ANALOG DEVICES

Ultralow Noise Amplifier at Lower Power

ADA4075-2

FEATURES

Ultralow noise: 2.8 nV/√Hz at 1 kHz typical
Ultralow distortion: 0.0002% typical
Low supply current: 1.8 mA per amplifier typical
Offset voltage: 1 mV maximum
Bandwidth: 6.5 MHz typical
Slew rate: 12 V/μs typical
Unity-gain stable
Extended industrial temperature range
SOIC package

APPLICATIONS

Precision instrumentation
Professional audio
Active filters
Low noise amplifier front end
Integrators

GENERAL DESCRIPTION

The ADA4075-2 is a dual, high performance, low noise operational amplifier combining excellent dc and ac characteristics on the Analog Devices, Inc., *i*Polar® process. The *i*Polar process is an advanced bipolar technology implementing vertical junction isolation with lateral trench isolation. This allows for low noise performance amplifiers in smaller die size at faster speed and lower power. Its high slew rate, low distortion, and ultralow noise make the ADA4075-2 ideal for high fidelity audio and high performance instrumentation applications. It is also especially useful for lower power demands, small enclosures, and high density applications. The ADA4075-2 is specified for the temperature range of −40°C to +125°C and is available in a standard SOIC package.

PIN CONFIGURATION

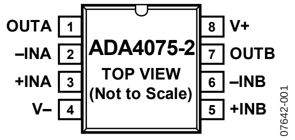

Figure 1. 8-Lead SOIC

Table 1. Low Noise Precision Op Amps

Supply	44 V	36 V	12 V to 16 V	5 V
Single	OP27	AD8671 AD8675 AD797	AD8665 OP162	AD8605 AD8655 AD8691
Dual	OP275	AD8672 AD8676 AD8599	AD8666 OP262	AD8606 AD8656 AD8692
Quad		ADA4004-4 AD8674	AD8668 OP462	AD8608 AD8694

Rev. 0

One Technology Way, P.O. Box 9106, Norwood, MA 02062-9106, U.S.A.
Tel: 781.329.4700 **www.analog.com**
Fax: 781.461.3113

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REVISION HISTORY

10/08—Revision 0: Initial Version

SPECIFICATIONS

V_{SY} = ±15 V, V_{CM} = 0 V, T_A = 25°C, unless otherwise noted.

Table 2.

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
Offset Voltage	V_{OS}			0.2	1	mV
		−40°C ≤ T_A ≤ +125°C			1.2	mV
Input Bias Current	I_B			30	100	nA
		−40°C ≤ T_A ≤ +125°C			150	nA
Input Offset Current	I_{OS}			5	50	nA
		−40°C ≤ T_A ≤ +125°C			75	nA
Input Voltage Range		−40°C ≤ T_A ≤ +125°C	−12.5		+12.5	V
Common-Mode Rejection Ratio	CMRR	V_{CM} = −12.5 V to +12.5 V	110	118		dB
		−40°C ≤ T_A ≤ +125°C	106			dB
Large-Signal Voltage Gain	A_{VO}	R_L = 2 kΩ, V_O = −11 V to +11 V	114	117		dB
		−40°C ≤ T_A ≤ +125°C	108			dB
		R_L = 600 Ω, V_O = −10 V to +10 V	112	117		dB
		−40°C ≤ T_A ≤ +125°C	106			dB
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$	−40°C ≤ T_A ≤ +125°C		0.3		μV/°C
Input Resistance	R_{IN}			40		MΩ
Input Capacitance, Differential Mode	C_{INDM}			2.4		pF
Input Capacitance, Common Mode	C_{INCM}			2.1		pF
OUTPUT CHARACTERISTICS						
Output Voltage High	V_{OH}	R_L = 2 kΩ to GND	12.8	13		V
		−40°C ≤ T_A ≤ +125°C	12.5			V
		R_L = 600 Ω to GND	12.4	12.8		V
		−40°C ≤ T_A ≤ +125°C	12			V
		V_{SY} = ±18 V, R_L = 600 Ω to GND	15.4	15.8		V
		−40°C ≤ T_A ≤ +125°C	15			V
Output Voltage Low	V_{OL}	R_L = 2 kΩ to GND		−14	−13.6	V
		−40°C ≤ T_A ≤ +125°C			−13	V
		R_L = 600 Ω to GND		−13.6	−13	V
		−40°C ≤ T_A ≤ +125°C			−12.5	V
		V_{SY} = ±18 V, R_L = 600 Ω to GND		−16.6	−16	V
		−40°C ≤ T_A ≤ +125°C			−15.5	V
Short-Circuit Current	I_{SC}			40		mA
Closed-Loop Output Impedance	Z_{OUT}	f = 100 kHz, A_V = 1		0.3		Ω
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	V_{SY} = ±4.5 V to ±18 V	106	110		dB
		−40°C ≤ T_A ≤ +125°C	100			dB
Supply Current per Amplifier	I_{SY}	V_{SY} = ±4.5 V to ±18 V, I_O = 0 mA		1.8	2.25	mA
		−40°C ≤ T_A ≤ +125°C			3.35	mA
DYNAMIC PERFORMANCE						
Slew Rate	SR	R_L = 2 kΩ, A_V = 1		12		V/μs
Settling Time	t_S	To 0.01%, V_{IN} = 10 V step, R_L = 1 kΩ		3		μs
Gain Bandwidth Product	GBP	R_L = 1 MΩ, C_L = 35 pF, A_V = 1		6.5		MHz
Phase Margin	Φ_M	R_L = 1 MΩ, C_L = 35 pF, A_V = 1		60		Degrees
THD + NOISE						
Total Harmonic Distortion and Noise	THD + N	R_L = 2 kΩ, A_V = 1, V_{IN} = 3 V rms, f = 20 Hz to 20 kHz		0.0002		%
NOISE PERFORMANCE						
Voltage Noise	e_n p-p	f = 0.1 Hz to 10 Hz		60		nV p-p
Voltage Noise Density	e_n	f = 1 kHz		2.8		nV/√Hz
Current Noise Density	i_n	f = 1 kHz		1.2		pA/√Hz

ABSOLUTE MAXIMUM RATINGS

Table 2.

Parameter	Rating
Supply Voltage	±20 V
Input Voltage	$\pm V_{SY}$
Input Current[1]	±10 mA
Differential Input Voltage	±1 V
Output Short-Circuit Duration to GND	Indefinite
Storage Temperature Range	−65°C to +150°C
Operating Temperature Range	−40°C to +125°C
Junction Temperature Range	−65°C to +150°C
Lead Temperature (Soldering, 60 sec)	300°C

[1] The input pins have clamp diodes to the power supply pins.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL RESISTANCE

θ_{JA} is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages. This was measured using a standard 2-layer board.

Table 3. Thermal Resistance

Package Type	θ_{JA}	θ_{JC}	Unit
8-Lead SOIC	158	43	°C/W

POWER SEQUENCING

The op amp supplies must be established simultaneously with, or before, any input signals are applied. If this is not possible, the input current must be limited to 10 mA.

ESD CAUTION

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

TYPICAL PERFORMANCE CHARACTERISTICS

T_A = 25°C, unless otherwise noted.

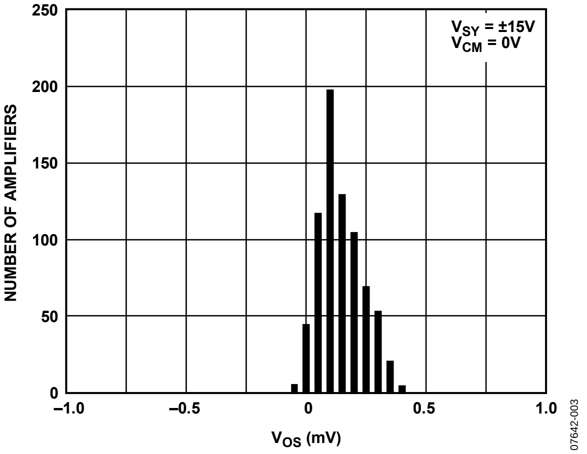


Figure 2. Input Offset Voltage Distribution

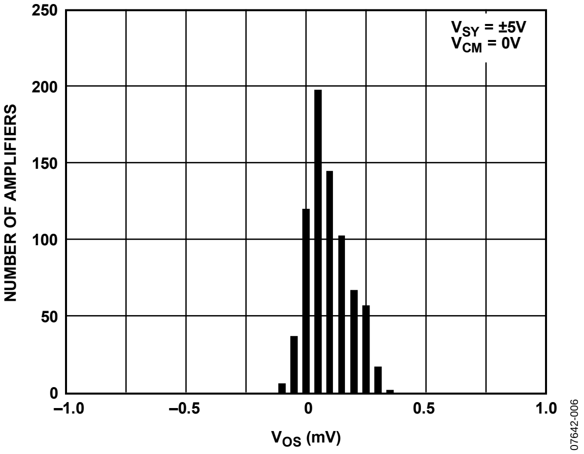


Figure 5. Input Offset Voltage Distribution

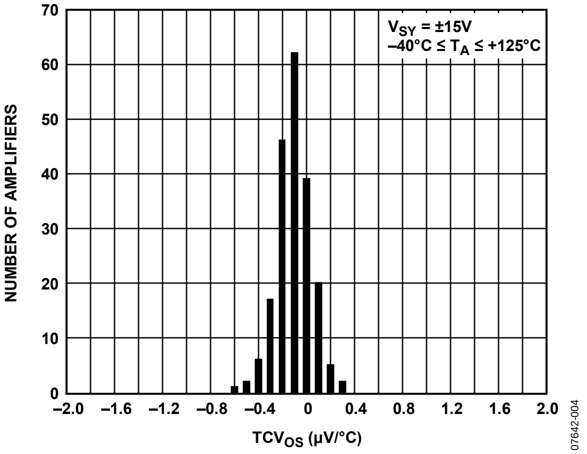
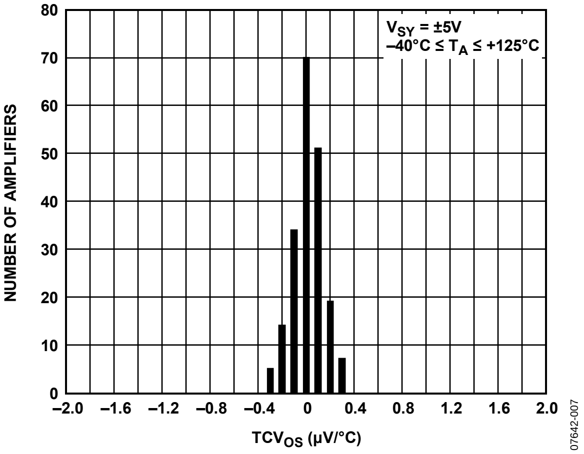


