

# W55RFS27R1B Data Sheet



## SUPER-REGENERATION RF RECEIVER

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## 1. GENERAL DESCRIPTION

The Winbond W55RFS27R1B is a fully integrated, S-R (Super-regeneration) RF receiver with full-function baseband command decoder for R/C vehicles, toys, or wireless data communication applications.

The W55RFS27R1B provides two input modes: ***uC-mode***, for general-purpose, micro-controller interfaces to the RF transmitter (the decoder is disabled); and ***manual-mode***, for a 6-function, baseband command decoder and RF receiver that works conveniently with the W55RFS27T1B to provide a simple remote control capability with low cost and high performance.

The W55RFS27R1B includes the ***Smart-Detector<sup>WB</sup>*** function, which makes the W55RFS27R1B the most suitable receiver for mass-produced applications. ***Smart-Detector<sup>WB</sup>*** overcomes the effects of component deviation and various kinds of environmental problems, such as temperature, moisture, or object-caused, antenna characteristic changes, to maintain maximum sensitivity.

The Super-Regenerative RF front-end architecture operates at 27 MHz, 35 MHz, 40 MHz, or 49MHz with a minimum number of external components. In addition, the W55RFS27R1B accommodates a wide range of operating voltages (2.1 V to 5.5 V) and supports 2- or 3-battery R/C applications.

### 1.1 W55RFS27R1B Features

- Operating frequencies: 27 MHz, 35 MHz, 40 MHz, 49 MHz
- **Smart-Detector<sup>WB</sup>** function overcomes component deviation and environmental problems to maintain highest sensitivity
- Wide operating voltage: 2.1 V ~ 5.5 V
- S-R (Super-regeneration) demodulation scheme
- (*uC-mode*) Receiving data rates up to 1.25Kbps for 50% duty cycle signals
- (*manual-mode*) R/C-toy baseband control command decoder, supporting 6 functions; Forward, Backward, Left-turn, Right-turn, and 2 user-defined functions F1 and F2
- Minimum current consumption
- Very low power-down current consumption (***uC-mode*** only)
- Minimum number of external components
- Dice form available for PCB bonding
- Operating temperature: 0°C ~ 70°C



## 1.2 W55RFS27R1B Pad Definition

### 1.2.1 Pad Description

SYMBOL	PAD NO.	I/O	FUNCTIONAL DESCRIPTION
GND	1	Ground	Ground return path
CMFB	2	O	Common-mode feedback capacitor connection
RBIAS	3	I	Resistor to adjust internal circuit bias
RSAW	4	O	Resistor to control internal saw generator
VDDA	5	Power	Regulated voltage output
OSCin	6	I	Oscillator tank input
OSCout	7	O	Oscillator tank output
GNDA	8	Ground	Regulator ground return path
Reset	9	I	Reset = 0 resets whole chip, internally pulled high
Mode0	10	I	Mode select LSB, please see 1.2.2 for details
Mode1	11	I	Mode select MSB, please see 1.2.2 for details
TEST	12	I	TEST = 1 for chip testing; must be set to "0" for regular operation.
F2	13	O/I	(manual mode) Decoder F2 output (uC-mode) \$ENB ("0" = power down)*
F1	14	O/I	(manual mode) Decoder F1 output (uC-mode) Not used; set to "0"*
R	15	O/I	(manual mode) Decoder Right-turn output (uC-mode) HOPCLK; set to "0"*
L	16	O/I	(manual mode) Decoder Left-turn output (uC-mode) \$OAGC2; set to "0" *
B	17	O/I	(manual mode) Decoder Backward output (uC-mode) \$OAGC1; set to "1" *
F	18	O/I	(manual mode) Decoder Forward output (uC-mode) \$OAGC0; set to "0" *
RXD	19	O/I	Receiver data output
VSPLY	20	Power	Power input

(\* For uC-mode control, please see section 4.2 W55RFS27R1B *Smart-Detector<sup>WB</sup>* Function)

