

# (2.5 Cycle Read Latency)

# Advanced Information May 2009

#### **Features**

- 2M x 36 or 4M x 18.
- On-chip delay-locked loop (DLL) for wide data valid window.
- · Common data input/output bus.
- Synchronous pipeline read with self-timed late write operation.
- Double data rate (DDR-IIP) interface for read and write input ports.
- Fixed 2-bit burst for read and write operations.
- · Clock stop support.
- Two input clocks (K and K) for address and control registering at rising edges only.
- Industrial temperature available upon request.

- Two echo clocks (CQ and CQ) that are delivered simultaneously with data.
- +1.8V core power supply and 1.5, 1.8V V<sub>DDQ</sub>, used with 0.75, 0.9V V<sub>RFF</sub>.
- HSTL input and output levels.
- Registered addresses, write and read controls, byte writes, data in, and data outputs.
- · Full data coherency.
- Boundary scan using limited set of JTAG 1149.1 functions.
- · Byte write capability.
- · Fine ball grid array (FBGA) package
  - 15mm x 17mm body size
  - 1mm pitch
  - 165-ball (11 x 15) array
- Programmable impedance output drivers via 5x user-supplied precision resistor.

### **Description**

The 72Mb IS61DDPB22M36 and IS61DDPB24M18 are synchronous, high-performance CMOS static random access memory (SRAM) devices. These SRAMs have a common I/O bus. The rising edge of K clock initiates the read/write operation, and all internal operations are self-timed.

Refer to the *Timing Reference Diagram for Truth Table* on page 8 for a description of the basic operations of these DDR-IIP (Burst of 2) CIO SRAMs.

The input addresses are registered on all rising edges of the K clock. The DQ bus operates at double data rate for reads and writes. The following are registered internally on the rising edge of the K clock:

- · Read and write addresses
- Address load
- Read/write enable Byte writes
- Data-in
- Data-out

The following are registered on the rising edge of the  $\overline{K}$  clock:

- Byte writes
- Data-in for second burst addresses
- Data-out

Byte writes can change with the corresponding data-in to enable or disable writes on a per-byte basis. An internal write buffer enables the data-ins to be registered one cycle later than the write address. The first data-in burst is clocked with the rising edge of the next K clock, and the second burst is timed to the following rising edge of the  $\overline{\rm K}$  clock.

During the burst read operation, at the first burst the data-outs are updated from output registers off the second rising edge of the  $\overline{K}$  clock (2.5 cycles later). At the second burst, the data-outs are updated with the fourth rising edge of the corresponding K clock (see page 8).

The device is operated with a single +1.8V power supply and is compatible with HSTL I/O interfaces.



### x36 FBGA Pinout (Top View)

	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	NC/SA*	SA	R/W	$\overline{\text{BW}}_2$	K	$\overline{BW}_1$	LD	SA	SA	CQ
В	NC	DQ27	DQ18	SA	$\overline{BW}_3$	K	$\overline{BW}_0$	SA	NC	NC	DQ8
С	NC	NC	DQ28	$V_{SS}$	SA	NC	SA	$V_{SS}$	NC	DQ17	DQ7
D	NC	DQ29	DQ19	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	NC	NC	DQ16
Е	NC	NC	DQ20	$V_{DDQ}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{DDQ}$	NC	DQ15	DQ6
F	NC	DQ30	DQ21	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	NC	DQ5
G	NC	DQ31	DQ22	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	NC	DQ14
Н	Doff	$V_{REF}$	$V_{DDQ}$	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	$V_{\mathrm{DDQ}}$	$V_{REF}$	ZQ
J	NC	NC	DQ32	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	DQ13	DQ4
K	NC	NC	DQ23	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	DQ12	DQ3
L	NC	DQ33	DQ24	$V_{DDQ}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{DDQ}$	NC	NC	DQ2
М	NC	NC	DQ34	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	NC	DQ11	DQ1
N	NC	DQ35	DQ25	$V_{SS}$	SA	SA	SA	$V_{SS}$	NC	NC	DQ10
Р	NC	NC	DQ26	SA	SA	NC	SA	SA	NC	DQ9	DQ0
R	TDO	TCK	SA	SA	SA	NC	SA	SA	SA	TMS	TDI

<sup>\*</sup> The following pins are reserved for higher densities: 2A for 144Mb

### x18 FBGA Pinout (Top View)

	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	SA	SA	R/W	$\overline{BW}_1$	K	NC/SA*	LD	SA	SA	CQ
В	NC	DQ9	NC	SA	NC/SA*	K	$\overline{BW}_0$	SA	NC	NC	DQ8
С	NC	NC	NC	$V_{SS}$	SA	NC	SA	$V_{SS}$	NC	DQ7	NC
D	NC	NC	DQ10	$V_{SS}$	V <sub>SS</sub>	$V_{SS}$	$V_{SS}$	$V_{SS}$	NC	NC	NC
Е	NC	NC	DQ11	$V_{DDQ}$	$V_{SS}$	$V_{SS}$	$V_{SS}$	$V_{DDQ}$	NC	NC	DQ6
F	NC	DQ12	NC	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	NC	DQ5
G	NC	NC	DQ13	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	NC	NC
Н	Doff	$V_{REF}$	$V_{DDQ}$	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	$V_{DDQ}$	$V_{REF}$	ZQ
J	NC	NC	NC	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	DQ4	NC
K	NC	NC	DQ14	$V_{DDQ}$	$V_{DD}$	$V_{SS}$	$V_{DD}$	$V_{DDQ}$	NC	NC	DQ3
L	NC	DQ15	NC	$V_{DDQ}$	$V_{SS}$	$V_{SS}$	V <sub>SS</sub>	$V_{DDQ}$	NC	NC	DQ2
М	NC	NC	NC	$V_{SS}$	$V_{SS}$	$V_{SS}$	V <sub>SS</sub>	$V_{SS}$	NC	DQ1	NC
N	NC	NC	DQ16	$V_{SS}$	SA	SA	SA	$V_{SS}$	NC	NC	NC
Р	NC	NC	DQ17	SA	SA	NC	SA	SA	NC	NC	DQ0
R	TDO	TCK	SA	SA	SA	NC	SA	SA	SA	TMS	TDI

<sup>\*</sup> The following pin is reserved for higher densities: 7A for 144Mb, 5B for 288Mb.

BW<sub>0</sub> controls writes to DQ0–DQ8; BW<sub>1</sub> controls writes to DQ9–DQ17; BW<sub>2</sub> controls writes to DQ18–DQ26; BW<sub>3</sub> controls writes to DQ27–DQ35.