Figure 3. Input Offset Voltage Drift Distribution



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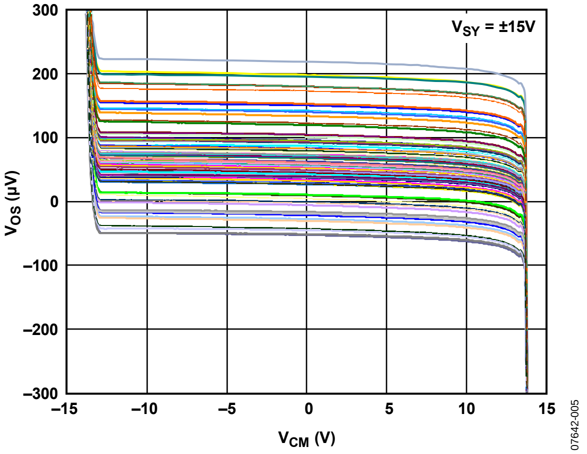
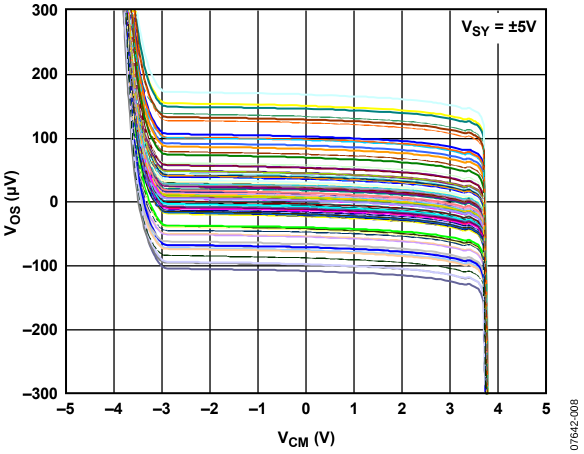


Figure 4. Input Offset Voltage vs. Common-Mode Voltage



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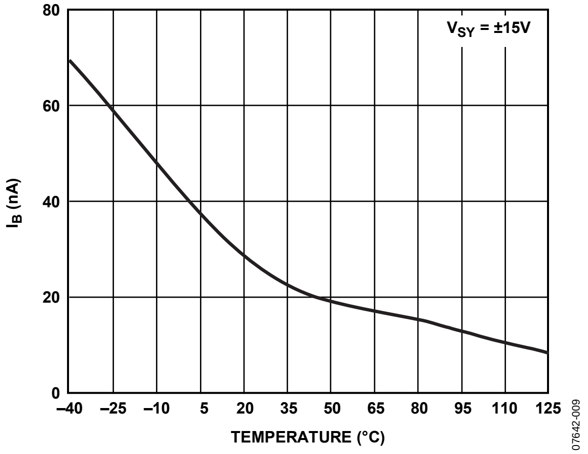

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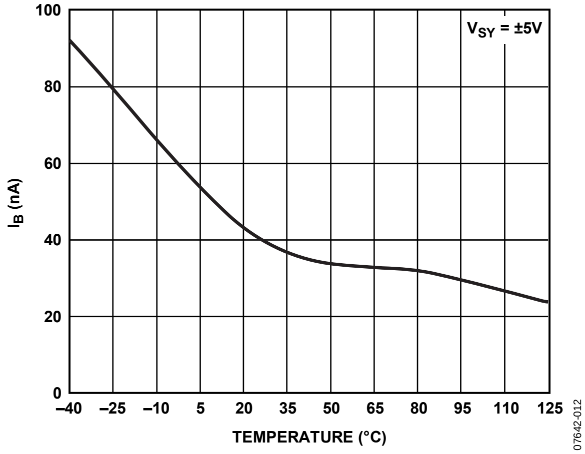

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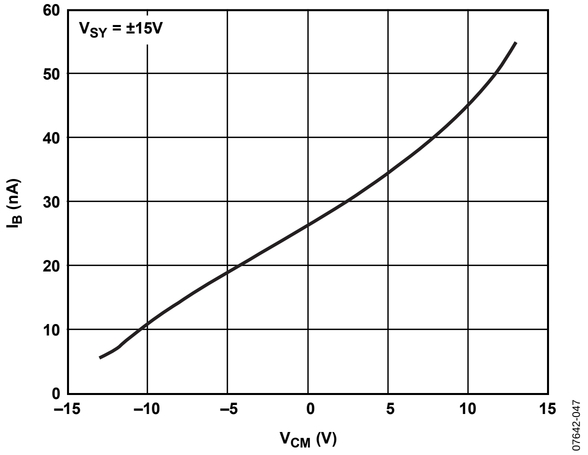

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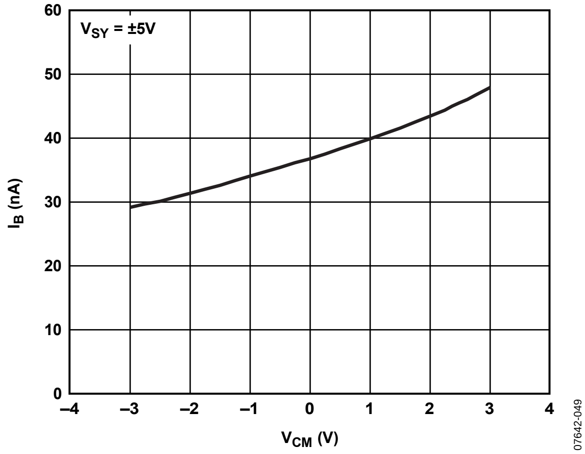

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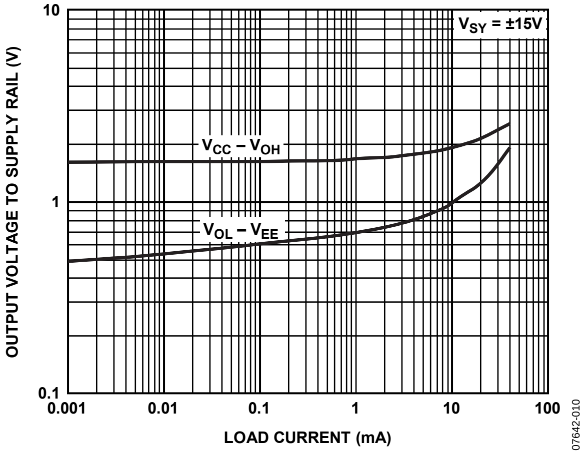


Figure 10. Output Voltage to Supply Rail vs. Load Current

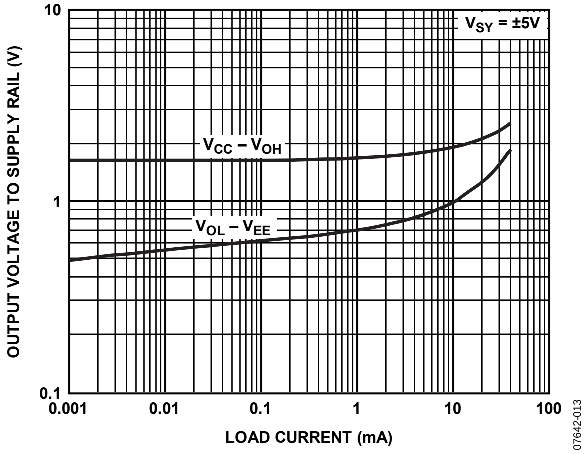
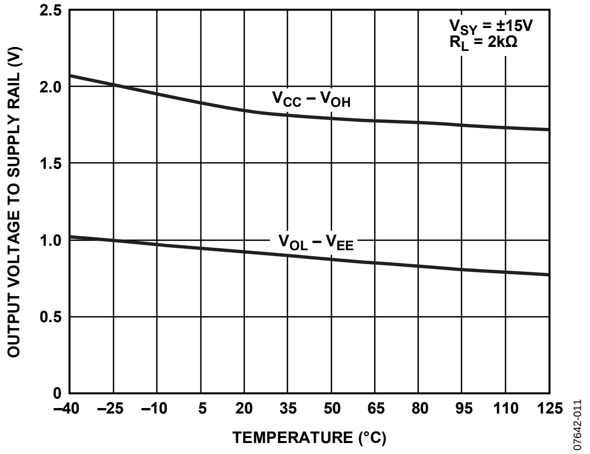


