## Multiple Switch Detection Interface with Suppressed Wake-Up and 32mA Wetting Current

Freescale offers multiple Switch Detection Interface Devices. The 33975 Multiple Switch Detection Interface with Suppressed Wake-Up is designed to detect the closing and opening of up to 22 switch contacts. The switch status, either open or closed, is transferred to the microprocessor unit (MCU) through a serial peripheral interface (SPI). The device also features a 22-to-1 analog multiplexer for reading inputs as analog.

The 33975 device has two modes of operation, Normal and Sleep. Normal mode allows programming of the device and supplies switch contacts with pull-up or pull-down current as it monitors switch change of state. The Sleep mode provides low quiescent current, which makes the 33975 ideal for automotive and industrial products requiring low sleep state currents.

Improvements are a programmable interrupt timer for Sleep mode that can be disabled, switch detection currents of 32 mA and 4.0 mA for switch-to-ground inputs, and an interrupt bit that can be reset.

## Features

- Designed to Operate $5.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V}$
- Switch Input Voltage Range - 14 V to $\mathrm{V}_{\text {PWR }}$
- Interfaces Directly to Microprocessor Using 3.3 V/5.0 V SPI Protocol
- Selectable Wake-Up on Change of State
- Selectable Wetting Current ( 32 mA or 4.0 mA for switch-to-ground inputs)
- 8 Programmable Inputs (Switches to Battery or Ground)
- 14 Switch-to-Ground Inputs
- $\mathrm{V}_{\text {PWR }}$ Standby Current $100 \mu \mathrm{~A}$ Typical, $\mathrm{V}_{\mathrm{DD}}$ Standby Current $20 \mu \mathrm{~A}$ Typical
- Pb-free 32-terminal suffix EK


Figure 1. 33975 Simplified Application Diagram

* This document contains certain information on a new product. Specifications and information herein are subject to change without notice.


## DEVICE VARIATIONS

## Table 1. Device Variations

| Freescale Part No. | Switch Input Voltage Range | Other Significant Device Variations | Reference <br> Location |
| :---: | :---: | :---: | :---: |
| MC33975 | -14 to $38 \mathrm{~V}_{\mathrm{DC}}$ | None | $\underline{5}$ |
| PC33975A | -14 to $40 \mathrm{~V}_{\mathrm{DC}}$ | None | $\underline{5}$ |

INTERNAL BLOCK DIAGRAM


Figure 2. 33975 Simplified Internal Block Diagram

## TERMINAL CONNECTIONS



Figure 3. 33975 Terminal Connections
Table 2. Terminal Definitions
A functional description of each terminal can be found in the Functional Terminal Description section on page 11.

| Terminal | Terminal <br> Name | Formal Name | Description |
| :---: | :---: | :---: | :--- |
| 1 | GND | Ground | Ground for logic, analog, and switch-to-battery inputs. |
| 2 | SI | SPI Slave In | SPI control data input terminal from MCU to 33975. |
| 3 | SCLK | Serial Clock | SPI control clock input terminal. |
| 4 | $\overline{\text { CS }}$ | Chip Select | SPI control chip select input terminal from MCU to 33975. Logic [0] allows data <br> to be transferred in. |
| $5-8$ <br> $25-28$ | SPn | Programmable Switches 0-3 <br> Programmable Switches 4-7 | Programmable switch-to-battery or switch-to-ground input terminals. |
| $9-15$, <br> $18-24$ | SGn | Switch-to-Ground Inputs 0-6 <br> Switch-to-Ground Inputs 13-7 | Switch-to-ground input terminals. |
| 16 | VPWR | Battery Input | Battery supply input terminal. This terminal requires external reverse battery <br> protection. |
| 17 | $\overline{\text { WAKE }}$ | Wake-Up | Open drain wake-up output is designed to control a power supply enable <br> terminal. |
| 29 | $\overline{\text { NT }}$ | Interrupt | Open-drain output to MCU is used to indicate input switch change of state. |
| 30 | AMUX | Analog Multiplex Output | Analog multiplex output. |
| 31 | VDD | Voltage Drain Supply | 3.3/5.0 V supply sets SPI communication level for SO driver. |
| 32 | SO | SPI Slave Out | Provides digital data from 33975 to MCU. |

## MAXIMUM RATINGS

## Table 3. Maximum Ratings

All voltages are with respect to ground unless otherwise noted. Exceeding these limits may cause malfunction or permanent damage to the device.

| Rating | Symbol | Value | Unit |
| :---: | :---: | :---: | :---: |

ELECTRICAL RATINGS

| $V_{\text {DD }}$ Supply Voltage | - | -0.3 to 7.0 | $V_{D C}$ |
| :---: | :---: | :---: | :---: |
| $\overline{\mathrm{CS}}, \mathrm{SI}, \mathrm{SO}, \mathrm{SCLK}, \overline{\mathrm{NT}}$, AMUX | - | -0.3 to 7.0 | $V_{D C}$ |
| WAKE | - | -0.3 to 40 | $V_{D C}$ |
| $\mathrm{V}_{\text {PWR }}$ Supply Voltage | - | -0.3 to 50 | $V_{D C}$ |
| Switch Input Voltage Range MC33975 PC339775A | - | $\begin{aligned} & -14 \text { to } 38 \\ & -14 \text { to } 40 \end{aligned}$ | $V_{D C}$ |
| Frequency of SPI Operation ( $\mathrm{V}_{\mathrm{DD}}=5.0 \mathrm{~V}$ ) | - | 6.0 | MHz |
| ESD Voltage ${ }^{(1)}$ <br> Human Body Model ${ }^{(2)}$ <br> Applies to all non-input terminals <br> Machine Model <br> Charge Device Model <br> Corner Terminals <br> Interior Terminals | $V_{\text {ESD }}$ | $\begin{gathered} \pm 4000 \\ \pm 2500 \\ \pm 200 \\ \\ 750 \\ 500 \end{gathered}$ | V |

THERMAL RATINGS

| Operating Temperature <br> Ambient <br> Junction <br> Case | $\mathrm{T}_{\mathrm{A}}$ | -40 to 125 |  |
| :--- | :---: | :---: | :---: |
| Storage Temperature | $\mathrm{T}_{\mathrm{J}}$ | ${ }^{\circ} \mathrm{C}$ |  |
| Power Dissipation ${ }^{(3)}$ | $\mathrm{T}_{\mathrm{C}}$ | -40 to 150 |  |
| Thermal Resistance <br> Junction to Ambient <br> Between the Die and the Exposed Die Pad ${ }^{(4)}$ | $\mathrm{T}_{\text {STG }}$ | -55 to 150 | ${ }^{\circ} \mathrm{C}$ |
| Peak Package Reflow Temperature During Solder Mounting ${ }^{(5)}$ | $\mathrm{R}_{\theta \mathrm{DA}}$ | 1.7 | W |

## Notes

1. ESD testing is performed in accordance with the Human Body Model ( $\left.C_{Z A P}=100 \mathrm{pF}, \mathrm{R}_{\mathrm{ZAP}}=1500 \Omega\right)$, the Machine Model $\left(C_{Z A P}=200\right.$ $\mathrm{pF}, \mathrm{R}_{\mathrm{ZAP}}=0 \Omega$ ), and the Charge Device Model.
2. All Programmable Switches (SP) and Switch-to-Ground (SG) input terminals when tested individually.
3. Maximum power dissipation at $\mathrm{T}_{\mathrm{J}}=150^{\circ} \mathrm{C}$ junction temperature with no heatsink used.
4. Thermal resistance between the die and the exposed die pad.
5. Terminal soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.