<sup>•</sup>  $\overline{BW}_0$  controls writes to DQ0–DQ8;  $\overline{BW}_1$  controls writes to DQ9–DQ17

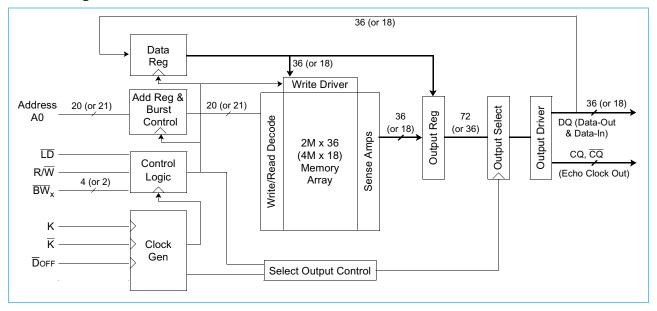


# **Pin Description**

Symbol	Pin Number	Description
K, $\overline{K}$	6B, 6A	Input clock.
CQ, CQ	11A, 1A	Output echo clock.
Doff	1H	DLL disable when low.
SA	3A, 9A, 10A, 4B, 8B, 5C, 7C, 5N, 6N, 7N, 4P, 5P, 7P, 8P, 3R, 4R, 5R, 7R,8R, 9R	2M x 36 address inputs.
SA	2A, 3A, 9A, 10A, 4B, 8B, 5C, 7C, 5N, 6N, 7N, 4P, 5P, 7P, 8P, 3R, 4R, 5R, 7R, 8R, 9R	4M x 18 address inputs.
DQ0-DQ8 DQ9-DQ17 DQ18-DQ26 DQ27-DQ35	11P, 11M, 11L, 11K, 11J, 11F, 11E, 11C, 11B 10P, 11N, 10M, 10K, 10J, 11G, 10E, 11D, 10C 3B, 3D, 3E, 3F, 3G, 3K, 3L, 3N, 3P 2B, 3C, 2D, 2F, 2G, 3J, 2L, 3M, 2N	2M x 36 DQ pins
DQ0–DQ8 DQ9–DQ17	11P, 10M, 11L, 11K, 10J, 11F, 11E, 10C, 11B 2B, 3D, 3E, 2F, 3G, 3K, 2L, 3N, 3P	4M x 18 DQ pins
R/W	4A	Read/write control. Read when active high.
LD	8A	Synchronizes load. Loads new address when low.
$\overline{BW}_{0,} \overline{BW}_{1,} \overline{BW}_{2,} \overline{BW}_{3}$	7B, 7A, 5A,5B	2M x 36 byte write control, active low.
$\overline{BW}_{0,} \overline{BW}_{1}$	7B, 5A	4M x 18 byte write control, active low.
V <sub>REF</sub>	2H, 10H	Input reference level.
$V_{DD}$	5F, 7F, 5G, 7G, 5H, 7H, 5J, 7J, 5K, 7K	Power supply.
$V_{DDQ}$	4E,8E,4F,8F,4G,8G,3H,4H,8H,9H,4J,8J,4K,8K,4L,8L	Output power supply.
V <sub>SS</sub>	4C, 8C, 4D, 5D, 6D, 7D, 8D, 5E, 6E, 7E, 6F, 6G, 6H, 6J, 6K, 5L, 6L, 7L, 4M, 5M, 6M, 7M, 8M, 4N, 8N	Ground
ZQ	11H	Output driver impedance control.
TMS, TDI, TCK	10R, 11R, 2R	IEEE 1149.1 test inputs (1.8V LVTTL levels).
TDO	1R	IEEE 1149.1 test output (1.8V LVTTL level).
NC	2A, 1B, 9B, 10B, 1C, 2C, 9C, 1D, 9D, 10D, 1E, 2E, 9E, 1F, 9F, 10F, 1G, 9G, 10G, 1J, 2J, 9J, 1K, 2K, 9K, 1L, 9L, 10L, 1M, 2M, 9M, 1N, 9N, 10N, 1P, 2P, 9P, 6R, 6P, 6C	x36 Configuration
NC	7A, 1B, 3B, 5B, 9B, 10B, 1C, 2C, 3C, 9C, 11C, 1D, 2D, 9D, 10D, 11D, 1E, 2E, 9E, 10E, 1F, 3F, 9F, 10F, 1G, 2G, 9G, 10G, 11G, 1J, 2J, 3J, 9J, 11J, 1K, 2K, 9K, 10K, 1L, 3L, 9L, 10L, 1M, 2M, 3M, 9M, 11M, 1N, 2N, 9N, 10N, 11N, 1P, 2P, 9P, 10P, 6R, 6P, 6C	x18 Configuration



#### **Block Diagram**



#### **SRAM Features**

#### **Read Operations**

The SRAM operates continuously in a burst-of-two mode. Read cycles are started by registering  $R\overline{W}$  in active high state at the rising edge of the K clock. The K and  $\overline{K}$  clocks are also used to control the timing to the outputs. The data corresponding to the first address is clocked 2.5 cycles later by the rising edge of the  $\overline{K}$  clock. The data corresponding to the second burst is clocked 3 cycles later by the following rising edge of the K clock. A set of free-running echo clocks, CQ and  $\overline{CQ}$ , are produced internally with timings identical to the data-outs. The echo clocks can be used as data capture clocks by the receiver device.

Whenever  $\overline{\text{LD}}$  is low, a new address is registered at the rising edge of the K clock. A NOP operation ( $\overline{\text{LD}}$  is high) does not terminate the previous read. The output drivers disable automatically to a high state.

#### **Write Operations**

Write operations can also be initiated at every rising edge of the K clock whenever  $R/\overline{W}$  is low. The write address is also registered at that time. When the address needs to change,  $\overline{LD}$  needs to be low simultaneously to be registered by the rising edge of K. Again, the write always occurs in bursts of two.

Because of its common I/O architecture, the data bus must be tri-stated at least one cycle before the new data-in is presented at the DQ bus.

The write data is provided in a 'late write' mode; that is, the data-in corresponding to the first address of the burst, is presented one cycle later or at the rising edge of the next K clock. The data-in corresponding to the second write burst address follows next, registered by the rising edge of  $\overline{K}$ .



The data-in provided for writing is initially kept in write buffers. The information on these buffers is written into the array on the following write cycle. A read cycle to the last write address produces data from the write buffers. Similarly, a read address followed by the same write address produces the latest write data. The SRAM maintains data coherency.

