

# High Performance Regulators for PCs Main Power Supply for Notebook PCs (With Built-in Linear Regulator)



BD9528AMUV

No.11030JAT46

## ●Description

BD9528AMUV is a 2ch switching regulator controller with high output current which can achieve low output voltage (1.0V~5.5V) from a wide input voltage range (5.5V~28V). High efficiency for the switching regulator can be realized by utilizing an external N-MOSFET power transistor. A new technology called H<sup>3</sup>Reg<sup>TM</sup>(High speed, High efficiency, High performance) is a Rohm proprietary control method to realize ultra high transient response against load change. SLLM (Simple Light Load Mode) technology is also integrated to improve efficiency in light load mode, providing high efficiency over a wide load range. For protection and ease of use, 2ch LDO (5V/3.3V (total 100mA)), the soft start function, variable frequency function, short circuit protection function with timer latch, over voltage protection, and Power good function are all built in. This switching regulator is specially designed for Main Power Supply of laptop PC.

## ●Features

- 1) 2ch H<sup>3</sup>REG<sup>TM</sup> DC/DC Converter controller
- 2) Adjustable Simple Light Load Mode (SLLM), Quiet Light Load Mode (QLLM) and Forced continuous Mode
- 3) Thermal Shut Down (TSD), Under Voltage LockOut (UVLO), Over Current Protection (OCP), Over Voltage Protection (OVP), Short circuit protection with 0.75ms timer-latch (SCP)
- 4) Soft start function to minimize rush current during startup
- 5) Switching Frequency Variable (f=150kHz~500kHz)
- 6) Built-in Power good circuit
- 7) Built-in 2ch Linear regulator (5V/3.3V (total 100mA))
- 8) Built in reference voltage(0.7V)
- 9) VQFN032-V5050 package
- 10) Built-in BOOT-Di
- 11) Built-in output discharge
- 12) ESD Susceptibility ( HBM (Human Body Model) : 2kV, MM (Machine Model) : 200V )

## ●Applications

Laptop PC, Desktop PC, LCD-TV, Digital Components

●Maximum Absolute Ratings (Ta=25°C)

| Parameter                   | Symbol  | Limits                    | Unit |
|-----------------------------|---|---------------------------|------|
| Terminal Voltage            | VIN, CTL, SW1, SW2  | 30 <sup>*1*2</sup>        | V    |
|                             | EN1, EN2, PGOOD1, PGOOD2<br>Vo1, Vo2, MCTL1, MCTL2                | 6 <sup>*1*2</sup>         | V    |
|                             | FS1, FS2, FB1, FB2, ILIM1, ILIM2,<br>SS1, SS2, LG1, LG2, REF,REG2 | REG1+0.3 <sup>*1</sup>    | V    |
|                             | BOOT1, BOOT2  | 35 <sup>*1*2</sup>        | V    |
|                             | BOOT1-SW1, BOOT2-SW2,<br>HG1-SW1, HG2-SW2                         | 7 <sup>*1*2</sup>         | V    |
|                             | HG1   | BOOT1+0.3 <sup>*1*2</sup> | V    |
|                             | HG2   | BOOT2+0.3 <sup>*1*2</sup> | V    |
|                             | PGND1, PGND2  | AGND±0.3 <sup>*1*2</sup>  | V    |
| Power Dissipation1          | Pd1   | 0.38 <sup>*3</sup>        | W    |
| Power Dissipation2          | Pd2   | 0.88 <sup>*4</sup>        | W    |
| Power Dissipation3          | Pd3   | 3.26 <sup>*5</sup>        | W    |
| Power Dissipation4          | Pd4   | 4.56 <sup>*6</sup>        | W    |
| Operating temperature Range | Topr  | -20~+100                  | °C   |
| Storage temperature Range   | Tstg  | -55~+150                  | °C   |
| Junction Temperature        | Tjmax   | +150                      | °C   |

\*1 Do not however exceed Pd.

\*2 Instantaneous surge voltage, back electromotive force and voltage under less than 10% duty cycle.

\*3 Reduced by 3.0mW for each increase in Ta of 1°C over 25°C (when don't mounted on a heat radiation board )

\*4 Reduced by 7.0mW for increase in Ta of 1°C over 25°C. (when mounted on a board 74.2mm × 74.2mm × 1.6mm Glass-epoxy PCB which has 1 layer.  
(Copper foil area : 20.2mm<sup>2</sup>)

\*5 Reduced by 26.1mW for increase in Ta of 1°C over 25°C. (when mounted on a board 74.2mm × 74.2mm × 1.6mm Glass-epoxy PCB which has 4 layers.  
(1<sup>st</sup> and 4<sup>th</sup> copper foil area : 20.2mm<sup>2</sup>, 2<sup>nd</sup> and 3<sup>rd</sup> copper foil area : 5505mm<sup>2</sup>)

\*6 Reduced by 36.5mW for increase in Ta of 1°C over 25°C. (when mounted on a board 74.2mm × 74.2mm × 1.6mm Glass-epoxy PCB which has 4 layers.  
(All copper foil area : 5505mm<sup>2</sup>)

●Operating Conditions (Ta=25°C)

| Parameter        | Symbol                                    | Min. | Max. | Unit |
|------------------|---|------|------|------|
| Terminal Voltage | VIN                                       | 5.5  | 28   | V    |
|                  | CTL                                       | -0.3 | 28   | V    |
|                  | EN1, EN2, MCTL1, MCTL2                    | -0.3 | 5.5  | V    |
|                  | BOOT1, BOOT2                              | 4.5  | 33   | V    |
|                  | SW1, SW2                                  | -0.3 | 28   | V    |
|                  | BOOT1-SW1, BOOT2-SW2,<br>HG1-SW1, HG2-SW2 | -0.3 | 5.5  | V    |
|                  | Vo1, Vo2, PGOOD1, PGOOD2                  | -0.3 | 5.5  | V    |
| MIN ON TIME      | TONmin                                    | -    | 150  | nsec |

★ This product should not be used in a radioactive environment.

### ●ELECTRICAL CHARACTERISTICS

(Unless otherwise noted, Ta=25°C VIN=12V, CTL=OPEN, EN1=EN2=5V, FS1=FS2=51kΩ)

| Parameter                             | Symbol               | Limits |       |       | Unit | Condition                    |
|---------------------------------------|----------------------|--------|-------|-------|------|------------------------------|
|                                       |                      | Min.   | Typ.  | Max.  |      |                              |
| VIN standby current                   | ISTB                 | 70     | 150   | 250   | μA   | EN1=EN2=0V, CTL=5V           |
| VIN bias current                      | IIN                  | 60     | 130   | 230   | μA   | Vo1=5V                       |
| VIN shut down mode current            | ISHD                 | 6      | 12    | 18    | μA   | CTL=0V                       |
| CTL Low Voltage                       | VCTLL                | -0.3   | -     | 0.8   | V    |                              |
| CTL High Voltage                      | VCTLH                | 2.3    | -     | 28    | V    |                              |
| CTL bias current                      | ICTL                 | -18    | -12   | -6    | μA   | CTL=0V                       |
| EN Low Voltage                        | VENL                 | -0.3   | -     | 0.8   | V    |                              |
| EN High Voltage                       | VENH                 | 2.3    | -     | 5.5   | V    |                              |
| EN bias current                       | IEN                  | -      | 3     | 6     | μA   | EN=3V                        |
| <b>[5V linear regulator](VIN)</b>     |                      |        |       |       |      |                              |
| REG1 output voltage                   | VREG1                | 4.90   | 5.00  | 5.10  | V    | I <sub>REG1</sub> =1mA       |
| Maximum current                       | I <sub>REG1</sub>    | 100    | -     | -     | mA   | I <sub>REG2</sub> =0mA*      |
| Line Regulation                       | Reg.L1               | -      | 90    | 180   | mV   | VIN=5.5 to 28V               |
| Load Regulation                       | Reg.L1               | -      | 30    | 50    | mV   | I <sub>REG1</sub> =0 to 30mA |
| <b>[3.3V linear regulator]</b>        |                      |        |       |       |      |                              |
| REG2 output voltage                   | VREG2                | 3.27   | 3.30  | 3.33  | V    | I <sub>REG2</sub> =1mA       |
| Maximum current                       | I <sub>REG2</sub>    | 100    | -     | -     | mA   | I <sub>REG1</sub> =0mA*      |
| Line Regulation                       | Reg.L2               | -      | -     | 20    | mV   | VIN=5.5 to 28V               |
| Load Regulation                       | Reg.L2               | -      | -     | 30    | mV   | I <sub>REG2</sub> =0 to 30mA |
| <b>[5V linear regulator](Vo1)</b>     |                      |        |       |       |      |                              |
| Input threshold voltage               | REG1th               | 4.1    | 4.4   | 4.7   | V    | Vo1: Sweep up                |
| Input delay time                      | T <sub>REG1</sub>    | 1.5    | 3     | 6     | ms   |                              |
| Switch resistance                     | R <sub>REG1</sub>    | -      | 1.0   | 3.0   | Ω    |                              |
| <b>[Under Voltage lock out block]</b> |                      |        |       |       |      |                              |
| REG1 threshold voltage                | REG1_UVLO            | 3.9    | 4.2   | 4.5   | V    | REG1: Sweep up               |
| Hysteresis voltage                    | dV_UVLO              | 50     | 100   | 200   | mV   | REG1: Sweep down             |
| <b>[Output voltage sense block]</b>   |                      |        |       |       |      |                              |
| Feedback voltage1                     | VFB1                 | 0.693  | 0.700 | 0.707 | V    |                              |
| FB1 bias current                      | IFB1                 | -      | 0     | 1     | μA   | FB1=REF                      |
| Output discharge resistance1          | R <sub>DISOUT1</sub> | 50     | 100   | 200   | Ω    |                              |
| Feedback voltage2                     | VFB2                 | 0.693  | 0.700 | 0.707 | V    |                              |
| FB2 bias current                      | IFB2                 | -      | 0     | 1     | μA   | FB2=REF                      |
| Output discharge resistance2          | R <sub>DISOUT2</sub> | 50     | 100   | 200   | Ω    |                              |

\* I<sub>REG1</sub>+I<sub>REG2</sub> ≤ 100mA

### ●ELECTRICAL CHARACTERISTICS

(unless otherwise noted, Ta=25°C VIN=12V, CTL=OPEN, EN1=EN2=5V, FS1=FS2=51kΩ)