Figure 13. Output Voltage to Supply Rail vs. Load Current



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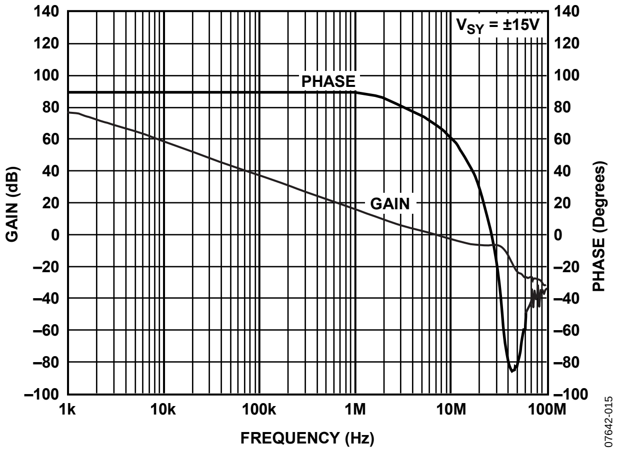
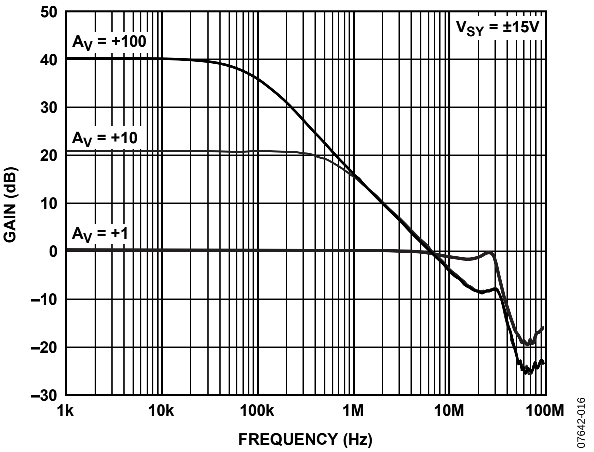


Figure 15. Open-Loop Gain and Phase vs. Frequency



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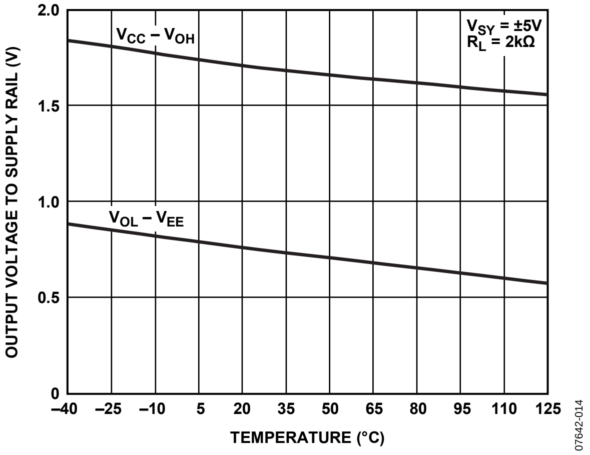

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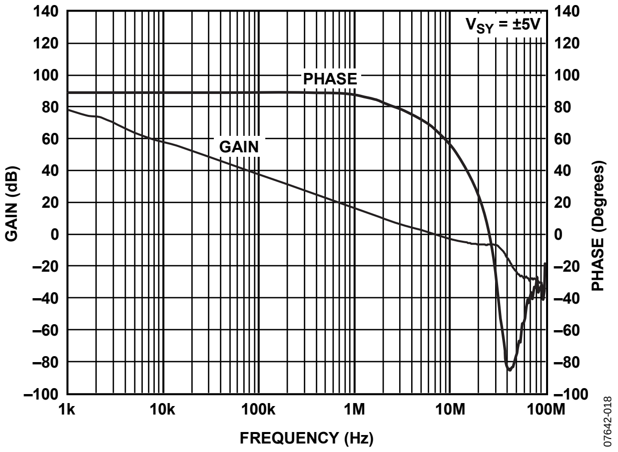

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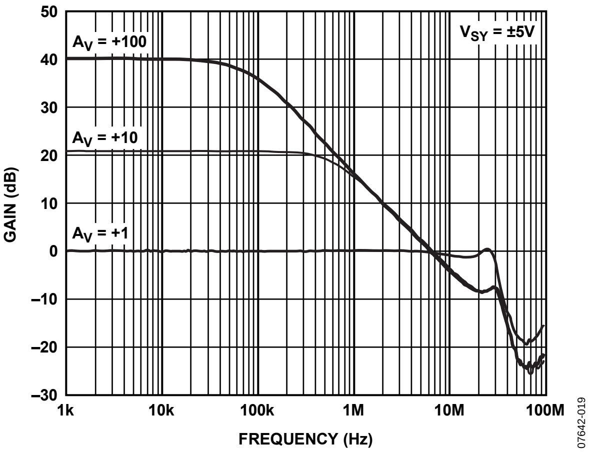

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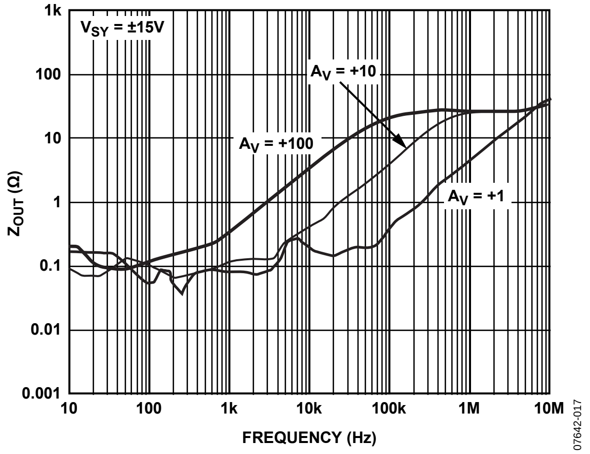

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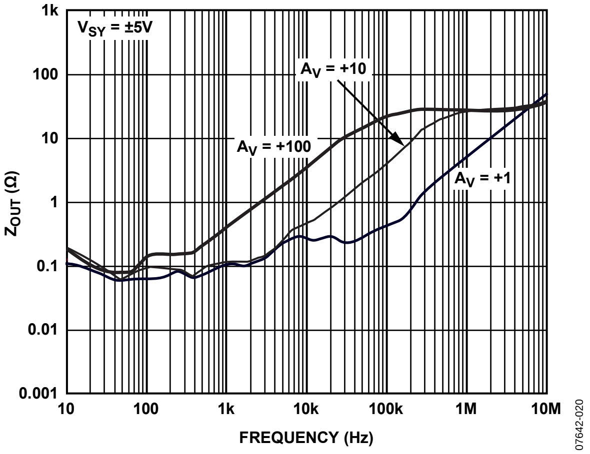

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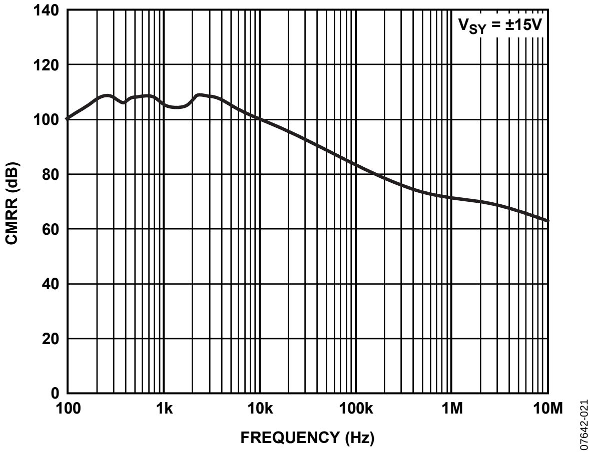

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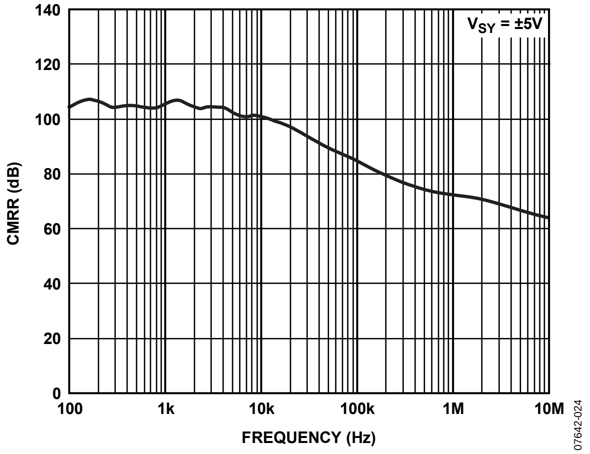

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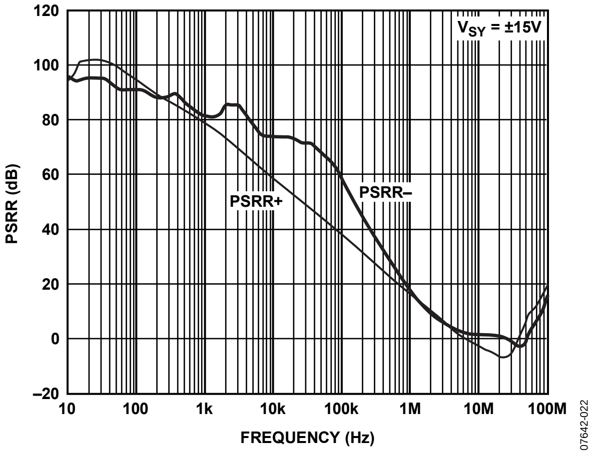