During a write, the byte writes independently control which byte of any of the two burst addresses is written (see *X18/X36 Write Truth Tables* on page 9 and *Timing Reference Diagram for Truth Table* on page 8).

Whenever a write is disabled  $(R/\overline{W})$  is high at the rising edge of K), data is not written into the memory.

#### **RQ** Programmable Impedance

An external resistor, RQ, must be connected between the ZQ pin on the SRAM and  $V_{SS}$  to enable the SRAM to adjust its output driver impedance. The value of RQ must be 5x the value of the intended line impedance driven by the SRAM. For example, an RQ of  $250\Omega$  results in a driver impedance of  $50\Omega$ . The allowable range of RQ to guarantee impedance matching is between  $175\Omega$  and  $350\Omega$ , with the tolerance described in *Programmable Impedance Output Driver DC Electrical Characteristics* on page 13. The RQ resistor should be placed less than two inches away from the ZQ ball on the SRAM module. The capacitance of the loaded ZQ trace must be less than 3 pF.

The ZQ pin can also be directly connected to  $V_{DDQ}$  to obtain a minimum impedance setting. ZQ must never be connected to  $V_{SS}$ .

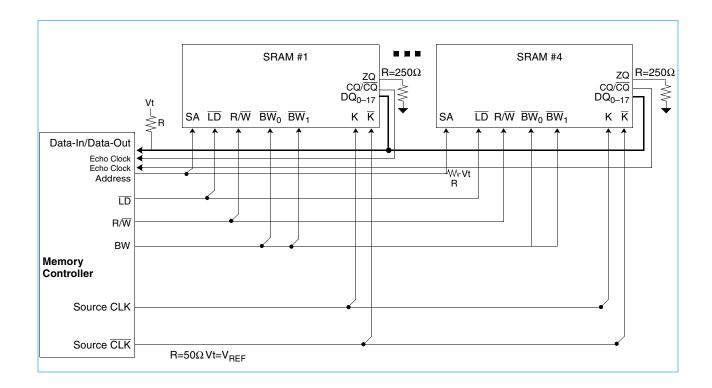
#### **Programmable Impedance and Power-Up Requirements**

Periodic readjustment of the output driver impedance is necessary as the impedance is greatly affected by drifts in supply voltage and temperature. At power-up, the driver impedance is in the middle of allowable impedances values. The final impedance value is achieved within 2048 clock cycles.



### **Application Example**

The following figure depicts an implementation of four 4M x 18 DDR-IIP SRAMs with common I/Os.



### **Power-Up and Power-Down Sequences**

The following sequence is used for power-up:

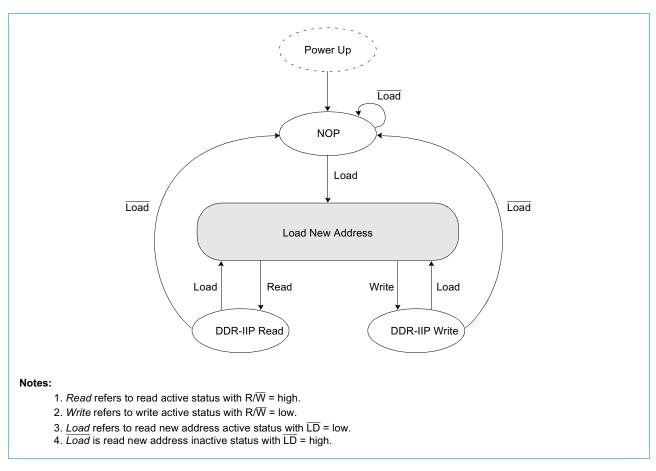
- 1. The power supply inputs must be applied in the following order while keeping Doff in LOW logic state:
  - 1) VDD
  - 2) VDDQ
  - 3) VREF
- 2. Start applying stable clock inputs  $(K, \overline{K}, C, \text{ and } \overline{C})$ .
- 3. After clock signals have stabilized, change Doff to HIGH logic state.
- 4. Once the Doff is switched to HIGH logic state, wait an additional 1024 clock cycles to lock the DLL.

#### NOTES:

- 1. The power-down sequence must be done in reverse of the power-up sequence.
- 2. VDDQ can be allowed to exceed VDD by no more than 0.6V.
- 3. VREF can be applied concurrently with VDDQ.



### **State Diagram**



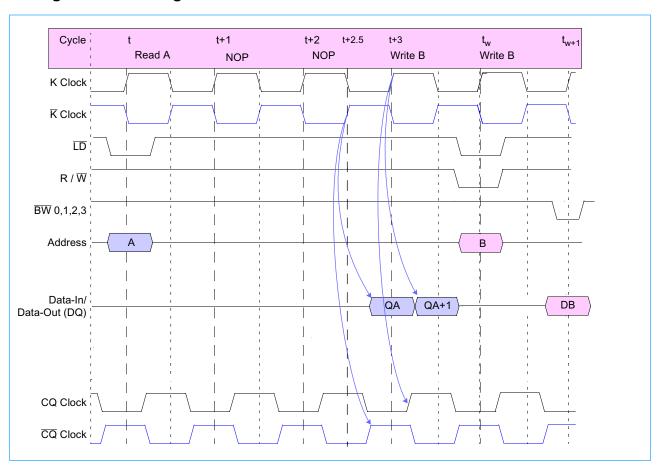
The *Timing Reference Diagram for Truth Table* on page 8 is helpful in understanding the clock and write truth tables, as it shows the cycle relationship between clocks, address, data in, data out, and controls. All read and write commands are issued at the beginning of cycle "t".

### **Linear Burst Sequence Table**

Burst Sequence	SA <sub>0</sub>
First Address	1
Second Address	0



### **Timing Reference Diagram for Truth Table**



### **Clock Truth Table** (Use the following table with the *Timing Reference Diagram for Truth Table*.)

Mode	Clock	Cor	ntrols	Data-Out/Data-In		
Wode	K	<u>LD</u>	R/W	Q <sub>A</sub> / D <sub>B</sub>	Q <sub>A+1</sub> / D <sub>B+1</sub>	
Stop Clock	Stop	Х	Х	Previous state	Previous state	
No Operation (NOP)	L H	Н	Н	High-Z	High-Z	
Read A	L H	L	Х	D out at <del>K</del> (t + 2.5)	D out at K (t + 3)	
Write B	L H	X	L	D <sub>B</sub> (t <sub>W</sub> + 1)	D <sub>B</sub> (t <sub>W</sub> + 1.5)	

#### Notes:

- 1. The internal burst counter is always fixed as two-bit.
- 2. X = don't care; H = logic "1"; L = logic "0".
- 3. A read operation is started when control signal  $R/\overline{W}$  is active high.
- 4. A write operation is started when control signal  $R/\overline{W}$  is active low.
- 5. Before entering into the stop clock, all pending read and write commands must be completed.
- 6. For timing definitions, refer to the *AC Characteristics* on page 15. Signals must have AC specifications at timings indicated in parenthesis with respect to switching clocks K and  $\overline{K}$ .