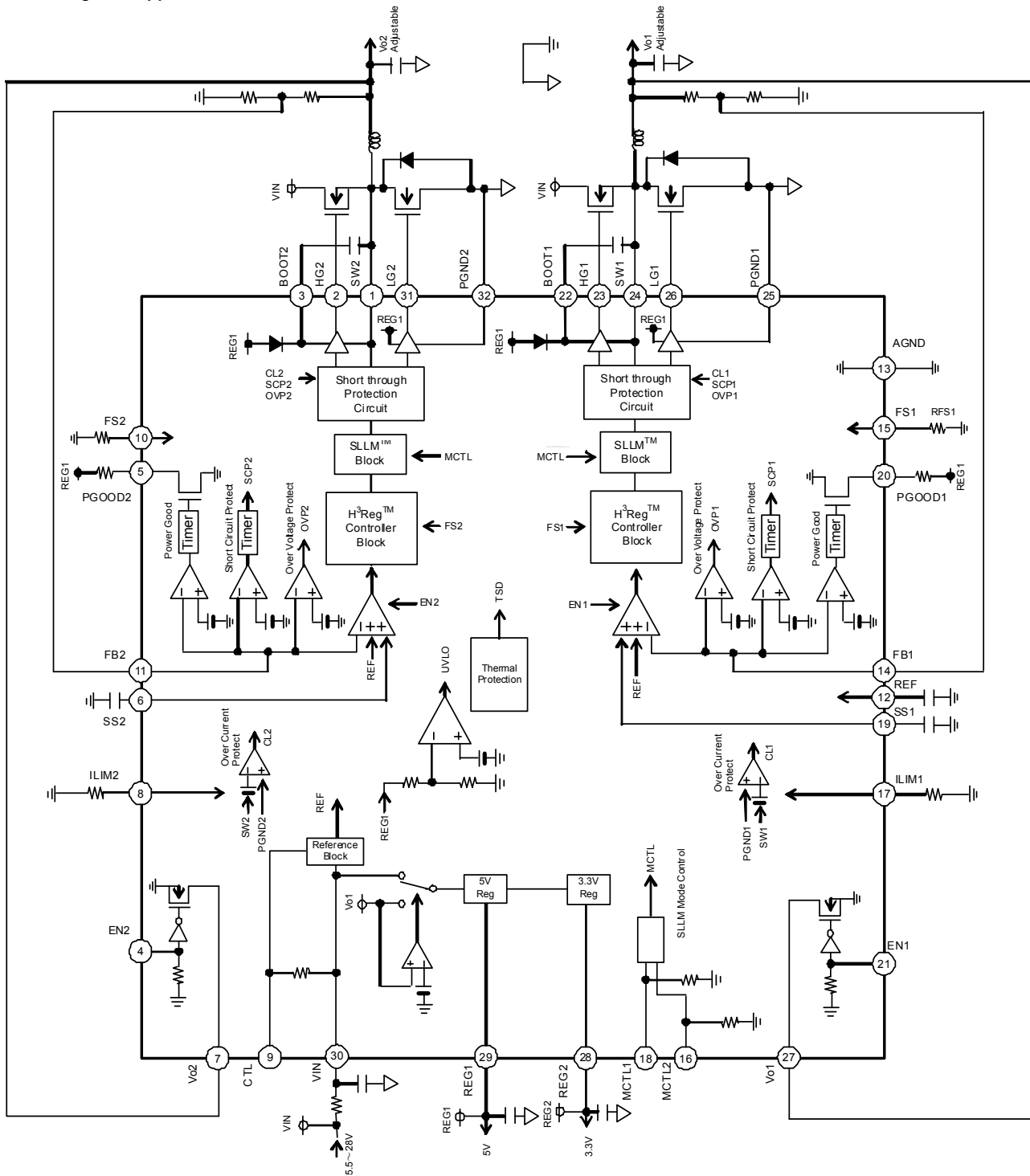
| Parameter                               | Symbol  | Limits          |                 |                | Unit | Condition  |
|---|---------|-----------------|-----------------|----------------|------|------------|
|   |         | Min.            | Typ.            | Max.           |      |            |
| <b>[H<sup>3</sup>REG block]</b>         |         |                 |                 |                |      |            |
| Ontime1                                 | TON1    | 0.760           | 0.910           | 1.060          | μs   | Vo1= 5V    |
| Ontime2                                 | TON2    | 0.470           | 0.620           | 0.770          | μs   | Vo2= 3.3V  |
| Maximum On time 1                       | TONMAX1 | 2.5             | 5               | 10             | μs   | Vo1= 5V    |
| Maximum On time 2                       | TONMAX2 | 1.65            | 3.3             | 6.6            | μs   | Vo2= 3.3V  |
| Minimum Off time                        | TOFFMIN | -               | 0.2             | 0.4            | μs   |            |
| <b>[FET driver block]</b>               |         |                 |                 |                |      |            |
| HG higher side ON resistor              | HGHON   | -               | 3.0             | 6.0            | Ω    |            |
| HG lower side ON resistor               | HGLON   | -               | 2.0             | 4.0            | Ω    |            |
| LG higher side ON resistor              | LGHON   | -               | 2.0             | 4.0            | Ω    |            |
| LG lower side ON resistor               | LGLON   | -               | 0.5             | 1.0            | Ω    |            |
| <b>[Over voltage protection block]</b>  |         |                 |                 |                |      |            |
| OVP threshold voltage                   | VOVP    | 0.77<br>(+10%)  | 0.84<br>(+20%)  | 0.91<br>(+30%) | V    |            |
| OVP Hysteresis                          | dV_OVP  | 50              | 150             | 300            | mV   |            |
| <b>[Short circuit protection block]</b> |         |                 |                 |                |      |            |
| SCP threshold voltage                   | VSCP    | 0.42<br>(-40%)  | 0.49<br>(-30%)  | 0.56<br>(-20%) | V    |            |
| Delay time                              | TSCP    | 0.4             | 0.75            | 1.5            | ms   |            |
| <b>Current limit protection block]</b>  |         |                 |                 |                |      |            |
| Offset voltage                          | dVSMAX  | 80              | 100             | 120            | mV   | ILIM=100kΩ |
| <b>[Power good block]</b>               |         |                 |                 |                |      |            |
| Power good low threshold                | VPGTHL  | 0.525<br>(-25%) | 0.595<br>(-15%) | 0.665<br>(-5%) | V    |            |
| Power good low voltage                  | VPGL    | -               | 0.1             | 0.2            | V    | IPGOOD=1mA |
| Delay time                              | TPGOOD  | 0.4             | 0.75            | 1.5            | ms   |            |
| Power good leakage current              | ILEAKPG | -2              | 0               | 2              | μA   | VPGOOD=5V  |
| <b>[Soft start block]</b>               |         |                 |                 |                |      |            |
| Charge current                          | ISS     | 1.5             | 2.3             | 3.1            | μA   |            |
| Standby voltage                         | VSS_STB | -               | -               | 50             | mV   |            |
| <b>[Mode control block]</b>             |         |                 |                 |                |      |            |
| MCTL Low voltage                        | VMCTL_L | -0.3            | -               | 0.3            | V    |            |
| MCTL High voltage                       | VMCTL_H | 2.3             | -               | REG1<br>+0.3   | V    |            |
| MCTL bias current                       | Imctl   | 8               | 16              | 24             | μA   | MCTL=5V    |

●Output condition table

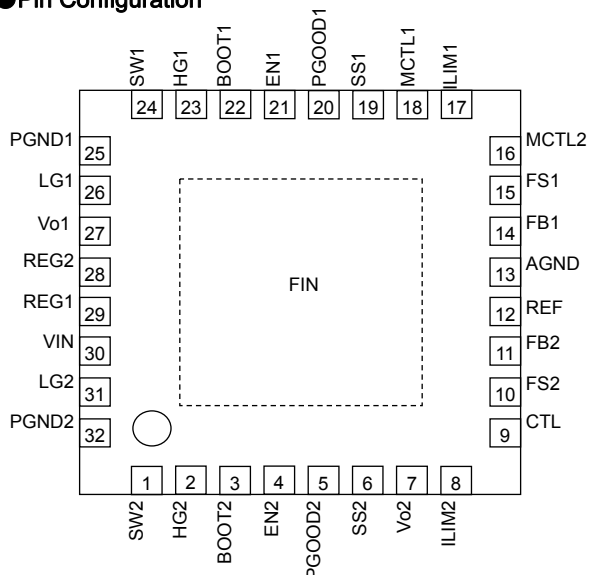
| Input |      |      | Output   |            |        |        |
|-------|------|------|----------|------------|--------|--------|
| CTL   | EN1  | EN2  | REG1(5V) | REG2(3.3V) | DC/DC1 | DC/DC2 |
| Low   | Low  | Low  | OFF      | OFF        | OFF    | OFF    |
| Low   | Low  | High | OFF      | OFF        | OFF    | OFF    |
| Low   | High | Low  | OFF      | OFF        | OFF    | OFF    |
| Low   | High | High | OFF      | OFF        | OFF    | OFF    |
| High  | Low  | Low  | ON       | ON         | OFF    | OFF    |
| High  | Low  | High | ON       | ON         | OFF    | ON     |
| High  | High | Low  | ON       | ON         | ON     | OFF    |
| High  | High | High | ON       | ON         | ON     | ON     |

※ CTL pin is connected to VIN pin with 1MΩ resistor(pull up) internal IC.  
 ※ EN pin is connected to AGND pin with 1MΩ resistor(pull down) internal IC.

●Block Diagram, Application circuit



● Pin Configuration



| Input |       | Control Mode           |
|-------|-------|------------------------|
| MCTL1 | MCTL2 |                        |
| Low   | Low   | SLLM                   |
| Low   | High  | QLLM                   |
| High  | Low   | Forced Continuous Mode |
| High  | High  | Forced Continuous Mode |

※ MCTL pin is connected to AGND pin with 500kΩ resistor ( pull down) internal IC

● Pin Function Table

| PIN No. | PIN name | PIN Function  |
|---------|----------|---|
| 1       | SW2      | Highside FET source pin 2                           |
| 2       | HG2      | Highside FET gate drive pin 2                       |
| 3       | BOOT2    | HG Driver power supply pin 2                        |
| 4       | EN2      | Vo2 ON/OFF pin (High=ON, Low,OPEN=OFF)              |
| 5       | PGOOD2   | Vo2 Power Good Open Drain Output pin                |
| 6       | SS2      | Vo2 Soft start pin                                  |
| 7       | Vo2      | Vo2 Output voltage sense pin                        |
| 8       | ILIM2    | OCP setting pin 2                                   |
| 9       | CTL      | Linear regulator ON/OFF pin (High,OPEN=ON, Low=OFF) |
| 10      | FS2      | Input pin for setting Vo2 frequency                 |
| 11      | FB2      | Vo2 output voltage feedback pin                     |
| 12      | REF      | Output voltage setting pin                          |
| 13      | AGND     | Input pin Ground                                    |
| 14      | FB1      | Vo1 output voltage feedback pin                     |
| 15      | FS1      | Input pin for setting Vo1 frequency                 |
| 16      | MCTL2    | Mode switch pin 2 ( OPEN = L )                      |
| 17      | ILIM1    | OCP setting pin 1                                   |
| 18      | MCTL1    | Mode switch pin 1 ( OPEN = L )                      |
| 19      | SS1      | Vo1 Soft start pin                                  |
| 20      | PGOOD1   | Vo1 Power Good Open Drain Output pin                |
| 21      | EN1      | Vo1 ON/OFF pin (High=ON, Low,OPEN=OFF)              |
| 22      | BOOT1    | HG Driver power supply pin                          |
| 23      | HG1      | Highside FET gate drive pin 1                       |
| 24      | SW1      | Highside FET source pin 1                           |
| 25      | PGND1    | Lowside FET source pin 1                            |
| 26      | LG1      | Lowside FET gate drive pin 1                        |
| 27      | Vo1      | Vo1 Output voltage sense pin                        |
| 28      | REG2     | 3.3V Linear regulator output pin                    |
| 29      | REG1     | 5V Linear regulator output pin                      |
| 30      | VIN      | Power supply input pin                              |
| 31      | LG2      | Lowside FET gate drive pin 2                        |
| 32      | PGND2    | Lowside FET source pin 2                            |
| reverse | FIN      | Exposed Pad1, connect to GND                        |

●Reference data

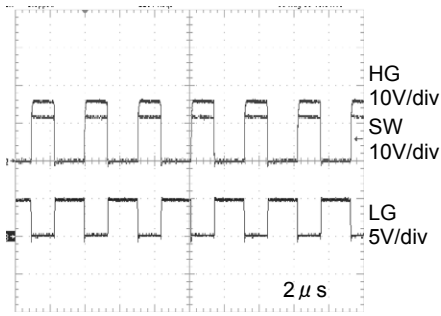


Fig.1 Switching Waveform  
( $V_o=5V$ ,  $I_o=0A$ , PWM)

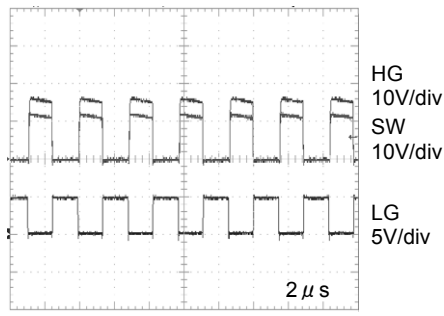


Fig.2 Switching Waveform  
( $V_o=5V$ ,  $I_o=8A$ , PWM)

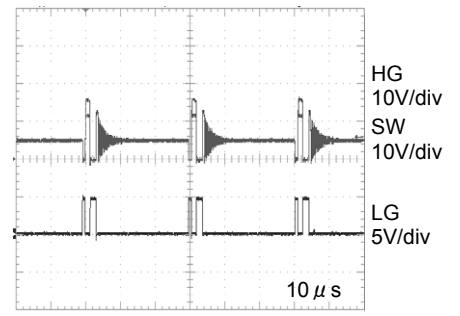


Fig.3 Switching Waveform  
( $V_o=5V$ ,  $I_o=0A$ , QLLM)

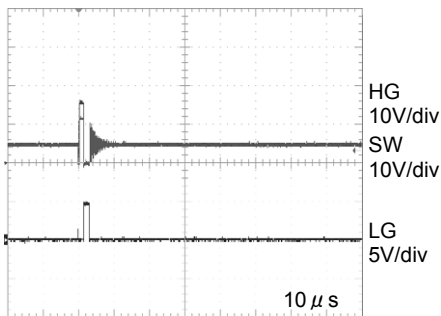


Fig.4 Switching Waveform  
( $V_o=5V$ ,  $I_o=0A$ , SLLM)

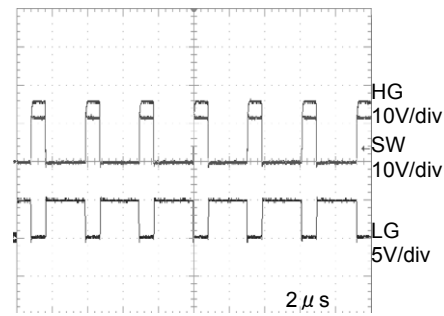


Fig.5 Switching Waveform  
( $V_o=3.3V$ ,  $I_o=0A$ , PWM)

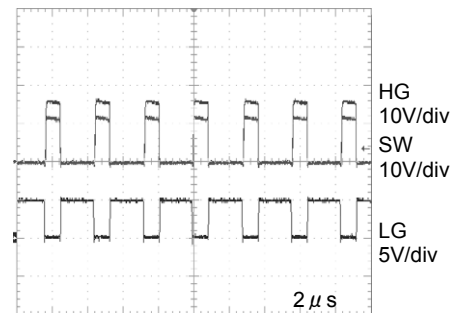


Fig.6 Switching Waveform  
( $V_o=3.3V$ ,  $I_o=8A$ , PWM)

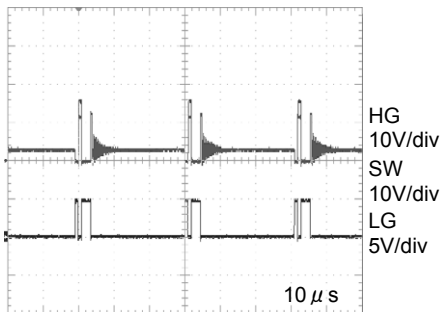


Fig.7 Switching Waveform  
( $V_o=3.3V$ ,  $I_o=0A$ , QLLM)

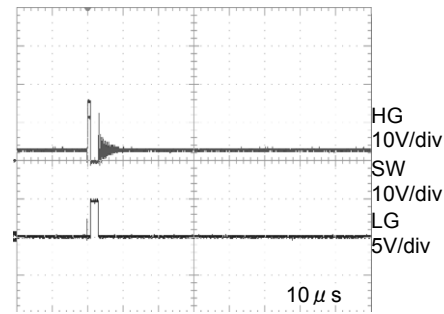


Fig.8 Switching Waveform  
( $V_o=3.3V$ ,  $I_o=0A$ , SLLM)

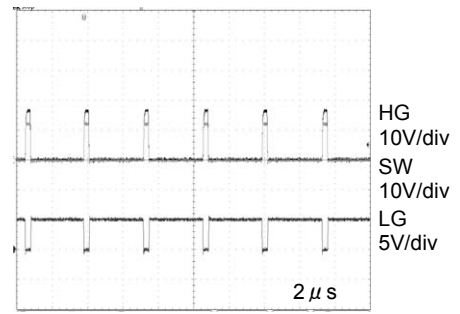


Fig.9 Switching Waveform  
( $V_o=1V$ ,  $I_o=0A$ , PWM)

