation (PPG4)]
    B --> C[Interrupt]
            
```

<Initial setting>

Port	Register name.Bit name
PPG output setting for ports	See "CHAPTER: I/O Port".

PPG1 control

Register name.Bit name	Register name.Bit name
Control register setting	PCN4
Timer operation enable»	.CNTE
Software trigger (unprocessed)»	.STRG
Operation mode selection»	.MDSE
Restart disable»	.RTRG
Clock source selection»	.CKS1-0
Output mask selection»	.PGMS
Edge selection»	.EGS1-0
Interrupt disable»	.IREN
Interrupt flag clear»	.IRQF
Output polarity selection»	.OSEL

<Cycle setting

Register name.Bit name	Register name.Bit name
Cycle setting for PPG4	PCSR4

<Duty setting

Register name.Bit name	Register name.Bit name
Duty setting for PPG4	PDUT4

<Interrupt setting

Register name.Bit name	Register name.Bit name
PPG4 interrupt level setting	ICR26
Setting for I flag	(CCR)

<Activation>

Register name.Bit name	Register name.Bit name
Interrupt enable	PCN4.IREN
PPG4 activation	PCN4.STRG

<Interrupt>

Register name.Bit name	Register name.Bit name
(Given process)	
Interrupt request flag clear	PCN4.IRQF

<Interrupt vector>
Vector table setting

<Others>
(Note)
You need settings for clock and ".set_il"(numerical value) in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)" for details.

Program example 4

```

void PPG_sample_4(void)
{
    PPG4_initial();
    PPG4_start ();
}

void PPG4_initial(void)
{
    PORT_SETTING_PPG4_OUT(); /* Set the PPG4 pins as peripheral input. */

    IO_PCN4.hword = 0x8004; /* Setting value = 1000_0000_0000_0100 */
                          /* bit15 = 1   CNTE timer enable */
                          /* bit14 = 0   STRG Software trigger */
                          /* bit13 = 1   MDSE one-shot operation */
                          /* bit12 = 0   RTRG restart disable */
                          /* bit11 to 10 = 00 CKS1,0 */
                          /* bit9 = 0    PGMS PPG output mask */
                          /* bit8 = 0    Undefined bit */
                          /* bit7 to 6 = 01  EGS1,0 edge selection: rising edge */
                          /* bit5 = 0    IREN interrupt request enable */
                          /* bit4 = 0    IRQF interrupt request flag */
                          /* bit3 to 2 = 01  IRS1,0 Interrupt factor: cycle match */
                          /* bit1 = 0    Undefined bit */
                          /* bit0 = 0    OSEL normal polarity */

    IO_PCSR4 = 0x0909; /* PPG cycle setting */

    IO_PDUT4 = 0x0242; /* PPG duty ratio (1/4) setting */

    IO_ICR[26].byte = 0x10; /* Interrupt level (given value) */
    __EI(); /* Interrupt enable */
}

void PPG4_start(void)
{
    IO_PCN4.bit.IREN = 1; /* bit5 = 1 IREN interrupt request enable */
    IO_PCN4.bit.STRG = 1; /* bit14 = 1 STRG Software trigger */
}

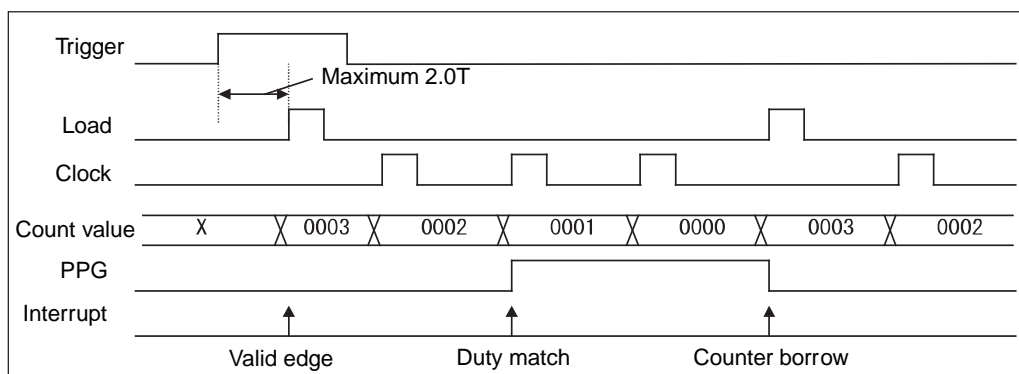
__interrupt void PPG4_int(void)
{
    /* Given process */
    IO_PCN4.bit.IRQF = 0; /* bit14 = 0 IRQF interrupt request flag */
}

Interrupt routine must be specified with the vector table.
#pragma intvect PPG4_int 42
            