## STATIC ELECTRICAL CHARACTERISTICS

Table 4. Static Electrical Characteristics
Characteristics noted under conditions of $3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD}} \leq 5.5 \mathrm{~V}, 8.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V},-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{C}} \leq 125^{\circ} \mathrm{C}$ unless otherwise noted. Where applicable, typical values reflect the parameter's approximate average value with $\mathrm{V}_{\mathrm{PWR}}=13 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |

POWER INPUT

| Supply Voltage <br> Supply Voltage Range Quasi-Functional <br> Fully Operational <br> Supply Voltage Range Quasi-Functional ${ }^{(7)}$ | $V_{\text {PWR(qf) }}$ <br> $V_{\text {PWR(fo) }}$ <br> $V_{\text {PWR(qf) }}$ | $\begin{aligned} & 5.5 \\ & 8.0 \\ & 28 \end{aligned}$ |  | $\begin{gathered} 8.0 \\ 28 \\ 38 / 40 \end{gathered}$ | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage <br> VPWR Supply Voltage Power On Reset | $\mathrm{V}_{\text {PWR(POR) }}$ | 4.2 | 4.6 | 5.0 | V |
| Supply Current <br> All Switches Open, Normal Mode, Tri-State Disabled | $\mathrm{I}_{\text {PWR(on) }}$ | - | 4.0 | 8.0 | mA |
| Sleep State Supply Current Scan Timer $=64 \mathrm{~ms}$, Switches Open | IPWR(ss) | 40 | 70 | 100 | $\mu \mathrm{A}$ |
| Logic Supply Voltage | $V_{D D}$ | 3.0 | - | 5.5 | V |
| Logic Supply Current <br> All Switches Open, Normal Mode | IDD | - | 0.25 | 0.5 | mA |
| Sleep State Logic Supply Current Scan Timer $=64 \mathrm{~ms}$, Switches Open | $\mathrm{I}_{\mathrm{DD}(\mathrm{ss})}$ | - | 10 | 20 | $\mu \mathrm{A}$ |

SWITCH INPUT

| Pulse Wetting Current Switch-to-Battery (Current Sink) $5.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V}$ | IPulse | 12 | 15 | 18 | mA |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Pulse Wetting Current Switch-to-Ground (Current Source) $\begin{aligned} & 5.5 \mathrm{~V} \leq \mathrm{V}_{\text {PWR }} \leq 8.0 \mathrm{~V} \\ & 8.0 \mathrm{~V} \leq \mathrm{V}_{\text {PWR }} \leq 28 \mathrm{~V} \end{aligned}$ | ${ }^{\text {Pulse }}$ | $\begin{aligned} & 7.0 \\ & 24 \end{aligned}$ | $\begin{gathered} 9.0 \\ 32 \end{gathered}$ | $36$ | mA |
| Sustain Current Switch-to-Battery Input (Current Sink) $5.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V}$ | $\mathrm{I}_{\text {sustain }}$ | 1.8 | 2.1 | 2.4 | mA |
| Sustain Current Switch-to-Ground Input (Current Source) $\begin{aligned} & 5.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 8.0 \mathrm{~V} \\ & 8.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V} \end{aligned}$ | $I_{\text {sustain }}$ | $\begin{aligned} & 0.5 \\ & 3.6 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 4.0 \end{aligned}$ | $4.4$ | mA |
| Sustain Current Matching Between Channels on Switch-to-Ground Inputs $\frac{I_{\text {SUS(MAX) }}-I_{\text {SUS(MIN) }}}{I_{\text {SUS(MIN })}} \times 100$ | ${ }^{\text {Match }}$ | - | 2.0 | 5.0 | \% |

Notes
6. Device operational. Wetting and sustain currents are reduced. Operating the analog multiplexer below 8.0 V is not recommended.
7. Thermal considerations must be taken when operating the device above 28 V .

Table 4. Static Electrical Characteristics (continued)
Characteristics noted under conditions of $3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD}} \leq 5.5 \mathrm{~V}, 8.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V}$, $-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{C}} \leq 125^{\circ} \mathrm{C}$ unless otherwise noted. Where applicable, typical values reflect the parameter's approximate average value with $\mathrm{V}_{\mathrm{PWR}}=13 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |

## SWITCH INPUT (CONTINUED)

| Input Offset Current when Selected as Analog | $l_{\text {offset }}$ | -2.0 | 1.4 | 2.0 | $\mu \mathrm{A}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input Offset Voltage when Selected as Analog $\mathrm{V}_{\text {(SP\&SGinputs) }}$ to AMUX Output | $\mathrm{V}_{\text {offset }}$ | -10 | 2.5 | 10 | mV |
| Analog Operational Amplifier Output Voltage <br> Sink $250 \mu \mathrm{~A}$ | $\mathrm{V}_{\text {OL }}$ | - | 10 | 30 | mV |
| Analog Operational Amplifier Output Voltage Source $250 \mu \mathrm{~A}$ | $\mathrm{V}_{\mathrm{OH}}$ | $V_{D D}-0.1$ | - | - | V |
| Switch Detection Threshold | $\mathrm{V}_{\text {th }}$ | 3.70 | 4.0 | 4.3 | V |
| Temperature Monitor ${ }^{(8)}$, ${ }^{(9)}$ | $\mathrm{T}_{\text {LIM }}$ | 155 | - | 185 | ${ }^{\circ} \mathrm{C}$ |
| Temperature Monitor Hysteresis ${ }^{(9)}$ | TLIM(hys) | 5.0 | 10 | 15 | ${ }^{\circ} \mathrm{C}$ |

## Notes

8. Thermal shutdown of 16 mA and 32 mA pull-up and pull-down current sources only. 4.0 mA and 2.0 mA current source/sink and all other functions remain active.
9. This parameter is guaranteed by design; however it is not production tested.

Table 4. Static Electrical Characteristics (continued)
Characteristics noted under conditions of $3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD}} \leq 5.5 \mathrm{~V}$, $8.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V},-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{C}} \leq 125^{\circ} \mathrm{C}$ unless otherwise noted. Where applicable, typical values reflect the parameter's approximate average value with $\mathrm{V}_{\mathrm{PWR}}=13 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: |

## DIGITAL INTERFACE

| Input Logic High-Voltage Thresholds ${ }^{(10)}$ | $\mathrm{V}_{\mathrm{IH}}$ | $0.7 \times \mathrm{V}_{\mathrm{DD}}$ | - | $V_{D D}+0.3$ | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input Logic Low-Voltage Thresholds ${ }^{(10)}$ | $\mathrm{V}_{\mathrm{IL}}$ | GND - 0.3 | - | $0.2 \times \mathrm{V}_{\mathrm{DD}}$ | V |
| SCLK, SI, Tri-State SO Input Current $0.0 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{DD}}$ | IsCLK, ISI, $\mathrm{I}_{\mathrm{SO}(\mathrm{Tri})}$ | -10 | - | 10 | $\mu \mathrm{A}$ |
| $\overline{\mathrm{CS}}$ Input Current $\overline{C S}=V_{D D}$ | ${ }^{1} \overline{\mathrm{CS}}$ | -10 | - | 10 | $\mu \mathrm{A}$ |
| $\overline{\mathrm{CS}}$ Pull-Up Current $\overline{\mathrm{CS}}=0.0 \mathrm{~V}$ | ${ }^{1} \overline{\mathrm{CS}}$ | 30 | - | 100 | $\mu \mathrm{A}$ |
| SO High-State Output Voltage $I_{\mathrm{SO}(\text { high })}=-200 \mu \mathrm{~A}$ | $\mathrm{V}_{\text {SO (high }}$ | $V_{D D}-0.8$ | - | VDD | V |
| SO Low-State Output Voltage $\mathrm{I}_{\mathrm{SO}(\mathrm{high})}=1.6 \mathrm{~mA}$ | $\mathrm{V}_{\text {SO(Iow }}$ | - | - | 0.4 | V |
| Input Capacitance on SCLK, SI, Tri-State SO ${ }^{(11)}$ | $\mathrm{C}_{\text {IN }}$ | - | - | 20 | pF |
| $\overline{\mathrm{INT}}$ Internal Pull-Up Current | - | 15 | 40 | 100 | $\mu \mathrm{A}$ |
| $\overline{\text { INT }}$ Voltage $\overline{\mathrm{INT}}=$ Open Circuit | $\mathrm{V}_{\overline{\mathrm{INT}} \text { (high) }}$ | VDD - 0.5 | - | VDD | V |
| $\overline{\text { INT }}$ Voltage $\overline{\mathrm{INT}}=1.0 \mathrm{~mA}$ | $\mathrm{V}_{\overline{\mathrm{INT}} \text { (low) }}$ | - | 0.2 | 0.4 | V |
| WAKE Internal Pull-Up Current | $1 \overline{\text { WAKE }}$ (pu) | 20 | 40 | 100 | $\mu \mathrm{A}$ |
| WAKE Voltage $\overline{\text { WAKE }}=\text { Open Circuit }$ | $\mathrm{V}_{\text {WAKE (high) }}$ | 4.0 | 4.3 | 5.3 | V |
| WAKE Voltage $I_{\overline{\text { WAKE }}}=1.0 \mathrm{~mA}$ | $\mathrm{V}_{\overline{\text { WAKE }} \text { (low) }}$ | - | 0.2 | 0.4 | V |
| $\overline{\text { WAKE Voltage }}{ }^{(11)}$ <br> Maximum Voltage Applied to $\overline{\text { WAKE }}$ Through External Pull-Up | $\mathrm{V}_{\text {WAKE }} \overline{\text { (max }}$ ) | - | - | 40 | V |

Notes
10. Upper and lower logic threshold voltage levels apply to SI, $\overline{\mathrm{CS}}$, and SCLK.
11. This parameter is guaranteed by design however, is not production tested.