# **X36 Write Truth Table** Use the following table with the *Timing Reference Diagram for Truth Table* on page 8.

Operation	K (t <sub>w</sub> )	(t <sub>w</sub> + 0.5)	$\overline{BW}_0$	BW₁	BW₂	BW₃	D <sub>B</sub>	D <sub>B+1</sub>
Write Byte 0	L→H		L	Н	Н	Н	D0-8 (t <sub>w</sub> + 1)	
Write Byte 1	L→H		Н	L	Н	Н	D9-17 (t <sub>w</sub> + 1)	
Write Byte 2	L→H		Н	Н	L	Н	D18-26 (t <sub>w</sub> + 1)	
Write Byte 3	L→H		Н	Н	Н	L	D27-35 (t <sub>w</sub> + 1)	
Write All Bytes	L→H		L	L	L	L	D0-35 (t <sub>w</sub> + 1)	
Abort Write	L→H		Н	Н	Н	Н	Don't care	
Write Byte 0		L→H	L	Н	Н	Н		D0-8 (t <sub>w</sub> + 1.5)
Write Byte 1		L→H	Н	L	Н	Н		D9-17 (t <sub>w+1.5</sub> )
Write Byte 2		L→H	Н	Н	L	Н		D18-26 (t <sub>w+1.5</sub> )
Write Byte 3		L→H	Н	Н	Н	L		D27-35 (t <sub>w+1.5</sub> )
Write All Bytes		L→H	L	L	L	L		D0-35 (t <sub>w+1.5</sub> )
Abort Write		L→H	Н	Н	Н	Н		Don't care

#### Notes;

- 1. For all cases.  $R/\overline{W}$  must be active low during the rising edge of K occurring at time  $t_{W}\!.$
- 2. For timing definitions, refer to the *AC Characteristics* on page 15. Signals must have AC specifications with respect to switching clocks K and  $\overline{K}$ .

### X18 Write Truth Table (Use this table with the Timing Reference Diagram for Truth Table on page 8.)

Operation	K (t <sub>w</sub> )	<del>K</del> (t <sub>w+0.5</sub> )	BW₀	BW₁	D <sub>B</sub>	D <sub>B+1</sub>
Write Byte 0 on B	L→H		L	Н	D0-8 (t <sub>w</sub> + 1)	
Write Byte 1 on B	L→H		Н	L	D9–17 (t <sub>w</sub> + 1)	
Write All Bytes on B	L→H		L	L	D0-17 (t <sub>w</sub> + 1)	
Abort Write on B	L→H		Н	Н	Don't care	
Write Byte 1 on B+1		L→H	L	Н		D0-8 (t <sub>w</sub> + 1.5)
Write Byte 2 on B+1		L→H	Н	L		D9-17 (t <sub>w</sub> + 1.5)
Write All Bytes on B+1		L→H	L	L		D0-17 (t <sub>w</sub> + 1.5)
Abort Write on B+1		L→H	Н	Н		Don't care

#### Notes

- 1. Refer to Timing Reference Diagram for Truth Table on page 8. Cycle time starts at n and is referenced to the K clock.
- 2. For all cases, R/W must be active low during the rising edge of K occurring at tw-
- 3. For timing definitions, refer to the AC Characteristics on page 15. Signals must have AC specs with respect to switching clocks K and K.



# **Absolute Maximum Ratings**

Item	Symbol	Rating	Units
Power supply voltage	V <sub>DD</sub>	-0.5 to 2.9	V
Output power supply voltage	$V_{\mathrm{DDQ}}$	-0.5 to 2.9	V
Input voltage	V <sub>IN</sub>	-0.5 to VDD+0.3	V
Data out voltage	V <sub>DOUT</sub>	-0.5 to 2.6	V
Operating temperature	T <sub>A</sub>	0 to 70	°C
Junction temperature	TJ	110	°C
Storage temperature	T <sub>STG</sub>	-55 to +125	°C

**Note:** Stresses greater than those listed in this table can cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this datasheet is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

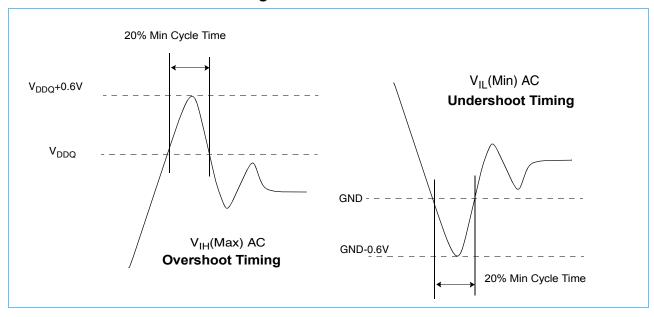


## **Recommended DC Operating Conditions** $(T_A = 0 \text{ to } +70^{\circ} \text{ C})$

Parameter	Symbol	Minimum	Typical	Maximum	Units	Notes
Supply voltage	$V_{DD}$	1.8 - 5%		1.8 + 5%	V	1
Output driver supply voltage	$V_{\mathrm{DDQ}}$	1.4		1.9	V	1
Input high voltage	V <sub>IH</sub>	V <sub>REF</sub> +0.1		V <sub>DDQ</sub> + 0.2	V	1, 2
Input low voltage	$V_{IL}$	-0.2		V <sub>REF</sub> - 0.1	V	1, 3
Input reference voltage	$V_{REF}$	0.68		0.95	V	1, 5
Clocks signal voltage	V <sub>IN - CLK</sub>	-0.2		V <sub>DDQ</sub> + 0.2	V	1, 4

- 1. All voltages are referenced to  $\rm V_{SS}.$  All  $\rm V_{DD},\,V_{DDQ},$  and  $\rm V_{SS}$  pins must be connected.
- 2. V<sub>IH</sub>(Max) AC = See Overshoot and Undershoot Timings.
- 3. V<sub>IL</sub>(Min) AC = See *Overshoot and Undershoot Timings*.
- 4.  $V_{IN-CLK}$  specifies the maximum allowable DC excursions of each clock (K and  $\overline{K}$ ).
- 5. Peak-to-peak AC component superimposed on  $V_{REF}$  may not exceed 5% of  $V_{REF}$