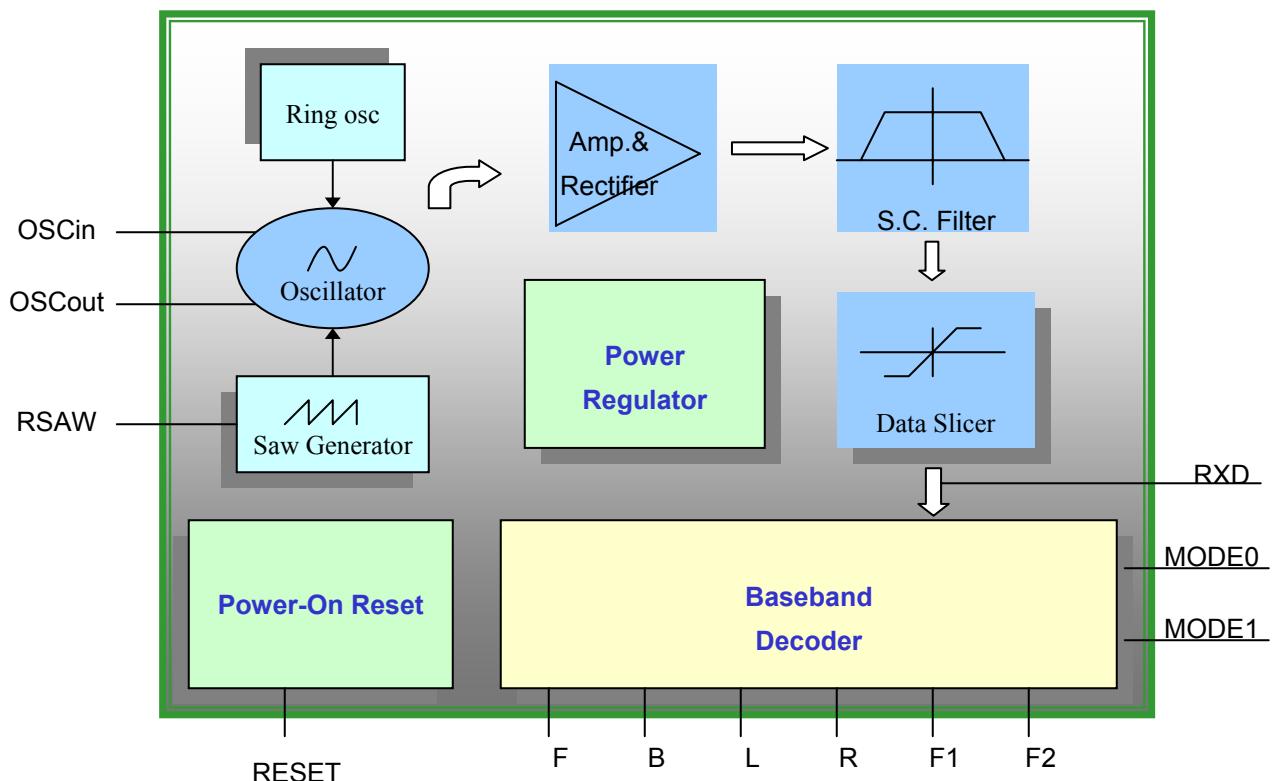


### 1.2.2 Mode selection

(MODE1,MODE0)	FUNCTION DESCRIPTION	NOTE
(0,0)	Disable <b>Smart-Detector<sup>WB</sup></b> Function	Function evaluation only
(0,1)	<b><i>uC-mode,</i></b> <b>Smart-Detector<sup>WB</sup></b> function is externally-controlled	Baseband decoder is disabled
(1,0)	<b><i>Manual-mode,</i></b> Enable half of <b>Smart-Detector<sup>WB</sup></b> function OAGC OFF , HOPPING ON	Function evaluation only
(1,1)	<b><i>Manual-mode,</i></b> Enable <b>Smart-Detector<sup>WB</sup></b> function OAGC ON, HOPPING ON	Suitable for mass-production

## 2. SYSTEM DESCRIPTION

### 2.1 W55RFS27R1B System Block Diagram





## 2.2 W55RFS27R1B Functional Description

### Power Regulator

The W55RFS27R1B built-in power regulator provides stable operating performance for operating voltages from 2.1 to 5.5 V, a very wide range of voltages suitable for 2- or 3-battery R/C toys or R/C vehicles.