## DYNAMIC ELECTRICAL CHARACTERISTICS

## Table 5. Dynamic Electrical Characteristics

Characteristics noted under conditions of $3.0 \mathrm{~V} \leq \mathrm{VDD} \leq 5.5 \mathrm{~V}, 8.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{PWR}} \leq 28 \mathrm{~V},-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{C}} \leq 125^{\circ} \mathrm{C}$ unless otherwise noted. Where applicable, typical values reflect the parameter's approximate average value with $\mathrm{V}_{\mathrm{PWR}}=13 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |

## SWITCH INPUT

| Pulse Wetting Current Time | $\mathrm{t}_{\text {pulse }(\mathrm{on})}$ | 15 | 16 | 22 | ms |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Interrupt Delay Time <br> Normal Mode | $\mathrm{t}_{\text {int-dly }}$ |  |  |  | $\mu \mathrm{s}$ |
| Sleep Mode Switch Scan Time | $\mathrm{t}_{\text {scan }}$ | 100 | 200 | 300 | $\mu \mathrm{~s}$ |
| Calibrated Scan Timer Accuracy <br> Sleep Mode | $\mathrm{t}_{\text {scan timer }}$ |  |  | 16 | $\%$ |
| Calibrated Interrupt Timer Accuracy <br> Sleep Mode | $\mathrm{t}_{\text {int timer }}$ | - | - | 10 | $\%$ |

DIGITAL INTERFACE TIMING ${ }^{(12)}$

| Required Low State Duration on VPWR for Reset $\mathrm{V}_{\mathrm{PWR}} \leq 0.2 \mathrm{~V}$ | $\mathrm{t}_{\text {RESET }}$ | - | - | 10 | $\mu \mathrm{s}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Falling Edge of $\overline{\mathrm{CS}}$ to Rising Edge of SCLK Required Setup Time | $t_{\text {lead }}$ | 100 | - | - | ns |
| Falling Edge of SCLK to Rising Edge of $\overline{C S}$ Required Setup Time | $t_{\text {lag }}$ | 50 | - | - | ns |
| SI to Falling Edge of SCLK Required Setup Time | ${ }^{\text {SII }}$ (su) | 16 | - | - | ns |
| Falling Edge of SCLK to SI Required Hold Time | ${ }^{\text {SII (hold) }}$ | 20 | - | - | ns |
| SI, $\overline{\text { CS }}$, SCLK Signal Rise Time ${ }^{(14)}$ | $\mathrm{t}_{\mathrm{r}(\mathrm{SI})}$ | - | 5.0 | - | ns |
| SI, $\overline{C S}$, SCLK Signal Fall Time ${ }^{(14)}$ | $\mathrm{t}_{\mathrm{f}(\mathrm{SI})}$ | - | 5.0 | - | ns |
| Time from Falling Edge of $\overline{\mathrm{CS}}$ to SO Low Impedance ${ }^{(15)}$ | ${ }^{\text {s SO(en) }}$ | - | - | 55 | ns |
| Time from Rising Edge of $\overline{\mathrm{CS}}$ to SO High Impedance ${ }^{(16)}$ | ${ }^{\text {S }}$ ( ${ }^{\text {(dis) }}$ | - | - | 55 | ns |
| Time from Rising Edge of SCLK to SO Data Valid ${ }^{(17)}$ | $\mathrm{t}_{\text {valid }}$ | - | 25 | 55 | ns |

## Notes

12. These parameters are guaranteed by design. Production test equipment uses $4.16 \mathrm{MHz}, 5.0 \mathrm{~V} \mathrm{SPI}$ interface.
13. This parameter is guaranteed by design but not production tested.
14. Rise and Fall time of incoming SI, $\overline{\mathrm{CS}}$, and SCLK signals suggested for design consideration to prevent the occurrence of double pulsing.
15. Time required for valid output status data to be available on SO terminal.
16. Time required for output states data to be terminated at SO terminal.
17. Time required to obtain valid data out from SO following the rise of SCLK with 200 pF load.

TIMING DIAGRAMS


Figure 4. SPI Timing Characteristics


Figure 5. Sleep Mode to Normal Mode Operation


Figure 6. Normal Mode Interrupt Operation

## FUNCTIONAL DESCRIPTIONS

## INTRODUCTION

The 33975 device is an integrated circuit designed to provide systems with ultra-low quiescent sleep/wake-up modes and a robust interface between switch contacts and a microprocessor. The 33975 replaces many of the discrete components required when interfacing to microprocessorbased systems while providing switch ground offset protection, contact wetting current, and system wake-up.

The 33975 features 8-programmable switch-to-ground or switch-to-battery inputs and 14 switch-to-ground inputs. All
switch inputs may be read as analog inputs through the analog multiplexer (AMUX). Other features include a programmable wake-up timer, programmable interrupt timer, programmable wake-up/interrupt bits, and programmable wetting current settings.

This device is designed primarily for automotive applications but may be used in a variety of other applications such as computer, telecommunications, and industrial controls.

## FUNCTIONAL TERMINAL DESCRIPTION

## CHIP SELECT (CS)

The system MCU selects the 33975 to receive communication using the chip select ( $\overline{\mathrm{CS}}$ ) terminal. With the $\overline{\mathrm{CS}}$ in a logic low state, command words may be sent to the 33975 via the serial input (SI) terminal, and switch status information can be received by the MCU via the serial output (SO) terminal. The falling edge of $\overline{C S}$ enables the SO output, latches the state of the INT terminal, and the state of the external switch inputs.

Rising edge of the $\overline{\mathrm{CS}}$ initiates the following operation:

1. Disables the SO driver (high impedance)
2. $\overline{\mathrm{INT}}$ terminal is reset to logic [1], except when additional switch changes occur during $\overline{\mathrm{CS}}$ low (see Figure 6, page 10).
3. Activates the received command word, allowing the 33975 to act upon new data from switch inputs.

To avoid any spurious data, it is essential the high-to-low and low-to-high transitions of the $\overline{\mathrm{CS}}$ signal occur only when SCLK is in a logic low state. Internal to the 33975 device is an active pull-up to VDD on $\overline{\mathrm{CS}}$.

In Sleep mode the negative edge of $\overline{\mathrm{CS}}$ (VDD applied) will wake up the 33975 device. Data received from the device during $\overline{\mathrm{CS}}$ wake-up may not be accurate.

## SERIAL CLOCK (SCLK)

The system clock (SCLK) terminal clocks the internal shift register of the 33975. The SI data is latched into the input shift register on the falling edge of SCLK signal. The SO terminal shifts the switch status bits out on the rising edge of SCLK. The SO data is available for the MCU to read on the falling edge of SCLK. False clocking of the shift register must be avoided to ensure validity of data. It is essential the SCLK terminal be in a logic low state whenever $\overline{\mathrm{CS}}$ makes any transition. For this reason, it is recommended, though not necessary, that the SCLK terminal is commanded to a low logic state as long as the device is not accessed and $\overline{\mathrm{CS}}$ is in a logic high state. When the $\overline{\mathrm{CS}}$ is in a logic high state, any
signal on the SCLK and SI terminals will be ignored and the SO terminal is tri-state.

## SERIAL INPUT (SI)

The SI terminal is used for serial instruction data input. SI information is latched into the input register on the falling edge of SCLK. A logic high state present on SI will program a one in the command word on the rising edge of the $\overline{\mathrm{CS}}$ signal. To program a complete word, 24 bits of information must be entered into the device.

## SERIAL OUTPUT (SO)

The SO terminal is the output from the shift register. The SO terminal remains tri-stated until the $\overline{\mathrm{CS}}$ terminal transitions to a logic low state. All open switches are reported as zero, all closed switches are reported as one. The negative transition of $\overline{\mathrm{CS}}$ enables the SO driver.

The first positive transition of SCLK will make the status data bit 24 available on the SO terminal. Each successive positive clock will make the next status data bit available for the MCU to read on the falling edge of SCLK. The SI/SO shifting of the data follows a first-in-first-out protocol, with both input and output words transferring the most significant bit (MSB) first.

## INTERRUPT OUTPUT (INT)

The $\overline{\mathrm{INT}}$ terminal is an interrupt output from the 33975 device. The INT terminal is an open-drain output with an internal pull-up to VDD. In Normal mode, a switch state change will trigger the $\overline{\mathrm{NT}}$ terminal (when enabled). The $\overline{\mathrm{INT}}$ terminal is latched on the falling edge of $\overline{\mathrm{CS}}$. and cleared on the rising edge of $\overline{\mathrm{CS}}$. The $\overline{\mathrm{INT}}$ terminal will not clear with rising edge of $\overline{\mathrm{CS}}$ if a switch contact change has occurred while $\overline{\mathrm{CS}}$ was low.