```

9. Notes

Notes on the use of the PPG are shown in this section.

- If the timing when the interrupt request flag (PCNn:IRQF) becomes "1" and the timing to become "0" are duplicated, the operation for setting the interrupt request flag to "1" will be prioritized and the request for clearing the flag will be invalid. (n = 0 to 23)
- If the load timing and counting timing of the down counter are duplicated, the load operation will be prioritized.



- The time from the activation trigger to finish loading the counter value requires up to 2.0 T (T: peripheral clock).
- Be sure to set the duty values (PDUTn) after the cycle value is set if you make initial setting and rewriting of the cycle value PCSRn.
(Be sure to write the values in the order of (1) PCSRn, (2) PDUTn.)
In addition, only PDUT can be rewritten for rewriting the duty value only. (n = 0 to 23)
- When you set the duty values (PDUTn), use values smaller than the cycle values (PCSRn). When larger values are set, rewrite the duty values to the smaller ones after the PPG operation is disabled. (n = 0 to 23)
- The PPG cycle setting register PCSRn and PPG duty setting register PDUTn must be accessed in half-word (16-bit). Both upper value and lower value will not be written if the access is made in byte. (n = 0 to 23)
- To activate the PPG, the timer operation enable bit (PCNn:CNTE) must be set to "1" to enable the PPG operation before the activation or simultaneously. (n = 0 to 23)
- Do not change the configuration of the mode (MDSE), restart enable (RTRG), count clock (CKS[2:0]), trigger input edge (EGS[1:0]), interrupt factor (IRS[1:0]), internal trigger (TSEL), and output polarity selection (OSEL), while the PPG is in operation.
If you changed the value while the PPG is in operation, first disable the PPG operation, and then retry register setting.
- When you write values to the GCN20/21/22/23/24/25, the undefined part of upper 4 bits must always be written to "0".
If you have written "1" instead of "0", first stop the PPG operation, and then rewrite them.
- When values other than specified values (1100 to 1111) are set to the activation trigger selection bits (TSEL3, TSEL2, TSEL1, TSEL0) of the GCN10/11/12/13/14/15, the operation will be returned to the normal operation if you first disable the PPG operation, then write the specified values.
- When the timer operation enable bit (PCNn:CNTE) is set to "0" to disable the PPG operation while the PPGn is in operation, the PPG will be stopped to retain the status. (Count value and output level will be retained) Moreover, when the timer operation enable bit (PCNn:CNTE) is set to "1" to enable the PPG operation, the PPG will be restarted from the state where the PPG stopped. (n = 0 to 23)
- As writing to the bits 11 and 10 (count clock selection bits CKS1 and CKS0) of the PPG control register will immediately be reflected just after the writing, setting change must be performed with the counting stopped.

CHAPTER : WATCHDOG TIMER

This chapter explains the watchdog timer.

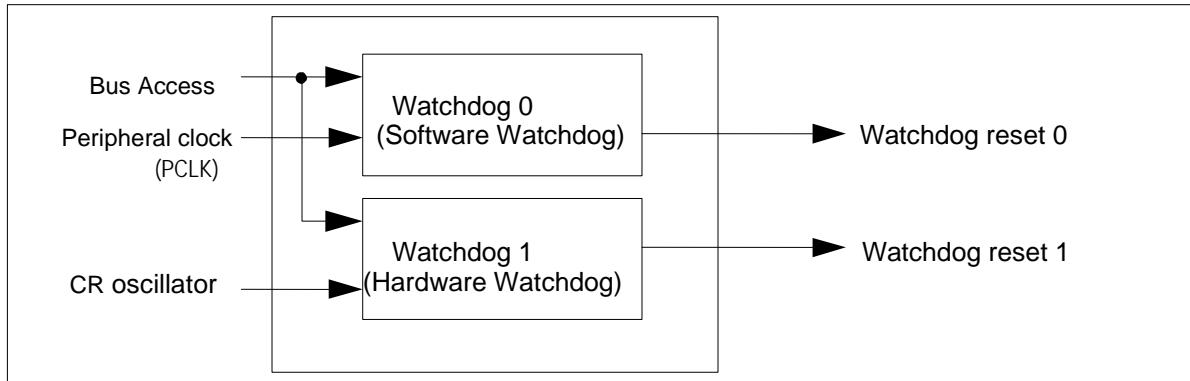
1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Usage Example

1. Overview

This section explains the overview of the watchdog timer.

This series has two watchdog timers that can detect software and hardware running out of control, and generate reset requests.

Figure 1-1 Block Diagram (Overview)



2. Features

This section explains features of the watchdog timer.

■ Watchdog Timer 0 (Software Watchdog)

- **Stop mode detection function**

Able to detect the transition to watch mode or stop mode and generate a reset request.

- **Watchdog timer clear**

The timer is cleared by operation initialization reset or by writing the inverse value of the value previously written to the clear register.

- **Illegal write detection function**

If the incorrect value is written to the clear register, a reset request is generated.

- **Watchdog timer period**

The period can be selected from among sixteen choices of the peripheral clock (PCLK) $\times (2^9 \text{ to } 2^{24})$ cycles.

- **Count stop conditions**

The count stops while the CPU is stopped.

■ Watchdog Timer 1 (Hardware Watchdog)

This timer is driven by the clock generated by the built-in CR oscillator circuit immediately after the reset is released. For information on CR oscillator settings (calibration), see "CHAPTER: RTC/WDT1 (CALIBRATION)".

- **Watchdog timer clear**

The timer is cleared by the operation initialization reset or by writing "0xA5" to the clear register.

- **Illegal write detection function**

If a value other than "0xA5" is written to the clear register, a reset request is generated.

- **Watchdog timer period**

The period is fixed by the hardware at CR oscillator $\times 2^{15}$ cycles.

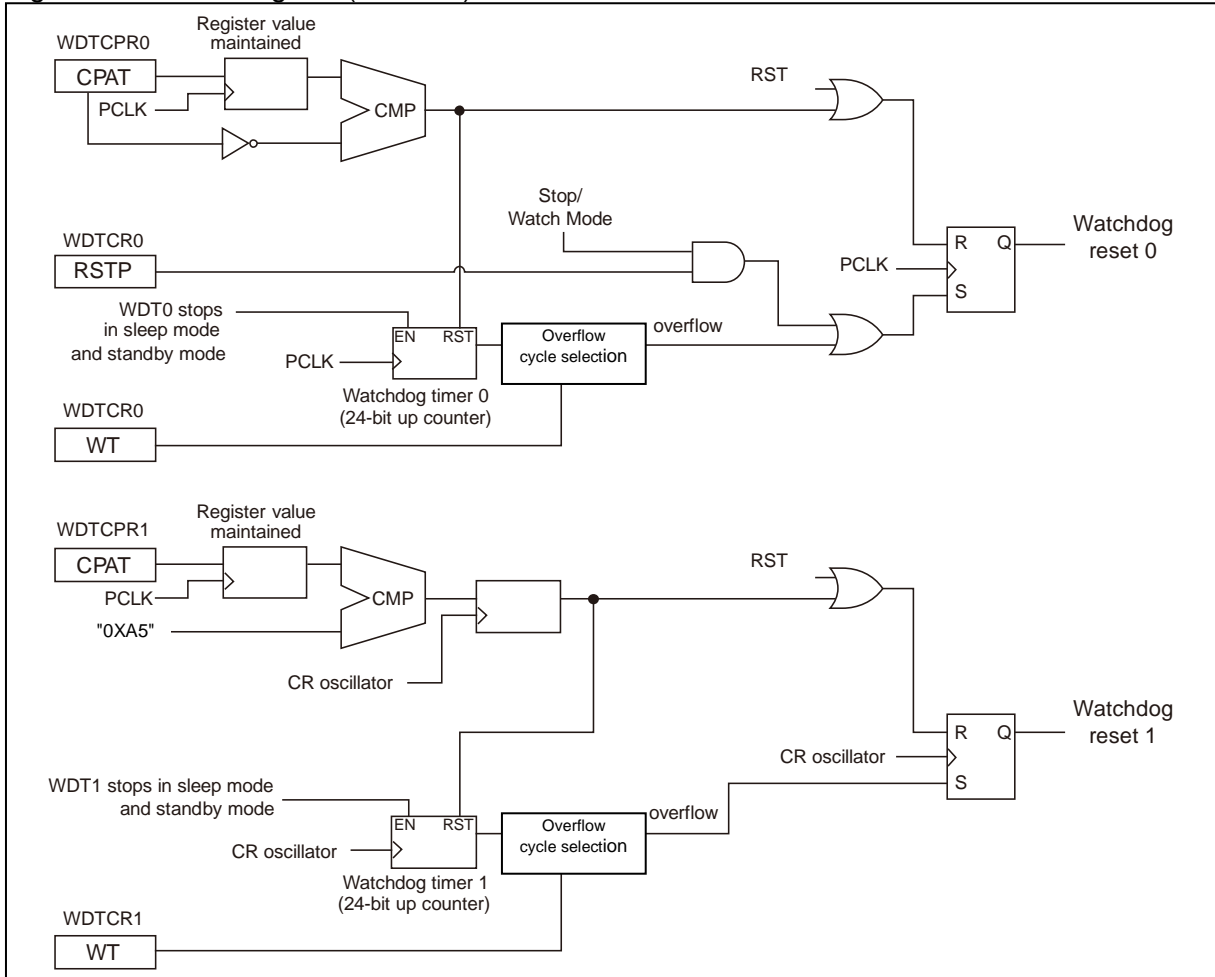
- **Count stop conditions**

The count stops when using ICE, during sleep mode, watch mode, stop mode, and when waiting for the oscillator to stabilize when recovering from standby mode.

3. Configuration

This section shows the configuration of the watchdog timer.

Figure 3-1 Block Diagram (Detailed)



4. Registers

This section explains the registers of the watchdog timer.

Table 4-1 Registers map

Address	Registers				Register function
	+0	+1	+2	+3	
0x003C	WDTCR0	WDTCP0	WDTCR1	WDTCP1	Watchdog timer configuration register 0 Watchdog timer 0 clear register Watchdog timer 1 cycle information register Watchdog timer 1 clear register

4.1. Watchdog Control Register 0 : WDTCR0 (WatchDog Timer Configuration Register 0)

The bit configuration of the watchdog control register 0 (WDTCR0) is explained.

This register configures each of the settings of watchdog timer 0.

Writing to this register is ignored after watchdog timer 0 activates.

■ WDTCR0 : Address 003C_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	RSTP	Reserved		WT[3:0]			
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R0,W0	R0,W0	R/W	R/W	R/W	R/W

[bit7] Reserved

"0" is always written to this bit. The reading value is "0".

[bit6] RSTP (Reset by SToP) : Stop mode detection reset enable

This bit configures whether a reset is generated when a transition to watch mode or stop mode is detected while watchdog timer 0 is operating. When this bit is enabled, the watchdog timer reset 0 occurs when the CPU switches to watch mode or stop mode. When this bit is not enabled, watchdog timer 0 is paused when the CPU switches to watch mode or stop mode, and the count stops until the CPU recovers from watch mode or stop mode.

RSTP	Stop mode detection
0	Not detected (initial value)
1	Generates a reset when detected

Writing to this bit is ignored after watchdog timer 0 activates.

[bit5, bit4] Reserved

"0" is always written to these bits. The reading value is "0".

[bit3 to bit0] WT[3:0] (Watchdog Timer interval) : Watchdog timer cycle selection

These bits configure the number of cycles from when watchdog timer 0 was last cleared until watchdog reset 0 is issued as follows.

WT[3:0]	Watchdog timer 0 cycle
0000	$\text{PCLK (Peripheral Clock)} \times 2^9 \text{ cycles}$
0001	$\text{PCLK} \times 2^{10} \text{ cycles}$
0010	$\text{PCLK} \times 2^{11} \text{ cycles}$
0011	$\text{PCLK} \times 2^{12} \text{ cycles}$
0100	$\text{PCLK} \times 2^{13} \text{ cycles}$
0101	$\text{PCLK} \times 2^{14} \text{ cycles}$
0110	$\text{PCLK} \times 2^{15} \text{ cycles}$
0111	$\text{PCLK} \times 2^{16} \text{ cycles}$
1000	$\text{PCLK} \times 2^{17} \text{ cycles}$
1001	$\text{PCLK} \times 2^{18} \text{ cycles}$
1010	$\text{PCLK} \times 2^{19} \text{ cycles}$
1011	$\text{PCLK} \times 2^{20} \text{ cycles}$
1100	$\text{PCLK} \times 2^{21} \text{ cycles}$
1101	$\text{PCLK} \times 2^{22} \text{ cycles}$
1110	$\text{PCLK} \times 2^{23} \text{ cycles}$
1111	$\text{PCLK} \times 2^{24} \text{ cycles}$

Writing to these bits are ignored after watchdog timer 0 activates.

Watchdog timer 0 is not counted during periods where the CPU is not operating.

Counting is performed while the CPU is operating even if DMA transfers are being performed.

4.2. Watchdog Timer 0 Clear Register : WDT CPR0 (WatchDog Timer Clear Pattern Register 0)

The bit configuration of the watchdog timer 0 clear register (WDT CPR0) is explained.

This register activates or clears (delays the issue of a reset) watchdog timer 0.

■ WDT CPR0 : Address 003D_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	CPAT[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W	R0,W	R0,W	R0,W	R0,W	R0,W	R0,W	R0,W

[bit7 to bit0] CPAT[7:0] (Clear PATtern) : Watchdog timer 0 clear

Watchdog timer 0 activates by the first write to this register after the reset is released. The watchdog timer is cleared after being activated by writing a value with all of the bits inverted from the previous value written. If a value other than the inverse value of the previously written value is written, the watchdog reset 0 is issued at that time.

The value read out from this register is always "0x00" regardless of the value written.

4.3. Watchdog Timer 1 Cycle information Register : WDTCR1 (WatchDog Timer Cycle information Register 1)

The bit configuration of the watchdog timer 1 cycle information register (WDTCR1) is explained.

This register configures each of the settings of watchdog timer 1.

■ **WDTCR1 : Address 003E_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				WT[3:0]			
Initial value	0	0	0	0	0	1	1	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R1,WX	R1,WX	R0,WX

This register cannot be rewritten.

[bit7 to bit4] Reserved

"0" is always read. Writing to it has no effect on operation.

[bit3 to bit0] WT[3:0] (Watchdog Timer interval) : Watchdog timer cycle selection

These bits configure the number of cycles from when watchdog timer 1 was last cleared until watchdog reset 1 is issued. The cycle is fixed to 2^{15} cycles. Writing to these bits are ignored.

WT[3:0]	Watchdog timer 1 cycle
0110	CR oscillator $\times 2^{15}$ cycles (initial value, fixed)

4.4. Watchdog Timer 1 Clear Register : WDT CPR1 (WatchDog Timer Clear Pattern Register 1)

The bit configuration of the watchdog timer 1 clear register (WDT CPR1) is explained.

This register clears watchdog timer 1 (delays the issue of a reset).

■ WDT CPR1 : Address 003F_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	CPAT[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W	R0,W	R0,W	R0,W	R0,W	R0,W	R0,W	R0,W

[bit7 to bit0] CPAT[7:0] (Clear PATtern) : Watchdog timer 1 clear

Watchdog timer 1 activates after the reset is released. The watchdog timer is cleared after being activated by writing "0xA5". When a value other than "0xA5" is written, the watchdog reset 1 is issued at that time. The value read out from this register is always "0x00" regardless of the value written.

5. Operation

This section explains the operation of the watchdog timer.

This section explains the watchdog timer function.

■ Software Watchdog Function

● Setup

Before activating watchdog timer 0, set bits 3 to 0: WT[3:0] of the WDTCR0 register to select the period from clearing the watchdog timer until the reset is issued.

Because watchdog timer 0 is only counted when the CPU is operating, set the period based on the number of program steps and the clock division setting.

Before activating watchdog timer 0, set bit6: RSTP of the WDTCR0 register to select whether or not to generate a reset when a transition to watch mode or stop mode is detected.

- When RSTP=0, the timer stops in watch mode or stop mode.
- When RSTP=1, a reset is generated as soon as the CPU enters watch mode or stop mode.

If you are using watch mode or stop mode, set RSTP=0. Writing to the RSTP bits is ignored after watchdog timer 0 activates.

● Starting

Watchdog timer 0 starts by the first write of any data to the WDTCPR0 register after reset.

It does not matter what the write data is.

The WDTCPR0 register always reads out "0x00" regardless of the data written.

● Operation

This section explains the operation of watchdog timer 0 after it has activated.

Counting Conditions

Watchdog timer 0 counts the rising edges of the peripheral clock (PCLK) while the CPU is operating.

DMA transfers do not effect the operation of the count.

The count only stops while the CPU is stopped, such as in sleep mode. Sampling of the CPU operating state is performed on the peripheral clock (PCLK), with changes in the operating state within the peripheral clock cycle ignored.

The count is stopped in emulator mode when the ICE is connected. The count is also stopped if the watchdog reset suppression function is enabled in the debug interface functions while the ICE is connected.

In all of the above circumstances, because the counter is not cleared but is only paused when the count is stopped, when the count resumes the count continues from the counter value prior to the stop.

Because the peripheral clock is stopped during the oscillation stabilization wait time of the source clock, the watchdog timer count also stops.

Clearing the Timer

Once the watchdog timer has activated, the timer must be cleared before the timer period has elapsed.

Clearing the watchdog timer is performed by writing data to WDTCPRO. The write data must be the value with all bits inverted of the data previously written to WDTCPRO.

When watchdog timer 0 is activated, for example, if it is activated by writing "0x55" to WDTCPRO, the timer is cleared subsequently by alternatingly writing "0xAA" then "0x55" then "0xAA" then "0x55".

Because the read value of WDTCPRO is always "0x00", the value written previously cannot be determined by reading WDTCPRO. Storing the previously written value in a different location can be avoided by performing two consecutive writes when performing a single clear.

Reset Request Generation

Watchdog timer 0 generates a watchdog reset request under the following conditions.

- An overflow of the configured watchdog timer cycle occurs
- There is a transition to watch mode or to stop mode while stop mode detection reset is enabled
- A value other than the inverse value of the previous written value is written to the clear register

■ Hardware Watchdog Function

● Setup

Bits 3 to bit0: WT[3:0] of the WDTCR1 register of watchdog timer 1 is fixed in hardware.

● Activating

Watchdog timer 1 activates immediately after the reset is released.

● Operation

This section explains the operation of watchdog timer 1 after it has activated.

Counting Conditions

Watchdog timer 1 counts the rising edges of the CR oscillator.

The count is stopped in emulator mode when the ICE is connected. The count is also stopped if the watchdog reset suppression function is enabled in the debug interface functions while the ICE is connected.

The count stops during sleep mode, watch mode, stop mode, and when waiting for the oscillator to stabilize when recovering from standby mode.

Clearing the Timer

Once the watchdog timer has activated, the timer must be cleared before the timer period has elapsed.

Watchdog timer 1 is cleared by writing "0xA5" to WDTCPR1.

Reset Request Generation

Watchdog timer 1 generates a watchdog reset request under the following conditions.

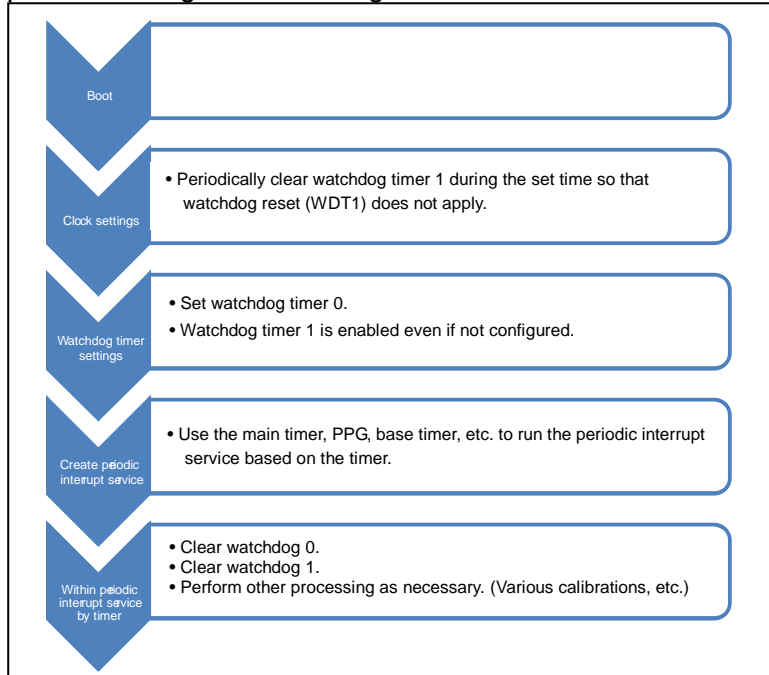
- An overflow of the watchdog timer cycle occurs
- A value other than "0xA5" is written to WDTCPR1

6. Usage Example

This section shows a usage example of the watchdog timer.

This example is provided for clearing the watchdog timer.

Figure 6-1 Example of Clearing the Watchdog Timers



CHAPTER : BASE TIMER

This chapter explains the base timer.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains the overview of the base timer.

This series includes the base timer for 2 channels. These base timers provide the following functions:

- 16/32-bit reload timer
- 16-bit PWM timer
- 16-bit PPG timer
- 16/32-bit PWC timer

2. Features

This section explains features of the base timer.

This series includes the base timer for 2 channels. Each channel selects and uses appropriate ones of the following functions:

- 2.1 16/32-bit Reload Timer
- 2.2 16-bit PWM Timer
- 2.3 16/32-bit PWC Timer
- 2.4 16-bit PPG Timer

2.1. 16/32-bit Reload Timer

This section explains the 16/32-bit reload timer of the base timer.

A base timer can be used as a 16/32-bit reload timer. The 16/32-bit reload timer is a timer that decreases from a preset value.

- **I/O mode**

You can select a signal (external clock, external activation trigger, waveform) I/O operation using the base timer I/O selection function.

- **Timer mode**

You can run multiple timers for individual channels and can combine 16-bit reload timers for two channels into one 32-bit reload timer.

- **Operation mode**

You can select one of the following two:

- Reload mode: In this mode, when the down counter underflows, the preset value (cycle) is reloaded to allow the timer to restart counting.
- One-shot mode: Once the down counter underflows, the counter will no longer count.

- **Count clock**

You can select one of five internal (peripheral) clocks and three external clocks (ECK signals).

- Internal clock (peripheral clock): Clock obtained by dividing the frequency of the peripheral clock (PCLK) by 1, 4, 16, 128, or 256.
- External clock (ECK signal): Rising edges, falling edges, or both edges are detected.

- **Activation trigger**

One of the following can be selected:

- Software trigger
- External event: Rising edge, falling edge, or both edges
- 16/32-bit reload timer reactivation: The 16/32-bit reload timer can be reactivated when an activation trigger is detected during counting.

- **Interrupt request**

An interrupt request can be generated in one of the following events:

- IRQ0: When an underflow occurs
- IRQ1: When a 16/32-bit reload timer activation trigger is detected

2.2. 16-bit PWM Timer

This section explains the 16-bit PWM timer of the base timer.

The 16-bit PWM timer, PWM standing for Pulse Width Modulator Timer, produces a desired waveform at an external pin when a duty ratio of the pulse width is specified.

- **I/O mode**

You can select a signal (external clock, external activation trigger, waveform) I/O operation using the base timer I/O selection function.

- **Operation mode**

You can select one of the following two:

- Reload mode: In this mode, when the 16-bit down counter underflows, the preset cycle is reloaded to allow the timer to restart counting.
- One-shot mode: Once the 16-bit down counter underflows, the counter will no longer count.

- **Count clock**

You can select one of five internal (peripheral) clocks and three external clocks (ECK signals).

- Internal clock (peripheral clock): Clock obtained by dividing the frequency of the peripheral clock (PCLK) by 1, 4, 16, 128, or 256.
- External clock (ECK signal): Rising edges, falling edges, or both edges are detected.

- **Activation trigger**

One of the following can be selected:

- Software trigger
- Three external events: (Rising edge, falling edge, or both edges detection)

- **16-bit PWM timer reactivation**

The 16-bit PWM timer can be reactivated when an activation trigger is detected during counting.

- **Output waveform**

The output signal from the external pin can be fixed at the "L" or "H" level.

- **Interrupt request**

An interrupt request can be generated in one of the following events:

- IRQ0 : When an underflow occurs or counting is performed up to a preset value (duty)
- IRQ1 : When a 16-bit PWM timer activation trigger is detected

2.3. 16/32-bit PWC Timer

This section explains the overview of the 16/32-bit PWC timer of the base timer.

The 16/32-bit PWC timer, PWC standing for Pulse Width Counter, is used to measure pulse widths or cycles.

- **I/O mode**

You can select a signal (waveform) I/O operation using the base timer I/O selection function.

- **Timer mode**

You can run multiple timers for individual channels and can combine 16-bit PWC timers for two channels into one 32-bit PWC timer.

- **Operation mode**

You can select one of the following two:

- Single measurement mode: In this mode, measurement is conducted only once.
- Continuous measurement mode: In this mode, after one sequence of measurement is conducted, the input of the next measurement start edge is awaited and the detection of the next measurement start edge triggers another sequence of measurement.

- **Count clock**

You can select one of the internal (peripheral) clocks obtained by dividing the frequency of the peripheral clock (PCLK) by five types.

- Clocks obtained by dividing the frequency of the peripheral clock (PCLK) by 1, 4, 16, 128, and 256.

- **Measurement mode**

You can select one of the following five options relating to the pulse width and cycle to be measured:

- "H" pulse width: Duration in which the input signal is maintained at the "H" level
- "L" pulse width: Duration in which the input signal is maintained at the "L" level
- Rising edge interval: Period from the detection of a rising edge to the detection of the next rising edge
- Falling edge interval: Period from the detection of a falling edge to the detection of the next falling edge
- Edge-to-edge pulse width: The width between consecutive input edges is one of the following:
 - Period from the detection of a rising edge to the detection of the falling edge
 - Period from the detection of a falling edge to the detection of the rising edge

- **16/32-bit PWC timer reactivation**

The 16/32-bit PWC timer can be reactivated when an activation trigger is detected during counting.

- **Interrupt request**

An interrupt request can be generated in one of the following events:

- IRQ0 : When an overflow occurs
- IRQ1 : When measurement ends

2.4. 16-bit PPG Timer

This section explains the 16-bit PPG timer of the base timer.

The 16-bit PPG timer, PPG standing for Programmable Pulse Generator Timer, is a timer that generates a waveform with a desired pulse width.

- **I/O mode**

You can select a signal (external clock, external activation trigger, waveform) I/O operation using the base timer I/O selection function.

- **Operation mode**

You can select one of the following two:

- Reload mode: A sequence of "L"-level and "H"-level signals (consecutive pulses) is output.
- One-shot mode: A string of one "L"-level signal and one "H"-level signal (single pulses) is output.

- **Count clock**

You can select one of five internal (peripheral) clocks and three external clocks (ECK signals).

- Internal clock (peripheral clock): Clock obtained by dividing the frequency of the peripheral clock (PCLK) by 1, 4, 16, 128, or 256.
- External clock (ECK signal): Rising edges, falling edges, or both edges are detected.

- **Activation trigger**

One of the following can be selected:

- Software trigger
- Three external events: (Rising edge, falling edge, or both edges detection)

- **16-bit PPG timer reactivation**

The 16-bit PPG timer can be reactivated when an activation trigger is detected during counting.

- **Interrupt request**

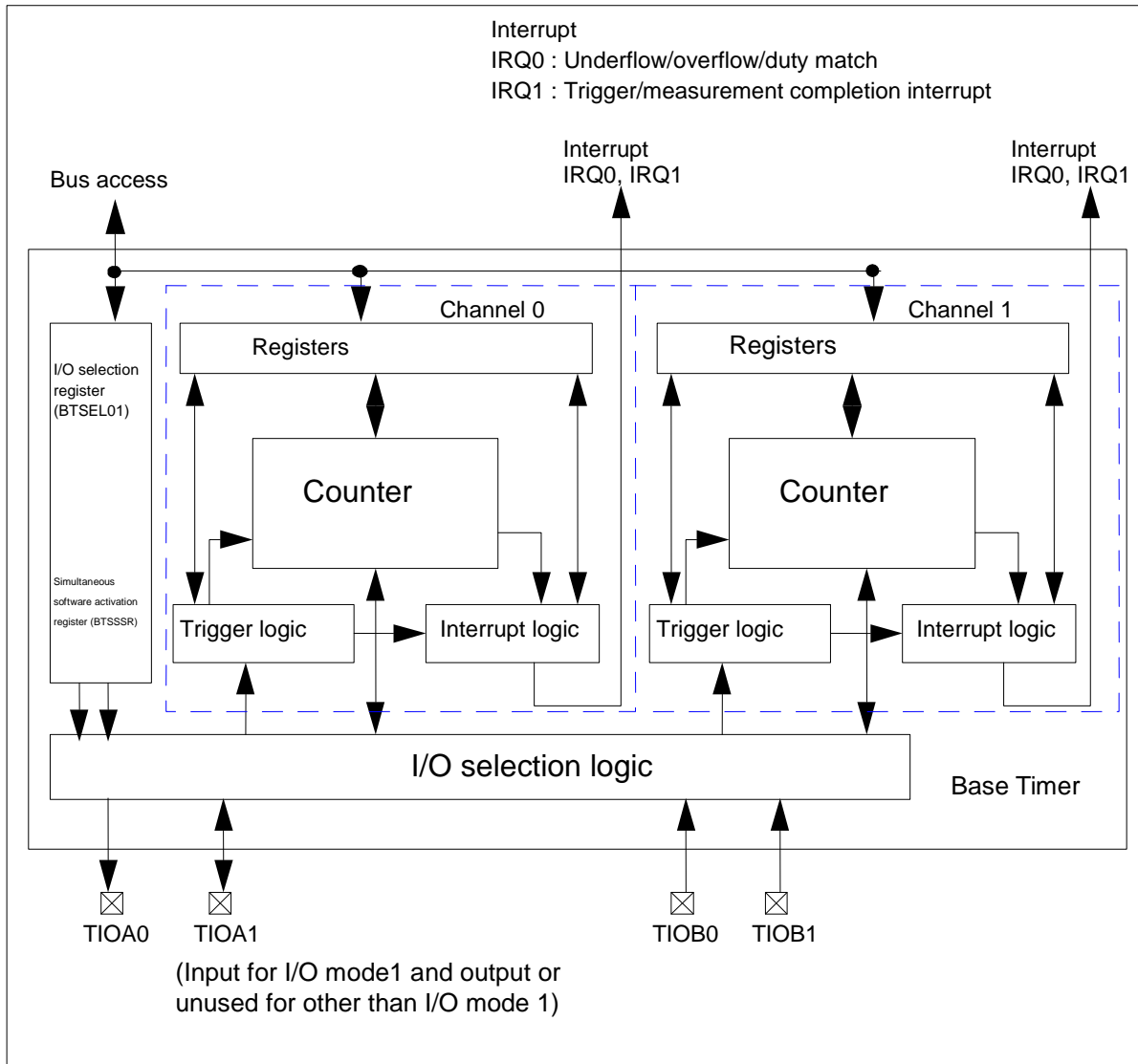
An interrupt request can be generated in one of the following events:

- IRQ0 : When an underflow occurs based on the value of the base timer x H width setting reload register (BTxPRLH).
- IRQ1 : When a 16-bit PPG timer activation trigger is detected.

3. Configuration

This section explains the configuration of the base timer.

Figure 3-1 Block Diagram (Overview)



4. Registers

This section explains registers of the base timer.

■ List of Base Addresses (Base_addr) and External Pins

Table 4-1 Table of Base Addresses (Base_addr) and External Pins

Channel number	Base address	External pin
0	0x0080	TIOA0, TIOA1, TIOB0, and TIOB1 are assigned based on the BTSEL01 register setting.
1	0x0090	

■ **Registers Map**

Table 4-2 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0080	[Common] BT0TMR		[Common] BT0TMCR		[Common] Timer register 0 [Common] Control register 0
0x0084	Reserved	[Reload timer] BT0STC [PWM] BT0STC [PPG] BT0STC [PWC] BT0STC	Reserved		[Reload timer] Status control register 0 [PWM] Status control register 0 [PPG] Status control register 0 [PWC] Status control register 0
0x0088	[Reload timer] BT0PCSR [PWM] BT0PCSR [PPG] BT0PRLH [PWC] Reserved		[Reload timer] Reserved [PWM] BT0PDUT [PPG] BT0PRLH [PWC] BT0DTBF		[Reload timer] Cycle setting register 0 [PWM] Cycle setting register 0 [PPG] L width setting reload register 0 [PWM] Duty setting register 0 [PPG] H width setting reload register 0 [PWC] Data buffer register 0
0x008C	Reserved				
0x0090	[Common] BT1TMR		[Common] BT1TMCR		[Common] Timer register 1 [Common] Control register 1
0x0094	Reserved	[Reload timer] BT1STC [PWM] BT1STC [PPG] BT1STC [PWC] BT1STC	Reserved		[Reload timer] Status control register 1 [PWM] Status control register 1 [PPG] Status control register 1 [PWC] Status control register 1
0x0098	[Reload timer] BT1PCSR [PWM] BT1PCSR [PPG] BT1PRLH [PWC] Reserved		[Reload timer] Reserved [PWM] BT1PDUT [PPG] BT1PRLH [PWC] BT1DTBF		[Reload timer] Cycle setting register 1 [PWM] Cycle setting register 1 [PPG] L width setting reload register 1 [PWM] Duty setting register 1 [PPG] H width setting reload register 1 [PWC] Data buffer register 1
0x009C	BTSEL01	Reserved	BTSSSR		I/O selection register Simultaneous software activation register

4.1. Common Registers

This section explains the common registers of the base timer.

The registers described here are common to various operations.

4.1.1. Timer Registers 0, 1 : BTxTMR (Base Timer 0/1 TiMer Register)

The bit configuration of timer registers 0, 1 (BTxTMR) is shown below.

These registers are used to read the counter value on the timer. The registers are only valid when its content represents a reload, PWM, or PPG timer. The value read from the registers is undefined if a PWC timer is read. For information on the values that will be read, see the section of Operation Description.

Note:

These registers must be accessed in 16-bit mode.

■ **BTxTMR : Address Base_addr + 00_H (Access: Half-word)**

	bit15	bit14	---	bit2	bit1	bit0
	D[15:0]					
Initial value	0	0	---	0	0	0
Attribute	R,WX	R,WX	---	R,WX	R,WX	R,WX

4.1.2. Timer Control Registers 0, 1 : BTxTMCR (Base Timer 0/1 TiMer Control Register)

The bit configuration of timer control registers 0, 1 (BTxTMCR) is shown below.

These registers are used to variously configure and stop the base timer and to issue software triggers.

Notes:

- If you need to change the FMD[2:0] setting, once reset it to FMD[2:0] = 000, and then set FMD[2:0] to the desired value.
- Reserved bits must be set to "0".
- If you want to set bits of these registers except for the software trigger (STRG) bit, proceed as follows:
 1. Once stop operation by writing FMD[2:0] = 000 or CTEN = 0.
 2. Write desired values to the timer function selection bits (FMD[2:0]) and other bits.
- When writing to the software trigger bit (STRG), be careful not to clear other bits.
- Since FMD[2:0] = 000 specifies reset mode, you cannot set other bits when setting FMD[2:0] = 000.
- These registers must be accessed in 16-bit mode.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxTMCR : Address Base_addr + 02_H (Access: Half-word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	CKS[2:0]			[PWM - PPG] RTGEN [Others] Reserved	[PWM - PPG] PMSK [PWC] EGS[2] [Others] Reserved	EGS[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W R0,WX(*3)	R/W	R/W	R/W	R/W R0,WX(*1)	R/W R0,WX(*1)	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	[Reload timer - PWC] T32 [Others] Reserved	FMD[2:0]			[Reload timer - PWM - PPG] OSEL [Others] Reserved	MDSE	CTEN	STRG
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W R0,WX(*1) R0,WX(*2)	R/W	R/W	R/W	R/W R/W0(*1)	R/W	R/W	R0,W

(*1) Attribute assumed for "Reserved"

(*2) Attribute assumed for a 32-bit timer serving an odd-numbered channel

(*3) Attribute assumed for a 32-bit timer serving an odd-numbered channel or for a 16/32-bit PWC timer

[bit15] Reserved

Writing to this bit does not affect the operation.

[bit14 to bit12] CKS[2:0] (Clock Select) : Count clock selection bits

Select a count clock.

CKS[2:0]	Description	
	Clock source	Description
000	Internal clock (Peripheral clock (PCLK))	1 division
001		4 division
010		16 division
011		128 division
100		256 division
101		[Reload timer/PWM/PPG] external clock (ECK signal) [PWC] Setting is prohibited
110	Falling edge	
111	Both edges	

In the PWC mode, settings of 101,110, and 111 are prohibited.

[PWM/PPG] [bit11] RTGEN (Restart by TriGger ENable) : Restart enable bit

If "1" is written to the STRG bit or an external activation trigger (TGIN signal) is detected, this bit sets whether or not to recount the value of cycle setting register (BTxPCSR)/L width setting reload register (BTxPRL) by reloading it to the 16-bit down counter.

RTGEN	Description of operation
0	Does not reactivate
1	Reactivates

[PWM/PPG] [bit10] PMSK (Pulse MaSK) : Pulse output mask bit

Select a level of waveform to output (TOUT signal) from the followings:

- Normal output : Output the waveform output from the 16-bit PWM/PPG timer without modification.
- Fixed output : Output a sequence of "L" level or "H" level signals regardless of the settings of cycle or duty.

PMSK	Description
0	Normal output
1	Fixed output

If the fixed output is selected by writing "1" to this bit, the level being output will vary depending on the settings of the OSEL bit.

- If OSEL=0 : "L" level will be output.
- If OSEL=1 : "H" level will be output.

[Reload timer/PWM/PPG] [bit9, bit8] EGS[1:0] (EdGe Select) : Trigger input selection bits
Select an effective edge for the external activation trigger (TGIN) signal.

EGS[1:0]	Description
00	Trigger input has no effect on the operation
01	Rising edge
10	Falling edge
11	Both edges

[PWC] [bit10 to bit8] EGS[2:0] (EdGe Select) : Measurement mode selection bits
Select a measurement mode.

EGS[2:0]	Description
000	"H" pulse width measurement: Duration in which the input signal is maintained at the "H" level
001	Rising edge interval measurement: Time from the detection of a rising edge to the detection of the next rising edge
010	Falling edge interval measurement: Time from the detection of a falling edge to the detection of the next falling edge
011	Edge-to-edge pulse width measurement: The width between consecutive input edges is either:(1) or (2). (1) Time from the detection of a rising edge to the detection of the falling edge (2) Time from the detection of a falling edge to the detection of the rising edge
100	"L" pulse width measurement: Duration in which the input signal is maintained at the "L" level(Time from the detection of a falling edge to the detection of the rising edge)
101 110 111	Setting is prohibited

[Reload timer/PWC] [bit7] T32 (Timer 32bit) : 32-bit timer selection bit
Select whether to run the 16/32-bit timer individually by each channel or use the two channels as 32-bit timer through a cascade connection. Set this bit for both channel 0 and channel 1.

T32 (channel 0)	T32 (channel 1)	Description
0	0	16-bit timer independent operation respectively
0	1	Setting is prohibited
1	0	32-bit timer
1	1	Setting is prohibited

Note:

Change this bit after changing the FMD[2:0] to 000. (Once you have changed the FMD[2:0] to 000, set the T32 bit and FMD[2:0] to a required value at the same time.)

[bit6 to bit4] FMD[2:0] (Function MoDe) : Timer function selection bits

These bits are used to select a function of base timer. To change these bits, go to 000 (reset mode) first, and set it to another mode.

FMD[2:0]	Description
000	Reset mode (Writing FMD = 000 will reverse the state of the base timer after the reset. Each register will be reset to the initial value.)
001	16-bit PWM timer
010	16-bit PPG timer
011	16/32-bit reload timer
100	16/32-bit PWC timer
101 110 111	Setting is prohibited

[bit3] OSEL (Output SElect) : Output polarity selection bit

When this bit is set, the signal level (H/L) output from TOUT will be inverted.

OSEL	Description
0	Normal output
1	Inverted output

[bit2] MDSE (MoDe Select) : Mode selection bit

[Reload timer-PWM]

MDSE	Description
0	Reload mode: When the down counter underflows, the value of the base timer x cycle setting register (BTxPCSR) is reloaded to continue counting.
1	One-shot mode: Once the down counter underflows, the counter will no longer count.

[PPG]

MDSE	Description
0	Reload mode: A sequence of "L"-level and "H"-level signals (consecutive pulses) is output.
1	One-shot mode: A string of one "L"-level signal and one "H"-level signal (single pulses) is output.

[PWC]

MDSE	Description
0	Continuous measurement mode: In this mode, after one sequence of measurement is conducted, the input of the next measurement start edge is awaited and the detection of the next measurement start edge triggers another sequence of measurement.
1	Single measurement mode: In this mode, measurement is conducted only once.

[bit1] CTEN (Count ENable) : Counter operation enable bit
Enables/disables the counter operation.

CTEN	Description
0	Disables/stops the operation.
1	Enables the operation.

[bit0] STRG (Software TRiGger) : Software trigger bit
Functions as a trigger for timer activation, etc.

Notes:

- When writing to this bit, be careful not to clear other bits.
- When writing to CTEN and FMD[2:0] simultaneously, issue a trigger as soon as the operation is enabled.

STRG	Description
0	Ignores.
1	Issues a trigger.

4.1.3. I/O Selection Register : BTSEL01 (Base Timer SElect register ch.0 and ch.1)

The bit configuration of the I/O selection register (BTSEL01) is shown below.

These bits are used to set the I/O mode of ch.0 and ch.1 for the base timer.

Notes:

- These registers must be accessed in 8-bit mode.
- These registers will not be initialized even if reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTSEL01 : Address 009C_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				SEL01[3:0]			
Initial value	1	1	1	1	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W	R/W	R/W

[bit3 to bit0] SEL01[3:0] (SElect) : ch.0/ch.1 I/O selection bits

These bits are used to set the I/O mode of ch.0 and ch.1 for the base timer.

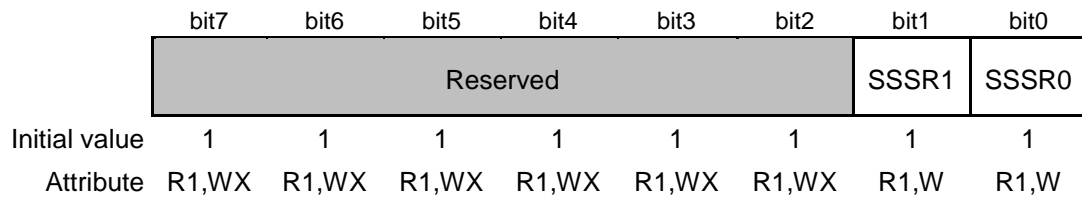
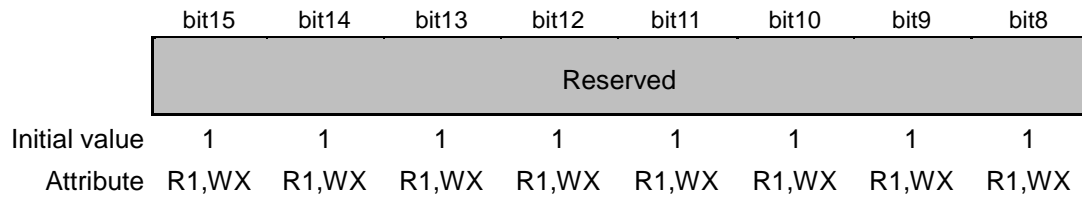
SEL01[3:0]	Description
0000	I/O mode 0 (16-bit timer standard mode)
0001	I/O mode 1 (32-bit timer full mode)
0010	I/O mode 2 (External trigger sharing mode)
0011	Setting is prohibited
0100	I/O mode 4 (Timer activation/stop mode)
0101	I/O mode 5 (Simultaneous software activation mode)
0110	I/O mode 6 (Software activation timer activation/stop mode)
0111	I/O mode 7 (Timer activation mode)
1xxx	Setting is prohibited

4.1.4. Simultaneous Software Activation Register : BTSSSR (Base Timer Software Synchronous Start Register)

The bit configuration of the simultaneous software activation register (BTSSSR) is shown below.

This register is the input signal in the I/O modes 5 and 6. Trigger can be generated simultaneously for all channels with this register.

■ **BTSSSR : Address 009E_H (Access: Byte, Half-word)**



[bit1] SSSR1 (Software Synchronous Start Register ch.1) : Simultaneous software activation bit ch.1
 [bit0] SSSR0 (Software Synchronous Start Register ch.0) : Simultaneous software activation bit ch.0
 These bits are the input signal in the I/O modes 5 and 6. For the connections, see Figure 5-2 .

SSSR0/1	Description
0	No effect on the operation.
1	"1" pulse to the timer input, then the corresponding channel is activated.

4.2. Registers for 16/32-bit Reload Timer

This section explains registers for 16/32-bit reload timer.

- 4.2.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control)
- 4.2.2. Cycle Setting Registers 0, 1 : BTxPCSR (Base Timer 0/1 Pulse Counter Start Register)

4.2.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 Status Control)

The bit configuration of status control registers 0, 1 (BTxSTC) is shown below.

These registers control interrupt requests.

Notes:

- Reserved bits must be set to "0".
- For the read-modify-write instruction to TGIR and UDIR, "1" is read out.
- These registers must be accessed in 8-bit mode.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxSTC : Address Base_addr + 05_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	TGIE	Reserved	UDIE	Reserved	TGIR	Reserved	UDIR
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R0,W0	R/W	R0,W0	R(RM1),W	R0,W0	R(RM1),W

[bit6] TGIE (TriGger Interrupt Enable) : Trigger interrupt request enable bit

This bit sets whether or not to generate a trigger interrupt request when an activation trigger for 16/32-bit reload timer has been detected (TGIR = 1).

[bit4] UDIE (UnDerflow Interrupt Enable) : Underflow interrupt request enable bit

This bit sets whether or not to generate an underflow interrupt request when the down counter underflows (UDIR = 1).

TGIE/UDIE	Description
0	Disables
1	Enables

[bit2] TGIR (TriGger Interrupt Register) : Trigger interrupt request flag bit

This bit indicates that an activation trigger for the 16/32-bit reload timer has been detected. When the TGIE bit is set to "1" while this bit is "1", a trigger interrupt request will be generated.

[bit0] UDIR (UnDerflow Interrupt Register) : Underflow interrupt request flag bit

This bit indicates that the down counter value has changed from "0000_H" to "FFFF_H" and an underflow occurred. When this bit is "1" and the UDIE bit is set to "1", an underflow interrupt request is generated.

TGIR/UDIR	Read	Write
0	No trigger detection/underflow occurred.	This bit is cleared.
1	Trigger detection/underflow occurred.	No effect on the operation

4.2.2. Cycle Setting Registers 0, 1 : BTxPCSR (Base Timer 0/1 Pulse Counter Start Register)

The bit configuration of cycle setting registers 0, 1 (BTxPCSR) is shown below.

These registers with a buffer set the cycle for 16/32-bit reload timer. The down counter counts down from the value set to these registers.

Notes:

- These registers must be accessed in 16-bit mode.
- Set these registers after selecting a base timer function to the 16/32-bit reload timer (FMD2 to FMD0 = 011) using the FMD2 to FMD0 bits of the timer control register (BTxTMCR).
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxPCSR : Address Base_addr + 08_H (Access: Half-word)**

	bit15	bit14	---	bit2	bit1	bit0
	D[15:0]					
Initial value	0	0	---	0	0	0
Attribute	R/W	R/W	---	R/W	R/W	R/W

[bit15 to bit0] D[15:0] (Data) : Data bits

These registers with a buffer set the cycle for the 16/32-bit reload timer. The down counter counts down from the value set to these registers.

The value set to these registers is loaded to the 16-bit down counter in the following cases:

- When the 16/32-bit reload timer is started
- When the down counter underflows

The following values are set to these registers when two channels of a 16-bit reload timer are cascaded and it is used as the 32-bit reload timer.

- Value of even-number channel cycle setting register (BTxPCSR) : Value of lower 16-bit
- Value of the odd-number channel cycle setting register (BTxPCSR) : Value of upper 16-bit

For this reason, in the 32-bit timer mode, write values into these registers in the following order.

1. Odd-number channel base timer x cycle setting register (BTxPCSR)
2. Even-number channel base timer x cycle setting register (BTxPCSR)

4.3. Registers for 16-bit PWM Timer

This section explains registers for 16-bit PWM timer.

- 4.3.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 Status Control)
- 4.3.2. Cycle Setting Registers 0, 1 : BTxPCSR (Base Timer 0/1 Pulse Counter Start Register)
- 4.3.3. Duty Setting Registers 0, 1 : BTxPDUT (Base Timer 0/1 Pulse DuTy register)

4.3.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 Status Control)

The bit configuration of status control registers 0, 1 (BTxSTC) is shown below.

These registers control interrupt requests.

Notes:

- Reserved bits must be set to "0".
- For the read-modify-write instruction to TGIR, DTIR, and UDIR, "1" is read out.
- These registers must be accessed in 8-bit mode.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxSTC : Address Base_addr + 05_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	TGIE	DTIE	UDIE	Reserved	TGIR	DTIR	UDIR
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R/W	R/W	R0,W0	R(RM1),W	R(RM1),W	R(RM1),W

[bit6] TGIE (TriGger Interrupt Enable) : Trigger interrupt request enable bit
This bit sets whether or not to generate a trigger interrupt request when a 16-bit PWM timer activation trigger is detected (TGIR = 1).

[bit5] DTIE (DuTy Interrupt Enable) : Duty match interrupt request enable bit
This bit sets whether or not to generate a duty match interrupt request when the value of the 16-bit down counter matches the value of the base timer x duty setting register (BTxPDUT) (DTIR = 1).

[bit4] UDIE (UnDerflow Interrupt Enable) : Underflow interrupt request enable bit
This bit sets whether or not to generate an underflow interrupt request when the down counter underflows (UDIR = 1).

TGIE/DTIE/UDIE	Description
0	Disables.
1	Enables.

[bit2] TGIR (TriGger Interrupt Register) : Trigger interrupt request flag bit
This bit indicates that a 16-bit PWM timer activation trigger is detected. When this bit is "1" and the TGIE bit is set to "1", a trigger interrupt request is generated.

[bit1] DTIR (DuTy Interrupt Register) : Duty match interrupt request flag bit
This bit indicates that the value of the 16-bit down counter matches the value of the duty setting register (BTxPDUT) (a duty matches). When this bit is "1" and the DTIE bit is set to "1", a duty match interrupt request is generated.

[bit0] UDIR (UnDerflow Interrupt Register) : Underflow interrupt request flag bit
This bit indicates that the 16-bit down counter value changed from "0000_H" to "FFFF_H" and an underflow occurred. When this bit is "1" and the UDIE bit is set to "1", an underflow interrupt request is generated.

TGIR/DTIR/UDIR	Read	Write
0	A trigger detection, duty match and underflow did not occur.	This bit is cleared.
1	A trigger detection, duty match or underflow occurred.	No effect on the operation.

4.3.2. Cycle Setting Registers 0, 1 : BTxPCSR (Base Timer 0/1 Pulse Counter Start Register)

The bit configuration of cycle setting registers 0, 1 (BTxPCSR) is shown below.

These registers with a buffer set the cycle for the 16-bit PWM timer. The 16-bit down counter counts down from the value set to these registers. When the counter value matches the value set to these registers, the level of the output signal (TOUT) is inverted.

Notes:

- These registers must be accessed in 16-bit mode.
- Set these registers after selecting a base timer function to the 16-bit PWM timer using the FMD2 to FMD0 bits of the timer control register (BTxTMCR).
- Be sure to rewrite the duty setting register (BTxPDUT) when these registers are rewritten.
- Do not set a value smaller than the value set to the duty setting register (BTxPDUT).
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxPCSR : Address Base_addr + 08_H (Access: Half-word)**

	bit15	bit14	---	bit2	bit1	bit0
	D[15:0]					
Initial value	0	0	---	0	0	0
Attribute	R/W	R/W	---	R/W	R/W	R/W

[bit15 to bit0] D[15:0] (Data) : Data bits

These registers with a buffer set the cycle for the 16-bit PWM timer. The 16-bit down counter counts down from the value set to these registers. When the counter value matches the value set to these registers, the level of the output signal (TOUT) is inverted.

These registers have a buffer and thus can be rewritten during counting. The value set to these registers is loaded to the 16-bit down counter in the following cases:

- When the 16-bit PWM timer is activated
- When the down counter underflows

When the same value is set to these registers and the base timer x duty setting register (BTxPDUT), the level of the output signal (TOUT) can be fixed. The output signal level is as follows according to the setting of the OSEL bit of the base timer x timer control register (BTxTMCR):

- OSEL=0: "H" level
- OSEL=1: "L" level

4.3.3. Duty Setting Registers 0, 1 : BTxPDUT (Base Timer 0/1 Pulse DuTy register)

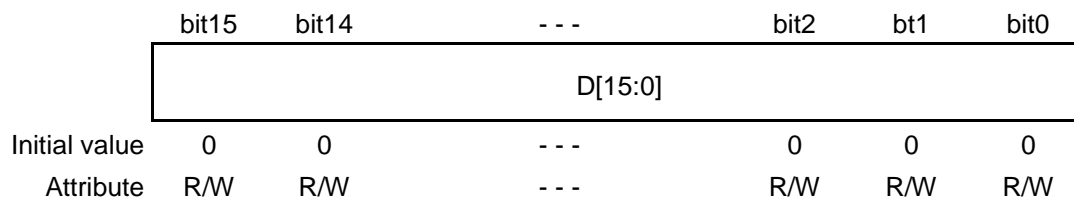
The bit configuration of duty setting registers 0, 1 (BTxPDUT) is shown below.

These registers with a buffer set the duty for the 16-bit PWM timer. When the 16-bit down counter value matches the value set to these registers, the level of the output signal (TOUT) is inverted.

Notes:

- These registers must be accessed in 16-bit mode.
- Set these registers after selecting a base timer function to the 16-bit PWM timer using the FMD2 to FMD0 bits of the timer control register (BTxTMCR).
- Do not set the value higher than the value set to the cycle setting register (BTxPCSR) when these registers are rewritten.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxPDUT : Address Base_addr + 0A_H (Access: Half-word)**



[bit15 to bit0] D[15:0] (Data) : Data bits

These registers with a buffer set the duty for the 16-bit PWM timer. When the 16-bit down counter value matches the value set to these registers, the level of the output signal (TOUT) is inverted.

These registers have a buffer and thus can be rewritten during counting.

If the 16-bit down counter underflows, the buffer value will be transferred.

When the same value is set to these registers and the base timer x cycle setting register (BTxPCSR), the level of the output signal (TOUT) can be fixed. The output signal level is as follows according to the setting of the OSEL bit of the base timer x timer control register (BTxTMCR):

- OSEL=0: All "H" level
- OSEL=1: All "L" level

4.4. Registers for 16-bit PPG Timer

This section explains registers for 16-bit PPG timer.

- 4.4.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control)
- 4.4.2. L Width Setting Registers 0, 1 : BTxPRL (Base Timer 0/1 Pulse Length of "L" register)
- 4.4.3. H Width Setting Registers 0, 1 : BTxPRLH (Base Timer 0/1 Pulse Length of "H" register)

4.4.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 Status Control)

The bit configuration of status control registers 0, 1 (BTxSTC) is shown below.

These registers control interrupt requests.

Notes:

- Reserved bits must be set to "0".
- For the read-modify-write instruction to TGIR and UDIR, "1" is read out.
- These registers must be accessed in 8-bit mode.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxSTC : Address Base_addr + 05_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	TGIE	Reserved	UDIE	Reserved	TGIR	Reserved	UDIR
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R0,W0	R/W	R0,W0	R(RM1),W	R0,W0	R(RM1),W

[bit6] TGIE (TriGger Interrupt Enable) : Trigger interrupt request enable bit

This bit sets whether or not to generate a trigger interrupt request when a 16-bit PPG timer activation trigger is detected (TGIR = 1).

[bit4] UDIE (UnDerflow Interrupt Enable) : Underflow interrupt request enable bit

This bit sets whether or not to generate an underflow interrupt request when the base timer x H width setting reload register (BTxPRLH) completed counting down and the counter underflows (UDIR = 1).

TGIE/UDIE	Description
0	Disabled.
1	Enabled.

[bit2] TGIR (TriGger Interrupt Register) : Trigger interrupt request flag bit

This bit indicates that a 16-bit PPG timer activation trigger is detected. When this bit is "1" and the TGIE bit is set to "1", a trigger interrupt request is generated.

[bit0] UDIR (UnDerflow Interrupt Register) : Underflow interrupt request flag bit

This bit indicates that the base timer x H width setting reload register (BTxPRLH) completed counting down and an underflow occurred. An underflow will occur if the register attempts counting down when the 16-bit down counter value is "0000_H". When this bit is "1" and the UDIE bit is set to "1", an underflow interrupt request is generated.

TGIR/UDIR	Read	Write
0	No trigger detection/underflow occurred.	This bit is cleared.
1	Trigger detection/underflow occurred.	No effect on the operation.

4.4.2. L Width Setting Registers 0, 1 : BTxPRL (Base Timer 0/1 Pulse Length of "L" register)

The bit configuration of L width setting registers 0, 1 (BTxPRL) is shown below.

These registers set the default level for the signal output from the 16-bit PPG timer.

Notes:

- These registers must be accessed in 16-bit mode.
- Set these registers after selecting a base timer function to the PPG timer using the FMD2 to FMD0 bits of the timer control register (BTxTMCR).
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxPRL : Address Base_addr + 08_H (Access: Half-word)**

	bit15	bit14	---	bit2	bit1	bit0
	D[15:0]					
Initial value	0	0	---	0	0	0
Attribute	R/W	R/W	---	R/W	R/W	R/W

[bit15 to bit0] D[15:0] (Data) : Data bits

These registers set the default level for the signal output from the 16-bit PPG timer. When the 16-bit down counter completes counting down the value set to these registers, the level of the output waveform (TOUT) will be inverted. Setting these registers and the base timer x H width setting reload register (BTxPRLH) determines the widths of "L" level and "H" level for the output signal. The signal level width set to these registers depends on the setting of the OSEL bit of the timer control register (BTxTMCR) as follows:

- OSEL=0: "L" level width
- OSEL=1: "H" level width

The value set to registers is loaded to the 16-bit down counter when a 16-bit PPG timer activation trigger is detected or when the base timer x H width setting reload register (BTxPRLH) completed counting values and underflows.

4.4.3. H Width Setting Registers 0, 1 : BTxPRLH (Base Timer 0/1 Pulse Length of "H" register)

The bit configuration of H width setting registers 0, 1 (BTxPRLH) is shown below.

These registers with a buffer set the width of signal level output when the base timer x L width setting reload register (BTxPRL) completes counting values.

Notes:

- These registers must be accessed in 16-bit mode.
- Set these registers after selecting a base timer function to the PPG timer using the FMD2 to FMD0 bits of the timer control register (BTxTMCR).
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxPRLH : Address Base_addr + 0A_H (Access: Half-word)**

	bit15	bit14	---	bit2	bit1	bit0
	D[15:0]					
Initial value	0	0	---	0	0	0
Attribute	R/W	R/W	---	R/W	R/W	R/W

[bit15 to bit0] D[15:0] (Data) : Data bits

These registers with a buffer set the width of signal level output when the L width setting reload register (BTxPRL) completes counting values. When the 16-bit down counter completes counting down the value set to these registers, the signal level of the output waveform (TOUT) will be inverted.

Setting these registers and the base timer x L width setting reload register (BTxPRL) determines the widths of "L" level and "H" level for the output signal. The signal level width set to these registers depends on the setting of the OSEL bit of the base timer x timer control register (BTxTMCR) as follows:

- OSEL = 0: "H" level width
- OSEL = 1: "L" level width

These registers have a buffer and thus can be rewritten during counting. These registers transfer values at the following timing.

- Transfer to the buffer
- When a 16-bit PPG timer activation trigger is detected
- When the base timer x H width setting reload register (BTxPRLH) completes counting down values and underflows
- Transfer to the 16-bit down counter
- When counting down from the value of the base timer x L width setting reload register (BTxPRL) is completed.

For rewriting timing, see "■ Write Timing" in "5.6.3 Operation in Reload Mode".

4.5. 16/32-bit PWC Timer Register

This section explains registers for 16/32-bit PWC timer.

- 4.5.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 SStatus Control)
- 4.5.2. Data Buffer Registers 0, 1 : BTxDTBFB (Base Timer 0/1 DaTa BuFfer register)

4.5.1. Status Control Registers 0, 1 : BTxSTC (Base Timer 0/1 Status Control)

The bit configuration of status control registers 0, 1 (BTxSTC) is shown below.

These registers control interrupt requests.

Notes:

- Reserved bits must be set to "0".
- For the read-modify-write instruction to OVIR, "1" is read out.
- These registers must be accessed in 8-bit mode.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD=000).

■ **BTxSTC : Address Base_addr + 05_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ERR	EDIE	Reserved	OVIE	Reserved	EDIR	Reserved	OVIR
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W0	R/W	R0,W0	R/W	R0,W0	R,WX	R0,W0	R(RM1), W

[bit7] ERR (ERRor) : Error flag bit

This bit indicates that the next measurement is completed before the measurement result is read from the data buffer register (BTxDTBFB) in the continuous measurement mode and the measurement result has been overwritten by the new value. The old value is discarded. This bit is cleared to "0" when a value is read from the data buffer register (BTxDTBFB).

ERR	Description
0	The measurement result has not been overwritten.
1	The measurement result has been overwritten.

[bit6] EDIE (EnD Interrupt Enable) : Measurement completion interrupt request enable bit

This bit sets whether or not to generate a measurement completion interrupt request when the measurement of the 16/32-bit PWC timer is completed (EDIR = 1).

[bit4] OVIE (OVerflow Interrupt Enable) : Overflow interrupt request enable bit

This bit sets whether or not to generate an overflow interrupt request when the up counter overflows (OVIR = 1).

EDIE/OVIE	Description
0	Disabled
1	Enabled

[bit2] EDIR (EnD Interrupt Register) : Measurement completion interrupt request flag bit

This bit indicates that the measurement of the 16/32-bit PWC timer is completed. When this bit is "1" and the EDIE bit is set to "1", a measurement completion interrupt request is generated. This bit is cleared when the measurement result (BTxDTBFB) is read out.

[bit0] OVIR (OVERflow Interrupt Register) : Overflow interrupt request flag bit

This bit indicates that the up counter value has changed from "FFFF_H" to "0000_H" and an overflow occurred. When this bit is "1" and the OVIE bit is set to "1", an overflow interrupt request is generated. This bit is cleared when "0" is written.

EDIR/OVIR	Read	Write
0	Measurement completion/overflow has not been occurred.	(EDIR) No effect on the operation. (OVIR) This bit is cleared.
1	Measurement completion/overflow has been occurred.	No effect on the operation.

4.5.2. Data Buffer Registers 0, 1 : BTxDTBF (Base Timer 0/1 DaTa BUffer register)

The bit configuration of data buffer registers 0, 1 (BTxDTBF) is shown below.

These registers are used to read out the measurement value of the 16/32-bit PWC timer and the up counter value.

Notes:

- These registers must be accessed in 16-bit mode.
- These registers will also be initialized when reset mode is set (writing of BTxTMCR:FMD = 000).

■ **BTxDTBF : Address Base_addr + 0A_H (Access: Half-word)**



[bit15 to bit0] D[15:0] (Data) : Data bits

These registers are used to read out the measurement value of the 16/32-bit PWC timer and the up counter value. The value read from these registers is different in the single measurement mode and continuous measurement mode.

- Single measurement mode: The up counter value is read during counting and the measurement result is read after the measurement completion.
- Continuous measurement mode: The value measured previously is read both during counting and after the measurement completion. The up counter value cannot be read.

The following values are set to these registers when two channels of a 16-bit PWC timer are cascaded and it is used as the 32-bit PWC timer.

- Value of even-number channel data buffer register (BTxDTBF): Value of lower 16-bit
- Value of odd-number channel data buffer register (BTxDTBF): Value of upper 16-bit

In the 32-bit timer mode, read these registers value in the following order.

1. Even-channel data buffer register (BTxDTBF)
2. Odd-channel data buffer register (BTxDTBF)

5. Operation

This section explains the operation of the base timer.

- 5.1. Selection of Timer Function
- 5.2. I/O Allocation
- 5.3. 32-bit Mode Operation
- 5.4. 16/32-bit Reload Timer Operation
- 5.5. 16-bit PWM Timer Operation
- 5.6. 16-bit PPG Timer Operation
- 5.7. 16/32-bit PWC Timer Operation

5.1. Selection of Timer Function

This section explains selection of the timer function.

Select the timer function for BTxTMCR:FMD[2:0].

5.2. I/O Allocation

This section explains I/O allocation.

Set I/O of the base timer for the BTSEL01 register before using the timer. You can select one of the following seven:

- **I/O mode 0**

16-bit timer standard mode

The base timer operates separately for each channel in this mode.

- **I/O mode 1**

32-bit timer full mode

The even-number channel signals of the base timer are allocated to the external pin in this mode.

- **I/O mode 2**

External trigger sharing mode

The external activation trigger can be input to two channels of base timer at the same time in this mode. Using this mode allows simultaneous activation of two channels of base timer.

- **I/O mode 4**

Timer activation/stop mode

Activation/stop of the odd-number channel is controlled by the even-number channel in this mode. The odd-number channel is started with the rising edge(*) of the output signal from the even-number channel and stops with the falling edge(*).

- **I/O mode 5**

Simultaneous software activation mode

More than one channels are started by the software at the same time in this mode.

- **I/O mode 6**

Software activation timer activation/stop mode

Activation/stop of the odd-number channel is controlled by the even-number channel in this mode. The even-number channel is started by the software. The odd-number channel is started with the rising edge(*) of the output signal from the even-number channel and stops with the falling edge(*).

- **I/O mode 7**

Timer activation mode

Activation of the odd-number channel is controlled by the even-number channel in this mode. The odd-number channel is started with the rising edge(*) of the output signal from the even-number channel.

(*): Make a setting using the trigger input selection bit (BTxTMCR:EGS).

Figure 5-1 Wiring Diagram of Each I/O Mode (1)

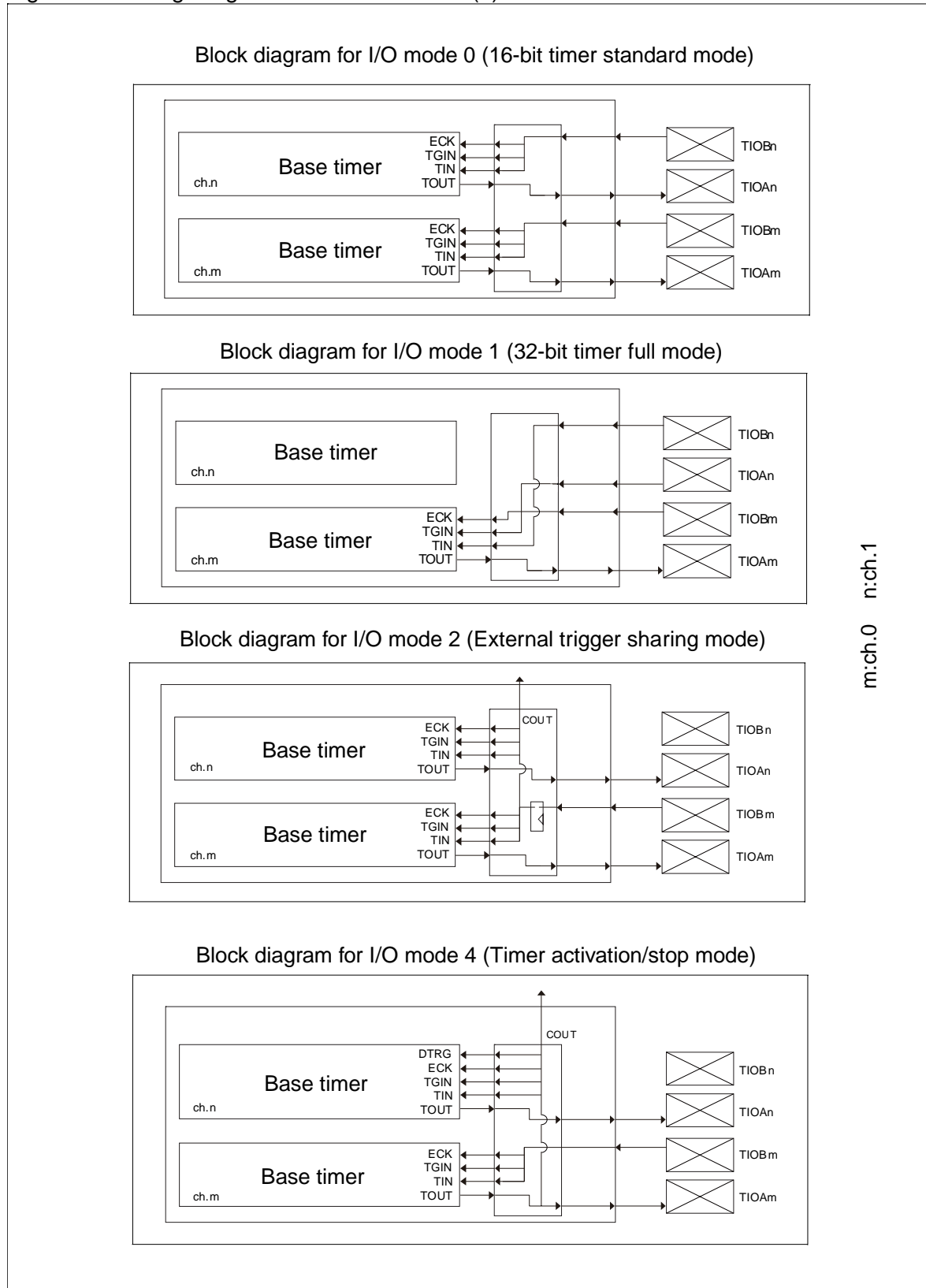
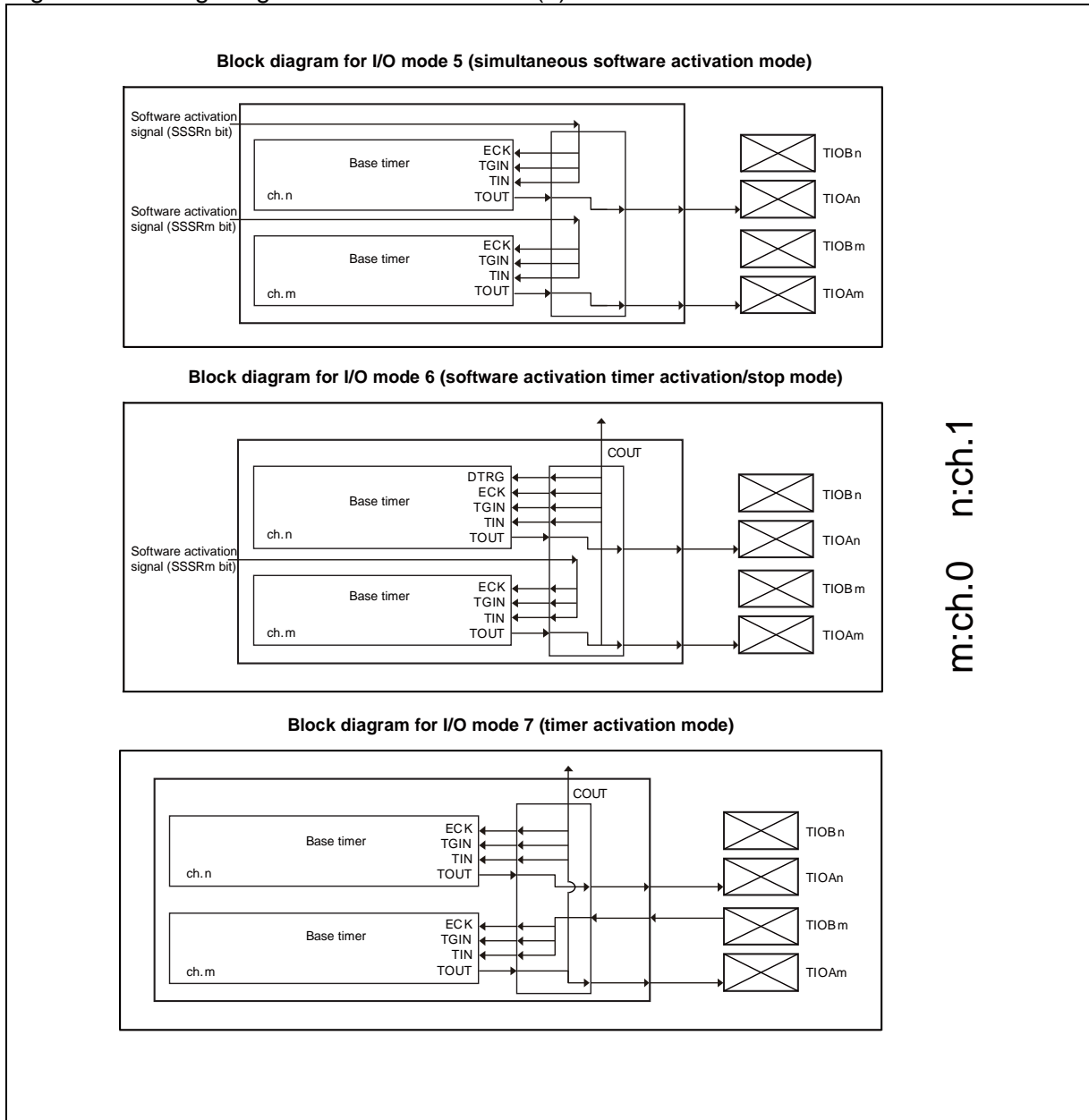


Figure 5-2 Wiring Diagram of Each I/O Mode (2)



5.3. 32-bit Mode Operation

This section explains the 32-bit mode operation.

The reload timer and PWC timer can be operated in the 32-bit mode using two channels. The basic function/operation in the 32-bit mode is shown below.

5.3.1. 32-bit Mode Function

This section explains the 32-bit mode function.

This function realizes the operation of the 32-bit data reload timer or 32-bit data PWC timer by combining two channels of base timer. The upper 16-bit timer counter value of the odd-number channel is also loaded when the lower 16-bit timer counter value of the even-number channel is read. Thus, the timer counter value in operation can also be read.

5.3.2. 32-bit Mode Setting

This section explains the 32-bit mode setting.

First, set "000" to the FMD bits of the BTxTMCR register of the even-number channel to reset to the reset mode, then select the reload timer or PWC timer and set the operation as in the 16-bit mode. While doing so, set to the 32-bit mode by writing "1" to the T32 bit of the BTxTMCR register. Leave the T32 bit of the odd-number channel "0". You do not have to set the reset mode. For the reload timer, set the upper 16-bit reload values of the 32-bit to the cycle setting register of the odd-number channel, then set the lower 16-bit reload values to the cycle setting register of the even-number channel.

The transition to the 32-bit mode is reflected immediately after the writing to the T32 bit. Thus, setting change for both channels must be done when the counting is stopped.

To transit from the 32-bit mode to the 16-bit mode, set "000" to the FMD bits of the BTxTMCR register of the even-number channel to reset to the reset mode for both the even-number and odd-number channels, and make a setting in the 16-bit mode for each channel.

5.3.3. 32-bit Mode Operation

This section explains 32-bit mode operation.

After setting the 32-bit mode when the reload timer or PWC timer is started with the control of the even-number channel, the timer/counter of the even-number channel operates with lower 16-bit and the timer/counter of the odd-number channel operates with upper 16-bit.

The 32-bit mode operation depends on the setting of the even-number channel. Thus, the setting of the odd-number channel (excepting the cycle setting register for the reload timer) is ignored. Timer activation, waveform output and interrupt signal also apply the setting of the even-number channel. (The odd-number channel is masked with the value fixed to L.)

For the configuration, see Figure 5-11 and Figure 5-28 .

5.4. 16/32-bit Reload Timer Operation

This section explains the 16/32-bit reload timer operation.

This section explains the operation performed when the base timer included in this series is used as the 16/32-bit reload timer. An example is also given to set various operation conditions.

Figure 5-3 Block Diagram (16-bit Reload Timer Operation)

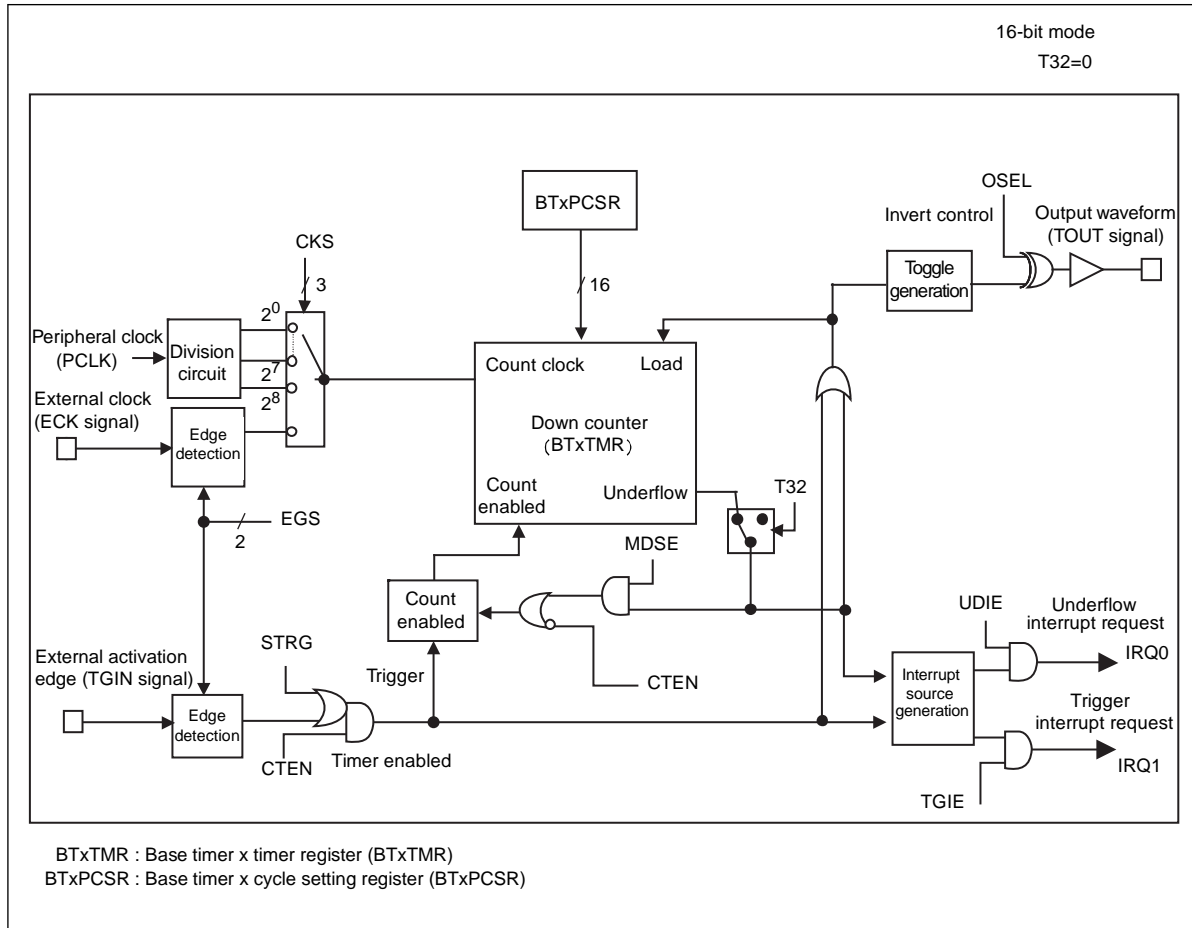
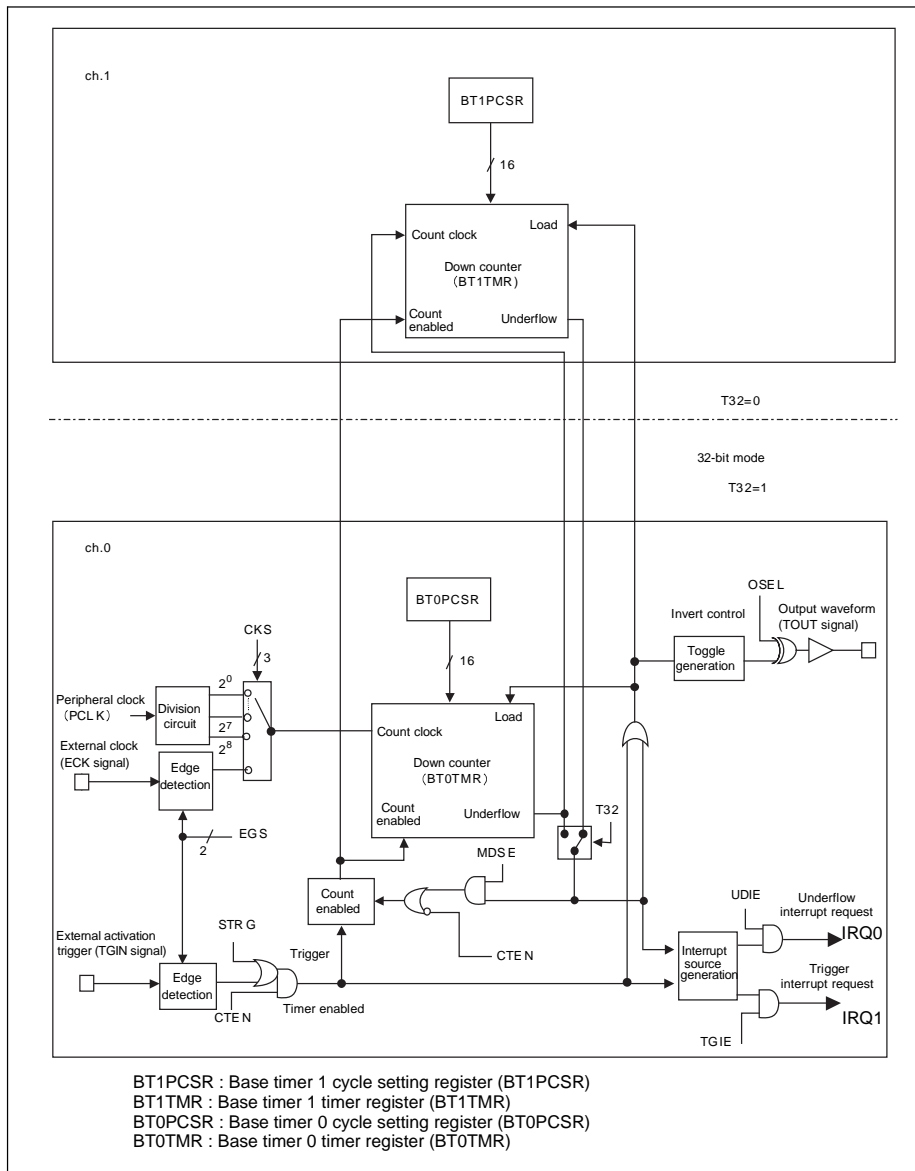


Figure 5-4 Block Diagram (32-bit Reload Timer Operation)



5.4.1. Overview

This section explains the overview of the 16/32-bit reload timer operation.

The 16/32-bit reload timer is a timer that decreases from the value set in the base timer x cycle setting register (BTxPCSR). This timer has a function of generating an underflow interrupt request when the down counter underflows.

The 16/32-bit reload timer has two modes: Timer mode and operation mode. The operation of the timer varies in accordance with combinations of these modes.

- Timer mode: One of the following two modes can be selected using the T32 bit of the base timer x timer control register (BTxTMCR).
 - 16-bit timer mode (T32 = 0): 16-bit reload timer can operate individually for each of the channels.
 - 32-bit timer mode (T32 = 1): 2 channels can be cascaded and used as a 32-bit reload timer.
- Operation mode: One of the following two modes can be selected using the MDSE bit of the base timer x timer control register (BTxTMCR).
 - Reload mode (MDSE = 0): In this mode, when the down counter underflows, the preset value (cycle) is reloaded to allow the timer to restart counting.
 - One-shot mode (MDSE = 1): Once the down counter underflows, the counter will no longer count.

5.4.2. Operation in Reload Mode

This section explains the operation in reload mode.

This section explains the operation in reload mode.

■ Overview

In this mode, the value set in the base timer x cycle setting register (BTxPCSR) is reloaded every time an underflow occurs to ensure that countdown is continued. To use this mode, set reload mode by resetting the MDSE bit of the base timer x timer control register (BTxTMCR) to "0" (MDSE=0).

■ Operation

● Activation

Activate the 16/32-bit reload timer with the following procedure:

1. Permit 16/32-bit reload timer operation by setting the CTEN bit of the base timer x timer control register (BTxTMCR) to "1" (CTEN=1).
The 16/32-bit reload timer begins to wait for an activation trigger.
2. Enter an activation trigger by one of the following methods:
 - Set the STRG bit of the base timer x timer control register (BTxTMCR) to "1" (software trigger).
 - Enter an effective edge (an edge set in the EGS1 and EGS0 bits) for an external activation trigger (TGIN signal).

Notes:

- The external activation trigger (TGIN signal) entry method varies depending on the I/O mode specified by the I/O selection register (BTSEL01). See "5.2 I/O Allocation".
 - To start counting as soon as the operation is permitted, set both CTEN and STRG bits of the base timer x timer control register (BTxTMCR) to "1".
-

Counting Operation

When an activation trigger is input, the value (cycle) set in the base timer x cycle setting register (BTxPCSR) is loaded to the down counter, which begins counting down, after one of the following lengths of time elapses:

- If a software trigger is input: 1T (T: Count clock cycle)
- If an external activation trigger (TGIN signal) is input: 2T to 3T (T: Count clock cycle)

Figure 5-5 and Figure 5-6 show the count start timing.

Figure 5-5 Count Start Timing (Software Trigger)

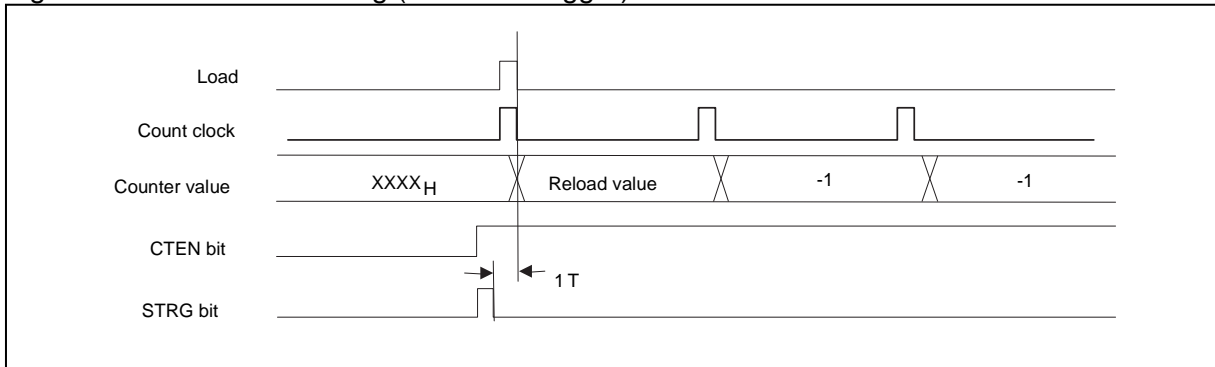
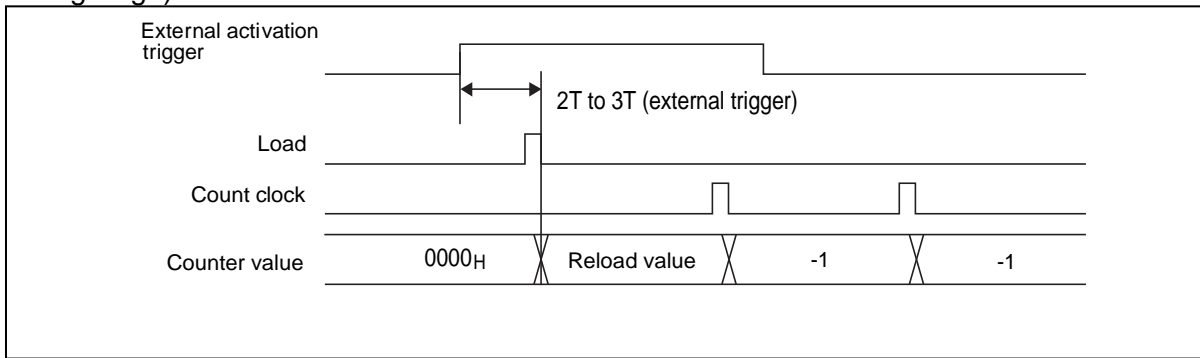


Figure 5-6 Count Start Timing (External Activation Trigger (TGIN Signal), Effective Edge = Rising Edge)

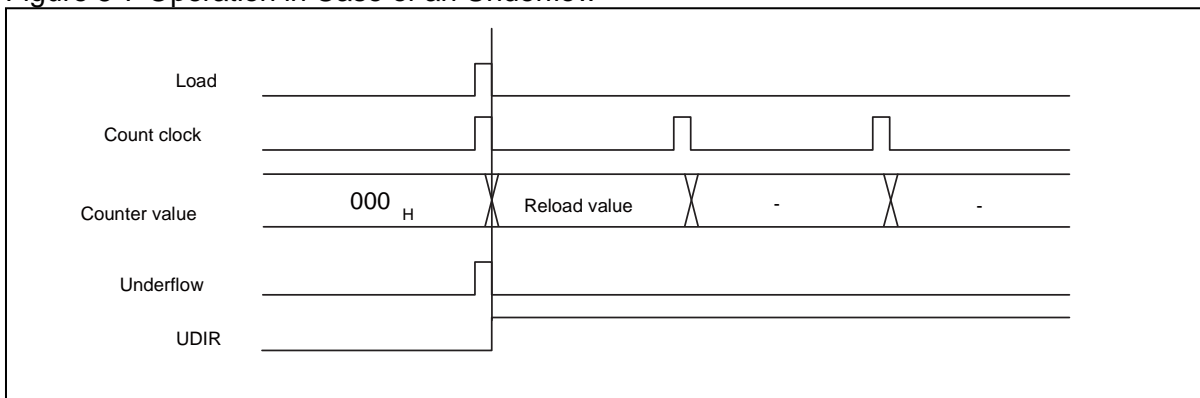


Note:

The external activation trigger (TGIN signal) entry method varies depending on the I/O mode specified by the I/O selection register (BTSEL01). See "5.2 I/O Allocation".

When the down counter underflows after attempting to count down further from the value of "0000_H", the value (cycle) set in the base timer x cycle setting register (BTxPCSR) is reloaded to the down counter, which continues to count down. If an underflow occurs, the UDIR bit of the base timer x status control register (BTxSTC) changes to "1". At this time, an underflow interrupt request occurs if the UDIE bit is set to "1". Figure 5-7 shows the operation in case of an underflow.

Figure 5-7 Operation in Case of an Underflow



■ **Output Waveform**

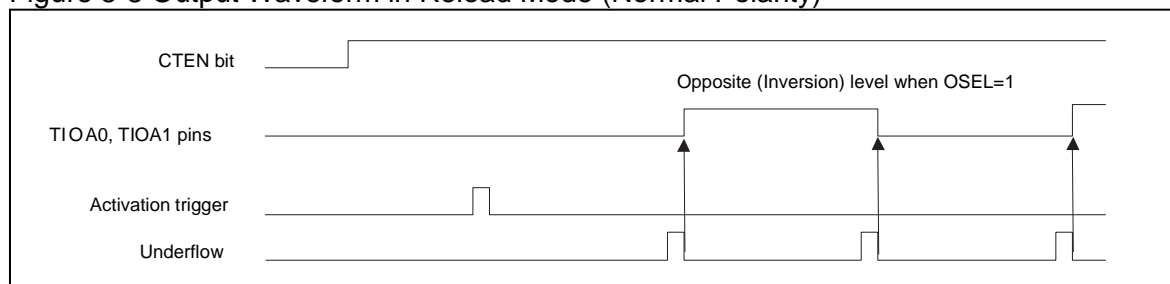
The waveform (TOUT signal) of the 16/32-bit reload timer can be output. The waveform (TOUT signal) to be output varies according to the setting of the OSEL bit of the base timer x timer control register (BTxTMCR).

Table 5-1 Correspondence between Output Polarities and Output Waveforms

Output polarity	Output waveform
Normal polarity (OSEL = 0)	"L" level pulse is output when counting starts. Thereafter, the output level is inverted every time an underflow occurs.
Inverted polarity (OSEL = 1)	"H" level pulse is output when counting starts. Thereafter, the output level is inverted every time an underflow occurs.

Figure 5-8 shows the output waveform in reload mode.

Figure 5-8 Output Waveform in Reload Mode (Normal Polarity)



5.4.3. Operation in One-Shot Mode

This section explains the operation in one-shot mode.

This section explains the operation in one-shot mode.

■ Overview

In this mode, the counter will no longer count down once an underflow occurs.

To use this mode, set one-shot mode by setting the MDSE bit of the base timer x timer control register (BTxTMCR) to "1"(MDSE=1).

■ Operation

● Activation

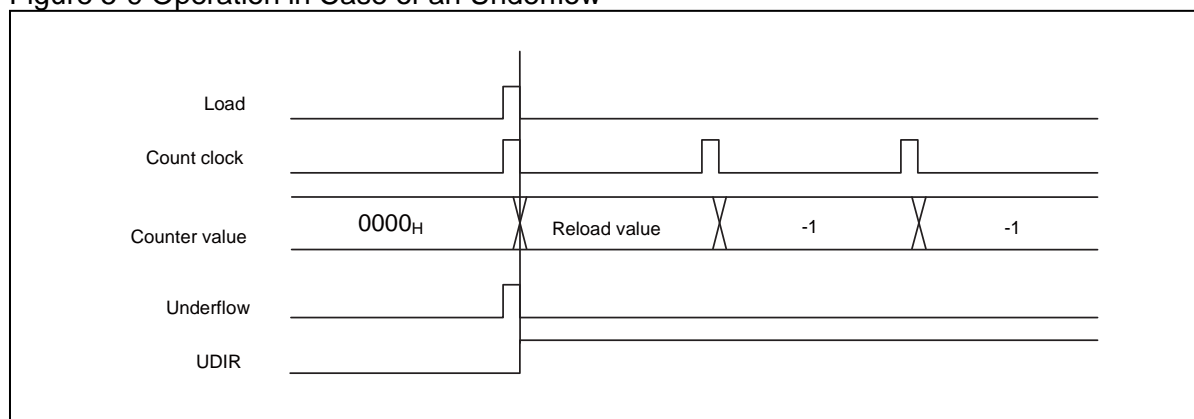
The same operation as in reload mode. See "■ Overview" in "5.4.2 Operation in Reload Mode".

● Counting Operation

The operation is the same as in reload mode until an underflow occurs. See "■ Overview". When the down counter underflows, the value (cycle) set in the base timer x cycle setting register (BTxPCSR) is reloaded to the down counter. However, the down counter stops counting. If an underflow occurs, the UDIR bit of the base timer x status control register (BTxSTC) changes to "1". At this time, an underflow interrupt request occurs if the UDIE bit of the base timer x status control register (BTxSTC) is set to "1".

Figure 5-9 shows the operation in case of an underflow.

Figure 5-9 Operation in Case of an Underflow



■ Output Waveform

The waveform (TOUT signal) of the 16/32-bit reload timer can be output. The waveform (TOUT signal) to be output varies according to the setting of the OSEL bit of the base timer x timer control register (BTxTMCR).

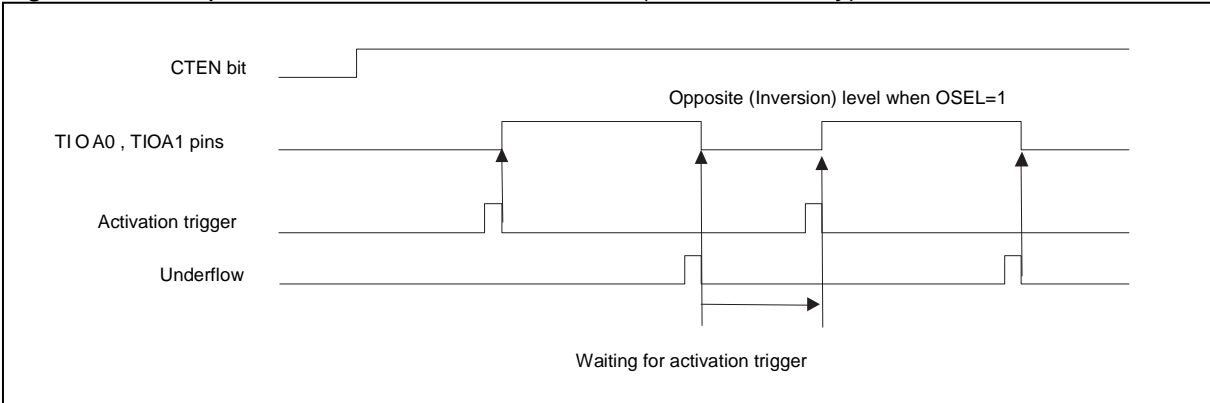
Table 5-2 shows the correspondence between output polarities and output waveforms.

Table 5-2 Correspondence between Output Polarities and Output Waveforms

Output polarity	Output waveform
Normal polarity (OSEL = 0)	When an activation trigger is input (counting in progress), "H" level pulse is output. "L" level pulse is output while the timer waits for an activation trigger.
Inverted polarity (OSEL = 1)	When an activation trigger is input (counting in progress), "L" level pulse is output. "H" level pulse is output while the timer waits for an activation trigger.

Figure 5-10 shows the output waveform in one-shot mode.

Figure 5-10 Output Waveform in One-shot Mode (Normal Polarity)



5.4.4. 32-bit Timer Mode Operation

This section explains the 32-bit timer mode operation.

This section explains the setting and operation for cascading 2 channels of a 16-bit reload timer and using them as a 32-bit reload timer.

■ Overview

Using the T32 bit of the base timer x timer control register (BTxTMCR), 2 channels of a 16-bit reload timer can be cascaded and used as a 32-bit reload timer. In this mode, the even-numbered channel corresponds to the lower 16-bit operation, and the odd-numbered channel corresponds to the upper 16-bit operation. Therefore, set the reload values in the order of the upper 16 bits (odd-number channels) → the lower 16 bits (even-number channels) and read the down counter values in the order of the lower 16 bits (even-number channels) → the upper 16 bits (odd-number channels).

■ Setting Procedure (Example)

To set 32-bit timer mode, set the T32 bit of the base timer x timer control register (BTxTMCR) of even-number channels to "1" and the T32 bit of the base timer x timer control register (BTxTMCR) of the odd-number channels to "0". When setting 32-bit timer mode, set the registers using the procedure shown below. Different register settings should be used between even-number and odd-number channels. The following shows an example of using a cascade connection.

1. Specify ch.0 to reset mode by setting FMD2 to FMD0 bits of base timer 0 timer control register (BT0TMCR). (FMD2 to FMD0 = 000)
2. Select 16/32-bit reload timer for ch.0 and ch.1 by setting the FMD2 to FMD0 bits of the base timer x timer control register (BT0TMCR, BT1TMCR) of ch.0 and ch.1. (FMD2 to FMD0 = 011)
At the same time, select 32-bit timer mode by setting the T32 bit of the base timer 0 timer control register (BT0TMCR).
3. Set a reload value in the upper 16 bits in the base timer 1 cycle setting register (BT1PCSR).
4. Set a reload value in the lower 16 bits in the base timer 0 cycle setting register (BT0PCSR).

Notes:

- Rewrite the T32 bit while the operation of both of the even-number and odd-number channels is stopped. Whether the counting operation is stopped can be checked by setting the CTEN bit of the base timer x timer control register (BTxTMCR) to "0"(CTEN=0).
- A reload value in the base timer x cycle setting register (BTxPCSR) must be set in the order of the odd-number → even-number channels.

■ Operation

In 32-bit timer mode, the counting operation is basically the same as in 16-bit timer mode.

However, the counting operation conforms to the settings of the even-number channels, ignoring the settings of the registers next to the odd-number channels.

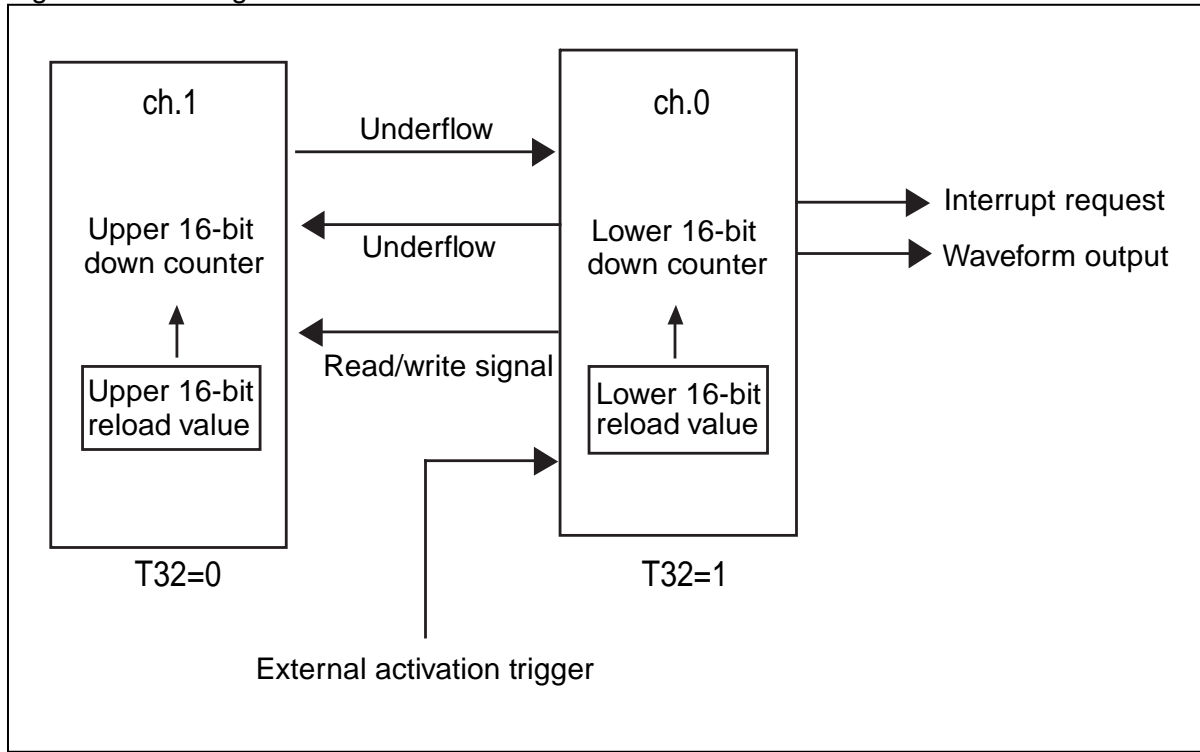
- Base timer x timer control register (BTxTMCR)
- Base timer x status control register (BTxSTC)

This section explains the counting in the 32-bit timer mode.

1. When the 32-bit reload timer activates, the values in the odd-number channel base timer x cycle setting register (BTxPCSR) and the even-number channel base timer x cycle setting register (BTxPCSR) (lower 16-bit) are loaded to the down counter.
2. The down counter starts counting as a 32-bit counter with the even-number channels serving as the lower 16-bit and the odd-number channels as the upper 16-bit.

3. When the down counter underflows, the UDIR bit of the base timer x timer control register (BTxTMCR) of the even-number channels changes to "1". The channel configuration in 32-bit timer mode is shown below.

Figure 5-11 Configuration in 32-bit Timer Mode



Notes:

- The value of the down counter can be checked by reading the base timer x timer register (BTxTMR). In the 32-bit timer mode, it must be read in the order of the lower 16-bit (even-numbered channel) → upper 16-bit (odd-number channel).
- In 32-bit timer mode, the operation of the 32-bit reload timer conforms to the settings of the even-number channels. Therefore, activation triggers and interrupt requests from even-number channels are valid. The output signal (TOUT) from an odd-number channel pin is fixed to "L" level.

5.4.5. Interrupts

This section explains interrupts of the base timer.

An interrupt request is generated in one of the following events:

- An activation trigger is detected. (trigger interrupt request)
- An underflow occurs (underflow interrupt request).

Table 5-3 Interrupt Occurrence Conditions

Interrupt request	Interrupt request flag	Permission of interrupt request	Interrupt request clear
Trigger interrupt request	BTxSTC:TGIR=1	BTxSTC:TGIE=1	Set the TGIR bit of BTxSTC to "0".
Underflow interrupt request	BTxSTC:UDIR=1	BTxSTC:UDIE=1	Set the UDIR bit of BTxSTC to "0".

Notes:

- Once the generation of an interrupt request is enabled while the interrupt request flag is "1", an interrupt request will be issued when the interrupt is enabled. To enable the generation of an interrupt request, perform one of the following operations:
 - Clear the current interrupt request before enabling the generation of an interrupt request.
 - Clear the current interrupt request when enabling the interrupt.
 - Either clear the current interrupt request after disabling the generation of an interrupt request or clear the current interrupt request within the interrupt processing routine.
- For interrupt vector numbers used when issuing an interrupt request, see "C. List of Interrupts Vector" in entitled "APPENDIX".
- Set the interrupt level corresponding to the interrupt vector number in one of the interrupt control registers (ICR00 to ICR47). For information on interrupt level setting, see the chapter entitled "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

5.4.6. Precautions for Using this Device

This section explains precautions for using this device.

Note the following when using the 16/32-bit reload timer:

■ Notes on Program Setting

- Change the following bits of the base timer x timer control register (BTxTMCR) after stopping the 16-bit down counter by resetting CTEN bit to "0"(CTEN=0).
 - CKS2 to CKS0 bits
 - EGS1 and EGS0 bits
 - T32 bit
 - FMD2 to FMD0 bits
 - MDSE bit
- All registers are initialized when the FMD2 to FMD0 bits of the timer control register (BTxTMCR) are set to "000" to select reset mode.
- Before the base timer function or T32 bit can be changed, the base timer must be reset once. Except when rewriting the status of FMD2 to FMD0 bits or T32 bit of the timer control register (BTxTMCR) after a reset, be sure to set the FMD2 to FMD0 bits to "000" to select the reset mode. Then, rewrite the status of these bits.

■ Notes on Operations

- If the count timing of the down counter and the load timing occur at the same time, the load operation is given precedence.
- If a 16/32-bit reload timer activation trigger is detected when counting ends in one-shot mode, the value (cycle) set in the base timer x cycle setting register (BTxPCSR) is loaded to the 16-bit down counter, which begins counting.
- A different signal (external clock, external activation trigger, wave form) I/O operation can be selected using the base timer I/O selection function.

■ Notes on Interrupts

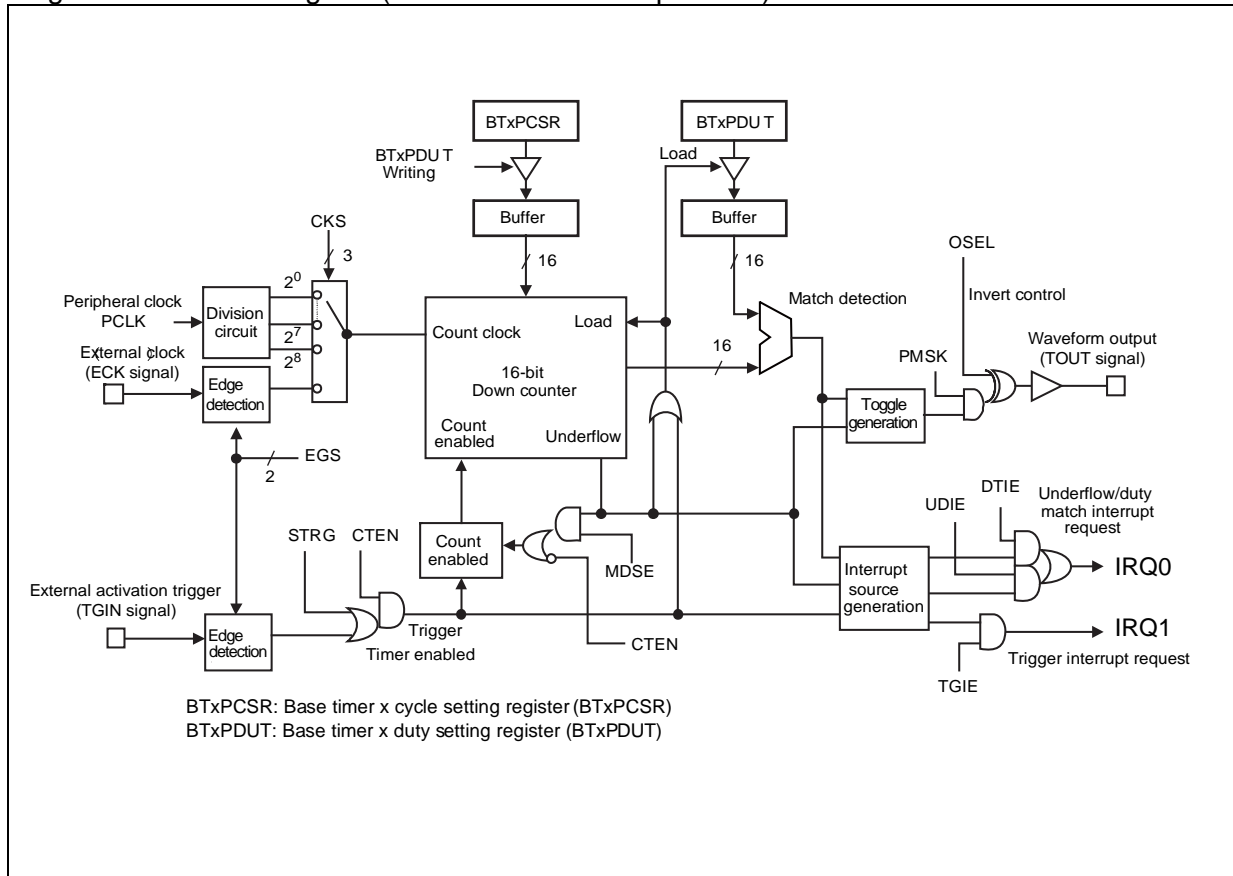
- If an instruction to clear the interrupt request flag and an instruction to change the interrupt request flag to "1" occur at the same time, the flag clear instruction is ignored. The interrupt request flag is held to "1".

5.5. 16-bit PWM Timer Operation

This section explains the 16-bit PWM timer operation.

This section explains the operation performed when the base timer included in this series is used as the 16-bit PWM timer. An example is also given to set various operation conditions.

Figure 5-12 Block Diagram (16-bit PWM Timer Operation)



5.5.1. Overview

This section explains the overview of the 16-bit PWM timer operation.

The 16-bit PWM timer sets the cycle in the cycle setting register (BTxPCSR) and the duty in the duty setting register (BTxPDUT). A desired waveform (TOUT signal) can be output by setting values in these registers. The 16-bit PWM timer starts decreasing from the value set in the base timer x cycle setting register (BTxPCSR). When the value of the down counter matches the value of the duty setting register (BTxPDUT), the output signal (TOUT) level is inverted. When the down counter underflows, the output level is inverted again. This method enables output of a desired waveform (TOUT signal) with a cycle and duty.

One of two 16-bit PWM timer operation modes can be selected using the MDSE bit of the timer control register (BTxTMCR) as follows:

- Reload mode (MDSE = 0): In this mode, when the 16-bit down counter underflows, the preset cycle is reloaded to allow the timer to restart counting.
- One-shot mode (MDSE = 1): Once the 16-bit down counter underflows, the counter will no longer count.

5.5.2. Operation in Reload Mode

This section explains the operation in reload mode.

This section explains the operation in reload mode.

■ Overview

In this mode, the value set in the base timer x cycle setting register (BTxPCSR) is reloaded every time an underflow occurs to ensure that countdown is continued. To use this mode, set reload mode by resetting the MDSE bit of the base timer x timer control register (BTxTMCR) to "0" (MDSE=0).

■ Operation

● Activation

Activate the 16-bit PWM timer with the following procedure:

1. Permit the 16-bit PWM timer operation by setting the CTEN bit of the base timer x timer control register (BTxTMCR) to "1" (CTEN=1).
The 16-bit PWM timer begins to wait for an activation trigger.
2. Enter an activation trigger by one of the following methods:
 - Set the STRG bit of the base timer x timer control register (BTxTMCR) to "1" (software trigger).
 - Enter an effective edge (an edge set in the EGS1 and EGS0 bits) for an external activation trigger (TGIN signal).

The 16-bit down counter starts decreasing from the value set in the base timer x cycle setting register (BTxPCSR).

Notes:

- The external activation trigger (TGIN signal) entry method varies depending on the I/O mode specified by the I/O selection register (BTSEL01).
 - After a 16-bit PWM timer activation trigger is detected, the following time is required before the value set in the base timer x cycle setting register (BTxPCSR) can be loaded to the 16-bit down counter:
 - If a software trigger is input: 1T (T: Count clock cycle)
 - If an external event trigger is used: 2T to 3T (T: Count clock cycle)
-

● Counting Operation

When an activation trigger is input, the 16-bit down counter, in synchronization with the count clock, starts decreasing from the value set in the cycle setting register (BTxPCSR).

When the value of the 16-bit down counter matches the value of the duty setting register (BTxPDUT), the operation is performed as follows:

- The DTIR bit of the status control register (BTxSTC) changes to "1".
- The level of the output signal (TOUT) is inverted.
- Countdown is continued. Later, when the 16-bit down counter underflows, the operation is performed as follows:
 - The UDIR bit of the status control register (BTxSTC) changes to "1" and the level of the output signal (TOUT) is inverted.
 - The value of the cycle setting register (BTxPCSR) is reloaded to continue countdown.

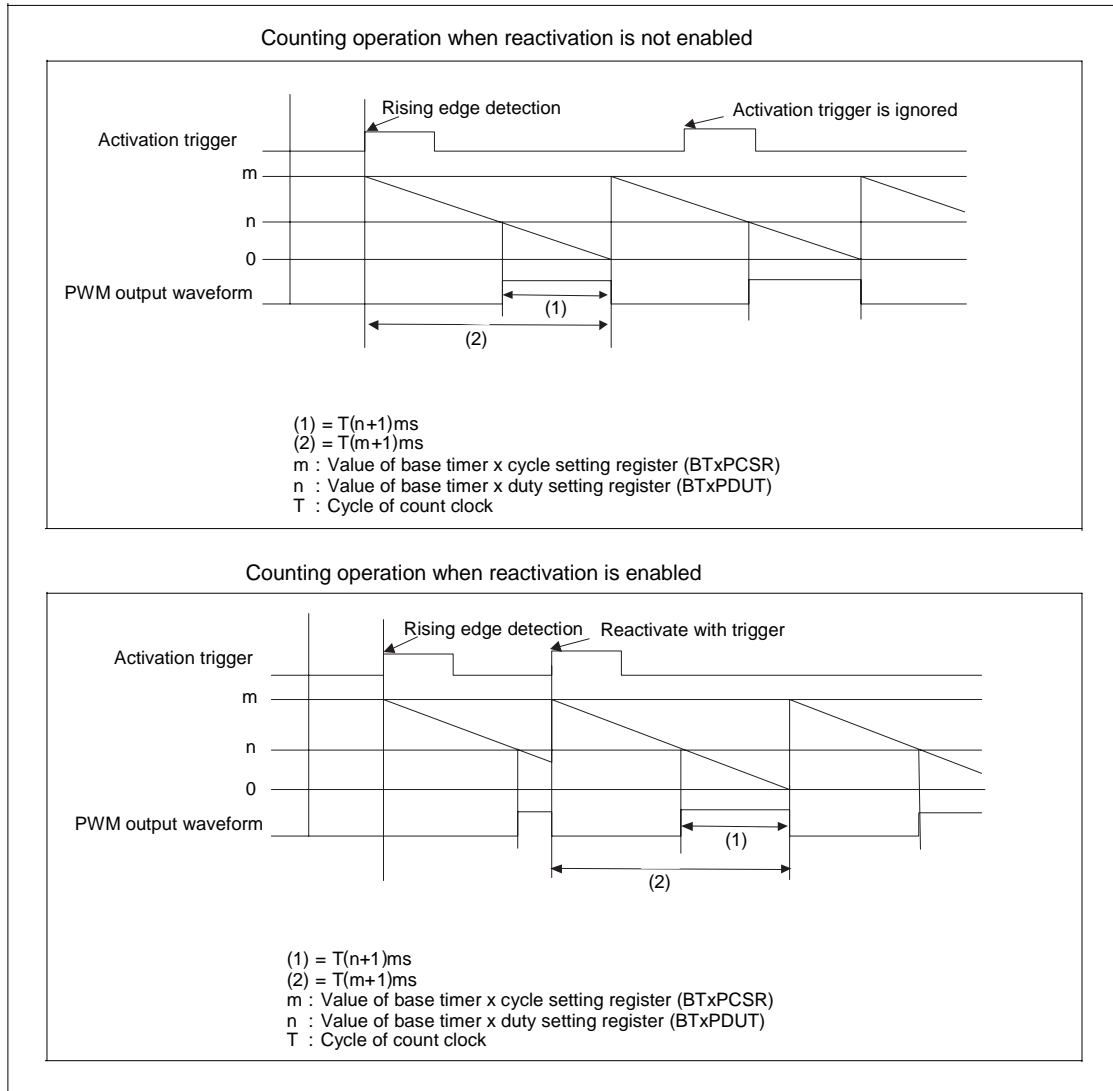
Every time an underflow occurs, the value of the cycle setting register (BTxPCSR) is reloaded to continue counting. Operation to be performed when an activation trigger is input during counting depends on whether

reactivation is permitted based on the RTGEN bit of the timer control register (BTxTMCR).

- If reactivation is not permitted (RTGEN = 0): Any activation trigger is ignored when it is entered during counting.
- If reactivation is permitted (RTGEN = 1): The TGIR bit of the base timer x status control register (BTxSTC) changes to "1". In addition, the value set in the base timer x cycle setting register (BTxPCSR) is reloaded to the 16-bit down counter, which begins counting.

These operations are shown below.

Figure 5-13 Counting Operation



Note:

If the count timing of the 16-bit down counter and the load timing occur at the same time, the load operation is given precedence.

■ **Output Waveform**

The waveform (TOUT signal) of the 16-bit PWM timer can be output. The waveform (TOUT signal) to be output varies according to the setting of the OSEL bit of the base timer x timer control register (BTxTMCR).

● **Normal polarity (OSEL = 0)**

- When the 16-bit PWM timer is activated: "L" level
- When a duty match occurs: "H" level
- When an underflow occurs: "L" level

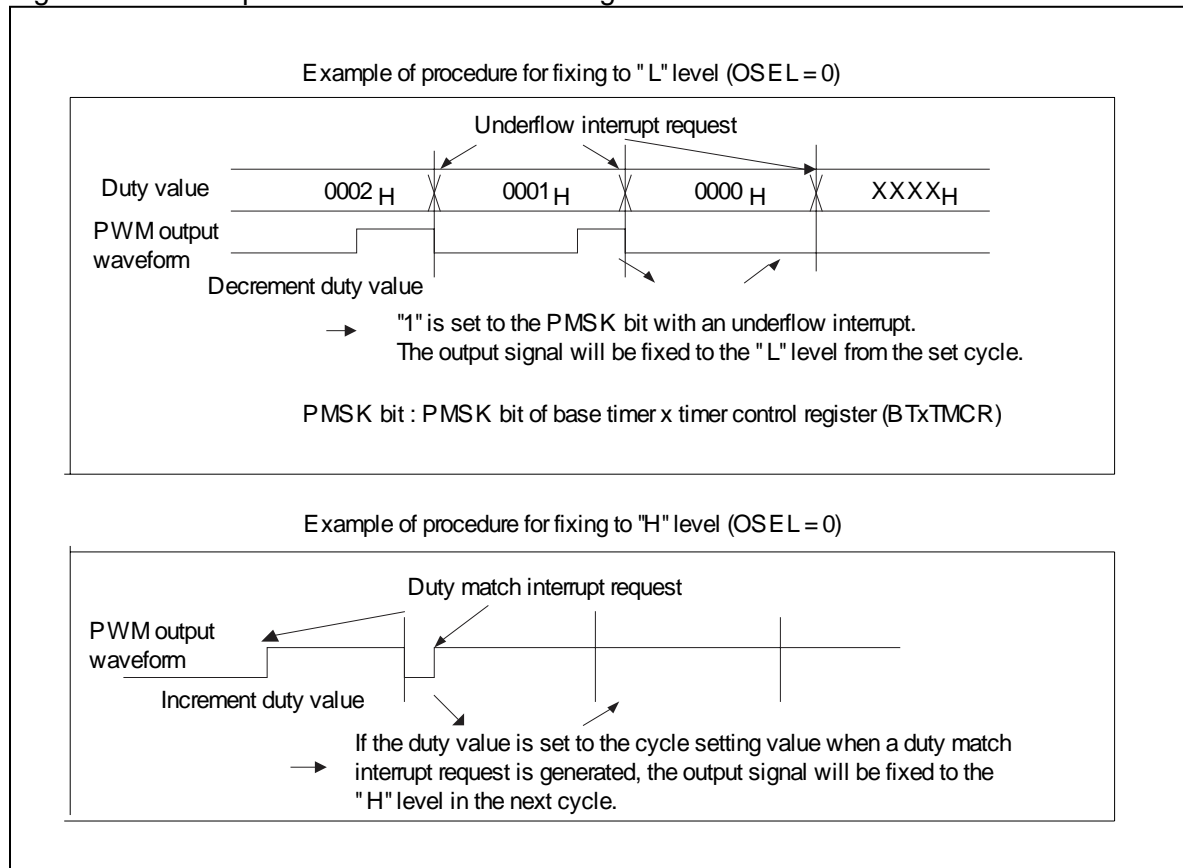
● **Inverted polarity (OSEL = 1)**

- When the 16-bit PWM timer is activated: "H" level
- When a duty match occurs: "L" level
- When an underflow occurs: "H" level

The output (TOUT signal) can be fixed at the "L" or "H" level.

The output level varies depending on the setting of the OSEL bit of the base timer x timer control register (BTxTMCR). Examples of procedures are shown below.

Figure 5-14 Examples of Procedures for Fixing to "L" and "H" Levels



Note:

- The output method and output destination of the waveform (TOUT signal) from the 16-bit PWM timer depend on the following settings:
 - Base timer I/O mode
 - TIOA0, TIOA1 pin functions

■ **Interrupt Generation Timing**

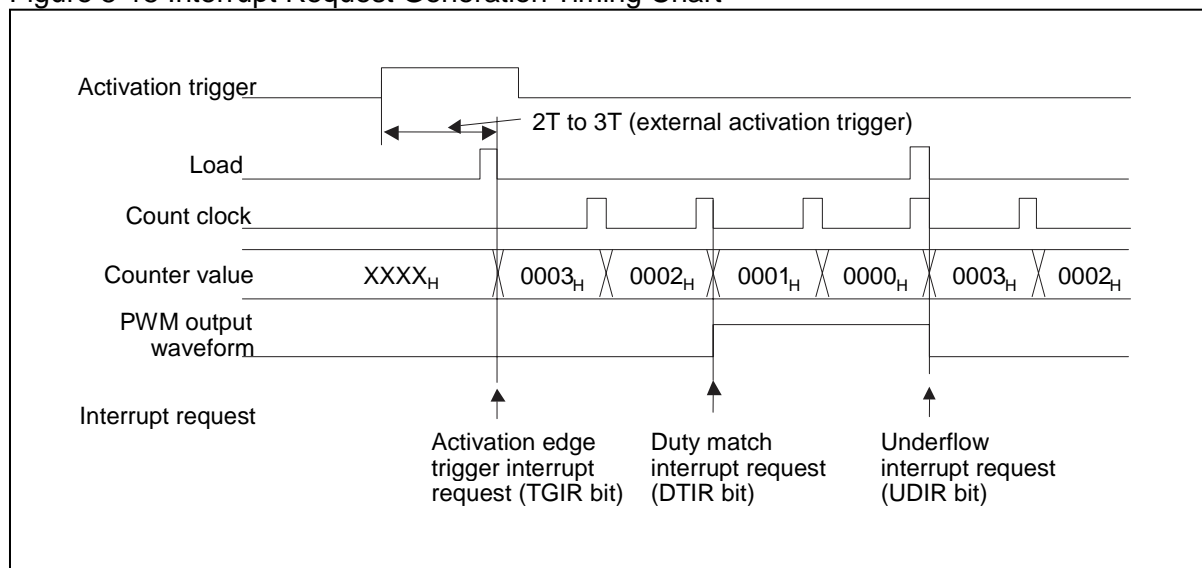
The 16-bit PPG timer can generate an interrupt request in one of the following events:

- An activation trigger is detected.
- The value of the 16-bit down counter matches the value of the base timer x duty setting register (BTxPDUT)
- When an underflow occurs:

An example of interrupt request generation timing using the following settings is shown below.

- Value of the cycle setting register (BTxPCSR) = 0003_H
- Value of the duty setting register (BTxPDUT) = 0001_H

Figure 5-15 Interrupt Request Generation Timing Chart



5.5.3. Operation in One-Shot Mode

This section explains the operation in one-shot mode.

This section explains the operation in one-shot mode.

■ Counting Operation

In this mode, counting stops if an underflow occurs when the value of the 16-bit down counter changes from the value set in the cycle setting register (BTxPCSR) to "FFFF_H".

To use this mode, set one-shot mode by setting the MDSE bit of the timer control register (BTxTMCR) to "1"(MDSE=1).

● Activation

It is the same operation as in reload mode. See "■ Operation" in the section entitled "5.5.2 Operation in Reload Mode".

● Counting Operation

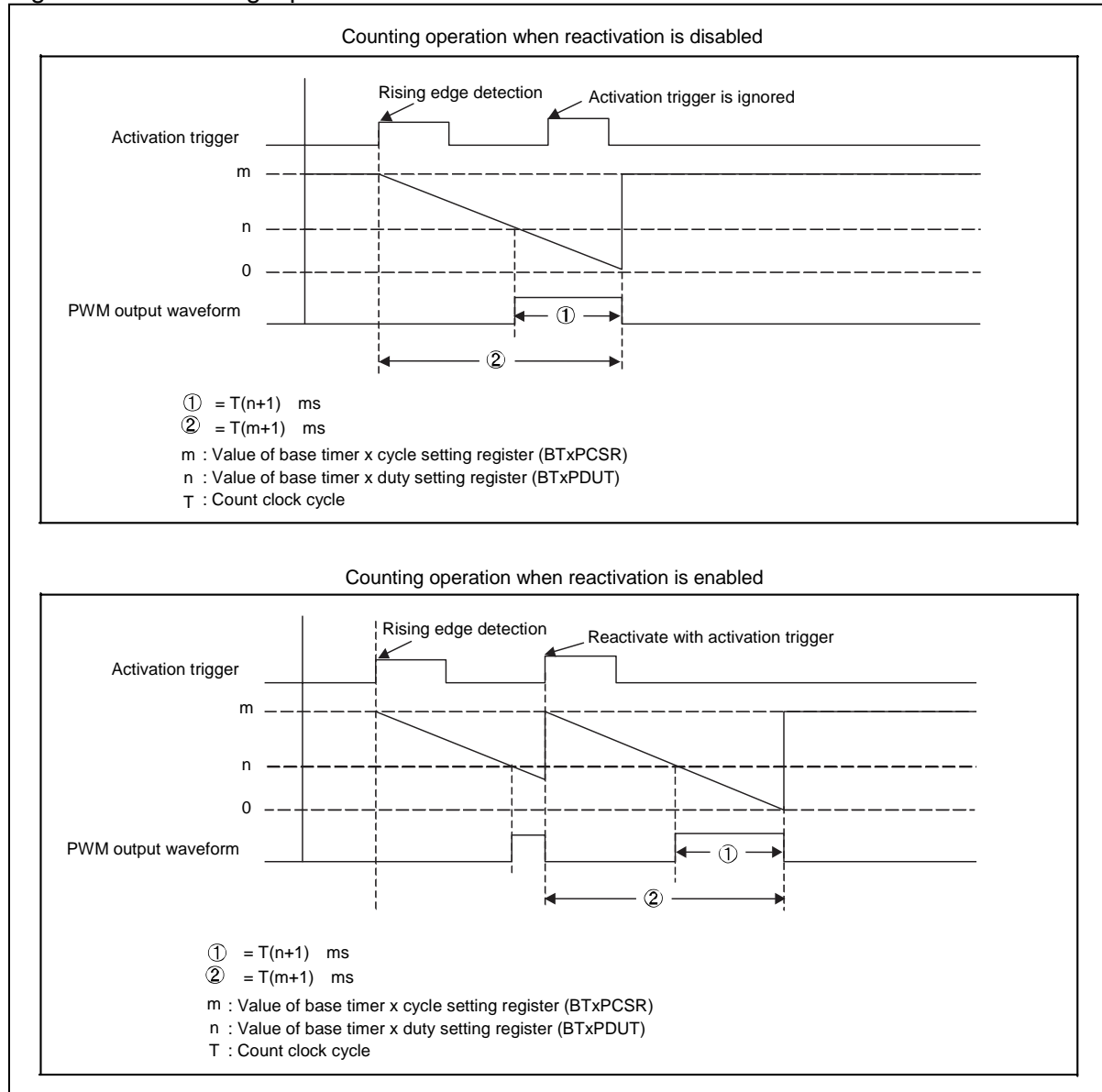
When an activation trigger is input, the 16-bit down counter, in synchronization with the count clock, starts decreasing from the value set in the cycle setting register (BTxPCSR). When the value of the 16-bit down counter matches the value of the duty setting register (BTxPDUT), the operation is performed as follows:

- The DTIR bit of the base timer x status control register (BTxSTC) changes to "1".
- The level of the output signal (TOUT signal) is inverted.
- Countdown is continued. Later, when the 16-bit down counter underflows, the operation is performed as follows:
 - The UDIR bit of the base timer x status control register (BTxSTC) changes to "1".
 - The level of the output signal (TOUT signal) is inverted.
 - Counting stops (The 16-bit down counter stops at the value "FFFF_H").

Operation to be performed when an activation trigger is input during counting depends on whether reactivation is permitted based on the RTGEN bit of the timer control register (BTxTMCR).

- If reactivation is not permitted (RTGEN = 0): Any activation trigger is ignored when it is entered during counting.
- If reactivation is permitted (RTGEN = 1): The TGIR bit of the base timer x status control register (BTxSTC) changes to "1". In addition, the value set in the base timer x cycle setting register (BTxPCSR) is reloaded to the 16-bit down counter, which begins counting.

Figure 5-16 Counting Operation



Note:

If a 16-bit PWM timer activation trigger is detected when counting ends, the value set in the cycle setting register (BTxPCSR) is loaded to the 16-bit down counter, which begins counting.

■ Output Waveform

It is the same operation as in reload mode. See "■ Output Waveform" in "5.5.2 Operation in Reload Mode".

■ Interrupt Generation Timing

It is the same operation as in reload mode. See "■ Interrupt Generation Timing" in "5.5.2 Operation in Reload Mode".

5.5.4. Interrupt

This section explains interrupts.

An interrupt request is generated in one of the following events:

- An activation trigger is detected. (trigger interrupt request)
- The value of the 16-bit down counter matches the value of (the base timer x duty setting register (BTxPDUT)) (duty match interrupt request).
- An underflow occurs (underflow interrupt request).

Table 5-4 Conditions for Interrupt Generation

Interrupt request	Interrupt request flag	Permission of interrupt request	Interrupt request clear
Trigger interrupt request	BTxSTC:TGIR = 1	BTxSTC:TGIE = 1	Set the TGIR bit of BTxSTC to "0".
Duty match interrupt request	BTxSTC:DTIR=1	BTxSTC:DTIE=1	Set the DTIR bit of BTxSTC to "0".
Underflow interrupt request	BTxSTC:UDIR = 1	BTxSTC:UDIE = 1	Set the UDIR bit of BTxSTC to "0".

Notes:

- Once the generation of an interrupt request is enabled while the interrupt request flag is "1", an interrupt request will be issued when the interrupt is enabled. To enable the generation of an interrupt request, perform one of the following operations:
 - Clear the current interrupt request before enabling the generation of an interrupt request.
 - Clear the current interrupt request when enabling the interrupt.
 - Either clear the current interrupt request after disabling the generation of an interrupt request or clear the current interrupt request within the interrupt processing routine.
- For interrupt vector numbers used when issuing an interrupt request, see "C. List of Interrupts Vector" in entitled "APPENDIX".
- Set the interrupt level corresponding to the interrupt vector number in one of the interrupt control registers (ICR00 to ICR47). For information on interrupt level setting, see the chapter entitled "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

5.5.5. Precautions for Using this Device

This section explains precautions for using this device.

Note the following when using the 16-bit PWM timer:

■ Notes on Program Setting

- Change the following bits of the timer control register (BTxTMCR) only after stopping the 16-bit down counter by resetting the CTEN bit to "0"(CTEN=0).
 - CKS2 to CKS0 bits
 - EGS1 and EGS0 bits
 - FMD2 to FMD0 bits
 - MDSE bit
- All registers are initialized when the FMD2 to FMD0 bits of the base timer x timer control register (BTxTMCR) are set to "000" to select reset mode.
- Before the base timer function can be changed, the base timer must be reset once. Except when rewriting the FMD2 to FMD0 bits of the base timer x timer control register (BTxTMCR) after reset, be sure to clear FMD2 to FMD0 bits to "000" to select the reset mode, and then select a base timer function using the FMD2 to FMD0 bits again.
- To set 16-bit PWM timer cycles or duties, proceed as follows:
 1. Select the 16-bit PWM timer as the base timer function by setting the FMD2 to FMD0 bits of the base timer x timer control register (BTxTMCR) to "001"(FMD2 to FMD0=001).
 2. Set the cycle in the base timer x cycle setting register (BTxPCSR).
 3. Set the duty in the base timer x duty setting register (BTxPDUT).

■ Notes on Operation

- If the count timing of the 16-bit down counter and the load timing occur at the same time, the load operation is given precedence.
- When a 16-bit PWM timer reactivation trigger is detected when counting ends in one-shot mode, the value in the base timer x cycle setting register (BTxPCSR) is loaded to the 16-bit down counter, which then starts counting.
- A different signal (external clock, external activation trigger, wave form) I/O operation can be selected using the base timer I/O selection function.

■ Notes on Interrupts

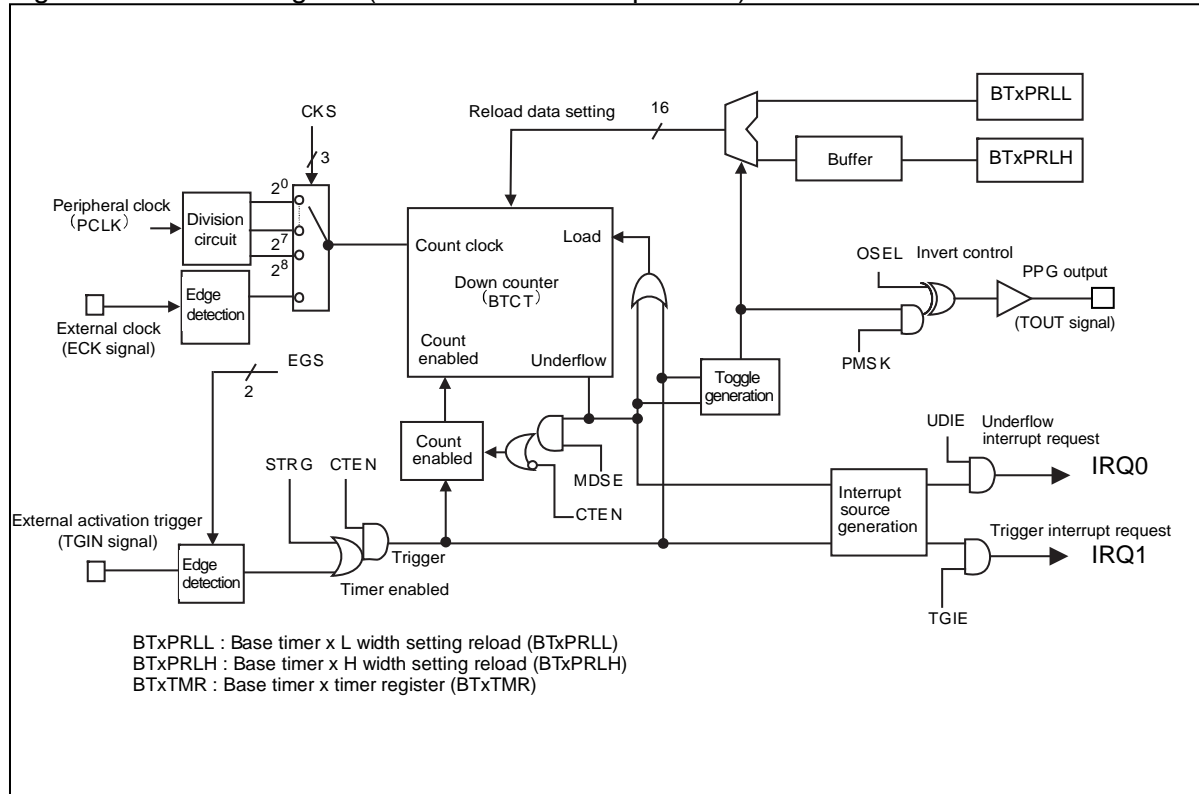
If an instruction to clear the interrupt request flag and an instruction to change the interrupt request flag to "1" occur at the same time, the flag clear instruction is ignored. The interrupt request flag is held to "1".

5.6. 16-bit PPG Timer Operation

This section explains the 16-bit PPG timer operation.

This section explains the operation performed when the base timer included in this series is used as the 16-bit PPG timer. Examples of procedures for setting various operating conditions are also provided.

Figure 5-17 Block Diagram (16-bit PPG Timer Operation)



5.6.1. Overview

This section explains the overview of the 16-bit PPG timer operation.

The 16-bit PPG timer, once activated, decreases from the value initially specified by the base timer x L width setting reload register (BTxPRLH). When counting down from the value set in the L width setting reload register (BTxPRLH) is completed, the timer begins counting down from the value set in the H width setting reload register (BTxPRLH).

When counting down from the value set in each register is completed, the output signal (TOUT) inverts its level. Therefore, by configuring the L width setting reload register (BTxPRLH) and H width setting reload register (BTxPRLH), you can arbitrarily set the widths of the "L" and "H" levels.

One of two 16-bit PPG timer operation modes can be selected using the MDSE bit of the timer control register (BTxTMCR) as follows:

- Reload mode (MDSE = 0): A sequence of "L"-level and "H"-level signals (consecutive pulses) is output.
- One-shot mode (MDSE = 1): A string of one "L"-level signal and one "H"-level signal (single pulses) is output.

5.6.2. Pulse Width Calculation Method

This section explains the pulse width calculation method.

When the 16-bit PPG timer has counted down by the value set in the L width setting reload register (BTxPRL) or base timer x H width setting reload register (BTxPRLH) plus 1, the output signal (TOUT) inverts its level. Therefore, the pulse width of the signal to be output is obtained by the following formula:

Example: If the output polarity is normal:

"L" level pulse width = $T \times (L + 1)$

"H" level pulse width = $T \times (H + 1)$

T: Count clock cycle

L: Value set in the base timer x L width setting reload register (BTxPRL)

H: Value set in the base timer x H width setting reload register (BTxPRLH)

This means that when the L width setting reload register (BTxPRL) and H width setting reload register (BTxPRLH) are set to "0000_H", the pulse width will be equal to one cycle of the count clock. When they are set to "FFFF_H", the pulse width will be equal to 65536 cycles of the count clock.

5.6.3. Operation in Reload Mode

This section explains the operation in reload mode.

This section explains the operation in reload mode.

■ Overview

In this mode, the values set in the base timer x L width setting reload register (BTxPRL) and base timer x H width setting reload register (BTxPRLH) are alternately reloaded to the down counter to ensure that the down counter continues to count down. A desired pulse width can be output continuously by rewriting the base timer x L width setting reload register (BTxPRL) and base timer x H width setting reload register (BTxPRLH) each time an underflow interrupt request is issued.

To use this mode, set reload mode by resetting the MDSE bit of the base timer x timer control register (BTxTMCR) to "0" (MDSE=0).

■ Operation

● Activation

Activate the 16-bit PPG timer with the following procedure:

1. Permit the 16-bit PPG timer operation by setting the CTEN bit of the timer control register (BTxTMCR) to "1" (CTEN=1). The 16-bit PPG timer begins to wait for an activation trigger.
2. Enter an activation trigger by one of the following methods:
Set the STRG bit of the base timer x timer control register (BTxTMCR) to "1" (software trigger).
Enter an effective edge (an edge set in the EGS1 and EGS0 bits) for an external activation trigger (TGIN signal).

Notes:

- The external activation trigger (TGIN signal) entry method varies depending on the I/O mode specified by the I/O selection register (BTSEL01).
- After a 16-bit PPG timer activation trigger is detected, the following time is required before the value (cycle) set in the L width setting reload register (BTxPRL) can be loaded to the 16-bit down counter:
 - If a software trigger is input: 1T (T: Count clock cycle)
 - If an external event trigger is used: 2T to 3T (T: Count clock cycle)

● Counting Operation

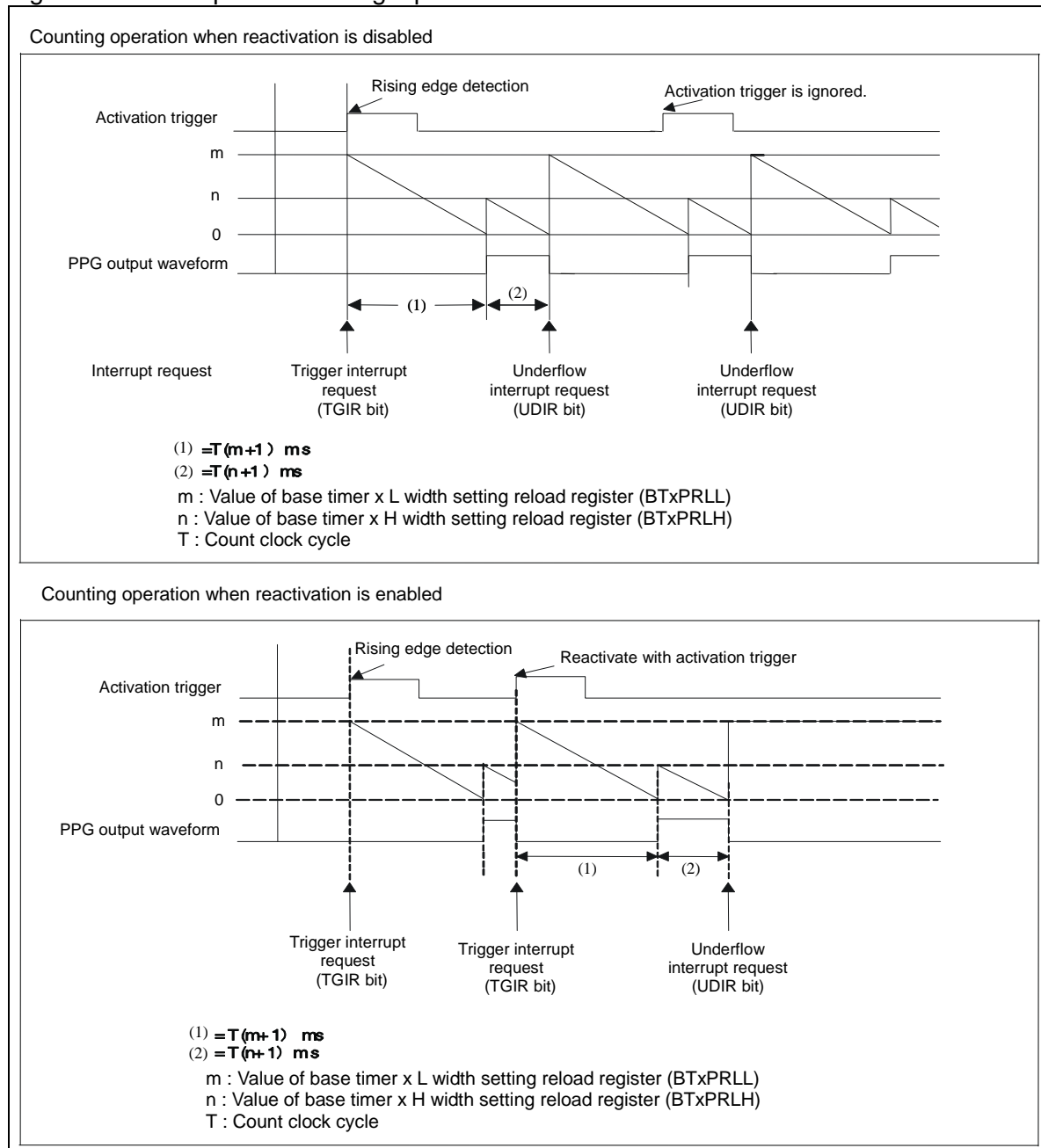
Counting operation initiated by the entry of an activation trigger is explained below, using an example where the OSEL bit of the timer control register (BTxTMCR) is set for normal polarity (OSEL = 0).

1. The value set in the L width setting reload register (BTxPRL) is transferred to the 16-bit down counter and the value set in the base timer x H width setting reload register (BTxPRLH) is transferred to the buffer. The 16-bit down counter begins to count down from the value of the L width setting reload register (BTxPRL). The output signal (TOUT) is at the "L" level.
2. The 16-bit down counter completes counting down from the value of L width setting reload register (BTxPRL).
3. The buffered value of H width setting reload register (BTxPRLH) is reloaded to the 16-bit down counter, which continues counting down. The output signal (TOUT) is at the "H" level.
4. The 16-bit down counter completes counting down from the value of H width setting reload register (BTxPRLH), thus causing an underflow.
5. The value of L width setting reload register (BTxPRL) is reloaded to the 16-bit down counter, which continues count down. The output signal (TOUT) is at the "L" level. In addition, the value of the H width setting reload register (BTxPRLH) is transferred to the buffer.
6. Steps 2 to 5 are repeated to continue counting.

Operation that is performed if reactivation is permitted or not during counting depends on whether reactivation is permitted based on the RTGEN bit of the timer control register (BTxTMCR).

- If reactivation is not permitted (RTGEN = 0): Any activation trigger is ignored when it is entered during counting.
- If reactivation is permitted (RTGEN = 1): The TGIR bit of the base timer x status control register (BTxSTC) changes to "1". In addition, the value of L width setting reload register (BTxPRL) is reloaded to the 16-bit down counter, which starts counting.

Figure 5-18 Example of Counting Operation in Reload Mode



Notes:

- The output method and output destination of the output signal (TOUT) from the 16-bit PPG timer depend on the following settings:
 - Base timer I/O mode
 - TIOA0, TIOA1 pin functions
 - If the count timing of the 16-bit down counter and the load timing occur at the same time, the load operation is given precedence.
-

■ **Write Timing**

The values of the base timer x L width setting reload register (BTxPRLl) and base timer x H width setting reload register (BTxPRLH) are reloaded at the following timing:

The value set in the base timer x L width setting reload register (BTxPRLl)

It is loaded to the 16-bit down counter in one of the following events:

- An activation trigger is detected.
- An underflow occurs after counting down from the value of the base timer x H width setting reload register (BTxPRLH) is completed.

The value set in the base timer x H width setting reload register (BTxPRLH)

It is transferred to the buffer in one of the following events:

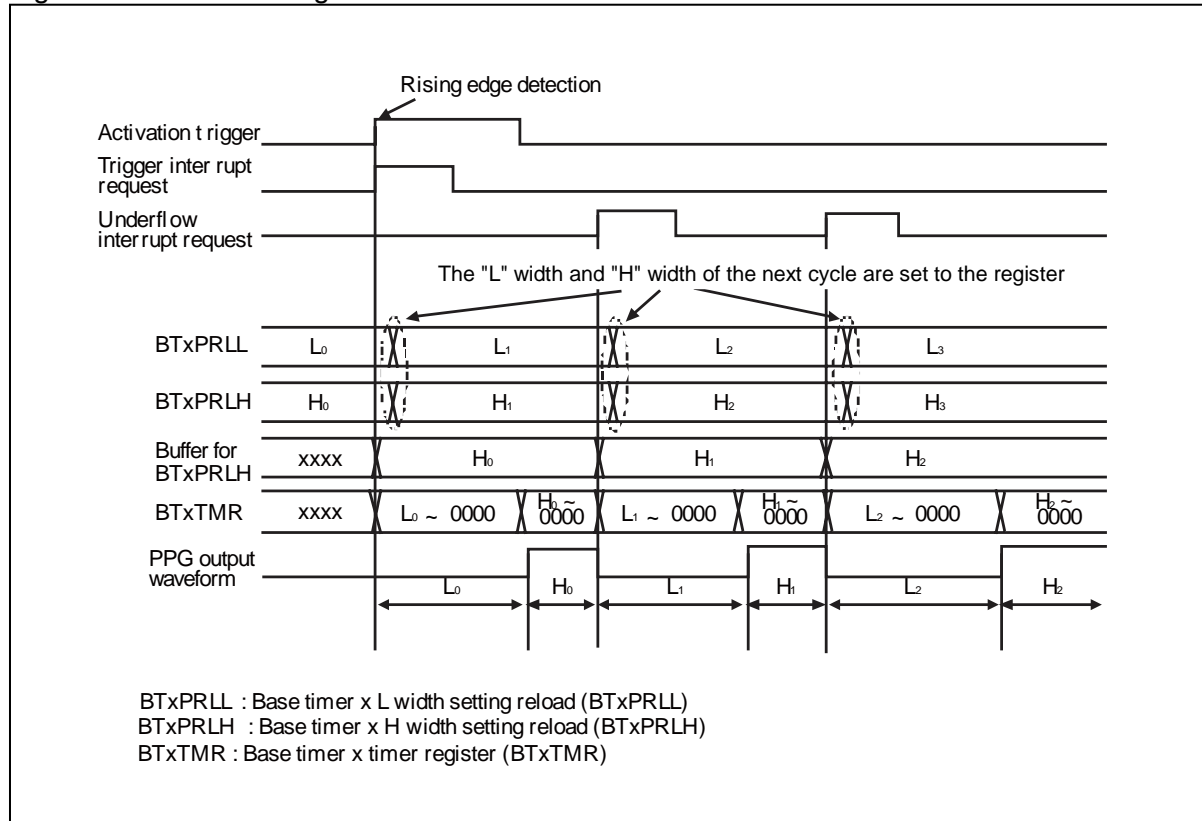
- An activation trigger is detected.
- An underflow occurs after counting down from the value of the base timer x H width setting reload register (BTxPRLH) is completed.

The content of the buffer is loaded to the 16-bit down counter in the following event:

- Counting down from the value of the base timer x L width setting reload register (BTxPRLl) is completed.

Therefore, rewrite the base timer x L width setting reload register (BTxPRLl) and base timer x H width setting reload register (BTxPRLH) during the period from the time an underflow occurs (the UDIR bit of the status control register (BTxSTC) changes to "1") to the time counting based on the next cycle begins. The new data will be effective as the next cycle.

Figure 5-19 Write Timing



■ Interrupt Generation Timing

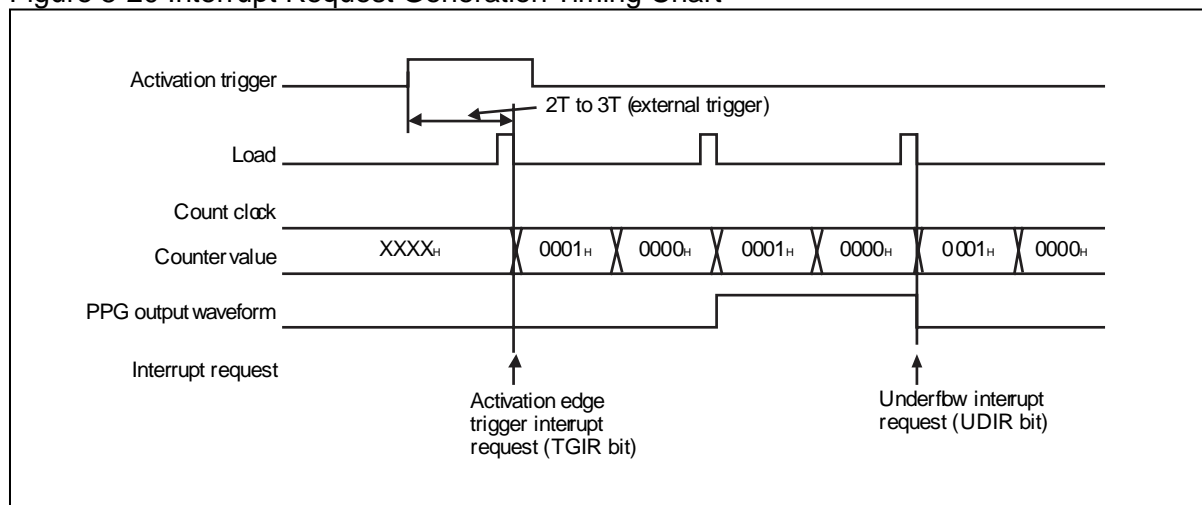
The 16-bit PPG timer can generate an interrupt request in one of the following events:

- An activation trigger is detected.
- An underflow occurs based on the value of H width setting reload register (BTxPRLH).

An example of interrupt request generation timing using the following settings is shown below.

- Value of L width setting reload register (BTxPRLH) = 0001_H
- Value of H width setting reload register (BTxPRLH) = 0001_H

Figure 5-20 Interrupt Request Generation Timing Chart



5.6.4. Operation in One-Shot Mode

This section explains the operation in one-shot mode.

This section explains the operation in one-shot mode.

■ Counting Operation

● Activation

It is the same operation as in reload mode. See "■ Operation" in "5.6.3 Operation in Reload Mode".

● Counting Operation

Counting operation initiated by the entry of an activation trigger is explained below, using an example where the OSEL bit of the timer control register (BTxTMCR) is set for normal polarity (OSEL = 0).

1. The value set in the base timer x L width setting reload register (BTxPRL) is transferred to the 16-bit down counter and the value set in the base timer x H width setting reload register (BTxPRLH) is transferred to the buffer. The 16-bit down counter begins to count down from the value of the L width setting reload register (BTxPRL). The output signal (TOUT) is at the "L" level.
2. The 16-bit down counter completes counting down from the value of L width setting reload register (BTxPRL).
3. The buffered value of H width setting reload register (BTxPRLH) is reloaded to the 16-bit down counter, which continues counting down. The output signal (TOUT) is at the "H" level.
4. The 16-bit down counter completes counting down from the value of H width setting reload register (BTxPRLH), thus causing an underflow.
5. The counting stops.

Operation that is performed if reactivation is permitted or not during counting depends on whether reactivation is permitted based on the RTGEN bit of the timer control register (BTxTMCR).

- If reactivation is not permitted (RTGEN = 0): Any activation trigger is ignored when it is entered during counting.
- If reactivation is permitted (RTGEN = 1): The TGIR bit of the status control register (BTxSTC) changes to "1". In addition, the value of L width setting reload register (BTxPRL) is reloaded to the 16-bit down counter, which starts counting.

Figure 5-21 Example of Counting Operation If Reactivation Is Not Enabled

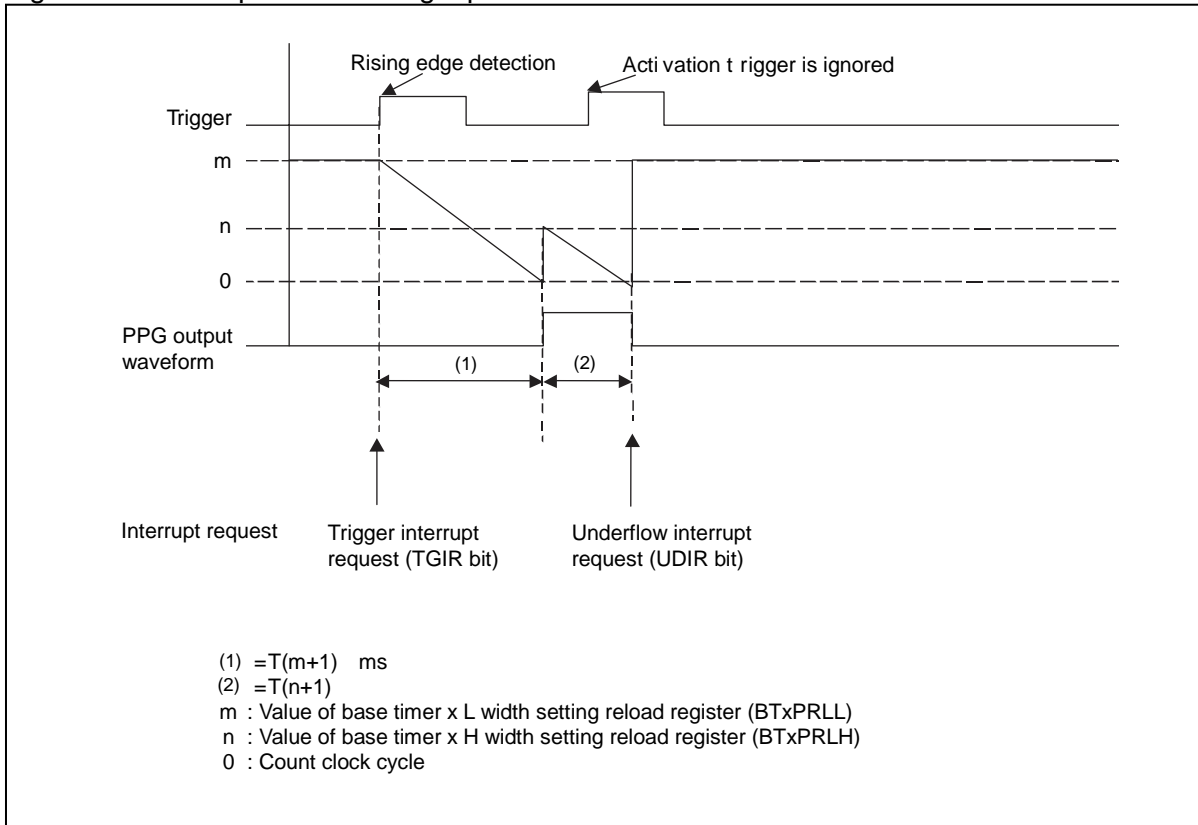
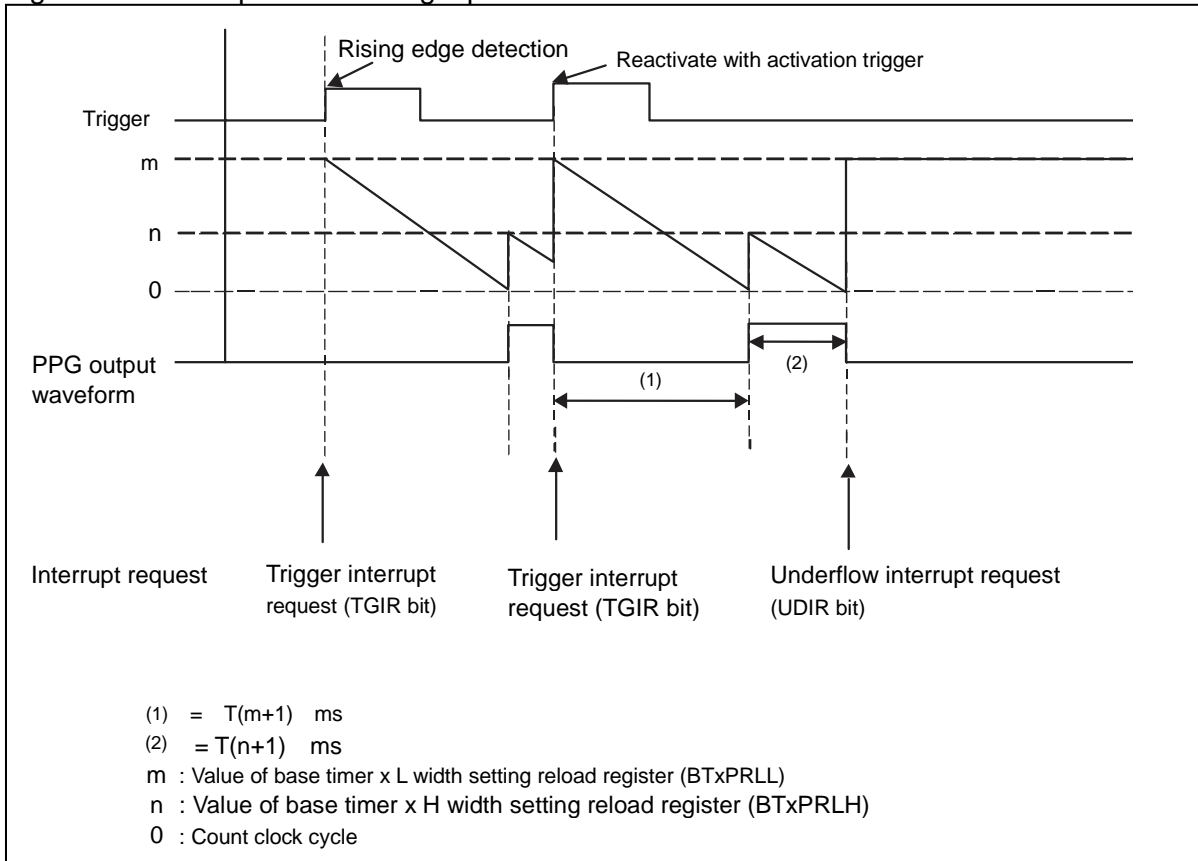


Figure 5-22 Example of Counting Operation If Reactivation Is Enabled



Notes:

- The output method and output destination of the output signal (TOUT) from the 16-bit PPG timer depend on the following settings:
 - Base timer I/O mode
 - TIOA0, TIOA1 pin functions
 - If a 16-bit PPG timer activation trigger is detected when counting ends, the value (cycle) of L width setting reload register (BTxPRL) is loaded to the 16-bit down counter, which starts counting.
-

■ Interrupt Generation Timing

It is the same operation as in reload mode. See "■ Interrupt Generation Timing" in "5.6.3 Operation in Reload Mode".

5.6.5. Interrupts

This section explains interrupts of the 16-bit PPG timer operation.

An interrupt request is generated in one of the following events:

- An activation trigger is detected. (trigger interrupt request)
- An underflow occurs based on the value of H width setting reload register (BTxPRLH). (underflow interrupt request)

Table 5-5 Interrupt Occurrence Conditions

Interrupt request	Interrupt request flag	Permission of interrupt request	Interrupt request clear
Trigger interrupt request	BTxSTC:TGIR = 1	BTxSTC:TGIE = 1	Set the TGIR bit of BTxSTC to "0".
Underflow interrupt request	BTxSTC:UDIR = 1	BTxSTC:UDIE = 1	Set the UDIR bit of BTxSTC to "0".

Notes:

- Once the generation of an interrupt request is enabled while the interrupt request flag is "1", an interrupt request will be issued when the interrupt is enabled.
- To enable the generation of an interrupt request, perform one of the following operations:
 - Clear the current interrupt request before enabling the generation of an interrupt request.
 - Clear the current interrupt request when enabling the interrupt.
 - Either clear the current interrupt request after disabling the generation of an interrupt request or clear the current interrupt request within the interrupt processing routine.
- Set an interrupt level corresponding to the interrupt vector number, using interrupt control registers (ICR00 to ICR47). For information on interrupt level setting, see the chapter entitled "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

5.6.6. Application Notes

This section explains notes when using the 16-bit PPG timer.

Note the following when using the 16-bit PPG timer:

■ Notes on Program Setting

- Change the following bits of the timer control register (BTxTMCR) only after stopping the 16-bit down counter by resetting the CTEN bit to "0"(CTEN=0).
 - CKS2 to CKS0 bits
 - EGS1 and EGS0 bits
 - FMD2 to FMD0 bits
 - MDSE bit
- All registers are initialized if the FMD2 to FMD0 bits of timer control register (BTxTMCR) are set to "000" to select reset mode.
- Before the base timer function can be changed, the base timer must be reset once. Except when rewriting the FMD2 to FMD0 bits of timer control register (BTxTMCR) after reset, be sure to clear FMD2 to FMD0 bits to "000" to select the reset mode, and then select a base timer function using the FMD2 to FMD0 bits again.
- Set the 16-bit PPG timer in the following steps.
 1. Set the 16-bit PPG timer as the base timer function by setting the FMD2 to FMD0 bits of timer control register (BTxTMCR) to "010"(FMD2 to FMD0=010).
 2. Set the L width setting reload register (BTxPRL).
 3. Set the H width setting reload register (BTxPRLH).

■ Notes on Operations

- The value loading precedes if the count timing of the 16-bit down counter and the load timing occur at the same time.
- If a 16-bit PPG timer reactivation trigger is detected when counting ends in the one-shot mode, the value (cycle) of L width setting reload register (BTxPRL) is loaded to the 16-bit down counter, which starts counting.
- A different signal (external clock, external activation trigger, wave form) I/O operation can be selected using the base timer I/O selection function.

■ Notes on Interrupts

If an instruction to clear the interrupt request flag and an instruction to change the interrupt request flag to "1" occur at the same time, the flag clear instruction is ignored. The interrupt request flag is held to "1".

5.7. 16/32-bit PWC Timer Operation

This section explains the 16/32-bit PWC timer operation.

This section explains the operation performed when the base timer included in this series is used as the 16/32-bit PWC timer. Examples of procedures for setting various operating conditions are also provided.

Figure 5-23 Block Diagram (16-bit PWC Timer Operation)

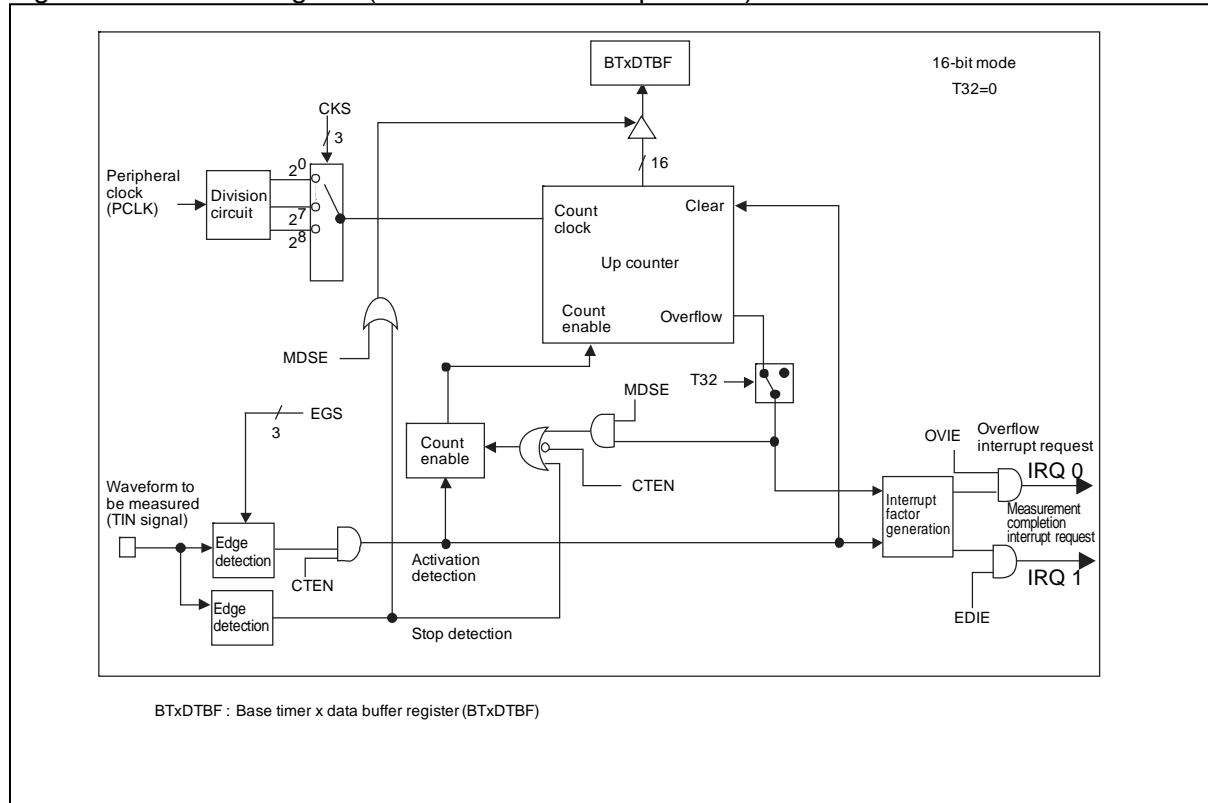
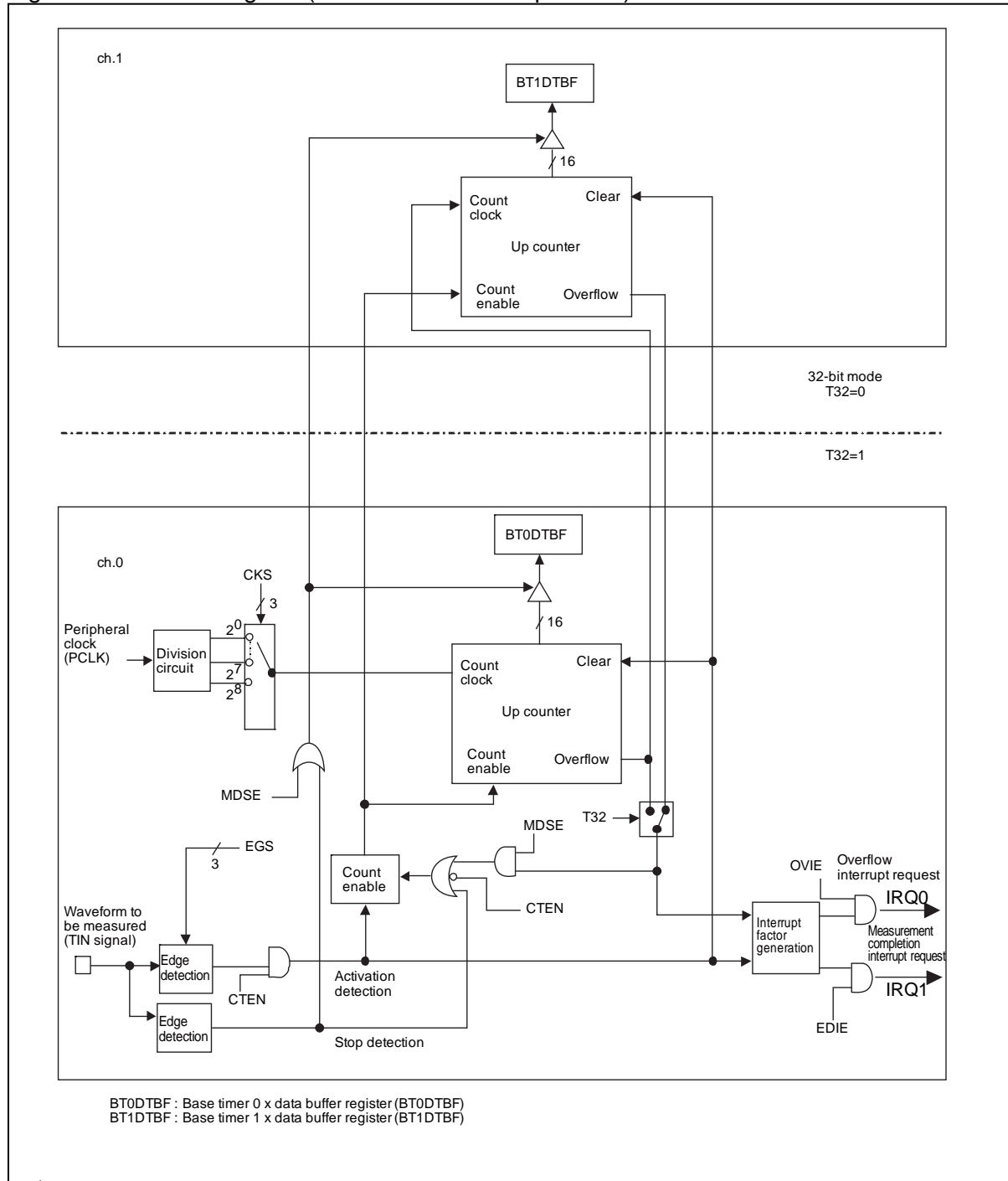


Figure 5-24 Block Diagram (32-bit PWC Timer Operation)



5.7.1. Overview

This section explains the overview of the 16/32-bit PWC timer operation.

The 16/32-bit PWC timer is used to measure the pulse width and cycle of input signals. When a measurement start edge is detected in an input signal (TIN), the counting up starts. This counting stops when a measurement end edge is detected. The counted value (that is, the measured result) is stored as the pulse width or cycles in the data buffer register (BTxDTBF).

The 16/32-bit PWC timer supports three modes: the timer mode, the operation mode, and measurement mode. The operation of the timer varies in accordance with a combination of these modes.

Note:

The input method of the TIN signal varies depending on the I/O mode that has been set by the I/O selection register (BTSEL01). See "5.2 I/O Allocation".

■ Timer Mode

Either of the following timer modes can be selected using the T32 bit of the timer control register (BTxTMCR).

- 16-bit timer mode (T32 = 0): A 16-bit PWC timer can operate individually for each of the channels.
- 32-bit timer mode (T32 = 1): Two channels can be cascaded and used as a 32-bit PWC timer.

See "5.7.3 32-bit Timer Mode Operation" for details on the operation in 32-bit timer mode.

Note:

The T32 bit setting differs between odd-numbered and even-numbered channels when the 32-bit timer mode is selected. For details, see "5.7.3 32-bit Timer Mode Operation".

■ Operation Mode

Either of the following two modes can be selected using the MDSE bit of the timer control register (BTxTMCR).

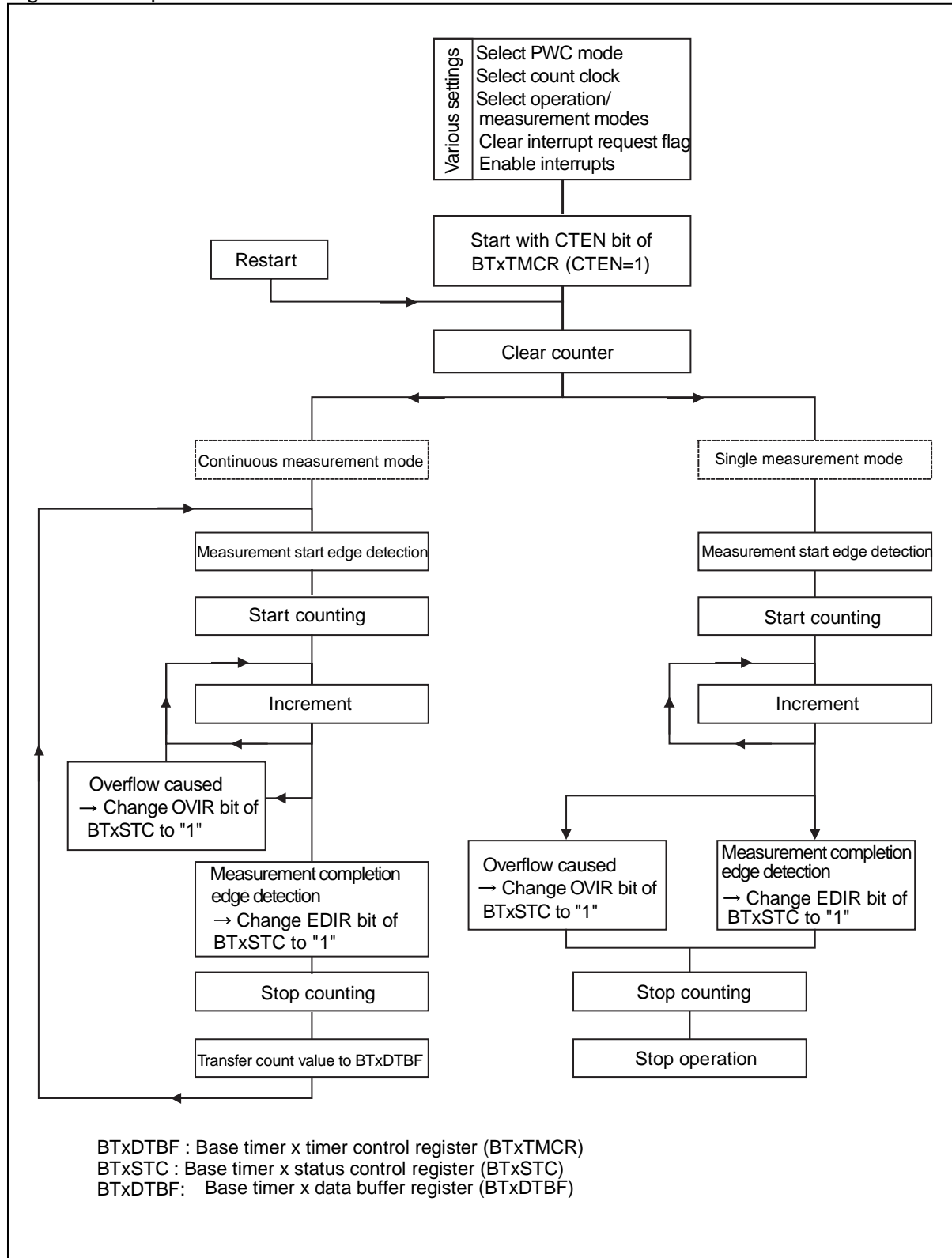
- Continuous measurement mode (MDSE = 0): In this mode, after one sequence of measurement is conducted, the input of the next measurement start edge is awaited and the detection of the next measurement start edge triggers another sequence of measurement.
- Single measurement mode (MDSE = 1): In this mode, measurement is conducted only once. Differences between the single and continuous measurement modes are listed on the table below.

Table 5-6 Differences between Single and Continuous Measurement Modes

	Single measurement mode	Continuous measurement mode
Measurement	Measurement stops when a measurement end edge is detected.	When a measurement end edge is detected, the measurement stops and the next measurement start edge is waited. When the next measurement start edge is detected, the measurement restarts.
BTxDTBF function	During measurement: The measured value is held. After measurement: The measurement result is held.	During measurement: The previous measurement result is held. After measurement: The measurement result is held.
During overflow	The measurement stops.	The measurement restarts from 0x0000

Figure 5-25 shows the standard operation flow.

Figure 5-25 Operation Flow



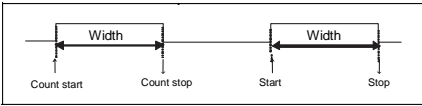
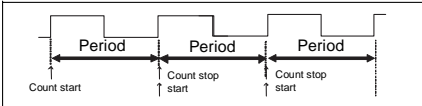
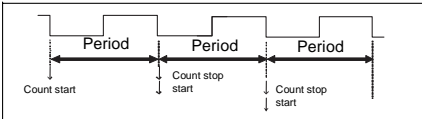
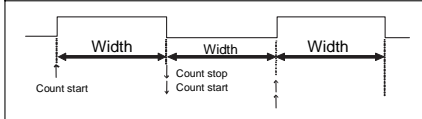
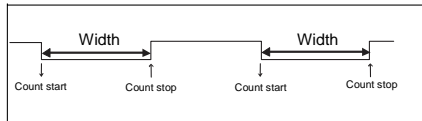
Note:

In the continuous measurement mode, if the next measurement is completed before the measurement result has been read from the data buffer register (BTxDTBF), the value being held by the data buffer register (BTxDTBF) is overwritten by the new value. The old value is discarded. If it has occurred, the ERR bit of the status control register (BTxSTC) changes to "1". This ERR bit is cleared to "0" when a value is read from the base timer x data buffer register (BTxDTBF).

■ **Measurement Mode**

Either of the following five modes can be selected using EGS2 to EGS0 bits of the timer control register (BTxTMCR).

Figure 5-26 Measurement Modes and their Explanation

Measurement mode (EGS2 to EGS0)	Measurement description
Measurement of H pulse width (EGS2 to EGS0=000)	<p>The width of the period which the the "H" level signal is being input is</p>  <p>Count (measurement) start: at rising edge detection Count (measurement) stop: at falling edge detection</p>
Measurement of the cycle between rising edges (EGS2 to EGS0=001)	<p>The cycle from the rising edge detection to the next rising edge detection is measured</p>  <p>Count (measurement) start: at rising edge detection Count (measurement) stop: at rising edge detection</p>
Measurement of the cycle between falling edges (EGS2 to EGS0=010)	<p>The cycle from the falling edge detection to the next falling edge detection is measured.</p>  <p>Count (measurement) start: at falling edge detection Count (measurement) stop: at falling edge detection</p>
Measurement of the pulse width between all edges (EGS2 to EGS0=011)	<p>The width between the edges input continuously is measured.</p> <ul style="list-style-type: none"> •From rising edge detection to falling edge detection •From falling edge detection to rising edge detection Count  <p>Count (measurement) start: at edge detection Count (measurement) stop: at edge detection</p>
Measurement of L pulse width(EGS2 to EGS0=100)	<p>The width of the period during which the "L" level signal being input is measured.</p>  <p>Count (measurement) start: at falling edge detection Count (measurement) stop: at rising edge detection</p>

5.7.2. Operation during PWC Measurement

This section explains the operation during PWC measurement.

This section explains the operations during measurement. For explanation of "sensitive edges" (1) and (2) described below, see Figure 5-26 Measurement Modes and their Explanation .

■ Activation

Activate the 16/32-bit PWC timer with the following procedure:

Enable the 16/32-bit PWC timer operation by setting the CTEN bit of the timer control register (BTxTMCR) to "1"(CTEN=1). The counter value is cleared to "0000_H" and the 16/32-bit PWC timer waits for an input of measurement start edge. (No counting occurs until an input of measurement start edge.)

■ Counting Operation

● Operation in single measurement mode

If sensitive edge (1) is detected in the input signal (TIN) when a measurement start edge is waited, the up counter starts counting up from "0001_H" in synchronous with the count clock. If sensitive edge (2) is detected in the input signal (TIN), the up counter stops from operating. During this time, the up counter value is stored in the data buffer register (BTxDTBFB). An interrupt request can be generated at the end of measurement or at an occurrence of overflow.

Notes:

- In the single measurement mode, the counting stops if an overflow occurs.
 - The input method of waveforms to be measured (TIN signal) varies depending on the I/O mode that has been set by the I/O selection register (BTSEL01).
-

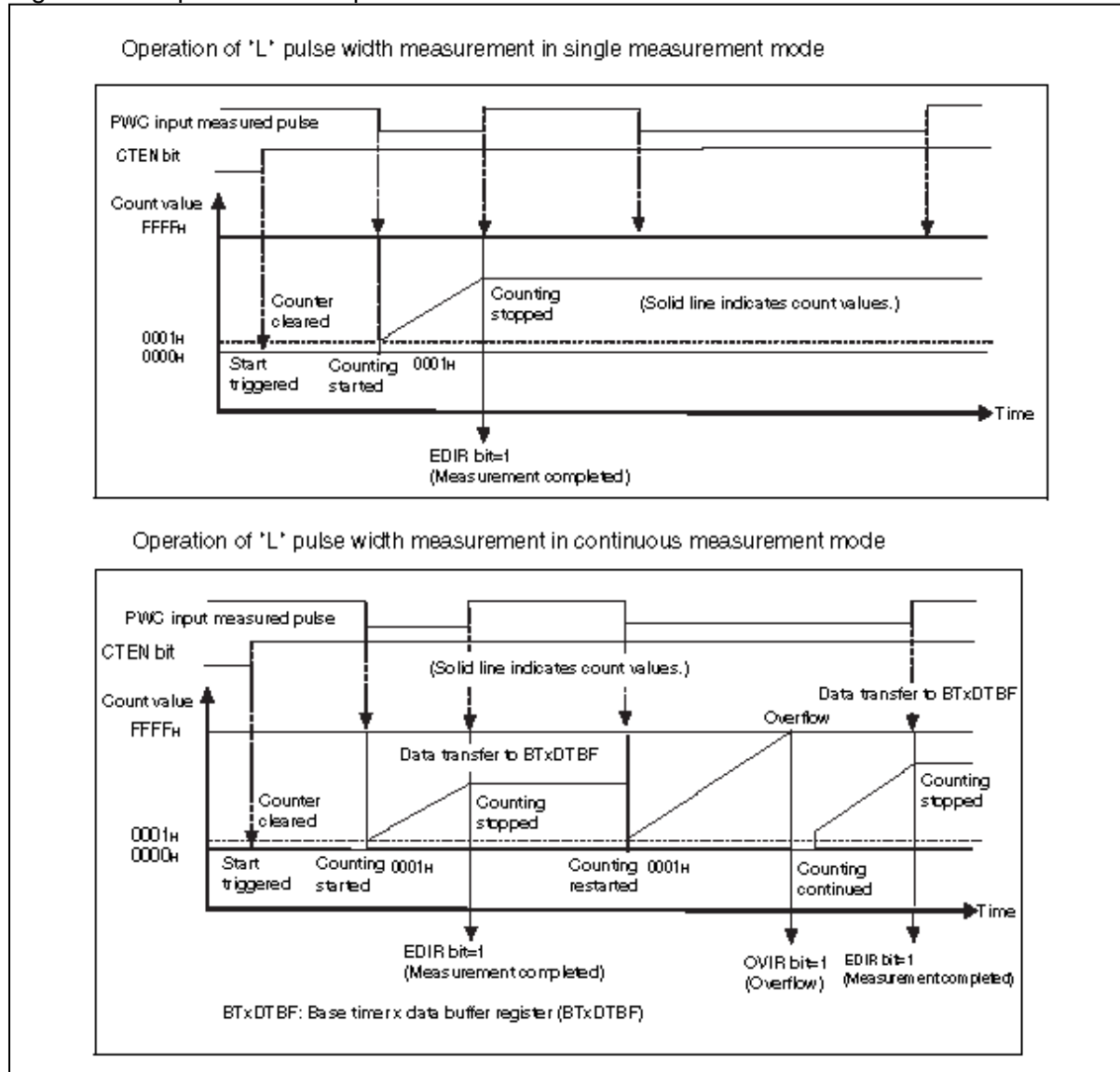
● Operation in continuous measurement mode

If sensitive edge (1) is detected in the input signal (TIN) when a measurement start edge is waited, the up counter starts counting up from "0001_H" in synchronous with the count clock. If sensitive edge (2) is detected in the input signal (TIN), the up counter stops from operating and waits for an input of measurement start edge. During this time, the up counter value is stored in the data buffer register (BTxDTBFB). If a rising edge of the input signal (TIN) is detected when a measurement start edge is waited, the up counter starts counting up from "0001_H" again. An interrupt request can be generated at the end of measurement or at an occurrence of overflow.

Note:

The input method of waveforms to be measured (TIN signal) varies depending on the I/O mode that has been set by the I/O selection register (BTSEL01).

Figure 5-27 Operation Example



■ **Reactivation**

If the CTEN bit of the base timer x timer control register (BTxTMCR) is set to "1" during counting, the up counter reactivates and operates as follows.

- **If the counter is reactivated when a measurement start edge is waited:**
The current status waiting for a measurement start edge is continued.
- **If the timer is reactivated during measurement:**
The up counter value is cleared to "0000_H" and set to the measurement start edge waiting status.

Notes:

- If a detection of measurement end edge and a timer reactivation occur simultaneously, the following may result. In such case, set the interrupt control correctly by considering the operation of interrupt request flag.
 - Single measurement mode: The timer reactivates and waits for a measurement start edge. Also, the EDIR bit (the measurement end interrupt request flag) of the status control register (BTxSTC) is set to "1".
 - Continuous measurement mode: The timer reactivates and waits for a measurement start edge. Also, the EDIR bit (the measurement end interrupt request flag) of the status control register (BTxSTC) is set to "1". Also, the current measurement result is transferred to the data buffer register (BTxDTBFB).
 - If the 16/32-bit PWC timer is reactivated in the continuous measurement mode and if a measurement start edge is detected in the input signal (TIN) simultaneously, the timer immediately starts counting from the value "0001_H".
-

■ **Calculating the Pulse Width**

After the measurement, the measurement result can be read from the base timer x data buffer register (BTxDTBFB) and the measured pulse width can be calculated using the following formula.

Pulse width = $n \times T$

n: Data buffer register (BTxDTBFB) value

T: Count clock cycle

5.7.3. 32-bit Timer Mode Operation

This section explains the 32-bit timer mode operation.

This section explains the setting and operation for cascading 2 channels of a 16-bit PWC timer and using them as a 32-bit PWC timer.

■ Overview

Using the T32 bit of the timer control register (BTxTMCR), 2 channels of a 16-bit PWC timer can be cascaded and used as a 32-bit PWC timer.

In this mode, the even-numbered channel corresponds to the lower 16-bit operation, and the odd-numbered channel corresponds to the upper 16-bit operation. Therefore, the up counter must be read in the order of the lower 16 bits (even-numbered channel) → the upper 16 bits (odd-numbered channel).

■ Setting Procedure (Example)

To select the 32-bit timer mode, set the T32 bit of the base timer x timer control register (BTxTMCR) of the even-numbered channel to "1". Also, set the T32 bit of the odd-numbered channel to "0". When setting 32-bit timer mode, set the registers using the procedure shown below.

The register setting differs between even-numbered and odd-numbered channels. In this example, channel 0 and channel 1 are connected by cascading.

1. Specify ch.0 to reset mode by setting FMD2 to FMD0 bits of the base timer 0 timer control register (BT0TMCR). (FMD2 to FMD0 = 000)
2. Select 16/32-bit PWC timer for ch.0 and ch.1 by setting the FMD2 to FMD0 bits of the base timer x timer control register (BT0TMCR, BT1TMCR) of ch.0 and ch.1. (FMD2 to FMD0 = 100) At the same time, select the 32-bit timer mode by setting the T32 bit of the base timer 0 timer control register (BT0TMCR). (T32 = 1)

Note:

Rewrite the T32 bit while the operation of both of the even-numbered and odd-numbered channels are stopped. Whether the counting operation is stopped can be checked by setting the CTEN bit of the timer control register (BTxTMCR) to "0"(CTEN=0).

■ Operations

In the 32-bit timer mode, the counting operation is basically the same as in the 16-bit timer mode. However, the counting operation conforms to the settings of the even-number channels, ignoring the settings of the registers next to the odd-number channels.

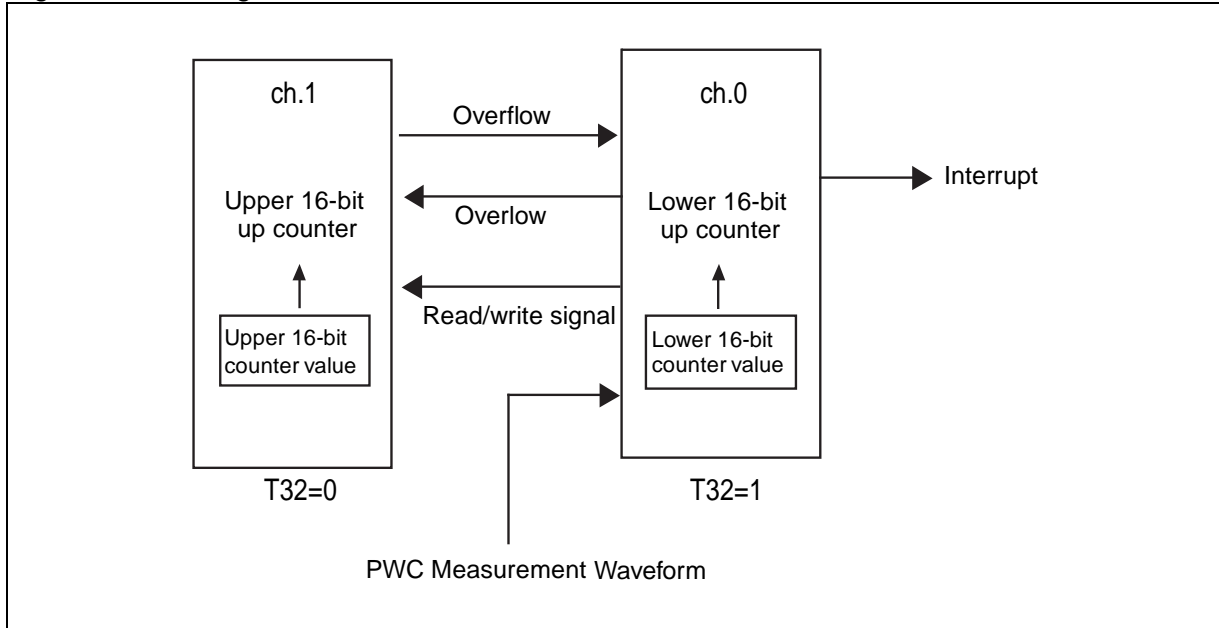
- Base timer x timer control register (BTxTMCR)
- Base timer x status control register (BTxSTC)

This section explains the counting in the 32-bit timer mode.

1. If the 16/32-bit PWC timer operation is enabled using the CTEN bit of the timer control register (BTxTMCR) (by setting CTEN = 1) of the even-numbered channel, the 32-bit PWC timer starts.
2. When a measurement start edge is detected in the input signal (TIN), the counting starts.
3. The up counter starts counting as a 32-bit counter with the even-number channel serving as the lower 16 bits and the odd-number channel as the upper 16 bits.
4. When a measurement end edge is detected in the input signal (TIN), the lower 16-bit data of the up counter is stored in the data buffer register (BTxDTBFB) of the even-numbered channel. Also, the upper 16-bit data is stored in the data buffer register (BTxDTBFB) of the odd-numbered channel.

The channel configuration in 32-bit timer mode is shown below.

Figure 5-28 Configuration in 32-bit Timer Mode



Notes:

- The down counter value can be checked by reading the data buffer register (BTxDTBF). In the 32-bit timer mode, it must be read in the order of the lower 16 bits (even-numbered channel) → upper 16 bits (odd-number channel).
- In 32-bit timer mode, the operation of the 32-bit PWC timer conforms to the settings of the even-number channel. Therefore, an interrupt request of the even-numbered channel is effective.

5.7.4. Interrupt

This section explains interrupt of the base timer.

An interrupt request is generated in one of the following events:

- An overflow occurs. (Overflow interrupt request)
- The measurement ends. (Measurement end interrupt request)

Table 5-7 Interrupt Occurrence Conditions

Interrupt request	Interrupt request flag	Permission of interrupt request	Interrupt request clear
Overflow interrupt request	BTxSTC:OVIR=1	BTxSTC:OVIE=1	Set the OVIR bit of BTxSTC to "0".
Measurement end interrupt request	BTxSTC:EDIR=1	BTxSTC:EDIE=1	Read BTxDTBF

Notes:

- Once the generation of an interrupt request is enabled while the interrupt request flag is "1", an interrupt request will be issued when the interrupt is enabled.
- To enable the generation of an interrupt request, perform one of the following operations:
 - Clear the current interrupt request before enabling the generation of an interrupt request.
 - Clear the current interrupt request when enabling the interrupt.
 - Either clear the current interrupt request after disabling the generation of an interrupt request or clear the current interrupt request within the interrupt processing routine.
- For interrupt vector numbers used for issuing an interrupt request, see "C. List of Interrupts Vector" in entitled "APPENDIX".
- Set the interrupt level corresponding to the interrupt vector number in one of the interrupt control registers (ICR00 to ICR47). For information on interrupt level setting, see the chapter entitled "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

5.7.5. Application Notes

This section explains application notes of the base timer.

Note the following when using the 16/32-bit PWC timer:

■ Notes on Program Setting

- Change the following bits of the base timer x timer control register (BTxTMCR) after stopping the up counter by resetting the CTEN bit to "0"(CTEN=0).
 - CKS2 to CKS0 bits
 - EGS2 to EGS0 bits
 - T32 bit
 - FMD2 to FMD0 bits
 - MDSE bit
- All registers are initialized when the FMD2 to FMD0 bits of the timer control register (BTxTMCR) are set to "000" to select reset mode.
- Before the base timer function or T32 bit can be changed, the base timer must be reset once. Except when rewriting the status of FMD2 to FMD0 bits or T32 bit of the timer control register (BTxTMCR) after a reset, be sure to reset the FMD2 to FMD0 bits to "000" to select the reset mode. Then, rewrite the status of these bits.
- The timer may operate due to the status of previously measured signals if the followings are set simultaneously during system reset or during reset mode.
- The base timer function is set for the 16/32-bit PWC timer by setting the FMD2 to FMD0 bits of the base timer x timer control register (BTxTMCR) to "100"(FMD2 to FMD0=100).
- Enable 16/32-bit PWC timer operation by setting the CTEN bit of the base timer x timer control register (BTxTMCR) to "1"(CTEN=1).

■ Notes on Operations

- The value loading precedes if the count timing of the up counter and the load timing occur at the same time.
- If the 16/32-bit PWC timer operation is enabled by setting the CTEN bit of the base timer x timer control register (BTxTMCR) to "1"(CTEN=1), the up counter value is cleared. Also, the up counter value is made invalid if it has been set before the operation is enabled.
- If the 16/32-bit PWC timer is reactivated in the continuous measurement mode and if a measurement start edge is detected in the input signal (TIN) simultaneously, the timer immediately starts counting from the value "0001_H".
- If two channels of PWC timers are used as a single 32-bit PWC timer, the 16-bit PWC timer setting of the even-numbered channel is made valid. The timer setting of odd-numbered channel is ignored.
- The input operation of measurement waveforms varies depending on the base timer I/O selection function.

■ Notes on Interrupts

- If an instruction to clear the interrupt request flag and an instruction to change the interrupt request flag to "1" occur at the same time, the flag clear instruction is ignored. The interrupt request flag is held to "1".
- If a detection of measurement end edge and a reactivation of 16/32-bit PWC timer occur simultaneously, the following may result. In such case, set the interrupt control correctly by considering the operation of the interrupt request flag.
 - Pulse width single measurement mode: The timer reactivates and waits for a measurement start edge. Also, the measurement end interrupt request flag (EDIR) is set to "1".
 - Pulse width continuous measurement mode: The timer reactivates and waits for a measurement start edge. The measurement end interrupt request flag (EDIR) is set to "1", and the currently measured result is transferred to the data buffer register (BTxDTBF).

CHAPTER: RELOAD TIMER

This chapter explains the reload timer.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Application Notes

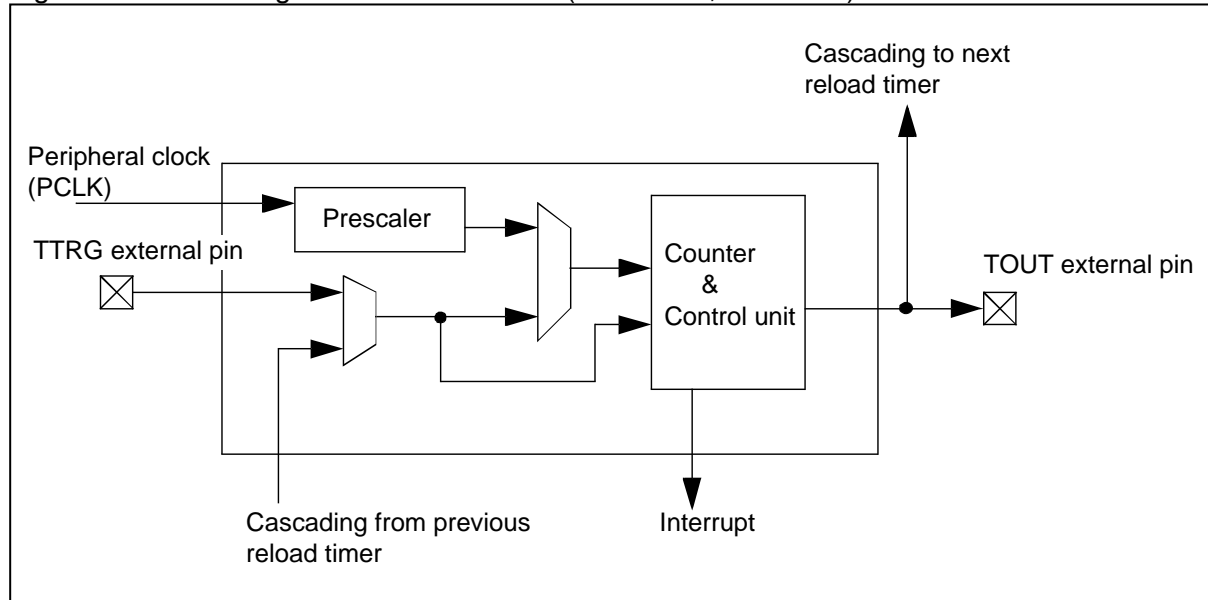
Code : 20_MB91590_HM_E_reloadtim_008_20111128

1. Overview

This section explains the overview of the reload timer.

This module is a 16-bit reload down count timer with the interval timer mode, which counts the internal clock, and the event counter mode, which counts external events.

Figure 1-1 Block Diagram of Reload Timer (1 Channel, Overview)



2. Features

This section explains features of the reload timer.

A 4-channel reload timer is installed in this series. Each channel is configured as follows:

- 16-bit down counter ×1
- 16-bit reload register ×1
- 16-bit reload / compare/ capture register ×1
- Buffers described above ×1
- 6-bit prescaler for internal count clock creation ×1
- External trigger/event input (TTRG) ×1
- External toggle output (TOUT) ×1
- Control register ×1
- Count comparator ×1

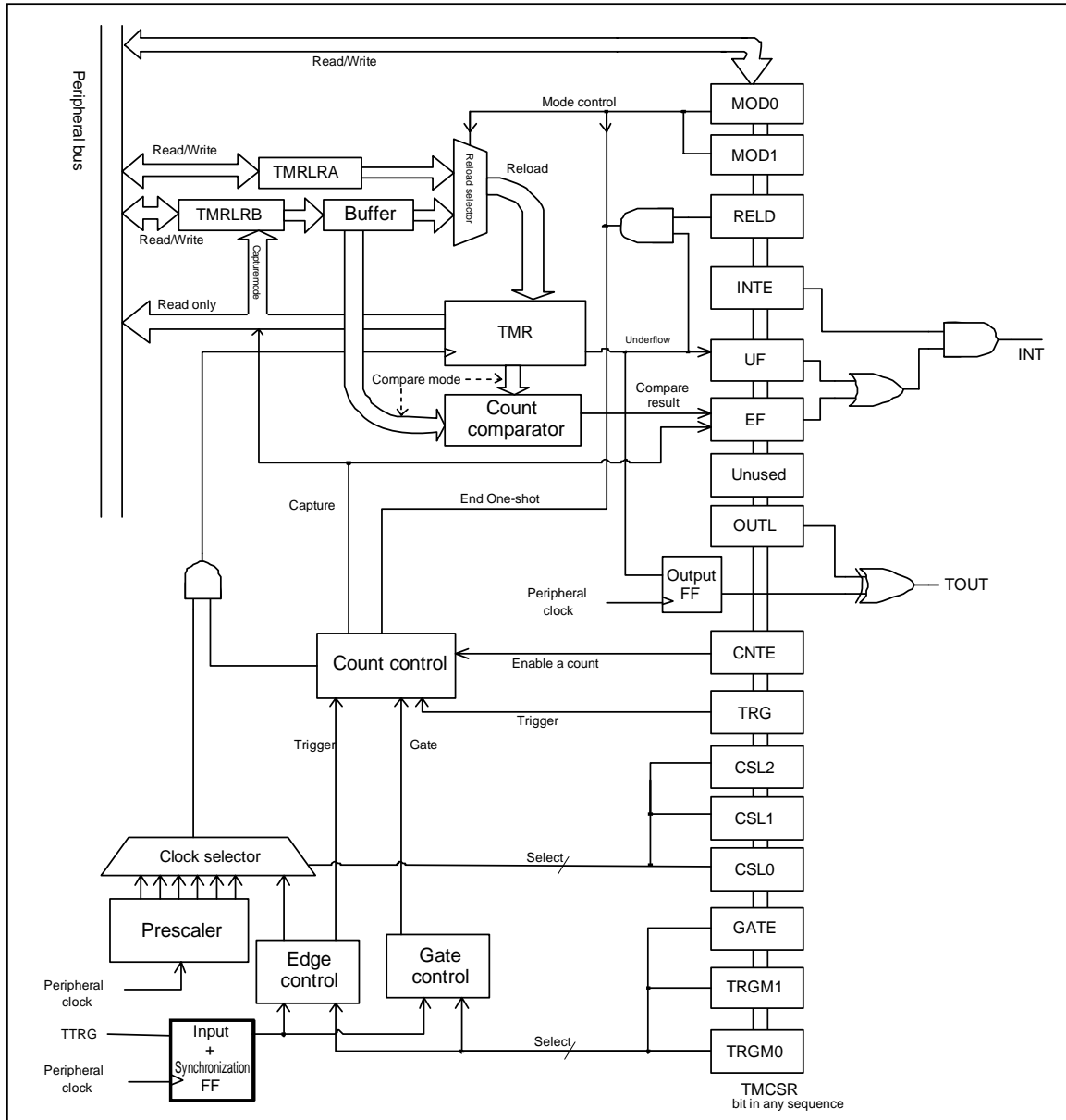
This timer, equipped with the interval timer mode/event counter mode described below, can be used for the following purposes and functions by setting the registers:

- Interval timer mode
 - Single one-shot operation ⇒ Single-shot Timer
 - Dual one-shot operation
 - Single reload operation ⇒ Reload Timer
 - Dual reload operation ⇒ PPG(Programmable Pulse Generator)
 - Compare mode ⇒ Output compare, PWM(Pulse Width Modulator)
 - Capture mode (external trigger input/software trigger use)
⇒ PWC(Pulse Width Counter)
 - Underflow interrupt/capture interrupt
 - 6 types of internal clocks (peripheral clock (PCLK) divided by 2/4/8/16/32/64)
 - External trigger input (rising edge/falling edge/both edges)
 - External gate input
- Event counter mode
 - Single one-shot operation
 - Dual one-shot operation
 - Single reload operation
 - Dual reload operation
 - Compare mode
 - Capture mode (only software trigger)
 - Underflow interrupt/capture interrupt/compare interrupt
 - External event input edge detection (rising edge detection/falling edge detection/both edge detection)
 - Cascade mode
 - Use ch.0 output for ch.1 input. Use ch.1 output for ch.2 input. Use ch.2 output for ch.3 input.

3. Configuration

This section explains the configuration of the reload timer.

Figure 3-1 Block Diagram of Reload Timer (1 Channel, Details)



4. Registers

This section explains registers of the reload timer.

■ Table of Base Address (Base_addr), External Pins

Table 4-1 Table of Base Address (Base_addr), External Pins

Channel	Base_addr	External pin	
		TOUT	TTRG
0	0x0060	TOT0/TOT0_1/TOT0_2	TIN0/TIN0_1/TIN0_2
1	0x0100	TOT1/TOT1_1/TOT1_2	TIN1/TIN1_1/TIN1_2
2	0x0108	TOT2/TOT2_1/TOT2_2	TIN2/TIN2_1/TIN2_2
3	0x0110	TOT3/TOT3_1/TOT3_2	TIN3/TIN3_1/TIN3_2

■ Registers Map

Table 4-2 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0060	TMRLRA0		TMR0		16-bit timer reload register A0 16-bit timer register 0
0x0064	TMRLRB0		TMCSR0		16-bit timer reload register B0 Control status register 0
0x0100	TMRLRA1		TMR1		16-bit timer reload register A1 16-bit timer register 1
0x0104	TMRLRB1		TMCSR1		16-bit timer reload register B1 Control status register 1
0x0108	TMRLRA2		TMR2		16-bit timer reload register A2 16-bit timer register 2
0x010C	TMRLRB2		TMCSR2		16-bit timer reload register B2 Control status register 2
0x0110	TMRLRA3		TMR3		16-bit timer reload register A3 16-bit timer register 3
0x0114	TMRLRB3		TMCSR3		16-bit timer reload register B3 Control status register 3

4.1. Control Status Register : TMCSR (TiMer Control and Status Register)

The bit configuration of the control status register is shown below.

These registers control the operating mode and interrupt.

It is not possible to rewrite any data other than bit7 and bit3 to bit0 when bit1:CNTE=1.

It is possible to rewrite bit15-bit8 and bit6-bit4 and write counter operation enabling by writing CNTE=1 simultaneously. It is also possible to rewrite bit15-bit8, bit6-bit4 and write operation disabling by writing CNTE=0 simultaneously.

■ TMCSR : Address Base_addr + 06_H (Access : Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	MOD[1:0]		TRGM[1:0]		CSL[2:0]			GATE
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EF	Reserved	OUTL	RELD	INTE	UF	CNTE	TRG
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1),W	R,W	R,W	R,W	R,W	R(RM1),W	R,W	R0,W

[bit15, bit14] MOD [1:0] (MODE) : Mode selection bits

MOD[1:0]	Operation mode
00	Single mode (initial value)
01	Dual mode
10	Compare mode
11	Capture mode

[bit13, bit12] TRGM[1:0] (TRiGger input Mode select) : TTRG Input mode selection bits

These bits control input pin functions. The functions of the interval timer mode differ from those of the event counter mode.

[Interval timer mode, trigger input (bit8:GATE bit=0)]

Select an effective external edge which can be a reload trigger through TTRG input in the following manner:

TRGM[1:0]	TTRG effective external edge
00	No external trigger detection (initial value)
01	Rising edge
10	Falling edge
11	Both edges

[Interval timer mode, gate input (bit8:GATE =1)]

Select the pin level which enables the counter during TTRG input in the following manner:

TRGM[1:0]	TTRG effective level
x0	TTRG pin "L" counted only during the input period (initial value)
x1	TTRG pin "H" counted only during the input period

[Effective edge setting at the event counter mode]

In the event counter mode, select an edge for external event detection in the following manner:

Every time an external event is detected, the counter value is decreased. When an external event is selected, the setting of the bit8:GATE bit becomes invalid.

TRGM[1:0]	Count target edge
00	Reserved
01	Rising edge
10	Falling edge
11	Both edges

[bit11 to bit9] CSL[2:0] (Conut source SeLect) : Count source selection bits

These are count source selection bits. Select a count source from the internal clock (peripheral clock (PCLK)) and the external event (TTRG input) specified following: When the event counter mode is set, set the count effective edge using bit13, bit12:TRGM[1:0].

CSL[2:0]	Count source	Operation mode
000	Division of the peripheral clock frequency by 2 (initial value)	Interval timer mode
001	Division of the peripheral clock frequency by 4	
010	Division of the peripheral clock frequency by 8	
011	Division of the peripheral clock frequency by 16	
100	Division of the peripheral clock frequency by 32	
101	Division of the peripheral clock frequency by 64	
110	Cascade mode (ch.0:TTRG0, ch.1:TOUT0, ch.2:TOUT1, ch.3:TOUT2)	Event counter mode
111	External event (TTRG input)	

[bit8] GATE (GATE input enable) : Gate input enabling bit

This bit controls the functions of the input pin (TTRG) of (bit11 to bit9:CSL[2:0]=000 to 101) at the interval timer mode specified following.

GATE	TTRG input pin functions
0	Use as trigger input (initial value)
1	Use as gate input

This bit does not influence any operation at the event counter mode.

[bit7] EF (Extended Flag) : Extended interrupt flag

This flag indicates that a compare match interrupt has occurred at the compare mode or a capture input interrupt has occurred at the capture mode.

Set factor	[Compare mode of the event counter mode] Count down occurs from compare match (TMR = TMRLRB) [Capture mode] Capture input (retrigger)
Clear factor	Writing "0" to this bit or reset.

Writing "1" to this bit will not be effective. In synchronization with the count clock, set operation or clear operation are performed in the compare mode. The values read with read-modify-write instructions will always be "1".

[bit6] Reserved

Reserved bit. Data writing is ineffective.

[bit5] OUTL (OUTput Level) : Output polarity setting bit

This bit controls output polarity of the timer output pin (TOUT).

OUTL	TOUT initial value	TOUT initial output level
0	Positive polarity (Initial value)	L level
1	Negative polarity	H level

[bit4] RELD (RELoAD enable) : Reload operation enabling bit

This bit sets reload operation in case of underflow specified following:

RELD	Operation mode	Description of operation
0	One-shot mode	No sooner does a counter underflow occur, than the count operation stops. Reload is not performed until the next trigger is inputted. * (initial value)
1	Reload mode	Counter underflow occurs. At the same time, the contents of the reload register are loaded to the counter to continue count operation.

* : However, the dual one-shot function reloads TMRLRB at the same time as TMRLRA underflow and continues counting. After that, count operation stops at the same time as TMRLRB underflow.

[bit3] INTE (INTerrupt Enable) : Interrupt request enabling bit

This bit controls an interrupt request in case of underflow/compare match (event counter mode)/capture specified following:

INTE	Description of operation
0	Interrupt disabled (no interrupt is generated even if the UF/EF bit is set.) (initial value)
1	Interrupt enabled (an interrupt request is generated if the UF/EF bit is set.)

[bit2] UF (Under flow Flag) : Underflow flag

This flag indicates that underflow has occurred when the counter value is decreased from 0x0000.

Set factor	Counter underflow occurrence
Clear factor	Writing "0" to this bit or reset.

[bit1] CNTE (timer CouNTEr Enable) : Timer count enabling bit

This bit controls the operation of the timer as follows:

CNTE	Description of operation
0	Operation disabled (initial value)
1	Operation enabled (waiting for activation trigger)

[bit0] TRG (software TRiGger) : software trigger bit

This bit generates a timer software trigger. If a software trigger is generated, the contents of the reload register are loaded to the counter to initiate count operation.

TRG	Description of operation
Write "0"	No influence on the operation
Write "1"	A software trigger is generated.

When "0" is written into this bit, no influence on the operation. The read value is always "0".

Trigger input through this register is effective only when bit1:CNTE =1.

Writing "1" into the TRG bit always generates an effective trigger if the timer is activated (bit1:CNTE=1) in any operation mode.

4.2. 16-bit Timer Register : TMR (16bit TiMer Register)

The bit configuration of the 16-bit timer register is shown below.

This register can read the timer count value.

Always perform 16-bit access to this register.

■ TMR : Address Base_addr + 02_H (Access : Half-word)

	bit15	bit14	bit2	bit1	bit0
	TMR[15:0]					
Initial value	X	X	X	X	X
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX

[bit15 to bit0] TMR[15:0] (TiMeR) : 16-bit timer

This register can be read the counter value of the 16-bit timer. The initial value is undefined.

4.3. 16-bit Timer Reload Register A, 16-bit Timer Reload Register B : TMRLRA, TMRLRB(16bit TiMer ReLoad Register A/B)

The bit configuration of 16-bit timer reload register A and 16-bit timer reload register B is shown below.

This register sets the count initial value and other items.

Always perform 16-bit access to this register.

■ TMRLRA : Address Base_addr + 00_H (Access : Half-word)

	bit15	bit14	bit2	bit1	bit0
	TMRLRA[15:0]					
Initial value	X	X	X	X	X
Attribute	R/W	R/W	R/W	R/W	R/W

■ TMRLRB : Address Base_addr + 04_H (Access : Half-word)

	bit15	bit14	bit2	bit1	bit0
	TMRLRB[15:0]					
Initial value	X	X	X	X	X
Attribute	R,W	R,W	R,W	R,W	R,W

[bit15 to bit0] TMRLRA[15:0] (TiMer ReLoad Register A) : 16-bit reload setting register A

[bit15 to bit0] TMRLRB[15:0] (TiMer ReLoad Register B) : 16-bit reload setting register B

The TMRLRA register is where the count initial value is hold. The TMRLRA can be used in all mode with regardless of the bit15, bit14:MOD[1:0] setting in the TMCSR register.

The TMRLRB is to be used by the bit15, bit14:MOD[1:0] setting in the TMCSR register specified following:

Mode	MOD[1:0]	TMRLRB functions
Single mode	00	Not used
Dual mode	01	H width (when OUTL=0) counter value
Compare mode	10	Compare register (when H width setting is OUTL=0)
Capture mode	11	Capture register (TMR value upon retrigger input)

When using as a counter value, underflow is generated if 1 count is set when writing 0x0000 and 65,536 is set when writing 0xFFFF.

H width and L width of the timer output waveform (TOUT) are determined by the MOD[1:0] (bit15, bit14 of the TMCSR register), RELD (bit4 of the TMCSR register), and OUTL (bit5 of the TMCSR register) bit setting as well as the TMRLRA/B register value. H width and L width setting of the waveform(TOUT) to be outputted is shown in the table below.

MOD[1:0]	Mode	RELD	OUTL	TOUT output	
				H width	L width
00	Single	0	0	TMRLRA+1	-
			1	-	TMRLRA+1
		1	0	TMRLRA+1	
			1		
01	Dual	0	0	TMRLRB+1	TMRLRA+1
			1	TMRLRA+1	TMRLRB+1
		1	0	TMRLRB+1	TMRLRA+1
			1	TMRLRA+1	TMRLRB+1
10	Compare	0	0	See the explanation below.*	
			1		
		1	0		
			1		
11	Capture	0	0	TMRLRA+1	-
			1	-	TMRLRA+1
		1	0	TMRLRA+1	
			1		

*: H width and L width are as follows in the compare mode:

- When $TMRLRB < TMRLRA$
(OUTL=0) "L" width of $TMRLRA - TMRLRB + 1$, "H" width of $TMRLRB$
(OUTL=1) "H" width of $TMRLRA - TMRLRB + 1$, "L" width of $TMRLRB$
- When $TMRLRB = 0$
(OUTL=0) "L" output fixed
(OUTL=1) "H" output fixed
- When $TMRLRB > TMRLRA$
(OUTL=0) "H" output fixed
(OUTL=1) "L" output fixed
- When $TMRLRB = TMRLRA$
(OUTL=0) "L" output of 1 cycle, "H" width of $TMRLRB$
(OUTL=1) "H" output of 1 cycle, "L" width of $TMRLRB$

The following formula represents the TOUT output time (TOUT) when the register is used as the single mode and dual mode in the interval time mode:

$$TOUT = (\text{Setting value of this register} + 1) \times \text{count source cycle}$$

* : The formula described above is effective only in the interval timer mode.

5. Operation

This section explains the operation of the reload timer.

- 5.1. Setting
- 5.2. Operation Procedure
- 5.3. Operations of Each Counter
- 5.4. Cascade Input
- 5.5. Priority of Concurrent Operations

5.1. Setting

Setting of the reload timer is shown below.

The operation of this timer is set based on the "count source" (select in the TMCSR:CSL[2:0]) and counter operation ({TMCSR:MOD[1:0], TMCSR:RELD}).

5.1.1. Count Source

The count source of the reload timer is shown below.

Select decrement conditions of the down counter in the TMCSR:CSL[2:0].

Table 5-1 List of Count Source

CSL[2:0]	Count source	Operation mode
000	Division of the peripheral clock frequency by 2 (initial value)	Interval timer mode
001	Division of the peripheral clock frequency by 4	
010	Division of the peripheral clock frequency by 8	
011	Division of the peripheral clock frequency by 16	
100	Division of the peripheral clock frequency by 32	
101	Division of the peripheral clock frequency by 64	
110	Cascade mode (ch.0:TTRG0, ch.1:TOUT0, ch.2:TOUT1, ch.3:TOUT2)	Event counter mode
111	External event (TTRG input)	

5.1.2. Timer Underflow period

The timer underflow period is shown below.

Underflow is defined as counter down-counting from 0x0000. Set the time (period) to underflow occurrence since timer count operation start in the reload register (TMRLRA/TMRLRB). After loading to the reload register, underflow takes place if the count value reaches "reload register setting value + 1" count. The timer underflow period, TUF, in the interval timer mode can be represented as follows:

$$\text{TUF} = \text{Peripheral clock (PCLK) period} \times \text{prescaler division value (2-64)} \times (\text{Reload register value (TMRLRA/B)} + 1)$$

5.1.3. Trigger

The trigger of the reload timer is shown below.

The trigger consists of the following two types:

- Software trigger ... Generated when writing "1" to the TMCSR:TRG
- External pin trigger ... Inputted from the TTRG pin.

The TTRG pin is used as a count source in the event counter mode. Hence, a software trigger is always used. In the interval timer mode, settings are made in the TMCSR register.

5.1.4. Gate

The gate of the reload timer is shown below.

When configuring gate input (TMCSR:GATE =1) in the interval timer mode, it is possible to stop counter down counting using the TTRG external pin.

Table 5-2 TTRG Effective Level

TRGM[0]	TTRG Effective Level
0	TTRG pin "L" counted only during the input period (initial value)
1	TTRG pin "H" counted only during the input period

5.1.5. Counter Operation Selection

The counter operation selection is shown below.

Select the operation in case of counter underflow in the mode selection bits (bit15, bit14:MOD[1:0] of the TMCSR register) and the reload operation enabling bit (bit4:RELD of the TMCSR register). For details of operation in each mode, see the section of each counter operation.

Table 5-3 List of Counter Operation

MOD[1:0]	RELD	Operation in case of underflow	Counter operation name
00	0	Stop the counter with 0xFFFF	Single one-shot
	1	Reload TMRLRA	Single reload
01	0	(1) Reload TMRLRB (2) Stop the counter with 0xFFFF (See “5.3.3 Dual One-shot Operation”)	Dual one-shot
	1	Reload TMRLRA and TMRLRB in turns	Dual reload
10	0	Stop the counter with 0xFFFF	Compare one-shot
	1	Reload TMRLRA	Compare reload
11	0	Stop the counter with 0xFFFF	Capture one-shot
	1	Reload TMRLRA	Capture reload

5.1.6. TOUT Pin Level Setting

The TOUT Pin level setting is shown below.

Set pin output polarity using bit5:OUTL bit in the TMCSR register.

The relationships between events and the TOUT pin in each function are as follows:

A/B of the section of the UF (underflow) below indicates whether down counting underflow has occurred with a value when loading TMRLRA data or TMRLRB data. CMP (compare-match) shows the timing of down counting from TMRLRB = TMR.

Figure 5-1 TOUT Output Change in Each Event (1 / 3)

Function name	OUTL	Initial value	Trigger	Counting in progress	UF	UF	UF
Single one-shot function	0				A	Trigger wait state	
	1						
Single reload function	0				A	A	A
	1						
Dual one-shot function	0				A	B	Trigger wait state
	1						
Dual reload function	0				A	B	A
	1						
Capture one-shot function	0				A	Trigger wait state	
	1						
Capture reload function	0				A	A	A
	1						

Figure 5-2 TOUT Output Change in Each Event (2 / 3)

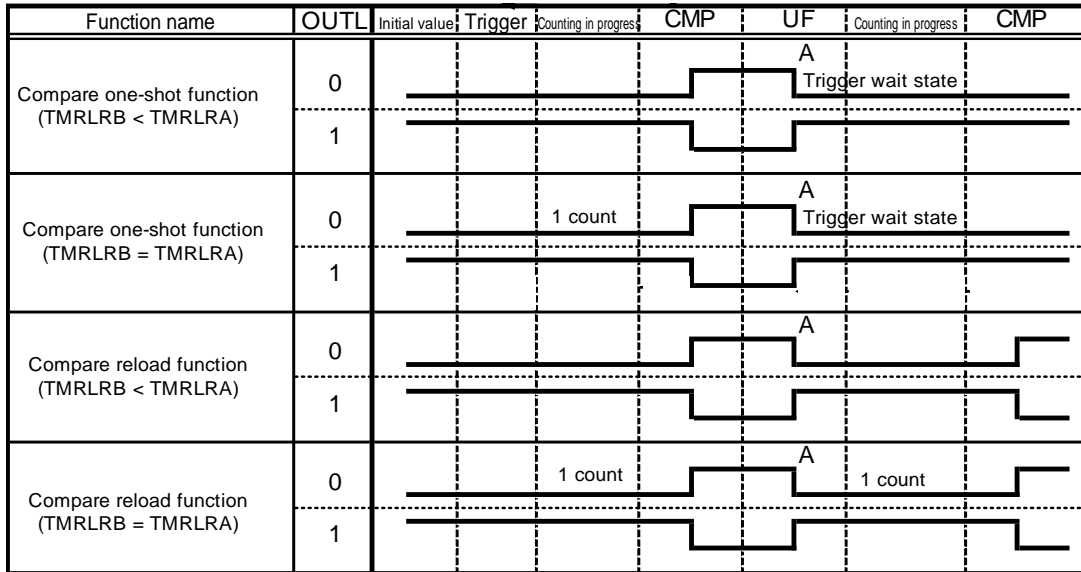
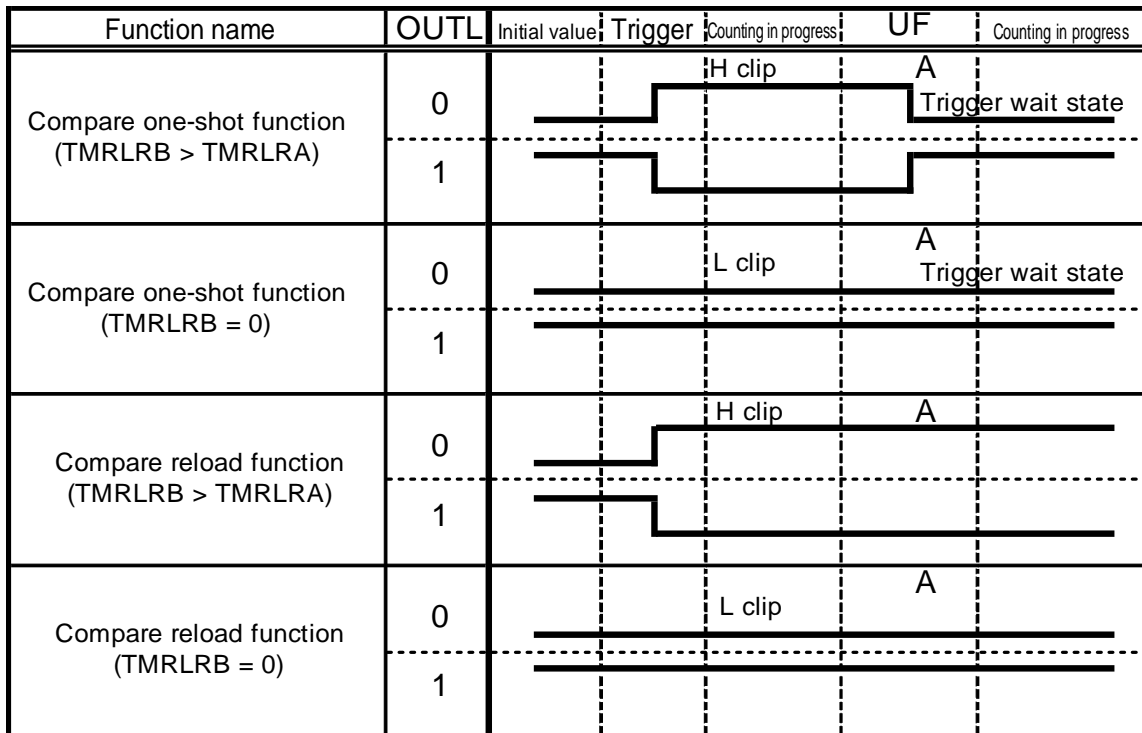


Figure 5-3 TOUT Output Change in Each Event (3 / 3)



5.2. Operation Procedure

Operation procedures are shown.

- 5.2.1. Activation
- 5.2.2. Retrigger
- 5.2.3. Underflow/Reload
- 5.2.4. Generation of Interrupt Requests
- 5.2.5. Concurrent Operation of Register Write and a Timer Activation

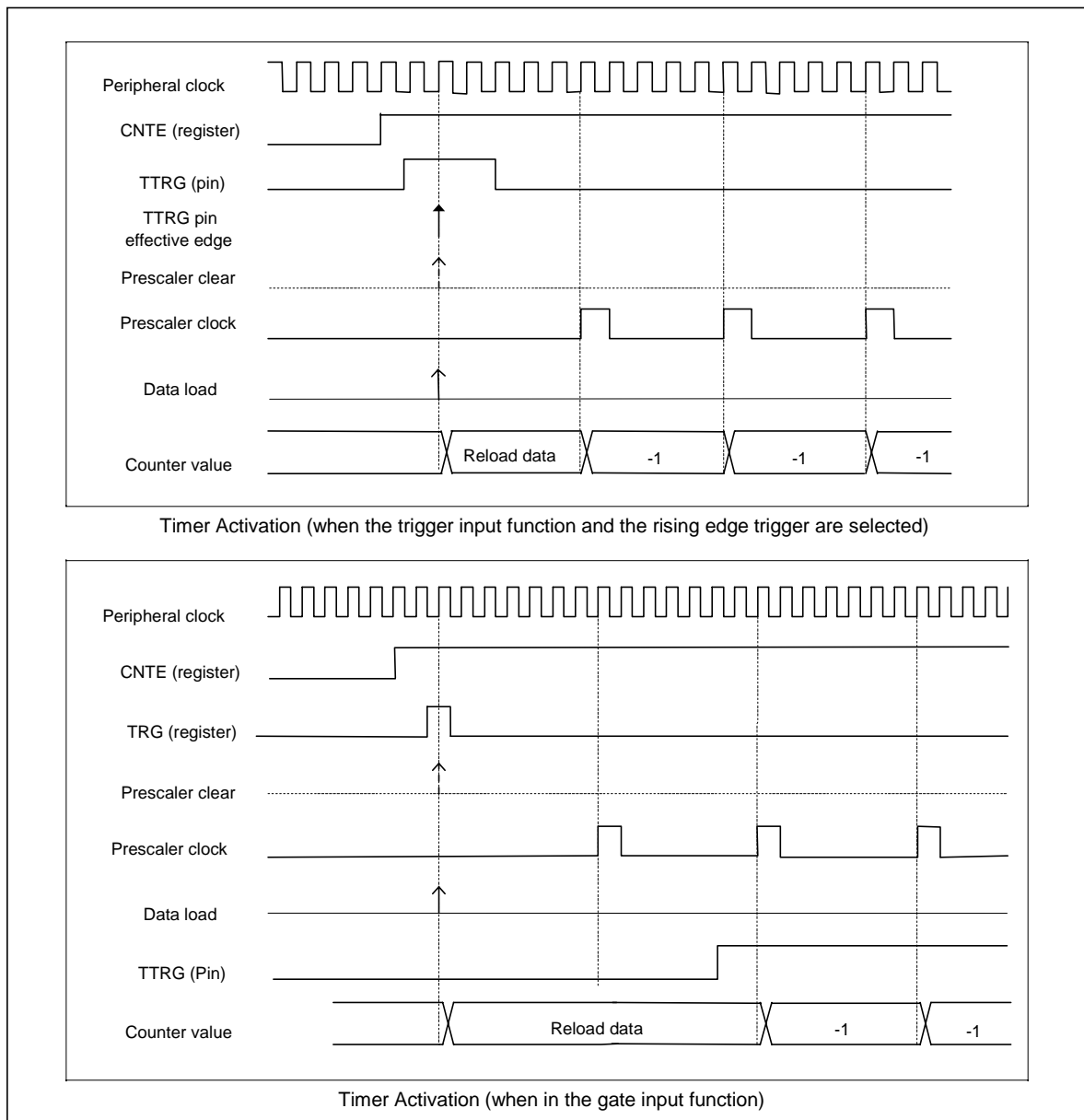
5.2.1. Activation

Activation is shown below.

Writing "1" into the bit1:CNTE bit of the TMCSR register changes the counter state to activation trigger waiting.

- TTRG input during trigger input functioning
If writing "1" to the bit0:TRG bit of the TMCSR register or inputting external trigger through TTRG input takes place during activation trigger waiting, the prescaler will be cleared and the timer will load a value from the reload register to start down count operation. For TTRG, input pulse of $2 \times T$ (T indicates the peripheral clock (PCLK) cycle) or more.
- TTRG input during gate input functioning
If writing "1" to the bit0:TRG bit of the TMCSR register during activation trigger waiting, the prescaler will be cleared and the timer will load a value from the reload register and change the state to effective input polarity waiting. If there is any gate input with effective polarity from TTRG input in the effective input polarity waiting, the timer initiates down count operation. For TTRG, input pulse of $2 \times T$ (T indicates the peripheral clock (PCLK) cycle) or more.

Figure 5-4 Timer Activation



5.2.2. Retrigger

The retrigger is explained.

The trigger which is generated during timer counting is called "retrigger". In this case, the following actions are taken:

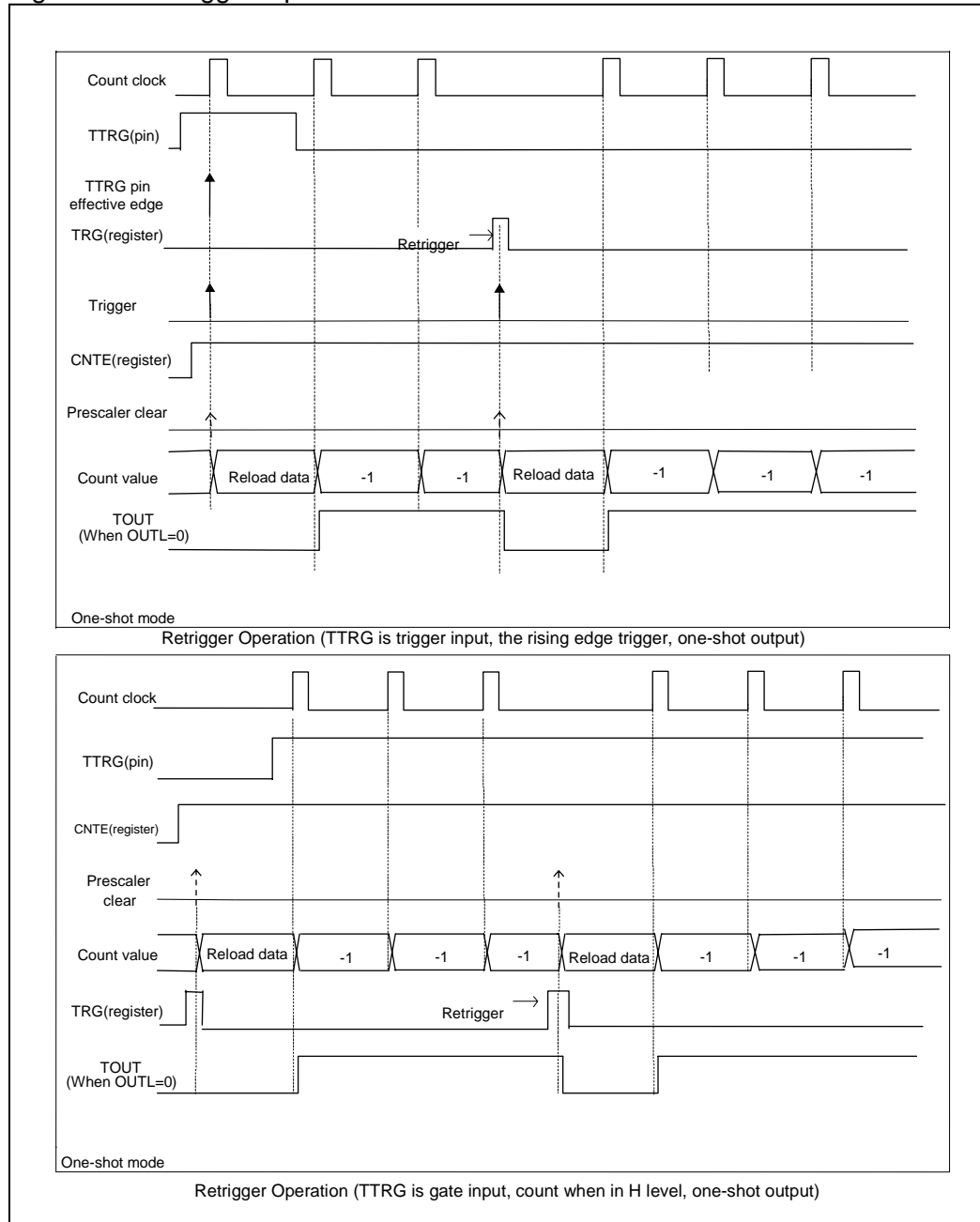
1. Initialize TOUT
2. Load the reload register value to the counter
3. Clear the 6-bit prescaler
4. Continue counting

Only in the capture mode, retrigger generation transfers a value being counted to the TMRLRB to set the EF bit of the TMCSR register.

Note:

TOUT is not initialized in the one shot mode at retrigger.

Figure 5-5 Retrigger Operation



5.2.3. Underflow/Reload

Underflow/reload is shown below.

Underflow is defined as the timer down-counting from 0x0000. When underflow occurs, the bit2:UF bit of the TMCSR register is set. Underflow takes place in the timer if the count value reaches "reload register setting value + 1" count.

5.2.4. Generation of Interrupt Requests

Generation of interrupt requests is shown below.

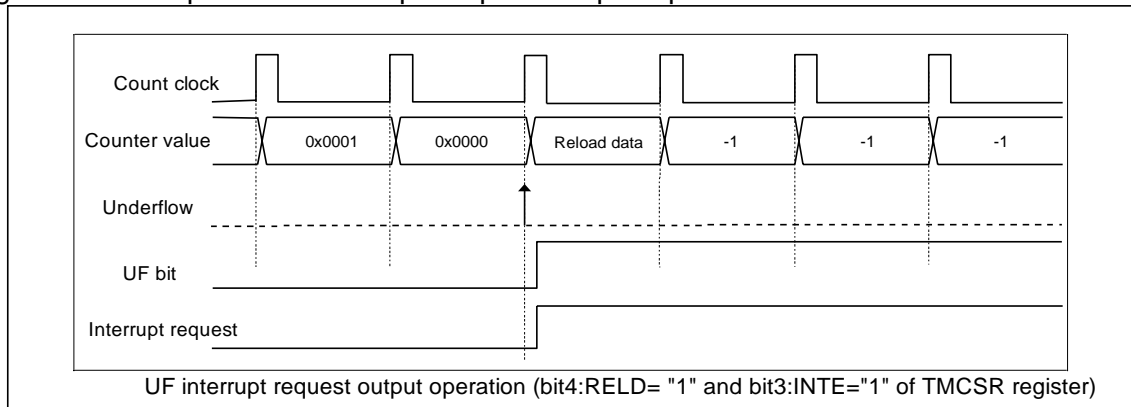
When bit3:INTE bit of the TMCSR register is "1", if bit2:UF bit/bit7:EF bit are set, an interrupt request is generated. In interval timer mode, the UF bit and the EF bit will be set under the following conditions.

- UF bit is set: A counter underflow occurred
- EF bit is set: A capture input occurred in capture mode

When a set of bit2:UF bit of the TMCSR register and a clear of the UF bit by writing "0" occurred concurrently, writing "0" to the UF bit will be invalid and the UF bit will be set. When a set of bit7:EF bit and a clear of the EF bit by writing "0" occurred concurrently, writing "0" to the EF bit will be invalid and the EF bit will be set.

The following is the example of generation of interrupt requests.

Figure 5-6 Example of UF Interrupt Request Output Operation



5.2.5. Concurrent Operation of Register Write and a Timer Activation

The concurrent operation of register write and a timer activation is shown below.

The following table shows the operation when a register write by a user and the timer operation occurred simultaneously.

Table 5-4 Concurrent Operation

Writing to register	Operation of timer	Operation to execute
A clear of the UF bit by writing "0"	Setting of the UF bit	Setting of the UF bit (Writing "0" is ignored)
A clear of the EF bit by writing "0"	Setting of the EF bit	Setting of the EF bit (Writing "0" is ignored)
Writing to the reload register	Loading of timer by retrigger	Reloading old data (The written value will be loaded next time)

5.3. Operations of Each Counter

Operations of each counter are shown.

- 5.3.1. Single One-shot Operation
- 5.3.2. Single Reload Operation
- 5.3.3. Dual One-shot Operation
- 5.3.4. Dual Reload Operation
- 5.3.5. Compare One-shot Operation
- 5.3.6. Compare Reload Operation
- 5.3.7. Capture Mode

5.3.1. Single One-shot Operation

The single one-shot operation is shown below.

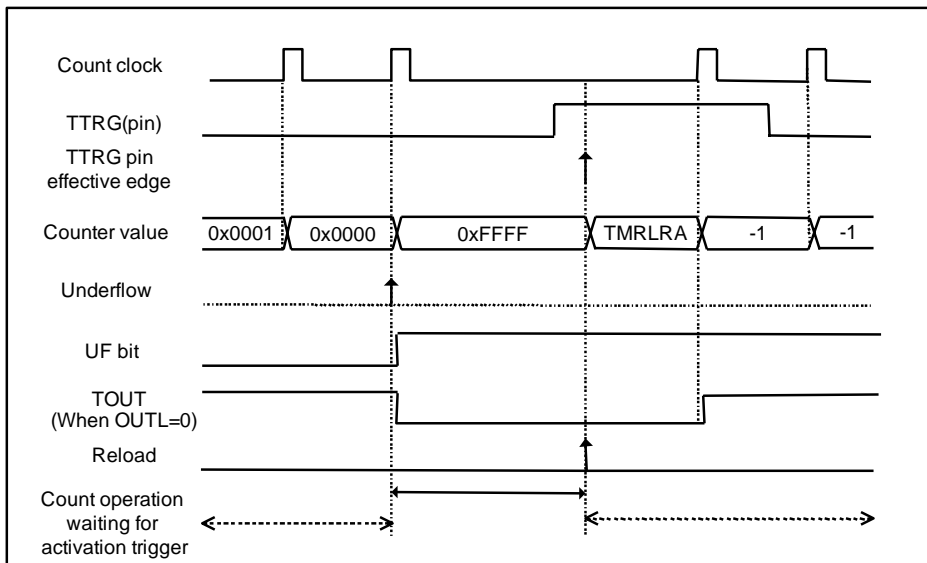
When bit15, bit14:MOD[1:0]=00 and bit4:RELD of the TMCSR register =0, the single one-shot operation will be performed in which the timer stops with 0xFFFF by an occurrence of an underflow.

In the single one-shot configuration, if an underflow occurs, the following operation will be performed.

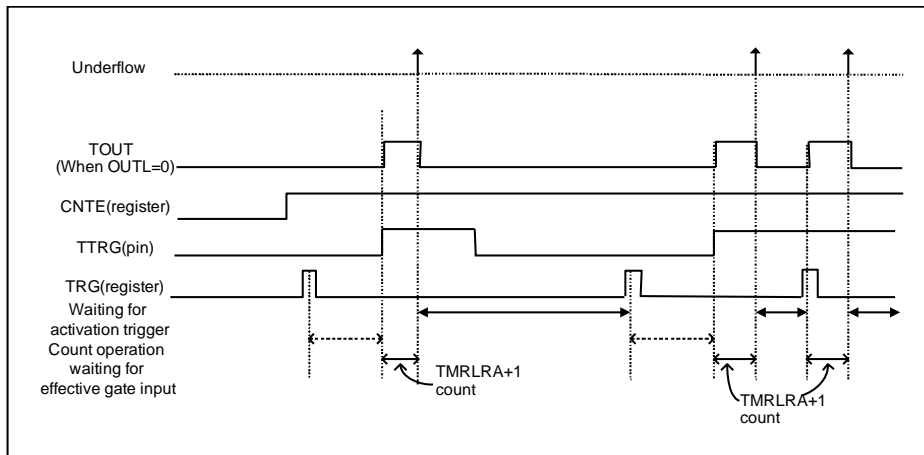
- Sets the UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Stops the count with 0xFFFF.
- Initializes TOUT output.
- Timer is waiting for a trigger.

For the single one-shot timer, TMRLRA turns to the initial value of the counter when a reload took place. TMRLRB is not used.

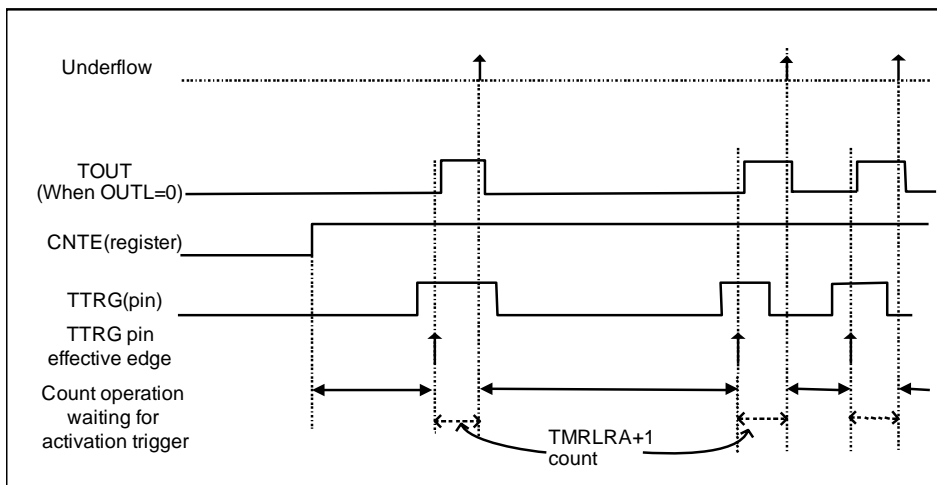
Figure 5-7 Single One-shot Operation



Details of Underflow operation
(When the trigger input and rising edge trigger are selected)



Single one-shot timer
(GATE="0": When the trigger input and rising edge trigger are selected)



Single one-shot timer (GATE="1": gate input, TRGM:H input interval count)

5.3.2. Single Reload Operation

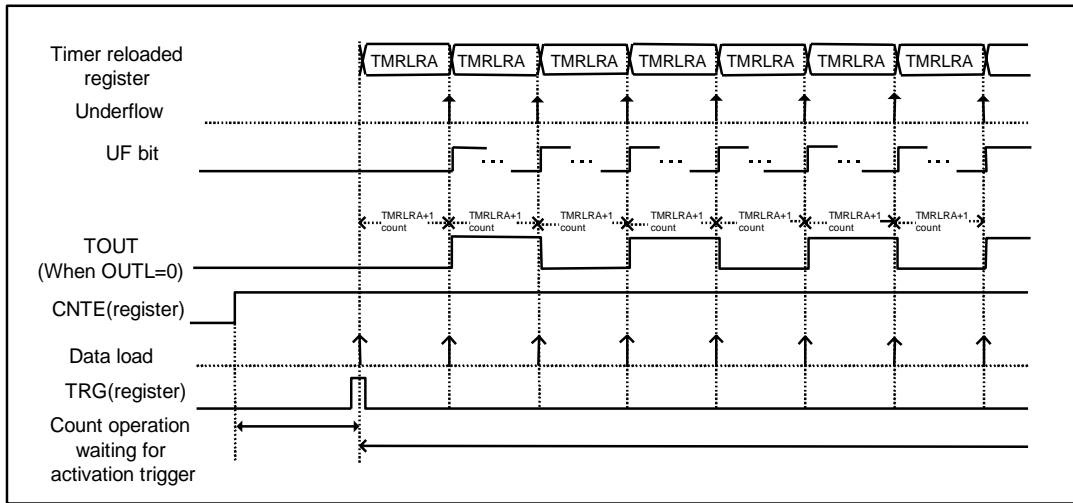
The single reload operation is shown below.

When bit15, bit14:MOD[1:0] of the TMCSR register =00, and bit4:RELD of the TMCSR register =1, the single reload operation will be performed.

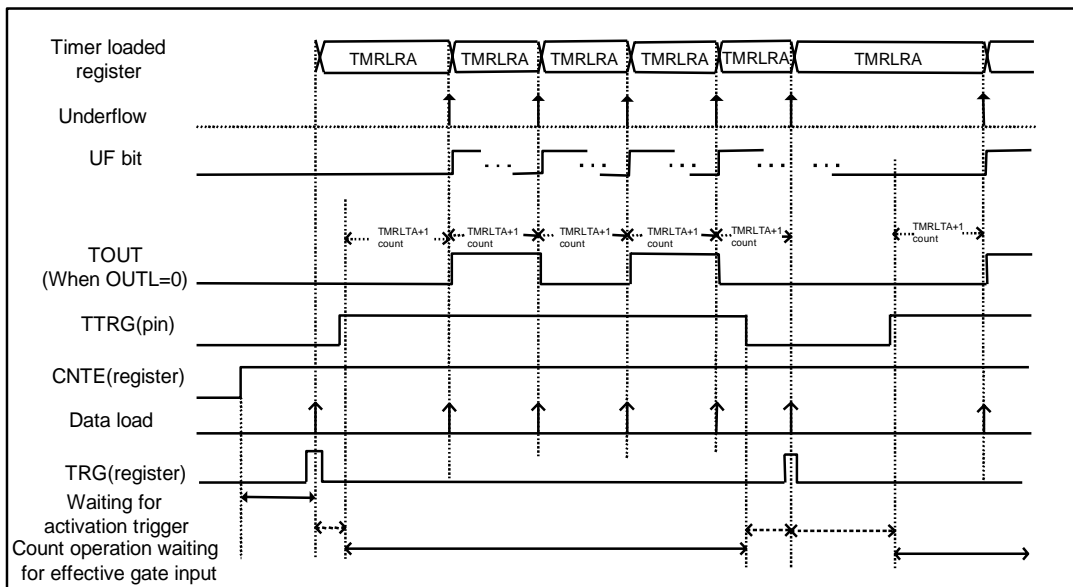
In single reload operation, a value will be loaded from TMRLRA to the timer by trigger input, a down count (decrementing the count) will start. When an underflow occurs, the value is reloaded from TMRLRA again and the down count operation continues. The value of TMRLRA represents the time the timer will reload. The TMRLRB register is not used. In single reload configuration, if an underflow occurs, the following operation will be performed.

- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Loads TMRLRA register onto the counter.
- Inverts TOUT output.
- Continues decrementing count.

Figure 5-8 Single Reload Operation



Single reload function (GATE="0": trigger input)



Single reload function (GATE="1": gate input, TRGM: H input interval count)

5.3.3. Dual One-shot Operation

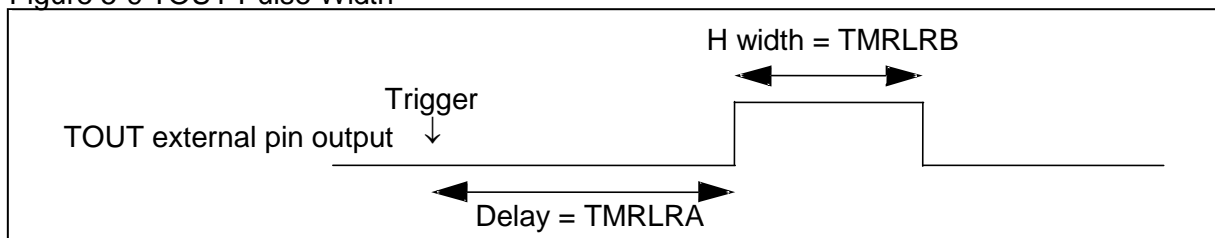
The dual one-shot operation is shown below.

When bit15, bit14:MOD[1:0] of the TMCSR register =01, and bit4:RELD of the TMCSR register =0, the timer performs the dual one-shot operation. This can be used as a one-shot PPG.

In dual one-shot operation, values are loaded into the counter one by one in the order of TMRLRA then TMRLRB, the loaded values decrements the counter for each load. The counter will stop by the second underflow.

When bit5:OUTL=0 of the TMCSR register, the value of TMRLRA represents the time interval between a timer activation (TOUT output is in L level) to a toggling of the TOUT output to "H", and the value of TMRLRB represents the time interval of H width of the TOUT output.

Figure 5-9 TOUT Pulse Width



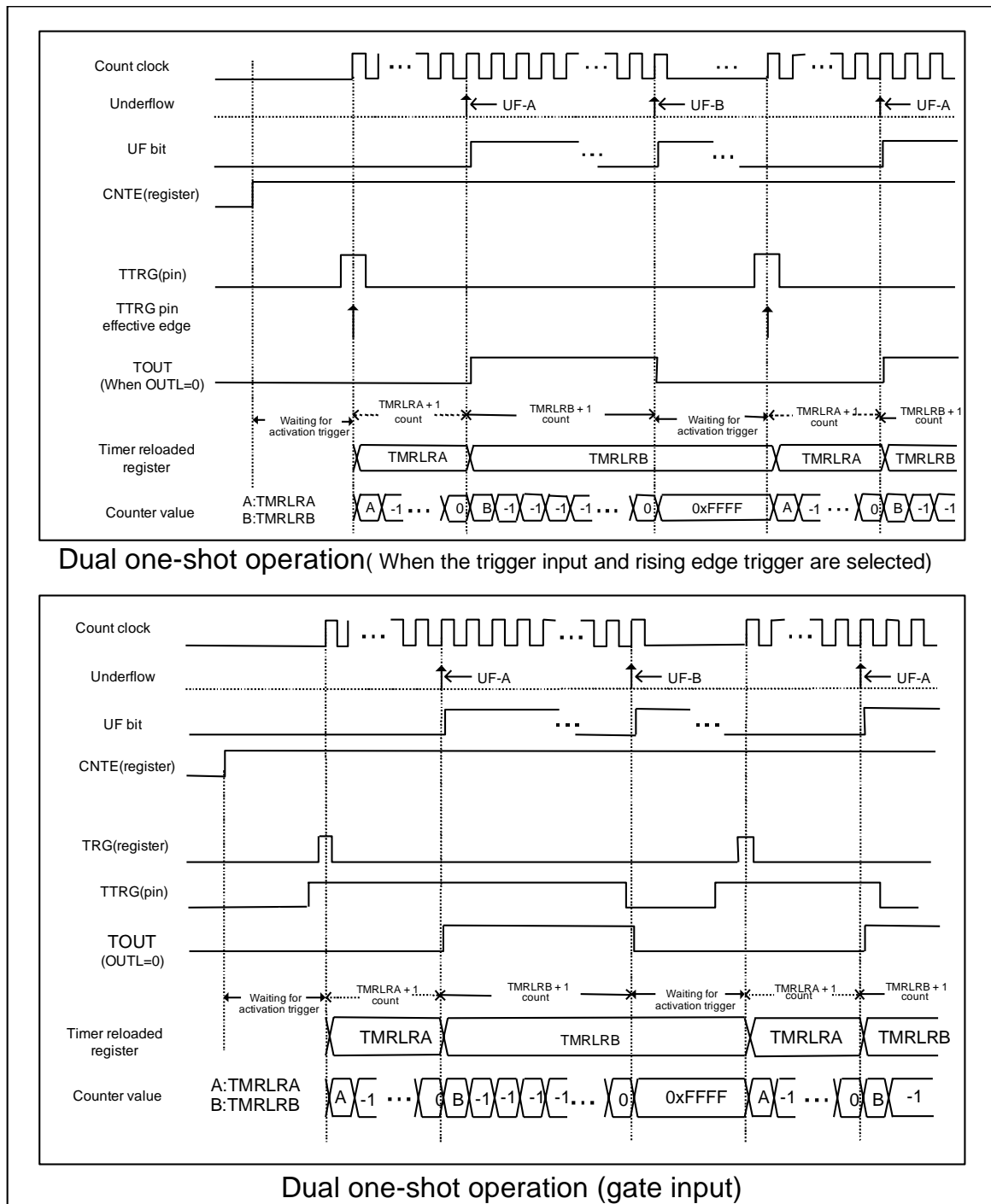
When the first underflow occurs (UF-A), the following operation will take place.

- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Loads TMRLRB to the counter.
- Inverts TOUT output.
- Starts a down count from TMRLRB.

When the second underflow (UF-B) occurs, the following operation will take place.

- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Stops the count with 0xFFFF.
- Initializes TOUT output.
- Timer is waiting for an activation trigger.

Figure 5-10 Dual One-shot Operation



5.3.4. Dual Reload Operation

The dual one-shot operation is shown below.

When bit15, bit14:MOD[1:0] of the TMCSR register =01, and bit4:RELD of the TMCSR register =1, the timer performs the dual reload operation.

In dual reload operation, the values of TMRLRA and TMRLRB are loaded alternatively and decrement the counters for each load, that is, loads TMRLRA onto the counter and decrements the counter, and if an underflow occurs, loads TMRLRB onto the counter and decrement the counter, and if an another underflow occurs, loads TMRLRA onto the counter and decrements the counter, and so on.

When bit5:OUTL=0 of the TMCSR register, the value of TMRLRA represents the time interval between a timer activation (TOUT output is in L level) to a toggling of the TOUT output to "H", and the value of TMRLRB represents the time interval of H width of the TOUT output.

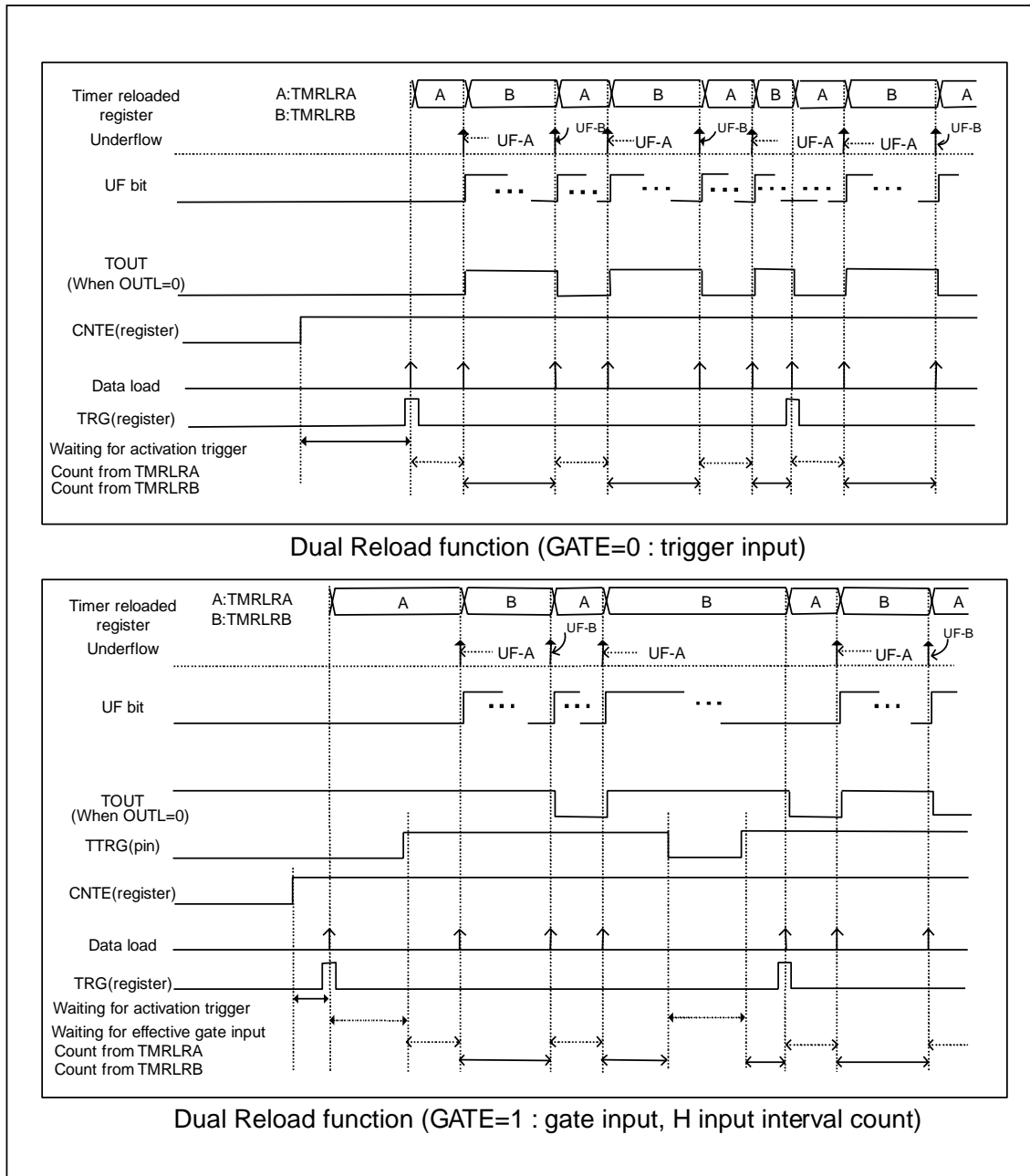
If an underflow (UF-A) occurs at the down count after loading a value from the TMRLRA, the following operation will be performed.

- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Loads TMRLRB to the counter.
- Inverts TOUT output.
- Starts a down count from TMRLRB.

If an underflow (UF-B) occurs at the down count after loading a value from the TMRLRB, the following operation will be performed.

- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Loads TMRLRA to the counter.
- Inverts TOUT output.
- Starts a down count from TMRLRA.

Figure 5-11 Dual Reload Operation



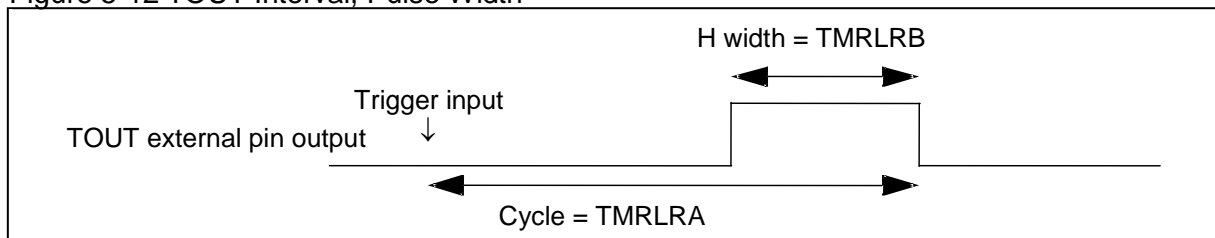
5.3.5. Compare One-shot Operation

The compare one-shot operation is shown below.

When bit15, bit14:MOD[1:0] of the TMCSR register =10, and bit4:RELD of the TMCSR register =0, the compare one-shot operation in which the counter value (TMR) and the value of TMRLRB register are compared for each down count will be performed. After accepting a trigger, the value of the TMRLRA register is loaded and the down count starts. When decrementing the count from the value of a compare matched (TMR = TMRLRB), the TOUT output will be inverted. When an underflow occurs, count operations stopped, TOUT output is initialized, and the timer go into the activation trigger wait state.

The value of TMRLRA indicates the time interval between the activation of a timer and the end of it and the value of TMRLRB indicates the counter value when an output of the H width of TOUT output starts. When OUTL="0" and $TMR < TMRLRB$, the TOUT output will become the "H level".

Figure 5-12 TOUT Interval, Pulse Width



From the start of a down count to $TMR = TMRLRB$ (while TMR is greater than or equal to TMRLRB), the following operation will be performed.

- TOUT output continues to hold the initial value.
- The timer continues to count.
- If a down count from $TMR = TMRLRB$ occurs, the following operation will be performed.
- Inverts TOUT output.
- The timer continues to count.

(For the compare operation in interval timer mode, bit7:EF bit of TMCSR register will not be set.)

If an underflow occurs, the following operation will be performed.

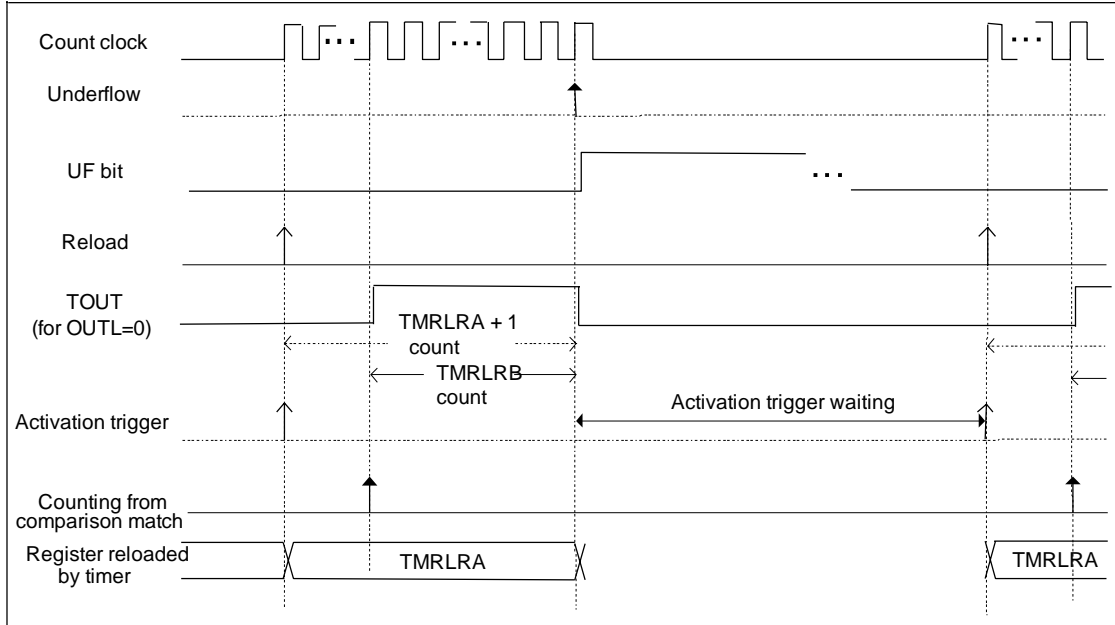
- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Initializes TOUT output.
- The timer stops with 0xFFFF.
- Timer is waiting for an activation trigger.

The operation of the compare function changes depending on the setting relation between TMRLRA and TMRLRB.

Figure 5-13 Compare One-shot Operation (1 / 2)

• Sets $TMRLRB < TMRLRA$

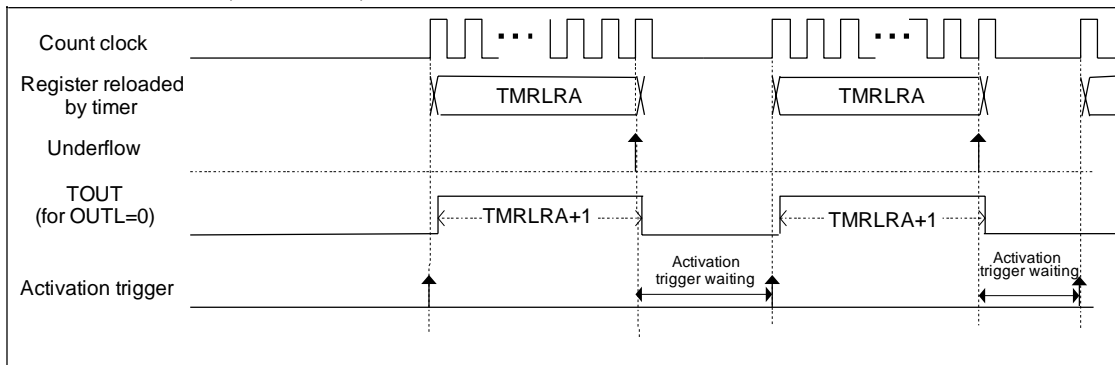
When the register relation is as described above, the TOUT output is the L level until TMR and TMRLRB match after loading to the timer. When down counting from the comparison match ($TMR = TMRLRB$), the level is H until the TOUT output is inverted and an underflow occurs. When an underflow occurs the TOUT output will be initialized. Then, the timer will stop counting operation and turn into the activation trigger waiting state (for $OUTL="0"$).



Compare one-shot function ($TMRLRB < TMRLRA$)

• Sets $TMRLRB > TMRLRA$

When the register relation is as described above, the TOUT output is the H level between an activation trigger generation and an underflow occurrence because TMR is already smaller than $TMRLRB$ after loading to the timer. When an underflow occurs, the timer will turn into the activation trigger waiting state and the TOUT output will be the L level (for $OUTL="0"$).

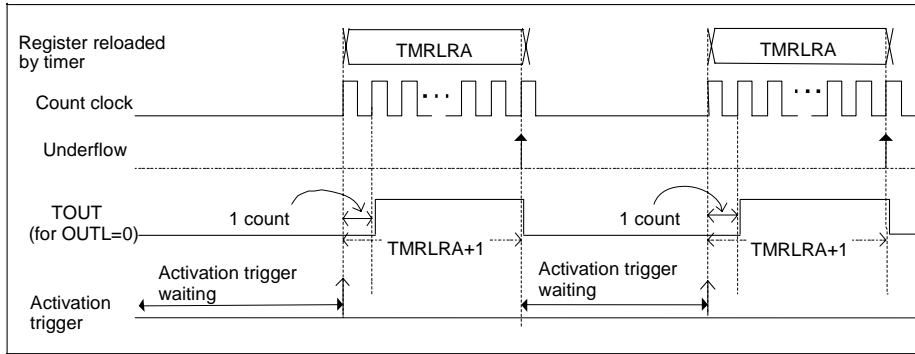


Compare one-shot function ($TMRLRB > TMRLRA$)

Figure 5-14 Compare One-shot Operation (2 / 2)

- Sets $TMRLRB = TMRLRA$

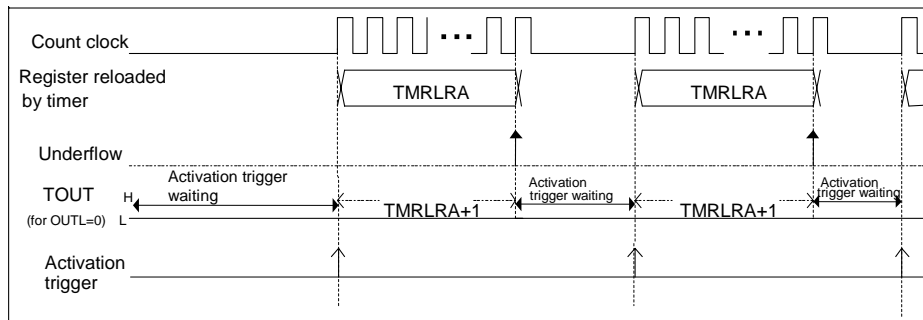
When the register relation is as described above, $TMRLRB$ will become bigger than TMR after 1 count. Thus the TOUT output is the L level for 1 down count and then the H level until an underflow occurs. When an underflow occurs, the timer will turn into the activation trigger waiting state and the TOUT output will be the L level (for $OUTL="0"$).



Compare one-shot function ($TMRLRB=TMRLRA$)

- Sets $TMRLRB = 0$

When the register relation is as described above, the TOUT output is the L level between down count start and an underflow occurrence because $TMRLRB$ is always smaller than TMR . The level will remain to be L even when an underflow occurs (for $OUTL="0"$).



Compare one-shot function ($TMRLRB="0"$)

5.3.6. Compare Reload Operation

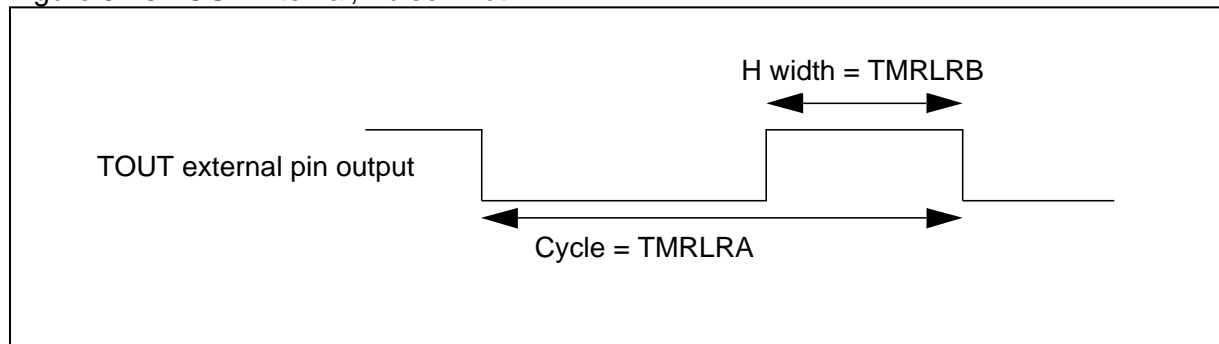
The compare reload operation is shown below.

When bit15, bit14:MOD[1:0] of the TMCSR register =10, and bit4:RELD of the TMCSR register =1, the timer compares a counter value (TMR) to the value of TMRLRB for each down count and if a compare matched (TMR = TMRLRB) is detected, a down count starts and the TOUT output will be inverted. When an underflow occurs, the compare reload operation will be performed, in which a value is loaded from TMRLRA again and the down count operation starts. A load onto the counter starts from TMRLRA.

The value of TMRLRA indicates the counter interval from a timer activation until a reload and the value of TMRLRB indicates the "H level width" after the TOUT output inverted from "L level output" to "H level output".

When $TMR + 1 = TMRLRB$, TOUT output will invert to the "H level" (when OUTL=0).

Figure 5-15 TOUT Interval, Pulse Width



From the start of a down count to $TMR = TMRLRB$ (while TMR is greater than or equal to TMRLRB), the following operation will be performed.

- TOUT output continues to hold the initial value.
- Count continues

When a down count starts from $TMR = TMRLRB$, the following operation will be performed.

- Inverts TOUT output.
- Count continues.

(For the compare operation in interval timer mode, bit7:EF bit of TMCSR register will not be set.)

If an underflow occurs, the following operation will be performed.

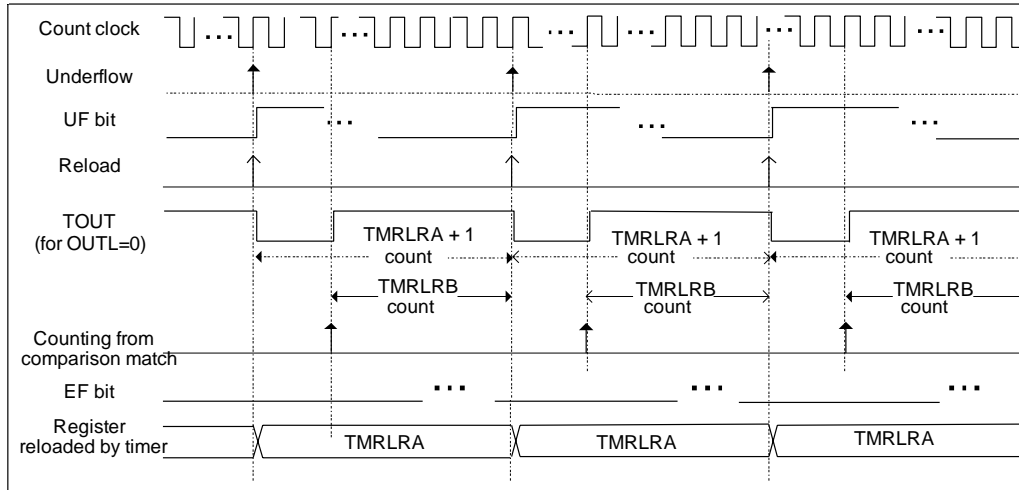
- Sets bit2:UF bit of the TMCSR register.
- When interrupts are enabled (bit3:INTE=1 of TMCSR register), an interrupt occurs.
- Initializes TOUT output.
- Reloads a value from TMRLRA.
- The timer continues to count.

The operation of a compare feature depends on the relationship between TMRLRA and TMRLRB.

Figure 5-16 Compare Reload Operation (1 / 2)

- Sets $TMRLRB < TMRLRA$

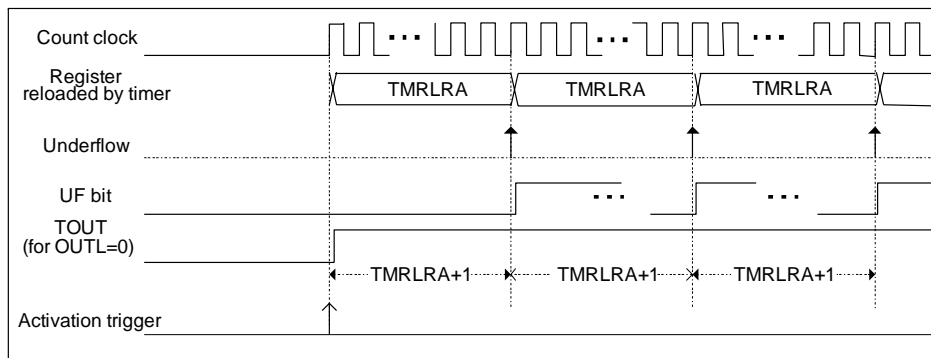
When the register relation is as described above, the TOUT output is the L level until TMR and TMRLRB match after loading to the timer. When down counting from the comparison match ($TMR=TMRLRB$), the level is H until the TOUT output is inverted and an underflow occurs. When an underflow occurs the TOUT output will be initialized. When an under flow occurs, the timer will reload from TMRLRA and continue counting operation (for $OUTL="0"$).



Compare reload function ($TMRLRB < TMRLRA$) trigger input

- Sets $TMRLRB > TMRLRA$

When the register relation is as described above, the TOUT output is the H level after an activation trigger is generated and an underflow occurs because TMR is always smaller than $TMRLRB$. The level will remain to be H even when an underflow occurs. When an underflow occurs, the timer will load from $TMRLRA$ and continue counting operation (for $OUTL="0"$).

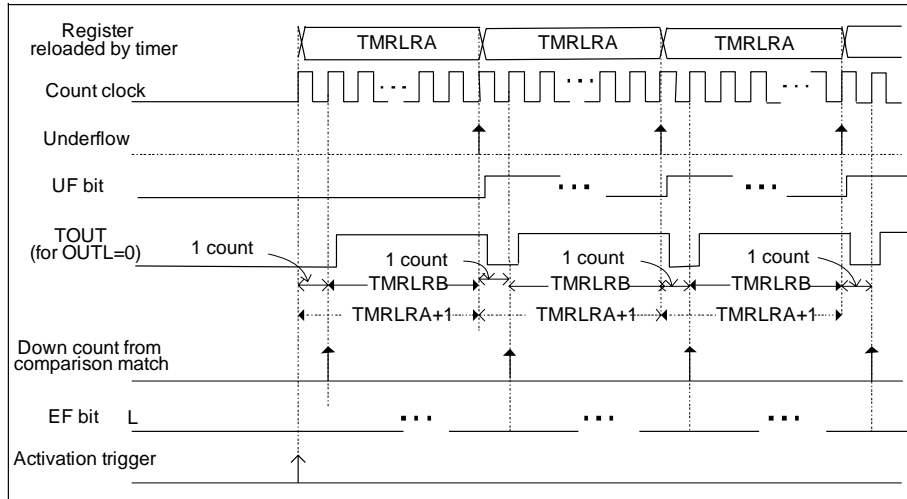


Compare reload function ($TMRLRB > TMRLRA$) trigger input

Figure 5-17 Compare Reload Operation (2 / 2)

- Sets TMRLRB = TMRLRA

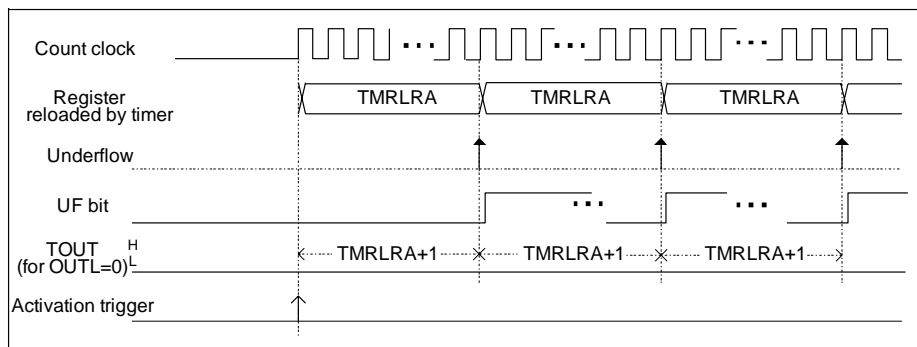
When the register relation is as described above, 1 count up after loading to the timer makes TMRLRB become bigger than TMR. Thus the TOUT output is the L level for 1 down count and then the H level until an underflow occurs. When an underflow occurs, the timer will reload from TMRLRA and continue counting operation. The TOUT output will remain to be the L level. (For OUTL=0)



Compare reload function (TMRLRB = TMRLRA) trigger input

- Sets TMRLRB = 0

When the register relation is as described above, the TOUT output is the L level between down count start and an underflow occurrence after loading to the timer because TMRLRB is smaller than TMR. The level will remain to be L even when an underflow occurs.



Compare reload function (TMRLRB = "0") trigger input

5.3.7. Capture Mode

The capture mode is shown below.

When bit15, bit14:MOD[1:0] of the TMCSR register =11, the timer will perform capture operation. When a retrigger occurs, TMRLRB register captures the TMR value and sets bit7:EF of the TMCSR register.

When you use TTRG input as the gate input (when bit8:GATE=1 of the TMCSR register), generate a retrigger by bit0:TRG of the TMCSR register.

In a mode other than trigger, a capture will not be performed at a retrigger. The EF bit interrupt will also not be generated.

The timer operation and the TOUT output will be the same for the single one-shot feature and the single reload feature.

Note:

TOUT is not initialized in the one shot mode at retrigger.

Figure 5-18 Operation of Capture

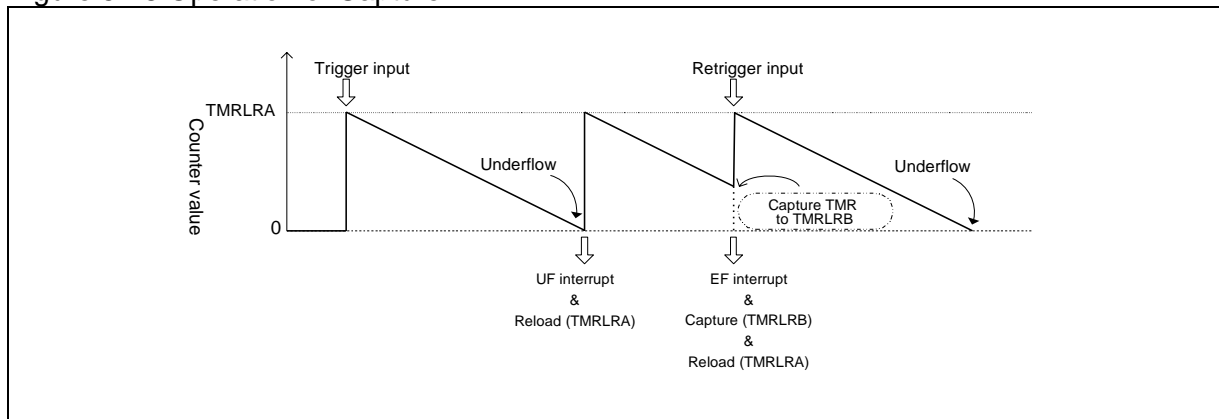


Figure 5-19 Flowchart of Trigger Input Features in Interval Timer Mode

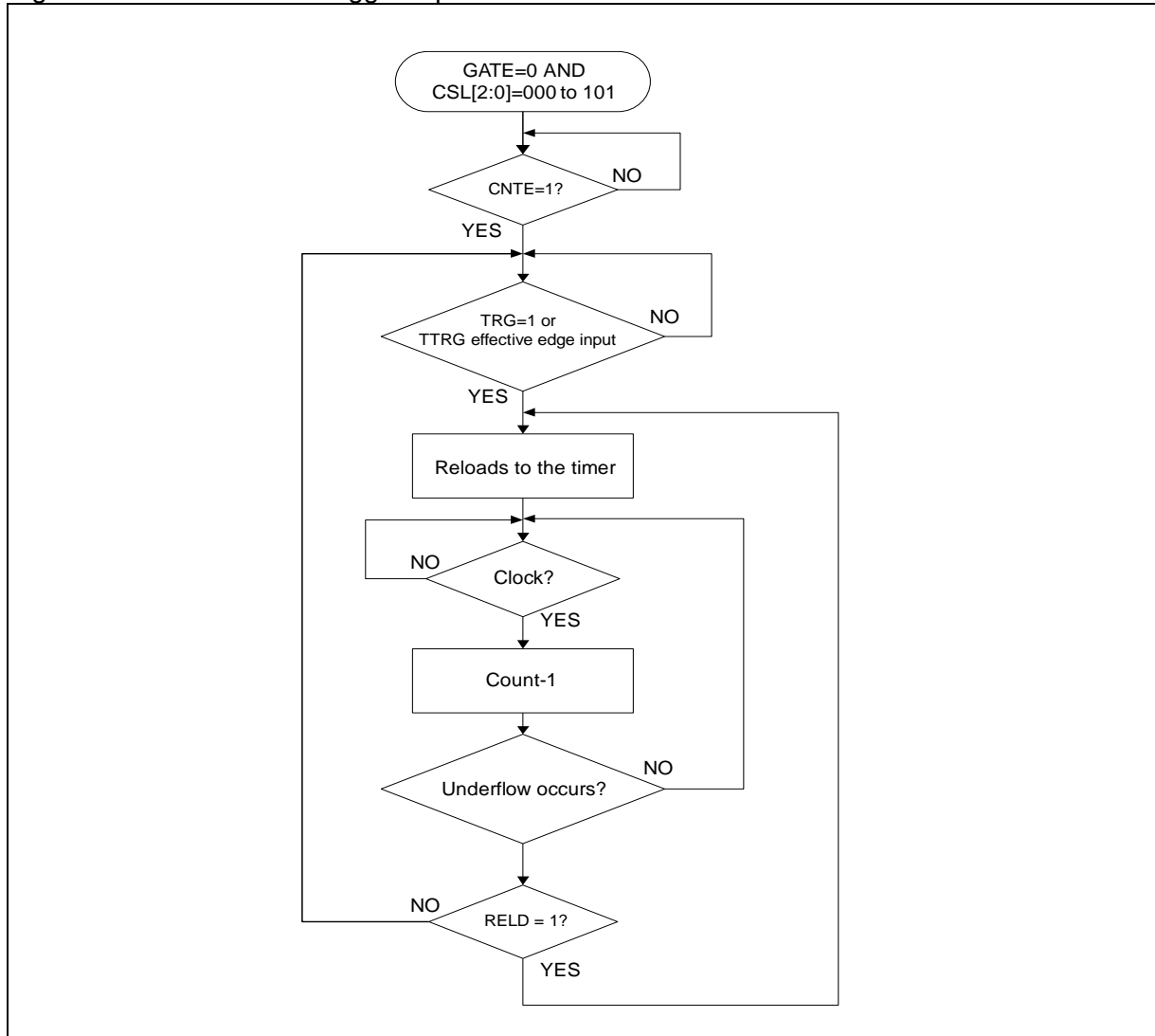
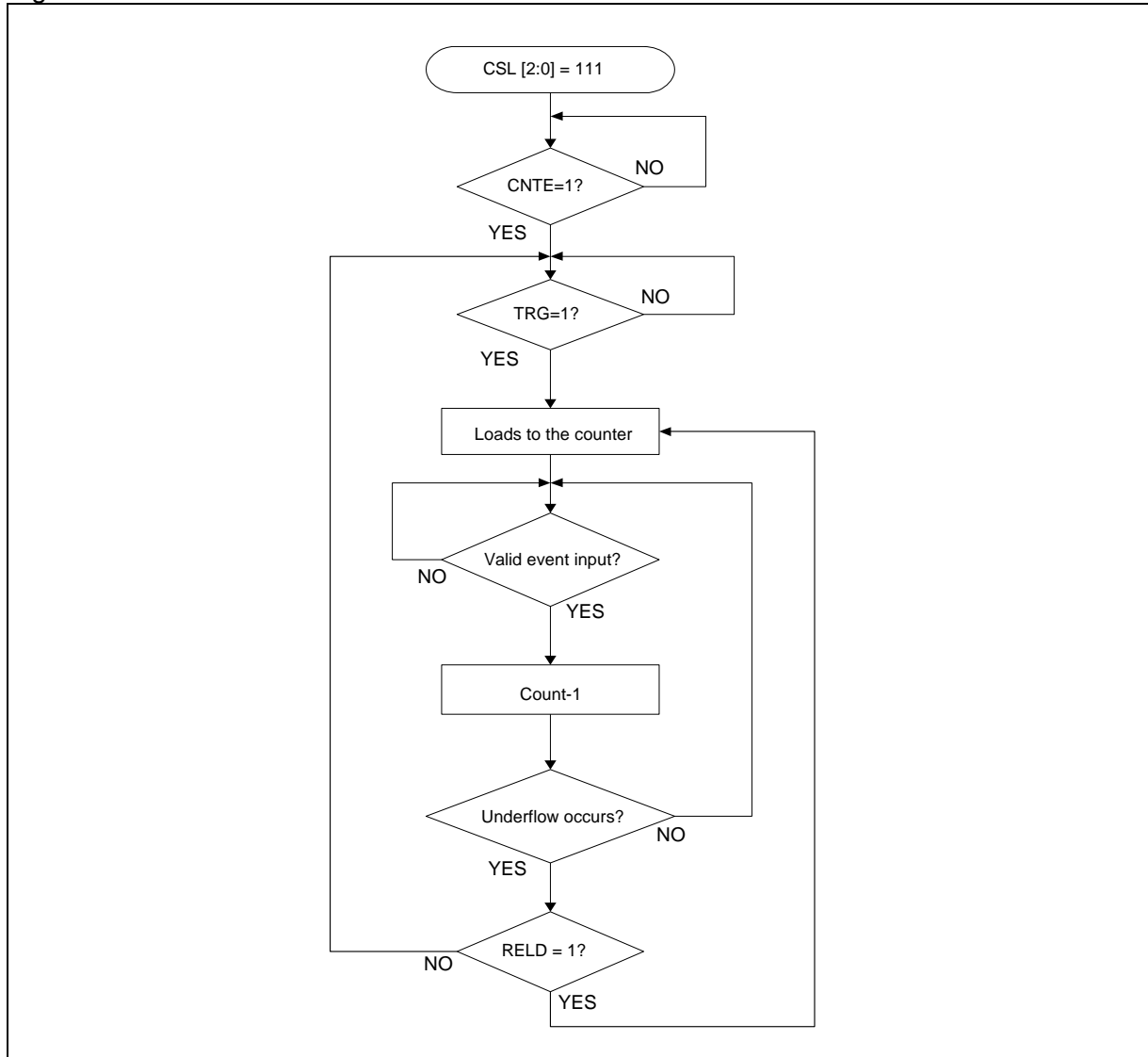


Figure 5-20 Flowchart in Event Counter Mode

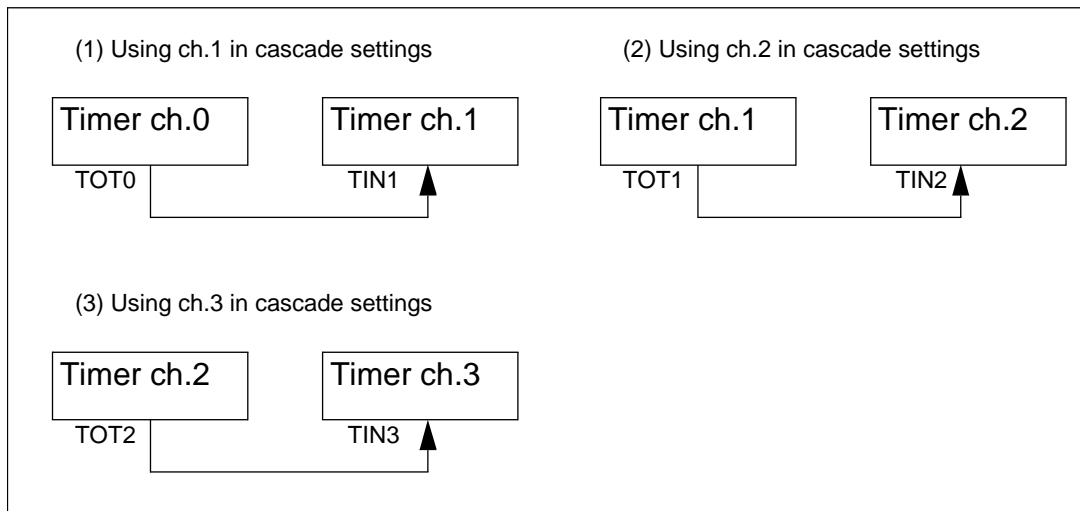


5.4. Cascade Input

Cascade input is shown below.

When you select cascade input (bit11 to bit9:CSL[2:0]=110 of TMCSR register), you can use the timer's ch.0 output (TOUT0) for the input for ch.1 (TTRG1), ch.1 output (TOUT1) for the input for ch.2 (TTRG2), and ch.2 output (TOUT2) for the input for ch.3 (TTRG3).

Figure 5-21 Timer Input/Output in Cascade Input Configuration



5.5. Priority of Concurrent Operations

The priority of concurrent operations is shown below.

When two events to decide the timer operation occur simultaneously, the priority of deciding the operating state is indicated.

1. Writing to register
2. Trigger input
3. Underflow
4. Clock input

When a set of each flag by the timer operation and a clear of a flag by register write occur concurrently, the priority of deciding the operation is indicated.

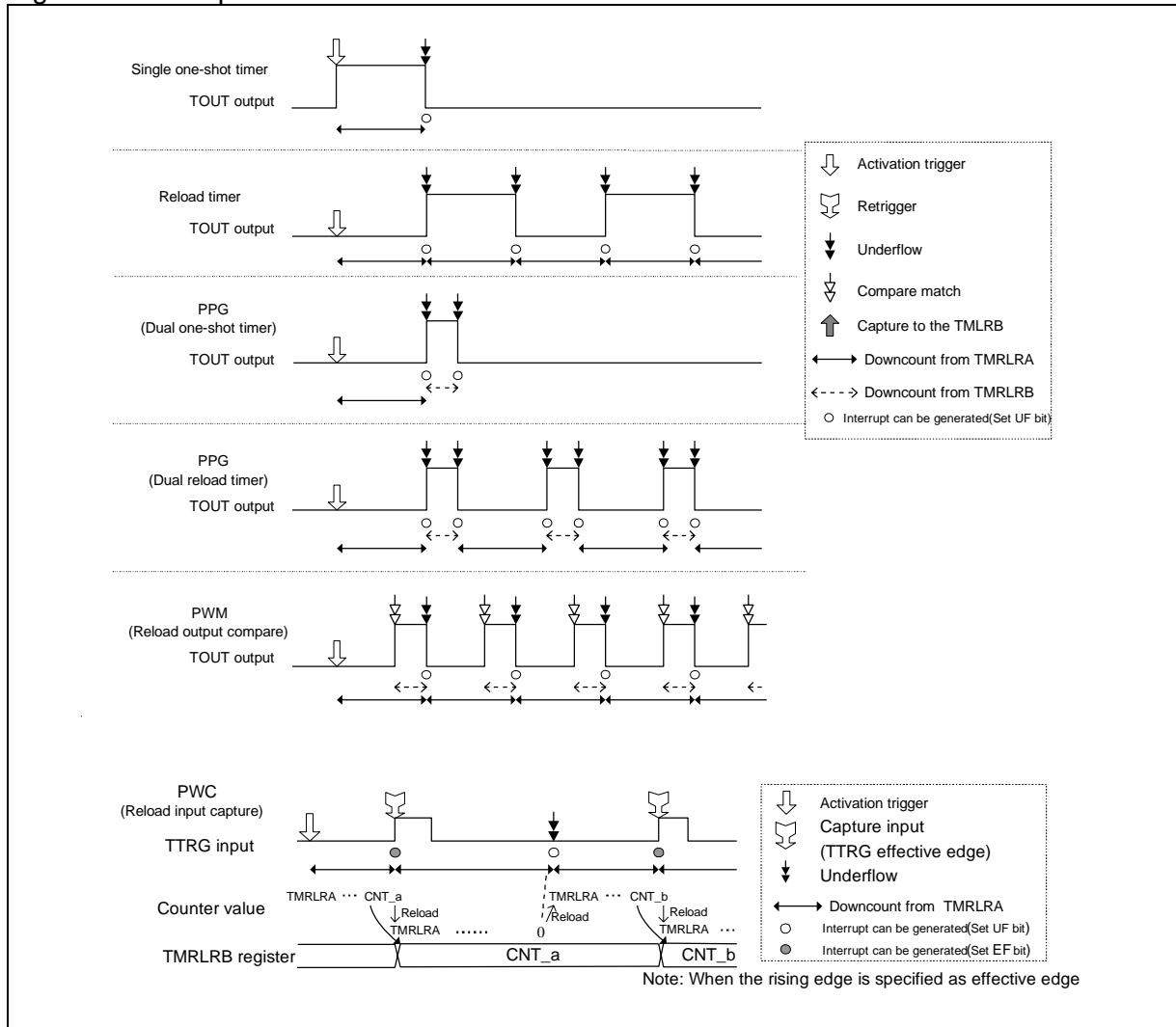
1. Setting flag by the timer operation
2. Writing to a register for a clear of flag to the UF bit/EF bit

6. Application Note

An application note is shown below.

This section shows the typical functions which can be realized with this timer.

Figure 6-1 Example



Following are some configurations for use of example figure above.

Table 6-1 Example of Configuration

Function	MOD[1:0]	RELD	TMRLRA	TMRLRB
Single one-shot timer	00 (Single mode)	0	Mandatory	-
Reload timer	00 (Single mode)	1	Mandatory	-
PPG (Programmable Pulse Generator)	01 (Dual mode)	0 or 1	Mandatory	Mandatory
PWM (Pulse Width Modulator)	10 (Compare mode)	1	Mandatory	Mandatory
PWC (Pulse Width Counter)	11 (Capture mode)	1	Mandatory	-

6.1. Single One-shot Timer

The single one-shot timer is shown below.

The single one-shot timer loads a value from the TMRLRA register onto the counter and starts to decrement the counter (down count operation) when a trigger is input. When an underflow occurs, the counting stops.

The TOUT pin outputs the "H level" in counting and when an underflow occurs it will output the "L level". (When OUTL=0)

[Configuration] To use this timer as a single one-shot timer, configure as follows.

1. When TTRG input is not used

TMCSR											TMRLRA
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	Count initial value setting
00	00	*1	0	-	*2	0	*3	-	1	S	

S :Use at timer activation

-:Does not influence operation

*1:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*2:TOUT output polarity setting

OUTL=0-----Initial value L=> Count starts H=> Underflow occurs L

OUTL=1-----Initial value H=> Count starts L=> Underflow occurs H

*3:Interrupt request enable setting

INTE=0-----Interrupt disabled

INTE=1-----Interrupt enabled

2. When using TTRG input as a gate input

TMCSR											TMRLRA
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	Count initial value setting
00	*1	*2	1	-	*3	0	*4	-	1	S	

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective level setting

TRGM[1:0]=x0-----Count only for L input interval

TRGM[1:0]=x1-----Count only for H input interval

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:TOUT output polarity setting

OUTL= 0-----Initial value L=> Count starts H=> Underflow occurs L

OUTL= 1-----Initial value H=> Count starts L=> Underflow occurs H

*4:Interrupt request enable setting

INTE= 0-----Interrupt disabled

INTE= 1-----Interrupt enabled

3. When using TTRG input as a trigger input

TMCSR											TMRLRA
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	Count initial value setting
00	*1	*2	0	-	*3	0	*4	-	1	S	

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective level setting

TRGM[1:0]= 00-----Does not detect external trigger edge

TRGM[1:0]= 01-----Rising edge

TRGM[1:0]= 10-----Falling edge

TRGM[1:0]= 11-----Both edges

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:OUT output polarity setting

OUTL= 0-----Initial value L=> Count starts H=> Underflow occurs L

OUTL= 1-----Initial value H=> Count starts L=> Underflow occurs H

*4:Interrupt request enable setting

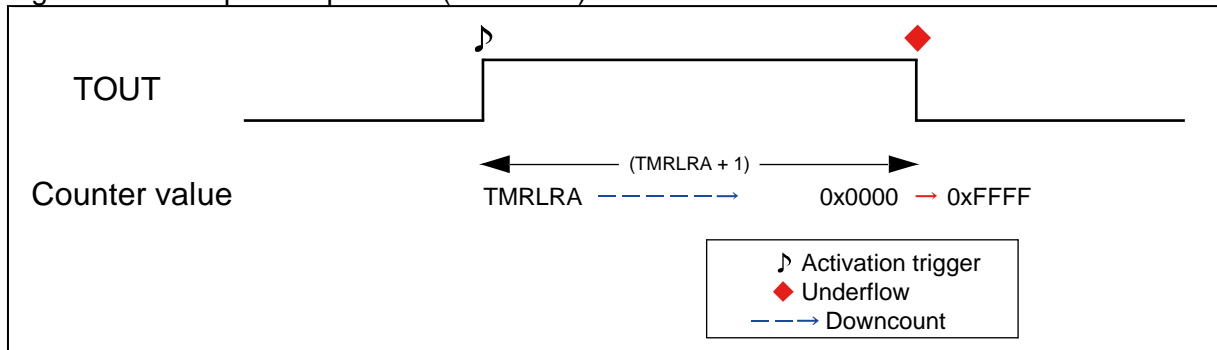
INTE= 0-----Interrupt disabled

INTE= 1-----Interrupt enabled

[Timer activation] Follow the steps below to activate the timer.

- Input an activation trigger (a write of "1" to the TRG bit or an input of effective external edge from TTRG pin)
- Input an effective level when you use TTRG pin input as the gate input

Figure 6-2 Example of Operation (OUTL = 0)



6.2. Reload Timer

The reload time is shown below.

The reload timer loads from the TMRLRA register onto the counter and repeats the down count operation each time underflow occurs. The TOUT outputs the "L level" while the count is going on from the activation trigger to the occurrence of the first underflow, then the output will be inverted to the "H level" at the timing of the occurrence of the first underflow, inverting the outputs whenever an underflow occurs. When a retrigger occurs, TOUT output returns to its initial value. (When OUTL=0)

[Configuration] To use the timer as the reload timer, configure as follows.

1. When TTRG input is not used

TMCSR											TMRLRA
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	Count initial value setting
00	00	*1	0	-	*2	1	*3	-	1	S	

S :Use at timer activation

-:Does not influence operation

*1:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*2:TOUT output polarity setting

OUTL=0-----Initial value L=> Count starts L=> Invert whenever an underflow occurs

OUTL=1-----Initial value H=> Count starts H=> Invert whenever an underflow occurs

*3:Interrupt request enable setting

INTE=0-----Interrupt disabled

INTE=1-----Interrupt enabled

2. When using TTRG input as a gate input

TMCSR											TMRLRA
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	Count initial value setting
00	*1	*2	1	-	*3	1	*4	-	1	S	

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective level setting

TRGM[1:0]=x0-----Count only for TTRG=L input interval

TRGM[1:0]=x1-----Count only for TTRG=H input interval

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:OUT output polarity setting

OUTL=0-----Initial value L=> Count starts L=> Invert whenever an underflow occurs

OUTL=1-----Initial value H=> Count starts H=> Invert whenever an underflow occurs

*4:Interrupt request enable setting

INTE=0-----Interrupt disabled

INTE=1-----Interrupt enabled

3. When using TTRG input as a trigger input

TMCSR											TMRLRA
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	Count initial value setting
00	*1	*2	0	-	*3	1	*4	-	1	S	

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective edge setting

TRGM[1:0]= 00-----Does not detect external trigger edge

TRGM[1:0]= 01-----Rising edge

TRGM[1:0]= 10-----Falling edge

TRGM[1:0]= 11-----Both edges

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:OUT output polarity setting

OUTL= 0-----Initial value L=> Count starts L=> Invert whenever an underflow occurs

OUTL= 1-----Initial value H=> Count starts H=> Invert whenever an underflow occurs

*4:Interrupt request enable setting

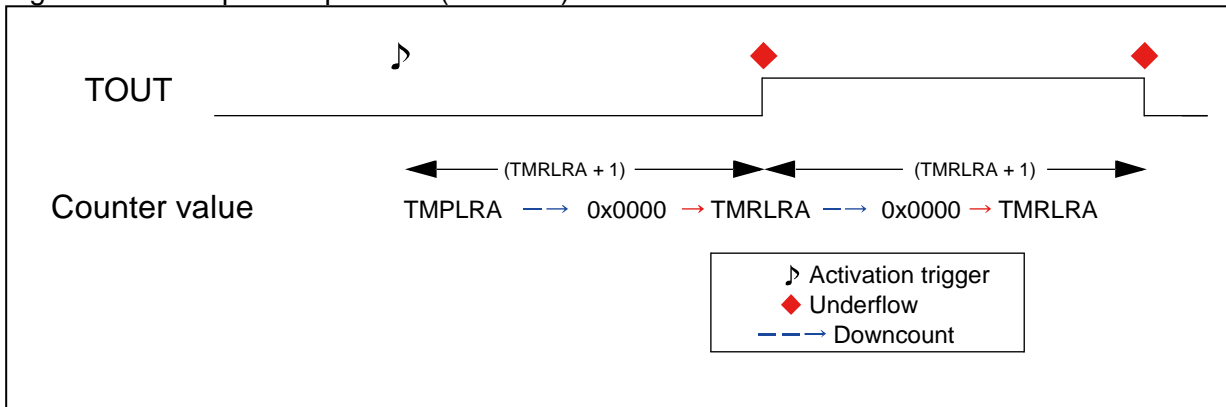
INTE= 0-----Interrupt disabled

INTE= 1-----Interrupt enabled

[Timer activation] Follow the steps below to activate the timer.

- Input an activation trigger (a write of "1" to the TRG bit or an input of effective external edge from TTRG pin)
- Input an effective level when you use TTRG pin input as the gate input

Figure 6-3 Example of Operation (OUTL=0)



6.3. PPG

PPG is shown below.

PPG is the feature which generates an output pulse by configuring L width/H width of the pulse. An activation trigger launches a load from TMRLRA to the counter and the operation switches to load the value from TMRLRB and executes a down count when an underflow occurs.

When RELD=0, "Activation trigger => TMRLRA load => Down count=> Underflow => TMRLRB load => Down count => Underflow," then stops the down count.

When RELD=1, counter is loaded with TMRLRA/TMRLRB alternatively and executes down count whenever an underflow occurs, such as Activation trigger => TMRLRA load => Down count => Underflow => TMRLRB load => Down count => Underflow => TMRLRA load => Down count => Underflow => TMRLRB load and so on.

The TOUT outputs the "L level" while counting until the occurrence of an underflow caused by the down count from TMRLRA, and outputs the "H level" while counting until the occurrence of an underflow caused by the down count from TMRLRB. When a retrigger occurs, TOUT output returns to its initial value.

Note:

TOUT is not initialized in the one shot mode at retrigger.

[Configuration] To use the timer as PPG, configure as follows.

1. When TTRG input is not used

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
01	00	*1	0	-	*2	*3	*4	-	1	S		

(A): The count initial value at an activation trigger/The reload value at an underflow caused by the count from the TMRLRB value (when RELD=1)

(B): The reload value at an underflow caused by the count from the TMRLRA value

S :Use at timer activation

-:Does not influence operation

* 1:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

* 2:TOUT output polarity setting

OUTL= 0-----

Initial value L => Count L from TMRLRA => H when an underflow occurs =>

Count H from TMRLRB => L when an underflow occurs

OUTL= 1-----

Initial value H => Count H from TMRLRA => L when an underflow occurs =>

Count L from TMRLRB => H when an underflow occurs

*3:Reload setting when an underflow occurs

RELD= 0-----One-shot mode

RELD= 1-----Reload mode

*4:Interrupt request enable setting

INTE= 0-----Interrupt disabled

INTE= 1-----Interrupt enabled

2. When using TTRG input as a gate input

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
01	*1	*2	1	-	*3	*4	*5	-	1	S		

(A): The count initial value at an activation trigger/The reload value at an underflow caused by the count from the TMRLRB value (when RELD=1)

(B): The reload value at an underflow caused by the count from the TMRLRA value

S :Use at timer activation

-:Does not influence operation

- * 1:TTRG effective level setting
 - TRGM[1:0]= x0-----Count only for TTRG=L input interval
 - TRGM[1:0]= x1-----Count only for TTRG=H input interval
- * 2:Count clock division setting
 - CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2
 - CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8
 - CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16
 - CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32
 - CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64
- * 3:TOUT output polarity setting
 - OUTL= 0-----
 - Initial value L=> Count L from TMRLRA => H when an underflow occurs =>
 - Count H from TMRLRB => L when an underflow occurs
 - OUTL= 1-----
 - Initial value H=> Count H from TMRLRA => L when an underflow occurs =>
 - Count L from TMRLRB => H when an underflow occurs
- *4:Reload setting when an underflow occurs
 - RELD=0-----One-shot mode
 - RELD=1-----Reload mode
- *5:Interrupt request enable setting
 - INTE=0-----Interrupt disabled
 - INTE=1-----Interrupt enabled

3. When using TTRG input as a trigger input

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
01	*1	*2	0	-	*3	*4	*5	-	1	S		

(A): The count initial value at an activation trigger/The reload value at an underflow caused by the count from the TMRLRB value (when RELD=1)

(B): The reload value at an underflow caused by the count from the TMRLRA value

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective edge setting

TRGM[1:0]= 00-----Does not detect external trigger edge

TRGM[1:0]= 01-----Rising edge

TRGM[1:0]= 10-----Falling edge

TRGM[1:0]= 11-----Both edges

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:TOUT output polarity setting

OUTL= 0-----Initial value L=> Count L from TMRLRA => Invert whenever an underflow occurs

OUTL= 1-----Initial value H=> Count H from TMRLRA => Invert whenever an underflow occurs

*4:Reload setting when an underflow occurs

RELD=0-----One-shot mode

RELD=1-----Reload mode

*5:Interrupt request enable setting

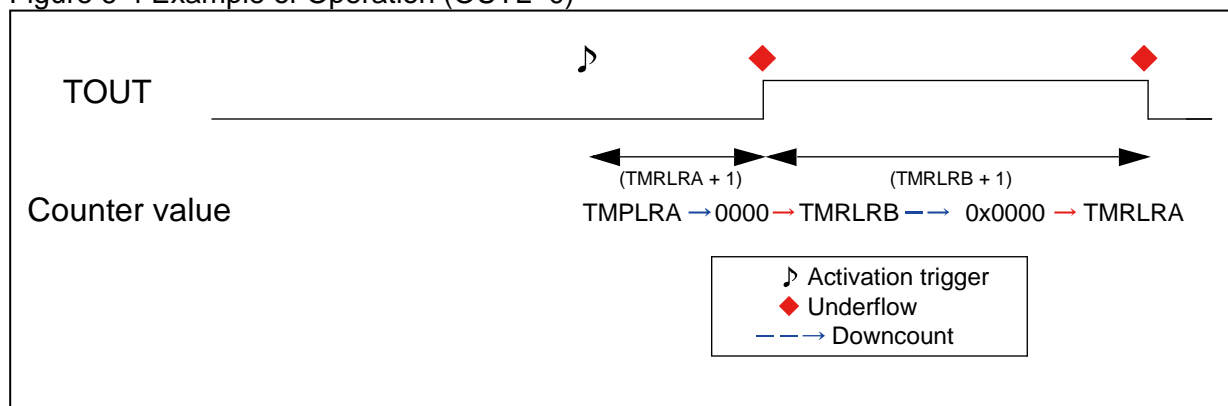
INTE=0-----Interrupt disabled

INTE=1-----Interrupt enabled

[Timer activation] Follow the steps below to activate the timer.

- Input an activation trigger (a write of "1" to the TRG bit or an input of effective external edge from TTRG pin)
- Input an effective level when you use TTRG pin input as the gate input

Figure 6-4 Example of Operation (OUTL=0)



6.4. PWM

PWM is shown below.

PWM is the feature which generates an output pulse by configuring the pulse interval and H width.

An activation trigger launches a load from TMRLRA to the counter and executes a down count.

TOUT outputs the "L level" after an activation trigger and then outputs the "H level" when the counter value becomes smaller than the TMRLRB value. When an underflow occurs, TOUT output returns to its initial value. (When OUTL=0)

When RELD=0, "Activation trigger=> TMRLRA load => Down count => Underflow, then counter stops the down count.

When RELD=1, Counter is loaded with TMRLRA, and it is decremented for each load whenever an underflow occurs, such as Activation trigger=> TMRLRA load=> Down count=> Underflow=> TMRLRA load=> Down count, and so on.

[Configuration] To use the timer as PWM, configure as follows.

1. When TTRG input is not used

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
10	0	*1	0	-	*2	*3	*4	-	1	S		

(A): The count initial value when activation trigger occurs/The reload value at an underflow (when RELD=1)

(B): Set the value to compare to the counter value (TMRLRB < TMRLRA) *5

S :Use at timer activation

-:Does not influence operation

*1:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*2:TOUT output polarity setting

OUTL= 0-----Initial value L=> Count L from TMRLRA => H, the counter value is smaller than TMRLRB

OUTL= 1-----Initial value H=> Count H from TMRLRA => L, the counter value is smaller than TMRLRB

*3:Reload setting when an underflow occurs

RELD= 0-----One-shot mode

RELD= 1-----Reload mode

*4:Interrupt request enable setting

INTE= 0-----Interrupt disabled

INTE= 1-----Interrupt enabled

*5:To use TOUT output with L clip output, set to TMRLRB = 0.

To use TOUT output with H clip output, set to TMRLRB = "TMRLRA + 1".

2. When using TTRG input as a gate input

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
10	*1	*2	1	-	*3	*4	*5	-	1	S		

(A): The count initial value when activation trigger occurs/The reload value at an underflow (when RELD=1)

(B): Set the value to compare to the counter value(TMRLRB < TMRLRA) *6

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective level setting

TRGM[1:0]= x0-----Count only for TRGM=L input interval

TRGM[1:0]= x1-----Count only for TRGM=H input interval

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:TOUT output polarity setting

OUTL= 0-----Initial value L=> Count L from TMRLRA => H, the counter value is smaller than TMRLRB

OUTL= 1-----Initial value H=> Count H from TMRLRA => L, the counter value is smaller than TMRLRB

*4:Reload setting when an underflow occurs

RELD=0-----One-shot mode

RELD=1-----Reload mode

*5:Interrupt request enable setting

INTE=0-----Interrupt disabled

INTE=1-----Interrupt enabled

*6:To use TOUT output with L clip output, set to TMRLRB = 0.

To use TOUT output with H clip output, set to TMRLRB = "TMRLRA + 1".

3. When using TTRG input as a trigger input

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
10	*1	*2	0	-	*3	*4	*5	-	1	S		

(A): The count initial value when activation trigger occurs/The reload value at an underflow (when RELD=1)

(B): Set the value to compare to the counter value (TMRLRB < TMRLRA) *6

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective edge setting

TRGM[1:0]= 00-----Does not detect external trigger edge

TRGM[1:0]= 01-----Rising edge

TRGM[1:0]= 10-----Falling edge

TRGM[1:0]= 11-----Both edges

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:TOUT output polarity setting

OUTL= 0-----Initial value L=> Count L from TMRLRA => H, the counter value is smaller than TMRLRB

OUTL= 1-----Initial value H=> Count H from TMRLRA => L, the counter value is smaller than TMRLRB

*4:Reload setting when an underflow occurs

RELD= 0-----One-shot mode

RELD= 1-----Reload mode

*5:Interrupt request enable setting

INTE= 0-----Interrupt disabled

INTE= 1-----Interrupt enabled

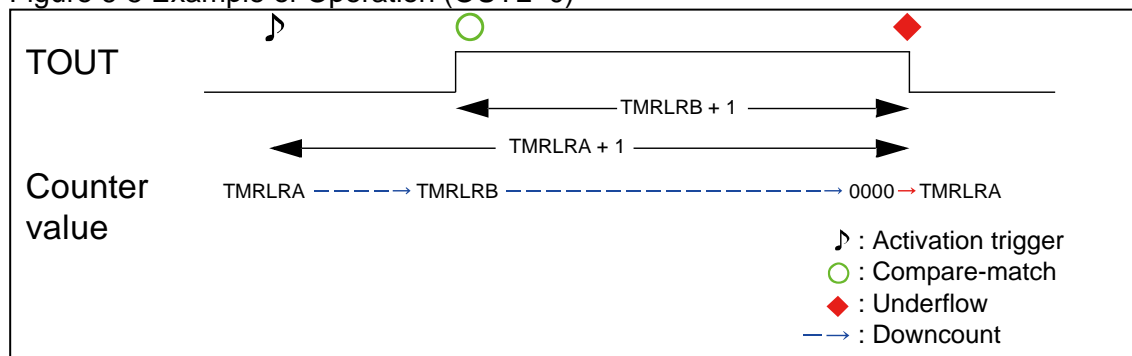
*6:To use TOUT output with L clip output, set to TMRLRB = 0.

To use TOUT output with H clip output, set to TMRLRB = "TMRLRA + 1".

[Timer activation] Follow the steps below to activate the timer.

- Input an activation trigger (a write of "1" to TRG bit or an input of effective external edge from TTRG pin)
- Input an effective level when you use TTRG pin input as the gate input

Figure 6-5 Example of Operation (OUTL=0)



6.5. PWC

PWC is shown below.

PWC is the feature to measure the time interval between triggers to input.

An activation trigger launches a load of a value from TMRLRA onto the counter and executes a down count operation. A trigger input during a count enables the counter value at that time to be captured onto TMRLRB, which allows measuring the time interval between triggers to input.

[Configuration] To use the timer as PWC, configure as follows.

TMCSR											TMRLRA	TMRLRB
MOD [1:0]	TRGM [1:0]	CSL [2:0]	GATE	EF	OUTL	RELD	INTE	UF	CNTE	TRG	(A)	(B)
11	*1	*2	0	-	*3	*4	*5	-	1	S		

(A): The count initial value when activation trigger occurs/The reload value at an underflow (when RELD=1)

S :Use at timer activation

-:Does not influence operation

*1:TTRG effective edge setting

TRGM[1:0]= 00-----Does not detect external trigger edge

TRGM[1:0]= 01-----Rising edge

TRGM[1:0]= 10-----Falling edge

TRGM[1:0]= 11-----Both edges

*2:Count clock division setting

CSL[2:0]= 000-----Division of peripheral clock (PCLK) by 2

CSL[2:0]= 010-----Division of peripheral clock (PCLK) by 8

CSL[2:0]= 011-----Division of peripheral clock (PCLK) by 16

CSL[2:0]= 100-----Division of peripheral clock (PCLK) by 32

CSL[2:0]= 101-----Division of peripheral clock (PCLK) by 64

*3:TOUT output polarity setting

OUTL= 0-----Initial value L=> Count L from TMRLRA => Invert whenever an underflow occurs

OUTL= 1-----Initial value H=> Count H from TMRLRA => Invert whenever an underflow occurs

*4:Reload setting when an underflow occurs

RELD= 0-----One-shot mode

RELD= 1-----Reload mode

*5:Interrupt request enable setting

INTE= 0-----Interrupt disabled

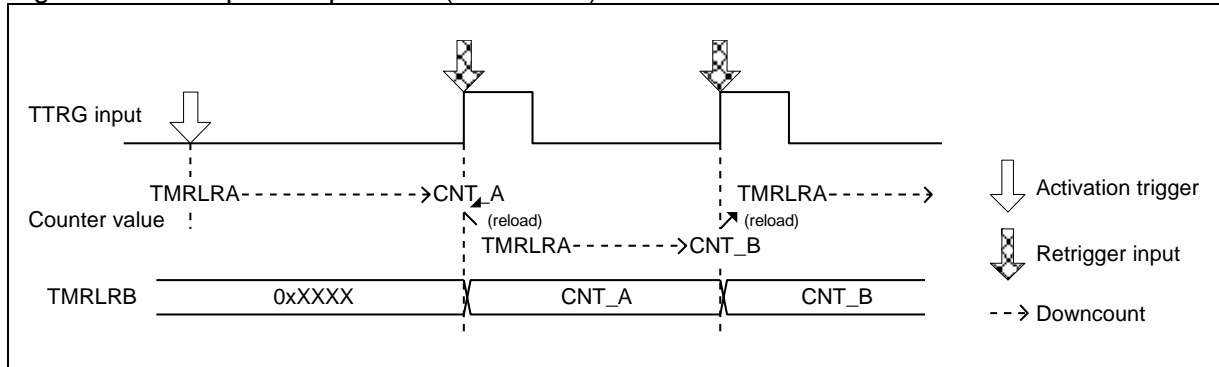
INTE= 1-----Interrupt enabled

[Timer activation] Follow the steps below to activate the timer.

- Input an activation trigger (a write of "1" to TRG bit or an input of effective external edge from TTRG pin) While down counting, the counter value will be captured onto the TMRLRB whenever a trigger input occurs. The time interval between edges of the triggers to input will be obtained by the following formula.

$$T = (\text{The set value for TMRLRA} - \text{The captured value for TMRLRB}) \times \text{Peripheral clock (PCLK) cycle} \times \text{Division ratio set with CSL}$$

Figure 6-6 Example of Operation (TRGM=01)



CHAPTER : FREE-RUN TIMER

This chapter explains the free-run timer.

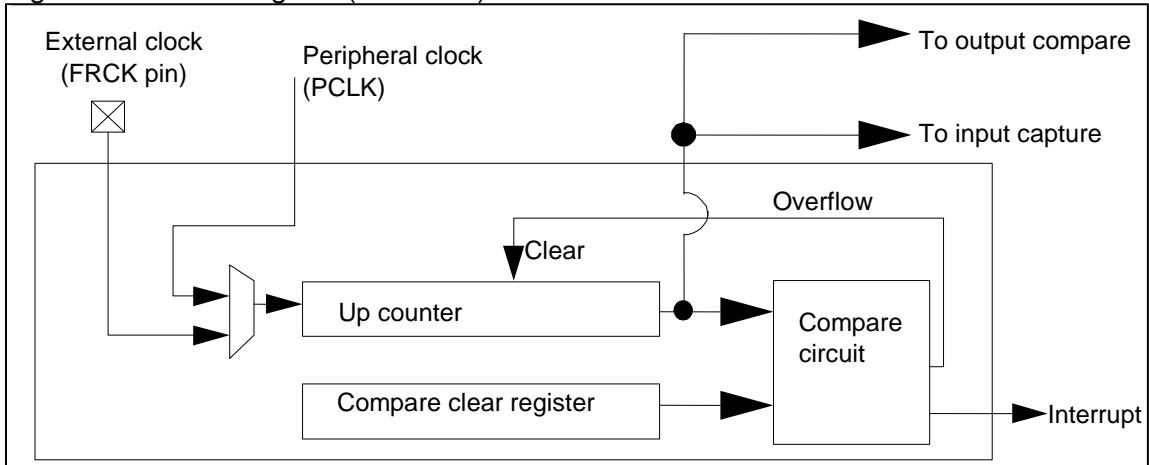
1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Setting
7. Q&A
8. Sample Program
9. Notes

1. Overview

This section explains the overview of the free-run timer.

The free-run timer consists of a 32-bit up counter and a control circuit. The free-run timer can be used in combination with input capture and output compare.

Figure 1-1 Block Diagram (Overview)



2. Features

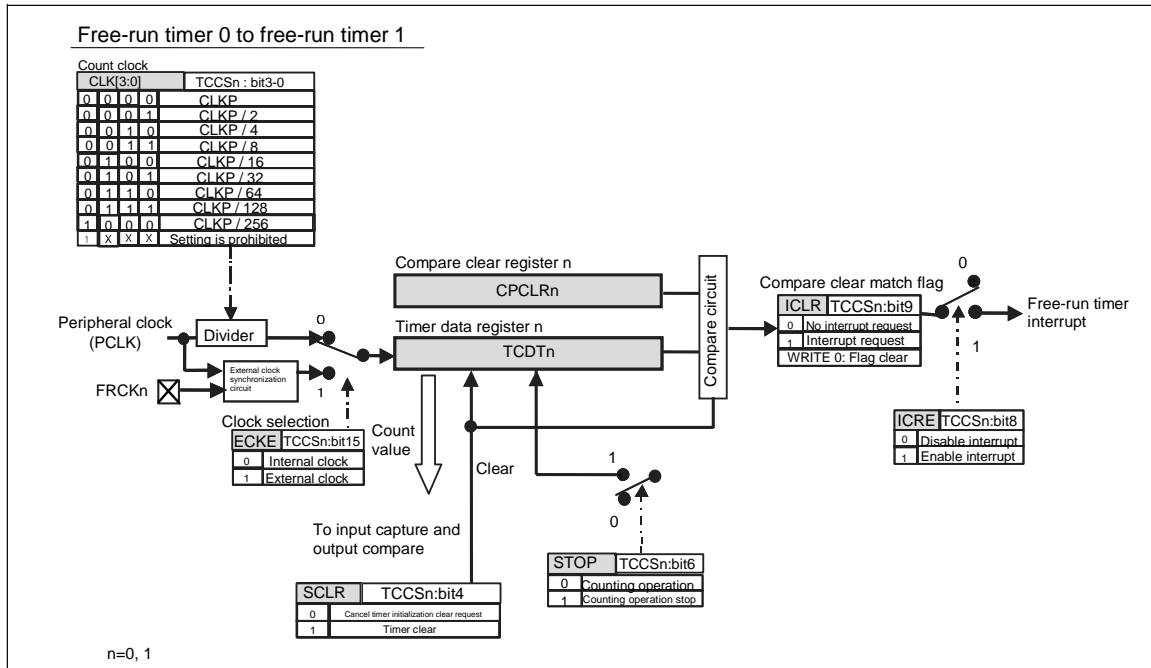
This section show the features of the free-run timer.

- Format : 32-bit up counter
- Number of units : 2 (free-run timer 0 and free-run timer 1) + 2 ((free-run timer 2 and free-run timer 3) used as input capture for LSYN (Lin Sync Field detection) only)
- Clock source : One of 9 internal clocks (peripheral clock (PCLK)/1, /2, /4, /8, /16, /32, /64, /128, /256) or one of two external clocks (FRCK0, FRCK1)
- Count clear factors :
 - Software
 - Reset
- Compare match (count value of the free-run timer matches the compare clear register)
- Operation start/stop: The operation can be started and stopped by software.
- Interrupt : Compare clear interrupt
- Count value : Read/write enabled (writing is only enabled while counting is inactive)
- The 32-bit free-run timer consists of a 32-bit up counter, control register, 32-bit compare clear register, and prescaler.
- A compare clear interrupt will be generated when a compare clear register matches the 32-bit free-run timer upon comparison of the two.
- If there is a compare match with reset, software clear or compare clear register, the counter value will be reset to "00000000_H".
- It is used as the reference count for output compare and input capture.

3. Configuration

This section explains configuration of the free-run timer.

Figure 3-1 Configuration Diagram (Detailed)



Note:

Free-run timer 2 and 3 are used as input capture for LSYN only. Therefore, they do not cooperate with output compare. Also, no external clock is provided to support them (During clock selection, selecting "External clock" is disabled).

4. Registers

This section explains the registers of the free-run timer.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0240	CPCLR0				Compare clear register 0
0x0244	TCDT0				Timer data register 0
0x0248	TCCSH0	TCCSL0	Reserved		Timer control register (Upper Bit) 0 Timer control register (Lower Bit) 0
0x024C	CPCLR1				Compare clear register 1
0x0250	TCDT1				Timer data register 1
0x0254	TCCSH1	TCCSL1	Reserved		Timer control register (Upper Bit) 1 Timer control register (Lower Bit) 1
0x0FA0	CPCLR2				Compare clear register 2 (only for LSYN)
0x0FA4	TCDT2				Timer data register 2 (only for LSYN)
0x0FA8	TCCSH2	TCCSL2	Reserved		Timer control register high-order 2 (only for LSYN) Timer control register low-order 2 (only for LSYN)
0x0FAC	CPCLR3				Compare clear register 3 (only for LSYN)
0x0FB0	TCDT3				Timer data register 3 (only for LSYN)
0x0FB4	TCCSH3	TCCSL3	Reserved		Timer control register high-order 3 (only for LSYN) Timer control register low-order 3 (only for LSYN)

4.1. Timer Control Register (Upper Bit) : TCCSH

The bit configuration of the timer control register (Upper bit) is shown.

This register is used to control the operation of the free-run timer.

■ **TCCSH0 (Free-run timer 0): Address 0248_H (Access: Byte, Half-word, Word)**

■ **TCCSH1 (Free-run timer 1): Address 0254_H (Access: Byte, Half-word, Word)**

■ **TCCSH2 (Free-run timer 2 (only for LSYN)): Address 0FA8_H (Access: Byte, Half-word, Word)**

■ **TCCSH3 (Free-run timer 3 (only for LSYN)): Address 0FB4_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	ECKE	-	-	-	-	-	ICLR	ICRE
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R(RM1),W	R/W

[bit15] ECKE : Clock selection

ECKE	Count clock selection
0	Internal clock
1	External clock (FRCK0 and FRCK1 pins) * For TCCSH2 (free-run timer 2 (only for LSYN)) and TCCSH3 (free-run timer 3 (only for LSYN)), this setting is disabled.

- When this bit is set to "0": Internal clock is selected. To select the count clock frequency, you will also need to select the clock frequency selection bits (CLK3 to CLK0:bit3 to bit0) of the TCCSL register.
- When this bit is set to "1": External clock is selected. The external clock is input from the "FRCK" pin. Therefore, enable external clock input by writing "0" to the bit of the port direction register (DDR) corresponding to the FRCK input pin and writing "0" to the bit of the corresponding port function register (PFR) to switch to port input state. If external clock is selected by the ECKE bit, clock count will detect both edges. Set the pulse width of the external clock to $4/F_{CLK}$ or more.

Note:

The setting change for the count clock selection bit must be performed while other peripheral modules using the free-run timer output (output compare and input capture) are inactive.

[bit14 to bit10] - : Undefined

The read value is always "0". This does not affect the writing operation.

[bit9] ICLR : Compare clear interrupt flag

ICLR	State	
	Read	Write
0	No compare clear match	Clear the flag (ICLR)
1	Compare clear match	No effect on operation

- This bit will be set to "1" when the compare clear value matches the 32-bit free-run timer value.

[bit8] ICRE : Compare clear interrupt request enabled

ICRE	Operation
0	Interrupt disabled
1	Interrupt enabled

- When the ICRE bit and compare clear interrupt flag bit (ICLR) are set to "1", an interrupt request for CPU will be generated.

4.2. Timer Control Register (Lower Bit) : TCCSL

The bit configuration of timer control register (Lower bit) is shown.

This register is used to control the operation of the free-run timer.

- **TCCSL0 (Free-run timer 0): Address 0249_H (Access: Byte, Half-word, Word)**
- **TCCSL1 (Free-run timer 1): Address 0255_H (Access: Byte, Half-word, Word)**
- **TCCSL2 (Free-run timer 2 (only for LSYN)): Address 0FA9_H (Access: Byte, Half-word, Word)**
- **TCCSL3 (Free-run timer 3 (only for LSYN)): Address 0FB5_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	STOP	-	SCLR	CLK3	CLK2	CLK1	CLK0
Initial value	0	1	0	0	0	0	0	0
Attribute	R0,WX	R/W	R0,WX	R0,W	R/W	R/W	R/W	R/W

[bit7] - : Undefined

The read value is always "0". This does not affect the writing operation.

[bit6] STOP : Timer enabled

STOP	Operation
0	Count enabled (operation)
1	Count disabled (stop)

- The STOP bit is used to start/stop counting of the 32-bit free-run timer.
- When the STOP bit is "0": Counter of the 32-bit free-run timer is started.
- When the STOP bit is "1": Counter of the 32-bit free-run timer is stopped.

Note:

If output compare is in use, the output compare operation will stop when the free-run timer stops.

[bit5] - : Undefined

The read value is always "0". This does not affect the writing operation.

[bit4] SCLR : Timer clear

SCLR	State	
	Read	Write
0	The read value is always "0".	Writing "0" has no effect on operation.
1		Clears the free-run timer.

- When this bit is set to "1", the count value of the free-run timer is cleared to "00000000_H". The prescaler within the macro is also cleared at this time.

- The value read out is always "0".

Note:

If you set this bit to "1", timer clear will be performed at the next internal clock timing.

[bit3 to bit0] CLK3 to CLK0 : Clock frequency selection (when internal clock is selected)

CLK3	CLK2	CLK1	CLK0	Clock frequency selection (F _{PCLK} : Peripheral clock (PCLK))				
				Count clock	F _{PCLK} =16MHz	F _{PCLK} =8MHz	F _{PCLK} =4MHz	F _{PCLK} =1MHz
0	0	0	0	1/F _{PCLK}	62.5ns	125ns	0.25μs	1μs
0	0	0	1	2/F _{PCLK}	125ns	0.25μs	0.5μs	2μs
0	0	1	0	4/F _{PCLK}	0.25μs	0.5μs	1μs	4μs
0	0	1	1	8/F _{PCLK}	0.5μs	1μs	2μs	8μs
0	1	0	0	16/F _{PCLK}	1μs	2μs	4μs	16μs
0	1	0	1	32/F _{PCLK}	2μs	4μs	8μs	32μs
0	1	1	0	64/F _{PCLK}	4μs	8μs	16μs	64μs
0	1	1	1	128/F _{PCLK}	8μs	16μs	32μs	128μs
1	0	0	0	256/F _{PCLK}	16μs	32μs	64μs	256μs
Other settings				—	Prohibit			

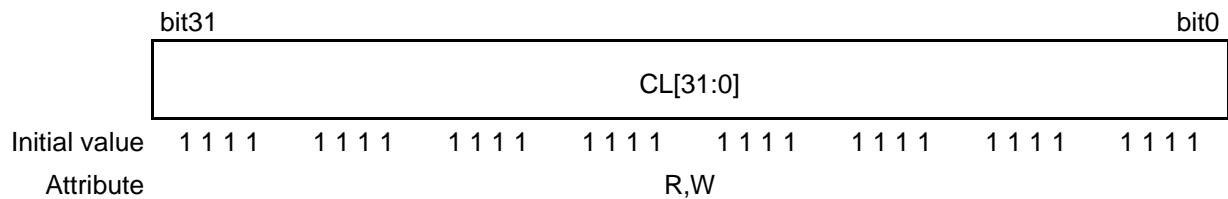
- The frequency is changed at the same time as the setting change to the clock frequency selection bit. If internal clock is selected as the count clock of the free-run timer (clock selection bit (ECKE= 0)), change the setting while other peripheral modules (output compare and input capture) using the free-run timer output are inactive.
- When the free-run timer is used as compare data for the output compare, the free-run timer clock frequency cannot be set as CLK[3:0]= 0000_B.

4.3. Compare Clear Register : CPCLR

The bit configuration of the compare clear register (CPCLR) is shown.

Compare clear register is a 32-bit register to be used for comparison with the free-run timer.

- **CPCLR0 (Free-run timer 0): Address 0240_H (Access: Word)**
- **CPCLR1 (Free-run timer 1): Address 024C_H (Access: Word)**
- **CPCLR2 (Free-run timer 2 (only for LSYN)): Address 0FA0_H (Access: Word)**
- **CPCLR3 (Free-run timer 3 (only for LSYN)): Address 0FAC_H (Access: Word)**



[bit31 to bit0] CL[31:0] : Compare clear

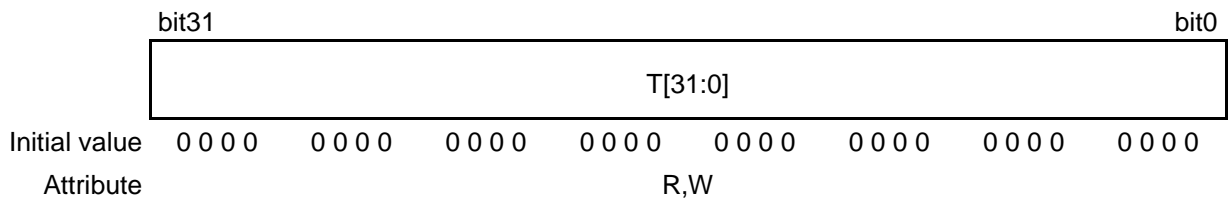
- The compare clear register is used for comparison with the count value of the 32-bit free-run timer. If the count value of this register matches that of the free-run timer, the 32-bit free-run timer will be reset to "00000000_H" and an interrupt will be generated when the value set to this register matches the counter value. However, the value needs to be written while the timer is inactive (the STOP bit of timer state control register lower (TCCSL) = 1).
- Writing to this register during operation will have no meaning.
- When accessing this register, use a word access instruction.

4.4. Timer Data Register : TCDT

The bit configuration of the timer data register (TCDT) is shown.

The timer data register is used for reading the count value of the 32-bit free-run timer.

- **TCDT0 (Free-run timer 0): Address 0244_H (Access: Word)**
- **TCDT1 (Free-run timer 1): Address 0250_H (Access: Word)**
- **TCDT2 (Free-run timer 2 (only for LSYN)): Address 0FA4_H (Access: Word)**
- **TCDT3 (Free-run timer 3 (only for LSYN)): Address 0FB0_H (Access: Word)**



- The count value of the 32-bit free-run timer can be read by reading the timer data register.
- Timer value can be written to the free-run timer by writing to the timer data register. Always write to this register while the free-run timer is inactive (timer control register lower (STOP of TCCSL = 1)).
- When accessing this register, use a word access instruction.
- The 32-bit free-run timer will be initialized as soon as any of the following occurs.
 - Reset
 - The Clear bit (SCLR = 1) of the timer state control register (TCCSL)
 - The timer count value matches the compare clear register
- Writing to this register while it is in operation will have no meaning.

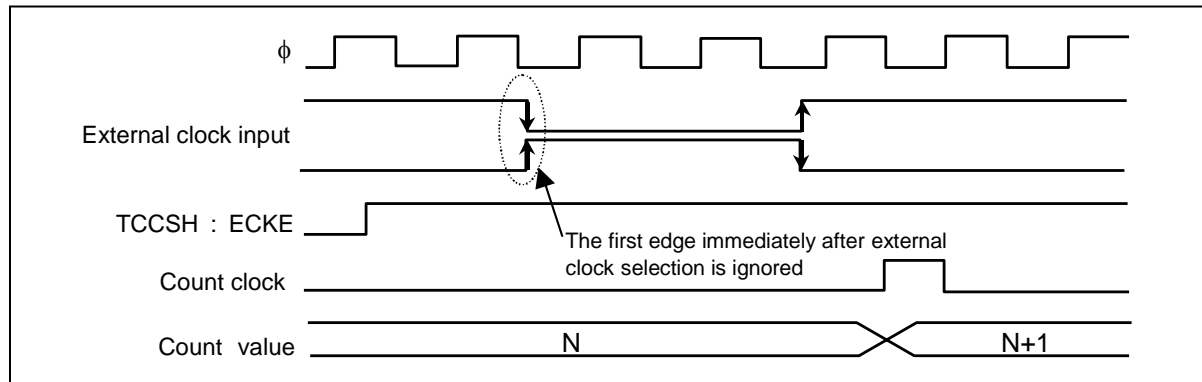
5. Operation

This section explains the operations of the free-run timer.

- 5.1. Count Operation of the Free-run Timer
- 5.2. Counting Up
- 5.3. Timer Clear
- 5.4. Clear Operations of the Free-run Timer
- 5.5. Timer Interrupt

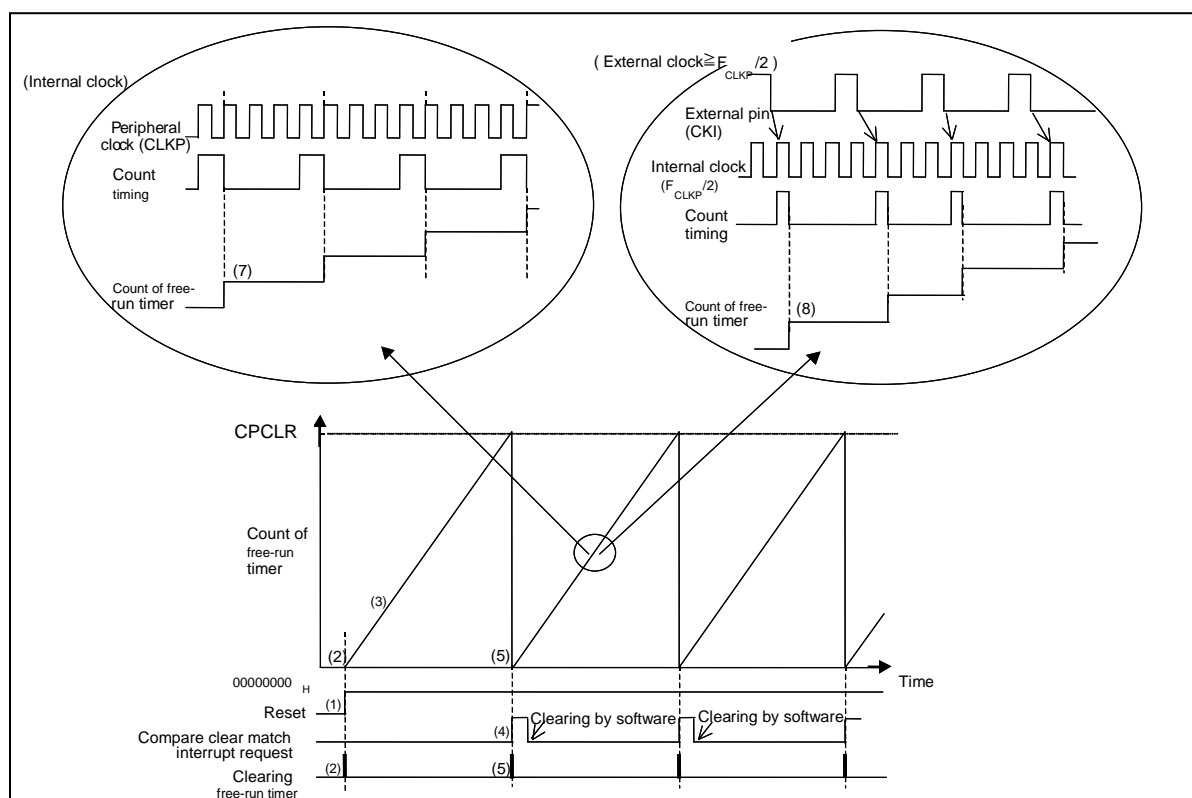
5.1. Count Operation of the Free-run Timer

This section explains the count operation of the free-run timer.



The free-run timer will be incremented based on the input clock (internal clock or external clock). If the external clock mode (TCCSH:ECKE = 1) is selected, the free-run timer starts counting up by the rising and falling edges of the external input clock.

The first rising and falling edges of the external clock immediately after the selection of external clock mode will be ignored. This means that the first falling edge will be ignored if the initial value of the external clock input is "1", and the first rising edge will be ignored if the initial value is "0".



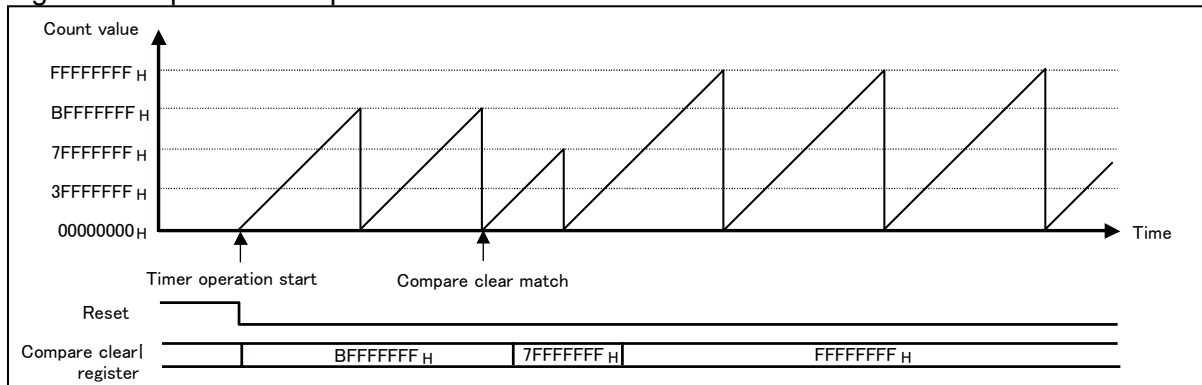
- (1) Reset
- (2) Clearing of the free-run timer by reset (Count value "00000000_H")
- (3) Count up operation by the free-run timer
- (4) Compare clear match of the free-run timer and interrupt generation
- (5) Clearing of the free-run timer by compare clear match (Count value "00000000_H")
- (6) Repetition of step (3) to (5)
- (7) The free-run timer counts up in the clock obtained by dividing the internal clock (count clock).
- (8) The free-run timer counts up in the count clock obtained by synchronizing the external clock with the internal clock.

5.2. Counting Up

This section explains counting up of the free-run timer.

32-bit free-run timer is an up counter. The counter starts counting up from the timer data register (TCDT) configured in advance. It continues to count up until the count value matches the value of the compare clear register (CPCLR). The counter will then be cleared to "00000000_H" and start counting up again.

Figure 5-1 Up Counter Operation



5.3. Timer Clear

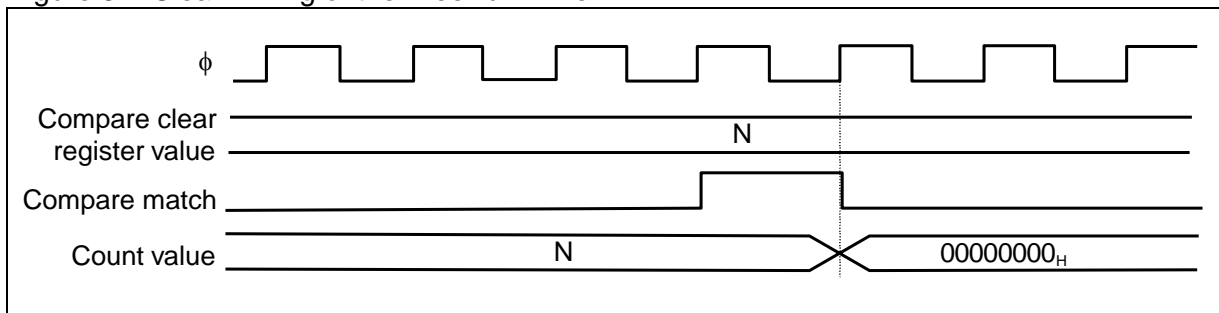
This section explains timer clear of the free-run timer.

The count value of the free-run timer will be cleared in any of the followings:

- When there is a match with the compare clear register
- When "1" is written to the SCLR bit of the TCCSL register while it is in operation
- When "00000000_H" is written to the TCDT register while it is in stop
- When it has been reset.

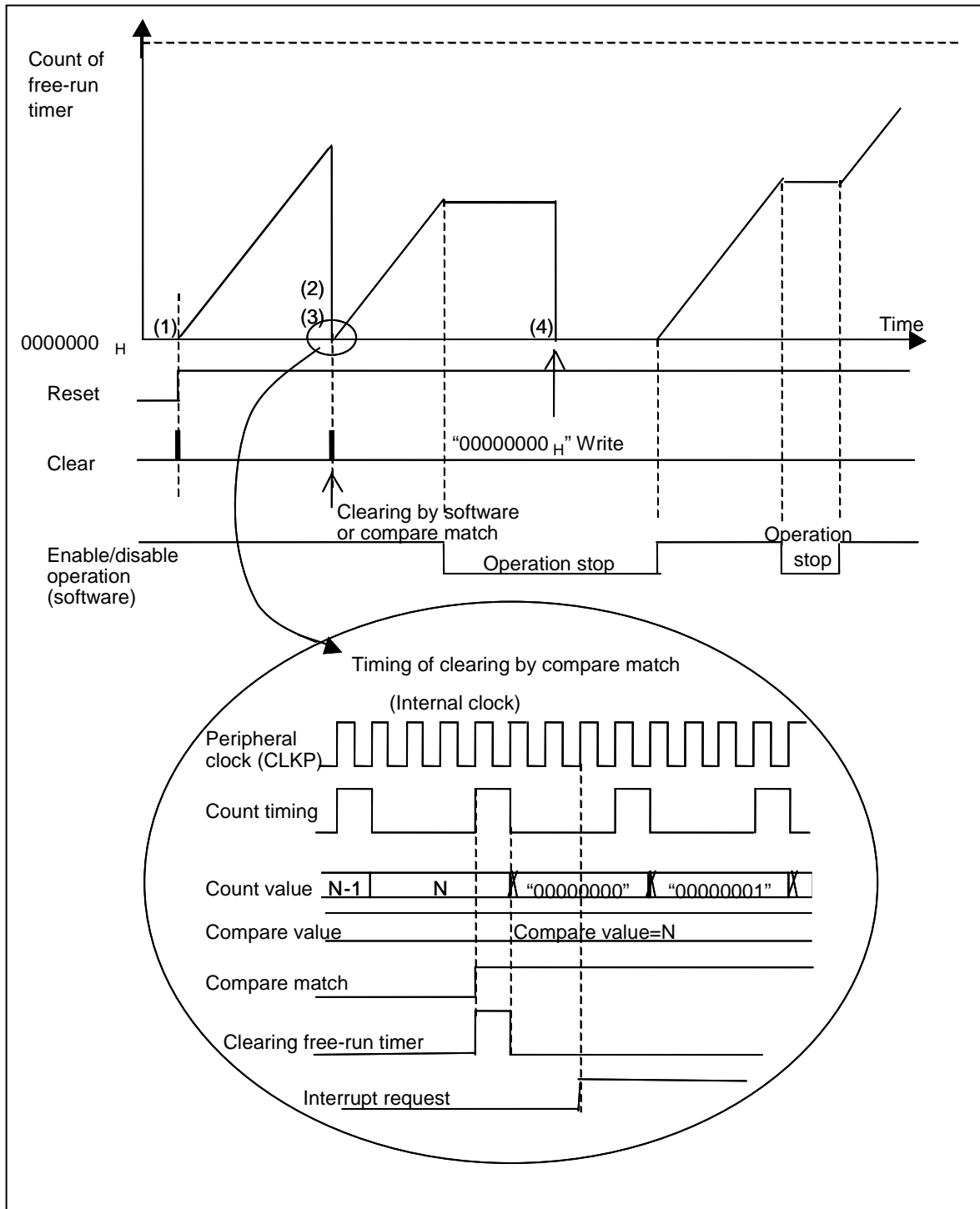
The counter will be cleared as soon as it has been reset. When there is a match with the compare clear register, the counter will be cleared in synchronization with the count timing.

Figure 5-2 Clear Timing of the Free-run Timer



5.4. Each Clear Operations of the Free-run Timer

This section explains each clear operations of the free-run timer.



Clearing of the free-run timer (4 types)

- (1) When it has been reset
- (2) When "1" is written to SCLR: bit4 of the TCCSL register while it is in operation
- (3) When there is a match with the compare clear register
- (4) When "00000000H" is written to the TCDT register while it is in stop

5.5. Timer Interrupt

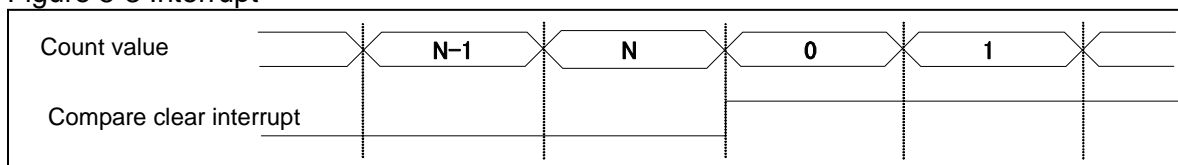
This section explains timer interrupt of the free-run timer.

For the free-run timer, you will be able to generate the following type of interrupt.

- Compare clear interrupt

The compare clear interrupt will be generated when the timer value matches the value of the compare clear register (CPCLR).

Figure 5-3 Interrupt



6. Setting

This section explains setting of the free-run timer.

Table 6-1 Settings Required for Using the Free-run Timer

Configuration	Configured register	Setting method
Timer initialization condition setting	Timer control registers (TCCS0 to TCCS3)	See 7.4.
Count clock setting Internal clock selection		See 7.1.
External clock selection		See 7.2.
Count operation start		See 7.3.
For external clock, set the clock input pins (FRCK0 and FRCK1) for input.	Set the pins for peripheral input. See "CHAPTER: I/O PORTS".	

Table 6-2 Settings Required for Performing Free-run Timer Interrupt

Configuration	Configured register	Setting method
Free-run timer interrupt vector Free-run timer interrupt level setting	See "CHAPTER: INTERRUPT CONTROL".	See 7.5.
Free-run timer interrupt setting Interrupt request clear Interrupt request enable	Timer control registers (TCCS0 to TCCS3)	See 7.6.

Table 6-3 Settings Required for Stopping the Free-run Timer

Configuration	Configured register	Setting method
Free-run timer stop bit setting	Timer control registers (TCCS0 to TCCS3)	See 7.7.

7. Q&A

This section explains Q&A of the free-run timer.

- 7.1. How to Select Internal Clock Dividers
- 7.2. How to Select the External Clock
- 7.3. How to Enable/Disable the Count Operation of the Free-run Timer
- 7.4. How to Clear the Free-run Timer
- 7.5. About Interrupt Related Registers
- 7.6. How to Enable Compare Clear Interrupt
- 7.7. How to Stop the Free-run Timer Operation

7.1. How to Select Internal Clock Dividers

This section explains how to select internal clock dividers.

There are nine types of internal clock dividers. You can configure it using the clock selection bits (TCCS0:ECKE), (TCCS1:ECKE), (TCCS2:ECKE), (TCCS3:ECKE) , and count clock bits (TCCS0:CLK[3:0]), (TCCS1:CLK[3:0]), (TCCS2:CLK[3:0]), (TCCS3:CLK[3:0]).

Internal clock	Configuration	
	Clock selection bit (ECKE)	Count clock bits (CLK[3:0])
To select F_{PCLK}	Set "0".	Set "0000".
To select $2/F_{PCLK}$	Set "0".	Set "0001".
To select $4/F_{PCLK}$	Set "0".	Set "0010".
To select $8/F_{PCLK}$	Set "0".	Set "0011".
To select $16/F_{PCLK}$	Set "0".	Set "0100".
To select $32/F_{PCLK}$	Set "0".	Set "0101".
To select $64/F_{PCLK}$	Set "0".	Set "0110".
To select $128/F_{PCLK}$	Set "0".	Set "0111".
To select $256/F_{PCLK}$	Set "0".	Set "1000".

7.2. How to Select the External Clock

This section explains how to select the external clock.

You can configure it using the clock selection bits (TCCS0:ECKE), (TCCS1:ECKE), data direction bits and port function bits.

To set to external clock input	Configuration		Pin	Pulse width (H width, L width)
Free-run timer 0	Set the clock selection bit (ECKE) to "1".	Set the FRCK0 pin for peripheral input. (See "CHAPTER: I/O PORTS".)	FRCK0	4/F _{PCLK} or higher
Free-run timer 1		Set the FRCK1 pin for peripheral input. (See "CHAPTER: I/O PORTS".)	FRCK1	

Note:

No external clock is provided to support free-run timer 2 (only for LSYN) and 3 (only for LSYN) (During clock selection, selecting "External clock" is disabled).

7.3. How to Enable/Disable the Count Operation of the Free-run Timer

This section explains how to enable/disable the count operation of the free-run timer.

Set the count operation bits (TCCS0:STOP), (TCCS1:STOP), (TCCS2:STOP), (TCCS3:STOP).

Operation	Count operation bit (STOP)
To operate the free-run timer	Set "0".
To stop the free-run timer	Set "1".

7.4. How to Clear the Free-run Timer

This section explains how to clear the free-run timer.

You can clear the free-run timer using the following method.

- Set using the clear bits (TCCS0:SCLR), (TCCS1:SCLR), (TCCS2:SCLR), (TCCS3:SCLR).

Operation	Clear bit (SCLR)
To clear the free-run timer	Write "1".

- Perform a reset.
When a reset is performed (RSTX pin input, watchdog reset, software reset, etc.), the free-run timer will be cleared to its initial state.
- Write "00000000_H" while the free-run timer is inactive.
If "00000000_H" is written while the free-run timer is inactive, the count value will be "00000000_H".
- Overflow of the free-run timer will result in the count value returning to "00000000_H".
- It will be cleared if there is a match with the compare clear register.

7.5. About Interrupt Related Registers

This section explains interrupt related registers.

Free-run timer interrupt vector and free-run timer interrupt level settings

The relationship between free-run timer numbers, interrupt levels and interrupt vectors is as shown in "C. List of Interrupt Vector" in "APPENDIX".

For details of the interrupt levels and interrupt vectors, see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

Number	Interrupt vector (default)	Interrupt level setting bit (ICR[4:0])
Free-run timer 0	#50 Address: 0FFF34 _H	Interrupt level register (ICR34) Address: 00462 _H
Free-run timer 1	#51 Address: 0FFF30 _H	Interrupt level register (ICR35) Address: 00463 _H
Free-run timer 2 (only for LSYN)	#50 Address: 0FFF34 _H	Interrupt level register (ICR34) Address: 00462 _H
Free-run timer 3 (only for LSYN)	#51 Address: 0FFF30 _H	Interrupt level register (ICR35) Address: 00463 _H

Since interrupt request flags (TCCS0:ICLR), (TCCS1:ICLR), (TCCS2:ICLR), (TCCS3:ICLR) will not be cleared automatically, clear the flags using software before returning from interrupt processing. (Write "0" to the ICLR bit)

7.6. How to Enable Compare Clear Interrupt

This section explains how to enable compare clear interrupt.

Enable interrupt request, interrupt request flag

Interrupt enable setting can be performed using interrupt request enable bits (TCCS0:ICRE), (TCCS1:ICRE), (TCCS2:ICRE), (TCCS3:ICRE).

Operation	Compare clear interrupt request enable bit (ICRE)
Interrupt disabled	Set "0".
Interrupt enabled	Set "1".

Clearing of the interrupt request can be configured using interrupt flag bits (TCCS0:ICLR), (TCCS1:ICLR), (TCCS2:ICLR), (TCCS3:ICLR).

Operation	Compare clear interrupt flag bit (ICLR)
Interrupt request clear	Write "0".

7.7. How to Stop the Free-run Timer Operation

This section explains how to stop the free-run timer operation.

Set using the count operation bits (TCCS0:STOP), (TCCS1:STOP), (TCCS2:STOP), (TCCS3:STOP).

See "7.3. How to Enable/Disable the Count Operation of the Free-run Timer".

8. Sample Program

This section explains sample program of the free-run timer.

<p>Setting procedure example 1</p> <p>Free-run timer 0, Clock=PCLK/2⁶, Count the number of compare matches using interrupt processing.</p> <p>< Initial setting ></p> <p>-Free-run timer ch.0 control</p> <table border="1"> <thead> <tr> <th>Register name.Bit name</th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Control register setting Clock selection»</td> <td>TCCSH0/TCCSL0 .ECKE</td> </tr> <tr> <td>Compare interrupt request flag»</td> <td>.ICLR</td> </tr> <tr> <td>Compare interrupt request enabled»</td> <td>.ICRE</td> </tr> <tr> <td>Counting Operation»</td> <td>.STOP</td> </tr> <tr> <td>TCDT clear»</td> <td>.CLR</td> </tr> <tr> <td>Count clock»</td> <td>.CLK3-0</td> </tr> <tr> <td>Timer data value setting</td> <td>TCDT0</td> </tr> </tbody> </table> <p>-Interrupt-related</p> <table border="1"> <thead> <tr> <th>Register name.Bit name</th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Sets an interrupt level.</td> <td>ICR34</td> </tr> <tr> <td>I flag setting</td> <td>(CCR)</td> </tr> </tbody> </table> <p>-Variable setting</p> <p><Activation></p> <p>-Free-run timer ch.0 activation</p> <table border="1"> <thead> <tr> <th>Register name.Bit name</th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Count operation activation</td> <td>TCCS0_STOP</td> </tr> </tbody> </table> <p><Interrupt ></p> <p>-Interrupt processing</p> <table border="1"> <thead> <tr> <th>Register name.Bit name</th> <th>Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Clearing of interrupt request flag (Any process)</td> <td>TCCS0.ICLR</td> </tr> <tr> <td>Variable counting</td> <td></td> </tr> </tbody> </table> <p><Interrupt vector></p> <p>Vector table setting</p> <p>(Note) Clock-related settings and the setting of __set_iI (numeric value) need to be configured in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)"</p>	Register name.Bit name	Register name.Bit name	Control register setting Clock selection»	TCCSH0/TCCSL0 .ECKE	Compare interrupt request flag»	.ICLR	Compare interrupt request enabled»	.ICRE	Counting Operation»	.STOP	TCDT clear»	.CLR	Count clock»	.CLK3-0	Timer data value setting	TCDT0	Register name.Bit name	Register name.Bit name	Sets an interrupt level.	ICR34	I flag setting	(CCR)	Register name.Bit name	Register name.Bit name	Count operation activation	TCCS0_STOP	Register name.Bit name	Register name.Bit name	Clearing of interrupt request flag (Any process)	TCCS0.ICLR	Variable counting		<p>Program example 1</p> <pre> void FREE_RUN_TIMER0_sample(void) { FREERUN0_initial(); FREERUN0_start(); } void FREERUN0_initial(void) { IO_TCCS1.word = 0x0041; /* Setting value=0000_0000_0100_0001 */ /* bit15 = 0 ECKE internal clock source */ /* bit14 -10= 00000 Reserved bit */ /* bit9 = 0 ICLR compare interrupt request flag */ /* bit8 = 0 ICRE compare interrupt disabled */ /* bit7 = 0 Reserved bit */ /* bit6 = 1 STOP count disabled */ /* bit5 = 0 Reserved bit */ /* bit4 = 0 SCLR Initialization of SCLR free-run timer value (no) */ /* bit3-0 = 0001 CLK3-0 Count clock PCLK/2=32MHz/2 */ IO_TCDT0 = 0x0000; /* Initialization of timer data value */ IO_ICR[34].byte = 0x10; /* Free-run timer 0 interrupt level setting (any value) */ __EI(); /* Interrupt enabled */ count = 0; } void FREERUN0_start(void) { IO_TCCS0.bit.STOP = 0; /* bit6 = 0 STOP count enabled */ } __interrupt void FREE_RUN_TIMER0_int(void) { IO_TCCS0.bit.ICLR = 0; /* bit9 = 0 Clearing of ICLR compare match flag */ count++; } Specification of interrupt routine required in vector table #pragma intvect FREE_RUN_TIMER0_int 50 </pre>
Register name.Bit name	Register name.Bit name																																
Control register setting Clock selection»	TCCSH0/TCCSL0 .ECKE																																
Compare interrupt request flag»	.ICLR																																
Compare interrupt request enabled»	.ICRE																																
Counting Operation»	.STOP																																
TCDT clear»	.CLR																																
Count clock»	.CLK3-0																																
Timer data value setting	TCDT0																																
Register name.Bit name	Register name.Bit name																																
Sets an interrupt level.	ICR34																																
I flag setting	(CCR)																																
Register name.Bit name	Register name.Bit name																																
Count operation activation	TCCS0_STOP																																
Register name.Bit name	Register name.Bit name																																
Clearing of interrupt request flag (Any process)	TCCS0.ICLR																																
Variable counting																																	

9. Notes

This section explains notes of the free-run timer.

● Clear Timing of the Free-run Timer

- When a reset is performed (RSTX pin input, watchdog reset, software reset, etc.) , the counter will stop counting after initializing to "00000000_H".
- A software clear (TCCSH:SCLR=1) clears the counter as soon as the clear request is generated. However, in the case of compare match, the counter is cleared in the same timing as the counting up.
- Counter clear operation (software, compare match) will only be enabled while the free-run timer is in operation. To clear the counter while the free-run timer is in stop, you need to write "00000000_H" to the timer count data register.

● Writing to the timer data register

- Always write a value to the free-run timer while the free-run timer is inactive (STOP = "1"), using a word access instruction.

● External clock operation

- The timings of the compare match output and generation of interrupt of the external clock will be the next count clock timing after the compare match. Therefore, in order to the generate compare match output and interrupt, 1 clock (external clock) must at least be input after the compare match.

● Read-modify-write

- Compare clear interrupt flag bits of the timer control register are "1" when read using a read-modify-write instruction.

CHAPTER : OUTPUT COMPARE

This chapter explains the output compare.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Setting
7. Q&A
8. Sample Program
9. Notes

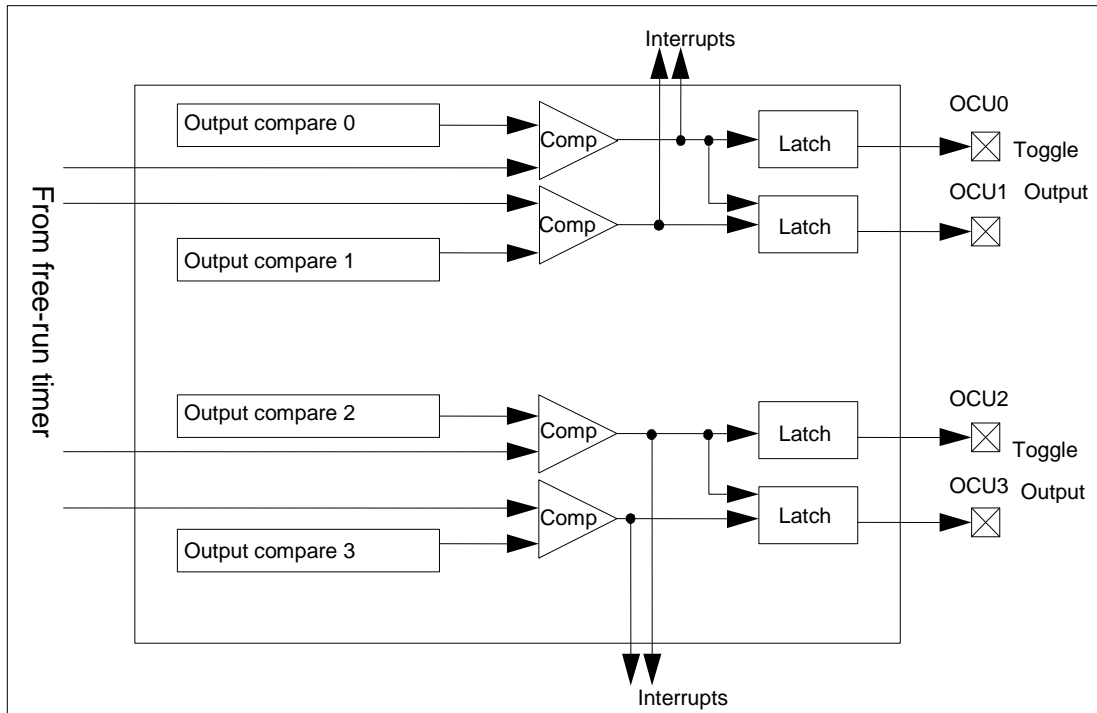
Code : 22_MB91590_HM_E_outputcom_007_20111127

1. Overview

This section explains the overview of the output compare.

The output compare consists of a 32-bit compare register, a compare output latch, and a compare control register. When the 32-bit free-run timer value matches the compare register value, the output level is inverted and an interrupt also can be generated.

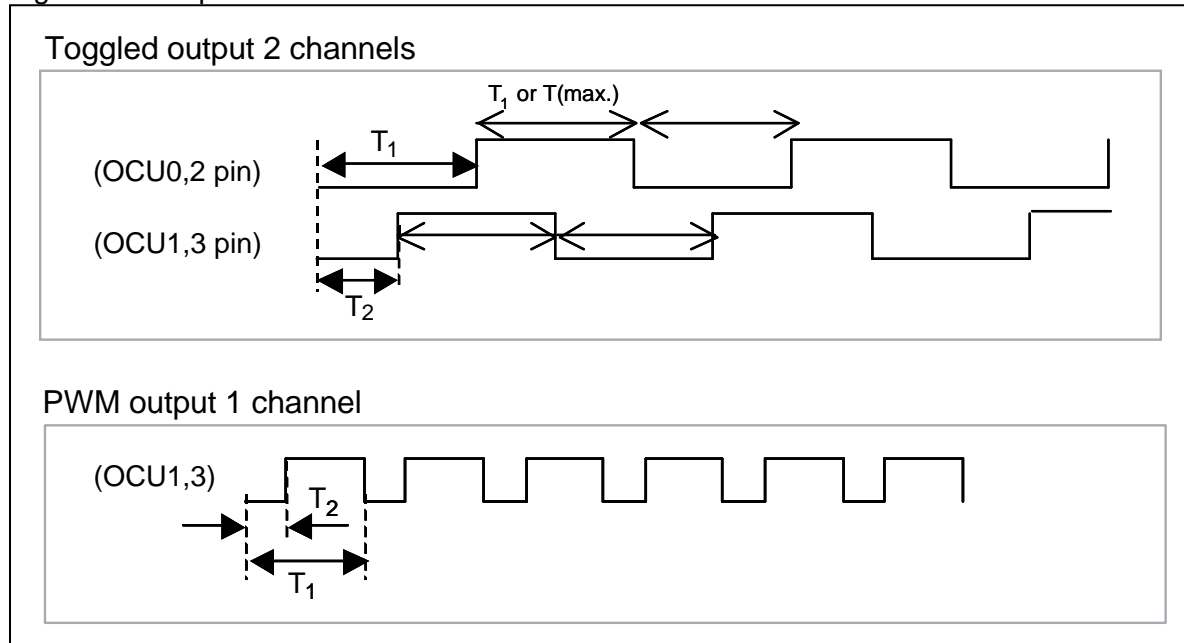
Figure 1-1 Block Diagram (Overview)



2. Features

This section explains the features of the output compare.

Figure 2-1 Output Waveform



- Type : 32-bit compare register × 4 + compare circuit
- Corresponding timer : Free-run timer 0 or 1 is used
- Number : 4 channels
- Operation by compare match
- Pin output value invert (toggle output)
- Interrupt occurrence
- Count accuracy : Peripheral clock (PCLK/2, PCLK/4, PCLK/8, PCLK/16, PCLK/32, PCLK/64, PCLK/128, PCLK/256) (Dependent on the free-run timer)

Note:

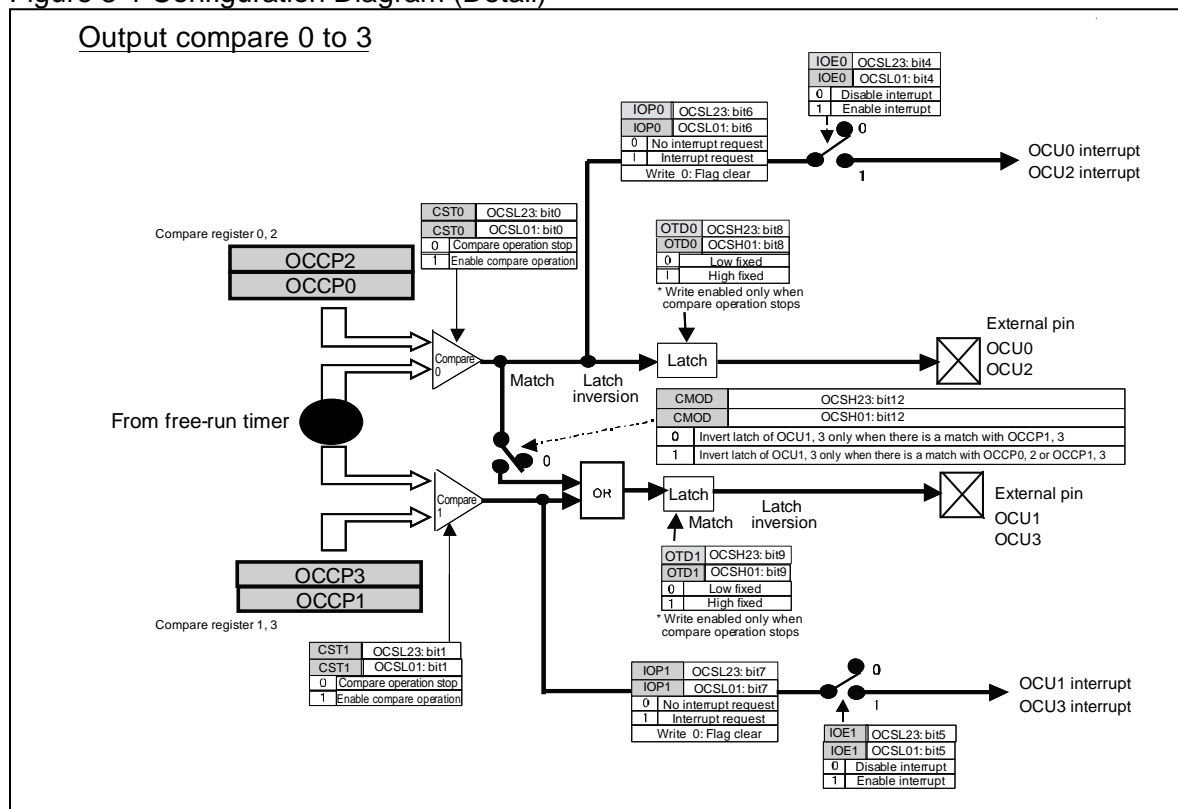
The setting of the peripheral clock (PCLK) divided by 1 is prohibited.

- Toggle change width (T): $1 \times \text{count accuracy to } 100000000_{\text{H}} \times \text{count accuracy}$
- Interrupt : Compare match interrupt
- Others :
 - Output level initial value setting is enabled. ("H"/"L")
 - Unused pins as OCU output can be used as general-purpose ports.
 - Four compare registers can be used for independence.
 - Output pins and interrupt flags correspond to the compare register.
 - Output pins can be inverted with the use of two compare registers. (Function only for OCU1, OCU3)
 - The initial value of each output pin can be set.
 - When the output compare register matches the 32-bit free-run timer, an interrupt can be generated.

3. Configuration Diagram

This section explains the configuration diagram of the output compare.

Figure 3-1 Configuration Diagram (Detail)



4. Registers

This section explains the registers of the output compare.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x02E8	OCCP0				Compare register 0
0x02EC	OCCP1				Compare register 1
0x02F0	OCFS01	Reserved	OCSH01	OCSL01	Free-run timer selection register 01 Output control register 01 upper Output control register 01 lower
0x02F4	OCCP2				Compare register 2
0x02F8	OCCP3				Compare register 3
0x02FC	OCFS23	Reserved	OCSH23	OCSL23	Free-run timer selection register 23 Output control register 23 upper Output control register 23 lower

4.1. Free-run Timer Selection Register : OCFS

The bit configuration of the free-run timer selection register is shown below.

The free-run timer to compare is selected.

■ OCFS01 (Free-run timer selection 01): Address 02F0_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	—	—	SEL1	SEL0
Initial value	—	—	—	—	—	—	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

■ OCFS23 (Free-run timer selection 23): Address 02FC_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	—	—	SEL3	SEL2
Initial value	—	—	—	—	—	—	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

[bit7 to bit2] - : Undefined

Writing to these bits does not affect the operation of the output compare.

[bit1, bit0] SEL_n : Free-run timer selection

SEL _n (n=0~3)	Operating mode
0	Free-run timer 0
1	Free-run timer 1

4.2. Output Control Register (Upper Bit) : OCSH

The bit configuration of the output control register (Upper bit) is shown below.

This register is to control operations of the output compare 0, 1, 2, 3.

■ OCSH01 (Output compare 01): Address 02F2_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	—	—	—	CMOD	Reserved	Reserved	OTD1	OTD0
Initial value	—	—	—	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W0	R/W0	R,W	R,W

■ OCSH23 (Output compare 23): Address 02FE_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	—	—	—	CMOD	Reserved	Reserved	OTD3	OTD2
Initial value	—	—	—	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R/W	R/W0	R/W0	R,W	R,W

[bit15 to bit13] - : Undefined

Writing to these bits does not affect the operation of the output compare.

[bit12] CMOD : Compare mode

CMOD	Operating mode
0	Independent operation (OCU0 to OCU3 pins output level invert operation is independent.) <ul style="list-style-type: none"> OCU0, OCU2 pins: When the free-run timer value corresponds to the compare register 0, 2 (OCCP0, OCCP2) value, the output is inverted. OCU1, OCU3 pins: When the free-run timer value corresponds to the compare register 1, 3 (OCCP1, OCCP3) value, the output is inverted. The comparison target free-run timer is selected by OCFS01 and OCFS23 registers.
1	Coordinated operation <ul style="list-style-type: none"> OCU0, OCU2 pins: When the free-run timer value corresponds to the compare register 0, 2 (OCCP0, OCCP2), the output is inverted. OCU1, OCU3 pins: When the free-run timer value corresponds to either the compare register (0 or 1) or (2 or 3), the output is inverted. The comparison target free-run timer is selected by OCFS01 and OCFS23 registers.

· When the compare register 0, 1 and 2, 3 have the same value, the operation is the same one as when only one compare register is used.

[bit11, bit10] Reserved

Always set these bits to "0".

[bit9] OTD : Pin level setting (Output compare 1,3)

This bit specifies the pin output level (initial value) when output from OCU1, OCU3 pins is allowed.

OTD1, 3	Operation
0	OCU1, OCU3 pins output level (initial value) is set to "L".
1	OCU1, OCU3 pins output level (initial value) is set to "H".

When output from OCU1, OCU3 pins is performed, the setting of a general-purpose port is required. The setting should be performed after the compare operation is stopped. With the reading operation, the output compare pin output is read.

[bit8] OTD : Pin level setting (Output compare 0, 2)

This bit specifies the pin output level (initial value) when output from OCU0, OCU2 pins output is enabled.

OTD0, 2	Operation
0	OCU0, OCU2 pins output level (initial value) is set to "L".
1	OCU0, OCU2 pins output level (initial value) is set to "H".

When OCU0, OCU2 pins output is performed, the setting of a general-purpose port is required. The setting should be performed after the compare operation is stopped. With the reading operation, the output compare pin output is read.

4.3. Output Control Register (Lower Bit) : OCSL

The bit configuration of the output control register (Lower bit) is shown below.

This register is to control operations of the output compare 0, 1, 2, 3.

■ **OCSL01 (Output compare 01): Address 02F3_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	IOP1	IOP0	IOE1	IOE0	—	—	CST1	CST0
Initial value	0	0	0	0	1	1	0	0
Attribute	R(RM1),W	R(RM1),W	R/W	R/W	R1,WX	R1,WX	R/W	R/W

■ **OCSL23 (Output compare 23): Address 02FF_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	IOP3	IOP2	IOE3	IOE2	—	—	CST3	CST2
Initial value	0	0	0	0	1	1	0	0
Attribute	R(RM1),W	R(RM1),W	R/W	R/W	R1,WX	R1,WX	R/W	R/W

[bit7] IOP : Interrupt request flag (output compare 1, 3)

IOP1, 3	State	
	Read	Write
0	Without interrupt request	Flag (IOP1, IOP3) is cleared.
1	With interrupt request	No effect on operations

- This bit becomes "1" when the count value of free-run timer (TCDT) corresponds to the output compare register (OCCP1, OCCP3).
- The interrupt request becomes enabled when the interrupt enable bit (IOE1, IOE3) is "1".

[bit6] IOP : Interrupt request flag (Output compare 0, 2)

IOP0, 2	State	
	Read	Write
0	Without interrupt request	Flag (IOP0, IOP2) is cleared.
1	With interrupt request	No effect on operations

- This bit becomes "1" when the count value of free-run timer (TCDT) corresponds to the output compare register (OCCP0, OCCP2).
- The interrupt request becomes enabled when the interrupt enable bit (IOE0, IOE2) is "1".

[bit5] IOE : Interrupt request enable (Output compare 1, 3)

IOE1, 3	State
0	Output compare 1, 3 interrupt request is disabled.
1	Output compare 1, 3 interrupt request is enabled.

- This bit is used to "enable" the output compare interrupt for the compare register 1, 3.
- While "1" is written to this bit, if the compare match interrupt flag bit (IOP1, IOP3) is set, the output compare interrupt is generated.

[bit4] IOE : Interrupt request enable (Output compare 0, 2)

IOE0, 2	State
0	Output compare 0, 2 interrupt request is disabled.
1	Output compare 0, 2 interrupt request is enabled.

- This bit is used to "enable" the output compare interrupt for the compare register 0, 2.
- While "1" is written to this bit, if the compare match interrupt flag bit (IOP0, IOP2) is set, the output compare interrupt is generated.

[bit3, bit2] - : Undefined

Writing to these bits does not affect the operation of the output compare.

[bit1] CST : Operation enable (Output compare 1, 3)

CST1,3	Operation
0	Operation of the output compare 1, 3 is stopped.
1	Operation of the output compare 1, 3 is enabled.

- This bit enables the compare operation for the count value of free-run timer (TCDT) and the output compare register.
- The compare registers (OCCP1, OCCP3) must be set with values before the compare operation is enabled.
- Because the output compare is synchronized with the free-run timer, when the free-run timer is stopped, the output compare also is stopped.

[bit0] CST : Operation enable (Output compare 0, 2)

CST0, 2	Operation
0	Operation of the output compares 0, 2 is stopped.
1	Operation of the output compares 0, 2 is enabled.

- This bit enables the compare operation for the count value of free-run timer (TCDT) and the output compare register.
- The compare registers (OCCP0, OCCP2) must be set with values before the compare operation is enabled.
- Because the output compare is synchronized with the free-run timer, when the free-run timer is stopped, the output compare operation also is stopped.

4.4. Compare Register : OCCP

The bit configuration of the compare register is shown below.

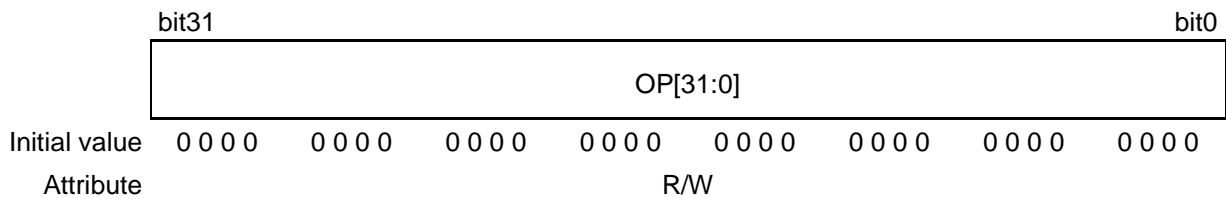
These registers set the values to be compared with the 32-bit free-run timer count value.

■ **OCCP0 (Output compare 0): Address 02E8_H (Access: Word)**

■ **OCCP1 (Output compare 1): Address 02EC_H (Access: Word)**

■ **OCCP2 (Output compare 2): Address 02F4_H (Access: Word)**

■ **OCCP3 (Output compare 3): Address 02F8_H (Access: Word)**



- The compare registers OCCP0 to OCCP3 are compared with the count value of free-run timer (TCDT).
- When the OCCP register values correspond to the 32-bit free-run timer value, a compare signal is generated and an output compare interrupt flag is set. The compare value is reflected after the write instruction is completed. Therefore, the compare value change during operation might generate an interrupt twice per one free-run counting if the newly written compare value is larger than the previous compare value.
- In addition, when the corresponding OCU of the port function register (PFR) is set and output is enabled, the output level corresponding to the compare register is inverted.
- For access to this register, use a word access instruction.

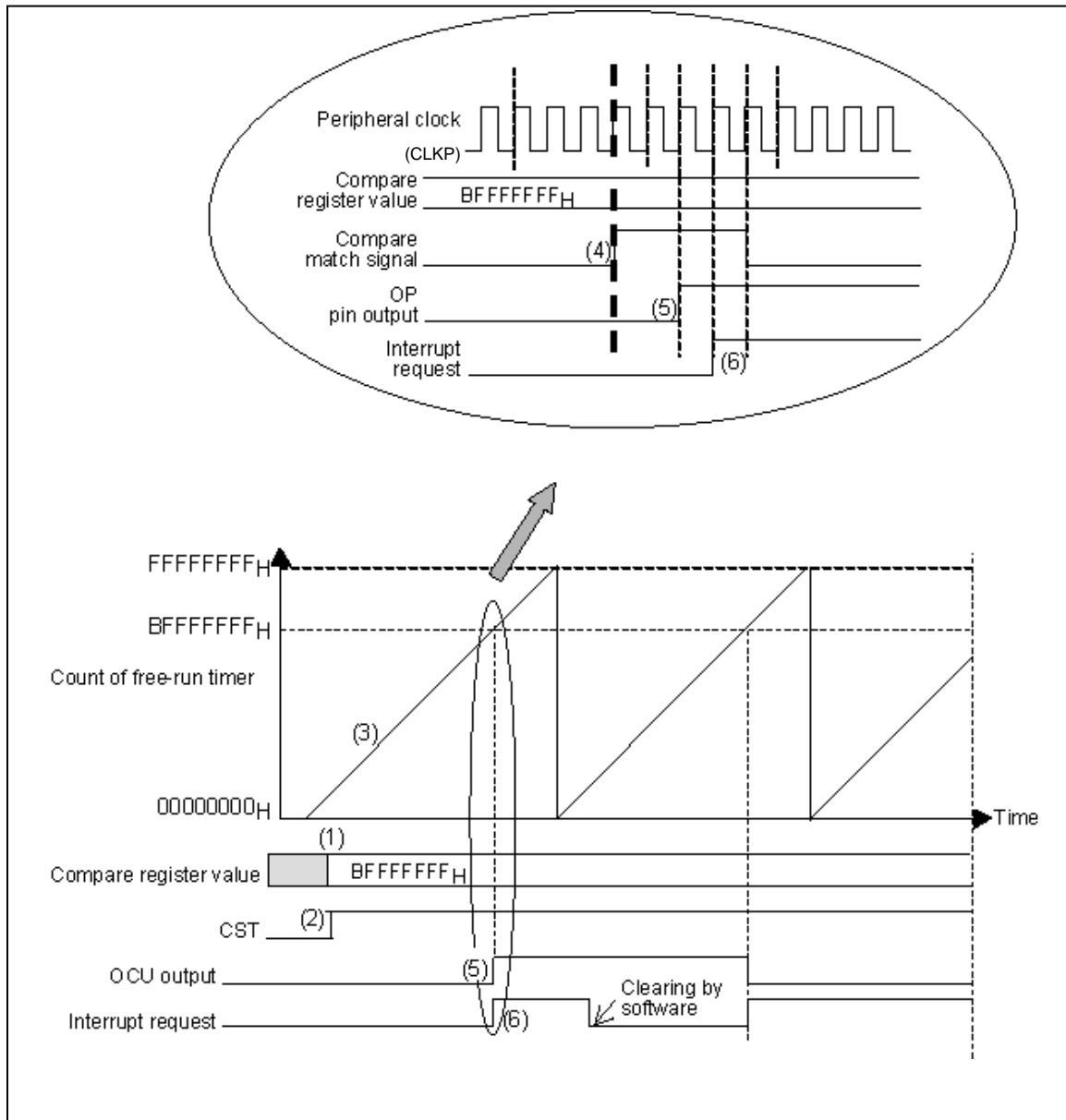
5. Operation

This section explains the operations of the output compare.

- 5.1. Output Compare Output (Independent Invert) CMOD = "0"
- 5.2. Output Compare Output (Coordinated Invert) CMOD = "1"
- 5.3. Output Compare Operation Timing

5.1. Output Compare Output (Independent Invert) CMOD = "0"

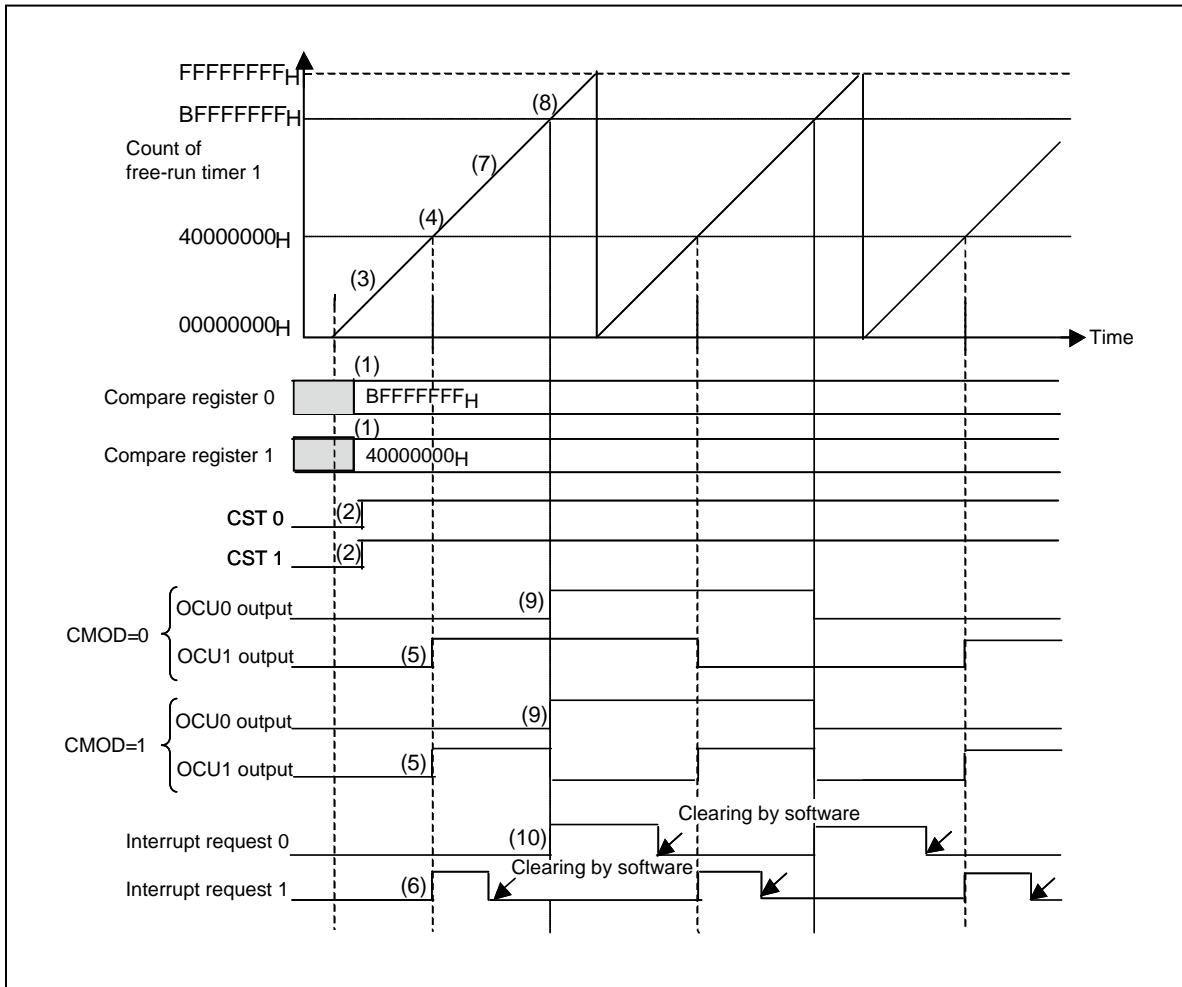
This section explains the output compare output (independent invert).



- (1) A compare value is set.
- (2) Compare operation is enabled (CST = 1)
- (3) Free-run timer count up (example of one count per four clocks)
- (4) A free-run timer value is compared with a compare value and they match (Compare match)
- (5) OCU output level is inverted.
- (6) A compare match interrupt request is generated.

5.2. Output Compare Output (Coordinated Invert) CMOD = "1"

This section explains the output compare output (coordinated invert).



- (1) Values of Compare 0 and Compare 1 are set.
- (2) Compare operation is enabled.
- (3) Free-run timer count up
- (4) Compare 1 match
- (5) OCU1 output level is inverted.
- (6) Compare1 match interrupt
- (7) Free-run timer count up
- (8) Compare 0 match
- (9) OCU0 output level is inverted.
When CMOD = 1, OCU1 output level also is inverted.
- (10) Compare 0 match interrupt

5.3. Output Compare Operation Timing

This section explains the output compare operation timing.

With the use of two pairs of compare registers, the output level can be changed. (For CMOD = 1)

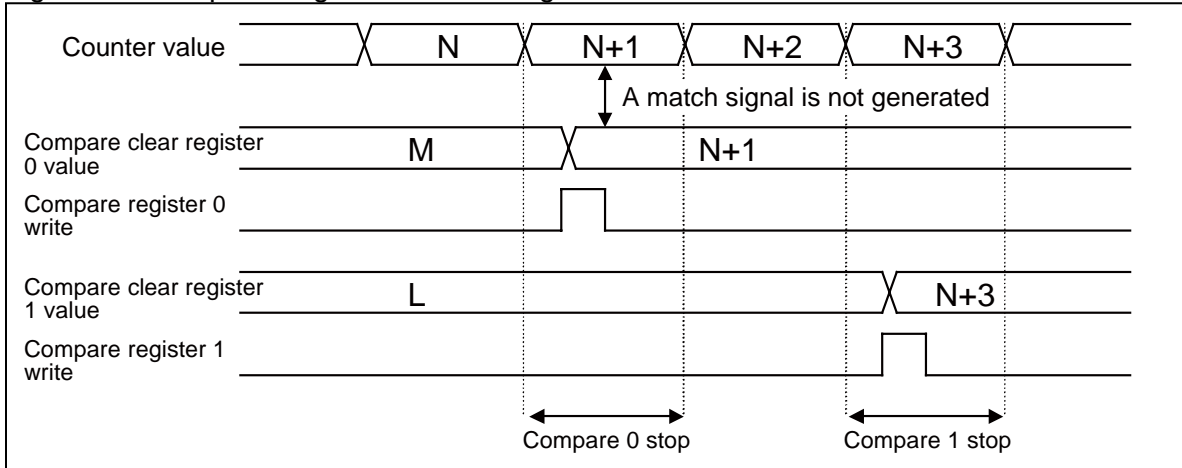
The output compare can invert the output as well as generate an interrupt when the free-run timer value matches the specified compare register value and a compare match signal is generated. The output invert timing on compare match is synchronized with the counter count timing.

5.3.1. Compare Register Write

Compare register write is shown below.

The compare operation with the counter value is not performed on compare register rewrite.

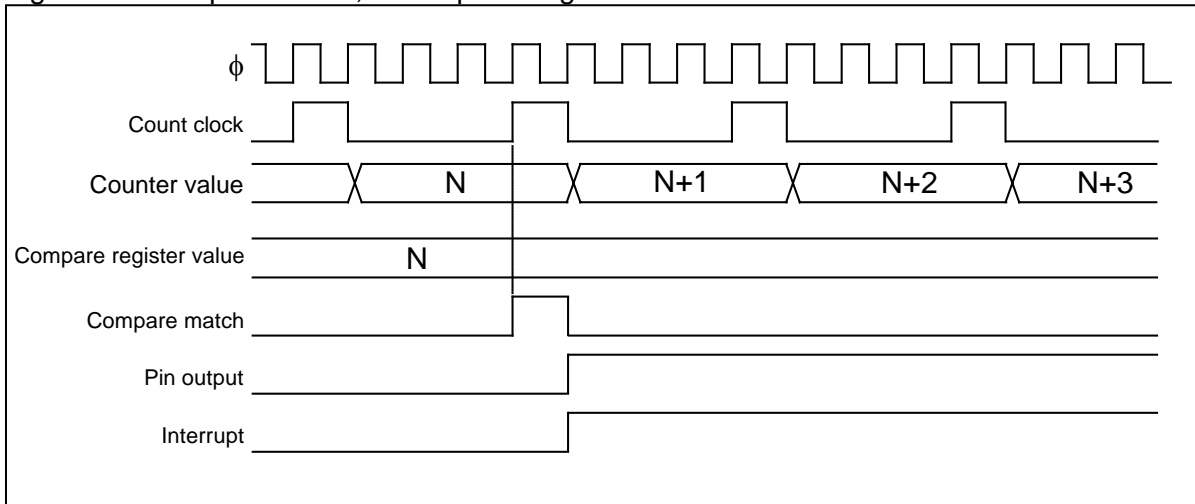
Figure 5-1 Compare Register Write Timing



5.3.2. Compare match, Interrupt

Compare match, interrupt are shown below.

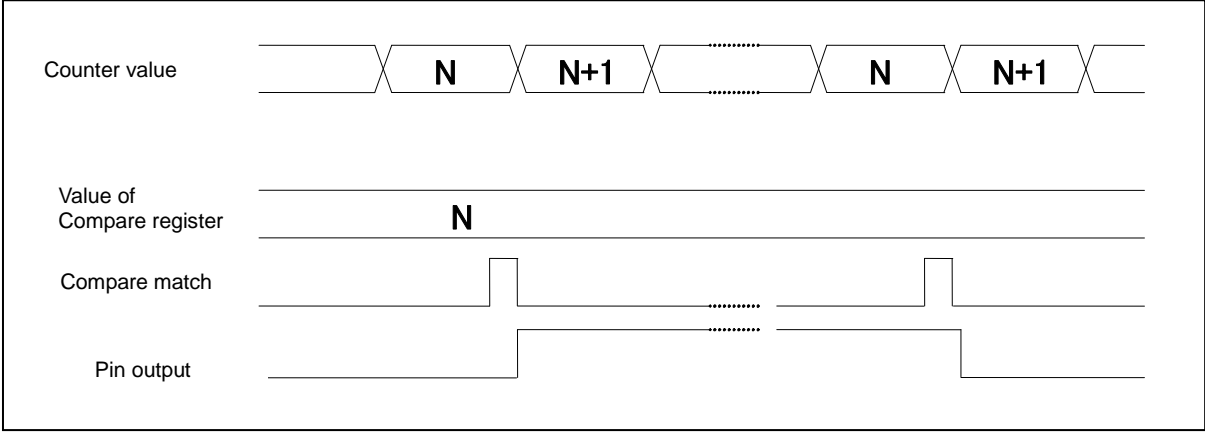
Figure 5-2 Compare match, Interrupt Timing



5.3.3. Pin Output

This section shows the pin output.

Figure 5-3 Pin Output Timing



6. Setting

This section explains settings of the output compare.

Table 6-1 Configuration Necessary for Use of Output Compare

Configuration	Register to be configured	Setting Method
Setting of the free-run timer	See "CHAPTER: Free-run Timer".	-
Setting of the compare value	Compare register: (OCCPx)	See 7.1.
Setting of the compare mode	Output control register (OCSHxx, OCSLxx)	See 7.2.
Compare operation stop		See 7.3.
Setting of the compare pin output initial level		See 7.4.
Setting of OCU0 to OCU3 pins to output	Set each pin for peripheral output. See "CHAPTER: I/O PORTS", for the setting method.	
The free-run timer clear	Timer control register (TCCS) See "CHAPTER: Free-run Timer".	See 7.6.
Compare operation enable (activation)	Output control register (OCSHxx, OCSLxx)	See 7.7.

Table 6-2 Items Necessary for Interrupt Execution

Configuration	Register to be configured	Setting Method
Setting of output compare interrupt vector and output compare interrupt level	See "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".	See 7.8.
Setting of output compare interrupt · Interrupt request clear · Interrupt request enable	Output control register (OCSHxx, OCSLxx)	See 7.10.

7. Q&A

This section explains Q&A of the output compare.

- 7.1. How Can I Set the Compare Value?
- 7.2. How Can I Set the Compare Mode? (Example with OCU1)
- 7.3. How Can I Enable/Disable the Compare Operation? (Example with OCU0,1)
- 7.4. How Can I Set the Compare Pin Output Initial Level? (Example with OCU0,1)
- 7.5. How Can I Set the Compare Pin OCU0 to OCU1 for Output?
- 7.6. How Can I Clear the Free-run Timer?
- 7.7. How Can I Enable the Compare Operation?**
- 7.8. Interrupt Related Register?
- 7.9. Interrupt Type?
- 7.10. How Can I Enable the Interrupt?
- 7.11. Calculation Method for the Compare Value?

7.1. How Can I Set the Compare Value?

This section explains how to set the compare value.

Write the compare value to the compare register OCCPx.

7.2. How Can I Set the Compare Mode? (Example with OCU1)

This section explains how to set the compare mode.

Set with the compare mode bit (OCSH01:CMOD)

Operation	Compare mode bit
To invert the OCU1, OCU3 pins output when the free-run timer value matches the compare register 1 (OCCP1)	Set (OCSH01:CMOD) to "0".
To invert the OCU1 pin output when the free-run timer value matches either the compare register 0 (OCCP0) or the compare register 1 (OCCP1)	Set (OCSH01:CMOD) to "1".

Regardless of the CMOD bit, the operation is as follows:

- Regardless of the compare mode bit (OCSH01:CMOD) setting, the OCU0 output is inverted when the free-run timer value matches the compare register (OCCP0).

7.3. How Can I Enable/Disable the Compare Operation? (Example with OCU0, OCU1)

This section explains how to enable/disable the compare operation.

Set the compare operation enable bit (OCSL01:CST0), (OCSL01:CST1).

Operation	Compare	Compare operation enable bit
To stop (disable) the compare operation	Compare 0	Set (OCSL01:CST0) to "0".
	Compare 1	Set (OCSL01:CST1) to "0".
To enable the compare operation	Compare 0	Set (OCSL01:CST0) to "1".
	Compare 1	Set (OCSL01:CST1) to "1".

7.4. How Can I Set the Compare Pin Output Initial Level? (Example with OCU0, OCU1)

This section explains how to set the compare pin output initial level.

Set the compare pin output specification bit (OCSH01:OTD0), (OCSH01:OTD1).

Operation	Compare pin output specification bit
To set the compare 0 pin to "L"	Set (OCSH01:OTD0) to "0".
To set the compare 0 pin to "H"	Set (OCSH01:OTD0) to "1".
To set the compare 1 pin to "L"	Set (OCSH01:OTD1) to "0".
To set the compare 1 pin to "H"	Set (OCSH01:OTD1) to "1".

7.5. How Can I Set the Compare Pin OCU0, OCU1 for Output?

This section explains how to set the compare pin OCU0, OCU1 for output.

Set the pin for peripheral output. For setting method, see "CHAPTER: I/O PORTS".

7.6. How Can I Clear the Free-run Timer?

This section explains how to clear the free-run timer.

Set the clear bit (TCCS:SCLR) of the free-run timer used.

Operation	Clear bit (SCLR)
To clear the free-run timer	Write "1".

For other methods, see "CHAPTER: FREE-RUN TIMER".

7.7. How Can I Enable the Compare Operation?

This section explains how to enable the compare operation.

Set the compare operation enable bit (OCSL01:CST0, OCSL01:CST1, OCSL23:CST2, OCSL23:CST3).

See "7.3 How Can I Enable/Disable the Compare Operation? (Example with OCU0, OCU1)".

7.8. Interrupt Related Register?

This section explains the interrupt related register.

Both the output compare interrupt vector and the output compare interrupt level are set.

The relation among the output compare number, interrupt level, and interrupt vector is shown in the table below:

For the interrupt level and interrupt vector, see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

Number	Interrupt Vector (Default)	Interrupt Level Setting Bit (ICR[4:0])
Output compare 0/1	#58 Address: 0FFF14 _H	Interrupt level register (ICR42) Address: 0046A _H
Output compare 2/3	#59 Address: 0FFF10 _H	Interrupt level register (ICR43) Address: 0046B _H

The interrupt request flag (OCSL01:IOP0, OCSL01:IOP1, OCSL23:IOP2, OCSL23:IOP3) are not cleared automatically. Before recovering from the interrupt process, write "0" to each bit to clear with software.

7.9. Interrupt Type?

This section explains the interrupt type.

The interrupt has one type only. It is generated by a compare match.

7.10. How Can I Enable the Interrupt?

This section explains how to enable the interrupt.

Set the interrupt request enable bit (OCSL01:IOE0, OCSL01:IOE1, OCSL23:IOE2, OCSL23:IOE3) for the interrupt enable.

Operation	Interrupt request enable bit (OCSL01:IOE0, OCSL01:IOE1, OCSL23:IOE2, OCSL23:IOE3)
Interrupt disable	Set "0".
Interrupt enable	Set "1".

Set the interrupt request flag bit (OCSL01:IOP0, OCSL01:IOP1, OCSL23:IOP2, OCSL23:IOP3) for the interrupt request clear.

Operation	Interrupt request flag bit (OCSL01:IOP0, OCSL01:IOP1, OCSL23:IOP2, OCSL23:IOP3)
Interrupt request clear	Write "0".

7.11. Calculation Method for the Compare Value?

This section explains the calculation method for the compare value.

7.11.1. Toggle Output Pulse

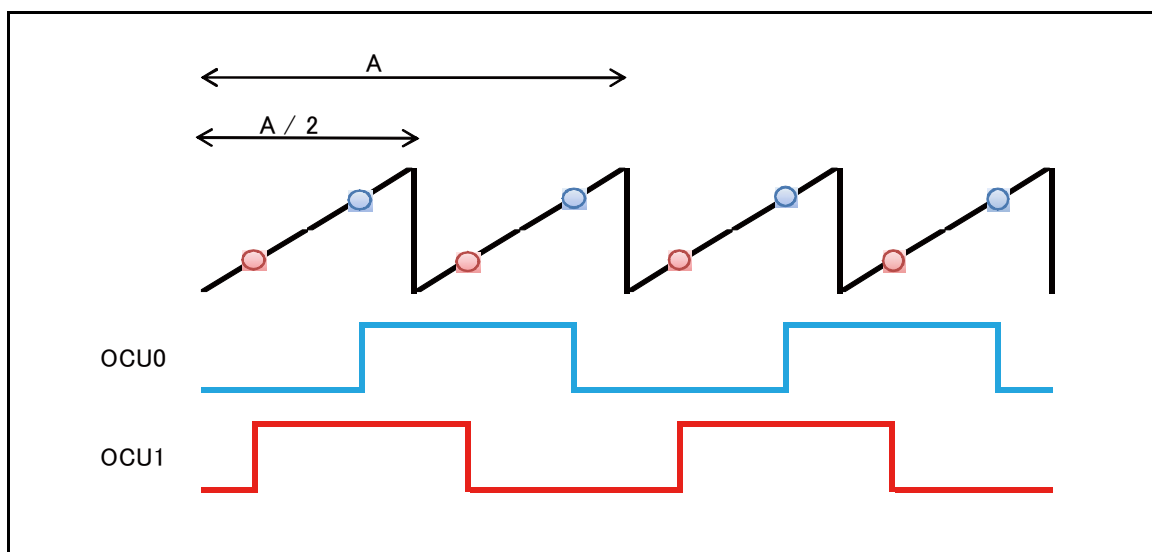
7.11.2. PWM Output

7.11.1. Toggle Output Pulse

This section explains the toggle output pulse.

(Example) To calculate a two-phase pulse with OCU0, OCU1, cycle: A, and one-fourth phase difference

- FreeRunTimer.CPCLR = $(A/2) - 1$
- Output Compare.OCCP0 = $(A/2) \times (3/4) - 1$
- Output Compare.OCCP1 = $(A/2) \times (1/4) - 1$
- Output Compare.OCSH01.CMOD = 0
are setting.

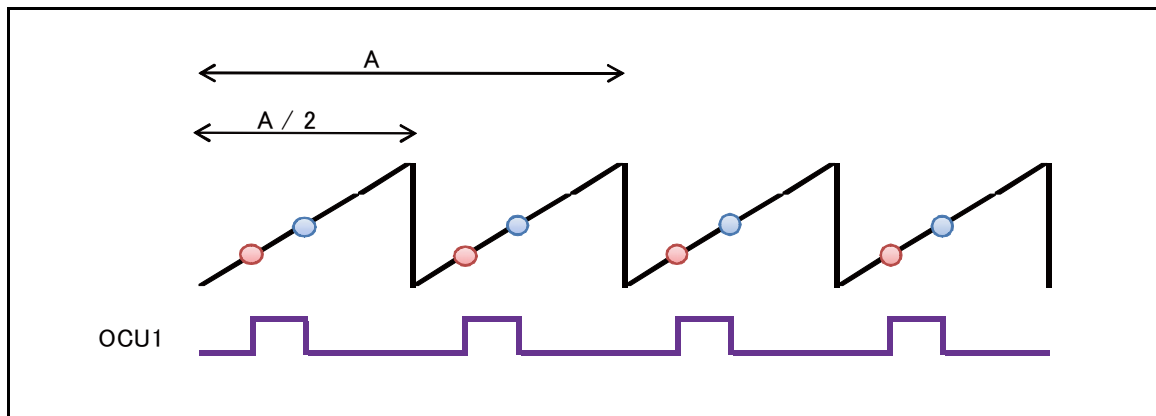


7.11.2. PWM Output

This section explains the PWM output.

(Example) To calculate the PWM with OCU0, OCU1, cycle: A, and duty 1/4

- FreeRunTimer.CPCLR = $(A/2)-1$
- Output Compare.OCCP0 = $(A/2) \times (1/2) - 1$
- Output Compare.OCCP1 = $(A/2) \times (1/4) - 1$
- Output Compare.OCSH01.CMOD = 1
are setting.



8. Sample Program

This section explains a sample program.

<p>Configuration procedure example 1</p> <p>.2 channels independent output Compare operation (7FFF, BFFF) Interrupt occurrence compare no clear</p> <p>1. Initial setting</p> <p>- Free-run timer ch.1 control</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Setting of control register Clock selection>></td> <td>TCCSH1.TCCSL11 .ECKE</td> </tr> <tr> <td>Compare interrupt request flag>></td> <td>.ICLR</td> </tr> <tr> <td>Compare interrupt request enable>></td> <td>.ICRE</td> </tr> <tr> <td>Counting Operation>></td> <td>.STOP</td> </tr> <tr> <td>TCDT clear>></td> <td>.SCLR</td> </tr> <tr> <td>Count clock>></td> <td>.CLK3-0</td> </tr> <tr> <td>Setting of the timer data value</td> <td>TCDT1</td> </tr> </tbody> </table> <p>- Port</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Port OCU0 output setting</td> <td>See "CHAPTER: I/O PORTS"</td> </tr> <tr> <td>Port OCU1 output setting</td> <td>PORTS</td> </tr> </tbody> </table> <p>- Output compare control</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Free-run timer selection</td> <td>OCFS01</td> </tr> <tr> <td>Setting of control register</td> <td>OCSH01.OCSL01</td> </tr> <tr> <td>Pin output level invert operation>></td> <td>.CMOD</td> </tr> <tr> <td>Pin output level specification>></td> <td>.OTD1,OTD0</td> </tr> <tr> <td>Interrupt request flag>></td> <td>.IOP1,IOP0</td> </tr> <tr> <td>Interrupt request enable>></td> <td>.IOE1,IOE0</td> </tr> <tr> <td>Operation enable setting>></td> <td>.CST1,CST0</td> </tr> <tr> <td>Setting of compare value ch0</td> <td>OCCP0</td> </tr> <tr> <td>Setting of compare value ch1</td> <td>OCCP1</td> </tr> </tbody> </table> <p>- Interrupt relation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Setting of an interrupt level.</td> <td>ICR42</td> </tr> <tr> <td></td> <td>ICR43</td> </tr> <tr> <td>Setting of I flag</td> <td>(CCR)</td> </tr> </tbody> </table> <p>2. Activation</p> <p>- Output compare activation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Interrupt control</td> <td>OCSL01.IOE1</td> </tr> <tr> <td>Compare operation activation</td> <td>OCSL01.CST1 OCSL01.CST0</td> </tr> </tbody> </table> <p>- Free-run timer ch1 activation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Counting operation activation</td> <td>TCCS1.STOP</td> </tr> </tbody> </table> <p>3. Interrupt</p> <p>- Interrupt process</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Clearing of interrupt request flag (any process)</td> <td>OCSL01.IOP0</td> </tr> <tr> <td>.....</td> <td></td> </tr> <tr> <td>Clearing of interrupt request flag (any process)</td> <td>OCSL01.IOP1</td> </tr> <tr> <td>.....</td> <td></td> </tr> </tbody> </table> <p>4. Interrupt vector</p> <p>- Setting of the vector table</p> <p>(Note) Clock-related setting and setting of __set_ll(numerical value) in advance are required. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".</p>	Register name.bit name	Register name.bit name	Setting of control register Clock selection>>	TCCSH1.TCCSL11 .ECKE	Compare interrupt request flag>>	.ICLR	Compare interrupt request enable>>	.ICRE	Counting Operation>>	.STOP	TCDT clear>>	.SCLR	Count clock>>	.CLK3-0	Setting of the timer data value	TCDT1	Register name.bit name	Register name.bit name	Port OCU0 output setting	See "CHAPTER: I/O PORTS"	Port OCU1 output setting	PORTS	Register name.bit name	Register name.bit name	Free-run timer selection	OCFS01	Setting of control register	OCSH01.OCSL01	Pin output level invert operation>>	.CMOD	Pin output level specification>>	.OTD1,OTD0	Interrupt request flag>>	.IOP1,IOP0	Interrupt request enable>>	.IOE1,IOE0	Operation enable setting>>	.CST1,CST0	Setting of compare value ch0	OCCP0	Setting of compare value ch1	OCCP1	Register name.bit name	Register name.bit name	Setting of an interrupt level.	ICR42		ICR43	Setting of I flag	(CCR)	Register name.bit name	Register name.bit name	Interrupt control	OCSL01.IOE1	Compare operation activation	OCSL01.CST1 OCSL01.CST0	Register name.bit name	Register name.bit name	Counting operation activation	TCCS1.STOP	Register name.bit name	Register name.bit name	Clearing of interrupt request flag (any process)	OCSL01.IOP0		Clearing of interrupt request flag (any process)	OCSL01.IOP1		<p>Program example 1</p> <pre> void OUTPUT01_sample(void) { freerun1_initial(); OUTPUT01_initial(); OUTPUT01_start(); freerun1_start(); } void freerun1_initial(void) { IO_TCCS1.word = 0x0041; /* Setting value =0000_0000_0100_0001 */ /* bit15 = 0 ECKE internal clock source */ /* bit14 -10 =0 Reserved Bit */ /* bit9 = 0 ICLR compare interrupt flag clear */ /* bit8 = 0 ICLR interrupt disable */ /* bit7 = 0 Reserved Bit */ /* bit6 = 1 STOP Counting disable */ /* bit5 = 0 Reserved Bit */ /* bit4 = 0 SCLR free-run timer value (no) initialization */ /* bit3-0 = 0001 CLK3-0 count clock PCLK/2=32MHz/2 */ IO_TCDT1 = 0x0000; /* timer data value initialization */ } void OUTPUT01_initial(void) { PORT_SETTING_OCU0_OUT(); /* Set the OCU0 pin for peripheral input. */ PORT_SETTING_OCU1_OUT(); /* Set the OCU1 pin for peripheral input. */ IO_OCFS01.hword = 0x0003; /* Select the free-run timer 1. */ IO_OCS01.hword = 0xEC0C; /* Setting value =1110_1100_0000_1100 */ /* bit15-13 = 111 Undefined bit */ /* bit12 = 0 CMOD ch.0, ch.1 level invert */ /* bit11-10 = 11 Undefined bit */ /* bit9-8 = 00 OTD1,OTD0 Compare pin output 0 */ /* bit7-6 = 00 IOP1,IOP0 Output compare no match */ /* bit5-4 = 00 IOE1,IOE0 Output compare interrupt disable */ /* bit3-2 = 11 Undefined bit */ /* bit1-0 = 00 CST1,CST0 Compare operation disable */ IO_OCCP0 = BFFF /* Setting of compare register ch.0 */ IO_OCCP1 = 7FFF /* Setting of compare register ch.1 */ IO_ICR[42].byte = 0x10; /* Output compare ch.0 interrupt level setting (any value) */ IO_ICR[43].byte = 0x10; /* Output compare ch.1 interrupt level setting (any value) */ __EI(); /* Interrupt enable */ } void OUTPUT01_start(void) { IO_OCS01.hword = 0xEC3C; /* bit5-4 = 11 IOE1,IOE0 Output compare interrupt enable */ IO_OCS01.hword = 0xEC3F; /* bit1-0 = 11 CST1,CST0 Compare operation enable */ } void freerun1_start(void) { IO_TCCS1.bit.STOP = 0; /* bit4 = 0 STOP Counting enable */ } __interrupt void INPUT0_int(void) { IO_OCSL01.byte &= 0xBF; /* bit6 = 0 IOP0 Clearing of interrupt flag */ } __interrupt void INPUT1_int(void) { IO_OCSL01.byte &= 0x7F; /* bit7 = 0 IOP1 Clearing of interrupt flag */ } </pre> <p>Interrupt routine specification with the vector table is required. #pragma intvect OUTPUT0_int 58 #pragma intvect OUTPUT1_int 59</p>
Register name.bit name	Register name.bit name																																																																						
Setting of control register Clock selection>>	TCCSH1.TCCSL11 .ECKE																																																																						
Compare interrupt request flag>>	.ICLR																																																																						
Compare interrupt request enable>>	.ICRE																																																																						
Counting Operation>>	.STOP																																																																						
TCDT clear>>	.SCLR																																																																						
Count clock>>	.CLK3-0																																																																						
Setting of the timer data value	TCDT1																																																																						
Register name.bit name	Register name.bit name																																																																						
Port OCU0 output setting	See "CHAPTER: I/O PORTS"																																																																						
Port OCU1 output setting	PORTS																																																																						
Register name.bit name	Register name.bit name																																																																						
Free-run timer selection	OCFS01																																																																						
Setting of control register	OCSH01.OCSL01																																																																						
Pin output level invert operation>>	.CMOD																																																																						
Pin output level specification>>	.OTD1,OTD0																																																																						
Interrupt request flag>>	.IOP1,IOP0																																																																						
Interrupt request enable>>	.IOE1,IOE0																																																																						
Operation enable setting>>	.CST1,CST0																																																																						
Setting of compare value ch0	OCCP0																																																																						
Setting of compare value ch1	OCCP1																																																																						
Register name.bit name	Register name.bit name																																																																						
Setting of an interrupt level.	ICR42																																																																						
	ICR43																																																																						
Setting of I flag	(CCR)																																																																						
Register name.bit name	Register name.bit name																																																																						
Interrupt control	OCSL01.IOE1																																																																						
Compare operation activation	OCSL01.CST1 OCSL01.CST0																																																																						
Register name.bit name	Register name.bit name																																																																						
Counting operation activation	TCCS1.STOP																																																																						
Register name.bit name	Register name.bit name																																																																						
Clearing of interrupt request flag (any process)	OCSL01.IOP0																																																																						
.....																																																																							
Clearing of interrupt request flag (any process)	OCSL01.IOP1																																																																						
.....																																																																							

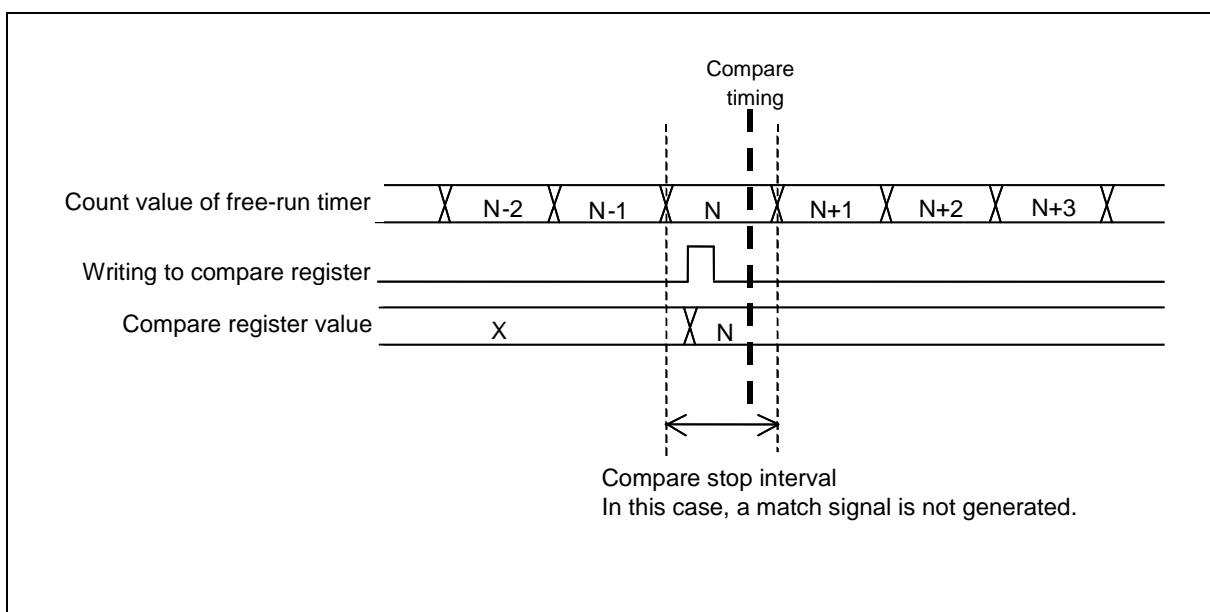
Configuration procedure example 2	Program example 2																																																						
<p>.Compare for two pairs Output of ch1 Compare operation (7FFF, BFFF) Compare is cleared with a cycle of a larger compare value. Interrupt occurrence</p> <p>1. Initial setting</p> <p>- Control of free-run timer ch.1</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Setting of control register Clock selection>></td> <td>TCCSH1.TCCSL1 .ECKE</td> </tr> <tr> <td>Compare interrupt request flag>> Compare interrupt request enable>></td> <td>.ICLR .ICRE</td> </tr> <tr> <td>Counting Operation>></td> <td>.STOP</td> </tr> <tr> <td>TCDT clear>> Count clock>></td> <td>.SCLR .CLK3-0</td> </tr> <tr> <td>Setting of the timer data value</td> <td>TCDT1</td> </tr> </tbody> </table> <p>- Port</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Port OCU1 output setting</td> <td>See "CHAPTER: I/O Port".</td> </tr> </tbody> </table> <p>- Output compare control</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Free-run timer selection Setting of control register</td> <td>OCFS01 OCSS01,OCCL01</td> </tr> <tr> <td>Pin output level invert operation>></td> <td>.CMOD</td> </tr> <tr> <td>Pin output level specification>> Interrupt request flag>> Interrupt request enable>></td> <td>.OTD1,OTD0 .IOP1,IOP0 .IOE1,IOE0</td> </tr> <tr> <td>Operation enable setting>> Setting of the compare value ch0 Setting of the compare value ch1</td> <td>.CST1,CST0 OCCP0 OCCP1</td> </tr> </tbody> </table> <p>- Interrupt relation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Setting of an interrupt level.</td> <td>ICR42 ICR43</td> </tr> <tr> <td>Setting of I flag</td> <td>(CCR)</td> </tr> </tbody> </table> <p>2. Activation</p> <p>- Output compare activation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Interrupt control</td> <td>OCSL01.IOE1</td> </tr> <tr> <td>Compare operation activation</td> <td>OCSL01.CST1 OCSL01.CST0</td> </tr> </tbody> </table> <p>- Free-run timer ch1 activation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Counting operation activation</td> <td>TCCS1.STOP</td> </tr> </tbody> </table> <p>3. Interrupt</p> <p>- Interrupt process</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Clearing of interrupt request flag (any process)</td> <td>OCSL01.IOP0</td> </tr> <tr> <td>.....</td> <td></td> </tr> <tr> <td></td> <td></td> </tr> <tr> <td></td> <td></td> </tr> <tr> <td></td> <td></td> </tr> </tbody> </table> <p>4. Interrupt vector</p> <p>- Setting of the vector table</p> <p>(Note) Clock-related setting and setting of __set_ii(numerical value) in advance are required. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".</p>	Register name.bit name	Register name.bit name	Setting of control register Clock selection>>	TCCSH1.TCCSL1 .ECKE	Compare interrupt request flag>> Compare interrupt request enable>>	.ICLR .ICRE	Counting Operation>>	.STOP	TCDT clear>> Count clock>>	.SCLR .CLK3-0	Setting of the timer data value	TCDT1	Register name.bit name	Register name.bit name	Port OCU1 output setting	See "CHAPTER: I/O Port".	Register name.bit name	Register name.bit name	Free-run timer selection Setting of control register	OCFS01 OCSS01,OCCL01	Pin output level invert operation>>	.CMOD	Pin output level specification>> Interrupt request flag>> Interrupt request enable>>	.OTD1,OTD0 .IOP1,IOP0 .IOE1,IOE0	Operation enable setting>> Setting of the compare value ch0 Setting of the compare value ch1	.CST1,CST0 OCCP0 OCCP1	Register name.bit name	Register name.bit name	Setting of an interrupt level.	ICR42 ICR43	Setting of I flag	(CCR)	Register name.bit name	Register name.bit name	Interrupt control	OCSL01.IOE1	Compare operation activation	OCSL01.CST1 OCSL01.CST0	Register name.bit name	Register name.bit name	Counting operation activation	TCCS1.STOP	Register name.bit name	Register name.bit name	Clearing of interrupt request flag (any process)	OCSL01.IOP0								<pre> void OUTPUT23_sample(void) { freerun1_initial(); OUTPUT01_initial(); OUTPUT01_start(); freerun1_start(); } void freerun1_initial(void) { IO_TCCS1.word = 0x0041; /* Setting value =0000_0000_0100_0001 */ /* bit15 = 0 ECKE internal clock source */ /* bit14 -10 =0 Reserved Bit */ /* bit9 = 0 ICLR interrupt flag clear */ /* bit8 = 0 ICLR interrupt disable */ /* bit7 = 0 Reserved Bit */ /* bit6 = 1 STOP Counting disable */ /* bit5 = 0 Reserved Bit */ /* bit4 = 0 SCLR free-run timer value (no) initialization */ /* bit3-0 = 0001 CLK3-0 count clock PCLK/2=32MHz/2 */ /* timer data value initialization */ IO_TCDT1 = 0x0000; } void OUTPUT01_initial(void) { PORT_SETTING_OCU0_OUT(); /* Set the OCU1 pin for peripheral input. */ IO_OCFS01.hword = 0x0003; /* Select the free-run timer 1. */ IO_OCS01.hword = 0xEC0C; /* Setting value =1110_1100_0000_1100 */ /* bit15-13 = 111 Undefined bit */ /* bit12 = 0 CMOD ch.0, ch.1 Level invert */ /* bit11-10 = 11 Undefined bit */ /* bit9-8 = 00 OTD1,OTD0 Compare pin output 0 */ /* bit7-6 = 00 IOP1,IOP0 Output compare no match */ /* bit5-4 = 00 IOE1,IOE0 Output compare interrupt disable */ /* bit3-2 = 11 Undefined bit */ /* bit1-0 = 00 CST1,CST0 Compare operation disable */ IO_OCCP0 = BFFF /* Setting of compare register ch.0 */ IO_OCCP1 = 7FFF /* Setting of compare register ch.1 */ IO_ICR[42].byte = 0x10; /* Output compare ch.0 interrupt level setting (any value) */ IO_ICR[43].byte = 0x10; /* Output compare ch.1 interrupt level setting (any value) */ __EI(); /* Interrupt enable */ } void OUTPUT01_start(void) { IO_OCS01.hword = 0xEC3C; /* bit5-4 = 11 IOE1,IOE0 Output compare interrupt enable */ IO_OCS01.hword = 0xEC3F; /* bit1-0 = 11 CST1,CST0 Compare operation enable */ } void freerun1_start(void) { IO_TCCS1.bit.STOP = 0; /* bit4 = 0 STOP Counting enable */ } __interrupt void INPUT0_int(void) { IO_OCSL01.byte &= 0xBF; /* bit6 = 0 IOP0 Clearing of interrupt flag */ IO_OCSL01.byte &= 0x7F; /* bit7 = 0 IOP1 Clearing of interrupt flag */ } Interrupt routine specification with the vector table is required. #pragma invect OUTPUT1_int 59 </pre>
Register name.bit name	Register name.bit name																																																						
Setting of control register Clock selection>>	TCCSH1.TCCSL1 .ECKE																																																						
Compare interrupt request flag>> Compare interrupt request enable>>	.ICLR .ICRE																																																						
Counting Operation>>	.STOP																																																						
TCDT clear>> Count clock>>	.SCLR .CLK3-0																																																						
Setting of the timer data value	TCDT1																																																						
Register name.bit name	Register name.bit name																																																						
Port OCU1 output setting	See "CHAPTER: I/O Port".																																																						
Register name.bit name	Register name.bit name																																																						
Free-run timer selection Setting of control register	OCFS01 OCSS01,OCCL01																																																						
Pin output level invert operation>>	.CMOD																																																						
Pin output level specification>> Interrupt request flag>> Interrupt request enable>>	.OTD1,OTD0 .IOP1,IOP0 .IOE1,IOE0																																																						
Operation enable setting>> Setting of the compare value ch0 Setting of the compare value ch1	.CST1,CST0 OCCP0 OCCP1																																																						
Register name.bit name	Register name.bit name																																																						
Setting of an interrupt level.	ICR42 ICR43																																																						
Setting of I flag	(CCR)																																																						
Register name.bit name	Register name.bit name																																																						
Interrupt control	OCSL01.IOE1																																																						
Compare operation activation	OCSL01.CST1 OCSL01.CST0																																																						
Register name.bit name	Register name.bit name																																																						
Counting operation activation	TCCS1.STOP																																																						
Register name.bit name	Register name.bit name																																																						
Clearing of interrupt request flag (any process)	OCSL01.IOP0																																																						
.....																																																							

9. Notes

This section explains the notes of the output compare.

● About the compare stop interval during compare operation

For one count right after the writing of a compare value to the compare register, there is no compare operation as shown below.



- For the setting of $CMOD = "1"$ and $OCCP0 = OCCP1$, $OCCP2 = OCCP3$, when compare match occurs, the port inverts only once.
- When the output level of compare pins (OCU0, OCU1, OCU2, OCU3) is specified, first stop the compare operation, and then specify it.
- Because the output compare is synchronized with the free-run timer, when the free-run timer is stopped, the compare operation also is stopped.
- When the compare mode bit is set to $CMOD = "1"$ also, the interrupt operation occurs for each OCU0, OCU1, OCU2, OCU3 independently.
- When the free-run timer is used as the compare data of the output compare, the setting of $"0000_B"$ ($1/F_{PCLK}$) is disabled for the free-run timer clock frequency $TCCSL:CLK[3:0]$.

● Read-modify-write

When the interrupt request flag bits (IOP0), (IOP1), (IOP2), (IOP3) are read with read-modify-write (RMW) instruction, "1" is read.

CHAPTER : INPUT CAPTURE

This chapter explains the input capture.

1. Overview
2. Features
3. Configuration
4. Register
5. Operation
6. Setting
7. Q&A
8. Sample Program
9. Notes

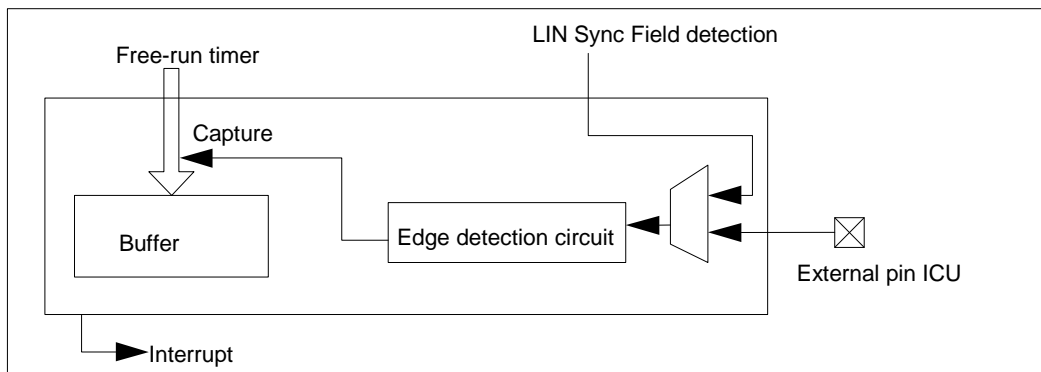
Code : 23_MB91590_HM_E_inputcap_005_20111127

1. Overview

This section explains the overview of the input capture.

The input capture stores the count value of the 32-bit free-run timer at the timing when the signal from the external source is detected. The time between signals can then be calculated from the count values that have been recorded repeatedly. An interrupt can be generated when an effective edge from the external input pin is detected.

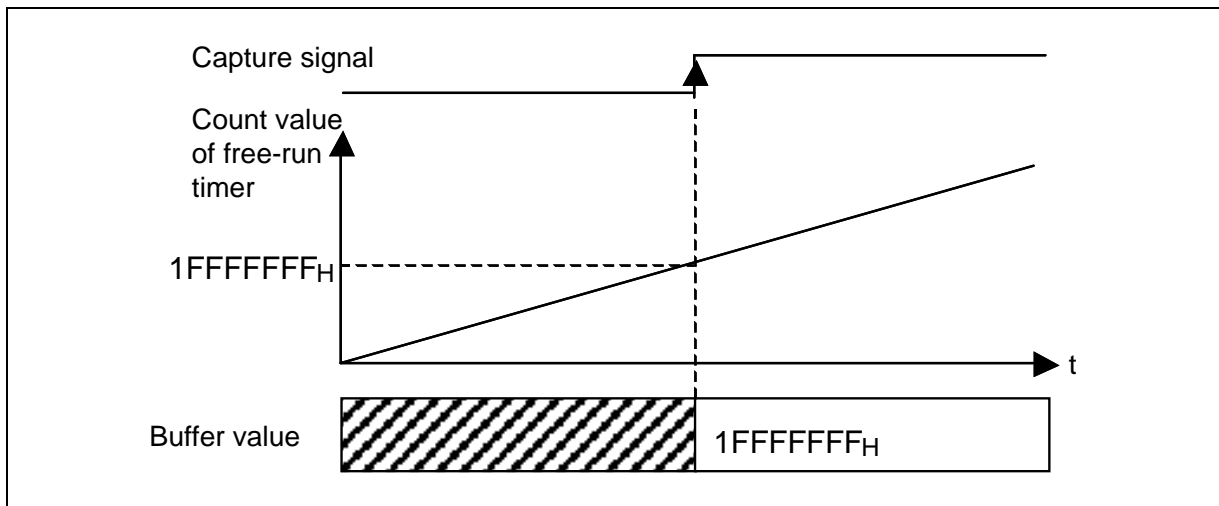
Figure 1-1 Block Diagram



2. Features

This section explains features of the input capture.

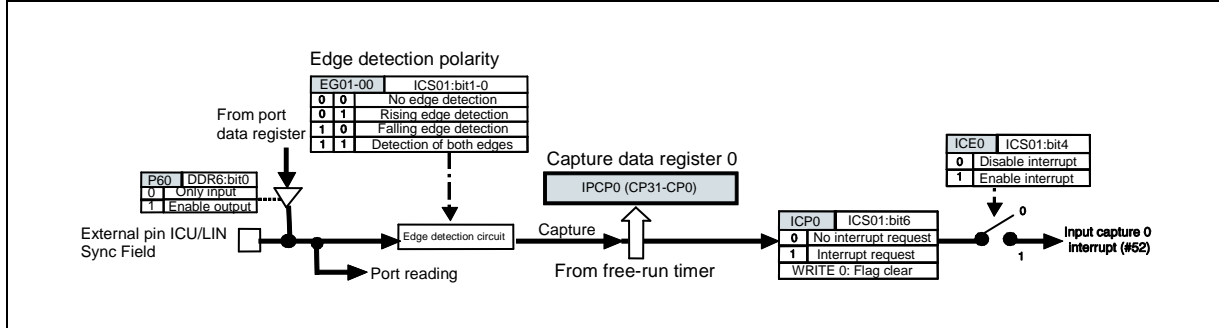
- Format : Edge detection circuit + 32-bit buffer (capture register)
- Number of units : 6 (input capture 0 to 5) + 2 (input capture 6, 7 for LSYN (LIN Sync Field detection) only)
- Edge detection : Rising/falling/both edges
- Interrupt : Edge detection interrupt
- Capture value : Timer count value (00000000_H to FFFFFFFF_H)
- Timer :
 - Input capture 0 to 5 : Use free-run timer 0 or 1.
 - Input capture 6, 7 for LSYN only : Use free-run timer 2 or 3.
- Precision: Peripheral clocks (PCLK)/1,/2, /4, /8, /16, /32, /64, /128, /256) (count clock of the free-run timer)



3. Configuration

This section explains the configuration of the input capture.

Figure 3-1 Block Diagram (detailed; per channel)



Note:

Input captures 6 and 7 are for LSYN only. No external pin is provided to support them.

4. Registers

This section explains registers of the input capture.

■ Table of Base Addresses (Base_addr) and External Pins

Table 4-1 Table of Base Addresses (Base_addr) and External Pins

Channel	Base_addr	External pin
		ICU input
0	0x02C4	ICU0/ICU0_1/ICU0_2
1	0x02C8	ICU1/ICU1_1/ICU1_2
2	0x02D0	ICU2/ICU2_1/ICU2_2
3	0x02D4	ICU3/ICU3_1/ICU3_2
4	0x02DC	ICU4/ICU4_1/ICU4_2
5	0x02E0	ICU5/ICU5_1/ICU5_2
6	0x0FD0	None (only for LSYN)
7	0x0FD4	None (only for LSYN)

Table 4-2 Registers Map

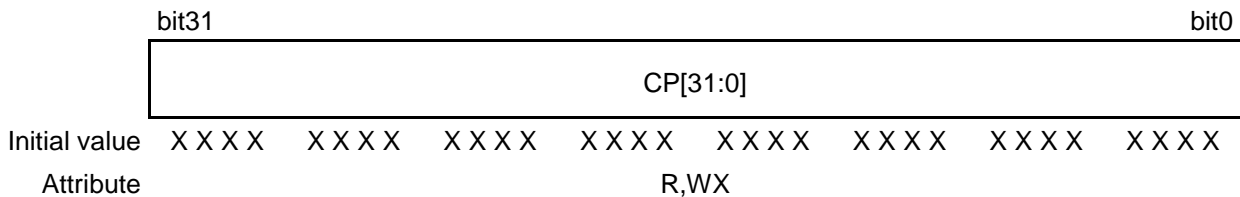
Address	Registers				Register function
	+0	+1	+2	+3	
0x02C4	IPCP0				Input capture data register 0
0x02C8	IPCP1				Input capture data register 1
0x02CC	ICFS01	Reserved	LSYNS0	ICS01	Free-run timer selection register 01 LIN SYNCH FIELD switching register 0 Input capture control register 01
0x02D0	IPCP2				Input capture data register 2
0x02D4	IPCP3				Input capture data register 3
0x02D8	ICFS23	Reserved		ICS23	Free-run timer selection register 23 Input capture control register 23
0x02DC	IPCP4				Input capture data register 4
0x02E0	IPCP5				Input capture data register 5
0x02E4	ICFS45	Reserved		ICS45	Free-run timer selection register 45 Input capture control register 45
0x0FD0	IPCP6				Input capture data register 6 (only for LSYN)
0x0FD4	IPCP7				Input capture data register 7 (only for LSYN)
0x0FD8	ICFS67	Reserved	LSYNS1	ICS67	Free-run timer selection register 67 (only for LSYN) LIN SYNCH FIELD switching register 1 (only for LSYN) Input capture control register 67 (only for LSYN)

4.1. Input Capture Data Register : IPCP

This section explains the bit configuration for the input capture data register (IPCP).

This register can be used to hold and read the count value of the free-run timer using a change in the input signal from the external source as a trigger.

- **IPCP0 (Input capture 0): Address 02C4_H (Access: Word)**
- **IPCP1 (Input capture 1): Address 02C8_H (Access: Word)**
- **IPCP2 (Input capture 2): Address 02D0_H (Access: Word)**
- **IPCP3 (Input capture 3): Address 02D4_H (Access: Word)**
- **IPCP4 (Input capture 4): Address 02DC_H (Access: Word)**
- **IPCP5 (Input capture 5): Address 02E0_H (Access: Word)**
- **IPCP6 (Input capture 6 (only for LSYN)): Address 0FD0_H (Access: Word)**
- **IPCP7 (Input capture 7(only for LSYN)): Address 0FD4_H (Access: Word)**



Note:

When accessing this register, use a word access instruction. No data can be written to this register.

4.2. Free-run Timer Selection Register : ICFS

This section explains the bit configuration for the free-run timer selection register (ICFS).

This register selects the capture source free-run timer.

■ ICFS01 (Free-run timer selection 01): Address 02CC_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	—	—	SEL1	SEL0
Initial value	—	—	—	—	—	—	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

■ ICFS23 (Free-run timer selection 23): Address 02D8_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	—	—	SEL3	SEL2
Initial value	—	—	—	—	—	—	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

■ ICFS45 (Free-run timer selection 45): Address 02E4_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	—	—	SEL5	SEL4
Initial value	—	—	—	—	—	—	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

■ ICFS67 (Free-run timer selection 67 (only for LSYN)): Address 0FD8_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	—	—	SEL7	SEL6
Initial value	—	—	—	—	—	—	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W

[bit7 to bit2] - : Undefined

This does not affect the writing operation.

[bit1, bit0] SELn : Free-run timer selection

SEL{0,1,2,3,4,5}	Operation
0	Free-run timer 0
1	Free-run timer 1

SEL{6,7}	Operation
0	Free-run timer 2
1	Free-run timer 3

4.3. Input Capture Control Register : ICS

This section explains the bit configuration the input capture control register (ICS).

This register is used to control the input capture.

■ **ICS01 (Input capture 0, 1): Address 02CF_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ICP1	ICP0	ICE1	ICE0	EG11	EG10	EG01	EG00
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1),W	R(RM1),W	R/W	R/W	R/W	R/W	R/W	R/W

■ **ICS23 (Input capture 2, 3): Address 02DB_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ICP3	ICP2	ICE3	ICE2	EG31	EG30	EG21	EG20
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1),W	R(RM1),W	R/W	R/W	R/W	R/W	R/W	R/W

■ **ICS45 (Input capture 4, 5): Address 02E7_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ICP5	ICP4	ICE5	ICE4	EG51	EG50	EG41	EG40
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1),W	R(RM1),W	R/W	R/W	R/W	R/W	R/W	R/W

■ **ICS67 (Input capture 6, 7 (only for LSYN)): Address 0FDB_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ICP7	ICP6	ICE7	ICE6	EG71	EG70	EG61	EG60
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1),W	R(RM1),W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] ICPn : Input capture interrupt request flag

ICPn	State	
	Read	Write
0	No interrupt request	Clear the flag
1	Interrupt request present (edge detected)	No effect on operation

- This flag will be set to "1" when the signal change (edge) selected in the capture effective edge selection bit (EG[n1:n0]) is detected in the input signal from the external pin.
 - To enable the CPU interrupt request, you need to enable interrupt request enable setting (ICEn= 1).
- * ICPn: n corresponds to the input capture channel numbers.

[bit5, bit4] ICEn : Input capture interrupt request enabled

ICEn	Operation
0	Interrupt disabled
1	Interrupt enabled

An input capture interrupt is generated when the input capture interrupt request flag is set to "1" while the input capture interrupt request enable bit is set to "1".

* ICEn: n corresponds to the input capture channel numbers.

[bit3 to bit0] EGn1, EGn0 : Input capture n effective edge selection

EGn1	EGn0	Edge selection
0	0	Input capture stopped
0	1	Rising edge
1	0	Falling edge
1	1	Both edges (rising and falling edges)

- These bits are used to select the capture effective edge(s) for the input capture signal from the external pin.
 - The input capture will be in stop if the effective edge selection bit is "00_B".
- * EGn1, EGn0: n corresponds to the input capture channel numbers.

4.4. LIN SYNCH FIELD Switching Register : LSYNS

This section explains the bit configuration for the LIN SYNCH FIELD switching register (LSYNS).

■ LSYNS0 (Input capture): Address 02CE_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	LSYN5	LSYN4	LSYN3	LSYN2	LSYN1	LSYN0
Initial value	—	—	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] - : Undefined

The read value is always "1". This does not affect the writing operation.

[bit5 to bit0] LSYN5 to LSYN0 : Input capture 5 to 0 input selection

LSYNn (n=0 to 5)	Input selection
0	External pin input (ICUn)
1	LIN synch field detection signal input from LIN-UART ch.(n +2)

Note:

The input for the input capture must be switched while the capture is inactive (ICS:EG[n1:n0]=00).

When the capture operation is enabled (ICS:EG[n1:n0] is other than "00") and input is switched while the signal level of the external pin input and the state of the LIN synch field detection signal (level) are different, edges will be detected and will operate as capture effective edges.

■ LSYNS1 (Input capture (only for LSYN)): Address 0FDA_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	—	Reserved	Reserved	LSYN7	LSYN6
Initial value	—	—	—	—	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R0,W0	R0,W0	R/W	R/W

[bit7 to bit4] - : Undefined

The read value is always "1". This does not affect the writing operation.

[bit3, bit2] Reserved

Always write "0" to these bits. The read value is "0".

[bit1, bit0] LSYN7, LSYN6 : Input capture 7, 6 input selection

LSYNn (n=6, 7)	Input selection
0	Disconnected
1	LIN synch field detection signal input from multi-function serial interface ch.(n-6)

Note:

The input for the input capture must be switched while the capture is inactive (ICS:EG[n1:n0]= 00).

5. Operation

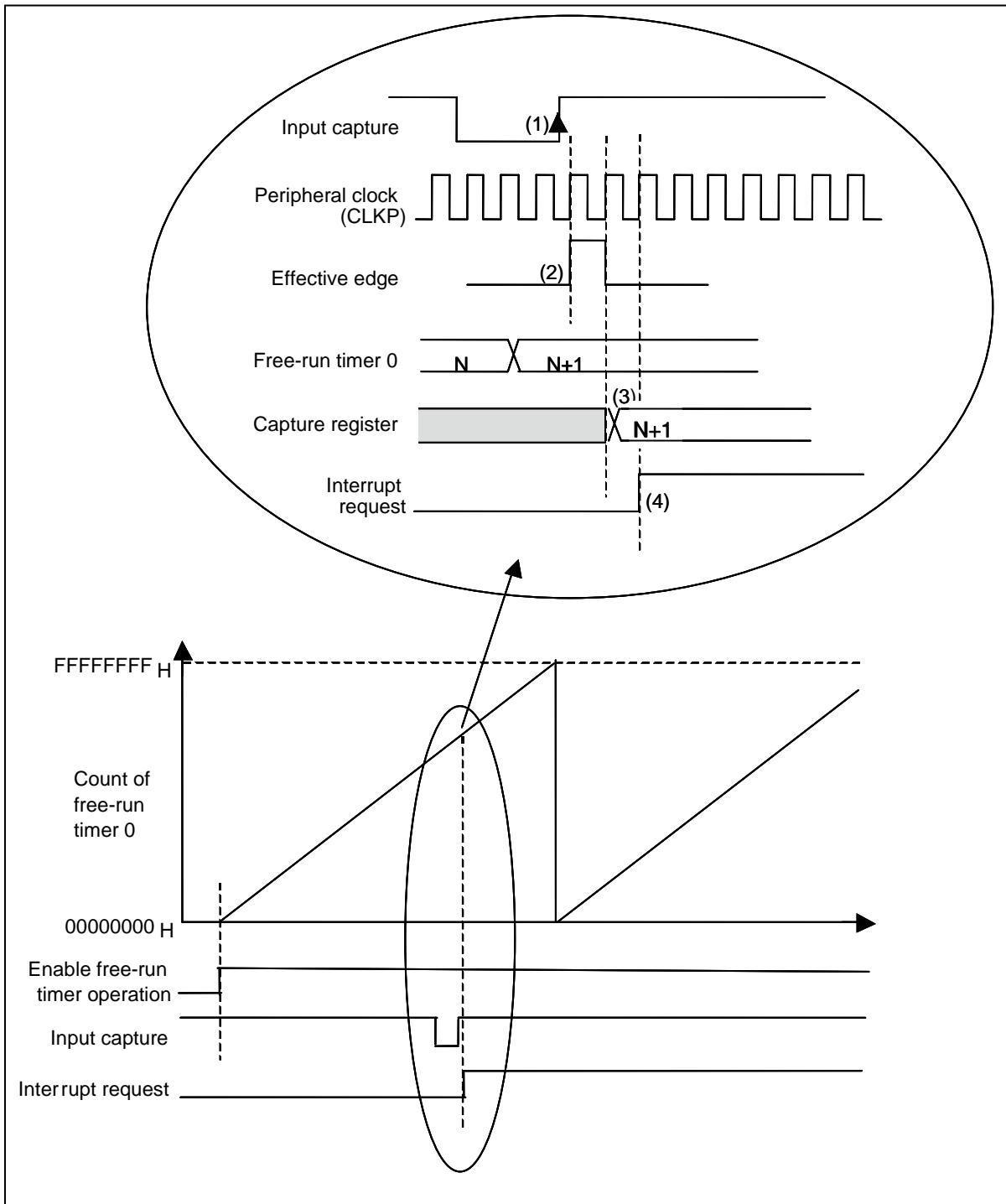
This section explains the operation of the input capture.

When a set effective edge is detected, the 32-bit input capture can retrieve the value of the 32-bit free-run timer into the capture register and generate an interrupt.

This section explains the input capture operation.

5.1. Capture and Interrupt Timings

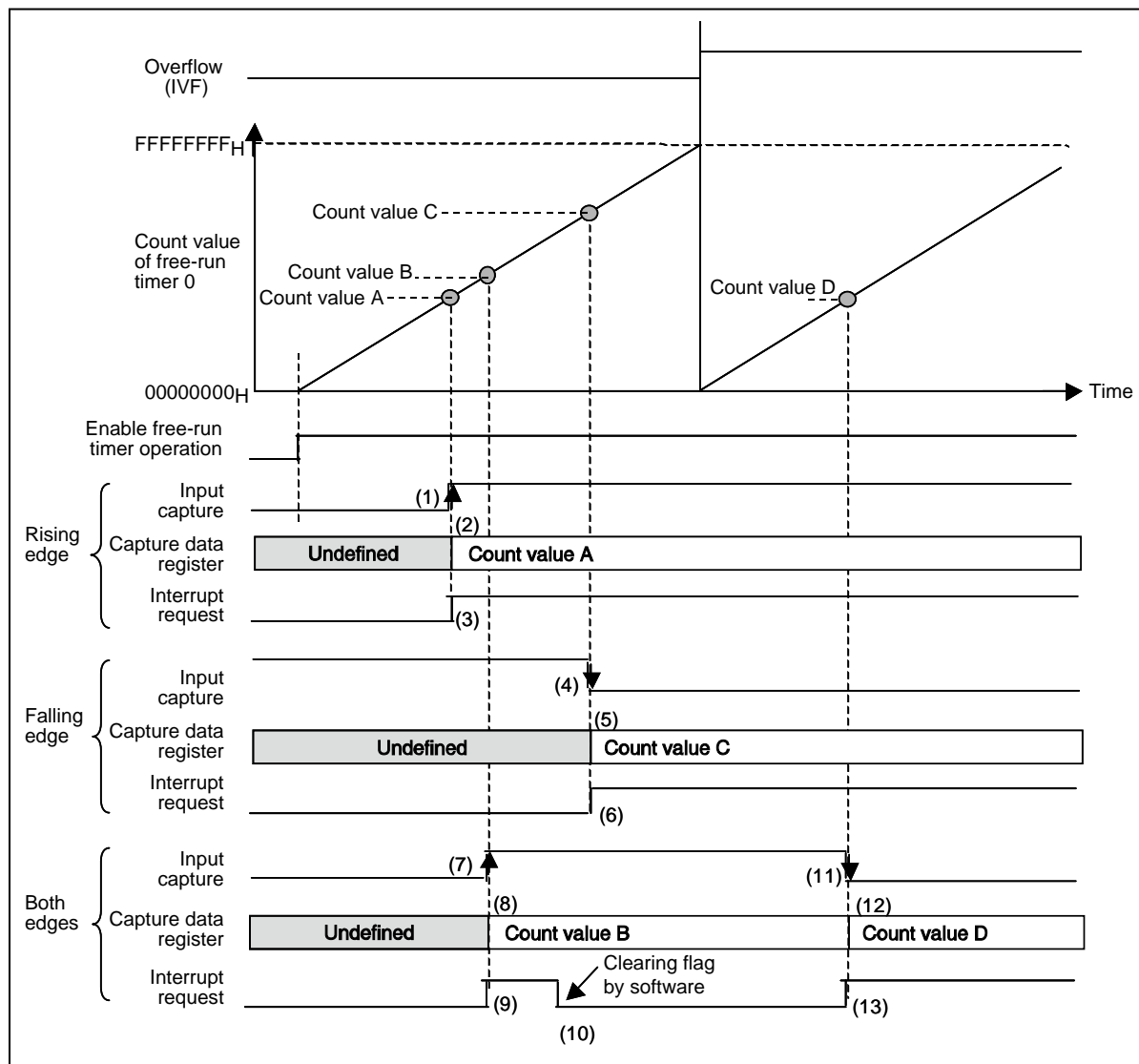
This section explains capture and interrupts timings of the input capture.



- (1) Rising edge of the input signal
- (2) Internal signal generated by edge detection (synchronized to the peripheral clock)
- (3) Free-run timer value is recorded to the capture register (capture).
- (4) Input capture interrupt is generated (ICP(0 to 5)=1, for LSYN ICP6=(6, 7)=1).

5.2. Edge Detection Specifications for Input Capture And Their Operations

This section explains edge detection specifications for the input capture and their operations.



● When rising edge is selected

- (1) Rising edge of the input signal is detected.
- (2) Free-run counter value is recorded to the capture register (capture).
- (3) Input capture interrupt is generated.

● When falling edge is selected

- (4) Falling edge of the input signal is detected.
- (5) Free-run counter value is recorded to the capture register (capture).
- (6) Input capture interrupt is generated.

● **Both edges**

- (7) Rising edge of the input signal is detected.
- (8) Free-run counter value is recorded to the capture register (capture).
- (9) Input capture interrupt is generated.
- (10) Interrupt request flag (ICS01:ICP0), (ICS01:ICP1), (ICS23:ICP2), (ICS23:ICP3), (ICS45:ICP4), (ICS45:ICP5), for LSYN (ICS67:ICP6), for LSYN(ICS67:ICP7) is cleared using software.
- (11) Falling edge of the input signal is detected.
- (12) Free-run counter value is recorded to the capture register (capture).
- (13) Input capture interrupt is generated.

6. Setting

This section explains setting of the input capture.

Table 6-1 Settings Required for Using Input Capture

Configuration	Configured register	Setting method
Free-run timer setting	See "CHAPTER: FREE-RUN TIMER".	—
Free-run timer activation		
Setting for switching inputs between input pins ICU0 to ICU5 and input capture	If the linkage function for LIN_UART or multi-function serial interface is used: LIN SYNCH FIELD switching register (LSYNS0), (LSYNS1) External input: Settings of the LIN SYNCH FIELD switching register (LSYNS0), ICU0 to ICU5 pins (See "CHAPTER: I/O PORTS").	See 7.2.
Effective edge polarity selection for external input	Input capture control registers (ICS01), (ICS23), (ICS45) Input capture control register (only for LSYN) (ICS67)	See 7.1.

Table 6-2 Settings Required for Performing Input Capture Interrupt

Configuration	Configured register	Setting method
Input capture interrupt vector and input capture interrupt level settings	See "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".	See 7.3.
Input capture interrupt setting Interrupt request clear Interrupt request enable	Input capture control registers (ICS01), (ICS23), (ICS45) Input capture control register (only for LSYN) (ICS67)	See 7.5.

7. Q&A

This section explains Q&A of the input capture.

- 7.1. Effective Edge Polarity of External Input: Types and How to Select
- 7.2. How to Enable External Input Pins (ICU0, ICU1, ICU2, ICU3, ICU4, ICU5)
- 7.3. About Interrupt Related Registers
- 7.4. About Interrupt Types
- 7.5. How to Enable Interrupt
- 7.6. How to Measure the Pulse Width of the Input Signal

7.1. Effective Edge Polarity of External Input: Types and How to Select

This section explains types of the effective edge polarity of external input and the selection method.

There are 3 types of the effective edge polarity: rising, falling and both edges.

You can configure it using the effective edge polarity bits of the external input (ICS01:EG[01:00]), (ICS01:EG[11:10]), (ICS23:EG[21:20]), (ICS23:EG[31:30]), (ICS45:EG[41:40]), (ICS45:EG[51:50]), (ICS67:EG[61:60]), (ICS67:EG[71:70]).

Operation	Effective edge polarity bits of the external input (EG[01:00]), (EG[11:10]), (EG[21:20]), (EG[31:30]), (EG[41:40]), (EG[51:50]), (EG[61:60]), (EG[71:70])
To select rising edge	Select "01".
To select falling edge	Select "10".
To select both edges	Select "11".

7.2. How to Enable External Input Pins (ICU0, ICU1, ICU2, ICU3, ICU4, ICU5)

This section explains how to enable external input pins (ICU0 to ICU5).

Set the LSYNS0 register for external pin input. Also, set the ICU0 to ICU5 pins for peripheral input. For information on the setting method, see "CHAPTER: I/O PORTS".

7.3. About Interrupt Related Registers

This section explains interrupt related registers.

Input capture interrupt vector and input capture interrupt level settings

See "3. List of Interrupt Vector" in "APPENDIX" for interrupt number.

For details of the interrupt levels and interrupt vectors, see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

Interrupt request flags (ICS01:ICP0), (ICS01:ICP1), (ICS23:ICP2), (ICS23:ICP3), (ICS45:ICP4), (ICS45:ICP5), (ICS67:ICP6) and (ICS67:ICP7) are not cleared automatically. Therefore, clear the input capture interrupt request flags (ICP0, ICP1, ICP2, ICP3, ICP4, ICP5, ICP6, ICP7) by writing "0" using software before returning from interrupt processing.

7.4. About Interrupt Types

This section explains interrupt types.

There is only 1 type of interrupt. It is generated when an edge is detected in the input signal.

7.5. How to Enable Interrupt

This section explains how to enable interrupt.

Enable interrupt request, interrupt request flag

You can configure the interrupt enable setting using the following interrupt request enable bits:

(ICS01:ICE0), (ICS01:ICE1), (ICS23:ICE2), (ICS23:ICE3), (ICS45:ICE4), (ICS45:ICE5), (ICS67:ICE6), (ICS67:ICE7)

Operation	Interrupt request enable bits (ICE0), (ICE1), (ICE2), (ICE3), (ICE4), (ICE5), (ICE6), (ICE7)
Interrupt disabled	Set "0".
Interrupt enabled	Set "1".

You can clear the interrupt request using the following interrupt request flags:

(ICS01:ICP0), (ICS01:ICP1), (ICS23:ICP2), (ICS23:ICP3), (ICS45:ICP4), (ICS45:ICP5), (ICS67:ICP6), (ICS67:ICP7)

Operation	Interrupt request flag bits (ICP0), (ICP1), (ICP2), (ICP3), (ICP4), (ICP5), (ICP6), (ICP7)
Interrupt request clear	Write "0".

7.6. How to Measure the Pulse Width of the Input Signal

This section explains how to measure the pulse width of the input signal.

● "H" width measurement

Enable detection of both edges.

Ensure that the rising edge is detected first, followed by the falling edge.

Pulse width = { Value recorded at falling edge (input capture register value)
+ "100000000_H" × No. of overflows
- Value recorded at rising edge (input capture register value) }
× Count clock width of the free-run timer

Example : Value recorded at falling edge = 23200000_H, Value recorded at rising edge = A6350000_H,
No. of overflows = 1, Count clock = 125ns
==> Pulse width = (23200000_H + 100000000_H - A6350000_H) × 125ns = 261.972s

● Interval measurement

Enable rising (or falling) edge detection.

The specified edge is detected twice.

Cycle = { 2nd recorded value (input capture register value)
+ "100000000_H" × No. of overflows
- { 1st recorded value (input capture register value) }
× Count clock width of the free-run timer

8. Sample Program

This section explains the sample program of the input capture.

<p>Setting procedure example 1</p> <p>Detect the rising edge of the pulse for input to ICU0 and record the value of free-run timer. This process is repeated twice to measure the time from one trigger to another. However, reading and calculation of the capture value are to be handled as interrupt processes.</p> <p>1. Initial setting</p> <p>-Free-run timer ch.0 control</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Control register setting Clock selection»</td> <td>TCCS0 .ECKE</td> </tr> <tr> <td>Compare interrupt request flag» Compare interrupt request enable»</td> <td>.ICLR .ICRE</td> </tr> <tr> <td>Counting operation»</td> <td>.STOP</td> </tr> <tr> <td>TCDT clear Count clock»</td> <td>.SCLR .CLK3-0</td> </tr> <tr> <td>Timer data value setting</td> <td>TCDT0</td> </tr> </tbody> </table> <p>-Port</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Port ICU0 input setting</td> <td>See "CHAPTER: I/O PORTS".</td> </tr> </tbody> </table> <p>-Input capture control</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Control register setting</td> <td>ICS0</td> </tr> <tr> <td>Interrupt request flag»</td> <td>.ICP1,ICP0</td> </tr> <tr> <td>Interrupt request enabled»</td> <td>.ICE1,ICE0</td> </tr> <tr> <td>ch1 Effective edge polarity selection»</td> <td>.EG11,EG10</td> </tr> <tr> <td>ch0 Effective edge polarity selection»</td> <td>.EG01,EG00</td> </tr> </tbody> </table> <p>-Interrupt-related</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Sets an interrupt level.</td> <td>ICR36</td> </tr> <tr> <td>I flag setting</td> <td>(CCR)</td> </tr> </tbody> </table> <p>-Variable setting</p> <p>2. Activation</p> <p>-Input capture ch.0 activation</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Interrupt control</td> <td>ICS01.ICE0</td> </tr> </tbody> </table> <p>-Free-run timer ch.0 activation</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Count operation activation</td> <td>TCCS0.STOP</td> </tr> </tbody> </table> <p>3. Interrupt</p> <p>-Interrupt processing</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;"></th> <th style="text-align: left;">Register name.Bit name</th> </tr> </thead> <tbody> <tr> <td>Clearing of interrupt request flag</td> <td>ICS01.ICP0</td> </tr> <tr> <td>(Any process)</td> <td></td> </tr> <tr> <td>.....</td> <td></td> </tr> <tr> <td></td> <td></td> </tr> <tr> <td></td> <td></td> </tr> <tr> <td></td> <td></td> </tr> </tbody> </table> <p>4. Interrupt vector</p> <p>-Vector table setting</p> <p>(Note) Clock-related settings and the setting of __set_il (numeric value) need to be configured in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPTS CONTROL (INTERRUPTS CONTROLLER)".</p>		Register name.Bit name	Control register setting Clock selection»	TCCS0 .ECKE	Compare interrupt request flag» Compare interrupt request enable»	.ICLR .ICRE	Counting operation»	.STOP	TCDT clear Count clock»	.SCLR .CLK3-0	Timer data value setting	TCDT0		Register name.Bit name	Port ICU0 input setting	See "CHAPTER: I/O PORTS".		Register name.Bit name	Control register setting	ICS0	Interrupt request flag»	.ICP1,ICP0	Interrupt request enabled»	.ICE1,ICE0	ch1 Effective edge polarity selection»	.EG11,EG10	ch0 Effective edge polarity selection»	.EG01,EG00		Register name.Bit name	Sets an interrupt level.	ICR36	I flag setting	(CCR)		Register name.Bit name	Interrupt control	ICS01.ICE0		Register name.Bit name	Count operation activation	TCCS0.STOP		Register name.Bit name	Clearing of interrupt request flag	ICS01.ICP0	(Any process)									<p>Program example 1</p> <pre> void INPUT0_sample_1(void) { freerun0_initial(); INPUT0_initial(); INPUT0_start(); freerun0_start(); } void freerun0_initial(void) { IO_TCCS0.word = 0x0041; /* Setting value=0000_0000_0100_0001 */ /* bit15 = 0 ECKE internal clock source */ /* bit14 -10 =0 Reserved bit */ /* bit9 = 0 Interrupt flag clear */ /* bit8 = 0 Interrupt disabled */ /* bit7 = 0 Reserved bit */ /* bit6 = 1 */ /* bit5 = 0 Reserved bit */ /* bit4 = 0 */ /* bit3-0 = 0001 */ IO_TCDT0 = 0x0000; /* Initialization of timer data value */ } void INPUT0_initial(void) { PORT_SETTING_ICU0_IN(); /* Set the ICU0 pin for peripheral input. */ IO_ICS01.byte = 0x01; /* Setting value=0000_0001 */ /* bit7 to 6 = 00 ICP1, 0 No effective edge detected */ /* bit5 to 4 = 00 ICE1, 0 Interrupt disabled */ /* bit3 to 2 = 00 EG11, EG10 ch.1 No edge detected */ /* bit1 to 0 = 01 EG01, EG00 ch.0 Rising edge detected */ IO_ICR[36].byte = 0x10; /* Input capture ch.0 interrupt level setting (any value) */ __EI(); /* Interrupt enabled */ count = 0; } void INPUT0_start(void) { IO_ICS01.bit.ICE0 = 1; /* bit4 = 1 ICE0 ch.0 Interrupt enabled */ } void freerun0_start(void) { IO_TCCS0.bit.STOP = 0; /* bit6 = 0 STOP count enabled */ } __interrupt void INPUT0_int(void) { IO_ICS01.bit.ICP0 = 0; /* bit6 = 0 Clearing of ICP0 effective edge detection flag */ if(count==0) data1 = IO_IPCP0; /* Free-run timer value is recorded. (1st time) */ else if(count==1) { data2 = IO_IPCP0; /* Free-run timer value is recorded. (2nd time) */ cycle = (data2-data1)*125; /* Time is measured. */ count = 0; } } count++; Specification of interrupt routine required in vector table #pragma intvect INPUT0_int 52 </pre>
	Register name.Bit name																																																								
Control register setting Clock selection»	TCCS0 .ECKE																																																								
Compare interrupt request flag» Compare interrupt request enable»	.ICLR .ICRE																																																								
Counting operation»	.STOP																																																								
TCDT clear Count clock»	.SCLR .CLK3-0																																																								
Timer data value setting	TCDT0																																																								
	Register name.Bit name																																																								
Port ICU0 input setting	See "CHAPTER: I/O PORTS".																																																								
	Register name.Bit name																																																								
Control register setting	ICS0																																																								
Interrupt request flag»	.ICP1,ICP0																																																								
Interrupt request enabled»	.ICE1,ICE0																																																								
ch1 Effective edge polarity selection»	.EG11,EG10																																																								
ch0 Effective edge polarity selection»	.EG01,EG00																																																								
	Register name.Bit name																																																								
Sets an interrupt level.	ICR36																																																								
I flag setting	(CCR)																																																								
	Register name.Bit name																																																								
Interrupt control	ICS01.ICE0																																																								
	Register name.Bit name																																																								
Count operation activation	TCCS0.STOP																																																								
	Register name.Bit name																																																								
Clearing of interrupt request flag	ICS01.ICP0																																																								
(Any process)																																																									
.....																																																									

9. Notes

This section explains notes of the input capture.

- **Input capture register**

The input capture register value is undefined after a reset.

Reading of the input capture register must be performed in word(32-bit mode) access.

- **Read-modify-write**

The input capture interrupt request bits (ICP0), (ICP1), (ICP2), (ICP3), (ICP4), (ICP5), (ICP6) and (ICP7) are "1" when read using a read-modify-write (RMW) instruction.

CHAPTER : REAL-TIME CLOCK(RTC)

This chapter explains the real-time clock (RTC).

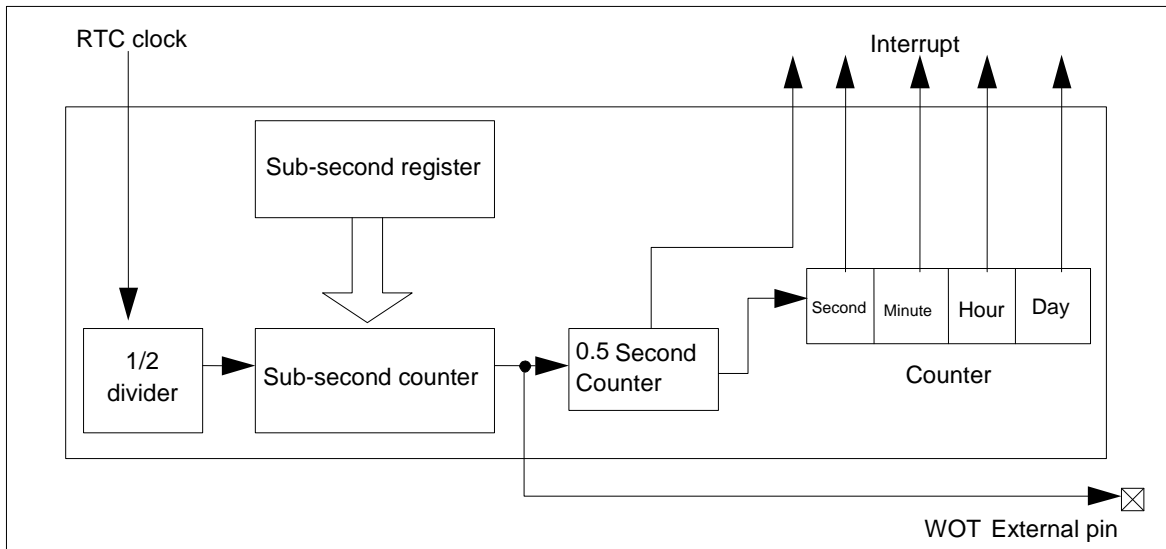
1. Overview
2. Features
3. Configuration
4. Register
5. Operation
6. Setting
7. Q&A
8. Sample Program
9. Notes

1. Overview

This section explains the overview of the real-time clock (RTC).

The real-time clock (watch timer) consists of the timer control register, sub-second register, Second/ Minute/ Hour/ Day registers, 1/2 clock frequency divider, sub-second counter(22-bit down counter) and Second/ Minute/ Hour/ Day counters. The real-time clock operates as the real-world timer and provides the real-world timer information.

Figure 1-1 Block Diagram (Overview)



2. Features

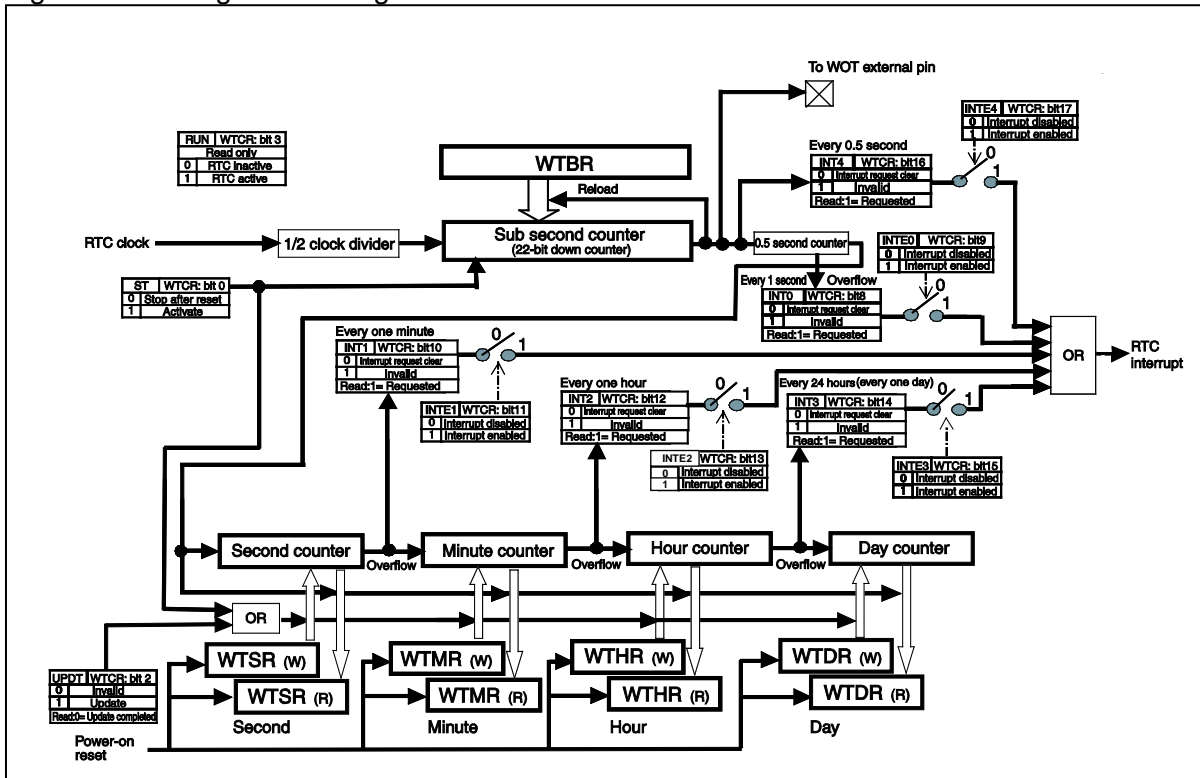
This section explains features of the real-time clock (RTC).

- Function : Counts the number of days and time (day/ hour/ minute/ second) (operations are kept on in the watch mode too.)
The default values of the number of days and time can be modified.
- Operation clock : RTC clock (See "CHAPTER: CLOCK" for the selection of the clock source of the RTC clock. See "CHAPTER: RTC/WDT1 CALIBRATION" for the correction when a sub-clock(only dual clock product) is selected as a source.)
- Interrupt : Interrupts can be generated based on five intervals: 0.5second, 1second, 1minute, 1hour, and 1day. In addition, interrupts at any interval (from short interval to long interval) can be generated by changing the sub-second value.

3. Configuration

This section explains the configuration of the real-time clock (RTC).

Figure 3-1 Configuration Diagram



4. Registers

This section explains registers of the real-time clock (RTC).

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x055C	Reserved	Reserved	WTDR		Day/Hour/Minute/Second Registers(day)
0x0560	Reserved	WTCR			RTC control register
0x0564	Reserved	WTBR			Sub-second register
0x0568	WTHR	WTMR	WTSR	Reserved	Day/Hour/Minute/Second registers(hour) Day/Hour/Minute/Second registers(minute) Day/Hour/Minute/Second registers(second)

4.1. RTC Control Register : WTCR

The bit configuration of the RTC control register (WTCR) is shown below.

This register controls the operations of the real-time clock module.

■ **WTCRH : Address 0561_H (Access: Byte)**

■ **WTCRM : Address 0562_H (Access: Byte, Half-word)**

■ **WTCRL : Address 0563_H (Access: Byte, Half-word)**

	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	-	-	-	-	-	-	INTE4	INT4
Initial value	-	-	-	-	-	-	0	0
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R(RM1), W

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	INTE3	INT3	INTE2	INT2	INTE1	INT1	INTE0	INT0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R(RM1), W	R/W	R(RM1), W	R/W	R(RM1), W	R/W	R(RM1), W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	Reserved	Reserved	Reserved	RUN	UPDT	Reserved	ST
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W0	R/W0	R/W0	R/W0	R,WX	R(RM0),W	R/W0	R/W

This register will be initialized by all reset source without the return reset from watch mode (power shut-down).

[bit23 to bit18] - : Undefined

The read value is always "1". The data writing does not affect the operation.

[bit17] INTE4 : 0.5 second interrupt request enable

INTE4	Operation
0	0.5 second interrupt request disabled
1	0.5 second interrupt request enabled

[bit16] INT4 : 0.5 second interrupt request flag

INT4	State	
	Read	Write
0	0.5 second interrupt request not generated	Flag clear
1	0.5 second interrupt request generated	This does not affect the operations

When the frequency division output of the borrow signal of the sub-second counter (22-bit down counter) is enabled, the flag will be set to "1".

[bit15] INTE3 : 1 day interrupt request enable

INTE3	Operation
0	1 day (24 hours) interrupt request disabled
1	1 day (24 hours) interrupt request enabled

[bit14] INT3 : 1 day interrupt request flag

INT3	State	
	Read	Write
0	1 day (24 hours) interrupt request not generated	Flag clear
1	1 day (24 hours) interrupt request generated	This does not affect the operations

When overflow occurs in the hour counter, the flag will be set to "1".

[bit13] INTE2 : 1 hour interrupt request enable

INTE2	Operation
0	1 hour interrupt request disabled
1	1 hour interrupt request enabled

[bit12] INT2 : 1 hour interrupt request flag

INT2	State	
	Read	Write
0	1 hour interrupt request not generated	Flag clear
1	1 hour interrupt request generated	This does not affect the operations

When overflow occurs in the minute counter, the flag will be set to "1".

[bit11] INTE1 : 1 minute interrupt request enable

INTE1	Operation
0	1 minute interrupt request disabled
1	1 minute interrupt request enabled

[bit10] INT1 : 1 minute interrupt request flag

INT1	Operation	
	Read	Write
0	1 minute interrupt request not generated	Flag clear
1	1 minute interrupt request generated	This does not affect the operations

When overflow occurs in the second counter, the flag will be set to "1".

[bit9] INTE0 : 1 second interrupt request enable

INTE0	Operation
0	1 second interrupt request disabled
1	1 second interrupt request enabled

[bit8] INT0 : 1 second interrupt request flag

INT0	State	
	Read	Write
0	1 second interrupt request not generated	Flag clear
1	1 second interrupt request generated	This does not affect the operations

When overflow occurs in the 0.5 second counter, the flag will be set to "1".

[bit7 to bit4] Reserved

These bits must always be written to "0".

[bit3] RUN : Operation state

RUN	State
0	Real-time clock module is stopped
1	Real-time clock module is running

[bit2] UPDT : Update

UPDT	State/Operation	
	Read	Write
0	Update completed	This does not affect the operations
1	Updating	The counter values of the Hour/ Minute/ Second counters are updated to Day/ Hour/Minute/ Second register values respectively.

Before writing "1" to the update bit (UPDT), set the value to be updated in the Day/ Hour/ Minute/ Second registers.

Update for Day/ Hour/ Minute/ Second registers will be performed when reload occurs at the sub-second counter (22-bit down counter).

When the counter value is updated, the UPDT bit will be cleared by hardware. However, when update is completed at the same time as writing "1", the UPDT bit will not be cleared to "0".

[bit1] Reserved

This bit must always be written to "0".

[bit0] ST : Start

ST	Operation
0	Real-time clock module is stopped. All the counters are cleared.
1	Values set at Day/Hour/Minute/Second registers are loaded into Day/Hour/Minute/Second counters, and the real-time clock starts to run.

Note:

When writing "1" to the start bit (ST) from RTC stop state (ST=0) (RTC operation start), do not write "1" to the update bit (UPDT) at the same time as the start bit.
(While ST=0, writing "1" as byte immediate value to the ST bit and the UPDT bit at the same time is prohibited.)

Note:

To write "1" to the update bit (UPDT), do it while RTC is working (ST=1).

Note:

While the update bit (UPDT) is "1", writing "0" to the start bit (ST) (RTC stop) is prohibited.

4.2. Sub-second Register : WTBR

The bit configuration of the sub-second register (WTBR) is shown below.

This register contains the reload value of the sub-second counter (22-bit down counter).

■ **WTBRH : Address 0565_H (Access: Byte)**

■ **WTBRM : Address 0566_H (Access: Byte)**

■ **WTBRL : Address 0567_H (Access: Byte)**

WTBRH

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	-	D21	D20	D19	D18	D17	D16
Initial value	-	-	X	X	X	X	X	X
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

WTBRM

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D15	D14	D13	D12	D11	D10	D9	D8
Initial value	X	X	X	X	X	X	X	X
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

WTBRL

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	X	X	X	X	X	X	X	X
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

This register will be initialized by all reset source without the reset return from watch mode (power shut-down).

The sub-second register contains the reload value used in the sub-second counter(22-bit down counter).

This value will be reloaded as soon as the sub-second counter (22-bit down counter) becomes "0". To modify the sub-second register, confirm that no reload operations are being performed during the writing instruction. Otherwise, the sub-second counter (22-bit down counter) will load a wrong value that combines both new and old data bytes. Generally, it is recommended to perform update while the ST bit is "0". While the sub-second register is set to "0", the sub-second counter(22-bit down counter) will not run at all.

The sub-second register settings for counting 0.5 second are as follows:

Table 4-2 WTBR Setting Example

RTC clock frequency	WTBR Setting value
32kHz	0x001F3F
4MHz	0x0F423F

4.3. Day/Hour/Minute/Second Register : WTDR/ WTHR/ WTMR/ WTSR

The bit configuration of the Day/Hour/Minute/Second register (WTDR/WTHR/WTMR/WTSR) is shown below.

These registers indicate the time information of the real-time clock (Day/ Hour/ Minute/ Second).

■ **WTDR (day register) : Address 055E_H (Access: Half-word)**

■ **WTHR (hour register) : Address 0568_H (Access: Byte, Half-word)**

■ **WTMR (minute register) : Address 0569_H (Access: Byte, Half-word)**

■ **WTSR (second register) : Address 056A_H (Access: Byte)**

WTDR

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	N15	N14	N13	N12	N11	N10	N9	N8
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	N7	N6	N5	N4	N3	N2	N1	N0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

WTHR

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	-	-	H4	H3	H2	H1	H0
Initial value	-	-	-	0	0	0	0	0
Attribute	R1,WX	R1,WX	R1,WX	R,W	R,W	R,W	R,W	R,W

WTMR

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	-	M5	M4	M3	M2	M1	M0
Initial value	-	-	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R,W	R,W	R,W	R,W	R,W	R,W

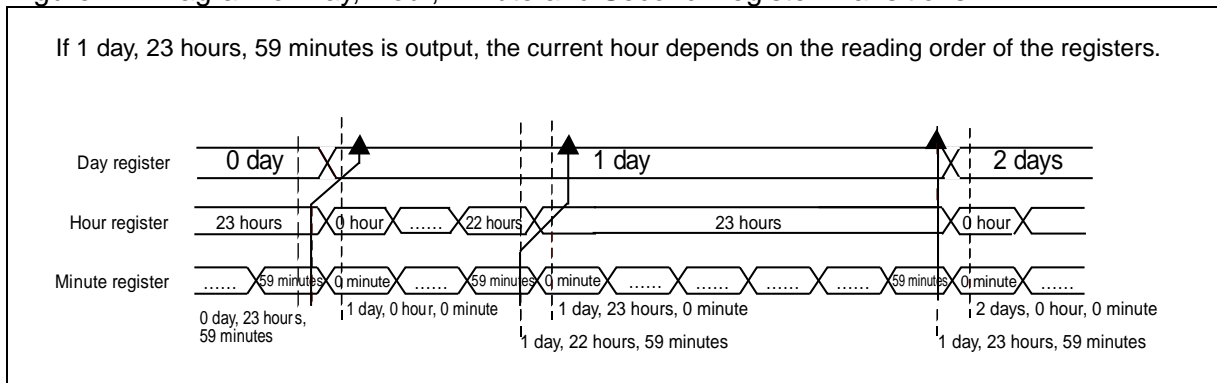
WTSR

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	-	S5	S4	S3	S2	S1	S0
Initial value	-	-	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R,W	R,W	R,W	R,W	R,W	R,W

This register will be initialized by power-on reset source.

- The Second/ Minute/ Hour/ Day registers contain day and time information. Binary-coded notation is used for second, minute, hour, and day.
- When the register is read out, the counter value will be read out. The written data will be loaded to the counter after the UPDT bit is set to "1".
- As word access is not available, perform access for the respective registers.
- Word access is not available for the number of days register either. In addition, be sure to perform halfword access for the number of days register as the number of days is counted using a 16-bit counter. As byte access may cause carry during read, having the possibility of getting an inappropriate read value, byte access and word access are prohibited.
- Set the Hour/Minute/Second registers within the following ranges:
 Hour (WTHR) : 0 to 17_H (0 hour to 23 hours)
 Minute (WTMR) : 0 to 3B_H (0 minute to 59 minutes)
 Second (WTSR) : 0 to 3B_H (0 second to 59 seconds)
- Confirm that there are no contradictions among the values output from the four registers:
 Day/Hour/Minute/Second registers. The following example may occur.
 [Ex.] Output value "1 day, 23 hours, 59 minutes, 59 seconds", "0 day, 23 hours, 59 minutes, 59 seconds".
 "1 day, 0 hour, 0 minute, 0 second", "1 day, 22 hours, 59 minutes, 59 seconds", 1 day, 23 hours, 0 minute, 0 second, "2 days, 0 hour, 0 minute, 0 second"

Figure 4-1 Diagram of Day, Hour, Minute and Second Register Transitions



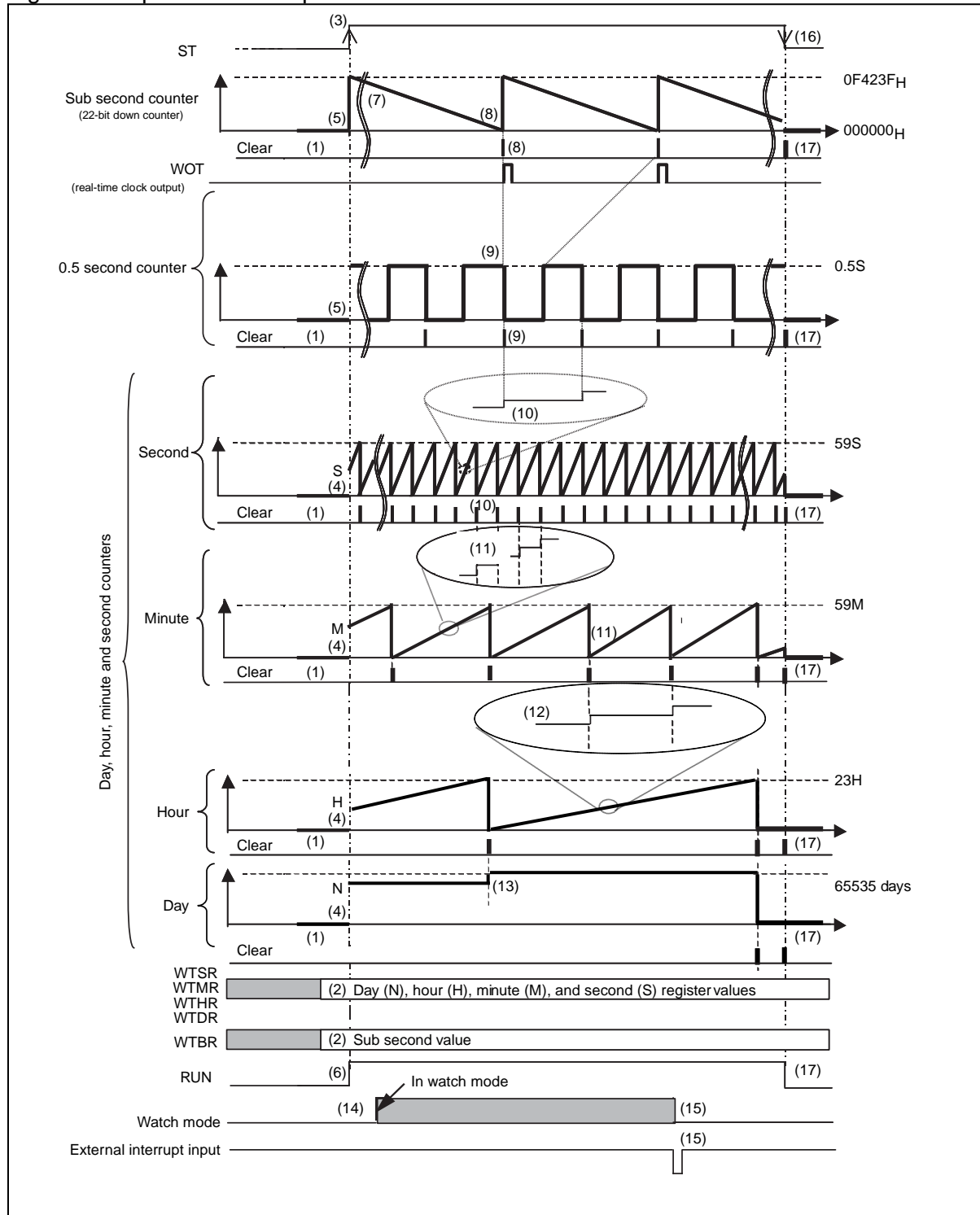
- When the operation clock frequency is obtained by dividing the frequency of the main clock by 2 (while PLL is stopped), the wrong values may be read out from the Hour/Minute/Second registers. This is caused due to synchronization adjustment between reading operations and count operations. Therefore, it is recommended to use second interrupts in the trigger for reading instructions.
- To restart operations with the duration the counter has stopped as the initial value, read the Day/Hour/Minute/Second registers prior to restart and write these values to the Day/Hour/Minute/Second registers to start.
- As this series does not provide the RTC detection reset function, the Day/Hour/Minute/Second registers are cleared only in case of power-on reset. Therefore, when the microcomputer internal low voltage detection flag is set, the Day/Hour/Minute/Second registers are recommended to be cleared.

5. Operation

This section explains the operation of the real-time clock (RTC).

This section explains the operations of the real-time clock.

Figure 5-1 Operation Descriptions for the Real-time Clock



- (1) Use the start bit (ST="0") to reset the sub-second counter (22-bit down counter) and Day/ Hour/ Minute/ Second timers (0), and then stop them.

- (2)
 - Write the values of Day/ Hour/ Minute/ Second to Day/ Hour/ Minute/ Second registers: WTDR, WTHR, WTMR, WTSR by software.
 - Write "0F_H", "42_H", "3F_H" to sub-second registers: WTBRH, WTBRM, WTBRL by software.
 - Initialize the interrupt request bits (INT0, INT1, INT2, INT3, INT4), and set the interrupt request enable bits (INTE0, INTE1, INTE2, INTE3, INTE4) (enable interrupts to be used).
- (3) Set the start bit (ST) to "1".
- (4) Use the start bit (ST="1") to load the values in the Day/ Hour/ Minute/ Second registers: WTDR, WTHR, WTMR, WTSR to the Day/ Hour/ Minute/ Second timers.
- (5) Moreover, as the count value of the sub-second counter (22-bit down counter) is "000000_H", load the values in second registers: WTBRH, WTBRM, WTBRL to the sub-second counter (22-bit down counter).
- (6) The operation flag (RUN) becomes "1".
- (7) The sub-second counter (22-bit down counter) starts to count using a clock obtained by dividing the main clock frequency by 2 (4/2MHz).
- (8) When the sub-second counter(22-bit down counter) becomes "000000_H", load the sub-second register value "0F423_H" to the sub-second counter(22-bit down counter).
In addition, an interrupt request of 0.5 second counter occurs.
Moreover, when the real-time clock output enable is set (WOT pin output enable), an "H" level with a width twice as long as that of the main clock is output to the WOT pin.
(Example: For main clock 4MHz, "H" output with a width of 500ns)
- (9) After the 0.5 second counter is counted up, it is cleared at the next count up, the second counter of the Day/ Hour/ Minute/ Second counters is counted up, and a second interrupt request occurs.
- (10) The second counter of the Day/ Hour/ Minute/ Second counters is counted up, it is cleared at the next count up when the value is "59", the minute counter is counted up, and the minute interrupt request occurs at this time.
- (11) The minute counter of Day/ Hour/ Minute/ Second counters is counted up, it is cleared at the next count up when the value is "59", the hour counter is counted up, and the hour interrupt request occurs at this time.
- (12) The hour counter of the Day/ Hour/ Minute/ Second counters is counted up, it is cleared at the next count up when the value is "23", the day counter is counted up, and the day interrupt request occurs at this time.
- (13) The day counter of the Day/ Hour/ Minute/ Second counters is counted up, it is cleared at the next count up when the value is "65535".
- (14) Move to the watch mode by software.
The real-time clock will continue to run in the watch mode.
- (15) Input a signal from an interrupt pin (INT_{xx}) to restore from the watch mode and restart CPU.
- (16) Set the start bit (ST) to "0".
- (17) Use the start bit ST="0" to clear(reset) the sub-second counter (22-bit down counter) and the Day/ Hour/ Minute/ Second counters, and then stop them.

6. Setting

This section explains setting of the real-time clock (RTC).

Table 6-1 Settings Required for Starting the Real-time Clock

Settings	Setting Registers	Setting procedure
Setting of the reload value (sub-second register)	Sub-second register (WTBRH, WTBRM, WTBRL)	See 7.1.
Initialization of the real-time clock	RTC Control Register (WTCR)	See 7.2
Setting of number of days, time (Day/Hour/Minute/Second)	Day/ Hour/ Minute/ Second registers (WTDR, WTHR, WTMR, WTSR)	See 7.3.
Startup of the real-time clock	RTC Control Register (WTCR)	See 7.4.

Table 6-2 Settings Required for Knowing the Time

Settings	Setting Registers	Setting procedure
Reading of number of days and time	Day/ Hour/ Minute/ Second registers (WTDR, WTHR, WTMR, WTSR)	See 7.6.

Table 6-3 Settings Required for Stopping the Real-time Clock

Settings	Setting Registers	Setting procedure
Stop of the real-time clock	RTC Control Register (WTCR)	See 7.7.

Table 6-4 Settings Required for Performing Real-time Clock Interrupts

Settings	Setting Registers	Setting procedure
Setting of the RTC interrupt vector and the RTC interrupt level	See "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".	See 7.10.
RTC interrupt setting Interrupt request clear Interrupt request enable	RTC Control Register (WTCR)	See 7.11.

7. Q&A

This section explains Q&A of the real-time clock (RTC).

- 7.1. How to Set the 0.5 Second Count Interval?
- 7.2. How to Initialize the Real-time Clock?
- 7.3. How to Set/Update Number of Days (Day) and Time (Hour/Minute/Second)?
- 7.4. How to Start/Stop the Count of the Real-time Clock?
- 7.5. How to Confirm That the Real-time Clock Is Running?
- 7.6. How to Know the Number of Days and Time?
- 7.7. How to Stop the Real-time Clock?
- 7.8. How to Calibrate the Real-time Clock?
- 7.9. What Are Interrupt Related Registers?
- 7.10. What Are the Interrupt Types and How to Select Them?
- 7.11. How to Enable Interrupts?

7.1. How to Set the 0.5 Second Count Interval?

This section explains how to set the 0.5 second count interval.

Stop the real-time clock, and set the value indicated in Table 4-2 WTBR Setting Example to the sub-second register(WTBR) according to the RTC clock frequency.

7.2. How to Initialize the Real-time Clock?

This section explains how to initialize the real-time clock.

Perform initialization using the start bit (WTCR:ST).

Write "0" instead of "1" to the start bit to reset all the bits of the Hour/ Minute/ Second counters and the subsecond counter (22-bit down counter) to "0" (initialization) and to stop counting.

7.3. How to Set/Update Number of Days (Day) and Time (Hour/Minute/Second)?

This section explains how to set/update number of days (day) and time (hour/minute/second).

Write the values in Day/ Hour/ Minute/ Second registers(WTDR, WTHR, WTMR, WTSR), and then update them using the update bit (UPDT).

Operation	Update bit (UPDT)
To update the Day/ Hour/ Minute/ Second counters	Set to "1"

7.4. How to Start/Stop the Count of the Real-time Clock?

This section explains how to start/stop the count of the real-time clock.

Use the start bit (WTCR:ST) to set.

Operation	Start bit (ST)
To stop the count of the real-time clock	Set to "0"
To start the count of the real-time clock	Set to "1"

7.5. How to Confirm That the Real-time Clock Is Running?

This section explains how to confirm that the real-time clock is running.

Confirm using the operation flag (WTCR:RUN).

Operation	Operation flag (RUN)
The real-time clock has stopped	"0" can be read
The real-time clock is running	"1" can be read

7.6. How to Know the Number of Days and Time?

This section explains how to know the number of days and time.

They can be known by reading Day/ Hour/ Minute/ Second registers: WTDR, WTHR, WTMR, WTSR.

However, as word access is not available, access to the respective registers is required. As the time may be misread when the value is read in the boundary of the hour/minute count, perform multiple reads and use the logically correct time.

Example:

When read from second:

1 day 2 hours 59 minutes 59 seconds => 1 day 3 hours 59 minutes 59 seconds => 1 day 3 hours 0 minute 0 second

When read from hour:

1 day 2 hours 59 minutes 59 seconds => 1 day 2 hours 0 minute 0 second => 1 day 3 hours 0 minute 0 second

7.7. How to Stop the Real-time Clock?

This section explains how to stop the real-time clock.

See "7.4How to Start/Stop the Count of the Real-time Clock? ".

7.8. How to Calibrate the Real-time Clock?

This section explains how to calibrate the real-time clock.

When the sub clock(only dual clock product) is selected as the RTC clock, the ratio of main clock: sub clock can be used for calibration. See "CHAPTER: RTC/WDT1 CALIBRATION".

7.9. What Are Interrupt Related Registers?

This section explains interrupt related registers.

Setting of RTC interrupt vector and the RTC interrupt level

The following table shows the relationship between interrupt levels and interrupt vectors.

For details on interrupt levels and interrupt vectors, see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".

Interrupt vector (default)	Interrupt level setting bit(ICR[4:0])
#37 (0FFF68 _H)	Interrupt level register ICR21 (00455 _H)

The interrupt request flags (INT0, INT1, INT2, INT3, INT4) are not automatically cleared. Therefore, use software to clear the flags prior to restoration from interrupt processing. (Write "0" to INT0, INT1, INT2, INT3, INT4 bits)

7.10. What Are the Interrupt Types and How to Select Them?

This section explains the interrupt types and selection method.

There are five interrupt factors as follows:

Interrupt factor	Interrupt request bit	Interrupt request enable bit
Time (1second) count timing	INT0	INTE0
Time (minute) count timing	INT1	INTE1
Time (hour) count timing	INT2	INTE2
1 day count timing	INT3	INTE3
Time(0.5 second) count timing	INT4	INTE4

As interrupt occurs by OR of these five factors, select using the interrupt request enable bit.

7.11. How to Enable Interrupts?

This section explains how to enable interrupts.

Use the interrupt request enable bits (WTCR:INTE0, WTCR:INTE1, WTCR:INTE2, WTCR:INTE3, WTCR:INTE4) to perform the operation.

Operation	Setting procedure
	Interrupt request enable bits (INTE0, INTE1, INTE2, INTE3, INTE4)
To disable interrupts	Set to "0"
To enable interrupts	Set to "1"

Use the interrupt request bits (WTCR:INT0, WTCR:INT1, WTCR:INT2, WTCR:INT3) to clear interrupt requests.

Operation	Setting procedure
	Interrupt request bits (INT0, INT1, INT2, INT3, INT4)
To clear interrupt requests	Write "0"

8. Sample Program

This section explains the sample program of the real-time clock.

<p>Setting Procedure Example 1</p> <p>Start to count the real-time clock from 10 days 10 hours 10 minutes 00 second, enable the external interrupt (INT0) for "H" level detection, and move to the watch mode. Restore from the watch mode in case of external interrupt detection, and read the time of the real-time clock.</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-bottom: 10px;"> <tr><td style="text-align: center;">RTC initialization</td></tr> <tr><td style="text-align: center;">RTC startup, interrupt level setting</td></tr> <tr><td style="text-align: center;">External interrupt settings</td></tr> <tr><td style="text-align: center;">Move to the watch mode</td></tr> <tr><td style="text-align: center;">Reading RTC after restoration from the watch mode</td></tr> </table> <p><RTC Initialization Settings></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Register name, bit name</th> <th style="text-align: left;">Register name, bit name</th> </tr> </thead> <tbody> <tr><td>Register initialization</td><td>WTCR.ST</td></tr> <tr><td>Setting of interval time (1second)</td><td>WTBR</td></tr> <tr><td>Setting of the time initialization values</td><td>WTSR WTMR WTHR WTDR</td></tr> <tr><td>Initialization setting for RTC interrupts</td><td>WTCRM,WTCRL WTCRH</td></tr> </tbody> </table> <p><RTC startup, interrupt level setting></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Register name, bit name</th> <th style="text-align: left;">Register name, bit name</th> </tr> </thead> <tbody> <tr><td>RTC startup</td><td>WTCR.ST</td></tr> <tr><td>Setting of interrupt level (RTC)</td><td>ICR21</td></tr> <tr><td>Setting of interrupt level (INT0)</td><td>ICR00</td></tr> <tr><td>Setting of the I flag</td><td>(CCR)</td></tr> </tbody> </table> <p><RTC time reading preparation (interrupt settings) ></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Register name, bit name</th> <th style="text-align: left;">Register name, bit name</th> </tr> </thead> <tbody> <tr><td>RTC interrupt setting</td><td>WTCR .INT0 .INTE0</td></tr> </tbody> </table> <p><RTC interrupt></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Register name, bit name</th> <th style="text-align: left;">Register name, bit name</th> </tr> </thead> <tbody> <tr><td>Time reading</td><td>WTHR WTMR WTSR WTDR</td></tr> <tr><td>Interrupt disable</td><td>WTCR.INTE0</td></tr> </tbody> </table> <p><External interrupt></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Register name, bit name</th> <th style="text-align: left;">Register name, bit name</th> </tr> </thead> <tbody> <tr><td>Clearing of interrupt request flag</td><td>EIRR.ER0</td></tr> </tbody> </table> <p><Interrupt Vector> Setting of the vector table</p> <p><Other> (Note) Clock related settings and __set_ii (number) setting are required to be performed in advance. See "CHAPTER: CLOCK" and "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)".</p>	RTC initialization	RTC startup, interrupt level setting	External interrupt settings	Move to the watch mode	Reading RTC after restoration from the watch mode	Register name, bit name	Register name, bit name	Register initialization	WTCR.ST	Setting of interval time (1second)	WTBR	Setting of the time initialization values	WTSR WTMR WTHR WTDR	Initialization setting for RTC interrupts	WTCRM,WTCRL WTCRH	Register name, bit name	Register name, bit name	RTC startup	WTCR.ST	Setting of interrupt level (RTC)	ICR21	Setting of interrupt level (INT0)	ICR00	Setting of the I flag	(CCR)	Register name, bit name	Register name, bit name	RTC interrupt setting	WTCR .INT0 .INTE0	Register name, bit name	Register name, bit name	Time reading	WTHR WTMR WTSR WTDR	Interrupt disable	WTCR.INTE0	Register name, bit name	Register name, bit name	Clearing of interrupt request flag	EIRR.ER0	<p>Program Example 1</p> <pre> void RTC_sample1(void) { RTC_initial(); RTC_start(); EX_INT0_initial(); /* Subroutine for external interrupt setting*/ STOP_Hiz_hold_with_clock(); /* Subroutine for moving to the watch mode*/ RTC_read(); } void RTC_initial(void) { IO_WTCR.bit.ST = 1; /* Initialization preparation*/ IO_WTCR.bit.ST = 0; /* Stop (register initialization)*/ IO_WTBR.word = 0x0F423F; /* Count value setting 4MHz/2 × 0x0F423F=0.5 second */ IO_WTSR.byte = 0x00; /* Second setting */ IO_WTMR.byte = 0x0A; /* Minute setting */ IO_WTHR.byte = 0x0A; /* Hour setting */ IO_WTDR.hword = 0x000A; /* Day setting */ IO_WTCRL.hword = IO_WTCRL.hword & 0x0000; /* Interrupt flag clear, interrupt disable*/ IO_WTCRH.byte = 0x00 /* Interrupt flag clear, interrupt disable*/ } void RTC_start(void) { IO_WTCR.bit.ST = 1; /* RTC startup*/ IO_ICR[21].bit.ICR = 18; /* The value is arbitrary */ IO_ICR[00].bit.ICR = 20; /* The value is arbitrary */ __EI(); /* Interrupt enable */ } RTC_read(void) { IO_WTCR.bit.INT0 = 0; /* RTC second interrupt request flag clear*/ IO_WTCR.bit.INTE0 = 1; /* RTC second interrupt request enable */ } __interrupt void RTC_read_int(void) /* RTC interrupt */ { JIKAN(char) = IO_WTHR.byte & 0x1F; /*Hour*/ FUNN(char) = IO_WTMR.byte & 0x3F; /*Minute*/ BYOU(char) = IO_WTSR.byte & 0x3F; /*Second*/ HI(char) = IO_WTDR.hword; /*Day*/ /*Multiple reads*/ IO_WTCR.bit.INTE0 = 0; /* RTC interrupt disable */ } __interrupt void INT0_int() /* External interrupt */ { IO_EIRR.bit.ER0= 0; /* ER0 second interrupt request flag clear*/ } </pre>
RTC initialization																																								
RTC startup, interrupt level setting																																								
External interrupt settings																																								
Move to the watch mode																																								
Reading RTC after restoration from the watch mode																																								
Register name, bit name	Register name, bit name																																							
Register initialization	WTCR.ST																																							
Setting of interval time (1second)	WTBR																																							
Setting of the time initialization values	WTSR WTMR WTHR WTDR																																							
Initialization setting for RTC interrupts	WTCRM,WTCRL WTCRH																																							
Register name, bit name	Register name, bit name																																							
RTC startup	WTCR.ST																																							
Setting of interrupt level (RTC)	ICR21																																							
Setting of interrupt level (INT0)	ICR00																																							
Setting of the I flag	(CCR)																																							
Register name, bit name	Register name, bit name																																							
RTC interrupt setting	WTCR .INT0 .INTE0																																							
Register name, bit name	Register name, bit name																																							
Time reading	WTHR WTMR WTSR WTDR																																							
Interrupt disable	WTCR.INTE0																																							
Register name, bit name	Register name, bit name																																							
Clearing of interrupt request flag	EIRR.ER0																																							

9. Notes

This section explains notes of the real-time clock.

- The interrupt request flags (WTCR:INT0, WTCR:INT1, WTCR:INT2, WTCR:INT3, WTCR:INT4) will be set to "1" when they are written to "0" at the same time when they are set to "1" in case of overflow. (Flag setting takes precedence)
- When reload occurs while update on the sub-second register (WTBRH, WTBRM, WTBRM) is in progress, an unexpected value may be reloaded to the sub-second counter (22-bit down counter). Therefore, it is recommended to update the sub-second register (WTBR) while the start bit (WTCR:ST) is "0".
- When all the bits of the sub-second register (WTBRH, WTBRM, WTBRM) are set to "0", the sub-second counter (22-bit down counter) will not run. Therefore, the real-time clock will not run.
- Carry may occur while Day/Hour/Minute/Second registers (WTDR, WTHR, WTMR, WTSR) are being read, leading to inappropriate read values. Therefore, it is recommended to use interrupt (INT0) to read the number of days and time (Day/Hour/Minute/Second).
- As word access is not available for Day/Hour/Minute/Second registers (WTDR, WTHR, WTMR, WTSR), access to the respective registers is required. Therefore, as the time may be misread when the value is read in the boundary of the hour/minute count, perform multiple reads and use the logically correct time.

Example:

When read from second:

1 day 23 hours 59 minutes 59 seconds=>2 days 0 hour 59 minutes 59 seconds=>2 days 0 hour 0 minute 0 second

When read from hour:

1 day 23 hours 59 minutes 59 seconds=>2 days 23 hours 0 minute 0 second=>2 days 0 hour 0 minute 0 second

When read from day:

1 day 23 hours 59 minutes 59 seconds=>1 day 0 hour 0 minute 0 second=>2 days 0 hour 0 minute 0 second

This case is judged as 2 days 0 hour.

- Day/Hour/Minute/Second registers are not cleared by internal reset, while Day/Hour/Minute/Second counters are cleared by internal reset. After internal reset occurs, the ST flag is cleared, and the RTC macro is in the stop state. In addition, counter values prior to internal reset are set to Day/Hour/Minute/Second registers. To use Day/Hour/Minute/Second in case of internal reset, set the values read from the Day/Hour/Minute/Second counters to the Day/Hour/Second registers.
- The number of days register has a built-in function for counting the number of days from "0 day" to "65535 days".
- Notes on Setting the RTC Control Register
 - When writing "1" to the start bit (ST) from RTC stop state (ST=0) (RTC operation start), do not write "1" to the update bit (UPDT) at the same time as the start bit. (While ST=0, writing "1" as byte immediate value to the ST bit and the UPDT bit at the same time is prohibited.)
 - To write "1" to the update bit (UPDT), do it while RTC is running (ST=1).
 - While the update bit (UPDT) is "1", writing "0" to the start bit (ST) (RTC stop) is prohibited.
- When returning from the standby watch mode (power shutdown), the register of RTC is not initialized.
- The internal reset is issued at the return from the standby watch mode (power shutdown). Therefore, only the reset factors (power-on reset, internal low-voltage reset, and simultaneous assert of RSTX and NMIX) are accepted. At this time, the register of the RTC is not initialized. If the reset input from the RSTX pin input or the external low-voltage detection flag is set after the start-up, initialize the register of RTC before using.

CHAPTER : RTC/WDT1 CALIBRATION

This chapter explains the RTC/WDT1 calibration.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

Code : 25_MB91590_HM_E_rtccal_003_20111127

1. Overview

This section explains the overview of the RTC/WDT1 calibration.

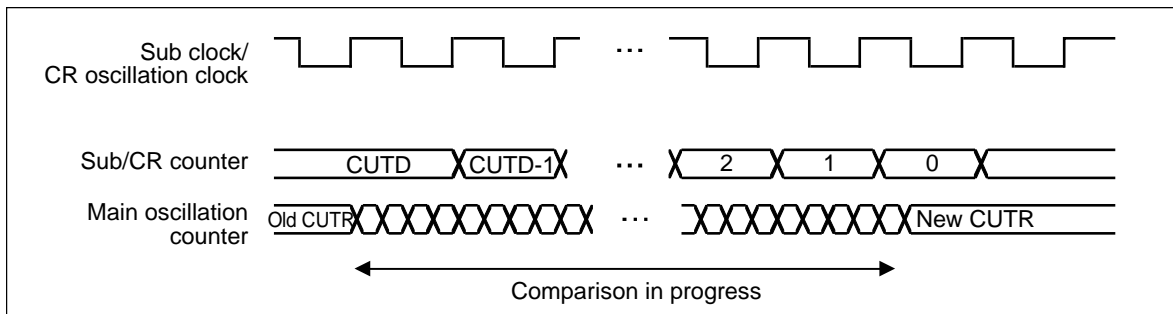
This module calculates the values for frequency calibrations in CR oscillation circuit built in real-time clock, WDT1 and CSV.

2. Features

This section explains features of the RTC/WDT1 calibration.

- RTC Clock source select register
 - See "CHAPTER: CLOCK" for the selection method. The main clock or sub clock(only dual clock product) can be selected.
- Real-Time Clock (RTC) Calibration (Only dual clock product. A function that is effective only when the sub clock is used.)
 - Operates the main clock driven counter and the sub clock driven counter concurrently (Figure 2-1), and calculates the sub clock frequency from the main clock frequency to set the prescaler value of RTC.
- WDT1(CR clock) calibration
 - Operates the main clock driven counter and the CR clock driven counter concurrently (Figure 2-1), and calculates the CR clock frequency from the main clock frequency to set the CR clock trimming value.

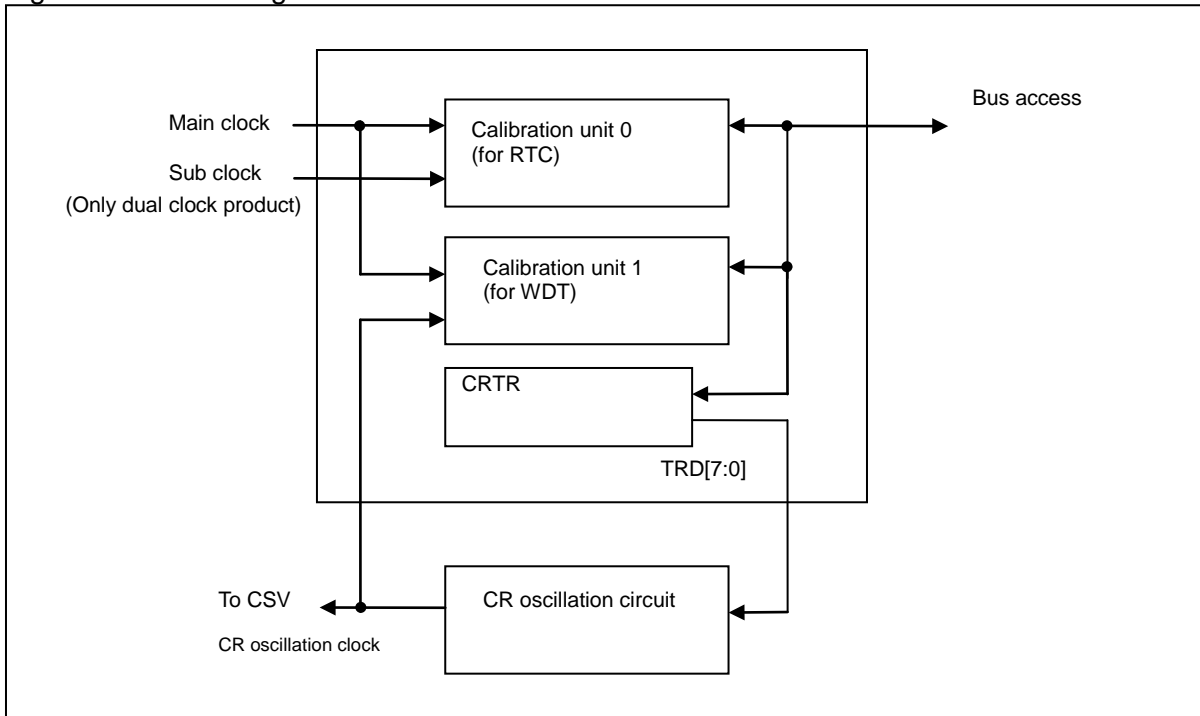
Figure 2-1 Comparison for Counters Driven by Different Clocks



3. Configuration

This section explains the configuration of the RTC/WDT1 calibration.

Figure 3-1 Block Diagram



4. Registers

This section explains the registers of the RTC/WDT1 calibration.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x04B8	CUCR0		CUTD0		Calibration unit control register 0 Sub clock timer data register
0x04BC	CUTR0				Main oscillation timer data register 0
0x04C0	Reserved	Reserved	Reserved	Reserved	Reserved
0x04C4	CUCR1		CUTD1		Calibration unit control register 1 CR oscillation timer data register
0x04C8	CUTR1				Main oscillation timer data register 1
0x04CC	CRTR	Reserved	Reserved	Reserved	CR oscillation trimming setting register

4.1. Calibration Unit Control Register 0 : CUCR0 (Calibration Unit Control Register 0)

The bit configuration of the calibration unit control register 0 (CUCR0) is explained.

This register configures calibration start and interrupts for RTC calibration unit.

■ CUCR0 : Address 04B8_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	1	1	1	1	1	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	Reserved		STRT	Reserved		INT	INTEN
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,WX	R0,WX	R,W	R0,WX	R0,WX	R,W	R,W

[bit7] Reserved

"0" should be written to this bit.

[bit4] STRT (calibration STaRT) : Calibration start

This bit starts counters driven by main clock and sub clock. The INT bit will be set at the end of comparison.

STRT	Function
"0" write	Stops comparison
"1" write	Starts comparison

Setting "0" to this bit stops comparison. While comparing, writing "1" to this bit will not take effect. This bit will be cleared to "0" at the end of comparison.

[bit1] INT (calibration INTerrupt) : Interrupt

The INT bit will be set to "1" at the end of comparison. If the INTEN bit has been set, an interrupt will occur. This bit is cleared by writing "0".

[bit0] INTEN (calibration INTerrupt ENable) : Interrupt enable

This bit sets whether to generate an interrupt when the INT bit is set.

INTEN	Interrupt
0	Disabled
1	Enabled

4.2. Sub Clock Timer Data Register : CUTD0 (Calibration Unit Timer Data register 0)

The bit configuration of the sub clock timer data register (CUTD0) is explained.

This register configures the time interval for driving sub clock driven counter.

■ CUTD0 : Address 04BA_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TDD[15:8]							
Initial value	1	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TDD[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit0] TDD[15:0] (Timer Data Data field) : Timer data

These bits configure the comparison time interval in number of sub clocks.

4.3. Main Oscillation Timer Result Register 0 : CUTR0 (Calibration Unit Timer Result register 0)

The bit configuration of the main oscillation timer result register 0 (CUTR0) is explained.

This register displays the number of the main clock driven counter within the interval set using CUTD0.

■ **CUTR0 : Address 04BC_H (Access: Byte, Half-word, Word)**

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX
	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	TDR[23:16]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX
	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TDR[15:8]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TDR[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit23 to bit0] TDR[23:0] (Timer Data Register) : Timer data

These bits display the value of the count in the comparison interval. Read the results at the end of comparison results. The read value during comparison is undefined. Writing has no effect on operation.

4.4. Calibration Unit Control Register 1 : CUCR1 (Calibration Unit Control Register 1)

The bit configuration of the calibration unit control register 1 (CUCR1) is explained.

This register configures calibration start and interrupts for the WDT calibration unit.

■ CUCR1 : Address 04C4_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	1	1	1	1	1	1	1	1
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	Reserved		STRT	Reserved		INT	INTEN
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,WX	R0,WX	R,W	R0,WX	R0,WX	R,W0	R/W

[bit7] Reserved

"0" should be written to this bit.

[bit4] STRT (calibration STaRT) : Calibration start

This bit starts counters driven by main clock and CR clock. The INT bit will be set at the end of comparison.

STRT	Function
"0" write	Stops comparison
"1" write	Starts comparison

Setting "0" to this bit stops comparison. While comparing, writing "1" to this bit will not take effect. This bit will be cleared to "0" at the end of comparison.

[bit1] INT (calibration INTerrupt) : Interrupt

The INT bit will be set to "1" at the end of comparison. If the INTEN bit has been set, an interrupt will occur. This bit is cleared by writing "0".

[bit0] INTEN (calibration INTerrupt Enable) : Interrupt enable

This bit sets whether to generate an interrupt when the INT bit is set.

INTEN	Interrupt
0	Disabled
1	Enabled

4.5. CR Clock Timer Data Register : CUTD1 (Calibration Unit Timer Data register 1)

The bit configuration of the CR clock timer data register (CUTD1) is explained.

This register sets the CR clock driven counter drive duration.

■ CUTD1 : Address 04C6_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TDD[15:8]							
Initial value	1	1	0	0	0	0	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TDD[7:0]							
Initial value	0	1	0	1	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit0] TDD[15:0] (Timer Data Data field) : Timer data

These bits configure the comparison time interval in number of CR clocks.

4.6. Main Oscillation Timer Result Register 1 : CUTR1 (Calibration Unit Timer Result register 1)

The bit configuration of the main oscillation timer result register 1 (CUTR1) is explained.

This register displays the number of the main clock driven counter in the interval set using CUTD1.

■ CUTR1 : Address 04C8_H (Access: Byte, Half-word, Word)

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX
	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	TDR[23:16]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX
	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TDR[15:8]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TDR[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit23 to bit0] TDR[23:0] (Timer Data Register) : Timer data

These bits display the value of the count in the comparison interval. Read the results at the end of comparison.
The read value during comparison is undefined. Writing is disabled.

4.7. CR Oscillation Trimming Setting Register : CRTR (CR oscillator calibration Trimming Register)

The bit configuration of the CR oscillation trimming setting register (CRTR) is explained.

This register sets the trimming value for the CR oscillation circuit.

■ CRTR : Address 04CC_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TRD[7:0]							
Initial value	0	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] TRD[7:0] (Trimming Data) :

								Trimming Value (in steps of about 0.4%)	
TRD7	TRD6	TRD5	TRD4	TRD3	TRD2	TRD1	TRD0	Trimming value *	n value
0	0	0	0	0	0	0	0	-48.01%	0
0	0	0	0	0	0	0	1	-47.61%	1
0	0	0	0	0	0	1	0	-47.23%	2
.
.
0	1	1	1	1	1	1	1	0% (Initial value)	127
.
.
1	1	1	1	1	1	0	1	+45.62%	253
1	1	1	1	1	1	1	0	+45.98%	254
1	1	1	1	1	1	1	1	+46.37%	255

*: As changes take place according to conditions such as temperature, it is necessary to perform using the procedure explained at "5.2".

5. Operation

This section explains an operation of the RTC/WDT1 calibration.

- 5.1. Real-Time Clock (RTC) Calibration
- 5.2. WDT1 Calibration (CR Clock Calibration)
- 5.3. Notes

5.1. Real-Time Clock (RTC) Calibration

This section explains real-time clock (RTC) calibration.

The calibration procedure is as follows:

1. Sets CUTD0
2. Sets CUCR0:INTEN
3. Sets CUCR0:STRT
4. Interrupt Waiting Loop
5. Interrupt Occurrence
6. CUTR0 Reading
7. Comparison of CUTR0 and CUTD0 can be used to calculate the ratio of the main clock frequency and the frequency of sub clock.
8. Sets the prescaler value in RTC using the value calculated at (7).

5.2. WDT1 Calibration (CR Clock Calibration)

This section explains WDT1 calibration (CR clock calibration).

Calculate the trimming value as follows:

1. Set TRD[7:0] to 00000000 to start the calibration unit, and get the CUTR value. Take the CR oscillation frequency calculated from this CUTR value as Fmin.
2. Set TRD[7:0] to 11111111 to start the calibration unit, and get the CUTR value. Take the CR oscillation frequency calculated from this CUTR value as Fmax.
3. Substitute 0 to 255 for n in the following formula, and find n which makes Fer the minimum, which is the trimming value.

$$Fstep = (Fmax - Fmin) / 255$$

$$Fer = |(100kHz) - (Fmin + Fstep \times n)|$$

5.3. Notes

This section explains notes of the RTC/WDT1 calibration.

The counter value becomes invalid if factors, such as standby mode transition have been included. Write "0" to the STRT bit to stop, and write "1" again to redo.

CHAPTER: POWER CONSUMPTION CONTROL

This chapter explains the power consumption control.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Example of Use

Code : 26_MB91590_HM_E_powercnt_010_20111127

1. Overview

This section explains the overview of the power consumption control.

This series have variety of low-power consumption modes and can perform the power consumption control feature accordingly for situations.

2. Features

This section explains features of the power consumption control.

● **Clock control for low-power**

Clock division

The clock division can change the division ratio for each running clock and lower the running frequency accordingly. See "CHAPTER: CLOCK".

● **Sleep mode**

CPU sleep mode

By setting this mode, operation of the CPU core are stopped. But, peripherals continue to run. .

Bus sleep mode

By setting this mode, operation of the CPU core and on-chip buses are stopped.

● **Standby mode**

Watch mode

By setting this mode, all operations are stopped except for some clock oscillations and the timer operations.

Stop mode

By setting this mode, all clock oscillation and operations are stopped.

● **Standby mode with power-shutdown**

Watch mode with power-shutdown

By setting this mode, microcontroller unit can be controlled to set power-shutdown state and all operations are stopped except for some clock oscillations and the timer.

Stop mode with power-shutdown

By setting this mode, microcontroller unit can be controlled to set power-shutdown state and all clock oscillations and operations are stopped.

Power-shutdown of GDC unit

By setting this mode, GDC unit can be controlled to power-shutdown state separately from microcontroller unit. Unless setting GDC unit to power-shutdown, microcontroller unit can not be controlled to set power-shutdown state.

3. Configuration

This section explains the configuration of the power consumption control.

Figure 3-1 Block Diagram of Overall Control

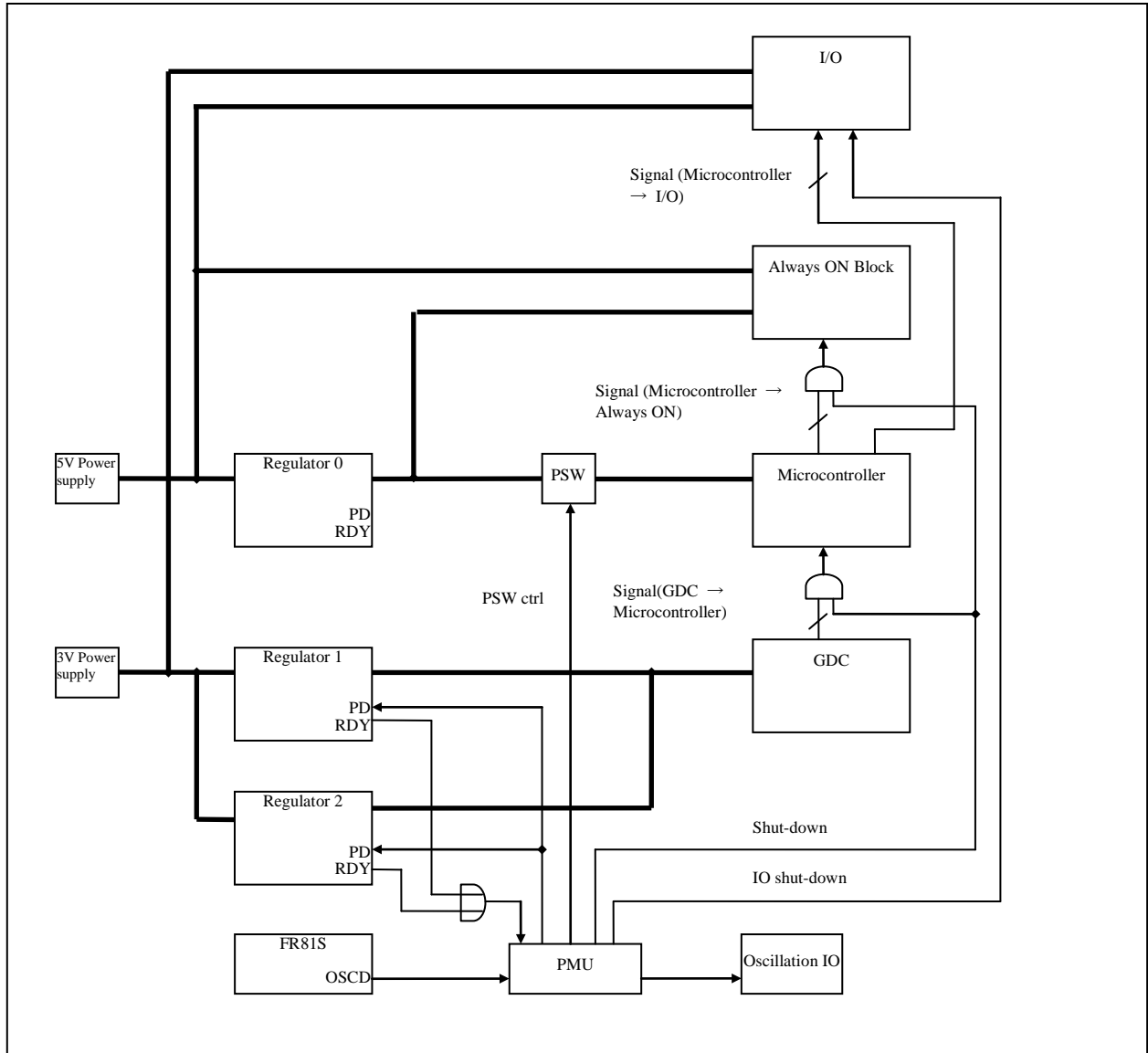
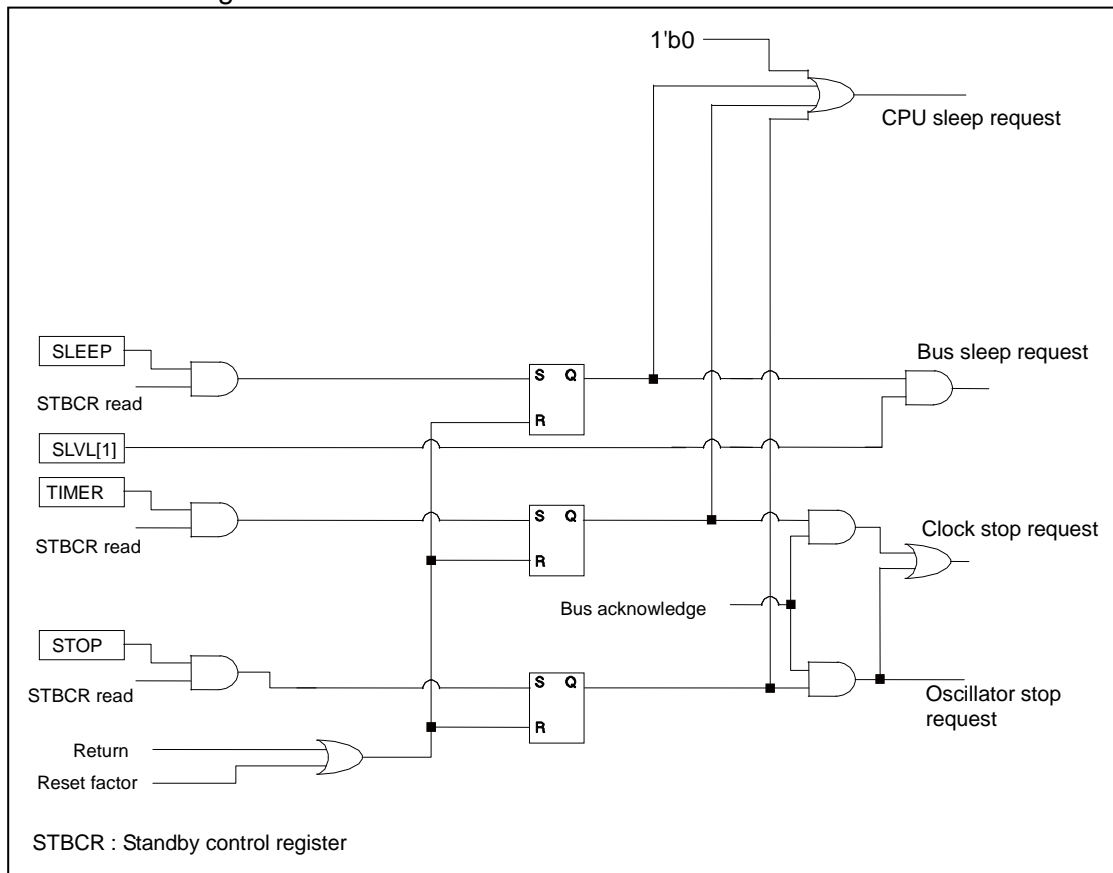


Figure 3-1 Block Diagram of Microcontroller Internal Control



4. Registers

This section explains registers of the power consumption control.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0480	Reserved	Reserved	STBCR	Reserved	Standby control register
0x0590	Reserved	PMUCTLR	PWRMCTL	Reserved	PMU control register Power on timing control register
0x0594	PMUINTF0	PMUINTF1	PMUINTF2	Reserved	PMU interrupt flag register 0 to 2
0x0598	GSTR	GCTLR	Reserved	Reserved	GDC status register GDC control register
0x059C	Reserved	Reserved	Reserved	Reserved	Reserved

Note:

Note that address of 0x0480 to 0x0481 and 0x0590 is allocated for the register of "RESET". (See "CHAPTER: RESET".)

Note:

A group of registers (except for STBCR) is initialized only when one or some of the following resources occur.

1. Power-on reset
2. Internal low-voltage detection
3. Simultaneous assert of RSTX and NMIX external pins
4. Hardware watchdog reset

* : Registers are not initialized by reset of the INIT level and RST level. (exception for STBCR)

4.1. Standby Control Register : STBCR (STandby mode Control Register)

The bit configurations of the standby control register are shown below.

This register configures low-power consumption modes.

Note:

Writing to this register by DMA is prohibited.

■ STBCR : Address 0482_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	STOP	TIMER	SLEEP	Reserved	Reserved		SLVL[1:0]	
Initial value	0	0	0	0	0	0	1	1
Attribute	R,W	R,W	R,W	R0,W0	R0,W0	R0,W0	R/W	R/W

[bit7] STOP (STOP mode) : Stop mode enabled

[bit6] TIMER (TIMER mode) : Watch mode enabled

[bit5] SLEEP (SLEEP mode) : Sleep mode enabled

Transition to each standby mode; stop, watch and sleep are specified and enabled by those 3 bit. CPU goes into each standby mode by reading STBCR after writing the values shown below to those 3 bit.

STOP	TIMER	SLEEP	Transition to each standby mode enabled
0	0	0	No transition (initial value)
0	0	1	Transit to sleep mode by reading STBCR
0	1	X	Transit to watch mode by reading STBCR
1	X	X	Transit to stop mode by reading STBCR

The read value of each bit is as follows regardless of the writing value.

STOP	TIMER	SLEEP	Transition to each standby mode enabled
0	0	0	No transition
0	0	1	Transit to sleep mode
0	1	0	Transit to watch mode
1	0	0	Transit to stop mode

These bits are cleared to an initial value by generating the wake up factor from each low-power consumption mode.

[bit4] Reserved

The read value is always "0". This bit must always be written to "0".

[bit3, bit2] Reserved

The read value is always "0". These bits must always be written to "0".

[bit1, bit0] SLVL[1:0] (Standby LeVeL) : Standby level setting

These bits control the operations in standby mode and sleep mode as follows.

Mode	SLVL[1:0]	Operation control
Stop mode	0x	Pins are not used for high impedance.
	1x	Pins are used for high impedance.
Watch mode	0x	Pins are not used for high impedance.
	1x	Pins are used for high impedance.
Sleep mode	0x	CPU sleep mode (stop only CPU)
	1x	Bus sleep mode (stop CPU and on-chip bus) *

* : On-chip bus will run when DMA transfer is in progress.

For information on pins with high impedance, see "APPENDIX".

4.2. PMU Control Register : PMUCTLR (Power Management Unit ConTRoL register)

The bit configurations of the PMU control register are shown below.

This register controls PMU.

■ PMUCTLR : Address 0591_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SHDE	Reserved	IOCTMD	IOCT	Reserved			
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R/W	R/W	R0,W0	R0,W0	R0,W0	R0,W0

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7] SHDE (SHut Down Enable)

This setting is for whether you establish shutdown mode when the CPU mode transits to standby (watch/stop).

SHDE	SHDE mode enable
0	When transiting to standby, you must not execute shutdown process.
1	When transiting to standby, you must execute shutdown process.

* Though this bit is enabled during GDC operation and the mode transits to standby, you must not execute shutdown process.

[bit6] Reserved

The read value is always "0". This bit must always be written to "0".

[bit5] IOCTMD (I/O Clear Timing MoDe)

This bit selects timing to maintain the I/O state when returning from standby (ShutDown) mode. (Hardware process)

IOCTMD	I/O maintain cancellation request mode
0	I/O state is maintained until returning from standby (WATCH and STOP) mode.
1	I/O state is maintained until IOCT register is cleared.

[bit4] IOCT (I/O Clear Timing)

By setting this bit to "1" when IOCTMD=1, I/O state maintaining are cancelled.

IOCT	I/O maintain cancellation request
0	No request
1	Request is on-going

This bit is cleared to "0" automatically after cancellation of I/O maintaining by I/O state maintaining cancellation request is accepted.

Writing at times other than when I/O is maintained is invalid.

Writing this bit to "0" is invalid.

[bit3 to bit0] Reserved

The read value is always "0". These bits must always be written to "0".

4.3. PoWeR on TiMing Control Register : PWRTMCTL (PoWeR on TiMing ConTroL register)

The bit configurations of the PoWeR on TiMing control register are shown below.

This register controls timing for power-on reset and so on.

■ **PWRTMCTL : Address 0592_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					PTC[2:0]		
Initial value	0	0	0	0	0	0	1	1
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7 to bit3] Reserved

The read value is always "0". These bits must always be written to "0".

[bit2 to bit0] PTC[2:0] (Power on Timing Cycle setting)

These bits set the rising time for PSW.

PTC[2:0]	Rising time	Remarks of the case that PMUCLK=32kHz
000	$1 \times (1/PMUCLK)$	30μS
001	$3 \times (1/PMUCLK)$	90μS
010	$5 \times (1/PMUCLK)$	150μS
011	$9 \times (1/PMUCLK)$	270μS
100	Prohibit	-
101	$2 \times (1/PMUCLK)$	60μS
110	$4 \times (1/PMUCLK)$	120μS
111	$7 \times (1/PMUCLK)$	210μS

4.4. PMU Interrupt Flag Register 0 : PMUINTF0 (Power Management Unit INTerrupt Flag0 register)

The bit configurations of the PMU interrupt flag register 0 are shown below.

This register indicates the interrupt request by external input at shutdown.

■ PMUINTF0 : Address 0594_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EIF15	EIF14	EIF13	EIF12	EIF11	EIF10	EIF9	EIF8
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7 to bit0] EIF15 to EIF8 (External Interrupt Flag15 to 8)

These flags indicate the interrupt request by external input at shutdown.

EIFn	External interrupt request
0	No request
1	Request

n -> The number from 15 to 8 is assigned.

These bits are enabled only at shutdown.

These bits are cleared by writing to "0". Writing to "1" is invalid.

4.5. PMU Interrupt Flag Register 1 : PMUINTF1 (Power Management Unit INTerrupt Flag1 register)

The bit configurations of the PMU interrupt flag register 1 are shown below.

This register indicates the interrupt request by external input at shutdown.

■ PMUINTF1 : Address 0595_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EIF7	EIF6	EIF5	EIF4	EIF3	EIF2	EIF1	EIF0
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7 to bit0] EIF7 to EIF0 (External Interrupt Flag7 to 0)

These flags indicate the interrupt request by external input at shutdown.

EIFn	External interrupt request
0	No request
1	Request

n -> The number from 7 to 0 is assigned.

These bits are enabled only at shutdown.

These bits are cleared by writing to "0". Writing to "1" is invalid.

4.6. PMU Interrupt Flag Register 2 : PMUINTF2 (Power Management Unit INTerrupt Flag2 register)

The bit configurations of the PMU interrupt flag register 2 are shown below.

This register indicates the interrupt request at shutdown.

■ PMUINTF2 : Address 0596_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	RIF	NIF	MTIF	STIF	Reserved			
Initial value	0	0	0	0	0	0	0	0
Attribute	R(RM1), W	R(RM1), W	R(RM1), W	R(RM1), W	R0,W0	R0,W0	R0,W0	R0,W0

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7] RIF (Rtc Interrupt Flag)

This flag indicates the interrupt request by RTC at shutdown.

RIF	RTC interrupt request
0	No request
1	Request

This bit is enabled only at shutdown.

This bit is cleared by writing to "0". Writing to "1" is invalid.

[bit6] NIF(Nml Flag)

This flag indicates the interrupt request by NMI at shutdown.

NIF	NMI interrupt request
0	No request
1	Request

This bit is valid only at shutdown.

This bit is cleared by writing to "0". Writing to "1" is invalid.

[bit5] MTIF (Main Timer Interrupt Flag)

This flag indicates the interrupt request by Main Timer at shutdown.

MTIF	Main timer interrupt request
0	No request
1	Request

This bit is enabled only at shutdown.

This bit is cleared by writing to "0". Writing to "1" is invalid.

[bit4] STIF (Sub Timer Interrupt Flag)

This flag indicates the interrupt request by Sub Timer at shutdown.

STIF	Sub timer interrupt request
0	No request
1	Request

This bit is enabled only at shutdown.

This bit is cleared by writing to "0". Writing to "1" is invalid.

[bit3 to bit0] Reserved

The read value is always "0". These bits must always be written to "0".

4.7. GDC Status Register : GSTR (Gdc Status Register)

The bit configurations of the GDC status register are shown below.

This register indicates the status of GDC.

■ GSTR : Address 0598_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GPWRST	Reserved						
Initial value	0	0	0	0	0	0	0	0
Attribute	R	R0	R0	R0	R0	R0	R0	R0

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7] GPWRST (Gdc PoWeR Status)

This bit indicates the status of power supply in GDC.

GPWRST	State of power supply
0	power off or power supply instability
1	during power-on

[bit6 to bit0] Reserved

The read value is always "0".

4.8. GDC Control Register : GCTLR (Gdc Control Register)

The bit configurations of the GDC control register are shown below.

This register controls GDC.

■ GCTLR : Address 0599_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SETEN				Reserved	GPSET	GSET	GPD
Initial value	0	0	0	0	0	1	1	1
Attribute	W	W	W	W	R0,W0	R/W	R/W	R/W

This register will be initialized by power-on reset, internal low-voltage reset, reset by simultaneous assert of RSTX and NMIX, and hardware watchdog timer reset.

[bit7 to bit4] SETEN (SET ENable)

When each bit of GPSET, GSET and GPD is set, these bit must be written simultaneously, for example, by storing "0xA" to the register. If other value is written, the setting for each bit of GPSET, GSET and GPD is disabled. (Countermeasures for malfunctions when the CPU runaway)

[bit3] Reserved

The read value is always "0". This bit must always be written to "0".

[bit2] GPSET (Gdc Power SET)

This bit controls Isolator (power supply monitor) in GDC.

GPSET	Isolator state
0	Isolator disabled
1	Isolator enabled

This bit masks input (power supply monitor) from GDC when Isolator is enabled.

[bit1] GSET (Gdc SET)

This bit controls Isolator (normal) in GDC.

GSET	Isolator state
0	Isolator disabled
1	Isolator enabled

This bit masks input (normal) from GDC when Isolator is enabled.

[bit0] GPD (Gdc Power Down)

This bit controls PD of regulator in GDC.

GPD	PD control
0	Disabled
1	Enabled

* This bit is not initialized by a hardware watchdog.

5. Operation

The power consumption control features of this series are explained as follows.

- 5.1. Clock Control
- 5.2. List of Clock Supply in Low-power Consumption Mode
- 5.3. Sleep Mode
- 5.4. Standby Mode : Watch Mode
- 5.5. Standby Mode : Watch Mode with power-shutdown
- 5.6. Standby Mode : Stop Mode
- 5.7. Standby Mode : Stop Mode with power-shutdown
- 5.8. Stop State of Microcontroller
- 5.9. Power-shutdown GDC Unit
- 5.10. Transition to Illegal Standby Mode
- 5.11. GDC Regulator
- 5.12. Restrictions on Power Shutdown and Normal Standby Control

5.1. Clock Control

This section explains the clock control of the power consumption control.

This series can perform optimization of power consumption and processing ability by adjusting each operating clock.

■ Division Setting

See "CHAPTER: CLOCK".

■ Stopping of Unused Clocks

Following clocks have the setting to stop separately.

- External bus clock (TCLK): Can select to supply/stop in bus sleep mode

For details on the setting method, see "CHAPTER: CLOCK".

5.2. List of Clock Supply in Low-power Consumption Mode

The list of clock supply in low-power consumption mode is shown below.

Table 5-1 List of Clock Supply in Low-power Consumption Mode

Clock	Standby		Sleep	
	Stop	Watch	Bus	CPU
CPU clock (CCLK)	○	○	○	×
CAN Prescaler Clock	○	○	*1	×
On-chip bus clock (HCLK)	○	○	○	×
Peripheral clock (PCLK)	○	○	×	×
External bus I/F clock (TCLK)	○	○	*2	×
PLL clock (PLLCLK)	○	○	×	×
Main clock (MCLK)	○	×	×	×
Sub clock (SBCLK)	○	×	×	×
CR oscillation	○*4	○*4	×*3	×*3

○: Stops

×: Does not stop.

(If the main/sub/PLL let them stop in each clock setting register, follow those.)

*1: When on-chip bus clock (HCLK) is selected as CAN prescaler clock, this clock stops. When PLL output is selected, it depends on PLL output. Otherwise, this clock does not stop.

*2: This clock is set by the DIVR1:TSTP bit. See "CHAPTER: CLOCK".

*3: During sleep mode, the CR oscillation does not stop, but the watchdog timer 1 (HWWDT) stops.

*4: It is necessary to set it beforehand to stop the CR oscillation at the standby.

See the description of CSVCR:RCE in "CHAPTER: CLOCK SUPERVISOR".

5.3. Sleep Mode

This section explains sleep mode.

Sleep mode is the mode which CPU and on-chip bus stop and only the peripherals run. In sleep mode, there are several modes for different stop ranges.

- CPU sleep mode : Stops CPU only.
- Bus sleep mode : Stops CPU and on-chip bus.

The stop state is continued until a wake up request occurs. A return to the program operation within several clock times is possible by generating a wake up request.

Following are the explanation of an operation of each mode.

■ CPU Sleep Mode

CPU sleep mode is the mode to stop the CPU operation.

In this mode, the DMA controller and on-chip bus can continue their operation, while more power will be consumed than that of bus sleep mode.

■ Bus Sleep Mode

Bus sleep mode is the mode to stop CPU and on-chip bus operations. In this mode, the CPU clock (CCLK) and on-chip bus clock (HCLK) will stop.

When accepting a DMA transfer request in bus sleep mode, on-chip bus clock (HCLK) supply resumes temporarily and performs DMA transfers. After the DMA transfer, stop the on-chip bus clock (HCLK) again.

In this mode, you can decrease the amount of power consumption more than that of CPU sleep mode, but the response time to the DMA transfer request will be somewhat degraded.

■ Configuration of Sleep Mode

Before activating sleep mode, select whether to supply/stop external bus clock in sleep mode with the values set to bit7:TSTP in the DIVR1 register.

- When setting bit7:TSTP="0" in the DIVR1 register, the external bus clock does not stop.
- When setting bit7:TSTP="1" in the DIVR1 register, the external bus clock stops.

When activating sleep mode, select the level of sleep mode with the values set to bit1:SLVL1 in the STBCR register.

- When setting bit1:SLVL1="0" in the STBCR register, CPU goes into CPU sleep mode.
- When setting bit1:SLVL1="1" in the STBCR register, CPU goes into bus sleep mode.

■ Activation of Sleep mode

To activate sleep mode, follow the steps below.

- Write "001" to bit7:STOP, bit6:TIMER, bit5:SLEEP in the STBCR register.
- Read STBCR

In FR81S core, if the read value will not be used in the next instruction, that instruction is executed before the read is completed. Perform dummy processing to use the read value in the next instruction so as not to make the program progress before entering sleep mode.

[Example] Sample program of sleep mode activation