### RF Receiver

The W55RFS27R1B has been implemented using a "Super-Regenerative" receiving architecture. The resulting high noise immunity is suitable for getting higher RF receiving performance in very noisy environments. In addition, the **Smart-Detector<sup>WB</sup>** function overcomes component deviation and various environmental problems to provide the highest receiver sensitivity, making it quite suitable for mass-produced applications.

### Baseband Control Function Decoder

The W55RFS27R1B has a built-in, 6-function baseband control function decoder for R/C toys. The six functions include **Forward**; **Backward**; **Left-turn**; **Right-turn**, and two user-defined functions **F1** and **F2**.



## 3. ELECTRONIC CHARACTERISTICS

### 3.1 W55RFS27R1B Absolute Maximum Ratings

PARAMETER	RATING	UNIT
Supply Voltage to Ground Potential	- 0.3 to 6.5	V
Applied Input/Output Voltage	- 0.3 to 6.5	V
Power Dissipation ( $T_a = 70^{\circ}\text{C}$ )	150	mW
Ambient Operating Temperature	0 to 70	$^{\circ}\text{C}$
Storage Temperature	-40 to 85	$^{\circ}\text{C}$

**Note:** Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

# W55RFS27R1B



## 3.2 W55RFS27R1B DC Characteristics

(VDD-VSS = 3 V, Ta = 25°C; unless otherwise specified)

PARAMETER	SYM.	CONDITIONS	MIN.	TYP.	MAX.	UNIT
<b>Power Supply</b>						
Operating Voltage	V <sub>DD</sub>		2.1	-	5.5	V
Operating Current	I <sub>OP</sub>		-	-	2.8	mA
Stand-by Current	I <sub>SBY</sub>	\$ENB= 0	-	-	2	μA
Regulated Voltage	V <sub>DDA</sub>		1.65	1.8	2.1	V
<b>Digital Input/Output Pin</b>						
Input High Voltage	V <sub>IH</sub>		0.8*V <sub>D<sub>D</sub></sub>	-	V <sub>DD</sub>	V
Input Low Voltage	V <sub>IL</sub>		V <sub>SS</sub>	-	0.1*V <sub>DD</sub>	V
F,B,L,R,F1,F2 Output High Source Current	I <sub>OH</sub>	V <sub>OH</sub> =0.7 * V <sub>DD</sub>	6	-	-	mA
F,B,L,R,F1,F2 Output Low Sink Current	I <sub>OL</sub>	V <sub>OL</sub> =0.3 * V <sub>DD</sub>	6	-	-	mA
RXD Output High Source Current	I <sub>OH</sub>	V <sub>OH</sub> =0.7 * V <sub>DD</sub>	2	-	-	mA
RXD Output Low Sink Current	I <sub>OL</sub>	V <sub>OL</sub> =0.3 * V <sub>DD</sub>	2	-	-	mA
<b>Crystal Oscillator</b>						
Operation Frequency	F <sub>C</sub>		27	-	49.8	MHz
On-chip Ring Oscillator frequency	T <sub>OSC</sub>		170	200	250	KHz
<b>Baseband Decoder Section</b>						
Modulation Duty Cycle	M <sub>DYT</sub>		40	50	60	%
Received Data Rate	R <sub>DTT</sub>	50% Duty-cycle Manchester Code	-	1.25	-	Kbps

# W55RFS27R1B



## 3.3 W55RFS27R1B Ordering Information

The W55RFS27R1B is available in two types: Dice form and Wafer form.