In a multiple 33975 device system with $\overline{\text { WAKE }}$ high and VDD on (Sleep mode), the falling edge of $\overline{\text { INT }}$ will place all 33975s in Normal mode.

## WAKE INPUT (WAKE)

The $\overline{\text { WAKE }}$ terminal is an open-drain output and a wake-up input. The terminal is designed to control a power supply Enable terminal. In the Normal mode, the WAKE terminal is low. In the Sleep mode, the WAKE terminal is high. The $\overline{\text { WAKE }}$ terminal has a pull-up to the internal +5.0 V supply.

In Sleep mode with the $\overline{\text { WAKE }}$ terminal high, falling edge of WAKE will place the 33975 in Normal mode. In Sleep mode with VDD applied, the INT terminal must be high for negative edge of WAKE to wake up the device. If VDD is not applied to the device in Sleep mode, $\overline{\text { INT }}$ does not affect WAKE operation.

## LOAD SUPPLY VOLTAGE (VPWR)

The VPWR terminal is battery input and Power-ON Reset to the 33975 IC. The VPWR terminal requires external reverse battery and transient protection. Maximum input voltage on $\mathrm{V}_{\mathrm{PWR}}$ is 50 V . All wetting, sustain, and internal logic current is provided from the $\mathrm{V}_{\mathrm{PWR}}$ terminal.

## LOGIC VOLTAGE (VDD)

The VDD input terminal is used to determine logic levels on the microprocessor interface (SPI) terminals. Current from VDD is used to drive SO output and the pull-up current for $\overline{\mathrm{CS}}$ and INT terminals. VDD must be applied for wake-up from negative edge of $\overline{C S}$ or $\overline{\mathrm{INT}}$.

## GROUND (GND)

The GND terminal provides ground for the IC as well as ground for inputs programmed as switch-to-battery inputs.

## PROGRAMMABLE SWITCHES (SP0-SP7)

The 33975 device has 8 switch inputs capable of being programmed to read switch-to-ground or switch-to-battery contacts. The input is compared with a 4.0 V reference. When programmed to be switch-to-battery, voltages greater than 4.0 V are considered closed. Voltages less than 4.0 V are considered open. The opposite holds true when inputs are programmed as switch-to-ground. Programming features are defined in Table 6 through Table 11 in the Functional Device Operation section of this datasheet beginning on page 14. Voltages greater than the $\mathrm{V}_{\text {PWR }}$ supply voltage will source current through the SP inputs to the VPWR terminal. Transient battery voltages greater than 38/40 V must be clamped by an external device.

## SWITCH-TO-GROUND (SG0-SG13)

The SGn terminals are switch-to-ground inputs only. The input is compared with a 4.0 V reference. Voltages greater than 4.0 V are considered open. Voltages less than 4.0 V are considered closed. Programming features are defined in Table 6 through Table 11 in the Functional Device Operation section of this datasheet beginning on page 14. Voltages greater than the $V_{\text {PWR }}$ supply voltage will source current through the SG inputs to the VPWR terminal. Transient battery voltages greater than $38 / 40 \mathrm{~V}$ must be clamped by an external device.

## MCU INTERFACE DESCRIPTION

The 33975 device directly interfaces to a 3.3 V or 5.0 V microcontroller unit (MCU). SPI serial clock frequencies up to 6.0 MHz may be used for programming and reading switch input status (production tested at 4.16 MHz ). Figure 7 illustrates the configuration between an MCU and one 33975.

Serial peripheral interface (SPI) data is sent to the 33975 device through the SI input terminal. As data is being clocked into the SI terminal, status information is being clocked out of the device by the SO output terminal. The response to a SPI command will always return the switch status, reset flag, and thermal flag. Input switch states are latched into the SO register on the falling edge of the chip select ( $\overline{\mathrm{CS}}$ ) terminal. Twenty-four bits are required to complete a transfer of information between the 33975 and the MCU.


Figure 7. SPI Interface with Microprocessor
Two or more 33975 devices may be used in a module system. Multiple ICs may be SPI-configured in parallel or serial. Figures 8 and $\underline{9}$ show the configurations. When using the serial configuration, 48 -clock cycles are required to transfer data in/out of the ICs.

MC68HCXX Microcontroller


Figure 8. SPI Parallel Interface with Microprocessor


Figure 9. SPI Serial Interface with Microprocessor

## FUNCTIONAL DEVICE OPERATION

## POWER SUPPLY

The 33975 is designed to operate from 5.5 V to $38 / 40 \mathrm{~V}$ on the VPWR terminal. Characteristics are provided from 8.0 V to 28 V for the device. Switch contact currents and the internal logic supply are generated from the VPWR terminal. The VDD supply terminal is used to set the SPI communication voltage levels, current source for the SO driver, and pull-up current on $\overline{\mathrm{NT}}$ and $\overline{\mathrm{CS}}$.

VDD supply may be removed from the device to reduce quiescent current. If VDD is removed while the device is in Normal mode, the device will remain in Normal mode. If VDD is removed in Sleep mode, the device will remain in Sleep mode until wake-up input is received (WAKE high to low, switch input or interrupt timer expires).

Removing VDD from the device disables SPI communication and will not allow the device to wake up from $\overline{\mathrm{INT}}$ and $\overline{\mathrm{CS}}$ terminals.

## POWER-ON RESET (POR)

Applying VPWR to the device will cause a Power-ON Reset and place the device in Normal mode.

Default settings from Power-ON Reset via VPWR or Reset Command are as follows:

- Programmable Switch - Set to Switch-to-Battery
- All Inputs Set as Wake-Up
- Wetting Current On (16 mA pull down, 32 mA pull up)
- Wetting Current Timer On (20 ms)
- All Inputs Tri-State
- Analog Select 00000 (No Input Channel Selected)

Note The 33975 device provides indication that a reset has occurred by placing a logic [1] in bit 22 of the SO buffer. The reset bit is cleared on rising edge of $\overline{\mathrm{CS}}$.

## OPERATIONAL MODES

The 33975 has two operating modes, Normal mode and Sleep mode. A discussion on Normal mode begins below. A discussion on Sleep Mode begins on page 20.

## NORMAL MODE

Normal mode may be entered by the following events:

- Application of VPWR to the IC
- Change-of-Switch State (when enabled)
- Falling Edge of WAKE
- Falling Edge of INT (with VDD $=5.0 \mathrm{~V}$ and $\overline{\text { WAKE }}$ at Logic [1])
- Falling Edge of $\overline{\mathrm{CS}}$ (with VDD $=5.0 \mathrm{~V}$ )
- Interrupt Timer Expires

Only in Normal mode with VDD applied can the registers of the 33975 be programmed through the SPI.

The registers that may be programmed in Normal mode are listed below. Further explanation of each register is provided in subsequent paragraphs.

- Programmable Switch Register (Settings Command)
- Wake-Up/Interrupt Register (Wake-Up/Interrupt Command)
- Wetting Current Register (Metallic Command)
- Wetting Current Timer Register (Wetting Current Timer Enable Command)
- Tri-State Register (Tri-State Command)
- Analog Select Register (Analog Command)
- Calibration of Timers (Calibration Command)
- Reset (Reset Command)

Figure 6, page 10, is a graphical description of the device operation in Normal mode. Switch states are latched into the input register on the falling edge of $\overline{\mathrm{CS}}$. The $\overline{\mathrm{INT}}$ to the MCU is cleared on the rising edge of $\overline{\mathrm{CS}}$. However, $\overline{\mathrm{INT}}$ will not clear on rising edge of $\overline{\mathrm{CS}}$ if a switch has closed during SPI communication ( $\overline{\mathrm{CS}}$ low). This prevents switch states from being missed by the MCU.

## PROGRAMMABLE SWITCH REGISTER

Inputs SP0 to SP7 may be programmable for switch-tobattery or switch-to-ground. These inputs types are defined using the settings command (refer to Table 6). To set an SPn input for switch-to-battery, a logic [1] for the appropriate bit must be set. To set an SPn input for switch-to-ground, a logic [ 0 ] for the appropriate bit must be set. The MCU may change or update the Programmable Switch Register via software at any time in Normal mode. Regardless of the setting, when the SPn input switch is closed a logic [1] will be placed in the Serial Output Response Register (refer to Table 17, page 19).