```
LDI    #value_of_sleep, R0    ; SLEEP bit ="1", SLVL setting
LDI    #_STBCR, R12           ;
STB    R0, @R12              ; Write
LDUB   @R12, R0              ; Read (activation of sleep mode)
MOV    R0, R0                ; Dummy processing for pipeline adjustment
NOP                          ; Dummy processing for pipeline adjustment
```

■ Wake Up from the Sleep Mode

To stop sleep mode, follow the conditions below.

- Reset
- Generation of interrupt request whose value of corresponding ICR register is value other than "0x1F"
- Generation of NMI request
- Generation of tool break while connected to ICE

For wake up from interrupt request, CPU does not always have to accept this interrupt request. When an interrupt request is not accepted, the program starts from next instruction which activates sleep mode.

In the bus sleep mode, the on-chip bus clock (HCLK) is temporarily returned by generating the DMA transfer request and DMA transfer is performed. After the DMA transfer is ended, the on-chip bus clock (HCLK) is stopped again.

■ Effect of Sleep Mode

You can reduce power consumption on the peripheral or external input event wait state drastically by using sleep mode. This mode does not decrease power consumption as much as that of in watch mode or stop mode because the peripheral clock (PCLK) will continue to run. While, a return to the program operation within several clock times is possible by generating a wake up request.

5.4. Standby Mode : Watch Mode

This section explains standby mode: watch mode.

Watch mode is the mode to continue oscillation only for the specific clock and count the clock timer corresponding to that clock. When the sub clock (SBCLK) is selected as the clock source, only the sub clock oscillates and only the sub timer counts.

Note:

Enter the standby mode only when main RUN or sub RUN is in progress. For the operation of transition to standby mode from PLL run, see "5.10 Transition to Illegal Standby Mode".

Note:

Transition to the standby state during FLASH program/erase is prohibited.

■ Configuration of Watch Mode

Before activating watch mode, the power supply of GDC must be shutdown and set the state of external pins in watch mode with the bit1:SLVL1 in the STBCR register.

- When setting bit1:SLVL1="0" in the STBCR register, the external pins hold previous state.
- When setting bit1:SLVL1="1" in the STBCR register, the external pins become high impedance. Pins whose state is controlled differ according to product types. See "APPENDIX".

■ Activation of Watch Mode

To activate watch mode, follow the steps below.

- The bit of the GCTLR register is controlled, and the power supply in the GDC unit is shut-down.
- "0" is written in bit7:SHDE of the PMUCTLR register.
- When performing PLL RUN, CPU must go into main RUN state first. (When performing sub RUN state, it transits directly to watch mode.)
- Write "010" to bit7:STOP, bit6:TIMER, bit5:SLEEP in the STBCR register.
- Read the STBCR register.

In FR81S core, if the read value will not be used in the next instruction, that instruction is executed before the read is completed. Perform dummy processing to use the read value in the next instruction so as not to make the program progress before entering watch mode.

[Example] Sample program of watch mode activation

```
LDI    #value_of_timer, R0    ;TIMER bit="1", SLVL setting
LDI    #_STBCR, R12           ;
STB    R0, @R12              ; Write
LDUB   @R12, R0              ; Read (activation of watch mode)
MOV    R0, R0                 ; Dummy processing for pipeline adjustment
NOP    ; Dummy processing for pipeline adjustment
```

■ Wake Up from the Watch Mode

To stop watch mode, follow the conditions below.

- Reset
- Generation of interrupt request whose value of corresponding ICR register is value other than "0x1F"
(see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)")
- Generation of NMI request
- Generation of tool break while connected to ICE

For wake up from an interrupt request, CPU does not always have to accept this interrupt request. When an interrupt request is not accepted, the program starts from next instruction which activates watch mode.

■ Effect of Watch Mode

You can reduce power consumption on the external input event wait state drastically by using watch mode. This mode does not decrease power consumption as much as that of in stop mode because enabled clock oscillation will continue to run. On the other hand, a clock timer can continue to run and a return to the program operation is possible by generating a wake up request in a short time compared with the return from the stop mode.*

* : When continue to run program with activate clocks.

5.5. Standby Mode : Watch Mode with power-shutdown

This section explains standby mode : watch mode with power-shutdown.

Watch mode with power-shutdown is the mode to continue oscillation only for the specific clock after the microcontroller shuts off the power and count the clock timer corresponding to that clock. When the sub clock (SBCLK) is selected as the clock source, only the sub clock oscillates and only the sub timer counts.

Note:

Enter the standby mode only when main RUN and sub RUN is in progress. For the operation of transition to standby mode from PLL run, see "5.10 Transition to Illegal Standby Mode".

Note:

Transition to the standby state during FLASH program/erase is prohibited.

■ Configuration of Watch Mode with power-shutdown

Before activating watch mode with power-shutdown, set and control the followings.

(1) Power off in GDC block

- See "5.9 Power-shutdown GDC Unit".

(2) Set the state of external pins in watch mode with power-shutdown with the bit1:SLVL1 in the STBCR register.

- When setting bit1:SLVL1="0" in the STBCR register, the external pins hold previous state.
- When setting bit1:SLVL1="1" in the STBCR register, the external pins become high impedance.

Pins whose state is controlled differ according to product types. See "APPENDIX".

■ Activation of Watch Mode with power-shutdown

To activate watch mode with power-shutdown, follow the steps below:

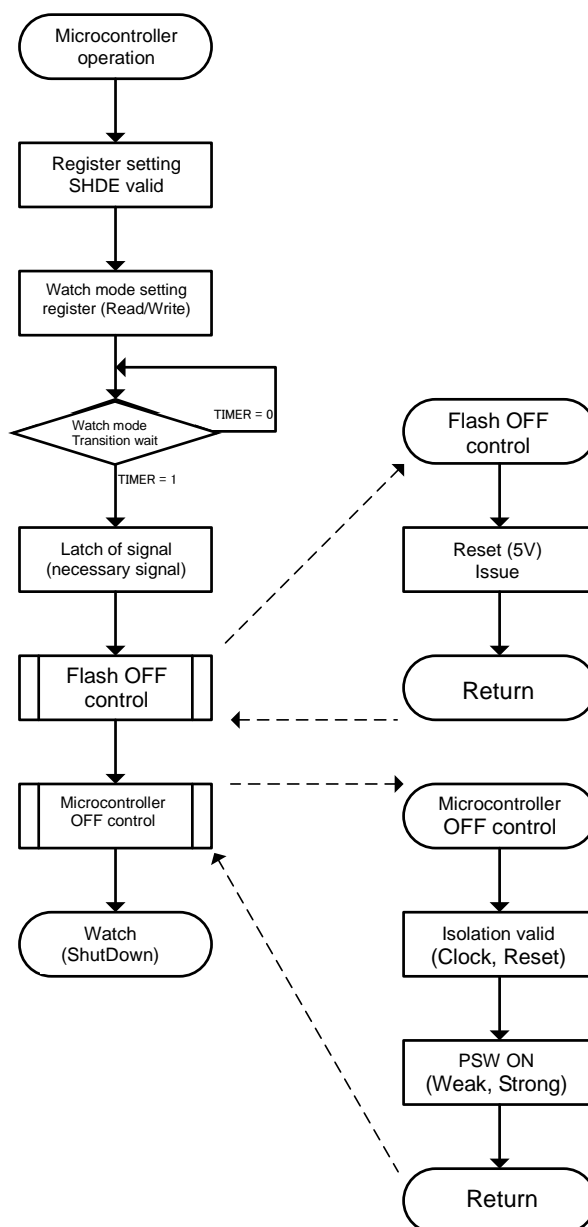
- The bit of the GCTLR register is controlled, and the power supply in the GDC unit is shut-down.
- "1" is written in bit7:SHDE of the PMUCTLR register.
- When performing PLL RUN, CPU must go into main RUN state first. (When performing sub RUN state, it transits directly to watch mode with power-shutdown.)
- Write "010" to bit7:STOP, bit6:TIMER, bit5:SLEEP in the STBCR register.
- Read the STBCR register.

In FR81S core, if the read value will not be used in the next instruction, that instruction is executed before the read is completed. Perform dummy processing to use the read value in the next instruction so as not to make the program progress before entering watch mode with power-shutdown.

[Example] Sample program of watch mode activation (power-shutdown)

```
LDI    #value_of_PMU, R0      ; SHDE bit ="1", IOCTMD/IOCT bit setting
LDI    #_PMUCTLR, R12        ;
STB    R0, @R12              ; Write
LDI    #value_of_timer, R0    ; TIMER bit ="1", SLVL setting
LDI    #_STBCR, R12          ;
STB    R0, @R12              ; Write
LDUB   @R12, R0              ; Read (activation of watch mode with power-shutdown)
MOV    R0, R0                ; Dummy processing for pipeline adjustment
NOP    ; Dummy processing for pipeline adjustment
```

Figure 5-1 Transition Sequence to Watch Mode with power-shutdown



■ Wake Up from the Watch Mode with power-shutdown

To stop watch mode with power-shutdown, follow the conditions below:

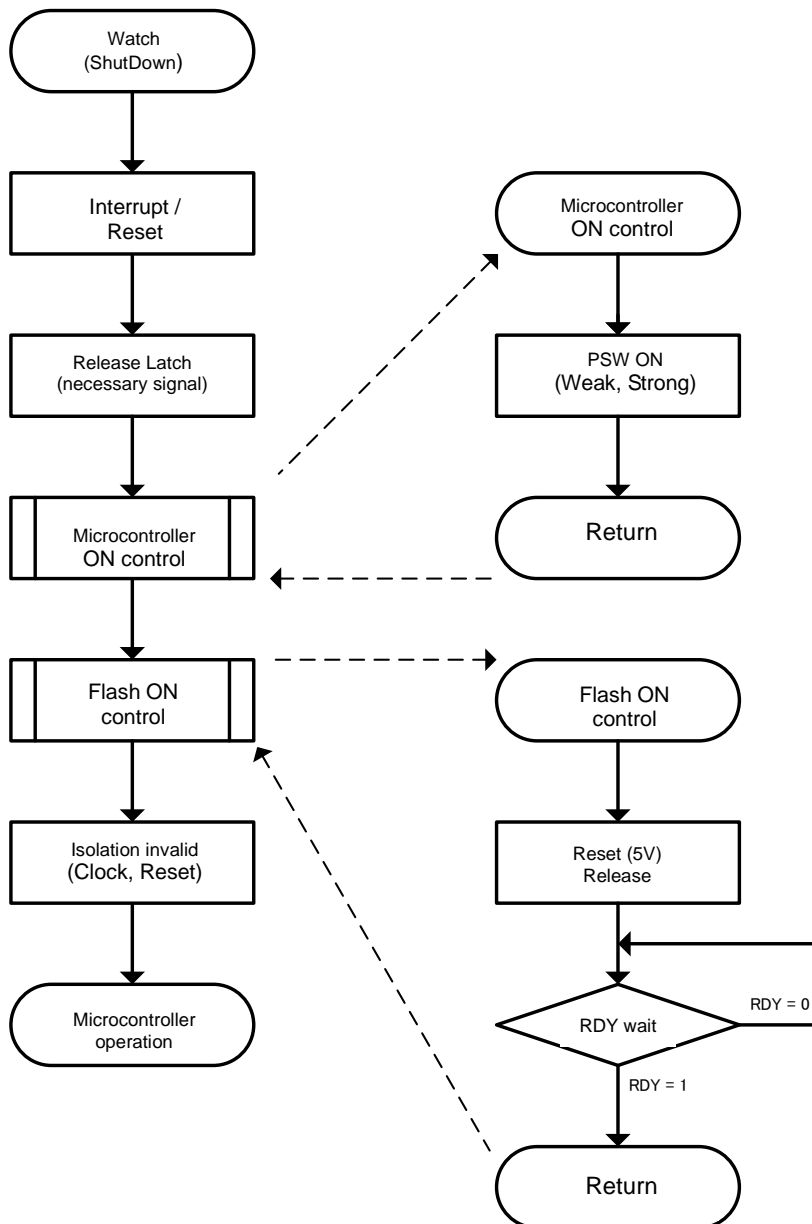
- Reset
- Generation of external interrupt request
- Generation of NMI request
- Generation of RTC interrupt request
- Generation of main/sub timer interrupt request

For wake up by interrupt request, CPU and interrupt controller do not always have to accept this interrupt request. CPU always starts operation from the reset state.

The register of RTC and external interrupt input (IOCTMD=1) is not initialized.

Only the reset factors (power-on reset, internal low-voltage reset, and simultaneous assert of RSTX and NMIX) are accepted during wake-up. At this time, the register of the RTC and external interrupt input (IOCTMD=1) is not initialized. If the reset input from RSTX pin input or the external low-voltage detection flag are set after the start-up, initialize the RTC/external interrupt input register before using.

Figure 5-2 Restore Sequence from Watch Mode with power-shutdown



■ Effect of Watch Mode with power-shutdown

You can reduce wait current for unnecessary circuit greatly by watch mode with power-shutdown. This mode does not decrease power consumption as much as that of in stop mode because enabled clock oscillation will continue to run. On the other hand, a clock timer can continue to run and a return to the program operation without clock oscillation stabilization wait is possible by generating a wake up request.

5.6. Standby Mode : Stop Mode

This section explains standby mode: stop mode.

Stop mode is the mode to stop all clock oscillations and minimize power consumption of this series.

Note:

Enter the standby mode only when main RUN or sub RUN is in progress. For the operation of transition to standby mode from PLL run, see "5.10 Transition to Illegal Standby Mode".

Note:

Transition to the standby state during FLASH program/erase is prohibited.

■ Configuration of Stop Mode

Before activating stop mode, the power supply of GDC must be shut-down and set the state of external pins in stop mode with the bit1:SLVL1 in the STBCR register.

- When setting bit1:SLVL1="0" in the STBCR register, the external pins hold previous state.
 - When setting bit1:SLVL1="1" in the STBCR register, the external pins become high impedance.
- Pins whose state is controlled differ according to product types. See "APPENDIX".

■ Activation of Stop Mode

To activate stop mode, follow the steps below.

- The bit of the GCTLR register is controlled, and the power supply in the GDC unit must be shut-down.
- "0" is written in bit7:SHDE of the PMUCTLR register.
- When performing PLL RUN, CPU must go into main RUN state first. (When performing sub RUN state, it transits directly to stop mode.)
- Write "100" to bit7:STOP, bit6:TIMER, bit5:SLEEP in the STBCR register.
- Read the STBCR register.

In FR81S core, if the read value will not be used in the next instruction, that instruction is executed before the read is completed. Perform dummy processing to use the read value in the next instruction so as not to make the program progress before entering stop mode.

[Example] Sample program of stop mode activation

```
LDI    #value_of_stop, R0    ; STOP bit ="1", SLVL setting
LDI    #_STBCR, R12         ;
STB    R0, @R12             ; Write
LDUB   @R12, R0             ; Read (activation of stop mode)
MOV    R0, R0               ; Dummy processing for pipeline adjustment
NOP    ; Dummy processing for pipeline adjustment
```

■ Wake Up from the Stop Mode

To stop stop mode, follow the conditions below:

- Reset
- Generation of interrupt request whose value of corresponding ICR register is value other than "0x1F"
(see "CHAPTER: INTERRUPT CONTROL (INTERRUPT CONTROLLER)")
- Generation of NMI request
- Generation of tool break while connected to ICE

For wake up from interrupt request, CPU does not always have to accept this interrupt request. When an interrupt request is not accepted, the program starts from the next instruction which activates stop mode.

■ Effect of Stop Mode

You can minimize power consumption on the external input event wait state by using stop mode. While, a return to the program operation after generating a wake up request needs the oscillation stabilization wait time.

5.7. Standby Mode : Stop Mode with power-shutdown

This section explains standby mode : stop mode with power-shutdown.

Stop mode with power-shutdown is the mode to stop all clock oscillations and minimize power consumption of this series.

Note:

Enter the standby mode only when main RUN or sub RUN is in progress. For the operation of transition to standby mode from PLL run, see "5.10 Transition to Illegal Standby Mode".

Note:

Transition to the standby state during FLASH program/erase is prohibited.

■ Configuration of Stop Mode with power-shutdown

Before activating stop mode with power-shutdown, set and control the followings.

- (1) Power off in GDC block.
 - See "5.9 Power off GDC Block".
- (2) Set the state of external pins in stop mode with power-shutdown with the bit1:SLVL1 in the STBCR register.
 - When setting bit1:SLVL1= 0 in the STBCR register, the external pins hold previous state.
 - When setting bit1:SLVL1= 1 in the STBCR register, the external pins become high impedance.Pins whose state is controlled differ according to product types. See "APPENDIX".

■ Activation of Stop Mode with power-shutdown

To activate stop mode with power-shutdown, follow the steps below:

- The bit of the GCTLR register is controlled, and the power supply in the GDC unit must be shut-down.
- "1" is written in bit7:SHDE of the PMUCTLR register.
- When performing PLL RUN, CPU must go into main RUN state first. (When performing sub RUN state, it transits directly to stop mode with power-shutdown.)
- Write "100" to bit7:STOP, bit6:TIMER, bit5:SLEEP in the STBCR register.
- Read the STBCR register.

In FR81S core, if the read value will not be used in the next instruction, that instruction is executed before the read is completed. Perform dummy processing to use the read value in the next instruction so as not to make the program progress before entering stop mode with power-shutdown.

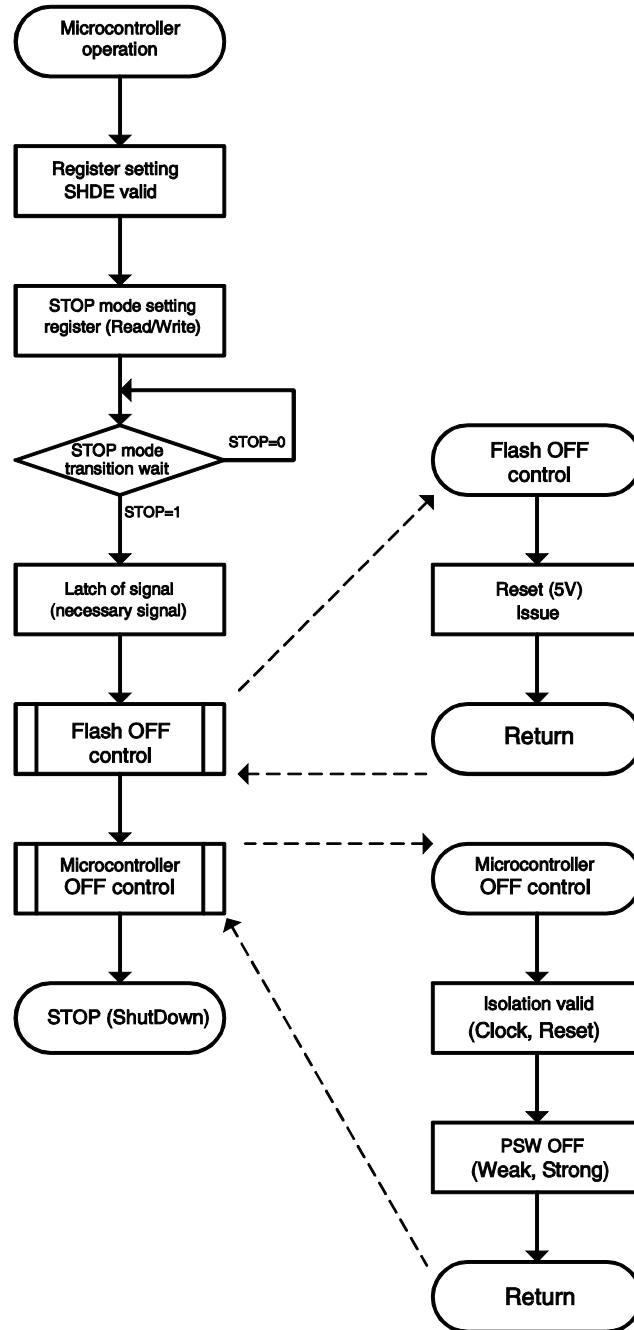
[Example] Sample program of stop mode with power-shutdown activation

```
LDI    #value_of_PMU, R0      ; SHDE bit = "1", IOCTMD/IOCT bit setting
LDI    #_PMUCTLR, R12        ;
STB    R0, @R12              ; Write
LDI    #value_of_stop, R0    ; STOP bit = "1", SLVL setting
LDI    #_STBCR, R12         ;
STB    R0, @R12              ; Write
LDUB   @R12, R0              ; Read (activation of stop mode with power-shutdown)
MOV    R0, R0                 ; Dummy processing for pipeline adjustment
NOP                                     ; Dummy processing for pipeline adjustment
```

Note:

Make sure that the supply voltage for 1.2V power supply is not over that of 3.3V power supply at power off.

Figure 5-3 Transition Sequence to Stop Mode with power-shutdown



■ **Wake Up from the Stop Mode with power-shutdown**

To stop the stop mode with power-shutdown, follow the conditions below :

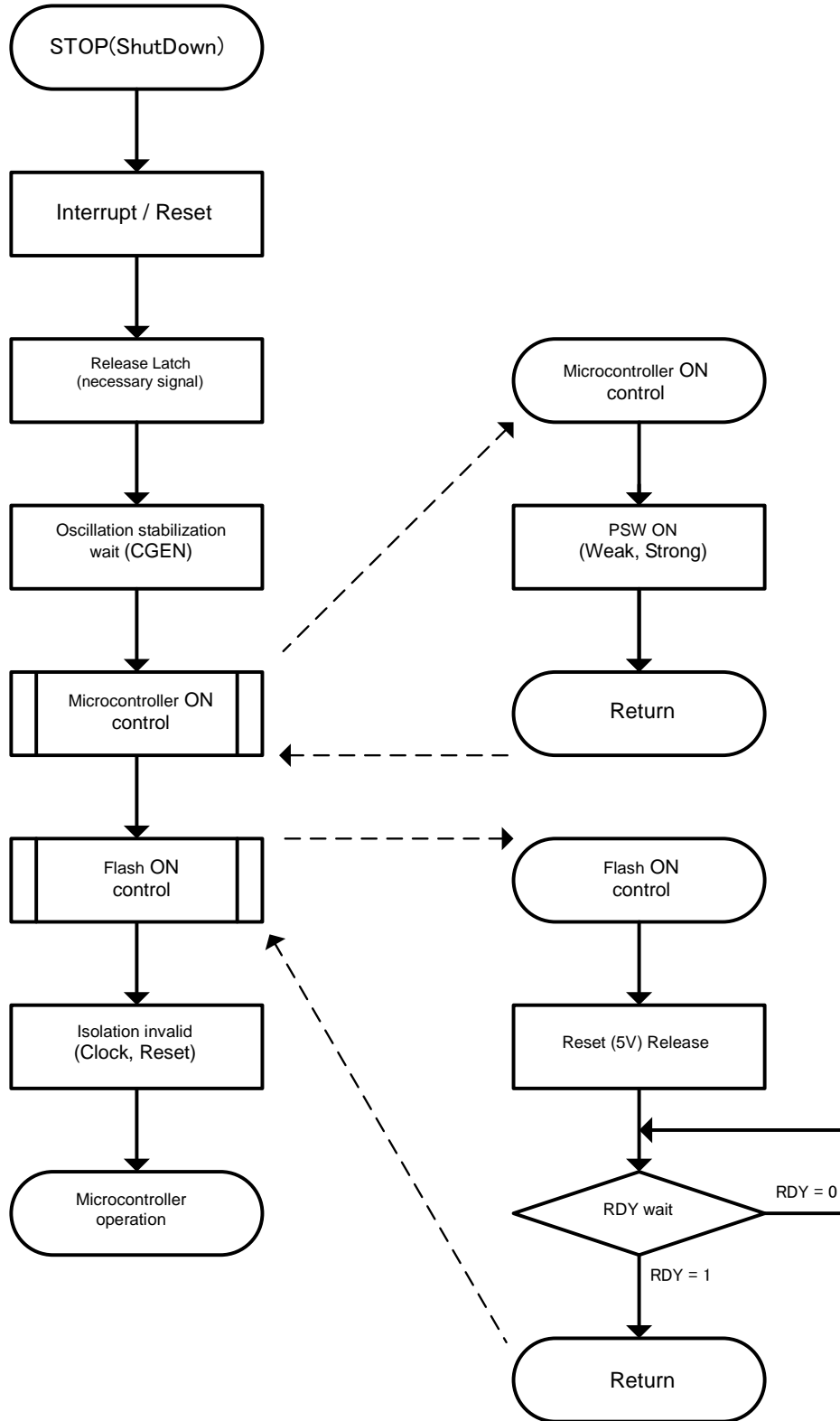
- Reset
- Generation of external interrupt request
- Generation of NMI request

For wake up by an interrupt request, CPU and the interrupt controller do not always have to accept this interrupt request. CPU always starts operation from the reset state.

The register of the external interrupt input (IOCTMD=1) is not initialized.

Only the reset factors (power-on reset, internal low-voltage reset and simultaneous assert of RSTX and NMIX) are accepted during wake-up. At this time, the register of the external interrupt input (IOCTMD=1) is not initialized. If the reset input from RSTX pin input or the external low-voltage detection flag are set after the start-up, initialize the register before using.

Figure 5-4 Return Sequence from Stop Mode with power-shutdown



■ **Effect of Stop Mode with power-shutdown**

You can minimize wait current for unnecessary circuit by stop mode with power-shutdown. While, a return to the program operation after generating a wake up request needs the oscillation stabilization wait time.

5.8. Stop State of Microcontroller

The stop state of microcontroller is shown below.

When the transition from the state of the standby mode (watch mode/watch mode with power-shutdown/stop mode/stop mode with power-shutdown) transition prohibition to the standby is controlled, the standby transition is not concluded.

< State of standby transition prohibition >

1. Operating GDC(GDC power ON)
2. Connecting OCD
3. Operating PLL

<Standby control not done by microcontroller stop condition>

1. Flash memory power saving control
2. Oscillation stop (At the stop mode stop mode with power-shutdown)

However, the oscillation stop operation is done detecting the illegal standby mode transition when the standby mode transition control is done while PLL is operating. See "5.10. Transition to Illegal Standby Mode" for the illegal standby mode transition.

5.9. Power-shutdown GDC Unit

This section explains power off GDC unit.

Power off in GDC is needed to save power consumption of this series or as prior step to transit to watch mode with power-shutdown / stop mode with power-shutdown. Power off is controlled by register. To transit/return to and from power-shutdown, follow the flow below.

■ Power on in GDC

If a register is configured (regulator PD disabled) under operation of MCU and power supply in GDC (3.3V) is provided, the regulator starts to operate in GDC. After that, configure a register (power supply surveillance Isolator disabled) and disable Isolator (power supply surveillance). The value of the source register is polled. When the regulator is stabilized, the value of the source register changes to "1". (RDY signal of the regulator is surveilled.) After the source register changes and register is configured (normal Isolator disabled), isolator goes to disable, GDC moves to the ready state.

■ Power off in GDC

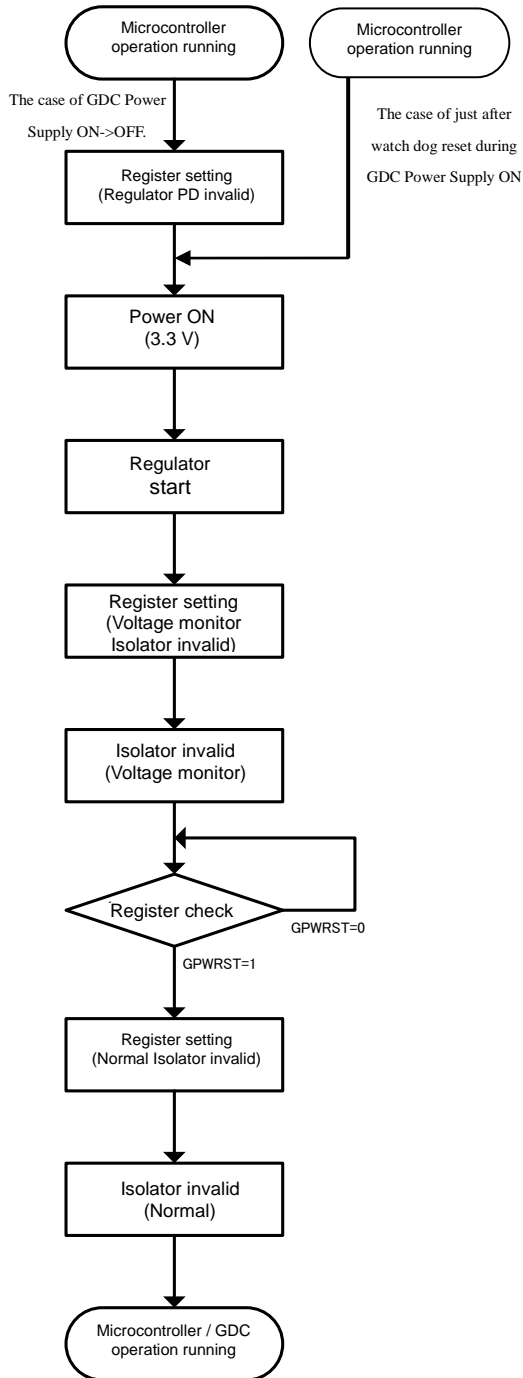
If a register (power supply surveillance normally) is configured (Isolator enabled) under operation of GDC and MCU, Isolator (power supply surveillance normally) is enabled. There is no problem in configuring either first. If a register is configured (regulator PD enabled) after the setting, the regulator is powered down and internal power supply is turned off. After that, turn off power supply in GDC (3.3V).

Note:

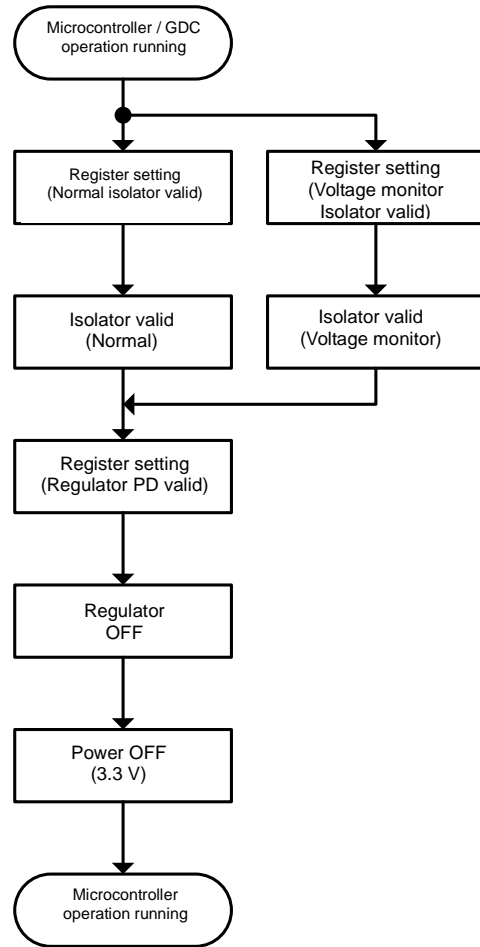
After the regulator is powered down, restarting the regulator without turning off 3.3V power supply is prohibited.

Figure 5-5 Power Supply Control in GDC

1. GDC Side Power Supply ON



2. GDC Side Power Supply OFF



5.10. Transition to Illegal Standby Mode

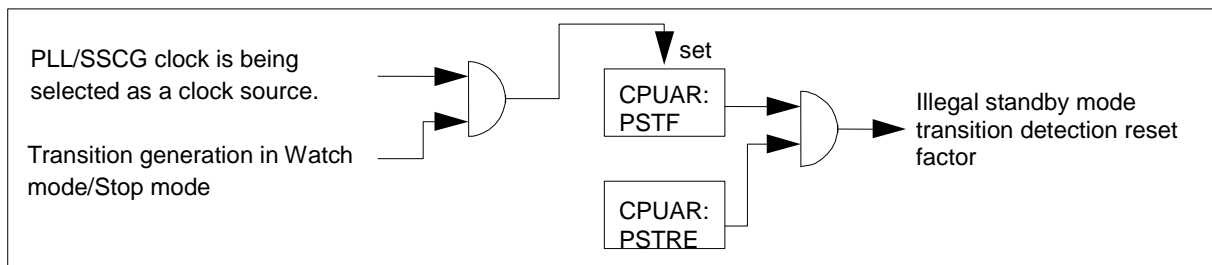
Transition to illegal standby mode is shown below.

If transit from the PLL run state to standby mode (watch mode/watch mode (power-shutdown)/stop mode/stop mode (power-shutdown)) is executed, standby mode is set and PLL oscillation stabilization is canceled. (Transition to illegal standby mode)

After returning from standby mode, CSELR:CKS[1:0]=00 and CMONR:CKM[1:0]=00 (divide-by-two of clock).

The PSTF flag of the CPUAR register is set concurrently with transition to the standby mode. When the PSTRE bit in the CPUAR register is set, reset occurs by illegal standby mode transition detection reset source. For the CPUAR register, see "4.3. CPU Abnormal Operation Register : CPUAR (CPU Abnormal operation Register) " in "CHAPTER: RESET".

Figure 5-6 Generation Diagram of Illegal Standby Mode Transition Detection Reset Source



Note:

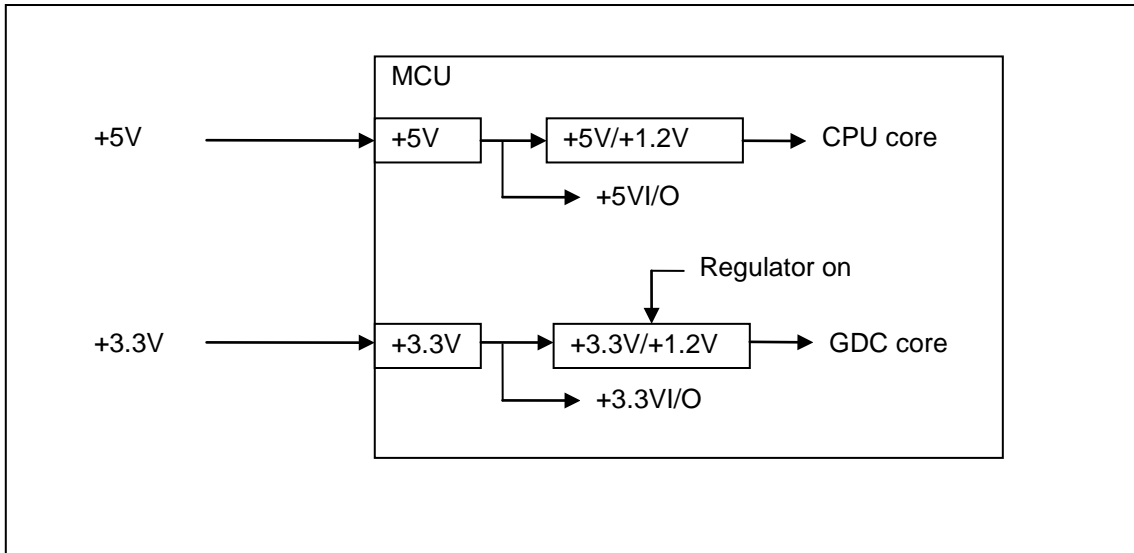
When high-speed UART mode and phase modulation UART mode are selected during connected to OCD tool, the illegal standby mode transition detection reset does not occur.

5.11. GDC Regulator

The GDC regulator is shown below.

The GDC a regulator is dedicated to a regulator in GDC and can be controlled independently from a regulator in MCU. See "4.8. GDC Control Register : GCTLR (Gdc ConTroL Register)" for the control of the GDC regulator.

Figure 5-7 Power Supply



5.12. Restrictions on Power Shutdown and Normal Standby Control

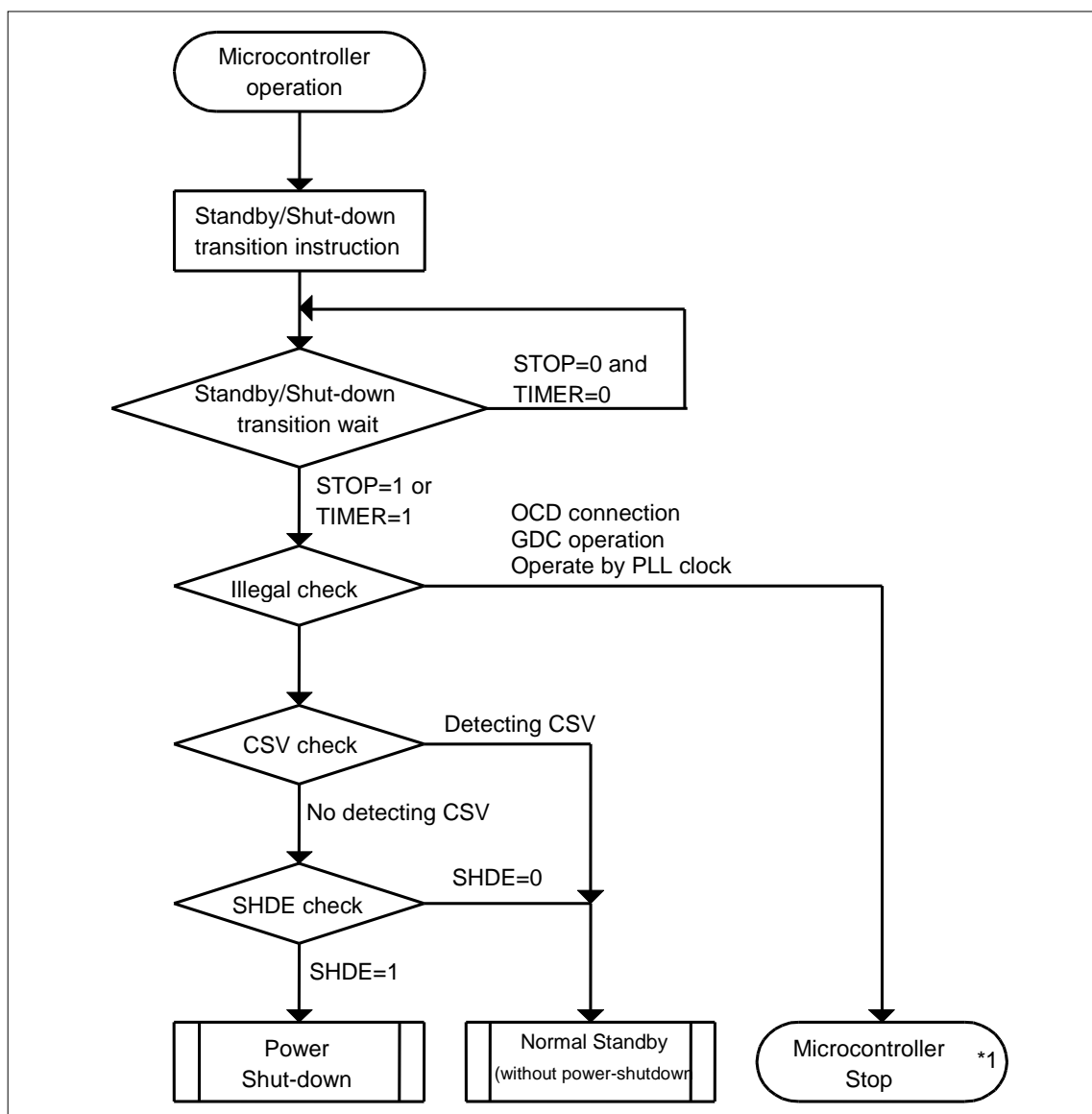
Restrictions on shutdown and normal standby control are explained below.

This microcontroller does not perform standby control on the following conditions.

- When CPU operate with PLL
- When enabling GDC operation
- When enabling OCD operation
- When missing the clock by CSV function *2, *3

The standby control does not operate in the states above, but CPU is in the standby state.

Figure 5-8 Restriction on Power Shutdown and Normal Standby Control



*1: This state is not recognized as power shutdown and the state that CPU transits to standby mode.

- *2: It is the case when stop of operationg clock source are detected by CSV circuit. For instance, in the case that cpu operate with the CR clock after main clock stop are detected, cpu does not perform standby control. However, it is not the limitation case, when stop detection of sub-clock is done while cpu run with the main clock.
- *3: When standby (power-shutdown) transition is directed after the operating clock source is missing, it usually becomes standby processing. Moreover, it is necessary to note it because the function of CSV stops when the power-shutdown permission is enabled with the operating clock source is not missing.

Only a part of registers is maintained at returning, because the power supply is not supplied to almost all blocks inside in standby mode with power-shutdown Table 5-2 shows the list of registers that are stored at return from standby mode with power-shutdown).

Table 5-2 List of Registers that are stored at Return from Standby Mode with Power-shutdown

Register group	Register, flag name	Type	Address	Remarks
PMU register	PMUSTR.PMUST	Flag	0590 _H bit7	
	PMUSTR.PONR_F	Flag	0590 _H bit1	
	PMUSTR.RSTX_F	Flag	0590 _H bit0	
	PMUCTLR	Register	0591 _H	
	PWRTMCTL	Register	0592 _H	
	PMUINTF0	Flag	0594 _H	
	PMUINTF1	Flag	0595 _H	
GDC status/control register	PMUINTF2	Flag	0596 _H	
	GSTR	Register	0598 _H	
Reset source register	GCTLR	Register	0599 _H	
	CPUAR.PMDF	Flag	051A _H bit2	
	CPUAR.PSTF	Flag	051A _H bit1	
	CPUAR.HWDF	Flag	051A _H bit0	
	LVD5R.LVD5R_F	Flag	0584 _H bit0	
	LVD5F.LVD5F_F	Flag	0585 _H bit0	
Low-voltage detection setting register	LVD.LVD_F	Flag	0586 _H bit0	
	LVD5F.LVD5F_PD	Register	0585 _H bit7	
	LVD5F.LVD5F_OE	Register	0585 _H bit3	
	LVD.LVD_PD	Register	0586 _H bit7	
GDC low-voltage detection register	LVD.LVD_OE	Register	0586 _H bit3	
	GLVD5R.LVD5R_F	Flag	0588 _H bit0	
	GLVD5F.LVD5F_F	Flag	0589 _H bit0	
CSV register	GLVD.LVD_F	Flag	058A _H bit0	
	CSVCR	Register	056D _H	
External interrupt register	EIRR0/1	Register	0550 _H /0554 _H	*3
	ENIR0/1	Register	0551 _H /0555 _H	*3
	ELVR0/1	Register	0552 _H /0556 _H	*3
RTC register	WTDR	Register	055E _H -055F _H	
	WTCR	Register	0561 _H -0563 _H	*1
	WTBR	Register	0565 _H -0567 _H	*1
	WTHR	Register	0568 _H	
	WTMR	Register	0569 _H	
	WTSR	Register	056A _H	
Clock selection register	CSELR.SCEN	Register	0510 _H bit7	*1,*2
	CMONR.SCRDY	Flag	0511 _H bit7	*1,*2
	CCRTSELR.CST	Flag	0530 _H bit7	*1,*2
	CCRTSELR.CSC	Register	0530 _H bit0	*1,*2

*1: These registers are initialized at return from stop mode with power-shutdown.

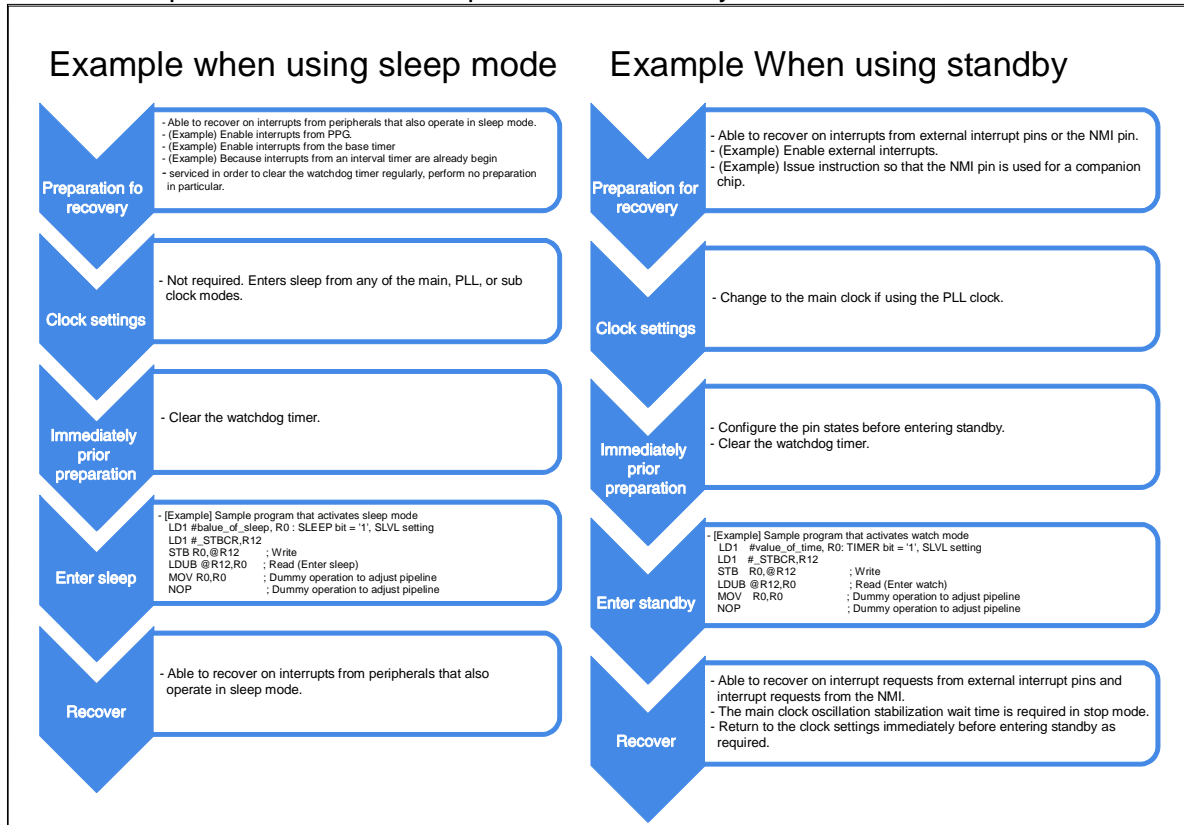
*2: These registers are for the dual clock products.

*3: It is initialized at PMUCTLR:IOCTMD=0.

6. Example of Use

The example of activation of sleep mode and standby mode is shown below.

Figure 6-1 Example of activation of sleep mode and standby mode



CHAPTER : LOW VOLTAGE DETECTION (INTERNAL LOW-VOLTAGE DETECTION)

This chapter explains the low voltage detection (internal low-voltage detection).

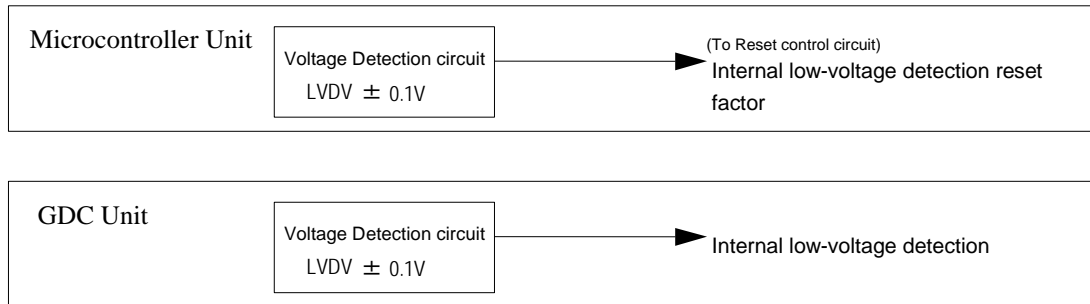
1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Notes

1. Overview

This section explains the overview of the low voltage detection (internal low-voltage detection).

The internal low voltage detection is a function that monitors the internal voltage and detects when the internal voltage falls below the detection voltage value. It sets the detection flag if low voltage is detected. Internal low voltage detection includes a microcontroller unit internal low voltage detection and a GDC unit internal low voltage detection. When a microcontroller unit internal low voltage detection sets the detection flag, it is in the reset state by low-voltage detection reset.

Figure 1-1 Block Diagram of Low Voltage Detection (Internal Low-voltage Detection)
(Overview)



2. Features

This section explains the features of the low voltage detection (internal low-voltage detection).

Microcontroller unit internal low voltage detection circuit

- Method : Generates a settings initialization reset if a voltage lower than $LVDV \pm 0.1V$ is detected. (LVDV : 0.9 V)
- Number of units : 1
- Operation : Continues to operate in sleep mode, stop mode, and watch mode.
- Voltage comparison circuit: Compares the microcontroller unit internal voltage to the detection voltage, and changes output from "H" to "L" if low voltage is detected.
Operates constantly after the power is turned on.

GDC unit internal low voltage detection circuit

- Method : Voltage lower than $LVDV \pm 0.1V$ is detected.
(LVDV : 0.9 V)
- Number of units : 1
- Operation : Operation/stop is switched by the user setting.
- Voltage comparison circuit: Compares the GDC unit internal voltage to the detection voltage, and changes output from "H" to "L" if low voltage is detected.

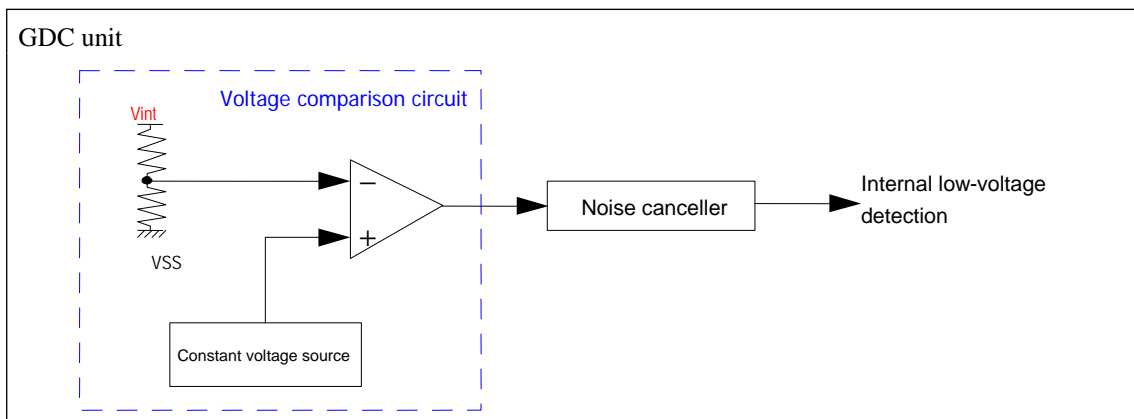
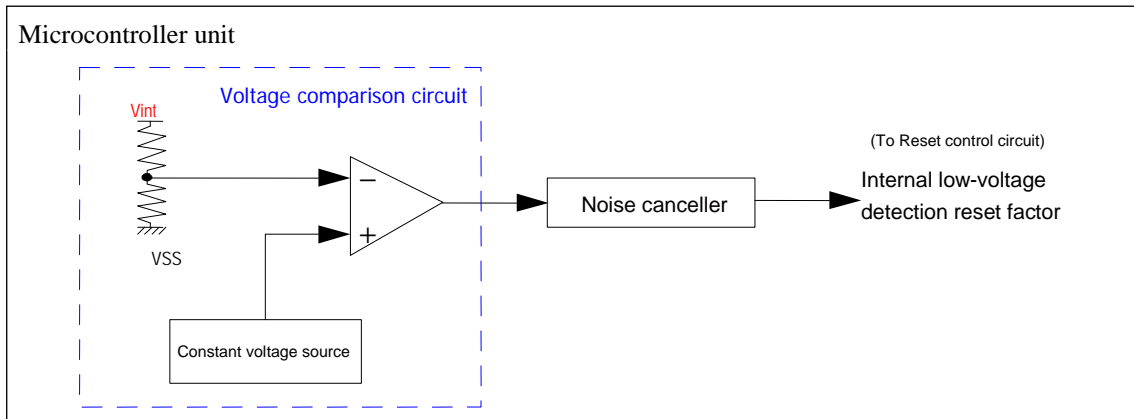
3. Configuration

This section shows the configuration of the low voltage detection (internal low-voltage detection).

■ Configuration Diagram of low voltage detection (internal low-voltage detection)

Figure 3-1 shows Configuration diagram.

Figure 3-1 Configuration diagram



4. Registers

This section explains the registers of the low voltage detection (internal low-voltage detection).

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0584	LVD5R	LVD5F	LVD	Reserved	Microcontroller unit internal low-voltage detection register
0x0588	GLVD5R	GLVD5F	GLVD	Reserved	GDC unit internal low-voltage detection register

4.1. Microcontroller Unit Internal Low Voltage Detection Register : LVD (Low Voltage Detect internal power fall register)

The bit configuration of the microcontroller unit internal low voltage detection register is explained.

This register has the microcontroller unit internal low voltage detection flag (LVD_F).

■ LVD : Address 0586_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	LVD_PD	LVD_SEL[2:0]			LVD_OE	Reserved		LVD_F
Initial value	0	1	0	0	0	0	0	0
Attribute	R/W	R/W1	R/W0	R/W0	R/W	R0,WX	R0,WX	R(RM1), W

[bit7] LVD_PD (Low Voltage Detect fall Power Down)

This bit is used to set whether to detect a fall in internal voltage of the microcontroller unit or not.

LVD_PD	Internal voltage fall power down setting in microcontroller unit
0	Disabled (Detection is executed.)
1	Enabled (Detection is stopped.)

This bit is initialized by only power-on reset.

Note:

Set detection enable (OE = 0) after 100 μs, if this bit sets the status of power-down enable to disable (operation start). If set it before 100 μs, some detection flag setting will be occur.

[bit6 to bit4] LVD_SEL [2:0] (Low Voltage Detect internal power fall SElect)

These bits are a selection signal of detection level of the internal voltage fall detection in microcontroller unit.

LVD_SEL[2:0]	Internal fall detection voltage setting in microcontroller unit
100	0.9V ± 0.1V
Other than the above	Setting is prohibited

*These bits can be rewritten only when LVD_OE="1".

[bit3] LVD_OE (Low Voltage Detect internal power fall Output Enable)

This bit is an output enable signal of the internal voltage fall detection in microcontroller unit.

LVD_OE	Internal voltage fall detection output enable setting in microcontroller unit
0	Enable
1	Disable

This bit is initialized by only power-on reset.

[bit2, bit1] Reserved

[bit0] LVD_F (Low Voltage Detect internal power fall Flag) : Microcontroller unit internal low voltage detection flag

This is an internal voltage fall detection flag in microcontroller unit.

LVD_F	Internal voltage fall detection flag in microcontroller unit	
	Read	Write
0	Not detected	Clear the flag
1	Detected	No effect on operation

If a power-on reset or a drop in the internal voltage in microcontroller unit is detected, the LVD_F bit is set to "1".

It will be initialized only at the external reset input.

4.2. GDC Unit Internal Low Voltage Detection Register : GLVD (Gdc Low Voltage Detect internal power fall register)

The bit configuration of the GDC unit internal low voltage detection register is explained.

This register has GDC unit internal low voltage detection flag (GLVD_F).

■ GLVD : Address 058A_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GLVD_PD	GLVD_SEL[2:0]			GLVD_OE	GLVD_IE	Reserved	GLVD_F
Initial value	0	1	0	0	0	0	0	X
Attribute	R/W	R/W1	R/W0	R/W0	R/W	R/W	R0,WX	R(RM1), W

[bit7] GLVD_PD (Gdc Low Voltage Detect fall Power Down)

This bit is used to set whether to detect a fall in internal voltage of the GDC unit or not.

GLVD_PD	Internal voltage fall power down setting in GDC unit
0	Disabled (Detection is executed.)
1	Enabled (Detection is stopped.)

Note:

Set detection enable (OE = 0) after 100 μ s, if this bit sets the status of power-down enable to disable (operation start). If set it before 100 μ s, some detection flag setting will be occur.

[bit6 to bit4] GLVD_SEL [2:0] (Gdc Low Voltage Detect internal power fall SElect)

These bits are selection signals of detection level of the GDC unit internal voltage fall detection.

GLVD_SEL[2:0]	Internal fall detection voltage setting in GDC unit
100	0.9V \pm 0.1V
Other than the above	Setting is prohibited

* These bits can be rewritten only when GLVD_OE="1".

[bit3] GLVD_OE (Gdc Low Voltage Detect internal power fall Output Enable)

This bit is an output enable signal of the GDC unit internal voltage fall detection.

GLVD_OE	Internal voltage fall detection output enable setting in GDC unit
0	Enable
1	Disable

[bit2] GLVD_IE (Gdc Low Voltage Detect Fall Interrupt Enable)

This bit shows the interrupt enable signal of the internal voltage fall detection for the GDC unit.

GLVD_IE	GDC unit internal voltage fall interrupt enable signal
0	Interrupt disable
1	Interrupt enable

[bit1] Reserved

[bit0] GLVD_F (Gdc Low Voltage Detect internal power fall Flag) : GDC unit Internal low voltage detection flag

This is the GDC unit internal voltage fall detection flag.

GLVD_F	Internal voltage fall detection flag in GDC unit	
	Read	Write
0	Not detected	Clear the flag
1	Detected	No effect on operation

If a power-on reset or a drop in the GDC unit internal voltage is detected, the GLVD_F bit is set to "1".

It will be initialized only at the external reset input

An initial value is undefined. Use it after it writes after the power supply of GDC is confirmed and it clears.

5. Operation

This section explains the operations of the low voltage detection (internal low-voltage detection).

- 5.1. Internal Low-voltage Detection in Microcontroller Unit
- 5.2. Internal Low-voltage Detection in GDC unit

5.1. Internal Low-voltage Detection in Microcontroller Unit

The internal low-voltage detection in microcontroller unit is explained.

The internal low-voltage detection in microcontroller unit monitors the internal voltage in microcontroller unit and detects when the internal voltage in microcontroller unit falls below the detection voltage value and sets the detection flag. It generates settings initialization reset if it detects low voltage and sets the flag.

If the internal voltage in microcontroller unit falls below the detection voltage, it takes the oscillation stabilization wait time after the internal low-voltage detection voltage in microcontroller unit recovered. For details, see "CHAPTER: RESET".

Oscillation stabilization wait time	$2^{15} \times$ Main clock cycle
-------------------------------------	----------------------------------

5.2. Internal Low-voltage Detection in GDC unit

The internal low-voltage detection in GDC unit is explained.

Internal low voltage detection in GDC unit monitors the internal voltage in GDC unit and detects when the internal voltage in GDC unit falls below the detection voltage value and sets the detection flag.

6. Notes

This section explains the notes on the low voltage detection (internal low-voltage detection).

- **Operation of internal low voltage detection in microcontroller unit**

If the internal voltage in microcontroller unit falls and the microcontroller unit internal low-voltage detection flag is set (LVD:LVD_F="1"), internal reset is generated by the low-voltage detection reset function. Thus, writing and reading of the microcontroller unit internal low voltage detection register (LVD) is not allowed.

The internal low-voltage detection circuit in a microcontroller unit can operate even though the microcontroller is in its sleep mode, stop mode, and watch mode, consuming a certain amount of current.

Internal low voltage detection circuit in microcontroller unit can be operate/stopped by the user setting.

- **Operation of internal low voltage detection in GDC unit**

Internal low voltage detection circuit in GDC unit can be operate/stopped by the user setting.

- **Initial value of internal low voltage detection flag (LVD:LVD_F and GLVD:GLVD_F)**

The internal low voltage detection flag is set to "1" immediately after power-on. The internal low voltage detection flag is cleared by external reset or by writing "0" to the LVD_F and GLVD_F bits of the internal low voltage detection register (LVD and GLVD).

- **Oscillation stabilization wait time**

If the internal voltage in microcontroller unit falls below the detection voltage, it takes the oscillation stabilization wait time after the microcontroller unit internal voltage recovered. For details, see "CHAPTER: RESET".

- **Hysteresis of detection/release**

The release voltage becomes set value +0.05V so that detection/release may have the hysteresis of 0.05V. For example, when LVD:1.0V ± 0.1V is set, the release voltage becomes 1.05V ± 0.1V.

CHAPTER : LOW VOLTAGE DETECTION (EXTERNAL LOW-VOLTAGE DETECTION)

This chapter explains the low voltage detection (external low-voltage detection).

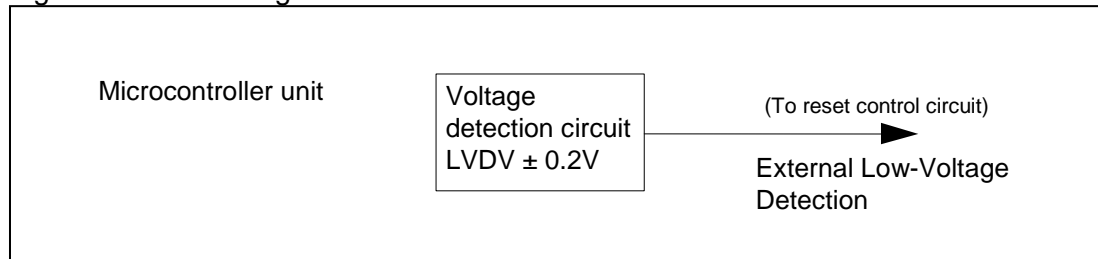
1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Notes

1. Overview

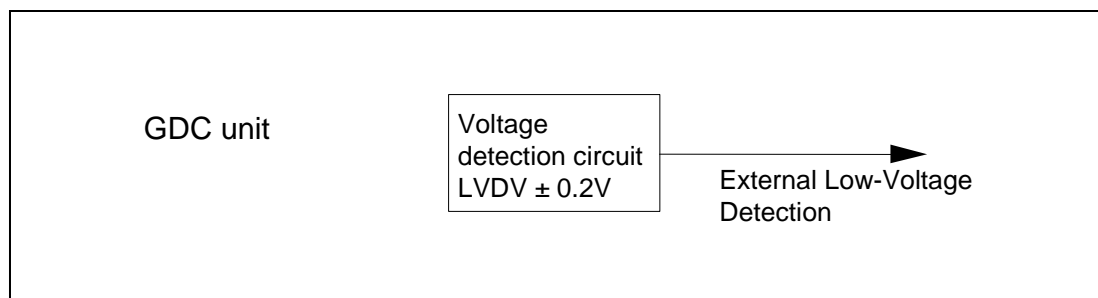
This section explains the overview of the low voltage detection (external low-voltage detection).

The external low voltage detection is a function that monitors the external voltage and detects when the voltage falls below the detection voltage value. There are two types of external low voltage detection: microcontroller unit external low voltage detection and GDC unit external low voltage detection.

Figure 1-1 Block Diagram



(Note) Rising LVDV: 2.3V
Falling LVDV: 3.7 to 4.3V (variable in units of 0.2V)



(Note) Rising LVDV: 2.3V, 2.5V, 2.7V, 2.8V (variable)
Falling LVDV: 2.2V, 2.4V, 2.6V, 2.7V (variable)

2. Features

This section explains the features of the low voltage detection (external low-voltage detection).

- **Microcontroller unit external low voltage detection circuit**

- Method : Generates a settings initialization reset if a voltage lower than $LVDV \pm 0.2V$ is detected. (Rising LVDV: 2.3V (fixed), falling LVDV: 3.7 to 4.3V (variable in units of 0.2V))
- Number of units : One
- Operation : Switches operation/stop by user setting.
During writes to the internal RAM, the low voltage reset occurs after the write has finished.
- Voltage comparison circuit : Compares the microcontroller unit external voltage to the detection voltage, and outputs "L" if low voltage is detected.

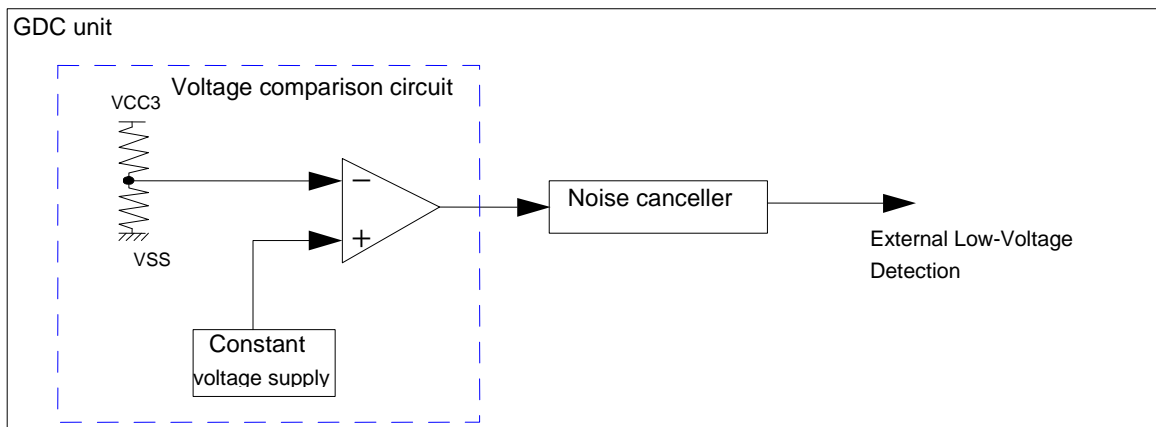
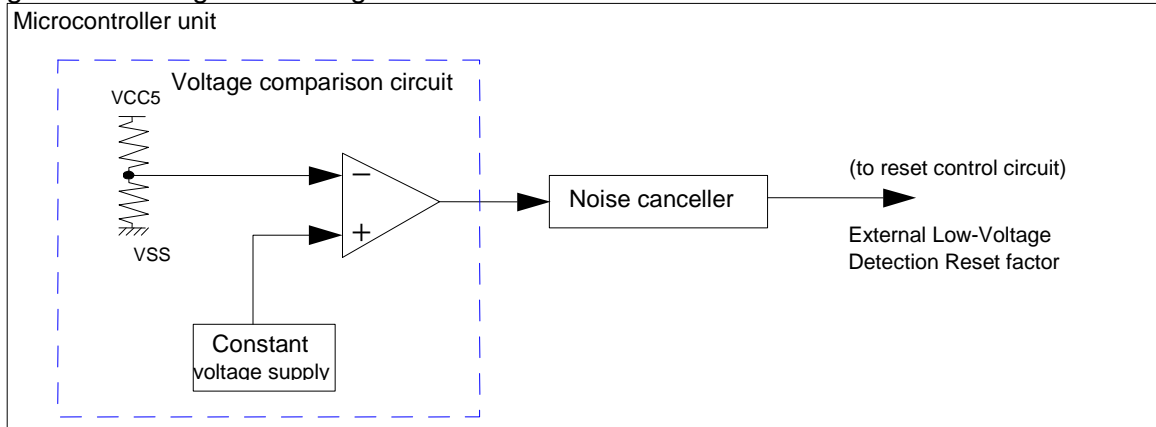
- **GDC unit external low voltage detection circuit**

- Method: Generates a settings initialization reset if a voltage lower than $LVDV \pm 0.2V$ is detected. (Rising LVDV: 2.3V, 2.5V, 2.7V, 2.8V (variable)
falling LVDV: 2.2V, 2.4V, 2.6V, 2.7V (variable))
- Number of units: One
- Operation: Switches operation/stop by user setting.
- Voltage comparison circuit: Compares the GDC unit external voltage to the detection voltage, and outputs "L" if low voltage is detected.

3. Configuration

This section explains the configuration of the low voltage detection (external low-voltage detection).

Figure 3-1 Configuration Diagram



4. Registers

This section explains the registers of the low voltage detection (external low-voltage detection).

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0584	LVD5R	LVD5F	LVD	Reserved	Microcontroller unit external low voltage detection rise detection register Microcontroller unit external low voltage detection fall detection register
0x0588	GLVD5R	GLVD5F	GLVD	Reserved	GDC unit external low voltage detection rise detection register GDC unit external low voltage detection fall detection register

4.1. Microcontroller Unit External Low Voltage Detection Rise Detection Register : LVD5R (Low Voltage Detect external 5v Rise register)

The bit configuration of the microcontroller unit external low voltage detection rise detection register (LVD5R) is explained.

This register is used to clear the low voltage detection reset flag, etc.

■ LVD5R : Address 0584_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							LVD5R_F
Initial value	0	0	0	0	0	0	0	1
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R(RM1), W

[bit7 to bit1] Reserved

[bit0] LVD5R_F (Low Voltage Detect external 5v Rise Flag): Microcontroller unit external voltage rise detection flag

This is an external voltage rise detection flag for the microcontroller unit.

LVD5R_F	Microcontroller unit external voltage rise detection flag	
	Read	Write
0	Not detected	Clear the flag
1	Detected	No effect on operation

If a rise in external voltage of the microcontroller unit is detected, the LVD5R_F bit is set to "1".

It is cleared when external reset is input.

4.2. Microcontroller Unit External Low Voltage Detection Fall Detection Register : LVD5F (Low Voltage Detect external 5v Fall register)

The bit configuration of the microcontroller unit external low voltage detection fall detection register (LVD5F) is explained.

This register is used to clear the low voltage detection reset flag, etc.

■ LVD5F : Address 0585_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	LVD5F_PD	Reserved	LVD5F_SEL[1:0]	LVD5F_OE	Reserved	Reserved	Reserved	LVD5F_F
Initial value	0	0	1	0	0	0	0	1
Attribute	R/W	R0,WX	R/W	R/W	R/W	R0,WX	R0,WX	R(RM1), W

[bit7] LVD5F_PD (Low Voltage Detect external 5v Fall Power Down): Microcontroller unit external voltage fall power down setting

This bit is used to set whether to detect a fall in external voltage of the microcontroller unit or not.

LVD5F_PD	Microcontroller unit external voltage fall power down setting
0	Disable (Performs detection)
1	Enable (Stops detection)

* This bit is initialized by only power-on reset.

Note:

Set detection enable (OE = 0) after 100 μ s, if this bit sets the status of power-down enable to disable (operation start). If set it before 100 μ s, some detection flag setting will be occur.

[bit6] Reserved

[bit5, bit4] LVD5F_SEL[1:0] (Low Voltage Detect 5v Fall SElect): Microcontroller unit external fall detection voltage setting

These bits are the selection signal for a detection level of external voltage fall detection for the microcontroller unit.

LVD5F_SEL[1:0]	Microcontroller unit external fall detection voltage setting
00	3.7V ± 0.2V
01	3.9V ± 0.2V
10	4.1V ± 0.2V
11	4.3V ± 0.2V

* LVD5F_SEL[1:0] bits can be rewritten only when LVD5F_OE = "1".

[bit3] LVD5F_OE (Low Voltage Detect external 5v Fall Output Enable): Microcontroller unit external voltage fall detection output enable setting

This bit is the output enable signal for external voltage fall detection for the microcontroller unit.

LVD5F_OE	Microcontroller unit external voltage fall detection output enable setting
0	Enable
1	Stop

* This bit is initialized by only power-on reset.

[bit2, bit1] Reserved

[bit0] LVD5F_F (Low Voltage Detect external 5v Fall Flag): Microcontroller unit external voltage fall detection flag

This is an external voltage fall detection flag for the microcontroller unit.

LVD5F_F	Microcontroller unit external voltage fall detection flag	
	Read	Write
0	Not detected	Clear the flag
1	Detected	No effect on operation

If a fall in external voltage of the microcontroller unit is detected, the LVD5F_F bit is set to "1".

This bit is cleared when external reset is input.

4.3. GDC Unit External Low Voltage Detection Rise Detection Register : GLVD5R (Gdc Low Voltage Detect external 5v Rise Register)

The bit configuration of the GDC unit external low voltage detection rise detection register (GLVD5R) is explained.

This register is used to clear the low voltage detection reset flag, etc.

■ GLVD5R : Address 0588_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GLVD5R_PD	Reserved	GLVD5R_SEL[1:0]	Reserved	GLVD5R_IE	Reserved	GLVD5R_F	
Initial value	0	0	0	1	0	0	0	X
Attribute	R/W	R0,WX	R/W	R/W	R0,WX	R/W	R0,WX	R(RM1), W

[bit7] GLVD5R_PD (Gdc Low Voltage Detect external 5v Rise Power Down): GDC unit external voltage rise power down setting

This bit is used to set whether to detect a rise in external voltage of the GDC unit or not.

GLVD5R_PD	GDC unit external voltage rise power down setting
0	Disable (Performs detection)
1	Enable (Stops detection)

[bit6] Reserved

[bit5, bit4] GLVD5R_SEL[1:0] (Gdc Low Voltage Detect external 5v Rise SElect): GDC unit external rise detection voltage setting

These bits are the selection signal for a detection level of external voltage rise detection for the GDC unit.

GLVD5R_SEL[1:0]	GDC unit external rise detection voltage setting
00	2.3V ± 0.2V
01	2.5V ± 0.2V
10	2.7V ± 0.2V
11	2.8V ± 0.2V

* GLVD5R_SEL[1:0] bits can be rewritten only when GLVD5R_PD = "1".

[bit3] Reserved

[bit2] GLVD5R_IE(Gdc Low Voltage Detect external 5v Rise Interrupt Enable): GDC unit external voltage rise interrupt enable

This bit shows the interrupt enable signal of the external voltage rise detection for the GDC unit.

GLVD5R_IE	GDC unit external voltage rise interrupt enable signal
0	Interrupt disable
1	Interrupt enable

[bit1] Reserved

[bit0] GLVD5R_F (Gdc Low Voltage Detect external 5v Rise Flag): GDC unit external voltage rise detection flag

This is an external voltage rise detection flag for the GDC unit.

GLVD5R_F	GDC unit external voltage rise detection flag	
	Read	Write
0	Not detected	Clear the flag
1	Detected	No effect on operation

If a rise in external voltage of the GDC unit is detected, the GLVD5R_F bit is set to "1".

This bit is cleared when external reset is input.

An initial value is undefined. Use it after the power supply of GDC is confirmed and it write clears.

4.4. GDC Unit External Low Voltage Detection Fall Detection Register : GLVD5F (Gdc Low Voltage Detect external 5v Fall Register)

The bit configuration of the GDC unit external low voltage detection fall detection register (GLVD5F) is explained.

This register is used to clear the low voltage detection reset flag, etc.

■ GLVD5F : Address 0589_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	GLVD5F_PD	Reserved	GLVD5F_SEL[1:0]	GLVD5F_OE	GLVD5F_IE	Reserved	GLVD5F_F	
Initial value	0	0	0	1	0	0	0	X
Attribute	R/W	R0,WX	R/W	R/W	R/W	R/W	R0,WX	R(RM1), W

[bit7] GLVD5F_PD (Gdc Low Voltage Detect external 5v Fall Power Down): GDC unit external voltage fall power down setting

This bit is used to set whether to detect a fall in external voltage of the GDC unit or not.

GLVD5F_PD	GDC unit external voltage fall power down setting
0	Disable (Performs detection)
1	Enable (Stops detection)

Note:

Set detection enable (OE = 0) after 100 μ s, if this bit sets the status of power-down enable to disable (operation start). If set it before 100 μ s, some detection flag setting will be occur.

[bit6] Reserved

[bit5, bit4] GLVD5F_SEL[1:0] (Gdc Low Voltage Detect external 5v Fall SElect): GDC unit external fall detection voltage setting

These bits are the selection signal for a detection level of external voltage fall detection for the GDC unit.

GLVD5F_SEL[1:0]	GDC unit external fall detection voltage setting
00	2.2V \pm 0.2V
01	2.4V \pm 0.2V
10	2.6V \pm 0.2V
11	2.7V \pm 0.2V

* GLVD5F_SEL[1:0] bits can be rewritten only when GLVD5F_OE = "1".

[bit3] GLVD5F_OE (Gdc Low Voltage Detect external 5v Fall Output Enable): GDC unit external voltage fall detection output enable setting

This bit is the output enable signal for external voltage fall detection for the GDC unit.

GLVD5F_OE	GDC unit external voltage fall detection output enable setting
0	Enable
1	Stop

[bit2] GLVD5F_IE(Gdc Low Voltage Detect external external 5v Fall Interrupt Enable): GDC unit external voltage fall interrupt enable

This bit shows the interrupt enable signal of the external voltage fall detection for the GDC unit.

GLVD5F_IE	GDC unit external voltage fall interrupt enable signal
0	Interrupt disable
1	Interrupt enable

[bit1] Reserved

[bit0] GLVD5F_F (Gdc Low Voltage Detect external 5v Fall Flag): GDC unit external voltage fall detection flag

This is an external voltage fall detection flag for the GDC unit.

GLVD5F_F	GDC unit external voltage fall detection flag	
	Read	Write
0	Not detected	Clear the flag
1	Detected	No effect on operation

If a fall in external voltage of the GDC unit is detected, the GLVD5F_F bit is set to "1".

This bit is cleared when external reset is input.

An initial value is undefined. Use it after the power supply of GDC is confirmed and it write clears.

5. Operation

This section explains the low voltage detection (external low-voltage detection).

- 5.1. Microcontroller Unit External Low Voltage Detection
- 5.2. GDC Unit External Low Voltage Detection

5.1. Microcontroller Unit External Low Voltage Detection

This section explains the microcontroller unit external low voltage detection.

The microcontroller unit external low voltage detection monitors the external voltage of the microcontroller unit and generates a initialization reset if the external voltage of the microcontroller unit drops below the configured value. The contents of this register cannot be guaranteed if a low voltage is detected and a settings initialization reset occurs. After the low voltage reset is released, the reset sequence is executed without delaying for the oscillation stabilization wait time, and then the program is restarted from the address specified by the reset vector.

5.2. GDC Unit External Low Voltage Detection

This section explains the GDC unit external low voltage detection (external low-voltage detection).

The GDC unit external low voltage detection monitors the external voltage of the GDC unit, detects a drop in the external voltage of the GDC unit below the configured detection voltage value, and sets a detection flag.

6. Notes

This section explains notes of the low voltage detection (external low-voltage detection).

■ Notes when using the low voltage detection reset circuit

● Program operation

- The low voltage detection reset circuit operates according to settings, except for the microcontroller unit external low voltage detection rise detection, which is used as power-on reset.
- Because the microcontroller unit external low voltage detection rise detection operates constantly, current is consumed even in sleep mode, stop mode, and watch mode.

● Operation in stop mode

- The low voltage detection reset can continue to operate even in stop mode by settings. If a low voltage is then detected in stop mode, the settings initialization reset is generated and stop mode is cleared.

● Hysteresis for detection/release

- The release voltage becomes set value +0.125V so that detection/release may have the hysteresis of 0.125V. For example, LVD5F: When $4.1V \pm 0.2V$ is set, the release voltage becomes $4.225V \pm 0.2V$.

CHAPTER : WILD REGISTER

This chapter explains the wild register.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation Description
6. Usage Example

Code : 29_MB91590_HM_E_wildreg_005_20111127

1. Overview

This section explains the overview of the wild register.

The function of the wild register is to switch the patch target address data that has been set to the address register with the data that has been set to the data register.

2. Features

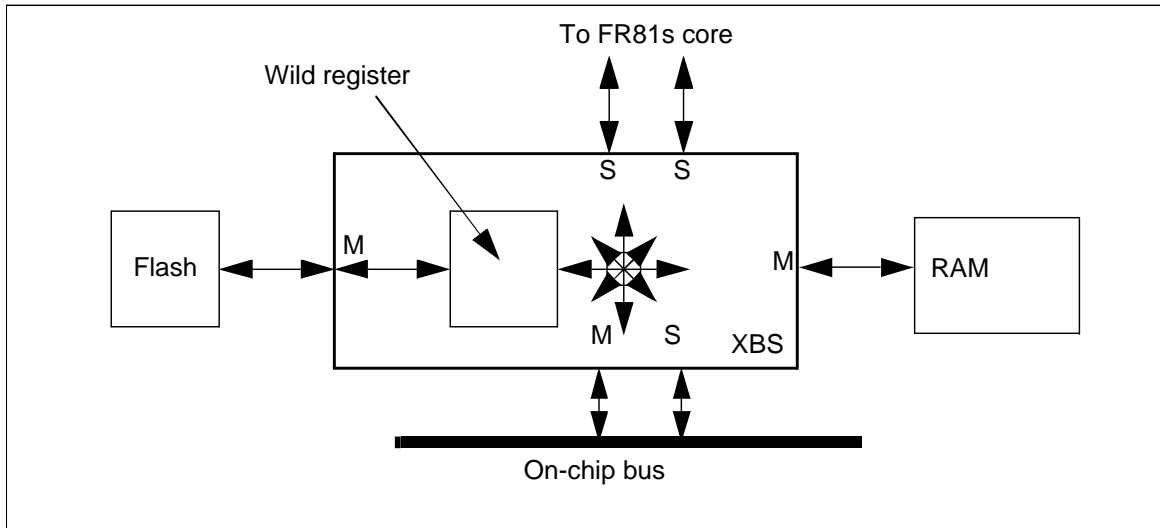
This section explains features of the wild register.

- Allows 16 locations of 1 word each to be patched.
- The target is only the flash area.
- One 16-bit control register
- Sixteen 32-bit address setting registers
- Sixteen 32-bit data setting registers

3. Configuration

This section explains the configuration of the wild register.

Figure 3-1 Configuration Diagram



Note:

When the access wait to the FLASH memory is set to one cycle, this function cannot be used.

4. Registers

This section explains registers of the wild register.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0858	Reserved		WREN		Wild register data enabled register
0x0880	WRAR00				Wild register address register 00
0x0884	WRDR00				Wild register data register 00
0x0888	WRAR01				Wild register address register 01
0x088C	WRDR01				Wild register data register 01
0x0890	WRAR02				Wild register address register 02
0x0894	WRDR02				Wild register data register 02
0x0898	WRAR03				Wild register address register 03
0x089C	WRDR03				Wild register data register 03
0x08A0	WRAR04				Wild register address register 04
0x08A4	WRDR04				Wild register data register 04
0x08A8	WRAR05				Wild register address register 05
0x08AC	WRDR05				Wild register data register 05
0x08B0	WRAR06				Wild register address register 06
0x08B4	WRDR06				Wild register data register 06
0x08B8	WRAR07				Wild register address register 07
0x08BC	WRDR07				Wild register data register 07
0x08C0	WRAR08				Wild register address register 08
0x08C4	WRDR08				Wild register data register 08
0x08C8	WRAR09				Wild register address register 09
0x08CC	WRDR09				Wild register data register 09
0x08D0	WRAR10				Wild register address register 10
0x08D4	WRDR10				Wild register data register 10
0x08D8	WRAR11				Wild register address register 11
0x08DC	WRDR11				Wild register data register 11

Address	Registers				Register function
	+0	+1	+2	+3	
0x08E0	WRAR12				Wild register address register 12
0x08E4	WRDR12				Wild register data register 12
0x08E8	WRAR13				Wild register address register 13
0x08EC	WRDR13				Wild register data register 13
0x08B0	WRAR14				Wild register address register 14
0x08F4	WRDR14				Wild register data register 14
0x08F8	WRAR15				Wild register address register 15
0x08FC	WRDR15				Wild register data register 15

4.1. Wild Register Data Enable Register : WREN (Wild Register data ENable register)

The bit configuration of the wild register data enable register is shown.

These bits set whether the wild register function is enabled or disabled on each channel.

■ WREN : Address085A_H (Access: Half-word)

	bit15	bit14	•	•	•	bit2	bit1	bit0	
	WREN[15:0]								
Initial value	0	0	•	•	•	0	0	0	
Attribute	R/W	R/W	•	•	•	R/W	R/W	R/W	

[bit15 to bit0] WREN[15:0] (Wild Register ENable) : Enable bits

These bits set whether the wild register function is enabled or disabled on each channel.

WREN _n (n = 0 to 15)	Function
0	Disables the wild register function of ch.n
1	Enables the wild register function of ch.n

4.2. Wild Register Address Register 00 to 15 : WRAR00 to 15 (Wild Register Address Register 00 to 15)

The bit configuration of wild register address register 00 to 15 is shown.

These registers set the address to be amended by the wild register function. The read value is undefined when the wild register operation is enabled.

Always set these registers in units of 32 bits.

■ WRAR : Address 0880_H to 08F8_H (Access: Word)

	bit31	bit30	bit29	bit28	bit27	bit26	bit25	bit24
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	Reserved		WRAR[21:16]					
Initial value	0	0	X	X	X	X	X	X
Attribute	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W	R/W

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	WRAR[15:8]							
Initial value	X	X	X	X	X	X	X	X
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	WRAR[7:2]						Reserved	
Initial value	X	X	X	X	X	X	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R0,WX	R0,WX

[bit21 to bit2] WRAR[21:2] (Wild Register Address Register) : Address register
These bits set the address to patch. The target address is (WRAR & 0x003FFFFC).

The read value is undefined when the wild register operation is enabled.

4.3. Wild Register Data Register 00 to 15 : WRDR00 to 15 (Wild Register Data Register 00 to 15)

The bit configuration of wild register data register 00 to 15 is shown.

These registers set the replacement data. When the contents of the memory at the addresses specified by the wild register address registers (WRAR00 to WRAR15) are read, the value set in these registers is returned instead of the actual contents of the memory.

The read value of these registers is undefined while the wild register function is operating.

Always set these registers in units of 32 bits.

■ **WRDR : Address 0884_H to 08FC_H (Access: Word)**

	bit31	bit30	•	•	•	bit2	bit1	bit0
	WRDR[31:0]							
Initial value	X	X	•	•	•	X	X	X
Attribute	R/W	R/W				R/W	R/W	R/W

[bit31 to bit0] WRDR[31:0] (Wild Register Data Register) : Data register

These bits set the replacement value.

The read value of these registers is undefined while the wild register function is operating.

5. Operation

This section explains the operation of the wild register.

This function is used to patch the flash area. Because the enable register is initialized by reset, this register needs to be set on each reset when being used.

The setting addresses need to be set so that they do not overlap each other. When addresses overlap, the reading value is undefined.

The data's byte line is the big endian.

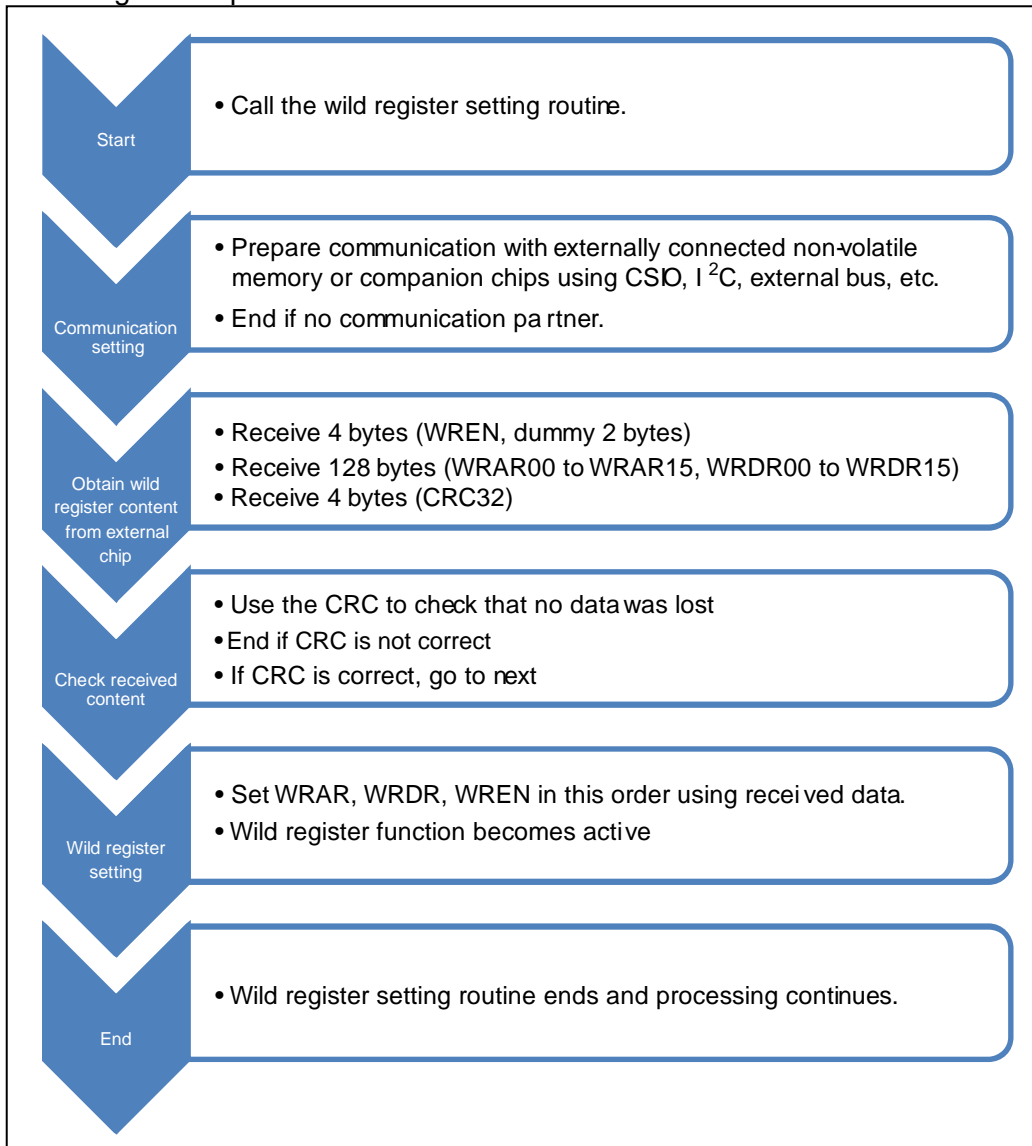
The target area to replace is the Flash area only.

6. Usage Example

This section explains a usage example of the wild register.

This section gives an example of using this function. In this example, the settings of this function are called from an externally attached device after reset is released.

Figure 6-1 Usage Example



CHAPTER: CLOCK SUPERVISOR

This chapter explains overview, features, and register, etc of the clock supervisor.

1. Overview
2. Configuration
3. Register
4. Operation

Code : 30_MB91590_HM_E_clocksv_005_20111127

1. Overview

This section explains the overview of the clock supervisor.

If some kind of problem occurs in the clock and it stops unintentionally, the built-in CR oscillator can substitute for the clock.

The clock supervisor for the sub clock is independent with the clock supervisor for the main. The clock supervisor can be enabled, and disabled separately.

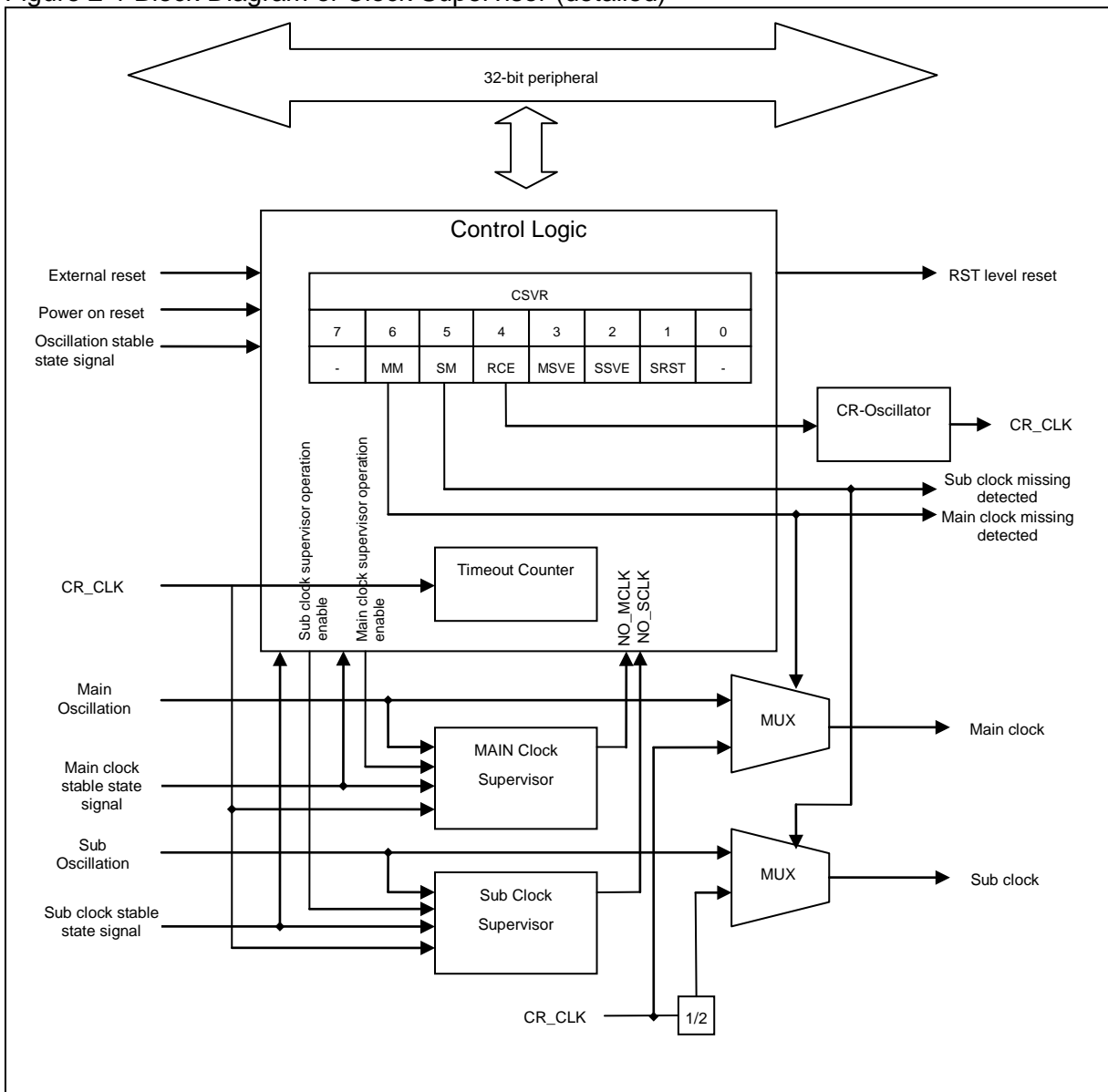
2. Configuration

This section shows the configuration of the clock supervisor.

The blocks that make up the clock supervisor are shown below.

- Clock supervisor
- Timeout counter
- Control logic
- CR oscillator

Figure 2-1 Block Diagram of Clock Supervisor (detailed)



* : External reset: On assert of RSTX pin (including simultaneous assert with NMIX)

Note:

The sub clock supervisor can be used for dual clock products.

3. Register

This section explains a register of the clock supervisor.

Table 3-1 Register Map

Address	Register				Register function
	+0	+1	+2	+3	
0x056C	Reserved	CSVCR	Reserved	Reserved	Clock supervisor control register

■ Clock Supervisor Control Register : CSVCR(Clock SuperVisor Control Register)

This register sets operation mode of clock supervisor.

This register has the bit that shows the breakdown of the clock.

● CSVCR : Address 056DH (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	MM	SM	RCE	MSVE	SSVE	SRST	Reserved

Initial value	0	0	0	1	1/0	1	0	0
Attribute	R0/W0	R,W	R,W	R/W	R/W	R/W	R0/W0	R0/W0

(Note) Initial value of bit3 depends on the part number.

[bit7] Reserved

"0" should be written to this bit.

[bit6] MM (Main clock Missing) : Main clock stop

When this bit is "1", it indicates that any problem is found in the main oscillation clock.

When this bit is "0", there are no problems in the main clock.

When the main clock is not restored, "0" write access is ignored.

This bit will be cleared to "0" on power on or external reset. Other types of resets have no effect on this bit.

MM	Read	Write
0	Main oscillation clock stop undetected	When the main clock is restored oscillating, this bit can be cleared
1	Main oscillation clock stop detected	No effect

Note:

Do not enable the PLL oscillation operation when this bit is "1".

[bit5] SM (Sub clock Missing) : Sub clock stop

When this bit is "1", it indicates that any problem is found in the sub oscillation clock.

When this bit is "0", there are no problems in the sub clock.

When the sub clock is not restored, "0" write access is ignored.

This bit will be cleared to "0" on power on or external reset. Other types of resets have no effect on this bit.

SM	Read	Write
0	Sub oscillation clock stop undetected	When the sub clock is restored oscillating, this bit can be cleared
1	Sub oscillation clock stop detected	No effect

[bit4] RCE (CR-oscillator Enable) : CR oscillator Enable

The oscillation of the CR oscillator is permitted at the standby mode when this bit is set to "1". The thing to set this bit to "0" is prohibited while main clock supervisor or the sub-clock supervisor has been still permitted.

First of all, it is necessary to confirm the MM bit and the SM bit are "0" after prohibiting the supervisor.

Afterwards, sets the RCE bit to "0".

Please do not set the RCE bit to "0" when either of the MM bit or the SM bit is "1". This bit is cleared to "1" by turning on the power supply or external reset. Other types of resets have no effect on this bit.

RCE	Description
0	CR oscillation disabled at STBY mode
1	CR oscillation enabled at STBY mode (Initial value)

[bit3] MSVE (Main clock SuperVisor Enable) : Main clock supervisor enable

When this bit is set to "1", the main clock supervisor is enabled.

This bit is only initialized to "1" when the power is turned on.

Other types of resets have no effect on this bit.

MSVE	Description
0	Main clock supervisor disabled (Initial Value of the products whose initial state of the clock supervisor is OFF)
1	Main clock supervisor enabled (Initial Value of the products whose initial state of the clock supervisor is ON)

Note:

Initial state of the clock supervisor depends on the part number. Therefore, initial value of this bit depends on the part number. Refer "3 Product Line-up" in "CHAPTER: OVERVIEW" for the detail of the part number.

[bit2] SSVE (Sub clock SuperVisor Enable) : Sub clock supervisor enable

When this bit is set to "1", the sub clock supervisor is enabled.

This bit is only initialized to "1" when the power is turned on.

Other types of resets have no effect on this bit.

SSVE	Description
0	Sub clock supervisor disabled
1	Sub clock supervisor enabled (Initial value)

[bit1] SRST (Sub clock mode reset) : Sub clock mode reset

"0" should be written to this bit.

SRST	Description
0	No reset occurs when user changes main clock to sub clock while sub clock missing (Initial value).
1	Reset occurs when user changes main clock to sub clock while sub clock missing.

[bit0] Reserved

"0" should be written to this bit.

4. Operation

This section explains the operation of the clock supervisor.

After the clock replaces the CR oscillator, it is reset at once when the main clock stops while CPU is working with the main clock. When the period of 30 μ s to 40 μ s and the clock is not input, it is judged that it stops. Because the bit that shows the thing that the main clock stops remains in the register, the thing that the problem occurs with software can be judged.

After the clock replaces the CR oscillator, it is reset at once when sub clock stops while CPU is working with sub clock. When the period of 310 μ s to 320 μ s and the clock is not input, it is judged that it stops. Because the bit that shows the thing that a sub clock stops remains in the register, the thing that the problem occurs with software can be judged.

When sub clock stops while CPU is working with the main clock, reset is not generated at once. It operates with the CR clock when changing to the sub clock mode.

The main clock supervisor stops automatically when the main clock is stopped intending it. When sub clock is stopped intending it, the sub clock supervisor stops automatically.

The CR oscillator stops automatically when the standby mode changes when the CR oscillation at the standby mode is prohibited. The CR oscillator reactivates automatically when returning from the standby mode.

Note:

Please do not permit the PLL oscillation operation when the main clock is replaced with the CR oscillator and works after detecting the main clock stop.

The following explains the operational mode of the clock supervisor.

4.1. Initial State

This section explains the initial state of the clock supervisor.

When initial setting, the oscillation of the CR oscillator, main clock supervisor function, and sub clock supervisor function have been enabled.

■ CR Oscillator

The oscillation is enabled when the power is turned on.

Only when changing to the standby mode with "0" written in oscillation enable bit (CSVCR:RCE) at the standby mode, it stops. When the standby mode is made clear, the oscillation is automatically restarted.

■ Main Clock Supervisor

Main clock supervisor is enabled after the main oscillation stabilization wait time has elapsed for the products whose initial state of the clock supervisor is ON.

Main clock supervisor is disabled initially for the products whose initial state of the clock supervisor is OFF. Main clock supervisor is enabled if it is enabled by the software.

When the main clock supervisor is enabled, if the main clock stops, the main clock is replaced by the CR oscillation clock.

Moreover, the MM bit of the CSVCR register is set to "1" and an RST level reset is generated.

[Notes]

For the products whose initial state of the clock supervisor is ON, Because the main oscillation stabilization wait time is measured by the main clock itself, if the main clock stops before the oscillation stabilization wait time has elapsed, the main oscillation stabilization wait time does not end and the main clock supervisor is not enabled.

In this case, after the timeout time measured by the internal CR oscillator has elapsed, the main supervisor function is enabled regardless of the oscillation stabilization wait time and the main clock stop is detected.

■ Sub Clock Supervisor

After the timeout period measured by internal CR oscillator passes, it is enabled.

Behavior when a sub-clock stops when the sub-clock supervisor has been permitted changes according to whether MCU operates with the main clock or it operates with a sub-clock.

● For the main clock mode

When a sub clock stops while operating in the main clock mode, a sub clock replaces two dividing frequency of the CR oscillation clock. Afterwards, reset keeps being not generated and operating in the main clock mode though the SM bit of the CSVCR register is set to "1".

Under such a condition, clock changes to the sub-clock mode that operates with the CR oscillation clock when changing to the sub-clock mode.

● For the sub clock mode

When a sub clock stops while operating in the sub-clock mode, two dividing frequency of the CR oscillation clock replaces a sub clock. Afterwards, the SM bit of the CSVCR register is set to "1", and reset of the RST level is generated.

4.2. Stopping CR Oscillator and the Clock Supervisor Function

This section explains stopping CR oscillator and the clock supervisor function.

■ CR Oscillator

The CR oscillator can be stopped only at the standby mode. Please change to the standby mode after setting oscillation permission bit (CSVCR:RCE) at the standby mode to "0".

The thing to stop the CR oscillator when there is a problem in the main clock or a sub-clock is prohibited. It can be confirmed whether or not the problem exists in the clock by the MM bit and the SM bit of the CSVCR register.

[Note]

The operation clock stops, too, when the CR oscillation is stopped because the operation clock has already replaced the CR oscillation clock when there is a problem in the clock.

■ Main Clock Supervisor

The MSVE bit of the CSVCR register is set to "0".

■ Sub Clock Supervisor

The SSVE bit of the CSVCR register is set to "0".

4.3. Re-enabling the Clock Supervisor

This section explains re-enabling the clock supervisor.

■ Main Clock Supervisor

To re-enable the main clock supervisor function, set the MSVE bit of the CSVCR register to "1".

The thing to permit the main clock supervisor function with the CR oscillator has stopped is prohibited.

[Notes]

Because the main oscillation stabilization wait time is measured by the main clock itself, if the main clock stops before the oscillation stabilization wait time has elapsed, the main oscillation stabilization wait time does not end and the main clock supervisor is not enabled.

In this case, after the timeout time measured by the internal CR oscillator has elapsed, the main supervisor function is enabled regardless of the oscillation stabilization wait time and the main clock stop is detected.

■ Sub Clock Supervisor

To permit the sub clock supervisor function again, the SSVE bit of the CSVCR register is set to "1". The thing to permit the sub clock supervisor function with the CR oscillator has stopped is prohibited.

4.4. Sub Clock Mode

This section explains the sub clock mode of the clock supervisor.

The main clock supervisor function stops automatically when the device changes to the sub clock mode with the main clock supervisor function has been permitted.

The main clock supervisor enable bit (CSVCR:MSVE) does not become "0".

After the oscillation stabilization wait time of the main clock passes, the main clock supervisor function is permitted again when the device changes from the sub-clock mode to the main clock mode.

[Notes]

Because the main oscillation stabilization wait time is measured by the main clock itself, if the main clock stops before the oscillation stabilization wait time has elapsed, the main oscillation stabilization wait time does not end and the main clock supervisor is not enabled.

In this case, after the timeout time measured by the internal CR oscillator has elapsed, the main supervisor function is enabled regardless of the oscillation stabilization wait time and the main clock stop is detected.

4.5. Stop Mode

This section explains stop mode of the clock supervisor.

■ CR Oscillator

The oscillation stops when oscillation permission bit (CSVCR:RCE) at the stop mode is set to "0" by changing to the stop mode.

After the stop mode is made clear, it is permitted automatically again.

■ Main Clock Supervisor

When the main clock supervisor function is enabled, it automatically stops when stop mode is entered.

The main clock supervisor enable bit (CSVCR:MSVE) does not change to "0".

After stop mode is released, the supervisor is automatically re-enabled after waiting for the main oscillation stabilization wait time.

[Notes]

Because the main oscillation stabilization wait time is measured by the main clock itself, if the main clock stops before the oscillation stabilization wait time has elapsed, the main oscillation stabilization wait time does not end and the main clock supervisor is not enabled.

In this case, after the timeout time measured by the internal CR oscillator has elapsed, the main supervisor function is enabled regardless of the oscillation stabilization wait time and the main clock stop is detected.

Note:

When the main clock supervisor function is disabled, if stop mode is entered, the supervisor remains disabled even after recovering from stop mode.

■ Sub Clock Supervisor

When the sub clock supervisor function is enabled, it automatically stops when stop mode is entered.

The sub clock supervisor enable bit (CSVCR:SSVE) does not change to "0".

After stop mode is released, the supervisor is automatically re-enabled after waiting for the main oscillation stabilization wait time.

Note:

When the sub clock supervisor function is disabled, if stop mode is entered, the supervisor remains disabled even after recovering from stop mode.

4.6. Watch Mode

This section explains watch mode.

■ Main Clock Supervisor

The main clock supervisor function is not influenced from the transition to the watch mode.

When the main clock stops, the change dividing and reset are issued to the CR oscillation clock when the main clock is connected with the permission of the main clock supervisor function and RTC.

The watch mode is made clear, and RTC is initialized.

The RTC clock stops only because it does not detect it even if the main clock stops when the main clock is connected with the prohibition of the main clock supervisor function and RTC.

■ Sub Clock Supervisor

The sub clock supervisor function is not influenced from the transition to the watch mode.

When a sub clock is connected with the permission of the sub clock supervisor function and RTC, reset is not issued though it cuts in the CR oscillation clock when a sub clock stops.

The RTC clock stops only because it does not detect it even if the sub clock stops when the sub clock is connected with the prohibition of the sub clock supervisor function and RTC.

4.7. Checking the Reset Factor Using the Clock Supervisor

Checking the reset factor using the clock supervisor is explained.

The method for checking whether or not the clock supervisor detected a clock problem and generated a reset is shown below.

First, read the RSTRR register (see "4.1 Reset Source Register: RSTRR (ReSeT Result Register)" in "CHAPTER: RESET") to check the reset factor.

If the ERST bit of the RSTRR register is "1", this indicates that either reset input from the RSTX external pin, illegal standby mode transition detection reset, external power supply low-voltage detection, clock supervisor reset, or simultaneous assert of RSTX and NMIX external pins was generated.

Please read the CSVCR register in this case, and confirm the MM bit. Also, read the RSTRR register (see "4.1 Reset Source Register: RSTRR (ReSeT Result Register)" in "CHAPTER: RESET") and confirm the reset factor.

The reset factor can be checked as follows.

MM	SM	Reset factor
1	0	Main clock supervisor reset
0	1	Sub clock supervisor reset
1	1	Main clock supervisor reset or Sub clock supervisor reset

[Notes]

Because the MM bit and SM bit are not cleared in conditions other than turning the power on and the external reset, it is necessary to confirm other reset factors reading the RSTRR register (see "4.1 Reset Source Register: RSTRR (ReSeT Result Register)" in "CHAPTER: RESET").

4.8. Return from CR Clock

Return from the CR clock is explained.

■ Main Clock Supervisor

The main clock stops when the MPU detects that the MM bit has been set after recovering from a reset, and it can be judged that there has been a change in the CR oscillation clock. At this time, it is possible to return to the main clock by writing "0" in the MM bit if it can be confirmed that the main clock is restored.

When the main clock is not restored, writing "0" in the MM bit does not have any influence. The MM bit keeps maintaining "1".

The MM bit is cleared when the main clock works when "0" is written in the MM bit, and the clock returns to the main clock via a synchronous stage.

It can perform polling on the MM bit until the main clock is restored.

```
ldi #_csvcr,r1
clear_CSV_loop:
bandh #0b1001,@r1 ;; Clear MM+SM
btsth #0b0110,@r1 ;; Check: Is one of them 1?
bne clear_CSV_loop
```

<Note>

Set "0" to PMUCTLR.SHDE to return to the main clock.

■ Sub Clock Supervisor

A sub clock stops when the MPU detects that the SM bit has been set and it can be judged that there has been a change in the CR oscillation clock. At this time, it is possible to return to the sub clock by writing "0" in the SM bit if it can be confirmed that the sub clock is restored.

When a sub clock is not restored, writing "0" in the SM bit does not have any influence. The SM bit keeps maintaining "1".

The SM bit is cleared when a sub clock works when "0" is written in the SM bit, and the clock returns to a sub clock via a synchronous stage.

It can perform polling on the SM bit until a sub-clock is restored. (The same method as main clock supervisor can be used.)

<Note>

Set "0" to PMUCTLR.SHDE to return to the sub clock.

CHAPTER : SOUND GENERATOR

This chapter explains the sound generator.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

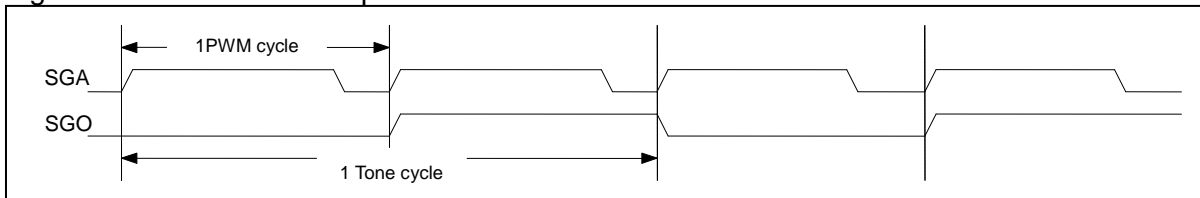
This section explains the overview of the sound generator.

This series includes a sound generator with 5 channels. The sound generator generates and outputs tone pulse signals (or mixed signals of tone pulse signals and PWM pulse signals) and PWM pulse signals according to the setting from the CPU. The frequency of tone pulse signals to output, sound volume (amplitude of PWM pulse), and sound length can be specified.

The sound generator consists of registers and counters below:

- DMA transfer update enable register
- Sound control register
- Amplitude data register
- Frequency data register
- Cycle register
- Tone outputs number register
- Increment decrement data register
- PWM cycles number data register
- DMA transfer indirect register
- PWM pulse generator
- Frequency counter
- Decrement counter
- Tone pulse counter

Figure 1-1 External Pin Output



2. Features

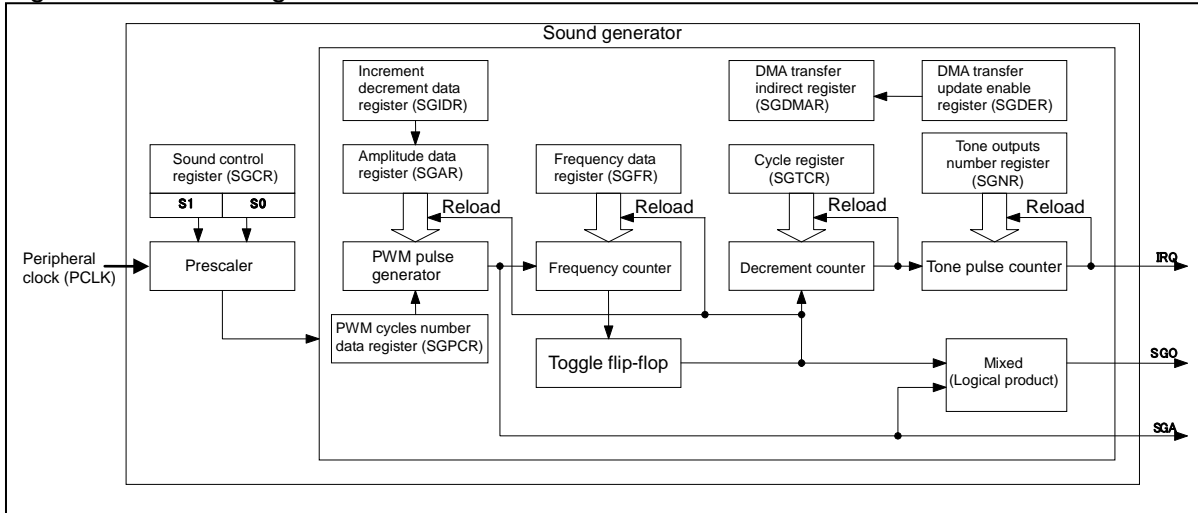
This section explains features of the sound generator.

No	Item	Function
1	Operating clock	Peripheral clock (PCLK) 16 MHz to 40 MHz
2	Clock input	For clock input for the sound generator, the peripheral clock (PCLK) is used with divided frequency. <ul style="list-style-type: none"> • Peripheral clock (PCLK) • $1/2 \times$ peripheral clock (PCLK) • $1/4 \times$ peripheral clock (PCLK) • $1/8 \times$ peripheral clock (PCLK)
3	Wave form	Square wave for sound (sound output from SGO pin)
4	Sound volume	Any volume can be set (amplitude output from SGA pin)
5	Frequency	Sound signal frequency can be set to any value (frequency setting and PWM cycles number setting)
6	Sound length	Any value can be set.
7	Interrupt	<ul style="list-style-type: none"> • When the specified sound length is finished to output, an interrupt request can be generated. (Tone pulse counter overflow) • In the DMA mode (SGCR:DMA="1"), when "1" is written to the start bit (SGCR:ST), an interrupt can be generated.

3. Configuration

This section explains the configuration of the sound generator.

Figure 3-1 Block Diagram



4. Registers

This section explains registers of the sound generator.

■ Table of Base Addresses (Base_addr) and External Pins

Table 4-1 Table of Base Addresses and External Pins

Channel	Base_addr	External pin	
		SGO	SGA
0	0x1040	SGO0	SGA0
1	0x1060	SGO1	SGA1
2	0x1080	SGO2	SGA2
3	0x10A0	SGO3	SGA3
4	0x10C0	SGO4	SGA4

■ Registers Map

Table 4-2 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x1040	Reserved	SGDER0	SGCR0		DMA transfer update register 0 Sound control register 0
0x1044	SGAR0		SGFR0	SGNR0	Amplitude data register 0 Frequency data register 0 Tone outputs number register 0
0x1048	SGTCR0	SGIDR0	SGPCR0		Cycle register 0 Increment decrement amount data register 0 PWM cycles number register 0
0x104C	SGDMAR0				DMA transfer indirect register 0
0x1060	Reserved	SGDER1	SGCR1		DMA transfer update register 1 Sound control register 1
0x1064	SGAR1		SGFR1	SGNR1	Amplitude data register 1 Frequency data register 1 Tone outputs number register 1
0x1068	SGTCR1	SGIDR1	SGPCR1		Cycle register 1 Increment decrement amount data register 1 PWM cycles number register 1
0x106C	SGDMAR1				DMA transfer indirect register 1
0x1080	Reserved	SGDER2	SGCR2		DMA transfer update register 2 Sound control register 2

Address	Registers				Register function
	+0	+1	+2	+3	
0x1084	SGAR2		SGFR2	SGNR2	Amplitude data register 2 Frequency data register 2 Tone outputs number register 2
0x1088	SGTCR2	SGIDR2	SGPCR2		Cycle register 2 Increment decrement amount data register 2 PWM cycles number register 2
0x108C	SGDMAR2				DMA transfer indirect register 2
0x10A0	Reserved	SGDER3	SGCR3		DMA transfer update register 3 Sound control register 3
0x10A4	SGAR3		SGFR3	SGNR3	Amplitude data register 3 Frequency data register 3 Tone outputs number register 3
0x10A8	SGTCR3	SGIDR3	SGPCR3		Cycle register 3 Increment decrement amount data register 3 PWM cycles number register 3
0x10AC	SGDMAR3				DMA transfer indirect register 3
0x10C0	Reserved	SGDER4	SGCR4		DMA transfer update register 4 Sound control register 4
0x10C4	SGAR4		SGFR4	SGNR4	Amplitude data register 4 Frequency data register 4 Tone outputs number register 4
0x10C8	SGTCR4	SGIDR4	SGPCR4		Cycle register 4 Increment decrement amount data register 4 PWM cycles number register 4
0x10CC	SGDMAR4				DMA transfer indirect register 4

4.1. DMA Transfer Update Enable Register : SGDER (SG DMA Enable Register)

This section explains the bit configuration for the DMA transfer update enable register (SGDER).

The DMA transfer update enable register (SGDER) is to set registers (SGAR, SGFR, SGNR, SGTCR, SGIDR, SGPCR) in bytes to be updated on DMA transfer. The sound generator determines the register to be updated on DMA transfer according to the configuration of this register. In addition, the transfer count of DMA transfers, number of transfer bytes, and DMA transfer indirect register (SGDMAR) enabled bytes location are determined with the configuration of this register.

■ SGDER : Address Base_addr + 01_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ARE1	ARE0	FRE	NRE	TCRE	IDRE	PCRE1	PCRE0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	ARE1: Amplitude data (upper byte) update enable bit	On DMA transfer, update of the amplitude data (upper byte) of the amplitude data register (SGAR) is enabled via the DMA transfer indirect register. When this bit is set to "0": Amplitude data (upper byte) is not updated. When this bit is set to "1": Amplitude data (upper byte) is updated.
bit6	ARE0: Amplitude data (lower byte) update enable bit	On DMA transfer, update of the amplitude data (lower byte) of the amplitude data register (SGAR) is enabled via the DMA transfer indirect register. When this bit is set to "0": Amplitude data (lower byte) is not updated. When this bit is set to "1": Amplitude data (lower byte) is updated.
bit5	FRE: Frequency data update enable bit	On DMA transfer, update of the frequency data of the frequency data register (SGFR) is enabled via the DMA transfer indirect register. When this bit is set to "0": Frequency data is not updated. When this bit is set to "1": Frequency data is updated.
bit4	NRE: Tone output number update enable bit	On DMA transfer, update of the tone outputs number of the tone outputs number register (SGNR) is enabled via the DMA transfer indirect register. When this bit is set to "0": Tone output number is not updated. When this bit is set to "1": Tone output number is updated.
bit3	TCRE: Cycle update enable bit	On DMA transfer, update of the cycle of the cycle register (SGTCR) is enabled via the DMA transfer indirect register. When this bit is set to "0": Cycle is not updated. When this bit is set to "1": Cycle is updated.
bit2	IDRE: Increment decrement amount data update enable bit	On DMA transfer, update of the increment decrement amount data of the increment decrement data register (SGIDR) is enabled via the DMA transfer indirect register. When this bit is set to "0": Increment decrement amount data is not updated. When this bit is set to "1": Increment decrement amount data is updated.

Bit name		Function
bit1	PCRE1: PWM cycles number data (upper byte) update enable bit	On DMA transfer, update of the PWM cycles number data (upper byte) of the PWM cycles number data register (SGPCR) is enabled via the DMA transfer indirect register. When this bit is set to "0": PWM cycles number data (upper byte) is not updated. When this bit is set to "1": PWM cycles number data (upper byte) is updated.
bit0	PCRE0: PWM cycles number data (lower byte) update enable bit	On DMA transfer, update of the PWM cycles number data (lower byte) of the PWM cycles number data register (SGPCR) is enabled via the DMA transfer indirect register. When this bit is set to "0": PWM cycles number data (lower byte) is not updated. When this bit is set to "1": PWM cycles number data (lower byte) is updated.

4.2. Sound Control Register : SGCR (SG Control Register)

This section explains the bit configuration for the sound control register (SGCR).

The sound control register (SGCR) controls interrupts and the operating state of the sound generator.

■ SGCR : Address Base_addr + 02_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	SRST	DMA	GID	GEN	Reserved	BUSY	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W0	R0,W	R/W	R/W	R/W	R0,W0	R/W	R0,W0

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	S1	S0	TONE	Reserved	INTE	INT	ST	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R(RM1),W	R,W

Bit name		Function
bit15	Reserved	This bit is reserved. This bit must always be written to "0".
bit14	SRST: Software reset bit	This bit is a software reset bit. When "1" is set to this bit, hardware issues a software reset. On read, "0" is always read, therefore, setting of this bit to "0" is invalid.
bit13	DMA: DMA transfer start interrupt set enable bit	This bit is a DMA transfer start interrupt set enable bit. When this bit is set to "0": When "1" is written to a start bit (SGCR:ST), an interrupt bit (SGCR:INT) is not set. When this bit is set to "1": When "1" is written to a start bit (SGCR:ST), an interrupt bit (SGCR:INT) is set. Note: Do not change the setting of this bit during the sound generator is being operated (SGCR:ST = 1).

Bit name		Function
bit12	GID: Increment decrement setting bit	<p>With the cycle register (SGTCR), increment decrement amount data register (SGIDR), and automatic increment decrement enable bit (SGCR:GEN), this bit is designed for automatic increment decrement of sound. The value stored in the amplitude data register is incremented or decremented by the value of the increment decrement amount data register on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register (increment decrement setting reflection timing) according to the setting of the increment decrement setting bit.</p> <p>When this bit is set to "0": The value stored in the amplitude data register is decremented.</p> <p>When this bit is set to "1": The value stored in the amplitude data register is incremented.</p> <p>Note: This bit is enabled only when the automatic increment decrement enable bit is enabled (SGCR:GEN = 1). If the setting is changed during operation, the register value of the increment decrement setting reflection timing is enabled.</p>
bit11	GEN: Automatic increment decrement enable bit	<p>With the cycle register (SGTCR), increment decrement amount data register (SGIDR), and increment decrement setting bit (SGCR:GID), this bit is designed for automatic increment decrement of sound.</p> <p>When this bit is set to "0": Automatic increment decrement of sound is disabled.</p> <p>When this bit is set to "1": Automatic increment decrement of sound is enabled.</p> <p>The value stored in the amplitude data register is incremented or decremented by the value of the increment decrement amount data register on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register (increment decrement setting reflection timing) according to the setting of the increment decrement setting bit.</p> <p>Note: When the automatic increment decrement enable setting is changed to disable setting, the amplitude data register keeps the current value. When the automatic increment decrement disable setting is changed to enable setting, the current value of the amplitude data register is incremented or decremented from the increment decrement setting reflection timing.</p>
bit10	Reserved	This bit is reserved. On read, "0" is read, and on write, write "0".
bit9	BUSY: Busy bit	<p>This bit indicates whether the sound generator is being operated or not.</p> <p>Condition for "1": When the SGCR:ST bit is set to "1", this bit is set to "1".</p> <p>Condition for "0": When the SGCR:ST bit is set to "0" and operation is completed on 1 tone cycle completion, this bit is cleared to "0".</p> <p>Note: This bit becomes "0" with a software reset (SGCR:SRST = 1 write).</p>
bit8	Reserved	This bit is reserved. On read, "0" is read, and on write, write "0".

Bit name		Function
bit7, bit6	S1, S0: Operating clock selection bits	These bits select a clock input signal for the sound generator. {S1,S0} Clock input 00 1/1 Input clock 01 1/2 Input clock 10 1/4 Input clock 11 1/8 Input clock
bit5	TONE: Tone output bit	This bit sets a SGO signal. When this bit is set to "0": The SGO signal is a mixed signal (logical multiply) of a tone pulse and a PWM pulse. When this bit is set to "1": The SGO signal is a simple square waveform (tone pulse) signal from the toggle flip-flop.
bit4	Reserved	This bit is reserved. Written value is ignored.
bit3	Reserved	This bit is reserved. Written value is ignored.
bit2	INTE: Interrupt enable bit	Interrupt signals of the sound generator are enabled. When this bit is set to "0": The interrupt by the SGCR:INT bit is disabled. When this bit is set to "1": The interrupt by the SGCR:INT bit is enabled. With SGCR:INT =1, an interrupt signal is output.
bit1	INT: Interrupt bit	When the tone pulse counter counts the tone pulses number specified to the tone outputs number register and cycle register, this bit is set to "1". In addition, in the DMA mode (SGCR:DMA = 1) when the amplitude data register (SGAR), frequency data register (SGFR), tone outputs number register (SGNR), cycle register (SGTCR), and increment decrement amount data register (SGIDR) are not written but the start bit (SGCR:ST) is written to "1" also, this bit becomes "1", and this can be used as a DMA transfer start request. When this bit is written to "0", it is cleared to "0", however, even if it is written to "1", it is disabled and the previous value is held. • Condition for "1": Tone pulse count number \geq (Cycle register value + 1) \times (Tone outputs number register value + 1) • Condition for "0": When this bit is written to "0", it is cleared to "0". Note: On a read access by a read-modify-write instruction, "1" is always read. This bit becomes "0" with a software reset (SGCR:SRST = 1 write).
bit0	ST: Start bit	This bit is for operation start for the sound generator. When this bit is set to "1": The operation of the sound generator is started. When this bit is set to "0": The operation of the sound generator is stopped after completion of the current tone cycle. Note: While this bit is "1", the sound generator is being operated. When this bit is set to "0", it is cleared to "0", and the operation of the sound generator is stopped after the current tone cycle is completed. Whether the sound generator is stopped completely or not is indicated by the SGCR:BUSY bit. This bit becomes "0" with a software reset (SGCR:SRST = 1 write).

4.3. Amplitude Data Register : SGAR (SG Amplitude Register)

This section explains the bit configuration for the amplitude data register (SGAR).

The amplitude data register (SGAR) stores reload values for the PWM pulse generator. The register value indicates the amplitude of sound. The register value is reloaded to the PWM pulse generator for each completion of a tone cycle.

■ **SGAR: Address Base_addr + 04_H (Access: Byte, Half-word, Word)**

	bit15	bit14	-	-	-	bit2	bit1	bit0
	D[15:0]							
Initial value	0	0	-	-	-	0	0	0
Attribute	R/W	R/W	-	-	-	R/W	R/W	R/W

[bit15 to bit0] D[15:0] (Data) : Amplitude data bits

These bits store reload values for the PWM pulse generator. Software sets the reload value for the PWM pulse generator. When the increment decrement enable bit is enabled (SGCR:GEN = 1), hardware increments or decrements the value stored in the amplitude data register by the value of the increment decrement amount data register (SGIDR) on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register (SGTCR) according to the setting of the increment decrement setting bit (SGCR:GID). When the increment decrement setting bit is set with decrement (SGCR:GID = 0) and the amplitude data register value is "0x0000", no more decrement is performed. When the increment decrement setting bit is set with increment decrement (SGCR:GID = 1) and the amplitude data register value is "0xFFFF", no more increment is performed. However, the operation of the sound generator is continued until the start bit (SGCR:ST) is cleared.

4.4. Frequency Data Register : SGFR (SG Frequency Register)

This section explains the bit configuration for the frequency data register (SGFR).

The frequency data register (SGFR) stores the reload value for the frequency counter. The stored value indicates the frequency of sound (or the tone signal from the toggle flip-flop). The register value is reloaded to the counter for each transition of the toggle signal.

■ SGFR : Address Base_addr + 06_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] D[7:0] (Data) : Frequency data bits

These bits store reload values for the frequency counter. Software sets the reload value for the frequency counter. Hardware uses the bits for the frequency of sound (or the tone signal from the toggle flip-flop). The register value is reloaded to the counter for each transition of the toggle signal.

Note:

Note that when the register value is changed during operation, 50% of the duty cycle of the sound (or the tone signal from the toggle flip-flop) might be changed depending on the change timing.

4.5. Tone Outputs Number Register : SGNR (SG tone Number Register)

This section explains the bit configuration for the tone outputs number register (SGNR).

The tone outputs number register (SGNR) stores the reload value for the tone pulse counter. The tone pulse counter accumulates the tone pulses number (or times of amplitude operations of the sound), and when the number reaches the reload value, the interrupt bit (SGCR:INT) is set. This aims to reduce the frequency of interrupts.

■ SGNR : Address Base_addr + 07_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] D[7:0] (Data) : Tone outputs number bits

These bits store reload values for the tone pulse counter. Software sets the reload value for the tone pulse counter. Hardware accumulates the tone pulses number (or times of amplitude operations of the sound) with the tone pulse counter, and when the number reaches the reload value, the interrupt bit (SGCR:INT) is set.

When "0x00" is set to the tone count register, the tone pulse counter sets the SGCR:INT bit for each the carry-out signal from the decrement counter. Accumulated tone pulses number is obtained by the formula below. In addition, the cycle register stores the reload value of the decrement counter.

$$(\text{Cycle register value} + 1) \times (\text{Tone outputs number register value} + 1)$$

When both the tone output register and the cycle register are set to "0x00", the interrupt bit (SGCR:INT) is set for each tone cycle.

4.6. Cycle Register : SGTCR (SG Tone Cycle Register)

This section explains the bit configuration for the cycle register (SGTCR).

The cycle register (SGTCR) stores the reload value for the decrement counter. This is designed to increment or decrement automatically the value stored in the amplitude data register (SGAR).

When the automatic increment decrement enable bit (SGCR:GEN) is set to enable, the value stored in the amplitude data register (SGAR) is incremented or decremented by the value of the increment decrement amount data register (SGIDR) on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register according to the setting of the increment decrement setting bit (SGCR:GID).

This behavior allows less CPU intervention to the sound automatic increment decrement performance.

Note that the pulses number specified by this register is "register value + 1". When it is set to "0x00", the automatic increment decrement behavior is performed for each tone cycle.

■ SGTCR : Address Base_addr + 08_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] D[7:0] (Data) : Cycle bits

These bits store reload values for the decrement counter. Software sets reload values for the decrement counter. Hardware increments or decrements the value stored in the amplitude data register (SGAR) by the value of the increment decrement amount data register (SGIDR) on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register according to the setting of the increment decrement setting bit (SGCR:GID).

Note:

Note that the pulses number specified by this register is "register value + 1".

4.7. Increment Decrement Data Register : SGIDR (SG Increment Decrement Register)

This section explains the bit configuration for the increment decrement data register (SGIDR).

The increment decrement data register (SGIDR) stores an increment and decrement amount for the amplitude data register (SGAR). It increments or decrements the value of the amplitude data register (SGAR) on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register according to the setting of the increment decrement setting bit (SGCR:GID).

■ SGIDR : Address Base_addr + 09_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7 to bit0] D[7:0] (Data) : Increment Decrement Data bits

These bits store increment and decrement amount for the amplitude data register (SGAR). Software sets increment and decrement amount for the amplitude data register (SGAR). Hardware increments or decrements the value stored in the amplitude data register (SGAR) on each counting by the decrement counter of the tone pulses number from the toggle flip-flop specified by the cycle register according to the setting of the increment decrement setting bit (SGCR:GID). When the increment decrement setting bit is set with decrement (SGCR:GID = "0") and the amplitude data register (SGAR) value is "0x0000", no more decrement is performed. When the increment decrement setting is increment (SGCR:GID = 1) and the amplitude data register (SGAR) value is "0xFFFF", no more increment is performed. In addition, when the increment decrement amount data register value is "0x00", increment or decrement is not performed.

4.8. PWM Cycles Number Data Register : SGPCR (SG PWM Cycle Register)

This section explains the bit configuration for the PWM cycles number data register (SGPCR).

The PWM cycles number data register (SGPCR) stores the cycles number of 1PWM cycle.

■ SGPCR : Address Base_addr + 0A_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	D[15:8]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D[7:0]							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit0] D[15:0] (Data) : PWM cycles number data bits

These bits store the cycles number of 1PWM cycle. The reference clock cycle is the input clock (prescaler).

Note:

Note that the clock cycles number specified by this register is "register value + 1".

4.9. DMA Transfer Indirect Register : SGDMAR (SG DMA Register)

This section explains the bit configuration for the DMA transfer indirect register (SGDMAR).

The DMA transfer indirect register (SGDMAR) is used for DMA transfer for the amplitude data register (SGAR), frequency data register (SGFR), tone outputs number register (SGNR), cycle register (SGTCR), increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR). The read value is always "0". To read the value written to this register, read the relevant register of the PWM cycles number data register (SGPCR) from the amplitude data register (SGAR).

This register must be accessed with 1/2/4 bytes according to the setting of the DMA transfer update enable register (SGDER). The access location is fixed to bit31 to bit24 for 1-byte access and bit31 to bit16 for 2-byte access.

When the operation enable (SGCR:ST = 1) is set while the DMA transfer start interrupt set is enabled (SGCR:DMA = 1), if sound is output only the number of times specified by the cycle register (SGTCR) and tone outputs number register (SGNR), the sound generator sets the interrupt bit (SGCR:INT) and asserts the interrupt signal (PIRQ).

When receiving an interrupt from the sound generator, the DMA controller performs the DMA transfer for this register. In addition, for the DMA controller, fix this register to the transfer destination address.

The sound generator writes the data written to this register to the amplitude data register (SGAR), frequency data register (SGFR), tone outputs number register, cycle register (SGTCR), increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR) according to the setting of the DMA transfer update enable register (SGDER).

■ SGDMAR : Address Base_addr + 0C_H (Access: Byte, Half-word, Word)

	bit31	bit30	-	-	-	bit2	bit1	bit0
	D[31:0]							
Initial value	0	0	-	-	-	0	0	0
Attribute	R0/W	R0/W	-	-	-	R0/W	R0/W	R0/W

[bit31 to bit0] D[31:0] (Data) : DMA transfer data bits

These are registers to be used for DMA transfer for the amplitude data register (SGAR), frequency data register (SGFR), tone outputs number register (SGNR), cycle register (SGTCR), increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR).

The DMA transfer size and transfer number of times must be set according to the setting of the DMA transfer update enable register (SGDER). Bit31 to bit24 are fixed for 1-byte access and bit31 to bit16 are fixed for 2-byte access.

In addition, the number of transfers is either once or twice, and the data transferred to this register in a single transfer must be all or a part of the "amplitude data, frequency data, and tone outputs number" or "cycle, increment decrement amount data, and PWM cycles number data". It is inhibited to transfer the data, which is in the address space from the amplitude data register (SGAR) to the PWM cycles number data register (SGPCR) and whose address exceeds 4-byte boundary, in a single transfer. (Example: The frequency data and increment decrement amount data cannot be transferred in a single transfer. They will be transferred in two transfers.)

Note:

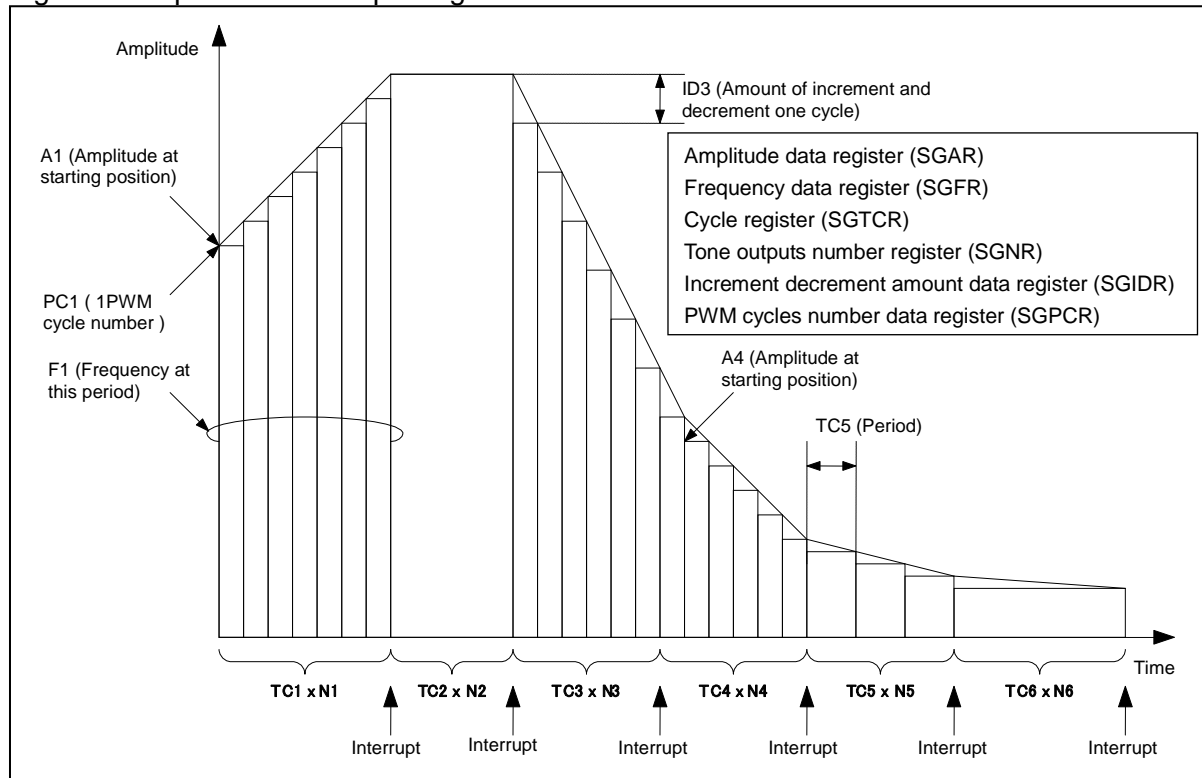
If the number of DMA transfers is more than the transfers count set in the DMA transfer update enable register (SGDER), the value will be updated.

5. Operation

This section explains the operation of the sound generator.

This section explains the operations of the sound generator. The sound generator operation concept diagram is shown below.

Figure 5-1 Operation Concept Diagram for Sound Generator



An amplitude of the output start position is set to the amplitude data register (SGAR), a frequency of the tone pulse signal is set to the frequency data register (SGFR), an output number of the tone pulse signal for one cycle is set to the cycle register (SGTCR), a frequency that generates an interrupt is set to the tone outputs number register (SGNR), the increment or decrement amount for one cycle is set to the increment decrement amount data register (SGIDR), 1PWM cycles number is set to the PWM cycles number data register (SGPCR), and other sound generator control information is set to the sound control register (SGCR).

The sound generator outputs the tone pulse signal and amplitude data with these settings.

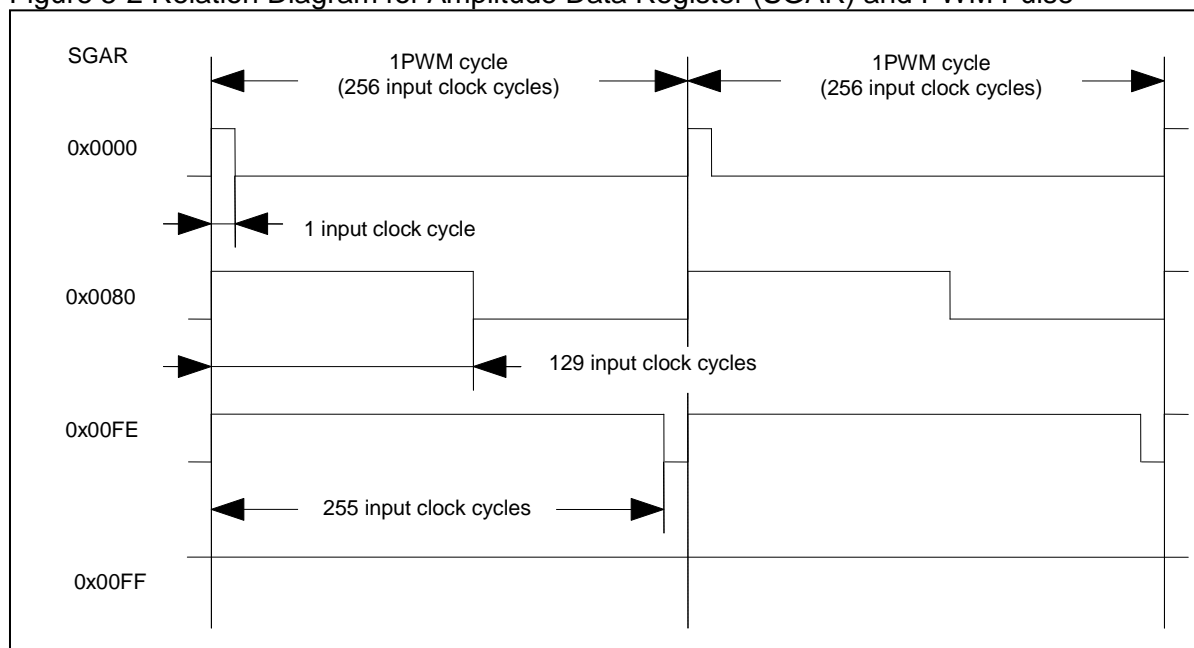
In the operation concept diagram above, the sound generator outputs six types of signals. Various register values such as the amplitude data register are set for output start and each interrupt occurrence.

5.1. Relation of Amplitude Data Register (SGAR) and PWM Pulse

The relation of the amplitude data register (SGAR) and PWM pulse is explained.

The relation of the amplitude data register (SGAR) and PWM pulse is explained. The relation diagram for the amplitude data register (SGAR) and PWM pulse is shown below.

Figure 5-2 Relation Diagram for Amplitude Data Register (SGAR) and PWM Pulse



The amplitude data is output by the SGA pin as PWM (Pulse Width Modulation) pulses.

One PWM cycle is 256 input clock cycles (SGPCR = "0x00FF"), which can be set with the PWM cycles number data register (SGPCR).

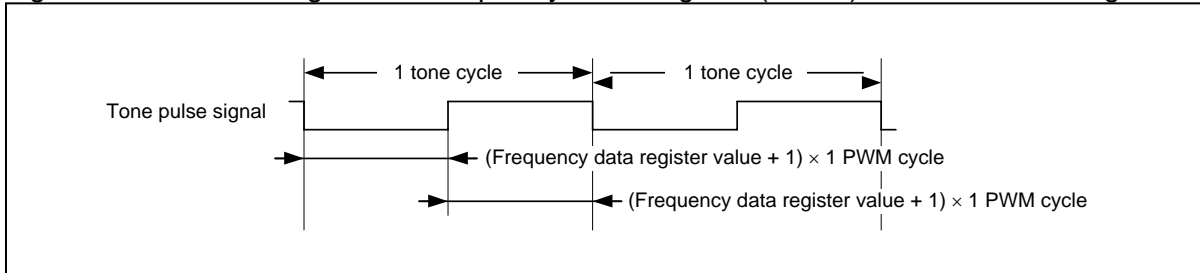
The value "register value + 1" of the amplitude data register (SGAR) is the input clock cycles number for SGA pin = "H" during one PWM cycle. In addition, when the amplitude data register (SGAR) \geq PWM cycles number data register (SGPCR), the SGA pin is always "H".

5.2. Relation of Frequency Data Register (SGFR) and Tone Pulse Signals

The relation of the frequency data register (SGFR) and tone pulse signals is explained.

The relation of the frequency data register (SGFR) and tone pulse signals is explained. The relation diagram for the frequency data register (SGFR) and tone pulse signals is shown below.

Figure 5-3 Relation Diagram for Frequency Data Register (SGFR) and Tone Pulse Signals



Tone pulse signals repeat "L" and "H" with the cycle of " $(\text{Frequency data register value} + 1) \times 1\text{PWM cycle}$ ". They are generated by the toggle flip-flop.

When the tone output bit (TONE) of the sound control register (SGCR) is "0", tone pulse signals are mixed with PWN pulses (logical multiply), and output from the SGO pin. In addition, when the tone output bit (TONE) of the sound control register (SGCR) is "1", tone pulse signals are output from the SGO pin without mixing.

Note:

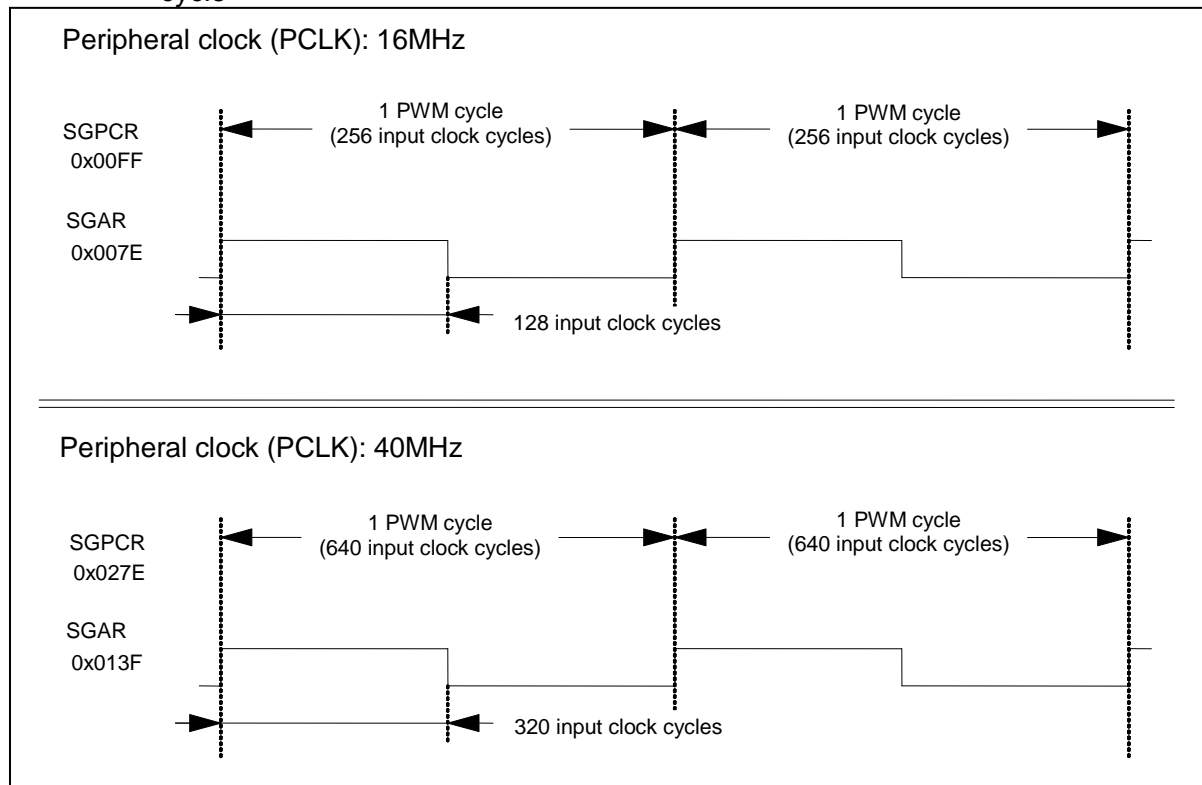
Note that when the register value is changed during operation of the sound generator, 50% of the duty cycle might be changed depending on the change timing.

5.3. Relation of PWM Cycles Number Data Register (SGPCR) and PWM cycle

The relation of the PWM cycles number data register (SGPCR) and the PWM cycle is explained.

The relation of the PWM cycles number data register (SGPCR) and the PWM cycle is explained. The relation diagram for the PWM cycles number data register (SGPCR) and the PWM cycle is shown below.

Figure 5-4 Relation Diagram for PWM Cycles Number Data Register (SGPCR) and PWM cycle



The PWM cycle can be set with the PWM cycles number data register (SGPCR).

"Register value + 1" of the PWM cycles number data register (SGPCR) is the input clock cycles number for one PWM cycle. The input clock is the division of the frequency of the peripheral clock (PCLK).

The PWM cycle is a reference cycle for the tone pulse signals (or mixed signals of tone pulse signals with the PWM pulse signals) and PWM pulse signals.

You can make the sound output for a peripheral clock (PCLK) of 16 MHz equal to the sound output for a peripheral clock of 40 MHz by changing the PWM cycles number data register (SGPCR) value and the amplitude data register (SGAR) value. This can be realized by making the ratio of the register values above 1:2.5 since the ratio of 16 MHz and 40 MHz for the peripheral clock (PCLK) is 1:2.5.

5.4. Relation of DMA Transfer Update Enable Register (SGDER) and DMA Transfers Count/DMA Transfer Size/Transfer Byte Location

The relation of the DMA transfer update enable register (SGDER) and the DMA transfers count/DMA transfer size/Transfer byte location is explained.

The relation of the DMA transfer update enable register (SGDER) and the DMA transfers count/DMA transfer size/transfer byte location is explained.

5.4.1. DMA Transfers Count

The DMA transfers count is explained below.

Whether the DMA transfer is $n \text{ byte} \times \text{once}$ or $n \text{ byte} \times \text{twice}$ depends on the setting of the DMA transfer update enable register (SGDER).

When all of SGDER:ARE1, SGER:ARE0, SGDER:FRE, and SGDER:NRE are "0", or, all of SGDER:TCRE, SGDER:IDRE, SGDER:PCRE1, and SGDER:PCRE0 are "0", the DMA transfers count is once. For other than that, the DMA transfers count is twice.

5.4.2. DMA Transfer Size

The DMA transfer size is explained below.

Whether the DMA transfer size is 1 byte, 2 bytes, or 4 bytes depends on the setting of the DMA transfer update enable register (SGDER). In addition, the DMA transfer size is larger one of the setting value of SGDER:ARE1, SGER:ARE0, SGDER:FRE, and SGDER:NRE and the setting value of SGDER:TCRE, SGDER:IDRE, SGDER:PCRE1, and SGDER:PCRE0. Furthermore, transfer for 3 bytes or more is assumed as 4 bytes.

5.4.3. Transfer Byte Location for DMA Transfer Indirect Register

The transfer byte location for the DMA transfer indirect register is explained below.

The transfer byte location for the DMA transfer indirect register (SGDMAR) is decided by the DMA transfer update enable register (SGDER) setting and DMA transfer size.

When the DMA transfer size for one transfer to the DMA transfer indirect register (SGDMAR) is less than 4 bytes, the transfer byte location is left-aligned. (Also when the DMA transfer size for one transfer is 3 bytes, the location is left-aligned.)

The relation of the DMA transfer update enable register (SGDER) and the transfer byte location of the amplitude data (SGAR[15:0]), frequency data (SGFR[7:0]), and tone outputs number (SGNR[7:0]) for the DMA transfer indirect register (SGDMAR) is shown below. When the transfer size #1 for the DMA transfer indirect register (SGDMAR) calculated from SGDER:ARE1, SGDER:ARE0, SGDER:FRE, and SGDER:NRE of the DMA transfer update enable register (SGDER) is 2 bytes or less, the transfer byte location is left-aligned.

Table 5-1 DMA Transfer Update Enable Register (SGDER) and Transfer Byte Location for SGDMAR #1

	SGDER setting				Transfer size #1 *1	Transfer byte location for SGDMAR			
	ARE1	ARE0	FRE	NRE		SGAR [15:8]	SGAR [7:0]	SGFR [7:0]	SGNR [7:0]
1	0	0	0	0	0	-	-	-	-
2	1	0	0	0	1	SGDMAR [31:24]	-	-	-
3	0	1	0	0	1	-	SGDMAR [31:24]	-	-
4	1	1	0	0	2	SGDMAR [31:24]	SGDMAR [23:16]	-	-
5	0	0	1	0	1	-	-	SGDMAR [31:24]	-
6	1	0	1	0	2	SGDMAR [31:24]	-	SGDMAR [23:16]	-
7	0	1	1	0	2	-	SGDMAR [31:24]	SGDMAR [23:16]	-
8	1	1	1	0	4	SGDMAR [31:24]	SGDMAR [23:16]	SGDMAR [15:8]	-
9	0	0	0	1	1	-	-	-	SGDMAR [31:24]
10	1	0	0	1	2	SGDMAR [31:24]	-	-	SGDMAR [23:16]
11	0	1	0	1	2	-	SGDMAR [31:24]	-	SGDMAR [23:16]

	SGDER setting				Transfer size #1 *1	Transfer byte location for SGDMAR			
	ARE1	ARE0	FRE	NRE		SGAR [15:8]	SGAR [7:0]	SGFR [7:0]	SGNR [7:0]
12	1	1	0	1	4	SGDMAR [31:24]	SGDMAR [23:16]	-	SGDMAR [15:8]
13	0	0	1	1	2	-	-	SGDMAR [31:24]	SGDMAR [23:16]
14	1	0	1	1	4	SGDMAR [31:24]	-	SGDMAR [23:16]	SGDMAR [15:8]
15	0	1	1	1	4	-	SGDMAR [31:24]	SGDMAR [23:16]	SGDMAR [15:8]
16	1	1	1	1	4	SGDMAR [31:24]	SGDMAR [23:16]	SGDMAR [15:8]	SGDMAR [7:0]

*1: Transfer size calculated from {SGDER:ARE1, SGER:ARE0, SGDER:FRE, SGDER:NRE}

X, - : Don't Care

The relation of the DMA transfer update enable register (SGDER) and the transfer byte location of the cycle (SGTCR[7:0]), increment decrement amount data (SGFR[7:0]), and PWM cycles number data (SGPCR[15:0]) for the DMA transfer indirect register (SGDMAR) is shown below. When the transfer size #2 for the DMA transfer indirect register (SGDMAR) calculated from SGDER:TCRE, SGDER:IDRE, SGDER:PCRE1, and SGDER:PCRE0 of the DMA transfer update enable register (SGDER) is 2 bytes or less, the transfer byte location is left-aligned.

Table 5-2 DMA Transfer Update Enable Register (SGDER) and Transfer Byte Location for SGDMAR #2

No.	SGDER setting				Transfer size #1 *1	Transfer byte location for SGDMAR			
	TCRE	IDRE	PCRE1	PCRE0		SGTCR [15:8]	SGIDR [7:0]	SGPCR [7:0]	SGPCR [7:0]
1	0	0	0	0	0	-	-	-	-
2	1	0	0	0	1	SGDMAR [31:24]	-	-	-
3	0	1	0	0	1	-	SGDMAR [31:24]	-	-
4	1	1	0	0	2	SGDMAR [31:24]	SGDMAR [23:16]	-	-
5	0	0	1	0	1	-	-	SGDMAR [31:24]	-
6	1	0	1	0	2	SGDMAR [31:24]	-	SGDMAR [23:16]	-
7	0	1	1	0	2	-	SGDMAR [31:24]	SGDMAR [23:16]	-
8	1	1	1	0	4	SGDMAR [31:24]	SGDMAR [23:16]	SGDMAR [15:8]	-

No.	SGDER setting				Transfer size #1 *1	Transfer byte location for SGDMAR			
	TCRE	IDRE	PCRE1	PCRE0		SGTCR [15:8]	SGIDR [7:0]	SGPCR [7:0]	SGPCR [7:0]
9	0	0	0	1	1	-	-	-	SGDMAR [31:24]
10	1	0	0	1	2	SGDMAR [31:24]	-	-	SGDMAR [23:16]
11	0	1	0	1	2	-	SGDMAR [31:24]	-	SGDMAR [23:16]
12	1	1	0	1	4	SGDMAR [31:24]	SGDMAR [23:16]	-	SGDMAR [15:8]
13	0	0	1	1	2	-	-	SGDMAR [31:24]	SGDMAR [23:16]
14	1	0	1	1	4	SGDMAR [31:24]	-	SGDMAR [23:16]	SGDMAR [15:8]
15	0	1	1	1	4	-	SGDMAR [31:24]	SGDMAR [23:16]	SGDMAR [15:8]
16	1	1	1	1	4	SGDMAR [31:24]	SGDMAR [23:16]	SGDMAR [15:8]	SGDMAR [7:0]

*1: Transfer size calculated from {SGDER:TCRE, SGDER:IDRE, SGDER:PCRE1, SGDER:PCRE0}

X: Don't Care

5.4.4. DMA Transfer Image

The DMA transfer image is shown below.

DMA transfer update enable register (SGDER) setting:

{SGDER:ARE1, SGER:ARE0, SGDER:FRE, SGDER:NRE} = 1001
{SGDER:TCRE, SGDER:IDRE, SGDER:PCRE1, SGDER:PCRE0} = 0100

An example with the setting above is described below:

DMA transfers count: Twice

DMA transfer size: 2 bytes

Transfer byte location for DMA transfer indirect register:

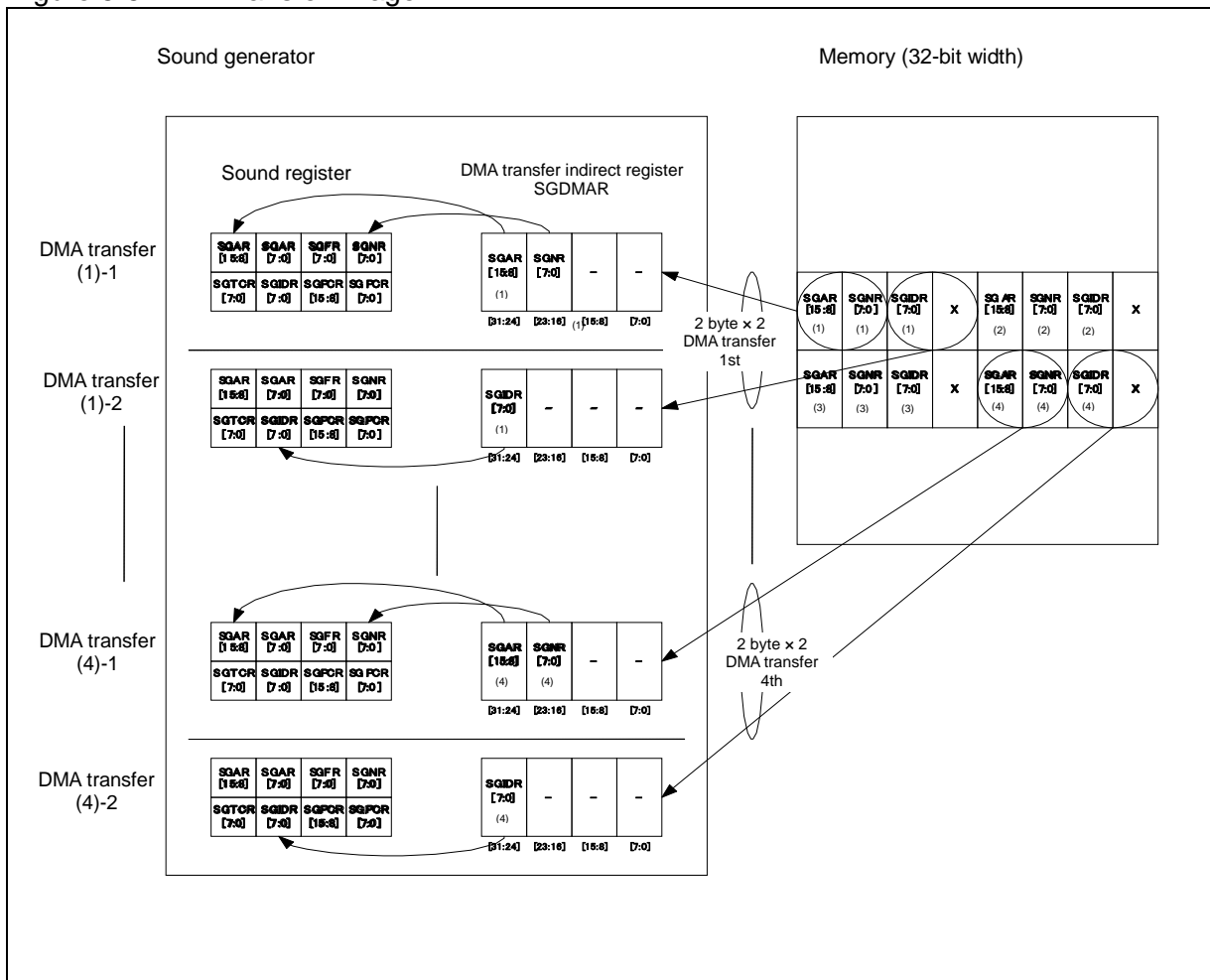
First

SGDMAR[31:24] ← Amplitude data (upper byte) / SGAR[15:8]
SGDMAR[23:16] ← Tone outputs number / SGNR[7:0]
SGDMAR[15:0] ← Don't care

Second

SGDMAR[31:24] ← Increment decrement amount data / SGIDR[7:0]
SGDMAR[23:0] ← Don't care

Figure 5-5 DMA Transfer Image

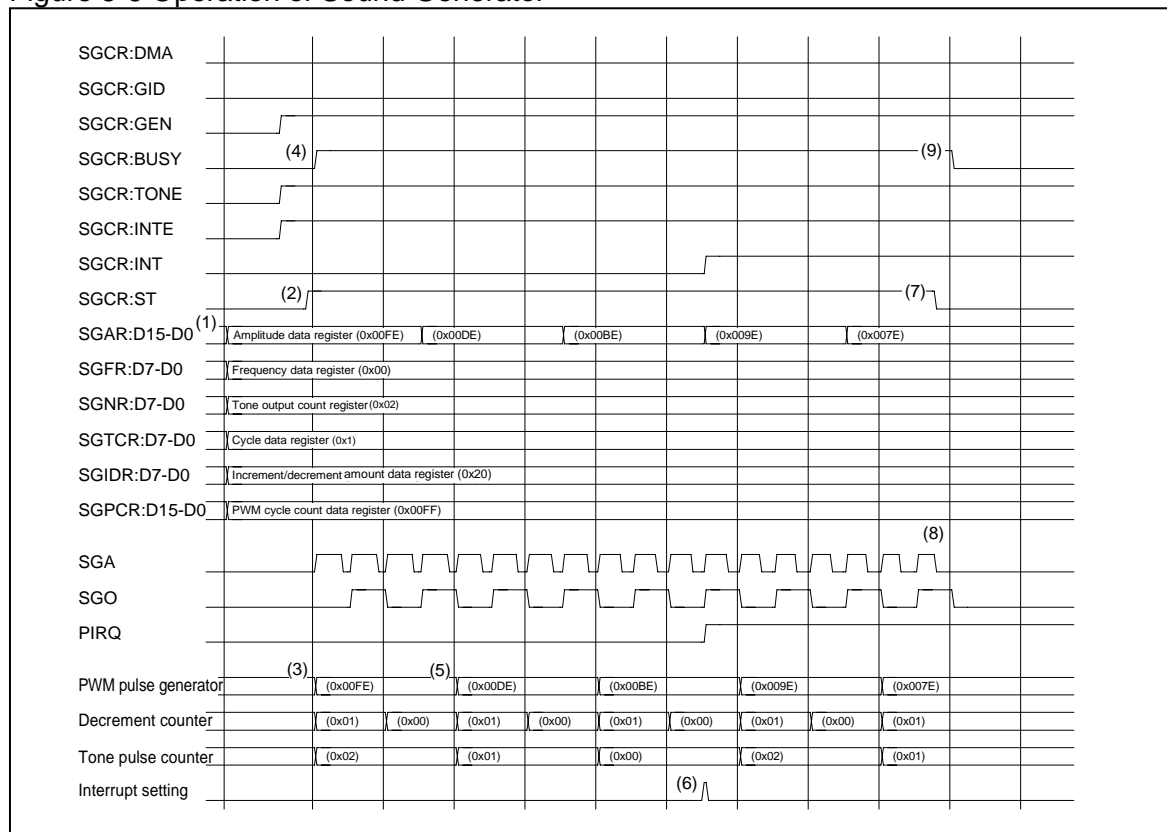


5.5. Operation of Sound Generator

The operation of the sound generator is shown below.

This section explains the operations of the sound generator. The sound generator operation is shown below.

Figure 5-6 Operation of Sound Generator



- (1) With software, write the reload value to the amplitude data register (SGAR), frequency data register (SGFR), tone outputs number register (SGNR), and cycle register (SGTCR), the amplitude increment or decrement amount to the increment decrement amount data register (SGIDR), and the 1PWM cycles number to the PWM cycles number data register (SGPCR). In addition, set other sound generator control information to the sound control register (SGCR). Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
- (2) Set the start bit (SGCR:ST) to "1".
- (3) By setting of the start bit (SGCR:ST) to "1", the amplitude data register (SGAR) value is loaded to the PWM generator, the frequency data register (SGFR) value is loaded to the frequency counter, the tone outputs number register (SGNR) value is loaded to the tone pulse counter, and the cycle register (SGTCR) value is loaded to the decrement counter.
- (4) The operation flag (SGCR:BUSY) is turned to "1".
- (5) By counting of the tone pulses number until the reload value by the decrement counter, the amplitude data register (SGAR) value increments or decrements according to the automatic increment decrement enable bit (SGCR:GEN) and the increment decrement setting bit (SGCR:GID).
- (6) When the tone pulses number specified with the tone outputs number register (SGNR) and the cycle register (SGTCR) is counted by the tone pulse counter (the timing of the tone pulse counter = "0x00", the decrement counter = "0x00", and SGO = "L" → "H"), an interrupt set request is generated, the interrupt bit (SGCR:INT) is set, and an interrupt (PIRQ) is generated.
- (7) Set the start bit (SGCR:ST) to "0". The operation is continued until the busy bit (SGCR:BUSY) is turned to "0".
- (8) The operation of the sound generator is stopped after completion of the current tone cycle.

(9) The operation flag (SGCR:BUSY) is turned to "0".

■ DMA Transfer Start Interrupt Set Enable Bit

The assert condition for the first interrupt after the start instruction by the CPU differs according to the setting of the DMA transfer start interrupt set enable bit.

- Normal mode : When the sound generator outputs the tone pulses number set in the cycle register (SGTCR)
- DMA mode : Immediately after the start instruction (DMA transfer request)

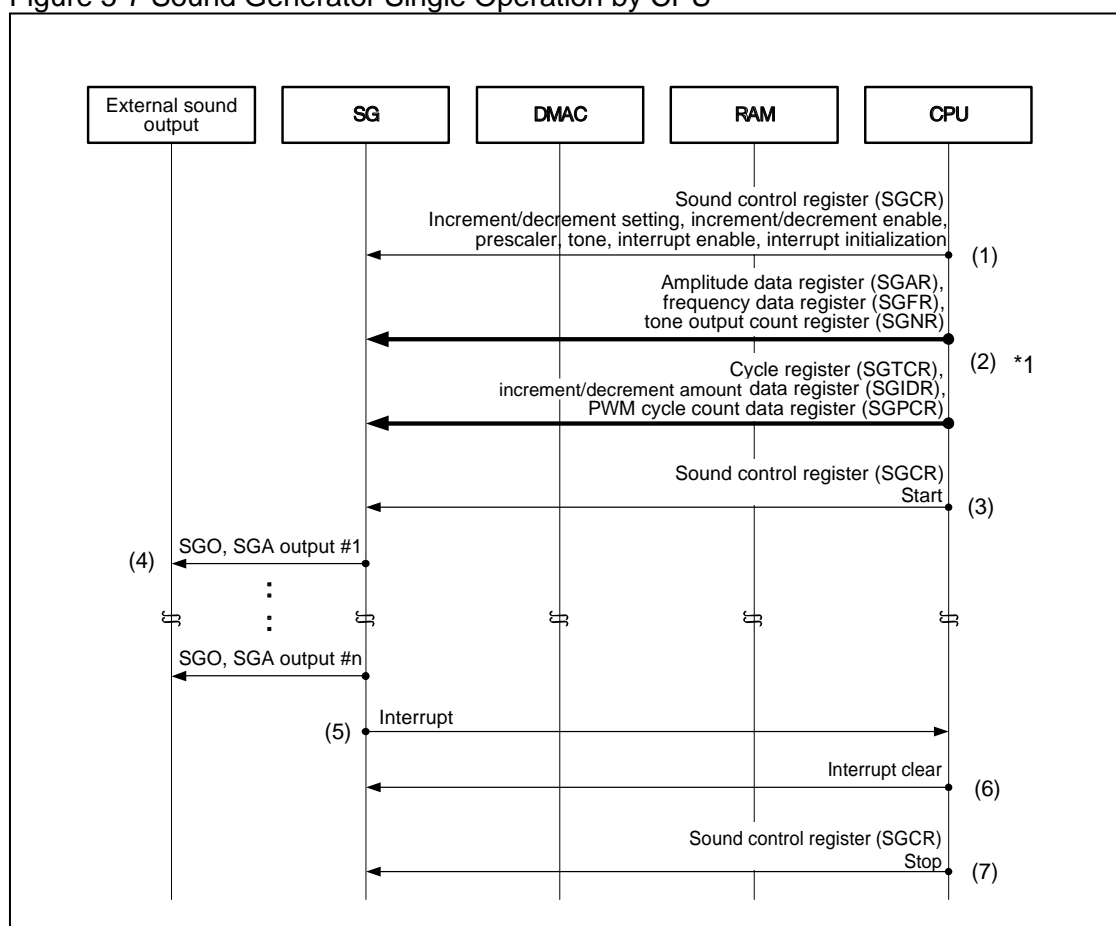
■ DMA Transfer

The setting of SGAR, SGFR, SGNR, SGTCR, SGIDR, and SGPCR is performed through the DMA transfer indirect register (SGDMAR).

■ Sound Generator Single Operation by CPU

The flow of the sound generator single operation by the CPU is shown below.

Figure 5-7 Sound Generator Single Operation by CPU



- (1) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
- (2) With software, set "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)."(*1: In addition, setting to all registers is not mandatory.)
- (3) Set the start bit (SGCR:ST) to "1".
- (4) The sound generator SGO and SGA output is started.
- (5) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
- (6) The CPU clears the interrupt.
- (7) The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.

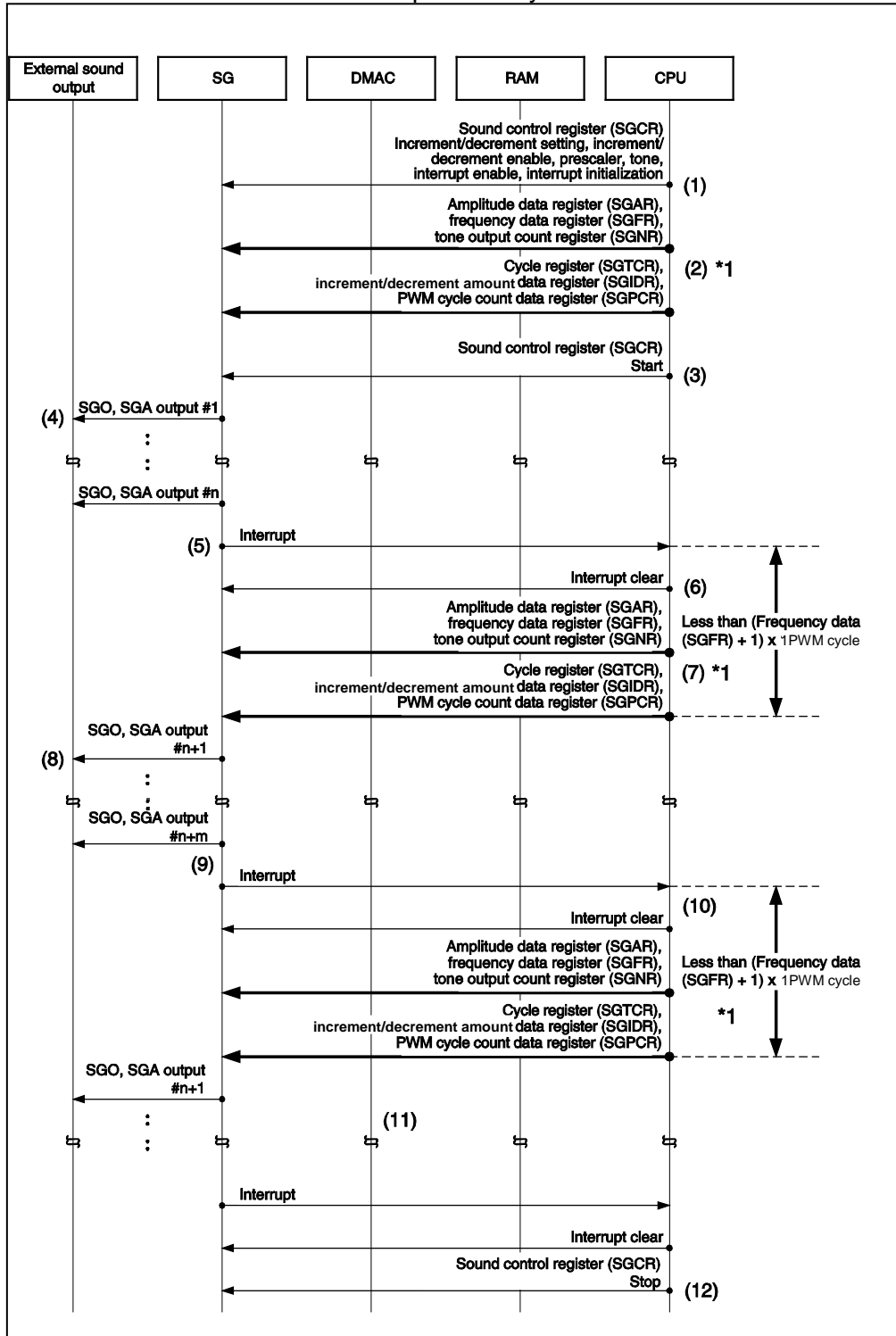
5.6. Sound Generator Continuous Operation by CPU

The sound generator continuous operation by CPU is shown below.

The flow of the sound generator continuous operation by the CPU is shown below.

(7) and later steps differ from the flow of the sound generator single operation by CPU.

Figure 5-8 Sound Generator Continuous Operation by CPU



(1) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).

- (2) With software, set "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)."(*1: In addition, setting to all registers is not mandatory.)
- (3) Set the start bit (SGCR:ST) to "1".
- (4) The sound generator SGO and SGA output is started.
- (5) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
- (6) The CPU clears the interrupt.
- (7) With software, set "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)."(*1: In addition, setting to all registers is not mandatory.)
- (8) Perform the SGO and SGA output of the sound generator with the setting values.
- (9) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
- (10)The CPU clears the interrupt.
- (11)From here, (7) through (11) is repeated.
- (12)The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.

Note:

Until the sound generator notifies of the interrupt and necessary settings are performed like Step (5) to (7), operations must be completed within $(\text{frequency data (SGFR)} + 1) \times 1\text{PWM cycle}$.

Note:

When the increment decrement setting is changed, the increment decrement setting bit (SGCR:GID) and automatic increment decrement enable bit (SGCR:GEN) of the sound control register (SGCR) must be changed within the cycle above.

5.7. Sound Generator Operation Coordinated with DMA

The sound generator operation coordinated with DMA is shown below.

The flow of the sound generator operation coordinated with DMA is shown.

DMAC performs setting of the data register for sound. The first interrupt assert differs from the flow of the sound generator operation by the CPU. In addition, the data register for sound is transferred through the DMA transfer indirect register (SGDMAR).

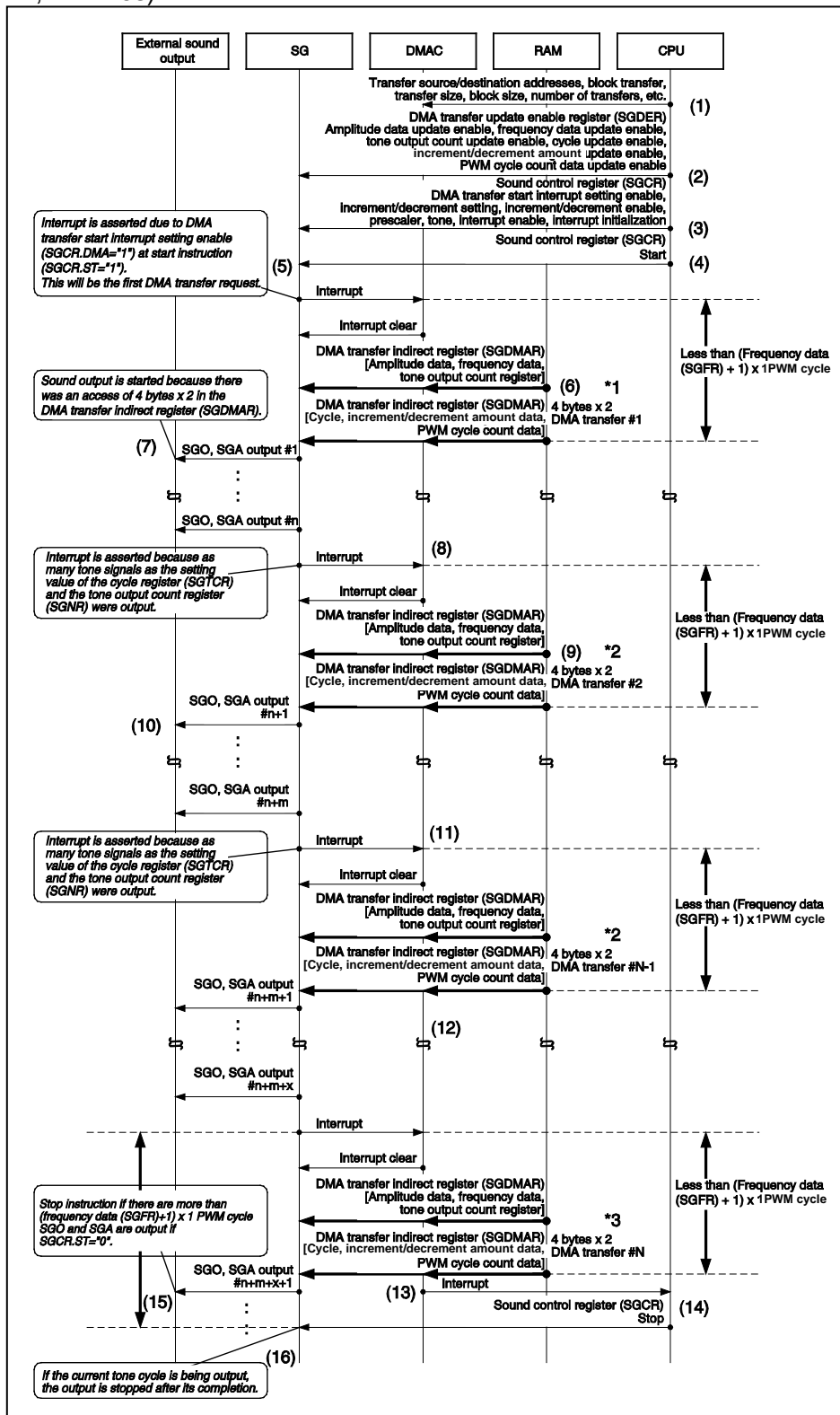
Note:

To make an interrupt signal a DMA transfer request, the interrupt enable (SGCR:INTE = 1) must be set with software.

5.8. When DMA Transfer of 4 Bytes × 2 Is Performed N Times

N times transfer of the data (4 bytes x2) is shown.

Figure 5-9 Sound Generator Operation Coordinated with DMA (For DMA Transfer of 4 Bytes × 2, N Times)



- (1) By software, set the configuration of DMAC required for DMA transfer. In addition, for the DMA transfer, perform a block transfer of 4 bytes × 2 N times. Transfer data of "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)" through the DMA transfer indirect register (SGDMAR). In addition, the setting of the transfer destination address for DMAC is fixed (address of the DMA transfer indirect register).

- (2) By software, set up "DMA transfer update enable register (SGDER)" for the registers that should be transferred and updated. Here, set to update all registers of "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)."
- (3) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. In addition, set "DMA transfer start interrupt enable bit" to enable. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
- (4) Set the start bit (SGCR:ST) to "1".
- (5) Due to the start instruction (SGCR:ST = 1) and DMA transfer start interrupt set enable setting (SGCR:DMA = 1), the interrupt bit (SGCR:INT) is set and the interrupt (PIRQ) is generated. This is used as a DMA transfer request.
- (6) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), with the first transfer, the values of the amplitude data register (SGAR), frequency data register (SGFR), and tone outputs number register (SGNR) are transferred, and with the second transfer, the values of the cycle register (SGTCR), increment decrement amount data register (SGDR), and PWM cycles number data register (SGPCR) are transferred. (*1: The block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
- (7) Since the block transfer of 4 bytes \times 2 was performed for the DMA transfer indirect register (SGDMAR), the SGO and SGA output of the sound generator is started.
- (8) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
- (9) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*2: For the second DMA transfer and later also, the block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
- (10) Sound is output with the data transferred with DMA.
- (11) When the DMAC completes DMA transfer for the number of times specified, it notifies the CPU of an interrupt.
- (12) Hereafter, the same operation is continued.
- (13) Since the DMAC completes DMA transfer for specified number of times (transfer of 4 bytes \times 2 N times), an interrupt is generated for the CPU.
- (14) The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.
- (15) When the stop instruction (SGCR:ST = 0) is sent within (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data are not output. (*3: The Nth transfer data is written to the register for sound, but sound is not output. The Nth transfer is to generate an interrupt for the CPU from the DMAC.)
- (16) When the stop instruction (SGCR:ST = 0) is sent after (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data stop output after the current tone cycle is completed. (*3: The Nth transfer data is output with sound.)

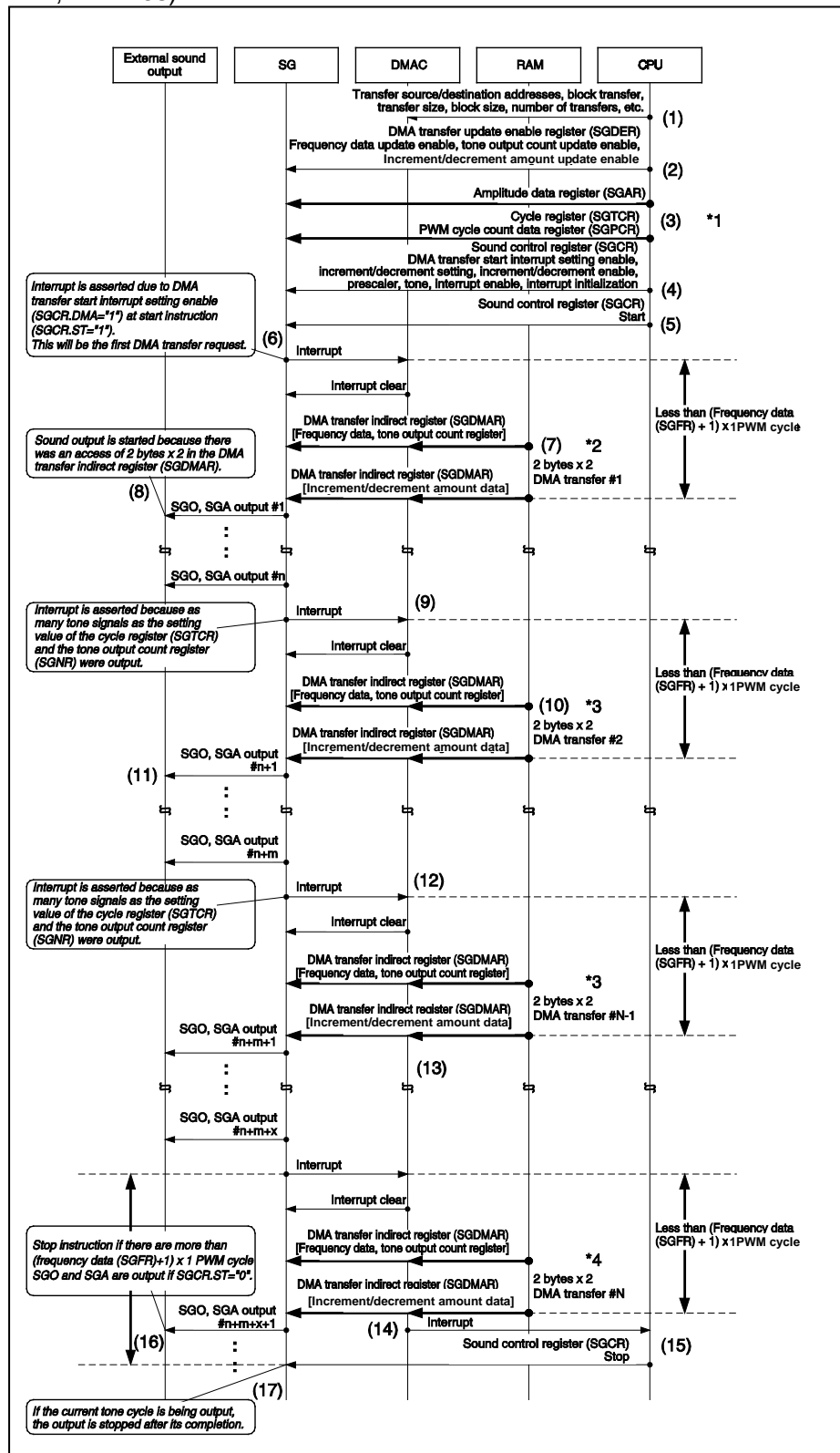
Note:

Until the sound generator notifies of the interrupt and the DMA transfer is completed like Step (5) to (6), operations must be completed within (frequency data (SGFR) + 1) \times 1PWM cycle.

5.8.1. When DMA Transfer of 2 Bytes × 2 Is Performed N Times

N times transfer of the data (2 bytes x2) is shown.

Figure 5-10 Sound Generator Operation Coordinated with DMA (For DMA Transfer of 2 Bytes × 2, N Times)



(1) By software, set the configuration of DMAC required for DMA transfer. In addition, for the DMA transfer, perform a block transfer of 2 bytes × 2 N times. Through the DMA transfer indirect register (SGDMAR), transfer data of "Frequency data register (SGFR) and Tone outputs number register (SGNR)" and "Increment decrement amount data register (SGIDR)". In addition, the setting of the transfer destination address for DMAC is fixed (address of the DMA transfer indirect register).

- (2) By software, set up "DMA transfer update enable register (SGDER)" for the registers that should be transferred and updated. Here, set to update "Frequency data register (SGFR) and Tone outputs number register (SGNR)" and "Increment decrement amount data register (SGIDR)".
- (3) With software, set "Amplitude data register (SGAR)" and "Cycle register (SGTCR) and PWM cycles number data register (SGPCR)" of the sound generator. (*1: Set registers that are not updated with the DMA transfer.)
- (4) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. In addition, set "DMA transfer start interrupt enable bit" to enable. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
- (5) Set the start bit (SGCR.ST) to "1".
- (6) Due to the start instruction (SGCR:ST = 1) and DMA transfer start interrupt set enable setting (SGCR:DMA = 1), the interrupt bit (SGCR:INT) is set and the interrupt (PIRQ) is generated. This is used as a DMA transfer request.
- (7) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), with the first transfer, the values of the frequency data register (SGFR) and tone outputs number register (SGNR) are transferred, and with the second transfer, the value of the increment decrement amount data register (SGDR) is transferred. (*2: The block transfer of 2 bytes \times 2 to the DMA transfer indirect register is mandatory.)
- (8) Since the block transfer of 2 bytes \times 2 was performed for the DMA transfer indirect register (SGDMAR), the SGO and SGA output of the sound generator is started.
- (9) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
- (10) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*3: For the second DMA transfer and later also, the block transfer of 2 bytes \times 2 to the DMA transfer indirect register is mandatory.)
- (11) Sound is output with the data transferred with DMA.
- (12) When the DMAC completes DMA transfer for the number of times specified, it notifies the CPU of an interrupt.
- (13) Hereafter, the same operation is continued.
- (14) Since the DMAC completes DMA transfer for specified number of times (transfer of 2 bytes \times 2 N times), an interrupt is generated for the CPU.
- (15) The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.
- (16) When the stop instruction (SGCR:ST = 0) is sent within (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data are not output. (*4: The Nth transfer data is written to the register for sound, but sound is not output. The Nth transfer is to generate an interrupt for the CPU from the DMAC.)
- (17) When the stop instruction (SGCR:ST = 0) is sent after (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data stop output after the current tone cycle is completed. (*4: The Nth transfer data is output with sound.)

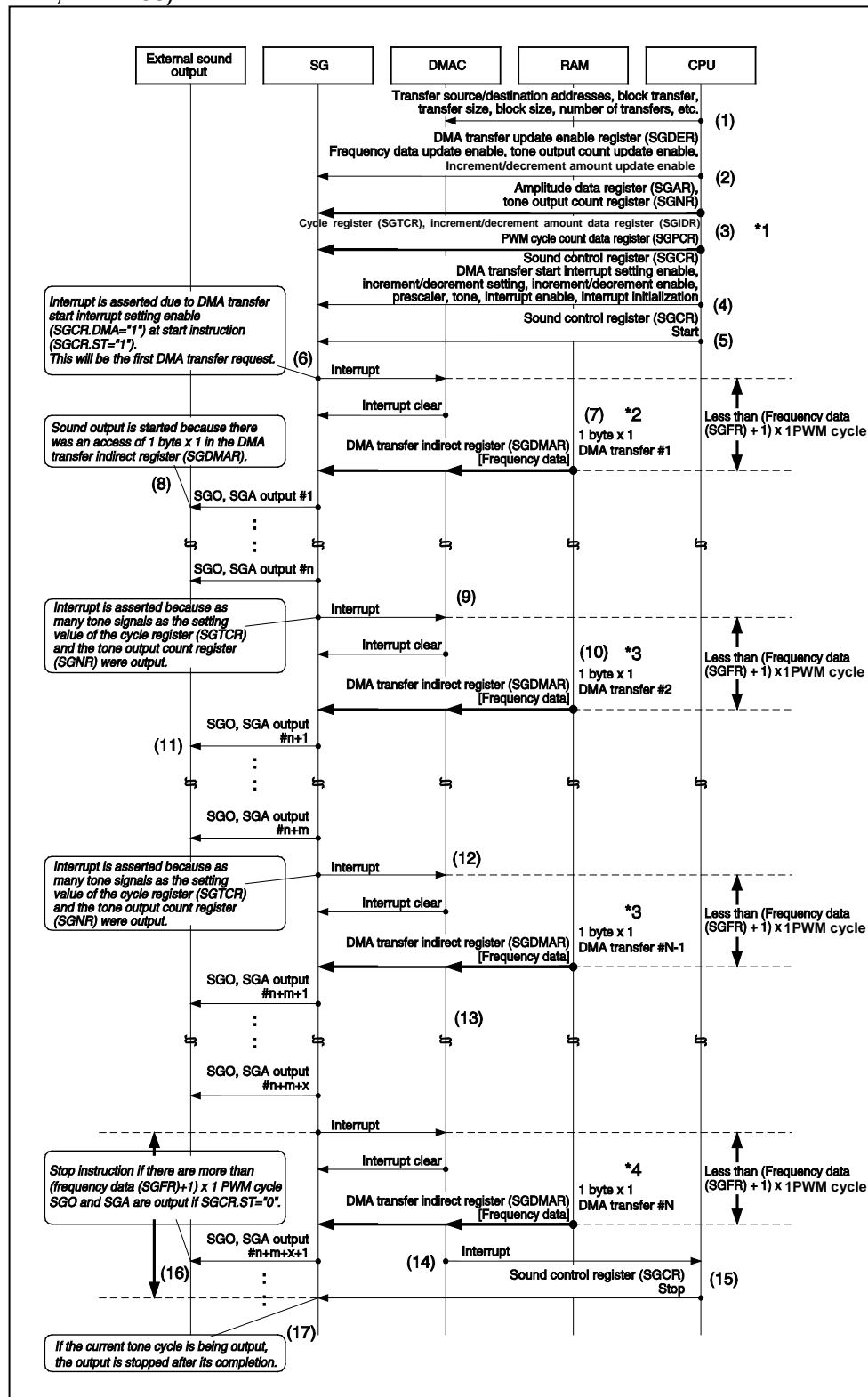
Note:

Until the sound generator notifies of the interrupt and the DMA transfer is completed like Step (6) to (7), operations must be completed within (frequency data (SGFR) + 1) \times 1PWM cycle.

5.8.2. When DMA Transfer of 1 Byte × 1 Is Performed N Times

N times transfer of the data (1 byte x1) is shown.

Figure 5-11 Sound Generator Operation Coordinated with DMA (For DMA Transfer of 1 Byte × 1, N Times)



- (1) By software, set the configuration of DMAC required for DMA transfer. In addition, for the DMA transfer, perform a block transfer of 1 byte × 1 N times. Through the DMA transfer indirect register (SGDMAR), transfer data of "Frequency data register (SGFR)." In addition, the setting of the transfer destination address for DMAC is fixed (address of the DMA transfer indirect register).
- (2) By software, set up "DMA transfer update enable register(SGDER)" for the registers that should be transferred and updated to the DMA transfer update enable register (SGDER) of the sound generator. Here, set to update "Frequency data register (SGFR)."

- (3) With software, set "Amplitude data register (SGAR) and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)" of the sound generator. (*1: Set registers that are not updated with the DMA transfer.)
- (4) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. In addition, set "DMA transfer start interrupt enable bit" to enable. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
- (5) Set the start bit (SGCR:ST) to "1".
- (6) Due to the start instruction (SGCR:ST = 1) and DMA transfer start interrupt set enable setting (SGCR:DMA = 1), the interrupt bit (SGCR:INT) is set and the interrupt (PIRQ) is generated. This is used as a DMA transfer request.
- (7) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the value of the frequency data register (SGFR) is transferred. (*2: The block transfer of 1 byte \times 1 to the DMA transfer indirect register is mandatory.)
- (8) Since the block transfer of 1 byte \times 1 was performed for the DMA transfer indirect register (SGDMAR), the SGO and SGA output of the sound generator is started.
- (9) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
- (10) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*3: For the second DMA transfer and later also, the block transfer of 1 byte \times 1 to the DMA transfer indirect register is mandatory.)
- (11) Sound is output with the data transferred with DMA.
- (12) When the DMAC completes DMA transfer for the number of times specified, it notifies the CPU of an interrupt.
- (13) Hereafter, the same operation is continued.
- (14) Since the DMAC completes DMA transfer for specified number of times (transfer of 1 byte \times 1 N times), an interrupt is generated for the CPU.
- (15) The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.
- (16) When the stop instruction (SGCR:ST = 0) is sent within (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data are not output. (*4: The Nth transfer data is written to the register for sound, but sound is not output. The Nth transfer is to generate an interrupt for the CPU from the DMAC.)
- (17) When the stop instruction (SGCR:ST = 0) is sent after (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data stop output after the current tone cycle is completed. (*4: The Nth transfer data is output with sound.)

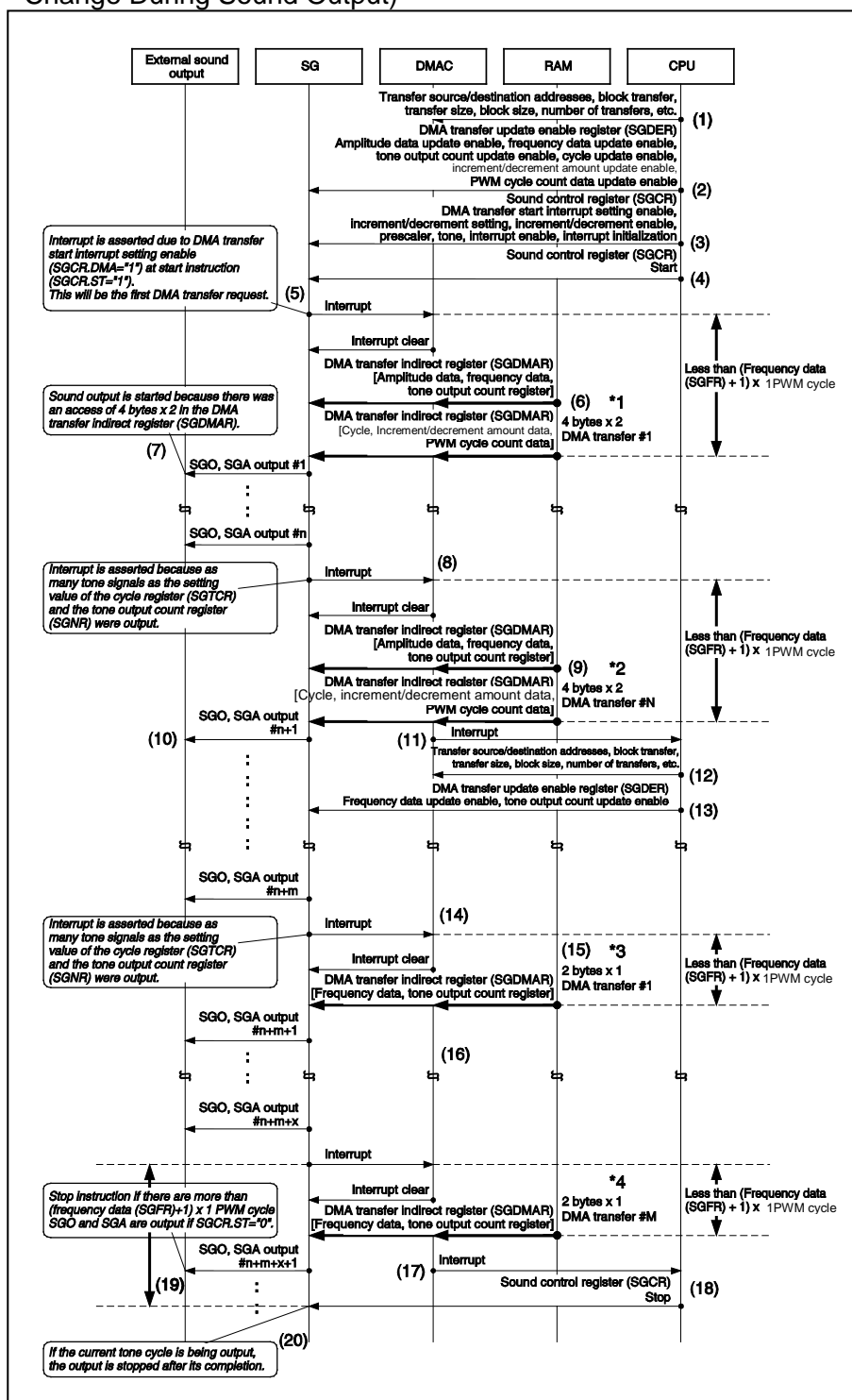
Note:

Until the sound generator notifies of the interrupt and the DMA transfer is completed like Step (6) to (7), operations must be completed within (frequency data (SGFR) + 1) \times 1PWM cycle.

5.8.3. For DMA Transfer of 4 Bytes × 2 N Times and DMA Transfer of 2 Bytes × 1 M Times (Transfer Bytes Number Change During Sound Output)

N times transfer of the data (4 bytes x2) and M times transfer of the data (2 bytes x1) are shown.

Figure 5-12 Sound Generator Operation Coordinated with DMA (Transfer Bytes Number Change During Sound Output)



- (1) By software, set the configuration of DMAC required for DMA transfer. In addition, for the DMA transfer, perform a block transfer of $4 \text{ bytes} \times 2 \text{ N}$ times. Transfer data of "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)" through the DMA transfer indirect register (SGDMAR). In addition, the setting of the transfer destination address for DMAC is fixed (address of the DMA transfer indirect register).
- (2) By software, set up "DMA transfer update enable register (SGDER)" for the registers that should be transferred and updated to the DMA transfer update enable register (SGDER) of the sound generator. Here, set to update all registers of "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register

- (SGIDR), and PWM cycles number data register (SGPCR)."
- (3) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. In addition, set "DMA transfer start interrupt enable bit" to enable. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
 - (4) Set the start bit (SGCR:ST) to "1".
 - (5) Due to the start instruction (SGCR:ST = 1) and DMA transfer start interrupt set enable setting (SGCR:DMA = 1), the interrupt bit (SGCR:INT) is set and the interrupt (PIRQ) is generated. This is used as a DMA transfer request.
 - (6) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), with the first transfer, the values of the amplitude data register (SGAR), frequency data register (SGFR), and tone outputs number register (SGNR) are transferred, and with the second transfer, the values of the cycle register (SGTCR), increment decrement amount data register (SGDR), and PWM cycles number data register (SGPCR) are transferred. (*1: The block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
 - (7) Since the block transfer of 4 bytes \times 2 was performed for the DMA transfer indirect register (SGDMAR), the SGO and SGA output of the sound generator is started.
 - (8) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
 - (9) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*2: For the second DMA transfer and later also, the block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
 - (10) Sound is output with the data transferred with DMA.
 - (11) When the DMAC completes DMA transfer for the number of times specified (transfer of 4 bytes \times 2, N times), it notifies the CPU of an interrupt.
 - (12) Set up DMAC for translation by software. In addition, for the DMA transfer, perform a block transfer of 2 bytes \times 1 M times. Through the DMA transfer indirect register (SGDMAR), transfer data of "Frequency data register (SGFR) and Tone outputs number register (SGNR)."
 - (13) By software, set up "DMA transfer update enable register (SGDER)" for the registers that should be transferred and updated to the DMA transfer update enable register (SGDER) of the sound generator. Here, set to update "Frequency data register (SGFR) and Tone outputs number register (SGNR)."
 - (14) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
 - (15) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*3: The block transfer of 2 bytes \times 1 to the DMA transfer indirect register is mandatory.)
 - (16) Hereafter, the same operation is continued.
 - (17) Since the DMAC completes DMA transfer for specified number of times (transfer of 2 bytes \times 1, M times), an interrupt is generated for the CPU.
 - (18) The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.
 - (19) When the stop instruction (SGCR:ST = 0) is sent within (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data are not output. (*4: The Nth transfer data is written to the register for sound, but sound is not output. The Nth transfer is to generate an interrupt for the CPU from the DMAC.)
 - (20) When the stop instruction (SGCR:ST = 0) is sent after (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data stop output after the current tone cycle is completed. (*4: The Nth transfer data is output with sound.)

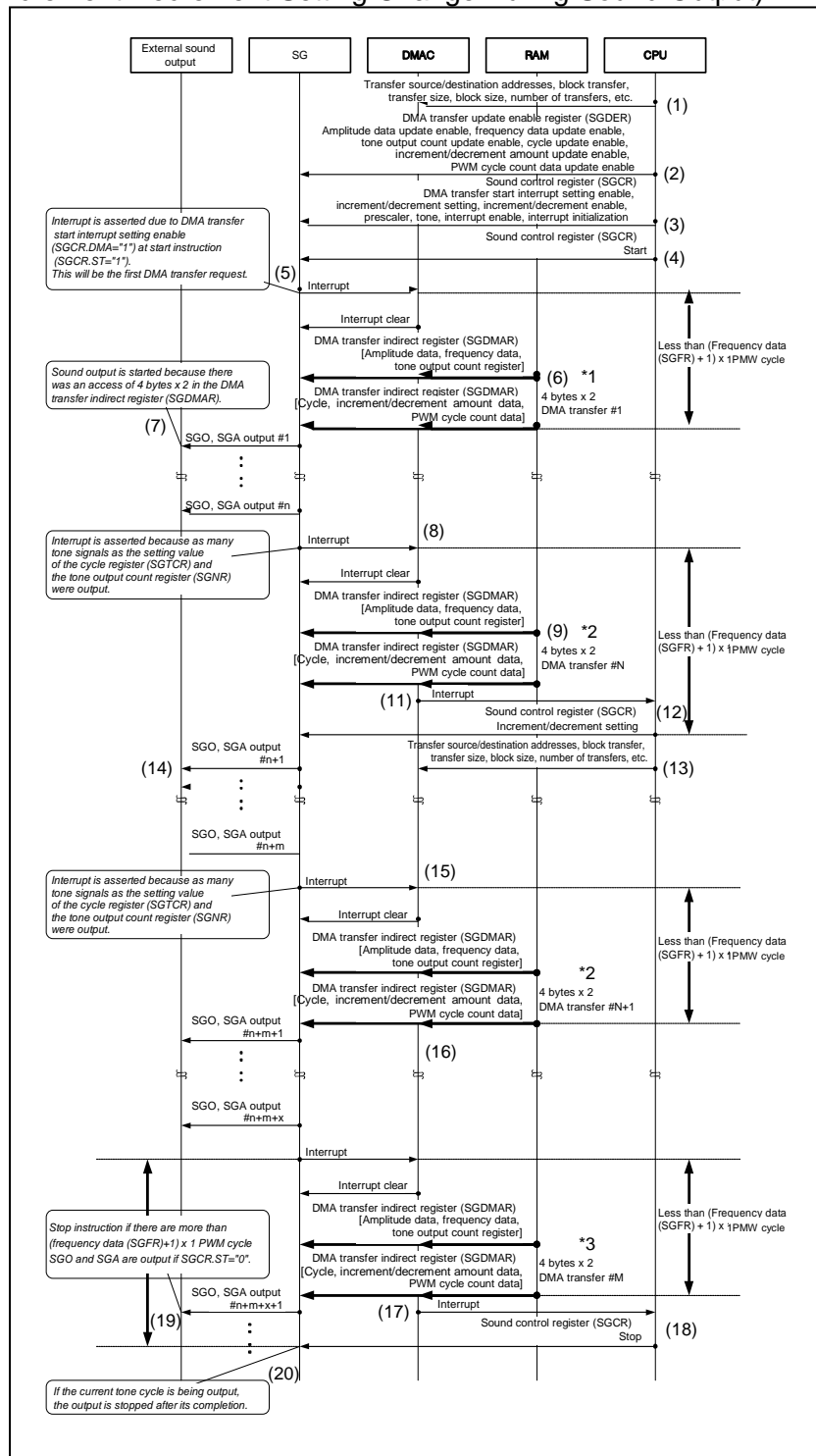
Note:

Until the sound generator notifies of the interrupt and the DMA transfer is completed like Step (5) to (6), operations must be completed within (frequency data (SGFR) + 1) \times 1PWM cycle.

5.8.4. For DMA Transfer of 4 Bytes × 2 N Times and DMA Transfer of 4 Bytes × 2 M Times (Transfer Bytes Number and Increment Decrement Setting Change During Sound Output)

N times transfer of the data (4 bytes x2) and M times transfer of the data (4 bytes x2) are shown.

Figure 5-13 Sound Generator Operation Coordinated with DMA (Transfer Bytes Number and Increment/Decrement Setting Change During Sound Output)



- (1) By software, set the configuration of DMAC required for DMA transfer. In addition, for the DMA transfer, perform a block transfer of 4 bytes × 2 N times. Transfer data of "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register (SGIDR), and PWM cycles number data register (SGPCR)" through the DMA transfer indirect register (SGDMAR). In addition, the setting of the transfer destination address for DMAC is fixed (address of the DMA transfer indirect register).
- (2) By software, set up "DMA transfer update enable register (SGDER)" for the registers that should be transferred and updated to the DMA transfer update enable register (SGDER) of the sound generator. Here, set to update all registers of "Amplitude data register (SGAR), Frequency data register (SGFR), and Tone outputs number register (SGNR)" and "Cycle register (SGTCR), Increment decrement amount data register

- (SGIDR), and PWM cycles number data register (SGPCR)."
- (3) With software, set the sound generator control information into the sound control register (SGCR) of the sound generator. In addition, set "DMA transfer start interrupt enable bit" to enable. Initialize the interrupt bit (SGCR:INT), and set the interrupt enable bit (SGCR:INTE).
 - (4) Set the start bit (SGCR:ST) to "1".
 - (5) Due to the start instruction (SGCR:ST = 1) and DMA transfer start interrupt set enable setting (SGCR:DMA = 1), the interrupt bit (SGCR:INT) is set and the interrupt (PIRQ) is generated. This is used as a DMA transfer request.
 - (6) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), with the first transfer, the values of the amplitude data register (SGAR), frequency data register (SGFR), and tone outputs number register (SGNR) are transferred, and with the second transfer, the values of the cycle register (SGTCR), increment decrement amount data register (SGDR), and PWM cycles number data register (SGPCR) are transferred. (*1: The block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
 - (7) Since the block transfer of 4 bytes \times 2 was performed for the DMA transfer indirect register (SGDMAR), the SGO and SGA output of the sound generator is started.
 - (8) When the sound generator outputs the tone pulses number set in the cycle register (SGTCR) and tone outputs number register (SGNR), an interrupt is generated.
 - (9) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*2: For the second DMA transfer and later also, the block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
 - (10) Sound is output with the data transferred with DMA.
 - (11) When the DMAC completes DMA transfer for the number of times specified (transfer of 4 bytes \times 2, N times), it notifies the CPU of an interrupt.
 - (12) With software, change the increment decrement setting of the sound control register (SGCR).
 - (13) By software, set the configuration of DMAC required for DMA transfer. Here, set the transfer of 4 bytes \times 2 M times.
 - (14) Sound is output with the data transferred with DMA.
 - (15) The DMAC clears the interrupt, and through the DMA transfer indirect register (SGDMAR), the DMA transfer is performed. (*2: The block transfer of 4 bytes \times 2 to the DMA transfer indirect register is mandatory.)
 - (16) Hereafter, the same operation is continued.
 - (17) Since the DMAC completes DMA transfer for specified number of times (transfer of 4 bytes \times 2, M times), an interrupt is generated for the CPU.
 - (18) The CPU sends the stop instruction (SGCR:ST = 0) to the sound generator.
 - (19) When the stop instruction (SGCR:ST = 0) is sent within (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data are not output. (*3: The Nth transfer data is written to the register for sound, but sound is not output. The Nth transfer is to generate an interrupt for the CPU from the DMAC.)
 - (20) When the stop instruction (SGCR:ST = 0) is sent after (frequency data (SGFR) + 1) \times 1PWM cycle, SGO and SGA by the Nth transfer data stop output after the current tone cycle is completed. (*3: The Nth transfer data is output with sound.)

Note:

Until the sound generator notifies of the interrupt and the DMA transfer is completed like Step (5) to (6), operations must be completed within (frequency data (SGFR) + 1) \times 1PWM cycle.

Note:

Until the sound generator notifies of the interrupt and the software changes the increment decrement setting like Step (8) to (12), operations must be completed within (frequency data (SGFR) + 1) \times 1PWM cycle.

Note:

The increment decrement setting is enabled from the sound output in Step (14). With the use of the Nth transfer data of 4 bytes \times 2, the automatic increment decrement is performed.

CHAPTER : STEPPING MOTOR CONTROLLER

This chapter explains the stepping motor controller.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Setting
7. Q&A
8. Sample Programs
9. Notes

Code : 32_MB91590_HM_E_steppingmotorcnt_006_20111127

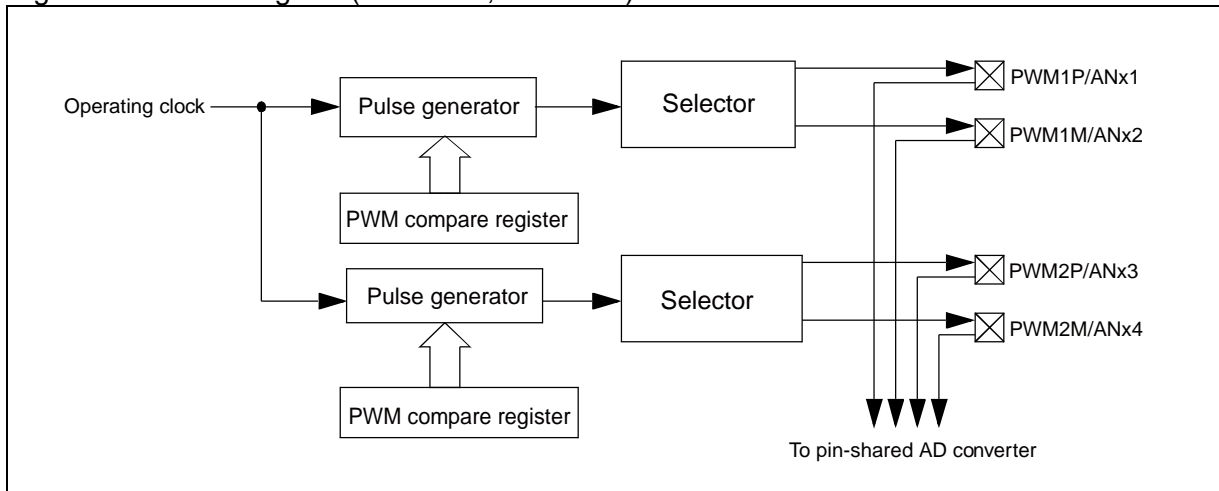
1. Overview

This section explains the overview of the stepping motor controller.

This stepping motor controller consists of 2 PWM pulse generators and 4 motor drivers.

The 4 set of motor drivers have high output power driving capacity and 2 set of motor coils are able to connect directly to the 4 terminals. This controller is designed to control the motor revolution with the combination of the PWM pulse generator and the selector logic. The synchronization mechanism ensures the synchronization operation between 2 set of PWMs.

Figure 1-1 Block Diagram (1 channel, Overview)



2. Features

This section explains features of the stepping motor controller.

PWM operation mode:

- The PWM operation mode can be selected from 8/10-bit operations.

Number of set: 6

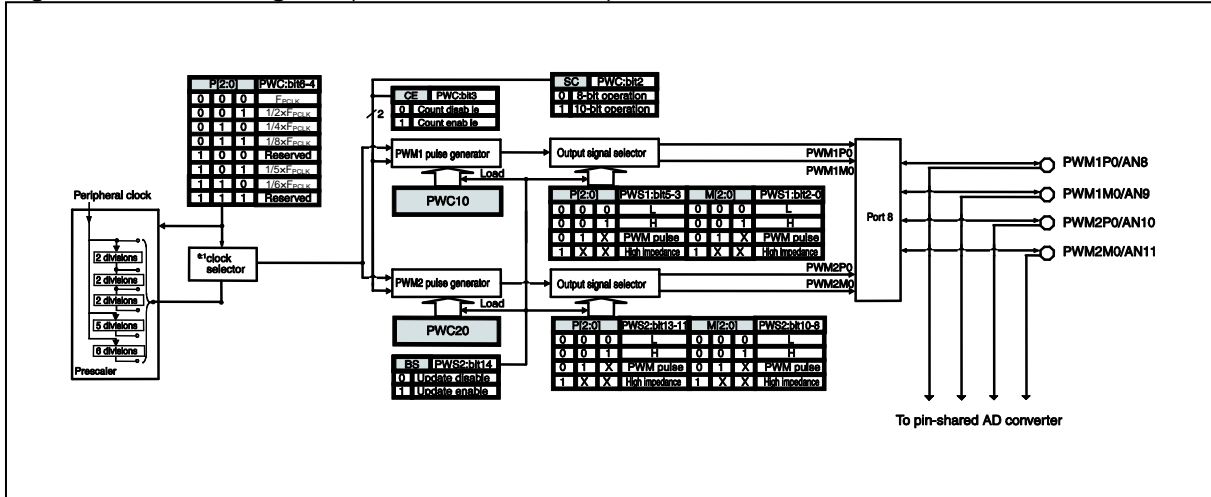
PWM operating clock:

- Peripheral clock/1, /2, /4, /5, /6, /8

3. Configuration

This section explains the configuration of the stepping motor controller.

Figure 3-1 Block Diagram (1 channel, Detailed)



4. Registers

This section explains registers of the stepping motor controller.

■ List of Base_addresses (Base_addr) and External Pins

Channel number	Base_addr	External pin name			
		PWM1P	PWM1M	PWM2P	PWM2M
0	0x200	PWM1P0	PWM1M0	PWM2P0	PWM2M0
1	0x208	PWM1P1	PWM1M1	PWM2P1	PWM2M1
2	0x210	PWM1P2	PWM1M2	PWM2P2	PWM2M2
3	0x218	PWM1P3	PWM1M3	PWM2P3	PWM2M3
4	0x220	PWM1P4	PWM1M4	PWM2P4	PWM2M4
5	0x228	PWM1P5	PWM1M5	PWM2P5	PWM2M5

■ **Registers Map**

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0200	PWC20		PWC10		PWM2 compare register 0 PWM1 compare register 0
0x204	Reserved	PWC0	PWS20	PWS10	PWM control register 0 PWM2 selection register 0 PWM1 selection register 0
0x0208	PWC21		PWC11		PWM2 compare register 1 PWM1 compare register 1
0x020C	Reserved	PWC1	PWS21	PWS11	PWM control register 1 PWM2 selection register 1 PWM1 selection register 1
0x0210	PWC22		PWC12		PWM2 compare register 2 PWM1 compare register 2
0x0214	Reserved	PWC2	PWS22	PWS12	PWM control register 2 PWM2 selection register 2 PWM1 selection register 2
0x0218	PWC23		PWC13		PWM2 compare register 3 PWM1 compare register 3
0x021C	Reserved	PWC3	PWS23	PWS13	PWM control register 3 PWM2 selection register 3 PWM1 selection register 3
0x0220	PWC24		PWC14		PWM2 compare register 4 PWM1 compare register 4
0x0224	Reserved	PWC4	PWS24	PWS14	PWM control register 4 PWM2 selection register 4 PWM1 selection register 4
0x0228	PWC25		PWC15		PWM2 compare register 5 PWM1 compare register 5
0x022C	Reserved	PWC5	PWS25	PWS15	PWM control register 5 PWM2 selection register 5 PWM1 selection register 5

4.1. PWM Control Register : PWC

The bit configuration of the PWM control register (PWC) is shown below.

The PWC is used to set activation/stop for the stepping motor controller.

■ PWC: Address Base_addr + 05_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	P2	P1	P0	CE	SC	-	Reserved
Initial value	0	0	0	0	0	0	-	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R1,WX	R/W0

[bit7] Reserved

[bit6 to bit4] P2 to P0 : Operating clock selection bits

P2 to P0 bits select a clock input signal for the PWM pulse generator.

P2	P1	P0	Clock input	PWM cycle ($F_{PCLK} = 16\text{MHz}$)	
				SC=0	SC=1
0	0	0	F_{PCLK}	16.0 μs	64.0 μs
0	0	1	$1/2 \times F_{PCLK}$	32.0 μs	128.0 μs
0	1	0	$1/4 \times F_{PCLK}$	64.0 μs	256.0 μs
0	1	1	$1/8 \times F_{PCLK}$	128.0 μs	512.0 μs
1	0	0	Reserved	-	-
1	0	1	$1/5 \times F_{PCLK}$	80.0 μs	320.0 μs
1	1	0	$1/6 \times F_{PCLK}$	96.0 μs	384.0 μs
1	1	1	Reserved	-	-

F_{PCLK} : Peripheral clock (PCLK)

[bit3] CE : Count enable bit

The CE bit enables the operation of the PWM pulse generator. When the CE bit is set to "1", the PWM pulse generator will start operating. The PWM2 pulse generator will start operating 1 machine cycle after the PWM1 pulse generator's start to reduce switching noise from the output drivers.

When the CE bit is cleared to "0" while the PWM pulse generator is operating, the PWM pulse generator will be initialized and stop operating.

Note:

If you set "1" to the CE bit, the operating clock selection must be completed.

[bit2] SC : 8/10 bit switching bit

When the SC bit is set to "1", the PWM will operate in 10-bit mode. When the SC bit is set to "0", the PWM will operate in 8-bit mode.

[bit1] - : Undefined bit

The read value is always "1". This does not affect the writing operation.

[bit0] Reserved

"0" should be written to this bit.

4.2. PWM1&2 Compare Register : PWC1/PWC2

The bit configuration of PWM1&2 compare registers (PWC1/PWC2) is shown below.

The 2 sets of 8 (10) bit compare registers for PWM1&2 are used to determine the width of PWM pulse. Memorized value "00_H"("000_H") means that the PWM duty is 0%, and "FF_H"("3FF_H") means 99.6% (99.9%).

The PWM1&2 compare registers can be accessed at given timing but modified value will be reflected to the pulse width at the end of current PWM cycle after the BS bit of the PWM2 selection register is set to "1".

When the SC bit of the PWM control register is set to "0" and the PWM is operating in 8-bit mode, the values of D9 and D8 will be unknown.

PWM1&2 compare registers must be accessed in half-word or word.

■ PWC1 : Address Base_addr + 02_H (Access: Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	-	-	-	-	-	-	D9	D8
Initial value	-	-	-	-	-	-	X	X
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	X	X	X	X	X	X	X	X
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ PWC2 : Address Base_addr + 00_H (Access: Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	-	-	-	-	-	-	D9	D8
Initial value	-	-	-	-	-	-	X	X
Attribute	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R1,WX	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	X	X	X	X	X	X	X	X
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit10] -: Undefined bits

The read value is always "1". This does not affect the writing operation.

[bit9 to bit0] D9 to D0 : Compare data

Set a pulse width for the PWM to these bits.

4.3. PWM1 Selection Register : PWS1

The bit configuration of the PWM1 selection register (PWS1) is shown below.

The PWM1 selection register is used to determine the output of the stepping motor controller's external pins from "0", "1", PWM pulse or high impedance.

■ **PWS1 : Address Base_addr + 07_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
-	-	P2	P1	P0	M2	M1	M0

Initial value	-	-	0	0	0	0	0	0
Attribute	R1,WX	R1,WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] - : Undefined bits

The read value is always "1". This does not affect the writing operation.

[bit5 to bit3] P2 to P0: Output selection bits

P2, P1 and P0 bits are used to select output signals for the PWM1P0 to PWM1P5.

[bit2 to bit0] M2 to M0: Output selection bits

M2, M1 and M0 bits are used to select output signals for the PWM1M0 to PWM1M5.

Following table shows the relation between the output level and selected bits:

P2	P1	P0	PWM1P _n	M2	M1	M0	PWM1M _n
0	0	0	L	0	0	0	L
0	0	1	H	0	0	1	H
0	1	X	PWM pulse	0	1	X	PWM pulse
1	X	X	High impedance	1	X	X	High impedance

n = 0 to 5

4.4. PWM2 Selection Register : PWS2

The bit configuration of the PWM2 selection register (PWS2) is shown below.

The PWM2 selection register is used to determine the output of the stepping motor controller's external pins from "0", "1", PWM pulse or high impedance.

■ PWS2 : Address Base_addr + 06_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	-	BS	P2	P1	P0	M2	M1	M0
Initial value	-	0	0	0	0	0	0	0
Attribute	R1,WX	R,W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7] - : Undefined bits

The read value is always "1". This does not affect the writing operation.

[bit6] BS : Rewrite bit

The BS bit is used to synchronize the setting for PWM outputs. The changes to the 2 set of compare registers and 2 set of selection registers will not be reflected to the output signals before the BS bit is set.

When the BS bit is set to "1", the PWM pulse generator and selector will load the contents of the registers at the end of PWM cycle. The BS bit will automatically be cleared to "0" at the beginning of next cycle. If the BS bit is set to "1" with software at the same time of this automatic clearing, the BS bit will be set to "1" (no change) and automatic clearing will be released.

If the BS bit is set to "0" with software at the same time of this automatic clearing, the BS bit will be cleared to "0" and the PWM pulse generator and selector will not load the contents of the registers at the end of PWM cycle.

Note:

If a read-modify-write instruction is executed to a bit other than BS with BS = "1", "1" will be read from the BS and "1" will be written to the BS bit once again. If the BS bit is automatically cleared at the beginning of PWM cycle between read and write, "1" will be written to the BS bit once again after cleared. Therefore, if "1" is not set to the BS bit by the end of next PWM cycle, the PWM pulse generator and selector will load the contents of the registers.

[bit5 to bit3] P2 to P0: Output selection bits

P2, P1 and P0 bits are used to select output signals for the PWM2P0 to PWM2P5.

[bit2 to bit0] M2 to M0: Output selection bits

M2, M1 and M0 bits are used to select output signals for the PWM2M0 to PWM2M5.

Following table shows the relation between the output level and selected bits:

P2	P1	P0	PWM2Pn	M2	M1	M0	PWM2Mn
0	0	0	L	0	0	0	L
0	0	1	H	0	0	1	H
0	1	X	PWM pulse	0	1	X	PWM pulse
1	X	X	High impedance	1	X	X	High impedance

n = 0 to 5

5. Operation

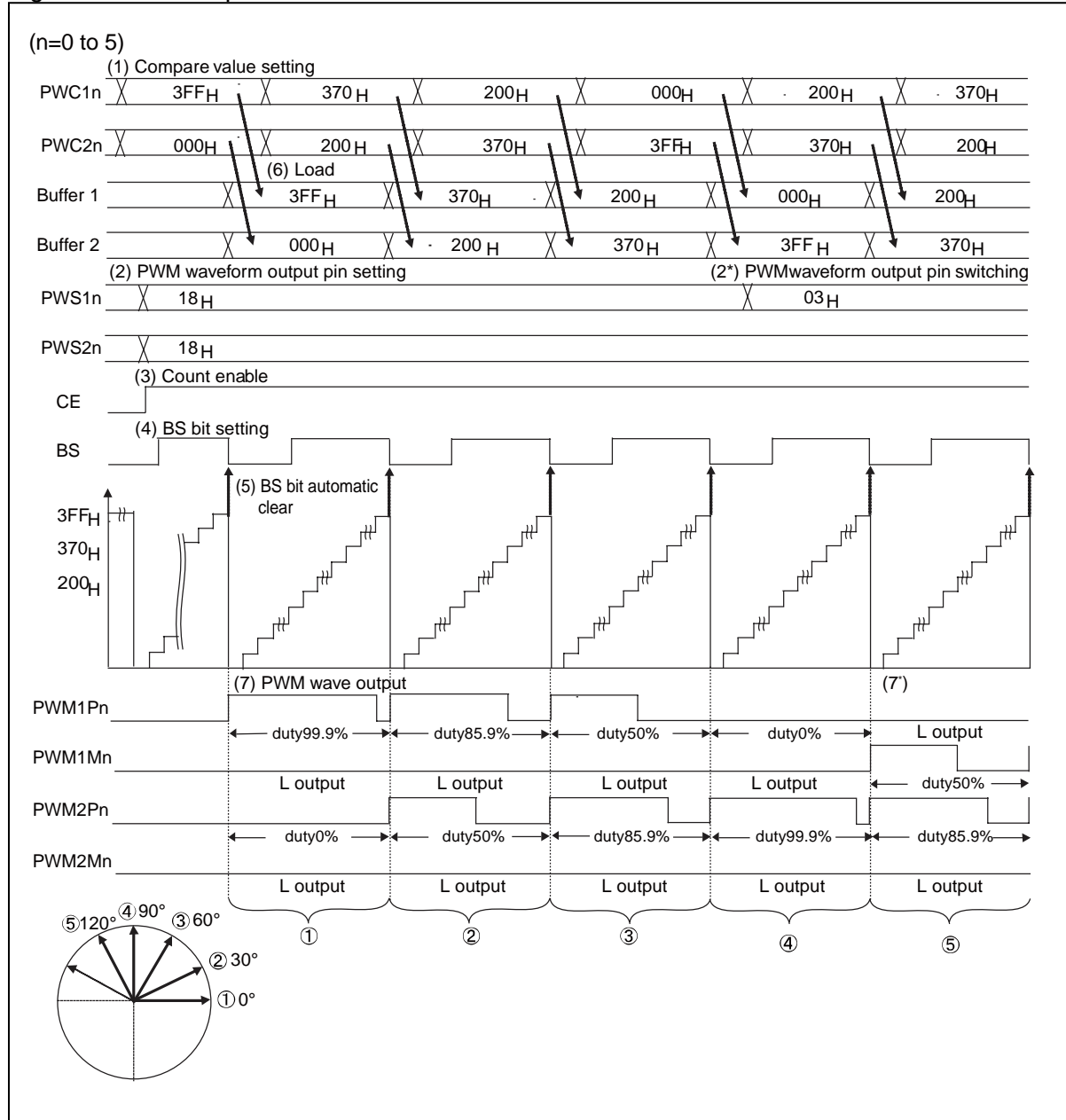
This section explains operating of the stepping motor controller.

- 5.1. PWM Operation
- 5.2. PWM Compare Register Loading with The BS bit
- 5.3. Selection of Motor Drive Signals

5.1. PWM Operation

The PWM operation is explained.

Figure 5-1 PWM Operation

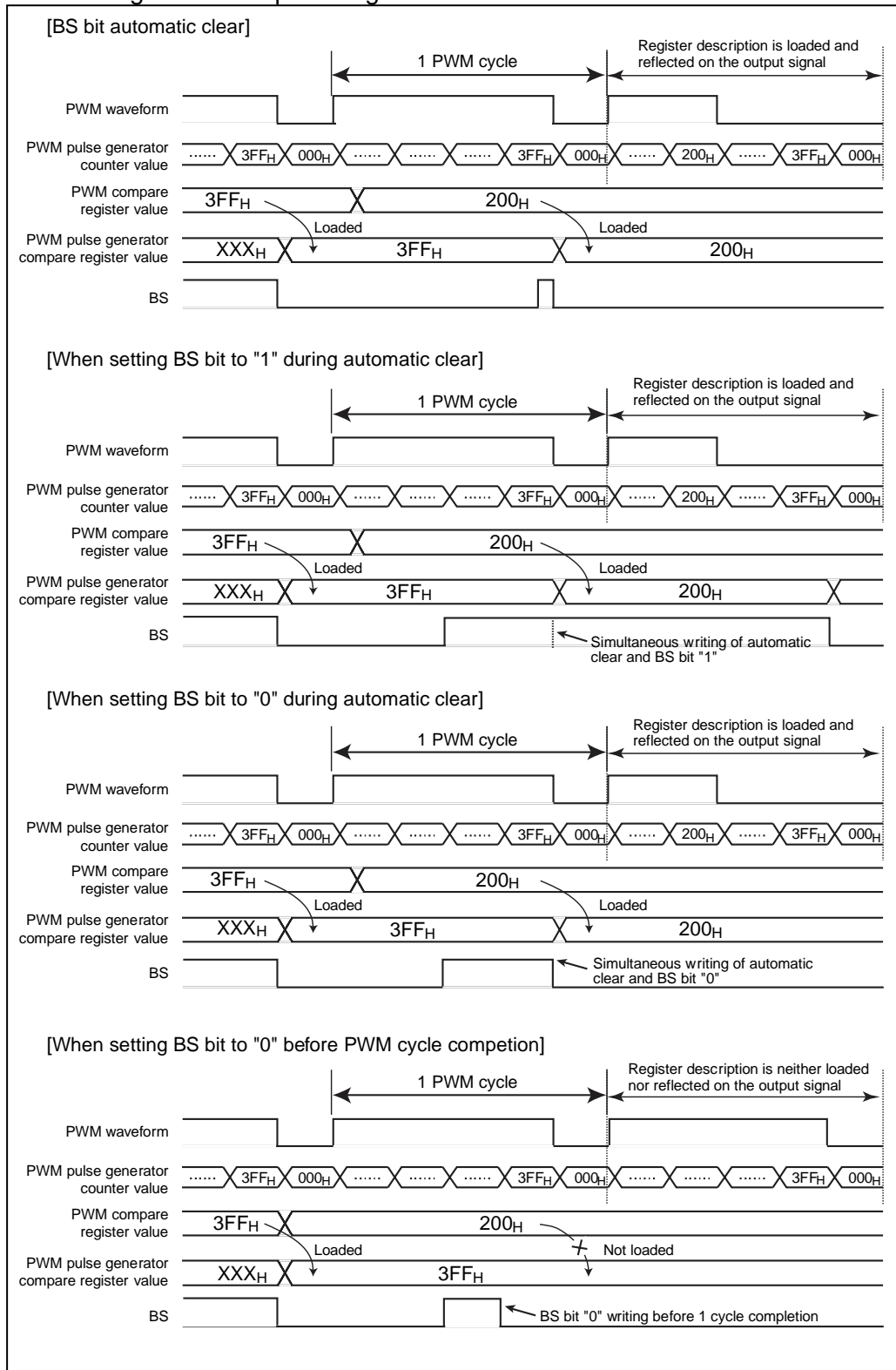


- (1) Set compare value
- (2) PWM waveform output pin setting/(2*) PWM waveform output pin switching
- (3) Count enable
- (4) The BS bit setting
- (5) The BS bit automatic clearing
- (6) Load compare value
- (7) PWM wave output/ PWM wave output switching by (7*) and (2*)
- (8) Repeat step (1) to (7).

5.2. PWM Compare Register Loading with The BS bit

PWM compare register loading with the BS bit is explained.

Figure 5-2 Loading PWM Compare Register Values



- (1) The BS bit automatic clearing: Loading will be performed to be reflected to the output signals.
- (2) Automatic clearing at the same time of setting "1" to the BS bit: Loading will be performed to be reflected to the output signals.
- (3) Automatic clearing at the same time of setting "0" to the BS bit: Loading will be performed to be reflected to the output signals.
- (4) "0" is set to the BS bit before the end of PWM cycle: Loading will not be performed and no reflection (See "Notes" for "[bit6] BS : Rewrite bit".)

5.3. Selection of Motor Drive Signals

This section explains selection of motor drive signals.

The motor drive signals which output to the pins related to the stepping motor controller can be selected for each pin from 4 types with the setting of the PWM selection registers.

Table 5-1 shows the motor drive signal selection and the settings for the PWM selection register 1 and 2.

Writing "1" to the BS bit of the PWM selection register 2 after these settings are made, the setting values will be valid at the end of current PWM cycle. This BS bit will automatically be cleared at the beginning of next cycle. If writing to the BS bit and BS bit clearing are occurred at the same time of the beginning of next cycle, writing to the BS bit is prioritized and the BS bit clearing will be cancelled.

Table 5-1 Motor Drive Signal Selection and Settings for PWM Selection Register

P2, P1, P0 bits	PWM1P0 to PWM1P5 outputs PWM2P0 to PWM2P5 outputs	M2, M1, M0 bits	PWM1M0 to PWM1M5 outputs PWM2M0 to PWM2M5 outputs
000 _B	L	000 _B	L
001 _B	H	001 _B	H
01X _B	PWM pulse	01X _B	PWM pulse
1XX _B	High impedance	1XX _B	High impedance

6. Setting

This section explains setting of the stepping motor controller.

Table 6-1 Settings Required for PWM Operation

Setting	Setting register	Setting method
PWM operation start	PWM control (PWC0 to PWC5)	See 7.2.
PWM operating clock setting		See 7.4.
8/10-bit mode switching		See 7.1.
Compare value (Duty value) setting	PWM1&2 compare (PWC10 to PWC15/PWC20 to PWC25)	
Selection of motor drive signals	PWS1&2 selection (PWS10 to PWS15/PWS20 to PWS25)	See 7.5.
PWM pin output setting	Set the pins as peripheral output. See "CHAPTER : I/O PORTS".	

Table 6-2 Settings Required to Stop PWM

Setting	Setting register	Setting method
PWM operation stop	PWM control (PWC0 to PWC5)	See 7.2.

Table 6-3 Settings Required for Changing PWM Output

Setting	Setting register	Setting method
Compare value (Duty value) setting	PWM1&2 compare (PWC10 to PWC15/PWC20 to PWC25)	See 7.1.
Selection of motor drive signals	PWS1&2 selection (PWS10 to PWS15/PWS20 to PWS25)	See 7.5.
Rewrite bit(BS bit) setting	PWM control (PWC0 to PWC5)	See 7.3.

7. Q&A

This section explains Q&A of the stepping motor controller.

- 7.1. How to Set Cycle and Duty
- 7.2. How to Enable/Stop PWM Operation
- 7.3. How to Reflect the Duty Change
- 7.4. Type and Selection of Operating Clock
- 7.5. How to Change the Motor Drive Signals
- 7.6. How to Assign a Pin as a PWM Output Pin
- 7.7. How to Assign a Pin as an A/D Converter Analog Input Pin

7.1. How to Set Cycle and Duty

How to set the cycle and duty is explained.

Cycle value setting and duty value setting

- Set the cycle value (operating clock selection, 8/10-bit operation selection) in the PWM control register PWC0 to PWC5.
- Set the duty value in the PWM1&2 compare register (PWC10 to PWC15, PWC20 to PWC25).

Calculation formulas:

Cycle:

8-bit operation (PWC0 to PWC5:SC = 0) : $(1/\text{operating clock}) \times 256$

10-bit operation (PWC0 to PWC5:SC = 1) : $(1/\text{operating clock}) \times 1024$

Note:

Specify the operating clock with PWC0 to PWC5:P[2:0]. (F_{PCLK} , $1/2 \times F_{\text{PCLK}}$, $1/4 \times F_{\text{PCLK}}$, $1/8 \times F_{\text{PCLK}}$, $1/5 \times F_{\text{PCLK}}$, $1/6 \times F_{\text{PCLK}}$ (F_{PCLK} : peripheral clock))

Duty:

8-bit operation (PWC0 to PWC5:SC = 0) : PWC1&2 compare register value = $\text{duty} \times (256/100)$

10-bit operation (PWC0 to PWC5:SC = 1) : PWC1&2 compare register value = $\text{duty} \times (1024/100)$

Available setting range

Cycle:

16 μ s, 32 μ s, 64 μ s, 80 μ s, 96 μ s, 128 μ s, 256 μ s, 320 μ s, 384 μ s, 512 μ s ($F_{\text{PCLK}} = 16\text{MHz}$)

PWC1&2 compare register value:

8-bit operation (PWC0 to PWC5:SC = 0) : 0 to 99.6% (0 to FF_H)

10-bit operation (PWC0 to PWC5:SC = 1) : 0 to 99.9% (0 to 3FF_H)

7.2. How to Enable/Stop PWM Operation

How to enable/stop the PWM operation is shown below.

PWM operation enable

Use the count enable bit (PWC0 to PWC5:CE).

Control	Count enable bit (CE)
How to stop PWM operation	Set to "0"
How to enable PWM operation	Set to "1"

If you enable the counting, the operating clock selection must be completed.

Note:

See "[bit3] CE : Count enable bit" in "4.1 PWM Control Register : PWC".

7.3. How to Reflect the Duty Change

How to reflect the duty change is shown below.

Duty change

Writing "1" to the BS bit of the PWM1&2 selection registers, the pulse width will be updated at the end of current PWM cycle.

Control	Rewrite bit (BS)
How to change the duty	Set to "1"

Note:

See Figure 5-2 for details on the load timing of the PWM1&2 compare registers.

7.4. Type and Selection of Operating Clock

The type and selection of the operating clock are shown below.

Operating clock selection

Use the operating clock selection bits (PWC0 to PWC5:P[2:0]).

See "4.1 PWM Control Register : PWC" for setting the operating clock selection bits (PWC0 to PWC5:P[2:0]).

7.5. How to Change the Motor Drive Signals

How to change the motor drive signals is shown below.

Motor drive signal change

The motor drive signals can be selected from L, H, PWM pulse, or high impedance with the output selection bits (PWS10 to PWS15/PWS20 to PWS25).

See "[bit2 to bit0] M2 to M0: Output selection bits" in "4.3 PWM1 Selection Register : PWS1" and "[bit2 to bit0] M2 to M0: Output selection bits" in "4.4 PWM2 Selection Register : PWS2" for details on the output selection bit setting.

7.6. How to Assign a Pin as a PWM Output Pin

How to assign a pin as a PWM output pin is shown below.

Set the pins as peripheral output. For details, see "CHAPTER : I/O PORTS".

7.7. How to Assign a Pin as an A/D Converter Analog Input Pin

How to assign a pin as an A/D converter analog input pin is shown below.

Set the pins as an A/D converter input. For details, see "CHAPTER : I/O PORTS".

8. Sample Programs

This section explains sample programs.

<p>Setting Procedure Example 1</p> <p>PWM pulse output from PWM1P0 and PWM2P0</p> <div style="text-align: center; border: 1px solid black; width: fit-content; margin: 0 auto; padding: 2px;">Initial setting (SMC0)</div> <div style="text-align: center; border: 1px solid black; width: fit-content; margin: 0 auto; padding: 2px;">Activation (SMC0)</div> <p><Initial setting (SMC0)></p> <p>- Port</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%;">SMC0 output setting for ports</td> <td style="width: 50%;">See "CHAPTER : I/O PORTS".</td> </tr> </table> <p>- SMC0 control</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Register name.Bit name</th> <th style="width: 30%;"></th> </tr> </thead> <tbody> <tr> <td>PWM control register setting</td> <td>PWC0</td> </tr> <tr> <td>Sampling clock selection>></td> <td>.S2</td> </tr> <tr> <td>Operating clock selection>></td> <td>.P[2:0]</td> </tr> <tr> <td>Count setting>></td> <td>.CE</td> </tr> <tr> <td>8/10 bit switch>></td> <td>.SC</td> </tr> </tbody> </table> <p>- Duty setting</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Register name.Bit name</th> <th style="width: 30%;"></th> </tr> </thead> <tbody> <tr> <td>PWC1 compare register setting</td> <td>PWC10</td> </tr> <tr> <td>PWC2 compare register setting</td> <td>PWC20</td> </tr> </tbody> </table> <p>- Output pin setting</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Register name.Bit name</th> <th style="width: 30%;"></th> </tr> </thead> <tbody> <tr> <td>PWS1 selection register setting</td> <td>PWS10</td> </tr> <tr> <td>PWM1P0 pin output selection>></td> <td>.P[2:0]</td> </tr> <tr> <td>PWM1M0 pin output selection>></td> <td>.M[2:0]</td> </tr> <tr> <td>PWS2 selection register setting</td> <td>PWS20</td> </tr> <tr> <td>PWM2P0 pin output selection>></td> <td>.P[2:0]</td> </tr> <tr> <td>PWM2M0 pin output selection>></td> <td>.M[2:0]</td> </tr> </tbody> </table> <p><Activation (SMC0)></p> <p>- SMC0 activation</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Register name.Bit name</th> <th style="width: 30%;"></th> </tr> </thead> <tbody> <tr> <td>Count enable</td> <td>PWC0.CE</td> </tr> </tbody> </table> <p>- Duty change</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Register name.Bit name</th> <th style="width: 30%;"></th> </tr> </thead> <tbody> <tr> <td>PWC1 compare register setting</td> <td>PWC10</td> </tr> <tr> <td>PWC2 compare register setting</td> <td>PWC20</td> </tr> </tbody> </table> <p>- BS bit set</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Register name.Bit name</th> <th style="width: 30%;"></th> </tr> </thead> <tbody> <tr> <td>PWS2 selection register setting</td> <td>PWS20.BS</td> </tr> </tbody> </table>	SMC0 output setting for ports	See "CHAPTER : I/O PORTS".	Register name.Bit name		PWM control register setting	PWC0	Sampling clock selection>>	.S2	Operating clock selection>>	.P[2:0]	Count setting>>	.CE	8/10 bit switch>>	.SC	Register name.Bit name		PWC1 compare register setting	PWC10	PWC2 compare register setting	PWC20	Register name.Bit name		PWS1 selection register setting	PWS10	PWM1P0 pin output selection>>	.P[2:0]	PWM1M0 pin output selection>>	.M[2:0]	PWS2 selection register setting	PWS20	PWM2P0 pin output selection>>	.P[2:0]	PWM2M0 pin output selection>>	.M[2:0]	Register name.Bit name		Count enable	PWC0.CE	Register name.Bit name		PWC1 compare register setting	PWC10	PWC2 compare register setting	PWC20	Register name.Bit name		PWS2 selection register setting	PWS20.BS	<p>Program Example 1</p> <pre> void SMC0_sample_1(void) { SMC0_initial(); SMC0_start(); } void SMC0_initial(void) { IPORT_SETTING_SMC0_OUT() /* Set the SMC0 pins as peripheral output. */ IO_PWC0.byte = 0x36; /* Setting value = 0011_0110 */ /* bit7 = 0 S2 sampling clock setting */ /* bit6 to 4 = 011 P[2:0] Operating clock setting */ /* bit3 = 0 CE count disable */ /* bit2 = 1 SC 10bit operation */ /* bit1 = 1 Undefined bit */ /* bit0 = 0 Reserved bit */ IO_PWC10.hword = 0x03ff; /* PWM10 Duty setting */ IO_PWC20.hword = 0x0000; /* PWM20 Duty setting */ IO_PWS10.byte = 0x1f; /* Setting value = 0001_1111 */ /* bit7 to 6 = 00 Undefined bits */ /* bit5 to 3 = 011 P[2:0] PWM1P0 = PWM output */ /* bit2 to 0 = 111 M[2:0] PWM1M0 = Hi-Z output */ IO_PWS20.byte = 0x58; /* Setting value = 0101_1000 */ /* bit7 = 0 Undefined bit */ /* bit6 = 1 BS rewrite setting */ /* bit5 to 3 = 011 P[2:0] PWM2P0 = PWM output */ /* bit2 to 0 = 000 M[2:0] PWM2M0 = L output */ } Void SMC0_start(void) { IO_PWC0.bit.CE = 1; /* bit3= 1 CE count enable */ /* BS bit automatic clearing waiting */ IO_PWC10.hword = 0x0370; /* PWM10 Duty change */ IO_PWC20.hword = 0x0200; /* PWM20 Duty change */ IO_PWS20.byte = 0x58; /* Setting value = 0101_1000 */ } </pre>
SMC0 output setting for ports	See "CHAPTER : I/O PORTS".																																																
Register name.Bit name																																																	
PWM control register setting	PWC0																																																
Sampling clock selection>>	.S2																																																
Operating clock selection>>	.P[2:0]																																																
Count setting>>	.CE																																																
8/10 bit switch>>	.SC																																																
Register name.Bit name																																																	
PWC1 compare register setting	PWC10																																																
PWC2 compare register setting	PWC20																																																
Register name.Bit name																																																	
PWS1 selection register setting	PWS10																																																
PWM1P0 pin output selection>>	.P[2:0]																																																
PWM1M0 pin output selection>>	.M[2:0]																																																
PWS2 selection register setting	PWS20																																																
PWM2P0 pin output selection>>	.P[2:0]																																																
PWM2M0 pin output selection>>	.M[2:0]																																																
Register name.Bit name																																																	
Count enable	PWC0.CE																																																
Register name.Bit name																																																	
PWC1 compare register setting	PWC10																																																
PWC2 compare register setting	PWC20																																																
Register name.Bit name																																																	
PWS2 selection register setting	PWS20.BS																																																

9. Notes

This section explains notes of the stepping motor controller.

■ Notes for PWM setting value change

- The PWM compare registers 1/2 (PWC10 to PWC15, PWC20 to PWC25) and the PWM selection registers 1/2 (PWS10 to PWS15, PWS20 to PWS25) can be always accessed. However, to change the width of the "H" level of the PWM or PWM output, "1" must be written to the BS bit of the PWM2 selection register after (or at the same time) the setting values are written to these registers.
- After "1" is set to the BS bit, new setting values will become valid at the end of the current PWM cycle and the BS bit will automatically be cleared.
- In addition, if writing "1" to the BS bit and the reset of the BS bit at the end of the PWM cycle are occurred at the same time, writing to the BS bit is prioritized and the BS bit reset will be cancelled.

CHAPTER: REGULATOR CONTROL

This chapter explains the overview, features and configurations of the regulator control.

1. Overview
2. Features
3. Configuration
4. Register
5. Operation

1. Overview

This section explains the overview of the regulator control.

The operation of the regulator that generates the internal voltage is automatically changed according to the device state transition.

It is changed automatically to following three regulator modes.

- Main mode (at normal operation)
- Sub mode (at sub run)
- Standby mode(at STOP mode and Watch mode)

2. Features

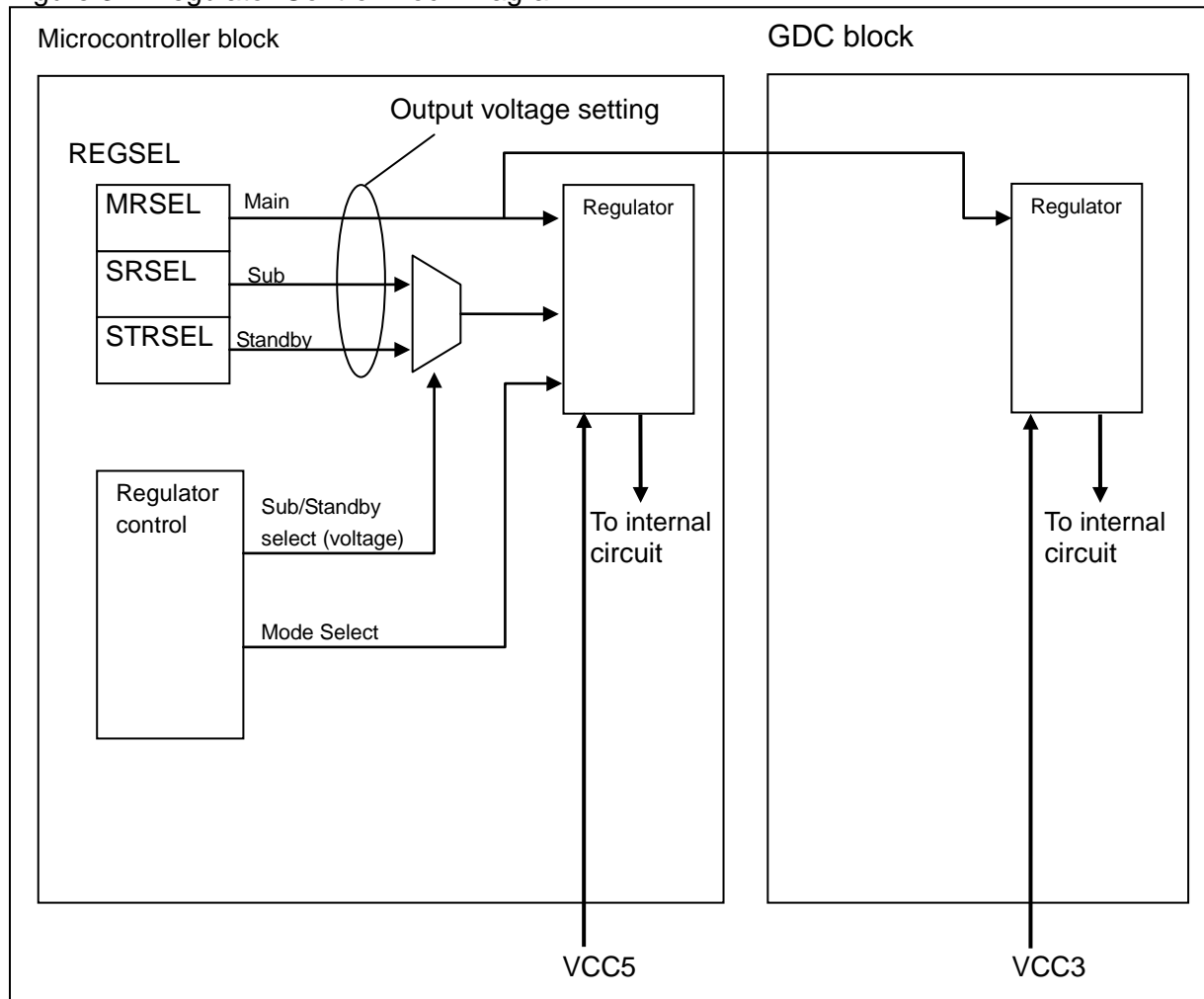
This section explains features of the regulator control.

- The regulator mode is automatically changed according to the device state transition.

3. Configuration

This section explains the configuration of the regulator control.

Figure 3-1 Regulator Control Block Diagram



Note:

The difference between the sub mode and the standby mode is only the output voltage settings.

4. Register

This section explains a register of the regulator control.

Table 4-1 Register Map

Address	Registers				Register Function
	+0	+1	+2	+3	
0x0580	REGSEL	Reserved	Reserved	Reserved	Regulator Output Voltage Selection Register

4.1. Regulator Output Voltage Select Register : REGSEL (REGulator output voltage SElect register)

The bit configuration of the regulator output voltage selection register is shown below.

It is a register that selects the output voltage level of each regulator mode (main/sub/standby).

■ REGSEL : Address 0580_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MRSEL[1:0]		SRSEL[1:0]		STRSEL[2:0]			Reserved
Initial value	0	1	1	0	0	1	1	0
Attribute	R/W0	R/W1	R/W1	R/W0	R/W1	R/W1	R/W0	R0,WX

[bit7, bit6] MRSEL[1:0] (Main Regulator voltage SElect)

These bits set the output voltage level of main regulator (microcontroller, GDC).

MRSEL[1:0]	Main regulator output voltage
00	Reserved
01	1.2±0.1V
10	Reserved
11	Reserved

[bit5, bit4] SRSEL[1:0] (Sub Regulator voltage SElect)

These bits set the output voltage level of sub regulator (microcontroller).

SRSEL[1:0]	Sub regulator output voltage
00	Reserved
01	Reserved
10	1.2±0.1V
11	Reserved

[bit3 to bit1] STRSEL[2:0] (STandby Regulator voltage SElect)

These bits set the output voltage level of standby regulator (microcontroller).

STRSEL[2:0]	Standby regulator output voltage
000	Reserved
001	Reserved
010	Reserved
011	$0.9 \pm 0.1V$
100	Reserved
101	Reserved
110	$1.2 \pm 0.1V$
111	Reserved

Note:

Please use 1.2V as the set value (STRSEL[2:0]=110).

[bit0] Reserved

5. Operation

This section explains the operation of the regulator control.

Before entering standby mode, set STRSEL[2:0] to 110. After a reset this value (STRSEL[2:0] = 110) note that it has not been set.

CHAPTER : BUS PERFORMANCE COUNTERS

This chapter explains the bus performance counters.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operations

Code : 34_MB91590_HM_E_busperform_006_20111127

1. Overview

This section explains the overview of the bus performance counters.

This series has a built-in bus performance counters (BPC) for measuring the performance of the on-chip bus. BPC measures the breakdown of traffic on the on-chip bus, and provides information for strategies to improve bus performance. Because the counters do not count while the on-chip bus is idle, use the timers in the system at the same time to measure the time.

2. Features

This section explains the features of the bus performance counters.

■ Counter configuration

Count clocks :	Clock for the on-chip bus
Counter bit length :	32-bit × 3 channels (BPC-A, BPC-B, BPC-C)
Overflow detection :	None
Counter value rewrite :	Allowed

■ Main functions

The following operations can be selected for counting in each channel

- Number of read accesses in the on-chip bus
- Number of write accesses in the on-chip bus
- Number of wait cycles in the on-chip bus

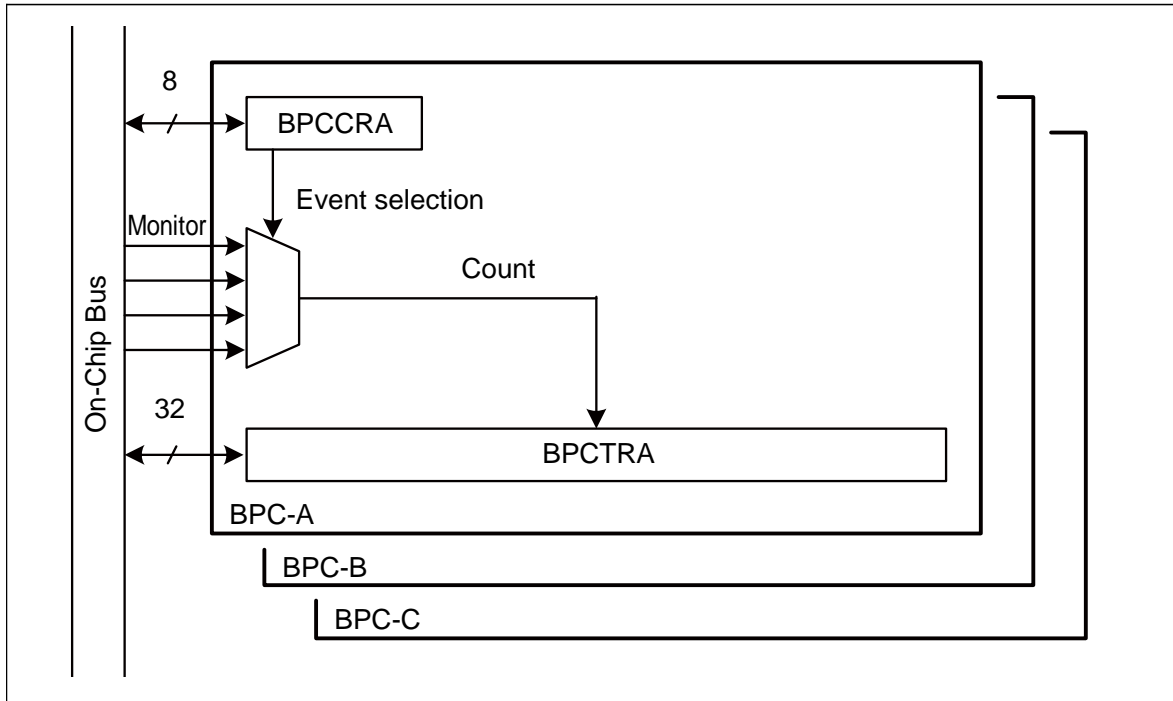
One of the following operations can be selected for counting in each channel

- Specific bus master (CPU, DMAC, other, or all)
- Specific target (ICH, MCH, other, or all)

3. Configuration

This section explains the configuration of the bus performance counters.

Figure 3-1 Block Diagram



4. Registers

This section explains the registers of the bus performance counters.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0710	BPCCRA	BPCCRB	BPCCRC	Reserved	BPC-A control register BPC-B control register BPC-C control register
0x0714	BPCTRA				BPC-A count register
0x0718	BPCTRB				BPC-B count register
0x071C	BPCTRC				BPC-C count register

4.1. BPC-A Control Register : BPC CRA (Bus Performance Counter Control Register A)

The bit configuration of the BPC-A control register is shown below.

This register configures the measurement target of bus performance counter A (BPC-A).

The bus performance counters have three channels, A, B, and C, and there is a control register for each of these counters. Each field of the control register is common to each channel.

■ BPC CRA : Address 0710_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FUNC[1:0]		MST[3:0]			SLV[1:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] FUNC[1:0] (Function Selection) : Measurement event selection
These bits select the event measured by BPC.

FUNC[1:0]	Event
00	BPC-A operation stopped (initial value)
01	Number of read accesses
10	Number of write accesses
11	Number of wait cycles

[bit5 to bit2] MST[3:0] (bus MaSTer select) : Bus master selection
These bits select the bus master for the events which are measured by BPC.

MST[3:0]	Bus master
0000	All bus masters (initial value)
0001	CPU (XBS)
0010	DMAC
0011	Reserved
0100	Reserved
0101 to 1111	Reserved

[bit1, bit0] SLV[1:0] (SLaVe select) : Slave selection

These bits select the slave for the events which are measured by BPC.

SLV[1:0]	Slave
00	All slaves (initial value)
01	MCH (registers, external bus)
10	ICH (peripherals)
11	Anything other than MCH/ICH

4.2. BPC-B Control Register : BPCCRB (Bus Performance Counter Control Register B)

The bit configuration of the BPC-B control register is shown below.

This register configures the measurement target of bus performance counter B (BPC-B).

The function of each bit is the same as BPCCRB.

■ BPCCRB : Address 0711_H (Access: Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FUNC[1:0]		MST[3:0]				SLV[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

4.3. BPC-C Control Register : BPCCRC (Bus Performance Counter Control Register C)

The bit configuration of the BPC-C control register is shown below.

This register configures the measurement target of bus performance counter C (BPC-C).

The function of each bit is the same as BPC CRA.

■ **BPCCRC : Address 0712_H (Access: Byte)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FUNC[1:0]		MST[3:0]				SLV[1:0]	
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

4.4. BPC-A Count Register : BPCTRA (Bus Performance Counter Register A)

The bit configuration of the BPC-A count register is shown below.

This register is a 32-bit length count register that counts the events configured by BPCCRA.

■ BPCTRA : Address 0714_H (Access: Word)

	bit31	bit30	•	•	•	bit3	bit2	bit1	bit0
	BPCTRA[31:0]								
Initial value	0	0	•	•	•	0	0	0	0
Attribute	R/W	R/W	•	•	•	R/W	R/W	R/W	R/W

[bit31 to bit0] BPCTRA[31:0] (Bus Performance Counter Register A) : BPC-A count

If bit7, bit6: FUNC of the BPCCRA register are set to a value other than "00", the count of the target events begins. This register is readable and writable, and can only be accessed using 32-bit access. Because the counter is not initialized when the count is started, set the initial value when starting a new count.

Furthermore, because there is no overflow control, if the counter overflows it returns to zero and continues counting.

4.5. BPC-B Count Register : BPCTRB (Bus Performance Counter Register B)

The bit configuration of the BPC-B count register is shown below.

This register is a 32-bit length count register that counts the events configured by BPCCRB. The usage is the same as BPCTRA.

■ BPCTRB : Address 0718_H (Access: Word)

	bit31	bit30	•	•	•	bit3	bit2	bit1	bit0
	BPCTRB[31:0]								
Initial value	0	0	•	•	•	0	0	0	0
Attribute	R/W	R/W	•	•	•	R/W	R/W	R/W	R/W

4.6. BPC-C Count Register : BPCTRC (Bus Performance Counter Register C)

The bit configuration of the BPC-C count register is shown below.

This register is a 32-bit length count register that counts the events configured by BPCCRC. The usage is the same as BPCTRA.

■ BPCTRC : Address 071C_H (Access: Word)

	bit31	bit30	•	•	•	bit3	bit2	bit1	bit0
	BPCTRC[31:0]								
Initial value	0	0	•	•	•	0	0	0	0
Attribute	R/W	R/W	•	•	•	R/W	R/W	R/W	R/W

5. Operations

This section explains the operations of the bus performance counters.

- 5.1. Setting
- 5.2. Starting and Stopping
- 5.3. Operation
- 5.4. Measurement and Result Processing

5.1. Setting

This section explains the setting of the bus performance counters.

Before starting each of the BPC channels, write "0x00000000" to BPCTRA, BPCTRB, and BPCTRC, and initialize each counter. Initialize each counter in the same way when changing the measurement target. Because the counter value is undefined after reset, always write the counter value before enabling operation.

When starting each BPC channel, configure the measurement target of each counter using BPC CRA, BPC CRB, and BPC CRC.

The events monitored by the settings of the bus performance counter A (B, C) control register (BPC CRA (B, C)) are as follows. Operation is not guaranteed for any combination that does not exist in the following table. Moreover, it does not count in emulator mode.

Table 5-1 List of BPC Settings

FUNC[1:0]	MST[3:0]	SLV[1:0]	Target event
01	0000	00	Read access from XBS, DMAC
		01	MCH read from XBS, DMAC
		10	ICH read from XBS, DMAC
		11	Other than MCH/ICH read from XBS, DMAC
	0001	00	Read access from XBS
		01	MCH read from XBS
		10	ICH read from XBS
		11	Other than MCH/ICH read from XBS
	0100	00	Read access from DMAC
		01	MCH read from DMAC
		10	ICH read from DMAC
		11	Other than MCH/ICH read from DMAC
10	0000	00	Write access from XBS, DMAC
		01	MCH write from XBS, DMAC
		10	ICH write from XBS, DMAC
		11	Other than MCH/ICH write from XBS, DMAC
	0001	00	Write access from XBS
		01	MCH write from XBS
		10	ICH write from XBS
		11	Other than MCH/ICH write from XBS
	0100	00	Write access from DMAC
		01	MCH write from DMAC
		10	ICH write from DMAC
		11	Other than MCH/ICH write from DMAC

FUNC[1:0]	MST[3:0]	SLV[1:0]	Target event
11	0000	00	Wait cycle of XBS, DMAC
		01	MCH wait from XBS, DMAC
		10	ICH wait from XBS, DMAC
		11	Other than MCH/ICH wait from XBS, DMAC
	0001	00	Wait access from XBS
		01	MCH wait from XBS
		10	ICH wait from XBS
		11	Other than MCH/ICH wait from XBS
	0100	00	Wait access from DMAC
		01	MCH wait from DMAC
		10	ICH wait from DMAC
		11	Other than MCH/ICH wait from DMAC

5.2. Starting and Stopping

This section explains the starting and stopping of the bus performance counters.

The target event count is started by setting the FUNC[1:0] field of the bus performance counter A control register (BPCCRA) to a value other than "00". However, at this time the count starts from the current value without initializing the bus performance counter A register (BPCTRA). The operation of the bus performance counter stops when BPCCRA:FUNC[1:0] is set to "00".

5.3. Operation

This section explains the operation of the bus performance counters.

Once operation has been enabled by setting the control register, each of the measurement target operations continues to be counted while the on-chip bus is operating. However, the count is paused in the circumstances shown below.

- While in emulator mode

The count operation when each of the low-power consumption modes is set is as follows.

- CPU sleep mode
Each measurement target operation is counted.
- Bus sleep mode
Only counted during DMA transfers that operate the on-chip bus. During other periods, counting is not performed because the measurement target operations do not occur.
- Standby mode (watch mode / stop mode)
Counting is not performed because the measurement target operations do not occur.

The control register is initialized when a reset occurs. Counting is not performed after a reset occurs.

5.4. Measurement and Result Processing

This section explains the measurement and result processing of the bus performance counters.

The use of BPC is anticipated for when ICE is connected or when using a monitor debugger. The configuring of measurements and reading of results are performed in debug mode while the user program execution is halted.

Examples of measurements are as follows.

- Measure between two points in a program
- Measure a reference time base

These are explained below.

- Measuring between two points in a program
During this measurement, the measurement starting point and measurement ending point in the user program are configured as follows.
 - Measurement starting point: Starting point of the user program execution
 - Measurement ending point: Breakpoint in the user program

The measurement sequence is as follows.

1. Configure the measurement and initialize the counter in debug mode
 2. Start executing the user program from the measurement starting point
 3. Break on the measurement ending point and stop executing the user program
 4. Switch to debug mode and read the measurement results
- Measuring the reference time base
During this measurement, switch to debug mode at each reference time, read out the measurement results and initialize the counters.

The following two methods are available for switching to debug mode at each reference time.

- Assert a tool break from the ICE at each reference time to switch to debug mode (when connected to ICE)
- Set the interval time of a built-in timer to the reference time, and execute the INTE instruction in the timer interrupt routine to switch to debug mode

The measurement sequence is as follows.

1. Configure the measurement and initialize the counter in debug mode
2. Begin executing the measurement target user program
3. Tool break by reference time, or execute the INTE instruction by built-in timer interrupt routine
4. Switch to debug mode and read the measurement results
5. Initialize the measurement counter
6. Repeat steps 2 to 5

Analyze the measurement results using a debugger host program, such as Softune Workbench. Visualize the analysis results by displaying them in a graph so that they can be understood intuitively (pie graph, bar graph, line graph, etc.), and provide information that is beneficial for user program tuning (bus performance analysis function). The following is an analysis example.

Analysis example:

1. Bus master access proportion
Ex. Proportion of DMA access vs. CPU access, specific bus master access that occupies the total access, etc.
2. Occurred event proportion
Ex. Proportion of write access vs. read access, proportion of total cycles made up of wait cycles, etc.
3. Target accessed proportion
Ex. Proportion of MCH vs. ICH, proportion of total accesses made up of accesses to a specific target, etc.
4. Proportion of specific accesses from a specific bus master to a specific target
Ex. Proportion of total access made up of read accesses from CPU to MCH, etc.
5. Proportion of wait cycles occurring in specific target
Ex. Proportion of total cycles made up of wait cycles during MCH access
6. Analyze operation of each bus between two specific points in a program
Ex. Proportion of total cycles between two specific points in the program consisting of read, write, wait cycles, etc.
7. Analyze operation of each bus during progress of each specific time
Ex. Time course of proportion of all accesses consisting of accesses to specific bus masters and specific targets, etc.

CHAPTER : CRC

This chapter explains the CRC.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

Code : 35_MB91590_HM_E_crc_004_20111127

1. Overview

This section explains the overview of the CRC (Cyclic Redundancy Check).

This module calculates CRC values.

CRC (Cyclic Redundancy Check) is a kind of error detection methods. CRC codes are remainders left when input data strings, regarded as high-degree polynomials, are divided by predefined generator polynomials. Normally, a CRC code is attached at the end of a data string, and received data is regarded as correct if the data leaves no remainder when divided by the same generator polynomial.

2. Features

This section explains features of the CRC (Cyclic Redundancy Check).

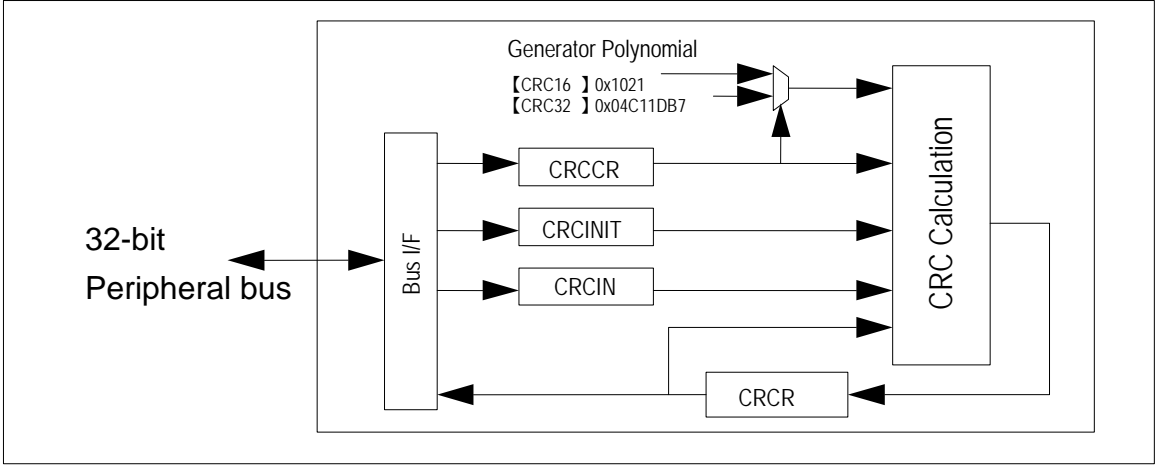
This module calculates CCITT CRC16 and IEEE-802.3 CRC32. This module cannot calculate CRC values based on other generator polynomials because the generator polynomials of this module are fixed for the values of CCITT CRC16 and IEEE-802.3 CRC32.

- CCITT CRC16 generator polynomials : 0x1021
- IEEE-802.3 CRC32 generator polynomials : 0x04C11DB7

3. Configuration

This section explains the configuration of the CRC (Cyclic Redundancy Check).

Figure 3-1 Block Diagram



4. Registers

This section explains registers of the CRC (Cyclic Redundancy Check).

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x1130	Reserved			CRCCR	CRC control register
0x1134	CRCINIT				CRC initial value register
0x1138	CRCIN				CRC input data register
0x113C	CRCR				CRC register

4.1. CRC Control Register : CRCCR

The bit configuration of the CRC control register is shown below.

This register controls the CRC calculation.

■ CRCCR : Address 1133_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	FXOR	CRCLSF	CRCLTE	LSBFST	LTLEND	CRC32	INIT
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W	R0,W

[bit7] Reserved

This bit must always be written to "0".

[bit6] FXOR (Final XOR) : Final XOR Control bit

The result is calculated XOR of "XOR value" and itself. The XOR values are ALL "H" and bit strings are inverted when FXOR = 1 is true. This process is made in the latter part of the CRC register, and the result is reflected in the CRC result readout value immediately after this bit setting.

[bit5] CRCLSF (CRC result LSb First) : CRC result bit order setting bit

This bit sets bit orders for CRC results. Changes the bit order in a byte. When this bit is "0", MSB First is applied, and when this bit is "1", LSB First is applied. This process is made in the latter part of the CRC register, and the result is reflected in the CRC result readout value immediately after this bit setting.

[bit4] CRCLTE (CRC result LiTtle-Endian) : CRC result byte order setting bit

This bit sets byte orders for CRC results. Changes the byte order in a word. When this bit is "0", big endian is applied, and when this bit is "1", little endian is applied. This process is made in the latter part of the CRC register, and the result is reflected in the CRC result readout value immediately after this bit setting. When this bit is set to 1 for CRC16, the result is output in 31 to 16 bits.

[bit3] LSBFST (LSB FirST) : Bit order setting bit

This bit sets bit orders. Specifies the first bit of a byte (8 bits). When this bit is "0", MSB First is applied, and when this bit is "1", LSB First is applied. Four patterns of process order can be specified by combining the LTLEND bit setting.

[bit2] LTLEND (LiTtLe-ENDian) : Byte order setting bit

This bit sets byte orders. This bit specifies byte orders in a writing width. When this bit is "0", big endian is applied, and when this bit is "1", little endian is applied.

[bit1] CRC32 (CRC32) : CRC mode selecting bit

This bit selects a mode for CRC16 and CRC32. When CRC32=1 is true, the arithmetic operation mode of CRC32 is applied.

[bit0] INIT (INITialize) : Initialization bit

Initialization bit. When "1" is written to this bit, software performs the initialization. This bit does not have a value and "0" is always returned at readout. In initialization, hardware loads the value of the initial value register to the CRC register. Initialization needs to be performed once at the beginning of the CRC calculation.

4.2. CRC Initial Value Register : CRCINIT

The bit configuration of the CRC initial value register is shown below.

This register sets the initial value for the CRC calculation.

■ CRCINIT : Address 1134_H (Access: Byte, Half-word, Word)

	bit31	bit30	•	•	•	bit2	bit1	bit0
	D[31:0]							
Initial value	1	1	•	•	•	1	1	1
Attribute	R/W	R/W	•	•	•	R/W	R/W	R/W

[bit31 to bit0] D[31:0] (Data) : Initialization Value bits

These bits store the initial value for the CRC calculation. Software writes the initial value for the CRC calculation. (0xFFFF_FFFF is applied after reset.) For CRC16, D15 to D0 are used and D31 to D16 are ignored.

4.3. CRC Input Data Register : CRCIN

The bit configuration of the CRC input data register is shown below.

This register sets the input data for the CRC calculation.

■ **CRCIN : Address 1138_H (Access: Byte, Half-word, Word)**

	bit31	bit30	•	•	•	bit2	bit1	bit0
	D[31:0]							
Initial value	0	0	•	•	•	0	0	0
Attribute	R/W	R/W	•	•	•	R/W	R/W	R/W

[bit31 to bit0] D[31:0] (Data) : Input Data bits

These bits set the input data for the CRC calculation. Software writes the input data for the CRC calculation. The bit width of 8, 16 or 32 is used. These bits width can be mixed. Bytes or half words can be written into any position. The address position can be +0, +1, +2 or +3 for byte writing and +0 or +2 for half word writing.

4.4. CRC Register : CRCR

The bit configuration of the CRC register is shown below.

This register outputs the result for the CRC calculation.

■ CRCR : Address 113C_H (Access: Byte, Half-word, Word)

	bit31	bit30	•	•	•	bit2	bit1	bit0
	D[31:0]							
Initial value	1	1	•	•	•	1	1	1
Attribute	R,WX	R,WX	•	•	•	R,WX	R,WX	R,WX

[bit31 to bit0] D[31:0] (Data) : CRC bits

These bits output the result for the CRC calculation. When software writes "1" to the initialization bit (CRCCR: INIT), the value of the initial value register (CRCINIT) is loaded to this register. When software writes the input data for the CRC calculation to the Input Data register (CRCIN), hardware immediately sets the CRC calculation result to this register. When all input data has been written, this register holds the final CRC code. When CRC16 is used, the result is output in D15 to D0 for big-endian (CRCLTE=0) byte order and in D31 to D16 for little-endian (CRCLTE=1) byte order.

5. Operation

This section explains the operation of the CRC (Cyclic Redundancy Check).

- 5.1. CRC Definition
- 5.2. Reset Operation
- 5.3. Initialization
- 5.4. Byte and Bit Orders
- 5.5. CRC Calculation Sequence
- 5.6. Examples

5.1. CRC Definition

This section explains the CRC (Cyclic Redundancy Check) definition.

● CCITT CRC16 Standard

Generator polynomials	0x1021	(CRCCR:CR32=0)
Initial value	0xFFFF	
Final XOR value	0x0000	(CRCCR:FXOR=0)
Bit order	MSB First	(CRCCR:LSBFST=0)
Output bit order	MSB First	(CRCCR:CRCLSF=0)

(Any byte order can be set for input and output)

● IEEE-802.3 CRC32 Ethernet Standard

Generator polynomials	0x04C11DB7	(CRCCR:CR32=1)
Initial value	0xFFFF_FFFF	
Final XOR value	0xFFFF_FFFF	(CRCCR:FXOR=1)
Bit order	LSB First	(CRCCR:LSBFST=1)
Output bit order	LSB First	(CRCCR:CRCLSF=1)

(Any byte order can be set for input and output)

5.2. Reset Operation

This section explains the reset operation of the CRC (Cyclic Redundancy Check).

To reset, set 0xFFFF_FFFF to the CRC initial value register (CRCINIT) and CRC register (CRCR). Other registers are cleared to "0".

5.3. Initialization

This section explains the initialization of the CRC (Cyclic Redundancy Check).

In initialization by CRCCR:INIT, the value of the initial value register is loaded to the CRC register (CRCR).

5.4. Byte and Bit Orders

This section explains the byte and bit orders of the CRC (Cyclic Redundancy Check).

This section explains the byte and bit orders using examples. Inputs the following one word to the CRC calculator.

133.82.171.1 = 10000101 01010010 10101011 00000001

When the byte order is big endian (CRCCR:LTLEND=0), the transmission sequence in bytes is:

10000101	01010010	10101011	00000001
(First)	(Second)	(Third)	(Fourth)

When the bit order is LSB First (CRCCR:LSBFST=1), the transmission sequence in bits is:

10100001	01001010	11010101	10000000
(first)			(last)

Notes:

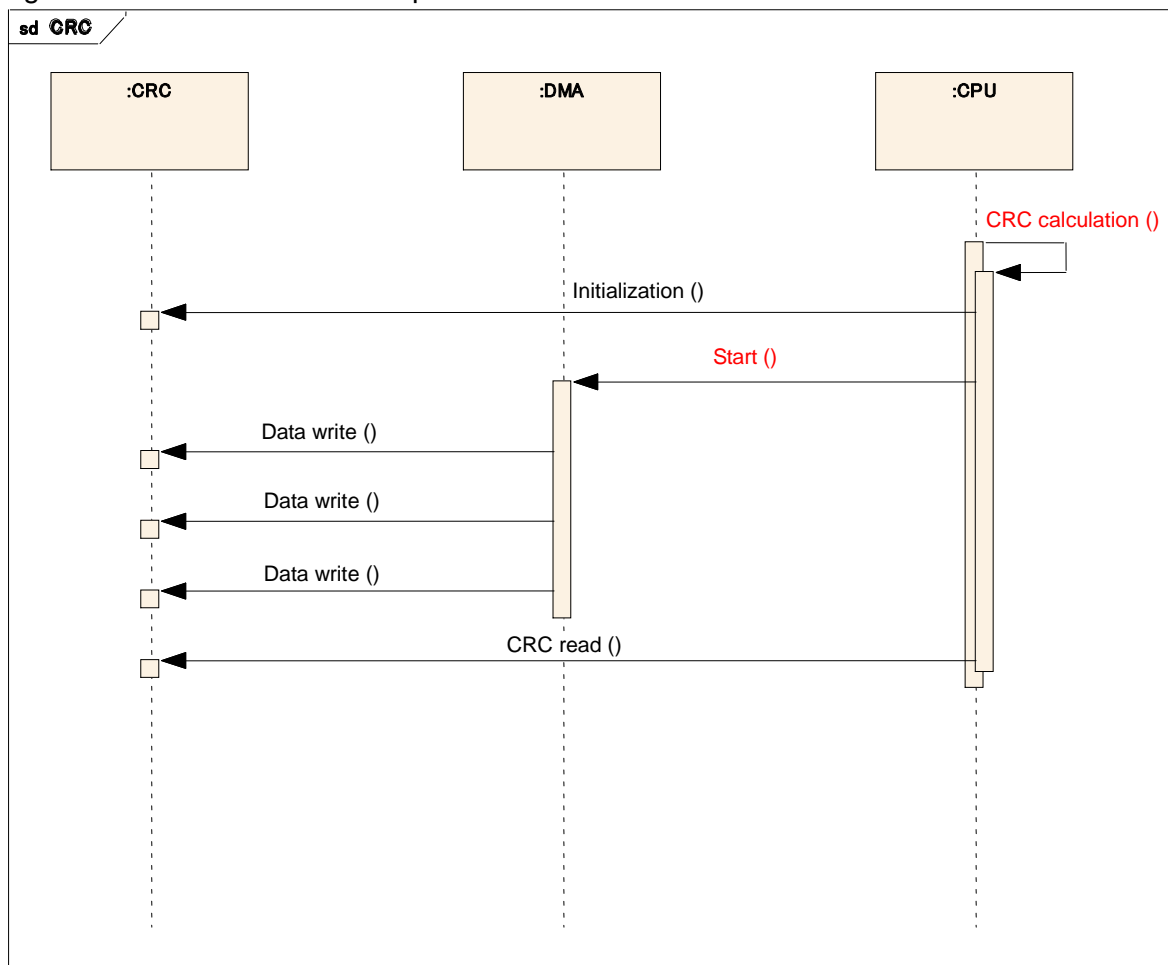
- When CRCCR:CRCLTE=1 is true, the byte order for the CRC result is changed in 32-bit width both for CRC16 and CRC32.
 - Note that output position for CRC16 is bit31 to bit16.
-

5.5. CRC Calculation Sequence

This section explains the CRC calculation sequence of the CRC.

The sequence for the CRC calculation is shown below. In the following explanation, the CRC initial value register (CRCINIT) setting, CRC16/32 selection (CRCCR: CRC32), byte order and bit order settings (CRCCR:LTLEND, CRCCR:LSBFST) have been done. (When the initial value of ALL "H" is acceptable, the setting for the initial value register (CRCINIT) can be omitted.)

Figure 5-1 CRC Calculation Sequence



- To initialize, write "1" to the initialization bit (CRCCR:INIT). The value of the initial value register will be loaded to the CRC register (CRCR).
- Input data is written to the CRC Input Data register (CRCIN). The writing operation starts the CRC calculation. Input data can be written continuously. In addition, there can be different bit widths of writing in a sequence.
- The CRC code is obtained with the readout of the CRC register (CRCR).

5.6. Examples

This section explains examples of the Cyclic Redundancy Check (CRC) operation.

- 5.6.1. Example 1 CRC16, Fixed Byte Input
- 5.6.2. Example 2 CRC16, Mixture of Different Input Bit Widths
- 5.6.3. Example 3 CRC32, Byte Order, Big-endian
- 5.6.4. Example 4 CRC32, Byte Order, Little-endian

5.6.1. Example 1 CRC16, Fixed Byte Input

Example 1 CRC16 and fixed byte input are shown below.

Figure 5-2 Example 1