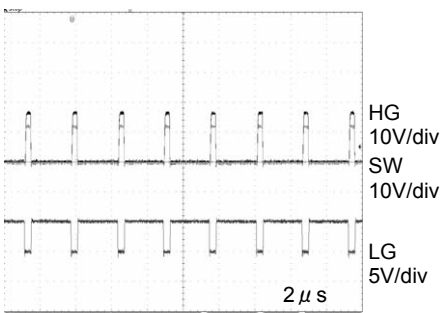


Fig.10 Switching Waveform  
( $V_o=1V$ ,  $I_o=8A$ , PWM)

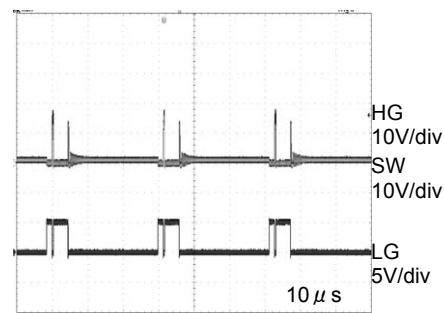


Fig.11 Switching Waveform  
( $V_o=1V$ ,  $I_o=0A$ , QLLM)

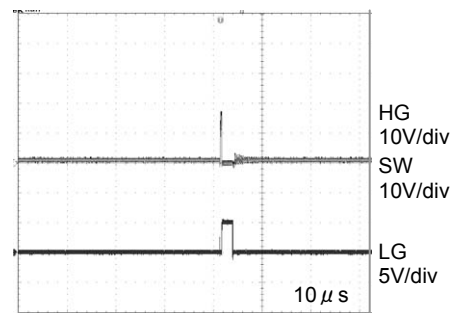


Fig.12 Switching Waveform  
( $V_o=1V$ ,  $I_o=0A$ , SLLM)

●Reference data

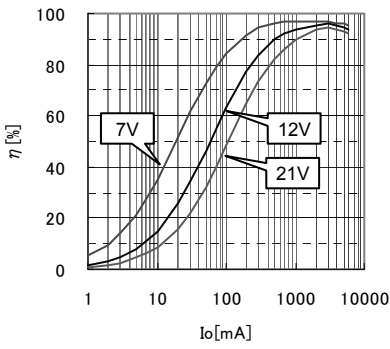


Fig.13 Efficiency (Vo=5V, PWM)

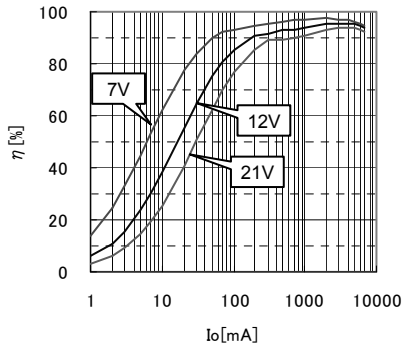


Fig.14 Efficiency (Vo=5V, QLLM)

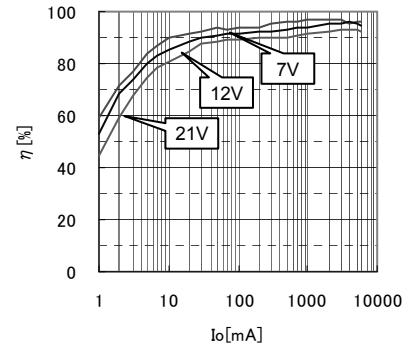


Fig.15 Efficiency (Vo=5V, SLLM)

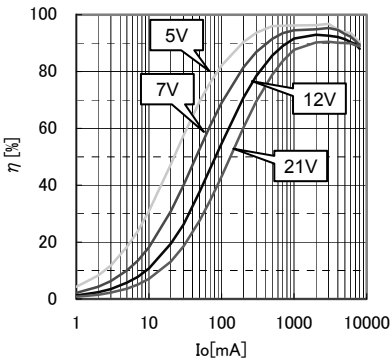


Fig.16 Efficiency (Vo=3.3V, PWM)

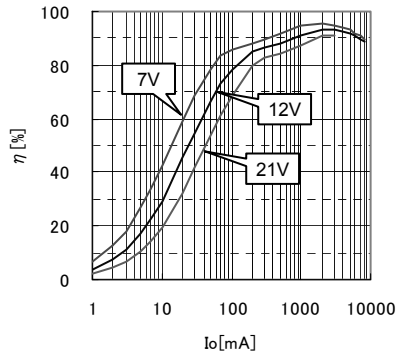


Fig.17 Efficiency (Vo=3.3V, QLLM)

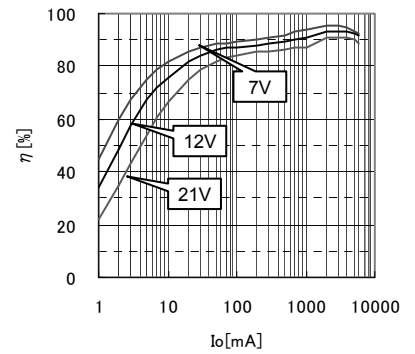


Fig.18 Efficiency (Vo=3.3V, SLLM)

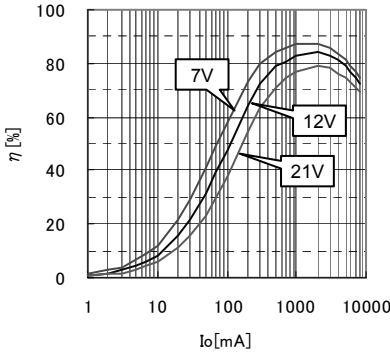


Fig.19 Efficiency (Vo=1V, PWM)

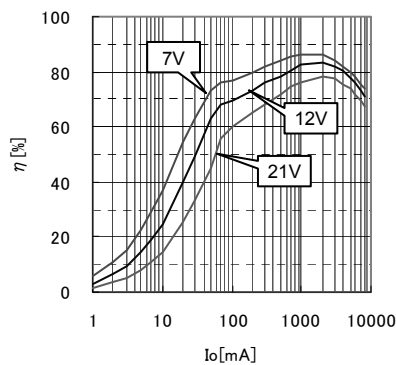


Fig.20 Efficiency (Vo=1V, QLLM)

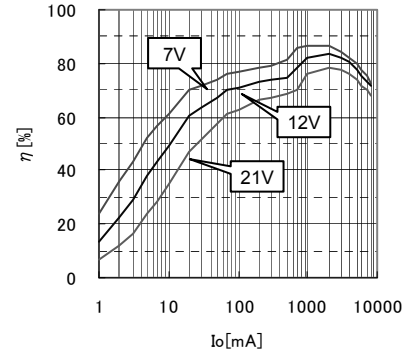


Fig.21 Efficiency (Vo=1V, SLLM)

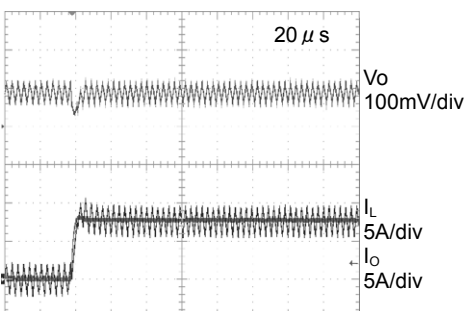


Fig.22 Transient Response (Vo=5V, PWM,  $I_o=0 \rightarrow 8A$ )

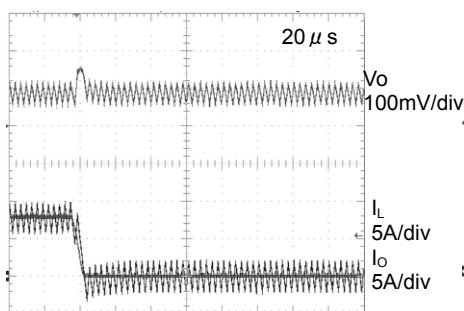


Fig.23 Transient Response (Vo=5V, PWM,  $I_o=8 \rightarrow 0A$ )

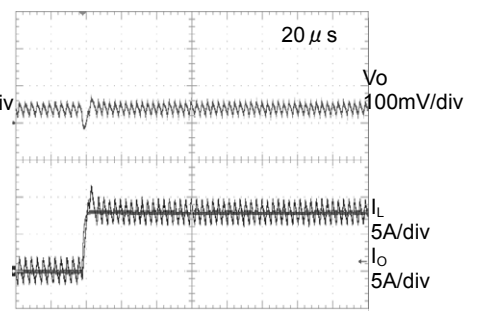


Fig.24 Transient Response (Vo=3.3V, PWM,  $I_o=0 \rightarrow 8A$ )



●Reference data

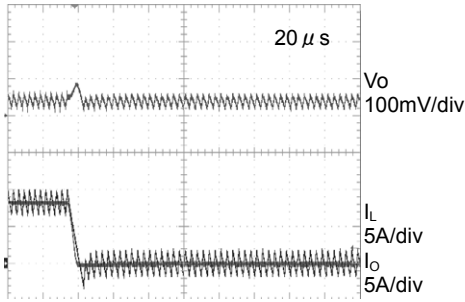


Fig.25 Transient Response  
(Vo=3.3V, PWM, Io=8→0A)

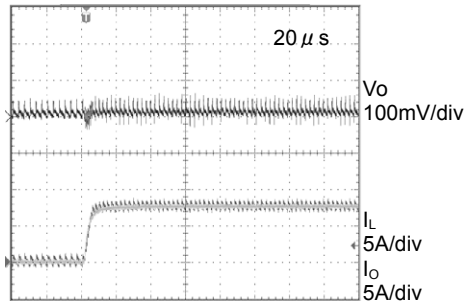


Fig.26 Transient Response  
(Vo=1V, PWM, Io=0→8A)

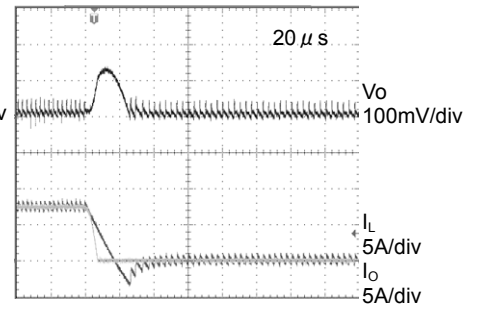


Fig.27 Transient Response  
(Vo=1V, PWM, Io=8→0A)

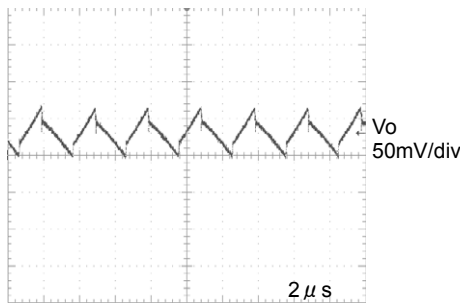


Fig.28 Output Voltage  
(Vo=5V, PWM, Io=0A)

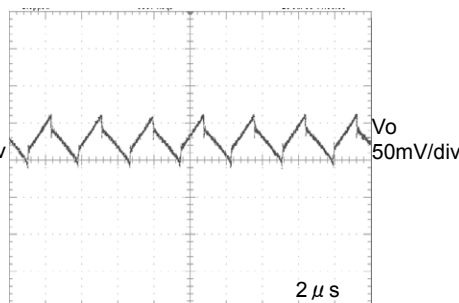


Fig.29 Output Voltage  
(Vo=5V, PWM, Io=8A)

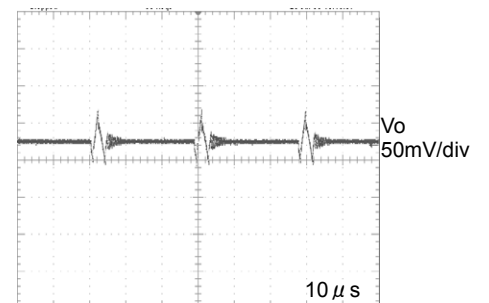


Fig.30 Output Voltage  
(Vo=5V, QLLM, Io=0A)

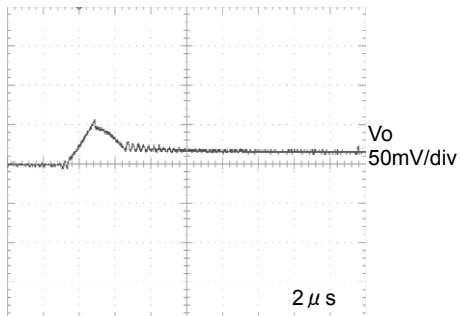


Fig.31 Output Voltage  
(Vo=5V, SLLM, Io=0A)

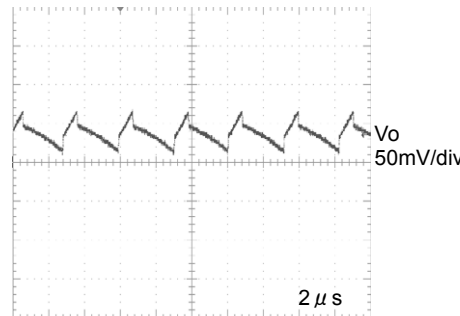


Fig.32 Output Voltage  
(Vo=3.3V, PWM, Io=0A)

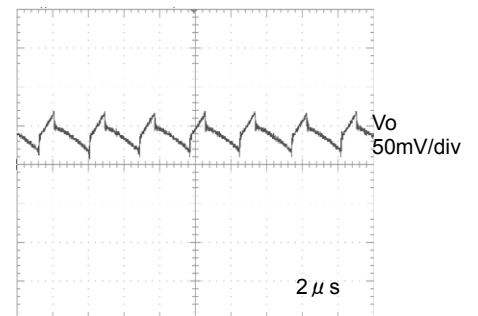


Fig.33 Output Voltage  
(Vo=3.3V, PWM, Io=8A)