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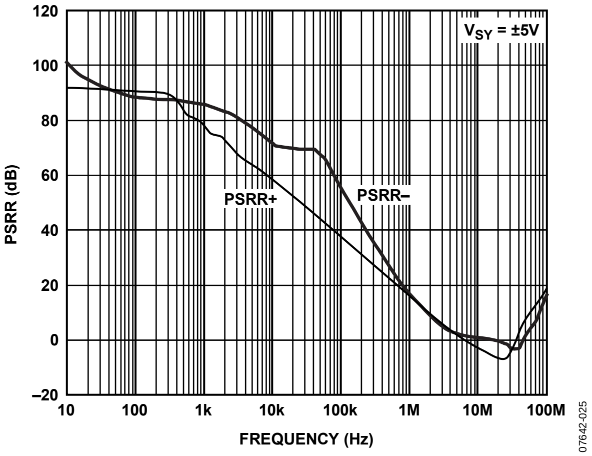

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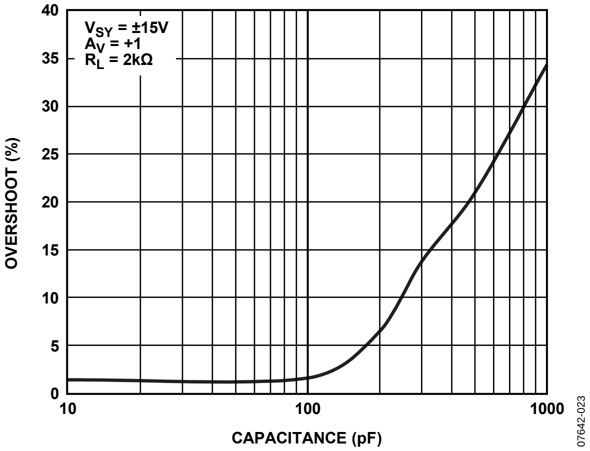

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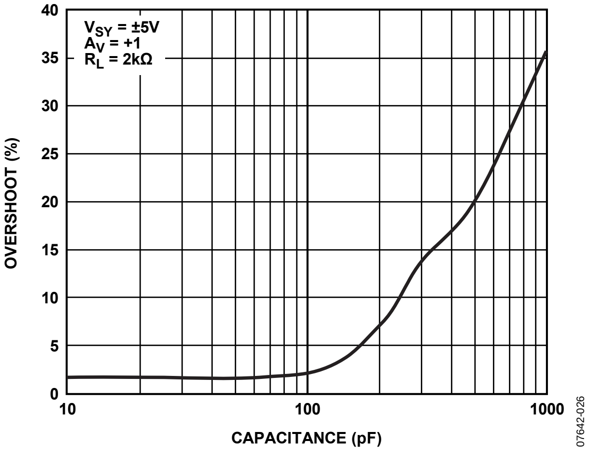

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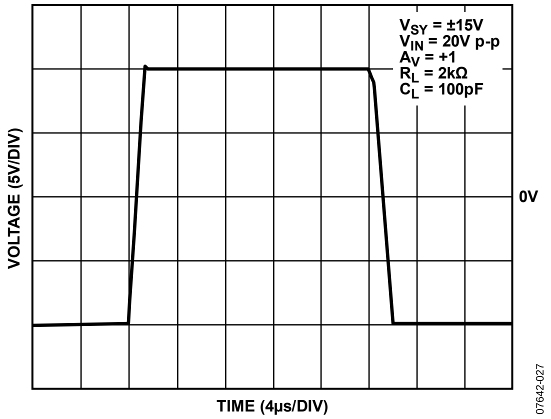

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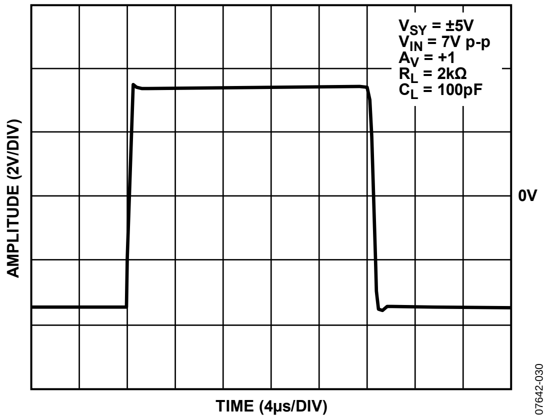

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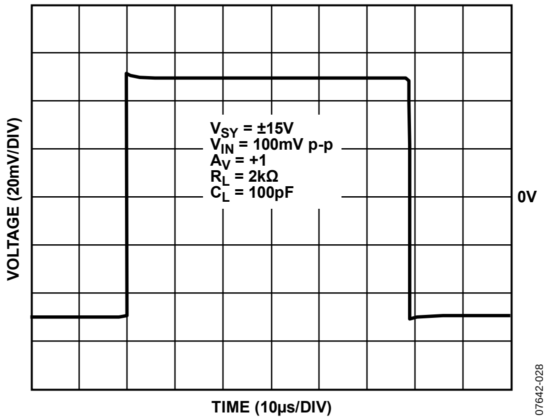

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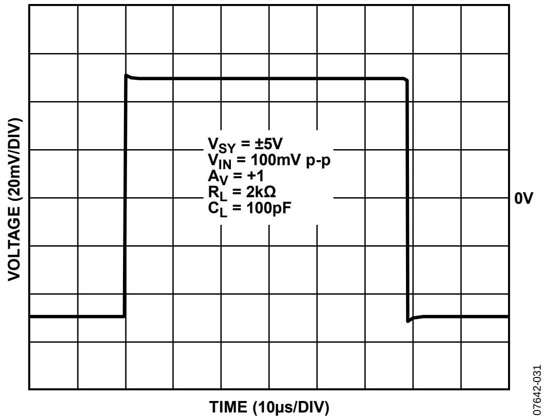

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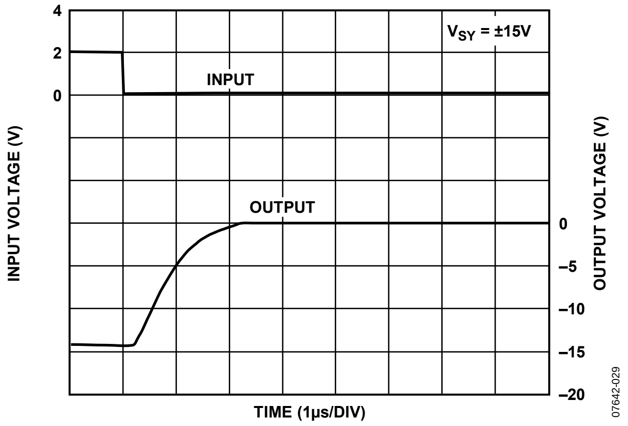