```

//*****
// CRC16 (CRC ITU-T)
// polynomial: 0x1021
// initial value: 0xFFFF
// CRCCR.CRC32: 0 // CRC16
// CRCCR.LTLEND: 0 // big endian
// CRCCR.LSBFST: 0 // MSB First
// CRCCR.CRCLTE: 0 // CRC big endian
// CRCCR.CRCLSF: 0 // CRC MSB First
// CRCCR.FXOR: 0 // CRC Final XOR off
//*****

//
// Example 1-1 (Byte-unit writing)
//

// Initialization
B_WRITE (CRCCR, 0x01);

// data write "123456789"
B_WRITE (CRCIN, 0x31);
B_WRITE (CRCIN, 0x32);
B_WRITE (CRCIN, 0x33);
B_WRITE (CRCIN, 0x34);
B_WRITE (CRCIN, 0x35);
B_WRITE (CRCIN, 0x36);
B_WRITE (CRCIN, 0x37);
B_WRITE (CRCIN, 0x38);
B_WRITE (CRCIN, 0x39);

// read result
H_READ (CRCCR+2, data);

// check result
assert (data == 0x29B1);

//
// Example 1-2 (CRC check)
//

// Initialization
B_WRITE (CRCCR, 0x01);

// data write "123456789" + CRC
B_WRITE (CRCIN, 0x31);
B_WRITE (CRCIN, 0x32);
B_WRITE (CRCIN, 0x33);
B_WRITE (CRCIN, 0x34);
B_WRITE (CRCIN, 0x35);
B_WRITE (CRCIN, 0x36);
B_WRITE (CRCIN, 0x37);
B_WRITE (CRCIN, 0x38);
B_WRITE (CRCIN, 0x39);
B_WRITE (CRCIN, 0x29); // <-- CRC
B_WRITE (CRCIN, 0xB1); // <-- CRC

// read result
H_READ (CRCCR+2, data);

// check result
assert (data == 0x0000);

```

(The following is assumed)

B_WRITE -- Byte writing
H_WRITE -- Half-word writing
W_WRITE -- Word writing

B_READ -- Byte reading
H_READ -- Half-word reading
W_READ -- Word reading

CRCCR -- Control register address
CRCINIT -- Initial value register address
CRCIN -- Input data register address
CRCCR -- Current CRC register address

Image of input order into CRC calculator

- Bytes and half words can be written into any position. In this example, data is written into +0 position continuously.
- When CRC16 is used, the CRC result is output in bit15 to bit0 for big-endian byte order and thus the address for H_READ (Half-word reading) is +2 in the example.

5.6.2. Example 2 CRC16, Mixture of Different Input Bit Widths

Example 2 CRC16 and Mixture of Different Input Bit Widths are shown below.

Figure 5-3 Example 2

```

//*****
// CRC16 (CRC ITU-T)
// polynomial: 0x1021
// initial value: 0xFFFF
// CRCCR.CRC32 0 // CRC16
// CRCCR.LTLEND: 0 // big endian
// CRCCR.LSBFST: 0 // MSB First
// CRCCR.CRCLTE: 0 // CRC big endian
// CRCCR.CRCLSF: 0 // CRC MSB First
// CRCCR.FXOR: 0 // CRC Final XOR off
//*****

//
// Example 2-1 (Mixture of writing size)
//

// Initialization
B_WRITE (CRCCR, 0x01);

// data write "123456789"
W_WRITE (CRCIN, 0x31323334);
H_WRITE (CRCIN, 0x3556);
H_WRITE (CRCIN+2, 0x3738);
B_WRITE (CRCIN+3, 0x39);

// read result
H_READ (CRCCR+2, data);

// check result
assert (data == 0x29B1);

//
// Example 2-2 (CRC check)
//

// Initialization
B_WRITE (CRCCR, 0x01);

// data write "123456789" + CRC
W_WRITE (CRCIN, 0x31313334);
W_WRITE (CRCIN, 0x35363738);
H_WRITE (CRCIN, 0x3929); // <-- CRC(0x29)
B_WRITE (CRCIN, 0xB1); // <-- CRC(0xB1)

// read result
H_READ (CRCCR+2, data);

// check result
assert (data == 0x0000);

```

(The following is assumed)

B_WRITE -- Byte writing
H_WRITE -- Half-word writing
W_WRITE -- Word writing

B_READ -- Byte reading
H_READ -- Half-word reading
W_READ -- Word reading

CRCCR -- Control register address
CRCINIT -- Initial value register address
CRCIN -- Input data register address
CRCCR -- Current CRC register address

Image of input order into CRC calculator

- When the byte and bit orders are set correctly and the orders to input bits to the CRC calculator are the same, any writing width can be used.
- For example, there is a case that words are written basically and bytes or a half word is written if there is a fraction of 1, 2, or 3 bytes at the end.

5.6.3. Example 3 CRC32, Byte Order, Big-endian

Example 3 CRC32, the byte order and big-endian are shown below.

Figure 5-4 Example 3

```

//*****
// CRC32 (IEEE-802.3)
// polynomial: 0x04C11DB7
// initial value: 0xFFFF_FFFF
// CRCCR.CRC32 1 // CRC32
// CRCCR.LTLEND: 0 // big endian
// CRCCR.LSBFST: 1 // LSB First
// CRCCR.CRCLTE: 0 // CRC big endian
// CRCCR.CRCLSF: 1 // CRC LSB First
// CRCCR.FXOR: 1 // CRC Final XOR on
//*****

//
// Example 3-1 (CRC32)
//

// Initialization
B_WRITE (CRCCR, 0x6B);

// data write "123456789"
W_WRITE (CRCIN, 0x31323334);
W_WRITE (CRCIN, 0x35363738);
B_WRITE (CRCIN, 0x39);

// read result
W_READ (CRCR, data);

// check CRC result
assert (data == 0x2639F4CB);
// <- big endian & LSB First

```

(The following is assumed)

B_WRITE -- Byte writing
H_WRITE -- Half-word writing
W_WRITE -- Word writing

B_READ -- Byte reading
H_READ -- Half-word reading
W_READ -- Word reading

CRCCR -- Control register address
CRCINIT -- Initial value register address
CRCIN -- Input data register address
CRCR -- Current CRC register address

Image of input order into CRC calculator

3	1	3	2	3	3	3	4
←←←←←←←←							
3	5	3	6	3	7	3	8
←←←←←←←←							
3	9						
←←←←←							

Top

CRC result (inside macro)							
9	B	6	3	D	0	2	C

Top

2	6	3	9	F	4	C	B
---	---	---	---	---	---	---	---

CRC output (FXOR and rearrangement)

When CRC32 (IEEE-802.3) is used, the bit order is LSB First. This CRC calculator supports both byte orders and the figure above shows the case for big endian.

5.6.4. Example 4 CRC32, Byte Order, Little-endian

Example 4 CRC32, the byte order and Little-endian are shown below.

Figure 5-5 Example 4

```

//*****
// CRC32 (IEEE-802.3)
// polynomial: 0x04C11DB7
// initial value: 0xFFFF_FFFF
// CRCCR.CRC32 1 // CRC32
// CRCCR.LTLEND: 1 // little endian
// CRCCR.LSBFST: 1 // LSB First
// CRCCR.CRCLTE: 1 // CRC little endian
// CRCCR.CRCLSF: 1 // CRC LSB First
// CRCCR.FXOR: 1 // CRC Final XOR on
//*****

//
// Example 4-1 (CRC32)
//

// Initialization
B_WRITE (CRCCR, 0x7F);

// data write "123456789"
W_WRITE (CRCIN, 0x34333231);
W_WRITE (CRCIN, 0x38373635);
B_WRITE (CRCIN, 0x39);

// read result
W_READ (CRCCR, data);

