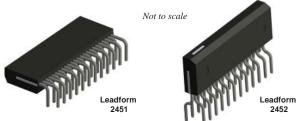




Features and Benefits

- Built-in pre-drive IC
- MOSFET power element
- Alleviate noise generation by adjusting an internal resistor
- CMOS compatible input (5 V)
- High-side gate driver using bootstrap circuit or floating power supply
- Built-in protection circuit for controlling power supply voltage drop (UVLO on VCC)
- Overcurrent protection (OCP), overcurrent limiting (OCL), and thermal shutdown (TSD)
- Output of fault signal during operation of protection circuit
- Output current 1.5 A
- Small SIP (SMA 24-pin)

Packages: Power SIP



Description

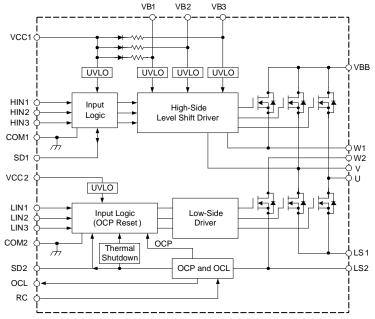
The SMA6862M inverter power module (IPM) device provides a robust, highly-integrated solution for optimally controlling 3-phase motor power inverter systems and variable speed control systems used in energy-conserving designs to drive motors of residential and commercial appliances. These ICs take 230 VAC input voltage, and 1.5 A (continuous) output current. They can withstand voltages of up to 500 V (MOSFET breakdown voltage).

The SMA6800M power package includes an IC with all of the necessary power elements (six MOSFETs), pre-driver ICs (two), and bootstrap diodes (three), needed to configure the main circuit of an inverter. This enables the main circuit of the inverter to be configured with fewer external components than traditional designs.

Applications include residential white goods (home applications) and commercial appliance motor control:

- · Air conditioner fan
- Refrigerator compressor
- · Dishwasher pump

Functional Block Diagram



- A. SD1, SD2 terminals are used for both input and output.
- B. SD1, SD2, and OCL terminals are open-collector output. RC terminal is open-drain output.
- C. Blanking Time (t_{blank}) is used in Overcurrent Limiting (OCL) and Overcurrent Protection (OCP). If the time exceeds the limit, the signal will be output (open-collector output turns on), and protection operation will start up.

Figure 1. Driver block diagram.

High Voltage 3-Phase Motor Driver

Selection Guide

		MOSFET Breakdown	Output Current		
Part Number	Packing	Voltage, V _{DSS} (min) (V)	Continuous, I _O (max) (A)	Pulsed, I _{OP} (max) (A)	
SMA6862M	18 pieces per tube	500	1.5	3	

Absolute Maximum Ratings, valid at $T_A = 25^{\circ}C$

Characteristic	Symbol	Remarks	Rating	Unit
MOSFET Breakdown Voltage	V _{DSS}	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	500	V
Logic Supply Voltage	V _{CC}	Between VCC and COM	20	V
Bootstrap Voltage	V _{BS}	Between VB and HS (U,V, and W phases)	20	V
Output Current, Continuous	Io		1.5	А
Output Current, Pulsed	I _{OP}	PW ≤ 100 µs, duty cycle = 1%	3	А
Input Voltage	V _{IN}	HINx and LINx pins	-0.5 to 7	V
Pull-up Voltage for Shutdown Pins	V _{SDX}	SDx pins	7	V
Pull-up Voltage for Overcurrent Limiting Pin	V _{OCL}		7	V
Allowable Power Dissipation	P _D	T _C = 25°C	28	W
Thermal Resistance (Junction to Case)	R _{eJC}	All elements operating	4.5	°C/W
Thermal Resistance (Junction to Case)	R _{θJA}	All elements operating	31.25	°C/W
Case Operating Temperature	T _{COP}		-20 to 100	°C
Junction Temperature (MOSFET)	TJ		150	°C
Storage Temperature	T _{stg}		-40 to 150	°C