Figure 32. Negative Overload Recovery

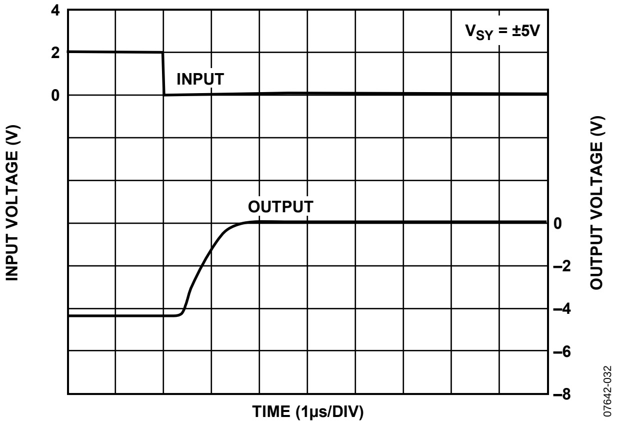


Figure 35. Negative Overload Recovery

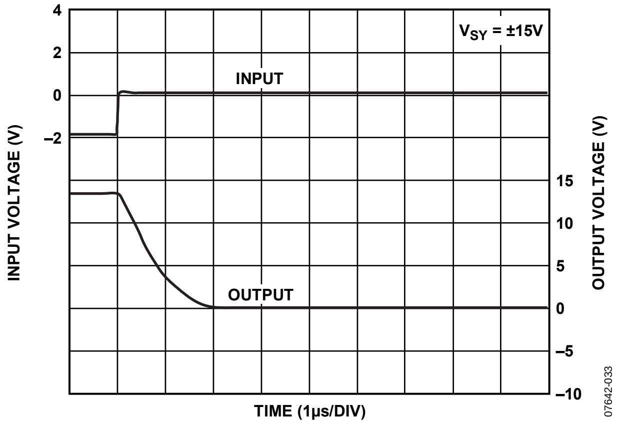


Figure 33. Positive Overload Recovery

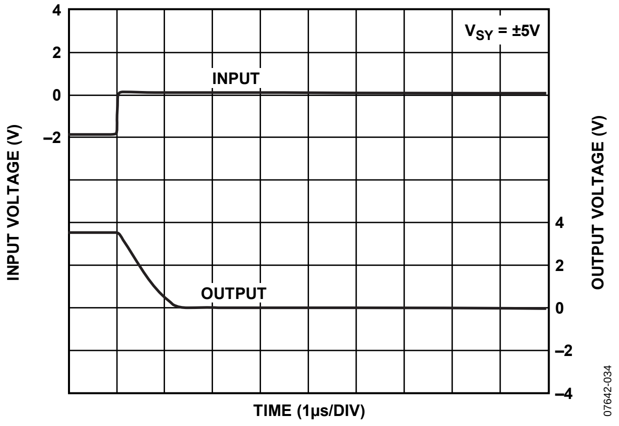


Figure 36. Positive Overload Recovery

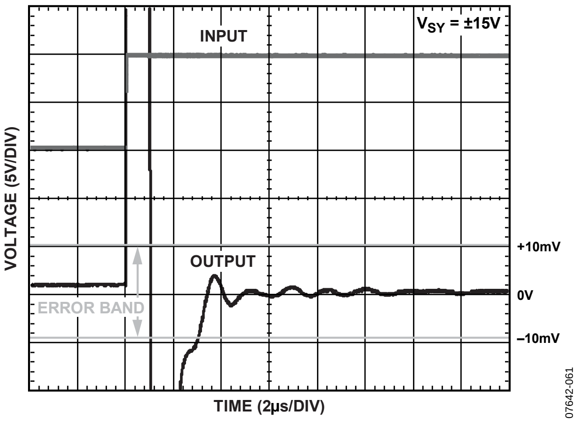


Figure 34. Positive Settling Time to 0.01%

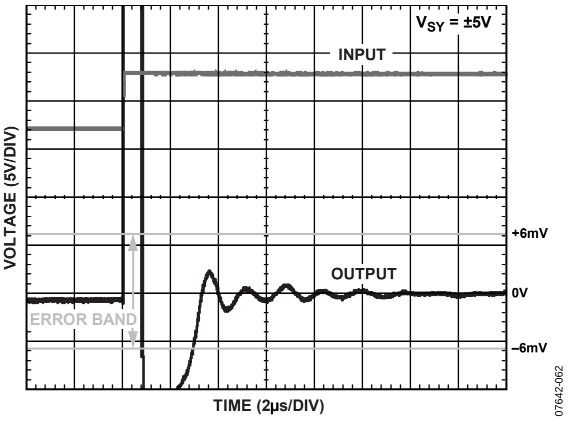


Figure 37. Positive Settling Time to 0.01%

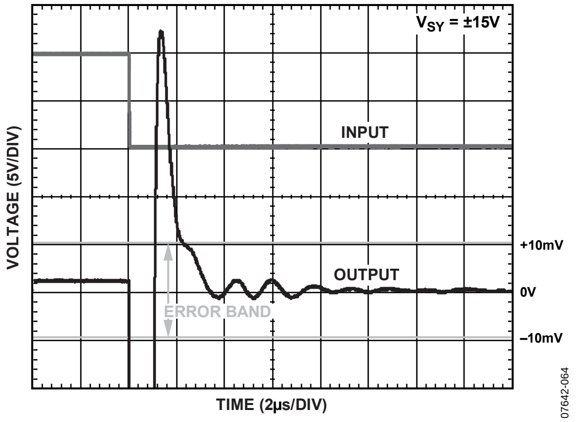
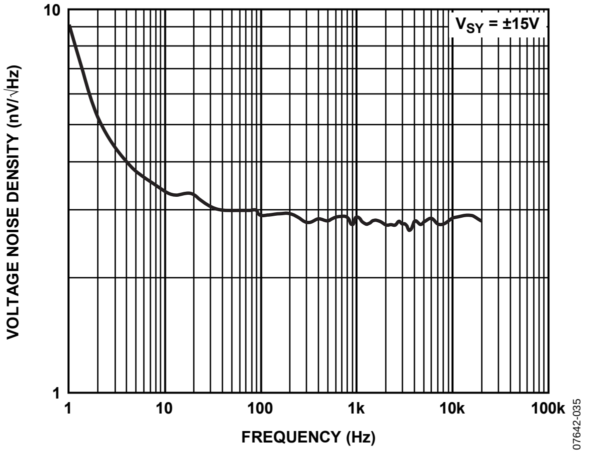


Figure 38. Negative Settling Time to 0.01%



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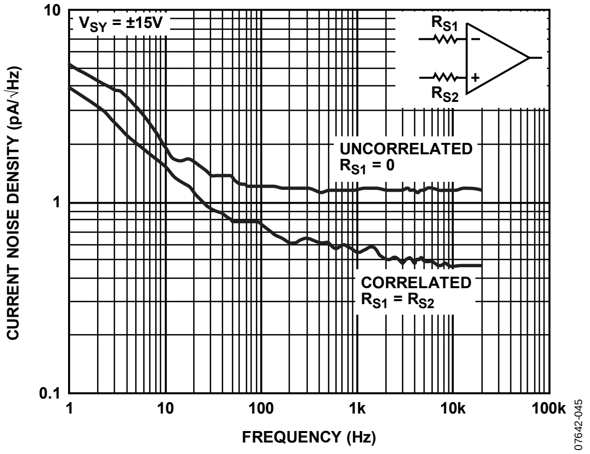