// check result
assert (data == 0xCBF43926);
// <- little endian & LSB First

```

(The following is assumed)

B_WRITE -- Byte writing
H_WRITE -- Half-word writing
W_WRITE -- Word writing

B_READ -- Byte reading
H_READ -- Half-word reading
W_READ -- Word reading

CRCCR -- Control register address
CRCINIT -- Initial value register address
CRCIN -- Input data register address
CRCCR -- Current CRC register address

Image of input order into CRC calculator

- When CRC32 (IEEE-802.3) is used, the bit order is LSB First. This CRC calculator supports both byte orders and the figure above shows the case for little endian.
- When bit inversion for CRC results is not needed, the bit inversion for the current results can be canceled either by calculation through initialization using 0x3F, or setting of CRCCR:FXOR to 0 (Example: CRCCR=0x3E) after data entry.

CHAPTER : RAMECC

This chapter explains the RAMECC.

1. Overview
2. Features
3. Configuration
4. Registers

Code : 36_MB91590_HM_E_ramecc_006_20111128

1. Overview

This section provides the overview of the RAMECC.

The RAMECC has a dual function in order to increase RAM's tolerance to soft error while the CPU is writing to or reading from the RAM. One function is to correct a single bit error in 1-byte units, and the other is to generate and check the code to detect a double-bit error in 1-byte units as well.

2. Features

This section explains features of the RAMECC.

- Target RAM:
XBS RAM: 64K bytes
Backup RAM: 8K bytes
- ECC: 5-bit ECC is added by byte. Single-bit error correction and double-bit error detection are enabled.
- Interrupt function : Single bit error is perceived and RAM single bit error interrupt signal is generated, and a double bit error is perceived and RAM double bit error interrupt signal is generated.
- Test function : A pseudo error occurs for the software debugging.

3. Configuration

This section shows the configuration of the RAMECC.

Figure 3-1 Block Diagram (XBS RAM)

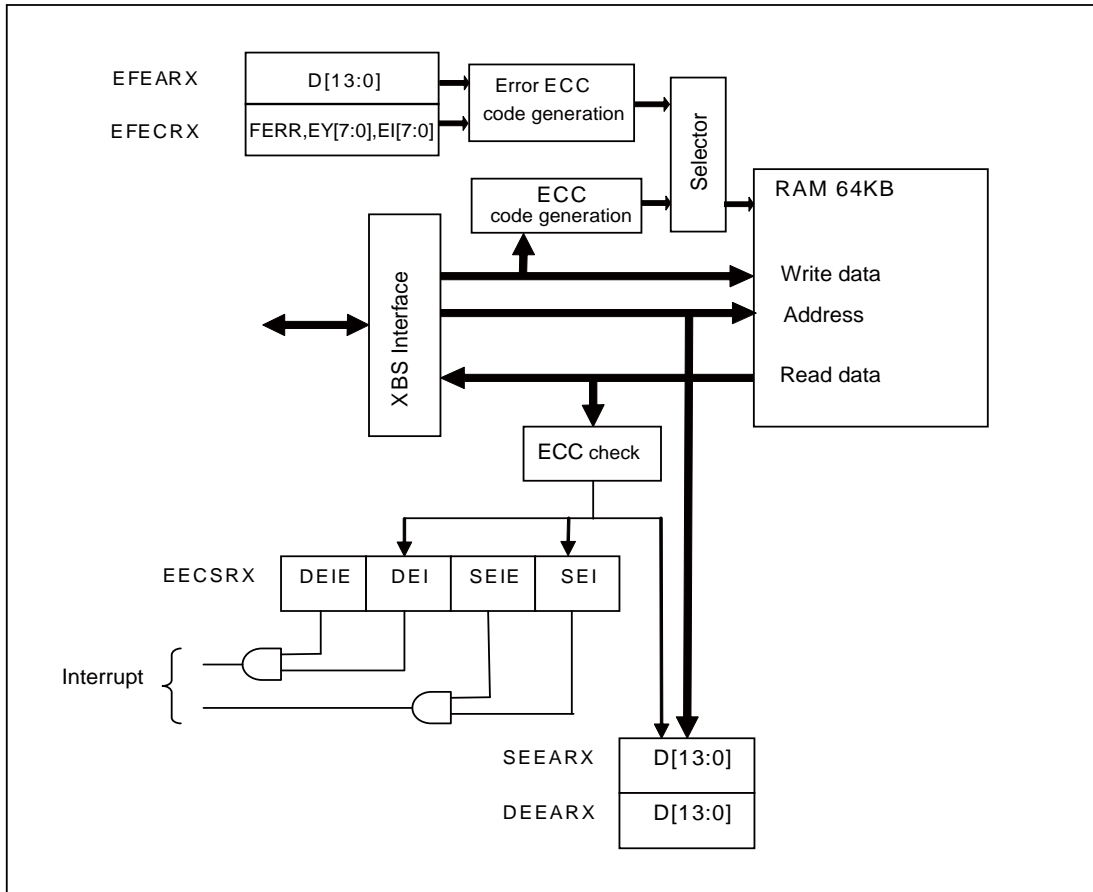
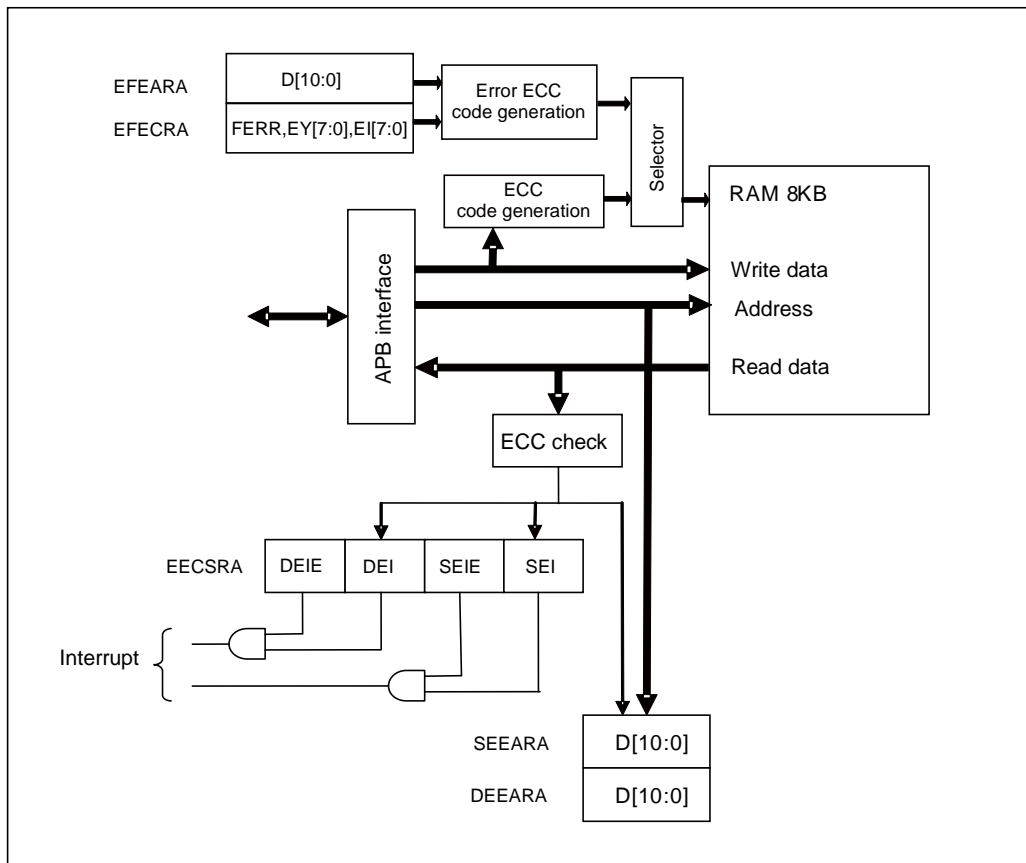


Figure 3-2 Block Diagram (Backup RAM)



4. Registers

This section explains the registers of the RAMECC.

Table 4-1 Registers Map

Address	Registers				Register Function
	+0	+1	+2	+3	
0x2400	SEEARX		DEEARX		Single-bit ECC error address register XBS RAM Double-bit ECC error address register XBS RAM
0x2404	EECSRX	Reserved	EFEARX		ECC error control register XBS RAM ECC flase error address register XBS RAM
0x2408	Reserved	EFECRX			ECC flase error control register XBS RAM
0x3000	SEEARA		DEEARA		Single-bit ECC error address register BACKUP-RAM Double-bit ECC error address register BACKUP-RAM
0x3004	EECSRA	Reserved	EFEARA		ECC error control register BACKUP-RAM ECC flase error address register BACKUP-RAM
0x3008	Reserved	EFECRA			ECC flase error control register BACKUP-RAM

4.1. ECC Error Control Register XBS RAM : EECSR_X (Ecc Error Control and Status Register Xbs ram)

The bit configuration of the ECC error control register XBS RAM is explained.

During the ECC check of XBS RAM, this register maintains the status that indicates whether or not the single-bit error correction or the double-bit error detection has been performed and specifies whether or not to enable interrupts by such events.

■ EECSR_X : Address 2404_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				DEIE	DEI	SEIE	SEI
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R(RM1),W	R/W	R(RM1), W

[bit7 to bit4] Reserved

Always write "0". Reading these bits returns "0".

[bit3] DEIE : Double-bit error factor interrupt enable bit

DEIE	Description of Setting
0	Disables interrupts.
1	Enables interrupts.

[bit2] DEI : Double-bit error occurrence bit

DEI	Read	Write
0	Double-bit error has not occurred.	Clears this bit.
1	Double-bit error has occurred.	No effect.

[bit1] SEIE : Single-bit error factor interrupt enable bit

SEIE	Description of Setting
0	Disables interrupts.
1	Enables interrupts.

[bit0] SEI : Single-bit error occurrence bit

SEI	Read	Write
0	Single-bit error has not occurred.	Clears this bit.
1	Single-bit error has occurred.	No effect.

4.2. Single-bit ECC Error Address Register XBS RAM : SEEARX (Single bit Ecc Error Address Register Xbs ram)

The bit configuration of the single-bit ECC error address register XBS RAM is explained.

When the single-bit error correction is performed during the ECC check of XBS RAM, this register maintains the address at which it occurred.

■ SEEARX : Address 2400_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved		D13	D12	D11	D10	D9	D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit15, bit14] Reserved

Reading these bits returns "0".

[bit13 to bit0] D13 to D0 : Single-bit error occurrence address bits

When the single-bit error correction is performed during the ECC check, these bits maintain the address at which it occurred.

If the event above is further detected when a value has already been set to these bits, the original value is maintained without overwriting these bits.

Note:

The address above is offset in words. Calculate the absolute address by adding the lower 2 bits to the offset address mentioned above, and then adding the base address of XBS RAM.

(Absolute address) = (0x00010000) + (Offset indicated by SEEARX +2b'00)

4.3. Double-bit ECC Error Address Register XBS RAM : DEEARX (Double bit Ecc Error Address Register Xbs ram)

The bit configuration of the double-bit ECC error address register XBS RAM is explained.

When the double-bit error detection is performed during the ECC check of XBS RAM, this register maintains the address at which it occurred.

■ **DEEARX : Address 2402_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved		D13	D12	D11	D10	D9	D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit15, bit14] Reserved.

Reading these bits returns "0".

[bit13 to bit0] D13 to D0 : Double-bit error occurrence address bits

When the double-bit error detection is performed during the ECC check, these bits maintain the address at which it occurred.

If the event above is further detected when a value has already been set to these bits, the original value is maintained without overwriting these bits.

Note:

The address above is offset in words. Calculate the absolute address by adding the lower 2 bits to the offset address mentioned above, and then adding the base address of XBS RAM.
(Absolute address) = (0x00010000)+(Offset indicated by DEEARX +2b'00)

4.4. ECC False Error Generation Address Register XBS RAM : EFEARX (Ecc False Error Address Register Xbs ram)

The bit configuration of the ECC false error (a pseudo ECC error) generation address register (EFEARX) is explained.

The ECC false error (a pseudo ECC error) generation address register (EFEARX) specifies the address where a false error (a pseudo error) is generated.

■ EFEARX : Address 2406_H (Access : Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved		D13	D12	D11	D10	D9	D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15,bit14] Reserved

Always write "0". Reading these bits returns "0".

[bit3 to bit0] D13 to D0 : False error generation address setting bits

These bits set the address where false ECC error (a pseudo ECC error) is caused.

ECC error is caused because the write access to this address is generated at EFECRX:FERR ="1", and the written data contains the error according to the setting of EFECRX by intention.

4.5. ECC False Error Generation Control Register XBS RAM : EFECRX (Ecc False Error Control Register Xbs ram)

The bit configuration of the ECC false error (a pseudo ECC error) generation control register (EFECRX) is explained.

The ECC false error (a pseudo ECC error) generation control register (EFECRX) specifies each false error by its byte position and its bit position where the false error is generated.

■ EFECRX : Address 2409_H (Access : Byte, Half-word, Word)

	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	Reserved							FERR
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R/W

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	EY7	EY6	EY5	EY4	EY3	EY2	EY1	EY0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EI7	EI6	EI5	EI4	EI3	EI2	EI1	EI0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit23 to bit17] Reserved

Always write "0". Reading these bits returns "0".

[bit16] FERR : false error generation enable bit

FERR	Description of Setting
0	false error (a pseudo error) generation disable
1	false error (a pseudo error) enable

[bit15 to bit8] EY7 to EY0 : false error generation byte setting bits

These bits specify byte position of the target that causes false ECC error (a pseudo ECC error).

EYn	Target byte on RAM
EY0	RAM data[7:0]
EY1	RAM data[15:8]
EY2	RAM data[23:16]
EY3	RAM data[31:24]
EY4	RAM data[36:32]
EY5	RAM data[41:37]
EY6	RAM data[46:42]
EY7	RAM data[51:47]

For example, when EY2 is filled with "1" and other EYn's are filled with "0", the target byte where a false error (a pseud error) is generated is RAM data[23:16] only. In other bytes on the RAM, no false error is generated.

In addition to the foregoing, when both EY2 and EY3 are filled with "1" and others are filled with "0", the target byte where a false error is generated is RAM data[31:16].

[bit7 to bit0] EI7 to EI0 : false error generation bit setting bits

These bits specify bit position of the target that causes false ECC error (a pseudo ECC error).

EIn	Target bit on byte
EI0	bit0
EI1	bit1
EI2	bit2
EI3	bit3
EI4	bit4
EI5	bit5
EI6	bit6
EI7	bit7

For example, when both EY2 and EI4 are filled with "1", and others are filled with "0", the target bit where a false error (a pseudo error) is generated is RAM data[20]. As a result, a single bit error can be corrected.

In addition to the foregoing, when EY2, EI4, and EI7 are filled with "1", and others are filled with "0", the target bits where a false error (a pseud error) is generated are RAM data[23] and RAM data[20]. As a result, a double bit error can be detected.

Moreover, when EY2, EY3, and EI4 are filled with "1", and others are filled with "0", the target bits where a false error (a pseudo error) is generated are RAM data[28] and RAM data[20]. As a result, a single bit error can be corrected in each byte.

4.6. ECC Error Control Register BACKUP-RAM : EECSRA (Ecc Error Control and Status Register bAckup-ram)

The bit configuration of the ECC error control register BACKUP-RAM is explained.

During the ECC check of Backup RAM, this register maintains the status that indicates whether or not the single-bit error correction or the double-bit error detection has been performed and specifies whether or not to enable interrupts by such events.

■ EECSRA : Address 3004_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved				DEIE	DEI	SEIE	SEI
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R(RM1),W	R/W	R(RM1), W

[bit7 to bit4] Reserved

Always write "0". Reading these bits returns "0".

[bit3] DEIE : Double-bit error factor interrupt enable bit

DEIE	Description of Setting
0	Disables interrupts.
1	Enables interrupts.

[bit2] DEI : Double-bit error occurrence bit

DEI	Read	Write
0	Double-bit error has not occurred.	Clears this bit.
1	Double-bit error has occurred.	No effect.

[bit1] SEIE : Single-bit error factor interrupt enable bit

SEIE	Description of Setting
0	Disables interrupts.
1	Enables interrupts.

[bit0] SEI : Single-bit error occurrence bit

SEI	Read	Write
0	Single-bit error has not occurred.	Clears this bit.
1	Single-bit error has occurred.	No effect.

4.7. Single-bit ECC Error Address Register BACKUP-RAM : SEEARA (Single bit Ecc Error Address Register bAckup-ram)

The bit configuration of the single-bit ECC error address register BACKUP-RAM is explained.

When the single-bit error correction is performed during the ECC check of Backup RAM, this register maintains the address at which it occurred.

■ SEEARA : Address 3000_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved					D10	D9	D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R,WX	R,WX	R,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit15 to bit11] Reserved

Reading these bits returns "0".

[bit10 to bit0] D10 to D0 : Single-bit error occurrence address bits

When the single-bit error correction is performed during the ECC check, these bits maintain the address at which it occurred.

If the events above is further detected when a value has already been set to these bits, the original value is maintained without overwriting these bits.

Note:

The address above is offset in words. Calculate the absolute address by adding the lower 2 bits to the offset address mentioned above, and then adding the base address of Backup RAM.
(Absolute address) = (0x00004000) + (Offset indicated by SEEARA +2b'00)

4.8. Double-bit ECC Error Address Register BACKUP-RAM : DEEARA (Double bit Ecc Error Address Register bAckup-ram)

The bit configuration of the double-bit ECC error address register BACKUP-RAM is explained.

When the double-bit error detection is performed during the ECC check of Backup RAM, this register maintains the address at which it occurred.

■ DEEARA : Address 3002_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved					D10	D9	D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R,WX	R,WX	R,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit15 to bit11] Reserved

Reading these bits returns "0".

[bit10 to bit0] D10 to D0 : Double-bit error occurrence address bits

When double-bit error detection is performed during the ECC check, these bits maintain the address at which it occurred.

If the event above is further detected when a value has already been set to these bits, the original value is maintained without overwriting these bits.

Note:

The address above is offset in words. Calculate the absolute address by adding the lower 2 bits to the offset address mentioned above, and then adding the base address of Backup RAM.
(Absolute address) = (0x00004000) + (Offset indicated by DEEARA + 2b'00)

4.9. ECC False Error Generation Address Register BACKUP-RAM : EFEARA (Ecc False Error Address Register bAckup-RAM)

The bit configuration of the ECC false error (a pseudo ECC error) generation address register BACKUP-RAM is explained.

The ECC false error (a pseudo ECC error) generation address register (EFEARA) specifies the address where a false error (a pseudo error) is caused.

■ EFEARA : Address 3006_H (Access : Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved					D10	D9	D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit11] Reserved

Always write "0". Reading these bits returns "0".

[bit10 to bit0] D10 to D0 : False error generation address setting bits

These bits set the address where false ECC error (a pseudo ECC error) is caused.

ECC error is caused because the write access to this address is generated at EFECRA:FERR ="1", and the written data contains the error according to the setting of EFECRA by intention.

4.10. ECC False Error Generation Control Register BACKUP-RAM : EFECRA (Ecc False Error Control Register bAckup-RAM)

The bit configuration of the ECC false error (a pseudo ECC error) generation control register BACKUP-RAM is explained.

The ECC false error (a pseudo ECC error) generation control register (EFECRA) specifies each false error by its byte position and its bit position where the false error is generated.

■ EFECRA: Address 3009_H (Access : Byte, Half-word, Word)

	bit23	bit22	bit21	bit20	bit19	bit18	bit17	bit16
	Reserved							FERR
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R/W
	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	EY7	EY6	EY5	EY4	EY3	EY2	EY1	EY0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EI7	EI6	EI5	EI4	EI3	EI2	EI1	EI0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit23 to bit17] Reserved

Always write "0". Reading these bits returns "0".

[bit16] FERR : false error generation enable bit

FERR	Description of Setting
0	false error (a pseudo error) generation disable
1	false error (a pseudo error) enable

[bit15 to bit8] EY7 to EY0 : false error generation byte setting bits

These bits specify byte position of the target that causes false ECC error (a pseudo ECC error).

EYn	Target byte on RAM
EY0	RAM data[7:0]
EY1	RAM data[15:8]
EY2	RAM data[23:16]
EY3	RAM data[31:24]
EY4	RAM data[36:32]
EY5	RAM data[41:37]
EY6	RAM data[46:42]
EY7	RAM data[51:47]

For example, when EY2 is filled with "1" and other EYn's are filled with "0", the target byte where a false error (a pseud error) is generated is RAM data[23:16] only. In other bytes on the RAM, no false error is generated.

In addition to the foregoing, when both EY2 and EY3 are filled with "1" and others are filled with "0", the target byte where a false error is generated is RAM data[31:16].

[bit7 to bit0] EI7 to EI0 : false error generation bit setting bits

These bits specify bit position of the target that causes false ECC error (a pseudo ECC error).

EIn	Target bit on byte
EI0	bit0
EI1	bit1
EI2	bit2
EI3	bit3
EI4	bit4
EI5	bit5
EI6	bit6
EI7	bit7

For example, when both EY2 and EI4 are filled with "1", and others are filled with "0", the target bit where a false error (a pseudo error) is generated is RAM data[20]. As a result, a single bit error can be corrected.

In addition to the foregoing, when EY2, EI4, and EI7 are filled with "1", and others are filled with "0", the target bits where a false error (a pseud error) is generated are RAM data[23] and RAM data[20]. As a result, a double bit error can be detected.

Moreover, when EY2, EY3, and EI4 are filled with "1", and others are filled with "0", the target bits where a false error (a pseudo error) is generated are RAM data[28] and RAM data[20]. As a result, a single bit error can be corrected in each byte.

5. Operation

This section explains operations of the RAMECC.

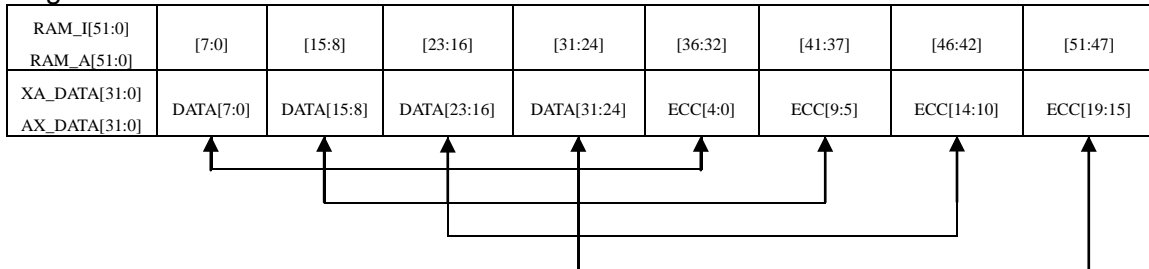
- 5.1. ECC Generation
- 5.2. ECC Inspection
- 5.3. Interrupt by Error Detection
- 5.4. Test Function

5.1. ECC Generation

The ECC generation is explained.

ECC for the unit of 8-bit (1 byte) is generated to the data of 32-bit on the XBS interface.

Figure 5-1 Relation between XBS Data and RAM Data



The relation between the XBS data (XA_DATA[31:0] / AX_DATA[31:0]) and RAM data (RAM_I [51:0] / RAM_A[51:0]) is defined as shown in the figure above. The one connected by the arrow in the figure is a pair of DATA and ECC. (Example: 8-bit {XA_DATA[15:8] / AX_DATA[15:8]} is stored in {RAM_I[15:8] / RAM_A[15:8]} as RAM data, and ECC[9:5] corresponding to it is stored in {RAM_I[41:37] / RAM_A[41:37]} as RAM data.)

Moreover, the (13,8) odd number weight sign shown in the table below is adopted as ECC sign matrix.

Table 5-1 ECC Sign Matrix

	1	2	3	4	5	6	7	8	9	10	11	12	13
1	1	0	0	1	1	1	0	1	1	0	0	0	0
2	1	1	0	0	1	0	1	0	0	1	0	0	0
3	1	1	1	0	0	1	0	1	0	0	1	0	0
4	0	1	1	1	0	1	1	0	0	0	0	1	0
5	0	0	1	1	1	0	1	1	0	0	0	0	1

As a result, each bit of ECC can be calculated by requesting 5 or 6 exclusive-OR from the data of 8 bits.

This forms the inspection matrix, and the generation matrix is requested by the transposed matrix of 5×8 matrix up to eight rows and the combinations with the unit matrix.

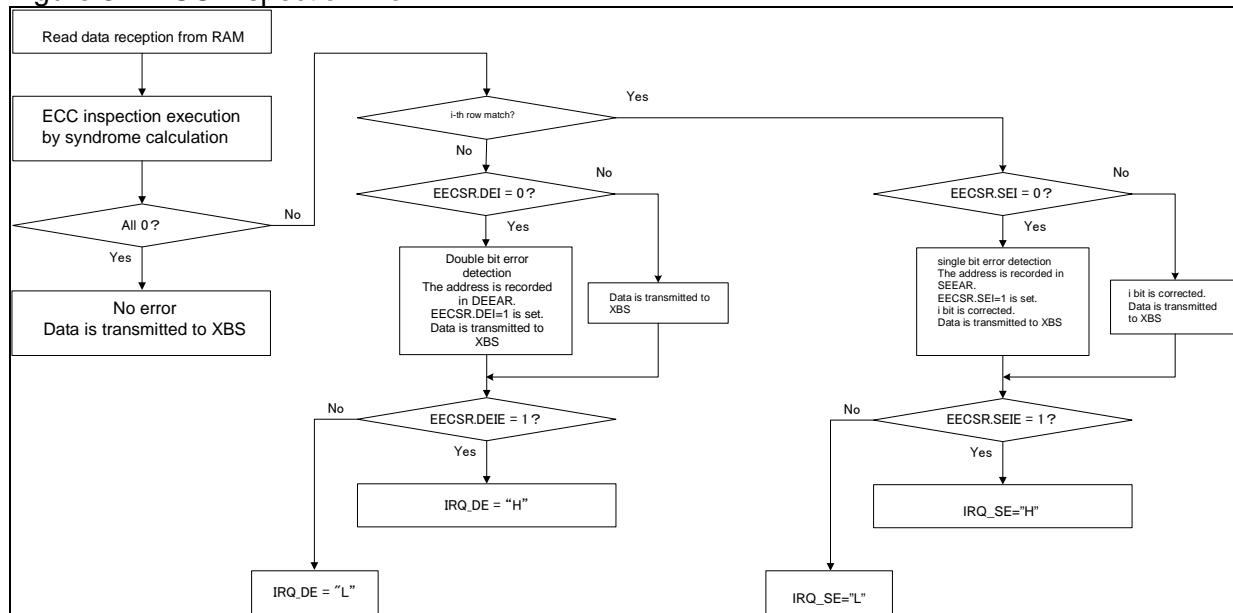
It is necessary to be going to generate ECC in one clock cycle after the XBS data is received, and to complete writing in RAM.

5.2. ECC Inspection

The ECC inspection is explained.

The inspection is executed by constructing the sign vector of 13-bit including ECC with the data that exists on RAM as shown in Figure 5-1, and using the inspection matrix of Table 5-1 according to the procedure of the figure below.

Figure 5-2 ECC Inspection Flow



5.3. Interrupt by Error Detection

This section explains the interrupt at the error detection.

When the ECC error is detected, the interrupt can be generated. Write "1" in the DEIE bit and the SEIE bit according to the usage to generate the interrupt, and set the RAMECC interrupt vector and the interrupt level.

Interrupt factor	Interrupt vector	Interrupt level
SEI (RAM single-bit error interrupt)	#61(000FFF08 _H)	ICR45
DEI (RAM double-bit error interrupt)	#15(000FFFC0 _H)	15(F _H) Fixed

See "CHAPTER: INTERRUPT CONTROL(INTERRUPT CONTROLLER)" for details of the interrupt level and the interrupt vector.

Since the interrupt request flag (DEI, SEI) is not automatically cleared, clear the flag forcibly with software before the status of the MCU returns from the interrupt. (Write "0" into the DEI bit and the SEI bit).

The interrupt at the NMI level is generated when a double-bit error is detected because the error data is read without any correction.

5.4. Test Function

Test function is explained.

An ECC false error (a pseudo ECC error) is generated in order to debug software.

The ECC false error (a pseudo ECC error) is generated in accordance with the following procedures.

1. The address where a false error (a pseudo error) is caused in ECC false error (a pseudo ECC error) generation address register (EFEARX/ EFEARA) is specified.
2. The byte and the bit are set by ECC false error (a pseudo ECC error) generation control register (EFECRX/EFECRA).
 - (a) Byte position in which a false error (a pseudo error) EFECRX:EY[7:0]/EFECRA:EY[7:0] is caused is specified.
 - (b) The bit position that causes a false error (a pseudo error) EFECRX:EI[7:0]/EFECRA:EI[7:0] is specified.
3. The FERR bit of ECC false error (a pseudo ECC error) generation control register (EFECRX/ EFECRA) is written "1".

The CPU starts writing the data, which intentionally includes error, into the address specified with EFEARX/EFEARA. The byte position and bit position in the address are specified with EY[7:0] and EI[7:0], respectively. Then the CPU reads the data subsequently, detecting the false error (a pseudo ECC error).

CHAPTER : MULTI FUNCTION SERIAL INTERFACE

This chapter explains the multi function serial interface.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation of UART
6. Operation of CSIO
7. Operation of LIN-UART
8. Operation of I²C

1. Overview

This section explains the overview of the multi function serial interface.

This module provides, UART (Asynchronous Serial Interface), CSIO(SPI supported, Clock Synchronous Serial Interface), LIN-UART(LIN Processing Hardware Attached Serial Interface) and I²C serial communication function.

2. Features

This section explains features of the multi function serial interface.

This product is equipped with 2-channel multi function serial interface communication module. To use this device, you will select UART, CSIO, LIN-UART, or I²C using the serial mode register (SMR).

2.1. UART

This section explains UART of the multi function serial interface.

UART (asynchronous serial interface) is the general-purpose serial data communication interface designed to communicate with external devices asynchronously (start-stop synchronization). It supports the bidirectional communication function (normal mode), master/slave type communication function (multi-processor mode: both master and slave are supported). It is also equipped with FIFO for transmission/reception.

Name	Function
Data	<ul style="list-style-type: none"> · Full-duplex double buffering (when FIFO is unused) · Transmission/reception FIFO (16 bytes each) (when FIFO is used)
Serial input	Execute over-sampling for three times and determine the reception value by the majority of the sampling value.
Transfer format	Asynchronous
Baud rate	<ul style="list-style-type: none"> · Dedicated baud rate generator (comprising 15-bit reload counter) · External clock input can be adjusted by the reload counter
Data length	<ul style="list-style-type: none"> · 5-9 bits (normal mode), 7, 8 bits (multi-processor mode)
Signaling system	NRZ (Non Return to Zero), Inverted NRZ
Start bit detection	<ul style="list-style-type: none"> · Synchronize with the start bit falling edge (NRZ system) · Synchronize with the start bit rising edge (inverted NRZ system)
Reception error detection	<ul style="list-style-type: none"> · Framing error · Overrun error · Parity error*
Interrupt request	<ul style="list-style-type: none"> · Reception interrupt (Reception completed, framing error, overrun error, parity error*) · Transmission interrupt (transmission data empty, transmission bus idle) · Transmission FIFO interrupt (when the transmission FIFO is empty) · Both transmission and reception have the DMA function
Master/slave mode communication function (multi-processor mode)	1 (Master)-to-n (slave) communication is supported (both master and slave systems are supported)
FIFO option	<ul style="list-style-type: none"> · Transmission/reception FIFO equipped (transmission FIFO: 16 bytes, reception FIFO: 16 bytes) · Transmission FIFO and reception FIFO can be selected · Transmission data can be retransmitted · Reception FIFO interrupt timing can be modified by software · FIFO reset is supported independently
DMA transfer support	Transmission: Supported Reception: Supported

*: Parity error is for the normal mode only.

2.2. CSIO

This section explains CSIO of the multi function serial interface.

CSIO (Clock Synchronous Serial Interface) is a general-purpose serial data communication interface for synchronous communication with external devices. (SPI supported) It is also equipped with the FIFO for transmission/reception (16 bytes each).

	Function
Data buffer	<ul style="list-style-type: none"> · Full-duplex double buffering(when FIFO is unused) · Transmission/reception FIFO (16 bytes each) (when FIFO is used)
Transfer format	<ul style="list-style-type: none"> · Clock synchronous (without start bit/stop bit) · Master/slave function · SPI supported (both master/slave mode supported)
Baud rate	<ul style="list-style-type: none"> · Dedicated baud rate generator provided (comprising 15-bit reload counter, master mode) · An external clock can be entered. (Slave operation)
Data length	Can be changed to 5-9 bits
Reception error detection	Overrun error
Interrupt request	<ul style="list-style-type: none"> · Reception interrupt (reception completed, overrun error) · Transmission interrupt (transmission data empty, transmission bus idle) · Transmission FIFO interrupt (when the transmission FIFO is empty) · Both transmission and reception have the DMA transfer support function
Synchronous mode	Master or slave function
Pin access	Serial data output pin can be set to "1"
FIFO option	<ul style="list-style-type: none"> · Transmission/reception FIFO equipped (transmission FIFO: 16 bytes, reception FIFO: 16 bytes) · Transmission FIFO and reception FIFO can be selected · Transmission data can be retransmitted · Reception FIFO interrupt timing can be modified by software · FIFO reset is supported independently
DMA transfer support	Transmission: Supported Reception: Supported

2.3. LIN-UART

This section explains LIN-UART of the multi function serial interface.

LIN-UART (LIN Communication Control UART) provides specific functions to support LIN bus. It is also equipped with the FIFO for transmission/reception (16 bytes each).

Name	Function
Data buffer	<ul style="list-style-type: none"> · Full-duplex double buffering(when FIFO is unused) · Transmission/reception FIFO (16 bytes each) (when FIFO is used)
Serial input	Execute over-sampling for three times by the peripheral clock (PCLK) and determine the reception value by the majority of the sampling value.
Transfer mode	Asynchronous
Baud rate	<ul style="list-style-type: none"> · Dedicate baud rate generator provided (comprising of 15-bit reload counter) · External clock can be adjusted by the reload counter
Data length	8 bits
Signaling system	NRZ (Non Return to Zero)
Start Bit Detection	Synchronize with the start bit falling edge
Reception error detection	<ul style="list-style-type: none"> · Framing error · Overrun error
Interrupt request	<ul style="list-style-type: none"> · Reception interrupt (Reception completed, framing error, overrun error) · Transmission interrupt (transmission data empty, transmission bus idle) · Status interrupt (Lin synch break detection) · Interrupt request for ICU (LIN synch field detected: LSYN) · Transmission FIFO interrupt (when the transmission FIFO is empty) · Both transmission and reception have the DMA function
LIN bus option	<ul style="list-style-type: none"> · LIN protocol revision 2.1 is supported. · Master device operation · Slave device operation · LIN Synch break generation (can be changed to 13-16 bits) · Synch Delimiter generation (can be changed to 1-4 bits) · LIN Synch break detection · Detection of start/stop edges for LIN synch field connected to the input capture by input capture (See "CHAPTER : INPUT CAPTURE".)
FIFO option	<ul style="list-style-type: none"> · Transmission/reception FIFO equipped (transmission FIFO: 16 bytes, reception FIFO: 16 bytes) · Transmission FIFO and reception FIFO can be selected · Transmission data can be retransmitted · Reception FIFO interrupt timing can be modified by software · FIFO reset is supported independently
DMA transfer support	Transmission: Supported Reception: Supported Status: Not supported

2.4. I²C

This section explains I²C of the multi function serial interface.

I²C interface supports buses among ICs, and runs as a master/slave device on the I²C bus. It is also equipped with the FIFO for transmission/reception (16 bytes each).

Name	Function
Data buffer	<ul style="list-style-type: none"> · Full-duplex double buffering (when FIFO is unused) · Transmission/reception FIFO (16 bytes each) (when FIFO is used)
Serial input	The noise up to two clocks of the serial clock/serial data input is filtered out by the peripheral clock (PCLK).
Transfer mode	Synchronization
Baud rate	<ul style="list-style-type: none"> · Dedicated baud rate generator provided (comprising 15-bit reload counter) · External clock can be adjusted by the reload counter
Data length	8-bit
Signaling system	NRZ (Non Return to Zero)
Start bit detection	Synchronize with the start bit falling edge
Interrupt request	<ul style="list-style-type: none"> · Reception interrupt · Transmission interrupt · Status interrupt/interrupt request for ICU · Transmission FIFO interrupt (when the transmission FIFO is empty)
I ² C	<ul style="list-style-type: none"> · Master/slave transmission/reception function · Adjustment function · Clock synchronous function · Transmission direction detection function · Generation of iterative start condition and detection function · Bus error detection function · General call addressing function · 7-bit addressing as master or slave · Interrupt can be generated at transmission or bus error · 10-bit addressing function is supported by a program
FIFO	<ul style="list-style-type: none"> · Transmission/reception FIFO equipped (transmission FIFO: 16 bytes, reception FIFO: 16 bytes) · Transmission FIFO and reception FIFO can be selected · Transmission data can be retransmitted · Reception FIFO interrupt timing can be modified by software · FIFO reset is supported independently
DMA transfer support	Transmission: Supported Reception: Not supported Status: Not supported

2.5. Note

Note:

In serial communications, there is a possibility of receiving the incorrect data by the noise etc.

Therefore, design the board that suppresses the noise.

Moreover, add the checksum of data at the end, in consideration of the case when the erroneous data is received by the influence of the noise etc. Transmit data again when you detect the error by checksum.

3. Configuration

This section explains the configuration of the multi function serial interface.

Figure 3-1 Block Diagram (UART: Operating mode 0, 1)

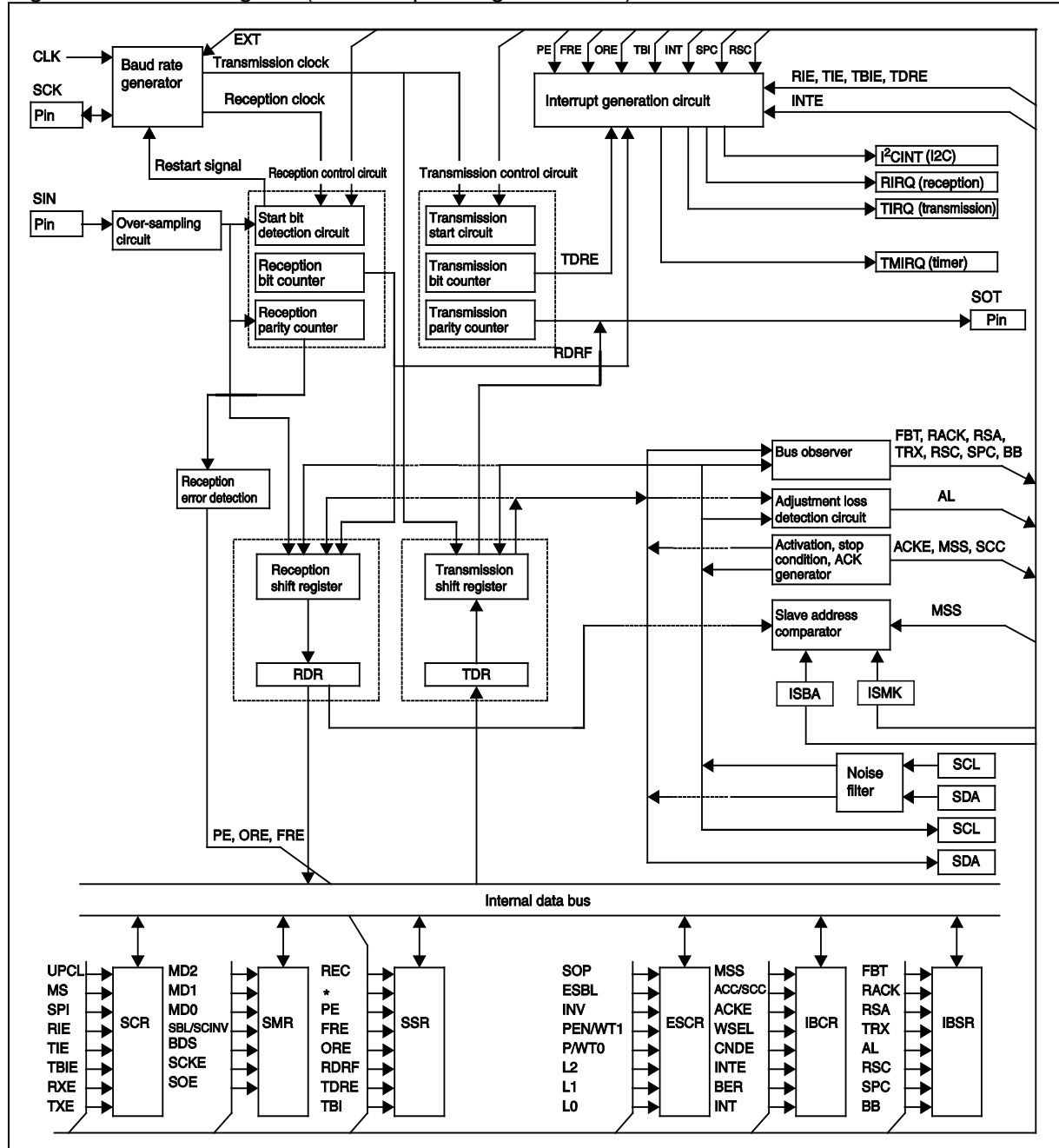


Figure 3-2 Block Diagram (CSIO: Operating mode 2)

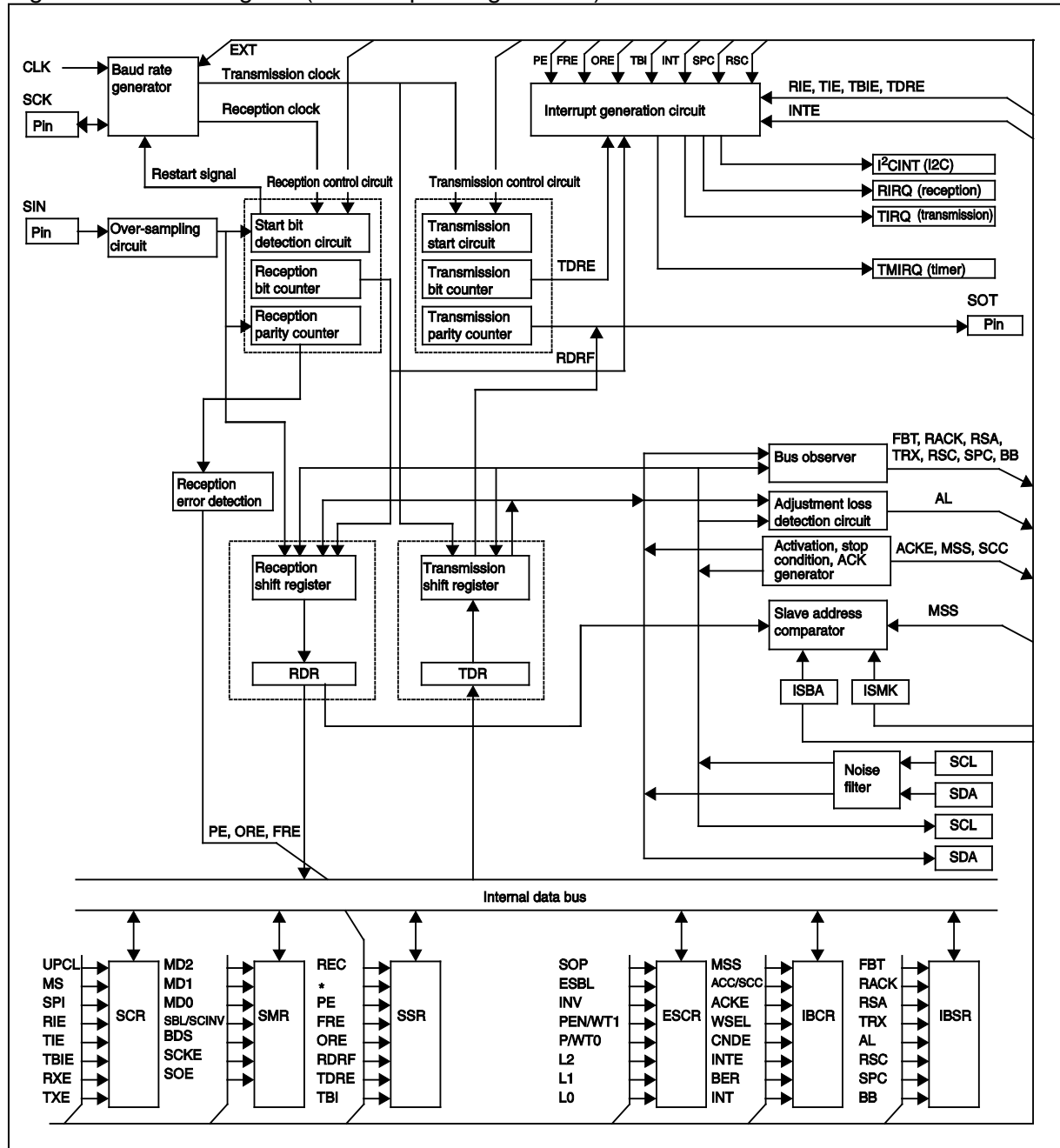


Figure 3-3 Block Diagram (LIN-UART: Operating mode 3)

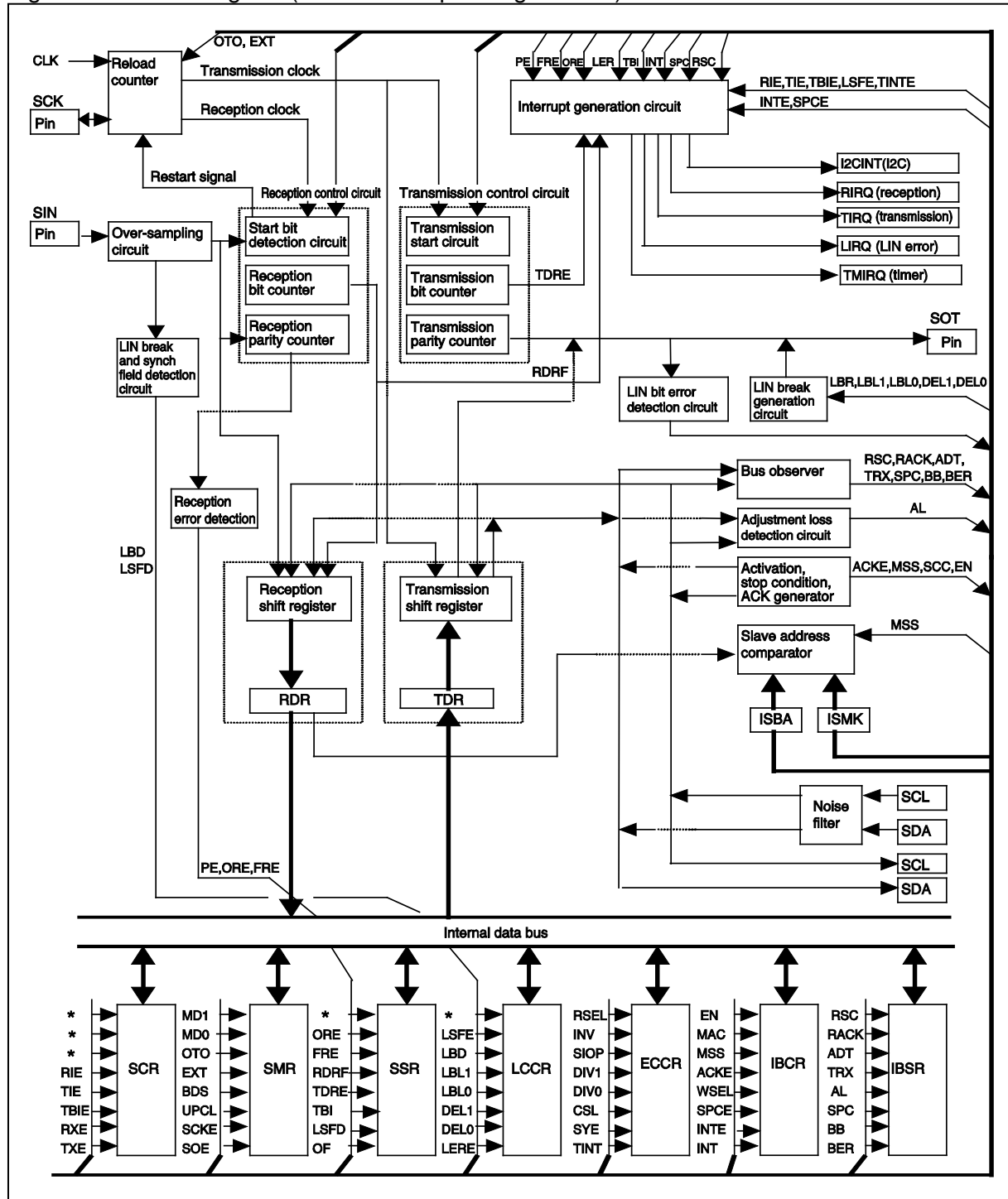
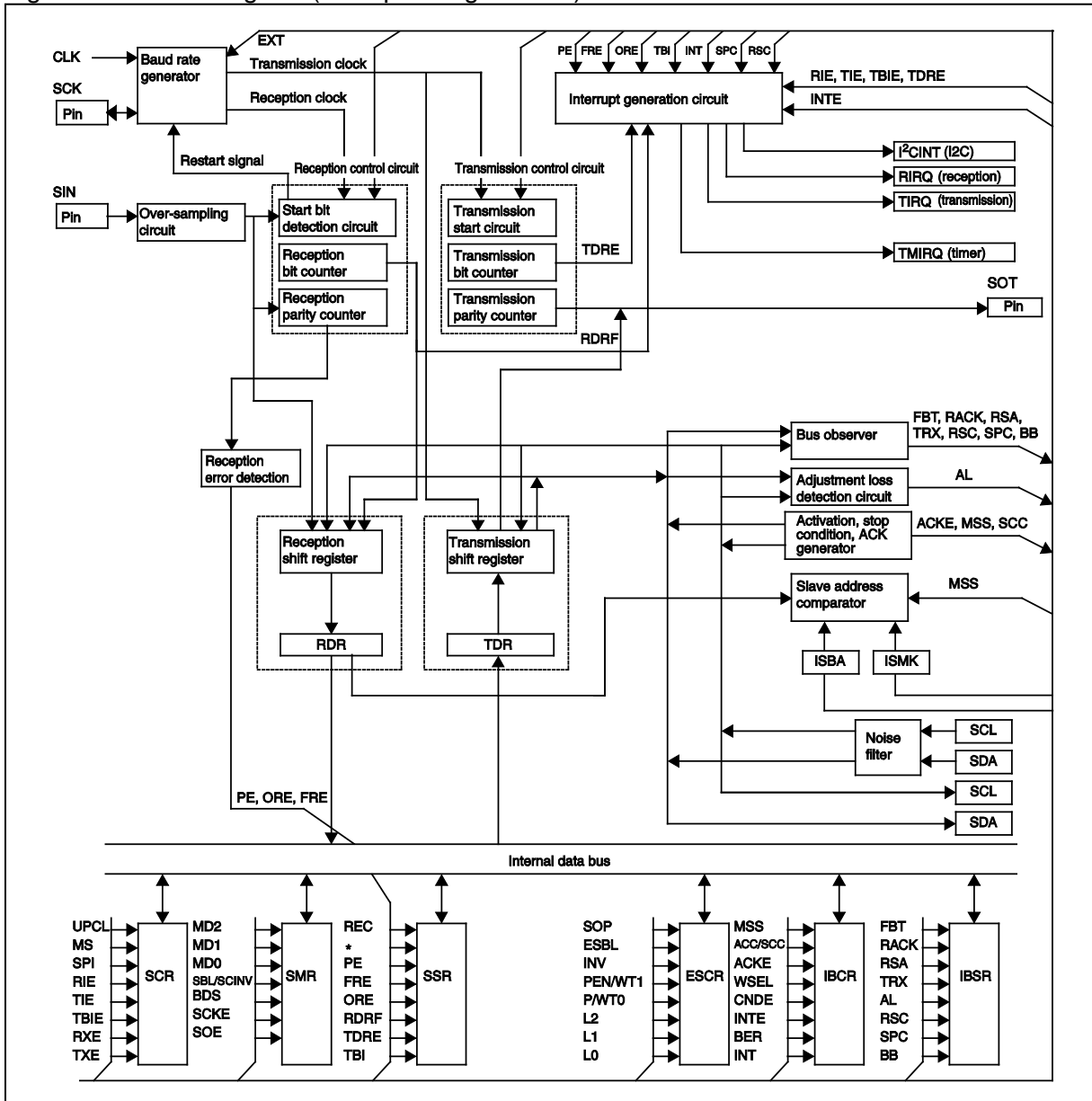


Figure 3-4 Block Diagram (I²C Operating mode 4)



4. Registers

This section explains registers of the multi function serial interface.

■ Table of Base Addresses (Base_addr) and External Pins

Table 4-1 Table of Base Addresses (Base_addr) and External Pins

Channels	Base_addr	External pin		
		SCK SCL(*)	SOT SDA(*)	SIN
0	0x00B0	SCK0	SOT0	SIN0
1	0x00C0	SCK1	SOT1	SIN1

(*) I²C

■ Registers Map

Table 4-2 Registers Map

Address	Registers				Registers function
	+0	+1	+2	+3	
0x00B0	[UART] SCR0 [CSIO] SCR0 [LIN-UAR T] SCR0 [I ² C] IBCR0	[Common] SMR0	[UART] SSR0 [CSIO] SSR0 [LIN-UAR T] SSR0 [I ² C] SSR0	[UART] ESCR0 [CSIO] ESCR0 [LIN-UAR T] ESCR0 [I ² C] IBSR0	--- ch.0 --- [UART] Serial control register [CSIO] Serial control register [LIN-UART] Serial control register [I ² C] I ² C Bus control register [Common] Serial mode register [UART] Serial status register [CSIO] Serial status register [LIN-UART] Serial status register [I ² C] Serial status register [UART] Extended serial control register [CSIO] Extended serial control register [LIN-UART] Extended serial control register [I ² C] I ² C Bus status register
0x00B4	[UART] RDR0/TDR0 [CSIO] RDR0/TDR0 [LIN-UART] RDR0/TDR0 [I ² C] RDR0/TDR0		[UART] BGR0 [CSIO] BGR0 [LIN-UART] BGR0 [I ² C] BGR0		--- ch.0 --- [UART] Transmit/receive data register [CSIO] Transmit/receive data register [LIN-UART] Transmit/receive data register [I ² C] Transmit/receive data register [UART] Baud rate generator register [CSIO] Baud rate generator register [LIN-UART] Baud rate generator register [I ² C] Baud rate generator register
0x00B8	[UART] Reserved [CSIO] Reserved [LIN-UAR T] Reserved [I ² C] ISMK0	[UART] Reserved [CSIO] Reserved [LIN-UAR T] Reserved [I ² C] ISBA0	Reserved		--- ch.0 --- [I ² C] 7-bit Slave address mask register [I ² C] 7-bit Slave address register

Address	Registers				Registers function
	+0	+1	+2	+3	
0x00BC	[Common] FCR10	[Common] FCR00	[Common] FBYTE0		--- ch.0 --- [Common] FIFO Control register 1 [Common] FIFO Control register 0 [Common] FIFO Byte register
0x00C0	[UART] SCR1 [CSIO] SCR1 [LIN-UAR T] SCR1 [I ² C] IBCR1	[Common] SMR1	[UART] SSR1 [CSIO] SSR1 [LIN-UAR T] SSR1 [I ² C] SSR1	[UART] ESCR1 [CSIO] ESCR1 [LIN-UAR T] ESCR1 [I ² C] IBSR1	--- ch.1 --- [UART] Serial control register [CSIO] Serial control register [LIN-UART] Serial control register [I ² C] I ² C Bus control register [Common] Serial mode register [UART] Serial status register [CSIO] Serial status register [LIN-UART] Serial status register [I ² C] Serial status register [UART] Extended serial control register [CSIO] Extended serial control register [LIN-UART] Extended serial control register [I ² C] I ² C Bus status register
0x00C4	[UART] RDR1/TDR1 [CSIO] RDR1/TDR1 [LIN-UART] RDR1/TDR1 [I ² C] RDR1/TDR1		[UART] BGR1 [CSIO] BGR1 [LIN-UART] BGR1 [I ² C] BGR1		--- ch.1 --- [UART] Transmit/receive data register [CSIO] Transmit/receive data register [LIN-UART] Transmit/receive data register [I ² C] Transmit/receive data register [UART] Baud rate generator register [CSIO] Baud rate generator register [LIN-UART] Baud rate generator register [I ² C] Baud rate generator register
0x00C8	[UART] Reserved [CSIO] Reserved [LIN-UAR T] Reserved [I ² C] ISMK1	[UART] Reserved [CSIO] Reserved [LIN-UAR T] Reserved [I ² C] ISBA1	Reserved		--- ch.1 --- [I ² C] 7-bit Slave address mask register [I ² C] 7-bit Slave address register
0x00CC	[Common] FCR11	[Common] FCR01	[Common] FBYTE1		--- ch.1 --- [Common] FIFO Control register 1 [Common] FIFO Control register 0 [Common] FIFO Byte register

4.1. Common Registers

Common registers are shown.

- 4.1.1. Serial Mode Register : SMR
- 4.1.2. FIFO Control Register 1 : FCR1
- 4.1.3. FIFO Control Register 0 : FCR0
- 4.1.4. FIFO BYTE Register : FBYTE

4.1.1. Serial Mode Register : SMR

The bit configuration of the serial mode register is shown below.

This register selects the serial communication method (UART or I²C). Bit3 to bit0 changes their function according to the method selected (UART, CSIO, or I²C).

■ **SMR : Address 00B1_H, 00C1_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MD[2:0]			Reserved	SBL/ SCINV/ RIE	BDS/TIE	SCKE/ (Reserved)	SOE/ (Reserved)
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W (R/W0)	R/W (R/W0)

[bit7 to bit5] MD[2:0] (MoDe) : Operation mode

These bits are used to set the communication method.

- 000_B: Operating mode 0 (asynchronous normal mode) is set.
- 001_B: Operating mode 1 (asynchronous multi-processor mode) is set.
- 010_B: Operating mode 2 (CSIO mode) is set.
- 011_B: Operating mode 3 (LIN communication mode) is set.
- 100_B: Operating mode 4 (I²C mode) is set.

Notes:

- Settings other than those listed above are prohibited.
- Configure each register after setting the operation mode.
- [UART][CSIO][LIN-UART] Before changing the operation mode, execute programmable clear (SCR:UPCL=1).
- [I²C] Before changing the operation mode, disable I²C (ISMK:EN=0).

[bit4] Reserved

Writing/reading does not affect the operation.

[bit3] SBL/SCINV/RIE (Stop Bit Length/Serial Clock Inversion/Receive Interrupt Enable) : Stop bit length selection bit/serial clock inversion bit, reception interrupt enable bit

[UART][LIN-UART]

This bit configures the bit length of stop bit (frame end mark for transmission data):

- When SBL=0 and ESCR:ESBL=0 are set: stop bit is set to 1-bit.
- When SBL=1 and ESCR:ESBL=0 are set: stop bits are set to 2-bit.
- When SBL=0 and ESCR:ESBL=1 are set: stop bits are set to 3-bit.
- When SBL=1 and ESCR:ESBL=1 are set: stop bits are set to 4-bit.

Notes:

- When receiving, only the first bit of the stop bits will always be detected.
 - This bit should be set when transmission is disabled (TXE=0).
-

[CSIO]

This bit inverses the serial clock format.

When this bit is set to "0":

Serial clock output mark level is set to "H". Transmission data is output in synchronization with a falling edge of the serial clock in the normal transfer while it is output in synchronization with a rising edge of the serial clock in the SPI transfer. Reception data is sampled at a rising edge of the serial clock in the normal transfer while it is sampled at a falling edge of the serial clock in the SPI transfer.

When this bit is set to "1":

Serial clock output mark level is set to "L". Transmission data is output in synchronization with a rising edge of the serial clock in the normal transfer while it is output in synchronization with a falling edge of the serial clock in the SPI transfer. Reception data is sampled at a falling edge of the serial clock in the normal transfer while it is sampled at a rising edge of the serial clock in the SPI transfer.

Notes:

- Set this bit when transmission and reception are disabled (TXE=RXE=0).
 - Set it to reception enabled(SCR:RXE=1) after setting the SCINV bit.
-

[I²C]

This bit enables or disables the output of reception interrupt request to the CPU.

When the RIE bit and the reception data flag bit (SSR:RDRF) are set to "1", or any of the error flag bits (SSR:ORE) is set to "1", a reception interrupt request will be output.

Note:

To receive data using the INT bit of I²C bus control register (IBCR), make sure to clear this bit to "0".

[bit2] BDS/TIE (Bit Direction Select/Transmit Interrupt Enable) : Transfer direction selection bit/
transmission interrupt enable bit

[LIN-UART]

LIN-UART does not use this bit. Writing a value to this bit does not affect the operation.

[UART][CSIO]

This bit selects whether to transfer the transfer serial data from the least significant bit (LSB-first, BDS=0) or from the most significant bit (MSB-first, BDS=1).

Note:

Set this bit when transmission and reception are disabled (TXE=RXE=0).

[I²C]

This bit enables or disables the output of transmission interrupt request to the CPU.
When the TIE bit and the SSR:TDRE bit are set to "1", a transmission interrupt request will be output.

Note:

To send data using the INT bit of I²C bus control register (IBCR), make sure to clear this bit to "0".

[bit1] SCKE (Serial Clock Enable) : Serial clock output enable bit

[UART][LIN-UART]

This bit is not used in UART/LIN-UART. The reading value is "0". Always set this bit to "0".

[CSIO]

This bit controls the I/O ports of a serial clock.

When this bit is set to "0":

The SCK pin functions as a general-purpose I/O port or serial clock input pin.

When this bit is set to "1":

The SCK pin functions as a serial clock output pin and outputs the clock.

Note:

To use the SCK pin as a serial clock input (SCKE=0), set the general-purpose I/O port as an input port. In this case, select the external clock using the external clock selection bit (BGR:EXT=1).

[I²C]

Reserved bit. Always set this bit to "0".

[bit0] SOE (Serial Output Enable) : Serial output enable bit

[UART][CSIO][LIN-UART]

This bit enables/disables output of serial data.

When this bit is set to "0":

The SOUT pin functions as a general-purpose I/O port.

When this bit is set to "1":

The SOUT pin functions as a serial data output pin (SOUT).

[I²C]

This bit is reserved. Always set this bit to "0".

4.1.2. FIFO Control Register 1 : FCR1

The bit configuration of the FIFO control register 1 is shown below.

The FIFO control register (FCR1) is used for the test settings of FIFO, selection of transmission/reception FIFO, settings of transmission FIFO interrupt enable, and control of interrupt flag.

■ FCR1 : Address 00BC_H, 00CC_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		Reserved	FLSTE	FRIIE	FDRQ	FTIE	FSEL
Initial value	0	0	-	0	0	1	0	0
Attribute	R/W0	R/W0	RX,WX	R/W	R/W	R(RM1), W	R/W	R/W

[bit7,bit6]: Reserved

These bits must always be written to "0".

[bit4] FLSTE (Flag for data LoST detection Enable) : Retransmission data lost detection enable bit

This bit is a bit that enables the FIFO retransmission data lost flag (FLST) detection.

When this bit is set to "0": the FLST bit detection disabled

When this bit is set to "1": the FLST bit detection enabled

Note:

When this bit is set to "1", set this bit to "1" after setting "1" to the FSET bit.

[bit3] FRIIE (Flag for Receive FIFO IdIE detection Enable) : Reception FIFO idle detection enable bit

This bit configures whether or not to detect the reception idle state for 8-bit time or longer while the reception FIFO contains valid data. When reception interrupts are enabled (SCR:RIE=1), a reception interrupt will be generated once it detects the reception idle state.

When this bit is set to "0":Reception idle state detection disabled

When this bit is set to "1":Reception idle state detection enabled

[bit2] FDRQ (transmit FIFO Data ReQuest) : Transmission FIFO data request bit

It is a data request bit for transmission FIFO. When this bit is set to "1", it indicates that transmission data is being requested. When transmission FIFO interrupts are enabled (FTIE=1) at this time, a FIFO transmission interrupt request will be output.

FDRQ set condition

- FBYTE (for transmission) = 0 (transmission FIFO is empty)

FDRQ reset condition

- Writing "0" to this bit.
- If the transmission FIFO becomes full.

Notes:

- When transmission FIFO is enabled, writing "0" to this bit is valid.
 - When FBYTE (for transmission) is "0", writing "0" to this bit is prohibited.
 - When you set this bit to "1", it does not affect the operation.
 - If a read-modify-write instruction is executed, "1" will be read.
-

[bit1] FTIE (Flag for Transmit Interrupt Enable) : Transmission FIFO interrupt enable bit

This bit is an interrupt enable bit for transmission FIFO. If you set this bit to "1", an interrupt will be generated when the FDRQ bit is "1".

[bit0] FSEL (FIFO SElect) : FIFO selection bit

This bit is used to select transmission/reception FIFO.

When this bit is set to "0", FIFO1 is assigned as the transmission FIFO, and FIFO2, the reception FIFO.

When this bit is set to "1", FIFO2 is assigned as the transmission FIFO, and FIFO1, the reception FIFO.

Notes:

- This bit will not be cleared by FIFO reset (FCR0:FCL2, FCL1=1).
 - When you change this bit, disable the FIFO operation (FCR0:FE2, FE1=0) first.
-

4.1.3. FIFO Control Register 0 : FCR0

The bit configuration of the FIFO control register 0 is shown below.

The FIFO control register 0 (FCR0) is used to enable/disable FIFO operation, reset FIFO, save read pointer, and configure retransmission.

■ **FCR0 : Address 00BD_H ,00CD_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	FLST	FLD	FSET	FCL2	FCL1	FE2	FE1
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R,WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit7] Reserved

This bit must always be written to "0".

[bit6] FLST (FIFO data LoST) : FIFO retransmission data lost flag bit

This bit indicates that the retransmission data of transmission FIFO has been lost.

FLST set condition

When you write (overwrite) FIFO while the FLSTE bit of the FIFO control register 1 (FCR1) is "1" and the read pointers saved by the FSET bit matches the write pointer of transmission FIFO

FLST reset condition

- FIFO reset (writing "1" to FCL)
- Writing "1" to the FSET bit

If this bit is set to "1", it will overwrite the data indicated by the read pointer saved by the FSET bit. As a result, you will not be able to configure the retransmission by the FLD bit even when an error occurs. To execute a retransmission while this bit is set to "1", reset FIFO and write data to FIFO once again.

[bit5] FLD (FIFO pointer reLoad bit)

This bit reloads the data saved by the FSET bit at transmission FIFO to the read pointer. This bit is used for a retransmission in case of a communication error occurs. Once the retransmission setting has completed, this bit will be cleared to "0".

Notes:

- Do not write any other than FIFO reset while this bit is set to "1" since a reload to the read pointer is in progress.
- During the FIFO enable state or while a transmission is in progress, writing "1" to this bit is prohibited.
- Before writing "1" to this bit, clear the TIE bit and TBIE bit to "0", then set the TIE bit and TBIE bit to "1" after enabling transmission FIFO.

[bit4] FSET (FIFO pointer SET) FIFO pointer save bit

This bit is used to save the read pointer of transmission FIFO. If you save the read pointer prior to communication, you will be able to retransmit while the FLST bit is "0" in case that a communication error occurs.

- If this bit is set to "1": Save the current read pointer value.
- If this bit is set to "0": No effect.

Note:

Set this bit to "1" when the transmission byte count (FBYTE) is 0.

[bit3] FCL2 (FIFO Clear 2) FIFO2 reset bit

This bit resets FIFO2.

When this bit is set to "1", it initializes the internal state of FIFO2.

Only the FCR1:FLST bit will be initialized while other bits of the FCR1/FCR0 register are retained.

Notes:

- Execute FIFO2 reset after disabling transmission/reception.
 - Execute after clearing the transmission FIFO interrupt enable bit to "0".
 - The valid data count of the FBYTE2 register will be 0.
-

[bit2] FCL1 (FIFO Clear 1) FIFO1 reset bit

This bit resets FIFO1.

When this bit is set to "1", it initializes the internal state of FIFO1.

Only the FCR1:FLST bit will be initialized while other bits of the FCR1/FCR0 register are retained.

Notes:

- Execute FIFO1 reset after disabling transmission/reception.
 - Execute after clearing the transmission FIFO interrupt enable bit to "0".
 - The valid data count of the FBYTE1 register will be 0.
-

[bit1] FE2 (FIFO Enable 2) FIFO2 operation enable bit

This bit enables/disables operation of FIFO2.

- To use FIFO2, set this bit to "1".
- With the FIFO2 configured as transmission FIFO (FCR1:FSEL=1), if FIFO2 contains data when you write "1" to this bit and transmission is enabled for UART (SCR:TXE=1), it immediately starts the transmission. Before writing "1" to this bit, clear the SCR:TIE bit and the SCR:TBIE bit to "0", then set the SCR:TIE bit and the SCR:TBIE bit to "1".
- When this bit is selected as reception FIFO by the FSEL bit, this bit is cleared to "0" if a reception error occurs. As long as the reception error is not cleared, you will not be able to set this bit to "1".
- When the transmission FIFO is used, if the transmission buffer is empty (SSR:TDRE=1), or when the reception FIFO is used, if the reception buffer is empty (SSR:RDRF=0), set "1" or "0" to this bit.
- Even if you have FIFO2 disabled, the state of FIFO2 will be retained.

[bit0] FE1 (FIFO Enable 1) FIFO1 operation enable bit

This bit enables/disables operation of FIFO1.

- To use FIFO1, set this bit to "1".
- With the FIFO1 configured as transmission FIFO (FCR1:FSEL=0), if FIFO1 contains data when you write "1" to this bit and transmission is enabled for UART (SCR:TXE=1), it immediately starts the transmission. Before writing "1" to this bit, clear the SCR:TIE bit and the SCR:TBIE bit to "0", then set the SCR:TIE bit and the SCR:TBIE bit to "1".
- When this bit is selected as reception FIFO by the FSEL bit, this bit is cleared to "0" if a reception error occurs. As long as the reception error is not cleared, you will not be able to set this bit to "1".
- When the transmission FIFO is used, if the transmission buffer is empty (SSR:TDRE=1), or when the reception FIFO is used, if the reception buffer is empty (SSR:RDRF=0), set "1" or "0" to this bit.
- Even if you have FIFO1 disabled, the state of FIFO1 will be retained.

4.1.4. FIFO BYTE Register : FBYTE

The bit configuration of the FIFO BYTE register is shown below.

■ **FBYTE : Address 00BE_H, 00CE_H (Access: Byte, Half-word, Word)**

The function of this register changes for reading and writing.

For reading, FIFO byte register (FBYTE) shows the valid data count of FIFO.

For writing, you will be able to configure whether to generate a reception interrupt when the reception FIFO receives the specified number of data sets.

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	FBYTE2[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FBYTE1[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

[bit15 to bit8] FBYTE2[7:0] (FIFO Byte 2) FIFO2 data count display bits

[bit7 to bit0] FBYTE1[7:0] (FIFO Byte 1) FIFO1 data count display bits

The FBYTE register indicates the valid data count written to or received at FIFO. The following table shows the details of FCR1:FSEL bit settings.

FSEL	FIFO selection	Data count display
0	FIFO2: Reception FIFO, FIFO1: Transmission FIFO	FIFO2: FBYTE2, FIFO1: FBYTE1
1	FIFO2: Transmission FIFO, FIFO1: Reception FIFO	FIFO2: FBYTE2, FIFO1: FBYTE1

- The initial value of FBYTE transfer count is 08_H.
- Set the data count at which you want to generate a reception interrupt flag with FBYTE for reception FIFO. If the specified transfer count and FBYTE data count display match, the interrupt flag (SSR:RDRF) will be set to "1".
- If the data count contained in the reception FIFO does not reach the transfer count while the reception FIFO idle detection enable bit (FRIIE) is set to "1", the interrupt flag (RDRF) will be set to "1" after the reception idle state continues for 8 baud rate clocks or longer. If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. If the reception FIFO is disabled, the counter is reset to 0. When the reception FIFO is enabled while there is data remaining in it, the counter starts counting again.

- [CSIO] To receive data in the master operation mode (master reception), clear the TIE bit and the TBIE bit to "0", set the reception data count at the FBYTE register of transmission FIFO, and write "0" to the FDRQ bit. Then, it outputs serial clocks for the volume of data configured when the TXE bit is "1", which allows you to receive the data volume you have configured. To set the TIE bit and the TBIE bit to "1", set them to 1 after FDRQ changes to "1".
- [I²C] To receive data in the master operation mode (master reception), clear the TIE bit to "0", set the reception data count at FBYTE of transmission FIFO, and write "0" to the FDRQ bit. It outputs the SCL clocks for the data volume configured. Then, the INT bit will be set to "1". To set the TIE bit to "1", set it to 1 after the FDRQ bit changes to "1".

Notes:

- [UART][LIN-UART] Set FBYTE of the transmission FIFO to 00_H.
 - [CSIO] [I²C] Other than the case of receiving data in the master operation mode, set FBYTE of the transmission FIFO to "8'h00".
 - [CSIO] When you configure the transmission data count for data reception in the master operation mode, make sure that the transmission FIFO is empty and the SCR:TIE bit and the SSR:TBIE bit are "0".
 - [I²C] When you configure the transmission data count for data reception in the master operation mode, make sure that the transmission FIFO is empty and the SCR:TIE bit is "0".
 - [CSIO] Before you disable reception (SCR:RXE=0) while data is being received in the master operation mode, you need to disable the transmission/reception, after you disable the transmission FIFO.
 - [I²C] Before you disable the I²C interface (ISMK:EN=0) while data is being received in the master operation mode, you will need to disable the transmission/reception FIFO first.
 - [Common] Data configured at FBYTE of the reception FIFO should be "1" or greater.
 - [Common] Change the bit after disabling transmission/reception.
 - [Common] You will not be able to use read-modify-write instructions for this register.
 - [Common] Settings that go over the FIFO capacity are prohibited.
-

4.2. Registers for UART

Registers for UART are shown.

- 4.2.1. Serial Control Register : SCR
- 4.2.2. Serial Status Register : SSR
- 4.2.3. Extended Serial Control Register : ESCR
- 4.2.4. Receive Data Register/Transmit Data Register : RDR/TDR
- 4.2.5. Baud rate Generator Register : BGR

4.2.1. Serial Control Register : SCR

The bit configuration of the serial control register is shown below.

The serial control register (SCR) allows you to disable/enable transmission and reception, disable/enable transmission/reception interrupts, disable/enable transmission bus idle interrupts, and reset UART.

■ **SCR : Address 00B0_H, 00C0_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	UPCL	Reserved	Reserved	RIE	TIE	TBIE	RXE	TXE
Initial value	0	-	-	0	0	0	0	0
Attribute	R0,W	RX,WX	RX,WX	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	UPCL: Programmable clear bit	<p>This bit initializes the internal state of UART.</p> <p>When this bit is set to "1":</p> <ul style="list-style-type: none"> · Directly reset UART (software reset). In this case, the register settings will be maintained. Note that any active transmission or reception will be cut off immediately. · Baud rate generator restarts by reloading the setting value of the BGR register. · All the transmission and reception interrupt factors (SSR:PE,FRE,ORE,RDRF,TDRE,TBI) are initialized(000011_B). <p>When this bit is set to "0": No effect.</p> <p>A read always results in "0".</p> <p>Notes:</p> <ul style="list-style-type: none"> · Execute a programmable clear after disabling interrupts. · When using FIFO, disable FIFO (FCR0:FE2,FE1=0) before you execute a programmable clear.
bit6, bit5	Reserved	<p>Read: The value is undefined.</p> <p>Write: No effect.</p>
bit4	RIE: Reception interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of reception interrupt request to the CPU. · When the RIE bit and reception data flag bit (SSR:RDRF) are set to "1", or any of the error flag bit (SSR:PE, ORE, FRE) is set to "1", a reception interrupt request will be output.
bit3	TIE: Transmission interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of transmission interrupt request to the CPU. · When the TIE bit and the SSR:TDRE bit are set to "1", a transmission interrupt request will be output.
bit2	TBIE: Transmission bus idle interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of transmission bus idle interrupt request to the CPU. · When the TBIE bit and the SSR:TBI bit are set to "1", a transmission bus idle interrupt request will be output.

Bit name		Function
bit1	RXE: Reception enable bit	<p>This bit enables/disables the reception of UART.</p> <ul style="list-style-type: none"> · If this bit is set to "0", reception is disabled. · If this bit is set to "1", reception is enabled. <p>Notes:</p> <ul style="list-style-type: none"> · Even when you enable reception (RXE=1), UART does not start the reception until a falling edge of the start bit (in the case of NRZ format (ESCR:INV=0)) is input. (In the case of inverted NRZ format (ESCR:INV=1), UART does not start the reception until a rising edge is input.) · If you disable reception (RXE=0) while a reception is in progress, it immediately stops the reception.
bit0	TXE: Transmission enable bit	<p>This bit enables/disables the transmission of UART.</p> <ul style="list-style-type: none"> · If this bit is set to "0", transmission is disabled. · If this bit is set to "1", transmission is enabled. <p>Note:</p> <ul style="list-style-type: none"> · If you disable transmission (TXE=0) while a transmission is in progress, it immediately stops the transmission.

4.2.2. Serial Status Register : SSR

The bit configuration of the serial status register is shown below.

The serial status register (SSR) allows you to check the status of transmission/reception and the reception error flag as well as to clear the reception error flag.

■ **SSR : Address 00B2_H, 00C2_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
REC	Reserved	PE	FRE	ORE	RDRF	TDRE	TBI

Initial value	0	-	0	0	0	0	1	1
Attribute	R0,W	RX,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

Bit name		Function
bit7	REC: Reception error flag clear bit	This bit clears the PE, FRE, ORE flags of the serial status register (SSR). <ul style="list-style-type: none"> To clear an error flag, write "1" to this bit. Writing "0" does not affect anything. A read always results in "0".
bit6	Reserved	Read : The value is undefined. Write: No effect.
bit5	PE: Parity error flag bit (Functions only in the operation mode 0)	"0" Read: No parity error "1" Read: Parity error exists <ul style="list-style-type: none"> If a parity error occurs while a reception is in progress (SMR:PEN=1), the bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). When the PE bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. If this flag is set, data contained in the receive data register (RDR) becomes invalid. When this flag is set while using the reception FIFO, the reception FIFO enable bit will be cleared. As a result, the reception data will not be stored in the reception FIFO.
bit4	FRE: Framing error flag bit	"0" Read: No framing error "1" Read: Framing error exists <ul style="list-style-type: none"> If a framing error occurs while a reception is in progress, this bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). When the FRE bit and SCR:RIE bit are set to "1", a reception interrupt request will be output. If this flag is set, data contained in the receive data register (RDR) becomes invalid. When this flag is set while using the reception FIFO, the reception FIFO enable bit will be cleared. As a result, the reception data will not be stored in the reception FIFO.

Bit name		Function
bit3	ORE: Overrun error flag bit	<p>"0" Read: No overrun error. "1" Read: Overrun error exists.</p> <ul style="list-style-type: none"> · If an overrun error occurs while a reception is in progress, this bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). · When the ORE bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · If this flag is set, data contained in the receive data register (RDR) becomes invalid. · When this flag is set while using the reception FIFO, the reception FIFO enable bit will be cleared. As a result, the reception data will not be stored in the reception FIFO.
bit2	RDRF: Reception data full flag bit	<p>"0" Read: Receive data register RDR is empty "1" Read: Receive data register RDR contains data.</p> <ul style="list-style-type: none"> · The flag indicates the state of the receive data register (RDR). · When received data is loaded in the RDR, this flag will be set to "1" and when the receive data register (RDR) is read out, it will be cleared to "0". · When the RDRF bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · While using reception FIFO, the RDRF will be set to "1" once the reception FIFO has received the specified number of data sets. · While using reception FIFO and the reception FIFO idle detection enable bit (FCR1:FRIIE) is set to "1", if the reception FIFO contains data without receiving the specified number of data sets and the reception idle state has continued for 8 baud rate clocks or longer, the RDRF will be set to "1". If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. · While using reception FIFO, the bit will be cleared to "0" once the reception FIFO becomes empty.
bit1	TDRE: Transmission data empty flag bit	<p>"0" Read: Transmit data register TDR contains data. "1" Read: Transmit data register TDR is empty.</p> <ul style="list-style-type: none"> · The flag indicates the state of the transmit data register (TDR). · When a transmit data is written to TDR, this flag turns to "0", which indicates that a valid data exists in the TDR. Once a transmission starts after data being loaded to the transmit shift register, the bit will be set to "1", which indicates that the TDR does not contain any valid data. · When the TDRE bit and the SCR:TIE bit are set to "1", a transmission interrupt request will be output. · When you set the UPCL bit of the serial control register (SCR) to "1", the TDRE bit will be set to "1". · For details of the timing of setting/resetting the TDRE bit while using transmission FIFO, see "5.1.5 Interrupts When Using Transmission FIFO and Flag Setting Timing".

Bit name		Function
bit0	TBI: Transmission bus idle flag bit	<p>"0" Read: Transmission is in progress "1" Read: No transmission is in progress</p> <ul style="list-style-type: none"> · This bit indicates that UART has no transmission in progress. · When transmission data has been written to the transmit data register (TDR), this bit will become "0". · When the transmit data register is empty (TDRE=1) and no transmission is in progress, this bit will be set to "1". · When you set "1" to the UPCL bit of the serial control register (SCR), the TBI bit will be set to "1". · When this bit is "1" and transmission bus idle interrupts are enabled (SCR:TBIE=1), a transmission interrupt request will be output.

4.2.3. Extended Serial Control Register : ESCR

The bit configuration of the extended serial control register is shown below.

The extended serial control register (ESCR) allows you to set the data length of transmission/reception, enable/disable the parity bit, select a parity bit, inverse the serial data format, as well as to select the length of stop bit.

■ **ESCR : Address 00B3_H, 00C3_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	ESBL	INV	PEN	P	L[2:0]		
Initial value	-	0	0	0	0	0	0	0
Attribute	RX,W0	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	Reserved	Always set this bit to "0".
bit6	ESBL: Extended stop bit length selection bit	This bit configures the bit length of stop bit (frame end mark for transmission data). When SMR:SBL=0 and ESBL=0 are set: stop bit is set to 1-bit. When SMR:SBL=1 and ESBL=0 are set: stop bits are set to 2-bit. When SMR:SBL=0 and ESBL=1 are set: stop bits are set to 3-bit. When SMR:SBL=1 and ESBL=1 are set: stop bits are set to 4-bit. Notes: · When receiving, only the first bit of the stop bits will always be detected. · This bit should be set when transmission is disabled (SCR:TXE=0).
bit5	INV: Invert serial data format bit	This bit selects the serial data format to be either NRZ format or inverted NRZ format. · When this bit is set to "0": NRZ format is set. · When this bit is set to "1": Inverted NRZ format is set.
bit4	PEN: Parity enable bit (Functions only in the operation mode 0)	This bit configures whether to enable addition (transmission) and detection (reception) of the parity bit. · When this bit is set to "0", no parity bit will be added. · When this bit is set to "1", a parity bit will be added. Note: In operation mode 1, this bit will be fixed to "0" internally.
bit3	P: Parity selection bit (Functions only in the operation mode 0)	When parity is enabled (ESCR:PEN=1), this bit selects odd parity "1" or even parity "0". · When this bit is set to "0": Selects even parity · When this bit is set to "1": Selects odd parity

Bit name		Function
bit2 to bit0	L2, L1, L0: Data length selection bits	<p>These bits specify the data length of transmission/reception data.</p> <ul style="list-style-type: none">· 000_B: Data length will be set to 8-bit.· 001_B: Data length will be set to 5-bit.· 010_B: Data length will be set to 6-bit.· 011_B: Data length will be set to 7-bit.· 100_B: Data length will be set to 9-bit. <p>Notes:</p> <ul style="list-style-type: none">· Settings other than those shown above are prohibited.· In operation mode 1, set the data length to 7/8-bit. The other settings are prohibited.

4.2.4. Receive Data Register/Transmit Data Register : RDR/TDR

The bit configuration of receive data register/transmit data register is shown below.

The receive data register and transmit data register are located within the same addresses. When read, it functions as the receive data register and when written, it functions as the transmit data register. When FIFO enabled, the address of RDR/TDR will be the address for reading/writing FIFO.

■ **RDR/TDR : Address 00B4_H, 00C4_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

Read

The receive data register (RDR) is a 9-bit data buffer register for serial data reception.

- Serial data signals sent to the serial input pin (SIN) are converted in the shift register and stored in the receive data register (RDR).
- Depending on the data length, "0" is inserted in the upper bit as shown below.

Data length	D8	D7	D6	D5	D4	D3	D2	D1	D0
9 bits	X	X	X	X	X	X	X	X	X
8 bits	0	X	X	X	X	X	X	X	X
7 bits	0	0	X	X	X	X	X	X	X
6 bits	0	0	0	X	X	X	X	X	X
5 bits	0	0	0	0	X	X	X	X	X

(X is the reception data bit)

- When the received data is stored in the receive data register (RDR), the reception data full flag bit (SSR:RDRF) will be set to "1". When reception interrupts are enabled (SSR:RIE=1), a reception interrupt request will be generated.
- The receive data register (RDR) should be read out when the reception data full flag bit (SSR:RDRF) is "1". The reception data full flag bit (SSR:RDRF) will be automatically cleared to "0" when the receive data register (RDR) has been read out.
- In case a reception error occurs (SSR: PE, ORE or FRE is "1"), data in the receive data register (RDR) will become invalid.

- In operation mode 1 (multi-processor mode), the operation will be 7-bit or 8-bit length. The AD bit received will be stored at the D8 bit.
- For the 9-bit length transfer and in operation mode 1, RDR will be read in 16-bit access mode.

Notes:

- When you use reception FIFO, if received data in the reception FIFO reaches specified number, "1" will be set to SSR:RDRF.
- When you are using reception FIFO, if the reception FIFO becomes empty, SSR:RDRF will be cleared to "0".
- If a reception error occurs (SSR: PE, ORE, or FRE is "1") while using reception FIFO, the reception FIFO enable bit will be cleared. As a result, data received will not be stored at the reception FIFO.

Write

The transmit data register (TDR) is the 9-bit data buffer register for sending serial data.

- When transmit operations are enabled (SCR:TXE=1), if transmission data is written to the transmit data register (TDR), the transmission data is transferred to the transmit shift register and converted to serial data, then output from the serial data output pin (SOUT).
- Depending on the data length, data will be invalidated from the upper bit as shown below.

Data length	D8	D7	D6	D5	D4	D3	D2	D1	D0
9 bits	X	X	X	X	X	X	X	X	X
8 bits	Invalid	X	X	X	X	X	X	X	X
7 bits	Invalid	Invalid	X	X	X	X	X	X	X
6 bits	Invalid	Invalid	Invalid	X	X	X	X	X	X
5 bits	Invalid	Invalid	Invalid	Invalid	X	X	X	X	X

(X is the transmission data bit)

- Transmission data empty flag (SSR:TDRE) will be cleared to "0" when the transmission data is written to the transmit data register (TDR).
- The transmission data empty flag (SSR:TDRE) will be set to "1" once a transmission starts after the transmission data has been transferred to the transmit shift register if the transmission FIFO is disabled or empty.
- You will be able to write transmission data when the transmission data empty flag (SSR:TDRE) is set to "1". If the transmission interrupt is enabled, a transmission interrupt will occur. Writing transmission data should be performed by the generation of transmission interrupt or be done when the transmission data empty flag (SSR:TDRE) is "1".
- You will not be able to write transmission data when the transmission data empty flag (SSR:TDRE) is "0" and transmission FIFO is disabled or full.
- In operation mode 1 (multi-processor mode), the operation will be 7-bit or 8-bit length. The AD bit will be transmitted by writing to the D8 bit.
- For the 9-bit length transfer and in operation mode 1, write a value to the TDR in 16-bit access mode.

Notes:

- Transmission data register is write-only register and receive data register is read-only register. The value written is different from the read value since the transmission/reception registers are located at the same address. Therefore instructions such as INC/DEC instructions which perform the read-modify-write (RMW) operation cannot be used.
- For more information about the set timing of the transmission data empty flag (SSR:TDRE) when using the transmission FIFO, see "5.1.5 Interrupts When Using Transmission FIFO and Flag Setting Timing".

4.2.5. Baud rate Generator Register : BGR

The bit configuration of the baud rate generator register is shown below.

The baud rate generator register (BGR) sets the division ratio of a serial clock. It can also select an external clock as the clock source of a reload counter.

■ **BGR: Address 00B6_H, 00C6_H (Access: Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	BGR[14:8]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	BGR[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15] EXT (EXTernal clock) : External clock selection bit

This bit selects whether to use an internal clock source or an external clock source for the internal reload counter for baud rate generation. When setting EXT=1, the external clock source will be used. This may not be implemented for some product types.

[bit14 to bit0] BGR[14:0] (Baud rate Generator)

These bits set the reload value for internal reload counter for baud rate generation. When the reload value is written in this register, the reload counter begins counting.

Notes:

- Write to the baud rate generator register (BGR) in 16-bit access mode.
- If the value of BGR is an even number, the "H" width of a serial clock is 1 cycle shorter than that of the "L" width. If it is an odd number, the duty ratio will be 1:1.
- If you change to the setting of External clock(EXT=1) in operation of baud rate generator, you write "0" in baud rate generator(BGR) and execute a programmable clear(SCR:UPCL), then set External clock(EXT=1).
- When you change the setting value of the baud rate generator register (BGR), a new setting value will be reloaded after the counter value becomes "15h00". Thus, if you wish to validate a new setting value immediately, execute programmable clear (SCR:UPCL) after you have change the setting value of BGR1/BGR0.
- Set the value of four or more to BGR. However, it is not likely to be able to receive the data normally by the error margin of the baud rate and setting the reload value.

4.3. Registers for CSIO

Registers for CSIO are shown.

- 4.3.1. Serial Control Register : SCR
- 4.3.2. Serial Status Register : SSR
- 4.3.3. Extended Serial Control Register : ESCR
- 4.3.4. Receive Data Register/Transmit Data Register : RDR/TDR
- 4.3.5. Baud rate Generator Register : BGR

4.3.1. Serial Control Register : SCR

The bit configuration of the serial control register is shown below.

The serial control register (SCR) allows you to disable/enable transmission and reception, disable/enable transmission/reception interrupts, disable/enable transmission bus idle interrupts, and reset UART.

■ **SCR : Address 00B0_H, 00C0_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
UPCL	MS	SPI	RIE	TIE	TBIE	RXE	TXE

Initial value	0	0	0	0	0	0	0
Attribute	R0,W	R/W	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	UPCL: Programmable clear bit	<p>This bit initializes the internal state of CSIO.</p> <p>When this bit is set to "1":</p> <ul style="list-style-type: none"> Directly reset CSIO (software reset). In this case, the register settings will be retained. Note that any active transmission or reception will be cut off immediately. Baud rate generator restarts by reloading the setting value of the BGR register. All transmission and reception interrupt sources (SSR:TDRE, TBI, RDRF, and ORE) are initialized. <p>When this bit is set to "0": No effect on the operation. A read always results in "0".</p> <p>Notes:</p> <ul style="list-style-type: none"> Execute a programmable clear after disabling interrupts. When using FIFO, disable FIFO (FCR0:FE2, FE1=0) before you execute a programmable clear.
bit6	MS: Master/slave function selection bit	<p>This bit selects master or slave mode.</p> <p>When this bit is set to "0": Master mode When this bit is set to "1": Slave mode</p> <p>Notes:</p> <ul style="list-style-type: none"> If SMR:SCKE=0 when the slave mode is selected, an external clock will be input directly. Set this bit to reception enable (RXE=1) after setting the MS bit.
bit5	SPI: SPI support bit	<p>This bit is used to execute a SPI communication.</p> <p>When this bit is set to "0": Normal synchronous communication When this bit is set to "1": SPI communication supported.</p>
bit4	RIE: Reception interrupt enable bit	<ul style="list-style-type: none"> This bit enables or disables the output of reception interrupt request to the CPU. When the RIE bit and reception data flag bit (SSR:RDRF) are set to "1", or any of the error flag bit (ORE) is set to "1", a reception interrupt request will be output.

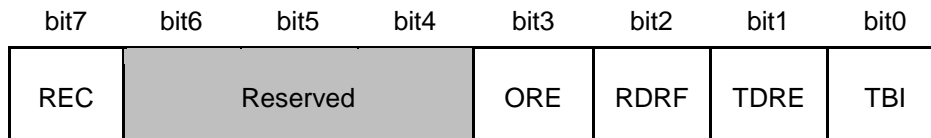
Bit name		Function
bit3	TIE: Transmission interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of transmission interrupt request to the CPU. · When the TIE bit and the SSR:TDRE bit are set to "1", a transmission interrupt request will be output.
bit2	TBIE: Transmission bus idle interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of transmission bus idle interrupt request to the CPU. · When the TBIE bit and the SSR:TBI bit are set to "1", a transmission bus idle interrupt request will be output.
bit1	RXE: Reception enable bit	<p>This bit enables/disables the reception of CSIO.</p> <ul style="list-style-type: none"> · If this bit is set to "0", data frame reception is disabled. · If this bit is set to "1", data frame reception is enabled. <p>Notes:</p> <ul style="list-style-type: none"> · If you disable reception (RXE=0) while a reception is in progress, it immediately stops the reception. · Set this bit to reception enable (RXE=1) after setting the MS bit and SMR:SCINV bit.
bit0	TXE: Transmission enable bit	<p>This bit enables/disables the transmission of CSIO.</p> <ul style="list-style-type: none"> · If this bit is set to "0", data frame transmission is disabled. · If this bit is set to "1", data frame transmission is enabled. <p>Note:</p> <ul style="list-style-type: none"> · If you disable transmission (TXE=0) while a transmission is in progress, it immediately stops the transmission.

4.3.2. Serial Status Register : SSR

The bit configuration of the serial status register is shown below.

The serial status register (SSR) allows you to check the status of transmission/reception and the reception error flag as well as to clear the reception error flag.

■ **SSR : Address 00B2_H, 00C2_H (Access: Byte, Half-word, Word)**



Initial value	0	-	-	-	0	0	1	1
Attribute	R0,W	RX,WX	RX,WX	RX,WX	R,WX	R,WX	R,WX	R,WX

Bit name		Function
bit7	REC: Reception error flag clear bit	This bit clears the ORE flag of the serial status register (SSR). <ul style="list-style-type: none"> · To clear an error flag, write "1" to this bit. · Writing "0" does not affect anything. A read always results in "0".
bit6 to bit4	Reserved	Read : The value is undefined. Write: No effect.
bit3	ORE: Overrun error flag bit	"0" Read :No overrun error "1" Read :There is an overrun error <ul style="list-style-type: none"> · If an overrun error occurs while a reception is in progress, this bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). · When the ORE bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · If this flag is set, data contained in the receive data register (RDR) becomes invalid. · When this flag is set while using the reception FIFO, the reception FIFO enable bit will be cleared. As a result, the reception data will not be stored in the reception FIFO.

Bit name		Function
bit2	RDRF: Reception data full flag bit	<p>"0" Read : Receive data register RDR is empty "1" Read : Receive data register RDR contains data.</p> <ul style="list-style-type: none"> · The flag indicates the state of the receive data register (RDR). · When received data is loaded in RDR, this flag will be set to "1" and when the receive data register (RDR) is read out, it will be cleared to "0". · When the RDRF bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · While using reception FIFO, the RDRF bit will be set to "1" once the reception FIFO has received the specified number of data sets. · When you use reception FIFO, if the reception FIFO contains data without receiving the specified number of data sets and the reception idle state has continued for 8 baud rate clocks or longer, the RDRF bit will be set to "1". If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. · While using reception FIFO, the bit will be cleared to "0" once the reception FIFO becomes empty.
bit1	TDRE: Transmission data empty flag bit	<p>"0" Read : Transmit data register TDR contains data. "1" Read : Transmit data register is empty</p> <ul style="list-style-type: none"> · The flag indicates the state of the transmit data register (TDR). · When a transmit data is written to TDR, this flag turns to "0", which indicates that a valid data exists in the TDR. Once a transmission starts after data being loaded to the transmit shift register, the bit will be set to "1", which indicates that the TDR does not contain any valid data. · When the TDRE bit and the SCR:TIE bit are set to "1", a transmission interrupt request will be output. · When you set the UPCL bit of the serial control register (SCR) to "1", the TDRE bit will be set to "1". · See "6.1.5. Interrupts When Using Transmission FIFO and Flag Setting Timing" for the set/reset timing of the TDRE bit when you use transmission FIFO.
bit0	TBI: Transmission bus idle flag bit	<p>"0" Read : Transmission is in progress. "1" Read : No transmission operation</p> <ul style="list-style-type: none"> · This bit indicates CSIO has no transmission in progress. · When transmission data has been written to the transmit data register (TDR), this bit will become "0". · When the transmit data register (TDR) is empty (TDRE=1) and no transmission is in progress, this bit will be set to "1". · When you set the UPCL bit of the serial control register (SCR) to "1", the TDRE bit will be set to "1". · When this bit is "1" and transmission bus idle interrupts are enabled (SCR:TBIE=1), a transmission interrupt request will be output.

4.3.3. Extended Serial Control Register : ESCR

The bit configuration of the extended serial control register is shown below.

The extended serial control register (ESCR) is used to set the transmission/reception data length as well as to fix the serial output at the "H" level.

■ **ESCR : Address 00B3_H, 00C3_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SOP	Reserved	WT[1:0]		L[2:0]			

Initial value	0	-	-	0	0	0	0	0
Attribute	R0,W	RX,WX	RX,WX	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	SOP: Serial output pin set bit	<ul style="list-style-type: none"> · This bit is used to set the serial output pin at the "H" level. When you write "1" to this bit, the SOUT pin will be set to "H". However, you do not need to write "0" to this bit afterward. · A read always results in "0". Note: Do not set this bit during serial data transmission.
bit6, bit5	Reserved	Read: The value is undefined. Write: No effect.
bit4, bit3	WT1, WT0: Data transmission/ reception wait selection bits	In the master mode, these bits set the number of wait for a successive data transmission or reception. Operation in the slave mode is "00". <ul style="list-style-type: none"> · "00": SCK will be output sequentially. · "01": SCK will be output after waiting for 1-bit time. · "10": SCK will be output after waiting for 2-bit time. · "11": SCK will be output after waiting for 3-bit time.
bit2 to bit0	L2, L1, L0: Data length selection bits	These bits specify the data length of transmission/reception data. <ul style="list-style-type: none"> · "000_B": Data length will be set to 8-bit. · "001_B": Data length will be set to 5-bit. · "010_B": Data length will be set to 6-bit. · "011_B": Data length will be set to 7-bit. · "100_B": Data length will be set to 9-bit. Note: Settings other than those listed above are prohibited.

4.3.4. Receive Data Register/Transmit Data Register : RDR/TDR

The bit configuration of receive data register/transmit data register is shown below.

The receive data register and transmit data register are located within the same addresses. When read, it functions as the receive data register and when written, it functions as the transmit data register. When FIFO enabled, the address of RDR/TDR will be the address for reading/writing FIFO.

■ **RDR/TDR : Address 00B4_H, 00C4_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							D8
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

Read

The receive data register (RDR) is a 9-bit data buffer register for serial data reception.

- Serial data signals sent to the serial input pin (SIN) are converted in the shift register and stored in the receive data register (RDR).
- Depending on the data length, "0" is inserted in the upper bit as shown below.

Data length	D8	D7	D6	D5	D4	D3	D2	D1	D0
9 bits	X	X	X	X	X	X	X	X	X
8 bits	0	X	X	X	X	X	X	X	X
7 bits	0	0	X	X	X	X	X	X	X
6 bits	0	0	0	X	X	X	X	X	X
5 bits	0	0	0	0	X	X	X	X	X

(X is the reception data bit)

- When the received data is stored in the receive data register (RDR), the reception data full flag bit (SSR:RDRF) will be set to "1". When reception interrupts are enabled (SSR:RIE=1), a reception interrupt request will be generated.
- The receive data register (RDR) should be read out when the reception data full flag bit (SSR:RDRF) is "1". The reception data full flag bit (SSR:RDRF) will be automatically cleared to "0" when the reception receive data register (RDR) has been read out.
- In case a reception error occurs (SSR:ORE is "1"), data in the receive data register (RDR) will become invalid.

- For the 9-bit long transfer, read a value from the RDR in 16-bit access mode.

Notes:

- When you use reception FIFO, if received data in the reception FIFO reaches specified number, "1" will be set to SSR:RDRF.
- When you are using reception FIFO, if the reception FIFO becomes empty, SSR:RDRF will be cleared to "0".
- If a reception error occurs (SSR:ORE is "1") while using reception FIFO, the reception FIFO enable bit will be cleared. As a result, data received will not be stored at the reception FIFO.

Write

The transmit data register (TDR) is the 9-bit data buffer register for sending serial data.

- When transmission operations are enabled (SCR:TXE=1), if transmission data is written to the transmit data register (TDR), the transmission data is transferred to the transmission shift register and converted to serial data, then output from the serial data output pin (SOUT).
- Depending on the data length, data will be invalidated from the upper bit as shown below.

Data length	D8	D7	D6	D5	D4	D3	D2	D1	D0
9 bits	X	X	X	X	X	X	X	X	X
8 bits	Invalid	X	X	X	X	X	X	X	X
7 bits	Invalid	Invalid	X	X	X	X	X	X	X
6 bits	Invalid	Invalid	Invalid	X	X	X	X	X	X
5 bits	Invalid	Invalid	Invalid	Invalid	X	X	X	X	X

(X is the transmission data bit)

- Transmission data empty flag (SSR:TDRE) will be cleared to "0" when the transmission data is written to the transmit data register (TDR).
- The transmission data empty flag (SSR:TDRE) will be set to "1" once a transmission starts after the transmission data has been transferred to the transmission shift register if the transmission FIFO is disabled or empty.
- You will be able to write transmission data when the transmission data empty flag (SSR:TDRE) is set to "1". If the transmission interrupt is enabled, a transmission interrupt will occur. Writing transmission data should be performed by the generation of transmission interrupt or be done when the transmission data empty flag (SSR:TDRE) is "1".
- You will not be able to write transmission data when the transmission data empty flag (SSR:TDRE) is "0" and transmission FIFO is disabled or full.
- For the 9-bit long transfer, write a value to the TDR in 16-bit access mode.

Notes:

- The transmit data register is write-only register and the receive data register is read-only register. The value written is different from the read value since the transmit/receive registers are located at the same address. Therefore, instructions such as INC/DEC instructions which perform read-modify-write (RMW) operations cannot be used.
- See "6.1.5 Interrupts When Using Transmission FIFO and Flag Setting Timing" for the set timing of the transmission data empty flag (SSR:TDRE) when you use transmission FIFO.

4.3.5. Baud rate Generator Register : BGR

The bit configuration of the baud rate generator register is shown below.

The baud rate generator register (BGR) sets the division ratio of a serial clock.

■ **BGR: Address 00B6_H, 00C6_H (Access: Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	BGR[14:8]						
Initial value	0	0	0	0	0	0	0	0
Attribute	RX,WX	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BGR[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit14 to bit0] BGR[14:0] (Baud rate Generator)

These bits set the reload value for internal reload counter for baud rate generation.

When the reload value is written in this register, the reload counter begins counting.

Notes:

- Write to the baud rate generator (BGR) in 16-bit access mode.
- If the reload value is an even number, the "H" and "L" widths of the serial clock depend on the SCINV bit setting as follows: If it is an odd number, the "H" and "L" widths of the serial clock are equal.
- If SMR:SCINV=0, the "H" width of the serial clock is longer by one cycle of the peripheral clock (PCLK).
- If SMR:SCINV=1, the "L" width of the serial clock is longer by one cycle of the peripheral clock (PCLK).
- Set the reload value to 3 or higher.
- When you change the setting value of the baud rate generator register (BGR), a new setting value will be reloaded after the counter value becomes "15h00". Thus, if you wish to validate a new setting value immediately, execute CSIO reset (SCR:UPCL) after you have change the setting value of BGR.
- To operate in the slave mode by setting "1" to the reception FIFO idle detection enable bit (FCR1:FRIIE) when you use reception FIFO, set the baud rate at the BGR.

4.4. Registers for LIN-UART

Registers for LIN-UART are shown.

- 4.4.1. Serial Control Register : SCR
- 4.4.2. Serial Status Register : SSR
- 4.4.3. Extended Serial Control Register : ESCR
- 4.4.4. Receive Data Register/Transmit Data Register : RDR/TDR
- 4.4.5. Baud rate Generator Register : BGR

4.4.1. Serial Control Register : SCR

The bit configuration of the serial control register is shown below.

The serial control register (SCR) allows you to disable/enable transmission/reception interrupts, disable/enable transmission idle interrupts, and disable/enable transmissions and receptions. This register also has a function to generate LIN Synch Break and reset LIN-UART.

■ **SCR: Address 00B0_H, 00C0_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
UPCL	MS	LBR	RIE	TIE	TBIE	RXE	TXE

Initial value	0	0	0	0	0	0	0
Attribute	R0,W	R/W	R0,W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	UPCL: Programmable clear bit	<p>This bit initializes the internal state of LIN-UART.</p> <p>When this bit is set to "1":</p> <ul style="list-style-type: none"> · Directly reset LIN-UART (software reset). In this case, the register settings will be maintained. Note that any active transmission or reception will be cut off immediately. · Baud rate generator restarts by reloading the setting value of the BGR register. · All transmission and reception interrupt sources (SSR:TDRE, TBI, RDRF, FRE, ORE, and LBD) are initialized. <p>When this bit is set to "0": No effect. For reading, "0" is always read out.</p> <p>Notes:</p> <ul style="list-style-type: none"> · Execute a programmable clear after disabling interrupts. · When using FIFO, disable FIFO (FCR:FE2,FE1=0) before you execute a programmable clear
bit6	MS: Master/slave selection bit	<p>This bit selects master or slave mode.</p> <p>0 : Master 1 : Slave</p>
bit5	LBR: Lin Synch Break setting bit (Functions only in the master operation)	<p>When you write "1" to this bit, the LIN Synch Break and the LIN Sync delimiter with the length specified by the ESCR:LBL1/LBL0 bits and DEL1/DEL0 are generated.</p> <p>Write:</p> <p>Writing "0": No effect. Writing "1": Generates LIN Synch Break.</p> <p>For reading, "0" will be always read out.</p> <p>Notes:</p> <ul style="list-style-type: none"> · Functions only in the master operation. · Do not set this bit to "1" while generating LIN Break field.

Bit name		Function
bit4	RIE: Reception interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of reception interrupt request to the CPU. · When the RIE bit and reception data flag bit (SSR:RDRF) are set to "1", or any of the error flag bits (SSR: LER, FRE, ORE) is set to "1", a reception interrupt request will be output.
bit3	TIE: Transmission interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of transmission interrupt request to the CPU. · When the TIE bit and the SSR:TDRE bit are set to "1", a transmission interrupt request will be output.
bit2	TBIE: Transmission bus idle interrupt enable bit	<ul style="list-style-type: none"> · This bit enables or disables the output of transmission bus idle interrupt request to the CPU. · When the TBIE bit and the SSR:TBI bit are set to "1", a transmission bus idle interrupt request will be output.
bit1	RXE: Reception enable bit	<p>This bit enables/disables the reception of LIN-UART.</p> <ul style="list-style-type: none"> · If this bit is set to "0", data frame reception is disabled. · If this bit is set to "1", data frame reception is enabled. <p>Notes:</p> <ul style="list-style-type: none"> · Even when you enable reception (RXE=1), LIN-UART does not start the reception until a falling edge of the start bit is input. · In the master operation mode, data will not be received even receptions are enabled (RXE=1) during LIN synch break field transmission. · If you disable reception (RXE=0) while a reception is in progress, it immediately stops the reception. · To detect a Lin synch break, enable LIN synch break detection interrupt (ESCR:LBIE=1) and then disable reception (SCR:RXE=0).
bit0	TXE: Transmission enable bit	<p>This bit enables/disables the transmission of LIN-UART.</p> <ul style="list-style-type: none"> · If this bit is set to "0", data frame transmission is disabled. · If this bit is set to "1", data frame transmission is enabled. <p>Note:</p> <p>If you disable transmission (TXE=0) while a transmission is in progress, it immediately stops the transmission.</p>

4.4.2. Serial Status Register : SSR

The bit configuration of the serial status register is shown below.

The serial status register (SSR) allows you to check the status of transmission/reception and the reception error flag and to detect the LIN Synch break as well as to clear the reception error flag.

■ **SSR: Address 00B2_H, 00C2_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	REC	Reserved	LBD	FRE	ORE	RDRF	TDRE	TBI
Initial value	0	-	0	0	0	0	1	1
Attribute	R0,W	RX,WX	R(RM1), W	R,WX	R,WX	R,WX	R,WX	R,WX

Bit name		Function
bit7	REC: Reception error flag clear bit	This bit clears the FRE and ORE flags of the serial status register (SSR). · To clear an error flag, write "1" to this bit. · Writing "0" does not affect anything. A read always results in "0".
bit6	Reserved	Read : The value is undefined. Write: No effect.
bit5	LBD: LIN Synch Break detection flag bit (Functions only in the slave operation)	"0" Read : No Synch Break "1" Read : There is a Synch Break "0" write: Clear LBD flag "1" write: No effect This bit indicates a detection of LIN Synch Break. The LBD bit is set to "1" when the serial input (SIN) is "0" for more than 11-bit width. In this case, if the LIN Synch Break interrupt enable bit (LBIE) is set to "1", a status interrupt will be generated. (For reading) "1": LIN Synch Break has been detected. "0": LIN Synch Break has not been detected. (For writing) "0": LBD bit will be cleared. "1": No effect. Notes: · This function is enabled only in the slave operation. · If a read-modify-write instruction is executed, "1" will be read out.

Bit name		Function
bit4	FRE: Framing error flag bit	<p>"0" Read : No framing error "1" Read : There is a framing error</p> <ul style="list-style-type: none"> · If a framing error occurs while a reception is in progress, this bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). · When the FRE bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · If this flag is set, data contained in the receive data register (RDR) becomes invalid. · When this flag is set while using the reception FIFO, the reception FIFO enable bit will be cleared. As a result, the reception data will not be stored in the reception FIFO.
bit3	ORE: Overrun error flag bit	<p>"0" Read :No overrun error "1" Read :There is an overrun error</p> <ul style="list-style-type: none"> · If an overrun error occurs while a reception is in progress, this bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). · When the ORE bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · If this flag is set, data contained in the receive data register (RDR) becomes invalid. · When this flag is set while using the reception FIFO, the reception FIFO enable bit will be cleared. As a result, the reception data will not be stored in the reception FIFO.
bit2	RDRF: Reception data full flag bit	<p>"0" Read :Receive data register (RDR) is empty "1" Read :Receive data register (RDR) contains data.</p> <ul style="list-style-type: none"> · The flag indicates the state of the receive data register (RDR). · When received data is loaded in RDR, this flag will be set to "1" and when RDR is read out, it will be cleared to "0". · When the RDRF bit and the SCR:RIE bit are set to "1", a reception interrupt request will be output. · While using reception FIFO, the RDRF will be set to "1" once the reception FIFO has received the specified number of data sets. · While using reception FIFO, the bit will be cleared to "0" once the reception FIFO becomes empty.

Bit name		Function
bit1	TDRE: Transmission data empty flag bit	<p>"0" Read :Transmit data register (TDR) contains data. "1" Read :Transmit data register (TDR) is empty</p> <ul style="list-style-type: none"> · The flag indicates the state of the transmit data register (TDR). · When a transmission data is written to TDR, this flag turns to "0", which indicates that a valid data exists in the TDR. Once a transmission starts after data being loaded to the transmit shift register, the bit will be set to "1", which indicates that the TDR does not contain any valid data. · When the TDRE bit and the SCR:TIE bit are set to "1", a transmission interrupt request will be output. · When you set the UPCL bit of the serial control register (SCR) to "1", the TDRE bit will be set to "1". · For details of the timing of setting/resetting the TDRE bit while using transmission FIFO, see "7.1.5 Interrupts When Using Transmission FIFO and Flag Setting Timing".
bit0	TBI: Transmission bus idle flag bit	<p>"0" Read :Transmitting "1" Read :No transmission operation</p> <ul style="list-style-type: none"> · This bit indicates that LIN-UART has no transmission in progress. · When transmission data has been written to the transmit data register (TDR), this bit will become "0". · If the LIN Break field is set (SCR:LBR=1), this bit will be cleared to "0". · When the transmit data register (TDR) is empty (TDRE=1) and no transmission is in progress, this bit will be set to "1". · If the LIN Break field transmission has ended, and the transmit data register is empty, this bit will be set to "1". · When this bit is "1" and transmission bus idle interrupts are enabled (SCR:TBIE=1), a transmission interrupt request will be output.

4.4.3. Extended Serial Control Register : ESCR

The bit configuration of the extended serial control register is shown below.

The extended serial control register (ESCR) is used to select LIN Synch Break interrupt enable/disable, LIN Synch Break detection, LIN Synch Break length, Synch delimiter length settings, and stop bit length.

■ **ESCR : Address 00B3_H, 00C3_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	ESBL	Reserved	LBIE	LBL[1:0]		DEL[1:0]	
Initial value	-	0	-	0	0	0	0	0
Attribute	R0,W0	R/W	RX,WX	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	Reserved	This is undefined bit. The read value is always "0". Always write "0" to this bit.
bit6	ESBL: Extended stop bit length selection bit	This bit configures the bit length of stop bit (frame end mark for transmission data). When SMR:SBL=0 and ESBL=0 are set: stop bit is set to 1-bit. When SMR:SBL=1 and ESBL=0 are set: stop bits are set to 2-bit. When SMR:SBL=0 and ESBL=1 are set: stop bits are set to 3-bit. When SMR:SBL=1 and ESBL=1 are set: stop bits are set to 4-bit. Notes: · When receiving, only the first bit of the stop bits will always be detected. · This bit should be set when transmission is disabled (TXE=0).
bit5	Reserved	Read: The value is undefined. Write: No effect.
bit4	LBIE: LIN Synch Break detection Interrupt enable bit	The bit to enable/disable LIN Synch Break detection interrupt. A reception interrupt occurs when LIN Synch Break detection flag (SSR:LBD) is set to "1" and interrupts are enabled (LBIE=1). Notes: · To detect a LIN synch break, enable LIN synch break detection interrupt (LBIE=1), and then disable reception (SCR:RXE=0).
bit3, bit2	LBL[1:0]: LIN synch break length selection bits (Functions only in the master operation)	00 : 13-bit length 01 : 14-bit length 10 : 15-bit length 11 : 16-bit length · These bits set the length of LIN Synch Break generation time interval (in bits). · Before you set the LBR bit in the serial control register (SCR) to "1" (LIN Synch Break transmission), set this bit. · The timing of Lin Synch Break detection is always the 11th bit at slave operation, regardless of the set value of this bit. Note: This function is enabled only in the master operation.

Bit name		Function
bit1, bit0	DEL[1:0]: LIN synch delimiter length selection bits (Functions only in the master operation)	00 : 1-bit length 01 : 2-bit length 10 : 3-bit length 11 : 4-bit length · These bits set the length of LIN Synch delimiter (in bits). · Before you set the LBR bit in the serial control register (SCR) to "1" (LIN Synch Break transmission), set this bit. Note: This function is enabled only in the master operation.

4.4.4. Receive Data Register/Transmit Data Register : RDR/TDR

The bit configuration of the receive data register/transmit data register is shown below.

The receive data register and transmit data register are located within the same addresses. When read, it functions as the receive data register and when written, it functions as the transmit data register.

■ **RDR/TDR: Address 00B4_H, 00C4_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

Read

The receive data register (RDR) is the data buffer register for serial data reception.

- Serial data signals sent to the serial input pin (SIN) are converted in the shift register and stored in the receive data register (RDR).
- When the received data is stored in the receive data register (RDR), the reception data full flag bit (SSR:RDRF) will be set to "1". When the reception interrupt is enabled (SSR:RIE=1), reception interrupt requests will be generated.
- The receive data register (RDR) should be read out when the reception data full flag bit (SSR:RDRF) is "1". The reception data full flag bit (SSR:RDRF) will be automatically cleared to "0" when the serial receive data register (RDR) has been read out.
- In case a reception error occurs (SSR:either ORE or FRE is "1"), data in the receive data register (RDR) will become invalid.

Notes:

- When you use reception FIFO, if received data in the reception FIFO reaches specified number, "1" will be set to SSR:RDRF.
- When you are using reception FIFO, if the reception FIFO becomes empty, SSR:RDRF will be cleared to "0".
- If a reception error occurs (either SSR:ORE or SSR:FRE is "1") while using reception FIFO, the reception FIFO enable bit will be cleared. As a result, data received will not be stored at the reception FIFO.

Write

The transmit data register (TDR) is the data buffer register for sending serial data.

- When transmission operations are enabled (SCR:TXE=1), if transmission data is written to the transmit data register (TDR), the transmission data is transferred to the transmit shift register and converted to serial data, then output from the serial data output pin (SOUT).
- The transmission data empty flag (SSR:TDRE) will be cleared to "0" when the transmission data is written to the transmit data register (TDR).
- The transmission data empty flag (SSR:TDRE) will be set to "1" once a transmission starts after the transmission data has been transferred to the transmit shift register if the transmission FIFO is disabled or empty.
- If the transmission data empty flag (SSR:TDRE) is "1", the next transmission data can be written. If the transmission interrupt is enabled, a transmission interrupt will occur. Writing the next transmission data should be performed by the generation of transmission interrupt or be done when the transmission data empty flag (SSR:TDRE) is "1".
- You will not be able to write transmission data to the transmit data register (TDR) when the transmission data empty flag (SSR:TDRE) is "0" and transmission FIFO is disabled or full.

Notes:

- The transmit data register is write-only register and the receive data register is read-only register. Because the two registers are located in the same address, the write value and read value might be different. Therefore instructions such as INC/DEC instructions which perform the read-modify-write (RMW) operation cannot be used.
- For more information about the set timing of the transmission data empty flag (SSR:TDRE) when using the transmission FIFO, see "7.1.5 Interrupts When Using Transmission FIFO and Flag Setting Timing".

4.4.5. Baud rate Generator Register : BGR

The bit configuration of the baud rate generator register is shown below.

The baud rate generator register (BGR) sets the division ratio of serial clock. It can also select an external clock as the clock source of reload counter.

■ **BGR : Address 00B6_H, 00C6_H (Access: Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	BGR[14:8]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BGR[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15] EXT (EXTernal clock) : External clock selection bit

This bit selects whether to use an internal clock source or an external clock source for the internal reload counter for baud rate generation. When setting EXT=1, the external clock source will be used.

[bit14 to bit0] BGR[14:0] (Baud rate Generator)

These bits set the reload value for internal reload counter for baud rate generation. When the reload value is written in this register, the reload counter begins counting.

Notes:

- Write to the baud rate generator register (BGR) in 16-bit access mode.
- If the value of BGR is an even number, the "H" width of a serial clock is 1 cycle shorter than that of the "L" width. If it is an odd number, the duty ratio will be 1:1.
- If you change to the setting of External clock(EXT=1) in operation of baud rate generator, you write "0" in baud rate generator(BGR) and execute a programmable clear(SCR:UPCL), then set External clock(EXT=1).
- When you change the setting value of the baud rate generator register (BGR), a new setting value will be reloaded after the counter value becomes "15h00". Thus, if you wish to validate a new setting value immediately, execute programmable clear (SCR:UPCL) after you have change the setting value of BGR1/BGR0.
- Set the value of three or more to BGR. However, it is not likely to be able to receive the data normally by the error margin of the baud rate and setting the reload value.

4.5. Registers for I²C

Registers for I²C are shown.

- 4.5.1. I2C Bus Control Register : IBCR
- 4.5.2. Serial Status Register : SSR
- 4.5.3. I2C Bus Status Register : IBSR
- 4.5.4. Receive Data Register/Transmit Data Register : RDR/TDR
- 4.5.5. Baud rate Generator Register : BGR
- 4.5.6. I2C 7-bit Slave Address Mask Register : ISMK
- 4.5.7. I2C 7-bit Slave Bus Address Register : ISBA

4.5.1. I²C Bus Control Register : IBCR

The bit configuration of the I²C bus control register is shown below.

The I²C bus control register (IBCR) indicates master/slave selection, generation of repeat start condition, acknowledge enable, interrupt enable setting, and display of interrupt flag.

■ **IBCR : Address 00B0_H, 00C0_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MSS	ACT/SCC	ACKE	WSEL	CNDE	INTE	BER	INT
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R,WX	R(RM1), W

Bit name		Function
bit7	MSS: Master/ slave selection bit	<ul style="list-style-type: none"> This bit selects master mode when it is set to "1" while I²C bus is in the idle state (ISMK:EN=1, IBSR:BB=0) When the BB bit in IBSR register is "1" if you set "1" to this bit, this microcontroller waits for the start condition until the BB bit turns to "0". While waiting, if the slave address matches and it operates as slave, this bit will turn to "0", the AL bit in IBSR register will turn to "1". When master is running (MSS=1, ACT=1) and interrupt flag (INT) is "1", if you write "0" to this bit, a stop condition occurs. <p>The MSS bit will be cleared on the following conditions.</p> <ol style="list-style-type: none"> I²C interface disable (ISMK:EN bit=0) When arbitration lost occurred Bus error detected (BER bit=1) Write "0" to the MSS bit when INT =1 The DMA mode is enabled (SSR:DMA=1) and "0" writing in the MSS bit at SSR:TBI =1. <p>The relation between the MSS bit and ACT bit is as follows.</p> <p>MSS=0, ACT=0 idle MSS=0, ACT=1 slave address matches or responds ACK* to the reserved address and the slave is in operation (slave mode) MSS=1, ACT=0 master operation wait MSS=1, ACT=1 master is in operation (master mode)</p> <p>*: ACK response: indicates that SDA of I²C bus is "L" in the acknowledge interval.</p> <p>Notes:</p> <ul style="list-style-type: none"> If the DMA mode is disabled (SSR:DMA=0) also MSS bit is set as "1", go at MSS bit =1 and INT bit =1 when you change the MSS bit to "0". When "0" is written in the MSS bit when the ACT bit is "1", the INT bit is cleared to "0". If the DMA mode is enabled (SSR:DMA=1), also MSS bit is set as "1", go when MSS bit =1, INT bit =1 or the SSR:TBI bit is "1" when the MSS bit is changed to "0". When "0" is written in the MSS bit when the ACT bit is "1", the INT bit is cleared to "0". While the master is in operation, even if you write "0" to the MSS bit, "1" will still be read out while the ACT bit stays "1".

Bit name	Function
<p>bit6</p> <p>ACT/SCC: Operation flag/repeat start condition generation bit</p>	<p>This bit differs in meanings between read and write. Read: ACT bit Write: SOC bit The ACT bit indicates whether the operation is in master mode or slave mode. ACT bit set conditions: (1) When outputting a start condition to I²C bus (master mode) (2) When the slave address matches the address sent from the master (slave mode) (3) When the reserved address was detected and an acknowledge response was sent toward it (slave mode with MSS=0) ACT bit reset conditions: <Master mode> (1) A stop condition detected (2) Arbitration lost detected (3) A bus error detected (4) I²C interface disable (ISMK:EN bit=0) <Slave mode> (1) (Repeat) start condition detected (2) A stop condition detected (3) Reserved address detected state (IBSR:RSA=1) and no acknowledge response sent (4) I²C interface disable (ISMK:EN bit=0) (5) A bus error occurs (BER bit=1) When in master mode, writing "1" to this bit executes a repeat start. Writing "0" to this bit is ignored. Notes: · Write "1" to the SCC bit while master mode is interrupted (MSS=1, ACT=1, INT=1). If the ACT bit is "1", writing "1" to the SCC bit when the ACT bit is "1" clears the INT bit to "0". · Writing "1" to this bit is disabled during slave mode (MSS=0, ACT=1). · When you write "1" to the SCC bit and "0" to the MSS bit, the MSS bit will take precedence. · For read-modify-write instructions, the SCC bit will be read. · If "1" writing in the SCC bit and NACK is received by the ninth bit when interrupting the master mode in the eighth bit (MSS=1, ACT=1, INT=1, WSEL=1), "1" is set in the INT bit and I²C bus wait (SCL="L"). It is necessary to write "1" in the SCC bit again to generate the repetition start condition, and to clear the INT bit. · If you issues the repetition start condition when the DMA mode is enabled (SSR:DMA=1), also the SSR:TBI bit is set as "1" and the INT bit is set as "0", please write the slave address in TDR and set "1" to this bit after "1" is written in the INT bit also confirm the INT bit is set in "1".</p>

Bit name		Function
bit5	<p>ACKE: Data byte acknowledge enable bit</p>	<ul style="list-style-type: none"> · If you set "1" to this bit, "L" will be output at the time of acknowledgement. · If ACT = 1, change this bit when the INT bit is "1". · If you change this bit when the DMA mode is disabled (SSR:DMA=0) also ACT=1, please do it when the INT bit is "1" and DMA interruption permission (SSM:DMA=1) also the SSR:TBI bit is "1", or DMA interruption permission (SSM:DMA=1) and slave reception also SSM:RDRF is "1". · If you change this bit when the DMA mode is enabled (SSR:DMA=1) also ACT=1, please do the INT bit is "1" and the SSR:TBI bit is "1", or slave reception and SSM:RDRF bit is "1". <p>This bit will be disabled on the following conditions.</p> <ol style="list-style-type: none"> (1) Acknowledgement for address fields except for reserved address (automatic generation). (2) At data transmission (IBSR:RSA=0, IBSR:TRX=1, IBSR:FBT=0). (3) At slave reception with reception FIFO enable (FCR0:FE=1, MSS=0, ACT=1), it always responds with ACK. (4) When reception FIFO is enabled and WSEL is "0" at master reception (FCR0:FE=1, MSS=1, ACT=1, WSEL=0), when the SSR:TDRE bit is "0", it responds with ACK and when the SSR:TDRE bit is "1", it responds with NACK. (5) When reception FIFO is enabled, WSEL=0, the reserved address is detected and slave is transmitted (IBSR:RSA=1, IBSR:TRX=1, IBSR:FBT=1), it always responds with ACK. If you want to respond with NACK, at an interrupt after the detection of reserved address, disable reception FIFO and set ACKE=0. (6) When reception FIFO is enabled and WSEL is "1", the transmit data register has data on master reception (FCR0:FE=1, MSS=1, ACT=1, WSEL=1, SSR:TDRE=0).
bit4	<p>WSEL: Wait selection bit</p>	<ul style="list-style-type: none"> · When the DMA mode is disabled (SSR:DMA=0), this bit is enable to select whether I²C bus is waited by generating interrupt (INT=1) at before or behind of the acknowledge. · When the DMA mode is enabled (SSR:DMA=1), this bit is enable to select whether I²C bus is waited by generating interrupt (INT=1, SSR:TBI=1 at the time of transmission, SSR:RDRF=1 at the time of reception) at before or behind of the acknowledge. · The WSEL bit will be disabled on the following condition. <ol style="list-style-type: none"> (1) When an interrupt to the first byte*1 is generated (INT=1) (2) When a reserved address is detected (IBSR:FBT=1,IBSR: RSA=1) (3) While the data transfer is in progress using FIFO and when NACK response *2 is detected (FCR0:FE=1, IBSR:RACK=1, ACT=1) (4) When reception FIFO is used and reception FIFO becomes FULL <p>*1: The first byte: indicates data after the (repeat) start condition. *2: NACK response: indicates that SDA of I²C bus is "H" in the acknowledge interval.</p>
bit3	<p>CNDE: Condition detection interrupt enable bit</p>	<p>This bit is used to enable interrupts when a stop condition or a repeat start condition is detected in master mode or in slave mode (ACT=1). When the RSC bit or the SPC bit in the IBSR register is "1" and this bit is "1", an interrupt occurs.</p>
bit2	<p>INTE: Interrupt enable bit</p>	<p>This bit is used to enable interrupts to the data transmission/reception and bus error in master mode or in slave mode (INT=1).</p>

Bit name		Function
bit1	BER: Bus error flag bit	<p>This bit indicates that an error has been detected on I²C bus.</p> <p>BER bit set conditions:</p> <ul style="list-style-type: none"> (1) While the first byte* transferring, the bit detects a start condition or a stop condition. (2) For the second byte or later, the bit detects a (repeat) start condition or a stop condition at the 2-9th (acknowledge) bit of data. <p>BER bit reset conditions:</p> <ul style="list-style-type: none"> (1) Write "0" to the INT bit when BER = 1 (2) I²C interface disable (EN bit=0) <p>*: The first byte: indicates data after the (repeat) start condition.</p> <p>Note: Please Check for this flag when interrupt flag (INT bit) turns "1" and if this bit is "1", please process re-transmission etc because normal send/receive operations cannot have been performed.</p>
bit0	INT: Interrupt flag bit	<p>Sets this flag to "1" when in master or slave mode, after 8-bit or 9-bit (ACK) of the data transmission/reception, or upon a bus error. When the INT bit is "1", the state of SCL turns to "L" and when the bit is "0", the "L" state is released except for bus errors.</p> <p>INT bit set conditions:</p> <p><8th bit></p> <p><It is unrelated to the DMA mode ></p> <ul style="list-style-type: none"> (1)When a reserved address is detected in the first byte (2) When WSEL is "1" and arbitration lost is detected in the second byte or later <p>< When DMA mode is disabled (SSR:DMA=0)></p> <ul style="list-style-type: none"> (3) When DMA mode is disabled (SSR:DMA=0), WSEL is "1" and the SSR:TDRE bit is "1" in the second byte or later in master operation (4) When DMA mode is disabled (SSR:DMA=0), WSEL is "1" and reception FIFO is disabled, the SSR:TDRE bit is "1" in the second byte or later in slave operation (5) When DMA mode is disabled (SSR:DMA=0), WSEL is "1" and the SSR:TDRE bit is "1" in the second byte or later in slave transmission (6) When DMA mode is disabled (SSR:DMA=0), WSEL is "1" and reception FIFO is disabled in the slave reception <p>< When DMA mode is enabled (SSR:DMA=1)></p> <ul style="list-style-type: none"> (7) When DMA mode is enabled (SSR:DMA=1), WSEL is "1" and the SSR:TBI bit is "1" and write the INTbit to "1" in the second byte or later in master operation <p><9th bit></p> <p>< It is unrelated to the DMA mode ></p> <ul style="list-style-type: none"> (1) When arbitration lost is detected in the first byte (2) When NACK is received except for stop condition setting (write "0" to MSS bit in master operation) (3) When WSEL is "0" and arbitration lost is detected in the second byte or later (4) In the first byte, no reserved address is detected in the receiving direction in master or slave mode (IBSR:TRX=0) and there are reception FIFO data at reception FIFO enable state <p>< When DMA mode is disabled (SSR:DMA=0)></p> <ul style="list-style-type: none"> (5) When DMA mode is disabled (SSR:DMA=0), in the first byte, no reserved address is detected and the SSR:TDRE bit is "1" in the receiving direction in master or slave mode (IBSR:TRX=1) (6) When the DMA mode is disabled (SSR:DMA=0), the master mode without detecting the reservation address in the first byte or the SSR:TDRE bit is "1" when reception FIFO is disabled at mode of production is received (7) When DMA mode is disabled (SSR:DMA=0), WSEL is "0" and the SSR:TDRE bit is "1" in the second byte or later in master operation (8) When DMA mode is disabled (SSR:DMA=0), WSEL is "0" and the SSR:TDRE bit is "1" in the second byte or later in slave transmission

Bit name	Function
	<p>(9) When DMA mode is disabled (SSR:DMA=0), WSEL is "0" and reception FIFO is disabled in slave reception. However, for slave reception at the first byte where a reserved address is detected, an interrupt will not occur at the 9th bit.</p> <p>(10) When DMA mode is disabled (SSR:DMA=0), reception FIFO enable, for slave reception, when FIFO is Full</p> <p>< When DMA mode is enabled (SSR:DMA=1)></p> <p>(11) When DMA mode is enabled (SSR:DMA=1), in the first byte, no reserved address is detected and the SSR:TDRE bit is "1" in the transmitting direction in slave mode (IBSR:TRX=1)</p> <p>(12) When DMA mode is enabled (SSR:DMA=1), in the first byte, no reserved address is detected, the SSR:TDRE bit is "1" in the receiving direction in slave mode (IBSR:TRX=0) and reception FIFO is disabled</p> <p>(13) When DMA mode is enabled (SSR:DMA=1), WSEL is "0" and when you write "1" in the INT bit while the master mode is operating when the SSR:TBI bit is "1" in the second byte or later in master operation</p> <p><Other></p> <p>(1) Bus error detected</p> <p>INT bit reset conditions:</p> <p>(1) write "0" to INT bit</p> <p>(2) INT bit is "1", write "0" to MSS bit when ACT bit is "1"</p> <p>(3) INT bit is "1", write "1" to SCC bit when ACT bit is "1"</p> <p>When DMA mode is disabled (SSR:DMA=0), writing "1" to this bit will not be effective.</p> <p>Notes:</p> <ul style="list-style-type: none"> · When the DMA mode is enabled (SSR:DMA=1) and the INT bit is set to "1" while the SSR:TBI bit is "1" after the second byte in the master mode, status interrupt (SIRQ=1) is not generated. · When the DMA mode is enabled (SSR:DMA=1) and if the SSR:TBI bit issues the repetition start condition when it is "1" and the INT bit is "0", after "1" is written in the INT bit, write the slave address in TDR after confirming the INT bit is set in "1" and set "1" to the SCC bit. · If "0" is written in the INT flag when the INT flag is set in "1", the wait of the I²C bus is released. · When the ISMK:EN bit is "0", the SSR:RDRF bit and the INT bit might be "1" depending on the reception timings. In this case, read the received data and clear the INT bit. · For read-modify-write instructions, "1" will be read. · When reception FIFO is enabled, even if reception FIFO is Full on the master reception operation, "1" will not be set to the INT bit.

4.5.2. Serial Status Register : SSR

The bit configuration of the serial status register is shown below.

The serial status register (SSR) checks for the transmission/reception states.

■ **SSR : Address 00B2_H, 00C2_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	REC	TSET	DMA	TBIE	ORE	RDRF	TDRE	TBI
Initial value	0	0	0	0	0	0	1	1
Attribute	R0,W	R0,W	R/W	R/W	R,WX	R,WX	R,WX	R,WX

Bit name		Function
bit7	REC: Reception error flag clear bit	This bit clears the ORE bit of the serial status register (SSR) <ul style="list-style-type: none"> · Writing "1" clears the ORE bit. · Writing "0" does not affect anything. A read always results in "0".
bit6	TSET: Transmission buffer empty flag set bit	This bit sets the TDRE bit in the serial status register (SSR) <ul style="list-style-type: none"> · Writing "1" sets the TDRE bit and also sets the TBI bit if the DMA mode is enabled (SSR:DMA=1).. · Writing "0" does not affect anything. A read always results in "0". Note: Write "1" in this bit when the IBCR:INT bit is "1".
bit5	DMA: DMA mode enable bit	This bit enables/disables the DMA mode. <ul style="list-style-type: none"> · When this bit is set in "1", it becomes an interruption condition corresponding to the DMA Transfer. · When this bit is set to "0", it becomes an interrupt condition during the normal transfer. See "Table 8-1" for details. Note: Only when ISMK:EN=0, this bit can be changed.
bit4	TBIE: Transmission bus idle enabled bit (Only the DMA mode enabled is effective.)	<ul style="list-style-type: none"> · This bit enables/disables the transmission bus idle interrupt demand output to CPU. · When the DMA mode is enabled (DMA=1) and the TBIE bit and the TBI bit are "1", the DMA mode outputs the transmission bus idle interrupt request. · When the DMA mode is disabled (DMA=0),this bit becomes "0" and no matter what this bit is written, writing is ignored and this bit keep the state of "0".

Bit name		Function
bit3	ORE: Overrun error flag bit	<p>"0" Read :No overrun error "1" Read :There is an overrun error</p> <ul style="list-style-type: none"> · If an overrun error occurs while a reception is in progress, this bit will be set to "1". To clear this bit, write "1" to the REC bit of the serial status register (SSR). · When the ORE bit and SMR:RIE bit are set to "1", a reception interrupt request will be output. · If this flag is set, the receive data register (RDR) will be disabled. · When you are using the reception FIFO, if this flag is set, the received data will not be stored in the reception FIFO.
bit2	RDRF: Reception data full flag bit	<p>"0" Read :Receive data register (RDR) is empty "1" Read :Receive data register (RDR) contains data.</p> <ul style="list-style-type: none"> · The flag indicates the state of the receive data register (RDR). · When the RIE bit and the reception data flag bit (RDRF) are "1", a reception interrupt request will be output. · When received data is loaded in the RDR, this flag will be set to "1" and when RDR is read out, it will be cleared to "0". · Set at the SCL falling timing in 8th bit of the data. · Also set at the NACK response*. · While using reception FIFO, the RDRF will be set to "1" once the reception FIFO has received the specified number of data sets. · While using reception FIFO, the bit will be cleared to "0" once the reception FIFO becomes empty. · When you use reception FIFO, if the reception FIFO contains data without receiving the specified number of data sets and the reception idle state has continued for 8 baud rate clocks or longer, the RDRF will be set to "1" with the IBCR:BER bit set to "0". If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. <p>*: NACK response: indicates that SDA of I²C bus is "H" in the acknowledge interval.</p> <p>Note:</p> <ul style="list-style-type: none"> · In case that the reception FIFO is unused, DMA mode is enabled (DMA=1), the RDRF bit is "1", and the WSEL bit is "0", SCL turns to "L" after ACK transmission. It is released after the RDRF bit become "0". · In case that the reception FIFO is unused, DMA mode is enabled (DMA=1), the RDRF bit is "1", and the WSEL bit is "1", SCL turns to "L" after 1 byte data reception. It is released after the RDRF bit become "0". · In case that the reception FIFO is used, DMA mode is enabled (DMA=1), SCL turns to "L" when the reception FIFO is full. It is released after the reception FIFO becomes not full.

Bit name		Function
bit1	TDRE: Transmission data empty flag bit	<p>"0" Read : Transmit data register (TDR) contains data. "1" Read :Transmit data register (TDR) is empty</p> <ul style="list-style-type: none"> · The flag indicates the state of the transmit data register (TDR). · When the TDRE bit and the TIE bit are set to "1", a transmission interrupt request will be output. · When a transmission data is written to TDR, this flag turns to "0", which indicates that a valid data exists in the TDR. Once a transmission starts after data being loaded to the transmission shift register, the bit will be set to "1", which indicates that the TDR does not contain any valid data. · Writing "1" to the TSET bit on the serial status register (SSR) results in a setting. Use this flag for setting "1" to the TDRE bit when detecting an arbitration lost or a bus error.
bit0	TBI: Transmission bus idle flag bit (Only the DMA mode enabled is effective.)	<p>This bit is a bit that shows that I²C does not do the transmission operation when the DMA mode is enabled (DMA=1). When the DMA mode is enabled (DMA=1) and the TBI bit becomes "1" after the second byte, the SCL becomes "L". The SCL is released from the state of "L" when the TBI bit becomes "0".</p> <p>Set condition of TBI bit :</p> <p>< 8th bit ></p> <ol style="list-style-type: none"> (1) In the 2nd or subsequent byte , the TDRE bit is "1" while WSEL is "1" and the master is operating (2) In the 2nd or subsequent byte , the SSR:TDRE bit is "1" while WSEL is "1" and the slave is transmitting <p>< 9th bit></p> <ol style="list-style-type: none"> (1) The SSR:TDRE bit is "1" without detecting the reservation address in the first byte while the master is operating (2) In the 2nd or subsequent byte , the SSR:TDRE bit is "1" while IBCR:WSEL is "0" and the master is operating (3) In the 2nd or subsequent byte , the SSR:TDRE bit is "1" while IBCR:WSEL is "0" and the slave is transmitting <p><other></p> <p>When the transmission buffer empty flag set bit (TSET) is set to "1"</p> <p>Reset condition of TBI bit :</p> <ol style="list-style-type: none"> (1) If the transmission data is written to the transmission data register (TDR) <p>When this bit is "1" and the transmission bus idle interrupt is enabled (SCR:TBIE=1), this bit outputs the transmission interruption request.</p> <ul style="list-style-type: none"> · This bit is undefined when the DMA mode is disabled (DMA=0).

4.5.3. I²C Bus Status Register : IBSR

The bit configuration of the I²C bus status register is shown below.

The I²C bus status register (IBSR) indicates that repeat starts, acknowledges, data directions, arbitration lost, stop conditions, I²C bus states, and bus errors have been detected.

■ **IBSR: Address 00B3_H, 00C3_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
FBT	RACK	RSA	TRX	AL	RSC	SPC	BB

Initial value	0	0	0	0	0	0	0	
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R(RM1), W	R(RM1), W	R,WX

Bit name		Function
bit7	FBT: First byte bit	"0" Read: Other than the first byte "1" Read: Transmitting/receiving the first byte This bit indicates the first byte. FBT bit set conditions: (1) When (repeat) starts condition detected FBT bit clear conditions: (1) Transmission/reception of the 2nd byte (2) A stop condition detected (3) I ² C interface disable (ISMK:EN bit=0) (4) Bus error detected (IBCR:BER bit=1)
bit6	RACK: Acknowledge flag bit	"0" Read: "L"Reception "1" Read: "H"Reception This bit indicates the acknowledges received on the first byte, in master or slave mode. Update condition for RACK bit (1) Acknowledgement at the first byte (2) Acknowledgement of the data in master or slave mode Clear condition of RACK bit (RACK bit=0) (1) (Repeat) start condition detected (2) I ² C interface disable (ISMK:EN bit=0) (3) Bus error detected (IBCR:BER bit=1)

Bit name		Function
bit5	RSA: Reserved address detection bit	<p>"0" Read: No reserved address detected "1" Read: Reserved address detected</p> <p>This bit indicates that a reserved address was detected.</p> <p>RSA bit set condition (RSA=1) (1) The first byte is (0000xxxx) or (1111xxxx). "x" represents "0" or "1".</p> <p>RSA bit set condition (RSA=0) (1) A (repeat) start condition detected (2) A stop condition detected (3) I²C interface disable (ISMK:EN bit=0) (4) Bus error detected (IBCR:BER bit=1)</p> <p>When the RSA bit is "1" at the first byte, the interrupt flag (IBCR:INT) turns to "1" and SCL turns to "L" at SCL falling edge of the 8th bit on the first byte, regardless of the FIFO enable/disable state. Read the received data and if you want to make it perform as slave, set IBCR:ACKE to "1" and set the interrupt flag (IBCR:INT) to "0". After that, if the TRX bit is "0", the data is received as the slave. When you are planning not to receive data at a relay point, set "0" to the IBCR:ACKE bit. After that, no data is received.</p> <p>Notes:</p> <ul style="list-style-type: none"> · When you turn IBCR:ACKE to "0" while data transfer is going on, do not set IBCR:ACKE to "1" until a stop condition or a repeat start condition is detected. · When a reserved address detection interrupt occurs and you identify a slave transmission, if the reception FIFO is enabled, it would respond with ACK, so disable the reception FIFO and turn to IBCR:ACKE=0.
bit4	TRX: Data direction bit	<p>"0" Read: Reception direction "1" Read: Transmission direction</p> <p>This bit indicates the direction of data.</p> <p>TRX bit set conditions: (1) Send a (repeat) start condition in master mode (2) When the 8th bit of the first byte is "1" in slave mode (transmission direction as a slave)</p> <p>TRX bit reset conditions: (1) Arbitration lost is generated(AL=1) (2) When the 8th bit of the first byte is "0" in slave mode (reception direction as a slave) (3) When the 8th bit of the first byte is "1" in master mode (reception direction as a master) (4) A stop condition detected (5) Detect a (repeat) start condition in a mode other than master mode (6) I²C interface disable (ISMK:EN bit=0) (7) Bus error detected (IBCR:BER bit=1)</p>

Bit name		Function
bit3	AL: Arbitration lost bit	<p>"0" Read: No arbitration lost occurred "1" Read: Arbitration lost occurred</p> <p>This bit indicates an arbitration lost.</p> <p>AL bit set conditions:</p> <ol style="list-style-type: none"> (1) When the data output in master mode and received data are different. (2) You set "1" to the MSS bit but the operation is still in slave mode. (3) A repeat start condition was detected at the first bit of the second byte or later in master mode. (4) A stop condition was detected at the first bit of the second byte or later in master mode. (5) Trying to generate a repeat start condition but cannot do so in master mode. (6) Trying to generate a stop condition but cannot do so in master mode. <p>AL bit reset conditions:</p> <ol style="list-style-type: none"> (1) Writing "1" to the MSS bit (2) Writing "0" to the INT bit (3) Writing "0" to SPC bit when AL=1 and SPC=1 (4) I²C interface disable (ISMK:EN bit=0) (5) Bus error detected (IBCR:BER bit=1)
bit2	RSC: Repeat start condition check bit	<p>"0" Read: No repeated start condition detected "1" Read: Repeated start condition detected</p> <p>This bit indicates that repeat start condition was detected in master mode or slave mode.</p> <p>RSC bit set conditions</p> <ol style="list-style-type: none"> (1) A repeat start condition was detected after acknowledgement in master mode or slave mode <p>RSC bit reset conditions:</p> <ol style="list-style-type: none"> (1) Writing "0" to the RSC bit (2) Writing "1" to the IBCR:MSS bit (3) I²C interface disable (ISMK:EN bit=0) <p>There will be no effect on the operation of writing "1" to this bit.</p> <p>Notes:</p> <ul style="list-style-type: none"> · If you do not respond with acknowledge when receiving data as the slave mode due to the detection of the reserved address, this bit will not be set "1" even if a repeat start condition is detected at the next time because it has already exited the slave mode. · For read-modify-write instructions, "1" will be read.

Bit name		Function
bit1	SPC: Stop condition check bit	<p>"0" Read: No stop condition detected "1" Read : (Master) stop condition detected or generation of arbitration lost at stop condition output "1" Read : (Slave) stop condition detected</p> <p>This bit indicates that stop condition was detected in master mode or slave mode. SPC bit set conditions: (1) A stop condition was detected in master mode or slave mode (2) An arbitration lost is generated on the stop condition generation in master mode SPC bit reset conditions: (1) Writing "0" to this bit (2) Writing "1" to the IBCR:MSS bit (3) I²C interface disable (ISMK:EN bit=0) There will be no effect on the operation of writing "1" to this bit.</p> <p>Notes: · If you do not respond with acknowledge when receiving data as the slave mode due to the detection of the reserved address, this bit will not be set "1" even if a stop condition is detected at the next time because it has already exited the slave mode. · For read-modify-write instructions, "1" will be read.</p>
bit0	BB: Bus state bit	<p>"0" Read: Bus idle state "1" Read: Bus transmission/reception state</p> <p>This bit indicates the bus state. BB bit set conditions: (1) When "L" was detected at SDA or SCL on I²C bus BB bit reset conditions: (1) When a stop condition detected (2) I²C interface disable (ISMK:EN bit=0) (3) Bus error detected (IBCR:BER bit=1)</p>

4.5.4. Receive Data Register/Transmit Data Register : RDR/TDR

The bit configuration of receive data register/transmit data register is shown below.

Receive data register and transmit data register are located within the same addresses. When read, it functions as the receive data register and when written, it functions as the transmit data register. When FIFO enabled, the address of RDR/TDR will be the address for reading/writing FIFO.

■ **RDR/TDR: Address 00B4_H, 00C4_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	0	0	0	0	0	0	0	0
Attribute	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Read

The receive data register (RDR) is the data buffer register for serial data reception.

- Serial data signals sent to the serial data line (SDA) are converted in the shift register and stored in the receive data register (RDR).
- When you receive the first byte*1, the least significant bit (RDR:D0) is the data direction bit.
- When the received data is stored in the receive data register (RDR), the reception data full flag bit (SSR:RDRF) will be set to "1".
- The reception data full flag bit (SSR:RDRF) will be automatically cleared to "0" when the receive data register (RDR) has been read out.

*1 : The first byte: indicates data after the (repeat) start condition.

Notes:

- When you use reception FIFO, if received data in the reception FIFO reaches specified number, "1" will be set to SSR:RDRF.
- When you are using reception FIFO, if the reception FIFO becomes empty, SSR:RDRF will be cleared to "0".

Write

The transmit data register (TDR) is the data buffer register for sending serial data.

- Output to serial data line (SDA pin) at the MSB first on transmit data register (TDR).
 - When you send the first byte, the least significant bit (TDR:D0) is the data direction bit.
 - Transmission data empty flag (SSR:TDRE) will be cleared to "0" when the transmission data is written to the transmit data register (TDR).
 - The transmission data empty flag (SSR:TDRE) will be set to "1" when transferred to the transmit shift register.
 - Following transmission data should be written on the following conditions.
 - (1) Interrupt flag (IBCR:INT bit) is "1".
 - (2) No bus error detected (IBCR:BER bit=0).
 - (3) Acknowledge is ACK response ("0" is received as acknowledge).
 - If transmission FIFO is disabled and the transmission data empty flag (SSR:TDRE) is "0", the transmission data cannot be written to the transmit data register (TDR).
 - When using transmission FIFO, the transmission data can be written to the amount of transmission FIFO, even if the transmission data empty flag (SSR:TDRE) is "0".
-

Note:

The transmit data register is write-only register and the receive data register is read-only register. Because the two registers are located in the same address, the write value and read value might be different. Therefore instructions such as INC/DEC instructions which perform read-modify-write (RMW) operations cannot be used.

4.5.5. Baud rate Generator Register : BGR

The bit configuration of the baud rate generator register is shown below.

The baud rate generator register (BGR) sets the division ratio of a serial clock.

■ **BGR : Address 00B6_H, 00C6_H (Access: Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	BGR[14:8]						
Initial value	-	0	0	0	0	0	0	0
Attribute	RX,WX	R/W	R/W	R/W	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BGR[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit14 to bit0] BGR[14:0] (Baud rate Generator)

These bits set the reload value for the internal reload counter for baud rate generation.

When the reload value is written in this register, the reload counter begins counting.

Notes:

- Write to the baud rate generator (BGR) in 16-bit access mode.
- Configure the baud rate generator when the EN bit of the ISMK register is "0".
- Configure baud rate regardless of the master mode or slave mode.
- The peripheral clock (PCLK) should be set with 8MHz or more in operating mode 4 (I²C mode) and baud rate generator configured in 400kbps or more should not be used.

4.5.6. I²C 7-bit Slave Address Mask Register : ISMK

The bit configuration of the 7-bit slave address mask register is shown below.

The 7-bit slave address mask register (ISMK) compares and configures bits of slave address.

■ **ISMK : Address 00B8_H, 00C8_H (Access: Byte, Half-word, Word)**

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
EN	SM[6:0]						

Initial value	0	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

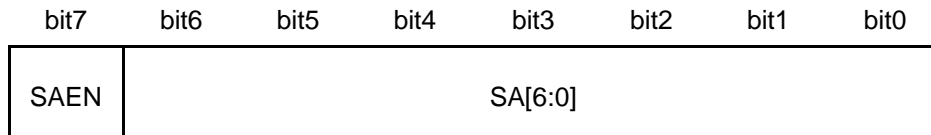
Bit name		Function
bit7	EN: I ² C Interface enable bit	<p>This bit enables/disables I²C interface operation. If this bit is set to "0", I²C interface becomes disabled. If this bit is set to "1", I²C interface becomes enabled.</p> <p>Notes:</p> <ul style="list-style-type: none"> · When the BER bit of the IBSR register is set to "1", this bit will not be cleared to "0". · Configure the baud rate generator when this bit is "0". · When this bit is "0", configure 7-bit slave address and 7-bit slave mask register. · If the I²C interface is disabled (EN=0), transmission/reception become disabled immediately. · When you disable the I²C interface operation after generating a stop condition by writing "0" to the IBCR:MSS bit, disable it (EN=0) after checking for the generation of the stop condition. · Setting "0" to the EN bit during transmission could generate SDA/SCL pulse on the I²C bus. <p>Note:</p> <ul style="list-style-type: none"> · For FIFO enable, write "0" to the EN bit after disabling FIFO.
bit6 to bit0	SM6 to SM0: Slave address mask bits	<p>This bit configures whether to exclude the 7-bit slave address and received address as the comparison targets. If these bits are set to "1": compare If these bits are set to "0": treat as matched</p> <p>Note:</p> <ul style="list-style-type: none"> · Configure this register when the EN bit is "0".

4.5.7. I²C 7-bit Slave Bus Address Register : ISBA

The bit configuration of the 7-bit slave bus address register is shown below.

The 7-bit slave address register (ISBA) sets slave addresses.

■ **ISBA : Address 00B9_H, 00C9_H (Access: Byte, Half-word, Word)**



Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Bit name		Function
bit7	SAEN: Slave address enable bit	This bit enables slave address detection. Setting "0" : Does not detect a slave address. Setting "1" : Compares the ISBA and ISMK values with the first byte received.
bit6 to bit0	SA6 to SA0: 7-bit slave address	<ul style="list-style-type: none"> · The 7-bit slave address register (ISBA), if the slave address detect is enabled (SAEN=1), compares the 7-bit data received after a (repeat) start condition detected with this register, and if all the bits are matched, it will operate as a slave and output ACK. At that time, the slave address received will be set to this register. (If SAEN=0, ACK will not be output.) · The address bits with "0" set on the ISMK register will be excluded from the comparison. Notes: <ul style="list-style-type: none"> · The reserved address cannot be set. · Set this register when the EN bit of the ISMK register is "0".

5. Operation of UART

The operation of UART is shown.

- 5.1. Interrupt of UART
- 5.2. Operation of UART
- 5.3. Setup Procedure and Program Flow

5.1. Interrupt of UART

Interrupt of UART is shown below.

There are interrupts for both transmission and reception in UART. You can generate an interrupt request for the following factors.

- Setting of reception data in the receive data register (RDR) or occurrence of a reception error
- Start of transmission after transfer of transmission data from the transmit data register (TDR) to the transmit shift register
- Transmission bus idle (no transmission operation)
- Transmission FIFO data request

5.1.1. List of Interrupt of UART

The list of interrupt of UART is shown below.

The following table indicates how UART interrupt control bits relate to interrupt factors.

Table 5-1 Interrupt Control Bits and the Interrupt Factors of UART

Interrupt type	Interrupt request flag bit	Flag register	Operation mode		Interrupt factor	Interrupt factor enable bit	Interrupt request flag clear
			0	1			
Reception	RDRF	SSR	○	○	1-byte reception	SCR:RIE	Reading of receive data (RDR)
					Reception of as much data as specified by FBYTE		Reading of receive data (RDR) until the reception FIFO is emptied
					Detection of reception idle for 8-bit time or more while there is valid data in the reception FIFO with the FRIIE bit set to "1".		
	ORE	SSR	○	○	Overrun error		Writing of "1" to the reception error flag clear bit (SSR:REC)
	FRE	SSR	○	○	Flaming error		
PE	SSR	○	×	Parity error			
Transmission	TDRE	SSR	○	○	Transmission register is empty	SCR:TIE	Writing to the transmit data (TDR) or writing of "1" to the transmission FIFO operation enable bit while the transmission FIFO operation enable bit is "0" and there is valid data in the transmission FIFO (retransmission)*
	TBI	SSR	○	○	No transmission operation	SCR:TBIE	Writing the transmit data (TDR) or writing of "1" to the transmission FIFO operation enable bit while the transmission FIFO operation enable bit is "0" and there is valid data in the transmission FIFO (retransmission)*
	FDRQ	FCR1	○	○	Transmission FIFO is empty	FCR1:FTIE	Writing of "0" to the FIFO transmission data request bit (FCR1:FDRQ) or the transmission FIFO is full

* : Set the TIE bit to "1" after the TDRE bit is cleared to "0".

5.1.2. Reception Interrupts and Flag Setting Timing

Reception interrupts and flag setting timing are shown below.

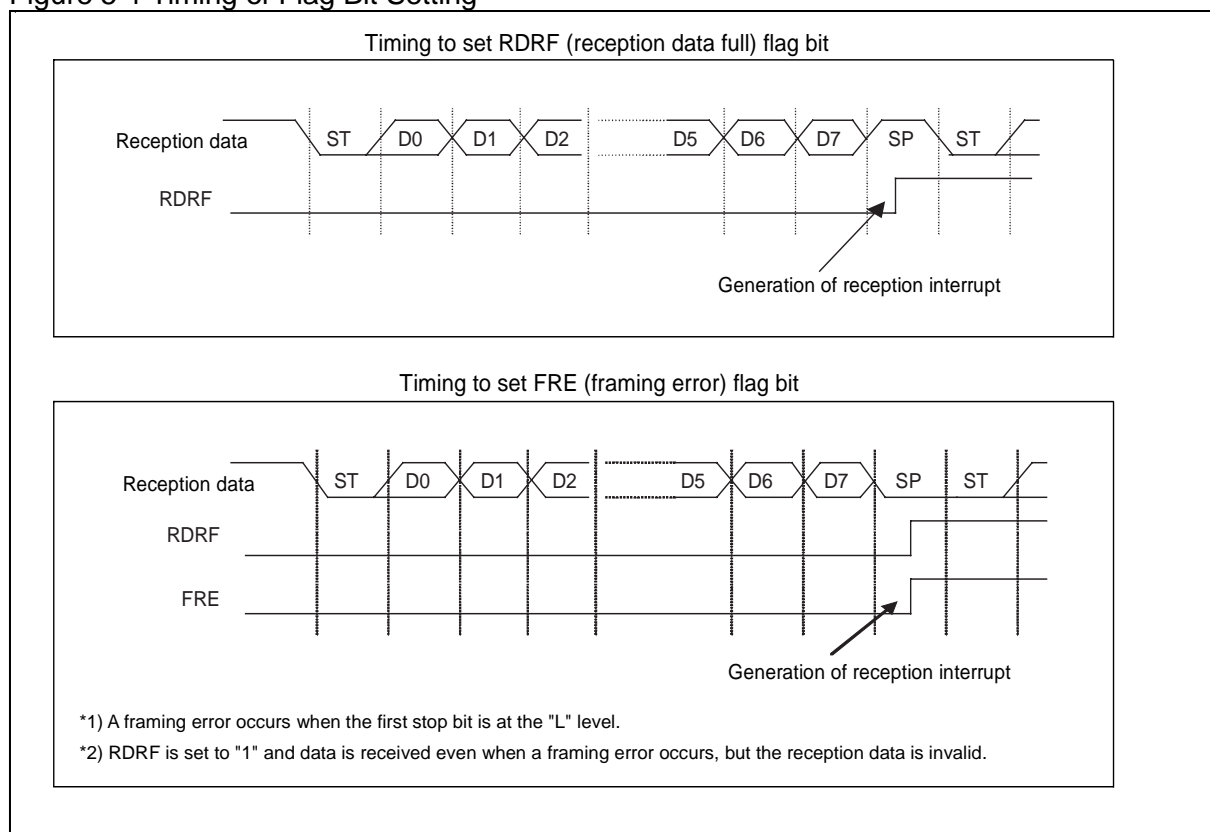
Reception interrupts occur either when the reception is completed (SSR:RDRF) or when a reception error occurs (SSR:PE, ORE, FRE).

When the first stop bit is detected, reception data is stored in the receive data register (RDR). When reception is completed (SSR:RDRF=1) or a reception error occurs (SSR:PE, ORE, FRE=1), a corresponding flag is set. If reception interrupts are enabled at this time (SCR:RIE=1), a reception interrupt occurs.

Note:

When a reception error occurs, the data in the receive data register (RDR) becomes invalid.

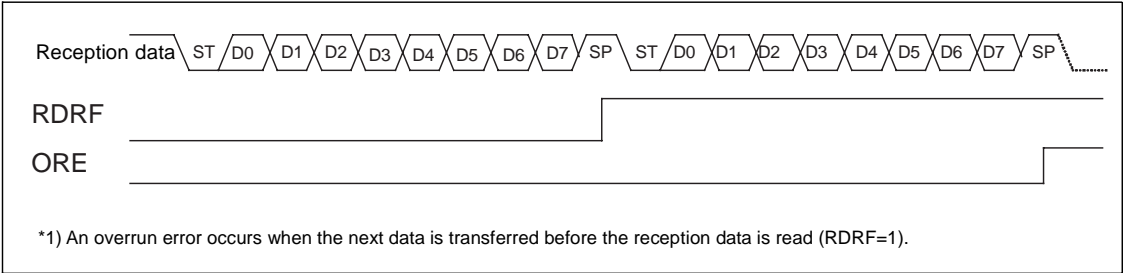
Figure 5-1 Timing of Flag Bit Setting



Note:

It becomes impossible to receive by invalidating the edge when the falling edge (ESCR:INV=0) or the rising edge (ESCR:INV=1) of the serial data is detected at the same clock or 1 or 2-machine clock earlier than the sampling point of the stop bit when it receives it. When the frame is continuously output, the interval of the frame is recommended to be opened.

Timing to set ORE (overrun error) flag bit



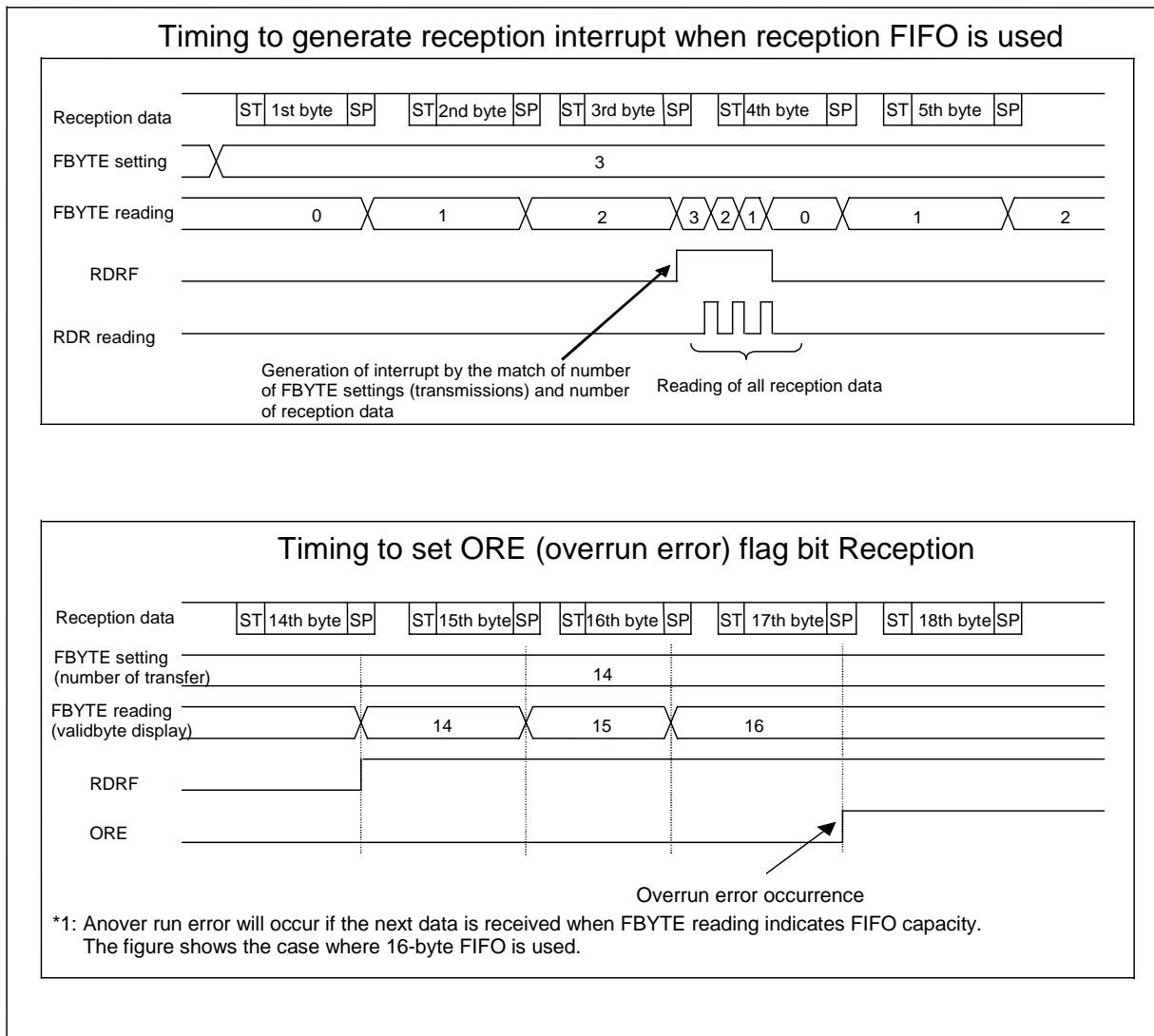
5.1.3. Interrupts when Using Reception FIFO and Flag Setting Timing

Interrupts when using reception FIFO and flag setting timing are shown below.

When the reception FIFO is used, an interrupt occurs after as much data as the FBYTE register (FBYTE) setting is received. The setting value of the FBYTE register determines the occurrence of an interrupt when the reception FIFO is used.

- After as much data as the transfer count setting of the FBYTE register is received, the reception data full flag of the serial status register (SSR:RDRF) is set to "1". If the reception interrupt is enabled (SCR:RIE) at this time, a reception interrupt is generated.
- If the data count contained in the reception FIFO does not reach the transfer count while reception FIFO idle detection enable bit (FCR1:FRIIE) is set to "1", the interrupt flag (SSR:RDRF) will be set to "1" after the reception idle state continues for 8 baud rate clocks or longer. If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. If the reception FIFO is disabled, the counter is reset to 0. When the reception FIFO is enabled while there is data remaining in it, the counter starts counting again.
- If the receive data (RDR) is read until the reception FIFO is empty, the reception data full flag (SSR:RDRF) is cleared.
- When the reception-enabled data count indication has shown the FIFO capacity, receiving the next data will generate an overrun error (SSR:ORE=1).

Figure 5-2 Timing of Using FIFO



5.1.4. Transmission Interrupts and Flag Setting Timing

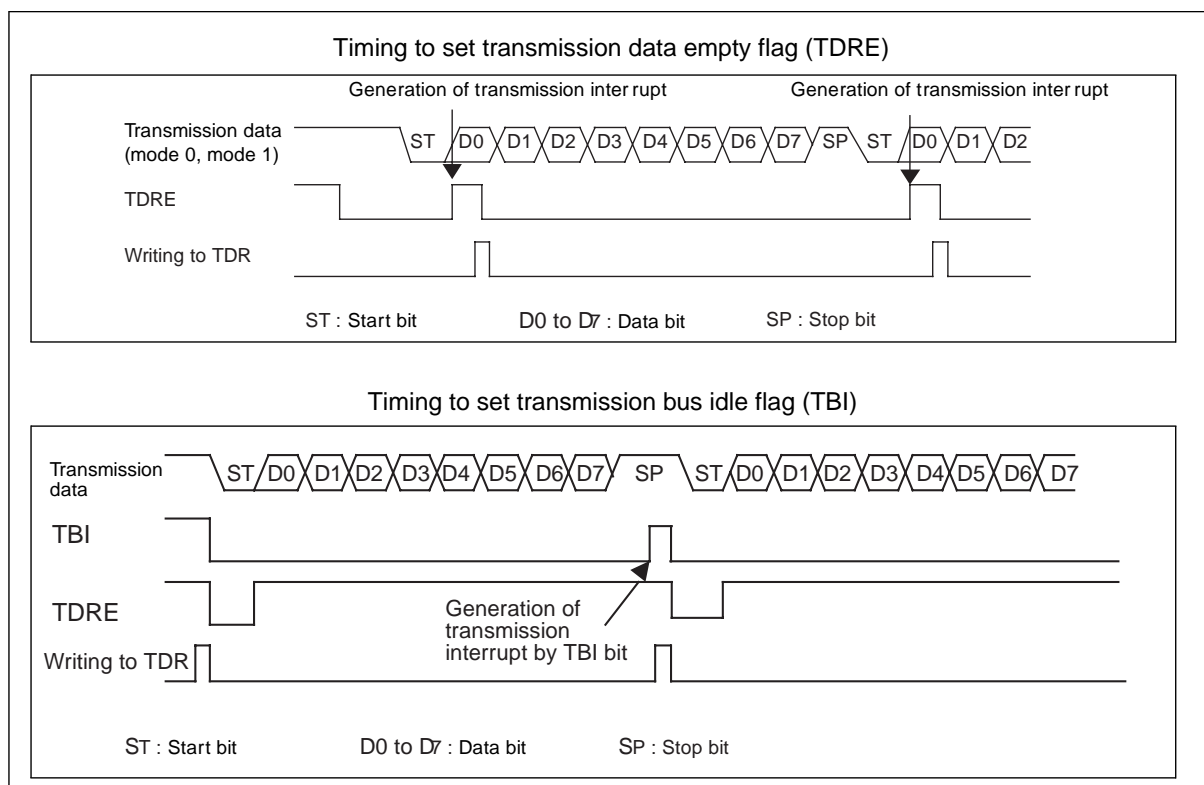
Transmission interrupts and flag setting timing are shown below.

Transmission interrupts occur either when transmission is started after transfer of transmission data from the transmit data register (TDR) to the transmit shift register (SSR:TDRE=1) or when the transmission operation is idle (SSR:TBI=1).

When data written to the transmit data register (TDR) is transferred to the transmit shift register, writing of next data is enabled (SSR:TDRE=1). If the transmission interrupt is enabled (SCR:TIE=1) at this time, a transmission interrupt occurs. The SSR:TDRE bit, being a read-only bit, is cleared to "0" by writing of data to the transmit data register (TDR).

When the transmit data register is empty (TDRE=1) and no transmission operation is in progress, the SSR:TBI bit is set to "1". If transmission bus idle interrupt is enabled (SCR:TBIE=1) at this time, a transmission interrupt will occur. When transmission data is written to the transmit data register (TDR), the SSR:TBI bit and the transmission interrupt request are cleared.

Figure 5-3 Timing of Transmission Interrupt Flag



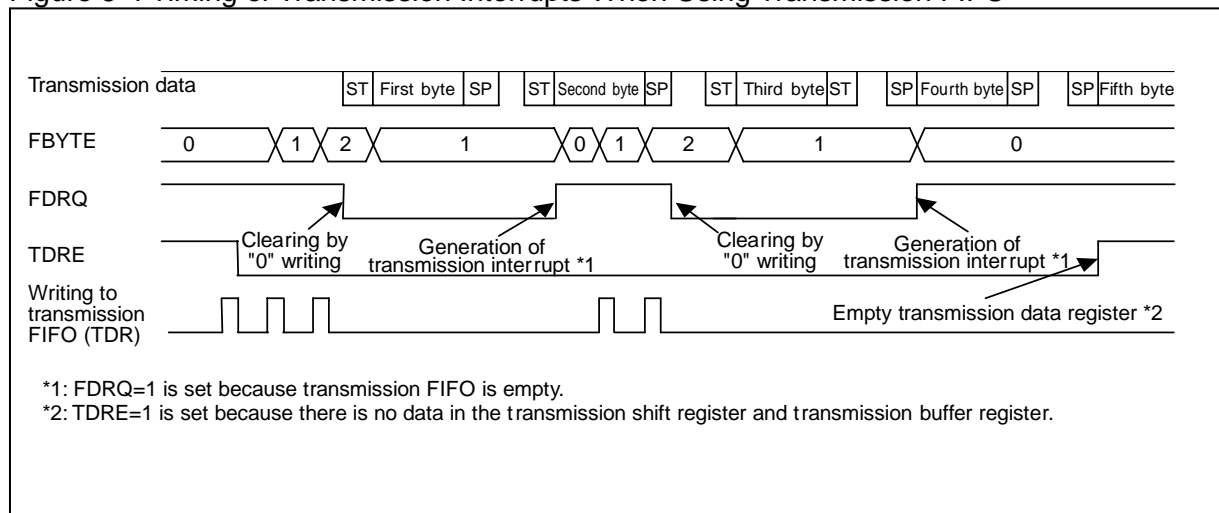
5.1.5. Interrupts When Using Transmission FIFO and Flag Setting Timing

Interrupts when using transmission FIFO and flag setting timing are shown below.

When the transmission FIFO is used, an interrupt occurs when there is no data in the transmission FIFO.

- When there is no data in the transmission FIFO, the FIFO transmission data request bit (FCR1:FDRQ) will be set to "1". If FIFO transmission interrupt is enabled (FCR1:FTIE=1) at this time, a transmission interrupt will occur.
- When required data is written to the transmission FIFO after the occurrence of a transmission interrupt, write "0" to the FIFO transmission data request bit (FCR1:FDRQ) to clear the interrupt request.
- When the transmission FIFO is full, the FIFO transmission data request bit (FCR1:FDRQ) is set to "0".
- The presence of data in the transmission FIFO can be checked by reading the FIFO byte register (FBYTE).
- When FBYTE=00_H, there is no data in the transmission FIFO.

Figure 5-4 Timing of Transmission Interrupts When Using Transmission FIFO



5.2. Operation of UART

The operation of UART is shown below.

UART operates with the mode 0 bidirectional serial asynchronous communication and the mode 1 master/slave multiprocessor communication.

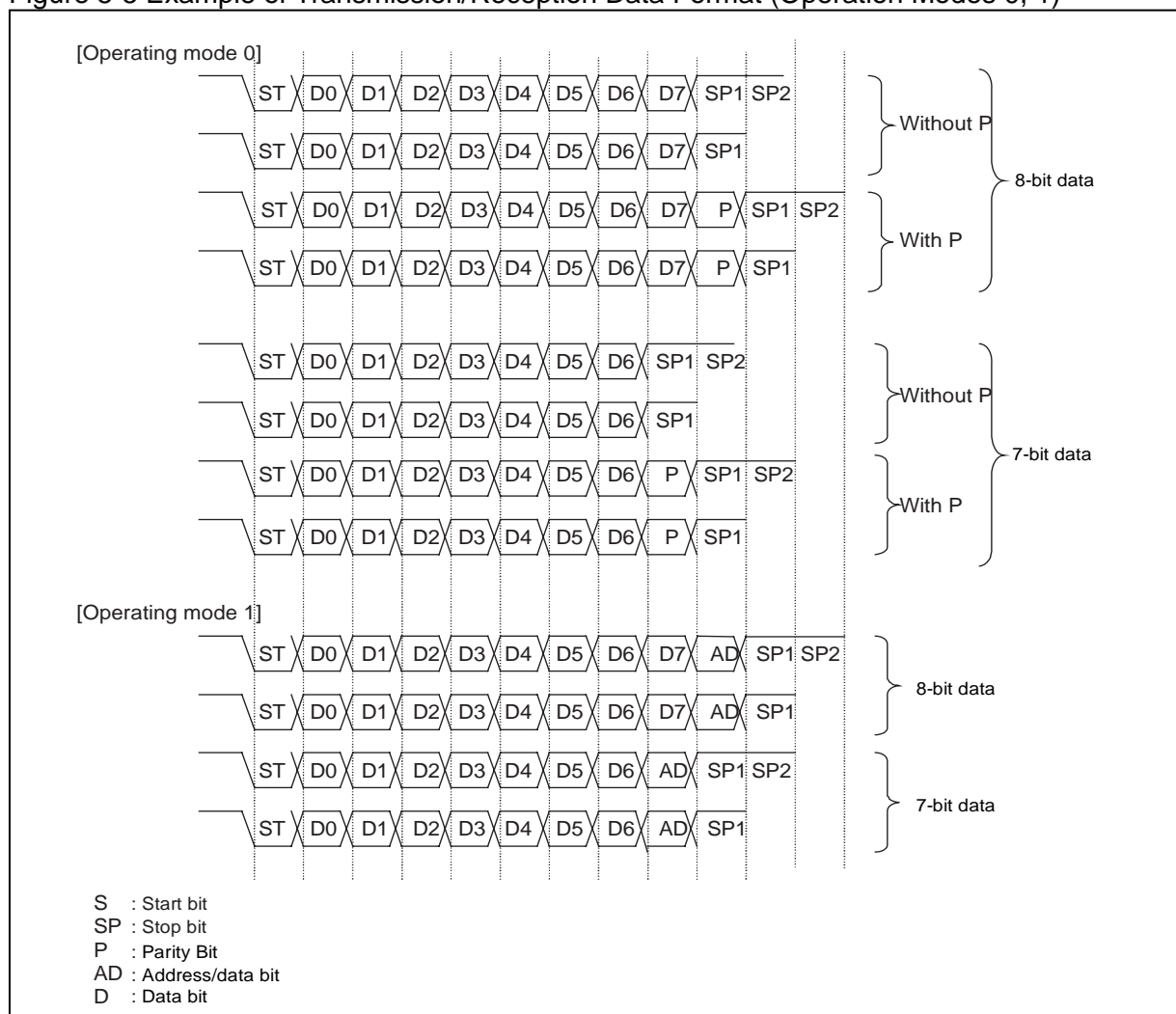
5.2.1. Transmission/Reception Data Format

Transmission/reception data format is shown below.

- The transmission/reception data always starts from the start bit and after the transmission/reception of data have taken place for the specified data bit length, ends at 1-bit or more length of stop bit.
- The direction of data transfer (LSB first or MSB first) is determined by the BDS bit of the serial mode register (SMR). If an operation with parity, the parity bit will always be placed between the last data bit and the first stop bit.
- In operation mode 0 (normal mode), you can select whether to use parity.
- In operation mode 1 (multiprocessor mode), the parity will not be added, instead AD bits will be added.

An example of transmission/reception data format (operation modes 0, 1) is shown below:

Figure 5-5 Example of Transmission/Reception Data Format (Operation Modes 0, 1)



Notes:

- The figure above shows the example of configurations with data length of 7 and 8 bits. (You can configure 5 to 9-bit data length in operation mode 0.)
 - When you set "1" to the BDS bit of the serial mode register (SMR) (MSB first), the bits will be processed in the order, D7, D6, D5, ..., D1, D0 (P).
 - When you configure x bit of data length, the lower x bits on transmit/receive data register (RDR/TDR) will be enabled.
-

5.2.2. Transmission Operation

The transmission operation is shown below.

- If the transmission data empty flag bit (TDRE) of the serial status register (SSR) is "1", the transmission data can be written to the transmit data register (TDR). (If the transmission FIFO is enabled, transmission data can be written even if TDRE=0.)
 - When transmission data is written to the transmit data register (TDR), the transmission data empty flag bit (TDRE) becomes "0".
 - When the transmission operation enable bit (SCR:TXE) of the serial control register is set to "1", the transmission data is loaded into the transmit shift register and the transmission starts from the start bit sequentially.
 - When the transmission starts the transmission data empty flag bit (SSR:TDRE) will be set to "1" again. If the transmission interrupt is enabled (SCR:TIE=1) at this time, a transmission interrupt occurs. Following transmission data can be written to the transmit data register when processing interrupts.
-

Notes:

- As soon as the transmission interrupt is enabled (SCR:TIE), a transmission interrupt occurs, because the transmission data empty flag bit (SSR:TDRE) has the initial value "1".
 - As soon as the FIFO transmission interrupt is enabled (FCR1:FTIE=1), a transmission interrupt will occur, because the FIFO transmission data request bit (FCR1:FDRQ) has the initial value "1".
-

5.2.3. Reception Operation

The reception operation is shown below.

- When reception operation is enabled (SCR:RXE=1), the reception operation will start.
- When a start bit is detected, one frame data will be received according to the data format set in the extended serial control register (ESCR:PEN, P, L2, L1, L0) and serial mode register (SMR:BDS). Detection of the start bit is as follows; falling edge (in case of ESCR:INV=0) or rising edge (in case of ESCR:INV=1) is detected after passing through the noise filter (which samples serial data input in 3 machine clock and decides the value by majority), and the data "L" is detected after the noise filter at the sampling point.
- When the reception of one frame data has completed, the reception data full flag bit (SSR:RDRF) will be set to "1". If reception interrupts are enabled (SCR:RIE=1) at this time, a reception interrupt occurs.
- When you read a reception data, do it after the one frame data reception has completed, and check for the state of error flag of the serial status register (SSR). When a reception error has detected, correct the error.
- After a read of reception data, the reception data full flag bit (SSR:RDRF) will be cleared to "0".
- When reception FIFO is enabled, if as many frames as set in the reception FBYTE have been received, the reception data full flag bit (SSR:RDRF) will be set to "1".
- If the data count contained in the reception FIFO does not reach the transfer count while reception FIFO idle detection enable bit (FRIIE) is set to "1", the interrupt flag (RDRF) will be set to "1" after the reception idle state continues for 8 baud rate clocks or longer. If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. If the reception FIFO is disabled, the counter is reset to 0. When the reception FIFO is enabled while there is data remaining in it, the counter starts counting again.
- When the reception FIFO is enabled, if the error flag of the serial status register is set to "1", the erroneous data will not be stored in the reception FIFO. Also, the reception data full flag bit (SSR:RDRF) at that time will not be set to "1". (However, when an overrun error does occur, the flag will be set to "1".) The reception FBYTE indicates the data count which have successfully received before the error occurs. Unless the error flag of the serial status register (SSR) is cleared to "0", the reception FIFO will not be enabled.
- When the reception FIFO is enabled, if the reception FIFO exhausted of data, the reception data full flag bit (SSR:RDRF) will be cleared to "0".

Notes:

- The data on the receive data register (RDR) will be enabled when the receive data register full flag bit (SSR:RDRF) is set to "1" and a reception error does not occur (SSR:PE, ORE, FRE=0).
 - When the noise passes the filter, the incorrect data is received though the noise filter (The serial data input is sampled three times with the machine clock and decision by majority) is built into. Design the board so that the noise should not pass this filter as the measures or communicate by noise passing so as not to become a problem (For instance, when the error occurs adding the checksum of data at the end, send it again).
 - It becomes impossible to receive by making the edge invalidity etc. when the falling edge (ESCR:INV =0) or the rising edge (ESCR:INV =1) of the serial data is detected at the same clock or 1 or 2-machine clock earlier than the sampling point of the stop bit when it receives it. When the frame is continuously output, the interval of the frame is recommended to be opened.
-

5.2.4. Clock Selection

The clock selection is shown below.

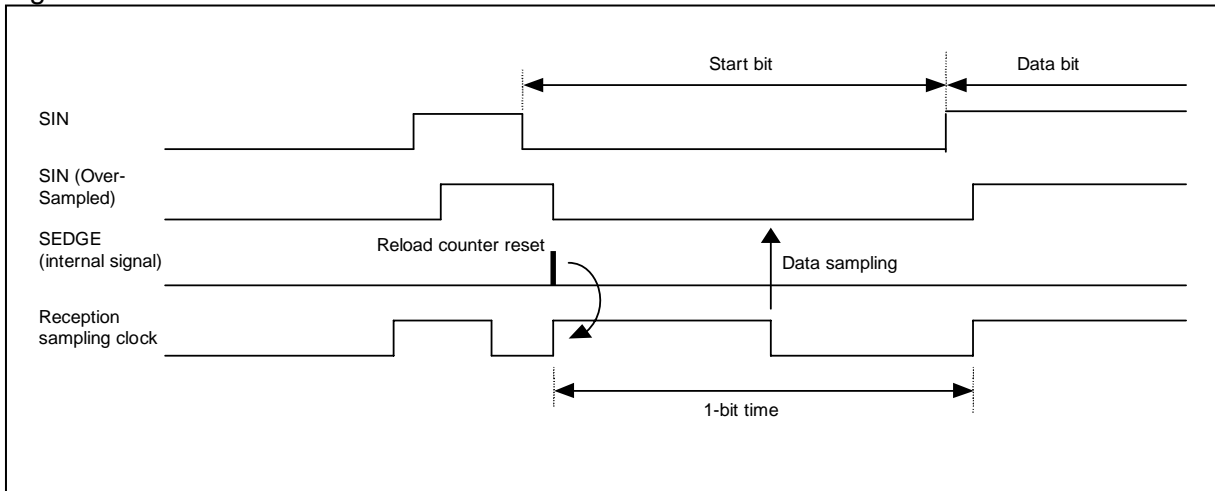
- Internal clocks or external clocks can be used.
- When you use an external clock, set BGR:EXT=1. In this case, the external clock is divided in the baud rate generator.

5.2.5. Start Bit Detection

The start bit detection is shown below.

- The start bit is recognized by the falling edge of the SIN signal in asynchronous mode. Therefore even if you enable reception operation (SCR:RXE=1), the reception operation will not start unless the falling edge of the SIN signal is entered.
- When the falling edge of the start bit is detected, the reception reload counter of the baud rate generator will be reset, a reload will take place again, and the count down will start. This will always launch a data sampling aimed at the center of the data.

Figure 5-6 Start Bit Detection



5.2.6. Stop Bit

The stop bit is shown below.

- You can select 1bit to 4bit length.
- The reception data full flag bit (SSR:RDRF) will be set to "1" when the first stop bit is detected.

5.2.7. Error Detection

The error detection is shown below.

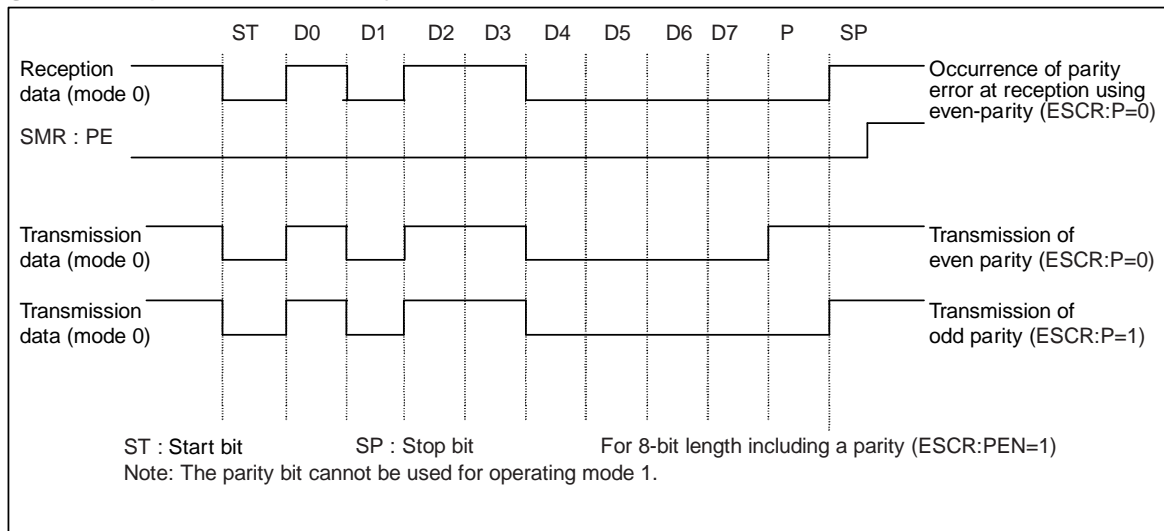
- In operation mode 0, parity errors, overrun errors, frame errors can be detected.
- In operation mode 1, overrun errors and frame errors can be detected. Parity errors cannot be detected.

5.2.8. Parity Bit

The parity bit is shown below.

- Parity bit can be added only in operating mode 0. The parity enable bit (ESCR:PE) can specify whether to enable or disable the parity, and the parity selection bit (ESCR:P) can specify whether to use even parity or odd parity.
- The parity can be used in operation mode 1.

Figure 5-7 Operation with Parity Enabled

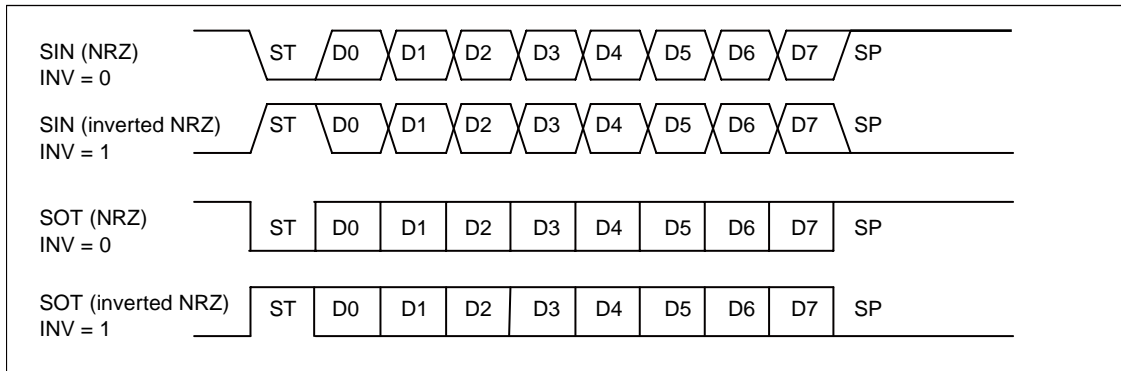


5.2.9. Data Signaling Method

The data signaling method is shown below.

- The INV bit setting of the extended serial control register enables you to select the NRZ (Non Return to Zero) signaling method (ESCR:INV=0) or the inverted NRZ signaling method (ESCR:INV=1).

Figure 5-8 NRZ (Non Return to Zero) Signaling Method and Inverted NRZ Signaling Method



5.2.10. Data Transfer Method

The data transfer method is shown below.

LSB first or MSB first can be selected on the data bit transfer method.

5.2.11. UART Baud Rate Selection/Setting

The UART baud rate selection/setting is shown below.

The UART transmission/reception baud rate generator can be configured for the settings below.

- Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the internal clock
There are two internal reload counters that correspond to the transmission and reception serial clocks, respectively. The baud rate can be selected by setting a 15-bit reload value in the baud rate generator register (BGR).

The reload counter divides the internal clock with the set value.

To configure the clock source, select the internal clock (BGR:EXT=0).

- Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the external clock
Use the external clock for the clock source of reload counter. The baud rate can be selected by setting a 15-bit reload value in the baud rate generator register (BGR). The reload counter divides the external clock with the set value. To configure the clock source, select the external clock and the baud rate generator clock (BGR:EXT=1).

This mode is designed to accommodate the case where the division of an oscillation of a special frequency is used.

Notes:

- Configure the external clock (EXT=1) after stopping the reload counter (BGR=15'h00).
 - When an external clock (EXT=1) has been set, the "H" width and "L" width of the external clock should be set to 2 peripheral clocks (PCLK) or more.
-

■ Baud Rate Calculation

Set two 15-bit reload counters in the baud rate generator register (BGR).

The baud rate calculation formulas are as follows:

(1) Reload value

$$V = \phi / b - 1$$

V: Reload value

b: Baud rate

ϕ : Internal clock (peripheral clock (PCLK)) or external clock frequency

(2) Example of calculation

Followings are the calculation of the reload value if the internal clock (peripheral clock (PCLK)) frequency is 16MHz and the baud rate is set to 19200 bps:

$$\begin{aligned} V &= (16 \times 1,000,000) / 19200 - 1 \\ &= 832 \end{aligned}$$

The baud rate when using this reload value is:

$$\begin{aligned} b &= (16 \times 1,000,000) / (832 + 1) \\ &= 19208 \text{ bps} \end{aligned}$$

(3) Baud rate error

The baud rate error can be obtained using the following formula:

$$\text{Error (\%)} = (\text{calculated value} - \text{desired value}) / \text{desired value} \times 100$$

(Example) Internal clock 20MHz, Target baud rate value 153600 bps

Reload value	= (20 × 1000000) / 153600 - 1	= 129
Baud rate (calculated value)	= (20 × 1000000) / (129 + 1)	= 153846 bps
Error (%)	= (153846 - 153600) / 153600 × 100	= 0.16(%)

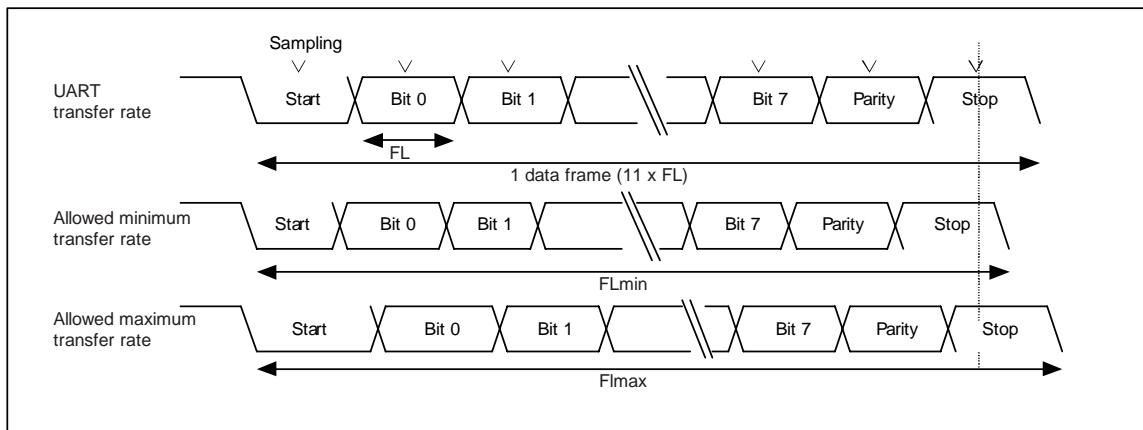
Notes:

- Set the reload value to "0" to stop the reload counter.
- If the reload value is an even number, the "L" width of the reception serial clock is 1 peripheral clock (PCLK) longer than "H" width. If it is an odd number, the "H" and "L" widths of the serial clock are equal.
- Set the reload value to 4 or higher. A normal data reception operation, however, could not be achieved for some baud rate error and reload value settings.

■ Allowed Baud Rate Error Range at Reception

This section explains the amount of the destination baud rate error that can be allowed at reception. The baud rate error at reception should be set within the allowed error range by using following formula.

Figure 5-9 Allowed Baud Rate Range at Reception



As shown in the figure, the counter set by the BGR register will determine the sampling timing of the reception data after having detected a start bit. A normal reception operation can be achieved if the last data (stop bit) have been completed on time at this sampling timing. In theory, the following is expected when this is applied to 11-bit reception.

If the margin of sampling timing is 1 clock of peripheral clock (PCLK) (ϕ), the allowed minimum transfer rate (FLmin) would be calculated as follows.

$$FLmin = (11\text{bit} \times (V+1) - (V+1) / 2 + 2) / \phi = (21V+25) / 2\phi \text{ (s)}$$

V : Reload value ϕ : Internal clock (peripheral clock(PCLK))(Hz)

Therefore, the allowed maximum baud rate (BGmax) at the destination would be calculated as follows.

$$BG_{max} = 11/FL_{min} = 22\phi/(21V+25) \text{ (bps)}$$

V : Reload value ϕ : Internal clock (peripheral clock(PCLK))(Hz)

When the allowance and maximum transfer rate (FLmax) receives the data, sampling is done in the starting point of received data in the 11th bit. Therefore, the allowance and maximum transfer rate (FLmax) is as follows.

$$10/11 \times FL_{max} = (11\text{bit} \times (V+1) - (V+1)/2) / \phi$$

V : Reload value ϕ : Internal clock (peripheral clock(PCLK))(Hz)

$$FL_{max} = (21/20 \times 11 \times (V+1)) / \phi$$

When margin (ϕ) of the sampling timing is made two clocks, the allowance and maximum transfer rate (FLmax) is as follows:

$$FL_{max} = (21/20 \times 11 \times (V+1) - 2) / \phi = (231V+191)/20\phi \text{ (s)}$$

V : Reload value ϕ : Internal clock (peripheral clock(PCLK))(Hz)

Therefore, the allowed minimum baud rate (BGmin) at the destination would be calculated as follows.

$$BG_{min} = 11/FL_{max} = 220\phi/(231V+191) \text{ (bps)}$$

V : Reload value ϕ : Internal clock (peripheral clock(PCLK))(Hz)

The allowed baud rate errors at UART and the destination can be obtained from above minimum/maximum baud rate calculation formulas, the result of which are as follows.

Table 5-2 Allowed Baud Rate Error

Reload value	Allowed maximum baud rate error	Allowed minimum baud rate error
3	0%	0%
10	2.98%	-3.24%
50	4.37%	-4.44%
100	4.56%	-4.60%
200	4.66%	-4.68%
32767	4.76%	-4.76%

Note:

The accuracy of reception depends on the number of bits in a frame, internal clock (peripheral clock (PCLK)), and the reload value. The higher the internal clock and the division ratio are, the more accurate it will become.

■ Reload Values and Errors for Each Internal Clock (Peripheral Clock (PCLK)) and Baud Rate

Table 5-3 Reload Values and Errors for Each Internal Clock (Peripheral Clock (PCLK)) and Baud Rate

Baud rate (bps)	8 MHz		10 MHz		16 MHz		20 MHz		24 MHz		32MHz	
	Value	ERR	Value	ERR	Value	ERR	Value	ERR	Value	ERR	Value	ERR
4M	-	-	-	-	-	0	4	0	5	0	7	0
2.5M	-	-	-	0	-	-	-	-	-	-	-	-
2M	-	0	4	0	7	0	9	0	11	0	15	0
1M	7	0	9	0	15	0	19	0	23	0	31	0
500000	15	0	19	0	31	0	39	0	47	0	63	0
460800	-	-	-	-	-	-	-	-	51	-0.16	-	-
250000	31	0	39	0	63	0	79	0	95	0	127	0
230400	-	-	-	-	-	-	-	-	103	-0.16	-	-
153600	51	-0.16	64	-0.16	103	-0.16	129	-0.16	155	-0.16	207	-0.16
125000	63	0	79	0	127	0	159	0	191	0	255	0
115200	68	-0.64	86	0.22	138	0.08	173	0.22	207	-0.16	277	0.08
76800	103	-0.16	129	-0.16	207	-0.16	259	-0.16	311	-0.16	416	0.08
57600	138	0.08	173	0.22	277	0.08	346	-0.16	416	0.08	555	0.08
38400	207	-0.16	259	-0.16	416	0.08	520	0.03	624	0	832	-0.04
28800	277	0.08	346	<0.01	554	-0.01	693	-0.06	832	-0.03	1110	-0.01
19200	416	0.08	520	0.03	832	-0.03	1041	0.03	1249	0	1666	0.02
10417	767	<0.01	959	<0.01	1535	<0.01	1919	<0.01	2303	<0.01	3071	<0.01
9600	832	0.04	1041	0.03	1666	0.02	2083	0.03	2499	0	3332	-0.01
7200	1110	<0.01	1388	<0.01	2221	<0.01	2777	<0.01	3332	<0.01	4443	-0.01
4800	1666	0.02	2082	-0.02	3332	<0.01	4166	<0.01	4999	0	6666	<0.01
2400	3332	<0.01	4166	<0.01	6666	<0.01	8332	<0.01	9999	0	13332	<-0.01
1200	6666	<0.01	8334	0.02	13332	<0.01	16666	<0.01	19999	0	26666	<0.01
600	13332	<0.01	16666	<0.01	26666	<0.01	-	-	-	-	-	-
300	26666	26666	<0.01	-	-	-	-	-	-	-	-	-

- Value: Setting value of the BGR register (decimal)
- ERR :Baud rate error(%)

■ External Clock

When the EXT bit of the baud rate generator register (BGR) is set to "1", the baud rate generator divides the external clock.

Note:

The external clock signals are synchronized with the internal clock by UART. If the external clock cannot be synchronized, therefore, the operation becomes unstable.

Reload Counter Functions

Reload counters, including transmission and reception reload counters, serve as the dedicated baud rate generators. It consists of a 15-bit register for reload values and generates a transmission/reception clock from the external or internal clock.

Count Start

When a reload value is written to the baud rate generator register (BGR), the reload counter starts counting.

Restart

The reload counter restarts under one of the following conditions:

- Common to the transmission and reception reload counters
Set "1" to the programmable clear bit (SCR:UPCL bit)
- Reception reload counter
Detection of a start bit falling edge in asynchronous mode

5.3. Setup Procedure and Program Flow

The setup procedure and program flow are shown.

5.3.1. Operation Mode 0 (One-to-One Connection)

5.3.2. Operation Mode 1 (One-to-N Connection)

5.3.1. Operation Mode 0 (One-to-One Connection)

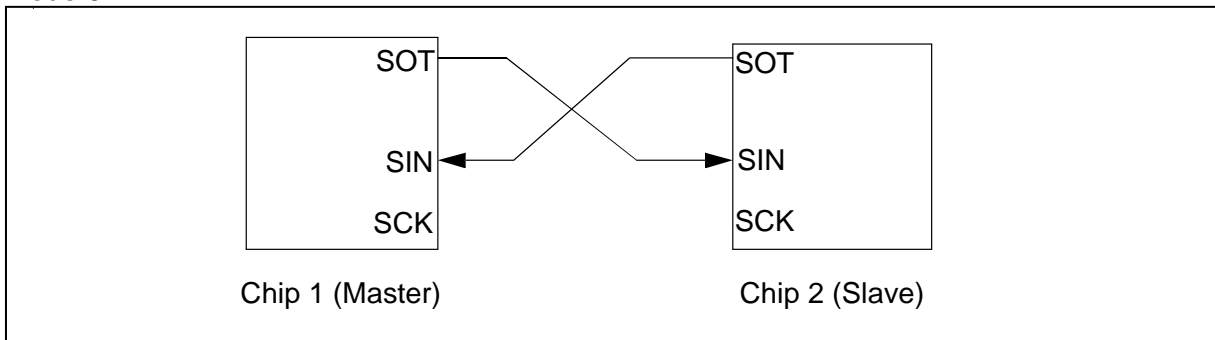
Operation mode 0 (One-to-One Connection) is shown below.

In operation mode 0, asynchronous serial bidirectional communications can be performed.

■ Connections between Chips

In operation mode 0 (normal mode), select bidirectional communications. Two CPUs are inter-connected as shown below:

Figure 5-10 Example of Connection for Bidirectional Communications in UART Operation Mode 0



■ Flowchart

Figure 5-11 Example of Settings for Bidirectional Communications (FIFO Not Used)

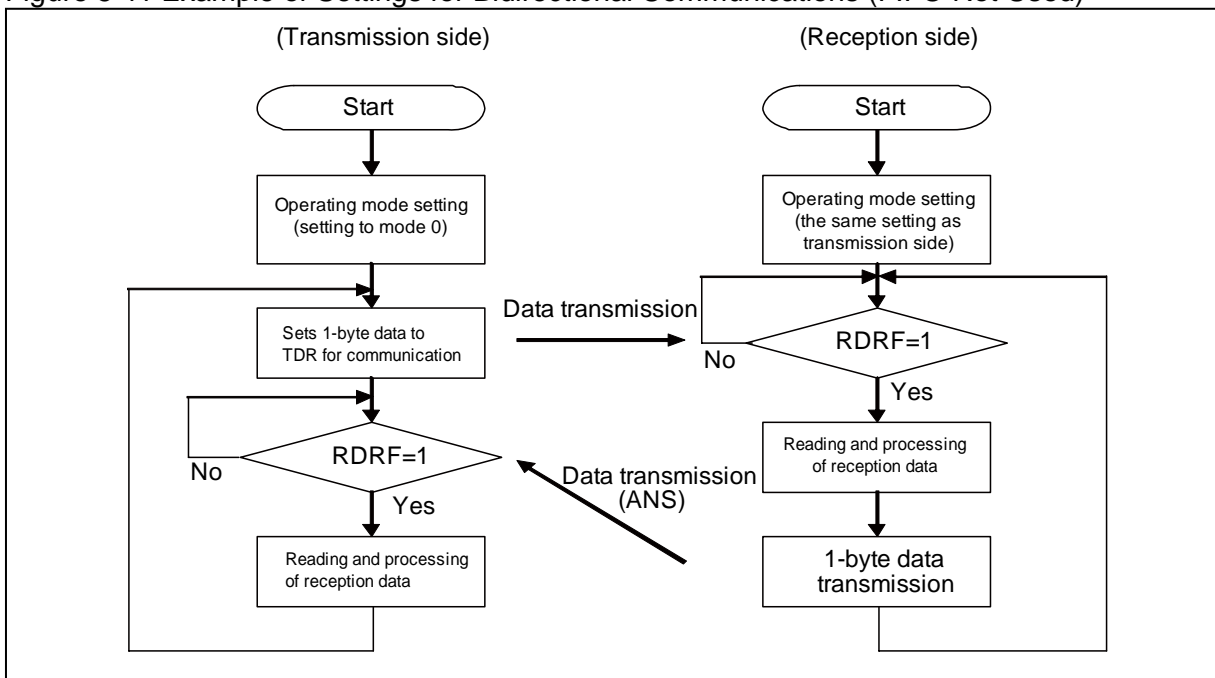
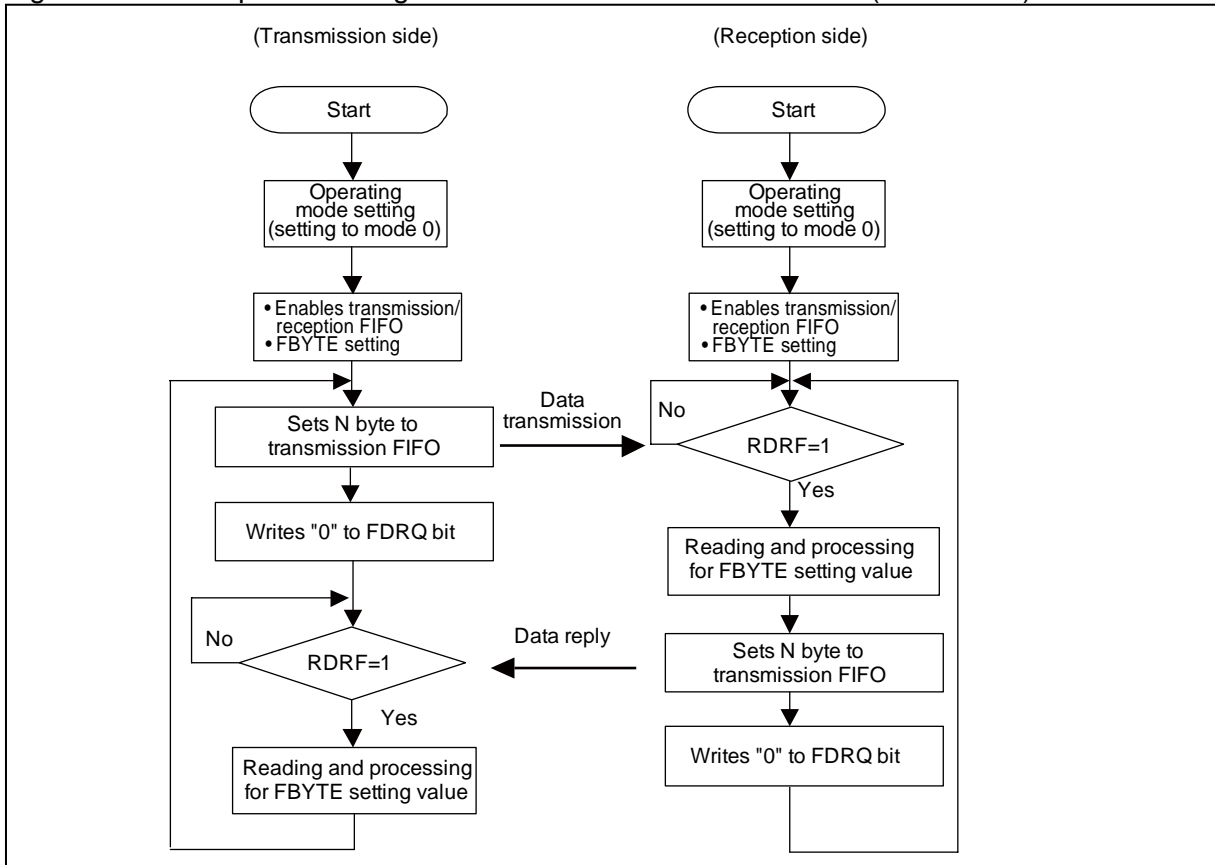


Figure 5-12 Example of Settings for Bidirectional Communications (FIFO Used)



5.3.2. Operation Mode 1 (One-to-N Connection)

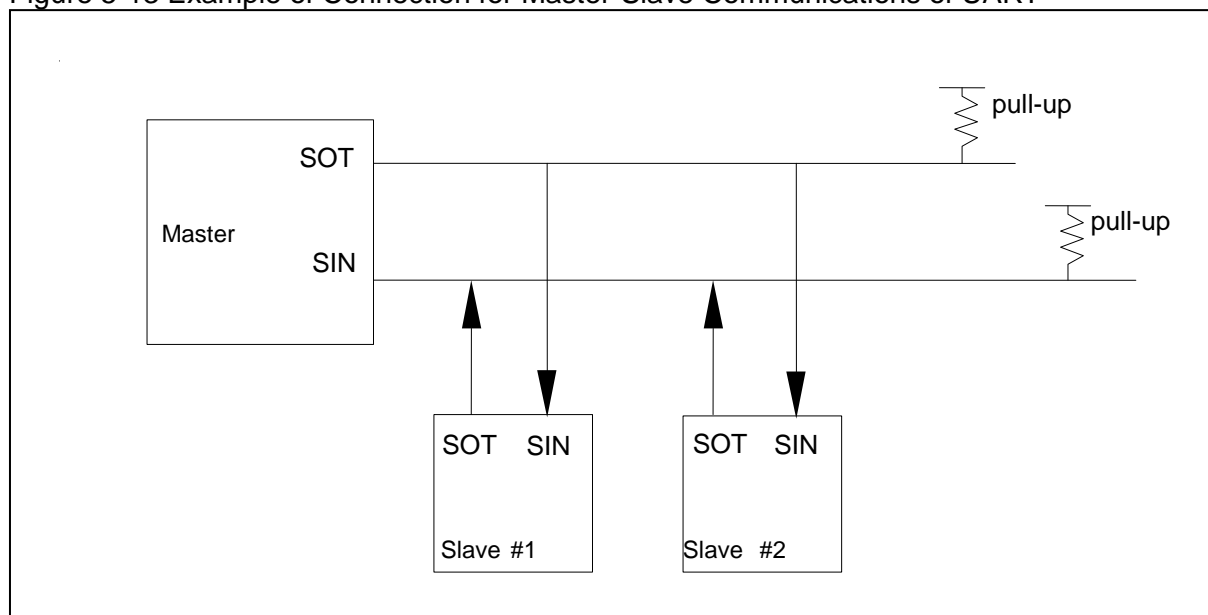
Operation mode 1 (One-to-N Connection) is shown below.

In operation mode 1 (multi-processor mode), communications can be performed via master-slave connection between multiple CPUs. UART can be used either as a master or slave.

■ Connections between Chips

For master-slave communications, a communication system can be configured as one master CPU and multiple slave CPUs connected to two common communication lines as shown in the figure below. UART can be used either as a master or slave.

Figure 5-13 Example of Connection for Master-Slave Communications of UART



■ Function Selection

For master-slave communications, select an operation mode and a data transfer method as follows:

Table 5-4 Selection of Master-Slave Communication Function

	Operation mode		Data	Parity	Stop bit	Bit direction
Address transmission and reception	Mode 1 (AD bit transmission)	Mode 1 (AD bit reception)	AD = 1 + 7 or 8-bit Address	None	1 bit or 2 bits	LSB or, MSB First
Data transmission and reception			AD = 0 + 7 or 8-bit Data			

Note:

Access the transmit and receive data (TDR/RDR) in word access in operation mode 1.

■ Communication Procedure

Communications start when the master CPU transmits address data. Address data refers to data with the D8 bit set to "1" and is used to select a slave CPU as the communication destination. Slave CPUs interpret address data via a program and the one with a matching address performs communications (normal data) with the master CPU. The following shows a flowchart of master-slave communications (multi-processor mode).

Figure 5-14 Example of Flowchart of Master-Slave Communications (FIFO Not Used)

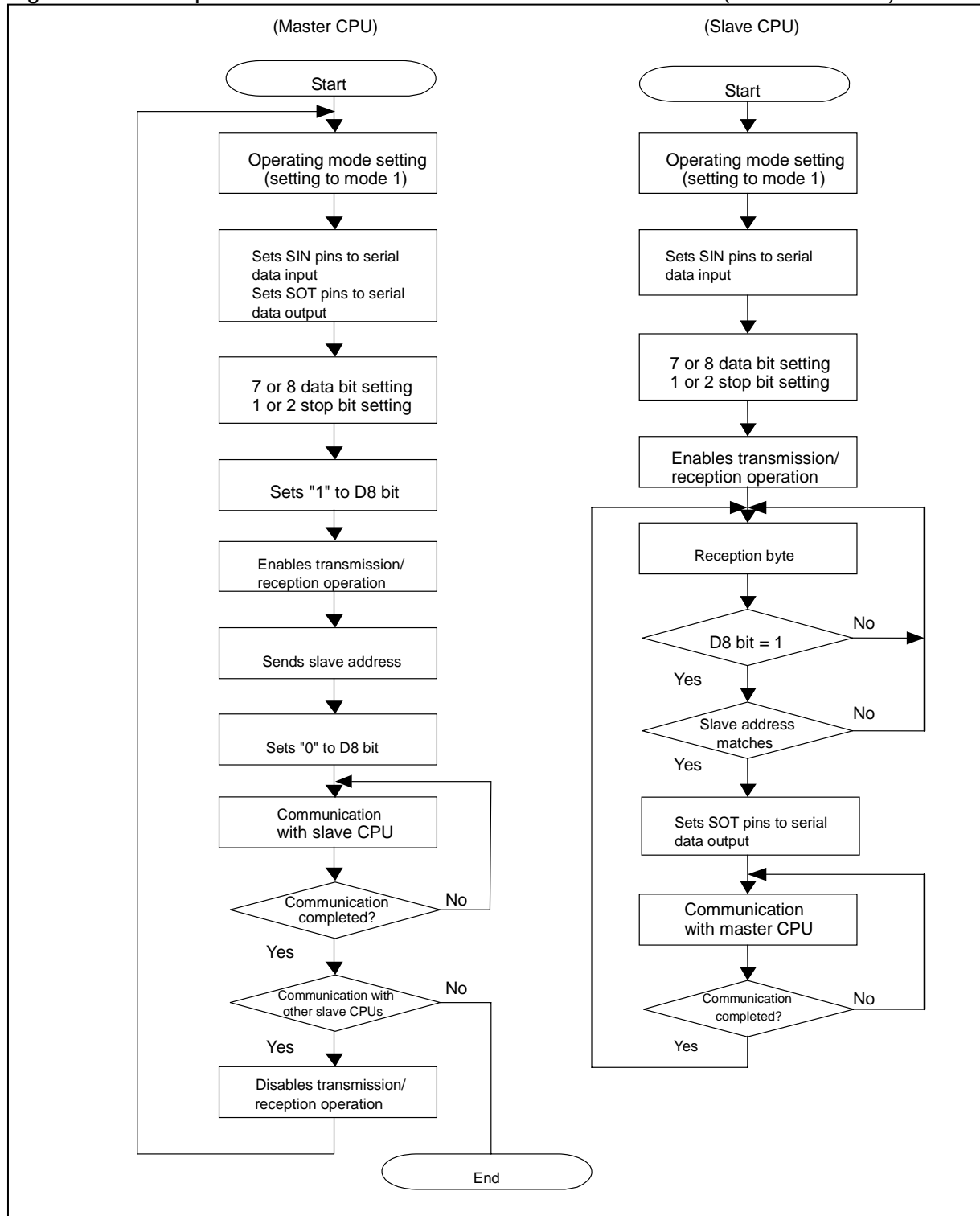
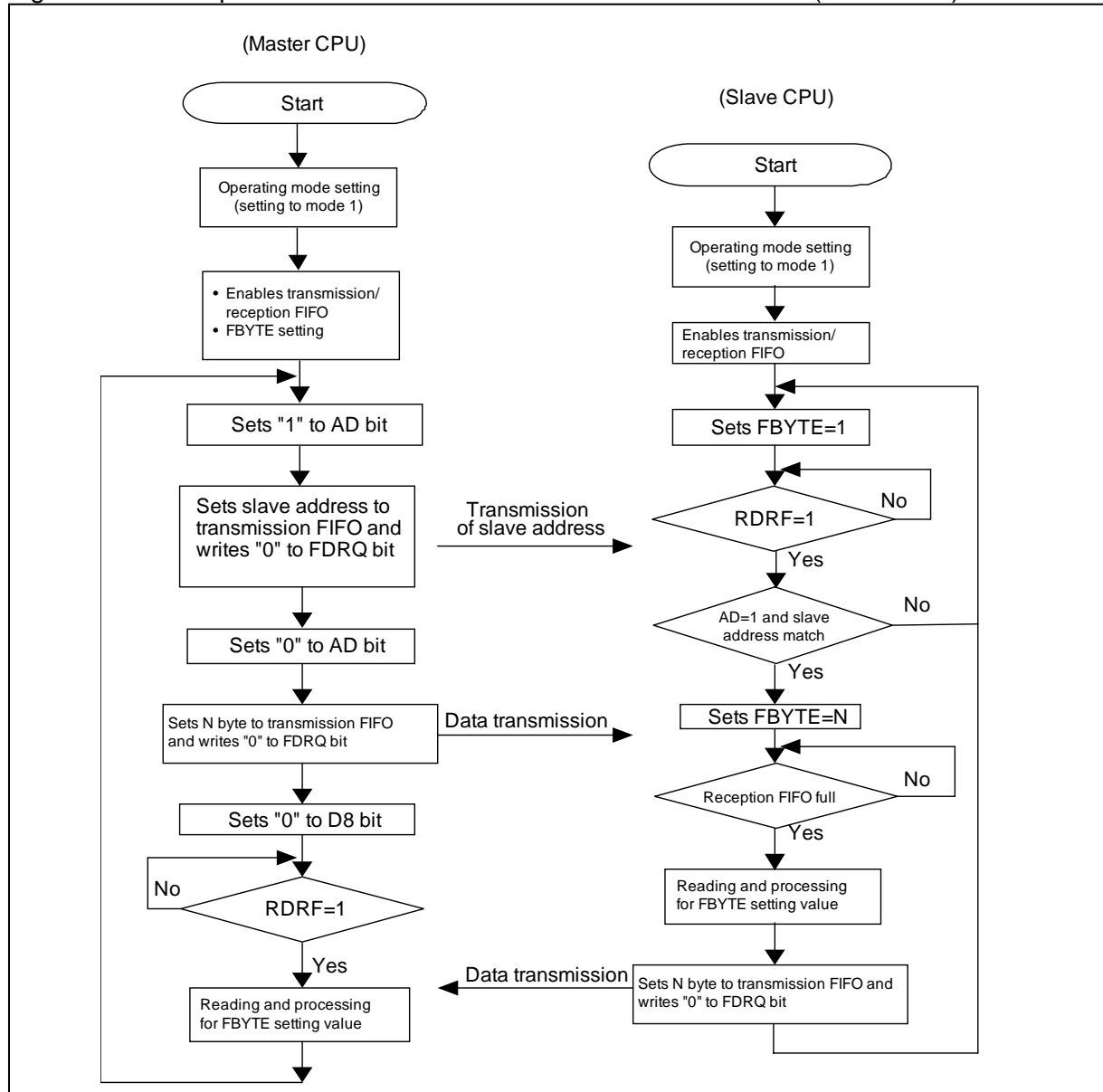


Figure 5-15 Example of Flowchart of Master-Slave Communications (FIFO Used)



6. Operation of CSIO

The operation of CSIO is shown.

- 6.1. Interrupts of CSIO
- 6.2. Operation of CSIO
- 6.3. Setup Procedure and Program Flow

6.1. Interrupts of CSIO

Interrupts of CSIO are shown below.

The interrupts for the CSIO (clock synchronous serial interface) include reception and transmission interrupts. An interrupt request can be generated using the following factors:

- Setting of reception data in the receive data register (RDR) or occurrence of a reception error
- Start of transmission after transfer of transmission data from the transmit data register (TDR) to the transmit shift register
- Transmission bus idle (no transmission operation)
- Transmission FIFO data request

6.1.1. List of Interrupts of CSIO

The list of Interrupts of CSIO is shown below.

Table 6-1 Interrupt Control Bits and Interrupt Factors of CSIO

Interrupt Type	Interrupt request flag bit	Flag register	Interrupt factor	Interrupt source enable bit	Clearing of interrupt request flag
Reception	RDRF	SSR	1-byte reception	SCR:RIE	Reading of receive data (RDR)
			Reception of as much data as specified by FBYTE		Reading of receive data (RDR) until the reception FIFO is emptied
			Detection of reception idle for 8-bit time or more while there is valid data in the reception FIFO with the FRIIE bit set to "1".		
ORE	SSR	Overrun error		Writing of "1" to the reception error flag clear bit (SSR:REC)	
Transmission	TDRE	SSR	Transmission register is empty	SCR:TIE	Writing of transmit data (TDR) or writing of "1" to the transmission FIFO operation enable bit while the transmission FIFO operation enable bit is "0" and there is valid data in the transmission FIFO (retransmission)*1
	TBI	SSR	No transmission operation	SCR:TBIE	Writing of transmit data (TDR) or writing of "1" to the transmission FIFO operation enable bit while the transmission FIFO operation enable bit is "0" and there is valid data in the transmission FIFO (retransmission)*1
	FDRQ	FCR1	Transmission FIFO is empty	FCR1:FTIE	Writing of "0" to the FIFO transmission data request bit (FCR1:FDRQ) or transmission FIFO is full

*1 : Set the TIE bit to "1" after the TDRE bit is cleared to "0".

6.1.2. Reception Interrupts and Flag Setting Timing

Reception interrupts and flag setting timing are shown below.

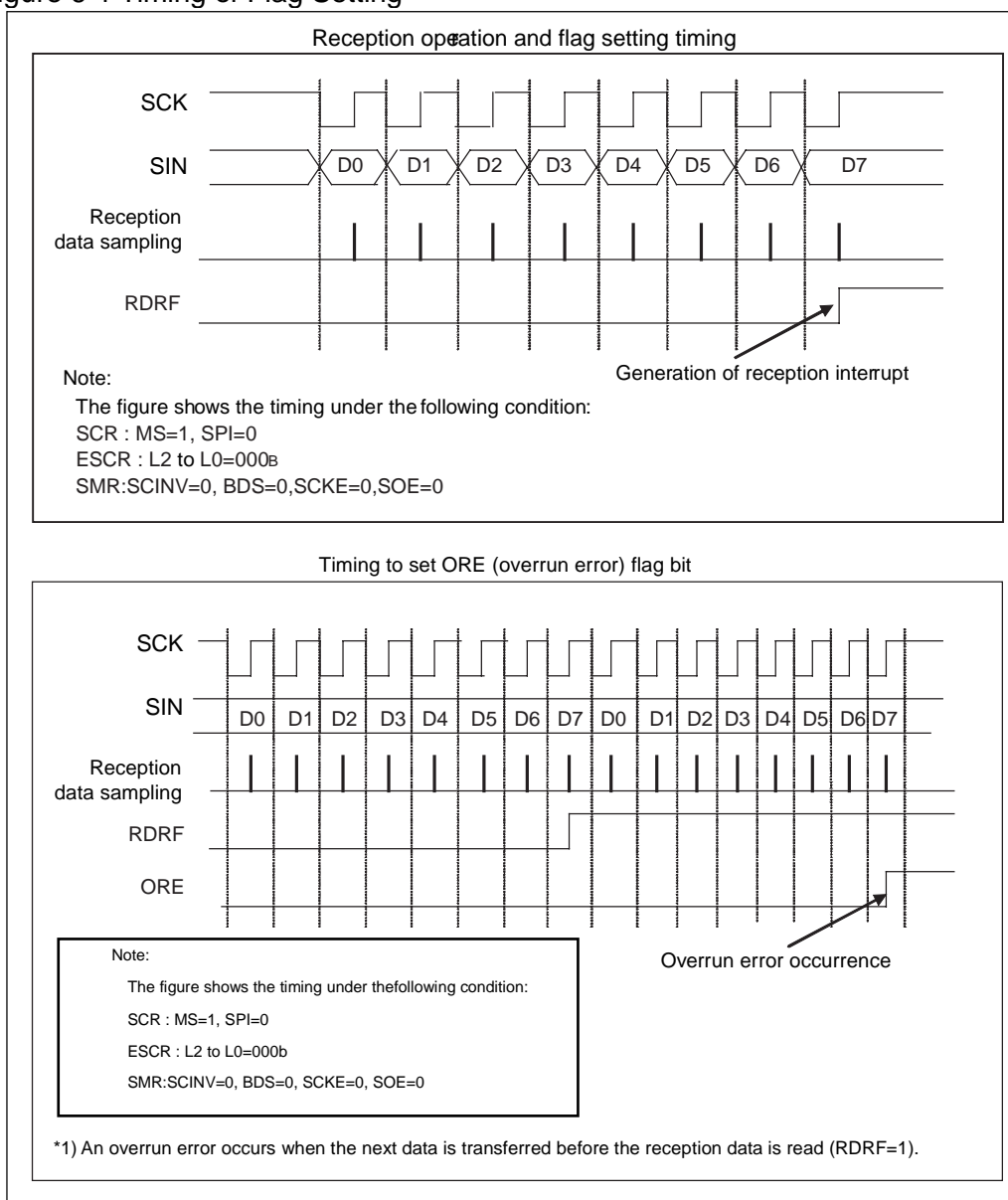
Reception interrupts occur either when the reception is completed (SSR:RDRF) or when a reception error occurs (SSR:ORE).

When the last data bit is detected, reception data is stored in the receive data register (RDR). When reception is completed (SSR:RDRF=1) or a reception error occurs (SSR:ORE=1), a corresponding flag is set. If reception interrupts are enabled at this time (SCR:RIE=1), a reception interrupt occurs.

Note:

When a reception error occurs, the data in the receive data register (RDR) becomes invalid.

Figure 6-1 Timing of Flag Setting



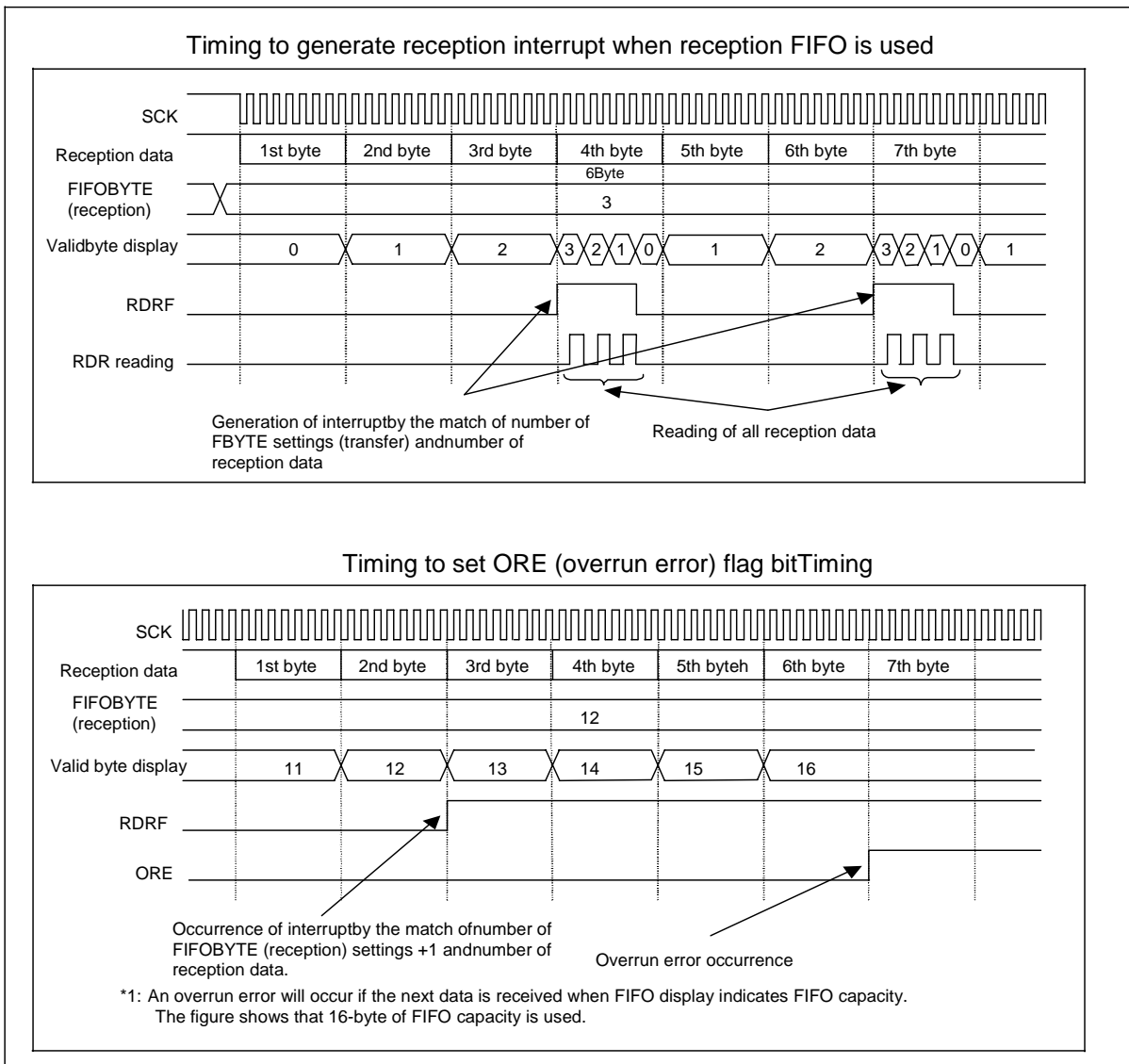
6.1.3. Interrupts when Using Reception FIFO and Flag Setting Timing

Interrupts when Using Reception FIFO and Flag Setting Timing are shown below.

When the reception FIFO is used, an interrupt occurs after as much data as the FBYTE register (FBYTE) setting is received. The setting value of the FBYTE register determines the occurrence of an interrupt when the reception FIFO is used.

- After as much data as the transfer count setting of the FBYTE register is received, the reception data full flag of the serial status register (SSR:RDRF) is set to "1". If the reception interrupt is enabled (SCR:RIE) at this time, a reception interrupt will be generated.
- If the data count contained in the reception FIFO does not reach the transfer count while reception FIFO idle detection enable bit (FRIIE) is set to "1", the interrupt flag (RDRF) will be set to "1" after the reception idle state continues for 8 baud rate clocks or longer. If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. If the reception FIFO is disabled, the counter is reset to 0. When the reception FIFO is enabled while there is data remaining in it, the counter starts counting again.
- If the receive data (RDR) is read until the reception FIFO is empty, the reception data full flag (SSR:RDRF) will be cleared.
- When the reception-enabled data count indication has shown the FIFO capacity, receiving the next data will generate an overrun error (SSR:ORE=1) .

Figure 6-2 Timing of Interrupts and Flag Setting



6.1.4. Transmission Interrupts and Flag Setting Timing

Transmission interrupts and flag setting timing are shown below.

Transmission interrupts occur either when transmission is started after transfer of transmission data from the transmit data register (TDR) to the transmit shift register (SSR:TDRE=1) or when the transmission operation is idle (SSR:TBI=1).

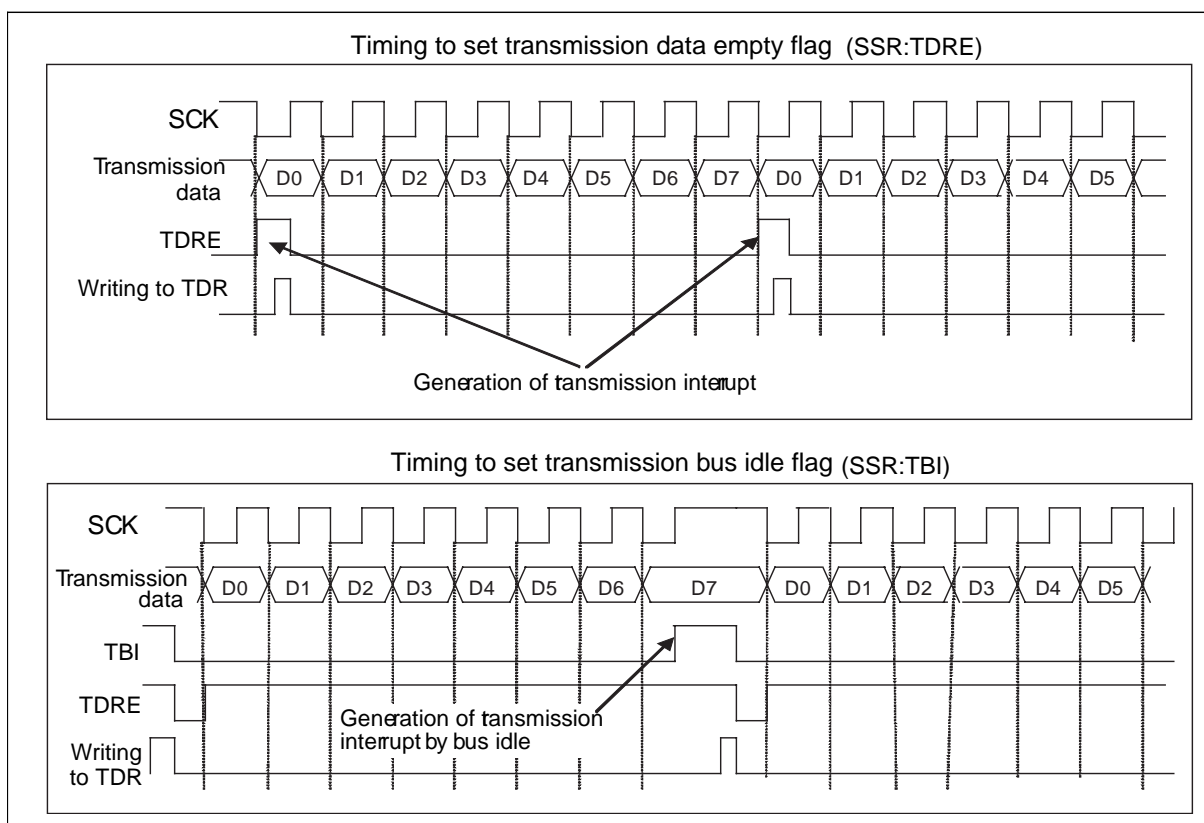
Timing of transmission data empty flag (SSR:TDRE) setting

When data written to the transmit data register (TDR) is transferred to the transmit shift register, writing of next data is enabled (SSR:TDRE=1). If the transmission interrupt is enabled (SCR:TIE=1) at this time, a transmission interrupt occurs. The SSR:TDRE bit, being a read-only bit, is cleared to "0" by writing of data to the transmit data register (TDR).

Timing of transmission bus idle flag (SSR:TBI) setting

When the transmit data register is empty (SSR:TDRE=1) and no transmission operation is in progress, the SSR:TBI bit is set to "1". If transmission bus idle interrupt is enabled (SCR:TBIE=1) at this time, a transmission interrupt occurs. When transmission data is written to the transmit data register (TDR), the SSR:TBI bit and the transmission interrupt request are cleared.

Figure 6-3 Timing of Flag Setting



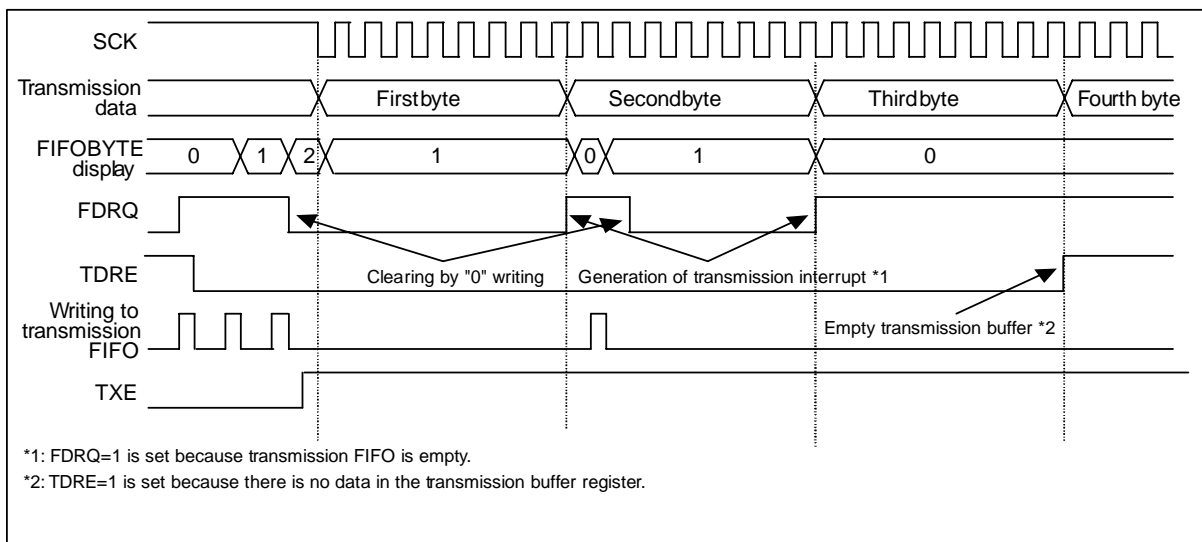
6.1.5. Interrupts When Using Transmission FIFO and Flag Setting Timing

Interrupts when using transmission FIFO and flag setting timing are shown below.

When the transmission FIFO is used, an interrupt occurs when there is no data in the transmission FIFO.

- When there is no data in the transmission FIFO, the FIFO transmission data request bit (FCR1:FDRQ) will be set to "1". If FIFO transmission interrupt is enabled (FCR1:FTIE=1) at this time, a transmission interrupt will occur.
- When required data is written to the transmission FIFO after the occurrence of a transmission interrupt, write "0" to the FIFO transmission data request bit (FCR1:FDRQ) to clear the interrupt request.
- When the transmission FIFO is full, the FIFO transmission data request bit (FCR1:FDRQ) is set to "0".
- The presence of data in the transmission FIFO can be checked by reading the FIFO byte register (FBYTE). When FBYTE=00_H, there is no data in the transmission FIFO.

Figure 6-4 Timing of Interrupt Generation



6.2. Operation of CSIO

The operation of CSIO is shown.

- 6.2.1. Normal Transfer (I)
- 6.2.2. Normal Transfer (II)
- 6.2.3. SPI Transfer (I)
- 6.2.4. SPI Transfer (II)
- 6.2.5. Baud Rate Generation

6.2.1. Normal Transfer (I)

Normal Transfer (I) is shown below.

■ Features

	Item	Description
1	Mark level of serial clock (SCK)	"H"
2	Transmission data output timing	SCK falling edge
3	Reception data sampling	SCK rising edge
4	Data length	5 to 9 bits

■ Register Settings

The following table lists the register settings required for normal transfer (I).

Table 6-2 Normal Transfer (I) Register Settings

	bit1 5	bit1 4	bit1 3	bit1 2	bit1 1	bit1 0	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR/SMR	UPC L	MS	SPI	RIE	TIE	TBI E	RXE	TXE	MD2	MD1	MD0	-	SCI NV	BDS	SCK E	SOE
	0	1/0	0	*	*	*	*	*	0	1	0	-	0	*	1/0	1/0
SSR/ESCR	REC	-	-	-	ORE	RDR F	TDR E	TBI	SOP	-	-	WT1	WT0	L2	L1	L0
	0	-	-	-	-	-	-	-	0	-	-	*	*	*	*	*
TDR/RDR								D8	D7	D6	D5	D4	D3	D2	D1	D0
								*	*	*	*	*	*	*	*	*
BGR	-	BGR[14:8]							BGR[7:0]							
	-	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*

1: Set to "1"

0: Set to "0"

*: User-configurable setting

Note:

The above bit settings (1 or 0) are different between the master and slave operations. Set the bits as follows:

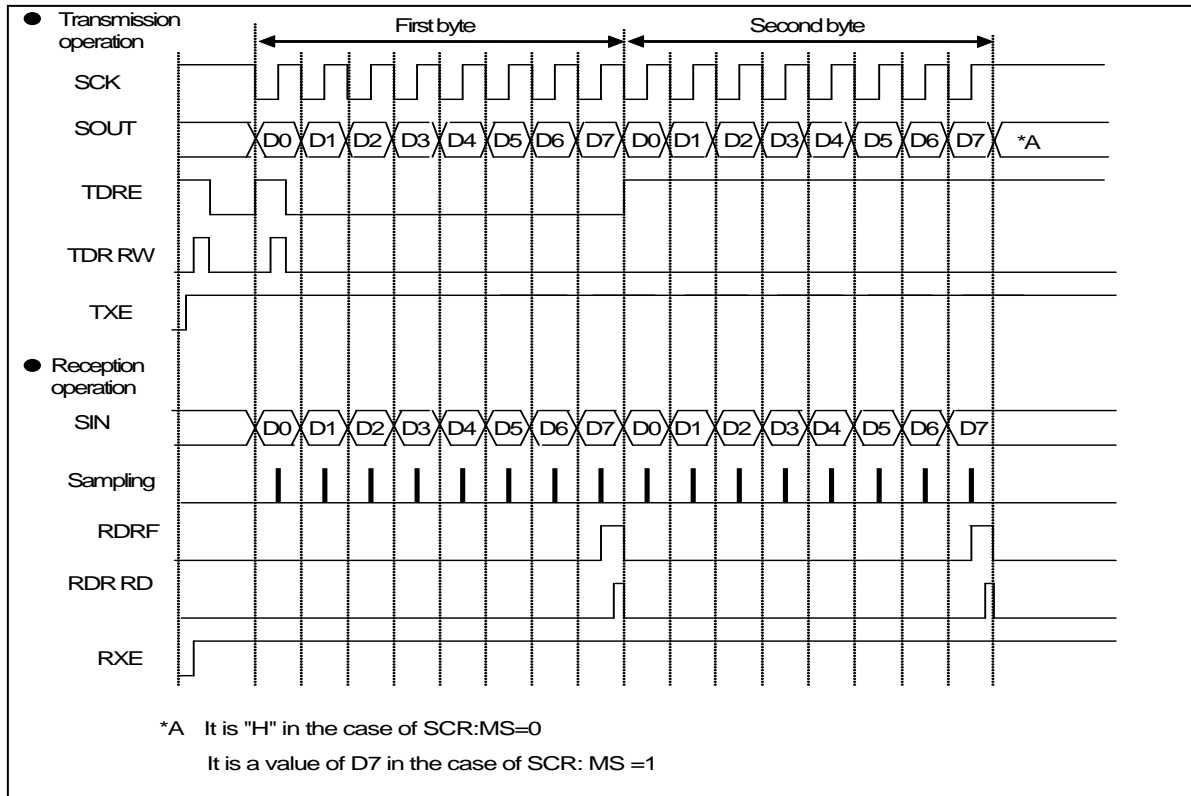
Master transmission : SCR:MS=0, SMR:SCKE=1, SOE=1

Master reception : SCR:MS=0, SMR:SCKE=1, SOE=0

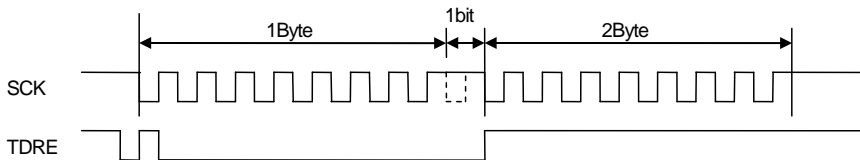
Slave transmission : SCR:MS=1, SMR:SCKE=0, SOE=1

Slave reception : SCR:MS=1, SMR:SCKE=0, SOE=0

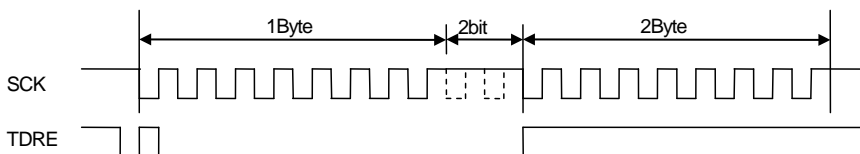
■ Normal Transfer (I) Timing Chart
Figure 6-5 Normal Transfer (I) Timing Chart



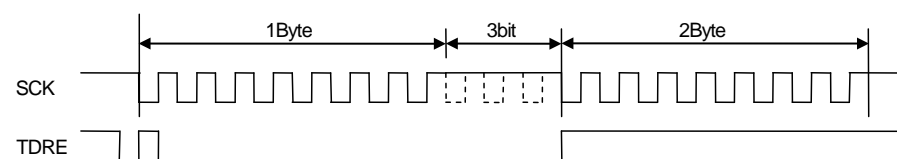
■ ESCR:WT1=0, ESCR:WT0=1 (for master)



■ ESCR:WT1=1, ESCR:WT0=0 (for master)



■ ESCR:WT1=1, ESCR:WT0=1 (for master)



■ Operation Explanation

[1] Master operation (Set SCR:MS=0, SMR:SCKE=1.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1), transmission operation enabled (SCR:TXE=1), and reception operation disabled (SCR:RXE=0), writing transmission data to TDR sets SSR:TDRE=0 and outputs the transmission data in synchronization with a falling edge of the serial clock (SCK) output.
 - (2) Outputting the transmission data in the first bit sets SSR:TDRE=1 and, if the transmission interrupt is enabled (SCR:TIE=1), outputs a transmission interrupt request. At this time, the transmission data in the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0), transmission operation enabled (SCR:TXE=1), and reception operation enabled (SCR:RXE=1), writing dummy data to TDR samples the reception data at a rising edge of the serial clock output (SCK).
 - (2) Receiving the last bit sets SSR:RDRF=1 and, if the reception interrupt is enabled (SCR:RIE=1), outputs a reception interrupt request. At this time, the receive data (RDR) can be read.
 - (3) Reading the receive data (RDR) clears SSR:RDRF to "0".

Notes:

- If only reception operation is to be performed, write dummy data to TDR to output the serial clock (SCK).
 - When transmission/reception FIFO is enabled, setting the FBYTE register to the number of frames to be transferred outputs as many frames of serial clock (SCK) as the setting.
-
- Transmission/ Reception operation
 - (1) When the transmission and reception operation is done at the same time, set serial data output enabled (SMR:SOE=1) and set reception operation enabled (SCR:TXE, RXE=1).
 - (2) If the transmission data is written in TDR, the SSR:TDRE is set as 0 also synchronization with the falling edge of serial clock (SCK) output and the transmission data is output. If the transmission data of the first bit outputted, the SSR:TDRE bit is set as 1 and when transmission interrupt enabled (SCR:TIE=1) is done, the transmission interrupt enabled is output. At this time, the transmission data of the second byte can be written.
 - (3) The reception data is sampled at the rising edge of serial clock (SCK) output. It changes to SSR:RDRF=1 if the last bit of the reception data is received, and when reception interrupt enabled (SCR:RIE=1) is done, the reception interrupt request is output. At this time, receive data (RDR) can be read. When the reception data is read, SSR:RDRF is cleared to "0".
 - Successive data transmission or reception wait operation
 - (1) If setting other than (ESCR:WT1, ESCR:WT0)= (0,0) is specified for successive data transmission or reception, a wait is inserted between frames.

[2] Slave operation (Set SCR:MS=1, SMR:SCKE=0.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1) and transmission operation enabled (SCR:TXE=1), writing transmission data to TDR sets SSR:TDRE=0 and outputs the transmission data in synchronization with a falling edge of the serial clock (SCK) input.
 - (2) Outputting the transmission data in the first bit sets SSR:TDRE=1 and, if the transmission interrupt is enabled (SCR:TIE=1), a transmission interrupt request is outputted. At this time, the transmission data in the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0) and reception operation enabled (SCR:RXE=1), the reception data is sampled at a rising edge of the serial clock input (SCK).

- (2) Receiving the last bit sets `SSR:RDRF=1` and, if the reception interrupt is enabled (`SCR:RIE=1`), a reception interrupt request is outputted. At this time, the receive data (RDR) can be read.
 - (3) Reading the receive data (RDR) clears `SSR:RDRF` to "0".
- Transmission/ Reception operation
 - (1) When the transmission and reception operation is done at the same time, set serial data output enabled (`SMR:SOE=1`) and set reception operation enabled (`SCR:TXE, RXE=1`).
 - (2) If the transmission data is written in TDR, the `SSR:TDRE` is set as 0 also synchronization with the falling edge of serial clock (SCK) input and the transmission data is output. If the transmission data of the first bit outputted, the `SSR:TDRE` bit is set as 1 and when transmission interrupt enabled (`SCR:TIE=1`) is done, the transmission interrupt enabled is output. At this time, the transmission data of the second byte can be written.
 - (3) The reception data is sampled by the rising edge of serial clock (SCK) input. It changes to `SSR:RDRF=1` if the last bit of the reception data is received, and when reception interrupt enabled (`SCR:RIE=1`) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, `SSR:RDRF` is cleared to "0".