Table 6. Settings Command

| Settings Command |  |  |  |  |  |  |  | Not used |  |  |  |  |  |  |  | Battery/Ground Select |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | X | X | X | X | X | X | X | X | sp7 | sp6 | sp5 | sp4 | sp3 | sp2 | sp1 | spo |

## WAKE-UP/INTERRUPT REGISTER

The Wake-Up/Interrupt Register defines the inputs that are allowed to wake the 33975 from Sleep mode or set the INT terminal low in Normal mode. Programming the wake-up/ interrupt bit to logic [0] will disable the specific input from generating an interrupt and will disable the specific input from waking the IC in Sleep mode (refer to Table 7). Programming Table 7. Wake-Up /Interrupt Command
the wake-up/interrupt bit to logic [1] will enable the specific input to generate an interrupt with switch change of state and will enable the specific input as wake-up. The MCU may change or update the Wake-Up/Interrupt Register via software at any time in Normal mode.

| Wake-Up/Interrupt Command |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | X | X | X | X | X | X | X | X | sp7 | sp6 | sp5 | sp4 | sp3 | sp2 | sp1 | sp0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | X | X | $\begin{gathered} \mathrm{sg} 1 \\ 3 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 2 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 1 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 0 \end{gathered}$ | sg9 | sg8 | sg7 | sg6 | sg5 | sg4 | sg3 | sg2 | sg1 | sgo |

## WETTING CURRENT REGISTER

The 33975 has two levels of switch-to-ground contact current, 32 mA and 4.0 mA , and two levels of switch-tobattery contact current, 16 mA and 2.0 mA (see Figure 10). The metallic command is used to set the switch contact current level (refer to Table 8). Programming the metallic bit to logic [0] will set the switch wetting current to $2.0 \mathrm{~mA} / 4.0$ mA . Programming the metallic bit to logic [1] will set the switch contact wetting current to $16 \mathrm{~mA} / 32 \mathrm{~mA}$. The MCU may change or update the Wetting Current Register via software at any time in Normal mode.

Wetting current is designed to provide higher levels of current during switch closure. The higher level of current is designed to keep switch contacts from building up oxides that form on the switch contact surface.


Figure 10. Contact Wetting and Sustain Current for Switch-to-Ground Input

Table 8. Metallic Command

| Metallic Command |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | X | X | X | X | $X$ | X | X | X | sp7 | sp6 | sp5 | sp4 | sp3 | sp2 | sp1 | sp0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | X | X | $\begin{gathered} \mathrm{sg} 1 \\ 3 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 2 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 1 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 0 \end{gathered}$ | sg9 | sg8 | sg7 | sg6 | sg5 | sg4 | sg3 | sg2 | sg1 | sg0 |

## WETTING CURRENT TIMER REGISTER

Each switch input has a designated 20 ms timer. The timer starts when the specific switch input crosses the comparator threshold ( 4.0 V ). When the 20 ms timer expires, the contact current is reduced from 16 mA to 2.0 mA for switch-to-battery inputs and 32 mA to 4.0 mA for switch-to-ground inputs. The wetting current timer may be disabled for a specific input. When the timer is disabled, wetting current will continue to flow through the closed switch contact. With multiple wetting
current timers disabled, power dissipation for the IC must be considered.

The MCU may change or update the Wetting Current Timer Register via software at any time in Normal mode. This allows the MCU to control the amount of time wetting current is applied to the switch contact. Programming the wetting current timer bit to logic [0] will disable the wetting current timer. Programming the wetting current timer bit to logic [1] will enable the wetting current timer (refer to Table 9).

Table 9. Wetting Current Timer Enable Command

| Wetting Current Timer Commands |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | X | X | X | X | X | X | X | X | sp7 | sp6 | sp5 | sp4 | sp3 | sp2 | sp1 | sp0 |
| 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | X | X | $\begin{gathered} \mathrm{sg} 1 \\ 3 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 2 \end{gathered}$ | $\begin{gathered} \mathrm{sg} 1 \\ 1 \end{gathered}$ | $\begin{gathered} \text { sg1 } \\ 0 \end{gathered}$ | sg9 | sg8 | sg7 | sg6 | sg5 | sg4 | sg3 | sg2 | sg1 | sgo |

## TRI-STATE REGISTER

The tri-state command is use to set the SPn or SGn input node as high impedance (refer to Table 10). By setting the Tri-State Register bit to logic [1], the input will be high impedance regardless of the metallic command setting. The Table 10. Tri-State Command
comparator on each input remains active. This command allows the use of each input as a comparator with a 4.0 V threshold. The MCU may change or update the Tri-State Register via software at any time in Normal mode.

| Tri-State Commands |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | X | X | X | X | X | X | X | X | sp7 | sp6 | sp5 | sp4 | sp3 | sp2 | sp1 | sp0 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | X | X | sg13 | sg12 | sg11 | sg10 | sg9 | sg8 | sg7 | sg6 | sg5 | sg4 | sg3 | sg2 | sg1 | sgo |

## ANALOG SELECT REGISTER

The analog voltage on switch inputs may be read by the MCU using the analog command (refer to Table 11). Internal to the IC is a 22-to-1 analog multiplexer. The voltage present on the selected input terminal is buffered and made available on the AMUX output terminal. The AMUX output terminal is clamped to a maximum of VDD volts regardless of the higher voltages present on the input terminal. After an input has been selected as the analog, the corresponding bit in the next SO data stream will be logic [0]. When selecting a channel to be read as analog, the user must also set the desired current ( $32 \mathrm{~mA}, 4.0 \mathrm{~mA}$, or high impedance). Setting bit 6 and bit 5 to 0,0 selects the input as high impedance. Setting bit 6 and bit 5 to 0,1 selects 4.0 mA , and 1,0 selects 32 mA . Setting
bit 6 and bit 5 to 1,1 in the Analog Select Register is not allowed and will place the input as an analog input with high impedance.

Analog currents set by the analog command are pull-up currents for all SGn and SPn inputs (refer to Table 11). The analog command does not allow pull-down currents on the SPn inputs. Setting the current to 32 mA or 4.0 mA may be useful for reading sensor inputs. Further information is provided in the Typical Applications section of this datasheet beginning on page 22. The MCU may change or update the Analog Select Register via software at any time in Normal mode.

Table 11. Analog Command

| Analog Command |  |  |  |  |  |  |  | Not used |  |  |  |  |  |  |  |  | Current Select |  | Analog Channel Select |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | X | X | X | X | X | X | X | X | X | $\begin{gathered} 32 \\ \mathrm{~mA} \end{gathered}$ | $\begin{aligned} & 4.0 \\ & \mathrm{~mA} \end{aligned}$ | 0 | 0 | 0 | 0 | 0 |

Table 12. Analog Channel

| Bits $\mathbf{4 3 2 1 0}$ | Analog Channel Select |
| :---: | :---: |
| 00000 | No Input Selected |
| 00001 | SG0 |
| 00010 | SG1 |
| 00011 | SG2 |
| 00100 | SG3 |
| 00101 | SG4 |
| 00110 | SG5 |
| 00111 | SG6 |
| 01000 | SG7 |
| 01001 | SG8 |
| 01010 | SG9 |
| 01011 | SG11 |
| 01100 | SG12 |
| 01101 | SG13 |
| 01110 | SP1 |
| 01111 | SP2 |
| 10000 | SP3 |
| 10001 | SP4 |
| 10010 | SP5 |
| 10011 | SP6 |
| 10100 | SP7 |
| 10101 |  |
| 10110 |  |

## CALIBRATION OF TIMERS

In cases where an accurate time base is required, the user may calibrate the internal timers using the calibration command (refer to Table 13). After the 33975 device receives the calibration command, the device expects $512 \mu \mathrm{~s}$ logic [0] calibration pulse on the $\overline{C S}$ terminal. The pulse is used to calibrate the internal clock. No other SPI terminals should transition during this $512 \mu$ s calibration pulse.

Because the oscillator frequency changes with temperature, calibration is required for an accurate time base. Calibrating the timers has no affect on the quiescent current measurement. The calibration command simply makes the time base more accurate. The calibration command may be used to update the device on a periodic basis. All reset conditions clear the calibration register and places the device in the uncalibrated state.

## Table 13. Calibration Command

| Calibration Command |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |

## RESET

The reset command resets all registers to Power-ON Reset (POR) state. Refer to Table 15, page 18, for POR
Table 14. Reset Command
states or the paragraph entitled Power-ON Reset (POR) on page 14 of this datasheet.

| Reset Command |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |

## SPI COMMAND SUMMARY

Table 15 below provides a comprehensive list of SPI commands recognized by the 33975 and the reset state of each register. Table 16 and Table 17 contain the Serial Output (SO) data for input voltages greater or less than the
threshold level. Open switches are always indicated with a logic [0], closed switches are indicated with logic [1].