Figure 40. Current Noise Density

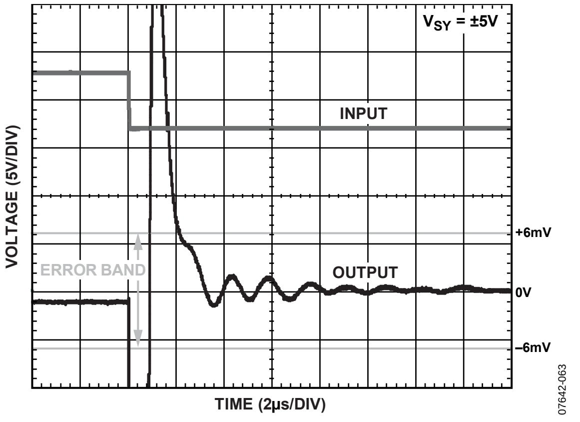


Figure 41. Negative Settling Time to 0.01%

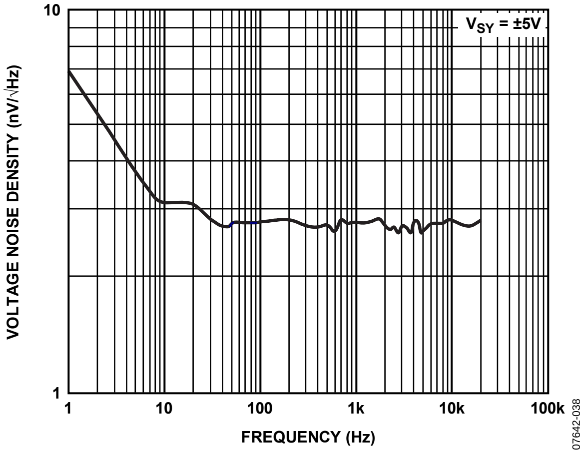


Figure 42. Voltage Noise Density

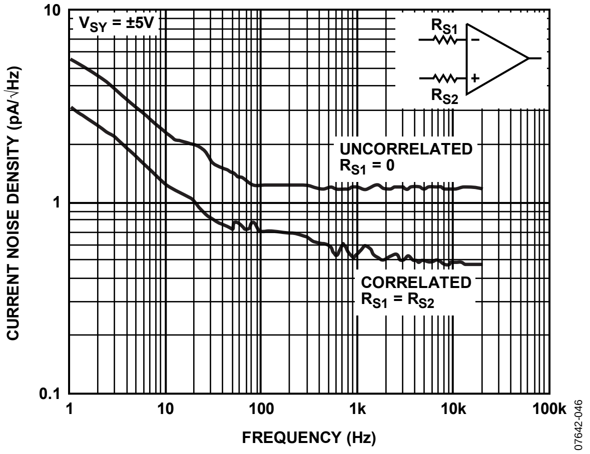


Figure 43. Current Noise Density

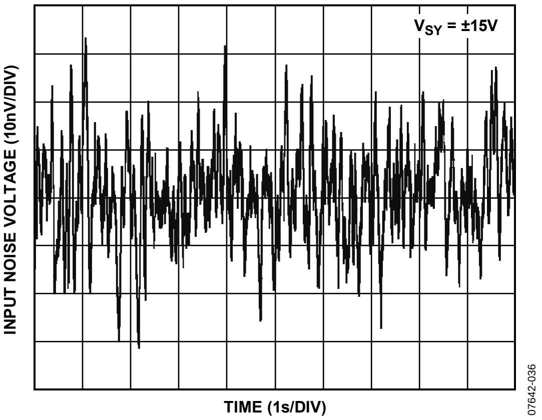


Figure 44. 0.1 Hz to 10 Hz Noise

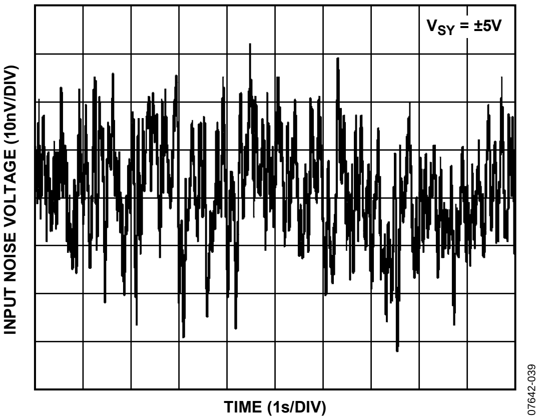


Figure 47. 0.1 Hz to 10 Hz Noise

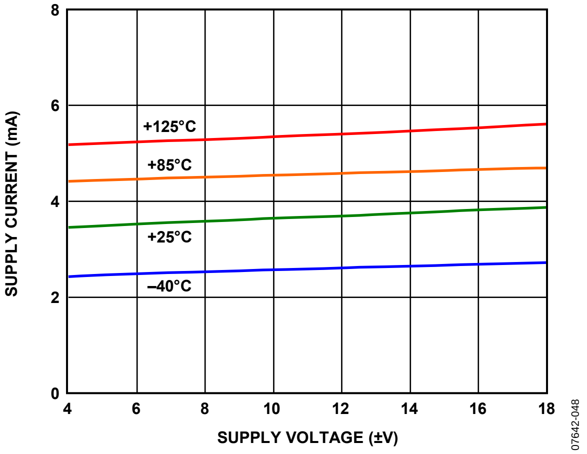


Figure 45. Supply Current vs. Supply Voltage

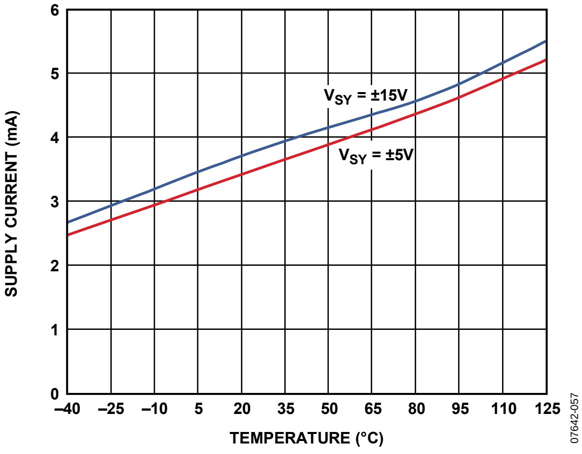


Figure 48. Supply Current vs. Temperature

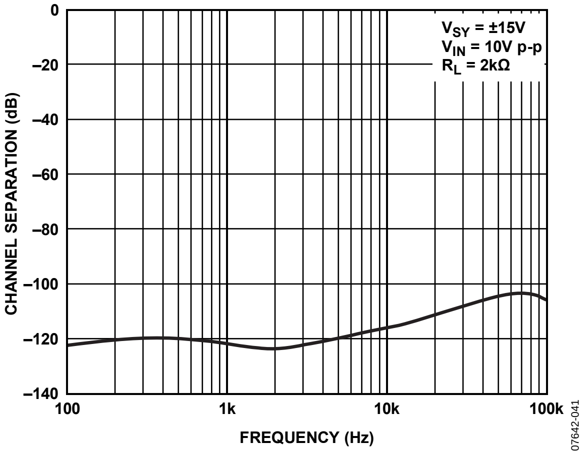


Figure 46. Channel Separation vs. Frequency

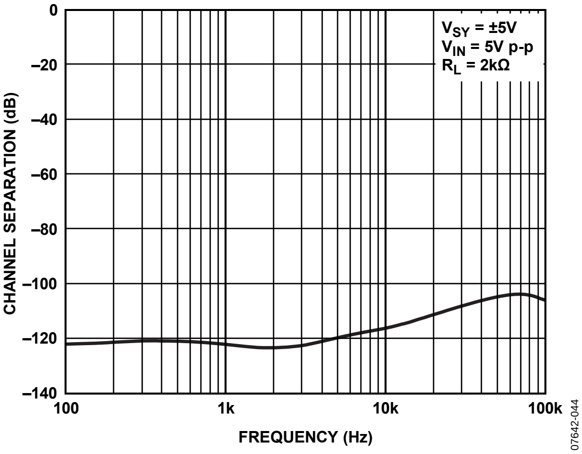


Figure 49. Channel Separation vs. Frequency

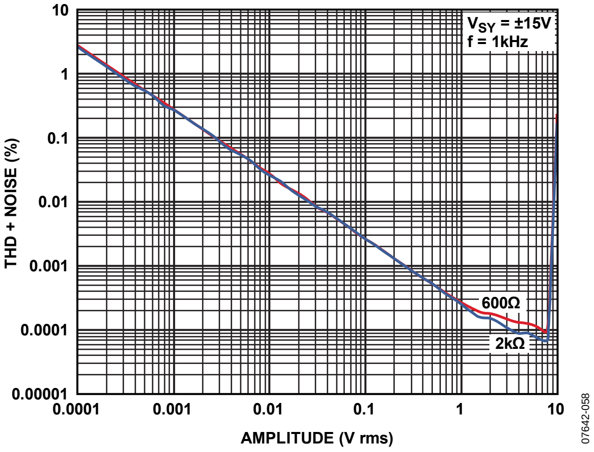


Figure 50. THD + Noise vs. Amplitude

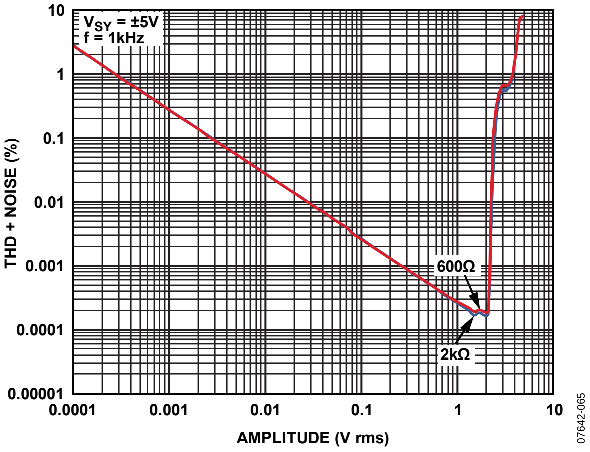


Figure 53. THD + Noise vs. Amplitude

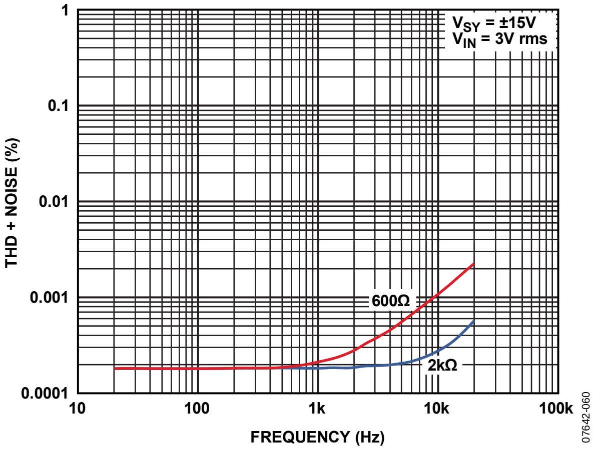


Figure 51. THD + Noise vs. Frequency

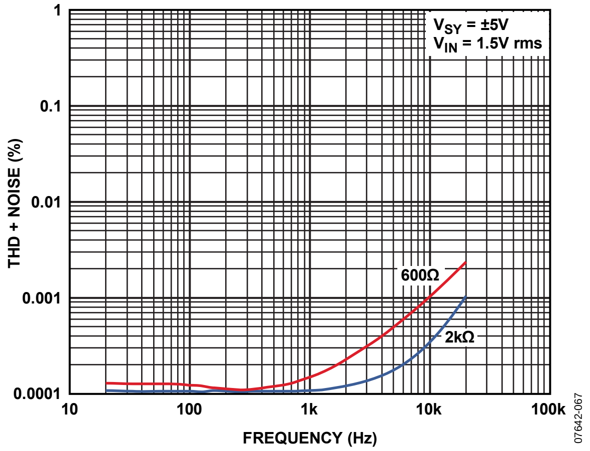


Figure 54. THD + Noise vs. Frequency

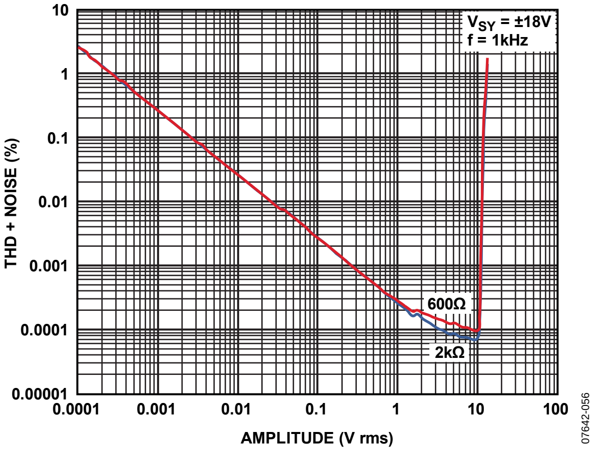


Figure 52. THD + Noise vs. Amplitude

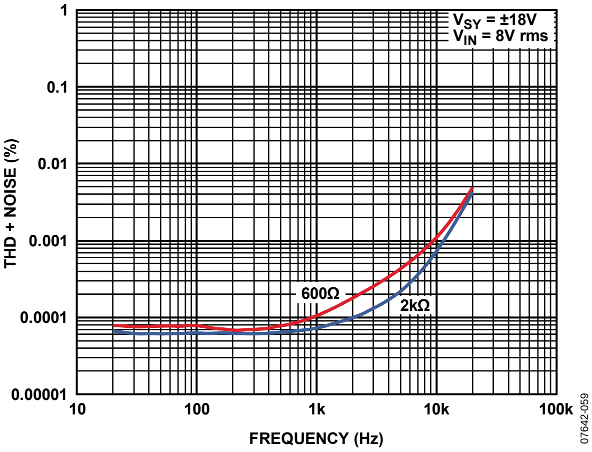


Figure 55. THD + Noise vs. Frequency

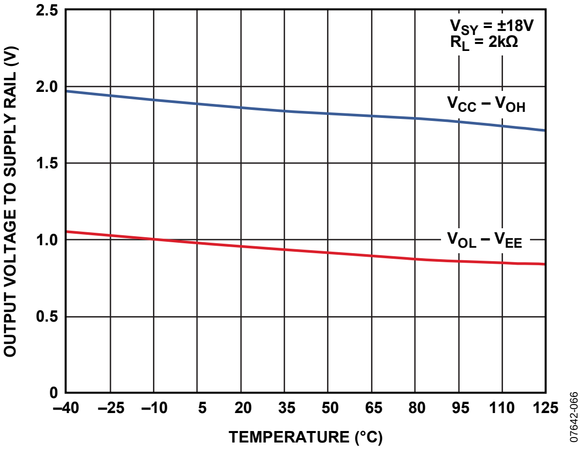


Figure 56. Output Voltage to Supply Rail vs. Temperature

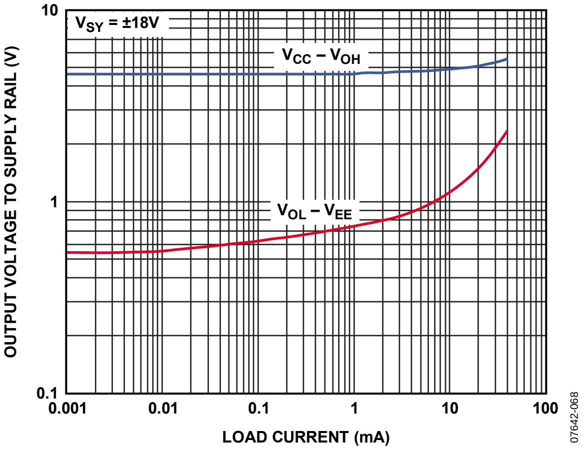


Figure 57. Output Voltage to Supply Rail vs. Load Current

APPLICATIONS INFORMATION

INPUT PROTECTION

The maximum differential input voltage that can be applied to the ADA4075-2 is determined by the internal diodes connected across its inputs. These diodes limit the maximum differential input voltage to ±1 V and are needed to prevent base-emitter junction breakdown from occurring in the input stage of the ADA4075-2 when very large differential voltages are applied. To make sure that the ultralow voltage noise feature of the ADA4075-2 is preserved, the commonly used internal resistors in series with the inputs were not used to limit the current in the diodes.

In small-signal applications, this is not an issue; however, in applications where large differential voltages can be inadvertently applied to the device, large currents may flow through these diodes. If the differential voltage of the ADA4075-2 exceeds ±1 V, external resistors should be used at both inputs of the op amp to limit the input currents to less than ±10 mA (see Figure 58). However, when series resistors are added, the total voltage noise degrades because the resistors may have a thermal noise that is greater than the voltage noise of the op amp itself. For example, a 1 kΩ resistor at room temperature has a thermal noise of 4 nV/√Hz, whereas the ADA4075-2 has an ultralow voltage noise of only 2.8 nV/√Hz typical.

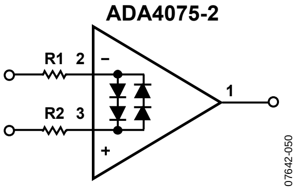


Figure 58. Input Protection

TOTAL HARMONIC DISTORTION

The total harmonic distortion + noise (THD + N) of the ADA4075-2 is 0.0002% typical with a load resistance of 2 kΩ. Figure 59 shows the performance of the ADA4075-2 driving a 2 kΩ load with supply voltages of ±4 V and ±15 V. Notice that there is more distortion for the supply voltage of ±4 V than for a supply voltage of ±15 V. Thus, it is very important to operate the ADA4075-2 at a supply voltage greater than ±5 V for optimum distortion. The THD + noise graphs for supply voltages of ±5 V and ±18 V are available in Figure 54 and Figure 55.