PART NUMBER	PACKAGE	REMARKS
W55RFS27R1B(H)	Dice form	
W55RFS27R1B(W)	Wafer form	

## 3.4 W55RFS27R1B Package Information

### 3.4.1 W55RFS27R1B Bonding Pad List

```
-----  
Window : (xl = -929.000, yl = -625.000),  
         (xh = 929.000, yh = 625.000)  
Windows size : Width = 1858.000, length = 1250.000  
=====
```

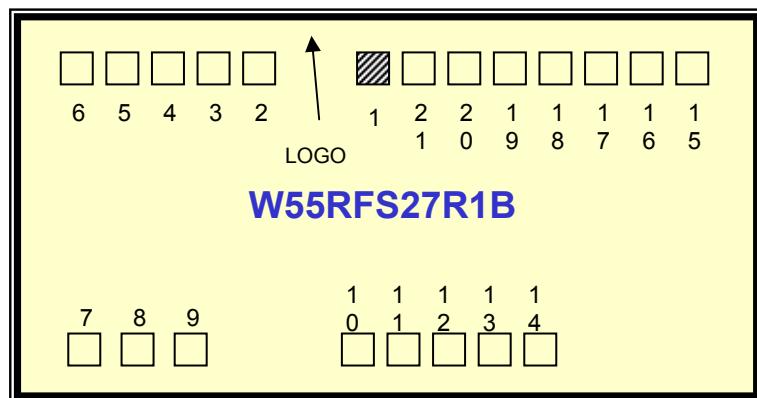
PAD NO	PAD NAME	PIN NAME	X	Y
1	* GND	* 1	-13.000	540.000
2	CMFB	2	-365.950	540.000
3	RBIAS	3	-472.950	540.000
4	RSAW	4	-579.950	540.000
5	VDDA	5	-689.350	540.000
6	VDDA	5	-801.150	540.000
7	OSCin	6	-795.075	-540.000
8	OSCout	7	-667.875	-540.000
9	GNDA	8	-555.150	-540.000
10	reset	9	-128.675	-540.000
11	MODE0	10	-21.675	-540.000
12	MODE1	11	85.325	-540.000
13	TEST	12	192.325	-540.000
14	F2	13	302.925	-540.000
15	F1	14	790.325	540.000
16	R	15	675.875	540.000
17	L	16	561.425	540.000
18	B	17	446.975	540.000
19	F	18	332.525	540.000
20	RXD	19	218.075	540.000
21	VSPLY	20	98.400	540.000

(\*: Bonding Sequence start from GND(Pin1))