## **Overshoot and Undershoot Timings**



### **PBGA Thermal Characteristics**

Item	Symbol	Rating	Units
Thermal resistance junction to ambient (airflow = 1m/s)	ROJA	TBD	° C/W
Thermal resistance junction to case	ROJC	TBD	° C/W
Thermal resistance junction to pins	R⊛JB	TBD	° C/W



# **Capacitance** $(T_A = 0 \text{ to } +70^{\circ} \text{ C}, V_{DD} = 1.8 \text{V} -5\%, +5\%, f = 1 \text{MHz})$

Parameter	Symbol	Test Condition	Maximum	Units
Input capacitance	C <sub>IN</sub>	V <sub>IN</sub> = 0V	4	pF
Data-in/Out capacitance (DQ0-DQ35)	C <sub>DQ</sub>	V <sub>DIN</sub> = 0V	4	pF
Clocks Capacitance (K and $\overline{K}$ )	C <sub>CLK</sub>	V <sub>CLK</sub> = 0V	4	pF

# **DC Electrical Characteristics** ( $T_A = 0 \text{ to } + 70 \text{ C}, V_{DD} = 1.8 \text{V} - 5\%, +5\%$ )

Parameter	Symbol	Minimum	Maximum	Units	Notes
x36 average power supply operating current $(I_{OUT} = 0, V_{IN} = V_{IH} \text{ or } V_{IL})$	I <sub>DD33</sub> I <sub>DD40</sub> I <sub>DD50</sub>	=	600 550 500	mA	1, 3
x18 average power supply operating current $(I_{OUT} = 0, V_{IN} = V_{IH} \text{ or } V_{IL})$	I <sub>DD33</sub> I <sub>DD40</sub> I <sub>DD50</sub>	=	600 550 500	mA	1, 3
Power supply standby current $(\overline{R} = V_{IH}, \overline{W} = V_{IH}. All other inputs = V_{IH} or V_{IH}, I_{IH} = 0)$	I <sub>SBSS</sub>	_	200	mA	1
Input leakage current, any input (except JTAG) (V <sub>IN</sub> = V <sub>SS</sub> or V <sub>DD</sub> )	I <sub>LI</sub>	-2	+2	uA	
Output leakage current (V <sub>OUT</sub> = V <sub>SS</sub> or V <sub>DDQ</sub> , Q in High-Z)	I <sub>LO</sub>	-2	+2	uA	
Output "high" level voltage (I <sub>OH</sub> = -6mA)	V <sub>OH</sub>	V <sub>DDQ</sub> 4	$V_{DDQ}$	V	2, 4
Output "low" level voltage (I <sub>OL</sub> = +6mA)	V <sub>OL</sub>	$V_{SS}$	V <sub>SS</sub> +.4	V	2, 4
JTAG leakage current (V <sub>IN</sub> = V <sub>SS</sub> or V <sub>DD</sub> )	I <sub>LIJTAG</sub>	-100	+100	uA	5

- 1.  $I_{OUT}$  = chip output current.
- 2. Minimum impedance output driver.
- 3. The numeric suffix indicates the part operating at speed, as indicated in AC Characteristics on page 15.
- 4. JEDEC Standard JESD8-6 Class 1 compatible.
- 5. For JTAG inputs only.
- 6. Currents are estimates only and need to be verified.

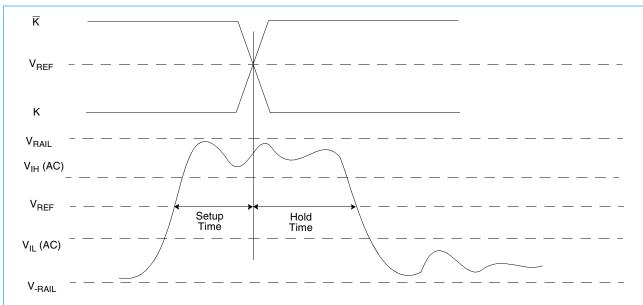


## **Typical AC Input Characteristics**

Item	Symbol	Minimum	Maximum	Notes
AC input logic high	V <sub>IH</sub> (ac)	V <sub>REF</sub> + 0.2		1, 2, 3, 4
AC input logic low	V <sub>IL</sub> (ac)		V <sub>REF</sub> - 0.2	1, 2, 3, 4
Clock input logic high (K, $\overline{K}$ )	V <sub>IH-CLK</sub> (ac)	V <sub>REF</sub> + 0.2		1, 2, 3
Clock input logic low (K, $\overline{\mathrm{K}}$ )	V <sub>IL-CLK</sub> (ac)		V <sub>REF</sub> - 0.2	1, 2, 3

- 1. The peak-to-peak AC component superimposed on  $V_{\rm REF}$  may not exceed 5% of the DC component of  $V_{\rm REF}$ .
- 2. Performance is a function of  $V_{IH}$  and  $V_{IL}$  levels to clock inputs.
- 3. See the AC Input Definition diagram.
- 4. See the AC Input Definition diagram. The signals should swing monotonically with no steps rail-to-rail with input signals never ringing back past VIH (AC) and VIL (AC) during the input setup and input hold window. VIH (AC) and VIL (AC) are used for timing purposes only.

## **AC Input Definition**



# **Programmable Impedance Output Driver DC Electrical Characteristics**

 $(T_A = 0 \text{ to } +70^{\circ} \text{ C}, V_{DD} = 1.8 \text{ V} -5\%, +5\%, V_{DDQ} = 1.5, 1.8 \text{ V})$ 

Parameter	Symbol	Minimum	Maximum	Units	Notes
Output "high" level voltage	V <sub>OH</sub>	V <sub>DDQ</sub> / 2	$V_{DDQ}$	V	1, 3
Output "low" level voltage	$V_{OL}$	$V_{SS}$	V <sub>DDQ</sub> / 2	V	2, 3

1. 
$$I_{OH} = \left(\frac{\mathrm{VDDQ}}{2}\right) / \left(\frac{\mathrm{RQ}}{5}\right) \pm 15\%$$
 @  $V_{OH} = V_{DDQ}$  / 2 For:  $175\Omega \leq \mathrm{RQ} \leq 350\Omega$ 

2. 
$$I_{OL} = \left(\frac{VDDQ}{2}\right) / \left(\frac{RQ}{5}\right) \pm 15\%$$
 @  $V_{OL} = V_{DDQ} / 2$  For:  $175\Omega \le RQ \le 350\Omega$ 