6.2.2. Normal Transfer (II)

Normal Transfer (II) is shown below.

■ Features

	Item	Description
1	Mark level of serial clock (SCK)	"L"
2	Transmission data output timing	SCK rising edge
3	Reception data sampling	SCK falling edge
4	Data length	5 to 9 bits

■ Register Settings

The following table lists the register settings required for normal transfer (II).

Table 6-3 Normal Transfer (II) Register Settings

	bit1 5	bit1 4	bit1 3	bit1 2	bit1 1	bit1 0	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR/ SMR	UPC L	MS	SPI	RIE	TIE	TBIE	RXE	TXE	MD2	MD1	MD0	-	SCIN V	BDS	SCK E	SOE
	0	1/0	0	*	*	*	*	*	0	1	0	-	1	*	1/0	1/0
SSR/ ESCR	REC	-	-	-	ORE	RDR F	TDR E	TBI	SOP	-	-	WT1	WT0	L2	L1	L0
	0	-	-	-	-	-	-	-	0	-	-	*	*	*	*	*
TDR/ RDR								D8	D7	D6	D5	D4	D3	D2	D1	D0
								*	*	*	*	*	*	*	*	*
BGR	-	BGR[14:8]							BGR[7:0]							
	-	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*

1: Set to "1"

0: Set to "0"

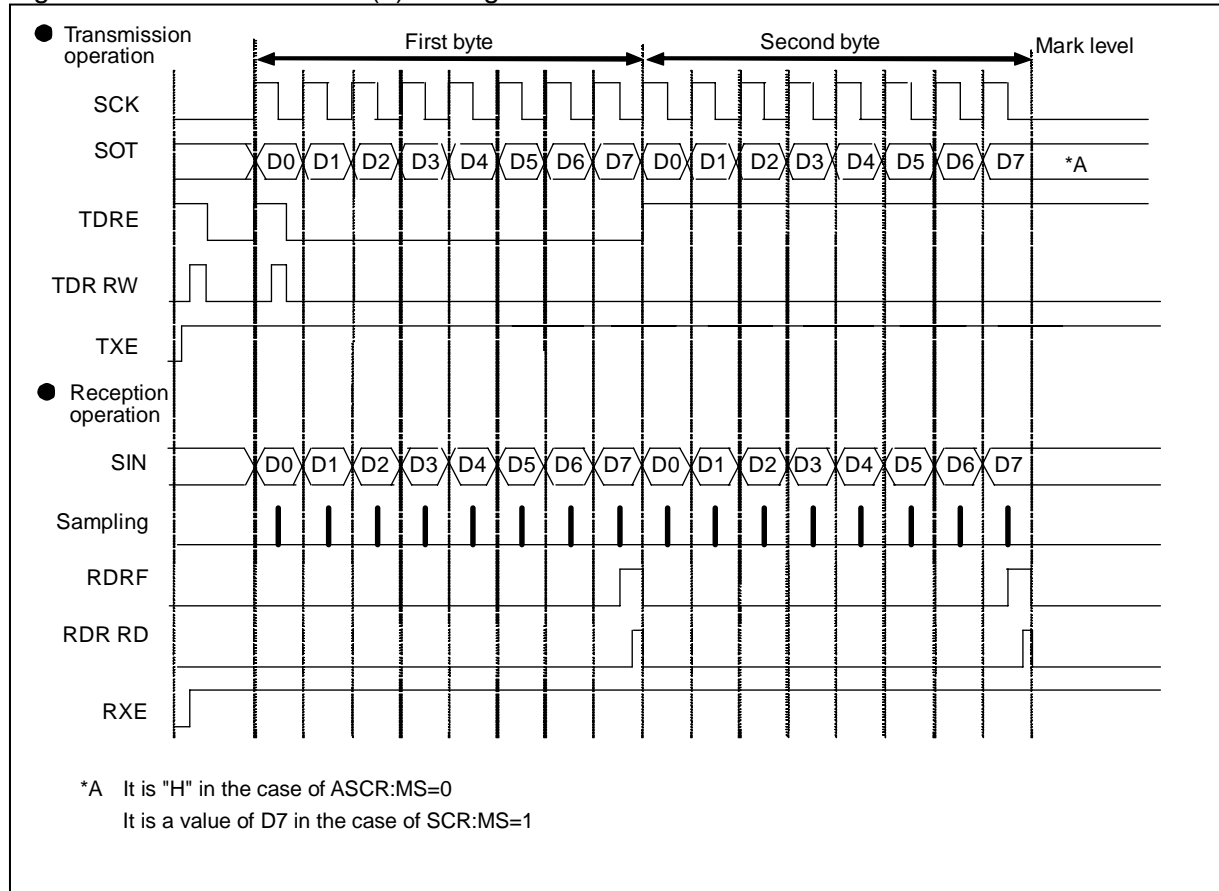
*: User-configurable setting

Note:

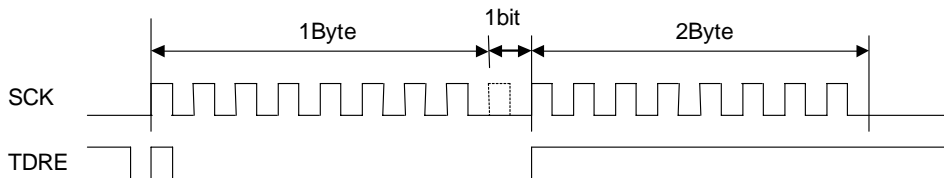
The above bit settings (1 or 0) are different between the master and slave operations. Set the bits as follows:

Master transmission : SCR:MS=0, SMR:SCKE=1, SOE=1
 Master reception : SCR:MS=0, SMR:SCKE=1, SOE=0
 Slave transmission : SCR:MS=1, SMR:SCKE=0, SOE=1
 Slave reception : SCR:MS=1, SMR:SCKE=0, SOE=0

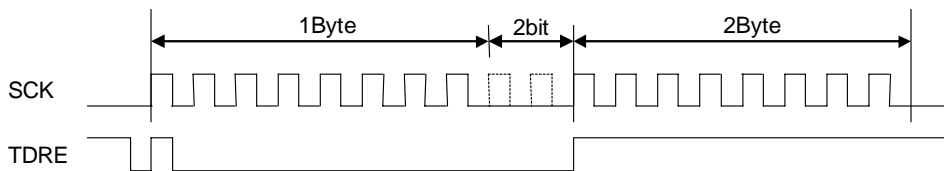
■ Normal Transfer (II) Timing Chart
Figure 6-6 Normal Transfer (II) Timing Chart



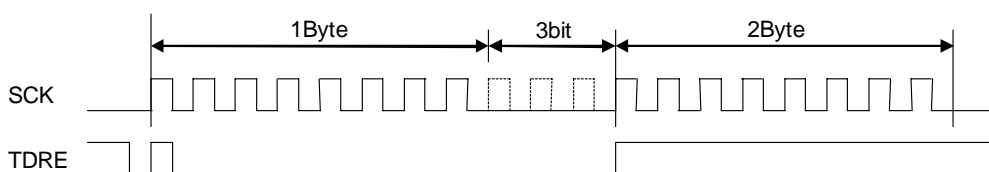
■ ESCR: WT1=0, ESCR: WT0=1 (for master)



■ ESCR: WT1=1, ESCR: WT0=0 (for master)



■ ESCR: WT1=1, ESCR: WT0=1 (for master)



■ Operation

[1] Master operation (Set SCR:MS=0, SMR:SCKE=1.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1), transmission operation enabled (SCR:TXE=1), and reception operation disabled (SCR:RXE=0), writing transmission data to TDR sets SSR:TDRE=0 and outputs the transmission data in synchronization with a rising edge of the serial clock (SCK) output.
 - (2) Outputting the transmission data in the first bit sets SSR:TDRE=1 and, if the transmission interrupt is enabled (SCR:TIE=1), a transmission interrupt request is outputted. At this time, the transmission data in the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0), transmission operation enabled (SCR:TXE=1), and reception operation enabled (SCR:RXE=1), writing dummy data to TDR samples the reception data at a falling edge of the serial clock output (SCK).
 - (2) Receiving the last bit sets SSR:RDRF=1 and, if the reception interrupt is enabled (SCR:RIE=1), a reception interrupt request is outputted. At this time, the receive data (RDR) can be read.
 - (3) Reading the receive data (RDR) clears SSR:RDRF to "0".

Notes:

- If only reception operation is to be performed, write dummy data to TDR to output the serial clock (SCK).
 - When transmission/reception FIFO is enabled, setting the FBYTE register to the number of frames to be transferred outputs as many frames of serial clock (SCK) as the setting.
-

- Transmission/ Reception operation
 - (1) When the transmission and reception operation is done at the same time, set serial data output enabled (SMR:SOE=1) and set reception operation enabled (SCR:TXE, RXE=1).
 - (2) If the transmission data is written in TDR, the SSR:TDRE is set as 0 also synchronization with the rising edge of serial clock (SCK) output and the transmission data is output. If the transmission data of the first bit outputted, the SSR:TDRE bit is set as 1 and when transmission interrupt enabled (SCR:TIE=1) is done, the transmission interrupt enabled is output. At this time, the transmission data of the second byte can be written.
 - (3) The reception data is sampled by the falling edge of serial clock (SCK) output. It changes to SSR:RDRF=1 if the last bit of the reception data is received, and when reception interrupt enabled (SCR:RIE=1) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, SSR:RDRF is cleared to "0".
- Successive data transmission or reception wait operation
 - (1) If setting other than (ESCR:WT1, WT0)= (0,0) is specified for successive data transmission or reception, a wait is inserted between frames.

[2] Slave operation (Set SCR:MS=1, SMR:SCKE=0.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1) and transmission operation enabled (SCR:TXE=1), writing transmission data to TDR sets SSR:TDRE=0 and outputs the transmission data in synchronization with a rising edge of the serial clock (SCK) input.
 - (2) Outputting the transmission data in the first bit sets SSR:TDRE=1 and, if the transmission interrupt is enabled (SCR:TIE=1), a transmission interrupt request is outputted. At this time, the transmission data in the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0) and reception operation enabled (SCR:RXE=1), the reception data is sampled at a falling edge of the serial clock input (SCK).

(2) Receiving the last bit sets $SSR:RDRF=1$ and, if the reception interrupt is enabled ($SCR:RIE=1$), a reception interrupt request is outputted. At this time, the receive data (RDR) can be read.

(3) Reading the receive data (RDR) clears $SSR:RDRF$ to "0".

· Transmission/ Reception operation

(1) When the transmission and reception operation is done at the same time, set serial data output enabled ($SMR:SOE=1$) and set reception operation enabled ($SCR:TXE, RXE=1$).

(2) If the transmission data is written in TDR, the $SSR:TDRE$ is set as 0 also synchronization with the rising edge of serial clock (SCK) input and the transmission data is output. If the transmission data of the first bit outputted, the $SSR:TDRE$ bit is set as 1 and when transmission interrupt enabled ($SCR:TIE=1$) is done, the transmission interrupt enabled is output. At this time, the transmission data of the second byte can be written.

(3) The reception data is sampled by the falling edge of serial clock (SCK) input. It changes to $SSR:RDRF=1$ if the last bit of the reception data is received, and when reception interrupt enabled ($SCR:RIE=1$) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, $SSR:RDRF$ is cleared to "0".

6.2.3. SPI Transfer (I)

SPI Transfer (I) is shown below.

■ Features

	Item	Description
1	Mark level of serial clock (SCK)	"H"
2	Transmission data output timing	SCK rising edge
3	Reception data sampling	SCK falling edge
4	Data length	5 to 9 bits

■ Register Settings

The following table lists the register settings required for SPI transfer (I).

Table 6-4 SPI Transfer (I) Register Settings

	bit1 5	bit1 4	bit1 3	bit1 2	bit1 1	bit1 0	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR/SMR	UPC L	MS	SPI	RIE	TIE	TBIE	RXE	TXE	MD2	MD1	MD0	-	SCI NV	BDS	SCK E	SOE
	0	1/0	1	*	*	*	*	*	0	1	0	-	0	*	1/0	1/0
SSR/ESCR	REC	-	-	-	ORE	RDR F	TDR E	TBI	SOP	-	-	WT1	WT0	L2	L1	L0
	0	-	-	-	-	-	-	-	0	-	-	*	*	*	*	*
TDR/RDR								D8	D7	D6	D5	D4	D3	D2	D1	D0
								*	*	*	*	*	*	*	*	*
BGR	-	BGR[14:8]							BGR[7:0]							
	-	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*

1: Set to "1"

0: Set to "0"

*: User-configurable setting

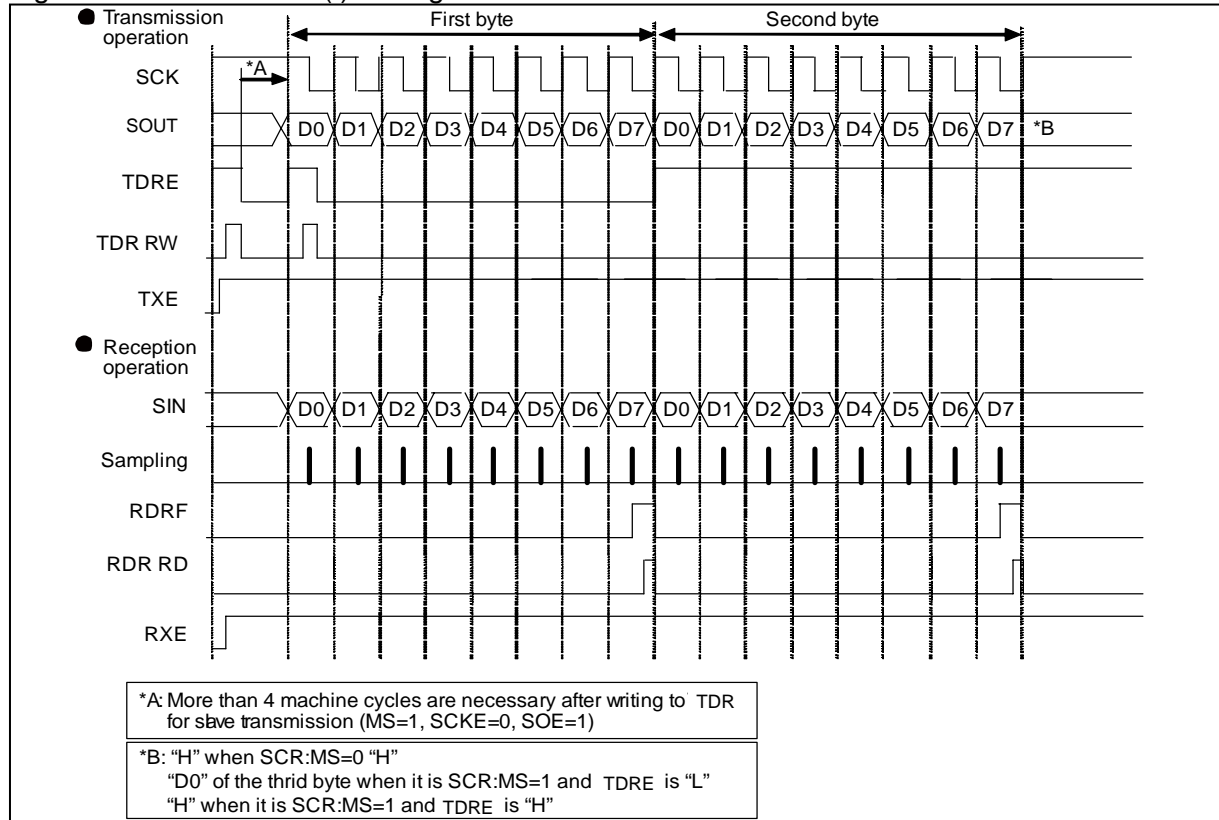
Note:

The above bit settings (1 or 0) are different between the master and slave operations. Set the bits as follows:

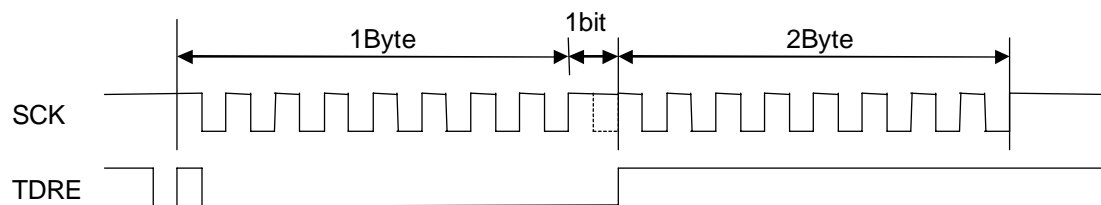
- Master transmission : SCR:MS=0, SMR:SCKE=1, SOE=1
- Master reception : SCR:MS=0, SMR:SCKE=1, SOE=0
- Slave transmission : SCR:MS=1, SMR:SCKE=0, SOE=1
- Slave reception : SCR:MS=1, SMR:SCKE=0, SOE=0

■ **SPI Transfer (I) Timing Chart**

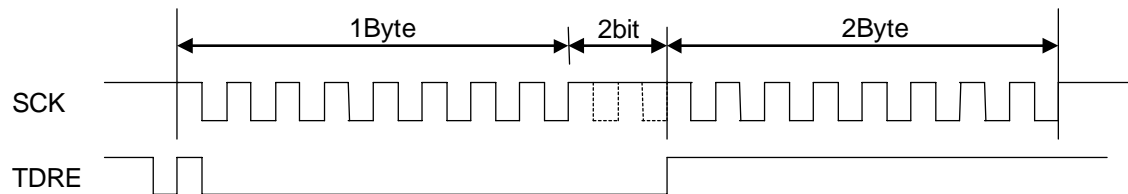
Figure 6-7 SPI Transfer (I) Timing Chart



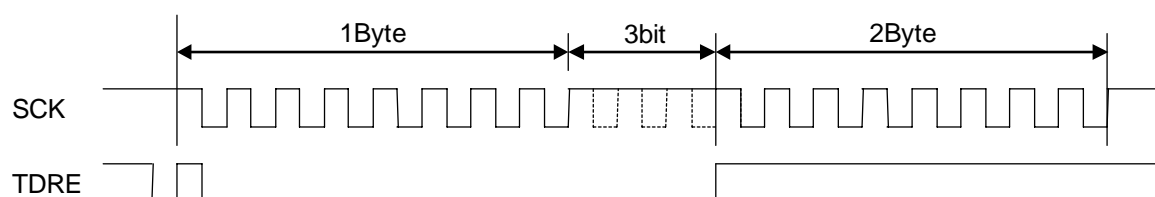
■ ESCR: WT1=0, ESCR: WT0=1 (for master)



■ ESCR: WT1=1, ESCR: WT0=0 (for master)



■ ESCR: WT1=1, ESCR: WT0=1 (for master)



■ Operation

[1] Master operation (Set SCR:MS=0, SMR:SCKE=1.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1), transmission operation enabled (SCR:TXE=1), and reception operation disabled (SCR:RXE=0), writing transmission data to TDR sets SSR:TDRE=0 and outputs the first bit. Then, the transmission data is output in synchronization with a rising edge of the serial clock (SCK) output.
 - (2) Half a cycle before a falling edge of the first serial clock, SSR:TDRE is set to 1 and, if the transmission interrupt is enabled (SCR:TIE=1), a transmission interrupt request is output. At this time, the transmission data in the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0), transmission operation enabled (SCR:TXE=1), and reception operation enabled (SCR:RXE=1), writing dummy data to TDR samples the reception data at a falling edge of the serial clock output (SCK).
 - (2) Receiving the last bit sets SSR:RDRF=1 and, if the reception interrupt is enabled (SCR:RIE=1), a reception interrupt request is outputted. At this time, the receive data (RDR) can be read.
 - (3) Reading the receive data (RDR) clears SSR:RDRF to "0".

Notes:

- If only reception operation is to be performed, write dummy data to TDR to output the serial clock (SCK).
 - When transmission/reception FIFO is enabled, setting the FBYTE register to the number of frames to be transferred outputs as many frames of serial clock (SCK) as the setting.
-
- Transmission/ Reception operation
 - (1) When the transmission and reception operation is done at the same time, set serial data output enabled (SMR:SOE=1) and set reception operation enabled (SCR:TXE, RXE=1).
 - (2) If the transmission data is written in TDR, the SSR:TDRE is set as 0 also the first bit is outputted. After synchronization with the rising edge of serial clock (SCK) output and the transmission data is output. The SSR:TDRE bit is set as 1 at before half cycle of the falling edge of first serial clock and transmission interrupt enabled is outputted when transmission interrupt enabled(SCR:TIE=1) is done. At this time, the transmission data of the second byte can be written.
 - (3)The reception data is sampled at the falling edge of serial clock (SCK) output. It changes to SSR:RDRF=1 if the last bit of the reception data is received, and when reception interrupt enabled (SCR:RIE=1) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, SSR:RDRF is cleared to "0".

- Successive data transmission or reception wait operation
 - (1) If setting other than (ESCR:WT1, WT0)= (0,0) is specified for successive data transmission or reception, a wait is inserted between frames.

[2] Slave operation (Set SCR:MS=1, SMR:SCKE=0.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1) and transmission operation enabled (SCR:TXE=1), writing transmission data to TDR sets SSR:TDRE=0 and outputs the first bit. Then, the transmission data is output in synchronization with a rising edge of the serial clock (SCK) output.
 - (2) It becomes SSR:TDRE=1 if the first bit of the transmission data is output, and when transmission interrupt enabled (SCR:TIE=1) is done, the transmission interrupt request is output. At this time, the transmission data of the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0) and reception operation enabled (SCR:RXE=1), the

reception data is sampled at a falling edge of the serial clock input (SCK).

- (2) Receiving the last bit sets SSR:RDRF=1 and, if the reception interrupt is enabled (SCR:RIE=1), a reception interrupt request is outputted.

At this time, the receive data (RDR) can be read.

- (3) Reading the receive data (RDR) clears SSR:RDRF to "0".

· Transmission/Reception operation

- (1) When the transmission and reception operation is done at the same time, set serial data output enabled (SMR:SOE=1) and set reception operation enabled (SCR:TXE, RXE=1).

(2) If the transmission data is written in TDR, the SSR:TDRE is set as 0 also the first bit is outputted. After synchronization with the rising edge of serial clock (SCK) input and the transmission data is output. The SSR:TDRE bit is set as 1 when the first byte of the transmission data is outputted and a transmission interrupt request is outputted when transmission interrupt enabled(SCR:TIE=1) is done. At this time, the transmission data of the second byte can be written.

(3)The reception data is sampled at the falling edge of serial clock (SCK) input. It changes to SSR:RDRF=1 if the last bit of the reception data is received, and when reception interrupt enabled (SCR:RIE=1) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, SSR:RDRF is cleared to "0".

· Continuous change from reception operation to transmission operation

(1) Serial data output is disabled(SMR:SOE=0),reception interrupt is enabled(SCR:RIE=1), reception operation is enabled(SCR:RXE=1) and transmission operation is enabled(SCR:TXE=1). When serial clock (SCK) writes the dummy data in TDR at the mark level, the reception data is sampled by the falling edge of serial clock input (SCK).

(2) Write the dummy data in TDR by rising edge of the following serial clock (SCK)after the reception interruption request, when you continue the reception operation.

- (3) To switch from the reception operation to the transmission operation, serial data output set enabled(SMR:SOE=1), reception interrupt set disabled(SCR:RIE=0), and reception operation set disabled(SCR:RXE=0) between the reception interrupt request and the rising edge of the next serial clock (SCK), and after transmission data is written to TDR and reception operation finishes, the transmission data is outputted in synchronization with the rising edge of the serial clock.

6.2.4. SPI Transfer (II)

SPI Transfer (II) is shown below.

■ Features

	Item	Description
1	Mark level of serial clock (SCK)	"L"
2	Transmission data output timing	SCK falling edge
3	Reception data sampling	SCK rising edge
4	Data length	5 to 9 bits

■ Register Settings

The following table lists the register settings required for SPI Transfer (II).

Table 6-5 SPI Transfer (II) Register Settings

	bit1 5	bit1 4	bit1 3	bit1 2	bit1 1	bit1 0	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR/SMR	UPCL	MS	SPI	RIE	TIE	TBIE	RXE	TXE	MD2	MD1	MD0	-	SCI NV	BDS	SCK E	SOE
	0	1/0	1	*	*	*	*	*	0	1	0	-	1	*	1/0	1/0
SSR/ESCR	REC	-	-	-	ORE	RDR F	TDR E	TBI	SOP	-	-	WT1	WT0	L2	L1	L0
	0	-	-	-	-	-	-	-	0	-	-	*	*	*	*	*
TDR/RDR								D8	D7	D6	D5	D4	D3	D2	D1	D0
								*	*	*	*	*	*	*	*	*
BGR	-	BGR[14:8]							BGR[7:0]							
	-	*	*	*	*	*	*	*	*	*	*	*	*	*	*	*

1: Set to "1"

0: Set to "0"

*: User-configurable setting

Note:

The above bit settings (1 or 0) are different between the master and slave operations. Set the bits as follows:

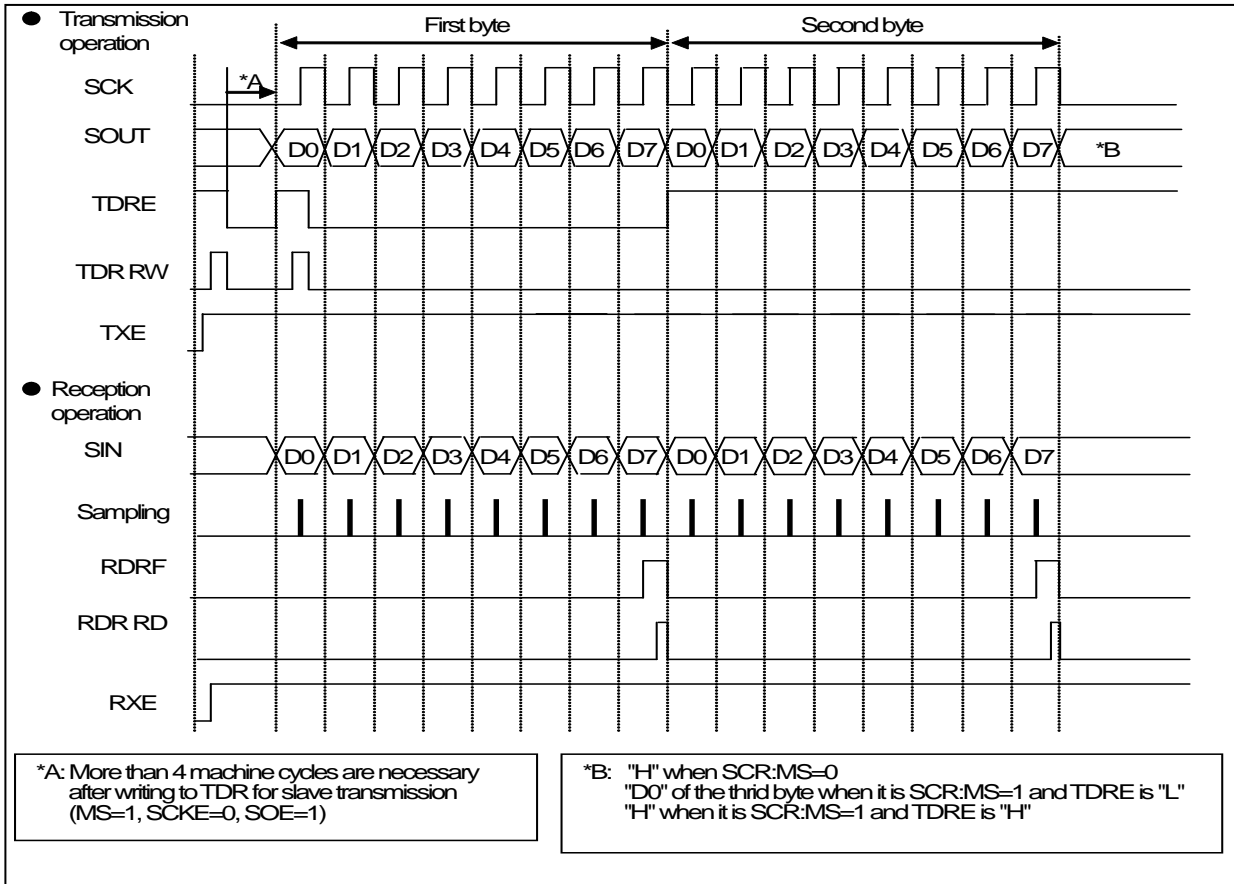
Master transmission : SCR:MS=0, SMR:SCKE=1, SOE=1

Master reception : SCR:MS=0, SMR:SCKE=1, SOE=0

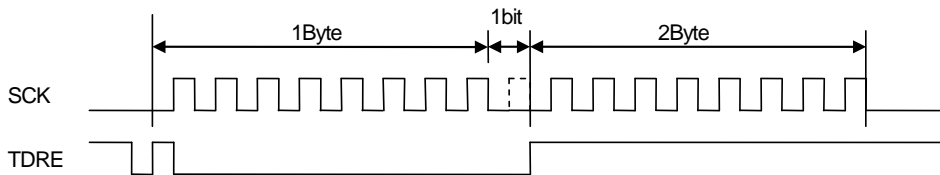
Slave transmission : SCR:MS=1, SMR:SCKE=0, SOE=1

Slave reception : SCR:MS=1, SMR:SCKE=0, SOE=0

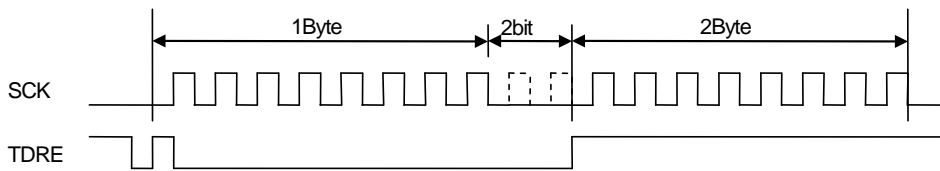
■ **SPI Transfer (II) Timing Chart**
Figure 6-8 SPI Transfer (II) Timing Chart



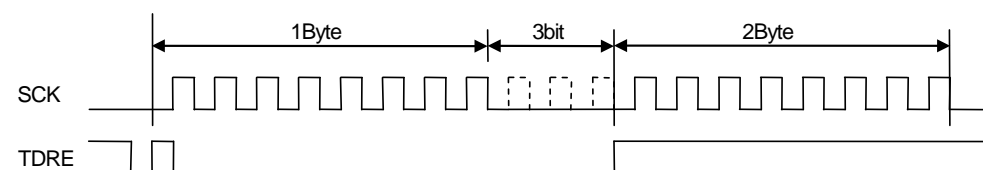
■ ESCR:WT1=0, ESCR:WT0=1 (for master)



■ ESCR:WT1=1, ESCR:WT0=0 (for master)



■ ESCR:WT1=1, ESCR:WT0=1 (for master)



■ Operation

[1] Master operation (Set SCR:MS=0, SMR:SCKE=1.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1), transmission operation enabled (SCR:TXE=1), and reception operation disabled (SCR:RXE=0), writing transmission data to TDR sets SSR:TDRE=0 and outputs the transmission data in synchronization with a falling edge of the serial clock (SCK) output.
 - (2) The SSR:TDRE bit is set as 1 at before half cycle of the rising edge of first serial clock (SCK) and transmission interrupt enabled is outputted when transmission interrupt enabled(SCR:TIE=1) is done. At this time, the transmission data in the second byte can be written.
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0), transmission operation enabled (SCR:TXE=1), and reception operation enabled (SCR:RXE=1), writing dummy data to TDR samples the reception data at a rising edge of the serial clock output (SCK).
 - (2) Receiving the last bit sets SSR:RDRF=1 and, if the reception interrupt is enabled (SCR:RIE=1), a reception interrupt request is outputted. At this time, the receive data (RDR) can be read.
 - (3) Reading the receive data (RDR) clears SSR:RDRF to "0".

Notes:

- If only reception operation is to be performed, write dummy data to TDR to output the serial clock (SCK).
 - When transmission/reception FIFO is enabled, setting the FBYTE register to the number of frames to be transferred outputs as many frames of serial clock (SCK) as the setting.
-

- Transmission/ Reception operation
 - (1) When the transmission and reception operation is done at the same time, set serial data output enabled (SMR:SOE=1) and set reception operation enabled (SCR:TXE, RXE=1).
 - (2) If the transmission data is written in TDR, the SSR:TDRE is set as 0 also the first bit is outputted. After synchronization with the falling edge of serial clock (SCK) output and the transmission data is output. The SSR:TDRE bit is set as 1 at before half cycle of the rising edge of first serial clock and transmission interrupt enabled is outputted when transmission interrupt enabled(SCR:TIE=1) is done.. At this time, the transmission data of the second byte can be written.
 - (3)The reception data is sampled at the rising edge of serial clock (SCK) output. It changes to SSR:RDRF=1 if the last bit of the reception data is received, and when reception interrupt enabled (SCR:RIE=1) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, SSR:RDRF is cleared to "0".
- Successive data transmission or reception wait operation
 - (1) If setting other than (ESCR:WT1, WT0)= (0,0) is specified for successive data transmission or reception, a wait is inserted between frames.

[2] Slave operation (Set SCR:MS=1, SMR:SCKE=0.)

- Transmission operation
 - (1) With serial data output enabled (SMR:SOE=1) and transmission operation enabled (SCR:TXE=1), writing transmission data to TDR sets SSR:TDRE=0 and outputs the transmission data in synchronization with a falling edge of the serial clock (SCK) output.
 - (2) Outputting the transmission data in the first bit sets SSR:TDRE=1 and, if the transmission interrupt is enabled (SCR:TIE=1), a transmission interrupt request is outputted. At this time, the transmission data in the second byte can be written.

Note:

- After the transmission operation is enabled (SCR:TXE=1), if transmission data is written to the first TDR except when serial clock (SCK) is at the mark level, the first bit data is not output and the transmission is not operated normally. After the transmission operation is enabled (SCR:TXE=1), write the transmission data to the first TDR when serial clock (SCK) is at the mark level.
-
- Reception operation
 - (1) With serial data output disabled (SMR:SOE=0) and reception operation enabled (SCR:RXE=1), the reception data is sampled at a rising edge of the serial clock input (SCK).
 - (2) Receiving the last bit sets SSR:RDRF=1 and, if the reception interrupt is enabled (SCR:RIE=1), a reception interrupt request is outputted. At this time, the receive data (RDR) can be read.
 - (3) Reading the receive data (RDR) clears SSR:RDRF to "0".
 - Transmission/ Reception operation
 - (1) When the transmission and reception operation is done at the same time, set serial data output enabled (SMR:SOE=1) and set reception operation enabled (SCR:TXE, RXE=1).
 - (2) If the transmission data is written in TDR, the SSR:TDRE is set as 0 also the first bit is outputted. After synchronization with the falling edge of serial clock (SCK) input and the transmission data is output. The SSR:TDRE bit is set as 1 when the first byte of the transmission data is outputted and a transmission interrupt request is outputted when transmission interrupt enabled(SCR:TIE=1) is done. At this time, the transmission data of the second byte can be written.
 - (3)The reception data is sampled at the rising edge of serial clock (SCK) input. It changes to SSR:RDRF=1 if the last bit of the reception data is received, and when reception interrupt enabled (SCR:RIE=1) is done, the reception interrupt request is output. At this time, the receive data (RDR) can be read. When the reception data is read, SSR:RDRF is cleared to "0".
 - Continuous change from reception operation to transmission operation
 - (1) Serial data output is disabled(SMR:SOE=0),reception interrupt is enabled(SCR:RIE=1), reception operation is enabled(SCR:RXE=1) and transmission operation is enabled(SCR:TXE=1). When serial clock (SCK) writes the dummy data in TDR at the mark level, receive data is sampled by the falling edge of serial clock input (SCK).
 - (2) Write the dummy data in TDR by rising edge of the following serial clock (SCK) after the reception interruption request, when you continue the reception operation.
 - (3) To switch from the reception operation to the transmission operation, set serial data output enabled(SMR:SOE=1), set reception interrupt disabled(SCR:RIE=0), and set reception operation disabled(SCR:RXE=0) between the reception interrupt request and the rising edge of the next serial clock (SCK), and after transmission data is written to TDR and reception operation finishes, The transmission data is outputted in synchronization with the rising edge of the serial clock.

6.2.5. Baud Rate Generation

The baud rate generation is shown below.

The dedicated baud rate generator works only in master operation. However, if the reception FIFO is to be used, set the dedicated baud rate generator even in slave operation.

The dedicated baud rate generator settings are different between the master and slave operations.

[1] Master operation

The dedicated baud rate generator divides the internal clock and a baud rate is selected.

- There are two internal reload counters that correspond to the transmission and reception serial clocks, respectively. The baud rate can be selected by setting a 15-bit reload value in the baud rate generator register (BGR).
- The reload counter divides the internal clock with the setting value.

[2] Slave operation

- The dedicated baud rate generator does not work in slave operation (SCR:MS=1). (The external clock entered from the clock input pin (SCK) is used without change.)
-

Note:

If the reception FIFO is to be used, set the dedicated baud rate generator even in slave operation.

■ Baud Rate Calculation

Set two 15-bit reload counters in the baud rate generator register (BGR). The baud rate calculation formulas are as follows:

(1) Reload value

$$V = \varphi / b - 1$$

V: Reload value φ : peripheral clock (PCLK) frequency b: Baud rate

(2) Example of calculation

If the peripheral clock (PCLK) of 16MHz, use of the internal clock, baud rate of 19200bps are to be set,

Reload value:

$$V = (16 \times 1,000,000) / 19200 - 1 = 832$$

Therefore, the baud rate is

$$b = (16 \times 1,000,000) / (832 + 1) = 19208 \text{ bps}$$

(3) Baud rate error

The baud rate error can be obtained using the following formula:

$$\text{Error (\%)} = (\text{calculated value} - \text{desired value}) / \text{desired value} \times 100$$

Notes:

- Set the reload value to "0" to stop the reload counter.
 - If the reload value is an even number, the "H" and "L" widths of the serial clock depend on the SCINV bit setting as follows: If it is an odd number, the "H" and "L" widths of the serial clock are equal.
 - If SCINV=0, the "H" width of the serial clock is longer by one cycle of the peripheral clock (PCLK).
 - If SCINV=1, the "L" width of the serial clock is longer by one cycle of the peripheral clock (PCLK).
 - Set the reload value to 3 or higher.
-

■ **Reload Counter Functions**

Reload counters, including transmission and reception reload counters, serve as the dedicated baud rate generators. It consists of a 15-bit register for reload values and generates a transmission/reception clock from the internal clock.

■ **Count Start**

When a reload value is written to the baud rate generator register (BGR), the reload counter starts counting.

■ **Restart**

The reload counter restarts under one of the following conditions:

- Common to the transmission and reception reload counters
 - Programmable reset (SCR:UPCL bit)

6.3. Setup Procedure and Program Flow

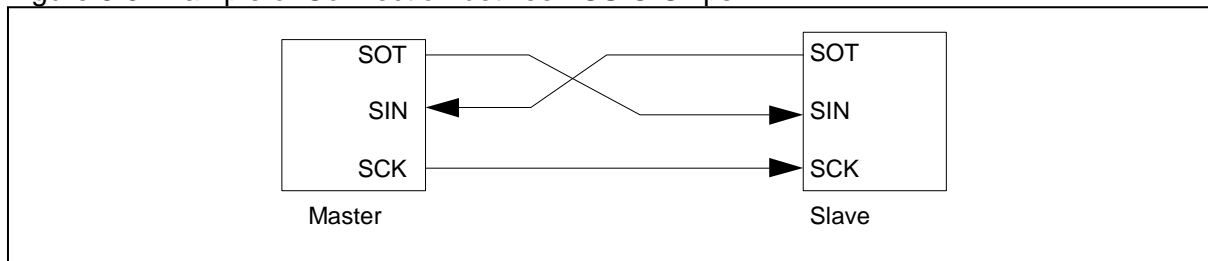
The setup procedure and program flow are shown.

- 6.3.1. Connections between Chips
- 6.3.2. Flowchart

6.3.1. Connections between Chips

Connections between chips are shown below.

Figure 6-9 Example of Connection between CSIO Chips



6.3.2. Flowchart

The flowchart is shown below.

Figure 6-10 Flowchart Example (FIFO Not Used)

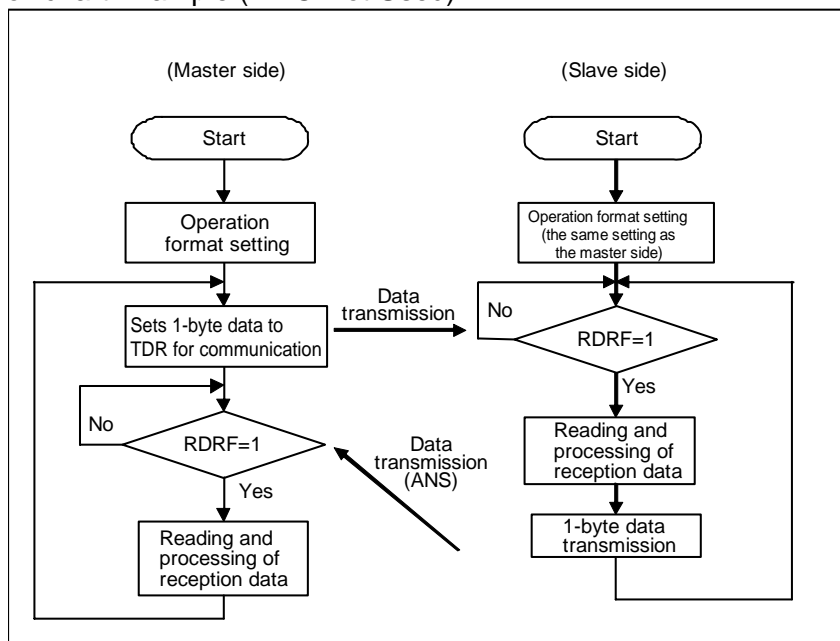
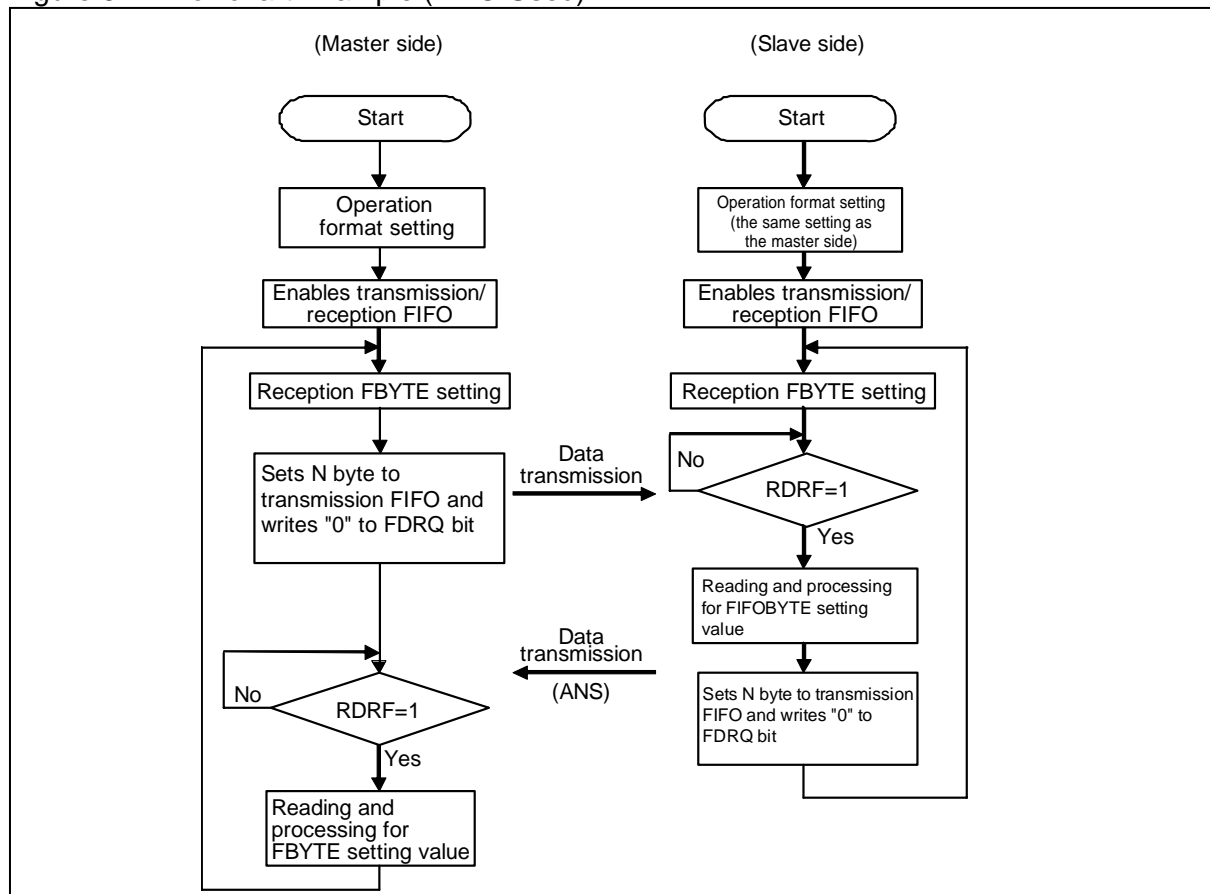


Figure 6-11 Flowchart Example (FIFO Used)



7. Operation of LIN-UART

The operation of LIN-UART is shown.

- 7.1. Interrupts of LIN-UART
- 7.2. Operation of LIN-UART
- 7.3. Setup Procedure and Program Flow

7.1. Interrupts of LIN-UART

Interrupts of LIN-UART are shown below.

The LIN-UART can generate interrupt requests for the following factors:

- Setting of reception data in the receive data register (RDR) or occurrence of a reception error
- Start of transmission after transfer of transmission data from the transmit data register (TDR) to the transmit shift register
- Transmission bus idle (no transmission operation)
- Transmission FIFO data request
- LIN Synch Break detection

7.1.1. List of Interrupts of LIN-UART Interface

The list of interrupts of LIN-UART interface is shown below.

The following table indicates how LIN-UART interrupt control bits relate to interrupt factors.

Table 7-1 Interrupt Control Bits and Interrupt Sources of LIN-UART

Interrupt type	Interrupt request flag bit	Flag register	Interrupt factor	Interrupt factor enable bit	Clearing of interrupt request
Reception	RDRF	SSR	1-byte reception	SCR:RIE	Reading of receive data (RDR)
			Reception of as much data as specified by FBYTE		Reading of receive data (RDR) until the reception FIFO is emptied
			Detection of reception idle for 8-bit time or more while there is valid data in the reception FIFO with the FRIIE bit set to "1".		
	ORE	SSR	Overrun error		Writing of "1" to the reception error flag clear bit (SSR:REC)
FRE	SSR	Framing error			
Transmission	TDRE	SSR	Transmission register is empty	SCR:TIE	Writing the transmit data (TDR) or writing of "1" to the transmission FIFO operation enable bit while the transmission FIFO operation enable bit is "0" and there is valid data in the transmission FIFO (retransmission)*1
	TBI	SSR	No transmission operation	SCR:TBIE	Write to the transmit data (TDR), write "1" to the LIN Synch Break set bit(LBR), or write "1" to the transmission FIFO operation enable bit when it is "0" and the transmission FIFO has valid data (retransmission)*1
	FDRQ	FCR1	Transmission FIFO is empty	FCR1:FTIE	Writing of "0" to the FIFO transmission data request bit (FCR1:FDRQ), or transmission FIFO is full
Status	LBD	SSR	Lin Synch Break detection	ESCR:LBIE	Writing "0" to the SSR:LBD

Interrupt type	Interrupt request flag bit	Flag register	Interrupt factor	Interrupt factor enable bit	Clearing of interrupt request
Input capture *2	ICP	ICS	1st falling edge of Lin Synch Field	ICS:ICE	Disabling of ICP
	ICP	ICS	5th falling edge of Lin Synch Field		

*1: Set the TIE bit after the TDRE bit is set to "0".

*2: For registers, see "CHAPTER : INPUT CAPTURE".

Notes:

- DMA transfer triggered by a status interrupt is not supported.
- To detect a LIN synch break, disable reception (SCR:RXE=0) after enabling LIN synch break detection interrupt(LBIE=1).

7.1.2. Reception Interrupts and Flag Setting Timing

Reception interrupts and flag setting timing are shown below.

Reception interrupts occur when the reception is completed (SSR:RDRF), when a reception error occurs (SSR:ORE, FRE), or when LIN Synch Break is detected.

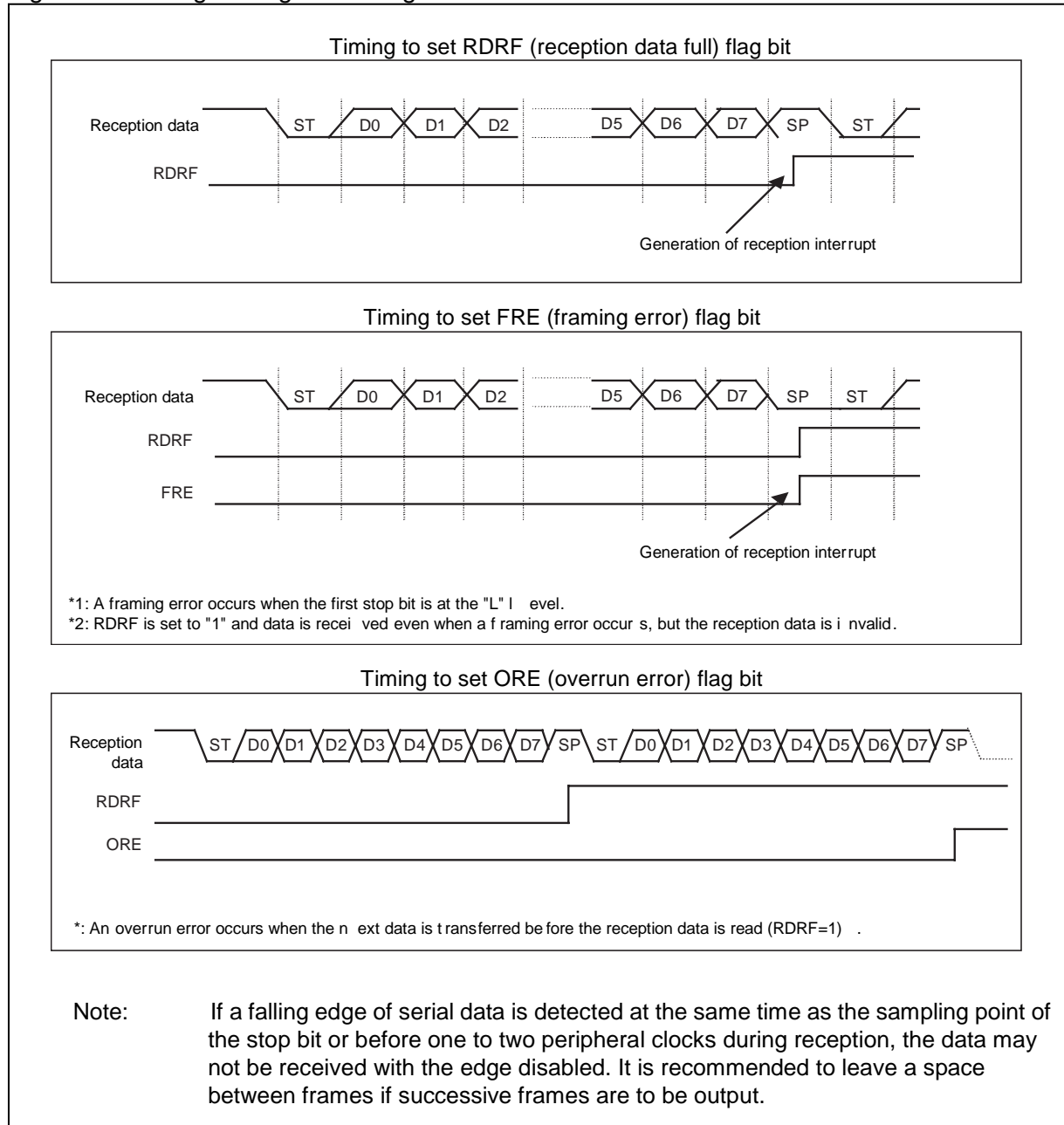
■ Reception Interrupts and Flag Setting Timing

When the first stop bit is detected, reception data is stored in the receive data register (RDR). When reception is completed (SSR:RDRF=1) or a reception error occurs (SSR:ORE, FRE=1), a corresponding flag is set. If reception interrupts are enabled at this time (SCR:RIE=1), a reception interrupt will occur.

Note:

When a reception error occurs, the data in the receive data register (RDR) becomes invalid.

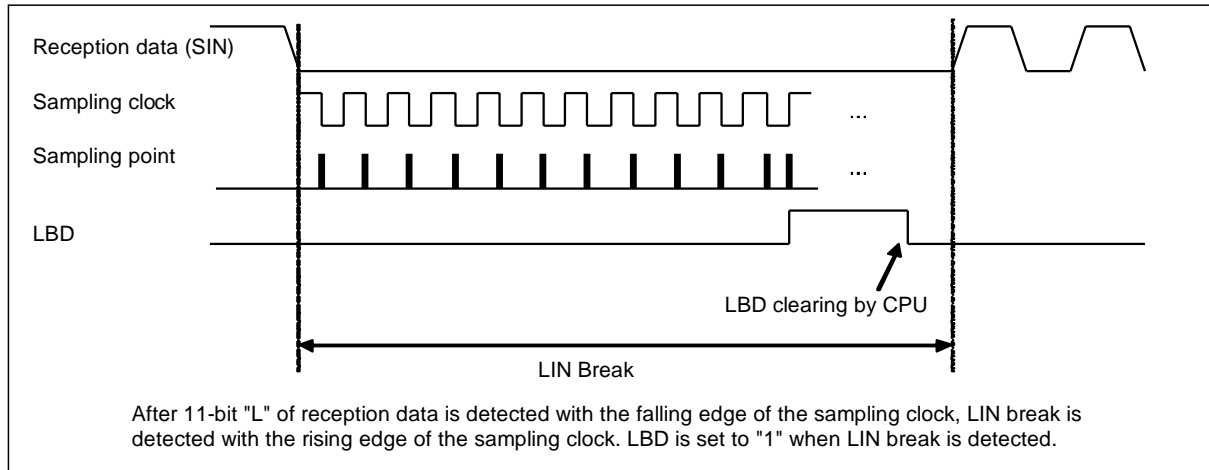
Figure 7-1 Timing of Flag Bit Setting



■ **Timing of LIN Synch Break Detection Flag (LBD) Setting**

In slave operation (SCR:MS=1), the LDB bit is set to "1" when the serial input (SIN) is "0" for more than 11-bit width. If the LIN Synch Break interrupt is enabled (ESCR:LBIE=1) at this time, a reception interrupt occurs.

Figure 7-2 Timing of LBD (LIN Synch Break Detection) Flag Setting



7.1.3. Interrupts when Using Reception FIFO and Flag Setting Timing

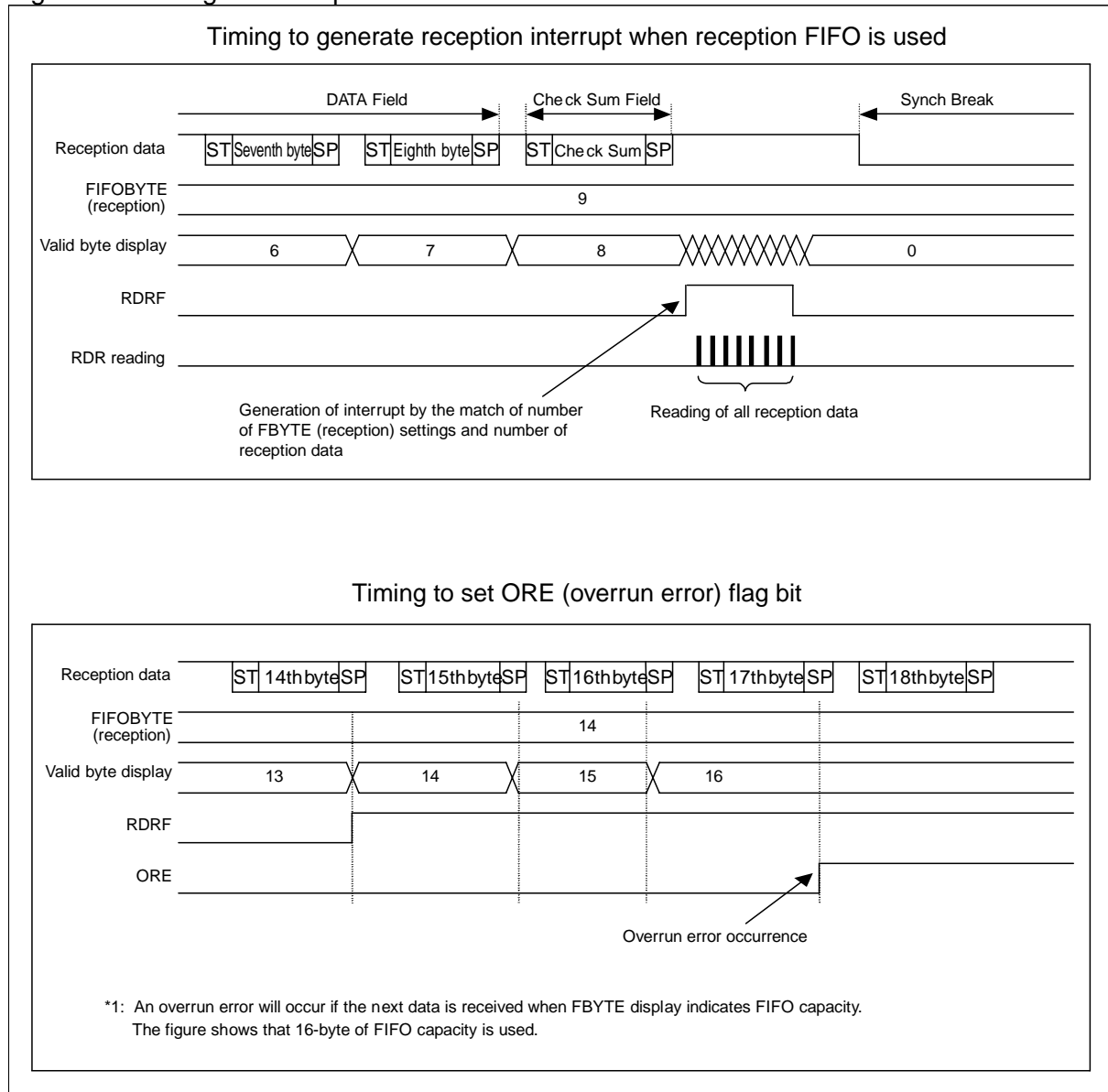
Interrupts when using reception FIFO and flag setting timing are shown below.

When the reception FIFO is used, an interrupt occurs after as much data as the FBYTE register (FBYTE) setting is received.

The setting value of the FBYTE register determines the occurrence of an interrupt when the reception FIFO is used.

- After as much data as the transfer count setting of the FBYTE register is received, the reception data full flag of the serial status register (SSR:RDRF) is set to "1". If the reception interrupt is enabled (SCR:RIE) at this time, a reception interrupt will be generated.
- If the data count contained in the reception FIFO does not reach the transfer count while reception FIFO idle detection enable bit (FRIIE) is set to "1", the interrupt flag (RDRF) will be set to "1" after the reception idle state continues for 8 baud rate clocks or longer. If you read the RDR while the counter is counting 8 baud rate clocks, the counter will be reset to 0 and start counting 8 clocks again. If the reception FIFO is disabled, the counter is reset to 0. When the reception FIFO is enabled while there is data remaining in it, the counter will start counting again.
- If the receive data (RDR) is read until the reception FIFO is empty, the reception data full flag (SSR:RDRF) will be cleared.
- When the reception-enabled data count indication has shown the FIFO capacity, receiving the next data will generate an overrun error (SSR:ORE=1).

Figure 7-3 Timing of Interrupt Generation



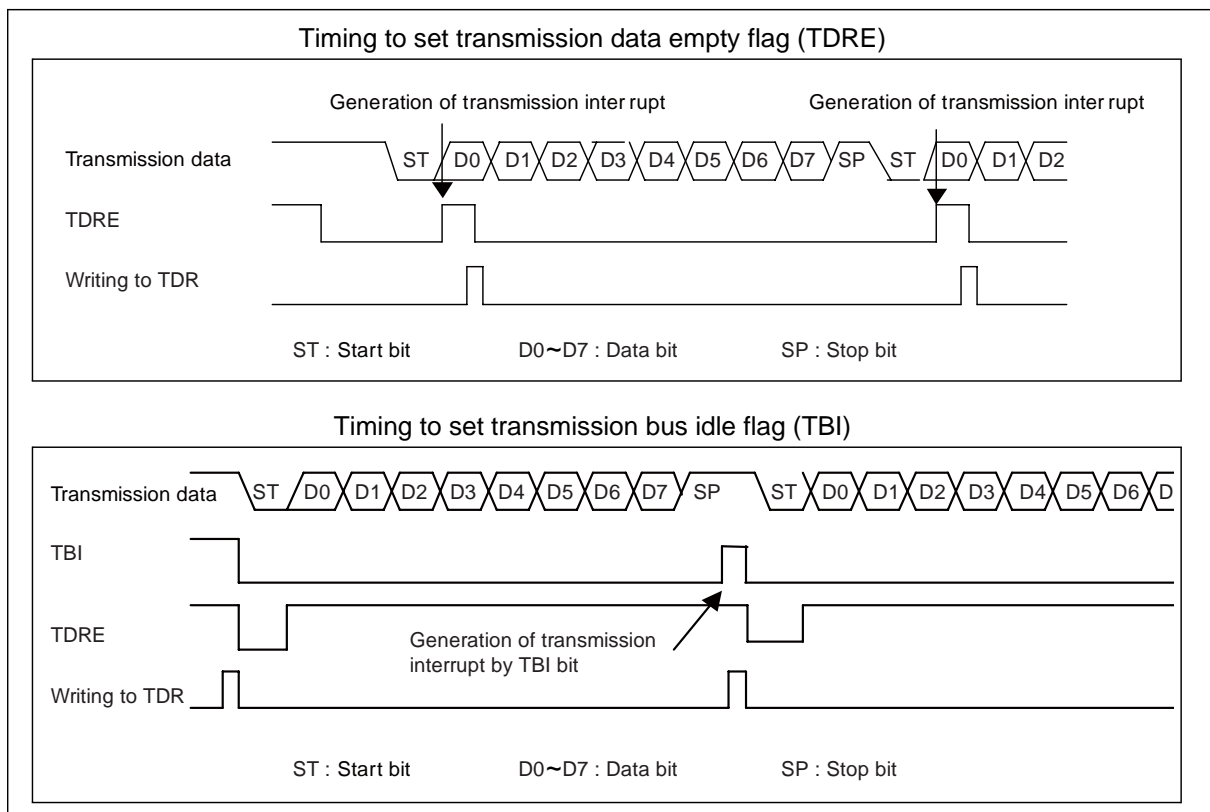
7.1.4. Transmission Interrupts and Flag Setting Timing

Transmission interrupts and flag setting timing are shown below.

Transmission interrupts occur either when transmission is started after transfer of transmission data from the transmit data register (TDR) to the transmit shift register (SSR:TDRE=1) or when the transmission operation is idle (SSR:TBI=1).

- Timing of transmission data empty flag (SSR:TDRE) setting
When data written to the transmit data register (TDR) is transferred to the transmit shift register, writing of next data is enabled (SSR:TDRE=1). If the transmission interrupt is enabled (SCR:TIE=1) at this time, a transmission interrupt occurs. The SSR:TDRE bit, being a read-only bit, is cleared to "0" by writing of data to the transmit data register (TDR).
- Timing of transmission bus idle flag (TBI) setting
When the transmit data register is empty (TDRE=1) and no transmission operation is in progress, the SSR:TBI bit is set to "1". If transmission bus idle interrupt is enabled (SCR:TBIE=1) at this time, a transmission interrupt occurs. When transmission data is written to the transmit data register (TDR), the TBI bit and the transmission interrupt request will be cleared.

Figure 7-4 Timing of TDRE and TBI Setting



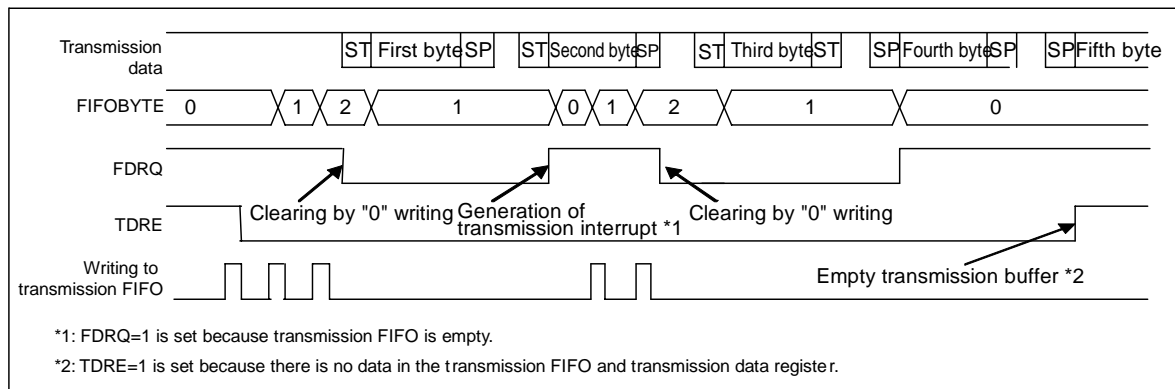
7.1.5. Interrupts When Using Transmission FIFO and Flag Setting Timing

Interrupts when using transmission FIFO and flag setting timing are shown below.

When the transmission FIFO is used, an interrupt will occur if there is no data in the transmission FIFO.

- When there is no data in the transmission FIFO, the FIFO transmission data request bit (FCR1:FDRQ) will be set to "1". If FIFO transmission interrupt is enabled (FCR1:FTIE=1) at this time, a transmission interrupt occurs.
- When required data is written to the transmission FIFO after the occurrence of a transmission interrupt, write "0" to the FIFO transmission data request bit (FCR1:FDRQ) to clear the interrupt request.
- When the transmission FIFO is full, the FIFO transmission data request bit (FCR1:FDRQ) is set to "0".
- The presence of data in the transmission FIFO can be checked by reading the FIFO byte register (FBYTE). When FBYTE=00_H, there is no data in the transmission FIFO.

Figure 7-5 Timing of Transmission Interrupts when Using Transmission FIFO



7.2. Operation of LIN-UART

The operation of LIN-UART is shown below.

The LIN-UART operates for the master/slave bidirectional LIN communication.

7.2.1. Master Device Operation

The Master device operation is shown below.

■ Device Selection

To make the LIN-UART work as the master device, set the SCR:MS bit to "0".

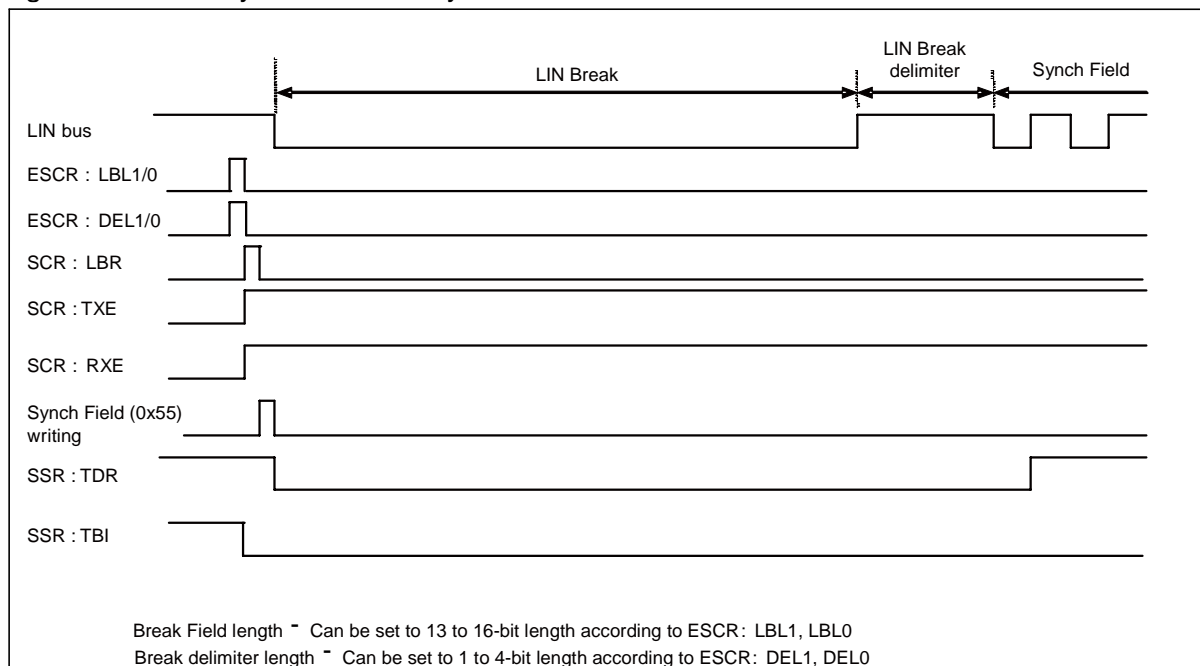
■ From Synch Break Transmission to Synch Field Transmission

- Selection of the Synch Break length (ESCR:LBL1, LBL0) and selection of the Synch Break delimiter length (ESCR:DEL1, DEL0) are performed.
- A Synch Break is transmitted by enabling transmission (SCR:TXE=1) and setting the SCR:LBR bit (LIN Synch Break setting bit) to "1".
- The Synch Field is transmitted by writing 0x55 in the transmit data register (TDR).

Notes:

- Set 0x55 in the transmit data register (TDR) after setting the SCR:LBR bit (LIN Synch Break setting bit) to "1".
- Even if the SCR:RXE bit (reception enable bit) is set to "1", the Synch Break part dose not perform the reception operation.

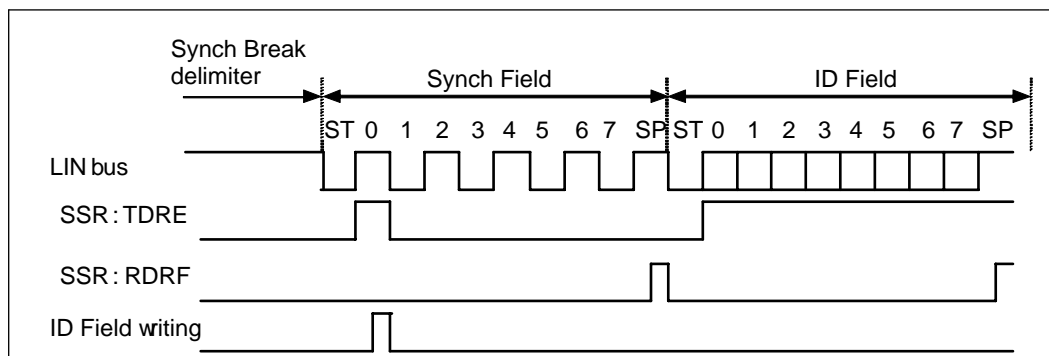
Figure 7-6 From Synch Break to Synch Field Transmission



■ **From Synch Field Transmission to ID Field Transmission**

- When the first bit of the Synch Field (0x55) is transmitted, the SSR:TDRE (transmission data empty) bit is set to "1". If the transmission interrupt is enabled (SCR:TIE=1) at this time, a transmission interrupt occurs.
- When this interrupt occurs, the ID Field can be written to the transmit data register (TDR).
- When a reception interrupt occurs, the received data will be compared with the transmitted data to confirm that no error has occurred.
- The ID Field is output in an LSB-first fashion with a data length of 8 bits.

Figure 7-7 From Synch Field Transmission to ID Field Transmission



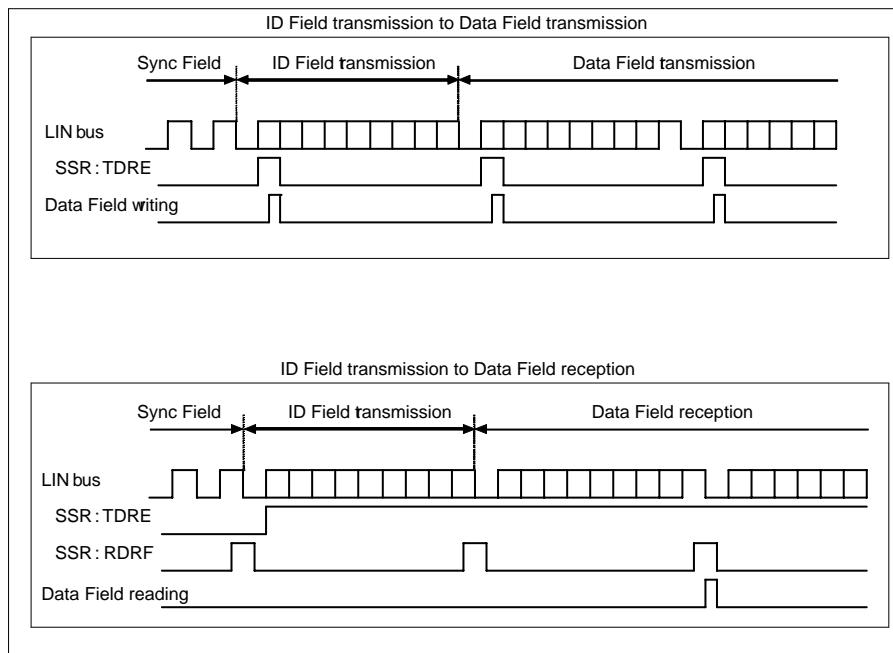
■ **From ID Field Transmission to Data Field Transmission/Reception**

Specify whether to transmit the Data Field to the slave device or receive it.

- In the case of Data Field transmission:
When the first bit of the ID Field is transmitted, the SSR:TDRE bit is set to "1". Data can then be written in the Data Field.
- In the case of Data Field reception:
When the first bit of the ID Field is transmitted, the SSR:TDRE bit is set to "1". However, do not write transmission data. Also, disable transmission interrupts (SCR:TIE=0).
When the Data Field is received, the SSR:RDRF bit is set to "1". If reception interrupts are enabled at this time (SCR:RIE=1), a reception interrupt will occur.

Detection of the start bit is as follows; falling edge is detected after the noise filter(The serial data input is sampled three times with the machine clock and decision by majority) is passed, and the data after passage detects "L" with the sampling point.

Figure 7-8 From ID Field Transmission to Data Field Transmission/Reception



Notes:

- The board is designed so that the noise should not pass this filter or communicate by noise passing so as not to become a problem (For instance, when the error occurs adding the checksum of data at the end, send it again) though the noise filter (The serial data input is sampled three times with the machine clock and decision by majority) is built into.
- It becomes impossible to receive by making the edge invalidity etc. when the falling edge of the serial data is detected at the same time as the sampling point of the stop bit or before 1 to 2 machine clocks when it receives it. When the frame is continuously output, the interval of the frame is recommended to be opened.

■ **Timing Chart when FIFO Is Not Used**

Figure 7-9 LIN Bus Timing (at the Time of Data Field Transmission without Using FIFO)

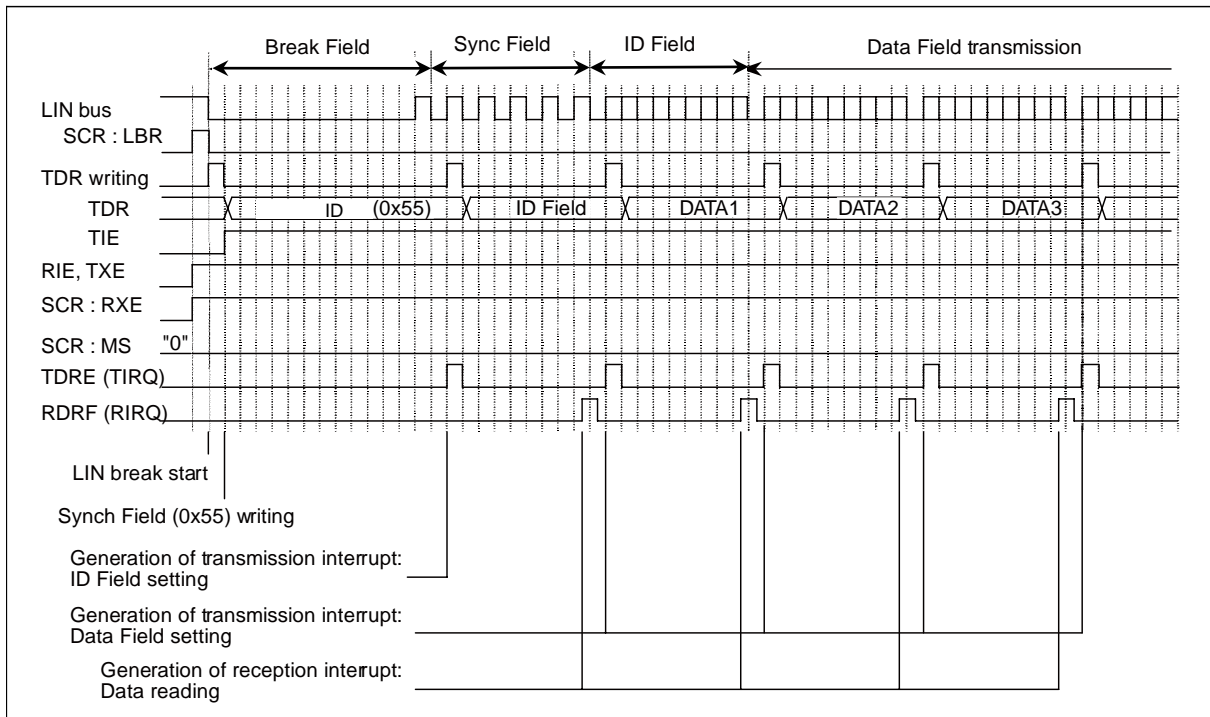
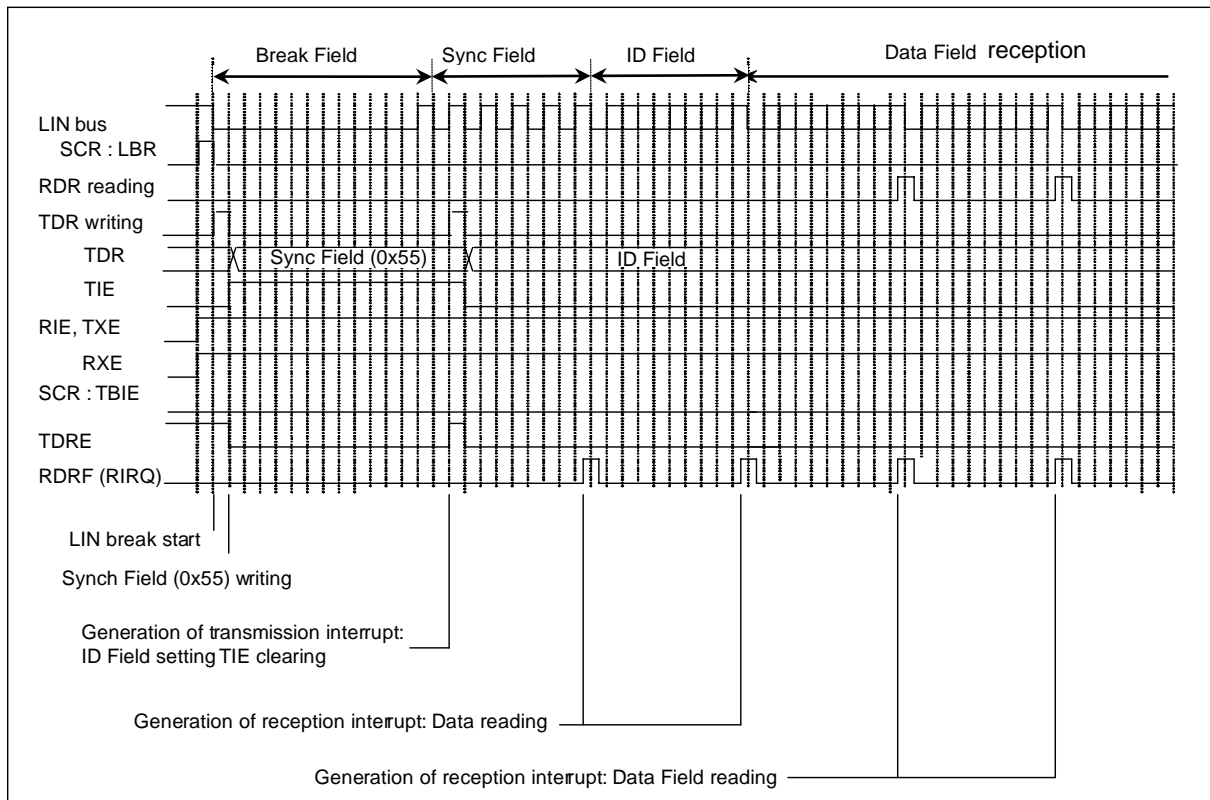


Figure 7-10 LIN Bus Timing (at the Time of Data Field Reception without Using FIFO)



■ **Timing Chart when FIFO Is Used**

Figure 7-11 LIN Bus Timing (at the Time of Data Field Transmission when Using FIFO)

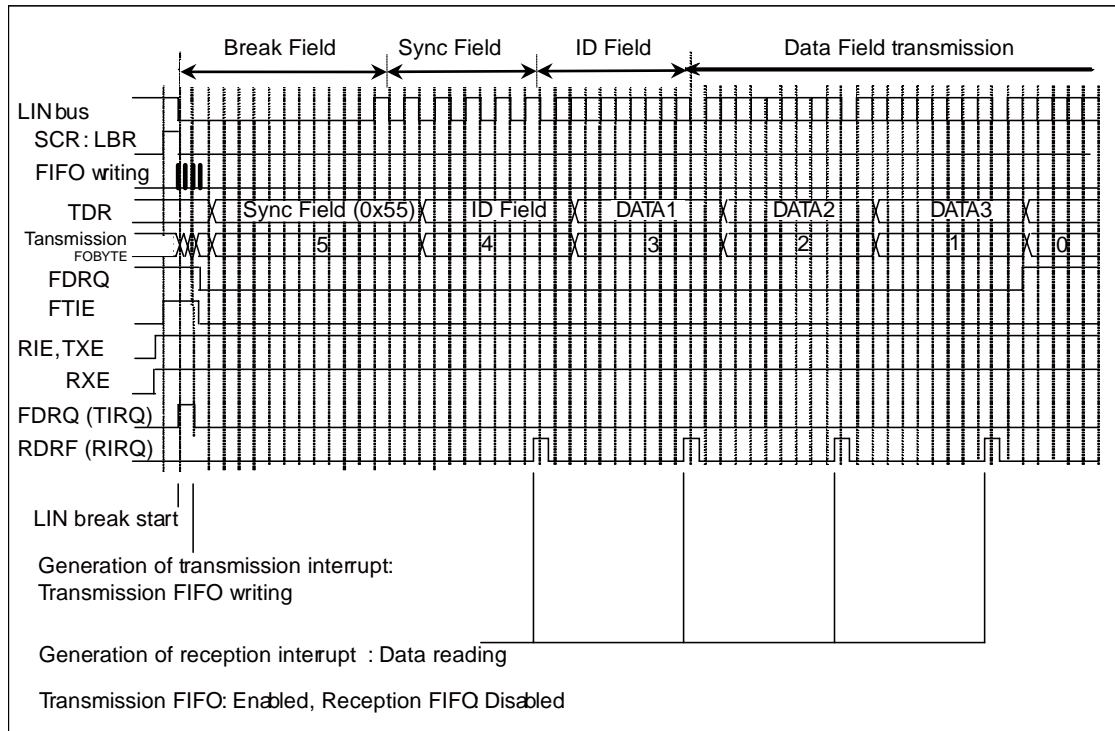
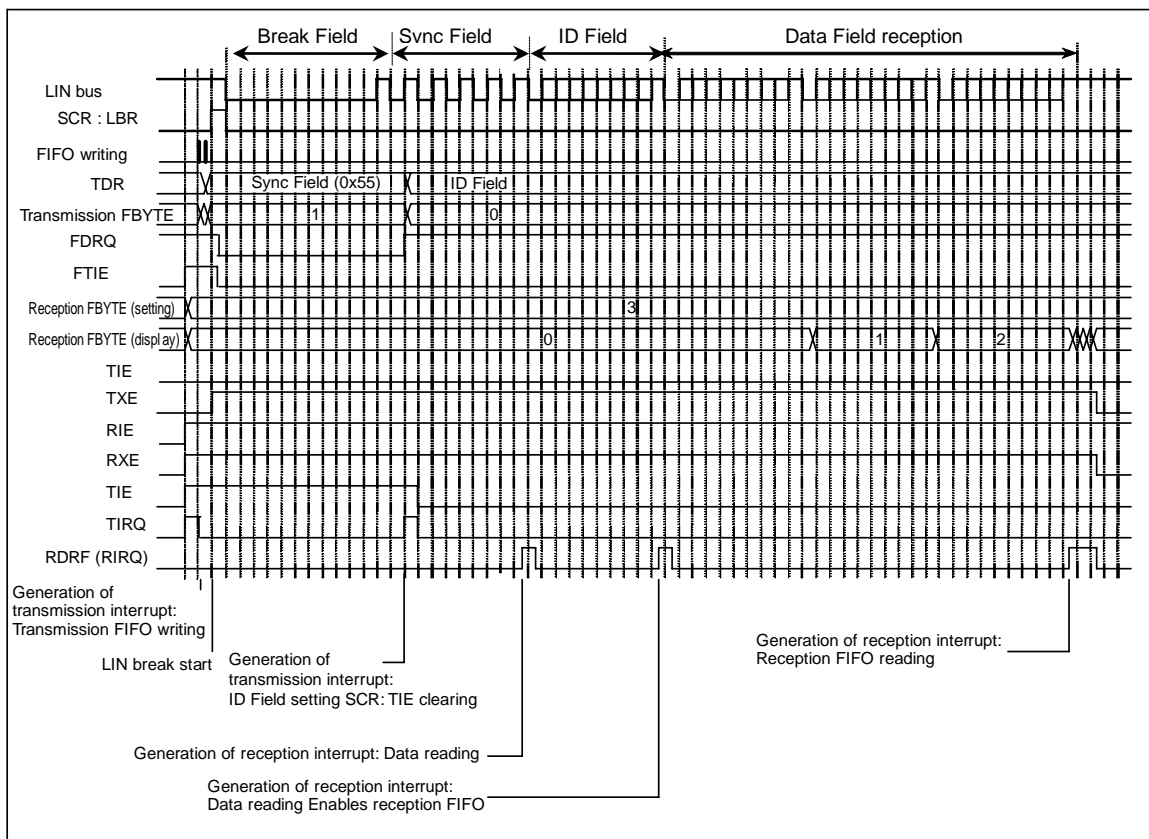


Figure 7-12 LIN Bus Timing (at the Time of Data Field Reception when Using FIFO)



7.2.2. Slave Device Operation

The slave device operation is shown below.

■ Device Selection

To make the LIN-UART work as the slave device, set the SCR:MS bit to "1".

■ From Synch Break Field Reception to Synch Field Reception

- (1) Once Synch Break input begins, the Synch Break will be detected (SSR:LBD=1) when the 11th bit is reached. If the ESCR:LBIE bit is set to "1" at this time, a reception interrupt will occur.
- (2) Enable ICU interrupts and set the detection mode to both edges.
- (3) When the LIN-UART detects the first falling edge of Synch Field, it sets the internal signal (LSYN) to be input to the ICU to "H" to start the ICU. This internal signal (LSYN) becomes "L" on the fifth falling edge.
- (4) The "H" duration of the internal signal (LSYN) input to the ICU becomes 8 times the baud rate. The baud rate setting is as follows:

If the free-run timer has not overflowed:

$$\text{BGR value} = (b - a) \times \text{Fe} / (8 \times \varphi) - 1$$

If the free-run timer has overflowed:

$$\text{BGR value} = (\text{max} + 1 + b - a) \times \text{Fe} / (8 \times \varphi) - 1$$

max: Free-run timer maximum value

a: ICU data register value after the first interrupt

b: ICU data register value after the second interrupt

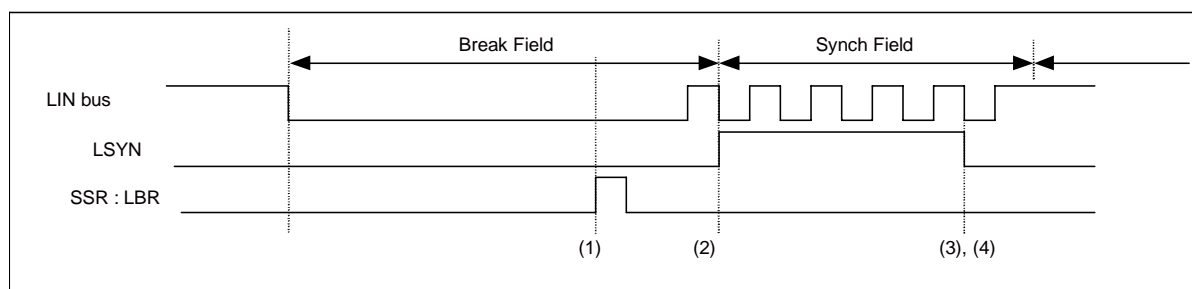
φ : Peripheral clock (PCLK) frequency (MHz)

Fe: External clock frequency (MHz). It is assumed that the internal clock is used (EXT=0) and Fe= φ .

Note:

For Synch Break and Synch Field, disable reception (SCR:RXE=0).

Figure 7-13 From Synch Break Field Reception to Synch Field Reception



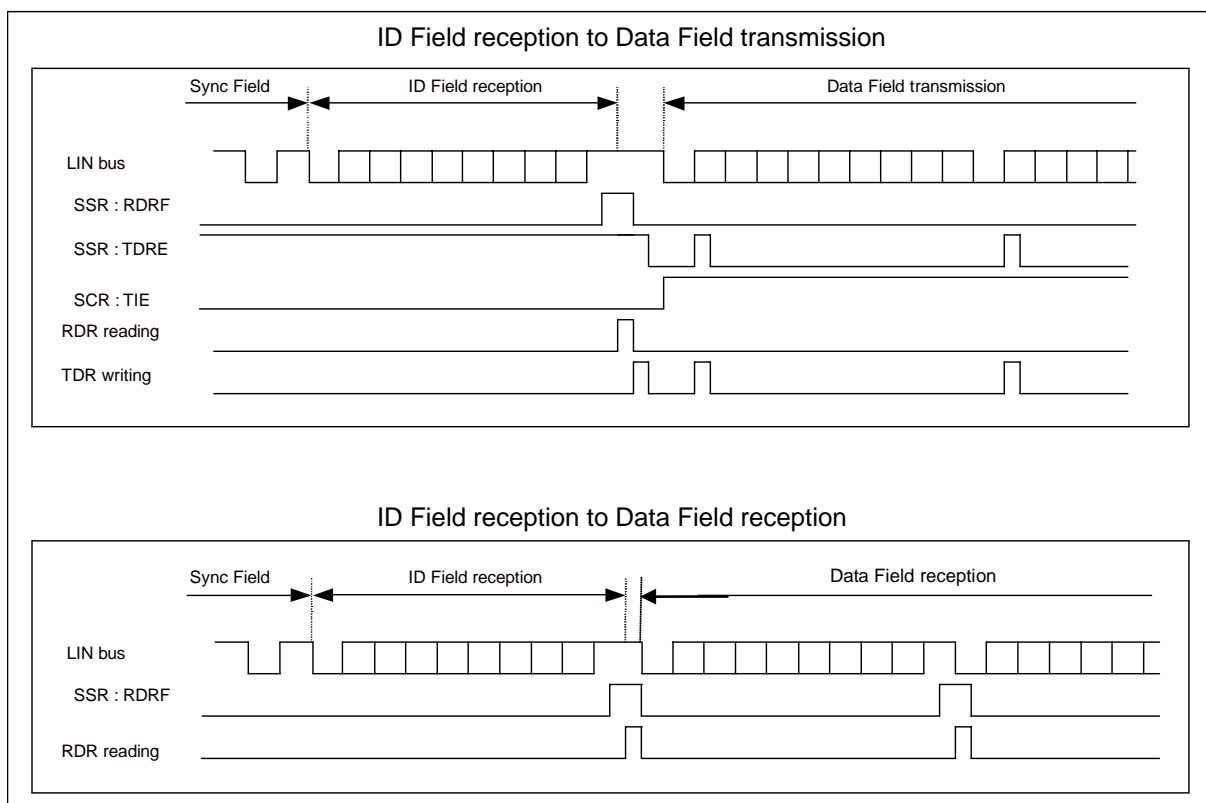
■ **From ID Field Reception to Data Field Transmission/Reception**

After the ID Field is received, specify whether to transmit the Data Field to the master device or receive it.

- In the case of Data Field transmission:
After the ID Field is received, write data in the transmit data register (TDR). At this time, transmission interrupts must be enabled (SCR:TIE=1).
- In the case of Data Field reception:
For every Data Field reception, the SSR:RDRF bit is set to "1". If reception interrupts are enabled (SCR:RDRF=1) at this time, a reception interrupt occurs.

When falling edge is detected after the noise filter (Decision by majority sampling the serial data input with the machine clock three times) is passed, and the data after it passes of that detects "L" with the sampling point, the detection condition of the start bit becomes it.

Figure 7-14 From ID Field Reception to Data Field Transmission/Reception



Notes:

- The board is designed so that the noise should not pass this filter or communicate by noise passing so as not to become a problem (For instance, when the error occurs adding the checksum of data at the end, send it again) though the noise filter (The serial data input is sampled three times with the machine clock and decision by majority) is built into.
- It becomes impossible to receive by making the edge invalidity etc. when the falling edge of the serial data is detected in reception, at the same time of sampling point of stop bit or before 1 to 2 machine clock. When the frame is continuously output, it is recommended to be opened the interval of the frame.

■ **Timing Chart when FIFO Is Not Used**

Figure 7-15 LIN Bus Timing (at the Time of Data Field Transmission without Using FIFO)

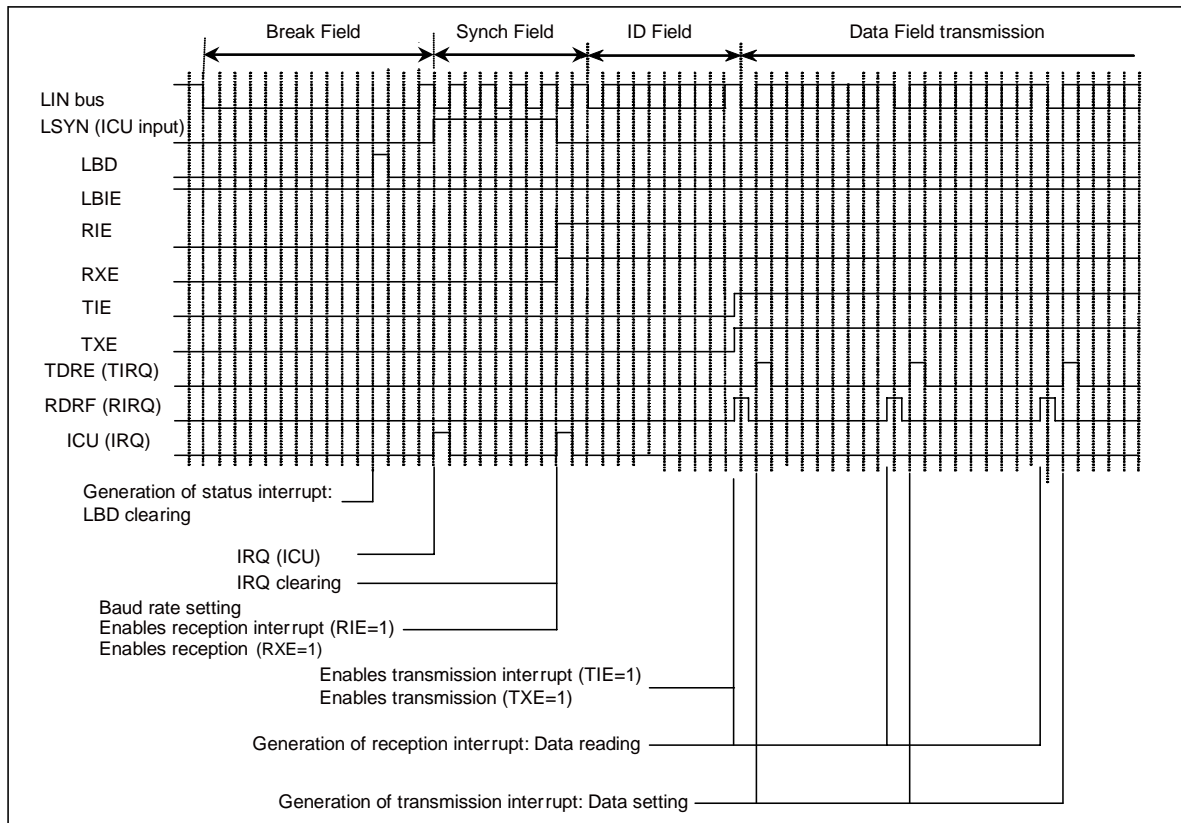
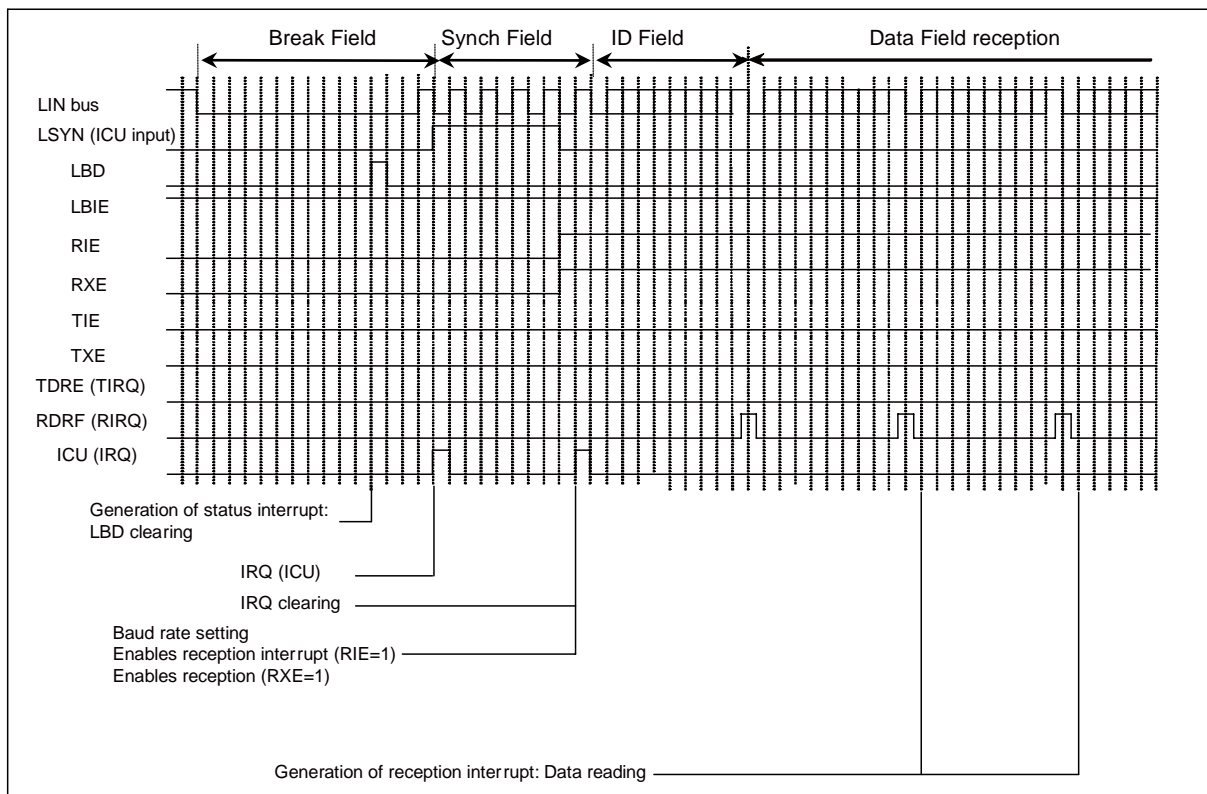


Figure 7-16 LIN Bus Timing (at the Time of Data Field Reception without Using FIFO)



■ **Timing Chart when FIFO Is Used**

Figure 7-17 LIN Bus Timing (at the Time of Data Field Transmission when Using FIFO)

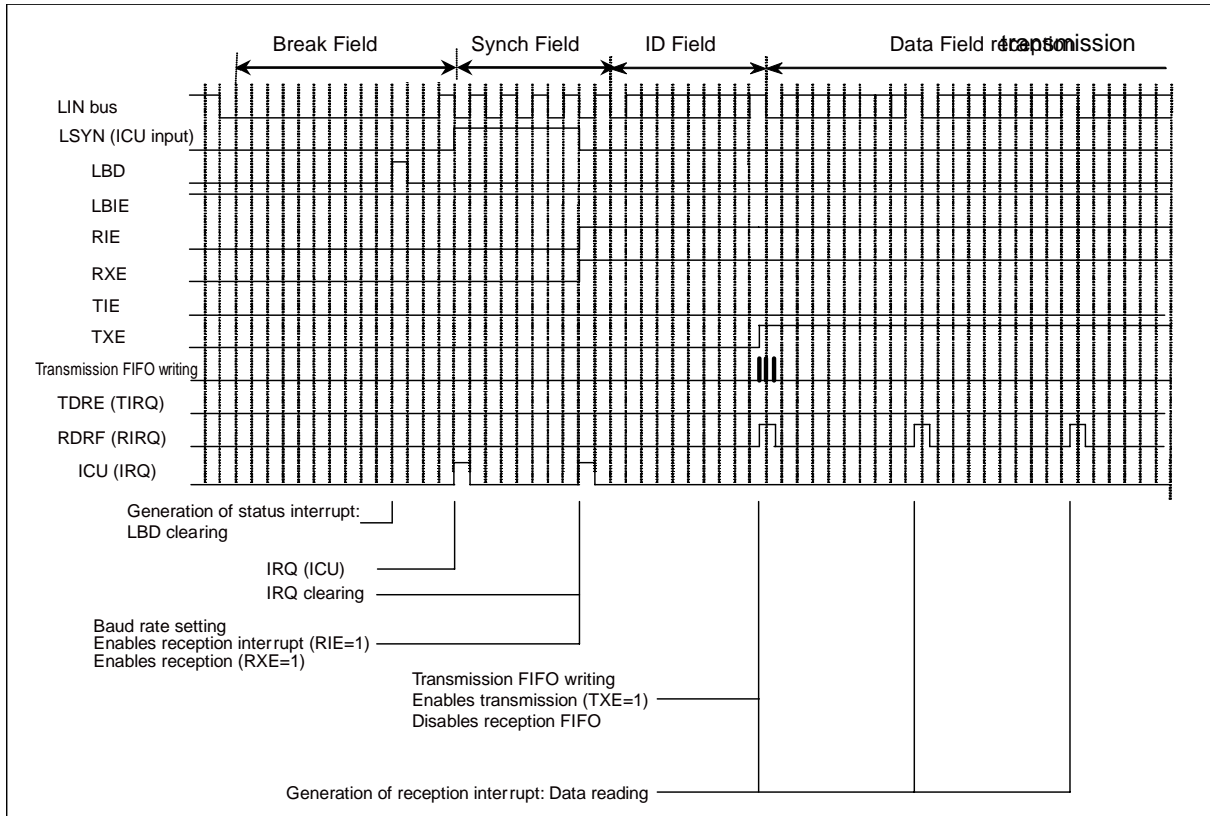
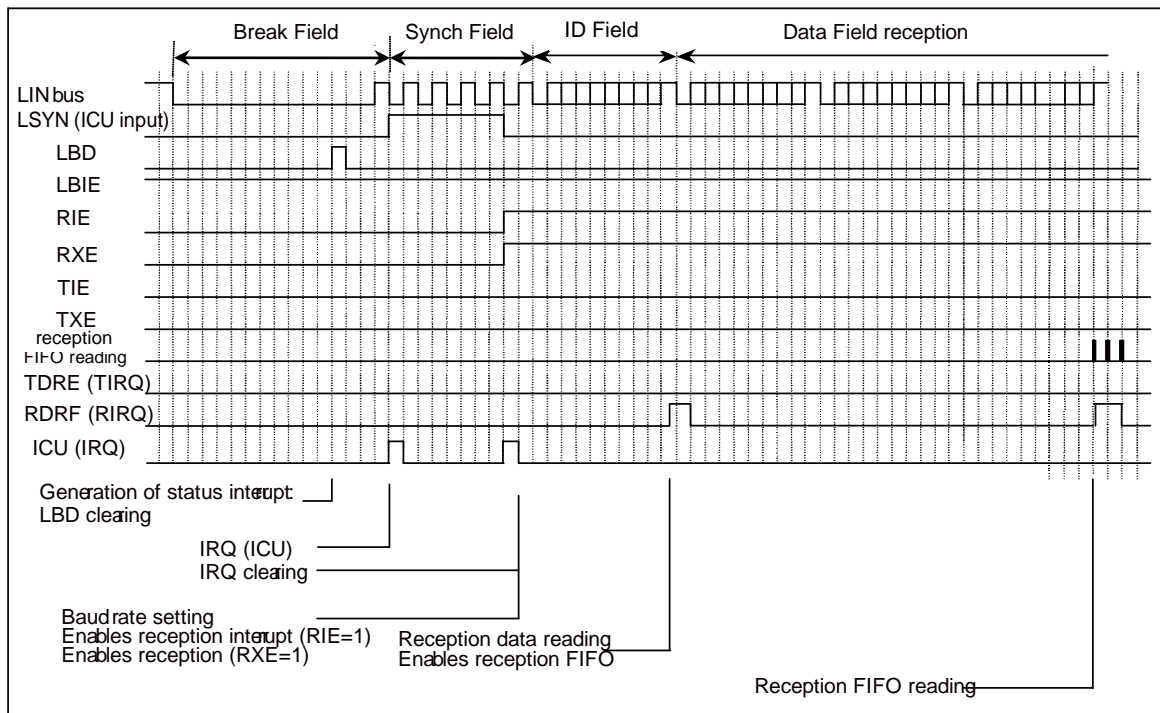


Figure 7-18 LIN Bus Timing (at the Time of Data Field Reception when Using FIFO)



7.2.3. LIN-UART Baud Rate Selection/Setting

The LIN-UART Baud Rate Selection/Setting is shown below.

The LIN-UART can use:

- Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the internal clock
- Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the external clock

The setting method is the same as the method used in the case of UART (mode 0/1). See "5.2.11. UART Baud Rate Selection/Setting".

7.3. Setup Procedure and Program Flow

The setup procedure and program flow are shown below.

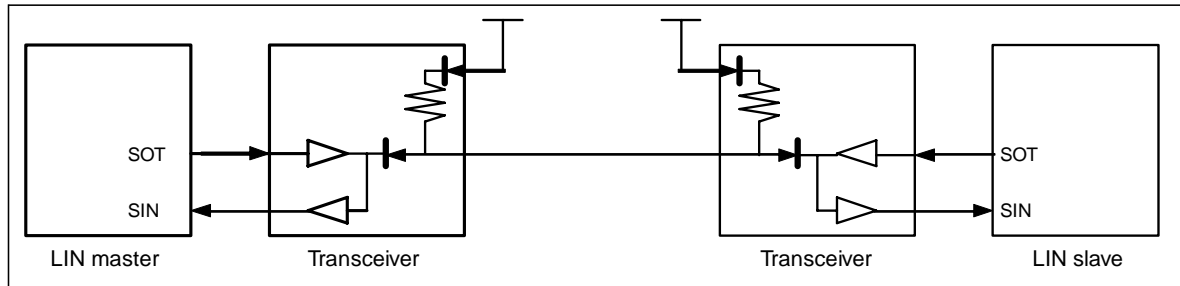
In operation mode 3 (LIN communication mode), the LIN-UART can be used for the LIN master system or LIN slave system.

7.3.1. Inter-CPU Connection

The Inter-CPU connection is shown below.

The following figure shows a communication system that contains one LIN master and one LIN slave. The multi function serial interface can work as a LIN master or LIN slave.

Figure 7-19 Example of LIN Bus System Communication



7.3.2. Flowchart Example

The flowchart Example is shown below.

Figure 7-20 Example of a Flowchart in LIN Communication Master Mode (without Using FIFO)

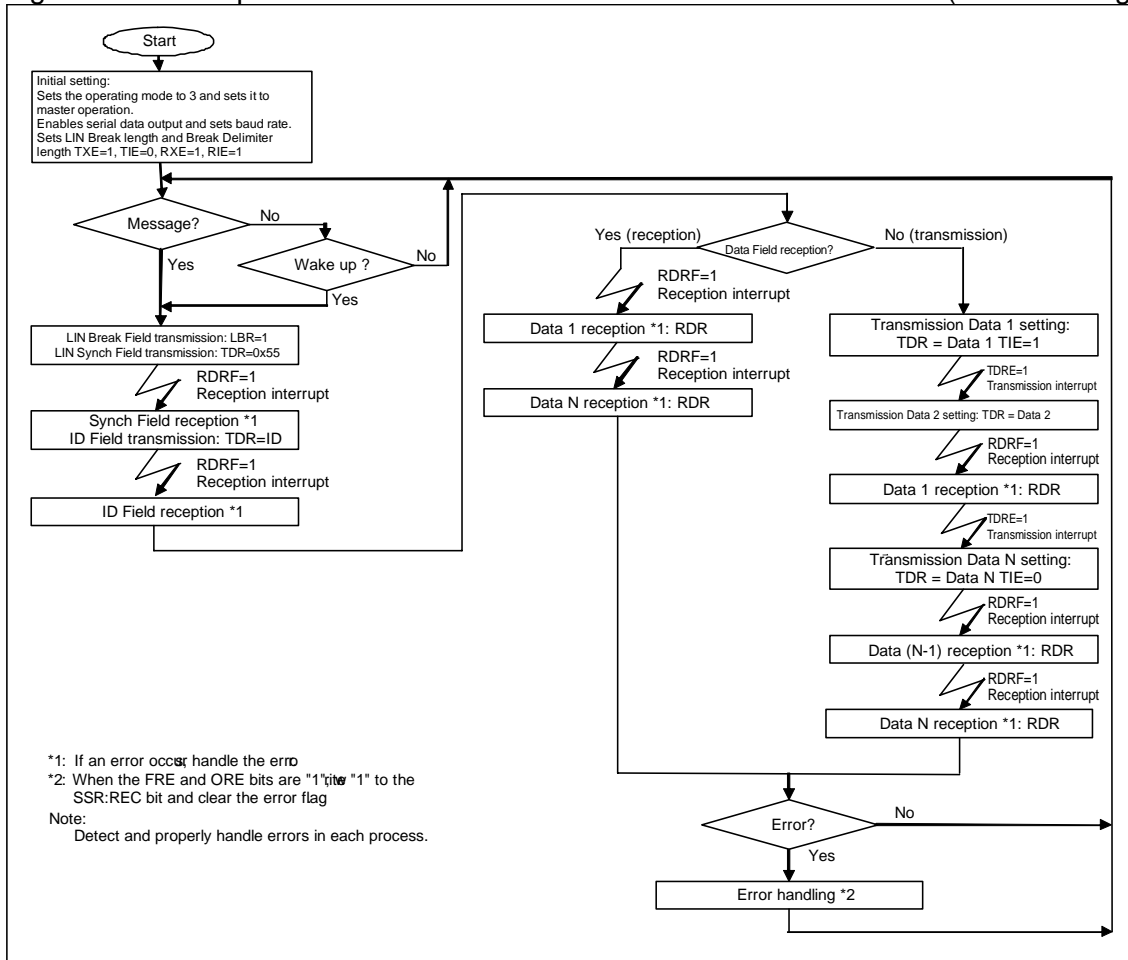


Figure 7-21 Example of a Flowchart in LIN Communication Master Mode (Using FIFO)

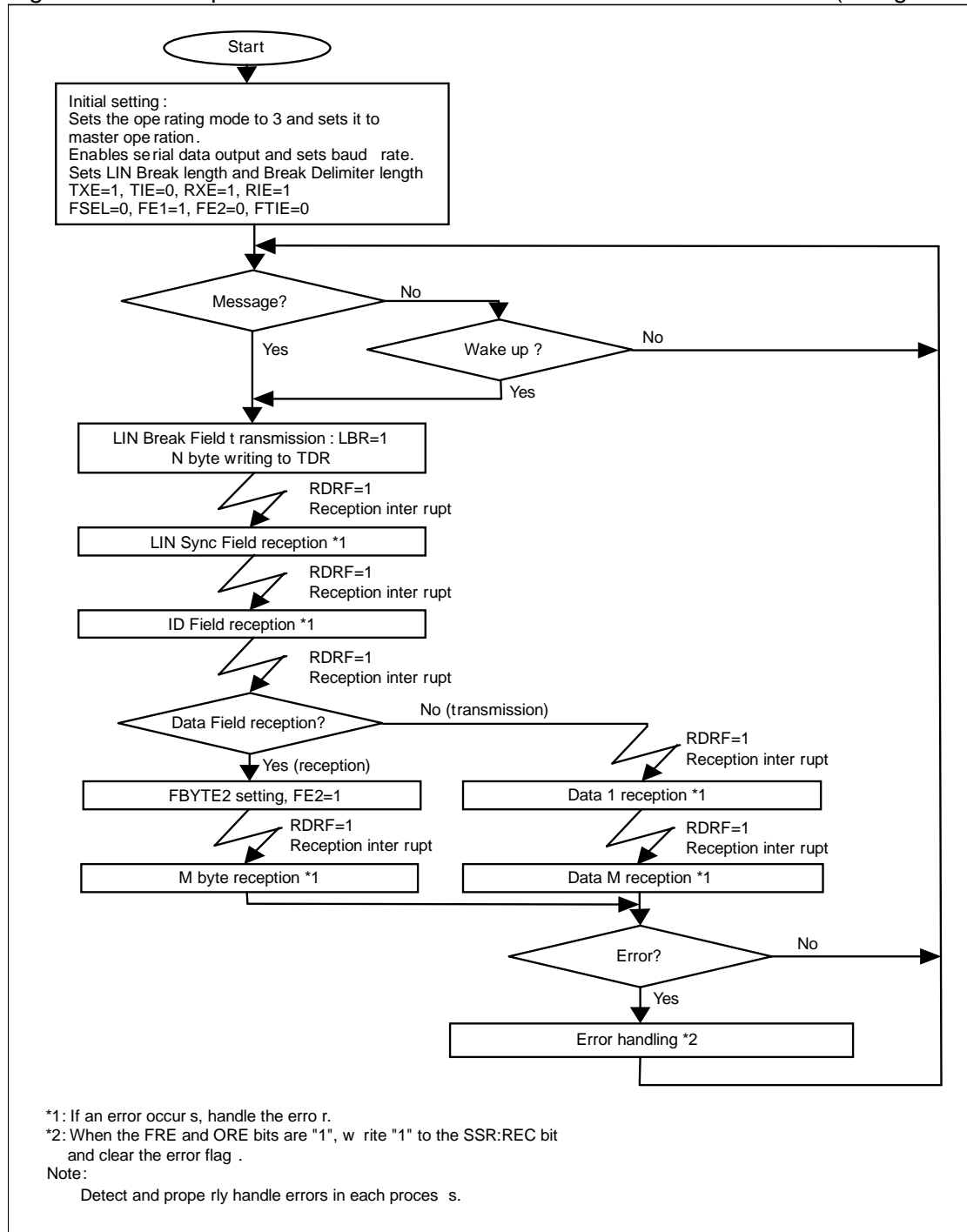


Figure 7-22 Example of a Flowchart in LIN Communication Slave Mode (without Using FIFO)

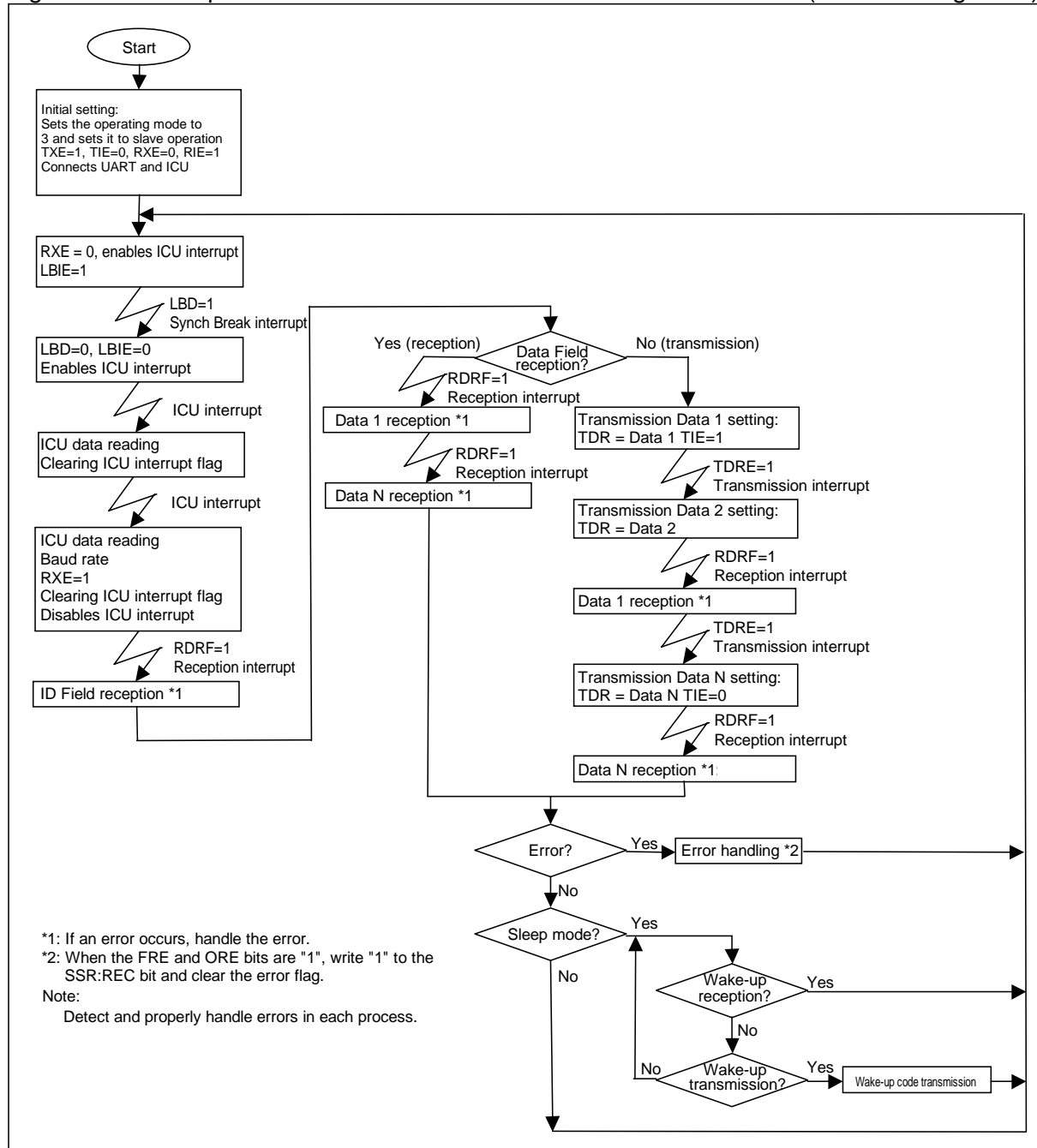
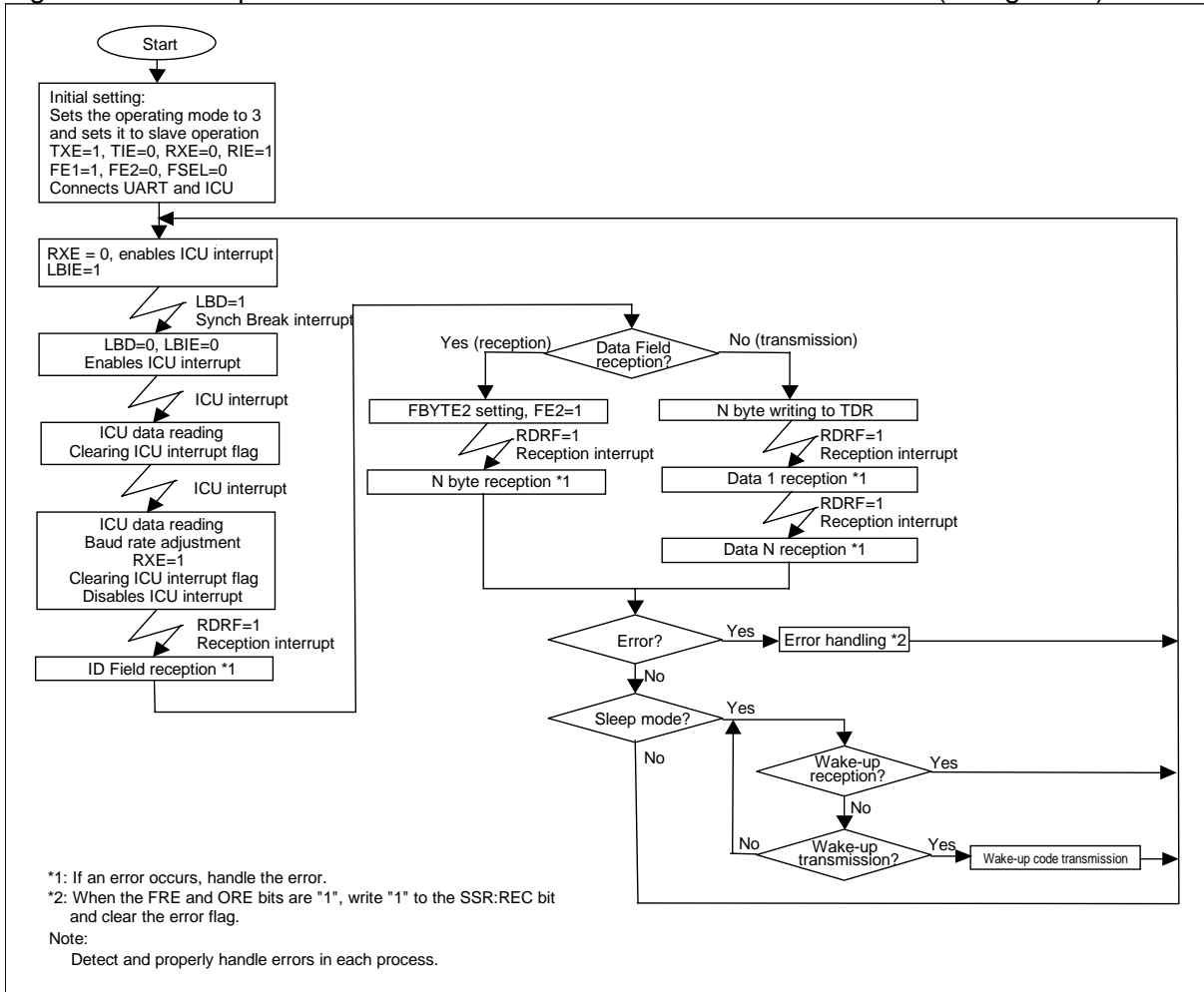


Figure 7-23 Example of a Flowchart in LIN Communication Slave Mode (Using FIFO)



8. Operation of I²C

The operation of I²C is shown.

- 8.1. Interrupts of I²C
- 8.2. Operation for I²C Interface Communication
- 8.3. I²C Master Mode
- 8.4. I²C Slave Mode
- 8.5. Bus Error
- 8.6. Example of I²C Flowchart

8.1. Interrupts of I²C

Interrupts of I²C are shown below.

The I²C interface can generate interrupt requests caused by the following factors:

- After transmission and reception of the first byte/after data transmission and reception
- Stop condition
- Repeated start condition
- FIFO transmission data request
- FIFO reception data completion

■ List of Interrupts of I²C Interface

The following table indicates how I²C interface interrupt control bits relate to interrupt factors.

Table 8-1 I²C Interface Interrupt Control Bits and Interrupt Factors

Interrupt type	Interrupt request flag bit	Flag register	Interrupt factor	Interrupt factor enable bit	Clearing of interrupt request flag
Status	INT	IBCR	After transmission and reception of the first byte *1 (except Master Mode of SSR:DMA=1)	IBCR:INTE	Writing "0" to the interrupt flag bit (IBCR:INT)
			After data transmission and reception *1 (in the case of SSR:DMA=0)		
			Bus error detected		
			Arbitration lost detected		
			Reserved address detected		
			NACK reception		
			Reception FIFO full during slave reception		
SPC	IBSR	Stop condition	IBCR:CNDE	Writing "0" to SPC	
RSC		Repeated start detected		Writing "0" to RSC	
Reception	RDRF	SSR	Reserved address received	SMR:RIE	Reading of receive data (RDR)
			After data reception		
			Reception of as much data as specified by FBYTE		
			Reception idle detected by FBIIE="1"		
	ORE	SSR	Overrun error	Writing of "1" to the reception error flag bit (SSR:REC)	

Interrupt type	Interrupt request flag bit	Flag register	Interrupt factor	Interrupt factor enable bit	Clearing of interrupt request flag	
Transmission	TDRE	SSR	Transmission register is empty	SMR:TIE	Write to the transmit data (TDR), or write "1" to the transmission FIFO operation enable bit when it is "0" and the transmission FIFO has a valid data (retransmission)*2	
			Writing of "1" to the transmission buffer empty flag set bit (SSR:TSET)			
	FDRQ	FCR1	Transmission FIFO is empty	FCR1:FTIE		Writing of "0" to the FIFO transmission data request bit or the transmission FIFO is full
	TBI(SSR:DMA=1)	SSR	No transmission operation	SCR:TBIE		Write to the transmit data (TDR), or write "1" to the transmission FIFO operation enable bit when it is "0" and the transmission FIFO has a valid data (retransmission)*3
Writing of "1" to the transmission buffer empty flag set bit (SSR:TSET)						

*1 : No interrupt occurs if normal data can be transmitted/received and TDRE is "0". The purpose of this is to support DMA transfer. If you want to the INT flag to be set when data is transmitted or received, it is necessary that the TDRE bit will become "1" before the INT flag is set.

*2 : Set the TIE bit to "1" after the TDRE bit is cleared to "0".

*3 : Set the SSR:TBIE bit to "1" after the SSR:TBI bit is cleared to "0".

Note:

The DMA transfer triggered by data reception and a status interrupt is not supported.

8.2. Operation for I²C Interface Communication

The operation for I²C interface communication is shown below.

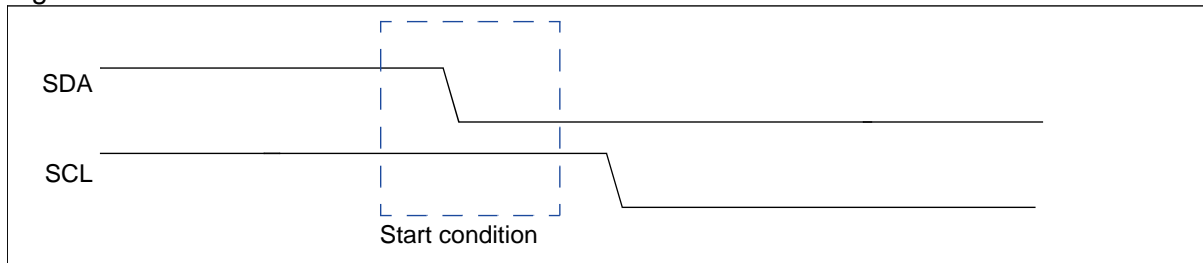
The I²C interface handles communication using two bidirectional bus lines, a serial data line (SDA), and a serial clock line (SCL).

8.2.1. I²C Bus Start Condition

The I²C bus start condition is shown below.

The condition for the I²C bus to be activated is as follows:

Figure 8-1 Start Condition

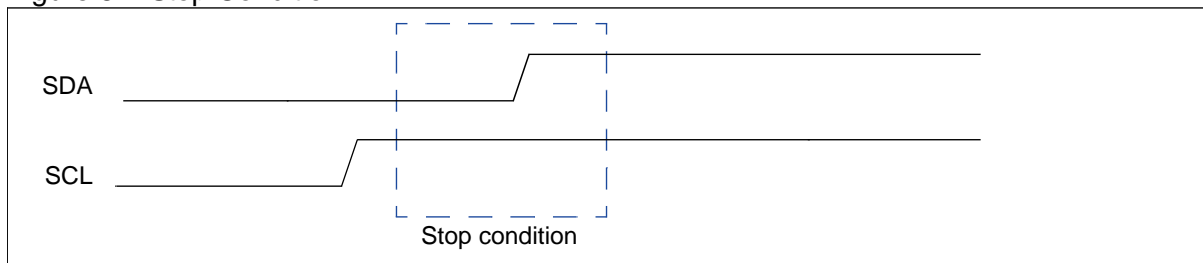


8.2.2. I²C Bus Stop Condition

The I²C Bus Stop Condition is shown below.

The condition for the I²C bus to stop is as follows:

Figure 8-2 Stop Condition

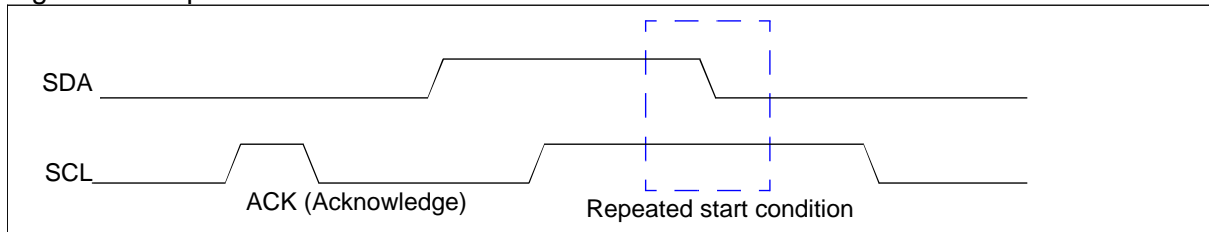


8.2.3. I²C Bus Repeated Start Condition

The I²C Bus repeated start condition is shown below.

The condition for the I²C bus to initiate a repeated start is as follows:

Figure 8-3 Repeated Start Condition



8.2.4. I²C Bus Error

The I²C bus error is shown below.

If a stop condition or (repeated) start condition is detected during data transmission/reception over the I²C bus, it is treated as a bus error.

- Bus Error Occurrence Condition

A bus error sets the IBCR:BER bit to "1" in one of the following conditions:

- Detection of a (repeated) start or stop condition during the transfer of the first byte
- Detection of a (repeated) start or stop condition at the second to ninth (acknowledge) bits of the data

- Bus Error Operation

If the interrupt flag (IBCR:INT) becomes "1" due to transmission or reception, check the IBCR:BER bit. If the IBCR:BER bit is "1", perform error handling. The IBCR:BER bit is cleared by writing "0" to the IBCR:INT bit. A bus error sets the IBCR:INT bit to "1", but does not bring the I²C bus to a wait state by setting SCL to "L".

8.2.5. Baud Rate Generation

The baud Rate Generation is shown below.

The dedicated baud rate generator sets a serial clock frequency.

■ Baud Rate Selection

- Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the internal clock

There are two internal reload counters that correspond to the transmission and reception serial clocks, respectively. The baud rate can be selected by setting a 15-bit reload value in the baud rate generator register (BGR). The reload counter divides the frequency of the internal clock by the specified value.

■ Baud Rate Calculation

The two 15-bit reload counters are set using the baud rate generator register (BGR). The baud rate calculation formulas are as follows:

(1) Reload value

$$V = \phi / b - 1$$

V: Reload value b: Baud rate ϕ : Internal clock (peripheral clock (PCLK)) frequency

However, the specified baud rate may not be generated depending on the rising time of SCL on the I²C bus. Adjust the reload value as required.

(2) Example of calculation

The reload value is as follows if the internal clock (peripheral clock (PCLK)) frequency is 16MHz, the baud rate is to be 400kbps:

Reload value:

$$V = (16 \times 1,000,000) / 400,000 - 1 = 39$$

Therefore, the baud rate is

$$b = (16 \times 1,000,000) / (39 + 1) = 400 \text{ kbps}$$

Notes:

- Write to the baud rate generator (BGR) in 16-bit access mode.
 - Configure the baud rate generator when the EN bit of the ISMK register is "0".
 - Peripheral clock (PCLK) should be set with 8MHz or more in operating mode 4 (I²C mode) and baud rate generator configured in 400kbps or more should not be used.
 - Set the reload value to "0" to stop the reload counter.
-

■ **Reload Values Relating to Baud Rates and Internal Clock Frequencies**

Table 8-2 Reload Values Relating to Baud Rates and Internal Clock Frequencies

Baud rate [bps]	Internal clock (peripheral clock (PCLK))					
	8MHz	10MHz	16MHz	20MHz	24MHz	32MHz
400000	19	24	39	49	59	79
200000	39	49	79	99	119	159
100000	79	99	159	199	239	319

In the number value, SCL raising of the I2C bus is a case of 0s. When SCL rising of the I²C bus is slow, it becomes a baud rate that is slower than the above-mentioned numerical value.

■ **Reload Counter Functions**

The reload counter consists of a 15-bit register for reload values and generates a transmission/reception clock from the internal clock. In addition, the count value of the transmission reload counter can be read via the baud rate generator register (BGR).

■ **Count Start**

When a reload value is written to the baud rate generator register (BGR), the reload counter will start counting.

8.3. I²C Master Mode

I²C master mode is shown below.

In master mode, a start condition is generated on the I²C bus, which then output the clock to the I²C bus. If I²C bus is in the idle state (SCL="H", SDA="H"), the master mode is selected when "1" is set to the MSS bit in the IBCR register, and the ACT bit in the IBCR register becomes "1".

8.3.1. Start Condition Generation

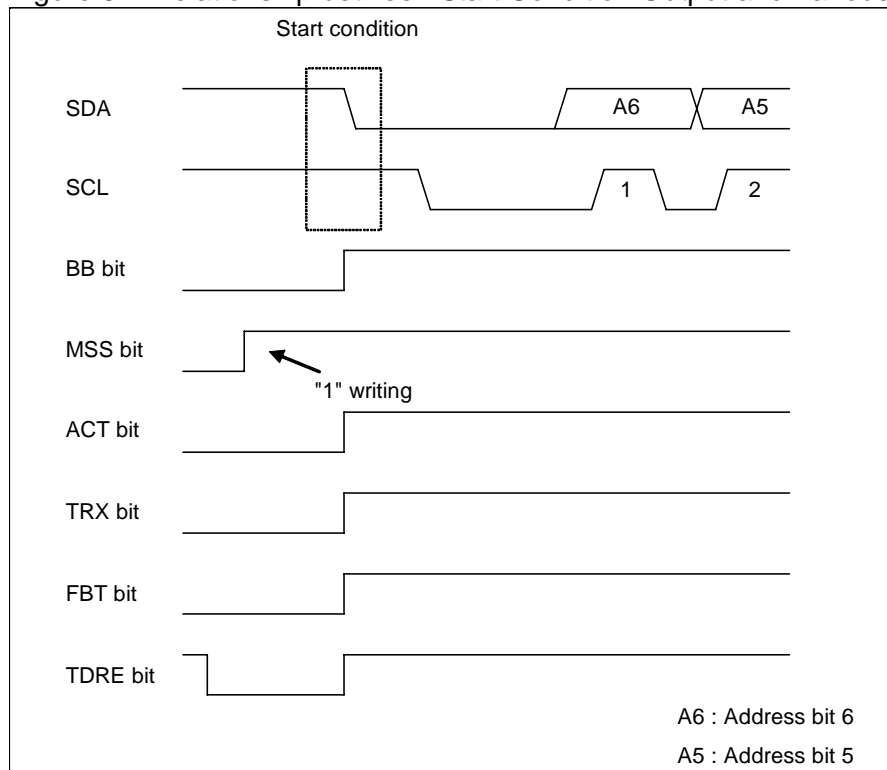
The start condition generation is shown below.

A start condition is output when:

- If SDA="H", SCL="H", EN=1, and BB=0, write "1" to the IBCR:MSS bit

If a start condition is output to I²C bus the IBCR:ACT bit is set to "1". Then, once the start condition is received, the IBSR:BB bit is set to "1", indicating that I²C bus is on the communication.

Figure 8-4 Relationship between Start Condition Output and Various Bits



Note:

The peripheral clock (PCLK) should be set with 8MHz or more in operating mode 4 (I²C mode) and baud rate generator configured in 400kbps or more should not be used.

8.3.2. Slave Address Output

The slave address output is shown below.

When a start condition is output, the data contained in the TDR register is output as the address, beginning with bit7. If FIFO is enabled, the data first written in the TDR register is output. Bit0 is used to indicate the data direction bit (R/W). If the data direction bit (R/W) is "0", the data is in the write direction (from master to slave). Set the address for the TDR register before "1" is written to IBCR:MSS or IBCR:SCC.

Figure 8-5 Address and Data Direction (when FIFO Is Disabled)

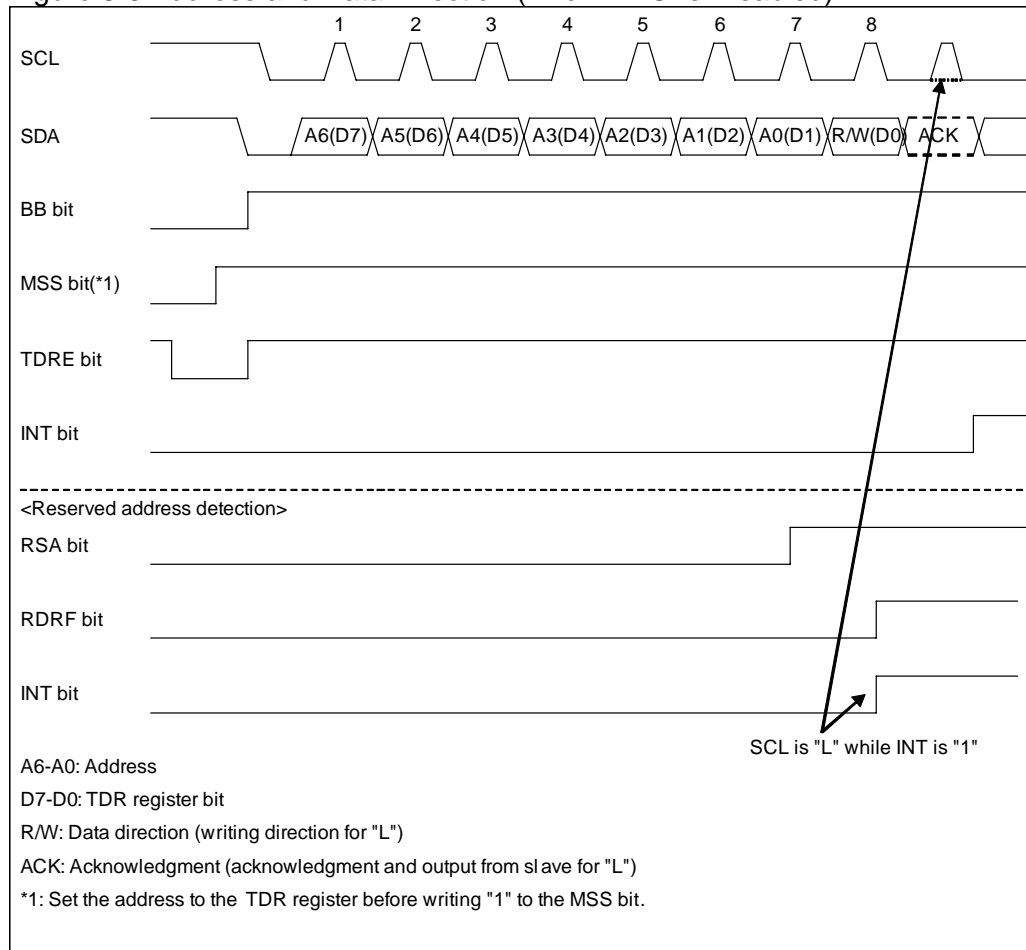
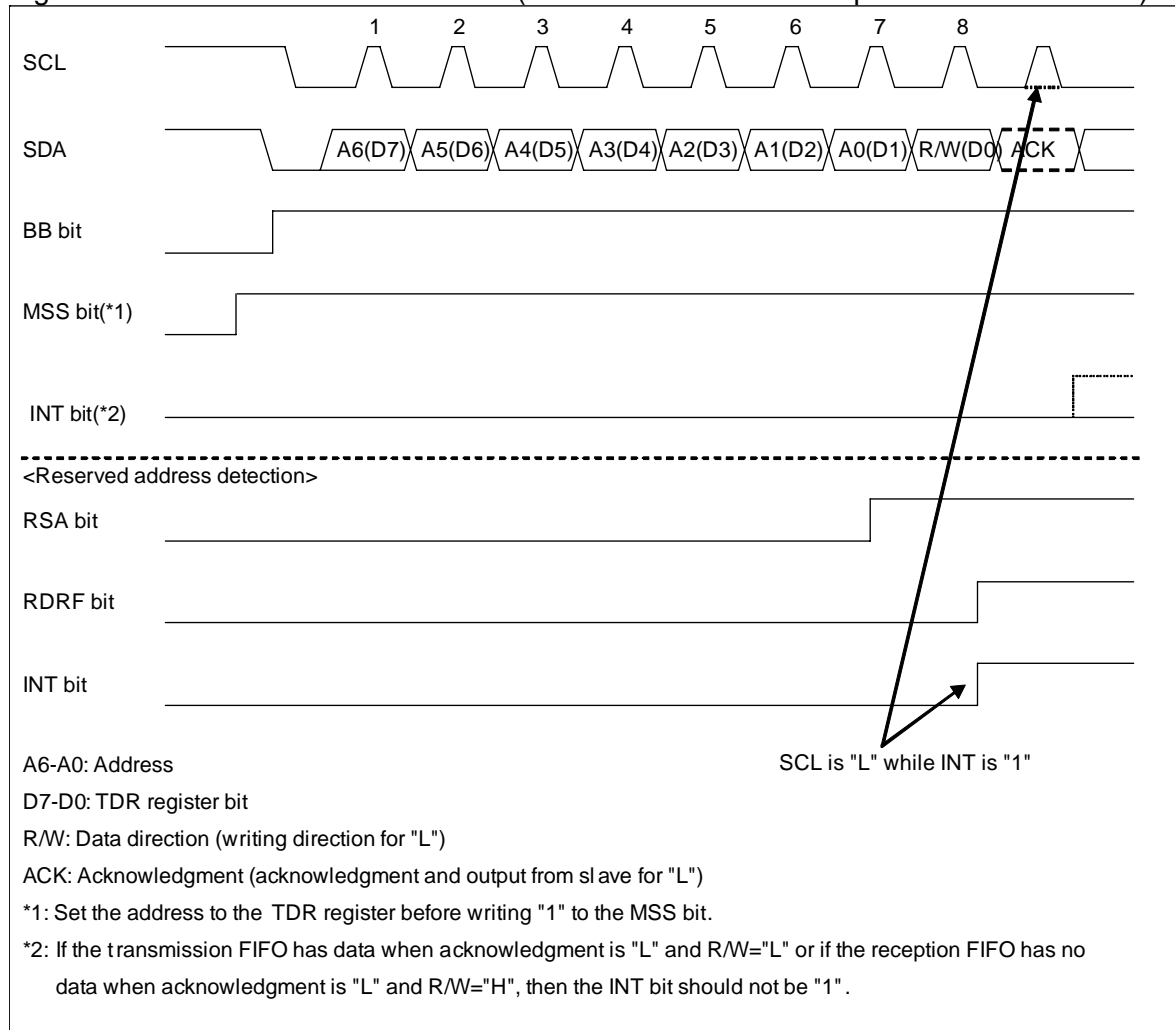


Figure 8-6 Address and Data Direction (when Transmission/Reception FIFO Is Enabled)



8.3.3. Acknowledge Reception by Transmitting First Byte

Acknowledge reception by transmitting first byte is shown below.

When the data direction bit (R/W) is output, the I²C interface receives an acknowledge from the slave. The operation varies depending on whether FIFO is enabled or disabled, as indicated in the following table:

Table 8-3 Operation after Acknowledge Reception when DMA mode is disabled (IBSR:RSA=0, SSR:DMA=0)

Transmission FIFO operation	Reception FIFO operation	Transmission FIFO status	Reception FIFO status	Data direction bit (R/W)	Operation immediately after acknowledge reception	
					Acknowledge is ACK	Acknowledge is NACK
Disabled	Disabled	-	-	0	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
				1		
Disabled	Enabled	-	Without data	0	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
			With data		The IBCR:INT bit is set to "1" and waited.	
			-	1	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	
Enabled	Disabled	-	-	0	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
				1		
Enabled	Enabled	-	Without data	0	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
			With data		The IBCR:INT bit is set to "1" and waited.	
			-	1	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	

Table 8-4 Operation after Acknowledge Reception (when DMA mode is enabled)
(IBSR:RSA=0, SSR:DMA=1)

Transmission FIFO operation	Reception FIFO operation	Transmission FIFO status	Reception FIFO status	Data direction bit (R/W)	Operation immediately after acknowledge reception	
					Acknowledge is ACK	Acknowledge is NACK
Disabled	Disabled	-	-	0	If the SSR:TDRE bit is "1", the SSR:TBI bit is set to "1" and waited. If the SSR:TDRE bit is "0", the SSR:TBI bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
				1		
Disabled	Enabled	-	Without data	0	If the SSR:TDRE bit is "1", the SSR:TBI bit is set to "1" and waited. If the SSR:TDRE bit is "0", the SSR:TBI bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
			With data		The IBCR:INT bit is set to "1" and waited.	
			-	1	If the SSR:TDRE bit is "1", the SSR:TBI bit is set to "1" and waited. If the SSR:TDRE bit is "0", the SSR:TBI bit is held to "0" and not waited.	
Enabled	Disabled	-	-	0	If the SSR:TDRE bit is "1", the SSR:TBI bit is set to "1" and waited. If the SSR:TDRE bit is "0", the SSR:TBI bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
				1		
Enabled	Enabled	-	Without data	0	If the SSR:TDRE bit is "1", the SSR:TBI bit is set to "1" and waited. If the SSR:TDRE bit is "0", the SSR:TBI bit is held to "0" and not waited.	The IBCR:INT bit is set to "1" and waited.
			With data		The IBCR:INT bit is set to "1" and waited.	
			-	1	If the SSR:TDRE bit is "1", the SSR:TBI bit is set to "1" and waited. If the SSR:TDRE bit is "0", the SSR:TBI bit is held to "0" and not waited.	

■ **FIFO Disabled (Both Transmission and Reception FIFOs Disabled, when DMA mode is disabled (SSR:DMA=0))**

- If the IBSR:RSA bit is "0", the interrupt flag (IBCR:INT) is set to "1" and SCL is held to "L" and waited if the SSR:TDRE bit is "1" after acknowledge reception. To release the wait, write "0" to the interrupt flag. If the SSR:TDRE bit is "0", the reception of ACK causes clock generation on SCL without setting the interrupt flag to "1".
- If the IBSR:RSA bit is "1", the interrupt flag (IBCR:INT) is set to "1" and SCL is held to "L" and waited after reserved address reception (before acknowledge). After the RDR register is read, the interrupt flag becomes "0" to release the wait when you set the IBCR:ACKE bit and the transmission data, and write "0" to the interrupt flag.
- The received acknowledge is set to the IBSR:RACK bit. The IBSR:RACK bit is checked during wait state. If it is NACK, "0" will be written to the IBCR:MSS bit or "1" is written to the IBCR:SCC bit to generate a stop condition or a repeated start condition. At this time, the IBCR:INT bit will be automatically cleared to "0".

■ **FIFO Enabling (when DMA mode is disabled (SSR:DMA=0))**

- Before setting the IBCR:MSS bit to "1", it is necessary to configure the following FIFO settings:
 - For transmission to the slave (data direction bit =0), set data including the slave address, etc in the transmission FIFO.
 - For data reception from the slave (data direction bit =1), configure the FIFO byte count register to specify the number of bytes to be received, write to the transmit data register using the slave address, data direction bit, and number of dummy data to be received.
- If the IBSR:RSA bit is "0", the master, after receiving ACK as an acknowledge, does not set the interrupt flag (IBCR:INT) to "1", but transmits/receives data according to the data direction bit (not waited). If NACK is received, the interrupt flag (IBCR:INT) is set to "1" and SCL is held to "L" and waited.
- The received acknowledge is set to the IBSR:RACK bit. The IBSR:RACK bit is checked during wait state. If it is NACK, "0" is written to the IBCR:MSS bit or "1" is written to the IBCR:SCC bit to generate a stop condition or a repeated start condition. At this time, the IBCR:INT bit is automatically cleared to "0".

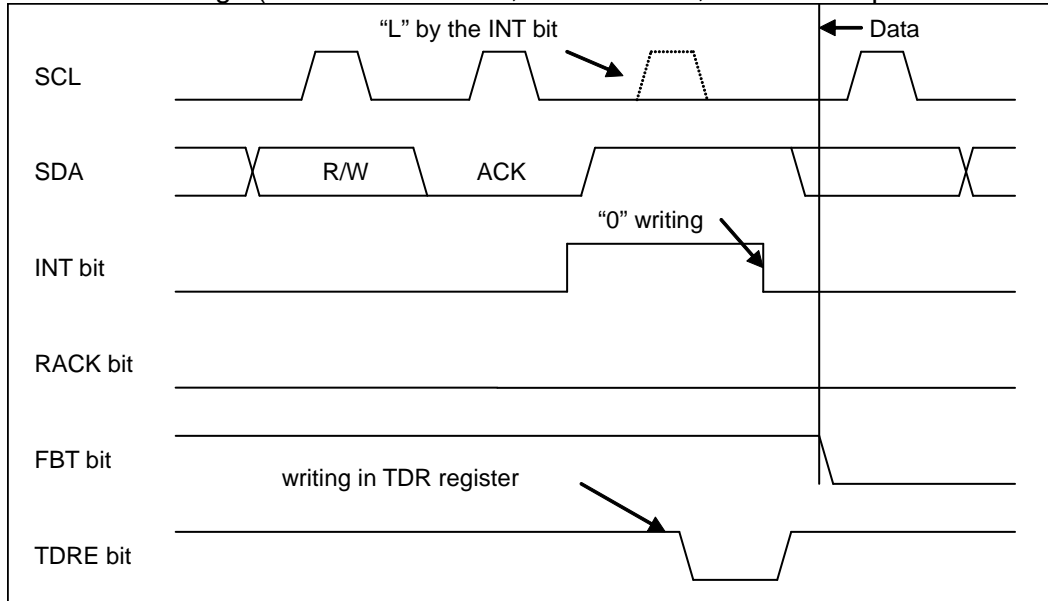
■ **FIFO Disabled (Both Transmission and Reception FIFOs Disabled, When DMA mode is enabled (SSR:DMA=1))**

- If the IBSR:RSA bit is "0", the transmission bus idle flag (SSR:TBI) is set to "1" and SCL is held to "L" and waited if the SSR:TDRE bit is "1" after acknowledge reception. If the transmission data is written to TDR register, the transmission bus idle flag becomes "0" and wait is released. If the SSR:TDRE bit is "0", the reception of ACK causes clock generation on SCL without setting the transmission bus idle flag (SSR:TBI) to "1".
- If the IBSR:RSA bit is "1", the interrupt flag (IBCR:INT) is set to "1" and SCL is held to "L" and waited after reserved address reception (before acknowledge). After the RDR register is read, the interrupt flag becomes "0" to release the wait when you set the IBCR:ACKE bit and the transmission data, and write "0" to the interrupt flag.
- The received acknowledge is set to the IBSR:RACK bit. The IBSR:RACK bit is checked during wait state. If it is NACK, "0" will be written to the IBCR:MSS bit or "1" is written to the IBCR:SCC bit to generate a stop condition or a repeated start condition. At this time, the IBCR:INT bit will be automatically cleared to "0".

■ **FIFO Enabling (When DMA mode is enabled (SSR:DMA=1))**

- Before setting the IBCR:MSS bit to "1", it is necessary to configure the following FIFO settings:
 - For transmission to the slave (data direction bit =0), set data including the slave address, etc in the transmission FIFO.
 - For data reception from the slave (data direction bit =1), configure the FIFO byte count register to specify the number of bytes to be received, write to the transmit data register using the slave address, data direction bit, and number of dummy data to be received.
- If the IBCR:RSA bit is "0", after receiving ACK as an acknowledge, the interrupt flag (IBCR:INT) is not set to "1", but transmits/receives data according to the data direction bit (not waited). If NACK is received, the interrupt flag (IBCR:INT) is set to "1" and SCL is held to "L" and waited.
- The received acknowledge is set to the IBSR:RACK bit. The IBSR:RACK bit is checked during wait state. If it is NACK, "0" is written to the IBCR:MSS bit or "1" is written to the IBCR:SCC bit to generate a stop condition or a repeated start condition. At this time, the IBCR:INT bit is automatically cleared to "0".

Figure 8-7 Acknowledge (If FIFO Is Disabled, IBSR:RSA=0, and the Response Is ACK)



Waiting to the address is as follows.

- After receiving the acknowledge when the IBSR:RSA bit is "0"
- Before receiving the acknowledge when the IBSR:RSA bit is "1"

It does not depend on the setting of IBCR:WSEL.

Figure 8-8 Acknowledge (If FIFO Is Disabled, IBSR:RSA=0, and the Response Is NACK)

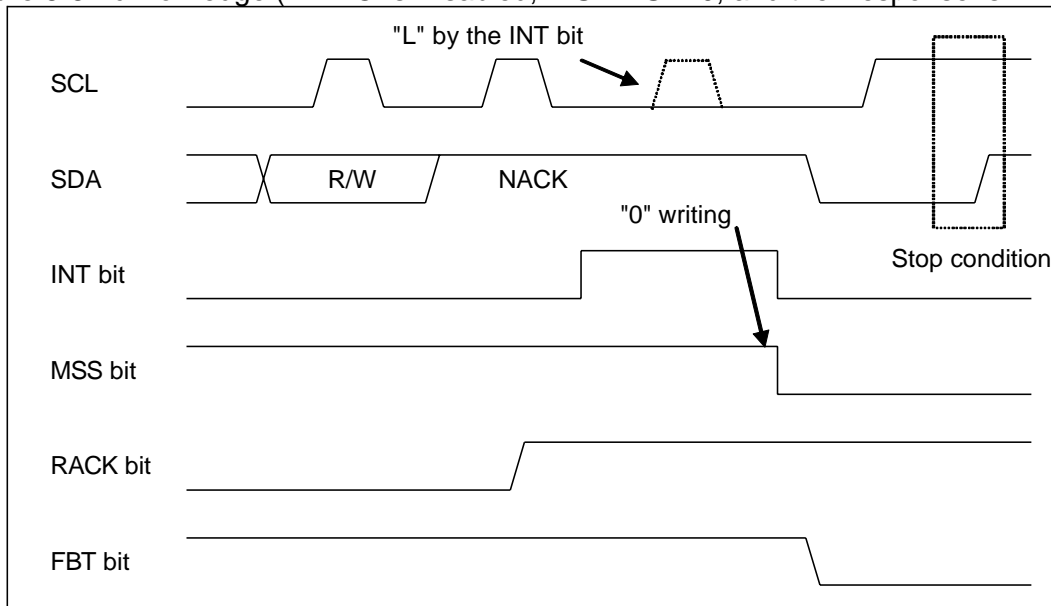


Figure 8-9 Acknowledge (If FIFO Is Disabled, IBSR:RSA=1, and the Response Is ACK)

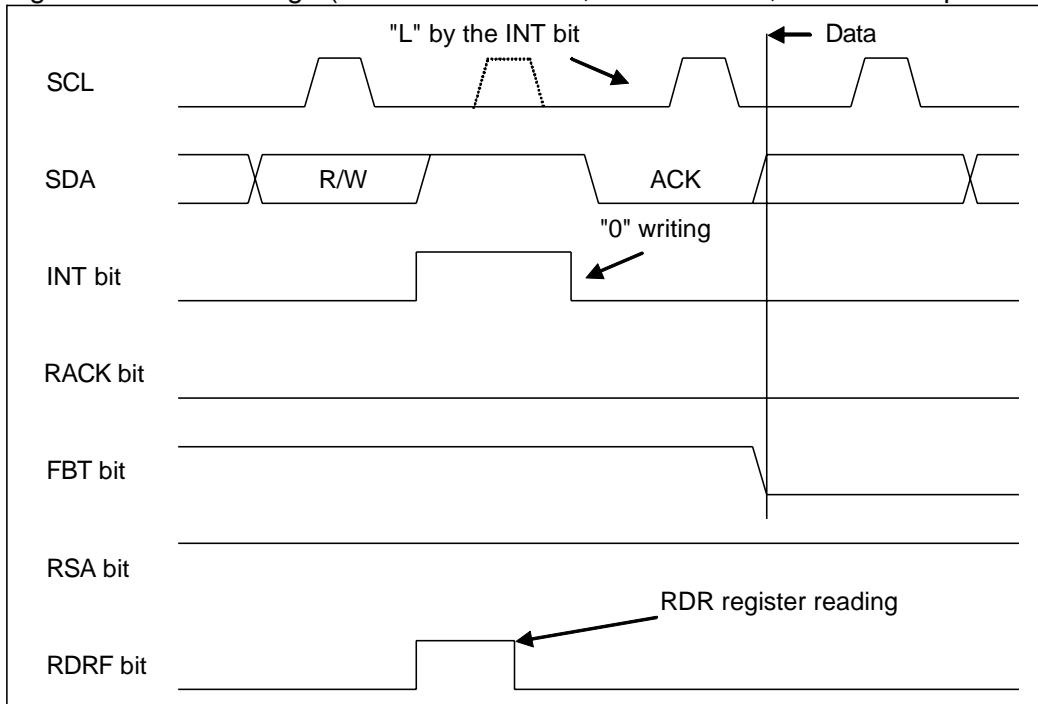


Figure 8-10 Acknowledge (If FIFO Is Disabled, IBSR:RSA=1, and the Response Is NACK)

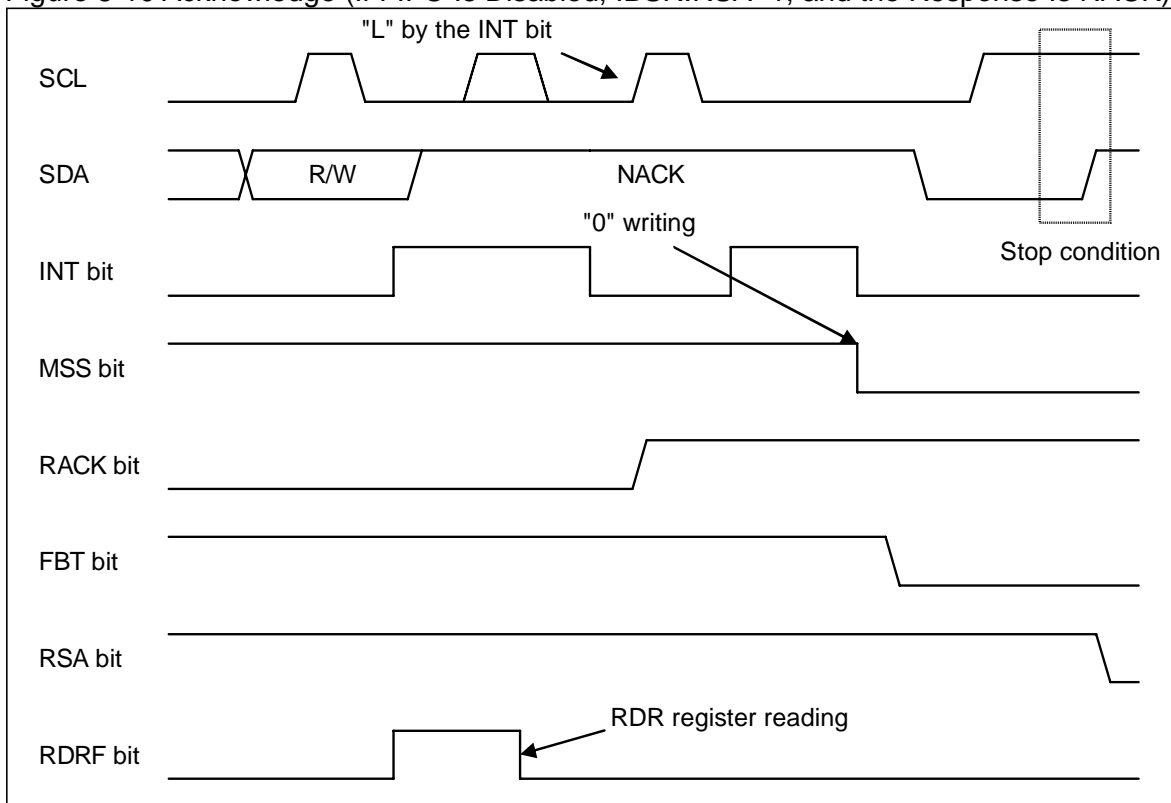
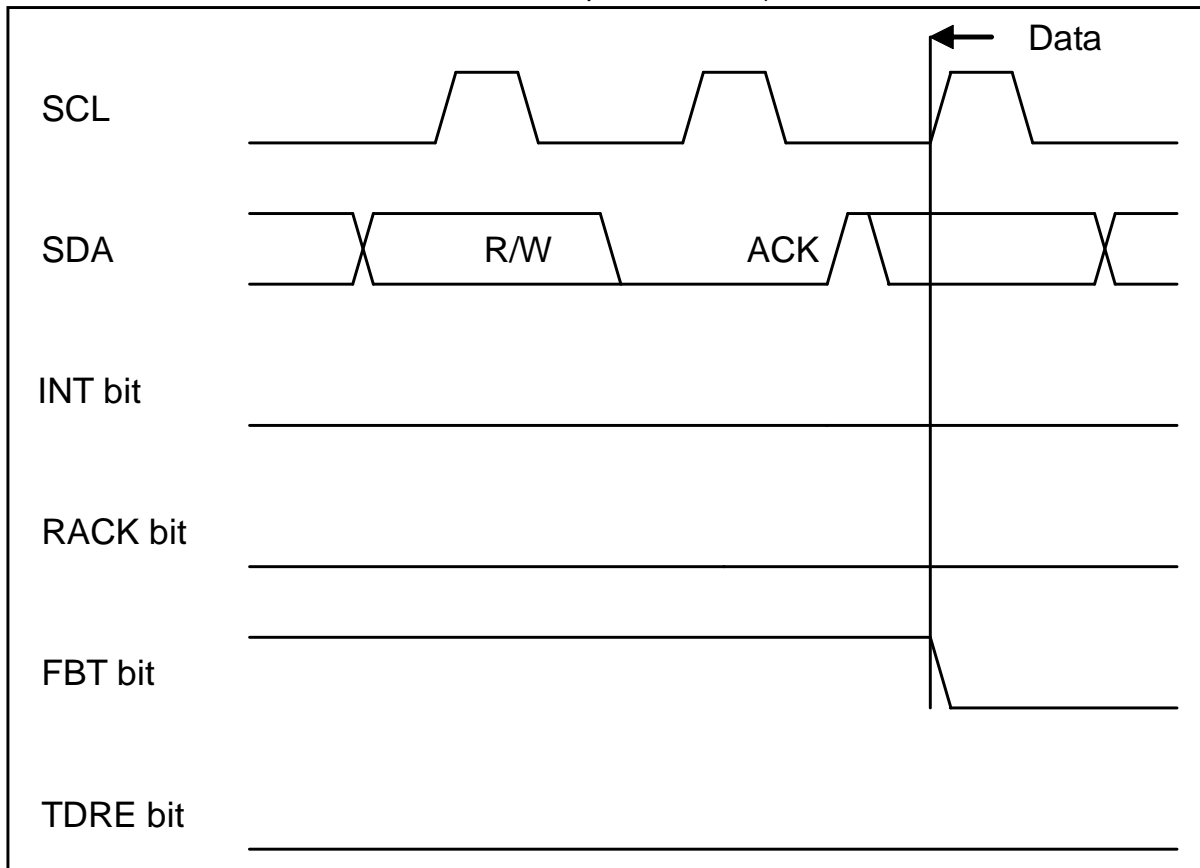


Figure 8-11 Acknowledge (If FIFO Is Enabled, Transmission FIFO Data Exists, No Reception FIFO Data Exists, IBSR:RSA=0, and the Response Is ACK)



8.3.4. Data Transmission by Master

Data transmission by master is shown below.

If the data direction bit (R/W) is "0", data is sent from the master. The slave responds with ACK or NACK each time one byte is transmitted. The location where a wait condition develops varies depending on the IBCR:WSEL bit setting as follows:

Table 8-5 IBCR:WSEL Bit at the Time of Master Data Transmission (When DMA mode is disabled(SSR:DMA=0))

WSEL	Operation
0	In the 2nd or subsequent byte, the interrupt flag bit (IBCR:INT) is set to "1" and SCL is set to "L" to go into the wait state when the SSR:TDRE bit is "1" or after the acknowledgment on the arbitration lost detection. If FIFO is enabled, the master, after receiving acknowledge, will set the post-acknowledge interrupt flag (IBCR:INT) to "1" to wait, when it detects an arbitration lost or finds no valid data in the transmit data register (SSR:TDRE=1).
1	In the 2nd or subsequent byte, the interrupt flag bit (IBCR:INT) will be set to "1" and SCL will be set to "L" to go into the wait state when the SSR:TDRE bit is "1" or after the master transmitted 1 byte data on the arbitration lost detection. If FIFO is enabled, the master will transmit data, and then set the interrupt flag (IBCR:INT) to "1" and wait, when it detects arbitration lost or finds no valid data in the transmit data register (SSR:TDRE=1).

Table 8-6 IBCR:WSEL Bit at the Time of Master Data Transmission (When DMA mode is enabled(SSR:DMA=1))

WSEL	Operation
0	In the 2nd or subsequent byte, after the acknowledge by the SSR:TDRE bit to "1", transmission bus idle flag (SSR:TBI) makes "1" and SCL "L" into the wait state. Moreover, transmission bus idle flag (SSR:TBI) is made "1" after the acknowledge at (SSR:TDRE=1) of lost of effective data for the transmission data register after the acknowledge at the FIFO enabled and it puts it into the wait state .
1	In the 2nd or subsequent byte, after the master transmits the data of one byte by the SSR:TDRE bit to "1", transmission bus idle flag (SSR:TBI) makes "1" and SCL "L" into the wait state. Moreover, transmission bus idle flag (SSR:TBI) is made "1" after the master transmits the data of one byte at (SSR:TDRE=1) of lost of effective data for the transmission data register after the acknowledge at the FIFO permission and it puts it into the wait state.

However, the master sets the interrupt flag (IBCR:INT) after receiving acknowledge regardless of the IBCR:WSEL setting in one of the following cases:

- If NACK is received except for stop condition setting (IBCR:MSS=0, ACT=1):
The following gives an example of procedure used to transmit data to the slave:
- Data transmission to slave of when DMA mode is disabled (SSR:DMA=0)
 - (1) Transmission to a destination that is not at the reserved address
If transmission FIFO is disabled:
 - (1) Set the slave address (including the data direction bit) in the TDR register, and set the IBCR: MSS bit to "1".
 - (2) Transmit the slave address and receive ACK. The interrupt flag (IBCR:INT) becomes "1".

- (3) Write transmission data in the TDR register.
- (4) Update the IBCR:WSEL bit and set the interrupt flag (IBCR:INT) to "0" to release the I²C bus from waiting state.
- (5) Put the I²C bus in a wait by setting the interrupt flag to "1", after receiving an acknowledge upon the transmission of one byte when WSEL is set to "0", or immediately after one byte has been transmitted when IBCR:WSEL is set to "1". Repeat steps (3) to (5) until the specified number of data have been transmitted. However, if NACK is received after the bus is released from waiting state when IBCR:WSEL=1, another interrupt will occur after acknowledge reception to make the bus wait.
- (6) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.

If transmission FIFO is enabled:

- (1) Write the slave address (including the data direction bit) and transmission data in the TDR register.
- (2) Set the IBCR:WSEL bit and write "1" to the IBCR:MSS bit.
- (3) If NACK is received during transmission, set the interrupt flag (IBCR:INT) to "1" immediately to make the I²C bus wait. If all responses received are ACK, set the interrupt flag to "1" after transmitting the last byte, according to the IBCR:WSEL setting to make the I²C bus wait.
- (4) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.

(2) Transmission to the reserved address

If transmission FIFO is disabled:

- (1) Set the reserved address as the slave address in the TDR register and set the IBCR:MSS bit to "1".
- (2) Transmit the slave address. The interrupt flag (IBCR:INT) becomes "1".
- (3) Read the RDR register and confirm the reserved address.(*1)
- (4) Write transmission data in the TDR register.
- (5) Update the IBCR:WSEL bit and set the interrupt flag (IBCR:INT) to "0" to release the I²C bus from waiting state.
- (6) Put the I²C bus in a wait by setting the interrupt flag to "1", after receiving an acknowledge upon the transmission of one byte when IBCR:WSEL is set to "0", or immediately after one byte has been transmitted when IBCR:WSEL is set to "1". Repeat steps (4) to (6) until the specified number of data have been transmitted. However, if NACK is received after the bus is released from waiting state when IBCR:WSEL=1, another interrupt will occur after acknowledge reception to make the bus wait.
- (7) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.

If transmission FIFO is enabled:

- (1) Set the reserved address as the slave address in the TDR register and set the IBCR:MSS bit to "1".
- (2) Transmit the slave address. The interrupt flag (IBCR:INT) becomes "1".
- (3) Read the RDR register and confirm the reserved address.(*1)
- (4) Write all transmission data in the TDR register (until the transmission FIFO becomes full if it can).
- (5) If NACK is received during transmission, set the interrupt flag (IBCR:INT) to "1" immediately to make the I²C bus wait. If all responses received are ACK, set the interrupt flag to "1" after transmitting the last byte, according to the IBCR:WSEL setting to make the I²C bus wait.
- (6) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.

*1: If the reserved address is a general-call address in a multi-master configuration or if an arbitration lost is detected and the device may work as the slave, it is necessary to set the IBCR:ACKE bit and IBCR:WSEL bit to "1" and determine whether the device is to work as the master or slave for subsequent data.

- Data transmission to slave of when DMA mode is enabled (SSR:DMA=1)

(1) Transmission to a destination that is not at the reserved address

If transmission FIFO is disabled:

- (1) Slave Address (The data direction bit is included) is set in the TDR register and set the IBCR:MSS bit to "1".
- (2) Transmit the slave address and receive ACK. The transmission bus idle flag (SSR:TBI) becomes "1".
- (3) The data transmitted to the TDR register is written and release the I²C bus from waiting state.
- (4) Put the I²C bus in a wait by setting the transmission bus idle flag (SSR:TBI) to "1", after receiving an acknowledge upon the transmission of one byte when WSEL is set to "0", or immediately after one byte has been transmitted when IBCR:WSEL is set to "1".
- (5) The data transmitted to the TDR register is written and release the I²C bus from waiting state.
- (6) Put the I²C bus in a wait by setting the transmission bus idle flag (SSR:TBI) to "1", after receiving an acknowledge upon the transmission of one byte when WSEL is set to "0", or immediately after one byte has been transmitted when IBCR:WSEL is set to "1". Repeat steps (6) to (7) until the specified number of data have been transmitted. However, if NACK is received after the bus is released from waiting state when IBCR:WSEL=1, interrupt flag (IBCR:INT) is set to "1" after acknowledge reception to make the bus wait.
- (7) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.(*2)

If transmission FIFO is enabled:

- (1) Slave Address (The data direction bit is included) and the transmission data is written to the TDR register.
- (2) Update the IBCR:WSEL bit and set the IBCR:MSS bit to "1".
- (3) If NACK is received during transmission, set the interrupt flag (IBCR:INT) to "1" immediately to make the I²C bus wait. If all responses received are ACK, set the transmission bus idle flag (SSR:TBI) to "1" after transmitting the last byte, according to the IBCR:WSEL setting to make the I²C bus wait.
- (4) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.(*2)

(2) Transmission to the reserved address

If transmission FIFO is disabled:

- (1) Set the reserved address as the slave address in the TDR register and set the IBCR:MSS bit to "1".
- (2) Transmit the slave address. The interrupt flag (IBCR:INT) becomes "1".
- (3) Read the RDR register and confirm the reserved address.(*1)
- (4) Write transmission data in the TDR register.
- (5) Update the IBCR:WSEL bit and set the interrupt flag (IBCR:INT) to "0" to release the I²C bus from waiting state.
- (6) Put the I²C bus in a wait by setting the interrupt flag to "1", after receiving an acknowledge upon the transmission of one byte when IBCR:WSEL is set to "0", or immediately after one byte has been transmitted when IBCR:WSEL is set to "1".

- (7) The data transmitted to the TDR register is written and release the I²C bus from waiting state.
- (8) When the IBCR:WSEL bit is 0 after one byte is transmitted, acknowledge reception also when the IBCR:WSEL=1 is 1, one byte is transmitted and the transmission bus idle flag (SSR:TBI) is set as "1" and I²C bus is wait. Repeat steps (7) to (8) until the specified number of data have been transmitted. However, if NACK is received after the bus is released from waiting state when IBCR:WSEL=1, another interrupt will occur after acknowledge reception to make the bus wait.
- (9) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.(*2)

If transmission FIFO is enabled:

- (1) Set the reserved address as the slave address in the TDR register and set the IBCR:MSS bit to "1".
- (2) Transmit the slave address. The interrupt flag (IBCR:INT) becomes "1".
- (3) Read the RDR register and confirm the reserved address.(*1)
- (4) Write all transmission data in the TDR register (until the transmission FIFO becomes full if it can).
- (5) If NACK is received during transmission, set the interrupt flag (IBCR:INT) to "1" immediately to make the I²C bus wait. If all responses received are ACK, set the interrupt flag (IBCR:INT) to "1" after transmitting the last byte, according to the IBCR:WSEL setting to make the I²C bus wait.
- (6) Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" to generate a stop condition or a repeated start condition.(*2)

*1 : If the reserved address is a general-call address in a multi-master configuration or if an arbitration lost is detected and the device may work as the slave, it is necessary to set the IBCR:ACKE bit and IBCR:WSEL bit to "1" and determine whether the device is to work as the master or slave for subsequent data.

*2: The DMA mode must write the slave address in TDR after confirming the IBCR:INT bit is set in "1" after "1" is written in the IBCR:INT bit, and set "1" to the IBCR:SCC bit when the SSR:TBI bit issues the repetition start condition by permission (SSR:DMA=1) when it is "1" and the IBCR:INT bit is "0".

Notes:

- If the 7-bit slave address detection is enabled (ISBA:SAEN=1), you cannot specify a 7-bit slave address in the master mode.
- If you need to change the IBCR register during data sending or receiving, change it only when the interrupt flag (IBCR:INT) is "1".
- If you change the IBCR:WSEL bit, it is used interrupt flag of following data (IBCR:INT) and generation condition of the transmission bus idle flag (SSR:TBI) when the DMA mode is enabled (DMA=1).
- In DMA mode prohibition (DMA=0), if transmission data is written to the TDR register when SSR:TDRE is "1" during data transmission, the detection of an ACK response triggers the transmission of the written data without setting the interrupt flag (IBCR:INT) to "1".
- In DMA mode prohibition (DMA=0), if transmission data is written to the TDR register when TDRE is "1" during data reception, also there is an ACK response, the interrupt flag (IBCR:INT) is not set as "1", but only sets RDRF to "1" (if reception FIFO is enabled and as much data as specified by the FBYTE register is received).
- In DMA mode permission, if transmission data is written to the TDR register when TDRE is "1" during data reception, also there is an ACK response, the transmission bus idle flag(SSR:TBI) is not set as "1", but only keep written data.
- In DMA mode permission, if transmission data is written to the TDR register when TDRE is "1" during data reception, also there is an ACK response, the transmission bus idle flag(SSR:TBI) is not set as "1", but only sets RDRF to "1" (if reception FIFO is enabled and as much data as specified by the FBYTE register is received).

Figure 8-12 Master Transmission Interrupt (1)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=0 and IBSR:RSA=0)

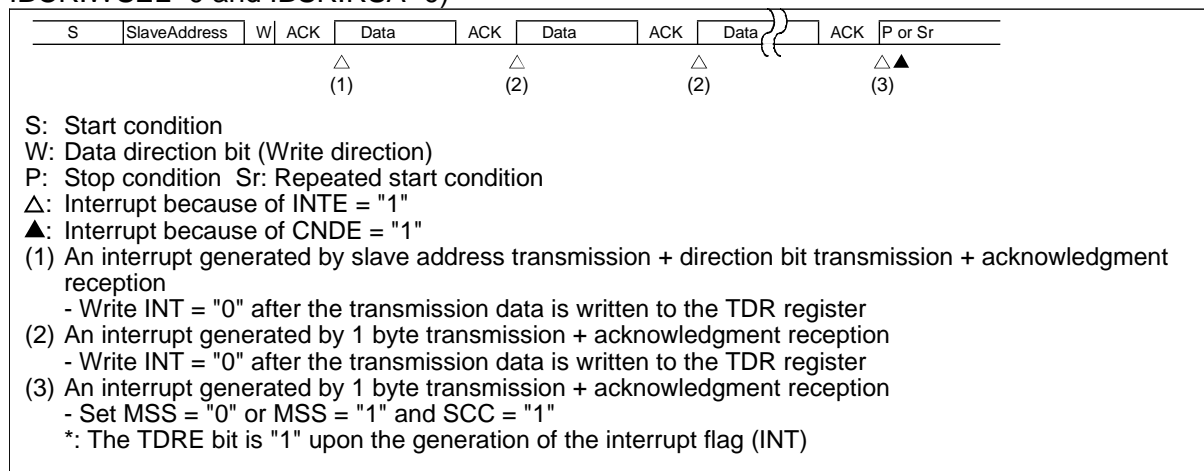


Figure 8-13 Master Transmission Interrupt (2)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0, ACK Response)

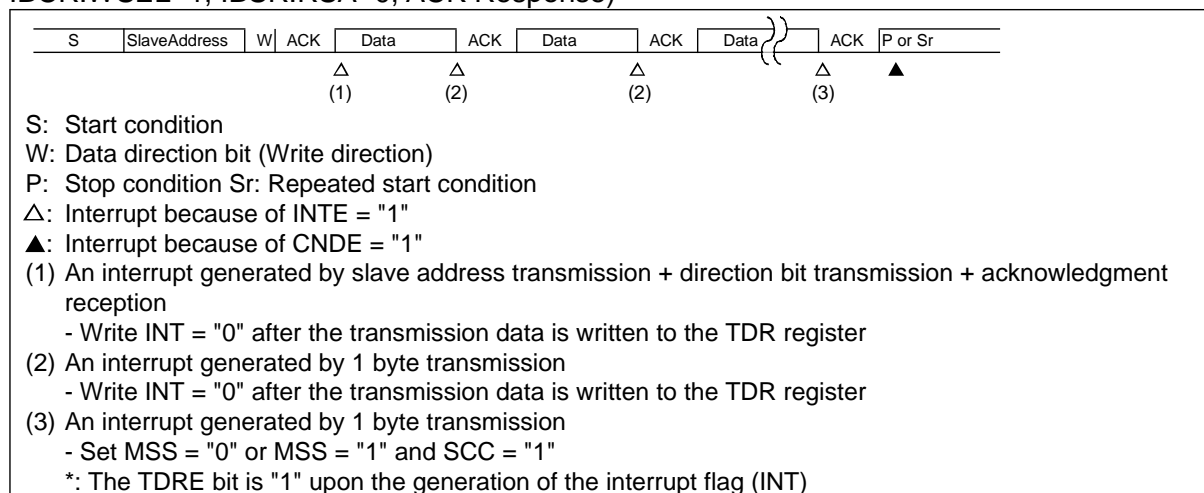


Figure 8-14 Master Transmission Interrupt (3)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0, NACK Response)

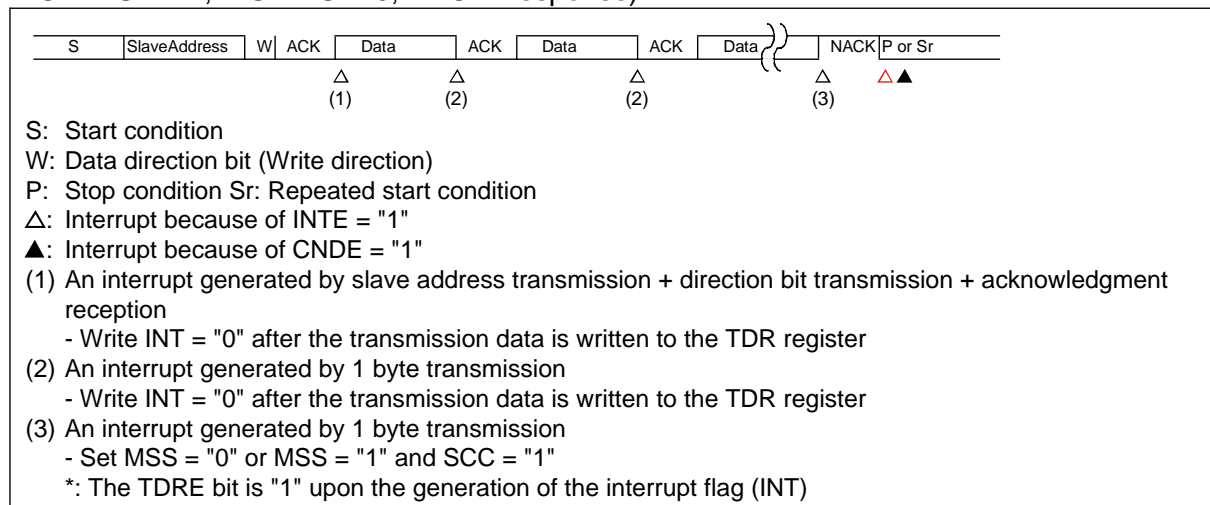


Figure 8-15 Master Transmission Interrupt (4)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0, Intermediate NACK Response)

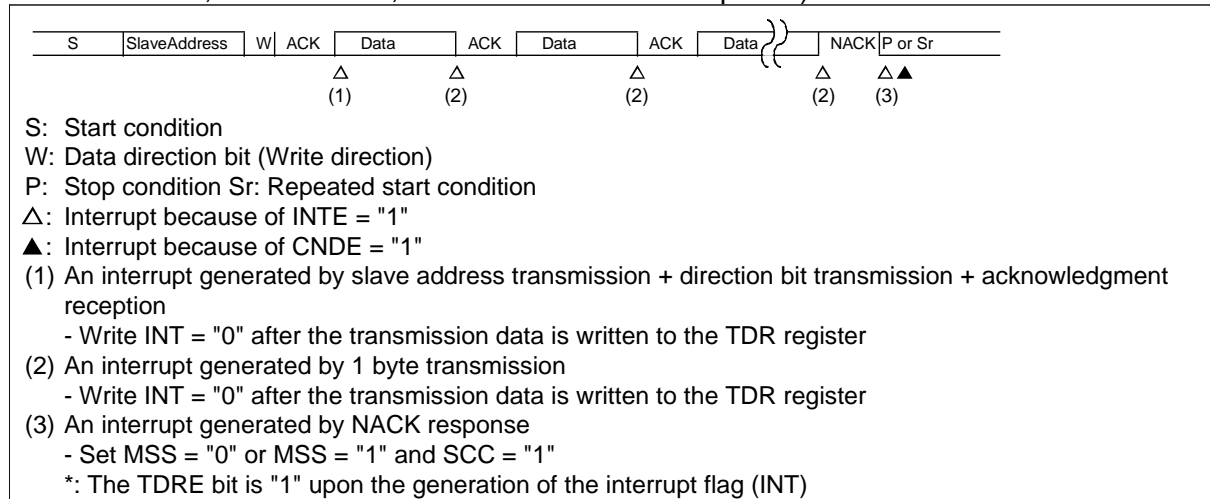


Figure 8-16 Master Transmission Interrupt (5)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1->0, IBSR:RSA=0, ACK Response)

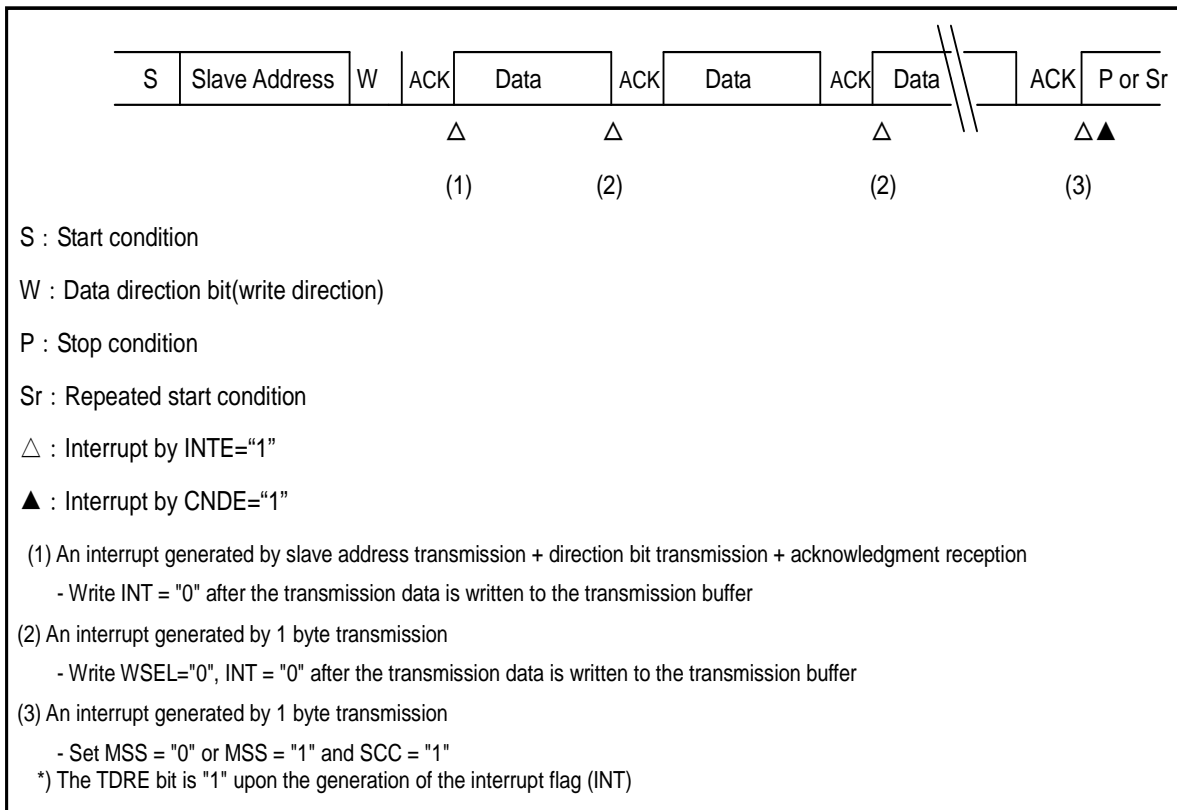


Figure 8-17 Master Transmission Interrupt (6)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=0, IBSR:RSA=1)

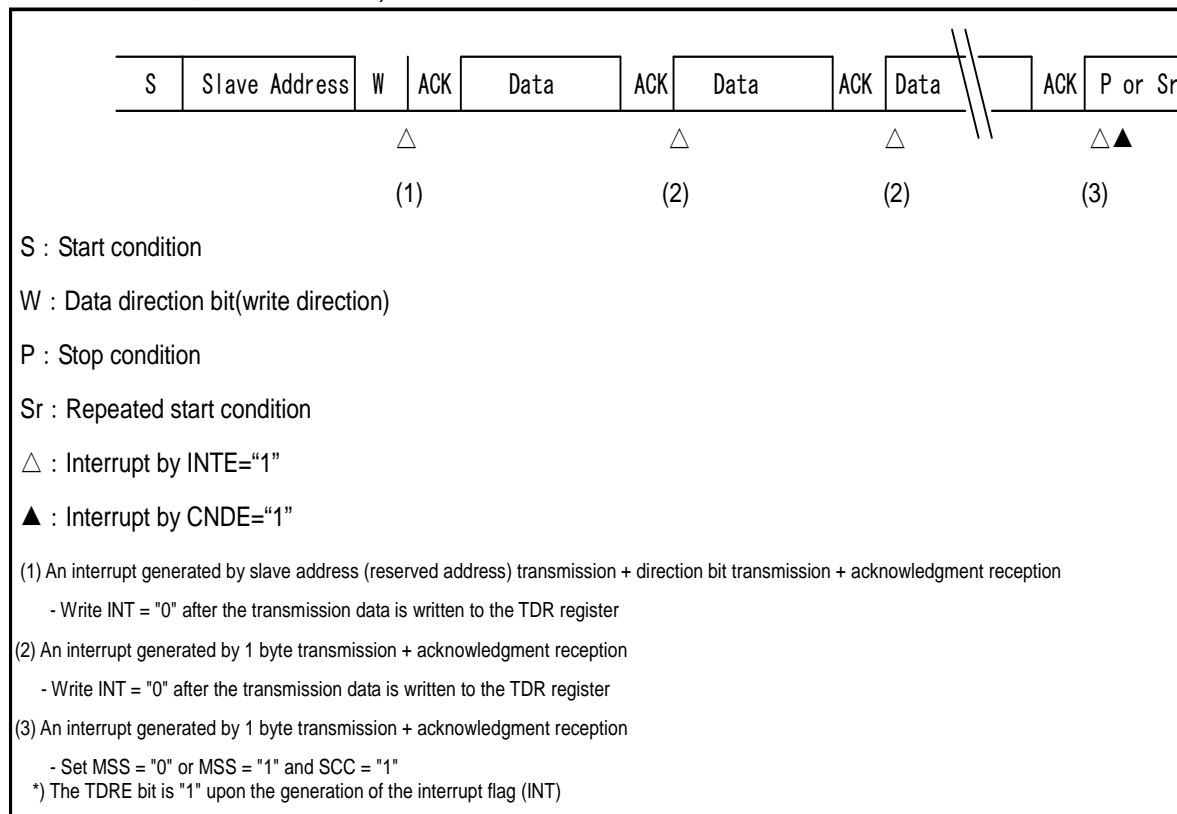


Figure 8-18 Master Transmission Interrupt (7)-when FIFO is Enabled (SSR:DMA=0, IBCR:WSEL=0, IBSR:RSA=0, ACK Response)

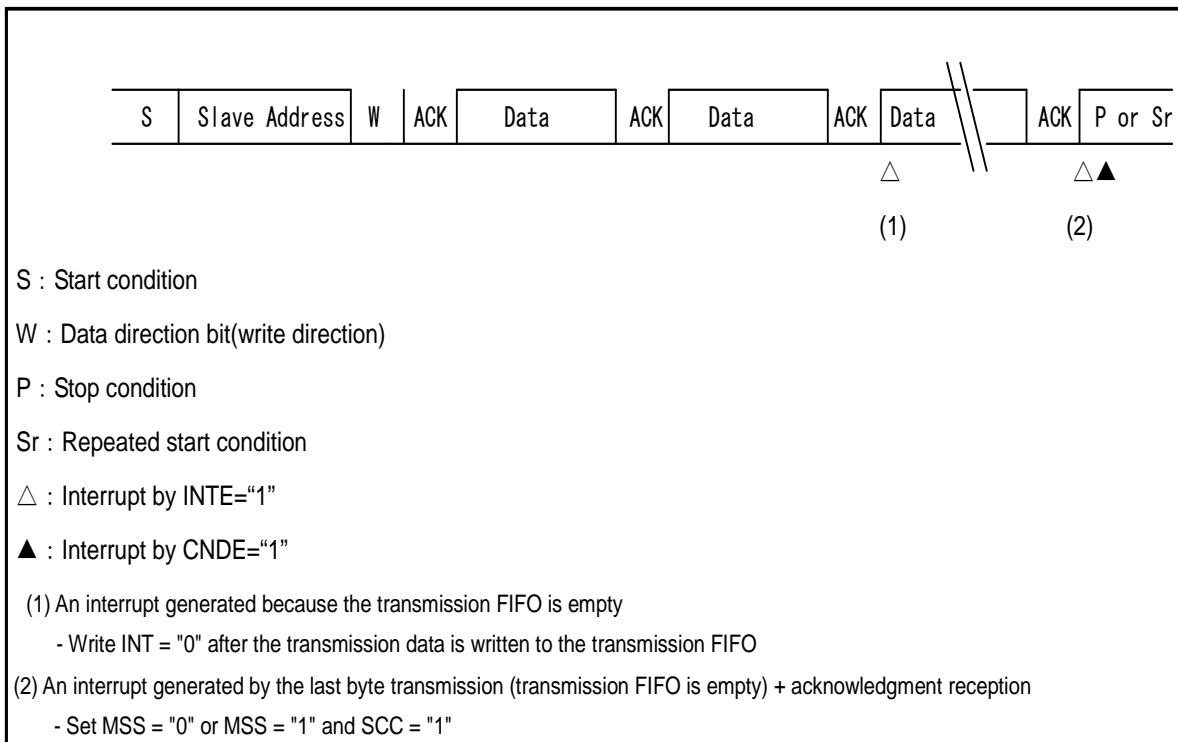


Figure 8-19 Master Transmission Interrupt (8)-when FIFO is Enabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0)

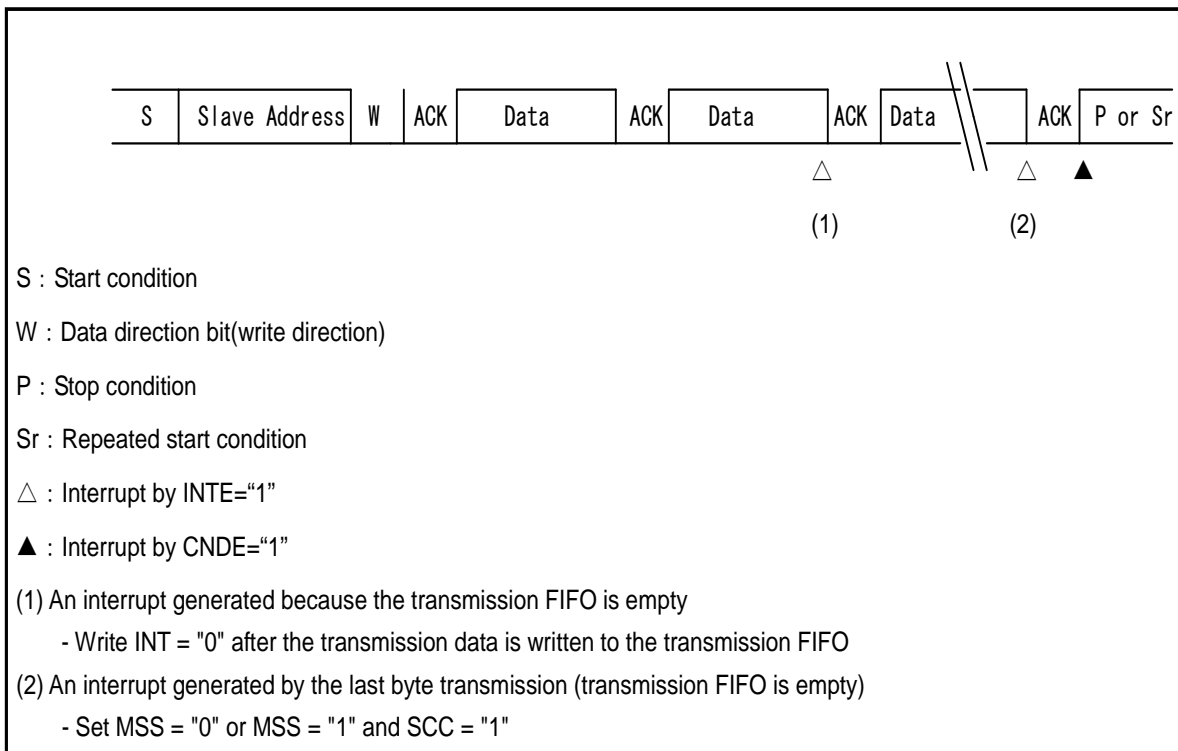


Figure 8-20 Master Transmission Interrupt (9)-when FIFO is Enabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0, NACK Response)

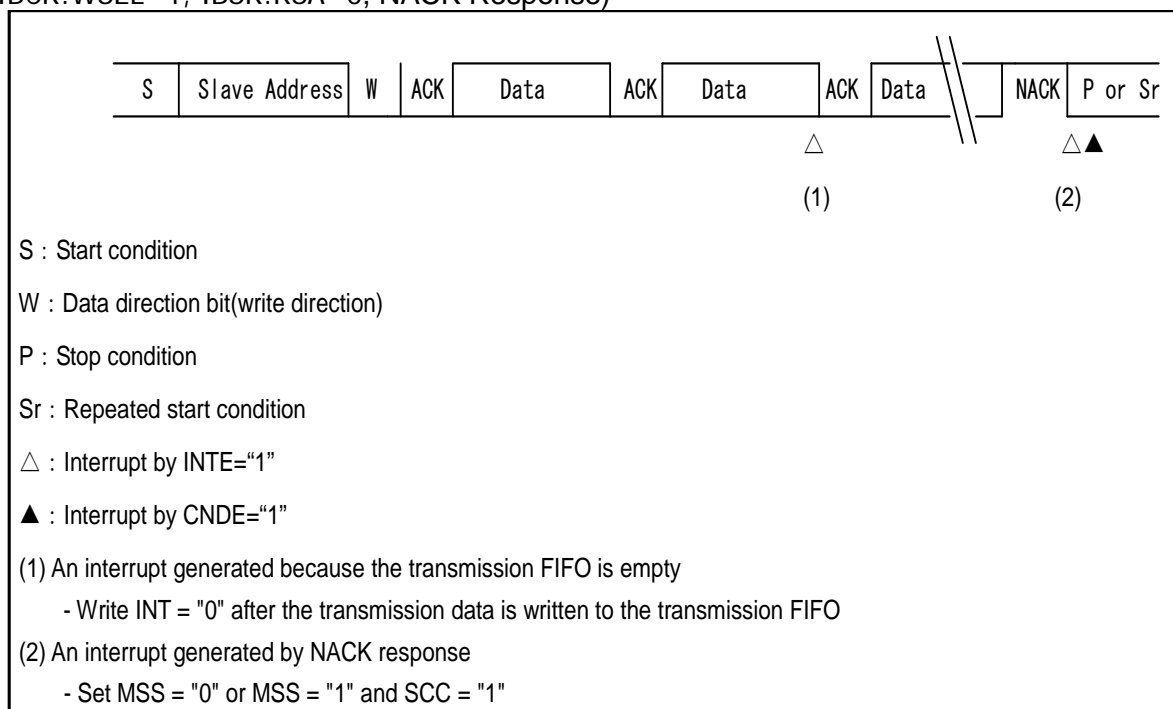


Figure 8-21 Master Transmission Interrupt (10)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=0)

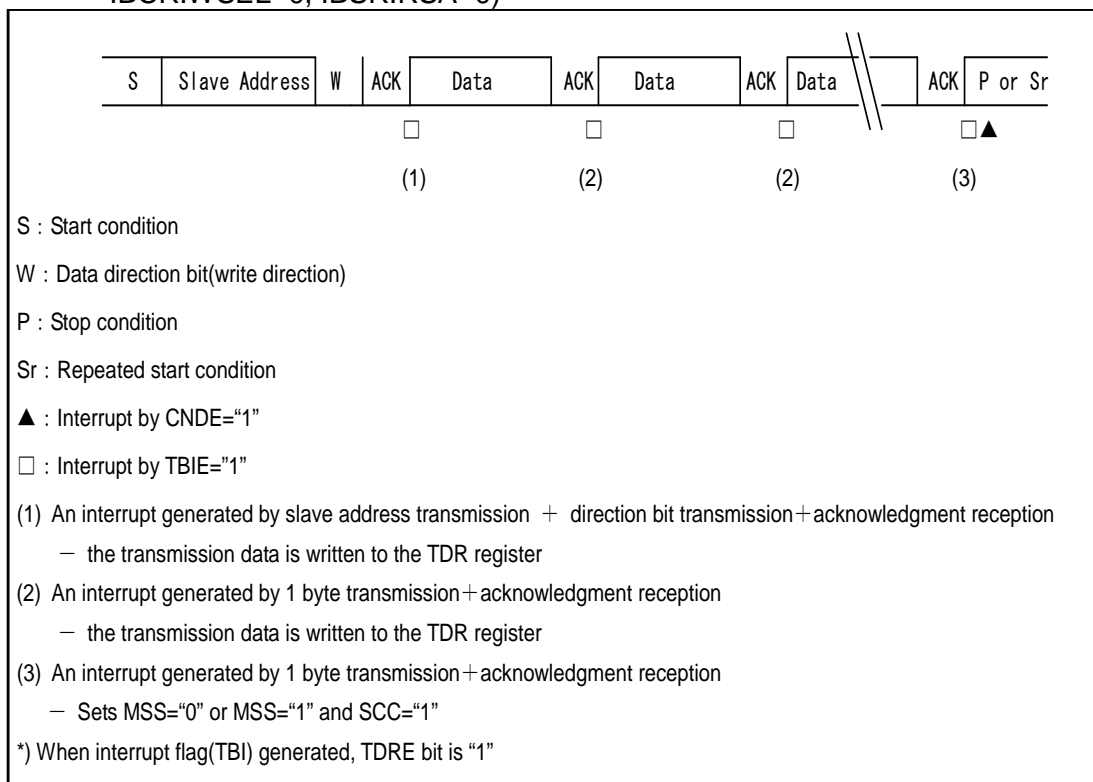


Figure 8-22 Master Transmission Interrupt (11)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0, ACK Response)

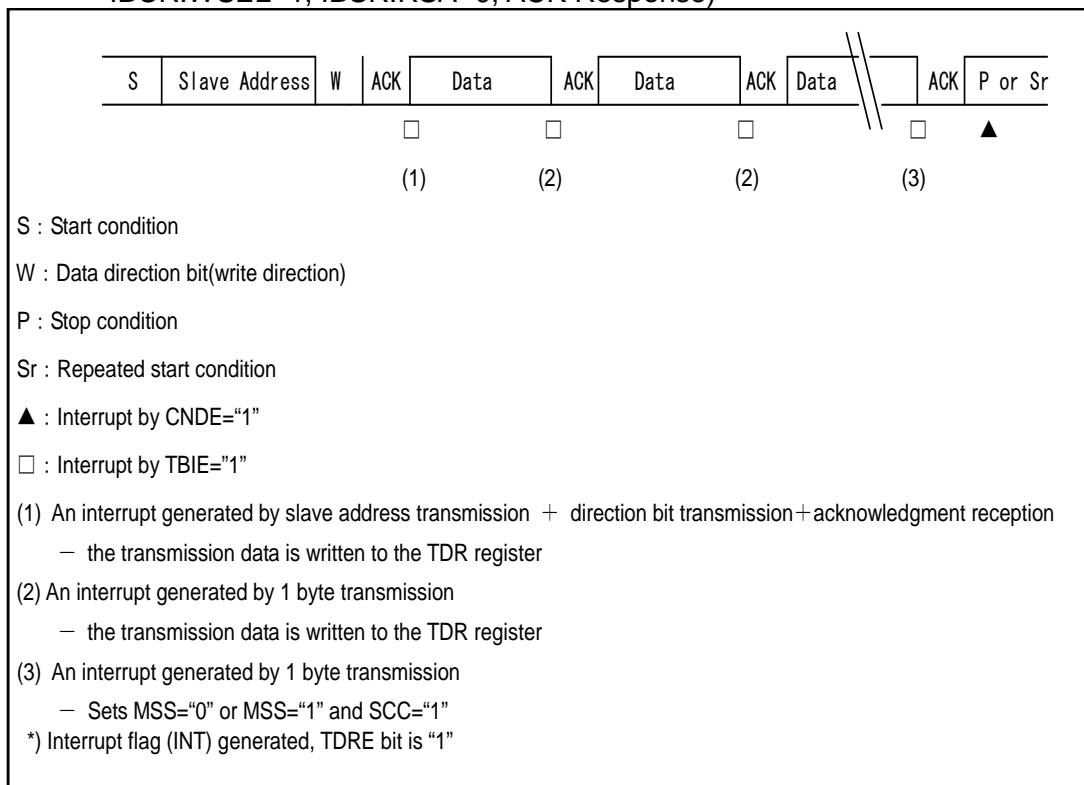


Figure 8-23 Master Transmission Interrupt (12)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0, NACK Response)

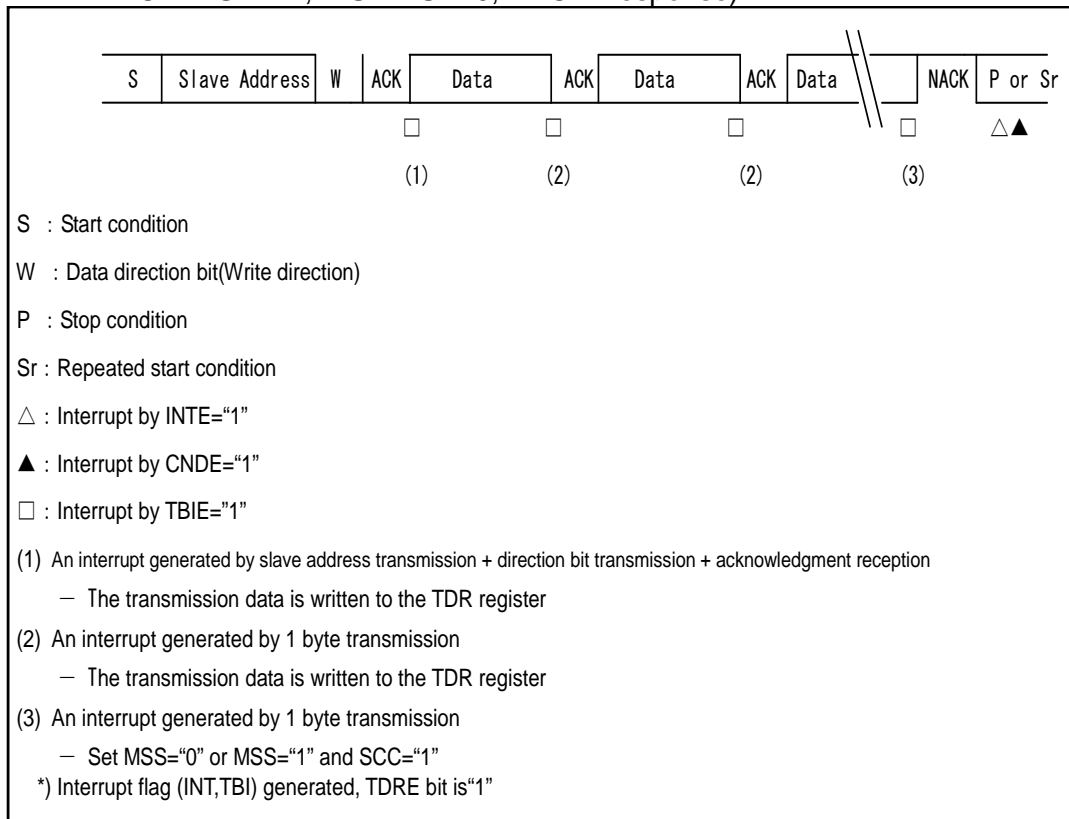


Figure 8-24 Master Transmission Interrupt (13)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0, Intermediate NACK Response)

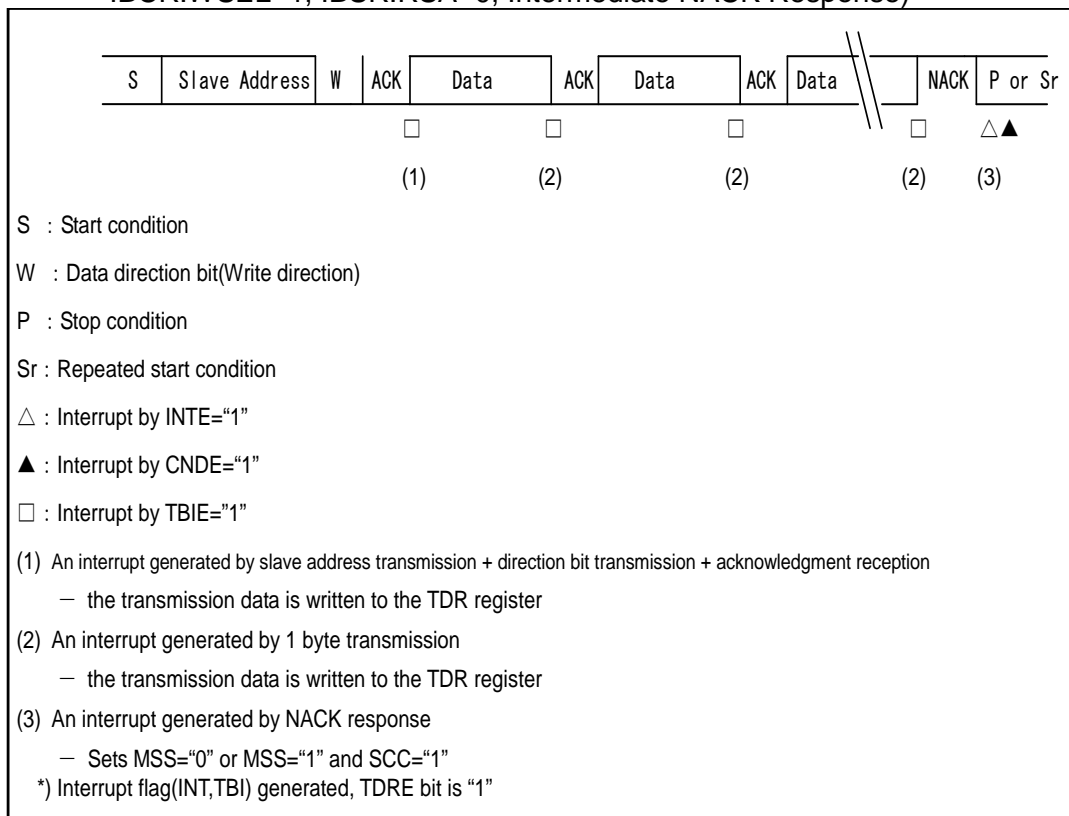


Figure 8-25 Master Transmission Interrupt (14)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1->0, IBSR:RSA=0, ACK Response)

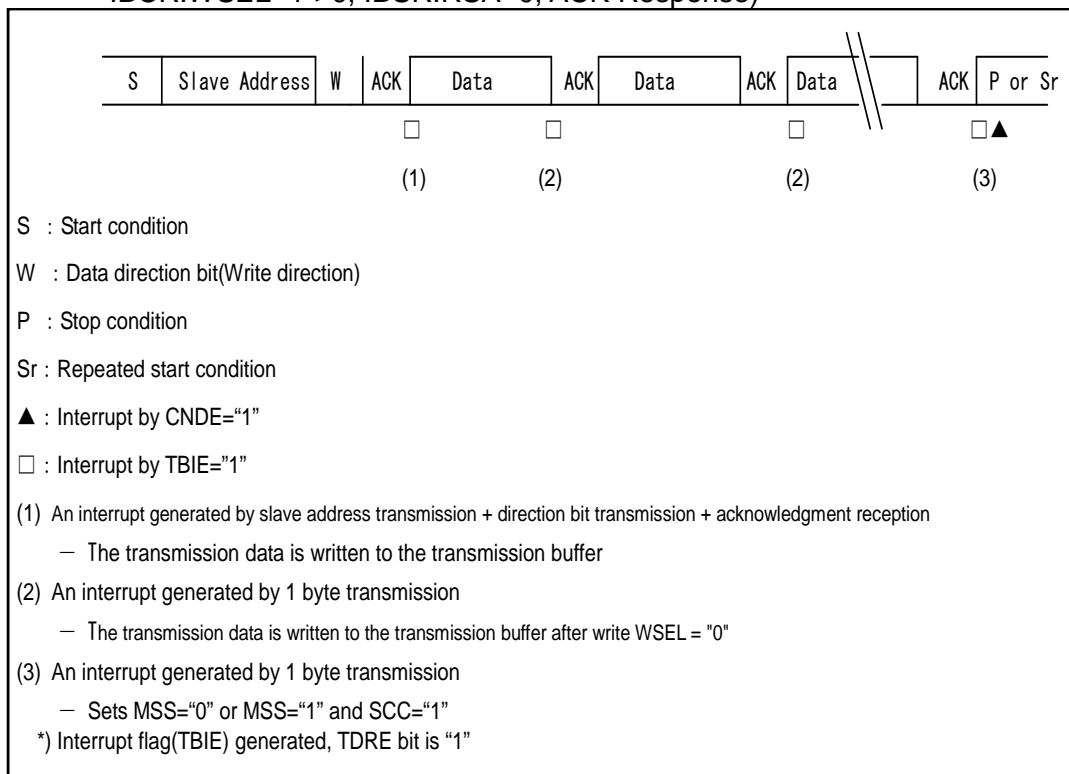


Figure 8-26 Master Interrupt (15)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=1)

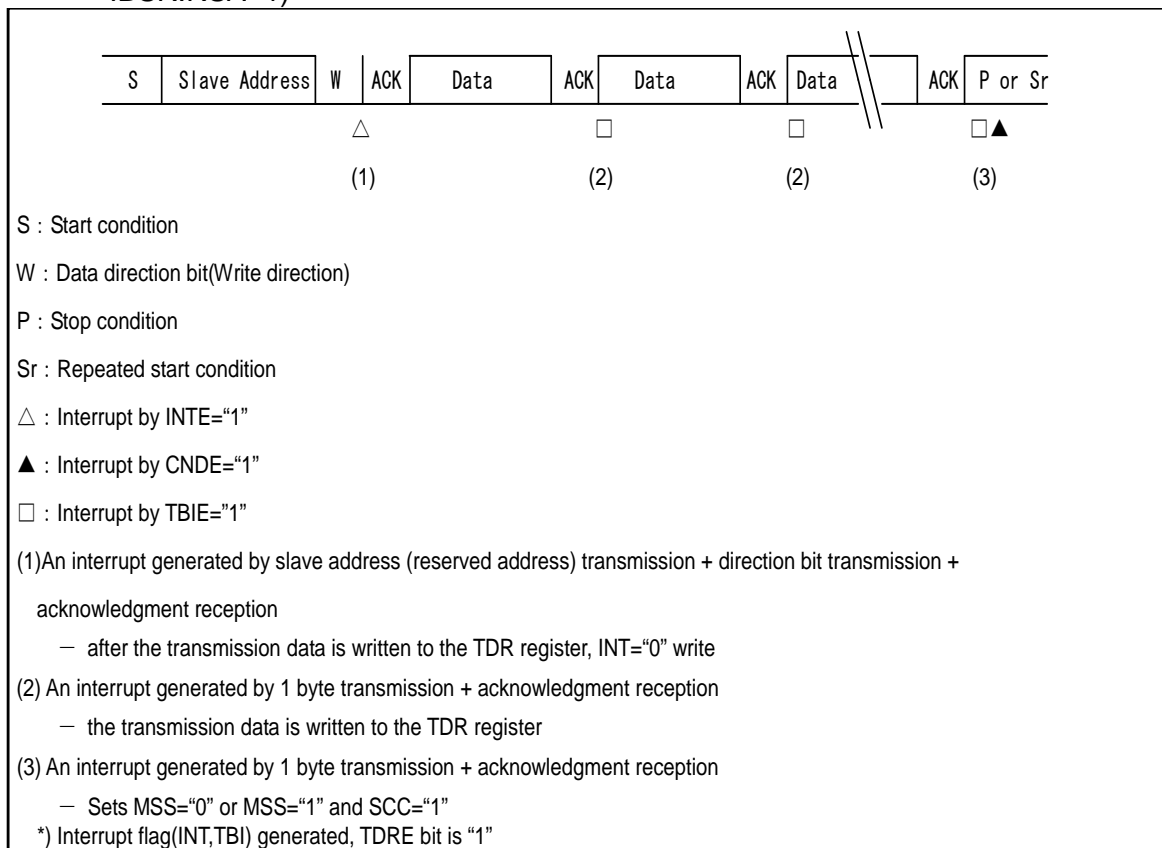


Figure 8-27 Master Transmission Interrupt (16)-when FIFO is Enabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=0, ACK Response)

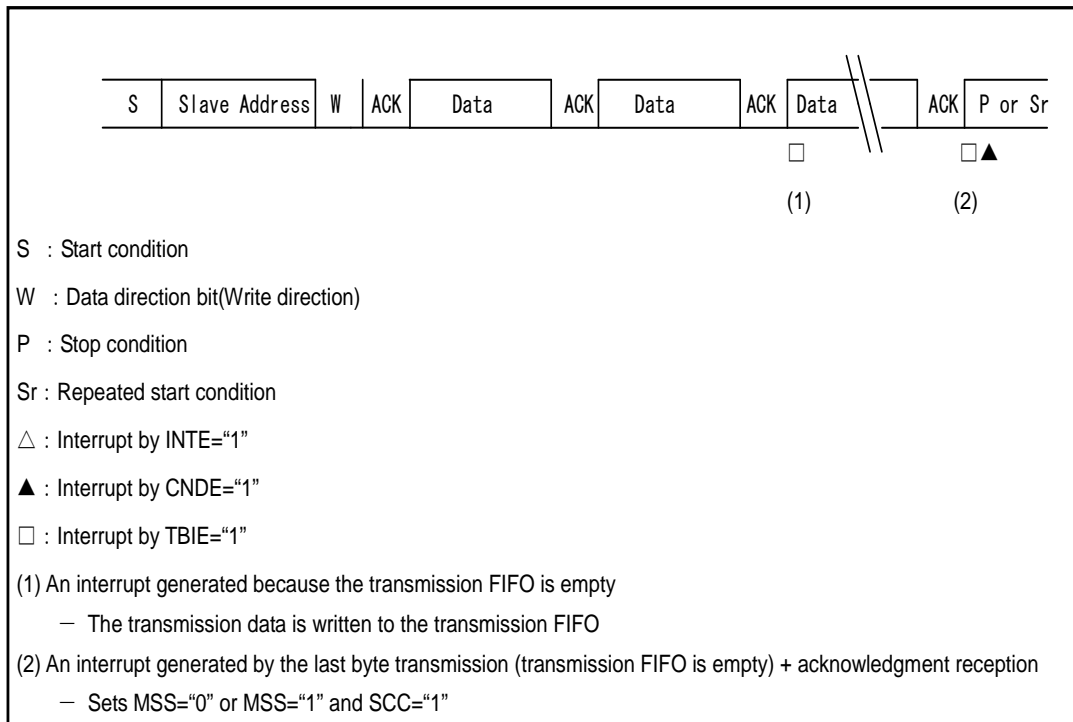


Figure 8-28 Master Transmission Interrupt (17)-when FIFO is Enabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0)

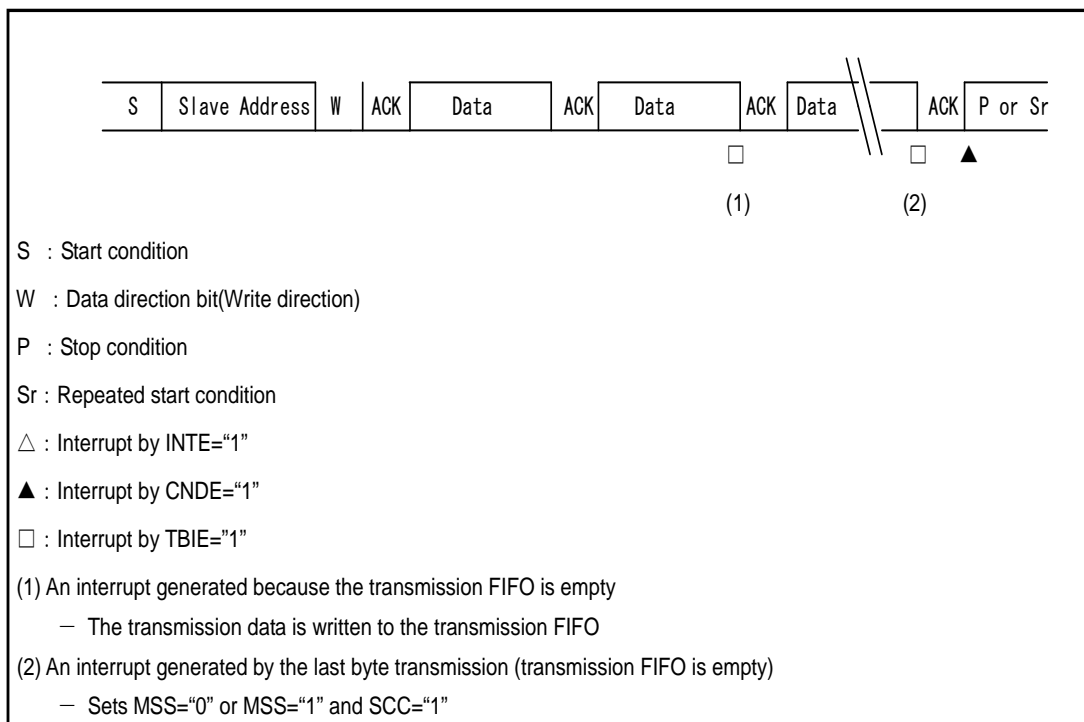
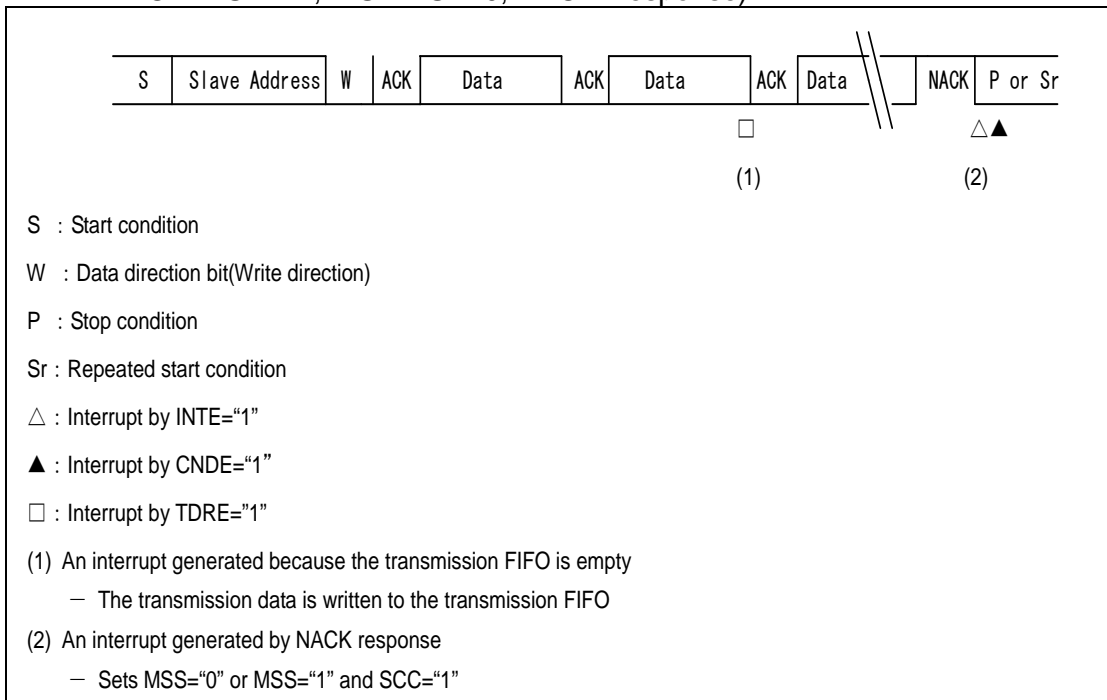


Figure 8-29 Master Transmission Interrupt (18)-when FIFO is Enabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0, NACK Response)



8.3.5. Data Reception by Master System

Data reception by the master system is shown below.

- When DMA mode is disable (SSR:DMA=0)

If the data direction bit (R/W) is "1", data sent from the slave device will be received.

If FIFO operation is disabled and if the SSR:TDRE bit is set to "1", the master device will generate a wait (IBCR:INT=1, SSR:RDRF=1) each time it receives 1 byte of data. Also, the master device responds with ACK or NACK to the ACKE bit setting of IBCR register based on the IBCR:WSEL bit setting. If the SSR:TDRE bit is "0" and if the ACKE bit setting of IBCR register is responded with ACK, no wait will be generated (IBCR:INT=0) and the next data will be received. If responded with NACK, a wait is generated (IBCR:INT=1).

If FIFO operation is enabled, the SSR:RDRF bit is set when the same number of bytes as the received data bytes is received. The interrupt flag is set if the SSR:TDRE bit is "1", and the I²C bus is waited. If IBCR:WSEL=0 and if the SSR:TDRE bit is set to "1", a NACK response is made and the interrupt flag is set to "1". When IBCR:WSEL=1, a wait is generated after the last byte is received. Set the IBCR:ACKE bit during the wait, and then the ACK or NACK response is performed according to the setting for the IBCR:ACKE bit once the interrupt flag is cleared to "0". The received data is stored in the receive FIFO memory even if a NACK response is made.

The following explains the waiting by interrupt.

Table 8-7 IBCR:WSEL Bit during Master Data Reception (When DMA mode is disable (SSR:DMA=0))

WSEL	Operation
0	In the 2nd or subsequent byte, the interrupt flag bit (IBCR:INT) is set to "1" and SCL is set to "L" to go into the wait state when the SSR:TDRE bit is "1" after the acknowledgment.
1	In the 2nd or subsequent byte, the interrupt flag bit (IBCR:INT) will be set to "1" and SCL will be set to "L" to go into the wait state when the SSR:TDRE bit is "1" after the master receives 1 byte data.

The following gives an example of procedure to receive data from the slave device.

- If the receive FIFO operation is disabled
 - Set the slave address (including the data direction bit) in the TDR register, and set the IBCR:MSS bit to "1".
 - Transmit the slave address and receive ACK. The interrupt flag (IBCR:INT) becomes "1".
 - Update the IBCR:WSEL bit and set the interrupt flag bit (IBCR:INT) to "0" to release the I²C bus from waiting state.
 - Put the I²C bus in a wait by setting the interrupt flag to "1", after transmitting an acknowledge upon the reception of one byte when IBCR:WSEL is set to "0", or immediately after one byte has been received when IBCR:WSEL is set to "1". Repeat Steps (3) to (4) until the specified number of data sets are received.
 - After reception of the last data, send a NACK response, set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" in order to generate a stop condition or a repeated start condition.
- If the send/receive FIFO operation is enabled
 - Set the receive data count to the FBYTE register.
 - Write the slave address (including the data direction bit) and the dummy data (for the receive data

size) into the TDR register.

- (3) Set the IBCR:MSS bit to "1".
- (4) Respond with an ACK and continue data reception when the SSR:TDRE bit is kept "0". After receiving the specified bytes of data (set by FBYTE), set the SSR:RDRF bit to "1". When the SSR:RDRF bit is set to "1", read the RDR register.
- (5) If the SSR:TDRE bit is set to "1" and if IBCR:WSEL=0, send a NACK response. If IBCR: WSEL=1, set the interrupt flag to "1" immediately after 1 byte of data reception in order to wait the I²C bus.
- (6) If IBCR:WSEL=1, set the IBCR:ACKE bit to "0". If IBCR:WSEL=0, the IBCR:ACKE bit needs not be set. Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" in order to generate a stop condition or a repeated start condition.

· When DMA mode is enable (SSR:DMA=1)

If the data direction bit (R/W) is "1", data sent from the slave device will be received.

If FIFO operation is disabled and if the SSR:TDRE bit is set to "1", the master device will generate a wait (SSR:TBI=1, SSR:RDRF=1) each time it receives 1 byte of data. Also, the master device responds with ACK or NACK to the ACKE bit setting of IBCR register based on the IBCR:WSEL bit setting. If the SSR:TDRE bit is "0" and if the ACKE bit setting of IBCR register is responded with ACK, no wait will be generated and the next data will be received. If responded with NACK, a wait is generated (IBCR:INT=1).

If FIFO operation is enabled, the SSR:RDRF bit is set when the same number of bytes as the received data bytes is received. The transmission bus idle flag (SSR:TBI) is set if the SSR:TDRE bit is "1", and the I²C bus is waited. If IBCR:WSEL=0 and if the SSR:TDRE bit is set to "1" if it is NACK by the ACKE bit setting, a NACK response is made and the interrupt flag (IBCR:INT) and transmission bus idle flag (SSR:TBI) are set to "1". When IBCR:WSEL=1, a wait (SSR: TBI=1) is generated after the last byte is received. Set the IBCR:ACKE bit during the wait, and then the ACK or NACK response is performed according to the setting for the IBCR:ACKE bit once the transmission bus idle flag (SSR:TBI) is cleared. The received data is stored in the reception FIFO memory even if a NACK response is made.

The following explains the waiting by interrupt.

Table 8-8 IBCR:WSEL Bit during Master Data Reception (When DMA mode is enabled (SSR:DMA=1))

WSEL	Operation
0	In the 2nd or subsequent byte, the transmission bus idle flag (SSR:TBI) is set to "1" and SCL is set to "L" to go into the wait state when the SSR:TDRE bit is "1" after the acknowledgment. In the 2nd or subsequent byte, the reception data full flag (SSR:RDRF) is set to "1" and SCL is set to "L" to go into the wait state when the reception FIFO is not used after the acknowledgment.
1	In the 2nd or subsequent byte, the interrupt flag (SSR:TBI) will be set to "1" and SCL will be set to "L" to go into the wait state when the SSR:TDRE bit is "1" after the master receives 1 byte data. In the 2nd or subsequent byte, the reception data full flag (SSR:RDRF) is set to "1" and SCL is set to "L" to go into the wait state after the data reception when the reception FIFO is not used after the acknowledgment.

The following gives an example of procedure to receive data from the slave device.

· If the reception FIFO operation is disabled

- (1) Set the slave address (including the data direction bit) in the TDR register, and set the IBCR:MSS bit to "1".
- (2) Transmit the slave address and receive ACK. The transmission bus idle flag (SSR:TBI) becomes "1".
- (3) The data transmitted to the TDR register is written, and release the I²C bus from waiting state.

- (4) Put the I²C bus in a wait by setting the transmission bus idle flag (SSR:TBI) and reception data full flag (SSR:RDRF)(*2) to "1", after transmitting an acknowledge upon the reception of one byte when IBCR:WSEL is set to "0", or immediately after one byte has been received when IBCR:WSEL is set to "1".
 - (5) Update the IBCR:WSEL bit and RDR register is read, and the data of the dummy is written in the TDR register.
 - (6) Put the I²C bus in a wait by setting the transmission bus idle flag (SSR:TBI) and reception data full flag (SSR:RDRF)(*2) to "1", after transmitting an acknowledge upon the reception of one byte when IBCR:WSEL is set to "0", or immediately after one byte has been received when IBCR:WSEL is set to "1". Repeat Steps (5) to (6) until the specified number of data sets are received.
 - (7) After reception of the last data, send a NACK response, set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" in order to generate a stop condition or a repeated start condition.
- If the transmission/reception FIFO operation is enabled
- (1) Set the reception data count to the FBYTE register.
 - (2) Write the slave address (including the data direction bit) and the dummy data (for the reception data size) into the TDR register.
 - (3) If IBCR:WSEL=0, it makes to NACK by setting the ACKE bit, and "1" is written in the IBCR:MSS bit.
 - (4) Respond with an ACK and continue data reception when the SSR:TDRE bit is kept "0". After receiving the specified bytes of data (set by FBYTE), set the SSR:RDRF bit to "1". When the SSR:RDRF bit is set to "1", read the RDR register.
 - (5) If the SSR:TDRE bit is set to "1" and if IBCR:WSEL=0, send a NACK response the interrupt flag is set as "1" in order to wait the I²C bus. If IBCR:WSEL=1, set the transmission bus idle flag (SSR:TBI) to "1" immediately after 1 byte of data reception in order to wait the I²C bus.
 - (6) If IBCR:WSEL=1, set the IBCR:ACKE bit to "0". If IBCR:WSEL=0, the IBCR:ACKE bit needs not be set. Set the IBCR:MSS bit to "0" or set the IBCR:SCC bit to "1" in order to generate a stop condition or a repeated start condition.

*1: The DMA mode must write the slave address in TDR after confirming the IBCR:INT bit is set in "1" after "1" is written in the IBCR:INT bit, and set "1" to the IBCR:SCC bit if you issues the repetition start condition when the DMA mode is enabled (SSR:DMA=1), also the SSR:TBI bit is set as "1" and the INT bit is set as "0".

*2: Reception data full flag (SSR:RDRF) is set in "1" regardless of the setting of IBCR:WSEL immediately after the reception one byte. When the reception data full flag is set as "1" since the second byte, if the IBCR:WSEL bit is 0, after acknowledge transmission also IBCR:WSEL=1, I²C bus is waited at one byte reception.

Notes:

- If the 7-bit slave address detection is enabled (ISBA:SAEN=1), you cannot specify a 7-bit slave address in the master mode.
- If SSR:TDRE is "0", an acknowledge signal will be sent based on the IBCR:ACKE bit setting and the subsequent process will be executed even if an overrun error occurs.
- If you need to change the IBCR register during data sending or receiving, change it only when the interrupt flag (IBCR:INT) is "1" or when the transmission bus idle flag (SSR:TBI1) is "1" during the DMA mode is enabled (SSR:DMA=1).
- When the master device is receiving data and if the DMA mode is disabled (SSR:DMA=0), dummy data is written in the TDR register and if the SSR:TDRE bit is set as "0" at the interrupt flag (IBCR:INT) is set to "1", the interrupt flag (IBCR:INT) will be held to "0" and the next data will be received.
- When the master device is receiving data and if the DMA mode is enable (SSR:DMA=1), dummy data is written in the TDR register and if the SSR:TDRE bit is set as "0" at the transmission bus idle flag (SSR:TBI) is set to "1", the transmission bus idle flag (SSR:TBI) will be held to "0" and the next data will be received.
- If data is received when the reception FIFO is enabled and IBCR:WSEL=0, the SSR:RDRF bit becomes "1" after the last bit is received and the interrupt flag (IBCR:INT) becomes "1" after ACK is transmitted.

Figure 8-30 Master Reception Interrupt (1)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=0, IBSR:RSA=0)

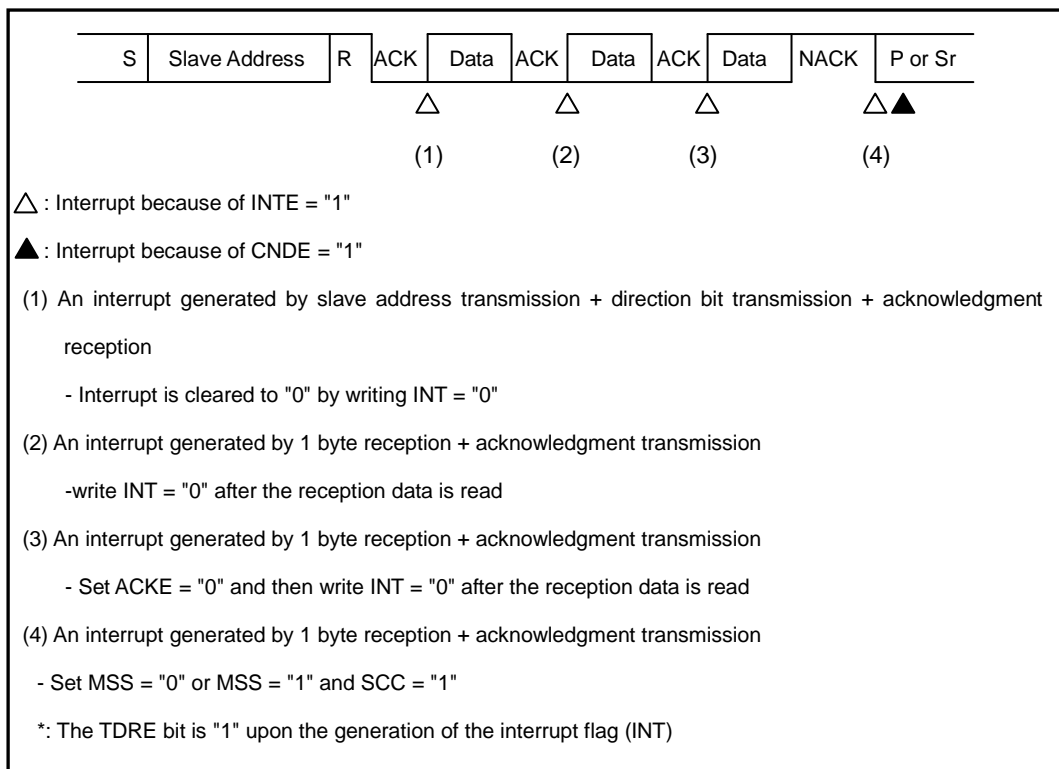


Figure 8-31 Master Reception Interrupt (2)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0)

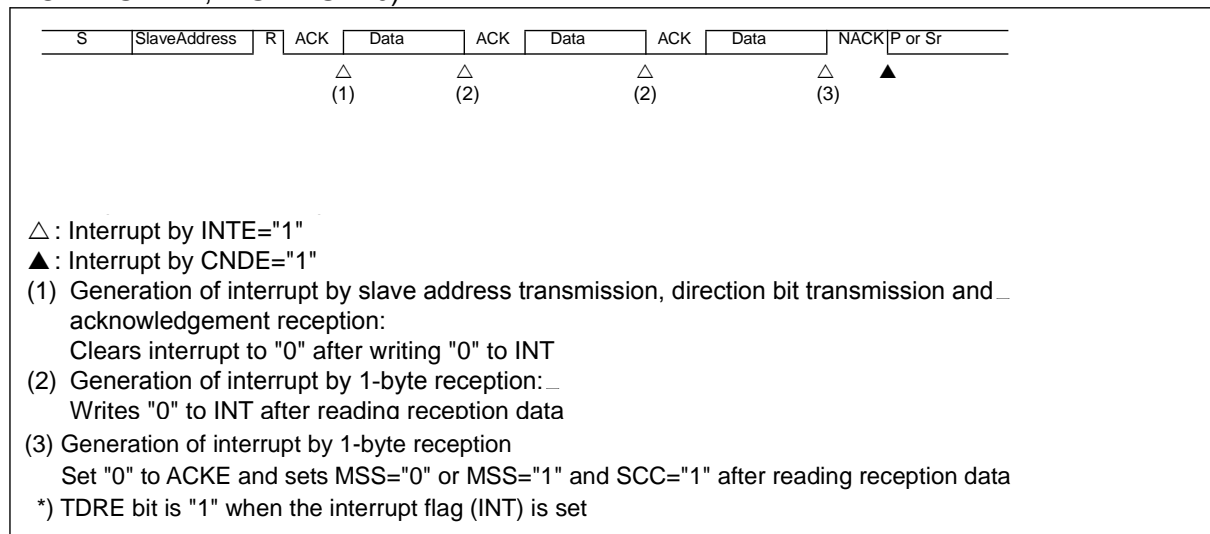


Figure 8-32 Master Reception interrupt (3)-when FIFO is Enabled (SSR:DMA=0, IBCR:WSEL=0, IBCR:ACKE=0, IBSR:RSA=0)

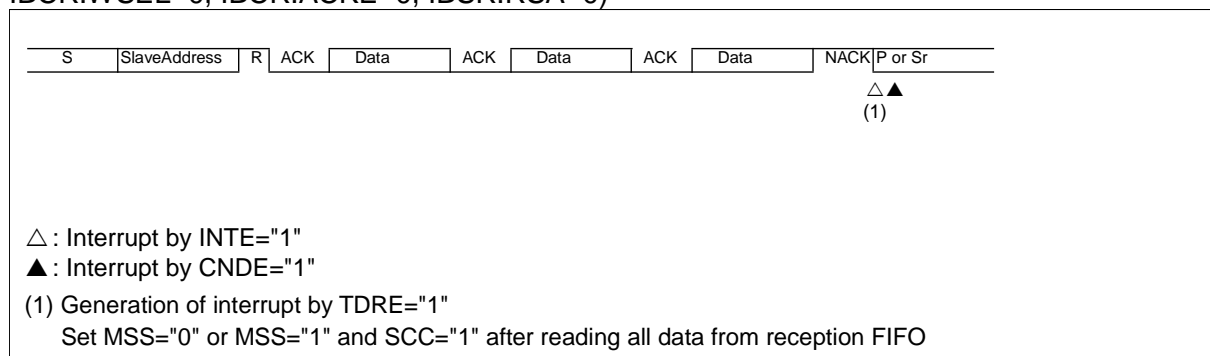


Figure 8-33 Master Reception interrupt (4)-when FIFO is Enabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0)

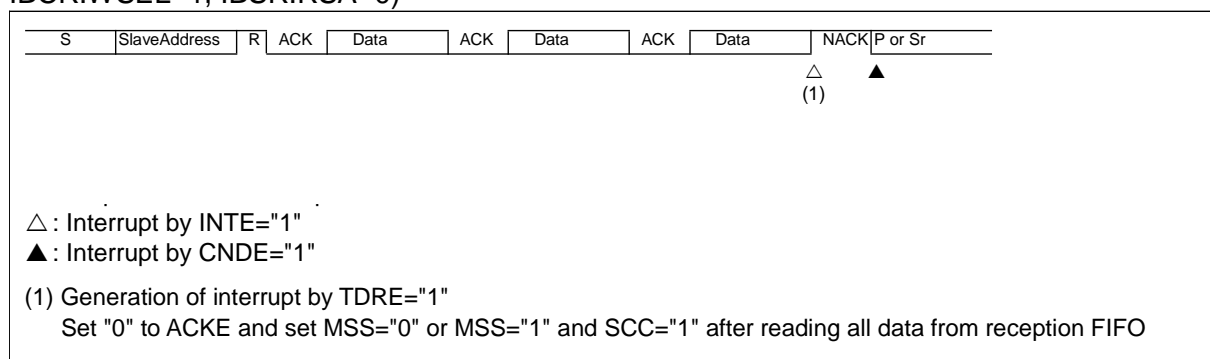


Figure 8-34 Master Reception interrupt (5)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=0)

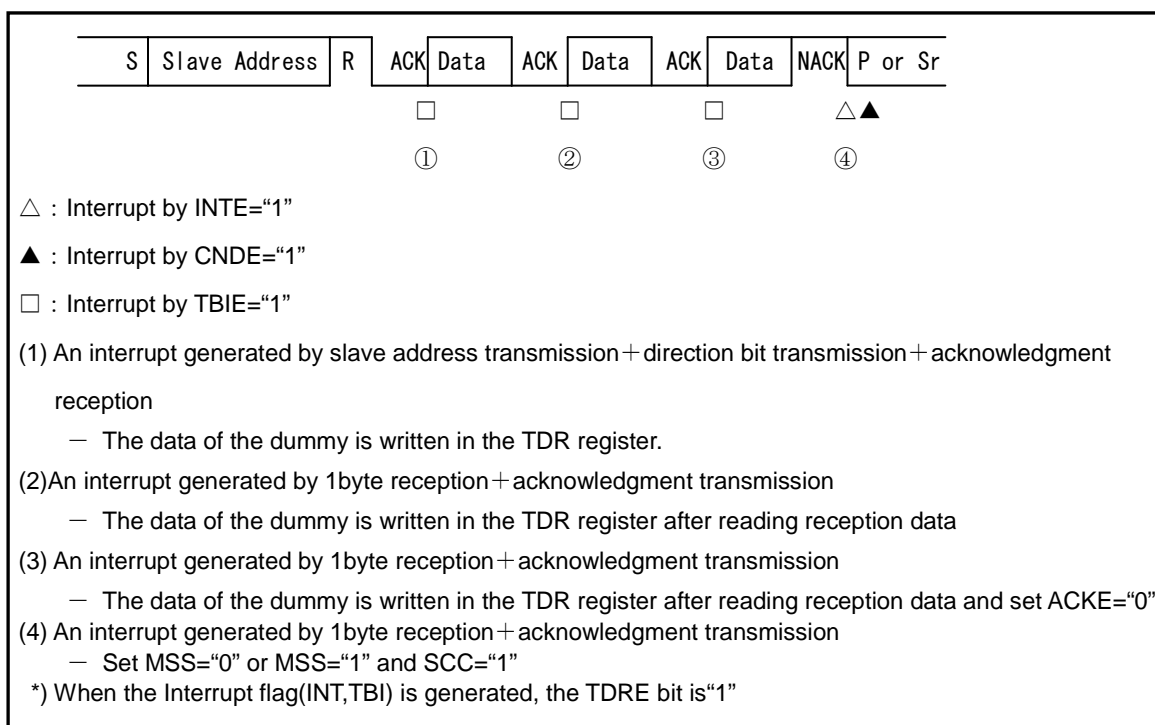


Figure 8-35 Master Reception interrupt (6)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0)

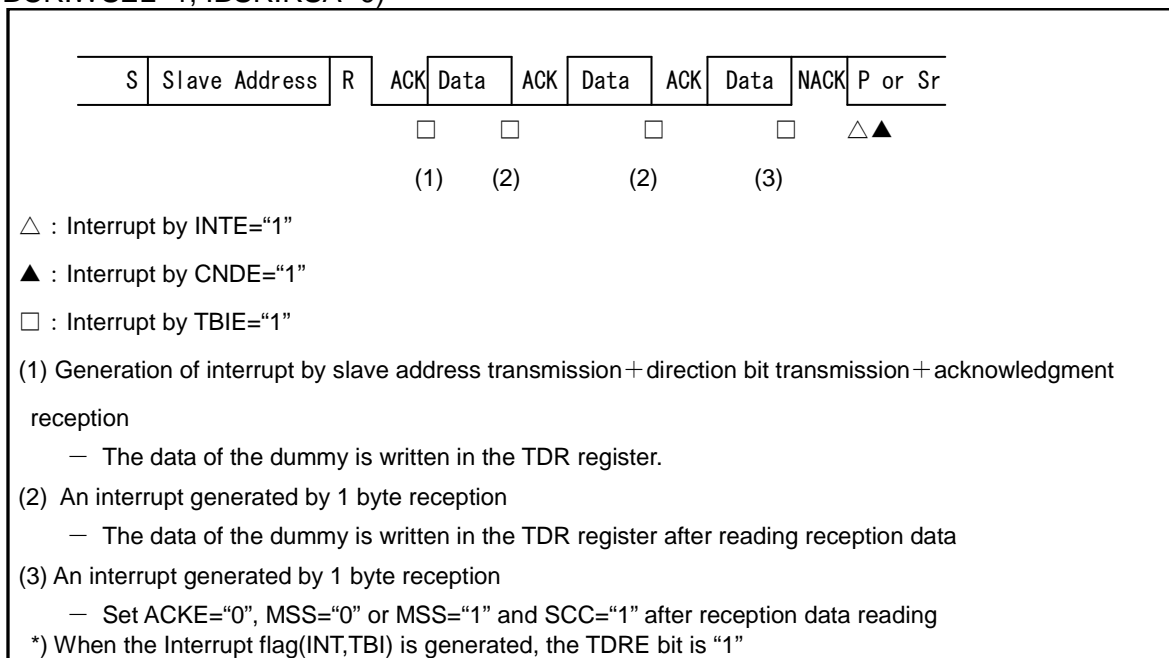


Figure 8-36 Master Reception interrupt (7)-when FIFO is Enabled (SSR:DMA=1, IBCR:WSEL=0, IBCR:ACKE=0, IBSR:RSA=0)

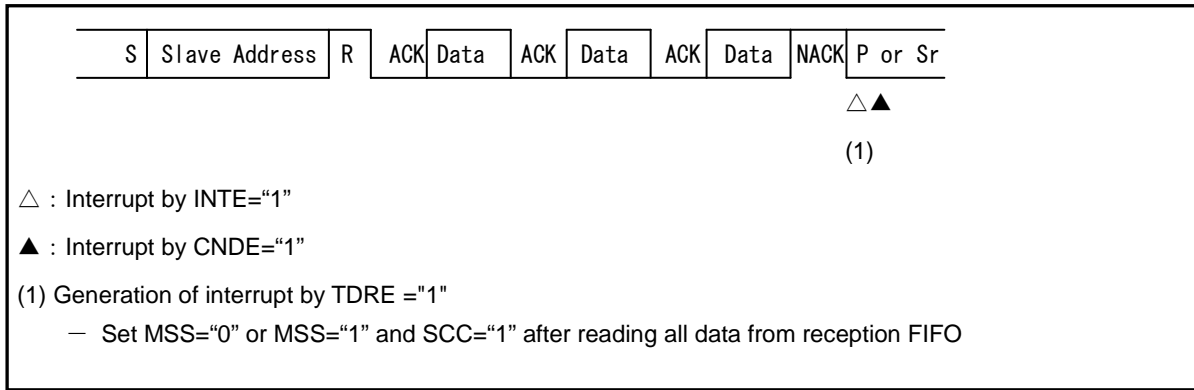
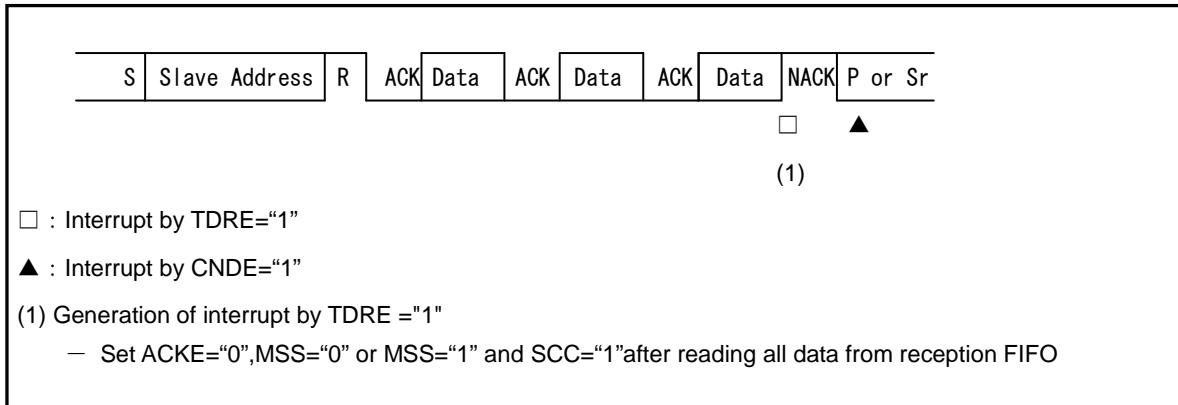


Figure 8-37 Master Reception interrupt (8)-when FIFO is Enabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0)



8.3.6. Arbitration Lost

The arbitration lost is shown below.

If data of the master device is hit by data from another master device and if the data that is different from the transmitted data is received, it will be determined to be an arbitration lost. The IBCR:MSS bit is set to "0" and the IBSR:AL bit is set to "1" so that the device can operate in the slave mode. The IBSR:AL bit is cleared to "0" if:

- The IBCR:MSS bit is set to "1"
- The IBCR:INT bit is set to "0".
- The IBSR:SPC bit is set to "0" when IBSR:AL=1 and IBSR:SPC=1.
- The I²C interface is disabled (ISMK:EN bit=0).

If an arbitration lost occurs, the interrupt flag (IBCR:INT) will be set to "1" and the SCL of I²C bus will be set to "L" based on the IBCR:WSEL setting.

8.3.7. Wait of the Master Mode

Wait of the master mode is shown below.

When the IBSR:BB bit is "1" and the IBCR:MSS bit is set to "1", if the slave mode is not operated, wait the master mode as long as the IBSR:BB bit is "1". The start condition is transmitted when the IBSR:BB bit becomes "0". You can judge whether the master mode is in wait state or not using IBCR:MSS and IBCR:ACT bits (in wait state if IBCR:MSS=1 and IBCR:ACT=0). To operate as the slave mode after the IBCR:MSS bit is set to "1", set the IBSR:AL and IBCR:ACT bits to "1" and the IBCR:MSS bit to "0".

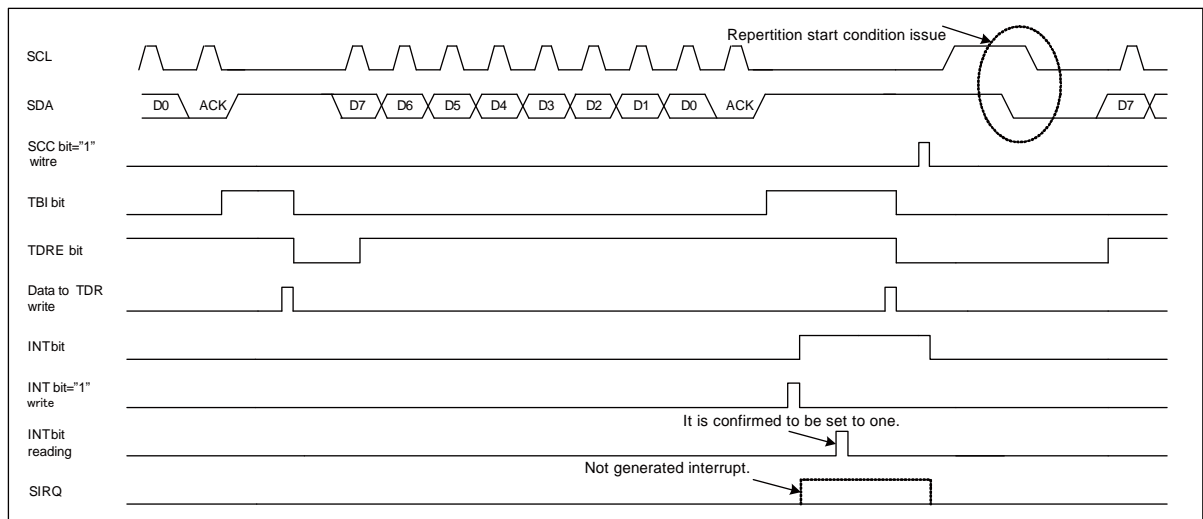
8.3.8. Repetition Start Condition Issue when DMA Mode Enabled (SSR:DMA=1)

The repetition start condition issue when DMA mode is enabled (SSR:DMA=1) is shown below.

The transmission operation begins when the slave address is written in the TDR register when the transmission bus idle is in progress (SSR:TBI=1) and interrupt flag (IBCR:INT) is "0", and it is impossible to issue the repetition start condition.

Therefore, if the repetition start condition is issued when the transmission bus idle is in progress (SSR:TBI=1) and the interrupt flag (IBCR:INT) is "0", it is confirmed that "1" is written in the interrupt flag (IBCR:INT) first, and the interrupt flag (IBCR:INT) is set in "1" afterwards. At this time, the SIRQ interrupt is not generated. Next, the slave address is written in the TDR register, and the repetition start is issued afterwards (IBCR:SCC=1).

Figure 8-38 Repetition Start Condition Issue when DMA Mode is Enabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=0, ACK Response)



8.4. I²C Slave Mode

The I²C Slave mode is shown below.

If the (repeated) start condition is detected and if a combination of ISBA register and ISMK register settings match the received address, an ACK response is sent and the slave mode operation starts.

8.4.1. Detection of Slave Address Matching

Detection of slave address matching is shown below.

When the (repeated) start condition is detected, the 7 bits of the next data are received as the address. If the bit is set to "1" in the ISMK register, it is compared with each bit of the ISBA register and the received address. If they match, an ACK signal is output.

Table 8-9 Operations Immediately After Slave Address Acknowledgment

Transmission FIFO	Reception FIFO	Transmission FIFO status	Reception FIFO status	Data direction bit (R/W)	Operation immediately after acknowledgement	
					Acknowledge is ACK	Acknowledge is NACK
Disabled	Disabled	-	-	0	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is held to "0" and not waited.
				1		
Disabled	Enabled	-	Without data	0	The IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is held to "0" and not waited.
			With data		The IBCR:INT bit is set to "1" and waited.	
			-	1	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	
Enabled	Disabled	-	-	0	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is held to "0" and not waited.
				1		
Enabled	Enabled	-	Without data	0	The IBCR:INT bit is held to "0" and not waited.	The IBCR:INT bit is held to "0" and not waited.
			With data		The IBCR:INT bit is set to "1" and waited.	
			-	1	If the SSR:TDRE bit is "1", the IBCR:INT bit is set to "1" and waited. If the SSR:TDRE bit is "0", the IBCR:INT bit is held to "0" and not waited.	

· Reserved address detected

If the first byte already matches the reserved address ("0000xxxx" or "1111xxxx"), the IBCR:INT bit is set to "1" and the I²C bus is waited after receiving the 8-th bit of data. These operations are not associated with a permission of transmission or reception FIFO operation. During this time, if you read the received data and operate the device as a slave one, set the IBCR:ACKE bit to "1" and check the data direction bit (IBSR:TRX). If it is the transmission direction, write the transmission data in the TDR register and clear the IBCR:INT bit. Then, the device operates as a slave one. If the IBCR:ACKE bit is set to "0", the device does not operate as a slave device after acknowledgement.

8.4.2. Data Direction Bit

The data direction bit is shown below.

After the address reception, a data direction bit that determines the data transmission or reception is received. If this bit is "0", it shows the data transmission from the master device while this device receives data as a slave device.

8.4.3. Reception by Slave Device

Data reception by the slave device is shown below.

If the slave address matches and if the data direction bit is "0", it indicates the data reception in the slave mode. The following gives an example of procedure of data reception in the slave mode.

- When DMA mode is disable (SSR:DMA=0)
 - If the reception FIFO operation is disabled
 - (1) After sending an ACK signal, set the interrupt flag (IBCR:INT) to "1" to wait the I²C bus. You can determine the interrupt occurrence due to slave address matching shown by IBCR:MSS bit, IBCR:ACT bit and IBSR:FBT bit. Set the IBCR:ACKE bit to "1" and set the interrupt flag (IBCR:INT) to "0" to release the I²C bus from the waiting state. See "Table 8-9 Operations Immediately After Slave Address Acknowledgment".
 - (2) After receiving one byte of data, set the interrupt flag (IBCR:INT) to "1" based on the IBCR:WSEL setting, and wait the I²C bus.
 - (3) Read the received data from the RDR register, set the IBCR:ACKE bit, and set the interrupt flag (IBCR:INT) to "0" to release the I²C bus from the waiting state.
 - (4) Repeat Steps (2) and (3) until the stop condition or the repeated start condition is detected.
 - If the reception FIFO operation is enabled
 - (1) When a NACK signal is detected or when the reception FIFO memory is full, the interrupt flag (IBCR:INT) is set to "1" and the I²C bus is waited. When the stop condition or the repeated start condition is detected, the IBSR:SPC bit and IBSR:RSC bit are set to "1" but the interrupt flag (IBCR:INT) is not set to "1" (and the I²C bus is not waited). If the value set in the FBYTE register matches the number of received data, the reception FIFO sets the SSR:RDRF bit to "1". During this time, if the SMR:RIE bit is "1", a reception interrupt occurs.
 - (2) If the interrupt flag (IBCR:INT) is set to "1", the received data is read from the RDR register. After reading all data sets, set the interrupt flag to "0" and release the I²C bus from the waiting state. When the stop condition or the repeated start condition is detected, all of the received data sets are read from the RDR register, and the IBSR:SPC bit or IBSR:RSC bit is cleared to "0".
- When DMA mode is enable (SSR:DMA=1)
 - If the reception FIFO operation is disabled
 - (1) After sending an ACK signal, set the interrupt flag (IBCR:INT) to "1" to wait the I²C bus. You can determine the interrupt occurrence due to slave address matching shown by IBCR:MSS bit, IBCR:ACT bit and IBSR:FBT bit. Set the IBCR:ACKE bit to "1" and set the interrupt flag (IBCR:INT) to "0" to release the I²C bus from the waiting state. See "Table 8-9 Operations Immediately After Slave Address Acknowledgment".
 - (2) Reception data full flag (SSR:RDRF) is set in "1" immediately after the reception 1 byte after the data of 1 byte is received. The I²C bus is waited for IBCR:WSEL=1 immediately after the reception 1 byte after the acknowledge is transmitted for IBCR:WSEL=0 in the place where reception data full flag (SSR:RDRF) is set in "1".
 - (3) Reading the data received from the RDR register after the IBCR:ACKE bit is set clears the reception data full flag (SSR:RDRF) to "0" and the I²C bus from the waiting state is released.
 - (4) Repeat Steps (2) and (3) until the stop condition or the repeated start condition is detected.
 - If the reception FIFO operation is enabled
 - (1) The interruption flag (IBCR:INT) becomes "1" and waits for the I²C bus by detecting NACK. The I²C bus is waited for when reception FIFO becomes full. The IBSR:SPC bit and the IBSR:RSC bit are made "1" when the stop condition and the repetition start condition are detected and the interrupt flag

(IBCR:INT) does not become "1" (none waiting of the I²C bus). When a set value of the FBYTE register is corresponding to the received number of data, reception FIFO makes the SSR:RDRF bit "1". When the SMR:RIE bit is "1" at that time, the reception interrupt is generated.

- (2) If the interrupt flag (IBCR:INT) is set to "1", the received data is read from the RDR register. After reading all data sets, set the interrupt flag to "0" and release the I²C bus from the waiting state. If the data received from the RDR register even once is read when reception FIFO becomes full, the I²C bus from the waiting state is released. When the stop condition or the repeated start condition is detected, all of the received data sets are read from the RDR register, and the IBSR:SPC bit or IBSR:RSC bit is cleared to "0".

Figure 8-39 Slave Reception Interrupt (1)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=0, IBSR:RSA=0)

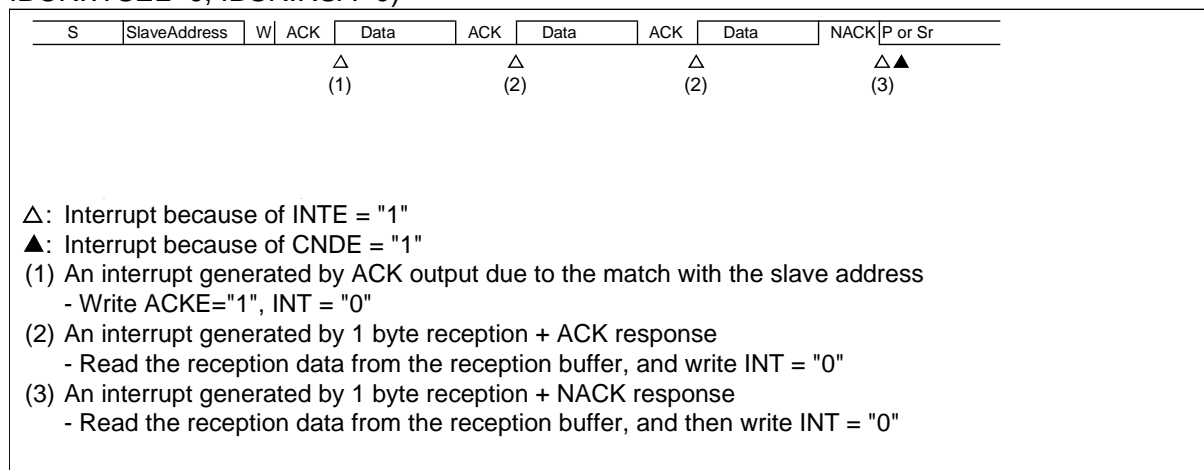


Figure 8-40 Slave Reception Interrupt (2)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0)

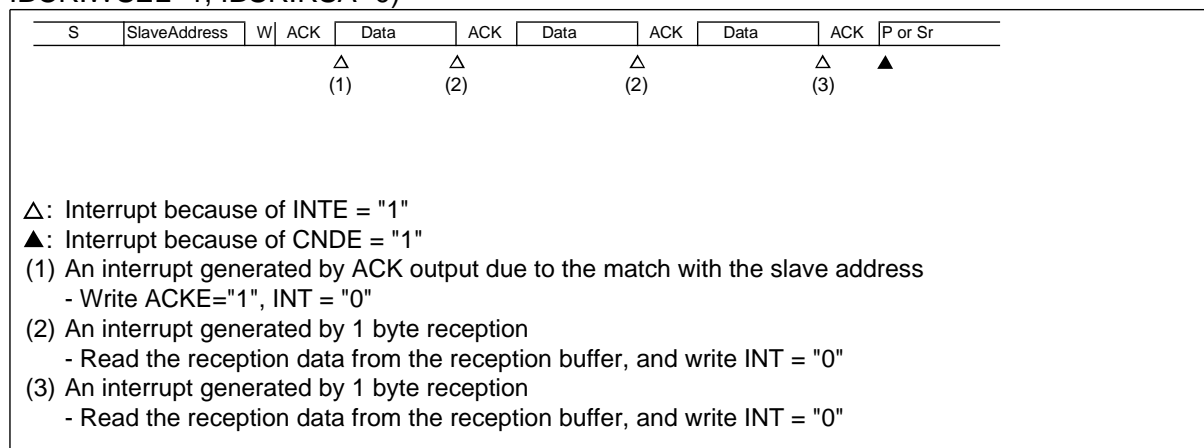


Figure 8-41 Slave Reception Interrupt (3)-when FIFO is Disabled (SSR:DMA=0, IBCR:WSEL=1, IBSR:RSA=0)

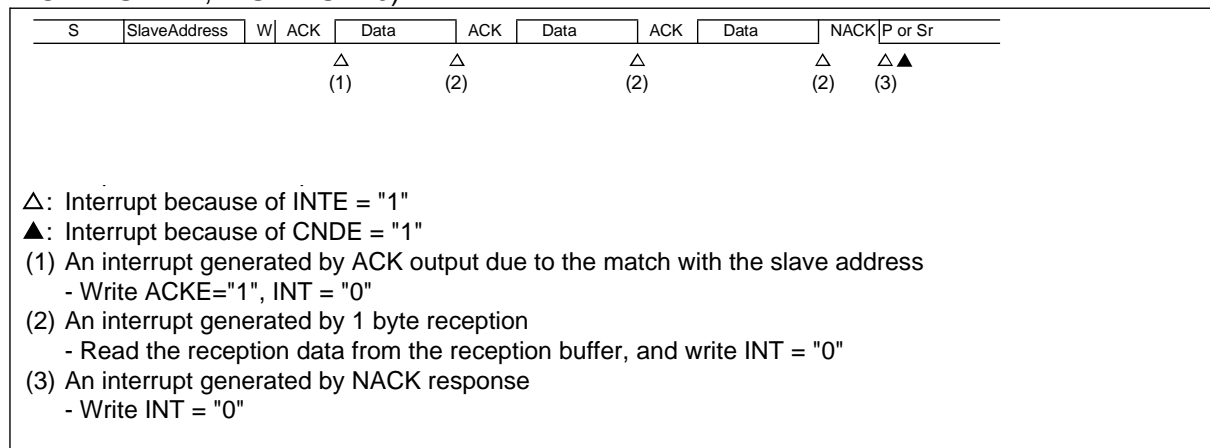


Figure 8-42 Slave Reception Interrupt (4)-when FIFO is Enabled (SSR:DMA=0, IBSR:RSA=0)

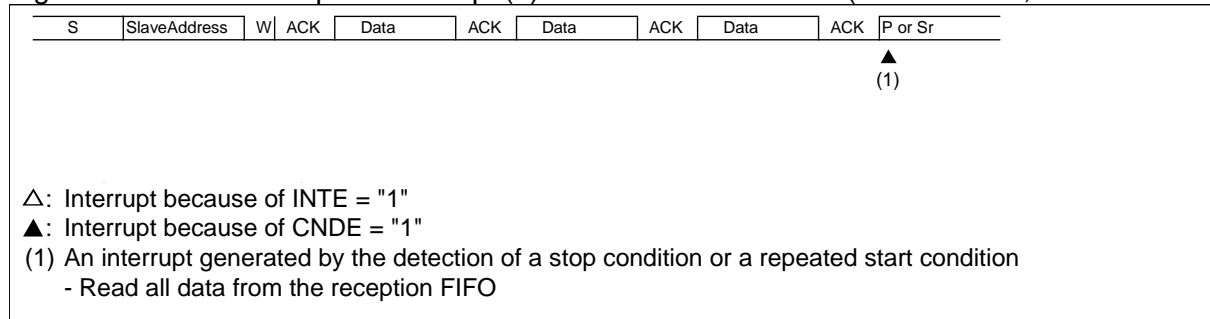


Figure 8-43 Slave Reception Interrupt (5)-when FIFO is Enabled (SSR:DMA=0, IBSR:RSA=0)

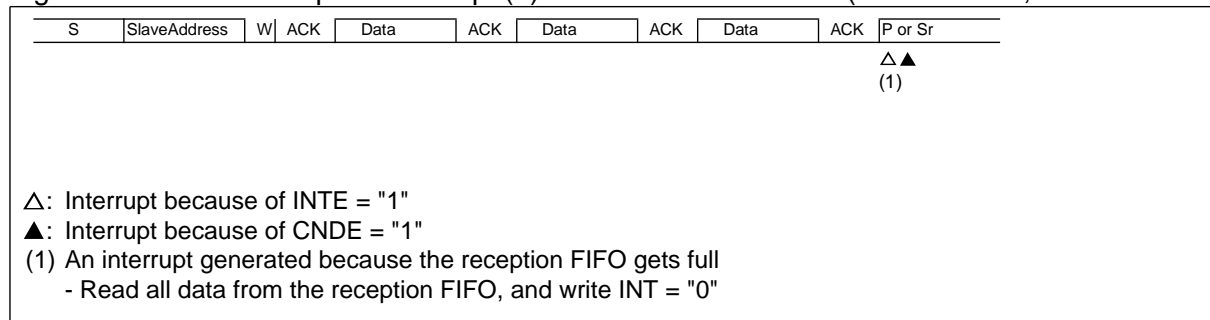


Figure 8-44 Slave Reception Interrupt (6)-when FIFO is Enabled (SSR:DMA=0, IBCR:WSEL=0, IBSR:RSA=1)

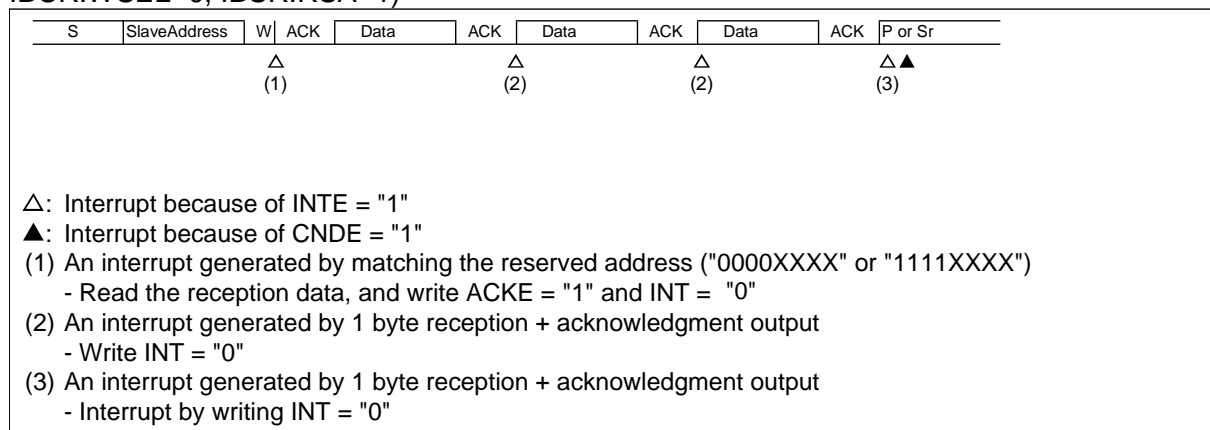


Figure 8-45 Slave Reception Interrupt (7)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=0)

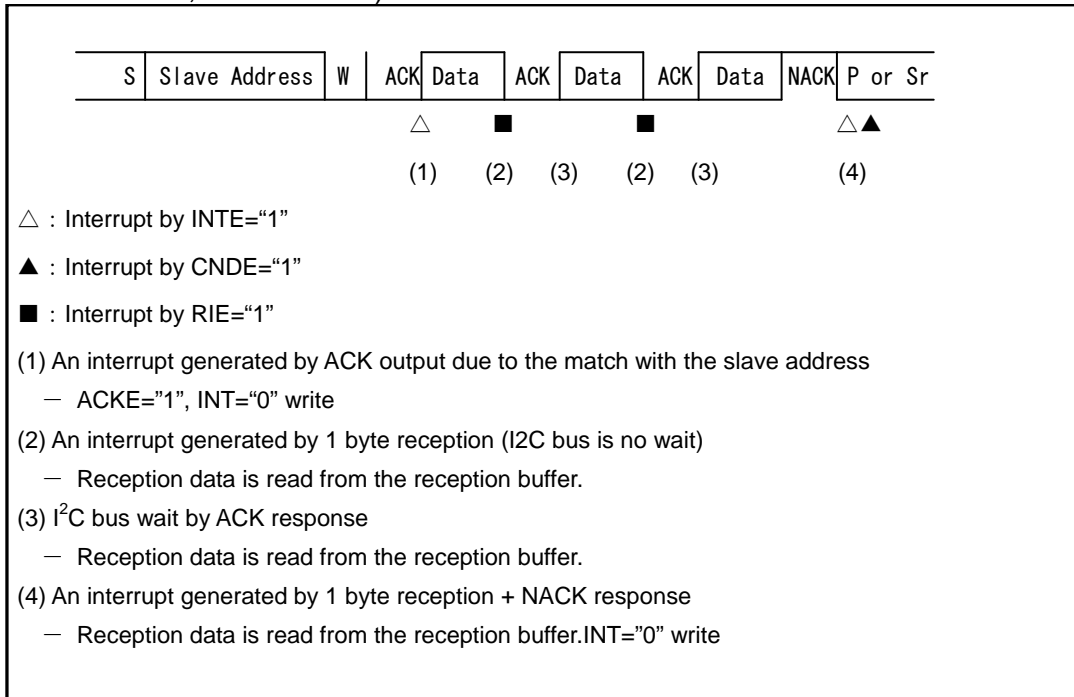


Figure 8-46 Slave Reception Interrupt (8)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0)

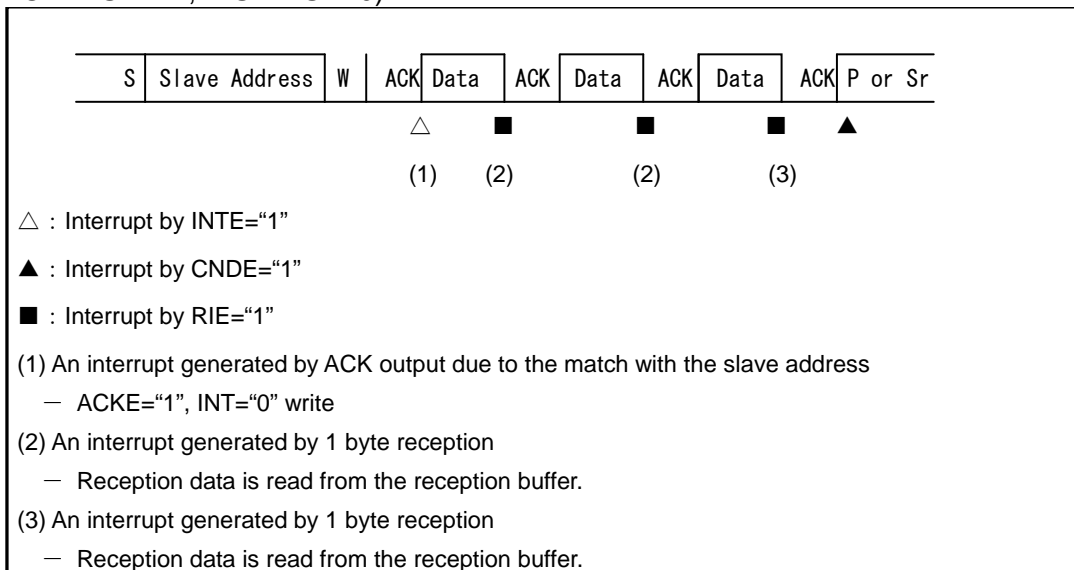


Figure 8-47 Slave Reception Interrupt (9)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=1, IBSR:RSA=0)

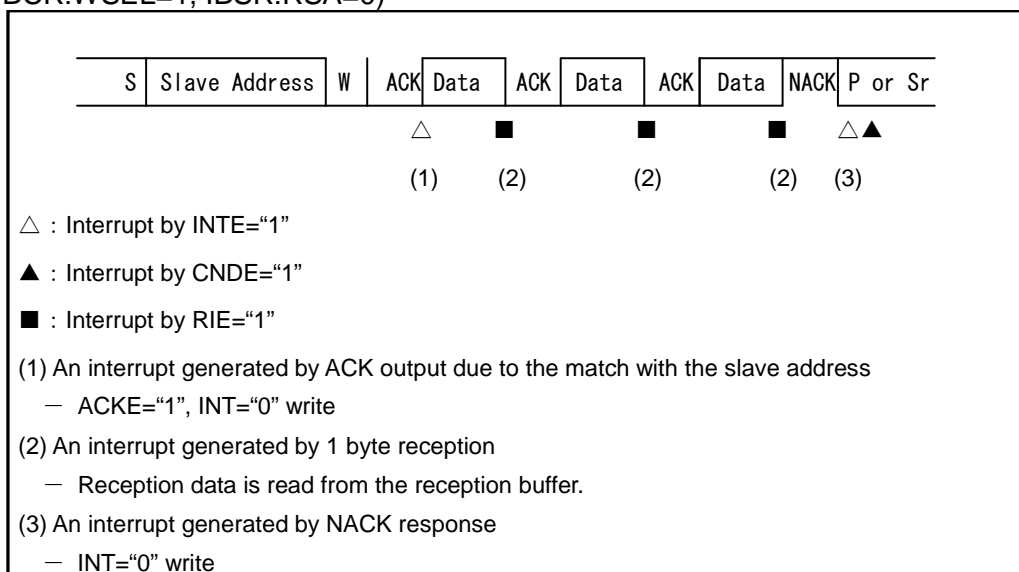


Figure 8-48 Slave Reception Interrupt (10)-when Reception FIFO is Enabled (SSR:DMA=1, IBSR:RSA=0)

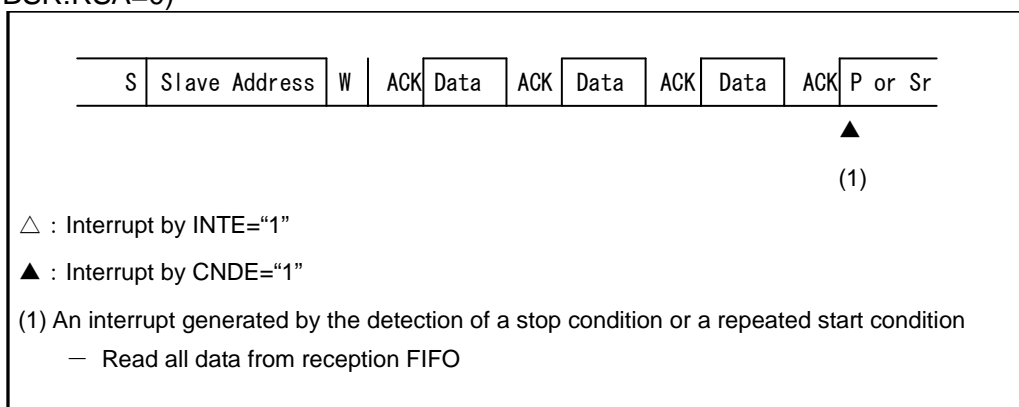


Figure 8-49 Slave Reception Interrupt (11)-when Reception FIFO is Enabled (SSR:DMA=1, IBSR:RSA=0)

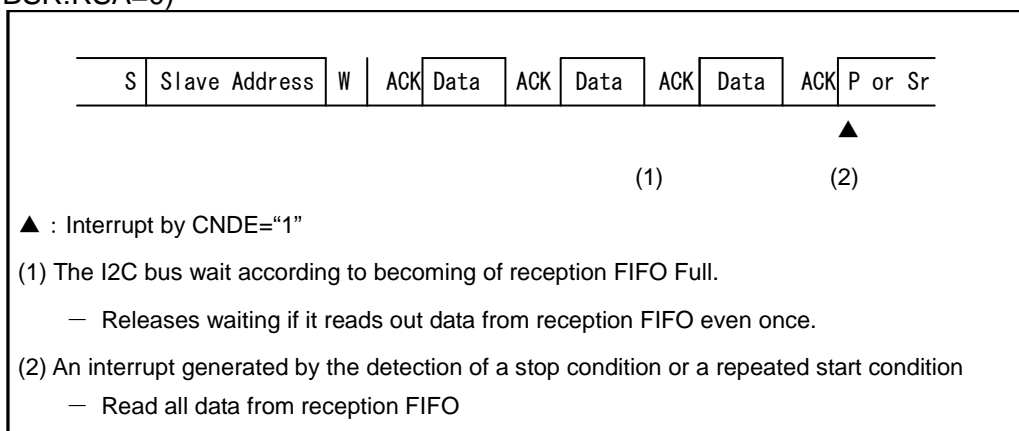
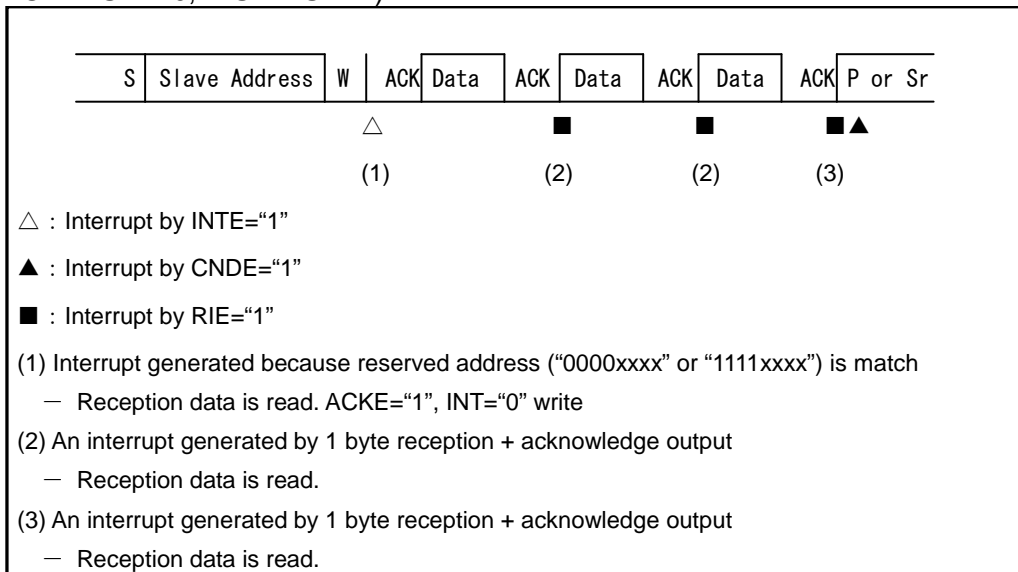


Figure 8-50 Slave Reception Interrupt (12)-when FIFO is Disabled (SSR:DMA=1, IBCR:WSEL=0, IBSR:RSA=1)



8.4.4. Transmission by Slave Device

Data transmission by the slave device is shown below.

If the slave address matches and if the data direction bit is "1", it indicates the data transmission in the slave mode. If the FIFO operation is disabled, the interrupt flag (IBCR:INT) is set to "1" and a wait is generated based on the IBCR:WSEL setting after sending one byte of data or after acknowledgement. (See "Table 8-9 Operations Immediately After Slave Address Acknowledgment").

The IBSR:RACK bit is used to check an acknowledgement by the master device. If the master returns a NACK response, it indicates that the master has failed to receive data or the data reception has completed. If a NACK signal is detected when the IBCR:WSEL bit is "1", an interrupt will occur and wait will be generated.

8.5. Bus Error

The bus error is shown below.

When the stop condition and the start(repetition) condition are detected while sending and receiving data on the I²C bus, it is treated as an bus error.

8.5.1. Bus Error Generation Condition

The bus error generation condition is shown below.

The bus error makes the IBCR:BER bit "1" on the following conditions.

- The start(repetition) condition or the stop condition is detected while forwarding the first byte.
- The start(repetition) condition or the stop condition is detected by 2nd to 9th(acknowledge) bit of data.

8.5.2. Bus Error Operation

The bus error Operation is shown below.

Confirm the IBCR:BER bit when the interrupt flag (IBCR:INT) by sending and receiving becomes "1", and do error processing when the IBCR:BER bit is "1". The IBCR:BER bit is cleared by writing "0" in the IBCR:INT bit.

SCL of the I²C bus is made "L" and it doesn't do to the wait state though the IBCR:INT bit is set in "1" by the bus error.

8.6. Example of I²C Flowchart

The example of I²C Flowchart is shown below.

8.6.1. Example of I²C Flowchart (FIFO Memory Not Used) (When DMA mode is disable (SSR: DMA=0))

Figure 8-51 Example of I²C Flowchart (FIFO Memory Not Used) (When DMA mode is disable (SSR: DMA=0))1/3

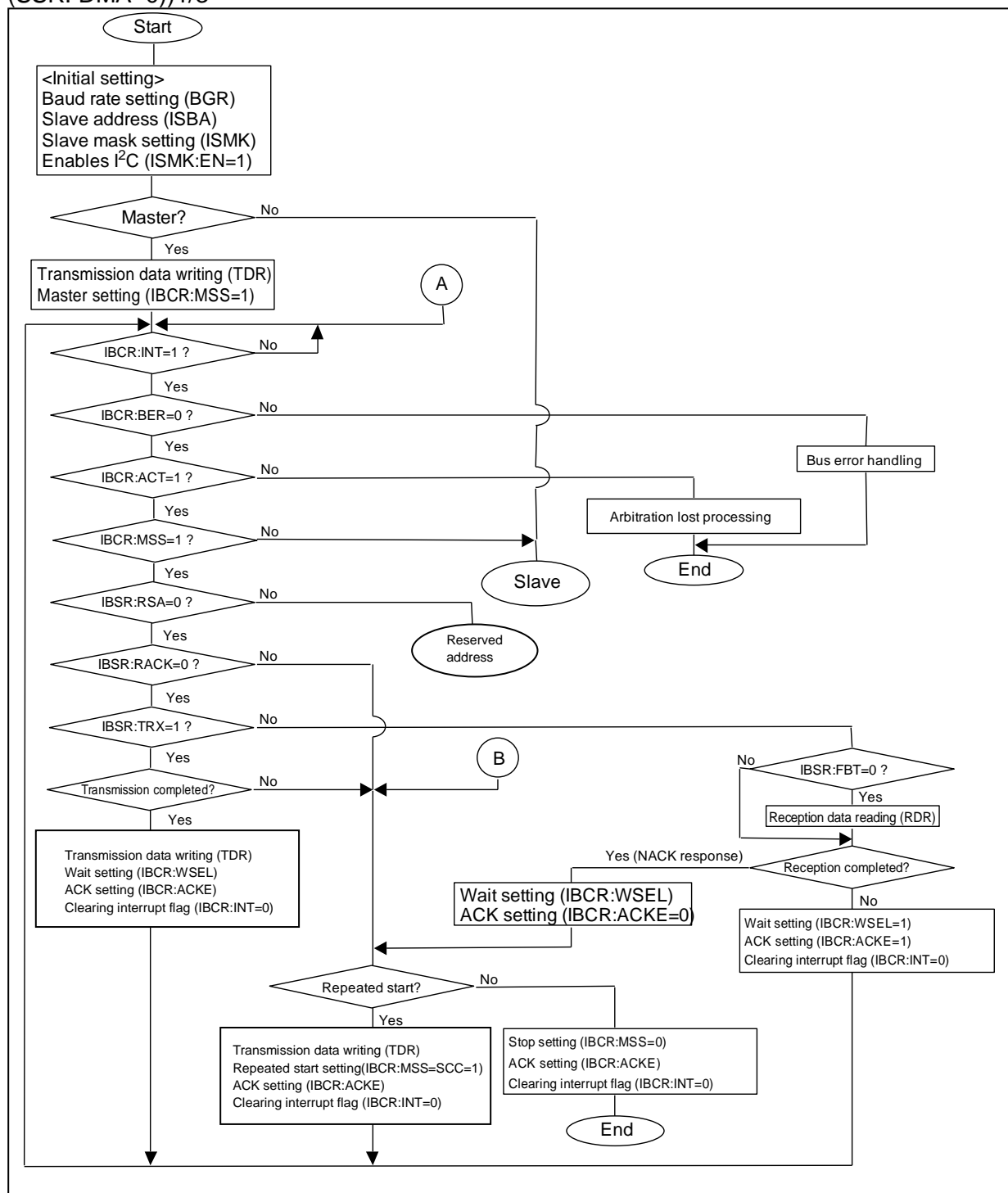


Figure 8-52 Example of I²C Flowchart (FIFO Memory Not Used) (When DMA mode is disable (SSR: DMA=0)) 2/3

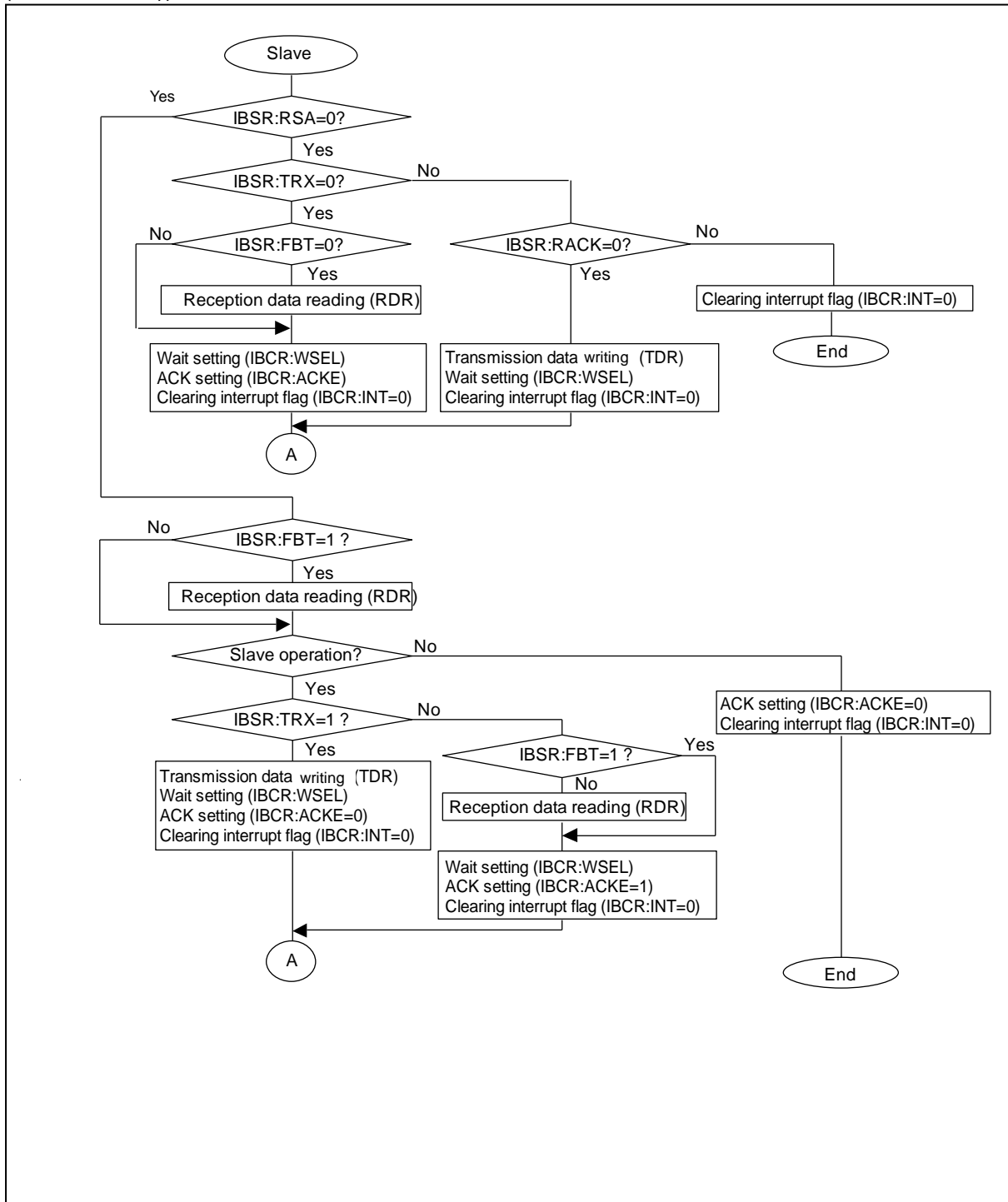
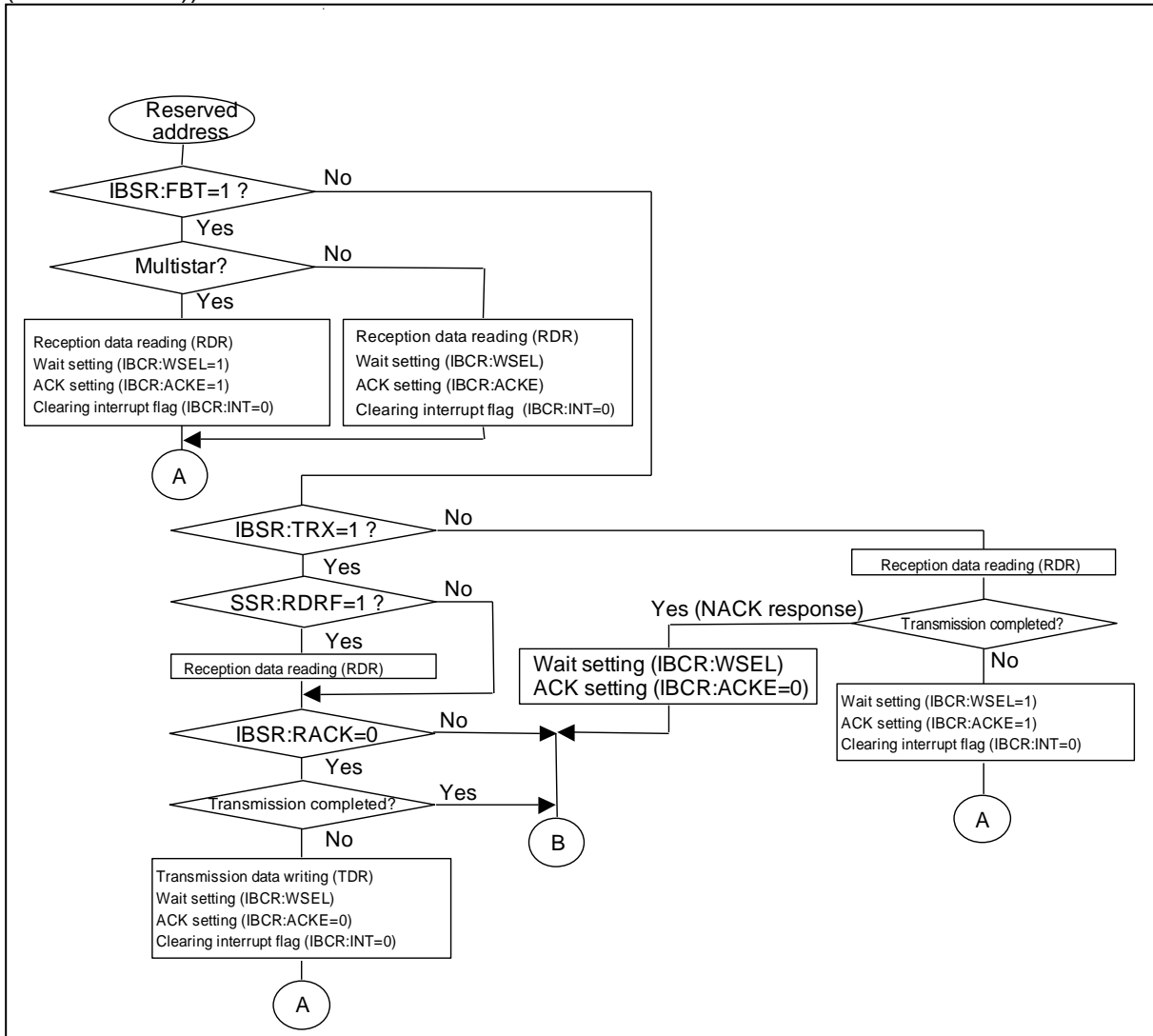


Figure 8-53 Example of I²C Flowchart (FIFO Memory Not Used) (When DMA mode is disable (SSR: DMA=0)) 3/3



8.6.2. Example of I²C Flowchart (FIFO Memory Not Used) (When DMA mode is enable (SSR: DMA=1))

Figure 8-54 Example of I²C flowchart (FIFO Not used) (When DMA mode is enable (SSR: DMA=1)1/4

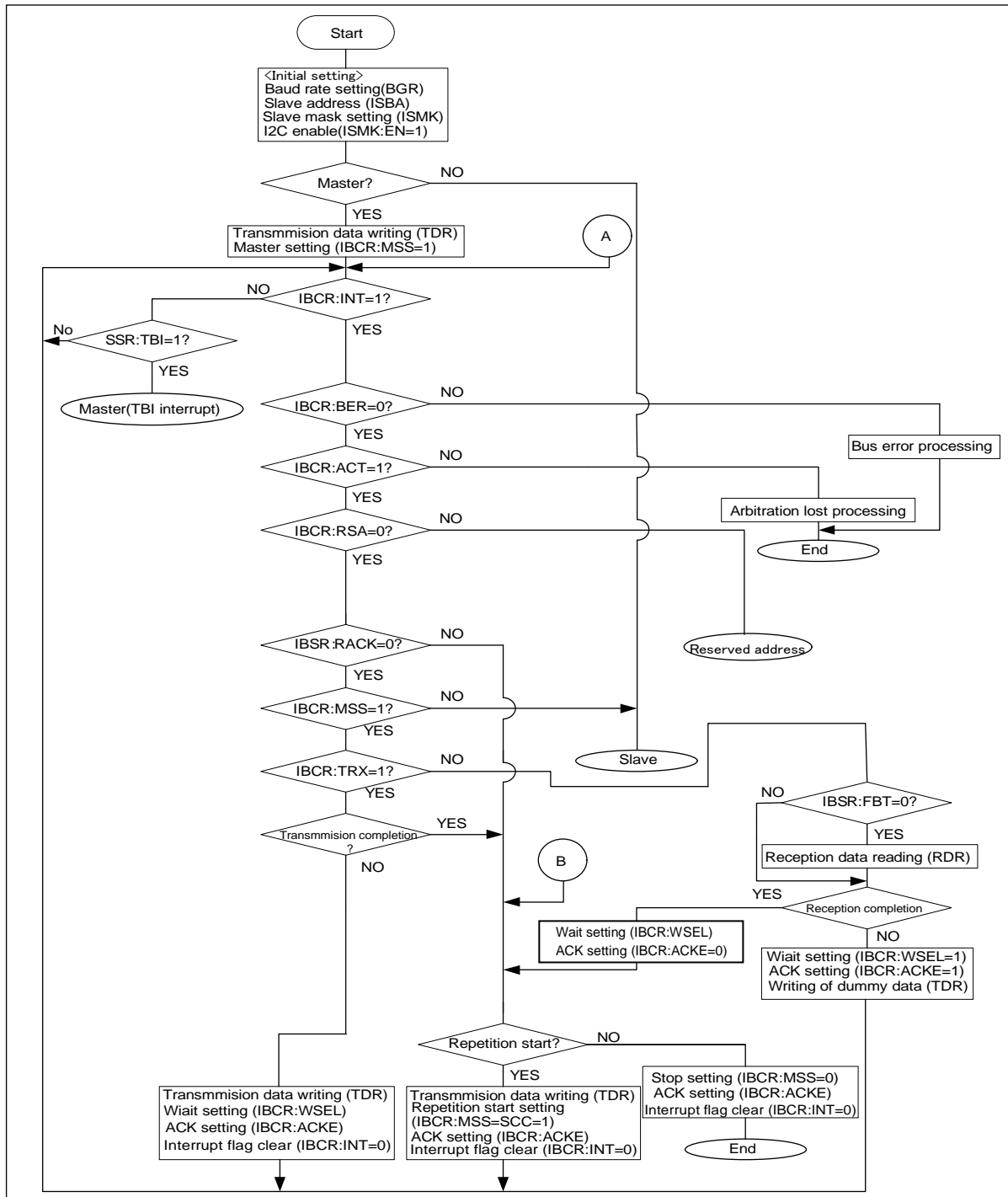


Figure 8-55 Example of I²C flowchart (FIFO Not used) (When DMA mode is enable (SSR: DMA=1) 2/4

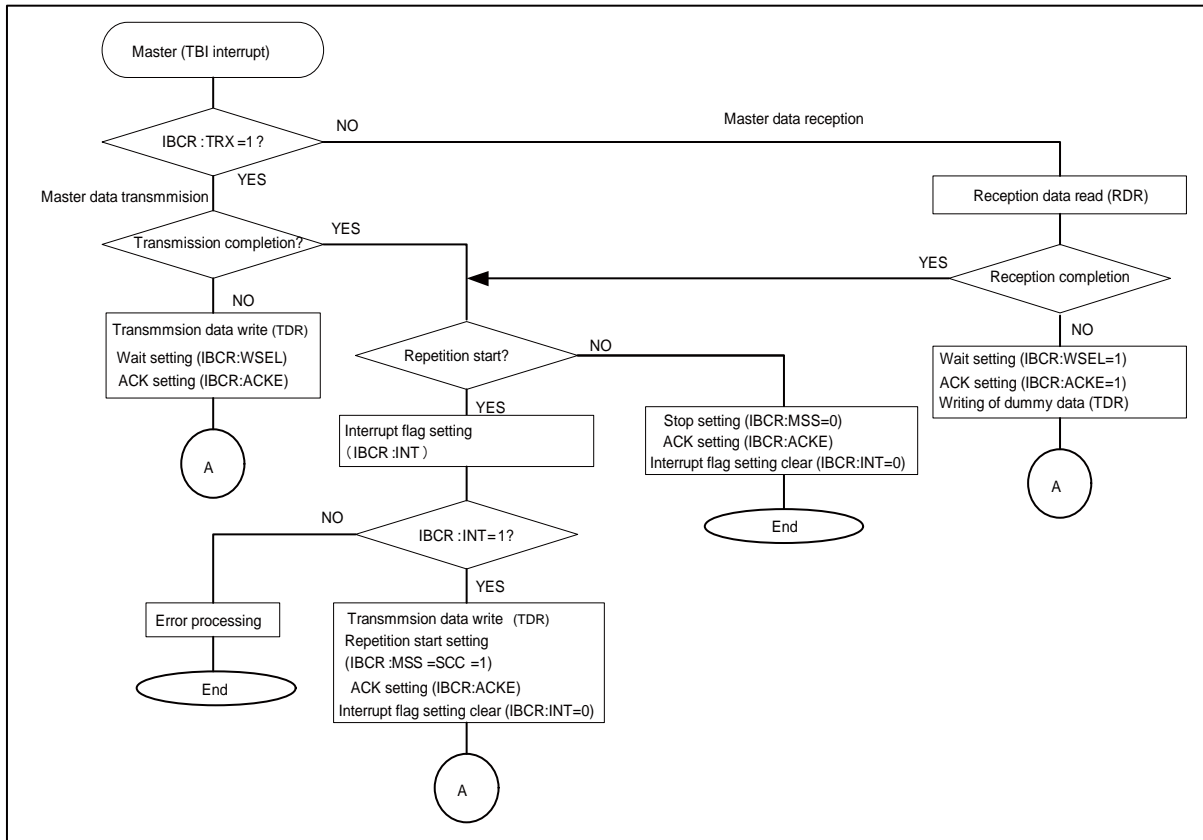


Figure 8-56 Example of I²C flowchart (FIFO Not used) (When DMA mode is enable (SSR:DMA=1)) 3/4

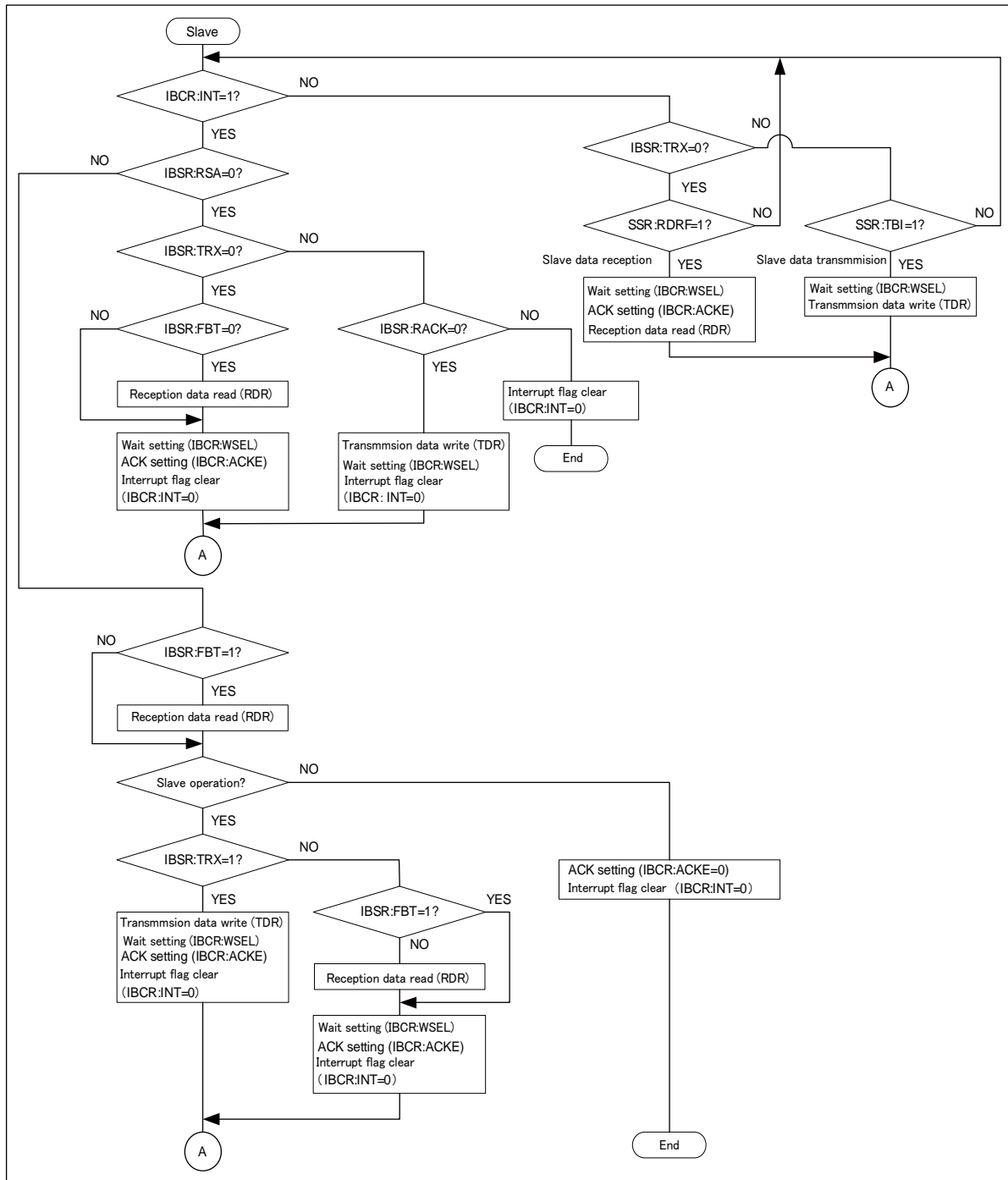
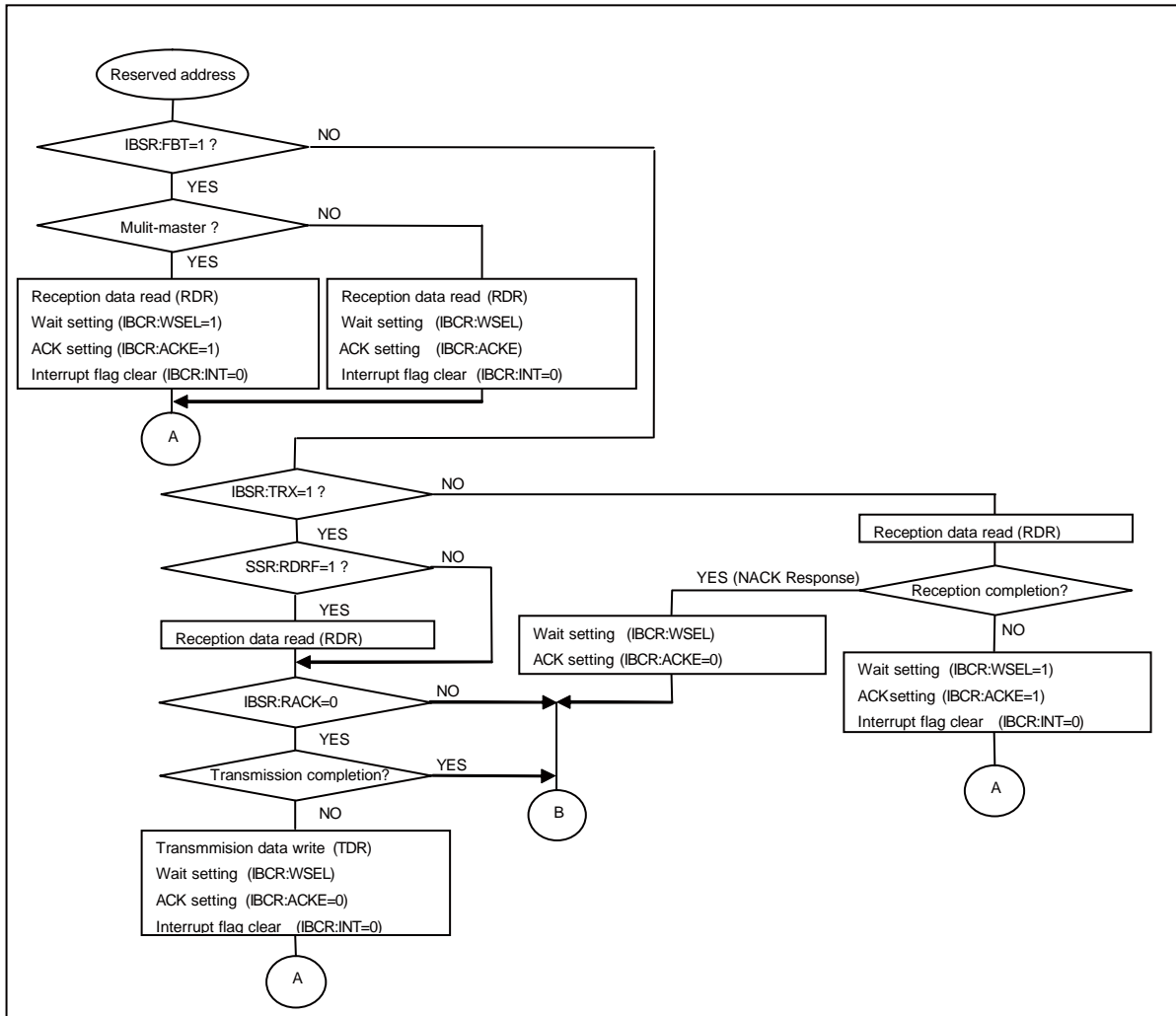


Figure 8-57 Example of I²C flowchart (FIFO Not used) (When DMA mode is enable (SSR:DMA=1)) 4/4



Note:

Flow is flow that shows the operation setting outline by the I²C mode. It is necessary to do processing that considers error processing etc. to the application.

CHAPTER : LIN-UART

This chapter explains the LIN-UART.

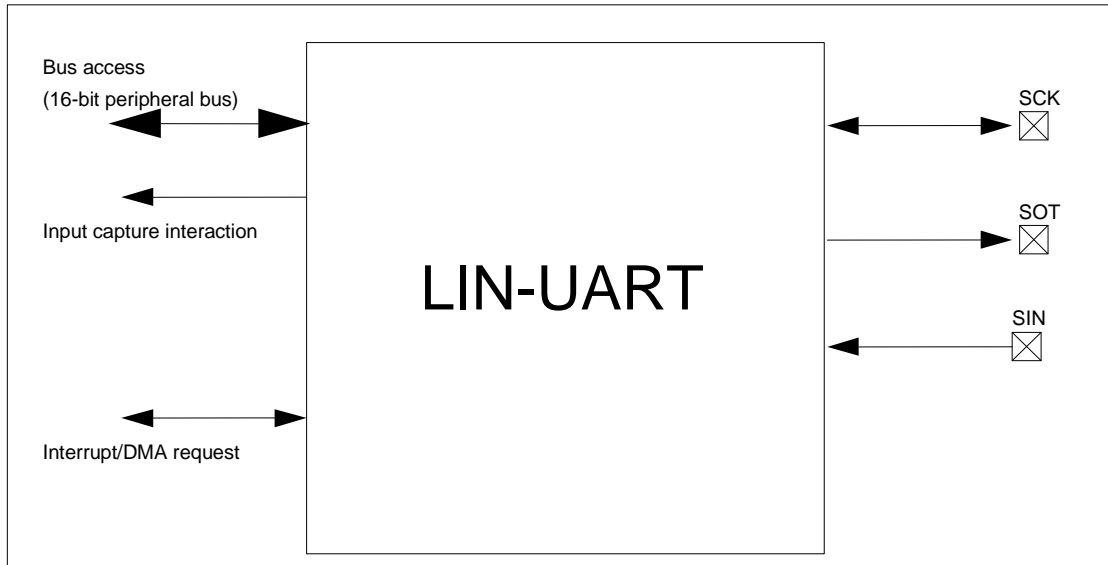
1. Overview
2. Features
3. Configuration
4. Registers
5. Interrupts
6. Baud Rates
7. Operation
8. Notes on Usage
9. Notes on DMAC Linkage Operation

1. Overview

This section explains the overview of the LIN-UART.

The LIN (Local Interconnect Network) supported UART (Universal Asynchronous Receiver and Transmitter) is a general-purpose serial data communication interface to allow synchronous or asynchronous communication with external devices. It supports the bidirectional communication function (normal mode), the master/slave type communication function (multi-processor mode: both master and slave are supported) and the LIN bus system (operable for both master and slave).

Figure 1-1 Block Diagram (Overview for 1 Channel)



2. Features

This section explains the features of the LIN-UART.

LIN-UART is the general-purpose serial data communication interface used to transmit/receive data with another CPU or external devices, especially a LIN device.

2.1. Functions

This section the explains functions of the LIN-UART.

Table 2-1 LIN-UART Functions

Item	Function
Data buffer	Full-duplex buffering
Serial input	Execute over-sampling for five times and determine the reception value by the majority of the sampling value.(Asynchronous mode only)
Transfer mode	<ul style="list-style-type: none"> · Clock synchronous (Start/stop synchronous, start/stop bit select) · Clock asynchronous (Start/stop bit available)
Baud rate	<ul style="list-style-type: none"> · Dedicated baud rate generator provided (comprising of 15-bit reload counter) · An external clock can be entered. It can also be adjusted by the reload counter.
Data length	<ul style="list-style-type: none"> · 7 bits (except for synchronous or LIN mode) · 8 bits
Signaling system	NRZ (Non Return to Zero)
Start bit timing	Synchronized with a falling edge of the start bit in asynchronous mode
Reception error detection	<ul style="list-style-type: none"> · Framing error · Overrun error · Parity error
Interrupt request	<ul style="list-style-type: none"> · Reception interrupt (Reception completion, reception error detection, LIN synch break detection) · Transmission interrupt (Transmission data empty) · Interrupt request to input capture (LIN synch field detection: LSYN)
Master/Slave Communication Function (Multi-processor Mode)	The "1-to-n" communication (between 1 master and multiple slave systems) can be performed. (both master and slave systems are supported)
Synchronous mode	Master or slave function
Pin access	The serial I/O pin state can be read and written directly.
LIN bus option	<ul style="list-style-type: none"> · Master device operation · Slave device operation · LIN synch break generation · LIN synch break detection · Detects the start/stop edge of LIN Synch field by input capture 0, 1, 2, 3, 4 or 5. (See the section "4.4" in the "CHAPTER : INPUT CAPTURE".) Supports LIN protocol Revision 2.1
Synchronous serial clock	Continuous clock output to the SCK pin is allowed for synchronous communication using start/stop bits.
Clock delay option	Special synchronous clock mode for clock delay (effective for SPI)

2.2. Operation Mode

This section the explains operation mode of the LIN-UART.

LIN-UART supports four operation modes, and the operation mode is determined using the MD0 and MD1 bits of the serial mode register (SMR). Mode 0 and 2 are used for bidirectional serial communication, and mode 1 is used for master/slave communication. Mode 3 is used for LIN master/slave communication.

Table 2-2 LIN-UART Operation Mode

Operation mode	Data length		Synchronous system	Stop bit length	Data bit format
	Parity No	Parity Yes			
0	Normal mode	7 or 8 bits		Asynchronous	1 bit or 2 bits
1	Multi-processor mode	7 bits or 8 bits + 1 bit (*1)	—		
2	Normal mode	8 bits		Synchronous	No, 1 bit, 2 bits
3	LIN Mode	8 bits	—	Asynchronous	1 bit or 2 bits

-: Setting is prohibited

*1: In the multi-processor mode, "+1" is used as a communication control address/data selection bit (AD).

Note:

Mode 1 (Multi-processor mode), when the master/slave are connected, supports the operation of both master and slave. In mode 3, communication format is fixed. If the current mode is changed, LIN-UART stops the data transmission or reception and waits for the start of the next communication.

The following table shows the operation modes to be set by MD1 and MD0 bits of the serial mode register (SMR).

Table 2-3 Mode Bit Settings

MD1	MD0	mode	Function
0	0	0	Asynchronous (normal mode)
0	1	1	Asynchronous (multi-processor mode)
1	0	2	Synchronous (normal mode)
1	1	3	Asynchronous (LIN mode)

3. Configuration

This section explains the configuration of the LIN-UART.

The following explains the configuration of the LIN-UART.

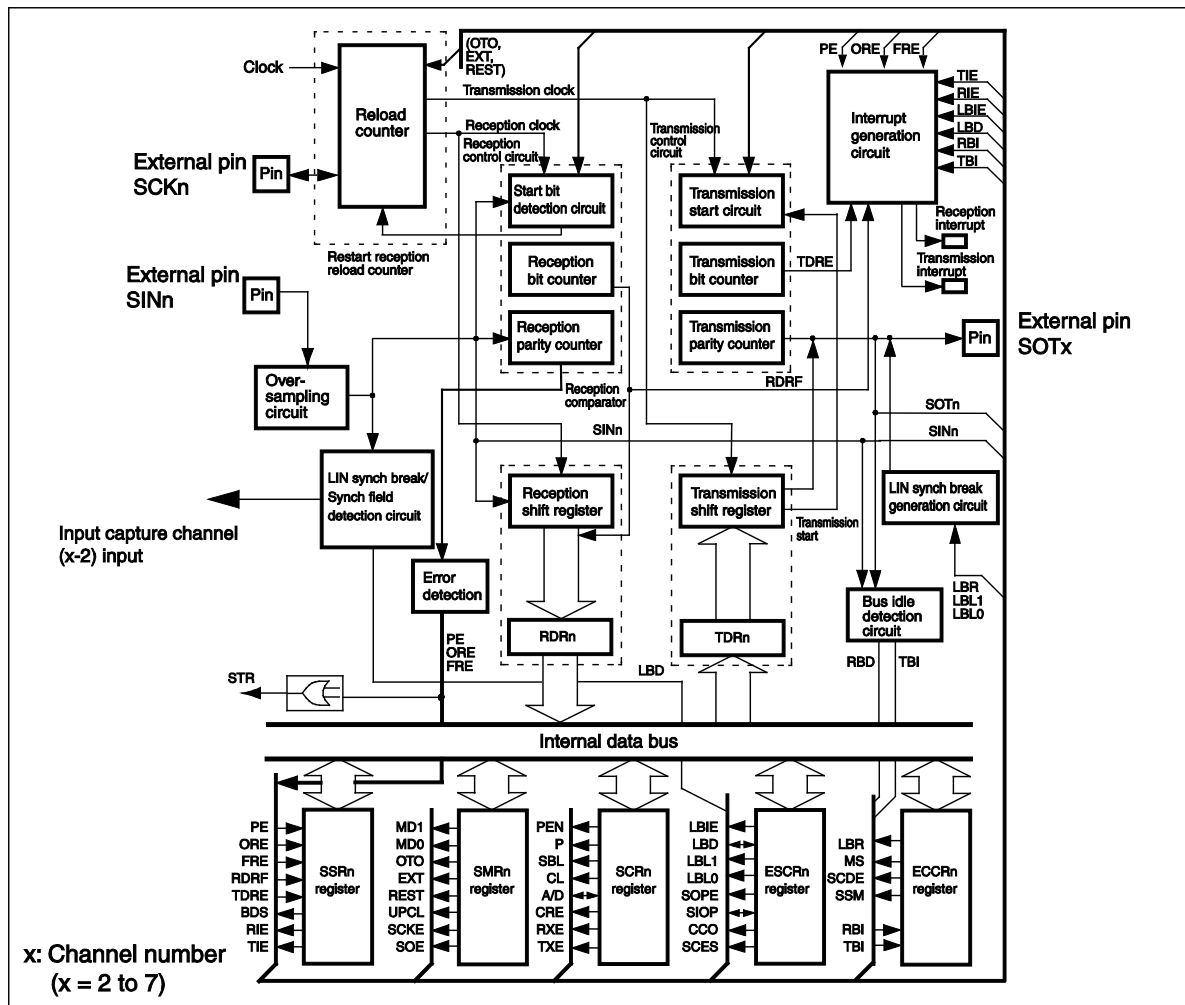
3.1. Block Diagram of the LIN-UART

This section explains the block diagram of the LIN-UART.

LIN-UART consists of the following functional blocks.

- Reload counter
- Reception control circuit
- Reception shift register
- Reception data register (RDR)
- Transmission control circuit
- Transmission shift register
- Transmission data register (TDR)
- Error detection circuit
- Over-sampling circuit
- Interrupt generation circuit
- LIN synch break or LIN synch field detection circuit
- Bus idle detection circuit
- Serial mode register (SMR)
- Serial control register (SCR)
- Serial status register (SSR)
- Extended communication control register (ECCR)
- Extended status control register (ESCR)

Figure 3-1 Block Diagram of the LIN-UART



3.2. Explanation of Each Block

This section explains each block of the LIN-UART.

- 3.2.1 Reload Counter
- 3.2.2 Reception Control Circuit
- 3.2.3 Reception Shift Register
- 3.2.4 Reception Data Register (RDR)
- 3.2.5 Transmission Control Circuit
- 3.2.6 Transmission Shift Register
- 3.2.7 Transmission Data Register (TDR)
- 3.2.8 Error Detection Circuit
- 3.2.9 Over-sampling Circuit
- 3.2.10 Interrupt Generation Circuit
- 3.2.11 LIN Synch Break/LIN Synch Field Detection Circuit
- 3.2.12 LIN Synch Break Generation Circuit
- 3.2.13 Bus Idle Detection Circuit
- 3.2.14 Serial Mode Register (SMR)
- 3.2.15 Serial Control Register (SCR)
- 3.2.16 Serial Status Register (SSR)
- 3.2.17 Extended Status Control Register (ESCR)
- 3.2.18 Extended Communication Control Register (ECCR)

3.2.1. Reload Counter

This section explains the reload counter of the LIN-UART.

The reload counter functions as the dedicated baud rate generator. The transmission/reception clocks are generated from either external or internal clocks. The reload counter has a 15-bit register as a reload value. The count value of the transmission reload counter can be read from the BGR value.

3.2.2. Reception Control Circuit

This section explains the reception control circuit of the LIN-UART.

The reception control circuit consists of the reception bit counter, the start bit detection circuit, and the reception parity counter.

The reception bit counter counts up the reception data. When a single data having the specified data length is received, the reception data full flag bit (SSR:RDRF) is set. If the reception interrupt is enabled (SSR:RIE=1) at this time, a reception interrupt request is generated.

The start bit detection circuit detects a start bit in the serial input signal, and sends a signal to the reload counter in synchronization with a falling edge of the start bit.

The reception parity counter calculates the parity of the reception data.

3.2.3. Reception Shift Register

This section the explains reception shift register of the LIN-UART.

The reception shift register the retrieves reception data entered from the SIN pin by bit shifting. When the data reception is completed, the reception shift register transfers the reception data to the reception data register (RDR).

3.2.4. Reception Data Register (RDR)

This section explains the reception data register (RDR) of the LIN-UART.

The reception data register holds the reception data. The serial input data is converted and stored in the reception data register.

3.2.5. Transmission Control Circuit

This section explains the transmission control circuit of the LIN-UART.

The transmission control circuit consists of the transmission bit counter, the transmission start circuit, and the transmission parity counter.

The transmission bit counter counts up the transmission data bits, and sends a single data having the specified data length. When the transmission bit counter indicates a start of transmission of the written data, the flag of the serial status register is set. If the transmission interrupt is enabled at this time, a transmission interrupt request is generated. The transmission start circuit starts transmitting data when it is written in the TDR.

The transmission parity counter generates a parity bit of the transmission data if parity has been specified.

3.2.6. Transmission Shift Register

This section explains the transmission shift register of the LIN-UART.

The transmission shift register shifts the transmission data that has been written in the transmission data register (TDR), and outputs the data in bits to the SOT pin.

3.2.7. Transmission Data Register (TDR)

This section explains the transmission data register (TDR) of the LIN-UART.

The transmission data is set in the transmission data register. The data written in the transmission data register is converted into serial data and output.

3.2.8. Error Detection Circuit

This section explains the error detection circuit of the LIN-UART.

This circuit detects whether an error has occurred at the end of data reception. If an error has occurred, this circuit sets the corresponding error flag.

3.2.9. Over-sampling Circuit

This section explains the over-sampling circuit of the LIN-UART.

In the asynchronous mode, this circuit executes over-sampling five times with the machine clock and determines the reception value by the majority of the sampling value. This circuit does not operate in the synchronous mode.

3.2.10. Interrupt Generation Circuit

This section explains the interrupt generation circuit of the LIN-UART.

This circuit controls all interrupt factors. If a corresponding interrupt enable bit has been set, an interrupt occurs immediately.

3.2.11. LIN Synch Break/LIN Synch Field Detection Circuit

This section explains the LIN synch break/LIN synch field detection circuit of the LIN-UART.

When the LIN master node transmits a message header, a LIN synch break is detected. If a LIN synch break is detected, the LBD flag bit is set. An internal signal (LSYN) is output to the input capture in order to detect the 1st and 5th falling edges of the LIN synch field signal and to measure the actual serial clock synchronization signal that is transmitted by the master node.

3.2.12. LIN Synch Break Generation Circuit

This section explains the LIN synch break generation circuit of the LIN-UART.

This circuit generates a LIN synch break of length selected by the LIN synch break length select bit of the extended status control register.

3.2.13. Bus Idle Detection Circuit

This section explains the bus idle detection circuit of the LIN-UART.

This circuit detects that no transmission/reception is in progress, and sets the TBI or RBI flag bit.

3.2.14. Serial Mode Register (SMR)

This section explains the serial mode register.

The serial mode register is used to:

- Select a LIN-UART operation mode.
- Select a clock input.
- Select either "1-to-1" connection or reload counter connection for the external clock.
- Reactivate the dedicated reload timer.
- Reset the LIN-UART software (by keeping the register settings).
- Enable/disable output to the serial data pin (SOT).
- Enable/disable output to the serial clock pin (SCK).

3.2.15. Serial Control Register (SCR)

This section explains the serial control register.

The serial control register is used to:

- Select whether or not to use parity bits.
- Select a parity bit.
- Set the stop bit length.
- Set the data length.
- Select a frame data format in mode 1.
- Clear the error flag.
- Enable/disable data transmission.
- Enable/disable data reception.

3.2.16. Serial Status Register (SSR)

This section explains the serial status register.

The SSR is used to:

- Check the data transmission/reception and error state.
- Select the LSB First or MSB First data transfer direction.
- Enable/disable the transmission interrupt.
- Enable/disable the reception interrupt.

3.2.17. Extended Status Control Register (ESCR)

This section explains the extended status control register.

The ESCR is used to:

- Enable/disable the LIN synch break interrupt.
- Detect a LIN synch break
- Select the LIN synch break length.
- Directly access the SINn or SOTn pin.
- Set the continuous clock output in the LIN-UART synchronous clock mode.
- Select a sampling clock edge.

3.2.18. Extended Communication Control Register (ECCR)

This section explains the extended communication control register.

The ECCR is used to:

- Detect thebus idle status.
- Set t asynchronous clock.
- LIN synch break generation

4. Registers

This section explains the registers of the LIN-UART.

■ List of Base_addresses (Base_addr) and External Pins

Channel number	Base_addr	External pin name		
		SIN	SOT	SCK
2	0x00D0	SIN2 / SIN2_1	SOT2 / SOT2_1	SCK2 / SCK2_1
3	0x00D8	SIN3 / SIN3_1	SOT3 / SOT3_1	SCK3 / SCK3_1
4	0x00E0	SIN4 / SIN4_1	SOT4 / SOT4_1	SCK4 / SCK4_1
5	0x00E8	SIN5 / SIN5_1	SOT5 / SOT5_1	SCK5 / SCK5_1
6	0x00F0	SIN6	SOT6	SCK6
7	0x00F8	SIN7_1	SOT7_1	SCK7_1

Select an external pin to be used for channels 2 to 5, using the IO relocation function.

■ **Registers Map**

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x00D0	SCR2	SMR2	SSR2	RDR2/TDR2	Serial control register 2 Serial mode register 2 Serial status register 2 Transmission/reception data register 2
0x00D4	ESCR2	ECCR2	BGR2		Extended status control register 2 Extended communication control register 2 Baud rate generator register 2
0x00D8	SCR3	SMR3	SSR3	RDR3/TDR3	Serial control register 3 Serial mode register 3 Serial status register 3 Transmission/reception data register 3
0x00DC	ESCR3	ECCR3	BGR3		Extended status control register 3 Extended communication control register 3 Baud rate generator register 3
0x00E0	SCR4	SMR4	SSR4	RDR4/TDR4	Serial control register 4 Serial mode register 4 Serial status register 4 Transmission/reception data register 4
0x00E4	ESCR4	ECCR4	BGR4		Extended status control register 4 Extended communication control register 4 Baud rate generator register 4
0x00E8	SCR5	SMR5	SSR5	RDR5/TDR5	Serial control register 5 Serial mode register 5 Serial status register 5 Transmission/reception data register 5
0x00EC	ESCR5	ECCR5	BGR5		Extended status control register 5 Extended communication control register 5 Baud rate generator register 5
0x00F0	SCR6	SMR6	SSR6	RDR6/TDR6	Serial control register 6 Serial mode register 6 Serial status register 6 Transmission/reception data register 6
0x00F4	ESCR6	ECCR6	BGR6		Extended status control register 6 Extended communication control register 6 Baud rate generator register 6
0x00F8	SCR7	SMR7	SSR7	RDR7/TDR7	Serial control register 7 Serial mode register 7 Serial status register 7 Transmission/reception data register 7

Address	Registers				Register function
	+0	+1	+2	+3	
0x00FC	ESCR7	ECCR7	BGR7		Extended status control register 7 Extended communication control register 7 Baud rate generator register 7

4.1. Serial Control Register : SCR

The bit configuration of the serial control register is shown below.

The serial control register (SCR) is used to set the parity bit, select the stop bit length and the data length, select the frame data format in mode 1, clear the reception error flag, and enable/disable data transmission and reception.

■ SCR: Address Base_addr + 00_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PEN	P	SBL	CL	AD	CRE	RXE	TXE
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R,W	R0,W	R/W	R/W

[bit7] PEN : Parity enable bit

PEN	Parity enable
0	Without parity [initial value]
1	With parity

This bit configures whether to enable addition (transmission) and detection (reception) of the parity bit.

The parity bit is added only when the start/stop is set in mode 0 or mode 2 (ECCR:SSM="1"). This bit is fixed to "0" in modes 1 and 3.

[bit6] P : Parity selection bit

P	Parity selection
0	Even parity [initial value]
1	Odd parity

If with parity (PEN=1), select either odd parity "1" or even parity "0".

[bit5] SBL : Stop bit length selection bit

SBL	Stop bit length
0	1 bit [initial value]
1	2 bits

This bit selects the length of the stop bit (the frame end mark of the transmission data) in the case where the start/stop bit is set to be used (ECCR:SSM=1) in operation mode 0, 1 or 3 (asynchronous) or in operation mode 2 (synchronous).

Note:

On reception, the framing error is detected only by one bit of the stop bit.

[bit4] CL : Data length selection bit

CL	Data length selection
0	7 bits [initial value]
1	8 bits

This bit specifies the data length of the transmission/reception data. This bit is fixed to "1" in mode 2 and mode 3.

[bit3] AD : Address/data format selection bit

AD	Address/data format selection
0	Data frame [initial value]
1	Address frame

This bit sets the data format to be used in the multi-processor mode (mode 1). The last received data format value is used for reading.

Note:

The AD bit read value is undefined in any mode other than the multi-processor mode (mode 1). To use the AD bit, see "8. Notes on Usage".

[bit2] : Reception error flag clear bit

CRE	Clearing of reception error	
	Write	Read
0	No effect [initial value]	The read value is always "0".
1	Clears all reception errors (PE, FRE and ORE).	

This bit clears the PE, FRE, and ORE flags of the serial status register (SSR).

Note:

Clear the reception error flag after the reception operation is disabled (RXE=0).

[bit1] RXE : Reception enable bit

RXE	Reception enable
0	Reception disabled [initial value]
1	Reception enabled

This bit enables/disables the LIN-UART reception. If this bit is set to "0", the data frame reception is disabled. This bit does not affect the LIN synch break detection in mode 3.

Note:

If you disable reception (RXE=0) while a reception is in progress, the reception stops immediately. In this case, the data cannot be guaranteed.

[bit0] TXE : Transmission enable bit

TXE	Transmission enable
0	Transmission disabled [initial value]
1	Transmission enabled

This bit enables the LIN-UART transmission. If this bit is set to "0", the data frame transmission is disabled. This bit does not affect the LIN synch break detection in mode 3.

Note:

If you disable transmission (TXE=0) while it is in progress, the transmission stops immediately. In this case, the data cannot be guaranteed.

4.2. Serial Mode Register : SMR

The bit configuration of the serial mode register (SMR) is shown below.

The serial mode register (SMR) is used to select the operation mode and baud rate clock. Also, this register is used to enable/disable output to the serial data and clock pin.

■ SMR: Address Base_addr + 01_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MD1	MD0	OTO	EXT	REST	UPCL	SCKE	SOE
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R0,W	R0,W	R/W	R/W

[bit7, bit6] MD1, MD0 : Operation mode selection bits

MD1	MD0	Operation mode setting
0	0	Mode 0: Asynchronous normal mode [initial value]
0	1	Mode 1: Asynchronous multi-processor mode
1	0	Mode 2: Synchronous mode
1	1	Mode 3: Asynchronous LIN mode

These bits set the LIN-UART operation mode.

Note:

The communication mode must be changed while the LIN-UART operation is inactive. If the mode is changed while transmission or reception is in progress, the transmitted/received data cannot be guaranteed. If the mode is changed after writing data to the transmission data register (TDR), the data written to the TDR becomes invalid and the transmission data empty flag is set (SSR:TDRE=1).

[bit5] : 1 to 1 external clock enable bit

OTO	External clock enabled
0	Uses the baud rate generator (reload counter). [initial value]
1	Uses an external clock directly.

If this bit is set to "1", an external clock will be allowed to be used directly as the LIN-UART serial clock. It is used during slave operation in mode 2 (synchronous) (ECCR:MS=1).

If EXT=0, the OTO bit is fixed to "0".

[bit4] EXT : External clock selection bit

EXT	External serial clock enabled
0	Uses the baud rate generator (reload counter). [initial value]
1	Uses an external clock's serial clock source.

This bit can be used to select a clock for the reload counter.

[bit3] REST : Reload counter restart bit

REST	Reload counter restart	
	Write	Read
0	No effect [initial value]	The read value is always "0".
1	Counter restart	

[bit2] UPCL : LIN-UART programmable clear bit (software reset)

UPCL	LIN-UART programmable clear (software reset)	
	Write	Read
0	No effect [initial value]	The read value is always "0".
1	LIN-UART reset	

If this bit is set to "1", the LIN-UART is reset immediately. However, the register settings are maintained. The current transmission or reception is aborted.

All transmission/reception interrupt factors (TDRE, RDRF, LBD, PE, ORE, and FRE) are cleared. Also, the reception data register is cleared (RDR=00_H), and the reload counter is restarted.

Note:

Perform LIN-UART software reset (UPCL=1) when the TXE bit of the serial control register (SCR) is "0".

[bit1] SCKE : Serial clock output enabled

SCKE	Serial clock output enabled
0	Clock input pin [initial value]
1	Serial clock output pin

This bit controls the I/O of the serial clock pin (SCK).

If this bit is set to "1", the clock is output in mode 2.

Notes:

- When using the SCK pin for serial clock input (SCKE="0"), set the external clock selection bit to the external clock state (EXT="1") at the same time.
- Set the SCK pin as a peripheral I/O pin. For information on the setting method, see "CHAPTER : I/O PORTS".

[bit0] SOE : Serial data output enable bit

SOE	Serial data output enabled
0	Output disabled [initial value]
1	Serial data output

To transmit data from LIN-UART set this bit to "1". The initial value of this bit is "0", and there is no case in which this bit must be set to "0".

4.3. Serial Status Register :SSR

The bit configuration of the serial status register (SSR) is shown below.

The serial status register (SSR) is used to check the current transmission/reception state and error occurrence. This register is also used to control transmission/reception interrupts.

■ **SSR: Address Base_addr + 02_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	PE	ORE	FRE	RDRF	TDRE	BDS	RIE	TIE
Initial value	0	0	0	0	1	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R/W	R/W	R/W

[bit7] PE : Parity error flag bit

PE	Parity error
0	No parity error [initial value]
1	A parity error occurs during reception.

If a parity error occurs during data reception, this bit is set to "1". This flag bit is cleared to "0" if the CRE bit of the serial control register (SCR) is set to "1".

If both PE and RIE bits are set to "1", a reception interrupt request is generated.

If this flag is set, the data contained in the reception data register (RDR) becomes invalid.

[bit6] ORE : Overrun error flag bit

ORE	Overrun error
0	No overrun error [initial value]
1	An overrun error occurs during reception.

If an overrun error occurs during data reception, this bit is set to "1". This flag bit is cleared to "0" if the CRE bit of the serial control register (SCR) is set to "1".

If both ORE and RIE bits are set to "1", a reception interrupt request is generated.

If this flag is set, the data contained in the reception data register (RDR) becomes invalid.

[bit5] FRE : Framing error flag bit

FRE	Framing error
0	No framing error [initial value]
1	A framing error occurs during reception.

If a framing error occurs during data reception, this bit is set to "1". This flag bit is cleared to "0" if the CRE bit of the serial control register (SCR) is set to "1".

If both FRE and RIE bits are set to "1", a reception interrupt request is generated.

If this flag is set, the data contained in the reception data register (RDR) becomes invalid.

Note:

Only the first bit of the stop bit detects the framing error even if it sets it to SCR:SBL=1.

[bit4] RDRF : Reception data full flag bit

RDRF	Reception data register full
0	The reception data register has no data. [initial value]
1	The reception data register has data.

This bit indicates the state of the reception data register (RDR).

This bit is set to "1" when the reception data is stored in the RDR. This bit is cleared to "0" when data is read from the RDR.

If both RDRF and RIE bits are set to "1", a reception interrupt request is generated.

[bit3] TDRE : Transmission data empty flag bit

TDRE	Transmission data register empty
0	The transmission data register has data.
1	The transmission data register has no data. [initial value]

This bit indicates the state of the transmission data register (TDR).

When the transmission data is written in the TDR, this bit is set to "0" indicating that the register has the transmission data. When data is stored in the transmission shift register and the transmission is started, this bit is set to "1".

If both TDRE and TIE bits are set to "1", a transmission interrupt request is generated.

If the TDRE bit is "1" and if the LBR bit of the extended communication control register (ECCR) is set to "1", the TDRE bit is switched to "0". If the TDR register does not have any valid data after the LIN synch break generation, this bit is set to "1".

Note:

The TDRE bit is initially set to "1".

If TDRE=0 is set by data writing in the transmission data register (TDR) and if the mode setting (SMR:MD[1:0]) is changed after that, the transmission data is made invalid and TDRE=1 is set.

[bit2] BDS : Transfer direction selection bit

BDS	Bit direction setting
0	LSB First (The least significant bit is transferred first.) [initial value]
1	MSB First (The most significant bit is transferred first.)

Either LSB first (BDS="0") or MSB first (BDS="1") can be selected for serial data transfer.

This bit is fixed to "0" in mode 3.

Note:

When data is written to or read from the reception data register, the high-order and low-order sides of the reception data are replaced. If the BDS bit value is changed after data has been written in the RDR, the data will become invalid.

[bit1] RIE : Reception interrupt request enable bit

RIE	Reception interrupt enabled
0	Reception interrupt disabled [initial value]
1	Reception interrupt enabled

This bit enables or disables output of a reception interrupt request to the CPU.

If the RIE bit and the reception data flag bit (RDRF) are set to "1" or if an error flag (PE, ORE, or FRE) is set to "1", a reception interrupt request is generated.

[bit0] TIE : Transmission interrupt request enable bit

TIE	Transmission interrupt enabled
0	Transmission interrupt disabled [initial value]
1	Transmission interrupt enabled

This bit enables or disables output of a transmission interrupt request to the CPU.

If both TIE and TDRE bits are set to "1", a transmission interrupt request is generated.

4.4. Reception Data Register / Transmission Data Register : RDR / TDR

This section explains the reception data register / transmission data register (RDR/TDR).

The reception data register (RDR) holds the reception data, and the transmission data register (TDR) holds the transmission data. RDR and TDR are placed in the same address.

4.4.1. Reception Data Register : RDR

The bit configuration of the reception data register (RDR) is shown below.

■ **Reception data register (RDR):**

RDR : Address Base_addr + 03_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit7 to bit0] D[7:0] : Data registers

Access	Data register
Read	Reads data from the reception data register.

The reception data register (RDR) is the data buffer register for serial data reception.

Serial data signals sent to the serial input pin (SIN) are converted in the shift register and stored in the reception data register (RDR).

If the data length is 7 bits, the upper 1 bit (RDR:D7) is set to "0".

When the reception data is stored in the reception data register (RDR), the reception data full flag bit (SSR:RDRF) will be set to "1". When the reception interrupt is enabled (SSR:RIE=1), a reception interrupt request is generated.

The reception data register (RDR) should be read out when the reception data full flag bit (SSR:RDRF) is "1". The reception data full flag bit (SSR:RDRF) will be automatically cleared to "0" when the reception data register (RDR) is read out. If a reception interrupt is enabled but if no error has occurred, the reception interrupt is also cleared.

If a reception error occurs (SSR:PE, ORE or FRE "1"), the data in the reception data register (RDR) will become invalid.

4.4.2. Transmission Data Register : TDR

The bit configuration of the transmission data register (TDR) is shown below.

■ Transmission Data Register (TDR) :

TDR: Address Base_addr + 03_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	-	-	-	-	-	-	-	-
Attribute	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W	RX,W

[bit7 to bit0] D[7:0] : Data registers

Access	Data register
Write	Writes data to the transmission data register.

When the transmission data is enabled to transmit and when it is written to the transmission data register, the data is transferred to the transmission shift register and it is converted into serial data and transmitted from the serial data output pin (SOT). If the data length is 7 bits, the most significant bit (D7) is not transmitted.

When the transmission data is written to the TDR register, the transmission data empty flag bit (TDRE bit of SSR) is cleared to "0". When data transfer to the transmission shift register is complete and when the transmission starts, the TDRE bit is set to "1". If the TDRE bit is "1", the next transmission data can be written to the TDR register. If a transmission interrupt request is enabled, a transmission interrupt is generated. If a transmission interrupt has occurred or if the TDRE bit is "1", write the next data.

Note:

The TDR is a write-only register, and the RDR is a read-only register. As these registers are located in the same address, the read value and the write value differ from each other. Therefore, none of read-modify-write instructions shall be used to access these registers.

4.5. Extended Status Control Register : ESCR

The bit configuration of the extended status control register is shown below.

Extended status control register can be used to set the LIN function. Also, it can be used to set the direct access to the SIN and SOT pins and the LIN-UART synchronous clock mode.

■ ESCR: Address Base_addr + 04_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	LBIE	LBD	LBL1	LBL0	SOPE	SIOP	CCO	SCES
Initial value	0	0	0	0	0	X	0	0
Attribute	R/W	R(RM1),W	R/W	R/W	R/W	R,W	R/W	R/W

[bit7] LBIE : LIN synch break detection interrupt enable bit

LBIE	LIN synch break detection interrupt enabled
0	LIN synch break interrupt disabled [initial value]
1	LIN synch break interrupt enabled

An interrupt occurs when the LIN synch break detection flag (LBD) is set to "1" and interrupts are enabled (LBIE=1).

This bit is fixed to "0" in operation modes 1 and 2.

[bit6] LBD : LIN synch break detection flag bit

LBD	LIN synch break detection	
	Write	Read
0	Clears the LIN synch break detection flag.	Does not detect the LIN synch break. [initial value]
1	No effect	Detects the LIN synch break.

When a LIN synch break is detected (if the serial input is "0" for more than 11-bit time), this bit is set to "1". If this bit is set to "0", the LBD flag bit is cleared. If the LIN synch break detection interrupt is enabled, the interrupt is also cleared.

When a read-modify-write instruction is issued, "1" is always returned. In such case, however, it does not signify a LIN synch break detection.

Note:

To detect a LIN synch break, enable LIN synch break detection interrupt (LBIE=1) and then disable reception (SCR:RXE=0).

[bit5, bit4] LBL1, LBL0 : LIN synch break length selection bits

LBL1	LBL0	LIN synch break length
0	0	13-bit length [initial value]
0	1	14-bit length
1	0	15-bit length
1	1	16-bit length

These bits define the serial bit length of the LIN synch break generated by the LIN-UART. The length is always fixed to 11 bits for LIN synch break reception.

[bit3] SOPE : Serial output pin direct access enable bit

SOPE	Serial output pin direct access
0	Serial output pin direct access disabled [initial value]
1	Serial output pin direct access enabled

If this bit is set to "1", data can be written directly in the SOT pin.

See "Table 4-2 SOPE and SIOP Functions" for details.

[bit2] SIOP : Serial I/O pin direct access enable bit

SIOP	Serial I/O pin access	
	Write (if SOPE is "1")	Read
0	Outputs "0" at the SOT pin.	Reads value from SIN pin.
1	Outputs "1" at the SOT pin. [initial value]	

When a normal read instruction is issued, the SIN pin value is returned. Set the SOT pin value for data writing. When a read-modify-write instruction is issued, the SOT pin value is returned.

See the following table for details:

Table 4-2 SOPE and SIOP Functions

SOPE	SIOP	Writing to SIOP	Reading from SIOP
0	R/W	No effect (The write value is held.)	The SIN value is returned.
1	R/W	"0" or "1" is written in the SOT pin.	The SIN value is returned.
0	RMW	No effect (The write value is held.)	The SOT value is returned.
1	RMW	"0" or "1" is written in the SOT pin.	The SOT value is returned.

[bit1] CCO : Continuous clock output enable bit

CCO	Continuous clock output (mode 2)
0	Continuous clock output disabled [initial value]
1	Continuous clock output enabled

If the LIN-UART is set as the master system (ECCR:MS=0) in mode 2 (synchronous mode) and if the SCK pin is set for clock output, the continuous serial clock output is enabled.

Note:

Set the SCK pin to the clock output (SMR:SCKE=1). When "1" is set to the CCO bit, it changes to start/stop bit addition setting (ECCR:SSM=1).

Set "0" to this bit at the slave setting of operation modes 0, 1, and 3 and operation mode 2.

Prescribed width of the clock might not be output to the serial clock output pin (SCK pin) immediately after the switch of the serial clock output when CCO and the SCES bit are set while enabling the serial clock output (SMR:SCKE="1") on the following conditions but, after this, it will be output normally.

- When the CCO bit changes the SCES bit in the state of "1"
- When the CCO bit and the SCES bit are changed at the same time
- When the CCO bit is changed from "1" to "0"

[bit0] SCES : Sampling serial clock edge selection bit

SCES	Sampling serial clock edge selection
0	Sample signals at a clock rising edge (normal) [initial value]
1	Sample signals at a clock falling edge (inverted clock)

If the LIN-UART is set as a slave system (ECCR:MS=1) in mode 2 (synchronous mode) and if the SCES is set to "1", the sampling edge is switched from the rising edge to the falling edge.

If it is set as the master system (ECCR:MS=0) in mode 2 (synchronous mode) and if the SCK pin is set for clock output, the internal serial clock and the output clock signal are inverted.

This bit must be set to "0" in modes 0, 1, and 3.

Note:

When "1" is set to the SCES bit, software reset is prohibited. Moreover, change the SCES bit when transmission/reception is prohibited.

4.6. Extended Communication Control Register : ECCR

The bit configuration of the extended communication control register (ECCR) is shown below.

The extended communication control register (ECCR) enables the bus idle detection setting, the synchronous clock setting, and the LIN synch break generation.

■ ECCR: Address Base_addr + 05_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	LBR	MS	SCDE	SSM	Reserved	RBI	TBI
Initial value	0	0	0	0	0	0	X	X
Attribute	R/W0	R0,W	R/W	R/W	R/W	R/W0	R,WX	R,WX

[bit7] Reserved bit

This bit must always be written to "0".

[bit6] LBR : LIN synch break generation bit

LBR	LIN synch break generation	
	Write	Read
0	No effect [initial value]	The read value is always "0".
1	LIN synch break generation	

If the LBR bit is set to "1" in mode 3, a LIN synch break with a length specified in LBL1 and LBL0 in ESCR is generated. In operation mode 0, set this bit to "0".

[bit5] MS : Master/slave mode selection bit

MS	Master/slave function (mode 2)
0	Master mode (Serial clock generated) [Initial value]
1	Slave mode (External serial clock received)

Select master or slave mode in mode 2 (synchronous). When master mode is selected, a synchronous clock is generated. When slave mode is selected, an external serial clock is received.

In operation modes 0, 1, and 3, this bit is fixed to "0".

Change the MS bit while transmission is disabled (SCR:TXE=0).

Note:

When slave mode is selected, set an external clock as the clock source and set it to one-to-one external clock input (SMR:SCKE="0", EXT="1", OTO="1").

[bit4] SCDE : Serial clock delay enable bit

SCDE	Serial clock delay enabled (mode 2)
0	Clock delay disabled [initial value]
1	Clock delay enabled

In master mode of mode 2, set the SCDE bit to "1" to output a delayed serial clock as shown in "Figure 7-5".

In operation modes 0, 1, and 3, this bit is fixed to "0".

[bit3] SSM : Start/stop bit enable

SSM	Start/stop bit enable (mode 2)
0	Start/stop bit not available [initial value]
1	Start/stop bit available

In mode 2, start and stop bits are added to the synchronous data format.

In operation modes 0, 1, and 3, this bit is fixed to "0".

[bit2] Reserved bit

This bit must always be written to "0".

[bit1] RBI : Reception bus idle flag bit

RBI	Reception bus idle
0	Reception operation in progress
1	No reception operation

This bit is set to "1" when the SIN pin is "H" level and no reception operation is in progress.

Do not use the RBI bit if the start/stop bit is not available in mode 2 (SSM=0).

[bit0] TBI : Transmission bus idle flag bit

TBI	Transmission bus idle
0	Transmission operation is in progress.
1	No transmission operation is in progress.

This bit is set to "1" if no transmission operation is in progress in the SOT pin.

Do not use the TBI bit if the start/stop bit is not available in mode 2 (SSM=0).

4.7. Baud Rate Generator Register : BGR

The bit configuration of the baud rate generator register (BGR) is shown below.

The baud rate generator register (BGR) sets the division ratio of the serial clock. It can also read an accurate value of the transmission reload counter.

■ BGR: Address Base_addr + 06_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	—	B14	B13	B12	B11	B10	B09	B08
Initial value	—	0	0	0	0	0	0	0
Attribute	R0,WX	R,W	R,W	R,W	R,W	R,W	R,W	R,W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	B07	B06	B05	B04	B03	B02	B01	B00
Initial value	0	0	0	0	0	0	0	0
Attribute	R,W	R,W	R,W	R,W	R,W	R,W	R,W	R,W

[bit15] - : Undefined bit

The read value is always "0". This does not affect the writing operation.

[bit14 to bit8] B[14:08] : Baud rate generator register 1

BGR	Baud rate generator register 1
Write	Writing of bit14 to bit8 of the reload value to the counter
Read	Reading of bit14 to bit8

[bit7 to bit0] B[07:00] : Baud rate generator register 0

BGR	Baud rate generator register 0
Write	Writing of bit7 to bit0 of the reload value to the counter
Read	Reading of bit7 to bit0

Baud rate generator register (BGR) sets the division ratio of the serial clock.

The reload value for counting can be written to, and the transmission reload counter value can be read from this register.

When a reload value is written to the baud rate generator register (BGR), the reload counter starts counting.

5. Interrupts

This section explains the interrupts.

- 5.1 Overview
- 5.2 Generation of Reception Interrupt and Flag Setting Timing
- 5.3 Occurrence of Transmission Interrupt and Flag Timing

5.1. Overview

Overview of the interrupts is shown below.

LIN-UART has reception and transmission interrupts. An interrupt request is generated in one of the following cases:

- Storage of reception data in the reception data register (RDR) or occurrence of a reception error
- Transfer of transmission data from the transmission data register (TDR) to the transmission shift register
- Detection of a LIN synch break

5.1.1. Interrupts of LIN-UART

Interrupts of LIN-UART are shown below.

The following table shows the interrupt control bits and the interrupt factors:

Table 5-1 Interrupt Control Bits and Interrupt Factors of LIN-UART

Reception/ Transmission/ Input capture	Interrupt request flag bit	Flag Register	Operation mode				Interrupt factor	Interrupt factor enable bit	Clearing of interrupt request
			0	1	2	3			
Reception	RDRF	SSR	○	○	○	○	Writing of reception data to RDR	SSR:RIE	Reading of reception data
	ORE	SSR	○	○	○	○	Overrun error		Writing of "1" to the reception error clear bit (SSR:CRE)
	FRE	SSR	○	○	△	○	Framing error		
	PE	SSR	○	×	△	×	Parity error		
	LBD	ESCR	×	×	×	○	Detection of a LIN-Synch- Break	ESCR:LBIE	Writing of "0" to the LBD bit of ESCR
Transmission	TDRE	SSR	○	○	○	○	Transmission register empty	SSR:TIE	Writing of transmission data, Writing of "1" to the LIN synch break generation bit (ECCR:LBR)
Input capture (ch.0 to ch.5)	ICP	ICS	×	×	×	○	1st falling edge of LIN synch field	ICS:ICE	Writing of "0" to the ICS:ICP bit
	ICP	ICS	×	×	×	○	5th falling edge of LIN synch field	ICS:ICE	

- : Available
 - △ : Available if the ECCR:SSM bit is "1"
 - ×
- ×

5.1.2. Reception Interrupt

Reception interrupt is shown below.

If one of the following occurs in reception mode, a corresponding flag bit in the serial status register (SSR) is set to "1".

- **Data reception completion: RDRF**

Transfer of reception data from the reception shift register to the reception data register (RDR) and reading of the data.

- **Overrun error: ORE**

When RDRF="1", RDR is not read by the CPU and the next reception data is transferred from the reception shift register to the reception data register (RDR).(ORE=1)

- **Framing error: FRE**

When the serial data is detected as "L" in the first bit of the stop bit. (FRE=1)

- **Parity error: PE**

Parity detection error.(PE=1)

When the reception interrupt is enabled (SSR:RIE = "1") and one or more of the above flags is set to "1", a reception interrupt request is generated.

When the reception data register (RDR) is read, the RDRF flag is automatically cleared to "0". If the reception error flag clear bit (CRE) in the serial control register (SCR) is set to "1", all the error flags are cleared to "0".

Note:

The CRE bit is write-only and, when "1" is written, it retains "1" for one clock cycle.

5.1.3. Transmission Interrupt

Transmission interrupt is shown below.

When transmission data is transferred from the transmission data register (TDR) to the transmission shift register and transmission is started, the transmission data register empty flag bit (TDRE) in the serial status register (SSR) is set to "1". If the transmission interrupt enable bit (TIE) in SSR is set at this time, an interrupt request is generated.

Note:

After reset, the initial value of TDRE is "1". Therefore, a transmission interrupt occurs as soon as the TIE flag is set to "1". The TDRE flag is cleared only if data is written to the transmission data register (TDR) or "1" is written to the LIN synch break generation bit (ECCR:LBR).

5.1.4. LIN Synch Break Interrupt

LIN synch break interrupt is shown below.

This interrupt is enabled when LIN-UART works as a LIN slave in mode 3.

When the serial input bus is "0" (dominant) for 11-bit time or longer, the LIN synch break detection flag bit (LBD) in the extended status control register (ESCR) is set to "1". The LIN synch break interrupt and the LBD flag are cleared when the LBD flag is set to "0". Clear the LBD flag before a capture interrupt occurs in the LIN synch field.

Reception must be disabled (SCR:RXE=0) if LIN synch break is to be detected.

5.1.5. LIN Synch Field Edge Detection Interrupt

LIN synch field edge detection interrupt is shown below.

This interrupt is enabled when LIN-UART works as a LIN slave in mode 3.

After a LIN synch break is detected, the internal signal is set to "1" at the 1st falling edge of the LIN synch field and set to "0" after the 5th falling edge. When the input capture (ICP) is set to the LSYN input (LSYNS:LSYN=1), both edges are detected (ICS:EG1, EG0=11), and interrupt is enabled (ICS:ICE=1), an interrupt occurs at rising and falling edges of LSYN (internal signal).

The difference of count values detected by input capture is equivalent to 8 bits of the serial clock of the master and a new baud rate can be calculated. When a falling edge of the start bit is detected, the reload counter automatically restarts.

The figures below show the interrupt generation timings:

Figure 5-1 LIN Synch Break Detection and Flag Set Timing

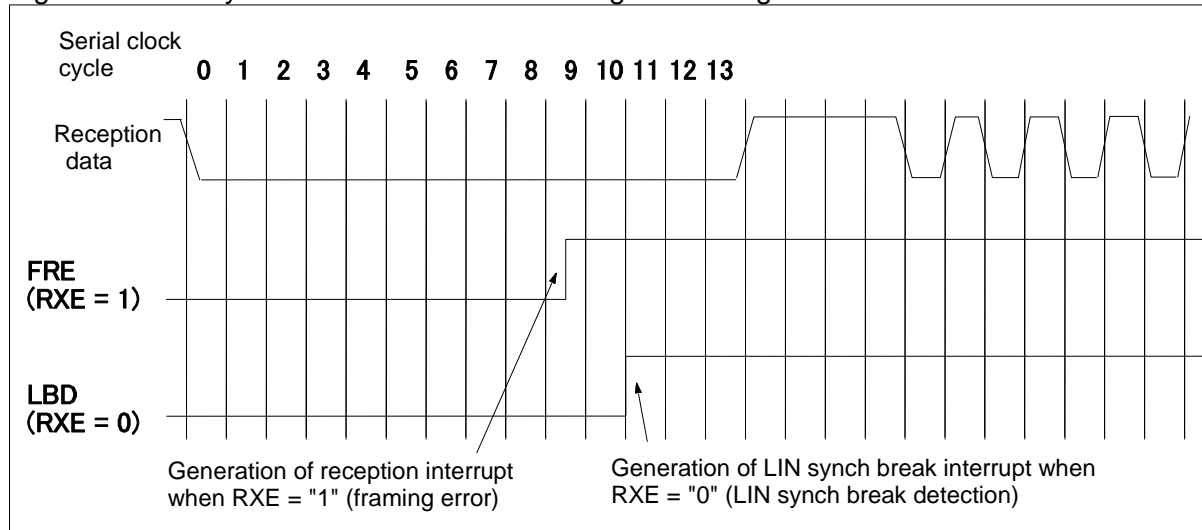
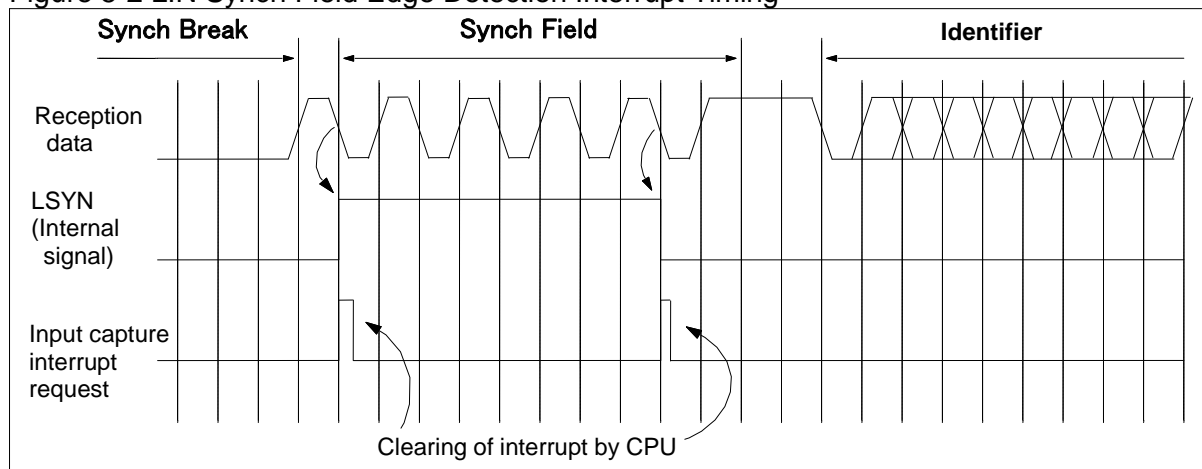


Figure 5-2 LIN Synch Field Edge Detection Interrupt Timing



5.2. Generation of Reception Interrupt and Flag Setting Timing

Generation of reception interrupt and flag setting timing is shown below.

This section explains the reception interrupt factors, reception completion (RDRF bit in SSR), and reception error occurrence (PE, ORE, and FRE bits in SSR).

5.2.1. Generation of Reception Interrupt and Flag Setting Timing

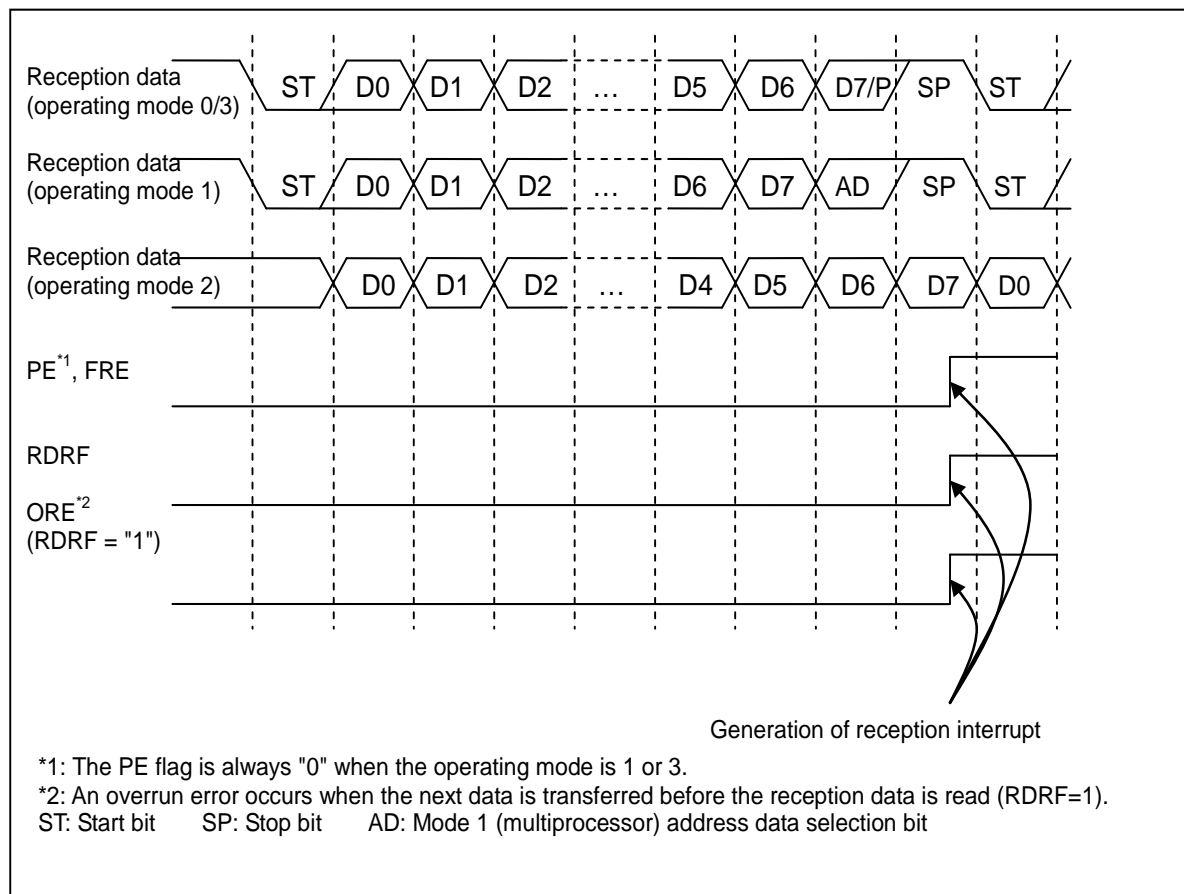
Generation of reception interrupt and flag setting timing is shown below.

When the first stop bit is detected in operation mode 0, 1, 2 (SSM=1), or 3 or the last data bit is detected in operation mode 2 (SSM=0), reception data is stored in the reception data register (RDR). When reception is completed (SSR:RDRF=1) or a reception error occurs (SSR:PE, ORE, FRE=1), a corresponding flag is set. If reception interrupt is enabled at this time (SSR:RIE=1), a reception interrupt is generated.

Note:

When a reception error occurs, the data in the reception data register (RDR) becomes invalid in any mode.

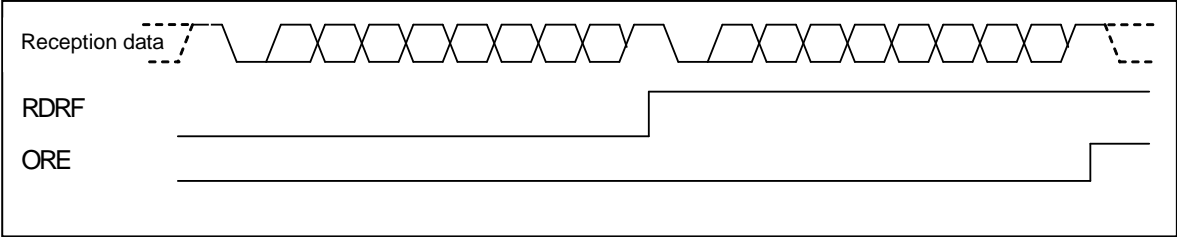
Figure 5-3 Example of Reception Operation and Flag Set Timing



Note:

The above figure does not show all the reception options in mode 0 and mode 3. In this example, they are "7p1" and "8N1" (p = "even parity" or "odd parity").

Figure 5-4 ORE Set Timing



5.3. Occurrence of Transmission Interrupt and Flag Timing

Occurrence of transmission interrupt and flag timing is shown below.

An interrupt occurs when transmission is started after transfer of transmission data from the transmission data register (TDR) to the transmission shift register.

5.3.1. Occurrence of Transmission Interrupt and Flag Timing

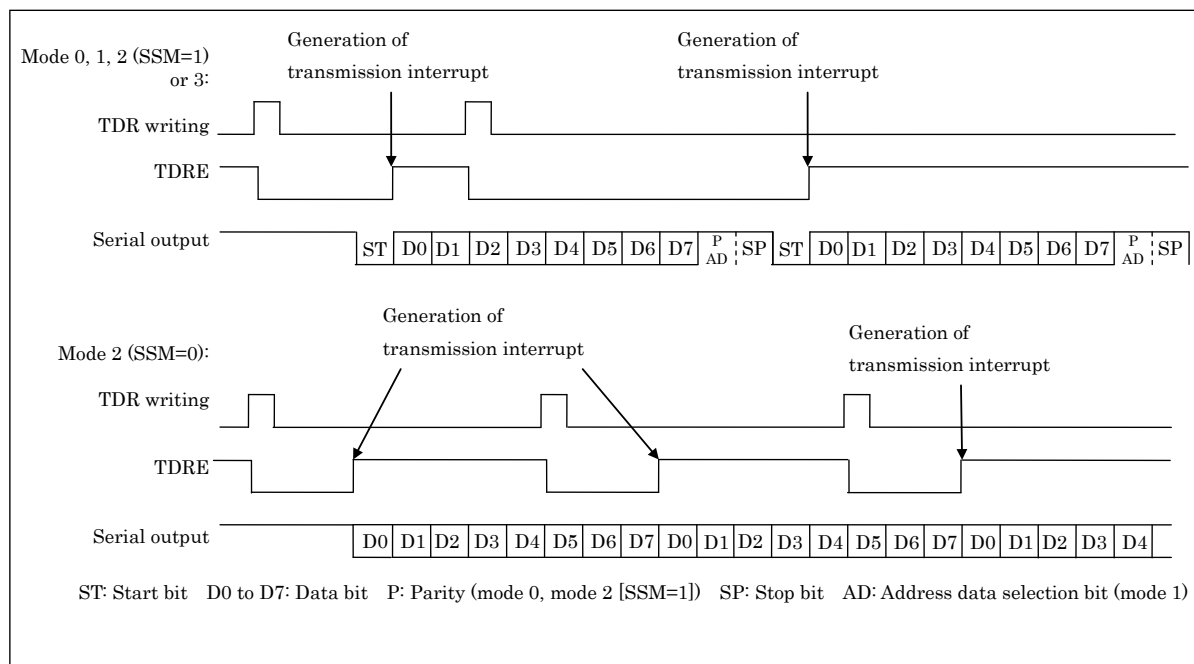
Occurrence of transmission interrupt and flag timing is shown below.

When data written to the transmission data register (TDR) is transferred to the transmission shift register and transmission is started, writing of the next data is enabled (SSR:TDRE=1). If the transmission interrupt is enabled (SSR:TIE=1) at this time, a transmission interrupt is generated.

The TDRE bit is cleared to "0" by the writing of data to the transmission data register (TDR).

The figure below shows an example of the LIN-UART transmission operation and flag set timing:

Figure 5-5 Example of Transmission Operation and Flag Set Timing



Note:

The example in the above figure does not show all the transmission options in mode 0. In this example, they are "8p1" (p = "even parity" or "odd parity"). If the SSM bit is "0" in mode 3 or mode 2, the parity and the address/data selection bit are not added.

5.3.2. Transmission Interrupt Request Generation Timing

Transmission interrupt request generation timing is shown below.

A transmission interrupt request is generated when the TDRE flag is set to "1" while transmission interrupt is enabled (TIE bit in SSR is set to "1").

Note:

The initial value of TDRE is "1". Therefore, a transmission completion interrupt is set as soon as transmission interrupt is enabled (TIE="1"). TDRE is read-only. The TDRE flag is cleared only if data is written to the transmission data register (TDR) or "1" is written to the LIN synch break generation bit (ECCR:LBR).

6. Baud Rates

Baud rates are shown below.

The serial clock of LIN-UART can be one of the following:

- Dedicated baud rate generator (reload counter)
- Input of an external clock to the baud rate generator (reload counter)
- External clock (direct use of the SCK pin input clock)

6.1. Selection of Baud Rates

Selection of baud rates is shown below.

Figure 6-1 shows the baud rate selection circuit. One of the following 3 baud rates can be selected.

6.1.1. Baud Rate Obtained when a Dedicated Baud Rate Generator (Reload Counter) Divides the Frequency of the Internal Clock

Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the internal clock is shown below.

There are two internal reload counters that correspond to the transmission and reception serial clocks, respectively. The baud rate can be selected by setting a 15-bit reload value in the baud rate generator register (BGR). The reload counter divides the frequency of the internal clock by the specified value.

This baud rate can be used in asynchronous and synchronous modes (master).

To configure the clock source, select the internal clock and the baud rate generator clock (SMR:EXT=0, OTO=0).

6.1.2. Baud Rate Obtained when a Dedicated Baud Rate Generator (Reload Counter) Divides the Frequency of the External Clock

Baud rate obtained when a dedicated baud rate generator (reload counter) divides the frequency of the external clock is shown below.

Use the external clock for the clock source of the reload counter.

The baud rate can be selected by setting a 15-bit reload value in the baud rate generator register (BGR).

The reload counter divides the frequency of the external clock by the specified value.

Use this baud rate in asynchronous mode.

To configure the clock source, select the external clock and the baud rate generator clock (SMR:EXT=1, OTO=0).

6.1.3. Baud Rate Due from External Clock (One-to-One Mode)

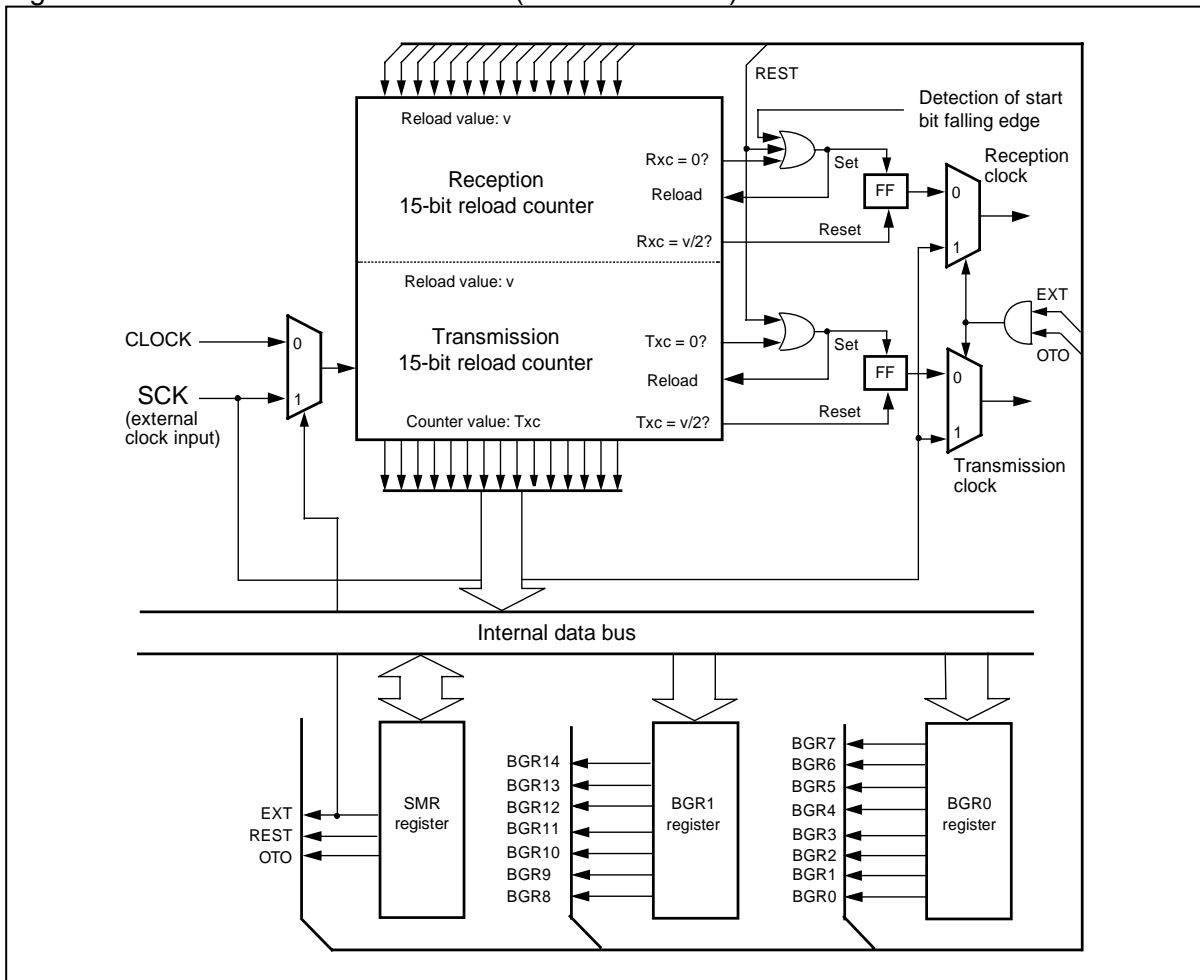
Baud rate due from external clock (one-to-one mode) is shown below.

The clock input from the LIN-UART clock input pin (SCK) is directly used as the baud rate (synchronous mode 2 slave operation (ECCR:MS=1)).

Use this baud rate in synchronous mode (slave).

To configure the clock source, select the external clock and the external clock direct use (SMR:EXT=1, OTO=1).

Figure 6-1 Baud Rate Selection Circuit (Reload Counter)



6.2. Baud Rate Setting

Baud rate setting is shown below.

This section indicates how to set the baud rate and the serial clock frequency calculations.

6.2.1. Baud Rate Calculations

Baud rate calculations are shown below.

The two 15-bit reload counters are set using the baud rate generator register (BGR).

The baud rate calculation formulas are as follows:

$$\text{Reload value: } v = (\varphi/b) - 1$$

$$\text{Baud rate value: } b = \varphi / (v + 1)$$

v: reload value b: baud rate φ : clock frequency

● Example of calculation

If the clock is 16MHz and the target baud rate is 19200 bps, the reload value "v" is calculated in the following manner:

Reload value:

$$v = \left(\frac{16 \times 10^6}{19200} \right) - 1 = 832$$

Therefore, the real baud rate can be calculated based on the following:

$$b = \frac{\varphi}{(v + 1)} = \frac{16 \times 10^6}{833} = 19207.6831$$

Note:

Set the reload value to "0" to stop the reload counter. Therefore, the smallest division ratio becomes a division by 2.

When sending or receiving is performed in asynchronous mode, it is necessary to set the reload value to 4 or more, because the reception value is determined by executing oversampling five times.

6.2.2. Baud Rate Setting Example for Each Clock Frequency

Baud rate setting example for each clock frequency is shown below.

The following table indicates the clock frequency and examples of the baud rate setting.

Table 6-1 Baud Rate Setting Example for Each Clock Frequency

Baud rate	8MHz		16MHz		24MHz		32MHz		40MHz	
	Value	dev.	Value	dev.	Value	dev.	Value	dev.	Value	dev.
4M	-	-	-	-	5	0	7	0	9	0
2M	-	-	7	0	11	0	15	0	19	0
1M	7	0	15	0	23	0	31	0	39	0
500000	15	0	31	0	47	0	63	0	79	0
460800	-	-	-	-	51	-0.16	68	-0.64	86	0.22
250000	31	0	63	0	95	0	127	0	159	0
230400	-	-	-	-	103	-0.16	138	0.08	173	0.22
153600	51	-0.16	103	-0.16	155	-0.16	207	-0.16	259	-0.16
125000	63	0	127	0	191	0	255	0	319	0
115200	68	-0.64	138	0.08	207	-0.16	277	0.08	346	-0.06
76800	103	-0.16	207	-0.16	311	-0.16	416	0.08	520	0.32
57600	138	0.08	277	0.08	416	0.08	555	0.08	693	-0.06
38400	207	-0.16	416	0.08	624	0	832	-0.04	1041	0.03
28800	277	0.08	554	-0.01	832	-0.03	1110	-0.01	1388	0.01
19200	416	0.08	832	-0.03	1249	0	1666	0.02	2082	-0.02
10417	767	0	1535	0	2303	0	3071	0	3839	0.003
9600	832	-0.04	1666	0.02	2499	0	3332	-0.01	4166	0.008
7200	1110	-0.01	2221	-0.01	3332	-0.01	4443	-0.01	5555	0.008
4800	1666	0.02	3332	-0.01	4999	0	6666	0	8332	0.004
2400	3332	-0.01	6666	0	9999	0	13332	0	16666	0.002
1200	6666	0	13332	0	19999	0	26666	0	-	-
600	13332	0	26666	0	-	-	-	-	-	-
300	26666	0	-	-	-	-	-	-	-	-

Note:

Unit of deviation is "%".

The greatest synchronous baud rate is the machine clock divided by 5.

6.2.3. Use of the External Clock

Use of the external clock is shown below.

When "1" is written in the EXT bit of the serial mode register (SMR), the external clock is chosen. In the baud rate generator, the external clock can be used in the same way as the internal clock.

When using the slave operation in synchronous mode 2, one to one external clock input mode (SMR:OTO=1) is chosen. Enter the external clock directly into the serial clock.

Note:

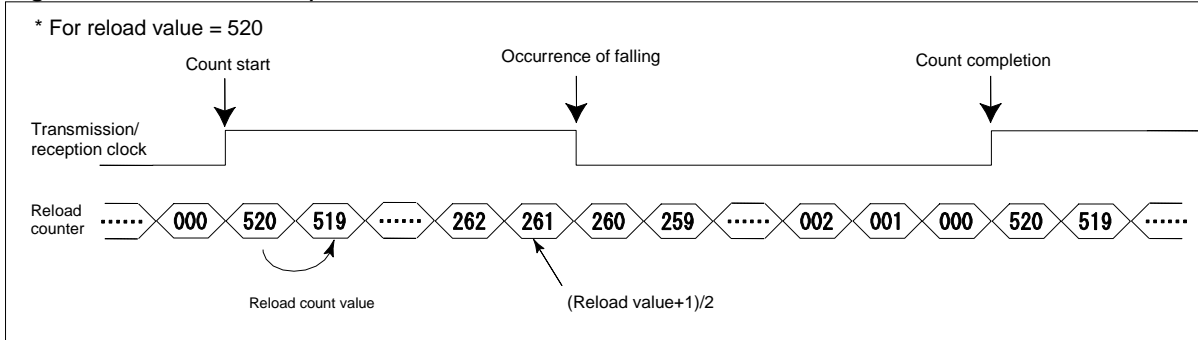
The external clock signals are synchronized with the internal clock by LIN-UART. Therefore, in the case where the external clock cannot be synchronized, LIN-UART will malfunction.

6.2.4. Reload Counter Operation

Reload counter operation is shown below.

The following indicates the operation examples of the transmission and reception reload counters.

Figure 6-2 Count Examples of the Reload Counter



Note:

A falling edge of the serial clock signal is generated after counting $\lfloor (v + 1) / 2 \rfloor$ that is the reload value divided by 2.

6.3. Reload Counter

Reload counter is shown below.

This is a 15-bit reload counter functioning as a dedicated baud rate generator.

The transmission/reception clock is generated from the external or internal clock.

In addition, the count value of the transmission reload counter can be read from the baud rate generator register (BGR).

6.3.1. Reload Counter Functions

Reload counter functions are shown below.

Reload counters, including transmission and reception reload counters, serve as the dedicated baud rate generators. It consists of a 15-bit register for reload values and generates a transmission/reception clock from the external or internal clock. In addition, the count value of the transmission reload counter can be read via the baud rate generator register (BGR).

6.3.2. Count Start

Count start is shown below.

When a reload value is written to the baud rate generator register (BGR), the reload counter starts counting.

6.3.3. Restart

Restart is shown below.

Configure the LIN-UART reset (writing of "1" to SMR:UPCL) or restart (writing of "1" to SMR:REST) to restart both reload counters.

The reception reload counter is also restarted when a falling edge of the start bit is detected in the asynchronous mode, and the reception shift register is synchronized by the reception data.

6.3.4. Counter Clear

Counter clear is shown below.

By resetting, the reload value of the baud rate generator register (BGR) and the reload counter are cleared to "00_H", and the reload counter stops.

The counter value is temporarily cleared to "00_H" by LIN-UART reset (writing of "1" to SMR:UPCL), but the reload counter will restart because the reload value has been held. The counter value will not be cleared to "00_H" by the restart configuration (writing of "1" to the SMR:REST).

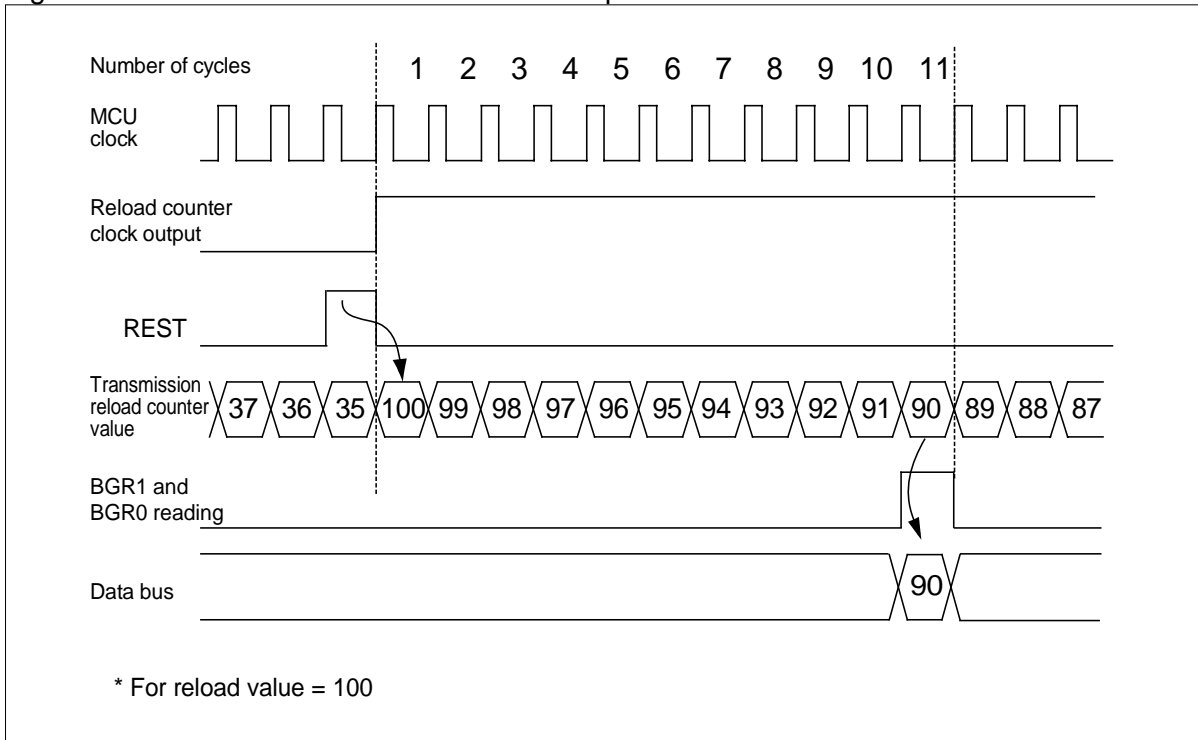
6.3.5. Simple Timer Use

Simple timer use is shown below.

The transmission reload counter can also be used as a simple timer.

The figure below indicates an example of usage as a simple timer:

Figure 6-3 Reload Counter Reactivation Example



In the example, the number of MCU clock cycles (cyc) after REST will be as follows:

$$\text{cyc} = v - c + 1 = 100 - 90 + 1 = 11$$

v: reload value, c: read counter value

7. Operation

The operation is shown below.

LIN-UART, in the operation mode 0, will usually operate as bidirectional serial communication. In mode 1, multi-processor communication as master/slave takes place. In mode 2 and mode 3, bidirectional communication as master/slave takes place.

7.1. Overview

The overview of the operation is shown.

- 7.1.1 Operation Mode
- 7.1.2 Connection Method between CPUs
- 7.1.3 Synchronization System
- 7.1.4 Signaling System
- 7.1.5 Transmission/Reception Start
- 7.1.6 Stopping of Transmission/Reception
- 7.1.7 Stopping of Transmission/Reception in Progress

7.1.1. Operation Mode

The operation mode is explained below.

LIN-UART has four operation modes from mode 0 to 3. The following table indicates the selectable operation mode based on the inter-CPU connection method and data transfer:

Table 7-1 LIN-UART Operation Mode

Operation mode	Data length		Synchronization system	Stop bit length	Data bit format
	Parity No	Parity Yes			
0	Normal mode	7 or 8 bits		Asynchronous	1 bit or 2 bits
1	Multi-processor mode	7 bits or 8 bits + 1 bit (*1)	—		
2	Normal mode	8 bits		Synchronous	No, 1 bit, 2 bits
3	LIN Mode	8 bits	—	Asynchronous	1 bit or 2 bits

-: Setting is prohibited

*1: In the multi-processor mode, "+1" is used as a communication control address/data selection bit (AD).

Note:

Mode 1 (Multi-processor mode) at the time of master/slave connection supports the operation of both master and slave. In mode 3, communication format is fixed. Switch the mode after releasing all LIN-UART transmission/reception and standby operations and then reset (SMR:UPCL=1) LIN-UART.

7.1.2. Connection Method between CPUs

The connection method between CPUs is shown below.

Either the external clock one to one connection (normal mode) or the master/slave connection (multiprocessor mode) can be chosen. Whichever system is chosen, data length, parity, synchronization system, etc. must be consistent among all CPUs. The operation mode will be chosen in the following manner:

Choose the operation mode as shown below:

- In the case of one to one connection: It will be necessary to adopt the same system in either operation mode 0 or mode 2 in both CPUs. Choose operation mode 0 for an asynchronous system, and operation mode 2 for a synchronous system. Additionally, in operation mode 2, configure one CPU as master and the other as slave.
- In the case of master/slave connection: choose operation mode 1. Use as a master/slave system.

7.1.3. Synchronization System

The synchronization system is shown below.

In an asynchronous system, the receiving clock is synchronized to the falling edge of the reception start bit.
In a synchronous system, it can be synchronized by the master clock signal or the clock signal when it operates as a master.

7.1.4. Signaling System

The signaling system is shown below.

The signaling system is NRZ (Non Return to Zero).

7.1.5. Transmission/Reception Start

Transmission/reception start is shown below.

When "1" is set to the transmission enable bit (SCR:TXE), the transmission will begin.

When "1" is set to the reception enable bit (SCR:RXE), the reception will begin.

7.1.6. Stopping of Transmission/Reception

Stopping of transmission/reception is shown below.

When "0" is set to the transmission enable bit (SCR:TXE), the transmission will stop.

When "0" is set to the reception enable bit (SCR:RXE), the reception will stop.

7.1.7. Stopping of Transmission/Reception in Progress

Stopping of transmission/reception in progress is shown below.

In the case when a transmission/reception operation is disabled (SCR2:TXE, RXE=0) while it is in progress, the transmission/reception operation will stop immediately. In this case, the data cannot be guaranteed.

7.2. Asynchronous Mode (Operation Modes 0 and 1)

Asynchronous mode (Operation modes 0 and 1) is shown below.

In the case of using the operation mode 0 (normal mode) or operation mode 1 (multi-processor mode), the transfer method becomes asynchronous.

7.2.1. Transmission/Reception Data Format

The transmission/reception data format is explained.

The transmission/reception data always starts from the start bit ("L" level) and, after the transmission/reception of data has taken place for the specified data bit length, ends at the stop bit ("H" level).

The direction of bit transfer (LSB First or MSB First) is determined by the BDS bit of the serial status register (SSR). If with parity, the parity bit will always be placed between the last data bit and the first stop bit.

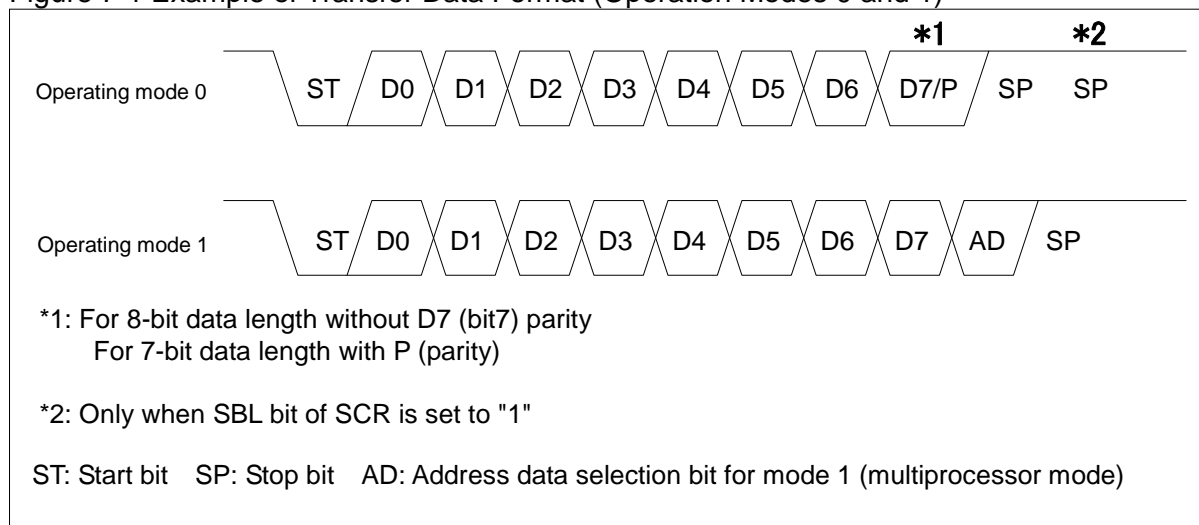
- In operation mode 0, data length of either 7 bits or 8 bits is chosen. Parity or no parity can be selected. A stop bit length (1 or 2) can be selected.
- In operation mode 1, data length is 7 or 8 bits, with no parity added, but with address/data bit added. A stop bit length (1 or 2) can be selected.

Calculation formula for the transfer frame bit length will be as follows:

$$\text{Length} = 1 + d + p + s$$

(d = number of data bit [7 or 8], p = parity [0 or 1], s = number of stop bit [1 or 2])

Figure 7-1 Example of Transfer Data Format (Operation Modes 0 and 1)



Note:

When the BDS bit of the serial status register (SSR) is set to "1", the bit stream is processed as D7, D6, ... , D1, D0, (P). In addition, in the case of data length of 7 bits, it is processed in the sequence of D6, . . . , D1, D0, (P).

7.2.2. Transmission Operation

The transmission operation is shown below.

Transmission data is written to the transmission data register (TDR) when there is no transmission data in the transmission data register (TDR) (SSR:TDRE=1). Transmission will start when the transmission operation is subsequently enabled (SCR:TXE=1). The transmission data empty flag bit (SSR:TDRE) becomes "0" when transmission data is written to the transmission data register (TDR).

When transmission data is transferred from the transmission data register (TDR) to the transmission shift register, the transmission data empty flag bit (SSR:TDRE) is set to "1" again. If transmission interrupt is enabled (SSR:TIE=1) at this time, a transmission interrupt request is generated. The following transmission data can be written to the transmission data register (TDR) when processing the interrupt. If data length is configured to 7 bits (CL=0), MSB of the TDR becomes an unused bit, with no regard to the setting of the transfer direction selection bit (BDS) (LSB First or MSB First).

Note:

An interrupt occurs immediately after transmission interrupt is enabled (SSR:TIE) because the initial value of the transmission data empty flag bit (SSR:TDRE) is "1".

7.2.3. Reception Operation

The reception operation is shown below.

When the reception operation is enabled (SCR:RXE=1), the reception operation will start. When the start bit is detected, 1-frame data is received according to the data format set in the serial control register (SCR). When an error occurs, the error flag is set (SSR:PE, ORE, FRE). When 1 frame has been received, reception data is transferred from the reception shift register to the reception data register (RDR), setting the reception data register full flag bit (SSR:RDRF) to "1". At this point, if reception interrupt request is enabled (SSR:RIE=1), a reception interrupt request is output.

To read reception data, first check the error flag state after 1-frame data has been received. If reception has been completed successfully, read reception data from the reception data register (RDR). When a reception error has detected, correct the error.

After the reading of reception data, the reception data register full flag bit (SSR:RDRF) will be cleared to "0". If data length is configured to 7 bits (CL=0), MSB of the TDR becomes an unused bit, with no regard to the setting of the transfer direction selection bit (BDS) (LSB First or MSB First).

Note:

If the reception data register full flag bit (SSR:RDRF) is configured to "1" and no error occurs (SSR:PE, ORE, FRE=0), the data in the reception data register (RDR) will be effective.

7.2.4. Clock Usage

Clock usage is shown below.

An internal clock or external clock can be used. For the baud rate, select the baud rate generator (SMR:EXT=0 or 1, and OTO=0).

7.2.5. Stop Bit

The stop bit is shown below.

It is possible to select a 1-bit or 2-bit stop bit at the time of transmission. If a 2-bit stop bit is selected, both stop bits are detected at the time of reception.

If the first stop bit is detected, the reception data register full flag (SSR:RDRF) will be set to "1". If no start bit is detected after that, the reception bus idle flag (ECCR:RBI) will be set to "1" to indicate that the reception operation is not activated.

7.2.6. Error Detection

Error detection is shown below.

In operation mode 0, parity errors, overrun errors, framing errors can be detected.

In operation mode 1, overrun errors and framing errors can be detected. Parity errors cannot be detected.

7.2.7. Parity

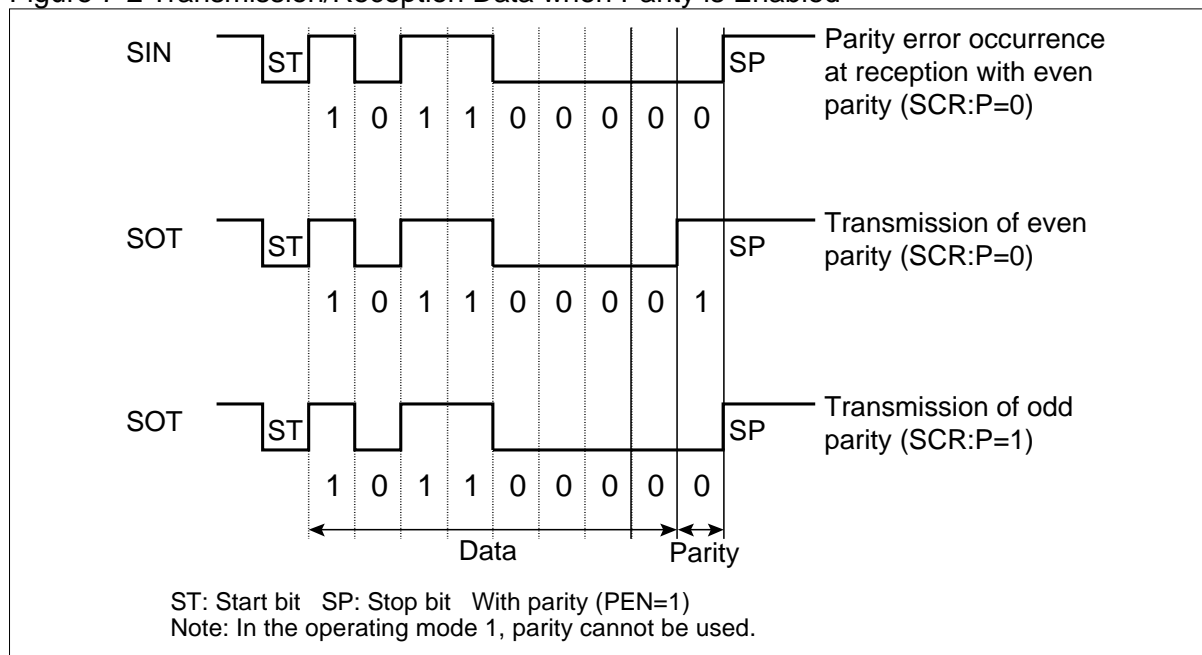
Parity is shown below.

It is possible to set the addition (at the time of transmission) and detection (at the time of reception) of a parity bit.

The parity enable bit (SCR:PEN) can specify whether to enable or disable the parity, and the parity selection bit (SCR:P) can specify whether to use even parity or odd parity.

Operation mode 1 does not use parity.

Figure 7-2 Transmission/Reception Data when Parity is Enabled



7.2.8. Data Signaling Method

The data signaling method is shown below.

This is based on the NRZ data format.

7.2.9. Data Transfer Method

The data transfer method is shown below.

It is possible to select LSB or MSB First as the data bit transfer method.

7.3. Synchronous Mode (Operation Mode 2)

Synchronous mode (Operation Mode 2) is shown below.

In the case of LIN-UART operation mode 2 (normal mode), the transfer method will be clock synchronous.

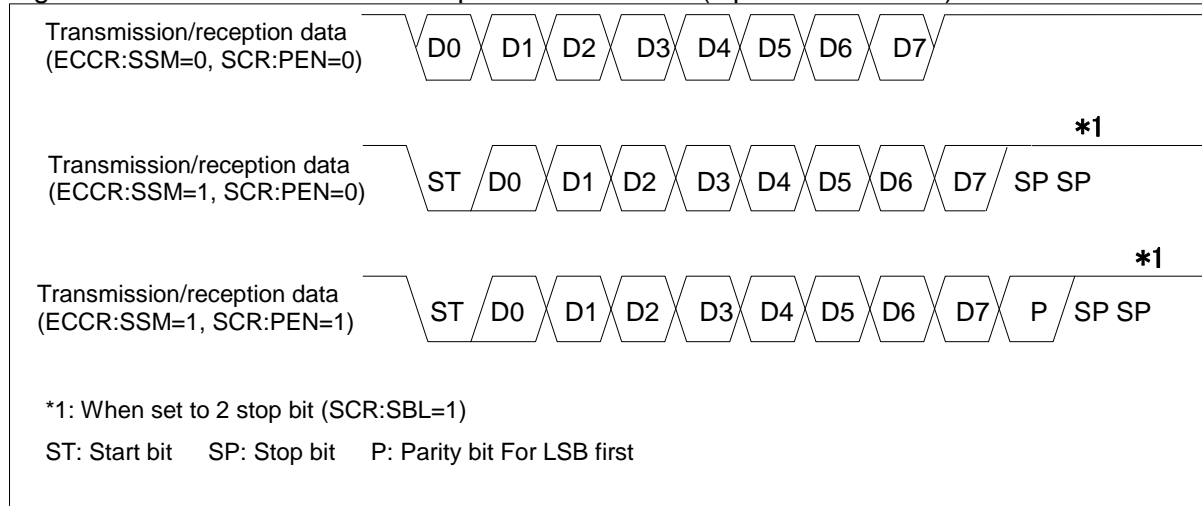
7.3.1. Transmission/Reception Data Format

The transmission/reception data format is shown below.

In the synchronous mode, it is possible to transmit and receive 8-bit data to select whether to include the start/stop bit or not (ECCR:SSM). In addition, if the start/stop bit is used (ECCR:SSM=1), you can choose whether to include the parity bit or not (SCR:PEN).

The figure below indicates the data format in the case when synchronous mode is used:

Figure 7-3 Transmission and Reception Data Format (Operation Mode 2)



7.3.2. Master/Slave Setting

Master/slave setting is shown below.

In mode 2, you can perform the settings for master and slave.

The master (ECCR:MS=0) generates the serial clock.

The slave (ECCR:MS=1) receives the external clock. Select the external clock and configure it to one-to-one external input (SMR:EXT, OTO=1).

7.3.3. Sampling Edge Selection

Sampling edge selection is shown below.

When sampling a data bit, it is possible to choose the sampling edge.

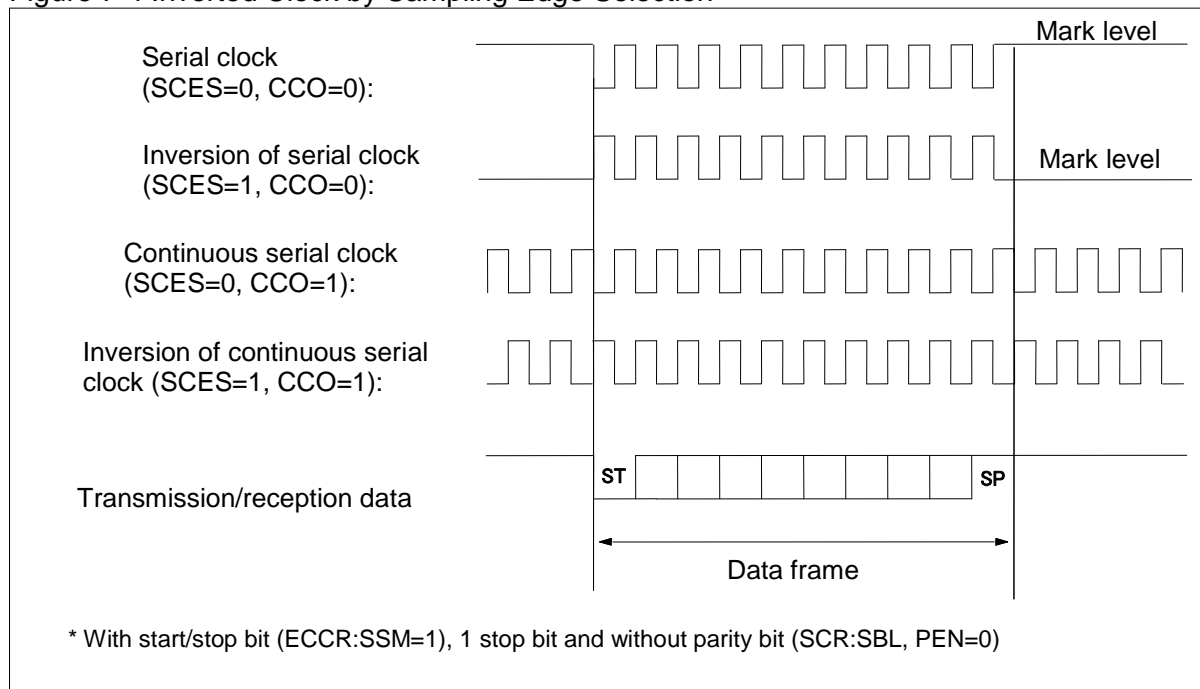
- Sampling in the rising edge (ESCR:SCES=0): Normal clock
- Sampling in the falling edge (ESCR:SCES=1): Clock inversion

As the transmission and reception clock, you can choose the serial clock (normal/delay) and sequential serial clock.

If the sequential serial clock is not used in the master mode (ESCR:CCO=0) and the clock is inverted (ESCR:SCES=1), the clock signal mark level becomes "L".

The figure below indicates a clock which is inverted by the selection of the sampling edge:

Figure 7-4 Inverted Clock by Sampling Edge Selection



7.3.4. Clock Supply

Clock supply is shown below.

It is necessary to supply clocks equivalent to the number of transmission and reception bits in the clock synchronous mode.

Note:

When performing communication with start/stop bit, the number of clock cycles must match the number of added start/stop bits.

7.3.5. Clock Usage

Clock usage is shown below.

In the master mode, the internal clock is used. Sending of data automatically generates the synchronous clock for data reception.

As for the baud rate, select the baud rate generator (SMR:EXT=0, OTO=0).

In the slave mode, the external clock is used. It is necessary to supply a clock exactly equivalent to 1 byte from the external source after confirming that there is data in the transmission data register on the transmission side. In addition, it is necessary to ensure that the mark level ("H" if SCES=0, and "L" if SCES=1) is set before and after transmission.

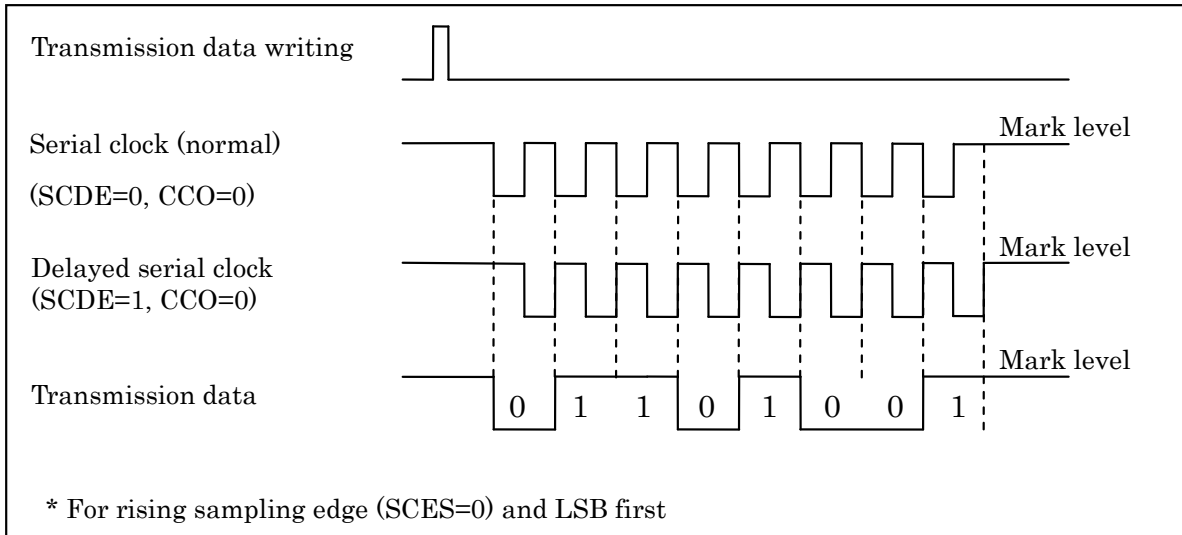
As for the baud rate, select the external clock (one to one) (SMR:EXT=1, OTO=1).

7.3.6. Delayed Serial Clock

The delayed serial clock is explained.

Setting the SCDE bit of the ECCR to "1" will output a delayed transmission clock as shown in the figure below. This function is required for the receiving device to sample data at the rising edge or falling edge of the clock.

Figure 7-5 Delayed Serial Clock Output by the Transmission Clock



Note:

If the sequential serial clock is selected for the transmission/reception clock (ESCR:CCO=1), setting the serial clock (normal/ delay) (ECCR:SCDE) will result in sequential serial clock and therefore will not delay.

7.3.7. Sequential Serial Clock

The sequential serial clock is shown below.

If the sequential serial clock is selected, a serial clock is sequentially output from the SCK pin of the master. In addition, when using the sequential serial clock, ensure that the start/stop bit is added (ECCR:SSM=1) to indicate the start/end of transmission and reception.

7.3.8. Parity

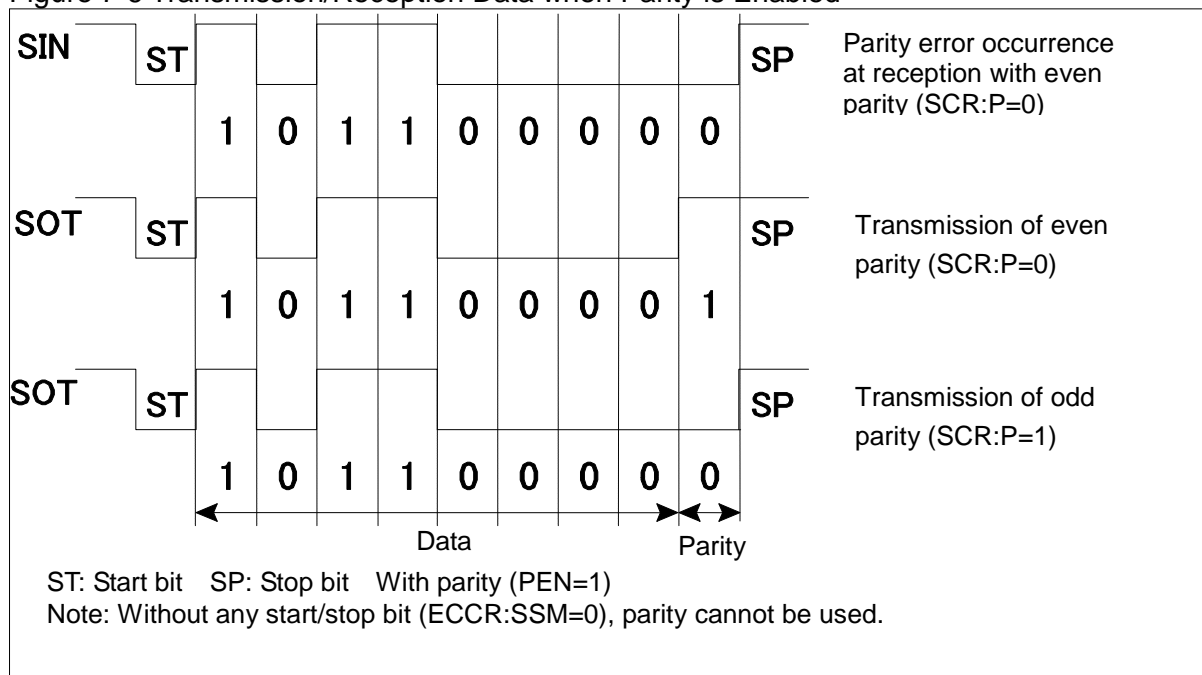
Parity is shown below.

It is possible to set the addition (at the time of transmission) and detection (at the time of reception) of a parity bit.

The parity enable bit (SCR:PEN) can specify whether to enable or disable the parity, and the parity selection bit (SCR:P) can specify whether to use even parity or odd parity.

It is not possible to use parity when there is no start/stop bit.

Figure 7-6 Transmission/Reception Data when Parity is Enabled



7.3.9. Data Signaling Method

The data signaling method is shown below.

This is based on the NRZ data format.

7.3.10. Stop Bit

The stop bit is shown below.

When transmitting, the stop bit in 1-bit or 2-bit can be selected. When only the first stop bit is received, it is detected when the stop bit in 2-bit is selected.

If the first stop bit is detected, the reception data register full flag (SSR:RDRF) will be set to "1". If no start bit is detected after that, the reception bus idle flag (ECCR:RBI) will be set to "1" to indicate that the reception operation is not activated.

7.3.11. Error Detection

Error detection is shown below.

If no start/stop bit exists (ECCR:SSM=0), only overrun error will be detected.

If the start/stop bit and parity bit exist, it is possible to detect parity error, overrun error, and framing error.

7.3.12. Communication Start

Communication start is shown below.

Communication starts when data is written to the transmission data register (TDR). Note that, in the case of data reception, it is also always necessary to first disable serial data output (SMR:SOE=0) and then write dummy data to the transmission data register (TDR) in order to start communication.

7.3.13. Communication End

Communication end is shown below.

When the transmission/reception of 1-frame data completes, the reception data register full flag bit (SSR:RDRF) will be set to "1". Check the error flag after reception to judge whether communication was performed successfully or not.

Note:

It is possible to configure a duplex communication system, such as asynchronous mode, by using the sequential clock and start/stop bit.

7.3.14. Data Transfer Method

The data transfer method is shown below.

It is possible to select LSB or MSB First as the data bit transfer method.

7.4. LIN Mode (Operation Mode 3)

The LIN mode (Operation mode 3) is shown below.

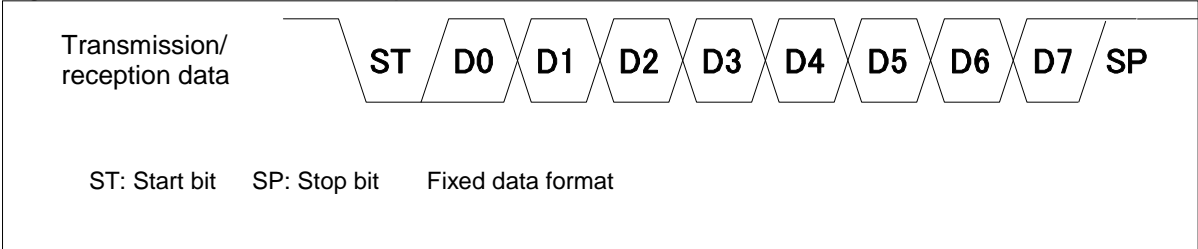
The LIN master/slave function is activated in LIN-UART operation mode 3. Asynchronous mode is adopted as the transfer method.

7.4.1. Transmission/Reception Data Format

The transmission/reception data format is shown below.

The data format is fixed in operation mode 3. 8-bit data is transmitted and received with additional start/stop bit, resulting in LSB First. No parity bit is added.

Figure 7-7 Transmission/Reception Data Format



7.4.2. LIN Master Operation

The LIN master operation is shown below.

In LIN master mode, all baud rates are determined to synchronize the slave with the master.

LIN communication starts when LIN synch break is transmitted from the master to the slave. LIN synch break generates 13-16 bits of "L" to the SOT pin. Select the length of LIN synch break (ESCR:LBL1/LBL0) to generate LIN synch break (ECCR:LBR=1).

LIN synch field (55_H) is transmitted after the LIN synch break. LIN synch break generation (writing of "1" to ECCR:LBR) changes the status to "transmission data exists" (SSR:TDRE=0). However, it is possible to write 55_H to the transmission data register (TDR). This prevents transmission interrupt from being generated after LIN synch break. Perform asynchronous communication after the LIN synch field. Perform asynchronous communication after the LIN synch field (55_H) has been transmitted.

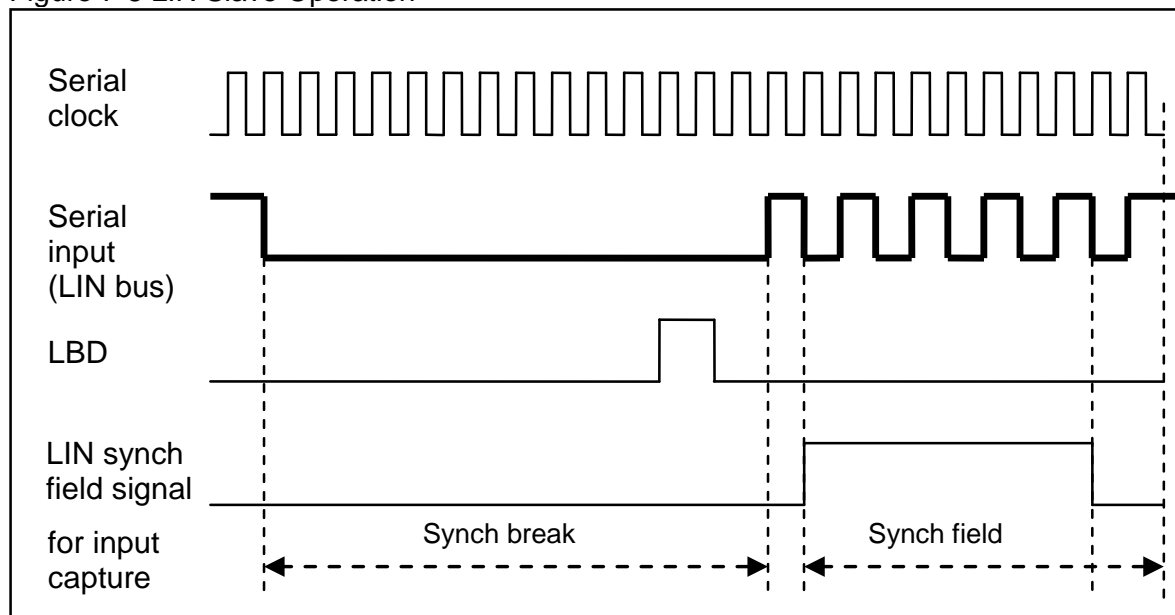
7.4.3. LIN Slave Operation

The LIN slave operation is shown below.

The LIN slave mode is synchronized with the master baud rate. When the bus (serial input) indicates "0" for 11-bit time or longer, LIN synch break of the LIN master will be detected (ESCR:LBD=1). To detect LIN synch break, it is necessary to either disable reception (SCR:RXE=0) or disable reception interrupt (SSR:RIE=0). If the LIN synch break interrupt is enabled (ESCR:LBIE=1) at this time, an interrupt is generated. Writing "0" to the LIN synch break detection flag bit (ESCR:LBD) will clear the interrupt. After a LIN synch break is detected, the internal signal is set to "1" at the 1st falling edge of the LIN synch field and set to "0" after the 5th falling edge. When both edges are detected and if input capture interrupt is enabled (ICS:ICE=1), an interrupt will be generated. When the LIN synch field is detected, the internal signal is equivalent to 8 bits of the master serial clock and is counted using input capture. After that, it will be possible to perform asynchronous communication. See "7.2 Asynchronous Mode (Operation Modes 0 and 1)".

The figure below shows a typical example of LIN communication frame start and LIN-UART operation.

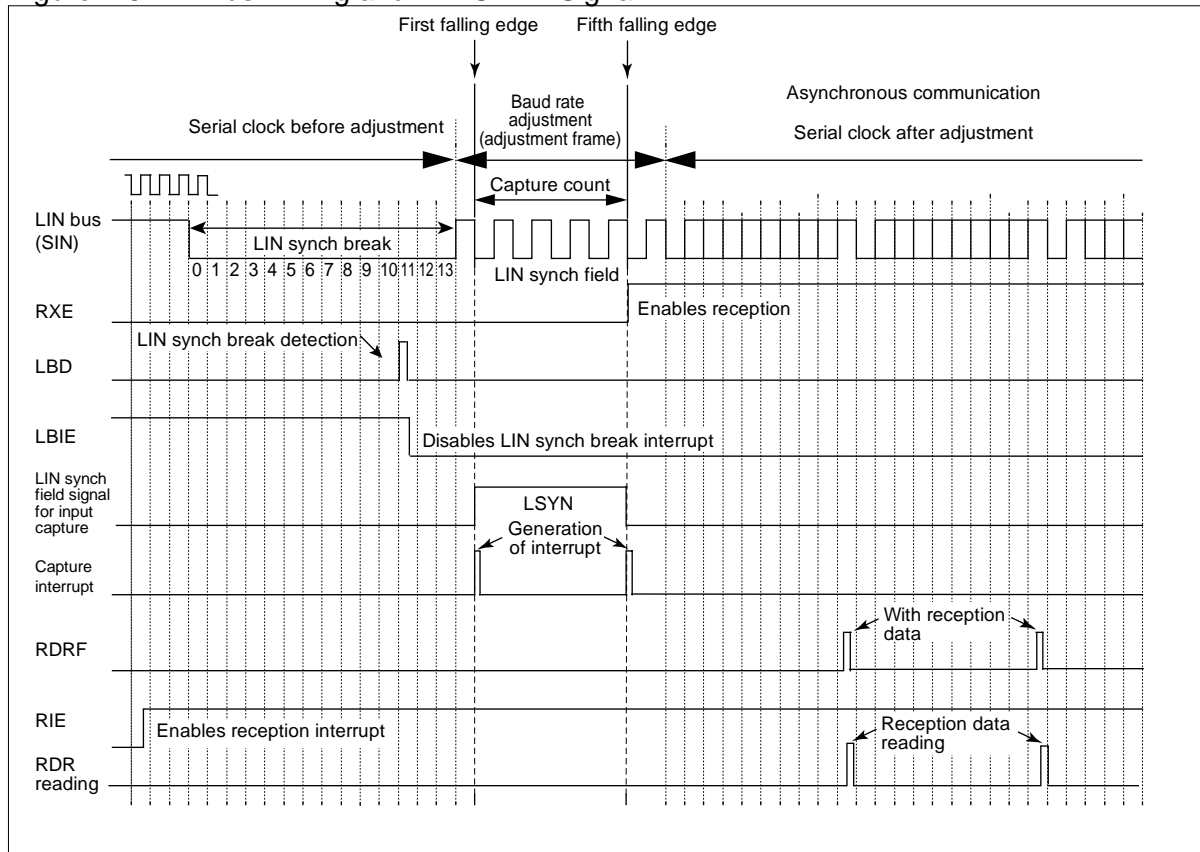
Figure 7-8 LIN Slave Operation



7.4.4. LIN Bus Timing

LIN bus timing is shown below.

Figure 7-9 LIN Bus Timing and LIN-UART Signal



7.4.5. Baud Rate Calculation

Baud rate calculation is explained.

As an example, the operation of LIN-UART ch.3 is described below. When the LIN-UART ch.3 detects the first falling edge of Synch Field, it sets the internal signal to be input to the input capture (ICU1) to "H" and starts the ICU1. This internal signal becomes "L" on the 5th falling edge. ICU1 needs to be set to LIN mode (LSYNS0:LSYN1). In addition, it is necessary to enable ICU1 interrupt (ICS01:ICE1) and detection of both edges (ICS01:EG11, ICS01:EG10). The time of when the input ICU1 signal is "1" will be equal to the baud rate multiplied by 8. The baud rate setting value can be calculated based on the following formula:

● **If the free-run timer has not overflowed:**

$$\text{BGR value} = \{(b - a) \times Fe / (8 \times \phi) - 1\}$$

● **If the free-run timer has overflowed:**

$$\text{BGR value} = \{(\text{max} + 1 + b - a) \times Fe / (8 \times \phi)\} - 1$$

max: Free-run timer maximum value

a: ICU data register value after the first interrupt

b: ICU data register value after the second interrupt

ϕ : Machine clock frequency (MHz)

Fe: External clock frequency (MHz)

It is assumed that the internal baud rate generator is used (EXT=0) and $Fe = \phi$.

Note:

As described above, do not set the baud rate if an error of baud rate $\pm 15\%$ or greater occurs in the new BGR value calculated in the Synch field in LIN slave mode.

For the relationship between LIN-UART and ICU, see "5. Operation Description" in "CHAPTER : FREE-RUN TIMER" and "5. Operation Description" in "CHAPTER : INPUT CAPTURE".

7.4.6. Clock Usage

Clock usage is shown below.

The internal clock is used. As for the baud rate, select the baud rate generator (SMR:EXT=0 or 1, and OTO=0).

7.4.7. Data Signaling Method

The data signaling method is shown below.

This is based on the NRZ data format.

7.4.8. Stop Bit

The stop bit is shown below.

When transmitting, the stop bit in 1-bit or 2-bit can be selected. When only the first stop bit is received, it is detected when the stop bit in 2-bit is selected.

If the first stop bit is detected, the reception data register full flag (SSR:RDRF) will be set to "1". If no start bit is detected after that, the reception bus idle flag (ECCR:RBI) will be set to "1" to indicate that the reception operation is not activated.

7.4.9. Error Detection

Error detection is shown below.

An overrun error and a framing error can be detected.

7.5. Direct Access to the Serial Pin

Direct access to the serial pin is shown below.

LIN-UART can directly access the transmission pin (SOT) and reception pin (SIN).

With LIN-UART, a programmer can directly access the serial I/O pin.

It is possible to read the status of the serial input pin (SIN) using the serial I/O pin direct access bit (ESCR:SIOP).