Table 15. SPI Command Summary

| MSB Command Bits |  |  |  |  |  |  |  |  | Setting Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Switch Status Command | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| Settings Command Bat $=1$, Gnd=0 <br> (Default state $=$ 1) | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | X | X | X | X | X | X | X | X | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SP0 |
| Wake-Up/Interrupt Bit | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | X | X | X | X | X | X | X | X | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SP0 |
| Nonwake-Up=0 <br> (Default state $=1$ ) | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | X | X | SG13 | SG12 | SG11 | SG10 | SG9 | SG8 | SG7 | SG6 | SG5 | SG4 | SG3 | SG2 | SG1 | SG0 |
| Metallic Command | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | X | X | X | X | X | X | X | X | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SP0 |
| Non-metallic $=0$ <br> (Default state $=$ <br> 1) | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | X | X | SG13 | SG12 | SG11 | SG10 | SG9 | SG8 | SG7 | SG6 | SG5 | SG4 | SG3 | SG2 | SG1 | SG0 |


| MSB Command Bits |  |  |  |  |  |  |  |  | Setting Bits LSB |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Analog Command | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | X | X | X | X | X | X | X | X | X | 32 mA 0 | $\left\|\begin{array}{c} 4.0 \mathrm{~m} \\ \mathrm{~A} \\ 0 \end{array}\right\|$ | 0 | 0 | 0 | 0 | 0 |
| Wetting Current Timer | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | X | X | X | X | X | X | X | X | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SP0 |
| $\begin{aligned} & \text { Timer ON = } 1 \\ & \text { Timer OFF = } 0 \\ & \text { (Default state }=1 \text { ) } \end{aligned}$ | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | x | x | SG13 | SG12 | SG11 | SG10 | SG9 | SG8 | SG7 | SG6 | SG5 | SG4 | SG3 | SG2 | SG1 | SG0 |
| Tri-State Command | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | X | X | X | X | X | X | X | X | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SPO |
| Input Active $=0$ | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | X | x | SG13 | SG12 | SG11 | SG10 | SG9 | SG8 | SG7 | SG6 | SG5 | SG4 | SG3 | SG2 | SG1 | SG0 |
| Calibration Command (Default state uncalibrated) | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| Sleep Command <br> (See Sleep Mode on page 20) | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | X | X | X | X | X | X | X | X | X | X | $\begin{gathered} \text { int } \\ \text { timer } \end{gathered}$ | $\begin{array}{\|c} \hline \text { int } \\ \text { timer } \end{array}$ | $\begin{array}{\|c\|c\|} \hline \text { int } \\ \text { timer } \end{array}$ | $\begin{gathered} \text { scan } \\ \text { timer } \end{gathered}$ | $\begin{gathered} \text { scan } \\ \text { timer } \end{gathered}$ | $\begin{aligned} & \text { scan } \\ & \text { timer } \end{aligned}$ |
| Reset Command | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | X | X | X | x | x | x | x | x | X | x | X | X | X | X | x | X |
| SO Response Will Always Send | $\left\lvert\, \begin{gathered} \text { therm } \\ \text { flg } \end{gathered}\right.$ | $\begin{gathered} \mathrm{RST} \\ \mathrm{flg} \end{gathered}$ | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SP0 | SG13 | SG12 | SG11 | SG10 | SG9 | SG8 | SG7 | SG6 | SG5 | SG4 | SG3 | SG2 | SG1 | SG0 |

Table 16. Serial Output (SO) Bit Data

| Type of Input | Input <br> Programmed | Voltage on <br> Input terminal | SO SPI Bit |
| :---: | :---: | :---: | :---: |
| SP | Switch to Ground | $\mathrm{SPn}<4.0 \mathrm{~V}$ | 1 |
|  | Switch to Ground | $\mathrm{SPn}>4.0 \mathrm{~V}$ | 0 |
|  | Switch to Battery | $\mathrm{SPn}<4.0 \mathrm{~V}$ | 0 |
|  | Switch to Battery | $\mathrm{SPn}>4.0 \mathrm{~V}$ | 1 |
|  | $\mathrm{N} / \mathrm{A}$ | $\mathrm{SGn}<4.0 \mathrm{~V}$ | 1 |
|  | $\mathrm{~N} / \mathrm{A}$ | $\mathrm{SGn}>4.0 \mathrm{~V}$ | 0 |

Table 17. Serial Output (SO) Response Register

| SO Response Will Always Send | therm flg | $\begin{gathered} \text { RST } \\ \text { flg } \end{gathered}$ | SP7 | SP6 | SP5 | SP4 | SP3 | SP2 | SP1 | SP0 | SG13 | SG12 | SG11 | SG10 | SG9 | SG8 | SG7 | SG6 | SG5 | SG4 | SG3 | SG2 | SG1 | SG0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

## EXAMPLE OF NORMAL MODE OPERATION

The operation of the device in Normal Mode is defined by the states of the programmable internal control registers. A typical application may have the following settings:

- Programmable Switch - Set to Switch-to-Ground
- All Inputs Set as Wake-Up
- Wetting Current On (32 mA)
- Wetting Current Timer On (20 ms)
- All inputs Tri-State-Disabled (comparator is active)
- Analog select 00000 (no input channel selected)

With the device programmed as above, an interrupt will be generated with each switch contact change of state (open-toclose or close-to-open) and 32 mA of contact wetting current will be source for 20 ms . The $\overline{\mathrm{NT}}$ terminal will remain low until switch status is acknowledged by the microprocessor. It is
critical to understand $\overline{\mathrm{INT}}$ will not be cleared on the rising edge of $\overline{C S}$ if a switch closure occurs while $\overline{\mathrm{CS}}$ is low. The maximum duration a switch state change can exist without acknowledgement depends on the software response time to the interrupt. Figure 6, page 10, shows the interaction between changing input states and the $\overline{\mathrm{INT}}$ and $\overline{\mathrm{CS}}$ terminals.

If desired the user may disable interrupts (wake up/ interrupt command) from the 33975 device and read the switch states on a periodic basis. Switch activation and deactivation faster than the MCU read rate will not be acknowledged.

The 33975 device will exit the Normal mode and enter the Sleep mode only with a valid sleep command.

## SLEEP MODE

Sleep mode is used to reduce system quiescent currents. Sleep mode may be entered only by sending the sleep command. All register settings programmed in Normal mode will be maintained in Sleep mode.

The 33975 will exit Sleep mode and enter Normal mode when any of the following events occur:

- Input Switch Change of State (when enabled)
- Interrupt Timer Expire
- Falling Edge of WAKE
- Falling Edge of $\overline{\mathrm{INT}}$ (with VDD $=5.0 \mathrm{~V}$ and $\overline{\mathrm{WAKE}}$ at Logic [1])
- Falling Edge of $\overline{\mathrm{CS}}$ (with VDD $=5.0 \mathrm{~V}$ )
- Power-ON Reset (POR)

The VDD supply may be removed from the device during Sleep mode. However removing VDD from the device in Sleep mode will disable a wake-up from falling edge of $\overline{\mathrm{INT}}$ and $\overline{\mathrm{CS}}$.

Note In cases where $\overline{\mathrm{CS}}$ is used to wake the device, the first SO data message is not valid.

The sleep command contains settings for two programmable timers for Sleep mode, the interrupt timer and the scan timer, as shown in Table 18 The interrupt timer is used as a periodic wake-up timer. When the timer expires, an interrupt is generated and the device enters Normal mode.

Note The interrupt timer in the 33975 device may be disabled by programming the interrupt bits to logic [llllll 11111$].$

Table 19 shows the programmable settings of the Interrupt timer.

Table 18. Sleep Command

| Sleep Command |  |  |  |  |  |  |  | Command Bits |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | X | X | X | X | X | X | X | X | X | X | $\xrightarrow{\text { 亏 }}$ |  |  |  |  |  |

Table 19. Interrupt Timer

| Bits 543 | Interrupt Period |
| :---: | :---: |
| 000 | 32 ms |
| 001 | 64 ms |
| 010 | 128 ms |
| 011 | 256 ms |
| 100 | 512 ms |
| 101 | 1.024 s |
| 110 | 2.048 s |
| 111 | No interrupt wake-up |

The scan timer sets the polling period between input switch reads in Sleep mode. The period is set in the sleep command and may be set to 000 (no period) to 111 ( 64 ms ). In Sleep mode when the scan timer expires, inputs will behave as programmed prior to sleep command. The 33975 will wake up for approximately $125 \mu$ s and read the switch inputs. At the end of the $125 \mu \mathrm{~s}$, the input switch states are compared with the switch state prior to sleep command.