3. Parameter tested with RQ =  $250\Omega$  and  $V_{DDQ}$  = 1.5V.

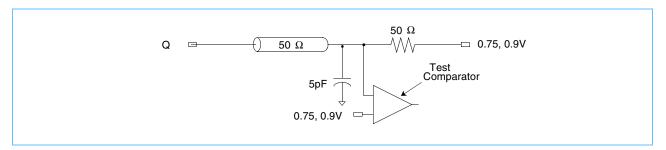


# **AC Test Conditions** ( $T_A = 0 \text{ to } +70^{\circ} \text{ C}, V_{DD} = 1.8 \text{ V} -5\%, +5\%, V_{DDQ} = 1.5, 1.8 \text{ V}$ )

Parameter	Symbol	Conditions	Units	Notes
Output driver supply voltage	$V_{DDQ}$	1.5, 1.8	V	
Input high level	V <sub>IH</sub>	V <sub>REF</sub> +0.5	V	
Input Low Level	$V_{IL}$	V <sub>REF</sub> -0.5	V	
Input reference voltage	$V_{REF}$	0.75, 0.9	V	
Input rise time	T <sub>R</sub>	0.35	ns	
Input fall time	T <sub>F</sub>	0.35	ns	
Output timing reference level		$V_{REF}$	V	
Clocks reference level		V <sub>REF</sub>	V	
Output load conditions				1, 2

<sup>1.</sup> See AC Test Loading.

# **AC Test Loading**



<sup>2.</sup> Parameter tested with RQ =  $250\Omega\,\text{and}\,\,\text{V}_{DDQ}$  = 1.5V.



# AC CHARACTERISTICS (Vdd = $1.8V \pm 0.1V$ , $T_A = 0$ °C to 70 °C)

						DDF	RIIP				
ISSI Parameter	Description	40	00	37	75	333 300		00	unit	note	
		min	max	min	max	min	max	min	max		
tKHKH	K Clock Cycle Time	2.50	7.50	2.66	7.50	3.00	7.50	3.30	7.50	ns	
tKHKL	Input Clock (K/K) HIGH	0.40		0.40		0.40		0.40		tKHKH	
tKLKH	Input Clock (K/K) LOW	0.40		0.40		0.40		0.40		tKHKH	
tKĦKH	K Clock Rise to K Clock Rise (rising edge to rising	1.06		1.13		1.28		1.40		ns	
	edge)										
Setup Times											
tAVKH	Address Setup to K Clock Rise	0.40		0.40		0.40		0.40		ns	2
tIVKH	Control Setup to K Clock Rise (R, W)	0.40		0.40		0.40		0.40		ns	2
tIVKH	Double Data Rate Control Setup to Clock (K, $\overline{K}$ )	0.28		0.28		0.28		0.28		ns	
	Rise $(\overline{BWS}_0, \overline{BWS}_1, \overline{BWS}_2, \overline{BWS}_3)$										2
tDVKH	Data Input Setup to Clock (K/K) Rise	0.28		0.28		0.28		0.28		ns	2
Hold Times											
tKHAX	Address Hold after K Clock Rise	0.40		0.40		0.40		0.40		ns	
tKHIX	Control Hold after K Clock Rise	0.40		0.40		0.40		0.40		ns	
tKHIX	Double Data Rate Control Hold after Clock (K/K)	0.28		0.28		0.28		0.28		ns	
	Rise $\overline{(BWS_0, \overline{BWS}_1, \overline{BWS}_2, \overline{BWS}_3)}$										
tKHDX	Data Input Hold after Clock (K/K) Rise	0.28		0.28		0.28		0.28		ns	
Output Times											
tCHQV	K/K Clock Rise to Data Valid		0.45		0.45		0.45		0.45	ns	1
tCHQX	Data Output Hold after Output K/K Clock Rise									ns	
	(Active to Active)	-0.45		-0.45		-0.45		-0.45			1
tCHCQV	K/K Clock Rise to Echo Clock Valid		0.45		0.45		0.45		0.45	ns	
tCHCQX	Echo Clock Hold after K/K Clock Rise	-0.45		-0.45		-0.45		-0.45		ns	
tCQHQV	Echo Clock High to Data Valid		0.20		0.20		0.20		0.20	ns	1
tCQHQX	Echo Clock High to Data Invalid	-0.20		-0.20		-0.20		-0.20		ns	1
tCHQZ	Clock (K/K) Rise to High-Z		0.45		0.45		0.45		0.45	ns	1
	(Active to High-Z)										
tCHQX1	Clock (K/K) Rise to Low-Z	-0.45		-0.45		-0.45		-0.45		ns	1
DLL Timing											
tKC Var	Clock Phase Jitter		0.20		0.20		0.20		0.20	ns	
tKC lock	DLL Lock Time (K)	2048		2048		2048				cycles	
tDoffLowToReset	Doff Low period to DLL Reset	5		5		5				ns	

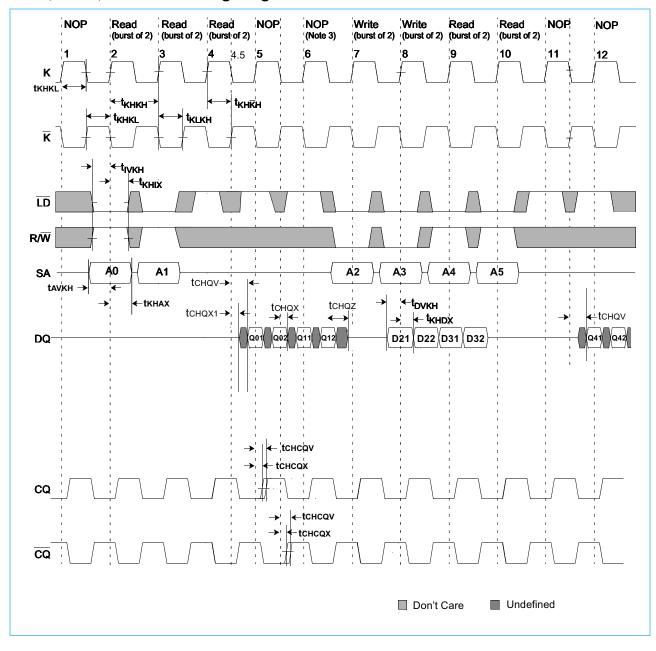
#### Notes:

<sup>1.</sup> See AC Test Loading on page 14.

<sup>2.</sup> During normal operation, VIH, VIL, TRISE, and TFALL of inputs must be within 20% of VIH, VIL, TRISE, and TFALL of clock.