Recommended Operating Conditions

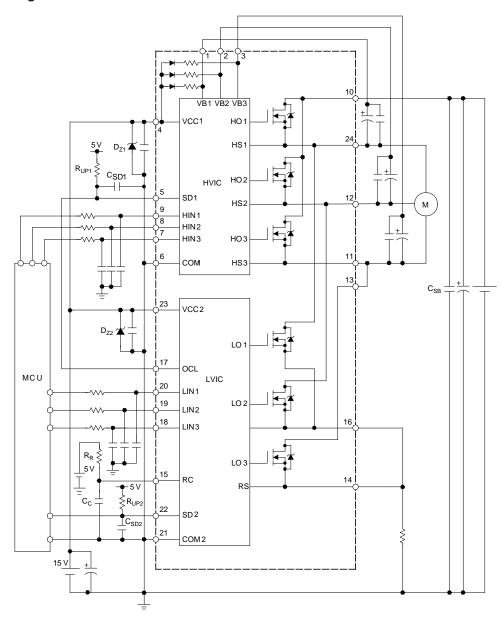
Characteristic	Symbol	Remarks	Min.	Тур.	Max.	Units
Main Supply Voltage	V_{BB}	Between VBB and LS	_	-	400	V
V _{BB} Snubber Capacitor	C _{SB}		0.01	-	0.1	μF
Logic Supply Voltage	V _{CC}	Between VCC and COM	13.5	15	16.5	V
Zener Voltage for VCCx Pins	Vz	Between VCC and COM	18	_	20	V
Pull-up Voltage	V _{SDx} , V _{OCL}		4.5	5	5.5	V
Pull-up Resistor SDx Pins	R _{UPX}		3.3	-	10	kΩ
Pull-up Resistor OCL Pin	R _{OCL(up)}		1	-	10	kΩ
Pull-up Resistor RC Pin	R _R		33	-	390	kΩ
Capacitor SDX and OCL Pins	C _{SDX} , C _{OCL}		1	-	10	nF
Capacitor RC Pin	C _C		1	-	4.7	nF
Dead Time	t _{dead}	$T_J = -20$ °C to 150°C	1.5	-	_	μs
Minimum Innut Dulge Width	I _{INMIN(on)}	$T_{J} = -20^{\circ}\text{C to } 150^{\circ}\text{C}$	0.5	-	-	μs
Minimum Input Pulse Width	I _{INMIN(off)}	$T_{J} = -20^{\circ}\text{C} \text{ to } 150^{\circ}\text{C}$	0.5	-	-	μs
Switching Frequency	f _{PWM}		_	_	20	kHz
Junction Temperature	TJ		_	-	125	°C

All performance characteristics given are typical values for circuit or system baseline design only and are at the nominal operating voltage and an ambient temperature, T_A , of 25°C, unless otherwise stated.





Typical Application Diagram



NOTE:

The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise susceptibility is necessary.