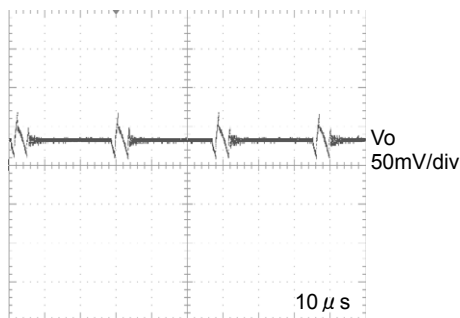


Fig.34 Output Voltage  
(Vo=3.3V, QLLM, Io=0A)

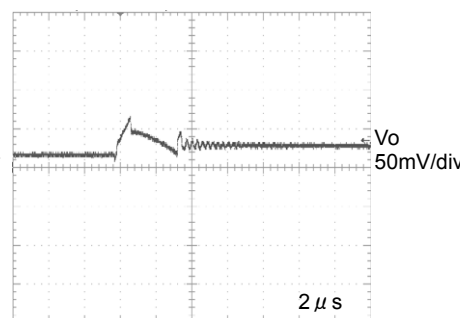


Fig.35 Output Voltage  
(Vo=3.3V, SLLM, Io=0A)

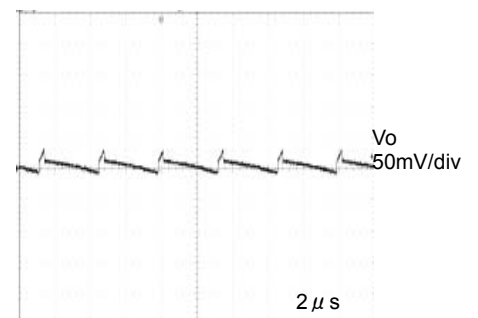


Fig.36 Output Voltage  
(Vo=1V, PWM, Io=0A)

●Reference data

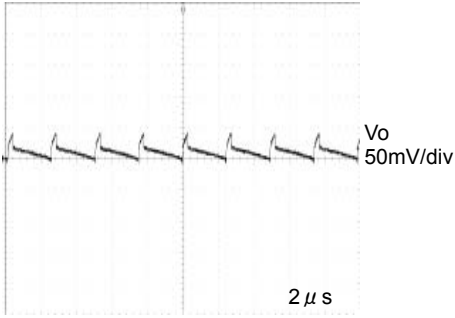


Fig.37 Output Voltage (Vo=1V, PWM, Io=8A)

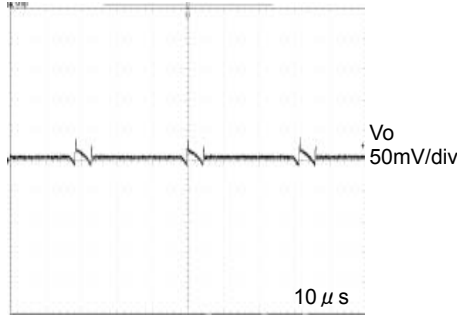


Fig.38 Output Voltage (Vo=1V, QLLM, Io=0A)

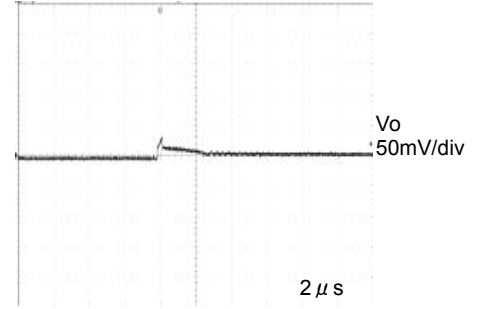


Fig.39 Output Voltage (Vo=1V, SLLM, Io=0A)

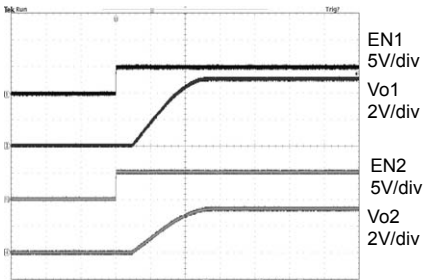


Fig.40 Wake up waveform (EN1=EN2)

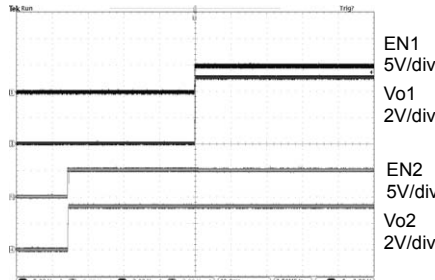


Fig.41 Wake up waveform (EN2→EN1)

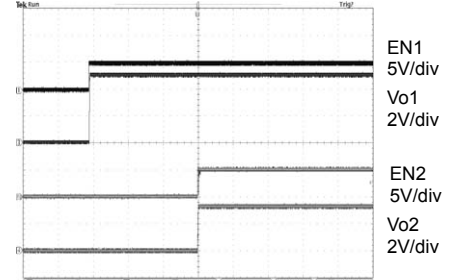


Fig.42 Wake up waveform (EN1→EN2)

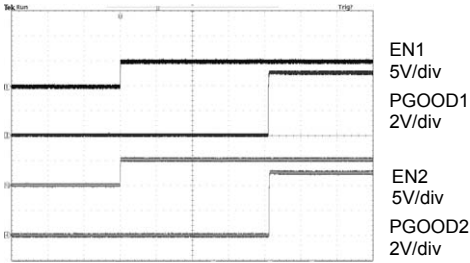


Fig.43 Wake up waveform (EN1/2→PGOOD1/2)

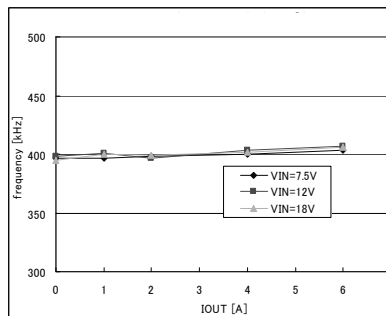


Fig.44 Io-frequency (Vo=5V, PWM, RFS=68kΩ)

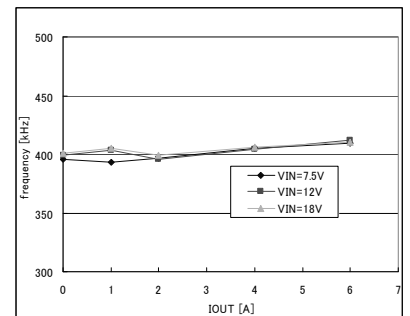


Fig.45 Io-frequency (Vo=3.3V, PWM, RFS=68kΩ)

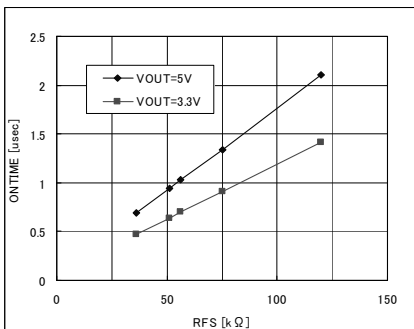


Fig.46 FS-ONTIME

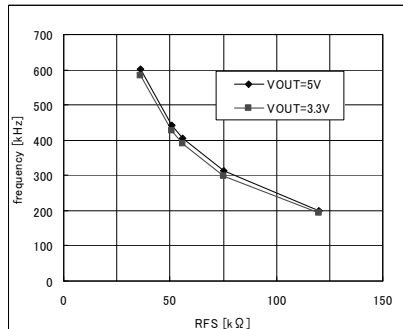


Fig.47 FS-frequency

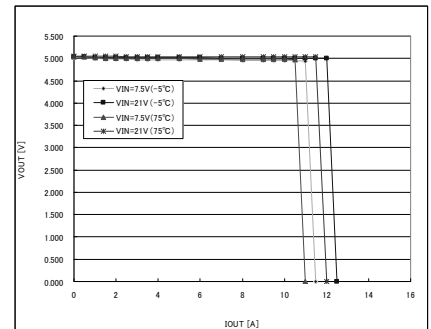


Fig.48 Ta-IocP (Vo=5V)

●Reference data

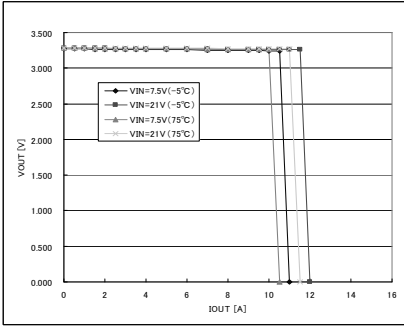


Fig.49 Ta-Iocp  
(Vo=3.3V)

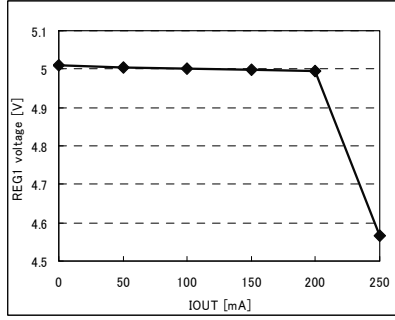


Fig.50 IREG1-REG1

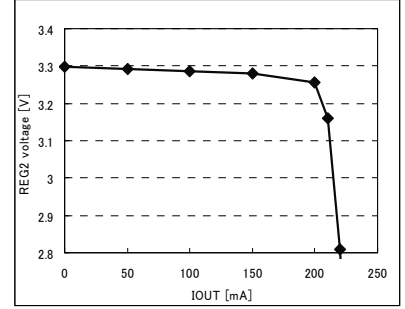


Fig.51 IREG2-REG2

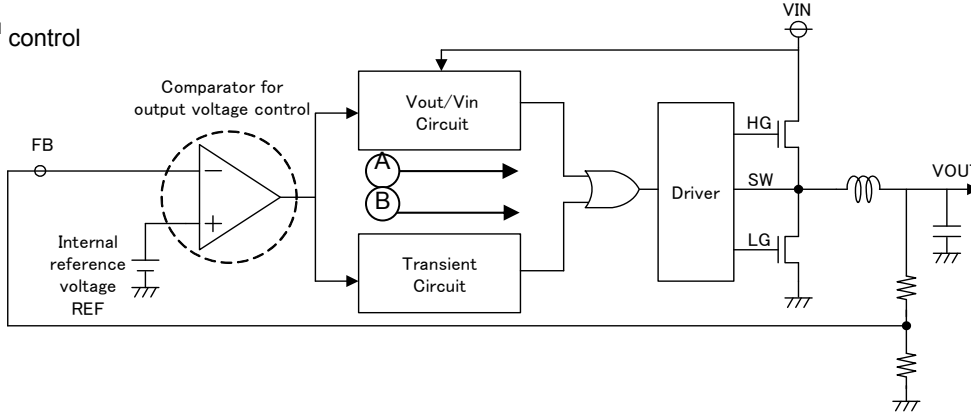
## ●Pin Descriptions

- VIN (30 pin)  
This is the main power supply pin. The input supply voltage range is 5.5V to 28V. The duty cycle of BD9528AMUV is determined by input voltage and control output voltage. Therefore, when VIN voltage fluctuated, the output voltage also becomes unstable. Since VIN line is also the input voltage of switching regulator, stability depends on the impedance of the voltage supply. It is recommended to establish bypass capacitor and CR filter suitable for the actual application.
- CTL (9 pin)  
When CTL pin voltage is at least 2.3V, the status of the linear regulator output becomes active (REG1=5V, REG2=3.3V). Conversely, the status switches off when CTL pin voltage goes lower than 0.8V. The switching regulator doesn't become active when the status of CTL pin is low, if the status of EN pin is high.  
(※CTL pin is connected to VIN pin with 1MΩ resistor(pull up) intermall IC)
- EN1, 2 (21 pin, 4 pin)  
When EN pin voltage is at least 2.3V, the status of the switching regulator becomes active. Conversely, the status switches off when EN pin voltage goes lower than 0.8V.  
(※EN pin is connected to AGND pin with 1MΩ resistor(pull down) intermall IC)
- REG1 (29 pin)  
This is the output pin for 5V linear regulator and also active in power supply for driver and control circuit of the inside. The standby function for REG1 is determined by CTL pin. The voltage is 5V, with 100mA current ability. It is recommended that a 10μF capacitor (X5R or X7R) be established between REG1 and GND.
- REG2 (28 pin)  
This is the output pin for 3.3V linear regulator. The standby function for REG2 is determined by CTL. The voltage is 3.3V, with 100mA current ability. It is recommended that a 10μF capacitor (X5R or X7R) be established between REG2 and GND.
- REF (12 pin)  
This is the setting pin for output voltage of switching regulator. This IC controls the voltage in the status of REF≒FB.
- FB 1, 2 (14 pin, 11 pin)  
This is the feedback pin from the output of switching regulator. This IC controls the voltage in the status of REF≒FB.
- Vo1 (27 pin)  
This is the output discharge pin, and output voltage feedback pin for frequency setting. When the voltage is beyond 4.4V from the external power supply during operation, it supplies REG1.
- Vo2 (7 pin)  
This is the output discharge pin, and output voltage feedback pin for frequency setting.
- SS1, 2 (19 pin, 6 pin)  
This is the setting pin for soft start. The rising time is determined by the capacitor connected between SS and GND, and the fixed current inside IC after it is the status of low in standby mode. It controls the output voltage till SS voltage catch up the REF pin to become the SS terminal voltage.
- FS1, 2 (15 pin, 10 pin)  
This is the input pin for setting the frequency. It is available to set it in frequency range is 150kHz to 500kHz.
- ILIM1, 2 (17 pin, 8 pin)  
BD9528AMUV detects voltage differential between SW and PGND, and set OCP. OCP setting current value is determined by the resistance value of ILIM pin. FET of various Ron is available.
- PGOOD 1, 2 (20 pin, 5 pin)  
This is the open drain pin for deciding the output of switching regulator.
- MCTL1, 2 (18 pin, 16 pin)  
This is the switching shift pin for SLLM (Simple Light Load Mode). MCTL pin is at low level when it goes lower than 0.8V, and at high level when it goes higher than 2.3V.  
(※MCTL pin is connected to AGND pin with 500kΩ resistor(pull down) intermall IC)
- AGND (13 pin)  
This is the ground pin.
- BOOT1, 2 (22 pin, 3 pin)  
This is the power supply pin for high side FET driver. The maximum voltage range to GND pin is to 35V, to SW pin is to 7V. In switching operations, the voltage swings from (VIN+REG1) to REG1 by BOOT pin operation.
- HG1, 2 (23 pin, 2 pin)  
This is the highside FET gate drive pin. It is operated in switching between BOOT to SW. In case the output MOS is 3ohm /the status of Hi, 2ohm/the status of Low, it is operated hi-side FET gate in high speed.
- SW1, 2 (24 pin, 1 pin)  
This is the ground pin for high side FET drive. The maximum voltage range to GND pin is to 30V. Switching operation swings from the status of BOOT to the status of GND.
- LG1, 2 (26 pin, 31 pin)  
This is the lowside FET gate drive pin. It is operated in switching between REG1 to PGND. In case the output MOS is 2ohm /the status of Hi, 0.5ohm/the status of Low, it is operated low-side FET gate in high speed.
- PGND1, 2 (25 pin, 32 pin)  
This is the ground pin for low side FET drive.