# Read, Write, and NOP Timing Diagram





#### IEEE 1149.1 TAP and Boundary Scan

The SRAM provides a limited set of JTAG functions to test the interconnection between SRAM I/Os and printed circuit board traces or other components. There is no multiplexer in the path from I/O pins to the RAM core.

In conformance with IEEE Standard 1149.1, the SRAM contains a TAP controller, instruction register, boundary scan register, bypass register, and ID register.

The TAP controller has a standard 16-state machine that resets internally on power-up. Therefore, a TRST signal is not required.

### Signal List

· TCK: test clock

• TMS: test mode select

TDI: test data-inTDO: test data-out

### **JTAG DC Operating Characteristics** $(T_A = 0 \text{ to } +70^{\circ} \text{ C})$

Operates with JEDEC Standard 8-5 (1.8V) logic signal levels

Parameter	Symbol	Minimum	Typical	Maximum	Units	Notes
JTAG input high voltage	V <sub>IH1</sub>	1.3	_	V <sub>DD</sub> +0.3	V	1
JTAG input low voltage	V <sub>IL1</sub>	-0.3	_	0.5	V	1
JTAG output high level	V <sub>OH1</sub>	V <sub>DD</sub> -0.4	_	V <sub>DD</sub>	V	1, 2
JTAG output low level	V <sub>OL1</sub>	$V_{SS}$	_	0.4	V	1, 3

<sup>1.</sup> All JTAG inputs and outputs are LVTTL-compatible.

# JTAG AC Test Conditions ( $T_A = 0 \text{ to } +70^{\circ} \text{ C}, V_{DD} = 1.8 \text{V} -5\%, +5\%$ )

Parameter	Symbol	Conditions	Units
Input pulse high level	V <sub>IH1</sub>	1.3	V
Input pulse low level	V <sub>IL1</sub>	0.5	V
Input rise time	T <sub>R1</sub>	1.0	ns
Input fall time	T <sub>F1</sub>	1.0	ns
Input and output timing reference level		0.9	٧

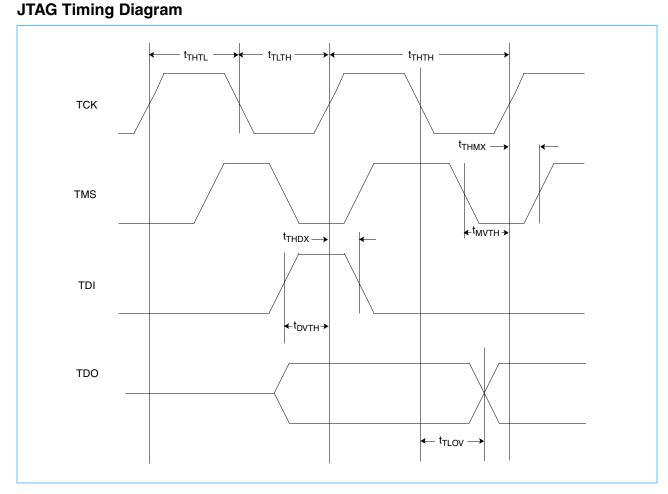
<sup>2.</sup>  $I_{OH1} \ge -2mA$ 

<sup>3.</sup>  $I_{OL1} \ge +2mA$ .



JTAG AC Characteristics ( $T_A = 0 \text{ to } +70^{\circ} \text{ C}, \ V_{DD} = 1.8 \text{V} -5\%, \ +5\%$ )

Parameter	Symbol	Minimum	Maximum	Units	Notes
TCK cycle time	t <sub>THTH</sub>	20	_	ns	
TCK high pulse width	t <sub>THTL</sub>	7	_	ns	
TCk low pulse width	t <sub>TLTH</sub>	7	_	ns	
TMS setup	t <sub>MVTH</sub>	4	_	ns	
TMS hold	t <sub>THMX</sub>	4	_	ns	
TDI setup	t <sub>DVTH</sub>	4	_	ns	
TDI hold	t <sub>THDX</sub>	4	_	ns	
TCK low to valid data	t <sub>TLOV</sub>	_	7	ns	1





# **Scan Register Definition**

Register Name	Bit Size x18 or x36
Instruction	3
Bypass	1
ID	32
Boundary Scan	109

# **ID Register Definition**

	Field Bit Number and Description					
Part	Revision Number (31:29)	Part Configuration (28:12)	JEDEC Code (11:1)	Start Bit (0)		
4M x 18	000	00def0wx0t0q0b0s0	000 101 001 00	1		
2M x 36	000	00def0wx0t0q0b0s0	000 101 001 00	1		

#### Part Configuration Definition:

def = 011 for 72Mb

wx = 11 for x36, 10 for x18

t = 1 for DLL, 0 for non-DLL

q = 1 for QUADB2, 0 for DDR-II, DDR-IIP

b = 1 for burst of 4, 0 for burst of 2

s = 1 for separate I/0, 0 for common I/O



#### **Instruction Set**

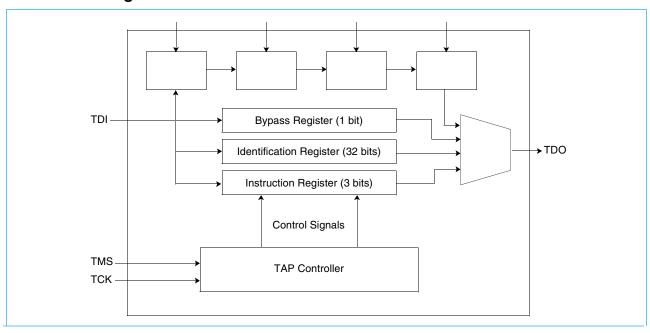
Code	Instruction	TDO Output	Notes
000	EXTEST	Boundary Scan Register	2,6
001	IDCODE	32-bit Identification Register	
010	SAMPLE-Z	Boundary Scan Register	1, 2
011	PRIVATE	Do not use	5
100	SAMPLE	Boundary Scan Register	4
101	PRIVATE	Do not use	5
110	PRIVATE	Do not use	5
111	BYPASS	Bypass Register	3

- 1. Places Qs in high-Z in order to sample all input data, regardless of other SRAM inputs.
- 2. TDI is sampled as an input to the first ID register to allow for the serial shift of the external TDI data.
- BYPASS register is initiated to V<sub>SS</sub> when BYPASS instruction is invoked. The BYPASS register also holds the last serially loaded TDI when exiting the shift-DR state.
- 4. SAMPLE instruction does not place DQs in high-Z.
- 5. This instruction is reserved. Invoking this instruction will cause improper SRAM functionality.
- 6. This EXTEST is not IEEE 1149.1-compliant. By default, it places Q in high-Z. If the internal register on the scan chain is set high, Q will be updated with information loaded via a previous SAMPLE instruction. The actual transfer occurs during the update IR state after EXTEST is loaded. The value of the internal register can be changed during SAMPLE and EXTEST only.