High Voltage 3-Phase Motor Driver

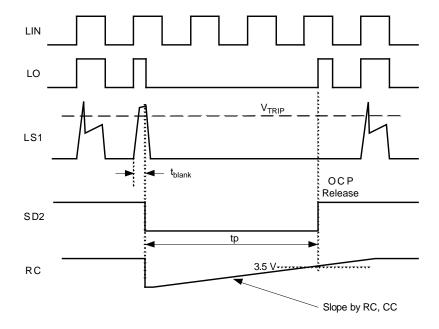
ELECTRICAL CHARACTERISTICS, valid at T_A =25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
Logic Supply Current	I _{cc}	$V_{CC} = 15 \text{ V}, T_{C} = -20 ^{\circ}\text{C} \text{ to } 125 ^{\circ}\text{C}$	_	4.2	7	mA
Bootstrap Supply Current	I _{BX}	V _{BX} = 15 V, V _{HIN} = 5 V, T _C = -20°C to 125°C	_	135	380	μΑ
January Valtage	V _{IH}	V _{CC} = 15 V	_	2.9	3.4	V
Input Voltage	V _{IL}	V _{CC} = 15 V	1.6	2.1	_	V
Input Voltage Hysteresis	V _{Ihys}	V _{CC} = 15 V	_	0.8	_	V
Input Current	I _{IN}	V _{IN} = 5 V	_	230	500	μΑ
	V _{UVHL}	High side, between VBx and U, V, or W	9.0	10.0	11.0	V
	V _{UVHH}		9.5	10.5	11.5	V
	V _{UVHhys}	High side, hysteresis	_	0.5	_	V
Undervoltage Lock Out	V _{UVLL}	, , , , , , , , , , , , , , , , , , ,	10.0	11.0	12.0	V
	V _{UVLH}	Low side, between VCC2 and COM2	10.5	11.5	12.5	V
	V _{UVLhys}	Low side, hysteresis	_	0.5	-	V
SDx and OCL Output Voltage	V _{SDX(on)} ,	$V_{SDX} = V_{OCL} = 5 \text{ V}, R_{UPX} = 3.3 \text{ k}\Omega$	_	_	0.6	V
Overtemperature DetectionThreshold	T _{DH}		120	135	150	°C
Temperature (Activation and	T _{DL}	V _{CC} = 15 V, high-side and low side	100	115	130	°C
Deactivation)	T _{Dhys}		_	20	-	°C
Overcurrent Protection Trip Voltage	V_{TRIP}	V _{CC} = 15 V, T _C = -20°C to 100°C	0.9	1.0	1.1	V
Overcurrent Limiting Reference Voltage	V _{LIM}	V _{CC} = 15 V, T _C = -20°C to 100°C	0.5035	0.53	0.5565	V
Overcurrent Protection Hold Time	t _p	$V_{RC} = 5 \text{ V}, R_R = 360 \text{ k}\Omega, C_C = 0.0047 \mu\text{F}$	_	2.0	-	ms
Blanking Time	t _{blank}	V _{CC} = 15 V	1.4	2.0	2.6	μs
Bootstrap Diode Leakage Current	I _{LBD}	V _R = 500 V	_	_	10	μΑ
Bootstrap Diode Forward Voltage	V _{FBD}	I _F = 0.15 A	_	1.1	1.3	V
Bootstrap Diode Recovery Time	t _{rrb}	$I_F / I_{RP} = 100 \text{ mA} / 100 \text{ mA}$	_	70	_	ns
Bootstrap Diode Series Resistor	R _{BD}		168	210	252	Ω
MOSFET Breakdown Voltage	V _{DSS}	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	500	_	_	V
MOSFET Leakage Current	I _{DSS}	V _{CC} = 15 V, V _{DS} = 500 V, V _{IN} = 0 V	_	_	100	μΑ
MOSFET On State Resistance	R _{DS(on)}	$V_{CC} = 15 \text{ V}, I_D = 1.5 \text{ A}, V_{IN} = 5 \text{ V}$	-	3.6	4.0	Ω
MOSFET Diode Forward Voltage	V _{SDF}	$V_{CC} = 15 \text{ V}, I_{SD} = 1.5 \text{ A}, V_{IN} = 0 \text{ V}$	_	1.1	1.5	V
	t _{dH(on)}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 1.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V}$	_	722	-	ns
	t _{rH}		_	40	-	ns
Switching Time, High Side	t _{rrH}		_	110	_	ns
	t _{dH(off)}		_	668	_	ns
	t _{fH}		_	22	_	ns
	t _{dL(on)}		_	596	-	ns
Switching Time, Low Side	t _{rL}		_	40	-	ns
	t _{rrL}		_	120	-	ns
	t _{dL(off)}		_	554	-	ns
	t _{fL}		_	22	_	ns