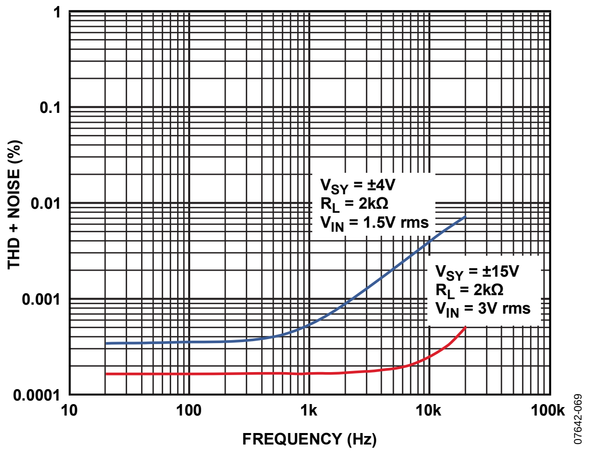


Figure 59. THD + Noise vs. Frequency

PHASE REVERSAL

Phase reversal occurs in some amplifiers when the input common-mode voltage range is exceeded. When the voltage driving the input to these amplifiers exceeds the maximum input common-mode voltage range, the output of the amplifiers changes polarity. Phase reversal can cause permanent damage to the amplifier as well as system lockups in feedback loops.

The ADA4075-2 amplifiers have been carefully designed to prevent output phase reversal when both inputs are maintained within the specified input voltage range. If one or both inputs exceed the input voltage range but remain within the supply rails, the output is capped at the maximum output that it can swing to. For a supply voltage of ±15 V and a load resistance of 2 kΩ, the output is capped at 13 V typical when the input voltage exceeds the input voltage range but stays within the supply rails. Figure 60 shows the output voltage of the AD4075-2 configured as a unity-gain buffer with a supply voltage of ±15 V.

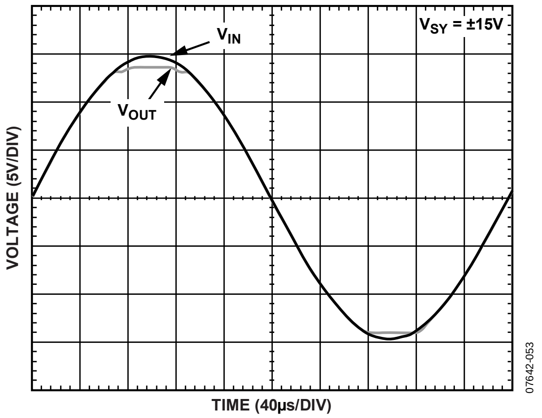


Figure 60. No Phase Reversal

DAC OUTPUT FILTER

The ultralow voltage noise, low distortion, and high slew rate of the ADA4075-2 make it an ideal choice for professional audio signal processing. Figure 61 shows the ADA4075-2 used in a typical audio DAC output filter configuration. The differential outputs of the DAC are fed into the ADA4075-2. The ADA4075-2 is configured as a differential Sallen-key filter. It operates as an external low-pass filter to remove high frequency noise present on the output pins of the DAC. It also provides differential-to-single-ended conversion from the differential outputs of the DAC.

For a DAC output filter, an op amp with reasonable slew rate and bandwidth is required. The slew rate of the ADA4075-2 is at a high 12 V/μs, and the bandwidth is 6.5 MHz. The cutoff frequency of the low-pass filter is approximately 167 kHz. In addition, the 100 kΩ and 47 μF RC network perform ac coupling to block out the dc components at the output.

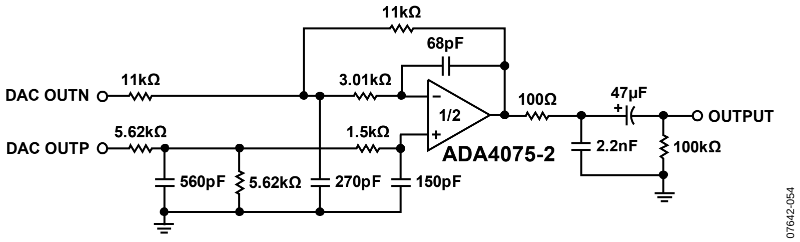


Figure 61. Typical DAC Output Filter Circuit (Differential)

BALANCED LINE DRIVER

The circuit of Figure 62 shows a balanced line driver designed for audio use. Such drivers are intended to mimic an output transformer in operation, whereby the common-mode voltage can be impressed by the load. Furthermore, either output can be shorted to ground in single-ended applications without affecting the overall operation.

Circuits of this type use positive and negative feedback to obtain a high common-mode output impedance, and they are somewhat notorious for component sensitivity and susceptibility to latch-up. This circuit uses several techniques to avoid spurious behavior.

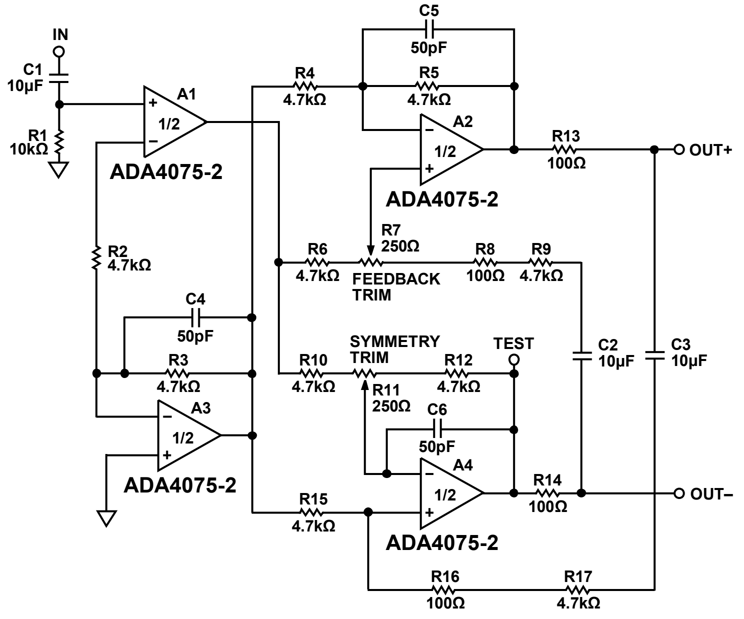
First, the 4-op-amp arrangement ensures that the input impedance is load independent (the input impedance can become negative with some configurations). Note that the output op amps are packaged with the input op amps to maximize drive capability.