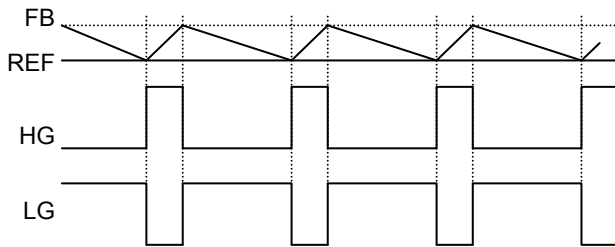
●Explanation of Operation

The BD9528AMUV is a 2ch synchronous buck regulator controller incorporating ROHM's proprietary H<sup>3</sup>REG CONTROLLA control system. Because controlling of output voltage by a comparator, high response is realized with not relying on the switching frequency. And, when VOUT drops due to a rapid load change, the system quickly restores VOUT by extending the TON time interval. Thus, it serves to improve the regulator's transient response. Activating the Light Load Mode will also exercise Simple Light Load Mode (SLLM) control when the load is light, to further increase efficiency.

H<sup>3</sup>Reg™ control



(Normal operation)

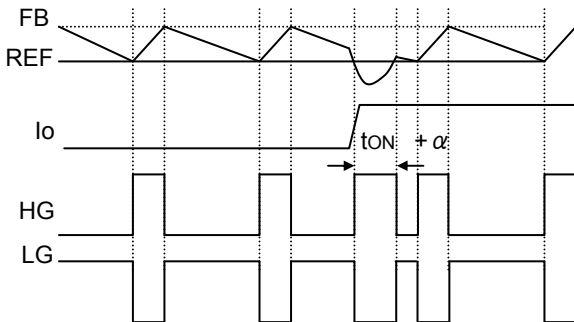


When FB falls to a reference voltage (REF), the drop is detected, activating the H<sup>3</sup>REG CONTROLLA system.<Route A>

$$t_{ON} = \frac{V_{OUT}}{V_{IN}} \times \frac{1}{f} \text{ [sec]} \dots (1)$$

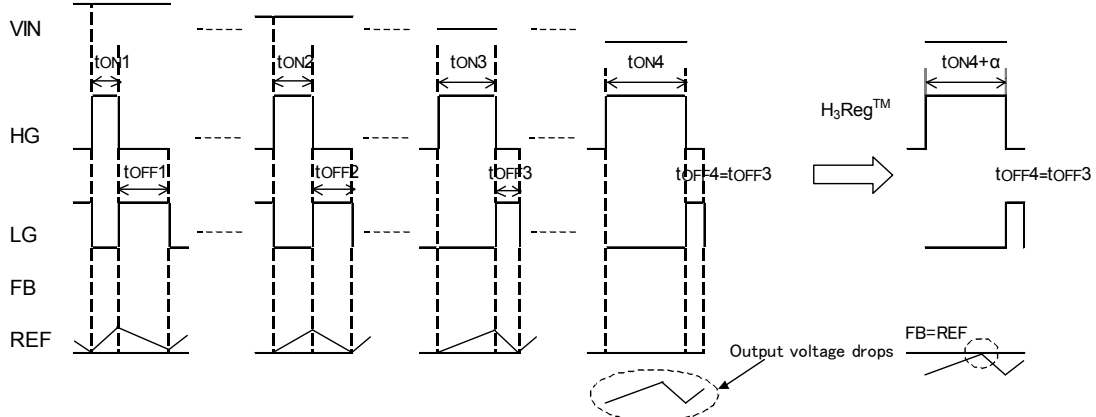
HG output is determined by the formula above. After the status of HG is OFF, LG go on outputting until output voltage become FB=REF.

(VOUT drops due to a rapid load change)



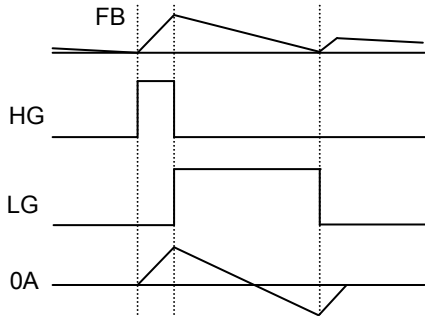
When VOUT drops due to a rapid load change, and the voltage remains below reference voltage after the programmed tON time interval has elapsed (Output of a comparator for output voltage control =H), the system quickly restores VOUT by extending the tON time, improving the transient response.<Route B> After VOUT restores (FB=REF), HG turns to be OFF, and it goes back to a normal operation.

(when VIN drops)



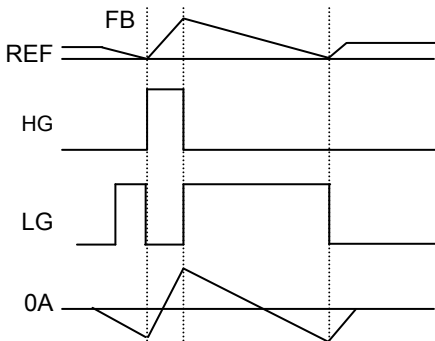
If VIN voltage drops because of the battery voltage fall, ontime tON and offtime tOFF is determined by the following formula: tON=VOUT/VIN × 1/f and tOFF=(VIN-VOUT)/VIN × f so that tON lengthen and tOFF shorten to keep output voltage constant. However, if VIN still drops and tOFF equals to tminoff (tminoff:Minimum OFF time, regulated inside IC) , because tOFF cannot shorten any more, as a result output voltage drops. In H3Reg™ system, lengthening tON time than regulated tON (lengthen tON time until FB > REF) enables to operate stable not to drop the output voltage even if VIN turns to be low. With the reason above, it is suitable for 2-cell battery.

Light Load Control (SLLM)



In SLLM, when the status of LG is OFF and the coil current is within 0A (it flows to SW from VOUT.), SLLM function is operated to prevent output next HG. The status of HG is ON, when FB falls below reference voltage again.

(QLLM)



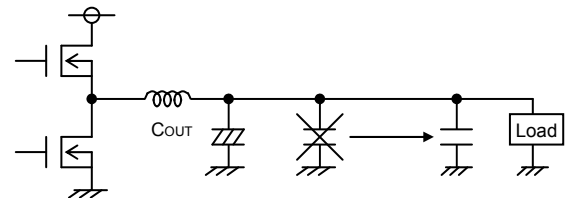
In QLLM, when the status of LG is OFF and the coil current is within 0A (it flows to SW from VOUT.), QLLM function is operated to prevent output next HG.

Then, FB falls below the output programmed voltage within the programmed time (typ=40µs), the status of HG is ON. In case FB doesn't fall in the programmed time, the status of LG is ON forcedly and VOUT falls. As a result, the status of next HG is ON.

| MCTL1 | MCTL2 | Control mode | Running |
|-------|-------|--------------|---------|
| L     | L     | SLLM         | PWM     |
| L     | H     | QLLM         | PWM     |
| H     | X     | PWM          | PWM     |

The BD9528AMUV operates in PWM mode until SS pin reaches clamp voltage (2.5V), regardless of the control mode setting, in order to operate stable during the operation.

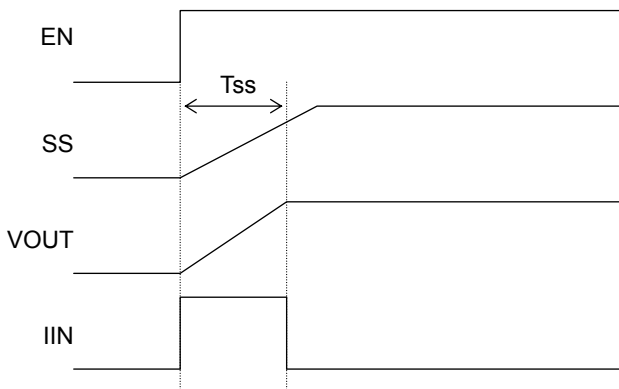
\*Attention: H<sup>3</sup>Reg™CONTROLLA monitors the supplying current from capacitor to load, using the ESR of output capacitor, and realize the rapid response. Bypass capacitor used at each load (Ex. Ceramic capacitor) exercises the effect with connecting to each load side. Do not put a ceramic capacitor on COUT side of power supply.



Soft start is exercised with the EN pin set high. Current control takes effect at startup, enabling a moderate output voltage "ramping start." Soft start timing and incoming current are calculated with formulas (2) and (3) below.

●Timing Chart

- Soft Start Function



Soft start time

$$T_{SS} = \frac{REF \times C_{SS}}{2.3 \mu A (typ)} \text{ [sec]} \dots (2)$$

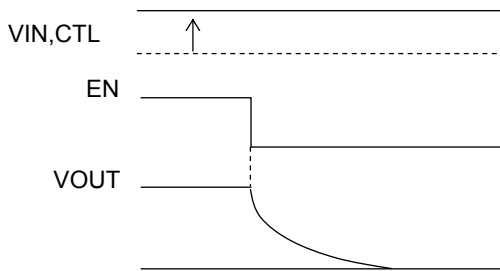
Incoming current

$$I_{IN} = \frac{C_o \times V_{OUT}}{T_{SS}} \text{ [A]} \dots (3)$$

(C<sub>SS</sub>: Soft start capacitor; C<sub>o</sub>: Output capacitor)



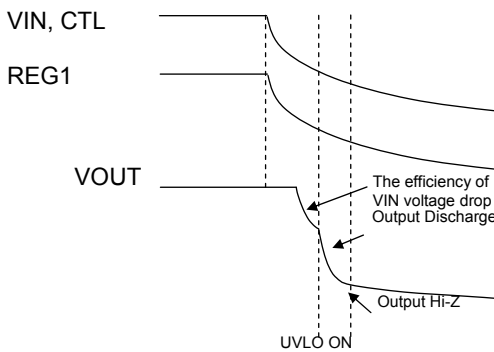
### ●Output Discharge



It will be available to use if connecting VOUT pin to DC/DC output. (Total about  $100\Omega$ ). Discharge function operates when ①EN='L' ②UVLO=ON (if input voltage is low) ③SCP Latch time ④TSD=ON. The function at output discharge time is shown as left.

(1) during EN='H' → 'L'

If EN pin voltage is below than EN threshold voltage, output discharge function is operated, and discharge output capacitor charge.

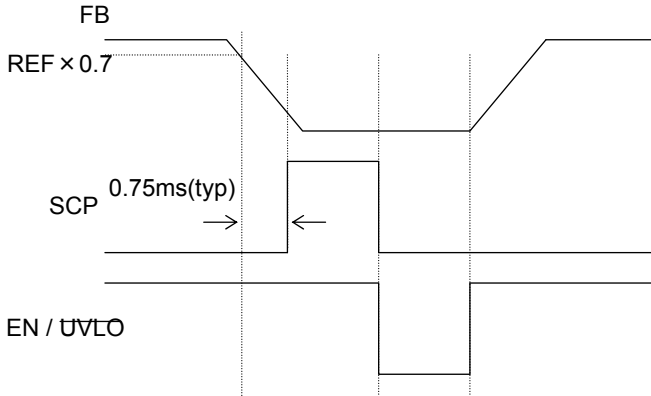


(2) during VIN=CTL=H → 0V

- ① IC is in normal operation until REG1 voltage becomes lower than UVLO voltage. However, because VIN voltage also becomes low, output voltage will drop, too.
- ② If REG1 voltage reaches the UVLO voltage, output discharge function is operated, and discharge output capacitor charge.
- ③ In addition, if REG1 voltage drops, inner IC logic cannot operate, so that output discharge function does not work, and becomes output Hi-z. (In case, FB has resistor against GND, discharge at the resistor.)