#### List of IEEE 1149.1 Standard Violations

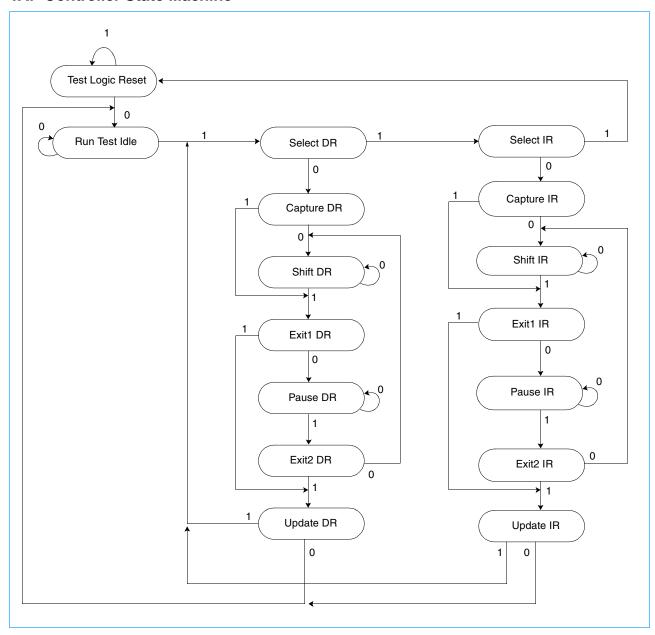
- 7.2.1.b, e
- 7.7.1.a-f
- 10.1.1.b, e
- 10.7.1.a-d
- 6.1.1.d

### JTAG Block Diagram





### **TAP Controller State Machine**





## **Boundary Scan Exit Order** The same length is used for x18 and x36 I/O configuration.

Order	Pin ID
1	6R
2	6P
3	6N
4	7P
5	7N
6	7R
7	8R
8	8P
9	9R
10	11P
11	10P
12	10N
13	9P
14	10M
15	11N
16	9M
17	9N
18	11L
19	11M
20	9L
21	10L
22	11K
23	10K
24	9J
25	9K
26	10J
27	11J
28	11H
29	10G
30	9G
31	11F
32	11G
33	9F
34	10F
35	11E
36	10E

Order	Pin ID
37	10D
37	9E
39	10C
40	11D
41	9C
42	9D
43	11B
44	11C
45	9B
46	10B
47	11A
48	10A
49	9A
50	8B
51	7C
52	6C
53	8A
54	7A
55	7B
56	6B
57	6A
58	5B
59	5A
60	4A
61	5C
62	4B
63	3A
64	2A
65	1A
66	2B
67	3B
68	1C
69	1B
70	3D
71	3C
72	1D

Order	Pin ID	
73	2C	
74	3E	
75	2D	
76	2E	
77	1E	
78	2F	
79	3F	
80	1G	
81	1F	
82	3G	
83	2G	
84	1H	
85	1J	
86	2J	
87	3K	
88	3J	
89	2K	
90	1K	
91	2L	
92	3L	
93	1M	
94	1L	
95	3N	
96	ЗМ	
97	1N	
98	2M	
99	3P	
100	2N	
101	2P	
102	1P	
103	3R	
104	4R	
105	4P	
106	5P	
107	5N	
108	5R	
109	Internal	

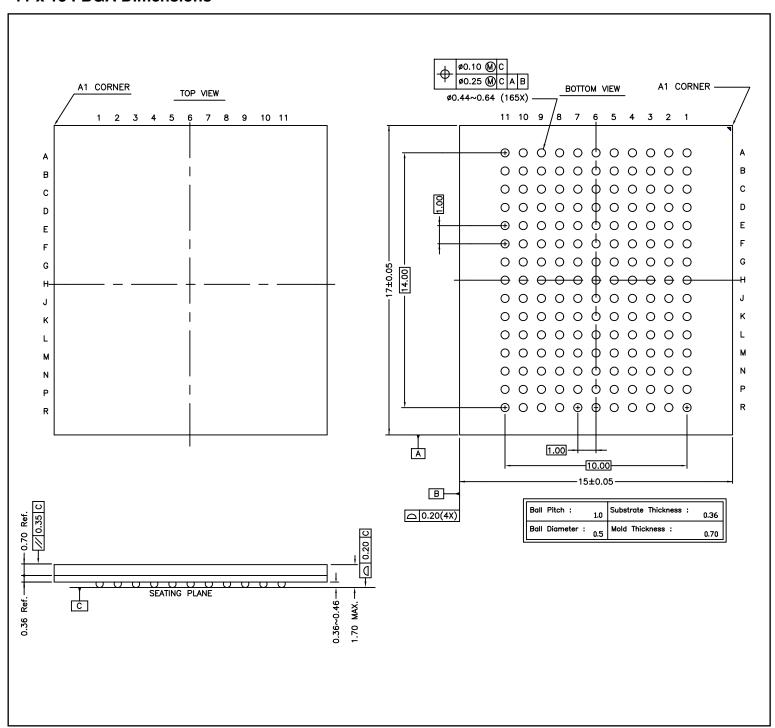
### Notes:

<sup>1)</sup> NC pins as defined on FBGA pinouts on page 2 are read as "don't cares".

<sup>2)</sup> State of Internal pin (#109) is loaded via JTAG



#### 11 x 15 FBGA Dimensions





## **ORDERING INFORMATION**

Commercial Range: 0°C to +70°C

Speed	Order Part No.	Organization	Package
400 MHz	IS61DDPB22M36-400M3	2Mx36	165 BGA
	IS61DDPB22M36-400M3L	2Mx36	165 BGA, Lead-free
	IS61DDPB24M18-400M3	4Mx18	165 BGA
	IS61DDPB24M18-400M3L	4Mx18	165 BGA, Lead-free
375 MHz	IS61DDPB22M36-375M3	2Mx36	165 BGA
	IS61DDPB22M36-375M3L	2Mx36	165 BGA, Lead-free
	IS61DDPB24M18-375M3	4Mx18	165 BGA
	IS61DDPB24M18-375M3L	4Mx18	165 BGA, Lead-free