If serial output is enabled (SMR:SOE=1) after enabling direct writing to the serial output pin (SOT) (ESCR:SOPE=1) and writing "0" or "1" in the serial I/O pin direct access bit (ESCR:SIOP), it will be possible to set any value in the serial output pin (SOT).

In the LIN mode, it is possible to apply this procedure to read the transmitted data or handle errors when the physical LIN bus line signal was incorrect.

Note:

Access is allowed only when no transmission operation is in progress (i.e. when the transmission shift register is empty). Prior to accessing the output pin (SMR:SOE=1), write a value in the serial I/O pin direct access bit (ESCR:SIOP). This task prevents any unexpected level of signal from being output as the previous value is retained in the SIOP bit. In a read-modify-write operation, the value of the SOT pin in the read cycle is returned.

7.6. Bidirectional Communication Function (Normal Mode)

The bidirectional communication function (Normal mode) is shown below.

Normal serial bidirectional communication is allowed in operation mode 0 and mode 2. You can select asynchronous communication in operation mode 0, and synchronous communication in operation mode 2.

The figure below shows the LIN-UART settings in normal mode (operation mode 0 and mode 2).

Figure 7-10 LIN-UART Settings in Operation Mode 0 and Mode 2

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR,SMR	PEN	P	SBL	CL	AD	CRE	RXE	TXE	MD1	MD0	OTO	EXT	REST	UPCL	SCKE	SOE
Mode 0 →	⊙	⊙	⊙	⊙	x	0	⊙	⊙	0	0	0	⊙	0	0	⊙	⊙
Mode 2 →	□	□	□	+	x	0	⊙	⊙	1	0	⊙	⊙	0	0	⊙	⊙
SSR, TDR/RDR	PE	ORE	FRE	RDRF	TDRE	BDS	RIE	TIE	Sets conversion data (at writing)/ Retains reception data (at reading)							
Mode 0 →	⊙	⊙	⊙	⊙	⊙	⊙	⊙	⊙								
Mode 2 →	□	⊙	□	⊙	⊙	⊙	⊙	⊙								
ESCR,ECCR	LBIE	LBD	LBL1	LBL0	SOPE	SIOP	CCO	SCES	Reserved	LBR	MS	SCDE	SSM	Reserved	RBI	TBI
Mode 0 →	x	x	x	x	⊙	⊙	0	+	0	0	x	x	x	0	⊙	⊙
Mode 2 →	x	x	x	x	⊙	⊙	□	⊙	0	x	⊙	⊙	⊙	0	□	□

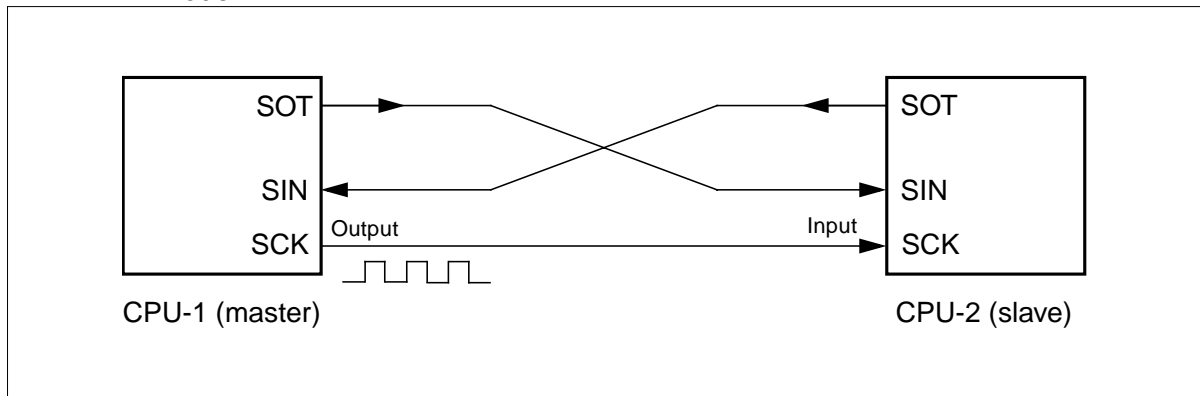
⊙ : Used bit
 x : Unused bit
 □ : Only ECCR:SSM=1 (synchronization start/stop bit mode) can be used
 1 : Sets to "1"
 0 : Sets to "0"
 + : Bit that is automatically set correctly

7.6.1. Connection between CPUs

The connection between CPUs is shown below.

The connection between 2 CPUs in LIN-UART mode 2 is shown below:

Figure 7-11 Connection Example for Bidirectional Communication in LIN-UART Operation Mode 2

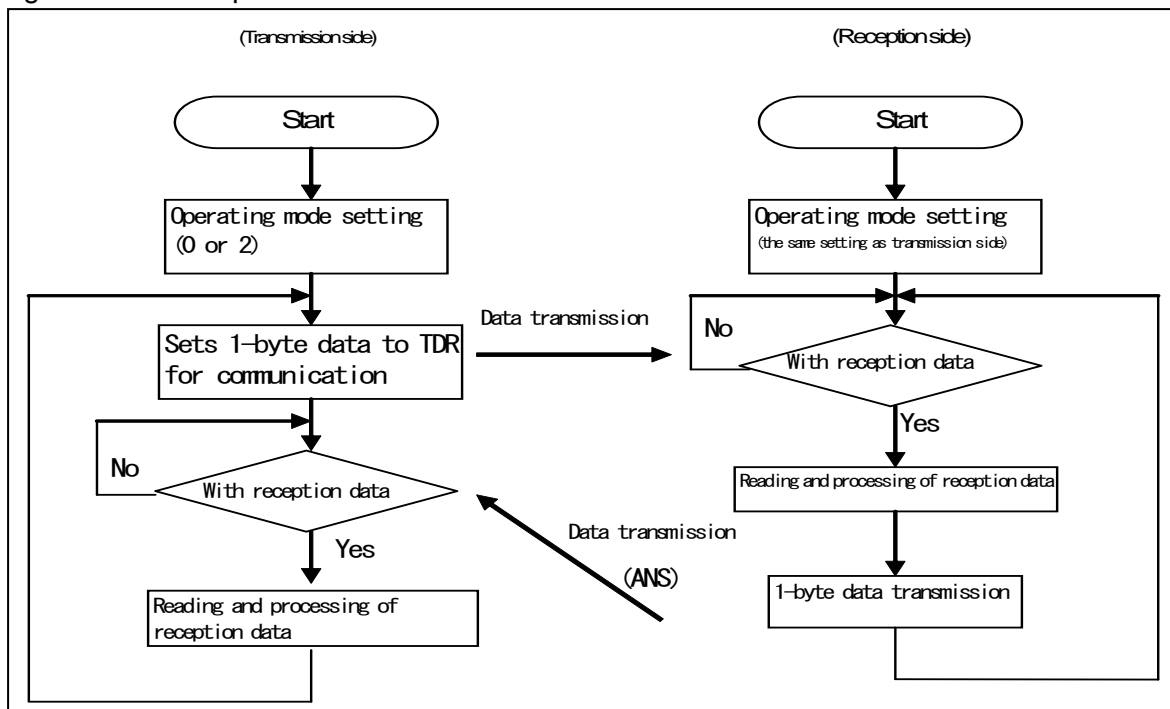


7.6.2. Communication Procedure

The communication procedure is shown below.

Communication is triggered by the transmitting side when transmission data becomes ready. When transmission data is received by the receiving side, ANS (1 byte in the example) is returned on a periodic basis. A flowchart example of bidirectional communication is shown below:

Figure 7-12 Example of Bidirectional Communication Flowchart



7.7. Master/ Slave Mode Communication Function (Multi-processor Mode)

The master/ slave mode communication function (Multi-processor mode) is shown below.

In operation mode 1, communications can be performed via master-slave connection between multiple CPUs. It can be used either as a master or slave.

The LIN-UART settings in multi-processor mode (operation mode 1) are shown below:

Figure 7-13 LIN-UART Settings in Operation Mode 1

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR,SMR	PEN	P	SBL	CL	AD	CRE	RXE	TXE	MD1	MD0	OTO	EXT	REST	UPCL	SCKE	SOE
Mode 1 →	x	x	⊙	⊙	⊙	0	⊙	⊙	0	1	0	⊙	0	0	0	⊙
SSR, TDR/RDR	PE	ORE	FRE	RDRF	TDRE	BDS	RIE	TIE	Sets conversion data (at writing)/ Retains reception data (at reading)							
Mode 1 →	x	⊙	⊙	⊙	⊙	⊙	⊙	⊙								
ESCR,ECCR	LBIE	LBD	LBL1	LBL0	SOPE	SIOP	CCO	SCES	Reserved	LBR	MS	SCDE	SSM	Reserved	RBI	TBI
Mode 1 →	x	x	x	x	⊙	⊙	0	+	0	x	x	x	x	0	⊙	⊙

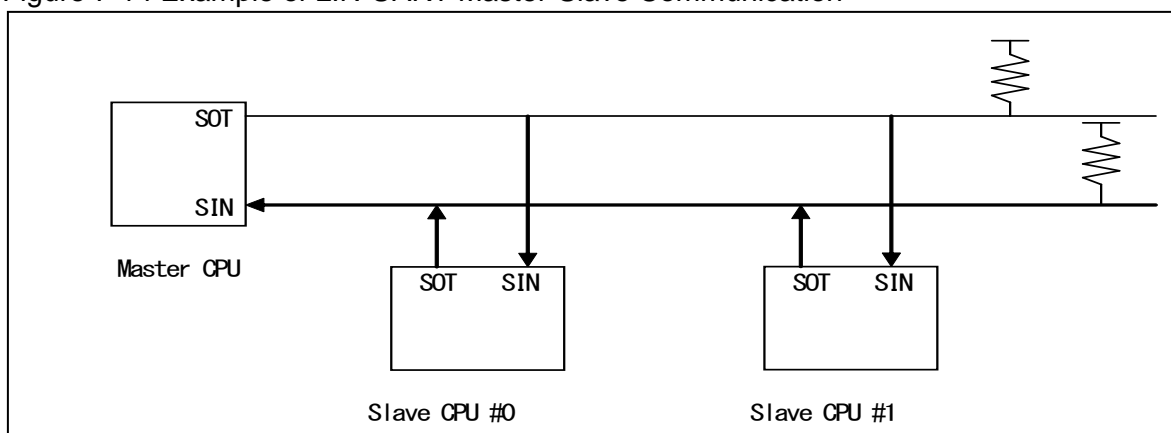
⊙ : Used bit
 x : Unused bit
 1 : Sets to "1"
 0 : Sets to "0"
 + : Bit that is automatically set correctly

7.7.1. Connection between CPUs

The connection between CPUs is shown below.

The figure below shows a communication system consisting of a master CPU and multiple slave CPUs that are connected with 2 communication lines. LIN-UART can be used either as a master or slave.

Figure 7-14 Example of LIN-UART Master-Slave Communication



7.7.2. Function Selection

The function selection is shown below.

For a master-slave communication, select an operation mode and data transfer method as shown in the table below:

Table 7-2 Setting of Master/Slave Communication Function

	Operation Mode		Data	Parity	Synchronization method	Stop bit	Bit direction
	Master CPU	Slave CPU					
Address transmission and reception	Mode 1 (AD bit transmission and reception)		AD="1" + 7 or 8-bit address	No	Asynchronous	1 bit or 2 bits	LSB or MSB First
Data transmission and reception			AD="0" + 7 or 8-bit data				

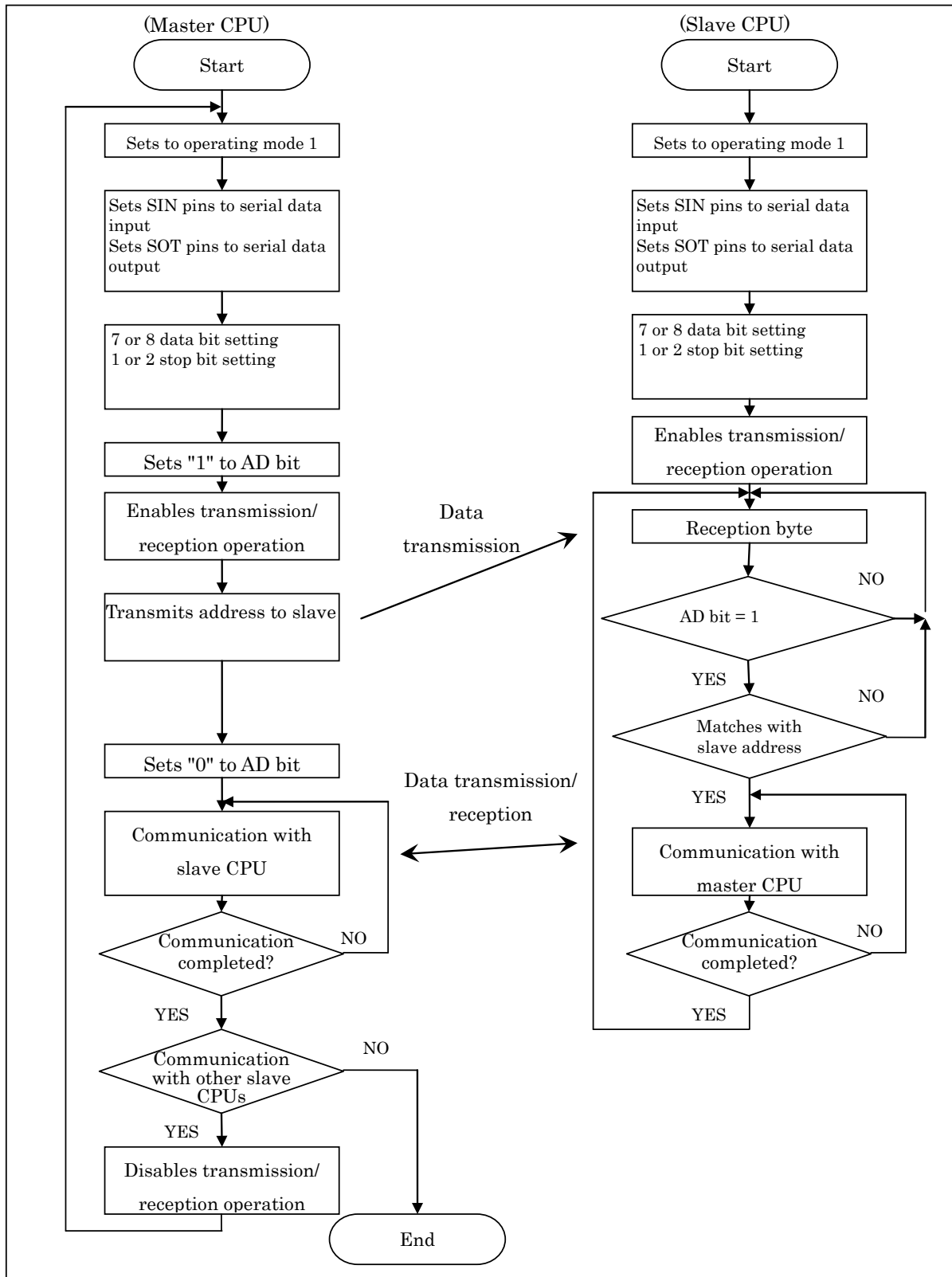
7.7.3. Communication Procedure

The communication procedure is shown below.

Communications start when the master CPU transmits address data. Address data refers to data with the AD bit set to "1" and is used to select a slave CPU as the communication destination. Slave CPUs interpret address data via a program and the data with a matching address will communicate with the master CPU.

A flowchart example of a master-slave communication (multi-processor mode) is shown below:

Figure 7-15 Master/Slave Communication Flowchart



7.8. LIN Communication Function

The LIN communication function is shown below.

LIN master/slave systems can be used in the LIN device during LIN-UART communication.

7.8.1. LIN Master/Slave Communication Function

The LIN master/slave communication function is shown below.

The LIN-UART settings in the LIN communication mode (operation mode 3) are shown below:

Figure 7-16 LIN-UART Setting in Operation Mode 3 (LIN)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SCR,SMR	PEN	P	SBL	CL	AD	CRE	RXE	TXE	MD1	MD0	OTO	EXT	REST	UPCL	SCKE	SOE
Mode 3 →	x	x	(0)	(1)	x	0	⊙	⊙	1	1	0	⊙	0	0	0	⊙
SSR, TDR/RDR	PE	ORE	FRE	RDRFTDRE	BDS	RIE	TIE	Sets conversion data (at writing)/ Retains reception data (at reading).								
Mode 3 →	x	⊙	⊙	⊙	⊙	(0)	⊙	⊙								
ESCR,ECCR	LBIE	LBD	LBL1	LBL0	SOPE	SIOP	CCO	SCES	Reserved	LBR	MS	SCDE	SSM	Reserved	RBI	TBI
Mode 3 →	⊙	⊙	⊙	⊙	⊙	⊙	0	+	0	⊙	x	x	x	0	⊙	⊙

⊙ : Used bit
 x : Unused bit
 1 : Sets to "1"
 0 : Sets to "0"
 (1) : Fixed to "1"
 (0) : Fixed to "0"
 + : Bit that is automatically set correctly

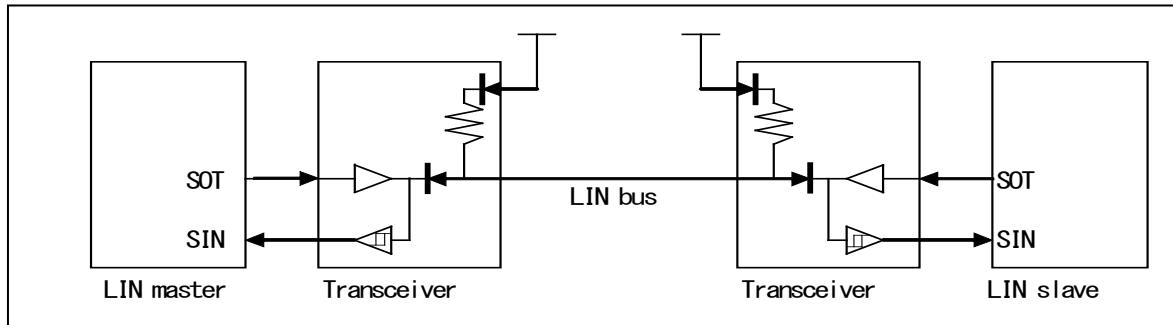
7.8.2. LIN Device Connection

The LIN device connection is shown below.

The connection of the LIN master and LIN slave devices is shown below.

LIN-UART can be set as LIN master or LIN slave.

Figure 7-17 Example of LIN Bus System Connection



7.9. LIN-UART Sample Flowchart in LIN Communication Mode (Operation Mode 3)

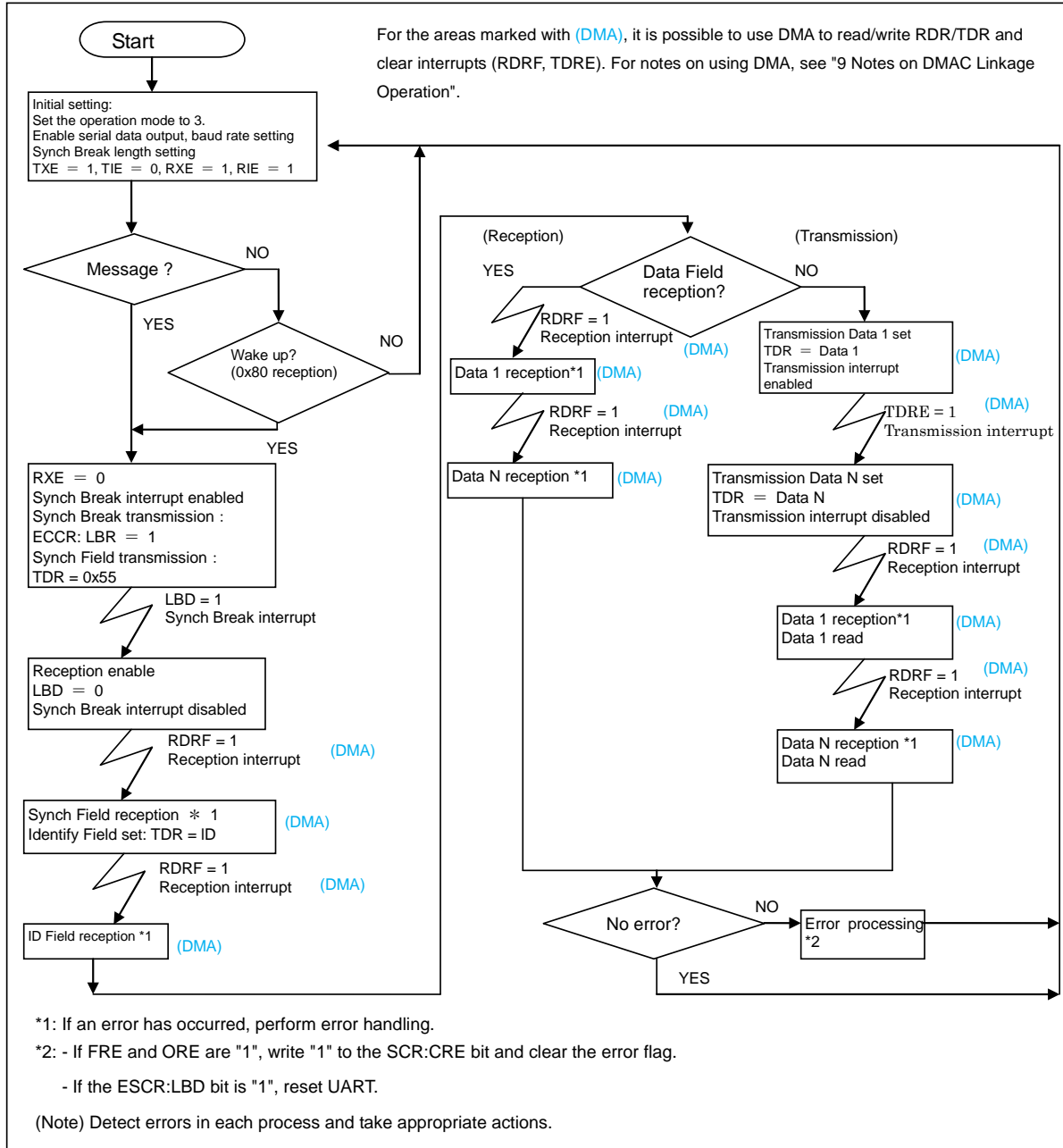
The LIN-UART sample flowchart in LIN communication mode (Operation mode 3) is shown below.

A LIN-UART flowchart example in the LIN communication mode is shown below.

7.9.1. LIN-UART as a Master Device

LIN-UART as a master device is shown below.

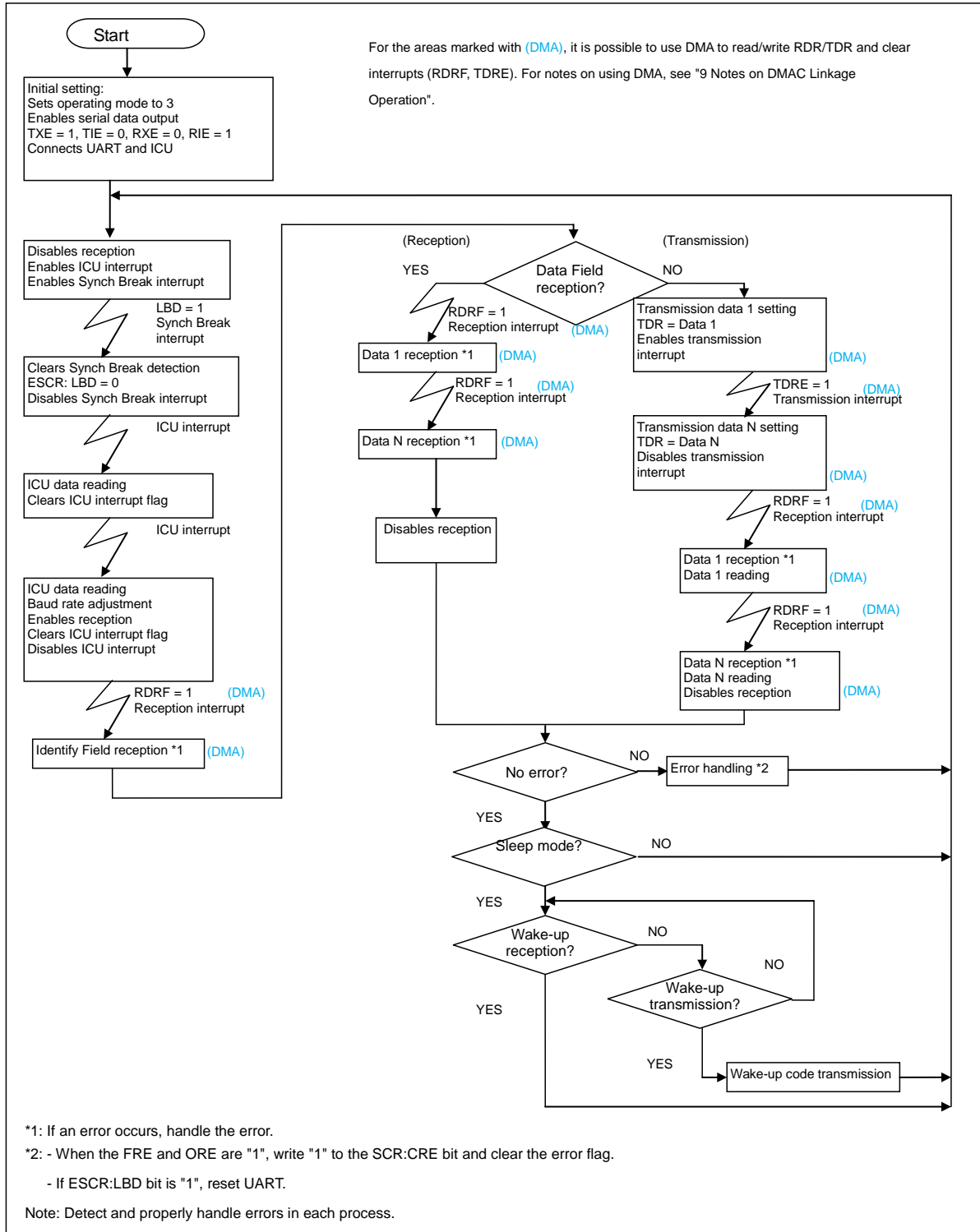
Figure 7-18 LIN-UART Flowchart in LIN Master Mode



7.9.2. LIN-UART as a Slave Device

LIN-UART as a slave device is shown below.

Figure 7-19 LIN-UART Flowchart in the LIN Slave Mode



8. Notes on Usage

Notes on usage are shown below.

Notes on using LIN-UART are shown below.

8.1. Operation Enable

Operation enable is shown below.

LIN-UART has TXE (transmission) and RXE (reception) operation enable bits in the serial control register (SCR) for transmission and reception, respectively. It is necessary to enable the operation before data transfer because both transmission and reception are disabled in the default setting (initial value). It is also possible to disable operation and cancel data transfer as needed.

8.2. Communication Mode Setting

The communication mode setting is shown below.

The communication mode must be changed while the LIN-UART operation is inactive. If the mode is changed while transmission or reception is in progress, the transmitted/received data cannot be guaranteed.

8.3. Timing of Enabling Transmission Interrupt

Timing of enabling transmission interrupt is shown below.

For the transmission data empty flag bit (SSR:TDRE), the default value (initial value) is set to "1" (no transmission data; writing of transmission data enabled). Therefore, a transmission interrupt request is generated as soon as transmission interrupt request is enabled (SSR:TIE=1). Always set the TIE flag to "1" after setting the transmission data.

8.4. Operation Setting Change

The operation setting change is shown below.

After changing any setting, such as adding a start/stop bit or changing the data format, it is recommended that you reset LIN-UART.

Setting the serial mode register (SMR) and resetting LIN-UART (SMR:UPCL=1) at the same time does not guarantee correct operation setting. Therefore, it is recommended that you reset LIN-UART (SMR:UPCL=1) again after setting the bit in the serial mode register (SMR).

8.5. Detection of a LIN Synch Break

Detection of a LIN synch break is shown below.

LIN synch break transmission time varies depending on the oscillation accuracy error between master and slave. The slave can detect LIN synch break with the length of 11 serial bits or longer.

If serial input is "0" for 11-bit width or more in mode 3 (LIN mode), LIN synch break is detected (ESCR:LBD=1) and LIN-UART will wait for synch field.

Therefore, if serial input is "0" for 11 bits or more at any point other than LIN synch break, LIN-UART recognizes it as synch break has been input (LBD=1) and will wait for synch field. In this case, reset LIN-UART (SMR:UPCL=1).

8.6. LIN Slave Setting

The LIN slave setting is shown below.

To ensure that the minimum 13-bit length of LIN synch break is detected, set the baud rate before receiving the first LIN synch break when activating the LIN slave.

8.7. Program Compatibility

The program compatibility is shown below.

LIN-UART is similar to the old FJ-UART. However, these two programs are not compatible. The programming type may be the same in some cases, but the register structure is different. Furthermore, at present, the baud rate setting is determined by the reload value, instead of selecting a predefined value.

8.8. Address/Data Format Selection Bit (SCR:AD)

The address/data format selection bit is shown below.

- The AD bit of the serial control register (SCR) performs the transmission address/data selection setting at the time of writing and returns the value of the last received AD bit at the time of reading. Internally, the transmission/reception AD bit values are stored in the individual registers.
- The read-modify-write instruction reads the value of the transmitted AD bit data.
- During the transmission operation (when the TDRE bit changes from "0" to "1"), the transmission AD bit is loaded to the transmission shift register together with data in the transmission data register (TDR). Hence, set the transmission AD bit before writing to the transmission data register (TDR).

8.9. LIN-UART Software Reset

LIN-UART software reset is shown below.

Perform LIN-UART software reset (SMR:UPCL=1) when the TXE bit of the serial control register (SCR) is "0".

8.10. Detection of LIN Synch Field in Input Capture

Detection of LIN synch field in input capture is shown below.

It is necessary to set the LSYNS0 register in input capture. See "CHAPTER : INPUT CAPTURE".

9. Notes on DMAC Linkage Operation

Notes on the DMAC linkage operation are shown below.

LIN-UART transmission and reception interrupts are allocated to the DMAC transfer factor making it possible to write transmission data and read reception data using the DMA data transfer function.

9.1. Transmission Operation

The transmission operation is shown below.

Perform dummy writing (writing of any data) to the transmission data register (TDR) before starting the LIN-UART transmission operation (SCR:TXE=1) and before activating the transmission interrupt request enable bit (SSR:TIE=1). In addition, issue a LIN-UART software reset (SMR:UPCL=1) to discard TDR data.

Depending on a previously performed LIN-UART transfer operation (including the case in which DMAC was not used), there is a possibility that an interrupt request to DMAC might not be issued correctly. The purpose of the operation described above is to restore the state required to correctly issue an interrupt request to DMAC.

9.2. Reception Operation

The reception operation is shown below.

Perform the reception data register (RDR) read operation before starting the LIN-UART reception operation (SCR:RXE=1) and before activating the reception interrupt enable bit (SSR:RIE=1).

Occurrence of an error during LIN-UART reception and other factors may cause unnecessary reception data to stay in the reception data register (RDR). This will prevent an interrupt request to DMAC from being issued correctly.

It is possible to disable the reception data by issuing a LIN-UART software reset (SMR:UPCL=1). However, read the reception data register (RDR) to ensure that subsequent DMA transfers will be performed correctly.

CHAPTER : CAN

This chapter explains the CAN.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains the overview of the CAN.

This series includes three CAN channels.

The CAN is based on the CAN protocol ver. 2.0A/B, which is a standard protocol for serial communication and is widely used for automobiles, FA, and other industrial fields.

2. Features

This section explains the features of the CAN.

The CAN of this series has the following features:

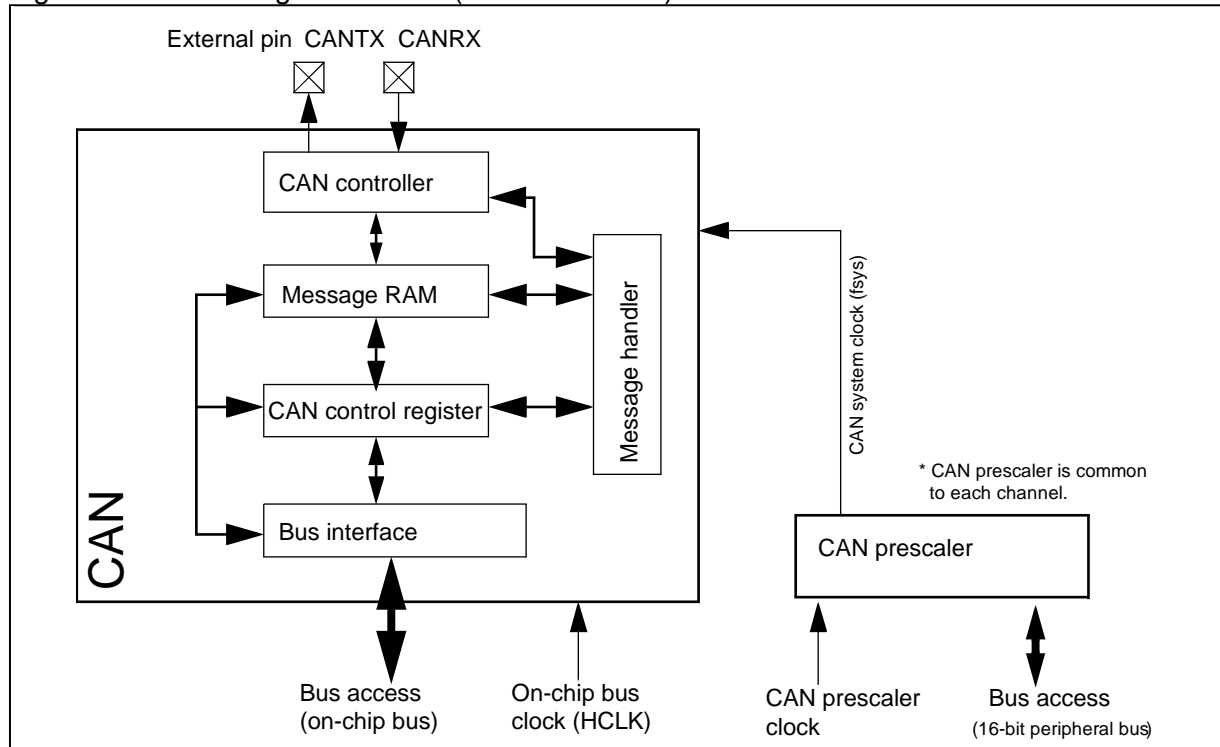
- CAN protocol ver. 2.0A/B is supported.
- Bit rates up to 1 Mbits/s are supported.
- An identification mask is applied to each message object.
- Programmable FIFO mode is supported.
- Maskable interrupts.
- Programmable loopback mode for self-test operation is supported.
- Data can be written to and read from a message buffer using an interface register.
- Support 32/64/128 message buffers. As the number depends on products and channels, see "CHAPTER : OVERVIEW".

3. Configuration

This section explains the configuration of the CAN.

A block diagram of the CAN is shown below:

Figure 3-1 Block Diagram of CAN (for one channel)



CAN controller

The CAN controller controls the CAN protocol and serial registers for serial/parallel conversion to transfer the transmission/reception message.

Message RAM

Stores message objects.

Message handler

Controls the message RAM and CAN controller.

CPU interface

Controls the interface with the FR internal bus.

CAN prescaler

Generates CAN system clocks (fsys).

4. Registers

The registers of the CAN are shown.

- 4.1. Overview
- 4.2. Overall Control Registers
- 4.3. Message Interface Register
- 4.4. Message Object
- 4.5. Message Handler Registers
- 4.6. CAN Prescaler Register (CANPRE)

4.1. Overview

This section explains the overview of the registers of the CAN.

The CAN includes the following registers:

- CAN control register (CTRLR)
- CAN status register (STATR)
- CAN error counter (ERRCNT)
- CAN bit timing register (BTR)
- CAN interrupt register (INTR)
- CAN test register (TESTR)
- CAN prescaler extension register (BRPER)
- IFx command request registers (IFxCREQ)
- IFx command mask registers (IFxCMSK)
- IFx mask registers 1, 2 (IFxMSK1, IFxMSK2)
- IFx arbitration registers 1, 2 (IFxARB1, IFxARB2)
- IFx message control register (IFxMCTR)(IFxMCTR)
- IFx data registers A1, A2, B1, B2 (IFxDTA1, IFxDTA2, IFxDTB1, IFxDTB2)
- CAN transmission request registers 1, 2 (TREQR1,TREQR2)
- CAN New Data registers 1, 2 (NEWDT1,NEWDT2)
- CAN interrupt pending registers 1, 2 (INTPND1,INTPND2)
- CAN message valid registers 1, 2 (MSGVAL1,MSGVAL2)
- CAN clock prescaler register (CANPRE)

The CAN register is given an address space of 256 bytes (64 words) and accessible in byte or word mode.
The CPU accesses the message RAM via a message interface register.

■ List of Base_addresses (Base_addr) and External Pins

Channel number	Base_addr	External pin name	
		CANTX	CANRX
0	0x2000	TX0	RX0
1	0x2100	TX1	RX1
2	0x2200	TX2	RX2

■ **List of Overall Control Register**

Table 4-1 List of Overall Control Register

Address	Registers				Note
	+0	+1	+2	+3	
Base_addr + 00 _H	CAN control register (CTRLR)		CAN status register (STATR)		STAR: BOff, EWarn, Epass = Read only RxOk, TxOk, LEC = Read/Write
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	Reserved bits	See the CTRLR.	Reserved bits	See the STATR.	
	Reset: 00 _H	Reset: 01 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 04 _H	CAN error counter (ERRCNT)		CAN bit timing register (BTR)		ERRCNT: Read only BTR: Write is enabled when Init(CTRLR) = CCE(CTRLR) = "1"
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	RP, REC[6:0]	TEC[7:0]	TSeg2[2:0], TSeg1[3:0]	SJW[1:0], BRP[5:0]	
	Reset: 00 _H	Reset: 00 _H	Reset: 23 _H	Reset: 01 _H	
Base_addr + 08 _H	CAN interrupt register (INTR)		CAN test register (TESTR)		INTR: Read only TESTR: Write is enabled when Test(CTRLR) = "1" "Rx" indicates the level at the CAN_RX pin.
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	IntId[15:8]	IntId[7:0]	Reserved bits	See the TESTR.	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H & 0br0000000	
Base_addr + 0C _H	CAN prescaler extension register (BRPER)		Reserved bits		BRPER: Write is enabled when CCE(CTRLR) = "1"
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	Reserved bits	BRPE[3:0]	-	-	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	

■ **List of Message Interface Register**

Table 4-2 List of Message Interface Register

Address	Registers				Note
	+0	+1	+2	+3	
Base_addr + 10 _H	IF1 command request register (IF1CREQ)		IF1 command mask register (IF1CMSK)		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	BUSY	Mess. No. [5:0]	Reserved bits	See the IF1CMSK.	
	Reset: 00 _H	Reset: 01 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 14 _H	IF1 mask register 2 (IF1MSK2)		IF1 mask register 1 (IF1MSK1)		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	MXtd, MDir, Msk[28:24]	Msk[23:16]	Msk[15:8]	Msk[7:0]	
	Reset: FF _H	Reset: FF _H	Reset: FF _H	Reset: FF _H	
Base_addr + 18 _H	IF1 arbitration register 2 (IF1ARB2)		IF1 arbitration register 1 (IF1ARB1)		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	MsgVal, Xtd, Dir, ID[28:24]	ID[23:16]	ID[15:8]	ID[7:0]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 1C _H	IF1 message control register (IF1MCTR)		Reserved bits		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	See the IF1MCTR.	See the IF1MCTR.	-	-	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 20 _H	IF1 data A register 1 (IF1DTA1)		IF1 data A register 2 (IF1DTA2)		Byte order: Big Endian
	bit[7:0]	bit[15:8]	bit[7:0]	bit[15:8]	
	Data[0]	Data[1]	Data[2]	Data[3]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 24 _H	IF1 data B register 1 (IF1DTB1)		IF1 data B register 2 (IF1DTB2)		Byte order: Big Endian
	bit[7:0]	bit[15:8]	bit[7:0]	bit[15:8]	
	Data[4]	Data[5]	Data[6]	Data[7]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	

Address	Registers				Note
	+0	+1	+2	+3	
Base_addr + 30 _H	IF1 data A register 2 (IF1DTA2)		IF1 data A register 1 (IF1DTA1)		Byte order: Little Endian
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	Data[3]	Data[2]	Data[1]	Data[0]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 34 _H	IF1 data B register 2 (IF1DTB2)		IF1 data B register 1 (IF1DTB1)		Byte order: Little Endian
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	Data[7]	Data[6]	Data[5]	Data[4]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 40 _H	IF2 command request register (IF2CREQ)		IF2 command mask register (IF2CMSK)		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	BUSY	Mess. No. [5:0]	Reserved bits	See the IF2CMSK.	
	Reset: 00 _H	Reset: 01 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 44 _H	IF2 mask register 2 (IF2MSK2)		IF2 mask register 1 (IF2MSK1)		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	MXtd, MDir, Msk[28:24]	Msk[23:16]	Msk[15:8]	Msk[7:0]	
	Reset: FF _H	Reset: FF _H	Reset: FF _H	Reset: FF _H	
Base_addr + 48 _H	IF2 arbitration register 2 (IF2ARB2)		IF2 arbitration register 1 (IF2ARB1)		
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	MsgVal, Xtd, Dir,ID[28:24]	ID[23:16]	ID[15:8]	ID[7:0]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 4C _H	IF2 message control register (IF2MCTR)		Reserved bits		
	bit[15:8]	bit[7:0]	bit[7:0]	bit[15:8]	
	See the IF2MCTR.	See the IF2MCTR.	-	-	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	

Address	Registers				Note
	+0	+1	+2	+3	
Base_addr + 50 _H	IF2 data A register 1 (IF2DTA1)		IF2 data A register 2 (IF2DTA2)		Byte order: Big Endian
	bit[7:0]	bit[15:8]	bit[7:0]	bit[15:8]	
	Data[0]	Data[1]	Data[2]	Data[3]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 54 _H	IF2 data B register 1 (IF2DTB1)		IF2 data B register 2 (IF2DTB2)		Byte order: Big Endian
	bit[7:0]	bit[15:8]	bit[7:0]	bit[15:8]	
	Data[4]	Data[5]	Data[6]	Data[7]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 60 _H	IF2 data A register 2 (IF2DTA2)		IF2 data A register 1 (IF2DTA1)		Byte order: Little Endian
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	Data[3]	Data[2]	Data[1]	Data[0]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 64 _H	IF2 data B register 2 (IF2DTB2)		IF2 data B register 1 (IF2DTB1)		Byte order: Little Endian
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	Data[7]	Data[6]	Data[5]	Data[4]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	

■ **List of Message Handler Register**

Table 4-3 List of Message Handler Register

Address	Registers				Note
	+0	+1	+2	+3	
Base_addr + 80 _H	CAN transmission request register 2 (TREQR2)		CAN transmission request register 1 (TREQR1)		INTR1, 2: Read only
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	TxRqst[32:25]	TxRqst[24:17]	TxRqst[16:9]	TxRqst[8:1]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 84 _H Base_addr + 88 _H Base_addr + 8C _H	Reservation area for supporting 32 or more message buffers (See CAN transmission request registers (TREQR1, TREQR2)) TREQ3 to TREQ4: 64 message buffers are supported TREQ3 to TREQ6: 96 message buffers are supported TREQ3 to TREQ8: 128 message buffers are supported				
Base_addr + 90 _H	CAN new data register 2 (NEWDT2)		CAN new data register 1 (NEWDT1)		NEWDT1, 2: Read only
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	NewDat[32:25]	NewDat[24:17]	NewData[16:9]	NewData[8:1]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + 94 _H Base_addr + 98 _H Base_addr + 9C _H	Reservation area for supporting 32 or more message buffers (See CAN data update registers (NEWDT1, NEWDT2)) NEWDT3 to NEWDT4: 64 message buffers are supported NEWDT3 to NEWDT6: 96 message buffers are supported NEWDT3 to NEWDT8: 128 message buffers are supported				
Base_addr + A0 _H	CAN interrupt pending register 2 (INTPND2)		CAN interrupt pending register 1 (INTPND1)		INTPND1, 2: Read only
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	IntPnd[32:25]	IntPnd[24:17]	IntPnd[16:9]	IntPnd[8:1]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	
Base_addr + A4 _H Base_addr + A8 _H Base_addr + AC _H	Reservation area for supporting 32 or more message buffers (See CAN interrupt pending registers (INTPND1, INTPND2)) INTPND3 to INTPND4: 64 message buffers are supported INTPND3 to INTPND6: 96 message buffers are supported INTPND3 to INTPND8: 128 message buffers are supported				
Base_addr + B0 _H	CAN message valid register 2 (MSGVAL2)		CAN message valid register 1 (MSGVAL1)		MSGVAL1, 2: Read only
	bit[15:8]	bit[7:0]	bit[15:8]	bit[7:0]	
	MsgVal[32:25]	MsgVal[24:17]	MsgVal[16:9]	MsgVal[8:1]	
	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	Reset: 00 _H	

Address	Registers				Note
	+0	+1	+2	+3	
Base_addr + B4 _H	Reservation area for supporting 32 or more message buffers (See CAN message valid registers (MSGVAL1, MSGVAL2))				
Base_addr + B8 _H					
Base_addr + BC _H					
	MSGVAL3 to MSGVAL4: 64 message buffers are supported				
	MSGVAL3 to MSGVAL6: 96 message buffers are supported				
	MSGVAL3 to MSGVAL8: 128 message buffers are supported				

■ Clock Prescaler Register

Table 4-4 Clock Prescaler Register

Address	Registers				Note
	+0	+1	+2	+3	
00_04A4 _H	CANPRE	-	-	-	CAN Prescaler
	bit[3:0]	-	-	-	
	CANPRE[3:0]	-	-	-	
	Reset: 00 _H	-	-	-	

■ Overall Control Registers

- CAN control register (CTRLR)
- CAN status register (STATR)
- CAN error counter (ERRCNT)
- CAN bit timing register (BTR)
- CAN interrupt register (INTR)
- CAN test register (TESTR)
- CAN prescaler extension register (BRPER)

■ Message Interface Register

- IFx command request register (IFxCREQ)
- IFx command mask register (IFxCMSK)
- IFx mask registers 1, 2 (IFxMSK1, IFxMSK2)
- IFx arbitration registers 1, 2 (IFxARB1, IFxARB2)
- IFx message control register (IFxMCTR)
- IFx data registers A1, A2, B1, B2 (IFxDTA1, IFxDTA2, IFxDTB1, IFxDTB2)

■ Message Handler Register

- CAN transmission request registers 1, 2 (TREQR1, TREQR2)
- CAN data update registers 1, 2 (NEWDT1, NEWDT2)
- CAN interrupt pending registers 1, 2 (INTPND1, INTPND2)
- CAN message valid registers 1, 2 (MSGVAL1, MSGVAL2)

■ Prescaler Register

- CAN clock prescaler register (CANPRE)

4.2. Overall Control Registers

Overall control registers are shown.

Overall control registers control the CAN protocol and operation modes and provide status information.

- CAN control register (CTRLR)
- CAN status register (STATR)
- CAN error counter (ERRCNT)
- CAN bit timing register (BTR)
- CAN interrupt register (INTR)
- CAN test register (TESTR)
- CAN prescaler extension register (BRPER)

4.2.1. CAN Control Register (CTRLR)

The bit configuration of the CAN control register is shown.

Controls the operation mode of the CAN controller.

■ **CAN Control Register (upper byte): Address Base_addr+00_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **CAN Control Register (lower byte): Address Base_addr+01_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Test	CCE	DAR	Reserved	EIE	SIE	IE	Init
Initial value	0	0	0	0	0	0	0	1
Attribute	R/W	R/W	R/W	R0,W0	R/W	R/W	R/W	R/W

[bit15 to bit8] Reserved

The read value is always "0". When writing to these bits, set "0".

[bit7] Test : Test mode enable bit

Test	Function
0	Normal operation [Initial value]
1	Test mode

Note:

Set "1" to the Test bit only when the Init bit is "1".

[bit6] CCE : Bit timing register write enable bit

CCE	Function
0	Disables the writing to the CAN bit timing register (BTR) and the CAN prescaler extension register (BRPER). [Initial value]
1	Enables the writing to the CAN bit timing register (BTR) and the CAN prescaler extension register (BRPER). This bit is valid when the Init bit is "1".

[bit5] DAR : Automatic retransmission disable bit

DAR	Function
0	Enables the automatic retransmission of the message when CAN loses the arbitration or when an error is detected. [Initial value]
1	Disables automatic retransmission.

The CAN controller retransmits the frame automatically when it loses the arbitration or when an error is detected during transfer. To enable automatic retransmission, set "0" to the DAR bit. In order to operate CAN in Time Triggered CAN environments, "1" needs to be set to the DAR bit.

Notes:

When "1" is set to the DAR bit, the values for the TxRqst and NewDat bits of the message objects are as follows: (For message objects, see "4.4 Message Object".)

- When frame transmission is started, the TxRqst bit for the message object is cleared to "0", but the NewDat bit remains to be "1".
- When frame transmission is completed successfully, the NewDat bit is cleared to "0". When the transmission loses the arbitration or when an error is detected, the NewDat bit remains to be set to "1". To restart the transmission, set "1" to the TxRqst bit.
- When the DAR bit in the CAN control register (CTRLR) is changed from "0" to "1" during frame transmission (TxRqst=1), the frame that is being sent is retried. Thus, change the DAR bit only when the Init bit is "1".
- The transmission operations when "1" is set to the DAR bit and several message buffers are used are as follows:
- When "1" is set to TxRqst of *other* message buffers (when "1" is set to TxRqst of several message buffers) before CAN starts frame transmission or during transmission, all TxRqst set are reset to "0" and the data of the highest order message buffer is sent when frame transmission is started.
- When frame transmission is completed successfully, NewDat of sent message buffer is reset to "0", and IntPnd of the message object is set to "1" when the TxIE of the message buffer is "1".
- Other message buffers do not send frames at frame transmission start because TxRqst is reset to "0". After the message buffer sent by NewDat or IntPnd is checked, "1" needs to be set to TxRqst and NewDat again for the message buffer to be sent.

[bit4] Reserved

The read value is always "0". When writing to this bit, set "0".

[bit3] EIE : Error interrupt code enable bit

EIE	Function
0	Disables the interrupt code setting to the CAN interrupt register (INTR) with the bit change for Boff or EWarn of the CAN status register (STATR). [Initial value]
1	Enables the status interrupt code setting to the CAN interrupt register (INTR) with the bit change for Boff or EWarn of the CAN status register (STATR).

[bit2] SIE : Status interrupt code enable bit

SIE	Function
0	Disables the interrupt code setting to the CAN interrupt register (INTR) with the bit change for TxOk, RxOk or LEC of the CAN status register (STATR). [Initial value]
1	Enables the status interrupt code setting to the CAN interrupt register (INTR) with the bit change for TxOk, RxOk or LEC of the CAN status register (STATR). The bit change for TxOk, RxOk and LEC generated by the writing from the CPU is not set to the CAN interrupt register (INTR).

[bit1] IE : Interrupt enable bit

IE	Function
0	Disables interrupt. [Initial value]
1	Enables interrupt.

[bit0] Init : Initialization bit

Init	Function
0	Operates after the initialization release of the CAN controller.
1	Initialize the CAN controller and stops the operation. [Initial value]

Notes:

- The bus-off recovery sequence cannot be shortened with the Init bit setting/release. When a device is in the bus-off state, the CAN controller itself sets "1" to the Init bit and stops all bus operations. When the Init bit is cleared to "0" in the bus-off state, the bus operation is stopped until the bus-idle continues 129 times (11-bit recessive is regarded as one time). The error counter is reset after the execution of the bus-off recovery sequence.
- When the Init bit is set to "1" and then to "0" during the bus-off recovery sequence, the bus-off recovery sequence runs from the beginning (129 times regarding 11-bit recessive as one time).
- To set the CAN bit timing register (BTR), set "1" to the Init and CCE bits.
- When "1" is set to the Init bit during transmission/reception, the transmission/reception is stopped immediately.
- Before transiting to the low-power consumption mode, set "1" to the Init bit and initialize the CAN controller.
- To change the clock divide ratio which supplies to the CAN interface by the following registers, set "1" to the Init bit and stop the CAN controller.
 - CAN bit timing register (BTR)
 - CAN prescaler extension register (BRPER)
 - CAN prescaler register (CANPRE)

4.2.2. CAN Status Register (STATR)

The bit configuration of the CAN status register is shown.

Displays the CAN and CAN bus statuses.

■ CAN Status Register (upper byte): Address Base_addr+02_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ CAN Status Register (lower byte): Address Base_addr+03_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BOff	EWarn	EPass	RxOk	TxOk	LEC[2:0]		
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,W	R,W	R,WX	R,WX	R,WX

[bit15 to bit8]: Reserved

The read value is always "0". When writing to these bits, set "0".

[bit7] BOff : Bus-off bit

BOff	Function
0	Indicates the CAN controller is not in the bus-off state. [Initial value]
1	Indicates the CAN controller is in the bus-off state.

[bit6] EWarn : Warning bit

EWarn	Function
0	Indicates both the transmission and reception counters are below 96. [Initial value]
1	Indicates the transmission or reception counter is 96 or more.

[bit5] EPass : Error passive bit

EPass	Function
0	Indicates both the transmission and reception counters are below 128 (error active state). [Initial value]
1	Indicates the reception counter is the RP bit = "1" and the transmission counter is 128 or more (error passive state).

[bit4] RxOk : Successful message reception bit

RxOk	Function
0	Indicates successful message communication is not performed on the CAN bus or the bus is in the idle state. [Initial value]
1	Indicates successful message communication is performed on the CAN bus.

[bit3] TxOk : Successful message transmission bit

TxOk	Function
0	Indicates the bus is in the idle state or successful message transmission is not performed. [Initial value]
1	Indicates successful message transmission is performed.

Note:

The RxOk and TxOk bits are cleared only with "0" writing.

[bit2 to bit0] LEC[2:0] : Last error code bits

LEC[2:0]	State	Function
000	Normal	Indicates transmission or reception is performed successfully. [Initial value]
001	Stuff error	Indicates more than 6 bits of dominant or recessive is detected continuously in a message.
010	Form error	Indicates the fixed format segment of a received frame is detected as incorrect.
011	Ack error	Indicates the transmission message is not acknowledged by other nodes.
100	Bit1 error	Indicates dominant was detected even though recessive was sent with the message transmission data other than arbitration field.
101	Bit0 error	Indicates recessive was detected even though dominant was sent with the message transmission data. This bit is set every time 11 bits of recessive is detected during the bus recovery. Reading this bit allows the monitoring of the bus recovery sequence.
110	CRC error	Indicates that CRC data and CRC result calculated for a received message did not match.
111	Undetected	Indicates no transmission or reception is performed during the period when LEC reads "111 _B " after "111 _B " is set to the LEC bit.(bus idle status)

The LEC bit holds the code that indicates the last error occurred on the CAN bus. This bit is cleared to "0" when a message transfer (reception/transmission) completes without error. The undetected code "111_B" can be used for checking the code update.

Notes:

- The status interrupt code (8000_H) is set to the CAN interrupt register (INTR) if the BOff or EWarn bit is changed when the EIE bit is "1" or if RxOk, TxOk or the LEC bit is changed when the SIE bit is "1".
 - The flag values for the RxOk and TxOk bits are updated with the program writing, and thus the RxOk and TxOk bit values set by the CAN controller are changed. When using RxOk and TxOk bits, these bits needs to be cleared within (45 x BT) time after the RxOk or TxOk bit is set to "1". BT is 1 bit time.
 - Do not write into the CAN status register (STATR) if an interrupt occurs due to the LEC bit change when the SIE bit is "1".
 - In the EPass bit change and writing operation into the RxOk, TxOk and the LEC bits, the error code interrupt is not set to the CAN interrupt register (INTR).
 - When the BOff bit is "1", the EPass and EWarn bits are "1". In addition, the EWarn bit is "1" when the EPass bit is "1".
 - The status interrupt (8000_H) of the CAN interrupt register (INTR) is cleared with the readout of the CAN status register (STATR).
-

4.2.3. CAN Error Counter (ERRCNT)

The bit configuration of the CAN error counter is shown.

Indicates reception error passive display, reception error counter and transmission error counter.

■ **CAN Error Counter Register (upper byte): Address Base_addr+04_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	RP	REC[6:0]						
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Error Counter Register (lower byte): Base_addr+05_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TEC[7:0]							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

[bit15] RP : Reception error passive display

RP	Function
0	The reception error counter indicates that it is not the error passive state. [Initial value]
1	The reception error counter indicates that the error passive state that is defined in the CAN specification has been reached.

[bit14 to bit8] REC[6:0]: Reception error counter

Reception error counter value. The range for the reception error counter values is 0 to 127.

When the reception error counter is greater than or equal to 128, "1" is set to the RP bit and the reception error counter is not updated.

Example:

When REC[6:0]=127 is incremented by 8 for reception error, the result is RP=1 and REC[6:0]=127.

When REC[6:0]=126 is incremented by 8 for reception error, the result is RP=1 and REC[6:0]=126.

When REC[6:0]=119 is incremented by 8 for reception error, the result is RP=0 and REC[6:0]=127.

[bit7 to bit0] TEC[7:0]: Transmission error counter

Transmission error counter value. The range for the transmission error counter values is 0 to 255.

When the transmission error counter is greater than or equal to 256, "1" is set to the Init bit of the CAN control register and the transmission error counter is not updated.

Example:

When TEC[7:0]=255 is incremented by 8 for transmission error, the result is Init=1 and TEC[7:0]=255.

When TEC[7:0]=254 is incremented by 8 for transmission error, the result is Init=1 and TEC[7:0]=254.

When TEC[7:0]=247 is incremented by 8 for transmission error, the result is Init=0 and TEC[7:0]=255.

4.2.4. CAN Bit Timing Register (BTR)

The bit configuration of the CAN bit timing register is shown.

Sets the prescaler and bit timing.

■ **CAN Bit Timing Register (upper byte): Address Base_addr+06_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	TSeg2			TSeg1			
Initial value	0	0	1	0	0	0	1	1
Attribute	R0,W0	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **CAN Bit Timing Register (lower byte): Address Base_addr+07_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	SJW		BRP					
Initial value	0	0	0	0	0	0	0	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15] Reserved

The read value is always "0". When writing to this bit, set "0".

[bit14 to bit12] Tseg2 : Time segment 2 setting bits

Valid setting values are 0 to 7. TSeg2+1 bit value is time segment 2.

Time segment 2 corresponds to the phase buffer segment (PHASE_SEG2) based on the CAN specification.

[bit11 to bit8] Tseg1 : Time segment 1 setting bits

Valid setting values are 1 to 15. 0 cannot be set. TSeg1+1 bit value is time segment 1.

Time segment 1 corresponds to the propagation segment (PROP_SEG) and phase buffer segment 1 (PHASE_SEG1) based on the CAN specification.

[bit7, bit6] SJW : Resynchronization jump width setting bits

Valid setting values are 0 to 3. The SJW+1 bit value is the resynchronization jump width.

[bit5 to bit0] BRP : Baud rate prescaler setting bits

Valid setting values are 0 to 63. The BRP+1 bit value is the baud rate prescaler.

Divides frequency for system clock (fsys) and determines the basic unit time (tq) of the CAN controller.

Note:

When "1" is set to the CCE and Init bits of the CAN control register (CTRLR), set the CAN bit timing register (BTR) and the CAN prescaler extension register (BRPER).

4.2.5. CAN Interrupt Register (INTR)

The bit configuration of the CAN interrupt register is shown.

Checks the message interrupt and status interrupt codes.

■ **CAN Interrupt Register (upper byte): Address Base_addr+08_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	IntId15 to IntId8							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Interrupt Register (lower byte): Address Base_addr+09_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	IntId7 to IntId0							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

IntId	Function
0000 _H	No interrupt
(For 32msg) 0001 _H to 0020 _H (For 64msg) 0001 _H to 0040 _H (For 128msg) 0001 _H to 0080 _H	The message object number is indicated as an interrupt factor. (Message interrupt code)
(For 32msg) 0021 _H to 7FFF _H (For 64msg) 0041 _H to 7FFF _H (For 128msg) 0081 _H to 7FFF _H	Unused
8000 _H	Indicates interrupts with the change of the CAN status register (STATR). (Status interrupt code)
8001 _H to FFFF _H	Unused

If more than one interrupt codes are pending, the CAN interrupt register (INTR) will indicate the interrupt code of the highest priority. If a higher-priority interrupt code is generated when an interrupt code is set to the CAN interrupt register (INTR), the CAN interrupt register (INTR) is updated to the higher-order interrupt code.

Higher orders are given to the status interrupt code (8000_H), message interrupt (0001_H, 0002_H, 0003_H,, 0020_H) in descending order. (For 32msg. Same for 64 or 128msg.)

When the IntId[15:0] bit is other than 0000_H and the IE bit of the CAN control register (CTRLR) is set to "1", the interrupt signal for CPU is active. When the IntId[15:0] bit is 0000_H (an interrupt factor is reset) or the IE bit of the CAN control register (CTRLR) is reset to "0", the interrupt signal is inactive.

If the IntPnd bit of the target message objects (for message objects, see "4.4 Message Object") is cleared to "0", the message interrupt code will be cleared.

Status interrupt code will be cleared when the CAN status register (STATR) is read.

4.2.6. CAN Test Register (TESTR)

The bit configuration of the CAN test register is shown.

Monitors the test mode setting and RX pins. For operation, see "5.7 Test Mode".

■ **CAN Test Register (upper byte): Address Base_addr+0A_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **CAN Test Register (lower byte): Address Base_addr+0B_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Rx	Tx1	Tx0	LBack	Silent	Basic	Reserved	Reserved
Initial value	r	0	0	0	0	0	0	0
Attribute	R,WX	R/W	R/W	R/W	R/W	R/W	R0,W0	R0,W0

The level on the CAN bus is displayed as the initial value (r) of Rx for bit7.

[bit15 to bit8] Reserved

The read value is always "0". When writing to these bits, set "0".

[bit7] Rx : Rx pin monitor bit

Rx	Function
0	Indicates the CAN bus is dominant.
1	Indicates the CAN bus is recessive.

[bit6, bit5] Tx1, Tx0 : TX pin control bits

Tx1, Tx0	Function
00	Normal operation [Initial value]
01	Sampling points will be output to the TX pin.
10	Dominant will be output to the TX pin.
11	Recessive will be output to the TX pin.

[bit4] LBack : Loopback Mode

LBack	Function
0	Disables loopback mode. [Initial value]
1	Enables loopback mode.

[bit3] Silent : Silent Mode

Silent	Function
0	Disables silent mode. [Initial value]
1	Enables silent mode.

[bit2] Basic : Basic mode

Basic	Function
0	Disables basic mode. [Initial value]
1	Enables basic mode. The IF1 register will be used as a transmission message, and the IF2 register will be used as a reception message.

[bit1, bit0] : Reserved

The read value is always "0". When writing to these bits, set "0".

Notes:

- After setting "1" to the Test bit of the CAN control register (CTRLR), write into the register. The test mode is valid when the Test bit of the CAN control register (CTRLR) is set to "1". The CAN controller transits from the test mode to the normal mode when the Test bit of the CAN control register (CTRLR) is set to "0".
- Messages cannot be sent when the Tx bit is set to a value other than "00".

4.2.7. CAN Prescaler Extension Register (BRPER)

The bit configuration of the CAN prescaler extension register is shown.

Extends the prescaler used in the CAN controller by combining the prescaler set at the CAN bit timing.

■ **CAN Prescaler Extension Register (upper byte): Address Base_addr+0C_H**
(Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **CAN Prescaler Extension Register (lower byte): Address Base_addr+0D_H**
(Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	Reserved	Reserved	Reserved	BRPE			
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W	R/W

[bit15 to bit4] Reserved

The read value is always "0". When writing to these bits, set "0".

[bit3 to bit0] BRPE : Baud rate prescaler extension bits

The baud rate prescaler can be extended up to 1023 by combining the BRP and BRPE bits of the CAN bit timing register (BTR).

The {BRPE (MSB:4 bit), BRP (LSB:6 bit)} + 1 value is the prescaler of the CAN controller.

4.3. Message Interface Register

This section explains the message interface register.

Provides two pairs of message interface registers to control access from the CPU to the message RAM.

There are two pairs of message interface registers used to control access from the CPU to the message RAM. These two pairs of registers avoid conflict between accesses from the message RAM to the CPU and from the CAN controller by buffering transferred data (message object). The message object (for message object, see "4.4 Message Object") transfers messages between the message interface register and the message RAM.

The functions for two pairs of message interface registers are the same except the test basic mode, and these registers can operate independently. For example, the message interface register of IF2 can be used for readout from the message RAM while the message interface register of IF1 is being written into the message RAM. Table 4-5 shows two-pairs of message interface registers.

The message interface register consists of the command register (command request, command mask registers) and the message buffer register (mask, arbitration, message control and data registers) controlled by this command register. The command mask register indicates data transfer direction and which part of the message object will be transferred. The command request register selects the message number and performs the operation set to the command mask register.

Table 4-5 IF1, IF2 Message Interface Registers

Address	IF1 register set	Address	IF2 register set
Base_addr+ 10 _H	IF1 command request	Base_addr+ 40 _H	IF2 command request
Base_addr+ 12 _H	IF1 command mask	Base_addr+ 42 _H	IF2 command mask
Base_addr+ 14 _H	IF1 mask 2	Base_addr+ 44 _H	IF2 mask 2
Base_addr+ 16 _H	IF1 mask 1	Base_addr+ 46 _H	IF2 mask 1
Base_addr+ 18 _H	IF1 arbitration 2	Base_addr+ 48 _H	IF2 arbitration 2
Base_addr+ 1A _H	IF1 arbitration 1	Base_addr+ 4A _H	IF2 arbitration 1
Base_addr+ 1C _H	IF1 message control	Base_addr+ 4C _H	IF2 message control
Base_addr+ 20 _H	IF1 data A1	Base_addr+ 50 _H	IF2 data A1
Base_addr+ 22 _H	IF1 data A2	Base_addr+ 52 _H	IF2 data A2
Base_addr+ 24 _H	IF1 data B1	Base_addr+ 54 _H	IF2 data B1
Base_addr+ 26 _H	IF1 data B2	Base_addr+ 56 _H	IF2 data B2

4.3.1. IFx Command Request Register (IFxCREQ)

The bit configuration of the IFx command request register is shown.

Selects the message number of the message RAM and transfers the message between the message RAM and the message buffer register. In addition, IF1 is used for transmission control and IF2 is used for reception control in the basic mode for tests.

■ **IFx Command Request Register (upper byte): Address Base_addr+10_H & Base_addr+40_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	BUSY	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **IFx Command Request Register (lower byte): Address Base_addr+11_H & Base_addr+41_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Message Number							
Initial value	0	0	0	0	0	0	0	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Immediately after the message number is written into the IFx command request register (IFxCREQ), the message transfer between the message RAM and the message buffer register (mask, arbitration, message control and data register) is started. This writing operation indicates that "1" is set to the BUSY bit and a message is being transferred. When the transfer is completed, the BUSY bit is reset to "0".

When "1" is set to the BUSY bit, the CPU will be kept waiting until the BUSY bit becomes "0" if the CPU accesses to the message interface register (3 to 6 clock cycles after writing into the command request register).

The BUSY bit is used differently in the basic mode for tests. The IF1 command request register is used as a transmission message, and setting "1" to the BUSY bit directs message transmission start. When the message transfer is completed successfully, the BUSY bit is reset to "0". In addition, resetting the BUSY bit to "0" aborts message transfer at any time.

The IF2 command request register is used as a reception message, and setting "1" to the BUSY bit stores the received message in the IF2 message interface register.

[bit15] BUSY : Busy flag bit
(1) Other than test basic mode

BUSY	Function
0	Indicates that data is not being transferred between the message interface register and the message RAM. [Initial value]
1	Indicates that data is being transferred between the message interface register and the message RAM.

(2) Test basic mode

IF1 command request register

BUSY	Function
0	Disables the message transmission.
1	Enables the message transmission.

IF2 command request register

BUSY	Function
0	Disables the message reception.
1	Enables the message reception.

[bit14 to bit8] Reserved

The read value is always "0". When writing to these bits, set "0".

[bit7 to bit0] Message Number : Message Number (For 32 message buffer CAN)

Message Number	Function
00 _H	Setting prohibited. If this value is set, it is interpreted as 20 _H and 20 _H is read out.
01 _H to 20 _H	Sets the message number for processing.
21 _H to 3F _H	Setting prohibited. If this value is set, it is interpreted as 01 _H to 1F _H and the value interpreted is read out.

[bit7 to bit0] Message Number : Message Number (For 64 message buffer CAN)

Message Number	Function
00 _H	Setting prohibited. If this value is set, it is interpreted as 40 _H and 40 _H is read out.
01 _H to 40 _H	Sets the message number for processing.
41 _H to FF _H	Setting prohibited. If this value is set, it is interpreted as 01 _H to 3F _H and the value interpreted is read out.

[bit7 to bit0] Message Number : Message Number (For 128 message buffer CAN)

Message Number	Function
00 _H	Setting prohibited. If this value is set, it is interpreted as 80 _H and 80 _H is read out.
01 _H to 80 _H	Sets the message number for processing.
81 _H to FF _H	Setting prohibited. If this value is set, it is interpreted as 01 _H to 7F _H and the value interpreted is read out.

Note:

The BUSY bit is readable/writable. Other than in the test basic mode, it does not affect the operation no matter which value is written to this bit. (See "5.7 Test Mode" for the details of the basic mode.)

4.3.2. IFx Command Mask Register (IFxCMSK)

The bit configuration of the IFx command mask register is shown.

This register sets which data to be updated by controlling the direction of transfer between the message interface register and message RAM. The register becomes invalid in the test basic mode.

■ **IFx Command Mask Register (upper byte): Address Base_addr+12_H & Base_addr+42_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0	R0,W0

■ **IFx Command Mask Register (lower byte): Address Base_addr+13_H & Base_addr+43_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	WR/RD	Mask	Arb	Control	CIP	TxRqst/ NewDat	Data A	Data B
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit8] Reserved

The read value is always "0". When writing to these bits, set "0".

[bit7] WR/RD : Write/read control bit

WR/RD	Function
0	Indicates reading data from message RAM. Reading data from message RAM will be executed by writing data to the IFx command request register (IFxCREQ). Data read from message RAM depends on the settings of Mask, Arb, Control, CIP, TxRqst/NewDat, Data A, and Data B bits. [Initial value]
1	Indicates writing data to message RAM. Writing data to message RAM will be executed by writing data to the IFx command request register (IFxCREQ). Data written to message RAM depends on the settings of Mask, Arb, Control, CIP, TxRqst/NewDat, Data A, and Data B bits.

Note:

Data in message RAM is undefined after reset. Reading data from message RAM is disabled while data in message RAM is undefined.

Bit6 to bit0 of the IFx command mask register (IFxCMSK) has different meanings depending on the settings of transfer direction (WR/RD bit).

(1) When the transfer direction is write (WR/RD="1")

[bit6] Mask : Mask data update bit

Mask	Function
0	Indicates not updating the mask data (ID mask + MDir + MXtd) of message object*1. [Initial value]
1	Indicates updating the mask data (ID mask + MDir + MXtd) of message object*1.

[bit5] Arb : Arbitration data update bit

Arb	Function
0	Indicates not updating the arbitration data (ID + Dir + Xtd + MsgVal) of message object*1. [Initial value]
1	Indicates updating the arbitration data (ID + Dir + Xtd + MsgVal) of message object*1.

[bit4] Control : Control data update bit

Control	Function
0	Indicates not updating the control data (IFx message control register (IFxMCTR)) of message object*1. [Initial value]
1	Indicates updating the control data (IFx message control register (IFxMCTR)) of message object*1.

[bit3] CIP : Interrupt clear bit

Operation of CAN controller will not be affected whether "0" or "1" is set.

[bit2] TxRqst/NewDat : Message transmission request bit

TxRqst/ NewDat	Function
0	Indicates not changing the TxRqst bit of message object*1 and CAN transmission request register (TREQR). [Initial value]
1	Indicates that "1" is set to the TxRqst bit of message object*1 and CAN transmission request register (TREQR) (transmission request) .

[bit1] Data A : Data 0 to 3 update bit

Data A	Function
0	Indicates not updating Data 0 to 3 of message object*1. [Initial value]
1	Indicates updating Data 0 to 3 of message object*1.

[bit0] Data B : Data 4 to 7 update bit

Data B	Function
0	Indicates not updating Data 4 to 7 of message object*1. [Initial value]
1	Indicates updating Data 4 to 7 of message object*1.

*1: See "4.4 Message Object".

Notes:

- When the TxRqst/NewDat bit of the IFx command mask register (IFxCMSK) is set to "1", the TxRqst bit settings of the IFx message control register (IFxMCTR) becomes invalid.
- The register becomes invalid in the test basic mode.

(2) When the transfer direction is read (WR/RD="0")

[bit6] Mask : Mask data update bit

Mask	Function
0	Indicates not transferring data (ID mask +MDir + MXtd) from message object*1 to IFx mask registers 1, 2 (IFxMSK1, IFxMSK2). [Initial value]
1	Indicates transferring data (ID mask +MDir + MXtd) from message object*1 to IFx mask registers 1, 2 (IFxMSK1, IFxMSK2) .

[bit5] Arb : Arbitration data update bit

Arb	Function
0	Indicates not transferring data (ID + Dir + Xtd + MsgVal) from message object*1 to IFx arbitration 1, 2 (IFxARB1, IFxARB2). [Initial value]
1	Indicates transferring data (ID + Dir + Xtd + MsgVal) from message object*1 to IFx arbitration 1, 2 (IFxARB1, IFxARB2) .

[bit4] Control : Control data update bit

Control	Function
0	Indicates not transferring data from message object*1 to IFx message control register (IFxMCTR). [Initial value]
1	Indicates transferring data from message object*1 to IFx message control register (IFxMCTR).

[bit3] CIP : Interrupt clear bit

CIP	Function
0	Indicates holding the IntPnd bit of message object*1 and CAN interrupt pending register (INTPND). [Initial value]
1	Indicates clearing the IntPnd bit of message object*1 and CAN interrupt pending register (INTPND) to "0".

[bit2] TxRqst/NewDat : Data update bit

TxRqst/ NewDat	Function
0	Indicates holding the NewDat bit of message object*1 and CAN data update register. [Initial value]
1	Indicates clearing the NewDat bit of message object*1 and CAN data update register to "0".

[bit1] Data A : Data 0 to 3 update bit

Data A	Function
0	Indicates holding data of message object*1 and CAN data registers A1, A2. [Initial value]
1	Indicates updating data of message object*1 and CAN data registers A1, A2.

[bit0] Data B : Data 4 to 7 update bit

Data B	Function
0	Indicates holding data of message object*1 and CAN data registers B1, B2. [Initial value]
1	Indicates updating data of message object*1 and CAN data registers B1, B2.

*1: See "4.4 Message Object".

Notes:

- It is possible to reset the IntPnd and NewDat bits to "0" by reading access to message object. However, for the IntPnd and NewDat bits of the IFx message control register (IFxMCTR), the IntPnd and NewDat bits prior to being reset by reading access will be stored.
- It becomes invalid in the test basic mode.

4.3.3. IFx Mask Registers 1, 2 (IFxMSK1, IFxMSK2)

The bit configuration of the IFx mask registers 1,2 is shown.

They are used to write/read message object mask data of message RAM. In the test basic mode, the configured mask data becomes invalid.

See "4.4 Message Object" for the functions of each bit.

■ **IFx Mask Register 2 (upper byte): Address Base_addr+14_H & Base_addr+44_H
(Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	MXtd	MDir	Reserved	Msk28 to Msk24				
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R1,W1	R/W	R/W	R/W	R/W	R/W

■ **IFx Mask Register 2 (lower byte): Address Base_addr+15_H & Base_addr+45_H
(Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Msk23 to Msk16							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **IFx Mask Register 1 (upper byte): Address Base_addr+16_H & Base_addr+46_H
(Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Msk15 to Msk8							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **IFx Mask Register 1 (lower byte): Address Base_addr+17_H & Base_addr+47_H
(Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Msk7 to Msk0							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

For the reserved bit (bit13 of IFx mask register 2), "1" is read out. When writing to this bit, set "1".

4.3.4. IFx Arbitration Registers 1, 2 (IFxARB1, IFxARB2)

The bit configuration of the IFx arbitration registers 1, 2 is shown.

They are used to write/read message object arbitration data of message RAM. They become invalid in the test basic mode.

See "4.4 Message Object" for the functions of each bit.

■ **IFx Arbitration Register 2 (upper byte): Address Base_addr+18_H & Base_addr+48_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	MsgVal	Xtd	Dir	ID28 to ID24				
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **IFx Arbitration Register 2 (lower byte): Address Base_addr+19_H & Base_addr+49_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ID23 to ID16							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **IFx Arbitration Register 1 (upper byte): Address Base_addr+1A_H & Base_addr+4A_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	ID15 to ID8							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **IFx Arbitration Register 1 (lower byte): Address Base_addr+1B_H & Base_addr+4B_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ID7 to ID0							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Note:

If the MsgVal bit of the message object is cleared to "0" while the transmission is in progress, the TxOk bit of the CAN status register (STATR) will be set to "1" when the transmission has completed. However, the TxRqst bits of the message object and CAN transmission request register (TREQR) will not be cleared to "0". So, make sure to clear the TxRqst bits to "0" using the message interface register.

4.3.5. IFx Message Control Register (IFxMCTR)

The bit configuration of the IFx message control register is shown.

They are used to write/read message object control data in message RAM. The IF1 message control register will be disabled in the test basic mode. NewDat and MsgLst of the IF2 message control register will operate normally and the DLC[3:0] bits will display the DLC of message received. Other control bits will operate as disabled ("0").

See "4.4 Message Object" for the functions of each bit.

■ **IFx Message Control Register (upper byte): Address Base_addr+1CH & Base_addr+4CH (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	NewDat	MsgLst	IntPnd	UMask	TxE	RxE	RmtEn	TxRqst
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ **IFx Message Control Register (lower byte): Address Base_addr+1DH & Base_addr+4DH (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	EoB	Reserved	Reserved	Reserved	DLC3-0			
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W	R/W

Notes:

TxRqst, NewDat, and IntPnd bits operate differently depending on the settings of the WR/RD bit in the IFx command mask register (IFxCMSK).

- If the transfer direction is "write" (IFx command mask register (IFxCMSK): WR/RD=1).
 - The TxRqst bit of this register will only be enabled when TxRqst/NewDat in the IFx command mask register (IFxCMSK) is set to "0".
- If the transfer direction is "read" (IFx command mask register (IFxCMSK): WR/RD=0).
 - The IntPnd bit before it has been reset will be stored to this register when the message object and the IntPnd bit of the CAN interrupt pending register (INTPND) are reset by a write operation to the IFx command request register (IFxCREQ) after setting the CIP bit of the IFx command mask register (IFxCMSK) to "1".
 - The NewDat bit before it has been reset will be stored to this register when the message object and the NewDat bit of the CAN data update register are reset by a write operation to the IFx command request register (IFxCREQ) after setting the TxRqst/NewDat bit of the IFx command mask register (IFxCMSK) to "1".

4.3.6. IFx Data Registers A1, A2, B1, B2 (IFxDTA1, IFxDTA2, IFxDTB1, IFxDTB2)

The bit configuration of the IFx data registers A1, A2, B1, B2 are shown.

They are used to write/read message object transmission/reception data in message RAM. Only used for transmitting/receiving data frames, and not for transmitting/receiving remote frames.

	addr+0	addr+1	addr+2	addr+3
IFx Message Data A1 (addresses 20 _H & 50 _H)	Data(0)	Data(1)		
IFx Message Data A2 (addresses 22 _H & 52 _H)			Data(2)	Data(3)
IFx Message Data B1 (addresses 24 _H & 54 _H)	Data(4)	Data(5)		
IFx Message Data B2 (addresses 26 _H & 56 _H)			Data(6)	Data(7)
IFx Message Data A2 (addresses 30 _H & 60 _H)	Data(3)	Data(2)		
IFx Message Data A1 (addresses 32 _H & 62 _H)			Data(1)	Data(0)
IFx Message Data B2 (addresses 34 _H & 64 _H)	Data(7)	Data(6)		
IFx Message Data B1 (addresses 36 _H & 66 _H)			Data(5)	Data(4)

■ IFx Data Register:

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Data							
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Transmission message data setting

Data set starts from MSB (bit7, bit15) and will be transmitted in the order of Data(0), Data(1), ..., Data(7).

Reception message data

Reception message data starts from MSB (bit7, bit15) and will be stored in the order of Data(0), Data(1), ..., Data(7).

Notes:

- If the reception message data is less than 8 bytes, undefined data will be written to the remaining bytes of the data register.
- Data transfer to the message object will be in units of 4 bytes of Data A or Data B. It is therefore not possible to update only a part of the 4-byte data.

4.4. Message Object

The message object is explained.

The message RAM has 32 (up to 64 or 128 depending on the channel) message objects. In order to prevent conflict between accesses to message RAM from CPU and CAN controller, the CPU cannot access the message object directly. These accesses are performed via the IFx message interface register.

This section explains the configuration and function of the message objects.

4.4.1. Configuration of Message Object

The configuration of the message object is shown.

The configuration of the message object is shown below:

Table 4-6 Configuration of Message Object

UMask	Msk28-0	MXtd	MDir	EoB	NewDat		MsgLst	RxIE	TxIE	IntPnd	RmtEn	TxRqst
MsgVal	ID28-0	Xtd	Dir	DLC3-0	Data0	Data1	Data2	Data3	Data4	Data5	Data6	Data7

Note:

The message object will not be initialized by the Init bit of the CAN control register (CTRLR) or hardware reset. In the case of hardware reset, after its release, initialize message RAM by the CPU or set the MsgVal bit of message RAM to "0".

4.4.2. Functions of Message Object

The functions of the message object are shown.

When transmitting a message, ID28 to ID0, Xtd and Dir bits will be used as the ID and type of the message. When receiving a message, Msk28 to Msk0, MXtd and MDir bits will be used in the acceptance filter. ID, IDE, RTR, DLC and DATA for data frame or remote frame passing through the acceptance filter will be stored in the ID28 to ID0, Xtd, Dir, DLC3 to DLC0, Data7 to Data0 of the message objects. Xtd indicates whether the message object is an extension frame or standard frame, a 29-bit ID (extension frame) will be received if Xtd is "1", and an 11-bit ID (standard frame) will be received if Xtd is "0".

If the received data frame or remote frame matches one or more message objects, it will be stored to the lowest matched message number. (See reception message acceptance filter in "5.3 Message Reception Operation" for details.)

MsgVal: Valid message bit

MsgVal	Function
0	Message object is invalid. Message transmission/reception will not be performed.
1	Message object is valid. Message transmission/reception will become possible.

Notes:

- Be sure to initialize the MsgVal bit of the message object before resetting the Init bit of the CAN control register (CTRLR) to "0" and changing the value of ID28 to ID0, Xtd, Dir, and DLC3 to DLC0.
- If the MsgVal bit is cleared to "0" while the transmission is in progress, the TxOk bit of the CAN status register (STATR) will become "1" as soon as the transmission ends. However, the message object and the TxRqst bit of the CAN transmission request register (TREQR) will not be cleared to "0". So be sure to clear the TxRqst bit to "0" by the message interface register.

UMask: Acceptance mask enable bit

UMask	Function
0	Does not use Msk28 to 0, MXtd, and MDir.
1	Uses Msk28 to 0, MXtd, and MDir.

Notes:

- Change the UMask bit while the Init bit of the CAN control register (CTRLR) is "1" or while the MsgVal bit is "0".
- When the Dir bit is "1" and the RmtEn bit is "0", it will operate differently depending on the UMask bit setting.
- If the UMask bit is "1", the TxRqst bit will be reset to "0" when the remote frame is received through the acceptance filter. At this time, the received ID, IDE, RTR and DLC will be stored to the message object, the NewDat bit will be set to "1", and the data will remain unchanged (treated as a data frame).
- If the UMask bit is "0", the TxRqst bit will remain unchanged by the remote frame reception; and it will ignore the remote frame.

ID28 to ID0: Message ID

ID	Function
ID28 to ID0	Instructs a 29-bit ID (extended frame).
ID28 to ID18	Instructs an 11-bit ID (standard frame).

Msk28 to Msk0: ID Mask

Msk	Function
0	Masks the bit corresponding to the message object ID.
1	Does not mask the bit corresponding to the message object ID.

Xtd: Extended ID enable bit

Xtd	Function
0	An 11-bit ID (standard frame) is used for the message object.
1	A 29-bit ID (extended frame) is used for the message object.

MXtd: Extended ID mask bit

MXtd	Function
0	Does not compare the values between those set to the Xtd bit of the message object and those for the IDE bit in the received frame. The IDE bit in the received frame determines whether to compare it as a standard frame ID or an extended frame ID.
1	Compares the values between those set to the Xtd bit of the message object and those for the IDE bit in the received frame.

Note:

If an 11-bit ID (standard frame) is set to the message object, ID of the received data frame will be written to ID28 to ID18. Msk28 to Msk18 are used for ID masks.

Dir: Message direction bit

Dir	Function
0	Indicates the reception direction. The remote frame will be transmitted when the TxRqst bit is set to "1", and the data frame that has passed through the acceptance filter will be received when it is set to "0".
1	Indicates the transmission direction. Data frame will be transmitted when the TxRqst bit is set to "1". If the TxRqst bit is "0" and the RmtEn is set to "1", the CAN controller itself sets its the TxRqst bit to "1" by receiving the remote frame that has passed through the acceptance filter.

MDir: Message direction mask bit

MDir	Function
0	Masks the message direction bit (Dir) in the acceptance filter.
1	Does not mask the message direction bit (Dir) in the acceptance filter.

Note:

Always set the MDir bit to "1".

EoB: End of Buffer bit (see "5.4 FIFO Buffer Function" for details)

EoB	Function
0	Indicates taht the massage object is used as FIFO buffer and is not the final message.
1	Indicates a singlemessage object or the final message object of FIFO buffer.

Notes:

- The EoB bit is used to configure the FIFO buffer of 2 to 32 messages.
- Always set the EoB bit to "1" in the case of a single message object (when FIFO is not used).

NewDat: Data update bit

NewDat	Function
0	Valid data does not exist.
1	Valid data exists.

MsgLst: Message lost

MsgLst	Function
0	No message lost occurs.
1	Message lost occurs.

Note:

The MsgLst bit is only enabled when the Dir bit is "0" (reception direction).

RxIE: Reception interrupt flag enable bit

RxIE	Function
0	The IntPnd bit remains unchanged after successful frame reception.
1	The IntPnd bit is set to "1" after successful frame reception.

TxE: Transmission interrupt flag enable bit

TxE	Function
0	The IntPnd bit remains unchanged after successful frame transmission.
1	The IntPnd bit is set to "1" after successful frame transmission.

IntPnd: Interrupt pending bit

IntPnd	Function
0	No interrupt factor exists.
1	Interrupt factor exists. If no other high priority interrupt exists, the IntId bit of the CAN interrupt register (INTR) will indicate this message object.

RmtEn: Remote enable

RmtEn	Function
0	The TxRqst bit remains unchanged by remote frame reception.
1	The TxRqst bit will be set to "1" if a remote frame is received while the Dir bit is "1".

Notes:

- When the Dir bit is "1" and the RmtEn bit is "0", it will operate differently depending on the UMask bit setting.
- If the UMask is "1", the TxRqst bit will be reset to "0" when the remote frame is received through the acceptance filter. At this time, the received ID, IDE, RTR and DLC will be stored in the message object, the NewDat bit will be set to "1", and the data will remain unchanged (treated as a data frame).
- If the UMask is "0", the TxRqst bit will remain unchanged by the remote frame reception; and it will ignore the remote frame.

TxRqst: Transmission request bits

TxRqst	Function
0	Indicates the transmission idle state (neither transmission is in progress nor in the transmission wait state).
1	Indicates that transmission is in progress or in the transmission wait state.

DLC3 to DLC0: Data length code

DLC3 to 0	Function
0 to 8	Data frame length is 0 to 8 bytes.
9 to 15	Setting prohibited. If set, it will be 8 bytes in length.

Note:

The received DLC will be stored in the DLC bit when the data frame is received.

Data 0 to 7: Data 0 to 7

	Function
Data 0	First data byte of the CAN data frame
Data 1	Second data byte of the CAN data frame
Data 2	Third data byte of the CAN data frame
Data 3	Fourth data byte of the CAN data frame
Data 4	Fifth data byte of the CAN data frame
Data 5	Sixth data byte of the CAN data frame
Data 6	Seventh data byte of the CAN data frame
Data 7	Eighth data byte of the CAN data frame

Notes:

- Serial output to the CAN bus is output from MSB (bit7 or bit15).
 - If the received message data is less than 8 bytes, the remaining byte data of the data register will be undefined.
 - Data transfer to the message object will be in units of 4 bytes of Data A or Data B. It is therefore not possible to update only a part of the 4-byte data.
-

4.5. Message Handler Registers

Message handler registers are shown.

All message handler registers are for reading only. The TxRqst, NewDat, IntPnd, MsgVal, and IntId bits of the message object are used to display a status.

- CAN transmission request registers 1, 2 (TREQR1, TREQR2)
- CAN data update registers 1, 2 (NEWDT1, NEWDT2)
- CAN interrupt pending registers 1, 2 (INTPND1, INTPND2)
- CAN message valid registers 1, 2 (MSGVAL1, MSGVAL2)

4.5.1. CAN Transmission Request Registers (TREQR1, TREQR2)

The bit configuration of the CAN transmission request registers is shown.

Displays the TxRqst bit of all message objects. It is possible to check which message objects transmission request is pending by reading the TxRqst bits.

■ **CAN Transmission Request Register 2 (upper byte): Address Base_addr+ 80_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TxRqst32 to TxRqst25							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Transmission Request Register 2 (lower byte): Address Base_addr+ 81_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TxRqst24 to TxRqst17							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Transmission Request Register 1 (upper byte): Address Base_addr+ 82_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	TxRqst16 to TxRqst9							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Transmission Request Register 1 (lower byte): Address Base_addr+ 83_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	TxRqst8 to TxRqst1							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

TxRqst32 to TxRqst1: Transmission request bits

TxRqst32 to 1	Function
0	Indicates the transmission idle state (neither transmission is in progress nor in the transmission wait state).
1	Indicates that transmission is in progress or in the transmission wait state.

Set/reset conditions of the TxRqst bits are shown below.

Set condition

It is possible to set the TxRqst of a specific object by setting "1" to the WR/RD of the IFx command mask register (IFxCMSK) and "1" to the TxRqst while writing data to the IFx command request register (IFxCREQ).

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "1", the TxRqst is set to "0", the Control is set to "1", and the TxRqst of the IFx message control register (IFxMCTR) is set to "1", it is possible to set the TxRqst of a specific object by writing data to the IFx command request register (IFxCREQ).

The bit will be set by a reception of remote frame that has passed the acceptance filter when the Dir bit and RmtEn bit are set to "1" respectively.

Reset condition

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "1", the TxRqst is set to "0", the Control is set to "1", and the TxRqst of the IFx message control register (IFxMCTR) is set to "0", it is possible to reset the TxRqst of a specific object by writing data to the IFx command request register (IFxCREQ).

When frame transmission is completed successfully, the bit will be reset.

The bit will be reset by a reception of remote frame that has passed the acceptance filter when the Dir bit is set to "1", the RmtEn bit is set to "0", and the UMask is set to "1".

See the following table to confirm the transmission request bit for CAN macro equipped with 32 message buffers of higher.

Table 4-7 Transmission Request Bit for CAN Macro Equipped with 32 Message Buffers or Higher

		addr + 0	addr + 1	addr + 2	addr + 3
TREQR 4 & 3	TxRqst 64 to 33 (address 84 _H)	TxRqst64 to 57	TxRqst56 to 49	TxRqst48 to 41	TxRqst40 to 33
TREQR 6 & 5	TxRqst 96 to 65 (address 88 _H)	TxRqst96 to 89	TxRqst88 to 81	TxRqst80 to 73	TxRqst72 to 65
TREQR 8 & 7	TxRqst 128 to 97 (address 8C _H)	TxRqst128 to 121	TxRqst120 to 113	TxRqst112 to 105	TxRqst104 to 97

Notes:

- When the message buffer with the lowest priority is used for transmission and the TXRqst is set to "1" and then to "0" to cancel transmission, setting the TXRqst to "1" again may not, depending on the timing, result in transmission of a message until one of the following events occurs:
 - A valid message is transmitted on the CAN bus.
 - A transmission request is issued to other message buffer.
 - CAN is initialized by the Init bit.

If there is a situation in which transmission is canceled due to system reasons, either do not use the message buffer with the lowest priority as the transmission message buffer or, after transmission cancellation, generate one of the above events and then set the TxRqst to "1" again.

- When the TxRqst bit is "1", do not change the message objects of ID28 to ID0, DLC3 to DLC0, Xtd, and Data7 to Data0. Otherwise, message objects before and after the change may be transmitted in a mixed way or message objects after the change may not be transmitted. Change them when the TxRqst bit is "0".

4.5.2. CAN Data Update Registers (NEWDT1, NEWDT2)

The bit configuration of the CAN data update registers is shown.

Displays the NewDat bit of all message objects. It is possible to check which message objects data has been updated by reading the NewDat bit.

■ **CAN Data Update Register 2 (upper byte): Address Base_addr+ 90_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	NewDat32 to NewDat25							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Data Update Register 2 (lower byte): Address Base_addr+ 91_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	NewDat24 to NewDat17							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Data Update Register 1 (upper byte): Address Base_addr+ 92_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	NewDat16 to NewDat9							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Data Update Register 1 (lower byte): Address Base_addr+93_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	NewDat8 to NewDat1							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

NewDat32 to NewDat1: Data update bits

NewDat 32 to 1	Function
0	Indicates no valid data exists
1	Indicates valid data exists

Set/reset conditions of the NewDat bits are shown below.

Set condition

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "1", the Control is set to "1", and the NewDat of the IFx message control register (IFxMCTR) is set to "1", it is possible to set a specific object by writing data to the IFx command request register (IFxCREQ).

The bit will be set by a reception of data frame that has passed the acceptance filter.

When the Dir is set to "1", the RmtEN is set to "0", and the UMask is set to "1", the bit will be set by a reception of remote frame that has passed the acceptance filter.

Reset condition

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "0" and the NewDat is set to "1", it is possible to reset the NewDat of a specific object by writing data to the IFx command request register (IFxCREQ).

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "1", the Control is set to "1", and the NewDat of the IFx message control register (IFxMCTR) is set to "0", it is possible to reset the NewDat of a specific object by writing data to the IFx command request register (IFxCREQ).

It will be reset after data has been transferred to the transmission shift register (internal register).

See the following table to confirm the data update bit for CAN macro equipped with 32 message buffers or higher.

Table 4-8 Data Update Bit for CAN Macro Equipped with 32 Message Buffers or Higher

		addr + 0	addr + 1	addr + 2	addr + 3
NEWDT 4 & 3	NewDat 64 to 33 (address 94 _H)	NewDat64 to 57	NewDat56 to 49	NewDat48 to 41	NewDat40 to 33
NEWDT 6 & 5	NewDat 96 to 65 (address 98 _H)	NewDat96 to 89	NewDat88 to 81	NewDat80 to 73	NewDat72 to 65
NEWDT 8 & 7	NewDat 128 to 97 (address 9C _H)	NewDat128 to 121	NewDat120-113	NewDat112 to 105	NewDat104 to 97

4.5.3. CAN Interrupt Pending Registers (INTPND1, INTPND2)

The bit configuration of the CAN interrupt pending registers is shown.

Displays the IntPnd bit of all message objects. It is possible to check which message objects interrupt is pending by reading the IntPnd bit.

■ **CAN Interrupt Pending Register 2 (upper byte): Address Base_addr+ A0_H
(Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	IntPnd32 to IndPnd25							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Interrupt Pending Register 2 (lower byte): Address Base_addr+ A1_H
(Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	IntPnd24 to IndPnd17							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Interrupt Pending Register 1 (upper byte): Address Base_addr+ A2_H
(Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	IntPnd16 to IntPnd9							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Interrupt Pending Register 1 (lower byte): Address Base_addr+ A3_H
(Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	IntPnd8 to IntPnd1							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

IntPnd32 to IntPnd1: Interrupt pending bits

IntPnd32 to 1	Function
0	No interrupt factor exists.
1	Interrupt factor exists.

Set/reset conditions of the IntPnd bits are shown below.

Set condition

If the TxIE is set to "1", the IntPnd bit will be set after the frame transmission has ended successfully.

If the RxIE is set to "1", the bit will be set after the frame reception that has passed the acceptance filter completed successfully.

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "1", the Control is set to "1", and the IntPnd of the IFx message control register is set to "1", it is possible to set the IntPnd of a specific object by writing data to the IFx command request register (IFxCREQ).

Reset condition

When the WR/RD of the IFx command mask register (IFxCMSK) is set to "0" and the CIP is set to "1", it is possible to reset the IntPnd of a specific object by writing data to the IFx command request register (IFxCREQ). When the WR/RD of the IFx command mask register is set to "1", the Control is set to "1", and the IntPnd of the IFx message control register (IFxMCTR) is set to "0", it is possible to reset the IntPnd of a specific object by writing data to the IFx command request register.

See the following table to confirm the interrupt pending bit for CAN macro equipped with 32 message buffers or higher.

Table 4-9 Interrupt Pending Bit for CAN Macro Equipped with 32 Message Buffers or Higher

		addr + 0	addr + 1	addr + 2	addr + 3
INTPND 4 & 3	IntPnd 64 to 33 (address A4 _H)	IntPnd64 to 57	IntPnd56 to 49	IntPnd48 to 41	IntPnd40 to 33
INTPND 6 & 5	IntPnd 96 to 65 (address A8 _H)	IntPnd96 to 89	IntPnd88 to 81	IntPnd80 to 73	IntPnd72 to 65
INTPND 8 & 7	IntPnd 128 to 97 (address AC _H)	IntPnd128 to 121	IntPnd120 to 113	IntPnd112 to 105	IntPnd104 to 97

4.5.4. CAN Message Valid Registers (MSGVAL1, MSGVAL2)

The bit configuration of the CAN message valid registers is shown.

Displays the MsgVal bit of all message objects. It is possible to check which message object is valid by reading the MsgVal bit.

■ **CAN Message Valid Register 2 (upper byte): Address Base_addr+ B0_H
(Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	MsgVal32 to MsgVal25							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Message Valid Register 2 (lower byte): Address Base_addr+ B1_H
(Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MsgVal24 to MsgVal17							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Message Valid Register 1 (upper byte): Address Base_addr+ B2_H
(Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	MsgVal16 to MsgVal9							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

■ **CAN Message Valid Register 1 (lower byte): Address Base_addr+ B3_H
(Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MsgVal8 to MsgVal1							
Initial value	0	0	0	0	0	0	0	0
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

MsgVal32 to MsgVal1: Message valid bits

MsgVal32 to 1	Function
0	Message object is invalid. Message will not be transmitted/received.
1	Message object is valid. Message transmission/reception is possible.

Set/reset conditions of the MsgVal bits are shown below.

Set condition

When the WR/RD of the IFx command mask register is set to "1", the Arb is set to "1", and the MsgVal bit of the IFx arbitration register 2 is set to "1", it is possible to set the MsgVal bit of a specific object by writing data to the IFx command request register (IFxCREQ).

Reset condition

When the WR/RD of the IFx command mask register is set to "1", the Arb is set to "1", and the MsgVal bit of the IFx arbitration register 2 is set to "0", it is possible to clear the MsgVal bit of a specific object by writing data to the IFx command request register (IFxCREQ).

See the following table to confirm the message valid bit for CAN macro equipped with 32 message buffers or higher.

Table 4-10 Message Valid Bit for CAN Macro Equipped with 32 Message Buffers or Higher

		addr + 0	addr + 1	addr + 2	addr + 3
MSGVAL 4 & 3	MsgVal 64 to 33 (address B4 _H)	MsgVal64 to 57	MsgVal56 to 49	MsgVal48 to 41	MsgVal40 to 33
MSGVAL 6 & 5	MsgVal 96 to 65 (address B8 _H)	MsgVal96 to 89	MsgVal88 to 81	MsgVal80 to 73	MsgVal72 to 65
MSGVAL 8 & 7	MsgVal 128 to 97 (address BC _H)	MsgVal128 to 121	MsgVal120 to 113	MsgVal112 to 105	MsgVal104 to 97

4.6. CAN Prescaler Register (CANPRE)

The bit configuration of the CAN prescaler register is shown.

This register sets the CAN system clock (fsys) generation prescaler. For details, see "5.6 Bit Timing and CAN System Clock (fsys) Generation". To change the value of this register, set the initialization bit (Init) in the CAN control register (CTRLR) to "1" to stop all the bus operations.

■ CAN Prescaler Register: Address 04A4_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved	Reserved			CANPRE3	CANPRE2	CANPRE1	CANPRE0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W0	R0,W0	R0,W0	R0,W0	R/W	R/W	R/W	R/W

[bit7] Reserved

Always write "0" to this bit.

[bit6 to bit4] Reserved

The read value is always "0". When writing to these bits, set "0".

[bit3 to bit0] CANPRE[3:0] :CAN prescaler setting bits

CANPRE[3:0]	Function	Input CAN prescaler clock: 128MHz	Input CAN prescaler clock: 80MHz	Input CAN prescaler clock: 64MHz	Input CAN prescaler clock: 48MHz
0000	Selects 1/1 period of the system clock as the CAN clock.(Initial value: CANPRE[3:0]=0000)	128MHz	80MHz	64MHz	48MHz
0001	Selects 1/2 period of the system clock as the CAN clock.	64MHz	40MHz	32MHz	24MHz
001x	Selects 1/4 period of the system clock as the CAN clock.	32MHz	20MHz	16MHz	12MHz
01xx	Selects 1/8 period of the system clock as the CAN clock.	16MHz	10MHz	8MHz	6MHz
1000	Selects 2/3 period of the system clock as the CAN clock. The duty of the clock is 67%.	85.3MHz	53.3MHz	42.7MHz	32MHz
1001	Selects 1/3 period of the system clock as the CAN clock.	42.7MHz	26.7MHz	21.4MHz	16MHz

CANPRE[3:0]	Function	Input CAN prescaler clock: 128MHz	Input CAN prescaler clock: 80MHz	Input CAN prescaler clock: 64MHz	Input CAN prescaler clock: 48MHz
1010	Selects 1/6 period of the system clock as the CAN clock.	21.3MHz	13.3MHz	10.7MHz	8MHz
1011	Selects 1/12 period of the system clock as the CAN clock.	10.7MHz	6.7MHz	5.4MHz	4MHz
110x	Selects 1/5 period of the system clock as the CAN clock.	25.6MHz	16.0MHz	12.8MHz	9.6MHz
111x	Selects 1/10 period of the system clock as the CAN clock.	12.8MHz	8.0MHz	6.4MHz	4.8MHz

Notes:

- Change the CAN prescaler setting bits after setting the initialization bit of the CAN control register (CTRLR) to "1" and stopping all the bus operations.
- The clock to be supplied to the CAN interface using the register setting must be 16MHz or less.
- When the OCD tool is connected and the high-speed UART mode or phase modulation UART mode is selected, this register is not initialized by an RST-level reset. It is initialized by an Init-level reset.

5. Operation

This section explains the operation of the CAN.

The CAN has the following functions:

- Message object
- Message transmission operation
- Message reception operation
- FIFO buffer function
- Interrupt function
- Bit timing
- Test mode
- Software initialization

5.1. Message Object

The message object is shown.

This section explains the message object and interface of message RAM.

5.1.1. Message Object

Message object is shown.

Message object settings (excluding MsgVal, NewDat, IntPnd and TxRqst bits) of message RAM will not be initialized by a hardware reset. Therefore, initialize message object by the CPU or disable the MsgVal bit (MsgVal="0"). Set CAN bit timing register (BTR) and CAN prescaler extension register (BRPER) while the Init bit of the CAN control register (CTRLR) is set to "1" and the CCE bit is set to "1".

Message object can be set by setting the data to the message interface register (IFx mask register, the IFx arbitration register, the IFx message control register (IFxMCTR) and IFx data register (IFxDTx)) and then writing the message number to the IFx command request register (IFxCREQ), as a result of which the data of the interface register will be transferred to the specified message object.

CAN controller starts operating when Init bit of the CAN control register (CTRLR) is cleared to "0". Reception message that has passed through the acceptance filter will be stored to message RAM. Messages with pending transmission request are transferred from message RAM to the shift register of the CAN controller and then transmitted to the CAN bus.

CPU reads the reception message via the message interface register and updates the transmission message. An interrupt is sent to the CPU according to the settings of the CAN control register (CTRLR) and IFx message control register (IFxMCTR) (message object).

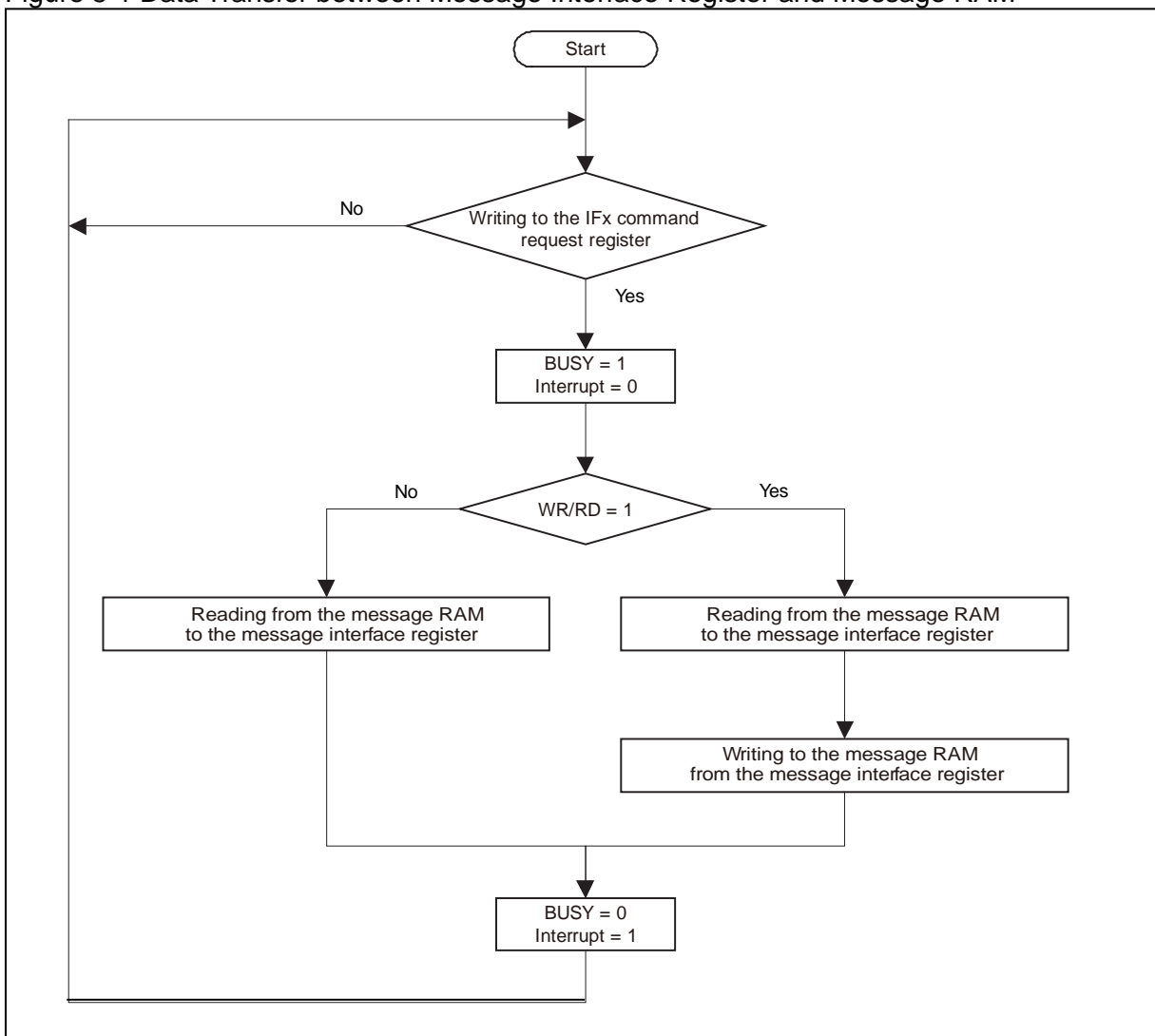
5.1.2. Data Transmission/Reception with Message RAM

Data transmission/reception with message RAM is shown.

The BUSY bit of the IFx command request register (IFxCREQ) will be set to "1" when the data transfer between the message interface register and message RAM is started. The BUSY bit will be cleared to "0" after the transfer completion (see Figure 5-1).

The IFx command mask register (IFxCMSK) sets whether to transfer the entire or partial data of a message object. Due to the structure of message RAM, it is not possible to write a single bit/byte of the message object to message RAM. The entire data of a single message object is always written to message RAM. Data transfer from the message interface register to message RAM therefore requires a read-modify-write cycle.

Figure 5-1 Data Transfer between Message Interface Register and Message RAM



5.2. Message Transmission Operation

Message transmission operation is shown.

This section explains the setting method and transmission operation of the transmission message object.

5.2.1. Message Transmission

Message transmission is explained.

If there is no data transfer between the message interface register and message RAM, the MsgVal bit of the CAN message valid register (MSGVAL) and the TxRqst bit of the CAN transmission request register (TREQR) will be evaluated. Of all message objects with pending transmission request, a valid message object having the highest priority will be transferred to the transmission shift register. The NewDat bit of the message object will be cleared to "0" at this time.

The TxRqst bit will be reset to "0" if there is no new data in the message object (NewDat=0) when the transmission has ended successfully. If the TxIE bit is set to "1", the IntPnd bit will be set to "1" after the transmission has ended successfully. If the CAN controller has lost the arbitration on the CAN bus or an error has occurred during the transfer, message will be retransmitted immediately when the CAN bus becomes idle.

5.2.2. Transmission Priority

Transmission priority is shown.

Transmission priority of a message object is determined by its message number. Message object 1 has the highest priority; and message object 32 (or the maximum equipped message object number) has the lowest priority. Therefore, if 2 or more transmission requests are pending, message objects will be transferred in the order starting from the message object having the smallest corresponding message number.

Notes:

- When the message buffer with the lowest priority is used for transmission and the TXRqst is set to "1" and then to "0" to cancel transmission, setting the TXRqst to "1" again may not, depending on the timing, result in transmission of a message until one of the following events occurs:
 - A valid message is transmitted on the CAN bus.
 - A transmission request is issued to other message buffer.
 - CAN is initialized by the Init bit.If there is a situation in which transmission is canceled due to system reasons, either do not use the message buffer with the lowest priority as the transmission message buffer or, after transmission cancellation, generate one of the above events and then set the TxRqst to "1" again.
 - When the TxRqst bit is "1", do not change the message objects of ID28 to ID0, DLC3 to DLC0, Xtd, and Data7 to Data0. Otherwise, message objects before and after the change may be transmitted in a mixed way or message objects after the change may not be transmitted. Change them when the TxRqst bit is "0".
-

5.2.3. Transmission Message Object Setting

Transmission message object setting is explained.

The initialization method for the transmission object is shown below:

Table 5-1 Transmission Message Object Initialization

MsgVal	Arb	Data	Mask	EoB	Dir	NewDat	MsgLst	RxIE	TxIE	IntPnd	RmtEn	TxRqst
1	appl.	appl.	appl.	1	1	0	0	0	appl.	0	appl.	0

The IFx arbitration register (ID28 to ID0 and Xtd bit) is provided by the application, and it defines the ID and type of the transmission message.

ID28 to ID18 will be used and ID17 to ID0 will be disabled if standard frame (11-bit ID) has been set. ID28 to ID0 will be used if extended frame (29-bit ID) has been set.

If the TxIE bit is set to "1", the IntPnd bit will be set to "1" after the transmission of the message object has ended successfully.

If the RmtEn bit is set to "1", the TxRqst bit will be set to "1" and the data frame will be transmitted automatically after receiving the matching remote frame.

Settings for the data registers (DLC3 to 0, Data0 to 7) are provided by the application.

When UMask=1, the IFx mask register (Msk28 to 0, UMask, MXtd and MDir bits) will receive the remote frame having the ID that has been grouped by the mask setting, and then will be used to allow the transmission (sets the TxRqst bit to "1"). See the heading "Remote frame" in "5.3 Message Reception Operation" for details.

Note:

Mask is not allowed for the Dir bit of the IFx mask register.

5.2.4. Update of Transmission Message Object

Update of transmission message object is explained.

CPU can update the data of the transmission message object via the message interface register.

Data of the transmission message object will be written in units of 4 bytes of the corresponding IFx data register (IFxDTx) (in unit of the IFx data register A (IFxDTAx) or IFx data register B (IFxDTBx)). Therefore, it is not possible to change only 1 byte of the transmission message object.

0087_H will be written to the IFx command mask register (IFxCMSK) first when updating 8-byte data. Then, data of the transmission message object (8-byte data) will be updated and "1" will be written to the TxRqst bit at the same time when a message number is written to the IFx command request register (IFxCREQ).

If the NewDat bit and TxRqst bit are both "1", the NewDat bit will be reset to "0" when the transmission starts.

Notes:

- When updating data, perform it in units of 4 bytes of the IFx data register A(IFxDTAx) or IFx data register B(IFxDTBx).
 - When the TxRqst bit is "1", do not change the message objects of ID28 to 0, DLC3 to 0, Xtd, and Data7 to 0. Otherwise, message objects before and after the change may be transmitted in a mixed way or message objects after the change may not be transmitted. Change them when the TxRqst bit is "0".
-

5.3. Message Reception Operation

Message reception operation is shown.

This section explains the setting method and reception operation of the reception message object.

5.3.1. Reception Message Acceptance Filter

Reception message acceptance filter is shown.

When the arbitration/control field (ID + IDE + RTR + DLC) of the message is completely shifted to the CAN controller reception shift register, scanning of message RAM for a match comparison with the valid message object will be started.

The arbitration field and mask data (including MsgVal, UMask, NewDat and EoB) will be loaded from the message object in message RAM at this time, and the arbitration fields of the message object and shift register will be compared (including mask data).

This operation will be repeated until a match is detected between the arbitration fields of the message object and shift register or until the final word of message RAM is reached. When a match is detected, scanning of message RAM will be stopped and CAN controller will perform different processes according to the type of the reception frame (data frame or remote frame).

5.3.2. Reception Priority

Reception priority is shown.

Reception priority of a message object is determined by its message number. Message object 1 has the highest priority; and message object 32 (or the maximum equipped message object number) has the lowest priority. If 2 or more message objects match the acceptance filter, the one having the smaller message number will be the reception message object.

5.3.3. Data Frame Reception

Data frame reception is shown.

CAN controller transfers and stores the reception message from the shift register to message RAM of the message object that matched the acceptance filter. This stored data not only contains data bytes but also all arbitration fields and data length codes. This operation will be performed even if the IFx mask register is set as a mask (stored in order to hold the ID and data bytes).

The NewDat bit will be set to "1" when a new data is received. Reset the NewDat bit to "0" when a message object is read by the CPU. If the NewDat bit is already set to "1" when the message is received, the previous data will be treated as lost and the MsgLst bit will be set to "1".

If the RxIE bit is set to "1", the IntPnd bit of the CAN interrupt pending register (INTPND) will be set to "1" when a message buffer is received. The TxRqst bit of the message object will be cleared to "0" at this time. This operation is performed to prevent a transmission process from starting when a request data frame is received while the remote frame transmission process is in progress.

5.3.4. Remote Frame

Remote frame is shown.

The following three processes are performed when the remote frame is received. The appropriate process will be selected from the setting of the matching message object.

1. Dir="1" (Transmission direction), RmtEn="1", UMask="1" or "0"
The matched remote frame will be received, only the TxRqst bit of this message object will be set to "1", and the automatic reply (transmission) of the data frame in response to the received remote frame will be performed. (The message object will remain unchanged except for the TxRqst bit.)
2. Dir="1" (Transmission direction), RmtEn="0", UMask="0"
Remote frame will be disabled without receiving the message, even if the received remote frame matches the message object. (the TxRqst bit of the message object will remain unchanged.)
3. Dir="1" (Transmission direction), RmtEn="0", UMask="1"
If the received remote frame matches the message object, the TxRqst bit of this message object will be reset to "0", and the remote frame will be processed as a reception data frame. The received arbitration field and control field (ID + IDE + RTR + DLC) will be stored to the message object in message RAM, and the NewDat bit of this message object will be set to "1". Data field of the message object will be unchanged.

5.3.5. Reception Message Object Setting

Reception message object setting is shown.

The initialization method for the reception message object is shown below:

Table 5-2 Reception Message Object Initialization

MsgVal	Arb	Data	Mask	EoB	Dir	NewDat	MsgLst	RxIE	TxIE	IntPnd	RmtEn	TxRqst
1	appl.	appl.	appl.	1	0	0	0	appl.	0	0	0	0

The IFx arbitration register (ID28 to 0 and Xtd bit) is provided by the application; and it defines the ID and type of the reception message to be used in the acceptance filter.

ID28 to ID18 will be used and ID17 to ID0 will be disabled if standard frame (11-bit ID) has been set. ID17 to ID0 will be reset to "0" when a standard frame is received. ID28 to ID0 will be used if extended frame (29-bit ID) has been set.

If the RxIE bit is set to "1", the IntPnd bit will be set to "1" when the reception data frame is stored to the message object.

Data length code (DLC3 to 0) is provided by the application. Reception data length code and an 8-byte data will be stored when the CAN controller stores the reception data frame to the message object. If the data length code is less than 8 bytes, undefined data will be written to the remaining data of the message object.

When UMask="1", the IFx mask register (Msk28 to 0, UMask, MXtd and MDir bits) will be used to allow the reception of the data frame having the ID that has been grouped by the mask setting. See the data frame reception in "5.3 Message Reception Operation" for details.

Note:

The Dir bit of the IFx mask register cannot be set as a mask.

5.3.6. Reception Message Processing

Reception message processing is explained.

CPU can read reception messages at any time via the message interface register.

Generally, "007F_H" is written to the IFx command mask register (IFxCMSK). Message number of the message object will then be written to the IFx command request register (IFxCREQ). By using this procedure, reception message of the specified message number will be transferred from message RAM to the message interface register. At this time, the NewDat bit and IntPnd bit of the message object can be cleared to "0" by the setting of the IFx command mask register (IFxCMSK).

The message will be received if it matches the acceptance filter. If the acceptance filter mask is used in the message object, the data that has been set as a mask will be excluded from the acceptance filter, and the decision of whether or not to receive the message will be made.

The NewDat bit indicates whether a new message has been received after the message object was last read.

The MsgLst bit indicates that the next reception data has been received before the previously received data is read from the message object, resulting in the loss of the previous data. The MsgLst bit will not be reset automatically.

The TxRqst bit will be cleared to "0" automatically when a data frame matching the acceptance filter is received while the remote frame transmission is being processed.

5.4. FIFO Buffer Function

FIFO buffer function is shown.

This section explains the configuration and operation of the FIFO buffer of the message object in the reception message processing.

5.4.1. Configuration of FIFO Buffer

The configuration of FIFO buffer is explained.

The configuration of the reception message objects in the FIFO buffer is the same as that of other reception message objects, except for the EoB bit (see "5.3 Message Reception Operation" for the reception message object setting).

FIFO buffer is used by linking 2 or more reception message objects. When using the ID and mask of the reception message object, it is necessary to match those settings in order to store the reception message to this FIFO buffer.

The first reception message object of the FIFO buffer will be the message object having the highest priority (smallest message number). The EoB bit of the final reception message object of the FIFO buffer must be set to "1" to indicate the end of the FIFO buffer block (Set The EoB bit to "0" for message objects other than the final message object that uses the configuration of the FIFO buffer).

Notes:

- Always make the same settings for ID and mask setting of the message object to be used in the FIFO buffer.
 - Always set The EoB bit to "1" when FIFO buffer is not used.
-

5.4.2. Message Reception by FIFO Buffer

Message reception by FIFO buffer is explained.

If the reception message matches the ID of the FIFO buffer, it will be stored to the reception message object in the FIFO buffer having the smallest message number.

The NewDat bit of this reception message object will be set to "1" when the message is stored to the reception message object in the FIFO buffer. When the NewDat bit is set to the reception message object whose the EoB bit is "0", a write operation to the FIFO buffer by the CAN controller will not be performed as the reception message object will be protected until the final reception message object (EoB = "1") is reached.

If the NewDat bit of the reception message object is not written to "0" (release of write protection) while valid data is stored up to the final FIFO buffer, the next reception message will be written to the final message object, overwriting the previous message.

5.4.3. Reading from FIFO Buffer

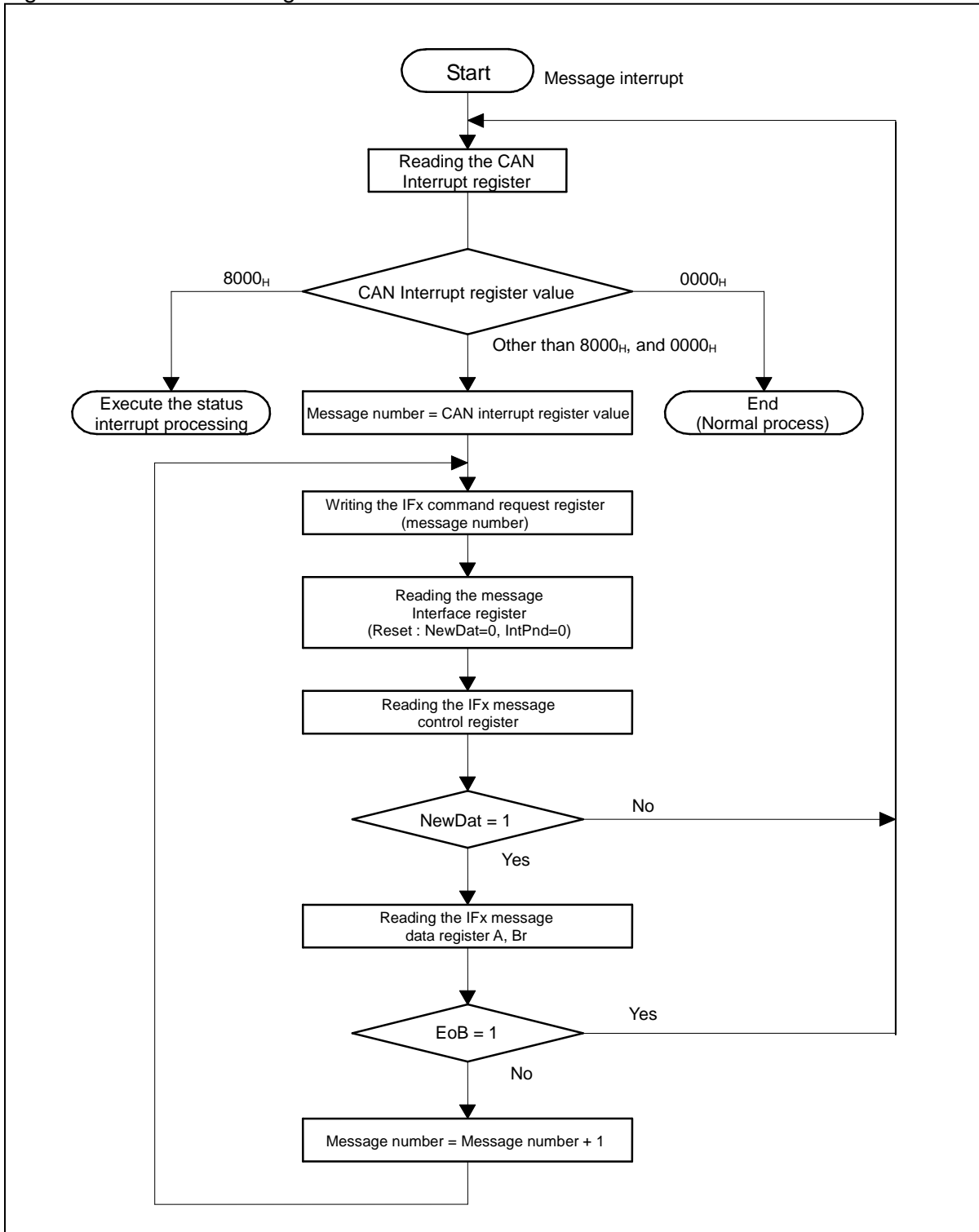
Reading from FIFO buffer is explained.

CPU can read the content of the received message object by writing the reception message number to the IFx command request register (IFxCREQ) that will cause the message object to be transferred to the message interface register. Set the WR/RD to "0" (read), set the TxRqst/NewDat and the IntPnd to "1" and reset NewDat and IntPnd bits to "0" in the IFx command mask register (IFxCMSK) at this time.

In order to guarantee the function of the FIFO buffer, always read the reception message objects in the FIFO buffer starting from the one having the smallest message number.

The figure below shows the CPU processing method for the message objects that are linked in the FIFO buffer.

Figure 5-2 CPU Processing of FIFO Buffer



5.5. Interrupt Function

Interrupt function is explained.

This section explains the processing of status interrupt (IntId=8000_H) and message interrupt (IntId=message number).

If 2 or more interrupts are pending, the CAN interrupt register (INTR) will indicate the pending interrupt code of the highest priority interrupt. High priority interrupt codes will always be displayed, ignoring the chronological order in which the interrupt codes were set. Interrupt code will be held until it is cleared by CPU.

Status interrupt (IntId bit = 8000_H) has the highest priority.

Priority of message interrupts becomes higher as the message number gets smaller, and vice versa.

Message interrupt will be cleared when the IntPnd bit of the message object is cleared. Status interrupt will be cleared when the CAN status register (STATR) is read.

the IntPnd bit of the CAN interrupt pending register (INTPND) indicates whether any interrupt exists. The IntPnd bit will indicate "0" if there is no pending interrupt.

The interrupt signal to the CPU will become active when the IndPnd bit becomes "1" while the IE bit of the CAN control register (CTRLR) and TxIE and RxIE bits of the IFx message control register (IFxMCTR) are set to "1". The interrupt signal maintains its active state until the CAN interrupt pending register (INTPND) is cleared to "0" (interrupt factor reset) or until IE bit of the CAN control register (CTRLR) is reset to "0".

the CAN interrupt register (INTR) being set to "8000_H" indicates an update of the CAN status register (STATR) by the CAN controller; and this interrupt will have the highest priority. The interrupt generated by updating the CAN status register (STATR) can allow or prohibit the setting of the CAN interrupt register (INTR) by using EIE and SIE bits of the CAN control register (CTRLR). Interrupt signal to the CPU can be controlled by the IE bit of the CAN control register (CTRLR).

The RxOk bit, TxOk bit and LEC bit of the CAN status register (STATR) can be updated (reset) by a write from the CPU. However, interrupt cannot be set or reset by the write operation.

The CAN interrupt register (INTR) set to other than "8000_H" and "0000_H" indicates that the message interrupt is currently pending and that it has a high priority.

The CAN interrupt register (INTR) will be updated even when IE has been reset.

Message interrupt factor to the CPU can be confirmed in the CAN interrupt register (INTR) or CAN interrupt pending register (INTPND). (See "4.5 Message Handler Registers".) When clearing a message interrupt, it is possible to read the message data at the same time. When the message interrupt specified by the CAN interrupt register (INTR) is cleared, the next priority interrupt will be set to the CAN interrupt register (INTR), waiting for the next interrupt process. The CAN interrupt register (INTR) will indicate "0000_H" if there is no interrupt.

Notes:

- Status interrupt (IntId=8000_H) will be cleared by a read access from the CAN status register (STATR).
 - Status interrupt (IntId=8000_H) by a write access to the CAN status register (STATR) will not be generated.
-

5.6. Bit Timing and CAN System Clock (fsys) Generation

Bit timing and CAN system clock (fsys) generation is explained.

This section explains the overview of bit timing and its role in the CAN controller.

Each CAN node of the CAN network has a clock oscillator (normally a crystal oscillator). Time parameter of bit time can be configured individually for each CAN node. A common bit rate can be produced even if the oscillation cycle (fosc) of each CAN node is different.

Frequency of these oscillators differ slightly by temperature/voltage change or component deterioration. CAN node can compensate different bit rates by resynchronizing to the bit stream, as long as this fluctuation falls within the tolerance range (df) of the oscillator.

The bit time is divided into the following four segments (see Figure 5-4 Bit timing) according to the CAN specification: synchronization segment (Sync_Seg), transmission time segment (Prop_Seg), phase buffer segment 1 (Phase_Seg1) and phase buffer segment 2 (Phase_Seg2). Each segment consists of a programmable time quantum (see Table 5-3 CAN Bit Time Parameters). Basic unit time (tq) of the bit time is defined by the system clock (fsys) of the CAN and baud rate prescaler (BRP).

$$tq = BRP / f_{sys}$$

CAN system clock (fsys) will be generated as shown in the figure below. Sync_Seg of the synchronization segment will be the timing within the bit time expecting the edge of the CAN bus. Prop_Seg of the transmission time segment compensates the physical delay time in the CAN network. Phase_Seg1 and Phase_Seg2 of the phase buffer segment specify the sampling point. Resynchronization jump width (SJW) defines the displacement of the sampling point at resynchronization in order to compensate the edge phase error.

Figure 5-3 Schematic Diagram of CAN System Clock (fsys) Generation

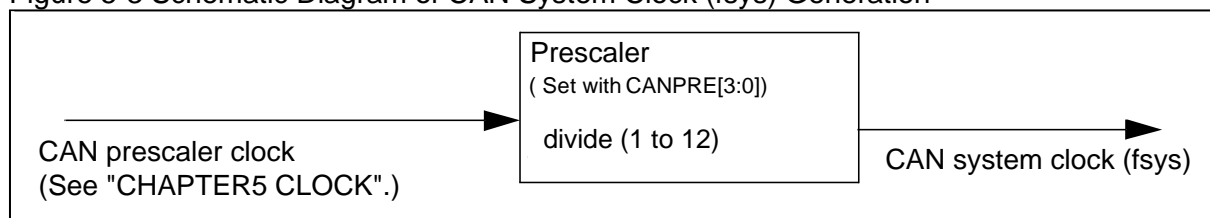


Figure 5-4 Bit timing

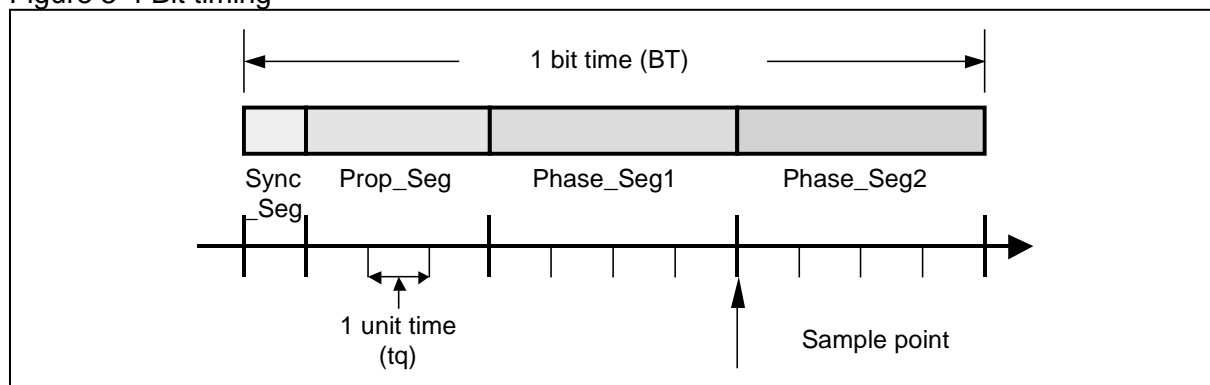


Table 5-3 CAN Bit Time Parameters

Parameter	Range	Function
BRP	[1 to 32]	Defines the time quantity t_q .
Sync_Seg	1 t_q	Fixed length. Synchronizes the bit time with the system clock.
Prop_Seg	[1 to 8] t_q	Compensates for physical delay time.
Phase_Seg1	[1 to 8] t_q	Guarantees identification of edge-phase errors prior to the sample point. The bit time may be temporarily prolonged due to synchronization.
Phase_Seg2	[1 to 8] t_q	Guarantees identification of edge-phase errors subsequent to the sample point. The bit time may be temporarily shortened due to synchronization.
SJW	[1 to 4] t_q	Defines the resynchronization jump width. It will not be greater than either of the phase buffer segments.

The bit timing effected by the CAN controller is shown in the following.

Figure 5-5 Bit Timing Effected by the CAN Controller

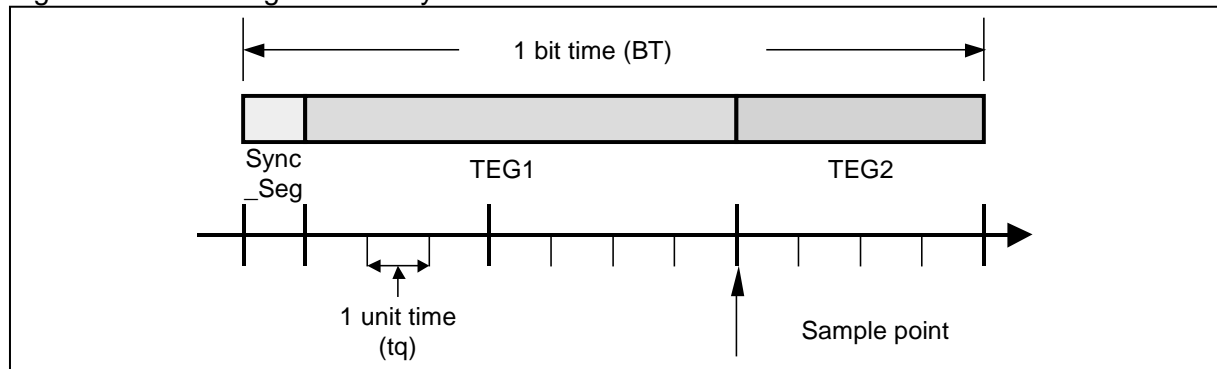


Table 5-4 CAN Controller Parameters

Parameter	Range	Function
BRPE, BRP	[0 to 1023]	Defines the time quantity tq . The prescaler can be extended up to 1024 using the bit timing and prescaler extension registers.
Sync_Seg	1 tq	Synchronizes the bit time with the system clock. Fixed length
TSEG1	[1 to 15] tq	Time segment prior to the sample point. This corresponds to Prop_Seg and Phase_Seg1. This width can be controlled using the bit timing register.
TSEG2	[0 to 7] tq	Time segment subsequent to the sample point. This corresponds to Phase_Seg2. This width can be controlled using the bit timing register.
SJW	[0 to 3] tq	Defines the resynchronization jump width. This width can be controlled using the bit timing register.

The relationships among the parameters are as follows:

$$tq = ([BRPE, BRP] + 1) / f_{sys}$$

$$BT = SYNC_SEG + TEG1 + TEG2$$

$$= (1 + (TSEG1 + 1) + (TSEG2 + 1)) \times tq$$

$$= (3 + TSEG1 + TSEG2) \times tq$$

5.7. Test Mode

Test mode is shown.

This section explains the test mode setting method and operation.

5.7.1. Test Mode Setting

Test mode setting is shown.

The CAN controller enters test mode when the Test bit of the CAN control register (CTRLR) is set to "1". In test mode, the bits Tx1, Tx0, LBack, Silent, and Basic of the CAN test register (TESTR) are valid.

All test register functions are invalidated when the Test bit of the CAN control register (CTRLR) is reset to "0".

5.7.2. Silent Mode

Silent mode is explained.

The CAN controller enters silent mode when the Silent bit of the CAN test register (TESTR) is set to "1".

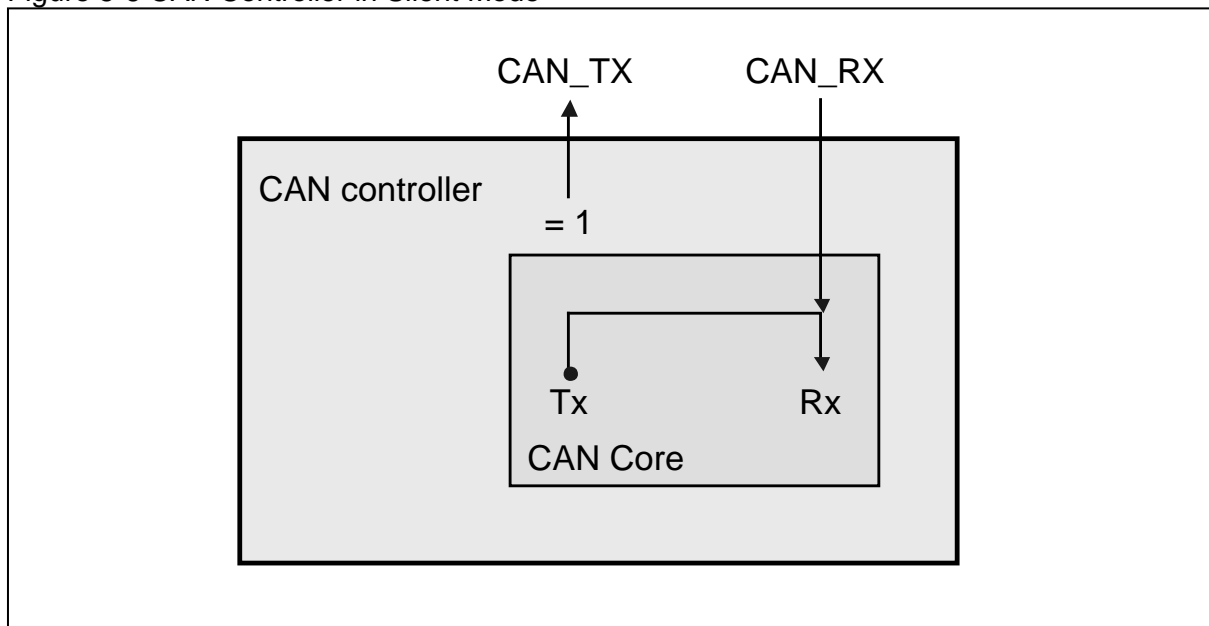
In silent mode, the CAN controller can receive data frames and remote frames, but only outputs a recessive level to the CAN bus and does not send messages or ACKs.

When the CAN controller is requested to send a dominant bit (the ACK bit, overload flag, or active error flag), it sends the dominant bit to the RX end through a loopback circuit within the CAN controller. During this operation, the receiving end can receive the dominant bit that is sent through the loopback circuit within the CAN controller even if the CAN bus is in the recessive-level state.

In silent mode, traffic over the CAN bus can be analyzed without influence from the transmission of dominant bits (ACK bits and error flags).

The figure below shows how signals CAN_TX and CAN_RX are connected to the CAN controller in silent mode:

Figure 5-6 CAN Controller in Silent Mode



5.7.3. Loopback Mode

Loopback mode is explained.

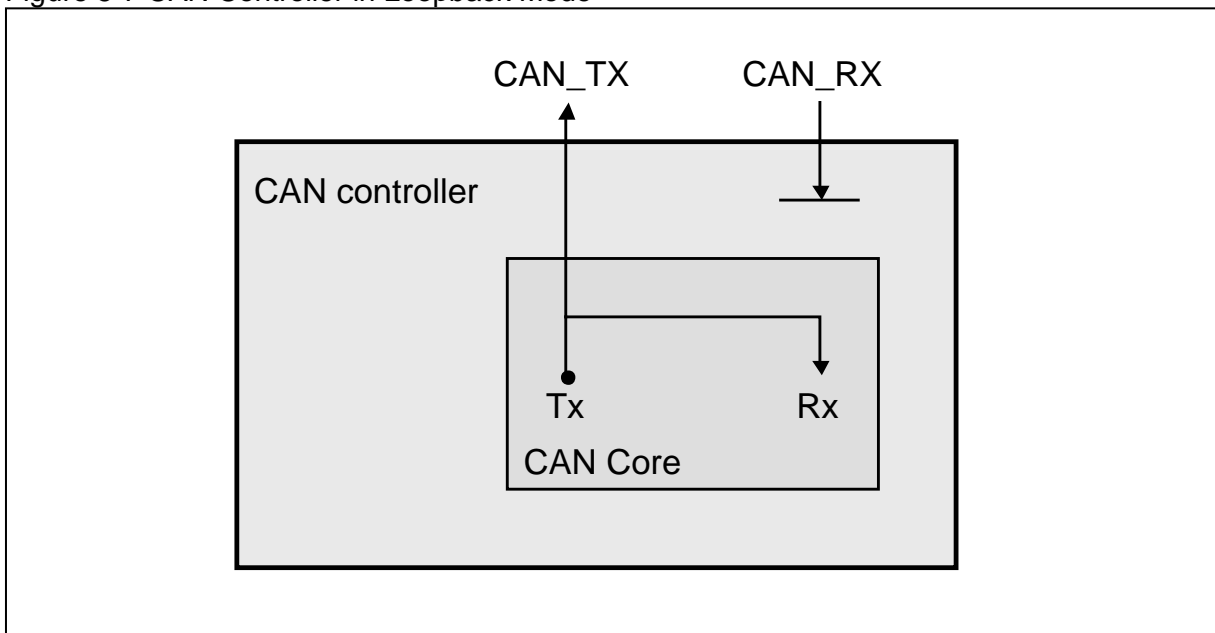
The CAN controller enters loopback mode when the LBack bit of the CAN test register (TESTR) is set to "1".

Loopback mode can be used for self-diagnostics.

In loopback mode, the TX end and the RX end are connected within the CAN controller, messages sent by the CAN controller are handled as messages received by the RX end, and messages that have passed through the acceptance filter are stored in the receive buffer.

The figure below shows how signals CAN_TX and CAN_RX are connected to the CAN controller in loopback mode:

Figure 5-7 CAN Controller in Loopback Mode



Note:

Dominant bits from the acknowledge slot of data/remote frames are not sampled to ensure that they are left independent of external signals. Therefore, the CAN controller will not generate acknowledge errors in test mode although it may generate these errors in other mode.

5.7.4. Combination of Silent and Loopback Modes

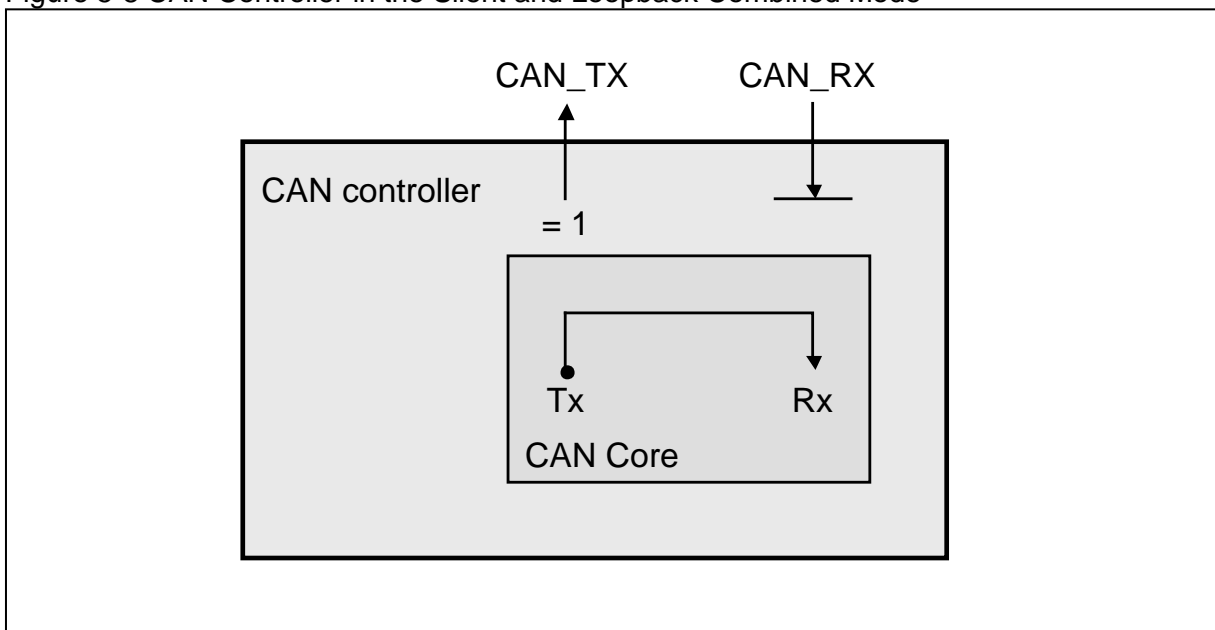
Combination of silent and loopback modes is explained.

The CAN controller can work in a mode that combines loopback and silent modes, when the LBack and Silent bits of the CAN test register (TESTR) are set to "1" simultaneously.

This combined mode can be used for hot self-tests. "Hot self-test" means that when the CAN controller is in process of tests in loopback mode, CAN system operation receives no influence from these tests because a fixed recessive-level output is at the CAN_TX pin and the input from the CAN_RX pin is invalid.

The figure below shows how signals CAN_TX and CAN_RX are connected to the CAN controller in the silent and loopback combined mode:

Figure 5-8 CAN Controller in the Silent and Loopback Combined Mode



5.7.5. Basic Mode

Basic mode is explained.

The CAN controller enters basic mode when the Basic bit of the CAN test register (TESTR) is set to "1".

In basic mode, the CAN controller works without using the message RAM.

The IF1 message interface register is used for transmission control.

The message transmission procedure begins with the setting of the send data in the IF1 message interface register. The next step is to set the BUSY bit of the IF1 command request register to "1" to issue a transmission request. While the BUSY bit is set to "1", the IF1 message interface register is locked or transmission is held.

When the BUSY bit is set to "1", the CAN controller performs the following operation:

As soon as the CAN bus becomes idling, the CAN controller begins transmission by loading the content of the IF1 message interface register to the transmission shift register. When transmission ends normally, the BUSY bit is reset to "0", and the locked IF1 message interface register is released.

While transmission is held, it can be suspended anytime by resetting the BUSY bit of the IF1 command request register to "0". When the BUSY bit is reset to "0" during transmission, retransmission that would be initiated after an arbitration loss or error will not be initiated.

The IF2 message interface register is used for reception control.

All messages are received without using the acceptance filter. The received message can be read when the BUSY bit of the IF2 command request register is set to "1".

When the BUSY bit is set to "1", the CAN controller performs the following operation:

- The CAN controller stores the received message (content of the reception shift register) in the IF2 message interface register without using the acceptance filter.

If the CAN controller has stored a new message in the IF2 message interface register, it sets the NewDat bit to "1". If the CAN controller receives a further new message when the NewDat bit is "1", it sets the MsgLst bit to "1".

Notes:

- In basic mode, all message objects relating to the control/status bits and the control mode settings on the IFx command mask register (IFxCMSK) are invalidated.
 - The message number in the command request register is invalid.
 - On the IF2 message control register, the NewDat and MsgLst bits work as usual, the DLC3 to 0 bits identify the received DLC, and the other control bits are read as "0".
-

5.7.6. Software Control of the CAN_TX Pin

Software control of the CAN_TX pin is explained.

The CAN_TX pin, which is the CAN transmission pin, has four output functions as follows:

- Serial data output (ordinary output)
- CAN sampling point signal output for CAN controller bit timing monitoring
- Fixed dominant output
- Fixed recessive output

Fixed dominant and recessive outputs can be used to check the physical layer of the CAN bus together with the CAN_RX monitoring function of the CAN reception pin.

The CAN_TX pin output mode can be controlled using the Tx1 and Tx0 bits of the CAN test register (TESTR).

Note:

For CAN message transmission or operation in loopback, silent, or basic mode, the CAN_TX pin must be configured for serial data output.

5.8. Software Initialization

Software initialization is explained.

Software-controlled initialization is as follows:

The causes of software-controlled initialization are as follows:

- Hardware reset
- Setting of the Init bit of the CAN control register (CTRLR)
- Transition to bus-off state

A hardware reset initializes everything except the message RAM (excluding the MsgVal, NewDat, IntPnd, and TxRqst bits). After a hardware reset, initialize the message RAM by way of the CPU or reset the MsgVal bit of the message RAM to "0". If the bit timing register needs to be set, set it before clearing the Init bit of the CAN control register (CTRLR) to "0".

The Init bit of the CAN control register (CTRLR) is set to "1" on one of the following conditions:

- Write of "1" from the CPU
- Hardware reset
- Bus-off

When the Init bit is set to "1", all message transmission/reception over the CAN bus is suspended and the CAN_TX pin, which is for CAN bus output, is set to a recessive-level output state (except for CAN_TX test mode).

When the Init bit is set to "1", the error counter does not change and the registers do not change.

When the Init and CCE bits of the CAN control register (CTRLR) are set to "1", the baud rate control bit timing register and prescaler extension register can be configured.

Software initialization will terminate when the Init bit is reset to "0". The Init bit can only be reset to "0" through access from the CPU.

When the generation of 11 consecutive recessive bits (indicating a bus-idling state) are waited after the Init bit is reset to "0", the CAN controller can be synchronized with the data transfer over the CAN bus. This can be followed by message transfer.

If the message object Msk, ID, XTD, EoB, and/or RmtEn needs to be changed during ordinary operation, change it after invalidating the MsgVal bit.

CHAPTER : AD CONVERTER

This chapter explains the AD converter.

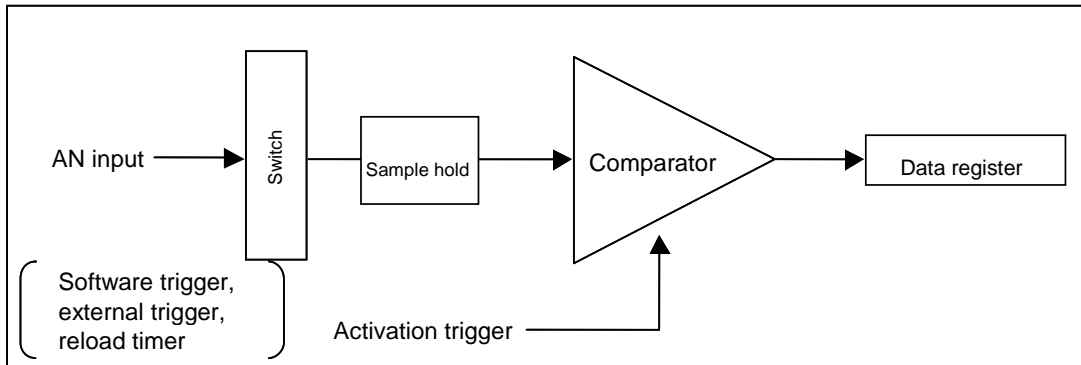
1. Overview
2. Features
3. Configuration
4. Registers
5. Operation
6. Setting
7. Q&A
8. Sample Program
9. Notes
10. Term Definition for A/D Converter

1. Overview

This section explains the overview of the AD converter.

An A/D converter is a device which converts an analog input voltage to a digital value.

Conversion modes include the single conversion mode, continuous conversion mode, and stop conversion mode, and each mode has the single conversion operation and scan conversion operation as a conversion operation. An activation factor can be selected from various triggers (software trigger/external trigger/reload timer).



2. Features

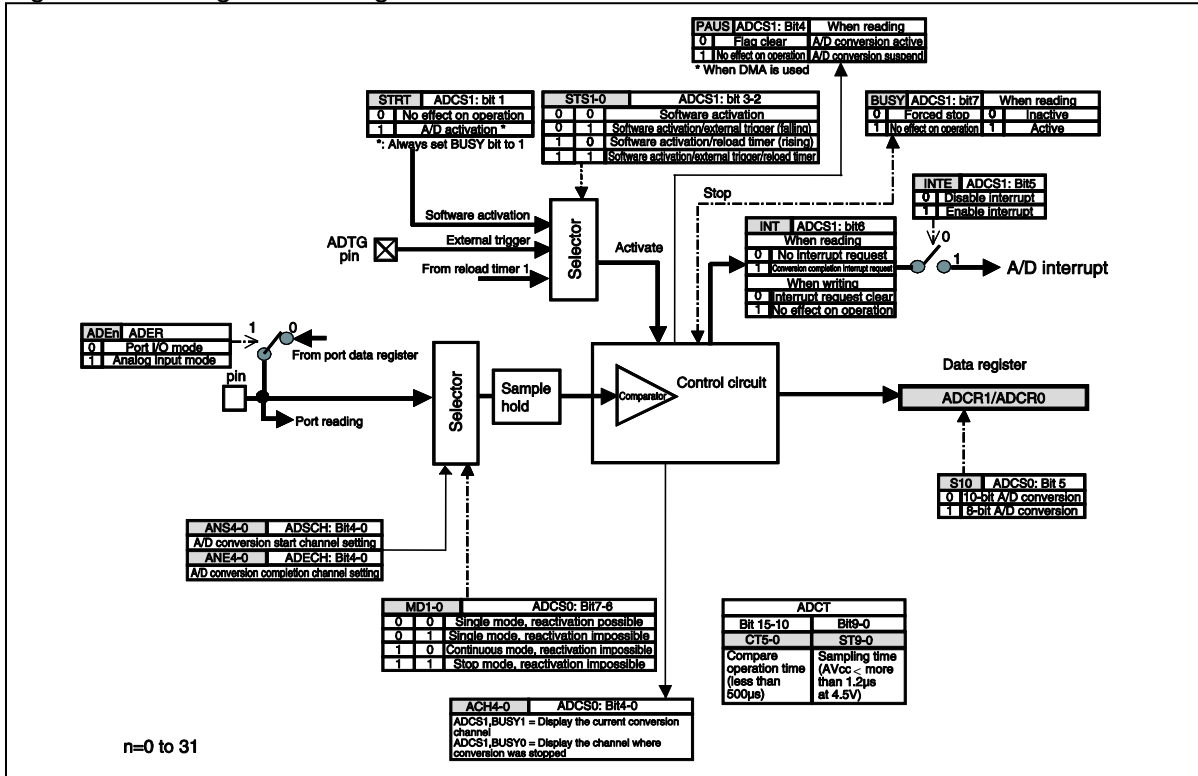
This section explains features of the AD converter.

- Conversion method: RC type sequential comparison conversion method with sample hold circuit
- Number: 1 (A/D converter input - 32 channels: AN0 to AN31)
- Conversion time:
 - Minimum 3 μ s (including sample hold time)
 - Conversion time = Sampling + Conversion
- Resolution: 8/10-bit resolution
- Conversion mode:
 - Single conversion mode : One cycle conversion of specified channel
 - Continuous conversion mode: Repeated conversion of specified channel
 - Stop conversion mode : Pause and wait until next activation after conversion of specified channel
(conversion start can be synchronized)
- Conversion operation: The following are conversion operations for conversion modes above.
 - Single conversion operation: One channel is selected and converted.
 - Scan conversion operation: Continuous multiple channels are converted. Maximum 32 channels programs enabled.
- Activation factor:
 - Soft trigger (ADCS1:STRT)
 - External trigger, falling (ADTG pin)
 - Reload timer, rising (Reload timer 1)
- Interrupt request:
 - A/D conversion completion interrupt request is generated for CPU on A/D conversion completion.
- Interrupt: Conversion completion interrupt
- Function stop: Forced stop of A/D conversion operation is enabled.

3. Configuration

This section explains the configuration of the AD converter.

Figure 3-1 Configuration Diagram



4. Registers

This section explains registers of the AD converter.

Table 4-1 Registers Map

Address	Registers				Register Function
	+0	+1	+2	+3	
0x00A0	ADDER				Analog input enable register
0x00A4	ADCS1	ADCS0	ADCR1	ADCR0	A/D control status register upper A/D control status register lower Data register upper Data register lower
0x00A8	ADCT		ADSCH	ADECH	Conversion time setting register A/D start channel setting register A/D completion channel setting register

4.1. Analog Input Enable Register : ADER

The analog input enable register is explained.

These registers set the appropriate pins to the analog inputs.

■ ADERH : Address 00A0_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	ADE31	ADE30	ADE29	ADE28	ADE27	ADE26	ADE25	ADE24
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ADE23	ADE22	ADE21	ADE20	ADE19	ADE18	ADE17	ADE16
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

■ ADERL : Address 00A2_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	ADE15	ADE14	ADE13	ADE12	ADE11	ADE10	ADE9	ADE8
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ADE7	ADE6	ADE5	ADE4	ADE3	ADE2	ADE1	ADE0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit0] ADE[31:0] : Analog input enable

ADE _n	Meaning
0	Port input/output mode
1	Analog input mode

n = 0 to 31

The analog input enable register (ADER) of the start channel and complete channel must be set with "1".

4.2. A/D Control Status Register (Upper) : ADCS1

The A/D control status register (upper) is explained.

This register is for A/D converter control and status display.

■ ADCS1 : Address 00A4_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	BUSY	INT	INTE	PAUS	STS1	STS0	STRT	Reserved
Initial value	0	0	0	0	0	0	0	0
Attribute	R (RM1),W	R (RM1),W	R/W	R,W	R/W	R/W	R (RM0),W	R0,W0

[bit7] BUSY : Forced stop directive bit/operation check bit

BUSY	Read	Write
0	The A/D converter is being stopped.	The A/D converter is stopped forcibly.
1	The A/D converter is being operated.	No effect on operations

- This bit is set by A/D conversion activation.
- It is cleared with conversion completion of the final channel in the single mode.
- It is not cleared until the A/D converter is stopped with "0" writing in the continuous/stop mode.
- Do not perform forced completion and software activation simultaneously (BUSY=0, STRT=1).
- When the soft trigger performs activation ("1" writing to the STRT bit), the forced stop directive bit must be written with "1".(If they are not set with "1" simultaneously, the activation is not started.)

[bit6] INT : A/D conversion completion flag/interrupt request flag

INT	Read	Write
0	Without interrupt request	Clear of flag
1	With interrupt request (A/D conversion completion, all scan conversion completion)	No effect on operations

Note:

Clear "0" writing during A/D stop.

[bit5] INTE : A/D interrupt request enable bit

INTE	Meaning
0	Interrupt request disable
1	Interrupt request enable

When the A/D interrupt request enable bit (INTE) and the A/D conversion completion flag/interrupt request flag (INT) are set with "1", an interrupt is generated.

[bit4] PAUS : A/D pause flag

PAUS	Read	Write
0	A/D conversion is being operated	Clear of flag
1	A/D conversion operation paused	No effect on operations

Since the register to store the A/D conversion result is one, for continuous conversions, if the conversion result is not transferred, the previous data will break.

To protect this, if the content of the data register is not transferred, next conversion data will not be stored. During this, the A/D conversion operation is stopped. After transfer is completed, if the INT bit is cleared, the A/D conversion is restarted.

- Clearing is enabled only with "0" writing. (Clearing is not enabled with the transfer completion.)
- If next A/D conversion is executed in the state where the INTE bit is set to "1", the PAUS bit will be set to "1". (To protect the data of the previous A/D conversion) after the A/D conversion of 1 channel, the INT bit must be cleared before next A/D conversion.
- For the protect function for conversion data, see "5.3 Conversion Mode".

[bit3, bit2] STS1, STS0 : Selection of A/D conversion activation factor

STS1	STS0	Activation Factor
0	0	Software trigger
0	1	External trigger (falling) or software trigger
1	0	Reload timer output (rising) or software trigger
1	1	External trigger (falling) or reload timer output (rising), or software trigger

- If multiple activation factors are specified, the A/D conversion is activated by the factor that occurs first.
- The activation factor that occurs during A/D conversion is enabled when the conversion is restarted in the single conversion mode (ADCS0:MD[1:0]="00") and the stop conversion mode (ADCS0:MD[1:0]="11").
- The reactivation in the single conversion mode (ADCS0:MD[1:0]="01"), continuous conversion mode, or stop conversion mode must be performed after the A/D conversion operation is stopped once (BUSY="0").
- When you rewrite the activation factor setting during A/D conversion, pay attention to that the activation factor setting is changed right after rewriting.
- The external pin trigger detects the falling edge. If the external pin trigger activation is set by rewriting of the bit during the external trigger input level is "L", A/D might be activated.
- On the timer selection, 16-bit reload timer 1 is selected.

[bit1] STRT : A/D conversion software trigger

STRT	Function
0	No effect on operations
1	The A/D converter is activated (software trigger).

- When the software trigger activation is set, the forced stop directive bit (BUSY) also must be set to "1". If the forced stop directive bit (BUSY) is set to "0" simultaneously, the A/D is not activated.
- For reactivation, write "1" again after the forced stop by writing "0" to the BUSY bit.
- Reactivation is disabled in the continuous mode and stop mode operation functionally. Check the BUSY bit before "1" is written. (Activate after the BUSY bit is cleared.)
- Do not perform forced completion and software activation simultaneously (BUSY=0, STRT=1).

[bit0] Reserved

This bit must always be written to "0".

4.3. A/D Control Status Register (Lower) : ADCS0

The A/D control status register (lower) is explained.

This register is for A/D converter control and status check.

Note:

Do not rewrite during the A/D conversion operation.

■ **ADCS0 : Address 00A5_H (Access: Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	MD1	MD0	S10	ACH4	ACH3	ACH2	ACH1	ACH0
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R,WX	R,WX	R,WX	R,WX	R,WX

[bit7, bit6] MD1, MD0 : Operation mode setting

MD1	MD0	Operating mode
0	0	Single conversion mode. Any reactivation during operation is enabled.
0	1	Single conversion mode. Reactivation during operation is disabled.
1	0	Continuous conversion mode. Reactivation during operation is disabled.
1	1	Stop conversion mode. Reactivation during operation is disabled.

- **Single conversion mode:**
A/D conversion is performed continuously for ADSCH:ANS[4:0] setting channel to ADECH:ANE[4:0] setting channel. When the conversion for all channels is completed, the A/D converter is stopped.
- **Continuous conversion mode:**
A/D conversion is performed repeatedly for ADSCH:ANS[4:0] setting channel to ADECH:ANE[4:0] setting channel.
- **Stop conversion mode:**
A/D conversion is performed and paused for each channel from ADSCH:ANS[4:0] setting channel to ADECH:ANE[4:0] setting channel. Conversion restart is performed with activation factor occurrence.
- When the A/D conversion is activated in the continuous conversion mode or stop conversion mode, the conversion operation is continued until the conversion is stopped forcibly with the BUSY bit.
- Forced stop is performed with "0" writing to the BUSY bit.
- On the activation after forced stop, the conversion is performed starting from the setting channel of ADSCH:ANS[4:0].
- The reactivation disable in the single, continuous, or stop conversion mode applies to any of timer, external trigger and software activation.

[bit5] S10 : Resolution setting

S10	Configuration
0	10-bit A/D conversion
1	8-bit A/D conversion

The result of 8-bit A/D conversion is stored to ADCR0.

[bit4 to bit0] ACH4 to ACH0 : Analog conversion channels

ACH4	ACH3	ACH2	ACH1	ACH0	Conversion Channel
0	0	0	0	0	AN0
0	0	0	0	1	AN1
0	0	0	1	0	AN2
0	0	0	1	1	AN3
0	0	1	0	0	AN4
0	0	1	0	1	AN5
0	0	1	1	0	AN6
0	0	1	1	1	AN7
0	1	0	0	0	AN8
0	1	0	0	1	AN9
0	1	0	1	0	AN10
0	1	0	1	1	AN11
0	1	1	0	0	AN12
0	1	1	0	1	AN13
0	1	1	1	0	AN14
0	1	1	1	1	AN15
1	0	0	0	0	AN16
1	0	0	0	1	AN17
1	0	0	1	0	AN18
1	0	0	1	1	AN19
1	0	1	0	0	AN20
1	0	1	0	1	AN21
1	0	1	1	0	AN22
1	0	1	1	1	AN23
1	1	0	0	0	AN24
1	1	0	0	1	AN25
1	1	0	1	0	AN26
1	1	0	1	1	AN27
1	1	1	0	0	AN28
1	1	1	0	1	AN29
1	1	1	1	0	AN30
1	1	1	1	1	AN31

ADCS1:BUSY	Channel Status on Read
1 (A/D conversion being performed)	Current conversion channel
0 (on forced completion)	Conversion stopped channel

4.4. Data Register : ADCR0, ADCR1

The bit configuration for the data register is explained.

The data registers (ADCR0, ADCR1) are used for storage of digital values generated as the result of conversion. ADCR0 stores the lower 8-bit and ADCR1 stores the most significant 2-bit of the conversion result.

The data register value is updated for one conversion completion.

The data register normally stores the final conversion values.

■ **ADCR1: Address 00A6_H (Access: Byte, Half-word, Word)**

■ **ADCR0: Address 00A7_H (Access: Byte, Half-word, Word)**

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved						D9	D8
Initial value	—	—	—	—	—	—	X	X
Attribute	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R0,WX	R,WX	R,WX

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	D7	D6	D5	D4	D3	D2	D1	D0
Initial value	X	X	X	X	X	X	X	X
Attribute	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX	R,WX

The conversion data protection function can be used. See "5.3 Conversion Mode".

Note:

- Access ADCR0 after accessing ADCR1 when you access ADCR1(0x0000A6) and ADCR0(0x0000A7) using the byte. There is a possibility that the conversion result is overwritten before reading the value of the ADCR1 register when accessing it in order of ADCR0 and ADCR1 because the superscription of the conversion result waits for reading to ADCR0 and it is done.

Note:

- In the state that an interrupt clear is previously done, and the conversion result is not read, it waits until the conversion result is read without overwriting the conversion result when the following conversion ends. If the read is previously done, it suspends the overwrite of the result until the interrupt is cleared.

4.5. Conversion Time Setting Register : ADCT

The conversion time setting register is explained.

This register controls the sampling time and comparison time. It is for setting of A/D conversion time.

Note:

Do not rewrite during the A/D conversion operation.

■ Recommended setting value

To achieve the optimum conversion time, the following settings are recommended. ($AVCC5 \geq 4.5V$)

Peripheral clock (PCLK) (MHz)	Comparison Operation Time (CT5 to CT0)	Sampling Time (ST9 to ST0)	Conversion Time (μs)
16	000011 (03 _H)	0000010110 (016 _H)	2.125+1.375=3.500
24	000100 (04 _H)	0000100001 (021 _H)	1.833+1.375=3.208
32	000110 (06 _H)	0000101100 (02C _H)	2.000+1.375=3.063

■ Conversion Time Setting Register : ADCT (ADCT0, ADCT1)

● ADCT1: Address 00A8_H (Access: Byte, Half-word, Word)

● ADCT0: Address 00A9_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	CT5	CT4	CT3	CT2	CT1	CT0	ST9	ST8
Initial value	0	0	0	1	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	ST7	ST6	ST5	ST4	ST3	ST2	ST1	ST0
Initial value	0	0	1	0	1	1	0	0
Attribute	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

[bit15 to bit10] CT5 to CT0 : Comparison operation time clock division value setting

- If CT5 to CT0 are set to "000001" (01_H), no division = PCLK is set.
- Do not set CT5 to CT0 to "000000" (00_H).

Note:

The following restriction should be applied to the maximum spread frequency of the base clock, if the spread clock is used for the peripheral clock. And the restriction should be applied to the PLL clock frequency, if the non spread clock is used. See Figure 1-1 and Figure 3-5 in

"CHAPTER: CLOCK" for the base clock and the PLL clock.

If the frequency of the base clock or the PLL clock is faster than 32MHz, the setting of division number of the peripheral clock must be larger than or equal to 2.

If the frequency of the base clock or the PLL clock is faster than 80MHz, CT5 to CT0 must be set larger than "000010"(02h) regardless of division setting of the peripheral clock (PCLK2).

Set CT5 to CT0 so that the clock at the comparison operation time becomes 8 to 17MHz.

[bit9 to bit0] ST9 to ST0 : Analog input sampling time setting

They are initialized to "0000101100"(02C_H) by reset.

Setting the following values to ST9 to ST0 is inhibited. Set the value larger than 3.

"00000010"(02_H), "00000001"(01_H), "00000000"(00_H)

4.6. A/D Start/Completion Channel Setting Register : ADSCH, ADECH

The bit configuration of the A/D start/completion channel setting register is explained.

This register is for setting of a start channel and a completion channel for A/D conversion.

Do not rewrite during the A/D conversion operation.

■ A/D Start Channel Setting Register:ADSCH

● ADSCH : Address 00AA_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	ANS4	ANS3	ANS2	ANS1	ANS0
Initial value	—	—	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R/W0	R/W	R/W	R/W	R/W	R/W

■ A/D Completion Channel Setting Register:ADECH

● ADECH : Address 00AB_H (Access: Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	—	—	—	ANE4	ANE3	ANE2	ANE1	ANE0
Initial value	—	—	0	0	0	0	0	0
Attribute	R0,WX	R0,WX	R/W0	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] - : Undefined

The read value is always "0". Writing has no effect on operation.

[bit5] Reserved

This bit must always be written to "0".

[bit4 to bit0] ANS4 to ANS0/ANE4 to ANE0 : Start/completion channel

ANS4	ANS3	ANS2	ANS1	ANS0	Start Channel
ANE4	ANE3	ANE2	ANE1	ANE0	Completion Channel
0	0	0	0	0	AN0
0	0	0	0	1	AN1
0	0	0	1	0	AN2
0	0	0	1	1	AN3
0	0	1	0	0	AN4
0	0	1	0	1	AN5
0	0	1	1	0	AN6

ANS4	ANS3	ANS2	ANS1	ANS0	Start Channel
ANE4	ANE3	ANE2	ANE1	ANE0	Completion Channel
0	0	1	1	1	AN7
0	1	0	0	0	AN8
0	1	0	0	1	AN9
0	1	0	1	0	AN10
0	1	0	1	1	AN11
0	1	1	0	0	AN12
0	1	1	0	1	AN13
0	1	1	1	0	AN14
0	1	1	1	1	AN15
1	0	0	0	0	AN16
1	0	0	0	1	AN17
1	0	0	1	0	AN18
1	0	0	1	1	AN19
1	0	1	0	0	AN20
1	0	1	0	1	AN21
1	0	1	1	0	AN22
1	0	1	1	1	AN23
1	1	0	0	0	AN24
1	1	0	0	1	AN25
1	1	0	1	0	AN26
1	1	0	1	1	AN27
1	1	1	0	0	AN28
1	1	1	0	1	AN29
1	1	1	1	0	AN30
1	1	1	1	1	AN31

These bits are for setting of a start channel and a completion channel for A/D conversion.

- When the same one channel is written to ANS4 to ANS0 and ANE4 to ANE0, conversion is performed only for one channel (Single conversion).
- When the continuous mode or stop mode is set, after the conversion for channels set by these bits group is completed, it returns to the start channel set by ANS4 to ANS0.

- When the set channels are $ANS > ANE$, the conversion is performed from ANS until ch.31 and returning to ch.0 and then it is performed until ANE.
- These bits group is initialized to $ANS="00000"$, $ANE="00000"$ by reset.
Example: When the channel setting is $ANS=ch.6$ $ANE=ch.3$ and in the single mode, the conversion is performed in the order below:
- $ch.6 \rightarrow ch.7 \rightarrow ch.8 \rightarrow \dots \rightarrow ch.31 \rightarrow ch.0 \rightarrow ch.1 \rightarrow ch.2 \rightarrow ch.3$

5. Operation

This section explains the operation of the AD converter.

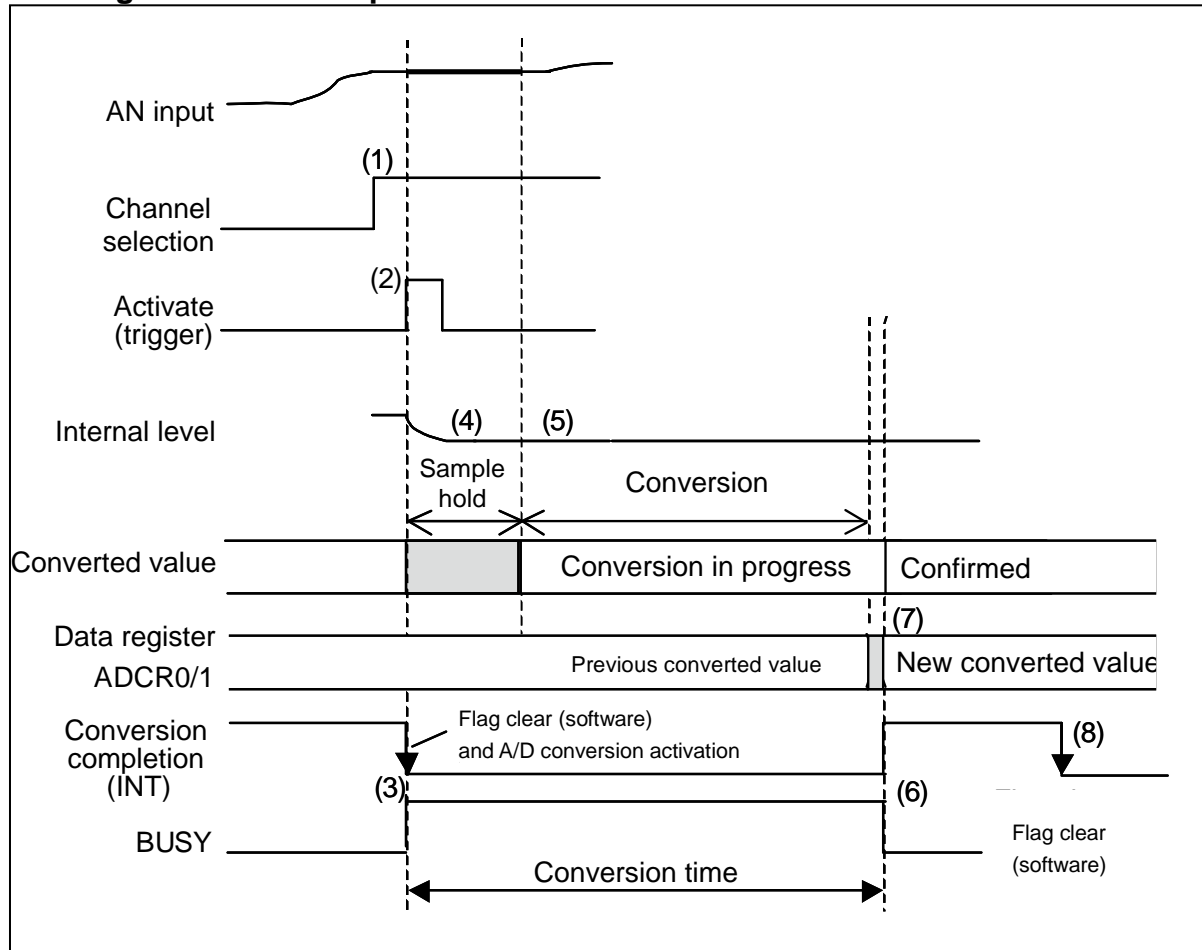
The A/D operation modes are explained below.

- 5.1. Single Conversion Operation
- 5.2. Scan Conversion Operation
- 5.3. Conversion Mode

5.1. Single Conversion Operation

The single conversion operation is explained.

■ Single conversion operation

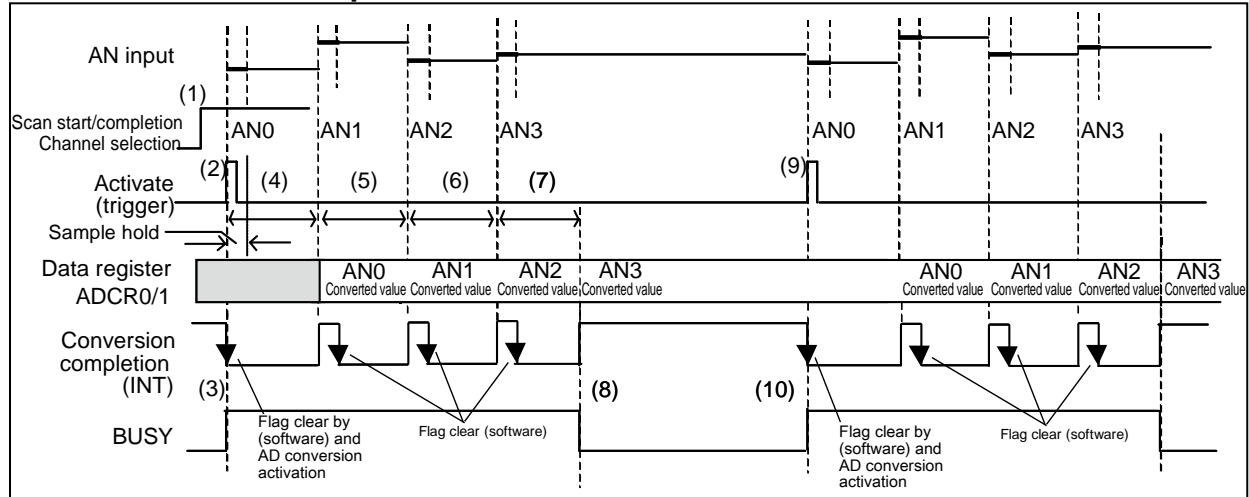


- (1) Channel selection
- (2) A/D conversion activation (Trigger input: Software trigger/reload timer/external trigger)
- (3) INT flag clear, BUSY flag set
- (4) Sample hold
- (5) Conversion
- (6) Conversion completion, INT flag set, BUSY flag clear
- (7) Storage of conversion values to the data register
- (8) INT flag clear by software

5.2. Scan Conversion Operation

The scan conversion operation is explained.

■ Scan conversion operation



- (1) Activation channel selection
- (2) A/D activation (Trigger: Software trigger/reload timer/external trigger)
- (3) INT flag clear, BUSY flag set
- (4) 1. AN0 conversion
2. INT flag set (Storage of AN0 conversion data)
- (5) 1. AN1 conversion
2. AN0 conversion result transfer
3. INT flag clear
4. INT flag set (Storage of AN1 conversion data)
- (6) 1. AN2 conversion
2. AN1 conversion result transfer
3. INT flag clear
4. INT flag set (Storage of AN2 conversion data)
- (7) 1. AN3 conversion
2. AN2 conversion result transfer
3. INT flag clear
4. INT flag set (Storage of AN3 conversion data)
- (8) INT flag set, BUSY flag clear
- (9) Next A/D activation
- (10) INT flag clear, BUSY flag set

5.3. Conversion Mode

The conversion mode is explained.

The A/D converter operates with a successive comparison method, and 10-bit or 8-bit resolution can be selected.

Since this A/D converter has one register (16-bit) for conversion result storage, the conversion data register (ADCR0 and ADCR1) is rewritten every time conversion is completed. Therefore, the A/D converter alone cannot perform continuous conversion process. It is recommended that conversion is performed while conversion data is transferred to a memory with the use of DMA. Operation modes are explained below.

■ Single Conversion Mode

In the single conversion mode, analog input set by ANS bits and ANE bits is converted in sequence. When the conversion is completed at the completion channel set by ANE bit, the operation of A/D converter is stopped. When the start channel and the completion channel is the same one (ANS = ANE), only one of them is converted.

[Example]

- ANS = 00000, ANE = 00011
Start → AN0 → AN1 → AN2 → AN3 → Completion
- ANS = 00010, ANE = 00010
Start → AN2 → Completion

■ Continuous Conversion Mode

In the continuous conversion mode, analog input set by ANS bits and ANE bits is converted in sequence. When the conversion is completed at the completion channel set by ANE bit, the conversion operation is continued returning to analog input of ANS bits. When the start channel and the completion channel is the same one (ANS = ANE), only conversion for one of them is continued.

[Example]

- ANS = 00000, ANE = 00011
Start → AN0 → AN1 → AN2 → AN3 → AN0 - - → Repeat
- ANS = 00010, ANE = 00010
Start → AN2 → AN2 → AN2 - - → Repeat

In the continuous conversion mode the conversion is repeated until "0" is written to the BUSY bit ("0" writing to the BUSY bit → Forced completion). Note that when the forced completion is performed, the conversion that is being processed is stopped halfway (When the forced completion is performed, the previous converted data is stored in the conversion register.).

■ Stop Conversion Mode

In the stop conversion mode, analog input set by ANS bits and ANE bits is converted in sequence, and the conversion operation is paused after each conversion of 1ch. The pause can be released by performing activation again.

When the conversion is completed until the completion channel set by the ANE bit, the conversion operation is continued returning to the analog input by ANS. When the start channel and the completion channel is the same one (ANS = ANE), only one of them is converted.

[Example]

- ANS = 00000, ANE = 00011
Start → AN0 → Stop → Activation → AN1 → Stop → Activation → AN2 → Stop → Activation → AN3 → Stop → Activation → AN0 - - → Repeat
- ANS = 00010, ANE = 00010
Start → AN2 → Stop → Activation → AN2 → Stop → Activation → AN2 - - → Repeat

In this case the activation factors are only ones set by STS1, STS0.

With the use of this mode, the conversion start can be synchronized.

6. Setting

This section explains setting of the AD converter.

Table 6-1 Necessary Configuration to Use A/D - Single Conversion Mode

Configuration	Register to be configured	Method
Mode selection (Single conversion)	A/D control (ADCS0)	See 7.1.
Bit length selection		See 7.2.
Channel selection		See 7.3.
Setting of conversion time	Conversion time setting (ADCT)	See 7.4.
Setting of AN pin to input	Analog input enable (ADER)	See 7.5.
A/D activation trigger selection	A/D control (ADCS1)	See 7.6.
A/D activation trigger occurrence Software trigger → Setting of software trigger bit		See 7.7.
Reload timer → Reload timer rising output		
External trigger → Input trigger to ADTG pin	Input from external	
Check of conversion completion flag	A/D control (ADCS1)	See 7.8.
Conversion value read	Data register (ADCR0, ADCR1)	See 7.9.

Table 6-2 Necessary Configuration to Use A/D - Continuous Conversion Mode

Configuration	Register to be configured	Method
Mode selection (Continuous conversion)	A/D control (ADCS0, ADCS1)	See 7.1.
Bit length selection		See 7.2.
Start channel selection		See 7.3.
Setting of conversion time	Conversion time setting (ADCT)	See 7.4.
Setting of AN pin to input	Analog input enable (ADER)	See 7.5.
A/D activation trigger selection	A/D control (ADCS1)	See 7.6.
A/D activation trigger occurrence Software trigger → Setting of software trigger bit		See 7.7.
Reload timer → Reload timer rising output		
External trigger → Input trigger to ADTG pin	Input from external	
Check of conversion completion flag	A/D control (ADCS1)	See 7.8.
Conversion value read	Data register (ADCR0, ADCR1)	See 7.9.

Table 6-3 Forced Stop of A/D Operation

Configuration	Register to be configured	Method
Forced stop	A/D control (ADCS1)	See 7.10.

Table 6-4 Items Necessary for A/D Interrupt

Configuration	Register to be configured	Method
Setting of A/D interrupt vector and A/D interrupt level	See "CHAPTER : INTERRUPT CONTROL (INTERRUPT CONTROLLER)".	See 7.11.
A/D interrupt factor selection (A/D conversion completion)	A/D control register (ADCS1)	See 7.12.
A/D interrupt setting Interrupt request clear Interrupt request enable		See 7.13

7. Q&A

This section explains Q&A of the A/D converter.

- 7.1. Conversion Mode Type and Setting Method?
- 7.2. How Can I Specify the Bit Length?
- 7.3. How Can I Select Channels?
- 7.4. How Can I Set the Conversion Time?
- 7.5. How Can I Enable the Analog Pin Input?
- 7.6. How Can I Select the A/D Converter Activation Method?
- 7.7. How Can I Activate the A/D Converter?
- 7.8. How Can I Check the Conversion Completion?
- 7.9. How Can I Read the Conversion Value?
- 7.10. How Can I Stop the A/D Conversion Operation Forcibly?
- 7.11. Interrupt-Related Register?
- 7.12. Interrupt Type?
- 7.13. How Can I Enable/Disable/Clear the Interrupt?

7.1. Conversion Mode Type and Setting Method?

The conversion mode type and setting method are shown below.

The conversion includes the following four types:

- Single conversion mode where specified channels are converted for one cycle and terminated (Reactivation enabled during operation)
- Single conversion mode where specified channels are converted for one cycle and terminated (Reactivation disabled during operation)
- Continuous conversion mode where specified channels are converted repeatedly
- Stop conversion mode where conversion is performed for one channel and paused for specified channels

Set by the operation mode setting bits (ADCS0:MD[1:0]).

Operating Mode	Operation mode setting bits (MD[1:0])
Single conversion mode (Reactivation enabled during operation)	Set "00".
Single conversion mode (Reactivation disabled during operation)	Set "01".
Continuous conversion mode	Set "10".
Stop conversion mode	Set "11".

7.2. How Can I Specify the Bit Length?

This section explains how to specify the bit length.

Set the number of storage bits of conversion results (ADCS0:S10).

Operation	Number of Storage Bits of Conversion Results (S10)
To store with 10-bit to the data register	Set "0".
To store with 8-bit to the data register	Set "1".

7.3. How Can I Select Channels?

This section explains how to select channels.

Specify channels to be converted by the A/D start channel setting bits (ADSCH:ANS[4:0]) and the A/D completion channel setting bits (ADECH:ANE[4:0]).

Specify the A/D conversion start channel.

A/D Conversion Start Channel	Channel selection bits (ANS[4:0])
To specify AN0	Set "00000".
To specify AN1	Set "00001".
To specify AN2	Set "00010".
To specify AN3	Set "00011".
To specify AN4	Set "00100".
To specify AN5	Set "00101".
To specify AN6	Set "00110".
To specify AN7	Set "00111".
To specify AN8	Set "01000".
To specify AN9	Set "01001".
To specify AN10	Set "01010".
To specify AN11	Set "01011".
To specify AN12	Set "01100".
To specify AN13	Set "01101".
To specify AN14	Set "01110".
To specify AN15	Set "01111".
To specify AN16	Set "10000".
To specify AN17	Set "10001".
To specify AN18	Set "10010".
To specify AN19	Set "10011".
To specify AN20	Set "10100".
To specify AN21	Set "10101".
To specify AN22	Set "10110".
To specify AN23	Set "10111".
To specify AN24	Set "11000".

A/D Conversion Start Channel	Channel selection bits (ANS[4:0])
To specify AN25	Set "11001".
To specify AN26	Set "11010".
To specify AN27	Set "11011".
To specify AN28	Set "11100".
To specify AN29	Set "11101".
To specify AN30	Set "11110".
To specify AN31	Set "11111".

Specify the A/D conversion completion channel.

A/D Conversion Completion Channel	Channel selection bits (ANE[4:0])
To specify AN0	Set "00000".
To specify AN1	Set "00001".
To specify AN2	Set "00010".
To specify AN3	Set "00011".
To specify AN4	Set "00100".
To specify AN5	Set "00101".
To specify AN6	Set "00110".
To specify AN7	Set "00111".
To specify AN8	Set "01000".
To specify AN9	Set "01001".
To specify AN10	Set "01010".
To specify AN11	Set "01011".
To specify AN12	Set "01100".
To specify AN13	Set "01101".
To specify AN14	Set "01110".
To specify AN15	Set "01111".
To specify AN16	Set "10000".
To specify AN17	Set "10001".
To specify AN18	Set "10010".
To specify AN19	Set "10011".

A/D Conversion Completion Channel	Channel selection bits (ANE[4:0])
To specify AN20	Set "10100".
To specify AN21	Set "10101".
To specify AN22	Set "10110".
To specify AN23	Set "10111".
To specify AN24	Set "11000".
To specify AN25	Set "11001".
To specify AN26	Set "11010".
To specify AN27	Set "11011".
To specify AN28	Set "11100".
To specify AN29	Set "11101".
To specify AN30	Set "11110".
To specify AN31	Set "11111".

7.4. How Can I Set the Conversion Time?

This section explains how to set the conversion time.

Set the conversion time by the conversion time setting register (ADCT).

(Formula 1) Sampling time = ST Setting value \times $1/F_{PCLK}$

(Formula 2) Comparison operation time = CT Setting value $\times 1/F_{PCLK} \times 10 + 4/F_{PCLK}$

(Formula 3) Conversion time (total) = Sampling time + Comparison operation time

Setting Item	Control bit	Recommended Value (F_{PCLK})			Remark
		At 16 MHz	At 24 MHz	At 32 MHz	
To set the sampling time	(ST[9:0])	"0000010110" (1.375 μ s)	"0000100001" (1.375 μ s)	"0000101100" (1.375 μ s)	Set it to 1.2 μ s or more.(For AVCC5<4.5V)
To set the comparison operation time	(CT[5:0])	000011 (2.125 μ s)	000100 (1.833 μ s)	000110 (2,000 μ s)	Set it to 500 μ s or less.

Note:

Set the ST[9:0] setting value for A/D sampling time to be the necessary sampling time or more.

See "4.5 Conversion Time Setting Register : ADCT" for the necessary sampling time.

7.5. How Can I Enable the Analog Pin Input?

This section explains how to enable the analog pin input.

Enable it with the analog input enable register (ADER).

Operation	Control bit	Configuration
To set AN0 pin to input	ADER:ADE0	Set "1".
To set AN1 pin to input	ADER:ADE1	Set "1".
To set AN2 pin to input	ADER:ADE2	Set "1".
To set AN3 pin to input	ADER:ADE3	Set "1".
To set AN4 pin to input	ADER:ADE4	Set "1".
To set AN5 pin to input	ADER:ADE5	Set "1".
To set AN6 pin to input	ADER:ADE6	Set "1".
To set AN7 pin to input	ADER:ADE7	Set "1".
To set AN8 pin to input	ADER:ADE8	Set "1".
To set AN9 pin to input	ADER:ADE9	Set "1".
To set AN10 pin to input	ADER:ADE10	Set "1".
To set AN11 pin to input	ADER:ADE11	Set "1".
To set AN12 pin to input	ADER:ADE12	Set "1".
To set AN13 pin to input	ADER:ADE13	Set "1".
To set AN14 pin to input	ADER:ADE14	Set "1".
To set AN15 pin to input	ADER:ADE15	Set "1".
To set AN16 pin to input	ADER:ADE16	Set "1".
To set AN17 pin to input	ADER:ADE17	Set "1".
To set AN18 pin to input	ADER:ADE18	Set "1".
To set AN19 pin to input	ADER:ADE19	Set "1".
To set AN20 pin to input	ADER:ADE20	Set "1".
To set AN21 pin to input	ADER:ADE21	Set "1".
To set AN22 pin to input	ADER:ADE22	Set "1".
To set AN23 pin to input	ADER:ADE23	Set "1".
To set AN24 pin to input	ADER:ADE24	Set "1".
To set AN25 pin to input	ADER:ADE25	Set "1".
To set AN26 pin to input	ADER:ADE26	Set "1".

Operation	Control bit	Configuration
To set AN27 pin to input	ADER:ADE27	Set "1".
To set AN28 pin to input	ADER:ADE28	Set "1".
To set AN29 pin to input	ADER:ADE29	Set "1".
To set AN30 pin to input	ADER:ADE30	Set "1".
To set AN31 pin to input	ADER:ADE31	Set "1".

7.6. How Can I Select the A/D Converter Activation Method?

This section explains how to select the A/D converter activation method.

The activation triggers have the following three types.

- Software trigger
- Reload timer rising signal
- External trigger input falling signal

Set the activation trigger with the activation factor selection bits (ADCS1:STS[1:0]).

A/D Activation Factor	Activation factor selection bits (STS[1:0])
To specify the software trigger	Set "00".
To specify the external trigger/software trigger	Set "01".
To specify the reload timer/software trigger	Set "10".
To specify the external trigger/reload timer/software trigger	Set "11".

The A/D converter is activated by the factor that comes first among ones selected.

7.7. How Can I Activate the A/D Converter?

This section explains how to activate the A/D converter.

- **Software trigger generation method**

Write into the A/D conversion software trigger bit (ADCS1:STRT) for the software trigger.

Operation	A/D conversion software trigger bit (STRT)
To generate the software trigger	Write "1".

- **Activation method with the reload timer 1**

The setting and activation of the reload timer are required. For details, see "CHAPTER : RELOAD TIMER".

When the reload timer output signal is rising by the reload timer underflow, the activation trigger is generated.

- **Activation method with the external trigger**

Set the external trigger input pin ADTG for the external trigger.

Set the ADTG pin to peripheral input. For setting method, see "CHAPTER : I/O PORTS".

Operation	Configuration
To set ADTG pin to trigger input	Set the pin to peripheral input. See "CHAPTER : I/O PORTS" for the setting method.

7.8. How Can I Check the Conversion Completion?

This section explains how to check the conversion completion.

The methods to check the conversion completion include the following two methods.

- **Check method with the A/D conversion completion/interrupt request flag (ADCS1:INT)**

(INT)	Meaning
When the read value is "0"	No A/D conversion completion interrupt request
When the read value is "1"	A/D conversion completion interrupt request exists

- **Check method with the operation check bit (ADCS1:BUSY)**

(BUSY)	Configuration
When the read value is "0"	A/D conversion completion (being stopped)
When the read value is "1"	A/D conversion is being operated

7.9. How Can I Read the Conversion Value?

This section explains how to read the conversion value.

Conversion values can be read from the data register ADCR0, ADCR1.

ADCR0 stores the lower 8-bit and ADCR1 stores the most significant 2-bit of the conversion result.

Values of the data register are updated every time after one conversion is completed. Normally the final conversion value is stored.

Operation	Register
To read 10-bit conversion value	Read from ADCR1, ADCR0 registers
To read 8-bit conversion value	Read from the ADCR0 register

7.10. How Can I Stop the A/D Conversion Operation Forcibly?

This section explains how to stop the A/D conversion operation forcibly.

Write to the forced stop bit (ADCS1:BUSY).

Operation	Forced stop bit (BUSY)
To stop the A/D conversion operation forcibly	Write "0".

Writing "1" to the forced stop bit (BUSY) has no effect on the A/D operation.

7.11. Interrupt-Related Register?

This section explains the interrupt-related register.

Setting of A/D interrupt vector and A/D interrupt level

The relation of the A/D number, interrupt level, and vector is as the table below:

For the interrupt level and interrupt vector, see "CHAPTER : INTERRUPT (CONTROL INTERRUPT CONTROLLER)".

Interrupt Vector (Default)	Interrupt level setting bits (ICR[4:0])
#48 Address: 0FFF3C _H	Interrupt level register (ICR32) Address: 00460 _H

7.12. Interrupt Type?

This section explains the interrupt type.

The interrupt factor is A/D conversion completion only. There are no bits for selection.

7.13. How Can I Enable/Disable/Clear the Interrupt?

This section explains how to enable/disable/clear the interrupt.

Interrupt request enable bit, interrupt request flag

Set the interrupt request enable bit (ADCS1:INTE) for the interrupt enable setting.

Operation	Interrupt request enable bit (INTE)
To disable the interrupt request	Set "0".
To enable the interrupt request	Set "1".

Write into the interrupt request flag (ADCS1:INT) for the interrupt request clear.

Operation	Interrupt request flag (INT)
To clear the interrupt request	Write "0", or, activate the A/D. (See "7.7 How Can I Activate the A/D Converter?".)

8. Sample Program

This section explains the sample program.

<p>Configuration procedure example 1</p> <p>The example of A/D conversion for the level input by AN0 (single conversion, software trigger) is described below.</p> <p><Initial setting></p> <table border="1"> <thead> <tr> <th>Port</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Port A/D input selection</td> <td>ADERL.AN7-0</td> </tr> </tbody> </table> <p><A/D start/completion channel setting</p> <table border="1"> <thead> <tr> <th>Conversion start channel setting</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ADCSCH</td> <td>.ANS4-0</td> </tr> <tr> <th>Conversion completion channel setting</th> <th>Register name.bit name</th> </tr> <tr> <td>ADECH</td> <td>.ANE4-0</td> </tr> </tbody> </table> <p><A/D start/completion channel setting</p> <table border="1"> <thead> <tr> <th>Conversion time setting</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ADCT</td> <td>.CT5-0</td> </tr> <tr> <td>.ST9-8</td> <td>.ST9-8</td> </tr> <tr> <td>.ST7-0</td> <td>.ST7-0</td> </tr> </tbody> </table> <p><A/D control</p> <table border="1"> <thead> <tr> <th>ANO control</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ADCS1</td> <td>.BUSY</td> </tr> <tr> <td>.INT</td> <td>.INTE</td> </tr> <tr> <td>.PAUS</td> <td>.PAUS</td> </tr> <tr> <td>.STS</td> <td>.STS</td> </tr> <tr> <td>.STRT</td> <td>.STRT</td> </tr> <tr> <td>.Reserved bit</td> <td>.Reserved bit</td> </tr> <tr> <td>.MD[1:0]</td> <td>.MD[1:0]</td> </tr> <tr> <td>.S10</td> <td>.S10</td> </tr> <tr> <td>.ACH4-0</td> <td>.ACH4-0</td> </tr> </tbody> </table> <p><Interrupt relation</p> <table border="1"> <thead> <tr> <th>A/D interrupt level setting</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ICR32</td> <td>ICR32</td> </tr> <tr> <th>I flag setting</th> <th>Register name.bit name</th> </tr> <tr> <td>(CCR)</td> <td>(CCR)</td> </tr> </tbody> </table> <p><A/D activation</p> <p><A/D control</p> <table border="1"> <thead> <tr> <th>A/D interrupt enable</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ADCS1</td> <td>.INT</td> </tr> <tr> <td>.INTE</td> <td>.INTE</td> </tr> <tr> <th>A/D0 software activation</th> <th>Register name.bit name</th> </tr> <tr> <td>ADCS1</td> <td>.BUSY</td> </tr> <tr> <td>.STRT</td> <td>.STRT</td> </tr> </tbody> </table> <p><Interrupt></p> <p><Conversion values read</p> <table border="1"> <thead> <tr> <th>Interrupt disable, interrupt request flag clear</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ADCS1</td> <td>.INT</td> </tr> <tr> <td>.INTE</td> <td>.INTE</td> </tr> <tr> <th>Conversion values read</th> <th>Register name.bit name</th> </tr> <tr> <td>D9 to D0</td> <td>D9 to D0</td> </tr> <tr> <th>Interrupt enable</th> <th>Register name.bit name</th> </tr> <tr> <td>ADCS1</td> <td>.INT</td> </tr> <tr> <td>.INTE</td> <td>.INTE</td> </tr> </tbody> </table> <p><Interrupt vector></p> <p>Setting of the vector table</p> <p><Other></p> <p>(Note)</p> <p>Clock-related setting and setting of "___set_il(value)" are required in advance. See "CHAPTER : CLOCK" and "CHAPTER : INTERRUPT CONTROL (INTERRUPT CONTROLLER)".</p>	Port	Register name.bit name	Port A/D input selection	ADERL.AN7-0	Conversion start channel setting	Register name.bit name	ADCSCH	.ANS4-0	Conversion completion channel setting	Register name.bit name	ADECH	.ANE4-0	Conversion time setting	Register name.bit name	ADCT	.CT5-0	.ST9-8	.ST9-8	.ST7-0	.ST7-0	ANO control	Register name.bit name	ADCS1	.BUSY	.INT	.INTE	.PAUS	.PAUS	.STS	.STS	.STRT	.STRT	.Reserved bit	.Reserved bit	.MD[1:0]	.MD[1:0]	.S10	.S10	.ACH4-0	.ACH4-0	A/D interrupt level setting	Register name.bit name	ICR32	ICR32	I flag setting	Register name.bit name	(CCR)	(CCR)	A/D interrupt enable	Register name.bit name	ADCS1	.INT	.INTE	.INTE	A/D0 software activation	Register name.bit name	ADCS1	.BUSY	.STRT	.STRT	Interrupt disable, interrupt request flag clear	Register name.bit name	ADCS1	.INT	.INTE	.INTE	Conversion values read	Register name.bit name	D9 to D0	D9 to D0	Interrupt enable	Register name.bit name	ADCS1	.INT	.INTE	.INTE	<p>Program example 1</p> <pre> void AD_sample_1(void) { AD_INITIAL(); AD_ch0_start(); } void AD_INITIAL(void) { IO_ADERL = 0x01; /* AN0 only A/D input */ IO_ADSCCH = 0x0000; /* AN0 setting */ /* 00000 */ IO_ADECH = 0x0000; /* AN0 setting */ /* 00000 */ IO_ADCT0 = 0x0816; /* Value is the recommended value (at 16 MHz) */ /* 00010 */ /* 00 */ /* 00010110 */ IO_ADSCS1.hword= 0x8000; /* Setting value: 10000000 00000000 (bit)*/ /* Bit15=1: (No effect)*/ /* Bit14=0: Interrupt request clear */ /* Bit13=0: Interrupt disable */ /* Bit12=0: Flag clear*/ /* Bit11-10=00: Software trigger*/ /* Bit9=0: (No effect)*/ /* Bit8=0: */ /* Bit7-6=00: Single conversion */ /* Bit5=0: 10 bits */ /* Bit4-0=00000: */ IO_ICR[32].bit.ICR = 32; /* Any value */ __EI(); /* Interrupt enable */ } AD_ch0_start() { IO_ADSCS1.hword= 0x2000; /* Bit6=0: AD interrupt flag clear */ /* Bit5=1: AD interrupt enable */ IO_ADSCS1.hword= 0xF200; /* Bit7=1: "1" writing is required.*/ /* Bit1=1: Software activation */ } __interrupt void AD_ch0_int() /* */ { IO_ADSCS1.hword = 0x8000; /* Bit6=0: AD interrupt flag clear */ /* Bit5=0: AD interrupt disable */ [Any storage location] = ADCR1.ADCR0; /* Storage of conversion values */ IO_ADSCS1.hword= 0xA000; /* Bit5=1: AD interrupt enable */ } Interrupt routine specification with the vector table is required. #pragma intvect AD_ch0_int 48 </pre>
Port	Register name.bit name																																																																												
Port A/D input selection	ADERL.AN7-0																																																																												
Conversion start channel setting	Register name.bit name																																																																												
ADCSCH	.ANS4-0																																																																												
Conversion completion channel setting	Register name.bit name																																																																												
ADECH	.ANE4-0																																																																												
Conversion time setting	Register name.bit name																																																																												
ADCT	.CT5-0																																																																												
.ST9-8	.ST9-8																																																																												
.ST7-0	.ST7-0																																																																												
ANO control	Register name.bit name																																																																												
ADCS1	.BUSY																																																																												
.INT	.INTE																																																																												
.PAUS	.PAUS																																																																												
.STS	.STS																																																																												
.STRT	.STRT																																																																												
.Reserved bit	.Reserved bit																																																																												
.MD[1:0]	.MD[1:0]																																																																												
.S10	.S10																																																																												
.ACH4-0	.ACH4-0																																																																												
A/D interrupt level setting	Register name.bit name																																																																												
ICR32	ICR32																																																																												
I flag setting	Register name.bit name																																																																												
(CCR)	(CCR)																																																																												
A/D interrupt enable	Register name.bit name																																																																												
ADCS1	.INT																																																																												
.INTE	.INTE																																																																												
A/D0 software activation	Register name.bit name																																																																												
ADCS1	.BUSY																																																																												
.STRT	.STRT																																																																												
Interrupt disable, interrupt request flag clear	Register name.bit name																																																																												
ADCS1	.INT																																																																												
.INTE	.INTE																																																																												
Conversion values read	Register name.bit name																																																																												
D9 to D0	D9 to D0																																																																												
Interrupt enable	Register name.bit name																																																																												
ADCS1	.INT																																																																												
.INTE	.INTE																																																																												

<p>Configuration procedure example 2</p> <p>A/D conversion is performed for the level input by AN1 to AN3 (Scan conversion, external trigger). (The external trigger (falling) input is required for ADTG.)</p> <p><Initial setting></p> <table border="1"> <thead> <tr> <th>Port</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Port A/D input selection</td> <td>ADERL. AN7-0</td> </tr> <tr> <td>External trigger port setting</td> <td>See "CHAPTER : I/O PORT".</td> </tr> </tbody> </table> <p><A/D start/completion channel setting</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Conversion start channel setting</td> <td>ADSCH .ANS4-0</td> </tr> <tr> <td>Conversion completion channel setting</td> <td>ADECH .ANE4-0</td> </tr> </tbody> </table> <p><A/D start/completion channel setting</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Conversion time setting</td> <td>ADCT .CT5-0 .ST9-8 .ST7-0</td> </tr> </tbody> </table> <p><A/D control</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ANO control</td> <td>ADCS1 .BUSY</td> </tr> <tr> <td>Clearing of interrupt request flag >> Interrupt disable>></td> <td>.INT .INTE</td> </tr> <tr> <td>Activation trigger selection>></td> <td>.PAUS .STS .STRT</td> </tr> <tr> <td>Conversion mode selection>> Bit length selection>></td> <td>.Reserved bit .MD[1:0] .S10 .ACH4-0</td> </tr> </tbody> </table> <p><Interrupt relation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>A/D interrupt level setting</td> <td>ICR32</td> </tr> <tr> <td>I flag setting</td> <td>(CCR)</td> </tr> </tbody> </table> <p><A/D activation</p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>A/D interrupt enable</td> <td>ADCS1 .INT .INTE</td> </tr> </tbody> </table> <p><Interrupt></p> <table border="1"> <thead> <tr> <th>Register name.bit name</th> <th>Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Interrupt disable, interrupt request flag clear</td> <td>ADCS1 .INT .INTE</td> </tr> <tr> <td>Conversion values read</td> <td>D9 to D0</td> </tr> <tr> <td>Interrupt enable</td> <td>ADCS1 .INTE</td> </tr> </tbody> </table> <p><Interrupt vector> Setting of the vector table</p> <p><Other> (Note) Clock-related setting and setting of __set_il(numerical value) are required in advance. See "CHAPTER : CLOCK" and "CHAPTER : INTERRUPT CONTROL (INTERRUPT CONTROLLER)".</p>	Port	Register name.bit name	Port A/D input selection	ADERL. AN7-0	External trigger port setting	See "CHAPTER : I/O PORT".	Register name.bit name	Register name.bit name	Conversion start channel setting	ADSCH .ANS4-0	Conversion completion channel setting	ADECH .ANE4-0	Register name.bit name	Register name.bit name	Conversion time setting	ADCT .CT5-0 .ST9-8 .ST7-0	Register name.bit name	Register name.bit name	ANO control	ADCS1 .BUSY	Clearing of interrupt request flag >> Interrupt disable>>	.INT .INTE	Activation trigger selection>>	.PAUS .STS .STRT	Conversion mode selection>> Bit length selection>>	.Reserved bit .MD[1:0] .S10 .ACH4-0	Register name.bit name	Register name.bit name	A/D interrupt level setting	ICR32	I flag setting	(CCR)	Register name.bit name	Register name.bit name	A/D interrupt enable	ADCS1 .INT .INTE	Register name.bit name	Register name.bit name	Interrupt disable, interrupt request flag clear	ADCS1 .INT .INTE	Conversion values read	D9 to D0	Interrupt enable	ADCS1 .INTE	<p>Program example 2 (Condition: PCLK = 16MHz)</p> <pre> void AD_sample_2(void) { AD_1to3_INITIAL(); AD_ch1to3_start(); } void AD_1to3_INITIAL(void) { IO_ADERL = 0x0E; /* AN1 to AN3 only A/D input */ /* Set the ADTG pin to peripheral input. */ PORT_SETTING_ADTG_IN(); IO_ADSCH = 0x0001; /* AN1 setting */ /* 00001 */ IO_ADECH = 0x0003; /* AN3 setting */ /* 00003 */ IO_ADCT0 = 0x0816; /* Value is the recommended value (at 16 MHz) */ /* 00010 */ /* 00 */ /* 00010110 */ IO_ADSC1.hword= 0x8800; /* Setting value: 10001000 00000000 (bit)*/ /* Bit15=1: (No effect)*/ /* Bit14=0: Interrupt request clear */ /* Bit13=0: Interrupt disable */ /* Bit12=0: Flag clear*/ /* Bit11-10=01: External trigger*/ /* Bit9=0: (No effect)*/ /* Bit8=0: */ /* Bit7-6=00: Single conversion*/ /* Bit5=0: 10 bits */ /* Bit4-0=00000: */ IO_ICR[32].bit.ICR =32; /* Any value */ __EI(); /* Interrupt enable */ } AD_ch01to3_start() { IO_ADSC1.hword= 0xB400; /* Bit6=0: AD interrupt flag clear */ /* Bit5=1: AD interrupt enable */ } __interrupt void AD_ch01to3_int() /* Interrupted after AN3 conversion */ { IO_ADSC1.hword = 0x9400; /* Bit6=0: AD interrupt flag clear */ /* Bit5=0: AD interrupt disable */ [Any storage location] = ADCR1,ADCR0; /* Storage of conversion values */ IO_ADSC1.hword= 0xA400; /* Bit5=1: AD interrupt enable */ } Interrupt routine specification with the vector table is required. #pragma intvect AD_ch01to3_int 48 </pre>
Port	Register name.bit name																																												
Port A/D input selection	ADERL. AN7-0																																												
External trigger port setting	See "CHAPTER : I/O PORT".																																												
Register name.bit name	Register name.bit name																																												
Conversion start channel setting	ADSCH .ANS4-0																																												
Conversion completion channel setting	ADECH .ANE4-0																																												
Register name.bit name	Register name.bit name																																												
Conversion time setting	ADCT .CT5-0 .ST9-8 .ST7-0																																												
Register name.bit name	Register name.bit name																																												
ANO control	ADCS1 .BUSY																																												
Clearing of interrupt request flag >> Interrupt disable>>	.INT .INTE																																												
Activation trigger selection>>	.PAUS .STS .STRT																																												
Conversion mode selection>> Bit length selection>>	.Reserved bit .MD[1:0] .S10 .ACH4-0																																												
Register name.bit name	Register name.bit name																																												
A/D interrupt level setting	ICR32																																												
I flag setting	(CCR)																																												
Register name.bit name	Register name.bit name																																												
A/D interrupt enable	ADCS1 .INT .INTE																																												
Register name.bit name	Register name.bit name																																												
Interrupt disable, interrupt request flag clear	ADCS1 .INT .INTE																																												
Conversion values read	D9 to D0																																												
Interrupt enable	ADCS1 .INTE																																												

<p>Configuration procedure example 3</p> <p>A/D conversion is performed for the level input by AN1 to AN3 (Scan conversion, external trigger, DMA use (Request by an interrupt. DMA channel 0)). (The external trigger (falling) input is required for ADTG.)</p> <p><Initial setting></p> <p>-Port</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Port</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Port A/D input selection</td> <td>ADERL .AN7-0</td> </tr> <tr> <td>External trigger port setting</td> <td>DDR7 .P70</td> </tr> </tbody> </table> <p>-A/D start/completion channel setting</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Conversion start channel setting</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Conversion start channel setting</td> <td>ADSCH .ANS4-0</td> </tr> <tr> <td>Conversion completion channel setting</td> <td>ADECH .ANE4-0</td> </tr> </tbody> </table> <p>-A/D start/completion channel setting</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Conversion time setting</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Conversion time setting</td> <td>ADCT .CT5-0 .ST9-8 .ST7-0</td> </tr> </tbody> </table> <p>-A/D control</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">ANO control</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>ANO control</td> <td>ADCS1 .BUSY</td> </tr> <tr> <td>Clearing of interrupt request flag >> Interrupt disable>></td> <td>.INT .INTE .PAUS</td> </tr> <tr> <td>Activation trigger selection>></td> <td>.STS .STRT</td> </tr> <tr> <td>Conversion mode selection>></td> <td>.Reserved bit</td> </tr> <tr> <td>Bit length selection>></td> <td>.MD[1:0] .S10 .ACH4-0</td> </tr> </tbody> </table> <p>-Interrupt relation</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">A/D interrupt level setting</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>A/D interrupt level setting</td> <td>ICR32</td> </tr> </tbody> </table> <p>-DMA relation</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">Generation and clear of DMA transfer request (Setting of ICSEL is not required.)</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>Generation and clear of DMA transfer request (Setting of ICSEL is not required.)</td> <td>IORR</td> </tr> <tr> <td>DMA channel 0 Setting</td> <td>DCCR</td> </tr> <tr> <td>DMA channel 0 Transfer source</td> <td>DSAR</td> </tr> <tr> <td>DMA channel 0 Transfer destination</td> <td>DDAR</td> </tr> <tr> <td>DMA channel 0 Transfers number</td> <td>DTCR</td> </tr> <tr> <td>DMA channel 0 Status clear</td> <td>DCSR</td> </tr> <tr> <td>DMA enable</td> <td>DMACR.DME</td> </tr> </tbody> </table> <p><A/D activation></p> <p>-A/D control</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 70%;">A/D interrupt enable</th> <th style="width: 30%;">Register name.bit name</th> </tr> </thead> <tbody> <tr> <td>A/D interrupt enable</td> <td>ADCS1 .INT .INTE</td> </tr> </tbody> </table>	Port	Register name.bit name	Port A/D input selection	ADERL .AN7-0	External trigger port setting	DDR7 .P70	Conversion start channel setting	Register name.bit name	Conversion start channel setting	ADSCH .ANS4-0	Conversion completion channel setting	ADECH .ANE4-0	Conversion time setting	Register name.bit name	Conversion time setting	ADCT .CT5-0 .ST9-8 .ST7-0	ANO control	Register name.bit name	ANO control	ADCS1 .BUSY	Clearing of interrupt request flag >> Interrupt disable>>	.INT .INTE .PAUS	Activation trigger selection>>	.STS .STRT	Conversion mode selection>>	.Reserved bit	Bit length selection>>	.MD[1:0] .S10 .ACH4-0	A/D interrupt level setting	Register name.bit name	A/D interrupt level setting	ICR32	Generation and clear of DMA transfer request (Setting of ICSEL is not required.)	Register name.bit name	Generation and clear of DMA transfer request (Setting of ICSEL is not required.)	IORR	DMA channel 0 Setting	DCCR	DMA channel 0 Transfer source	DSAR	DMA channel 0 Transfer destination	DDAR	DMA channel 0 Transfers number	DTCR	DMA channel 0 Status clear	DCSR	DMA enable	DMACR.DME	A/D interrupt enable	Register name.bit name	A/D interrupt enable	ADCS1 .INT .INTE	<p>Program example 3 (Condition: PCLK = 16MHz)</p> <pre> void AD_sample_3(void) { AD_1to3_INITIAL(); DMA_Setting(); AD_ch1to3_start(); } void AD_1to3_INITIAL(void) { IO_ADERL = 0x0E; /* AN1 to AN3 only A/D input */ IO_PORT1.IO_DDR7.bit.P70 = 0; /* DDR7.P70 set to input */ IO_ADSCH = 0x0001; /* AN1 setting */ /* 00001 */ IO_ADECH = 0x0003; /* AN3 setting */ /* 00011 */ IO_ADCT0 = 0x0816; /* Value is the recommended value (at 16 MHz) */ /* 000010 */ /* 00 */ /* 00010110 */ IO_ADCS1.hword= 0x8400; /* Setting value: 10001000 00000000 (bit)*/ /* Bit15=1: (No effect)*/ /* Bit14=0: Interrupt request clear */ /* Bit13=0: Interrupt disable */ /* Bit12=0: Flag clear*/ /* Bit11-10=01: External trigger*/ /* Bit9=0: (No effect)*/ /* Bit8=0: */ /* Bit7-6=00: Single conversion */ /* Bit5=0: 10 bits */ /* Bit4-0=00000: */ IO_ICR[32].bit.ICR = 31; /* Any value */ } void DMA_Setting() { IO_DMA0_DCCR.word= 0x00000000 /* Channel 0 disable IO_DMA0_DCSR.hword= 0x0000 /* Channel 0 status clear IO_DMA0_DSAR.word= /* Transferred from the ADC data register &IO_ADCR1.hword; /* IO_DMA0_DDAR.word= (any); /* Buffer in SRAM(FIFO with software) IO_DMA0_DTCR.hword= 0x0100; /* 256 maximum IO_DMAREQCLR_IORR0.byte= /* IO transfer request register ((0x30 - 0x10) + 0x40); /* Vector number #0x30, IOE bit set IO_DMA0_DCCR.word= 0x8010B010; /* Channel 0 enable, request by an interrupt, /* Block transfer, transfer source address fixed, ST = 1 /* Transfer destination address increment /* 1 block = 2 bytes X once IO_DMACR.word= 0x80000000 /* DMA enable } AD_ch01to3_start() { IO_ADCS1.hword= 0xB400; /* Bit6=0: AD interrupt flag clear */ /* Bit5=1: AD interrupt enable */ } </pre>
Port	Register name.bit name																																																				
Port A/D input selection	ADERL .AN7-0																																																				
External trigger port setting	DDR7 .P70																																																				
Conversion start channel setting	Register name.bit name																																																				
Conversion start channel setting	ADSCH .ANS4-0																																																				
Conversion completion channel setting	ADECH .ANE4-0																																																				
Conversion time setting	Register name.bit name																																																				
Conversion time setting	ADCT .CT5-0 .ST9-8 .ST7-0																																																				
ANO control	Register name.bit name																																																				
ANO control	ADCS1 .BUSY																																																				
Clearing of interrupt request flag >> Interrupt disable>>	.INT .INTE .PAUS																																																				
Activation trigger selection>>	.STS .STRT																																																				
Conversion mode selection>>	.Reserved bit																																																				
Bit length selection>>	.MD[1:0] .S10 .ACH4-0																																																				
A/D interrupt level setting	Register name.bit name																																																				
A/D interrupt level setting	ICR32																																																				
Generation and clear of DMA transfer request (Setting of ICSEL is not required.)	Register name.bit name																																																				
Generation and clear of DMA transfer request (Setting of ICSEL is not required.)	IORR																																																				
DMA channel 0 Setting	DCCR																																																				
DMA channel 0 Transfer source	DSAR																																																				
DMA channel 0 Transfer destination	DDAR																																																				
DMA channel 0 Transfers number	DTCR																																																				
DMA channel 0 Status clear	DCSR																																																				