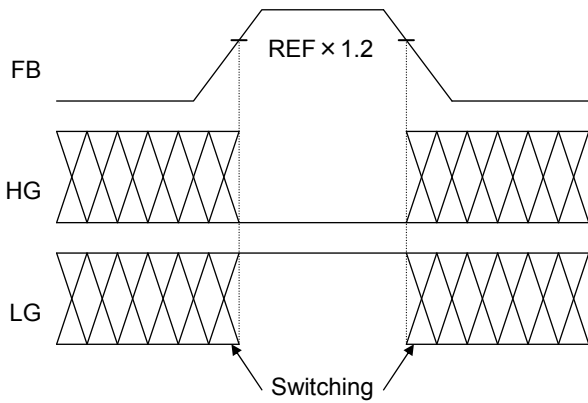


• Timer Latch Type Short Circuit Protection



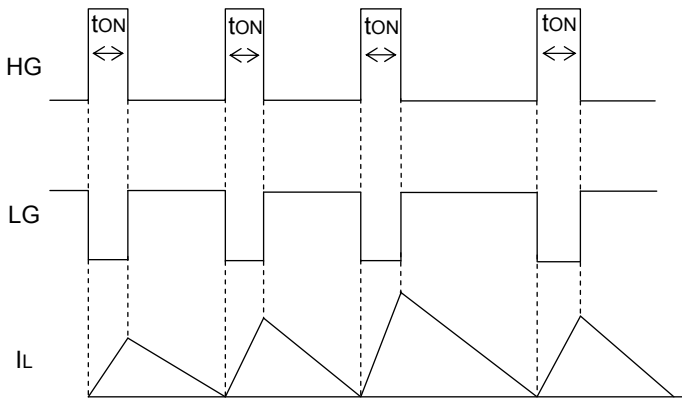
Short protection kicks in when output falls to or below REF X 0.7. When the programmed time period elapses, output is latched OFF to prevent destruction of the IC. (HG=Low, LG=Low) Output voltage can be restored either by reconnecting the EN pin or disabling UVLO.

• Over Voltage Protection



When output rise to or above REF × 1.2 (typ), output over voltage protection is exercised, and low side FET goes up maximum for reducing output.(LG=High, HG=Low).When output falls, output voltage can be restored., and go back to the normal operation.

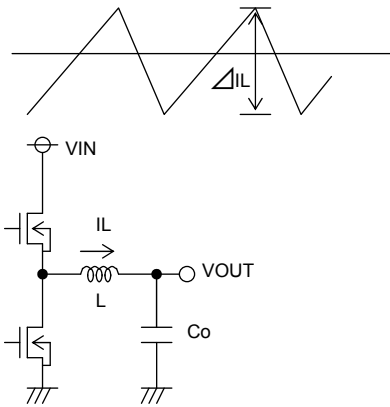
• Over current protection circuit



During the normal operation, when FB becomes less than REF, HG becomes High during the time tON, and after HG becomes OFF, it output LG. However, when inductor current exceeds I<sub>LIMIT</sub> threshold, next HG pulse doesn't pulsate until it is lower than I<sub>LIMIT</sub> level.

●External Component Selection

1. Inductor (L) selection



Output ripple current

※Passing a current larger than the inductor’s rated current will cause magnetic saturation in the inductor and decrease system efficiency. In selecting the inductor, be sure to allow enough margin to assure that peak current does not exceed the inductor rated current value.

※To minimize possible inductor damage and maximize efficiency, choose a inductor with a low (DCR, ACR) resistance.

The inductor value is a major influence on the output ripple current. As formula (4) below indicates, the greater the inductor or the switching frequency, the lower the ripple current.

$$\Delta I_L = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{L \times V_{IN} \times f} \text{ [A]} \dots (4)$$

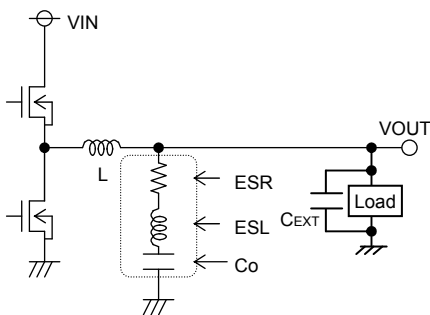
The proper output ripple current setting is about 30% of maximum output current.

$$\Delta I_L = 0.3 \times I_{OUTmax} \text{ [A]} \dots (5)$$

$$L = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{\Delta I_L \times V_{IN} \times f} \text{ [H]} \dots (6)$$

( $\Delta I_L$ : output ripple current; f: switch frequency)

2. Output Capacitor (Co) Selection



Output Capacitor

When determining the proper output capacitor, be sure to factor in the equivalent series resistance required to smooth out ripple volume and maintain a stable output voltage range.

Output ripple voltage is determined as in formula (7) below.

$$\Delta V_{OUT} = \Delta I_L \times ESR + ESL \times \Delta I_L / T_{ON} \dots (7)$$

( $\Delta I_L$ : Output ripple current, ESR: Co equivalent series resistance, ESL: Co equivalent series inductance)

※In selecting a capacitor, make sure the capacitor rating allows sufficient margin relative to output voltage. Note that a lower ESR can minimize output ripple voltage.

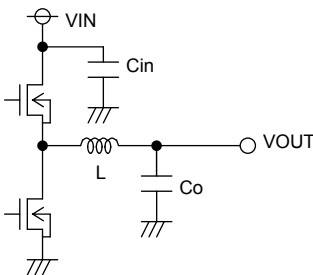
Please give due consideration to the conditions in formula (8) below for output capacity, bear in mind that output rise time must be established within the soft start time frame. Capacitor for bypass capacitor is connected to Load side which connect to output in output capacitor capacity (C<sub>EXT</sub>, figure above). Please set the soft start time or over current detecting value, regarding these capacities.

$$C_o + C_{EXT} \leq \frac{T_{SS} \times (\text{Limit} - I_{OUT})}{V_{OUT}} \dots (8)$$

T<sub>SS</sub>: Soft start time  
Limit: Over current detection

Note: Improper capacitor may cause startup malfunctions.

3. Input Capacitor (Cin) Selection



Input Capacitor

The input capacitor selected must have low enough ESR resistance to fully support large ripple output, in order to prevent extreme over current. The formula for ripple current IRMS is given in (9) below.

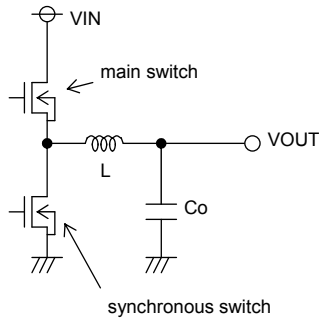
$$I_{RMS} = I_{OUT} \times \frac{\sqrt{V_{IN} (V_{IN} - V_{OUT})}}{V_{IN}} \text{ [A]} \dots (9)$$

$$\text{Where } V_{IN} = 2 \times V_{OUT}, I_{RMS} = \frac{I_{OUT}}{2}$$

A low ESR capacitor is recommended to reduce ESR loss and maximize efficiency.

4. MOSFET Selection

MOSFET may cause the loss as below, so please select proper FET for each.



<Loss on the main MOSFET >

$$P_{main} = P_{RON} + P_{GATE} + P_{TRAN}$$

$$= \frac{V_{OUT}}{V_{IN}} \times R_{ON} \times I_{OUT}^2 + C_{iss} \times f \times V_{DD} + \frac{V_{IN}^2 \times C_{rss} \times I_{OUT} \times f}{I_{DRIVE}} \dots (10)$$

(RON: On-resistance of FET; Ciss: FET gate capacitance;  
f: Switching frequency Crss: FET inverse transfer function;  
IDRIVE: Gate peak current)

<Loss on the synchronous MOSFET >

$$P_{syn} = P_{RON} + P_{GATE}$$

$$= \frac{V_{IN} - V_{OUT}}{V_{IN}} \times R_{ON} \times I_{OUT}^2 + C_{iss} \times f \times V_{DD} \dots (11)$$

5. Setting output voltage

This IC is operated that output voltage is REF ≒ FB.  
And it is operated that output voltage is feed back to FB pin.

<Output Voltage >

$$V_{OUT} = \frac{(R1+R2)}{R2} \times REF(0.7V) + \frac{1}{2} \Delta V_{OUT} \quad (\Delta V_{OUT}: \text{Output ripple voltage})$$

$$\Delta V_{OUT} = \Delta I_L \times ESR \quad (\Delta I_L: \text{ripple current of coil})$$

$$\Delta I_L = (V_{IN} - V_{OUT}) \times \frac{V_{OUT}}{(L \times V_{IN} \times f)} \quad (L: \text{inductance[H] } f: \text{switching frequency[Hz]})$$

※(Notice) Please set ΔFB more than 10mV

Ex. VIN=20V, VOUT=5V, f=300kHz, L=2.5uH, ESR=20mΩ, R1=56kΩ, R2=9.1kΩ

$$\Delta I_L = (20V - 5V) \times 5V / (2.5 \times 10^{-6}H \times 20V \times 300 \times 10^3Hz) = 5[A]$$

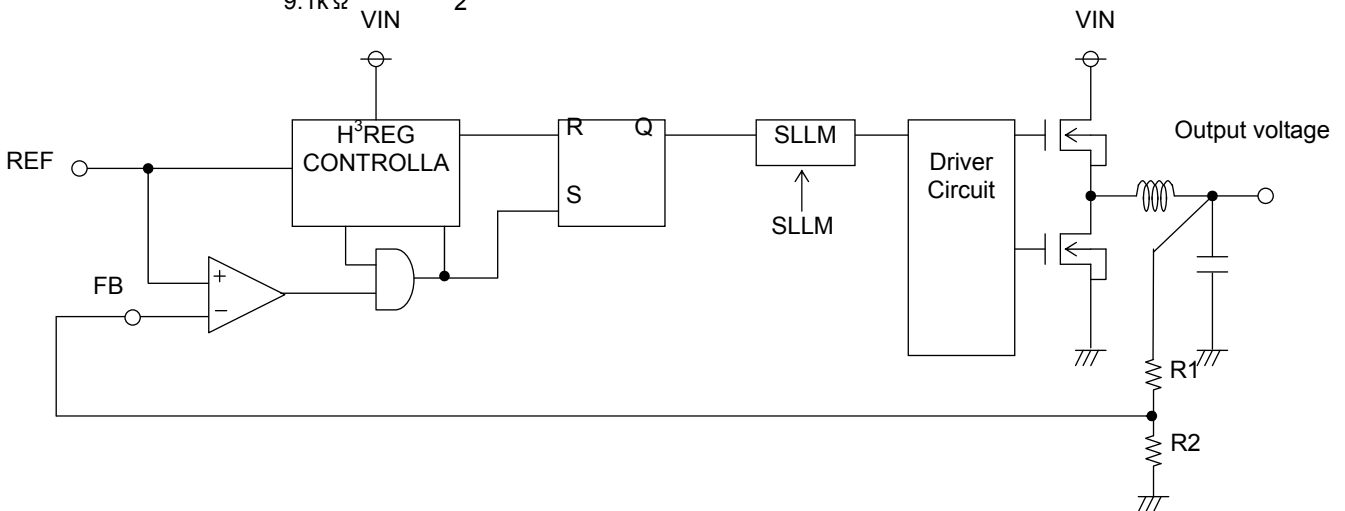
$$\Delta V_{OUT} = 5A \times 20 \times 10^{-3}\Omega = 0.1[V]$$

$$V_{OUT} = 0.7V \times (56k\Omega + 9.1k\Omega) / 9.1k\Omega + 1/2 \times 0.1V = 5.057[V]$$

$$\Delta I_L = (20V - 5V) \times \frac{5V}{(2.5 \times 10^{-6}H \times 20V \times 300 \times 10^3Hz)} = 5(A)$$

$$\Delta V_{OUT} = 5A \times 20 \times 10^{-3}\Omega = 0.1(V)$$

$$V_{OUT} = 0.7V \times \frac{(51k\Omega + 9.1k\Omega)}{9.1k\Omega} + \frac{1}{2} \times 0.1V = 5.057(V)$$





## 8. Relation between output voltage and frequency

Because the BD9528AMUV is Ton time focused regulator controller, if output current is up, switching loss of Coil, MOSFET and output capacitor will increase, and frequency will be fast.

Loss of each Coil, MOSFET and output capacitor are below.

$$\textcircled{1} \text{ Coil loss} = I_{OUT}^2 \times DCR$$

$$\textcircled{2} \text{ MOSFET(High Side) loss} = I_{OUT}^2 \times R_{onh} \times \frac{V_{OUT}}{V_{IN}}$$

$$\textcircled{3} \text{ MOSFET(Low Side) loss} = I_{OUT}^2 \times R_{onL} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

(Ronh : ON resistance of high side MOSFET, RonL : ON resistance of low side MOSFET,  
ESR : Output capacitor equivalent cascade resistance)

Regarding those loss above and frequency formula, it is determined below.