When switch state changes are detected, an interrupt (when enabled; refer to wake-up/interrupt command description on page 15) is generated and the device enters Normal mode. Without switch state changes, the 33975 will reset the scan timer, inputs become tri-state, and the Sleep mode continues until the scan timer expires again.

Table 20 shows the programmable settings of the Scan timer.

Table 20. Scan Timer

| Bits 210 | Scan Period |
| :---: | :---: |
| 000 | No Scan |
| 001 | 1.0 ms |
| 010 | 2.0 ms |
| 011 | 4.0 ms |
| 100 | 8.0 ms |
| 101 | 16 ms |
| 110 | 32 ms |
| 111 | 64 ms |

Note The interrupt and scan timers are disabled in the Normal mode.

Figure 5, page 10, is a graphical description of how the 33975 device exits Sleep mode and enters Normal mode. Notice that the device will exit Sleep mode when the interrupt timer expires or when a switch change of state occurs. The falling edge of $\overline{\mathrm{NT}}$ triggers the MCU to wake from Sleep state. Figure 11 illustrates the current consumed during Sleep mode. During the $125 \mu \mathrm{~s}$, the device is fully active and switch states are read. The quiescent current is calculated by integrating the normal running current over scan period plus approximately $60 \mu \mathrm{~A}$.


Figure 11. Sleep Current Waveform

## TEMPERATURE MONITOR

With multiple switch inputs closed and the device programmed with the wetting current timers disabled, considerable power will be dissipated by the IC. For this reason temperature monitoring has been implemented. The temperature monitor is active in the Normal mode only. When the IC temperature is above the thermal limit, the temperature monitor will do all of the following:

- Generate an interrupt.
- Force all wetting current sources to revert to $2.0 \mathrm{~mA} /$ 4.0 mA sustain currents
- Maintain the $2.0 \mathrm{~mA} / 4.0 \mathrm{~mA}$ sustain currents and all other functionality.
- Set the thermal flag bit in the SPI output register.

The thermal flag bit in the SPI word will be cleared on rising edge of $\overline{C S}$ provided the die temperature has cooled below the thermal limit. When die temperature has cooled below thermal limit, the device will resume previously programmed settings.

## TYPICAL APPLICATIONS

The 33975's primary function is the detection of open or closed switch contacts. However, there are many features that allow the device to be used in a variety of applications. The following is a list of applications to consider for the IC:

- Sensor Power Supply
- Switch Monitor for Metallic or Elastomeric Switches
- Analog Sensor Inputs (Ratiometric)
- Power MOSFET/LED Driver and Monitor
- Multiple 33975 Devices in a Module System

The following paragraphs describe the applications in detail.

## SENSOR POWER SUPPLY

Each input may be used to supply current to sensors external to a module. Many sensors such as Hall effect, pressure sensors, and temperature sensors require a supply voltage to power the sensor and provide an open collector or analog output. Figure 12 shows how the 33975 may be used to supply power and interface to these types of sensors. In an application where the input makes continuous transitions, consider using the wake-up/interrupt command to disable the interrupt for the particular input.


Figure 12. Sensor Power Supply

## METALLIC/ELASTOMERIC SWITCH

Metallic switch contacts often develop higher contact resistance over time owing to contact corrosion. The corrosion is induced by humidity, salt, and other elements that exist in the environment. For this reason the 33975 provides two settings for contacts. When programmed for metallic switches, the device provides higher wetting current to keep switch contacts free of oxides. The higher current occurs for the first 20 ms of switch closure. Where longer duration of wetting current is desired, the user may send the wetting current timer command and disable the timer. Wetting current will be continuous to the closed switch. After the time period set by the MCU, the wetting current timer command may be sent again to enable the timer. The user must consider power dissipation on the device when disabling the timer. (Refer to the paragraph entitled Temperature Monitor, page 21.)

To increase the amount of wetting current for a switch contact, the user has two options. Higher wetting current to a switch may be achieved by paralleling SGn or SPn inputs. This will increase wetting current by 32 mA for each input added to the switch-to- ground contact and 16 mA for switch-to-battery contacts. The second option is to simply add an external resistor pull-up to the $\mathrm{V}_{\text {PWR }}$ supply for switch-toground inputs or a resistor to ground for a switch-to-battery input. Adding an external resistor has no effect on the operation of the device.

Elastomeric switch contacts are made of carbon and have a high contact resistance. Resistance of $1.0 \mathrm{k} \Omega$ is common. In applications with elastomeric switches, the pull-up and pull-down currents must be reduced to prevent excessive power dissipation at the contact. Programming for a lower current settings is provided in the Functional Device Operation Section beginning on page 14 under Table 8, Metallic Command.

## ANALOG SENSOR INPUTS (RATIOMETRIC)

The 33975 features a 22-to-1 analog multiplexer. Setting the binary code for a specific input in the analog command allows the microcontroller to perform analog to digital conversion on any of the 22 inputs. On rising edge of $\overline{\mathrm{CS}}$ the multiplexer connects a requested input to the AMUX terminal. The AMUX terminal is clamped to max of VDD volts regardless of the higher voltages present on the input terminal. After an input has been selected as the analog, the corresponding bit in the next SO data stream will be logic [0].

The input terminal, when selected as analog, may be configured as analog with high impedance, analog with 4.0 mA pull-up, or analog with 32 mA pull-up. Figure 13, page $\underline{23}$, shows how the 33975 may be used to provide a ratiometric reading of variable resistive input.


Figure 13. Analog Ratiometric Conversion
To read a potentiometer sensor, the wiper should be grounded and brought back to the module ground, as illustrated in Figure 13. With the wiper changing the impedance of the sensor, the analog voltage on the input will represent the position of the sensor.

Using the Analog feature to provide 4.0 mA of pull-up current to an analog sensor may induce error due to the accuracy of the current source. For this reason, a ratiometric conversion must be considered. Using two current sources (one for the sensor and one to set the reference voltage to the A/D converter) will yield a maximum error (owing to the 33975) of $4 \%$.

Higher accuracy may be achieved through module level calibration. In this example, we use the resistor values from Figure 13 and assume the current sources are $4 \%$ from each other. The user may use the module end-of-line tester to calculate the error in the A/D conversion. By placing a $1.0 \mathrm{k} \Omega, 0.1 \%$ resistor in the end-of-line test equipment and assuming a perfect 4.0 mA current source from the 33975, a calculated A/D conversion may be obtained.

Using the equation yields the following:

$$
\begin{gathered}
\mathrm{ADC}=\frac{11 \times \mathrm{R} 1}{12 \times \mathrm{R} 2} \times 225 \\
\mathrm{ADC}=\frac{4.0 \mathrm{~mA} \times 1.0 \mathrm{k} \Omega}{4.0 \mathrm{~mA} \times 1.21 \mathrm{k} \Omega} \times 225 \\
\mathrm{ADC}=210 \text { counts }
\end{gathered}
$$

The ADC value of 213 counts is the value with $0 \%$ error (neglecting the resistor tolerance and AMUX input offset voltage). Now we can calculate the count value induced by the mismatch in current sources. From a sample device the maximum current source was measured at 3.979 mA and minimum current source was measured at 3.933 mA . This yields $1.16 \%$ error in A/D conversion due to the current source mismatch. The A/D measurement will be as follows:

$$
\begin{gathered}
\mathrm{ADC}=\frac{3.933 \mathrm{~mA} \times 1.0 \mathrm{k} \Omega}{3.979 \mathrm{~mA} \times 1.21 \mathrm{k} \Omega} \times 225 \\
\mathrm{ADC}=208 \text { counts }
\end{gathered}
$$

This A/D conversion is $1.16 \%$ low in value. The error correction factor of 1.0115 may be used to correct the value:

$$
\begin{gathered}
\text { ADC }=208 \text { counts } \times 1.0116 \\
\text { ADC }=210 \text { counts }
\end{gathered}
$$

An error correction factor may then be stored in $E^{2}$ memory and used in the A/D calculation for the specific input. Each input used as analog measurement will have a dedicated calibrated error correction factor.

## POWER MOSFET/LED DRIVER AND MONITOR

Because of the flexible programming of the 33975 device, it may be used to drive small loads like LEDs or MOSFET gates. It was specifically designed to power up in the Normal mode with the inputs tri-state. This was done to ensure the LEDs or MOSFETs connected to the 33975 power up in the off-state. The Switch Programmable (SP0-SP7) inputs have a source-and-sink capability, providing effective MOSFET gate control. To complete the circuit, a pull-down resistor should be used to keep the gate from floating during the Sleep modes. Figure 14, page 24, shows an application where the SG0 input is used to monitor the drain-to-source voltage of the external MOSFET. The $750 \Omega$ resistor is used to set the drain-to-source trip voltage. With the 4.0 mA current source enabled, an interrupt will be generated when the drain-to-source voltage is approximately 1.0 V .