Second, the positive feedback is ac-coupled by C2 and C3, which eliminates the need for offset trim. Because the circuit is ac-coupled at the input, these capacitors do not have significant dc voltage across them, thus tantalum types of capacitors can be used.

Finally, even with these precautions, it is vital that the positive feedback be accurately controlled. This is partly achieved by using 1% resistors. In addition, the following setup procedure ensures that the positive feedback does not become excessive:

1. Set R11 to its mid position (or short the ends together, whichever is easier), and temporarily short the negative output to ground.
2. Apply a 10 V p-p sine wave at approximately 1 kHz to the input, and adjust R7 to provide 930 mV p-p at the point marked “test.”
3. Remove the short from the negative output (and across R11, if used), and adjust R11 until the output waveforms are symmetric.

The overall gain of the driver is equal to 2, which provides an extra 6 dB of headroom in balanced differential mode. The output noise is about −109 dBV in a 20 kHz bandwidth.



NOTES
1. ALL RESISTORS SHOULD HAVE 1% TOLERANCE.
2. A1/A2 IN SAME PACKAGE; A3/A4 IN SAME PACKAGE.

Figure 62. Balanced Line Driver

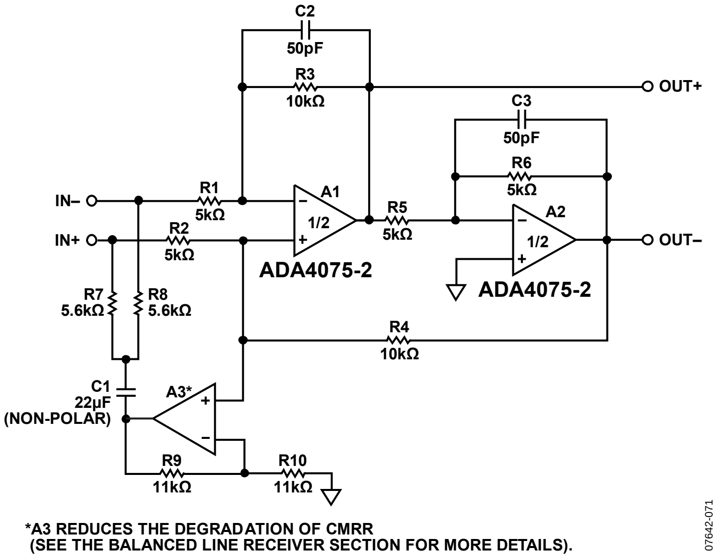
BALANCED LINE RECEIVER

Figure 63 depicts a unity-gain balanced line receiver capable of a high degree of hum rejection. The CMRR is approximately given by

$$20\log_{10}\left(\frac{R1R4}{R2R3}\right)$$

Therefore, R1 to R4 should be close-tolerance components to obtain the best possible CMRR without adjustment. The presence of A2 ensures that the impedances are symmetric at the two inputs (unlike many other designs), and, as a bonus, A2 also provides a complementary output. A3 raises the common-mode input impedance from about 7.5 kΩ to about 70 kΩ, reducing the degradation of CMRR due to mismatches in source impedance. It should be noted that A3 is not in the signal path, and almost any op amp will work well here. Although it may seem as though the inverting output should be noisier than the noninverting one, they are in fact symmetric at about −111 dBV (20 kHz bandwidth).

Sometimes an overall gain of ½ is desired to provide an extra 6 dB of differential input headroom. This can be attained by reducing R3 and R4 to 5 kΩ and increasing R9 to 22 kΩ.

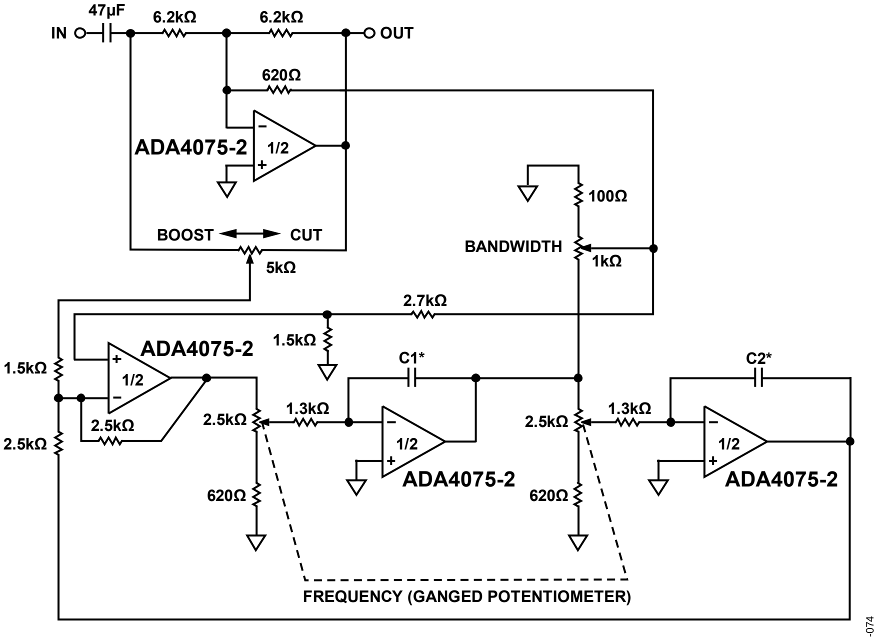


*A3 REDUCES THE DEGRADATION OF CMRR
(SEE THE BALANCED LINE RECEIVER SECTION FOR MORE DETAILS).

Figure 63. Balanced Line Receiver

LOW NOISE PARAMETRIC EQUALIZER

The circuit of Figure 64 is a reciprocal parametric equalizer yielding ±20 dB of cut or boost with variable bandwidth and frequency. The frequency control range is 6.9:1, with the geometric mean center frequency conveniently occurring at the midpoint of the potentiometer setting. The center frequency is equal to 48 Hz/Ct, where Ct is the value of C1 and C2 in microfarads. The bandwidth control adjusts the Q from 0.9 to about 11. The overall noise is setting dependent, but with all controls centered it is about −104 dBV in a 20 kHz bandwidth. Such a low noise level can obviate the need for a bypass switch in many applications.



*THE CENTER FREQUENCY IS AFFECTED BY THE VALUE OF C1 AND C2 (SEE THE LOW NOISE PARAMETRIC EQUALIZER SECTION FOR MORE DETAILS).

Figure 64. Low Noise Parametric Equalizer

SCHEMATIC

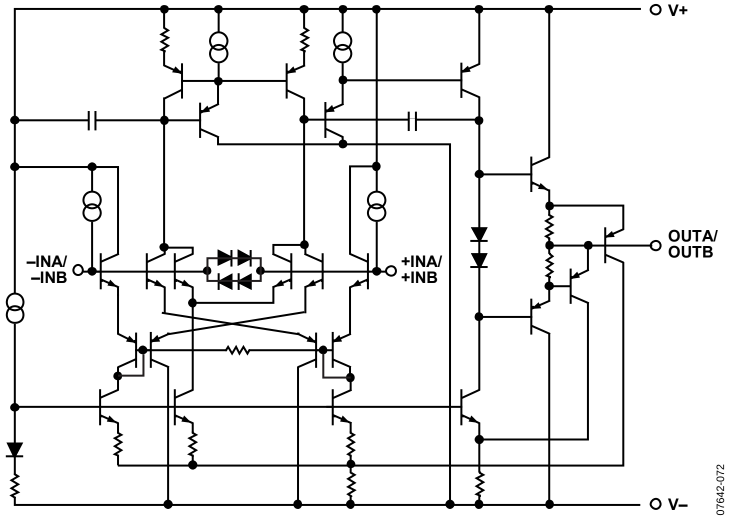
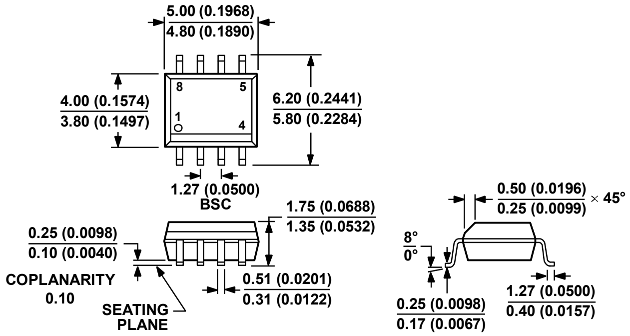


Figure 65. Simplified Schematic

OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-012-AA

CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

012407-A

Figure 66. 8-Lead Standard Small Outline Package [SOIC_N]
Narrow Body
(R-8)
Dimensions shown in millimeters and (inches)

ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
ADA4075-2ARZ[1]	−40°C to +125°C	8-Lead SOIC_N	R-8
ADA4075-2ARZ-R7[1]	−40°C to +125°C	8-Lead SOIC_N	R-8
ADA4075-2ARZ-RL[1]	−40°C to +125°C	8-Lead SOIC_N	R-8

[1] Z = RoHS Compliant Part.

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