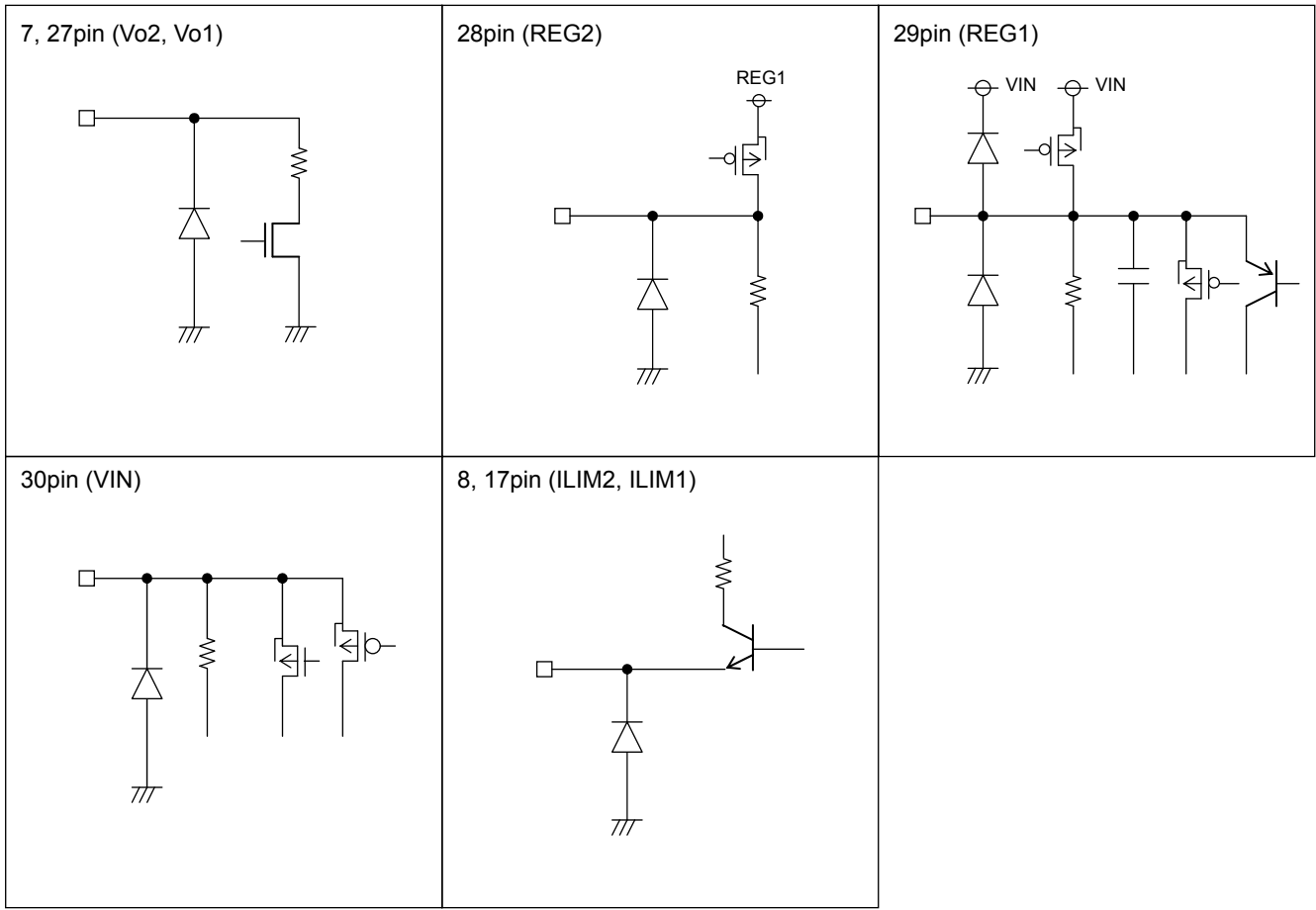
$$T (=1/\text{Freq}) = \frac{V_{IN} \times I_{OUT} \times T_{on}}{V_{OUT} \times I_{OUT} + \textcircled{1} + \textcircled{2} + \textcircled{3}} \dots (17)$$

However, real-life considerations (such as parasitic resistance element of Layout pattern) must be factored in as they affect the loss, please confirm in reality by the instrument.

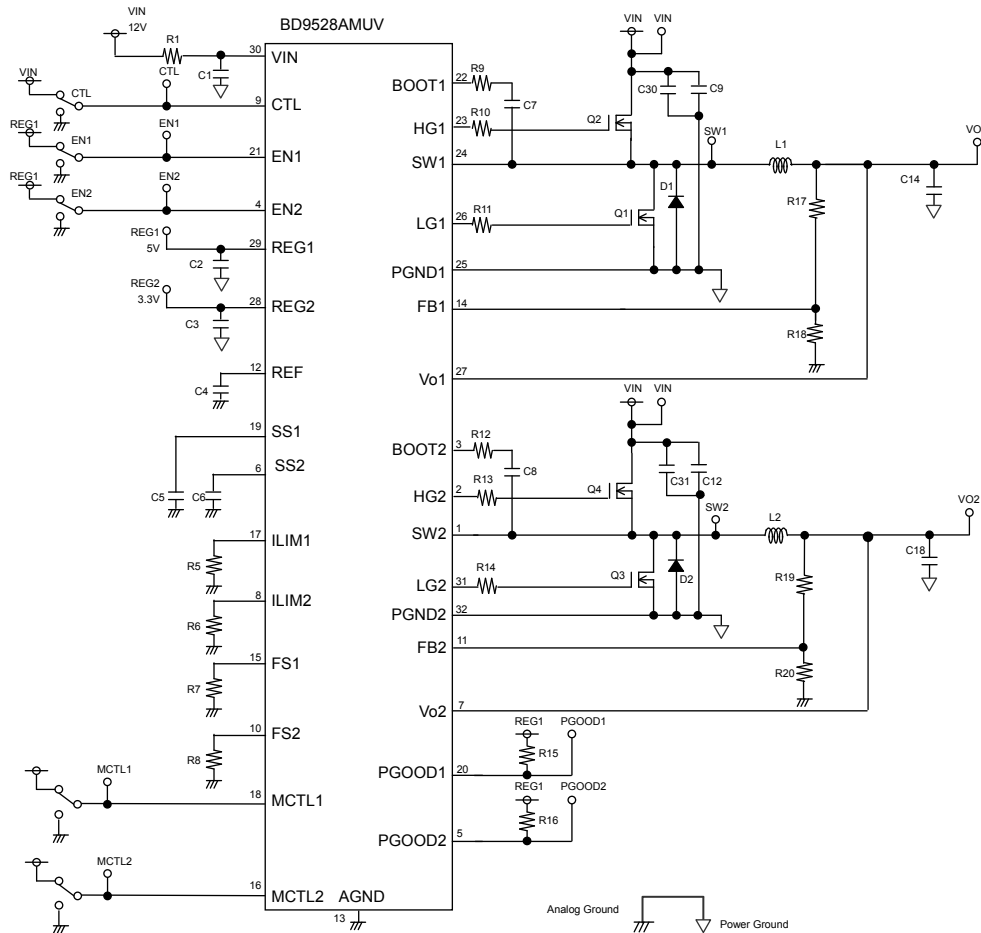
● I/O Equivalent Circuit

|                                  |                                  |                                |
|----------------------------------|----------------------------------|--------------------------------|
| <p>1, 24pin (SW2, SW1)</p>       | <p>2, 23pin (HG2, HG1)</p>       | <p>3, 22pin (BOOT2, BOOT1)</p> |
| <p>4, 21pin (EN2, EN1)</p>       | <p>5, 20pin (PGOOD2, PGOOD1)</p> | <p>6, 19pin (SS2, SS1)</p>     |
| <p>12pin (REF)</p>               | <p>11, 14pin (FB2, FB1)</p>      | <p>10, 15pin (FS2, FS1)</p>    |
| <p>16, 18pin (MCTL2, MCTL 1)</p> | <p>9pin (CTL)</p>                | <p>26, 31pin (LG1, LG2)</p>    |

● I/O Equivalent Circuit



●Evaluation Board Circuit (Vo1=5V/8A, f1=300kHz Vo2=3.3V/8A f2=300kHz)



| DESIGNATION | RATING     | PART No.          | COMPANY |
|-------------|------------|-------------------|---------|
| R1          | 0Ω         | -                 | -       |
| R5          | 68kΩ       | MCR03             | ROHM    |
| R6          | 68kΩ       | MCR03             | ROHM    |
| R7          | 75kΩ       | MCR03             | ROHM    |
| R8          | 75kΩ       | MCR03             | ROHM    |
| R9          | 0Ω         | -                 | -       |
| R10         | 0Ω         | -                 | -       |
| R11         | 0Ω         | -                 | -       |
| R12         | 0Ω         | -                 | -       |
| R13         | 0Ω         | -                 | -       |
| R14         | 0Ω         | -                 | -       |
| R15         | 100kΩ      | MCR03             | ROHM    |
| R16         | 100kΩ      | MCR03             | ROHM    |
| R17         | 56kΩ       | MCR03             | ROHM    |
| R18         | 9.1kΩ      | MCR03             | ROHM    |
| R19         | 30kΩ       | MCR03             | ROHM    |
| R20         | 8.2kΩ      | MCR03             | ROHM    |
| C1          | 10uF(25V)  | GRM31CB31E106KA75 | MURATA  |
| C2          | 10uF(10V)  | GRM21BB10J106KD   | MURATA  |
| C3          | 10uF(6.3V) | GRM21BB10J106KD   | MURATA  |

| DESIGNATION | RATING      | PART No.          | COMPANY |
|-------------|-------------|-------------------|---------|
| C4          | 0.1uF(6.3V) | GRM21BB10J104KD   | MURATA  |
| C5          | 2200pF      | GRM188B11H102KD   | MURATA  |
| C6          | 2200pF      | GRM188B11H102KD   | MURATA  |
| C7          | 0.47uF      | GRM188B11A474KD   | MURATA  |
| C8          | 0.47uF      | GRM188B11A474KD   | MURATA  |
| C9          | 10uF(25V)   | GRM31CB31E106KA75 | MURATA  |
| C12         | 10uF(25V)   | GRM31CB31E106KA75 | MURATA  |
| C14         | 330uF       | 6TPE330MI         | SANYO   |
| C18         | 330uF       | 6TPE330MI         | SANYO   |
| C30         | 1000pF      | GRM1882C1H102JA01 | MURATA  |
| C31         | 1000pF      | GRM1882C1H102JA01 | MURATA  |
| (D1)        | (Diode)     | (RSX501L-20)      | (ROHM)  |
| (D2)        | (Diode)     | (RSX501L-20)      | (ROHM)  |
| L1          | 2.2uH       | FDVE1040-2R2M     | TOKO    |
| L2          | 2.2uH       | FDVE1040-2R2M     | TOKO    |
| Q1          | FET         | RMW130N03         | ROHM    |
| Q2          | FET         | RMW130N03         | ROHM    |
| Q3          | FET         | RMW130N03         | ROHM    |
| Q4          | FET         | RMW130N03         | ROHM    |
| U1          | -           | BD9528AMUV        | ROHM    |

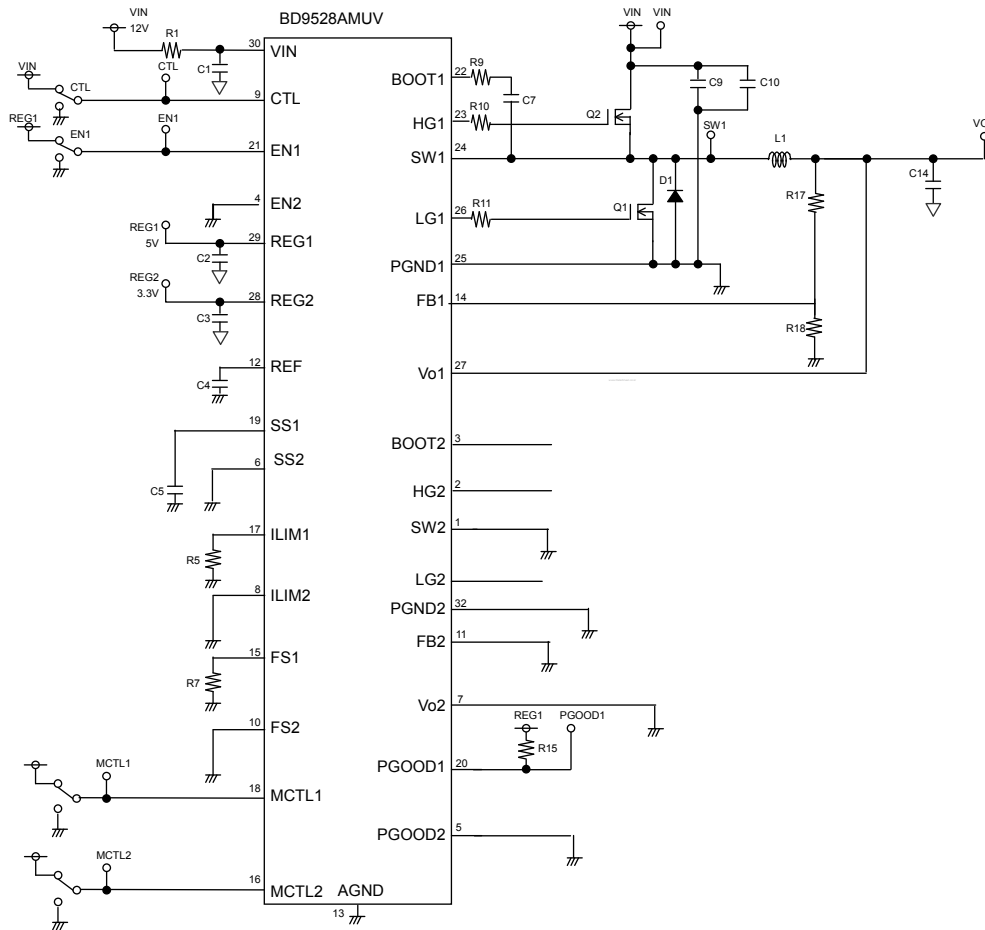
note) Without any value of ripple(about 10mV), there is a possibility of FB signal not acting stable switching due to the adoption of comparator control method. Please use in condition with enough ripple voltage either by ①reducing the L-value of coil, or ②using big output capacitor of ESR. Ripple voltage can be generated in FB terminal by adding capacitor in parallel to resistor (R17, R19) of FB terminal, but because it becomes delicate to noise from output (Vo1/Vo2) line it is not recommended. Also condition of stable action gets effected by layout of board, etc., so please give full attention.