# **W55RFS27R1B**



## **3.4.2 W55RFS27R1B Bonding Pad Diagram**

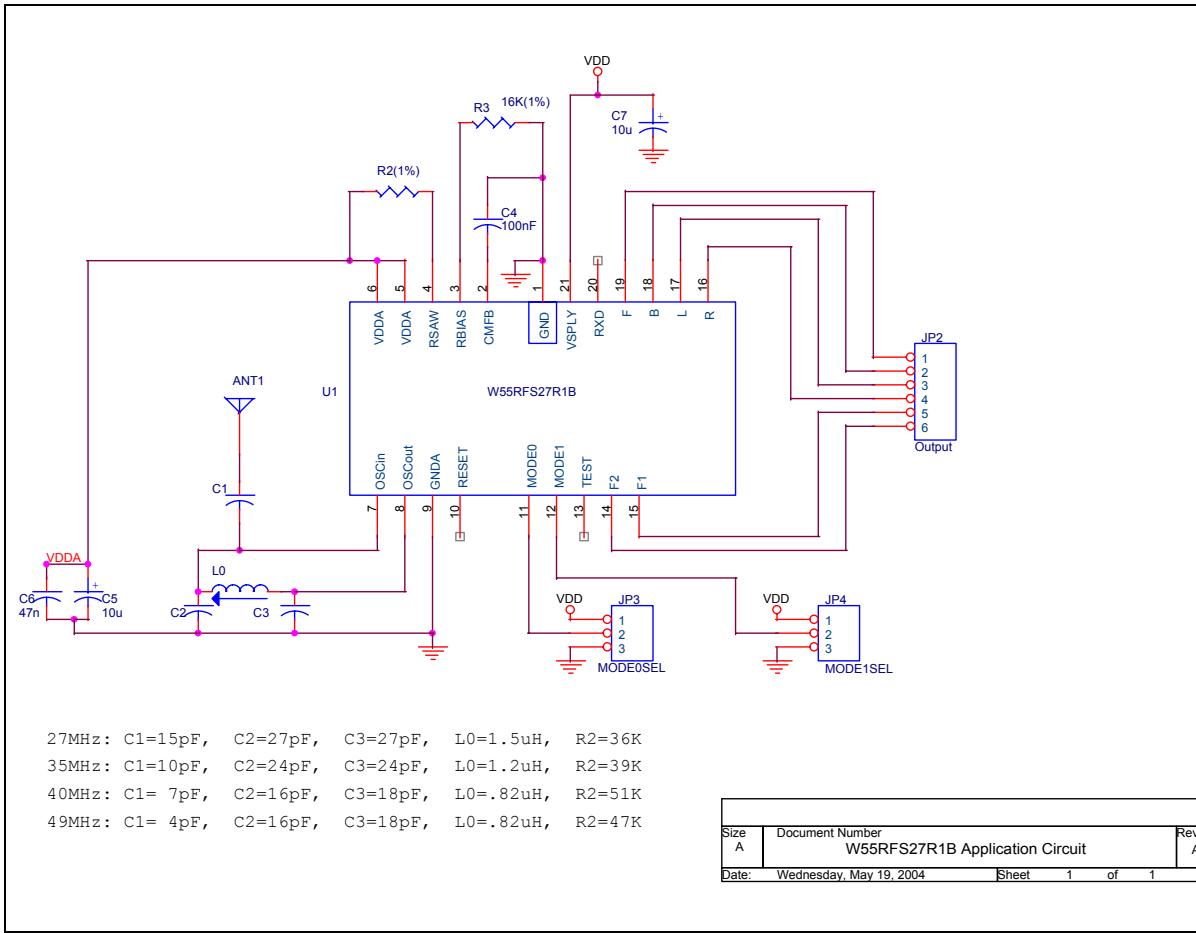




## 4. DESIGN INFORMATION

### 4.1 W55RFS27R1B Reference Design

#### 4.1.1 W55RFS27R1B Application Circuit



(\* Note: The component values are suitable for a 15-cm antenna. Different antenna might change RSAW (R2).)

# W55RFS27R1B



## W55RFS27R1B Application Schematic BOM:

Item	Qty	Reference	Part
1	1	ANT1	ANTENNA
2	1	C1	4pF
3	1	C2	16P
4	1	C3	18P
5	1	C4	100nF
6	2	C7,C5	10u
7	1	C6	47n
8	1	JP2	Output
9	1	JP3	MODE0SEL
10	1	JP4	MODE1SEL
11	1	L0	0.82u
12	1	R2	47K(1%)
13	1	R3	16K(1%)
14	1	U1	W55RFS27R1B



## 4.2 W55RFS27R1B Smart-Detector<sup>WB</sup> Function

### 4.2.1 Introduction

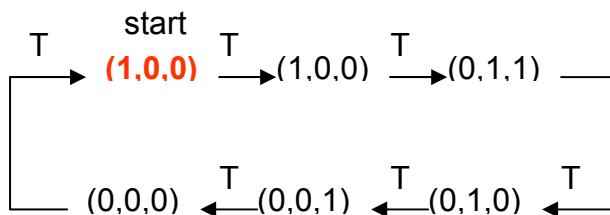
The **Smart-Detector<sup>WB</sup>** function is designed to overcome the effects of component deviation and environmental changes. It enables the on-chip OAGC (Oscillator Auto-Gain-Control) and hopping clock functions, dynamically searching for the best operating conditions and

maintaining the highest sensitivity in different environments.

In **manual-mode**, the control mechanism is built in while, in **uC-mode**, the OAGC and hopping functions are fixed or controlled by the external MCU.