Figure 14. MOSFET or LED Driver Output
The sequence of commands (from Normal mode with inputs tri-state) required to set up the device to drive a MOSFET are as follows:

- wetting current timer enable command -Disable SPn wetting current timer (refer to Table 9, page 16).
- metallic command-Set SPn to $16 / 32 \mathrm{~mA}$ or $2.0 / 4.0 \mathrm{~mA}$ gate drive current (refer to Table 8, page 15).
- settings command -Set SPn as switch-to-battery (refer to Table 6, page 14).
- tri-state command -Disable tri-state for SPn (refer to Table 10, page 16).

After the tri-state command has been sent (tri-state disable), the MOSFET gate will be pulled to ground. From this point forward the MOSFET may be turned on and off by sending the settings command:

- settings command -SPn as switch-to-ground (MOSFET ON).
- settings command -SPn as switch-to-battery (MOSFET OFF).

Monitoring of the MOSFET drain in the OFF state provides open load detection. This is done by using an input comparator. With the SGn input in tri-state, the load will pull up the input to battery. With the load open, the SGn terminal is pulled down to ground through an external resistor. The open load is indicated by a logic [1] in the SO data bit.

The analog command may be used to monitor the drain voltage in the MOSFET ON state. By sourcing 4.0 mA of current to the $750 \Omega$ resistor, the analog voltage on the SGn terminal will be approximately:

$$
V_{S G n}=I_{S G n} \times 750 \Omega+V_{D S}
$$

As the voltage on the drain of the MOSFET increases, so does the voltage on the SGn terminal. With the SGn terminal selected as analog, the MCU may perform the A/D conversion.

Using this method for controlling unclamped inductive loads is not recommended. Inductive fly-back voltages greater than $V_{\text {PWR }}$ may damage the IC.

The SP0-SP7 terminals of this device may also be used to send signals from one module to another. Operation is similar to the gate control of a MOSFET.

For LED applications a resistor in series with the LED is recommended but not required. The switch-to-ground inputs are recommended for LED application. To drive the LED use the following commands:

- wetting current timer enable command -Disable SGn wetting current timer.
- metallic command -Set SGn to 32 mA .

From this point forward the LED may be turned on and off using the tri-state command:

- tri-state command -Disable tri-state for SGn (LED ON).
- tri-state command -Enable tri-state for SGn (LED OFF).

These parameters are easily programmed via SPI commands in Normal mode.

## Multiple 33975 Devices in a Module System

Connecting power to the 33975 and the MCU for Sleep mode operation may be done in several ways. Table 21 shows several system configurations for power between the MCU and the 33975 and their specific requirements for functionality.

Table 21. Sleep Mode Power Supply

| MCU <br> VDD | 33975 <br> VDD | Comments |
| :---: | :---: | :--- |
| 5.0 V | 5.0 V | All wake-up conditions apply. (Refer to Sleep <br> Mode, page 20.) |
| 5.0 V | 0 V | SPI wake-up is not possible. |
| 0 V | 5.0 V | Sleep mode not possible. Current from $\overline{\mathrm{CS}}$ pull <br> up will flow through MCU to VDD that has been <br> switched off. Negative edge of $\overline{\mathrm{CS}}$ will put 33975 <br> in Normal mode. |
| 0 V | 0 V | SPI wake-up is not possible. |

Multiple 33975 devices may be used in a module system. SPI control may be done in parallel or serial. However when parallel mode is used, each device is addressed independently (refer to MCU Interface Description, page 13). Therefore when sending the sleep command, one device will enter sleep before the other. For multiple devices in a system, it is recommended that the devices are controlled in serial (S0 from first device is connected to SI of second device). With two devices, 48 clock pulses are required to shift data in. When the WAKE feature is used to enable the power supply, both WAKE terminals should be connected to the enable terminal on the power supply. The INT terminals may be connected to one interrupt terminal on the MCU or may have their own dedicated interrupt to the MCU.

The transition from Normal to Sleep mode is done by sending the sleep command. With the devices connected in serial and the sleep command sent, both will enter Sleep mode on the rising edge of $\overline{\mathrm{CS}}$. When Sleep mode is entered, the WAKE terminal will be logic [1]. If either device wakes up, the $\overline{\text { WAKE }}$ terminal will transition low, waking the other device.

A condition exists where the MCU is sending the sleep command ( $\overline{\mathrm{CS}}$ logic [0]) and a switch input changes state. With this event the device that detects this input will not transition to Sleep mode, while the second device will enter Sleep mode. In this case two switch status commands must be sent to receive accurate switch status data. The first switch status command will wake the device in Sleep mode. Switch status data may not be valid from the first switch status command because of the time required for the input voltage to rise above the 4.0 V input comparator threshold. This time is dependant on the impedance of SGn or SPn node. The second switch status command will provide accurate switch status information. It is recommended that software wait 10 ms to 20 ms between the two switch status commands, allowing time for switch input voltages to stabilize. With all switch states acknowledged by the MCU, the sleep sequence may be initiated. All parameters for Sleep
mode should be updated prior to sending the sleep command.

The 33975 IC has an internal 5.0 V supply from the VPWR terminal. A POR circuit monitors the internal 5.0 V supply. In the event of transients on the VPWR terminal, an internal reset may occur. Upon reset the 33975 will enter Normal mode with the internal registers as defined in Table 15, page 18. Therefore it is recommended that the MCU periodically update all registers internal to the IC.

## USING THE $\overline{\text { WAKE FEATURE }}$

The 33975 provides a $\overline{\text { WAKE output and wake-up input }}$ designed to control an enable terminal on system power supply. While in the Normal mode, the WAKE output is low, enabling the power supply. In the Sleep mode, the WAKE terminal is high, disabling the power supply. The WAKE terminal has a passive pull-up to the internal 5.0 V supply but may be pulled up through a resistor to $\mathrm{V}_{\text {PWR }}$ supply (see Figure 16, page 26).

When the WAKE output is not used the terminal should be pulled up to the VDD supply through a resistor as shown in Figure 15, page 26).

During the Sleep mode, a switch closure will set the WAKE terminal low, causing the 33975 to enter the Normal mode. The power supply will then be activated, supplying power to the VDD terminal and the microprocessor and the 33975. The microprocessor can determine the source of the wake-up by reading the interrupt flag.

## COST AND FLEXIBILITY

Systems requiring a significant number of switch interfaces have many discrete components. Discrete components on standard PWB consume board space and must be checked for solder joint integrity. An integrated approach reduces solder joints, consumes less board space, and offers wider operating voltage, analog interface capability, and greater interfacing flexibility.


Figure 15. Power Supply Active in Sleep Mode


Figure 16. Power Supply Shutdown in Sleep Mode

## PACKAGE DIMENSIONS

The silicon device is packaged in the 32 terminal SOIC with an exposed pad. The exposed pad is thermally conductive and electrically isolated to the die. It is recommended that the exposed pad be electrically connected to ground.

Important: For the most current revision of the package, visit www.freescale.com and perform a "keyword" search on the " 98 A " number listed below.



## PACKAGE DIMENSIONS (CONTINUED)




## PACKAGE DIMENSIONS (CONTINUED)

NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.
2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
3. DATUMS B AND C TO BE DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.
4. THIS DIMENSION DOES NOT INCLUDE MOLD FLASH, PROTRUSION OR GATE BURRS. MOLD FLASH, PROTRUSION OR GATE BURRS SHALL NOT EXCEED 0.15 MM PER SIDE. THIS DIMENSION IS DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.
S
THIS DIMENSION DOES NOT INCLUDE INTER-LEAD FLASH OR PROTRUSIONS. INTER-LEAD FLASH AND PROTRUSIONS SHALL NOT EXCEED 0.25 MM PER SIDE. THIS DIMENSION IS determined at the plane where the bottom of the leadd exit the plastic body.
5. THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED 0.4 mm . DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT LESS THAN 0.07 mm .
6. EXACT SHAPE OF EACH CORNER IS OPTIONAL.
7. THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10 mm AND 0.3 mm FROM THE LEAD TIP.

THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM. THIS DIMENSION IS DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTER-LEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
亿d. THESE DIMENSIONS DEFINE THE PRIMARY SOLDERABLE SURFACE AREA.


## NOTES

## NOTES

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