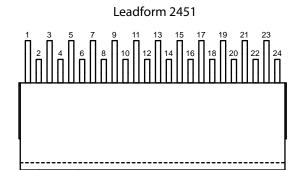
Low-Side Input/Output Timing Diagram

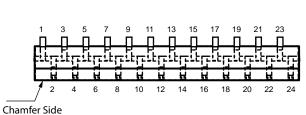






Pin-out Diagrams





Leadform 2452

Chamfer on Opposite Side

Terminal List Table

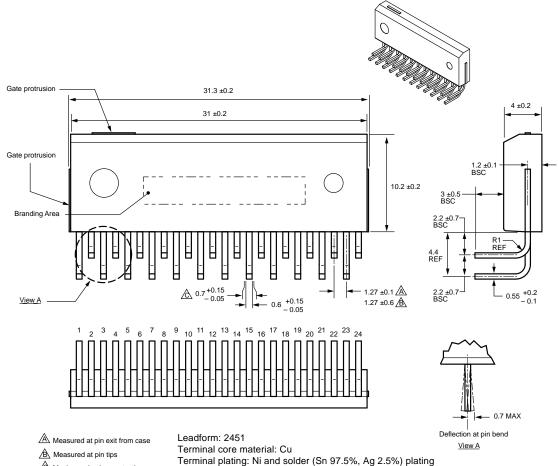
Number	Name	Function
1	VB1	High side bootstrap terminal (U phase)
2	VB2	High side bootstrap terminal (V phase)
3	VB3	High side bootstrap terminal (W phase)
4	VCC1	High side logic supply voltage
5	SD1	High side shutdown input and overtemperature fault signal output (open-collector output)
6	COM1	High side logic GND terminal
7	HIN3	High side input terminal (W phase)
8	HIN2	High side input terminal (V phase)
9	HIN1	High side input terminal (U phase)
10	VBB	Main supply voltage
11	W1	Output of W phase (connect to W2 externally)
12	V	Output of V phase
13	W2	Output of W phase (connect to W1 externally)
14	LS2	Low side emitter terminal (connect to LS1 externally)
15	RC	Overcurrent protection hold time adjustment input terminal and open-drain output
16	LS1	Low side emitter terminal (connect to LS2 externally)
17	OCL	Output for overcurrent limiting (open-collector output)
18	LIN3	Low side input terminal (W phase)
19	LIN2	Low side input terminal (V phase)
20	LIN1	Low side input terminal (U phase)
21	COM2	Low side GND terminal
22	SD2	Low side shutdown input and overtemperature and overcurrent fault signals output (open-collector output)
23	VCC2	Low side logic supply voltage
24	U	Output of U phase



Package Outline Drawing

Leadform 2451

Dual rows, 24 alternating pins; pins bent 90° for horizontal case mounting; pin #1 in outer row



A Maximum dambar protrusion

Case material: Epoxy resin

Dimensions in millimeters

Branding codes (exact appearance at manufacturer discretion):

1st line, lot: **YMDDT**

Where: Y is the last digit of the year of manufacture

M is the month (1 to 9, O, N, D)

DD is the date

T is the tracking letter

2nd line, type: SMA6862M



Leadframe plating Pb-free. Device composition complies with the RoHS directive.

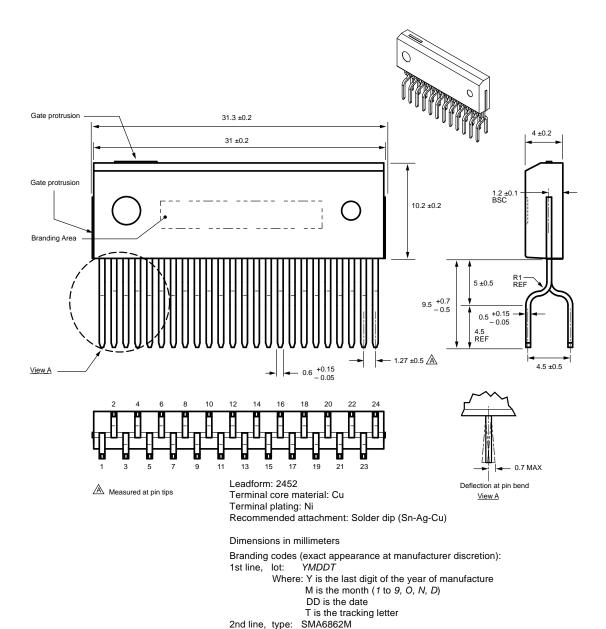




Package Outline Drawing

Leadform 2452

Dual rows, 24 alternating pins; vertical case mounting; pin #1 opposite chamfer side





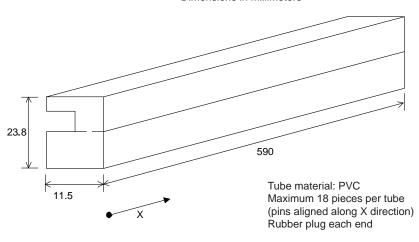
Leadframe plating Pb-free. Device composition complies with the RoHS directive.