DMA enable	DMACR.DME																																																				
A/D interrupt enable	Register name.bit name																																																				
A/D interrupt enable	ADCS1 .INT .INTE																																																				

9. Notes

This section explains notes of the A/D converter.

Precautions when using the A/D converter are described.

● Power-on sequence

The A/D converter power (AVCC5, AVRH5)-on and voltage application to analog input must be performed after MCU power (VCC5) is turned on.

$VCC5 \geq AVCC5 \geq AVRH5$

$AVCC5 \geq AN$ (Analog applied voltage) $\geq VSS$

Observe above.

For the input impedance of analog input pins, the A/D converter includes a sample hold circuit, and takes voltage of the analog input pin in a capacitor for sample hold after A/D conversion activation. Therefore, if the output impedance of the analog input external circuit is high, the analog input voltage might not be stabilized during the analog input sampling period. Thus, make the output impedance of the external circuit low enough.

If the output impedance of the external circuit cannot be made low, extend the sampling time enough.

As $|AVRH5-AVSS|$ gets smaller, an error gets larger relatively.

10. Term Definition for A/D Converter

This section explains the term definition for the A/D converter.

- **Resolution**

Analog change identifiable by an A/D converter

- **Linearity error**

Deviation between the line that connect the following transition points and the actual conversion characteristics:

The zero transition point (00 0000 0000 ↔ 00 0000 0001) and;

The full scale transition point (11 1111 1110 ↔ 11 1111 1111)

- **Differential linearity error**

Deviation from the ideal value of input voltage necessary for 1LSB change of output code

$$1\text{LSB} = \frac{V_{\text{FST}} - V_{\text{OT}}}{1022} \quad [\text{V}]$$

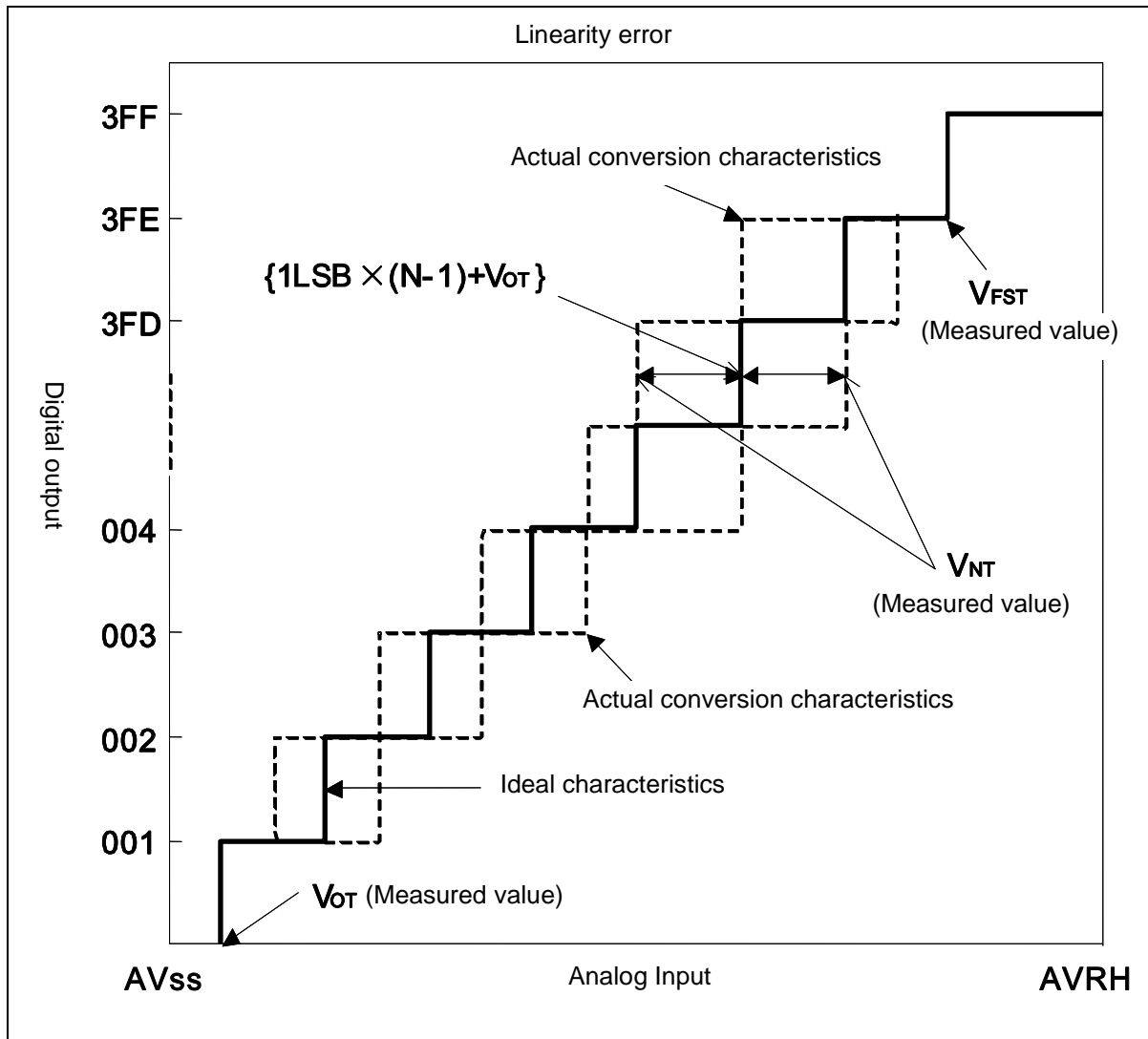
V_{OT} : Voltage for digital output to transit from (000)_H to (001)_H

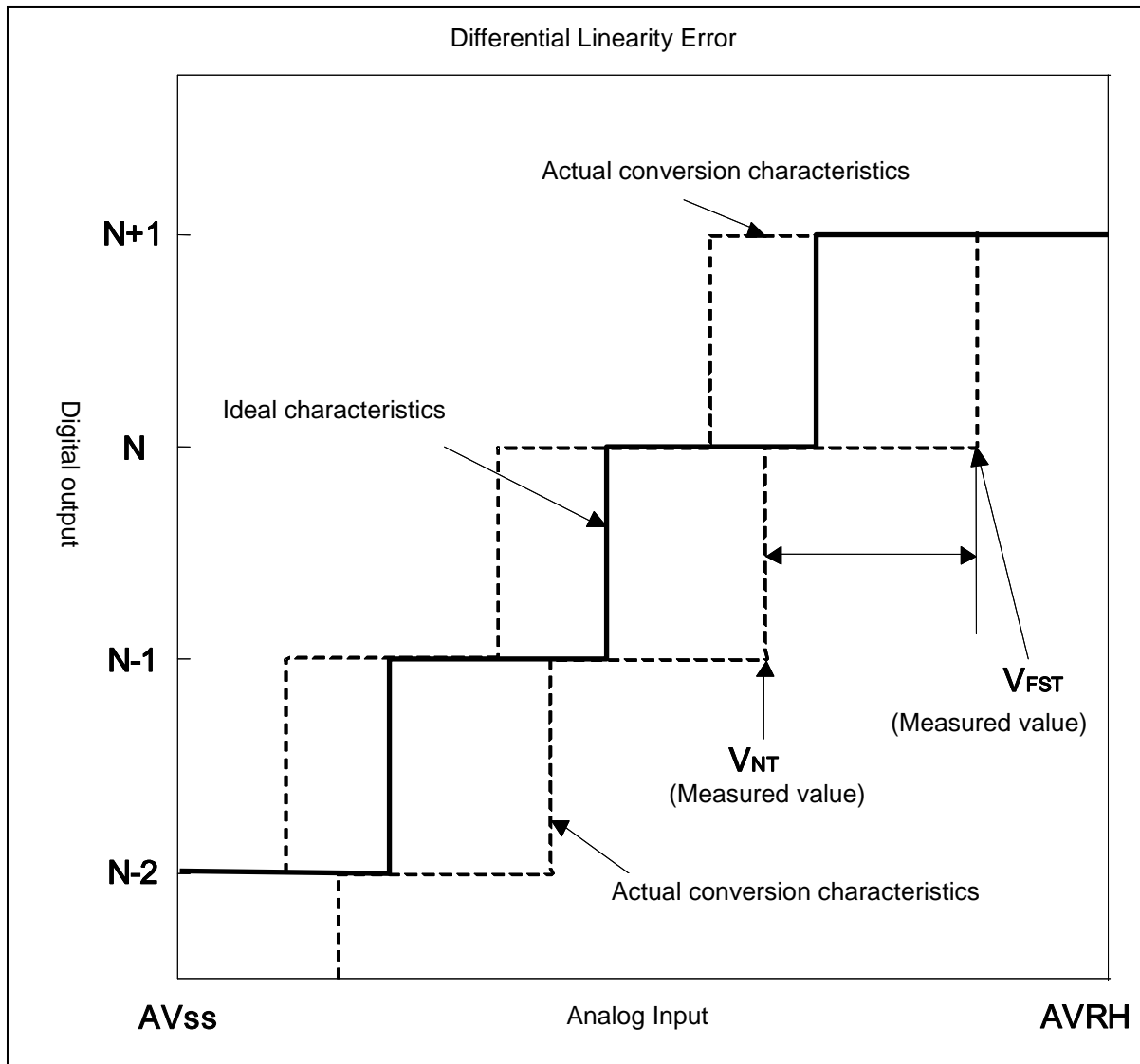
V_{FST} : Voltage for digital output to transit from (3FE)_H to (3FF)_H

$$\text{Linearity error of digital output N} = \frac{V_{\text{NT}} - \{1\text{LSB} \times (\text{N}-1) + V_{\text{OT}}\}}{1\text{LSB}} \quad [\text{LSB}]$$

$$\text{Differential linearity error of digital output N} = \frac{V_{(\text{N}+1)\text{T}} - V_{\text{NT}}}{1\text{LSB}} - 1 \quad [\text{LSB}]$$

V_{NT} : Voltage for digital output to transit from (N+1) to N





● **Total error**

Difference between an actual value and theoretical value, and an error including a zero transition error/full scale transition error/linearity error.

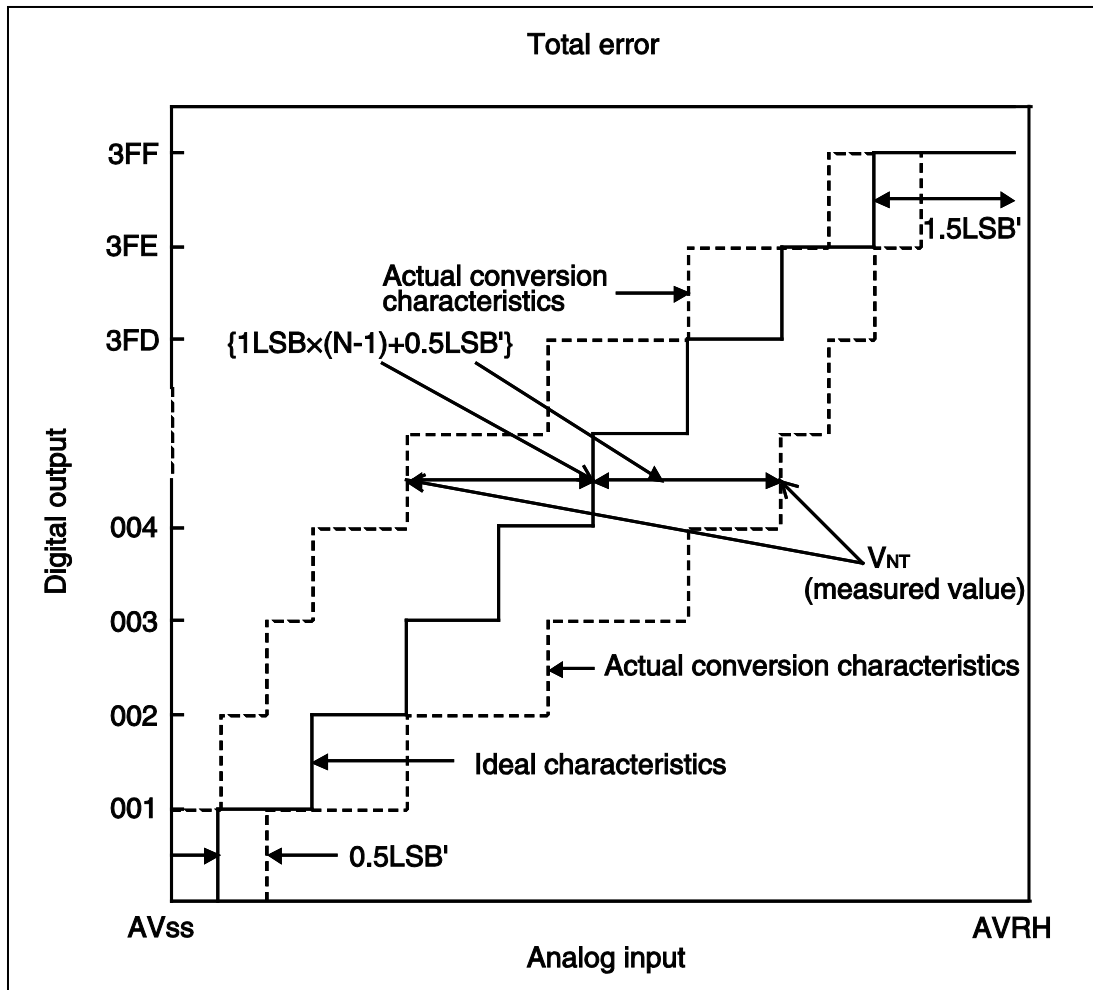
$$1\text{LSB}' \text{ (Ideal value)} = \frac{\text{AVRH5} - \text{AVSS5}}{1024} \quad [\text{V}]$$

$$V_{\text{OT}}' \text{ (Ideal value)} = \text{AVSS5} + 0.5\text{LSB}' \quad [\text{V}]$$

$$V_{\text{FST}}' \text{ (Ideal value)} = \text{AVRH5} - 1.5\text{LSB}' \quad [\text{V}]$$

$$\text{Total error of digital output } N = \frac{V_{\text{NT}} - \{1\text{LSB}' \times (N - 1) + 0.5\text{LSB}'\}}{1\text{LSB}'}$$

V_{NT} : Voltage for digital output to transit from (N + 1) to N



CHAPTER : FLASH MEMORY

This chapter explains the flash memory.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains an overview of the flash memory.

A memory size of the flash memory built in this series is

576Kbytes (512K+64Kbytes) : MB91F591, MB91F592, MB91F596, MB91F597

1088Kbytes (1024K+64Kbytes): MB91F594, MB91F599.

Error correction codes (ECC) are attached.

2. Features

This section explains features of the flash memory.

● Usable capacity:

- MB91F591 : 576Kbytes (large sectors 128K × 4bytes + small sectors 16K × 4bytes)
- MB91F592 : 576Kbytes (large sectors 128K × 4bytes + small sectors 16K × 4bytes)
- MB91F594 : 1088Kbytes (large sectors 128K × 8bytes + small sectors 16K × 4bytes)
- MB91F596 : 576Kbytes (large sectors 128K × 4bytes + small sectors 16K × 4bytes)
- MB91F597 : 576Kbytes (large sectors 128K × 4bytes + small sectors 16K × 4bytes)
- MB91F599 : 1088Kbytes (large sectors 128K × 8bytes + small sectors 16K × 4 bytes)

Since this series has ECC code storage, there are 6 bits of built-in flash memory for every 4 bytes described above.

* The large capacity sector consists of 64Kbytes in size and the small capacity sector consists of 8Kbytes in size. Since two sectors appear alternately when a contiguous area is used, the large capacity sector is 128Kbytes in size and the small capacity sector is 16Kbytes in size.

● High speed operation :

- Reading at the word (32-bit) unit can be performed in 1 cycle at 80MHz.
- Reading at the word (32-bit) unit can be performed in 2 cycles at 128MHz.

● Write from external :

- Possible from ROM writer

● Operation mode :

1. CPU-ROM mode
(CPU / DMA accesses the flash memory. Read-only)
2. CPU programming mode
(CPU accesses the flash memory. Read/Write/Erase)
3. Flash memory mode (flash memory accessible from external)

● Can be read, written, or erased (automatic algorithm*) by CPU

● Can be read, written, or erased (automatic algorithm*) by ROM writer

● Security function

- In order to prevent the content of flash memory from being read by a third party, when security is on, operation from external source after instruction fetch and writing/erasing other than chip erase are suppressed.
- After password authentication when using the on chip debugger (OCD), this can be read externally using the OCD even when security is on.

● Error correction code (ECC) security function

- There is an error correction code (ECC) function that corrects errors of up to one bit in each word. (A function for detecting 2-bit errors is not provided.) Errors are automatically corrected during read. Furthermore, ECC codes are automatically added when writing to flash memory. Because there is no read cycle penalty due to error correction, no consideration needs to be given to error correction penalties during software development.

*: Automatic algorithm = Embedded Algorithm

3. Configuration

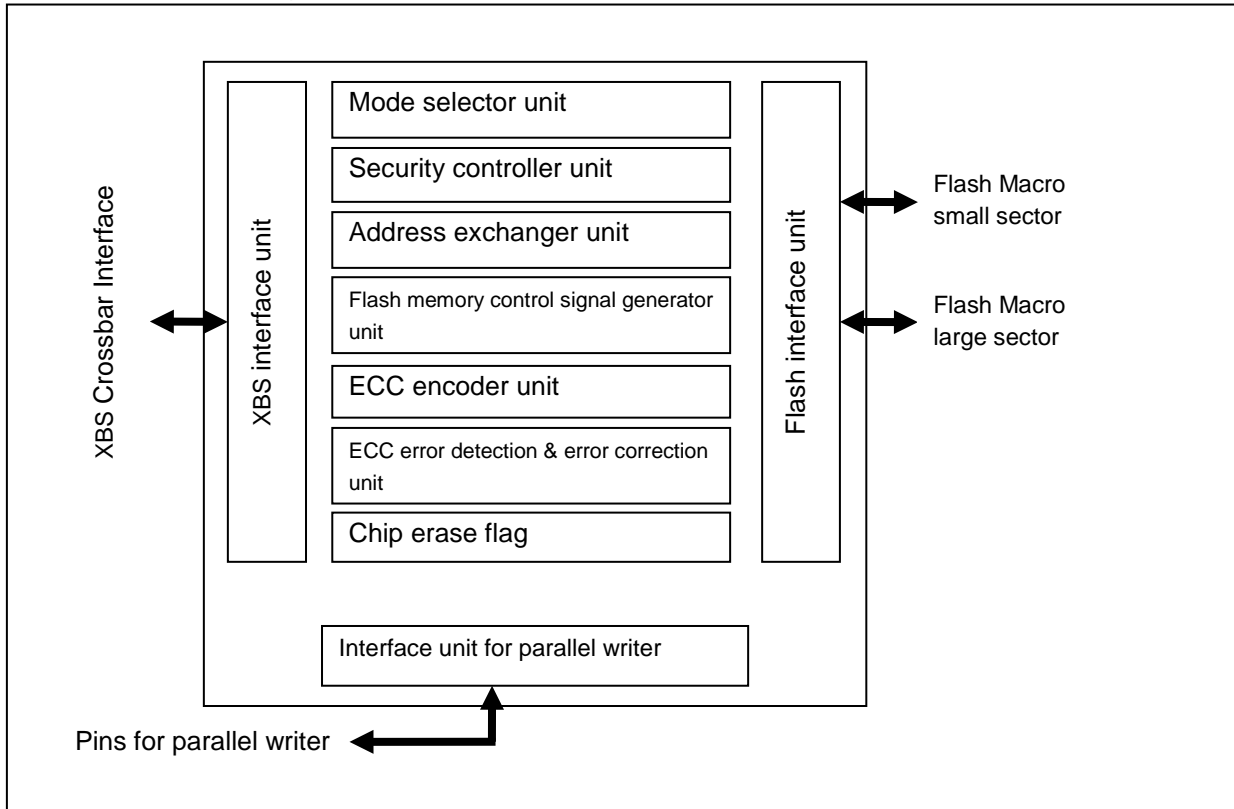
This section explains the configuration of the flash memory.

- 3.1 Block Diagram
- 3.2 Sector Configuration Diagram
- 3.3 Sector Number and Flash Macro Number Correspondence Chart

3.1. Block Diagram

The block diagram of the flash memory is shown below.

Figure 3-1 Block Diagram (1024KB/512KB+64KB products)



3.2. Sector Configuration Diagram

The sector configuration diagram of the flash memory is shown below.

Figure 3-2 Sector Configuration Diagram (1024KB+64KB)

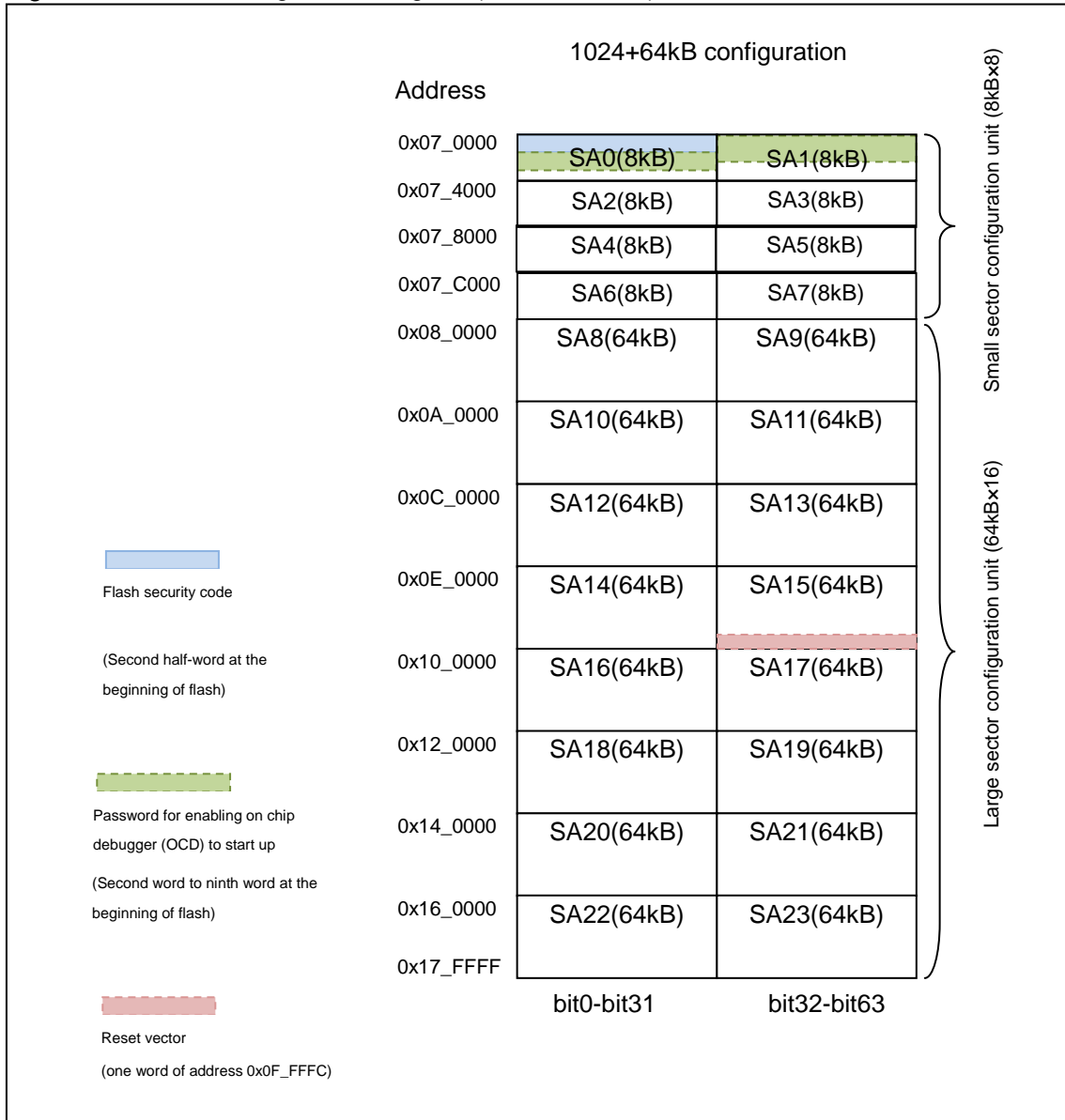
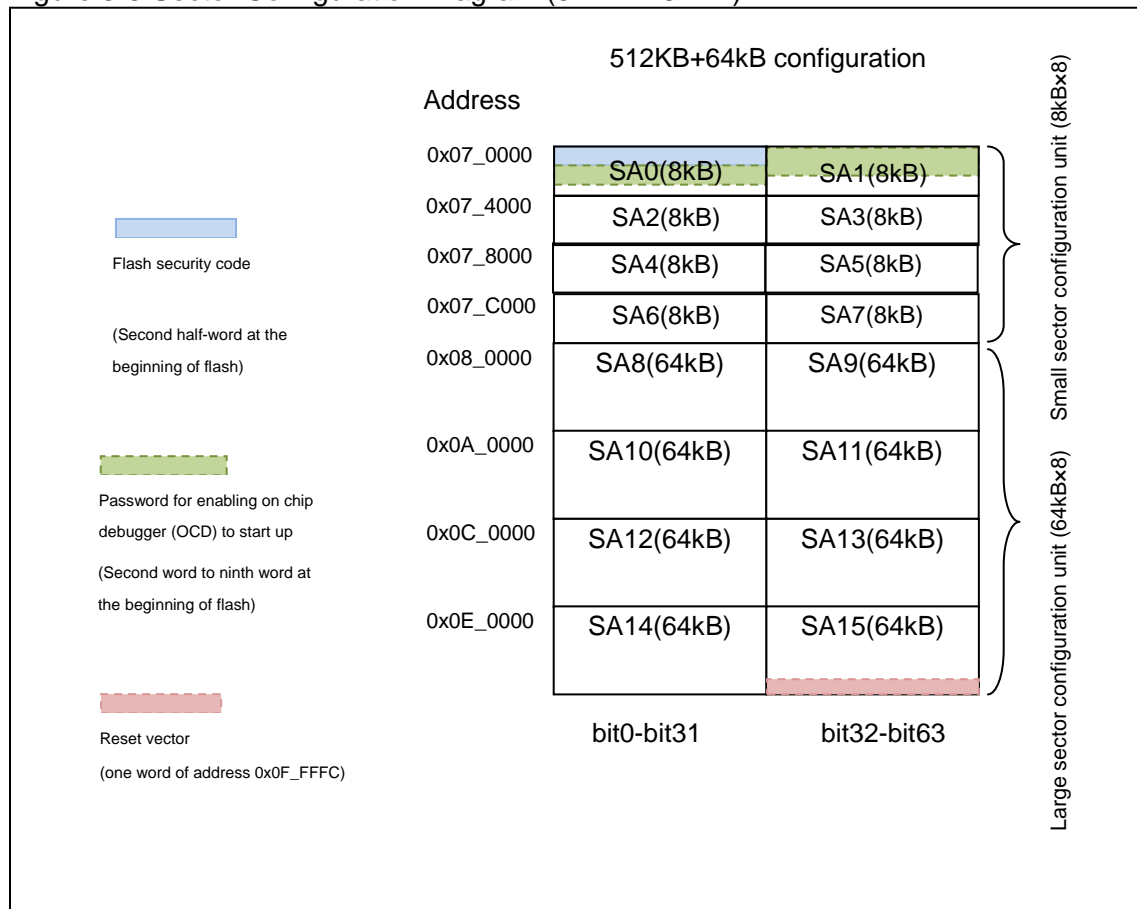


Figure 3-3 Sector Configuration Diagram (512KB+64KB)



Notes:

- The FixedVector function returns the start address of flash memory + 0x0024 instead of the value written in address 0x0F_FFFC as the reset vector. For details, see "CHAPTER : FixedVector FUNCTION"
- As for a password setting for enabling on chip debugger (OCD) to start, see "CHAPTER : ON CHIP DEBUGGER (OCD)". If it is unnecessary to use the security function for on chip debugger (OCD), do not write anything to the area and keep the default state just after the flash erase (all bits=1).

3.3. Sector Number and Flash Macro Number Correspondence Chart

A sector configuration of the flash memory is shown below.

Table 3-1 Sector number table (1024KB/512KB+64KB)

Sector number	Address	Sector size	Remark
SA0	0x07_0000 to 0x07_3FFB (Lower 32 bits)	8KB	Flash security code area (0x07_0002 to 0x07_0003) Password area for enabling on chip debugger (OCD) startup (0x07_0008 to 0x07_000B, 0x07_0010 to 0x07_0013, 0x07_0018 to 0x07_001B, 0x07_0020 to 0x07_0023)
SA1	0x07_0004 to 0x07_3FFF (Upper 32 bits)	8KB	Password area for enabling on chip debugger (OCD) startup (0x07_0004 to 0x07_0007, 0x07_000C to 0x07_000F, 0x07_0014 to 0x07_0017, 0x07_001C to 0x07_001F)
SA2	0x07_4000 to 0x07_7FFB (Lower 32 bits)	8KB	
SA3	0x07_4004 to 0x07_7FFF (Upper 32 bits)	8KB	
SA4	0x07_8000 to 0x07_BFFB (Lower 32 bits)	8KB	
SA5	0x07_8004 to 0x07_BFFF (Upper 32 bits)	8KB	
SA6	0x07_C000 to 0x07_FFFB (Lower 32 bits)	8KB	
SA7	0x07_C004 to 0x07_FFFF (Upper 32 bits)	8KB	
SA8	0x08_0000 to 0x09_FFFB (Lower 32 bits)	64KB	
SA9	0x08_0004 to 0x09_FFFF (Upper 32 bits)	64KB	
SA10	0x0A_0000 to 0x0B_FFFB (Lower 32 bits)	64KB	
SA11	0x0A_0004 to 0x0B_FFFF (Upper 32 bits)	64KB	
SA12	0x0C_0000 to 0x0D_FFFB (Lower 32 bits)	64KB	
SA13	0x0C_0004 to 0x0D_FFFF (Upper 32 bits)	64KB	
SA14	0x0E_0000 to 0x0F_FFFB (Lower 32 bits)	64KB	

Sector number	Address	Sector size	Remark
SA15	0x0E_0004 to 0x0F_FFFF (Upper 32 bits)	64KB	Reset vector position (0x0F_FFFC to 0x0F_FFFF)
SA16	0x10_0000 to 0x11_FFFB (Lower 32 bits)	64KB	
SA17	0x10_0004 to 0x11_FFFF (Upper 32 bits)	64KB	
SA18	0x12_0000 to 0x13_FFFB (Lower 32 bits)	64KB	
SA19	0x12_0004 to 0x13_FFFF (Upper 32 bits)	64KB	
SA20	0x14_0000 to 0x15_FFFB (Lower 32 bits)	64KB	
SA21	0x14_0004 to 0x15_FFFF (Upper 32 bits)	64KB	
SA22	0x16_0000 to 0x17_FFFB (Lower 32 bits)	64KB	
SA23	0x16_0004 to 0x17_FFFF (Upper 32 bits)	64KB	

4. Registers

This section explains registers of the flash memory.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0840	FCTL		Reserved	FSTR	Flash control register Flash status register
0x2308	FLIFCTL	Reserved	FLIFFER1	FLIFFER2	Flash interface control register Flash interface feature extension register 1 Flash interface feature extension register 2

4.1. Flash Control Register : FCTLR (Flash ConTrol Register)

The bit configuration of the flash control register is shown below.

This register configures the access control to flash.

■ FCTLR : Address 0840_H (Access : Half-word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	FWE	Reserved		FSZ[1:0]		FAW[1:0]	
Initial value	1	0	-	-	1	0	0	0
Attribute	R1,WX	R/W	RX,W0	RX,W0	R/W	R/W	R/W	R/W
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	FDSBL	Reserved		RDYF	Reserved			
Initial value	0	-	-	0	-	-	-	-
Attribute	R/W	RX,W0	RX,W0	R/W	RX,W0	RX,W0	RX,W0	RX,W0

[bit15] Reserved

This bit is reserved. This bit always reads out as "1". Writing has no effect on the operation.

[bit14] FWE (Flash Write Enable) : Flash Write Enable

It is the write enable bit to flash. Setting this bit configures CPU programming mode. Use the FSTR:FRDY bit to check whether or not writing is enabled.

If this bit is set, the ECC error detection and data correcting function will be disabled for data fetching to the flash memory.

FWE	Description
0	Flash write disabled (Initial value)
1	Flash write enabled

Note:

When writing to FLASH, instruction fetch from FLASH is disabled.

[bit13, bit12] Reserved

These bits are reserved. The read value is undefined. When writing, always write "0" to these bits.

[bit11, bit10] FSZ[1:0] (Flash write access SiZe) : Flash write access size setting

The FLASH write access size at CPU mode is specified. Be sure to write in the specified bit count of the access width. These two bits, bit11 and bit12, do not influence the reading access size. 32-bit Read is done to the FLASH macro whenever it is read. When the wait cycle is inserted by the FAW bit, it becomes 64-bit read access.

FSZ[1:0]	Description
00	8-bit
01/10/11	16-bit

[bit9, bit8] FAW[1:0] (FLASH Access Wait) : FLASH access / wait setting

The wait cycle to the FLASH access at CPU mode is set. Because the reading time of the flash memory is 12.5ns, when it accesses the flash memory at 80MHz or more, the access without waiting is impossible. It is indispensable to insert wait with these bits. Please set it to FAW=1(1 wait) when you access it at 80MHz or more.

Please set these bits before making the clock high-speed when you insert the wait cycle by FAW. Moreover, please set these bits after setting the clock low-speed when you delete the wait cycle.

FAW[1:0]	Description
00	0 cycle (Initial value)
01	1cycle
10/11	Setting is prohibited

Note:

When 1 wait cycle is set by these bits, the wild register function cannot be used. Please make the core operation speed to 80MHz or less, and set value of the FAW bits to 2'b00(0cycle) when you use the wild register function.

[bit7] FDSBL (Flash DiSaBLE) : Flash Disable directive

This bit configures the Flash access disabled state (both reads and writes).

FDSBL	Description
0	Flash access Enable (Initial value)
1	Flash access Disable

[bit6, bit5] Reserved

Reserved bits. The read value is undefined. When writing, always write "0" to these bits.

[bit4] RDYF (ReaDY Flag) : RDY negating instruction when branch is accessed

The wait cycle insertion when the branch is access is directed. When the branch is accessed, the wait cycle is inserted when this bit is set to "1". The purpose of this is to match the processing cycle when branching. When the branch access is generated, the control at the wait cycle is made by an internal state of FLASH I/F when this bit is "0". If the cycle time is not necessary to be secured when the branch access is accepted, the wait cycle is not inserted. When it is necessary to secure the cycle time, the wait cycle is inserted.

RDYF	Description
0	It depends on the state of FLASH I/F (Initial value)
1	Wait cycle insert

[bit3 to bit0] Reserved

These bits are reserved. The read value is undefined. When writing, always write "0" to these bits.

4.2. Flash Status Register : FSTR (Flash Status Register)

The bit configuration of the flash status register is shown below.

This register indicates the flash state.

■ FSTR : Address 0843_H (Access : Byte)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					FECCERR	FHANG	FRDY
Initial value	-	-	-	-	-	0	0	1
Attribute	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	R,W	R,WX	R,WX

[bit7 to bit3] Reserved

These bits are reserved. The read value is undefined. Writing has no effect on the operation.

[bit2] FECCERR (Flash ECC Error coRRection) : data read ECC correction occurred

This bit is set if an ECC error correction occurs while reading flash memory other than CPU instruction read. This bit is cleared by writing "0".

FECCERR	Read	Write
0	An error correction by ECC has not occurred during data read (initial value)	Clears this bit
1	ECC error correction occurred during data read	No effect

If there are errors in 2 bits or more in a single word, the read value of this bit is undefined.

When reading a CPU instruction, this bit is not set even if an ECC error correction occurs.

When both an ECC error and "0" writing occur simultaneously, the "0" writing will take priority.

[bit1] FHANG (Flash HANG) : Flash HANG state

This bit indicates the flash memory HANG state.

FHANG	Description
0	Normal state
1	HANGUP state

If there is a timing overrun (See "[bit5] TLOV: (Timing Limit Elapsed Flag Bit)), the flash memory will go into the HANG state. If this bit becomes "1", issue a reset command (See "5.3.1. Command Sequence").

The correct value might not be read out immediately after a command of automatic algorithm has been issued. In that case, ignore the first read value of this bit after the command issuance.

[bit0] FRDY (Flash ReaDY) : Flash write enable

This bit indicates whether the flash memory write/erase operation by automatic algorithm is currently running or finished. Flash memory data cannot be written or erased while the operation is in progress.

FRDY	Description
0	Operation in progress (write/erase disabled, read status enabled)
1	Operation finished (write/erase enabled, read enabled)

The correct value might not be read out immediately after a command of automatic algorithm has been issued. Therefore, ignore the first read value of this bit after the command issuance.

4.3. Flash Interface Control Register : FLIFCTLR(Flash I/F Control Register)

The bit configuration of the flash interface control register is shown below.

This register controls flash I/F. This register is shared among program flash and WorkFlash.

■ **FLIFCTLR : Address 2308_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			DFWDSBL	Reserved		ECCDSBL1	ECCDSBL0
Initial value	-	-	-	0	-	0	0	0
Attribute	RX,WX	RX,WX	RX,WX	R/W	RX,WX	R/W0	R/W	R/W

[bit7 to bit5] Reserved

These bits are reserved bits. The read value is undefined. Writing has no effect on the operation.

[bit4] DFWDSBL (Data Fetch Wait cycle Disable) : Data fetch wait cycle disable

If this bit is set to "1", the wait cycle inserted when setting wait at data fetch is disabled. However, you cannot disable the wait cycle to guarantee cycle time.

DFWDSBL	Description
0	Wait cycle enabled (Initial value)
1	Wait cycle disabled

[bit3] Reserved

This bit is reserved. The read value is undefined. Writing has no effect on the operation.

[bit2] Reserved

This bit is reserved. When writing, always write "0" to this bit.

[bit1] ECCDSBL1 (ECC Disable1) : ECC function disable 1

This bit sets the ECC function enabled/disabled while the CPU is accessing the WorkFlash memory in order to write or fetch data.

ECCDSBL1	Description
0	ECC function enabled (Initial value)
1	ECC function disabled

[bit0] ECCDSBL0 (ECC Disable0) : ECC function disable 0

This bit sets the ECC function enabled/disabled while the CPU is accessing the program flash memory in order to write or fetch data.

ECCDSBL0	Description
0	ECC function enabled (Initial value)
1	ECC function disabled

4.4. Flash I/F Feature Extension Register 1: FLIFFER1

The bit configuration of the flash I/F feature extension register 1 is shown below.

This register is the spare register. If the register is written, please write 0xFF.

■ FLIFFER1: Address 230A_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W1	R/W1	R/W1	R/W1	R/W1	R/W1	R/W1	R/W1

[bit7 to bit0] Reserved

These bits are reserved. Always write "0xFF" to these bits.

4.5. Flash I/F Feature Extension Register 2: FLIFFER2

The bit configuration of the flash I/F feature extension register 2 is shown below.

This register is the spare register. If the register is written, please write 0xFF.

■ FLIFFER2: Address 230B_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	1	1	1	1	1	1	1	1
Attribute	R/W1	R/W1	R/W1	R/W1	R/W1	R/W1	R/W1	R/W1

[bit7 to bit0] Reserved

These bits are reserved. Always write "0xFF" to these bits.

5. Operation

This section explains operations of the flash memory.

- 5.1. Access Mode Setting
- 5.2. Programming Flash Memory by CPU
- 5.3. Automatic Algorithm
- 5.4. Reset Command
- 5.5. Write Command
- 5.6. Chip Erase Command
- 5.7. Sector Erase Command
- 5.8. Sector Erase Suspend Command
- 5.9. Security Function
- 5.10. Notes on Using Flash Memory

5.1. Access Mode Setting

The access mode setting is shown below.

The flash memory in this series has the following three modes. The methods for configuring modes (1) and (2) are explained in this section. See the instruction manual of the ROM writer you are using for details on (3).

- (1) CPU-ROM mode
(CPU accesses flash memory. For only read, Byte/Half-word/Word access)
- (2) CPU programming mode
(CPU accesses flash memory. For reading and writing, only Half-word access)
- (3) Flash memory mode
(Access to flash memory from external is enabled.)

5.1.1. Configuring CPU-ROM Mode

Configuring CPU-ROM mode is shown below.

When the FWE bit of the flash control register (FCTLR) is "0", it is CPU-ROM mode. When the FRDY bit of the flash status register (FSTR) is "1", read from the flash memory is enabled in this mode. In the mode, write to the flash memory is disabled. After released reset, the mode will be the CPU-ROM mode.

5.1.2. Configuring CPU Programming Mode

Configuring CPU programming mode is shown below.

When the FWE bit of the flash control register (FCTLR) is "1", it is CPU programming mode. When the FRDY bit of the flash status register (FSTR) is "1", read/write from/to the flash memory is enabled in this mode.

5.2. Programming Flash Memory by CPU

This section explains programming flash memory by CPU.

After configuring CPU programming mode, perform erasing and programming using the automatic algorithm. In this model, because error correction codes (ECC) are added to each single word, programming needs to be performed for each single word. In the following procedure, each word is programmed by two operations to write one half-word. If this procedure is not followed, the written values will not be read correctly because the values will be written to flash memory without calculating the ECC.

1. Set the flash access size to 16 bits. (FCTLR:FSZ[1:0]=01)
2. Issue the write command. Write address = PA, write data = PD[31:16] See "5.5. Write Command" for details on the write command.
3. Read the hardware sequence flag until the write has finished. See "5.3.2. Automatic Algorithm Execution State" for details on reading the hardware sequence flag.
4. Issue the write command. Write address = PA+2, write data = PD[15:0] At this time, the hardware automatically calculates the ECC codes by combining with PD[31:16] from (2), and writing of ECC codes is also performed automatically at the same time.
5. Read the hardware sequence flag until the write has finished.
6. If there is more data to write, return to (2). Continue to (7) when all writes have finished.
7. Set CPU-ROM mode
8. Read the value which has already been written, and check that the correct value can be read. Even if the correct value can be read, check the FSTR:FECCERR bit to make sure that there was no ECC correction. If ECC correction occurs, follow the same procedure again starting from erasing the flash memory.

PA: Write target address (word aligned)
PD[31:0]: Write data
PD[31:16]: Write data upper 16 bits
PD[15:0]: Write data lower 16 bits

5.3. Automatic Algorithm

This section explains the automatic algorithm.

When using CPU programming mode, writes and erasures of flash memory are performed by starting the automatic algorithm. This section explains the automatic algorithm.

5.3.1. Command Sequence

The command sequence is shown below.

The automatic algorithm starts when half-word (16-bit) data is written to the flash memory once to six times in a row. This is called a command. The command sequences are shown below.

Table 5-1 Command Sequence

Command	Number of writes	1 st time		2 nd time		3 rd time		4 th time		5 th time		6 th time	
		Address [11:0]	Data [7:0]	Address [11:0]	Data [7:0]	Address [11:0]	Data [7:0]	Address [11:0]	Data [7:0]	Address [11:0]	Data [7:0]	Address [11:0]	Data [7:0]
Reset	1	arbitrary	F0 _H										
Read	1	RA	RD										
Write	4	x554 _H	AA _H	yAA8 _H	55 _H	x554 _H	A0 _H	PA	PD				
Chip erase	6	x554 _H	AA _H	yAA8 _H	55 _H	x554 _H	80 _H	x554 _H	AA _H	yAA8 _H	55 _H	x554 _H	10 _H
Sector erase	6	x554 _H	AA _H	yAA8 _H	55 _H	x554 _H	80 _H	x554 _H	AA _H	yAA8 _H	55 _H	SA	30 _H
Sector erase suspend	1	arbitrary	B0 _H										
Sector erase resume	1	arbitrary	30 _H										

* : The data written in the table only shows the lower 8 bits. The upper 8 bits can be any value. The commands are written as half-words or bytes.

* : The addresses written in the table only show the lower 16 bits. Set the upper 16 bits to any address within the address range of the target flash macro.

x:1,3,5,7,9,B,D,F
y:0,2,4,6,8,A,C,E

PA: Write address (half-word aligned)

PD: Write data (Write as half-word.)

SA: Sector address (specify an arbitrary address within the address range of the sector to erase.)

RA: Read address

RD: Read data (the read width is arbitrary.)

Note:

Do as follows to LSB 2-bit of the sector address (SA) to input when the command address and the sector erase command are issued.

- When half-word access : 2'b00
- When byte access : 2'b01 or 2'b11

Example 1:

When byte access and command address = (LSB 2-bit of the standard command address is changed to 2'b01.)

yAA8_H → yAA9_H, x554_H → x555_H, and SA → { SA[31:2] and 2'b01 }

(SA: When the sector erase command is issued, it is an arbitrary address in the input erase target sector)

Example 2:

When byte access and command address = (LSB 2-bit of the standard command address is changed to 2'b11.)

yAA8_H → yAAB_H, x554_H → x577_H, and SA → { SA[31:2] and 2'b11 }

(SA: When the sector erase command is issued, it is an arbitrary address in the input erase target sector)

Note:

If an incorrect address value or data value is written, or an incorrect sequence is written, the commands written till then will be cleared.

■ Reset Command

Each command input shown in Table 5-1 input to send the reset command to the object flash memory till then can try to be canceled, and to input the command from the first time again.

However, when each command is input to the last minute and automatic algorithm starts, automatic algorithm cannot be discontinued by this reset command.

If the execution of the automatic algorithm exceeds the timing limit, the flash memory returns to the reset state if the reset command is input.

■ Read Command

The flash memory can be read by sending the reading command to the target sector. If the read command is issued, the flash memory stays in read state until another command is issued.

■ Program (Write) Command

If a write command is sent to the target sector four times in a row, the automatic algorithm starts and writes data to the flash memory. Programming (writing) of data can be performed in any order of addresses or across a sector boundary.

In CPU programming mode, data is written in half-words or bytes. Once the fourth write has finished, the automatic algorithm starts and the automatic write to flash memory is started. After executing the automatic write algorithm command sequence, there is no need to control the flash memory externally.

See "5.5. Write Command" for details on the actual operation.

Notes:

- If the fourth write command (write data cycle) is written to an odd address when writing in half-word, the write is not performed correctly. Always write to an even address.
 - In the first write command sequence, only a single half-word data can be written. If you want to write multiple data, issue one write command sequence for each data.
 - When security is ON, there are restrictions in the procedure for writing the flash. See "5.9.4. Flash Access Restrictions When Security is ON" for details.
-

■ Chip Erase Command

If the chip erase command is sent to the target sector six times in a row, all sectors of the flash memory can be erased in one step. Once the sixth write has finished, the automatic algorithm starts and the chip erase operation is started. When the automatic erase algorithm is started, "0" is written to all of the cells in the flash memory chip before erasing the entire chip, and there is no need to write to flash memory before the chip erases to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.

See "5.6. Chip Erase Command" for details on the actual operation.

■ Sector Erase Command

If the sector erase command is sent to the target sector six times in a row, the sector of the flash memory is erased. When 40 μ s elapses (timeout period) after the sixth write has finished, the automatic algorithm starts and the sector erase operation is started. If you want to erase multiple sectors, write the erase code (30_H) to the address of the sector to erase within the 40 μ s (timeout period). If the next sector is not input within the timeout period, the sector erase command may become invalid. When the automatic erase algorithm is started, "0" is written to the cells in the sector to erase in flash memory before erasing the sector, and there is no need to write to flash memory before erasing the sector to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.

See "5.7. Sector Erase Command" for details on the actual operation.

Note:

When security is ON, there are restrictions in the procedure for erasing the sector of the flash. See "5.9.4. Flash Access Restrictions When Security is ON" for details.

■ Sector Erase Suspend Command

It is possible to shift to the sector erase suspend condition (state of the sector erase suspension) by sending the sector erase suspend command in the command time-out or while executing the sector erase.

In the sector erase suspend condition, the reading operation of the memory cell of the sector that is not the erase target becomes possible. However, a new neither writing nor erase command is accepted.

To restart the interrupting erase operation from the sector erase suspend condition, the erase restart command is sent.

When the erase resume command is accepted, the state comes back to the sector erase condition, resuming the erase operation.

It does not change to the state of the command time-out when the erase resume command is normally written even if it is time when it changes from the state of the command time-out in this state, it changes to the state of the erase deletion, and the sector erase operation is restarted at once.

See "5.8 Sector Erase Suspend Command" for actual operation.

Notes:

16.7 μ s or less is required until the sector erase operation is stopped from the issue of the sector erase suspend command and reading from the sector that is not the erase target becomes possible.

Whether it entered the state that can be read is confirmed with the FRDY bit of the flash status register (FSTR) or TOGG1 of the hardware sequence flag.

5.3.2. Automatic Algorithm Execution State

This section explains the automatic algorithm execution state.

Because writing and erasing flash memory is performed by an automatic algorithm, the operating state can be checked by the hardware sequence flag using the FRDY bit of the FLASH status register (FSTR) to determine whether or not the automatic algorithm is executing.

■ Hardware Sequence Flag

This flag indicates the state of the automatic algorithm. When the FRDY bit of the FLASH status register (FSTR) is "0", the operating state can be checked by reading from an arbitrary address in flash memory. The following shows the bit configuration of the hardware sequence flag.

Figure 5-1 Bit Configuration of Hardware Sequence Flag

<u>When half-word access</u>							
bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
Undefined	Undefined	Undefined	Undefined	Undefined	Undefined	Undefined	Undefined
bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
D POLL	TOGG1	TLOV	Undefined	SET1	TOGG2	Undefined	Undefined
<u>When byte access</u>							
bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
D POLL	TOGG1	TLOV	Undefined	SET1	TOGG2	Undefined	Undefined

Notes:

- It is impossible to read by word access. Always read using half-word or byte access in CPU programming mode.
- In CPU ROM mode, the hardware sequence flag cannot be read no matter which address is read.

● **Each bit and flash memory status**

Table 5-2 shows the correspondence between the state of each bit of the hardware sequence flag and the flash memory status.

Table 5-2 Correspondence between Flags and Flash Memory Status

Status		D POLL	TOGG1	TLOV	SETI	TOGG2
Run	Writing	Inverted data (*1)	Toggle	0	0	-
	Sector/Chip erasing	0	Toggle	0	1	-
Time limit exceed	Write command	Inverted data (*1)	Toggle	1	0	-
	Sector erase/Chip erase command	0	Toggle	1	1	-
Sector erase suspend	Erase target sector	-	-	-	-	Toggle

*1 : See "● Bit descriptions" for the values that are read out.

● **Bit descriptions**

[bit15 to bit8] Undefined bits

[bit7] D POLL : Data polling flag bit

When the hardware sequence flag is read by specifying the write/erase target address, this bit indicates whether or not the automatic algorithm is running using a data polling function.

The value that is read differs depending on the state.

1. When writing

During execution of writing	Reads out the opposite value (inverted data) of the value of bit7 of the last data to be written. The address specified for reading the hardware sequence flag is not accessed.
After writing finished	Reads out the value of bit7 of the address specified for reading the hardware sequence flag.

2. During sector erase

During sector erase	Reads "0" from the sector being erased.
After sector erase	This bit always reads out as "1".

3. During chip erase

During execution of chip erase	This bit always reads out as "0".
After chip erase	This bit always reads out as "1".

4. During sector erase suspend

State of suspend (incomplete end)	"0" is read from the sector erase suspend sector.
Sector erase operation completion	"1" is read from the sector erase suspend sector..

Note:

When the automatic algorithm is running, the data for the specified address cannot be read. Read data after using this bit to check whether the automatic algorithm operation has finished.

[bit6] TOGG1 :Toggle flag 1 bit

When the hardware sequence flag is read by specifying an arbitrary address, this bit indicates whether or not the automatic algorithm is running. The value that is read differs depending on the status.

During write / sector erase / chip erase

During write / sector erase / chip erase	If this bit is read sequentially, "1" and "0" are read alternatively (toggle operation). The address specified for reading the hardware sequence flag is not accessed.
After write / sector erase / chip erase	Reads out the value of bit6 of the address specified for reading the hardware sequence flag.

[bit5] TLOV : Timing limit exceed flag bit

When the hardware sequence flag is read by specifying an arbitrary address, this bit indicates whether or not the execution time of the automatic algorithm exceeded the time specifying internally within the flash memory (number of internal pulses). The value that is read differs depending on the state.

During write / sector erase / chip erase

The next values are read.

"0"	Within the rated time
"1"	Exceeds rated time

When this bit is "1", if the DPOLL bit and TOGG1 bit indicate that the automatic algorithm execution is in progress, the write or erase has failed.

For example, because data written to "0" cannot be rewritten with "1" in flash memory, when an attempt is made to write "1" to an address already written with "0", the flash memory is locked and the automatic algorithm does not end. In this case, the value of the DPOLL bit remains invalid and the value read from the TOGG1 bit continues to alternate between "1" and "0". If the rated time is exceeded in this state, this bit changes to "1". If this bit becomes "1", issue a reset command.

Note:

When this bit is "1", this indicates that the flash memory was not used correctly. The flash memory is not faulty. Perform the appropriate processing after issuing the reset command.

[bit4] Undefined bit

[bit3] SET1 : Sector erase timer flag bit

During sector erase, a timeout period of 40μs is required from when the sector erase command is issued until the sector erase actually starts. When the hardware sequence flag is read by specifying an arbitrary address, this bit indicates whether or not the sector erase command is within the timeout period. The value that is read differs depending on the state.

When erasing sectors:

When erasing sectors, you can check whether the next sector erase code is ready to be accepted by checking this bit before inputting the next sector erase code. Reads out the next value without accessing the address specified for reading the hardware sequence flag.

"0"	Within sector erase wait period (the next sector erase code (0x30) can be accepted.)
"1"	When exceeding the sector erase wait period (if the DPOLL bit and TOGG1 bit indicate that the automatic algorithm is executing at this time, the flash memory internal erase is started. In this case, commands other than the sector erase code (0x30) are ignored until the flash memory internal erase finishes.)

[bit2] TOGG2 : Toggle flag 2 bit

In the sector erase suspend state, non target sector for erase can be read (read), but the target sector for erase cannot be read. This flag indicates that output data is toggled and the target sector for erase when read address is the target sector for erase during sector erase suspend.

Read out target erase sector	If this bit is read sequentially, "1" and "0" are read alternatively (toggle operation). The address specified for reading the hardware sequence flag is not accessed.
Read out non target erase sector	Read data from specified address

[bit1,bit0] Undefined bits

5.4. Reset Command

The reset command is explained.

The flash memory can be reset by sending reset commands sequentially to the target flash memory. Because this state is the flash memory initial state, the flash memory always returns to the reset state when the power is turned on or a command finishes successfully. When the power is turned on, there is no need to issue a data read command. Furthermore, in reset state, data can be read using normal read access and programs can be accessed by the CPU; thus there is no need to issue the reset command when reading data.

5.5. Write Command

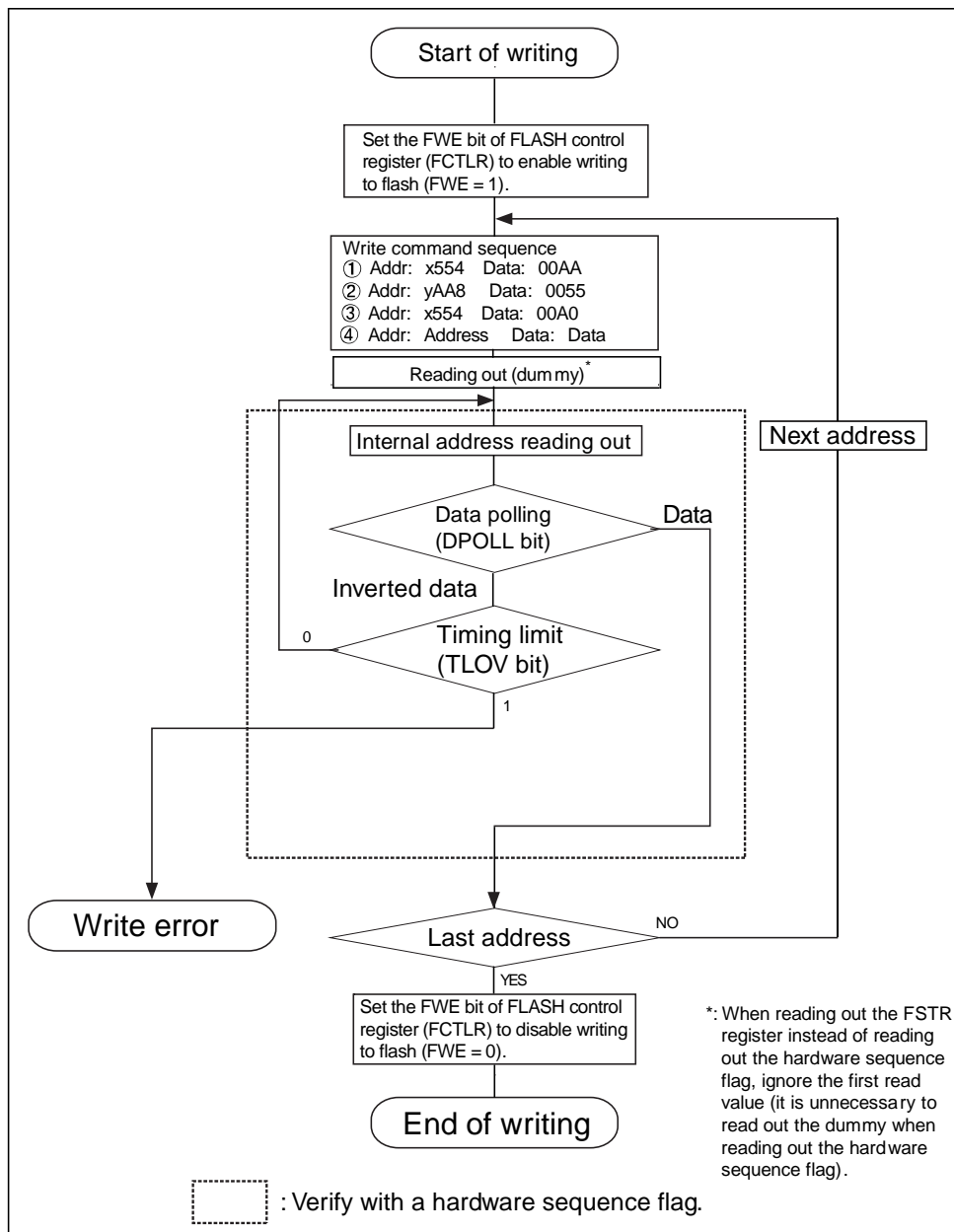
The write command is shown below

Writes are performed in the following order.

1. Send write commands sequentially to the target sector
The automatic algorithm is started and data is written to the flash memory. After issuing a write command, there is no need to control the flash memory externally.
2. Perform read access to the written address
The read data is the hardware sequence flag. Therefore, if bit7 (DPOLL bit) of the read data matches the written data, the write to the flash memory has finished. If the write has not finished, the opposite value (inverse data) of the value of bit7 of the last written data is read out.

The following shows an example of a write operation to the flash memory.

Figure 5-2 Example of Write Procedure



Notes:

- Once the write has finished, because the flash memory returns to read mode, write addresses are no longer accepted.
- See "5.3 Automatic Algorithm" for details on write commands.
- Because the DPOLL bit and the TLOV bit of the hardware sequence flag change at the same time, even when the TLOV bit is "1", it is necessary to confirm again.
- When the TOGG1 bit and the TLOV bit of the hardware sequence flag change to "1", the toggle operation stops at the same time. Therefore, it is necessary to confirm the TOGG1 bit again even the TLOV bit is "1".
- Although flash memory can be written to in any order of addresses, even if it crosses a sector boundary, only a single half-word data can be written in each write command sequence. If you want to write multiple data, issue one write command sequence for each data.
- Data that has been written to "0" once cannot be returned to "1". If "0" is rewritten with "1", one of the following occurs.
 - The element is judged as faulty by the data polling algorithm.

-The write rated time is exceeded, and the TLOV bit of the hardware sequence flag changes to "1".

-It appears to have been written as "1".

However, even if it appears to have been written as "1", the actual data remains "0" and "0" will be read out when the data is read in read/reset mode. If you want to return data to "1", perform a chip erase or sector erase.

- During write operations, all commands written to flash memory are ignored.
 - If this device is reset during a write, the data that was written cannot be guaranteed.
 - Because this series has the ECC bit added, data always needs to be written as 32-bit by two 16-bit writes. See "5.2 Programming Flash Memory by CPU" for the procedure.
-

5.6. Chip Erase Command

The chip erase command is shown below.

The erase target flash macros in the flash memory can be erased in one step using the chip erase command. If the chip erase command is sent to the target flash memory sequentially, the automatic algorithm starts and all sectors of the flash memory can be erased in one step. See "5.3 Automatic Algorithm" for details on the chip erase command.

1. Send chip erase commands sequentially to a sector in the flash macro to erase
The automatic algorithm is started and data is written to the flash memory.
2. Perform a read access to an arbitrary address in the flash macro to erase
The read data is the hardware sequence flag. Therefore, when bit7 (DPOLL bit) of the read data is "1", the chip erase has finished.

The time required to erase the chip is [sector erasure time x total no. of sectors + chip write time (preprogram)]. When the chip erase operation finishes, the flash memory returns to the read/reset state.

Notes:

- When the automatic erase algorithm is started, "0" is written to all of the cells in the flash memory chip before erasing the entire chip, and there is no need to write to flash memory before the chip erase to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.
 - When security is on, there are restrictions in the procedure for erasing the flash. See "5.9.3 Unlocking Flash Security" for details.
-

5.7. Sector Erase Command

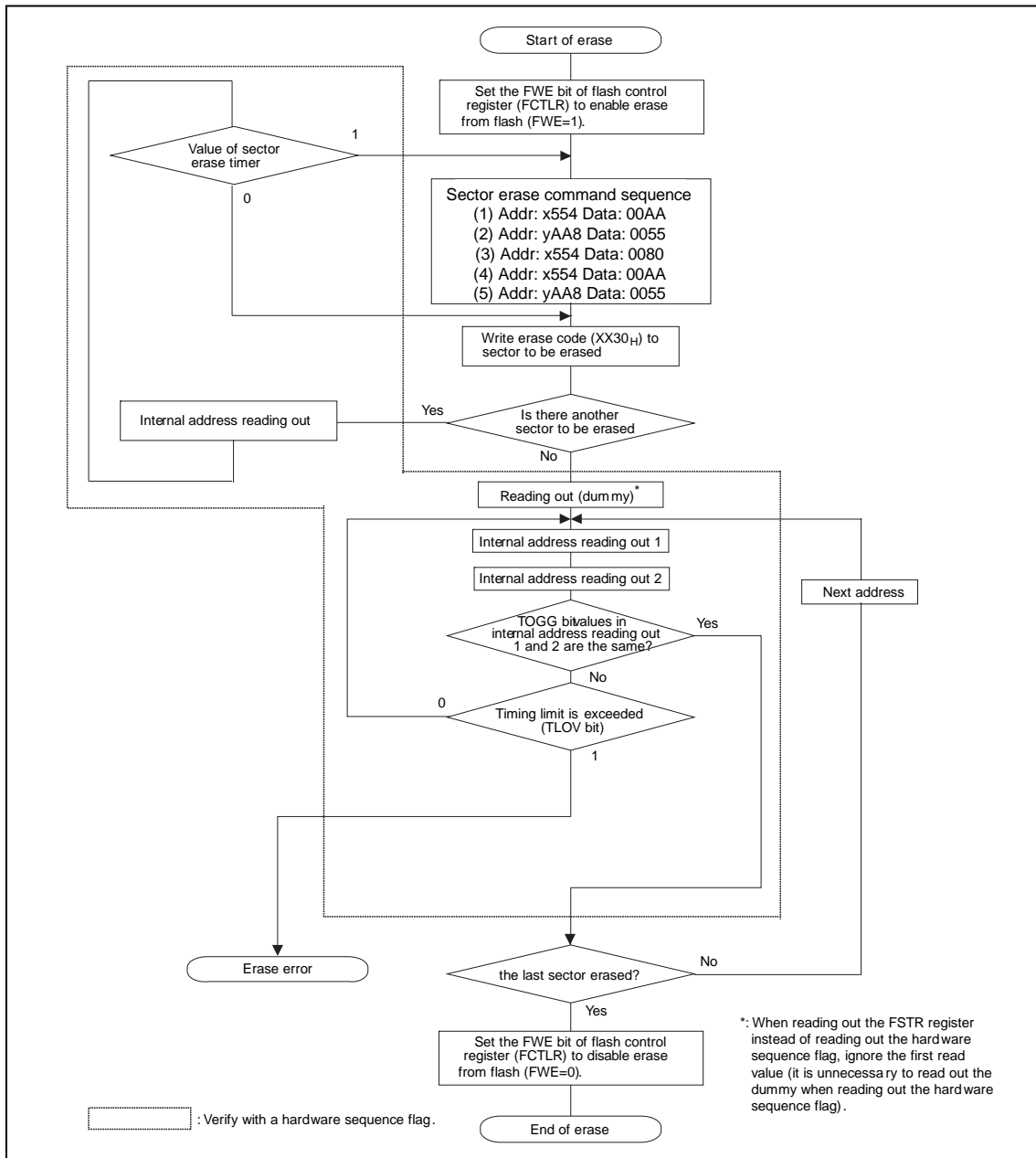
The sector erase command is shown below.

A sector in the flash memory can be selected and only data in the selected sector can be deleted. Multiple sectors can also be specified at the same time. Sector erase is performed in the following order.

1. Send sector erase commands sequentially to the target sector
Once 40 μ s has elapsed (timeout period), the automatic algorithm starts and the sector erase operation is started. If you want to erase multiple sectors, write the erase code (30_H) to the address of the sector to erase within the 40 μ s (timeout period). If the write is performed after the timeout period has elapsed, the sector erase command may be invalid.
2. Perform read access to an arbitrary address
The read data is the hardware sequence flag. Therefore, when bit7 (DPOLL bit) of the read data is "1", the sector erase has finished. Furthermore, you can use the TOGG1 bit to check whether or not the sector erase has finished.

The following shows an example of the sector erase procedure taking the example of using the TOGG1 bit in the check operation.

Figure 5-3 Example of Sector Erase Procedure



Notes:

- The time required to erase the sector is [(sector erase time + sector write time (pre-program)) × number of sectors].
- When the sector erase operation finishes, the flash memory returns to the read/reset state.
- See "5.3. Automatic Algorithm" for details on the sector erase command.
- Because the DPOLL bit and the TLOV bit of the hardware sequence flag change at the same time, even when TLOV bit is "1", it is necessary to confirm again.
- When the TOGG1 bit and the TLOV bit of the hardware sequence flag change to "1", toggle operation stops at the same time. Therefore, it is necessary to confirm the TOGG1 bit again even the TLOV bit is "1".
- If a command other than the sector erase command is issued during sector erase including the timeout period, the flash memory returns to the read/reset state. In this case, because the flash memory is reset, the previously issued command or multiple sector erase commands become invalid. To erase the sector, reissue the sector erase commands from the beginning.
- When the automatic erase algorithm is started, "0" is written to the cells to erase in flash memory before erasing the sector, and there is no need to write to flash memory before

erasing the sector to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.

5.8. Sector Erase Suspend Command

The sector erase suspend command is shown below

The sector erase can temporarily be stopped in the command time-out or while executing the sector erase.

The reading operation of the memory cell of the sector that is not the erase target becomes possible in the suspend condition of the sector erase. However, a new neither writing nor erase command is accepted.

The sector erase suspend command is sent to an arbitrary address of target FLASH macro to suspend of the sector erase.

After the sector erase stops, the reading operation from target FLASH macro is permitted.

At this time, the hardware sequence flag is read from the sector which is under the sector erase suspend condition.

- The TOGG1 bit that does the toggle while erasing the sector does not toggle in the sector erase suspend condition.
- FRDY of the flash status register becomes "1".

The thing that entered the sector erase suspend condition can be confirmed by using these.

Note:

16.7 μ s or less is required until the sector erase operation is stopped from the issue of the sector erase suspend command and reading from the sector that is not the erase target becomes possible.

Because Bit2:TOGG2 of the hardware sequence flag does the toggle while the sector erase is temporarily stopping, the sector can be confirmed while stopping by using this bit.

To restart the interrupting erase operation from the sector erase suspend condition, the sector erase restart command in Table 5-1 is sent.

The sector erase restart command is accepted only by the sector erase suspend condition.

Send the command after confirming becoming the sector erase suspend condition.

Accepting the erase restart command, the flash memory comes back to the sector erase condition, resuming the erase operation.

5.9. Security Function

The security function is shown below.

This flash memory is equipped with a security function. When the security function is off, the flash memory can be used without limits. However, when the security function is on, the operation after an instruction fetches from the external bus, and writes and erases other than chip erase are suppressed. See "5.9.4 Flash Access Restrictions When Security is ON" for details on the restrictions.

5.9.1. Flash Security On/Off Determination When Reset Released

Flash security on/off determination when reset released is shown below.

The flash interface of this series reads two bytes from the flash security code area after reset is released. If this value is 0x0001, security is turned on and access restrictions are imposed on subsequent accesses to flash memory. For any other value, the security is turned off.

5.9.2. Flash Security Setting Method

The flash security setting method is shown below.

When reset is input and released after writing 0x0001 to the flash security code area (see Figure 3-2), security is turned on. Once security has been turned on, the security is not turned off unless the entire flash memory area is erased.

5.9.3. Unlocking Flash Security

Unlocking flash security is shown below.

The chip erase command can be performed on all flash macros using the following procedure.

- (1) Erase WorkFlash.
- (2) Erase program flash which contains the flash security code.

Erase program flash last, as shown above. Otherwise, the erase command to program flash is ignored. Furthermore, if a reset is input between erases, repeat from step (1).

Note:

In the user-mode (internal FLASH activation), the erase command can be issued to an arbitrary flash macro, and data in the flash macro be deleted. The order of the chip erase to each flash macro is recommended to be executed from the viewpoint of the data protection stored in the flash macro as shown in the above-mentioned.

5.9.4. Flash Access Restrictions When Security is ON

Flash access restrictions when security is ON are shown below.

When security is on, the restrictions shown below are created by the start mode.

Table 5-3 Access Restrictions when Security is ON

Operating mode	Access restriction
User / external bus	<p>In normal mode (the state where there are no access restrictions due to the following flash security violations), writing in the security information area (first nine words of the FLASH memory) is canceled. Moreover, a sector erase command to sector 0/sector 1 is ignored.</p> <p>If an instruction fetch is performed to the on-chip bus area, a reset request is issued by the flash security violation reset source. Accesses to the flash memory are not accepted thereafter.</p> <p>The flash memory returns to the normal state by reset.</p>
Other than above (writer etc.)	<p>Access to flash memory is restricted.</p> <p>The data from reads is masked and 0xFFFF_FFFF is returned. Write commands and sector erase commands are ignored.</p> <p>Chip erase commands are accepted. See "5.9.3 Unlocking Flash Security".</p>

Furthermore, while the security is ON, when a data read is performed to the security information storage area (9 words at the start of the flash memory)

- A data access error will occur, and an illegal instruction exception or data access error interrupt will occur. (See "FR Family FR81 32-bit microcontroller programming manual" for details.)
- 0xFFFFFFFF is returned as the read value.

However, when the OCD tool is connected, this restriction does not apply to access from OCDU or read during the debug state.

5.10. Notes on Using Flash Memory

Notes on using flash memory are shown below.

- If this device is reset during a write, the data that was written cannot be guaranteed.
- If CPU programming mode is set (FWE=1) using the FWE bit of the FLASH control register (FCTLR), do not execute the program in flash memory. The program runs out of control without fetching the correct values.
- If CPU programming mode is set (FWE=1) using the FWE bit of the FLASH control register (FCTLR) and the interrupt vector table is in flash memory, do not generate interrupt requests. The program runs out of control without fetching the correct values.
- Because this model has the ECC bit added, data always needs to be written as 32 bits by two 16-bit writes. See "5.2. Programming Flash Memory by CPU" for the procedure.
- Do not issue commands to multiple macros simultaneously (i.e. in parallel). Input a command to the next macro after confirming that the command has completed using either the hardware sequence flag or FRDY bit.
- Once authentication is complete using the debugger (OCD) password, OCD can be used to read the content of flash memory externally even if security is on. If you want to prevent a third party from reading, always set a password for enabling on chip debugger (OCD) startup.
- Changing to the standby state is a prohibition during FLASH program/erase.
- Because of build-in ECC in this flash memory, the data superscription to the address where some values have already been written cannot be done.

CHAPTER : WORKFLASH MEMORY

This chapter explains the WorkFlash memory.

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains the overview of the WorkFlash memory.

A memory size of the WorkFlash memory built in this series is 64 Kbytes. Error correction codes (ECC) are attached.

2. Features

This section explains features of the WorkFlash memory.

- Usable capacity:
MB91F591/MB91F592/MB91F594/MB91F596/MB91F597/MB91F599 : 64K bytes (8K bytes × 8 sectors)
For ECC code storage, there are 6 bits of built-in flash memory for every 4 bytes.
 - High-speed operation:
read on a word-by-word basis (32 bit) is possible by 80 MHz × 2 cycle.
For 128 MHz, 4 cycles are needed.
 - Write from external: Possible from ROM writer
 - Operation mode:
 - (1) CPU-ROM mode
(CPU/DMA accesses flash memory. Only read)
Only data access is enabled. Instruction fetch is not enabled.
 - (2) CPU programming mode
(CPU accesses flash memory. Read/Write/Erase)
 - (3) Flash memory mode
(Access flash memory from the external is enabled.)
 - Security function
 - Operations after instruction fetch from external and write/erase except for chip erase at security on are inhibited to avoid reading out flash memory data by an outsider.
 - The use of on-chip debugger (OCD) enables read from external by using OCD, even if security is on after password authentication.
 - There is an error correction code (ECC) function that corrects errors of up to one bit in each word. (A function for detecting 2-bit errors is not provided.) Errors are automatically corrected during read. Furthermore, ECC codes are automatically added when writing to the flash memory. Because there is no read cycle penalty due to error correction, no consideration needs to be given to error correction penalties during software development.
- *: Automatic Algorithm=Embedded Algorithm

3. Configuration

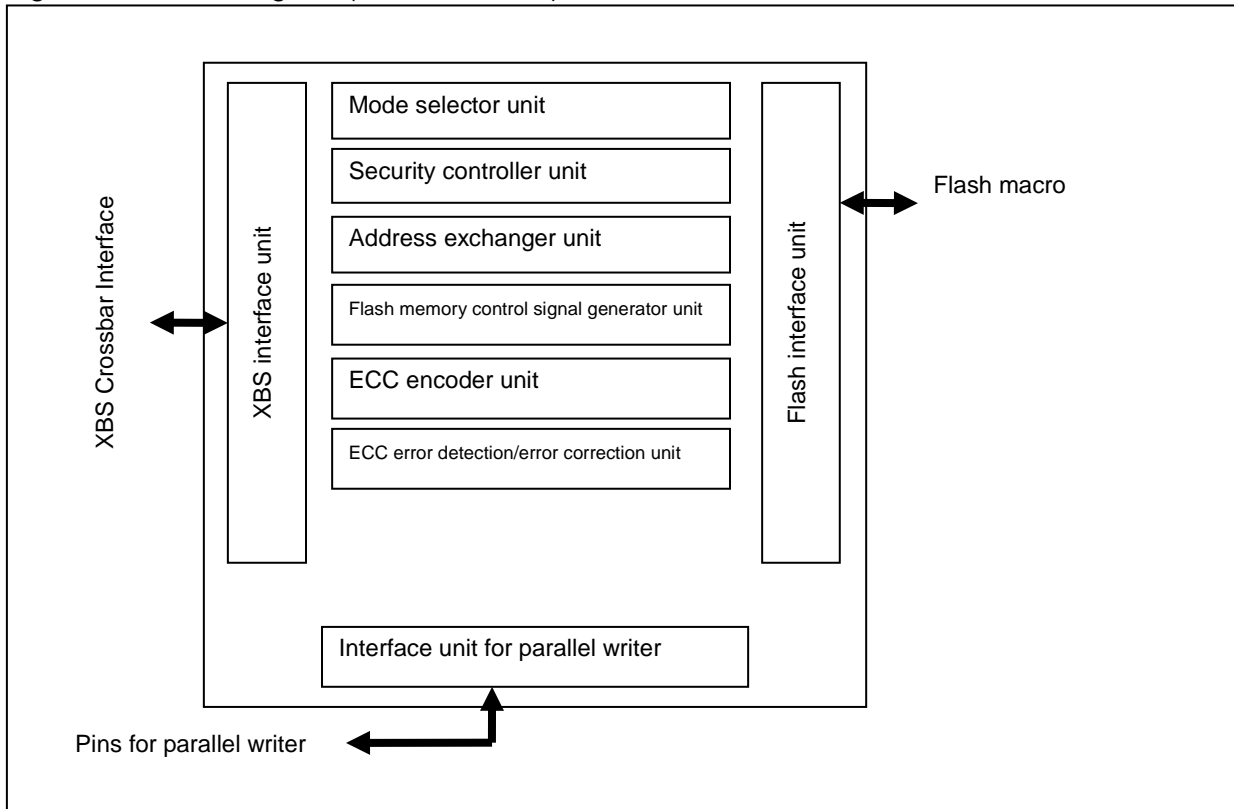
This section explains the configuration of the WorkFlash memory.

- 3.1. Block Diagram
- 3.2. Sector Configuration Diagram

3.1. Block Diagram

This section shows the block diagram of the WorkFlash memory.

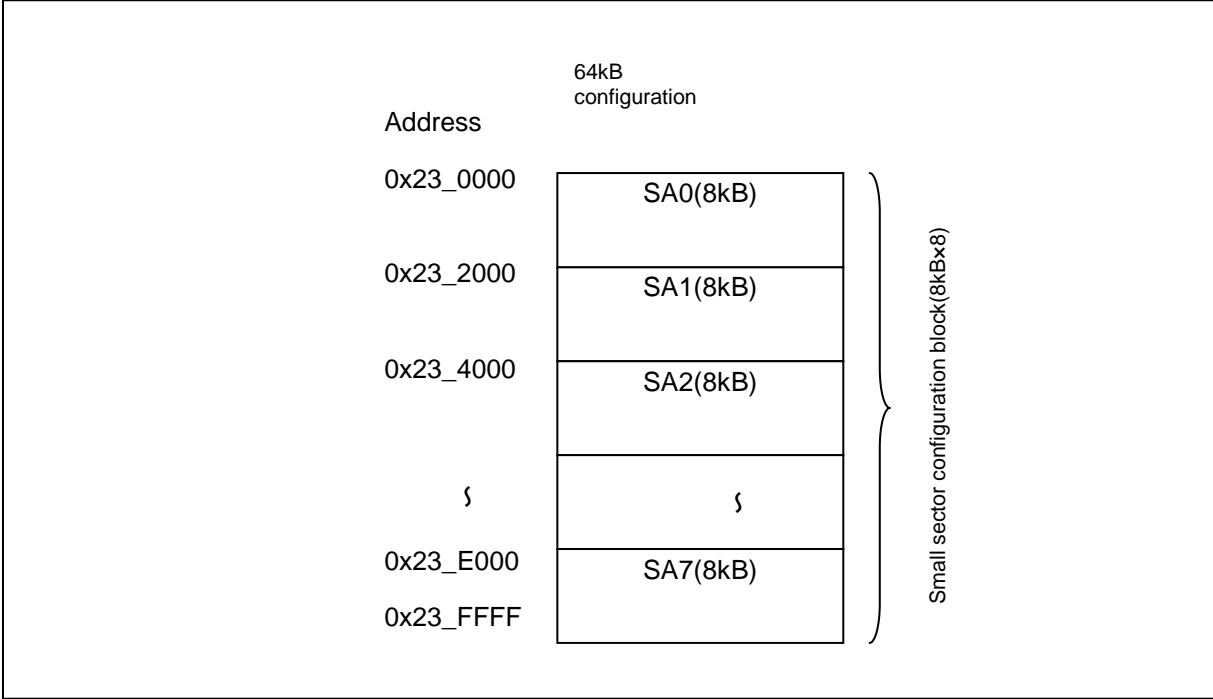
Figure 3-1 Block Diagram (64KB Products)



3.2. Sector Configuration Diagram

The sector configuration diagram of the WorkFlash memory is shown below.

Figure 3-2 Sector Configuration Diagram



4. Registers

This section explains registers of the WorkFlash memory.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x2300	DFCTLR		Reserved	DFSTR	WorkFlash Control Register WorkFlash Status Register
0x2308	FLIFCTLR	Reserved	Reserved	Reserved	Flash Interface Control Register

4.1. WorkFlash Control Register : DFCTLR (WorkFlash Control Register)

The bit configuration of the WorkFlash control register is shown below.

This register configures the access control to the WorkFlash.

■ DFCTLR: Address 2300_H (Access : Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved	FWE	Reserved					
Initial value	-	0	-	-	-	-	-	-
Attribute	RX,WX	R/W	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							
Initial value	-	-	-	-	-	-	-	-
Attribute	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX

[bit15] Reserved

This bit is reserved. The read value is undefined. Writing has no effect on the operation.

[bit14] FWE (Flash Write Enable) : Flash write enable

This bit is a control bit to enable write to the WorkFlash in the CPU mode.

If this bit is set, the ECC error detection and data correcting function will be disabled for data fetching to the WorkFlash memory.

FWE	Description
0	Flash write disabled (Initial value)
1	Flash write enabled

[bit13 to bit0] Reserved

These bits are reserved. The read value is undefined. Writing has no effect on the operation

4.2. WorkFlash Status Register : DFSTR (WorkFlash Status Register)

The bit configuration of the WorkFlash status register is shown below.

This register indicates the WorkFlash status.

■ DFSTR: Address 2303_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved					DFECCERR	DFHANG	DFRDY
Initial value	-	-	-	-	-	0	0	1
Attribute	RX,WX	RX,WX	RX,WX	RX,WX	RX,WX	R/W	R,WX	R,WX

[bit7 to bit3] Reserved

These bits are reserved. The read value is undefined. Writing has no effect on the operation.

[bit2] DFECCERR (WorkFlash ECC Error coRRection) : data read ECC correction occurred

This bit indicates that ECC error occurs when reading data of WorkFlash in the CPU mode. This bit is cleared by writing "0". Writing "0" is prioritized when ECC error and writing "0" occur concurrently.

DFECCERR	Read	Write
0	An error correction by ECC has not occurred during data read (initial value)	Clears this bit
1	ECC error correction occurred during data read	No effect

If there are errors in 2-bit or more in a single word, the read value of this bit is undefined.

[bit1] DFHANG (WorkFlash HANG) : WorkFlash HANG status

This bit indicates the WorkFlash memory HANG status. If there is a timing overrun (See "[bit5]: TLOV: (Timing Limit Elapsed Flag Bit)"), the flash memory will go into the HANG status. If this bit becomes "1", issue the Reset command (See "5.3.1 Command Sequence").

The correct value might not be read out immediately after a command of automatic algorithm has been issued. Therefore, ignore the first read value of this bit after the command issuance.

DFHANG	Description
0	Normal state
1	HANGUP state

[bit0]DFRDY (WorkFlash ReaDY) : WorkFlash write enable

This bit indicates whether the flash memory write/erase operation by automatic algorithm is currently running or finished. Flash memory data cannot be written or erased while the operation is in progress.

DFRDY	Description
0	During operation (write/erase disabled, read status enabled)
1	Completion of operation (write/erase enabled, read enabled)

The correct value might not be read out immediately after a command of automatic algorithm has been issued. Therefore, ignore the first read value of this bit after the command issuance.

4.3. Flash Interface Control Register : FLIFCTLR (Flash I/F Control Register)

The bit configuration of the flash interface control register is shown below.

This register controls Flash I/F. This register is shared among program flash and WorkFlash.

■ **FLIFCTLR: Address 2308_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			DFWDSBL	Reserved		ECCDSBL1	ECCDSBL0
Initial value	-	-	-	0	-	0	0	0
Attribute	RX,WX	RX,WX	RX,WX	R/W	RX,WX	R/W0	R/W	R/W

[bit7 to bit5] Reserved

These bits are reserved. The read value is undefined. Writing has no effect on the operation.

[bit4] DFWDSBL (Data Fetch Wait cycle Disable) : Data fetch wait cycle disabled

If this bit is set to "1", the wait cycle inserted when setting wait at data fetch is disabled. However, you cannot disable the wait cycle to guarantee the cycle time.

DFWDSBL	Description
0	Wait cycle enabled (Initial value)
1	Wait cycle disabled

[bit3] Reserved

This bit is reserved. The read value is undefined. Writing has no effect on the operation.

[bit2] Reserved

This bit is reserved. When writing, always write "0" to this bit.

[bit1] ECCDSBL1 (ECC Disable1) : ECC function disable 1

This bit configures enable/disable for the ECC function when write access and data fetch to WorkFlash memory in the CPU mode.

ECCDSBL1	Description
0	ECC function enabled (Initial value)
1	ECC function disabled

[bit0] ECCDSBL0 (ECC Disable0) : ECC function disable 0

This bit configures enable/disable for the ECC function when write access and data fetch to program flash memory in the CPU mode.

ECCDSBL0	Description
0	ECC function enabled (Initial value)
1	ECC function disabled

5. Operation

The section explains the operation of the WorkFlash memory.

This section explains the method for accessing the flash area.

- 5.1. Access Mode Setting
- 5.2. Writing Flash Memory by CPU
- 5.3. Automatic Algorithm
- 5.4. Reset Command
- 5.5. Write Command
- 5.6. Chip Erase Command
- 5.7. Sector Erase Command
- 5.8. Sector Erase Suspend Command
- 5.9. Security Function
- 5.10. Notes on Using Flash Memory

5.1. Access Mode Setting

Access mode setting is shown below.

The flash memory in this series has the following three modes. Methods of setting the modes (1) and (2) are explained in this section. As for the mode (3), see the instruction manual of the ROM writer you are using for details.

- (1) CPU-ROM mode
(CPU accesses flash memory. For only read, Byte/Half-word/Word access)
- (2) CPU programming mode
(CPU accesses flash memory. For reading and writing, only Half-word access)
- (3) Flash memory mode
(Access to flash memory from external is enabled.)

5.1.1. Configuring CPU-ROM Mode below

Configuring CPU-ROM mode is shown below.

When the FWE bit of the WorkFlash control register (DFCTLR) is "0", it is CPU-ROM mode. When the DFRDY bit of the WorkFlash status register (DFSTR) is "1", read from the flash memory is enabled in this mode. In the mode, write to the flash memory is disabled. After released reset, the mode will be the CPU-ROM mode.

5.1.2. Configuring CPU Programming Mode

Configuring CPU programming mode is shown below.

When the FWE bit of the WorkFlash control register (DFCTLR) is "1", it is CPU programming mode. When the DFRDY bit of the WorkFlash status register (DFSTR) is "1", read/write from/to the flash memory is enabled in this mode.

5.2. Writing Flash Memory by CPU

Writing the flash memory by CPU is shown below.

After configuring CPU programming mode, perform erasing and programming using the automatic algorithm. In this model, because error correction codes (ECC) are added to each single word, programming needs to be performed for each single word. In the following procedure, each word is programmed by two operations to write one half-word. If this procedure is not followed, the written values will not be read correctly because the values will be written to the flash memory without calculating the ECC.

- (1) Set the flash access size to 16-bit. (FCTLR:FSZ[1:0]=01)
* See "CHAPTER : FLASH MEMORY" for FCTLR.
- (2) Issue the write command. Write address = PA, write data = PD[31:16]
See "5.5 Write Command" for details on the write command.
- (3) Read the hardware sequence flag until the write has finished.
See "5.3.2 Automatic Algorithm Execution State" for details on hardware sequence flag read.
- (4) Issue the write command. Write address = PA+2, write data = PD[15:0]
At this time, the hardware automatically calculates the ECC codes by combining with PD[31:16] from (2), and writing of ECC codes is also performed automatically at the same time.
- (5) Read the hardware sequence flag until the write has finished.
- (6) If there is more data to write, return to (2). Continue to (7) when all writes have finished.
- (7) Set CPU-Rom mode.
- (8) Read the value that was written and check that the correct value is read. Even if the correct value could be read, check the DFSTR:DFECCERR bit to confirm that there was no ECC correction. If ECC correction occurred, write again starting from erasing the flash memory.

PA : Write target address (word alignment)
PD[31:0] : Write data
PD[31:16]: Write data upper 16-bit
PD[15:0] : Write data lower 16-bit

5.3. Automatic Algorithm

The automatic algorithm is shown below.

When using CPU programming mode, write and erase of flash memory are performed by starting the automatic algorithm. This section explains the automatic algorithm.

5.3.1. Command Sequence

The command sequence is shown below.

The automatic algorithm starts when half-word (16-bit) data is written to the flash memory once to six times in a row. This is called a command. The command sequences are shown below.

Table 5-1 Command Sequence

Command	Number of writing	1st time		2nd time		3rd time		4th time		5th time		6th time	
		Address	Data	Address	Data	Address	Data	Address	Data	Address	Data	Address	Data
Reset	1	arbitrary	F0 _H										
Read	1	RA	RD										
Write	4	AA8 _H	AA _H	554 _H	55 _H	AA8 _H	A0 _H	PA	PD				
Chip erase	6	AA8 _H	AA _H	554 _H	55 _H	AA8 _H	80 _H	AA8 _H	AA _H	554 _H	55 _H	AA8 _H	10 _H
Sector erase	6	AA8 _H	AA _H	554 _H	55 _H	AA8 _H	80 _H	AA8 _H	AA _H	554 _H	55 _H	SA	30 _H
Sector erase suspend	1	arbitrary	B0 _H										
Sector erase resume	1	arbitrary	30 _H										

* The data written in the table only shows the lower 8-bit. The upper 8-bit can be any value. The commands must be written as bytes or half-words.

* The addresses written in the table only show the lower 12-bit. Set the upper 20-bit to any address within the address range of the target flash macro.

PA: Write address (half-word alignment)

PD: Write data (Write as 16-bit.)

SA: Sector address (specify an arbitrary address within the address range of the sector to erase.)

RA: Read address

RD: Read data (the read width is arbitrary.)

Note:

Do as follows to LSB 2-bit of the sector address (SA) to input when the command address and the sector erase command are issued.

- When half-word access : 2'b00
- When byte access : 2'b01 or 2'b11

Example 1:

When byte access and command address = (LSB 2-bit of the standard command address is changed to 2'b01.)

AA8_H → AA9_H, 554_H → 555_H, and SA → { SA[31:2] and 2'b01 }

(SA: When the sector erase command is issued, it is an arbitrary address in the input erase target sector)

Example 2:

When byte access and command address = (LSB 2-bit of the standard command address is changed to 2'b11.)

AA8_H → AAB_H, 554_H → 577_H, and SA → { SA[31:2] and 2'b11 }

(SA: When the sector erase command is issued, it is an arbitrary address in the input erase target sector)

Note:

When the wrong address value and data value are written or writing is performed in the wrong sequence, commands that have been written are cleared.

■ Reset Command

When the reset command is given to the target flash memory, a sequential input of each command shown in Table 5-1 is cancelled, and another sequential input can be done again from the first time.

However, when each command is input to the last minute and automatic algorithm starts, automatic algorithm cannot be discontinued by this reset command.

If the execution of the automatic algorithm exceeds the timing limit, the flash memory returns to the reset state if a reset command is input.

■ Read Command

The flash memory can be read by sending read commands to the target sector. If a read command is issued, the flash memory stays in read state until another command is issued.

■ Programming (Write) Command

If a write command is sent to the target sector four times in a row, the automatic program algorithm starts and writes data to the flash memory. Programming (writing) of data can be performed in any order of addresses or across a sector boundary. In the CPU programming mode, data is written in half-words. Once the fourth write has finished, the automatic algorithm starts and the automatic write to flash memory is started. After executing the automatic write algorithm command sequence, there is no need to control the flash memory externally.

See "5.5 Write Command" for details on the actual operation.

Notes:

- When writing in half-word, if the forth command (write data cycle) is written in the odd address, writing is not performed correctly. Always write in even address.
 - In the first write command sequence, a single half-word data can be written. If you want to write multiple data, issue one write command sequence for each data.
 - While security is ON, writing of flash is limited. See "5.9.4. Flash Access Restrictions When Security is ON" for details.
-

■ Chip Erase Command

If the chip erase command is sent to the target sector six times in a row, all sectors of the flash memory can be erased in one step. Once the sixth write has finished, the automatic program algorithm starts and the chip erase operation is started. When the automatic erase algorithm is started, "0" is written to all of the cells in the flash memory chip before erasing the entire chip, and there is no needs to write to the flash memory before the chip erase to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.

See "5.6 Chip Erase Command" for details on the actual operation.

■ Sector Erase Command

If the sector erase command is sent to the target sector six times in a row, the sector of the flash memory is erased. When 40 μ s elapses (timeout period) after the sixth write has finished, the automatic algorithm starts and the sector erase operation is started. If you want to erase multiple sectors, write the erase code (30_H) to the address of the sector to erase within the 40 μ s (timeout period). If the next sector is not input within the timeout period, the sector erase command may become invalid. When the automatic erase algorithm is started, "0" is written to the cells in the sector to erase in flash memory before erasing the sector, and there is no need to write to the flash memory before erasing the sector to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.

See "5.7 Sector Erase Command" for details on the actual operation.

Note:

While security is ON, the sector erase procedure of flash is limited. See "5.9.4. Flash Access Restrictions When Security is ON" for details.

■ Sector Erase Suspend Command

It is possible to shift to the sector erase suspend condition (state of the sector erase suspension) by sending the sector erase suspend command in the command time-out or while executing the sector erase.

In the sector erase suspend condition, the reading operation of the memory cell of the sector that is not the erase target becomes possible. However, a new neither writing nor erase command is accepted.

To restart the interrupting erase operation from the sector erase suspend condition, the erase restart command is sent.

When the flash memory accepts the erase resume command, it goes back to sector erase state and starts erase operation again.

It does not change to the state of the command time-out when the erase resume command is normally written even if it is time when it changes from the state of the command time-out in this state, it changes to the state of the sector erase, and the sector erase operation is restarted at once.

See "5.8 Sector Erase Suspend Command" for actual operation.

Notes:

- 16.7 μ s or less is required until the sector erase operation is stopped from the issue of the sector erase suspend command and reading from the sector that is not the erase target becomes possible.
 - Whether it entered the state that can be read is confirmed with the DFRDY bit of the WorkFlash status register (DFSTR) or TOGG1 of the hardware sequence flag.
-

5.3.2. Automatic Algorithm Execution State

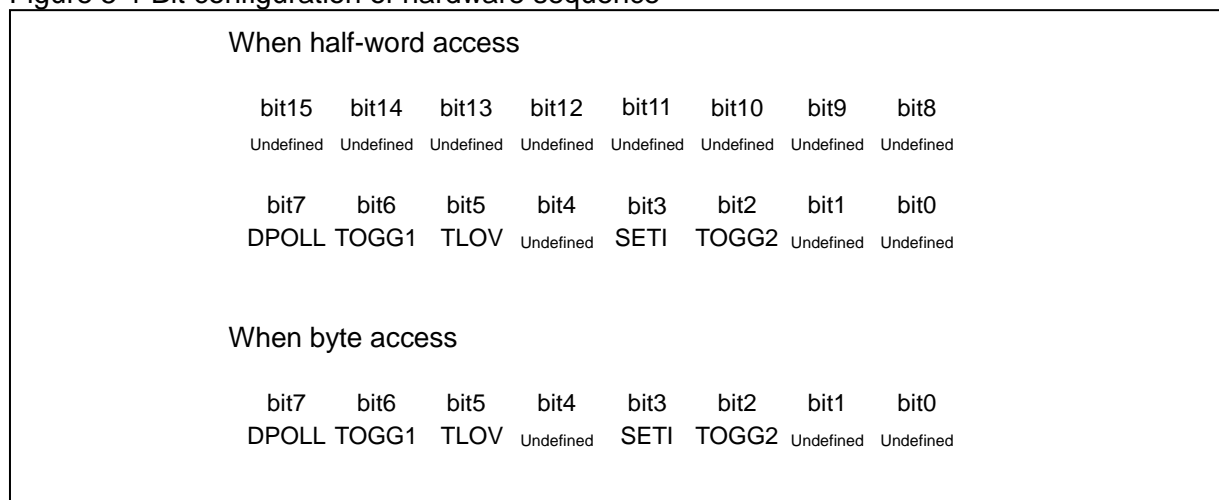
The automatic algorithm execution state is shown below.

Because writing and erasing flash memory is performed by an automatic algorithm, the operating state can be checked by the hardware sequence flag using the DFRDY bit of the WorkFlash status register (DFSTR) to determine whether or not the automatic algorithm is executing.

■ Hardware Sequence Flag

This flag indicates the state of the automatic algorithm. When the DFRDY bit of the WorkFlash status register (DFSTR) is "0", the operating state can be checked by reading from an arbitrary address in flash memory. Following figure shows the bit configuration of the hardware sequence flag.

Figure 5-1 Bit configuration of hardware sequence



Notes:

- It is impossible to read by word access. Always read using half-word or byte access in CPU programming mode.
- In CPU ROM mode, the hardware sequence flag cannot be read no matter which address is read.

● **Each bit and flash memory status**

Following table shows the correspondence between the status of each bit of the hardware sequence flag and the flash memory status.

Table 5-2 Correspondence between Flags and Flash Memory status

State		D POLL	TOGG1	TLOV	SETI	TOGG2
Run	Writing	Inverted data (*1)	Toggle	0	0	-
	Sector/Chip erasing	0	Toggle	0	1	-
Time limit exceed	Write command	Inverted data (*1)	Toggle	1	0	-
	Sector erase/Chip erase command	0	Toggle	1	1	-
Sector erase suspend	Erase target sector	-	-	-	-	Toggle

*1 : See "● Bit descriptions" for the values that are read out.

● **Bit descriptions**

[bit15 to bit8] Undefined bits

[bit7] D POLL (Data polling flag bit)

When the hardware sequence flag is read by specifying the write/erase target address, this bit indicates whether or not the automatic algorithm is running using a data polling function.

The value that is read differs depending on the state.

1. When writing

During execution of writing	Reads out the opposite value (inverted data) of the value of bit7 of the last data to be written. The address specified for reading the hardware sequence flag is not accessed.
After writing finished	Reads out the value of bit7 of the address specified for reading the hardware sequence flag.

2. During sector erase

During execution of sector erase	Reads "0" from the sector being erased.
After sector erase	This bit always reads out as "1".

3. During chip erase

During execution of chip erase	This bit always reads out as "0".
After chip erase	This bit always reads out as "1".

4. During sector erase suspend

State of suspend (incomplete end)	"0" is read from the sector erase suspend sector.
Sector erase operation completion	"1" is read from the sector erase suspend sector..

Note:

When the automatic algorithm is running, the data for the specified address cannot be read. Read data after using this bit to check whether the automatic algorithm operation has finished.

[bit6] TOGG1 (Toggle flag 1 bit)

When the hardware sequence flag is read by specifying an arbitrary address, this bit indicates whether or not the automatic algorithm is running. The value that is read differs depending on the status.

During write / sector erase / chip erase

During write / sector erase / chip erase	If this bit is read sequentially, "1" and "0" are read alternatively (toggle operation). The address specified for reading the hardware sequence flag is not accessed.
After write / sector erase / chip erase	Reads out the value of bit6 of the address specified for reading the hardware sequence flag.

[bit5] TLOV (Timing limit exceeded flag bit)

When the hardware sequence flag is read by specifying an arbitrary address, this bit indicates whether or not the execution time of the automatic algorithm exceeded the time specifying internally within the flash memory (number of internal pulses). The value that is read differs depending on the state.

During write / sector erase / chip erase

The next values are read.

"0"	Within the rated time
"1"	Exceeds rated time

When this bit is "1", if the DPOLL bit and TOGG1 bit indicate that the automatic algorithm execution is in progress, the write or erase has failed.

For example, because data written to "0" cannot be rewritten with "1" in flash memory, when an attempt is made to write "1" to an address already written with "0", the flash memory is locked and the automatic algorithm does not end. In this case, the value of the DPOLL bit remains invalid and the value read from the TOGG1 bit continues to alternate between "1" and "0". If the rated time is exceeded in this state, this bit changes to "1". If this bit becomes "1", issue a reset command.

Note:

When this bit is "1", this indicates that the flash memory was not used correctly. The flash memory is not faulty. Perform the appropriate processing after issuing the reset command.

[bit4] Undefined bit

[bit3] SET1 (Sector erase timer flag bit)

During sector erase, a timeout period of 40µs is required from when the sector erase command is issued until the sector erase actually starts. When the hardware sequence flag is read by specifying an arbitrary address, this bit indicates whether or not the sector erase command is within the timeout period. The value that is read differs depending on the state.

When erasing sectors:

When erasing sectors, you can check whether the next sector erase code is ready to be accepted by checking this bit before inputting the next sector erase code. The the next value is read out without accessing the address specified for reading the hardware sequence flag.

"0"	Within sector erase wait period (the next sector erase code (0x30) can be accepted.)
"1"	When exceeding the sector erase wait period (if the DPOLL bit and TOGG1 bit indicate that the automatic algorithm is executing at this time, the flash memory internal erase is started. In this case, commands other than the sector erase code (0x30) are ignored until the flash memory internal erase finishes.)

[bit2] TOGG2: (Toggle Flag 2 bit)

In the sector erase suspend state, non target sector for erase can be read (read), but target sector for erase cannot be read. This flag indicates that output data is toggled and target sector for erase when read address is the target sector for erase during sector erase suspend.

Read out target erase sector	If this bit is read sequentially, "1" and "0" are read alternatively (toggle operation). The address specified for reading the hardware sequence flag is not accessed.
Read out non target erase sector	Read data from specified address

[bit1, bit0] Undefined bits

5.4. Reset Command

The reset command is shown below.

The flash memory can be reset by sending reset commands to the target flash memory. Because this state is the flash memory initial state, the flash memory always returns to the reset state when the power is turned on or a command finishes successfully. When the power is turned on, there is no need to issue a data read command. Furthermore, in reset state, data can be read using normal read access and programs can be accessed by the CPU; thus there is no need to issue the set command when reading data.

5.5. Write Command

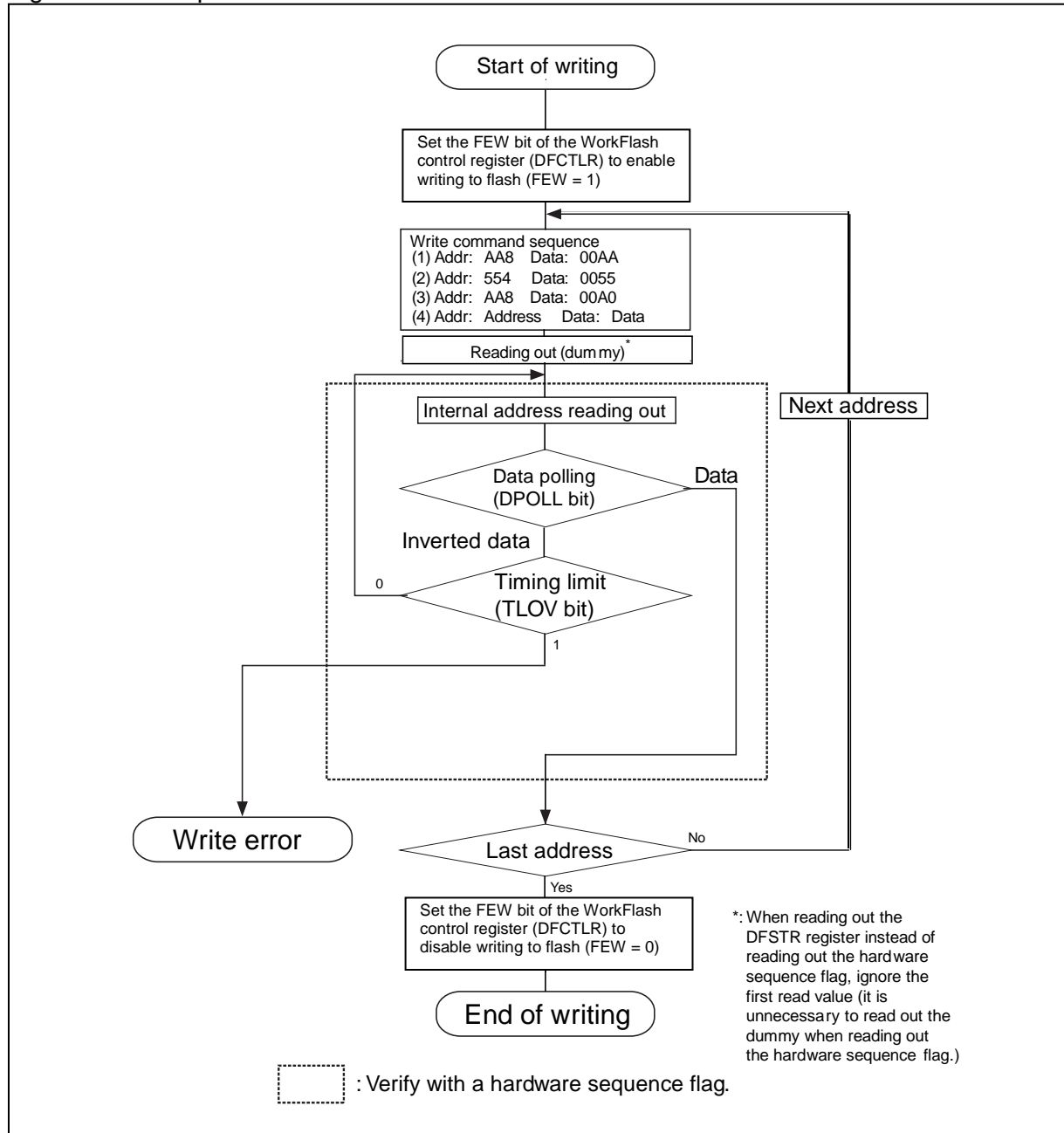
The write command is shown below.

Writes are performed in the following order.

1. Send write commands sequentially to the target sector
The automatic algorithm is started and data is written to the flash memory. After issuing a write command, there is no need to control the flash memory externally.
2. Perform read access to the written address
The read data is the hardware sequence flag. Therefore, if bit7 (DPOLL bit) of the read data matches the written data, the write to the flash memory has finished. If the write has not finished, the opposite value (inverted data) of the bit7's value of the last written data is read out.

The following figure shows an example of write operation to the flash memory.

Figure 5-2 Example of Write Procedure



Notes:

- If write completes, the write address is not accepted because the flash memory returns to the read mode.
- See "5.3 Automatic Algorithm" for details on the write command.
- Because the value of the DPOLL bit of the hardware sequence flag changes concurrently with the TLOV bit, check this bit again even if the value of the TLOV bit is "1".
- The moment when the TOGG1 bit of the hardware sequence flag and TLOV bit change to "1", the toggle operation stops. Therefore, even if the TLOV bit is "1", checking the TOGG1 bit again must be needed.
- Although the flash memory can be written to in any order of addresses, even if it crosses a sector boundary, only a single half-word data can be written in each write command sequence. If you want to write multiple data, issue one write command sequence for each data.
- Data that has been written to "0" once cannot be returned to "1". If "0" is rewritten with "1", one of the following occurs.
 - The element is judged as faulty by the data polling algorithm.

-The write rated time is exceeded, and the TLOV bit of the hardware sequence flag changes to "1".

-It appears to have been written as "1".

However, even if it appears to have been written as "1", the actual data remains "0" and "0" will be read out when the data is read in read/reset mode. If you want to return data to "1", perform a chip erase or sector erase.

- During write operations, all commands written to the flash memory are ignored.
 - If this series is reset during a write, the data that was written cannot be guaranteed.
 - Because this series has the ECC bit added, data always needs to be written as 32-bit by two 16-bit writes. See "5.2 Writing Flash Memory" for procedure.
-

5.6. Chip Erase Command

The chip erase command is shown below.

The erase target flash macros in the flash memory can be erased in one step using the chip erase command.

If the chip erase command is sent to the target sector sequentially, the automatic algorithm starts and all sectors of the flash memory can be erased in one step. See "5.3 Automatic Algorithm" for details on the chip erase command.

1. Send chip erase commands sequentially to a sector in the flash macro to erase.
The automatic algorithm is started and data is written to the flash memory.
2. Perform a read access to an arbitrary address in the flash macro to erase.
The read data is the hardware sequence flag. Therefore, when bit7 (DPOLL bit) of the read data is "1", the chip erase has finished.

The time required to erase the chip is [sector erasure time × total no. of sectors + chip write time (preprogram)]. When the chip erase operation finishes, the flash memory returns to the read/reset state.

Notes:

- When the automatic erase algorithm is started, "0" is written to all of the cells in the flash memory chip before erasing the entire chip, and there is no need to write to the flash memory before the chip erase to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.
 - When security is on, there are restrictions in the procedure for erasing the flash. See "5.9.3 Unlocking Flash Security" for details.
-

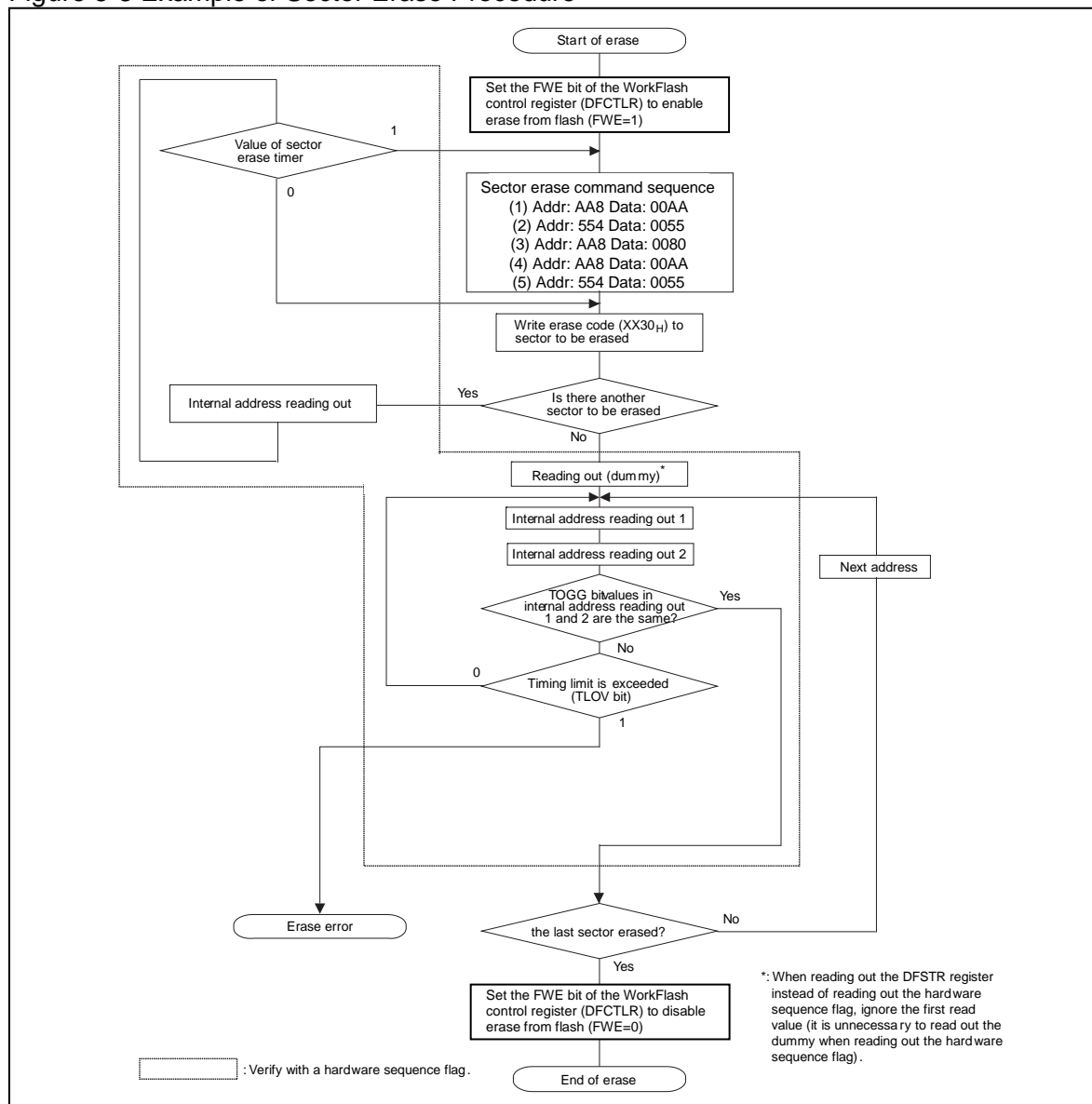
5.7. Sector Erase Command

The sector erase command is shown below.

A sector in the flash memory can be selected and only data in the selected sector can be deleted. Multiple sectors can also be specified at the same time. Sector erase is performed in the following order.

1. Send sector erase commands sequentially to the target sector
Once 40 μ s has elapsed (timeout period), the automatic algorithm starts and the sector erase operation is started. If you want to erase multiple sectors, write the erase code (30_H) to the address of the sector to erase within the 40 μ s (timeout period). If the write is performed after the timeout period has elapsed, the sector erase command may be invalid.
2. Perform read access to an arbitrary address
The read data is the hardware sequence flag. Therefore, when bit7 (DPOLL bit) of the read data is "1", the sector erase has finished. Furthermore, you can use the TOGG1 bit to check whether or not the sector erase has finished.
The following shows an example of the sector erase procedure taking the example of using the TOGG1 bit in the check operation.

Figure 5-3 Example of Sector Erase Procedure



Notes:

- The time required to erase the sector is [(sector erase time + sector write time (preprogram)) × no. of sectors].
- When the sector erase operation finishes, the flash memory returns to the read/reset state.
- See "5.3 Automatic Algorithm" for details on the sector erase command.
- Because the value of the DPOLL bit of the hardware sequence flag changes concurrently with the TLOV bit, check this bit again even if the value of the TLOV bit is "1".
- The moment when the TOGG1 bit of the hardware sequence flag and the TLOV bit change to "1", the toggle operation stops. Therefore, even if the TLOV bit is "1", checking the TOGG1 bit again must be needed.
- If commands other than sector erase command are issued while erasing a sector including the time out period, the flash memory becomes read/reset state. In this case, because the flash memory is reset, the sector erase command one or multiple prior to command that is issued is invalid. When sector erase is performed, reissue the sector erase command from scratch.
- When the automatic erase algorithm is started, "0" is written to the cells to erase in the flash memory before erasing the sector, and there is no need to write to the flash memory before erasing the sector to verify the margins (preprogramming). Furthermore, while verifying the margin, there is no need to control the flash memory externally.

5.8. Sector Erase Suspend Command

The sector erase suspend command is explained below

The sector erase can temporarily be stopped in the command time-out or while executing the sector erase.

The reading operation of the memory cell of the sector that is not the erase target becomes possible in the suspend condition of the sector erase. However, a new neither writing nor erase command is accepted.

The sector erase suspend command is sent to an arbitrary address of target FLASH macro to suspend of the sector erase.

After the sector erase stops, the reading operation from target FLASH macro is permitted.

At this time, the hardware sequence flag is read from the sector which is under the sector erase suspend condition.

It enters the following states when entering the sector erase suspend condition.

- The TOGG1 bit that does the toggle while erasing the sector does not toggle while being suspended from the sector erase operation.
- DFRDY of the WorkFlash status register becomes "1".

The thing that entered the sector erase suspend condition can be confirmed by using these.

Note:

16.7 μ s or less is required until the sector erase operation is stopped from the issue of the sector erase suspend command and reading from the sector that is not the erase target becomes possible.

Because bit2:TOGG2 of the hardware sequence flag does the toggle while the sector erase is temporarily stopping, the sector can be confirmed while stopping by using this bit.

To restart the interrupting erase operation from the sector erase suspend condition, the sector erase restart command in Table 5-1 is sent.

The sector erase restart command is accepted only by the sector erase suspend condition.

Send the command after confirming becoming the sector erase suspend condition.

Accepting the erase restart command, the flash memory comes back to the sector erase condition, resuming the erase operation.

5.9. Security Function

The security function is shown below.

This flash memory is equipped with a security function. When the security function is off, the flash memory can be used without limits. However, when the security function is on, the operation after an instruction fetches from the external bus, and writes and erases other than chip erase are suppressed. See "5.9.4 Flash Access Restrictions When Security is ON" for details of the restrictions.

5.9.1. Flash Security On/Off Determination When Reset Released

Flash security on/off determination when reset released is shown below.

For flash interface of this series, 2 bytes in the area of flash security code are read after releasing reset. When the value is 0x0001, security is ON and from then on access limitation to flash memory occurs. When the value is other than that, security becomes OFF.

5.9.2. Flash Security Setting Method

The flash security setting method is shown below.

If the input and the release of reset are done after 0x0001 is written in the flash security code area (see "Figure 3-2 Sector Block Diagram" in "CHAPTER : FLASH MEMORY"), it becomes security ON. If security is ON once, security does not become OFF without erasing all flash memory area.

5.9.3. Unlocking Flash Security

Unlocking flash security is shown below.

The chip erase command can be performed on all flash macros using the following procedure.

- (1) Erase WorkFlash.
- (2) Erase program flash which contains the flash security code.

Erase program flash last, as shown above. Otherwise, the erase command to program flash is ignored. Furthermore, if a reset is input between erases, repeat from step (1).

Note:

In the user-mode (internal FLASH activation), the erase command can be issued to an arbitrary flash macro, and data in the flash macro be deleted. The order of the chip erase to each flash macro is recommended to be executed from the viewpoint of the data protection stored in the flash macro as shown in the above-mentioned.

5.9.4. Flash Access Restrictions When Security is ON

Flash access restrictions when security is ON is shown below.

When security is on, the restrictions shown below are created by the start mode.

Table 5-3 Access Restrictions when Security is ON

Operating mode	Access restriction
User /External bus	<p>In normal mode (the state where there are no access restrictions due to the following flash security violations), there are no restrictions on access to FLASH memory.</p> <p>If an instruction fetch is performed to the on-chip bus area, a reset request is issued by the flash security violation reset source. Accesses to the flash memory are not accepted thereafter.</p> <p>The flash memory returns to normal state by reset.</p>
Other than aforementioned. (Writer, etc)	<p>Access to flash memory is restricted.</p> <p>The data from reads is masked and 0xFFFF_FFFF is returned. Write commands and sector erase commands are ignored.</p> <p>Chip erase commands are accepted. See "5.9.3 Unlocking Flash Security".</p>

5.10. Notes on Using Flash Memory

Notes on using the flash memory are shown below.

- If this device is reset during a write, the data that was written cannot be guaranteed.
- If CPU programming mode is set (FWE=1) using the FWE bit of the flash control register (DFCTLR), do not perform the program in flash memory. The program runs out of control without fetching the correct values.
- If CPU programming mode is set (FWE=1) using the FWE bit of the flash control register (DFCTLR) and the interrupt vector table is in flash memory, do not generate interrupt requests. The program runs out of control without fetching the correct values.
- Because this model has the ECC bit added, data always needs to be written as 32-bit by two 16-bit writes. See "5.2 Writing Flash Memory" for procedure.
- Concurrent commands (parallel) to multiple macros must not be issued. After checking the completion of command by the hardware sequence flag or DFRDY bit, command for the next macro must be input.
- If authentication by password of on-chip debugger (OCD) completes, you can read the content of flash memory from external by using OCD even if security is ON. When you want to stop reading by an outsider, password for on-chip debugger (OCD) activation approval must be configured.
- Changing to the state of the standby is a prohibition during FLASH program/erase.
- Because of the build-in ECC in this flash memory, the data superscription to the address where some values have already been written cannot be done.

CHAPTER : ON CHIP DEBUGGER (OCD)

This chapter explains the on chip debugger (OCD).

1. Overview
2. Features
3. Configuration
4. Registers
5. Operation

1. Overview

This section explains the overview of the on chip debugger (OCD).

This chapter explains an overview of the on chip debugger (OCD) in this series and the related specification restrictions.

OCDU is the device built-in debug support unit that provides the on-chip debug function in FR81. OCDU provides the basic debugger functions (CPU execution/break control, CPU register/memory/IO access), small-scale debug support functions (event, execution time measurement, trace, etc), and security function.

2. Features

This section explains features of the on chip debugger (OCD).

- One-wire debug tool I/F
- Debug security function
- Debug mode control function
- Execution control function
 - Status display functions (chip status, CPU status, etc)
 - Debug command execution control function
 - Small-scale debug main memory (8bytes=4 instructions)
 - CPU register save register (PC/PS)
 - PC monitor function
- Reset function
 - Chip reset (INT)
 - CPU reset (RST)
- Break function
 - Step execution break
 - Event trigger break
 - Forced break
 - Guarded access break
 - Trace end break
 - Control on interrupt acceptance immediately after the execution start address
- Debug DMA function (DDMA function)
 - Support of transfer modes (address mode, verify mode, DEBUG I/F burst transfer)
- Event function
 - Code event: 8
 - Conditional code event: 2
 - Data event: 8
 - Interrupt event: 2
 - User event: 2
 - Event sequencer: 2 levels + reset
- Execution time measurement timer function
 - Go-Break measurement
 - Inter-trigger measurement (single measurement/cumulative measurement)
- Trace function
 - Special state trace
 - Branch trace
 - Data trace
 - Trace delay
 - Number of trace frames: 512

3. Configuration

This section shows the configuration of the on chip debugger (OCD).

Figure 3-1 Block Diagram of OCDU

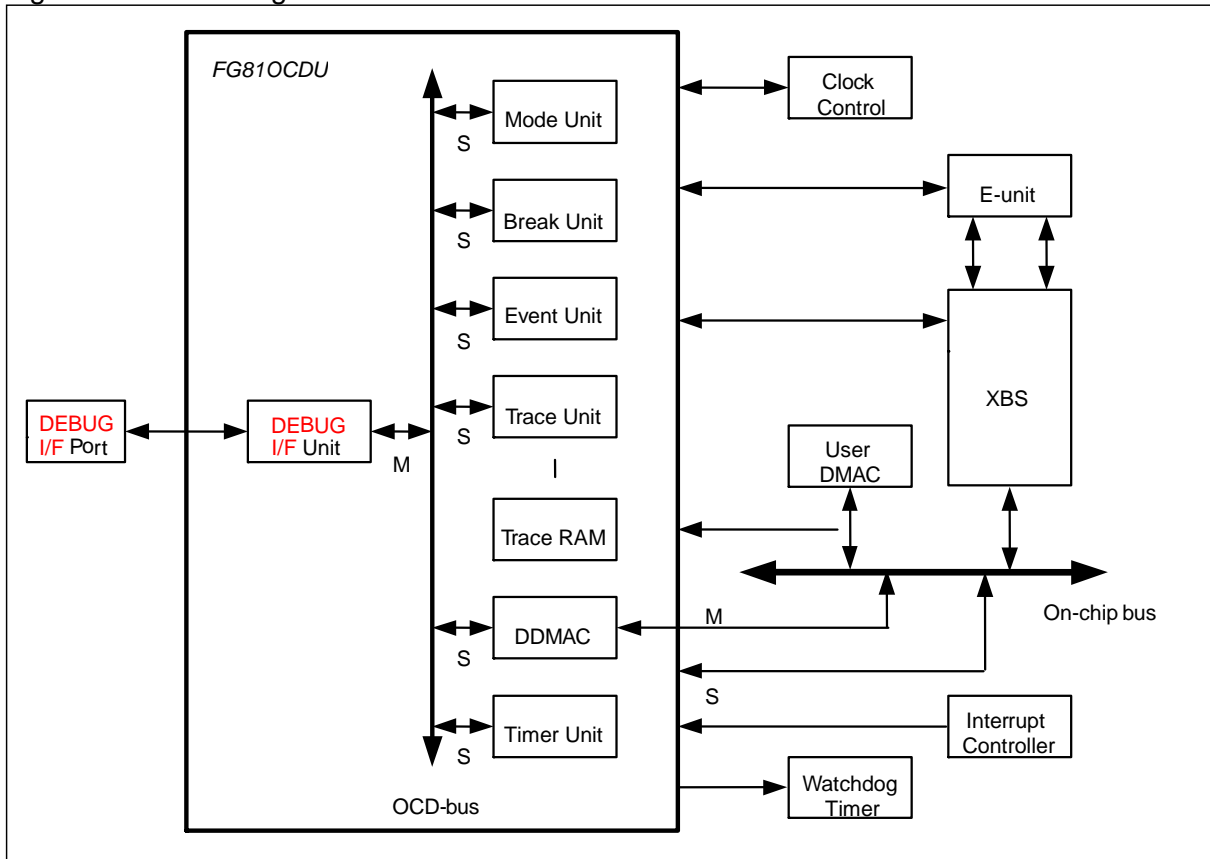
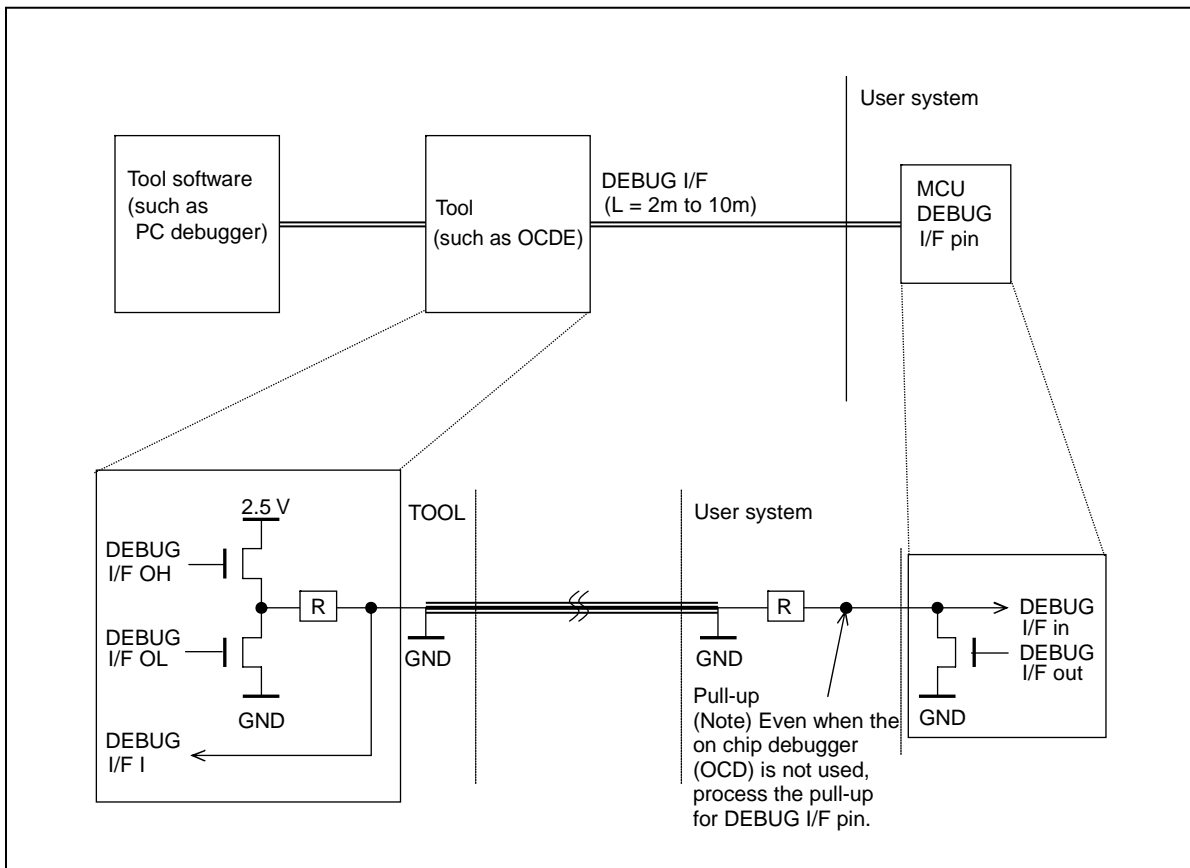


Figure 3-2 OCD Connection Diagram



3.1. DEBUG I/F Clock

DEBUG I/F clock is shown.

See "CHAPTER : CLOCK" for the clock connection configuration of the DEBUG I/F clock.

3.1.1. DEBUG I/F Main Clock (M_MCLK)

DEBUG I/F main clock (M_MCLK) is shown.

When OCD tool is connected, the main clock (MCLK) is supplied for DEBUG I/F main clock (M_MCLK).

When OCD tool is not connected, DEBUG I/F main clock (M_MCLK) stops.

3.1.2. DEBUG I/F PLL Clock (M_PCLK)

DEBUG I/F PLL clock (M_PCLK) is shown.

When the OCD tool is connected and the high-speed UART mode or phase modulation UART mode is selected, the PLL clock (PLLCLK) is supplied for DEBUG I/F PLL clock (M_PCLK).

When the OCD tool is connected and the high-speed UART mode or phase modulation UART mode is not selected, or when the OCD tool is not connected, DEBUG I/F PLL clock (M_PCLK) stops.

4. Registers

This section explains the registers of the on-chip debugger (OCD).

- 4.1 DBG Register
- 4.2 User IO Register

4.1. DBG Register

The bit configuration of the DBG register is shown.

Table 4-1 Register Map (DBG Register)

Address	Register				Register function
	+0	+1	+2	+3	
0xFF00	DSUCR		Reserved		DSU control register

■ DSU Control Register (DSUCR)

This register is used to control DSU in the free-run mode.

For details, contact our sales representative.

● DSUCR: Address FF00_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							DSU
Initial value	X	X	X	X	X	X	X	0
Attribute	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	R,W

4.2. User IO Register

The bit configuration of the User IO register is shown.

Table 4-2 Register Map (User IO Register)

Address	Register				Register function
	+0	+1	+2	+3	
0x0BFC	Reserved		UER		User event register

■ User Event Register (UER)

This register is used to detect a user event.

For details, contact our representative.

● UER: Address 0BFE_H (Access: Byte, Half-word, Word)

	bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8
	Reserved							
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0
	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved							UEVT
Initial value	X	X	X	X	X	X	X	X
Attribute	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W0	RX,W

5. Operation

This section explains the operation of the on-chip debugger (OCD).

- 5.1 OCDU Operating Mode
- 5.2 Overview of DEBUG I/F
- 5.3 Specification Restrictions at Connection to OCD Tool of This Series
- 5.4 OCD-DSU ID Code and Mount Type Information on This Series

5.1. OCDU Operating Mode

OCDU operating mode is shown.

- 5.1.1 Operating Mode
- 5.1.2 Operating Mode Status Transition

5.1.1. Operating Mode

Operating mode is shown.

The OCDU operating mode includes emulator mode and free-run mode.

- Emulator mode (debug running status)

The emulator mode consists of the debug state for executing the debug instruction and the user state for executing a user program. If the RETI instruction is executed in the debug state, control transits to the user state. If a break occurs in the user state, control transits to the debug state.

- Free-run mode (normal running status)

Mode in which only the user program runs

5.1.2. Operating Mode Status Transition

Operating mode status transition is shown.

At INIT releasing (including RST accompanied by INIT), control transits to the debug state of the emulator mode or to the free-run mode according to the mode command from DEBUG I/F in the chip reset sequence.

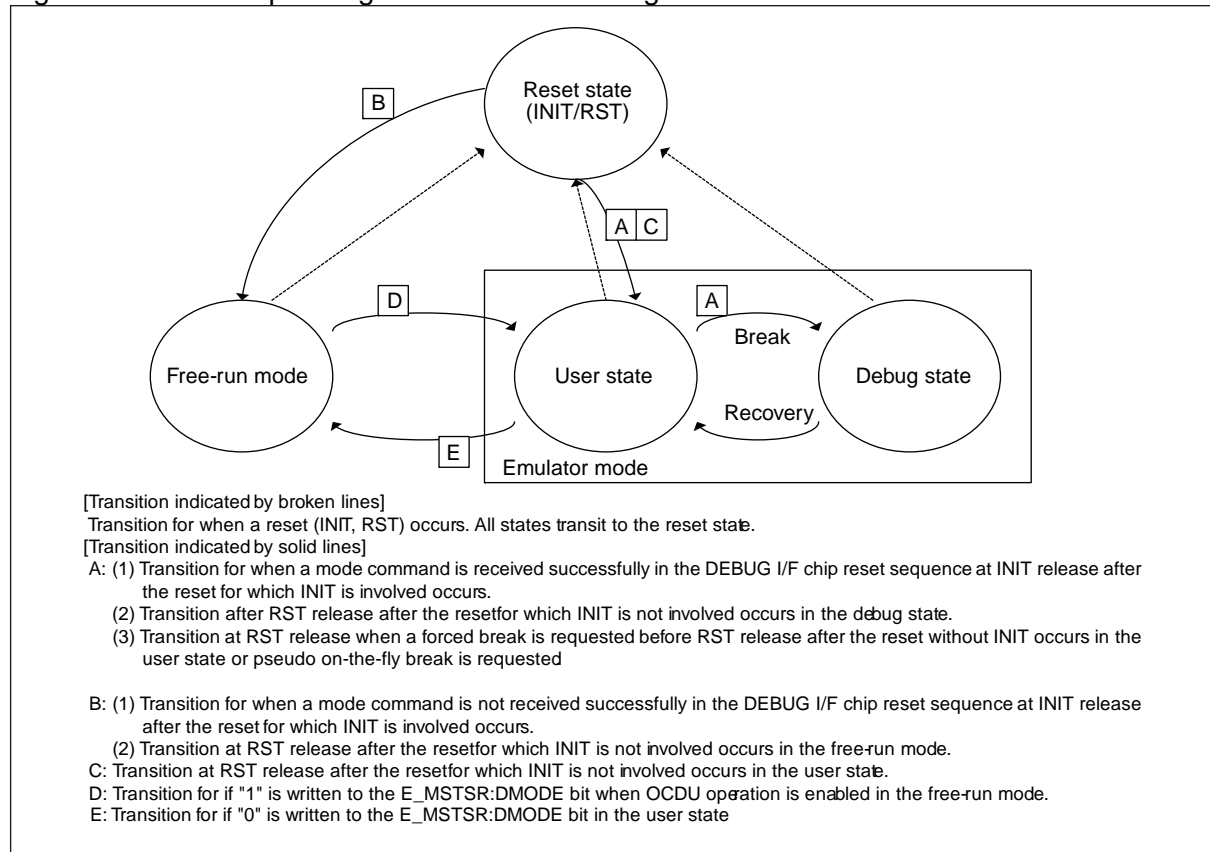
At RST releasing (not accompanied by INIT), control transits to the operating mode occurring before RST generation. However, if a forced break request is issued after RST occurs in the user state, control transits to the debug state of the emulator mode at RST releasing.

Moreover, transition between the free-run mode and user state of emulator mode is enabled by OCD register control.

At transition from the reset status to the debug state, control first transits to the user state. In this case, requesting a break by OCDU makes the following transition:
reset status → user state → (break) → debug state.

The transition conditions are shown below.

Figure 5-1 OCDU Operating Mode Transition Diagram



5.2. Overview of DEBUG I/F

The overview of DEBUG I/F is shown.

DEBUG I/F is a single-wire debug interface that connects MCU to a tool via one wire (+GND). MCU uses one pin as the one for the debug interface.

DEBUG I/F is a two-way pin and provides the communication function and special sequence function. Communication uses the serial transmission method (UART). In the normal UART mode, the communication baud rate is obtained by division clocks that are based on the main source oscillation clock of MCU. In the high-speed UART mode and in phase modulation UART (Manchester encode UART), the division clock is based on the PLL clock. The special sequence includes chip reset sequence and stall. There are the function that MCU notifies the INIT generation and the function to detect the debug mode that activated after releasing INIT in the chip reset sequence. The stall function provides communication stall and forced break requests from the tool, and communication error notification from MCU.

The main DEBUG I/F functions are shown below.

- Chip reset sequence function (INIT notification, mode command)
- UART function (normal UART, high-speed UART, phase modulation UART)
- Stall request (communication stall request, forced break request, communication error notification)

The two-way pin of DEBUG I/F is accomplished by N-ch open-drain output. The DEBUG I/F pin is pulled up on a user system. It is pulled up with a tool during tool connection.

For the tool connection, see Figure 3-2 .

5.2.1. Chip Reset Sequence

Chip reset sequence is shown.

When INIT is generated, OCDU executes the chip reset sequence according to the specification of DEBUG I/F. A reference clock that executes the chip reset sequence is a sampling clock of the normal UART (8 division clock of the main source oscillation clock).

The chip reset sequence consists of the following 5 phases:

- Start phase
- INIT phase
- Level sense phase
- Mode entry phase
- End phase

● Start phase

Start phase is the interval when the generated INIT is released until 32 sampling clock cycles of the normal UART is counted. OCDU does not perform the special operation in this phase.

● INIT notification phase

INIT notification phase is the interval when the start phase is ended until 480 sampling clock cycles of the normal UART is counted. OCDU outputs L to MDI and notifies the generation of INIT to the tool in this phase.

● Level sense phase

Level sense phase is the interval when the INIT notification phase is ended until 256 sampling clock cycles of the normal UART is counted. OCDU does not perform the special operation in this phase.

● Mode entry phase

Mode entry phase is the interval when the level sense phase is ended until 256 sampling clock cycles of the normal UART is counted. OCDU starts the reception of the mode command from the tool in this phase.

When starting reception of the mode command is detected (start bit detected in the UART reception) in this phase, OCDU activates in the emulator mode (debug state). Then, if the normal mode command (no reception error and mode command match) is received, OCDU can receive the subsequent register access command after this. If the normal mode command (reception error and no mode command match) is not received, OCDU generates INIT request and executes the chip reset sequence again after INIT is released.

When starting reception of the mode command is not detected (start bit detected in the UART reception) in this phase, OCDU activates in the free-run mode.

If the mode command is received immediately after starting the mode entry phase, the mode command must be received after waiting one cycle or more for inputting H to MDI using the UART reception sampling clock. If this condition is not met, the start bit of the mode command reception cannot be detected normally, the mode may not be entered correctly.

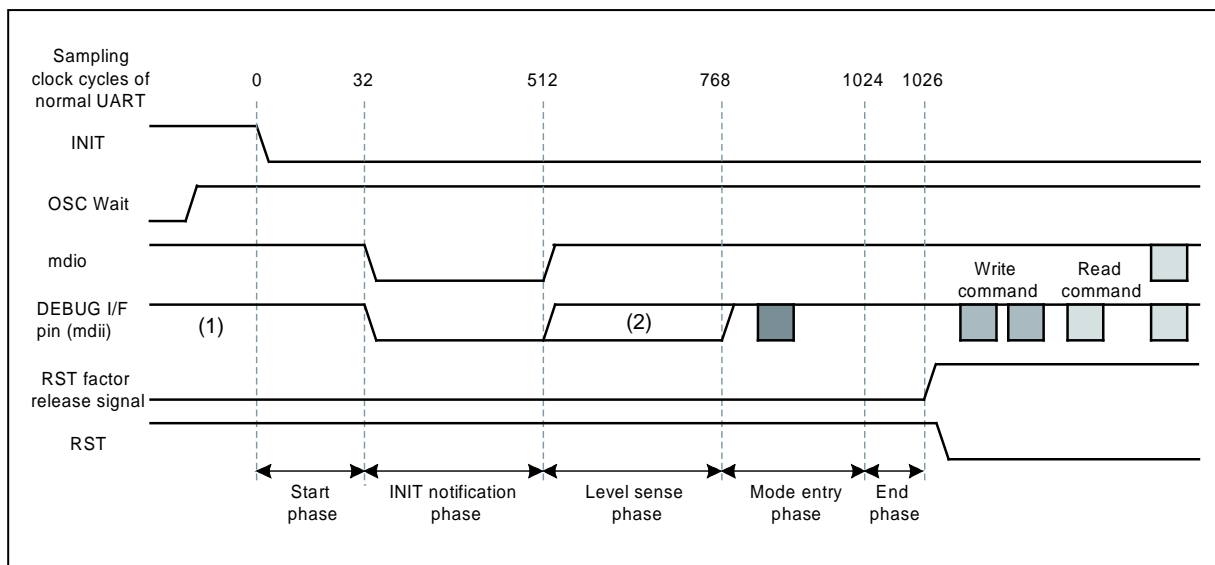
● End phase

End phase is the interval when the mode entry phase is ended until 2 sampling clock cycles of the normal UART is counted. OCDU does not perform the special operation in this phase. OCDU executes the reset issuance sequence described in "5.4.3 Reset (RST)" of "CHAPTER : RESET" when the end phase is ended. The RST factor is released.

The relationship between the number of sampling clock cycles of the normal UART and the phase for the chip reset sequence is as follows.

Phase of chip reset sequence	Start phase	INIT notification phase	Level sense phase	Mode entry phase	End phase
Sampling clock cycles of the normal UART from INIT release	1 - 32	33 - 512	513 - 768	769 - 1024	1025, 1026

The following shows the chip reset sequence.



OSC Wait: Oscillation of main source oscillation clock is stabilized. INIT is released after the oscillation stabilization is confirmed.

- (1) : DEBUG I/F is set to H level by pull-up processing of the tool.
- (2) : DEBUG I/F becomes the level of pull-up processing on the user system.

5.2.2. Security Function

Security function is shown.

OCDU has the security function. OCDU enables the security function by setting the security information stored in a debug security area of the memory space in CPU. If the security function is enabled, OCDU enters the security lock state. To release this, the security is unlocked by writing a password set in the security information to the number of specified length and the E_SLPR register.

■ Security Information

The debug security area is allocated at 30 bytes of built-in flash start address+4 to +33. For OCDU, see this area using the security sequence.

The following security information is available for the debug security area.

- Security password length (PW length)
The security password length is 16-bit data in the start address of the debug security area, and the lower 4 bits are the enabled PW length. The upper 12 bits have no effect on operation. If the PW length is 0x0 or 0xF, the security is disabled. If the PW length is 0x1 to 0xE (1 to 14), the security is enabled.
- Security password (PW)
The security password is 16-bit data in the debug security area. 14 areas that writes data are provided. The PW is assigned from an address next to the PW length address, in the order of PW1, PW2,... PW14 (See figure below). If the security is enabled (PW length:1 to 14), the value of the PW length indicates the enabled PW.
(Example : If the PW length is 8, PW1 to PW8 are enabled, and PW9 to PW14 are disabled.)

Address	15	0
ROM/Flash start address +4	PW length	
ROM/Flash start address +6	PW1	
ROM/Flash start address +8	PW2	
...	...	
ROM/Flash start address +32	PW14	

Note:

If the security function of the on chip debugger (OCD) is not used, nothing is written to this area and the initial state(all bits=1) immediately after flash erase is retained.

5.3. Specification Restrictions at Connection to OCD Tool of This Series

Specification restrictions at connection to OCD tool of this series is shown.

The following restrictions are placed at OCD tool connection:

5.3.1. Clock Setting

Clock setting is shown.

- The registers listed below are not initialized by the RST-level reset when the high-speed UART and phase modulation UART modes are selected at OCD tool connection. They are initialized at the INIT-level reset.
 - CSELR
 - CMONR
 - PLLCR
 - CSTBR
- The main clock oscillation does not stop. Writing to CSELR:MCEN bit does not influence operation. The read value is always "1". CMONR:MCRDY bit is always "1" when read.
- The main clock oscillation stabilization wait timer does not run because of CMONR:MCRDY=1.
- The main timer (used as the general-purpose timer) runs.
- PLL oscillation does not stop when OCD high-speed UART and phase modulation UART communication are enabled. Writing to CSELR:PCEN bit does not influence operation. The read value is always "1". CMONR:PCRDY bit is "1" when read. The following shows the operation after the RST-level reset is released when the OCD high-speed UART and phase modulation UART communication are enabled:
 - PLL oscillation stabilization (CMONR:PCRDY=1) continues after a return from the reset.
 - The source clock selection is the same as before the reset.
 - The PLL oscillation stabilization wait timer does not run because of CMONR:PCRDY=1.

5.3.2. Standby Mode

Standby mode is shown.

- Even if the watch mode is entered, PLL oscillation does not stop when OCD high-speed UART and phase modulation UART communication are enabled.
- The main clock oscillation does not stop even if the stop mode is entered. PLL oscillation does not stop when OCD high-speed UART and phase modulation UART communication are enabled. During sub clock oscillation, the sub clock does not stop and oscillation continues.
- The following shows the functions that differ in operation when the OCD tool is not connected, according to the above restrictions:
 - CAN operation continues in the watch mode and stop mode when PLL is stopped down (CSELR:PCEN=0) or OCD high-speed UART and phase modulation UART communication are enabled. (This operation is performed within the range in which no CPU processing occurs.)
 - In the stop mode, the LCD controller operates in the same way as in the watch mode.
 - The real-time clock continues operating even during stop mode.
 - The counter operation for the RTC/WDT1 calibration continues in the stop mode.
 - When the high-speed UART mode and phase modulation UART mode are selected, an illegal standby mode transition detection reset will not be generated.
- The following functions perform the same operations as those when the OCD tool is not connected, with the above restrictions not placed:
 - The main timer and sub timer do not run in the stop mode because they are cleared in that mode.
 - The power consumption in the watch mode becomes greater than that when the OCD tool is not connected because the PLL clock oscillation continues.
 - The power consumption in the stop mode becomes greater than that when the OCD tool is not connected because the PLL clock, main clock, and sub clock oscillation continue.

5.3.3. CAN Prescaler Register

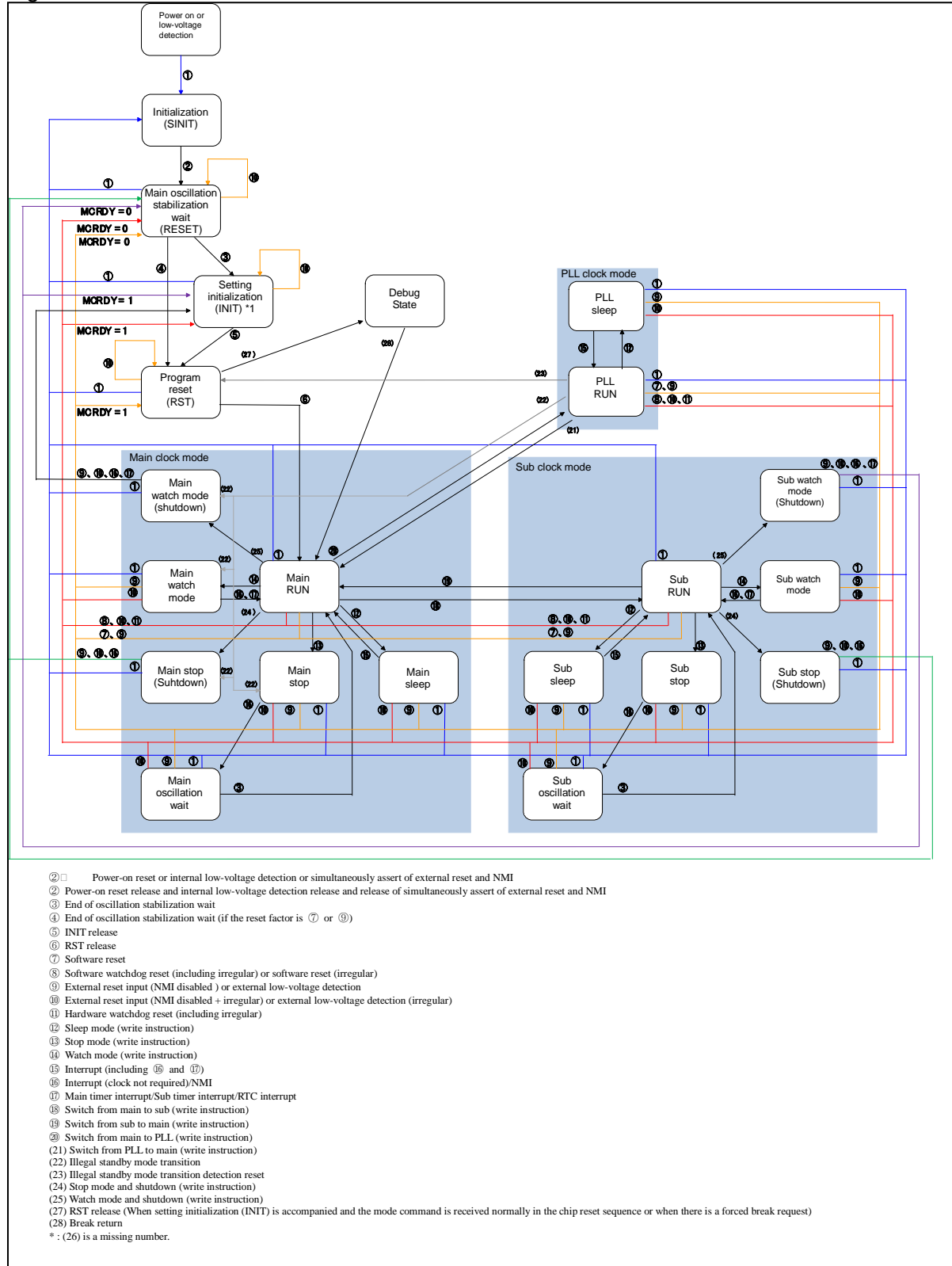
CAN prescaler register is shown.

When the OCD tool is connected, and the high-speed UART mode and phase modulation UART mode are selected, the CAN prescaler register (CANPRE) is not initialized by an RST-level reset. It is initialized by an INIT-level reset.

5.3.4. Clock Reset State Transitions

Clock reset state transitions is shown.

Figure 5-2 Device State



*1 : There is a register not reset when returning from the watch mode (Shutdown) and returning from the stop mode (Shutdown). See " Limitations of power shutdown and normal standby control" of "CHAPTER : POWER

CONSUMPTION CONTROL" for details.

Note:

As single clock products do not have sub clock input, they do not make a transition to the sub clock mode.

5.3.5. Summary of Specification Restrictions

Summary of specification restrictions is shown.

1) Communication mode (*1): Normal UART

Note: Debug the standby mode (stop mode) when the OCD tool is not connected.

Reset factor	Difference from when the OCD tool is not connected		Remarks	
	Initialization range	Processing time		
Power-on reset	No	Yes	Causes a transition to the emulator mode (debug state) after reset is released	
RSTX pin input (irregular)				
RSTX pin input			No voltage step-down circuit switch stabilization wait time (*2) *: Only recovery from main/sub stop mode or main/sub watch mode No main oscillation stabilization wait time *: Only recovery from main/sub stop mode or sub watch mode	
RSTX pin input (+NMIX pin input)			Causes a transition to the emulator mode (debug state) after reset is released	
Watchdog reset 0 (irregular)				
Watchdog reset 0				
Watchdog reset 1 (irregular)				
Watchdog reset 1				
External low voltage detection reset (irregular)				
External low voltage detection reset			No voltage step-down circuit switch stabilization wait time (*2) *: Only recovery from main/sub stop mode or main/sub watch mode No main oscillation stabilization wait time *: Only recovery from main/sub stop mode or sub watch mode	
Illegal standby mode transition detection reset (irregular)			Causes a transition to the emulator mode (debug state) after reset is released	
Illegal standby mode transition detection reset			No	
Internal low voltage detection reset			Yes	Causes a transition to the emulator mode (debug state) after reset is released
Flash security violation reset (irregular)				

Reset factor	Difference from when the OCD tool is not connected		Remarks
	Initialization range	Processing time	
Flash security violation reset		No	
Software reset (irregular)		Yes	Causes a transition to the emulator mode (debug state) after reset is released
Software reset		No	

Interrupt factor	Processing time difference from when the OCD tool is not connected	Remarks
All interrupts	Yes	No voltage step-down circuit switch stabilization wait time (*2) *: Only recovery from main/sub stop mode or main/sub watch mode No main oscillation stabilization wait time *: Only recovery from main/sub stop mode or sub watch mode No sub oscillation stabilization wait time *: Only recovery from main/sub stop mode

Device states other than those related to reset	Operation difference from when the OCD tool is not connected	Remarks
Main RUN/main sleep mode	No	
PLL RUN/PLL sleep mode		
Sub RUN/sub sleep mode	Yes	Main oscillation continues (*3)
Main/sub stop mode		Voltage step-down circuit is fixed Main oscillation continues Sub oscillation continues Operation continues (LCD controller, real-time clock, RTC/WDT1 calibration counter operation)
Main/sub watch mode		Voltage step-down circuit is fixed Main oscillation continues *: Sub watch mode

- 2) Communication mode (*1): High-speed UART/phase modulation UART
Note: If you are to perform clock settings or debug standby mode (watch mode) or illegal standby mode transition detection, use the normal UART for the communication mode.

Reset factor	Difference from when the OCD tool is not connected		Remarks
	Initialization range	Processing time	
Power-on reset	No		Causes a transition to the emulator mode (debug state) after reset is released
RSTX pin input (irregular)			
RSTX pin input	Yes	Yes	No voltage step-down circuit switch stabilization wait time (*2) *: Only recovery from main/sub stop mode or main/sub watch mode No main oscillation stabilization wait time *: Only recovery from main/sub stop mode or sub watch mode No sub oscillation stabilization wait time *: Only recovery from main/sub stop mode No PLL oscillation stabilization wait time Retains clock setting register (*4)
RSTX pin input (+NMIX pin input)			
Watchdog reset 0 (irregular)			
Watchdog reset 0			
Watchdog reset 1 (irregular)			
Watchdog reset 1			
External low voltage detection reset (irregular)	No	Yes	Causes a transition to the emulator mode (debug state) after reset is released
External low voltage detection reset			
External low voltage detection reset	Yes	Yes	No voltage step-down circuit switch stabilization wait time (*2) *: Only recovery from main/sub stop mode or main/sub watch mode No main oscillation stabilization wait time *: Only recovery from main/sub stop mode or sub watch mode No sub oscillation stabilization wait time *: Only recovery from main/sub stop mode No PLL oscillation stabilization wait time Retains clock setting register (*4)
External low voltage detection reset			
Illegal standby mode transition detection reset (irregular)	-	-	
Illegal standby mode transition detection reset			
Internal low voltage detection reset	No	Yes	Causes a transition to the emulator mode (debug state) after reset is released
Flash security violation reset (irregular)			

Reset factor	Difference from when the OCD tool is not connected		Remarks
	Initialization range	Processing time	
Flash security violation reset	Yes	Yes	No PLL oscillation stabilization wait time Retains clock setting register (*4)
Software reset (irregular)	No		Causes a transition to the emulator mode (debug state) after reset is released
Software reset	Yes		No PLL oscillation stabilization wait time Retains clock setting register (*4)

Interrupt factor	Processing time difference from when the OCD tool is not connected	Remarks
All interrupts	Yes	No voltage step-down circuit switch stabilization wait time (*2) *: Only recovery from main/sub stop mode or main/sub watch mode No main oscillation stabilization wait time *: Only recovery from main/sub stop mode or sub watch mode No sub oscillation stabilization wait time *: Only recovery from main/sub stop mode No PLL oscillation stabilization wait time

Device states other than those related to reset	Operation difference from when the OCD tool is not connected	Remarks
Main RUN/main sleep mode	Yes	PLL oscillation continues (*5)
PLL RUN/PLL sleep mode	No	
Sub RUN/sub sleep mode	Yes	Main oscillation continues (*3) PLL oscillation continues (*5)
Main/sub stop mode		Voltage step-down circuit is fixed Main oscillation continues Sub oscillation continues PLL oscillation continues (illegal standby mode transition detection is disabled) Operation continues (CAN, LCD controller, real-time clock, RTC/WDT1 calibration counter operation)
Main/sub watch mode		Voltage step-down circuit is fixed Main oscillation continues *: Sub watch mode PLL oscillation continues (illegal standby mode transition detection is disabled) Operation continues (CAN)

*1: For communication mode settings, see "SOFTUNE Workbench Operating Manual".

*2: Voltage step-down circuit stabilization wait time: about 6μs

*3: Writing to the main clock oscillation enable bit (CSELR:MCEN) is disabled

*4: Clock source setting register (CSELR), clock source monitor register (CMONR), PLL setting register (PLLCR), oscillation stabilization wait setting register (CSTBR), CAN prescaler register (CANPRE)

*5: Writing to the PLL oscillation enable bit (CSELR:PCEN) and PLL setting register (PLLCR) is disabled

5.4. OCD-DSU ID Code and Mount Type Information on This Series

OCD-DSU ID code and mount type information of this series are shown.

Table 5-1 OCD-DSU ID Code of This Series

ID name	bit width	Associated ID register name	Address in the OCD space	Value	Remarks
Manufacturer ID	16	E_IDMCR	0x000	0x0400	Fujitsu code
CPU family ID	16	E_IDFCR	0x001	0x0200	FR81E/FR81S
DSU type ID	8	E_IDVCR	0x003	0x06	
DSU version ID	4	E_IDVCR	0x003	0x1	
Device ID	16	E_IDDCR	0x002	*	* MB91F591: 0x0015 MB91F592: 0x0015 MB91F594: 0x0015 MB91F596: 0x0015 MB91F597: 0x0015 MB91F599: 0x0015
Device version ID	4	E_IDVCR	0x003	0x1	

Table 5-2 Mount Type Information of This Product Type

Product name	Number of code events	Number of data events	Data event (Compare)	Sequencer event	Trace
MB91F591 MB91F592 MB91F594 MB91F596 MB91F597 MB91F599	8	8	○	○	512 frames

CHAPTER: GDC EXTERNAL CONTROL

This chapter explains the GDC external control.

1. Overview
2. Features
3. Configuration
4. Registers
5. Note

1. Overview

The overview of the GDC external control is shown.

In this block, the following four functions are provided.

1. The setting needed to activate/stop the GDC function is done.
2. The execution trigger of the command list is put.
3. The count number of the wait trigger is decreased.
4. ECC function installed in Command RAM is set.

2. Features

Features of the GDC external control is shown.

- **Reset control**

GDC function controls activate/stop.

- **FLASH access control**

The FLASH access control selects the data interface that GDC uses. 16-bit bus or SPI can be selected as external FLASH.

- **Command RAM ECC control**

ECC function installed in Command RAM of the GDC macro is controlled.

- **Boot control function**

The boot sequence is set after reset of the GDC macro is released.

- **Wait/Priority control**

Trigger/Wait/ Priority control

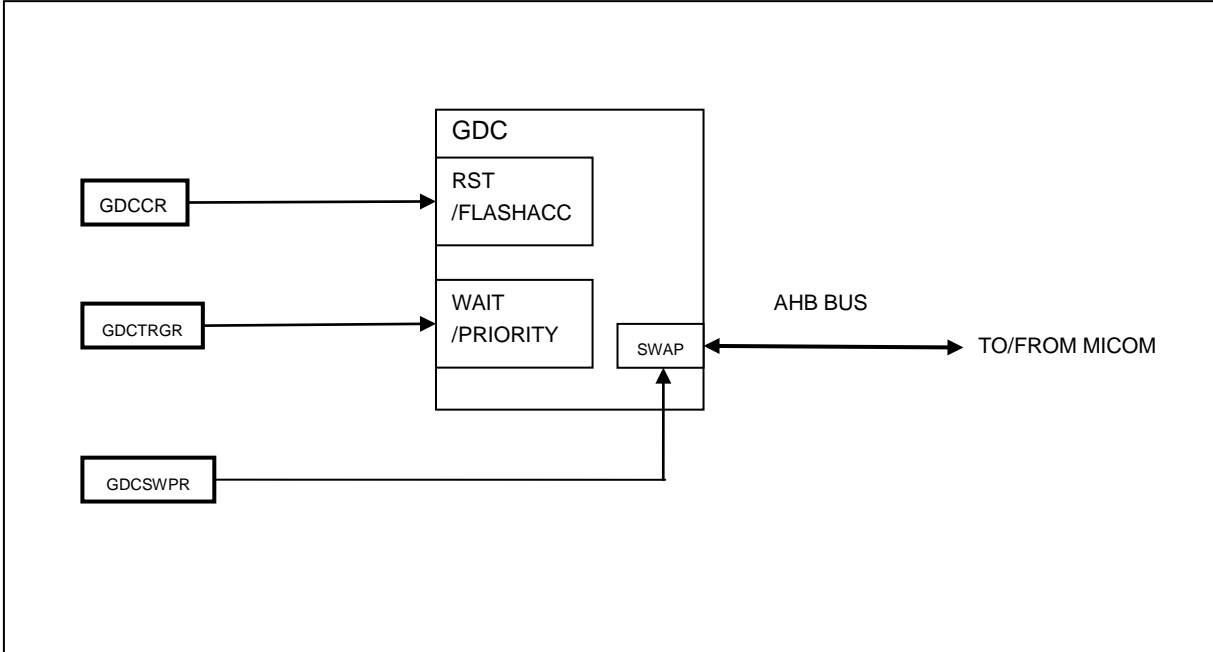
- **Bus/Swap function**

GDC is little endian. The arrangement of the internal register can be changed to the access by the microcontroller.

3. Configuration

The configuration of the GDC external control is shown.

Figure 3-1 Block Diagram



4. Registers

Registers of the GDC external control are shown.

Table 4-1 Registers Map

Address	Registers				Register function
	+0	+1	+2	+3	
0x0F64	Reserved	GDCCR	GDCTRGR	GDCSWPR	GDC control register GDC trigger register GDC swap setting register

4.1. GDC Control Register : GDCCR

The bit configuration of the GDC control register is shown.

This register controls GDC.

■ GDCCR : Address 0F65_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved		MEM[1:0]		ECCDIV	ECC	BOOT	GRST
Initial value	0	0	0	0	0	0	0	1
Attribute	R0/WX	R0/WX	R/W	R/W	R/W	R/W	R/W	R/W

[bit7, bit6] Reserved

[bit5, bit4] MEM[1:0] : External memory interface mode selection bits

The external memory interface is selected from either External Flash / SPI Flash.

* Sets these bits before GRST=0 (GDC reset release).

MEM[1:0]	Description
00	External Flash
01	SPI Flash
1x	Setting is prohibited

[bit3] ECCDIV : Command RAM ECC clock divide mode selection bit

This bit selects dividing the clock accessed ECC macro and Command RAM when the ECC function is used (ECC bit =1).

Always select the doing no divide clock.

ECCDIV	Description
0	No divide clock
1	2 division clock

[bit2] ECC : Command RAM ECC mode selection bit

This bit selects whether to use ECC function for Command RAM.

* Sets this bit when you do not access Command RAM.

ECC	Description
0	No use of ECC function
1	Use of ECC function

[bit1] BOOT : CMDSEQ BOOT start mode selection bit

This bit controls that CMDSEQ accesses/no-access external Flash after releasing GDC reset.

* Sets this bit before GRST=0 (GDC reset release).

BOOT	Description
0	After reset is released, it accesses external Flash.
1	After reset is released, it does not access external Flash.

[bit0] GRST : GDC reset control bit

This bit controls reset of the GDC macro.

GRST	Description
0	Release of reset
1	Setting of reset

4.2. GDC Trigger Register : GDCTRGR

The bit configuration of the GDC trigger register is shown.

It is a function to control the following.

- The execution trigger of the GDC command list arranged in the command memory is put.
(bit field : bit1, bit0)
- The waiting number of times set by the wait trigger command of GDC is decreased.
(bit field : bit7 to bit4)

■ GDCTRGR : Address 0F66_H (Access : Byte, Half-word, Word)

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	WAITEN 15	WAITEN 14	WAIT15	WAIT14	Reserved		TRG13	TRG12
Initial value	0	0	0	0	0	0	0	0
Attribute	R/W	R/W	R/W	R/W	R0/WX	R0/WX	R/W	R/W

[bit7] WAITEN15 : Wait processing factor 15 enable setting bit

This bit sets permission/prohibition of wait processing factor 15.

WAITEN15	Description
0	No use of wait processing factor 15
1	Use of wait processing factor 15

[bit6] WAITEN14 : Wait processing factor 14 enable setting bit

This bit sets permission/prohibition of wait processing factor 14.

WAITEN14	Description
0	No use of wait processing factor 14
1	Use of wait processing factor 14

[bit5] WAIT15 : Wait processing factor 15 trigger setting bit

This bit supplies the set value to the GDC macro for wait processing factor 15.

[bit4] WAIT14 : Wait processing factor 14 trigger setting bit

This bit supplies the set value to the GDC macro for wait processing factor 14.

[bit3, bit2] Reserved

[bit1] TRG13 : Priority 4 trigger start factor setting bit

This bit supplies the value in which start factor 13 of priority 4 triggers is set to each bit to the GDC macro.

[bit0] TRG12 : Priority 4 trigger start factor setting bit

This bit supplies the value in which start factor 12 of priority 4 triggers is set to each bit to the GDC macro.

4.3. GDC Swap Setting Register : GDCSWPR

The bit configuration of the GDC swap setting register is shown.

It is an insertion swap function of address/data when CPU accesses the bus in the GDC macro.

■ **GDCSWPR : Address 0F67_H (Access : Byte, Half-word, Word)**

	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
	Reserved			ADSWP	WSWP	HSWP[1:0]		BSWP
Initial value	0	0	0	0	0	1	0	1
Attribute	R0,WX	R0,WX	R0,WX	R/W	R/W	R/W	R/W	R/W

* Sets this register before GDCCR:GRST=0 (GDCRST release).

[bit7 to bit5] Reserved

[bit4] ADSWP : Address swap control bit

When the word access, the half-word access, and the byte access, this bit controls the address as follows.

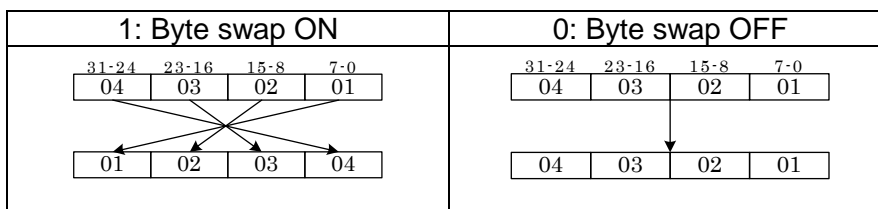
- Word access : The input address is output as it is.
ex) input:0x0000_0000 -> output:0x0000_0000
- Half-word access : The second bit from the subordinate position of the input address is reversed and output.
ex) input:0x0000_0000 -> output:0x0000_0002
- Byte access : lower 2-bit of the input address are reversed and output.
ex) input:0x0000_0000 -> output:0x0000_0003

ADSWP	Description
0	Address swap OFF
1	Address swap ON

[bit3] WSWP : Word access swap control bit

This bit controls the half-word swap and byte swap when the word is accessed to GDC_AHB.

It is possible to control as follows.



It is possible to set it as follows.

WSWP	Word access swap control
0	Byte swap OFF
1	Byte swap ON

[bit2, bit1] HSWP[1:0] : Half-word access swap control bits

This bit controls byte swap when the half-word swap and the half-word are accessed for GDC_AHB.

It is possible to control as follows.

11: Half-word swap ON, Byte swap ON	10: Half-word swap ON, Byte swap OFF
01 : Half-word swap OFF, Byte swap ON	00 : Half-word swap OFF, Byte swap OFF

It is possible to set it as follows.

HSWP[1:0]	Byte swap and Half-word swap control
00	Half-word swap OFF, Byte swap OFF,
01	Half-word swap OFF, Byte swap ON
10	Half-word swap ON, Byte swap OFF
11	Half-word swap ON, Byte swap ON,

[bit0] BSWP : Byte access swap control bit

This bit controls byte swap for GDC_AHB.

It is possible to control as follows.

1: Byte swap ON	0: Byte swap OFF

It is possible to set it as follows.

BSWP	Byte swap control
0	Byte swap OFF
1	Byte swap ON

5. Note

Note of the GDC external control is shown.

After releasing GDC reset (0x0F65 GDCCR register bit0:GRST), the GDC macro processes BOOT. When it accesses the GDC macro while processing BOOT, operation is not guaranteed.

The completion of the BOOT processing is notified by the interrupt. Access the GDC macro after confirming the generations of the following interrupt.

The GDC interrupt request: 0x0424 IRPR6H register bit7 GDC (See "CHAPTER : INTERRUPT REQUEST BATCH READ").

Confirm the following register is read by the first access and a pertinent bit is set though the access to the GDC macro becomes possible after confirming the above-mentioned.

GDC interrupt factor: 0x023B_2100 INTST register bit0:INT0

APPENDIX

The appendix is shown.

- A. Memory Map
- B. I/O Map
- C. List of Interrupt Vector
- D. Pin Status in CPU Status

Code : 45_MB91590_HM_E_appendix_005_20111127

A. Memory Map

Memory maps are shown below.

■ Memory Map

Figure A-1 Memory Map

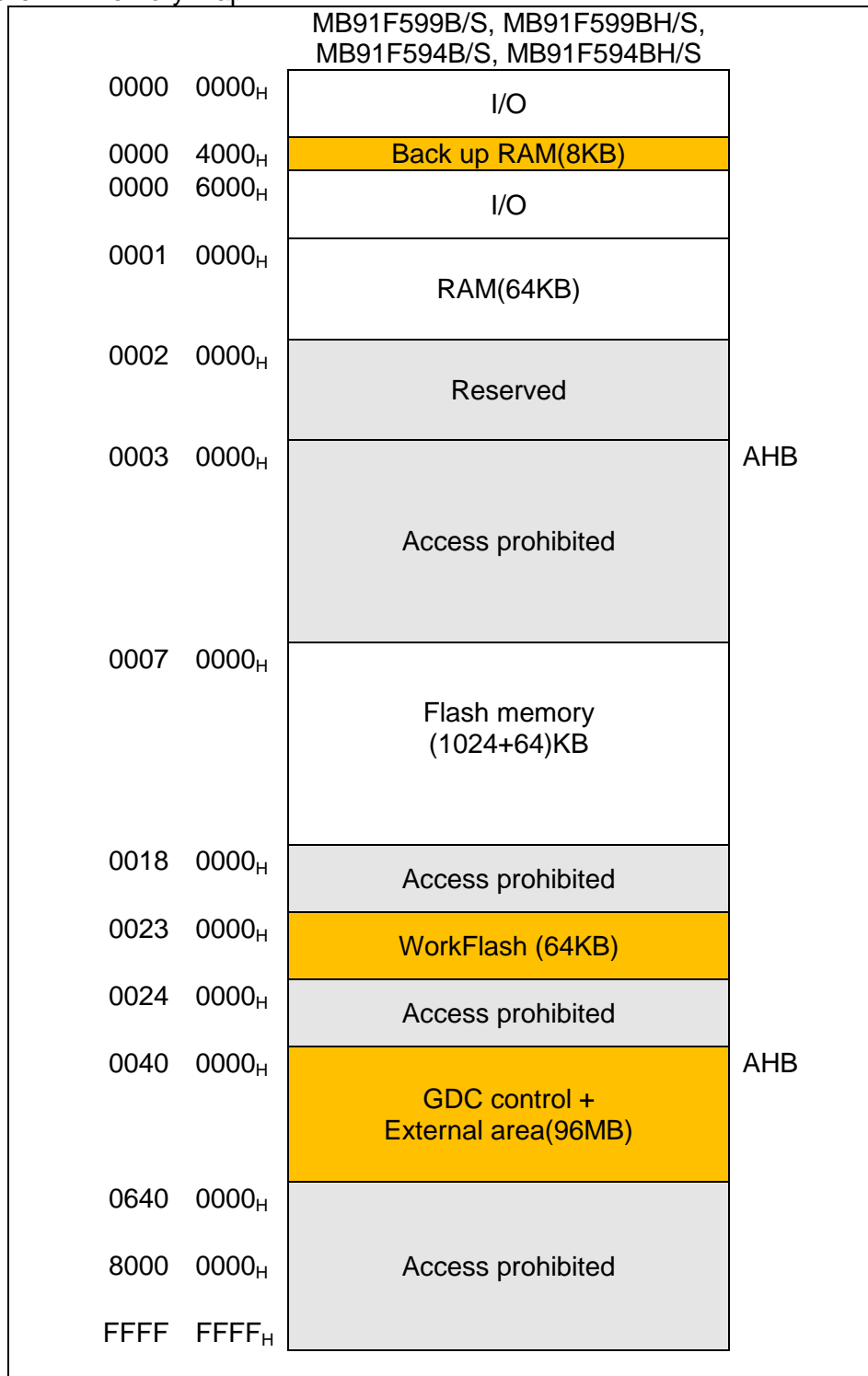
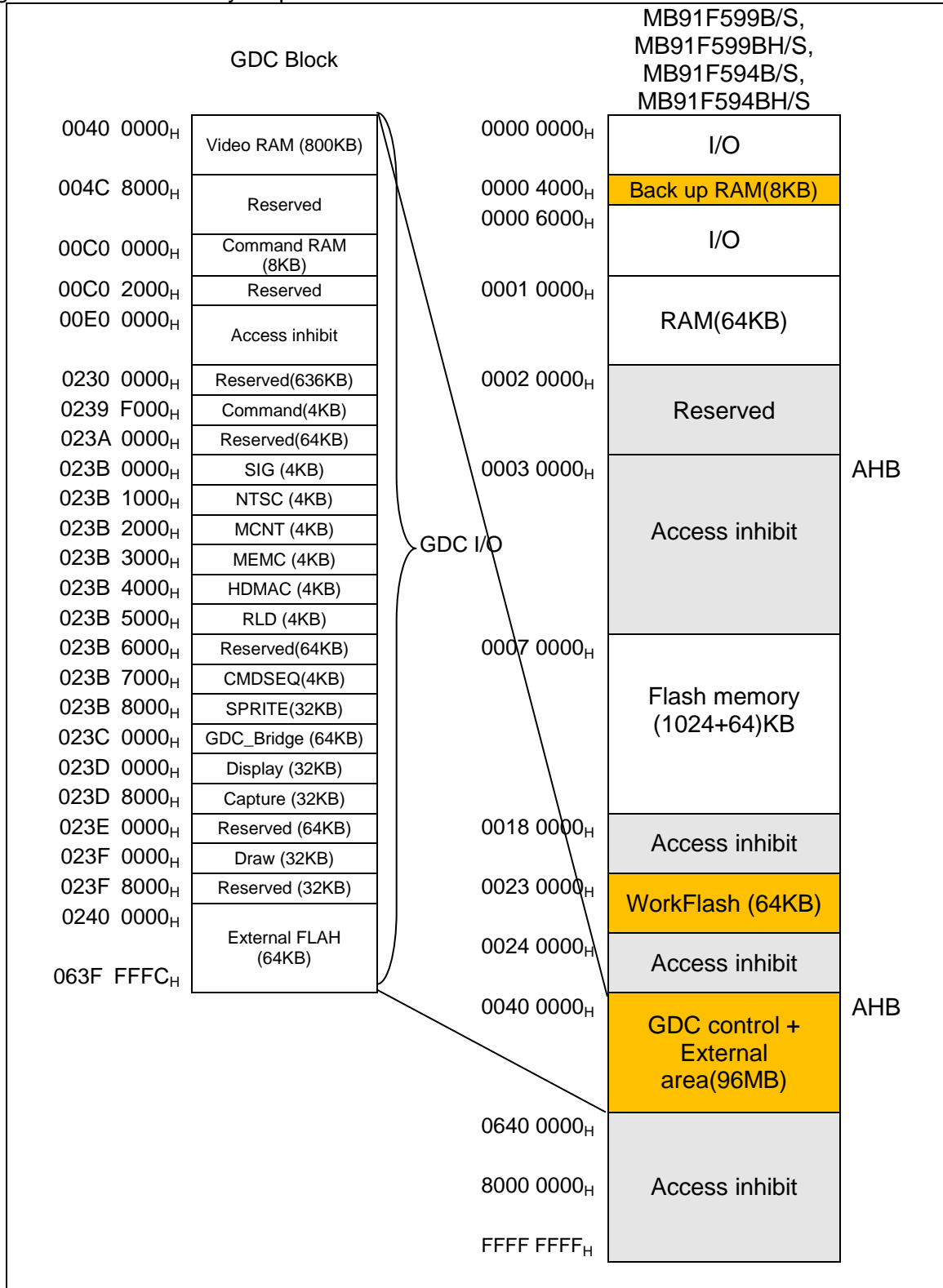


Figure A-2 GDC Memory Map



Note:

The GDC area is executed mapping with the little endian.

Figure A-3 Memory Map

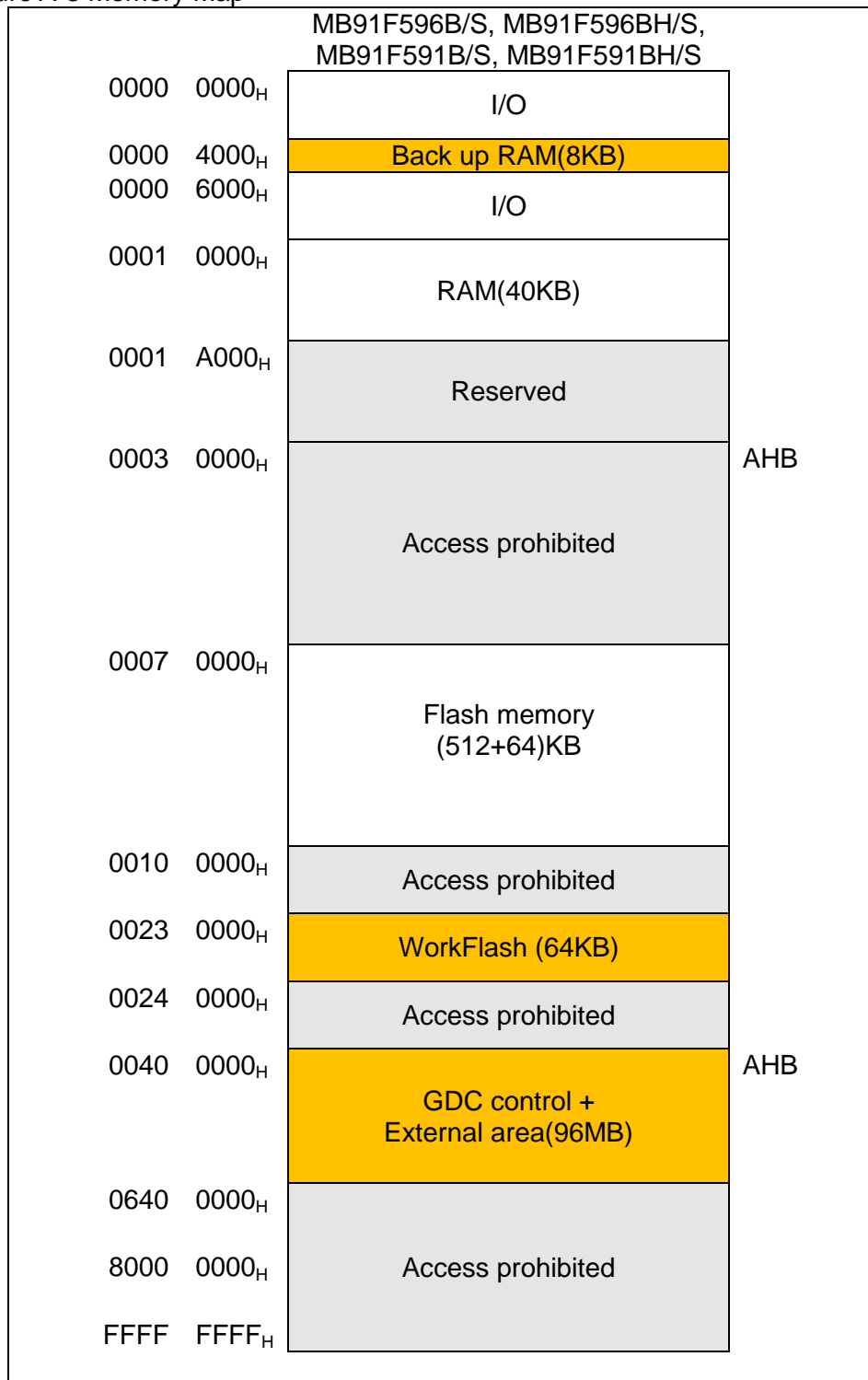
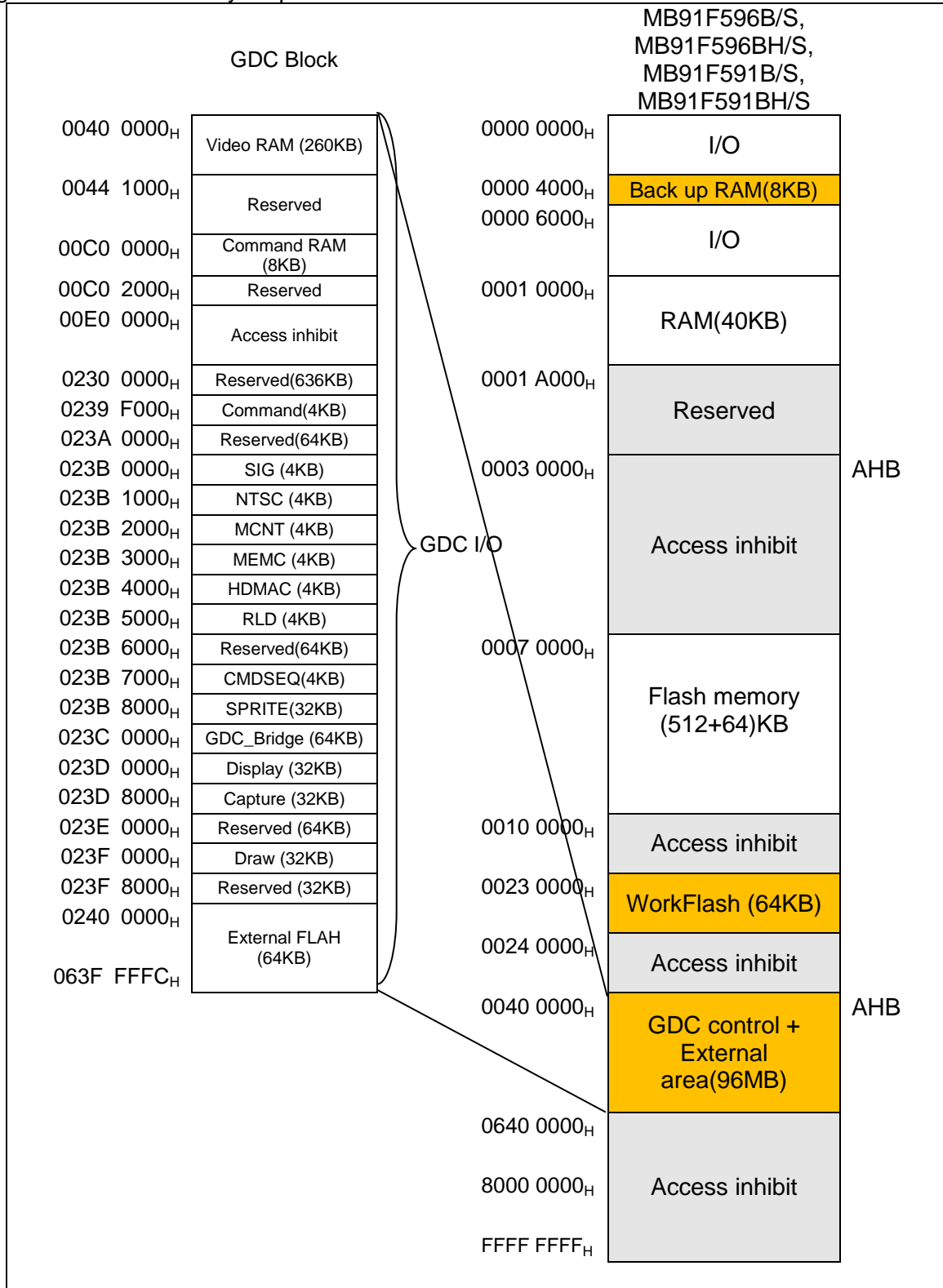


Figure A-4 GDC Memory Map



Note:

The GDC area is executed mapping with the little endian.

Figure A-5 Memory Map

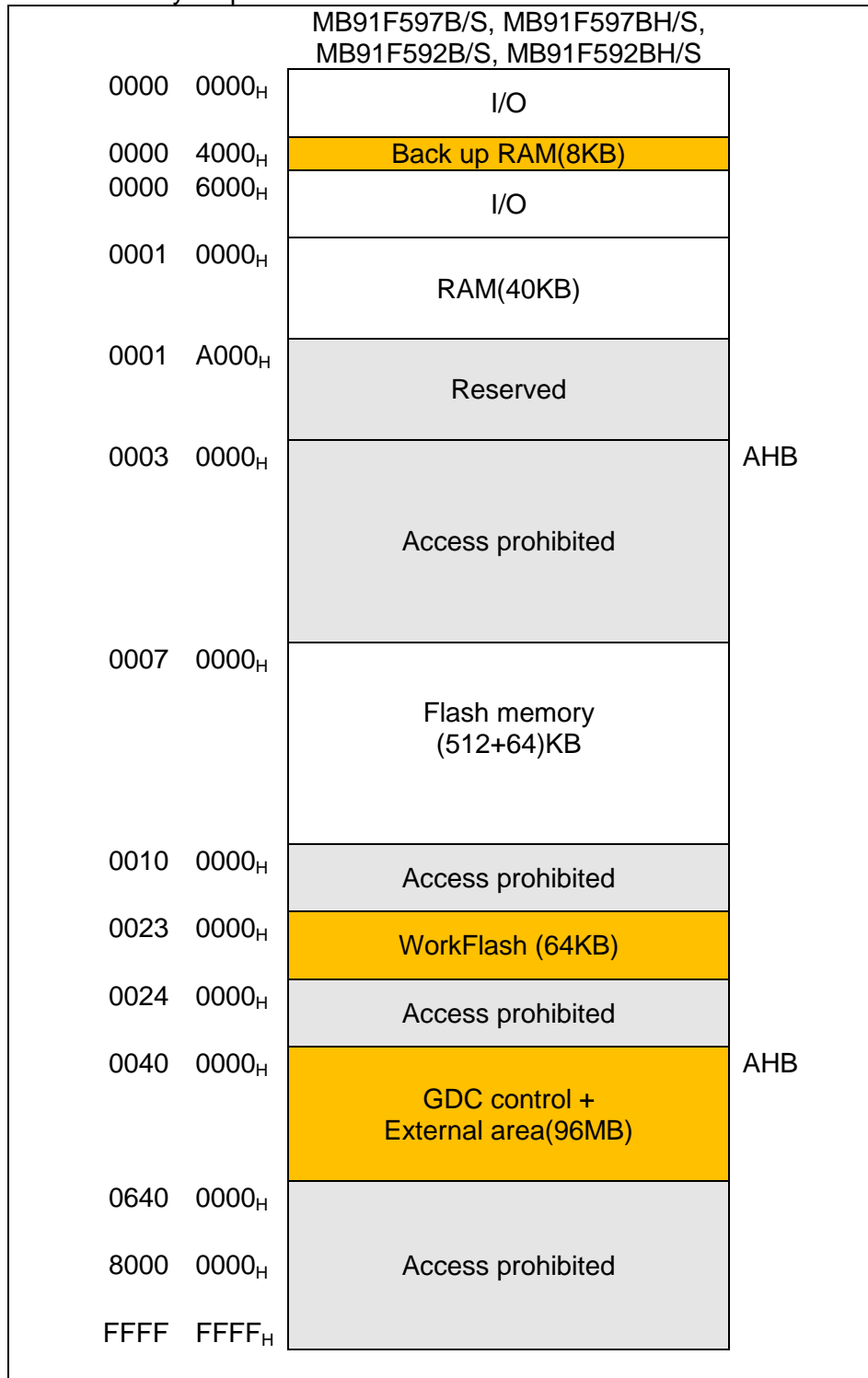
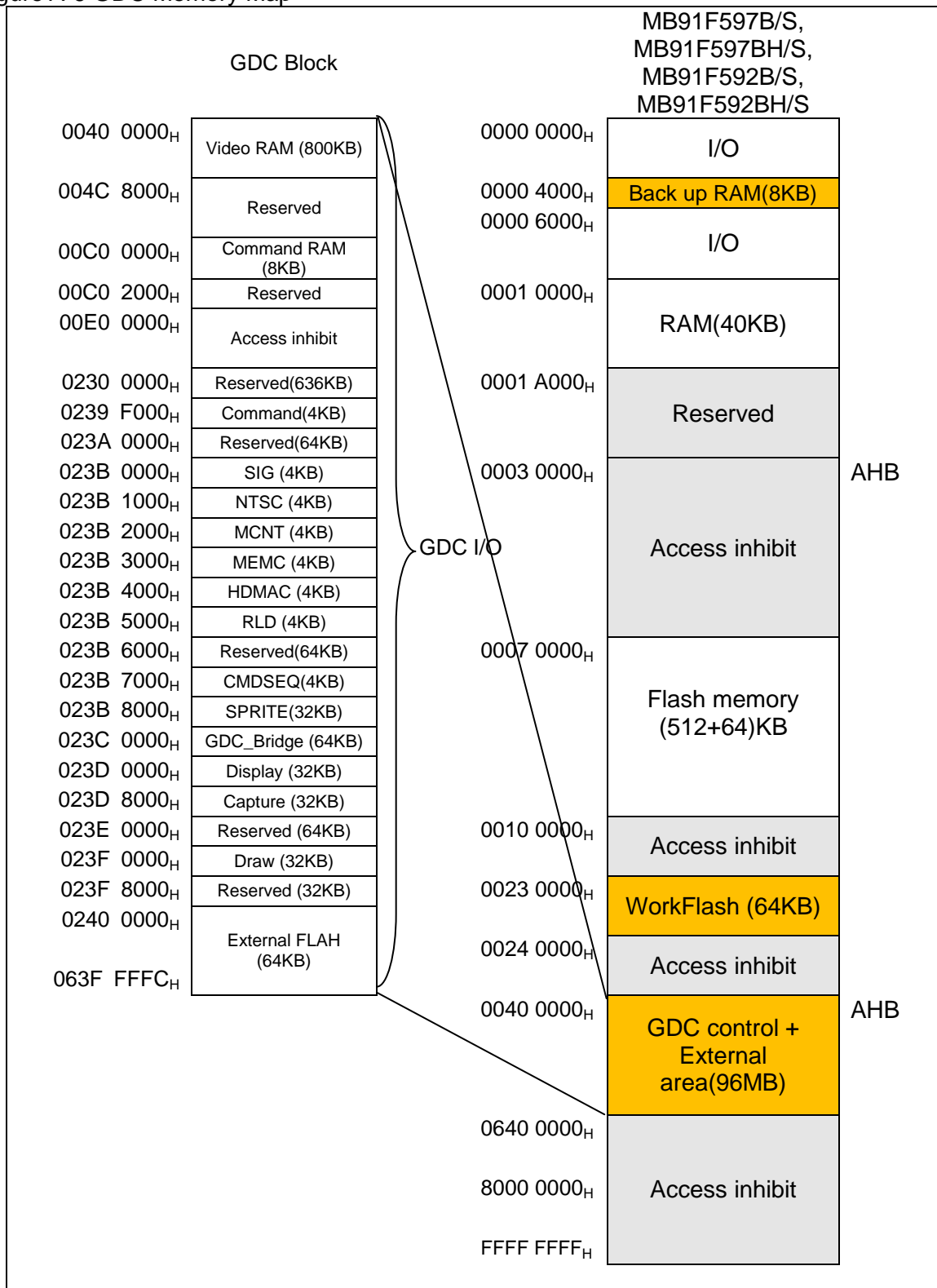


Figure A-6 GDC Memory Map



Note:

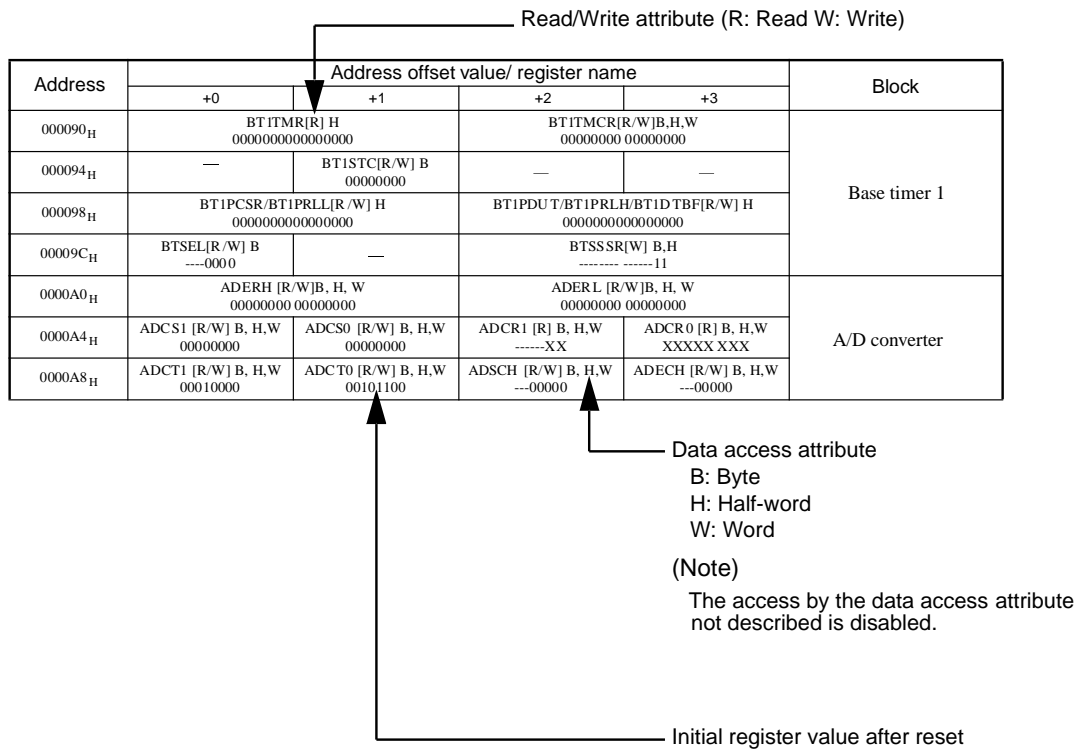
The GDC area is executed mapping with the little endian.

B. I/O Map

The I/O map is shown below.

The following I/O map shows the relationship between the memory space and registers for peripheral resources.

Figure B-1 Legend of I/O Map



The initial register values after reset are indicated as follows:

- "1": Initial value "1"
- "0": Initial value "0"
- "X": Initial value undefined
- "-": Reserved bit/Undefined bit
- "*": Initial value "0" or "1" according to the setting

Note:

The access to addresses not described is disabled.

Table B-1 : I/O Map

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000000 _H	PDR00[R/W] B,H,W XXXXXXXXXX	PDR01[R/W] B,H,W XXXXXXXXXX	PDR02[R/W] B,H,W XXXXXXXXXX	PDR03[R/W] B,H,W XXXXXXXXXX	Port data register
000004 _H	PDR04[R/W] B,H,W XXXXXXXXXX	PDR05[R/W] B,H,W XXXXXXXXXX	PDR06[R/W] B,H,W XXXXXXXXXX	PDR07[R/W] B,H,W XXXXXXXXXX	
000008 _H	PDR08[R/W] B,H,W XXXXXXXXXX	PDR09[R/W] B,H,W XXXXXXXXXX	PDR10[R/W] B,H,W XXXXXXXXXX	PDR11[R/W] B,H,W XXXXXXXXXX	
00000C _H	PDR12[R/W] B,H,W XXXXXXXXXX	PDR13[R/W] B,H,W XX-XXXXXX	—	—	
000010 _H	PDRA[R/W] B,H,W XXXXXX--	PDRB[R/W] B,H,W XXXXXX--	PDRC[R/W] B,H,W XXXXXX--	PDRD[R/W] B,H,W XXXXXX--	
000014 _H	PDRE[R/W] B,H,W XXXXXX--	PDRF[R/W] B,H,W XXXXXX--	PDRG[R/W] B,H,W XXXXXXXXXX	PDRH[R/W] B,H,W ---X---	
000018 _H to 000028 _H	—	—	—	—	Reserved
00002C _H to 000030 _H	—	—	—	—	Reserved
000034 _H to 000038 _H	—	—	—	—	Reserved
00003C _H	WDTCR0[R/W] B,H,W -0--0000	WDTCP0[R/W] B,H,W 00000000	WDTCR1[R] B,H,W ---0110	WDTCP1[W] B,H,W 00000000	Watchdog timer [S]
000040 _H	—	—	—	—	Reserved
000044 _H	DICR [R/W] B XXXXXXXXX0	—	—	—	Delay interrupt
000048 _H to 00005C _H	—	—	—	—	Reserved
000060 _H	TMRLRA0 [R/W] H XXXXXXXXXX XXXXXXXXX		TMR0 [R] H XXXXXXXXXX XXXXXXXXX		Reload timer 0
000064 _H	TMRLRB0 [R/W] H XXXXXXXXXX XXXXXXXXX		TMCSR0 [R/W] B, H,W 00000000 0-000000		
000068 _H to 00007C _H	—	—	—	—	Reserved

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000080 _H	BT0TMR [R] H 0000000000000000		BT0TMCR [R/W] H -0000000 00000000		Base timer 0
000084 _H	—	BT0STC [R/W] B 0000-000	—	—	
000088 _H	BT0PCSR/BT0PRL [R/W] H 0000000000000000		BT0PDUT/BT0PRLH/BT0DTBF [R/W] H 0000000000000000		
00008C _H	—	—	—	—	
000090 _H	BT1TMR [R] H 0000000000000000		BT1TMCR [R/W] H -0000000 00000000		Base timer 1
000094 _H	—	BT1STC [R/W] B 0000-000	—	—	
000098 _H	BT1PCSR/BT1PRL [R/W] H 0000000000000000		BT1PDUT/BT1PRLH/BT1DTBF [R/W] H 0000000000000000		
00009C _H	BTSEL01 [R/W] B ----0000	—	BTSSSR [W] B,H -----11		Base timer 0,1
0000A0 _H	ADERH [R/W] B, H, W 00000000 00000000		ADERL [R/W] B, H, W 00000000 00000000		A/D converter
0000A4 _H	ADCS1 [R/W] B, H,W 0000000-	ADCS0 [R/W] B, H,W 00000000	ADCR1 [R] B, H,W -----XX	ADCR0 [R] B, H,W XXXXXXXXXX	
0000A8 _H	ADCT1 [R/W] B, H,W 00010000	ADCT0 [R/W] B, H,W 00101100	ADSCH [R/W] B, H,W ---00000	ADECH [R/W] B, H,W ---00000	
0000AC _H	—	—	—	—	
0000B0 _H	SCR0/(IBCR0) [R/W] B,H,W 0-00000	SMR0 [R/W] B,H,W 000-0000	SSR0 [R/W] B,H,W 0-000011	ESCR0/(IBSR0) [R/W] B,H,W -0000000	Multi-UART0
0000B4 _H	RDR0/(TDR0)[R/W] B,H,W *1 -----0 00000000		BGR0 [R/W] H,W 00000000 00000000		*1 : Byte access is possible only for access to lower 8 bits
0000B8 _H	— / (ISMK0) [R/W] B,H,W ----- *2	— / (ISBA0) [R/W] B,H,W ----- *2	—	—	
0000BC _H	FCR10 [R/W] B,H,W ---00100	FCR00 [R/W] B,H,W -0000000	FBYTE20 [R/W] B,H,W 00000000	FBYTE10 [R/W] B,H,W 00000000	*2 : Reserved because I ² C mode is not set immediately after reset.

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
0000C0 _H	SCR1/(IBCR1) [R/W] B,H,W 0--00000	SMR1 [R/W] B,H,W 000-0000	SSR1 [R/W] B,H,W 0-000011	ESCR1/(IBSR1) [R/W] B,H,W -0000000	Multi-UART1 *1 : Byte access is possible only for access to lower 8 bits *2 : Reserved because I ² C mode is not set immediately after reset.
0000C4 _H	RDR1/(TDR1)[R/W] B,H,W *1 -----0 00000000		BGR1 [R/W] H,W 00000000 00000000		
0000C8 _H	— / (ISMK1) [R/W] B,H,W ----- *2	— / (ISBA1) [R/W] B,H,W ----- *2	—	—	
0000CC _H	FCR11 [R/W] B,H,W ---00100	FCR01[R/W] B,H,W -0000000	FBYTE21 [R/W] B,H,W 00000000	FBYTE11[R/W] B,H,W 00000000	
0000D0 _H	SCR2 [R/W] B, H, W 00000000	SMR2 [R/W] B, H, W 00000000	SSR2 [R/W] B, H, W 00001000	RDR2 /TDR2 [R/W] B, H, W 00000000	LIN-UART2
0000D4 _H	ESCR2 [R/W] B, H, W 00000X00	ECCR2 [R/W] B, H, W -0000-XX	BGR2 [R/W] B, H, W -0000000 00000000		
0000D8 _H	SCR3 [R/W] B, H, W 00000000	SMR3 [R/W] B, H, W 00000000	SSR3 [R/W] B, H, W 00001000	RDR3 /TDR3 [R/W] B, H, W 00000000	LIN-UART3
0000DC _H	ESCR3 [R/W] B, H, W 00000X00	ECCR3 [R/W] B, H, W -0000-XX	BGR3 [R/W] B, H, W -0000000 00000000		
0000E0 _H	SCR4 [R/W] B, H, W 00000000	SMR4[R/W] B, H, W 00000000	SSR4[R/W] B, H, W 00001000	RDR4 /TDR4 [R/W] B, H, W 00000000	LIN-UART4
0000E4 _H	ESCR4 [R/W] B, H, W 00000X00	ECCR4 [R/W] B, H, W -0000-XX	BGR4 [R/W] B, H, W -0000000 00000000		
0000E8 _H	SCR5 [R/W] B, H, W 00000000	SMR5 [R/W] B, H, W 00000000	SSR5 [R/W] B, H, W 00001000	RDR5 /TDR5 [R/W] B, H, W 00000000	LIN-UART5
0000EC _H	ESCR5 [R/W] B, H, W 00000X00	ECCR5 [R/W] B, H, W -0000-XX	BGR5 [R/W] B, H, W -0000000 00000000		
0000F0 _H	SCR6 [R/W] B, H, W 00000000	SMR6 [R/W] B, H, W 00000000	SSR6 [R/W] B, H, W 00001000	RDR6 /TDR6 [R/W] B, H, W 00000000	LIN-UART6
0000F4 _H	ESCR6 [R/W] B, H, W 00000X00	ECCR6 [R/W] B, H, W -0000-XX	BGR6 [R/W] B, H, W -0000000 00000000		
0000F8 _H	SCR7 [R/W] B, H, W 00000000	SMR7 [R/W] B, H, W 00000000	SSR7 [R/W] B, H, W 00001000	RDR7 /TDR7 [R/W] B, H, W 00000000	LIN-UART7
0000FC _H	ESCR7 [R/W] B, H, W 00000X00	ECCR7 [R/W] B, H, W -0000-XX	BGR7 [R/W] B, H, W -0000000 00000000		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000100 _H	TMRLRA1 [R/W] H XXXXXXXX XXXXXXXX		TMR1 [R] H XXXXXXXX XXXXXXXX		Reload timer 1
000104 _H	TMRLRB1 [R/W] H XXXXXXXX XXXXXXXX		TMCSR1 [R/W] B, H,W 00000000 0-000000		
000108 _H	TMRLRA2 [R/W] H XXXXXXXX XXXXXXXX		TMR2 [R] H XXXXXXXX XXXXXXXX		Reload timer 2
00010C _H	TMRLRB2 [R/W] H XXXXXXXX XXXXXXXX		TMCSR2 [R/W] B, H,W 00000000 0-000000		
000110 _H	TMRLRA3 [R/W] H XXXXXXXX XXXXXXXX		TMR3 [R] H XXXXXXXX XXXXXXXX		Reload timer 3
000114 _H	TMRLRB3 [R/W] H XXXXXXXX XXXXXXXX		TMCSR3 [R/W] B, H,W 00000000 0-000000		
000118 _H to 000140 _H	—	—	—	—	Reserved
000144 _H	GCN13 [R/W] H 00110010 00010000		—	GCN23 [R/W] B ----0000	PPG12,13,14,15 control
000148 _H	GCN14 [R/W] H 00110010 00010000		—	GCN24 [R/W] B ----0000	PPG16,17,18,19 control
00014C _H	GCN15 [R/W] H 00110010 00010000		—	GCN25 [R/W] B ----0000	PPG20,21,22,23 control
000150 _H	PTMR11 [R] H,W 11111111 11111111		PCSR11 [W] H, W XXXXXXXX XXXXXXXX		PPG11
000154 _H	PDUT11 [W] H,W XXXXXXXX XXXXXXXX		PCN11 [R/W] B, H,W 0000000- 000000-0		
000158 _H	PTMR12 [R] H,W 11111111 11111111		PCSR12 [W] H,W XXXXXXXX XXXXXXXX		PPG12
00015C _H	PDUT12 [W] H,W XXXXXXXX XXXXXXXX		PCN12 [R/W] B, H,W 0000000- 000000-0		
000160 _H	PTMR13 [R] H,W 11111111 11111111		PCSR13 [W] H,W XXXXXXXX XXXXXXXX		PPG13
000164 _H	PDUT13 [W] H,W XXXXXXXX XXXXXXXX		PCN13 [R/W] B, H,W 0000000- 000000-0		
000168 _H	PTMR14 [R] H,W 11111111 11111111		PCSR14 [W] H,W XXXXXXXX XXXXXXXX		PPG14
00016C _H	PDUT14 [W] H,W XXXXXXXX XXXXXXXX		PCN14 [R/W] B, H,W 0000000- 000000-0		
000170 _H	PTMR15 [R] H,W 11111111 11111111		PCSR15 [W] H,W XXXXXXXX XXXXXXXX		PPG15
000174 _H	PDUT15 [W] H,W XXXXXXXX XXXXXXXX		PCN15 [R/W] B, H,W 0000000- 000000-0		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000178 _H	PTMR16 [R] H,W 11111111 11111111		PCSR16 [W] H, W XXXXXXXX XXXXXXXX		PPG16
00017C _H	PDUT16 [W] H,W XXXXXXXX XXXXXXXX		PCN16 [R/W] B, H,W 000000- 000000-0		
000180 _H	PTMR17 [R] H,W 11111111 11111111		PCSR17 [W] H,W XXXXXXXX XXXXXXXX		PPG17
000184 _H	PDUT17 [W] H,W XXXXXXXX XXXXXXXX		PCN17 [R/W] B, H,W 000000- 000000-0		
000188 _H	PTMR18 [R] H,W 11111111 11111111		PCSR18 [W] H,W XXXXXXXX XXXXXXXX		PPG18
00018C _H	PDUT18 [W] H,W XXXXXXXX XXXXXXXX		PCN18 [R/W] B, H,W 000000- 000000-0		
000190 _H	PTMR19 [R] H,W 11111111 11111111		PCSR19 [W] H,W XXXXXXXX XXXXXXXX		PPG19
000194 _H	PDUT19 [W] H,W XXXXXXXX XXXXXXXX		PCN19 [R/W] B, H,W 000000- 000000-0		
000198 _H	PTMR20 [R] H,W 11111111 11111111		PCSR20 [W] H,W XXXXXXXX XXXXXXXX		PPG20
00019C _H	PDUT20 [W] H,W XXXXXXXX XXXXXXXX		PCN20 [R/W] B, H,W 000000- 000000-0		
0001A0 _H	PTMR21 [R] H,W 11111111 11111111		PCSR21 [W] H, W XXXXXXXX XXXXXXXX		PPG21
0001A4 _H	PDUT21 [W] H,W XXXXXXXX XXXXXXXX		PCN21 [R/W] B, H,W 000000- 000000-0		
0001A8 _H	PTMR22 [R] H,W 11111111 11111111		PCSR22 [W] H,W XXXXXXXX XXXXXXXX		PPG22
0001AC _H	PDUT22 [W] H,W XXXXXXXX XXXXXXXX		PCN22 [R/W] B, H,W 000000- 000000-0		
0001B0 _H	PTMR23 [R] H,W 11111111 11111111		PCSR23 [W] H,W XXXXXXXX XXXXXXXX		PPG23
0001B4 _H	PDUT23 [W] H,W XXXXXXXX XXXXXXXX		PCN23 [R/W] B, H,W 000000- 000000-0		
0001B8 _H to 0001FC _H	—	—	—	—	Reserved
000200 _H	PWC20 [R/W] H,W -----XX XXXXXXXX		PWC10 [R/W] H,W -----XX XXXXXXXX		Stepping motor controller
000204 _H	—	PWC0 [R/W] B -00000--	PWS20 [R/W] B,H,W -0000000	PWS10 [R/W] B,H,W --000000	
000208 _H	PWC21 [R/W] H,W -----XX XXXXXXXX		PWC11 [R/W] H,W -----XX XXXXXXXX		
00020C _H	—	PWC1 [R/W] B -00000--	PWS21 [R/W] B,H,W -0000000	PWS11 [R/W] B,H,W --000000	
000210 _H	PWC22 [R/W] H,W -----XX XXXXXXXX		PWC12 [R/W] H,W -----XX XXXXXXXX		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000214 _H	—	PWC2 [R/W] B -00000--	PWS22 [R/W] B,H,W -0000000	PWS12 [R/W] B,H,W --000000	Stepping motor controller (continuation)
000218 _H	PWC23 [R/W] H,W -----XX XXXXXXXXX		PWC13 [R/W] H,W -----XX XXXXXXXXX		
00021C _H	—	PWC3 [R/W] B -00000--	PWS23 [R/W] B,H,W -0000000	PWS13 [R/W] B,H,W --000000	
000220 _H	PWC24 [R/W] H,W -----XX XXXXXXXXX		PWC14 [R/W] H,W -----XX XXXXXXXXX		
000224 _H	—	PWC4 [R/W] B -00000--	PWS24 [R/W] B,H,W -0000000	PWS14 [R/W] B,H,W --000000	
000228 _H	PWC25 [R/W] H,W -----XX XXXXXXXXX		PWC15 [R/W] H,W -----XX XXXXXXXXX		
00022C _H	—	PWC5 [R/W] B -00000--	PWS25 [R/W] B,H,W -0000000	PWS15 [R/W] B,H,W --000000	
000230 _H to 00023C _H	—	—	—	—	Reserved
000240 _H	CPCLR0 [R/W] W 11111111 11111111 11111111 11111111				Free-run timer 0
000244 _H	TCDT0 [R/W] W 00000000 00000000 00000000 00000000				
000248 _H	TCCSH0 [R/W]B, H, W 0----00	TCCSL0 [R/W]B, H, W -1-00000	—		
00024C _H	CPCLR1 [R/W] W 11111111 11111111 11111111 11111111				Free-run timer 1
000250 _H	TCDT1 [R/W] W 00000000 00000000 00000000 00000000				
000254 _H	TCCSH1 [R/W]B, H, W 0----00	TCCSL1 [R/W]B, H, W -1-00000	—		
000258 _H	—	—	—	—	Reserved
00025C _H	GCN10 [R/W] H 00110010 00010000		—	GCN20 [R/W] B ----0000	PPG0,1,2,3 control
000260 _H	GCN11 [R/W] H 00110010 00010000		—	GCN21 [R/W] B ----0000	PPG4,5,6,7 control
000264 _H	GCN12 [R/W] H 00110010 00010000		—	GCN22 [R/W] B ----0000	PPG8,9,10,11 control

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000268 _H	—	—	—	PPGDIV [R/W] B -----00	PPG0
00026C _H	PTMR0 [R] H,W 11111111 11111111		PCSR0 [W] H,W XXXXXXXX XXXXXXXX		
000270 _H	PDUT0 [W] H,W XXXXXXXX XXXXXXXX		PCN0 [R/W] B, H,W 000000- 000000-0		PPG1
000274 _H	PTMR1 [R] H,W 11111111 11111111		PCSR1 [W] H, W XXXXXXXX XXXXXXXX		
000278 _H	PDUT1 [W] H,W XXXXXXXX XXXXXXXX		PCN1 [R/W] B, H,W 000000- 000000-0		PPG2
00027C _H	PTMR2 [R] H,W 11111111 11111111		PCSR2 [W] H,W XXXXXXXX XXXXXXXX		
000280 _H	PDUT2 [W] H,W XXXXXXXX XXXXXXXX		PCN2 [R/W] B, H,W 000000- 000000-0		PPG3
000284 _H	PTMR3 [R] H,W 11111111 11111111		PCSR3 [W] H,W XXXXXXXX XXXXXXXX		
000288 _H	PDUT3 [W] H,W XXXXXXXX XXXXXXXX		PCN3 [R/W] B, H,W 000000- 000000-0		PPG4
00028C _H	PTMR4 [R] H,W 11111111 11111111		PCSR4 [W] H,W XXXXXXXX XXXXXXXX		
000290 _H	PDUT4 [W] H,W XXXXXXXX XXXXXXXX		PCN4 [R/W] B, H,W 000000- 000000-0		PPG5
000294 _H	PTMR5 [R] H,W 11111111 11111111		PCSR5 [W] H,W XXXXXXXX XXXXXXXX		
000298 _H	PDUT5 [W] H,W XXXXXXXX XXXXXXXX		PCN5 [R/W] B, H,W 000000- 000000-0		PPG6
00029C _H	PTMR6 [R] H,W 11111111 11111111		PCSR6 [W] H,W XXXXXXXX XXXXXXXX		
0002A0 _H	PDUT6 [W] H,W XXXXXXXX XXXXXXXX		PCN6 [R/W] B, H,W 000000- 000000-0		PPG7
0002A4 _H	PTMR7 [R] H,W 11111111 11111111		PCSR7 [W] H,W XXXXXXXX XXXXXXXX		
0002A8 _H	PDUT7 [W] H,W XXXXXXXX XXXXXXXX		PCN7 [R/W] B, H,W 000000- 000000-0		PPG8
0002AC _H	PTMR8 [R] H,W 11111111 11111111		PCSR8 [W] H,W XXXXXXXX XXXXXXXX		
0002B0 _H	PDUT8 [W] H,W XXXXXXXX XXXXXXXX		PCN8 [R/W] B, H,W 000000- 000000-0		PPG9
0002B4 _H	PTMR9 [R] H,W 11111111 11111111		PCSR9 [W] H,W XXXXXXXX XXXXXXXX		
0002B8 _H	PDUT9 [W] H,W XXXXXXXX XXXXXXXX		PCN9 [R/W] B, H,W 000000- 000000-0		PPG10
0002BC _H	PTMR10 [R] H,W 11111111 11111111		PCSR10 [W] H,W XXXXXXXX XXXXXXXX		
0002C0 _H	PDUT10 [W] H,W XXXXXXXX XXXXXXXX		PCN10 [R/W] B, H,W 000000- 000000-0		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
0002C4 _H	IPCP0 [R] W XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				Input Capture 0,1
0002C8 _H	IPCP1 [R] W XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				
0002CC _H	ICFS01 [R/W] B, H, W -----00	—	LSYN0 [R/W] B,H,W --000000	ICS01 [R/W] B, H, W 00000000	
0002D0 _H	IPCP2 [R] W XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				Input Capture 2,3
0002D4 _H	IPCP3 [R] W XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				
0002D8 _H	ICFS23 [R/W] B, H, W -----00	—	—	ICS23 [R/W] B, H, W 00000000	
0002DC _H	IPCP4 [R] W XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				Input Capture 4,5
0002E0 _H	IPCP5 [R] W XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				
0002E4 _H	ICFS45 [R/W] B, H, W -----00	—	—	ICS45 [R/W] B, H, W 00000000	
0002E8 _H	OCCP0 [R/W] W 00000000 00000000 00000000 00000000				Output compare 0,1
0002EC _H	OCCP1 [R/W] W 00000000 00000000 00000000 00000000				
0002F0 _H	OCFS01 [R/W] B, H, W -----11	—	OCSH01[R/W] B, H, W ---0--00	OCSL01[R/W] B, H, W 0000--00	
0002F4 _H	OCCP2 [R/W] W 00000000 00000000 00000000 00000000				Output compare 2,3
0002F8 _H	OCCP3 [R/W] W 00000000 00000000 00000000 00000000				
0002FC _H	OCFS23 [R/W] B, H, W -----11	—	OCSH23[R/W] B, H, W ---0--00	OCSL23[R/W] B, H, W 0000--00	
000300 _H to 00030C _H	—	—	—	—	Reserved

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000310 _H	—	—	MPUCR [R/W] H 000000-0 ----0100		MPU [S] (Only the CPU can access this area)
000314 _H	—	—	—	—	
000318 _H	—				
00031C _H	—	—	—		
000320 _H	DPVAR [R] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000324 _H	—	—	DPVSR [R/W] H ----- 0000--0		
000328 _H	DEAR [R] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
00032C _H	—	—	DESR [R/W] H ----- 0000--0		
000330 _H	PABR0 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000334 _H	—	—	PACR0 [R/W] H 000000-0 0000--0		
000338 _H	PABR1 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
00033C _H	—	—	PACR1 [R/W] H 000000-0 0000--0		
000340 _H	PABR2 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000344 _H	—	—	PACR2 [R/W] H 000000-0 0000--0		
000348 _H	PABR3 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
00034C _H	—	—	PACR3 [R/W] H 000000-0 0000--0		
000350 _H	PABR4 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000354 _H	—	—	PACR4 [R/W] H 000000-0 0000--0		
000358 _H	PABR5 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
00035C _H	—	—	PACR5 [R/W] H 000000-0 0000--0		
000360 _H	PABR6 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000364 _H	—	—	PACR6 [R/W] H 000000-0 0000--0		
000368 _H	PABR7 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
00036C _H	—	—	PACR7 [R/W] H 000000-0 00000--0		MPU [S] (Only the CPU can access this area)
000370 _H	PABR8 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000374 _H	—	—	PACR8 [R/W] H 000000-0 00000--0		MPU [S] (Only product mounting MPU 12ch or 16ch) (Only the CPU can access this area)
000378 _H	PABR9[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
00037C _H	—	—	PACR9 [R/W] H 000000-0 00000--0		
000380 _H	PABR10 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000384 _H	—	—	PACR10 [R/W] H 000000-0 00000--0		
000388 _H	PABR11 [R/W] ,W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
00038C _H	—	—	PACR11 [R/W] H 000000-0 00000--0		MPU [S] (Only product mounting MPU 16ch) (Only the CPU can access this area)
000390 _H	PABR12 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
000394 _H	—	—	PACR12 [R/W] H 000000-0 00000--0		
000398 _H	PABR13 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
00039C _H	—	—	PACR13 [R/W] H 000000-0 00000--0		
0003A0 _H	PABR14 [R/W]W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
0003A4 _H	—	—	PACR14 [R/W] H 000000-0 00000--0		Reserved [S]
0003A8 _H	PABR15 [R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXX0000				
0003AC _H	—	—	PACR15 [R/W] H 000000-0 00000--0		
0003B0 _H to 0003FC _H	—	—	—	—	Generation and clear of DMA transfer request
000400 _H	ICSEL0[R/W] B, H, W ----000	ICSEL1[R/W] B, H, W ----000	ICSEL2[R/W] B, H, W -----0	ICSEL3[R/W] B, H, W -----0	
000404 _H	ICSEL4[R/W] B, H, W -----0	ICSEL5[R/W] B, H, W -----0	ICSEL6[R/W] B, H, W ----000	ICSEL7[R/W] B, H, W ----000	
000408 _H	ICSEL8[R/W] B, H, W -----00	ICSEL9[R/W] B, H, W -----00	ICSEL10[R/W] B, H, W -----00	ICSEL11[R/W] B, H, W -----00	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
00040 _{CH}	ICSEL12[R/W] B, H, W -----00	ICSEL13[R/W] B, H, W -----0	ICSEL14[R/W] B, H, W -----0	ICSEL15[R/W] B, H, W -----	Generation and clear of DMA transfer request
000410 _H	ICSEL16[R/W] B, H, W -----	ICSEL17[R/W] B, H, W -----	ICSEL18[R/W] B, H, W -----	ICSEL19[R/W] B, H, W ----000	
000414 _H	ICSEL20[R/W] B, H, W ----000	ICSEL21[R/W] B, H, W -----00	ICSEL22[R/W] B, H, W -----00	—	
000418 _H	IRPR0H[R] B, H, W 00-----	IRPR0L[R] B, H, W 00-----	IRPR1H[R] B, H, W 00-----	IRPR1L[R] B, H, W 00-----	Interrupt request batch read register
00041C _H	IRPR2H[R] B, H, W 00-----	IRPR2L[R] B, H, W 00-----	IRPR3H[R] B, H, W 000000--	IRPR3L[R] B, H, W 000000--	
000420 _H	IRPR4H[R] B, H, W 0000----	IRPR4L[R] B, H, W 0000----	IRPR5H[R] B, H, W 0000----	IRPR5L[R] B, H, W 0-----	
000424 _H	IRPR6H[R] B, H, W 00-0---	IRPR6L[R] B, H, W 000-----	IRPR7H[R] B, H, W -00-----	IRPR7L[R] B, H, W -----0-	
000428 _H	IRPR8H[R] B, H, W 00-----	IRPR8L[R] B, H, W 00-----	IRPR9H[R] B, H, W 00-----	IRPR9L[R] B, H, W 00-----	
00042C _H	—	—	—	—	Reserved
000430 _H	IRPR12H[R] B, H, W 00-----	IRPR12L[R] B, H, W 00-----	IRPR13H[R] B, H, W 000-----	IRPR13L[R] B, H, W 000000---	Interrupt request batch read register
000434 _H	IRPR14H[R] B, H, W 00000000	IRPR14L[R] B, H, W 00000000	IRPR15H[R] B, H, W 000-----	—	
000438 _H to 00043C _H	—	—	—	—	Reserved
000440 _H	ICR00 [R/W] B, H, W ---11111	ICR01 [R/W] B, H, W ---11111	ICR02 [R/W] B, H, W ---11111	ICR03 [R/W] B, H, W ---11111	Interrupt controller [S]
000444 _H	ICR04 [R/W] B, H, W ---11111	ICR05 [R/W] B, H, W ---11111	ICR06 [R/W] B, H, W ---11111	ICR07 [R/W] B, H, W ---11111	
000448 _H	ICR08 [R/W] B, H, W ---11111	ICR09 [R/W] B, H, W ---11111	ICR10 [R/W] B, H, W ---11111	ICR11 [R/W] B, H, W ---11111	
00044C _H	ICR12 [R/W] B, H, W ---11111	ICR13 [R/W] B, H, W ---11111	ICR14 [R/W] B, H, W ---11111	ICR15 [R/W] B, H, W ---11111	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000450 _H	ICR16 [R/W] B, H, W ---11111	ICR17 [R/W] B, H, W ---11111	ICR18 [R/W] B, H, W ---11111	ICR19 [R/W] B, H, W ---11111	Interrupt controller [S]
000454 _H	ICR20 [R/W] B, H, W ---11111	ICR21 [R/W] B, H, W ---11111	ICR22 [R/W] B, H, W ---11111	ICR23 [R/W] B, H, W ---11111	
000458 _H	ICR24 [R/W] B, H, W ---11111	ICR25 [R/W] B, H, W ---11111	ICR26 [R/W] B, H, W ---11111	ICR27 [R/W] B, H, W ---11111	
00045C _H	ICR28 [R/W] B, H, W ---11111	ICR29 [R/W] B, H, W ---11111	ICR30 [R/W] B, H, W ---11111	ICR31 [R/W] B, H, W ---11111	
000460 _H	ICR32 [R/W] B, H, W ---11111	ICR33 [R/W] B, H, W ---11111	ICR34 [R/W] B, H, W ---11111	ICR35 [R/W] B, H, W ---11111	
000464 _H	ICR36 [R/W] B, H, W ---11111	ICR37 [R/W] B, H, W ---11111	ICR38 [R/W] B, H, W ---11111	ICR39 [R/W] B, H, W ---11111	
000468 _H	ICR40 [R/W] B, H, W ---11111	ICR41 [R/W] B, H, W ---11111	ICR42 [R/W] B, H, W ---11111	ICR43 [R/W] B, H, W ---11111	
00046C _H	ICR44 [R/W] B, H, W ---11111	ICR45 [R/W] B, H, W ---11111	ICR46 [R/W] B, H, W ---11111	ICR47 [R/W] B, H, W ---11111	
000470 _H to 00047C _H	—	—	—	—	Reserved [S]
000480 _H	RSTRR [R] B,H,W XXXX--XX	RSTCR [R/W] B,H,W 111----0	STBCR [R/W] B,H,W * 000---11	—	Reset control [S] Power consumption control [S] * :Writing to STBCR by DMA is disabled
000484 _H	—	—	—	—	Reserved [S]
000488 _H	DIVR0 [R/W] B,H,W 000-----	DIVR1 [R/W] B,H,W 0001----	DIVR2 [R/W] B,H,W 0011----	—	Clock control [S]
00048C _H	—	—	—	—	Reserved [S]
000490 _H	IORR0[R/W] B, H, W -0000000	IORR1[R/W] B, H, W -0000000	IORR2[R/W] B, H, W -0000000	IORR3[R/W] B, H, W -0000000	DMA transfer request from a peripheral [S]
000494 _H	IORR4[R/W] B, H, W -0000000	IORR5[R/W] B, H, W -0000000	IORR6[R/W] B, H, W -0000000	IORR7[R/W] B, H, W -0000000	
000498 _H	IORR8[R/W] B, H, W -0000000	IORR9[R/W] B, H, W -0000000	IORR10[R/W] B, H, W -0000000	IORR11[R/W] B, H, W -0000000	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
00049C _H	IORR12[R/W] B, H, W -0000000	IORR13[R/W] B, H, W -0000000	IORR14[R/W] B, H, W -0000000	IORR15[R/W] B, H, W -0000000	DMA transfer request from a peripheral [S] (continuation)
0004A0 _H	—	—	—	—	Reserved
0004A4 _H	CANPRE [R/W] B,H,W ----0000	—	—	—	CAN prescaler
0004A8 _H	—	—	—	—	Reserved
0004AC _H	—	—	—	—	Reserved
0004B0 _H	—	—	—	—	Reserved
0004B4 _H	—	—	—	—	Reserved
0004B8 _H	CUCR0 [R/W] B,H,W -----0--00		CUTD0 [R/W] B,H,W 10000000 00000000		RTC/WDT1 calibration (Calibration)
0004BC _H	CUTR0 [R] B,H,W -----00000000 00000000 00000000				
0004C0 _H	—	—	—	—	
0004C4 _H	CUCR1 [R/W] B,H,W -----0--00		CUTD1[R/W] B,H,W 11000011 01010000		
0004C8 _H	CUTR1 [R] B,H,W -----00000000 00000000 00000000				
0004CC _H	CRTR [R/W] B,H,W 01111111	—	—	—	RC trimming setting register
0004D0 _H to 0004DC _H	—	—	—	—	Reserved
0004E0 _H to 00050C _H	—	—	—	—	Reserved
000510 _H	CSELR [R/W] B,H,W 001---00	CMONR [R] B,H,W 001---00	MTMCR [R/W] B,H,W 00001111	STMCR [R/W] B,H,W 0000-111	Clock control [S]
000514 _H	PLLCR [R/W] B,H,W -----11110000		CSTBR [R/W] B,H,W -0000000	PTMCR [R/W] B,H,W 00-----	
000518 _H	—	—	CPUAR [R/W] B,H,W 0---XXX	—	Reset [S]
00051C _H	—	—	—	—	Reserved [S]
000520 _H	CCPSSELR [R/W] B,H,W -----0	—	—	CCPSDIVR [R/W] B,H,W -000-000	Clock control 2
000524 _H	—	CCPLLFBR [R/W] B,H,W -0000000	CCSSFBR0 [R/W] B,H,W --000000	CCSSFBR1 [R/W] B,H,W ---00000	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000528 _H	—	CCSSCCR0 [R/W] B,H,W ----0000	CCSSCCR1 [R/W] H,W 000----_-----		Clock control 2 (continuation)
00052C _H	—	CCCGRCR0 [R/W] B,H,W 00----00	CCCGRCR1 [R/W] B,H,W 00000000	CCCGRCR2 [R/W] B,H,W 00000000	
000530 _H	CCRTSELR [R/W] B,H,W 0-----0	—	CCPMUCR0 [R/W] B,H,W 0----00	CCPMUCR1 [R/W] B,H,W 0--00000	
000534 _H	—	—	—	—	
000538 _H	—	—	—	—	
00053C _H	—	—	—	—	
000540 _H to 00054C _H	—	—	—	—	
000550 _H	EIRR0 [R/W] B,H,W XXXXXXXXXX	ENIR0 [R/W] B,H,W 00000000	ELVR0 [R/W] B,H,W 00000000 00000000		Extrenal interrupt (INT0 to INT7)
000554 _H	EIRR1 [R/W] B,H,W XXXXXXXXXX	ENIR1 [R/W] B,H,W 00000000	ELVR1 [R/W] B,H,W 00000000 00000000		External interrupt (INT8 to INT15)
000558 _H	—	—	—	—	Reserved
00055C _H	—	—	WTDR[R/W] H 00000000 00000000		Real-time clock
000560 _H	—	WTCRH [R/W] B -----00	WTCRM [R/W] B,H 00000000	WTCRL [R/W] B,H ----00-0	
000564 _H	—	WTBRH [R/W] B --XXXXXX	WTBRM [R/W] B XXXXXXXXXX	WTBRL [R/W] B XXXXXXXXXX	
000568 _H	WTHR [R/W] B,H ---00000	WTMR [R/W] B,H --000000	WTSR [R/W] B --000000	—	
00056C _H	—	CSVCR [R/W] B -001110- -001010- ^{*3}	—	—	
000570 _H to 00057C _H	—	—	—	—	Reserved
000580 _H	REGSEL [R/W] B,H,W 0110011-	—	—	—	Regulator control

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000584 _H	LVD5R [R/W] B,H,W -----1	LVD5F [R/W] B,H,W 0-100--1	LVD [R/W] B,H,W 01000--0	—	Low-voltage detection
000588 _H	GLVD5R[R/W] B,H,W 0-01-0-X	GLVD5F[R/W] B,H,W 0-0100-X	GLVD[R/W] B,H,W 010000-X	—	
00058C _H	—	—	—	—	Reserved
000590 _H	PMUSTR [R/W] B,H,W 0-----1X	PMUCTLR [R/W] B,H,W 0-00----	PWRTMCTL [R/W] B,H,W -----011	—	PMU
000594 _H	PMUINTF0 [R/W] B,H,W 00000000	PMUINTF1 [R/W] B,H,W 00000000	PMUINTF2 [R/W] B,H,W 0000----	—	
000598 _H	GSTR[R] B,H,W 0-----	GCTLR[R/W] B,H,W 0000-111	—	—	
00059C _H	—	—	—	—	
0005A0 _H to 0005FC _H	—	—	—	—	Reserved
000600 _H to 00060C _H	—	—	—	—	Reserved [S]
000610 _H to 00063C _H	—	—	—	—	Reserved [S]
000640 _H to 00064C _H	—	—	—	—	Reserved [S]
000650 _H to 00067C _H	—	—	—	—	Reserved [S]
000680 _H to 00068C _H	—	—	—	—	Reserved [S]
000690 _H to 0006BC _H	—	—	—	—	Reserved [S]
0006C0 _H to 0006CC _H	—	—	—	—	Reserved [S]
0006D0 _H to 0006F0 _H	—	—	—	—	Reserved
0006F4 _H	—	—	—	—	Reserved

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
0006F8 _H to 00070C _H	—	—	—	—	Reserved
000710 _H	BPC CRA [R/W] B 00000000	BPC CRB [R/W] B 00000000	BPC CRC [R/W] B 00000000	—	Bus performance counter
000714 _H	BPCTRA[R/W] W 00000000 00000000 00000000 00000000				
000718 _H	BPCTRB[R/W] W 00000000 00000000 00000000 00000000				
00071C _H	BPCTRC[R/W] W 00000000 00000000 00000000 00000000				
000720 _H to 0007F8 _H	—	—	—	—	Reserved
0007FC _H	BMODR[R] B, H, W XXXXXXXX	—	—	—	Operation mode
000800 _H to 00083C _H	—	—	—	—	Reserved [S]
000840 _H	FCTL R[R/W] H -0--1000 0--0----		—	FSTR[R/W] B ----001	Flash memory register [S]
000844 _H to 000854 _H	—	—	—	—	Reserved [S]
000858 _H	—	—	WREN[R/W] H 00000000 00000000		Wild register [S]
00085C _H to 00087C _H	—	—	—	—	Reserved [S]
000880 _H	WRAR00[R/W] W ----- --XXXXXX XXXXXXXXXXX XXXXXXX--				Wild register [S]
000884 _H	WRDR00[R/W] W XXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				
000888 _H	WRAR01[R/W] W ----- --XXXXXX XXXXXXXXXXX XXXXXXX--				
00088C _H	WRDR01[R/W] W XXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				
000890 _H	WRAR02[R/W] W ----- --XXXXXX XXXXXXXXXXX XXXXXXX--				
000894 _H	WRDR02[R/W] W XXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				
000898 _H	WRAR03[R/W] W ----- --XXXXXX XXXXXXXXXXX XXXXXXX--				
00089C _H	WRDR03[R/W] W XXXXXXXX XXXXXXXXXXX XXXXXXXXXXX XXXXXXXXXXX				

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
0008A0 _H	WRAR04[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				Wild register [S]
0008A4 _H	WRDR04[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008A8 _H	WRAR05[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008AC _H	WRDR05[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008B0 _H	WRAR06[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008B4 _H	WRDR06[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008B8 _H	WRAR07[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008BC _H	WRDR07[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008C0 _H	WRAR08[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008C4 _H	WRDR08[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008C8 _H	WRAR09[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008CC _H	WRDR09[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008D0 _H	WRAR10[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008D4 _H	WRDR10[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008D8 _H	WRAR11[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008DC _H	WRDR11[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008E0 _H	WRAR12[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008E4 _H	WRDR12[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008E8 _H	WRAR13[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008EC _H	WRDR13[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008F0 _H	WRAR14[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				
0008F4 _H	WRDR14[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
0008F8 _H	WRAR15[R/W] W ----- --XXXXXX XXXXXXXX XXXXXX--				

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
0008FC _H	WRDR15[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				Wild register [S]
000900 _H to 000BF8 _H	—	—	—	—	Reserved
000BFC _H	—	—	UER [W] B,H,W -----X		OCDU
000C00 _H	DCCR0[R/W] W 0---000 --00--00 00000000 0-000000				DMA controller [S]
000C04 _H	DCSR0[R/W] H 0----- ----000		DTCR0[R/W] H 00000000 00000000		
000C08 _H	DSAR0[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C0C _H	DDAR0[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C10 _H	DCCR1[R/W] W 0---000 --00--00 00000000 0-000000				
000C14 _H	DCSR1[R/W] H 0----- ----000		DTCR1[R/W] H 00000000 00000000		
000C18 _H	DSAR1[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C1C _H	DDAR1[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C20 _H	DCCR2[R/W] W 0---000 --00--00 00000000 0-000000				
000C24 _H	DCSR2[R/W] H 0----- ----000		DTCR2[R/W] H 00000000 00000000		
000C28 _H	DSAR2[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C2C _H	DDAR2[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C30 _H	DCCR3[R/W] W 0---000 --00--00 00000000 0-000000				
000C34 _H	DCSR3[R/W] H 0----- ----000		DTCR3[R/W] H 00000000 00000000		
000C38 _H	DSAR3[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C3C _H	DDAR3[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C40 _H	DCCR4[R/W] W 0---000 --00--00 00000000 0-000000				
000C44 _H	DCSR4[R/W] H 0----- ----000		DTCR4[R/W] H 00000000 00000000		
000C48 _H	DSAR4[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				
000C4C _H	DDAR4[R/W] W XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX				

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000C50 _H	DCCR5[R/W] W 0----000 --00--00 00000000 0-000000				DMA controller [S]
000C54 _H	DCSR5[R/W] H 0----- ----000		DTCR5[R/W] H 00000000 00000000		
000C58 _H	DSAR5[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C5C _H	DDAR5[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C60 _H	DCCR6[R/W] W 0----000 --00--00 00000000 0-000000				
000C64 _H	DCSR6[R/W] H 0----- ----000		DTCR6[R/W] H 00000000 00000000		
000C68 _H	DSAR6[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C6C _H	DDAR6[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C70 _H	DCCR7[R/W] W 0----000 --00--00 00000000 0-000000				
000C74 _H	DCSR7[R/W] H 0----- ----000		DTCR7[R/W] H 00000000 00000000		
000C78 _H	DSAR7[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C7C _H	DDAR7[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C80 _H	DCCR8[R/W] W 0----000 --00--00 00000000 0-000000				
000C84 _H	DCSR8[R/W] H 0----- ----000		DTCR8[R/W] H 00000000 00000000		
000C88 _H	DSAR8[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C8C _H	DDAR8[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C90 _H	DCCR9[R/W] W 0----000 --00--00 00000000 0-000000				
000C94 _H	DCSR9[R/W] H 0----- ----000		DTCR9[R/W] H 00000000 00000000		
000C98 _H	DSAR9[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000C9C _H	DDAR9[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000CA0 _H	DCCR10[R/W] W 0----000 --00--00 00000000 0-000000				
000CA4 _H	DCSR10[R/W] H 0----- ----000		DTCR10[R/W] H 00000000 00000000		

Address	Address offset value / Register name				Block	
	+0	+1	+2	+3		
000CA8 _H	DSAR10[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				DMA Contorller [S]	
000CAC _H	DDAR10[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CB0 _H	DCCR11[R/W] W 0---000 --00--00 00000000 0-000000					
000CB4 _H	DCSR11[R/W] H 0----- ----000		DTCR11[R/W] H 00000000 00000000			
000CB8 _H	DSAR11[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CBC _H	DDAR11[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CC0 _H	DCCR12[R/W] W 0---000 --00--00 00000000 0-000000					
000CC4 _H	DCSR12[R/W] H 0----- ----000		DTCR12[R/W] H 00000000 00000000			
000CC8 _H	DSAR12[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CCC _H	DDAR12[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CD0 _H	DCCR13[R/W] W 0---000 --00--00 00000000 0-000000					
000CD4 _H	DCSR13[R/W] H 0----- ----000		DTCR13[R/W] H 00000000 00000000			
000CD8 _H	DSAR13[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CDC _H	DDAR13[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CE0 _H	DCCR14[R/W] W 0---000 --00--00 00000000 0-000000					
000CE4 _H	DCSR14[R/W] H 0----- ----000		DTCR14[R/W] H 00000000 00000000			
000CE8 _H	DSAR14[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CEC _H	DDAR14[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CF0 _H	DCCR15[R/W] W 0---000 --00--00 00000000 0-000000					
000CF4 _H	DCSR15[R/W] H 0----- ----000		DTCR15[R/W] H 00000000 00000000			
000CF8 _H	DSAR15[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000CFC _H	DDAR15[R/W] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX					
000D00 _H to 000DF0 _H	—	—	—	—		Reserved [S]

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000DF4 _H	—	—	DNMIR[R/W] B 0-----0	DILVR[R/W] B ---11111	DMA controller [S]
000DF8 _H	DMACR[R/W] W 0-----0-----0-----0-----				
000DFC _H	—	—	—	—	Reserved [S]
000E00 _H	DDR00[R/W] B,H,W 00000000	DDR01[R/W] B,H,W 00000000	DDR02[R/W] B,H,W 00000000	DDR03[R/W] B,H,W 00000000	Data direction register
000E04 _H	DDR04[R/W] B,H,W 00000000	DDR05[R/W] B,H,W 00000000	DDR06[R/W] B,H,W 00000000	DDR07[R/W] B,H,W 00000000	
000E08 _H	DDR08[R/W] B,H,W 00000000	DDR09[R/W] B,H,W 00000000	DDR10[R/W] B,H,W 00000000	DDR11[R/W] B,H,W 00000000	
000E0C _H	DDR12[R/W] B,H,W 00000000	DDR13[R/W] B,H,W 00-00000	—	—	
000E10 _H	DDRA[R/W] B,H,W 000000--	DDRB[R/W] B,H,W 000000--	DDRC[R/W] B,H,W 000000--	DDRD[R/W] B,H,W 000000--	
000E14 _H	DDRE[R/W] B,H,W 000000--	DDRF[R/W] B,H,W 000000--	DDRG[R/W] B,H,W 00000000	DDRH[R/W] B,H,W ---0---	
000E18 _H to 000E1C _H	—	—	—	—	
000E20 _H	PFR00[R/W] B,H,W 00000000	PFR01[R/W] B,H,W 00000000	PFR02[R/W] B,H,W 00000000	PFR03[R/W] B,H,W 00000000	Port function register
000E24 _H	PFR04[R/W] B,H,W 00000000	PFR05[R/W] B,H,W -0000000	PFR06[R/W] B,H,W 00000000	PFR07[R/W] B,H,W 00000000	
000E28 _H	PFR08[R/W] B,H,W 00000000	PFR09[R/W] B,H,W 0-000000	PFR10[R/W] B,H,W 00000000	PFR11[R/W] B,H,W 00000000	
000E2C _H	PFR12[R/W] B,H,W 0-000000	PFR13[R/W] B,H,W ---00000	—	—	
000E30 _H	PFRA[R/W] B,H,W -----	PFRB[R/W] B,H,W -----	PFRC[R/W] B,H,W -----	PFRD[R/W] B,H,W 000000--	
000E34 _H	PFRE[R/W] B,H,W 000000--	PFRF[R/W] B,H,W 000000--	PFRG[R/W] B,H,W 00000---	PFRH[R/W] B,H,W -----	
000E38 _H to 000E3C _H	—	—	—	—	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000E40 _H	PDDR00[R] B,H,W XXXXXXXXXX	PDDR01[R] B,H,W XXXXXXXXXX	PDDR02[R] B,H,W XXXXXXXXXX	PDDR03[R] B,H,W XXXXXXXXXX	Input data direct read register
000E44 _H	PDDR04[R] B,H,W XXXXXXXXXX	PDDR05[R] B,H,W XXXXXXXXXX	PDDR06[R] B,H,W XXXXXXXXXX	PDDR07[R] B,H,W XXXXXXXXXX	
000E48 _H	PDDR08[R] B,H,W XXXXXXXXXX	PDDR09[R] B,H,W XXXXXXXXXX	PDDR10[R] B,H,W XXXXXXXXXX	PDDR11[R] B,H,W XXXXXXXXXX	
000E4C _H	PDDR12[R] B,H,W XXXXXXXXXX	PDDR13[R] B,H,W XX-XXXXXX	—	—	
000E50 _H	PDDRA[R] B,H,W XXXXXXX--	PDDRB[R] B,H,W XXXXXXX--	PDDRC[R] B,H,W XXXXXXX--	PDDRD[R] B,H,W XXXXXXX--	
000E54 _H	PDDRE[R] B,H,W XXXXXXX--	PDDRF[R] B,H,W XXXXXXX--	PDDRG[R] B,H,W XXXXXXXXXX	PDDRH[R] B,H,W ----X--	
000E58 _H to 000E5C _H	—	—	—	—	
000E60 _H	EPFR00[R/W] B,H,W 00000000	EPFR01[R/W] B,H,W ---0000	EPFR02[R/W] B,H,W ---00000	EPFR03[R/W] B,H,W ---00000	Extended port function register
000E64 _H	EPFR04[R/W] B,H,W ---00000	EPFR05[R/W] B,H,W ---00000	EPFR06[R/W] B,H,W ---00000	EPFR07[R/W] B,H,W ---00000	
000E68 _H	EPFR08[R/W] B,H,W ---00000	EPFR09[R/W] B,H,W ---00000	EPFR10[R/W] B,H,W -0000000	EPFR11[R/W] B,H,W --000000	
000E6C _H	EPFR12[R/W] B,H,W --000000	EPFR13[R/W] B,H,W --000000	EPFR14[R/W] B,H,W --000000	EPFR15[R/W] B,H,W -0000000	
000E70 _H	EPFR16[R/W] B,H,W 00000000	EPFR17[R/W] B,H,W 00000000	EPFR18[R/W] B,H,W 10000000	EPFR19[R/W] B,H,W 11111111	
000E74 _H	EPFR20[R/W] B,H,W -1111111	EPFR21[R/W] B,H,W 00000000	EPFR22[R/W] B,H,W 00000000	EPFR23[R/W] B,H,W 00000000	
000E78 _H	EPFR24[R/W] B,H,W ----000	EPFR25[R/W] B,H,W ----000	EPFR26[R/W] B,H,W ----0000	EPFR27[R/W] B,H,W ---00000	
000E7C _H	EPFR28[R/W] B,H,W -----00	EPFR29[R/W] B,H,W 00000000	EPFR30[R/W] B,H,W 00000000	EPFR31[R/W] B,H,W 00000000	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000E80 _H	EPFR32[R/W] B,H,W 00000000	EPFR33[R/W] B,H,W ---00000	EPFR34[R/W] B,H,W ---00000	EPFR35[R/W] B,H,W ---00000	Extended port function register
000E84 _H	EPFR36[R/W] B,H,W ---00000	EPFR37[R/W] B,H,W 00000000	EPFR38[R/W] B,H,W ---00000	EPFR39[R/W] B,H,W 00000000	
000E88 _H	EPFR40[R/W] B,H,W --000000	EPFR41[R/W] B,H,W ----000	EPFR42[R/W] B,H,W -----00	EPFR43[R/W] B,H,W 00000000	
000E8C _H	EPFR44[R/W] B,H,W 00000000	EPFR45[R/W] B,H,W 00000000	EPFR46[R/W] B,H,W --000000	EPFR47[R/W] B,H,W -----0	
000E90 _H	EPFR48[R/W] B,H,W 00000000	EPFR49[R/W] B,H,W 00000000	EPFR50[R/W] B,H,W 00000000	EPFR51[R/W] B,H,W ---00000	
000E94 _H	EPFR52[R/W] B,H,W ----000	EPFR53[R/W] B,H,W ---00000	EPFR54[R/W] B,H,W ----0000	EPFR55[R/W] B,H,W -----01	
000E98 _H to 000E9C _H	—	—	—	—	Reserved
000EA0 _H	PPCR00[R/W] B,H,W 11111111	PPCR01[R/W] B,H,W 11111111	PPCR02[R/W] B,H,W 11111111	PPCR03[R/W] B,H,W 11111111	Port pull-up/down control register
000EA4 _H	PPCR04[R/W] B,H,W 11111111	PPCR05[R/W] B,H,W 11111111	PPCR06[R/W] B,H,W 11111111	PPCR07[R/W] B,H,W 11111111	
000EA8 _H	PPCR08[R/W] B,H,W 11111111	PPCR09[R/W] B,H,W 11111111	PPCR10[R/W] B,H,W 11111111	PPCR11[R/W] B,H,W 11111111	
000EAC _H	PPCR12[R/W] B,H,W 11111111	PPCR13[R/W] B,H,W 11-11111	—	—	
000EB0 _H	PPCRA[R/W] B,H,W 111111--	PPCRB[R/W] B,H,W 111111--	PPCRC[R/W] B,H,W 111111--	PPCRD[R/W] B,H,W 111111--	
000EB4 _H	PPCRE[R/W] B,H,W 111111--	PPCRF[R/W] B,H,W 111111--	PPCRG[R/W] B,H,W 11111111	PPCRH[R/W] B,H,W ---1---	
000EB8 _H to 000EBC _H	—	—	—	—	Reserved
000EC0 _H	PPER00[R/W] B,H,W 00000000	PPER01[R/W] B,H,W 00000000	PPER02[R/W] B,H,W 00000000	PPER03[R/W] B,H,W 00000000	Port pull-up/down enable register
000EC4 _H	PPER04[R/W] B,H,W 00000000	PPER05[R/W] B,H,W 00000000	PPER06[R/W] B,H,W 00000000	PPER07[R/W] B,H,W 00000000	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000EC8 _H	PPER08[R/W] B,H,W 00000000	PPER09[R/W] B,H,W 00000000	PPER10[R/W] B,H,W 00000000	PPER11[R/W] B,H,W 00000000	Port pull-up/down enable register
000ECC _H	PPER12[R/W] B,H,W 00000000	PPER13[R/W] B,H,W 00-00000	—	—	
000ED0 _H	PPERA[R/W] B,H,W 000000--	PPERB[R/W] B,H,W 000000--	PPERC[R/W] B,H,W 000000--	PPERD[R/W] B,H,W 000000--	
000ED4 _H	PPERE[R/W] B,H,W 000000--	PPERF[R/W] B,H,W 000000--	PPERG[R/W] B,H,W 00000000	PPERH[R/W] B,H,W ---0---	
000ED8 _H to 000EDC _H	—	—	—	—	Reserved
000EE0 _H	PILR00[R/W] B,H,W 11111111	PILR01[R/W] B,H,W 11111111	PILR02[R/W] B,H,W 11111111	PILR03[R/W] B,H,W 11111111	Port input level selection register
000EE4 _H	PILR04[R/W] B,H,W 11111111	PILR05[R/W] B,H,W 11111111	PILR06[R/W] B,H,W 11111111	PILR07[R/W] B,H,W 11111111	
000EE8 _H	PILR08[R/W] B,H,W 11111111	PILR09[R/W] B,H,W 11111111	PILR10[R/W] B,H,W 11111111	PILR11[R/W] B,H,W 11111111	
000EEC _H	PILR12[R/W] B,H,W 11111111	PILR13[R/W] B,H,W 11-11111	—	—	
000EF0 _H	PILRA[R/W] B,H,W 111111--	PILRB[R/W] B,H,W 111111--	PILRC[R/W] B,H,W 111111--	PILRD[R/W] B,H,W 111111--	
000EF4 _H	PILRE[R/W] B,H,W 111111--	PILRF[R/W] B,H,W 111111--	PILRG[R/W] B,H,W 11111111	PILRH[R/W] B,H,W ---1---	
000EF8 _H to 000EFC _H	—	—	—	—	Reserved
000F00 _H	—	—	—	—	Extended Port input level selection register
000F04 _H	—	—	EPILR06[R/W] B,H,W 00000000	EPILR07[R/W] B,H,W 00000000	
000F08 _H	EPILR08[R/W] B,H,W 00000000	EPILR09[R/W] B,H,W 00000000	EPILR10[R/W] B,H,W 00000000	EPILR11[R/W] B,H,W 00000000	
000F0C _H	EPILR12[R/W] B,H,W 00000000	EPILR13[R/W] B,H,W 00-00000	—	—	
000F10 _H	—	—	—	—	
000F14 _H	—	—	—	—	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000F18 _H to 000F1C _H	—	—	—	—	Reserved
000F20 _H	—	—	—	—	Port output drive register
000F24 _H	—	—	PODR06[R/W] B,H,W 00000000	PODR07[R/W] B,H,W 00000000	
000F28 _H	PODR08[R/W] B,H,W 00000000	PODR09[R/W] B,H,W 00000000	PODR10[R/W] B,H,W 00000000	PODR11[R/W] B,H,W 00000000	
000F2C _H	PODR12[R/W] B,H,W 00000000	PODR13[R/W] B,H,W 00-00000	—	—	
000F30 _H	—	—	—	—	
000F34 _H	—	—	—	—	
000F38 _H	EPODR06[R/W] B,H,W 00000000	EPODR07[R/W] B,H,W 00000000	EPODR08[R/W] B,H,W 00000000	—	Extended Port output drive register
000F3C _H	EPODRGD [R/W]B,H,W ----1010	EPODRGF [R/W]B,H,W --101010	—	—	
000F40 _H	PORTEN [R/W] B,H,W -----0	—	—	—	Port input enable register
000F44 _H to 000F4C _H	—	—	—	—	Reserved
000F50 _H	—	GPLLCR[R/W] B,H,W 0-----0	PTIMCR[R/W] B,H,W ----1111	PEDIVCR[R/W] B,H,W -000-000	GDC control register
000F54 _H	—	PDIVCR[R/W] B,H,W -0000000	SDIVCR0[R/W] B,H,W --000000	SDIVCR1[R/W] B,H,W ---00000	
000F58 _H	—	SSSCR0[R/W] B,H,W ---0000	SSSCR1[R/W] H,W 000-----		
000F5C _H	—	PGRCR0[R/W] B,H,W 00----00	PGRCR1[R/W] B,H,W 00000000	PGRCR2[R/W] B,H,W 00000000	
000F60 _H	—	SGRCR0[R/W] B,H,W 00----00	SGRCR1[R/W] B,H,W 00000000	SGRCR2[R/W] B,H,W 00000000	
000F64 _H	—	GDCCR[R/W] B,H,W --000001	GDCTRGR [R/W] B,H,W 0000-00	GDCSWPR [R/W] B,H,W ---00101	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
000F68 _H to 000F9C _H	—	—	—	—	Reserved
000FA0 _H	CPCLR2 [R/W] W 11111111 11111111 11111111 11111111				Dedicated LSYN input capture free-run timer 2
000FA4 _H	TCDT2 [R/W] W 00000000 00000000 00000000 00000000				
000FA8 _H	TCCSH2 [R/W] B, H, W 0----00	TCCSL2 [R/W] B, H, W -1-00000	—		
000FAC _H	CPCLR3 [R/W] W 11111111 11111111 11111111 11111111				Dedicated LSYN input capture free-run timer 3
000FB0 _H	TCDT3 [R/W] W 00000000 00000000 00000000 00000000				
000FB4 _H	TCCSH3 [R/W] B, H, W 0----00	TCCSL3 [R/W] B, H, W -1-00000	—		
000FB8 _H to 000FCC _H	—	—	—	—	Reserved
000FD0 _H	IPCP6 [R] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				Dedicated LSYN input capture 6,7
000FD4 _H	IPCP7 [R] W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
000FD8 _H	ICFS67 [R/W] B, H, W -----00	—	LSYNS1 [R/W] B,H,W -----00	ICS67 [R/W] B, H, W 00000000	
000FDC _H to 000FFC _H	—	—	—	—	Reserved
001000 _H	SACR [R/W] B,H,W -----0	PICD [R/W] B,H,W ----0011	—	—	Synchronous/ asynchronous switching control
001004 _H to 00103C _H	—	—	—	—	Reserved
001040 _H	—	SGDER0[R/W] B,H,W 00000000	SGCR0[R/W] B,H,W -0000-0- 000--000		Sound generator 0
001044 _H	SGAR0[R/W] B,H,W 00000000 00000000		SGFR0[R/W] B,H,W 00000000	SGNR0[R/W] B,H,W 00000000	
001048 _H	SGTCR0[R/W] B,H,W 00000000	SGIDR0[R/W] B,H,W 00000000	SGPCR0[R/W] B,H,W 00000000 11111111		
00104C _H	SGDMAR0[W] B,H,W 00000000 00000000 00000000 00000000				

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
001050 _H to 00105C _H	—	—	—	—	Reserved
001060 _H	—	SGDER1[R/W] B,H,W 00000000	SGCR1[R/W] B,H,W -0000-0- 000--000		Sound generator 1
001064 _H	SGAR1[R/W] B,H,W 00000000 00000000		SGFR1[R/W] B,H,W 00000000	SGNR1[R/W] B,H,W 00000000	
001068 _H	SGTCR1[R/W] B,H,W 00000000	SGIDR1[R/W] B,H,W 00000000	SGPCR1[R/W] B,H,W 00000000 11111111		
00106C _H	SGDMAR1[W] B,H,W 00000000 00000000 00000000 00000000				
001070 _H to 00107C _H	—	—	—	—	Reserved
001080 _H	—	SGDER2[R/W] B,H,W 00000000	SGCR2[R/W] B,H,W -0000-0- 000--000		Sound generator 2
001084 _H	SGAR2[R/W] B,H,W 00000000 00000000		SGFR2[R/W] B,H,W 00000000	SGNR2[R/W] B,H,W 00000000	
001088 _H	SGTCR2[R/W] B,H,W 00000000	SGIDR2[R/W] B,H,W 00000000	SGPCR2[R/W] B,H,W 00000000 11111111		
00108C _H	SGDMAR2[W] B,H,W 00000000 00000000 00000000 00000000				
001090 _H to 00109C _H	—	—	—	—	Reserved
0010A0 _H	—	SGDER3[R/W] B,H,W 00000000	SGCR3[R/W] B,H,W -0000-0- 000—000		Sound generator 3
0010A4 _H	SGAR3[R/W] B,H,W 00000000 00000000		SGFR3[R/W] B,H,W 00000000	SGNR3[R/W] B,H,W 00000000	
0010A8 _H	SGTCR3[R/W] B,H,W 00000000	SGIDR3[R/W] B,H,W 00000000	SGPCR3[R/W] B,H,W 00000000 11111111		
0010AC _H	SGDMAR3[W] B,H,W 00000000 00000000 00000000 00000000				
0010B0 _H to 0010BC _H	—	—	—	—	Reserved

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
0010C0 _H	—	SGDER4[R/W] B,H,W 00000000	SGCR4[R/W] B,H,W -0000-0- 000-000		Sound generator 4
0010C4 _H	SGAR4[R/W] B,H,W 00000000 00000000		SGFR4[R/W] B,H,W 00000000	SGNR4[R/W] B,H,W 00000000	
0010C8 _H	SGTCR4[R/W] B,H,W 00000000	SGIDR4[R/W] B,H,W 00000000	SGPCR4[R/W] B,H,W 00000000 11111111		
0010CC _H	SGDMAR4[W] B,H,W 00000000 00000000 00000000 00000000				
0010D0 _H to 00112C _H	—	—	—	—	Reserved
001130 _H	—	—	—	CRCCR[R/W] B,H,W -0000000	CRC arithmetic operation
001134 _H	CRCINIT[R/W] B,H,W 1111111 1111111 1111111 1111111				
001138 _H	CRCIN[R/W] B,H,W 00000000 00000000 00000000 00000000				
00113C _H	CRCR[R] B,H,W 1111111 1111111 1111111 1111111				
001140 _H to 0013FC _H	—	—	—	—	Reserved
001400 _H to 001FFC _H	—	—	—	—	Reserved(3KB)
002000 _H	CTRLR0 [R/W] B,H,W ----- 000-0001		STATR0[R/W] B,H,W ----- 00000000		CAN0 (64msb)
002004 _H	ERRCNT0 [R] B,H,W 00000000 00000000		BTR0[R/W] B,H,W -0100011 00000001		
002008 _H	INTR0 [R] B,H,W 00000000 00000000		TESTR0[R/W] B,H,W ----- X00000--		
00200C _H	BRPER0 [R/W] B,H,W ----- ----0000		—		
002010 _H	IF1CREQ0 [R/W] B,H,W 0----- 00000001		IF1CMSK0 [R/W] B,H,W ----- 00000000		
002014 _H	IF1MSK20 [R/W] B,H,W 11-11111 11111111		IF1MSK10 [R/W] B,H,W 11111111 11111111		
002018 _H	IF1ARB20 [R/W] B,H,W 00000000 00000000		IF1ARB10 [R/W] B,H,W 00000000 00000000		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
00201C _H	IF1MCTR0 [R/W] B,H,W 00000000 0---0000		—		CAN0 (64msb)
002020 _H	IF1DTA10 [R/W] B,H,W 00000000 00000000		IF1DTA20[R/W] B,H,W 00000000 00000000		
002024 _H	IF1DTB10 [R/W] B,H,W 00000000 00000000		IF1DTB20 [R/W] B,H,W 00000000 00000000		
002028 _H 00202C _H	Reserved				
002030 _H 002034 _H	Reserved (IF1 data mirror)				
002038 _H 00203C _H	Reserved				
002040 _H	IF2CREQ0 [R/W] B,H,W 0----- 00000001		IF2CMSK0 [R/W] B,H,W ----- 00000000		
002044 _H	IF2MSK20 [R/W] B,H,W 11-11111 11111111		IF2MSK10 [R/W] B,H,W 11111111 11111111		
002048 _H	IF2ARB20 [R/W] B,H,W 00000000 00000000		IF2ARB10 [R/W] B,H,W 00000000 00000000		
00204C _H	IF2MCTR0 [R/W] B,H,W 00000000 0---0000		—		
002050 _H	IF2DTA10 [R/W] B,H,W 00000000 00000000		IF2DTA20 [R/W] B,H,W 00000000 00000000		
002054 _H	IF2DTB10 [R/W] B,H,W 00000000 00000000		IF2DTB20 [R/W] B,H,W 00000000 00000000		
002058 _H 00205C _H	Reserved				
002060 _H 002064 _H	Reserved (IF2 data mirror)				
002068 _H to 00207C _H	Reserved				
002080 _H	TREQR20 [R] B,H,W 00000000 00000000		TREQR10 [R] B,H,W 00000000 00000000		
002084 _H	TREQR40 [R] B,H,W 00000000 00000000		TREQR30 [R] B,H,W 00000000 00000000		
002088 _H	—		—		

Address	Address offset value / Register name				Block	
	+0	+1	+2	+3		
00208 _H	—		—		CAN0 (64msg)	
00209 _H	NEWDT20 [R] B,H,W 00000000 00000000		NEWDT10 [R] B,H,W 00000000 00000000			
002094 _H	NEWDT40 [R] B,H,W 00000000 00000000		NEWDT30 [R] B,H,W 00000000 00000000			
002098 _H	—		—			
00209C _H	—		—			
0020A0 _H	INTPND20 [R] B,H,W 00000000 00000000		INTPND10 [R] B,H,W 00000000 00000000			
0020A4 _H	INTPND40 [R] B,H,W 00000000 00000000		INTPND30 [R] B,H,W 00000000 00000000			
0020A8 _H	—		—			
0020AC _H	—		—			
0020B0 _H	MSGVAL20 [R] B,H,W 00000000 00000000		MSGVAL10 [R] B,H,W 00000000 00000000			
0020B4 _H	MSGVAL40 [R] B,H,W 00000000 00000000		MSGVAL30 [R] B,H,W 00000000 00000000			
0020B8 _H	—		—			
0020BC _H	—		—			
0020C0 _H to 0020FC _H	Reserved					
002100 _H	CTRLR1 [R/W] B,H,W ----- 000-0001		STATR1[R/W] B,H,W ----- 00000000			CAN1 (32msg)
002104 _H	ERRCNT1 [R] B,H,W 00000000 00000000		BTR1[R/W] B,H,W -0100011 00000001			
002108 _H	INTR1 [R] B,H,W 00000000 00000000		TESTR1[R/W] B,H,W ----- X00000--			
00210C _H	BRPER1 [R/W] B,H,W ----- ----0000		—			
002110 _H	IF1CREQ1 [R/W] B,H,W 0----- 00000001		IF1CMSK1 [R/W] B,H,W ----- 00000000			

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
002114 _H	IF1MSK21 [R/W] B,H,W 11-11111 11111111		IF1MSK11 [R/W] B,H,W 11111111 11111111		CAN1 (32msg)
002118 _H	IF1ARB21 [R/W] B,H,W 00000000 00000000		IF1ARB11 [R/W] B,H,W 00000000 00000000		
00211C _H	IF1MCTR1 [R/W] B,H,W 00000000 0---0000		—		
002120 _H	IF1DTA11 [R/W] B,H,W 00000000 00000000		IF1DTA21 [R/W] B,H,W 00000000 00000000		
002124 _H	IF1DTB11 [R/W] B,H,W 00000000 00000000		IF1DTB21 [R/W] B,H,W 00000000 00000000		
002128 _H 00212C _H	Reserved				
002130 _H 002134 _H	Reserved (IF1 data mirror)				
002138 _H 00213C _H	Reserved				
002140 _H	IF2CREQ1 [R/W] B,H,W 0----- 00000001		IF2CMSK1 [R/W] B,H,W ----- 00000000		
002144 _H	IF2MSK21 [R/W] B,H,W 11-11111 11111111		IF2MSK11 [R/W] B,H,W 11111111 11111111		
002148 _H	IF2ARB21 [R/W] B,H,W 00000000 00000000		IF2ARB11 [R/W] B,H,W 00000000 00000000		
00214C _H	IF2MCTR1 [R/W] B,H,W 00000000 0---0000		—		
002150 _H	IF2DTA11 [R/W] B,H,W 00000000 00000000		IF2DTA21 [R/W] B,H,W 00000000 00000000		
002154 _H	IF2DTB11 [R/W] B,H,W 00000000 00000000		IF2DTB21 [R/W] B,H,W 00000000 00000000		
002158 _H 00215C _H	Reserved				
002160 _H 002164 _H	Reserved (IF2 data mirror)				
002168 _H to 00217C _H	Reserved				
002180 _H	TREQR21 [R] B,H,W 00000000 00000000		TREQR11 [R] B,H,W 00000000 00000000		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
002184 _H	—		—		CAN1 (32msg)
002188 _H	—		—		
00218C _H	—		—		
002190 _H	NEWDT21 [R] B,H,W 00000000 00000000		NEWDT11 [R] B,H,W 00000000 00000000		
002194 _H	—		—		
002198 _H	—		—		
00219C _H	—		—		
0021A0 _H	INTPND21 [R] B,H,W 00000000 00000000		INTPND11 [R] B,H,W 00000000 00000000		
0021A4 _H	—		—		
0021A8 _H	—		—		
0021AC _H	—		—		
0021B0 _H	MSGVAL21 [R] B,H,W 00000000 00000000		MSGVAL11 [R] B,H,W 00000000 00000000		
0021B4 _H	—		—		
0021B8 _H	—		—		
0021BC _H	—		—		
0021C0 _H to 0021FC _H	Reserved				
002200 _H	CTRLR2 [R/W] B,H,W ----- 000-0001		STATR2[R/W] B,H,W ----- 00000000		CAN2 (32msg)
002204 _H	ERRCNT2[R] B,H,W 00000000 00000000		BTR2[R/W] B,H,W -0100011 00000001		
002208 _H	INTR2[R] B,H,W 00000000 00000000		TESTR2[R/W] B,H,W ----- X00000--		
00220C _H	BRPER2 [R/W] B,H,W ----- ----0000		—		
002210 _H	IF1CREQ2[R/W] B,H,W 0----- 00000001		IF1CMSK2[R/W] B,H,W ----- 00000000		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
002214 _H	IF1MSK22 [R/W] B,H,W 11-11111 11111111		IF1MSK12[R/W] B,H,W 11111111 11111111		CAN2 (32msg)
002218 _H	IF1ARB22 [R/W] B,H,W 00000000 00000000		IF1ARB12[R/W] B,H,W 00000000 00000000		
00221C _H	IF1MCTR2[R/W] B,H,W 00000000 0---0000		—		
002220 _H	IF1DTA12 [R/W] B,H,W 00000000 00000000		IF1DTA22[R/W] B,H,W 00000000 00000000		
002224 _H	IF1DTB12 [R/W] B,H,W 00000000 00000000		IF1DTB22[R/W] B,H,W 00000000 00000000		
002228 _H , 00222C _H	Reserved				
002230 _H , 002234 _H	Reserved (IF1 data mirror)				
002238 _H , 00223C _H	Reserved				
002240 _H	IF2CREQ2[R/W] B,H,W 0----- 00000001		IF2CMSK2[R/W] B,H,W ----- 00000000		
002244 _H	IF2MSK22 [R/W] B,H,W 11-11111 11111111		IF2MSK12[R/W] B,H,W 11111111 11111111		
002248 _H	IF2ARB22[R/W] B,H,W 00000000 00000000		IF2ARB12[R/W] B,H,W 00000000 00000000		
00224C _H	IF2MCTR2[R/W] B,H,W 00000000 0---0000		—		
002250 _H	IF2DTA12[R/W] B,H,W 00000000 00000000		IF2DTA22[R/W] B,H,W 00000000 00000000		
002254 _H	IF2DTB12[R/W] B,H,W 00000000 00000000		IF2DTB22[R/W] B,H,W 00000000 00000000		
002258 _H , 00225C _H	Reserved				
002260 _H , 002264 _H	Reserved (IF2 data mirror)				
002268 _H to 00227C _H	Reserved				
002280 _H	TREQR22[R] B,H,W 00000000 00000000		TREQR12[R] B,H,W 00000000 00000000		
002284 _H	—		—		
002288 _H	—		—		
00228C _H	—		—		

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
002290 _H	NEWDT22[R] B,H,W 00000000 00000000		NEWDT12[R] B,H,W 00000000 00000000		CAN2 (32msg)
002294 _H	—		—		
002298 _H	—		—		
00229C _H	—		—		
0022A0 _H	INTPND22[R] B,H,W 00000000 00000000		INTPND12[R] B,H,W 00000000 00000000		
0022A4 _H	—		—		
0022A8 _H	—		—		
0022AC _H	—		—		
0022B0 _H	MSGVAL22[R] B,H,W 00000000 00000000		MSGVAL12[R] B,H,W 00000000 00000000		
0022B4 _H	—		—		
0022B8 _H	—		—		
0022BC _H	—		—		
0022C0 _H to 0022FC _H	—	—	—	—	Reserved
002300 _H	DFCTLR[R/W]B,H,W -0-----_-----		—	DFSTR [R/W] B,H,W -----001	WorkFlash
002304 _H	—	—	—	—	
002308 _H	FLIFCTLR [R/W] B,H,W ---0--00	—	FLIFFER1 [R/W] B, H, W -----	FLIFFER2 [R/W] B, H, W -----	
00230C _H to 0023FC _H	—	—	—	—	Reserved
002400 _H	SEEARX[R] B,H,W --000000 00000000		DEEARX[R] B,H,W --000000 00000000		XBS RAM ECC control register
002404 _H	EECSRX [R/W] B,H,W ----0000	—	EFEARX[R/W] B,H,W --000000 00000000		
002408 _H	—	EFECRX[R/W] B,H,W -----0 00000000 00000000			
00240C _H to 0024FC _H	—	—	—	—	

Address	Address offset value / Register name				Block
	+0	+1	+2	+3	
003000 _H	SEEARA[R] B,H,W -----000 00000000		DEEARA[R] B,H,W -----000 00000000		Backup RAM ECC control register
003004 _H	ECSRA [R/W] B,H,W ----0000	—	EFEARA[R/W] B,H,W -----000 00000000		
003008 _H	—	EFECRA[R/W] B,H,W -----0 00000000 00000000			
00300C _H to 003FFC _H	—	—	—	—	Reserved
004000 _H to 005FFC _H	Backup RAM				Backup RAM area
006000 _H to 00FEFC _H	—	—	—	—	Reserved
00F000 _H to 00FEFC _H	—	—	—	—	Reserved [S]
00FF00 _H	DSUCR [R/W] B,H,W -----0		—	—	OCDU [S]
00FF04 _H to 00FF0C _H	—	—	—	—	Reserved [S]
00FF10 _H	PCSR [R/W] B,H,W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				OCDU [S]
00FF14 _H	PSSR [R/W] B,H,W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				
00FF18 _H to 00FFF4 _H	—	—	—	—	Reserved [S]
00FFF8 _H	EDIR1 [R] B,H,W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				OCDU [S]
00FFFC _H	EDIR0 [R] B,H,W XXXXXXXX XXXXXXXX XXXXXXXX XXXXXXXX				

[S] : It is a system register. The illegal instruction exception (data access error) is generated when reading and writing to these registers in the user mode.

*3 : Initial value depends on the part number of product. Detail is on section 3.1 in chapter "Clock Super Visor".

C. List of Interrupt Vector

The list of the Interrupt Vector is shown below.

This list shows the assignments of interrupt factors and interrupt vectors/interrupt control registers.

Table C-1 Interrupt Vector

Interrupt factor	Interrupt number		Interrupt level	Offset	Default address for TBR	RN *1
	Decimal	Hexadecimal				
Reset	0	00	-	3FC _H	000FFF _{FC} _H	-
System reserved	1	01	-	3F8 _H	000FFF _{F8} _H	-
System reserved	2	02	-	3F4 _H	000FFF _{F4} _H	-
System reserved	3	03	-	3F0 _H	000FFF _{F0} _H	-
System reserved	4	04	-	3EC _H	000FFF _{EC} _H	-
FPU exception	5	05	-	3E8 _H	000FFF _{E8} _H	-
Exception of instruction access protection violation	6	06	-	3E4 _H	000FFF _{E4} _H	-
Exception of data access protection violation	7	07	-	3E0 _H	000FFF _{E0} _H	-
Data access error interrupt	8	08	-	3DC _H	000FFF _{DC} _H	-
INTE instruction	9	09	-	3D8 _H	000FFF _{D8} _H	-
Instruction break	10	0A	-	3D4 _H	000FFF _{D4} _H	-
System Reserved	11	0B	-	3D0 _H	000FFF _{D0} _H	-
System Reserved	12	0C	-	3CC _H	000FFF _{CC} _H	-
System Reserved	13	0D	-	3C8 _H	000FFF _{C8} _H	-
Exception of invalid instruction	14	0E	-	3C4 _H	000FFF _{C4} _H	-
NMI request / XBS RAM double-bit error generation/ Backup RAM double-bit error generation	15	0F	15 (F _H) Fixed	3C0 _H	000FFF _{C0} _H	-
External interrupt 0-7	16	10	ICR00	3BC _H	000FFF _{BC} _H	0
External interrupt 8-15	17	11	ICR01	3B8 _H	000FFF _{B8} _H	1
Reload timer 0/1	18	12	ICR02	3B4 _H	000FFF _{B4} _H	2
Reload timer 2/3	19	13	ICR03	3B0 _H	000FFF _{B0} _H	3
Multi-function serial interface ch.0 (reception completed)/ Multi-function serial interface ch.0(status)	20	14	ICR04	3AC _H	000FFF _{AC} _H	4 (*2)
Multi-function serial interface ch.0(transmission completed)	21	15	ICR05	3A8 _H	000FFF _{A8} _H	5
Multi-function serial interface ch.1 (reception completed)/ Multi-function serial interface ch.1(status)	22	16	ICR06	3A4 _H	000FFF _{A4} _H	6 (*2)
Multi-function serial interface ch.1(transmission completed)	23	17	ICR07	3A0 _H	000FFF _{A0} _H	7
LIN-UART2(reception completed)	24	18	ICR08	39C _H	000FFF _{9C} _H	8

Interrupt factor	Interrupt number		Interrupt level	Offset	Default address for TBR	RN *1
	Decimal	Hexadecimal				
LIN-UART2(transmission completed)	25	19	ICR09	398 _H	000FFF98 _H	9
LIN-UART3(reception completed)	26	1A	ICR10	394 _H	000FFF94 _H	10
LIN-UART3(transmission completed)	27	1B	ICR11	390 _H	000FFF90 _H	11
LIN-UART4(reception completed)	28	1C	ICR12	38C _H	000FFF8C _H	12
LIN-UART4(transmission completed)	29	1D	ICR13	388 _H	000FFF88 _H	13
LIN-UART5(reception completed)	30	1E	ICR14	384 _H	000FFF84 _H	14
LIN-UART5(transmission completed)	31	1F	ICR15	380 _H	000FFF80 _H	15
LIN-UART6(reception completed)	32	20	ICR16	37C _H	000FFF7C _H	16
LIN-UART6(transmission completed)	33	21	ICR17	378 _H	000FFF78 _H	17
CAN0	34	22	ICR18	374 _H	000FFF74 _H	-
CAN1	35	23	ICR19	370 _H	000FFF70 _H	-
CAN2	36	24	ICR20	36C _H	000FFF6C _H	-
Real time clock	37	25	ICR21	368 _H	000FFF68 _H	-
Sound generator 0 / LIN-UART7(reception completed)	38	26	ICR22	364 _H	000FFF64 _H	22
Sound generator 1 / LIN-UART7(transmission completed)	39	27	ICR23	360 _H	000FFF60 _H	23
PPG0/1/10/11/20/21	40	28	ICR24	35C _H	000FFF5C _H	24
PPG2/3/12/13/22/23	41	29	ICR25	358 _H	000FFF58 _H	25
PPG4/5/14/15	42	2A	ICR26	354 _H	000FFF54 _H	26
PPG6/7/16/17	43	2B	ICR27	350 _H	000FFF50 _H	27
PPG8/9/18/19	44	2C	ICR28	34C _H	000FFF4C _H	28
GDC / GDC_ALM	45	2D	ICR29	348 _H	000FFF48 _H	29
Main timer/Sub timer/PLL timer	46	2E	ICR30	344 _H	000FFF44 _H	30
Clock calibration unit (Sub oscillation) / Sound generator 4	47	2F	ICR31	340 _H	000FFF40 _H	31 (*3)
A/D converter	48	30	ICR32	33C _H	000FFF3C _H	32
Clock calibration Unit (CR oscillation)	49	31	ICR33	338 _H	000FFF38 _H	33 (*3)
Free-run timer 0/2	50	32	ICR34	334 _H	000FFF34 _H	-
Free-run timer 1/3	51	33	ICR35	330 _H	000FFF30 _H	-
ICU0/6(fetching)	52	34	ICR36	32C _H	000FFF2C _H	36
ICU1/7(fetching)	53	35	ICR37	328 _H	000FFF28 _H	37
ICU2(fetching)	54	36	ICR38	324 _H	000FFF24 _H	38
ICU3(fetching)	55	37	ICR39	320 _H	000FFF20 _H	39
ICU4(fetching)	56	38	ICR40	31C _H	000FFF1C _H	40
ICU5(fetching)	57	39	ICR41	318 _H	000FFF18 _H	41
OCU0/1(match)	58	3A	ICR42	314 _H	000FFF14 _H	42
OCU2/3(match)	59	3B	ICR43	310 _H	000FFF10 _H	43
Base timer 0 IRQ0 / Base timer 0 IRQ1 / Sound generator 2	60	3C	ICR44	30C _H	000FFF0C _H	44

Interrupt factor	Interrupt number		Interrupt level	Offset	Default address for TBR	RN *1
	Decimal	Hexadecimal				
Base timer 1 IRQ0 / Base timer 1 IRQ1/ Sound generator 3 / XBS RAM single bit error generation / Backup RAM single bit error generation	61	3D	ICR45	308 _H	000FFF08 _H	45 (*4)
DMAC0/1/2/3/4/5/6/7/8/9/10/11/12/13/14/15	62	3E	ICR46	304 _H	000FFF04 _H	-
Delay interrupt	63	3F	ICR47	300 _H	000FFF00 _H	-
System Reserved (Used for REALOS*5.)	64	40	-	2FC _H	000FFEFC _H	-
System Reserved (Used for REALOS*5.)	65	41	-	2F8 _H	000FFE8 _H	-
Used with the INT instruction.	66	42	-	2F4 _H	000FEF4 _H	-
	 255	 FF		 000 _H	 000FFC00 _H	

*1: Does not support a DMA transfer request caused by an interrupt generated from a peripheral to which no RN (Resource Number) is assigned.

*2: The status of the multi function serial interface does not support a DMA transfer caused by I²C reception.

*3: The clock calibration unit does not support a DMA transfer caused by an interrupt.

*4: No support for a DMA transfer caused by an interrupt because of the RAM ECC bit error.

*5: REALOS is the registered trademark of FUJITSU SEMICONDUCTOR Limited.

MN705-00009-3v0-E

FUJITSU SEMICONDUCTOR • CONTROLLER MANUAL

FR81S

32-BIT MICROCONTROLLER

MB91590 Series

HARDWARE MANUAL

November 2011 the 3rd edition

Published **FUJITSU SEMICONDUCTOR LIMITED**

Edited Sales Promotion Department.