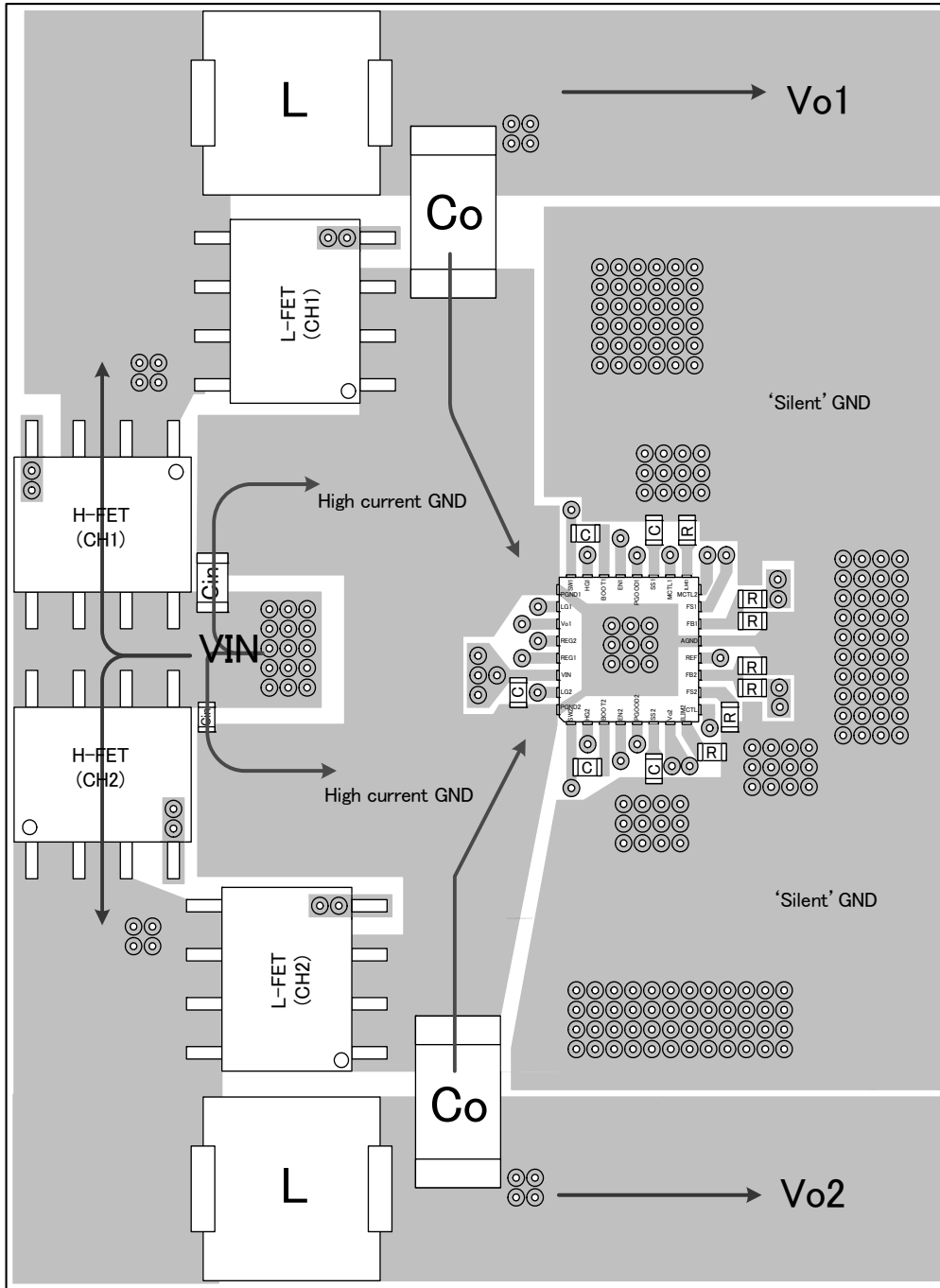
● Handling method of unused pin during using only DC/DC 1ch

If using only 1ch DC/DC and 2ch pin is set to be off at all times, please manage the unused pin as diagram below.

| PIN No, | PIN name | Management |
|---------|----------|------------|
| 1       | SW2      | GND        |
| 2       | HG2      | Open       |
| 3       | BOOT2    | Open       |
| 4       | EN2      | GND        |
| 5       | PGOOD2   | GND        |
| 6       | SS2      | GND        |
| 7       | Vo2      | GND        |
| 8       | ILIM2    | GND        |
| 10      | FS2      | GND        |
| 11      | FB2      | GND        |
| 31      | LG2      | Open       |



## ● Example of PCB layout

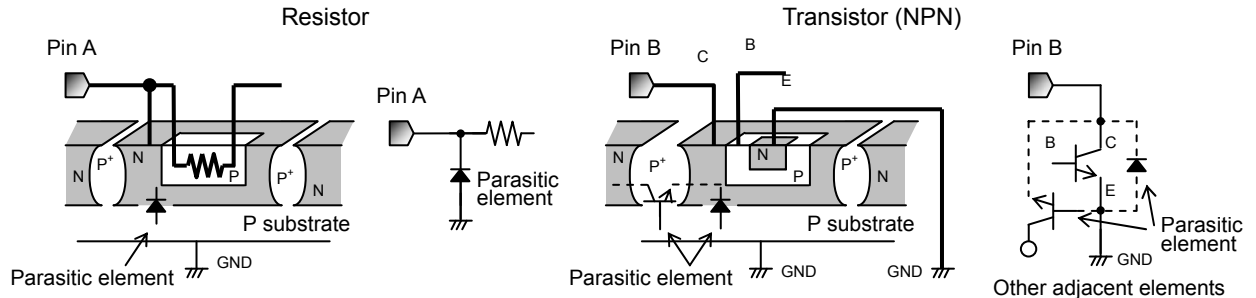


- ① Because high pulse current rush into power loop, consisted of input capacitor  $C_{in}$ , output inductor  $L$  and output capacitor  $C_o$ , this part layout should be built at parts side (upper side) including GND pattern. Also, drawing via formation in power loop line should be avoided. (The reason is that it will be a factor of noise because via oneself holds some nH parasitic inductance)
- ② FB pin has comparatively high impedance, so floating capacity should be minimum as possible. And feedback wiring from output should be taken properly, and shielding, not going through around  $L$  (because of magnetic). Please be careful in drawing.
- ③ Trace from SW node pin to inductor should be cut short. And both inductor element pattern should be kept away. (Closer wiring has SW node noise influence  $V_o$  by parasitic capacity between wiring). This layout example shows that SW node is outside, but if the application board will be like that, SW node should be shielded. Please consider the influence to other circuit.
- ④ Input capacitor  $C_{in}$  should be placed close to IC with low inductance. If that is difficult, please place a capacitor for high frequency removal with PKG size small like 0.1 $\mu$ F (ESL small).
- ⑤ 2<sup>nd</sup> layer and 3<sup>rd</sup> layer are plain GND, so connect from parts side GND to plain GND by low impedance with many via as possible. Inner GND is only for shielding, so that no to form loop for high current.
- ⑥ Please take GND pattern space widely, and design layout to be able to increase radiation efficiency.
- ⑦ FS pin and ILIM pin has high impedance. External resistor should be connected to "Silent GND".

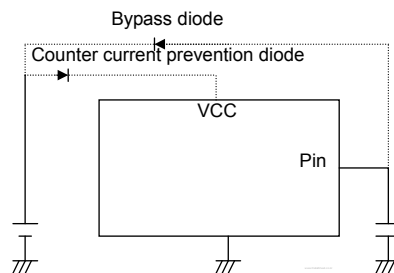
### ● Operation Notes and Precautions

- This integrated circuit is a monolithic IC, which (as shown in the figure below), has P<sup>+</sup> isolation in the P substrate and between the various pins. A P-N junction is formed from this P layer and N layer of each pin, with the type of junction depending on the relation between each potential, as follows:
  - When GND > element A > element B, the P-N junction is a diode.
  - When element B > GND element A, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, as well as operating malfunctions and physical damage. Therefore, be careful to avoid methods by which parasitic diodes operate, such as applying a voltage lower than the GND (P substrate) voltage to an input pin.



- In some modes of operation, power supply voltage and pin voltage are reversed, giving rise to possible internal circuit damage. For example, when the external capacitor is charged, the electric charge can cause a VCC short circuit to the GND. In order to avoid these problems, inserting a VCC series countercurrent prevention diode or bypass diode between the various pins and the VCC is recommended.



- Absolute maximum rating**  
Although the quality of this IC is rigorously controlled, the IC may be destroyed when applied voltage or operating temperature exceeds its absolute maximum rating. Because short mode or open mode cannot be specified when the IC is destroyed, it is important to take physical safety measures such as fusing if a special mode in excess of absolute rating limits is to be implemented.
- GND potential**  
Make sure the potential for the GND pin is always kept lower than the potentials of all other pins, regardless of the operating mode.
- Thermal design**  
In order to build sufficient margin into the thermal design, give proper consideration to the allowable loss (Power Dissipation) in actual operation.
- Short-circuits between pins and incorrect mounting position**  
When mounting the IC onto the circuit board, be extremely careful about the orientation and position of the IC. The IC may be destroyed if it is incorrectly positioned for mounting. Do not short-circuit between any output pin and supply pin or ground, or between the output pins themselves. Accidental attachment of small objects on these pins will cause shorts and may damage the IC.
- Operation in strong electromagnetic fields**  
Use in strong electromagnetic fields may cause malfunctions. Use extreme caution with electromagnetic fields.
- Thermal shutdown circuit**  
This IC is provided with a built-in thermal shutdown (TSD) circuit, which is activated when the operating temperature reaches 175°C (standard value), and has a hysteresis range of -15°C (standard value). When the IC chip temperature rises to the threshold, all the inputs automatically turn OFF. Note that the TSD circuit is provided for the exclusive purpose shutting down the IC in the presence of extreme heat, and is not designed to protect the IC per se or guarantee performance when or after extreme heat conditions occur. Therefore, do not operate the IC with the expectation of continued use or subsequent operation once the TSD is activated.

## 9. Capacitor between output and GND

When a larger capacitor is connected between the output and GND, Vcc or VIN shorted with the GND or 0V line – for any reason – may cause the charged capacitor current to flow to the output, possibly destroying the IC. Do not connect a capacitor larger than 1000uF between the output and GND.

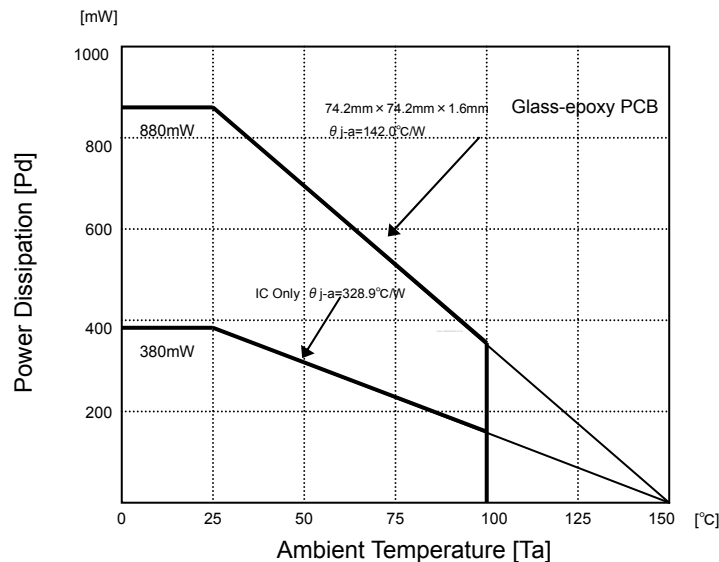
## 10. Precautions for board inspection

Connecting low-impedance capacitors to run inspections with the board may produce stress on the IC. Therefore, be certain to use proper discharge procedure before each process of the operation. To prevent electrostatic accumulation and discharge in the assembly process, thoroughly ground yourself and any equipment that could sustain ESD damage, and continue observing ESD-prevention procedures in all handling, transfer and storage operations. Before attempting to connect components to the test setup, make certain that the power supply is OFF. Likewise, be sure the power supply is OFF before removing any component connected to the test setup.

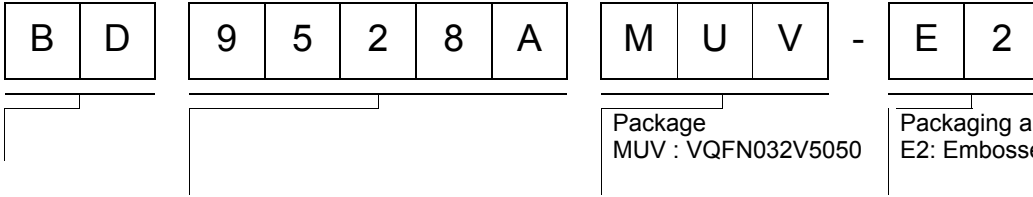
## 11. GND wiring pattern

When both a small-signal GND and high current GND are present, single-point grounding (at the set standard point) is recommended, in order to separate the small-signal and high current patterns, and to be sure the voltage change stemming from the wiring resistance and high current does not cause any voltage change in the small-signal GND. In the same way, care must be taken to avoid wiring pattern fluctuations in any connected external component GND.

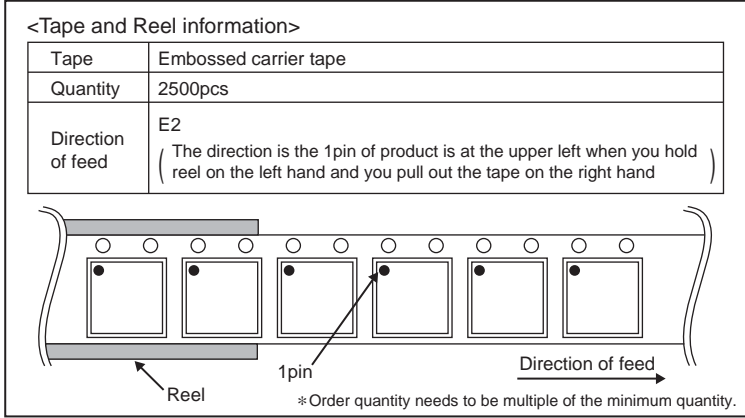
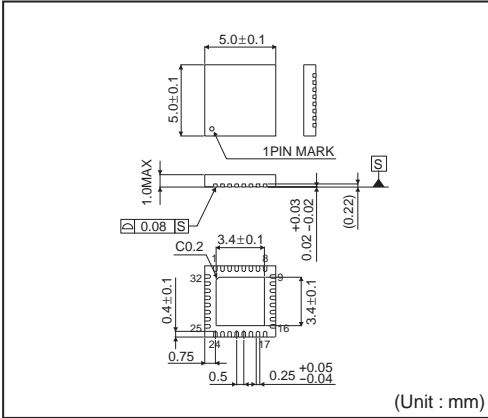
## ● Heat Dissipation Characteristics



●Ordering Part Number



VQFN032V5050



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