### 4.2.2 Using Smart-Detector<sup>WB</sup> in Manual-mode

- a). Set [MODE1:MODE0] to [00] to disable **Smart-Detector<sup>WB</sup>**. Then, select RSAW to provide the highest sensitivity. Note the default values for OAGC and HOPCLK are OAGC[2:0] = {0,1,0} and HOPCLK = 0.
- b). Set [MODE1:MODE0] to [11] to enable **Smart-Detector<sup>WB</sup>**. Then, OAGC[2:0] change according to the following sequence, and HOPCLK toggles once ("0" => "1" or "1" => "0") every T seconds.



(T ≈ 20ms)

- c). When a data packet is received, the W55RFS27R1B holds the current OAGC and HOPCLK settings for around 50ms. When there is no more data input, OAGC and HOPCLK resume sequencing and toggling.

### 4.2.3 Using Smart-Detector<sup>WB</sup> in uC-mode

In **uC-mode**, OAGC[2:0] and HOPCLK are externally controlled. They can be fixed at specific values or changed to follow the sequence described in manual-mode. Winbond recommends using fixed settings in **uC-mode** because it can be difficult for the MCU to control these pins.

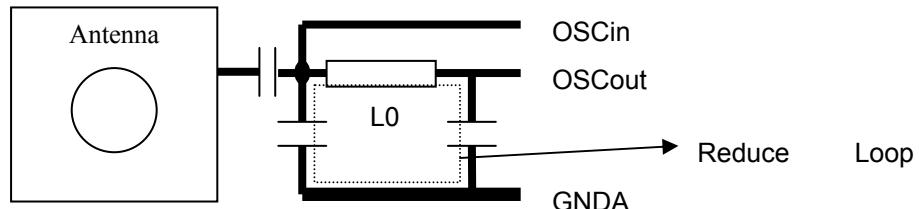
When OAGC and HOPCLK are fixed, the corresponding pins should be set to OAGC[2:0] = (0,1,0) and HOPCLK = 0. Component deviation should be controlled tightly for consistent results in mass-produced applications.



When following the sequence above, the switching time T should be based on the data repeat time of the transmitter. Usually, the switching time is twice the repeat time. For example, if a transmitter sends data every 10 ms, then the switching time T should be 20 ms.

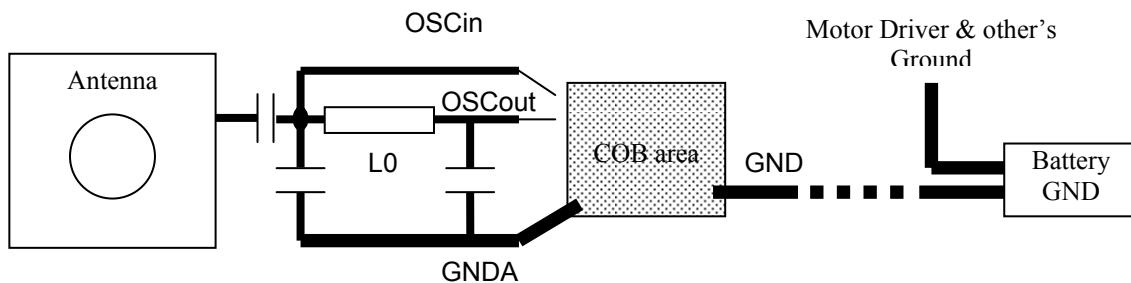
### 4.3 W55RFS27R1B Layout Guide

- Make the antenna signal input path (ANT->C1->L0,C2,C3) as short as possible, and keep it away from any sources of noise.
- Place the oscillation tank components (L0,C2,C3) as close to each other as possible and as close to the OSCin and OSCout pins as possible.
- Make the oscillator ground return path (GNDA) as short and as wide as possible to GNDA. Keep this path isolated from noise sources too.



**Pic.1 Graphic representation for a),b),c)**

- Separate the oscillation tank ground from the other ground paths, and connect it directly to GNDA.



**Pic.2 Graphic representation for d)**



## 5. REVISION HISTORY

VERSION	DATE	PAGE	DESCRIPTION
A1	2004/5/27	-	Preliminary version
A2	2004/7/15	-	Released version A2
A3	2005/5/30	-	Revised by Brand and add important notice

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