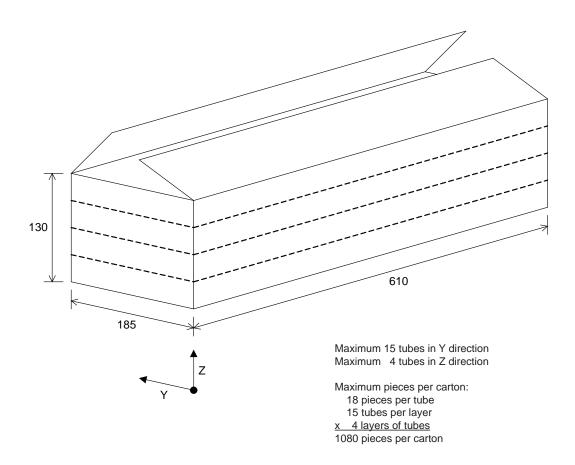




Packing Specification Leadform 2451

Dimensions in millimeters



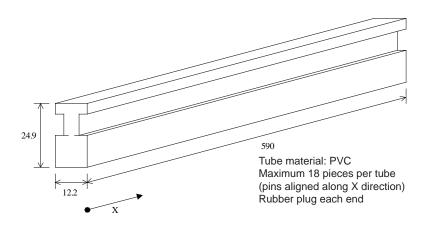


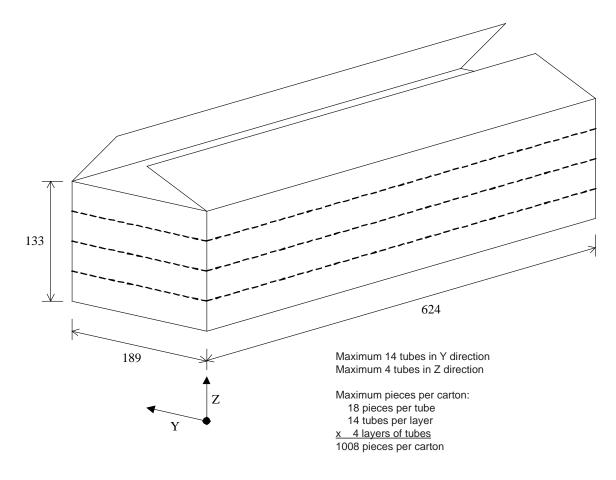




Packing Specification Leadforms 2452

Dimensions in millimeters









High Voltage 3-Phase Motor Driver

WARNING — These devices are designed to be operated at lethal voltages and energy levels. Circuit designs that embody these components must conform with applicable safety requirements. Precautions must be taken to prevent accidental contact with power-line potentials. Do not connect grounded test equipment.

The use of an isolation transformer is recommended during circuit development and breadboarding.

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following cautions.

Cautions for Storage

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40 to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of products that have been stored for a long time.

Cautions for Testing and Handling

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between adjacent products, and shorts to the heatsink.

Remarks About Using Silicone Grease with a Heatsink

- When silicone grease is used in mounting this product on a heatsink, it shall be applied evenly and thinly. If more silicone grease than required is applied, it may produce stress.
- Volatile-type silicone greases may permeate the product and produce cracks after long periods of time, resulting in reduced heat radiation effect, and possibly shortening the lifetime of the product
- Our recommended silicone greases for heat radiation purposes, which will not cause any adverse effect on the product life, are indicated below:

Type		Suppliers
	G746	Shin-Etsu Chemical Co., Ltd.
	YG6260	Momentive Performance Materials, Inc.
	SC102	Dow Corning Toray Silicone Co., Ltd.

Heatsink Mounting Method

Torque When Tightening Mounting Screws. The recommended tightening torque for this product package type is: 58.8 to 78.4 N•cm (6.0 to 8.0 kgf•cm).

Soldering

 When soldering the products, please be sure to minimize the working time, within the following limits:

260±5°C 10 s 380±5°C 5 s

 Soldering iron should be at a distance of at least 1.5 mm from the body of the products

Electrostatic Discharge

- When handling the products, operator must be grounded.
 Grounded wrist straps worn should have at least 1 MΩ of resistance to ground to prevent shock hazard.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in other to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in our shipping containers or conductive containers, or be wrapped in aluminum foil.





High Voltage 3-Phase Motor Driver

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